

On the nature of variations in the measured star formation efficiency of molecular clouds

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ABSTRACT

Measurements of the star formation efficiency (SFE) of giant molecular clouds (GMCs) in the Milky Way generally show a large scatter, which could be intrinsic or observational. We use magnetohydrodynamic simulations of GMCs (including feedback) to forward-model the relationship between the true GMC SFE and observational proxies. We show that individual GMCs trace broad ranges of observed SFE throughout collapse, star formation, and disruption. Low measured SFEs ($\ll 1$ per cent) are ‘real’ but correspond to early stages; the true ‘per-freefall’ SFE where most stars actually form can be much larger. Very high ($\gg 10$ per cent) values are often artificially enhanced by rapid gas dispersal. Simulations including stellar feedback reproduce observed GMC-scale SFEs, but simulations without feedback produce $20\times$ larger SFEs. Radiative feedback dominates among mechanisms simulated. An anticorrelation of SFE with cloud mass is shown to be an observational artefact. We also explore individual dense ‘clumps’ within GMCs and show that (with feedback) their bulk properties agree well with observations. Predicted SFEs within the dense clumps are $\sim 2\times$ larger than observed, possibly indicating physics other than feedback from massive (main-sequence) stars is needed to regulate their collapse.

Key words: stars: formation – ISM: clouds – H II regions – galaxies: star formation.

1 INTRODUCTION

Giant molecular clouds (GMCs) are the sites of star formation within the Galaxy (Myers et al. 1986; Shu, Adams & Lizano 1987; Scoville & Good 1989). They are regions of elevated ($> 100 \text{ cm}^{-3}$) molecular gas density with typical masses $M \sim 4 \times 10^4$ to $4 \times 10^6 M_\odot$ and radii $R \sim 10\text{--}100 \text{ pc}$, with a characteristic surface density of the order of $\Sigma \sim 100 M_\odot \text{ pc}^{-2}$ in local galaxies (Solomon et al. 1987; Bolatto et al. 2008). Star-forming GMCs tend to host massive stars and H II regions, have supersonically turbulent internal gas motions (Larson 1981), and may be self-gravitating (McKee & Tan 2003). It is thus believed that the evolution of star-forming clouds is the result of a complex interplay of stellar and protostellar feedback, supersonic magnetohydrodynamic (MHD) turbulence, and gravity in concert (McKee & Ostriker 2007; Krumholz et al. 2014).

Possibly the most powerful diagnostic of the effects of these physical mechanisms is the star formation efficiency (SFE) of a

molecular cloud: the fraction of the molecular gas mass converted to stars. The question of what fraction of a molecular cloud’s mass is converted to stars, and how quickly, is a fundamental one in star formation theory. Turbulence, magnetic fields, and feedback can all oppose the gravitational collapse that leads to star formation, and in doing so they can reduce the SFE to varying degrees.

The SFE of star-forming clouds has been measured with many different methodologies and tracers of both stellar mass and molecular gas mass,¹ but virtually all studies of Local Group clouds have found that typical (i.e. median) values are of the order of 1 per cent (Myers et al. 1986; Mooney & Solomon 1988; Williams & McKee 1997; Evans et al. 2009; Heiderman et al. 2010; Lada, Lombardi & Alves 2010; Murray 2011; Lee, Miville-Deschênes & Murray 2016; Vutisalchavakul, Evans & Heyer 2016; Ochsendorf et al. 2017). However, the cited studies have also generally found considerable *scatter* in the SFE – typically at least 0.5 dex.

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¹ See Section 2 for the various definitions of SFE and how they are measured; our discussion thus far is not specific to any in particular.

If this scatter reflects an actual diversity in the intrinsic scale of the SFE of molecular clouds with otherwise similar properties, then it presents a serious challenge to theories that attempt to explain the SFE of molecular clouds in terms of their large-scale turbulent properties such as the virial parameter or Mach number (e.g. Krumholz & McKee 2005; Hennebelle & Chabrier 2011; Padoan & Nordlund 2011; Federrath & Klessen 2012), as the variations in these properties were found to account for less than ~ 0.24 dex of the observed scatter (Lee et al. 2016). It would also challenge theories that attempt to explain the SFE of molecular clouds in terms of the balance of feedback from massive stars and gravity in a collapse-blowout scenario (Fall, Krumholz & Matzner 2010; Murray, Quataert & Thompson 2010; Dale, Ercolano & Bonnell 2012; Hopkins, Quataert & Murray 2012; Dale et al. 2014; Myers et al. 2014a; Raskutti, Ostriker & Skinner 2016; Kim et al. 2017; Grudić et al. 2018): stochastic variations in the SFE for a fixed set of cloud parameters tend to be rather small in numerical simulations, and the SFE spread predicted from the variations in the cloud properties that determine the SFE (e.g. surface density for momentum-conserving feedback, escape velocity for expanding HII bubbles) are also much smaller than observed. However, a more likely explanation for the scatter comes from the fact that these observationally inferred efficiencies have intrinsic variation over the lifetime of a GMC that does not necessarily reflect the true SFE. Although one theoretical picture of star-forming clouds is one of quasi-equilibrium (Zuckerman & Evans 1974; Shu et al. 1987; Krumholz, Matzner & McKee 2006) with a relatively steady star formation rate (SFR), the age distributions of nearby star-forming regions suggest an accelerating SFR (Palla & Stahler 2000). This can produce large variations in the stellar mass tracer over the lifetime of a single cloud. Such acceleration has a theoretical basis in the behaviour of self-gravitating isothermal supersonic turbulence, wherein it is expected that $\dot{M}_* \propto t$ from both analytic considerations (Murray & Chang 2015) and hydrodynamics simulations (Lee, Chang & Murray 2015; Vázquez-Semadeni 2015; Murray et al. 2017).

The inferred gas mass will also vary over the lifetime of the cloud: while the effect of gas consumption might be negligible if overall efficiencies are small, molecular gas will also be destroyed and ejected by stellar feedback, so towards the end of a cloud's star-forming lifetime the inferred efficiency might be biased upward. Semi-analytic models of cloud evolution that model both the effects of time-varying SFR and mass-loss due to feedback have been found to produce SFE scatter similar to that observed (Feldmann & Gnedin 2011; Lee et al. 2016). Meanwhile, many simulations of star-forming clouds have been done that consider at least some subset of the important stellar feedback channels (Murray et al. 2010; Vázquez-Semadeni et al. 2010; Dale et al. 2012, 2013; Colín, Vázquez-Semadeni & Gómez 2013; Dale et al. 2014; Skinner & Ostriker 2015; Howard, Pudritz & Harris 2016, 2017; Raskutti et al. 2016; Dale 2017; Gavagnin et al. 2017; Kim et al. 2017; Vázquez-Semadeni, González-Samaniego & Colín 2017; Grudić et al. 2018; Kim, Kim & Ostriker 2018, for review see Krumholz et al. 2014; Dale 2015), however of these only Geen, Soler & Hennebelle (2017) has addressed the specific problem of the interpretation of predicted molecular cloud SFEs vis-a-vis observations. They performed MHD simulations of the evolution of a low-mass molecular cloud with ionizing radiation feedback, and compared simulation results with SFE measurements in nearby star-forming regions derived from YSO counts (e.g. Lada et al. 2010). Notably, they found that errors and biases in the inferred SFE can be quite large depending upon the time of observation during the cloud lifetime. They also found

that the stellar feedback was necessary to reproduce observations, finding that observations were most consistent with simulated clouds of mean surface density $\Sigma_{\text{gas}} \sim 40 M_{\odot} \text{pc}^{-2}$.

In this paper, we use a suite of MHD cloud collapse simulations modelling Milky Way GMCs to make a self-consistent prediction for the evolution of the SFE-related observables of a star-forming cloud. By including the effects of feedback from massive stars (in the form of stellar winds, radiation, and supernova explosions), we are able to follow the entire cloud lifetime from initial collapse to eventual disruption by stellar feedback. We will show the SFE observations are reasonably consistent with the hypothesis that GMCs with a given set of bulk properties do not have widely different star formation histories – rather, the observed spread in SFE is comparable to that observed over the lifetime of a single cloud. The model of feedback-moderated star formation can thus explain the observed SFEs of molecular clouds.

2 STAR FORMATION EFFICIENCY IN THEORY AND OBSERVATION

There are several flavours of SFE, some of which are motivated by observational convenience and others which are motivated by theory. We summarize the various definitions of SFE and the quantities from which they are derived in Table 1. First, we emphasize that we are interested in SFE as on the scale of individual gas clouds, rather than the SFE integrated over a larger region or an entire galaxy. In principle, these two SFEs can be completely decoupled from one another, and in feedback-regulated models for the Kennicutt (1998) relation, they generally are to some extent (Thompson, Quataert & Murray 2005; Ostriker & Shetty 2011; Faucher-Giguère, Quataert & Hopkins 2013; Orr et al. 2018).

Among the possible cloud-scale SFEs, the most conceptually straightforward is the ‘integrated’ SFE, the fraction of the gas mass that is converted to stars across the entire lifetime of a cloud:

$$\epsilon_{\text{int}} = \frac{M_*(t = \infty)}{M_{\text{gas}}(t = 0)}, \quad (1)$$

where M_* is the total mass in stars formed and M_{gas} is the total gas mass. ϵ_{int} is of particular interest because it is sensitive to the details of stellar feedback physics, as eventually a sufficient number of massive stars will form to expel the gas. ϵ_{int} ultimately determines the mapping between the GMC and star cluster mass functions in a galaxy, and dictates the fraction of stars remaining in a gravitationally bound clusters after gas expulsion (Tutukov 1978; Hills 1980; Mathieu 1983; Lada, Margulis & Dearborn 1984; Elmegreen & Clemens 1985; Baumgardt & Kroupa 2007). Although this quantity is ubiquitously reported in numerical simulations of star-forming clouds, it is not readily observable. It is difficult to define an unambiguous ‘initial’ gas mass because the evolution of the mass of GMCs is often highly dynamic, subject to ongoing processes of accretion, merging, and splitting (Dobbs & Pringle 2013). However, even supposing that a completely isolated, self-gravitating initial gas mass can be identified, the desired gas and stellar masses must be measured at the beginning and the end of the star-forming lifetime, respectively. Thus, although ϵ_{int} is a quantity of great theoretical interest, we must resort to measuring it by proxy.

Instead, one might measure the ‘instantaneous’ SFE, which is simply the mass fraction of stars associated with the star-forming cloud at a given time (Myers et al. 1986):

$$\epsilon = \frac{M_*(t)}{M_*(t) + M_{\text{gas}}(t)}. \quad (2)$$

ϵ will evolve from 0 to some finite value during the star-forming lifetime of a cloud, so a certain amount of scatter in this quantity is expected even for a population of clouds with identical properties. As $t \rightarrow \infty$, $\epsilon \rightarrow \epsilon_{\text{int}}$.

The natural time-scale for the evolution of self-gravitating objects is the gravitational freefall time,

$$t_{\text{ff}} = \sqrt{\frac{3\pi}{32G\bar{\rho}}} = 13.2 \text{ Myr} \left(\frac{\Sigma}{50 M_{\odot} \text{ pc}^{-2}} \right)^{-\frac{1}{2}} \left(\frac{R}{100 \text{ pc}} \right)^{\frac{1}{2}}, \quad (3)$$

where $\bar{\rho}$ is the volume-averaged density of the cloud, $\Sigma = M/\pi R^2$ is the average surface density, and R the effective radius. This fact has motivated the development of theoretical models that predict the *per-freefall* SFE ϵ_{ff} , the fraction of gas converted to stars per freefall time (Krumholz & McKee 2005; Hennebelle & Chabrier 2011; Padoan & Nordlund 2011; Federrath & Klessen 2012):

$$\epsilon_{\text{ff}} = \frac{\dot{M}_{\star}(t) t_{\text{ff}}(t)}{M_{\text{gas}}(t)}, \quad (4)$$

where \dot{M}_{\star} is the SFR. These theories typically predict $\epsilon_{\text{ff}} \sim 1$ per cent for molecular clouds with properties similar to those observed in local spiral galaxies (e.g. Bolatto et al. 2008), solely from the properties of isothermal supersonic turbulence plus a gravitational collapse criterion. Because these physics are scale-free, this could potentially explain the observation that $\epsilon_{\text{ff}} \sim 1$ per cent on a wide range of scales from galaxies to dense star-forming clumps (Krumholz, Dekel & McKee 2012a).

However, such a steady and universal SFE has not been found in hydrodynamics simulations of self-gravitating isothermal turbulence, with or without a source of turbulent stirring to maintain a constant virial parameter (Kritsuk, Norman & Wagner 2011; Padoan, Haugbølle & Nordlund 2012; Lee et al. 2015; Murray et al. 2017). Rather, simulations with virial parameters ~ 1 have found that ϵ_{ff} tends to increase roughly linearly to a saturation point of the order of several tens of percent. This saturation point has a residual dependence upon the magnetic field strength at the factor of 2 level, and is actually more consistent with ‘multifreefall’ versions of the turbulence-regulated theories that account for the local freefall time fully, predicting much greater SFE (Federrath & Klessen 2012).

