Entropy Decay in the Swendsen-Wang Dynamics on \mathbb{Z}^d

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ABSTRACT

We study the mixing time of the Swendsen-Wang dynamics for the ferromagnetic Ising and Potts models on the integer lattice \mathbb{Z}^d . This dynamics is a widely used Markov chain that has largely resisted sharp analysis because it is non-local, i.e., it changes the entire configuration in one step. We prove that, whenever strong spatial mixing (SSM) holds, the mixing time on any n-vertex cube in \mathbb{Z}^d is $O(\log n)$, and we prove this is tight by establishing a matching lower bound. The previous best known bound was O(n). SSM is a standard condition corresponding to exponential decay of correlations with distance between spins on the lattice and is known to hold in d = 2 dimensions throughout the high-temperature (single phase) region. Our result follows from a modified log-Sobolev inequality, which expresses the fact that the dynamics contracts relative entropy at a constant rate at each step. The proof of this fact utilizes a new factorization of the entropy in the joint probability space over spins and edges that underlies the Swendsen-Wang dynamics, which extends to general bipartite graphs of bounded degree. This factorization leads to several additional results, including mixing time bounds for a number of natural local and non-local Markov chains on the joint space, as well as for the standard random-cluster dynamics.

CCS CONCEPTS

• Mathematics of computing \rightarrow Markov processes; Probabilistic algorithms; • Theory of computation \rightarrow Random walks and Markov chains.

KEYWORDS

Ising/Potts model, Swendsen–Wang dynamics, entropy decay, mixing time, spin systems.

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1 INTRODUCTION

The ferromagnetic Potts model is a classical spin system in statistical physics and theoretical computer science. It is specified by a finite graph $G=(V,\mathbb{E})$, a set of spins (or colors) $[q]=\{1,\ldots,q\}$, and an $edge\ weight$ or inverse temperature parameter $\beta>0$. A configuration $\sigma\in\Omega=\{1,\ldots,q\}^V$ of the model assigns a spin value to each vertex $v\in V$, and the probability of finding the system in a given configuration σ is given by the Gibbs (or Boltzmann) distribution

$$\mu(\sigma) = \mu_{G,\beta}(\sigma) := \frac{1}{Z} \exp(-\beta |D(\sigma)|), \tag{1.1}$$

where $D(\sigma):=\{\{v,w\}\in\mathbb{E}:\sigma_v\neq\sigma_w\}$ is the set of edges whose endpoints have disagreeing spins in σ and

$$Z := \sum_{\sigma \in \Omega} \exp(-\beta |D(\sigma)|)$$

is the normalizing factor or *partition function*. Note that this model is *ferromagnetic*, in the sense that neighboring spins tend to align with each other. The Ising model of ferromagnetism is exactly the case q=2.

We focus on the classical setting where G is a subgraph of the infinite d-dimensional lattice \mathbb{Z}^d . We will mostly restrict attention to the case where $V = \{0, \dots, \ell\}^d$ is a cube, but our results can be extended to more general subgraphs of \mathbb{Z}^d ; see Remark 2.2. In fact, our main technical contributions apply to general bipartite graphs of bounded degree.

A popular Markov chain for sampling from the Gibbs distribution (1.1) is the *Swendsen–Wang (SW)* dynamics [45], which utilizes the random-cluster representation of the Potts model to derive a sophisticated *non-local* Markov chain in which every vertex can update its spin in each step. From the current spin configuration $\sigma(t) \in \Omega$, the SW dynamics generates $\sigma(t+1) \in \Omega$ as follows:

(1) Let $M(\sigma(t)) = \mathbb{E} \setminus D(\sigma(t)) = \{\{v, w\} \in \mathbb{E} : \sigma_v(t) = \sigma_w(t)\}$ be the set of monochromatic edges of G in $\sigma(t)$.

- (2) Independently for each edge $e \in M(\sigma(t))$, retain e with probability $1 \exp(-\beta)$ and delete it otherwise, resulting in the subset $A(t) \subseteq M(\sigma(t))$. (This is equivalent to performing bond percolation with probability $1 \exp(-\beta)$ on the subgraph $(V, M(\sigma(t)))$.)
- (3) For each connected component C in the subgraph (V, A(t)), independently choose a spin s_C uniformly at random from [q] and assign s_C to all vertices in C, yielding $\sigma(t+1) \in \Omega$.

The Swendsen–Wang dynamics is ergodic, and has (1.1) as its stationary distribution; see [19] for a proof.

This non-local dynamics was originally proposed as an algorithm for sampling at low temperatures, where the space of configurations is partitioned into q "phases" (in each of which one of the q spins dominates). Unlike the standard Glauber dynamics, the local Markov chain that updates the spin of a single, randomly chosen vertex at each step, the SW dynamics can flip large regions of spins in a single step allowing it to jump between phases. Even at high temperatures, where the Glauber dynamics is fast, the SW dynamics provides a powerful alternative sampling algorithm since one can efficiently parallelize its global steps.

In this paper, we are interested in the speed of convergence of the SW dynamics to stationarity, and in particular its *mixing time*. The mixing time captures the convergence rate in total variation distance of a Markov chain from the worst possible starting configuration and is the most standard measure of the speed of convergence. Results proving tight bounds for the mixing time of the SW dynamics are rare, and are limited to very special classes of graphs, such as the complete graph and trees [8, 21, 29, 32], or to very high temperatures [39, 43]. Most bounds for the mixing time of the SW dynamics are derived by comparison with the Glauber dynamics [46], and are consequently often very far from sharp. We also know of multiple examples where the mixing time of the SW dynamics is exponential in the number of vertices of the graph; see, e.g., [8, 11, 12, 21–23].

There is a long line of work studying the connection between *spatial mixing* (i.e., decay of correlations) properties of Gibbs distributions and the speed of convergence of Markov chains (see, e.g., [1, 14, 18, 28, 36, 37, 42, 44, 47]). These results focus on local Markov chains, such as the Glauber dynamics, but there has also been some recent progress in understanding this connection for non-local Markov chains such as the SW dynamics [5, 6, 13]. In particular, it was established in [5] that the *strong spatial mixing* (SSM) property implies that the mixing time $T_{\text{mix}}(SW)$ of the SW dynamics is O(n), where n := |V| is the number of vertices.

SSM is a standard formalization of decay of correlations in spin systems and, roughly speaking, expresses the fact that the correlation between spins at different vertices decreases exponentially with the distance between them. More precisely, given a pair of fixed configurations ψ and ψ_u on the boundary of V such that ψ and ψ_u differ only in the spin of the vertex u, the effect on the (conditional) marginal distribution at a set $B \subset V$ decays exponentially with the distance between B and the disagreement at u; see Section 2 for a precise definition. Our main algorithmic result in this paper is that the mixing time of the SW dynamics is in fact $O(\log n)$ whenever SSM holds, and this is tight.

THEOREM 1.1. In an n-vertex cube of \mathbb{Z}^d , for all integer $q \geq 2$, SSM implies that for all boundary conditions $T_{\text{mix}}(SW) = \Theta(\log n)$.

We recall that a *boundary condition* τ for the Potts model is a fixed assignment of spins to the boundary of V; in the presence of a boundary condition, we consider the Gibbs distribution on V conditional on the assignment τ on the boundary of V. The case where there is no boundary condition is known as the *free boundary* case and is also covered by our results.

In \mathbb{Z}^2 , SSM is known to hold for all $q \geq 2$ and all $\beta < \beta_c(q)$, where $\beta_c(q) = \ln(1 + \sqrt{q})$ is the uniqueness threshold [2, 3, 38]. Therefore, we obtain the following immediate corollary of Theorem 1.1.

COROLLARY 1.2. In an n-vertex square region of \mathbb{Z}^2 , for all $q \geq 2$, all $\beta < \beta_c(q)$ and all boundary conditions, we have $T_{\text{mix}}(SW) = \Theta(\log n)$.

The best previous bound in the setting of Corollary 1.2 was $T_{\text{mix}}(SW) = O(n)$ and follows from the results in [5]. Nam and Sly [43] recently proved an $O(\log n)$ mixing time bound (as well as the cutoff phenomenon) for the periodic boundary condition for sufficiently high temperatures ($\beta \ll \beta_c(q)$), a stronger assumption than SSM. In higher dimensions $d \geq 3$, SSM is not known to hold up to the corresponding uniqueness threshold (it is only known for sufficiently small β ; see [35]), but we expect the SW dynamics to be rapidly mixing throughout the high temperature regime for all $d \geq 3$.

The key to our improved mixing time analysis is a novel *factorization of entropy* based on the joint probability space of spins and edges that underlies the SW dynamics. This factorization implies that the relative entropy decays at a constant rate, which in turn implies a tight bound on the mixing time via a modified log-Sobolev inequality. In contrast, previous bounds for the SW dynamics [5, 6, 9, 25, 46] have used the spectral gap, which inherently loses a factor of O(n) when transferred to mixing time bounds and cannot deliver a tight result. We discuss our new technique and its ramifications in the next subsection.

A priori the correct order of the mixing time of the SW dynamics is unclear. In some settings, such as on the complete graph (the mean-field Potts model) for all β below the uniqueness threshold, the dynamics mixes in $\Theta(1)$ steps [21, 32]. In this paper, to complement our main result of an $O(\log n)$ upper bound, we also establish a lower bound of $\Omega(\log n)$ for all boundary conditions whenever SSM holds. To prove our lower bound, we follow the strategy introduced by Hayes and Sinclair [26], who proved a tight lower bound on the mixing time of the local Glauber dynamics. However, the synchronicity and non-locality of the updates in the SW dynamics presents a significant obstacle to the adaptation of their techniques and some new ideas are required. The main novel ingredient in our proof of the lower bound is an analysis of the speed of propagation of disagreements under a coupling of the steps of the SW dynamics, provided SSM holds. To establish this we use a recent breakthrough result of Duminil-Copin, Raoufi, and Tassion [17] establishing exponential decay of correlations (i.e., weak spatial mixing) in the entire high-temperature phase for the Potts model on \mathbb{Z}^d . We believe that our analysis of the speed of disagreement propagation could be useful for establishing lower bounds for the mixing time of SW dynamics in other settings.

Our methods also provide new results for the low-temperature regime $\beta > \beta_c(q)$ in \mathbb{Z}^2 for specific boundary conditions. We say that a boundary condition τ is *monochromatic* if τ fixes the spin of every boundary vertex to the same color. One of the most fundamental open problems in the study of the Glauber dynamics for the Ising and Potts model concerns the mixing time at low temperatures with a monochromatic boundary [33, 40]. We provide new bounds for the mixing time of the SW dynamics in this setting.

THEOREM 1.3. In an n-vertex square region of \mathbb{Z}^2 , for all $q \geq 2$ and all $\beta > \beta_c(q)$ we have $T_{\min}(SW) = O(n \log n)$ for the free or monochromatic boundary condition.

The best previously known bound for the mixing time of the SW dynamics in an n-vertex square region of \mathbb{Z}^2 when $\beta > \beta_c(q)$ was $O(n^2\log^2 n)$, which follows from the results in [9, 46]; see also [34] for better (sub-linear) bounds for the mixing time when q=2 and $\beta \gg \beta_c(q)$. The bound in Theorem 1.3 is likely not tight, and establishing that the SW dynamics mixes in $O(\log n)$ steps in \mathbb{Z}^2 throughout the low-temperature regime remains an important open problem. Furthermore, our result for low temperature with a monochromatic boundary does not extend to higher dimensions $d \geq 3$, since it crucially uses the self-duality for the associated random-cluster distribution on \mathbb{Z}^2 . For the Ising model with $d \geq 3$, the state of the art seems to be the results from [34] for $\beta \gg \beta_c(q)$.

1.1 A New Analytic Tool

A standard tool for the analysis of Markov chains are comparison inequalities, which relate the spectral gap of a chain of interest to that of some simpler chain that has already been analyzed. This approach has proven particularly useful for analysis of the SW dynamics; indeed, some of the currently best known upper bounds on its mixing time are obtained in this manner [5, 6, 9, 25, 46]. As mentioned earlier, this approach is unable to yield tight bounds on the mixing time of the SW dynamics since bounds obtained via the spectral gap inherently introduce a factor $\log(1/\mu_*) = \Omega(n)$ into the mixing time, where $\mu_* = \min_{\sigma} \mu(\sigma)$.

A potentially more powerful approach is to compare instead the (classical) log-Sobolev constants (see Definition 2.6). This yields mixing time bounds with only a $\log\log(1/\mu_*) = O(\log n)$ dependence on μ_* , which is potentially tight. Unfortunately, however, log-Sobolev inequalities are not tight for the SW dynamics, and the best possible mixing time bound obtained in this way would be O(n) (see Remark 3.2 for details).

