
RESEARCH ARTICLES

p-Adic Dynamical Systems of the Function $\frac{ax}{x^2+a}^*$

U. A. Rozikov^{1**}, I. A. Sattarov^{1***}, and S. Yam^{2****}

¹*Institute of Mathematics, 81, Mirzo Ulug'bek str., 100125, Tashkent, Uzbekistan*

²*California State University, Monterey Bay, 100 Campus Center, Seaside, California, 93955 USA*

Received July 30, 2018; in final form, January 7, 2019; accepted January 7, 2019

Abstract—We show that any $(1, 2)$ -rational function with a unique fixed point is topologically conjugate to a $(2, 2)$ -rational function or to the function $f(x) = \frac{ax}{x^2+a}$. The case $(2, 2)$ was studied in our previous paper, here we study the dynamical systems generated by the function f on the set of complex p -adic field \mathbb{C}_p . We show that the unique fixed point is indifferent and therefore the convergence of the trajectories is not the typical case for the dynamical systems. We construct the corresponding Siegel disk of these dynamical systems. We determine a sufficiently small set containing the set of limit points. It is given all possible invariant spheres. We show that the p -adic dynamical system reduced on each invariant sphere is not ergodic with respect to Haar measure on the set of p -adic numbers \mathbb{Q}_p . Moreover some periodic orbits of the system are investigated.

DOI: 10.1134/S2070046619010059

Key words: *rational dynamical systems, fixed point, invariant set, Siegel disk, complex p -adic field, ergodic.*

1. INTRODUCTION

We study p -adic dynamical systems generated by a rational function. For motivation of such investigations see [1–8] and references therein. The paper is organized as follows: First we give some necessary definitions and facts. Then in Section 2 show that any $(1, 2)$ -rational function with a unique fixed point is topologically conjugate to a $(2, 2)$ -rational function or to the function $f(x) = \frac{ax}{x^2+a}$. In [7] the case of $(2, 2)$ -rational function with a unique fixed point is studied. In this paper for f we show that the unique fixed point is indifferent. We give a Siegel disk of the dynamical system. We give a localization of the set of limit points. Section 3 contains a description of all invariant spheres with respect to f . We study ergodicity properties of the dynamical system reduced on each invariant sphere with respect to Haar measure and show that the p -adic dynamical system reduced on each invariant sphere is not ergodic. In Section 4 we find 2-periodic orbit $\{t_1, t_2\}$ and show that it can only be either an attracting or an indifferent. We shall prove that if the cycle is attracting then it attracts each trajectory which starts from an element of an open ball of radius $h = |t_1 - t_2|_p$ centered at t_1 or at t_2 . If the 2-periodic cycle is an indifferent one then every iteration maps either of the two aforementioned balls to another one. All other spheres of radius $> h$ and center t_1 and t_2 are invariant independently of the attractiveness of the cycle.

*The text was submitted by the authors in English.

**E-mail: rozikovu@yandex.ru

***E-mail: sattarovi-a@yandex.ru

****E-mail: syam@csumb.edu

1.1. p -Adic Numbers

Let \mathbb{Q} be the field of rational numbers. The greatest common divisor of the positive integers n and m is denoted by (n, m) . Every rational number $x \neq 0$ can be represented in the form $x = p^r \frac{n}{m}$, where $r, n \in \mathbb{Z}$, m is a positive integer, $(p, n) = 1$, $(p, m) = 1$ and p is a fixed prime number.

The p -adic norm of x is given by

$$|x|_p = \begin{cases} p^{-r}, & \text{for } x \neq 0, \\ 0, & \text{for } x = 0. \end{cases}$$

It has the following properties:

- 1) $|x|_p \geq 0$ and $|x|_p = 0$ if and only if $x = 0$,
- 2) $|xy|_p = |x|_p |y|_p$,
- 3) the strong triangle inequality

$$|x + y|_p \leq \max\{|x|_p, |y|_p\},$$

3.1) if $|x|_p \neq |y|_p$ then $|x + y|_p = \max\{|x|_p, |y|_p\}$,

3.2) if $|x|_p = |y|_p$ then for $p = 2$ we have $|x + y|_p \leq \frac{1}{2}|x|_p$ (see [10]).

This norm is a non-Archimedean one.

The completion of \mathbb{Q} with respect to p -adic norm defines the p -adic field which is denoted by \mathbb{Q}_p (see [3]).

The algebraic completion of \mathbb{Q}_p is denoted by \mathbb{C}_p and it is called *complex p -adic numbers*. Note that (see [3, 5, 9]) \mathbb{C}_p is algebraically closed, an infinite dimensional vector space over \mathbb{Q}_p , and separable. The value group of \mathbb{C}_p is $\{p^r : r \in \mathbb{Q}\}$. Any element of \mathbb{C}_p can be expressed as the product of a fractional power of p , a root of unity and an element of the unit disk around 1 in \mathbb{C}_p .

