

Kinetic Theory and Fast Wind Observations of the Electron Strahl

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ABSTRACT

We develop a model for the strahl population in the solar wind – a narrow, low-density and high-energy electron beam centered on the magnetic field direction. Our model is based on the solution of the electron drift-kinetic equation at heliospheric distances where the plasma density, temperature, and the magnetic field strength decline as power-laws of the distance along a magnetic flux tube. Our solution for the strahl depends on a number of parameters that, in the absence of the analytic solution for the full electron velocity distribution function (eVDF), cannot be derived from the theory. We however demonstrate that these parameters can be efficiently found from matching our solution with observations of the eVDF made by the Wind satellite’s SWE strahl detector. The model is successful at predicting the angular width (FWHM) of the strahl for the Wind data at 1 AU, in particular by predicting how this width scales with particle energy and background density. We find the strahl distribution is largely determined by the local temperature Knudsen number $\gamma \sim |TdT/dx|/n$, which parametrizes solar wind collisionality. We compute averaged strahl distributions for typical Knudsen numbers observed in the solar wind, and fit our model to these data. The model can be matched quite closely to the eVDFs at 1 AU; however, it then overestimates the strahl amplitude at larger heliocentric distances. This indicates that our model may be improved through the inclusion of additional physics, possibly through the introduction of “anomalous diffusion” of the strahl electrons.

Key words: solar wind – plasmas – scattering

1 INTRODUCTION

The strahl is a narrow, magnetic field-aligned population of suprathermal electrons (Rosenbauer et al. 1977) routinely observed in the ambient solar wind. The strahl is comprised of “thermal runaway” electrons (Gurevich & Istomin 1979). Because high energy particles are relatively insensitive to Coulomb collisions ($v_{coll} \sim v^{-3}$), electrons of sufficiently high energy can stream over large distances without coming into local thermal equilibrium (Scudder & Olbert 1979). The strahl electrons generally move antisunward, because the relatively hot inner regions of the heliosphere act as a source of high-energy particles. However, in some instances—notably, during the transit of interplanetary coronal mass ejections—“counterstreaming” strahls (e.g., Gosling et al. 1987; Anderson et al. 2012), which are directed towards the sun, are also observed. When it is prominent, the strahl can provide the dominant contribution to the electron heat flux (Pilipp et al. 1987), which is

an important source of heating of the solar wind during its non-adiabatic expansion (e.g., Štverák et al. 2015).

The beam-like shape of the strahl in velocity space is believed to come from the competition of two physical processes: the mirror force and pitch angle scattering. The mirror force narrows this population, so that electron velocities run nearly parallel to the local magnetic field. The runaway electrons see a weakening field as they travel to larger heliocentric distances, which converts the particles’ perpendicular velocity into parallel velocity. The observed strahls, however, are not as narrow as one would expect from conservation of the first adiabatic invariant. It is therefore inferred that a scattering process provides some diffusion that broadens the distribution.

This pitch angle scattering is usually attributed to either Coulomb collisions or wave-particle interactions, and interest in the latter has been partially motivated by the perceived failure of the former. In particular, measurements conducted by Lemons & Feldman (1983) showed the strahl to be even broader than would be predicted by incorporating Coulomb collisions into exospheric theory, and it was suggested that a source of “anomalous diffusion” in the form of wave-particle interactions may be scattering the strahl particles.

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Nonetheless, there is a wealth of evidence indicating that on average, characteristics of the strahl can be strongly correlated with the Coulomb collisionality of the background solar wind. We here refer to “collisionality” in terms of the Knudsen number $\gamma(x = \text{const.}) \propto T^2/n$, which parameterizes the ratio between advective and Coulomb scattering terms in the kinetic equation. Prominent, narrow strahls have long been associated with the fast solar wind (e.g., Feldman et al. 1978; Pilipp et al. 1987; Anderson et al. 2012). The fast wind is less collisional on average, since typically n is lower and T higher than in the slow wind. Ogilvie et al. (2000) specifically noted that prominent, narrow strahls can be seen when the fast solar wind has very low density. Salem et al. (2003) showed that the solar wind heat flux q , which comes from the skewness of $f(\mathbf{v})$ owing partially to the strahl, is correlated with γ . Bale et al. (2013) clarified this picture, demonstrating in a broad statistical study of Wind data that the solar wind heat flux in fact scales with γ exactly as predicted by classical theory (Spitzer & Härn 1953) in the collisional regime $\gamma \ll 1$. In the regime $\gamma \gtrsim 1$, the heat flux was observed to “saturate” at a collisionless value $q \sim nv_{th}T$. This saturation is also predicted, and may owe to the onset of various plasma instabilities (e.g., Cowie & McKee 1977). In Horaites et al. (2015), average field-parallel cuts of the electron distribution computed from Helios data were shown to vary with γ as predicted by a “self-similar” kinetic theory, with strahl amplitude increasing with γ . The fact that the solar wind data are so well-ordered by γ is a strong indication that Coulomb collisions play a central role in the physics that shapes the electron strahl.

Most wave-particle theories of strahl scattering have considered the effect of whistler waves (e.g., Vocks & Mann 2003; Vocks et al. 2005; Saito & Gary 2007). These waves can resonate with the cyclotron motion of strahl electrons, scattering the particles and broadening their distribution. Seough et al. (2015) suggested a variation on this mechanism, in which anti-sunward halo particles *not* scattered by whistlers can be focused by the magnetic field into the strahl. Whistlers may be generated by the electron heat flux instability (e.g., Gary et al. 1975, 1994); this view has been supported by studies of whistler wave events (e.g., Wilson et al. 2013; Stansby et al. 2016). Whistlers may also be excited by the temperature anisotropy of the strahl population (e.g., Viñas et al. 2010), or may help comprise the small-scale interplanetary turbulence (e.g., Pagel et al. 2007; Boldyrev et al. 2013). Recently, the first direct observations of long-lived (lasting longer than 5 minutes) whistler waves were made (Lacombe et al. 2014), using Cluster data. A subsequent study (Kajdič et al. 2016) demonstrated that the presence of whistler waves is correlated with broader strahl widths. However, the authors emphasized that whistler waves were detected infrequently by Cluster in the “pristine” (unperturbed by transient structures) fast wind: only 37 time intervals sustaining whistlers for a minute or longer were observed in a 10-year period. Looking beyond whistler waves, Pavan et al. (2013) proposed that strahl distributions focused by the mirror force should generate Langmuir oscillations. In their numerical simulations, quasilinear oscillations continually scatter the strahl electrons, developing a steady state in which scattering balances magnetic focusing.

The detailed shape of the strahl distribution, which carries information about the physics that formed it, has been characterized in multiple observational studies. Using data from the Imp 6, 7, and 8 satellites, Feldman et al. (1978) found that the angular breadth of the strahl distribution decreases monotonically with energy in the fast wind. This is consistent with the predictions of Coulomb scattering models (see e.g., Saito & Gary 2007; Fairfield & Scudder 1985) and some wave scattering models (e.g., Pavan et al. 2013). This

picture is not always observed in the data, however; Anderson et al. (2012) reported that the strahl width can either increase or decrease with energy. Some instances where the strahl broadens with energy have been associated with rare transient events, such as solar electron bursts (de Koning et al. 2007) and periods of increased wave activity (Pagel et al. 2007). Counter to the notion that the magnetic field continuously focuses the strahl as the particles travel away from the sun, Hammond et al. (1996) found that the strahl width (at a given energy) actually increases with heliocentric distance r for Ulysses data $r > 1$ AU (see also Graham et al. (2017)).

The goal of this work is to develop an analytical model for the electron strahl population in the solar wind. The accurate analytic derivation of the full electron distribution function is a very complicated task since it requires one to solve the electron kinetic equation in an expanding background, subject to the boundary conditions at the base of the solar wind and at infinity. In our approach we build upon our previous work (Horaites et al. 2015), and consider the electron kinetic equation in the range of distances where the parameters of the solar wind (density, temperature, magnetic field strength) can be approximated as power laws of the distance along a magnetic flux tube. We then expect that the solution for the strahl is *scale invariant*, namely, it has similar structure at different distances after appropriate rescaling of the velocity field and the amplitude of the distribution function. This allows one to find a nontrivial solution for the electron strahl, which incorporates the effects of advection, focusing by the expanding magnetic field, and pitch angle scattering by Coulomb collisions.¹

The scale-invariance does not allow us to determine the solution uniquely, which reflects the fact that we do not solve a full boundary value problem, and, therefore, do not have enough information to fully describe the fast electrons that stream from the hot solar surface. We however demonstrate that the remaining arbitrariness can be removed very efficiently by matching our analytic solution with the observations.

As a test of our theory, we examine high resolution measurements of the strahl distribution made by the Wind satellite, whose Solar Wind Experiment (SWE) had an electrostatic analyzer dedicated to measuring the strahl distribution (Ogilvie et al. 1995). Wind’s strahl detector had very fine ($\sim 4.5^\circ$) angular resolution, making it ideal for measuring the shape of the strahl distribution. Following previous observational papers (e.g. Ogilvie et al. 2000), we will characterize the breadth of the distribution in terms of the angular full width at half maximum (FWHM). We will demonstrate in section 3 that the strahl widths are accurately described by our theory, as it correctly predicts how the width decreases with particle energy and increases with background density.

Our conclusions differ somewhat from those of Lemons & Feldman (1983), in that we do not find the strahl widths at 1 AU to be too broad, necessarily. In our model, the parameters defining the large-scale structure of the solar wind (variation of temperature, density, etc.) are intertwined with the predicted shape of the strahl distribution, including its width, energy-dependence, and variation with heliocentric distance. So although in section 3.4 we will show that our model can be matched to average eVDFs at 1 AU, in section 4 we will infer from published measurements of the solar wind structure that the strahl should increase in amplitude with distance, relative to the core. This may be in contradiction with measurements made by Maksimovic et al.