Grudić et al. (2018) (hereafter G18) argued that $\epsilon_{\text{ff}} \sim 1$ per cent is the typical value observed for molecular clouds because feedback from massive stars is able to prevent runaway star formation, and that the ubiquity of the observed 1 per cent value is a consequence of the lack of variation of cloud surface density Σ , which they found determined both ϵ_{int} and ϵ_{ff} . However, this cannot explain slow star formation in regions where massive stars are absent. Federrath (2015) found that protostellar outflow feedback can bring ϵ_{ff} down to values of the order of 1 per cent in the regime of low-mass cluster formation, but this mechanism is unlikely to scale up to more massive systems. It is thus possible that the protostellar and massive stellar feedback complement each other in limiting the *per-freefall* SFE of molecular clouds on different scales.

Measuring ϵ and ϵ_{ff} requires some estimate of the stellar mass formed and the currently present gas mass. We distinguish between the true instantaneous SFE ϵ and its observational tracer-inferred value:

$$\epsilon_{\text{obs}} = \frac{M_{\star, \text{tr}}(t)}{M_{\star, \text{tr}}(t) + M_{\text{mol, tr}}(t)}, \quad (5)$$

where $M_{\text{mol, tr}}$ and $M_{\star, \text{tr}}$ are the tracer-inferred molecular gas and stellar masses, respectively. Similarly, we define the tracer-inferred

proxy for ϵ_{ff} :

$$\epsilon_{\text{ff, obs}} = \frac{M_{\star, \text{tr}}(t) t_{\text{ff}}(t)}{M_{\text{mol, tr}}(t) \tau_{\text{tr}}}, \quad (6)$$

where we introduce the characteristic lifetime τ_{tr} of the species being traced, so that the SFR \dot{M}_{\star} , which is not directly observable, may be estimated as $M_{\star, \text{tr}}/\tau_{\text{tr}}$.

2.1 Stellar mass tracers

There are several methods for estimating M_{\star} . The most readily measured tracer of stellar mass is the emission associated with H II regions, such as far-IR (Myers et al. 1986), mid-IR (Vutisalchavakul et al. 2016), or free–free emission (Murray & Rahman 2010; Lee, Murray & Rahman 2012; Vutisalchavakul et al. 2016). This flux is dominated by the contribution from the reprocessed radiation from young, massive stars, and effectively traces the mass in stars younger than the ionizing flux-weighted mean stellar lifetime of a stellar population, $\tau_{\text{MS}} = 3.9 \text{ Myr}$ (McKee & Williams 1997; Murray 2011). We refer to this stellar mass as the ‘live’ stellar mass, $M_{\star, \text{live}}$. $M_{\star, \text{live}}$ can underestimate the total stellar mass formed in a cloud if its star formation history spans longer than τ_{MS} , which appears to be the case for a majority of local GMCs (Kawamura et al. 2009; Fukui & Kawamura 2010; Murray 2011; Lee et al. 2016).

Another tracer of the formed stellar mass is the mass of young stellar objects (YSOs), M_{young} , which can be measured in sufficiently well-resolved star-forming clouds or clumps (Evans et al. 2009; Heiderman et al. 2010; Evans et al. 2014; Heyer et al. 2016). In this case the measured mass traces the stars formed over the characteristic evolutionary time-scale τ_{SF} for the class of YSO that is being counted, typically taken to be 0.5 and 2 Myr for Class I and II YSOs, respectively (Evans et al. 2009). Whatever the stellar mass tracer, the characteristic lifetime τ_{tr} introduces certain biases in the inferred stellar mass. If the star-forming lifetime of a cloud scales with the freefall time, then $M_{\star, \text{tr}}/M_{\star} \sim \tau_{\text{tr}} t_{\text{ff}}$, so $M_{\star, \text{tr}}$ would typically underestimate M_{\star} in less-dense clouds that have longer freefall times. On the other hand, assuming $\dot{M}_{\star} = M_{\star, \text{tr}}/\tau_{\text{tr}}$ provides a reasonably accurate estimate of the SFR of clouds with lifetimes longer than τ_{tr} , averaged over τ_{tr} , but if the star formation has only been occurring for a shorter time $\Delta t \ll \tau_{\text{tr}}$, this method will underestimate the true SFR by a factor $\sim \Delta t/\tau_{\text{tr}}$.

When comparing simulations to observations, we will model stellar mass tracers from simulation data in a straightforward manner, simply taking $M_{\star, \text{tr}}$ to be the mass of the star particles that formed more recently than τ_{tr} .

2.2 Gas mass tracers

The ro-vibrational lines of molecular hydrogen are not excited in cold molecular clouds, so it is also necessary to use a tracer to measure M_{mol} . Most commonly, this tracer is CO, the second most common molecule in the cold ISM and its primary coolant. M_{mol} can be estimated by measuring the total luminosity L_{CO} of a CO rotational transition and convert this to a gas mass via the CO-to- H_2 conversion factor X_{CO} (Bolatto, Wolfire & Leroy 2013). Most studies of molecular clouds measure the brightest line, the $^{12}\text{CO J} = 1-0$ transition, which traces the gas mass of molecular number density. Higher transitions, or emission from the less-abundant ^{13}CO species, trace higher densities, $> 10^3 \text{ cm}^{-3}$.

In addition to CO observations, we shall consider observations of dense clumps within GMCs. Dense clumps are typically traced by

the HCN $J = 1-0$ transition, which generally have been understood to trace the gas mass of density 10^4 cm^{-3} or greater (Gao & Solomon 2004), however recent work has brought into question whether HCN emission really originates from such high-density gas (Goldsmith & Kauffmann 2017; Kauffmann et al. 2017). Gas at this density is believed to have a more direct relationship with star formation, as there is a proportional relationship between FIR luminosity and HCN luminosity on the scale of galaxies (Gao & Solomon 2004; Wu et al. 2005) and dense clumps within the Milky Way (Wu et al. 2010). This is also roughly the threshold above which Lada et al. (2010) proposed a linear relationship between gas mass (derived from dust extinction mapping) and the SFR derived from YSO counts. However, the correspondence between the gas mass actually measured by Lada et al. (2010) and the gas mass denser than 10^4 cm^{-3} is questionable (Clark & Glover 2014). We will be able to examine this relationship in our simulations (Section 5).

All of these methods of tracing the gas distribution of a cloud have their own uncertainties, biases, and limitations. A fully rigorous comparison between theory and observations would use a calculation that models the relevant dust and molecular abundances self-consistently. One would then model the species' observed emission or extinction self-consistently via a radiative transfer calculation to produce mock observations to which the same analysis can be applied as the actual observation. We consider this to be beyond the scope of this work, and throughout we shall simply compare the simulated gas mass directly with observationally reported gas masses. We will model M_{mol} from the simulation data in a straightforward manner, using the Krumholz & Gnedin (2011) prescription to derive the abundance of H_2 , and assuming that a faithful tracer of H_2 is available.

2.3 Data compilation

We will compare simulations with measurements from several recent studies that have measured ϵ and ϵ_{ff} in both GMCs and dense clumps in the Milky Way with various methodologies. These studies, their tracers, and their results are summarized in Table 2. We consider star-forming GMC data from Evans et al. (2014), Vutisalchavakul et al. (2016), and Lee et al. (2016). We also consider data from star-forming dense clumps from Wu et al. (2010) and Heyer et al. (2016).

All of the studies in Table 2 report values for $\epsilon_{\text{ff, obs}}$, but only Lee et al. (2016) reported ϵ_{obs} (their ϵ_{br}). Where stellar masses are not reported, the measured stellar mass $M_{\text{*, tr}}$ is obtained by simply multiplying reported SFRs by the tracer lifetime τ_{tr} . For Vutisalchavakul et al. (2016), we compute it by multiplying the SFRs inferred from the clouds' $24 \mu\text{m}$ luminosities by the ionization-weighted mean stellar lifetime $\tau_{\text{MS}} = 3.9 \text{ Myr}$. We compute the stellar mass in the Wu et al. (2010) clumps by assuming that their IR luminosities are due to reprocessed radiation from a stellar population with a Kroupa (2002) IMF, and hence

$$M_{\text{*, tr}} = 8 \times 10^{-4} \left(\frac{L_{\text{IR}}}{L_{\odot}} \right) M_{\odot} \quad (7)$$

and we consider only those clumps with $L_{\text{IR}} > 10^{4.5} L_{\odot}$ so that the IMF is well sampled (Heiderman et al. 2010). The stellar mass obtained directly from YSO counting by Heyer et al. (2016) is a lower bound on M_{young} , while an upper bound is obtained by correcting the total stellar mass assuming a Kroupa IMF. Throughout, we will take the IMF-corrected SFEs computed in this way, but emphasize that these are in fact upper bounds. For consistency with Heyer et al. (2016), we estimate SFRs in the Wu

et al. (2010) clumps via equation (6) assuming the same $\tau_{\text{tr}} = 0.5 \text{ Myr}$ as for Heyer et al. (2016). Under the above assumptions, SFEs for both catalogues of dense clumps are in good agreement.

3 SIMULATIONS

We perform a suite of 3D MHD simulations of GMC collapse, star formation, and cloud disruption with the GIZMO² code (Hopkins 2015; Hopkins & Raives 2016), with the prescriptions for star formation, cooling and stellar feedback developed for the Feedback In Realistic Environments (FIRE) simulations (Hopkins et al. 2014).³ The simulations are similar in methodology to the Grudić et al. (2018) simulations, using the Meshless Finite Mass Lagrangian MHD method (Hopkins & Raives 2016) and feedback prescriptions as in FIRE-2 (Hopkins et al. 2018b). However, the simulations differ in the following ways that we shall describe in turn: the initial conditions (ICs), the star formation prescription, and a modification of the feedback routines that accounts for the effects of undersampling the IMF when the total stellar mass is small. The reader is referred to G18 paper for a description of the general results and behaviour of this type of simulation, and to Hopkins et al. (2018b) for the details of the numerical implementations of feedback and ISM physics.

3.1 Initial conditions

To model Milky Way GMCs more closely than G18, we simulate three points in mass–radius parameter space, with masses $M = 2 \times 10^4, 2 \times 10^5, \text{ and } 2 \times 10^6 M_{\odot}$, and radii $R = 10, 30, \text{ and } 100 \text{ pc}$, respectively, for a mean surface density of $64 M_{\odot} \text{ pc}^{-2}$. This parameter space falls within the range of parameters in which most star-forming GMCs in the MWG lie (e.g. Miville-Deschênes, Murray & Lee 2017). However, we emphasize that selecting a single surface density is not fully representative of a real GMC population, and since we expect the SFE to be dependent on the surface density, we expect there to be residual variations in SFE that this parameter study does not account for.

Unlike G18, the initial velocity field has no bulk rotation component to support it at constant mean surface density – it is dominated by turbulent motions, which is more consistent with the properties of GMCs in the Local Group, which have quite weak rotation (Braine et al. 2018). Krumholz, Klein & McKee (2012b) found that the initial rise of the SFR was artificially fast when an initial tophat-density distribution was used, as in G18. As this can potentially affect the SFE observables of interest, we follow Krumholz et al. (2012b) by using ICs extracted from a simulation of driven isothermal supersonic MHD turbulence without self-gravity. The turbulent forcing is realized as a Orstein–Uhlenbeck process as in Bauer & Springel (2012), with purely solenoidal forcing, normalized so that the RMS Mach number saturates to ~ 10 and the turbulent plasma β to ~ 20 (e.g. Federrath et al. 2014). For each set of cloud parameters, we effectively sample three independent statistical realizations of the turbulent ICs by extracting snapshots separated by 10 crossing times each. From each of these snapshots, we excise a sphere centred upon the density-weighted centre of mass and rescale the particle masses, positions, and velocities to achieve the desired mass and radius and virial parameter $\alpha_{\text{vir}} = \frac{2E_{\text{turb}}}{|E_{\text{grav}}|} = 2$.

²A public version of this code is available at <http://www.tapir.caltech.edu/~phopkins/Site/GIZMO.html>.

³<http://fire.northwestern.edu>

Table 1. Summary of the quantities related to observed and theoretical SFE discussed in this paper, with defining equations given where applicable in Section 2.

