

HOW MUCH CAN ONE LEARN FROM A SINGLE SOLUTION OF A PDE?

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ABSTRACT. In this work, we study the problem of learning a partial differential equation (PDE) from its solution data. PDEs of various types are used to illustrate how much the solution data can reveal the PDE operator depending on the underlying operator and initial data. A data-driven and data-adaptive approach based on local regression and global consistency is proposed for stable PDE identification. Numerical experiments are provided to verify our analysis and demonstrate the performance of the proposed algorithms.

1. Introduction

Partial differential equations (PDE) play an important role in modeling, studying, and predicting complicated dynamics in science, engineering and related fields as well as many real-world applications such as heat convection/diffusion, fluid flow, weather forecast, climate change, etc. A typical procedure is to derive a PDE model, e.g., using physical laws or assumptions, then study the model and develop numerical algorithms for computer simulation. With the advance of technologies, abundant data are available from measurements and observations in many situations where the underlying model is not yet known or not accurate enough, a natural question is whether one can learn or predict the dynamic using data driven approach, which prompt recent increasing interest in PDE learning from its solution data.

A basic and essential question for PDE learning is how much solution data is needed and how much data is available realistically. A common issue in most of the previous PDE learning approaches is the assumption of availability of any solution data and as much as one would like. In many real applications, one only has the chance to observe a phenomenon and its dynamics once it happens for some time duration, i.e, a single solution $u(x,t), 0 < t \le T$. Even if the event happens again, the environment and setup is different. In our earlier work [4], we characterized the solution data space, the dimension of the space spanned by all snapshots in time of a solution with certain tolerance, and showed how it is affected by the underlying PDE and the initial data for an evolution PDE $\partial_t u(x,t) = -\mathcal{L}u$. In particular, it was shown that the data space is small if \mathcal{L} is strongly elliptic, which implies limited data from a single solution trajectory and the challenge for PDE learning in

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practice. It was also shown that the space spanned by all possible solution is small after t > 0.

In this work, we study if the space of a single (or a finite number of) solution(s) is as rich as the space of all solutions, or in other words, can one use a superposition of snapshots of a single (or a finite number of) solution(s) to construct an arbitrary solution. When the answer is positive, one can use data driven approach for model reduction and solution approximation bypassing explicit learning or approximation of the PDE operator. In our study, the following evolution PDE on a compact domain $\Omega \subset \mathbb{R}^d$ satisfying certain homogeneous boundary condition,

(1.1)
$$\partial_t u(x,t) = -\mathcal{L}u(x,t), \qquad x \in \Omega \subset \mathbb{R}^d, \ 0 < t \le T \le \infty,$$

$$\mathcal{B}u(x,t) = 0, \qquad x \in \partial\Omega,$$

$$u(x,0) = f(x) \qquad x \in \Omega,$$

where $\mathcal{L} = \sum_{0 \leq |\alpha| \leq N_{\mathcal{L}}} p_{\alpha}(x) \partial^{\alpha}$ is a self-adjoint strongly elliptic differential operator of order $N_{\mathcal{L}}$ with coefficients $p_{\alpha} \in C^{|\alpha|+N_{\mathcal{L}}/2}(\overline{\Omega})$ and the boundary $\partial\Omega$ is smooth (if not empty) and $\mathcal{B}u = 0$ denotes the Dirichlet boundary condition $\partial^{\alpha}u(x,t) = 0$ for $x \in \partial\Omega$, $|\alpha| \leq \frac{N_{\mathcal{L}}}{2} - 1$, then \mathcal{L} is self-adjoint [7].

The rest of the paper is organized as follows. We first present in Section 2 some preliminaries and formulate the problem into a moment problem. We then consider in Section 3 the cases where eigenvalues μ_n of \mathcal{L} are simple and grows superlinearly or (sub-)linearly in terms of n, which gives different statements. In Section 4 we study the problem when eigenvalues has finite multiplicities. We then present numerical experiments in Section 5 to verify our analysis and provide an application of data driven approach for solving PDEs without knowing the underlying PDE. We finally give a conclusion in Section 6.

2. Preliminaries

Consider the PDE (1.1), for simplicity, we assume the eigenvalues $0 < \mu_1 < \mu_2 < \dots$ of the self-adjoint strongly elliptic differential operator \mathcal{L} are positive and distinct and denote $\phi_1(x), \phi_2(x), \dots$ to be the corresponding eigenfunctions which form a complete orthonormal basis in $L^2(\Omega)$. Let u(x,t) be a sample solution which can be represented as

(2.1)
$$u(x,t) = \sum_{n=1}^{\infty} e^{-\mu_n t} c_n \phi_n(x),$$

where $u(x,0) = \sum_{n=1}^{\infty} c_n \phi_n(x)$, $c_n \neq 0$. Given an initial condition $f(x) = \sum_{n=1}^{\infty} f_n \phi_n(x) \in L^2(\Omega)$, we can express the solution at time τ by

(2.2)
$$w(x,\tau) = \sum_{n=1}^{\infty} e^{-\mu_n \tau} f_n \phi_n(x).$$

In order to express the solution $w(x,\tau)$ at $\tau > 0$ as a superposition of snapshots of the sample solution, we introduce the interpolation or weight function $\nu(t;\tau) \in$

 $L^2([0,T])$ and solve the following equation

(2.3)
$$w(x,\tau) = \int_0^T u(x,t)\nu(t;\tau)dt,$$

which is equivalent to solving the exponential moment problem

(2.4)
$$\int_0^T e^{-\mu_n t} \nu(t; \tau) dt = m_n := e^{-\mu_n \tau} f_n / c_n.$$

Definition 2.1. The functions $\{\varphi_n\}_{n\geq 1}$ are bi-orthogonal with respect to $\{e^{-\mu_n t}\}_{n\geq 1}$ in [0,T] if

(2.5)
$$\int_0^T e^{-\mu_n t} \varphi_k(t) dt = \delta_{kn},$$

where δ_{kn} is the Kronecker delta.

Suppose the bi-orthogonal functions $\{\varphi_n\}_{n\geq 1}$ exist, then a formal expansion of $\nu(t)$ can be written as

(2.6)
$$\nu(t) = \sum_{n=1}^{\infty} m_n \varphi_n(t).$$

However, the exact characterization of the convergence behavior of the series (2.6) is a difficult task. Instead, we will study the absolute convergence in $L^2[0,T]$, which means

(2.7)
$$\sum_{n=1}^{\infty} |m_n| \cdot ||\varphi_n||_{L^2[0,T]} < \infty.$$

If the series indeed converges absolutely, then the series converges in $L^2[0,T]$. The existence of ν implies $w(x,\tau)$ can be linearly represented by the sample solution u(x,t) on [0,T]. Clearly, it only remains to estimate the norms $\|\varphi_n\|_{L^2[0,T]}$.

Remark 2.2. When there exist non-positive eigenvalues, one can find a constant $\overline{\mu}$ that $\mu_1 + \overline{\mu} > 0$, then the interpolation function can be changed to $\nu(t)e^{\overline{\mu}t}$ instead. Hence in the rest of this paper, we only focus on the case that all eigenvalues are positive.

3. Solution of the moment problem

3.1. Convergent series. Let \mathcal{E}_T be the smallest closed subspace of $L^2[0,T]$ containing the functions $e^{-\mu_n t}$, $n=1,2,\ldots$ It is known [3] that \mathcal{E}_T is a proper subspace of $L^2[0,T]$ if and only if

$$(3.1) \qquad \sum_{n=1}^{\infty} \mu_n^{-1} < \infty.$$

In the case that (3.1) is convergent, we define \mathcal{E}_T^n by the smallest closed subspace of $L^2[0,T]$ containing all $e^{-\mu_k t}$ for $k \neq n$, then $e^{-\mu_n t} \notin \mathcal{E}_T^n$, there exists a unique

element $r_n \in \mathcal{E}_T^n$ such that minimizes $d_n(T) := \|e^{-\mu_n t} - r_n\|_{L^2[0,T]}$, then the optimal bi-orthogonal function φ_n is chosen by

(3.2)
$$\varphi_n = \frac{e^{-\mu_n t} - r_n}{d_n(T)^2}$$

and its norm $\|\varphi_n\|_{L^2[0,T]} = d_n(T)^{-1}$. If $T = \infty$, the computation of $d_n(T)$ is fairly simple [3]

(3.3)
$$d_n(\infty) = \sqrt{\frac{2}{\mu_n}} \frac{\left| \prod_{j \neq n} \left(1 - \frac{\mu_n}{\mu_j} \right) \right|}{\prod_{j \geq 1} \left(1 + \frac{\mu_n}{\mu_j} \right)},$$

while for a finite T, there exists a constant $\kappa(T) > 0$ such that $d_n(T) \ge \kappa(T)^{-1} d_n(\infty)$ [9], hence

(3.4)
$$\|\varphi_n\|_{L^2[0,T]} \le \kappa(T) \sqrt{\frac{\mu_n}{2}} \frac{\prod_{j \ge 1} \left(1 + \frac{\mu_n}{\mu_j}\right)}{\left|\prod_{j \ne n} \left(1 - \frac{\mu_n}{\mu_j}\right)\right|}.$$

We estimate $\|\varphi_n\|_{L^2[0,T]}$ under the following two assumptions.