¹ As it would greatly complicate our current project, we do not yet incorporate the effects of wave-particle scattering in our model.

(2005) and Štverák et al. (2009), which show the opposite trend, at least in the low-energy portion of the strahl distribution. We believe a more complete theory of the strahl may require the inclusion of additional physics, for instance in the form of anomalous diffusion. The search for such a theory should be well-constrained by the existing body of observations, including those presented here.

2 THEORY

Consider a solar wind in which the electron temperature T , density n , and magnetic field strength B all vary as power laws with distance x along a flux tube: $n = n_0(x/x_0)^{\alpha_n}$, $T = T_0(x/x_0)^{\alpha_T}$, and $B = B_0(x/x_0)^{\alpha_B}$. Throughout this paper, the subscript 0 will be used to note values of a variable at reference position $x = x_0$. Specifically, we will let $x_0 \sim 1AU$ be the position of the Wind spacecraft. We assume that the number of particles in the nearly Maxwellian core of the electron distribution function is typically much larger than the number of particles in the strahl (and in the halo), so the electron temperature is mostly defined by the core population (e.g. Štverák et al. 2009). Without loss of generality, we will express the electron distribution in the form:

$$f(\mathbf{v}, x) = NF(\mathbf{v}/v_{th}(x), x)/T(x)^\alpha, \quad (1)$$

where $v_{th} \equiv \sqrt{2T/m_e}$ is the electron thermal speed and N is a constant set by the normalizations $\int f(\mathbf{v}, x)d^3v = n(x)$, $\int F(\mathbf{u}, x)d^3u = 1$. Applying these normalizations to equation (1) leads to the relation

$$\alpha = 3/2 - \alpha_n/\alpha_T. \quad (2)$$

We also define the Knudsen number $\gamma(x)$, which parametrizes the Coulomb collisionality:

$$\gamma(x) \equiv -T^2(d \ln T/dx)/(2\pi e^4 \Lambda n) = \lambda_{mfp}/L_T, \quad (3)$$

and the electric Knudsen number $\gamma_E(x)$ which is the ratio of the electric field to the Dreicer field

$$\gamma_E(x) \equiv E_{\parallel}eT/(2\pi e^4 \Lambda n), \quad (4)$$

where E_{\parallel} is the component of the electric field parallel to the magnetic field. In these expressions we use the Coulomb logarithm Λ , which we treat as a constant ($\Lambda = 25.5$), and introduce the electron mean free path

$$\lambda_{mfp} \equiv T^2/(2\pi e^4 \Lambda n), \quad (5)$$

and the length scale of temperature variation

$$L_T \equiv (d \ln T/dx)^{-1} = -x/\alpha_T. \quad (6)$$

At frequencies much smaller than the electron gyrofrequency, and at scales much larger than the electron gyroscale, the distribution function $f(\mathbf{v}, \mu, x)$ obeys the drift-kinetic equation (e.g., Kulsrud 1983), which, in a steady state ($\partial f/\partial t = 0$), takes the form:

$$\begin{aligned} \mu v \frac{\partial f}{\partial x} - \frac{1}{2} \frac{d \ln B}{dx} v(1 - \mu^2) \frac{\partial f}{\partial \mu} - \\ - \frac{eE_{\parallel}}{m} \left[\frac{1 - \mu^2}{v} \frac{\partial f}{\partial \mu} + \mu \frac{\partial f}{\partial v} \right] = \hat{C}(f), \end{aligned} \quad (7)$$

where $v = |\mathbf{v}|$, $\mu = \mathbf{v} \cdot \hat{\mathbf{B}}/v$, the unit vector $\hat{\mathbf{B}}$ points anti-sunward along the local magnetic field. Equation (7) presumes the $\mathbf{E} \times \mathbf{B}$ drift is negligible. It describes the evolution of the (gyrotropic) distribution function in the reference frame of a fixed flux tube, for electrons with speeds much greater than the solar wind speed: $v \gg v_{sw}$.

The effect of Coulomb collisions are described by the operator $\hat{C}(f)$. We will be mostly interested in the strahl component of the distribution function, which has a relatively low density and a relatively high velocity as compared to the core distribution. Under these conditions, one can use the linearized, high-energy form of the collision integral (e.g., Helander & Sigmar 2002):

$$\begin{aligned} \hat{C}(f) = \frac{4\pi n e^4 \Lambda}{m_e^2} & \left[\frac{\beta}{v^3} \frac{\partial}{\partial \mu} (1 - \mu^2) \frac{\partial f}{\partial \mu} \right. \\ & \left. + \frac{1}{v^2} \frac{\partial f}{\partial v} + \frac{v_{th}^2}{2v^2} \left(-\frac{1}{v^2} \frac{\partial f}{\partial v} + \frac{1}{v} \frac{\partial^2 f}{\partial v^2} \right) \right]. \end{aligned} \quad (8)$$

In this expression, $\beta \equiv (1 + Z_{eff})/2$, and Z_{eff} is the effective charge of the ion species (e.g., Rathgeber et al. 2010). We note $Z_{eff} \approx 1$ in the solar wind, where most ions are protons. The derivation of Eq. (8) requires an explanation. The collision integral (8) describes the interaction of fast “test” electrons with the Maxwellian electron and ion “field” populations (core), which are assumed to have similar temperatures $T_e \sim T_i$. In the derivation of Eq. (8) it is assumed that the density of the test particles is much smaller than the density of the core particles and the energy of the test particles is much larger than the core energy, $(v/v_{th})^2 \gg 1$. The first term in the rhs of Eq. (8) describes the pitch angle scattering of the test electrons by the core electrons and ions, while the remaining terms describe the energy exchange of the test electrons with the core electrons. Due to low density of the test electrons, their mutual interactions are neglected. We will naturally identify the test electrons with the strahl electrons, while the field particles will correspond to the nearly Maxwellian core of the solar wind distribution function.

Substituting expression (1) into equation (7) and introducing the dimensionless variable $\xi \equiv (v/v_{th})^2$, we find the following equation for $F(x, \xi, \mu)$:

$$\begin{aligned} \lambda_{mfp}(x) \frac{\partial F}{\partial x} & \\ + \gamma(x) \left[\alpha \mu F + \mu \xi \frac{\partial F}{\partial \xi} + \frac{\alpha_B}{2} (\alpha + 1/2) (1 - \mu^2) \frac{\partial F}{\partial \mu} \right] & \\ - \gamma_E(x) \left[\mu \frac{\partial F}{\partial \xi} + \frac{1 - \mu^2}{2\xi} \frac{\partial F}{\partial \mu} \right] = \hat{C}(F), \end{aligned} \quad (9)$$

where the collision operator (8) takes the form (Krasheninnikov 1988; Krasheninnikov & Bakunin 1993):

$$\hat{C}(F) = \frac{1}{\xi} \left[\frac{\partial F}{\partial \xi} + \frac{\partial^2 F}{\partial \xi^2} \right] + \frac{\beta}{2\xi^2} \frac{\partial}{\partial \mu} (1 - \mu^2) \frac{\partial F}{\partial \mu}. \quad (10)$$

Equation (9) is nearly identical to the self-similar kinetic equation studied in Horaites et al. (2015), where it was assumed that the distribution function F , and the Knudsen numbers $\gamma(x)$ and $\gamma_E(x)$ are independent of x . In the present work we do not make such simplifying assumptions, and allow for explicit dependence of the distribution function F on x . We however assume that similarly to density, temperature, and magnetic field, $\gamma(x)$ varies along a magnetic flux tube as a power law:

$$\gamma(x) = \gamma_0(x/x_0)^{\alpha_\gamma}, \quad (11)$$

where, as it follows from the definition (3),

$$\alpha_\gamma = 2\alpha_T - \alpha_n - 1. \quad (12)$$

We now apply the kinetic equation (7) to the strahl electron population. The field-aligned, high-energy strahl population corresponds to $\mu \approx 1$, $\xi \gg 1$. Let us look for asymptotic solutions to equations (9) and (10) in this regime. We approximate $(1 - \mu^2) \approx 2(1 - \mu)$,

and neglect the ambipolar electric field terms and the collisional energy-exchange terms (the terms containing ξ -derivatives in (10)), which are higher-order in $1/\xi$.

Neglecting the electric field terms in equation (9) amounts to assuming $\gamma_E \ll \gamma\xi$, which requires further justification based on an estimate of the function $\gamma_E(x)$. For a rough estimate of the function $\gamma_E(x)$ we note that in spherically symmetric exospheric models of the solar wind, in which the magnetic field lines are assumed to point radially ($x = r$), the ambipolar electric field $E_{\parallel}(x)$ can be evaluated from the electron momentum equation (e.g., Hollweg 1970; Jockers 1970):

$$enE_{\parallel} + \frac{d}{dx}(nT) = 0. \quad (13)$$

This equation retains only the most important terms (neglecting, e.g., gravity) and assumes that the electron bulk flow is subsonic. In a scale-invariant model in which $n(x)$ and $T(x)$ are power laws, the solution to this equation can be approximated as:

$$E_{\parallel}(x) \sim \frac{T(x)}{ex}. \quad (14)$$

For such a model, we obtain using Eqs. (3) and (4) that $\gamma_E(x)/\gamma(x) \sim 1$. It is therefore reasonable to assume $\gamma_E \ll \gamma\xi$, and we can indeed neglect the electric field terms in (9). We also note that the latter condition may be re-written as $m_e v^2 \gg eE_{\parallel} L_T$. Noting that L_T is on the order of the electron mean-free-path λ_{mfp} , we see that the electric field does not affect the dynamics of the fast electrons between the collisions.