Symbol	Name	Definition
ϵ_{int}	Integrated SFE	Equation (1)
ϵ	Instantaneous SFE	Equation (2)
ϵ_{ff}	Per-freefall SFE	Equation (4)
ϵ_{obs}	Tracer-inferred instantaneous SFE	Equation (5)
$\epsilon_{\text{ff, obs}}$	Tracer-inferred per-freefall SFE	Equation (6)
M_{gas}	Actual gas mass present in a cloud	
M_{\star}	Actual stellar mass formed in a cloud	
$M_{\text{mol, tr}}$	Tracer-inferred molecular gas mass	
$M_{\star, \text{tr}}$	Tracer-inferred stellar mass	
$M_{\star, \text{live}}$	M_{\star} inferred from emission associated with H II regions around massive stars (e.g. free-free, IR)	
$M_{0.8}$	Gas mass in a cloud with $A_k > 0.8$ mag	
M_{dense}	Gas mass in a cloud with $n_{\text{H}} > 10^4 \text{ cm}^{-3}$	

Table 2. Methodologies, parameter space, and summarized SFE results of several recent studies of star-forming clouds or clumps in the Milky Way. All quantities are given in the format median $^{+}_{-}\sigma$. *Class*: class of star-forming cloud studied: GMC or dense clump. M_{mol} *tracer*: method used to obtain the properties of the molecular gas distribution. M_{\star} *tracer*: emission type or object count used to estimate the SFR or stellar mass present. n_{H_2} : number density of molecular hydrogen at the volume-averaged cloud density $3M/(4\pi R^3)$, in cm^{-3} . Σ_{gas} : of the mean gas surface density $M/\pi R^2$. ϵ_{obs} : observed instantaneous SFE (equation 5). $\epsilon_{\text{ff, obs}}$: Observed per-freefall SFE (equation 6).

Study	Class	M_{gas} tracer	M_{\star} tracer	$\log \frac{n_{\text{H}_2}}{\text{cm}^{-3}}$	$\log \frac{\Sigma_{\text{gas}}}{M_{\odot} \text{ pc}^{-2}}$	$\log \epsilon_{\text{obs}}$	$\log \epsilon_{\text{ff, obs}}$
Wu et al. (2010)	Dense clumps	HCN 1 \rightarrow 0	FIR	4.08 $^{4.68}_{3.38}$	3.00 $^{3.38}_{2.63}$	-1.10 $^{-0.86}_{-1.76}$	-1.44 $^{-0.82}_{-2.03}$
Evans, Heiderman & Vutisalchavakul (2014)	GMCs	Dust extinction	YSO counts	2.62 $^{2.99}_{2.33}$	1.80 $^{1.97}_{1.76}$	-1.72 $^{-1.37}_{-2.19}$	-1.79 $^{-1.48}_{-2.38}$
Heyer et al. (2016)	Dense clumps	Dust Emission	YSO counts	4.11 $^{4.62}_{3.64}$	2.78 $^{3.04}_{2.56}$	-1.11 $^{-0.62}_{-1.66}$	-1.32 $^{-0.84}_{-1.87}$
Vutisalchavakul et al. (2016)	GMCs	^{13}CO 1 \rightarrow 0	Free-free, MIR	2.20 $^{2.72}_{1.69}$	1.94 $^{2.23}_{1.67}$	-2.26 $^{-1.82}_{-2.94}$	-2.40 $^{-1.99}_{-2.89}$
Lee et al. (2016)	GMCs	^{12}CO 1 \rightarrow 0	Free-free	1.36 $^{1.82}_{0.78}$	1.88 $^{2.19}_{1.40}$	-1.97 $^{-1.20}_{-2.76}$	-1.73 $^{-0.96}_{-2.66}$

The magnetic field is rescaled to preserve the turbulent plasma β from the original turbulent box simulation. In all simulations, the gas mass is initially resolved in 10^6 particles. We found in Grudić et al. (2018) that the SFE converges rapidly in simulations using these methods, with similar SFE achieved at 50^3 resolution.

3.2 Star formation

We handle star formation with an accreting sink particle prescription, derived from Federrath et al. (2010) and described fully in Guszejnov et al. (2018). To summarize, gas cells are converted to sink particles when they are self-gravitating at the resolution scale (including thermal, turbulent, and magnetic energy contributions), or equivalently, the effective Jeans mass is no longer resolvable. They must also be a local density maximum within their hydrodynamic stencil of nearest neighbour cells, and be a site of converging flow ($\nabla \cdot \mathbf{v} < 0$). Gas cells are accreted by an existing sink particle if they are gravitationally bound to it and fall within an accretion radius of 0.01 pc. This is a more appropriate method for this problem than the discretization of stellar mass into equal-mass star particles used in G18, as the mass resolution of the simulations is always $\ll 100 M_{\odot}$, sufficient to resolve the formation of some stellar-mass objects.

3.3 Stellar feedback

A fully self-consistent determination of the stellar feedback budget would require a self-consistent treatment of massive star formation, which is currently an open physics problem that is sensitive to

radiative transfer physics on scales of 1000 au or less (Zinnecker & Yorke 2007; Krumholz et al. 2009; Tan et al. 2014; Rosen et al. 2016), which we do not resolve in our simulations. Therefore, in the spirit of G18, we choose not to attempt to model the IMF self-consistently, and assume that the mass, energy, and momentum fluxes from stellar feedback are consistent with that from a single stellar population with a well-sampled Kroupa (2002) IMF. We discretize this feedback budget among sink particles as in Sormani et al. (2017) and Su et al. (2018), giving each particle a discrete number of ‘O-stars’ sampled from a Poisson distribution with mean $\lambda = \frac{\Delta m}{100 M_{\odot}}$, where Δm is the mass of the particle. The O-star number is incremented by a Poisson-sampled value whenever a sink particle is spawned or accretes. This captures some of the effect of undersampling the IMF in low-mass clusters. Fluxes due to stellar feedback are scaled in proportion to the number of O stars a particle has, and in the limit where the total stellar mass is $\gg 100 M_{\odot}$, the IMF-averaged stellar feedback budget is recovered.

3.3.1 Radiation

We use the LEBRON radiative transfer approximation (for details see Hopkins et al. 2018b), which accounts for absorption of single-scattered photons within the stencil around a star particle (including ionizing radiation, expanding the search radius until ionizing photons are exhausted). Photons not absorbed within the stencil are propagated through the simulation domain using an optically thin approximation that uses the gravity solver, with extinction corrections at the source and absorber. The radiation field is computed in far-UV, near-UV, optical/NIR, and FIR bins,

subject to extinction according to appropriate flux-mean opacities, including dust extinction. We have shown in previous work that this radiative transfer approximation gives cloud SFEs in fair agreement (factor of ~ 2) with results from flux-conservative M1 closure scheme (e.g. Rosdahl & Teyssier 2015, as demonstrated in Hopkins & Grudić 2019), and even better agreement with the results of a state-of-the-art adaptive ray tracing scheme (e.g. Kim et al. 2018, as shown in Grudić & Hopkins 2018).

3.3.2 Stellar winds

Stellar winds are emitted from sink particles hosting O-stars, with mass, energy, and momentum flux rates proportional to that expected from a simple stellar population. These fluxes are injected into the gas particles surrounding the sink particle using the fully conservative coupling scheme in Hopkins et al. (2018a). Note that although the high-velocity outflows associated with stellar winds impose punishing time-step constraints on Eulerian codes due to the Courant–Friedrichs–Lewy condition, this is less of an issue for our Galilean-invariant, Lagrangian MHD method (Hopkins & Raives 2016), whose time-step is constrained only by the local signal velocity rather than the bulk fluid velocity. Lagrangian gas cells surrounding feedback-emitting particles do still tend to be driven to short time-steps due to the presence of shocks and hot gas, but those cells tend to disperse quickly.

3.3.3 Supernovae

Supernova explosions occur stochastically after ~ 3 Myr in sink particles hosting O-stars, as described in Su et al. (2018). We also adopt the Hopkins et al. (2018a) conservative coupling scheme for supernova explosions, however at our mass resolution (which is never coarser than $2 M_{\odot}$), this simply amounts to dumping the thermal energy of the supernova into surrounding gas particles and resolving the energy-conserving Sedov–Taylor phase of supernova blastwaves self-consistently.

4 GMC STAR FORMATION HISTORIES

4.1 True SFE values

In all simulations, the cloud initially collapses in a disordered manner, with multiple centres of collapse and little initial global contraction (see Fig. 1). Stars eventually form in dense, gravitationally bound subregions until stellar feedback is sufficient to halt collapse and accretion locally. Eventually, a sufficient stellar mass forms that the entire cloud is disrupted by stellar feedback and star formation ceases. At this point, a fraction ϵ_{int} of the initial gas mass has been converted to stars. As has generally been found in similar simulations, an order-unity fraction of the gas mass is rapidly converted to stars on the freefall time-scale when stellar feedback is neglected. When stellar feedback is included, ϵ_{int} is always a few per cent and does not vary greatly across our parameter space. This is because all of the cloud models have the same mean initial surface density, which determines ϵ_{int} for feedback-disrupted self-gravitating molecular clouds (Fall et al. 2010; Grudić et al. 2018). This is in good agreement with the median value of ϵ_{obs} found in Milky Way GMCs (see Table 2), however much greater and smaller values are also observed, which we will address in Section 4.2. The variation in ϵ_{int} for different random realizations of a given point in parameter space is also quite small (< 0.1 dex). Therefore, even

when fully turbulent initial conditions are considered, the intrinsic SFE variations due to variations in specific microstates of the initial conditions clearly cannot explain the observed range of SFE values.

In Table 3, we report $T_{2\sigma}$, the length of time containing 95 per cent of star formation, as well as ϵ_{int} and the average value of ϵ_{ff} over entire the star formation history. Here, the freefall time used to compute ϵ_{ff} is that computed from the initial volume-averaged density, $t_{\text{ff},0} = \frac{\pi}{2\sqrt{2}} \sqrt{\frac{R^3}{GM}}$, however in Section 4.2 we will consider the effects of a dynamic mean cloud density upon the observed ϵ_{ff} . The volume-averaged density tends to increase slightly due to turbulent dissipation in the initial stages of cloud collapse, but it then decreases rapidly as stellar feedback launches outflows.

In general $t_{2\sigma} \sim t_{\text{ff},0}$, so most star formation is found to take place within a single initial freefall time (although this can be several *local* freefall times in the denser gas that forms as fragmentation proceeds), as found in G18 and similar works. In all instances, the SFR, and hence ϵ_{ff} , is found to vary significantly throughout the GMC lifetime. The SFR tends to continue to increase until star formation is quenched abruptly when the molecular cloud is disrupted by feedback. In Fig. 2, we present the detailed star formation histories of all simulations, plotting ϵ and ϵ_{ff} as functions of time in panels 1 and 2, respectively. We find that the initial growth of ϵ from the beginning of star formation is superlinear, with the exception of the $M = 2 \times 10^4 M_{\odot}$ runs, and is typically initially well described by a power law with index close to 2, as has been predicted analytically and found in hydrodynamic simulations without stellar feedback (Lee et al. 2015; Murray & Chang 2015; Murray et al. 2017) and with a more limited subset of feedback channels (Vazquez-Semadeni 2015; Raskutti et al. 2016; Geen et al. 2017). However, this state of affairs does not continue indefinitely, and stellar feedback eventually causes the SFR to level off and eventually fall to 0.

The lowest mass cloud models, with $M = 2 \times 10^4 M_{\odot}$, have the noisiest star formation histories (e.g. Fig. 2 panel 2). These clouds only ever only form 4–8 massive stars before being disrupted, so the proportional effect of an individual massive star on the overall cloud evolution is much greater than in the more massive clouds, which form tens to hundreds of massive stars, making the onset of feedback effectively ‘smoother’. The more pronounced effect of the discreteness of massive stars also explains the shallower, nearly linear initial growth of the SFR in the low-mass clouds compared to the more massive ones. We have confirmed that when feedback is disabled, the growth in stellar mass is superlinear as in the more massive cloud models.

Because $t_{2\sigma} \sim t_{\text{ff},0}$, ϵ_{ff} is on average of the same order as ϵ_{int} , which is ~ 100 per cent without stellar feedback and several per cent with stellar feedback. To summarize, we find the key results of the simulations of G18 concerning the true star formation efficiencies of molecular clouds still hold for the more realistic GMC and stellar feedback models we have considered here. Most star formation occurs within a single $t_{\text{ff},0}$, and during this time only several per cent of the initial gas mass is converted to stars, because this fraction is sufficient to disrupt the cloud via stellar feedback. This fraction ϵ_{int} is approximately the same for clouds of the same surface density, and depends upon spatial scale only weakly. We also find a time-varying ϵ_{ff} that initially grows in a manner similar to what was found in previous calculations that did not include stellar feedback (Lee et al. 2015; Murray & Chang 2015; Murray et al. 2017), however stellar feedback eventually halts the growth. We will now consider how these highly dynamic star formation histories would imprint upon the observed distributions of star formation efficiencies.

