

Revealing Continuous Brain Dynamical Organization with Multimodal Graph Transformer

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Abstract. Brain large-scale dynamics is constrained by the heterogeneity of intrinsic anatomical substrate. Little is known how the spatio-temporal dynamics adapt for the heterogeneous structural connectivity (SC). Modern neuroimaging modalities make it possible to study the intrinsic brain activity at the scale of seconds to minutes. Diffusion magnetic resonance imaging (dMRI) and functional MRI reveals the large-scale SC across different brain regions. Electrophysiological methods (i.e. MEG/EEG) provide direct measures of neural activity and exhibits complex neurobiological temporal dynamics which could not be solved by fMRI. However, most of existing multimodal analytical methods collapse the brain measurements either in space or time domain and fail to capture the spatio-temporal circuit dynamics. In this paper, we propose a novel spatio-temporal graph Transformer model to integrate the structural and functional connectivity in both spatial and temporal domain. The proposed method learns the heterogeneous node and graph representation via contrastive learning and multi-head attention based graph Transformer using multimodal brain data (i.e. fMRI, MRI, MEG and behavior performance). The proposed contrastive graph Transformer representation model incorporates the heterogeneity map constrained by T1-to-T2-weighted (T1w/T2w) to improve the model fit to structure-function interactions. The experimental results with multimodal resting state brain measurements demonstrate the proposed method could highlight the local properties of large-scale brain spatio-temporal dynamics and capture the dependence strength between functional connectivity and behaviors. In summary, the proposed method enables the complex brain dynamics explanation for different modal variants.

Keywords: Multimodal graph transformer · Graph contrastive representation · Neural graph differential equations.

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1 Introduction

Understanding how our brain dynamically adapts for mind and behaviors helps to extract fine-grained information for typical and atypical brain functioning. But how the microcircuit heterogeneity shapes the structure-function interactions remains an open question in systems neuroscience. Magnetic resonance imaging (MRI) makes it possible to infer the large-scale structural and functional connectivity and characterize the anatomical and functional patterns in human cortex. Electrophysiological methods reveal the dynamical circuit mechanisms at the structural and functional level with higher temporal resolution. Different neuroimaging modalities such as fMRI, dMRI and MEG enable us to estimate both static and functional connectivity during resting state and task experimental paradigms.

Existing studies of large-scale brain dynamics relate the structural and functional connectivity with dynamical circuit mechanisms. The biophysically based dynamical models explore the time-variant function connectivity with excitatory and inhibitory interactions which is interconnected through structural connections [20, 6, 22]. Microcircuit specialization could be summarized using graph model [3], showing insights into inter-individual brain architecture, development and dysfunction in disease or disorder states. Recently, the graph harmonic analysis based on Laplacian embedding [4] and spectral clustering [19] is introduced to inform the cortical architectural variation. Basically, the previous methods define the nodes of the graph with the harmonic components to quantify the density of anatomical fibers. However, the inter-areal heterogeneity of human cortex has not been widely studied. The next challenging is to decompose the spatio-temporal brain dynamics with multimodal data[21]. Rahim et al. [15] improve the Alzheimer’s disease classification performance with fMRI and PET modalities. The stacking method of multimodal neuroimaging data is explored in age prediction task [10]. Representational similarity analysis (RSA) [9] based methods use the common similarity space to associate multivariate modalities. Subsequent research uses Gaussian process to allow complex linking functions [2]. In order to associate the higher temporal resolution of Electrophysiological measurements at millisecond with the higher spatial resolution of MRI and fMRI at millimeter, we introduce the contrastive learning with the Graph Transformer model to learn the heterogeneous graph representation.

Contrastive methods measure the distribution loss with the discriminative structure and achieve the state-of-the-art performance in graph classification. Contrastive multiview coding (CMC) [18], augmented multi-scale DIM (AMDIM) [1] and SimCLR [5] take advantages of multiview mutual information maximization with data augmentation to learn better representations. The graph-level representation is further explored with the extension of the mutual information principle in [17]. Recently, the Graph Transformer based method [16] is proposed to explore the nodes relationship in node embedding learning. However, it is challenging to accurately represent the entire given graph.