Defining

$$\kappa \equiv 2 - \alpha_{\gamma}/\alpha_T, \quad (15)$$

and

$$\alpha' \equiv \kappa - (\alpha + 1/2)\alpha_B, \quad (16)$$

we write the resulting equation for $F(x, \xi, \mu)$ in the form:

$$\begin{aligned} \lambda_{mfp}(x) \frac{\partial F}{\partial x} + \gamma(x) \left\{ \alpha F + \xi \frac{\partial F}{\partial \xi} + (\kappa - \alpha')(1 - \mu) \frac{\partial F}{\partial \mu} \right\} = \\ = \frac{\beta}{\xi^2} \frac{\partial}{\partial \mu} (1 - \mu) \frac{\partial F}{\partial \mu}. \end{aligned} \quad (17)$$

Equation (17) includes the effects of advection, angular focusing due to the spatially expanding magnetic field, and pitch angle scattering due to $e - e$ and $e - p$ Coulomb collisions. To bring equation (17) into a more tractable form, we would like to use the variable $v = \sqrt{\xi} v_{th}(x)$ instead of the variable x . This choice of variables leads to the following equation for $F(v, \xi, \mu)$:

$$\alpha F + \xi \frac{\partial F}{\partial \xi} + (\kappa - \alpha')(1 - \mu) \frac{\partial F}{\partial \mu} = \frac{\beta}{\gamma(x) \xi^2} \frac{\partial}{\partial \mu} (1 - \mu) \frac{\partial F}{\partial \mu}. \quad (18)$$

In this equation the Knudsen number $\gamma(x)$ should be expressed as a function of ξ and v as follows

$$\gamma(x) \equiv \gamma_0 \left(v/v_{th,0} \right)^{2\alpha_{\gamma}/\alpha_T} \xi^{-\alpha_{\gamma}/\alpha_T}. \quad (19)$$

We show this intermediate step to demonstrate that equation (18) contains no derivatives with respect to v , which significantly simplifies the PDE. As a result, our solutions will include arbitrary functions of v , which, as we demonstrate later, may be effectively determined from comparison with observations.

To find the solution of Eq. (17) we perform another change of variables by treating F as a function of independent variables v, η ,

and z , where $\eta = \ln \xi$ and $z = \xi^{\kappa}(1 - \mu)$. The differential equation for $F(v, \eta, z)$ then takes the form:

$$\alpha F + \frac{\partial F}{\partial \eta} + \left[\alpha' z - \frac{\beta}{G(v)} \right] \frac{\partial F}{\partial z} = \frac{\beta}{G(v)} z \frac{\partial^2 F}{\partial z^2}, \quad (20)$$

where

$$G(v) = \gamma_0 \left(v/v_{th,0} \right)^{2\alpha_{\gamma}/\alpha_T} = \gamma(x) \xi^{(\alpha_{\gamma}/\alpha_T)}. \quad (21)$$

The solution of this advection-diffusion equation can be sought in the form $F(v, \eta, z) = \exp\{-za(v, \eta) + b(v, \eta)\}$, where $a(v, \eta)$ and $b(v, \eta)$ are general functions. Substituting this solution form into equation (18), and equating coefficients at like powers of z , we obtain the following two equations:

$$\alpha + \frac{\partial b}{\partial \eta} + \left(\frac{\beta}{G(v)} \right) a = 0, \quad (22)$$

$$\frac{\partial a}{\partial \eta} + \alpha' a + \left(\frac{\beta}{G(v)} \right) a^2 = 0. \quad (23)$$

Equation (23) can be solved for $a(v, \eta)$ by integration, and $b(v, \eta)$ is similarly obtained from equation (22). Substituting these functions into our assumed solution form yields the strahl distribution $F(v, \xi, \mu)$:

$$F(v, \xi, \mu) = C_1(v) \frac{\exp \left\{ \frac{\alpha' C_2(v) \xi^{\kappa - \alpha'} (1 - \mu)}{1 + \beta C_2(v) \xi^{-\alpha'} / G(v)} \right\}}{1 + \beta C_2(v) \xi^{-\alpha'} / G(v)} \xi^{-\alpha}, \quad (24)$$

where $C_1(v)$ and $C_2(v)$ are arbitrary functions. Due to assumed scale invariance of the strahl distribution function, we expect that the physically relevant solution should correspond to either $1 \ll \beta C_2(v) \xi^{-\alpha'} / G(v)$ or $1 \gg \beta C_2(v) \xi^{-\alpha'} / G(v)$. It may be argued the observed breadth of the strahl is more consistent with the first case (see Appendix), in which case equation (24) reduces to the relatively simple expression:

$$F(v, \xi, \mu) = C(v) \xi^{\alpha' - \alpha} \exp \left\{ \tilde{\gamma}(v, \xi) \Omega \xi^2 (1 - \mu) \right\}, \quad (25)$$

where $C(v)$ is an arbitrary (dimensionless) function of v . For convenience later in the paper, we here introduced the notation

$$\tilde{\gamma} \equiv T^2 / (2\pi e^4 \Lambda n x) = -\gamma(x)/\alpha_T, \quad (26)$$

and

$$\Omega \equiv -\alpha' \alpha_T / \beta. \quad (27)$$

For relevant solar wind profiles, α' and α_T (and Ω) are negative.

Equation (25) is an exact solution to equation (18). The field-parallel ($\mu = 1$) energy profile of the strahl amplitude depends on the function $C(v)$, which in turn determines how the strahl amplitude varies with distance x at fixed ξ . The presence of the arbitrary function $C(v)$ reflects the fact that the fast electrons are not generated locally, but rather produced at the base of the solar wind and then propagate along the magnetic field lines almost without collisions. This function could be obtained if the analytic solution for the full electron distribution function (for all energies and distances) were available. Such an exact solution is however very complicated and currently cannot be obtained. The function $C(v)$ can however be well constrained from the analysis of the observational data. We will do this in the next section, where we compare equation (25) with direct measurements of the distribution function made by Wind's strahl detector.

3 OBSERVATIONS

3.1 SWE Strahl Detector

The Wind satellite's strahl detector is a toroidal electrostatic analyzer (Ogilvie et al. 1995), which directly sampled the solar wind electron distribution function (eVDF) at a heliocentric distance $r = 1$ AU. The instrument's 12 anodes are set in a vertical pattern in a plane that contains the spacecraft spin axis, spanning a field of view $\pm 28^\circ$ centered around the ecliptic. Wind's spin axis is set at a right angle with the ecliptic plane, allowing different azimuthal angles to be sampled as the spacecraft spins (3 sec spin period). These azimuthal bins have a fixed separation of 3.53° . Each strahl distribution measured by the spacecraft consists of a 14x12 angular grid of electron counts, that was measured at a fixed energy during a single spacecraft spin. Counts can be converted into physical units of $f(\mathbf{v})$ (e.g., cm^{-6}s^3) in the standard fashion by accounting for the detector efficiency and geometric factor. Accompanying each strahl measurement is an analogous 14x12 measurement of the "antistrahl", made at a clock angle 180° with respect to the strahl measurement. The detector voltage was set to a different value each spin, so that 32 energies from 19.34 to 1238 eV would be sampled in as many rotations.

In the original mode of operation, each measurement grid was centered on the nominal average Parker spiral (in the ecliptic plane, 45° offset from the radial direction \hat{r}). In practice, however, the local magnetic field only fell within the field of view of the detector about half the time. This prompted a revision of the instrument software in February 1999 (Ogilvie et al. 2000), which matched the clock angle of the strahl measurement with the instantaneous measurement of the magnetic field provided by Wind's Magnetic Field Investigation (MFI).

Our data set ranges from January 1, 1995 to May 30, 2001, which nearly covers the operational lifetime of the strahl instrument. The strahl detector was reconfigured shortly after this period to serve as a replacement for SWE's Vector Electron/Ion Spectrometer (VEIS), whose power supply had recently failed.

3.2 Strahl Data

The data studied here are derived primarily from Wind's SWE strahl detector, supplemented by plasma data from SWE/VEIS and vector magnetic field data from MFI (Ogilvie et al. 1995; Lepping et al. 1995). The background electron density n is taken from the VEIS measurement of proton density n_p , which is a reasonable estimate for the quasineutral, proton-dominated solar wind. This is more reliable than direct measurement of n with the electron instrument since measurements of the proton distribution are less susceptible to spacecraft charging effects (see, e.g., DeForest 1972; Pilipp et al. 1987). The temperature is calculated from the second-order moment of the eVDF measured by VEIS. We note that this measurement overestimates the core temperature T by a small factor (10-20%), since the suprathermal populations are included in the calculation. Plasma parameters (which are used to calculate ξ , γ , etc.) from other instruments are associated with each strahl measurement by matching to the nearest measurement time. If plasma data are not available within 5 minutes of the strahl measurement, then the data are excluded from our analysis. We also exclude data for which the \hat{B} direction, as measured by the MFI instrument, is outside of the strahl detector's field of view.

Each measurement made by the SWE strahl detector is a composition of signals from the strahl, halo, and (at low energies) core

components of the electron distribution (e.g., Pilipp et al. 1987). In order to conduct a statistical study of the fast wind strahl, we developed an automated procedure for isolating the strahl signal from the background formed by the other populations. The procedure is as follows:

Find the strahl—For each 14x12 strahl distribution f_s (measured at a single energy), find the bin where the distribution is at a maximum, and designate the nominal velocity direction of electrons measured in that bin as the "peak direction".

Remove the halo—Let the maxima of the measured strahl and associated anti-strahl distributions be designated $f_{s,max}$, $f_{a,max}$ respectively. Zero out (ignore in future analysis) the bins of the strahl distribution where the criterion $f_s < \text{Max}\{f_{a,max} \times 3/2, f_{s,max}/5\}$ is satisfied.

Clean up residual noise—Calculate the pitch angle θ , relative to the peak direction, of every bin in the 14x12 grid. Find the minimum pitch angle $\theta_{min} = \text{Min}\{\theta\}$ among the bins zeroed out in the previous step. Zero out every bin in the strahl distribution f_s that satisfies $\theta > \theta_{min}$. From this point forward, " f_s " will refer to the cleaned strahl distribution resulting from the above procedure.

This cleaning procedure leads to a very clearly defined strahl, an example of which is shown in figure 1.

