Layer-dependent spin-orbit torques generated by the centrosymmetric transition metal dichalcogenide β-MoTe₂

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Single-crystal materials with sufficiently low crystal symmetry and strong spin-orbit interactions can be used to generate novel forms of spin-orbit torques on adjacent ferromagnets, such as the out-of-plane antidamping torque previously observed in WTe₂/ferromagnet heterostructures. Here, we present measurements of spin-orbit torques produced by the low-symmetry material β -MoTe₂, which, unlike WTe₂, retains bulk inversion symmetry. We measure spin-orbit torques on β -MoTe₂/Permalloy heterostructures using spin-torque ferromagnetic resonance as a function of crystallographic alignment and MoTe₂ thickness down to the monolayer limit. We observe an out-of-plane antidamping torque with a spin-torque conductivity as strong as 1/3 of that of WTe₂, demonstrating that the breaking of bulk inversion symmetry in the spin-generation material is not a necessary requirement for producing an out-of-plane antidamping torque. We also measure an unexpected dependence on the thickness of the β -MoTe₂—the out-of-plane antidamping torque is present in MoTe₂/Permalloy heterostructures when the β -MoTe₂ is a monolayer or trilayer thick, but goes to zero for devices with bilayer β -MoTe₂.

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I. INTRODUCTION

Spin-orbit torques represent one of the most promising methods for manipulating emerging magnetic memory technologies [1]. When a charge current is applied to a material with large spin-orbit coupling, such as a heavy metal [2–7], a topological insulator [8,9], or a transition metal dichalcogenide (TMD) [10–16], a spin current generated through mechanisms such as the spin Hall or Rashba-Edelstein effects can be used to exert a torque on an adjacent ferromagnet. Recent work from several research groups has focused on understanding how a controlled breaking of symmetry in a spin-generating material/ferromagnet heterostructure can be used to tune the direction of the observed spin-orbit torques [12-14,17-26]. An out-of-plane antidamping torque is particularly desired, because it is the component of torque required for the most efficient mode of switching for magnets with perpendicular magnetic anisotropy, but forbidden in high-symmetry materials. Previous experiments have shown that an out-of-plane antidamping torque can be generated using low-symmetry crystals of the TMD WTe2 as the spinsource material [12,13], or by using symmetry breaking associated with magnetic order [23,26]. However, many questions remain regarding what mechanisms and materials might be useful for generating the strongest possible out-of-plane antidamping spin-orbit torques.

In this work, we study the spin-orbit torques generated in TMD/ferromagnet heterostructures with a crystal symmetry that is distinct from WTe₂ in an important way—inversion

symmetry is intact in the bulk of the spin-generation material. We perform spin-torque measurements of TMD/ferromagnet heterostructures with the monoclinic phase (β) of MoTe₂ as the spin-source material. Using spin-torque ferromagnetic resonance (ST-FMR), we measure the spin-orbit torques as a function of crystal axis alignment and TMD thickness down to the monolayer limit. We find that an out-of-plane antidamping torque is present in β -MoTe₂/ferromagnet heterostructures even though inversion symmetry is intact in the MoTe₂ bulk. Interestingly, we find that while this out-of-plane antidamping torque is strong in both monolayer- and trilayer-thick MoTe₂ devices, the observed torque goes to zero in bilayer-thick MoTe₂.

II. SAMPLE FABRICATION AND CHARACTERIZATION

The monoclinic (β or 1T') phase of MoTe₂ provides a unique opportunity to probe the symmetries relevant for the generation of novel spin-orbit torques, in that the individual monolayers of β -MoTe₂ are isostructural to WTe₂ monolayers, but they are stacked such that inversion symmetry is maintained in the bulk crystal. Bulk β -MoTe₂ has the space group $P2_1/m$ (no. 11), with a screw axis along the Mo chain and a mirror plane perpendicular to the screw axis [Fig. 1(a)] [27]. Similar to WTe₂, however, the surface symmetry is limited to just one mirror plane perpendicular to the Mo chain shown in Fig. 1(b).

To fabricate our samples, we exfoliate flakes of bulk β -MoTe₂ crystal (provided by HQ graphene) onto high-resistivity silicon/silicon oxide wafers, where the last step of the exfoliation process is carried out under vacuum ($<10^{-6}$ torr) in the load lock of our sputtering system. We then use

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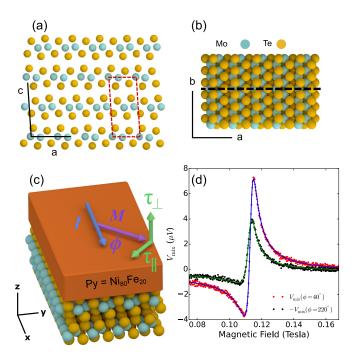


FIG. 1. (a) and (b) Structure of the MoTe₂ crystal in the monoclinic (β or 1T') phase (a) depicted in the a-c plane for which the mirror plane is within the page and the Mo chains run into the page, and (b) in the a-b plane where the a-c mirror plane is depicted by the dashed black line. (c) Geometry of the induced spin-orbit torques in our MoTe₂/Py heterostructures. The applied current is defined as being in the \hat{x} direction. (d) The measured mixing voltage, V_{mix} , as a function of applied magnetic field for Device 1, MoTe₂ (monolayer)/Py(6 nm), where the current is applied perpendicular to the mirror plane and the field applied at an angle of 40° (red) and 220° (black), showing a clear lack of twofold rotational symmetry in the generated spin-orbit torques. Fits using a sum of symmetric and antisymmetric Lorentzians, shown in blue and green respectively, show good agreement with the data. The applied microwave power is 5 dBm at 9 GHz.

grazing angle sputtering to deposit 6 nm of our ferromagnet, Permalloy (Py = $Ni_{80}Fe_{20}$), and subsequently cap the films with 2 nm of Al that is oxidized upon exposure to air. The equilibrium direction of the Py magnetic moment is within the sample plane. Flakes are identified for patterning by optical and atomic force microscopy (AFM); we select regions of flakes that are clean (no tape residue) and atomically flat (<300 pm roughness) with no monolayer steps over the entire region from which devices will be fabricated. The thicknesses of the β -MoTe₂ flakes can be accurately determined by AFM (with a layer step-height of ~ 0.7 nm). Samples are then patterned into device structures using electron beam lithography and ion mill etching. Electrical contact is made using 5 nm Ti/75 nm Pt electrodes. The data presented in the main text of this work are all taken at room temperature. We have confirmed that all our devices (down to the monolayer limit) are in the β -MoTe₂ phase at room temperature by polarized Raman spectroscopy (see Appendix G). We have also used polarized Raman spectroscopy to determine the crystallographic orientation of each device with respect to the applied current direction [28–34].

