

Optimal control and analysis of a modified trojan Y-Chromosome strategy

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ABSTRACT

The Trojan Y Chromosome (TYC) strategy is a promising eradication method that attempts to manipulate the female to male ratio to promote the reduction of the population of an invasive species. The manipulation stems from an introduction of sex-reversed males, called supermales, into an ecosystem. The offspring of the supermales is guaranteed to be male. Mathematical models have shown that the population can be driven to extinction with a continuous supply of supermales. In this paper, a new model of the TYC strategy is introduced and analyzed that includes two important modeling characteristics, that are neglected in all previous models. First, the new model includes intraspecies competition for mates. Second, a strong Allee effect is included. Several conclusions about the strategy via optimal control are established. These results have large scale implications for the biological control of invasive species.

1. Introduction

The detrimental effects of aquatic invasive species is well-documented (Arim et al., 2006; Averill and Lou, 2012; Bampfylde and Lewis, 2007; Clark et al., 2001; Lou and Munther, 2012; Myers et al., 2000; Okubo et al., 1989; Shigesada and Kawasaki, 1997; Van Driesche and Bellows, 1996). Subsequently, a tremendous amount of effort by habitat controllers is devoted to designing effective eradication strategies such as chemical treatment, local harvesting, dewatering, ichthyocides, or a suitable combination (Schofield and Loftus, 2015). However, these methods are known to negatively impact ecosystems, which may be already stressed by the presence of an aquatic invasive species (Schofield and Loftus, 2015).

The Trojan Y chromosome strategy (TYC) is a new eradication strategy which circumvents many of the known negative ecological impacts due to current practice (Gutierrez and Teem, 2006; Schofield and Loftus, 2015; Teem et al., 2013). TYC strategy involves an introduction of a sex-reversed male. The off-spring of the sex-reversed male, called a supermale, with a wild-type female is guaranteed to be male. Therefore, subsequent generations become male-dominant and this skews the sex ratio towards more males. The goal, is that through the gradual reduction in the female population, extinction of the population may occur (see Fig. 1). The supermale is not a genetically

modified organism (GMO) and the TYC process is reversible, that is, if the introduction of supermales is stopped then the supermale population will die out (Schill et al., 2017). The TYC strategy has seen tremendous experimental and theoretical interest (Cotton and Wedekind, 2007a, 2007b, 2009; Gutierrez et al., 2012; Kennedy et al., 2018; Parshad, 2011; Parshad and Gutierrez, 2011, 2010; Parshad et al., 2013; Perrin, 2009; Schill et al., 2016; Teem et al., 2013; Wang et al., 2016, 2014; Zhao et al., 2012).

The classical population model of the TYC strategy relates the populations of the wild-type XX females (f), wild-type XY males (m), and the YY supermale (s) populations over time. A mathematical model was first proposed by Gutierrez and Teem (2006), Teem et al. (2013):

$$\dot{f} = \frac{1}{2}\beta L f m - \delta f, \quad (1)$$

$$\dot{m} = \frac{1}{2}\beta L f m + \beta L f s - \delta m, \quad (2)$$

$$\dot{s} = \mu - \delta s, \quad (3)$$

where $L = 1 - \frac{f+m+s}{K}$, K is the carrying capacity, β is the birth rate, δ is the death rate, and μ is the constant introduction rate. The parameters and populations are assumed to be nonnegative. Due to the nonlinearities, it is not necessary to assume that $\beta > \delta > 0$, to obtain a

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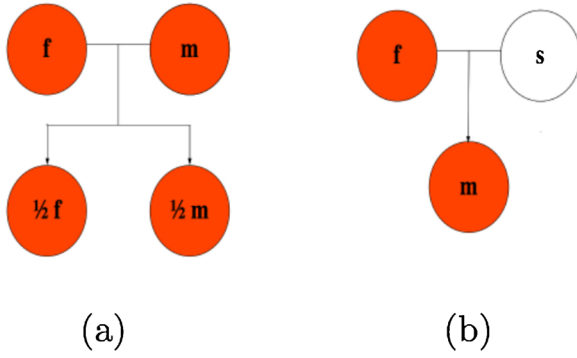


Fig. 1. The pedigree tree of the TYC model (that demonstrates Trojan Y-Chromosome eradication strategy). (a) Mating of a wild-type XX female (f) and a wild-type XY male (m). (b) Mating of a wild-type XX female (f) and a YY supermale (s). Red color represents wild types, and white color represents phenotypes. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

persistent invasive population. It was shown in Teem et al. (2013) that there exists a μ^* such that for all $\mu > \mu^* > 0$ that $f, m \rightarrow 0$ in infinite time.