For strahl distributions measured after the February 1999 software revision, anomalously high count rates were observed when the sun was in the detector's view (R. J. Fitzenreiter 2016, personal communication). These spurious counts were caused by photoelectrons, and should be removed from our analysis. As a simple correction, we zero out (prior to step "Find the strahl" above) data from all 12 anodes at a given azimuthal angle, if one of these anodes pointed within 10° of the sun's position.

3.3 Analysis of Strahl Widths

We now compare the SWE strahl detector data with our model. We will only consider the fast solar wind, i.e. when the solar wind bulk velocity exceeded 550 km/sec . The strahl detector measures each distribution at fixed energy ξ and position x . We therefore predict that the distribution function $F(\mu)$ should fall off exponentially with $(1 - \mu)$, as it follows from equation 25:

$$F(\mu) \propto \exp\{\tilde{\gamma}\Omega\xi^2(1 - \mu)\}. \quad (28)$$

Let us express equation 28 in terms of the pitch angle with respect to the magnetic field, $\theta \equiv \cos^{-1}(\mu)$. That is, for the small angles ($\theta \approx 0$) relevant to the strahl, we can approximate $\mu \approx 1 - \theta^2/2$, implying F should fall off as a Gaussian with θ :

$$F(\theta) \sim \exp\left\{\frac{\tilde{\gamma}\Omega\xi^2\theta^2}{2}\right\}. \quad (29)$$

This prediction agrees with previous attempts to model the strahl; functions of the form $f(\theta) \propto \exp(-C\theta^2)$, where C is some constant, have been used to fit measured strahl distributions at fixed energy (Hammond et al. 1996; Anderson et al. 2012).

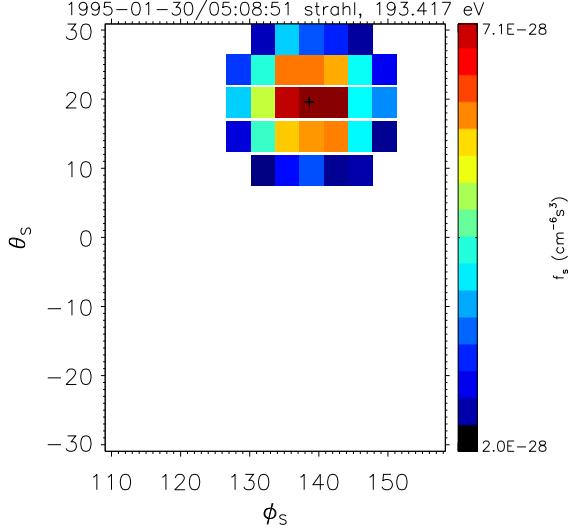


Figure 1. An example strahl spectrum f_s (linear z-axis scale), after applying an automated procedure for removing the halo population. This plot can be compared with figure 3, [Fitzenreiter et al. \(1998\)](#), which shows the “raw” spectrum. The variables θ_S , ϕ_S are spherical (GSE) coordinates that describe the velocity direction of the measured electrons. The angle $\theta_S = 0$ corresponds with the ecliptic. Note that the detector’s 12 anodes are not evenly spaced in θ_S . The magnetic field direction \hat{B} is determined through the process of nonlinear fitting described in section 3.3, and is shown in this example by a “+” symbol.

The full width at half maximum of the strahl, θ_{FWHM} , follows immediately from equation 28:

$$\begin{aligned} \theta_{FWHM} &= 2 \cos^{-1} \left[1 - \frac{\ln(2)}{\tilde{\gamma} |\Omega| \xi^2} \right] \\ &\approx \frac{360}{\pi \xi} \sqrt{\frac{2 \ln(2)}{\tilde{\gamma} |\Omega|}} \text{ deg.} \end{aligned} \quad (30)$$

The approximate expression in equation 30, which we arrived at by substituting $\mu \approx 1 - \theta^2/2$ into equation 28, reveals how θ_{FWHM} should scale with other locally observable quantities, i.e. density n , core temperature T , energy $\mathcal{E} = m_e v^2/2$, and distance x along the flux tube. In terms of these physical quantities, equation 30 can be expressed:

$$\theta_{FWHM} \approx 951 \sqrt{\frac{nx}{|\Omega| \mathcal{E}^2}} \text{ deg.} \quad (31)$$

Equation 31 is written with the choice of units, $[n] = \text{cm}^{-3}$, $[x] = \text{AU}$, $[\mathcal{E}] = \text{eV}$. In the inner heliosphere, we can make the reasonable estimate $x \approx r$ (for radial field lines).

In the context of our model, Ω is a constant that depends on solar wind structure (eq. 27). From equation 30, we obtain the following scaling relations for fixed x and Ω :

- i For given n , $\theta_{FWHM} \propto \mathcal{E}^{-1}$
- ii For given \mathcal{E} , $\theta_{FWHM} \propto \sqrt{n}$

The local quantities n and \mathcal{E} , which determine the breadth of the strahl in our model, are known to high accuracy. Measurements

of these parameters have relative errors 10% and 3% for n and \mathcal{E} , respectively ([Ogilvie et al. 1995](#)). We note also that our prediction for θ_{FWHM} is independent of T .

To test our prediction for θ_{FWHM} , we fit each strahl distribution f_s to our model (28). Recalling $f_s(\mu) \propto F(\mu)$ (see eq. (1)), let us define $z \equiv \ln(f_s/f_{s,max})$, $y \equiv (1 - \mu)$, $m \equiv \tilde{\gamma} \Omega \xi^2$, and write equation 28 as:

$$z(y) = my + \mathcal{Z}, \quad (32)$$

where m and \mathcal{Z} are constants.

Since our model (32) is linear when expressed in these variables, it would seem natural to employ the weighted ordinary least squares (OLS) technique to find the parameters m , \mathcal{Z} for each distribution. This could be accomplished by fitting to the data \bar{z}_i comprising the distribution, which is measured at independent coordinates y_i (“ i ” indexes the bins of f_s). However, it turns out that there is considerable error in our determination of the magnetic field direction \hat{B} which must be corrected for. If our measurement of \hat{B} (as determined by the MFI instrument) is off by even a few degrees, errors in y_i will lead to significant inaccuracies in the determination of the strahl width. This effect is most problematic when the angular error of the \hat{B} direction is on the order of θ_{FWHM} , which can occur for narrow strahls.

We therefore conduct a weighted *nonlinear* least squares fit to the distribution function (z), in which the direction \hat{B} is determined by the fitting procedure. Our fits are generated using the MPFIT software ([Markwardt 2009](#)), which implements the Levenberg-Marquardt algorithm. We fit to the (2D) model function:

$$z(\phi_S, \theta_S) = my(\phi_S, \theta_S; \phi_B, \theta_B) + \mathcal{Z}. \quad (33)$$

Here we introduced the function $y(\phi, \theta; \phi', \theta')$,

$$y(\phi, \theta; \phi', \theta') = 1 - \hat{U}(\phi, \theta) \cdot \hat{U}(\phi', \theta'), \quad (34)$$

and $\hat{U}(\phi, \theta)$ is a function that produces a unit vector pointing in the direction specified by ϕ , θ (azimuth and altitude, in GSE coordinates).

Equation (33) is the same as the OLS function (32) described above, with some nuance. Now there are two independent coordinates, ϕ_S and θ_S , which represent azimuth and altitude in spherical (GSE) coordinates. The model (eq. 33) has four fit parameters: m , ϕ_B , θ_B , and \mathcal{Z} . The parameters m and \mathcal{Z} are as above. The direction \hat{B} is specified by the fit parameters ϕ_B and θ_B , i.e. $\hat{B} = \hat{U}(\phi_B, \theta_B)$. The y_i data are interpreted as above, but now $y_i = 1 - \mu_i$ depends on the ϕ_i , θ_i identified with the nominal velocity direction of electrons measured in the i^{th} bin, as well as on the fit parameters ϕ_B and θ_B . Namely, $y_i = y(\phi_i, \theta_i; \phi_B, \theta_B)$.

Our weighted fit requires an estimate of the standard error of the \bar{z}_i measurements, which we denote as σ_i . This can be estimated by assuming the strahl detector obeys Poisson (“counting”) statistics. We assume the raw number of counts ζ_i registered by the detector in the i^{th} bin is sufficiently large, so that we can approximate the error of ζ_i as Gaussian-distributed, with standard deviation $\sqrt{\zeta_i}$. Then, we find $\sigma_i \approx 1/\sqrt{\zeta_i}$ from straightforward error propagation (noting f_s is proportional to counts).

Our fitting procedure minimizes the chi-squared statistic:

$$\chi^2 = \sum_{i=1}^N (z_i - \bar{z}_i)^2 / \sigma_i^2. \quad (35)$$

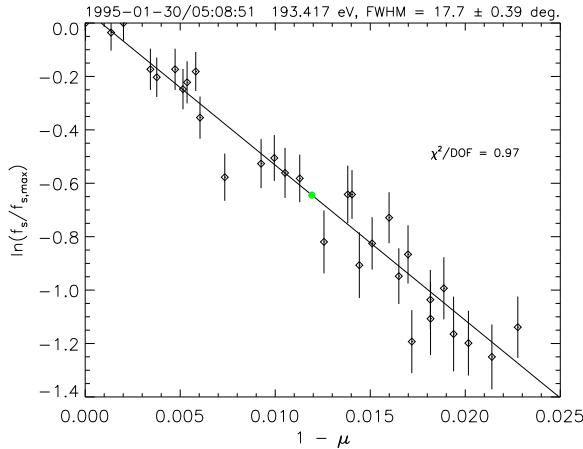


Figure 2. An illustration of our fitting method: the angular distribution f_s (from Figure 1) is displayed above as a pitch angle distribution $z(y)$, where $y = (1 - \mu)$ and $z = \ln(f_s/f_{s,max})$. The data in the vicinity of the strahl peak is fit to the function $z = my + \mathcal{Z}$. Our method of fitting, a nonlinear least squares fit that allows the \hat{B} direction to vary, is a weighted fit that accounts for the uncertainties σ_i of the \bar{z}_i measurements. The σ_i are shown above as error bars. The full width at half-maximum of the strahl (green dot), θ_{FWHM} , is calculated from m according to equation 36.