III. MEASUREMENTS

For the ST-FMR measurements [3,8,12], we use a ground-signal-ground type device structure, in which we apply a GHz frequency current to the MoTe₂/Py bar through the capacitive branch of a bias tee. We set the angle of the applied magnetic field with respect to the current direction, ϕ , and sweep the magnitude of that field to tune the ferromagnet through its resonance condition while measuring the resultant dc mixing voltage at the inductive end of the bias tee. The mixing voltage, V_{mix} , as a function of field magnitude can be fit accurately as the sum of symmetric and antisymmetric Lorentzians. The amplitudes of those Lorentzians are related to the in-plane (τ_{\parallel}) and out-of-plane (τ_{\perp}) torques on the ferromagnet, respectively, by [3,8,12]

$$V_{\rm S} = -\frac{I_{\rm RF}}{2} \frac{dR}{d\phi} \frac{1}{\alpha_{\rm G} \gamma (2B_0 + \mu_0 M_{\rm eff})} \tau_{\parallel},\tag{1}$$

$$V_{\rm A} = -\frac{I_{\rm RF}}{2} \frac{dR}{d\phi} \frac{\sqrt{1 + \mu_0 M_{\rm eff}/B_0}}{\alpha_{\rm G} \gamma (2B_0 + \mu_0 M_{\rm eff})} \tau_{\perp},\tag{2}$$

where R is the device resistance, $dR/d\phi$ is due to the anisotropic magnetoresistance in the Py, $\mu_0 M_{\rm eff}$ is the out-ofplane demagnetization field, B_0 is the resonance field, $I_{\rm RF}$ is the microwave current in the bilayer, $\alpha_{\rm G}$ is the Gilbert damping coefficient, and γ is the gyromagnetic ratio. Figure 1(d) shows $V_{\rm mix}$ at two applied field angles, 40° and 220°, for one of our devices (Device 1, containing one monolayer of MoTe₂) where the applied current in the device is perpendicular to the MoTe₂ mirror plane and the 220° trace has been multiplied by -1 for comparison. Fits to the data using a sum of symmetric and antisymmetric Lorentzians show good agreement.

In high-symmetry materials such as Pt, the generated spinorbit torques are limited by symmetry to consist of an out-ofplane fieldlike torque, $\vec{\tau}_A \propto \hat{m} \times \hat{y}$, and an in-plane antidamping torque, $\vec{\tau}_S \propto \hat{m} \times (\hat{m} \times \hat{y})$, which both have a dependence on the magnetization direction $\propto \cos(\phi)$ [35]. That the V_{mix} data in Fig. 1(d) are not identical up to a minus sign for the two applied field angles indicates that torques in the β -MoTe₂/Py system do not preserve twofold symmetry, i.e., an out-of-plane antidamping torque, $\vec{\tau}_B \propto \hat{m} \times (\hat{m} \times \hat{z})$, may be present. Note that we define the applied current as always being in the \hat{x} direction [Fig. 1(c)].

To determine the components of current-induced torque, we analyze the extracted fit parameters V_S and V_A as a function of applied field angle. Representative data for Device 1 are shown in Figs. 2(a) and 2(b). If only the torques τ_A and τ_S are present, V_A and V_S will be $\propto \sin(2\phi)\cos(\phi)$, where the $\propto \sin(2\phi)$ arises from $dR/d\phi$ due to the anisotropic magnetoresistance of the Py. However, the angular dependence of V_A [Fig. 2(b)] cannot be described with this simple overall angular dependence $\propto \sin(2\phi)\cos(\phi)$. To extract the other out-of-plane torques present in the system, we fit the angular dependence of V_A as

$$V_{\rm A} = \sin(2\phi)[A\cos(\phi) + B + C\sin(\phi)]. \tag{3}$$

The fit parameter B corresponds to torques $\vec{\tau}_B \propto \hat{m} \times (\hat{m} \times \hat{z})$. The fit parameter C corresponds to torques $\vec{\tau}_C \propto \hat{m} \times \hat{x}$ —the torque with a Dresselhaus-like symmetry observed in TaTe₂ and WTe₂ that likely arises from the in-plane resistance

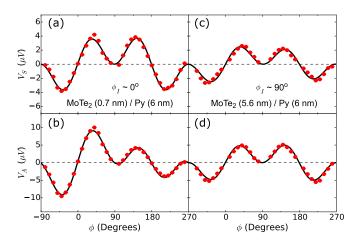


FIG. 2. (a) and (b) Dependence on the applied field angle for both the (a) symmetric, $V_{\rm S}$, and (b) antisymmetric, $V_{\rm A}$, component of the mixing voltage for Device 1, MoTe₂(monolayer)/Py(6 nm), with current applied perpendicular to the MoTe₂ mirror plane. Fits of the angular dependence are made using Eqs. (3) and (4). An out-of-plane antidamping torque is observed, with fit values $B/A = 0.302 \pm 0.001$. (c) and (d) Dependence on the applied field angle for (c) $V_{\rm S}$ and (d) $V_{\rm A}$ in Device 2, MoTe₂(5.6 nm)/Py(6 nm), with current applied along the MoTe₂ mirror plane. No out-of-plane antidamping torque is observed within experimental uncertainty, consistent with the symmetry requirements of the MoTe₂ surface. In both samples, the applied microwave power is 5 dBm at 9 GHz.

anisotropy of the low-symmetry TMD [16]. For Device 1, we find a ratio $B/A = 0.302 \pm 0.001$ indicating a sizable out-of-plane antidamping torque, whereas C is zero to within experimental uncertainty.

We may similarly fit V_S to test for additional in-plane torques:

$$V_{\rm S} = \sin(2\phi)[S\cos(\phi) + T + U\sin(\phi)],\tag{4}$$

where T corresponds to torques $\vec{\tau_T} \propto \hat{m} \times \hat{z}$, and U gives torques $\vec{\tau_U} \propto \hat{m} \times (\hat{m} \times \hat{x})$. In Device 1, T and U are zero within experimental uncertainty. However, other samples show nonzero values for T and U, as discussed below.

When a spin-generation system has a single mirror symmetry and the current is applied perpendicular to this mirror plane [as is the case for the MoTe₂/Py interface of Device 1 in Figs. 2(a) and 2(b)], a net torque generated by an out-of-plane spin is allowed by symmetry [a torque $\propto \hat{m} \times \hat{z}$ or $\propto \hat{m} \times (\hat{m} \times \hat{z})$]. However, if the current instead flows along a mirror plane, such a torque is forbidden by symmetry. Figures 2(c) and 2(d) show V_S and V_A for a MoTe₂/Py device in which current is applied along the MoTe₂ mirror plane (Device 2). Consistent with this symmetry requirement, fits of V_A using Eq. (3) yield values of B that are zero within experimental uncertainty. We note the presence of a small, but nonzero, value of T as determined by fits of V_S using Eq. (4), $T/S = 0.067 \pm 0.003$, which is discussed below and in Appendix F.

