



ARTICLE TYPE

BeatNet+: Real-Time Rhythm Analysis for Diverse Music Audio

XXX XXX*, and XXX XXX

Abstract

This paper presents a comprehensive study on real-time music rhythm analysis, covering joint beat and downbeat tracking for diverse kinds of music signals. We introduce BeatNet+, a two-stage approach to real-time rhythm analysis built on a previous state-of-the-art method named BeatNet. The main innovation of the proposed method is the auxiliary training strategy that helps the neural network model to learn a representation invariant to the amount of percussive components in the music. Together with other architectural improvements, this strategy significantly improves the model performance for generic music. Another innovation is on the adaptation strategies that help develop real-time rhythm analysis models for challenging music scenarios including isolated singing voices and non-percussive music. Two adaptation strategies are proposed and experimented with different neural architectures and training schemes. Comprehensive experiments and comparisons with multiple baselines are conducted, and results show that BeatNet+ achieves superior beat tracking and downbeat tracking F1 scores for generic music, isolated singing voices and non-percussive audio, with competitive latency and computational complexity. Finally, we release beat and downbeat annotations for two datasets that are designed for other tasks, and revised annotations of three existing datasets. We also plan to release the code repository and pre-trained models on GitHub.

Keywords: Real-time beat tracking, downbeat tracking, rhythm analysis, singing voices, non-percussive music, BeatNet, BeatNet+

1. Introduction

Music can be regarded as one of the most intricate and diverse art forms in the world. It is created through the incorporation of various sounds that are arranged in a meaningful manner to produce a unique composition. One of the key elements of music is rhythm, which refers to the sequential pattern of sounds and silences that occur over time. Rhythm is crucial in music as it forms the fundamental basis upon which a piece is constructed. In recent years, there has been an increasing interest in developing real-time music rhythm analysis systems Heydari and Duan (2021).

Accurate and robust real-time music rhythm analysis holds the potential to **advance** the music industry, enabling innovative applications. It can serve as a fundamental component for a variety of use cases, including automatic music generation, processing and analysis. With the recent advancements in virtual and augmented reality, there is a growing demand

for real-time music processing and analysis across various situations. This need has also gained prominence due to its role in empowering the creation of immersive music-based interactive experiences. These experiences, **include but are not limited to** real-time music visualization (Bain, 2008), dancing robots (Bi et al., 2018), **DJing and live remixing and sampling performance** (Cliff, 2000), live video editing and synchronization (Davis and Agrawala, 2018), dynamic lighting systems, and music-driven interactive video games (Bégel et al., 2018), offer users the chance to engage with music on the fly.

Developing real-time music rhythm analysis systems involves addressing three key challenges: The first challenge is on maintaining high accuracy while not accessing future input data as offline models do. The second challenge is on achieving low latency, especially on low-powered devices. While the first two challenges are easy to understand, we argue that the third challenge is on the generalization to various kinds of music audio. While state-of-the-art rhythm analysis

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41 research has shown promising performance on music
 42 recordings that contain strong percussive components
 43 (e.g., drums, rhythmic guitar, piano) (Heydari et al.,
 44 2021), there are scenarios where the music audio lacks
 45 such components. For example, real-time rhythm anal-
 46 ysis of isolated singing voices plays a crucial role in
 47 understanding and processing vocal performances and
 48 it enables applications such as accompaniment gen-
 49 eration on the fly and live music remixing (Heydari
 50 et al., 2023). As another example, real-time genera-
 51 tion of drum tracks requires rhythm analysis of non-
 52 percussive music tracks and can enable collaborative
 53 music making between human musicians and artificial
 54 intelligence (AI) agents.

55 In this work, we propose BeatNet+ for real-time
 56 rhythm analysis for diverse kinds of music audio. Simi-
 57 lar to BeatNet (Heydari et al., 2021), BeatNet+ pro-
 58 cesses the music audio magnitude spectrum with a
 59 Convolutional Recurrent Neural Network (CRNN) to
 60 compute beat and downbeat activations in each audio
 61 frame. The activations are then post-processed by a
 62 two-level cascade Monte Carlo particle filter. The key
 63 innovations of BeatNet+ are on an auxiliary training
 64 strategy that improves the system performance over
 65 state-of-the-art rhythm tracking methods on generic
 66 music, as well as adaptation strategies that improve
 67 the generalization ability to less percussive music such
 68 as isolated singing voices and music without drums,
 69 which are novel rhythm analysis settings.

70 Specifically, the auxiliary training strategy lever-
 71 ages a parallel regularization branch that has an iden-
 72 tical structure without weight sharing with the main
 73 branch (i.e., used for inference) during training. The
 74 main branch is fed with full music mixtures while the
 75 auxiliary branch is fed with the full music less drum
 76 tracks (referred to as *non-percussive* versions) of the
 77 same pieces. In addition to the Cross Entropy (CE)
 78 losses for each branch, a Mean Squared Error (MSE)
 79 loss is computed between the latent embeddings of the
 80 two branches to regularize the representation learning
 81 of the main branch.

82 Regarding the adaptation strategies for BeatNet+
 83 to work with less percussive music, we propose two
 84 techniques termed *Auxiliary-Freezing (AF)* and *Guided*
 85 *Fine-tuning (GF)*. The AF approach (Figure 2) again
 86 adopts a two-branch auxiliary training strategy simi-
 87 lar to the one mentioned above. Differently, the main
 88 branch (left) is now trained on the target music type
 89 (i.e., less percussive music) while the auxiliary branch
 90 (right) is frozen as the pre-trained *main branch of*
 91 *the BeatNet+ which is trained* for full music mixtures.
 92 The GF technique (Figure 3) employs a single-branch
 93 model initialized with the *pre-trained main branch of*
 94 *the BeatNet+ model*. Subsequently, this model under-
 95 *goes fine-tuning on input music pieces, starting with*
 96 *full music mixtures (aligned with the original data type*
 97 *of the pre-trained model)*, which are gradually adapted

98 to match the target music type. For instance, if the tar-
 99 get is isolated singing voices, non-singing parts of the
 100 music input are progressively removed during training
 101 iterations. We perform experiments on two types of
 102 less percussive music types to demonstrate the effec-
 103 tiveness of the adaptation strategies: *Isolated singing*
 104 *voices* and *non-percussive music*. Rhythm tracking for
 105 both settings is novel and could enable novel applica-
 106 tions such as real-time drum track generation.

107 Finally, we release beat and downbeat annotations
 108 of MUSDB18 (Rafii et al., 2017) and URSing (Li et al.,
 109 2021) datasets, which were originally designed for
 110 other MIR tasks, enabling them to be utilized for music
 111 rhythm analysis applications. Also, we correct mistakes
 112 in the rhythm annotations of three pre-existing mu-
 113 sic rhythm analysis datasets including RWC jazz, RWC
 114 pop, and RWC royalty-free (Goto et al., 2002; Goto,
 115 2004). The source code of the BeatNet+, adaptation
 116 models and rhythmic annotations of MUSDB and URS-
 117 ing will be online¹.

2. Related Work

118 Existing work on rhythm analysis can be reviewed
 119 along different dimensions. In this section, we provide
 120 a review along the dimensions that are related to the
 121 proposed work.

