

SoK: Security of Programmable Logic Controllers

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Abstract

Billions of people rely on essential utility and manufacturing infrastructures such as water treatment plants, energy management, and food production. Our dependence on reliable infrastructures makes them valuable targets for cyberattacks. One of the prime targets for adversaries attacking physical infrastructures are Programmable Logic Controllers (PLCs) because they connect the cyber and physical worlds. In this study, we conduct the first comprehensive systematization of knowledge that explores the security of PLCs: We present an in-depth analysis of PLC attacks and defenses and discover trends in the security of PLCs from the last 17 years of research. We introduce a novel threat taxonomy for PLCs and Industrial Control Systems (ICS). Finally, we identify and point out research gaps that, if left ignored, could lead to new catastrophic attacks against critical infrastructures.

Introduction

Programmable Logic Controllers, or PLCs, are small rugged computers that have programmable memory to store functions such as timers and logic gates. These functions can control physical machines, such as water pumps or centrifuges [33]. PLCs are rather unique systems due to two main characteristics: First, they act as a bridge that connects the cyber and physical worlds; therefore any attack carried out on them can have an immediate effect in the real world. Second, they have opaque, heterogeneous architectures that are different from traditional computer architectures, comprising multiple firmware, which makes them difficult to secure [165].

Before the introduction of PLCs, physical processes were controlled by relay panels. Relays are switched either on or off by an electric current, and thus they can be used in logic circuits. Ladder logic was created as a way to configure relay panels to automatically launch actuation commands based on sensor information. As industrial processes became more complex and varied, relays were not enough to meet the new requirements. An evolution of PLCs, first based on

microprocessors, then on networks, and more recently on modern technology paradigms, such as virtualization, has introduced multiple benefits, but at the same time increased the attack surface of these systems.

The first PLC, the Modicon 084, was introduced in 1968 [35]. Unlike relays, PLCs could be programmed and reprogrammed to adjust to the process requirements without any physical changes to the control system. A flurry of programming languages emerged, extending ladder logic and introducing new paradigms. Eventually, in 1993, the IEC 61131-3 standard unified these multiple languages into basic standards for PLC programming languages [171].

The first PLCs communicated with the physical world as well as with other computers via analog or serial communications. As computer networks became more reliable and available in the IT world, Ethernet communications were introduced to PLCs. This network connectivity keeps increasing. For example, the Siemens S7-1500 PLC includes up to 4 Ethernet ports, whereas the legacy S7-300 needed an expansion module to support Ethernet connectivity. At the same time, network accessibility now allows remote attackers to deploy classical network attacks against PLCs.

Nowadays, with the advent of Industry 4.0 and IIoT [160], PLCs are going through another paradigm shift bringing even more functionalities like cloud integration, web services, and virtualization. New players like CODESYS and OpenPLC have also entered the market, challenging the longstanding practice of using proprietary hardware and proprietary software products that dominated the PLC industry. These changes pose many open questions about the security of PLCs to the research community.

In order to advance the security of PLCs and the systems they interact with, plenty of research has been produced in the past decades. In particular, research output increased after the term Cyber-Physical System (CPS) was coined in late 2006 by the NSF in the United States [47]. However, the community still lacks an up-to-date general understanding of where the security of PLCs stands and what directions should (or should not) be taken in the future.

To address this challenge, we introduce a comprehensive analysis of the security of PLCs by integrating knowledge from multiple fragmented origins (scientific and grey literature), comprising many existing attack and defense methods in the literature. In addition, we introduce a novel threat model as well as classification and evaluation criteria for summarizing and structuring the existing knowledge about PLC security.

In summary, we make the following contributions:

- We provide a systematization of the literature that consists of 133 papers, which include 119 attack methods, and 70 defense methods (one paper might include one or more attack or defense methods).
- We present a comprehensive taxonomy¹ that integrates the scientific literature with the existing ATT&CK for ICS Matrix in collaboration with MITRE ATT&CK®.
- We identify important PLC security research gaps and discuss future research directions and recommendations.
- We provide **three public tools** to facilitate and foster research and collaboration on this topic. **1**) Our full systematization dataset², which other researchers can use to replicate our results and perform their own analyses. **2**) A PLC security artifacts repository³, which acts as a centralized database for artifacts updated by the community. **3**) A reference graph⁴ that enables researchers to further analyze the reviewed literature in this SoK.

2 Background

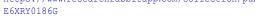
We now introduce some relevant background topics on PLCs that will be leveraged in future sections.

2.1 PLC System Environment

PLCs [152] are an essential component of most physical critical infrastructures such as water treatment systems and gas pipelines. PLCs are commonly found in Industrial Control Systems and Supervisory Control and Data Acquisition (SCADA) systems.

In the last few years, two new concepts have emerged in the context of Cyber-Physical Systems: Industrial IoT (IIoT) and Indystry 4.0. IIoT is a subset of IoT concerned with connecting industrial assets, e.g., PLCs, with information systems and business processes. Industry 4.0, on the other hand, is a subset of IIoT and refers to the use of Internet technologies to improve production efficiency by employing smart services in smart factories [160]. Furthermore, IIoT and Industry 4.0 have changed PLCs in two ways: First, they have introduced support for modern network protocols, which we

⁴https://www.researchrabbitapp.com/collection/public/



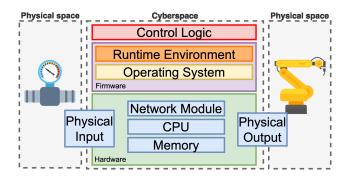


Figure 1: A Generalized PLC Architecture. Based on [33, 59].

discuss further in Sec. 2.3. Second, they have changed the hardware and software architectures to support virtualization and compatibility. We further discuss these topics in Sec. 2.4.

PLCs' industrial environment, however, remains largely the same and typically includes the following [166]:

Actuator. A hardware component that moves or operates a device in the physical world. Examples of actuators include valves, motors, and piezoelectric actuators.

Sensor. A device that generates an electrical analog or digital signal that represents a physical property of a process. Examples include temperature or magnetic field sensors.

Engineering Station. A general-purpose computer that is used to write the control logic or ladder logic code for the PLC to execute. It is usually connected to the PLC so that the compiled control logic program can be uploaded.

Human Machine Interface (HMI). The hardware or software used to interact with the PLC, e.g, a physical control panel with buttons and lights or a software display.

We further discuss PLCs' underlying architecture and environment in the extended version of this paper [105].

2.2 PLC Basic Components

As shown in Fig. 1, a typical PLC has the following basic components that are susceptible to attacks:

Control Logic. A control logic program contains the instructions that the PLC executes to interact with its environment. The IEC 61131-3 standard [171] specifies the syntax and semantics of a unified suite of programming languages for PLCs. Control programs are written in one of these supported languages, e.g., Structured Text, and then compiled into machine code or bytecode. For instance, Siemens PLCs run proprietary MC7 bytecode [126] compiled by the SIMATIC S7 Manager software [157].

Runtime Environment. The runtime environment executes the process control code [59] and interacts with the I/O modules. It can be proprietary, e.g., Schneider, or open source like the OpenPLC runtime [17].

Operating System. Most PLCs have a Real-Time Oper-

¹https://github.com/efrenlopezm/ics2matrix

²https://github.com/efrenlopezm/plc-sok-dataset

³https://github.com/efrenlopezm/plcsecurityartifacts

ating System (RTOS) [164]. RTOS are operating systems that meet strict processing time requirements and support real-time applications. Vendors support a variety of RTOS in their platforms. For example, Siemens supports the Nucleus RTOS [159] and VxWorks [158].

Firmware. The firmware bridges the gap between the PLC hardware and software. While simple PLCs might run applications as bare metal (without an OS) [24, 196], modern PLCs use the firmware under an RTOS. Firmware can be upgraded via SD cards or through a network connection [83].