The torque conductivity, defined as the angular momentum absorbed by the magnet per second per unit interface area per unit applied electric field, provides an absolute measure of the torques produced in a spin source/ferromagnet heterostructure nominally independent of geometric factors. For

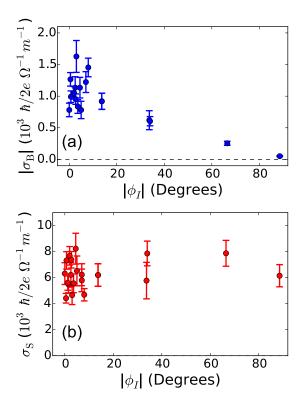


FIG. 3. (a) Torque conductivities for the out-of-plane antidamping torque, τ_B , as a function of the angle $|\phi_I|$ for 17 of our MoTe₂/Py devices, all with distinct MoTe₂ thicknesses. We have excluded our bilayer MoTe₂ devices in this plot, which are discussed in detail later. (b) Torque conductivities for the standard in-plane antidamping torque, τ_S , as a function of $|\phi_I|$ in all of our MoTe₂/Py devices. In both plots, the applied microwave power is 5 dBm. Torque conductivities are averaged over measurements at frequencies 8–11 GHz in steps of 1 GHz.

a torque τ_K (where K = A, B, C, S, T, or U) we calculate the corresponding torque conductivity via

$$\sigma_{K} = \frac{M_{s}lwt_{Py}}{\gamma} \frac{\tau_{K}}{(lw)E} = \frac{M_{s}lt_{Py}}{\gamma} \frac{\tau_{K}}{I_{RF}Z_{RF}},$$
 (5)

where M_s is the saturation magnetization, E is the electric field, l and w are the length and width of the MoTe₂/Py bilayer, $t_{\rm Py}=6$ nm is the thickness of the Py, and $Z_{\rm RF}$ is the device impedance. The factor $M_s l w t_{\rm Py}/\gamma$ is the total angular momentum of the magnet, and converts the normalized torque into units of angular momentum per second. Further details of the ST-FMR analysis can be found in Appendix A.

We have determined the torque conductivities for 20 MoTe₂(t_{TMD})/Py(6 nm) devices, all with distinct thicknesses of MoTe₂, t_{TMD} , and angles between the current direction and the MoTe₂ mirror plane. Details of each device can be found in Table I of Appendix B. We define ϕ_I as the angle between the current and the vector normal to the MoTe₂ mirror plane (typically called the *b*-axis in the β phase), such that $\phi_I = 0^\circ$ is perpendicular to the mirror plane and $\phi_I = 90^\circ$ is parallel. Figure 3(a) shows σ_B as a function of ϕ_I for 17 of our devices (we have excluded our bilayer-thick MoTe₂ devices for now, which will be discussed later). Consistent with the symmetry requirements on the torques, σ_B is largest when current

is applied perpendicular to the MoTe₂ mirror plane and is progressively reduced as more of the applied current flows along the mirror plane. Note that in Fig. 3(a) we have plotted $|\sigma_B|$. This is because the sign of σ_B is not solely determined by ϕ_I but also the canting of the molybdenum dimerization at the MoTe₂/Py interface, which we do not control and cannot determine by polarized Raman spectroscopy (to visualize this difference, consider a twofold rotation about the MoTe₂ c-axis for a monolayer).

In contrast to the strong dependence on ϕ_I for σ_B , the torque conductivity for the conventional component of inplane antidamping spin Hall torque, σ_S , shows no significant dependence [Fig. 3(b)]. This is similar to the σ_S dependence on ϕ_I observed in our WTe₂/Py heterostructures [12,13]. We note, however, that the relative insensitivity of σ_S to the in-plane current direction observed in β -MoTe₂ and WTe2 is not required by symmetry, and in general the magnitudes of the in-plane spins generated in response to a current along the a- or b-axes are allowed to differ [36]. We obtain an average value of σ_S for our MoTe₂/Py devices of $5800 \pm 160 \ \hbar/(2e) \ (\Omega^{-1} \,\mathrm{m}^{-1})$, smaller than the average value observed in our WTe2/Py heterostructures, $8000 \pm 200 \ \hbar/(2e) \ (\Omega^{-1} \, \mathrm{m}^{-1}) \ [12,13]$, and larger than the $\approx 3000 \ \hbar/(2e) \ (\Omega^{-1} \ \mathrm{m}^{-1})$ observed in our NbSe₂/Py heterostructures [14].

To help analyze the mechanism that drives the spin-orbit torques in our MoTe₂/Py heterostructures, it is helpful to study the torques as a function of MoTe2 thickness, holding the crystal alignment fixed. In Appendix D, we discuss the observed thickness dependence for σ_A , and we show that this torque contribution is dominated by the Oersted field. Figure 4(a) shows the thickness dependence for σ_B and σ_S for devices with current aligned perpendicular to the MoTe₂ mirror plane, where $|\phi_I| < 15^{\circ}$ and usually less than 10° . Both torques are largely independent of MoTe₂ thickness, with the notable exception of bilayer MoTe₂ devices, implying an interfacial origin for these torque components. This is in qualitative similarity to the TMD thickness dependence previously observed in WTe2. The striking exception in the thickness dependence is from our devices in which the MoTe₂ is just a bilayer (1.4 nm) thick (three different samples). In these devices, no out-of-plane antidamping torque is observed within our experimental uncertainty. Excluding the bilayer devices, we find an average value for $|\sigma_{\rm B}| = 1020 \pm$ 30 $\hbar/(2e)$ (Ω^{-1} m⁻¹). It is interesting that while the magnitude of σ_S in MoTe₂ is similar to that observed in our WTe₂ devices, the value of $|\sigma_B|$ is approximately 1/3 that of WTe₂ [12,13].