In the current manuscript, we seek to include two important and relevant modeling features. First, the influx of supermales leads to competition between wild-males and supermales for female mates. Second, if the female population is below a given threshold then the population loses fitness and extinction should occur (Drake and Kramer, 2011; Kramer, 2009). This latter phenomena is called the Allee effect. These two modeling features are introduced in Section 2. A stability analysis of the equilibrium solutions is also included in Section 2. In Section 3, we then investigate the influence that intraspecies competition and the Allee effect have on the optimal introduction rate that minimizes an objective function based on the total wild population and introduced super males. A stochastic model is introduced to examine the influence of noise on the birth and death rates have on the objective function's value at the optimal introduction rate.

2. Modified TYC model with strong Allee effect

In this paper, we investigate and propose a new model of the TYC strategy. Namely,

$$\dot{f} = \frac{1}{2}\beta L \left(\frac{f}{\alpha} - 1 \right) \rho_1(m, s) fm - \delta f, \quad (4)$$

$$\dot{m} = \frac{1}{2}\beta L \left(\frac{f}{\alpha} - 1 \right) \rho_1(m, s) fm + \beta L \left(\frac{f}{\alpha} - 1 \right) \rho_2(m, s) fs - \delta m, \quad (5)$$

$$\dot{s} = \mu - \delta s, \quad (6)$$

where L, μ, β , and δ are as before. Again, the parameters and populations are assumed to be nonnegative and that $\beta > \delta > 0$, that is, the birth supercedes the death rate.

Intraspecies competition between wild male and supermale populations for female mates is modeled through the nonnegative saturation term:

$$\rho_1(m, s) = \frac{m}{m + s}, \quad \rho_2(m, s) = \frac{s}{m + s}.$$

The saturation terms provide the percentage of the total male population that is either wild-type or supermale. Clearly, the range of the saturations term is $[0, 1]$. Notice, for a fixed wild-type population, as $s \rightarrow \infty$ then $\rho_1 \rightarrow 0^+$ and $\rho_2 \rightarrow 1^-$. In this situation, the birth of females approaches zero while male offspring only occurs from female and supermale progeny. Likewise, for a fixed supermale population, as $m \rightarrow$

∞ then $\rho_1 \rightarrow 1^-$ and $\rho_2 \rightarrow 0^+$; subsequently, male progeny only occurs from wild-type male and female mating. Therefore, ρ_1 and ρ_2 attempt to model the difficulty of wild-type female finding suitable mates from either wild-type or supermale populations.

The term $f/\alpha - 1$ models a strong Allee effect and represents a loss of fitness in the female population when below the Allee threshold, α . This effect models the problem of *undercrowding* of a species and was first motivated by observations made by Allee in 1927 (Allee, 1927, 1931; Odum and Allee, 1954). Since then, numerous evidences of this effect have been established (Kramer, 2009; Stephens and Sutherland, 1999). Notice, that when $f/\alpha - 1 < 0$ then $\dot{f} < 0$, provided $L > 0$. Therefore, the female population will decrease toward extinction. Subsequently, a goal of the TYC strategy is to *push*, via the introduction of supermales, the female population below the Allee threshold.

In the forthcoming analysis, the equations are rescaled. The populations are scaled by the carrying capacity while the t is scaled by the deathrate, that is $t \rightarrow t/\delta$. The rescaled equations are:

$$\dot{f} = r L \left(\frac{f}{a} - 1 \right) \left(\frac{m}{m + s} \right) fm - f, \quad (7)$$

$$\dot{m} = r \frac{L f}{m + s} \left(\frac{f}{a} - 1 \right) (m^2 + 2s^2) - m, \quad (8)$$

$$\dot{s} = \gamma - s, \quad (9)$$

where $L \rightarrow 1 - (f + m + s)$, $r = \frac{K\beta}{2\delta} > 1$, $a = \frac{\alpha}{K} \ll 1$, and $\gamma = \frac{\mu}{K\delta}$.

