

Characterizing the Location and Extent of Myocardial Infarctions With Inverse ECG Modeling and Spatiotemporal Regularization

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Abstract—Myocardial infarction (MI) is among the leading causes of death in the United States. It is imperative to identify and characterize MIs for timely delivery of life-saving medical interventions. Cardiac electrical activity propagates in space and evolves over time. Traditional works focus on the analysis of time-domain ECG (e.g., 12-lead ECG) on the body surface for the detection of MIs, but tend to overlook spatiotemporal dynamics in the heart. Body surface potential mappings (BSPMs) provide high-resolution distribution of electric potentials over the entire torso, and therefore provide richer information than 12-lead ECG. However, BSPMs are available on the body surface. Clinicians are in need of a closer look of the electric potentials in the heart to investigate cardiac pathology and optimize treatment strategies. In this paper, we applied the method of spatiotemporal inverse ECG (ST-iECG) modeling to map electrical potentials from the body surface to the heart, and then characterize the location and extent of MIs by investigating the reconstructed heart-surface electrograms. First, we investigate the impact of mesh resolution on the inverse ECG modeling. Second, we solve the inverse ECG problem and reconstruct heart-surface electrograms using the ST-iECG model. Finally, we propose a wavelet-clustering method to investigate the pathological behaviors of heart-surface electrograms, and thereby characterize the extent and location of MIs. The proposed methodology is evaluated and validated with real data of MIs from human subjects. Experimental results show that negative QRS waves in heart-surface electrograms indicate potential regions of MI, and the proposed ST-iECG model yields superior characterization results of MIs on the heart surface over existing methods.

Index Terms—Inverse ECG problem, myocardial infarction, spatiotemporal regularization, wavelet clustering.

1. INTRODUCTION

MYOCARDIAL infarction (MI), commonly known as heart attack, is among the leading causes of death throughout the world. It is shown that approximately every 40 seconds, an American will suffer a heart attack [1]. MI occurs

Manuscript received May 10, 2017; revised September 20, 2017 and October 28, 2017; accepted October 29, 2017. This work was supported in part by the National Science Foundation (CMMI-1646660) and in part by Harold and Inge Marcus Career Professorship (HY). (Corresponding author: Hui Yang.)

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Digital Object Identifier 10.1109/JBHI.2017.2768534

due to the blockage of coronary arteries. This will significantly decrease or stop the blood flow or oxygen supply to the heart, thereby damaging the heart muscle and triggering the heart attack. According to the American Heart Association, heart disease accounts for approximately 1 in 7 deaths in 2016, and there are about 790,000 people experience heart attacks annually in the United States [1]. MI is among the most expensive diseases for clinical diagnosis, medical treatment, and follow-up care. The economic costs of heart diseases are estimated to be around \$1,044 billion by 2030 [1]. The effective time window for MI treatments is within one hour from the onset of symptoms. Therefore, it is imperative to characterize and identify MIs in the early stage for timely delivery of optimal medical interventions and the improvement of heart health.

There are two categories of tests commonly used in clinical practice for the MI identification, namely structure imaging or functional sensing. Structure imaging is essentially frozen screenshots of heart structures. For example, computed tomography (CT) helps examine the inside structure of the heart and identify tissue damages. Magnetic resonance imaging (MRI) utilizes the magnetic fields to get images of the heart. Most of them are expensive tests conducted in a short period of time and are not always readily available. Even if routine examinations are performed multiple times each day, the intermittence still fails to detect life-threatening cardiac events [2]. Functional sensing captures a wealth of information pertinent to dynamic changes in cardiac conditions, e.g., electrocardiogram (ECG) signals. Cardiac dynamics over time are essential to monitor the progression of disease processes.

The 12-lead ECG is widely used for the identification of MIs by checking abnormalities in ECG wave deflections, e.g., significant Q waves, ST depression/elevation, or inverted T-waves. It may be noted that cardiac electrical activity propagates in space and evolves in time. One lead ECG captures 1-dimensional views of such space-time cardiac electrical activity. The 12-lead ECG systems provide 12-directional views of such space-time dynamics [3]. Most existing works [4], [5] focus on the analysis of time-domain ECG signals on the body surface for the detection of ECG wave deflections (i.e., P, QRS, T waves) on the body surface but tend to overlook spatiotemporal dynamics in the heart [4]–[6]. Time-domain ECG is a projected view of spatiotemporal cardiac electrical activity that diminishes important spatial information pertinent to heart diseases (e.g., myocardial infarction). Because distributed sensors at various locations

87 on the body surface respond to changes of heart conditions
 88 differently, body surface potential mapping (BSPM) employs
 89 hundreds of sensors to achieve high-resolution ECG sensing.
 90 High-resolution ECG images from BSPM facilitate the recon-
 91 struction of spatiotemporal distribution of electric potentials
 92 over the entire torso, and therefore provide richer information
 93 than 12-lead ECG for clinical decision making [7], [8].

94 However, ECG images provide the distribution of electri-
 95 cal potentials on the body surface. Clinicians call for the es-
 96 timation of heart-surface potentials to delineate pathological
 97 changes in the heart (e.g., infarct tissues). This is also called
 98 inverse ECG problem. Note that spatiotemporal ECG data and
 99 complex torso-heart geometries pose significant challenges on
 100 analytical modeling of the relationship between body-surface
 101 potentials $\phi_B(t)$ and heart-surface potentials $\phi_H(t)$. The high-
 102 dimensional predictive model, $\phi_B(t) = \mathbf{R}_{BH}\phi_H(t) + \epsilon$, is
 103 generally ill-conditioned. The transfer matrix \mathbf{R}_{BH} is derived
 104 based on torso-heart geometries and electromagnetic theory, but
 105 physics-based models do not account for real-world uncertain-
 106 ties (i.e., approximation errors and measurement noises), and
 107 therefore do not always match satisfactorily with data from
 108 real-world experiments. Our previous investigation developed a
 109 new methodology of spatiotemporal regularization (STRE) to
 110 solve inverse ECG problems, see details in [9]. This approach
 111 leverages ECG data to improve the spatial and temporal regular-
 112 arity of the solutions, thereby making more accurate predictions
 113 (closer to reality). Note that the STRE model involves both
 114 the spatial and temporal regularization terms, and is difficult to
 115 be solved analytically. We developed an iterative algorithm of
 116 dipole multiplicative update, inspired by the dipole assumptions
 117 in electrodynamic physics, to solve spatiotemporal regulariza-
 118 tion problems.

119 In this paper, we further investigate the application of
 120 the STRE model to reconstruct heart-surface potentials from
 121 BSPMs for MI characterization. Also, we develop a wavelet-
 122 clustering method to cluster time series of electrical potentials
 123 on the heart surface and thereby characterize the extent and lo-
 124 cation of the MIs. Specifically, our contributions in the present
 125 investigation are as follows:

126 1) *Wavelet clustering of heart-surface electrograms to dif-
 127 ferentiate healthy and infarcted regions:* It is common to iden-
 128 tify and characterize MIs by checking abnormalities of time-
 129 domain ECGs on the *body surface* (i.e., significant Q waves,
 130 ST depression/elevation, and inverted T waves). However, lit-
 131 ttle has been done to study pathological behaviors of *heart-
 132 surface* electrograms in the time-frequency domain. We solve
 133 the inverse ECG problem using the STRE model and pro-
 134 pose a wavelet-clustering method of heart electrograms to dif-
 135 ferentiate healthy and infarcted patterns. Different frequency
 136 bands of heart-surface electrograms are studied. Experimental
 137 results show approximation bands provide better characteriza-
 138 tion results than detailed bands. (See details in the experimental
 139 results.)