Assumption 3.1. For certain $\sigma \in (0,1]$ and $\beta > 1$, $\mu_n = Mn^{\beta}(1 + o(n^{-\sigma}))$.

Assumption 3.2. For certain $\theta > 0$ and $s \ge 0$ such that for each $n \ge 1$, $\mu_{n+1} - \mu_n \ge \theta n^{-s}$.

Under suitable conditions, the first assumption holds true for the strongly elliptic operators [1,2,5,8,15], where the growth rate is $\beta=N_{\mathcal{L}}/d>1$ when the space dimension is less than the order of the elliptic operator. The exponent σ can be made explicit in certain cases, see Theorem C in [2] and Theorem 3.1 in [1]. The second assumption is to prevent the blowing-up of $\|\varphi_n\|_{L^2[0,T]}$. When the eigenvalues are multiple of integers, i.e., $\mu_n=Mn^{\beta}$, this is guaranteed. However in general there is no known estimate for $\mu_{n+1}-\mu_n$ except the spectral gap. For specific cases (see Section 6.3), it is possible to claim the desired lower bound. Particularly, the one dimensional Sturm-Liouville operators with Dirichlet boundary conditions satisfy both of the assumptions.

In the following, we introduce a lemma for the estimates of the products appearing in (3.4). The proof is included in the appendix B and the main idea follows [3]. **Lemma 3.3.** The following estimates hold.

(3.5)
$$\left| \prod_{j \ge 1} \left(1 + \frac{\mu_n}{\mu_j} \right) = \exp\left(M^{-1/\beta} \mu_n^{1/\beta} (\zeta_{0,\beta} + o(1)) \right),$$

$$\left| \prod_{j \ne n} \left(1 - \frac{\mu_n}{\mu_j} \right) \right| \ge \exp(-K_0 \mu_n^{1/\beta} M^{-1/\beta} (\log \mu_n + K_1)),$$

where $\zeta_{0,\beta} := \int_0^\infty \frac{dy}{y^{1-1/\beta}(1+y)}$ and K_0 , K_1 are positive constants independent of n.

Lemma 3.4. The bi-orthogonal set $\{\varphi_n\}_{n\geq 1}$ satisfies the following bound

(3.6)
$$\|\varphi_n\|_{L^2[0,T]} \le \sqrt{\frac{\mu_n}{2}} \kappa(T) \exp\left(K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2)\right),$$

where K_2 is a positive constant independent of n.

Proof. It is known that

$$\|\varphi_{n}\|_{L^{2}[0,T]} \leq \sqrt{\frac{\mu_{n}}{2}} \kappa(T) \frac{\prod_{j \geq 1} \left(1 + \frac{\mu_{n}}{\mu_{j}}\right)}{\left|\prod_{j \neq n} \left(1 - \frac{\mu_{n}}{\mu_{j}}\right)\right|}$$

$$\leq \sqrt{\frac{\mu_{n}}{2}} \kappa(T) \exp\left(M^{-1/\beta} \mu_{n}^{1/\beta} \left[\left(\zeta_{0,\beta} + o(1)\right) + K_{0}(\log \mu_{n} + K_{1})\right]\right)$$

$$\leq \sqrt{\frac{\mu_{n}}{2}} \kappa(T) \exp\left(K_{0} M^{-1/\beta} \mu_{n}^{1/\beta} (\log \mu_{n} + K_{2})\right),$$

where the constant $K_2 \geq K_1 + (\zeta_{0,\beta} + o(1))/K_0$.

Using the above estimate of $\|\varphi_n\|_{L^2[0,T]}$, we immediately obtain the following theorem to characterize the absolute convergence of ν .

Theorem 3.5. The exponential moment problem has an absolutely convergent solution in $L^2[0,T]$ if

(3.8)
$$\sum_{n=1}^{\infty} |m_n| \sqrt{\mu_n} \exp\left(K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2)\right) < \infty$$

Corollary 3.6. If $\tau > 0$, then the moment problem with $m_n = e^{-\mu_n \tau} \frac{f_n}{c_n}$ has a solution in $L^2[0,T]$ if

$$(3.9) \sum_{n=1}^{\infty} \left| \frac{f_n}{c_n} \right|^2 \exp(-2\mu_n \tau_0) < \infty.$$

for certain $\tau_0 \in [0, \tau)$.

Proof. From the Theorem 3.5, we just need to show

(3.10)
$$\sum_{n=1}^{\infty} \frac{f_n}{c_n} \sqrt{\mu_n} \exp\left(-\mu_n \tau + K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2)\right) < \infty.$$

By the Cauchy-Schwartz inequality,

$$(3.11) \left[\sum_{n=1}^{\infty} \frac{f_n}{c_n} \sqrt{\mu_n} \exp\left(-\mu_n \tau + K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2)\right) \right]^2$$

$$\leq \sum_{n=1}^{\infty} \left| \frac{f_n}{c_n} \right|^2 \exp(-2\mu_n \tau_0) \sum_{n=1}^{\infty} \mu_n \exp\left(-2\mu_n (\tau - \tau_0) + 2K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2)\right)$$

Our conclusion is immediately proved by noticing that when n is sufficiently large,

$$(3.12) -2\mu_n(\tau - \tau_0) + 2K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2) + \log \mu_n < -\mu_n(\tau - \tau_0).$$

Theorem 3.7. Suppose g(x) satisfies that

(3.13)
$$g(x) = \sum_{n=1}^{\infty} c_n \phi_n(x),$$

where $|c_n| \geq Ce^{-pn^{\alpha}}$ for certain constants C > 0, $p \geq 0$ and $\alpha \in [0, \beta)$, $n = 1, 2, \ldots$ and $f \in L^2(\Omega)$. Let u(x,t) and w(x,t) be the solutions with respect to initial conditions g(x) and f(x) respectively. $\forall \tau > t_0$, there exists an interpolation function $\nu(t; \tau, [t_0, t_1]) \in L^2[t_0, t_1]$ such that

(3.14)
$$w(x,\tau) = \int_{t_0}^{t_1} u(x,t)\nu(t;\tau)dt,$$

and $\|\nu(\cdot;\tau)\|_{L^2[t_0,t_1]} \leq \frac{1}{\sqrt{2}C}\kappa(t_1-t_0)\|f\|_{L^2(\Omega)}\cdot(\tau-t_0)^{-\omega(\tau-t_0)/2}$ with

(3.15)
$$\omega(t) = 1 + \varpi t^{-\frac{\max(\alpha, 1)}{(\beta - \max(\alpha, 1) - \delta)}},$$

where $\delta \in (0, \beta - \max(\alpha, 1))$ is arbitrary and ϖ is a constant independent of t.

Proof. By the Corollary (3.6), we only need to check if

(3.16)
$$\sum_{n=1}^{\infty} \left| \frac{f_n e^{-\mu_n t_0}}{c_n e^{-\mu_n t_0}} \right|^2 e^{-2\mu_n \tau_0} = \sum_{n=1}^{\infty} \left| \frac{f_n}{c_n} \right|^2 e^{-2\mu_n \tau_0} < \infty$$

for certain $\tau_0 \in [0, \tau - t_0)$. Since $|c_n| \ge Ce^{-pn^{\alpha}}$, this becomes $\sum_{n=1}^{\infty} |f_n|^2 e^{2pn^{\alpha}} e^{-2\mu_n \tau_0}$, which is finite if $\sum_{n=1}^{\infty} |f_n|^2 < \infty$. Now we give an estimate of $\|\nu(\cdot;\tau)\|_{L^2[t_0,t_1]}$. Denoting $T = t_1 - t_0$ and $\tilde{\tau} = \tau - t_0$, we recall (2.6) and Lemma 3.4,

$$\|\nu(\cdot;\tau)\|_{L^{2}[t_{0},t_{1}]} \leq \sum_{n=1}^{\infty} \left| \frac{f_{n}}{c_{n}} \exp(-\mu_{n}\tilde{\tau}) \right| \sqrt{\frac{\mu_{n}}{2}} \kappa(T) \exp\left(K_{0} M^{-1/\beta} \mu_{n}^{1/\beta} (\log \mu_{n} + K_{2})\right)$$

$$\leq \frac{\kappa(T)}{C} \sum_{n=1}^{\infty} |f_{n}| \sqrt{\frac{\mu_{n}}{2}} \exp\left(-\mu_{n}\tilde{\tau} + K_{0} M^{-1/\beta} \mu_{n}^{1/\beta} (\log \mu_{n} + K_{2}) + pn^{\alpha}\right)$$

$$\leq \frac{\kappa(T)}{\sqrt{2}C} \left(\sum_{n=1}^{\infty} |f_{n}|^{2}\right)^{1/2} \sqrt{\mathcal{A}(\tilde{\tau})},$$

where $\mathcal{A}(\tilde{\tau})$ is the summation (3.17)

$$\mathcal{A}(\tilde{\tau}) = \sum_{n=1}^{\infty} \exp\left(-2\mu_n \tilde{\tau} + \log \mu_n + 2K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2) + 2pn^{\alpha}\right).$$