For any $a \in \mathbb{C}_p$ and $r > 0$ denote

$$U_r(a) = \{x \in \mathbb{C}_p : |x - a|_p < r\}, \quad V_r(a) = \{x \in \mathbb{C}_p : |x - a|_p \leq r\},$$

$$S_r(a) = \{x \in \mathbb{C}_p : |x - a|_p = r\}.$$

A function $f : U_r(a) \rightarrow \mathbb{C}_p$ is said to be *analytic* if it can be represented by

$$f(x) = \sum_{n=0}^{\infty} f_n(x - a)^n, \quad f_n \in \mathbb{C}_p,$$

which converges uniformly on the ball $U_r(a)$.

1.2. Dynamical Systems in \mathbb{C}_p

Recall some known facts concerning dynamical systems (f, U) in \mathbb{C}_p , where $f : x \in U \rightarrow f(x) \in U$ is an analytic function and $U = U_r(a)$ or \mathbb{C}_p (see for example [4, 11]).

Now let $f : U \rightarrow U$ be an analytic function. Denote $f^n(x) = \underbrace{f \circ \dots \circ f}_n(x)$.

If $f(x_0) = x_0$ then x_0 is called a *fixed point*. The set of all fixed points of f is denoted by $\text{Fix}(f)$. A fixed point x_0 is called an *attractor* if there exists a neighborhood $U(x_0)$ of x_0 such that for all points $x \in U(x_0)$ it holds $\lim_{n \rightarrow \infty} f^n(x) = x_0$. If x_0 is an attractor then its *basin of attraction* is

$$A(x_0) = \{x \in \mathbb{C}_p : f^n(x) \rightarrow x_0, n \rightarrow \infty\}.$$

A fixed point x_0 is called *repeller* if there exists a neighborhood $U(x_0)$ of x_0 such that $|f(x) - x_0|_p > |x - x_0|_p$ for $x \in U(x_0)$, $x \neq x_0$.

Let x_0 be a fixed point of a function $f(x)$. Put $\lambda = f'(x_0)$. The point x_0 is attractive if $0 < |\lambda|_p < 1$, *indifferent* if $|\lambda|_p = 1$, and repelling if $|\lambda|_p > 1$.

The ball $U_r(x_0)$ (contained in V) is said to be a *Siegel disk* if each sphere $S_\rho(x_0)$, $\rho < r$ is an invariant sphere of $f(x)$, i.e. if $x \in S_\rho(x_0)$ then all iterated points $f^n(x) \in S_\rho(x_0)$ for all $n = 1, 2, \dots$. The union of all Siegel disks with the center at x_0 is said to be a *maximum Siegel disk* and is denoted by $SI(x_0)$.

Let $f : U \rightarrow U$ and $g : V \rightarrow V$ be two maps. f and g are said to be *topologically conjugate* if there exists a homeomorphism $h : U \rightarrow V$ such that, $h \circ f = g \circ h$. The homeomorphism h is called a *topological conjugacy*. Mappings that are topologically conjugate are completely equivalent in terms of their dynamics. For example, if f is topologically conjugate to g via h , and x_0 is a fixed point for f , then $h(x_0)$ is fixed for g . Indeed, $h(x_0) = hf(x_0) = gh(x_0)$.

2. (1, 2)-RATIONAL p -ADIC DYNAMICAL SYSTEMS

In this paper we consider the dynamical system associated with the (1, 2)-rational function $f : \mathbb{C}_p \rightarrow \mathbb{C}_p$ defined by

$$f(x) = \frac{ax + b}{x^2 + cx + d}, \quad a \neq 0, \quad a, b, c, d \in \mathbb{C}_p. \quad (2.1)$$

where $x \neq x_{1,2} = \frac{-c \pm \sqrt{c^2 - 4d}}{2}$.

We can see that for (1, 2)-rational function (2.1) the equation $f(x) = x$ for fixed points is equivalent to the equation

$$x^3 + cx^2 + (d - a)x - b = 0. \quad (2.2)$$

Since \mathbb{C}_p is algebraic closed the equation (2.2) may have three solutions with one of the following:

- (i) One solution having multiplicity three;
- (ii) Two solutions, one of which has multiplicity two;
- (iii) Three distinct solutions.

In this paper we investigate the behavior of trajectories of an arbitrary (1, 2)-rational dynamical system in complex p -adic field \mathbb{C}_p when there is unique fixed point for f , i.e., we consider the case (i).

The following lemma gives a criterion on parameters of the function (2.1) guaranteeing the uniqueness of its fixed point.