140 2) *Case studies on ECG images from human subjects:* First,
 141 we performed wavelet-clustering of the electrograms on the
 142 heart surface for two training cases. We studied different seg-
 143 ments of heart-surface ECGs, including the entire ECG cycle,

144 P wave, QRS wave, and T wave. Experimental results show that
 145 QRS clustering yields the best characterization of MIs based
 146 on the MRI images. Second, we validated the characterization
 147 results with the other two test cases, and found consistent re-
 148 sults that the cluster of negative QRS waves on the heart surface
 149 indicates potential infarction areas. The characterization results
 150 by the proposed methodology are further benchmarked with
 151 golden standards provided by Gadolinium-enhanced transaxial
 152 MRI (GE-MRI) images.

153 The rest of this paper is organized as follows: Section II intro-
 154 duces the research background of existing MI characterization
 155 methods and inverse ECG problems. Section III presents the re-
 156 search methodology of spatiotemporal inverse ECG model and
 157 wavelet clustering. Section IV describes the experimental design
 158 and results. Section V concludes the present investigation.

II. RESEARCH BACKGROUND

A. Characterizing MIs From BSPMs

161 BSPM employs hundreds of electrodes on the body surface
 162 and records the spatiotemporal distribution of electric poten-
 163 tials over the entire torso. Many previous studies characterized
 164 the size and location of MIs by investigating BSPMs. Simelius
 165 *et al.* [10] proposed the use of self-organizing maps to analyze
 166 and classify the spatiotemporal BSPM data and further local-
 167 ize the abnormal ventricular activation. Li and He *et al.* [11]
 168 and Farina *et al.* [12] proposed to determine the optimal extent
 169 and location of a spherical MI by minimizing the differences
 170 between the real-world BSPM data and the BSPM simulated
 171 from a heart model with infarctions. SadAbadi *et al.* [13] de-
 172 veloped a location relationship between the positions of BSPM
 173 sensors and regions of the heart, and further characterized the
 174 extent and location of MIs by investigating abnormal features
 175 in BSPM. Mneimneh *et al.* [14] proposed to use a reconstructed
 176 phase space and a Gaussian mixture model to create a multi-
 177 dimensional representation of the BSPMs to differentiate the
 178 electrical signals from healthy and infarct segments of the hu-
 179 man heart, and further quantify the MIs on the heart surface.

180 Although BSPMs provides the high-resolution distribution of
 181 electric potentials on the body surface, cardiac electrical activity
 182 is often blurred while propagating from the heart to the body,
 183 which diminishes important spatiotemporal characteristics per-
 184 pertinent to the MIs. The characterization methods by investigating
 185 BSPMs are therefore limited in the ability to quantify the extent
 186 and location of MIs on the heart surface. In order to delineate
 187 pathological changes in the heart, medical scientists call
 188 for the estimation of heart-surface electrograms from the high-
 189 resolution BSPMs and the complex torso-heart geometry, i.e.,
 190 the inverse ECG problem.

B. Inverse ECG Problem

191 The inverse ECG model is proposed to reconstruct heart-
 192 surface electrograms from BSPMs, and is further used to non-
 193 invasively image electrical activities of the heart. Two source
 194 models are commonly used in the inverse ECG problems.
 195 The first source model is called “action-based model”, where

197 the dominant feature of cardiac electrical activity is assumed
 198 to be the arrival timing of the depolarization wavefront at each
 199 location in the heart. In this model, the entire heart is modeled
 200 with finite element method instead of the epicardial surface [15],
 201 [16]. For example, Wang *et al.* [17] modeled the inverse ECG
 202 problem by constraining the solution on the electrophysiological
 203 model, i.e., the reaction-diffusion model, that guides the
 204 propagation of potential and recovery current.

205 The second source model is called "potential-based" model,
 206 which assumes that cardiac sources are represented by time-
 207 varying electrical potentials on the heart surface. Electromagnetic
 208 theory is integrated with boundary element method to
 209 model the relationship between potential distributions on the
 210 body and heart surfaces [9], [18]. Cheng *et al.* [19] compared the
 211 two source models and found there are no significant differences
 212 between the reconstructed heart-surface potentials. Nonetheless,
 213 the "activation-based" model requires modeling the entire heart,
 214 which introduces more imaging and computational efforts than
 215 the "potential-based" model [15], [20].

216 The present investigation will focus on the "potential-based"
 217 model. The relationship between the potential distributions on the
 218 body and heart surfaces is represented by a transfer matrix
 219 \mathbf{R}_{BH} . In order to calculate \mathbf{R}_{BH} , the human body is first mod-
 220 eled as a source-free homogeneous volume conductor, whose
 221 boundary consists of the heart and body surfaces. Second, the
 222 boundary element method is implemented to discretize the heart
 223 and body surfaces [21]. Finally, the electric potentials on the two
 224 surfaces are related by:

$$\phi_B = \mathbf{R}_{BH} \phi_H \quad (1)$$

225 in which ϕ_B and ϕ_H denote the potential distributions on the
 226 body and heart surfaces, respectively, and \mathbf{R}_{BH} incorporates
 227 both the torso-heart geometries and the electrical conducting
 228 properties of the human body [22].

229 However, the inverse ECG problem involves dynamic poten-
 230 tials distributed on the complex heart and body surfaces, and
 231 is generally ill-conditioned. The transfer matrix \mathbf{R}_{BH} is with
 232 large condition number (i.e., $cond(\mathbf{R}_{BH}) = \|\mathbf{R}_{BH}^{-1}\| \|\mathbf{R}_{BH}\|$),
 233 indicating that a small noise $\Delta\phi_B$ in ϕ_B caused by measurement
 234 equipment will result in a big difference $\Delta\phi_H$ in the estimation
 235 of ϕ_H (i.e., $\frac{\Delta\phi_H}{\phi_H} \simeq cond(\mathbf{R}_{BH}) \frac{\Delta\phi_B}{\phi_B}$). To address this prob-
 236 lem, different methods have been proposed, such as Tikhonov
 237 L2-norm [23] and L1-norm regularization methods [24], [25].
 238 These methods solve the inverse ECG problem individually at
 239 each time point, and do not account for temporal correlations
 240 among the time-varying electric potentials.

241 Brooks *et al.* [18] proposed to increase the spatial and tem-
 242 poral regularity of the inverse solution by simultaneously con-
 243 straining the magnitude or second-order spatial derivative and
 244 the first-order temporal derivative of heart-surface potentials.
 245 In order to solve the proposed model, they reformulated the
 246 problem with an augmented model, which resulted in a ma-
 247 trix representation with the dimension of $(N * T) \times (N * T)$,
 248 where N is the number of nodes on the heart surface and T is
 249 the length of the time series. The computation involves complex
 250 matrix-operations and the complexity will increase when the
 251 dimension (N or T) is getting large.