CPU. The CPU interprets the input signals and executes the logic instructions saved in memory. The CPU chassis has slots where other components may be attached, e.g., a network module. It may also include USB ports and SD Card slots.

Memory Unit. It stores the program that the CPU will execute along with input data. The memory unit may include different types of memory blocks, which are further discussed in the extended version of this paper [105].

Network Module. Modern PLCs can have one or more ports to communicate with the supervisory control network (regular computers monitoring the process) or the fieldbus (actuators and sensors).

Physical I/O Modules. These include input modules with metal pins that receive information (via a voltage or current analog signal) from sensors. The output modules send analog data to actuators such as servo motors.

PLC Scan Cycle. It is the cycle in which the PLC reads the sensor inputs, executes the current control logic program and updates the output to the actuators. It is measured in ms and should stay constant. If its time increases, PLCs implement a watchdog timer that sends the PLC to a Fault mode [6, 21].

2.3 **PLC Communication Protocols**

As discussed in the introduction, PLCs are becoming more connected via modern communication protocols. Many of these protocols were not designed to include strong security features [85], allowing for the proliferation of vulnerabilities that make the PLCs running them susceptible to attacks [31, 189]. Protocols commonly used in practice include, but are not limited to, the following:

Fieldbus. PLCs use Fieldbus [170] protocols to talk to sensors and actuators. Historically these communications were done through serial-based interfaces or analog signals. Sample standards include Profibus, CAN bus, Modbus, and DeviceNet. They all differ in features and implementation, resulting in limited compatibility [57, 96].

Supervisory Network Protocols. PLCs communicate with other controllers or classical computers through a variety of proprietary and standardized protocols. These protocols use the IEEE 802.3 Ethernet standard [84] in industrial environments [111]. For example, the EtherNet/IP protocol combines IEEE 802.3 and the TCP/IP Suite [54]. Some are designed to operate on LANs (they do not use IP addresses but only

MAC addresses), such as GOOSE, while others use TCP/IP and can be used on LANs and WANs, such as Modbus TCP.

Industry 4.0 Protocols. These protocols include support for cloud connectivity, compatibility between devices, and security features. Examples include MQTT (Message Oueuing Telemetry Transport) [122] and OPC-UA (Open Platform Communications-Unified Architecture) [176]. Currently, some PLC models support Industry 4.0 protocols [41], whereas older PLCs can be retrofitted to support them [80].

2.4 SoftPLCs

The term SoftPLC has been used in the scientific literature since the late 1990s [49, 142, 162]. Although it has not been well defined, generally a SoftPLC is a software runtime environment that executes PLC programs, for example, programs that follow the IEC 61131-3 standard [171]. The runtime is portable and compatible with multiple hardware that can range from microcontrollers to cloud servers [129]. The two major SoftPLC projects are CODESYS [44] and Open-PLC [129]. CODESYS supports approximately a thousand different device types from more than 500 manufacturers [43]. OpenPLC, first proposed in 2014 [20], includes a runtime and an editor, and it is compatible with 18 platforms including Windows and Linux [129]. One of the biggest differences between OpenPLC and CODESYS is that OpenPLC's runtime is open source [17], unlike that of CODESYS. For the remainder of this work, we will refer to traditional PLCs as HardPLCs, in order to differentiate them from SoftPLCs.

Research Questions and Methodology

In this section, we first elaborate on the research questions addressed in this paper, and we then describe the methodology we followed to systematize knowledge by collecting, analyzing, and evaluating works in the literature.

Overview of Research Questions 3.1

RQ-1: What are the attack methods against PLCs? We aim to categorize and analyze attack methodologies targeting PLCs introduced in the literature in the last 17 years.

- **RQ-1.1:** Which components of the PLC are targeted? We aim to identify what internal components of a PLC, e.g., the CPU described in Sec. 2.2, are being targeted, in an effort to identify patterns such as the components that have received the most attention in the literature.
- **RQ-1.2:** *How difficult is it to deploy attacks?* We also aim to identify the level of effort required by attackers to successfully carry out attacks against PLCs. In Sec. 4, we elaborate on a threat model and classification criteria, including the

potential attack vectors as well as the level of access required by attackers, e.g., Internet access, needed to deploy an attack.

• **RQ-1.3:** What is the impact of deploying attacks? Finally, we are interested in identifying the impact that attacks against PLCs may have if they are deployed successfully. This includes the level of disruption achieved, e.g., modifications to control logic programs as shown in Sec. 2.1.

RQ-2: What are the defense methods to protect PLCs? In addition to attacks, we want to systematize the PLC defenses proposed in the literature in the last 17 years.

- **RQ-2.1:** Which components of the PLC are protected? We want to identify which of the components introduced in Sec. 2.2 are the focus of defenses to understand which of them have received less attention and may therefore remain unprotected.
- **RQ-2.2:** How difficult is it to deploy defenses for PLCs? We also study the level of effort required to deploy defense mechanisms for PLCs. As shown in Sec. 4.5, this includes the organizational effort from administrators and/or operators to modify and adjust a given PLC/ICS Environment and the performance overhead.
- **RQ-2.3:** Are there enough defenses addressing reported attacks for PLCs? Finally, we are interested to know if enough defenses exist in the literature to counteract the attacks we have identified as a part of this work. This way, we aim to identify research gaps and discuss the directions of future work as we describe in Sec. 6 and Sec. 7.

3.2 Knowledge Systematization Methodology

To answer the Research Questions raised in Sec 3.1, we use the systematization methodology shown in Fig. 2. First, we perform a systematic literature review. Second, based on the data obtained in the literature review, we perform data analysis and modeling. Finally, we assess the data.

① Systematic Literature Review. We review both scientific and grey literature to collect PLC attack and defense methods. We also define the final SoK scope based on the specified inclusion criteria.

Scientific Literature Review. We consider scientific literature to mean the literature that is based on the scientific method that uses evidence to develop conclusions. It uses previous literature to develop theories and hypotheses while taking care to cite the authors and tools that are used. For the scientific literature review, we carried out the following steps: 1) Search Querying. We used search queries based on keywords such as "plc", "ics", and "security". The complete list of keywords can be found in Appendix A. 2) Consulting literature resources. We used these queries to search the selected resources such as Google Scholar and the ACM Digital Library. The complete list of consulted resources can be found

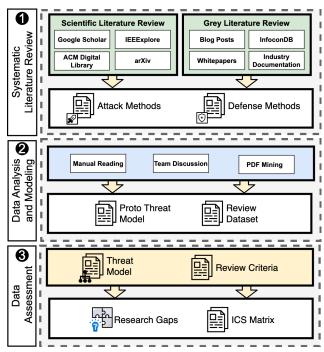


Figure 2: Our systematization methodology. Based on [100].

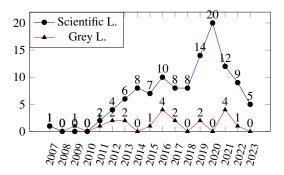


Figure 3: Literature focused on PLC Security per Year.

in Appendix A. 3) Applying inclusion criteria. After collecting all these papers, we include them only if they meet the following three criteria. A) The paper must include the term "PLC" or "Programmable Logic Controller". B) It proposes an attack or defense method. C) It includes an experimental evaluation of an attack or defense with at least one PLC. 4) Applying snowballing. We applied the snowballing technique [187] on all the papers that matched the above criteria to find papers that went unnoticed during the initial search.

Grey Literature Review. We consider grey literature as literature with limited distribution (i.e., not included in academic publishing libraries). It includes unpublished reports, policy documents, white papers, and technical reports [45]. To perform our grey literature review, we followed the same steps used in the scientific literature review, except that in step 2) (consulting literature resources) we instead searched in the grey literature resources listed in Appendix A.

Final Sok Scope. As a result of the scientific and grey literature reviews we collected 133 papers with the earliest being from 2007 and the latest from 2023. Although we searched for papers before 2007, we did not find any that met our criteria. To the best of our knowledge, and based on our exhaustive research, there was no research on designing new attacks or defenses for PLCs before 2007. Fig. 3 shows the final number of scientific and grey papers included in our selection criteria per year of publication, depicting an overall increase in PLC security research over the years, peaking in 2020.