A modified log-Sobolev inequality (which essentially bounds the rate of decay of relative entropy; see again Definition 2.6) is a strictly weaker (and hence easier to satisfy) inequality than the classical log-Sobolev inequality, but still strong enough to establish mixing time bounds with the same dependence on μ_* . There have been several notable recent results bounding the modified log-Sobolev constant for various Markov chains [15, 27]. However, there are no prior results addressing the modified log-Sobolev constant for the SW dynamics and, more generally, no comparison inequalities are available for the modified log-Sobolev constant. In this paper, we develop new machinery that essentially allows us to compare the modified log-Sobolev constant of the SW dynamics with that of a much simpler dynamics, and hence obtain tight mixing time bounds. This comparison is at the level of entropy factorization

rather than the modified log-Sobolev constant itself, as we now describe.

Approximate factorization of the entropy of the Gibbs distribution μ with constant C says that, for any nonnegative function $f: \Omega \mapsto \mathbb{R}_+$,

$$\operatorname{Ent}_{\mu}(f) \le C \sum_{v \in V} \mu[\operatorname{Ent}_{v}(f)], \tag{1.2}$$

where $\mu[f] = \sum_{\sigma \in \Omega} \mu(\sigma) f(\sigma)$ and $\operatorname{Ent}_{\mu}(f) := \mu[f \log(f/\mu[f])]$ are the expectation and entropy, respectively, of f with respect to μ , and Ent_{v} is the entropy with respect to the conditional distribution at vertex v given the spins of its neighbors. Note that necessarily $C \geq 1$, and C = 1 when μ is a product measure. (The term "constant" here indicates that (1.2) holds for fixed C, independent of f. In most applications, C will in fact be a constant independent of the size of the underlying graph G; we will write C = O(1) to indicate this.) Approximate factorization with C = O(1) played a central role in classical results proving that SSM implies $O(n \log n)$ mixing time of the Glauber dynamics; see, e.g., [14, 37, 44, 47].

Until recently it was unclear how to apply this approach to more general Markov chains. However, in a very recent paper, Caputo and Parisi [13] took an important step in this direction by extending the above factorization as follows:

Definition 1.4. For a spin configuration σ on a bipartite graph G, let σ_E (respectively, σ_O) denote the spins on the even (respectively, odd) side of the bipartition. We say that approximate even/odd factorization with constant C holds if for all functions $f: \Omega \mapsto \mathbb{R}_+$,

$$\operatorname{Ent}_{\mu}(f) \le C(\mu \left[\operatorname{Ent}_{\mu}(f|\sigma_{E}) \right] + \mu \left[\operatorname{Ent}_{\mu}(f|\sigma_{O}) \right]). \tag{1.3}$$

To clarify the meaning of the inequality (1.3), we use the notation $\operatorname{Ent}_{\mu}(f|\sigma_E)$ for the entropy of f with respect to the conditional probability $\mu(\cdot|\sigma_E)$, that is, the Gibbs measure conditioned on a given realization of the even spins σ_E , with similar notation for odd spins. In particular, taking expectations one has

$$\mu \left[\operatorname{Ent}_{\mu}(f|\sigma_{E}) \right] = \mu [f \log(f/\mu[f|\sigma_{E}])],$$

$$\mu \left[\operatorname{Ent}_{\mu}(f|\sigma_{O}) \right] = \mu [f \log(f/\mu[f|\sigma_{O}])].$$

Caputo and Parisi [13] showed that for spin systems on \mathbb{Z}^d , under the SSM assumption, approximate even/odd factorization holds with C = O(1), and used this fact to establish a tight mixing time bound for "block dynamics" in \mathbb{Z}^d , a generalization of Glauber dynamics in which a randomly chosen block of spins (rather than a single spin) is updated in each step.

Our main analytic tool in this paper establishes that, on any bounded degree bipartite graph, even/odd factorization is in fact sufficient to ensure $O(\log n)$ mixing time for the much more complex SW dynamics. Note that SW is very far from a block dynamics, in that the configurations of multiple, dynamically changing clusters of spins are updated simultaneously in each step.

Theorem 1.5. For all constant Δ , for any bipartite graph of maximum degree Δ , if the Gibbs distribution satisfies approximate even/odd factorization with C = O(1) then the mixing time of the Swendsen–Wang dynamics is $O(\log n)$.

We remark that Theorem 1.5 holds for arbitrary boundary conditions (or pinnings of vertices) of the bipartite graph, and thus

Theorem 1.1 for the lattice \mathbb{Z}^d follows immediately from this theorem and the above mentioned results in [13].

The main technical step in the proof of Theorem 1.5 is to show that even/odd factorization implies a novel *spin/edge factorization* of entropy (see Defintion (1.6) below), which is tailored to the SW dynamics so that it implies $O(\log n)$ mixing fairly directly.

1.2 The Spin/Edge Factorization

Our new entropy factorization is based on the joint probability space on spins and edges introduced by Edwards and Sokal [19], that underlies the SW dynamics. Let $\Omega_J = \Omega \times \{0,1\}^{\mathbb{E}}$ be the set of joint configurations (σ,A) consisting of a spin assignment to the vertices $\sigma \in \Omega$ and a subset of edges $A \subseteq \mathbb{E}$, where recall that \mathbb{E} is the set of edges with both endpoints in V. The Edwards-Sokal distribution on G with parameters $p \in [0,1]$ and $q \in \mathbb{N}$, and free boundary condition, is the probability measure on Ω_I given by

$$\nu(\sigma, A) := \frac{1}{Z_{\mathsf{I}}} p^{|A|} (1 - p)^{|\mathbb{E}| - |A|} \mathbf{1}(\sigma \sim A), \tag{1.4}$$

where $\sigma \sim A$ means that $A \subseteq M(\sigma)$ (i.e., that every edge in A is monochromatic in σ) and Z_J is the corresponding normalizing constant or partition function. When $p=1-e^{-\beta}$, the "spin marginal" of ν is precisely the Potts distribution μ and $Z=Z_J$; the "edge marginal" of ν corresponds to the well-known random-cluster measure; see [20, 24]. The SW dynamics alternates between spin configurations and joint spin/edge configurations in a manner consistent with (1.4).

We note that a boundary condition on the joint space allows fixing the state of both spins and edges and thus may introduce more complex dependencies. While our results in the joint space are stated here only for the free boundary condition, they actually extend to any spin-only boundary condition. By a "spin-only" boundary condition we mean any boundary condition that fixes the spins of a subset of vertices, and fixes no values for the edges. In fact, in \mathbb{Z}^d , we can handle a slightly more general class of boundary conditions we call admissible (see Definition 4.1) which will be useful for proving Theorem 1.3 and our results for random-cluster dynamics.

Our entropy factorization for the SW dynamics is defined as follows.

DEFINITION 1.6. We say that approximate spin/edge factorization with constant C holds if for all functions $f: \Omega_I \mapsto \mathbb{R}_+$,

$$\operatorname{Ent}_{\nu}(f) \le C \left(\nu \left[\operatorname{Ent}_{\nu}(f|\sigma) \right] + \nu \left[\operatorname{Ent}_{\nu}(f|A) \right] \right). \tag{1.5}$$

Let us explain the terms in (1.5) in more detail. We write $v(\cdot|\sigma)$ for the probability obtained from v by conditioning the on whole spin configuration being equal to a given $\sigma \in \Omega$ and $v(\cdot|A)$ for the probability obtained from v by conditioning on the whole edge configuration being equal to a given $A \subseteq \mathbb{E}$. With this notation, $\operatorname{Ent}_{v}(f|\sigma)$ and $\operatorname{Ent}_{v}(f|A)$ denote the entropy of f with respect to the conditional measures $v(\cdot|\sigma)$ and $v(\cdot|A)$, respectively. Therefore, taking their expectations with respect to v one obtains

$$v\left[\operatorname{Ent}_{\nu}(f|\sigma)\right] = \nu[f\log(f/\nu[f|\sigma])],$$

$$v\left[\operatorname{Ent}_{\nu}(f|A)\right] = \nu[f\log(f/\nu[f|A])]. \tag{1.6}$$

The main technical ingredient in proving Theorem 1.5 is the following "comparison lemma" for entropy factorization.

Lemma 1.7. For the Potts model at inverse temperature β on any bipartite graph of maximum degree Δ , approximate even/odd factorization with constant C implies approximate spin/edge factorization with constant $C' = C'(C, \Delta, q, \beta)$.

To complete the proof of Theorem 1.5, we show that the spin/edge factorization in (1.5) implies decay of entropy for the SW dynamics: namely, there exists a constant $\delta > 0$ such that, for all functions $f: \Omega \mapsto \mathbb{R}_+$, we have

$$\operatorname{Ent}_{\mu}(P_{\mathrm{SW}}f) \le (1 - \delta)\operatorname{Ent}_{\mu}(f),\tag{1.7}$$

where $P_{\rm SW}$ denotes the transition matrix of the SW dynamics. As we recall in Section 2.2, standard arguments then imply a modified log-Sobolev inequality, and a bound of $O(\log n)$ on the mixing time of the SW dynamics.

LEMMA 1.8. For the Potts model on any n-vertex graph, approximate spin/edge factorization with constant C = O(1) implies that (1.7) holds with $\delta = 1/C$ and hence $T_{mix}(SW) = O(\log n)$.

1.3 Further Results

Our new entropy factorization framework leads to several additional algorithmic results on \mathbb{Z}^d that hold under the condition of SSM, which we briefly summarize here. First, we prove optimal $O(\log n)$ mixing time for alternating systematic scan dynamics, a natural non-local dynamics in which even and odd sides of the bipartition are updated on alternate steps. Systematic scan dynamics, in which updates are performed in a deterministic rather than random sequence, are widely used in practice but are non-reversible and typically much harder to analyze. Second, we are able to show that various versions of the SW dynamics on the joint spin/edge space mix in $O(\log n)$ time, as does the SW dynamics for the random-cluster model. Finally, we show that a natural local Glauber dynamics in the joint space has optimal mixing time $\Theta(n \log n)$. Formal statements of all these results and their proofs can be found in the full version of the paper [4].

Organization of the paper: In Section 2 we gather definitions of various standard concepts used throughout the paper. Section 3 proves Lemma 1.8 showing that the spin/edge entropy factorization implies $O(\log n)$ mixing for the SW dynamics. We prove Lemma 1.7 relating even/odd factorization to spin/edge factorization in Section 4, and then combine Lemmas 1.7 and 1.8 to establish our main technical tool (Theorem 1.5) and our main algorithmic result (Theorem 1.1). Our lower bound on the mixing time is proved in Section 5. The rest of our results and further applications are proved and discussed in the full version [4].

2 BACKGROUND

In this section, we formally define the spatial mixing property to be used throughout the paper. We also recall some known relations and prove some preliminary facts concerning entropy and mixing times.

2.1 Strong Spatial Mixing (SSM)

We assume $V \subset \mathbb{Z}^d$ is a d-dimensional cube in \mathbb{Z}^d . That is, $V = \{0, 1, \dots, \ell\}^d$ where ℓ is a positive integer. We use $\partial V \subseteq V$ to denote the *internal boundary* of V; i.e., the set of vertices in V

adjacent to at least one vertex in $\mathbb{Z}^d \setminus V$. A boundary condition ψ for V is an assignment of spins to some (or all) vertices in ∂V ; i.e., $\psi: U^\psi \to [q]$ with $U^\psi \subset \partial V$. The boundary condition where $U^\psi = \emptyset$ is called the *free boundary condition*. Given a boundary condition ψ , each configuration $\sigma \in \Omega$ that agrees with ψ on U^ψ is assigned probability

$$\mu^{\psi}(\sigma) = \frac{1}{Z^{\psi}} \cdot e^{-\beta |D(\sigma)|},$$

where Z^{ψ} is the corresponding normalizing constant and $D(\sigma) := \{\{v, w\} \in \mathbb{E} : \sigma_v \neq \sigma_w\}$. We define $\mu^{\psi}(\sigma) = 0$ for $\sigma \in \Omega$ that does not agree with ψ .

Let C(V, a, b) be the property that, for all $B \subset V$, all $u \in \partial V$ and any pair of boundary conditions ψ , ψ_u on ∂V that differ only in the spin of the vertex u, we have

$$\|\mu_B^{\psi} - \mu_B^{\psi_u}\|_{\text{TV}} \le b \exp(-a \cdot \text{dist}(u, B)), \tag{2.1}$$

where μ_B^{ψ} and $\mu_B^{\psi_u}$ are the probability measures induced in B by the Potts distribution with boundary conditions ψ and ψ_u , respectively, $\|\cdot\|_{\text{TV}}$ denotes total variation distance and $\text{dist}(u, B) = \min_{v \in B} \|u - v\|_1$.

DEFINITION 2.1. We say that strong spatial mixing (SSM) holds if there exist a, b > 0 such that C(V, a, b) holds for every cube $V \subset \mathbb{Z}^d$.