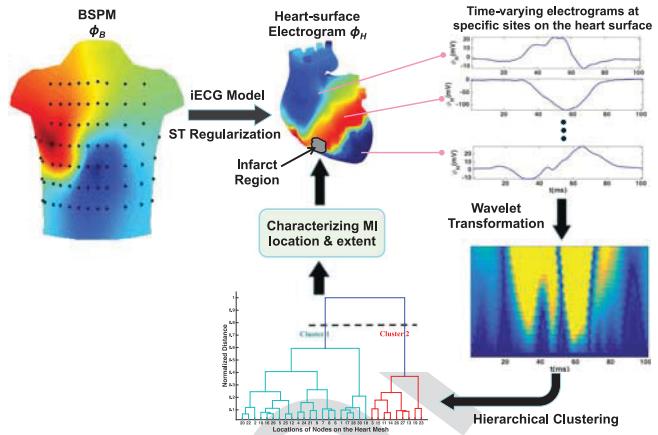


Fig. 1. The flowchart of research methodology.

252 Messnarz *et al.* [26] estimated cardiac electric potentials us-
 253 ing a spatiotemporal approach, in which they accounted for the
 254 spatial correlation by a symmetric gradient matrix, and formu-
 255 late the temporal constraint assuming that the potential signals
 256 are monotonically nonincreasing during depolarization phase.
 257 However, the torso-heart geometry is highly complex, and a
 258 symmetric matrix tends to be limited to approximate the surface
 259 gradient. Moreover, the nondecreasing assumption in the tem-
 260 poral constraint may not be generally applicable to real-world
 261 inverse ECG model.

262 Our previous work proposed a spatiotemporal regularization
 263 (STRE) model to solve the high-dimensional inverse ECG prob-
 264 lem [9]. We define a surface Laplacian for irregular triangle
 265 meshes to improve the spatial regularity of the inverse solution,
 266 and account for the temporal correlation by constraining the
 267 sum-of-square of the differences in potential signals in a small
 268 time window. In addition, we proposed an iterative method of
 269 dipole multiplicative update to solve the STRE model, which is
 270 inspired by the dipole assumption in electrodynamic physics.

271 However, very little has been done to identify and characterize
 272 MIs on the heart surface using the spatiotemporal regularization
 273 method. In this investigation, we utilize the STRE framework
 274 to solve the inverse ECG problem from BSPMs and torso-heart
 275 geometry, and further quantify the extent and location of MIs
 276 on the heart surface using a wavelet-clustering method.

III. RESEARCH METHODOLOGY

277 As shown in Fig. 1, this paper presents the application of spa-
 278 tiotemporal inverse ECG (ST-iECG) modeling to character-
 279 ize the location and extent of MIs. First, we reconstruct the time-
 280 varying heart-surface electrograms from BSPMs using the in-
 281 verse ECG modeling and spatiotemporal regularization method.
 282 Second, heart-surface electrograms are decomposed into mul-
 283 tiple frequency bands through the wavelet transformation. This
 284 time-frequency decomposition provides salient features to rep-
 285 resent disease-altered patterns in heart-surface electrograms.
 286 Finally, we performed the hierarchical clustering of wavelet
 287 coefficients to delineate the grouping behavior of heart-surface
 288 electrograms, which further help characterize the extent and
 289 location of MIs.

291 *A. Spatiotemporal Regularization*

292 BSPMs provide high-resolution distribution of electric po-
 293 tentials over the entire torso to delineate the spatiotemporal
 294 dynamics in the heart. Little has been done to reconstruct the
 295 electric potentials on the heart surface from BSPMs using spa-
 296 tiotemporal regularization method and further quantify the MIs.
 297 In the present investigation, we solve the inverse ECG problem
 298 from BSPMs and the torso-heart geometries using the STRE
 299 model, and will characterize the extent and location of MIs by
 300 investigating the reconstructed heart-surface electrograms. The
 301 objective function of the STRE model [9] is as follows:

$$\min_{\phi_H(t)} J = \sum_{t=1}^T \{ \|\phi_B(t) - \mathbf{R}_{BH} \phi_H(t)\|^2 + \lambda_s^2 \|\Delta_s \phi_H(t)\|^2 \\ + \lambda_t^2 \sum_{\tau=t-\frac{w}{2}}^{t+\frac{w}{2}} \|\phi_H(t) - \phi_H(\tau)\|^2 \} \quad (2)$$

302 where λ_s and λ_t are the spatial and temporal regulariza-
 303 tion parameters, respectively, which are chosen by L-curve method
 304 [27] or cross validation. The matrix Δ_s represents the spatial
 305 Laplacian operator of irregular triangle meshes and is proposed
 306 to improve the spatial regularity of the estimated potentials on
 307 the heart surface. The sum-of-square of the differences in elec-
 308 trical potentials in a time window w , i.e., the third term in (2), is
 309 proposed to increase model robustness to measurement noises
 310 in the time domain.

311 The STRE model involves both the spatial and temporal cor-
 312 relations among the electric potential ϕ_H , and it is difficult
 313 to solve for ϕ_H analytically. In our previous work, we pro-
 314 pose to estimate ϕ_H using the iterative method of dipole mul-
 315 tiplicative update (DMU) inspired by the dipole assumption in
 316 electrodynamic physics. Briefly, the DMU method splits the
 317 electric potential ϕ_H into its positive part ϕ_H^+ and negative
 318 part ϕ_H^- , where ϕ_H^+ and ϕ_H^- are defined as $\phi_H^+ = \max\{0, \phi_H\}$
 319 and $\phi_H^- = \max\{0, -\phi_H\}$. And then, we can write ϕ_H as
 320 $\phi_H = \phi_H^+ - \phi_H^-$, and obtain the updating rules for ϕ_H^+ and
 321 ϕ_H^- in the algorithm shown in Table I (see details in [9]).

322 *B. Wavelet Decomposition of Heart-Surface
 323 Electrograms*

324 The time series data such as heart-surface electrograms ϕ_H
 325 are generally characterized by high dimensionality, high corre-
 326 lation, uncertainties and measurement noises. Traditional time-
 327 domain investigation tends to overlook hidden information in-
 328 herent in original signals (e.g., spatial information pertinent to
 329 MIs). Frequency-domain analysis such as Fourier transforma-
 330 tion identifies spectral components present in the signal but does
 331 not provide temporal localization of these components. Meth-
 332 ods of time-frequency analysis such as wavelet transforma-
 333 tion provide interpretation of time series in both time and frequency
 334 simultaneously, which enables the delineation of local, transient
 335 or intermittent components inherent to the data.