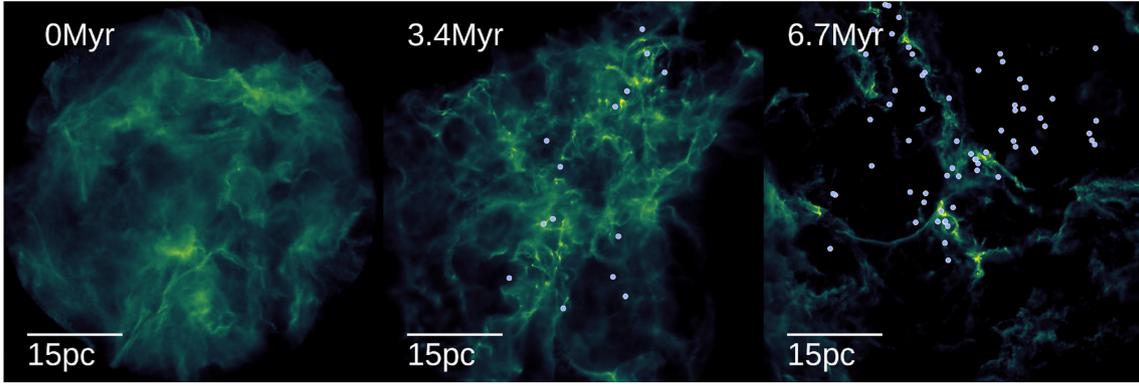


Figure 1. Gas surface density map showing the evolution of a simulated GMC with mass $2 \times 10^5 M_\odot$ and radius 30 pc, with a dynamic range of $10\text{--}1000 M_\odot \text{pc}^{-2}$. The cloud undergoes a turbulent, disordered collapse into stars until the combined feedback of massive stars (shown as dots) destroys the cloud. A movie of this sequence can be found at http://www.tapir.caltech.edu/mgrudich/M2e5_R30.mp4.

Table 3. Parameters and basic results of the simulations. (1) M : the initial total gas mass. (2) R : the initial cloud radius. (3) Random seed: the random realization of isothermal MHD turbulence used for the initial conditions. (4) Modifications: variations of subset of feedback mechanisms included. (5) t_{ff} : the initial freefall time computed from the mean density $3M/4\pi R^3$. (6) $t_{2\sigma}$: the length of time between the $\pm 2\sigma$ star formation times. (7) n_{H_2} : volume-averaged initial number density of H_2 . (8) ϵ_{int} : fraction of M converted to stars by the end of the simulation. (9–11) Star formation efficiencies, see Table 1. $\log \epsilon_{\text{obs}}$ and $\log \epsilon_{\text{ff, obs}}$ are given in the format median $^{+\sigma}_{-\sigma}$, with the quantiles computed over ‘observable’ lifetime of the cloud, during which massive stars are present and the cloud is above the assumed molecular gas surface density sensitivity threshold of $10 M_\odot \text{pc}^{-2}$ (see Section 4.2.1).

$M (M_\odot)$	R (pc)	Random seed	Modifications	t_{ff} (Myr)	$t_{2\sigma}$ (Myr)	$\log \frac{n_{\text{H}_2}}{\text{cm}^{-3}}$	$\log \epsilon_{\text{int}}$	$\log \epsilon_{\text{obs}}$	$\log \epsilon_{\text{ff, obs}}$
2×10^4	10	1		3.79	2.48	1.83	-1.39	$-0.79^{+0.68}_{-1.08}$	$-0.86^{+0.52}_{-1.45}$
2×10^4	10	1	No feedback	3.79	7.27	1.83	-0.23	$-0.18^{+0.07}_{-1.08}$	$-0.40^{+0.12}_{-1.49}$
2×10^4	10	2		3.79	3.08	1.83	-1.37	$-1.28^{+0.96}_{-1.69}$	$-1.44^{+0.70}_{-2.10}$
2×10^4	10	3		3.79	3.19	1.83	-1.36	$-1.06^{+0.02}_{-1.40}$	$-1.06^{+0.20}_{-1.86}$
2×10^5	30	1		6.22	5.12	1.39	-1.43	$-1.45^{+0.91}_{-2.44}$	$-1.58^{+0.64}_{-2.67}$
2×10^5	30	1	No feedback	6.22	14.19	1.39	-0.16	$-0.12^{+0.04}_{-1.20}$	$0.16^{+0.43}_{-1.39}$
2×10^5	30	2		6.22	6.64	1.39	-1.45	$-1.48^{+0.99}_{-2.10}$	$-1.57^{+0.63}_{-2.32}$
2×10^5	30	3		6.22	5.06	1.39	-1.42	$-1.35^{+0.99}_{-2.28}$	$-1.47^{+0.67}_{-2.53}$
2×10^6	100	1		11.98	15.83	0.825	-1.45	$-1.55^{+0.99}_{-2.64}$	$-1.38^{+0.28}_{-2.60}$
2×10^6	100	1	No feedback	11.98	28.61	0.825	-0.14	$-0.44^{+0.09}_{-1.62}$	$-0.21^{+0.42}_{-1.54}$
2×10^6	100	1	No radiative feedback	11.98	13.72	0.825	-1.10	$-1.33^{+0.54}_{-2.21}$	$-1.17^{+0.01}_{-2.16}$
2×10^6	100	1	No SNe	11.98	14.19	0.825	-1.46	$-1.57^{+1.03}_{-2.43}$	$-1.41^{+0.46}_{-2.39}$
2×10^6	100	1	No OB winds	11.98	12.66	0.825	-1.59	$-1.52^{+1.27}_{-2.36}$	$-1.36^{+0.75}_{-2.31}$
2×10^6	100	1	Radiative feedback only	11.98	14.89	0.825	-1.59	$-1.39^{+1.00}_{-2.26}$	$-1.20^{+0.37}_{-2.22}$
2×10^6	100	1	SN feedback only	11.98	12.43	0.825	-0.96	$-1.03^{+0.65}_{-2.22}$	$-0.90^{+0.15}_{-2.18}$
2×10^6	100	2		11.98	15.83	0.825	-1.53	$-1.65^{+1.22}_{-2.77}$	$-1.51^{+0.63}_{-2.71}$
2×10^6	100	3		11.98	10.79	0.825	-1.57	$-1.70^{+1.09}_{-3.00}$	$-1.62^{+0.60}_{-2.97}$

4.2 Tracer-inferred values

4.2.1 Modelling of observables

To forward-model ϵ_{obs} and $\epsilon_{\text{ff, obs}}$ from the simulations, we must estimate the observationally inferred M_\star and M_{mol} . One possibility is to perform ISM chemistry and radiative transfer calculations to directly model the observed emission maps, and apply the same procedure for identifying clouds and correlating them with young stars as was used in a particular study. This would be necessary to compare with observations in detail. This approach is possible in principle, but here we merely aim to explain various general features and trends from many studies of widely varying methodology, so

in this initial investigation we use simple approximations, leaving a more detailed treatment to future work.

We estimate the observed $M_{\star, \text{tr}}$ in the simulation data by taking $M_{\star, \text{live}}$, approximately the mass in stars younger than the ionization-weighted mean stellar lifetime 3.9 Myr (Murray 2011). We estimate $M_{\text{mol, tr}}$ by assuming that a perfect tracer of H_2 is available, and simply take the actual molecular gas mass M_{mol} . Note that the simulations do not include live chemistry, so the mass in H_2 is not followed self-consistently. Rather, we estimate the H_2 mass by calculating the molecular fraction f_{H_2} of each gas cell according to the analytic prescription of Krumholz & Gnedin (2011), which was found to agree well with detailed chemistry and radiation

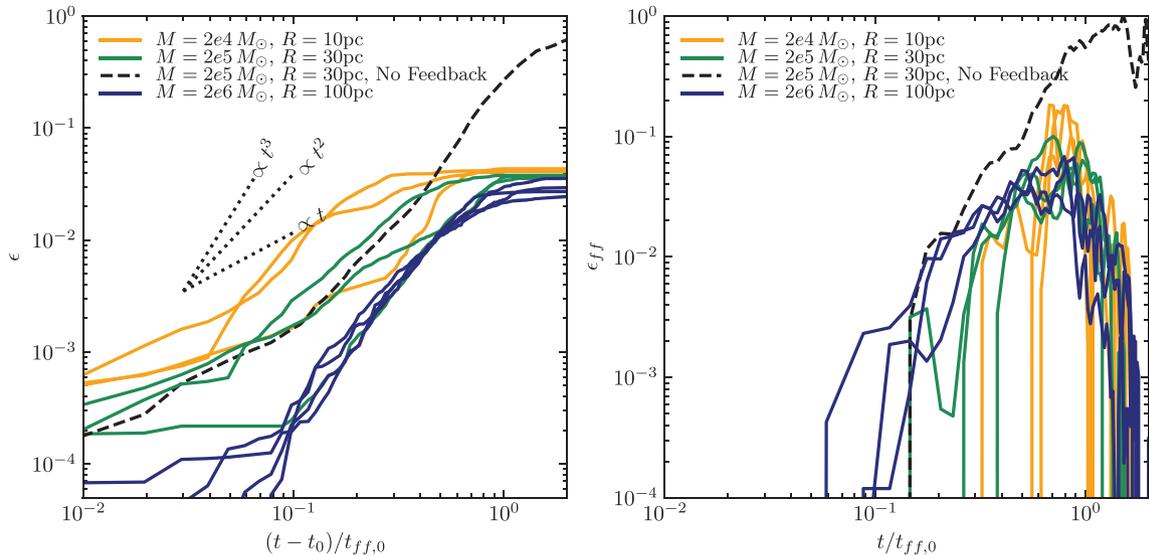


Figure 2. Star formation histories of the simulations. *Left:* the fraction of the initial gas mass converted to stars M_*/M_{tot} as a function of time since the formation of the first sink particle at t_0 , in units of the global cloud freefall time t_{ff} . In most cases, the stellar mass is $\propto (t - t_0)^2$ as the SFR ramps up, so there is intrinsic variation in the SFR that would translate into a range of observed ϵ_{ff} . Eventually, sufficient stellar mass forms to disrupt the cloud via stellar feedback, and $M_*/M \rightarrow \epsilon_{\text{int}}$, which is of the order of a few per cent when stellar feedback is included, but approaches 100 per cent in absence of feedback.

transfer calculations. We assume a standard Milky Way value for the external UV background (Draine 1978). This prescription requires an estimate of the effective dust optical depth τ_c at the position of each gas cell. This is calculated on-the-fly in the simulations using a local Sobolev-like column density estimator (Hopkins et al. 2012), but we compute τ_c more accurately in post-processing by ray-tracing the dust opacity field to infinity along 64 rays on an equal-area spherical grid. An optical depth τ_i is thus obtained for each ray, and the effective optical depth τ_c is that which gives the spherically averaged extinction over all angles θ and ϕ :

$$\exp(-\tau_c) = \frac{1}{4\pi} \int \exp(-\tau(\theta, \phi)) d\Omega \approx \langle \exp(-\tau_i) \rangle_i, \quad (8)$$

where $\langle \cdot \rangle_i$ denotes the mean value over all rays.

Modelling $\epsilon_{\text{ff, obs}}$ requires a measurement of t_{ff} , which depends upon the mean cloud density and hence its effective volume. For this, we use the 3D equivalent of the technique used in Miville-Deschênes et al. (2017) for deriving effective cloud volumes from CO emission maps. We take the volume of the ellipsoid with axes given by the eigenvalues of the 3D f_{H_2} -weighted covariance matrix of the gas distribution. Given eigenvalues λ_i , the observed effective volume is taken as $V = 4\pi R_{\text{eff}}^3/3$, where $R_{\text{eff}} = (\lambda_1 \lambda_2 \lambda_3)^{1/6}$.

Lastly, we must account for observational selection effects and reject simulation data that clearly would not be identified as a data point in a catalogue of star-forming GMCs. We measure all relevant SFE statistics only during the fraction of the GMC's lifetime during which it could possibly be counted as an association between emission from young stars and molecular gas emission. We do this by including only simulation snapshots satisfying two criteria:

(i) Both molecular gas and stars younger than 3.9 Myr are present. This effectively determines the beginning of the observable time interval.

(ii) The mean molecular gas surface density $\Sigma_{\text{gas}} = M_{\text{mol}}/\pi R_{\text{eff}}^2$ is $> 10 M_{\odot} \text{pc}^{-2}$, corresponding to the -2σ quantile of measured

mean surface density of the star-forming GMCs in Lee et al. (2016). This approximates the latter boundary of the observable cloud lifetime, since $\Sigma_{\text{gas}} \rightarrow 0$ as the cloud is disrupted.

4.2.2 Evolution of observables

In the first panel of Fig. 3, we plot the evolution of the true and observable masses and SFEs in the simulation with $M = 2 \times 10^5 M_{\odot}$, $R = 30 \text{ pc}$, and random seed 1. M_{mol} is initially close to the actual total gas mass present, missing only the gas mass in the low surface density tail of the lognormal turbulent column density PDF (e.g. Thompson & Krumholz 2016), which is not self-shielding. We therefore expect that M_{mol} measured in observations is a reasonably faithful estimate of the total gas mass of molecular clouds that have not yet undergone significant star formation, in so far as the tracer-to- H_2 conversion factor is accurate.

As massive stars form, M_{mol} begins to decrease increasingly rapidly as stellar feedback starts to disrupt the cloud. Two physical effects cause this: gas launched in feedback-driven outflows tends to expand to the point that it is no longer self-shielding to the UV background, and gas near massive stars is ionized, forming H II regions. Once the cloud is fully disrupted and star formation has ceased, M_{mol} decays rapidly towards 0 with a roughly exponential behaviour with an e-folding time of only $\sim 0.5 \text{ Myr}$.