We note that the definition of SSM varies in the literature, but we work here with one of the weakest (easiest to satisfy) versions. In \mathbb{Z}^2 , this form of SSM has been established for all $q\geq 2$ and $\beta<\beta_c(q)$, where $\beta_c(q)=\ln(1+\sqrt{q})$ is the uniqueness threshold [2, 3, 38]. Finally, we stress that the SSM property is determined only by the values of the parameters q and $p=1-e^{-\beta}$, and not by any particular boundary condition.

Remark 2.2. For definiteness, we have stated all of our results for n-vertex d-dimensional cubes but they extend to more general regions of \mathbb{Z}^d . In particular, we can consider regions which are the union of disjoint translates of a given large enough cube. The variant of the SSM condition that requires C(U, a, b) to hold for every such region U is equivalent to the one in Definition 2.1 (see [36, Theorem 2.6]). As noted in [36], a version of SSM which requires C(V, a, b) to hold for arbitrarily shaped regions V does not hold all the way to the uniqueness threshold.

2.2 Mixing Time, Entropy and Log-Sobolev Inequalities

Let P be the transition matrix of an ergodic Markov chain with finite state space Γ and stationary distribution π . Let $P^t(X_0,\cdot)$ denote the distribution of the chain after t steps starting from the initial state $X_0 \in \Gamma$. The $mixing\ time\ T_{mix}(P)$ of the chain is defined as

$$T_{\min}(P) = \max_{X_0 \in \Gamma} \min \{ t \ge 0 : \|P^t(X_0, \cdot) - \pi\|_{\text{TV}} \le 1/4 \}.$$

To prove upper bounds on the mixing time, in this paper we mostly rely on functional inequalities related to entropy.

For a function $f: \Gamma \mapsto \mathbb{R}$, let $\pi[f] = \sum_{\sigma \in \Omega} \pi(\sigma) f(\sigma)$ and $\operatorname{Var}_{\pi}(f) = \pi[f^2] - \pi[f]^2$ denote its mean and variance with respect

to π . Likewise, for f positive, the *entropy* of f with respect to π is defined as

$$\operatorname{Ent}_{\pi}(f) = \pi \left[f \log \left(\frac{f}{\pi[f]} \right) \right] = \pi[f \log f] - \pi[f] \log \pi[f]. \tag{2.2}$$

We often consider these functionals and their conditional versions with respect to the Potts measure μ or the joint measure ν (as defined in (1.1) and (1.4) respectively). In particular, if the function f is such that $f: \Omega_{\mathsf{J}} \mapsto \mathbb{R}_+$, for fixed $\sigma \in \Omega$ and $A \subseteq \mathbb{E}$, we write $\nu[f|\sigma] = \sum_{A \subseteq \mathbb{E}} \nu(A|\sigma) f(\sigma, A)$, $\nu[f|A] = \sum_{\sigma \in \Omega} \nu(\sigma|A) f(\sigma, A)$ and

$$\operatorname{Ent}_{\nu}(f|\sigma) = \nu \left[f \cdot \log \left(\frac{f}{\nu[f|\sigma]} \right) \middle| \sigma \right],$$

$$\operatorname{Ent}_{\nu}(f|A) = \nu \left[f \cdot \log \left(\frac{f}{\nu[f|A]} \right) \middle| A \right].$$

Note that $\operatorname{Ent}_{\nu}(f|\sigma)$ and $\operatorname{Ent}_{\nu}(f|A)$ are functions of $\sigma \in \Omega$ and $A \subseteq \mathbb{E}$, respectively, and with slight abuse of notation, we write $\nu \operatorname{[Ent}_{\nu}(f|\sigma)$] and $\nu \operatorname{[Ent}_{\nu}(f|A)$] for the corresponding expectations with respect to ν ; see (1.6). The following identities hold:

$$\operatorname{Ent}_{\nu}(f) = \operatorname{Ent}_{\nu}(\nu[f|A]) + \nu[\operatorname{Ent}_{\nu}(f|A)]; \tag{2.3}$$

$$\operatorname{Ent}_{\nu}(f) = \operatorname{Ent}_{\nu}(\nu[f|\sigma]) + \nu[\operatorname{Ent}_{\nu}(f|\sigma)]. \tag{2.4}$$

Indeed, both statements follow from the general decomposition

$$\operatorname{Ent}_{\pi}(f) = \operatorname{Ent}_{\pi}(\pi[f|\mathcal{F}]) + \pi[\operatorname{Ent}_{\pi}(f|\mathcal{F})], \tag{2.5}$$

valid for any distribution π , and any sub σ -algebra \mathcal{F} , which follows by adding and subtracting the term $\pi(f \log \pi[f|\mathcal{F}])$ in (2.2). Another basic property of entropy that we shall use is the variational principle

$$\operatorname{Ent}_{\pi}(f) = \sup \left\{ \pi [f\varphi], \ \pi [e^{\varphi}] \le 1 \right\}, \tag{2.6}$$

valid for any distribution π , and any $f \ge 0$, where the supremum ranges over all functions $\varphi : \Gamma \mapsto \mathbb{R}$ such that $\pi[e^{\varphi}] \le 1$, see e.g. Proposition 2.2 in [31].

When $f \ge 0$ is such that $\pi[f] = 1$, then $\operatorname{Ent}_{\pi}(f) = H(f\pi \mid \pi)$ corresponds to the *relative entropy*, or Kullback-Leibler divergence, between the distribution $f\pi$ and π .

DEFINITION 2.3. A Markov chain with transition matrix P and stationary distribution π is said to satisfy the (discrete time) relative entropy decay with rate $\delta > 0$ if for all distributions ζ ,

$$H(\zeta P|\pi) \le (1 - \delta)H(\zeta|\pi). \tag{2.7}$$

We recall a well known consequence of entropy decay for the mixing time. For completeness, we include a proof in the full version of our paper [4].

Lemma 2.4. If a Markov chain with transition matrix P and stationary distribution π satisfies relative entropy decay with rate $\delta > 0$, then its mixing time $T_{mix}(P)$ satisfies

$$T_{\text{mix}}(P) \le 1 + \delta^{-1} [\log(8) + \log \log(1/\pi_*)],$$

where $\pi_* = \min_{\sigma} \pi(\sigma)$.

Remark 2.5. If ζ has density f with respect to π (i.e., $\zeta = f\pi$), then ζP has density P^*f with respect to π , where P^* is the adjoint or time-reversal matrix $P^*(\sigma,\sigma') = \frac{\pi(\sigma')}{\pi(\sigma)}P(\sigma',\sigma)$. Thus, (2.7) is equivalent to

$$\operatorname{Ent}_{\pi}(P^*f) \le (1 - \delta)\operatorname{Ent}_{\pi}(f), \tag{2.8}$$

for all $f \ge 0$ such that $\pi[f] = 1$. By homogeneity, this is equivalent to (2.8) for all $f \ge 0$. When P is reversible, that is when $P = P^*$, (2.7) is equivalent to $\operatorname{Ent}_{\pi}(Pf) \le (1 - \delta)\operatorname{Ent}_{\pi}(f)$ for all $f \ge 0$.

The inequality (2.8) can be considered as a discrete time analogue of the so-called modified log-Sobolev inequality characterizing the relative entropy decay for continuous time Markov chains; see, e.g. [10]. Below we discuss some basic relations among (2.8), the standard log-Sobolev inequality and the modified log-Sobolev inequality.

Consider a transition matrix P with stationary distribution π . The *Dirichlet form* associated to the pair (P, π) is defined as

$$\mathcal{D}_P(f,g) = \langle f, (1-P)g \rangle,$$

where f,g are real functions on Γ , $\langle f,g\rangle=\pi[fg]$ denotes the scalar product in $L^2(\pi)$ and 1 is the identity matrix. Since f is real we also have

$$\mathcal{D}_{P}(f,f) = \langle (1-Q)f, f \rangle = \frac{1}{2} \sum_{x,y} \pi(x) Q(x,y) (f(x) - f(y))^{2},$$

where $Q = \frac{1}{2}(P + P^*)$. Moreover, if $P = P^*$ one has

$$\mathcal{D}_{P}(f,g) = \frac{1}{2} \sum_{x,y} \pi(x) P(x,y) (f(x) - f(y)) (g(x) - g(y)),$$

for all f, g.

DEFINITION 2.6. The pair (P, π) is said to satisfy the (standard) log-Sobolev inequality (LSI) with constant α if for all $f \ge 0$:

$$\mathcal{D}_P(\sqrt{f}, \sqrt{f}) \ge \alpha \operatorname{Ent}_{\pi}(f).$$

It is said to satisfy the modified log-Sobolev inequality (MLSI) with constant δ if for all $f \geq 0$:

$$\mathcal{D}_P(f, \log f) \ge \delta \operatorname{Ent}_{\pi}(f).$$
 (2.9)

It is well known that the Log-Sobolev inequality is equivalent to the so-called hypercontractivity (see [16, Theorem 3.5]), while the modified Log-Sobolev inequality (2.9) is equivalent to exponential decay of the relative entropy with rate δ for the continuous time kernel $K_t = e^{(P-1)t}$ (see [16, Theorem 3.6]). Note that we are not assuming reversibility. To see the relation between the MLSI and the entropy decay in continuous time, note that if $K_t = e^{(P-1)t}$ and f has mean $\pi[f] = 1$ then using $K_t^* = e^{(P^*-1)t}$ one checks that the time derivative of the relative entropy satisfies

$$\frac{d}{dt}H(\zeta K_t|\pi) = \frac{d}{dt}\text{Ent}(K_t^*f) = -\mathcal{D}_P(K_t^*f, \log K_t^*f),$$

where $\zeta = f \cdot \pi$. Therefore (2.9) implies, for all $t \ge 0$:

$$H(\zeta K_t | \pi) \leq H(\zeta | \pi) e^{-\delta t}$$
.

Next, we observe that the bound (2.8) is stronger than the MLSI in (2.9).

Lemma 2.7. If the entropy decay holds with rate δ in discrete time then it holds with the same rate in continuous time. That is, (2.8) implies the MLSI with constant δ .

A proof of this fact is given in the full version of the paper [4]. It is also well known that the standard LSI with constant α implies entropy decay in continuous time with rate $\delta = 2\alpha$, since

 $\mathcal{D}_P(f, \log f) \ge 2\mathcal{D}_P(\sqrt{f}, \sqrt{f})$ for all $f \ge 0$, and this can be improved to $\delta = 4\alpha$ in the reversible case; see [16, Lemma 2.7]. Here we recall a result of Miclo [41] showing in what sense the LSI implies the discrete time entropy decay.

LEMMA 2.8. If the pair (P^*P, π) satisfies the standard LSI with constant α , then the discrete time entropy decay holds for (P, π) with constant $\delta = \alpha$. In particular, if P is reversible and (P, π) satisfies the LSI with constant α , then for all $f \geq 0$:

$$\operatorname{Ent}_{\pi} Pf \leq (1 - \alpha) \operatorname{Ent}_{\pi} f$$
.

3 SPIN/EDGE FACTORIZATION IMPLIES FAST MIXING: PROOF OF LEMMA 1.8

As mentioned in the introduction, the proof of our main new analytic tool (Theorem 1.5) has two components. We show that approximate even/odd factorization implies spin/edge factorization (Lemma 1.7), and then that spin/edge factorization implies $O(\log n)$ mixing for the SW dynamics (Lemma 1.8). In this section, we provide the proof of the latter result, whereas Lemma 1.7 is proved in the subsequent section.

PROOF OF LEMMA 1.8. We show that the spin/edge factorization with constant C implies that for all functions $f \ge 0$ with $\mu[f] = 1$, one has

$$\operatorname{Ent}_{\mu}(P_{\operatorname{SW}}f) \le (1 - \delta)\operatorname{Ent}_{\mu}(f), \tag{3.1}$$

with $\delta = 1/C$. Since the SW dynamics is reversible with respect to μ , we have $P_{\rm SW} = P_{\rm SW}^*$, and the desired mixing time bound follows from Lemma 2.4 and Remark 2.5.