336 In the present investigation, we propose to transform the elec-
 337 trograms on the heart surface with the Daubechies wavelet [28].
 338 Note that most of the previous works show that the closer the

339 wavelet functions match the signal pattern, the more compact
 340 the representation will be [29]. The heart electrogram ϕ_H is
 341 denoted as $\{\phi_H(t)\}_{t=1}^T$ and is decomposed into the running aver-
 342 ages $A_j(k)$ to approximate the original time sequence, and
 343 running differences $D_j(k)$ to characterize the details of the
 344 time series ϕ_H , where $j = 1, 2, \dots$ denotes the decomposition
 345 level (i.e., scaling value) and $k = 1, 2, \dots$ represents the pos-
 346 ition (i.e., translation value). $A_j(k)$ and $D_j(k)$ are defined
 347 recursively as

$$A_j(k) = \sum_{t=1}^T h_j A_{j-1}((2k+t) \bmod 2^{j+2}) \quad (3)$$

$$D_j(k) = \sum_{t=1}^T (-1)^t h_j A_{j-1}((2k+2T-t) \bmod 2^{j+2}) \quad (4)$$

$$A_1(k) = \sum_{t=1}^T \phi(t) V_n(t-k) \quad (5)$$

348 where h_j 's are filter coefficients of the Daubechies scaling func-
 349 tion, and the scaling function $V_n(t)$ and wavelet function $W_n(t)$
 350 are defined recursively as

$$V_n(t) = \sqrt{2} \sum_{k=0}^{2n-1} h_k V_n(2t-k) \quad (6)$$

$$W_n(t) = \sqrt{2} \sum_{k=0}^{2n-1} (-1)^k h_{2n-1-k} V_n(2t-k) \quad (7)$$

351 Thus, at level j of decomposition, ϕ_H is expressed as

$$\phi_H(t) = \sum_k A_j(k) V_n\left(\frac{t}{2^j} - 2^j k\right) \\ + \sum_{j'=1}^j \sum_k D_{j'}(k) W_n\left(\frac{t}{2^{j'}} - 2^{j'} k\right) \quad (8)$$

352 The wavelet decomposition provides an effective framework
 353 of multi-resolution analysis for investigating the heart-surface
 354 electrogram ϕ_H at various levels of approximations A_j 's and de-
 355 tails D_j 's. This multi-resolution framework will better elucidate
 356 both the local and transient characteristics of ϕ_H that are often
 357 obscured by the traditional time-domain or frequency-domain
 358 analysis.

359 *C. Hierarchical Clustering*

360 Hierarchical clustering (HC) algorithm is further used to clus-
 361 ter each sequence of running average A_j 's and running differ-
 362 ence D_j 's of heart-surface electrogram $\phi_H(t)$ at different level
 363 j . The HC algorithm creates a hierarchical decomposition of
 364 the input data represented by a dendrogram. The dendrogram is
 365 constructed according to the $N \times N$ distance (similarity) ma-
 366 trix given by the N observations (i.e., N ECG time series) in
 367 the dataset. (Note in the present investigation, N is the number
 368 of nodes on the heart surface.) At the first step of HC, each
 369 observation is assigned to its own cluster, which results in N
 370 singleton clusters. Then, the closest (i.e., most similar) pair