Here, $(z_i - \bar{z}_i)$ represents the difference between our model function and the data, for the i^{th} bin of the distribution. N is the number of non-zero data points in the 12×14 strahl distribution f_s ; we only conduct a fit if there are at least 6 points left after applying the cleaning procedure (section 3.2), so $6 \leq N \leq 168$. Figure 2 shows an example of our fitting procedure, applied to the data appearing in figure 1.

The normalized chi-squared statistic χ^2/DOF can be used to test goodness of fit. Here $DOF = N-4$ represents the degrees of freedom of our 4-parameter model function (33). For our fast wind data, we find $\langle \chi^2/DOF \rangle = 1.12$. The angle brackets indicate the average value among the $>100,000$ fits in our analysis. To calculate this average, we excluded outlier fits for which $\chi^2/DOF > 10$, which constituted only 1% of the completed fits. Since $\langle \chi^2/DOF \rangle \approx 1$, we conclude that equation 28 accurately describes the strahl data.

Having fit for the slope m for each strahl distribution f_s , we calculate the distribution’s ‘‘measured θ_{FWHM} ’’:

$$\theta_{FWHM} = 2 \cos^{-1} \{1 - \log(1/2)/m\}. \quad (36)$$

This formula follows from equation (32), utilizing the definitions of y and z . We can additionally calculate a ‘‘measured Ω ’’:

$$\Omega = \frac{m}{\bar{\gamma} \mathcal{E}^2}. \quad (37)$$

For completeness, we note a selection criterion: a distribution f_s was only retained for study if the fit for the slope m (eq. 33) yielded a ‘‘measured θ_{FWHM} ’’ (eq. 36) that was less than twice the maximum pitch angle among the bins of f_s . This avoids extrapolation errors in our determination of θ_{FWHM} .

In Figure 3, the ‘‘measured θ_{FWHM} ’’ is compared with the ‘‘expected θ_{FWHM} ’’. The latter quantity is calculated according to equation 30 from the detector energy \mathcal{E} and plasma electron

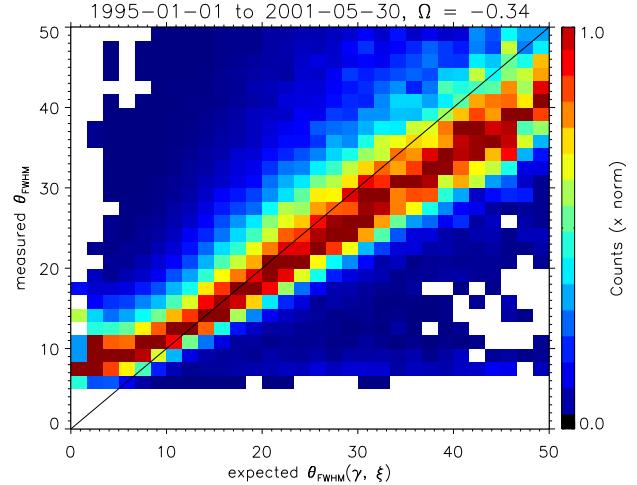


Figure 3. Expected θ_{FWHM} (degrees) from equation 30 (using $\Omega = -0.34$), plotted versus measured widths. The overplotted line, shown for comparison, represents a one-to-one correspondence.

density n , assuming some value for Ω (which depends on the solar wind’s large-scale structure, see eq. 40). Figure 3 is a normalized 2D histogram, with each column normalized to its peak value. The measured θ_{FWHM} is observed to be proportional to the expected θ_{FWHM} , with a slope near unity under the appropriate choice of the quantity Ω . We here treat the quantity Ω , which appears in equation 30, as a single constant for all measurements. We set $\Omega = -0.34$ to produce figures 3, 4, and 5. This value is derived from the average measured Ω (eq. 37) among all distributions whose measured widths (eq. 36) fall within a representative range: $8^\circ < \theta_{FWHM} < 50^\circ$.

Our model predicts that θ_{FWHM} depends on both the electron density n and the detector energy \mathcal{E} , through scaling relations (i) and (ii). These dependencies cannot be discriminated in figure 3, so we will now examine them individually. In figure 4 we demonstrate (i): the strahl width is inversely proportional to the energy, for fixed density. To make this figure, we consider only fast wind data for which the background electron density falls within a narrow range, $3.6 < n < 4.4 \text{ cm}^{-3}$. For this data, which is effectively a subset of the data shown in figure 3, we plot the measured θ_{FWHM} versus the detector energy \mathcal{E} . The column-normalized 2D histogram nicely matches the predicted trend (equation 30), which is shown as a solid line for $n = 4 \text{ cm}^{-3}$. Similar predictions for $n = 3.6, 4.4 \text{ cm}^{-3}$ are shown as dotted lines.

We now verify scaling relation (ii), in a similar manner. The SWE strahl detector only sampled the distribution function at discrete energies; in figure 5, we only show fast wind data measured at energy $\mathcal{E} = 270 \text{ eV}$. Here we plot a column-normalized 2D histogram of the measured θ_{FWHM} versus the electron density n . For comparison, we show our model’s prediction for the strahl width at this energy, as a solid line. Predictions resulting from varying \mathcal{E} by $\pm 3\%$ (energy range admitted by the detector), are shown as dotted lines.

In figures 3, 4, and 5, strahl widths are only shown for the regime $\theta_{FWHM} < 50^\circ$. This is because the asymptotic formula for the strahl, equation 25, was derived under the assumption $\mu \approx 1$. Including data with pitch angles less than 25° corresponds with the regime $\mu > 0.9$, so our assumption is well-satisfied.

Our 100,000 fits represent only about 1% of the distributions

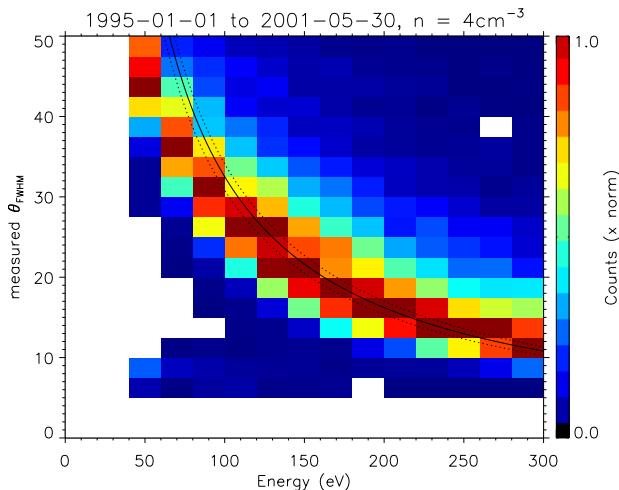


Figure 4. Experimental verification of scaling relation (i): $\theta_{FWHM} \propto \mathcal{E}^{-1}$ at fixed n . Data shown fall in the range of densities $3.6 < n < 4.4 \text{ cm}^{-3}$.

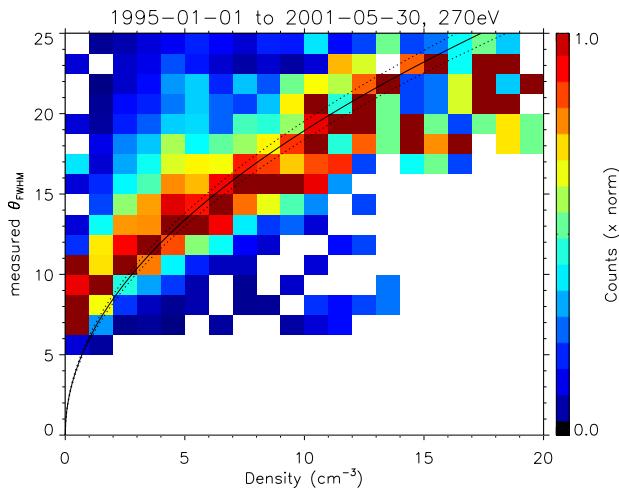


Figure 5. Experimental verification of scaling relation (ii): $\theta_{FWHM} \propto \sqrt{n}$ at fixed \mathcal{E} . Data shown at detector energy 270 eV (specified by the detector with accuracy $\Delta \mathcal{E}/\mathcal{E} \approx 3\%$).

(f_s) measured by the SWE strahl detector. Despite this low proportion, we believe our data are representative of the fast wind strahl. We note our cleaning procedure (section 3.2) and selection criteria make only a small proportion of the observed f_s suitable for our study. That is, we only consider fast wind strahls that are prominent and resolved by the detector. This tends to exclude high-energy measurements. For example, SWE/strahl measured f_s at energies > 500 eV about 38% of the time; only 5% of our retained fits are at these energies.

The data presented in this study include some measurements made during transient events, such as shocks and coronal mass ejections (CMEs). During such events, the eVDF can exhibit properties that are not representative of the ambient fast wind; e.g. “counter-streaming” strahls associated with CMEs. Due to the complexity

of the task of sorting our data for all events that could potentially exhibit anomalous anti-sunward strahls, we assume such events to be infrequent enough as to not appreciably bias our data. To justify this assumption, we have conducted a preliminary study, in which we repeated the analysis presented in this section, but excluded data measured during times when a CME passed the Earth (as tabulated in Richardson & Cane (2010)). This exclusion had minimal effect on the plots presented in figures 3, 4, and 5. We note also that of the eVDF measurements used for fitting here, that took place after May 27, 1996 (the date of the first CME in the index), only 16% were measured during the transit of a near-Earth CME.