The transition matrix of the SW dynamics satisfies $P_{\rm SW}(\sigma,\tau) = \sum_{A\subseteq M(\sigma)} v(A|\sigma)v(\tau|A)$, where we recall that $M(\sigma)$ is the set of monochromatic edges in σ . Hence,

$$P_{\mathrm{SW}}f(\sigma) = \sum_{\tau \in \Omega} P_{\mathrm{SW}}(\sigma,\tau) f(\tau) = \sum_{\tau \in \Omega} \sum_{A \subseteq M(\sigma)} v(A|\sigma) v(\tau|A) \hat{f}(\tau,A),$$

where the function $\hat{f}: \Omega_J \mapsto \mathbb{R}_+$ is the "lift" of f to the joint space, i.e., $\hat{f}(\sigma, A) = f(\sigma)$ for every $(\sigma, A) \in \Omega_J$. Recalling that we write $v[f], v[f|A], v[f|\sigma]$ for the expectations of f with respect to the measures $v(\cdot), v(\cdot \mid A), v(\cdot \mid \sigma)$, respectively, we obtain

$$P_{\mathrm{SW}}f(\sigma) = \sum_{A \subseteq M(\sigma)} \nu(A|\sigma)\nu[\hat{f} \mid A] = \nu[\nu[\hat{f}|A]|\sigma] = \nu[g|\sigma],$$

where for ease of notation we set $g := \nu[\hat{f}|A]$. Since $\mu[f] = 1$, we have $\mu[P_{\text{SW}}f] = 1$ and

$$\operatorname{Ent}_{\mu}(P_{\operatorname{SW}} f) = \mu[(P_{\operatorname{SW}} f) \log(P_{\operatorname{SW}} f)] = \mu \left[\nu \left[g | \sigma \right] \log(\nu \left[g | \sigma \right]) \right].$$

The convexity of the function $x \cdot \log x$ and Jensen's inequality imply

$$v[g|\sigma]\log(v[g|\sigma]) \le v[g\log g \mid \sigma],$$

and then, since $v[q] = v[\hat{f}] = \mu[f] = 1$, we have

$$\operatorname{Ent}_{\mu}(P_{\mathrm{SW}}f) \le \mu \left[\nu \left[g \log g \mid \sigma \right] \right] = \nu \left[\nu \left[g \log g \right] \mid \sigma \right]$$
$$= \nu \left[g \log q \right] = \operatorname{Ent}_{\nu}(q). \tag{3.2}$$

For any function $h: \Omega_J \mapsto \mathbb{R}_+$, we have by (2.3) that $\operatorname{Ent}_{\nu}(h) = \operatorname{Ent}_{\nu}(\nu[h|A]) + \nu[\operatorname{Ent}_{\nu}(h|A)]$. Hence,

$$\operatorname{Ent}_{\nu}(\hat{f}) = \operatorname{Ent}_{\nu}(g) + \nu [\operatorname{Ent}_{\nu}(\hat{f}|A)],$$

which by (3.2) gives $\operatorname{Ent}_{\mu}(P_{\operatorname{SW}}f) \leq \operatorname{Ent}_{\nu}(\hat{f}) - \nu[\operatorname{Ent}_{\nu}(\hat{f}|A)]$. The function \hat{f} depends on σ only, so $\operatorname{Ent}_{\nu}(\hat{f}|\sigma) = 0$. Therefore,

$$\operatorname{Ent}_{\mu}(P_{\operatorname{sw}}f) \leq \operatorname{Ent}_{\nu}(\hat{f}) - \nu \left[\operatorname{Ent}_{\nu}(\hat{f}|A) + \operatorname{Ent}_{\nu}(\hat{f}|\sigma) \right].$$

The assumed spin/edge factorization (1.5) then implies that

$$\operatorname{Ent}_{\mu}(P_{\operatorname{SW}}f) \leq (1-\delta)\operatorname{Ent}_{\nu}(\hat{f}),$$

with $\delta = 1/C$. Inequality (3.1) follows from the fact that $\operatorname{Ent}_{\nu}(\hat{f}) = \operatorname{Ent}_{\mu}(f)$.

Remark 3.1. We do not assume anything about the underlying graph in the previous proof, so Lemma 1.8 holds for any graph G. In addition, our proof as stated applies to the Potts measure μ obtained as the marginal on spins of the joint measure v. If v is as in (1.4), this yields only the Potts measure on V with the free boundary condition. However, the proof extends to the Potts measure with any boundary condition (or pinning of vertices) by choosing a spin-only boundary condition for v. In particular, Theorem 1.1 holds for arbitrary boundary conditions, as stated in the introduction. For the special case when G is a cube of \mathbb{Z}^d , we allow a slightly more general class of boundary conditions, involving both spin and edges, which we call admissible; see Definition 4.1 and the examples immediately following it.

Remark 3.2. The entropy contraction established in (3.1) implies a modified log-Sobolev inequality, and can be viewed as a discrete time version of it; see Section 2.2. The classical log-Sobolev constant, however, is not tight for the SW dynamics. Indeed, the remark in [35, Section 3.7] shows a test function f such that $\mathrm{Var}_{\mu}(\sqrt{f})/\mathrm{Ent}_{\mu}(f) = O(n^{-1})$. Since $\mathcal{D}_{P_{SW}}(\sqrt{f},\sqrt{f}) = v[\mathrm{Var}(\sqrt{f}|A)]$, it follows from monotonicity of variance functional that $\mathcal{D}_{P_{SW}}(\sqrt{f},\sqrt{f}) \leq \mathrm{Var}_{\mu}(\sqrt{f})$ and so $\frac{\mathcal{D}_{P_{SW}}(\sqrt{f},\sqrt{f})}{\mathrm{Ent}_{\mu}(f)} = O(n^{-1})$ for this function.

4 FACTORIZATION OF ENTROPY IN THE JOINT SPACE

In this section, we prove our main technical result, Lemma 1.7, which states that approximate even/odd factorization implies approximate spin/edge factorization for the Potts measure on bipartite graphs. For clarity of notation, and to simplify the proofs, we will restrict attention to n-vertex cubes in \mathbb{Z}^d , but it should be clear that everything extends to arbitrary bipartite graphs of constant degree with any spin-only boundary condition. In addition, on \mathbb{Z}^d we are able to extend our results to a more general class of boundary conditions in the joint space, involving both edges and vertices, that we call admissible.

Admissible boundary conditions. Let ∂V be the set of vertices of V with a neighbor in $\mathbb{Z}^d \setminus V$. Let $\partial \mathbb{E}$ denote the set of edges in \mathbb{E} with at least one endpoint in ∂V . (Recall that \mathbb{E} is the set of edges with both endpoints in V.) We consider boundary conditions for the joint space on subsets $V_0 \subseteq \partial V$ and $\mathbb{E}_0 \subseteq \partial \mathbb{E}$. Specifically, we let $\psi: V_0 \mapsto [q]$ and $\varphi: \mathbb{E}_0 \mapsto \{0, 1\}$ and define

$$v^{\psi,\varphi}(\sigma,A) = \frac{1}{Z^{\psi,\varphi}} p^{|A|} (1-p)^{|\mathbb{E}|-|A|} \mathbf{1}(\sigma \sim A) \mathbf{1}(\sigma \sim \psi) \mathbf{1}(A \sim \varphi), \tag{4.1}$$

where $\sigma \sim A$ means that $A \subseteq M(\sigma)$, $\sigma \sim \psi$ that σ and ψ agree on the spins in V_0 , and $A \sim \varphi$ that A and φ agree on the edges in \mathbb{E}_0 . As usual, $Z^{\psi,\varphi}$ is the corresponding partition function.

DEFINITION 4.1. We call the boundary condition admissible if $\mathbb{E}_0 \subset \{\{u,v\} \in \partial \mathbb{E} : u \in V_0\}$; that is, if all edges in \mathbb{E}_0 have at least one endpoint in V_0 .

Notice that the free boundary condition $(V_0 = \emptyset)$ and $\mathbb{E}_0 = \emptyset$) is admissible, and all spin-only boundary conditions $(V_0 \subset \partial V)$ and $\mathbb{E}_0 = \emptyset$) are also admissible. In this case, the marginal on spins is just the Potts measure with ψ as the boundary condition on ∂V with $U^{\psi} = V_0$. For some additional examples of admissible boundary conditions the reader is referred to the full version [4].

The main motivation for introducing the notion of admissible boundary conditions is that it guarantees that the spin marginal of $\nu^{\psi,\varphi}$ has the desired exponential decay of correlations if the parameters q and β are such that SSM holds. We shall see that all of our results concerning the joint measure and its dynamics on \mathbb{Z}^d extend to the more general class of admissible boundary conditions. We can therefore restate Lemma 1.7 from the introduction for the special case of \mathbb{Z}^d allowing arbitrary admissible boundary conditions.

LEMMA 4.2. Let $v := v^{\psi, \varphi}$ be the joint distribution with an admissible boundary condition (ψ, φ) . Approximate even/odd factorization with constant C of the spin marginal of v implies that approximate spin/edge factorization holds with constant $C' = C'(C, d, q, \beta)$.

For simplicity, we will continue to write ν for the joint measure $\nu^{\psi,\varphi}$ and μ for its marginal on spins. We shall see that our proofs in this section are largely oblivious to the boundary condition or the geometry of \mathbb{Z}^d (in fact, we only require the underlying graph to be bipartite). We also remark that, while we could allow a slightly more general family of boundary conditions than the admissible ones, some limitations are needed. For instance, arbitrary edge boundary conditions may cause long-range dependencies; see, e.g., [7, 9]. We proceed next with the proof of Lemma 4.2.

4.1 Proof of Lemma 4.2

Overview. The following high level observations might be of help before entering the technical details of the proof. First, notice that the conclusion in the theorem would trivially hold true with constant C=1 if ν were a product measure with respect to the two sets of variables (σ,A) . This is a consequence of standard factorization properties of product measures. Thus, the minimal constant C for which that statement holds is a measure of the "cost" for "separating" the two sets of variables.

When the dependencies between the two sets of variables are very weak, a factorization statement could be obtained as in [14]. However, in our case the dependencies are not weak, since the spin variables interact locally with the edge variable in a strong way. For instance, the presence of the edge xy in A forces deterministically the condition $\sigma_X = \sigma_y$. Thus, the fact that our statement holds with a constant C independent of n is highly nontrivial.

On the other hand, for every $x \in V$ one can separate *locally* the two variables (σ_x, A_x) , where A_x denotes the set of edge variables for edges incident to x, by paying a finite cost C; this is the content of Lemma 4.7 below. We can then lift this local factorization to a global factorization statement for the conditional measure $v(\cdot|\sigma_E)$, respectively $v(\cdot|\sigma_O)$, obtained by conditioning on the spin variables

of all even vertices $E \subset V$, respectively of all odd vertices $O \subset V$. This is the content of Lemma 4.4.

Lemma 4.4 is the heart of the proof and relies crucially on the fact that $v(\cdot|\sigma_E)$ is a product measure with respect to $\{(\sigma_x,A_x),x\in O\}$, and $v(\cdot|\sigma_O)$ is a product measure with respect to $\{(\sigma_x,A_x),x\in E\}$. Thus, we reduce the problem of separating the spin/edge variables (σ,A) to the problem of separating the even/odd spin variables (σ_E,σ_O) for the joint distribution v. We then conclude by showing that even/odd factorization for the Potts measure μ implies the even/odd factorization for v. This is the content of Lemma 4.5.

We now turn to the actual proof. Let $\nu(\cdot|\sigma_E,A)$ denote the measure ν conditioned on $\sigma_E = \{\sigma_{\upsilon}, \ \upsilon \in E\}$ and $A \subseteq \mathbb{E}$. Similarly, $\nu(\cdot|\sigma_O,A)$ denotes the measure ν conditioned on $\sigma_O = \{\sigma_{\upsilon}, \ \upsilon \in O\}$ and A. We use $\mathrm{Ent}_{\nu}(f|\sigma_E,A)$ and $\mathrm{Ent}_{\nu}(f|\sigma_O,A)$ to denote the corresponding conditional entropies; for their expectations with respect to ν we use ν [$\mathrm{Ent}_{\nu}(f|\sigma_E,A)$] and ν [$\mathrm{Ent}_{\nu}(f|\sigma_O,A)$]. The next lemma shows that conditioning on the spin configuration of the even or the odd sub-lattice can only decrease the entropy of a function with respect to $\nu(\cdot \mid A)$.

Lemma 4.3. For all functions
$$f: \Omega_J \mapsto \mathbb{R}_+$$
 we have $\nu \left[\operatorname{Ent}_{\nu}(f|A) \right] \geq \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_E, A) \right]; \ \ and \ \ \nu \left[\operatorname{Ent}_{\nu}(f|A) \right] \geq \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_O, A) \right].$

PROOF. We can write

 $\nu[\operatorname{Ent}_{\nu}(f|A)]$

$$\begin{split} &= \nu \left[f \log \left(\frac{f}{\nu[f|A]} \right) \right] \\ &= \nu \left[f \log \left(\frac{f}{\nu[f|\sigma_E, A]} \right) \right] + \nu \left[f \log \left(\frac{\nu[f|\sigma_E, A]}{\nu[f|A]} \right) \right] \\ &= \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_E, A) \right] + \nu \left[\nu[f|\sigma_E, A] \log \left(\frac{\nu[f|\sigma_E, A]}{\nu[f|A]} \right) \right] \\ &= \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_E, A) \right] + \nu \left[\operatorname{Ent}_{\nu}(\nu[f|\sigma_E, A]|A) \right] \\ &\geq \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_E, A) \right]. \end{split}$$

The same argument applies to the odd sites, so we also deduce that $\nu \left[\mathrm{Ent}_{\nu}(f|A) \right] \geq \nu \left[\mathrm{Ent}_{\nu}(f|\sigma_{O},A) \right].$

The advantage of working with $v(\cdot|\sigma_O,A)$ or $v(\cdot|\sigma_E,A)$ instead of $v(\cdot|A)$ is that once we condition on the spins on all odd (resp. even) sites the measure becomes a product over the even (resp. odd) vertices, and we can exploit tensorization properties of entropy for product measures. The next lemma is a key step in the proof.