We define

(3.18)
$$H := \sup_{n \ge 1} \frac{\log \mu_n + 2K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2)}{\mu_n^{1/\beta} \log \mu_n},$$
$$N_{\tilde{\tau}} := \sup \left\{ n \in \mathbb{N} \mid H \log \mu_n + 2p n^{\alpha} \mu_n^{-1/\beta} \ge \tilde{\tau} \mu_n^{1-1/\beta} \right\},$$

then we have the estimate $H = 2K_0M^{-1/\beta} + O(1)$ and $N_{\tilde{\tau}} \leq L\tilde{\tau}^{-1/(\beta - \max(\alpha, 1) - \delta)}$ for arbitrary $\delta \in (0, \beta - \max(\alpha, 1))$ and a constant $L = L(H, \delta) > 0$ as $\tilde{\tau} \to 0$. On the other hand, since $xe^{-x} \leq e^{-1}$ for any x > 0, we can derive

(3.19)
$$\sum_{n=1}^{\infty} \exp(-\mu_n \tilde{\tau}) \le \frac{1}{e} \sum_{n=1}^{\infty} \frac{1}{\mu_n \tilde{\tau}} = \frac{C'}{\tilde{\tau}},$$

where $C' = e^{-1} \sum_{n=1}^{\infty} \mu_n^{-1} < \infty$. Therefore as $\tilde{\tau} \to 0$,

$$\mathcal{A}(\tilde{\tau})$$

$$\leq \sum_{n=1}^{N_{\tilde{\tau}}} \exp\left(-2\mu_n \tilde{\tau} + \log \mu_n + 2K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2) + 2pn^{\alpha}\right)$$

$$+ \sum_{n>N_{\tilde{\tau}}} \exp(-\mu_n \tilde{\tau})$$

$$\leq \left[\sum_{n=1}^{N_{\tilde{\tau}}} \exp(-2\mu_n \tilde{\tau})\right] \sup_{1\leq n\leq N_{\tilde{\tau}}} \exp\left(\log \mu_n + 2K_0 M^{-1/\beta} \mu_n^{1/\beta} (\log \mu_n + K_2) + 2pn^{\alpha}\right)$$

$$+ \frac{C'}{\tilde{\tau}}$$

$$\leq \frac{C'}{\tilde{\tau}} \exp\left(H\beta M^{1/\beta} N_{\tilde{\tau}} \log N_{\tilde{\tau}} (1 + o(1)) + 2pN_{\tilde{\tau}}^{\alpha}\right) + \frac{C'}{\tilde{\tau}}$$

$$\leq \frac{C'}{\tilde{\tau}} \left(e^{2pN_{\tilde{\tau}}^{\alpha} + C''N_{\tilde{\tau}} \log N_{\tilde{\tau}}} + 1\right),$$

where $C'' = C''(H, \beta, M)$ is a constant.

Remark 3.8. It is worthwhile to notice the upper bound for $\|\nu(\cdot;\tau)\|_{L^2[t_0,t_1]}$ only depends on the differences t_1-t_0 and $\tau-t_0$ and the initial time t_0 does not matter. Actually the dependence on t_1-t_0 from $\kappa(t_1-t_0)$ in (3.4) is quite mild. However, the dependence on $\tilde{\tau}=\tau-t_0$ is significant, which implies stability issue when τ is close to t_0 .

Remark 3.9. One of the practical issues is that without knowing much of the self-adjoint differential operator \mathcal{L} , can one create a sample solution corresponding to an initial condition satisfying the condition in Theorem 3.7? An intuitive choice is to use a point source (or an approximate one in practice) as initial condition, which has the expansion

(3.20)
$$\delta(x-y) = \sum_{n=1}^{\infty} \phi_n(x) \overline{\phi_n(y)}.$$

When the set $\cap_{n\geq 1}\{|\phi_n(z)| > \exp(-pn^{\alpha})\}$ has a positive measure for certain p, then it is possible to randomly select single point sources to fulfill the condition in Theorem 3.7. For instance, if we take the domain as d-dimension torus $\Omega = \mathbb{T}^d$ and $\mathcal{L} = -\nabla \cdot (A(x)\nabla)$ that A(x) is Lipschitz, the eigenfunction ϕ_n satisfies

(3.21)
$$\sup_{\Omega} |\phi_n| \le C \sup_{E} |\phi_n| \left(C \frac{|\Omega|}{|E|} \right)^{C\sqrt{\mu_n}}$$

for certain C > 0 for any measurable subset $E \subset \Omega$ [6]. If we denote $E = \{|\phi_n| \le e^{-pn^{\alpha}}\}$ and use $\|\phi_n\|_{L^{\infty}(\Omega)} \ge \frac{1}{\sqrt{|\Omega|}}$, then

$$(3.22) |\{|\phi_n(x)| \le e^{-pn^{\alpha}}\}| \le C|\Omega| \left[\frac{C \exp(-pn^{\alpha})}{1/\sqrt{|\Omega|}}\right]^{\frac{1}{C\sqrt{\mu n}}}$$

$$\le C|\Omega| \left[C\sqrt{|\Omega|}\right]^{\frac{1}{C\sqrt{\mu n}}} \exp(-\frac{p}{C\sqrt{M}}n^{\alpha-\beta/2}(1+o(1))),$$

where we have used the fact that $\mu_n = Mn^{\beta}(1+o(1))$. If $\beta > \alpha > \frac{\beta}{2}$, we obtain

(3.23)
$$\sum_{n>1} |\{|\phi_n(x)| \le e^{-pn^{\alpha}}\}| < \infty.$$

Therefore as $p \to \infty$, the summation converges to zero. This implies that for sufficiently large p, there is a high probability that a random point $z \in \Omega$ that $|\phi_n(z)| > \exp(-pn^{\alpha})$ for all $n \ge 1$. It is unclear whether such statement can be extended to high order strongly elliptic operators.

3.2. Divergent series. It still remains to discuss about the case that

$$(3.24) \qquad \qquad \sum_{n=1}^{\infty} \mu_n^{-1} = \infty,$$

then $\mathcal{E}_T = L^2[0,T]$ [3]. For simplicity, we let $T = \infty$, instead of dealing with the infinite moment sequence, we consider the finite case for the first N moments. Similarly, we define the bi-orthogonal functions $\widetilde{\varphi}_n$, $n = 1, 2, \ldots, N$,

(3.25)
$$\int_0^\infty e^{-\mu_n t} \widetilde{\varphi}_k(t) dt = \delta_{k,n}, \quad 1 \le k, n \le N.$$

the corresponding solution is

(3.26)
$$\nu_N(t) = \sum_{n=1}^N m_n \widetilde{\varphi}_n(t).$$

where $\widetilde{\varphi}_n$ is optimal in L^2 norm. Using the same argument as Section 3.1, the bi-orthogonal functions $\widetilde{\varphi}_n$ to (3.25) satisfies

(3.27)
$$\|\widetilde{\varphi}_n\|_{L^2[0,\infty)} = \sqrt{2\mu_n} \frac{\prod_{j\neq n}^N (1 + \frac{\mu_n}{\mu_j})}{\left|\prod_{j\neq n}^N (1 - \frac{\mu_n}{\mu_j})\right|}, \quad n = 1, 2, \dots, N.$$

For the sake of simplicity, we still make the same assumptions 3.1 and 3.2. When $0 \le \beta \le 1$ and given any fixed n,

(3.28)
$$\sum_{j\neq n}^{N} \log \left(\frac{1 + \frac{\mu_n}{\mu_j}}{|1 - \frac{\mu_n}{\mu_j}|} \right) = \sum_{j=1}^{N} \frac{2\mu_n}{\mu_j} \left(1 + o(1) \right), \text{ as } N \to \infty,$$

therefore

(3.29)
$$\|\widetilde{\varphi}_n\|_{L^2[0,\infty)} = \sqrt{2\mu_n} \exp\left(2\mu_n \sum_{j=1}^N \mu_j^{-1} (1 + o(1))\right), \text{ as } N \to \infty.$$

Then $\|\widetilde{\varphi}_n\|_{L^2[0,\infty)} \to \infty$ as $N \to \infty$, we can conclude the following theorem.

Theorem 3.10. If $\beta \in [0,1]$, then the series solution $\lim_{N\to\infty} \nu_N$ cannot be absolutely convergent unless $m_n \equiv 0$ for all n.