2.1. Equilibria and stability analysis

A clear requirement of a valid intervention strategy is that in the absence of the strategy the invasive population would persist, while if the intervention strategy was employed then control, ideally extinction, of the invasive species would be established. Therefore, an effective TYC strategy is one that provides an introduction rate, $\gamma(t)$, and initial supermale population, $s(0)$, such that the wild-population is driven to extinction, while in the supermale free case the population would persist.

It is clear that the modified model exhibits the equilibrium solution $(0, 0, \gamma)$, which is deemed the *extinction state*. Once $f < a$, the introduction rate of supermales, γ , should be set zero, causing $s \rightarrow 0$. As a result, a clear requirement of a successful TYC strategy is that there exists some time for which the female population is below the Allee threshold, that is, $f < a$.

In the forthcoming equilibrium analysis we are interested in equilibrium solutions in the situation where $\gamma = 0$. Obviously, when $\gamma = 0$ then in equilibrium $s = 0$, therefore the intraspecies terms $\rho_1(m, 0) = 1$ and $\rho_2(m, 0) = 0$. In such case:

$$f \left(r L \left(\frac{f}{a} - 1 \right) m - 1 \right) = 0, \quad m \left(r L \left(\frac{f}{a} - 1 \right) f - 1 \right) = 0.$$

We seek to analyze the stability and presence of nontrivial equilibrium solutions. Noting that in equilibrium $f/a - 1 \neq 0$ then

$$m = f = \frac{1}{r L (f/a - 1)}.$$

Hence, all equilibrium solutions fall on the line $f = m$. The non-trivial equilibrium solutions are roots to the third degree polynomial:

$$g(f) = -2f^3 + (2a + 1)f^2 - a f - \frac{a}{r}. \quad (10)$$

By Descartes' rule of signs there always exists a one negative real root, which is neglected since this is not realistic. In addition, there are either two or zero positive real roots. If there are zero positive real roots then the only equilibrium solution is the extinction state and is globally attracting. In such case, the TYC strategy is not necessary. Therefore, we

assume there are two real roots, f_1 and f_2 , where $0 < f_1 < f_2$.

The Jacobian of our system of equations is

$$J = \begin{pmatrix} \kappa + \mu - 1 & \kappa & c \\ \kappa + \mu & \kappa - 1 & c \\ 0 & 0 & -1 \end{pmatrix}$$

where

$$\begin{aligned} \kappa &= (1 - 2f)f \left(-1 + \frac{f}{a} \right) r - f^2 \left(-1 + \frac{f}{a} \right) r, \\ c &= -(1 - 2f)f \left(-1 + \frac{f}{a} \right) r - f^2 \left(-1 + \frac{f}{a} \right) r, \\ \mu &= \frac{(1 - 2f)f^2 r}{a}. \end{aligned}$$

Clearly, $\lambda_3 = -1$ is an eigenvalue, which indicates exponentially decay in the supermale population. The remaining two eigenvalues are determined by the characteristic equation of the submatrix J_{33} . Namely,

$$\begin{aligned} \lambda_{1,2} &= \frac{\text{tr}(J_{33}) \pm \sqrt{\text{tr}(J_{33})^2 - 4\det(J_{33})}}{2} \\ &= -1, \quad 2\kappa + \mu - 1. \end{aligned}$$

To investigate the sign of λ_2 we recall that f_i is a root of Eq. (10). This fact, is used to determine an expression for λ_2 as a function of f_i :

$$\lambda_2(f_i) = 3 + 2f_i r - \left(2 + \frac{1}{a} \right) f_i^2 r.$$

Notice, that this function is a concave down quadratic with a maximum location located at $f = 1/(2 + 1/a) > 0$. Define f_+ as the positive root of the quadratic function $\lambda_2(f)$. Then $\lambda_2 > 0$ if $f_i < f_+$ and $\lambda_2 < 0$ if $f_i > f_+$. Notice that $\lambda_2(1) = 3 - r/a$. Since $a \ll 1$ implies that $r/a \gg 1$ then $\lambda_2(1) < 0$. Subsequently, we have $0 < f_+ < 1$.