Lemma 4.4. There exists a constant $\delta_1 > 0$ depending only on d, β, q such that, for all functions $f: \Omega_J \mapsto \mathbb{R}_+$,

$$\nu \left[\operatorname{Ent}_{\nu}(f|\sigma) \right] + \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_{O}, A) \right] \ge \delta_{1} \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_{O}) \right], \quad (4.2)$$

$$\nu \left[\operatorname{Ent}_{\nu}(f|\sigma) \right] + \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_{E}, A) \right] \ge \delta_{1} \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_{E}) \right]. \tag{4.3}$$

We defer the proof of Lemma 4.4 to later. Adding up (4.2) and (4.3) and using Lemma 4.3 we obtain the estimate

$$\nu \left[\operatorname{Ent}_{\nu}(f|\sigma) + \operatorname{Ent}_{\nu}(f|A) \right] \ge \frac{\delta_{1}}{2} \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_{E}) + \operatorname{Ent}_{\nu}(f|\sigma_{O}) \right]. \tag{4.4}$$

We then use a generalization of the entropy factorization from [13] to reconstruct, in the presence of approximate even/odd factorization, the global entropy $\operatorname{Ent}_{\nu}(f)$ from the conditional average

entropies ν [Ent $_{\nu}(f|\sigma_E)$] and ν [Ent $_{\nu}(f|\sigma_O)$] on the right hand side of (4.4).

LEMMA 4.5. Approximate even/odd factorization with consant C implies that for all functions $f: \Omega_I \mapsto \mathbb{R}_+$,

$$\nu \left[\operatorname{Ent}_{\nu}(f|\sigma_{E}) + \operatorname{Ent}_{\nu}(f|\sigma_{O}) \right] \ge \delta_{2} \operatorname{Ent}_{\nu}(f),$$

where $\delta_2 = 1/C$.

PROOF. We need the following observations:

$$\operatorname{Ent}_{\nu}(f|\sigma_{O}) = \operatorname{Ent}_{\nu}\left(\nu\left[f|\sigma\right]|\sigma_{O}\right) + \nu\left[\operatorname{Ent}_{\nu}(f|\sigma)|\sigma_{O}\right], \tag{4.5}$$

$$\operatorname{Ent}_{\nu}(f|\sigma_{E}) = \operatorname{Ent}_{\nu}\left(\nu\left[f|\sigma\right]|\sigma_{E}\right) + \nu\left[\operatorname{Ent}_{\nu}(f|\sigma)|\sigma_{E}\right]. \tag{4.6}$$

Indeed, to establish (4.5) note that from the definition of conditional entropy we get

 $\operatorname{Ent}_{\nu}(f|\sigma_O)$

$$\begin{split} &= v \left[f \log \left(\frac{f}{v[f|\sigma_O]} \right) \middle| \sigma_O \right] \\ &= v \left[f \log \left(\frac{f}{v[f|\sigma_E, \sigma_O]} \right) \middle| \sigma_O \right] + v \left[f \log \left(\frac{v[f|\sigma_E, \sigma_O]}{v[f|\sigma_O]} \right) \middle| \sigma_O \right] \\ &= v \left[f \log \left(\frac{f}{v[f|\sigma_E, \sigma_O]} \right) \middle| \sigma_O \right] + v \left[v[f|\sigma] \log \left(\frac{v[f|\sigma]}{v[f|\sigma_O]} \right) \middle| \sigma_O \right] \\ &= v \left[\text{Ent}_v(f|\sigma) \middle| \sigma_O \right] + \text{Ent}_v(v[f|\sigma] \middle| \sigma_O), \end{split}$$

where we also use the fact that $v[\cdot|\sigma_E, \sigma_O] = v[\cdot|\sigma]$. The same argument applies to (4.6).

Now, since the function $\nu[f|\sigma]$ depends only on the spin configuration σ ,

$$\begin{split} &\nu\left[\mathrm{Ent}_{\nu}(\nu[f|\sigma]|\sigma_{E}) + \mathrm{Ent}_{\nu}(\nu[f|\sigma]|\sigma_{O})\right] = \\ &\mu\left[\mathrm{Ent}_{\mu}(\nu[f|\sigma]|\sigma_{E}) + \mathrm{Ent}_{\mu}(\nu[f|\sigma]|\sigma_{O})\right]; \end{split}$$

and we may apply the approximate even/odd factorization to the function ν [$f|\sigma$]. Then, there exists a constant $\delta_2 \in (0,1]$ such that

$$\mu \left[\operatorname{Ent}_{\mu}(\nu[f|\sigma]|\sigma_{E}) + \operatorname{Ent}_{\mu}(\nu[f|\sigma]|\sigma_{O}) \right] \ge \delta_{2} \operatorname{Ent}_{\mu} \left(\nu[f|\sigma] \right). \tag{4.7}$$

Therefore, observing that

$$\nu \left[\nu \left[\text{Ent}_{\nu}(f|\sigma)|\sigma_{O} \right] + \nu \left[\text{Ent}_{\nu}(f|\sigma)|\sigma_{E} \right] \right] = 2 \nu \left[\text{Ent}_{\nu}(f|\sigma) \right],$$

we obtain from (4.5), (4.6) and (4.7)

$$\nu[\operatorname{Ent}_{\nu}(f|\sigma_{E}) + \operatorname{Ent}_{\nu}(f|\sigma_{O})]$$

$$\geq \delta_{2} \operatorname{Ent}_{\nu} \left(\nu[f|\sigma]\right) + 2 \nu \left[\operatorname{Ent}_{\nu}(f|\sigma)\right].$$

Since $\delta_2 \leq 1$, the standard decomposition in (2.4) implies

$$\nu \left[\operatorname{Ent}_{\nu}(f|\sigma_{E}) + \operatorname{Ent}_{\nu}(f|\sigma_{O}) \right] \ge \delta_{2} \operatorname{Ent}_{\nu}(f),$$

as claimed.

4.2 Proofs of Main Results

The proofs of Lemma 1.7 and Theorems 1.1 and 1.5 are now immediate.

Proof of Lemma 1.7. We note that inequality (4.4) and Lemma 4.5 are valid for any bipartite graph of bounded degree; the result follows by taking $C = 2/\delta_1 \delta_2$.

Proof of Theorem 1.5. It follows immediately from Lemmas 1.7 and 1.8. $\hfill\Box$

We now also prove our main theorem (Theorem 1.1). We use the following result of [13] that under SSM the even/odd factorization holds.

Theorem 4.6 (Theorem 4.3 in [13]). SSM implies that there exists a constant $\delta > 0$ such that for all cubes of \mathbb{Z}^d , all boundary conditions, and for all functions $f: \Omega \mapsto \mathbb{R}_+$,

$$\mu \left[\operatorname{Ent}_{\mu}(f|\sigma_{E}) + \operatorname{Ent}_{\mu}(f|\sigma_{O}) \right] \geq \delta \operatorname{Ent}_{\mu}(f).$$

PROOF OF THEOREM 1.1. Theorem 4.6 [13, Theorem 4.3] implies that the even/odd factorization holds for any boundary condition whenever SSM holds. Then, from Lemma 4.2 we know that approximate spin/edge factorization holds; the result then follows from applying Lemmas 1.7 and 1.8. $\hfill \Box$

It remains for us to provide the proof of Lemma 4.4, which we do in the next subsection.

4.3 Proof of Lemma 4.4

Before giving the proof of Lemma 4.4, we mention several useful facts about the joint distribution ν . The first key fact is that, for any fixed configuration σ_O of spins on the odd sub-lattice, the conditional probability $\nu(\cdot|\sigma_O)$ is a product measure. That is,

$$\nu(\cdot|\sigma_O) = \bigotimes_{x \in E} \nu_x(\cdot|\sigma_O), \tag{4.8}$$

where, for each $x \in E$, $v_x(\cdot|\sigma_O)$ is the probability measure on $\{1,\ldots,q\} \times \{0,1\}^{\deg(x)}$, where $\deg(x)$ denotes the degree of x, described as follows: pick the spin of site x according to the Potts measure on x conditioned on the spin of its neighbors in σ_O ; then, independently for every edge $xy \in \mathbb{E}$ incident to the vertex x, if $\sigma_x = \sigma_y$ set $A_{xy} = 1$ with probability p and set $A_{xy} = 0$ otherwise; if $\sigma_x \neq \sigma_y$, set $A_{xy} = 0$. (Note that in this section, to simplify notation, we shall use xy to denote the edge $\{x,y\}$, and view the edge configuration A as a vector in $\{0,1\}^{\mathbb{E}}$.)

Consider now the measure $v(\cdot|\sigma_O, A)$ obtained by further conditioning on a valid configuration of all edge variables A. Here A is *valid* if it is compatible with the fixed spins σ_O . This is again a product measure; namely

$$\nu(\cdot|\sigma_O, A) = \bigotimes_{x \in E} \nu_x(\cdot|\sigma_O, A), \tag{4.9}$$

where $v_X(\cdot|\sigma_O, A)$ is the probability measure on $\{1, \ldots, q\}$ that is uniform if x has no incident edges in A, and is concentrated on the unique admissible value given σ_O and A otherwise.

Next, we note that $v(\cdot|\sigma)$ is a product of Bernoulli(p) random variables over all monochromatic edges in σ , while it is concentrated on $A_e=0$ on all remaining edges. Therefore we may write

$$\nu(\cdot|\sigma) = \bigotimes_{x \in E} \nu_x(\cdot|\sigma), \tag{4.10}$$

where $v_X(\cdot|\sigma)$ is the probability measure on $\{0,1\}^{\deg(x)}$ given by the product of Bernoulli(p) variables on all edges xy incident to x such that $\sigma_X = \sigma_y$ and is concentrated on $A_{xy} = 0$ if $\sigma_x \neq \sigma_y$.

We write $\operatorname{Ent}_X(\cdot|\sigma_O)$, $\operatorname{Ent}_X(\cdot|\sigma_O,A)$, $\operatorname{Ent}_X(\cdot|\sigma)$ for the entropies with respect to the distributions $v_X(\cdot|\sigma_O)$, $v_X(\cdot|\sigma_O,A)$, $v_X(\cdot|\sigma)$ respectively. The first observation is that, for every site x, there is a local factorization of entropies in the following sense.

LEMMA 4.7. There exists a constant $\delta_1 > 0$ such that, for all functions $f \ge 0$ and all $x \in E$,

$$\nu_{X} \left[\operatorname{Ent}_{X}(f|\sigma)|\sigma_{O} \right] + \nu_{X} \left[\operatorname{Ent}_{X}(f|\sigma_{O}, A)|\sigma_{O} \right] \ge \delta_{1} \operatorname{Ent}_{X}(f|\sigma_{O}).$$
(4.11)

PROOF. For $x \in V$, let A_x be random variable in $\{0,1\}^{\deg(x)}$ corresponding to the configuration of the edges incident to x in A. If we replace entropy by variance, then (4.11) is a spectral gap inequality for the Markov chain where the variable $(\sigma_x, A_x) \in [q] \times \{0,1\}^{\deg(x)} =: \mathcal{S}$ is updated as follows. At each step, with probability 1/2 the spin σ_x is updated with a sample from $v_x(\cdot|\sigma_O,A)$, and with probability 1/2 the edges A_x incident to x are simultaneously updated with a sample from $v_x(\cdot|\sigma)$. Let $P_x = \frac{Q_x + S_x}{2}$ denote the transition matrix of this Markov chain, where Q_x , S_x are the stochastic matrices corresponding to the spin and edge moves at x, respectively. Let \mathcal{D}_{P_x} , \mathcal{D}_{Q_x} and \mathcal{D}_{S_x} denote the corresponding Dirichlet forms. Observe that, by updating first the edges with an empty configuration and then the spin, two arbitrary initial configurations can be coupled after two steps with probability at least $\frac{1}{4}(1-p)^{-2d}$, and thus for any function $f: \mathcal{S} \mapsto \mathbb{R}_+$

$$\frac{\mathcal{D}_{Q_x}(f,f) + \mathcal{D}_{S_x}(f,f)}{2} = \mathcal{D}_{P_x}(f,f) \ge \delta_0 \operatorname{Var}_x(f|\sigma_O),$$

where $\delta_0 > 0$ is a constant depending only on p and d. Using the standard facts that

$$\begin{split} \mathcal{D}_{Q_X}(f,f) &= \nu_X \left[\mathrm{Var}_X(f|\sigma) |\sigma_O \right], \text{ and } \\ \mathcal{D}_{S_X}(f,f) &= \nu_X \left[\mathrm{Var}_X(f|\sigma_O,A) |\sigma_O \right], \end{split}$$

we arrive at the inequality

$$\frac{\nu_{X}\left[\operatorname{Var}_{X}(f|\sigma)|\sigma_{O}\right] + \nu_{X}\left[\operatorname{Var}_{X}(f|\sigma_{O}, A)|\sigma_{O}\right]}{2} \ge \delta_{0}\operatorname{Var}_{X}(f|\sigma_{O}). \tag{4.12}$$

A well known general relation between entropy and variance (see, e.g., Theorem A.1 and Corollary A.4 in [16]) shows that, for all $f \ge 0$,

$$\operatorname{Ent}_{x}(f|\sigma_{O}) \le C_{1} \operatorname{Var}_{x}(\sqrt{f}|\sigma_{O}),$$
 (4.13)

where $C_1 = C_1(q, p, d)$ is a constant independent of n, since we are considering the conditional measure at the single site x. Thus, applying (4.12) to \sqrt{f} instead of f, we obtain

$$\frac{\delta_{0}}{C_{1}} \operatorname{Ent}_{x}(f|\sigma_{O})$$

$$\leq \frac{\nu_{x} \left[\operatorname{Var}_{x}(\sqrt{f}|\sigma)|\sigma_{O} \right] + \nu_{x} \left[\operatorname{Var}_{x}(\sqrt{f}|\sigma_{O}, A)|\sigma_{O} \right]}{2}. \quad (4.14)$$

The conclusion (4.11) follows by recalling that for any $f \geq 0$ the variance of \sqrt{f} is at most the entropy of f for any underlying probability measure; see, e.g., [30, Lemma 1]. In particular, $\operatorname{Var}_x(\sqrt{f}|\sigma) \leq \operatorname{Ent}_x(f|\sigma)$ and $\operatorname{Var}_x(\sqrt{f}|\sigma_O, A) \leq \operatorname{Ent}_x(f|\sigma_O, A)$.