Lemma 2.1. *The function (2.1) has unique fixed point if and only if*

$$\frac{-c}{3} = -\sqrt{\frac{d-a}{3}} = \sqrt[3]{b} \quad \text{or} \quad \frac{-c}{3} = \sqrt{\frac{d-a}{3}} = \sqrt[3]{b}. \quad (2.3)$$

Proof. Necessariness. Assume (2.1) has a unique fixed point, say x_0 . Then the LHS of equation (2.2) (which is equivalent to $f(x) = x$) can be written as

$$x^3 + cx^2 + (d - a)x - b = (x - x_0)^3.$$

Consequently,

$$\begin{cases} 3x_0 = -c \\ 3x_0^2 = d - a \\ x_0^3 = b \end{cases},$$

which gives

$$x_0 = \frac{-c}{3} = \pm \sqrt{\frac{d-a}{3}} = \sqrt[3]{b}.$$

Sufficiency. Assume the coefficients of (2.1) satisfy (2.3). Then it can be written as

$$f(x) = \frac{ax - \frac{c^3}{27}}{x^2 + cx + \frac{c^2}{3} + a}, \quad a \neq 0, \quad a, c \in \mathbb{C}_p. \quad (2.4)$$

In this case the equation $f(x) = x$ can be written as

$$\left(x + \frac{c}{3}\right)^3 = 0.$$

Thus $f(x)$ has unique fixed point $x_0 = -\frac{c}{3}$. □

It follows from this lemma that if the function (2.1) has unique fixed point then it has the form (2.4). Thus we study the dynamical system (f, \mathbb{C}_p) with f given by (2.4).

Let homeomorphism $h : \mathbb{C}_p \rightarrow \mathbb{C}_p$ is defined by $x = h(t) = t + x_0$. So $h^{-1}(x) = x - x_0$. Note that, the function f is topologically conjugate to function $h^{-1} \circ f \circ h$. We have

$$(h^{-1} \circ f \circ h)(t) = \frac{\frac{c}{3}t^2 + (a + \frac{c^2}{9})t}{t^2 + \frac{c}{3}t + a + \frac{c^2}{9}}. \quad (2.5)$$

In (2.5), the case $c \neq 0$ is studied in [7].

Thus in this paper we consider the case $c = 0$ in (2.5). Therefore, in this paper we study dynamical systems of the following function

$$f(x) = \frac{ax}{x^2 + a}, \quad a \neq 0, \quad a \in \mathbb{C}_p. \quad (2.6)$$

where $x \neq \hat{x}_1, \hat{x}_2 = \pm\sqrt{-a}$.

It is easy to see that function (2.6) has unique fixed point $x_0 = 0$. For (2.6) we have

$$f'(x_0) = f'(0) = 1,$$

i.e., the point x_0 is an indifferent point for (2.6).

It follows from (2.6) that

$$|f(x) - x_0|_p = |f(x)|_p = |x|_p \cdot \frac{|a|_p}{|x^2 + a|_p}. \quad (2.7)$$

Letting $A = |a|_p$, we have

$$|f(x)|_p = |x|_p \cdot \frac{A}{|x^2 + a|_p}.$$

Denote:

$$\mathcal{P} = \{x \in \mathbb{C}_p : \exists n \in \mathbb{N} \cup \{0\}, f^n(x) \in \{\hat{x}_1, \hat{x}_2\}\}. \quad (2.8)$$

Let the function $\varphi_A : [0, +\infty) \rightarrow [0, +\infty)$ be defined by:

$$\varphi_A(r) = \begin{cases} r, & \text{if } r < \sqrt{A} \\ A^*, & \text{if } r = \sqrt{A} \\ \frac{A}{r}, & \text{if } r > \sqrt{A} \end{cases},$$

where A^* is a positive number such that $A^* \geq \sqrt{A}$.

Lemma 2.2. *If $x \in S_r(x_0)$, then the following holds for the function (2.6):*

$$|f^n(x)|_p = \varphi_A^n(r).$$

We now see that the real dynamical system compiled from φ_A^n is directly related to the p -adic dynamical system $f^n(x)$, $n \geq 1$, $x \in \mathbb{C}_p \setminus \mathcal{P}$. The following lemma gives properties to this real dynamical system.

Lemma 2.3. *The function φ_A has the following properties*

1. $\text{Fix}(\varphi_A) = \{r : 0 \leq r < \sqrt{A}\} \cup \{\sqrt{A} : \text{if } A^* = \sqrt{A}\}$.
2. If $r > \sqrt{A}$ then $\varphi_A^n(r) = \frac{A}{r}$ for all $n \geq 1$.
3. If $r = \sqrt{A}$ and $A^* > \sqrt{A}$, then $\varphi_A^n(\sqrt{A}) = \frac{A}{A^*}$ for all $n \geq 2$.