$M_{*, \text{tr}}$ always underestimates M_* , but it is a reasonably good estimate during the initial ramp-up of the SFR because the total stellar mass formed is dominated by the most recently formed stars. Towards the end of the star formation history, when the SFR starts to drop, $M_{*, \text{tr}}$ begins to underestimate M_* more significantly, eventually decaying to 0 after star formation has ceased. The observable masses in all other simulations follow these same general patterns as the run shown in Fig. 3. However, we do find that more massive clouds tend to have a longer span of time during which $M_{*, \text{tr}}$ underestimates M_* noticeably. This is due to their longer star-forming lifetimes compared to the tracer lifetime ($t_{\text{ff}} \propto M^{1/4}$ at constant Σ).

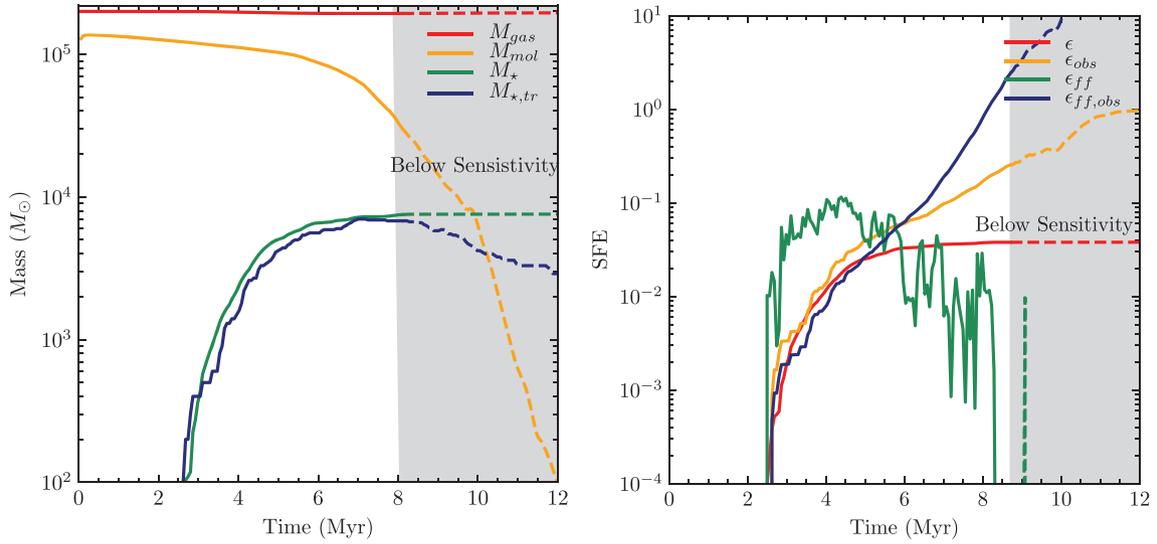


Figure 3. Comparison of the true and observable masses and SFEs in the simulation with $M = 2 \times 10^5 M_{\odot}$, $R = 30$ pc and random seed 1. Solid lines denote the portion of the lifetime during which the cloud would plausibly be identified in a star-forming GMC catalogue according to the criteria given in Section 4.2.1. *Left:* total gas mass, molecular gas mass, total stellar mass, and traced stellar mass (with $\tau_{tr} = 3.9$ Myr) as a function of time. Both the observed molecular gas and stellar mass underestimate the true gas and stellar masses present at all times. The observed molecular gas mass decreases rapidly once cloud disruption begins. The observed stellar mass also decays to 0 at late times, but not necessarily as rapidly as the observed gas mass, possibly leading to large observed SFE. *Right:* various measures of SFE (see Section 2 and Table 1).

In the second panel of Fig. 3, we plot the evolution of the true and observable SFEs that result from these evolving stellar and gas masses. ϵ increases monotonically towards ϵ_{int} , but ϵ_{obs} does not necessarily approach a constant because it is a ratio of two rapidly changing observed masses. During the cloud disruption phase, $M_{mol} \epsilon_{ff}$ rises with the initial increase in SFR, peaks, and decays to 0 as the cloud is disrupted, but again $\epsilon_{ff,obs}$ continues to increase without bound even more rapidly than ϵ_{obs} . This is due to a combination of effects: the ratio $M_{*,tr}/M_{mol}$ increases rapidly, and the observed t_{ff} also increases due to the expanding effective cloud volume. The observed $\epsilon_{ff,obs}$ can be doubly boosted by orders of magnitude beyond the true ϵ_{ff} , which never exceeds a few per cent.

4.2.3 Distributions of ϵ_{obs} and $\epsilon_{ff,obs}$

The manner in which ϵ_{obs} and $\epsilon_{ff,obs}$ vary throughout the cloud lifetime will imprint upon the distributions of values observed for an ensemble of clouds at random points in their lifetimes. In Fig. 4, we plot the quantiles of these distributions by cloud mass and compare them with the observations of Lee et al. (2016), Evans et al. (2014), and Vutisalchavakul et al. (2016). For each simulation we also overlay ϵ_{int} for each simulation for comparison with ϵ_{obs} and the true per-freefall SFE averaged over the star-forming lifetime, $\langle \epsilon_{ff} \rangle_t$, for comparison with $\epsilon_{ff,obs}$.

The ϵ_{obs} and $\epsilon_{ff,obs}$ distributions from the simulations are able to reproduce all essential features of the observed ones: they are all fairly broad, with significant scatter about a median value of the order of 1 percent. The spreads in ϵ_{obs} and $\epsilon_{ff,obs}$ dwarf the true variation in ϵ_{int} and the time-averaged $\langle \epsilon_{ff} \rangle_t$ from one cloud to another. Heavy lower tails result from the initial gradual growth of the SFR (Fig. 2). Excursions of ϵ_{obs} in excess of 10 per cent occur due to the rapid depletion of molecular gas, and even heavier upper

tails are found for $\epsilon_{ff,obs}$ because this effect is combined with an increase in the observed t_{ff} as the cloud expands.

4.2.4 Trends in observed SFE with GMC mass

The median ‘observed’ SFEs from the simulations are typically fairly close to the true SFEs. However, although there is no systematic trend in the true ϵ_{int} with cloud mass, the median ϵ_{obs} is anticorrelated with cloud mass, scaling approximately $\epsilon_{obs} \propto M^{-0.25}$ (see Fig. 4: the median decreases ~ 0.5 dex over ~ 2 dex in cloud mass). A similar trend is also found in observations (Murray 2011; Lee et al. 2016), with Lee et al. (2016) finding $\epsilon_{obs} \propto M^{-0.31}$, and has several possible explanations.

The use of free-free emission as a stellar mass tracer introduces a selection bias for star-forming regions that host massive stars. Assuming a universal and stochastically sampled IMF, the effect of this would be to bias measurements towards star-forming regions hosting a stellar mass greater than a certain threshold mass $M_{*,min}$, above which the IMF is well-sampled and massive stars are expected to be present. This translates into an effective threshold for ϵ_{obs} , $\epsilon_{min} = M_{*,min}/M \propto M^{-1}$, which accounts nicely for the trend found in Murray (2011), but is much steeper than the trend found in Lee et al. (2016). Murray (2011) also noted that uncertainties in M_{gas} will tend to scatter points along a locus $\epsilon_{obs} \propto M^{-1}$, which again is steeper than the trend that is observed in Lee et al. (2016).

In the simulations, we find that the trend is due to the fact that more massive clouds have longer lifetimes, so $M_{*,tr}$ will tend to underestimate M_* . If the cloud lifetime scales $\propto t_{ff}$, which we find, then we expect a scaling $\epsilon_{obs} \propto t_{ff}^{-1} \propto M^{-1/4}$, hence the ~ 0.5 dex decrease over 2 dex in cloud mass. This is much closer to the observed scaling, so we favour this explanation.

Ochsendorf et al. (2017) also identified an anticorrelation of $\epsilon_{ff,obs}$ with total mass in star-forming complexes in the Lee et al. (2016)

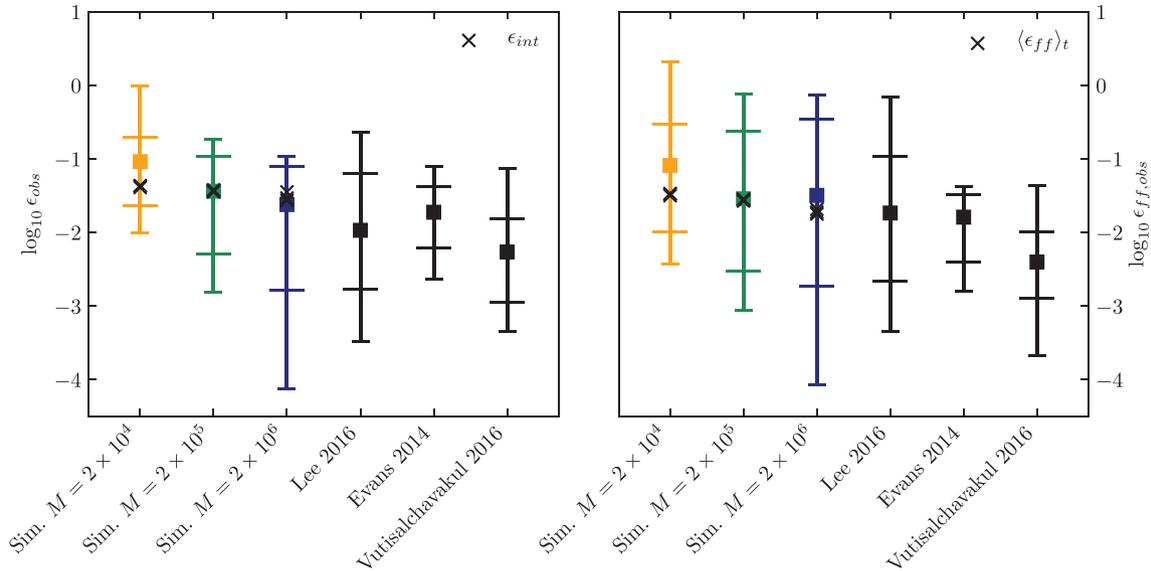


Figure 4. Quantiles of the distributions of ϵ_{obs} (left) and $\epsilon_{\text{ff, obs}}$ (right) arising from ‘observing’ simulated molecular clouds at random points in their observable star formation history, compared with observed cloud SFEs in the Milky Way. Points plot median values, inner whiskers plot $\pm\sigma$ quantiles, and outer whiskers plot $\pm 2\sigma$ quantiles. Both ϵ_{obs} and $\epsilon_{\text{ff, obs}}$ can both be measured to be considerably higher or lower than the true typical efficiencies (overlaid as black markers), depending on when they are measured. The spread in ϵ_{obs} is as great as 0.8 dex and the spread in $\epsilon_{\text{ff, obs}}/\langle\epsilon_{\text{ff}}\rangle$ is 0.8–1.1 dex. The median observed ϵ_{obs} is anticorrelated with cloud mass, as has been observed (Murray 2011; Lee et al. 2016). Details of how ϵ_{obs} and $\epsilon_{\text{ff, obs}}$ are modelled are described in Section 4.2.1.

Milky Way clouds as well as the LMC, of strength ranging from $\propto M^{-0.11}$ to $\propto M^{-0.49}$, respectively. Our simulations do not predict a correlation as strong as is observed in the LMC, and thus are not able to explain this trend. As Ochsendorf et al. (2017) argued, the greater importance of diffuse, CO-dark gas in the overall mass budget in the lower metallicity environment of the LMC might explain the difference in the strength of the trend between the Milky Way and the LMC. Since we have assumed that all molecular gas is being traced, this type of effect is not captured in our analysis.

4.2.5 Conclusions

We find that spread in SFE in a given sample of clouds can potentially be driven by two effects: (1) the slow initial growth of stellar populations and the late dispersal of clouds and (2) systematic trends with cloud mass within the sample. Both effects may explain why the data sets of Evans et al. (2014) and Vutisalchavakul et al. (2016) have less spread than Lee et al. (2016): the samples both span a much narrower range in M and Σ_{gas} (for a summary of cloud properties see Table 2). A narrower range, and in particular a greater lower bound on Σ_{gas} would capture less of the late cloud disruption stage. A narrower range in mass scale will capture less of the systematic scalings with mass scale that we have found.

The normalization of the observed SFEs – set by the physics of stellar feedback as shown in the simulations – is recovered within factors of ~ 2 –3. An order unity discrepancy can be easily accounted for by the systematic errors expected from models (e.g. uncertainties in massive star formation, stellar evolution, and stellar feedback; see discussion in G18) and from observations (e.g. errors in tracer conversion factors and the identification of gravitationally bound gas). Vutisalchavakul et al. (2016) point out that the SFR estimator they used underestimates the total star formation in the Milky Way by a factor of 2–3, which may explain why their SFEs are noticeably lower than the simulations and other observations.