2.1 Two-Stage Approach

122 The majority of rhythm analysis methods (e.g., beat
 123 tracking, downbeat tracking) adopt a two-stage ap-
 124 proach. In the first stage, a salience function (also
 125 called likelihood function, detection function, or acti-
 126 vation strength) is computed from the input audio sig-
 127 nal to represent the salience of the target event (e.g., a
 128 beat) in different time frames. In the second stage, an
 129 inference process (also called post-processing) is em-
 130 ployed to make binary decisions on the presence of the
 131 target event in each audio frame based on the salience
 132 function. Different techniques have been proposed in
 133 each of these stages, and we will review them in the
 134 following.

2.1.1 Salience Calculation Stage

135 There are generally two paradigms in computing the
 136 salience function. The first paradigm is rule-based and
 137 uses hand-crafted functions to indicate the presence of
 138 important rhythmic elements in music, such as onsets
 139 and beats (Mottaghi et al., 2017; Chiu et al., 2023).
 140 Such function often describes the “novelty” of the cur-
 141 rent audio frame compared to the previous frame(s)
 142 in terms of energy (Schloss, 1985) and spectral con-
 143 tent (Masri, 1996). These hand-crafted functions are
 144 generally fast to compute and robust to music styles.
 145 However, their detection accuracy is limited compared
 146 to data-driven methods in the next paragraph.

1[[]We open-source the following upon the paper acceptance:
 Codes: <https://github.com/XXXXXX/XXXXXX>
 Annotations: <https://github.com/XXXXXX/XXXXXX>

150 The second paradigm focuses on machine learning
 151 techniques, where models are trained to establish
 152 the relationship between low-level acoustic features
 153 and annotations of rhythmic elements (Holzapfel
 154 et al., 2012; Gkiokas et al., 2012; Böck and Schedl,
 155 2011; Böck et al., 2016). Deep learning-based meth-
 156 ods have gained significant attention due to their
 157 exceptional performance in rhythm analysis. These
 158 models typically require supervision and are trained
 159 on large datasets with labeled rhythmic patterns,
 160 making them highly accurate in recognizing com-
 161 plex rhythmic patterns. They leverage neural net-
 162 works to extract “activation strength” for every time
 163 frame. Several neural network structures are uti-
 164 lized for music rhythm analysis tasks such as con-
 165 volutional networks (Gkiokas and Katsouros, 2017),
 166 cepstroid invariant networks (Elowsson, 2016), re-
 167 current networks (Eyben et al., 2013), transform-
 168 ers (Heydari and Duan, 2022), temporal convolu-
 169 tional networks (Davies and Böck, 2019), and autoen-
 170 coders (Greenlees, 2020).

171 Recently, self-supervised learning (SSL) models
 172 have gained popularity as they can be trained on
 173 massive amounts of unlabeled data. Desblancs
 174 et al. (2023) proposed ZeroNS that leverages a self-
 175 supervised pre-processing block for their beat track-
 176 ing model. Similar to our proposed BeatNet+ model,
 177 ZeroNS contains two branches and leverages differ-
 178 ent music stems in training. However, there are sev-
 179 eral fundamental differences between the two models.
 180 BeatNet+ is a supervised model with a latent match-
 181 ing loss, whereas ZeroNS is self-supervised and lacks a
 182 loss-matching regularization term. BeatNet+ focuses
 183 on the causal joint beat and downbeat tracking, while
 184 ZeroNS serves as a non-causal model designed only for
 185 beat tracking. In terms of structure, BeatNet+ utilizes
 186 CRNN networks, while ZeroNS only incorporates con-
 187 volutional blocks in its pipeline. SSL representations
 188 have also been used in rhythm analysis of challeng-
 189 ing music inputs such as isolated singing voice (Hey-
 190 dari and Duan, 2022). Such representations, however,
 191 can be difficult to use in real-time applications due to
 192 causal and low latency requirements.

193 It is worth mentioning that each of the men-
 194 tioned methods can operate in either the time do-
 195 main, e.g., (Steinmetz and Reiss, 2021; Heydari
 196 and Duan, 2022) or frequency domain, e.g., (Meier
 197 et al., 2021; Böck and Davies, 2020; Chiu et al.,
 198 2023), or combined, e.g., (Morais et al., 2023).
 199 Time-domain techniques operate on the audio wave-
 200 form, while frequency-domain techniques operate on a
 201 time-frequency representation computed from Fourier,
 202 constant-Q or other transforms. They provide ex-
 203 plicit information about the signal’s frequency com-
 204 ponents and are known for their robustness to noise
 205 when compared with time-domain techniques (Zheng-
 206 qing and Jian-hua, 2005). Spectral approaches face

207 a time-frequency resolution trade-off where extending
 208 the time window captures lower frequencies benefi-
 209 cial for rhythm analysis but reduces time resolution,
 210 and vice versa. To tackle the time-frequency reso-
 211 lution tradeoff issue, some works, e.g., (Böck et al.,
 212 2014), employ multi-resolution embeddings, which in-
 213 volve concatenating spectral features calculated based
 214 on different window lengths.

2.1.2 Decision Stage

215 Depending on whether future audio frames are con-
 216 sidered in making the prediction at the current frame,
 217 the decision stage can be categorized as *offline* and
 218 *online* methods. *Offline methods*, such as *comb fil-
 219 ters* (Scheirer, 1998), *dynamic programming* (Ellis,
 220 2007), and *dynamic Bayesian networks* (Böck et al.,
 221 2014), improve prediction coherence but are unsuit-
 222 able for real-time use. A sliding window frame-
 223 work allows offline methods to work in online scenar-
 224 ios (Davies et al., 2005), processing only signals within
 225 the window. However, this ignores past signals outside
 226 the window, affecting coherence. Overlapping win-
 227 dows can cause computational overload as well.

228 In online (especially real-time) scenarios, various
 229 inherently causal inference methods are utilized, in-
 230 cluding the forward algorithm (Federgruen and Tzur,
 231 1991), Kalman filtering (Shiu and Kuo, 2007), par-
 232 ticle filtering (Hainsworth and Macleod, 2004; Hey-
 233 dari and Duan, 2021; Heydari et al., 2023) and jump-
 234 reward inference (Heydari et al., 2022). In particular,
 235 particle filtering uses particles to represent and evolve
 236 the posterior distribution of rhythmic states like beat,
 237 downbeat, and non-beat over time. Hainsworth and
 238 Macleod (2004) applied it to tempo detection and Hey-
 239 dari et al. (2021) applied it to joint beat, downbeat,
 240 and time signature tracking.

241 Particle filtering faces challenges in capturing ex-
 242 tended temporal dependencies like time signature
 243 tracking due to its Markovian nature, relying only
 244 on current state predictions. Heydari et al. (2023)
 245 proposed dynamic particle filtering, enhancing infer-
 246 ence by incorporating historical and salience infor-
 247 mation, albeit with increased computational cost. Par-
 248 ticle filtering also requires numerous particles for ex-
 249 tensive state spaces, crucial for detailed time granular-
 250 ity and broad tempo ranges in rhythm analysis, lead-
 251 ing to higher computational overhead. Heydari et al.
 252 (2022) introduced “jump-reward inference,” a semi-
 253 Markovian model operating in a 1-dimensional state
 254 space, significantly cutting computation time, albeit
 255 with a performance drop in higher-level music analysis
 256 tasks such as downbeat tracking.