Figure 4(b) shows in more detail the measured out-of-plane antidamping torque conductivity $|\sigma_B|$ in MoTe₂/Py heterostructures in monolayer steps from a single MoTe₂ layer to quadlayer MoTe₂, all with current perpendicular to the MoTe₂ mirror plane. The contrast is striking between the large torques in the monolayer, trilayer, and quadlayer MoTe₂ devices, and the nearly zero torque in the three bilayer samples. In our previous work on WTe₂/Py devices, bilayer WTe₂ (two samples) also showed a decrease in σ_B , although in that case σ_B for the bilayer devices was $\sim 1/2$ that of the monolayer and trilayer devices rather than zero (see Fig. 5 of Ref. [13]). The origin of these reductions is unknown. Only

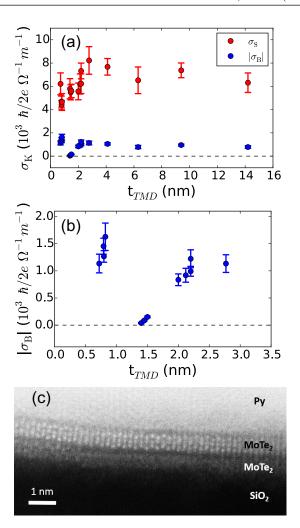


FIG. 4. (a) The torque conductivities σ_B and σ_S as a function of TMD thickness for devices with current aligned perpendicular to the MoTe₂ mirror plane. (b) Detail of the thickness dependence of σ_B in the monolayer to quadlayer regime (with a layer step size of \sim 0.7 nm). The devices that show a value near zero are bilayer MoTe₂. The applied microwave power is 5 dBm. Torque conductivities are averaged over measurements at frequencies 8–11 GHz in steps of 1 GHz. (c) Cross-sectional HAADF-STEM image of a MoTe₂ (1.4 nm)/Py device with the *a*-axis of β -MoTe₂ pointing into the page and the *b*-axis oriented within the page. The image shows two MoTe₂ layers, where the layer interfaced with the Si/SiO₂ substrate (white MoTe₂ label) shows regions of disorder that we attribute to partial oxidation. The Py is polycrystalline.

the out-of-plane antidamping torque is reduced, not σ_S or σ_A . In WTe₂, nonsymmorphic crystal symmetries (the *b-c* glide plane and *c*-axis screw) require that the spin responsible for generating τ_B must have opposite signs in adjacent layers [13]. While β -MoTe₂ does not possess the same nonsymmorphic symmetries, there is an effective in-plane polar vector at the β -MoTe₂/Py interface that changes sign for adjacent β -MoTe₂ layers [37], which could lead to oppositely directed current-induced out-of-plane spins in adjacent layers. Such a layer-dependent sign for the out-of-plane spin might lead to a partial cancellation of contributions from adjacent layers, and may have some bearing on this layer-dependent effect.

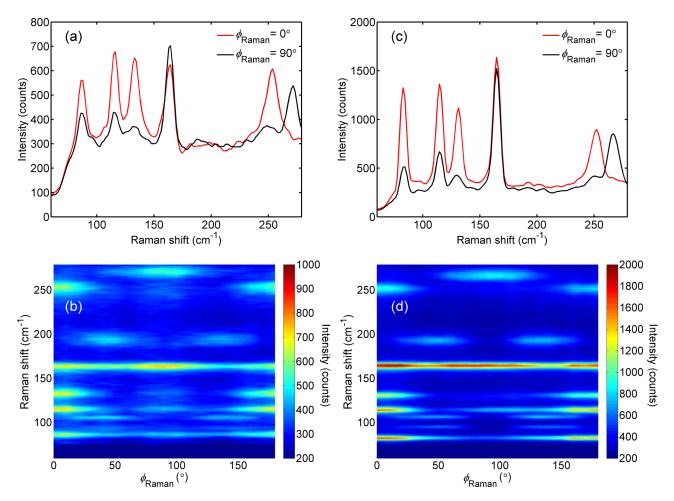


FIG. 5. (a), (c) Raman spectra for MoTe₂ monolayer and bilayer/Py devices, respectively, with a linearly polarized 488 nm excitation aligned parallel to a polarizer in front of the spectrometer. ϕ_{Raman} is the angle between the excitation polarization and the device current direction (along the bar). The red traces show spectra with the polarization parallel to the current, and the black traces show spectra with the polarization perpendicular to the current. (b), (d) Angular dependence of the Raman spectra for the two devices. The color map represents the peak intensity (with units of counts), where both spectra are taken under the same excitation power. The maximum of the ~133 and ~250 cm⁻¹ peaks correspond to the MoTe₂ *b*-axis, where $\phi_{\text{Raman}} \rightarrow -\phi_I$.

However, this mechanism alone is difficult to reconcile with our observations that a strong layer dependence is present only in the bilayer MoTe₂, and that the lower layer in our bilayer devices is also likely partially oxidized (see below).

The in-plane fieldlike torque, $\vec{\tau}_T \propto \hat{m} \times \hat{z}$, has the same symmetry constraints as $\vec{\tau}_B$ and is symmetry-allowed in our MoTe₂/Py devices when the current is applied perpendicular to the MoTe₂ mirror plane. Interestingly, we observe significant values of σ_T only in devices with sufficiently thick MoTe₂, above about 3 nm. Details can be found in Appendixes F and H. In all such devices, the ratio of σ_T/σ_B is always negative, even though the signs of σ_T and σ_B vary from sample to sample. In addition, we find that τ_T and τ_B scale similarly with the sample temperature. These observations suggest that the two torque components are correlated. However, we also find that σ_T and σ_B have distinct dependencies on the MoTe₂ thickness, in conflict with the idea that the two torques are generated through the same mechanism. Surprisingly, we also find a significant, though reduced,

value of σ_T in samples where current is flowed predominately along the MoTe₂ mirror plane [Fig. 2(c)]—i.e., the condition under which the torque is symmetry-forbidden. This suggests the possibility of two distinct mechanisms contributing to the generation of τ_T : one that is correlated with τ_B and the MoTe₂ crystal structure, and the other independent of the nominal MoTe₂ crystal structure and possibly due to strain induced by the fabrication procedure [14,38]. We note that the observation of nonzero values of both $\sigma_{\rm B}$ and $\sigma_{\rm T}$ in the same sample is in contrast to previous measurements on other TMDs. In WTe2 we did not observe any significant value of $\tau_{\rm T}$ even though a large $\tau_{\rm B}$ was present (see Fig. 6 of Ref. [13]). For (presumably) strained NbSe₂/Py devices, the situation was exactly the opposite. There we observed a large value of $\tau_{\rm T}$, but no $\tau_{\rm B}$, though with no clear dependence on the TMD thickness.