However, the solution still can be convergent for certain cases. As an interesting example, we consider that $\mu_n = n - \frac{1}{2}$, $n = 1, 2, \ldots$ and $T = \infty$, then finding the interpolating function is equivalent to solve the moment problem

(3.30)
$$\int_0^\infty e^{-(n-\frac{1}{2})t} \nu(t) dt = m_n.$$

With a change of variable $x = e^{-t}$ and denote $\tilde{\nu}(x) = \nu(t)$, this is similar to the Hausdorff moment problem

(3.31)
$$\int_0^1 x^{n-1} \cdot x^{-1/2} \tilde{\nu}(x) dx = m_n.$$

Definition 3.11. For a given sequence m_1, m_2, \ldots , we define

(3.32)
$$\lambda_{k,k'} := \binom{k}{k'} \sum_{l=0}^{k-k'} (-1)^{k-k'+l} \binom{k-k'}{l} m_{k-l+1}, \quad k \ge k' \ge 0.$$

Lemma 3.12 (Widder [14]). Let $\overline{L} > 0$ be an arbitrary fixed number, then the following condition

(3.33)
$$(k+1) \sum_{k'=0}^{k} |\lambda_{k,k'}|^2 < \overline{L}, \quad \forall k = 0, 1, \dots$$

is necessary and sufficient for $x^{-1/2}\tilde{\nu}(x)\in L^2[0,1]$ satisfying the moment problem (3.31).

Corollary 3.13. If and only if the condition (3.33) is satisfied, the interpolation function $\nu(t)$ exists in $L^2[0,\infty)$ and

(3.34)
$$\int_{0}^{\infty} |\nu(t)|^{2} dt = \int_{0}^{1} x^{-1} |\tilde{\nu}(x)|^{2} dx < \infty$$

Especially, if $m_n = n^{-1}$, one can compute directly that $(k+1)\sum_{n=0}^{k} |\lambda_{k,n}|^2 \equiv 1$ which permits a solution in $L^2[0,\infty)$. However, if we set $c_n = e^{-pn^{\alpha}}$ (same as Theorem 3.7) and use the same initial condition that

$$\sum_{n=1}^{\infty} |f_n|^2 < \infty, \text{ and } m_n = e^{-(n-\frac{1}{2})\tau} \frac{f_n}{c_n} = e^{-(n-\frac{1}{2})\tau} e^{pn^{\alpha}} f_n, \quad n \ge 1.$$

Then for a given k, let A denotes the upper triangle matrix

$$(3.35) A_{l,l'} = \sqrt{k+1} \binom{k}{l} e^{-(l'+\frac{1}{2})\tau} e^{(l'+1)^{\alpha}p} (-1)^{l'-l} \binom{k-l}{l'-l}, 0 \le l \le l' \le k$$

and denote $\mathbf{f} = (f_1, \dots, f_k)^T \in \ell^2$, then (3.36)

$$\sup_{\|\mathbf{f}\|=1} \sum_{k'=0}^{k} (k+1) |\lambda_{k,k'}|^2 = \sup_{\|\mathbf{f}\|=1} \mathbf{f}^T A^T A \mathbf{f} = \sup_{0 \le l \le k} \sigma_l^2(A)$$

$$\geq \sup_{0 \le l \le k} |A_{l,l}|^2 = \sup_{0 \le l \le k} \left[\sqrt{k+1} \binom{k}{l} e^{-(l+\frac{1}{2})\tau} e^{(l+1)^{\alpha} p} \right]^2$$

$$\geq (k+1) e^{-\tau + 2p} \to \infty, \quad \text{as } k \to \infty.$$

This implies that there exists $\mathbf{f} = (f_1, f_2, \dots,)^T \in \ell^2$ such that the moment problem has no solution in $L^2[0, \infty)$ as long as τ is finite.

4. Multiplicities

In this section, we study the case that the eigenvalues have finite multiplicities. Denote the maximal multiplicity as D, we show that at most D sampled trajectories $\{u_j\}_{j=1}^D$ are sufficient to span the solution subspace, that is, if $\tau > t_0$ then there exist interpolation functions $\nu_j \in L^2[t_0, t_1], j = 1, 2, ..., D$ that

(4.1)
$$w(x,\tau) = \sum_{j=1}^{D} \int_{t_0}^{t_1} u_j(x,t)\nu_j(t)dt$$

Let the eigenvalues of \mathcal{L} be $0 < \mu_1 < \mu_2 < \cdots$ without counting the multiplicities and the eigenfunctions $\{\phi_{n,l}\}$, $l = 1, 2, \ldots, d_n$, are corresponding to the eigenvalue μ_n , where $d_n \leq D$ is the multiplicity of eigenvalue μ_n , then for each sample solution u_j , we may write

(4.2)
$$u_j(x,t) = \sum_{n=1}^{\infty} e^{-\mu_n t} \sum_{l=1}^{d_n} b_{j,l}^n \phi_{n,l}(x), \quad j = 1, 2, \dots, D$$

for some coefficients $\{b_{j,l}^n\}$. Consider an arbitrary initial condition $f(x) \in L^2(\Omega)$ that

(4.3)
$$f(x) = \sum_{n=1}^{\infty} \sum_{l=1}^{d_n} f_{n,l} \phi_{n,l}(x),$$

the solution to (1.1) at time $\tau > t_0$ will be

(4.4)
$$w(x,\tau) = \sum_{n=1}^{\infty} e^{-\mu_n \tau} \sum_{l=1}^{d_n} f_{n,l} \phi_{n,l}(x).$$

If the matrix $B_n = (b_{j,l}^n)_{jl} \in \mathbb{R}^{D \times d_n}$ is of full rank d_n for each $n \geq 1$, there exist p_j^n , $j = 1, 2, \ldots, D$ such that $f_{n,l} = \sum_{j=1}^D p_j^n b_{j,l}^n$, $l = 1, 2, \ldots, d_n$. It means there is a decomposition $f(x) = \sum_{j=1}^D f_j(x)$, where each f_j is

(4.5)
$$f_j(x) = \sum_{n=1}^{\infty} p_j^n \sum_{l=1}^{d_n} b_{j,l}^n \phi_{n,l}(x).$$

As a summary of above analysis, we have the following theorem as an analogue of Theorem 3.7 for eigenvalues with multiplicities.

Theorem 4.1. Suppose the function $g_i(x)$ satisfies that

(4.6)
$$g_j(x) = \sum_{n=1}^{\infty} \sum_{l=1}^{d_n} b_{jl}^n \phi_{n,l}(x), \quad j = 1, 2, \dots, D.$$

Denote B_n^{\dagger} as the Moore-Penrose inverse of B_n and assume $||B_n^{\dagger}|| \leq Le^{pn^{\alpha}}$, $\alpha \in [0,\beta)$, $n=1,2,\ldots$ Let $f \in L^2(\Omega)$ and denote $u_j(x,t)$, w(x,t) the solutions with respect to initial conditions $g_j(x)$ and f(x) respectively, then there exists an interpolation function $\nu_j(t;\tau,[t_0,t_1]) \in L^2[t_0,t_1]$ that

(4.7)
$$w(x,\tau) = \sum_{j=1}^{D} \int_{t_0}^{t_1} u_j(x,t) \nu_j(t;\tau) dt, \quad \tau > t_0.$$

Proof. Denote $\mathbf{p}^n = (p_1^n, \dots, p_D^n)$ and $\mathbf{f}^n = (f_{n,1}, \dots, f_{n,d_n})$, then $\mathbf{p}^n = B_n^{\dagger} \mathbf{f}^n$. Define $\hat{\phi}_{j,n}(x) = \sum_{l=1}^{d_n} b_{jl}^n \phi_{n,l}(x), n = 1, 2, \dots$ which form an orthogonal set for each $j = 1, 2, \dots, D$. We have

$$u_j(x,t) = \sum_{n=1}^{\infty} e^{-\mu_n t} \hat{\phi}_{j,n}(x), \quad w_j(x,t) = \sum_{n=1}^{\infty} e^{-\mu_n t} p_j^n \hat{\phi}_{j,n}(x), \quad w(x,t) = \sum_{j=1}^{D} w_j(x,t).$$

Since $||B_n^{\dagger}|| \leq Le^{pn^{\alpha}}$.

(4.8)
$$|p_j^n| \le ||\mathbf{p}^n|| \le Le^{pn^{\alpha}}||\mathbf{f}^n|| \le Le^{pn^{\alpha}}||f||_{L^2(\Omega)} \le Ce^{pn^{\alpha}}, \quad j = 1, 2, \dots, D,$$
 according to the Theorem 3.7, there exist $\nu_j \in L^2[t_0, t_1], \quad w_j(x, \tau) = \int_{t_0}^{t_1} u_j(x, t) \nu_j(t; \tau) dt.$

Remark 4.2. The above theorem requires finite multiplicities of eigenvalues to obtain the exact interpolation (4.7) which may not be true in general, for instance, $-\Delta$ in 2D unit square. However instead of producing an accurate representation, we usually only need to find an approximation. If the solution trajectories $\{u_i\}_{i=1}^D$ can capture the subspace spanned by the leading eigenfunctions up to a small tolerance, the approximation suffices for practical uses.