2 Data Analysis and Modeling. In this phase, we first read and analyzed each paper to extract important security-relevant information such as attack vectors, PLC models and manufacturers, and PLC target component. Second, we matched each of the attack and defense methods to their corresponding MITRE technique, subtechnique or mitigation category. The MITRE framework is further discussed in Sec. 4.1. Third, we recorded this information in a spreadsheet. The result of this data analysis and modeling was the identification of the building blocks for a first draft of our threat model depicted in Fig. 4 and the classification criteria discussed in Sec. 4., e.g., the access level and PLC target component.

3 Model Assessment. In this phase, we evaluate the data, threat model, and criteria developed in **2** to produce the SoK contributions. We use these results to summarize our findings and identify the research gaps discussed in Sec. 6. Finally, we evaluate the results to produce the ICS threat taxonomy discussed in Sec. 4.1.

4 Classification and Evaluation Criteria

In this section, we present the criteria to classify and evaluate the works considered for this SoK. These criteria and the symbols introduced alongside them will later be used in Tables 1 and 2. Our first research question RQ-1 is addressed in Sec. 4.2, Sec. 4.3, and Sec. 4.4. Our second research question RQ-2 is addressed in Sec. 4.5, Sec. 4.6, and Sec. 4.7.

4.1 ICS Threat Taxonomy

To better classify attack and defense methods in the following sections, we extended the MITRE ATT&CK for ICS Matrix [112] and the Hybrid ATT&CK Matrix [9] to create the ICS² Matrix, a taxonomy of threats against PLCs and ICS. The taxonomy includes adversary tactics that describe "what" is the adversary's goal and attack techniques that describe "how" the adversary can complete their goal. Additionally, it includes mitigations that prevent a technique from being successfully executed. The ICS² Matrix incorporates the scientific knowledge accumulated during the past 17 years of PLC security research by adding 6 new attack techniques and 5 new mitigation categories based on the literature reviewed in this SoK. Due to space restrictions, we provide a condensed

version of our taxonomy in the extended version of this paper [105]. The full ICS² Matrix version is publicly available⁵ for the security community to use and extend. Additionally, at the time of writing this paper, we are actively working with MITRE to integrate our research findings within the next version of MITRE ATT&CK for ICS [112] and D3FEND Knowledge Graph [90, 121].

Matrix Integration. One of the main limitations of the MITRE ATT&CK for ICS Matrix [112] is that it does not incorporate techniques based on security research findings but instead focuses on techniques based on real-world ICS cyberattacks. For example, the "system firmware" technique [169] includes a reference to Triton discussed in the extended version of this paper [105]. However, it does not include any references to any of the PLC Firmware research listed in Table 2. This was also confirmed by MITRE during one of our communications. Our ICS² Matrix fills this gap. To integrate our systematization findings with the existing MITRE for ICS Matrix, we needed to add techniques not already covered by MITRE. To develop these new techniques, we used MITRE's official guidelines [120]. This document outlines the information required to create a new MITRE-style technique, for example, a matching "tactic" and "procedure example". In the extended version of this paper [105] we describe in detail how we developed and included one of these techniques.

4.2 Attack Classification

Considering RQ-1.1, the following criteria classify attacks according to the taxonomy technique, e.g., Adversary-in-the-Middle, the basic components that are targeted, e.g., the CPU or Memory, and the attack vectors that can be ultimately used against a PLC.

Target PLC Component. Each attack method was classified according to the PLC Basic Component that is the primary target, following the description previously shown in Sec. 2.2. Such information was retrieved based on the descriptions explicitly provided by the paper's authors.

Attack Category. Each attack method was sorted into one *technique* category, based on our ICS² Matrix. The technique categories allowed us to determine what kind of defenses might (or might not) counter them.

Attack Vector. When launching an attack against a PLC, there might be one or more vectors or paths available to the adversary to deliver the payload. The complete list of attack vectors we considered is shown in the extended version of this paper [105]. Most of the time the attack vector is a vulnerability in the implementation of a network protocol, e.g., S7comm. However, there are other vectors like inserting an SD card into the PLC chassis, for instance, the work by Garcia et al. [65].

 $^{^{5}}$ https://github.com/efrenlopezm/ics2matrix

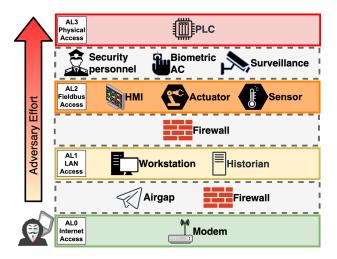


Figure 4: PLC-centered Threat Model. Based on [166].

Attack Complexity 4.3

Following RQ-1.2, the criteria shown next are intended to understand, qualify, and quantify how complex it is for an attacker to carry out an attack against a target PLC.

Environment Knowledge. This criterion evaluates how much knowledge of the cyber-physical system environment where the PLC lives, e.g., the system topology discussed in Sec. 2.1, is required to launch the attack. An attack may require zero knowledge (O), e.g., a DoS [193] attack targeting the PLC network module only requires an IP address and does not require any environment knowledge. Partial knowledge (**1**) may require basic information only, e.g., a high-level description of the physical process. CaFDI [116], for example, requires limited local information about the substation configuration. Finally, extensive knowledge () requires detailed information about the cyber-physical environment. For example, SABOT [115] requires the adversary to encode their understanding of the system behavior into a specification.

Available Source Code. This criterion evaluates whether the attack source code is publicly available (**①**) or not (**O**).

Access Level. We also consider the level of access an attacker needs to carry out the suggested attacks. Our threat model, shown in Fig. 4, is divided into four distinct Access Levels (ALs) labeled from AL0 to AL3. Adversaries might try to move through the ICS environment in order to reach the PLC and deliver their exploit payload. Overall, our threat model helps us answer two main questions: 1) What access level is required to attempt the attack?, and 2) What attack surfaces are available to the adversary?

AL0: Access to PLC via the Internet (0). An adversary may be able to access a PLC through an Internet-compatible protocol, e.g., S7comm. This is usually a private network where a remote SCADA computer connects to a PLC via an industrial protocol such as DNP3. Attacks may also be

launched if a PLC is publicly exposed on the Internet. At first, this might seem like a ludicrous idea: Why would anybody make a PLC publicly available over the Internet? However, a preliminary Shodan search suggests that the number of publicly accessible PLCs (excluding Shodan-identified honeypots) is over 6,500 as of September 2023⁶

AL1: Access to Supervisory LAN (1). This level requires an attacker to have access to the LAN network of the industrial process. This can be achieved if the attacker compromises workstation computers, data historians, or similar operational computers. Some industrial protocols run only on Ethernet and are non-routable (such as GOOSE), so an attacker targeting a vulnerable GOOSE stack on a PLC will have to do so in the same LAN.

AL2: Access to PLC Fieldbus Network (2). As mentioned in Sec. 2.3, fieldbus represents the lower level of communications between the PLC and nearby field equipment such as actuators and sensors. An attacker can compromise any of these devices to exploit a vulnerability in the fieldbus code implementation. The attacker can also launch Adversary-in-the-Middle attacks in this network, as fieldbus communications are rarely authenticated in practice.

AL3: Physical Access to PLC (**6**). Lastly, this level assumes the adversary has bypassed environmental and physical protection measures (e.g., locked doors) of the target. Having physical access to the PLC may be the most difficult scenario for an adversary but can still be achieved by malicious insiders or disgruntled employees. An attacker with physical access can use a JTAG interface.

Attack Impact

Following RQ-1.3, the criteria below are intended to understand and quantify the potential impact of a successfully carried out attack, e.g., the payoff in return of the effort invested, as discussed in Sec. 4.3.