To prove Lemma 4.4, we need to lift the inequality of Lemma 4.7 to the product measure $\nu(\cdot|\sigma_O) = \bigotimes_{x \in E} \nu_x(\cdot|\sigma_O)$.

PROOF OF LEMMA 4.4. We will prove (4.2); exactly the same argument applies to (4.3). Let x = 1, ..., w denote an arbitrary ordering

of the even sites $x \in E$. Let $A_x \in \{0,1\}^{\deg(x)}$ be the random variable corresponding to the state of the edges incident to x. We write $\xi_x = (\sigma_x, A_x)$ for the pair of variables at x. We first observe that

$$\operatorname{Ent}_{\nu}(f|\sigma_{O}) = \sum_{x=1}^{w} \nu \left[\operatorname{Ent}_{x}(g_{x-1}|\sigma_{O})|\sigma_{O} \right], \tag{4.15}$$

where $g_x = v[f|\sigma_O, \xi_{x+1}, \dots, \xi_w]$, so that $g_0 = f$ and $g_w = f$ $v[f|\sigma_O]$. To prove (4.15) note that since $v(\cdot|\sigma_O) = \bigotimes_{x \in E} v_x(\cdot|\sigma_O)$, one has $v_x[g_{x-1}|\sigma_O] = g_x$. Therefore,

$$\begin{split} \operatorname{Ent}_{\nu}(f|\sigma_{O}) &= \nu \left[g_{0} \log \left(g_{0}/g_{w} \right) |\sigma_{O} \right] \\ &= \sum_{x=1}^{w} \nu \left[g_{0} \log \left(g_{x-1}/g_{x} \right) |\sigma_{O} \right]. \end{split}$$

Since the q_x are (conditional) expectations, we deduce

$$\operatorname{Ent}_{\nu}(f|\sigma_{O}) = \sum_{x=1}^{w} \nu \left[g_{x-1} \log \left(g_{x-1}/g_{x} \right) | \sigma_{O} \right]$$

$$= \sum_{x=1}^{w} \nu \left[\nu_{x} \left[g_{x-1} \log \left(g_{x-1}/g_{x} \right) | \sigma_{O} \right] | \sigma_{O} \right]$$

$$= \sum_{x=1}^{w} \nu \left[\operatorname{Ent}_{x}(g_{x-1}|\sigma_{O}) | \sigma_{O} \right]. \tag{4.16}$$

From (4.16), using Lemma 4.7 we obtain

$$\delta_{1}\operatorname{Ent}_{\nu}(f|\sigma_{O}) \leq \sum_{x=1}^{w} \nu \left[\nu_{x} \left[\operatorname{Ent}_{x}(g_{x-1}|\sigma)|\sigma_{O}\right] |\sigma_{O}\right] + \\ \sum_{x=1}^{w} \nu \left[\nu_{x} \left[\operatorname{Ent}_{x}(g_{x-1}|\sigma_{O}, A)|\sigma_{O}\right] |\sigma_{O}\right] \right] \\ = \sum_{x=1}^{w} \nu \left[\operatorname{Ent}_{x}(g_{x-1}|\sigma)|\sigma_{O}\right] + \\ \sum_{x=1}^{w} \nu \left[\operatorname{Ent}_{x}(g_{x-1}|\sigma_{O}, A)|\sigma_{O}\right]. \tag{4.17}$$

The two sums in (4.17) are "tensorized" versions of ν [Ent_{ν}($f|\sigma$)| σ_O] and ν [Ent $_{\nu}(f|\sigma_{O},A)$], respectively, which are the terms on the right hand side of (4.2). Using similar but somewhat more involved ideas to those used to derive (4.16), we can establish the following.

LEMMA 4.8.

$$\begin{array}{l} (1) \ \sum_{x=1}^{w} \nu \left[\mathrm{Ent}_{x}(g_{x-1}|\sigma)|\sigma_{O} \right] \leq \nu \left[\mathrm{Ent}_{\nu}(f|\sigma)|\sigma_{O} \right]; \\ (2) \ \sum_{x=1}^{w} \nu \left[\mathrm{Ent}_{x}(g_{x-1}|\sigma_{O},A)|\sigma_{O} \right] \leq \nu \left[\mathrm{Ent}_{\nu}(f|\sigma_{O},A)|\sigma_{O} \right]. \end{array}$$

Before providing the proof of this lemma, we finish the proof of Lemma 4.4. Inequality (4.17) together with parts 1 and 2 of Lemma 4.8 show that

$$\delta_{1} \operatorname{Ent}_{\nu}(f|\sigma_{O}) \leq \nu \left[\operatorname{Ent}_{\nu}(f|\sigma)|\sigma_{O} \right] + \nu \left[\operatorname{Ent}_{\nu}(f|\sigma_{O}, A)|\sigma_{O} \right].$$
(4.18)

Taking expectations with respect to ν in (4.18) we arrive at (4.2) and the proof is complete.

We finish the proof of Lemma 4.4 by providing the proof of Lemma 4.8.

PROOF OF LEMMA 4.8. We start with part 2. Let

$$h_X = v [f | \sigma_O, \sigma_{X+1}, \dots, \sigma_w, A],$$

so that $h_0 = f$ and $h_w = v[f|\sigma_O, A]$. Since $v(\cdot|\sigma_O, A)$ is a product measure, $v_x[h_{x-1}|\sigma_O, A] = h_x$. Therefore, reasoning as in (4.15)

$$\operatorname{Ent}_{\nu}(f|\sigma_{O},A) = \sum_{x=1}^{w} \nu \left[\operatorname{Ent}_{x}(h_{x-1}|\sigma_{O},A)|\sigma_{O},A \right]. \tag{4.19}$$

Taking expectations with respect to $v(\cdot|\sigma_O)$ in (4.19) we see that it is sufficient to show that, for all x,

$$\nu \left[\operatorname{Ent}_{X}(g_{X-1}|\sigma_{O}, A) |\sigma_{O} \right] \leq \nu \left[\operatorname{Ent}_{X}(h_{X-1}|\sigma_{O}, A) |\sigma_{O} \right]. \tag{4.20}$$

To prove (4.20), we introduce the measures $\mu_k = \bigotimes_{r=1}^k v_r(\cdot | \sigma_O)$ and $\mu_k^A = \bigotimes_{x=1}^k v_x(\cdot | \sigma_O, A)$. Then we have $g_x = \mu_x[f], h_x =$ $\mu_x^A[f]$, and $g_x = \mu_x[h_x]$. Also, we simplify the notation by writing $v_x(\cdot|\sigma_O,A) =: v_x^A$. Now the product structure implies the commutation relation between expectations

$$v_x^A g_{x-1} = v_x^A \mu_{x-1} h_{x-1} = \mu_{x-1} v_x^A h_{x-1}. \tag{4.21}$$

Therefore,

$$v \left[\operatorname{Ent}_{x}(g_{x-1}|\sigma_{O}, A) |\sigma_{O} \right]$$

$$= v \left[g_{x-1} \log \left(g_{x-1} / v_{x}^{A} g_{x-1} \right) |\sigma_{O} \right]$$

$$= v \left[\mu_{x-1} h_{x-1} \log \left(\mu_{x-1} h_{x-1} / \mu_{x-1} v_{x}^{A} h_{x-1} \right) |\sigma_{O} \right]$$

$$= v \left[h_{x-1} \log \left(\mu_{x-1} h_{x-1} / \mu_{x-1} v_{x}^{A} h_{x-1} \right) |\sigma_{O} \right]$$

$$= v \left[v_{x}^{A} \left(h_{x-1} \log \left(g_{x-1} / v_{x}^{A} g_{x-1} \right) \right) |\sigma_{O} \right] .$$

$$(4.22)$$

From the variational principle (2.6) it follows that

$$v_x^A \left[h_{x-1} \log \left(g_{x-1} / v_x^A [g_{x-1}] \right) \right] \le \operatorname{Ent}_x(h_{x-1} | \sigma_O, A),$$
 (4.24)

which combined with (4.23) proves (4.20). This completes the proof of part 2.

We use a similar argument for part 1. Let

$$\psi_x = v(f|\sigma, A_{x+1}, \dots, A_w),$$

so that $\psi_0 = f$ and $\psi_w = v(f|\sigma)$. Notice that $v_x[\psi_{x-1}|\sigma] = \psi_x$. Therefore, as in (4.15),

$$\operatorname{Ent}_{\nu}(f|\sigma) = \sum_{x=1}^{w} \nu \left[\operatorname{Ent}_{x}(\psi_{x-1}|\sigma) |\sigma \right].$$

Taking expectations with respect to $\nu(\cdot|\sigma_O)$ we see that it is sufficient to show that, for all $x \in E$,

$$\nu \left[\operatorname{Ent}_{x}(g_{x-1}|\sigma)|\sigma_{O} \right] \le \nu \left[\operatorname{Ent}_{x}(\psi_{x-1}|\sigma)|\sigma_{O} \right]. \tag{4.25}$$

Introducing the measures $\mu_k = \bigotimes_{x=1}^k v_x(\cdot | \sigma_O), \ \mu_k^{\sigma} = \bigotimes_{x=1}^k v_x(\cdot | \sigma),$ and $v_x^{\sigma} = v_x(\cdot|\sigma)$, we have $g_x = \mu_x[f]$, $\psi_x = \mu_x^{\sigma}[f]$, and $g_x = \mu_x[f]$ $\mu_x[\psi_x]$. As in (4.21), we have the commutation relation

$$v_{x}^{\sigma}q_{x-1} = v_{x}^{\sigma}\mu_{x-1}\psi_{x-1} = \mu_{x-1}v_{x}^{\sigma}\psi_{x-1}.$$

Therefore, as in (4.23)-(4.24) we obtain

$$\begin{split} \nu[\text{Ent}_{X}(g_{X-1}|\sigma)|\sigma_{O}] \\ &= \nu \left[g_{X-1} \log \left(g_{X-1} / \nu_{X}^{\sigma} g_{X-1} \right) | \sigma_{O} \right] \\ &= \nu \left[\mu_{X-1} \psi_{X-1} \log \left(\mu_{X-1} \psi_{X-1} / \mu_{X-1} \nu_{X}^{\sigma} \psi_{X-1} \right) | \sigma_{O} \right] \\ &= \nu \left[\psi_{X-1} \log \left(\mu_{X-1} \psi_{X-1} / \mu_{X-1} \nu_{X}^{\sigma} \psi_{X-1} \right) | \sigma_{O} \right] \\ &= \nu \left[\nu_{X}^{\sigma} \left(\psi_{X-1} \log \left(g_{X-1} / \nu_{X}^{\sigma} g_{X-1} \right) \right) | \sigma_{O} \right] \\ &\leq \nu \left[\text{Ent}_{X}(\psi_{X-1}|\sigma) | \sigma_{O} \right]. \end{split}$$

This proves (4.25) and completes the proof of part 1.

5 A LOWER BOUND FOR THE SW DYNAMICS

In this section we establish an asymptotically tight lower bound for the mixing time of SW dynamics whenever SSM holds; this result implies the lower bound in Theorem 1.1 from the introduction.

Theorem 5.1. In an n-vertex cube of \mathbb{Z}^d , for all integer $q \geq 2$ and all $\beta > 0$, SSM implies that for all boundary conditions $T_{\text{mix}}(SW) = \Omega(\log n)$.