In summary, we find that most of the observed spread in the SFE of molecular clouds can be explained by the variation that occurs during the evolution a single cloud, subject to the effects of feedback from massive stars. There is also a spread due to a systematic trend between the observable SFE and the bulk properties of the cloud, but this does *not* imply a trend in the true SFE. Indeed, most of the various SFE observations could be attributed to a population of clouds for which ϵ_{int} actually varies very little. This is in line with a picture where molecular clouds in the Milky Way form with only small spread in Σ_{gas} (e.g. due to the properties of supersonic turbulence: Larson 1981; Ballesteros-Paredes et al. 2011; Hopkins 2012), and as a result do not vary greatly in ϵ_{int} because it is a function of surface density due to the scalings of self-gravity and stellar feedback (e.g. Fall et al. 2010; Grudić et al. 2018; Kim et al. 2018).

4.3 Evolution of α_{vir}

The results of this section suggest an interpretation of the upper tails of the SFE distributions in terms of molecular cloud dispersal: molecular gas is destroyed or ejected at the end of the cloud lifetime due to stellar feedback, causing the M_{gas} term in the denominator of the SFE to become small and the inferred SFE to rise, although the actual SFR is dropping. If molecular clouds are initially gravitationally bound, with $\alpha_{\text{vir}} \leq 2$, as we have simulated, then a key prediction of this picture is an increase of α_{vir} from the initial bound state to greater values as the cloud evolves. We have verified that when the simulations reach the threshold of detectability, the clouds have $\alpha_{\text{vir}} \sim 10$ –20, similar to the maximum value observed. However, Lee et al. (2016) searched for a correlation between the size of the H II bubble associated with a cloud and its virial parameter, and none was found. Since we find ϵ_{ff} to be a monotonic and fairly sensitive function of the cloud evolutionary stage (Fig. 3), we may also test for correlations between $\epsilon_{\text{ff, obs}}$ and α_{vir} in our data compilation. The results of the Kendall τ -test for

Table 4. Parameters of the Kendall τ -test for correlation between α_{vir} and $\epsilon_{\text{ff, obs}}$ in our GMC data compilation. Both significant correlations ($p < 0.05$) are positive ($\tau > 0$), consistent with a monotonic increase of both α_{vir} and $\epsilon_{\text{ff, obs}}$ with cloud age.

$\epsilon_{\text{ff, obs}} - \alpha_{\text{vir}}$ data set	Kendall τ	p -value
Lee et al. (2016)	0.142	0.00359
Vutisalchavakul et al. (2016)	0.194	0.0313
Evans et al. (2014)	-0.0533	0.708

correlations between $\epsilon_{\text{ff, obs}}$ and α_{vir} are given in Table 4. We find a positive correlation between α_{vir} and ϵ_{ff} for both the Lee et al. (2016) and Vutisalchavakul et al. (2016) data sets at 2.9σ and 2.1σ significance, respectively.

Nevertheless, these correlations are rather weak, and the lack of correlation with H II region size is still puzzling – clearly the picture is more complicated than a universal evolution from $\alpha_{\text{vir}} = 2$ to > 10 . However, many factors might explain the scatter and weakness of the trend in α_{vir} with cloud evolution, either by introducing scatter or by increasing the expected mean measured value of α_{vir} . The empirically measured α_{vir} is (Bertoldi & McKee 1992):

$$\alpha_{\text{vir}} = \frac{5\sigma_v^2 R}{GM}, \quad (9)$$

where σ_v is the measured 1D velocity dispersion. This only equals the virial ratio $\frac{2E_{\text{turb}}}{|E_{\text{grav}}|}$ in the case of a uniform sphere with a flat internal size–linewidth relation. If GMCs are triaxial, intrinsic scatter is immediately introduced by using only 1D and 2D information for σ_v and R , respectively. Correcting the size–linewidth relation to that of supersonic turbulence raises the threshold for marginal boundness from 2 to $10/3 \sim 3.3$ (Miville-Deschênes et al. 2017). It is also possible that the typical virial parameter at which a GMC starts to form stars is even greater than this threshold: a cloud that is not globally bound may still have bound subregions that can collapse and form stars, so theory predicts the SFR to be a continuously decreasing function of α_{vir} , rather than a sharp cut-off (e.g. Padoan et al. 2012). Furthermore, the traditional concept of gravitational boundness of clouds in terms of α_{vir} neglects the fact that GMCs are in a state of supersonic turbulence, and hence are dissipating kinetic energy on a crossing time (Gammie & Ostriker 1996). This could potentially allow them to reach higher virial parameters than an equivalent dissipationless system without dispersing. If a significant fraction of star formation is in less-bound clouds, then the actual variation of α_{vir} throughout the observable cloud lifetime might actually be quite modest, weakening any observed correlation. Lastly, it is possible that a significant fraction of molecular emission from a cloud does not originate in the dynamically active region that is causally connected to the star formation event and directly affected by feedback. A molecular cloud consisting of a diffuse molecular envelope and a more tightly bound, star-forming core might not be observed to have a large variation in α_{vir} throughout its observable lifetime.

4.4 Effects of different feedback mechanisms

Stellar radiation, winds from OB stars, and supernova explosions all contribute to the disruption of clouds, but which of these feedback mechanisms is the most dominant? In answering this question, we focus upon the cloud model with mass $2 \times 10^6 M_{\odot}$ and radius 100 pc, because it provides the most dynamically interesting environment: the cloud lifetime of ~ 10 Myr is sufficiently long for Type II SNe from the first massive stars to occur during it, but

is not so long that the net fluxes of OB winds and stellar radiation from the stellar population are seriously reduced by the deaths of these massive stars. As such, all mechanisms could potentially be important.

We have re-simulated the $2 \times 10^6 M_{\odot}$, 100 pc cloud model with random seed 1, with several combinations of feedback physics, performing three runs that neglect stellar radiation, OB winds, and SNe, respectively, as well as runs where radiation and SNe are the only feedback, with results summarized in Table 3. Radiative feedback is clearly the most important: when it is neglected, both the true and observed SFE values increase by 0.3–0.5 dex. However, if the other feedback mechanisms are neglected, the change in SFE is quite small, < 0.1 dex. The relatively weak effect of stellar winds on cloud scales is in agreement with previous non-MHD simulations (Dale et al. 2014). Because the star-forming lifetime is > 3.5 Myr, we find that SNe alone are able to moderate star formation and disrupt the this cloud model, giving a $\epsilon_{\text{int}} \sim 10$ per cent compared to ~ 4 per cent with all feedback mechanisms. However, this would not be the case for the smaller cloud models, which evolve on a shorter freefall time-scale

It should be noted that although we find that radiative feedback alone to be sufficient to set the cloud SFE, the interplay of different feedback mechanisms in concert may have other effects not considered here. For example, although SNe may be subdominant in setting the cloud SFE, they can conceivably enhance the terminal momentum of the cloud once it is disrupted. Such an effect could easily be important in the greater galactic context, where feedback supports the galactic disc against collapse (Ostriker & Shetty 2011; Faucher-Giguère et al. 2013; Kim, Ostriker & Kim 2013; Hennebelle & Iffrig 2014; Gatto et al. 2015; Kim & Ostriker 2015; Walch et al. 2015; Iffrig & Hennebelle 2017; Kim & Ostriker 2018; Orr et al. 2018).

5 STAR FORMATION IN DENSE GAS

Because only a small fraction of the initial gas mass of a GMC is converted to stars (e.g. Fig. 2), one expects that the densest regions of molecular clouds are the most tightly correlated with star formation activity. Thus far we have examined the behaviour of SFE observables derived from integrated quantities for entire GMCs, and found that molecular cloud evolution under the influence of feedback from massive stars is a satisfactory explanation for the observed ranges of cloud SFEs. We now examine the properties of dense subregions of molecular clouds and determine whether our model can also explain observations on this smaller scale. We shall consider both observations pertaining to the total gas mass above a certain density threshold within a cloud, and the properties of individual dense clumps.

5.1 SFR versus gas mass above a 2D/3D density threshold

In nearby star-forming regions, a proportional relation was found between the SFR and the gas mass at above a certain K -band extinction threshold by Lada et al. (2010) (see also Heiderman et al. 2010):

$$\text{SFR} = 4.6 \times 10^{-8} \left(\frac{M_{0.8}}{M_{\odot}} \right) (M_{\odot} \text{ yr}^{-1}), \quad (10)$$

where $M_{0.8}$ is the gas mass of the cloud with K -band extinction greater than 0.8 mag, corresponding to a gas surface density of $116 M_{\odot} \text{ pc}^{-2}$. To compare the simulations with this relation, we

calculate the K -band extinction of a gas cell by calculating the column density via the ray-tracing method described in Section 4.2.1, but using the same K -band dust opacity assumed in Lada et al. (2010) (Lombardi 2009). In the left-hand panels of Fig. 5, we plot the average SFR over $\tau_{\text{SF}} = 2 \text{ Myr}$ (similar to the YSO count-inferred SFR in Lada et al. 2010) as a function of $M_{0.8}$. We find that the clouds simulated with stellar feedback do spend a significant fraction of their lifetime on or near the relation. On the other hand, the simulations without feedback almost always lie ~ 1 dex above the relation. We thus reproduce the finding of Geen et al. (2017) that some form of feedback is necessary to place star-forming clouds on the Lada et al. (2010) relation. While it is tempting to then claim that the relation is explained by feedback from massive stars, we caution that this type of mechanism cannot explain the SFR of the lowest mass star-forming regions considered in Lada et al. (2010), because the stellar masses present are so low that no massive stars are expected to be present. Rather, we have simulated only what would be considered high-mass star-forming systems. Explaining the Lada et al. (2010) relation for low-mass systems in terms of feedback may require another mechanism that can moderate star formation in the absence of massive stars.

Lada et al. (2010) further conjectured that $M_{0.8}$ might correspond to the gas mass denser than $n_{\text{H}_2} = 10^4 \text{ cm}^{-3}$, denoted M_{dense} . If so, the Lada et al. (2010) relation would suggest a simple universal star formation relation:

$$\text{SFR} = \epsilon_{\text{ff}} M_{\text{dense}} / t_{\text{ff}}, \quad (11)$$

where $t_{\text{ff}} = 0.3 \text{ Myr}$ is the freefall time at that density and $\epsilon_{\text{ff}} \sim 1$ per cent. This would roughly agree with the star formation relation suggested by the $L_{\text{IR}} - L_{\text{HCN}}$ correlation (Wu et al. 2005, 2010; Bigiel et al. 2016) under the assumption that HCN emission does actually trace the gas mass of characteristic density $\sim 10^4 \text{ cm}^{-3}$ (Krumholz & Tan 2007; Onus, Krumholz & Federrath 2018, however note recent evidence to the contrary: Goldsmith & Kauffmann 2017; Kauffmann et al. 2017). We plot the relation between M_{dense} and the SFR in the rightmost panels of Fig. 5, and find that the simulations lie well above a $\epsilon_{\text{ff}} \sim 1$ per cent relation, and the relation is steeper than linear. As in Clark & Glover (2014) and Geen et al. (2017), we find a correlation but no general proportionality between M_{dense} and $M_{0.8}$ in the simulations, so equation (11) does not follow from equation (10). Both with and without feedback, the simulations lie mostly in the range $\epsilon_{\text{ff}} = 10\text{--}100$ per cent, so feedback from massive stars as implemented here does not appear to be sufficient to achieve ‘slow’ star formation in dense gas.

5.2 Individual dense clumps

To compare to observations of individual dense clumps in Wu et al. (2010) and Heyer et al. (2016), we identify contiguous regions with $n_{\text{H}_2} > 10^4 \text{ cm}^{-3}$ in the simulations, and associate these with sink particles younger than 0.5 Myr found within $2R_{\text{eff}}$ of the gas centre of mass, with R_{eff} computed as in Section 4.2.1. We find that the stellar masses associated with the dense clumps are relatively insensitive to the choice of cut-off radius beyond this value because young sink particles are tightly clustered around dense clumps. Within this population we find stellar-mass objects that would be more readily identified as ‘cores’ rather than ‘clumps’. To make a reasonable comparison with observed dense clumps, we apply a mass cut of $100 M_{\odot}$, which excludes these cores.

The mass–size relation of simulated clumps is compared to observations in Fig. 6. We find that in the mass–size plane the

clump catalogue from the simulations overlaps most of the dense clumps in Heyer et al. (2016) and roughly half of those in Wu et al. (2010). This supports the interpretation of dense clumps as dense subregions that formed dynamically within a larger molecular gas complex. However, although we have simulated cloud models similar to the most massive Milky Way GMCs, we do not find dense clumps with masses as great as the most massive in either catalogue. This might be due to a genuine missing physical mechanism that might slow down gas consumption in dense clumps, allowing them to live longer and accrete to greater masses. However, resolution effects might also account for the discrepancy: observations with finite spatial and/or spectral resolution would be more likely to lump together multiple small clumps into a larger single clump.