Potential Damage. This criterion evaluates the *immediate* damage inflicted to the physical operation of the ICS. The damage is *limited* (1) if the attack does not change the operation of the process but instead aims to collect information or gain unauthorized access, for example, a password sniffing attack [184]. The potential damage is *substantial* (2) if the attack can stop the industrial process partially or completely, e.g., a DoS attack [128]. The potential damage is severe (3) if the attack is able to insidiously control the physical process, e.g., a logic bomb or firmware modification attack, where the attacker can launch arbitrary control commands to the system (similar to Stuxnet, discussed in the extended version of this paper [105].

HardPLC Targets. An attack may affect a *single* PLC model (O), e.g., the Siemens SIMATIC S7-300, or may affect multiple PLC models of the same manufacturer (**①**), e.g., the Rockwell's Allen-Bradley 1100 and 1400 models. Also, an

⁶https://www.shodan.io/search?query=plc+-%22792%2F71644%22.

attack may affect multiple PLC models from two or more manufacturers (), e.g., Siemens' SIMATIC S7-1500 and Modicon's M221. An attack that is effective against various devices is an indicator of the severity of the problem, while an attack focusing on a single device might be contained.

SoftPLC Targets. Finally, this criterion indicates if a Soft-PLC was used to evaluate the proposed attack. An attack may have been evaluated using CODESYS (C), OpenPLC (O) or no SoftPLC at all (-) (i.e., the attack only focused on HardPLCs).

Defense Classification

After describing our criteria for attacks, we now focus on defenses by looking at RQ-2.1.

Defense Category. Each defense method was sorted into one mitigation category, based on our ICS² Matrix. The mitigation categories allowed us to determine what kind of attacks might (or might not) be countered.

Defense Vector. The defense vector is the path used to stop the attack payload from being delivered. The available defense vectors are defined in our threat model for PLCs in the extended version of this paper [105]. Most of the time, the attack and defense vectors will match. However, they can differ. For example, Rajput et al. use the JTAG interface as a defense vector [139].

4.6 **Defense Deployability**

Following RQ-2.2, the following criteria evaluate how difficult it is to deploy a defense method to protect PLCs.

PLC Overhead. This criterion quantifies the overhead that the defense method incurs on the PLC itself, which can be either zero (1), negligible (2), or considerable (3).

Infrastructure Overhead. This criterion quantifies the cost that comes with setting up the required infrastructure to implement a defense method. That may involve no changes (1), or it may involve *either* an infrastructure change, e.g., setting up new VLANs or an additional hardware component, e.g., bump-in-the-wire (2). Finally, a defense may involve both infrastructure changes and hardware components (3).

Maintenance. This criterion quantifies the level of postdeployment maintenance required by a given defense method. A defense method may require no maintenance (1), sporadic maintenance (2), or constant maintenance (3).

Source Code Availability. This criterion evaluates whether the defense source code is publicly available (**①**) or not (**O**).

Defense Robustness

Following RQ-2.3, we also characterize how the defense mitigates attacks.

Defense Stage. Defenses can be categorized in three different stages of the security process. 1) Prevention Defense (PR) aims to reduce the possibility of an incident before a known

vulnerability is exploited. 2) Detection Defense (DE) aims to identify and alert about a current or recent attack. 3) Recovery Defense (RE) aims to reduce the damage of an attack after it has been carried out successfully.

Effectiveness. The defense method's effectiveness is indicated by its accuracy. The accuracy values are taken from the research paper itself. If the paper did not report or specify the accuracy, it is marked as N/S (not specified). We selected accuracy because it is the most reported metric across the defense method papers. We recognize that this metric does not work for all defense methods, however, it is the most frequently reported quantitative metric available in the current literature. We further discuss this problem in Sec.7.

HardPLC Scope. This criterion evaluates the number of different PLC models that are protected by the defense. The defense may protect a *single* PLC model (**O**), e.g., the Siemens SIMATIC S7-300, or it may protect multiple PLC models of the same manufacturer (**0**), e.g., the Rockwell's Allen-Bradley 1100 and 1400 models. Also, a defense may protect *multiple* PLC models from two or more manufacturers (•), e.g., Siemens' SIMATIC S7-1500 and Modicon's M221. **SoftPLC Scope.** This criterion indicates if any SoftPLC was used to evaluate a defense, either CODESYS (C), Open-

Overview of Attacks

PLC (O) or no SoftPLC at all (-).

By using the systematization methodology presented in Sec. 3 and the criteria discussed in Sec. 4, we obtained Tables 1, and 2. These tables use the *PLC target component* categorization defined in Fig. 1.

We now illustrate examples of attacks per target component. Due to the large number of papers in our SoK (133 papers), we cannot discuss all of them. To select the papers systematically, we picked the two papers with the most citations from each category. We used Google Scholar to perform the search on June 3, 2023. In the next paragraphs, we discuss the insights provided by these highly-cited papers.

Attacks that Target the PLC Communications Module. Urbina et al. [177] introduce an AitM attack between the PLC and the field devices (AL2). An interesting observation of that paper is that field networks tend to follow a ring topology rather than the typical star topology of switched Ethernet networks; therefore, an AitM attack does not need to use ARP (Address Resolution Protocol) spoofing or similar techniques to place itself between two devices. It just needs to inject the attack between the two attacked devices. An AitM attacker can then send false sensor readings to the PLC or false control commands to actuators.

Wardak et al. [184] introduce another network attack, which focuses on password sniffing on the network interface between a workstation and the PLC (AL1) in Fig. 4. Several of the connections between the workstations and the PLCs are not encrypted (or authenticated). Thus, passwords can be

