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Quantile Co-Movement in Financial Markets: A Panel Quantile Model With Unobserved Heterogeneity

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ABSTRACT

This article introduces a new procedure for analyzing the quantile co-movement of a large number of financial time series based on a large-scale panel data model with factor structures. The proposed method attempts to capture the unobservable heterogeneity of each of the financial time series based on sensitivity to explanatory variables and to the unobservable factor structure. In our model, the dimension of the common factor structure varies across quantiles, and the explanatory variables is allowed to depend on the factor structure. The proposed method allows for both cross-sectional and serial dependence, and heteroscedasticity, which are common in financial markets.

We propose new estimation procedures for both frequentist and Bayesian frameworks. Consistency and asymptotic normality of the proposed estimator are established. We also propose a new model selection criterion for determining the number of common factors together with theoretical support.

We apply the method to analyze the returns for over 6000 international stocks from over 60 countries during the subprime crisis, European sovereign debt crisis, and subsequent period. The empirical analysis indicates that the common factor structure varies across quantiles. We find that the common factors for the quantiles and the common factors for the mean are different. Supplementary materials for this article are available online.

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1. Introduction


The goal of this article is to develop a new statistical method for analyzing the quantile co-movement of a large number of financial time series and to empirically investigate the quantile co-movement structure of the global financial market. In the context of the arbitrage pricing theory (APT) of Ross (1976), the first theoretically grounded multifactor model in asset pricing (Goyal et al. 2008), the asset return variation of each security is explained by a linear combination of common factors, which captures the co-movements, plus the idiosyncratic return. A large body of asset pricing literature has considered models that explain expected returns or the mean structure (see, e.g., Fama and French 2016; Griffin 2002; Hou, Karolyi, and Kho 2011, and references therein). However, little is known about the quantile co-movement structure of asset return distributions despite the fact that identifying the sources of co-movement is an important issue in asset pricing and risk management in finance. The chief obstacle to this investigation is that common factors that capture the quantile structure of asset returns may not be measurable/accessible in practice. Ideally, one would directly use measurable/accessible factors, such as Fama and French's (1993) three factors. However, in reality, even for explaining expected asset returns, there is limited access to all common factors (Ando and Bai 2015). Econometric methods for analyzing the quantile co-movement of a large number of financial time series and the effects of common factors on the asset return

distribution, rather than the mean, remain limited. The U.S. subprime crisis of 2007 led to massive declines in global financial markets, which subsequently affected economic activities worldwide. The Dow Jones Industrial Average hit the bottom in April 2009; the long-term interest rates of Euro zone countries started to increase at the end of 2009, the onset of the European sovereign debt crisis. From the perspective of governmental policy, regulators, and asset management, it is important to understand the quantile co-movement structure during such extreme events. Similar to asset pricing studies that search for factors that explain the co-movement of expected returns in global stock markets (Fama and French 1998; Heston, Steven, and Rouwenhorst 1994; Griffin 2002; Hou, Karolyi, and Kho 2011), it is worthwhile to identify the determinants of the quantile co-movement structure of the global financial market. By analyzing a large number of stock returns in the financial industry stock, this article seeks to answer the following empirical questions.

1. Do the quantile common-factor structures that explain the asset-return distribution vary across quantiles?
2. Are the quantile common-factor structures symmetric in the sense that their structures in the lower tails and the upper tails are identical?
3. Are the quantile common-factor structures in the tails and at the mean different?
4. Are the co-movements of quantiles captured by the stock's listed exchange and industry?

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5. Are there any special characteristics of the quantile structures of financial markets during the recent financial crisis and European sovereign debt crisis compared with the subsequent period?

To address these important but challenging empirical questions, we introduce a new heterogeneous panel quantile model with factor structures, in which a few unobservable factors may explain the co-movement of the asset return distributions in a large number of asset returns. Quantile regression methods have been previously used to model financial data (Engle and Manganelli 2004; Baur 2013; Baur, Dimpfl, and Jung 2012; Chuang, Kuan, and Lin 2009; Cappiello et al. 2014; Chen 2015; So and Chung 2015; Gerlach, Chen, and Lin 2016; Chen et al. 2017; Han et al. 2016). In this article, we consider large-scale panel data that consist of a large number of asset return time series. There is a growing number of studies on panel quantile models (see Koenker 2004; Abrevaya and Dahl 2008; Lamarche 2010; Kato, Galvao, and Montes-Rojas 2012; Harding and Lamarche 2014; Chen, Dolado, and Gonzalo 2017, among others). In particular, we introduce a new panel data model with heterogeneous regression coefficients, which has many attractive features that are lacking in those used in the above studies. First, the heterogeneity of asset returns is captured by using heterogeneous regression coefficients and a factor error structure. Second, observable factors can depend on the unobservable common factors, factor loadings or both. Third, the unobservable common factors are allowed to vary across quantiles. The model is formulated without imposing any parametric family of distributions. We note that this is the first study that introduces and analyzes such a general model.