Notice that $g(0), g(1) < 0$. Now, $g(f_+) > 0$ provided that

$$\begin{aligned} q(r, a) &= r(2 + 16a^3 + ar + 4a^3r + \sqrt{ar(3 + 6a + ar)} \\ &\quad + 4a^2\sqrt{ar(3 + 6a + ar)}) \\ &\quad - 2(3 + 6a + 2ar)(ar + \sqrt{ar(3 + 6a + ar)}) > 0. \end{aligned}$$

Fig. 2 shows the region where $q(r, a) > 0$ and $q(r, a) < 0$. While the Allee threshold is difficult to know precisely for any biological system (Drake and Kramer, 2011), it is reasonable to expect values less than 5% of the carrying capacity (Drake and Kramer, 2011; Odum and Allee, 1954). In such case, $g(f_+) > 0$ then by the Intermediate Value

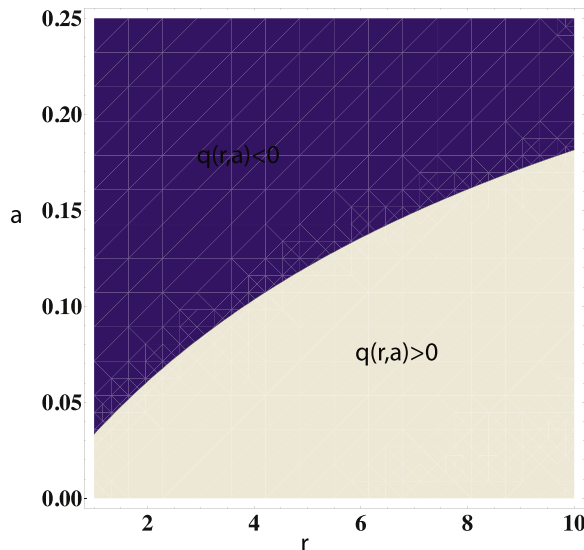


Fig. 2. Plot of $q(r, a)$ indicating regions where $q(r, a)$ is greater than zero and less than zero.

Theorem we have $f_1 < f_+ < f_2$. Subsequently, $(f_1, f_1, 0)$ and $(f_2, f_2, 0)$ are a saddle and a sink, respectively. We call $(f_2, f_2, 0)$ the *sustained state*. An effective TYC strategy will push populations away from the sustained state and toward the basin of attraction of the extinction state.

3. Optimal control analysis

3.1. Optimal control analysis

The goal of this section is to investigate the mechanisms in our TYC system of equations, that, if controlled, could lead to optimal levels of both densities. We assume that the scaled introduction rate γ is not known *a priori* and enter the system as a time-dependent control, such that $0 \leq \gamma(t) < \infty$. Consider the objective function

$$J_0(\gamma) = \int_0^T - (f + m) - \frac{1}{2}\gamma^2 dt$$

subject to the governing Eqs. (7)–(9) and initial conditions. Optimal strategies are derived for the objective function, where we minimize both female and male populations while also minimizing the introduction rate γ . Optimal controls are searched for within the set U_0 , namely,

$$U_0 = \{\gamma | \gamma \text{ measurable, } 0 \leq \gamma < \infty, t \in [0, T], \forall T\}.$$

The goal is to seek an optimal $\gamma^*(t)$ such that,

$$J_0(\gamma^*) = \max_{\gamma} \int_0^T - (f + m) - \frac{1}{2}\gamma^2 dt. \quad (11)$$

We use the Pontryagin's maximum principle to derive the necessary conditions on the optimal control (Lenhart and Workman, 2007). The Hamiltonian for J_0 is given by

$$H_0 = -(f + m) - \frac{1}{2}\gamma^2 + \lambda_1 f' + \lambda_2 m' + \lambda_3 s'.$$

