



The Relativistic Euler Equations: Remarkable Null Structures and Regularity Properties

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Abstract. We derive a new formulation of the relativistic Euler equations that exhibits remarkable properties. This new formulation consists of a coupled system of geometric wave, transport, and transport-div-curl equations, sourced by nonlinearities that are null forms relative to the acoustical metric. Our new formulation is well-suited for various applications, in particular, for the study of stable shock formation, as it is surveyed in the paper. Moreover, using the new formulation presented here, we establish a local well-posedness result showing that the vorticity and the entropy of the fluid are one degree more differentiable compared to the regularity guaranteed by standard estimates (assuming that the initial data enjoy the extra differentiability). This gain in regularity is essential for the study of shock formation without symmetry assumptions. Our results hold for an arbitrary equation of state, not necessarily of barotropic type.

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1. Introduction

The relativistic Euler equations are the most well-studied PDE system in relativistic fluid mechanics. In particular, they play a prominent role in cosmology, where they are often used to model the evolution of the average matter-energy content of the universe; see, for example, Weinberg's well-known monograph [40] for an account of the role that the relativistic Euler equations play in the standard model of cosmology. The equations are also widely used in astrophysics and high-energy nuclear physics, as is described, for example, in [28]. Our main result in this article is our derivation of a new formulation of the relativistic Euler equations that reveals remarkable new regularity and null structures that are not visible relative standard order formulations. The

new formulation is available for an arbitrary equation of state, not necessarily of barotropic¹ type. Below we will describe potential applications that we anticipate will be the subject of future works. We mention already that our new formulation of the equations provides a viable framework for the rigorous mathematical study of stable shock formation without symmetry assumptions in solutions to the relativistic Euler equations; for reasons to be explained, standard first-order formulations are not adequate for tracking the behavior of solutions (without symmetry assumptions) all the way to the formation of a shock or for extending the solution (uniquely, in a weak sense tied to suitable selection criteria) past the first singularity.

We derive the new formulation by differentiating a standard first-order formulation with various geometric differential operators and observing remarkable cancellations.² The calculations are rather involved and make up the bulk of the article. We have carefully divided them into manageable pieces; see Sects. 4–8. Readers can jump ahead to Theorem 1.2 for a rough statement of the equations and Theorem 3.1 for the precise version.

As we alluded to above, the relativistic Euler equations are typically formulated as a first-order quasilinear hyperbolic PDE system. In our new formulation, the equations take the form of a system of covariant wave equations coupled to transport equations and to two transport-div-curl systems. The new formulation is well suited for various applications in ways that first-order formulations are not. In particular, the equations of Theorem 3.1 can be used to prove that *the vorticity and entropy are one degree more differentiable than one might naively expect* (assuming that the gain in differentiability is present in the initial data). This gain in differentiability is crucial for the rigorous mathematical study of some fundamental phenomena that occur in fluid dynamics. In particular, this gain, as well as other structural aspects of the new formulation, is essential for the study of shock waves (without symmetry assumptions) in relativistic fluid mechanics; see Sect. 1.2 for further discussion. Although the gain in differentiability for the vorticity had previously been observed relative to Lagrangian coordinates [13, 15], Lagrangian coordinates are inadequate, for example, for the study of the formation of shock singularities because they are not adapted to the acoustic characteristics, whose intersection corresponds to a shock. Hence, it is of fundamental importance that our new formulation allows one to prove the gain in differentiability relative to *arbitrary vectorfield differential operators* (with suitably regular coefficients). In this vein, we also mention the works [9–11] on the non-relativistic compressible Euler equations, in which a gain in differentiability for the vorticity was shown relative to Lagrangian coordinates, and the first author’s joint work [12], in which elliptic

¹Barotropic equations of state are such that the pressure is a function of the proper energy density ρ alone.

²In observing many of the cancellations, the precise numerical coefficients in the equations are important; roughly, these cancellations lead to the presence of the null-form structures described below. However, for most applications, the overall coefficient of the null forms is not important; what matters is that the cancellations lead to null forms.

estimates were used to show that for the non-relativistic barotropic compressible Euler equations, it is possible to gain one derivative on the density relative to the velocity (again, assuming that the gain is present in the initial data).

We also highlight the following key advantage of our new formulation:

It dramatically enlarges the set of energy estimate techniques that can be applied to the study of the relativistic Euler equations. More precisely, the new formulation partially decouples the “wave parts” and “transport parts” of the system and unlocks our ability to apply the full power of the commutator and multiplier vectorfield methods to the study of the wave part; see Sect. 9.6 for further discussion.

For applications to shock waves, it is fundamentally important that one is able to use the full scope of the vectorfield method on the wave part of the system; see the introduction of [23] for a discussion of this issue in the related context of the non-relativistic barotropic compressible Euler equations with vorticity. In particular, our new formulation of the equations allows one to derive a coercive energy estimate for the wave part of the system for any multiplier vectorfield that is causal relative to the acoustical metric g of Definition 2.6 and on any hypersurface that is null or spacelike relative to g ; see Sect. 9.6.1 for further discussion. In contrast, for first-order hyperbolic systems (a special case of which is the relativistic Euler equations) without additional structure, there is, up to scalar function multiple, only one³ available energy estimate on each causal or spacelike hypersurface.

Our second result in this article is that we provide a proof of local well-posedness for the relativistic Euler equations that relies on the new formulation; see Theorem 9.12. The new feature of Theorem 9.12 compared to standard proofs of local well-posedness for the relativistic Euler equations is that it provides the aforementioned gain in differentiability for the vorticity and entropy. Although many aspects of the proof of the theorem are standard, we also rely on some geometric and analytic insights that are tied to the special structure of our new formulation of the equations and thus are likely not known to the broader PDE research community; see the end of Sect. 1.2.3 for further discussion of this point.

³Here we further explain how standard first-order formulations of the relativistic Euler equations limit the available energy estimates. In deriving energy estimates for the relativistic Euler equations in their standard first-order form, one is effectively controlling the wave and transport parts of the system at the same time, and, up to a scalar function multiple, there is only one energy estimate available for transport equations. To see this limitation in a more concrete fashion, one can rewrite the relativistic Euler equations in first-order symmetric hyperbolic form as $A^\alpha(\mathbf{V})\partial_\alpha \mathbf{V} = 0$, where \mathbf{V} is the array of solution variables and the A^α are symmetric matrices with A^0 positive definite; see, for example, [27] for a symmetric hyperbolic formulation of the general relativistic Euler equations in the barotropic case. The standard energy estimate for symmetric hyperbolic systems is obtained by taking the Euclidean dot product of both sides of the equation with \mathbf{V} and then integrating by parts over an appropriate spacetime domain foliated by spacelike hypersurfaces. The key point is that for systems without additional structure, no other energy estimate is known, aside from rescaling the standard one by a scalar function.

For convenience, throughout the article, we restrict our attention to the special relativistic Euler equations, that is, the relativistic Euler equations on the Minkowski spacetime background (\mathbb{R}^{1+3}, η) , where η is the Minkowski metric. However, using arguments similar to the ones given in the present article, our results could be extended to apply to the relativistic Euler equations on a general Lorentzian manifold; such an extension could be useful, for example, in applications to fluid mechanics in the setting of general relativity. For use throughout the article, we fix a standard rectangular coordinate system $\{x^\alpha\}_{\alpha=0,1,2,3}$, relative to which $\eta_{\alpha\beta} := \text{diag}(-1, 1, 1, 1)$. See Sect. 2.1 for our index conventions. We clarify that in Sect. 9, we prove local well-posedness for the relativistic Euler equations (including the aforementioned gain in regularity for the vorticity and entropy) on the flat spacetime background $(\mathbb{R} \times \mathbb{T}^3, \eta)$, where the “spatial manifold” \mathbb{T}^3 is the three-dimensional torus and we recycle the notation in the sense that $\{x^\alpha\}_{\alpha=0,1,2,3}$ denotes standard coordinates on $\mathbb{R} \times \mathbb{T}^3$ (see Sect. 9.1.1 for further discussion) and η again denotes the Minkowski metric; the compactness of \mathbb{T}^3 allows for a simplified approach to some technical aspects of the argument while allowing us to illustrate the ideas needed to exhibit the gain in regularity for the vorticity and entropy.

Our work here can be viewed as extensions of the second author’s previous joint work [22], in which the authors derived a similar formulation of the non-relativistic compressible Euler equations under an arbitrary barotropic equation of state, as well as the second author’s work [33], which extended the results of [22] to a general equation of state. However, since the geo-analytic structures revealed by [22, 33] are rather delicate (that is, quite unstable under perturbations of the equations), it is far from obvious that similar results hold in the relativistic case. We also stress that compared to the non-relativistic case, our work here is substantially more intricate in that it extensively relies on decompositions of various spacetime tensors into tensors that are parallel to the four-velocity u and tensors that are η -orthogonal to u . In particular, we heavily exploit that many of the tensorfields appearing in our analysis exhibit improved regularity under u -directional differentiation *or* contraction against u .

1.1. Rough Statement of the New Formulation

In this subsection, we provide a schematic version of our new formulation of the equations; in Sect. 1.2, we will refer to the schematic version when describing potential applications. In any formulation of the relativistic Euler equations, there is great freedom in choosing state-space variables (i.e., the fundamental unknowns in the system). In this article, as state-space variables, we use the logarithmic enthalpy h , the entropy s , and the four-velocity u , which is a future-directed timelike vectorfield normalized by $\eta_{\alpha\beta}u^\alpha u^\beta = -1$. Other fluid quantities such as the proper energy density ρ , the pressure p will also play a role in our discussion, but these quantities can be viewed as functions of the state-space variables; see Sect. 2 for detailed descriptions of all of these variables as well as the first-order formulation of the equations that forms the starting point for our ensuing analysis.

As we mentioned earlier, our new formulation comprises a system of covariant wave equations coupled to transport equations and to two transport-div-curl systems. Roughly, the wave equations correspond to the propagation of sound waves, while the transport equations correspond to the transporting of vorticity and entropy along the integral curves of u . The transport-div-curl systems are needed to control the top-order derivatives of the vorticity and the entropy and to exhibit the aforementioned gain in differentiability. In addition to the state-space variables h , s , and u , our formulation also involves a collection of auxiliary⁴ fluid variables, including the entropy gradient one-form $S_\alpha := \partial_\alpha s$ and the vorticity ϖ^α , which is a vectorfield that is η -orthogonal to u (see Definition 2.2). Among these auxiliary variables, of crucial importance for our work is that we have identified new combinations of fluid variables that solve transport equations with unexpectedly good structure. These structures can be used to show that the combinations exhibit a gain in regularity compared to what can be inferred from a standard first-order formulation of the equations. We refer to these special combinations as “modified variables,” and throughout, we denote them by \mathcal{C}^α and \mathcal{D} ; see Definition 2.8.

The remaining discussion in this subsection relies on some schematic notation and refers to some geometric objects that are not precisely defined until later in the article:

- The notation “ \sim ” below means that we are only highlighting the maximum number of derivatives of the state-space variables that the auxiliary variables depend on. We note, however, that in practice, the precise structure of many of the terms that we encounter is important for observing the cancellations that lie behind our main results.
- “ ∂ ” schematically denotes the spacetime gradient with respect to the rectangular coordinates, and “ ∂^2 ” schematically denotes two differentiations with respect to the rectangular coordinates.
- $g = g(h, s, u)$ denotes the acoustical metric, which is Lorentzian (see Definition 2.6).
- $\varpi \sim \partial u + \partial h$ is the vorticity vectorfield (see Definition 2.2).
- $S_\alpha := \partial_\alpha s$ is the entropy gradient one-form.
- $\mathcal{C}^\alpha \sim \partial^2 u + \partial^2 h$ is a modified version of the vorticity of ϖ , that is, the vorticity of the vorticity (see Definition 2.8).
- $\mathcal{D} \sim \partial^2 s$ is a modified version of $\partial_\alpha S^\alpha$ (see Definition 2.8).
- $\mathfrak{Q}(\partial T_1, \dots, \partial T_m)$ denotes *special* terms that are quadratic in the tensorfields $\partial T_1, \dots, \partial T_m$. More precisely, the $\mathfrak{Q}(\partial T_1, \dots, \partial T_m)$ are linear combinations of the standard **null forms relative to g** ; see Definition 1.1 for the definitions of the standard null forms relative to g and Sect. 1.2.2 for a discussion of the significance that the special structure of these null forms plays in the context of the study of shock waves.
- $\mathfrak{L}(\partial T_1, \dots, \partial T_m)$ denotes linear combinations of terms that are at most **linear** in $\partial T_1, \dots, \partial T_m$; see Sect. 1.2.2 for a discussion of the significance of the linear dependence in the context of the study of shock waves.

⁴By “auxiliary,” we mean that they are determined by h , s , and u .

Before schematically stating our main theorem, we first provide the definitions of the standard null forms relative to g .

Definition 1.1 (*Standard null forms relative to g*). We define the standard null forms relative to g (which we refer to as “standard g -null forms” for short) as follows, where ϕ and ψ are scalar functions and $0 \leq \mu < \nu \leq 3$:

$$\begin{aligned}\mathfrak{Q}^{(g)}(\partial\phi, \partial\psi) &:= (g^{-1})^{\alpha\beta}(\partial_\alpha\phi)(\partial_\beta\psi), \\ \mathfrak{Q}_{\mu\nu}(\partial\phi, \partial\psi) &:= (\partial_\mu\phi)(\partial_\nu\psi) - (\partial_\nu\phi)(\partial_\mu\psi).\end{aligned}\quad (1.1)$$

We now present the schematic version of our main theorem; see Theorem 3.1 for the precise statements.

Theorem 1.2 (New formulation of the relativistic Euler equation (schematic version)). *Assume that (h, s, u^α) is a C^3 solution to the (first-order) relativistic Euler equations (2.17)–(2.19) + (2.20). Then h , u^α , and s also verify the following covariant⁵ wave equations, where the schematic notation “ \simeq ” below means that we have ignored the coefficients of the inhomogeneous terms and also harmless (from the point of view of applications to shock waves) lower-order terms, which are allowed to depend on h , s , u , S , and ϖ (but not their derivatives):*

$$\square_g h \simeq \mathcal{D} + \mathfrak{Q}(\partial h, \partial u) + \mathfrak{L}(\partial h), \quad (1.2a)$$

$$\square_g u^\alpha \simeq \mathcal{C}^\alpha + \mathfrak{Q}(\partial h, \partial u) + \mathfrak{L}(\partial h, \partial u), \quad (1.2b)$$

$$\square_g s \simeq \mathcal{D} + \mathfrak{L}(\partial h). \quad (1.2c)$$

In addition, s , S^α , and ϖ^α verify the following transport equations:

$$u^\kappa \partial_\kappa s = 0, \quad (1.3a)$$

$$u^\kappa \partial_\kappa S^\alpha \simeq \mathfrak{L}(\partial u), \quad (1.3b)$$

$$u^\kappa \partial_\kappa \varpi^\alpha \simeq \mathfrak{L}(\partial h, \partial u). \quad (1.3c)$$

Moreover, S^α verifies the following transport-div-curl system:

$$u^\kappa \partial_\kappa \mathcal{D} \simeq \mathcal{C} + \mathfrak{Q}(\partial S, \partial h, \partial u) + \mathfrak{L}(\partial h, \partial u), \quad (1.4a)$$

$$\text{vort}^\alpha(S) = 0, \quad (1.4b)$$

where the vorticity operator vort is defined in Definition 2.1.

Finally, ϖ^α verifies the following transport-div-curl system:

$$\partial_\kappa \varpi^\kappa \simeq \mathfrak{L}(\partial h), \quad (1.5a)$$

$$u^\kappa \partial_\kappa \mathcal{C}^\alpha \simeq \mathcal{C} + \mathcal{D} + \mathfrak{Q}(\partial S, \partial \varpi, \partial h, \partial u) + \mathfrak{L}(\partial S, \partial \varpi, \partial h, \partial u). \quad (1.5b)$$

⁵Relative to arbitrary coordinates, for scalar functions f , we have

$$\square_g f = \frac{1}{\sqrt{|\det g|}} \partial_\alpha \left(\sqrt{|\det g|} (g^{-1})^{\alpha\beta} \partial_\beta f \right).$$

1.2. Connections to the Study of Shock Waves

As we have mentioned, the relativistic Euler equations are an example of a quasilinear hyperbolic PDE system. A central feature of the study of such systems is that initially smooth solutions can form shock singularities in finite time. By a “shock,” we roughly mean that one of the solution’s partial derivatives with respect to the standard coordinates blows up in finite time while the solution itself remains bounded. In the last decade, for interesting classes of quasilinear hyperbolic PDEs in multiple spatial dimensions, there has been dramatic progress [4, 8, 23–25, 32, 34, 36, 37] on our understanding of the formation of shocks as well as our understanding of the subsequent behavior of solutions past their singularities [5, 7] (where the equations are verified in a weak sense past singularities).

The works cited above have roots in the work of John [16] on singularity formation for quasilinear wave equations in one spatial dimension as well as Alinhac’s foundational works [2, 3], which were the first to provide a constructive description of shock formation for quasilinear wave equations in more than one spatial dimension without symmetry assumptions. More precisely, Alinhac’s approach allowed him to follow the solution precisely to the time of first blowup, but not further. His work yielded sharp information about the first singularity, but only for a subset of “non-degenerate” initial data such that the solution’s first singularity is isolated in the constant-time hypersurface of first blowup; in particular, his proof did not apply to spherically symmetric initial data, where the “first” singularity typically corresponds to blowup on a sphere.

Subsequently, Christodoulou [4] proved a breakthrough result on the formation of shocks for solutions to the relativistic Euler equations in irrotational (that is, vorticity free) and isentropic regions of spacetime. More precisely, for the family of quasilinear wave equations that arise in the study of the irrotational and isentropic relativistic Euler equations,⁶ Christodoulou gave a complete description of the maximal development of an open set (without symmetry assumptions) of initial data and showed in particular that an open subset of these data lead to shock-forming⁷ solutions. Moreover, he gave a precise geometric description of the set of spacetime points where blowup occurs by showing that the singularity formation is exactly characterized by the intersection of the acoustic characteristics. In practice, he accomplished this by constructing an acoustical *eikonal function* U , whose level sets are acoustic

⁶For solutions with vanishing vorticity and constant entropy, one can introduce a potential function Φ and reformulate the relativistic Euler equations as a quasilinear wave equation in Φ .

⁷One of the key results of [4] is conditional: For small data, the only possible singularities that can form are shocks driven by the intersection of the acoustic characteristics. Here “small” means a small perturbation of the data of a non-vacuum constant fluid state, where the size of the perturbation is measured relative to a high-order Sobolev norm. Another result of [4] is that there is an open subset of small data, perhaps strictly contained in the aforementioned set of data, such that the acoustic characteristics do in fact intersect in finite time. The results of [4] leave open the possibility that there might exist some non-trivial small global solutions.

characteristics (see Sect. 1.2.1 for further discussion), and then constructing an initially positive geometric scalar function $\mu \sim 1/\partial U$ known as the *inverse foliation density* of the characteristics, such that $\mu \rightarrow 0$ corresponds to the intersection of the characteristics and the blowup of ∂U and of the fluid solution's derivatives too. Analytically, μ plays the role of a weight that appears throughout the work [4], and the main theme of the proof is to control the solution all the way up to the region where $\mu = 0$. We stress that [4] was the first work that provided sharp information about the boundary of the maximal development in more than one spatial dimension in the context of shock formation. Roughly, the maximal development is the largest possible classical solution that is uniquely determined by the initial data; see [29, 41] for further discussion.

To prove his results, Christodoulou relied on a novel formulation of the relativistic Euler equations. However, since he studied the shock formation only in irrotational and isentropic regions, he was able to introduce a potential function Φ , and his new formulation of the equations was drastically simpler than the equations of Theorem 1.2. In fact, the equations are exactly the covariant wave equation system $\square_{\tilde{g}} \partial_\alpha \Phi = 0$ (with $\alpha = 0, 1, 2, 3$), where \tilde{g} is an appropriate scalar function multiple of the acoustical metric g and $\tilde{g} = \tilde{g}(\partial \Phi)$. In particular, Christodoulou was able to avoid deriving/relying on the transport-div-curl equations from Theorem 1.2, and he therefore did not need to derive elliptic estimates for the fluid variables. In total, the potential formulation leads to dramatic simplifications compared to the equations of Theorem 1.2, especially in the context of the study of shock waves; it seems quite miraculous that the equations of Theorem 1.2 have structures that are compatible with extending Christodoulou's results away from the irrotational and isentropic case (see below for further discussion).

Although the sharp information that Christodoulou derived about the maximal development is of interest in itself, it is also an essential ingredient for setting up the shock development problem. The shock development problem, which was recently partially⁸ solved in the breakthrough work [5] (see also the precursor work [7] in spherical symmetry), is the problem of constructing the shock hypersurface of discontinuity (across which the solution jumps) as well as constructing a unique weak solution in a neighborhood of the shock hypersurface (uniqueness is enforced by selection criteria that are equivalent to the well-known Rankine–Hugoniot conditions). Christodoulou's description of the maximal development provided substantial new information that was not available under Alinhac's approach; as we mentioned above, due to some technical limitations tied to his reliance on Nash–Moser estimates, Alinhac was able to follow the solution only to the constant-time hypersurface of first blowup. In contrast, by exploiting some delicate tensorial regularity properties of eikonal functions for wave equations (see below for more details),

⁸In [5], Christodoulou solved the “restricted” shock development problem, in which he ignored the jump in entropy and vorticity across the shock hypersurface.

Christodoulou was able to avoid Nash–Moser estimates; this was a key ingredient in his following the solution to the boundary of the maximal development. Readers can consult [14] for a survey of some of these works, with a focus on the geometric and analytic techniques that lie behind the proofs.

We now aim to connect the works mentioned above to the new formulation of the relativistic Euler equations that we provide in this paper. To this end, for the equations in the works mentioned above, we first highlight the main structural features that allowed the proofs to go through. Specifically, the works [4, 8, 23–25, 32, 34, 36, 37] crucially relied on the following ingredients:

1. **(Nonlinear geometric optics).** The authors relied on geometric decompositions adapted to the characteristic hypersurfaces (also known as “characteristics” or “null hypersurfaces” in the context of wave equations) corresponding to the solution variable whose derivatives blow up. This was implemented with the help of an *eikonal function* U , whose level sets are characteristics. The eikonal function is a solution to the *eikonal equation*, which is a fully nonlinear transport equation that is coupled to the solution in the sense that the coefficients of the eikonal equation depend on the solution. Moreover, the authors showed that the intersection of the characteristics corresponds to the formation of a singularity in the derivatives of the eikonal function and in the derivatives of the solution.
2. **(Quasilinear null structure).** The authors found a formulation of the equations exhibiting remarkable null structures, where the notion of “null” is tied to the true characteristics, which are solution-dependent in view of the quasilinear nature of the equations. These structures allow one to derive sharp, fully nonlinear decompositions along characteristic hypersurfaces that reveal exactly which directional derivatives blow up and that precisely identify the terms driving the blowup (which are typically of Riccati-type, i.e., in analogy with the nonlinearities in the ODE $\dot{y} = y^2$).
3. **(Regularity properties and singular high-order energy estimates).** The authors’ formulation allows one to derive sufficient L^2 -type Sobolev regularity for all unknowns in the problem, including the eikonal function, *whose regularity properties are tied to the regularity of the solution through the dependence of the coefficients of the eikonal equation on the solution*. In particular, to close these estimates, *the authors had to show that various solution variables are one degree more differentiable compared to the degree of differentiability guaranteed by standard energy estimates*.
4. **(Structures amenable to commutations with geometric vectorfields).** The authors’ formulation is such that one can commute *all* of the equations with geometric vectorfields constructed out of the eikonal function U , generating only controllable commutator error terms. By “controllable,” we mean both from the point of view of regularity and from the point of view of the strength of their singular nature. In the works [23, 34, 36] that treat systems with multiple characteristic speeds, these are particularly delicate tasks that are quite sensitive to the structure of the equations;

one key reason behind their delicate nature is that the eikonal function (and thus the geometric vectorfields constructed from it) can be fully adapted only to “one speed,” that is, to the characteristics whose intersection correspond to the singularity.

In the remainder of this subsection, we explain why our new formulation of the relativistic Euler equations has all four of the features listed above and is therefore well-suited for studying shocks without symmetry assumptions. Readers can consult the works [22, 33, 35] for related but extended discussion in the case of the non-relativistic compressible Euler equations.

1.2.1. Nonlinear Geometric Optics and Geometric Coordinates. First, to implement nonlinear geometric optics, one can construct an eikonal function. In the context of the relativistic Euler equations, one would construct an eikonal function U adapted to the acoustic characteristics, that is, a solution to the eikonal equation

$$(g^{-1})^{\alpha\beta}\partial_\alpha U\partial_\beta U = 0, \quad (1.6)$$

supplemented by appropriate initial conditions, where $g = g(h, s, u)$ is the acoustical metric (see Definition 2.6). Note that U is adapted to the “wave part” of the system and not the transport part. In the context of the relativistic Euler equations, this is reasonable in the sense that the transport part corresponds to the evolution of vorticity and entropy, and there are no known blowup results for these quantities, even in one spatial dimension.⁹ Put differently, U is adapted to the “portion” of the relativistic Euler flow that is expected to develop singularities. More generally, eikonal functions are a natural tool for the study of wave-like systems, regardless of whether or not one is studying shocks. We also stress that introducing an eikonal function is essentially the same as relying on the method of characteristics. However, in more than one spatial dimension, the method of characteristics must be supplemented with an exceptionally technical ingredient that we further describe below: energy estimates that hold all the way up to the shock.

The first instance of an eikonal function being used to study the global properties of solutions to a quasilinear hyperbolic PDE occurred not in the context of singularity formation, but rather in a celebrated global existence result: the Christodoulou–Klainerman [6] proof of the stability of the Minkowski spacetime as a solution to the Einstein vacuum equations. Alinhac’s aforementioned works [2, 3] were the first instances in which an eikonal function was used to study a non-trivial set of solutions (without symmetry assumptions) to a quasilinear wave equation all the way up to the first singularity. Eikonal functions also played a fundamental role in all of the other shock formation results mentioned above. They have also played a role in other contexts, such as low-regularity local well-posedness for quasilinear wave equations [20, 21, 30, 39]. In all of these works, the eikonal equation is a fully nonlinear hyperbolic PDE that is coupled to the PDE system of interest (here the relativistic Euler equations) through its coefficients [here through the acoustical metric, since $g = g(h, s, u)$].

⁹In one spatial dimension, the vorticity must vanish, but the entropy can be dynamic.

As we mentioned above, in the case of the relativistic Euler equations, the level sets of U are characteristics for the “wave part” of the system. Following Alinhac [2,3] and Christodoulou [4], in order to study the formation of shocks in relativistic Euler solutions, one completes U to a *geometric coordinate system*

$$(t, U, \vartheta^1, \vartheta^2) \quad (1.7)$$

on spacetime, where $t = x^0$ is the Minkowski time coordinate and the ϑ^A are solutions to the transport equation $(g^{-1})^{\alpha\beta} \partial_\alpha U \partial_\beta \vartheta^A = 0$ supplemented by appropriate initial conditions on the initial constant-time hypersurface Σ_0 . Note that $(t, \vartheta^1, \vartheta^2)$ can be viewed as a coordinate system along each characteristic hypersurface $\{U = \text{const}\}$.

1.2.2. Nonlinear Null Structure. We now aim to explain the role that the nonlinear null structure of the equations played in the works [4,8,23–25,32,34,36,37] and to explain why the equations of Theorem 1.2 enjoy the same good structures. In total, one could say that the equations of Theorem 1.2 have been geometrically decomposed into terms that are capable of generating shocks and “harmless” terms, whose nonlinear structure is such that they do not interfere with the shock formation mechanisms. To flesh out these notions, we first provide some background material. In the works cited above, the main idea behind proving shock formation is to study the solution relative to the geometric coordinates (1.7) and to show that in fact, the solution remains rather smooth in these coordinates, all the way up to the shock. This approach allows one to transform the problem of shock formation into a more traditional one in which one tries to derive long-time estimates for the solution relative to the geometric coordinates. One then recovers the blowup of the solution’s derivatives with respect to the *original* coordinates by showing that the geometric coordinates degenerate in a precise fashion relative to the standard rectangular coordinates as the shock forms; the degeneration is exactly tied to the vanishing of the inverse foliation density μ that we mentioned earlier. Although the above description might seem compellingly simple, as we explain in Sect. 1.2.3, in implementing this approach, one encounters severe analytical difficulties.

We now highlight another key aspect of the proofs in the works cited above: showing that Euclidean-unit-length derivatives of the solution in directions *tangent* to the characteristics remain bounded all the way up to the shock. It turns out that in terms of the geometric coordinates (1.7), this is equivalent to showing that the $\frac{\partial}{\partial t}$ and $\frac{\partial}{\partial \vartheta^A}$ derivatives of the solution remain bounded all the way up to the shock. Put differently, the following holds:

The singularity occurs only for derivatives of the solution with respect to vectorfields that are transversal to the characteristics and non-degenerate¹⁰ with respect to the rectangular coordinates.

¹⁰In all known shock formation results, at the location of shock singularities, the geometric partial derivative vectorfield $\frac{\partial}{\partial U}$ has vanishing Euclidean length (i.e., $\delta_{ab} \left(\frac{\partial}{\partial U} \right)^a \left(\frac{\partial}{\partial U} \right)^b = 0$, where $\left\{ \left(\frac{\partial}{\partial U} \right)^a \right\}_{a=1,2,3}$ denotes the rectangular spatial components of $\frac{\partial}{\partial U}$ and δ_{ab} is the

In the works cited above, to prove all of these facts, the authors had to control various inhomogeneous error terms by showing that they enjoy a good nonlinear null structure *relative to the wave characteristics*. A key conclusion of the present article is that the derivative-quadratic inhomogeneous terms in the equations of Theorem 1.2 enjoy the same good structure (which we further describe just below). In fact, *all terms* on the RHSs of *all equations* of Theorem 1.2 are harmless in that they do not drive the Riccati-type blowup that lies behind shock formation. Consequently, the equations of Theorem 1.2 pinpoint the dangerous nonlinear terms in the relativistic Euler equations:

The terms capable of driving shock formation are of Riccati-type and are hidden in the covariant wave operator terms on RHSs (1.2a)–(1.2b). These terms become visible only when the covariant wave operator terms are expanded relative to the standard coordinates.

In view of the above remarks, one might wonder why it is important to “hide” the dangerous terms in the covariant wave operator. The answer is that there is an advanced framework for constructing geometric vectorfields adapted to wave equations, and *the framework is tailored to covariant wave operators*.¹¹ As we explain later in this subsection, this geometric framework seems to be essential in more than one spatial dimension,¹² when one is forced to commute the wave equations with suitable vectorfields and to derive energy estimates.

We now further describe the good structure found in the terms on the RHSs of the equations of Theorem 1.2. The good nonlinear “null structure” is found precisely in the (quadratic) null-form terms \mathfrak{Q} appearing on the RHSs of the equations of Theorem 1.2. More precisely, these \mathfrak{Q} are *null forms relative to the acoustical metric g* , which means that they are linear combinations (with coefficients that are allowed to depend on the solution variables—but not their derivatives) of the standard null forms relative to g (see Definition 1.1). The key property of null forms relative to g is that given *any* hypersurface \mathcal{H} that is characteristic relative to g [e.g., any level set of any eikonal function U that solves Eq. (1.6)], we have the following well-known schematic decomposition:

$$\mathfrak{Q}(\partial\phi, \partial\psi) = \mathcal{T}\phi \cdot \partial\psi + \mathcal{T}\psi \cdot \partial\phi, \quad (1.8)$$

where \mathcal{T} denotes a differentiation in a direction *tangent* to \mathcal{H} and ∂ denotes a generic directional derivative; see, for example, [22] for a standard proof of (1.8). Equation (1.8) implies that even though \mathfrak{Q} is quadratic, it *never involves two differentiations in directions transversal to any characteristic*. Since,

Footnote 10 continued

Kronecker delta). That is, at the shock singularities, $\frac{\partial}{\partial U}$ degenerates with respect to the rectangular coordinates. Due to this degeneracy, the solution’s $\frac{\partial}{\partial U}$ derivatives can remain bounded all the way up to the shock, even though $\frac{\partial}{\partial U}$ is transversal to the characteristics.
¹¹Roughly, these covariant wave operators are equivalent to divergence-form wave operators. In this way, one could say that a better theory is available for divergence-form wave operators than for non-divergence-form wave operators. This reminds one of the situation in elliptic PDE theory, where better results are known for elliptic PDEs in divergence form compared to ones in non-divergence form.

¹²In one spatial dimension, one can rely exclusively on the method of characteristics and thus avoid energy estimates.

in all known proofs, it is precisely the transversal derivatives that blow up when a shock forms (since the Riccati-type terms that drive the blowup are precisely quadratic in the transversal derivatives), we see that g -null forms are linear in the tensorial component of the solution that blows up. This can be viewed as *the absence of the worst possible combinations of terms in \mathfrak{Q}* . In terms of the geometric coordinates (1.7), null forms do not contain any “dangerous” terms proportional to $\frac{\partial}{\partial U}\phi \cdot \frac{\partial}{\partial U}\psi$. We also note that, obviously, the terms \mathfrak{L} from Theorem 1.2 cannot contain any dangerous quadratic terms since they are linear in the solution’s derivatives. In contrast, upon expanding the covariant wave operator terms on LHSs (1.2a)–(1.2b) relative to the standard coordinates, one typically encounters terms that are quadratic in derivatives of h and u that are transversal to the characteristics; as we highlighted above, it is precisely such “Riccati-type” terms that can drive the formation of a shock. We stress that near a shock, such transversal-derivative-quadratic terms are much larger than the null form terms. We also stress that for the relativistic Euler equations, one encounters such transversal-derivative-quadratic terms on LHSs (1.2a)–(1.2b) under *any* equation of state aside from a single exceptional one. In the irrotational and isentropic case (in which case the relativistic Euler equations reduce to a quasilinear wave equation satisfied by a potential function), this exceptional equation of state was identified in [4]; it corresponds to the quasilinear wave equation satisfied by a timelike minimal surface graph in an ambient Minkowski spacetime, which can be expressed as

$$\text{follows: } \partial_\alpha \left\{ \frac{(\eta^{-1})^{\alpha\beta} \partial_\beta \Phi}{\sqrt{1 + (\eta^{-1})^{\kappa\lambda} (\partial_\kappa \Phi) (\partial_\lambda \Phi)}} \right\} = 0.$$

In view of the previous paragraph, we would like to highlight the following point:

Proofs of shock formation are unstable under typical perturbations of the equations by nonlinear terms that are of quadratic or higher order in derivatives. However, proofs of shock formation for wave equations typically *are* stable under perturbations of the equations by null forms that are adapted to the metric of the shock-forming wave. By “stable,” we mean in the following sense: as the shock forms, null form terms become “asymptotically negligible” compared to the shock-driving terms (for the reasons described above).

The reason that the precise structure of the nonlinearities is so important for the proofs is that the known framework is designed precisely to handle specific kinds of singularity-driving derivative-quadratic terms: the kind that are hidden in the covariant wave operator terms on LHSs (1.2a)–(1.2b). In the context of the relativistic Euler equations, this means that if *any* of the equations of Theorem 1.2 had contained, on the right-hand side, an inhomogeneous non- g -null-form quadratic term of type $(\partial h)^2$, $\partial u \cdot \partial h$, $(\partial u)^2$, etc., or a term of type $(\partial h)^3$, $(\partial h)^4$, etc., then the *only known framework for proving shock formation would not work*. The difficulty is that adding such terms to the equation could in principle radically alter the expected blowup rate or even altogether prevent

the formation of a singularity; either way, this would invalidate¹³ the known approach for proving shock formation. One might draw an analogy with the Riccati ODE $\dot{y} = y^2$, which we suggest as a caricature model for the formation of shocks (in the case of the relativistic Euler equations, y should be identified with ∂h and/or ∂u). Note that for all data $y(0) = y_0$ with $y_0 > 0$, the solution to the Riccati ODE blows up in finite time. Now if one perturbs the Riccati ODE to obtain the perturbed equation $\dot{y} = y^2 \pm \epsilon y^3$, with ϵ a small positive number, then depending on the sign of \pm , the perturbed solutions with $y_0 > 0$ will either exist for all time or will blow up at a quite different rate compared to the blowup rate for the unperturbed equation.

1.2.3. Regularity Properties and Singular High-Order Energy Estimates. In the rigorous mathematical study of quasilinear hyperbolic PDEs in more than one spatial dimension, one is forced to derive energy estimates for the solution's higher derivatives by commuting the equations with appropriate differential operators. Indeed, all known approaches to studying even the basic local well-posedness theory for such equations rely on deriving estimates in L^2 -based Sobolev spaces. In the works [4, 8, 23–25, 32, 34, 36, 37] on shock formation in multiple spatial dimensions, the authors controlled the solutions' higher geometric derivatives by differentiating the equations with geometric “commutator vectorfields” Z that are adapted to the characteristics, more precisely to the characteristics corresponding to the variables that form a shock singularity. As we mentioned earlier, the Z are designed to avoid generating uncontrollable commutator error terms. It turns out that all Z that have been successfully used to study shock formation have the schematic structure $Z^\alpha \sim \partial U$, where Z^α denotes a rectangular component of Z and U is the eikonal function.

Although the geometric vectorfields Z exhibit good commutation properties with the differential operators corresponding to the characteristics to which they are adapted, the regularity theory of the vectorfields themselves is very delicate and is intimately tied to that of the solution. We now further explain this fact in the context of wave equations whose principal operator is $(g^{-1})^{\alpha\beta} \partial_\alpha \partial_\beta$. The corresponding eikonal equation is the nonlinear transport equation $(g^{-1})^{\alpha\beta} \partial_\alpha U \partial_\beta U = 0$. The key point is that the standard regularity theory of transport equations yields only that U is as regular as its coefficients, that is, as regular as $g_{\alpha\beta}$. In the context of the relativistic Euler equations (where the formation of a shock corresponds to the intersection of the wave characteristics and $g = g(h, s, u)$), this suggests that one might expect U to be only as regular as h , s , and u . Since, as we mentioned in the previous paragraph, we have $Z^\alpha \sim \partial U$, this leads to the following severe difficulty: In commuting equation the wave equation (1.2a) with Z , one obtains the wave equation

¹³As is explained in [22], in the known framework for proving shock formation, one crucially relies on the fact that the derivatives of the solution blow up at a linear rate, that is like $\frac{C}{T_{\text{(Lifespan)}} - t}$, where C is a constant and $T_{\text{(Lifespan)}} > 0$ is the (future) classical lifespan of the solution; if one perturbs the equation by adding terms that are expected to alter this blowup rate, then one should expect that the known approach for proving shock formation will not work (at least in its current form).

$\square_g(Zh) = \square_g Z^\alpha \cdot \partial_\alpha h + \dots \sim \partial^3 U \cdot \partial h + \dots$ (one would obtain similar wave equations for Zs and Zu^α upon commuting equations (1.2b) and (1.2c) with Z). The difficulty is that the above discussion suggests that the factor $\partial^3 U$ can be controlled only in terms of *three* derivatives of h , s , and u , while standard energy estimates for the wave equations $\square_g(Zh) = \dots$, $\square_g(Zs) = \dots$, and $\square_g(Zu^\alpha) = \dots$ yield control of only *two* derivatives of h , s , and u . This suggests that there is a loss of regularity and in fact, this is the reason that Alinhac used Nash–Moser estimates in his works [2, 3]. However, for wave equations, one can in fact overcome this loss of regularity by exploiting some delicate tensorial properties of the eikonal equation $(g^{-1})^{\alpha\beta} \partial_\alpha U \partial_\beta U = 0$ and of the wave equation itself relative to geometric coordinates, which together can be used to show that in directions *tangent to the characteristics*, some geometric tensors constructed out of the derivatives of U are *one degree more differentiable than one might naively expect*. In particular, the factor $\partial^3 U$ in the aforementioned product $\partial^3 U \cdot \partial h$ has special structure and enjoys this gain in regularity. These crucial structures were first observed by Christodoulou–Klainerman in their proof [6] of the stability of Minkowski spacetime as a solution to Einstein’s equations, and later by Klainerman–Rodnianski in their proof of improved regularity local well-posedness [20] for a general class of scalar quasilinear wave equations. In total, using this gain in regularity along the characteristics and carefully accounting for the precise tensorial structure of the product $\partial^3 U \cdot \partial h$ highlighted above, one can avoid the loss of derivatives tied to the product $\partial^3 U \cdot \partial h$.

Despite the fact that the procedure described above allows one to avoid losing derivatives, at least in the context of wave equations,¹⁴ one pays a steep price: It turns out that upon implementing this procedure, one introduces a dangerous factor into the wave equation energy identities, one that in fact blows up as the shock forms. More precisely, the singular factor is $1/\mu$, where μ is the inverse foliation density mentioned earlier, with $\mu \rightarrow 0$ signifying the formation of a shock. This leads to singular top-order a priori energy estimates for the wave equation solutions relative to the geometric coordinates. At first glance, these singular geometric energy estimates might seem to obstruct the philosophy of obtaining regular estimates relative to the geometric coordinates. However, below the top derivative level, one can allow the loss of a derivative, and it turns out that this allows one to derive improved (i.e., less singular) energy estimates below the top derivative level. In fact, by an induction-from-the-top-down argument, one can show that the mid-derivative-level and below geometric energies remain bounded up to the shock. This allows one to show that indeed, the solution remains rather smooth relative to the geometric coordinates, which in practice is a crucial ingredient that is needed to close the proof. It also turns out that many steps are needed to descend to the level of a non-singular energy, which in practice means that one must assume that the

¹⁴Actually, it is not known whether or not the derivative-loss-avoiding procedure can be implemented for general systems of wave equations featuring more than one distinct wave operator. From this perspective, we find it fortunate that the equations of Theorem 1.2 feature only one wave operator.

data have a lot of Sobolev regularity to close the proof; see [14] for an in-depth overview of these issues in the context of quasilinear wave equations.

The structures described above, which allow one to avoid the loss of derivatives in eikonal functions for quasilinear wave equations, are rather delicate. Thus, it is not a priori clear that one can also avoid the loss of derivatives in eikonal functions for the relativistic Euler equations. A key advantage of our new formulation of the relativistic Euler equations is that it can be used to prove that *one can still avoid the loss of derivatives, even though there is deep coupling between the wave and transport equations in the new formulation*. That is, one can show that the acoustic eikonal function U [see (1.6), where $g = g(h, s, u)$ is the acoustical metric from Definition 2.6] for the relativistic Euler equations has enough regularity to be used in the study of shock formation; see three paragraphs below for further discussion. However, this requires one to first prove that the fluid variables have a consistent amount of regularity among themselves. At first thought, the desired consistency of regularity might seem to follow from standard local well-posedness. However, all standard local well-posedness results for the relativistic Euler equations are based on first-order formulations, which are not known to be sufficient for avoiding a loss of derivatives in the eikonal function U ; the above outline for how to avoid derivative loss in U implicitly relied on the assumption that h , s , and u^α solve wave equations whose source terms have an allowable amount of regularity, which, as we will explain, for the relativistic Euler equations is a true—but deep—fact. Moreover, the first-order formulations do not seem to be sufficient for studying solutions all the way up to a shock; as we have mentioned, the known framework for studying shocks crucially relies on the special null structures exhibited by the equations of Theorem 1.2.

In view of the regularity concerns raised in the previous paragraph, one must carefully check that (under suitable assumptions on the initial data), all terms in the equations of Theorem 1.2 have a *consistent amount of regularity*. We stress that this is not obvious, as we now illustrate by counting derivatives. For example, to control ∂u^α in L^2 using standard energy estimates for the wave equation (1.2b), one must control, also in L^2 , the source term \mathcal{C}^α on RHS (1.2b). Note that from the point of view of regularity, we have the schematic relationship [see (2.16a) for the definition of \mathcal{C}^α] $\mathcal{C}^\alpha \sim \text{vort}^\alpha(\varpi) \sim \partial \varpi$. Moreover, since ϖ solves the transport equation (1.3c), whose source term depends on ∂u and ∂h , this suggests that $\partial \varpi$ should be no more regular¹⁵ than $(\partial^2 u, \partial^2 h)$ and thus \mathcal{C}^α should be no more regular than $(\partial^2 u, \partial^2 h)$. In total, this discussion suggests that the wave equation for u has the following schematic structure from the point of view of regularity: $\square_g u^\alpha = \partial^2 u + \dots$. That is, this discussion *suggests* that in order to control ∂u in L^2 using standard energy estimates for wave equations, we must control $\partial^2 u$ in L^2 . This approach therefore *seems* to lead to a loss in derivatives, which is a serious obstacle to using the equations of Theorem 1.2 to prove any rigorous

¹⁵In the absence of special structures, solutions to transport equations are not more regular than their source terms.

result. Similar difficulties arise in the study of h and s , due to the source term \mathcal{D} in the wave equations (1.2a) and (1.2c).

A crucial feature of the equations of Theorem 1.2 is that *one can in fact overcome the loss of derivative difficulty for the fluid variables described in the previous paragraph*. To this end, one must rely on the transport-div-curl equations for ϖ and S ; see Sect. 9.5 and the proofs of Proposition 9.22 and Theorem 9.12 for the details on how one can use these equations and elliptic estimates to avoid the loss of derivatives. Equally important for applications to shock waves is the fact that the elliptic div-curl estimates, which occur across space, are compatible with the proof of the formation of a spatially localized shock singularity and with the singular high-order geometric energy estimates described earlier in this subsubsection. These are delicate issues, especially since the elliptic estimates involve derivatives in directions transversal to the characteristics, i.e., in the singular directions; see [22] for an overview of how to derive the relevant elliptic estimates in the context of shock-forming solutions to the non-relativistic compressible Euler equations.

We now return to the issue of the regularity of the acoustic eikonal function U for the relativistic Euler equations [see (1.6), where $g = g(h, s, u)$ is the acoustical metric from Definition 2.6]. As we explained above, in order to avoid a loss of regularity in U , one needs to show that its regularity theory is compatible with the regularity of the fluid variables. It turns out that this requires proving, in particular, that $\square_g h$, $\square_g s$, and $\square_g u^\alpha$ have the same regularity as ∂h , ∂s , and ∂u^α . The connection between $\square_g h$, $\square_g s$, and $\square_g u^\alpha$ and the regularity theory of U is through the null mean curvature of the level sets of U , a critically important geometric quantity whose evolution equation¹⁶ depends on a certain component of the Ricci curvature tensor of the Lorentzian metric $g(h, s, u)$, whose rectangular components can be shown to depend on $\square_g h$, $\square_g s$, and $\square_g u^\alpha$. We will not further discuss this crucial technical issue here; we instead refer readers to [14, Section 3.4] for further discussion of the regularity theory of eikonal functions in the context of shock formation for quasilinear wave equations. In view of the wave equations (1.2a)–(1.2c), we see that obtaining the desired regularity for $\square_g h$, $\square_g s$, and $\square_g u^\alpha$ requires, in particular, establishing that the source terms \mathcal{C}^α and \mathcal{D} on RHSs (1.2a)–(1.2c) have the same regularity as ∂h , ∂s , and ∂u^α . This is again tantamount to showing that the vorticity and entropy are one degree more differentiable compared to the regularity guaranteed by deriving standard energy estimates for first-order formulations of the equations; to obtain the desired extra regularity for \mathcal{C}^α and \mathcal{D} , one can again rely on the transport-div-curl equations mentioned in the previous paragraph. We prove a rigorous version of this gain in regularity in Theorem 9.12, in which we use the new formulation of the relativistic Euler equations to prove a local well-posedness result that, in particular, yields the desired extra differentiability (assuming that it is present in the initial data).