To better understand the microscopic structure of the MoTe₂/Py samples, we have performed cross-sectional high-angle annular dark-field scanning transmission elec-

tron microscopy (HAADF-STEM) imaging on a bilayer β -MoTe₂/Py device [Fig. 4(c)] as initially identified by AFM. Both β -MoTe₂ layers are clearly visible. However, the layer adjacent to the Si/SiO2 substrate shows increased localized disorder in some regions, which we attribute to partial oxidation. This partially oxidized layer remains crystallographically oriented in the unoxidized regions, while the top layer appears pristine. Oxidation just of the lower MoTe₂ layer is consistent with our sample fabrication process—the layer of MoTe₂ adjacent to the substrate is exposed to air before being placed on the substrate for exfoliation, while the other layers are protected from air exposure throughout the fabrication process. We stress that while the cross-sectional STEM does reveal some degradation to the bottom MoTe₂ layer, there are regions within that layer with substantial crystallographic order. This is demonstrated by the polarized Raman spectroscopy measurements shown in Fig. 5 for a MoTe₂/Py sample containing just a single monolayer of MoTe₂ that had been exposed to air during exfoliation. The polarized Raman spectrum still shows the peaks and polarization dependence expected for a crystalline device. This implies that some crystallographic order is preserved (since it is required to generate the expected Raman modes), and that although some damage to the layer may be present, the overall crystalline orientation remains uniform across the layer, i.e., the layer does not consist of randomly oriented polycrystalline domains.

IV. CONCLUSIONS

In summary, we have studied the current-induced spinorbit torques in β -MoTe₂/Py heterostructures at room temperature. We have observed an out-of-plane antidamping torque, $\tau_{\rm B}$, qualitatively similar to the $\tau_{\rm B}$ observed in WTe₂/Py heterostructures. This torque is consistent with the symmetries of the MoTe₂ surface—at the interface of MoTe₂ and Py the structural symmetries are limited to a single mirror plane, and consistent with that symmetry, $\tau_{\rm B}$ is observed only when a component of the current is applied perpendicular to that mirror plane. This demonstrates that breaking of inversion symmetry in the bulk of the spin-generation layer is not a necessary requirement for τ_B . The magnitude of the observed torque conductivity is $\sim 1/3$ that observed in similar devices that use WTe₂ as the spin source layer. In both materials, $\sigma_{\rm B}$ is largely independent of the TMD thickness. The torque conductivity for the standard antidamping torque, σ_S , is also independent of thickness, indicating that both torques are likely generated by an interfacial mechanism. The notable exception in the thickness dependence of $\sigma_{\rm B}$ is for bilayer-thick MoTe₂ devices, for which σ_B is zero to within measurement uncertainty. Bilayer WTe2 devices also have a greatly reduced out-of-plane antidamping torque compared to monolayer or trilayer devices, but the origin of this effect is unknown.

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APPENDIX A: CALIBRATED ST-FMR MEASUREMENTS

To make a quantitative measurement of the magnitude of the torques using Eqs. (1) and (2) we must first determine values for α_G , $R(\phi)$, and I_{RF} . The Gilbert damping is estimated from the frequency dependence of the linewidth via $\Delta = 2\pi f \alpha_G/\gamma + \Delta_0$, where Δ_0 is the inhomogeneous broadening. $R(\phi)$ is determined by measurements of the device resistance as a function of applied in-plane magnetic field angle (with a field magnitude of 0.1 T). The RF current is determined by calibrating the reflection coefficients of our devices (S_{11}) and the transmission coefficient of our RF circuit (S_{21}) through vector network analyzer measurements. These calibrations allow calculation of the RF current flowing in the device as a function of applied microwave power and frequency:

$$I_{\text{RF}} = 2\sqrt{1 \text{ mW} \times 10^{\frac{P_{\text{S}}(\text{dBm}) + S_{21}(\text{dBm})}{10}} (1 - |\Gamma|)^2 / 50 \Omega},$$
 (A1)

where $P_{\rm s}$ is the power sourced by the microwave generator and $\Gamma = 10^{S_{11}({\rm dBm})/20}$. The frequency-dependent device impedance, $Z_{\rm RF}$, is given by $50~\Omega \times (1+\Gamma)/(1-\Gamma)$.

To determine a torque conductivity [Eq. (5)], we must also obtain a value of $M_{\rm s}$ for the Py. As $M_{\rm s}$ is influenced by the material on which the Py grows (here, MoTe₂), and as mmscale β -MoTe₂/Permalloy heterostructures are unavailable, we are unable to measure $M_{\rm s}$ directly via magnetometry. Instead we approximate $M_{\rm s} \approx M_{\rm eff}$, which we have found to be accurate in other Py heterostructure systems. We estimate an average value of $\mu_{\rm o} M_{\rm eff} = 0.84 \pm 0.01$ T as extracted from the ST-FMR measurements.

APPENDIX B: DEVICES PARAMETERS

Table I shows a comparison of device parameters and torque conductivities for all samples presented in this work.

APPENDIX C: DETERMINATION OF CRYSTAL ORIENTATION

Crystals of β -MoTe₂ exfoliate in the a-b plane and are generally elongated in the Mo-chain direction, with sharp and cleanly cleaved edges running parallel to that direction. This is very similar to WTe₂, and it can be used as a first-order approximation of the in-plane crystal axis during device fabrication. We have also verified the crystal orientation more precisely for each of our devices using Raman spectroscopy.

1. Raman spectroscopy

The Raman spectra of MoTe₂ have been well characterized in all three crystal phases [28–34]. We performed Raman

TABLE I. Comparison of device parameters and torque conductivities for $MoTe_2/Py$ bilayers. Here ϕ_I is the angle between the current and the crystal axis perpendicular to the $MoTe_2$ mirror plane as measured by polarized Raman spectroscopy. For the torque conductivities, the number in parentheses gives the uncertainty of the last reported digit.

Device number	t (nm) ± 0.3 nm	$L \times W \; (\mu \text{m}) \\ \pm 0.2 \; \mu \text{m}$	$\sigma_{\rm S}$ (10 ³ $\hbar/2e~\Omega^{-1}~{ m m}^{-1}$)	$\sigma_{ m B} \ (10^3 \ \hbar/2e \ \Omega^{-1} \ { m m}^{-1})$	$\sigma_{\rm T}$ (10 ³ $\hbar/2e~\Omega^{-1}~{ m m}^{-1}$)	$ \phi_{\rm I} ({ m deg})$ $\pm 5^{\circ}$
1	0.7	5 × 4	-6.2(1)	-1.1(2)	0.026(5)	3
2	5.6	5×4	-6.1(9)	0.051(7)	-0.39(6)	89
3	6.3	5×4	-7(1)	-0.8(1)	0.8(1)	5
4	1.4	5×4	-5.8(9)	-0.04(1)	-0.22(5)	7
5	14.2	5×4	-6.3(8)	-0.8(1)	0.7(1)	0
6	2.1	5×4	-6.2(9)	0.9(1)	-0.13(2)	14
7	2.2	5×4	-7.3(7)	-0.99(9)	0.032(5)	1
8	2.8	5×4	-8(1)	-1.1(2)	0.28(4)	5
9	4.1	5×4	-7.7(7)	1.1(1)	-0.78(7)	2
10	9.4	5×4	-7.4(6)	0.95(8)	-1.0(1)	3
11	0.8	5×4	-4.4(4)	-1.3(1)	0.14(1)	1
12	1.5	5×4	-5.5(7)	-0.09(1)	0.25(3)	2
13	1.5	5×4	-5.6(6)	-0.15(2)	0.23(2)	1
14	2.0	5×4	-5.6(7)	-0.8(1)	0.21(3)	4
15	2.2	5×4	-6.2(8)	1.2(2)	0.18(2)	7
16	0.8	5×4	-4.7(5)	-1.4(1)	0.06(1)	8
17	0.8	5×4	-4.7(7)	1.6(3)	0.08(1)	3
18	2.2	5×4	-5(1)	0.6(2)	-0.17(4)	34
19	2.3	4.5×4	-8(1)	-0.60(7)	-0.41(5)	34
20	9.4	4 × 3	-8(1)	-0.26(3)	-0.55(7)	67