TABLE I
THE PROPOSED DIPOLE MULTIPLICATIVE UPDATE ALGORITHM

```

1: Set constants  $\lambda_s$ ,  $\lambda_t$  and  $w$  .
2: Initialize  $\{\phi_H^+\}$  and  $\{\phi_H^-\}$  as positive random matrices: whose columns
   (rows) denote different time points (different nodes on the heart surface)
3: Repeat
4:   for  $t = 1, \dots, T$  do
5:      $(\phi_{H,t}^+)_i \leftarrow \frac{(\mathbf{A}\phi_{H,t}^-)_i + B_i + \sqrt{((\mathbf{A}\phi_{H,t}^-)_i + B_i)^2 + 4(\mathbf{A}^+\phi_{H,t}^+)_i(\mathbf{A}^-\phi_{H,t}^+)_i}}{(2\mathbf{A}^+\phi_{H,t}^+)_i} (\phi_{H,t}^+)_i$ 
6:      $(\phi_{H,t}^-)_i \leftarrow \frac{(\mathbf{A}\phi_{H,t}^+)_i - B_i + \sqrt{((\mathbf{A}\phi_{H,t}^+)_i - B_i)^2 + 4(\mathbf{A}^+\phi_{H,t}^-)_i(\mathbf{A}^-\phi_{H,t}^-)_i}}{(2\mathbf{A}^+\phi_{H,t}^-)_i} (\phi_{H,t}^-)_i$ 
7:     where
8:      $\mathbf{A} = \mathbf{R}_{BH}^T \mathbf{R}_{BH} + \lambda_s^2 \Delta_s^T \Delta_s + 2\lambda_t^2 w \mathbf{I}$ 
9:      $\mathbf{B} = \phi_B^T(t) \mathbf{R}_{BH} + 2\lambda_t^2 \sum_{\tau=t-w/2}^{t-1} \phi_H^T(\tau) + 2\lambda_t^2 \sum_{\tau=t+1}^{t+w/2} \phi_H^T(\tau)$ 
10:   end for
11: until convergence

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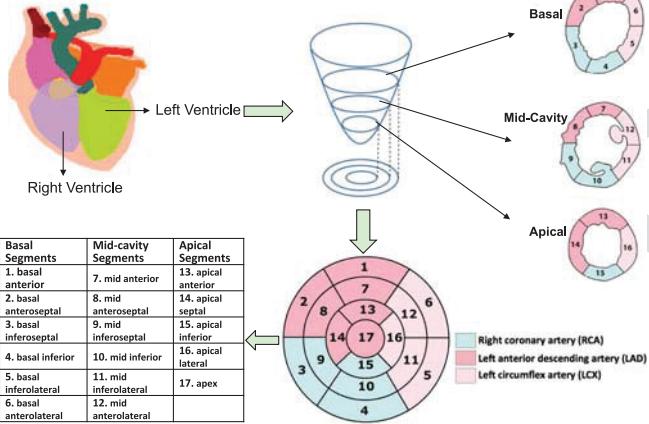


Fig. 2. 17-segment model of the left ventricle.

371 of clusters is merged into one single cluster. The recursive
372 merging strategy continues to move up the hierarchy until
373 all the observations are clustered into one single cluster of
374 size N .

375 The optimal number of clusters is chosen by the Silhouette
376 index. Let $\mathcal{C} = \{C_1, \dots, C_K\}$ denote the K clusters of the data
377 set. The j^{th} cluster is defined as $C_j = \{\phi_1^j(t), \dots, \phi_{n_j}^j(t)\}$, and
378 $n_j = |C_j|$ is the cardinality of the j^{th} cluster. Let $d(\phi_k(t), \phi_l(t))$
379 denote the distance between $\phi_k(t)$ and $\phi_l(t)$. Then the Silhouette
380 index with K clusters is defined as:

$$S_K = \frac{1}{K} \sum_{j=1}^K \frac{1}{n_j} \sum_{i=1}^{n_j} \frac{b_i^j - a_i^j}{\max\{a_i^j, b_i^j\}} \quad (9)$$

381 where a_i^j is the average distance between the i^{th} observation
382 in cluster C_j and the other observations in the same cluster,
383 b_i^j denotes the minimum average distance between the i^{th} ob-
384 servation in C_j and all the observations in C_k , $k = 1, \dots, K$,

$k \neq j$.

$$a_i^j = \frac{1}{n_j - 1} \sum_{k=1, k \neq i}^{n_j} d(\phi_i^j(t), \phi_k^j(t)) \quad (10)$$

$$b_i^j = \min_{m=1, \dots, K, m \neq j} \left\{ \frac{1}{n_m} \sum_{k=1}^{n_m} d(\phi_i^j(t), \phi_k^m(t)) \right\} \quad (11)$$

385 The value of S_K is between -1 and 1, and a bigger S_K indicates
386 better clustering result. Therefore, the optimal number of cluster
387 K^* is chosen as
388

$$K^* = \arg \max_K S_K \quad (12)$$

389 Furthermore, A_j 's and D_j 's are clustered into K^* clusters
390 using the HC algorithm. The clustering results are further used
391 to characterize the extent and location of MIs on the heart surface
392 in the experiment.

D. Performance Metrics

393 Gadolinium-enhanced transaxial MRI (GE-MRI) images pro-
394 vide the golden standards to evaluate the performance of the
395 ST-iECG model. The extent, centroid and location of infarc-
396 tion area on the heart surface are presented by the 17-segment
397 model [30] as shown in Fig. 2. In the 17-segment model, the left
398 ventricle (LV) is first segmented into three coarse parts: basal,
399 apical and mid-cavity along its long axis from the apex of LV
400 to the base. Furthermore, the basal area and the mid-cavity are
401 divided into six finer segments, respectively, and the apical area
402 is divided into four finer segments. The name of each segment
403 is displayed in Fig. 2.

404 Three performance metrics are defined to evaluate the perfor-
405 mance of the proposed ST-iECG model:

- 406 1) **EPD**-percentage discrepancy between the extent of in-
407 farction as estimated and as given by GE-MRI images;
- 408 2) **SO**-overlap percentage between infarct segments as esti-
409 mated and as given by GE-MRI images;

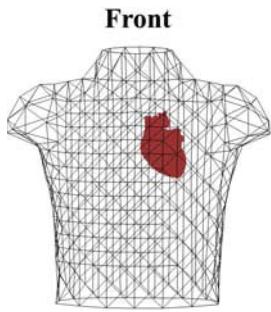


Fig. 3. Torso-heart geometry.

411 3) CED-distance from the centroid of the infarct area as
 412 given by GE-MRI images to that as estimated.
 413 The three metrics of the proposed ST-iECG model are further
 414 benchmarked with the results provided by the existing iECG
 415 model [23] in the next section.

416 IV. EXPERIMENTAL DESIGN AND RESULTS

417 A. Dataset

418 The dataset in this investigation including the customized
 419 torso-heart geometry (as shown in Fig. 3) and body surface
 420 potential mapping (BSPM) is sourced from the PhysioNet web-
 421 site [23], [31]. The BSPMs are collected from four patients
 422 who carried one-year MIs, which contain time series of electric
 423 potentials from 0 to 1000 ms at 352 locations on the body
 424 surface. These four cases are split into two training cases and two
 425 test cases. The true MI segments for each patient are outlined by
 426 the GE-MRI images, which provides the reference for evaluating
 427 the performance of the ST-iECG model.

428 B. The Impact of Mesh Resolution on Inverse ECG 429 Modeling

430 In potential-based inverse ECG problem, the transfer ma-
 431 trix \mathbf{R}_{BH} is computed by integrating electromagnetic theory
 432 and boundary element method (BEM). In BEM, the torso-heart
 433 geometries are discretized into triangle meshes to numerically
 434 solve the Laplacian equation that establishes the relationship be-
 435 tween ϕ_H and ϕ_B . The solution integrals are approximated by
 436 the summation of a series of numerical integrations over triangle
 437 elements. The approximation accuracy is closely dependent on
 438 the mesh resolution, which impacts the estimation of the inverse