¹⁶The evolution equation is in fact the famous *Raychaudhuri equation*, which plays an important role in general relativity.

Although one might view the results of Theorem 9.12 as expected consequences of our new formulation of the relativistic Euler equations, we highlight that its proof relies on a few ingredients that are not entirely straightforward:

- (i) *Time-continuity* for the L^2 norms of the vorticity and entropy at top-order, i.e., including the extra differentiability of these variables, is non-standard in view of the necessity of invoking elliptic–hyperbolic estimates.
- (ii) The transport-div-curl systems featured in the new formulation of the equations involve *spacetime* divergence and curl operators, but we need to extract L^2 regularity along the constant-time hypersurfaces. This requires connecting the spacetime divergence and curl to spatial elliptic estimates, which in turn requires some geometric and technical insights.
- (iii) For the wave equation energy estimates, one cannot use the multiplier¹⁷ ∂_t when the three-velocity is large, since the corresponding energy will not necessarily be coercive¹⁸ in this case. Consequently, one has to use the four-velocity as a multiplier.¹⁹

1.2.4. Structures Amenable to Commutations with Geometric Vectorfields.

A key point is that the geometric vectorfields Z described in Sect. 1.2.3 are adapted only to the principal part of the shock-forming solution variables, e.g., the operator \square_g in the case that a wave equation solution is the shock-forming variable. However, to close the proof of shock formation for a system in which wave equations of the type $\square_g \cdot = \dots$ are *coupled* to other equations, one must commute that Z through *all* of the equations in the system. One then has to handle the commutator terms generated by commuting the Z through the other equations. It turns out, perhaps not surprisingly, that commuting Z through a generic second-order differential operator ∂^2 leads to uncontrollable error terms, from the point of view of regularity and from the point of view of the singular nature of the commutator error terms; see the work [22] on the non-relativistic compressible barotropic Euler equations for further discussion on this point. However, as was first shown in [22], it is possible to commute the Z through an arbitrary first-order differential operator ∂ by first weighting it by μ (where μ is the inverse foliation density mentioned above); it can be shown

¹⁷See Sect. 9.6.1 for additional details regarding the multiplier method in the context of wave equations.

¹⁸Equations (2.11), (2.20), and (2.13a) collectively imply that when $\sum_{a=1}^3 |u^a|$ is large, $g(\partial_t, \partial_t) = g_{00} = -1 + (c^{-2} - 1)u_a u^a$ can be positive, i.e., ∂_t can be spacelike with respect to the acoustical metric g ; it is well known that this can lead to indefinite energies if the standard partial time derivative vectorfield ∂_t is used as a multiplier in the wave equation energy estimates.

¹⁹The use of u as a multiplier is likely familiar to researchers who have previously studied the relativistic Euler equations, but it might be unknown to the broader PDE community. We also remark that in searching the literature, we were unable to find results that, given our new formulation of the relativistic Euler equations, could be directly applied to establish points (i) and (ii) above. Moreover, we were not able to locate a local well-posedness result for elliptic–hyperbolic systems that can be directly applied to our new formulation of the equations. In particular, we could not locate a result that would directly imply continuous dependence of solutions on the initial data up to top order, i.e., a result that applies in the case when the vorticity and entropy enjoy the aforementioned extra regularity.

that this leads to commutator error terms that are controllable under the scope of the approach. **It is for this reason that we have formulated Theorem 1.2 in such a way that all of the equations are of the type $\square_g \cdot = \dots$ or are first-order**; i.e., the equations of Theorem 1.2 are such that the approach described in [22] can be applied. Put differently, the geometric vectorfields Z that are of essential importance for commuting the wave equations of Theorem 1.2 can also be commuted through all of the remaining equations, generating only controllable error terms.

2. A First-Order Formulation of the Relativistic Euler Equations, Geometric Tensorfields, and the Modified Fluid Variables

In this section, we introduce some notation, define the fluid variables that play a role in the subsequent discussion, introduce some geometric tensorfields associated to the flow, and provide the standard first-order formulation of the relativistic Euler equations that will serve as a starting point for our main results. Most of the discussion here is standard and therefore, we are somewhat terse; we refer readers to [4, Chapter 1] for a detailed introduction to the relativistic Euler equations. Section 2.2.5, however, is not standard. In that subsubsection, we define *modified fluid variables*, which are special combinations of the derivatives of the vorticity and entropy. The structures revealed by Theorem 3.1 imply (see the proof of Theorem 9.12 for additional details) that these special combinations enjoy a gain of one derivative compared to the regularity afforded by standard estimates. As we mentioned in the introduction, this gain is crucial for applications to shock waves.

2.1. Notation and Conventions

We somewhat follow the setup of [4], but there are some differences, including sign differences and notational differences.

Greek “spacetime” indices α, β, \dots take on the values 0, 1, 2, 3, while Latin “spatial” indices a, b, \dots take on the values 1, 2, 3. Repeated indices are summed over (from 0 to 3 if they are Greek, and from 1 to 3 if they are Latin). Greek and Latin indices are lowered and raised with the Minkowski metric η and its inverse η^{-1} , and **not with the acoustical metric g of Definition 2.6**. Moreover, $\epsilon_{\alpha\beta\gamma\delta}$ denotes the fully antisymmetric symbol normalized by $\epsilon_{0123} = 1$. Note that $\epsilon^{0123} = -1$.

If X^α is a vectorfield and $\xi^{\alpha_1 \dots \alpha_l}_{\beta_1 \dots \beta_m}$ is a type $(\frac{l}{m})$ tensorfield, then

$$\begin{aligned} (\mathcal{L}_X \xi)^{\alpha_1 \dots \alpha_l}_{\beta_1 \dots \beta_m} &= X^\kappa \partial_\kappa \xi^{\alpha_1 \dots \alpha_l}_{\beta_1 \dots \beta_m} - \sum_{a=1}^l (\partial_\kappa X^{\alpha_a}) \xi^{\alpha_1 \dots \alpha_{a-1} \kappa \alpha_{a+1} \dots \alpha_l}_{\beta_1 \dots \beta_m} \\ &\quad + \sum_{b=1}^m (\partial_{\beta_b} X^\kappa) \xi^{\alpha_1 \dots \alpha_l}_{\beta_1 \dots \beta_{b-1} \kappa \beta_{b+1} \dots \beta_m} \end{aligned} \tag{2.1}$$

denotes the Lie derivative of ξ with respect to X .

We derive all of our results relative to a Minkowski-rectangular coordinate system $\{x^\alpha\}_{\alpha=0,1,2,3}$, that is, a coordinate system on \mathbb{R}^{1+3} in which the Minkowski metric η takes the form $\eta_{\alpha\beta} := \text{diag}(-1, 1, 1, 1)$. $\{\partial_\alpha\}_{\alpha=0,1,2,3}$ denotes the corresponding rectangular coordinate partial derivative vectorfields. We sometimes use the alternate notation $x^0 := t$ and $\partial_t := \partial_0$.

Throughout, d denotes the exterior derivative operator. In particular, if f is a scalar function, then $(df)_\alpha := \partial_\alpha f$, and if V is a one-form, then $(dV)_{\alpha\beta} := \partial_\alpha V_\beta - \partial_\beta V_\alpha$. We use the notation V_\flat to denote the one-form that is η -dual to the vectorfield V , i.e., $(V_\flat)_\alpha := \eta_{\alpha\kappa} V^\kappa$.

2.2. Definitions of the Fluid Variables and Related Geometric Quantities

In this subsection, we define the fluid variables and geometric quantities that play a role in the subsequent discussion.

2.2.1. The Basic Fluid Variables. The fluid four velocity u^α is future-directed and normalized by $u_\alpha u^\alpha = -1$. p denotes the pressure, ρ denotes the proper energy density, n denotes the proper number density, s denotes the entropy per particle, θ denotes the temperature, and

$$H = (\rho + p)/n \quad (2.2)$$

is the enthalpy per particle. Thermodynamics supplies the following laws:

$$H = \frac{\partial \rho}{\partial n} \Big|_s, \quad \theta = \frac{1}{n} \frac{\partial \rho}{\partial s} \Big|_n, \quad dH = \frac{dp}{n} + \theta ds, \quad (2.3)$$

where $\frac{\partial}{\partial n} \Big|_s$ denotes partial differentiation with respect to n at fixed s and $\frac{\partial}{\partial s} \Big|_n$ denotes partial differentiation with respect to s at fixed n . Below we employ similar partial differentiation notation, and in Definition 2.7, we introduce alternate partial differentiation notation, which we use throughout the remainder of the article.

2.2.2. The u -orthogonal Vorticity of a One-Form and Auxiliary Fluid Variables. In this subsubsection, we define some auxiliary fluid variables that will play a role throughout the paper. By “auxiliary,” we mean that they are determined by the variables introduced in Sect. 2.2.1.

We start by defining the u -orthogonal vorticity of a one form.

Definition 2.1 (*The u -orthogonal vorticity of a one form*). Given a one-form V , we define the corresponding u -orthogonal vorticity vectorfield as follows:

$$\text{vort}^\alpha(V) := -\epsilon^{\alpha\beta\gamma\delta} u_\beta \partial_\gamma V_\delta. \quad (2.4)$$

Definition 2.2 (*Vorticity vectorfield*). We define the vorticity vectorfield ϖ^α as follows:

$$\varpi^\alpha := \text{vort}^\alpha(Hu) = -\epsilon^{\alpha\beta\gamma\delta} u_\beta \partial_\gamma (Hu_\delta). \quad (2.5)$$

We find it convenient to work with the natural log of the enthalpy.

Definition 2.3 (*Logarithmic enthalpy*). Let $\bar{H} > 0$ be a fixed constant value of the enthalpy. We define the (dimensionless) logarithmic enthalpy h as follows:

$$h := \ln(H/\bar{H}). \quad (2.6)$$

Definition 2.4 (*The quantity q*). We define the quantity q as follows:

$$q := \frac{\theta}{H}. \quad (2.7)$$

Definition 2.5 (*Entropy gradient one-form*). We define the entropy gradient one-form S_α as follows:

$$S_\alpha := \partial_\alpha s. \quad (2.8)$$

2.2.3. Equation of State and Speed of Sound. To obtain a closed system of equations, we assume an *equation of state* of the form $p = p(\rho, s)$. The *speed of sound* is defined by

$$c := \sqrt{\left| \frac{\partial p}{\partial \rho} \right|_s}. \quad (2.9)$$

For reasons that will become clear in Sect. 2.3, in the rest of the article, we view the speed of sound to be a function of h and s :

$$c = c(h, s). \quad (2.10)$$

In this article, we will confine our study to equations of state and solutions that verify

$$0 < c \leq 1. \quad (2.11)$$

The upper bound in (2.11) signifies that the speed of sound is no bigger than the speed of light. In this article, we exploit both inequalities in (2.11). We use the bound $c \leq 1$ to ensure that we can always solve for time derivatives of the solution in terms of spatial derivatives; see the discussion surrounding Eq. (2.28). The bound $c > 0$ is important because some of the equations featured in Theorem 3.1 contain factors of c^{-1} .

2.2.4. Projection Onto the Minkowski-Orthogonal Complement of the Four-Velocity and the Acoustical Metric. We start by introducing the tensorfield $\Pi^{\alpha\beta}$, defined by

$$\Pi^{\alpha\beta} := (\eta^{-1})^{\alpha\beta} + u^\alpha u^\beta. \quad (2.12)$$

It is straightforward to see Π is the projection onto the η -orthogonal complement of u . In particular, $\Pi^{\alpha\kappa} u_\kappa = 0$.

We now introduce the acoustical metric g . It is a Lorentzian²⁰ metric that drives the propagation of sound waves.

Definition 2.6 (*Acoustical metric and its inverse*). We define the acoustical metric $g_{\alpha\beta}$ and its inverse²¹ $(g^{-1})^{\alpha\beta}$ as follows:

$$g_{\alpha\beta} := c^{-2} \eta_{\alpha\beta} + (c^{-2} - 1) u_\alpha u_\beta, \quad (2.13a)$$

$$(g^{-1})^{\alpha\beta} := c^2 \Pi^{\alpha\beta} - u^\alpha u^\beta = c^2 (\eta^{-1})^{\alpha\beta} + (c^2 - 1) u^\alpha u^\beta. \quad (2.13b)$$

²⁰That is, the signature of the 4×4 matrix $g_{\alpha\beta}$, viewed as a quadratic form, is $(-, +, +, +)$.

²¹It is straightforward to check that $(g^{-1})^{\alpha\kappa} g_{\kappa\beta} = \delta_\beta^\alpha$, where δ_β^α is the Kronecker delta. That is, g^{-1} is indeed the inverse of g .

It is straightforward to compute that relative to the rectangular coordinates, we have

$$\det g = -c^{-6}, \quad (2.14a)$$

$$|\det g|^{1/2} (g^{-1})^{\alpha\beta} = c^{-1} (\eta^{-1})^{\alpha\beta} + (c^{-1} - c^{-3}) u^\alpha u^\beta. \quad (2.14b)$$

The notation featured in the next definition will allow for a simplified presentation of various equations.

Definition 2.7 (*Partial derivatives with respect to h and s*). If Q is a quantity that can be expressed as a function of (h, s) , then

$$Q_{;h} = Q_{;h}(h, s) := \frac{\partial Q}{\partial h} |_s, \quad (2.15a)$$

$$Q_{;s} = Q_{;s}(h, s) := \frac{\partial Q}{\partial s} |_h, \quad (2.15b)$$

where $\frac{\partial}{\partial h} |_s$ denotes partial differentiation with respect to h at fixed s and $\frac{\partial}{\partial s} |_h$ denotes partial differentiation with respect to s at fixed h .

2.2.5. Modified Fluid Variables. In our analysis, we will have to control the vorticity of the vorticity, that is, $\text{vort}^\alpha(\varpi)$. The following modified version of $\text{vort}^\alpha(\varpi)$, denoted by \mathcal{C}^α obeys a transport equation [see (3.11b)] with a better structure (from the point of view of the regularity of the RHS and also the null structure of the RHS) than the one satisfied by $\text{vort}^\alpha(\varpi)$. Similar remarks apply to the modified version of the divergence of entropy gradient, which we denote by \mathcal{D} [see Eq. (3.9a) for the transport equation verified by \mathcal{D}].

Definition 2.8 (*Modified fluid variables*).

$$\begin{aligned} \mathcal{C}^\alpha &:= \text{vort}^\alpha(\varpi) + c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \\ &+ (\theta - \theta_{;h}) S^\alpha (\partial_\kappa u^\kappa) + (\theta - \theta_{;h}) u^\alpha (S^\kappa \partial_\kappa h) \\ &+ (\theta_{;h} - \theta) S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\kappa), \end{aligned} \quad (2.16a)$$

$$\mathcal{D} := \frac{1}{n} (\partial_\kappa S^\kappa) + \frac{1}{n} (S^\kappa \partial_\kappa h) - \frac{1}{n} c^{-2} (S^\kappa \partial_\kappa h). \quad (2.16b)$$

2.3. A Standard First-Order Formulation of the Relativistic Euler Equations

In formulating the relativistic Euler equations as a first-order hyperbolic system, we will consider h , s , and $\{u^\alpha\}_{\alpha=0,1,2,3}$ to be the fundamental unknowns.²² In terms of these variables and the quantities defined in (2.9), (2.12), and (2.7), the relativistic Euler equations are

$$u^\kappa \partial_\kappa h + c^2 \partial_\kappa u^\kappa = 0, \quad (2.17)$$

$$u^\kappa \partial_\kappa u^\alpha + \Pi^{\alpha\kappa} \partial_\kappa h - q(\eta^{-1})^{\alpha\kappa} \partial_\kappa s = 0, \quad (2.18)$$

$$u^\kappa \partial_\kappa s = 0. \quad (2.19)$$

²²One might argue that it is more accurate to think of u^0 as being “redundant” in the sense that it is algebraically determined in terms of $\{u^\alpha\}_{\alpha=1,2,3}$ via the condition $u^0 > 0$ and the normalization condition (2.20). In fact, in most of Sect. 9, we adopt this point of view. However, prior to Sect. 9, we do not adopt this point of view.

It is straightforward to see that the following constraint is preserved by the flow of Eqs. (2.18)–(2.19).

$$u_\kappa u^\kappa = -1. \quad (2.20)$$

Remark 2.9 (More common first-order formulations). Many authors define the relativistic Euler equations to be the system comprising (2.20), (2.25), and the four equations $\partial_\kappa T^{\alpha\kappa} = 0$, where $T^{\alpha\beta} := (\rho + p)u^\alpha u^\beta + p(\eta^{-1})^{\alpha\beta}$ is the fluid's energy-momentum tensor. These equations are in fact equivalent (at least in the case of C^1 solutions with $\rho > 0$) to Eqs. (2.17)–(2.20). We refer readers to [4, Chapter 1] for background material that is sufficient for understanding the equivalence.

Note that (2.19) is equivalent to

$$u^\kappa S_\kappa = 0. \quad (2.21)$$

Equation (2.18) can be written more explicitly as

$$u^\kappa \partial_\kappa u_\alpha + \partial_\alpha h + u_\alpha u^\kappa \partial_\kappa h - q S_\alpha = 0. \quad (2.22)$$

Also, from (2.22), we easily derive

$$u^\kappa \partial_\kappa (H u_\alpha) + \partial_\alpha H - \theta S_\alpha = 0. \quad (2.23)$$

Moreover, differentiating (2.19) with a rectangular coordinate partial derivative, we deduce

$$u^\kappa \partial_\kappa S_\alpha = -S_\kappa (\partial_\alpha u^\kappa). \quad (2.24)$$

In our analysis, we will also use the following evolution equation for n :

$$u^\kappa \partial_\kappa n + n \partial_\kappa u^\kappa = 0. \quad (2.25)$$

To obtain (2.25), we first use Eqs. (2.17) and (2.19), the thermodynamic relation $dH = dp/n + \theta ds$, and the relation $H = (\rho + p)/n$ to deduce $u^\kappa \partial_\kappa p + c^2(\rho + p)\partial_\kappa u^\kappa = 0$. We then use this equation, (2.9), and (2.19) to deduce $u^\kappa \partial_\kappa \rho + (\rho + p)\partial_\kappa u^\kappa = 0$. Next, using this equation and Eq. (2.19), we deduce $\frac{\partial \rho(n,s)}{\partial n} |_s u^\kappa \partial_\kappa n + (\rho + p)\partial_\kappa u^\kappa = 0$. Finally, from this equation and the thermodynamic relation $\rho + p = n \frac{\partial \rho(n,s)}{\partial n} |_s$, we conclude (2.25).

For future use, we also note that Eqs. (2.17)–(2.19) can be written [using (2.20)] in the form

$$A^\alpha \partial_\alpha \begin{pmatrix} h \\ u^0 \\ u^1 \\ u^2 \\ u^3 \\ s \end{pmatrix} = 0, \quad (2.26)$$

where for $\alpha = 0, 1, 2, 3$, A^α is a 6×6 matrix that is a smooth function of the solution array $(h, u^0, u^1, u^2, u^3, s)$. In particular, we compute that

$$A^0 = \begin{pmatrix} u^0 & c^2 & 0 & 0 & 0 & 0 \\ u_a u^a & u^0 & 0 & 0 & 0 & q \\ u^0 u^1 & 0 & u^0 & 0 & 0 & 0 \\ u^0 u^2 & 0 & 0 & u^0 & 0 & 0 \\ u^0 u^3 & 0 & 0 & 0 & u^0 & 0 \\ 0 & 0 & 0 & 0 & 0 & u^0 \end{pmatrix}, \quad (2.27)$$

and we compute that

$$\det A^0 = (u^0)^6 - c^2 (u^0)^4 u_a u^a = (1 + u_a u^a)^4 \{1 + (1 - c^2) u_b u^b\}. \quad (2.28)$$

In particular, in view of (2.11), we deduce from (2.28) that A^0 is invertible.

3. The New Formulation of the Relativistic Euler Equations

In the next theorem, we provide the main result of the article: the new formulation of the relativistic Euler equations.

Theorem 3.1 (New formulation of the relativistic Euler equations). *For C^3 solutions (h, s, u^α) to the relativistic Euler equations (2.17)–(2.19) + (2.20), the following equations hold, where the phrase “***g*-null form**” refers to a linear combination of the standard *g*-null forms of Definition 1.1 with coefficients that are allowed to depend on the quantities $(h, s, u^\alpha, S^\alpha, \varpi^\alpha)$ (but **not** their derivatives).*

Wave equations. *The logarithmic enthalpy h verifies the following covariant wave equation (see Footnote 5 on pg. 6 for a formula for the covariant wave operator):*

$$\square_g h = nc^2 q \mathcal{D} + \mathfrak{Q}_{(h)} + \mathfrak{L}_{(h)}, \quad (3.1)$$

where $\mathfrak{Q}_{(h)}$ is the ***g*-null form** defined by

$$\begin{aligned} \mathfrak{Q}_{(h)} := & -c^{-1} c_{;h} (g^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) \\ & + c^2 \{ (\partial_\kappa u^\kappa) (\partial_\lambda u^\lambda) - (\partial_\lambda u^\kappa) (\partial_\kappa u^\lambda) \}, \end{aligned} \quad (3.2a)$$

and $\mathfrak{L}_{(h)}$, which is at most linear in the derivatives of $(h, s, u^\alpha, S^\alpha, \varpi^\alpha)$, is defined by

$$\mathfrak{L}_{(h)} := \{ (1 - c^2) q + c^2 q_{;h} - cc_{;s} \} (S^\kappa \partial_\kappa h) + c^2 q_{;s} S_\kappa S^\kappa. \quad (3.2b)$$

Moreover, the rectangular four-velocity components²³ u^α verify the following covariant wave equations:

$$\square_g u^\alpha = -\frac{c^2}{H} \mathcal{C}^\alpha + \mathfrak{Q}_{(u^\alpha)} + \mathfrak{L}_{(u^\alpha)}, \quad (3.3)$$

²³We stress that on LHS (3.3), the components u^α are treated as scalar functions under the action of the covariant wave operator \square_g .

where $\mathfrak{Q}_{(u^\alpha)}$ is the ***g-null form*** defined by

$$\begin{aligned}\mathfrak{Q}_{(u^\alpha)} := & (\eta^{-1})^{\alpha\lambda} \{ (\partial_\kappa u^\kappa)(\partial_\lambda h) - (\partial_\lambda u^\kappa)(\partial_\kappa h) \} \\ & + c^2 u^\alpha \{ (\partial_\kappa u^\lambda)(\partial_\lambda u^\kappa) - (\partial_\lambda u^\lambda)(\partial_\kappa u^\kappa) \} \\ & - \{ 1 + c^{-1} c_{;h} \} (g^{-1})^{\kappa\lambda} (\partial_\kappa h)(\partial_\lambda u^\alpha),\end{aligned}\quad (3.4a)$$

and $\mathfrak{L}_{(u^\alpha)}$, which is at most linear in the derivatives of $(h, s, u^\alpha, S^\alpha, \varpi^\alpha)$, is defined by

$$\begin{aligned}\mathfrak{L}_{(u^\alpha)} := & -\frac{c^2}{H} \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta u_\gamma) \varpi_\delta + \frac{(1-c^2)}{H} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \\ & + \frac{(1-c^2)q}{H} \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma \varpi_\delta \\ & + \{ q - cc_{;s} \} (S^\kappa \partial_\kappa u^\alpha) + q(c^2 - 1) u^\alpha S^\kappa (u^\lambda \partial_\lambda u_\kappa) \\ & + S^\kappa \left\{ c^2 q + \frac{(\theta - \theta_{;h})c^2}{H} \right\} ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\kappa) \\ & + \{ 2c^{-1} c_{;h} q S^\alpha + 2c^{-1} c_{;s} S^\alpha - q_{;h} S^\alpha \} (u^\kappa \partial_\kappa h) \\ & + S^\alpha \left\{ \frac{(\theta - \theta_{;h})c^2}{H} - q \right\} (\partial_\kappa u^\kappa) + \frac{(\theta - \theta_{;h})c^2}{H} u^\alpha (S^\kappa \partial_\kappa h).\end{aligned}\quad (3.4b)$$

Auxiliary wave equation for s. The entropy s verifies the following covariant wave equation²⁴:

$$\square_g s = c^2 n \mathcal{D} + \mathfrak{L}_{(s)}, \quad (3.5)$$

where $\mathfrak{L}_{(s)}$, which is at most linear in the derivatives of $(h, s, u^\alpha, S^\alpha, \varpi^\alpha)$, is defined by

$$\mathfrak{L}_{(s)} := \{ 1 - c^2 - cc_{;h} \} (S^\kappa \partial_\kappa h) - cc_{;s} S_\kappa S^\kappa. \quad (3.6)$$

Transport equations. The rectangular components of the entropy gradient vectorfield S^α , whose η -dual is defined in (2.8), verify the following transport equations:

$$u^\kappa \partial_\kappa S^\alpha = -S_\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\kappa). \quad (3.7)$$

Moreover, the rectangular components of the vorticity vectorfield ϖ^α , which is defined in (2.5), verify the following transport equations:

$$\begin{aligned}u^\kappa \partial_\kappa \varpi^\alpha = & -u^\alpha (\varpi^\kappa \partial_\kappa h) + \varpi^\kappa \partial_\kappa u^\alpha - \varpi^\alpha (\partial_\kappa u^\kappa) \\ & + (\theta - \theta_{;h}) \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) S_\delta + qu^\alpha \varpi^\kappa S_\kappa.\end{aligned}\quad (3.8)$$

Transport-div-curl systems. The modified divergence of the entropy gradient \mathcal{D} [which is defined in (2.16b)] and the rectangular components $\text{vort}^\alpha(S)$

²⁴The wave equation (3.5) is auxiliary in the sense that we do not use it in our proof of Theorem 9.12. However, in applications (for example, in the study of shock formation), one has to compute \square_g applied to the scalar component functions $g_{\alpha\beta}$, and, by virtue of the chain rule, the quantity $\square_g s$ arises in such computations. It is for this reason that we have included Eq. (3.5) in this paper.

of the u -orthogonal vorticity of the entropy gradient vectorfield [see definition (2.4)] verify the following transport-div-curl system:

$$\begin{aligned} u^\kappa \partial_\kappa \mathcal{D} &= \frac{2}{n} \{ (\partial_\kappa S^\kappa) (\partial_\lambda u^\lambda) - (\partial_\lambda S^\kappa) (\partial_\kappa u^\lambda) \} \\ &\quad + \frac{1}{n} c^{-2} u^\kappa \{ (\partial_\kappa h) (\partial_\lambda S^\lambda) - (\partial_\lambda h) (\partial_\kappa S^\lambda) \} \\ &\quad + \frac{S_\kappa \mathcal{C}^\kappa}{nH} + \mathfrak{Q}_{(\mathcal{D})} + \mathfrak{L}_{(\mathcal{D})}, \end{aligned} \quad (3.9a)$$

$$\text{vort}^\alpha(S) = 0, \quad (3.9b)$$

where $\mathfrak{Q}_{(\mathcal{D})}$ is the **g -null form** defined by

$$\mathfrak{Q}_{(\mathcal{D})} := \frac{1}{n} c^{-2} S^\kappa \{ (\partial_\kappa u^\lambda) (\partial_\lambda h) - (\partial_\lambda u^\lambda) (\partial_\kappa h) \}, \quad (3.10a)$$

and $\mathfrak{L}_{(\mathcal{D})}$, which is linear in the derivatives of $(h, s, u^\alpha, S^\alpha, \varpi^\alpha)$, is defined by

$$\begin{aligned} \mathfrak{L}_{(\mathcal{D})} &:= \frac{(1 - c^{-2})}{nH} \epsilon^{\alpha\beta\gamma\delta} S_\alpha u_\beta (\partial_\gamma h) \varpi_\delta + \frac{1}{nH} \epsilon^{\alpha\beta\gamma\delta} S_\alpha (\partial_\beta u_\gamma) \varpi_\delta \\ &\quad + \frac{S^\kappa S^\lambda}{n} \left\{ \frac{(\theta - \theta_{;h})}{H} - 2q \right\} (\partial_\kappa u_\lambda) \\ &\quad + \frac{S_\kappa S^\kappa}{n} \left\{ \frac{(\theta_{;h} - \theta)}{H} + 2c^{-1} c_{;s} - c^2 q_{;h} + q \right\} (\partial_\lambda u^\lambda). \end{aligned} \quad (3.10b)$$

Finally, the divergence of the vorticity vectorfield ϖ^α (which is defined in (2.5)) and the rectangular components \mathcal{C}^α of the modified vorticity of the vorticity (which is defined in (2.16a)) verify the following equations:

$$\partial_\alpha \varpi^\alpha = -\varpi^\kappa \partial_\kappa h + 2q \varpi^\kappa S_\kappa, \quad (3.11a)$$

$$\begin{aligned} u^\kappa \partial_\kappa \mathcal{C}^\alpha &= \mathcal{C}^\kappa \partial_\kappa u^\alpha - 2\mathcal{C}^\alpha (\partial_\kappa u^\kappa) + u^\alpha \mathcal{C}^\kappa (u^\lambda \partial_\lambda u_\kappa) \\ &\quad - 2\epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\delta u_\kappa) \\ &\quad + (\theta_{;h} - \theta) \{ (\eta^{-1})^{\alpha\kappa} + 2u^\alpha u^\kappa \} \{ (\partial_\kappa h) (\partial_\lambda S^\lambda) - (\partial_\lambda h) (\partial_\kappa S^\lambda) \} \\ &\quad + (\theta - \theta_{;h}) n u^\alpha (u^\kappa \partial_\kappa h) \mathcal{D} \\ &\quad + (\theta - \theta_{;h}) q S^\alpha (\partial_\kappa S^\kappa) + (\theta_{;h} - \theta) q S_\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\kappa) \\ &\quad + \mathfrak{Q}_{(\mathcal{C}^\alpha)} + \mathfrak{L}_{(\mathcal{C}^\alpha)}, \end{aligned} \quad (3.11b)$$

where $\mathfrak{Q}_{(\mathcal{C}^\alpha)}$ is the **g -null form** defined by

$$\begin{aligned} \mathfrak{Q}_{(\mathcal{C}^\alpha)} &:= -c^{-2} \epsilon^{\kappa\beta\gamma\delta} (\partial_\kappa u^\alpha) u_\beta (\partial_\gamma h) \varpi_\delta \\ &\quad + (c^{-2} + 2) \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi^\kappa (\partial_\delta u_\kappa) \\ &\quad + c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta \varpi_\delta \{ (\partial_\kappa u^\kappa) (\partial_\gamma h) - (\partial_\gamma u^\kappa) (\partial_\kappa h) \} \\ &\quad + \{ (\theta_{;h;h} - \theta_h) + c^{-2} (\theta - \theta_{;h}) \} u^\kappa (\eta^{-1})^{\alpha\lambda} S^\beta \times \\ &\quad \{ (\partial_\kappa h) (\partial_\lambda u_\beta) - (\partial_\lambda h) (\partial_\kappa u_\beta) \} \\ &\quad + (\theta_{;h} - \theta) S^\kappa u^\lambda \{ (\partial_\kappa u^\alpha) (\partial_\lambda h) - (\partial_\lambda u^\alpha) (\partial_\kappa h) \} \\ &\quad + (\theta_{;h} - \theta) \{ (\eta^{-1})^{\alpha\kappa} + u^\alpha u^\kappa \} S^\beta \{ (\partial_\kappa u_\beta) (\partial_\lambda u^\lambda) - (\partial_\lambda u_\beta) (\partial_\kappa u^\lambda) \} \end{aligned}$$

$$\begin{aligned}
& + (\theta_{;h} - \theta) S^\alpha \{ (\partial_\kappa u^\lambda) \partial_\lambda u^\kappa - (\partial_\lambda u^\lambda) (\partial_\kappa u^\kappa) \} \\
& + (\theta_{;h} - \theta) S^\kappa \{ (\partial_\kappa u^\alpha) (\partial_\lambda u^\lambda) - (\partial_\lambda u^\alpha) (\partial_\kappa u^\lambda) \} \\
& + S^\alpha \{ c^{-2} (\theta_h - \theta_{;h;h}) + c^{-4} (\theta_{;h} - \theta) \} (g^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h),
\end{aligned} \tag{3.12a}$$

and $\mathfrak{L}_{(\mathcal{C}^\alpha)}$, which is linear in the derivatives of $(h, s, u^\alpha, S^\alpha, \varpi^\alpha)$, is defined by

$$\begin{aligned}
\mathfrak{L}_{(\mathcal{C}^\alpha)} := & \frac{2q}{H} (\varpi^\kappa S_\kappa \varpi^\alpha) - \frac{2}{H} \varpi^\alpha (\varpi^\kappa \partial_\kappa h) \\
& + 2c^{-3} c_{;\beta} \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi_\delta (u^\kappa \partial_\kappa h) \\
& - 2q \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi^\kappa (\partial_\delta u_\kappa) - q \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma \varpi_\delta (\partial_\kappa u^\kappa) \\
& + \frac{1}{H} (\theta - \theta_{;h}) \epsilon^{\kappa\beta\gamma\delta} (\partial_\kappa u^\alpha) S_\beta u_\gamma \varpi_\delta + c^{-2} q \epsilon^{\alpha\beta\gamma\delta} S_\beta (\partial_\gamma h) \varpi_\delta \\
& - c^{-2} q u^\alpha \epsilon^{\kappa\beta\gamma\delta} S_\kappa u_\beta (\partial_\gamma h) \varpi_\delta \\
& + (\theta_{;h} - \theta) q S_\kappa S^\kappa (u^\lambda \partial_\lambda u^\alpha) \\
& + u^\alpha S_\kappa S^\kappa \{ (\theta_{;h} - \theta) q + (\theta_{;h;s} - \theta_{;s}) \} (u^\lambda \partial_\lambda h) \\
& + S^\alpha \{ (\theta_{;s} - \theta_{;h;s}) + (\theta - \theta_{;h}) q_{;h} \} (S^\kappa \partial_\kappa h) \\
& + S_\kappa S^\kappa \{ (\theta_{;h;h} - \theta_h) q + (\theta_{;h;s} - \theta_{;s}) + (\theta - \theta_{;h}) q c^{-2} + (\theta_{;h} - \theta) q_{;h} \} \times \\
& \quad ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h).
\end{aligned} \tag{3.12b}$$

Remark 3.2 (Special structure of the inhomogeneous terms). We emphasize the following two points, which are of crucial importance for applications to shock waves (see Sect. 1.2.2 for further discussion): (i) all inhomogeneous terms on the RHSs of the equations of the theorem are at most quadratic in the derivatives of $(h, s, u^\alpha, S^\alpha, \varpi^\alpha)$ and (ii) **all derivative-quadratic terms on the RHSs of the equations of the theorem are linear combinations of standard g -null forms**. In particular, the following are linear combinations of standard g -null forms, even though we did not explicitly state so in the theorem: the terms on the first and second lines of RHS (3.9a) and the terms on the second and third lines of RHS (3.11b). We have separated these null forms, which involve the derivatives of ϖ and S , because they need to be handled with elliptic estimates, at least at the top derivative level (see the proof of Theorem 9.12). This is different compared to the terms $\mathfrak{Q}_{(h)}$, $\mathfrak{Q}_{(u^\alpha)}$, $\mathfrak{Q}_{(\mathcal{D})}$, and $\mathfrak{Q}_{(\mathcal{C}^\alpha)}$, which can be handled with standard energy estimates at all derivative levels.

Proof. Theorem 3.1 follows from a lengthy series of calculations, most of which we derive later in the paper, except that we have somewhat reorganized (using only simple algebra) the terms on the right-hand sides of the equations of the theorem. More precisely, we prove (3.1)–(3.2b) in Proposition 5.2.

We prove (3.3)–(3.4b) in Proposition 5.3.

We prove (3.5)–(3.6) in Proposition 5.4.

Equation (3.7) follows from raising the indices of (2.24) with the inverse Minkowski metric.

We prove (3.8) in Proposition 7.1.

Except for (3.9b), (3.9a)–(3.10b) follow from Proposition 6.2. Equation (3.9b) is a simple consequence of definition (2.4) and the symmetry property $\partial_\alpha S_\beta = \partial_\beta S_\alpha$ [see (4.1)].

Finally, we prove (3.11a)–(3.12b) in Proposition 8.2. \square

4. Preliminary Identities

In the next lemma, we derive some preliminary identities that we will later use when deriving the equations stated in Theorem 3.1.

Lemma 4.1 (Some useful identities). *Assume that (h, s, u^α) is a C^2 solution to (2.17)–(2.19) + (2.20), and let V_α be any C^1 one-form. Then the following identities hold:*

$$\partial_\alpha S_\beta = \partial_\beta S_\alpha, \quad (4.1)$$

$$\varpi^\kappa u_\kappa = 0, \quad (4.2)$$

$$\kappa \partial_\alpha u_\kappa = 0, \quad (4.3)$$

$$u^\kappa \partial_\alpha S_\kappa = -S^\kappa \partial_\alpha u_\kappa, \quad (4.4)$$

$$u^\kappa \partial_\alpha \varpi_\kappa = -\varpi^\kappa \partial_\alpha u_\kappa, \quad (4.5)$$

$$\partial_\alpha = -u_\alpha u^\kappa \partial_\kappa + \Pi_\alpha^\kappa \partial_\kappa, \quad (4.6)$$

$$\partial_\kappa V^\kappa = -u_\kappa u^\lambda \partial_\lambda V^\kappa + \Pi^{\kappa\lambda} \partial_\kappa V_\lambda, \quad (4.7)$$

$$\begin{aligned} \partial_\alpha V_\beta - \partial_\beta V_\alpha &= \epsilon_{\alpha\beta\gamma\delta} u^\gamma \text{vort}^\delta(V) + u_\alpha u^\kappa \partial_\beta V_\kappa - u_\beta u^\kappa \partial_\alpha V_\kappa \\ &\quad + u_\beta u^\kappa \partial_\kappa V_\alpha - u_\alpha u^\kappa \partial_\kappa V_\beta, \end{aligned} \quad (4.8)$$

$$\Pi^{\alpha\beta} \Pi^{\gamma\delta} (\partial_\alpha V_\gamma - \partial_\gamma V_\alpha) (\partial_\beta V_\delta - \partial_\delta V_\beta) = 2\Pi^{\alpha\beta} \text{vort}_\alpha(V) \text{vort}_\beta(V). \quad (4.9)$$

Moreover, if $u^\kappa V_\kappa = 0$, then

$$\begin{aligned} \partial_\alpha V_\beta - \partial_\beta V_\alpha &= \epsilon_{\alpha\beta\gamma\delta} u^\gamma \text{vort}^\delta(V) - u_\alpha V_\kappa \partial_\beta u^\kappa + u_\beta V_\kappa \partial_\alpha u^\kappa \\ &\quad + u_\beta u^\kappa \partial_\kappa V_\alpha - u_\alpha u^\kappa \partial_\kappa V_\beta. \end{aligned} \quad (4.10)$$

In addition, the following identity holds, where the indices for ϵ on LHS (4.11) are raised before Lie differentiation:

$$\mathcal{L}_u(\epsilon^{\alpha\beta\gamma\delta}) = (-\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta}. \quad (4.11)$$

Furthermore, the following identities hold:

$$\mathcal{L}_u(u_\beta)_\alpha = u^\kappa \partial_\kappa u_\alpha = -\partial_\alpha h - u_\alpha u^\kappa \partial_\kappa h + q S_\alpha, \quad (4.12)$$

$$\mathcal{L}_u d(Hu_\beta) = d\mathcal{L}_u(Hu_\beta), \quad (4.13)$$

$$[\mathcal{L}_u d(Hu_\beta)]_{\alpha\beta} = \theta_{;h}(\partial_\alpha h) \partial_\beta s - \theta_{;h}(\partial_\alpha s) \partial_\beta h, \quad (4.14)$$

$$\partial_\alpha (Hu_\beta) - \partial_\beta (Hu_\alpha) = \epsilon_{\alpha\beta\gamma\delta} u^\gamma \varpi^\delta + \theta \{S_\alpha u_\beta - S_\beta u_\alpha\}, \quad (4.15)$$

$$\epsilon^{\alpha\beta\gamma\delta} \partial_\gamma (Hu_\delta) = \varpi^\alpha u^\beta - u^\alpha \varpi^\beta + \theta \epsilon^{\alpha\beta\gamma\delta} S_\gamma u_\delta, \quad (4.16)$$

$$\begin{aligned} \partial_\alpha u_\beta - \partial_\beta u_\alpha &= \frac{1}{H} \epsilon_{\alpha\beta\gamma\delta} u^\gamma \varpi^\delta - (\partial_\alpha h) u_\beta + (\partial_\beta h) u_\alpha \\ &\quad + q \{S_\alpha u_\beta - S_\beta u_\alpha\}, \end{aligned} \quad (4.17)$$

$$(u^\kappa \partial_\kappa u_\lambda) S^\lambda = -S^\kappa \partial_\kappa h + q S_\kappa S^\kappa, \quad (4.18)$$

$$(u^\kappa \partial_\kappa S_\lambda) u^\lambda = S^\kappa \partial_\kappa h - q S_\kappa S^\kappa, \quad (4.19)$$

$$\begin{aligned} S^\kappa \partial_\alpha u_\kappa &= S^\kappa \partial_\kappa u_\alpha + (S^\kappa \partial_\kappa h) u_\alpha - q S^\kappa S_\kappa u_\alpha + \frac{1}{H} \epsilon_{\alpha\kappa\gamma\delta} S^\kappa u^\gamma \varpi^\delta \\ &= S^\kappa \partial_\kappa u_\alpha - (S^\kappa u^\lambda \partial_\lambda u_\kappa) u_\alpha + \frac{1}{H} \epsilon_{\alpha\beta\gamma\delta} S^\beta u^\gamma \varpi^\delta, \end{aligned} \quad (4.20)$$

$$\varpi^\kappa \partial_\kappa u_\alpha = \varpi^\kappa \partial_\alpha u_\kappa - (\varpi^\kappa \partial_\kappa h) u_\alpha + q \varpi^\kappa S_\kappa u_\alpha, \quad (4.21)$$

$$\epsilon^{\alpha\beta\gamma\delta} \partial_\gamma u_\delta = \frac{1}{H} \varpi^\alpha u^\beta - \frac{1}{H} u^\alpha \varpi^\beta - \epsilon^{\alpha\beta\gamma\delta} (\partial_\gamma h) u_\delta + q \epsilon^{\alpha\beta\gamma\delta} S_\gamma u_\delta, \quad (4.22)$$

$$\epsilon^{\alpha\beta\gamma\delta} u_\beta \partial_\gamma u_\delta = -\frac{1}{H} \varpi^\alpha, \quad (4.23)$$

$$\begin{aligned} \partial_\gamma \varpi_\delta - \partial_\delta \varpi_\gamma &= \epsilon_{\gamma\delta\kappa\lambda} u^\kappa \text{vort}^\lambda(\varpi) - (u^\kappa \partial_\kappa \varpi_\delta) u_\gamma + u^\kappa (\partial_\delta \varpi_\kappa) u_\gamma \\ &\quad + (u^\kappa \partial_\kappa \varpi_\gamma) u_\delta - u^\kappa (\partial_\gamma \varpi_\kappa) u_\delta, \end{aligned} \quad (4.24)$$

$$\begin{aligned} \epsilon^{\alpha\beta\gamma\delta} \partial_\gamma \varpi_\delta &= \text{vort}^\alpha(\varpi) u^\beta - u^\alpha \text{vort}^\beta(\varpi) + \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa \varpi_\gamma) u_\delta \\ &\quad - \epsilon^{\alpha\beta\gamma\delta} u^\kappa (\partial_\gamma \varpi_\kappa) u_\delta. \end{aligned} \quad (4.25)$$

Proof. (4.1) follows from definition (2.8) and the symmetry property $\partial_\alpha \partial_\beta s = \partial_\beta \partial_\alpha s$. Equation (4.2) is a simple consequence of definition (2.2). Equation (4.3) follows from differentiating (2.20) with ∂_α . Equation (4.4) follows from differentiating (2.21) with ∂_α . Equation (4.5) follows from differentiating (4.2) with ∂_α . Equation (4.6) follows directly from definition (2.12). Equation (4.7) then follows from (4.6).

To prove (4.8), we first use definition (2.4) to express the first product on RHS (4.8) as follows:

$$\epsilon_{\alpha\beta\gamma\delta} u^\gamma \text{vort}^\delta(V) = -\epsilon_{\alpha\beta\gamma\delta} \epsilon^{\delta\theta\kappa\lambda} u^\gamma u_\theta \partial_\kappa V_\lambda. \quad (4.26)$$

Next, we observe the following identity for the first two factors on RHS (4.26):

$$\begin{aligned} -\epsilon_{\alpha\beta\gamma\delta} \epsilon^{\delta\theta\kappa\lambda} &= \epsilon_{\alpha\beta\gamma\delta} \epsilon^{\theta\kappa\lambda\delta} \\ &= \delta_\alpha^\theta \delta_\gamma^\kappa \delta_\beta^\lambda - \delta_\alpha^\theta \delta_\gamma^\lambda \delta_\beta^\kappa + \delta_\alpha^\lambda \delta_\gamma^\theta \delta_\beta^\kappa - \delta_\alpha^\lambda \delta_\gamma^\kappa \delta_\beta^\theta + \delta_\alpha^\kappa \delta_\gamma^\lambda \delta_\beta^\theta - \delta_\alpha^\kappa \delta_\gamma^\theta \delta_\beta^\lambda. \end{aligned} \quad (4.27)$$

Using (4.27) to substitute on RHS (4.26), we deduce, in view of (2.20), the following identity:

$$\begin{aligned} -\epsilon_{\alpha\beta\gamma\delta} \epsilon^{\delta\theta\kappa\lambda} u_\theta \partial_\kappa V_\lambda u^\gamma &= u_\alpha u^\kappa \partial_\kappa V_\beta - u_\alpha u^\kappa \partial_\beta V_\kappa - \partial_\beta V_\alpha \\ &\quad - u_\beta u^\kappa \partial_\kappa V_\alpha + u_\beta u^\kappa \partial_\alpha V_\kappa + \partial_\alpha V_\beta. \end{aligned} \quad (4.28)$$

Combining (4.26) and (4.28) and rearranging the terms, we arrive at the desired identity (4.8). Equation (4.10) then follows from (4.8) and the relation $u^\kappa \partial_\alpha V_\kappa = -V_\kappa \partial_\alpha u^\kappa$, which follows from differentiating the assumed identity $u^\kappa V_\kappa = 0$ with ∂_α .