3.4 Fitting to F_{ave}

Having analyzed the angular variation of the strahl in detail, we now conduct a new comparison between the data and equation 25, with 2D fits that describe the variation of the eVDF with both angle and energy. We will assume the function $C(v)$ appearing in equation 25 is a power law, so that our strahl model can be expressed in the form:

$$F(x, \xi, \mu) = C_0(x/x_0)^{\alpha_s} \xi^\epsilon \exp \left\{ \tilde{\gamma}(x) \Omega \xi^2 (1 - \mu) \right\}. \quad (38)$$

Here α_s and C_0 are constants to be determined via the fitting procedure, and we introduced the parameter ϵ for notational convenience:

$$\epsilon \equiv \alpha' - \alpha + \frac{\alpha_s}{\alpha_T}. \quad (39)$$

For convenience, we give here the expressions of Ω , ϵ , and $\tilde{\gamma}(x)$ in terms of the basic parameters α_n , α_T , α_B , and α_s :

$$\Omega = \alpha_B(2\alpha_T - \alpha_n) - \alpha_n - 1, \quad (40)$$

where we assumed $\beta = 1$, the value for a proton-electron plasma,

$$\epsilon = \frac{1}{\alpha_T} \left(1 + 2\alpha_n - \frac{3}{2} \alpha_T + \alpha_s + \alpha_n \alpha_B - 2\alpha_T \alpha_B \right), \quad (41)$$

and

$$\tilde{\gamma}(x) = -\gamma(x)/\alpha_T, \quad (42)$$

where the Knudsen number $\gamma(x)$ is defined in Eq. (3).

Since each angular distribution f_s was measured at a single energy by the SWE strahl detector, for the purpose of filling out the μ - ξ space with data we must develop a method of combining multiple measurements. We choose to do this by computing an average distribution $F_{ave}(\mu, \xi)$ from the data, which will be used for our 2D fits. $F_{ave}(\mu, \xi)$ is composed from data that are measured in principle at many different times within our > 6 year period of study, and may be associated with many different flux tubes. Since we expect the prevalence of the strahl to vary significantly with collisionality, we will only average together distributions that fall within a narrow range of Knudsen numbers.

We first note that the function $F(\mathbf{v}/v_{th})$ can be computed from the local distribution $f(\mathbf{v})$ by normalizing to the local density and thermal speed (Horaites et al. 2015):

$$F(\mathbf{v}/v_{th}) = \frac{f(\mathbf{v}) v_{th}^3}{n} \quad (43)$$

Equation 43 follows from equation 1 and the normalizations $\int f d^3v = n$, $\int F d^3(v/v_{th}) = 1$.

The mean distributions F_{ave} are computed after fitting the angular distributions f_s for the strahl width, a process that was described in section 3.3. That is, for each cleaned angular distribution

f_s , the associated normalized distribution F_s is calculated according to equation 43 using the local plasma parameters n , v_{th} . The angular bins of F_s are assigned coordinates² μ and ξ , which are then sorted into a μ - ξ grid with resolution $\Delta\mu = 0.0005$, $\Delta\xi = 1$. All of the strahl data from our $>100,000$ fits are sorted in this way and averaged by μ - ξ bin to construct the distribution F_{ave} . As mentioned, we expect the distribution to depend on the Knudsen number, so we sort the data by $\tilde{\gamma}$ (calculated from n and T) when computing F_{ave} . We bin by $\tilde{\gamma}$ logarithmically, covering the range $0.365 < \tilde{\gamma} < 3.651$ in 8 bins. This range contains $\sim 90\%$ of our fast wind strahl measurements. Cuts of F_{ave} , for these 8 Knudsen numbers, are shown as points in figure 6. The error bars displayed are the nominal standard deviation of the mean that is computed during the averaging process.

Once the average distribution $F_{ave}(\mu, \xi)$ is constructed, we fit the data to our model function, equation 38. The parameters C_0 , ϵ , and Ω are determined by a nonlinear least squares fit. For the purpose of fitting, $\tilde{\gamma}$ is set to a fixed value, the geometric mean of the maximum and minimum $\tilde{\gamma}$ that were used to bin F_{ave} . A comparison between F_{ave} and our fitted model function is shown in figure 6. In the interest of presenting the data clearly, we choose to fit along only a few cuts of F_{ave} . Namely, we fit to data along the cuts $\mu = 0.9995, 0.9960, 0.9850, 0.9660, 0.9395, 0.9065$, which corresponds with roughly 5° spacing in pitch angle. These cuts of our fit function are shown as lines in the figure.

Some cuts in figure 6 span a larger energy range than others, because the data must satisfy multiple selection criteria to be included in the fit. Two of these selection criteria are based on the expected width of the strahl at each energy ξ , which we predicted by assuming $\Omega = -0.34$ (section 3.3). First, if F at a given angle is expected to be less than 1/5 the peak ($\mu = 0$) value at that same energy, then the data are not included in the fit; this is to prevent any accidental contamination by the halo.³ Second, if the expected θ_{FWHM} at a given energy is less than 10° , these data are not included; this is to ensure that the measured strahl is resolved by the detector. Additionally, we only include data that falls in the energy range $\xi > 5$, because our model equation was derived under the assumption $\xi \gg 1$.

The results of our fits, for various Knudsen numbers, are summarized in table 1. We note that the overall amplitude of the strahl, C_0 , increases with $\tilde{\gamma}$. This is as expected, since more runaway electrons should be observed as collisionality decreases. The fit parameter ϵ , which dictates the energy dependence of the strahl amplitude, seems fairly independent of $\tilde{\gamma}$, with $\epsilon \approx -2.1$ for all 8 fits. The fit parameter Ω is also fairly constant, with $\Omega \approx -0.3$ describing most fits well. The fits are in reasonable agreement with our previous estimate $\Omega = -0.34$ (section 3.3).

4 DISCUSSION

The shape of the strahl distribution is characterized by the fit parameters Ω and ϵ in our model. We would like to determine whether our observed values of Ω and ϵ are consistent with the known structure of the solar wind. This structure is described by the parameters α_n , α_T , and α_B .

² The energy $\xi = \mathcal{E}/T$ is calculated from the detector energy \mathcal{E} and local temperature T , while μ depends on each angular bin and on the \hat{B} direction that was determined during the angular fitting procedure (section 3.3).

³ see also step ‘‘Remove the halo’’ of our data cleaning procedure, section 3.2

The parameters Ω and ϵ are measured in this paper, so we will treat them as given. If we select values for two parameters in the set $\{\alpha_n, \alpha_T, \alpha_B, \alpha_s\}$, the remaining two are determined by equations 40, 41. We believe that α_n and α_B are the best-understood of these four, so we will take these values from observations and solve for α_T , α_s . We can consider our model to be reasonable if all these values are within experimental error.

Inverting equations 40, 41, we find equations for α_T and α_s , in terms of the other parameters:

$$\alpha_T = \frac{\Omega + \alpha_n(\alpha_B + 1) + 1}{2\alpha_B}, \quad (44)$$

$$\alpha_s = \alpha_T(\epsilon + 2\alpha_B + 3/2) - \alpha_n(\alpha_B + 2) - 1. \quad (45)$$

Let us see which values of α_T , α_s are predicted by our model for the typical fast wind, $\tilde{\gamma} \approx 0.75$. We will at first neglect the flux tube curvature and substitute the observed radial power law indices directly into equations 44, 45. Let us assume the bulk solar wind is spherically expanding and has reached its asymptotic velocity, so $\alpha_n = -2$ (which follows from the continuity equation). Mariani et al. (1979) found $B \propto r^{-1.86}$ using Helios 2 fast wind data gathered over the range of heliocentric distances $0.3AU < r < 1AU$, so let us assume $\alpha_B = -1.86$. If we substitute these values for α_n and α_B into equation 44, while while also letting $\Omega = -0.30$, $\epsilon = -2.14$ (see table 1), we predict $\alpha_T = -0.65$. Then it follows $\alpha_s = 2.12$ from equation 45.

This predicted value of α_T is consistent with the observed radial scaling of the fast wind core temperature, $T \propto r^{-0.64}$, measured by Pilipp et al. (1990) using Helios 1 data. These findings are summarized in table 2. Here the column ‘‘Measured (radial)’’ quotes empirical values, uncertainties, and relevant references. The adjacent column, ‘‘Model (radial)’’, presents the set of values described above, that are consistent with our model.

Technically, the effective power law indices that describe variation along a curved flux tube will differ from the radial indices quoted above. We can estimate these effective indices by assuming the flux tube forms an arm in the Parker spiral. Let us assume that the Parker spiral angle $\theta_P \equiv \hat{B} \cdot \hat{r}$ in the ecliptic follows the well-known formula $\tan \theta_P(r) = wr/v_{sw}$. This follows from magnetic flux conservation, assuming the nominal angular velocity of the Sun’s rotation ω and the solar wind speed v_{sw} are both constant. Observations show $\theta_P \approx 45^\circ$ at $r = 1$ AU (e.g., Luhmann et al. 1993), so let us write $\tan \theta_P = r/r_0$, where $r_0 = 1$ AU. We can define the distance x along such a flux tube in terms of r , i.e. $x(r) = \int_0^r dr'/\cos \theta_P(r')$. Evaluating this integral, we find:

$$x(r) = \frac{r_0}{2} \left\{ \frac{r}{r_0} \sqrt{\left(\frac{r}{r_0}\right)^2 + 1} + \ln \left[\frac{r}{r_0} + \sqrt{\left(\frac{r}{r_0}\right)^2 + 1} \right] \right\}. \quad (46)$$

Consider now a physical quantity, Y , that varies as a power law with heliocentric distance: $Y(r) = Y_0(r/r_0)^{\alpha_Y}$, where Y_0 and α_Y are constants. The local power law along the flux tube, $d \ln Y / d \ln x(r)$, evaluated at $r = r_0$ is:

$$\frac{d \ln Y}{d \ln x(r)} \Big|_{r=r_0} = \frac{\sqrt{2} + \ln(1 + \sqrt{2})}{2\sqrt{2}} \alpha_Y \approx 0.812 \alpha_Y. \quad (47)$$