5. Application

5.1. Data driven model reduction. In the case that snapshots of a sample solution trajectory can be superposed to approximate any snapshot of an arbitrary solution, one can use a data driven approach for model reduction and approximation of new solution bypass explicit learning of the underlying PDE. For example, if the sample solution u(x,t) is observed on the time interval $[t_0,t_1]$, then in theory one can approximate any solution at a later time $\tau > t_0$ using certain superposition of the observed sample solution snapshots. In particular, if one can find a finite dimensional space V to which the sample solution trajectory is close,

$$(5.1) ||u(x,t) - P_V u(x,t)||_{L^2(\Omega)} \le \varepsilon ||u(x,0)||_{L^2(\Omega)}, \quad t \in [t_0, t_1],$$

where P_V is the projection operator onto V, then any solution $w(x,\tau), \tau > t_0$ is close to V as well since (5.2)

$$||w(x,\tau) - P_V w(x,\tau)||_{L^2(\Omega)} = \left\| \int_{t_0}^{t_1} u(x,t) \nu(t) dt - \int_{t_0}^{t_1} P_V u(x,t) \nu(t;\tau) dt \right\|_{L^2(\Omega)}$$

$$\leq \int_{t_0}^{t_1} ||u(x,t) - P_V u(x,t)) \nu(t;\tau)||_{L^2(\Omega)} dt$$

$$\leq \varepsilon ||u(x,0)||_{L^2(\Omega)} \int_{t_0}^{t_1} |\nu(t;\tau)| dt$$

$$\leq \varepsilon \sqrt{(t_1 - t_0)} ||\nu(\cdot;\tau)||_{L^2[t_0,t_1]} ||u(x,0)||_{L^2(\Omega)}.$$

However, fixing t_0 and t_1 and let $\tau \to t_0^+$, the norm $\|\nu(\cdot;\tau)\|_{L^2[t_0,t_1]}$ will increase rapidly according to Theorem 3.7. For $u_t = -\mathcal{L}u$, where \mathcal{L} is a self-adjoint elliptic operator, it has been shown [4] that given any $\varepsilon > 0$, for any solution trajectory u(x,t) on $[t_0,t_1]$, there exists a linear subspace $V \subset L^2(\Omega)$ of dimension $\dim(V) = \mathcal{O}(|\log \varepsilon|\log(t_1/t_0))$ such that (5.1) is satisfied.

To find a discrete approximation of the subspace V for a sample solution u(x,t), one can observe $u(x_i,\tau_j)$ on a space time grid, (x_i,τ_j) , with grid size $h,\Delta t$ in space and time respectively such that, for any j and $\forall t \in [\tau_j,\tau_{j+1}), \|u(\cdot,t) - I_t[u(\cdot,\tau_j),u(\cdot,\tau_{j+1})]\|_{L^2(\Omega)} = O(\Delta t^2) = O(\varepsilon)$ and $\|u(\cdot,\tau_j) - I_x[u(x_i,\tau_j)]\|_{L^2(\Omega)} = O(h^2) = O(\varepsilon)$, where I_t and I_x are linear interpolation operators in time and space respectively. Let $U_{ij} = u(x_i,\tau_j)$ denote the solution matrix whose singular value decomposition (SVD) is $U = P\Sigma Q^*$. V can be approximated by the finite dimensional linear space spanned by the leading left-singular vectors from columns of P. Once V is found, it can be used for model reduction and other applications. For example, an arbitrary solution can be approximated well by a linear combination of the basis of V. The coefficients can be determined by a few measurements, e.g., at a few locations or some integral quantities, of the new solution without knowing or solving the underlying PDE (see an example in 6.5).

5.2. Noisy data. In practice, the observed solution data $u(x_i, \tau_j)$ could have some measurement errors. Hence it is natural to ask if the subspace V is stable under such perturbations. For that reason, we assume the noisy sampled solution matrix

$$\tilde{U}_{ij} = \tilde{u}(x_i, \tau_j) = u(x_i, \tau_j) + e(x_i, \tau_j),$$

where $u(x_i, \tau_j)$ denotes the exact solution data and the random perturbations $e(x_i, \tau_j)$ are i.i.d mean-zero random variables with variation δ^2 . We approximate \tilde{V} from the corresponding singular vectors of \tilde{U} such that $\dim(\tilde{V}) = \dim(V) = v$. Suppose $U = P\Sigma Q^*$ and $\tilde{U} = \tilde{P}\tilde{\Sigma}\tilde{Q}^*$, the perturbation matrix $E = \tilde{U} - U$, then from the Wedin's theorem [13],

(5.3)
$$\|\sin\Theta(V,\tilde{V})\|_F \le \frac{\sqrt{2v}}{\ell} \|E\|_F,$$

where $\Theta(V, \tilde{V})$ denotes the canonical angles between V and \tilde{V} , the left-hand side measures the difference between the projection mappings onto V and \tilde{V} , respectively, see [10] and references therein for detailed discussions. Let σ_i and $\tilde{\sigma}_i$ be the i-th singular value of U and \tilde{U} , respectively, the parameter

$$\ell := \min \{ \min_{1 \leq i \leq v, 1 \leq j \leq N-v} |\sigma_i - \tilde{\sigma}_{v+j}|, \min_{1 \leq i \leq v} \sigma_i \}.$$

Particularly, the Bernoulli random perturbation has been studied in [11] and Gaussian random perturbation is considered in [12]. For $u_t = -\mathcal{L}u$, where $-\mathcal{L}$ is a self-adjoint elliptic operator, given any $\varepsilon > 0$ and any solution trajectory u(x,t) on $[t_0,t_1]$, there exists a linear subspace $V \subset L^2(\Omega)$ of dimension $\dim(V) = \mathcal{O}(|\log \varepsilon| \log(t_1/t_0))$ such that (5.1) is satisfied [4]. This means $\sigma_n = O(e^{-n})$ which makes ℓ decay very fast with respect to v and the computation of V is sensitive to noise.

When the resolution in time is sufficiently fine, due to the linearity, instead of taking the singular value decomposition directly on the sample solution data $\tilde{u}(x_i, \tau_j)$, we may first regularize the data by averaging on a time window $[\tau_j, \tau_j + S\Delta t]$

(5.4)
$$v(x_i, \tau_j) = \frac{1}{S+1} \sum_{s=0}^{S} \tilde{u}(x_i, \tau_{j+s}) = \frac{1}{S+1} \sum_{s=0}^{S} u(x_i, \tau_{j+s}) + \tilde{e}_{i,j},$$

where the variation of $\tilde{e}_{i,j}$ is $\operatorname{Var}\left[\frac{1}{S+1}\sum_{s=0}^{S}e(x_i,\tau_{j+s})\right]=\frac{\delta^2}{S+1}$. This process is equivalent to sampling the averaged data

(5.5)
$$v(x,t) = \sum_{n=1}^{\infty} e^{-\mu_n t} \left(\frac{1}{(S+1)} \frac{1 - e^{-(S+1)\mu_n \Delta t}}{1 - e^{-\mu_n \Delta t}} \right) c_n \phi_n(x) + \tilde{e}(x,t),$$

where $\tilde{e}(x,t)$ is a random variable for each (x,t) with variance $\frac{\delta^2}{S+1}$. Therefore as $\Delta t \to 0$ is sufficiently fine, one can fix r > 0 and take $S = r\Delta t^{-1} \to \infty$ to reduce the noise variations, then we perform the singular value decomposition on the modified solution (5.5) which has a smaller error bound in (5.3). The above modified sampled solution trajectory becomes

(5.6)
$$\lim_{S \to \infty} v(x,t) \stackrel{P}{=} \sum_{n=1}^{\infty} e^{-\mu_n t} \left(\frac{1 - e^{-r\mu_n}}{r\mu_n} \right) c_n \phi_n(x),$$

which averages the u(x,t) in a window (t,t+r), the coefficient $\frac{1-e^{-r\mu_n}}{r\mu_n}c_n$ still satisfies the condition in Theorem 3.7, although the factor $\frac{1}{\mu_n}$ will make the interpolation function $\|\tilde{\nu}(t)\|_{L^2[t_0,t_1]}$ larger than using the true u(x,t) data. As a summary, if the solution data are finely sampled and contain mean-zero noises, we can simply perform a local average on finely sampled solution and extract the subspace from the smoothed solution.

6. Numerical experiments

The following experiments are computed with MATLAB 2016a. The experiment source code is hosted at GitHub 1 .

¹https://github.com/lowrank/pde-subspacehttps://github.com/lowrank/pde-subspace

6.1. **Experiment 1.** In this experiment, we take the elliptic operator $\mathcal{L}u = -u_{xx}$ on [0, 1] with Dirichlet boundary condition. The eigenvalue $\mu_n = \pi^2 n^2$, $n = 1, 2, \ldots$, which satisfies the Assumption 3.1 with $\beta = 2$ and Assumption 3.2. We take the sample solution as

(6.1)
$$u(x,t) = \sum_{n=1}^{\infty} \frac{(-1)^n}{n^2} e^{-n^2 \pi^2 t} \sin n\pi x$$

on the time span $t \in [10^{-6}, 1]$ and the subspace V is computed by selecting the leading left-singular vectors above the singular value threshold 10^{-12} and $\dim(V) = 27$ in this example. It should be pointed out that the singular vectors are not necessarily close to eigenfunctions, see Fig 1.

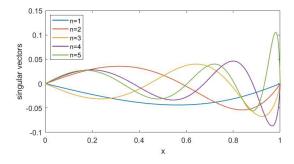


FIGURE 1. The first five singular vectors of sampled solution data.