		Attacks	Defenses													
ent			Complexity Impact							ų.			yal	oility	Rob	ustness
Target Component	Method	Category (Technique)		Access Level Env Knowledge			HPLC Targets SPLC Targets	Method	Category (Mitigation)			Infra Overhead	Maintenance	Source Code		D. Strategy HPLC Scope
	Attacks on situational awareness [99]		P	1	0	\rightarrow		Cross-layer fingerprinting [61]		D	1	1	1			DEO .
- 1 ⊢	Concealment Attack [53]		M	10	•			DFA-based intrusion detection [72]		M	1	2	1			DE O -
	Controller Eavesdropping [68]		P	10		_	-	Encrypted Traffic IDS [82]		I	1	2	1	0	N/S	DE - ·
	Controller Packet Tampering [68]		P	0	_	8	_	IDS for S7 networks [94]	Network Intrusion Pre.	S7	_	2	U			DE O :
	False Data Injection Attack [40] Man in the middle [22]	Adversary-in-the-Middle	Е	00		1	-	Model-based anomaly detection [97] Physical fingerprinting [61]		S7 D	1	2	1	00		DEO :
	OPC-UA Rogue Client [8]			00	_	_	-	PLC Watermarking [6]		E		2	ă	0		DEO .
I 1	Replay attack [184]		\vdash	00	_	_	_	Embedding Encryption [18]		M	ă	1	ă	ŏ	N/S	
	Replay attack [149]			00	-	_	_	Hash Authentication [64]		F	Ĭ	i	Ď			PRO ·
	SDN Enabled MitM [68]		P	10	0	_	-	LVST (LabView SSH Tunnel) [135]	Encrypt Network Traffic	Е	Ŏ	2	Ō	_		PR •
J	SO-TSAP Replay Attack [28]]	P	00	0	2	0 -	AES-256 Implementation [19]		M	1	1	1	•	N/S	PR - (
l ħ	Third-party Eavesdropping [68]		P	10	0	1	•0	PLCrypto [190]		Е	1	1	1	•	N/S	PRO -
	Change the IP [145]		Е	00	•	2	0 -	PLC-Sleuth [191]		S7	1	2	1	0	100	DEO -
	Control engine attack [137]		-	00		_	_	Semantic IDS [78]	Network Intrusion Pre.	M	_	2	1	0	N/S	
	Denial of Service Attack [193]	Denial of Service	\longrightarrow	00	-			Telemetry IDS [136]		M	1	2	1		99.5	
	OoS clearing Flow Table [68]	Beniar of Service		00	-			Zeus [79]		Е	1	2	2			DE O
! ⊢	Flow Rule Blocking [68]			00		\rightarrow	_	Side-channel Anomaly Detection [51]	Out-of-Band Comms Channel	-	_	-	2			DEO -
1 +	JDP reflect attack [149]			00				Anomaly detection [200]		- 1	_	-	2	0		DE ·
	Authentication Bypass [76]			10		1	-	Arcade.PLC [30]	Control Logic Verification	S7	_	-	1	0		PRO
	Cryptographic attack [149]	M I'C A I D	F	0		1		ShadowPLCs [88]		S7	2	1	2		-	DEO -
	Replay attack [103]	Modify Auth. Process		00		1		Snapshooter [86]	Network Intrusion Pre.	S	2	2	1	-		DE - C
1	87 Authentication Bypass [28]		I - I	00	_	1	_	Traffic Data Classification [101]		-	1	1	2			PRO PRO
10	Unauthorized password updating [184] SoMachine Authentication [22]			00		1	_	vBump [172]		G	_		2	_	11/3	rko
75 -	Credentials from storage [22]			00		1						H	_			\rightarrow
! ⊢	subverting read/write-protection [22]	Hardcoded Credentials		00	_	1	-					Н	\dashv			++
I +	subverting write-protection [22]			00		1	-				F	H				\pm
	Command packet flooding [75]		Е	00	_	1	<u>0</u> -	Modbus/TCP Firewall [155]	Filter Net. Traffic	M	1	2	1	0	N/S	PRO -
	Modbus Flooding Attack [29]	N. 15 :166 :		00		2	_				Ť	Ħ	Ĭ			
1	Network Flooding Attack [128]	Network Denial of Service	M	00	0	2	• -				Г	П				
Ī	UDP flooding Attack [93]		M	00	0	2	0 -				Г	П				
I	Password reset attack [22]		M	00	0	1	0 -	Shade [195]		Е	2	1	1	•	N/S	DE ·
	CLIK password attack [89]	Brute Force	M	00	•	1	0 -	Host Anomaly Detecton [59]	Network Intrusion Pre.	M	2	1	1	0	N/S	DE •
	Dictionary Attack [34]		-	00	_	1	-	Argus [5]		Е	_	3	3		N/S	
	Dump module code [145]	Data from Local System	-	00	_	1	_	PLC-PROV [7]	Validate Program Inputs	N	_	2	2	_	N/S	
1 L	Memory Logic Attack [28]		\vdash	00	_	1		PLCPrint [46]			_	1	1	0		DE ·
	Crash 1756-ENBT module [145]	Device Restart/Shutdown		00	_		-	ABAC model for PLC [74]	Authorization Enforcement	S7	=	2	0	_		PR •
! ⊢	Reset 1756-ENBT module [145]		\vdash	00			0 - 0 C	FINS detection rules [63]	Network Allowlists	F		2	1	0	IN/S	PR 🛈 -
1 +	Leak Modbus data [175] Leak OPC-UA Process Data [175]	Exfiltration Side-channel	-	00		_	OC.			Н	\vdash	Н	-			+
	Passive network scanner [185]		M	10	_	1	_			\vdash	\vdash	Н	\dashv			+
	Port scanner [95]	Network Conn. Enumeration	\vdash	00		_	OC			H	\vdash	Н	\dashv			+
	SOCKS Proxy [95]	Connection Proxy		00	_			SDN-enabled automatic response [124]	Network Intrusion Pre.	Е	1	2	1	•	N/S	DE -
	New ADMIN account [34]	Exp. for Credential Access	$\overline{}$	00	_	1	_	WeaselBoard [123]	Exploit Protection	BP	-	3	6			PR •
1 +	Getting a Shell on the PLC [28]	Exp. for Privilege Escalation	-	00		_	-	Memory Access Taintedness [26]	Exploit Protection	M	_	1	1		N/S	
	Password stealing [184]	Network Sniffing		00		1		SCADA Protocol Obfuscation [25]	Encrypt Net. Traffic			1	_	_		PRO -
N	Wireless Fieldbus MiTM [177]	Wireless Sniffing	Е	<u> </u>	0	1	0 -	Secure Logging for ICS [150]	Encrypt Net. Traffic	S	1	3	1	0	N/S	PRO -
	SS CoDeSys Tools [186]	Exp. for Privilege Escalation	С	10			- C			П	Г					
- H	Remote arbitrary code execution [92]		\rightarrow	00	_			ECFI [3]	Exploit Protection	RT	2	2	1	0	N/S	PR O
_	Arbitrary Code Execution [4]	Exp. for Client Execution	R	<u> </u>		_	0 -			Ш	L					Щ
	Ghost in the PLC [2]	Block I/O Communication	R			_	-	GhostBuster [1]	Exploit Protection	RT	2	1	1	0	N/S	DE O (
	Unauthenticated file read/write [71]	Data from Local System	C	10			O C				\vdash	Н	_			\dashv
 	XML bomb [71]	Modify Parameter	C	10	0	2	OC				L					$\perp \! \! \perp \! \! \! \perp$

Table 1: A Summary of PLC Attack and Defense Methods (Network, OS and Runtime Components).

D=DNP3, G=GOOSE, S7=57COMM, I=IEC 104, UA=OPC-UA, P=Profinet, E=EtherNet/IP, M=Modbus TCP, F=FINS, S=Syslog, B=Beckhoff, BP=Backpane, R=SoC Register, RT=Runtime, O=OpenPLC, C=CODESYS / CODESYS upload protocol, N=Not Specified, DE=Detection, PR=Prevention, RE=Recovery