We see from equation 47 that a power law with respect to r will appear (locally) as a shallower power law with respect to x . In the column ‘‘Measured (curvilinear)’’ of table 2, we correct for the curvature of the Parker spiral at 1 AU by multiplying the values of

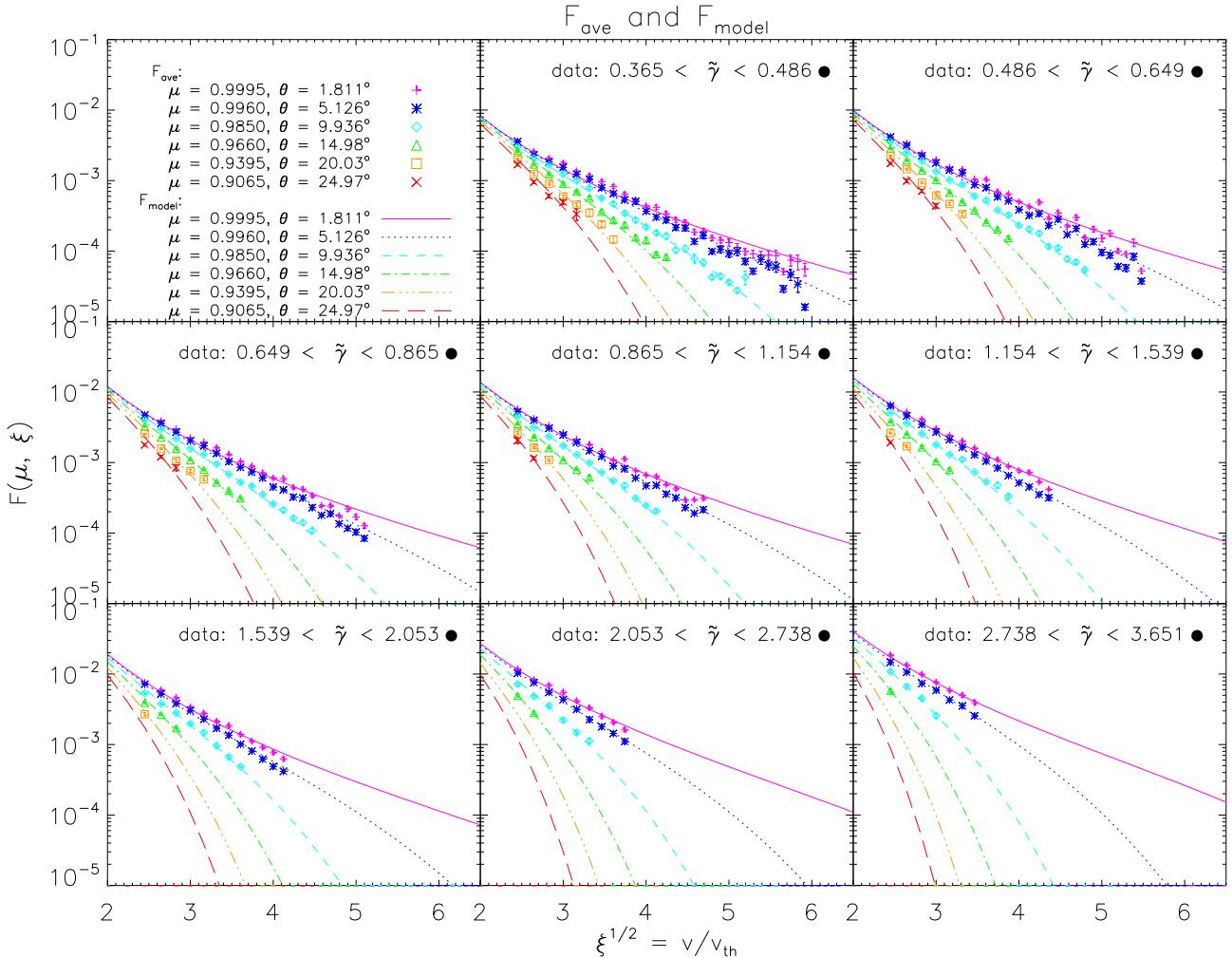


Figure 6. The 2D strahl distributions $F_{ave}(\mu, \xi)$ are constructed from averaging pitch angle distributions measured by the SWE strahl detector, from fast wind data where $\tilde{\gamma}$ falls within a given range. Data are selected only where the strahl amplitude is sufficiently above the background, and where the strahl is expected to be resolved (see section 3.4). Cuts of F_{ave} are shown as points. Fits to a Coulomb scattering model (F_{model}), given by equation 38, are plotted as lines. Parameters of the fits are displayed in table 1.

α_n , α_T and α_B reported in column ‘‘Measured (radial)’’ by a factor of 0.812. This describes the effective power law that is relevant to our solutions to the drift-kinetic equation. We then repeat our previous analysis, by setting α_n , α_B , Ω , ϵ to their measured values, and solving for α_T and α_s from equations 44, 45. The resulting values, shown in column ‘‘Model (curvilinear)’’ of table 2, are self-consistent with regards to our model and are in good agreement with observations of the solar wind’s large-scale structure.

Table 2 serves to illustrate the ease with which observations of the strahl shape can be explained in terms the solar wind’s large scale structure. We note that the values of these structural parameters are subject to appreciable experimental uncertainty, and the ‘‘true’’ values may be significantly different from those quoted here. In particular, different published measurements of α_T in the fast wind near 1 AU vary quite widely, with some measurements falling well outside the error bars quoted from our reference, Pilipp et al. (1990). For a review of published measurements of α_T , see Maksimovic et al. (2000). We note it is generally agreed that temperature varies with a significantly flatter profile than $\alpha_T = -4/3$, the value associated with adiabatic expansion.

In both the radial and curvilinear models displayed in Table 2, we predict $\alpha_s > 0$. The positive sign of α_s means that the amplitude of the strahl (in our normalized distribution F) should increase with heliocentric distance r . This prediction holds even if we allow the input parameters of our model to vary by $\pm 20\%$. We highlight this prediction because it is in some conflict with the observations of Maksimovic et al. (2005) and Šverák et al. (2009), which showed that the strahl density (relative to core density) actually *decreases* with r .

To address this point, let us consider Figure 10 of Šverák et al. (2009). The upper right panel of that figure shows the parallel cuts of the average fast wind eVDF at different heliocentric distances. The eVDF can be roughly interpreted as a cut of $F(\mathbf{v}/v_{th})$, up to an amplitude coefficient, since the velocities shown on the x-axis are normalized to the core thermal speed, as in our equation 1. Their figure indeed shows that the strahl diminishes with r , but only in the velocity range $v_{\parallel}/v_{th} \lesssim 5$. We note that the trend is fairly weak, so that although α_s is negative we can estimate $|\alpha_s| < 1$ from their plot. At higher velocities the opposite trend can be observed: the relative strahl amplitude actually increases with distance, in

$\tilde{\gamma}$ range (F_{ave})	nominal $\tilde{\gamma}$ (F_{model})	C_0	ϵ	Ω	
—	—	model: $F(\mu, \xi) = C_0 \xi^\epsilon \exp\{\tilde{\gamma} \Omega \xi^2 (1 - \mu)\}$			
0.365 < $\tilde{\gamma}$ < 0.486	$\tilde{\gamma} = 0.421$	0.157 ± 0.011	-2.13 ± 0.031	-0.38 ± 0.013	
0.486 < $\tilde{\gamma}$ < 0.649	$\tilde{\gamma} = 0.562$	0.191 ± 0.014	-2.14 ± 0.033	-0.35 ± 0.013	
0.649 < $\tilde{\gamma}$ < 0.865	$\tilde{\gamma} = 0.749$	0.234 ± 0.019	-2.14 ± 0.035	-0.30 ± 0.012	
0.865 < $\tilde{\gamma}$ < 1.154	$\tilde{\gamma} = 1.000$	0.264 ± 0.020	-2.13 ± 0.033	-0.28 ± 0.011	
1.154 < $\tilde{\gamma}$ < 1.539	$\tilde{\gamma} = 1.333$	0.306 ± 0.025	-2.13 ± 0.036	-0.27 ± 0.010	
1.539 < $\tilde{\gamma}$ < 2.053	$\tilde{\gamma} = 1.778$	0.401 ± 0.040	-2.19 ± 0.045	-0.25 ± 0.011	
2.053 < $\tilde{\gamma}$ < 2.738	$\tilde{\gamma} = 2.371$	0.485 ± 0.053	-2.08 ± 0.050	-0.28 ± 0.010	
2.738 < $\tilde{\gamma}$ < 3.651	$\tilde{\gamma} = 3.162$	0.669 ± 0.065	-2.02 ± 0.046	-0.28 ± 0.009	

Table 1. Model parameters C_0 , ϵ , Ω corresponding with fits displayed in figure 6. The range of $\tilde{\gamma}$ listed in each row represents the Knudsen numbers spanned by the data used to create F_{ave} . The column “nominal $\tilde{\gamma}$ ” shows the Knudsen number used for the fit.