We then validate Theorem 3.7 with solutions corresponding to eigenmodes

(6.2)
$$w_n(x,\tau) = e^{-n^2 \pi^2 \tau} \sin n\pi x, \quad 1 \le n \le 8$$

at time $\tau = 0.1$. If τ is very close to $t_0 = 10^{-6}$, the norm of $\|\nu\|_2$ will be very large by Theorem 3.7 which leads to a relatively large constant in the approximation error (5.2). For each n, we evaluate the relative error by

(6.3)
$$\eta = \frac{\|w_n(x,\tau) - P_V w_n(x,\tau)\|}{\|w_n(x,\tau)\|}.$$

We summarize the experiment result in the following Tab 1, where the eigenmodes $w_n(x,\tau)$ can be approximated with quite small relative errors by the subspace V.

Table 1. Relative error of approximation by subspace V.

n	1	2	3	4
η	2.10×10^{-16}	5.09×10^{-16}	6.91×10^{-16}	1.35×10^{-16}
n	5	6	7	8
η	4.75×10^{-16}	3.76×10^{-16}	2.81×10^{-15}	3.66×10^{-13}

6.2. Experiment 2. In this experiment, we take the operator $\mathcal{L}u = -u_{xx} + u$ with periodic boundary condition on [0,1], then the multiplicity of each eigenvalue $\mu_n = n^2 + 1$ is two except for n = 0 which corresponds to the constant eigenfunction. In this case, according to the Theorem 4.1, we will need two sample solution trajectories with linearly independent coefficients on the time span $t \in [10^{-6}, 1]$:

(6.4)
$$u_1(x,t) = \sum_{n=1}^{\infty} \frac{(-1)^n}{n^2} e^{-(n^2 \pi^2 + 1)t} \sin n\pi x,$$
$$u_2(x,t) = e^{-t} + \sum_{n=1}^{\infty} \frac{(-1)^n}{n^2} e^{-(n^2 \pi^2 + 1)t} \cos n\pi x.$$

Similar to the previous experiment, the solution subspace V is union of the singular vectors from singular value decomposition of u_1 and u_2 truncated at the threshold of 10^{-12} and $\dim(V) = 52$. We validate Theorem 4.1 with eigenmodes

(6.5)
$$w_n(x,\tau) = e^{-(n^2\pi^2 + 1)\tau} e^{in\pi x}, \quad 0 \le n \le 8$$

at time $\tau = 0.1$. The relative errors are computed by (6.3) and summarized in Tab 2.

Table 2. Relative error of approximation by subspace V.

n	1	2	3	4
η	5.82×10^{-16}	8.55×10^{-16}	9.28×10^{-16}	2.98×10^{-16}
n	5	6	7	8
η	6.56×10^{-16}	4.64×10^{-16}	4.19×10^{-15}	5.54×10^{-13}

6.3. Experiment 3. In contrast to one dimensional case, we demonstrate in 2D that the subspace spanned by a single solution trajectory of second order parabolic equation's cannot be used to approximate all solutions well. For simplicity, we take the elliptic operator

$$\mathcal{L}u = -\Delta u$$

on a rectangular domain $[0,1] \times [0,2^{-1/4}]$ with Dirichlet boundary condition. The eigenvalues are $\lambda_{m,n} = \pi^2(m^2 + \sqrt{2}n^2) \in \pi^2\mathbb{Z}[\sqrt{2}], m \geq 1, n \geq 1$. It can be shown the eigenvalues are simple and grow with rate $\beta = n/d = 1$ which violates the Assumption 3.1. On the other hand, if $m_1^2 + \sqrt{2}n_1^2 < m_2^2 + \sqrt{2}n_2^2$, then the difference

(6.7)
$$\left| m_1^2 + \sqrt{2}n_1^2 - (m_2^2 + \sqrt{2}n_2^2) \right| \ge \frac{c}{\sqrt{2}(m_2^2 + \sqrt{2}n_2^2)}$$

for certain c > 0. The proof is found in Lemma A.1. That is to say the eigenvalue gap $\mu_{n+1} - \mu_n \ge \frac{c\pi^2}{\sqrt{2}\mu_{n+1}} = \Theta(n^{-1})$, hence satisfies the Assumption 3.2.

We take the sample solution on the time span $t \in [10^{-6}, 1]$ in the following expansion form,

(6.8)
$$u(x,y,t) = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \frac{1}{m^2 n^2} e^{-\pi^2 (m^2 + \sqrt{2}n^2)t} \sin(m\pi x) \sin(2^{1/4}n\pi y)$$
$$= \sum_{m=1}^{\infty} \frac{1}{m^2} e^{-\pi^2 m^2 t} \sin(m\pi x) \sum_{n=1}^{\infty} \frac{1}{n^2} e^{-\sqrt{2}\pi^2 n^2 t} \sin(2^{1/4}n\pi y).$$

Similarly, we formulate the data matrix by evaluating the solution uniformly in both space and time, the subspace V consists of the leading left-singular vectors above the singular value threshold 10^{-12} and $\dim(V) = 34$. The subspace is validated against the first 8 eigenmodes

(6.9)
$$w_{m,n}(x,y,\tau) = e^{-\pi^2(m^2 + \sqrt{2}n^2)\tau} \sin(m\pi x) \sin(2^{1/4}n\pi y)$$

at time $\tau = 0.1$. The relative errors are summarized in the Tab 3. It can be seen that the subspace spanned by the sample solution trajectory cannot even approximate the first few eigenmodes well.

Table 3. Relative error of approximation by subspace V.

(m,n)	(1,1)	(2,1)	(1,2)	(2,2)
η	4.02×10^{-14}	5.20×10^{-14}	9.14×10^{-15}	2.03×10^{-12}
(m,n)	(3,1)	(1,3)	(3, 2)	(2,3)
η	5.47×10^{-12}	1.84×10^{-8}	2.93×10^{-6}	1.05×10^{-4}

6.4. **Experiment 4.** In two dimension, we consider the 4th order elliptic operator $\mathcal{L} = \partial_x^{(4)} + \partial_y^{(4)}$ on the rectangular domain $\Omega = [0,1] \times [0,2^{-1/8}]$ with boundary conditions: u = 0 on $\partial\Omega$, $u_{xx} = 0$ on $\{x = 0, x = 1\}$ and $u_{yy} = 0$ on $\{y = 0, y = 2^{-1/8}\}$. The eigenvalues are $\lambda_{m,n} = \pi^4(m^4 + \sqrt{2}n^4)$, $m,n \in \mathbb{Z}_+$. The eigenvalues satisfies both assumptions 3.1 and 3.2 by deriving an analogue of the inequality (6.7).

The sampled solution on the time span $t \in [10^{-6}, 1]$ is the following form

(6.10)
$$u(x,y,t) = \sum_{m=1}^{\infty} \frac{1}{m^2} e^{-\pi^4 m^4 t} \sin(m\pi x) \sum_{n=1}^{\infty} \frac{1}{n^2} e^{-\sqrt{2}\pi^4 n^4 t} \sin(2^{1/8}n\pi y).$$

The subspace V consists of the left-singular vectors above the singular value threshold 10^{-12} and $\dim(V) = 23$. We validate the subspace against the first 8 eigenmodes

(6.11)
$$w_{m,n}(x,y,\tau) = e^{-\pi^4(m^4 + \sqrt{2}n^4)\tau} \sin(m\pi x) \sin(2^{1/8}n\pi y)$$

at $\tau = 0.1$. The relative errors are summarized in the Tab 4. Unlike the second order case, the eigenmodes (6.11) are well resolved by V.

Table 4. Relative error of approximation to eigenmodes by subspace V.

(m,n)	(1,1)	(2,1)	(1, 2)	(2,2)
η	3.46×10^{-15}	3.37×10^{-14}	3.31×10^{-14}	2.35×10^{-14}
(m,n)	(3,1)	(3, 2)	(1,3)	(2,3)
η	3.61×10^{-14}	1.62×10^{-12}	1.26×10^{-12}	3.66×10^{-11}

6.5. Experiment 5. One useful application for data driven model reduction is to predict a PDE solution from limited observed data, e.g., by a few local sensors. Suppose that a small linear space V has been found from a sample solution. One can then approximate a new solution by a linear combination of basis of V, where the coefficients can be determined, e.g., least square fitting, by a few measurements of the new solution. Let us take the subspace V from the experiment in 6.1. If we observed certain solution at time τ

(6.12)
$$\tilde{u}(x,\tau) = \sum_{n=1}^{\infty} \omega_n e^{-\pi^2 n^2 \tau} \sin(\pi nx)$$

at locations $z_i \in [0,1]$, i = 1, 2, ..., 50 (uniformly distributed), we can use the subspace V, whose orthonormal basis is available, to find out the solution by a direct least square fitting at $\{u(z_i, \tau)\}_{i=1}^{50}$. In this experiment, we set

(6.13)
$$\omega_n = \begin{cases} \text{i.i.d } \mathcal{U}(-1,1) \text{ random variables,} & n = 1, 2, \dots, 10^3, \\ 0, & \text{otherwise.} \end{cases}$$

For each value of τ , we sample 10^3 realizations of \tilde{u} and compute the approximated solutions from V. The recorded average relative errors are shown in Fig 2. When τ decreases, the constant in the estimate (5.2) grows very fast, thus we can see the error is quite large for small value of τ .