Attacks																
'n				Com	plex	ity	Impac	t	Defenses	L	De	ploy	abil	lity	Rob	ustnes
Target Component	Method	Category (Technique)	Attack Vector	Access Level Env Knowledge	Source Code	anno aninos	P. Damage HPLC Targets	-	Category (Mitigation)	Defense Vector		Infra Overhead	Source Code	- Deficionation	Ellectiveness	D. Strategy HPLC Scope
	Advanced Stealthy Injection Attack [15] CLIK [89] Data Execution Attack [194] Fragmentation and Noise Padding [194] Ladder Logic Bomb [73] Time-of-Day (TOD) interrupt attack [14]	Modify Control Logic	M U	0 Q 1 C 0 C 0 C			30 20 20 30	Safety Verification [67] CPLCD [192] Trusted Safety Verifier [117] Detection Manipulation [102] PLCloud [154] PLC Guard [109]	- Control Logic Verification	S7 N X S7 S7	1 1	2 1 2 1 3 2 2	1 C 1 C 3 C	1 C 1 C 1 C	N/S I N/S I N/S I N/S I	DEO DEO DE - DEO REO
ogic.	Control logic injection attack [13] Dynamic Malware Payloads [113] Executing arbitrary ladder logic [71] Immediate Failure Attack [104] Latent Failure Attack [104] SABOT [115]	Modify Program	N	0 C 0 C 1 C 1 C 1 C 1 C 1 C 1 C 1 C 1 C)	3 -		Vulnerability Scanning Update Control Logic Limit Access to MCU R.	S7 N X	1	1020	1)	100	PRO PRO PRO
Contro	Ladder Logic Exfiltration [48] Leak Application data [175]	Exfiltration over Side-channel	U N	3 0) ()	10 1 -						\pm			\blacksquare
	S7-1200 Download Attack [31] S7-1500 Download Attack [31]	Program Download	S7	0 C) ()	20		l n . a	-	_		\pm	\downarrow		
	Denial of Engineering Operations [153]	Adversary-in-the-Middle	E	1 C		_	20	Optimised Datablocks [141]	Encrypt Sensitive Info.	S7	2	2	<u> </u>	ון כ	N/S	PRO
	CaFDI [116] Time-of-Day Attack [16] LogicLocker [60] Denial of Decompilation Attack [201] Stable Perturbation Attack [147]	Brute Force I/O Change Operating Mode Data Encrypted for Impact Denial of Service ICS Sector Discovery	M	2 0 1 0 0 C 0 C	0 0)))	2	PLC redundancy framework [87] Quad-redundant PLC [107] Digital twin-based simulation [50]	Redundancy of Service	E X N	2 2	3(2 (ı C	N/S	PRO PRO RE -
	Evil PLC Attack [146]	Lateral Tool Transfer		00		_	3 •			\vdash		+	+	+	\dashv	$+\!\!+\!\!\!+$
- 1	Targeted Manipulation of FB Operation [77]	Manipulate I/O Image	_	1 C	_		30			H	\vdash		+	\dashv	_	+
	Bricking the device [71] Compromise System Functions [202] Decrypting Siemens Simatic firmware [28] Firmware leakage [32] Firmware modification attack [24]	System Firmware	N SM P U	1 C 1 C 1 C 6 C	0 ()	30 20 10	AttkFinder [36] VETPLC [197] Similo [138] Logging input simulation [182] CPAC [55]	Process Vul. Discovery Auth. Enforcement	E E E X	1	1 2 2 2	1 C 2 C 1 C	0 1 0 1 0 9	N/S 100 99.9	PR O (RE O (DE O (PR O (
irmwa	Persistent denial-of-service attack [151] Remotely-triggered DoS [151]	Modify Program	E E	0 C) ()	2 O	Firmware verification tool [118]	Code Signing	x		1				PRO
	Time-based denial-of-service attack [151]	A C C T	Е	0 C				PLCDefender [144]	Attestation	Е	2	8		2	98	PR ● 0
- 1	Flash Update [145] HARVEY [65]	Activate Firmware Update Mode Data from Debug Port	E MC	0 C	+		2 O	•				+	+	\dashv	-	$+\!\!+\!\!\!+$
	Shutting down the PLC [71]	Device Restart/Shutdown	N	1 C	_	_	20			\vdash		+	+	+	\dashv	$+\!\!+\!\!\!+$
	Rogue Firmware Load [133] Leak I/O Process Data [175] Blinkware [174]	Module Firmware	E N X	1 C	0 0)	2	SNIFU [27] ORRIS [139]	Code Signing Antivirus/Antimalware	U X	-	2				PRO DEO
	Analog Emissions attack [98] PHYCO [66]	Exfiltration over Side-channel	N U	3 0)	10						\pm			
0	Escalated Privilege I/O Command [76] I/O Command attack [76]	Adversary-in-the-Middle	E	1 C) ()	20	Hidden Sensor Measurements [70] Physics-based attack detection [178]	Network Intrusion Detection	E	1	1	1 (ı C	N/S I	DEO
	Wireless Control [58] Malicious Expanders [58]	Spoof Reporting Message	N N				2 O	Blockchain Monitoring [39]	Encrypt Network Traffic	Е	T	3 (4	ı C	N/S	PR O
	False sequence attack [188]	Brute Force I/O	N	2				PCAT [156]	- Validate Program Inputs	Е	1	2				PR -
- 1 - 1	Manipulated Variable [10]	Manipulation of Control	X	20				Smart I/O Modules [132]				2				PR -
	OPC UA Supply Chain Attack [81]			00				PAtt [69]	Attestation	X	2	2		ر د	97	PRO
П	Backdoor Attack [181] Leak Crypto secrets [175] WaterLeakage [140]	Unauthorized Command Message Exfiltration over Side-channel	N	1 C) ()	2 - 1 - 1 O						\pm			#
		Change Operating Mode	_	0 C				Mitigate Malicious Disruption [37]	+	N	2	1	1 (c	N/S I	DE - (
	Clear PLC memory [184]	Data Destruction		0 C				CPS Twinning [52]	Redundancy of Service	M	_					REO
ory	ICS-BROCK [199]	Data Encrypted for Impact	U	3 C) ()	20	Armor PLC [198]				3				DE - C
em	Memory Dump [202]	Data from Debug Port		1 C			10			L	L	Ц	丄	_[$\perp \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \!$
Σ	Exfiltrate FB Variables [77]	Exfiltration over ICS Protocol		0 C			10	•		-	_	\dashv	+	4	_	\dashv
	Storage Based Covert Channel [77] DB content manipulation [110]	Fallback Channels Modify Parameter		0 C			1 0 ·			\vdash	\vdash	+	+	+	\dashv	+
	ROP Attack [23]	Process Injection		0 C			20			\vdash	\vdash	+	+	+	\dashv	+
	False Command Injection Attack [12]	Unauthorized Command Message		0 C			200		1	H	\vdash	\vdash	+	+	\dashv	+
-	Forcing a CPU Stop [145]		Е	0 C	•		20	WeaselBoard [123]	Exploit Protection	BP	3	3				PR●
	Crash CPU [145]	Device Restart/Shutdown		0 C				· C2 [114]	Exploit Flotection	N	2	2	1	ı C	N/S	PR O
	CPU Stop and Start Attack [28]			0 C			20			L	L	Ц	\perp	4	\Box	$\perp \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \! \!$
	S7-1200 Start/Stop Attack [31] S7-1500 Start/Stop Attack [31]	Change Operating Mode		0 C			2 O				\vdash	+	+	+		\pm
	ASIC Reverse Engineering	Supply Chain Compromise		6 C		$\overline{}$	6 0			-		$\overline{}$	-			

Table 2: A Summary of PLC Attack and Defense Methods (Control Logic, Firmware, I/O, Memory and CPU Components). S7=S7COMM, UA=OPC-UA, P=Profinet, E=EtherNet/IP, M=Modbus TCP, T=TriStation, SM=SoMachine, U=USB Port, MC=Memory Card, X=Others, O=OpenPLC, C=CODESYS, N=Not Specified, DE=Detection, PR=Prevention, RE=Recovery

sniffed and then used to gain access to protected actions in the PLC (e.g., start and stop PLC commands).

Attacks that Target the Control Logic. Two of the most important challenges for modifying the control logic of a PLC are 1) how to infect the PLC without being detected and 2) how to hide the infection from the engineering workstation. To address challenge 1, *Yoo and Ahmed* [194] propose two control logic infection attacks that bypass network intrusion detection systems (IDS). In the first attack, they bypass IDS that look for transfers of control logic (compile code) by injecting control code in data blocks and then modifying the execution pointer to execute code in data blocks. The second attack uses fragmentation and noise to further obfuscate these control logic transfers to the PLC.

Kalle et al. [89] target both challenges (infection and stealthiness). They consider a different problem in code injection, where they assume they have a binary they want to modify. They then develop a decompiler transforming low-level control logic to a high-level instruction list to help them inject the malicious code before recompiling it into a binary that can be uploaded to the vulnerable PLC. They also develop a virtual PLC that interfaces with the engineering workstation (via an AiTM attack); this virtual PLC then sends previously captured network traffic of the original uninfected control logic back to the workstation.

Attacks that Target the PLC CPU. As discussed in the extended version of this paper [105], PLCs generally have three CPU operating modes: "STOP," "RUN," and "PROGRAM." Attacks targeting the PLC CPU focus on disabling the CPU remotely (AL3 or AL2) with STOP commands. Beresford [28]'s work is an example of such attacks. *Biham et al.* [31] created a rogue engineering station that could remotely start or stop these newer PLCs by compromising a vulnerable key exchange protocol.

Passwords can protect CPU modes of operation, but a compromised password can still enable remote attacks. Higherend PLCs protect their CPU modes with physical methods, such as using a physical switch or a physical key. These methods are further discussed in the extended version of this paper [105].