If we can ignore the unobservable common factor structures, then the estimator of the regression coefficient can be found by running the standard quantile regression approach equation by equation. However, the model allows the explanatory variables depend on the unobservable effects. If the unobservable common factor structure exists and is ignored, which implies ignoring possible endogeneity, then the standard quantile regression approach produces biased results. Indeed, our simulation study indicates that failing to account for endogeneity increases the bias of the estimation. Even if the true regression coefficients are zero, a direct application of the principal component approach in the quantile panel model may yield inconsistent estimation of the unobservable factor structure (Chen et al. 2017).

In the case of mean panel data models with factor structures, the inference procedure is well studied. Indeed, one can employ various estimation procedures, including Bai (2009) for homogeneous panels, Song (2013) for heterogeneous panels, and Ando and Bai (2015) for heterogeneous panels with shrinkage. However, these estimation procedures cannot be applied to the panel quantile models with interactive effects. Although some studies on nonlinear panel studies are available (Freyberger 2015; Chen et al. 2014; Fernández-Val and Weidner 2016), these studies focused on smoothed objective functions and homogeneous coefficients, and thus are not directly applicable to our settings. Furthermore, our model allows for a large number of parameters.

To overcome this issue, we propose new estimation procedures for both a frequentist and Bayesian framework. For fre-

quentist estimation, the proposed algorithm converges quickly to a local minimizer. In a standard Bayesian quantile regression for cross-sectional data, Markov chain Monte Carlo (MCMC) is commonly employed. Assuming the asymmetric Laplace distribution for the error term, the MCMC posterior sampling procedure is well studied (Yu and Moyeed 2001; Geraci and Bottai 2007; Yue and Rue 2011; Alhamzawi and Yu 2013; Chen and Gerlach 2013). However, these studies ignored the issue of “endogeneity,” where the set of regressors are correlated with the error terms. Although Lancaster and Jun (2010) studied the Bayesian estimation of the quantile regression model with endogeneity, their study addresses cross-sectional data and a borrowed Bayesian exponentially tilted empirical likelihood framework. Obviously, these studies on MCMC for estimating the cross-sectional quantile regression model can not be easily extended to estimate panel quantile regression models with interactive fixed effects. There are no studies that consider the Bayesian MCMC procedure for estimating the panel quantile regression models with interactive fixed effects. This is the first study to investigate a data-augmentation approach to the analysis of panel quantile regression models with endogeneity. We develop a data-augmentation strategy without imposing any probability distributions on the error term. We demonstrate that our method will greatly simplify inference on the unobservable factor structure. Our Monte Carlo simulation study shows that the proposed procedure improves the estimation accuracy of the underlying quantile structures in the presence of interactive fixed effects.

In practical applications, the number of common factors should be determined. We note that previous studies (including Ahn and Horenstein 2013; Ando and Bai 2016, 2017; Bai and Ng 2002; Hallin and Liška 2007; Onatski 2009) cannot be applied directly because these methods were designed for panel “mean” regression models with factor structures instead of panel “quantile” models. As there are no studies that allow us to determine the number of common factors, this issue is not straightforward. We propose a new information criterion for selecting the number of common factors. Our simulation study indicates that the proposed information criterion is capable of selecting the true dimension of the common factors.

We make further theoretical contributions by developing an asymptotic theory for the proposed estimator. We establish the consistency and the asymptotic normality of the estimator. We also establish the model selection consistency of the information criterion in determining the number of common factors. In our asymptotic framework, the time series dimension and individual dimension are diverging. Due to the presence of the unobservable common factor structures and nonsmoothness of the quantile loss function, the development of these results is nontrivial. Therefore, we need a novel strategy for the proof.