measurements with a confocal Raman microscope using a linearly polarized 488 nm excitation and a parallel polarizer placed in front of the spectrometer. The sample is aligned to the linear polarization direction (along the length of the device), and spectra are taken as the sample is rotated in steps of 10°. The maximum of the ~133 and ~250 cm⁻¹ peaks correspond to the MoTe₂ *b*-axis. Figure 5 shows polarized Raman spectra for two MoTe₂/Py devices in which the MoTe₂ is (a,b) a monolayer thick and (c,d) a bilayer thick. The symmetries of the observed peaks are consistent with previous measurements [28,29]. No evidence of crystallographic twinning is observed in the polarized Raman spectra.

2. Magnetic easy axis

In WTe₂/Py bilayers, we observed previously that the WTe₂ induced a strong in-plane magnetic easy axis that corresponded with the *b*-axis of the crystal, regardless of the applied current direction [12,13]. This correlation provided an efficient means for extracting the angle between the WTe₂ crystal axes and the current direction through electrical measurements alone. However, we find that MoTe₂ does not induce any significant magnetic easy-axis within the Py, so this method cannot be used to characterize the crystal alignment of MoTe₂. TaTe₂ generates a magnetic easy axis with strength intermediate between WTe₂ and MoTe₂ [16]. This variation suggests different degrees of coupling between the TMDs and Permalloy.

APPENDIX D: OUT-OF-PLANE FIELDLIKE TORQUE AND OERSTED TORQUE

We extract the individual resistivities of the MoTe₂ and Py layers using the two-point resistances of our devices for which the current is aligned perpendicular to the MoTe₂ mirror plane (i.e., $\phi_I = 0^{\circ}$) within 15° and usually within 10°, where we have used only devices in which the Py thin-film and Al capping layers where grown in the same sputtering deposition batch in order to minimize effects from small variations in the Py and Al thicknesses. We plot the inverse of the sheet resistance as a function of $t_{\rm TMD}$ [Fig. 6(a)], and using the relation

$$\frac{1}{R_{\square}} = \frac{l}{wR} = \frac{t_{\text{Py}}}{\rho_{\text{Py}}} + \frac{t_{\text{TMD}}}{\rho_{\text{TMD}}},\tag{D1}$$

we extract the resistivities $\rho_{Py} = 95 \pm 2 \ (\mu\Omega \ cm)$ and $\rho_{TMD} = 550 \pm 75 \ (\mu\Omega \ cm)$. The value obtained for ρ_{Py} is similar to that seen in our WTe₂/Py devices when the Py is deposited using glancing-angle sputtering.

Figure 6(b) shows σ_A as a function of t_{TMD} (red circles) for devices in which current is aligned perpendicular to the MoTe₂ mirror plane. A strong thickness dependence of the torques is observed. In many material systems this component of torque, $\propto \hat{m} \times \hat{y}$ (for current in the \hat{x} direction), is dominated by the Oersted torque—that is, the magnetic field generated from a simple current-carrying wire. For instance, we have previously shown that this is the case in the WTe₂/Py and NbSe₂/Py systems. We can model the torque conductivity

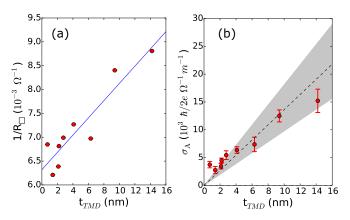


FIG. 6. (a) Inverse sheet resistance of devices with current perpendicular to the MoTe₂ mirror plane (red circles) as a function of MoTe₂ thickness as measured by a two-point method. The blue line gives a fit using Eq. (D1) to extract the sheet resistances for the Py and MoTe₂. (b) Torque conductivity for the out-of-plane fieldlike torque $(\propto \hat{m} \times \hat{y})$ as a function of thickness for devices with current perpendicular to the MoTe₂ mirror plane (red circles). The dashed line gives the predicted Oersted field contribution from the torques [Eq. (D2)], and the shaded region gives the spread in the expected contribution as given by the uncertainty in the measured charge conductivity of MoTe₂. The applied microwave power is 5 dBm. Torque conductivities are averaged over measurements at frequencies 8–11 GHz in steps of 1 GHz. In both plots, we have used only devices in which the Py thin-film and Al capping layers were grown in the same sputtering deposition batch in order to minimize effects from small variations in the Py and Al thicknesses.

generated by the Oersted torque as

$$\sigma_{\text{Oe}} = \frac{e\mu_0 M_{\text{S}} t_{\text{Py}} \sigma_{\text{TMD}}}{\hbar} t_{\text{TMD}}, \tag{D2}$$

where σ_{TMD} is the charge conductivity of the MoTe₂. The dashed line in Fig. 6(b) shows the predicted Oersted torque using the extracted value of ρ_{TMD} , and the shaded region about the dashed line gives the uncertainty in the predicted torque as given by the spread in ρ_{TMD} . All devices with the possible exception of our monolayer device are well described by the predicted Oersted torque. Deviation from the predicted Oersted torque in our monolayer device may suggest a nonuniform current distribution in the Py film, as cross-sectional HAADF STEM imaging of one of our β -MoTe₂ devices suggests that partial oxidation of the monolayer may play a role in an increased resistivity of that layer, and could affect the growth of the Py on top of such a layer [see Fig. 4(c) and associated discussion].