 439 ECG problem. Few, if any previous works studied the effects
 440 of mesh resolution on the inverse ECG solution. At the present
 441 investigation, we study the effects of mesh resolution on the
 442 solution to inverse models in order to find the optimal mesh
 443 resolution [21].

444 We vary the number of elements N_T on the triangle mesh of
 445 the heart surface by setting it to be 136, 272, 408, 546, 654, 872
 446 and 1092. Fig. 4 is an illustration of the triangle mesh and the
 447 3D heart model. Under different mesh resolution, we solve the
 448 inverse problem and investigate the variation of mean squared
 449 error (MSE) with respect to N_T as shown in Fig. 5. Note that
 450 in order to calculate MSE, the estimated heart-surface potential
 451 $\phi_H(t)$ is used to predict the body-surface potential from the

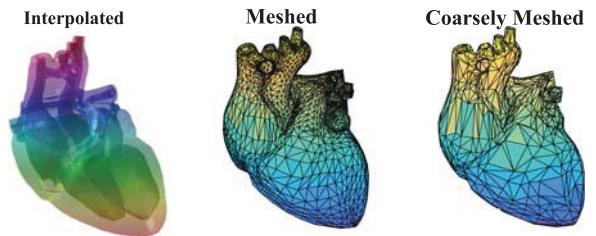


Fig. 4. Illustration of the interpolated 3D heart model and triangle meshes of the heart surface.

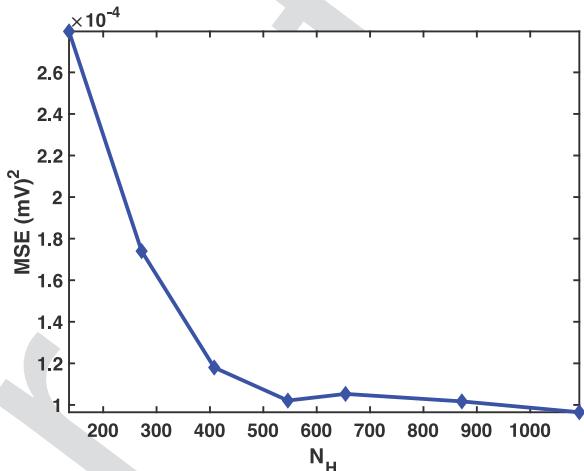


Fig. 5. The variation of mean squared errors with respect to the number of triangle elements N_T on the heart mesh.

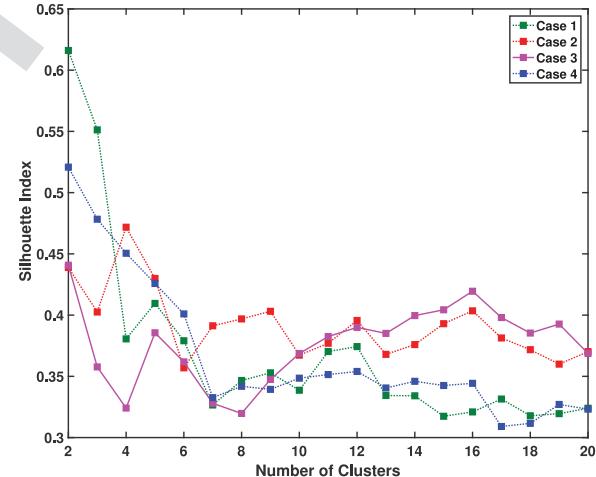


Fig. 6. The variation of Silhouette index with respect to different number of clusters for the 4 cases.

forward ECG model, i.e., $\hat{\phi}_B(t) = \mathbf{R}_{BH} \phi_H(t)$. Then the MSE 452 is computed as 453

$$MSE = \frac{\sum_{t=1}^T \|\hat{\phi}_B(t) - \phi_B(t)\|}{T \times N_B} \quad (13)$$

where $\phi_B(t)$ is real data of body-surface potentials, T is the 454 length of time series, and N_B is the number of nodes on the 455 body surface. 456

According to Fig. 5, the MSE decreases as the number of 457 triangles increases. Moreover, when N_T exceeds 400, the value 458

TABLE II
 RESULTS OF MI CHARACTERIZATION WITH WAVELET CLUSTERING IN TRAINING CASE 1 AND CASE 2

MI Characterization	GE-MRI	Signal	A1	A2	A3	A4	A5	A6	D1	D2	D3	D4	D5	D6	
Case 1	Extent	31%	24%	34%	34%	32%	22%	24%	25%	61%	38%	23%	40%	26%	26%
	MI segments	1, 2, 3, 8, 9, 1, 2, 3, 8, 9, 2, 3, 5, 7, 8, 9, 1, 2, 3, 8, 9, 13, 14, 15, 16, 11, 13, 14, 13, 15, 16	1, 2, 3, 8, 9, 13, 15, 16	1, 2, 3, 8, 9, 13, 15, 16	1, 2, 3, 8, 9, 13, 15, 16	1, 2, 3, 8, 9, 13, 15, 16	1, 2, 3, 8, 9, 13, 15, 16	1, 2, 3, 8, 9, 13, 15, 16	1, 2, 3, 4, 5, 7, 8, 9, 12, 13, 1, 4, 15, 17	1, 2, 3, 5, 7, 8, 9, 12, 13, 14, 15, 17	2, 3, 6, 8, 9, 10, 14	1, 2, 3, 5, 8, 9, 11, 12, 13, 14, 17	1, 2, 3, 4, 7, 8, 9, 14, 15, 16	1, 2, 3, 4, 7, 8, 9, 14, 15, 16	
	Centroid	8	8	8 or 9	8	8	8	8	14	13	9	14	8 or 9	8 or 9	
	EPD	-	7%	3%	3%	1%	9%	7%	6%	30%	7%	8%	9%	5%	5%
	SO	-	67%	50%	67%	67%	67%	67%	56%	50%	45%	54%	58%	58%	
	CED	-	0	0	0	0	0	0	1	2	0	0	0	0	
Case 2	Extent	30%	17%	19%	28%	20%	18%	28%	36%	43%	21%	36%	43%	26%	31%
	MI segments	3, 4, 9, 10	3, 5, 9, 10	3, 5, 9, 10	1, 3, 5, 9, 10, 1, 3	3, 5, 9, 10	3, 5, 9, 10	1, 3, 4, 7, 9, 15, 17	1, 3, 5, 7, 9, 10, 13, 14, 15, 1, 6	1, 3, 4, 7, 9, 10, 12, 13, 15, 1	3, 4, 7, 9, 15	1, 3, 5, 9, 10, 1, 14, 17	1, 2, 5, 7, 9, 10, 11, 13, 17	1, 3, 4, 7, 9, 10, 15	1, 3, 4, 7, 9, 10, 15
	Centroid	3 or 4 or 9 or 10	10	10	9	10	10	9	14	15	9	10	13	15	15
	EPD	-	13%	11%	2%	10%	12%	2%	6%	13%	9%	6%	13%	4%	1%
	SO	-	60%	60%	42%	60%	60%	37.50%	30%	40%	50%	33%	18%	57%	57%
	CED	0	0	0	0	0	0	1	1	0	0	3	1	1	

459 of MSE remains relatively stable and little improvement can be
 460 achieved if we further increase the number of triangle elements.
 461 The value of N_T should be greater than 400 to guarantee the
 462 accuracy of the inverse model, but should not be very large
 463 to make the inverse model computationally expensive. In this
 464 investigation, we therefore set the number of mesh elements
 465 triangulating the heart surface to be 546, which is the elbow
 466 point between $N_T = 500$ and $N_T = 600$.

467 C. MI Characterization With Wavelet Clustering

468 The body surface consists of 677 triangle elements and 352
 469 nodes, and the heart surface is formed with 546 triangle el-
 470 ements and 275 nodes, which results in a 352×275 transfer
 471 matrix \mathbf{R}_{BH} . The ST-iECG method with $\lambda_s = 0.06$, $\lambda_t = 0.005$
 472 chosen by L-curve method and $w = 2$ is implemented to solve
 473 the potential distribution ϕ_H on the heart surface. The QRS
 474 interval (represents ventricular depolarization) of estimated po-
 475 tential signals on the heart surface are grouped into different
 476 clusters by the HC algorithm with the cluster number varying
 477 from 2 to 20. Note that we conducted experiments to study
 478 different segments of heart-surface electrograms, including the
 479 entire ECG cycle, P wave, QRS wave, and T wave. Experimental
 480 results show that clustering of QRS wave yields the best char-
 481 acterization results. This agrees with the fact that QRS wave
 482 corresponds to the ventricular depolarization. Therefore, in this
 483 investigation we characterize the MIs using the QRS waves of
 484 the heart-surface electrograms.

485 Fig. 6 shows the variation of Silhouette index with respect to
 486 the cluster number of the four cases. Notably, cases 1, 3 and 4
 487 yield the highest Silhouette index when the number of clusters
 488 is two. This shows that two different clusters exist in the heart-
 489 surface electrograms. One cluster denotes signals from healthy
 490 segments and the other represents signals from infarct segments
 491 on the heart surface. In case 2, the Silhouette index is higher with
 492 four clusters than that with two clusters. This may be due to the
 493 existence of inhomogeneous tissues and cellular structures in the

infarction regions of case 2. Such inhomogeneity leads to more variations in heart-surface electrograms, which can be further partitioned into sub-clusters. In other words, the big cluster is further split into three sub-clusters. In the present investigation, the number of cluster is selected as two so as to achieve the overall highest Silhouette index for four cases. 499