Proof. 1) This is a simple observation of the equation $\varphi_A(r) = r$.

2) If $r > \sqrt{A}$, then by definition of function φ_A , we have

$$\varphi_A(r) = \frac{A}{r}. \quad (2.9)$$

Moreover, $r > \sqrt{A}$, $\frac{A}{r} < \sqrt{A}$. By part 1 of this lemma, $\frac{A}{r}$ is to be considered a fixed point for $\varphi_A(r)$. Furthermore, $\varphi_A^n = \frac{A}{r}$ for all $n \geq 1$.

3) The proof of part 3 follows from part 2 of this lemma. □

From this lemma it follows that

$$\lim_{n \rightarrow \infty} \varphi^n(r) = \begin{cases} r, & 0 \leq r < \sqrt{A} \\ \sqrt{A}, & r = \sqrt{A}, A^* = \sqrt{A} \\ \frac{A}{A^*}, & r = \sqrt{A}, A^* > \sqrt{A} \\ \frac{A}{r}, & r > \sqrt{A} \end{cases}, \quad (2.10)$$

for any $r \geq 0$.

Denote:

$$A^*(x) = |f(x)|_p, \text{ if } x \in S_{\sqrt{A}}(0).$$

Applying Lemma 2.2, and 2.3, and formula (2.10) we get the following properties of the p -adic dynamical system compiled by the function (2.6).

Theorem 2.4. *The p -adic dynamical system is generated by the function (2.6) has the following properties:*

1. 1.1) $SI(x_0) = U_{\sqrt{A}}(0)$.
- 1.2) $\mathcal{P} \subset S_{\sqrt{A}}(0)$.
2. If $r > \sqrt{A}$ and $x \in S_r(0)$, then

$$f^n(x) \in S_{\frac{A}{r}}(0) \text{ for all } n \geq 1.$$

3. Let $x \in S_{\sqrt{A}}(0) \setminus \mathcal{P}$.

3.1) If $A^*(x) = \sqrt{A}$, then

$$f(x) \in S_{\sqrt{A}}(0).$$

3.2) If $A^*(x) > \sqrt{A}$, then

$$f^n(x) \in S_{\frac{A}{A^*(x)}}(0), \quad \forall n \geq 2.$$

Proof. 1.1 By lemma 2.2 and part 1 of Lemma 2.3, sphere $S_r(0)$ is invariant for f if and only if $r < \sqrt{A}$. Consequently, $SI(x_0) = U_{\sqrt{A}}(0)$.

1.2 Note that $|\hat{x}_1| = |\hat{x}_2| = \sqrt{A}$, i.e., $\{\hat{x}_1, \hat{x}_2\} \subset S_{\sqrt{A}}(0)$. By part 1.1, and 2 of this theorem if $x \in S_r(0)$, $r \neq \sqrt{A}$, then $f(x) \notin S_{\sqrt{A}}(0)$. By definition of set \mathcal{P} , we can conclude that $\mathcal{P} \subset S_{\sqrt{A}}(0)$.

2. The proof of part 2 easily follows from Lemma 2.2 and part 2 of Lemma 2.3.

3.1 If $x \in S_{\sqrt{A}}(0) \setminus \mathcal{P}$ and $A^* = \sqrt{A}$, we have $|f(x)|_p = \sqrt{A}$, i.e., $f(x) \in S_{\sqrt{A}}(0)$.

3.2 If $A^* > \sqrt{A}$, then by part 2 of this theorem we have $f^n(x) \in S_{\frac{A}{A^*(x)}}(0)$, for all $n \geq 2$.

□

3. ERGODICITY PROPERTIES OF THE DYNAMICAL SYSTEM $f(x) = \frac{ax}{x^2+a}$ IN \mathbb{Q}_p

In this section we assume that $\sqrt{-a}$ exists in \mathbb{Q}_p . Consider the dynamical system (2.6) in \mathbb{Q}_p .

Define the following set:

$$\Delta = \{r : 0 < r < \sqrt{A}\}.$$

From previous section we have

Corollary 3.1. *The sphere $S_r(0)$ is invariant for f if and only if $r \in \Delta$.*

In this section we study ergodicity of dynamical system on each invariant sphere.

Lemma 3.2. *For every closed ball $V_\rho(c) \subset S_r(0)$, $r \in \Delta$, the following is sufficient to say*

$$f(V_\rho(c)) = V_\rho(f(c)). \quad (3.1)$$

Proof. By inclusion of $V_\rho(c) \subset S_r(0)$, we have $|c|_p = r$.