To prove (4.9), we first use (4.8) to deduce

$$\begin{aligned} & \Pi^{\alpha\beta}\Pi^{\gamma\delta}(\partial_\alpha V_\gamma - \partial_\gamma V_\alpha)(\partial_\beta V_\delta - \partial_\delta V_\beta) \\ &= \Pi^{\alpha\beta}\Pi^{\gamma\delta}\epsilon_{\alpha\gamma\kappa\lambda}\epsilon_{\beta\delta\mu\nu}u^\kappa\text{vort}^\lambda(V)u^\mu\text{vort}^\nu(V). \end{aligned} \quad (4.29)$$

Next, we note the following identity, which follows easily from definition (2.12):

$$\begin{aligned} & \Pi^{\alpha\beta}\Pi^{\gamma\delta}\epsilon_{\alpha\gamma\kappa\lambda}\epsilon_{\beta\delta\mu\nu}u^\kappa\text{vort}^\lambda(V)u^\mu\text{vort}^\nu(V) \\ &= (\eta^{-1})^{\alpha\beta}(\eta^{-1})^{\gamma\delta}\epsilon_{\alpha\gamma\kappa\lambda}\epsilon_{\beta\delta\mu\nu}u^\kappa\text{vort}^\lambda(V)u^\mu\text{vort}^\nu(V) \\ &= \epsilon^{\alpha\beta\kappa\lambda}\epsilon_{\alpha\beta\mu\nu}u_\kappa\text{vort}_\lambda(V)u^\mu\text{vort}^\nu(V). \end{aligned} \quad (4.30)$$

From (4.30), the identity $\epsilon^{\alpha\beta\kappa\lambda}\epsilon_{\alpha\beta\mu\nu} = 2\delta_\mu^\lambda\delta_\nu^\kappa - 2\delta_\mu^\kappa\delta_\nu^\lambda$, (2.20), and the simple identity $u_\alpha\text{vort}^\alpha(V) = 0$ [which follows easily from definition (2.4)], we find that RHS (4.30) = 2vort _{α} (V)vort ^{α (V). Again using that $u_\alpha\text{vort}^\alpha(V) = 0$, we conclude, in view of definition (2.12), the desired identity (4.9). Equation (4.11) is a standard geometric identity, as is (4.13).}

To prove (4.12), we first note the Lie differentiation identity $\mathcal{L}_u(u_b)_\alpha = u^\kappa\partial_\kappa u_\alpha + u_\kappa\partial_\alpha u^\kappa$, which follows from (2.1). Equation (4.12) follows from this identity, (2.22), and (4.3).

To prove (4.14), we first use (2.23) and the Lie derivative formula (2.1) to deduce that $\mathcal{L}_u(Hu_b)_\alpha = u^\kappa\partial_\kappa(Hu_\alpha) + Hu_\kappa\partial_\alpha u^\kappa = -\partial_\alpha H + \theta\partial_\alpha s + Hu_\kappa\partial_\alpha u^\kappa$. From (4.3), we see that the last product on the RHS of this identity vanishes. Hence, taking the exterior derivative of the identity, we obtain $[d\mathcal{L}_u(Hu_b)]_{\alpha\beta} = \theta_{;h}(\partial_\alpha h)\partial_\beta s - \theta_{;h}(\partial_\alpha s)\partial_\beta h$. The desired identity (4.14) now follows from this identity and (4.13).

To prove (4.15), we first use definition (2.5) to compute that

$$\epsilon_{\alpha\beta\gamma\delta}u^\gamma\varpi^\delta = -\epsilon_{\alpha\beta\gamma\delta}\epsilon^{\delta\kappa\theta\lambda}u^\gamma u_\kappa\partial_\theta(Hu_\lambda).$$

Using the identity $\epsilon_{\alpha\beta\gamma\delta}\epsilon^{\delta\kappa\theta\lambda} = -\epsilon_{\alpha\beta\gamma\delta}\epsilon^{\lambda\kappa\theta\delta} = \delta_\alpha^\lambda\delta_\beta^\kappa\delta_\gamma^\theta - \delta_\alpha^\lambda\delta_\beta^\theta\delta_\gamma^\kappa + \delta_\alpha^\kappa\delta_\beta^\theta\delta_\gamma^\lambda - \delta_\alpha^\kappa\delta_\beta^\lambda\delta_\gamma^\theta + \delta_\alpha^\theta\delta_\beta^\lambda\delta_\gamma^\kappa - \delta_\alpha^\theta\delta_\beta^\kappa\delta_\gamma^\lambda$, we deduce, in view of (2.20), that

$$\begin{aligned} -\epsilon_{\alpha\beta\gamma\delta}\epsilon^{\delta\kappa\theta\lambda}u^\gamma u_\kappa\partial_\theta(Hu_\lambda) &= \partial_\alpha(Hu_\beta) - \partial_\beta(Hu_\alpha) \\ &\quad - u_\beta u^\kappa\partial_\kappa(Hu_\alpha) - u_\alpha u^\kappa\partial_\beta(Hu_\kappa) \\ &\quad + u_\alpha u^\kappa\partial_\kappa(Hu_\beta) + u_\beta u^\kappa\partial_\alpha(Hu_\kappa). \end{aligned} \quad (4.31)$$

Using (2.20), (2.23), and (4.3), we compute that the last four products on RHS (4.31) sum to $\theta(u_\alpha S_\beta - u_\beta S_\alpha)$, which yields the desired identity (4.15).

To prove (4.16), we first contract $\frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}$ against (4.15) to obtain the identity

$$\epsilon^{\alpha\beta\gamma\delta}\partial_\gamma(Hu_\delta) = \frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\gamma\delta\kappa\lambda}u^\kappa\varpi^\lambda + \theta\epsilon^{\alpha\beta\gamma\delta}S_\gamma u_\delta. \quad (4.32)$$

(4.16) now follows from using the identity $\frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\gamma\delta\kappa\lambda} = \delta_\kappa^\beta\delta_\lambda^\alpha - \delta_\kappa^\alpha\delta_\lambda^\beta$ to substitute for the factor $\frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\gamma\delta\kappa\lambda}$ on RHS (4.32). Equation (4.17) follows from (4.15) and simple computations.

To prove (4.18), we contract S^α against Eq. (2.22) and use Eq. (2.21). Equation (4.19) then follows from (4.4) and (4.18).

To prove the first equality in (4.20), we contract S^β against (4.17) and use Eq. (2.21). To obtain the second equality in (4.20), we use the first equality and the identity (4.18). Equation (4.21) follows from contracting (4.17) against ϖ^α and using (4.2).

To prove (4.22), we first use (4.17) to deduce that

$$\epsilon^{\alpha\beta\gamma\delta}\partial_\gamma u_\delta = \frac{1}{2}\frac{1}{H}\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\gamma\delta\kappa\lambda}u^\kappa\varpi^\lambda - \epsilon^{\alpha\beta\gamma\delta}(\partial_\gamma h)u_\delta + q\epsilon^{\alpha\beta\gamma\delta}S_\gamma u_\delta. \quad (4.33)$$

(4.22) now follows from using the identity $\frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\gamma\delta\kappa\lambda} = \delta_\kappa^\beta\delta_\lambda^\alpha - \delta_\kappa^\alpha\delta_\lambda^\beta$ to substitute for the product $\frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\gamma\delta\kappa\lambda}$ on RHS (4.33).

To prove (4.23), we contract (4.22) against u_β and use (2.20) and (4.2).

To prove (4.24), we first use definition (2.4) to express the first product on RHS (4.24) as follows:

$$\epsilon_{\gamma\delta\kappa\lambda}u^\kappa\text{vort}^\lambda(\varpi) = -\epsilon_{\gamma\delta\kappa\lambda}\epsilon^{\lambda\theta\alpha\beta}u^\kappa u_\theta\partial_\alpha\varpi_\beta. \quad (4.34)$$

Next, we use the identity $-\epsilon_{\gamma\delta\kappa\lambda}\epsilon^{\lambda\theta\alpha\beta} = \epsilon_{\gamma\delta\kappa\lambda}\epsilon^{\theta\alpha\beta\lambda} = \delta_\gamma^\theta\delta_\delta^\beta\delta_\kappa^\alpha - \delta_\gamma^\theta\delta_\delta^\alpha\delta_\kappa^\beta + \delta_\gamma^\alpha\delta_\delta^\theta\delta_\kappa^\beta - \delta_\gamma^\alpha\delta_\delta^\beta\delta_\kappa^\theta + \delta_\gamma^\beta\delta_\delta^\alpha\delta_\kappa^\theta - \delta_\gamma^\beta\delta_\delta^\theta\delta_\kappa^\alpha$ to substitute on RHS (4.34), thereby obtaining, in view of (2.20), the following identity:

$$\begin{aligned} \epsilon_{\gamma\delta\kappa\lambda}u^\kappa\text{vort}^\lambda(\varpi) &= u_\gamma u^\kappa\partial_\kappa\varpi_\delta - u_\gamma u^\kappa\partial_\delta\varpi_\kappa + u_\delta u^\kappa\partial_\gamma\varpi_\kappa + \partial_\gamma\varpi_\delta \\ &\quad - \partial_\delta\varpi_\gamma - u_\delta u^\kappa\partial_\kappa\varpi_\gamma. \end{aligned} \quad (4.35)$$

Finally, we note that it is straightforward to see that (4.35) is equivalent to the desired identity (4.24).

To prove (4.25), we first contract (4.24) against $\frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}$ to deduce

$$\begin{aligned} \epsilon^{\alpha\beta\gamma\delta}\partial_\gamma\varpi_\delta &= \frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\gamma\delta\kappa\lambda}u^\kappa\text{vort}^\lambda(\varpi) + \epsilon^{\alpha\beta\gamma\delta}(u^\kappa\partial_\kappa\varpi_\gamma)u_\delta \\ &\quad - \epsilon^{\alpha\beta\gamma\delta}u^\kappa(\partial_\gamma\varpi_\kappa)u_\delta. \end{aligned} \quad (4.36)$$

Using the identity $\frac{1}{2}\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\gamma\delta\kappa\lambda} = \frac{1}{2}\epsilon^{\gamma\delta\alpha\beta}\epsilon_{\gamma\delta\kappa\lambda} = \delta_\kappa^\beta\delta_\lambda^\alpha - \delta_\kappa^\alpha\delta_\lambda^\beta$ to substitute in the first product on RHS (4.36), we arrive at the desired identity (4.25). \square

5. Wave Equations

In this section, with the help of the preliminary identities of Lemma 4.1, we derive the covariant wave equations (3.1), (3.3), and (5.18).

5.1. Covariant Wave Operator

We start by establishing a formula for the covariant wave operator of the acoustical metric acting on a scalar function.

Lemma 5.1 (Covariant wave operator of g). *Assume that (h, s, u^α) is a C^2 solution to (2.17)–(2.19) + (2.20). Then the covariant wave operator of the acoustical metric $g = g(h, s, u)$ (see Definition 2.6) acts on scalar functions ϕ as follows, where RHS (5.1) is expressed relative to the rectangular coordinates:*

$$\begin{aligned}
\Box_g \phi &= (c^2 - 1)u^\kappa \partial_\kappa (u^\lambda \partial_\lambda \phi) + c^2((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda \phi) \\
&\quad + (c^2 - 1)(\partial_\kappa u^\kappa)(u^\lambda \partial_\lambda \phi) + 2c^{-1}c_{;h}(u^\kappa \partial_\kappa h)(u^\lambda \partial_\lambda \phi) \\
&\quad - c^{-1}c_{;h}(g^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda \phi) \\
&\quad - cc_{;s}(S^\kappa \partial_\kappa \phi).
\end{aligned} \tag{5.1}$$

Proof. It is a standard fact that relative to arbitrary coordinates (and in particular relative to the rectangular coordinates), we have

$$\Box_g \phi = \frac{1}{\sqrt{|\det g|}} \partial_\kappa \left(\sqrt{|\det g|} (g^{-1})^{\kappa\lambda} \partial_\lambda \phi \right).$$

Using this formula and (2.14a)–(2.14b), we compute that

$$\begin{aligned}
\Box_g \phi &= c^3 \partial_\kappa \left\{ -(c^{-3} - c^{-1})u^\kappa (u^\lambda \partial_\lambda \phi) + c^{-1}((\eta^{-1})^{\kappa\lambda} \partial_\lambda \phi) \right\} \\
&= -(1 - c^2)u^\kappa \partial_\kappa (u^\lambda \partial_\lambda \phi) - (1 - c^2)(\partial_\kappa u^\kappa)(u^\lambda \partial_\lambda \phi) \\
&\quad + (3c^{-1} - c)(u^\kappa \partial_\kappa c)(u^\lambda \partial_\lambda \phi) - c(\eta^{-1})^{\kappa\lambda}(\partial_\kappa c)(\partial_\lambda \phi) \\
&\quad + c^2((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda \phi).
\end{aligned} \tag{5.2}$$

The desired identity (5.1) now follows from (5.2), (2.13b), the evolution equation (2.19), and straightforward computations. \square

5.2. Covariant Wave Equation for the Logarithmic Enthalpy

We now derive the covariant wave equation (3.1).

Proposition 5.2 (Covariant wave equation for the logarithmic enthalpy). *Assume that (h, s, u^α) is a C^2 solution to (2.17)–(2.19) + (2.20). Then the logarithmic enthalpy h verifies the following covariant wave equation:*

$$\begin{aligned}
\Box_g h &= nc^2 q \mathcal{D} - c^{-1}c_{;h}(g^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda h) \\
&\quad + c^2 \{(\partial_\kappa u^\kappa)(\partial_\lambda u^\lambda) - (\partial_\kappa u^\lambda)(\partial_\lambda u^\kappa)\} \\
&\quad + (1 - c^2)q(S^\kappa \partial_\kappa h) - cc_{;s}(S^\kappa \partial_\kappa h) + c^2 q_{;h}(S^\kappa \partial_\kappa h) + c^2 q_{;s}S_\kappa S^\kappa.
\end{aligned} \tag{5.3}$$

Proof. From (5.1) with $\phi := h$, we deduce

$$\begin{aligned}
\Box_g h &= (c^2 - 1)u^\kappa \partial_\kappa (u^\lambda \partial_\lambda h) + c^2((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h) \\
&\quad + (c^2 - 1)(\partial_\kappa u^\kappa)(u^\lambda \partial_\lambda h) + 2c^{-1}c_{;h}(u^\kappa \partial_\kappa h)(u^\lambda \partial_\lambda h) \\
&\quad - c^{-1}c_{;h}(g^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda h) \\
&\quad - cc_{;s}(S^\kappa \partial_\kappa h).
\end{aligned} \tag{5.4}$$

Next, we differentiate Eq. (2.22) with ∂_β , contract against $(\eta^{-1})^{\alpha\beta}$, and multiply by c^2 to obtain the identity

$$\begin{aligned}
c^2((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h) &= -c^2(u^\kappa \partial_\kappa \partial_\lambda u^\lambda) - c^2(\partial_\kappa u^\lambda)(\partial_\lambda u^\kappa) \\
&\quad - c^2 u^\kappa \partial_\kappa (u^\lambda \partial_\lambda h) - c^2(\partial_\kappa u^\kappa)(u^\lambda \partial_\lambda h) \\
&\quad + c^2 q(\partial_\kappa S^\kappa) + c^2 q_{;h}(S^\kappa \partial_\kappa h) + c^2 q_{;s}S^\kappa S_\kappa.
\end{aligned} \tag{5.5}$$

Next, we use (2.17) and the evolution equation (2.19) to rewrite the first product on RHS (5.5) as follows:

$$\begin{aligned} -c^2(u^\kappa \partial_\kappa \partial_\lambda u^\lambda) &= c^2 u^\kappa \partial_\kappa (c^{-2} u^\lambda \partial_\lambda h) \\ &= u^\kappa \partial_\kappa (u^\lambda \partial_\lambda h) - 2c^{-1} c_{;h} (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h). \end{aligned} \quad (5.6)$$

Using (5.6) to substitute for the first product on RHS (5.5) and then using the resulting identity to substitute for the product $c^2(\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h$ on RHS (5.4), we deduce

$$\begin{aligned} \square_g h &= -c^2(\partial_\kappa u^\lambda)(\partial_\lambda u^\kappa) - (\partial_\kappa u^\kappa)(u^\lambda \partial_\lambda h) \\ &\quad - c^{-1} c_{;h} (g^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) \\ &\quad - c c_{;s} (S^\kappa \partial_\kappa h) + c^2 q (\partial_\kappa S^\kappa) + c^2 q_{;h} (S^\kappa \partial_\kappa h) + c^2 q_{;s} S^\kappa S_\kappa. \end{aligned} \quad (5.7)$$

Finally, we use Eq. (2.17) to substitute for the factor $u^\lambda \partial_\lambda h$ in the second product on RHS (5.7), and we use definition (2.16b) to express the product $c^2 q (\partial_\kappa S^\kappa)$ on RHS (5.7) as $nc^2 q \mathcal{D} + (1 - c^2) q (S^\kappa \partial_\kappa h)$, which in total yields the desired Eq. (5.3). \square

5.3. Covariant Wave Equation for the Rectangular Components of the Four-Velocity

We now derive the covariant wave equation (3.3).

Proposition 5.3 (Covariant wave equation for the rectangular four-velocity components). *Assume that (h, s, u^α) is a C^2 solution to (2.17)–(2.19) + (2.20). Then the rectangular velocity components u^α verify the following covariant wave equations:*

$$\begin{aligned} \square_g u^\alpha &= -\frac{c^2}{H} \mathcal{C}^\alpha \\ &\quad - \frac{c^2}{H} \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta u_\gamma) \varpi_\delta + \frac{(1 - c^2)}{H} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \\ &\quad + \frac{(1 - c^2)q}{H} \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma \varpi_\delta \\ &\quad - (g^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda u^\alpha) - c^{-1} c_{;h} (g^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda u^\alpha) \\ &\quad + (\eta^{-1})^{\alpha\lambda} \{(\partial_\kappa u^\kappa) (\partial_\lambda h) - (\partial_\lambda u^\kappa) (\partial_\kappa h)\} \\ &\quad + c^2 u^\alpha \{(\partial_\kappa u^\lambda) (\partial_\lambda u^\kappa) - (\partial_\lambda u^\lambda) (\partial_\kappa u^\kappa)\} \\ &\quad - c c_{;s} (S^\kappa \partial_\kappa u^\alpha) + q (S^\kappa \partial_\kappa u^\alpha) \\ &\quad + (c^2 - 1) q u^\alpha (S^\kappa u^\lambda \partial_\lambda u_\kappa) + c^2 q S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\kappa) \\ &\quad + 2c^{-1} c_{;s} S^\alpha (u^\kappa \partial_\kappa h) + 2c^{-1} c_{;h} q S^\alpha (u^\kappa \partial_\kappa h) \\ &\quad - q_{;h} S^\alpha (u^\kappa \partial_\kappa h) - q S^\alpha (\partial_\kappa u^\kappa) \\ &\quad + (\theta - \theta_{;h}) \frac{c^2}{H} S^\alpha (\partial_\kappa u^\kappa) + (\theta - \theta_{;h}) \frac{c^2}{H} u^\alpha (S^\kappa \partial_\kappa h) \\ &\quad + (\theta_{;h} - \theta) \frac{c^2}{H} S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\kappa). \end{aligned} \quad (5.8)$$

Proof. From (5.1) with $\phi := u_\alpha$, we deduce

$$\begin{aligned}\square_g u_\alpha &= (c^2 - 1)u^\kappa \partial_\kappa (u^\lambda \partial_\lambda u_\alpha) + c^2((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda u_\alpha) \\ &\quad + (c^2 - 1)(\partial_\kappa u^\kappa)(u^\lambda \partial_\lambda u_\alpha) + 2c^{-1}c_{;h}(u^\kappa \partial_\kappa h)(u^\lambda \partial_\lambda u_\alpha) \\ &\quad - c^{-1}c_{;h}(g^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda u_\alpha) - cc_{;s}(S^\kappa \partial_\kappa u_\alpha).\end{aligned}\quad (5.9)$$

Next, we use Eqs. (2.19), (2.22), and the second line of (6.1) [where below, we derive (6.1) using an independent argument] to rewrite the first product on RHS (5.9) as follows:

$$\begin{aligned}(c^2 - 1)u^\kappa \partial_\kappa (u^\lambda \partial_\lambda u_\alpha) &= (1 - c^2)(u^\kappa \partial_\kappa \partial_\alpha h) + (1 - c^2)\{u^\kappa \partial_\kappa (u^\lambda \partial_\lambda h)\} u_\alpha \\ &\quad + (1 - c^2)(u^\kappa \partial_\kappa u_\alpha)(u^\lambda \partial_\lambda h) + (c^2 - 1)u^\kappa \partial_\kappa (qS_\alpha) \\ &= (1 - c^2)(u^\kappa \partial_\kappa \partial_\alpha h) + (1 - c^2)\{u^\kappa \partial_\kappa (u^\lambda \partial_\lambda h)\} u_\alpha \\ &\quad + (1 - c^2)(u^\kappa \partial_\kappa u_\alpha)(u^\lambda \partial_\lambda h) + (c^2 - 1)q_{;h}(u^\kappa \partial_\kappa h)S_\alpha \\ &\quad + (1 - c^2)q(S^\kappa \partial_\kappa u_\alpha) + \frac{1}{H}(1 - c^2)q\epsilon_{\alpha\beta\gamma\delta}S^\beta u^\gamma \varpi^\delta \\ &\quad + (c^2 - 1)qS^\kappa(u^\lambda \partial_\lambda u_\kappa)u_\alpha.\end{aligned}\quad (5.10)$$

Next, we use definition (2.16b), the identity (4.17), and the evolution equations (2.17), (2.19), and (2.24) to rewrite the second product on RHS (5.9) as follows:

$$\begin{aligned}c^2((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda u_\alpha) &= c^2(\partial_\alpha \partial_\kappa u^\kappa) \\ &\quad + c^2(\eta^{-1})^{\kappa\lambda} \partial_\kappa \left\{ \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} u^\gamma \varpi^\delta - (\partial_\lambda h)u_\alpha + (\partial_\alpha h)u_\lambda + \right. \\ &\quad \left. qS_\lambda u_\alpha - qS_\alpha u_\lambda \right\} \\ &= (c^2 - 1)(u^\kappa \partial_\kappa \partial_\alpha h) - (\partial_\alpha u^\kappa)(\partial_\kappa h) \\ &\quad + 2c^{-1}c_{;h}(\partial_\alpha h)(u^\kappa \partial_\kappa h) + 2c^{-1}c_{;s}S_\alpha(u^\kappa \partial_\kappa h) \\ &\quad - c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa h)u^\gamma \varpi^\delta \\ &\quad + c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa u^\gamma) \varpi^\delta \\ &\quad + c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} u^\gamma ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \varpi^\delta) \\ &\quad - c^2((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h)u_\alpha - c^2(\eta^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda u_\alpha) \\ &\quad + c^2(\partial_\alpha h)(\partial_\kappa u^\kappa) \\ &\quad + c^2q_{;h}(S^\kappa \partial_\kappa h)u_\alpha + c^2q_{;s}S_\kappa S^\kappa u_\alpha \\ &\quad + c^2q(\partial_\kappa S^\kappa)u_\alpha + c^2q(S^\kappa \partial_\kappa u_\alpha) \\ &\quad - c^2q_{;h}(u^\kappa \partial_\kappa h)S_\alpha - c^2q(u^\kappa \partial_\kappa S_\alpha) - c^2q(\partial_\kappa u^\kappa)S_\alpha \\ &= nc^2q\mathcal{D}u_\alpha \\ &\quad + (c^2 - 1)(u^\kappa \partial_\kappa \partial_\alpha h) - (\partial_\alpha u^\kappa)(\partial_\kappa h)\end{aligned}$$

$$\begin{aligned}
& + 2c^{-1}c_{;h}(\partial_\alpha h)(u^\kappa \partial_\kappa h) \\
& - c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa h) u^\gamma \varpi^\delta \\
& + c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa u^\gamma) \varpi^\delta \\
& + c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} u^\gamma ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \varpi^\delta) \\
& - c^2 ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h) u_\alpha - c^2 (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda u_\alpha) \\
& + c^2 (\partial_\alpha h) (\partial_\kappa u^\kappa) \\
& + c^2 q_{;h} (S^\kappa \partial_\kappa h) u_\alpha + c^2 q_{;s} S_\kappa S^\kappa u_\alpha + c^2 q (S^\kappa \partial_\kappa u_\alpha) \\
& - c^2 q_{;h} (u^\kappa \partial_\kappa h) S_\alpha + c^2 q (\partial_\alpha u^\kappa) S_\kappa - c^2 q (\partial_\kappa u^\kappa) S_\alpha \\
& + (1 - c^2) q (S^\kappa \partial_\kappa h) u_\alpha + 2c^{-1}c_{;s} (u^\kappa \partial_\kappa h) S_\alpha. \quad (5.11)
\end{aligned}$$

Next, we use the identity (5.1) with $\phi := h$ to substitute for the term $\square_g h$ on LHS (5.3), which yields the identity

$$\begin{aligned}
c^2 ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h) & = c^2 \{ (\partial_\kappa u^\kappa) (\partial_\lambda u^\lambda) - (\partial_\lambda u^\kappa) (\partial_\kappa u^\lambda) \} \\
& + (1 - c^2) u^\kappa \partial_\kappa (u^\lambda \partial_\lambda h) + (1 - c^2) (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda h) \\
& - 2c^{-1} c_{;h} (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + nc^2 q \mathcal{D} \\
& + (1 - c^2) q (S^\kappa \partial_\kappa h) + c^2 q_{;h} (S^\kappa \partial_\kappa h) + c^2 q_{;s} S_\kappa S^\kappa. \quad (5.12)
\end{aligned}$$

From (5.12), it follows that the product $-c^2 ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h) u_\alpha$ on RHS (5.11) can be expressed as

$$\begin{aligned}
-c^2 ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h) u_\alpha & = c^2 \{ (\partial_\kappa u^\lambda) (\partial_\lambda u^\kappa) - (\partial_\lambda u^\lambda) (\partial_\kappa u^\kappa) \} u_\alpha \\
& + (c^2 - 1) \{ u^\kappa \partial_\kappa (u^\lambda \partial_\lambda h) \} u_\alpha \\
& + (c^2 - 1) (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda h) u_\alpha \\
& + 2c^{-1} c_{;h} (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) u_\alpha \\
& - nc^2 q \mathcal{D} u_\alpha \\
& + (c^2 - 1) q (S^\kappa \partial_\kappa h) u_\alpha - c^2 q_{;h} (S^\kappa \partial_\kappa h) u_\alpha \\
& - c^2 q_{;s} S_\kappa S^\kappa u_\alpha. \quad (5.13)
\end{aligned}$$

Using (5.13) to substitute for the term $-c^2 ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h) u_\alpha$ on RHS (5.11), we obtain the identity

$$\begin{aligned}
c^2 ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda u_\alpha) & = (c^2 - 1) (u^\kappa \partial_\kappa \partial_\alpha h) - (\partial_\alpha u^\kappa) (\partial_\kappa h) \\
& + 2c^{-1} c_{;h} (\partial_\alpha h) (u^\kappa \partial_\kappa h) \\
& - c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa h) u^\gamma \varpi^\delta \\
& + c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa u^\gamma) \varpi^\delta
\end{aligned}$$

$$\begin{aligned}
& + c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} u^\gamma ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \varpi^\delta) \\
& + c^2 \{ (\partial_\kappa u^\lambda) (\partial_\lambda u^\kappa) - (\partial_\lambda u^\lambda) (\partial_\kappa u^\kappa) \} u_\alpha \\
& + (c^2 - 1) \{ u^\kappa \partial_\kappa (u^\lambda \partial_\lambda h) \} u_\alpha \\
& + (c^2 - 1) (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda h) u_\alpha \\
& + 2c^{-1} c_{;h} (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) u_\alpha \\
& - c^2 (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda u_\alpha) + c^2 (\partial_\alpha h) (\partial_\kappa u^\kappa) \\
& + c^2 q (S^\kappa \partial_\kappa u_\alpha) \\
& - c^2 q_{;h} (u^\kappa \partial_\kappa h) S_\alpha + c^2 q (\partial_\alpha u^\kappa) S_\kappa - c^2 q (\partial_\kappa u^\kappa) S_\alpha \\
& + 2c^{-1} c_{;s} (u^\kappa \partial_\kappa h) S_\alpha. \tag{5.14}
\end{aligned}$$

Using (5.10) and (5.14) to substitute for the first and second products on RHS (5.9), and reorganizing the terms, we deduce [where we have added and subtracted $(\partial_\kappa u^\kappa) (\partial_\alpha h)$ on the third and fourth lines of RHS (5.15)]

$$\begin{aligned}
\Box_g u_\alpha & = c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} u^\gamma ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \varpi^\delta) \\
& + (1 - c^2) (u^\kappa \partial_\kappa u_\alpha) (u^\lambda \partial_\lambda h) - c^2 (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda u_\alpha) \\
& + \{ (\partial_\kappa u^\kappa) (\partial_\alpha h) - (\partial_\alpha u^\kappa) (\partial_\kappa h) \} \\
& + (c^2 - 1) (\partial_\kappa u^\kappa) (\partial_\alpha h) + (c^2 - 1) (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda h) u_\alpha \\
& + (c^2 - 1) (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda u_\alpha) \\
& + 2c^{-1} c_{;h} (\partial_\alpha h) (u^\kappa \partial_\kappa h) + 2c^{-1} c_{;h} (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) u_\alpha \\
& + 2c^{-1} c_{;h} (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda u_\alpha) \\
& - c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa h) u^\gamma \varpi^\delta + c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa u^\gamma) \varpi^\delta \\
& + c^2 \{ (\partial_\kappa u^\lambda) (\partial_\lambda u^\kappa) - (\partial_\lambda u^\lambda) (\partial_\kappa u^\kappa) \} u_\alpha \\
& - c^{-1} c_{;h} (g^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda u_\alpha) - c c_{;s} (S^\kappa \partial_\kappa u_\alpha) \\
& + 2c^{-1} c_{;s} (u^\kappa \partial_\kappa h) S_\alpha - q_{;h} (u^\kappa \partial_\kappa h) S_\alpha + c^2 q (\partial_\alpha u^\kappa) S_\kappa \\
& - c^2 q (\partial_\kappa u^\kappa) S_\alpha + q (S^\kappa \partial_\kappa u_\alpha) \\
& + \frac{1}{H} (1 - c^2) q \epsilon_{\alpha\beta\gamma\delta} S^\beta u^\gamma \varpi^\delta + (c^2 - 1) q (S^\kappa u^\lambda \partial_\lambda u_\kappa) u_\alpha. \tag{5.15}
\end{aligned}$$

Next, using (2.13b), we observe the following identity for the two terms on the second line of RHS (5.15):

$$\begin{aligned}
& (1 - c^2) (u^\kappa \partial_\kappa u_\alpha) (u^\lambda \partial_\lambda h) - c^2 (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda u_\alpha) \\
& = -(g^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda u_\alpha). \tag{5.16}
\end{aligned}$$

Moreover, using Eq. (2.22), we see that the terms on the fourth through seventh lines of RHS (5.15) sum to $(c^2 - 1) q (\partial_\kappa u^\kappa) S_\alpha + 2c^{-1} c_{;h} q (u^\kappa \partial_\kappa h) S_\alpha$. In addition, appealing to definition (2.4) with $V_\alpha := \varpi_\alpha$, we obtain the following identity for the first product on RHS (5.15): $c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} u^\gamma ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \varpi^\delta) =$

$-c^2 \frac{1}{H} \text{vort}_\alpha(\varpi)$. From these facts, (5.15), and (5.16), we obtain the following equation:

$$\begin{aligned}
\Box_g u_\alpha = & -c^2 \frac{1}{H} \text{vort}_\alpha(\varpi) \\
& - c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa h) u^\gamma \varpi^\delta + c^2 \frac{1}{H} \epsilon_{\lambda\alpha\gamma\delta} ((\eta^{-1})^{\kappa\lambda} \partial_\kappa u^\gamma) \varpi^\delta \\
& + \{(\partial_\kappa u^\kappa)(\partial_\alpha h) - (\partial_\alpha u^\kappa)(\partial_\kappa h)\} - (g^{-1})^{\kappa\lambda} (\partial_\kappa h)(\partial_\lambda u_\alpha) \\
& + c^2 \{(\partial_\kappa u^\lambda)(\partial_\lambda u^\kappa) - (\partial_\lambda u^\lambda)(\partial_\kappa u^\kappa)\} u_\alpha \\
& - c^{-1} c_{;h} (g^{-1})^{\kappa\lambda} (\partial_\kappa h)(\partial_\lambda u_\alpha) - c c_{;s} (S^\kappa \partial_\kappa u_\alpha) \\
& + 2c^{-1} c_{;s} (u^\kappa \partial_\kappa h) S_\alpha - q_{;h} (u^\kappa \partial_\kappa h) S_\alpha + c^2 q (\partial_\alpha u^\kappa) S_\kappa \\
& + q (S^\kappa \partial_\kappa u_\alpha) + \frac{1}{H} (1 - c^2) q \epsilon_{\alpha\beta\gamma\delta} S^\beta u^\gamma \varpi^\delta \\
& + (c^2 - 1) q (S^\kappa u^\lambda \partial_\lambda u_\kappa) u_\alpha \\
& - q (\partial_\kappa u^\kappa) S_\alpha + 2c^{-1} c_{;h} q (u^\kappa \partial_\kappa h) S_\alpha. \tag{5.17}
\end{aligned}$$

Using definition (2.16a) to express the product $-c^2 \frac{1}{H} \text{vort}_\alpha(\varpi)$ on RHS (5.17) as $-c^2 \frac{1}{H} \mathcal{C}_\alpha + \dots$, reorganizing the terms on the RHS of the resulting identity, and raising the α index with η^{-1} , we arrive at the desired identity (5.8). \square

5.4. Covariant Wave Equation for the Entropy

In this subsection, we derive the covariant wave equation (3.5).

Proposition 5.4 (Covariant wave equation for s). *Assume that (h, s, u^α) is a C^2 solution to (2.17)–(2.19) + (2.20). Then the entropy s verifies the following covariant wave equation:*

$$\Box_g s = c^2 n \mathcal{D} + S^\kappa \partial_\kappa h - c^2 S^\kappa \partial_\kappa h - c c_{;h} S^\kappa \partial_\kappa h - c c_{;s} S_\kappa S^\kappa. \tag{5.18}$$

Proof. Applying (5.1) with $\phi := s$, using (2.13b) to algebraically substitute for the factor of $(g^{-1})^{\kappa\lambda}$ on RHS (5.1), and using the evolution equation (2.19) [which implies that many factors on RHS (5.1) vanish], we deduce, in view of definition (2.8), that

$$\Box_g s = c^2 \partial_\kappa S^\kappa - c c_{;h} S^\kappa \partial_\kappa h - c c_{;s} S_\kappa S^\kappa. \tag{5.19}$$

We then solve for $\partial_\kappa S^\kappa$ in terms of the remaining terms in definition (2.16b) and then use the resulting identity to algebraically substitute for the factor $\partial_\kappa S^\kappa$ in the first product on RHS (5.19), which in total yields the desired Eq. (5.18). \square

6. Transport Equations for the Entropy Gradient and the Modified Divergence of the Entropy

In this section, with the help of the preliminary identities of Lemma 4.1, we derive Eqs. (3.7) and (3.9a). We start by deriving (3.7) (more precisely, its η -dual).

Proposition 6.1 (Transport equation for the entropy gradient). *Assume that (h, s, u^α) is a C^2 solution to (2.17)–(2.19) + (2.20). Then the rectangular components the S_α of the entropy gradient vectorfield (see Definition 2.5) verify the following transport equations:*

$$\begin{aligned} u^\kappa \partial_\kappa S_\alpha &= -S^\kappa \partial_\kappa u_\alpha - \frac{1}{H} \epsilon_{\alpha\beta\gamma\delta} S^\beta u^\gamma \varpi^\delta - (S^\kappa \partial_\kappa h) u_\alpha + q S_\kappa S^\kappa u_\alpha \\ &= -S^\kappa \partial_\kappa u_\alpha - \frac{1}{H} \epsilon_{\alpha\beta\gamma\delta} S^\beta u^\gamma \varpi^\delta + S^\kappa (u^\lambda \partial_\lambda u_\kappa) u_\alpha. \end{aligned} \quad (6.1)$$

Proof. From Eq. (2.24), the identity (4.17), (2.20), and (2.21), we deduce

$$\begin{aligned} u^\kappa \partial_\kappa S_\alpha &= -S^\kappa \partial_\kappa u_\alpha - \frac{1}{H} \epsilon_{\alpha\beta\gamma\delta} S^\beta u^\gamma \varpi^\delta + (\partial_\alpha h) S^\kappa u_\kappa - (S^\kappa \partial_\kappa h) u_\alpha \\ &\quad - q \{ S_\alpha S^\kappa u_\kappa - S^\kappa S_\kappa u_\alpha \} \\ &= -S^\kappa \partial_\kappa u_\alpha - \frac{1}{H} \epsilon_{\alpha\beta\gamma\delta} S^\beta u^\gamma \varpi^\delta - (S^\kappa \partial_\kappa h) u_\alpha + q S^\kappa S_\kappa u_\alpha, \end{aligned} \quad (6.2)$$

which yields the first line of (6.1). To obtain the second line of (6.1) from the first, we use the identity (4.18). \square

We now derive Eq. (3.9a).

Proposition 6.2 (Transport equation for the modified divergence of the entropy). *Assume that (h, s, u^α) is a C^3 solution to (2.17)–(2.19) + (2.20). Then the modified divergence of the entropy gradient \mathcal{D} , which is defined in (2.16b), verifies the following transport equation:*

$$\begin{aligned} u^\kappa \partial_\kappa \mathcal{D} &= \frac{2}{n} \{ (\partial_\kappa S^\kappa) (\partial_\lambda u^\lambda) - (\partial_\lambda S^\kappa) (\partial_\kappa u^\lambda) \} \\ &\quad + \frac{1}{n} c^{-2} u^\kappa \{ (\partial_\kappa h) (\partial_\lambda S^\lambda) - (\partial_\lambda h) (\partial_\kappa S^\lambda) \} \\ &\quad + \frac{1}{n} c^{-2} S^\kappa \{ (\partial_\kappa u^\lambda) (\partial_\lambda h) - (\partial_\lambda u^\lambda) (\partial_\kappa h) \} \\ &\quad + \frac{S_\kappa \mathcal{C}^\kappa}{nH} \\ &\quad + \frac{(1 - c^{-2})}{nH} \epsilon^{\alpha\beta\gamma\delta} S_\alpha u_\beta (\partial_\gamma h) \varpi_\delta + \frac{1}{nH} \epsilon^{\alpha\beta\gamma\delta} S_\alpha (\partial_\beta u_\gamma) \varpi_\delta \\ &\quad + \frac{(\theta - \theta_{;h})}{nH} S^\kappa (S^\lambda \partial_\lambda u_\kappa) - \frac{2q}{n} S^\kappa (S^\lambda \partial_\lambda u_\kappa) \\ &\quad + \frac{(\theta_{;h} - \theta)}{nH} S_\kappa S^\kappa (\partial_\lambda u^\lambda) + \frac{2c^{-1} c_{;s}}{n} S_\kappa S^\kappa (\partial_\lambda u^\lambda) \\ &\quad - \frac{c^2 q_{;h}}{n} S_\kappa S^\kappa (\partial_\lambda u^\lambda) + \frac{q}{n} S_\kappa S^\kappa (\partial_\lambda u^\lambda). \end{aligned} \quad (6.3)$$

Proof. We apply $(\eta^{-1})^{\alpha\lambda} \partial_\lambda$ to Eq. (6.1) [where we use the first equality in (6.1)] and use the evolution equation (2.19) and the identity (4.18) to deduce

$$\begin{aligned} u^\kappa \partial_\kappa \partial_\lambda S^\lambda &= -u^\kappa \partial_\kappa (S^\lambda \partial_\lambda h) - 2(\partial_\lambda S^\kappa) (\partial_\kappa u^\lambda) \\ &\quad - S^\kappa \partial_\kappa \partial_\lambda u^\lambda - (S^\kappa \partial_\kappa h) (\partial_\lambda u^\lambda) \end{aligned}$$

$$\begin{aligned}
& + \frac{1}{H} \epsilon^{\alpha\beta\gamma\delta} (\partial_\alpha h) S_\beta u_\gamma \varpi_\delta - \frac{1}{H} \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma (\partial_\alpha \varpi_\delta) \\
& - \frac{1}{H} \epsilon^{\alpha\beta\gamma\delta} S_\beta (\partial_\alpha u_\gamma) \varpi_\delta \\
& + q_{;h} S_\kappa S^\kappa (u^\lambda \partial_\lambda h) + 2q S^\kappa (u^\lambda \partial_\lambda S_\kappa) + q S_\kappa S^\kappa (\partial_\lambda u^\lambda). \quad (6.4)
\end{aligned}$$

Next, we use the evolution equations (2.17) and (2.19) to rewrite the third product on RHS (6.4) as follows:

$$\begin{aligned}
-S^\kappa \partial_\kappa \partial_\lambda u^\lambda &= S^\kappa \partial_\kappa (c^{-2} u^\lambda \partial_\lambda h) \\
&= c^{-2} (S^\kappa u^\lambda \partial_\lambda \partial_\kappa h) - 2c^{-3} c_{;h} (S^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
&\quad - 2c^{-3} c_{;s} S_\kappa S^\kappa (u^\lambda \partial_\lambda h) + c^{-2} (S^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) \\
&= u^\kappa \partial_\kappa (c^{-2} S^\lambda \partial_\lambda h) + c^{-2} (S^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) - c^{-2} (u^\kappa \partial_\kappa S^\lambda) (\partial_\lambda h) \\
&\quad - 2c^{-3} c_{;s} S_\kappa S^\kappa (u^\lambda \partial_\lambda h). \quad (6.5)
\end{aligned}$$

Next, with the help of the evolution equation (2.17), we decompose the second and third products on RHS (6.5) as follows:

$$\begin{aligned}
c^{-2} (S^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) &= c^{-2} (S^\kappa \partial_\kappa h) (\partial_\lambda u^\lambda) \\
&\quad + c^{-2} \{ (S^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) - (\partial_\lambda u^\lambda) (S^\kappa \partial_\kappa h) \}, \quad (6.6)
\end{aligned}$$

$$\begin{aligned}
-c^{-2} (u^\kappa \partial_\kappa S^\lambda) (\partial_\lambda h) &= -c^{-2} (u^\kappa \partial_\kappa h) (\partial_\lambda S^\lambda) \\
&\quad + c^{-2} \{ (u^\kappa \partial_\kappa h) (\partial_\lambda S^\lambda) - (u^\kappa \partial_\kappa S^\lambda) (\partial_\lambda h) \} \\
&= (\partial_\kappa u^\kappa) (\partial_\lambda S^\lambda) \\
&\quad + c^{-2} \{ (u^\kappa \partial_\kappa h) (\partial_\lambda S^\lambda) - (u^\kappa \partial_\kappa S^\lambda) (\partial_\lambda h) \}. \quad (6.7)
\end{aligned}$$

Using (6.6)–(6.7) to substitute for the second and third products on RHS (6.5) and then using the resulting identity to substitute for the third product on RHS (6.4), we obtain the following equation:

$$\begin{aligned}
& u^\kappa \partial_\kappa \{ \partial_\lambda S^\lambda + S^\lambda \partial_\lambda h - c^{-2} (S^\lambda \partial_\lambda h) \} \\
&= (\partial_\kappa S^\kappa) (\partial_\lambda u^\lambda) - 2(\partial_\lambda S^\kappa) (\partial_\kappa u^\lambda) \\
&\quad - (S^\kappa \partial_\kappa h) (\partial_\lambda u^\lambda) + c^{-2} (S^\kappa \partial_\kappa h) (\partial_\lambda u^\lambda) \\
&\quad + c^{-2} \{ (S^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) - (\partial_\lambda u^\lambda) (S^\kappa \partial_\kappa h) \} \\
&\quad + c^{-2} \{ (u^\kappa \partial_\kappa h) (\partial_\lambda S^\lambda) - (u^\kappa \partial_\kappa S^\lambda) (\partial_\lambda h) \} \\
&\quad + \frac{1}{H} \epsilon^{\alpha\beta\gamma\delta} (\partial_\alpha h) S_\beta u_\gamma \varpi_\delta - \frac{1}{H} \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma (\partial_\alpha \varpi_\delta) - \frac{1}{H} \epsilon^{\alpha\beta\gamma\delta} S_\beta (\partial_\alpha u_\gamma) \varpi_\delta \\
&\quad + q_{;h} S_\kappa S^\kappa (u^\lambda \partial_\lambda h) + 2q S^\kappa (u^\lambda \partial_\lambda S_\kappa) + q S_\kappa S^\kappa (\partial_\lambda u^\lambda) \\
&\quad - 2c^{-3} c_{;s} S_\kappa S^\kappa (u^\lambda \partial_\lambda h). \quad (6.8)
\end{aligned}$$

We now multiply both sides of (6.8) by $1/n$, commute the factor of $1/n$ under the operator $u^\kappa \partial_\kappa$ on LHS (6.8), use Eq. (2.25) (which in particular implies that $u^\kappa \partial_\kappa (1/n) = (1/n) \partial_\kappa u^\kappa$), and use Eq. (2.17) to replace the two factors of

$u^\lambda \partial_\lambda h$ on the last and next-to-last lines of RHS (6.8) with $-c^2 \partial_\lambda u^\lambda$, thereby obtaining the following equation:

$$\begin{aligned}
& u^\kappa \partial_\kappa \left\{ \frac{1}{n} (\partial_\lambda S^\lambda) + \frac{1}{n} (S^\lambda \partial_\lambda h) - \frac{1}{n} c^{-2} (S^\lambda \partial_\lambda h) \right\} \\
&= \frac{2}{n} \left\{ (\partial_\kappa S^\kappa) (\partial_\lambda u^\lambda) - (\partial_\lambda S^\kappa) (\partial_\kappa u^\lambda) \right\} \\
&\quad + \frac{1}{n} c^{-2} \left\{ (S^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) - (\partial_\lambda u^\lambda) (S^\kappa \partial_\kappa h) \right\} \\
&\quad + \frac{1}{n} c^{-2} \left\{ (u^\kappa \partial_\kappa h) (\partial_\lambda S^\lambda) - (\partial_\lambda h) (u^\kappa \partial_\kappa S^\lambda) \right\} \\
&\quad + \frac{1}{nH} \epsilon^{\alpha\beta\gamma\delta} (\partial_\alpha h) S_\beta u_\gamma \varpi_\delta - \frac{1}{nH} \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma (\partial_\alpha \varpi_\delta) \\
&\quad - \frac{1}{nH} \epsilon^{\alpha\beta\gamma\delta} S_\beta (\partial_\alpha u_\gamma) \varpi_\delta \\
&\quad + \frac{2q}{n} S^\kappa (u^\lambda \partial_\lambda S_\kappa) + \frac{2c^{-1} c_{;s}}{n} S_\kappa S^\kappa (\partial_\lambda u^\lambda) - \frac{c^2 q_{;h}}{n} S_\kappa S^\kappa (\partial_\lambda u^\lambda) \\
&\quad + \frac{q}{n} S_\kappa S^\kappa (\partial_\lambda u^\lambda). \tag{6.9}
\end{aligned}$$

Next, we use definitions (2.4) and (2.16a) and the identity (2.21) to obtain the following identity for the second product on the fourth line of RHS (6.9):

$$\begin{aligned}
-\frac{1}{nH} \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma (\partial_\alpha \varpi_\delta) &= -\frac{1}{nH} \epsilon^{\alpha\beta\gamma\delta} S_\alpha u_\beta (\partial_\gamma \varpi_\delta) \\
&= \frac{\mathcal{C}^\kappa S_\kappa}{nH} - \frac{1}{nH} c^{-2} \epsilon^{\alpha\beta\gamma\delta} S_\alpha u_\beta (\partial_\gamma h) \varpi_\delta \\
&\quad + \frac{(\theta_{;h} - \theta)}{nH} S_\kappa S^\kappa (\partial_\lambda u^\lambda) + \frac{(\theta - \theta_{;h})}{nH} S^\kappa (S^\lambda \partial_\lambda u_\kappa). \tag{6.10}
\end{aligned}$$

Using (6.10) to substitute for the second product on the fourth line of RHS (6.9), using (2.24) to express the first product on the next-to-last line of RHS (6.9) as $\frac{2q}{n} S^\kappa (u^\lambda \partial_\lambda S_\kappa) = -\frac{2q}{n} S^\kappa (S^\lambda \partial_\lambda u_\kappa)$, and noting that the terms in parentheses on LHS (6.9) are equal to \mathcal{D} [see (2.16b)], we arrive at the desired evolution equation (6.3). \square

7. Transport Equation for the Vorticity

In this section, with the help of the preliminary identities of Lemma 4.1, we derive Eq. (3.8). We also derive some preliminary identities that, in the next section, we will use when deriving Eq. (3.11b). We collect all of these results in the following proposition.