2.2 Real-Time Systems

258 In this subsection, we briefly review a few real-time
 259 beat and downbeat tracking systems. IBT (Oliveira
 260 et al., 2010) is a signal processing based multi-agent
 261 system for real-time beat tracking. It initializes a set of

263 agents with various hypotheses. Each agent carries a
 264 hypothesis concerning the rate and placement of musical
 265 beats and the model dynamically chooses the best
 266 agent based on music onsets.

267 In the realm of deep learning based methods, Böck
 268 et al. (2014) employed an RNN to compute activations
 269 and apply the forward algorithm (Federgruen and
 270 Tzur, 1991) for inferring beats in a causal setting. Hey-
 271 dari et al. (2021) proposed BeatNet, a real-time sys-
 272 tem for joint beat, downbeat, and meter tracking. It
 273 employs a fully causal CRNN structure with a 1D con-
 274 volutional layer to produce three activations for beat,
 275 downbeat, and non-beat. It uses an efficient two-level
 276 particle filtering for inference. In their follow-up work,
 277 Heydari et al. (2022) utilized BeatNet activations and
 278 presented a so-called “jump-back reward” strategy to
 279 speed up the particle filtering process as reviewed in
 280 the previous subsection.

281 Chang and Su (2024) proposed an online beat and
 282 downbeat tracking system named BEAST based on the
 283 streaming Transformer Tsunoo et al. (2019). Through
 284 the incorporation of contextual block processing in
 285 the Transformer encoder and relative positional en-
 286 coding in the attention layer, BEAST achieves signifi-
 287 cant improvements over existing state-of-the-art mod-
 288 els. It uses the forward algorithm (Federgruen and
 289 Tzur, 1991) as the inference stage.

290 2.3 Rhythm Analysis for Isolated Singing Voices

291 In order to address the isolated singing voice rhythm
 292 analysis task, Heydari and Duan (2022) proposed
 293 a model that leverages pre-trained self-supervised
 294 speech models such as WavLM (Chen et al., 2022) and
 295 Distilhubert (Chang et al., 2022) and built some lin-
 296 ear transformers (Katharopoulos et al., 2020) on top
 297 of them to jointly extract the beats of singing voices in
 298 an offline fashion. This study highlights the substantial
 299 performance improvement achieved by utilizing pre-
 300 trained speech models and transformers. Nonethe-
 301 less, their computational heaviness poses challenges
 302 for real-time and low-resource applications, especially
 303 in scenarios with limited computational power, such
 304 as in-device use cases. SingNet (Heydari et al., 2023)
 305 pioneered real-time singing voice joint beat and down-
 306 beat, and meter tracking. It utilizes a slightly larger
 307 CRNN model compared to BeatNet for calculating ac-
 308 tivation functions. Recognizing the irregular and noisy
 309 activations delivered by singing voices, SingNet in-
 310 troduces dynamic particle filtering, a novel inference
 311 module that incorporates offline estimation and acti-
 312 vation saliences into the online inference process.

313 2.4 Rhythm Analysis for Non-Percussive Music

314 In addition to isolated singing voices, there are other
 315 types of music audio that are less percussive, e.g., mu-
 316 sic without drums. Real-time music rhythm analysis
 317 for these kinds of music is also challenging but can be
 318 very useful in many applications such as the automatic

319 generation of drum tracks. Wu et al. (2022) developed
 320 an offline drum accompaniment system based on an
 321 offline drum-aware beat tracking method (Chiu et al.,
 322 2021). Online rhythm analysis of non-percussive mu-
 323 sic, however, is limited to a few traditional signal pro-
 324 cessing approaches such as (Goto, 2001; Goto and Mu-
 325 raoka, 1999) that only track beats but not downbeats
 326 or meter.

3. Methodology

327 In this section, we present a novel two-stage approach
 328 named BeatNet+ to real-time joint beat, downbeat and
 329 meter tracking for diverse kinds of music inputs. The
 330 first stage estimates beat and downbeat saliences from
 331 audio frames, while the second stage makes decisions
 332 using particle filtering. Additionally, we elaborate on
 333 adapting the BeatNet+ model for rhythm analysis of
 334 more challenging data types.

3.1 Stage 1: Beat and Downbeat Salience Estimation

336 This section describes the proposed neural network
 337 model and training strategies for robust computation
 338 of beat and downbeat saliences from diverse kinds of
 339 music inputs.

3.1.1 Audio Feature Representation

341 We utilize Short-Time Fourier Transform (STFT) to
 342 compute a log-magnitude spectrogram as the input fea-
 343 ture representation. The window length is set to 80 ms
 344 with a Hann window. The window hop size, i.e., the
 345 model’s theoretical latency, is set to 20 ms. The fre-
 346 quency range is between 30 Hz and 17,000 Hz with
 347 288 bins.

3.1.2 Neural Architecture and Training Strategy

349 BeatNet+ (Figure 1) features two branches where both
 350 the main branch (left) and the auxiliary branch (right)
 351 are used in training while for inference, only the main
 352 branch is utilized. Both branches employ a convolu-
 353 tional recurrent neural network (CRNN) structure sim-
 354 ilar to BeatNet (Heydari et al., 2021), where the convolu-
 355 tional block is identical to that of BeatNet but the re-
 356 current block is expanded from two layers to four lay-
 357 ers based on preliminary empirical studies. This deeper
 358 design is reasonable, as BeatNet+ is expected to han-
 359 dle diverse music inputs, including isolated singing
 360 voices and less-percussive music with complex rhyth-
 361 mic structures. Each recurrent layer contains 150 long
 362 short-term memory (LSTM) cells, the same as in Beat-
 363 Net. It is worth mentioning that in our pilot study, we
 364 explored various alterations to the neural architecture,
 365 such as incorporating batch normalization, linear lay-
 366 ers, Rectified Linear Unit (ReLU) activations, and leaky
 367 ReLU activations. However, these modifications did not
 368 yield significant performance improvements.

369 To increase the robustness to music with various
 370 levels of percussive components, we use an auxiliary
 371 branch (the right branch of Figure 1) to train Beat-

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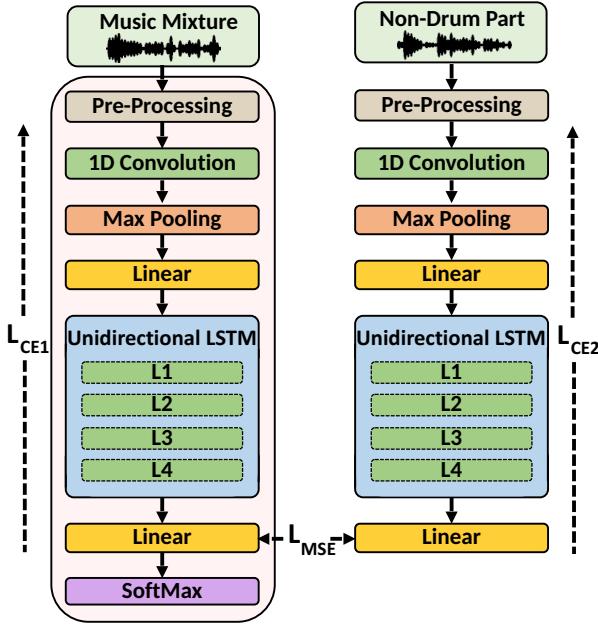


Figure 1: Neural structure of *BeatNet+* for general music rhythm analysis. Both the main (left) and auxiliary (right) branches are initialized randomly and trained jointly, but only the main branch is utilized for inference.