Let $x \in V_\rho(c)$, i.e. $|x - c|_p \leq \rho$, then

$$|f(x) - f(c)|_p = |x - c|_p \cdot \frac{|a|_p \cdot |a - xc|_p}{(x^2 + a)(c^2 + a)}. \quad (3.2)$$

$|x \cdot c|_p = r^2$, since $x \in V_\rho(c) \subset S_r(0)$. Moreover, $|a|_p = A$. If $r \in \Delta$ i.e. $r < \sqrt{A}$, then $|x^2|_p = |x \cdot c|_p = r^2 < A = |a|_p$. By the equality of (3.2), $|f(x) - f(c)|_p = |x - c|_p \leq \rho$. □

Lemma 3.3. *If $c \in S_r(0)$, $r \in \Delta$, then $|f(c) - c|_p = \frac{r^3}{A}$.*

Proof. This follows from the following equality,

$$|f(c) - c|_p = \left| \frac{-c^3}{c^2 + a} \right|_p = \frac{|c^3|_p}{|c^2 + a|_p} = \frac{r^3}{A}, \text{ because } r^2 < A. \quad (3.3)$$

□

By Lemma 3.3, we have that $|f(c) - c|_p$ relies on r , but does not rely on $c \in S_r(0)$, therefore we define $\rho(r) = |f(c) - c|_p$, if $c \in S_r(0)$.

The following theorems and respective proofs can be reviewed upon in the references as they are similar to the results of paper [7].

Theorem 3.4. *If $c \in S_r(0)$, $r \in \Delta$ then,*

1. *For any $n \geq 1$ the following equality holds $|f^{n+1}(c) - f^n(c)|_p = \rho(r)$.*
2. *$f(V_{\rho(r)}(c)) = V_{\rho(r)}(c)$.*
3. *If for some $\theta > 0$, the ball $V_\theta(c) \subset S_r(0)$ is an invariant for f , then $\theta \geq \rho(r)$.*

For each $r \in \Delta$, let us consider a measurable space $(S_r(0), \mathcal{B})$, in this case, \mathcal{B} is the algebra generated by the closed subsets of $S_r(0)$. Each element of \mathcal{B} is a union of some balls $V_\rho(c)$.

A measure $\bar{\mu} : \mathcal{B} \rightarrow \mathbb{R}$ is considered to be Haar Measure if it is defined by $\bar{\mu}(V_\rho(c)) = \rho$.

Notice that $S_r(a) = V_r(a)/V_{\frac{r}{p}}(a)$, where p is a prime.

Consider the normalized (probability) Haar measure:

$$\mu(V_\rho(c)) = \frac{\bar{\mu}(V_\rho(c))}{\bar{\mu}(S_r(0))} = \frac{p\rho}{r(p-1)}.$$

By Lemma 3.2, we can conclude that f preserves the measure μ , i.e.,

$$\mu(f(V_\rho(c))) = \mu(V_\rho(f(c))) = \frac{p\rho}{r(p-1)} = \mu(V_\rho(c)).$$

The dynamical system, (X, T, μ) , where $T : X \rightarrow X$, is a measure preserving transformation (i.e. $\mu(T^{-1}(A)) = \mu(A)$, for all A) and μ is a probability measure. The dynamical system is *ergodic*, if for every invariant set V we have $\mu(V) = 0$ or $\mu(V) = 1$.

Theorem 3.5. *The p -adic dynamical system $(S_r(0), f, \mu)$ is not ergodic for all prime p and all $r \in \Delta$.*

Proof. Consider $(S_r(0), f, \mu)$ a dynamical system where μ is normalized Haar measure. Note that $V_{\rho(r)}(c) \subset S_r(0)$ is a minimal invariant ball. By Lemma 3.3, we have the following:

$$\mu(V_{\rho(r)}(c)) = \frac{p\rho(r)}{r(p-1)} = \frac{p \cdot \frac{r^3}{A}}{r(p-1)} = \frac{pr^2}{A(p-1)}.$$

If $r \in \Delta$, then $r < \sqrt{A}$, i.e., $pr \leq \sqrt{A}$. By this inequality, we have

$$\mu(V_{\rho(r)}(c)) \leq \frac{1}{p(p-1)} < 1,$$

for all prime p . □

Remark 3.6. *The result of this section, by example $\frac{ax}{x^2+a}$, illustrates the general result on ergodic functions on a sphere (see, for example, [2]). The case of a sphere with a radius greater than 1 reduced to the case considered in this paper.*

4. 2-PERIODIC POINTS

In this section, we will be interested in finding periodic points of function (2.6).