We use the Hamiltonian to find a differential equation of the adjoint $\lambda_i, i = 1, 2, 3$. Namely,

$$\begin{aligned} \lambda_1'(t) &= \lambda_2 \frac{r(m^2 + 2s^2)}{m + s} \left(f \left(\frac{f}{a} - 1 \right) + \left(\frac{2f}{a} - 1 \right) (f + m + s - 1) \right) + \\ &\quad \lambda_1 \frac{m^2 r}{m + s} \left(f \left(\frac{f}{a} - 1 \right) + \left(\frac{2f}{a} - 1 \right) (f + m + s - 1) + 1 \right) + 1, \\ \lambda_2'(t) &= \left(\frac{f}{a} - 1 \right) \left[\lambda_1 \frac{fmr}{m + s} \left(m + 2(f + m + s - 1) \right) \right. \\ &\quad \left. - \frac{m(f + m + s - 1)}{m + s} \right] + \\ &\quad \lambda_2 \frac{fr(m^2 + 2s^2)}{m + s} + \lambda_2 \frac{fr(f + m + s - 1)}{m + s} \left(2m - \frac{m^2 + 2s^2}{m + s} \right) + 1, \\ \lambda_3'(t) &= \left(\frac{f}{a} - 1 \right) \frac{fr}{m + s} \left[\lambda_2 \left\{ (f + m + s - 1) \left(4s - \frac{m^2 + 2s^2}{m + s} \right) + \right. \right. \\ &\quad \left. \left. (m^2 + 2s^2) \right\} + \lambda_1 \left(m^2 - \frac{m^2(f + m + s - 1)}{(m + s)} \right) \right] + \lambda_3. \end{aligned}$$

with the transversality condition given by

$$\lambda_1(T) = \lambda_2(T) = \lambda_3(T) = 0.$$

In consideration of the optimality conditions, the Hamiltonian function is differentiated with respect to control variable γ resulting in:

$$\frac{\partial H}{\partial \gamma} = \lambda_3 - \gamma.$$

A compact way of writing the optimal control γ^* is

$$\gamma^*(t) = \max(0, \lambda_3).$$

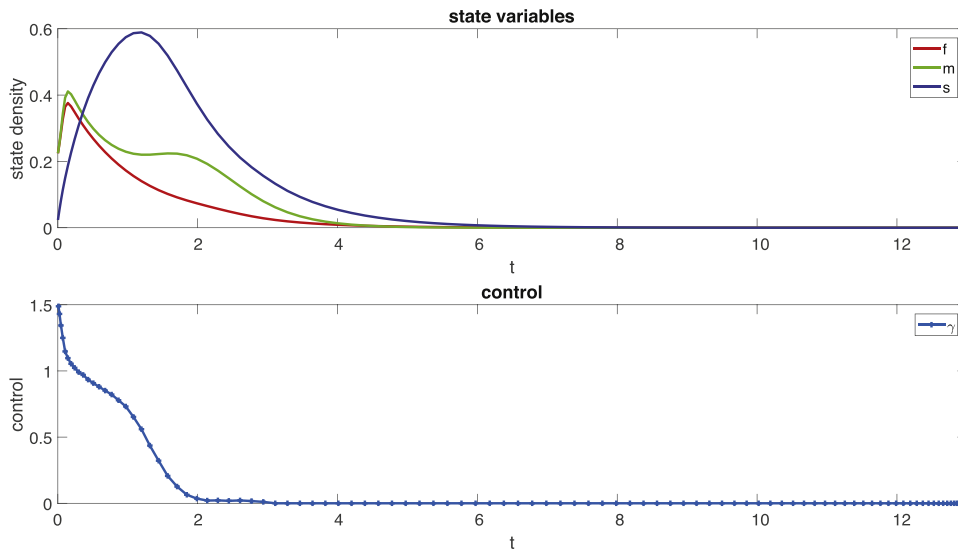


Fig. 3. Female (top-red), male (top-green) and supermale (top-blue) densities and optimal control of $\gamma(t)$ (bottom) in change with time t for the modified Eqs. (7)–(9) that include intraspecies competition and a strong Allee effect. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

3.2. Numerical simulations

In this section, we will numerically simulate the optimal control for the modified TYC model with strong Allee effect. The following unscaled parameters used for simulation are provided from a least squares approximation of population experiments of guppy fish in [Lyu et al. \(2019\)](#), namely, $\beta = 0.0057$, $\delta = 0.0648$, $K = 405$, $\alpha = 24$, and time interval of $(0, 200)$. In scaled variables:

$$r \approx 17.8125, \quad a \approx .06, \quad 0 < t < 12.96.$$

In [Fig. 3](#), the numerically determined optimal $\gamma(t)$ is shown in conjunction with the scaled populations using the optimal control $\gamma(t)$. This indicates, that a gradual reduction in the introduction rate of the supermales is ideal, with the highest introduction rate at the beginning of the intervention program.