3.1.3 *Adaptation for More Challenging Music Inputs* 398
 To address the real-time rhythm analysis of challenging 399 inputs such as isolated singing voices and other less- 400 percussive music, we propose two adaptation strate- 401 gies named as *Auxiliary Freezing (AF)* and *Guided Fine- 402 tuning (GF)*, respectively. Here we take the isolated 403 singing voice scenario as an example, but the proposed 404 adaptation strategies can be applied to other scenarios, 405 e.g., non-percussive music, as well. In the AF approach 406 (shown in Figure 2), we adopt a similar two-branch 407 auxiliary training approach to that in Section 3.1.2. In 408 this case, the *auxiliary branch* (right) is initialized with 409 the frozen weights from the pre-trained main branch 410 of *BeatNet+* (i.e., *left branch* in Figure 1) taking full 411 music mixtures as inputs, while the *main branch* (left), 412 is trained from scratch on isolated singing voices of the 413 corresponding music mixtures. MSE loss is imposed 414 between the latent representations of the two branches 415 in addition to the cross entropy loss of the right branch. 416 After this adaptation, the *main branch (left)* is used 417 for rhythm analysis of isolated singing voices. Note 418 that this approach bears similarity to teacher-student 419 model distillation methods e.g., Kim and Rush (2016), 420 wherein the student model is trained to replicate sim- 421 ilar latents as the frozen teacher model. However, the 422 key distinction lies in the fact that commonly used 423 teacher-student models try to perform model distilla- 424

373 Net+. The auxiliary branch is identical to the main 374 branch, except that it takes a different *type of* input 375 during training and *it does not include the SoftMax* 376 *layer, which is only used during inference in the main* 377 *branch*. Note that since cross-entropy loss with logits 378 *is being used, applying SoftMax is unnecessary during* 379 *training.*

Training of *BeatNet+* takes three losses as in Equation (1):

$$L_{total} = L_{CE1} + L_{CE2} + \lambda L_{MSE}. \quad (1)$$

380 The main branch is trained on full music mixtures with 381 a cross-entropy loss denoted as L_{CE1} . The auxiliary 382 branch is trained on the non-percussive parts of the 383 *same* music mixtures with another cross-entropy loss 384 denoted as L_{CE2} . Additionally, we introduce a Mean 385 Squared Error (MSE) loss, L_{MSE} , between intermediate 386 representations of the two branches. This can be 387 viewed as a training regularization to encourage sim- 388 ilarity between the latent representations of the two 389 branches, given that their outputs, i.e., *their rhythm in- 390 formation*, are expected to be identical. Based on our 391 pilot studies, Mean Squared Error (MSE) is found to 392 be more suitable than other losses like Mean Absolute 393 Error (MAE) or Huber loss for this regularization. The 394 constant weight parameter λ controls the strength of 395 the regularization. A similar latent matching strategy 396 has been used before to enhance a talking face genera- 397 tion model's robustness to noise (Eskimez et al., 2019).

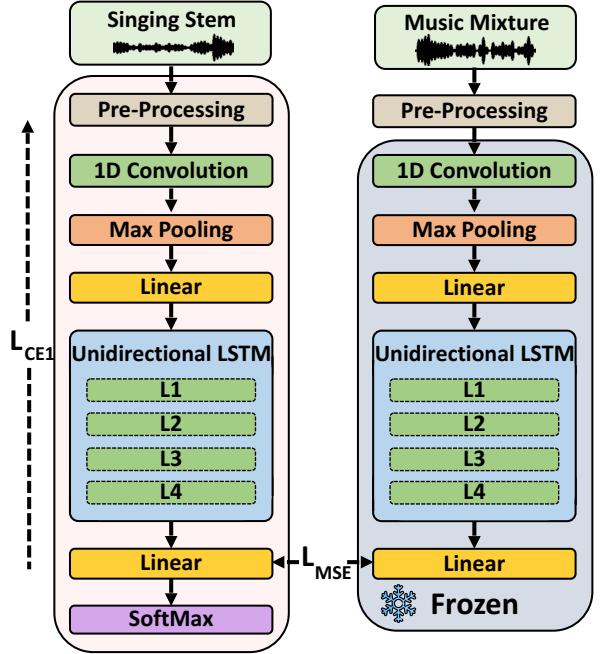


Figure 2: Neural structure of *Auxiliary-Freezing (AF)* 425 adaptation approach for singing voice rhythm 426 analysis. The main branch (left) is initialized ran- 427 domly and trained for real-time inference, while 428 the auxiliary branch (right) is initialized with the 429 pre-trained *BeatNet+* main branch weights and re- 430 mains frozen during training.

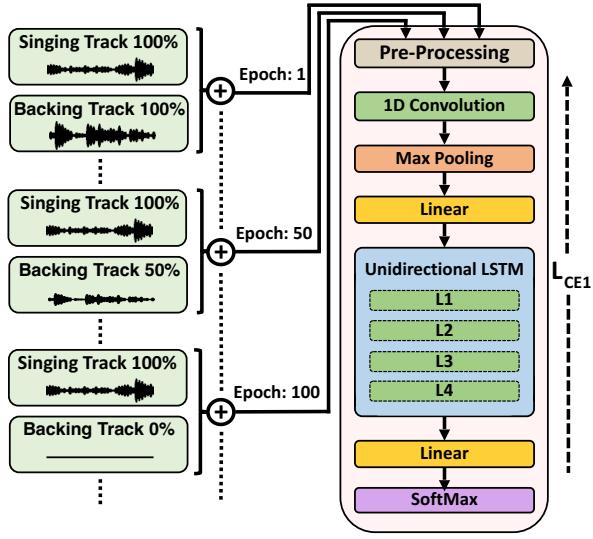


Figure 3: Illustration of the *Guided Fine-tuning (GF)* approach for singing voice rhythm analysis. The model is initialized with the pre-trained BeatNet+ main branch weights and fine-tuned using music mixtures with backing music gradually removed over training epochs.