Proposition 4.1. *If function (2.6) has k -periodic points $\{y_0 \rightarrow y_1 \rightarrow \dots \rightarrow y_k \rightarrow y_0\}$, then*

$$|y_0|_p = |y_1|_p = \dots = |y_k|_p \leq \sqrt{A}.$$

Proof. Let function (2.6) has k -periodic points $\{y_0 \rightarrow y_1 \rightarrow \dots \rightarrow y_k \rightarrow y_0\}$.

Assume that $|y_i|_p > \sqrt{A}$ for some $i \in \{0, 1, \dots, k\}$. Then by part 2 of Theorem 2.4 we have $y_{i+1} = f(y_i) \in U_{\sqrt{A}}(0)$, i.e., $|y_{i+1}|_p = r < \sqrt{A}$ and $S_r(0)$ is invariant sphere of function (2.6). From this

$$|y_{i+1}|_p = |y_{i+2}|_p = \dots = |y_k|_p = |y_0|_p = \dots = |y_i|_p < \sqrt{A}.$$

This contradicts to our assumption. Consequently $|y_i|_p \leq \sqrt{A}$ for any $i \in \{0, 1, \dots, k\}$.

If $|y_i|_p = r < \sqrt{A}$, then $|y_0|_p = |y_1|_p = \dots = |y_k|_p = r < \sqrt{A}$, because $S_r(0)$ is invariant for all $r < \sqrt{A}$.

If $|y_i|_p = r = \sqrt{A}$, then by the above-mentioned results $|y_{i+1}|_p \not\geq \sqrt{A}$ and $|y_{i+1}|_p \not\leq \sqrt{A}$. Consequently, $|y_0|_p = |y_1|_p = \dots = |y_k|_p = \sqrt{A}$. \square

Let us consider 2-periodic points, i.e. consider the equation

$$g(x) \equiv f(f(x)) = \frac{ax^3 + a^2x}{x^4 + 3ax^2 + a^2} = x. \quad (4.1)$$

Since $x = 0$ is the unique fixed point, it satisfies (4.1). Assuming that $x \neq 0$, the equation (4.1) is equivalent to $x^2 + 2a = 0$, hence two solutions, $t_{1,2} = \pm\sqrt{-2a}$. For these points we have

$$|t_1|_p = |t_2|_p = \begin{cases} \sqrt{A}, & \text{if } p \neq 2 \\ \sqrt{\frac{A}{2}}, & \text{if } p = 2. \end{cases}$$

It is a coincidence that $g'(t_1) = g'(t_2) = 9$, i.e. the value does not rely on the parameter a . Therefore we have

$$|g'(t_1)|_p = |g'(t_2)|_p = \begin{cases} 1, & \text{if } p \neq 3 \\ \frac{1}{9}, & \text{if } p = 3. \end{cases}$$

Note that the function g is defined in $\mathbb{C}_p \setminus \left\{ \hat{x}_{1,2} = \pm\sqrt{-a}, \hat{x}_{1,2,3,4} = \pm\sqrt{\frac{(-3 \pm \sqrt{5})a}{2}} \right\}$.

Let us define the following:

$$\mathcal{P}_2 = \{x \in \mathbb{C}_p : \exists n \in \mathbb{N}, \text{ such that } f^n(x) \in \{\hat{x}_{1,2}, \hat{x}_{1,2,3,4}\}\}.$$

4.1. Case $p = 2$

In this case we have $|t_1|_2 = |t_2|_2 = \sqrt{\frac{A}{2}} < \sqrt{A}$ and $|t_2 - t_1|_2 = \frac{\sqrt{A}}{2\sqrt{2}}$. By Lemma 3.3 and part 2 of Theorem 3.4 we have

$$\rho\left(\sqrt{\frac{A}{2}}\right) = |f(t_1) - t_1|_2 = \frac{\sqrt{A}}{2\sqrt{2}} \text{ and } f(V_{\frac{\sqrt{A}}{2\sqrt{2}}}(t_1)) = V_{\frac{\sqrt{A}}{2\sqrt{2}}}(t_1).$$

In this case each fixed point t_1, t_2 of g is an indifferent point and is the center of a Siegel disk.