As a basis of comparison, the optimal μ in unscaled variables for the classical model was determined in [Lyu et al. \(2019\)](#) (see [Fig. 5](#)), which is shown in [Fig. 4](#) in scaled variables for convenience. In such case, a larger objective function value at the optimal introduction rate is discovered in the absence of intraspecies competition and a strong Allee

effect. In particular, the objective values, in absolute value, for the classical and modified models are 501.9203 and 315.1675, respectively. The reduced value of the objective function in the modified model is clear by inspection of the plots of the integrands of the corresponding objective functions given in [Fig. 5](#). Therefore, the inclusion of intraspecies competition and the Allee effect greatly influence the overall cost of the TYC strategy and indicate the strategy is less costly than previously considered in [Lyu et al. \(2019\)](#). In the case, of the TYC model that includes intraspecies competition for mates and does not consider the Allee effect obtains an objective value of 381.3074, which is still considerably lower than the classical model. Likewise, the model that includes the Allee effect but no intraspecies competition obtains an objective value of 390.3713. However, this suggests that intraspecies competition for mates has a greater influence on the choice of γ than the Allee effect.

In [Fig. 6](#) we examine the influence of increasing the value of the dimensionless variable r . As r increases we see that optimal control is maintains the same overall shape. In particular, the initial introduction remains the same, however, the initial drop in the introduction rate is less severe in the case of higher reproductive rates.

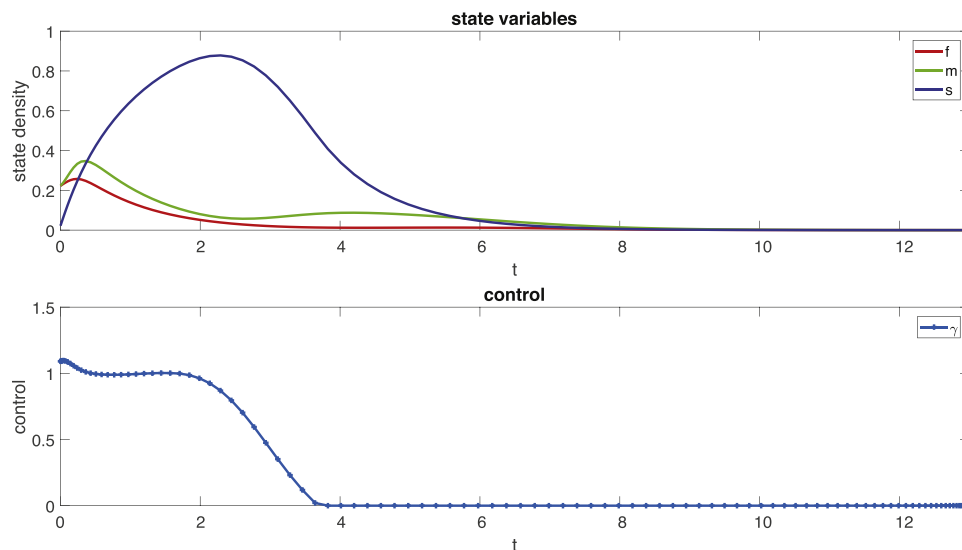


Fig. 4. Female (top-red), male (top-green) and supermale (top-blue) densities and optimal control of $\gamma(t)$ (bottom) in change with time t for the classical TYC model. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