Proposition 7.1 (Transport equation for the vorticity). *Assume that (h, s, u^α) is a C^3 solution to (2.17)–(2.19) + (2.20). Then the rectangular components ϖ^α of the vorticity vectorfield defined in (2.5) verify the following transport equations:*

$$\begin{aligned} u^\kappa \partial_\kappa \varpi^\alpha &= \varpi^\kappa \partial_\kappa u^\alpha - (\partial_\kappa u^\kappa) \varpi^\alpha - (\varpi^\kappa \partial_\kappa h) u^\alpha \\ &\quad + (\theta - \theta_{;h}) \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) S_\delta + q \varpi^\kappa S_\kappa u^\alpha. \end{aligned} \quad (7.1)$$

Moreover, the following identity holds:

$$\begin{aligned} (\mathcal{L}_u \varpi_b)_\alpha &= \varpi^\kappa \partial_\kappa u_\alpha + \varpi^\kappa (\partial_\alpha u^\kappa) - (\partial_\kappa u^\kappa) \varpi_\alpha + (u^\kappa \partial_\kappa u_\lambda) u_\alpha \varpi^\lambda \\ &\quad + (\theta - \theta_{;h}) \epsilon_\alpha^{\beta\gamma\delta} u_\beta (\partial_\gamma h) S_\delta. \end{aligned} \quad (7.2)$$

In addition, the following identity holds:

$$\begin{aligned} (d\mathcal{L}_u \varpi_b)_{\alpha\beta} &= (\partial_\alpha \varpi^\kappa) (\partial_\kappa u_\beta) - (\partial_\beta \varpi^\kappa) (\partial_\kappa u_\alpha) \\ &\quad + \varpi^\kappa \partial_\kappa \partial_\alpha u_\beta - \varpi^\kappa \partial_\kappa \partial_\beta u_\alpha \\ &\quad + (\partial_\alpha \varpi^\kappa) (\partial_\beta u_\kappa) - (\partial_\beta \varpi^\kappa) (\partial_\alpha u_\kappa) \\ &\quad - (\partial_\alpha \partial_\kappa u^\kappa) \varpi_\beta + (\partial_\beta \partial_\kappa u^\kappa) \varpi_\alpha \\ &\quad - (\partial_\kappa u^\kappa) (\partial_\alpha \varpi_\beta) + (\partial_\kappa u^\kappa) (\partial_\beta \varpi_\alpha) \\ &\quad + (\partial_\alpha u_\beta) \varpi^\lambda (u^\kappa \partial_\kappa u_\lambda) - (\partial_\beta u_\alpha) \varpi^\lambda (u^\kappa \partial_\kappa u_\lambda) \\ &\quad + u_\beta (\partial_\alpha \varpi^\lambda) (u^\kappa \partial_\kappa u_\lambda) - u_\alpha (\partial_\beta \varpi^\lambda) (u^\kappa \partial_\kappa u_\lambda) \\ &\quad + u_\beta \varpi^\lambda (\partial_\alpha u^\kappa) (\partial_\kappa u_\lambda) - u_\alpha \varpi^\lambda (\partial_\beta u^\kappa) (\partial_\kappa u_\lambda) \\ &\quad + u_\beta \varpi^\lambda (u^\kappa \partial_\kappa \partial_\alpha u_\lambda) - u_\alpha \varpi^\lambda (u^\kappa \partial_\kappa \partial_\beta u_\lambda) \\ &\quad + (\theta_h - \theta_{;h;h}) \epsilon_{\beta\kappa}^{\gamma\delta} u^\kappa (\partial_\alpha h) (\partial_\gamma h) S_\delta \\ &\quad + (\theta_{;h;h} - \theta_h) \epsilon_{\alpha\kappa}^{\gamma\delta} u^\kappa (\partial_\beta h) (\partial_\gamma h) S_\delta \\ &\quad + (\theta_{;s} - \theta_{;h;s}) \epsilon_{\beta\kappa}^{\gamma\delta} u^\kappa S_\alpha (\partial_\gamma h) S_\delta + (\theta_{;h;s} - \theta_{;s}) \epsilon_{\alpha\kappa}^{\gamma\delta} u^\kappa S_\beta (\partial_\gamma h) S_\delta \\ &\quad + (\theta - \theta_{;h}) \epsilon_{\beta\kappa}^{\gamma\delta} (\partial_\alpha u^\kappa) (\partial_\gamma h) S_\delta + (\theta_{;h} - \theta) \epsilon_{\alpha\kappa}^{\gamma\delta} (\partial_\beta u^\kappa) (\partial_\gamma h) S_\delta \\ &\quad + (\theta - \theta_{;h}) \epsilon_{\beta\kappa}^{\gamma\delta} u^\kappa (\partial_\alpha \partial_\gamma h) S_\delta + (\theta_{;h} - \theta) \epsilon_{\alpha\kappa}^{\gamma\delta} u^\kappa (\partial_\beta \partial_\gamma h) S_\delta \\ &\quad + (\theta - \theta_{;h}) \epsilon_{\beta\kappa}^{\gamma\delta} u^\kappa (\partial_\gamma h) (\partial_\alpha S_\delta) + (\theta_{;h} - \theta) \epsilon_{\alpha\kappa}^{\gamma\delta} u^\kappa (\partial_\gamma h) (\partial_\beta S_\delta). \end{aligned} \quad (7.3)$$

Finally, the rectangular components $\text{vort}^\alpha(\varpi)$ of the vorticity of the vorticity, which is defined by (2.4) and (2.5), verify the following transport equations:

$$\begin{aligned} u^\kappa \partial_\kappa \text{vort}^\alpha(\varpi) &= \text{vort}^\kappa(\varpi) \partial_\kappa u^\alpha - (\partial_\kappa u^\kappa) \text{vort}^\alpha(\varpi) \\ &\quad + u^\alpha (u^\kappa \partial_\kappa u_\beta) \text{vort}^\beta(\varpi) \\ &\quad + \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \partial_\kappa u^\kappa) \varpi_\delta - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\varpi^\kappa \partial_\kappa \partial_\gamma u_\delta) \\ &\quad + \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (u^\lambda \partial_\lambda \varpi_\delta) u_\gamma + \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) \varpi^\lambda (\partial_\delta u_\lambda) u_\gamma \\ &\quad - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\delta u_\kappa) - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\kappa u_\delta) \\ &\quad + \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\kappa u^\kappa) (\partial_\gamma \varpi_\delta) \\ &\quad - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma u_\delta) \varpi^\lambda (u^\kappa \partial_\kappa u_\lambda) \\ &\quad + (\theta_h - \theta_{;h;h}) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) \end{aligned}$$

$$\begin{aligned}
& + (\theta_h - \theta_{;h;h}) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + (\theta_{;h;h} - \theta_h) u^\alpha (S^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + (\theta_{;h;h} - \theta_h) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (S^\lambda \partial_\lambda h) \\
& + (\theta_{;s} - \theta_{;h;s}) S^\alpha (S^\kappa \partial_\kappa h) + (\theta_{;h;s} - \theta_{;s}) u^\alpha S_\kappa S^\kappa (u^\lambda \partial_\lambda h) \\
& + (\theta_{;h;s} - \theta_{;s}) S_\kappa S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\
& + (\theta - \theta_{;h}) S^\alpha (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda h) + (\theta_{;h} - \theta) (S^\kappa \partial_\kappa u^\alpha) (u^\lambda \partial_\lambda h) \\
& + (\theta - \theta_{;h}) S^\alpha ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h) + (\theta - \theta_{;h}) S^\alpha (u^\kappa u^\lambda \partial_\kappa \partial_\lambda h) \\
& + (\theta_{;h} - \theta) u^\alpha (S^\kappa u^\lambda \partial_\kappa \partial_\lambda h) + (\theta_{;h} - \theta) (\eta^{-1})^{\alpha\lambda} (S^\kappa \partial_\kappa \partial_\lambda h) \\
& + (\theta - \theta_{;h}) (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda S^\alpha) + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda S^\alpha) \\
& + (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa h) (\partial_\lambda S^\lambda) + (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (\partial_\lambda S^\lambda) \\
& + (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) u_\beta (u^\lambda \partial_\lambda S^\beta) \\
& + (\theta - \theta_{;h}) u^\alpha (\eta^{-1})^{\kappa\lambda} \partial_\kappa h) u_\beta (\partial_\lambda S^\beta).
\end{aligned} \tag{7.4}$$

Remark 7.2 Note that RHS (7.4) features some terms that explicitly depend on two derivatives of u , falsely suggesting that there is derivative loss, that is, that $\text{vort}^\alpha(\varpi)$ cannot be more regular than $\partial^2 u$. For this reason, Eq. (7.4) is not suitable for obtaining top-order energy estimates for $\text{vort}^\alpha(\varpi)$. To overcome this difficulty, we will derive a transport-div-curl system for ϖ that does not lose derivatives; see Proposition 8.2.

Proof of Proposition 7.1. We first prove (7.1). From definition (2.5) and the Lie differentiation formula (2.1), we deduce that

$$u^\kappa \partial_\kappa \varpi^\alpha - \varpi^\kappa \partial_\kappa u^\alpha = \mathcal{L}_u \varpi^\alpha = -\frac{1}{2} \mathcal{L}_u \{ \epsilon^{\alpha\beta\gamma\delta} u_\beta (d(Hu_\delta))_{\gamma\delta} \}. \tag{7.5}$$

Using (7.5), the Leibniz rule for Lie derivatives, definition (2.5), (4.11), the first identity in (4.12), (4.14), and (4.16), we compute that

$$\begin{aligned}
u^\kappa \partial_\kappa \varpi^\alpha &= \varpi^\kappa \partial_\kappa u^\alpha - (\partial_\kappa u^\kappa) \varpi^\alpha + (u^\kappa \partial_\kappa u_\lambda) u^\alpha \varpi^\lambda - (u^\kappa \partial_\kappa u_\lambda) u^\lambda \varpi^\alpha \\
&\quad - \theta \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) S_\gamma u_\delta - \theta_{;h} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) S_\delta.
\end{aligned} \tag{7.6}$$

Using (4.3), we see that the fourth product on RHS (7.6) vanishes. Next, we use (2.22) and (4.2) to obtain the following identity for the third product on RHS (7.6): $(u^\kappa \partial_\kappa u_\lambda) u^\alpha \varpi^\lambda = -(\varpi^\kappa \partial_\kappa h) u^\alpha + q \varpi^\kappa S_\kappa u^\alpha$. Next, we use (2.22) to obtain the following identity for the fifth product on RHS (7.6): $-\theta \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) S_\gamma u_\delta = \theta \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta h) S_\gamma u_\delta = \theta \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) S_\delta$. Substituting these two identities for the third and fifth products on RHS (7.6), we arrive at the desired identity (7.1).

Equation (7.2) follows from the Lie derivative identity

$$(\mathcal{L}_u \varpi_\beta)_\alpha = u^\kappa \partial_\kappa \varpi_\alpha + \varpi^\kappa \partial_\alpha u_\kappa$$

[see (2.1)], from using (4.3) to observe the vanishing of the fourth product on RHS (7.6), and from using the identity for the fifth product on RHS (7.6)

proved in the previous paragraph. Equation (7.3) then follows from taking the exterior derivative of Eq. (7.2) and carrying out straightforward computations.

To derive (7.4), we first use definition (2.4) to deduce

$$\mathcal{L}_u \text{vort}^\alpha(\varpi) = -\frac{1}{2} \mathcal{L}_u(\epsilon^{\alpha\beta\gamma\delta} u_\beta (d\varpi_b)_{\gamma\delta}). \quad (7.7)$$

Next, we use (7.7), the Leibniz rule for Lie derivatives, (4.11), the first equality in (4.12), and the standard commutation identity $\mathcal{L}_u d\varpi_b = d\mathcal{L}_u \varpi_b$ to deduce

$$\begin{aligned} \mathcal{L}_u \text{vort}^\alpha(\varpi) &= -(\partial_\kappa u^\kappa) \text{vort}^\alpha(\varpi) - \frac{1}{2} \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (d\varpi_b)_{\gamma\delta} \\ &\quad - \frac{1}{2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (d\mathcal{L}_u \varpi_b)_{\gamma\delta}. \end{aligned} \quad (7.8)$$

Next, using (4.25), we express the second product on RHS (7.8) as follows:

$$\begin{aligned} -\frac{1}{2} \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (d\varpi_b)_{\gamma\delta} &= -\text{vort}^\alpha(\varpi) (u^\kappa \partial_\kappa u_\beta) u^\beta \\ &\quad + u^\alpha (u^\kappa \partial_\kappa u_\beta) \text{vort}^\beta(\varpi) \\ &\quad - \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (u^\lambda \partial_\lambda \varpi_\gamma) u_\delta \\ &\quad + \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (u^\lambda \partial_\gamma \varpi_\lambda) u_\delta. \end{aligned} \quad (7.9)$$

Next, using (4.3), we observe that the first product on RHS (7.9) vanishes. From this fact, the Lie derivative identity $\mathcal{L}_u \text{vort}^\alpha(\varpi) = u^\kappa \partial_\kappa \text{vort}^\alpha(\varpi) - \text{vort}^\kappa(\varpi) \partial_\kappa u^\alpha$ [see (2.1)], (7.8), and (7.9), we deduce

$$\begin{aligned} u^\kappa \partial_\kappa \text{vort}^\alpha(\varpi) &= \text{vort}^\kappa(\varpi) \partial_\kappa u^\alpha - (\partial_\kappa u^\kappa) \text{vort}^\alpha(\varpi) \\ &\quad + u^\alpha (u^\kappa \partial_\kappa u_\beta) \text{vort}^\beta(\varpi) \\ &\quad + \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (u^\lambda \partial_\gamma \varpi_\lambda) u_\delta \\ &\quad - \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (u^\lambda \partial_\lambda \varpi_\gamma) u_\delta \\ &\quad - \frac{1}{2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (d\mathcal{L}_u \varpi_b)_{\gamma\delta}. \end{aligned} \quad (7.10)$$

Next, we use (4.5) and the antisymmetry of $\epsilon^{\cdots\cdots}$ to express the product on the third line of RHS (7.10) as

$$\epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (u^\lambda \partial_\gamma \varpi_\lambda) u_\delta = \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) \varpi^\lambda (\partial_\delta u_\lambda) u_\gamma,$$

use the antisymmetry of $\epsilon^{\cdots\cdots}$ to express the product on the fourth line of RHS (7.10)

$$-\epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (u^\lambda \partial_\lambda \varpi_\gamma) u_\delta = \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (u^\lambda \partial_\lambda \varpi_\delta) u_\gamma,$$

use (7.3) to substitute for the factor $(d\mathcal{L}_u \varpi_b)_{\gamma\delta}$ in the last product on RHS (7.10), and carry out straightforward computations, thereby deducing that

$$\begin{aligned} u^\kappa \partial_\kappa \text{vort}^\alpha(\varpi) &= \text{vort}^\kappa(\varpi) \partial_\kappa u^\alpha - (\partial_\kappa u^\kappa) \text{vort}^\alpha(\varpi) \\ &\quad + u^\alpha (u^\kappa \partial_\kappa u_\beta) \text{vort}^\beta(\varpi) \\ &\quad + \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \partial_\kappa u^\kappa) \varpi_\delta - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\varpi^\kappa \partial_\kappa \partial_\gamma u_\delta) \end{aligned}$$

$$\begin{aligned}
& + \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (u^\lambda \partial_\lambda \varpi_\delta) u_\gamma \\
& + \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) \varpi^\lambda (\partial_\delta u_\lambda) u_\gamma \\
& - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\delta u_\kappa) - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\kappa u_\delta) \\
& + \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\kappa u^\kappa) (\partial_\gamma \varpi_\delta) \\
& - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma u_\delta) \varpi^\lambda (u^\kappa \partial_\kappa u_\lambda) \\
& + (\theta_{;h} - \theta_h) \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\kappa}^{\mu\nu} u_\beta u^\kappa (\partial_\gamma h) (\partial_\mu h) S_\nu \\
& + (\theta_{;h;s} - \theta_{;s}) \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\kappa}^{\mu\nu} u_\beta u^\kappa S_\gamma (\partial_\mu h) S_\nu \\
& + (\theta_{;h} - \theta) \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\kappa}^{\mu\nu} u_\beta (\partial_\gamma u^\kappa) (\partial_\mu h) S_\nu \\
& + (\theta_{;h} - \theta) \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\kappa}^{\mu\nu} u_\beta u^\kappa (\partial_\gamma \partial_\mu h) S_\nu \\
& + (\theta_{;h} - \theta) \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\kappa}^{\mu\nu} u_\beta u^\kappa (\partial_\mu h) (\partial_\gamma S_\nu). \tag{7.11}
\end{aligned}$$

Finally, we use the identity

$$\begin{aligned}
\epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\kappa}^{\mu\nu} &= (\eta^{-1})^{\nu\alpha} \delta_\kappa^\beta (\eta^{-1})^{\mu\gamma} - (\eta^{-1})^{\nu\alpha} \delta_\kappa^\gamma (\eta^{-1})^{\mu\beta} \\
&+ (\eta^{-1})^{\nu\gamma} \delta_\kappa^\alpha (\eta^{-1})^{\mu\beta} - (\eta^{-1})^{\nu\gamma} \delta_\kappa^\beta (\eta^{-1})^{\mu\alpha} \\
&+ (\eta^{-1})^{\nu\beta} \delta_\kappa^\gamma (\eta^{-1})^{\mu\alpha} - (\eta^{-1})^{\nu\beta} \delta_\kappa^\alpha (\eta^{-1})^{\mu\gamma}
\end{aligned}$$

to substitute for the five products $\epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\kappa}^{\mu\nu}$ on RHS (7.11). Also using (2.20), (2.21), and (4.3), we arrive at the desired identity (7.4). \square

8. The Transport-div-curl System for the Vorticity

Our main goal in this section is to derive Eqs. (3.11a) and (3.11b). We accomplish this in Proposition 8.2. Before proving the proposition, we will first establish some preliminary identities.

8.1. Preliminary Identities

In the next lemma, we derive a large collection of identities that we will use in deriving the transport equation verified by the vectorfield \mathcal{C}^α defined in (2.16a).

Lemma 8.1 (Identification of the null structure of some terms tied to the transport-div-curl system for the vorticity). *Assume that (h, s, u^α) is a C^2 solution to (2.17)–(2.19) + (2.20). Then the following identities hold for some of the terms on the third through seventh lines of RHS (7.4):*

$$\begin{aligned}
\epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \partial_\kappa u^\kappa) \varpi_\delta &= -u^\kappa \partial_\kappa \{ c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \} \\
&- 2(\partial_\kappa u^\kappa) c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \\
&+ c^{-2} \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (\partial_\gamma h) \varpi_\delta \\
&+ c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi^\kappa (\partial_\delta u_\kappa) \\
&+ c^{-2} (\theta - \theta_{;h}) (S^\kappa \partial_\kappa h) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\
&+ c^{-2} (\theta - \theta_{;h}) u^\alpha (S^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
&+ c^{-2} (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h)
\end{aligned}$$

$$\begin{aligned}
& + c^{-2}(\theta_{;h} - \theta)S^\alpha(\eta^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda h) \\
& + c^{-2}\epsilon^{\alpha\beta\gamma\delta}u_\beta\{(\partial_\kappa u^\kappa)(\partial_\gamma h) - (\partial_\gamma u^\kappa)(\partial_\kappa h)\}\varpi_\delta \\
& + 2c^{-3}c_{;s}(u^\kappa\partial_\kappa h)\epsilon^{\alpha\beta\gamma\delta}u_\beta S_\gamma\varpi_\delta,
\end{aligned} \tag{8.1a}$$

$$\begin{aligned}
-\epsilon^{\alpha\beta\gamma\delta}u_\beta(\varpi^\kappa\partial_\kappa\partial_\gamma u_\delta) &= \frac{1}{H}(\varpi^\kappa\partial_\kappa\varpi^\alpha) - \frac{1}{H}\varpi^\alpha(\varpi^\kappa\partial_\kappa h) \\
& - \frac{1}{H}u^\alpha\varpi^\lambda(\varpi^\kappa\partial_\kappa u_\lambda) + \epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma h)\varpi^\kappa(\partial_\delta u_\kappa) \\
& - q\epsilon^{\alpha\beta\gamma\delta}u_\beta S_\gamma\varpi^\kappa(\partial_\delta u_\kappa),
\end{aligned} \tag{8.1b}$$

$$\begin{aligned}
\epsilon^{\alpha\beta\gamma\delta}(u^\kappa\partial_\kappa u_\beta)(u^\lambda\partial_\lambda\varpi_\delta)u_\gamma &= -\epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)u_\gamma\varpi^\kappa(\partial_\delta u_\kappa) \\
& + (\partial_\kappa u^\kappa)\epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)u_\gamma\varpi_\delta \\
& + (\theta - \theta_{;h})((\eta^{-1})^{\alpha\kappa}\partial_\kappa h)(S^\lambda\partial_\lambda h) \\
& + (\theta - \theta_{;h})u^\alpha(u^\kappa\partial_\kappa h)(S^\lambda\partial_\lambda h) \\
& + (\theta_{;h} - \theta)S^\alpha(u^\kappa\partial_\kappa h)(u^\lambda\partial_\lambda h) \\
& + (\theta_{;h} - \theta)S^\alpha(\eta^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda h) \\
& + q\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma\varpi^\kappa(\partial_\delta u_\kappa) \\
& - q(\partial_\kappa u^\kappa)\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma\varpi_\delta \\
& + q(\theta_{;h} - \theta)((\eta^{-1})^{\kappa\alpha}\partial_\kappa h)S^\lambda S_\lambda \\
& + q(\theta_{;h} - \theta)u^\alpha(u^\kappa\partial_\kappa h)S^\lambda S_\lambda \\
& + q(\theta - \theta_{;h})S^\alpha(S^\kappa\partial_\kappa h),
\end{aligned} \tag{8.1c}$$

$$\begin{aligned}
\epsilon^{\alpha\beta\gamma\delta}(u^\kappa\partial_\kappa u_\beta)u_\gamma\varpi^\lambda(\partial_\delta u_\lambda) &= -\epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)u_\gamma\varpi^\lambda(\partial_\delta u_\lambda) \\
& + q\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma\varpi^\lambda(\partial_\delta u_\lambda),
\end{aligned} \tag{8.1d}$$

$$\begin{aligned}
-\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma\varpi^\kappa)(\partial_\kappa u_\delta) &= -\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma\varpi^\kappa)(\partial_\delta u_\kappa) \\
& - \epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma h)\varpi^\kappa(\partial_\delta u_\kappa) \\
& - \frac{1}{H}(\varpi^\kappa\partial_\kappa\varpi^\alpha) + \frac{1}{H}\varpi^\alpha(\partial_\kappa\varpi^\kappa) \\
& - \frac{1}{H}\varpi^\alpha\varpi^\lambda(u^\kappa\partial_\kappa u_\lambda) + \frac{1}{H}u^\alpha\varpi^\lambda(\varpi^\kappa\partial_\kappa u_\lambda) \\
& - q\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma u^\kappa)\varpi_\kappa S_\delta,
\end{aligned} \tag{8.1e}$$

$$\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\kappa u^\kappa)(\partial_\gamma\varpi_\delta) = -(\partial_\kappa u^\kappa)\text{vort}^\alpha(\varpi), \tag{8.1f}$$

$$-\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma u_\delta)\varpi^\lambda(u^\kappa\partial_\kappa u_\lambda) = \frac{1}{H}\varpi^\alpha\varpi^\lambda(u^\kappa\partial_\kappa u_\lambda). \tag{8.1g}$$

Moreover, we have

$$\begin{aligned}
& (\theta - \theta_{;h})S^\alpha((\eta^{-1})^{\kappa\lambda}\partial_\kappa\partial_\lambda h) + (\theta - \theta_{;h})S^\alpha(u^\kappa u^\lambda\partial_\kappa\partial_\lambda h) \\
& = u^\kappa\partial_\kappa\{(\theta_{;h} - \theta)S^\alpha(\partial_\lambda u^\lambda)\} \\
& + (\theta_{;h} - \theta_{;h;h})S^\alpha(u^\kappa\partial_\kappa h)(\partial_\lambda u^\lambda) + (\theta - \theta_{;h})(u^\kappa\partial_\kappa S^\alpha)(\partial_\lambda u^\lambda)
\end{aligned}$$

$$\begin{aligned}
& + (\theta_{;h} - \theta) S^\alpha (\partial_\kappa u^\lambda) (\partial_\lambda u^\kappa) + (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) \\
& + (\theta_{;h} - \theta) S^\alpha (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda h) \\
& + (\theta - \theta_{;h}) q S^\alpha (\partial_\kappa S^\kappa) + (\theta - \theta_{;h}) q_{;h} S^\alpha (S^\kappa \partial_\kappa h) + (\theta - \theta_{;h}) q_{;s} S^\alpha S_\kappa S^\kappa,
\end{aligned} \tag{8.2a}$$

$$\begin{aligned}
(\theta_{;h} - \theta) u^\alpha (S^\kappa u^\lambda \partial_\kappa \partial_\lambda h) & = u^\kappa \partial_\kappa \{ (\theta_{;h} - \theta) u^\alpha (S^\lambda \partial_\lambda h) \} \\
& + (\theta_h - \theta_{;h;h}) u^\alpha (u^\kappa \partial_\kappa h) (S^\lambda \partial_\lambda h) \\
& + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa u^\alpha) (S^\lambda \partial_\lambda h) \\
& + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa S^\lambda) (\partial_\lambda h),
\end{aligned} \tag{8.2b}$$

$$\begin{aligned}
(\theta_{;h} - \theta) (\eta^{-1})^{\alpha\lambda} (S^\kappa \partial_\kappa \partial_\lambda h) & = u^\kappa \partial_\kappa \{ (\theta - \theta_{;h}) (\eta^{-1})^{\alpha\lambda} S^\beta (\partial_\lambda u_\beta) \} \\
& + (\theta_{;h;h} - \theta_h) (u^\kappa \partial_\kappa h) (\eta^{-1})^{\alpha\lambda} S^\beta (\partial_\lambda u_\beta) \\
& + (\theta_{;h} - \theta) (u^\kappa \partial_\kappa S^\beta) (\eta^{-1})^{\alpha\lambda} (\partial_\lambda u_\beta) \\
& + (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) (u^\kappa \partial_\kappa h) \\
& + (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\kappa) (\partial_\kappa u_\beta) \\
& + (\theta - \theta_{;h}) q ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\beta) S_\beta \\
& + (\theta_{;h} - \theta) q_{;h} ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) S_\kappa S^\kappa \\
& + (\theta_{;h} - \theta) q_{;s} S^\alpha S_\kappa S^\kappa \\
& + 2(\theta_{;h} - \theta) q ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\kappa) S_\kappa.
\end{aligned} \tag{8.2c}$$

Identities that reveal null-form structure and cancellations. The following identities hold²⁵:

$$\begin{aligned}
\mathcal{Q}_2 & := (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) \partial_\lambda S^\lambda + (\theta - \theta_{;h}) (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda S^\alpha) \\
& = (\theta_{;h} - \theta) (\eta^{-1})^{\alpha\kappa} \{ (\partial_\kappa h) (\partial_\lambda S^\lambda) - (\partial_\lambda h) (\partial_\kappa S^\lambda) \},
\end{aligned} \tag{8.3a}$$

$$\begin{aligned}
\mathcal{Q}_4 & := (\theta_h - \theta_{;h;h}) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) \\
& + (\theta_h - \theta_{;h;h}) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) + (\theta_h - \theta_{;h;h}) S^\alpha (u^\kappa \partial_\kappa h) (\partial_\lambda u^\lambda) \\
& = c^{-2} (\theta_h - \theta_{;h;h}) S^\alpha (g^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h),
\end{aligned} \tag{8.3b}$$

$$\begin{aligned}
\mathcal{Q}_5 & := (\theta_{;h;h} - \theta_h) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (S^\lambda \partial_\lambda h) \\
& + (\theta_{;h;h} - \theta_h) (u^\kappa \partial_\kappa h) (\eta^{-1})^{\alpha\lambda} S^\beta (\partial_\lambda u_\beta) \\
& = (\theta_{;h;h} - \theta_h) S^\beta u^\kappa (\eta^{-1})^{\alpha\lambda} \{ (\partial_\kappa h) (\partial_\lambda u_\beta) - (\partial_\lambda h) (\partial_\kappa u_\beta) \} \\
& + (\theta_{;h;h} - \theta_h) q ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) S^\lambda S_\lambda,
\end{aligned} \tag{8.3c}$$

$$\begin{aligned}
\mathcal{Q}_6 & := c^{-2} (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + c^{-2} (\theta_{;h} - \theta) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) + (\theta - \theta_{;h}) S^\alpha (\partial_\kappa u^\kappa) (\partial_\lambda u^\lambda) \\
& = c^{-4} (\theta_{;h} - \theta) S^\alpha (g^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h),
\end{aligned} \tag{8.3d}$$

²⁵Our labeling of the terms \mathcal{Q}_2 , \mathcal{Q}_3 , etc. is tied to the order in which terms appear in our proof of (8.41).

$$\begin{aligned}
\mathcal{Q}_7 &:= (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) + (\theta_{;h} - \theta) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) \\
&\quad + (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) \\
&= (\theta_{;h} - \theta) q S^\alpha (S^\kappa \partial_\kappa h),
\end{aligned} \tag{8.3e}$$

$$\begin{aligned}
\mathcal{Q}_9 &:= (\theta_{;h} - \theta) (S^\kappa \partial_\kappa u^\alpha) (\partial_\lambda u^\lambda) + (\theta_{;h} - \theta) (u^\kappa \partial_\kappa u^\alpha) (S^\lambda \partial_\lambda h) \\
&\quad + (\theta - \theta_{;h}) ((\eta^{-1})^{\kappa\lambda} \partial_\kappa u^\alpha) S^\beta (\partial_\lambda u_\beta) \\
&= (\theta_{;h} - \theta) S^\kappa \{ (\partial_\kappa u^\alpha) (\partial_\lambda u^\lambda) - (\partial_\lambda u^\alpha) (\partial_\kappa u^\lambda) \} \\
&\quad + \frac{1}{H} (\theta - \theta_{;h}) \epsilon^{\kappa\beta\gamma\delta} (\partial_\kappa u^\alpha) S_\beta u_\gamma \varpi_\delta + q (\theta_{;h} - \theta) (u^\kappa \partial_\kappa u^\alpha) S^\lambda S_\lambda,
\end{aligned} \tag{8.3f}$$

$$\begin{aligned}
\mathcal{Q}_{11} &:= (\theta - \theta_{;h}) (u^\kappa \partial_\kappa S^\alpha) (\partial_\lambda u^\lambda) + (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\kappa) (\partial_\kappa u_\beta) \\
&= (\theta_{;h} - \theta) S^\beta (\eta^{-1})^{\alpha\kappa} \{ (\partial_\kappa u_\beta) (\partial_\lambda u^\lambda) - (\partial_\lambda u_\beta) (\partial_\kappa u^\lambda) \},
\end{aligned} \tag{8.3g}$$

$$\begin{aligned}
\mathcal{Q}_{12} &:= 2(\theta_{;h} - \theta) (\partial_\kappa u^\kappa) (\eta^{-1})^{\alpha\lambda} S^\beta (\partial_\lambda u_\beta) \\
&\quad + c^{-2} (\theta - \theta_{;h}) (S^\kappa \partial_\kappa h) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\
&\quad + (\theta_{;h} - \theta) (u^\kappa \partial_\kappa S^\beta) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\
&= (\theta_{;h} - \theta) (\eta^{-1})^{\alpha\kappa} S^\beta \{ (\partial_\kappa u_\beta) (\partial_\lambda u^\lambda) - (\partial_\lambda u_\beta) (\partial_\kappa u^\lambda) \} \\
&\quad + c^{-2} (\theta_{;h} - \theta) (\eta^{-1})^{\alpha\kappa} S^\beta u^\lambda \{ (\partial_\lambda u_\beta) (\partial_\kappa h) - (\partial_\kappa u_\beta) (\partial_\lambda h) \} \\
&\quad + qc^{-2} (\theta - \theta_{;h}) S_\kappa S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h),
\end{aligned} \tag{8.3h}$$

$$\begin{aligned}
\mathcal{Q}_{13} &:= (\theta - \theta_{;h}) u^\alpha (\partial_\kappa u^\kappa) (S^\lambda \partial_\lambda h) + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa u^\lambda) S^\beta (\partial_\lambda u_\beta) \\
&= (\theta_{;h} - \theta) u^\alpha S^\beta u^\lambda \{ (\partial_\kappa u^\kappa) (\partial_\lambda u_\beta) - (\partial_\lambda u^\kappa) (\partial_\kappa u_\beta) \} \\
&\quad + q (\theta - \theta_{;h}) u^\alpha S_\kappa S^\kappa (\partial_\lambda u^\lambda),
\end{aligned} \tag{8.3i}$$

$$\begin{aligned}
\mathcal{Q}_{14} &:= (\theta - \theta_{;h}) u^\alpha (\partial_\kappa u^\kappa) (S^\lambda \partial_\lambda h) + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa h) (S^\lambda \partial_\lambda h) \\
&\quad + (\theta - \theta_{;h}) u^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) u_\beta (\partial_\lambda S^\beta) \\
&= n (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa h) \mathcal{D} \\
&\quad + (\theta_{;h} - \theta) u^\alpha u^\kappa \{ (\partial_\kappa h) (\partial_\lambda S^\lambda) - (\partial_\lambda h) (\partial_\kappa S^\lambda) \},
\end{aligned} \tag{8.3j}$$

$$\begin{aligned}
\mathcal{Q}_{15} &:= (\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta h) u_\gamma \varpi_\delta + c^{-2} \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (\partial_\gamma h) \varpi_\delta \\
&= c^{-2} q \epsilon^{\alpha\beta\gamma\delta} S_\beta (\partial_\gamma h) \varpi_\delta,
\end{aligned} \tag{8.3k}$$

$$\begin{aligned}
\mathcal{Q}_{16} &:= -c^{-2} u^\alpha \epsilon^{\sigma\beta\gamma\delta} (u^\kappa \partial_\kappa u_\sigma) u_\beta (\partial_\gamma h) \varpi_\delta \\
&= -c^{-2} q u^\alpha \epsilon^{\kappa\beta\gamma\delta} S_\kappa u_\beta (\partial_\gamma h) \varpi_\delta,
\end{aligned} \tag{8.3l}$$

$$\begin{aligned}
\mathcal{Q}_{18} &:= (\theta - \theta_{;h}) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (S^\lambda \partial_\lambda h) \\
&\quad + (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) u_\beta (u^\lambda \partial_\lambda S^\beta) \\
&= q (\theta - \theta_{;h}) S_\kappa S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h),
\end{aligned} \tag{8.3m}$$

$$\begin{aligned}
\mathcal{Q}_{19} &:= (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa u_\sigma) S^\sigma (\partial_\lambda u^\lambda) \\
&\quad + c^{-2} (\theta - \theta_{;h}) u^\alpha (S^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
&= q (\theta_{;h} - \theta) u^\alpha S_\kappa S^\kappa (\partial_\lambda u^\lambda),
\end{aligned} \tag{8.3n}$$

$$\begin{aligned}\mathcal{D}_{20} &:= (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) (u^\kappa \partial_\kappa h) \\ &\quad + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda S^\alpha) \\ &= 0,\end{aligned}\tag{8.3o}$$

$$\begin{aligned}\mathcal{D}_{21} &:= (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa u_\beta) u^\beta (S^\lambda \partial_\lambda h) \\ &= 0.\end{aligned}\tag{8.3p}$$

Proof. We split the proof into many pieces.

- **Proof of (8.1a):** We first use Eq. (2.17) to deduce

$$\begin{aligned}\epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \partial_\kappa u^\kappa) \varpi_\delta &= -\epsilon^{\alpha\beta\gamma\delta} u_\beta \{ \partial_\gamma (c^{-2} u^\kappa \partial_\kappa h) \} \varpi_\delta \\ &= -\epsilon^{\alpha\beta\gamma\delta} u_\beta (c^{-2} u^\kappa \partial_\kappa \partial_\gamma h) \varpi_\delta \\ &\quad + 2c^{-3} c_{;h} (u^\kappa \partial_\kappa h) \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \\ &\quad + 2c^{-3} c_{;s} (u^\kappa \partial_\kappa h) \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi_\delta \\ &\quad - c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma u^\kappa) (\partial_\kappa h) \varpi_\delta.\end{aligned}\tag{8.4}$$

Next, we rewrite the first term on RHS (8.4) as a perfect $u^\kappa \partial_\kappa$ derivative plus error terms, thereby obtaining, with the help of (2.19), the following identity:

$$\begin{aligned}\epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \partial_\kappa u^\kappa) \varpi_\delta &= -u^\kappa \partial_\kappa \{ \epsilon^{\alpha\beta\gamma\delta} c^{-2} u_\beta (\partial_\gamma h) \varpi_\delta \} \\ &\quad + c^{-2} \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (\partial_\gamma h) \varpi_\delta \\ &\quad + c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) (u^\kappa \partial_\kappa \varpi_\delta) \\ &\quad - c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma u^\kappa) (\partial_\kappa h) \varpi_\delta \\ &\quad + 2c^{-3} c_{;s} (u^\kappa \partial_\kappa h) \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi_\delta.\end{aligned}\tag{8.5}$$

Using Eq. (7.1) to substitute for the factor $u^\kappa \partial_\kappa \varpi_\delta$ in the third product on RHS (8.5), we deduce

$$\begin{aligned}\epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \partial_\kappa u^\kappa) \varpi_\delta &= -u^\kappa \partial_\kappa \{ c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \} \\ &\quad + c^{-2} \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (\partial_\gamma h) \varpi_\delta \\ &\quad + c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) (\varpi^\kappa \partial_\kappa u_\delta) \\ &\quad - c^{-2} (\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \\ &\quad + c^{-2} (\theta - \theta_{;h}) \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\nu}^{\quad \kappa\lambda} u_\beta u^\nu (\partial_\gamma h) (\partial_\kappa h) S_\lambda \\ &\quad - c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma u^\kappa) (\partial_\kappa h) \varpi_\delta \\ &\quad + 2c^{-3} c_{;s} (u^\kappa \partial_\kappa h) \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi_\delta.\end{aligned}\tag{8.6}$$

Next, using the identity (4.21), we express the third product on RHS (8.6) as follows:

$$c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) (\varpi^\kappa \partial_\kappa u_\delta) = c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi^\kappa (\partial_\delta u_\kappa).\tag{8.7}$$

Next, using the identity

$$\begin{aligned} -\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\delta\nu}^{\kappa\lambda} &= (\eta^{-1})^{\lambda\beta}\delta_\nu^\alpha(\eta^{-1})^{\kappa\gamma} - (\eta^{-1})^{\lambda\beta}\delta_\nu^\gamma(\eta^{-1})^{\kappa\alpha} \\ &\quad + (\eta^{-1})^{\lambda\gamma}\delta_\nu^\beta(\eta^{-1})^{\kappa\alpha} - (\eta^{-1})^{\lambda\gamma}\delta_\nu^\alpha(\eta^{-1})^{\kappa\beta} \\ &\quad + (\eta^{-1})^{\lambda\alpha}\delta_\nu^\gamma(\eta^{-1})^{\kappa\beta} - (\eta^{-1})^{\lambda\alpha}\delta_\nu^\beta(\eta^{-1})^{\kappa\gamma} \end{aligned}$$

and Eqs. (2.20), (2.21), and (4.2), we express the third-from-last product on RHS (8.6) as follows:

$$\begin{aligned} c^{-2}(\theta - \theta_{;h})\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\delta\nu}^{\kappa\lambda}u_\beta u^\nu(\partial_\gamma h)(\partial_\kappa h)S_\lambda \\ = c^{-2}(\theta - \theta_{;h})(S^\kappa\partial_\kappa h)((\eta^{-1})^{\alpha\lambda}\partial_\lambda h) \\ + c^{-2}(\theta - \theta_{;h})u^\alpha(S^\kappa\partial_\kappa h)(u^\lambda\partial_\lambda h) \\ + c^{-2}(\theta_{;h} - \theta)S^\alpha(u^\kappa\partial_\kappa h)(u^\lambda\partial_\lambda h) \\ + c^{-2}(\theta_{;h} - \theta)S^\alpha(\eta^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda h). \end{aligned} \quad (8.8)$$

Using (8.7) and (8.8) to substitute for the relevant products on RHS (8.6), adding and subtracting $c^{-2}\epsilon^{\alpha\beta\gamma\delta}u_\beta\varpi_\delta(\partial_\kappa u^\kappa)(\partial_\gamma h)$, and reorganizing the terms, we arrive at the desired identity (8.1a).

• **Proof of (8.1b):** We first use (4.22) to deduce

$$\begin{aligned} \epsilon^{\alpha\beta\gamma\delta}u_\beta(\varpi^\kappa\partial_\kappa\partial_\gamma u_\delta) \\ = u_\beta\varpi^\kappa\partial_\kappa\left\{\frac{1}{H}\varpi^\alpha u^\beta - \frac{1}{H}u^\alpha\varpi^\beta - \epsilon^{\alpha\beta\gamma\delta}(\partial_\gamma h)u_\delta + q\epsilon^{\alpha\beta\gamma\delta}S_\gamma u_\delta\right\}. \end{aligned} \quad (8.9)$$

The desired identity (8.1b) now follows from (2.6), (2.20), (4.2), (4.3), (4.5), (4.21), (8.9), and straightforward calculations.

• **Proof of (8.1c):** We first use Eq. (2.22) to substitute for the factor $u^\kappa\partial_\kappa u_\beta$ on LHS (8.1c), thereby obtaining the identity

$$\begin{aligned} \epsilon^{\alpha\beta\gamma\delta}(u^\kappa\partial_\kappa u_\beta)(u^\lambda\partial_\lambda\varpi_\delta)u_\gamma &= -\epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)(u^\lambda\partial_\lambda\varpi_\delta)u_\gamma \\ &\quad + q\epsilon^{\alpha\beta\gamma\delta}S_\beta(u^\lambda\partial_\lambda\varpi_\delta)u_\gamma. \end{aligned} \quad (8.10)$$

We then use Eq. (7.1) to substitute for the two factors of $u^\lambda\partial_\lambda\varpi_\delta$ on RHS (8.10), which yields the identity

$$\begin{aligned} \epsilon^{\alpha\beta\gamma\delta}(u^\kappa\partial_\kappa u_\beta)(u^\lambda\partial_\lambda\varpi_\delta)u_\gamma &= -\epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)u_\gamma(\varpi^\kappa\partial_\kappa u_\delta) \\ &\quad + (\partial_\kappa u^\kappa)\epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)u_\gamma\varpi_\delta \\ &\quad + (\theta_{;h} - \theta)\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\delta\nu}^{\kappa\lambda}(\partial_\beta h)u^\nu(\partial_\kappa h)S_\lambda u_\gamma \\ &\quad + q\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma(\varpi^\kappa\partial_\kappa u_\delta) \\ &\quad - q(\partial_\kappa u^\kappa)\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma\varpi_\delta \\ &\quad + q(\theta - \theta_{;h})\epsilon^{\alpha\beta\gamma\delta}\epsilon_{\delta\nu}^{\kappa\lambda}u^\nu(\partial_\kappa h)S_\lambda S_\beta u_\gamma. \end{aligned} \quad (8.11)$$

Next, we use the identity (4.21) to express the first and fourth products on RHS (8.11) as follows:

$$-\epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)(\varpi^\lambda\partial_\lambda u_\delta)u_\gamma = -\epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)\varpi^\lambda(\partial_\delta u_\lambda)u_\gamma, \quad (8.12)$$

$$q\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma(\varpi^\kappa \partial_\kappa u_\delta) = q\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma \varpi^\kappa (\partial_\delta u_\kappa). \quad (8.13)$$

We then use the identity

$$\begin{aligned} \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\nu}^{\kappa\lambda} &= (\eta^{-1})^{\lambda\beta} \delta_\nu^\gamma (\eta^{-1})^{\kappa\alpha} - (\eta^{-1})^{\lambda\beta} \delta_\nu^\alpha (\eta^{-1})^{\kappa\gamma} \\ &\quad + (\eta^{-1})^{\lambda\gamma} \delta_\nu^\alpha (\eta^{-1})^{\kappa\beta} - (\eta^{-1})^{\lambda\gamma} \delta_\nu^\beta (\eta^{-1})^{\kappa\alpha} \\ &\quad + (\eta^{-1})^{\lambda\alpha} \delta_\nu^\beta (\eta^{-1})^{\kappa\gamma} - (\eta^{-1})^{\lambda\alpha} \delta_\nu^\gamma (\eta^{-1})^{\kappa\beta} \end{aligned}$$

and Eqs. (2.20) and (2.21) to express the third product on RHS (8.11) as follows:

$$\begin{aligned} &(\theta_{;h} - \theta) \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\nu}^{\kappa\lambda} (\partial_\beta h) u^\nu (\partial_\kappa h) S_\lambda u_\gamma \\ &= (\theta - \theta_{;h}) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (S^\lambda \partial_\lambda h) \\ &\quad + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa h) (S^\lambda \partial_\lambda h) \\ &\quad + (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\ &\quad + (\theta_{;h} - \theta) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h). \end{aligned} \quad (8.14)$$

Similarly, we express the last product on RHS (8.11) as follows:

$$\begin{aligned} q(\theta - \theta_{;h}) \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\delta\nu}^{\kappa\lambda} u^\nu (\partial_\kappa h) S_\lambda S_\beta u_\gamma &= q(\theta_{;h} - \theta) ((\eta^{-1})^{\kappa\alpha} \partial_\kappa h) S^\lambda S_\lambda \\ &\quad + q(\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa h) S^\lambda S_\lambda \\ &\quad + q(\theta - \theta_{;h}) S^\alpha (S^\kappa \partial_\kappa h). \end{aligned} \quad (8.15)$$

Using (8.12)–(8.13) and (8.14)–(8.15) to substitute for the relevant products on RHS (8.11), we arrive at the desired identity (8.1c).