3.2.1 *State Space, Transition and Observation Models* 455
 The state space, transition, and observation models 456
 mirror those of BeatNet (Heydari et al., 2021). We 457
 implement the discrete 2D state space proposed in 458
 (Krebs et al., 2015) and adapt BeatNet’s cascade approach. In 459
 this approach, instead of merging multiple beat state 460
 spaces into a bar state space, two separate state spaces 461
 are employed, one for beat and tempo tracking and the 462
 other for downbeat and meter tracking, organized 463
 hierarchically. The first space comprises tempo and 464
 beat phase as the two dimensions; Adjacent states with the 465
 same tempo correspond to adjacent time frames of 466
 audio. The second space comprises meter (represented 467
 as the number of beats per bar) and downbeat phase 468
 as the two dimensions; Adjacent states with the same 469
 meter correspond to adjacent beats in time. Transition 470
 models permit tempo and meter changes to update at 471
 beat and downbeat positions, respectively. Observation 472
 models calculate beat and downbeat likelihoods based 473
 on salience estimated by the neural network. 474

3.2.2 *Causal Inference*

Monte Carlo particle filtering is a top choice for real- 475
 time inference due to two key advantages. Firstly, 476
 it does not rely on future data, unlike popular maxi- 477
 mum a posteriori (MAP) algorithms such as the Viterbi 478
 algorithm and smoothing algorithms like forward- 479
 backward. Secondly, unlike many inference algorithms 480
 such as Kalman filtering which require strong distri- 481
 bution type assumptions, it is a general and non- 482
 parametric approach, capable of decoding any un- 483
 known distribution among causal filtering methods. 484
 Some previous works (Heydari et al., 2021; Heydari 485
 and Duan, 2021) demonstrated its superiority com- 486
 pared to other inference models. 487

Particle filtering is a two-step inference process 488
 that encompasses the *predict/motion* step and the *up- 489
 date/correction* step. In the motion step, particle po- 490
 sitions are updated based on predicted trajectories, 491
 while the correction step involves adjusting particles 492
 and assigning weights based on observed data compati- 493
 bility. Given the latent state ϕ_k and observation y_k at 494
 frame k , assuming that the current position poste- 495
 rior $p(\phi_k|y_{1:k})$ is estimated, the “predict-update” 496
 procedure computes the next frame’s position poste- 497
 rior $p(\phi_{k+1}|y_{1:k+1})$. Equation (2) details the motion step for 498
 one-step-ahead prediction by applying the state transi- 499
 tion model $p(\phi_{k+1}|\phi_k)$ into the current frame poste- 500
 rior,

$$p(\phi_{k+1}|y_{1:k}) = \sum_{\phi_k} p(\phi_{k+1}|\phi_k) p(\phi_k|y_{1:k}). \quad (2)$$

Equation (3) describes the correction step by incor- 501
 porating the observation likelihood $p(y_{k+1}|\phi_{k+1})$ into 502
 the one-step-ahead prediction to estimate the next step 503
 posterior,

$$p(\phi_{k+1}|y_{1:k+1}) = \frac{1}{Z_{k+1}} p(y_{k+1}|\phi_{k+1}) p(\phi_{k+1}|y_{1:k}). \quad (3)$$

425 tution, i.e., to attain similar results with smaller networks 426 on the same data, while our model’s objective is to 427 achieve similar results with identical networks on dif- 428 ferent but related data.

429 In the Guided Fine-tuning (GF) approach, we com- 430 mence by initializing a single-branch model with the 431 weights and biases of the main branch of BeatNet+ 432 that is pre-trained on full music mixtures, i.e., the left 433 branch of Figure 1. Subsequently, we fine-tune the 434 model for isolated singing voices by gradually reducing 435 the intensity of the accompanying music during train- 436 ing. In each epoch, a percentage of the accompanying 437 music is deducted, with a linear decay factor denoted 438 as γ . After a number of epochs, the strength of accom- 439 panying music in the training data diminishes to 440 zero. Figure 2 illustrates this adaptation approach for 441 isolated singing voice music with $\gamma = 0.01$.

442 As previously mentioned, both adaptation strate- 443 gies can be applied to address different types of less- 444 percussive music input. For instance, in Figures 2 and 445 3, substituting the singing stem with complete musical 446 mixtures excluding drum stems, enables the models to 447 be trained specifically for non-percussive music.

3.2 Stage 2: Decision

449 Since Cascade Monte Carlo particle filtering demon- 450 strated superior performance for online rhythm analy- 451 sis tasks among the proposed methods (Heydari et al., 452 2021, 2023), we use it as the decision-making block for 453 all proposed methods and scenarios. In this section, we 454 provide a brief description of the method we used.

489 By combining these motion and correction steps iter-
 490 atively, particle filtering refines the estimation of the sys-
 491 tem’s state, making it a powerful technique for tracking
 492 and inference in dynamic environments.

4. Experiments

493 In this section, we discuss the training specifics of the
 494 proposed models. We also describe the details of our
 495 comparison methods, utilized datasets (existing and
 496 annotated), and the evaluation metrics for each task.
 497 Finally, we report the experimental results for all of the
 498 models and compare them with state-of-the-art meth-
 499 ods for each task. Note that all experiments with the
 500 proposed methods employ the same inference method
 501 i.e., the particle filtering approach proposed in Beat-
 502 Net (Heydari et al., 2021).

504 4.1 Datasets

505 **To increase data diversity**, we use multiple music au-
 506 dio datasets with beat and downbeat annotations,
 507 as shown in Table 1. Among these datasets, Ball-
 508 room (Gouyon et al., 2006; Krebs et al., 2013),
 509 GTZAN (Marchand and Peeters, 2015; Tzanetakis and
 510 Cook, 2002), Hainsworth (Hainsworth and Macleod,
 511 2004), Rock Corpus (De Clercq and Temperley, 2011),
 512 and RWC Jazz, Pop and Royalty-free datasets (Goto
 513 et al., 2002; Goto, 2004) already come with beat and
 514 downbeat annotations. However, some downbeat an-
 515 notations of RWC Jazz, Pop and Royalty-free datasets
 516 are not accurate, and we revise them manually. In ad-
 517 dition, MUSDB18 (Rafii et al., 2017) and URSing (Li
 518 et al., 2021) are multi-track singing datasets without
 519 beat or downbeat annotations, and we annotate them
 520 using BeatNet (Heydari et al., 2021) followed by man-
 521 ual corrections.

522 Following the previous works, we employ the whole
 523 GTZAN dataset as the test set, given that it is one of the
 524 largest and most genre-inclusive datasets for our tasks.
 525 Importantly, none of the reported models have been
 526 exposed to this dataset during their training phase, en-
 527 suring a fair and unbiased assessment. The rest of the
 528 datasets outlined in Table 1 are utilized for training
 529 and validation purposes.

530 It is noted that to obtain the audio stems of the
 531 datasets for different tasks except the ones that include
 532 separate stems i.e., MUSDB18 and URSing, we util-
 533 ize Demucs (Défossez, 2021), a top-performing open-
 534 source music source separation model. It separates
 535 each piece of music into four tracks: bass, drums, vo-
 536 cals and others.

537 For the isolated singing rhythm analysis task, the
 538 availability of singing stems is essential. Yet, in the
 539 datasets we use, many pieces do not have singing, and
 540 some have extended segments with only instrumen-
 541 tal music and no vocals. To address this challenge,
 542 we introduce a preprocessing stage designed to el-
 543 iminate vocal-less pieces and extended segments with-
 544 out singing. This is achieved by implementing energy-

545 based vocal Root Mean Square (RMS) thresholding on
 546 separated singing tracks. As a consequence, datasets
 547 such as RWC-Jazz (Goto et al., 2002; Goto, 2004) were
 548 entirely excluded from the data pool for the singing
 549 voice rhythm analysis task. Furthermore, some vocal
 550 tracks containing extended silent intervals are split into
 551 shorter vocal segments.