Theorem 4.2. *If $p = 2$ then $f(S_r(t_1) \setminus \mathcal{P}_2) \subseteq S_r(t_2)$, $f(S_r(t_2) \setminus \mathcal{P}_2) \subseteq S_r(t_1)$, for any $0 < r \leq \frac{\sqrt{A}}{2\sqrt{2}}$.*

Proof. We shall use the following equalities:

$$f(t_1) = t_2, \quad f(t_2) = t_1.$$

Let $t_1 = \sqrt{-2a}$ and $x \in S_r(t_1) \setminus \mathcal{P}_2 \subset V_{\frac{\sqrt{A}}{2\sqrt{2}}}(t_1)$, i.e., $|x - t_1|_2 = r \leq \frac{\sqrt{A}}{2\sqrt{2}}$. We have

$$|f(x) - t_2|_2 = |f(x) - f(t_1)|_2 = r \cdot \left| \frac{-3a + \sqrt{-2a}(x - t_1)}{[x - t_1 + \sqrt{-a}(\sqrt{2} - 1)][x - t_1 + \sqrt{-a}(\sqrt{2} + 1)]} \right|_2. \quad (4.2)$$

In RHS of equality (4.2) we have $|-3a|_2 = A$, $|\sqrt{-2a}(x - t_1)|_2 = r\sqrt{\frac{A}{2}} < A$ and $|\sqrt{2} - 1|_2 = |\sqrt{2} + 1|_2 = 1$. So $|f(x) - t_2|_2 = |f(x) - f(t_1)|_2 = r$, i.e., $f(x) \in S_r(t_2)$.

If $x \in S_r(t_2) \setminus \mathcal{P}_2 \subset V_{\frac{\sqrt{A}}{2\sqrt{2}}}(t_1)$, then we have

$$|f(x) - t_1|_2 = |f(x) - f(t_2)|_2 = r \cdot \left| \frac{-3a - \sqrt{-2a}(x - t_2)}{[x - t_2 - \sqrt{-a}(\sqrt{2} - 1)][x - t_2 - \sqrt{-a}(\sqrt{2} + 1)]} \right|_2. \quad (4.3)$$

Consequently, $|f(x) - t_1|_2 = |f(x) - f(t_2)|_2 = r$, i.e., $f(x) \in S_r(t_1)$. \square

4.2. Case $p = 3$

In this case $|t_1|_3 = |t_2|_3 = |t_2 - t_1|_3 = \sqrt{A}$ and each fixed point t_1, t_2 of g is an attractive point of g .

Theorem 4.3. *If $p = 3$ and $r < \sqrt{A}$, then*

a) *For any $x \in S_r(t_1) \setminus \mathcal{P}_2$, $\lim_{n \rightarrow \infty} f^{2n}(x) = t_1$ and $\lim_{n \rightarrow \infty} f^{2n+1}(x) = t_2$.*

b) *For any $x \in S_r(t_2) \setminus \mathcal{P}_2$, $\lim_{n \rightarrow \infty} f^{2n}(x) = t_2$ and $\lim_{n \rightarrow \infty} f^{2n+1}(x) = t_1$.*

Proof. Let $S_r(t_1) \subset S_{\sqrt{A}}(0)$, $r < \sqrt{A}$ and $x \in S_r(t_1) \setminus \mathcal{P}_2$, i.e., $|x - t_1|_3 = r$. We have

$$|f(x) - t_2|_3 = |f(x) - f(t_1)|_3 = |x - t_1|_3 \cdot \frac{|-3a + \sqrt{-2a}(x - t_1)|_3}{|x - t_1 + \sqrt{-a}(\sqrt{2} - 1)|_3 |x - t_1 + \sqrt{-a}(\sqrt{2} + 1)|_3}.$$

By this equality

$$|f(x) - t_2|_3 = \phi(r) = \begin{cases} \frac{r^2}{\sqrt{A}}, & \text{if } \frac{\sqrt{A}}{3} < r < \sqrt{A}, \\ \leq \frac{\sqrt{A}}{9}, & \text{if } r = \frac{\sqrt{A}}{3}, \\ \frac{r}{3}, & \text{if } r < \frac{\sqrt{A}}{3}. \end{cases} \quad (4.4)$$

For $f^2(x)$ we have

$$|f^2(x) - t_1|_3 = |f^2(x) - f^2(t_1)|_3$$

$$\begin{aligned}
&= |f(x) - t_2|_3 \cdot \frac{|-3a + \sqrt{-2a}(f(x) - t_2)|_3}{|f(x) - t_2 + \sqrt{-a}(\sqrt{2} - 1)|_3 \cdot |f(x) - t_2 + \sqrt{-a}(\sqrt{2} + 1)|_3} \\
&= \phi(\phi(r)) = \begin{cases} \frac{(\phi(r))^2}{\sqrt{A}}, & \text{if } \frac{\sqrt{A}}{3} < \phi(r) < \sqrt{A}, \\ \leq \frac{\sqrt{A}}{9}, & \text{if } \phi(r) = \frac{\sqrt{A}}{3}, \\ \frac{\phi(r)}{3}, & \text{if } \phi(r) < \frac{\sqrt{A}}{3}. \end{cases}
\end{aligned}$$

Iterating this argument we obtain the following formulas for $x \in S_r(t_1) \setminus \mathcal{P}_2$:

$$|f^{2n}(x) - t_1|_3 = \phi^{2n}(r), \quad |f^{2n+1}(x) - t_2|_3 = \phi^{2n+1}(r). \quad (4.5)$$

Thus the dynamics of the radius r of the spheres is given by the function $\phi : [0, \sqrt{A}] \rightarrow [0, \sqrt{A}]$, which is defined in formula (4.4). The following properties of ϕ are obvious:

1. The set of fixed points of $\phi(r)$ is $\text{Fix}(\phi) = \{0\}$;
2. The fixed point $r = 0$ is attractive with basin of attraction $[0, \sqrt{A}]$, independently on the value $\phi(\frac{\sqrt{A}}{3}) \leq \frac{\sqrt{A}}{9}$.