In Fig. 7, we plot the distributions for ϵ_{obs} and ϵ_{ff} of dense clumps in the simulations compared to observations. We compute ϵ_{obs} from the total dense gas and stellar mass. We compute $\epsilon_{\text{ff, obs}}$ via equation (6) using the fiducial star formation time-scale $\tau_{\text{tr}} = 0.5 \text{ Myr}$ used in Heyer et al. (2016). We find a similar amount of scatter to what is observed, which is presumably due to similar effects to what we have found on GMC scales. However, as in the previous subsection, we find efficiencies that are generally greater than what is observed: both ϵ_{obs} and $\epsilon_{\text{ff, obs}}$ for dense clumps are systematically ~ 0.3 dex greater than the observations, which themselves are really upper bounds (see discussion in 2.3). Moreover, the efficiencies and bulk properties of the observed dense clumps agree well despite the use of different methodologies, and the bulk properties of Heyer et al. (2016) in particular were derived independently of any assumptions about the characteristic density traced by HCN. It therefore seems quite possible that there is a genuine discrepancy in the efficiency of star formation in dense gas in the simulations: the physics that we have included may not be sufficient to slow down star formation in dense gas down to the levels observed.

5.3 Possible missing physics

Assuming that the discrepancy in the SFE of dense gas shown in this section is genuine, and not due to some unknown systematic, there are several pieces of physics neglected here that might affect the clump SFEs:

(i) Multiply-scattered IR radiation pressure in the optically thick limit (e.g. Krumholz & Thompson 2012; Davis et al. 2014; Skinner & Ostriker 2015; Tsz-Ho Tsang & Milosavljević 2018; Zhang & Davis 2017), which can conceivably become comparable or greater in magnitude to the radiation pressure from direct stellar emission at the gas surface density of these clumps, $> 10^3 M_{\odot} \text{ pc}^{-2}$. Note however that recent work has shown that the viability of this mechanism in Milky Way environments is dubious (Reissl et al. 2018).

(ii) Radiative heating from protostellar accretion, which has been found to be sufficient, and possibly necessary, to set the characteristic mass scale of stars (Bate 2009; Krumholz 2014; Guszejnov, Krumholz & Hopkins 2016; Federrath, Krumholz & Hopkins 2017). The simulations form sink particles of stellar mass, so this may well be dynamically relevant on the scales resolved.

(iii) Protostellar outflows, which have been shown to be able to slow down star formation in high-resolution periodic box simulations on scales similar to dense clumps (Myers et al. 2014; Federrath 2015; Cunningham et al. 2018), but have not been treated in the present context, in which dense clumps form and disperse dynamically within a larger molecular cloud.

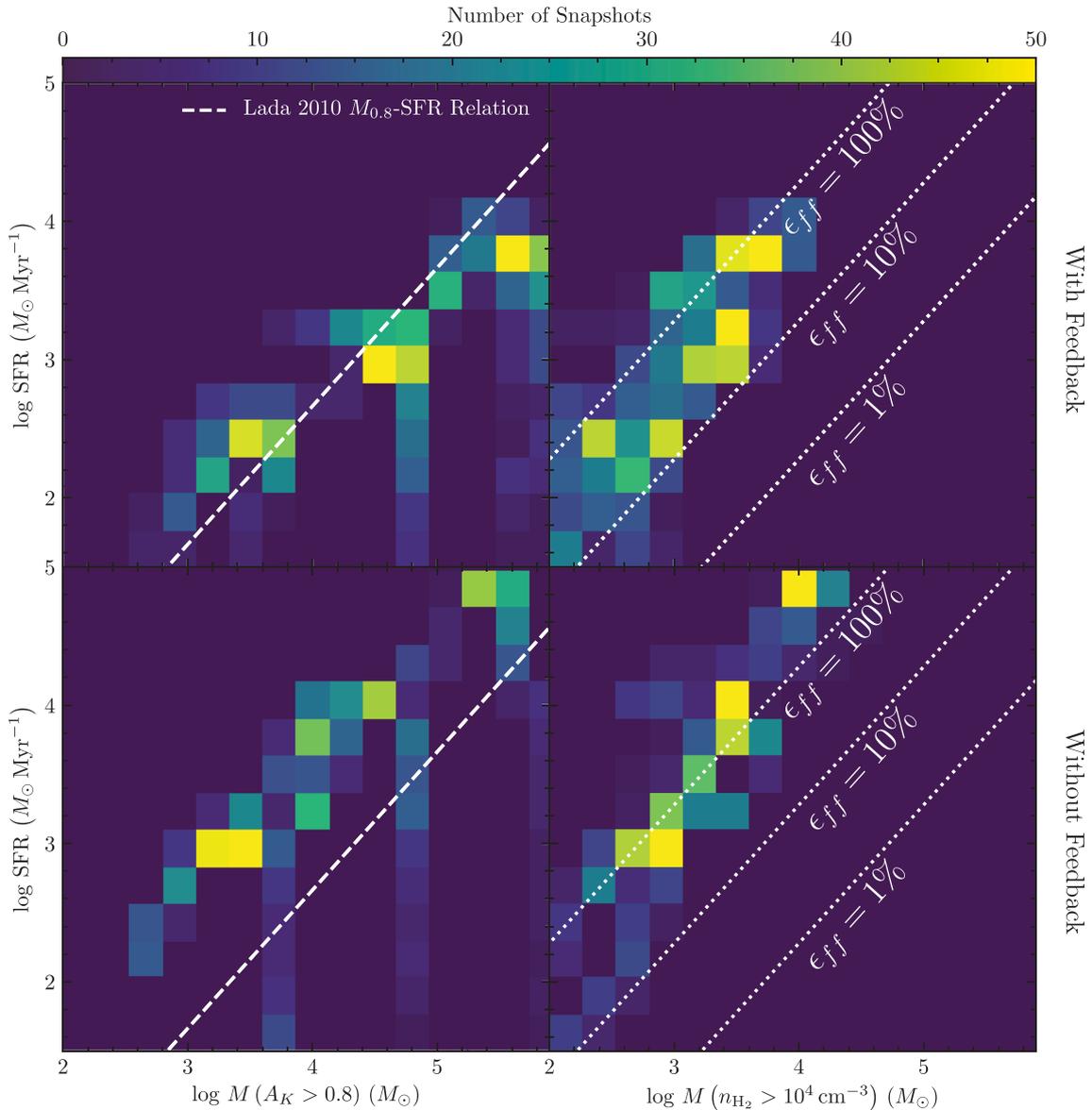


Figure 5. SFR as a function of ‘dense’ gas mass in the simulations, for both 2D and 3D density thresholds. We plot 2D histograms of the compilation of all simulation snapshots in $M_{\text{gas}}-\text{SFR}$ space to give a sense of the relative amount of time spent by the simulations at a given point. *Left:* SFR as a function of gas mass above 0.8 mag extinction, compared to the Lada et al. (2010) relation, for simulations with (top) and without (bottom) stellar feedback. *Right:* SFR as a function of gas mass with molecular gas density n_{H_2} greater than 10^4 cm^{-3} , for simulations with (top) and without (bottom) stellar feedback.

(iv) Hard-scattering N -body interactions, which would not necessarily bring down the actual SFE, but would reduce the observed SFE if able to dynamically eject YSOs from their natal clumps, as in the classic competitive accretion picture (Bonnell et al. 2001). Such interactions depend sensitively upon the relative masses of protostars in a clump, so this effect is only expected to have the correct behaviour in simulations that resolve the IMF self-consistently, which we have not attempted to do here – a numerically converged IMF likely requires some subset of the physics mentioned in the above points (see references). In a previous iteration of these simulations, we encountered a bug that caused spurious ejection of sink particles from clumps, and found that the resulting measured SFE was in good agreement with observations. Therefore, the efficient removal of stellar mass in a clump crossing time might reduce the SFE to observed levels.

Another possibility is that a mechanism is actually slowing down star formation in dense gas. Krumholz & Tan (2007) showed that the Krumholz & McKee (2005) turbulence-regulated star formation model predicts the correct normalization of the value of $\epsilon_{\text{ff, obs}}$ observed in dense gas, although it makes no specific prediction for the dispersion in $\epsilon_{\text{ff, obs}}$ because it relies upon a model with stationary turbulent properties, sustained by some driving mechanism. On the other hand, our simulations with feedback from massive stars predict a similar dispersion in $\epsilon_{\text{ff, obs}}$ to what is observed, but *cannot* explain the ~ 1 per cent magnitude. As the simulations followed the dense gas self-consistently down to the resolution limit, the properties of MHD turbulence in dense clumps inside a molecular clouds alone could not have slowed down star formation. This fact, combined with the severe deficit of dense gas for the amount of star formation (Fig. 5), suggests a missing piece of physics.

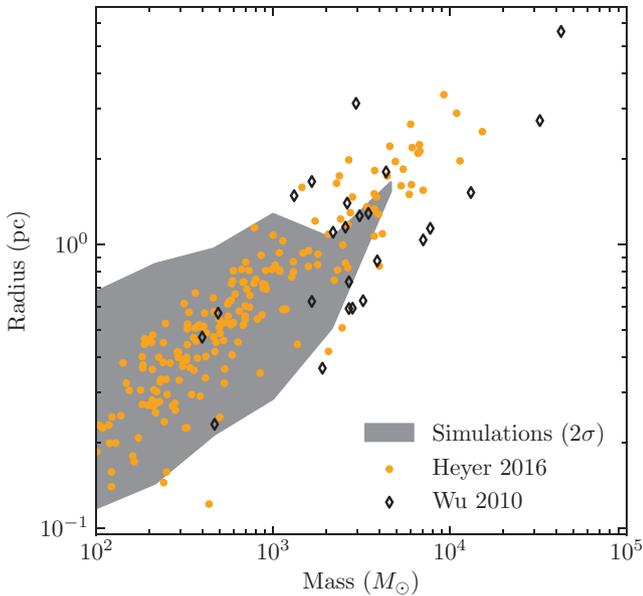


Figure 6. Mass versus effective radius for the dense clumps catalogued in the simulations, compared with the star-forming dense clumps in Wu et al. (2010) and Heyer et al. (2016). The grey contour encloses the $\pm 2\sigma$ contours of clump size at a given mass.

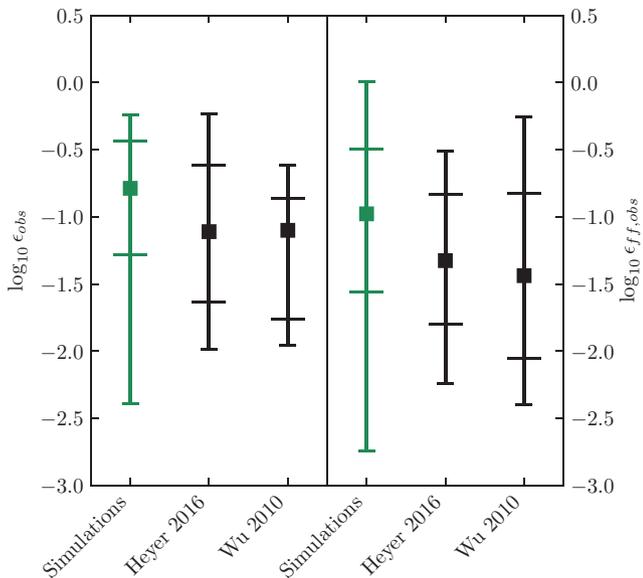


Figure 7. Comparison of the distributions (medians, $\pm\sigma$, and $\pm 2\sigma$ quantiles) of ϵ_{obs} and $\epsilon_{\text{ff,obs}}$ for dense ($n_{\text{H}_2} > 10^4 \text{ cm}^{-3}$) clumps in the simulations with the star-forming dense clump data sets from Wu et al. (2010) and Heyer et al. (2016). We plot $\epsilon_{\text{ff,obs}}$ as calculated from the same procedure as Heyer et al. (2016), which assumes a fixed tracer-identified SF time-scale $\tau_{\text{tr}} = 0.5 \text{ Myr}$.

6 DISCUSSION

6.1 Other drivers of scatter in observed SFE

We found in Section 4.2 that the effect of measuring the SFE of GMCs at different points in their lifetimes can produce enough scatter to account for observations. However, this does not necessarily imply that it is the *only* driver of scatter. Here, we discuss other possibilities.

6.1.1 Chaotic star formation and IMF sampling

Geen et al. (2018) points out another potentially important source of scatter: the unpredictable nature of star formation at the cloud level, especially in terms of the sampling of the IMF and its implications for stellar feedback. The output of ionizing photons from a star is such a steep function of its mass that it is often dominated by the most massive star in the cluster. As such, on mass scales where the IMF is not well sampled (when $< 10^4 M_{\odot}$ is formed), the outcome of star formation can be quite different if, for instance, two $50 M_{\odot}$ stars form versus a single $100 M_{\odot}$ star. Geen et al. (2018) found that the combined variance due to IMF sampling and the initial turbulent velocity field can cause the actual SFE of a $10^4 M_{\odot}$ GMC to vary from 6 to 23 per cent. We do not reproduce variations of this magnitude in our three realizations of a $2 \times 10^4 M_{\odot}$ cloud, but this is possibly because we adopt the approximate, single-species IMF sampling scheme (Su et al. 2018) rather than sampling from the full range of stellar masses as Geen et al. (2018) did.

Even when *assuming* some (possibly well sampled) IMF as a phenomenological input, it is not at all clear what the ‘correct’ way to model it in simulations is (i.e. the specific manner of dividing the total feedback budget among sink particles). Any method of doing so is making assumptions about the nature of massive star formation. In Grudić & Hopkins (2018), we surveyed various approaches that have been used in the literature, and found that the choice of prescription affected cloud SFE at the factor of ~ 3 level.