4.2 Evaluation Metrics

552 The reported metrics comprise beat and downbeat F1
 553 scores, system latency, and real-time Factor (RTF). Fol-
 554 lowing the literature, F1 scores are reported with a tol-
 555 erance window of 70 ms. Latency is defined as the hop
 556 size of the Short-Time Fourier Transform (STFT) for
 557 processed data. RTF is another important metric for
 558 real-time models and refers to the speed or responsive-
 559 ness with which a model can process and generate out-
 560 puts in real-time. It is the averaged ratio between the
 561 total processing time and the total audio length across
 562 the whole test set. Note that the reported RTFs are
 563 measured on a Windows machine with an AMD Ryzen
 564 9 3900X CPU and 3.80 GHz clock frequency.

565 Previous work (Heydari et al., 2023) used 200 ms
 566 as the tolerance for singing voice beat and downbeat
 567 tracking. This was based on their observation that hu-
 568 man tolerance to beat and downbeat timing deviations
 569 tends to be more lenient for less percussive music com-
 570 pared to music with strong percussions. Therefore, we
 571 also report F1 scores with a tolerance of 200 ms for
 572 singing voice and non-percussive music datasets in ad-
 573 dition to the standard 70 ms tolerance.

4.3 Comparison Methods

575 To assess the effectiveness of the auxiliary training
 576 strategy in Section 3.1.2, we trained two models: **Beat-**
 577 **Net+** is the proposed model with auxiliary training
 578 using two branches, and **BeatNet+ (Solo)** trains the
 579 main branch without the auxiliary branch, i.e., only
 580 L_{CE1} is used in Equation (1).

581 To evaluate BeatNet+ model on real-time rhythm
 582 analysis for generic music, we compare it with five
 583 baseline models. 1) **BeatNet** (Heydari et al., 2021)

Dataset	#Pieces	#Vocals	Labels
Ballroom	699	452	Original
GTZAN	999	741	Original
Hainsworth	220	154	Original
Rock Corpus	200	315	Original
MUSDB18	150	263	Added
URSing	65	106	Added
RWC jazz	50	0	Revised
RWC pop	100	188	Revised
RWC Royalty-free	15	29	Revised

584 **Table 1: Datasets used in our experiments.** GTZAN
 585 is used for evaluation and the others are used for
 586 training and validation.

585 employs a CRNN structure and proposes efficient particle filtering for joint beat, downbeat, and meter tracking. 2) **Novel 1D** (Heydari et al., 2022) utilizes Beat-
 586 Net activations and proposes the jump-back reward
 587 strategy, a semi-Markov inference method, to reduce
 588 computation. 3) **IBT** (Oliveira et al., 2010) is a signal
 589 processing based method that uses onset strength
 590 to select an agent with the most correct beat position
 591 hypothesis out of multiple agents. 4) **Böck FF** Böck
 592 et al. (2014) utilizes an RNN and a forward algorithm
 593 for beat tracking. 5) **BEAST** (Chang and Su, 2024)
 594 employs a streaming Transformer and a forward algorithm
 595 for joint beat and downbeat tracking, achieving
 596 the best performance over existing state-of-the-art
 597 models on the GTZAN benchmark. Among the reported
 598 methods, IBT and Böck FF only perform beat
 599 tracking and do not provide downbeat results.

600 It is also important to mention that certain prior
 601 studies, such as Beast (Chang and Su, 2024), present
 602 their results by incorporating multiple hop-size look-
 603 ahead steps in addition to their real-time online perfor-
 604 mance. While these look-ahead steps enhance the per-
 605 formance of rhythm analysis systems, they introduce
 606 significant delays and make the models non-causal. To
 607 ensure a fair and consistent comparison among online
 608 models, we only compare the fully online performance
 609 of all models.

610 To better put online music rhythm analysis methods
 611 in context, we also compare with two state-of-the-
 612 art offline rhythm analysis models. They include 1)
 613 **Transformers** (Zhao et al., 2022) model that uses a
 614 transformer encoder for estimating the activations and
 615 dynamic Bayesian Networks (DBN) for decisions, and
 616 2) **SpecTNT-TCN** (Hung et al., 2022) that leverages
 617 a combination of Temporal Convolutional Networks
 618 (TCN) and SpecTNT (Lu et al., 2021), which integrates
 619 spectral and temporal information, to calculate activa-
 620 tions and a DBN block for decisions.

621 For the two challenging scenarios, isolated singing
 622 voices and non-percussive music, we evaluate the two
 623 proposed adaptation methods. **AF** represents the first
 624 adaptation approach illustrated in Figure 2, where the
 625 auxiliary branch (right) is initialized with the frozen
 626 weights of the BeatNet+ generic model, and the main
 627 branch (left) undergoes training on the particular mu-
 628 sic arrangement **and is used for inference**. **GF** rep-
 629 presents the second adaptation approach illustrated in
 630 Figure 3, involving fine-tuning a pre-trained model for
 631 specific tasks by adaptation of the input data over time.

632 To assess the effectiveness of the adaptation ap-
 633 proaches, we also present results for the same mod-
 634 els trained from scratch for the specific tasks, with-
 635 out leveraging the adaptation techniques. These mod-
 636 els are referred to as **AF-scratch** and **GF-scratch**, re-
 637 spectively. In particular, **AF-scratch** uses the auxil-
 638 iary branch structure and training data, but trained
 639 from scratch without initializing the auxiliary branch

640 **weights with the frozen weights of the pre-trained**
 641 **BeatNet+ main branch.** **GF-scratch** utilizes GF single
 642 branch structure, **trained from the scratch and** without
 643 guided fine-tuning.

644 For singing voice rhythm analysis, we compare with
 645 **SingNet** (Heydari et al., 2023), the current state of
 646 the art for this task. For non-percussive music rhythm
 647 analysis, no prior models are available. Thus, we com-
 648 pare with the state-of-the-art real-time rhythm analy-
 649 sis method, **BeatNet** (Heydari et al., 2021), when is
 650 trained exclusively on non-percussive music pieces.

4.4 Training Details

651 This section covers the training details of the BeatNet+
 652 models for generic music rhythm analysis as well as
 653 the “auxiliary-freezing” and “guided fine-tuning” adap-
 654 tation techniques for challenging scenarios.

655 All proposed models are trained using the Adam op-
 656 timizer with a constant learning rate of 5×10^{-4} and a
 657 batch size of 40. All models employ a cross-entropy
 658 loss **with logits**, whose weights are set to 200 for down-
 659 beats, 60 for beats, and 1 for non-beats, accounting for
 660 their average occurrence rates across total training au-
 661 dio frames. The **feature matching** MSE loss weight for
 662 models with auxiliary training is set to $\lambda = 200$. Train-
 663 ing batches comprise randomly selected 15-second ex-
 664 cerpts from the training audio files.