• **Proof of (8.1d):** (8.1d) follows easily from using Eq. (2.22) to substitute for the factor $u^\kappa \partial_\kappa u_\beta$ on the LHS.

• **Proof of (8.1e):** We first use the identity (4.17) to deduce

$$\begin{aligned} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\kappa u_\delta) &= \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\delta u_\kappa) \\ &\quad + \frac{1}{H} \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\kappa\delta\theta\lambda} u^\theta \varpi^\lambda u_\beta (\partial_\gamma \varpi^\kappa) \\ &\quad + \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) u_\kappa (\partial_\delta h) - q \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) u_\kappa S_\delta. \end{aligned} \quad (8.16)$$

Next, we note the identity

$$\begin{aligned} \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\kappa\delta\theta\lambda} &= -\epsilon^{\alpha\beta\gamma\delta} \epsilon_{\kappa\lambda\theta\delta} = \delta_\kappa^\alpha \delta_\lambda^\beta \delta_\theta^\gamma - \delta_\kappa^\beta \delta_\lambda^\alpha \delta_\theta^\gamma \\ &\quad + \delta_\kappa^\beta \delta_\lambda^\gamma \delta_\theta^\alpha - \delta_\kappa^\alpha \delta_\lambda^\gamma \delta_\theta^\beta + \delta_\kappa^\gamma \delta_\lambda^\alpha \delta_\theta^\beta - \delta_\kappa^\gamma \delta_\lambda^\beta \delta_\theta^\alpha, \end{aligned}$$

which, in view of (2.20), (4.2), and (4.5), allows us to express the second product on RHS (8.16) as follows:

$$\begin{aligned} \frac{1}{H} \epsilon^{\alpha\beta\gamma\delta} \epsilon_{\kappa\delta\theta\lambda} u^\theta \varpi^\lambda u_\beta (\partial_\gamma \varpi^\kappa) &= -\frac{1}{H} \varpi^\alpha u_\lambda (u^\kappa \partial_\kappa \varpi^\lambda) \\ &\quad + \frac{1}{H} u^\alpha u_\lambda (\varpi^\kappa \partial_\kappa \varpi^\lambda) \end{aligned}$$

$$\begin{aligned}
& + \frac{1}{H} (\varpi^\kappa \partial_\kappa \varpi^\alpha) - \frac{1}{H} \varpi^\alpha (\partial_\kappa \varpi^\kappa) \\
& = \frac{1}{H} \varpi^\alpha \varpi^\lambda (u^\kappa \partial_\kappa u_\lambda) - \frac{1}{H} u^\alpha \varpi^\lambda (\varpi^\kappa \partial_\kappa u_\lambda) \\
& \quad + \frac{1}{H} (\varpi^\kappa \partial_\kappa \varpi^\alpha) - \frac{1}{H} \varpi^\alpha (\partial_\kappa \varpi^\kappa). \quad (8.17)
\end{aligned}$$

Using (8.17) to substitute for the second product on RHS (8.16), and using (4.5) to express the third product on RHS (8.16) as $\epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) u_\kappa (\partial_\delta h) = -\epsilon^{\alpha\beta\gamma\delta} u_\beta \varpi^\kappa (\partial_\gamma u_\kappa) (\partial_\delta h) = \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi^\kappa (\partial_\delta u_\kappa)$ and the last product on RHS (8.16) as $-q \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) u_\kappa S_\delta = q \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma u^\kappa) \varpi_\kappa S_\delta$, we arrive at the desired identity (8.1e).

- **Proof of (8.1f):** (8.1f) follows from definition (2.4) with $V_\delta := \varpi_\delta$.
- **Proof of (8.1g):** (8.1g) is a straightforward consequence of (4.22), (2.20), and (4.2).

- **Proof of (8.2a):** We first use (5.5) to express LHS (8.2a) as follows:

$$\begin{aligned}
& (\theta - \theta_{;h}) S^\alpha ((\eta^{-1})^{\kappa\lambda} \partial_\kappa \partial_\lambda h) + (\theta - \theta_{;h}) S^\alpha (u^\kappa u^\lambda \partial_\kappa \partial_\lambda h) \\
& = (\theta_{;h} - \theta) S^\alpha (u^\lambda \partial_\lambda \partial_\kappa u^\kappa) + (\theta_{;h} - \theta) S^\alpha (\partial_\kappa u^\lambda) (\partial_\lambda u^\kappa) \\
& \quad + (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) + (\theta_{;h} - \theta) S^\alpha (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda h) \\
& \quad + (\theta - \theta_{;h}) q S^\alpha (\partial_\kappa S^\kappa) + (\theta - \theta_{;h}) q_{;h} S^\alpha (S^\kappa \partial_\kappa h) + (\theta - \theta_{;h}) q_{;s} S^\alpha S_\kappa S^\kappa. \quad (8.18)
\end{aligned}$$

Next, with the help of Eq. (2.19), we rewrite the first product on RHS (8.18) as follows:

$$\begin{aligned}
(\theta_{;h} - \theta) S^\alpha (u^\lambda \partial_\lambda \partial_\kappa u^\kappa) & = u^\kappa \partial_\kappa \{ (\theta_{;h} - \theta) S^\alpha (\partial_\lambda u^\lambda) \} \\
& \quad + (\theta_h - \theta_{;h;h}) S^\alpha (u^\kappa \partial_\kappa h) (\partial_\lambda u^\lambda) \\
& \quad + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa S^\alpha) (\partial_\lambda u^\lambda). \quad (8.19)
\end{aligned}$$

Using (8.19) to substitute for the first product on RHS (8.18), we arrive at the desired identity (8.2a).

- **Proof of (8.2b):** (8.2b) is a straightforward consequence of Eq. (2.19).
- **Proof of (8.2c):** We first differentiate Eq. (4.18) with $(\eta^{-1})^{\alpha\lambda} \partial_\lambda$ and then multiply the resulting identity by $(\theta_{;h} - \theta)$ to obtain

$$\begin{aligned}
(\theta_{;h} - \theta) (\eta^{-1})^{\alpha\lambda} (S^\kappa \partial_\kappa \partial_\lambda h) & = (\theta - \theta_{;h}) (\eta^{-1})^{\alpha\lambda} S^\beta (u^\kappa \partial_\kappa \partial_\lambda u_\beta) \\
& \quad + (\theta - \theta_{;h}) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\kappa) (\partial_\kappa h) \\
& \quad + (\theta - \theta_{;h}) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\beta) (u^\kappa \partial_\kappa u_\beta) \\
& \quad + (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\kappa) (\partial_\kappa u_\beta) \\
& \quad + (\theta_{;h} - \theta) q_{;h} ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) S_\kappa S^\kappa \\
& \quad + (\theta_{;h} - \theta) q_{;s} S^\alpha S_\kappa S^\kappa \\
& \quad + 2(\theta_{;h} - \theta) q ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\kappa) S_\kappa. \quad (8.20)
\end{aligned}$$

Next, with the help of Eq. (2.19), we rewrite the first product on RHS (8.20) as follows:

$$\begin{aligned}
 & (\theta - \theta_{;h})(\eta^{-1})^{\alpha\lambda} S^\beta (u^\kappa \partial_\kappa \partial_\lambda u_\beta) \\
 &= u^\kappa \partial_\kappa \{ (\theta - \theta_{;h})(\eta^{-1})^{\alpha\lambda} S^\beta (\partial_\lambda u_\beta) \} \\
 &+ (\theta_{;h;h} - \theta_h)(u^\kappa \partial_\kappa h)(\eta^{-1})^{\alpha\lambda} S^\beta (\partial_\lambda u_\beta) \\
 &+ (\theta_{;h} - \theta)(u^\kappa \partial_\kappa S^\beta)(\eta^{-1})^{\alpha\lambda} (\partial_\lambda u_\beta). \tag{8.21}
 \end{aligned}$$

Next, we use Eqs. (2.22) and (4.4) to express the sum of the second and third products on RHS (8.20) as follows:

$$\begin{aligned}
 & (\theta - \theta_{;h})((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\kappa)(\partial_\kappa h) + (\theta - \theta_{;h})((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\beta)(u^\kappa \partial_\kappa u_\beta) \\
 &= (\theta_{;h} - \theta)((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\beta)u_\beta (u^\kappa \partial_\kappa h) + (\theta - \theta_{;h})q((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\beta)S_\beta \\
 &= (\theta - \theta_{;h})S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta)(u^\kappa \partial_\kappa h) + (\theta - \theta_{;h})q((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\beta)S_\beta. \tag{8.22}
 \end{aligned}$$

Using (8.21) to substitute for the first product on RHS (8.20), and using (8.22) to substitute for the second and third products on RHS (8.20), we arrive at the desired identity (8.2c).

- **Proof of (8.3a):** We simply use (4.1) to express the second product on LHS (8.3a) as follows:

$$(\theta - \theta_{;h})(\eta^{-1})^{\kappa\lambda} (\partial_\kappa h)(\partial_\lambda S^\alpha) = (\theta - \theta_{;h})(\eta^{-1})^{\alpha\kappa} (\partial_\lambda h)(\partial_\kappa S^\lambda).$$

- **Proof of (8.3b):** We use Eq. (2.17) to substitute for the last factor $\partial_\lambda u^\lambda$ on LHS (8.3b) and then appeal to Eq. (2.13b).

- **Proof of (8.3c):** We first use (4.18) to express the first product on LHS (8.3c) as follows:

$$\begin{aligned}
 & (\theta_{;h;h} - \theta_h)((\eta^{-1})^{\alpha\kappa} \partial_\kappa h)(S^\lambda \partial_\lambda h) \\
 &= (\theta_h - \theta_{;h;h})((\eta^{-1})^{\alpha\kappa} \partial_\kappa h)(u^\lambda \partial_\lambda u_\beta)S^\beta \\
 &+ (\theta_{;h;h} - \theta_h)q((\eta^{-1})^{\alpha\kappa} \partial_\kappa h)S^\lambda S_\lambda. \tag{8.23}
 \end{aligned}$$

Using (8.23) to substitute for the first product on LHS (8.3c), we arrive at the desired identity.

- **Proof of (8.3d):** To prove (8.3d), we first use Eq. (2.17) to express the last product on LHS (8.3d) as follows:

$$(\theta - \theta_{;h})S^\alpha (\partial_\kappa u^\kappa)(\partial_\lambda u^\lambda) = c^{-4}(\theta - \theta_{;h})S^\alpha (u^\kappa \partial_\kappa h)(u^\lambda \partial_\lambda h). \tag{8.24}$$

Using (8.24) to substitute for the last product on LHS (8.3d) and appealing to Eq. (2.13b), we arrive at the desired identity.

- **Proof of (8.3e):** We first use (2.22) to substitute for the factor $u^\kappa \partial_\kappa u^\lambda$ in the last product on LHS (8.3e), thereby obtaining the following identity:

$$(\theta_{;h} - \theta)S^\alpha (u^\kappa \partial_\kappa u^\lambda)(\partial_\lambda h) = (\theta - \theta_{;h})S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h)(\partial_\lambda h)$$

$$\begin{aligned}
& + (\theta - \theta_{;h}) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + (\theta_{;h} - \theta) q S^\alpha (S^\kappa \partial_\kappa h).
\end{aligned} \tag{8.25}$$

Using (8.25) to substitute for the last product on LHS (8.3e), we arrive at the desired identity.

- **Proof of (8.3f):** We first use (4.1), (4.4), and the first equality in (6.1) to express the last product on LHS (8.3f) as follows:

$$\begin{aligned}
(\theta - \theta_{;h}) ((\eta^{-1})^{\kappa\lambda} \partial_\kappa u^\alpha) S^\beta (\partial_\lambda u_\beta) & = (\theta_{;h} - \theta) (\partial_\kappa u^\alpha) (u^\beta \partial_\beta S^\kappa) \\
& = (\theta - \theta_{;h}) (\partial_\kappa u^\alpha) (S^\lambda \partial_\lambda u^\kappa) \\
& \quad + \frac{1}{H} (\theta - \theta_{;h}) \epsilon^{\kappa\beta\gamma\delta} (\partial_\kappa u^\alpha) S_\beta u_\gamma \varpi_\delta \\
& \quad + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa u^\alpha) (S^\lambda \partial_\lambda h) \\
& \quad + q (\theta_{;h} - \theta) (u^\kappa \partial_\kappa u^\alpha) S^\lambda S_\lambda.
\end{aligned} \tag{8.26}$$

Using (8.26) to substitute for the last product on LHS (8.3f), we arrive at the desired identity.

- **Proof of (8.3g):** We use (4.1) and (4.4) to express the first product on LHS (8.3g) as follows:

$$\begin{aligned}
(\theta - \theta_{;h}) (u^\kappa \partial_\kappa S^\alpha) (\partial_\lambda u^\lambda) & = (\theta - \theta_{;h}) (u^\kappa (\eta^{-1})^{\alpha\beta} \partial_\beta S_\kappa) (\partial_\lambda u^\lambda) \\
& = (\theta_{;h} - \theta) S^\beta ((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) (\partial_\lambda u^\lambda).
\end{aligned} \tag{8.27}$$

Using (8.27) to substitute for the first product on LHS (8.3g), we conclude the desired identity.

- **Proof of (8.3h):** To prove (8.3h), we first note the following identity, which we derive below:

$$\begin{aligned}
& c^{-2} (\theta - \theta_{;h}) (S^\kappa \partial_\kappa h) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\
& \quad + (\theta_{;h} - \theta) (u^\kappa \partial_\kappa S^\beta) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\
& = (\theta - \theta_{;h}) S^\kappa (\partial_\beta u_\kappa) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\beta) \\
& \quad + c^{-2} (\theta_{;h} - \theta) (u^\lambda \partial_\lambda u_\beta) S^\beta ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) \\
& \quad + c^{-2} (\theta - \theta_{;h}) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta (u^\lambda \partial_\lambda h) \\
& \quad + (\theta - \theta_{;h}) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta (\partial_\lambda u^\lambda) + q c^{-2} (\theta - \theta_{;h}) S^\beta S_\beta ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h).
\end{aligned} \tag{8.28}$$

Using (8.28) to substitute for the sum of the second and third products on LHS (8.3h), we conclude the desired identity (8.3h).

It remains for us to prove (8.28). To proceed, we first use (4.1) and (4.4) to express the second product on LHS (8.28) as follows:

$$\begin{aligned}
& (\theta_{;h} - \theta) (u^\kappa \partial_\kappa S^\beta) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\
& = (\theta_{;h} - \theta) (u^\kappa \partial_\beta S_\kappa) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\beta) \\
& = (\theta - \theta_{;h}) (S^\beta \partial_\lambda u_\beta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa u^\lambda)
\end{aligned}$$

$$\begin{aligned}
&= (\theta - \theta_{;h})((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(\partial_\lambda u^\lambda) \\
&\quad + (\theta_{;h} - \theta)((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(\partial_\lambda u^\lambda) \\
&\quad + (\theta - \theta_{;h})(S^\beta \partial_\lambda u_\beta)((\eta^{-1})^{\alpha\kappa} \partial_\kappa u^\lambda),
\end{aligned} \tag{8.29}$$

where to obtain the last equality, we have added and subtracted

$$(\theta_{;h} - \theta)((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(\partial_\lambda u^\lambda).$$

Next, we use Eq. (2.17) to substitute for the factor $\partial_\lambda u^\lambda$ in the first product on RHS (8.29), which allows us to express the product as follows:

$$\begin{aligned}
&(\theta - \theta_{;h})((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(\partial_\lambda u^\lambda) \\
&= c^{-2}(\theta_{;h} - \theta)((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(u^\lambda \partial_\lambda h) \\
&= c^{-2}(\theta_{;h} - \theta)(u^\lambda \partial_\lambda u_\beta) S^\beta((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) \\
&\quad + c^{-2}(\theta - \theta_{;h})(u^\lambda \partial_\lambda u_\beta) S^\beta((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) \\
&\quad + c^{-2}(\theta_{;h} - \theta)((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(u^\lambda \partial_\lambda h),
\end{aligned} \tag{8.30}$$

where to obtain the last equality, we have added and subtracted

$$c^{-2}(\theta - \theta_{;h})(u^\lambda \partial_\lambda u_\beta) S^\beta((\eta^{-1})^{\alpha\kappa} \partial_\kappa h).$$

Next, we use Eq. (4.18) to express the first product on RHS (8.30) as follows:

$$\begin{aligned}
&c^{-2}(\theta_{;h} - \theta)(u^\lambda \partial_\lambda u_\beta) S^\beta((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) \\
&= c^{-2}(\theta - \theta_{;h})(S^\kappa \partial_\kappa h)((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\
&\quad + qc^{-2}(\theta_{;h} - \theta) S_\kappa S^\kappa((\eta^{-1})^{\alpha\lambda} \partial_\lambda h).
\end{aligned} \tag{8.31}$$

Combining (8.29)–(8.31), we find that

$$\begin{aligned}
&c^{-2}(\theta - \theta_{;h})(S^\kappa \partial_\kappa h)((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\
&= (\theta_{;h} - \theta)(u^\kappa \partial_\kappa S^\beta)((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\
&\quad + (\theta - \theta_{;h})((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(\partial_\lambda u^\lambda) + (\theta_{;h} - \theta)(S^\beta \partial_\lambda u_\beta)((\eta^{-1})^{\alpha\kappa} \partial_\kappa u^\lambda) \\
&\quad + c^{-2}(\theta_{;h} - \theta)(u^\lambda \partial_\lambda u_\beta) S^\beta((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) \\
&\quad + c^{-2}(\theta - \theta_{;h})((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(u^\lambda \partial_\lambda h) \\
&\quad + qc^{-2}(\theta - \theta_{;h}) S_\kappa S^\kappa((\eta^{-1})^{\alpha\lambda} \partial_\lambda h).
\end{aligned} \tag{8.32}$$

Using (8.32) to substitute for the first product on LHS (8.28), we deduce

$$\begin{aligned}
&c^{-2}(\theta - \theta_{;h})(S^\kappa \partial_\kappa h)((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\
&\quad + (\theta_{;h} - \theta)(u^\kappa \partial_\kappa S^\beta)((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\
&= 2(\theta_{;h} - \theta)(u^\kappa \partial_\kappa S^\beta)((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\
&\quad + (\theta - \theta_{;h})((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(\partial_\lambda u^\lambda) + (\theta_{;h} - \theta)(S^\beta \partial_\lambda u_\beta)(\eta^{-1})^{\alpha\kappa}(\partial_\kappa u^\lambda) \\
&\quad + c^{-2}(\theta_{;h} - \theta)(u^\lambda \partial_\lambda u_\beta) S^\beta((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) \\
&\quad + c^{-2}(\theta - \theta_{;h})((\eta^{-1})^{\alpha\kappa} \partial_\kappa u_\beta) S^\beta(u^\lambda \partial_\lambda h) \\
&\quad + qc^{-2}(\theta - \theta_{;h}) S_\kappa S^\kappa((\eta^{-1})^{\alpha\lambda} \partial_\lambda h).
\end{aligned} \tag{8.33}$$

Next, we use (4.1) and (4.4) to express the first product on RHS (8.33) as

$$\begin{aligned} 2(\theta_{;h} - \theta)(u^\kappa \partial_\kappa S^\beta) & ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\ & = 2(\theta_{;h} - \theta)(u^\kappa \partial_\beta S_\kappa) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\beta) \\ & = 2(\theta - \theta_{;h})(S^\kappa \partial_\beta u_\kappa) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\beta). \end{aligned} \quad (8.34)$$

Using (8.34) to substitute for the first product on RHS (8.33), we arrive at the desired identity (8.28). This completes the proof of (8.3h).

• **Proof of (8.3i):** We use the identity (4.18) to substitute for the factor $S^\lambda \partial_\lambda h$ on LHS (8.3i), thus obtaining

$$\begin{aligned} (\theta - \theta_{;h})u^\alpha(\partial_\kappa u^\kappa)(S^\lambda \partial_\lambda h) & = (\theta_{;h} - \theta)u^\alpha(\partial_\kappa u^\kappa)S^\beta(u^\lambda \partial_\lambda u_\beta) \\ & \quad + (\theta - \theta_{;h})qu^\alpha(\partial_\kappa u^\kappa)S^\lambda S_\lambda. \end{aligned} \quad (8.35)$$

Using (8.35) to substitute for the first product on LHS (8.3i), we arrive at the desired identity.

• **Proof of (8.3j):** We first use Eq. (4.1) to express the last product on LHS (8.3j) as follows:

$$\begin{aligned} (\theta - \theta_{;h})u^\alpha(\eta^{-1})^{\kappa\lambda}(\partial_\kappa h)u_\beta(\partial_\lambda S^\beta) & \\ & = (\theta - \theta_{;h})u^\alpha(\partial_\kappa h)(u^\beta \partial_\beta S^\kappa) \\ & = (\theta - \theta_{;h})u^\alpha(u^\kappa \partial_\kappa h)(\partial_\lambda S^\lambda) \\ & \quad + (\theta_{;h} - \theta)u^\alpha u^\lambda \{(\partial_\lambda h)(\partial_\kappa S^\kappa) - (\partial_\kappa h)(\partial_\lambda S^\kappa)\}, \end{aligned} \quad (8.36)$$

where to obtain the second equality in (8.36), we added and subtracted $(\theta_{;h} - \theta)u^\alpha(u^\kappa \partial_\kappa h)(\partial_\lambda S^\lambda)$. Next, we solve for $\partial_\lambda S^\lambda$ in terms of the remaining terms in definition (2.16b) and then use the resulting identity to algebraically substitute for the factor $\partial_\lambda S^\lambda$ in the first product on RHS (8.36), which yields the identity

$$\begin{aligned} (\theta - \theta_{;h})u^\alpha(u^\kappa \partial_\kappa h)(\partial_\lambda S^\lambda) & = n(\theta - \theta_{;h})u^\alpha(u^\kappa \partial_\kappa h)\mathcal{D} \\ & \quad + (\theta_{;h} - \theta)u^\alpha(u^\kappa \partial_\kappa h)(S^\lambda \partial_\lambda h) \\ & \quad + c^{-2}(\theta - \theta_{;h})u^\alpha(u^\kappa \partial_\kappa h)(S^\lambda \partial_\lambda h). \end{aligned} \quad (8.37)$$

Next, we use Eq. (2.17) to substitute for the factor $u^\kappa \partial_\kappa h$ in the last product on RHS (8.37), which yields the identity

$$\begin{aligned} (\theta - \theta_{;h})u^\alpha(u^\kappa \partial_\kappa h)(\partial_\lambda S^\lambda) & = n(\theta - \theta_{;h})u^\alpha(u^\kappa \partial_\kappa h)\mathcal{D} \\ & \quad + (\theta_{;h} - \theta)u^\alpha(u^\kappa \partial_\kappa h)(S^\lambda \partial_\lambda h) \\ & \quad + (\theta_{;h} - \theta)u^\alpha(\partial_\kappa u^\kappa)(S^\lambda \partial_\lambda h). \end{aligned} \quad (8.38)$$

Substituting RHS (8.38) for the first product on RHS (8.36) and then using the resulting identity to substitute for the last product on LHS (8.3j), we arrive at the desired identity (8.3j).

- **Proof of (8.3k):** We first use Eq. (2.22) to substitute for the factor of $u^\kappa \partial_\kappa u_\beta$ in the second product on LHS (8.3k), which yields the identity

$$\begin{aligned} & (\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta h) u_\gamma \varpi_\delta + c^{-2} \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (\partial_\gamma h) \varpi_\delta \\ &= (\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta h) u_\gamma \varpi_\delta - c^{-2} (u^\kappa \partial_\kappa h) \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \\ & \quad + c^{-2} q \epsilon^{\alpha\beta\gamma\delta} S_\beta (\partial_\gamma h) \varpi_\delta. \end{aligned} \quad (8.39)$$

Using Eq. (2.17) to substitute for the factor $\partial_\kappa u^\kappa$ in the first product on RHS (8.39) and taking into account the antisymmetry of ϵ , we see that the first and second products on RHS (8.39) cancel, which yields the desired identity (8.3k).

- **Proof of (8.3l):** We simply use Eq. (2.22) to substitute for the factor $u^\kappa \partial_\kappa u_\sigma$ on LHS (8.3l).

- **Proof of (8.3m):** We simply multiply Eq. (4.19) by $(\theta_{;h} - \theta)(\eta^{-1})^{\alpha\kappa} \partial_\kappa h$.

- **Proof of (8.3n):** We use Eq. (4.18) to substitute for the factor $(u^\kappa \partial_\kappa u_\sigma) S^\sigma$ in the first product on LHS (8.3n) and Eq. (2.17) to substitute for the factor $u^\lambda \partial_\lambda h$ in the second product on LHS (8.3n).

- **Proof of (8.3o):** We simply use Eq. (2.24) to substitute for the factor $u^\lambda \partial_\lambda S^\alpha$ in the second product on LHS (8.3o).

- **Proof of (8.3p):** (8.3p) follows from (4.3). \square

8.2. The Transport-div-curl System

Armed with Lemma 8.1, we now derive the main result of this section.

Proposition 8.2 (The transport-div-curl system for the vorticity). *Assume that (h, s, u^α) is a C^3 solution to (2.17)–(2.19) + (2.20). Then the divergence of the vorticity vectorfield ϖ^α defined in (2.5) verifies the following identity:*

$$\partial_\alpha \varpi^\alpha = -\varpi^\kappa \partial_\kappa h + 2q \varpi^\kappa S_\kappa. \quad (8.40)$$

Moreover, the rectangular components \mathcal{C}^α of the modified vorticity of the vorticity, which is defined in (2.16a), verify the following transport equations:

$$\begin{aligned} u^\kappa \partial_\kappa \mathcal{C}^\alpha &= \mathcal{C}^\kappa \partial_\kappa u^\alpha - 2(\partial_\kappa u^\kappa) \mathcal{C}^\alpha + u^\alpha (u^\kappa \partial_\kappa u_\lambda) \mathcal{C}^\lambda \\ & \quad - 2\epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\delta u_\kappa) \\ & \quad + (\theta_{;h} - \theta) \{(\eta^{-1})^{\alpha\kappa} + 2u^\alpha u^\kappa\} \{(\partial_\kappa h)(\partial_\lambda S^\lambda) - (\partial_\lambda h)(\partial_\kappa S^\lambda)\} \\ & \quad + n(\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa h) \mathcal{D} \\ & \quad + (\theta - \theta_{;h}) q S^\alpha \partial_\kappa S^\kappa + (\theta_{;h} - \theta) q ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\kappa) S_\kappa \\ & \quad + \mathfrak{Q}_{(\mathcal{C}^\alpha)} + \mathfrak{L}_{(\mathcal{C}^\alpha)}, \end{aligned} \quad (8.41)$$

where $\mathfrak{Q}_{(\mathcal{C}^\alpha)}$ is the linear combination of **null forms** defined by

$$\begin{aligned} \mathfrak{Q}_{(\mathcal{C}^\alpha)} &:= -c^{-2} \epsilon^{\kappa\beta\gamma\delta} (\partial_\kappa u^\alpha) u_\beta (\partial_\gamma h) \varpi_\delta \\ & \quad + (c^{-2} + 2) \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi^\kappa (\partial_\delta u_\kappa) \\ & \quad + c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta \varpi_\delta \{(\partial_\kappa u^\kappa) (\partial_\gamma h) - (\partial_\gamma u^\kappa) (\partial_\kappa h)\} \end{aligned}$$

$$\begin{aligned}
& + \{(\theta_{;h;h} - \theta_h) + c^{-2}(\theta - \theta_{;h})\} (\eta^{-1})^{\alpha\lambda} S^\beta u^\kappa \times \\
& \quad \{(\partial_\kappa h)(\partial_\lambda u_\beta) - (\partial_\lambda h)(\partial_\kappa u_\beta)\} \\
& + (\theta_{;h} - \theta) S^\kappa u^\lambda \{(\partial_\kappa u^\alpha)(\partial_\lambda h) - (\partial_\lambda u^\alpha)(\partial_\kappa h)\} \\
& + (\theta_{;h} - \theta) \{(\eta^{-1})^{\alpha\kappa} + u^\alpha u^\kappa\} S^\beta \times \\
& \quad \{(\partial_\kappa u_\beta)(\partial_\lambda u^\lambda) - (\partial_\lambda u_\beta)(\partial_\kappa u^\lambda)\} \\
& + (\theta_{;h} - \theta) S^\alpha \{(\partial_\kappa u^\lambda)(\partial_\lambda u^\kappa) - (\partial_\kappa u^\kappa)(\partial_\lambda u^\lambda)\} \\
& + (\theta_{;h} - \theta) S^\kappa \{(\partial_\kappa u^\alpha)(\partial_\lambda u^\lambda) - (\partial_\lambda u^\alpha)(\partial_\kappa u^\lambda)\} \\
& + S^\alpha \{c^{-2}(\theta_h - \theta_{;h;h}) + c^{-4}(\theta_{;h} - \theta)\} (g^{-1})^{\kappa\lambda} (\partial_\kappa h)(\partial_\lambda h), \quad (8.42)
\end{aligned}$$

and $\mathfrak{L}_{(\mathcal{C}^\alpha)}$, which is at most linear in the derivatives of the solution variables, is defined by

$$\begin{aligned}
\mathfrak{L}_{(\mathcal{C}^\alpha)} := & \frac{2q}{H} \varpi^\kappa S_\kappa \varpi^\alpha - \frac{2}{H} \varpi^\alpha (\varpi^\kappa \partial_\kappa h) \\
& + 2c^{-3} c_{,s} (u^\kappa \partial_\kappa h) \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi_\delta \\
& - 2q \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi^\kappa (\partial_\delta u_\kappa) - q (\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma \varpi_\delta \\
& + \frac{1}{H} (\theta - \theta_{;h}) \epsilon^{\kappa\beta\gamma\delta} (\partial_\kappa u^\alpha) S_\beta u_\gamma \varpi_\delta + c^{-2} q \epsilon^{\alpha\beta\gamma\delta} S_\beta (\partial_\gamma h) \varpi_\delta \\
& - c^{-2} q u^\alpha \epsilon^{\kappa\beta\gamma\delta} S_\kappa u_\beta (\partial_\gamma h) \varpi_\delta \\
& + q (\theta_{;h} - \theta) S_\kappa S^\kappa (u^\lambda \partial_\lambda u^\alpha) \\
& + q (\theta_{;h} - \theta) u^\alpha S_\kappa S^\kappa (u^\lambda \partial_\lambda h) + (\theta_{;h;s} - \theta_{;s}) u^\alpha S_\kappa S^\kappa (u^\lambda \partial_\lambda h) \\
& + (\theta_{;s} - \theta_{;h;s}) S^\alpha (S^\kappa \partial_\kappa h) + (\theta - \theta_{;h}) q_{;h} S^\alpha (S^\kappa \partial_\kappa h) \\
& + q (\theta_{;h;h} - \theta_h) S_\kappa S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) + (\theta_{;h;s} - \theta_{;s}) S_\kappa S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\
& + q c^{-2} (\theta - \theta_{;h}) S_\kappa S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) + (\theta_{;h} - \theta) q_{;h} S_\kappa S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h). \quad (8.43)
\end{aligned}$$

Proof. We split the proof into several pieces.

• **Proof of (8.40):** First, from definition (2.5) and the antisymmetry of $\epsilon^{\kappa\lambda\gamma\delta}$, we deduce

$$\partial_\kappa \varpi^\kappa = -\epsilon^{\kappa\lambda\gamma\delta} (\partial_\kappa u_\lambda) \partial_\gamma (H u_\delta). \quad (8.44)$$

Next, using (4.16), we deduce that

$$\text{RHS (8.44)} = \varpi^\lambda (u^\kappa \partial_\kappa u_\lambda) - \varpi^\kappa u^\lambda (\partial_\kappa u_\lambda) - \theta \epsilon^{\kappa\lambda\gamma\delta} (\partial_\kappa u_\lambda) S_\gamma u_\delta. \quad (8.45)$$

Using (4.3), we see that the second product on RHS (8.45) vanishes. Moreover, using Eq. (2.22) and the identity (4.2), we can express the first product on RHS (8.45) as follows:

$$\varpi^\lambda (u^\kappa \partial_\kappa u_\lambda) = -\varpi^\kappa \partial_\kappa h + q \varpi^\kappa S_\kappa. \quad (8.46)$$

In addition, using definition (2.7) and the identity (4.23), we can express the last product on RHS (8.45) as follows:

$$-\theta \epsilon^{\kappa\lambda\gamma\delta} (\partial_\kappa u_\lambda) S_\gamma u_\delta = q \varpi^\kappa S_\kappa. \quad (8.47)$$

Combining these calculations, we arrive at the desired identity (8.40).

• **Proof of (8.41):** The proof is a series of lengthy calculations in which we observe many cancellations. We start by using (8.1a)–(8.1g) to substitute for all of the terms on the third through seventh lines of RHS (7.4) except for the term $-\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma\varpi^\kappa)(\partial_\delta u_\kappa)$ from the fifth line, which we leave as is. We also use (8.40) to express the fourth product on RHS (8.1e) as $\frac{1}{H}\varpi^\alpha(\partial_\kappa\varpi^\kappa) = -\frac{1}{H}\varpi^\alpha(\varpi^\kappa\partial_\kappa h) + \frac{2q}{H}\varpi^\alpha\varpi^\kappa S_\kappa$, and we use (8.2a)–(8.2c) to substitute for the four products (which depend on the second derivatives of h) on the sixth-to-last and fifth-to-last lines of RHS (7.4), thereby obtaining the following equation (where at this stage in the argument, we have simply performed a term-by-term substitution and have not yet organized the terms):

$$\begin{aligned}
u^\kappa\partial_\kappa\text{vort}^\alpha(\varpi) &= \text{vort}^\kappa(\varpi)\partial_\kappa u^\alpha - (\partial_\kappa u^\kappa)\text{vort}^\alpha(\varpi) \\
&\quad + u^\alpha(u^\kappa\partial_\kappa u_\beta)\text{vort}^\beta(\varpi) \\
&\quad - u^\kappa\partial_\kappa\{c^{-2}\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma h)\varpi_\delta\} \\
&\quad - 2(\partial_\kappa u^\kappa)c^{-2}\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma h)\varpi_\delta \\
&\quad + c^{-2}\epsilon^{\alpha\beta\gamma\delta}(u^\kappa\partial_\kappa u_\beta)(\partial_\gamma h)\varpi_\delta \\
&\quad + c^{-2}\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma h)\varpi^\kappa(\partial_\delta u_\kappa) \\
&\quad + c^{-2}(\theta - \theta_{;h})(S^\kappa\partial_\kappa h)((\eta^{-1})^{\alpha\lambda}\partial_\lambda h) \\
&\quad + c^{-2}(\theta - \theta_{;h})u^\alpha(S^\kappa\partial_\kappa h)(u^\lambda\partial_\lambda h) \\
&\quad + c^{-2}(\theta_{;h} - \theta)S^\alpha(u^\kappa\partial_\kappa h)(u^\lambda\partial_\lambda h) \\
&\quad + c^{-2}(\theta_{;h} - \theta)S^\alpha(\eta^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda h) \\
&\quad + c^{-2}\epsilon^{\alpha\beta\gamma\delta}u_\beta\{(\partial_\kappa u^\kappa)(\partial_\gamma h) - (\partial_\gamma u^\kappa)(\partial_\kappa h)\}\varpi_\delta \\
&\quad + 2c^{-3}c_{;s}(u^\kappa\partial_\kappa h)\epsilon^{\alpha\beta\gamma\delta}u_\beta S_\gamma\varpi_\delta \\
&\quad + \frac{1}{H}(\varpi^\kappa\partial_\kappa\varpi^\alpha) - \frac{1}{H}(\varpi^\kappa\partial_\kappa h)\varpi^\alpha \\
&\quad - \frac{1}{H}u^\alpha\varpi^\lambda(\varpi^\kappa\partial_\kappa u_\lambda) + \epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma h)\varpi^\kappa(\partial_\delta u_\kappa) \\
&\quad - q\epsilon^{\alpha\beta\gamma\delta}u_\beta S_\gamma\varpi^\kappa(\partial_\delta u_\kappa) \\
&\quad - \epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)u_\gamma\varpi^\kappa(\partial_\delta u_\kappa) + (\partial_\kappa u^\kappa)\epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)u_\gamma\varpi_\delta \\
&\quad + (\theta - \theta_{;h})((\eta^{-1})^{\alpha\kappa}\partial_\kappa h)(S^\lambda\partial_\lambda h) \\
&\quad + (\theta - \theta_{;h})u^\alpha(u^\kappa\partial_\kappa h)(S^\lambda\partial_\lambda h) \\
&\quad + (\theta_{;h} - \theta)S^\alpha(u^\kappa\partial_\kappa h)(u^\lambda\partial_\lambda h) \\
&\quad + (\theta_{;h} - \theta)S^\alpha(\eta^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda h) \\
&\quad + q\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma\varpi^\kappa(\partial_\delta u_\kappa) \\
&\quad - q(\partial_\kappa u^\kappa)\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma\varpi_\delta \\
&\quad + q(\theta_{;h} - \theta)((\eta^{-1})^{\kappa\alpha}\partial_\kappa h)S^\lambda S_\lambda
\end{aligned}$$

$$\begin{aligned}
& + q(\theta_{;h} - \theta)u^\alpha(u^\kappa\partial_\kappa h)S^\lambda S_\lambda + q(\theta - \theta_{;h})S^\alpha(S^\kappa\partial_\kappa h) \\
& - \epsilon^{\alpha\beta\gamma\delta}(\partial_\beta h)u_\gamma\varpi^\lambda(\partial_\delta u_\lambda) + q\epsilon^{\alpha\beta\gamma\delta}S_\beta u_\gamma\varpi^\lambda(\partial_\delta u_\lambda) \\
& - \epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma\varpi^\kappa)(\partial_\delta u_\kappa) \\
& - \epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma\varpi^\kappa)(\partial_\delta u_\kappa) - \epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma h)\varpi^\kappa(\partial_\delta u_\kappa) \\
& - \frac{1}{H}(\varpi^\kappa\partial_\kappa\varpi^\alpha) - \frac{1}{H}\varpi^\alpha(\varpi^\kappa\partial_\kappa h) + \frac{2q}{H}\varpi^\alpha\varpi^\kappa S_\kappa \\
& - \frac{1}{H}\varpi^\alpha\varpi^\lambda(u^\kappa\partial_\kappa u_\lambda) + \frac{1}{H}u^\alpha\varpi^\lambda(\varpi^\kappa\partial_\kappa u_\lambda) \\
& - q\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma u^\kappa)\varpi_\kappa S_\delta \\
& - (\partial_\kappa u^\kappa)\text{vort}^\alpha(\varpi) \\
& + \frac{1}{H}\varpi^\alpha\varpi^\lambda(u^\kappa\partial_\kappa u_\lambda) \\
& + (\theta_h - \theta_{;h;h})S^\alpha(\eta^{-1})^{\kappa\lambda}(\partial_\kappa h)(\partial_\lambda h) \\
& + (\theta_h - \theta_{;h;h})S^\alpha(u^\kappa\partial_\kappa h)(u^\lambda\partial_\lambda h) \\
& + (\theta_{;h;h} - \theta_h)u^\alpha(S^\kappa\partial_\kappa h)(u^\lambda\partial_\lambda h) \\
& + (\theta_{;h;h} - \theta_h)((\eta^{-1})^{\alpha\kappa}\partial_\kappa h)(S^\lambda\partial_\lambda h) \\
& + (\theta_{;s} - \theta_{;h;s})S^\alpha(S^\kappa\partial_\kappa h) + (\theta_{;h;s} - \theta_{;s})u^\alpha S_\kappa S^\kappa(u^\lambda\partial_\lambda h) \\
& + (\theta_{;h;s} - \theta_{;s})S_\kappa S^\kappa((\eta^{-1})^{\alpha\lambda}\partial_\lambda h) \\
& + (\theta - \theta_{;h})S^\alpha(\partial_\kappa u^\kappa)(u^\lambda\partial_\lambda h) \\
& + (\theta_{;h} - \theta)(S^\kappa\partial_\kappa u^\alpha)(u^\lambda\partial_\lambda h) \\
& + u^\kappa\partial_\kappa\{(\theta_{;h} - \theta)S^\alpha(\partial_\lambda u^\lambda)\} \\
& + (\theta_h - \theta_{;h;h})S^\alpha(u^\kappa\partial_\kappa h)(\partial_\lambda u^\lambda) \\
& + (\theta - \theta_{;h})(u^\kappa\partial_\kappa S^\alpha)(\partial_\lambda u^\lambda) \\
& + (\theta_{;h} - \theta)S^\alpha(\partial_\kappa u^\lambda)(\partial_\lambda u^\kappa) \\
& + (\theta_{;h} - \theta)S^\alpha(u^\kappa\partial_\kappa u^\lambda)(\partial_\lambda h) + (\theta_{;h} - \theta)S^\alpha(\partial_\kappa u^\kappa)(u^\lambda\partial_\lambda h) \\
& + (\theta - \theta_{;h})qS^\alpha(\partial_\kappa S^\kappa) + (\theta - \theta_{;h})q_{;h}S^\alpha(S^\kappa\partial_\kappa h) \\
& + (\theta - \theta_{;h})q_{;s}S^\alpha S_\kappa S^\kappa \\
& + u^\kappa\partial_\kappa\{(\theta_{;h} - \theta)u^\alpha(S^\lambda\partial_\lambda h)\} \\
& + (\theta_h - \theta_{;h;h})u^\alpha(u^\kappa\partial_\kappa h)(S^\lambda\partial_\lambda h) \\
& + (\theta - \theta_{;h})(u^\kappa\partial_\kappa u^\alpha)(S^\lambda\partial_\lambda h) \\
& + (\theta - \theta_{;h})u^\alpha(u^\kappa\partial_\kappa S^\lambda)(\partial_\lambda h) \\
& + u^\kappa\partial_\kappa\{(\theta - \theta_{;h})(\eta^{-1})^{\alpha\lambda}S^\beta(\partial_\lambda u_\beta)\} \\
& + (\theta_{;h;h} - \theta_h)(u^\kappa\partial_\kappa h)S^\beta((\eta^{-1})^{\alpha\lambda}\partial_\lambda u_\beta) \\
& + (\theta_{;h} - \theta)(u^\kappa\partial_\kappa S^\beta)((\eta^{-1})^{\alpha\lambda}\partial_\lambda u_\beta) \\
& + (\theta - \theta_{;h})S^\beta((\eta^{-1})^{\alpha\lambda}\partial_\lambda u_\beta)(u^\kappa\partial_\kappa h)
\end{aligned}$$

$$\begin{aligned}
& + (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\kappa) (\partial_\kappa u_\beta) \\
& + (\theta - \theta_{;h}) q ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\beta) S_\beta \\
& + (\theta_{;h} - \theta) q_{;h} ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) S_\kappa S^\kappa \\
& + (\theta_{;h} - \theta) q_{;s} S^\alpha S_\kappa S^\kappa + 2(\theta_{;h} - \theta) q ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\kappa) S_\kappa \\
& + (\theta - \theta_{;h}) (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda S^\alpha) \\
& + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda S^\alpha) \\
& + (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa h) (\partial_\lambda S^\lambda) \\
& + (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (\partial_\lambda S^\lambda) \\
& + (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) u_\beta (u^\lambda \partial_\lambda S^\beta) \\
& + (\theta - \theta_{;h}) u^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) u_\beta (\partial_\lambda S^\beta).
\end{aligned} \tag{8.48}$$