The main new ingredient in the proof of this result is a bound on the speed of propagation of disagreements under a coupling of the steps of the SW dynamics provided SSM holds. With this new tool, we are able to adapt the lower bound framework of Hayes and Sinclair [26] for the Glauber dynamics to the SW setting. We also use a recently established fact about concentration properties of the Potts measure due to [17].

SW coupling. Consider two copies of the SW dynamics on the graph $G = (V, \mathbb{E})$, where V is an n-vertex cube of \mathbb{Z}^d . Let X_t and Y_t be the configurations of these copies at time $t \ge 0$. We can couple the steps of the SW dynamics as follows:

- (1) Draw $|\mathbb{E}|$ independent, uniform random numbers from [0,1], one for each edge. Let $r_e(t) \in [0,1]$ denote the random number corresponding to the edge $e \in \mathbb{E}$.
- (2) Draw |V| independent, uniform random numbers from the set $\{1,...,q\}$, one for each vertex. Let $s_v(t) \in \{1,...,q\}$ denote the random number for $v \in V$.
- (3) Let $A_X = \{e \in M(X_t) : r_e(t) \le p\}$ and $A_Y = \{e \in M(Y_t) : r_e(t) \le p\}$, where recall that $M(X_t)$ and $M(Y_t)$ denote the set of monochromatic edges in X_t and Y_t , respectively
- (4) For each connected component C of (V, A_X) or (V, A_Y) , we let $s_C = s_v(t)$, where v is the vertex in C with the smallest coordinate sum. (If two or more vertices in C have the same coordinate sum, we break ties "lexicographically" using the coordinates.) Then, every vertex of C is assigned the spin s_C .

The key property of the SW coupling is that, after assigning the edges, two identical connected components in A_X and A_Y will be assigned the same spin (namely, the spin s_v of their common vertex v with smallest coordinate sum). We show that, under SSM, the SW coupling propagates disagreements slowly for a suitable starting condition.

To describe our starting condition we introduce the notion of *L-shattered* configurations.

Definition 5.2. Consider the graph $G=(V,\mathbb{E})$, where V is an n-vertex cube of \mathbb{Z}^d . For a configuration σ on V, let $A_\sigma\subseteq M(\sigma)$ be the configuration that results from keeping each monochromatic edge in $M(\sigma)$ independently with probability $p=1-\exp(-\beta)$. We say that σ is L-shattered in V if, with probability at least $1-|V|\exp(-\gamma L)$ where $\gamma>0$ is a fixed constant we choose later, for every $v\in |V|$ at distance at least 2L from the boundary of |V|, the connected component of v in A_σ does not reach the boundary of the cube $\Lambda_v(L)$ centered at v of side length L.

Note that the above defined notion involves a probability that decays exponentially with L, so the dimension of the cube V will not be as significant as long as $\log n \ll L \ll n$. The following lemma establishes a concentration of the probability mass on shattered configurations under SSM (for the monochromatic "all 1" boundary condition).

Lemma 5.3. Let \mathfrak{S} be the set of L-shattered configurations of the n-vertex cube $G = (V, \mathbb{E})$ of \mathbb{Z}^d . There exists a constant c > 0 such that for all integers $q \geq 2$ and $L \geq 1$, SSM implies that $\mu^1(\mathfrak{S}) \geq 1 - \exp(-cL)$.

The proof of this lemma, which follows straightforwardly from the results in [17], is provided in the full version [4]. We can now describe our starting condition for the SW dynamics.

A starting condition. We consider a regular pattern of non-overlapping d-dimensional cubes of side length $\ell = (\log n)^3$ with a fixed minimal distance between cubes. Formally, consider the cubes of side length ℓ centered at $(\ell+3)\cdot\vec{h}$ where $\vec{h}\in\mathbb{Z}^d$. These cubes have volume ℓ^d and are at distance 4 from each other. We let $B_1, B_2, \ldots B_N \subset V$ be the collection of those cubes that are contained in V and at distance at least 4 from the boundary ∂V ; then, $N = \Theta(n/\ell^d)$.

Let $B = \bigcup_{i=1}^N B_i$, $\partial B = \bigcup_{i=1}^N \partial B_i$ and let e_i be an edge at the center of B_i . For definiteness, we may assume that ℓ is odd so that there is a unique vertex v_i at the center of each B_i ; we take $e_i = \{v_i, u_i\}$ where $u_i = v_i + (1, 0, \dots, 0) \in \mathbb{Z}^d$. Let \mathcal{A}_i be the set of configurations on B_i in which the spins at the endpoints of e_i are the same, and let S_i be the set of L-shattered configurations in each B_i . (Later we will set $L = C(\log n)$ with C > 0 a large constant.)

We consider two variants of the SW dynamics, $\{X_t\}$ and $\{Y_t\}$, with the same initial condition $X_0 = Y_0$. The chain $\{X_t\}$ is an instance of the standard SW dynamics on (V, \mathbb{E}) ; for the initial state X_0 of $\{X_t\}$ we set the spins of all the vertices in $U = (V \setminus B) \cup \partial B$ to 1. The configuration in each cube B_i is sampled (independently) proportional to $\mu^1_{B_i}$ on $S_i \cap \mathcal{A}_i$, where $\mu^1_{B_i}$ denotes the Potts measure on B_i with the "all 1" monochromatic boundary condition.

The other instance we consider, $\{Y_t\}$, only updates the spins of the vertices in $B \setminus \partial B$. That is, after adding all the monochromatic edges independently with probability $p = 1 - \exp(-\beta)$, only the connected components fully contained in B update their spins. (Note that if a component touches the boundary of B, then it is not updated since the boundary is frozen to the spin 1 by the boundary condition.) We set $Y_0 = X_0$ and couple the evolution of Y_t and X_t using the SW coupling defined earlier. We can view $\{Y_t\}$ as a dynamics on the configurations on B whose stationary measure is

 $\mu_B^1 = \bigotimes_{i=1}^N \mu_{B_i}^1$. We also observe that a step of $\{Y_t\}$ is equivalent to performing one step of the SW dynamics in each B_i independently.

Note that $X_0 = Y_0$, and any disagreements between X_t , Y_t at later times t can arise only from the fact that Y_t does not update the spins outside B: i.e., disagreements must propagate into the B_i from their boundaries. The following result, whose proof we defer until after the proof of Theorem 5.1, provides a bound on the speed of propagation of these disagreements under the SW coupling with the specified initial condition. In particular it says that, for $t = \Omega(\log n)$ steps, X_t , Y_t agree w.h.p. on the spins at the center of every cube B_i .

Theorem 5.4. Let $C=\bigcup_{i=1}^N e_i$ and set $L=C(\log n)$. For any constant A>0, for a sufficiently large constant C>0 SSM implies that

$$\Pr \left[\forall t \le A \log n : X_t(C) = Y_t(C) \right] = 1 - o(1).$$

A key ingredient in the proof of Theorem 5.4 (and also of Theorem 5.1) is the following discrete time version of the completely monotone decreasing (CMD) property of reversible Markov chains from [26]; the proof of this lemma is provided in the full version [4].

Lemma 5.5. Let $\{X_t\}$ denote a discrete time Markov chain with finite state space Ω , reversible with respect to π and with a positive semidefinite transition matrix. Let $B \subset \Omega$ denote an event. If X_0 is sampled proportional to π on B, then $\Pr(X_t \in B) \geq \pi(B)$ for all $t \geq 0$, and for all $t \geq 1$

$$\Pr(X_t \in B) \ge \pi(B) + (1 - \pi(B))^{-t+1} (\Pr(X_1 \in B) - \pi(B))^t.$$

We now proceed with the proof of Theorem 5.1.

PROOF OF THEOREM 5.1. Our goal is to show that at some time $T = \Theta(\log n)$

$$||X_T - \mu||_{\text{TV}} > \frac{1}{2},$$

where with a slight abuse of notation we use X_T for the distribution of the chain $\{X_t\}$ at time T. This clearly implies that the mixing time of the SW dynamics is $\Omega(\log n)$.

Let $C = \bigcup e_i$ and let $e_i = \{a_i, b_i\}$. Let $\hat{\mu}_C$ and $\hat{\mu}_C^1$ be the marginals of μ and μ_R^1 , respectively, on C. Then,

$$\begin{split} & \|X_{T} - \mu\|_{\text{TV}} \ge \|X_{T}(C) - \hat{\mu}_{C}\|_{\text{TV}} \\ & \ge \|Y_{T}(C) - \hat{\mu}_{C}\|_{\text{TV}} - \|X_{T}(C) - Y_{T}(C)\|_{\text{TV}} \\ & \ge \|Y_{T}(C) - \hat{\mu}_{C}^{1}\|_{\text{TV}} - \|\hat{\mu}_{C}^{1} - \hat{\mu}_{C}\|_{\text{TV}} - \|X_{T}(C) - Y_{T}(C)\|_{\text{TV}}. \end{split}$$
 (5.1)

We bound each term of (5.1) independently. We note first that by Theorem $5.4\,$

$$||X_T(C) - Y_T(C)||_{TV} \le \Pr(X_T(C) \ne Y_T(C)) = o(1).$$

We proceed to bound the term $\|\hat{\mu}_C^1 - \hat{\mu}_C\|_{\mathrm{TV}}$ in (5.1), for which we use SSM. Let $\Omega(A)$ be the set of all possible configurations on the set $A \subseteq V$. For a configuration ψ on U, let $\hat{\mu}_C^{\psi}$ denote the marginal of μ_B^{ψ} on C. Let $\hat{\mu}_{e_i}^1$, $\hat{\mu}_{e_i}^{\psi}$ be the marginals of $\hat{\mu}_{B_i}^1$, $\hat{\mu}_{B_i}^{\psi}$ on e_i , respectively. Then

$$\begin{split} \left\| \hat{\mu}_C^1 - \hat{\mu}_C \right\|_{\text{TV}} &\leq \sum_{\psi \in \Omega(U)} \mu(\psi) \| \hat{\mu}_C^1 - \hat{\mu}_C^\psi \|_{\text{TV}} \\ &\leq \sum_{\psi \in \Omega(U)} \sum_{i=1}^N \mu(\psi) \| \hat{\mu}_{e_i}^1 - \hat{\mu}_{e_i}^\psi \|_{\text{TV}} \leq \frac{N}{e^{\kappa \ell}} = o(1), \end{split}$$

where the second inequality follows from the fact that μ_B^1 and μ_B^{ψ} are product measures over the B_i 's, and the last one follows from the SSM property for a suitable constant $\kappa > 0$.

It remains for us to provide a lower bound for $\|Y_T(C) - \hat{\mu}_C^1\|_{_{\mathrm{TV}}}$. For this, we introduce an auxiliary copy of the chain $\{Y_t\}$, denoted $\{Z_t\}$, which is coupled with $\{Y_t\}$ but with a slightly different starting condition. Namely, Z_0 is sampled proportional to $\mu_{B_i}^1$ on the set \mathcal{A}_i , independently for each B_i . (Recall that $Y_0 = X_0$ is sampled proportional to $\mu_{B_i}^1$ on $S_i \cap \mathcal{A}_i$ instead.) Then,

$$\|Y_T(C) - \hat{\mu}_C^1\|_{_{\mathrm{TV}}} \ge \|Z_T(C) - \hat{\mu}_C^1\|_{_{\mathrm{TV}}} - \|Y_T(C) - Z_T(C)\|_{_{\mathrm{TV}}}. \tag{5.2}$$