6.1.2 Ambiguity of cross-correlating GMCs and young stars

To measure SFE, it is necessary to cross-correlate young star clusters with GMCs in some manner. This can be challenging to do in an unambiguous fashion, and is not without an inherent possibility of error. For instance, it is possible that a cluster has completely dispersed its parent cloud, but that there is a nearby cloud that actually had nothing to do with forming it, and that this cluster would be cross-correlated with that cloud. This could result in large errors in the observed SFE that could contribute to the scatter.

Similarly, as mentioned in Section 4.3, it is possible that only some dynamically relevant *subset* of an observed cloud is actually participating in star formation, in the sense that it is gravitationally bound and can be modelled as in the present simulation work. Gas tracers, such as CO emission, do not necessarily only trace only the ‘star-forming’ component of the cloud – they may well trace a large part of the surrounding gas that is not part of any bound, star-forming subsystem. If this relatively unassociated gas were rolled into the SFE measurement, it would reduce the SFE. Inversely, if there is a large amount of dynamically relevant gas present that does *not* contribute to the observed gas tracer (e.g. CO-dark gas), the opposite would occur. Both possibilities could contribute to the scatter.

6.2 Does SFE scale with cloud properties?

An objective of star formation theory is to use observations of star-forming clouds to gain insights about the underlying physical mechanisms that determine their evolution and lead to star formation. Constraints can be obtained by comparing observations to the various theories of turbulence-regulated and feedback-regulated star formation, which make specific predictions for ϵ_{int} and ϵ_{ff} in terms of the bulk properties of GMCs, such as M , R , and α_{vir} . For example, hydrodynamics simulations with stellar feedback generally predict ϵ_{int} to scale in some manner with escape velocity, density, or surface

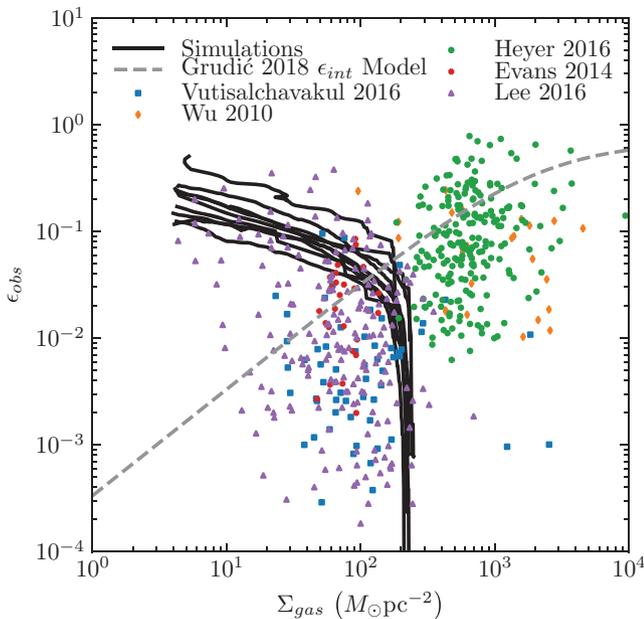


Figure 8. Tracks traced out by the simulations in the $\Sigma_{\text{gas}}-\epsilon_{\text{obs}}$ plane compared with data from star-forming Milky Way clouds and clumps (Section 2.3) and the G18 theory for the dependence of ϵ_{int} upon Σ_{gas} . For consistency, Σ_{gas} is computed using the effective R_{eff} (see Section 4.2.1), which is less than the nominal bounding radius R and thus gives a somewhat greater surface density than the nominal $M/\pi R^2$. Both the observed SFEs and surface densities evolve throughout the GMC lifetime, which scatters the data. The prediction of GMC evolution subject to stellar feedback is therefore not a functional dependence of ϵ_{int} on Σ_{gas} , but rather a complicated joint probability distribution function that will depend upon the statistics of the underlying cloud population. This complicates the task of discerning true systematic scalings from the observational data.

density. G18 pointed out that the median ϵ_{obs} appears to scale by a factor of ~ 10 over the surface density range separating Milky Way GMCs and dense clumps, which is also roughly a factor of 10 (Fig. 8). However, so far such SFE scalings have not yet been conclusively demonstrated in observational studies within a single population of homogeneously catalogued gas structures. Our simulations suggest that this may be due, at least in part, to the fact that the observable quantities predicted by theory vary in a complex manner that complicates the comparison of theoretical models with observations.

The observed M_{mol} , R_{eff} (and hence Σ_{gas}), and ϵ_{obs} of a star-forming GMCs will all vary by orders of magnitude throughout the cloud lifetime (see Fig. 8), so numerical simulations of star formation with stellar feedback from massive stars predict a large spread in ϵ_{obs} in ϵ_{ff} . Therefore, ϵ_{obs} cannot be treated as a one-to-one function of the bulk cloud properties. To properly investigate possible SFE scalings due to feedback-regulated star formation, it is necessary to model the posterior distribution of predicted *observable* GMC properties, which is very broad in both the space of GMC bulk properties and in observed SFE. Furthermore, because a GMC will begin its star-forming process below the threshold of detectable massive star formation, and end its evolution in catastrophic dispersal only to be found below the detectable threshold of molecular emission brightness, some understanding of the selection function is also important to model the likelihood. Failing this, any true underlying scalings in SFE with cloud properties can easily be obscured or fit incorrectly. Although the simulations equip us with

some idea of the likelihood function for a given cloud model, fitting to data from a population of clouds makes it necessary to forward-model the statistics of the cloud parameters within an entire galactic GMC population, which is beyond the scope of this work.

6.3 Turbulence regulation versus feedback regulation

The results of this work do permit certain definite conclusions about the physics governing molecular cloud evolution. We have shown that our simulated GMC models do predict the observed distribution of SFEs of Milky Way GMCs in some detail (Fig. 4), and are able to reproduce the observed anticorrelation of ϵ_{obs} with total cloud mass (Lee et al. 2016). Lee et al. (2016) showed that turbulence-regulated SFE theories derived from the lognormal density PDF and a gravitational collapse criterion (e.g. Krumholz & McKee 2005; Hennebelle & Chabrier 2011; Padoan & Nordlund 2011) predict neither of these features, generally predicting a positive correlation of SFE with cloud mass with much less scatter than is observed. We therefore favour the model of dynamic star formation in feedback-disrupted GMCs as an explanation for the observed properties of star-forming GMCs in the Milky Way. The observed scatter is due to the large variation in observable gas and stellar mass throughout the cloud lifetime, both due to a dynamic SFR during the initial collapse phase and the depletion of stellar and molecular gas tracers due to stellar evolution and cloud disruption. Furthermore, the normalization of the SFE is not due to regulation by turbulence, but rather stellar feedback from massive stars setting the stellar mass that can be formed before star formation ceases. This is not to minimize the importance of turbulence in the dynamics of star-forming clouds, which is self-evident. Rather, the specific predictions of analytic theories that assume the properties of statistically stationary, non-self-gravitating turbulence fail to capture the full dynamics of self-gravitating clouds subject to the effects of feedback.

7 SUMMARY

In this work, we have presented MHD simulations intended to directly model star-forming GMCs in the Milky Way, accounting for the stellar feedback mechanisms due to massive stars: stellar winds, supernova explosions, and radiation, including the effects of photon momentum in multiple bands, and heating mechanisms due to UV photons. From these simulations we have arrived at several conclusions about the nature of local star-forming molecular clouds:

(i) When the effects of magnetic fields and feedback from massive stars are included, the simulations predict an dynamically rising SFR in molecular clouds (Fig. 2), as predicted analytically (Murray & Chang 2015) and found in previous works that considered only gravity and isothermal (magneto-) hydrodynamics (Federrath & Klessen 2012; Padoan et al. 2012; Lee et al. 2015; Murray et al. 2017) or a different subset of relevant feedback mechanisms (Raskutti et al. 2016; Geen et al. 2017; Vázquez-Semadeni et al. 2017). After this initial growth phase, stellar feedback eventually causes the SFR to level off and drop to 0 as the molecular cloud is disrupted.

(ii) The simulations predict a normalization and spread in the observed SFEs that is reasonably consistent with those of observed Milky Way GMC SFEs. The diversity in the measured SFE of molecular clouds in the Milky Way is similar to the range of SFE values that is measured across the star-forming lifetime of a single molecular cloud subject to stellar feedback. This stands in contrast

to quasi-static models of molecular cloud evolution (Zuckerman & Evans 1974; Krumholz et al. 2006), where molecular cloud properties vary on time-scales longer than a cloud freefall time.

(iii) According to the above interpretation of the SFE spread, very large (> 10 per cent) or very small (< 0.1 per cent) observed SFEs in individual clouds do not imply that GMCs actually exhibit such great variation in the fraction of their mass that they convert to stars, because these correspond only indirectly to the true SFE values. The true SFE variation could actually be quite small, and the observed scatter would still be observed. Because these effects are a consequence of non-linear molecular cloud evolution subject to the interplay of feedback, gravity, and hydrodynamics, we concur with Lee et al. (2016) that theories invoking gravity and turbulence alone cannot explain the observed range of SFE.

(iv) The observed trend of decreasing ϵ_{obs} with cloud mass (Murray 2011; Lee et al. 2016) can be understood as an observational effect arising from the use of only recently formed stars as a tracer of stellar mass, which underestimates the total stellar mass formed in more massive clouds, which have longer lifetimes. The true SFE in the simulations has no strong trend with mass.

(v) We examined the relations between gas mass above 2D and 3D density thresholds in the simulations and the SFR. Simulations lie on the Lada et al. (2010) $M_{0.8}$ –SFR relation (equation 10) if and only if stellar feedback is included, however this does not explain the relation in low-mass star-forming regions where massive stars are absent. However, with or without feedback, the simulations lie well above the proposed corresponding 3D relation for dense ($> 10^4 \text{ cm}^{-3}$) gas (equation 11) that assumes that $M_{0.8} = M_{\text{dense}}$. This is in agreement with previous simulation work showing that $M_{0.8} \neq M_{\text{dense}}$ in general (Clark & Glover 2014; Geen et al. 2017).

(vi) We identify contiguous regions of dense ($> 10^4 \text{ cm}^{-3}$) gas within the simulated GMCs with observed dense clumps (Wu et al. 2010; Heyer et al. 2016), and find that their bulk properties are mostly in good agreement with observed clumps, except for a dearth of predicted clumps more massive than $3000 M_{\odot}$. We measure the clump SFE in a manner replicating observation techniques and find that ϵ_{obs} and $\epsilon_{\text{ff, obs}}$ are both systematically 0.3 dex greater than is observed. It is possible that feedback from main-sequence massive stars is insufficient to bring the SFE of dense gas down to the levels observed.

We can identify several avenues for further progress on this problem. Our simulations relied upon ad hoc initial conditions generated by stirring supersonic MHD turbulence and then ‘switching on’ gravity. This is fairly artificial, because in a real galaxy it is likely that gravity plays a role in the actual formation of the molecular cloud and the generation of its turbulent motions. Furthermore, the extent to which even gravitationally bound clouds can be treated as isolated objects is not well established, even if they only survive for roughly a freefall time as they do in the simulations. To address these questions, future studies should account for the greater galactic context of molecular cloud formation and dispersal.

For purposes of determining the stellar feedback budget, we made the single phenomenological assumption of a Kroupa (2002) IMF, which was sampled within sink particles according to the simple prescription of Su et al. (2018). While the universality of the IMF across most Milky Way environments is reasonably well established (Offner et al. 2014), in reality the IMF must somehow emerge from the dynamics of star-forming clouds. Therefore, the manner in which we have decoupled the formation of massive stars from the actual local cloud dynamics is not fully self-consistent. If special conditions are actually necessary for massive star formation, the

simulations would not capture the effect and might overestimate feedback. A fully self-consistent molecular cloud simulation with sufficient resolution and physics to *predict* the IMF would be necessary to validate our approach. This presents a challenging resolution requirement due to the factor of $\sim 10^6$ disparity in mass scale between the average molecular cloud and the average star. However, recent cloud-collapse simulations without stellar feedback have managed to scale to a relative mass resolution of $< 10^{-8}$ (Guszejnov et al. 2018), demonstrating that GMC simulations with such a dynamic range are becoming possible.

Lastly, we caution that many conclusions about molecular clouds can be sensitive to the definition of a cloud. For instance, there is no one well-defined way to decompose a CO emission map into clouds, because the ISM exhibits substructure on all scales from the galactic scale height to individual stars, with no obvious preferred intermediate scale. It is likely that GMCs do exist as well-defined dynamical entities in the sense that they may be identified with the largest self-gravitating gas structures within a galaxy (Rosolowsky et al. 2008; Hopkins 2012), but these do not necessarily correspond to observationally catalogued GMCs on a one-to-one basis. A more sensitive quantitative comparison of simulated SFEs with observations than we have presented here should account for this by applying the same observational cloud decomposition and cross-correlation algorithms to mock observations.

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