665 For the BeatNet+ and BeatNet+ (Solo), **AF-scratch**
 666 and **GF-scratch**, all weights and biases are randomly
 667 initialized. In contrast, the AF model only initializes
 668 its main branch randomly, while its auxiliary branch is
 669 initialized as the pre-trained main branch of BeatNet+.
 670 Similarly, the GF model is also initialized as the pre-
 671 trained main branch of BeatNet+.

672 Note that for all **external** comparison methods,
 673 their pre-trained models are utilized. However, for
 674 non-percussive music rhythm analysis, the benchmark
 675 BeatNet model is trained on non-percussive audio with
 676 the training specifics of the original BeatNet model.

4.5 Results and Discussions

677 In this section, we present our evaluation results for
 678 various scenarios on the GTZAN dataset. We report
 679 the performance of the proposed model and adaptation
 680 techniques for generic music, isolated singing voices,
 681 and non-percussive music rhythm analysis.

4.5.1 Results on Generic Music

683 Table 2 compares the performance of online rhythm
 684 analysis methods as well as two offline methods for
 685 generic music. We can see that the proposed BeatNet+
 686 outperforms all the other online methods on both beat
 687 tracking and downbeat tracking F1 scores, while main-
 688 taining competitive latency and RTF. Regarding com-
 689 putational complexity, the Novel 1D model achieves
 690 the lowest RTF, thanks to its utilization of an excep-
 691 tionally lightweight inference approach. The F1 score
 692 improvement from BeatNet+ (Solo) to BeatNet+, es-
 693 pecially in the downbeat tracking task, is significant.
 694 The GF-scratch model achieves the best F1 score in
 695 the downbeat tracking task, while the AF-scratch model
 696 achieves the best F1 score in the beat tracking task.

Method	Metrics (Performance on Full Mixtures)			
	Beat F1↑ (70ms)	Downbeat F1↑ (70ms)	Latency ↓ (ms)	RTF ↓
<i>Online Models</i>				
BeatNet+	80.62	56.51	20	0.08
BeatNet+ (Solo)	78.43	49.74	20	0.08
BeatNet (Heydari et al., 2021)	75.44	46.69	20	0.06
Novel 1D (Heydari et al., 2022)	76.47	42.57	20	0.02
IBT (Oliveira et al., 2010)	68.99	—	23	0.16
Böck FF (Böck et al., 2014)	74.18	—	46	0.05
Beast (Chang and Su, 2024)	80.04	52.23	46	0.40
<i>Offline Models</i>				
Transformers (Zhao et al., 2022)	88.5	71.4	—	—
SpecTNT-TCN (Hung et al., 2022)	88.7	75.6	—	—

Table 2: Results of online rhythm analysis evaluation for generic music and offline state-of-the-art references, showcasing F1 scores in % with a tolerance window of 70 ms, latency, and RTF for the GTZAN dataset.

697 pecially on downbeat tracking, highlights the benefit
698 of using the auxiliary branch during the training process
699 and leveraging the latent-matching technique between
700 the two branches; The latency and RTF do not
701 change as BeatNet+ utilizes only one branch during
702 inference. Finally, BeatNet+ (Solo) improves over Beat-
703 Net on both beat and downbeat F1 scores.

704 In the comparative analysis between BeatNet+ and
705 Beast, BeatNet+ demonstrates a marginal advantage
706 in beat tracking and a significant superiority in down-
707 beat tracking. Noteworthy is the fact that the latency
708 and RTF of BeatNet+ models are more than two times
709 and nearly seven times shorter than those of the Beast
710 model, making them more convenient for real-time
711 and low-resource applications. The main reason for
712 its substantially reduced computational cost lies in its
713 utilization of a source-efficient light 1D CRNN model,
714 in contrast to the inclusion of streaming transformers
715 used in Beast.

716 To assess system performance across various genres,
717 we present the beat and downbeat F1 scores
718 achieved by the top-performing method, BeatNet+,
719 across all GTZAN genres in Figure 4. **A comparative**
720 **analysis of the reported box plots reveals notable**
721 **variations in model performance for different genres.**
722 Specifically, the model’s best overall performance is ob-
723 served for Disco and Hip-hop; This is potentially at-
724 tributed to the presence of strong percussive and har-
725 monic cues and their more straightforward rhythmic
726 patterns. Conversely, genres like Classical and Jazz
727 demonstrate below-average model performance, po-
728 tentially due to the diverse musical characteristics and
729 intricate rhythmic patterns inherent to these genres.

730 Interestingly, some genres show contrasting perfor-
731 mance between beat tracking and downbeat tracking.

732 Specifically, Reggae receives one of the best beat track-
733 ing performance but the second-worst downbeat track-
734 ing performance with the widest range across differ-
735 ent pieces. This suggests that, while the percussive
736 and harmonic elements of Reggae are ample for beat
737 tracking, they are not sufficient for distinguishing be-
738 tween beats and downbeats. This phenomenon is at-
739 tributed to the presence of a substantial amount of
740 syncopation and frequently used off-beat rhythmic pat-
741 terns such as “One-drop”, “Steppers” and “Rockers” in
742 Reggae. Similarly, Jazz and Blues also show large per-
743 formance disparity between beat and downbeat track-
744 ing, attributable to the prevalent use of styles such as
745 the “Swing feel” within these genres².

4.5.2 Results on Singing Voices

746 Rhythm analysis of isolated singing voices is the most
747 challenging task among all discussed in this work. The
748 first row of Figure 5 compares the F1 scores of the
749 proposed model with different adaptation strategies
750 against SingNet Heydari et al. (2023), the state-of-the-
751 art singing voice rhythm analysis model, on singing
752 stems of the GTZAN dataset. According to the figure,
753 GF delivers the best performance for beat tracking by
754 a significant improvement of 14.58% and 13.27% over
755 the SingNet model for $T = 70ms$ and $T = 200ms$ toler-
756 ances, respectively. For downbeat tracking, AF outper-
757

²*Syncopation*: Irregular drum patterns by accenting weak beats commonly not emphasized, and by omitting or displacing notes, such as downbeats and upbeats, in a 4/4 meter. *One drop*: is a prominent drum set rhythm in reggae, differing from the typical backbeat by emphasizing the kick on beats 2 and 4 instead of 1 and 3. *Steppers*: follows the “four on the floor” pattern, featuring the kick drum hitting on all four downbeats in each measure. *Rockers*: a reggae beat in which the kick drum is on 1 and 3, while the snare is on beats 2 and 4 in a 4/4 meter. *Swing feel*: a specific type of syncopation that emphasizes the off-beat, giving the music a bouncy, lively feel (Morena, 2021).