To address these issues, we develop a novel Graph Transformer based framework for associating the heterogeneity of local circuit properties and revealing

the dependency of functional connectivity on anatomical structure. The proposed method consists of three parts, the Dynamical Neural Graph Encoder, the graph Transformer pooling with multi-head attention, and the contrastive representation learning model. The proposed method has the following advantages:

- The proposed method provides insights into the brain spatio-temporal dynamical organization related to mind and behavior performance. Existing graph pooling methods may yield similar graph representation for two different graphs. To obtain accurate graph representation, the novel Graph Transformer use multi-head attention to acquire the global graph structure given multimodal inputs. Moreover, we use the contrastive learning model to associate structural and functional details of dMRI, fMRI and MEG.
- The proposed method makes it possible to incorporate the areal heterogeneity map with functional signals using multimodal data from the human connectome project (HCP).
- The proposed method is evaluated with the meta-analysis to explore the behavioral relevance of different brain regions and characterize the brain dynamical organization into low level functions region (i.e. sensory) and the complex function regions (i.e. memory).

2 Methods

To explore the coupling strength of structural and functional connectivity, the heterogeneous Graph Transformer with contrastive learning is trained based on the multimodal brain measurements (i.e. MRI, fMRI and MEG). We use a graph $\mathcal{G}_i = (\mathcal{V}, \mathcal{E}_i)$ to represent the heterogeneous graph representation, with the node type $\mathcal{V} = [v_{t,i} | t = 1, \dots, T; i = 1, \dots, N]$ with N brain ROIs and T time points. The connection of different brain ROIs in spatial and temporal domain is denoted by the edge mapping \mathcal{E} . Given two types of multimodal graph representation \mathcal{G}_A and \mathcal{G}_B with different time points T_A and T_B and their multivariate value $X_A = [x_{t_1}^A, x_{t_2}^A, \dots, x_{t_A}^A]$ and $X_B = [x_{t_1}^B, x_{t_2}^B, \dots, x_{t_B}^B]$. The dynamical neural graph encoder is used to represent the spatio-temporal dynamics within each modality. $Y_A = [y_{t_1}^A, y_{t_2}^A, \dots, y_{T_A}^A]$ and $Y_B = [y_{t_1}^B, y_{t_2}^B, \dots, y_{T_B}^B]$. The adjacency matrices for each view are represented as A_A and A_B . We use H^A and H^B to represent the learned node representation within each modality. Then we use the Graph Transformer pooling layer together with the multi-head attention model to stack the entire node features. The overall framework is illustrated in Fig. 1.

2.1 Dynamical Neural Graph Encoder for Single Modal Data

The dynamical brain network with N neurons could be modeled as

$$\dot{z}(t) = f(z, l, t), \quad (1)$$

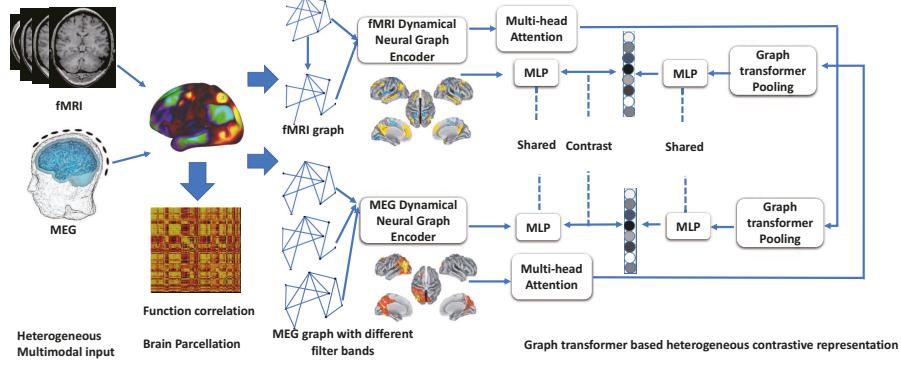


Fig. 1: Schematic illustration of the graph transformer representation learning

where $z(t) = [z_1(t), z_2(t), \dots, z_N(t)]^T$ represents the internal states of N neuron nodes at time t . $f(\cdot)$ denotes the nonlinear dynamical function of each node. And $l(t) = [l_1(t), l_2(t), \dots, l_S(t)]^T$ represents the external stimuli for S neurons.