Attacks that Target the PLC Firmware. Firmware modification is one of the most powerful attacks in any platform, as the attacker can control access to the input and output modules of the PLC while remaining undetected. *Basnight et al.* [24] pioneered methods on PLC firmware reverse-engineering and how to develop modified firmware as a proof of concept.

The most cited firmware attack paper in our study is Harvey [65]. The authors extracted firmware images from the update packages of the PLC vendor's website and the PLC memory through the JTAG interface of the PLC processor. Then they identified the subroutines that allowed them to modify the inputs and outputs for the PLC. To upload the firmware, they rely on vulnerabilities to protect remote firmware update functions (AL0, AL1 or AL2 in Fig. 4) or directly through

the JTAG interface (AL3 in Fig. 4).

Attacks that Target the PLC I/O. The two most cited papers targeting the inputs and outputs of the PLC focus on how to use input or output physical signals as covert channels to exchange information. For example, *PHYCO* [66] proposes a method where two compromised PLCs can talk to each other, even when a firewall exists between them. One PLC can send an output to increase power generation, and the other PLC can read the increased generation as a bit of information. Adversaries can also use the PLC I/O to exfiltrate data. *Krishnamurthy et al.* [98] illustrate how a PLC sending control commands to a motor can leak information about the status of a chemical plant.

Attacks that Target the PLC Runtime. An illustrative example of runtime attacks is provided by *Abbasi et al.* [2], by introducing Pin Control Attacks. This attack involves tampering with the SoC configuration within the PLCs, aiming to disrupt the communication between the PLC runtime and the hardware peripherals. By implementing this attack, the adversary severs the connection between the runtime software and the physical world, allowing them to manipulate the control data within the actual physical process.

Runtime attacks can also target the availability of the system; for example, *Gjendemsjø et al.* [71] proposed an XML Bomb Attack that causes the PLC runtime to crash by modifying an XML file.

Attacks that Target the PLC Operating System. There are not a lot of papers focusing on attacking the OS of PLCs. In their comprehensive study of the attack surface of a PLC, *Abbasi et al.* [4] touch upon an intriguing aspect of PLC security: the vulnerability of the Siemens Adonis Real-Time Operating System. Although their primary focus lies on the bootloader security of Siemens PLCs, they also explore security weaknesses inherent in the Adonis RTOS.

Attacks that Target the PLC Memory. Some network or control logic attacks target the memory of the PLC as part of their infection chain by modifying memory blocks or by getting memory dumps. The most cited efforts focused on developing worms stored in memory [140, 163].

So far, we have introduced the most cited examples of attacks per target, but we have not illustrated representative defenses. Because of limited space, we refer the reader to a discussion of defenses in the extended version of this paper [105].

6 Research Gaps

We now focus on identifying research gaps, and recommendations for future work by analyzing the data from Tables 1 and 2.

Most of the Attacks Require Zero Environment Knowledge. We found that 82% (97/119) of the attacks that may cause either *limited* (1) (36% (35/97)), *substantial* (2) (56% (54/97)), or *severe* (3) (8% (8/97)) damage require *zero*

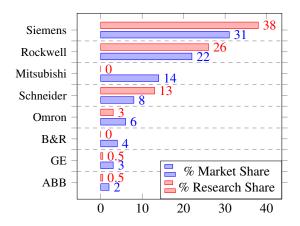


Figure 5: Comparison of Research Share vs Market Share.

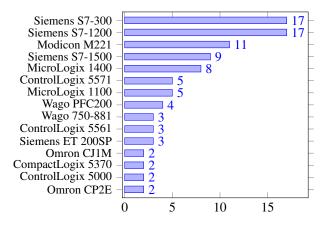


Figure 6: The 15 Most Common PLC Models.

knowledge (**O**) of the environment in which the PLC lives, following the description presented in Sec. 2.1 and the criteria discussed in Sec. 4.3. This may imply that adversaries can potentially launch non-trivial attacks against power grids, chemical plants, water treatment plants, etc. by targeting PLCs without having to invest time performing reconnaissance or learning the specifics of actuators, sensors, etc. Moreover, we were able to identify that only a few defense methods, e.g., Formby et al. [59] and Bellettini et al. [25], make use of such important environmental information. We therefore recommend that future defenses make use of environment knowledge in their strategy to increase their effectiveness.

The Security of Important PLC Brands Has Not Been Explored. We found that the security of some important PLC platforms widely used in practice has been ignored. As shown in Fig. 5, the *market* share percentage of important PLC manufacturers such as Mitsubishi, Omron, ABB, and GE is considerably higher than their *research* share, e.g., the number of papers explicitly using them for attack/defense evaluation purposes. For example, even though Mitsubishi PLCs account for 14% of the global market, they contribute to 0% of the research share in our review (they only appear once in our

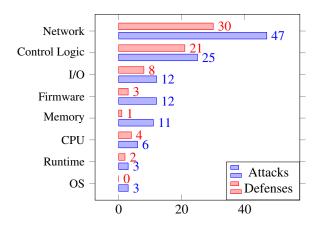


Figure 7: Defense vs Attack Methods per Target Component.

Grey literature survey [38]).

This means that there are potentially thousands of PLCs deployed in the world whose security has not been explored or may not have been adequately understood. We therefore recommend future lines of work specifically addressing these devices, exploring the effectiveness of existing attacks and defenses as discussed in this work, as well as the introduction of newer security methods tailored for them.

Lack of Defenses at the Recovery Stage. We found that most defense methods are designed for the Prevention (PR) and Detection (DE) stages discussed in Sec. 4.7, 47% (33/70) and 47% (33/70) out of 70 respectively, whereas the Recovery (RE) stage accounts for only 6% (4/70). This means that in the event of a successful attack there are limited options to recover and bring the PLC back to operation.

Most Attacks and Defenses are Evaluated on a Small Subset of PLCs. Our results show that the top 5 most common PLC models in our literature review (as shown in Fig. 6) account for 40% of all studies. This may result in a narrow understanding of PLC security that excludes the rest of the PLC models in the market. Additionally, we found that 80% (95/119) of attack methods and 81% (57/70) of defense methods were evaluated using a single HardPLC model (O). This means that most attack and defense methods are shown to work with a single HardPLC model, making it unclear whether or not the defense method can be generalized to other PLC models and manufacturers. Therefore, we recommend that future research include an evaluation of multiple PLCs.

Important Tactics have Little to No Research. Our ICS² Matrix includes 14 Tactics. However, as Fig. 8 shows, most of the attack methods focus on Impair Process Control, Inhibit Response Function, Exfiltration, Collection, and Persistence. On the other hand, important Tactics like Command and Control, Lateral Movement, Evasion, Credential Access, and Initial Access have not been investigated. One reason that might explain why these tactics have not been explored in previous research is that they are too specific or custom-fit. For ex-

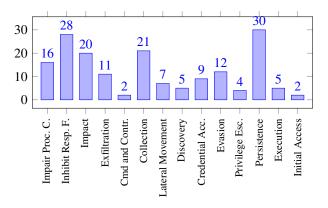


Figure 8: Attack Methods according to their Tactic.

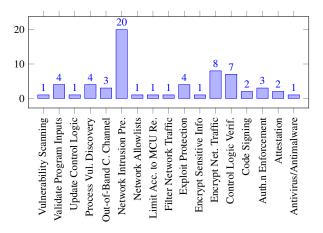


Figure 9: Defense Methods per Mitigation Category.

ample, the Command and Control tactic includes techniques such as Commonly Used Port and Standard Application Layer Protocol, which depend on specific network protocols and ports. This specific focus on network ports might limit the scope of research that can be carried out for this tactic.

Most Mitigation Strategies have Little to No Research. We found defense methods that match 17 Mitigation categories. However, as shown in Fig.9, the majority of these defenses fall into the Network Intrusion Prevention, Encrypt Network Traffic and Control Logic Verification categories. The remaining 14 Mitigation categories have only 4 or fewer defenses. These include important categories like Antivirus/Antimalware, Vulnerability Scanning, and Attestation, which are especially important given the rise of ICS malware such as the ones described in the extended version of this paper [105].