Next, we bring the four perfect-derivative terms $u^\kappa \partial_\kappa \{\dots\}$ on RHS (8.48) over to the left-hand side, which yields the equation

$$\begin{aligned}
& u^\kappa \partial_\kappa \left\{ \text{vort}^\alpha(\varpi) + c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta + (\theta - \theta_{;h}) S^\alpha (\partial_\lambda u^\lambda) \right. \\
& \quad \left. + (\theta - \theta_{;h}) u^\alpha (S^\lambda \partial_\lambda h) + (\theta_{;h} - \theta) (\eta^{-1})^{\alpha\lambda} S^\beta (\partial_\lambda u_\beta) \right\} \\
& = \text{vort}^\kappa(\varpi) \partial_\kappa u^\alpha - 2(\partial_\kappa u^\kappa) \text{vort}^\alpha(\varpi) + u^\alpha (u^\kappa \partial_\kappa u_\beta) \text{vort}^\beta(\varpi) + \dots,
\end{aligned} \tag{8.49}$$

where the terms \dots do not involve $\text{vort}(\varpi)$. Next, we solve for $\text{vort}(\varpi)$ in terms of the remaining terms in definition (2.16a) and then use the resulting identity to algebraically substitute for the four instances of $\text{vort}(\varpi)$ in Eq. (8.49) (note in particular that the terms in braces on LHS (8.49) are equal to \mathcal{C}^α). In total, this yields the following equation, where we have placed the terms generated by the algebraic substitution on the first through tenth lines of RHS (8.50):

$$\begin{aligned}
u^\kappa \partial_\kappa \mathcal{C}^\alpha & = \mathcal{C}^\kappa \partial_\kappa u^\alpha - 2(\partial_\kappa u^\kappa) \mathcal{C}^\alpha + u^\alpha (u^\kappa \partial_\kappa u_\beta) \mathcal{C}^\beta \\
& \quad - c^{-2} \epsilon^{\kappa\beta\gamma\delta} (\partial_\kappa u^\alpha) u_\beta (\partial_\gamma h) \varpi_\delta + (\theta_{;h} - \theta) (S^\kappa \partial_\kappa u^\alpha) (\partial_\lambda u^\lambda) \\
& \quad + (\theta_{;h} - \theta) (u^\kappa \partial_\kappa u^\alpha) (S^\lambda \partial_\lambda h) + (\theta - \theta_{;h}) (\eta^{-1})^{\kappa\lambda} (\partial_\kappa u^\alpha) S^\beta (\partial_\lambda u_\beta) \\
& \quad + 2(\partial_\kappa u^\kappa) c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta + 2(\theta - \theta_{;h}) S^\alpha (\partial_\kappa u^\kappa) (\partial_\lambda u^\lambda) \\
& \quad + 2(\theta - \theta_{;h}) u^\alpha (\partial_\kappa u^\kappa) (S^\lambda \partial_\lambda h) \\
& \quad + 2(\theta_{;h} - \theta) (\partial_\kappa u^\kappa) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\
& \quad - u^\alpha (u^\kappa \partial_\kappa u_\sigma) c^{-2} \epsilon^{\sigma\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \\
& \quad + (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa u_\sigma) S^\sigma (\partial_\lambda u^\lambda) \\
& \quad + (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa u_\beta) u^\beta (S^\lambda \partial_\lambda h) \\
& \quad + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa u^\lambda) S^\beta (\partial_\lambda u_\beta) \\
& \quad - 2(\partial_\kappa u^\kappa) c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi_\delta \\
& \quad + c^{-2} \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (\partial_\gamma h) \varpi_\delta
\end{aligned}$$

$$\begin{aligned}
& + c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi^\kappa (\partial_\delta u_\kappa) \\
& + c^{-2} (\theta - \theta_{;h}) (S^\kappa \partial_\kappa h) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\
& + c^{-2} (\theta - \theta_{;h}) u^\alpha (S^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + c^{-2} (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + c^{-2} (\theta_{;h} - \theta) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) \\
& + c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta \{ (\partial_\kappa u^\kappa) (\partial_\gamma h) - (\partial_\gamma u^\kappa) (\partial_\kappa h) \} \varpi_\delta \\
& + 2c^{-3} c_{;s} (u^\kappa \partial_\kappa h) \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi_\delta \\
& + \frac{1}{H} (\varpi^\kappa \partial_\kappa \varpi^\alpha) - \frac{1}{H} \varpi^\alpha (\varpi^\kappa \partial_\kappa h) \\
& - \frac{1}{H} u^\alpha \varpi^\lambda (\varpi^\kappa \partial_\kappa u_\lambda) + \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi^\kappa (\partial_\delta u_\kappa) \\
& - q \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi^\kappa (\partial_\delta u_\kappa) \\
& - \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta h) u_\gamma \varpi^\kappa (\partial_\delta u_\kappa) + (\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta h) u_\gamma \varpi_\delta \\
& + (\theta - \theta_{;h}) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (S^\lambda \partial_\lambda h) + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa h) (S^\lambda \partial_\lambda h) \\
& + (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) + (\theta_{;h} - \theta) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) \\
& + q \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma \varpi^\kappa (\partial_\delta u_\kappa) \\
& - q (\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma \varpi_\delta \\
& + q (\theta_{;h} - \theta) ((\eta^{-1})^{\kappa\alpha} \partial_\kappa h) S^\lambda S_\lambda + q (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa h) S^\lambda S_\lambda \\
& + q (\theta - \theta_{;h}) S^\alpha (S^\kappa \partial_\kappa h) \\
& - \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta h) u_\gamma \varpi^\lambda (\partial_\delta u_\lambda) + q \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma \varpi^\lambda (\partial_\delta u_\lambda) \\
& - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\delta u_\kappa) \\
& - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\delta u_\kappa) - \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi^\kappa (\partial_\delta u_\kappa) \\
& - \frac{1}{H} (\varpi^\kappa \partial_\kappa \varpi^\alpha) - \frac{1}{H} \varpi^\alpha (\varpi^\kappa \partial_\kappa h) + \frac{2q}{H} \varpi^\alpha \varpi^\kappa S_\kappa \\
& - \frac{1}{H} \varpi^\alpha \varpi^\lambda (u^\kappa \partial_\kappa u_\lambda) + \frac{1}{H} u^\alpha \varpi^\lambda (\varpi^\kappa \partial_\kappa u_\lambda) \\
& - q \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma u^\kappa) \varpi_\kappa S_\delta \\
& + \frac{1}{H} \varpi^\alpha \varpi^\lambda (u^\kappa \partial_\kappa u_\lambda) \\
& + (\theta_h - \theta_{;h;h}) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) \\
& + (\theta_h - \theta_{;h;h}) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + (\theta_{;h;h} - \theta_h) u^\alpha (S^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + (\theta_{;h;h} - \theta_h) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (S^\lambda \partial_\lambda h) \\
& + (\theta_{;s} - \theta_{;h;s}) S^\alpha (S^\kappa \partial_\kappa h) + (\theta_{;h;s} - \theta_{;s}) u^\alpha S_\kappa S^\kappa (u^\lambda \partial_\lambda h) \\
& + (\theta_{;h;s} - \theta_{;s}) S_\kappa S^\kappa ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h)
\end{aligned}$$

$$\begin{aligned}
& + (\theta - \theta_{;h}) S^\alpha (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda h) + (\theta_{;h} - \theta) (S^\kappa \partial_\kappa u^\alpha) (u^\lambda \partial_\lambda h) \\
& + (\theta_h - \theta_{;h;h}) S^\alpha (u^\kappa \partial_\kappa h) (\partial_\lambda u^\lambda) + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa S^\alpha) (\partial_\lambda u^\lambda) \\
& + (\theta_{;h} - \theta) S^\alpha (\partial_\kappa u^\lambda) (\partial_\lambda u^\kappa) + (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h) \\
& + (\theta_{;h} - \theta) S^\alpha (\partial_\kappa u^\kappa) (u^\lambda \partial_\lambda h) \\
& + (\theta - \theta_{;h}) q S^\alpha (\partial_\kappa S^\kappa) + (\theta - \theta_{;h}) q_{;h} S^\alpha (S^\kappa \partial_\kappa h) \\
& + (\theta - \theta_{;h}) q_{;s} S^\alpha S_\kappa S^\kappa \\
& + (\theta_h - \theta_{;h;h}) u^\alpha (u^\kappa \partial_\kappa h) (S^\lambda \partial_\lambda h) + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa u^\alpha) (S^\lambda \partial_\lambda h) \\
& + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa S^\lambda) (\partial_\lambda h) \\
& + (\theta_{;h;h} - \theta_h) (u^\kappa \partial_\kappa h) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\
& + (\theta_{;h} - \theta) (u^\kappa \partial_\kappa S^\beta) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) \\
& + (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) (u^\kappa \partial_\kappa h) \\
& + (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\kappa) (\partial_\kappa u_\beta) \\
& + (\theta - \theta_{;h}) q ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\beta) S_\beta + (\theta_{;h} - \theta) q_{;h} ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) S_\kappa S^\kappa \\
& + (\theta_{;h} - \theta) q_{;s} S^\alpha S_\kappa S^\kappa + 2(\theta_{;h} - \theta) q ((\eta^{-1})^{\alpha\lambda} \partial_\lambda S^\kappa) S_\kappa \\
& + (\theta - \theta_{;h}) (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda S^\alpha) + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda S^\alpha) \\
& + (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa h) (\partial_\lambda S^\lambda) + (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (\partial_\lambda S^\lambda) \\
& + (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) u_\beta (u^\lambda \partial_\lambda S^\beta) \\
& + (\theta - \theta_{;h}) u^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) u_\beta (\partial_\lambda S^\beta).
\end{aligned} \tag{8.50}$$

Next, we reorganize the terms on RHS (8.50) to obtain the equation

$$u^\kappa \partial_\kappa \mathcal{C}^\alpha = \mathcal{C}^\kappa \partial_\kappa u^\alpha - 2(\partial_\kappa u^\kappa) \mathcal{C}^\alpha + u^\alpha (u^\kappa \partial_\kappa u_\beta) \mathcal{C}^\beta + \sum_{i=1}^{21} \mathcal{Q}_i + \mathcal{L}, \tag{8.51}$$

where

$$\mathcal{Q}_1 := -2\epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma \varpi^\kappa) (\partial_\delta u_\kappa), \tag{8.52}$$

$$\mathcal{Q}_2 := (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) \partial_\lambda S^\lambda + (\theta - \theta_{;h}) (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda S^\alpha), \tag{8.53}$$

$$\mathcal{Q}_3 := (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa h) (\partial_\lambda S^\lambda) + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa S^\lambda) (\partial_\lambda h), \tag{8.54}$$

$$\begin{aligned}
\mathcal{Q}_4 := & (\theta_h - \theta_{;h;h}) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) \\
& + (\theta_h - \theta_{;h;h}) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) + (\theta_h - \theta_{;h;h}) S^\alpha (u^\kappa \partial_\kappa h) (\partial_\lambda u^\lambda),
\end{aligned} \tag{8.55}$$

$$\begin{aligned}
\mathcal{Q}_5 := & (\theta_{;h;h} - \theta_h) (\eta^{-1})^{\alpha\kappa} (\partial_\kappa h) (S^\lambda \partial_\lambda h) \\
& + (\theta_{;h;h} - \theta_h) (u^\kappa \partial_\kappa h) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta),
\end{aligned} \tag{8.56}$$

$$\begin{aligned}
\mathcal{Q}_6 := & c^{-2} (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) \\
& + c^{-2} (\theta_{;h} - \theta) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) + (\theta - \theta_{;h}) S^\alpha (\partial_\kappa u^\kappa) (\partial_\lambda u^\lambda),
\end{aligned} \tag{8.57}$$

$$\mathcal{Q}_7 := (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h) + (\theta_{;h} - \theta) S^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) (\partial_\lambda h) + (\theta_{;h} - \theta) S^\alpha (u^\kappa \partial_\kappa u^\lambda) (\partial_\lambda h), \quad (8.58)$$

$$\mathcal{Q}_8 := (\theta_{;h} - \theta) S^\alpha (\partial_\kappa u^\lambda) (\partial_\lambda u^\kappa) + (\theta - \theta_{;h}) S^\alpha (\partial_\kappa u^\kappa) (\partial_\lambda u^\lambda), \quad (8.59)$$

$$\begin{aligned} \mathcal{Q}_9 := & (\theta_{;h} - \theta) (S^\kappa \partial_\kappa u^\alpha) (\partial_\lambda u^\lambda) + (\theta_{;h} - \theta) (u^\kappa \partial_\kappa u^\alpha) (S^\lambda \partial_\lambda h) \\ & + (\theta - \theta_{;h}) ((\eta^{-1})^{\kappa\lambda} \partial_\kappa u^\alpha) S^\beta (\partial_\lambda u_\beta), \end{aligned} \quad (8.60)$$

$$\mathcal{Q}_{10} := (\theta_{;h} - \theta) (S^\kappa \partial_\kappa u^\alpha) (u^\lambda \partial_\lambda h) + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa u^\alpha) (S^\lambda \partial_\lambda h), \quad (8.61)$$

$$\begin{aligned} \mathcal{Q}_{11} := & (\theta - \theta_{;h}) (u^\kappa \partial_\kappa S^\alpha) (\partial_\lambda u^\lambda) \\ & + (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u^\kappa) (\partial_\kappa u_\beta), \end{aligned} \quad (8.62)$$

$$\begin{aligned} \mathcal{Q}_{12} := & 2(\theta_{;h} - \theta) (\partial_\kappa u^\kappa) (\eta^{-1})^{\alpha\lambda} S^\beta (\partial_\lambda u_\beta) \\ & + c^{-2} (\theta - \theta_{;h}) (S^\kappa \partial_\kappa h) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda h) \\ & + (\theta_{;h} - \theta) (u^\kappa \partial_\kappa S^\beta) ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta), \end{aligned} \quad (8.63)$$

$$\mathcal{Q}_{13} := (\theta - \theta_{;h}) u^\alpha (\partial_\kappa u^\kappa) (S^\lambda \partial_\lambda h) + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa u^\lambda) S^\beta (\partial_\lambda u_\beta), \quad (8.64)$$

$$\begin{aligned} \mathcal{Q}_{14} := & (\theta - \theta_{;h}) u^\alpha (\partial_\kappa u^\kappa) (S^\lambda \partial_\lambda h) + (\theta - \theta_{;h}) u^\alpha (u^\kappa \partial_\kappa h) (S^\lambda \partial_\lambda h) \\ & + (\theta - \theta_{;h}) u^\alpha (\eta^{-1})^{\kappa\lambda} (\partial_\kappa h) u_\beta (\partial_\lambda S^\beta), \end{aligned} \quad (8.65)$$

$$\mathcal{Q}_{15} := (\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta} (\partial_\beta h) u_\gamma \varpi_\delta + c^{-2} \epsilon^{\alpha\beta\gamma\delta} (u^\kappa \partial_\kappa u_\beta) (\partial_\gamma h) \varpi_\delta, \quad (8.66)$$

$$\mathcal{Q}_{16} := -c^{-2} u^\alpha \epsilon^{\sigma\beta\gamma\delta} (u^\kappa \partial_\kappa u_\sigma) u_\beta (\partial_\gamma h) \varpi_\delta, \quad (8.67)$$

$$\begin{aligned} \mathcal{Q}_{17} := & -c^{-2} \epsilon^{\kappa\beta\gamma\delta} (\partial_\kappa u^\alpha) u_\beta (\partial_\gamma h) \varpi_\delta \\ & + (c^{-2} + 2) \epsilon^{\alpha\beta\gamma\delta} u_\beta (\partial_\gamma h) \varpi^\kappa (\partial_\delta u_\kappa) \\ & + c^{-2} \epsilon^{\alpha\beta\gamma\delta} u_\beta \varpi_\delta \{ (\partial_\kappa u^\kappa) (\partial_\gamma h) - (\partial_\gamma u^\kappa) (\partial_\kappa h) \}, \end{aligned} \quad (8.68)$$

$$\begin{aligned} \mathcal{Q}_{18} := & (\theta - \theta_{;h}) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) (S^\lambda \partial_\lambda h) \\ & + (\theta_{;h} - \theta) ((\eta^{-1})^{\alpha\kappa} \partial_\kappa h) u_\beta (u^\lambda \partial_\lambda S^\beta), \end{aligned} \quad (8.69)$$

$$\begin{aligned} \mathcal{Q}_{19} := & (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa u_\sigma) S^\sigma (\partial_\lambda u^\lambda) \\ & + c^{-2} (\theta - \theta_{;h}) u^\alpha (S^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda h), \end{aligned} \quad (8.70)$$

$$\begin{aligned} \mathcal{Q}_{20} := & (\theta - \theta_{;h}) S^\beta ((\eta^{-1})^{\alpha\lambda} \partial_\lambda u_\beta) (u^\kappa \partial_\kappa h) \\ & + (\theta - \theta_{;h}) (u^\kappa \partial_\kappa h) (u^\lambda \partial_\lambda S^\alpha), \end{aligned} \quad (8.71)$$

$$\mathcal{Q}_{21} := (\theta_{;h} - \theta) u^\alpha (u^\kappa \partial_\kappa u_\beta) (u^\beta S^\lambda \partial_\lambda h), \quad (8.72)$$

and

$$\begin{aligned} \mathcal{L} := & -\frac{2}{H} \varpi^\alpha (\varpi^\kappa \partial_\kappa h) + \frac{2q}{H} \varpi^\alpha \varpi^\kappa S_\kappa \\ & + 2c^{-3} c_{;s} (u^\kappa \partial_\kappa h) \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi_\delta - q \epsilon^{\alpha\beta\gamma\delta} u_\beta S_\gamma \varpi^\kappa (\partial_\delta u_\kappa) \\ & + 2q \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma \varpi^\kappa (\partial_\delta u_\kappa) \\ & - q (\partial_\kappa u^\kappa) \epsilon^{\alpha\beta\gamma\delta} S_\beta u_\gamma \varpi_\delta \end{aligned}$$

$$\begin{aligned}
& + q(\theta_{;h} - \theta)((\eta^{-1})^{\kappa\alpha}\partial_\kappa h)S^\lambda S_\lambda + q(\theta_{;h} - \theta)u^\alpha(u^\kappa\partial_\kappa h)S^\lambda S_\lambda \\
& + q(\theta - \theta_{;h})S^\alpha(S^\kappa\partial_\kappa h) \\
& - q\epsilon^{\alpha\beta\gamma\delta}u_\beta(\partial_\gamma u^\kappa)\varpi_\kappa S_\delta \\
& + (\theta_{;s} - \theta_{;h;s})S^\alpha(S^\kappa\partial_\kappa h) + (\theta_{;h;s} - \theta_{;s})u^\alpha S_\kappa S^\kappa(u^\lambda\partial_\lambda h) \\
& + (\theta_{;h;s} - \theta_{;s})S_\kappa S^\kappa((\eta^{-1})^{\alpha\lambda}\partial_\lambda h) \\
& + (\theta - \theta_{;h})qS^\alpha(\partial_\kappa S^\kappa) + (\theta - \theta_{;h})q_{;h}S^\alpha(S^\kappa\partial_\kappa h) + (\theta - \theta_{;h})q_{;s}S^\alpha S_\kappa S^\kappa \\
& + (\theta - \theta_{;h})q((\eta^{-1})^{\alpha\lambda}\partial_\lambda S^\beta)S_\beta + (\theta_{;h} - \theta)q_{;h}((\eta^{-1})^{\alpha\lambda}\partial_\lambda h)S_\kappa S^\kappa \\
& + (\theta_{;h} - \theta)q_{;s}S^\alpha S_\kappa S^\kappa + 2(\theta_{;h} - \theta)q((\eta^{-1})^{\alpha\lambda}\partial_\lambda S^\kappa)S_\kappa. \tag{8.73}
\end{aligned}$$

Note that the terms on RHSs (8.52)–(8.72) are precisely quadratic in the first-order derivatives of the solution variables $(h, u^\alpha, \varpi^\alpha, S^\alpha)_{\alpha=0,1,2,3}$ while the terms on RHS (8.73) are at most linear in the derivatives of the solution variables. We will now show that $\mathcal{Q}_1, \mathcal{Q}_2, \dots, \mathcal{Q}_{21}$ can be expressed as null forms or terms that are at most linear in the derivatives of the solution variables. To this end, we simply use (8.3a)–(8.3p) to algebraically substitute for $\mathcal{Q}_2, \mathcal{Q}_4, \mathcal{Q}_5, \mathcal{Q}_6, \mathcal{Q}_7, \mathcal{Q}_9, \mathcal{Q}_{11}, \mathcal{Q}_{12}, \mathcal{Q}_{13}, \mathcal{Q}_{14}, \mathcal{Q}_{15}, \mathcal{Q}_{16}, \mathcal{Q}_{18}, \mathcal{Q}_{19}, \mathcal{Q}_{20}$, and \mathcal{Q}_{21} (we do not substitute for $\mathcal{Q}_1, \mathcal{Q}_3, \mathcal{Q}_8, \mathcal{Q}_{10}$, and \mathcal{Q}_{17} since these terms are already manifestly linear combinations of null forms). Following this substitution, there are only two kinds of terms on RHS (8.51): null forms and terms that are at most linear in the derivatives of the solution variables. We now place all null forms on RHS (8.42) except for null forms that involve the derivatives of ϖ or S ; these null forms we place directly on RHS (8.41). We then place all terms that are linear in \mathcal{C} , linear in \mathcal{D} , linear in the first-order derivatives of ϖ , or linear in the first-order derivatives of S directly on RHS (8.41). Finally, we place all remaining terms, which are at most linear in the derivatives of the solution variables and do not depend on the derivatives of ϖ or S , on RHS (8.43). This completes the proof of the proposition. \square

9. Local Well-Posedness with Additional Regularity for the Vorticity and Entropy

Our main goal in this section is to prove Theorem 9.12, which is a local well-posedness result for the relativistic Euler equations based on our new formulation of the equations, that is, based on the equations of Theorem 3.1. The main new feature of Theorem 9.12 compared to standard local well-posedness results for the relativistic Euler equations (see Theorem 9.10 for a statement of standard local well-posedness) is that it yields an extra degree of differentiability for the vorticity and the entropy, assuming that the initial vorticity and entropy enjoy the same extra differentiability. We stress that this gain in regularity holds even though the logarithmic enthalpy and four-velocity do not generally enjoy the same gain. As we described in Sect. 1.2, this extra regularity for the vorticity and the entropy is essential for the study of shocks in more than one spatial dimension.

For convenience, instead of proving local well-posedness for the relativistic Euler equations on the standard Minkowski spacetime background, we instead consider the spacetime background $(\mathbb{R} \times \mathbb{T}^3, \eta)$, where the “spatial manifold” \mathbb{T}^3 is the standard three-dimensional torus and, relative to standard coordinates on $\mathbb{R} \times \mathbb{T}^3$, $\eta_{\alpha\beta} := \text{diag}(-1, 1, 1, 1)$ is the standard Minkowski metric. Thus, strictly speaking, in this section, η denotes a tensor on a different manifold compared to the rest of the paper, but this minor change has no substantial bearing on the discussion. In particular, the relativistic Euler equations on $(\mathbb{R} \times \mathbb{T}^3, \eta)$ take the same form that they take in Theorem 3.1. The advantage of the compact spatial topology is that it allows for a simplified approach to some technical aspects of the proof of local well-posedness. However, the arguments that we give in this section feature all of the main ideas needed to prove local well-posedness on the standard Minkowski spacetime background (in which the spacetime manifold is diffeomorphic to \mathbb{R}^{1+3}).

9.1. Notation, Norms, and Basic Tools from Analysis

9.1.1. Notation. Throughout this section, $\{x^\alpha\}_{\alpha=0,1,2,3}$ denote standard rectangular coordinates on $\mathbb{R} \times \mathbb{T}^3$, where $\{x^a\}_{a=1,2,3}$ are standard local coordinates on \mathbb{T}^3 , and we often use the alternate notation $t := x^0$. Note that even though $\{x^a\}_{a=1,2,3}$ are only locally defined on \mathbb{T}^3 , the coordinate partial derivative vectorfields $\{\partial_a\}_{a=1,2,3}$ can be extended to a smooth global frame on \mathbb{T}^3 ; by a slight abuse of notation, we will denote the globally defined “spatial” frame by $\{\partial_a\}_{a=1,2,3}$, and the corresponding globally defined “spacetime frame” by $\{\partial_\alpha\}_{\alpha=0,1,2,3}$. Also, we often use the alternate partial derivative notation $\partial_t := \partial_0$.

$$\Sigma_t := \{(t, x) \mid x \in \mathbb{T}^3\} \quad (9.1)$$

denotes the standard flat constant-time hypersurface.

Throughout Sect. 9, we use the same conventions for lowering and raising indices stated in Sect. 2.1, i.e., we lower and raise indices with the Minkowski metric and its inverse. Note that for Latin “spatial” indices, this is equivalent to lowering and raising via the Euclidean metric $\delta_{ij} = \text{diag}(1, 1, 1)$ and its inverse $\delta^{ij} = \text{diag}(1, 1, 1)$. Finally, we note that we sometimes identify the Euclidean metric or its inverse with the Kronecker delta.

To each “spatial multi-index” $\vec{I} = (\iota_1, \iota_2, \iota_3)$, where the ι_a are non-negative integers, we associate the spatial differential operator $\partial_{\vec{I}} := \partial_1^{\iota_1} \partial_2^{\iota_2} \partial_3^{\iota_3}$. Note that $\partial_{\vec{I}}$ is an operator of order $|\vec{I}| := \iota_1 + \iota_2 + \iota_3$.

If V is a spacetime vectorfield or a one-form, then \underline{V} denotes the η -orthogonal projection of V onto Σ_t , that is, the “spatial part” of V . For example, $\underline{\varpi}$ is the vectorfield on Σ_t with rectangular components $\underline{\varpi}^i := \varpi^i$ for $i = 1, 2, 3$. Moreover, we use the notation

$${}^{(3)}\text{curl}^i(W) := \epsilon^{ijk} \partial_j W_k \quad (9.2)$$

to denote the standard Euclidean curl operator acting on one-forms on Σ_t , where ϵ^{ijk} is the fully antisymmetric symbol normalized by $\epsilon^{123} = 1$.

9.1.2. Norms.

Definition 9.1 (*Lebesgue and Sobolev norms*). We define the following Lebesgue norms for scalar functions f :

$$\|f\|_{L^\infty(\mathbb{T}^3)} := \text{ess sup}_{x \in \mathbb{T}^3} |f(x)|, \quad (9.3)$$

$$\|f\|_{L^2(\mathbb{T}^3)} := \left\{ \int_{\mathbb{T}^3} f^2(x) dx \right\}^{1/2}, \quad (9.4)$$

where in the rest of Sect. 9, $dx := dx^1 dx^2 dx^3$ denotes the standard volume form on \mathbb{T}^3 induced by the Euclidean metric $\text{diag}(1, 1, 1)$.

Remark 9.2 (Extending the definitions of the norms from \mathbb{T}^3 to Σ_t). In our proof of local well-posedness, we will use norms in which the manifold \mathbb{T}^3 from Definition 9.1 is replaced with the constant time slice $\Sigma_t = \{t\} \times \mathbb{T}^3$, which is diffeomorphic to \mathbb{T}^3 . We will not explicitly define these norms along Σ_t since their definitions are obvious analogs of the ones appearing in Definition 9.1. For example, $\|f\|_{L^2(\Sigma_t)} := \left\{ \int_{\Sigma_t} f^2(t, x) dx \right\}^{1/2}$, which is also equal to $\left\{ \int_{\mathbb{T}^3} f^2(t, x) dx \right\}^{1/2}$. Here, we are using that the volume form induced by the Minkowski metric on Σ_t equals dx . Similar remarks apply to other norms on \mathbb{T}^3 introduced later in this subsubsection.

We define the following Sobolev norms for integers $r \geq 0$:

$$\|f\|_{H^r(\mathbb{T}^3)} := \left\{ \sum_{|\vec{I}| \leq r} \|\partial_{\vec{I}} f\|_{L^2(\mathbb{R}^3)}^2 \right\}^{1/2}, \quad (9.5a)$$

$$\|f\|_{\dot{H}^r(\mathbb{T}^3)} := \left\{ \sum_{|\vec{I}| = r} \|\partial_{\vec{I}} f\|_{L^2(\mathbb{R}^3)}^2 \right\}^{1/2}. \quad (9.5b)$$

If $r \in \mathbb{R}$ is not an integer, then we define²⁶

$$\|f\|_{H^r(\mathbb{T}^3)} := \left\{ \sum_{(k_1, k_2, k_3) \in \mathbb{Z}^3} (1 + |k|^2)^r \left| \hat{f}(k_1, k_2, k_3) \right|^2 \right\}^{1/2}, \quad (9.6)$$

where $\hat{f}(k_1, k_2, k_3) := \int_{\mathbb{T}^3} f(x) e^{-2\pi i \sum_{a=1}^3 x^a k_a} dx$ is the spatial Fourier transform of f and $|k|^2 := \sum_{a=1}^3 k_a^2$.

If $U = (U_1, \dots, U_m)$ is an array of scalar-valued functions and $\|\cdot\|$ denotes any of the norms introduced in this subsubsection, then we define

$$\|U\| := \sum_{a=1}^m \|U_a\|. \quad (9.7)$$

²⁶As is well known, when r is an integer, RHS (9.6) defines a norm that is equivalent to the norm defined in (9.5a).

Definition 9.3 (*Some additional function spaces*). If \mathfrak{B} is a Banach space with norm $\|\cdot\|_{\mathfrak{B}}$ and $r \geq 0$ is an integer, then $C^r([0, T], \mathfrak{B})$ denotes the space of r -times continuously differentiable functions from $[0, T]$ to \mathfrak{B} . We omit the superscript when $r = 0$. We denote the corresponding norm of an element f of this space by $\|f\|_{C^r([0, T], \mathfrak{B})} := \max_{t \in [0, T]} \sum_{k=0}^r \|f^{(k)}(t)\|_{\mathfrak{B}}$, where $f^{(k)}$ denotes the k th derivative of f with respect to t .

$L^\infty([0, T], \mathfrak{B})$ denotes the space of functions from $[0, T]$ to \mathfrak{B} that are essentially bounded over the interval $[0, T]$. We denote the corresponding norm of an element f of this space by $\|f\|_{L^\infty([0, T], \mathfrak{B})} := \text{ess sup}_{t \in [0, T]} \|f(t)\|_{\mathfrak{B}}$.

$C^r(\mathbb{T}^3)$ denotes the space of functions on \mathbb{T}^3 that are r -times continuously differentiable. We omit the superscript when $r = 0$. We denote the corresponding norm of an element f of this space by

$$\|f\|_{C^r(\mathbb{T}^3)} := \sum_{|\vec{I}| \leq r} \max_{x \in \mathbb{T}^3} |\partial_{\vec{I}} f(x)|.$$

We now fix, for the rest of Sect. 9, an integer N subject to

$$N \geq 3. \quad (9.8)$$

9.1.3. Basic Analytical Tools. In our analysis, we will rely on the following standard results; see, e.g., [1, 26, 38] for proofs.

Lemma 9.4 (Sobolev embedding, product, difference, and interpolation estimates). *If $r > 3/2$, then $H^r(\mathbb{T}^3)$ continuously embeds into $C(\mathbb{T}^3)$, and there exists a constant $C_r > 0$ such that the following estimate holds for $v \in H^r(\mathbb{T}^3)$:*

$$\|v\|_{C(\mathbb{T}^3)} \leq C_r \|v\|_{H^r(\mathbb{T}^3)}. \quad (9.9)$$

Let $r \geq 0$ be an integer and let $v := (v_1, \dots, v_A)$ and $w := (w_1, \dots, w_B)$ be finite-dimensional arrays of real-valued functions on \mathbb{T}^3 such that $v_a \in \dot{H}^r(\mathbb{T}^3) \cap C(\mathbb{T}^3)$ for $1 \leq a \leq A$ and $w_b \in C(\mathbb{T}^3)$ $1 \leq b \leq B$. Let

$$\mathcal{I}_r := \left\{ (\vec{I}_1, \dots, \vec{I}_A) \mid \sum_{a=1}^A |\vec{I}_a| = r \right\}. \quad (9.10)$$

Assume that $w(\mathbb{T}^3) \subset \text{int } \mathcal{K}$, where \mathcal{K} is a compact subset of \mathbb{R}^B , and let f be a smooth real-valued function on an open subset of \mathbb{R}^B containing \mathcal{K} . Then the following estimate holds:

$$\begin{aligned} & \max_{(\vec{I}_1, \dots, \vec{I}_A) \in \mathcal{I}_r} \left\| f(w) \prod_{a=1}^A \partial_{\vec{I}_a} v_a \right\|_{L^2(\mathbb{T}^3)} \\ & \leq C_{f, \mathcal{K}, r} \sum_{a=1}^A \|v_a\|_{\dot{H}^r(\mathbb{T}^3)} \prod_{b \neq a} \|w_b\|_{C(\mathbb{T}^3)}. \end{aligned} \quad (9.11)$$

Moreover, under the same assumptions stated in the previous paragraph, if $(\vec{I}_1, \dots, \vec{I}_A) \in \mathcal{I}_r$, then the map $(v, w) \rightarrow f(w) \prod_{a=1}^A \partial_{\vec{I}_a} v_a$ is continuous from $(\dot{H}^r(\mathbb{T}^3) \cap C(\mathbb{T}^3))^A \times (C(\mathbb{T}^3))^B$ to $L^2(\mathbb{T}^3)$. In particular, let $\delta = \delta_w > 0$

be such that the following holds²⁷: if $d(p, w(\mathbb{T}^3)) < \delta$, $d(q, w(\mathbb{T}^3)) < \delta$, and $d(p, q) < \delta$, where d is the standard Euclidean distance function on \mathbb{R}^B , then the straight-line segment joining p to q is contained in $\text{int } \mathcal{K}$. Then if (v, w) and (\tilde{v}, \tilde{w}) are two array pairs of the type described in the previous paragraph such that $\|w - \tilde{w}\|_{C(\mathbb{T}^3)} \leq \delta$, and if $r > 3/2$, then the following estimate holds (where the function f is assumed to be the same in both appearances on LHS (9.12) and \mathcal{I}_r is defined by (9.10)):

$$\begin{aligned} & \max_{(\tilde{I}_1, \dots, \tilde{I}_A) \in \mathcal{I}_r} \left\| f(w) \prod_{a=1}^A \partial_{\tilde{I}_a} v_a - f(\tilde{w}) \prod_{a=1}^A \partial_{\tilde{I}_a} \tilde{v}_a \right\|_{L^2(\mathbb{T}^3)} \\ & \leq C_{f, \mathcal{K}, \|v\|_{H^r(\mathbb{T}^3)}, \|\tilde{v}\|_{H^r(\mathbb{T}^3)}, A, r} \{ \|v - \tilde{v}\|_{H^r(\mathbb{T}^3)} + \|w - \tilde{w}\|_{C(\mathbb{T}^3)} \}. \end{aligned} \quad (9.12)$$

Furthermore, if $r > 3/2$ and $v_a \in H^r(\mathbb{T}^3)$ for $a = 1, 2$, then $v_1 v_2 \in H^r(\mathbb{T}^3)$, and there exists a constant $C_r > 0$ such that

$$\|v_1 v_2\|_{H^r(\mathbb{T}^3)} \leq C_r \|v_1\|_{H^r(\mathbb{T}^3)} \|v_2\|_{H^r(\mathbb{T}^3)}, \quad (9.13)$$

and function multiplication $(v_1, v_2) \rightarrow v_1 v_2$ is a continuous map from $H^r(\mathbb{T}^3) \times H^r(\mathbb{T}^3)$ to $H^r(\mathbb{T}^3)$.

Finally, if $0 \leq s \leq r$ and $v \in H^r(\mathbb{T}^3)$, then there exists a constant $C_{r,s} > 0$ such that

$$\|v\|_{H^s(\mathbb{T}^3)} \leq C_{r,s} \|v\|_{L^2(\mathbb{T}^3)}^{1-\frac{s}{r}} \|v\|_{H^r(\mathbb{T}^3)}^{\frac{s}{r}}. \quad (9.14)$$

Remark 9.5 (The same estimates hold along Σ_t). All of the results of Lemma 9.4 hold verbatim if we replace \mathbb{T}^3 by Σ_t throughout.

9.1.4. An L^2 -in-time Continuity Result for Transport Equations. We will use the following simple technical result in our proof of local well-posedness.

Lemma 9.6 (An L^2 -in-time continuity result for transport equations). *Let $T > 0$. Assume that $\mathcal{F} \in L^\infty([0, T], L^2(\mathbb{T}^3))$, and let f be the solution to the inhomogeneous transport equation initial value problem*

$$u^\alpha \partial_\alpha f = \mathcal{F}, \quad (9.15)$$

$$f|_{\Sigma_0} := \mathring{f} \in L^2(\Sigma_0). \quad (9.16)$$

Assume further that $u^\alpha \in L^\infty([0, T], C^1(\mathbb{T}^3))$ for $\alpha = 0, 1, 2, 3$. Then

$$f \in C([0, T], L^2(\mathbb{T}^3)). \quad (9.17)$$

Proof. We will prove right continuity at $t = 0$; continuity at any other time $t \in (0, T]$ could be proved using similar arguments. More precisely, we will show that

$$\lim_{t \downarrow 0} \|f(t, \cdot) - \mathring{f}\|_{L^2(\mathbb{T}^3)} = 0. \quad (9.18)$$

²⁷Such a $\delta > 0$ exists due to the compactness of $w(\mathbb{T}^3)$ and \mathcal{K} , where the compactness of $w(\mathbb{T}^3)$ follows from the assumption that the v_a are continuous.

To proceed, we let $\{\mathring{f}_k\}_{k=1}^\infty \subset C^\infty(\mathbb{T}^3)$ be a sequence of smooth functions such that

$$\|\mathring{f} - \mathring{f}_k\|_{L^2(\Sigma_0)} \leq \frac{1}{k}. \quad (9.19)$$

Note that

$$u^\alpha \partial_\alpha (f - \mathring{f}_k) = -u^a \partial_a \mathring{f}_k + \mathcal{F}. \quad (9.20)$$

Hence, a standard integration by parts argument based on the divergence identity

$$\begin{aligned} \partial_t \left\{ (f - \mathring{f}_k) \right\}^2 &= \left\{ \partial_a \left(\frac{u^a}{u^0} \right) \right\} (f - \mathring{f}_k)^2 \\ &\quad + 2 \frac{(f - \mathring{f}_k)}{u^0} \left\{ -u^a \partial_a \mathring{f}_k + \mathcal{F} \right\} \\ &\quad - \partial_a \left\{ \left(\frac{u^a}{u^0} \right) (f - \mathring{f}_k)^2 \right\} \end{aligned} \quad (9.21)$$

yields that for $0 \leq t \leq T$, we have

$$\begin{aligned} \|f - \mathring{f}_k\|_{L^2(\Sigma_t)}^2 &= \|\mathring{f} - \mathring{f}_k\|_{L^2(\Sigma_0)}^2 \\ &\quad + \int_{\tau=0}^t \int_{\Sigma_\tau} \left\{ \partial_a \left(\frac{u^a}{u^0} \right) \right\} (f - \mathring{f}_k)^2 \, dx \, d\tau \\ &\quad + 2 \int_{\tau=0}^t \int_{\Sigma_\tau} \frac{(f - \mathring{f}_k)}{u^0} \left\{ -u^a \partial_a \mathring{f}_k + \mathcal{F} \right\} \, dx \, d\tau. \end{aligned} \quad (9.22)$$

In particular, from (9.19), (9.22), our assumptions on \mathcal{F} and u^α , and Young's inequality, we find that if $0 \leq t \leq T$, then there is a constant C_T (independent of k) such that

$$\begin{aligned} \|f - \mathring{f}_k\|_{L^2(\Sigma_t)}^2 &\leq \frac{1}{k^2} + C_T \int_{\tau=0}^t \left\{ 1 + \|\mathring{f}_k\|_{H^1(\Sigma_0)}^2 \right\} \, d\tau \\ &\quad + C_T \int_{\tau=0}^t \|f - \mathring{f}_k\|_{L^2(\Sigma_\tau)}^2 \, d\tau. \end{aligned} \quad (9.23)$$

From (9.23) and Gronwall's inequality, we deduce (allowing C_T to vary from line to line in the rest of the proof) that if $0 \leq t \leq T$, then the following inequality holds:

$$\|f - \mathring{f}_k\|_{L^2(\Sigma_t)}^2 \leq \left\{ \frac{1}{k^2} + C_T t \left(1 + \|\mathring{f}_k\|_{H^1(\Sigma_0)}^2 \right) \right\} \exp(C_T t). \quad (9.24)$$

From (9.24), (9.19), and the triangle inequality, it follows that

$$\lim_{t \rightarrow 0^+} \sup_{0 \leq \tau \leq t} \|f - \mathring{f}\|_{L^2(\Sigma_\tau)} \leq \frac{2}{k}. \quad (9.25)$$

Finally, allowing $k \rightarrow \infty$ in (9.25), we conclude (9.18). We have therefore proved the lemma. \square

9.2. The Regime of Hyperbolicity

Our proof of well-posedness relies on a standard assumption, namely that the solution lies in the interior of the region of state space where the equations are hyperbolic without degeneracy. This notion is precisely captured by the next definition.

Definition 9.7 (*Regime of hyperbolicity*). We define the regime of hyperbolicity \mathcal{H} to be the following subset of state-space:

$$\mathcal{H} := \{(h, s, u^1, u^2, u^3) \in \mathbb{R}^5 \mid 0 < c(h, s) \leq 1\}. \quad (9.26)$$

9.3. Standard Local Well-Posedness

Our principal goal in this subsection is to state Theorem 9.12, which is our main local well-posedness result exhibiting the gain in regularity for the vorticity and entropy. Most aspects of the theorem are standard. We summarize these standard aspects in Theorem 9.10, which will serve as a precursor to our proof of Theorem 9.12.

Remark 9.8 (Some non-standard aspects of Theorem 9.12). One of the non-standard aspects of Theorem 9.12 is that it shows the continuous time dependence of the top-order derivatives of ϖ and s in the norm $\|\cdot\|_{L^2(\Sigma_t)}$. The proof relies on some results that are not easy to locate in the literature, tied in part to the fact that the required estimates are of elliptic–hyperbolic type. In our proof of Theorem 9.12, we will show how to obtain these top-order time-continuity results. A second non-standard aspect of Theorem 9.12 is that the transport-div-curl systems [specifically (3.9a)–(3.9b) and (3.11a)–(3.11b)] leading to the gain in regularity for ϖ and s involve *spacetime* divergence and curl operators. Hence, additional arguments are needed to obtain the needed *spatial* elliptic estimates along Σ_t ; the key ingredients in this vein are provided by the identity (9.34) and Lemma 9.20.

Remark 9.9 (The “fundamental” initial data). In the rest of Sect. 9, we view $\mathring{h} := h|_{\Sigma_0}$, $\mathring{s} := s|_{\Sigma_0}$, and $\mathring{u}^i := u^i|_{\Sigma_0}$ to be the “fundamental” initial data in the following sense: with the help of the relativistic Euler equations (2.17)–(2.19) + (2.20), along Σ_0 , all of the other quantities that are relevant for our analysis can be expressed in term of the fundamental initial data; see Lemma 9.17.

Theorem 9.10 (Standard local Well-Posedness). *Let $\mathring{h} := h|_{\Sigma_0}$, $\mathring{s} := s|_{\Sigma_0}$, and $\mathring{u}^i := u^i|_{\Sigma_0}$ be initial data²⁸ for the relativistic Euler equations (2.17)–(2.19) + (2.20). Assume that for some integer $N \geq 3$, we have*

$$\mathring{h}, \mathring{s}, \mathring{u}^i \in H^N(\Sigma_0). \quad (9.27)$$

Assume moreover that there is a compact subset $\mathfrak{K} \subset \text{int}\mathcal{H}$ (where $\text{int}\mathcal{H}$ is the interior of \mathcal{H}) such that for all $p \in \Sigma_0$, we have

$$(\mathring{h}(p), \mathring{s}(p), \mathring{u}^1(p), \mathring{u}^2(p), \mathring{u}^3(p)) \in \text{int}\mathfrak{K}.$$

²⁸The datum $u^0|_{\Sigma_0}$ is determined from the other data by virtue of the constraint (2.20).

Then there exists a time $T > 0$ depending only on²⁹ \mathfrak{K} , $\|\mathring{h}\|_{H^3(\Sigma_0)}$, $\|\mathring{s}\|_{H^3(\Sigma_0)}$, and $\|\mathring{u}^i\|_{H^3(\Sigma_0)}$, such that a unique classical solution $(h, s, u^\alpha, \varpi^\alpha)$ exists on the slab $[0, T] \times \mathbb{T}^3$ and satisfies $(h(p), s(p), u^1(p), u^2(p), u^3(p)) \in \text{int}\mathfrak{K}$ for $p \in [0, T] \times \mathbb{T}^3$. Moreover, the solution depends continuously on the initial data,³⁰ and its components relative to the standard coordinates enjoy the following regularity properties:

$$h, s, u^\alpha \in C([0, T], H^N(\mathbb{T}^3)), \quad (9.28a)$$

$$S^\alpha, \varpi^\alpha \in C([0, T], H^{N-1}(\mathbb{T}^3)). \quad (9.28b)$$

Proof. (Discussion of the proof). Theorem 9.10 is standard. Readers can consult, for example, [31] for detailed proofs in the case of the relativistic Euler equations on a family of conformally flat³¹ spacetimes. The main step in the proof is deriving a priori energy estimates for linearized versions of a first-order formulation of the equations, such as (2.17)–(2.19) + (2.20). For a first-order formulation that is equivalent (for C^1 solutions) to (2.17)–(2.19) + (2.20), this step was carried out in detail in [31] using the method of energy currents, a technique that originated in the context of the relativistic Euler equations in Christodoulou's foundational work [4] on shock formation. \square

Remark 9.11 (C^∞ data give rise to C^∞ solutions). In view of the Sobolev embedding result (9.9), we see that Theorem 9.10 implies that C^∞ initial data give rise to (local-in-time) C^∞ solutions.

We now state our main local well-posedness theorem. Its proof is located in Sect. 9.7.

Theorem 9.12 (Local well-posedness with improved regularity for the entropy and vorticity). *Assume the hypotheses of Theorem 9.10, but in addition to (9.27), assume also that the initial vorticity and entropy enjoy one extra degree of Sobolev regularity. That is, assume that for some integer $N \geq 3$ and $i = 1, 2, 3$, we have*

$$\mathring{h}, \mathring{u}^i \in H^N(\Sigma_0), \quad (9.29a)$$

$$\mathring{s}, \mathring{\varpi}^i \in H^N(\Sigma_0), \quad (9.29b)$$

where ϖ is defined in (2.5) and $\mathring{\varpi}^i := \varpi|_{\Sigma_0}^i$.

Then the conclusions of Theorem 9.10 hold, and the solution's components relative to standard coordinates enjoy the following regularity properties for

²⁹In fact, using additional arguments not presented here, one can show that for any fixed real number $r > 5/2$, the time of existence can be controlled by a function of \mathfrak{K} , $\|\mathring{h}\|_{H^r(\Sigma_0)}$, $\|\mathring{s}\|_{H^r(\Sigma_0)}$, and $\|\mathring{u}^i\|_{H^r(\Sigma_0)}$. Of course, if the initial data enjoy additional Sobolev regularity, then the additional regularity persists in the solution during its classical lifespan.

³⁰In particular, there is a $(H^3(\Sigma_0))^5$ -neighborhood of $(\mathring{h}, \mathring{s}, \mathring{u}^i)$ such that all data in the neighborhood launch solutions that exist on the same slab $[0, T] \times \mathbb{T}^3$ and, assuming also that the data belong to $(H^N(\Sigma_0))^5$, enjoy the regularity properties stated in the theorem.

³¹More precisely, in [31], the spacetime metrics are scalar function multiples of the Minkowski metric on \mathbb{R}^{1+3} .

$\alpha = 0, 1, 2, 3$, where $T > 0$ is the same time from Theorem 9.10:

$$h, u^\alpha \in C([0, T], H^N(\mathbb{T}^3)), \quad (9.30a)$$

$$s \in C([0, T], H^{N+1}(\mathbb{T}^3)), \quad S^\alpha, \varpi^\alpha \in C([0, T], H^N(\mathbb{T}^3)). \quad (9.30b)$$

In particular, according to (9.30b), the additional regularity of the entropy and vorticity featured in the initial data is propagated by the flow of the equations. Moreover, the solution depends continuously on the initial data relative the norms corresponding to (9.30a)–(9.30b).

9.4. A New Inverse Riemannian Metric and the Classification of Various Combinations of Solution Variables

In our proof of Theorem 9.12, when controlling the top-order derivatives of the vorticity and entropy, we will rely on “geometrically sharp” elliptic estimates in which the precise details of the principal coefficients of the elliptic operators are important for our arguments. Due to the quasilinear nature of the relativistic Euler equations, these precise elliptic estimates involve the inverse Riemannian metric G^{-1} from the next definition. In particular, we will need to use G^{-1} -based norms when proving that the top-order derivatives of ϖ and S are continuous in time with values in $L^2(\mathbb{T}^3)$ [these facts are contained within the statement (9.30b)]; the role of G^{-1} in our analysis will become clear in Sect. 9.7.

Definition 9.13 (*An inverse Riemannian metric on Σ_t*). On each Σ_t , we define the inverse Riemannian metric G^{-1} as follows:

$$(G^{-1})^{ij} := \delta^{ij} - \frac{u^i u^j}{(u^0)^2}, \quad (9.31)$$

where $\delta^{ij} := \text{diag}(1, 1, 1)$ is the standard Kronecker delta.

Remark 9.14 From the relation $\eta_{\alpha\beta} u^\alpha u^\beta = -1$, one can easily show that G^{-1} is Riemannian, that is, of signature $(+, +, +)$.

In proving that the solution depends continuously on the initial data, we will use a modified version of Kato’s framework [17–19]. His framework was designed to handle hyperbolic systems, while our formulation of the relativistic Euler equations is elliptic–hyperbolic. For this reason, we find it convenient to divide the solution variables into various classes, which we provide in the next definition. Roughly, we will handle the “hyperbolic quantities” using Kato’s framework, and to handle the remaining quantities, we will use elliptic estimates and algebraic relationships to control them in terms of the hyperbolic quantities.

