Low-Cost Remote Supervisory Control System for an Industrial Process

Abstract

A low-cost remote supervisory control capability is added to a packaging process, in which a lowvoltage signal is used to communicate between a distant HMI control panel and a PLC network using the AC power line as a communication medium. The network is a star-topology and uses a Materslave protocol. Remote Supervisory control is achieved using a user-defined toolbox of control functions.

In this system, a Programmable Logic Controller (PLC) is used to control a process and interface with the operator through a Human Machine Interface (HMI) Panel. A star topology ethernet network is used to connect the PLCs and the HMI panel.

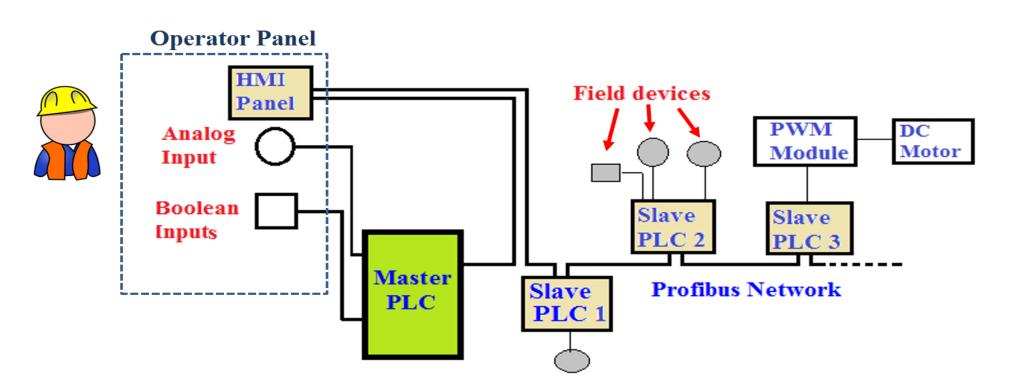
Introduction

- . Supervisory Control and Data Acquisition Systems (SCADA) are commonly used in factory settings to provide a centralized control and monitoring of processes in industrial plants [1-6].
- . These systems consist of a master computer unit connected to Programmable Logic Controllers (PLCs), which are connected to field devices such as actuators, motors, CNC machines, and sensors.
- . The master control unit is equipped with a sophisticated software such as Matlab [1] to perform the control functions as well as a capability to be interfaced to the PLC devices.
- . SCADA systems are also used in a wide range of applications that include water and gas distribution systems [3]



Results: Model 1 of this Project

A low-Cost supervisory control system was designed and illustrated in reference [4].

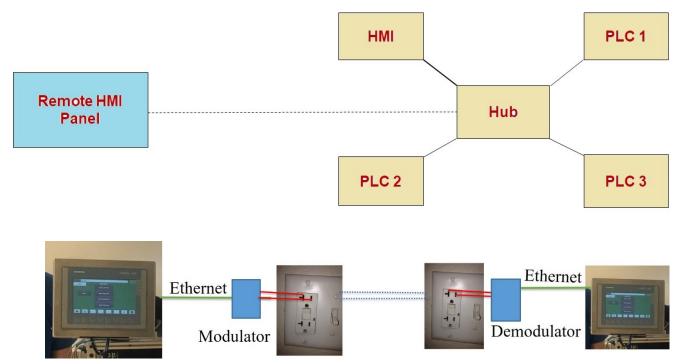


Features of this model:

- 1.The system implemented speed control of a DC motor over a deterministic Profibus Network.
- 2.The system used a collection of block-oriented Ladder Logic programs collected in a toolbox of programs that may be used as multi-purpose functions.

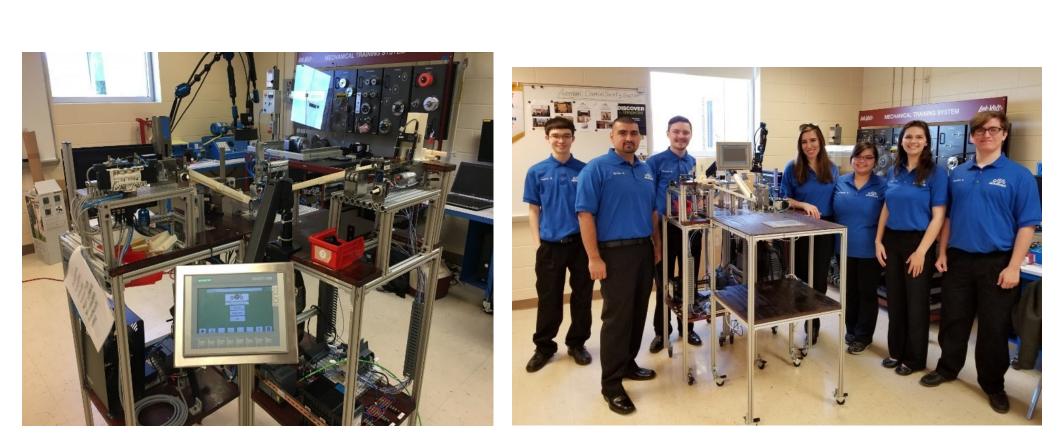
Model 2: Remote Supervisory Control and Data Acquisition

The first model was improved:



Features of this model:

- 1.The system used a star-topology network over the bus topology that was used in model 1
- 2.A remote control capability was added in which the HMI remote control panel is connected to the network through the power line at a high frequency.
- 3.Block-oriented programming is used in this model as well, in which a toolbox of functions is used.
- 4.Data acquisition is demonstrated through the use of a vision system and other sensory systems.



The Low-Cost Remote Supervisory Control System is demonstrated on a bearing packaging process, that includes three stations that perform package cap and body dispensing and handling, and assembly and quality check functions.

Yasmin Musa, Omar Tantawi, Khalid H. Tantawi^{1*}

¹Mechatronics Department, Motlow State Community College, Smyrna, TN 37167 ^{*}Email: <u>ktantawi@mscc.edu</u>

Conclusion:

. A Low-Cost Remote Supervisory Control System is designed and built.

. The system uses ladder logic functions that are packaged together in a toolbox.

. Two models were built:

the first model is demonstrated on a dc motor control,

and used a bus-topology network

The second model included a remote control capability demonstrated on a bearing packaging process.

References

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