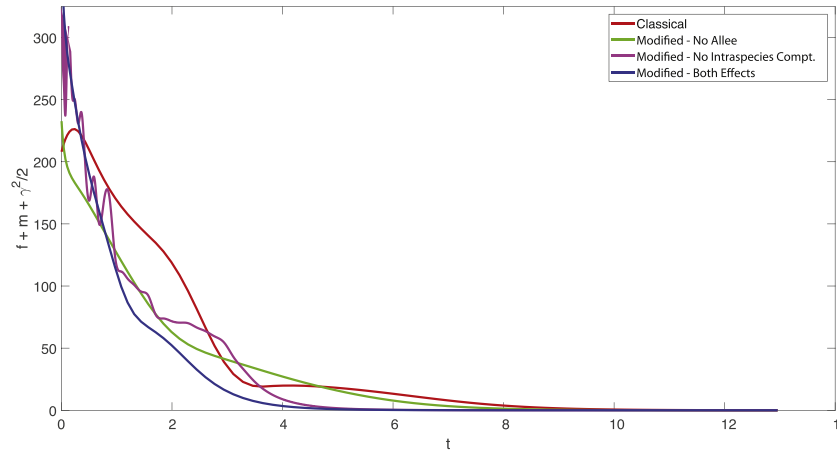


Fig. 5. A plot of the integrands of the objective functions, $f + m + \frac{\gamma^2}{2}$, for the classical (red), model with intraspecies competition but no Allee effect (green), model with Allee effect but no intraspecies competition (magenta), and the modified model including both effects (blue). We notice that the area under the curve for the modified model that includes both effects is less than that of each of the other situations, in particular the classical case. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

3.3. Stochastic model & sensitivity analysis

There are numerous environmental influences that may cause perturbations to the birth and death rates of the invasive species. Here, we assume that β and δ fluctuate around average values (Gray et al., 2011; Zhang and Men, 2018). Therefore, the birth and death rates may be treated as random variables such that $\beta \mapsto \beta + \sigma_\beta \dot{W}_\beta$ and $\delta \mapsto \delta + \sigma_\delta \dot{W}_\delta$ (Zhang and Men, 2018), namely,

$$df = \left(\beta L \left(\frac{f}{\alpha} - 1 \right) \left(\frac{m}{m+s} \right) fm - \delta f \right) dt + \sigma_\beta \left(\frac{f}{\alpha} - 1 \right) \left(\frac{m}{m+s} \right) f m dW_\beta - \sigma_\delta f dW_\delta \quad (12)$$

$$dm = \left(\beta \frac{Lf}{m+s} \left(\frac{f}{\alpha} - 1 \right) (m^2 + 2s^2) - \delta m \right) dt + \sigma_\beta \frac{Lf}{m+s} \left(\frac{f}{\alpha} - 1 \right) (m^2 + 2s^2) dW_\beta - \sigma_\delta m dW_\delta \quad (13)$$

$$ds = (\mu - \delta s) dt - \sigma_\delta s dW_\delta \quad (14)$$

where W_β and W_δ are independent Brownian motions with intensities σ_β and σ_δ , respectively.

Here, we examine the influence of noise on the objective value in simulations with the optimal control given Fig. 5. The noise on the

birth, $d\beta$, and death, $d\delta$, rates are taken from a normal distribution. An Euler–Maruyama method is employed to determine a numerical solution to the stochastic model. In each simulation we determine the objective function value (Eq. (11)) and compare the percent difference between the objective function value determined in the case of no noise. The results for increasing percent noise are shown in Fig. 7. A linear regression through the bounds of 95% confidence intervals at each noise level is shown as a reference. Notice, that for large amount of noise in the death and birth rates that the objective function is no more than 8% away from the no noise situation. The slopes of the upper and lower 95% confidence intervals are relatively small and, subsequently, means that the value of objective function is changed only slightly for perturbations in the birth and death rates. This provides experimental evidence that the determined optimal introduction rate is fairly robust to noise or perturbations to the death and birth rates.

4. Conclusions and future work

The mathematical analysis and improvement of models of the TYC eradication strategy are essential to understanding the efficacy of the strategy as a control. This is especially important in light of recent field studies of reproductivity and survivability of introduced Trojan supermale populations of brook trout (*Salvelinus fontinalis*), in the Big Lost River basin in south-central Idaho (Kennedy et al., 2018).