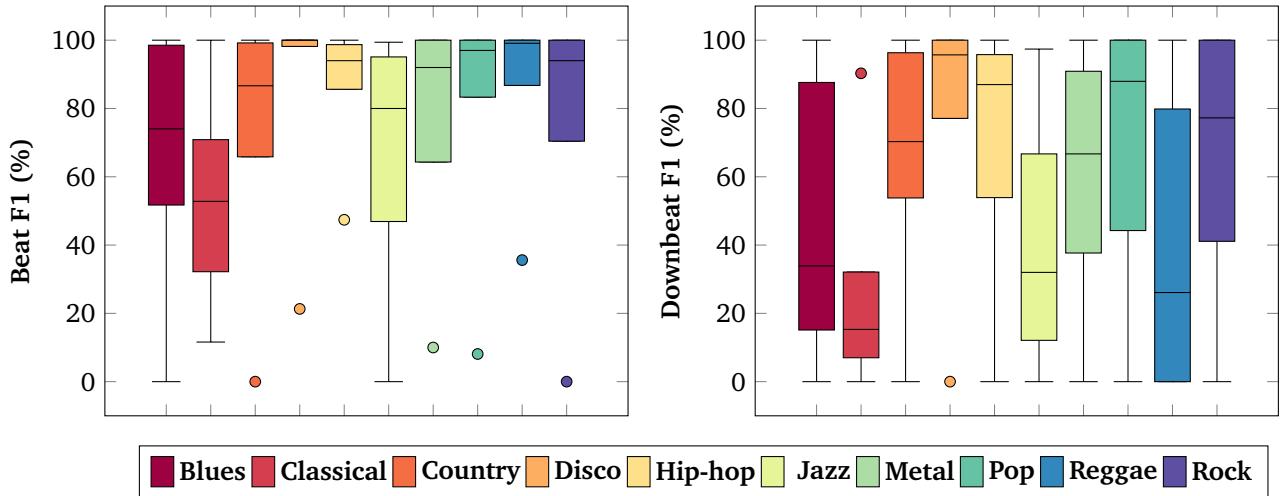


Figure 4: F1 scores for beat tracking and downbeat tracking of the BeatNet+ model across diverse genres within the GTZAN dataset.

forms SingNet by 2.43% and 0.51% for $T = 70\text{ms}$ ms and $T = 200\text{ms}$, tolerances. A more significant improvement in beat tracking accuracy compared to downbeat tracking suggests that the proposed models enhance acoustic modeling more effectively than capturing higher-level semantic modeling.

Comparing the adaptation models with the same BeatNet+ structures trained from scratch, GF outperforms GF-scratch significantly for beat tracking across both tolerances. However, it marginally underperforms GF-scratch for downbeat tracking. On the other hand, AF outperforms AF-scratch, for downbeat tracking while underperforming AF-scratch for beat detection. The aforementioned records indicate that for singing voice rhythm analysis, guided fine-tuning and auxiliary freezing techniques are effective for beat and downbeat tracking, respectively. However, there is no optimal joint model for both tasks.

4.5.3 Results on Non-Percussive Music

Rhythm analysis of non-percussive music is another challenging task. The plots on the second row of Figure 5 compare the performance of the proposed BeatNet+ model with different adaptation strategies against the BeatNet model on GTZAN pieces after removing the drums. As mentioned earlier, for this comparison, the BeatNet model is trained on the same data as the proposed models, i.e., non-percussive parts of the training set from scratch. According to the results, AF delivers the best performance for both beat and downbeat tracking among all models with a significant improvement of 8.88% and 8.19% for $T = 70$ and 10.55% and 12.85% for $T = 200$ over the baseline BeatNet model.

Comparing AF with AF-scratch underscores the impact of the auxiliary freezing technique on non-percussive music rhythm analysis. Disabling auxiliary freezing results in a notable downgrade in model per-

formance, shifting it from being the best across all models to the overall worst. However, comparing GF with GF-scratch reveals that guided fine-tuning offers similar performance for non-percussive rhythm analysis.

Also, We acknowledge that the rhythm analysis performance for non-percussive and isolated singing voices may be impacted by residual signals and data leakage, resulting from utilizing source separation techniques to extract music stems for training and evaluation. However, prior studies such as Heydari et al. (2021) have shown that this effect is negligible, as evidenced by comparing their model performances on music pieces with pure stems versus separated ones. Importantly, a fair comparison is ensured by using the same datasets for all reported models.

5. Conclusion

This paper presents BeatNet+, a cutting-edge online rhythm analysis model that significantly advances the state of the art in real-time music rhythm analysis. By incorporating an auxiliary branch regularization mechanism and employing innovative adaptation strategies, BeatNet+ demonstrates outstanding performance across various music scenarios, including generic music pieces, isolated singing voices, and non-percussive audio tracks. Additionally, we release the rhythmic annotations of MUSDB and URSing datasets, enabling them to be utilized for music rhythm analysis as well as revised annotations of RWC Jazz, Pop and Royalty-free along with this work.

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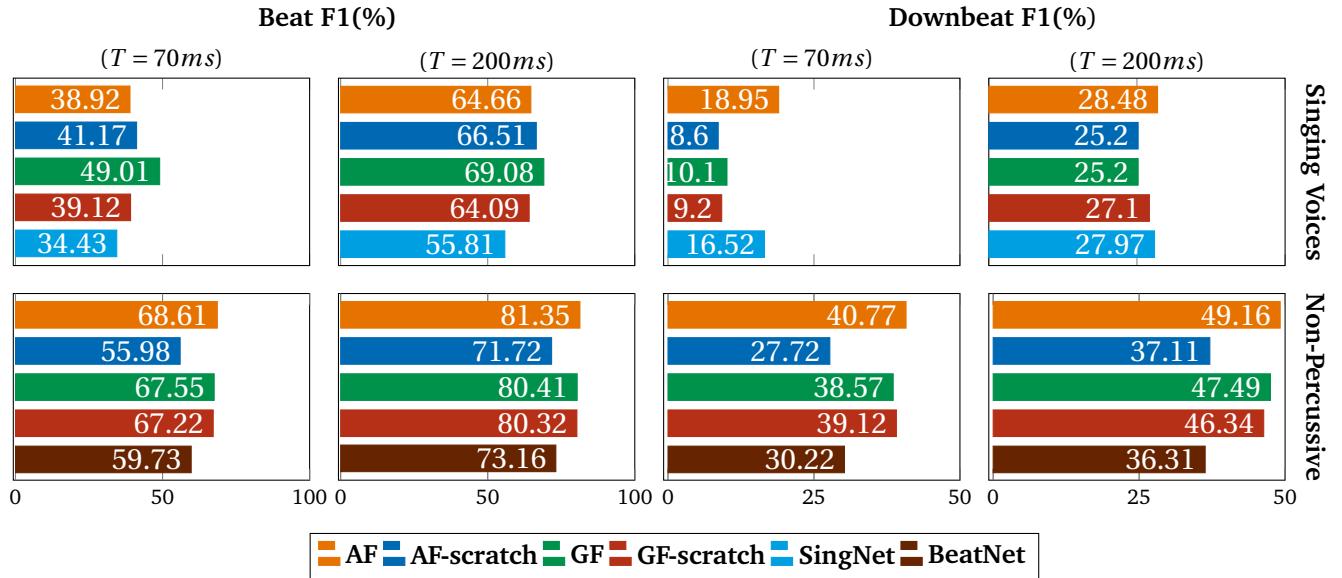


Figure 5: F1 scores of online rhythm analysis models on singing voices (top row) and non-percussion music (bottom row) with two tolerance windows, 70 ms and 200 ms.

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