The calculated ϕ_H in training case 1 and case 2 is further decomposed into running averages A_j 's and running difference D_j 's with $j = 1, 2, 3, 4, 5, 6$ by Daubechies wavelet. The estimated signal ϕ_H , each A_j and D_j are grouped into two clusters by the HC algorithm. [Table II](#) shows the characterization results estimated by the wavelet-clustering method and the reference results given by the GE-MRI images. Note that characterization of MIs by the approximation levels A_j 's generally yield better performance metrics, i.e., lower EPD, higher SO, and lower CED. This suggests that the characteristics in transient parts (high-frequency details, D_j 's) in the heart electrograms may not relate to useful information pertinent to MIs. It is worth noting that in training case 1, A3 (i.e., the approximation at level $j = 3$) yields the smallest EPD of 1%, highest SO of 67%, and CED of zero. In training case 2, A3 yields a zero CED and the highest SO of 60%. Therefore, A_3 is chosen as the optimal representation of ϕ_H , and is grouped into healthy and infarct clusters to further characterize the MIs on the heart surface in later experiments.

D. Characterization Results in Training Case 1 and Case 2

Fig. 7(a) shows the average potential signals \pm standard deviation of two clusters denoting onset of infarction and normal heart activity of training case 1 by the proposed ST-iECG model. Note that although significant variations exist in the clusters of onset of infarction and normal heart activity due to the heart geometry and disease complexity, the cluster colored in blue contains more positive signals, while the one in red consists of negative signals, particularly, a negative Q wave. Fig. 7(b) shows

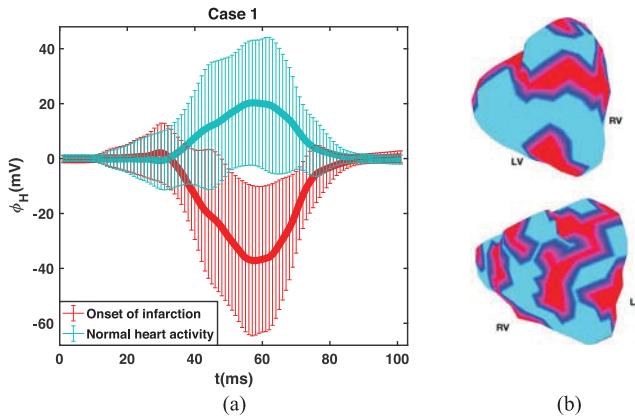


Fig. 7. (a) Average potential signals \pm one standard deviation of the clusters of normal heart activity and onset of infarction in training case 1; (b) Color-coded distribution of the two clusters on the heart surface with inferior view (top) and anterosuperior view (bottom).

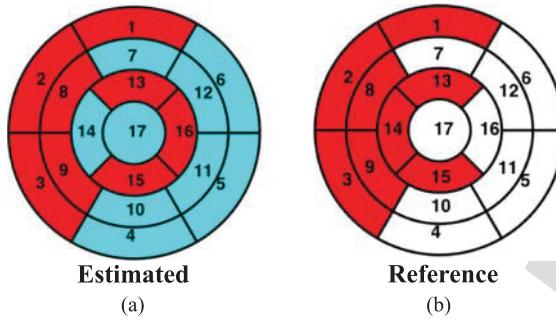


Fig. 8. (a) Estimated MIs (i.e., segments colored in red) by the proposed ST-iECG model of training case 1; (b) Reference MIs (i.e., segments colored in red) provided by the GE-MRI image of training case 1.

529 the color-coded 3D heart surface with red and blue colors representing the infarct and normal clusters respectively. The 3D
530 heart surface is then projected into the 17-segment model, as
531 shown in Fig. 8(a). The true infarct segments (colored in red)
532 given by the GE-MRI image is shown in Fig. 8(b). By comparing
533 the segments of each cluster estimated by the ST-iECG
534 model with the true infarct segments, the red cluster, i.e., the
535 one contains negative Q wave, is identified as the cluster of
536 onset of infarction, while the blue one, i.e., the one contains
537 more positive signals, is specified as the cluster of normal heart
538 activity.

539 As shown in Fig. 8(a), the estimated infarct segments (i.e.,
540 the segments colored in red) are 1, 2, 3, 8, 9, 13, 15 and 16 in
541 case 1. The true infarct segments given by GE-MRI image are
542 1, 2, 3, 8, 9, 13, 14 and 15 as shown in Fig. 8(b). The extent
543 of infarction is obtained by dividing the number of the infarct
544 nodes on the heart surface by the total number of nodes, which
545 is 32% in case 1, and is close to the GE-MRI result of 31%.
546 In addition, it can be noted from Fig. 8(a) that the centroid of
547 the estimated infarct segments is segment 8, which matches the
548 centroid given by the GE-MRI image.

549 Fig. 9(a) illustrates average potential signals \pm one standard
550 deviation of the clusters of normal heart activity and onset of
551 infarction in training case 2 by the proposed ST-iECG model.
552 Notably, the magnitude of negative potentials in the blue cluster

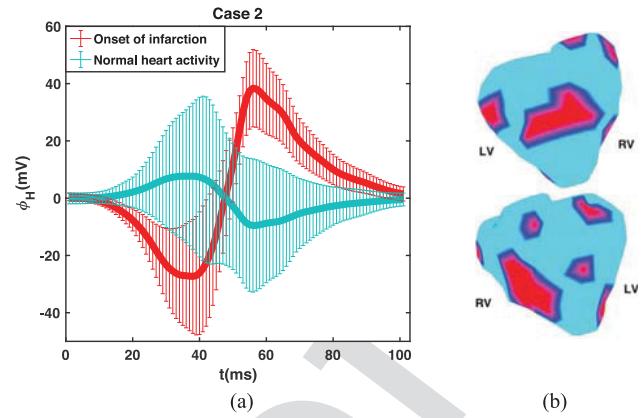


Fig. 9. (a) Average potential signals \pm one standard deviation of the clusters of normal heart activity and onset of infarction in training case 2; (b) Color-coded distribution of the two clusters on the heart surface with inferior view (top) and anterosuperior view (bottom).

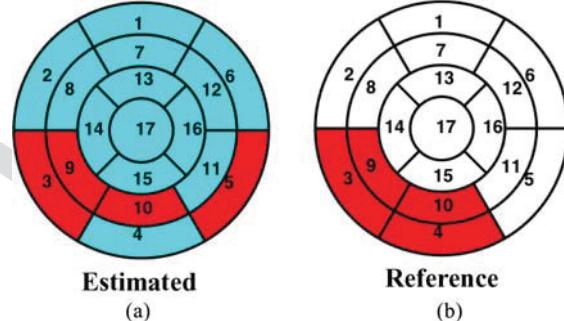


Fig. 10. (a) Estimated MIs (i.e., segments colored in red) by the proposed ST-iECG model of training case 2; (b) Reference MIs (i.e., segments colored in red) provided by the GE-MRI image of training case 2.

553 is much smaller compared with that in the red cluster. Fig. 9(b)
554 shows the color-coded heart surface with red and blue colors
555 representing the two different clusters. The corresponding 17-
556 segment model is shown in Fig. 10(a), and Fig. 10(b) shows
557 the true infarct clusters (colored in red) given by the GE-MRI
558 image. Comparing the two clusters estimated by the proposed
559 ST-iECG model with the true infarct segments of case 2, the
560 red cluster is identified as the infarct cluster, while the blue one
561 denotes the normal cluster, which is consistent with the training
562 result in case 1.

563 As shown in Fig. 10(a), the estimated infarct segments (i.e.,
564 segments colored in red) are 3, 5, 9 and 10 in case 2. The true
565 infarct segments are 3, 4, 9 and 10 given by the GE-MRI image
566 as shown in Fig. 10(b). The estimated extent of infarction in
567 case 2 is 20% which is not too far away from 30% given by
568 the GE-MRI analysis, and the estimated centroid is segment 10
569 matching the centroid given by GE-MRI image.

E. Characterization Results in Test Case 3 and Case 4

572 Fig. 11(a) shows the average potential signals \pm one standard
573 deviation of the two clusters representing onset of infarction and