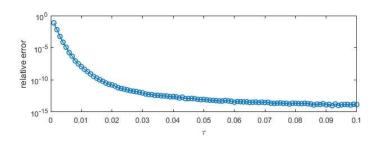


FIGURE 2. Average relative L^2 error for noiseless data with respect to different τ .

6.6. Experiment 6. We use the same setting of Experiment 5 but with noises. Suppose the equally spaced discretization of time $\{t_j\}_{j\geq 1}$ with time step Δt varying from 10^{-8} to 10^{-3} . Spatially the discretization $\{x_i\}_{i\geq 1}$ is equally spaced that $\Delta x =$

 10^{-3} . The discretized sample solution data is

(6.14)
$$\tilde{u}(x_i, t_j) = \sum_{n=1}^{\infty} \frac{(-1)^n}{n^2} e^{-n^2 \pi^2 t_j} \sin n\pi x_i + e(x_i, t_j),$$

where $e(x_i, t_j)$ is i.i.d uniformly sampled in $[-10^{-3}, 10^{-3}]$. The averaging is taken on a window size of $S = \lceil 0.1/\Delta t \rceil$, see Sec 5.2. We perform the same experiment as in Experiment 5 on \tilde{u} . The resulting relative errors are recorded in Fig 6.6. The random noises in the sampled solution introduce quite large errors in the reconstructed solution compared to the noiseless Experiment 5 since the parameter $\ell \approx 10^{-12}$ in (5.3) amplifies the error greatly.

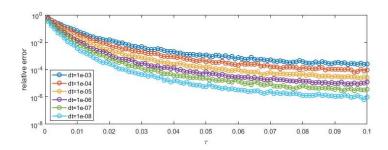


FIGURE 3. Average relative L^2 error for noise data with respect to different τ and Δt .

7. Conclusion

In this work, time evolution equation is used as an example to show if the space spanned by all snapshots of a single (or multiple) solution(s) is as rich as the space spanned by the snapshots of all solutions. It is shown that when smoothing of the differential operator dominates the diversity in spatial dimensions, i.e., the order of the PDE is larger than the space dimension, one can use superposition of snapshots of a single (or multiple) solution(s) to construct an arbitrary solution. In practice, this means that if one can find a linear space a single (or multiple) sampled solution(s) is (are) close to, that space can be used to approximate all solutions. Moreover, the learned solution space can be used as a general regularization for PDE learning [4] which complements the limitations of local matching.

APPENDIX A. AUXILIARY LEMMAS

Lemma A.1. Suppose $m_1, n_1, m_2, n_2 \in \mathbb{Z}_+ \cup \{0\}$ and if $m_1^2 + \sqrt{2}n_1^2 < m_2^2 + \sqrt{2}n_2^2$, then

(A.1)
$$\left| (m_2^2 + \sqrt{2}n_2^2) - (m_1^2 + \sqrt{2}n_1^2) \right| > \min \left(\frac{c}{n_2^2}, \frac{c}{\sqrt{2}(m_2^2)} \right).$$

where $c \in (0,1)$ is a constant. In particular, we have

(A.2)
$$\left| (m_2^2 + \sqrt{2}n_2^2) - (m_1^2 + \sqrt{2}n_1^2) \right| > \frac{c}{\sqrt{2}(m_2^2 + \sqrt{2}n_2^2)}.$$

Proof. We consider 3 cases. (1). $m_2 \ge m_1$ and $n_2 \ge n_1$, since both equal signs cannot hold simultaneously, we obtain the trivial bound

(A.3)
$$\left| (m_2^2 + \sqrt{2}n_2^2) - (m_1^2 + \sqrt{2}n_1^2) \right| \ge 1.$$

(2). $m_1 \ge m_2$, $n_2 > n_1$. According to the Liouville's theorem, for any $p, q \in \mathbb{Z}_+$, there exists a constant c > 0 that

$$(A.4) |q\sqrt{2} - p| > \frac{c}{q}.$$

therefore

(A.5)
$$\left| m_2^2 + \sqrt{2}n_2^2 - (m_1^2 + \sqrt{2}n_1^2) \right| = \left| (m_1^2 - m_2^2) - \sqrt{2}(n_2^2 - n_1^2) \right|$$

$$> \frac{c}{|n_2^2 - n_1^2|} \ge \frac{c}{n_2^2}.$$

(3). $m_1 < m_2, n_2 \le n_1$. Use the same argument as above,

(A.6)
$$\left| m_2^2 + \sqrt{2}n_2^2 - (m_1^2 + \sqrt{2}n_1^2) \right| = \frac{1}{\sqrt{2}} \left| 2(n_1^2 - n_2^2) - \sqrt{2}(m_2^2 - m_1^2) \right|$$

$$> \frac{c}{\sqrt{2}|m_2^2 - m_1^2|} \ge \frac{c}{\sqrt{2}(m_2^2)}.$$

By taking the minimum of the three cases, we obtain the desired result.

APPENDIX B. PROOF OF LEMMA 3.3

Proof. Let N(x) be the counting function for the eigenvalues $\{\mu_k\}_{k>1}$ that

(B.1)
$$N(x) = \begin{cases} 0, & 0 \le x < \mu_1, \\ k, & \lambda_k \le x < \lambda_{k+1}. \end{cases}$$

Then from the estimate in assumption A1, we find

(B.2)
$$0 \le M^{-1/\beta} x^{1/\beta} + \delta(x) - N(x) \le 1,$$

where $\delta(x) = o(x^{(1-\sigma)/\beta})$ as $x \to \infty$. Then use Riemann-Stieljes integral,

(B.3)
$$\log \left(\prod_{j \ge 1} \left(1 + \frac{\mu_n}{\mu_j} \right) \right) = \sum_{j \ge 1} \log \left(1 + \frac{\mu_n}{\mu_j} \right)$$
$$= \int_{\mu_1^-}^{\infty} \log \left(1 + \frac{\mu_n}{x} \right) dN(x) = \mu_n \int_{\mu_1}^{\infty} \frac{N(x) dx}{x(x + \mu_n)}$$

The error bound of (B.2) implies there exists a constant C > 0 that

(B.4)
$$\left| \mu_n \int_{\mu_1}^{\infty} \frac{N(x)dx}{x(x+\mu_n)} - M^{-1/\beta} \mu_n \int_{\mu_1}^{\infty} \frac{x^{1/\beta}dx}{u(u+\mu_n)} \right| \le C\mu_n \int_{\mu_1}^{\infty} \frac{x^{(1-\sigma)/\beta}dx}{x(x+\mu_n)}.$$

The integral on right-hand side is

$$C\mu_n \int_{\mu_1}^{\infty} \frac{x^{(1-\sigma)/\beta} dx}{x(x+\mu_n)} = C\mu_n^{(1-\sigma)/\beta} \int_{\mu_1/\mu_n}^{\infty} \frac{dy}{y^{1-(1-\sigma)/\beta}(y+1)}$$

$$= \begin{cases} C\mu_n^{(1-\sigma)/\beta} \left(\int_0^{\infty} \frac{dy}{y^{1-(1-\sigma)/\beta}(y+1)} + o(1) \right), & 0 < \sigma < 1 \\ C\log \frac{\mu_n + \mu_1}{\mu_1} & \sigma = 1 \end{cases}$$

$$= o(\mu_n^{1/\beta}).$$

By a similar argument, we derive

(B.6)
$$M^{-1/\beta}\mu_n \int_{\mu_1}^{\infty} \frac{x^{1/\beta} dx}{x(x+\mu_n)} = M^{-1/\beta}\mu_n^{1/\beta} \left(\int_0^{\infty} \frac{dy}{y^{1-1/\beta}(y+1)} + o(1) \right).$$

Then we absorb (B.5) into (B.6) and immediately obtain the first product in (3.5) is

(B.7)
$$\prod_{j>1} \left(1 + \frac{\mu_n}{\mu_j} \right) = \exp\left(M^{-1/\beta} \mu_n^{1/\beta} (\zeta_{0,\beta} + o(1)) \right), \quad n \to \infty.$$

where $\zeta_{a,b}$ denotes the following integral,

(B.8)
$$\zeta_{a,b} := \int_0^\infty \frac{dy}{y^{1-a/b}(y+1)}, \quad 0 \le a < b.$$

Now we estimate the second product.