Definition 9.15 (*Classification of various combinations of solution variables*). We define the *hyperbolic quantities* \mathbf{H} , the *elliptic quantities* \mathbf{E} , and the *algebraic quantities* $\mathbf{A}_\mathbf{H}$, $\mathbf{A}_{\mathbf{H}, \mathbf{E}}$, and \mathbf{A} as follows, where the Euclidean curl operator ${}^{(3)}\text{curl}$ is defined in (9.2):

$$\mathbf{H} := (h, s, u^a, \partial_a h, \partial_a u^b, \varpi^a, S^a, \mathcal{C}^a, \mathcal{D})_{a,b=1,2,3}, \quad (9.32a)$$

$$\mathbf{E} := (\partial_a \varpi_b, \partial_a S_b)_{a,b=1,2,3}, \quad (9.32b)$$

$$\begin{aligned} \mathbf{A}_{\mathbf{H}} &:= (u^0 - 1, \varpi^0, S^0, \mathcal{C}^0, \partial_t h, \partial_t u^\alpha, \partial_a u^0, \partial_t s)_{\alpha=0,1,2,3; a=1,2,3} \\ &\cup \left((G^{-1})^{cd} \partial_c \varpi_d, (G^{-1})^{cd} \partial_c S_d, {}^{(3)}\text{curl}^a(\underline{\varpi}), {}^{(3)}\text{curl}^a(\underline{S}) \right)_{a=1,2,3}, \end{aligned} \quad (9.32c)$$

$$\mathbf{A}_{\mathbf{H}, \mathbf{E}} := (\partial_t \varpi_\alpha, \partial_a \varpi_0, \partial_t S_\alpha, \partial_a S_0, \partial_b \varpi^b, \partial_b S^b)_{\alpha=0,1,2,3; a=1,2,3}, \quad (9.32d)$$

$$\mathbf{A} := \mathbf{A}_{\mathbf{H}} \cup \mathbf{A}_{\mathbf{H}, \mathbf{E}}. \quad (9.32e)$$

Some remarks are in order.

- The point of introducing the algebraic quantities \mathbf{A} is that, by virtue of the relativistic Euler equations, they can be algebraically expressed in terms of \mathbf{H} and \mathbf{E} (and thus are redundant); see Lemma 9.17. We stress that in (9.32c), it is crucial that the inverse metric G^{-1} is the one from Definition 9.13; the proof of (9.33a) will clarify that it is essential that the inverse metric is precisely G^{-1} .
- The elliptic quantities \mathbf{E} can be controlled (in appropriate Sobolev norms) in terms of \mathbf{H} via elliptic estimates; see Lemma 9.20 and its proof.
- The hyperbolic quantities \mathbf{H} solve evolution equations with source terms that depend on \mathbf{H} and \mathbf{E} . In view of the previous point, we see that one can bound the source terms (in appropriate Sobolev norms) in terms of \mathbf{H} . This will allow us to derive a closed system of energy inequalities that can be used to estimate \mathbf{H} . In view of the previous two points, we see that the estimates for \mathbf{H} imply corresponding estimates for \mathbf{E} and \mathbf{A} .

Remark 9.16 (The hyperbolic quantities verify first-order hyperbolic equations). In our proof of local well-posedness, we will use the fact that the hyperbolic quantities \mathbf{H} solve first-order hyperbolic equations. More precisely, the elements h , s , and u^a of (9.32a) satisfy the first-order hyperbolic system (2.17)–(2.19) + (2.20), the elements $\partial_a h$ and $\partial_a u^b$ satisfy hyperbolic equations obtained by taking one spatial derivative of the Eqs. (2.17)–(2.19) + (2.20), and S^a , ϖ^a , \mathcal{C}^a , and \mathcal{D} respectively satisfy the (spatial components of the) transport Eqs. (3.7), (3.8), (3.11b), and (3.9a); it is in this sense that we consider the variables \mathbf{H} to be “hyperbolic.”

Lemma 9.17 (Expressions for the algebraic quantities in terms of the hyperbolic and elliptic quantities). *Assume that (h, s, u^α) is a smooth solution to (2.17)–(2.19) + (2.20). Then we can express*

$$\mathbf{A}_{\mathbf{H}} = f(\mathbf{H}), \quad (9.33a)$$

$$\mathbf{A}_{\mathbf{H}, \mathbf{E}} = f(\mathbf{H}, \mathbf{E}), \quad (9.33b)$$

$$\mathbf{A} = f(\mathbf{H}, \mathbf{E}), \quad (9.33c)$$

where in (9.33a)–(9.33c), f is a schematically denoted smooth function that satisfies $f(0) = 0$ and that is allowed to vary from line to line.

Moreover, let \vec{I} be a spatial multi-index with $|\vec{I}| \geq 1$. Then

$$(G^{-1})^{ab} \partial_a \partial_{\vec{I}} \varpi_b, (G^{-1})^{ab} \partial_a \partial_{\vec{I}} S_b, {}^{(3)}\text{curl}^i (\partial_{\vec{I}} \varpi) \\ = \sum_{\substack{M=1 \\ |\vec{J}_1| + \dots + |\vec{J}_M| = |\vec{I}|}}^{|I|} f_{\vec{J}_1, \dots, \vec{J}_M}(\mathbf{H}) \prod_{m=1}^M \partial_{\vec{J}_m} \mathbf{H}. \quad (9.34)$$

where $f_{\vec{J}_1, \dots, \vec{J}_M}$ are schematically denoted smooth functions (not necessarily vanishing at 0) and $\prod_{m=1}^M \partial_{\vec{J}_m} \mathbf{H}$ schematically denotes an order M monomial in the derivatives of the elements of \mathbf{H} .

Proof. Throughout this proof, f is a smooth function that can vary from line to line and satisfies $f(0) = 0$ (except that the functions $f_{\vec{J}_1, \dots, \vec{J}_M}$ on RHS (9.34) do not necessarily satisfy $f_{\vec{J}_1, \dots, \vec{J}_M}(0) = 0$). Moreover, \mathbf{H} and \mathbf{E} are as defined in (9.32a) and (9.32b).

We first prove (9.33a). We must show that the elements of (9.32c) can be written as smooth functions of the elements of (9.32a) that vanish at 0. We first note that by the normalization condition $\eta_{\kappa\lambda} u^\kappa u^\lambda = -1$, $u^0 - 1$ is a smooth function of the spatial components of u that vanishes when $u^1 = u^2 = u^3 = 0$. From this fact and the identity $u^\kappa S_\kappa = 0$ [see (2.21)], we deduce that S^0 is a smooth function of the spatial components of u and S that vanishes at 0. A similar result holds for ϖ^0 by virtue of (4.2). Next, we note that, in view of the above discussion and the discussion surrounding Eq. (2.28), we can solve for the time derivatives of h , s , and u^α in terms of their spatial derivatives. Thus far, we have shown that $u^0 - 1$, ϖ^0 , S^0 , $\partial_t h$, $\partial_t u^\alpha$, $\partial_a u^0$, $\partial_t s$ can be expressed as $f(\mathbf{H})$. In the rest of the proof, we will use these facts without explicitly mentioning them every time. Next, we use definitions (2.4) and (2.16a) to deduce that $u^\kappa \mathcal{C}_\kappa = f(\mathbf{H})$. Using this equation to algebraically solve for \mathcal{C}^0 , we deduce that $\mathcal{C}^0 = f(\mathbf{H})$, as desired. We will now show that $(G^{-1})^{cd} \partial_c S_d = f(\mathbf{H})$. To begin, we use definition (2.16b) to deduce that $\partial_i S^i = \partial_\alpha S^\alpha - \partial_t S^0 = n\mathcal{D} - S^\kappa \partial_\kappa h + c^{-2} S^\kappa \partial_\kappa h - \partial_t S^0 = f(\mathbf{H}) - \partial_t S^0$. Next, using the identity $\partial_t = \frac{u^\kappa \partial_\kappa}{u^0} - \frac{u^i \partial_i}{u^0}$ and the evolution equation (3.7) with $\alpha = 0$, we find that $\partial_t S^0 = f(\mathbf{H}) - \frac{u^i \partial_i S^0}{u^0}$. Moreover, using (2.21), we find that $S^0 = \frac{S_i u^i}{u^0}$, from which we deduce that $\frac{u^i \partial_i S^0}{u^0} = f(\mathbf{H}) + \frac{u^i u^j \partial_i S_j}{(u^0)^2}$. Combining the above calculations, we find that $\partial_i S^i - \frac{u^i u^j \partial_i S_j}{(u^0)^2} = f(\mathbf{H})$ which, in view of definition (9.31), yields the desired relation $(G^{-1})^{cd} \partial_c S_d = f(\mathbf{H})$. The relation $(G^{-1})^{cd} \partial_c \varpi_d = f(\mathbf{H})$ can be proved using a similar argument based on Eqs. (3.8) and (3.11a), and we omit the details. To show that ${}^{(3)}\text{curl}^a(\varpi) = f(\mathbf{H})$, we first note that by definition (9.2), it suffices to show that $\partial_i \varpi_j - \partial_j \varpi_i = f(\mathbf{H})$ for $i, j = 1, 2, 3$. To proceed, we use (4.10) with $V := \varpi$ [which is applicable in view of (4.2)], definition (2.16a), and the transport Eq. (3.8) to deduce that $\partial_i \varpi_j - \partial_j \varpi_i = \epsilon_{ij\gamma\delta} u^\gamma \text{vort}^\delta(\varpi) + u_j u^\kappa \partial_\kappa \varpi_i - u_i u^\kappa \partial_\kappa \varpi_j + f(\mathbf{H}) = f(\mathbf{H})$, which is the desired result. The fact that ${}^{(3)}\text{curl}^a(S) = 0 = f(\mathbf{H})$ is a trivial consequence of the symmetry property (4.1) and definition (9.2). We have therefore proved (9.33a).

We now prove (9.33b). We must show that elements of (9.32d) can be written as smooth functions of the elements of (9.32a) and the elements of (9.32b) that vanish at 0. To handle $\partial_t \varpi_i$, we use the identity $\partial_t = \frac{u^\kappa \partial_\kappa}{u^0} - \frac{u^j \partial_j}{u^0}$ and the transport Eq. (3.8) to deduce that $\partial_t \varpi_i = \frac{u^\kappa \partial_\kappa \varpi_i}{u^0} + f(\mathbf{H}, \mathbf{E}) = f(\mathbf{H}, \mathbf{E})$ as desired. To handle $\partial_t \varpi_0$, we simply use (4.2) to obtain the identity $\varpi^0 = \frac{\varpi_j u^j}{u^0}$, differentiate this identity with respect to ∂_t , and then use the already proven facts that $\varpi_j, u^\alpha - \delta_0^\alpha$, and their time derivatives are equal to $f(\mathbf{H}, \mathbf{E})$. Similarly, by differentiating the identity $\varpi^0 = \frac{\varpi_j u^j}{u^0}$ with ∂_a , we conclude that $\partial_a \varpi_0 = f(\mathbf{H}, \mathbf{E})$. The relations $\partial_t S_\alpha = f(\mathbf{H}, \mathbf{E})$ and $\partial_a S_0 = f(\mathbf{H}, \mathbf{E})$ can be proved using a similar argument based on Eqs. (2.21) and (3.7), and we omit the details. The facts that $\partial_b \varpi^b = f(\mathbf{H}, \mathbf{E})$ and $\partial_b S^b = f(\mathbf{H}, \mathbf{E})$ follow trivially from the definitions. We have therefore proved (9.33b). Equation (9.33c) then follows from definition (9.32e) and (9.33a)–(9.33b).

To prove (9.34), we first note that definition (9.32c) and (9.33a) imply that $(G^{-1})^{ab} \partial_a \varpi_b$, $(G^{-1})^{ab} \partial_a S_b$, and ${}^{(3)}\text{curl}^i(\underline{\varpi})$ are all of the form $f(\mathbf{H})$. Hence, (9.34) follows from the Leibniz and chain rules and the definition (9.32a) of \mathbf{H} . \square

9.5. Elliptic Estimates and the Corresponding Energies

In this subsection, we construct the energies that we will use to control the top-order derivatives of the vorticity and entropy; see Definition 9.19. The proof that the energies are coercive relies on elliptic estimates; see the proof of Lemma 9.20. We start by defining a bilinear form on the relevant Hilbert space of functions. Lemma 9.20 shows that the bilinear form induces a norm on the Hilbert space.

Definition 9.18 (*A new Hilbert space inner product*). Let $(\underline{\varpi}, \underline{S})$ denote the array of spatial components of the vorticity and entropy gradient (i.e., the η -orthogonally projection of (ϖ, S) onto Σ_t , as in Sect. 9.1.1). Let $\alpha > 0$ be a parameter and let $M^{-1}(t, \cdot)$ be an inverse Riemannian metric on Σ_t . We define the following bilinear form on the corresponding Hilbert space $(H^N(\Sigma_t))^3 \times (H^N(\Sigma_t))^3$:

$$\begin{aligned} & \left\langle (\underline{\varpi}, \underline{S}), (\tilde{\underline{\varpi}}, \tilde{\underline{S}}) \right\rangle_{M^{-1}; \alpha}(t) \\ &:= \alpha \sum_{|\vec{I}|=N-1} \int_{\Sigma_t} \left\{ (M^{-1})^{ab} \partial_a \partial_{\vec{I}} \varpi_b \right\} \left\{ (M^{-1})^{cd} \partial_c \partial_{\vec{I}} \tilde{\varpi}_d \right\} dx \\ &+ \alpha \sum_{|\vec{I}|=N-1} \int_{\Sigma_t} \left\{ (M^{-1})^{ab} \partial_a \partial_{\vec{I}} S_b \right\} \left\{ (M^{-1})^{cd} \partial_c \partial_{\vec{I}} \tilde{S}_d \right\} dx \\ &+ \alpha \sum_{|\vec{I}|=N-1} \int_{\Sigma_t} (M^{-1})^{ab} (M^{-1})^{cd} \epsilon_{aci} \epsilon_{bdj} {}^{(3)}\text{curl}^i(\partial_{\vec{I}} \underline{\varpi}) {}^{(3)}\text{curl}^j(\partial_{\vec{I}} \tilde{\underline{\varpi}}) dx \\ &+ \alpha \sum_{|\vec{I}|=N-1} \int_{\Sigma_t} (M^{-1})^{ab} (M^{-1})^{cd} \epsilon_{aci} \epsilon_{bdj} {}^{(3)}\text{curl}^i(\partial_{\vec{I}} \underline{S}) {}^{(3)}\text{curl}^j(\partial_{\vec{I}} \tilde{\underline{S}}) dx \end{aligned}$$

$$+ \sum_{|\vec{I}| \leq N-1} \int_{\Sigma_t} \delta^{ab} (\partial_{\vec{I}} \varpi_a) (\partial_{\vec{I}} \tilde{\varpi}_b) \, dx + \sum_{|\vec{I}| \leq N-1} \int_{\Sigma_t} \delta^{ab} (\partial_{\vec{I}} S_a) (\partial_{\vec{I}} \tilde{S}_b) \, dx, \quad (9.35)$$

where δ^{ab} is the standard Kronecker delta and ϵ_{abc} is the fully antisymmetric symbol normalized by $\epsilon_{123} = 1$.

We now define the family of energies that we will use to control the top-order derivatives of the vorticity and entropy.

Definition 9.19 (“Elliptic” energy). Let $N \geq 3$ be an integer, let $\alpha > 0$ be a parameter (below we will choose it to be sufficiently small), and let $M^{-1}(t, \cdot)$ be a C^1 inverse Riemannian metric on Σ_t . We define the square of the “elliptic” energy $\mathbb{E}_{N; M^{-1}; \alpha}[(\varpi, S)] = \mathbb{E}_{N; M^{-1}; \alpha}[(\varpi, S)](t) \geq 0$ as follows:

$$\mathbb{E}_{N; M^{-1}; \alpha}^2[(\varpi, S)](t) := \langle (\varpi, S), (\varpi, S) \rangle_{M^{-1}; \alpha}(t). \quad (9.36)$$

In the next lemma, with the help of elliptic estimates, we exhibit the coercivity of $\mathbb{E}_{N; M^{-1}; \alpha}[(\varpi, S)](t)$. The lemma shows in particular that if $\alpha > 0$ is sufficiently small (depending on the inverse Riemannian metric M^{-1}), then the bilinear form from Definition 9.18 is a Hilbert space inner product.

Lemma 9.20 (Energy-norm comparison estimate based on elliptic estimates). *Let $T > 0$, and let $M^{-1} = M^{-1}(t, x)$ be an inverse Riemannian metric defined for $(t, x) \in [0, T] \times \mathbb{T}^3$. Let λ be the infimum of the eigenvalues of the 3×3 matrix $(M^{-1})^{ij}(t, x)$ over $(t, x) \in [0, T] \times \mathbb{T}^3$, and let Λ be the supremum of the eigenvalues of the 3×3 matrix $(M^{-1})^{ij}(t, x)$ over $(t, x) \in [0, T] \times \mathbb{T}^3$, and assume that $0 < \lambda \leq \Lambda < \infty$. Let $\mathbb{E}_{N; M^{-1}; \alpha}[(\varpi, S)]$ be as in Definition 9.19. There exist a small constant $\alpha_* > 0$ and a large constant $C > 0$ such that α_*^{-1} and C depend continuously in an increasing fashion on (i) $\max_{i,j=1,2,3} \|(M^{-1})^{ij}\|_{C([0,T], C^1(\mathbb{T}^3))}$; (ii) Λ ; and (iii) λ^{-1} , such that the following comparison estimates hold for $t \in [0, T]$:*

$$\mathbb{E}_{N; M^{-1}; \alpha_*}[(\varpi, S)](t) \leq C \sum_{a=1}^3 \|\varpi^a\|_{H^N(\Sigma_t)} + C \sum_{a=1}^3 \|S_a\|_{H^N(\Sigma_t)}, \quad (9.37a)$$

$$\sum_{a=1}^3 \|\varpi^a\|_{H^N(\Sigma_t)} + \sum_{a=1}^3 \|S_a\|_{H^N(\Sigma_t)} \leq C \mathbb{E}_{N; M^{-1}; \alpha_*}[(\varpi, S)](t). \quad (9.37b)$$

Proof. We prove only (9.37b) since (9.37a) can be proved using similar but simpler arguments. Throughout the proof, $C > 0$ denotes a constant with the dependence-properties stated in the lemma. To proceed, we note the following divergence identity for one-forms V on Σ_t , which can be directly verified:

$$\begin{aligned} & (M^{-1})^{ab} (M^{-1})^{cd} (\partial_a V_b) (\partial_c V_d) \\ & + \overbrace{\frac{1}{2} (M^{-1})^{ab} (M^{-1})^{cd} (\partial_a V_c - \partial_c V_a) (\partial_b V_d - \partial_d V_b)} \\ & + \frac{1}{2} (M^{-1})^{ab} (M^{-1})^{cd} \epsilon_{aci} \epsilon_{bdj} {}^{(3)}\text{curl}^i(V) {}^{(3)}\text{curl}^j(V) \end{aligned}$$

$$\begin{aligned}
&= (M^{-1})^{ab}(M^{-1})^{cd}(\partial_a V_c)(\partial_b V_d) \\
&\quad + \frac{1}{2} \{ \partial_a [(M^{-1})^{ab}(M^{-1})^{cd}] \} [V_c \partial_b V_d + V_c \partial_d V_b] \\
&\quad + \frac{1}{2} \{ \partial_c [(M^{-1})^{ab}(M^{-1})^{cd}] \} [V_a \partial_b V_d + V_a \partial_d V_b] \\
&\quad - \frac{1}{2} \{ \partial_b [(M^{-1})^{ab}(M^{-1})^{cd}] \} [V_a \partial_c V_d + V_c \partial_a V_d] \\
&\quad - \frac{1}{2} \{ \partial_d [(M^{-1})^{ab}(M^{-1})^{cd}] \} [V_a \partial_c V_b + V_c \partial_a V_b] \\
&\quad + \frac{1}{2} \partial_b \{ (M^{-1})^{ab}(M^{-1})^{cd} [V_a \partial_c V_d + V_c \partial_a V_d] \} \\
&\quad + \frac{1}{2} \partial_d \{ (M^{-1})^{ab}(M^{-1})^{cd} [V_a \partial_c V_b + V_c \partial_a V_b] \} \\
&\quad - \frac{1}{2} \partial_a \{ (M^{-1})^{ab}(M^{-1})^{cd} [V_c \partial_b V_d + V_c \partial_d V_b] \} \\
&\quad - \frac{1}{2} \partial_c \{ (M^{-1})^{ab}(M^{-1})^{cd} [V_a \partial_b V_d + V_a \partial_d V_b] \}. \tag{9.38}
\end{aligned}$$

We now integrate (9.38) over Σ_t with respect to dx and note that the integrals of the last four (perfect spatial derivative) terms on the right-hand side vanish. In view of our assumptions on the eigenvalues of $(M^{-1})^{ij}(t, \cdot)$, we see that the integral of the first term $(M^{-1})^{ab}(M^{-1})^{cd}(\partial_a V_c)(\partial_b V_d)$ on RHS (9.38) is $\geq \lambda^2 \sum_{a,b=1}^3 \|\partial_a V_b\|_{L^2(\Sigma_t)}^2$. Also using Young's inequality, we see that the integrals of the second through fifth terms on RHS (9.38) (in which a derivative falls on M^{-1}) are collectively bounded from below by $\geq -\frac{\lambda^2}{2} \sum_{a,b=1}^3 \|\partial_a V_b\|_{L^2(\Sigma_t)}^2 - \frac{C}{\lambda^2} \sum_{a=1}^3 \|V_a\|_{L^2(\Sigma_t)}^2$. It follows that the integral of (9.38) is bounded from below by

$$\geq \frac{\lambda^2}{2} \sum_{a,b=1}^3 \|\partial_a V_b\|_{L^2(\Sigma_t)}^2 - \frac{C}{\lambda^2} \sum_{a=1}^3 \|V_a\|_{L^2(\Sigma_t)}^2.$$

The desired estimate (9.37b) now follows from these considerations with ϖ and \underline{S} in the role of V , and definitions (9.35) and (9.36), where $\alpha := \alpha_* > 0$ is chosen so that $\alpha_* \frac{C}{\lambda^2} = \frac{1}{2}$, and $\frac{C}{\lambda^2}$ is the (absolute value of the) coefficient from the previous inequality. We clarify that, by our conventions, factors of $\frac{1}{\lambda^2}$ can be absorbed into the constant C on RHS (9.37b). \square

In the next lemma, we show that some Sobolev norms of the elliptic variables \mathbf{E} can be bounded by corresponding Sobolev norms of the hyperbolic variables \mathbf{H} . We also derive related estimates for the difference of two solutions. The main ingredients in the proofs are the elliptic estimates provided by Lemma 9.20.

Lemma 9.21 (Controlling Sobolev norms of the elliptic variables in terms of Sobolev norms of the hyperbolic variables).

(A) Let $\mathring{h} := h|_{\Sigma_0}$, $\mathring{s} := s|_{\Sigma_0}$, and $\mathring{u}^i := u^i|_{\Sigma_0}$ be initial data for the relativistic Euler equations (2.17)–(2.19) + (2.20), let $\mathring{\varpi}^i := \varpi^i|_{\Sigma_0}$, and let (h, s, u^α)

be the solution provided by Theorem 9.10. In particular, let $N \geq 3$ be an integer, let $[0, T] \times \mathbb{T}^3$ be the slab of existence provided by the theorem, and let \mathfrak{K} be the set featured in Theorem 9.10. Assume in addition that the rectangular components of the initial data are elements of $C^\infty(\Sigma_0)$, and note that by Theorem 9.10 and the Sobolev embedding result (9.9), the rectangular components of the solution belong to $C^\infty([0, T] \times \mathbb{T}^3)$. Let \mathbf{E} and \mathbf{H} be the corresponding elliptic and hyperbolic variables as defined in Definition 9.15. Then there exists a constant $C > 0$, depending only on:

1. N
2. \mathfrak{K}
3. $\|\mathring{h}\|_{H^N(\Sigma_0)} + \|\mathring{s}\|_{H^{N+1}(\Sigma_0)} + \sum_{a=1}^3 \|\mathring{u}^a\|_{H^N(\Sigma_0)} + \sum_{a=1}^3 \|\mathring{\varpi}^a\|_{H^N(\Sigma_0)}$
- 4.

$$\begin{aligned} & \|h\|_{C([0, T], C^1(\mathbb{T}^3))} + \|s\|_{C([0, T], C^1(\mathbb{T}^3))} + \sum_{a=1}^3 \|u^a\|_{C([0, T], C^1(\mathbb{T}^3))} \\ & + \sum_{a=1}^3 \|S^a\|_{C([0, T], C^1(\mathbb{T}^3))} + \sum_{a=1}^3 \|\varpi^a\|_{C([0, T], C^1(\mathbb{T}^3))}, \end{aligned}$$

such that the following estimate holds for $t \in [0, T]$:

$$\|\mathbf{E}\|_{H^{N-1}(\Sigma_t)} \leq C \|\mathbf{H}\|_{H^{N-1}(\Sigma_t)}. \quad (9.39)$$

(B) For $i = 1, 2$, let $(h_{(i)}, s_{(i)}, u_{(i)})$ be classical solutions to the relativistic Euler equations (2.17)–(2.19) + (2.20) that have the properties stated in part (A). Assume that the slab of existence $[0, T] \times \mathbb{T}^3$ is the same for both solutions and that the set \mathfrak{K} is the same for both solutions, that is, that there exists a compact set $\mathfrak{K} \subset \text{int}\mathcal{H}$ such that for $i = 1, 2$, we have $(h_{(i)}, s_{(i)}, u_{(i)}^1, u_{(i)}^2, u_{(i)}^3)([0, T] \times \mathbb{T}^3) \subset \text{int}\mathfrak{K}$. Let $\mathbf{E}_{(i)}$ and $\mathbf{H}_{(i)}$ be the corresponding elliptic and hyperbolic variables as defined in Definition 9.15. Then there exist constants $\delta > 0$ and $C > 0$, depending only on:

1. N
2. \mathfrak{K}
- 3.
- 4.

$$\begin{aligned} & \sum_{i=1}^2 \left\{ \|\mathring{h}_{(i)}\|_{H^N(\Sigma_0)} + \|\mathring{s}_{(i)}\|_{H^{N+1}(\Sigma_0)} + \sum_{a=1}^3 \|\mathring{u}_{(i)}^a\|_{H^N(\Sigma_0)} + \sum_{a=1}^3 \|\mathring{\varpi}_{(i)}^a\|_{H^N(\Sigma_0)} \right\} \\ & \sum_{i=1}^2 \left\{ \|h_{(i)}\|_{C([0, T], C^1(\mathbb{T}^3))} + \|s_{(i)}\|_{C([0, T], C^1(\mathbb{T}^3))} + \sum_{a=1}^3 \|u_{(i)}^a\|_{C([0, T], C^1(\mathbb{T}^3))} \right. \\ & \left. + \sum_{a=1}^3 \|S_{(i)}^a\|_{C([0, T], C^1(\mathbb{T}^3))} + \sum_{a=1}^3 \|\varpi_{(i)}^a\|_{C([0, T], C^1(\mathbb{T}^3))} \right\} \end{aligned}$$

5.

$$\sum_{i=1}^2 \left\{ \|h_{(i)}\|_{C([0,T], H^N(\mathbb{T}^3))} + \sum_{a=1}^3 \|u_{(i)}^a\|_{C([0,T], H^N(\mathbb{T}^3))} \right. \\ \left. + \|s_{(i)}\|_{C([0,T], H^{N+1}(\mathbb{T}^3))} + \sum_{a=1}^3 \|\varpi_{(i)}^a\|_{C([0,T], H^N(\mathbb{T}^3))} \right\},$$

such that if $\|\mathbf{H}_{(1)} - \mathbf{H}_{(2)}\|_{C(\Sigma_t)} \leq \delta$, then the following estimate holds for $t \in [0, T]$:

$$\|\mathbf{E}_{(1)} - \mathbf{E}_{(2)}\|_{H^{N-1}(\Sigma_t)} \leq C\|\mathbf{H}_{(1)} - \mathbf{H}_{(2)}\|_{H^{N-1}(\Sigma_t)}. \quad (9.40)$$

Proof. Throughout this proof, C denotes a constant with the dependence-properties stated in the lemma. We begin by establishing (9.39). Invoking definitions (9.32a), (9.32b), (9.35), and (9.36), using the fact that ${}^{(3)}\text{curl}(\underline{S}) = 0$ [see (4.1)], and using the estimate (9.37b) with $M^{-1} := G^{-1}$ and with $\alpha_* > 0$ as in the statement of Lemma 9.20 (where G^{-1} is defined in Definition 9.13, and we stress that the proof of (9.37b) relied on elliptic estimates), we find that

$$\begin{aligned} \|\mathbf{E}\|_{H^{N-1}(\Sigma_t)} &\leq C\mathbb{E}_{N;G^{-1};\alpha_*}[(\varpi, \underline{S})](t) \\ &\leq C \sum_{|\vec{I}|=N-1} \| (G^{-1})^{ab} \partial_a \partial_{\vec{I}} \varpi_b \|_{L^2(\Sigma_t)} \\ &\quad + C \sum_{|\vec{I}|=N-1} \| (G^{-1})^{ab} \partial_a \partial_{\vec{I}} S_b \|_{L^2(\Sigma_t)} \\ &\quad + C \sum_{|\vec{I}|=N-1} \sum_{a=1}^3 \| {}^{(3)}\text{curl}^a(\partial_{\vec{I}} \varpi) \|_{L^2(\Sigma_t)} \\ &\quad + C\|\mathbf{H}\|_{H^{N-1}(\Sigma_t)}. \end{aligned} \quad (9.41)$$

Next, using (9.34), we see that the terms $(G^{-1})^{ab} \partial_a \partial_{\vec{I}} \varpi_b$, $(G^{-1})^{ab} \partial_a \partial_{\vec{I}} S_b$, and ${}^{(3)}\text{curl}^a(\partial_{\vec{I}} \varpi)$ on RHS (9.41) are smooth functions of \mathbf{H} and its spatial derivatives. Thus, using inequality (9.11) to bound RHS (9.34) in the norm $\|\cdot\|_{L^2(\Sigma_t)}$, we arrive at the desired estimate (9.39). We stress that RHS (9.11) is *linear* in the order r derivatives of the solution; this is the reason that RHS (9.39) is linear in $\|\mathbf{H}\|_{H^{N-1}(\Sigma_t)}$.

We now prove (9.40). For $i = 1, 2$, we let $G_{(i)}^{-1}$ denote the inverse Riemannian metric corresponding to the i th solution, that is, the inverse Riemannian metric whose rectangular components are formed by evaluating RHS (9.31) at the solution corresponding to the labeling index i . To proceed, we use definitions (9.32a), (9.32b), (9.35), and (9.36), the fact that ${}^{(3)}\text{curl}(\underline{S}_{(1)}) = {}^{(3)}\text{curl}(\underline{S}_{(2)}) = 0$ [see (4.1)], and the comparison estimate (9.37b) with $M^{-1} := G_{(1)}^{-1}$ and with $\alpha_* > 0$ as in the statement of Lemma 9.20 to deduce that

$$\begin{aligned} \|\mathbf{E}_{(1)} - \mathbf{E}_{(2)}\|_{H^{N-1}(\Sigma_t)} &\leq C\mathbb{E}_{N;G_{(1)}^{-1};\alpha_*}[(\varpi_{(1)} - \varpi_{(2)}, \underline{S}_{(1)} - \underline{S}_{(2)})](t) \end{aligned}$$

$$\begin{aligned}
&\leq C \sum_{|\vec{I}|=N-1} \left\| (G_{(1)}^{-1})^{ab} \partial_a \partial_{\vec{I}} (\varpi_{(1)b} - \varpi_{(2)b}) \right\|_{L^2(\Sigma_t)} \\
&\quad + C \sum_{|\vec{I}|=N-1} \left\| (G_{(1)}^{-1})^{ab} \partial_a \partial_{\vec{I}} (S_{(1)b} - S_{(2)b}) \right\|_{L^2(\Sigma_t)} \\
&\quad + C \sum_{|\vec{I}|=N-1} \sum_{a=1}^3 \left\| {}^{(3)}\text{curl}^a \left(\partial_{\vec{I}} (\varpi_{(1)} - \varpi_{(2)}) \right) \right\|_{L^2(\Sigma_t)} \\
&\quad + C \|\mathbf{H}_{(1)} - \mathbf{H}_{(2)}\|_{H^{N-1}(\Sigma_t)}. \tag{9.42}
\end{aligned}$$

Next, using the triangle inequality, we find that

$$\begin{aligned}
&\text{RHS (9.42)} \\
&\leq C \sum_{|\vec{I}|=N-1} \left\| (G_{(1)}^{-1})^{ab} \partial_a \partial_{\vec{I}} \varpi_{(1)b} - (G_{(2)}^{-1})^{ab} \partial_a \partial_{\vec{I}} \varpi_{(2)b} \right\|_{L^2(\Sigma_t)} \\
&\quad + C \sum_{|\vec{I}|=N-1} \left\| (G_{(2)}^{-1})^{ab} - (G_{(1)}^{-1})^{ab} \right\|_{C(\Sigma_t)} \|\partial_a \partial_{\vec{I}} \varpi_{(2)b}\|_{L^2(\Sigma_t)} \\
&\quad + C \sum_{|\vec{I}|=N-1} \left\| (G_{(1)}^{-1})^{ab} \partial_a \partial_{\vec{I}} S_{(1)b} - (G_{(2)}^{-1})^{ab} \partial_a \partial_{\vec{I}} S_{(2)b} \right\|_{L^2(\Sigma_t)} \\
&\quad + C \sum_{|\vec{I}|=N-1} \left\| (G_{(2)}^{-1})^{ab} - (G_{(1)}^{-1})^{ab} \right\|_{C(\Sigma_t)} \|\partial_a \partial_{\vec{I}} S_{(2)b}\|_{L^2(\Sigma_t)} \\
&\quad + C \sum_{|\vec{I}|=N-1} \sum_{a=1}^3 \left\| {}^{(3)}\text{curl}^a (\partial_{\vec{I}} \varpi_{(1)}) - {}^{(3)}\text{curl}^a (\partial_{\vec{I}} \varpi_{(2)}) \right\|_{L^2(\Sigma_t)} \\
&\quad + C \|\mathbf{H}_{(1)} - \mathbf{H}_{(2)}\|_{H^{N-1}(\Sigma_t)}. \tag{9.43}
\end{aligned}$$

Using the assumed bounds $\sum_{|\vec{I}|=N-1} \sum_{a,b=1}^3 \|\partial_a \partial_{\vec{I}} \varpi_{(2)b}\|_{L^2(\Sigma_t)} \leq C$ and $\sum_{|\vec{I}|=N-1} \sum_{a,b=1}^3 \|\partial_a \partial_{\vec{I}} S_{(2)b}\|_{L^2(\Sigma_t)} \leq C$, (9.34), (9.9), and (9.12) (where the hypotheses needed to invoke (9.12) are satisfied if $\|\mathbf{H}_{(1)} - \mathbf{H}_{(2)}\|_{C(\Sigma_t)}$ is sufficiently small), we see that the terms on the first, third, and fifth lines of RHS (9.43) are $\leq C \|\mathbf{H}_{(1)} - \mathbf{H}_{(2)}\|_{H^{N-1}(\Sigma_t)}$ as desired. To handle the terms on the second and fourth lines of RHS (9.43), we use the assumed bounds

$$\sum_{|\vec{I}|=N-1} \sum_{a,b=1}^3 \|\partial_a \partial_{\vec{I}} \varpi_{(2)b}\|_{L^2(\Sigma_t)} \leq C, \quad \sum_{|\vec{I}|=N-1} \sum_{a,b=1}^3 \|\partial_a \partial_{\vec{I}} S_{(2)b}\|_{L^2(\Sigma_t)} \leq C,$$

the mean value theorem estimate $\left| (G_{(2)}^{-1})^{ab} - (G_{(1)}^{-1})^{ab} \right| \leq C |\mathbf{H}_{(1)} - \mathbf{H}_{(2)}|$ (where we are using that RHS (9.31) can be viewed as a smooth function of (u^1, u^2, u^3)), and the Sobolev embedding result (9.9) to deduce that the terms on the second and fourth lines of RHS (9.43) are $\leq C \|\mathbf{H}_{(1)} - \mathbf{H}_{(2)}\|_{C(\Sigma_t)} \leq C \|\mathbf{H}_{(1)} - \mathbf{H}_{(2)}\|_{H^{N-1}(\Sigma_t)}$ as desired. We have therefore proved (9.40). \square

9.6. Energies for the Wave Equations via the Vectorfield Multiplier Method

In this subsection, we derive a priori estimates for our new formulation of the relativistic Euler equations. The main result is provided by the next proposition. The proposition shows in particular that the vorticity and entropy are one degree more differentiable compared to the standard estimates that follow from first-order formulations of the equations. The main analytic tools in the proof of the proposition are the elliptic estimates from Sect. 9.5 and the vectorfield method for wave equations (see Sect. 9.6.1).

Proposition 9.22 (A priori estimates for solutions to the relativistic Euler equations). *Let $\mathring{h} := h|_{\Sigma_0}$, $\mathring{s} := s|_{\Sigma_0}$, and $\mathring{u}^i := u^i|_{\Sigma_0}$ be initial data for the relativistic Euler equations (2.17)–(2.19) + (2.20) obeying the assumptions of Theorem 9.10, and let $(h, s, u^0, u^1, u^2, u^3)$ be the corresponding solution. In particular, let $N \geq 3$ be an integer, let $[0, T] \times \mathbb{T}^3$ be the slab of existence provided by the theorem, and let \mathfrak{K} be the set featured in theorem. Assume in addition that the components of the initial data relative to standard coordinates belong to $C^\infty(\mathbb{T}^3)$ and note that by Remark 9.11, the solution components belong to $C^\infty([0, T] \times \mathbb{T}^3)$. Let ϖ be the vorticity (see Definition 2.2), and let $\mathring{\varpi}^i := \varpi^i|_{\Sigma_0}$ be its initial spatial components.*

Then there exists a constant $C > 0$, depending only on:

1. N
2. \mathfrak{K}
3. $\|\mathring{h}\|_{H^N(\Sigma_0)} + \sum_{a=1}^3 \|\mathring{u}^a\|_{H^N(\Sigma_0)} + \|\mathring{s}\|_{H^{N+1}(\Sigma_0)} + \sum_{a=1}^3 \|\mathring{\varpi}^a\|_{H^N(\Sigma_0)}$
- 4.

$$\begin{aligned} & \|h\|_{C([0, T], C^1(\mathbb{T}^3))} + \sum_{a=1}^3 \|u^a\|_{C([0, T], C^1(\mathbb{T}^3))} + \|s\|_{C([0, T], C^1(\mathbb{T}^3))} \\ & + \sum_{a=1}^3 \|S^a\|_{C([0, T], C^1(\mathbb{T}^3))} + \sum_{a=1}^3 \|\varpi^a\|_{C([0, T], C^1(\mathbb{T}^3))} \end{aligned}$$

such that for $t \in [0, T]$, the components of the solution relative to the standard coordinates verify the following estimates:

$$\begin{aligned} & \|h\|_{H^N(\Sigma_t)} + \sum_{a=0}^3 \|u^\alpha - \delta_0^\alpha\|_{H^N(\Sigma_t)} + \|s\|_{H^{N+1}(\Sigma_t)} \\ & + \sum_{\alpha=0}^3 \|S^\alpha\|_{H^N(\Sigma_t)} + \sum_{\alpha=0}^3 \|\varpi^\alpha\|_{H^N(\Sigma_t)} \\ & \leq C \exp(Ct) \leq C \exp(CT) := C_*, \end{aligned} \tag{9.44}$$

where δ_0^α is the Kronecker delta.

The proof of Proposition 9.22 is located in Sect. 9.6.4. We will first derive some preliminary results. We start by noting that we can rewrite the spatial components of (3.1), (3.3), (3.7), (3.8), (3.9a), and (3.11b) in concise form as follows, where f denotes a smooth function of its arguments that is free to vary from line to line and that satisfies $f(0) = 0$, \underline{V} denotes η -orthogonal projection

of V onto constant-time hypersurfaces (see Sect. 9.1.1), and the hyperbolic variables \mathbf{H} and the elliptic variables \mathbf{E} are as in Definition 9.15:

$$\square_g h = f(\mathbf{H}), \quad (9.45a)$$

$$\square_g u = f(\mathbf{H}), \quad (9.45b)$$

$$u^\alpha \partial_\alpha \underline{S} = f(\mathbf{H}), \quad (9.45c)$$

$$u^\alpha \partial_\alpha \underline{\varpi} = f(\mathbf{H}), \quad (9.45d)$$

$$u^\alpha \partial_\alpha \mathcal{D} = f(\mathbf{H}, \mathbf{E}), \quad (9.45e)$$

$$u^\alpha \partial_\alpha \underline{\mathcal{C}} = f(\mathbf{H}, \mathbf{E}). \quad (9.45f)$$

The crux of the proof of Proposition 9.22 is to derive energy estimates for the covariant wave equations (9.45a) and (9.45b), energy estimates for the transport equations (9.45c), (9.45d), (9.45e), and (9.45f), and elliptic estimates to handle the terms \mathbf{E} on RHSs (9.45e) and (9.45f). We have already derived the necessary elliptic estimates in Sect. 9.5. In the next three subsections, we will outline the energy estimates, which are standard.

9.6.1. Energy Estimates for Covariant Wave Equations. The wave operator in (9.45a) and (9.45b) is with respect to the acoustical metric g introduced in Definition 2.6. These are covariant wave equations for the scalar quantities h and u^α . Estimates for such equations can be derived by using the well-known vectorfield multiplier method³² for wave equations, which we outline in this subsubsection.

Let φ be any element of $\{h, u^1, u^2, u^3\}$ (in practice, we will not need to derive separate energy estimates for u^0 since estimates for u^0 can be obtained as a consequence of the estimates for the spatial components of u and the normalization condition $\eta_{\kappa\lambda} u^\kappa u^\lambda = -1$). We start by defining the energy-momentum tensor associated to a scalar function φ :

$$T_{\alpha\beta} = T_{\alpha\beta}[\varphi] := (\partial_\alpha \varphi)(\partial_\beta \varphi) - \frac{1}{2} g_{\alpha\beta} (g^{-1})^{\mu\nu} (\partial_\mu \varphi)(\partial_\nu \varphi). \quad (9.46)$$

A crucial property of $T_{\alpha\beta}$ is that it satisfies the *dominant energy condition*: $T_{\alpha\beta} X^\alpha Y^\beta \geq 0$ whenever the vectorfields X and Y are future-directed³³ and timelike³⁴ with respect to g . In practice, the dominant energy condition allows one to construct energies that are *coercive* along causal (with respect to g) hypersurfaces,³⁵ see Eq. (9.56) below for the energy that we use in deriving a priori estimates for h and u .

³²In deriving a priori estimates, in addition to the multiplier method, we will use only the simplest version of the vectorfield commutator method. Specifically, we will commute the equations only with the coordinate spatial derivative operators $\partial_{\vec{I}}$.

³³By a “future-directed” vectorfield X , we mean that $X^0 > 0$.

³⁴ X is defined to be timelike with respect to g if $g_{\alpha\beta} X^\alpha X^\beta < 0$.

³⁵By a “causal hypersurface,” we mean a hypersurface whose future-directed unit normal is either timelike with respect to g or null with respect to g at each point.

Next, for any vectorfield X (soon to be employed in the role of a “multiplier vectorfield”), we let ${}^{(X)}\pi$ be its deformation tensor relative to g , which takes the following form relative to arbitrary coordinates:

$${}^{(X)}\pi_{\alpha\beta} := g_{\beta\mu} \nabla_\alpha X^\mu + g_{\alpha\mu} \nabla_\beta X^\mu. \quad (9.47)$$

In (9.47) and in the rest of this subsubsection, ∇ is the covariant derivative induced by g . Next, we define the *energy current* vectorfield corresponding to X as follows:

$$(X)J^\alpha = {}^{(X)}J^\alpha[\varphi] := (g^{-1})^{\alpha\mu} T_{\mu\beta}[\varphi] X^\beta - X^\alpha \varphi^2. \quad (9.48)$$

From straightforward computations, we derive the following identity:

$$\begin{aligned} \nabla_\alpha {}^{(X)}J^\alpha &= (\square_g \varphi) X^\alpha \partial_\alpha \varphi + \frac{1}{2} (g^{-1})^{\alpha\gamma} (g^{-1})^{\beta\delta} T_{\alpha\beta} {}^{(X)}\pi_{\gamma\delta} \\ &\quad - (\nabla_\alpha X^\alpha) \varphi^2 - 2\varphi (X^\alpha \partial_\alpha \varphi). \end{aligned} \quad (9.49)$$

Applying the divergence theorem on the spacetime slab $[0, T] \times \mathbb{T}^3$ and using (9.49), we deduce the following identity:

$$\begin{aligned} &\int_{\Sigma_t} g_{\alpha\beta} {}^{(X)}J^\alpha[\varphi] \hat{N}^\beta \, d\mu_{\underline{g}} \\ &= \int_{\Sigma_0} g_{\alpha\beta} {}^{(X)}J^\alpha[\varphi] \hat{N}^\beta \, d\mu_{\underline{g}} \\ &\quad - \int_{[0, t] \times \mathbb{T}^3} \left\{ (\square_g \varphi) X^\alpha \partial_\alpha \varphi + \frac{1}{2} (g^{-1})^{\alpha\gamma} (g^{-1})^{\beta\delta} T_{\alpha\beta} {}^{(X)}\pi_{\gamma\delta} \right\} \, d\mu_g \\ &\quad + \int_{[0, t] \times \mathbb{T}^3} \left\{ (\nabla_\alpha X^\alpha) \varphi^2 + 2\varphi (X^\alpha \partial_\alpha \varphi) \right\} \, d\mu_g. \end{aligned} \quad (9.50)$$

In (9.50), $d\mu_g$ is the volume form that g induces on $[0, t] \times \mathbb{T}^3$, \hat{N} is the future-directed unit normal to Σ_t with respect to the metric g , and $d\mu_{\underline{g}}$ is the volume form that \underline{g} induces on Σ_t , where \underline{g} is the first fundamental form of Σ_t , that is, $\underline{g}_{ij} := g_{ij}$ for $1 \leq i, j \leq 3$. We also note that relative to the standard coordinates, $\hat{N}^\alpha = -\frac{(g^{-1})^{\alpha 0}}{\sqrt{|(g^{-1})^{00}|}}$, $d\mu_g = \sqrt{|\det g|} dx^1 dx^2 dx^3 dx^0$, and $d\mu_{\underline{g}} = \sqrt{\det \underline{g}} dx^1 dx^2 dx^3 = \sqrt{|(g^{-1})^{00}|} \sqrt{|\det g|} dx^1 dx^2 dx^3$, where the last equality is a basic linear algebraic identity. Note that \hat{N} is future-directed and timelike with respect to g , and that we used the fact that $(g^{-1})^{00} < 0$ (which is a simple consequence of the formula (2.13b) and our assumption that $0 < c \leq 1$).