APPENDIX E: DRESSELHAUS-LIKE TORQUES

Figure 7 shows the torque conductivities for the torque components $\sigma_C \propto \hat{m} \times \hat{x}$, and $\sigma_U \propto \hat{m} \times (\hat{m} \times \hat{x})$ as a function of applied current direction, ϕ_I . (Recall that $\phi_I = 0^\circ$ corresponds to current directed perpendicular to the MoTe₂ mirror plane.) We refer to the torques σ_C and σ_U as Dresselhauslike [16]. Symmetry requires that the Dresselhaus-like torques be zero when the current is either along or perpendicular to

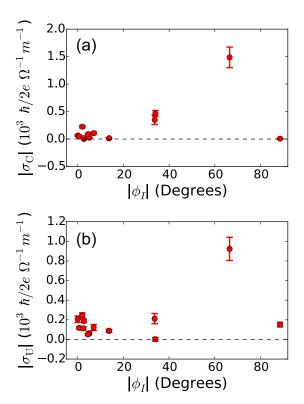


FIG. 7. (a) and (b) Torque conductivities for the Dresselhaus-like torques (a) $\propto \hat{m} \times \hat{x}$ and (b) $\propto \hat{m} \times (\hat{m} \times \hat{x})$ as a function of $|\phi_I|$ for all of our ST-FMR devices. The applied microwave power is 5 dBm. Torque conductivities are averaged over measurements at frequencies 8–11 GHz in steps of 1 GHz.

a mirror plane (e.g., $\phi_I = 0^\circ$ or 90° , the situations for the majority of the samples studied in this work, including all the samples shown in Fig. 4). Consistent with this requirement, in Fig. 7 both σ_C and σ_U are zero when $\phi_I = 0^\circ$ or 90° , and they can be nonzero at intermediary angles. At present, we do not have enough devices at intermediary values of ϕ_I to accurately gauge the magnitude of these effects. However, these torque components should arise naturally in MoTe₂/ferromagnet heterostructures because MoTe₂ has an in-plane resistivity anisotropy [39], and this will cause spatially nonuniform current flows with nonzero transverse components whenever the voltage is applied at an angle tilted away from a symmetry axis [16].

APPENDIX F: IN-PLANE FIELDLIKE TORQUE

The symmetry requirements for the in-plane fieldlike torque component, $\vec{\tau}_T \propto \hat{m} \times \hat{z}$, are identical to that of $\vec{\tau}_B \propto \hat{m} \times (\hat{m} \times \hat{z})$. That is, τ_T is allowed by symmetry if there is a component of current perpendicular to the single mirror plane. In some but not all of our MoTe₂/Py devices, we observe a small but nonzero value of τ_T . Figure 8 shows V_S and V_A for one such device (Device 3, with 6.3 nm of MoTe₂) for which current is applied perpendicular to the mirror plane. Fitting V_A and V_S with Eqs. (3) and (4), we can extract a ratio of the torques $\tau_T/\tau_S = -0.114 \pm 0.002$ and $\tau_T/\tau_B = -0.90 \pm 0.02$. We observe significant values of σ_T only in devices

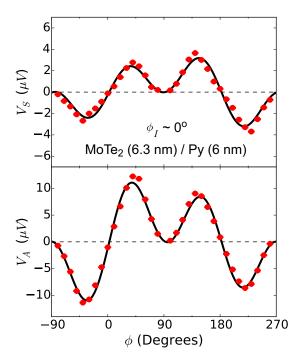


FIG. 8. Dependence on the applied magnetic field angle for both the symmetric, $V_{\rm S}$, and antisymmetric, $V_{\rm A}$, component of the mixing voltage for a device that shows an in-plane fieldlike torque $\propto \hat{m} \times \hat{z}$ (Device 3), with MoTe₂(6.3 nm)/Py(6 nm) and current applied perpendicular to the MoTe₂ mirror plane. Fits of the angular dependence are made using Eqs. (3) and (4). The applied microwave power is 5 dBm at 9 GHz.

with sufficiently thick MoTe₂, above about 3 nm (Fig. 9). The average value of $|\sigma_T|$ for samples with MoTe₂ thickness greater than 3 nm and $\phi_I \approx 0^\circ$ is $810 \pm 50 \, \hbar/(2e) \, (\Omega^{-1} \, \text{m}^{-1})$. In all such devices with the current perpendicular to the mirror plane, the ratio of σ_T/σ_B is always negative, even though the signs of σ_T and σ_B vary from sample to sample [see Fig. 9(a)]. This, together with a similar dependence on sample temperature for τ_T and τ_B as discussed in Appendix H, suggests that these two torque components are correlated. We note, however, that σ_T and σ_B exhibit very different thickness dependencies, with σ_T showing a dependence on thickness typically associated with bulk spin-orbit torque generation, whereas σ_B is interfacial in nature.

Figure 9(c) shows $|\sigma_T|$ as a function of $|\phi_I|$ for devices with TMD thickness above 3 nm. σ_T shows a clear decrease in magnitude as the direction of the current is increasingly aligned along the MoTe₂ mirror plane. However, near $|\phi_I|$ = 90° there remains a significantly nonzero value of σ_T inconsistent with a symmetry analysis of the nominal MoTe₂/Py structure. This is reminiscent of the observed σ_T in NbSe₂/Py devices [14], in which we presumed a uniaxial strain induced by the fabrication procedure reduced the nominally high symmetry NbSe₂ structure in such a way that this torque could be generated [38]. Note that for (presumably) strained NbSe₂/Py devices we observed a large value of τ_T , but no τ_B .

Together, these observations suggest that there may be two mechanisms that contribute to σ_T in β -MoTe₂: one that

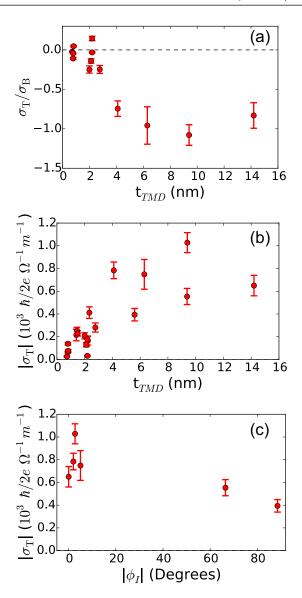


FIG. 9. (a) The torque ratio σ_T/σ_B as a function of thickness for devices with the current applied perpendicular to the MoTe₂ mirror plane direction. Note that the ratio is always negative when nonzero. We have excluded the bilayer devices as $\sigma_B \sim 0$. (b) Torque conductivity $|\sigma_T|$ as a function of TMD thickness for all devices. The torque is only appreciable above a TMD thickness of 3 nm. (c) $|\sigma_T|$ as a function of $|\phi_I|$ for devices with TMD thickness above 3 nm. The applied microwave power is 5 dBm. Torque conductivities are averaged over measurements at frequencies 8–11 GHz in steps of 1 GHz.

is correlated with σ_B and dependent on the MoTe₂ crystal structure, and another that is generated by a symmetry breaking associated with the strain induced during the fabrication procedure.