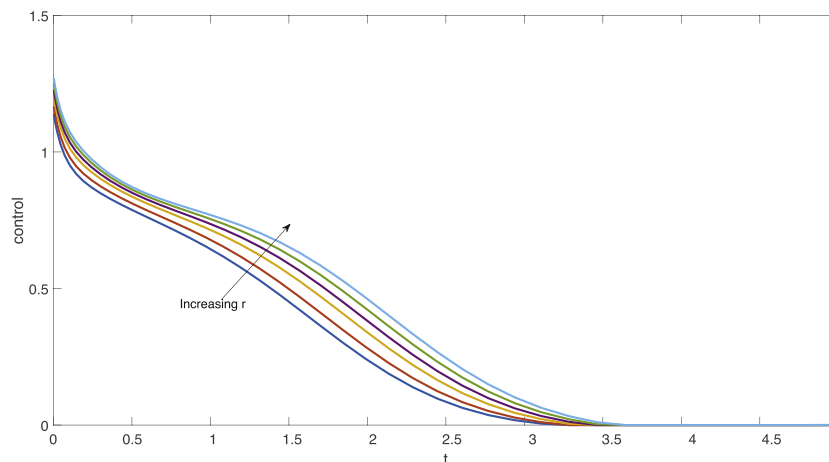


Fig. 6. A plot of the optimal controls for increasing r on the interval $[15, 21]$.

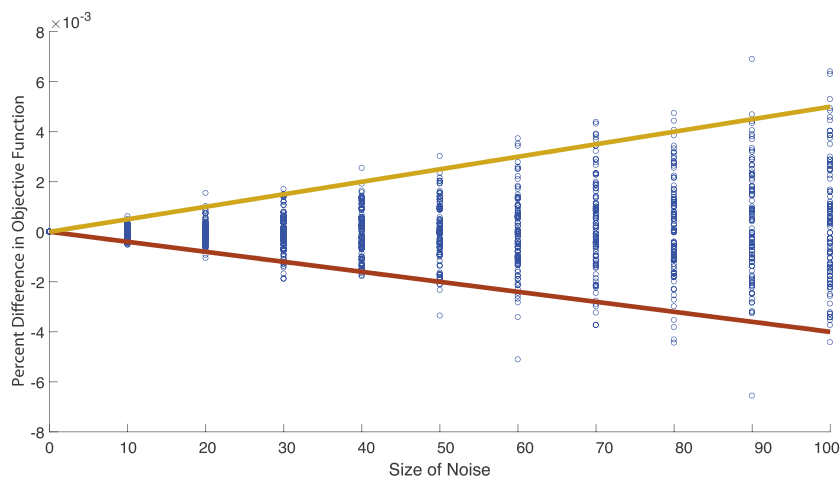


Fig. 7. A plot of numerical simulations for increasing size of noise ranging from 0–100%. A linear regression is shown for the upper (yellow) and lower (red) 95% confidence interval. The slopes for the upper and lower confidence levels are .00052 and $-.00049$, respectively. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

In this paper, a modification to the classical model of the TYC strategy is proposed that includes intraspecific competition between males and supermales for female mates and a strong Allee effect in the female population. It is shown that the dynamical system may exhibit an extinction and recovery equilibrium solutions for realistic parameter values of the carrying capacity and birth and death rates. In such case, the equilibrium solutions are shown to be asymptotically stable and hence the goal of an effective TYC strategy is to *push* the wild-type populations toward the basin of attraction of the extinction state.

An optimal introduction rate of supermales is determined through optimal control theory and was chosen to minimize an objective function that measures the total amount of wild population and introduced supermales. The optimal introduction rate for the classical model was given in [Lyu et al. \(2019\)](#). Here, we compare the influence of including the intraspecific competition for mates and the Allee effect on the optimal introduction rate. It is determined that the optimal introduction rate yields a significantly smaller objective function value as compared to the classical model. This suggests that it is important to include intraspecific competition and the Allee effect to appropriately determine the overall cost of the TYC eradication strategy. In addition, this indicates that the overall cost of the strategy is smaller than previously predicted ([Lyu et al., 2019](#)). Lastly, a stochastic model is proposed to investigate the influence of noise in the birth and death rates on the objective function's value. These results show the sensitivity in the objective function's value in light of perturbations to the birth and death rates. Numerical results indicate that the optimal introduction rate is indeed robust to noise in the birth and death rate. Hence, the optimal introduction rate is not greatly influenced by noise or perturbations in death and birth rates.

Conflicts of interest

The authors declare no conflicts of interest.

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