To represent the dynamics of each single modality, we define a continuous neural-graph differential equation as follows,

$$\dot{Z}(t) = f_{G_{t_k}}(t, Z_t, \theta_t); Z_t^+ = \mathcal{L}_{G_{t_k}}^j(Z_t, X_t); Y_t = \mathcal{L}_{G_{t_k}}^y(Z_t), \quad (2)$$

where f_G , \mathcal{L}_G^j and \mathcal{L}_G^y are graph encoder networks. Z_t^+ is introduced to represent the value after discrete operation.

2.2 Multimodal Graph Transformer Module

To explore the relationship among different modalities, we introduce the multimodal graph transformer layer. The previous pooling layer ignores the importance of nodes, we design a novel Graph Transformer pooling layer to keep the permutation invariance and injectiveness. The Graph Transformer module consists of a multi-head attention layer and a Graph Transformer pooling layer. **Graph multi-head attention** Within each view, the inputs for the multi-head attention consists the terminal state of dynamical neural graph encoder. The inputs are transformed to query $Q \in R^{n_q \times d_k}$, key $K \in R^{n \times d_k}$ and value $V \in R^{n \times d_v}$, where n_q is the number of query vectors and n represents the number of input nodes. d_k and d_v denotes the dimensionality of corresponding key vector and value vector. The attention dot production is defined as $Att(Q, K, V) = w(QK^T)V$. We define the output of the multi-head attention module (MH) as

$$MH(Q, K, V) = [O_1, \dots, O_h]W^O; O_i = Att(QW_i^Q, KW_i^K, VW_i^V), \quad (3)$$

where W_i^Q, W_i^K and W_i^V are parameter matrices. The output project matrices is defined as W^O . Using the heterogeneous graph representation learned by graph

encoder (GE), the graph multi-head attention block could be denoted by

$$GMH(Q, K, V) = [O_1, \dots, O_h]W^O; O_i = Att(QW_i^Q, GE_i^K(H, A), GE_i^V(H, A)), \quad (4)$$

Graph transformer pooling together with graph multi-head attention
 Inspired by traditional Transformer based method [12], we introduce a novel Graph Transformer pooling layer to learn the global representation of the entire graph, which is defined as follows:

$$GMPool_k(H, A) = LN(Z + rFF(Z)); Z = LN(S + GMH(S, H, A)), \quad (5)$$

where rFF is any row-wise feed forward layer. S is the seed matrix which could be directly optimized. LN is a layer normalization. In addition, we introduce the self-attention layer to explore the relationship between different nodes.

$$SelfAtt(H) = LN(Z + rFF(Z)); Z = LN(H + MH(H, H, H)), \quad (6)$$

Together with graph encoder module, the overall framework is defined with the coarsened adjacency matrix A'

$$Pooling(H, A) = GMPool_1(selfAtt(GMPool_k(H, A)), A'), \quad (7)$$

2.3 Contrastive Graph Representation Learning

Finally, we apply the shared projection head $f_\phi(\cdot) \in R^{d_h}$ to the aggregated heterogeneous representation of each view. In the experiment, we use an MLP with two hidden layers as the projection head. The projected representations are defined as, \vec{h}_g^A and \vec{h}_g^B . For each view, the node representation are concatenated as follows,

$$\vec{h}_g = \sigma\left(\left\|\sum_{i=1}^n \vec{h}_i^l\right\|W\right), \quad (8)$$

The graph and node representations of the overall Graph Transformer module are defined as $\vec{h} = \vec{h}_g^A + \vec{h}_g^B$ and $\hat{H} = H^A + H^B$. In the training stage, the cross modal mutual information between the node representation and graph representation is defined as,

$$\max_{\theta, \omega, \phi, \psi} \frac{1}{|\mathcal{G}|} \sum_{\mathcal{G}} \left[\frac{1}{|g|} \sum_{i=1}^{|g|} [MI(\vec{h}_i^A, \vec{h}_g^B) + MI(\vec{h}_i^B, \vec{h}_g^A)] \right], \quad (9)$$

where $\theta, \omega, \phi, \psi$ represent the parameters of heterogeneous graph convolution and projection head. $|\mathcal{G}|$ is the total numbers of graph. $|g|$ is the number of nodes. MI is denoted as the dot production $MI(\vec{h}_i^A, \vec{h}_g^B) = \vec{h}_i^A \cdot (\vec{h}_g^B)^T$.