Using (4.5) it is easy to see that the assertion (a) and (b) follows from property 2. \square

4.3. Case $p \geq 5$

In this case we have $|t_1|_p = |t_2|_p = |t_2 - t_1|_p = \sqrt{A}$ and each fixed point t_1, t_2 of g is an indifferent point and is the center of a Siegel disk.

Theorem 4.4. *If $p \geq 5$ then $f(S_r(t_1) \setminus \mathcal{P}_2) \subseteq S_r(t_2)$, $f(S_r(t_2) \setminus \mathcal{P}_2) \subseteq S_r(t_1)$, for any $0 < r < \sqrt{A}$.*

Proof. Let $x \in S_r(t_1) \setminus \mathcal{P}_2 \subset V_{\sqrt{A}}(t_1)$, i.e., $|x - t_1|_p = r < \sqrt{A}$. In RHS of equality (4.2) we have $|-3a|_p = A$, $|\sqrt{-2a}(x - t_1)|_p = r\sqrt{A} < A$ and $|\sqrt{2} - 1|_p = |\sqrt{2} + 1|_p = 1$. So $|f(x) - t_2|_p = |f(x) - f(t_1)|_p = r$, i.e., $f(x) \in S_r(t_2)$.

If $x \in S_r(t_2) \setminus \mathcal{P}_2 \subset V_{\frac{\sqrt{A}}{2\sqrt{2}}}(t_1)$, then we have $|f(x) - t_1|_p = |f(x) - f(t_2)|_p = r$, i.e., $f(x) \in S_r(t_1)$.

Consequently, $f(S_r(t_1) \setminus \mathcal{P}_2) \subseteq S_r(t_2)$ and $f(S_r(t_2) \setminus \mathcal{P}_2) \subseteq S_r(t_1)$, for any $0 < r < \sqrt{A}$. \square

ACKNOWLEDGEMENTS

The third author was supported by the National Science Foundation, grant number NSF HRD 1302873. Authors thank both referees for their helpful comments.

REFERENCES

1. S. Albeverio, U. A. Rozikov and I. A. Sattarov, “ p -Adic $(2, 1)$ -rational dynamical systems,” J. Math. Anal. Appl. **398** (2), 553–566 (2013).
2. V. Anashin and A. Khrennikov, *Applied Algebraic Dynamics*, de Gruyter Expositions in Math. **49** (Walter de Gruyter, Berlin-New York, 2009).
3. N. Koblitz, *p -Adic Numbers, p -Adic Analysis and Zeta-Function* (Springer, Berlin, 1977).
4. H.-O. Peitgen, H. Jungers and D. Saupe, *Chaos Fractals* (Springer, Heidelberg-New York, 1992).
5. A. C. M. van Rooij, *Non-Archimedean Functional Analysis*, Monographs and Textbooks in Pure and Applied Math. **51** (Marcel Dekker, Inc., New York, 1978).
6. U. A. Rozikov and I. A. Sattarov, “On a non-linear p -adic dynamical system,” p -Adic Numbers Ultrametric Anal. Appl. **6** (1), 53–64 (2014).
7. U. A. Rozikov and I. A. Sattarov, “ p -Adic dynamical systems of $(2, 2)$ -rational functions with unique fixed point,” Chaos Solit. Fract. **105**, 260–270 (2017).

8. I. A. Sattarov, “ p -Adic $(3, 2)$ -rational dynamical systems,” *p-Adic Numbers Ultrametric Anal. Appl.* **7** (1), 39–55 (2015).
9. W. H. Schikhof, *Ultrametric Calculus: An introduction to p -adic analysis*, Cambridge Studies in Advanced Math. **4** (Cambridge Univ. Press, Cambridge, 2006).
10. V. S. Vladimirov, I. V. Volovich and E. I. Zelenov, *p-Adic Analysis and Mathematical Physics* (World Scientific, River Edge, N. Y., 1994).
11. P. Walters, *An Introduction to Ergodic Theory* (Springer, Berlin-Heidelberg-New York, 1982).