Weaknesses of State-of-the-Art Defenses Based on the results shown in Tables 1 and 2, we identified the following three major weaknesses when it comes to defending PLCs: 1) No ransomware detection. Even though researchers have shown that ransomware attacks against PLCs are possible [60, 199] and there are multiple documented ransomware attacks against ICS, there is no available research focused on how to

detect and stop PLC ransomware. To address this research gap, future research should introduce new defense methods that take advantage of state-of-the-art malware and ransomware detection techniques such as sandbox detection [179] and static and dynamic analysis [130]. 2) No web-based malware detection. Research shows that attackers target PLCs' web interfaces [106, 148] and that it is possible to compromise PLCs via their web applications [134]. However, there is no available research focused on how to detect and stop malware targeting PLCs' web interfaces. 3) No Exfiltration over Covert Channel Detection. This is one of the new techniques that we introduced in our ICS² Matrix, which includes methods such as PHYCO [66]. Introducing this technique lays the groundwork for identifying the need for mitigations against such techniques. Currently, there is no known mitigation for this type of attack. Indeed, in 2014 Garcia et al. wrote: "There has been no detection solution capable of identifying such hidden communications in the physical power system," [66] which still holds true.

Discussion

We now discuss research challenges that have not attracted enough attention and may become relevant as PLCs evolve.

Reproducible Research. Based on our analysis and the results presented in Tables 1 and 2, few defense and attack methods provide publicly available research artifacts. During our literature review, we searched for research artifacts for each paper. We searched the paper itself on Google and the author's website. We were able to find the source code for 19 papers (only 16%). This limits the reproducibility of attacks and defenses. In an attempt to find the artifacts for papers without openly available code, we contacted 91 authors via email requesting their research artifacts, receiving 16 responses (17.6%). Ultimately only 3 shared a research artifact. The other 13 did not share the source code for the following reasons: 1) The project was completed long ago or the first author moved on to a different institution (30%). 2) There were funding or distribution restrictions (25%). 3) The authors were working on it and will publish it later (15%). 4) There were no plans to release it to the public (30%). 16% is a low number of papers with artifacts, this does not even consider documentation quality or if they are easy to run. Therefore, we encourage researchers to release their PLC security artifacts so that research can be replicated and built upon and to leverage our PLC security artifacts repository discussed in Sec. 1 to disseminate their artifacts. We acknowledge that given the criticality of PLCs it is not always possible to release artifacts at the time of publication if at all. For example, the US' Cybersecurity & Infrastructure Security Agency (CISA) recommends researchers "provide us a reasonable amount of time to resolve the issue before you disclose it publicly [180]."

A second challenge that compounds the problem of lack of reproducible research is the absence of standardized perfor-

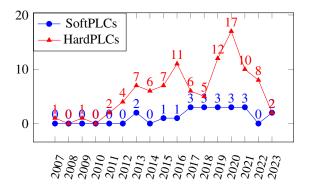


Figure 10: Papers evaluated using SoftPLCs vs HardPLCs.

mance metrics. Based on the results in Tables 1 and 2, few defense methods reported detailed PLC overhead or effectiveness metrics as described in Sec. 4.7. This makes comparing and building upon previous research almost impossible. To overcome this challenge we recommend that future defense methods report detailed quantifiable metrics. First, papers that propose methods such as Intrusion Detection Systems (IDS) should report a complete and detailed confusion matrix. The work by Salehi et al. [144] provides an excellent example. Second, future research on defense methods should report detailed and quantifiable benchmark metrics, e.g., memory overhead. Existing benchmarks such as *BenchmarkIoT* [11] can be customized for PLCs to overcome this challenge.

Transition from HardPLCs to SoftPLCs. As discussed in the introduction, PLCs are going through a paradigm shift with support for new protocols and new functionalities. Support for SoftPLCs appears to be increasing. While SoftPLCs currently have a minimal market share, large manufacturers like Siemens and Rockwell are preparing hardware-agnostic products [161]. This paradigm shift has also reached the scientific community. As shown in Fig. 10, PLC security research has diverged into two different strands: evaluations that use HardPLCs and evaluations that use SoftPLCs.

Considering this trend, future research should be aimed at addressing the following challenges: 1) Developing transitional defense methods that secure both HardPLCs and Soft-PLCs. For example, developing bump-in-the-wire solutions that are compatible with HardPLCs and SoftPLCs. This may involve evaluating research on both HardPLCs and SoftPLCs. 2) Investigating defense mechanisms available for SoftPLCs that were previously unavailable for HardPLCs. For example, HardPLCs' proprietary nature limited their access control and encryption capabilities by incorporating weak encryption protocols. SoftPLCs' less opaque architecture provides the opportunity to solve this problem. 3) Investigating both attack and defense methods that are possible only with SoftPLCs. For example, CODESYS' SoftPLCs can be connected to the cloud [42], which opens new ways to collect data that can be used to train machine learning-based IDS.

Related Work

SoKs on PLCs. To the best of our knowledge, the work by *Sun* et al. [168] is the only SoK focused on attacks and defenses on the control logic of PLCs. However, our work is different in two ways. First, Sun et al. focuses on PLCs' control logic, while we take a more comprehensive approach that includes 8 additional PLC components. Second, our SoK includes papers with practical evaluations, while Sun et al. focus on formal or theoretical research.

PLC Honeypots. While previous work includes approaches for PLC honeypots [62, 106], their focus is intelligence gathering rather than attacking PLCs.

Fuzzing and Binary Reverse Engineering. There is also noticeable research on fuzzing and reverse engineering for ICS and PLCs in the literature [56, 91, 127, 173, 183]. Our focus, however, is not on software analysis or patching but on outlining specific attacks.

Embedded Controllers. While they have received most of the attention in the security literature, PLCs are not the only embedded equipment in ICS. Remote Terminal Units (RTUs) and Intelligent Electronic Devices (IEDs) are even more prevalent in energy transmission systems and substation automation [131, 143, 167]. We need further research into the security of these other embedded controllers.

Conclusion and Future Work

In this paper, we provide a systematic review of currentlyknown attacks and defenses for PLCs. We also pointed out research gaps that should be tackled in the future so that the security of PLCs can be better understood, thus helping avoid future attacks against ICS and PLCs. We hope this systematization is useful to newcomers to the field as well as experienced PLC researchers looking to contextualize their work. As a part of Future Work, we are developing an experimental testbed as discussed in Sec. 2.1. This way, different attack and defense strategies can be replicated to provide experimental evidence on their effectiveness, deployability, and robustness, thus ultimately complementing the results provided in this work.

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Appendices

Appendix A Scientific and Grey Literature Resources

The seven digital libraries queried during our scientific literature review are as follows: ACM Digital Library⁷, arXiv⁸, dblp⁹, Google Scholar¹⁰, IEEExplore¹¹, USENIX Papers Search¹², and NDSS Symposium Search¹³.

The three main sources we queried during our grey literature review are as follows: Digital Bond Archives¹⁴, InfoconDB¹⁵, and Google¹⁶.

Search keywords.

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"plc", "programmable logic controller", "scada", "cps",
"cyber-physical system", "cyber physical system", "iiot",
"industrial internet of things", "industry 4.0",
"industrial control system", "ics", "embedded system",
"attack", "threat", "vulnerability", "defense"
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⁷https://dl.acm.org/

⁸https://arxiv.org/

 $^{^{9}}$ https://dblp.org/

¹⁰https://scholar.google.com/

¹¹https://ieeexplore.ieee.org/Xplore/home.jsp

¹²https://www.usenix.org/publications/proceedings/

¹³ https://www.ndss-symposium.org/

¹⁴https://dale-peterson.com/digital-bond-archives/

¹⁵https://infocondb.org/

¹⁶https://www.google.com/