We first provide an upper bound for the second term in (5.2). Plainly,

$$||Y_T(C) - Z_T(C)||_{TV} \le ||Y_T - Z_T||_{TV} \le Pr[Y_0 \ne Z_0].$$

Let μ_0^Y , μ_0^Z be the initial distribution for $\{Y_t\}$ and $\{Z_t\}$, respectively, and let $S = \otimes S_i$ and $\mathcal{A} = \otimes \mathcal{A}_i$. For $\sigma \in S \cap \mathcal{A}$, we have $\mu_0^Y(\sigma) = \mu_B^1(\sigma)/\mu_B^1(S \cap \mathcal{A})$, and for $\sigma \in \mathcal{A}$, $\mu_0^Z(\sigma) = \mu_B^1(\sigma)/\mu_B^1(\mathcal{A})$. Therefore, if the configurations Y_0 and Z_0 are sampled from the optimal coupling between μ_0^Y , μ_0^Z and the steps of $\{Y_t\}$, $\{Z_t\}$ are then coupled with the SW coupling, we have

$$\begin{split} \|Y_T(C) - Z_T(C)\|_{\text{TV}} &\leq \|\mu_0^Y - \mu_0^Z\|_{\text{TV}} \leq \sum_{i=1}^N \|\mu_0^{Y,i} - \mu_0^{Z,i}\|_{\text{TV}} \\ &= N\|\mu_0^{Y,1} - \mu_0^{Z,1}\|_{\text{TV}}, \end{split}$$

where $\mu_0^{Y,i}, \mu_0^{Z,i}$ are the initial distributions of Y_0, Z_0 on B_i . Then,

$$\|\mu_0^{Y,1} - \mu_0^{Z,1}\|_{\scriptscriptstyle \mathrm{TV}} = \frac{\mu_{B_1}^1(\mathcal{A}_1 \setminus \mathcal{S}_1)}{\mu_{B_1}^1(\mathcal{A}_1)} \leq \frac{\mu_{B_1}^1(\mathcal{S}_1^c)}{\mu_{B_1}^1(\mathcal{A}_1)} = O\left(e^{-cL}\right),$$

where the last inequality follows from Lemma 5.3 and the fact that $\mu^1_{B_1}(\mathcal{A}_1)=\Omega(1)$. In summary, since $L=C(\log n)$ and C can be taken large enough, we have proved

$$||Y_T(C) - Z_T(C)||_{TV} = o(1).$$

It remains for us to find a lower bound for $\|Z_T(C) - \hat{\mu}_C^1\|_{\text{TV}}$ in (5.2) for a suitable T. For a configuration σ on B, let $f(\sigma)$ denote the number of edges $e_i \in C$ that are monochromatic in σ . For any $a \geq 0$ we have

$$\|Z_T(C) - \hat{\mu}_C^1\|_{\text{TV}} \ge \Pr[f(Z_T) \ge a] - \Pr_{\sigma \sim \mu_n^1}[f(\sigma) \ge a]. \quad (5.3)$$

We will show that, for a suitable T and any i = 1, ..., N,

$$\Pr[Z_T(B_i) \in \mathcal{A}_i] \ge \mu_{B_i}^1(\mathcal{A}_i) + \frac{1}{N^{1/4}}.$$
 (5.4)

Assuming this is the case, then setting $\mathcal{W} = \sum_{i=1}^N \mu_{B_i}^1(\mathcal{A}_i)$ we obtain by Hoeffding's inequality

$$\Pr\left[f(Z_T) \ge \mathcal{W} + N^{3/4} - \sqrt{N\log N}\right] \ge 1 - \frac{1}{N^2}$$

and

$$\Pr_{\sigma \sim \mu_B^1} \left[f(\sigma) \ge \mathcal{W} + \sqrt{N \log N} \right] \le \frac{1}{N^2},$$

which yields from (5.3) that $\|Z_T(C) - \hat{\mu}_C^1\|_{\text{TV}} \ge 1 - 2/N^2$ by taking, e.g., $a = W + \sqrt{N \log N}$.

To establish (5.4), note that by Lemma 5.5

$$\Pr(Z_T(B_i) \in \mathcal{A}_i) \ge \mu_{B_i}^1(\mathcal{A}_i) + (1 - \mu_{B_i}^1(\mathcal{A}_i))^{-T+1} \mathcal{Z}^T,$$
 (5.5)

where $\mathcal{Z} := \Pr(Z_1(B_i) \in \mathcal{A}_i) - \mu_{B_i}^1(\mathcal{A}_i)$. We remark that $\{Z_t\}$ has positive semidefinite transition matrix; this follows from the fact $\{Z_t\}$ is a product of SW dynamics in each B_i , and the SW dynamics has positive semidefinite transition matrix [5].

Let $P_{\text{SW}}^{(i)}$ denote the transition matrix of the SW dynamics on B_i . Then

$$\Pr(Z_{1}(B_{i}) \in \mathcal{A}_{i}) = \sum_{\sigma \in \mathcal{A}_{i}} \frac{\mu_{B_{i}}^{1}(\sigma)}{\mu_{B_{i}}^{1}(\mathcal{A}_{i})} P_{\text{SW}}^{(i)}(\sigma, \mathcal{A}_{i})$$

$$= \sum_{\sigma \in \mathcal{A}_{i}} \frac{\mu_{B_{i}}^{1}(\sigma)}{\mu_{B_{i}}^{1}(\mathcal{A}_{i})} \left(\theta(\sigma) + \frac{1 - \theta(\sigma)}{q}\right)$$

$$= \frac{1}{q} + \frac{q - 1}{q\mu_{B_{i}}^{1}(\mathcal{A}_{i})} \sum_{\sigma \in \mathcal{A}_{i}} \mu_{B_{i}}^{1}(\sigma)\theta(\sigma), \quad (5.6)$$

where $\theta(\sigma)$ denotes the probability that, after the edge percolation phase of the SW step, the end points of the edge e_i are connected in the edge configuration. Similarly,

$$\begin{split} \mu_{B_i}^1(\mathcal{A}_i) &= \sum_{\sigma \in \Omega(B_i)} \mu_{B_i}^1(\sigma) P_{\mathrm{sw}}^{(i)}(\sigma, \mathcal{A}_i) \\ &= \sum_{\sigma \in \Omega(B_i) \backslash \mathcal{A}_i} \mu_{B_i}^1(\sigma) P_{\mathrm{sw}}^{(i)}(\sigma, \mathcal{A}_i) + \sum_{\sigma \in \mathcal{A}_i} \mu_{B_i}^1(\sigma) P_{\mathrm{sw}}^{(i)}(\sigma, \mathcal{A}_i) \\ &= \sum_{\sigma \in \Omega(B_i) \backslash \mathcal{A}_i} \frac{\mu_{B_i}^1(\sigma)}{q} + \sum_{\sigma \in \mathcal{A}_i} \mu_{B_i}^1(\sigma) \left(\theta(\sigma) + \frac{1 - \theta(\sigma)}{q}\right) \\ &= \frac{1}{q} + \frac{q - 1}{q} \sum_{\sigma \in \mathcal{A}_i} \mu_{B_i}^1(\sigma) \theta(\sigma). \end{split}$$

Combining with (5.6) we get

$$\begin{split} \mathcal{Z} &= \frac{q-1}{q} \left(\frac{1}{\mu_{B_i}^1(\mathcal{A}_i)} - 1 \right) \sum_{\sigma \in \mathcal{A}_i} \mu_{B_i}^1(\sigma) \theta(\sigma) \\ &\geq \frac{q-1}{q} \left(\frac{1}{\mu_{B_i}^1(\mathcal{A}_i)} - 1 \right) p \cdot \mu_{B_i}^1(\mathcal{A}_i) = \frac{q-1}{q} \left(1 - \mu_{B_i}^1(\mathcal{A}_i) \right) p, \end{split}$$

where in the last inequality we use the fact that $\theta(\sigma) \ge p$ when $\sigma \in \mathcal{A}_i$; recall that $p = 1 - e^{-\beta}$.

Plugging this bound into (5.5), we obtain

$$\begin{split} \Pr(Z_T(B_i) \in \mathcal{A}_i) &= \mu_{B_i}^1(\mathcal{A}_i) + (1 - \mu_{B_i}^1(\mathcal{A}_i)) \left(\frac{(q-1)p}{q}\right)^T \\ &\geq \mu_{B_i}^1(\mathcal{A}_i) + \frac{1}{N^{1/4}}, \end{split}$$

where the last inequality holds for $T = \xi \log n$ for a suitable constant $\xi > 0$ since $\mu_{B_i}^1(\mathcal{A}_i) = \Omega(1)$.

We provide next the proof of Theorem 5.4, our bound on the speed of disagreement propagation under the SW coupling.

Proof of Theorem 5.4. We will show inductively that with high probability disagreements propagate a distance of at most L in each step. Let $\Lambda_i(k) \subseteq B_i$ be the cube of side length $k < \ell$ centered at v_i ; recall that $e_i = \{v_i, u_i\}$ where v_i is the center of B_i . Let $\Lambda(k) = \bigcup_{i=1}^N \Lambda_i(k)$. Note that at time 0, X_0 and Y_0 agree on $B = \Lambda(\ell)$.

Let us assume that X_t and Y_t agree on $\Lambda(k)$ for some $k \leq \ell - 2L$. Suppose Y_t is L-shattered in each B_i ; i.e., $Y_t(B_i) \in S_i$ for $i = 1, \ldots, N$. If E(k) is the set of edges with both endpoints in $\Lambda(k)$, after adding the monochromatic edges of E(k) in X_t and Y_t coupled with the SW coupling, the joint edge/spin configuration on $(\Lambda(k), E(k))$ will be the same in both copies. However, when assigning the new spins, the connected components are not necessarily the same since there can be external connections; i.e., monochromatic paths in $V \setminus \Lambda(k)$. This may create disagreements between the two chains on $\Lambda(k)$ but only in the components touching the boundary of $\Lambda(k)$. Since we are assuming that Y_t is L-shattered in each B_i , then with probability $1 - N|B_i| \cdot \exp(-\gamma L)$, the disagreements cannot propagate to $\Lambda(k-2(L+1))$. Consequently, the spin configurations of X_{t+1} and Y_{t+1} on $\Lambda(k-2(L+1))$ are the same.

Proceeding inductively, and assuming that Y_t is L-shattered in each B_i for all t = 0, ..., T, we deduce from a union bound that X_T and Y_T agree on $\Lambda(\ell - 2L - 2T(L + 1))$ with probability at least $1 - TN|B_i| \exp(-\gamma L)$, provided $\ell > 2T(L + 1) + 2L$. Therefore, $X_t(C) = Y_t(C)$ for all $t \le T$ since $C \subseteq \Lambda(\ell - 2L - 2t(L + 1))$.

It remains for us to show that Y_t is L-shattered in each B_i for all $t=0,\ldots,T$ with probability at least 1-o(1). The configuration of Y_0 on B_i is sampled proportional to $\mu^1_{B_i}$ on $\mathcal{S}_i\cap\mathcal{A}_i$. For $\sigma\in\mathcal{S}_i\cap\mathcal{A}_i$, let $\pi_i(\sigma)=\mu^1_{B_i}(\sigma)/\mu^1_{B_i}(\mathcal{S}_i\cap\mathcal{A}_i)$ and for $\sigma\in\mathcal{S}_i$, let $\hat{\pi}_i(\sigma)=\mu^1_{B_i}(\sigma)/\mu^1_{B_i}(\mathcal{S}_i)$. We have

$$\begin{split} \Pr_{Y_0(B_i) \sim \hat{\pi}_i}(Y_t(B_i) \in \mathcal{S}_i) &= \\ \Pr_{Y_0(B_i) \sim \hat{\pi}_i}(Y_t(B_i) \in \mathcal{S}_i \mid Y_0(B_i) \in \mathcal{A}_i)\alpha + \\ \Pr_{Y_0(B_i) \sim \hat{\pi}_i}(Y_t(B_i) \in \mathcal{S}_i \mid Y_0(B_i) \notin \mathcal{A}_i)(1 - \alpha), \end{split}$$

where $\alpha = \Pr_{Y_0(B_i) \sim \hat{\pi}_i}(Y_0(B_i) \in \mathcal{A}_i)$, and so

$$\Pr_{Y_0(B_i) \sim \pi_i}(Y_t(B_i) \in \mathcal{S}_i) = \Pr_{Y_0(B_i) \sim \hat{\pi}_i}(Y_t(B_i) \in \mathcal{S}_i \mid Y_0(B_i) \in \mathcal{A}_i)$$

$$\geq 1 - \frac{1 - \Pr_{Y_0(B_i) \sim \hat{\pi}_i}(Y_t(B_i) \in \mathcal{S}_i)}{\alpha}$$
(5.7)

By Lemmas 5.5 and 5.3,

$$\Pr_{Y_0(B_i) \sim \hat{\pi}_i}(Y_t(B_i) \in \mathcal{S}_i) \ge \mu_{B_i}^1(\mathcal{S}_i) \ge 1 - \frac{1}{e^{cL}}.$$

Moreover, $\Pr_{Y_0(B_i) \sim \hat{\pi}_i}(Y_0(B_i) \in \mathcal{A}_i) = \alpha = \alpha(\beta, q, d) = \Omega(1)$, and so we obtain from (5.7)

$$\Pr_{Y_0(B_i) \sim \pi_i}(Y_t(B_i) \in \mathcal{S}_i) = 1 - O\left(\frac{1}{e^{cL}}\right).$$

Setting $S = \bigotimes_{i=1}^{N} S_i$, a union bound over the B_i 's implies

$$\Pr(Y_t \in \mathcal{S}) = 1 - O\left(\frac{N}{e^{cL}}\right).$$

It follows from another union bound over the steps that $\Pr(\forall t \leq T: Y_t \in \mathcal{S}) \geq 1 - O\left(\frac{TN}{e^{cL}}\right)$. Setting $T = A(\log n)$ (which satisfies $\ell > 2T(L+1) + 2L$ as required), recalling that $N = \Theta(n/\ell^d)$, and taking C sufficiently large, we obtain that $\Pr(\forall t \leq T: Y_t \in \mathcal{S}) \geq 1 - o(1)$, and hence

$$\Pr[\forall t \le A \log n : X_t(C) = Y_t(C)] = 1 - o(1),$$

as claimed. \Box

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