APPENDIX G: DETERMINING THE CRYSTAL PHASE IN THE FEW-LAYER LIMIT

In bulk crystals, MoTe₂ undergoes a hysteretic transition from the β phase to the γ phase when cooled below

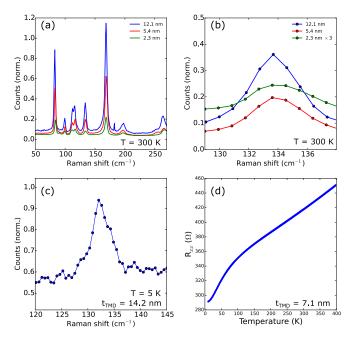


FIG. 10. (a) Raman spectroscopy measurements of MoTe₂/Py samples with the excitation and collection linearly polarized in a parallel configuration along the Mo chain for three different thicknesses at room temperature. (b) A detailed view of the 133 cm⁻¹ mode shown in (a). No peak splitting is observed indicating that the MoTe₂ is in the β phase. Spectra for (a) and (b) are taken with a 532 nm excitation. (c) Raman spectrum with a 633 nm excitation at 5 K for a 14.2 nm MoTe₂/Py device. (d) Four-point resistance of a MoTe₂(7.1 nm)/Py device as a function of temperature, with a sample width of 4 μ m, length 15 μ m, and a dc current of 50 μ A.

approximately 250 K [27], with a temperature hysteresis of about 20 K. The orthorhombic (γ) phase is obtained by a shift in the stacking of the van der Waals layers in β -MoTe₂. This phase is isostructural to WTe₂. Both pressure [40,41] and impurity doping [42–44] have been shown to influence the transition temperature. While the majority of published studies on γ -MoTe₂ have focused on bulk crystals [27,29,31,45–48], a handful of reports have studied the phase transition in thin films [28–30,34,49]. Recent work has suggested there may be a thickness dependence to the transition in the few-layer limit [34,49].

The β and γ phase can be distinguished experimentally through polarized Raman spectroscopy by the presence in the γ phase of one additional peak at \sim 11 cm⁻¹ and a peak splitting in the \sim 133 cm⁻¹ mode [29,31]. To verify the MoTe₂ crystal phase of our devices, we performed Raman spectroscopy measurements of our MoTe₂/Py films using 532 and 633 nm excitations at room temperature and at 5 K [Figs. 10(a)–10(c)]. We see no evidence of the 133 cm⁻¹ peak splitting at room temperature for samples with MoTe₂

thicknesses from 2.3 to 12.1 nm [Fig. 10(b)], indicating that at room temperature our films are in the β phase, as expected. The 133 cm⁻¹ peak splitting in the γ phase is approximately 5 cm⁻¹ wide, and so it should be resolved by these measurements. The Raman measurements at 5 K also do not show a splitting in the 133 cm⁻¹ peak [Fig. 10(c)]. Furthermore, measurements of the four-point resistance of a MoTe₂/Py device as a function of temperature [Fig. 10(d)] do not show the hysteretic resistivity feature associated with the transition in bulk samples. These data, therefore, suggest that our thin films are stabilized in the β phase, perhaps due to the deposition of the Py, with no transition to the γ phase in the measured temperature range.

APPENDIX H: TEMPERATURE-DEPENDENT MEASUREMENTS OF SPIN-ORBIT TORQUE

One of our original motivations for studying spin-orbit torques generated by MoTe₂ was to try to observe changes in the torques as the MoTe₂ underwent a phase transition from the β to the γ phase as a function of decreasing temperature. As noted in Appendix G, it turns out that our device structure stabilizes the β phase so that we did not observe any transition to the γ phase. Consistent with the lack of a phase transition in the Raman and four-point resistivity data, measurements of the spin-orbit torques as a function of temperature also reveal a smooth evolution, with no indication of an abrupt transition.

We performed temperature-dependent ST-FMR measurements for one of our MoTe₂/Py devices ($t_{TMD} = 8.6$ nm, length 4 μ m and width 3 μ m), where current is applied perpendicular to the MoTe₂ mirror plane ($\phi_I \sim 0^\circ$). Figure 11 shows the ratios of the measured torques as a function of temperature, where the torque magnitudes are extracted from the angular dependence of the applied field direction for V_A and $V_{\rm S}$, as discussed in the main text. The reason why we plot torque ratios rather than individual values is that it is difficult to calibrate accurately within our cryostat the exact value of the microwave current within the sample. We observe a smooth increase in the Oersted torque τ_A with decreasing temperature, reflected in a decrease in the ratio $\tau_{\rm S}/\tau_{\rm A}$. This is consistent with the decrease in resistivity of MoTe₂ as a function of decreasing temperature, but with no indication of a phase transition to the γ phase. The out-of-plane antidamping component $\tau_{\rm B}$ increases as temperature decreases while the corresponding in-plane antidamping component τ_S decreases, meaning that the total effective tilt angle of the generated antidamping torque is increasingly pulled out of plane with decreasing temperature. The ratio of $\tau_{\rm T}/\tau_{\rm B}$ is constant, indicating that the two torques have the same dependence on temperature. This is additional evidence for the conjecture that these two torque components may arise from related microscopic mechanisms (see the discussion in Appendix F).

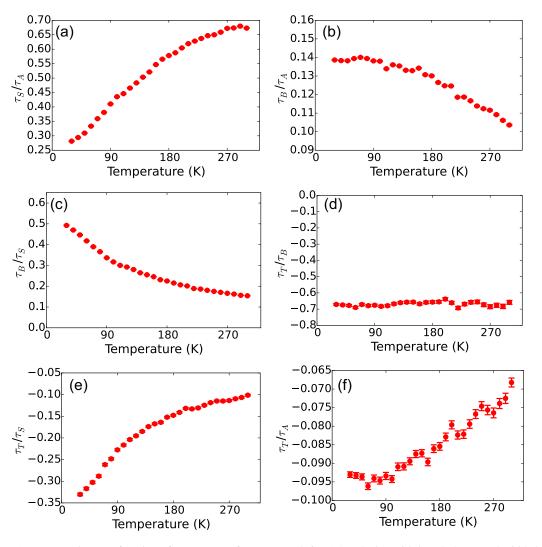


FIG. 11. (a)–(e) Torque ratios as a function of temperature for a MoTe₂(8.6 nm)/Py device with length 4 μ m and width 3 μ m, with the current applied perpendicular to the MoTe₂ mirror plane ($\phi_I \sim 0^{\circ}$). The applied microwave power is 8 dBm at a frequency of 9 GHz.

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