3 Experimental Results

We evaluated the proposed method with resting state fMRI of 1200 subjects from Human Connectome Project (HCP). The resting state fMRI was preprocessed using the HCP minimal preprocessing pipeline [8]. The artefacts of the BOLD signal were further removed using ICA-FIX. The cortical surface was parcellated into $N=360$ major ROIs using MMP1.0 parcellation[7]. We excluded 5 subjects with less than 1200 time points for resting-state fMRI data. Additionally, about 95 subjects have resting-state and/or task MEG (tMEG) data. We used 80% of the whole dataset for training and evaluation. The remaining dataset is used for testing. The corresponding resting-state MEG data were acquired in three 6 minutes runs. The preprocessing of MEG data followed the pipeline provided by HCP data [11]. The source reconstruction was performed using the FieldTrip toolbox. Then sensor data was bandpass filtered into 1.3 to 55Hz and projected into source space by synthetic aperture magnetometry. After source reconstruction on the 8k-grid, the time courses were parcellated using MSMAAll atlas [8]. The parcellated time courses were z-score normalized for both fMRI and MEG data. In addition, we used the ratio between T1 to T2 weighted maps from HCP dataset as the heterogeneity map. The parcellated diffusion MRI (dMRI) was analysed to generate the structural connectivity (SC) and compute the adjacency matrix \tilde{A} for graph encoder module.

3.1 Heterogeneity Improves the Model Fit to FC

In the first experiment, we tested the similarity between empirical FC and heterogeneous FC patterns acquired by the proposed method compared with the homogeneous model. The empirical group averaged FC, particle-averaged homogeneous FC and heterogeneous FC are shown in Fig. 2. We used a simple non-neural model to introduce self-coupling heterogeneity strength $w_i = w_{min} + w_{scale}s_i$ based on the heterogeneity map s_i , where w_{min} and w_{scale} are heterogeneity parameters.

Synaptic dynamical equations We introduced the biophysically-based computational model to simulate the functional dynamics $\dot{y}_i(t)$ for each node i with the heterogeneity map s_i .

$$\dot{y}_i(t) = -y_i(t) + \sum_j C_{ij}y_j(t) + n_{\nu_i}(t), \quad (10)$$

where $n_{\nu_i}(t)$ is the independent Gaussian white noise. C represents the coupling matrix. $y_i(t)$ is the learned representation using the proposed method. We incorporated the SC matrix S^C and global coupling parameter G^C with $\dot{y}_i(t)$,

$$\dot{y}_i(t) = - \sum_j [(1 - w_i)\delta_{ij} - G^C S_{ij}^C]y_j(t) + n_{\nu_i}(t), \quad (11)$$

We used the squared Pearson correlation coefficient to evaluate the similarity between empirical FC and model fit FC for a single hemisphere. Fig. 2