(B.9)

$$\left| \log \left| \prod_{j \neq n} \left(1 - \frac{\mu_n}{\mu_j} \right) \right| = \sum_{j < n} \log \left(\frac{\mu_n}{\mu_j} - 1 \right) + \sum_{j > n} \log \left(1 - \frac{\mu_n}{\mu_j} \right) \\
= \int_{\mu_1^-}^{\mu_{n-1}} \log \left(\frac{\mu_n}{x} - 1 \right) dN_n(x) + \int_{\mu_{n+1}^-}^{\infty} \log \left(1 - \frac{\mu_n}{x} \right) dN_n(x).$$

where $N_n(x)$ is the counting function without the point at $x = \mu_n$ that

(B.10)
$$N_n(x) = \begin{cases} N(x), & x < \mu_n \\ N(x) - 1, & x \ge \mu_n. \end{cases}$$

Therefore the previous estimate is modified to

(B.11)
$$0 \le M^{-1/\beta} x^{1/\beta} + \delta(x) - N_n(x) \le 2$$

and use integration by parts, the integrals of (B.9) equals to

(B.12)
$$\left[N_n(x) \log \left(\frac{\mu_n}{x} - 1 \right) \right] \Big|_{\mu_1^-}^{\mu_{n-1}} + \left[N_n(x) \log \left(1 - \frac{\mu_n}{x} \right) \right] \Big|_{\mu_{n+1}^-}^{\infty}$$

$$+ \mu_n \int_{\mu_1}^{\mu_{n-1}} \frac{N_n(x) dx}{x(\mu_n - x)} + \mu_n \int_{\mu_{n+1}}^{\infty} \frac{N_n(x) dx}{x(\mu_n - x)} dx$$

For the boundary terms, it is simple to see

(B.13)
$$\lim_{x \to \infty} N_n(x) \log(1 - \frac{\mu_n}{x}) = 0,$$

therefore the boundary terms become

(B.14)
$$(n-1) \left[\log \left(\frac{\mu_n}{\mu_{n-1}} - 1 \right) - \log \left(1 - \frac{\mu_n}{\mu_{n+1}} \right) \right]$$

$$= (n-1) \left[\log \left(\frac{\mu_n - \mu_{n-1}}{\mu_{n+1} - \mu_n} \right) + \log \left(\frac{\mu_{n+1}}{\mu_{n-1}} \right) \right].$$

Using the assumption A2,

(B.15)
$$\frac{\mu_{n} - \mu_{n-1}}{\mu_{n+1} - \mu_{n}} = M \frac{n^{\beta} - (n-1)^{\beta} + o(n^{\beta-\sigma})}{\mu_{n+1} - \mu_{n}} \le \theta^{-1} M(\beta n^{s+\beta-1} + o(n^{s+\beta-\sigma})),$$

$$\frac{\mu_{n+1}}{\mu_{n-1}} = \frac{M(n+1)^{\beta} (1 + o((n+1)^{-\sigma}))}{M(n-1)^{\beta} (1 + o((n-1)^{-\sigma}))} = 1 + o(n^{-\sigma}).$$

Therefore the boundary terms are bounded by

(B.16)
$$(n-1)((s+\beta-\sigma)\log n + O(1)) = M^{-1/\beta} \frac{s+\beta-\sigma}{\beta} \mu_n^{1/\beta} \log \mu_n (1+o(1)).$$

The integral terms in (B.12) can be estimated by (B.17)

$$\left| \mu_n \int_{\mu_1}^{\mu_{n-1}} \frac{N_n(x)dx}{x(\mu_n - x)} - \mu_n M^{-1/\beta} \int_{\mu_1}^{\mu_{n-1}} \frac{x^{1/\beta}dx}{x(\mu_n - x)} \right| \le C\mu_n \int_{\mu_1}^{\mu_{n-1}} \frac{x^{(1-\sigma)/\beta}dx}{x(\mu_n - x)}$$

$$\left| \mu_n \int_{\mu_{n+1}}^{\infty} \frac{N_n(x)dx}{x(\mu_n - x)} - \mu_n M^{-1/\beta} \int_{\mu_{n+1}}^{\infty} \frac{x^{1/\beta}dx}{x(\mu_n - x)} \right| \le C\mu_n \int_{\mu_{n+1}}^{\infty} \frac{x^{(1-\sigma)/\beta}dx}{x(x-\mu_n)}$$

The right-hand sides are bounded by

$$C\mu_n \int_{\mu_1}^{\mu_{n-1}} \frac{x^{(1-\sigma)/\beta} dx}{x(\mu_n - x)} = C\mu_n^{(1-\sigma)/\beta} \int_{\mu_1/\mu_n}^{\mu_{n-1}/\mu_n} \frac{dy}{y^{1-(1-\sigma)/\beta}(1 - y)}$$

$$\leq C_1 \mu_n^{(1-\sigma)/\beta} \left(\log \left(\frac{\mu_n}{\mu_n - \mu_{n-1}} \right) + O(1) \right)$$

$$\leq C_1 \mu_n^{(1-\sigma)/\beta} \left(\log \mu_n + O(1) \right)$$

and

(B.19)
$$C\mu_n \int_{\mu_{n+1}}^{\infty} \frac{x^{(1-\sigma)/\beta} dx}{x(x-\mu_n)} = C\mu_n^{(1-\sigma)/\beta} \int_{\mu_{n+1}/\mu_n}^{\infty} \frac{dy}{y^{1-(1-\sigma)/\beta}(y-1)}$$
$$= C_1 \mu_n^{(1-\sigma)/\beta} \left(\log\left(\frac{\mu_{n+1} - \mu_n}{\mu_n}\right) + O(1) \right)$$
$$= C_1 \mu_n^{(1-\sigma)/\beta} O(1).$$

where C_1 is a positive constant independent of n. At last, we estimate the following integral

(B.20)
$$\mu_n M^{-1/\beta} \int_{\mu_1}^{\mu_{n-1}} \frac{x^{1/\beta} dx}{x(\mu_n - x)} + \mu_n M^{-1/\beta} \int_{\mu_{n+1}}^{\infty} \frac{x^{1/\beta} dx}{x(\mu_n - x)}$$

$$= \mu_n^{1/\beta} M^{-1/\beta} \left(\int_{\mu_1/\mu_n}^{\mu_{n-1}/\mu_n} \frac{dy}{y^{1-1/\beta} (1 - y)} + \int_{\mu_{n+1}/\mu_n}^{\infty} \frac{dy}{y^{1-1/\beta} (1 - y)} \right)$$

In order to provide an estimate for (B.20), we consider two cases. The first case is $1 - \frac{\mu_{n-1}}{\mu_n} \le \frac{\mu_{n+1}}{\mu_n} - 1$, then the integral

$$\begin{split} &\int_{\mu_{1}/\mu_{n}}^{\mu_{n-1}/\mu_{n}} \frac{dy}{y^{1-1/\beta}(1-y)} + \int_{\mu_{n+1}/\mu_{n}}^{\infty} \frac{dy}{y^{1-1/\beta}(1-y)} \\ &= \int_{\mu_{1}/\mu_{n}}^{\mu_{n-1}/\mu_{n}} \frac{dy}{y^{1-1/\beta}(1-y)} + \int_{2-\mu_{n-1}/\mu_{n}}^{\infty} \frac{dy}{y^{1-1/\beta}(1-y)} - \int_{2-\mu_{n-1}/\mu_{n}}^{\mu_{n+1}/\mu_{n}} \frac{dy}{y^{1-1/\beta}(1-y)} \\ &= \text{p.v.} \int_{0}^{\infty} \frac{dy}{y^{1-1/\beta}(1-y)} + o(1) - \int_{2-\mu_{n-1}/\mu_{n}}^{\mu_{n+1}/\mu_{n}} \frac{dy}{y^{1-1/\beta}(1-y)} \\ &\geq \text{p.v.} \int_{0}^{\infty} \frac{dy}{y^{1-1/\beta}(1-y)} + o(1), \end{split}$$

The second case is $1 - \frac{\mu_{n-1}}{\mu_n} > \frac{\mu_{n+1}}{\mu_n} - 1$, then

$$\int_{\mu_{1}/\mu_{n}}^{\mu_{n-1}/\mu_{n}} \frac{dy}{y^{1-1/\beta}(1-y)} + \int_{\mu_{n+1}/\mu_{n}}^{\infty} \frac{dy}{y^{1-1/\beta}(1-y)}
= \int_{\mu_{1}/\mu_{n}}^{2-\mu_{n+1}/\mu_{n}} \frac{dy}{y^{1-1/\beta}(1-y)} + \int_{\mu_{n+1}/\mu_{n}}^{\infty} \frac{dy}{y^{1-1/\beta}(1-y)} - \int_{\mu_{n-1}/\mu_{n}}^{2-\mu_{n+1}/\mu_{n}} \frac{dy}{y^{1-1/\beta}(1-y)}
\geq \text{p.v.} \int_{0}^{\infty} \frac{dy}{y^{1-1/\beta}(1-y)} + o(1) - C_{2} \left| \log \frac{\mu_{n+1} - \mu_{n}}{\mu_{n} - \mu_{n-1}} \right|
\geq -C_{3}(\log \mu_{n} + C_{4}),$$

where C_2, C_3, C_4 are positive constants independent of n. Combine the previous estimates (B.16), (B.18), (B.19) and (B.22), we obtain the following inequality

(B.23)
$$\log \left| \prod_{j \neq n} \left(1 - \frac{\mu_n}{\mu_j} \right) \right| \ge -K_0 \mu_n^{1/\beta} M^{-1/\beta} (\log \mu_n + K_1)$$

for certain $K_0, K_1 > 0$.

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