574 normal heart activity estimated by the proposed ST-iECG model
575 in test case 3. According to the experimental results in training
576 case 1 and case 2 in subsection D, the red cluster containing

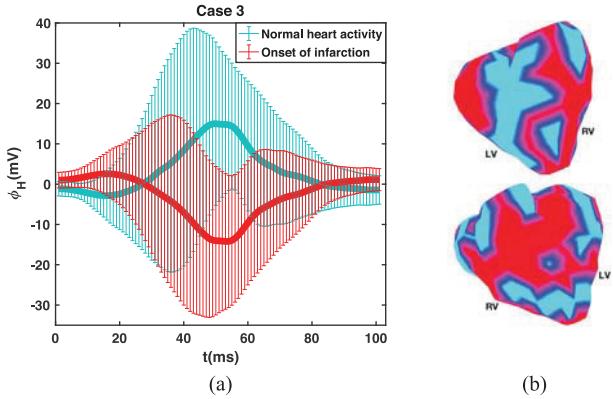


Fig. 11. (a) Average potential signals \pm one standard deviation of the clusters of normal heart activity and onset of infarction in test case 3; (b) Color-coded distribution of the two clusters on the heart surface with inferior view (top) and anterosuperior view (bottom).

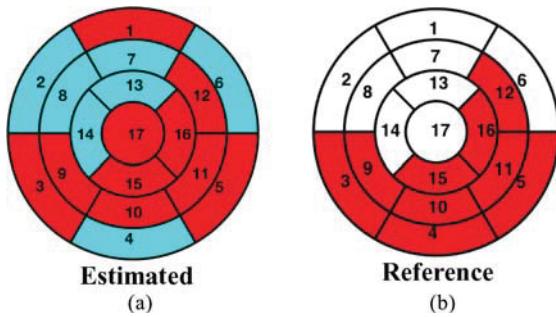


TABLE III
RESULTS FROM THE PROPOSED ST-iECG MODEL, EXISTING iECG MODEL [23], AND GE-MRI IMAGES

Characteristic	Method	Case 1	Case 2	Case 3	Case 4
Extent	GE-MRI	31%	30%	52%	14%
	iECG	25%	35%	35%	40%
	ST-iECG	32%	20%	51%	29%
Infarct Segments	GE-MRI	1, 2, 3, 8, 9, 13, 14, 15	3, 4, 9, 10	3, 4, 5, 9, 10, 11, 12, 15, 16	1, 9, 10, 11, 15, 17
	iECG	2, 3, 8, 9, 14	3, 4, 5, 9, 10, 11	3, 4, 5, 10, 11	3, 4, 5, 6, 9, 10, 11
	ST-iECG	1, 2, 3, 8, 9, 13, 15, 16	3, 5, 9, 10	1, 3, 5, 9, 10, 11, 12, 15, 16, 17	1, 4, 5, 7, 9, 15, 17
Centroid	GE-MRI	8	3 or 9 or 4 or 10	10 or 11	15
	iECG	9	10	4	4
	ST-iECG	8	10	11 or 15	15

TABLE IV
COMPARISON OF PERFORMANCE METRICS OF THE PROPOSED ST-iECG MODEL AND THE EXISTING iECG MODEL [23]

Metric	Method	Case 3	Case 4
EPD	iECG	17%	26%
	ST-iECG	1%	15%
SO	iECG	0.556	0.3
	ST-iECG	0.727	0.444
CED	iECG	1	2
	ST-iECG	0	0

Notably, the estimated centroids by the proposed ST-iECG model in all the training and test cases match that given by GE-MRI images, while there are discrepancies in the extent and segments of infarction between the estimated and true results. One of the possible sources of the discrepancies might be the orientation mismatch between the body surface and the heart surface in the 3D torso-heart model. Another possible reason is that we use a customized torso-heart geometry in this investigation, but the torso-heart geometries may vary from person to person, which will introduce uncertainties and errors in the estimation. In addition, the reference results given by GE-MRI images are characterized in terms of the 17-segment model of the left ventricle, while the modeled heart surface consists of both the right and left ventricles. The electrical activity in the inter-ventricular segments is thus greatly blurred by the activities on the right ventricle. Nevertheless, our inverse model is able to provide valuable information on the centroid, location, and extent of MIs on the heart surface, which is important to support medical scientists to make intervention decisions for patients with heart disease.

V. CONCLUSIONS

Myocardial infarction (MI) is among the leading causes of death in the United States. It is imperative to identify and characterize MIs for the timely delivery of medical intervention and the improvement of the quality of life. Cardiac electrical activity propagates in space and evolves over time. Most existing work identifies heart abnormalities by analyzing time-domain ECG signals (e.g., 12-lead ECG) on the body surface for detecting ECG wave deflections (i.e., P, QRS, and T waves), but tend to overlook spatiotemporal dynamics in the heart. They are limited

in the ability to identify and characterize the extent and location of MIs.

BSPMs provide high-resolution of spatiotemporal distribution of electrical potentials on the entire torso, and therefore provide richer information than 12-lead ECG. Little has been done to reconstruct the heart-surface electrograms from BSPMs using spatiotemporal regularization method and further characterize MIs. In this paper, we propose the ST-iECG method to characterize the location and extent of MIs on the heart surface. We solve the inverse ECG problem and reconstruct heart-surface electrograms from BSPMs using the STRE model. In addition, we propose a wavelet-clustering method to investigate the pathological behaviors of heart-surface electrograms to characterize the MIs.

The ST-iECG model is evaluated and validated with real data of MIs from 4 human subjects. First, we perform wavelet-clustering of electrograms on the heart surface for two training cases. Experimental results show that A3 (i.e., the approximation at level $j = 3$ of the Daubechies wavelet decomposition) of the QRS waves on the heart surface yields the best characterization of MIs based on golden standards by GE-MRI images. Second, we validate the characterization results with the other two test cases, and found that negative QRS waves in the heart-surface electrograms indicate potential regions of MI. The performance of the proposed ST-iECG model is described by three metrics, i.e., EPD, SO and CED, all of which score better compared with existing iECG model, and demonstrate strong potential as a decision-support tool to noninvasively investigate cardiac pathological activities.

One limitation of the present study lies in the sample size and the range of patients' characteristics, although there are a large number of heart-surface electrograms in the healthy and infarction regions in each of four cases. The availability of BSPM data and GE-MRI images helps mitigate this limitation to some extent in the evaluation and validation experiments. In the future work, it is necessary to include more patients with healthy status and patients with mild and severe MIs in the investigation before fully establishing the utility of proposed methods for clinical applications.

ACKNOWLEDGMENT

The authors would also like to thank editors and anonymous reviewers for their constructive comments and suggestions to improve the quality of this paper.

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801 Authors' photographs and biographies not available at the time of
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