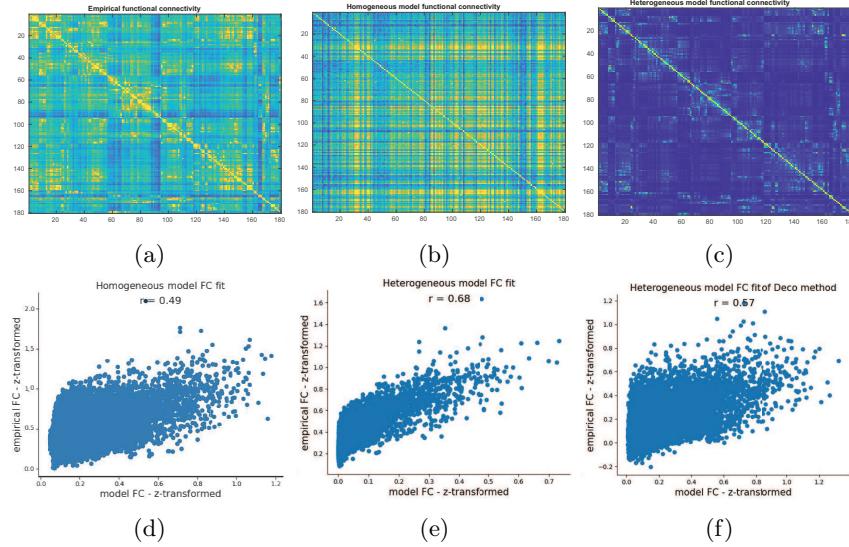


Fig. 2: Heterogeneity map improves the model fit to functional connectivity (FC). (a) Empirical FC. (b) Homogeneous FC. (c) Heterogeneous FC. And (d-f) correlations between empirical FC and model FC, for the Homogeneous (d) Heterogeneous Graph Transformer (e) and Deco's model (f).

shows that the similarity of the proposed graph Transformer model is larger with $r=0.68$ than the homogeneous model ($r = 0.49$) ($p < 10^{-4}$, dependent correlation test). The proposed model also yields higher FC similarity than Deco's model[6] ($r=0.57$). The experimental result linking multiple modalities demonstrates the hypothesis that the T1w/T2w map shapes the microcircuit properties and spatio-temporal brain dynamics. The introduction of T1w/T2w heterogeneity with the proposed method could capture the dominant neural axis for microcircuit specialization is shown in Fig. 3. In summary, the proposed method with the prior of areal heterogeneity could inform the dynamical relationships among structure, function, and physiology.

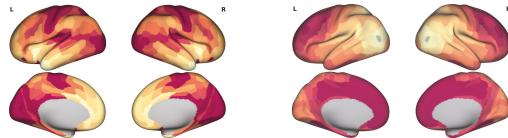


Fig. 3: T1w/T2w heterogeneity map (left) and the example surrogate heterogeneity map (right)

3.2 Functional Connectivity and Behaviors

In the second experiment, we used a NeuroSynth meta-analysis [13] to assess the topic terms with the structural-functional coupling index in Fig. 4. The experimental results demonstrate the existence of behavior related global gradient spanning from lower to higher level cognitive functions. The evidence of global gradient reveals that higher coupling strength in sensory-motor areas which requires fast reacting (i.e. “visual perception”, “multisensory processing”, “motor/eye movement”). However, the coupling strength in high level cognitive regions (i.e. “autobiographical memory”, “emotion” and “reward-based decision making”) is low. Similar organization phenomenon could be found in the previous research [13, 14].

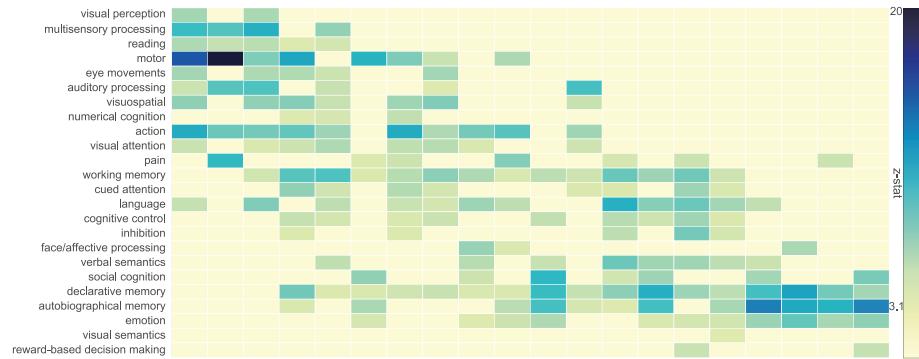


Fig. 4: Behaviorally relevant gradient shows brain organization

4 Conclusions

In the study, we propose a novel Graph Transformer based method for decoding the brain spatio-temporal dynamics. Different from most of the existing graph convolution method, the Graph Transformer model with multi-head attention guarantees the learning of global graph structure of multimodal data (i.e. dMRI, fMRI and MEG). The contrastive learning model makes it possible to associate multimodal graph representation and reveal how the heterogeneity map shapes the human cortical dynamics. The experimental results demonstrate the importance of regional heterogeneity and the corresponding intrinsic structure-function relationship within brain dynamical organization. Moreover, the proposed method provides insights into brain inter- and intra-regional coupling structure and the relationship between dynamical FC and human behaviors.

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