From the above discussion, it follows that along any spacelike (with respect³⁶ to g) hypersurface with future-directed unit normal \hat{N} , we can construct a positive-definite energy density $g_{\alpha\beta} {}^{(X)}J^\alpha[\varphi] \hat{N}^\beta$ using any multiplier vectorfield X that is future-directed and timelike with respect to g . For the basic a priori estimates of interest to us, we will apply the above constructions along Σ_t with $X := u$, which is future-directed timelike with respect to g . As we described in Footnote 18, we cannot generally use $X := \partial_t$ because $g(\partial_t, \partial_t) > 0$

³⁶A hypersurface is spacelike with respect to g if, at each point, its unit normal is timelike with respect to g .

can occur when $\sum_{a=1}^3 |u^a|$ is large; in contrast, note that by (2.13a) and the normalization condition $\eta_{\kappa\lambda} u^\kappa u^\lambda = -1$, we have $g_{\kappa\lambda} u^\kappa u^\lambda = -1$. Thus, we define the following energy (where $\hat{N}^\alpha = -\frac{(g^{-1})^{\alpha 0}}{\sqrt{|(g^{-1})^{00}|}}$):

$$E_{\text{wave}}(t) = E_{\text{wave}}[\varphi](t) := \int_{\Sigma_t} g_{\alpha\beta}^{(u)} J^\alpha[\varphi] \hat{N}^\beta \, d\mu_g. \quad (9.51)$$

From (9.50), definition (9.51), and the standard expansion³⁷ of covariant derivatives in terms of partial derivatives and Christoffel symbols (which in particular can be used to derive the identity ${}^{(u)}\pi_{\alpha\beta} = u^\kappa \partial_\kappa g_{\alpha\beta} + g_{\alpha\kappa} \partial_\beta u^\kappa + g_{\beta\kappa} \partial_\alpha u^\kappa$), we deduce the following energy identity relative to the standard coordinates:

$$\begin{aligned} E_{\text{wave}}[\varphi](t) &= E_{\text{wave}}[\varphi](0) - \int_{[0,t] \times \mathbb{T}^3} (\square_g \varphi) u^\kappa \partial_\kappa \varphi \, d\mu_g \\ &\quad - \frac{1}{2} \int_{[0,t] \times \mathbb{T}^3} (g^{-1})^{\alpha\gamma} (g^{-1})^{\beta\delta} T_{\alpha\beta}[\varphi] u^\kappa \partial_\kappa g_{\gamma\delta} \, d\mu_g \\ &\quad - \int_{[0,t] \times \mathbb{T}^3} (g^{-1})^{\beta\delta} T_{\alpha\beta}[\varphi] \partial_\delta u^\alpha \, d\mu_g \\ &\quad + \int_{[0,t] \times \mathbb{T}^3} \{(\partial_\kappa u^\kappa) \varphi^2 + \Gamma^\kappa_\lambda u^\lambda \varphi^2 + 2\varphi u^\kappa \partial_\kappa \varphi\} \, d\mu_g. \end{aligned} \quad (9.52)$$

On RHS (9.52),

$$\Gamma^\gamma_{\alpha\beta} := \frac{1}{2} (g^{-1})^{\gamma\delta} \{ \partial_\alpha g_{\delta\beta} + \partial_\beta g_{\alpha\delta} - \partial_\delta g_{\alpha\beta} \} \quad (9.53)$$

are the Christoffel symbols of g relative to the standard coordinates. Note that by (2.13a)–(2.13b) we have that

$$\Gamma^\gamma_{\alpha\beta} = f(h, s, u, \partial h, S, \partial u), \quad (9.54)$$

where f is a smooth function (depending on α , β , and γ).

Next, with the help of (2.13a)–(2.13b) and the normalization condition $\eta_{\kappa\lambda} u^\kappa u^\lambda = -1$, we compute that

$$\begin{aligned} g_{\alpha\beta}^{(u)} J^\alpha[\varphi] \hat{N}^\beta &= \{c^2 T_{0\beta}[\varphi] u^\beta + (1 - c^2) u^0 T_{\alpha\beta}[\varphi] u^\alpha u^\beta + u^0 \varphi^2\} \frac{1}{\sqrt{|(g^{-1})^{00}|}} \\ &= \frac{\frac{1}{2} u^0 \{c^2 (\partial_t \varphi)^2 + c^2 \delta^{ab} (\partial_a \varphi) \partial_b \varphi + (1 - c^2) (u^\alpha \partial_\alpha \varphi)^2\}}{\sqrt{|(g^{-1})^{00}|}} \\ &\quad + \frac{\{c^2 (\partial_t \varphi) u^a \partial_a \varphi + u^0 \varphi^2\}}{\sqrt{|(g^{-1})^{00}|}}, \end{aligned} \quad (9.55)$$

where δ^{ab} is the Kronecker delta. From (9.51) and (9.55), it follows that

³⁷For example, $\nabla_\alpha X^\beta = \partial_\alpha X^\beta + \Gamma^\beta_\alpha{}^\gamma X^\gamma$, where $\Gamma^\beta_\alpha{}^\gamma$ is defined by (9.53).

$$\begin{aligned}
E_{\text{wave}}[\varphi](t) &= \frac{1}{2} \int_{\Sigma_t} u^0 \left\{ c^2 (\partial_t \varphi)^2 + c^2 \delta^{ab} (\partial_a \varphi) \partial_b \varphi + (1 - c^2) (u^\alpha \partial_\alpha \varphi)^2 \right\} \frac{d\mu_g}{\sqrt{|(g^{-1})^{00}|}} \\
&\quad + \int_{\Sigma_t} \left\{ c^2 (\partial_t \varphi) u^a \partial_a \varphi + u^0 \varphi^2 \right\} \frac{d\mu_g}{\sqrt{|(g^{-1})^{00}|}}. \tag{9.56}
\end{aligned}$$

The energy $E_{\text{wave}}[\varphi](t)$ will yield L^2 control of φ and its first derivatives. In Sect. 9.6.3, we will establish the coerciveness $E_{\text{wave}}[\varphi](t)$. To obtain L^2 control of the higher-order spatial derivatives of φ , one can use energies of the form $E_{\text{wave}}[\partial_{\vec{I}} \varphi]$, where \vec{I} is a spatial multi-index.

9.6.2. Energy Estimates for Transport Equations. One can derive energy estimates for transport equations of the form $u^\alpha \partial_\alpha \varphi = f$ by relying on the following energy:

$$E_{\text{transport}}[\varphi](t) := \int_{\Sigma_t} \varphi^2 dx, \tag{9.57}$$

as in the proof of Lemma 9.6. The analog of the wave equation energy identity (9.52) is the following integral identity, whose simple proof follows from the ideas featured in the proof of Lemma 9.6:

$$\begin{aligned}
E_{\text{transport}}[\varphi](t) &= E_{\text{transport}}[\varphi](0) + \int_0^t \int_{\Sigma_\tau} \left\{ \partial_a \left(\frac{u^a}{u^0} \right) \right\} \varphi^2 dx d\tau \\
&\quad + 2 \int_0^t \int_{\Sigma_\tau} \varphi \frac{u^\alpha \partial_\alpha \varphi}{u^0} dx d\tau. \tag{9.58}
\end{aligned}$$

To control the higher-order derivatives of φ , one can rely on energies of the form $E_{\text{transport}}[\partial_{\vec{I}} \varphi]$. We mention that the argument we have sketched here relies on the basic fact that $u^0 > 0$, which allows us to divide by u^0 on RHS (9.58); for the relativistic Euler equations, this fact follows from the normalization condition $\eta_{\kappa\lambda} u^\kappa u^\lambda = -1$ and the fact that u is future-directed.

9.6.3. Comparison of the Energies with the Sobolev Norm. The coerciveness properties of the wave equation energy $E_{\text{wave}}[\varphi](t)$ constructed in Sect. 9.6.1 are tied to the metric g ; see (9.51). In order to obtain our results, we need $E_{\text{wave}}[\varphi](t)$ to be uniformly comparable to a corresponding Sobolev norm along Σ_t . More precisely, we need to ensure the existence of a constant $C > 1$ such that on the slab $[0, T] \times \mathbb{T}^3$ of existence guaranteed by Theorem 9.10, the following estimates hold:

$$\begin{aligned}
C^{-1} \left\{ \|\varphi\|_{H^N(\Sigma_t)}^2 + \|\partial_t \varphi\|_{H^{N-1}(\Sigma_t)}^2 \right\} &\leq \sum_{0 \leq |\vec{I}| \leq N-1} E_{\text{wave}}[\partial_{\vec{I}} \varphi](t) \\
&\leq C \left\{ \|\varphi\|_{H^N(\Sigma_t)}^2 + \|\partial_t \varphi\|_{H^{N-1}(\Sigma_t)}^2 \right\}. \tag{9.59}
\end{aligned}$$

To see that such a constant C exists, we first use Young's inequality, (2.20), and Cauchy–Schwarz to bound the first product in braces on the last line of

RHS (9.56) as follows:

$$\begin{aligned}
& c^2(\partial_t\varphi)u^a\partial_a\varphi \\
& \geq -\frac{1}{2}c^2\left(\sqrt{\sum_{i=1}^3(u^i)^2}\right)(\partial_t\varphi)^2 - \frac{1}{2}c^2\left(\sqrt{\sum_{i=1}^3(u^i)^2}\right)\delta^{ab}(\partial_a\varphi)\partial_b\varphi \\
& = -\frac{1}{2}c^2\left(\sqrt{(u^0)^2-1}\right)(\partial_t\varphi)^2 - \frac{1}{2}c^2\left(\sqrt{(u^0)^2-1}\right)\delta^{ab}(\partial_a\varphi)\partial_b\varphi. \quad (9.60)
\end{aligned}$$

Next, we recall that Theorem 9.10 guarantees that on $[0, T] \times \mathbb{T}^3$, the solution never escapes the compact subset \mathfrak{K} featured in the statement of the theorem. In view of (9.60), we see that this ensures that on $[0, T] \times \mathbb{T}^3$, the product $c^2(\partial_t\varphi)u^a\partial_a\varphi$ on the last line of RHS (9.56) can be absorbed into the sum $\frac{1}{2}c^2u^0(\partial_t\varphi)^2 + \frac{1}{2}c^2u^0\delta^{ab}(\partial_a\varphi)\partial_b\varphi$ from the first line of RHS (9.56), with room to spare. This implies that for solutions contained in \mathfrak{K} , the integrands on RHS (9.56) are in total uniformly comparable to $\sum_{\alpha=0}^3(\partial_\alpha\varphi)^2 + \varphi^2$. This also ensures that on $[0, T] \times \mathbb{T}^3$, the volume form $\frac{d\mu_g}{\sqrt{|(g^{-1})^{00}|}}$ on Σ_t is uniformly comparable³⁸ to $dx := dx^1dx^2dx^3$. From these observations, it readily follows that a $C > 1$ exists such that (9.59) holds.

9.6.4. Proof of Proposition 9.22. Recall that the assumptions of the proposition guarantee that we have a smooth solution to the system (2.17)–(2.19) + (2.20). Consider the scalar component functions

$$h, u^\alpha, S^\alpha, \varpi^\alpha, \mathcal{C}^\alpha, \mathcal{D}, \quad (9.61)$$

introduced in Sect. 2. According to Theorem 3.1, they satisfy the system of evolution equations given by Eqs. (3.1), (3.3), (3.7), (3.8), (3.9a), and (3.11b). Next, we recall that the hyperbolic quantities \mathbf{H} and the elliptic quantities \mathbf{E} were defined in Definition 9.15. To prove the proposition, we claim that it suffices to show that the following inequality holds for $t \in [0, T]$:

$$\|\mathbf{H}\|_{H^{N-1}(\Sigma_t)}^2 \leq C\|\mathbf{H}\|_{H^{N-1}(\Sigma_0)}^2 + C \int_0^t \|\mathbf{H}\|_{H^{N-1}(\Sigma_\tau)}^2 d\tau, \quad (9.62)$$

where in (9.62) and in the rest of this proof, C is as in the statement of Proposition 9.22. For once we have shown (9.62), we can use Gronwall's inequality to deduce (recalling that C is allowed to depend on the initial data and can vary from line to line) that the following estimate holds for $t \in [0, T]$:

$$\|\mathbf{H}\|_{H^{N-1}(\Sigma_t)}^2 \leq C\|\mathbf{H}\|_{H^{N-1}(\Sigma_0)}^2 \exp(Ct) \leq C \exp(Ct) \leq C \exp(CT). \quad (9.63)$$

Then from (9.39) and (9.63) we conclude, in view of Definition 9.15, the desired bound (9.44), except for the estimates for u^0 , S^0 , and ϖ^0 . To obtain the desired estimate for these quantities, we first express $u^0 - 1$, S^0 , ϖ^0 , $\partial_a u^0$, $\partial_a S^0$, and $\partial_a \varpi^0$ as $f(\mathbf{H}, \mathbf{E})$, with f smooth and satisfying $f(0) = 0$ [this is

³⁸To see this, it is helpful to note the following identity, which holds relative to the standard coordinates: $\frac{d\mu_g}{\sqrt{|(g^{-1})^{00}|}} = c^{-3} dx^1 dx^2 dx^3$. This identity follows from (2.14a) and the linear algebraic identity $\det g = (g^{-1})^{00} \det g$.

possible in view of definition (9.32e) and (9.33c)]. We then use Lemma 9.4 to deduce that $\|\mathbf{f}(\mathbf{H}, \mathbf{E})\|_{H^{N-1}(\Sigma_t)} \leq C\|\mathbf{H}\|_{H^{N-1}(\Sigma_t)} + C\|\mathbf{E}\|_{H^{N-1}(\Sigma_t)}$. Finally, we use the elliptic estimate (9.39) and (9.63) to conclude that $C\|\mathbf{H}\|_{H^{N-1}(\Sigma_t)} + C\|\mathbf{E}\|_{H^{N-1}(\Sigma_t)} \leq \text{RHS } (9.44)$, which yields the desired estimates.

It remains for us to prove (9.62). We start by noting that the results described in Sects. 9.6.1–9.6.3 can be used to derive the following estimates, where we recall that \underline{V} denotes the spatial components of V (i.e., the η -orthogonal projection of V onto constant-time hypersurfaces, as in Sect. 9.1.1):

$$\begin{aligned} \|h\|_{H^N(\Sigma_t)}^2 + \|\partial_t h\|_{H^{N-1}(\Sigma_t)}^2 &\leq C \left\{ \|h\|_{H^N(\Sigma_0)}^2 + \|\partial_t h\|_{H^{N-1}(\Sigma_0)}^2 \right\} \\ &\quad + C \int_0^t \|\mathbf{H}\|_{H^{N-1}(\Sigma_\tau)}^2 d\tau, \end{aligned} \quad (9.64)$$

$$\begin{aligned} \|\underline{u}\|_{H^N(\Sigma_t)}^2 + \|\partial_t \underline{u}\|_{H^N(\Sigma_t)}^2 &\leq C \left\{ \|\underline{u}\|_{H^N(\Sigma_0)}^2 + \|\partial_t \underline{u}\|_{H^N(\Sigma_0)}^2 \right\} \\ &\quad + C \int_0^t \|\mathbf{H}\|_{H^{N-1}(\Sigma_\tau)}^2 d\tau, \end{aligned} \quad (9.65)$$

$$\begin{aligned} \|\underline{S}\|_{H^{N-1}(\Sigma_t)}^2 &\leq C \|\underline{S}\|_{H^{N-1}(\Sigma_0)}^2 \\ &\quad + C \int_0^t \|\mathbf{H}\|_{H^{N-1}(\Sigma_\tau)}^2 d\tau, \end{aligned} \quad (9.66)$$

$$\begin{aligned} \|\underline{\varpi}\|_{H^{N-1}(\Sigma_t)}^2 &\leq C \|\underline{\varpi}\|_{H^{N-1}(\Sigma_0)}^2 \\ &\quad + C \int_0^t \|\mathbf{H}\|_{H^{N-1}(\Sigma_\tau)}^2 d\tau, \end{aligned} \quad (9.67)$$

$$\begin{aligned} \|\mathcal{D}\|_{H^{N-1}(\Sigma_t)}^2 &\leq C \|\mathcal{D}\|_{H^{N-1}(\Sigma_0)}^2 \\ &\quad + C \int_0^t \left\{ \|\mathbf{H}\|_{H^{N-1}(\Sigma_\tau)}^2 + \|\mathbf{E}\|_{H^{N-1}(\Sigma_\tau)}^2 \right\} d\tau, \end{aligned} \quad (9.68)$$

$$\begin{aligned} \|\mathcal{C}\|_{H^{N-1}(\Sigma_t)}^2 &\leq C \|\mathcal{C}\|_{H^{N-1}(\Sigma_0)}^2 \\ &\quad + C \int_0^t \left\{ \|\mathbf{H}\|_{H^{N-1}(\Sigma_\tau)}^2 + \|\mathbf{E}\|_{H^{N-1}(\Sigma_\tau)}^2 \right\} d\tau. \end{aligned} \quad (9.69)$$

The estimates (9.64)–(9.69) are standard and can be derived by commuting the evolution equations of Theorem 3.1 (more precisely, only the evolution equations for the spatial components of u , ϖ , S , and \mathcal{C}) with spatial derivative operators $\partial_{\tilde{I}}$ and using the energy identities (9.52) and (9.58) (and their analogs for the $\partial_{\tilde{I}}$ -differentiated solution variables), the coerciveness estimate (9.59), Lemma 9.17, and the Sobolev–Moser-type estimate (9.11). We stress that RHS (9.11) is *linear* in the order r derivatives of the solution; this is the reason the integrands on RHS (9.64)–(9.69) are quadratic in $\|\mathbf{H}\|_{H^{N-1}(\Sigma_\tau)}$ and $\|\mathbf{E}\|_{H^{N-1}(\Sigma_\tau)}$ [the sup-norm factors on RHS (9.11) can be bounded by $\leq C$ since those factors are among the quantities that constants C are allowed

to depend on]. The non-standard aspect of the remaining part of the proof is the appearance of the term $\|\mathbf{E}\|_{H^{N-1}(\Sigma_\tau)}^2$ on RHSs (9.68)–(9.69); we clarify that these terms are generated by the terms $\partial_a S_b$ and $\partial_a \varpi_b$ on RHSs (3.9a) and (3.11b) [see definition (9.32b)]. Next, adding (9.64)–(9.69) and appealing to Definition 9.15, we deduce that

$$\begin{aligned} \|\mathbf{H}\|_{H^{N-1}(\Sigma_t)}^2 &\leq C \|\mathbf{H}\|_{H^{N-1}(\Sigma_0)}^2 \\ &\quad + C \int_0^t \left\{ \|\mathbf{H}\|_{H^{N-1}(\Sigma_\tau)}^2 + \|\mathbf{E}\|_{H^{N-1}(\Sigma_\tau)}^2 \right\} d\tau. \end{aligned} \quad (9.70)$$

Finally, from (9.70) and the elliptic estimate (9.39), we conclude the desired bound (9.62). \square

9.7. Proof of Theorem 9.12

We now prove Theorem 9.12, which is the main result of Sect. 9. By Theorem 9.10, we need only to show that (i) under the regularity assumptions on the initial data stated in Theorem 9.12, the standard local well-posedness results (9.28a)–(9.28b) can be upgraded to (9.30a)–(9.30b) and (ii) that the solution depends continuously on the initial data, where continuity is measured in the norms corresponding to the function spaces featured in (9.30a)–(9.30b). Throughout this proof, \mathfrak{K} denotes the set featured in the statement of Theorem 9.10. To proceed, we let $(\mathring{h}_{(m)}, \mathring{s}_{(m)}, \mathring{u}_{(m)}^i) \subset (C^\infty(\mathbb{T}^3))^5$ be a sequence of smooth initial data such that as $m \rightarrow \infty$, we have

$$\left\| \mathring{h}_{(m)} - \mathring{h} \right\|_{H^N(\Sigma_0)} \rightarrow 0, \quad \left\| \mathring{u}_{(m)}^i - \mathring{u}^i \right\|_{H^N(\Sigma_0)} \rightarrow 0, \quad (9.71)$$

$$\left\| \mathring{s}_{(m)} - \mathring{s} \right\|_{H^{N+1}(\Sigma_0)} \rightarrow 0, \quad \left\| \mathring{\varpi}_{(m)}^i - \mathring{\varpi}^i \right\|_{H^N(\Sigma_0)} \rightarrow 0, \quad (9.72)$$

where $\mathring{\varpi}_{(m)}^i$ denotes the initial vorticity of the m th element of the sequence and $\mathring{\varpi}^i$ is as in the statement of the theorem. Let $(h_{(m)}, s_{(m)}, u_{(m)}^\alpha, S_{(m)}^\alpha, \varpi_{(m)}^\alpha)$ denote the corresponding sequence of solution variables. Theorem 9.10 yields (see, for example, [31], for additional details) that for m sufficiently large, the element $(h_{(m)}, s_{(m)}, u_{(m)}^\alpha)$ is a C^∞ classical solution to Eqs. (2.17)–(2.19) + (2.20) on the fixed slab $[0, T] \times \mathbb{T}^3$ with

$$(h_{(m)}(p), s_{(m)}(p), u_{(m)}^1(p), u_{(m)}^2(p), u_{(m)}^3(p)) \in \text{int}\mathfrak{K}$$

for $p \in [0, T] \times \mathbb{T}^3$, and that on the same slab, $(h_{(m)}, s_{(m)}, u_{(m)}^\alpha, S_{(m)}^\alpha, \varpi_{(m)}^\alpha)$ is a C^∞ solution to the equations of Theorem 3.1 [which are consequences of (2.17)–(2.19) + (2.20)]. Moreover, Theorem 9.10 also implies that the sequence converges to the solution in the following norms as $m \rightarrow \infty$:

$$\|h_{(m)} - h\|_{C([0, T], H^N(\mathbb{T}^3))} \rightarrow 0, \quad (9.73)$$

$$\|u_{(m)}^\alpha - u^\alpha\|_{C([0, T], H^N(\mathbb{T}^3))} \rightarrow 0, \quad (9.74)$$

$$\|s_{(m)} - s\|_{C([0, T], H^N(\mathbb{T}^3))} \rightarrow 0, \quad (9.75)$$

$$\left\| S_{(m)}^\alpha - S^\alpha \right\|_{C([0,T], H^{N-1}(\mathbb{T}^3))} \rightarrow 0, \quad (9.76)$$

$$\left\| \varpi_{(m)}^\alpha - \varpi^\alpha \right\|_{C([0,T], H^{N-1}(\mathbb{T}^3))} \rightarrow 0. \quad (9.77)$$

Next, we use the convergence results (9.73)–(9.77), Theorem 9.10, and the a priori estimates provided by Proposition 9.22 to deduce that exist a constant $C > 0$, depending on T and on the four types of quantities listed just above (9.44), and a positive integer m_0 such that

$$\sup_{m \geq m_0} \sup_{\tau \in [0,T]} \|s_{(m)}\|_{H^{N+1}(\Sigma_\tau)} \leq C, \quad (9.78)$$

$$\sup_{m \geq m_0} \sup_{\tau \in [0,T]} \|S_{(m)}^\alpha\|_{H^N(\Sigma_\tau)} \leq C, \quad (9.79)$$

$$\sup_{m \geq m_0} \sup_{\tau \in [0,T]} \|\varpi_{(m)}^\alpha\|_{H^N(\Sigma_\tau)} \leq C. \quad (9.80)$$

Since $H^r(\mathbb{T}^3)$ is a Hilbert space for $r \in \mathbb{R}$, it follows from the norm-boundedness results (9.78)–(9.80) that for each $\tau \in [0, T]$, there exist subsequences $s_{(m_n)}$, $S_{(m_n)}^\alpha$, and $\varpi_{(m_n)}^\alpha$ that weakly converge in $H^{N+1}(\Sigma_\tau)$, $H^N(\Sigma_\tau)$, and $H^N(\Sigma_\tau)$ respectively as $n \rightarrow \infty$. Moreover, since the norm is weakly lower semicontinuous in a Hilbert space, it follows that the limits are bounded, respectively, in the norms $\|\cdot\|_{H^{N+1}(\Sigma_\tau)}$, $\|\cdot\|_{H^N(\Sigma_\tau)}$, and $\|\cdot\|_{H^N(\Sigma_\tau)}$, by $\leq C$, where C is the same constant found on RHSs (9.78)–(9.80). From (9.76) to (9.77), it follows that the limits must be s , S^α , and ϖ^α respectively. We have therefore shown that

$$\sup_{\tau \in [0,T]} \|s\|_{H^{N+1}(\Sigma_\tau)} \leq C, \quad (9.81)$$

$$\sup_{\tau \in [0,T]} \|S^\alpha\|_{H^N(\Sigma_\tau)} \leq C, \quad (9.82)$$

$$\sup_{\tau \in [0,T]} \|\varpi^\alpha\|_{H^N(\Sigma_\tau)} \leq C. \quad (9.83)$$

To complete the proof of (9.30b), we must show that for each spatial multi-index \vec{I} with $|\vec{I}| = N$, the map $t \rightarrow \partial_{\vec{I}} S^\alpha(t, \cdot)$ is a continuous map from $[0, T]$ into $L^2(\mathbb{T}^3)$, and similarly for ϖ^α (the desired time-continuity results for s then follow from the relation $\partial_t s = S_i$). To keep the presentation short, we illustrate only the right-continuity of these maps at $t = 0$; the general statement can be proved by making minor modifications to the argument that we give. That is, we will show that

$$\lim_{t \downarrow 0} \|\partial_{\vec{I}} S^\alpha(t, \cdot) - \partial_{\vec{I}} \mathring{S}^\alpha(\cdot)\|_{L^2(\mathbb{T}^3)} = 0, \quad |\vec{I}| = N, \quad (9.84a)$$

$$\lim_{t \downarrow 0} \|\partial_{\vec{I}} \varpi^\alpha(t, \cdot) - \partial_{\vec{I}} \mathring{\varpi}^\alpha(\cdot)\|_{L^2(\mathbb{T}^3)} = 0, \quad |\vec{I}| = N, \quad (9.84b)$$

where $\mathring{S}^\alpha(\cdot) := S^\alpha(0, \cdot)$. The rest of our proof is based on Lemmas 9.6 and 9.20, but to apply the lemmas, we first have to derive some preliminary results. We will use the estimates provided by Lemma 9.4 without giving complete details each time we use them; we will refer to these estimates as the “standard

Sobolev calculus.” In the rest of the proof, we will refer to the variable sets \mathbf{H} , \mathbf{E} , $\mathbf{A}_\mathbf{H}$, $\mathbf{A}_{\mathbf{H},\mathbf{E}}$, and \mathbf{A} from Definition 9.15.

As a first step in proving (9.84a)–(9.84b), we will show that

$$\mathbf{H}, \mathbf{A}_\mathbf{H} \in C([0, T], H^{N-1}(\mathbb{T}^3)), \quad (9.85)$$

where \mathbf{H} and $\mathbf{A}_\mathbf{H}$ are defined in (9.32a) and (9.32c). Note that by (9.33a) and the standard Sobolev calculus, the desired result $\mathbf{A}_\mathbf{H} \in C([0, T], H^{N-1}(\mathbb{T}^3))$ would follow from $\mathbf{H} \in C([0, T], H^{N-1}(\mathbb{T}^3))$. The latter statement is equivalent to showing that $\partial_{\vec{I}} \mathbf{H} \in C([0, T], L^2(\mathbb{T}^3))$ for $|\vec{I}| \leq N - 1$. All of these results, except in the case of the top-order (i.e., order $N - 1$) derivatives of \mathcal{C}^i and \mathcal{D} , follow from the standard local well-posedness time-continuity results (9.28a)–(9.28b), and the standard Sobolev calculus. Thus, to complete the proof of (9.85), we need only to show that for $i = 1, 2, 3$, we have

$$\partial_{\vec{I}} \mathcal{C}^i, \partial_{\vec{I}} \mathcal{D} \in C([0, T], L^2(\mathbb{T}^3)), \quad |\vec{I}| = N - 1. \quad (9.86)$$

The desired result (9.86) follows from using Eqs. (3.9a) and (3.11b) [more precisely, we need only to consider the spatial components of (3.11b)], the boundedness results (9.81)–(9.83), the standard local well-posedness time-continuity results (9.28a)–(9.28b), and the standard Sobolev calculus to deduce that $\partial_{\vec{I}} \mathcal{C}^i$ and $\partial_{\vec{I}} \mathcal{D}$ solve transport equations that satisfy the hypotheses of Lemma 9.6; put succinctly, we can apply Lemma 9.6 with $f := \partial_{\vec{I}} \mathcal{C}^i$ and $f := \partial_{\vec{I}} \mathcal{D}$. We have therefore proved (9.85). In particular, it follows from (9.85) and the definition of $\mathbf{A}_\mathbf{H}$ that for $i = 1, 2, 3$, we have

$${}^{(3)}\text{curl}^i(\underline{\varpi}), {}^{(3)}\text{curl}^i(\underline{S}) \in C([0, T], H^{N-1}(\mathbb{T}^3)). \quad (9.87)$$

Next, we note that in view of Definition 9.15, Lemma 9.17 (in particular the relation (9.33b) for $\partial_a S^0$ and $\partial_a \varpi^0$), (9.85), and the standard Sobolev calculus, the desired results (9.84a)–(9.84b) would follow as a consequence of the following convergence result:

$$\lim_{t \downarrow 0} \|\partial_{\vec{I}} \mathbf{E}(t, \cdot) - \partial_{\vec{I}} \mathbf{E}(0, \cdot)\|_{L^2(\mathbb{T}^3)} = 0, \quad |\vec{I}| = N - 1. \quad (9.88)$$

To establish (9.88), we first use (9.85), (9.34), and the standard Sobolev calculus to deduce the following facts, where $(G^{-1})^{ij}$ is defined in Definition 9.13:

$$(G^{-1})^{ab} \partial_a \partial_{\vec{I}} S_b, (G^{-1})^{ab} \partial_a \partial_{\vec{I}} \varpi_b \in C([0, T], L^2(\mathbb{T}^3)), \quad |\vec{I}| = N - 1. \quad (9.89)$$

In the rest of the proof, $\alpha_* > 0$ is as in the statement of Lemma 9.20 in the case $(M^{-1})^{ij}(t, x) := (G^{-1})^{ij}(t, x)$. Next, setting

$$(\mathring{G}^{-1})^{ij}(\cdot) := (G^{-1})^{ij}(0, \cdot), \quad (9.90)$$

applying Lemma 9.20 with $(M^{-1})^{ij} := (\mathring{G}^{-1})^{ij}$, and appealing to definition (9.32b), we see that in order to prove (9.88), it suffices to show the following convergence result:

$$\lim_{t \downarrow 0} \mathbb{E}_{N; \mathring{G}^{-1}; \alpha_*} [(\underline{\varpi}, \underline{S}) - (\mathring{\underline{\varpi}}, \mathring{\underline{S}})](t) = 0, \quad (9.91)$$

where $(\mathring{\underline{\varpi}}, \mathring{\underline{S}}) := (\underline{\varpi}, \underline{S})|_{\Sigma_0}$.

To initiate the proof of (9.91), we let $\varphi \in H^{-N}(\mathbb{T}^3)$ be any element of the dual space of $H^N(\mathbb{T}^3)$. From the below-top-order continuity result (9.28b), the top-order boundedness results (9.82)–(9.83), and the density of C^∞ functions in $H^{-N}(\mathbb{T}^3)$, it is straightforward to deduce that the following “weak continuity” result holds for $i = 1, 2, 3$:

$$\lim_{t \downarrow 0} \int_{\mathbb{T}^3} S^i(t, x) \varphi \, dx = \int_{\mathbb{T}^3} \mathring{S}^i \varphi \, dx. \quad (9.92)$$

Since φ was arbitrary, we conclude that $S^i(t, \cdot)$ weakly converges to \mathring{S}^i in $H^N(\mathbb{T}^3)$ as $t \downarrow 0$. Similarly, $\varpi^i(t, \cdot)$ weakly converges to $\mathring{\varpi}^i$ in $H^N(\mathbb{T}^3)$ as $t \downarrow 0$. We now let $\langle \cdot, \cdot \rangle_{\mathring{G}^{-1}; \alpha_*}$ denote the inner product (9.35) on the Hilbert space $(H^N(\Sigma_t))^3 \times (H^N(\Sigma_t))^3$, and we let $\langle \cdot, \cdot \rangle$ denote the standard inner product on the same Hilbert space (obtained by keeping only the two sums on the last line of RHS (9.35) and replacing $N - 1$ with N in the summation bounds). By Lemma 9.20, the two corresponding norms [i.e., the norms on the left- and right-hand sides of (9.37a)–(9.37b)] are equivalent. It is a basic result of functional analysis that given these two inner products with equivalent norms, a sequence weakly converges relative to $\langle \cdot, \cdot \rangle_{\mathring{G}^{-1}; \alpha_*}$ if and only if it weakly converges relative to $\langle \cdot, \cdot \rangle$. In particular, in view of the weak convergence results for $S^i(t, \cdot)$ and $\varpi^i(t, \cdot)$ proved above, we infer that $(\varpi(t, \cdot), S(t, \cdot))$ weakly converges to $(\mathring{\varpi}(\cdot), \mathring{S}(\cdot))$ relative to the inner product $\langle \cdot, \cdot \rangle_{\mathring{G}^{-1}; \alpha_*}$ as $t \downarrow 0$. Moreover, it is another basic result of functional analysis that based on this weak convergence and Lemma 9.20, in order to prove the result (9.91), it suffices to show that

$$\limsup_{t \downarrow 0} \mathbb{E}_{N; \mathring{G}^{-1}; \alpha_*}[(\varpi, S)](t) \leq \mathbb{E}_{N; \mathring{G}^{-1}; \alpha_*}[(\mathring{\varpi}, \mathring{S})]. \quad (9.93)$$

Moreover, since the standard local well-posedness time-continuity results (9.28a) and (9.9) imply that $\lim_{t \downarrow 0} \left\| (G^{-1})^{ij}(t, \cdot) - (\mathring{G}^{-1})^{ij} \right\|_{C(\mathbb{T}^3)} = 0$, it follows from definitions (9.35) and (9.36) and the top-order boundedness results (9.81)–(9.83) that in order to prove (9.93), it suffices to show that

$$\limsup_{t \downarrow 0} \mathbb{E}_{N; G^{-1}; \alpha_*}[(\varpi, S)](t) \leq \mathbb{E}_{N; \mathring{G}^{-1}; \alpha_*}[(\mathring{\varpi}, \mathring{S})], \quad (9.94)$$

where we stress that the inverse metric G^{-1} on LHS (9.94) depends on t [which is different compared to (9.93)]. In fact, our arguments will yield a stronger statement than (9.94). More precisely, we will show the following time-continuity result:

$$\lim_{t \downarrow 0} \mathbb{E}_{N; G^{-1}; \alpha_*}[(\varpi, S)](t) = \mathbb{E}_{N; \mathring{G}^{-1}; \alpha_*}[(\mathring{\varpi}, \mathring{S})], \quad (9.95)$$

To proceed, we use definitions (9.35) and (9.36) and the standard local well-posedness time-continuity results (9.28a)–(9.28b) to deduce that all terms in the definition of $\mathbb{E}_{N; G^{-1}; \alpha_*}[(\varpi, S)](t)$ have been shown to have the desired continuous time dependence except for the ones depending on the order N derivatives of ϖ or S [i.e., the ones corresponding to the terms on the

first four lines of RHS (9.35)]. The continuous time dependence of these remaining four terms follows from (9.87), (9.89), and the fact that $(G^{-1})^{ij} \in C([0, T], C(\mathbb{T}^3))$ [which follows from the standard local well-posedness time-continuity results (9.28a) and (9.9)]. We have therefore proved (9.95), which finishes the proof of the desired result (9.30b).

To complete our proof of Theorem 9.12, we need to show continuous dependence on the initial data. To proceed, we let $(\dot{h}_{(m)}, \dot{u}_{(m)}^i, \dot{s}_{(m)})$ be a sequence of initial data (not necessarily C^∞ now) such that as $m \rightarrow \infty$, the convergence results (9.71)–(9.72) hold. We again let $(h_{(m)}, s_{(m)}, u_{(m)}^\alpha, S_{(m)}^\alpha, \varpi_{(m)}^\alpha)$ denote the corresponding sequence of solution variables (which are not necessarily C^∞ now). We aim to show that the sequence converges to the limiting solution $(h, u^\alpha, s, S^\alpha, \varpi^\alpha)$ in the norm $\|\cdot\|_{C([0, T], H^N \mathbb{T}^3)}$ as $m \rightarrow \infty$. To proceed, we first note that Theorem 9.10 yields that for m sufficiently large, the element $(h_{(m)}, s_{(m)}, u_{(m)}^\alpha, S_{(m)}^\alpha, \varpi_{(m)}^\alpha)$ is a classical solution (not necessarily C^∞ now) to Eqs. (2.17)–(2.19) + (2.20) on the fixed slab $[0, T] \times \mathbb{T}^3$ with $(h_{(m)}(p), s_{(m)}(p), u_{(m)}^1(p), u_{(m)}^2(p), u_{(m)}^3(p)) \in \text{int}\mathfrak{K}$ for $p \in [0, T] \times \mathbb{T}^3$, that it also is a strong solution³⁹ to the equations of Theorem 3.1, that there exists an integer m_0 such that

$$\sup_{m \geq m_0} \|s_{(m)}\|_{C([0, T], H^{N+1}(\mathbb{T}^3))} \leq C, \quad (9.96)$$

$$\sup_{m \geq m_0} \|S_{(m)}^\alpha\|_{C([0, T], H^N(\mathbb{T}^3))} \leq C, \quad (9.97)$$

$$\sup_{m \geq m_0} \|\varpi_{(m)}^\alpha\|_{C([0, T], H^N(\mathbb{T}^3))} \leq C, \quad (9.98)$$

and that the following convergence results (which are below top-order for S and ϖ) hold as $m \rightarrow \infty$:

$$\|h - h_{(m)}\|_{C([0, T], H^N(\mathbb{T}^3))} \rightarrow 0, \quad (9.99)$$

$$\|u^\alpha - u_{(m)}^\alpha\|_{C([0, T], H^N(\mathbb{T}^3))} \rightarrow 0, \quad (9.100)$$

$$\|s - s_{(m)}\|_{C([0, T], H^N(\mathbb{T}^3))} \rightarrow 0, \quad (9.101)$$

$$\|S^\alpha - S_{(m)}^\alpha\|_{C([0, T], H^{N-1}(\mathbb{T}^3))} \rightarrow 0, \quad (9.102)$$

$$\|\varpi^\alpha - \varpi_{(m)}^\alpha\|_{C([0, T], H^{N-1}(\mathbb{T}^3))} \rightarrow 0. \quad (9.103)$$

In view of (9.99)–(9.103), we see that to complete our proof of Theorem 9.12, we need only to show continuity in the top-order norms. That is, we must show that if $|\vec{I}| = N$, then as $m \rightarrow \infty$, we have

$$\|\partial_{\vec{I}} S^\alpha - \partial_{\vec{I}} S_{(m)}^\alpha\|_{C([0, T], L^2(\mathbb{T}^3))} \rightarrow 0, \quad (9.104)$$

³⁹By “strong solution,” we mean in particular that at each fixed $t \in [0, T]$, the equations of Theorem 3.1 are satisfied for almost every $x \in \mathbb{T}^3$.

$$\left\| \partial_{\bar{I}} \varpi^\alpha - \partial_{\bar{I}} \varpi_{(m)}^\alpha \right\|_{C([0, T], L^2(\mathbb{T}^3))} \rightarrow 0. \quad (9.105)$$

To proceed, we first review an approach to proving the standard estimates (9.99)–(9.103). These estimates can be proved by applying Kato’s abstract framework [17–19], which is designed to handle first-order hyperbolic systems in a rather general Banach space setting. In particular, one can apply Kato’s framework to the first-order system (2.17)–(2.19) + (2.20); this is described in detail, for example, in [31]. To prove (9.104)–(9.105), we will modify Kato’s framework so that it applies to the hyperbolic variables \mathbf{H} and the elliptic variables \mathbf{E} from Definition 9.15.

To employ Kato’s framework, one relies on the propagators $\mathcal{U}(t, \tau) := \mathcal{U}(t, \tau; \mathbf{H})$ for the linear homogeneous hyperbolic system corresponding to the (nonlinear) first-order hyperbolic system that \mathbf{H} satisfies. To shorten the presentation, we will not explicitly state the form of this linear first-order hyperbolic system; see Remark 9.16 for further discussion of its nature. By definition, $\mathcal{U}(t, \tau; \mathbf{H})$ maps initial data given at time τ to the solution of the linear homogeneous hyperbolic system (whose principal coefficients depend on \mathbf{H}) at time t . Similarly, one relies on the operators $\mathcal{U}_{(m)}(t, \tau) := \mathcal{U}(t, \tau; \mathbf{H}_{(m)})$ corresponding to the homogeneous linear system whose principal coefficients depend on $\mathbf{H}_{(m)}$. By Duhamel’s principle, we have

$$\mathbf{H}(t) = \mathcal{U}(t, 0) \mathring{\mathbf{H}} + \int_{\tau=0}^t \mathcal{U}(t, \tau) \mathbf{f}(\mathbf{H}(\tau), \mathbf{E}(\tau)) \, d\tau, \quad (9.106)$$

$$\mathbf{H}_{(m)}(t) = \mathcal{U}_{(m)}(t, 0) \mathring{\mathbf{H}}_{(m)} + \int_{\tau=0}^t \mathcal{U}_{(m)}(t, \tau) \mathbf{f}(\mathbf{H}_{(m)}(\tau), \mathbf{E}_{(m)}(\tau)) \, d\tau, \quad (9.107)$$

where $\mathring{\mathbf{H}}$ and $\mathring{\mathbf{H}}_{(m)}$ respectively denote the initial data of \mathbf{H} and $\mathbf{H}_{(m)}$, and on RHSs (9.106)–(9.107), \mathbf{f} denotes the inhomogeneous term in the first-order hyperbolic system satisfied by the elements of \mathbf{H} and $\mathbf{H}_{(m)}$. We have not explicitly stated the form of \mathbf{f} since its precise structure is not important for our arguments here; what matters is only the following basic facts (that can easily be checked): \mathbf{f} is a smooth function of its arguments satisfying $\mathbf{f}(0) = 0$, and the *same* \mathbf{f} appears on RHSs (9.106)–(9.107).

The strategy behind Kato’s framework is to control the difference $\mathbf{H}(t, \cdot) - \mathbf{H}_{(m)}(t, \cdot)$ in the norm $\|\cdot\|_{H^{N-1}(\mathbb{T}^3)}$ by subtracting (9.106)–(9.107), splitting the right-hand side of the resulting equation into various pieces, and bounding each piece by exploiting some standard properties of the propagators $\mathcal{U}(t, \tau)$ and $\mathcal{U}_{(m)}(t, \tau)$. This is explained in detail in [31, Section 7.4], and most of the arguments given there for controlling $\|\mathbf{H}(t, \cdot) - \mathbf{H}_{(m)}(t, \cdot)\|_{H^{N-1}(\mathbb{T}^3)}$ go through without any substantial changes. The one part of the argument that does require substantial changes is: in order to obtain a closed inequality for $\|\mathbf{H}(t, \cdot) - \mathbf{H}_{(m)}(t, \cdot)\|_{H^{N-1}(\mathbb{T}^3)}$, one needs to show that the difference of the inhomogeneous terms on RHSs (9.106)–(9.107) satisfies the following estimate for $t \in [0, T]$:

$$\|\mathbf{f}(\mathbf{H}, \mathbf{E}) - \mathbf{f}(\mathbf{H}_{(m)}, \mathbf{E}_{(m)})\|_{H^{N-1}(\Sigma_t)} \leq C \|\mathbf{H} - \mathbf{H}_{(m)}\|_{H^{N-1}(\Sigma_t)}, \quad (9.108)$$

where the key point is that *the quantity $\|\mathbf{E} - \mathbf{E}_{(m)}\|_{H^{N-1}(\Sigma_t)}$ does not appear on RHS (9.108)*.

The estimate (9.108) can be obtained with the help of elliptic estimates, as we now explain. First, we note that the top-order norm-boundedness results (9.96)–(9.98) and the convergence results (9.99)–(9.103) imply that

$$\lim_{m \rightarrow \infty} \left\{ \|\mathbf{H} - \mathbf{H}_{(m)}\|_{C([0,T], L^2(\mathbb{T}^3))} + \|\mathbf{E} - \mathbf{E}_{(m)}\|_{C([0,T], L^2(\mathbb{T}^3))} \right\} = 0, \quad (9.109)$$

and that there exists an integer m_0 and a constant $C > 0$ such that

$$\|\mathbf{H}\|_{C([0,T], H^{N-1}(\mathbb{T}^3))} + \|\mathbf{E}\|_{C([0,T], H^{N-1}(\mathbb{T}^3))} \leq C, \quad (9.110)$$

$$\sup_{m \geq m_0} \left\{ \|\mathbf{H}_{(m)}\|_{C([0,T], H^{N-1}(\mathbb{T}^3))} + \|\mathbf{E}_{(m)}\|_{C([0,T], H^{N-1}(\mathbb{T}^3))} \right\} \leq C. \quad (9.111)$$

From (9.109), (9.110)–(9.111), and the Sobolev interpolation result (9.14), we deduce that if $N' < N - 1$, then

$$\lim_{m \rightarrow \infty} \left\{ \|\mathbf{H} - \mathbf{H}_{(m)}\|_{C([0,T], H^{N'}(\mathbb{T}^3))} + \|\mathbf{E} - \mathbf{E}_{(m)}\|_{C([0,T], H^{N'}(\mathbb{T}^3))} \right\} = 0. \quad (9.112)$$

Fixing a real number N' satisfying $3/2 < N' < 2$ and using (9.112) and the Sobolev embedding result (9.9), we deduce that

$$\lim_{m \rightarrow \infty} \left\{ \|\mathbf{H} - \mathbf{H}_{(m)}\|_{C([0,T] \times \mathbb{T}^3)} + \|\mathbf{E} - \mathbf{E}_{(m)}\|_{C([0,T] \times \mathbb{T}^3)} \right\} = 0. \quad (9.113)$$

Next, we use (9.110), (9.111), (9.113), (9.9), and (9.12) to deduce that there is a constant $C > 0$ such that if m is sufficiently large, then for $t \in [0, T]$, the following estimate holds for the function f appearing on RHSs (9.106)–(9.107):

$$\begin{aligned} \|f(\mathbf{H}, \mathbf{E}) - f(\mathbf{H}_{(m)}, \mathbf{E}_{(m)})\|_{H^{N-1}(\Sigma_t)} &\leq C\|\mathbf{H} - \mathbf{H}_{(m)}\|_{H^{N-1}(\Sigma_t)} \\ &\quad + C\|\mathbf{E} - \mathbf{E}_{(m)}\|_{H^{N-1}(\Sigma_t)}. \end{aligned} \quad (9.114)$$

Next, we use (9.110), (9.111), (9.113), and (9.40) to deduce that if m is sufficiently large, then for $t \in [0, T]$, the last term on RHS (9.114) obeys the following bound:

$$\|\mathbf{E} - \mathbf{E}_{(m)}\|_{H^{N-1}(\Sigma_t)} \leq C\|\mathbf{H} - \mathbf{H}_{(m)}\|_{H^{N-1}(\Sigma_t)}. \quad (9.115)$$

The desired bound (9.108) follows from (9.114) and (9.115). Kato's framework (see [31, Section 7.4]) then allows one to conclude that

$$\lim_{m \rightarrow \infty} \|\mathbf{H} - \mathbf{H}_{(m)}\|_{C([0,T], H^{N-1}(\mathbb{T}^3))} = 0. \quad (9.116)$$

Moreover, (9.115) and (9.116) imply that

$$\lim_{m \rightarrow \infty} \|\mathbf{E} - \mathbf{E}_{(m)}\|_{C([0,T], H^{N-1}(\mathbb{T}^3))} = 0. \quad (9.117)$$

Finally, in view of Definition 9.15 and the relation (9.33c), we note that the desired convergence results (9.104)–(9.105) follow from (9.116) to (9.117) and

the standard Sobolev calculus [which is needed to handle the components $\alpha = 0$ in (9.104)–(9.105)]. \square

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