—	Measured (radial)	Model (radial)	Measured (curvilinear)	Model (curvilinear)
Ω	-0.30 ± 0.01 (present paper)	-0.30	-0.30 ± 0.01 (present paper)	-0.30
ϵ	-2.14 ± 0.04 (present paper)	-2.14	-2.14 ± 0.04 (present paper)	-2.14
α_n	-2	-2	-1.62	-1.62
α_B	-1.86 ± 0.05 (Mariani et al. 1979)	-1.86	-1.51 ± 0.04	-1.51
α_T	-0.64 ± 0.06 (Pilipp et al. 1990)	-0.65	-0.52 ± 0.05	-0.51
α_s	see “Discussion”	2.12	see “Discussion”	1.65

Table 2. Comparison between observations of the large-scale structure in the fast solar wind and a set of parameters that is consistent with our model (eq. 38). The relevant reference for each nominal observational value is given in parentheses in the “Measured (radial)” column. Values of α_n , α_T , α_B in the “Measured (curvilinear)” column are found by multiplying the corresponding values in the “Measured (radial)” column by 0.812 (eq. 47). This approximates the local power law along a curved Parker spiral flux tube. Each “Model” column is identical to the corresponding “Measured” column, except for the values of α_T and α_s , which are obtained from equations 44, 45, given the other model parameters.

agreement with our model. We note that this regime $v \gg v_{th}$ is actually where our model is most applicable, since in our derivation we assumed $\xi \gg 1$ and dropped terms that were low order in ξ (e.g. the electric field terms). The strahl is certainly present at these energies⁴, and is well above the halo background. However, only some of our current measurements apply to this regime; velocities only as high as $v \approx 6v_{th}$ are used in our fits to F_{ave} (figure 6). As discussed in section 3.4, these data are excluded because the strahl becomes unresolved at high energies. We conclude that the rate of strahl growth relative to the core ($\sim \alpha_s$), at both intermediate and very high strahl energies, deserves further empirical investigation.

Since current empirical evidence indicates that the relative amplitude of the strahl at intermediate energies diminishes with increasing r , we must account for this discrepancy between the data and our model. One possible explanation is that the regime $v \lesssim 5v_{th}$ is not truly asymptotic, so that the electric field terms (which we neglected) should be considered at these energies. Unfortunately, if we include the electric field terms in the steps following equation 9 in section 2, we run into two difficulties. First, the spatial dependence of the ambipolar field $\gamma_E(x)$ must be assumed, and this quantity is model-dependent and not directly measurable by current satellites. Second, there is no guarantee that closed form analytic solutions, analogous to equation 24, can be found if the electric field terms are included. The problem appears intractable, for instance, if we

assume $\gamma_E \propto \gamma$. We note ambipolar electric forces can be included in kinetic simulations (e.g., Smith et al. 2012), so that the effect of γ_E may be understood through numerical analysis.

Finally, we note that other diffusion mechanisms, such as wave-particle interactions, may affect the solar wind strahl. Indeed, Štverák et al. (2009) suggest the diminishment of the relative strahl density with distance, and the corresponding increase in halo density, might indicate that wave-particle interactions scatter strahl electrons into the halo population (see also Gurgiolo et al. 2012). We do not make an effort to include wave-particle scattering into our current model, as this would greatly complicate our discussion. However, we do note that if such interactions can be expressed in terms of a pitch angle diffusion operator, it may be possible to predict a form for the strahl distribution via methods analogous to those introduced in section 2.

5 SUMMARY AND CONCLUSIONS

The theory developed in this paper should be understood as a reduced model of solar wind electron kinetics. Our model assumes an ordered structure of the large-scale profiles of n , T , and B , which allows the drift kinetic equation to be written in a tractable form. This yields, for the first time, a simple analytic prediction for the shape of the strahl distribution (equation 25). In the present paper we show this prediction captures the essential features of strahl eVDFs in the ambient fast wind. In particular, we find that at a given energy, the strahl is approximately Gaussian with respect to the pitch angle θ . We obtain scaling relations (i) and (ii), which describe how the beam width θ_{FWHM} varies with energy and density. We verify the accuracy of our model by comparing it with data collected by the Wind satellite’s SWE strahl detector, which sampled the eVDF at high angular resolution.

Our model’s success in predicting the strahl widths strongly

⁴ See e.g., Figure 4, Ogilvie et al. (2000). On May 11, 1999, a narrow strahl beam was observed up to the highest energy sampled by the SWE strahl detector, ~ 1200 eV. Comparing with the local temperature T , this energy corresponds with $v/v_{th} \approx 6.5$. We have checked this distribution by hand (not shown), which indeed exhibits a high-energy strahl. However, we believe the distribution is too narrow to be resolved by the detector. Indeed, if the strahl continues to narrow at high energies, the detector may not register significant counts even if the field-parallel (peak) amplitude of the strahl is significant, and falsely appear to be subsumed by the halo.

supports the view that Coulomb collisions are an important source of pitch angle scattering. We note also that the temperature Knudsen number γ , which describes Coulomb collisionality, plays a central role in our model. Indeed, γ appears to be an important parameter for ordering strahl eVDFs (figure 6), and we observe the strahl amplitude (C_0) is correlated with γ (table 1). However, we cannot say definitively that strahl scattering is only due to Coulomb collisions, as it seems our model's predictiveness might be improved by incorporating another physical effect.

Our observations show that the strahl narrows with energy, in agreement with previous measurements (e.g., Feldman et al. 1978; Pilipp et al. 1987; Fitzenreiter et al. 1998; Ogilvie et al. 2000). However, one survey of strahl eVDFs measured at 1 AU by ACE (Anderson et al. 2012) indicated that the strahl width broadens 40% and narrows 60% of the time. This trend is not seen in our current observations of the fast wind, in which the strahl appears systematically narrower at higher energies. We have conducted a preliminary investigation of SWE strahl detector data measured in the slow wind (not shown), and again find narrower strahls at higher energies. The discrepancy with (Anderson et al. 2012) may be due to differences in methodology and data selection—their study presented a broad survey of strahl data, whereas the current work deals with narrow, prominent strahls in the fast wind. We note that the SWE strahl detector samples only a $\sim 50 \times 60$ degree field of view, so that we may have difficulty identifying very broad strahls. Finally, we note that identification of the strahl, as distinguished from the core and halo populations that also help form the distribution, is in part a matter of definition (see e.g., Štverák et al. 2009).

The presence of the arbitrary function $C(v)$ makes our model (eq. 25) quite flexible, in that it can be matched to any energy spectrum observed at 1 AU. The function $C(v)$ carries information about the electrons' origin—as argued in e.g., Smith et al. (2012), the energy spectrum of the strahl may be a vestige of the thermal distribution of electrons near the base of the corona. In practice, we find that $C(v)$ can be matched well to a power law (eq. 38). However, matching our model to the eVDFs at 1 AU leads us to predict that the relative strahl amplitude should grow with heliocentric distance ($\alpha_s > 0$), which appears to conflict with observations. So, our model may require further theoretical development, motivated by detailed observations of the strahl over a range of heliocentric distances. Like Lemons & Feldman (1983), we consider wave-particle interactions to be a potentially important source of strahl scattering.

As discussed in Saito & Gary (2007), the energy dependence of strahl widths is intimately connected with the energy dependence of the diffusion operator. For diffusion caused by turbulent wave-particle interactions, the relevant diffusion operator in the kinetic equation is determined by the properties of the waves and their turbulent spectrum. Therefore, the observed shape of the strahl should help direct the search for theories of anomalous diffusion caused by wave-particle scattering. We intend to discuss this in future work.

APPENDIX A:

As mentioned in section 2, we may reduce equation 24 to a scale-invariant form by assuming either $\beta C_2(v) \xi^{-\alpha'} / G(v) \gg 1$ or $\beta C_2(v) \xi^{-\alpha'} / G(v) \ll 1$. Our model function (25) corresponds with the former case. We will now consider the latter case, and show that it is inconsistent with our observations of the solar wind strahl.

Let us assume

$$\beta C_2(v) \xi^{-\alpha'} / G(v) \ll 1, \quad (\text{A1})$$

so that equation 24 can be written approximately as

$$F(v, \xi, \mu) = C_1(v) \xi^{-\alpha} \exp \left\{ \alpha' C_2(v) \xi^{\kappa-\alpha'} (1-\mu) \right\}, \quad (\text{A2})$$

where $C_1(v)$ and $C_2(v)$ are arbitrary functions. If we try to match equation A2 to the observed strahl, the function $C_2(v)$ can be constrained by recalling scaling relation (i): the strahl width is inversely proportional to the energy (figure 4). If we recast equation A2 in terms of x, ξ, μ , we then require an overall factor ξ^2 to appear inside of the exponential function. This can only be accomplished if we assume $C_2(v)$ has the form:

$$\begin{aligned} C_2(v) &= C_3 G(v) \left(\frac{v}{v_{th,0}} \right)^{2\alpha'} \\ &= C_3 G(v) \xi^{\alpha'} \left(\frac{x}{x_0} \right)^{\alpha' \alpha_T}. \end{aligned} \quad (\text{A3})$$

Here, C_3 is a dimensionless constant, and the function $G(v)$ is given by equation 21. Substituting (A3) into equation A2 yields a prediction for the strahl width. At the position of the Wind satellite, $x = x_0$, this formula for the angular variation of the strahl at a given energy ξ can be written:

$$\begin{aligned} F(\mu) &\propto \exp \{ C_3 \alpha' \gamma(x_0) \xi^2 (1-\mu) \}. \\ &= \exp \{ \tilde{\gamma}(x_0) \Omega' \xi^2 (1-\mu) \}. \end{aligned} \quad (\text{A4})$$

Here we introduced the notation $\Omega' \equiv -C_3 \alpha' \alpha_T$. Equation A4 is analogous to equation 28, and has a similar form. If we were to fit the strahl distribution f_s to (A4), we would find values of Ω' identical to the values of Ω found in section 3.3. So let us identify $\Omega \sim \Omega'$, and estimate the value of C_3 that would be consistent with our measurements:

$$C_3 = \frac{-\Omega'}{\alpha' \alpha_T} \sim 1/\beta \quad (\text{A5})$$

However, from (A3), the scale-invariant assumption (A1) reduces to the requirement $C_3 \ll 1/\beta$, at the position of the Wind satellite $x = x_0$. We therefore have a contradiction, and judge eq. A2 to be less consistent with observed solar wind profiles than eq. 25. In other words: the measured solar wind profiles ($\alpha_n, \alpha_T, \alpha_B$) and strahl widths (characterized by Ω , see eq. 40) conform well with the model studied in this paper (see table 2)—these same parameters could not be explained by a scale-invariant solution based on the assumption (A1).

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