In summary, our contributions are as follows. First, a novel panel heterogeneous quantile model with a factor structure is introduced. Second, new estimation procedures are developed for the simultaneous estimation of heterogeneous regression coefficients and the factor structures. Third, the consistency and asymptotic normality of the proposed frequentist estimator are established. Fourth, a novel information criterion for determining the number of common factors is proposed together with theoretical supports. Finally, these new results are applied

to investigate the quantile co-movement structure of global financial markets. In contrast to Ando and Bai (2017), which focused on the subprime crisis period, we compared the quantile structures of the subprime crisis period, European sovereign debt crisis period, and the subsequent period. As a result, a number of interesting findings are obtained. It is found that quantile common-factor structures in the tails and at the mean are different. Because Ando and Bai's (2017) method is designed for exploring the mean structures, this article complements Ando and Bai (2017) as it provides a useful tool for exploring the quantile structures.

The remainder of this article is organized as follows. Section 2 introduces a new panel quantile model with a factor structure and its assumptions. Section 3 develops the parameter estimation procedures. Section 4 proposes the new information criterion for determining the number of common factors. Section 5 investigates the consistency and the asymptotic distribution of the estimator. Section 6 applies the procedure to the analysis of global stock market data. Concluding remarks are provided in Section 7. To save space, all technical proofs of the theoretical results and Monte Carlo simulations are provided in the online supplementary materials.

2. Panel Quantile Regression With Interactive Fixed Effects

2.1. The Model

Suppose that the response of an individual unit is measured over T time periods together with some observable regressors. For the i th unit ($i = 1, \dots, N$), at time t , its response y_{it} is observed together with a $(p+1)$ -dimensional vector of observable regressors $\mathbf{x}_{it} = (1, x_{it,1}, \dots, x_{it,p})'$. We consider the following model for the τ th conditional quantile function of the response y_{it} :

$$Q_{y_{it}}(\tau | \mathbf{x}_{it}, \mathbf{f}_{t,\tau}, \boldsymbol{\lambda}_{i,\tau}) \equiv \mathbf{x}_{it}' \mathbf{b}_{i,\tau} + \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}, \quad i = 1, \dots, N, t = 1, \dots, T, \quad (1)$$

where $\mathbf{b}_{i,\tau} = (b_{i,0,\tau}, b_{i,1,\tau}, \dots, b_{i,p,\tau})'$ is a $(p+1)$ -dimensional vector of regression coefficients, where $\mathbf{f}_{t,\tau}$ is an $r_\tau \times 1$ vector of unobservable factors and $\boldsymbol{\lambda}_{i,\tau}$ represents the unobservable factor loadings. Throughout the article, we treat the true unobservable structure $\mathbf{f}_{t,\tau}$ and $\boldsymbol{\lambda}_{i,\tau}$ as fixed parameters. For notational simplicity, we often write $\eta_{it,\tau} = \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}$. This unobservable factor structure is known as the interactive effect in the econometric literature (e.g., Bai 2009) and employed in asset pricing (e.g., Ando and Bai 2017). This interactive effect provides a convenient way of modeling the cross-sectional dependence of asset returns. If we specify the dimension of the unobservable factor as $r_\tau = 1$ and the corresponding factor loading is constant over all possible τ , model (1) reduces to panel quantile regression models with individual fixed effects (Koenker 2004; Kato, Galvao, and Montes-Rojas 2012). In contrast to these studies, model (1) allows the dimension of unobservable factor $\mathbf{f}_{t,\tau}$ to depend on quantile τ .

Here are some examples. The first example is an interactive effect model in the mean, $y_{it} = \mathbf{x}_{it}' \mathbf{b}_i + \mathbf{f}_t' \boldsymbol{\lambda}_i + \varepsilon_{it}$, where ε_{it} are independent over i , but are iid over t . Also, ε_{it} are independent of $\{\mathbf{x}_{it}, \mathbf{f}_t, \boldsymbol{\lambda}_i\}$. Let $q_i(\tau)$ be the τ th quantile of ε_{it} , then,

$$Q_{y_{it}}(\tau | \mathbf{x}_{it}, \mathbf{f}_t, \boldsymbol{\lambda}_i) = \mathbf{x}_{it}' \mathbf{b}_i + \mathbf{f}_t' \boldsymbol{\lambda}_i + q_i(\tau).$$

We can absorb $q_i(\tau)$ into the coefficient of the constant regressor. Next, consider $y_{it} = \mathbf{x}_{it}' \mathbf{b}_i(u_{it}) + \mathbf{f}_t' \boldsymbol{\lambda}_i$, where u_{it} are iid $U(0, 1)$, independent of $\{\mathbf{x}_{it}, \mathbf{f}_t, \boldsymbol{\lambda}_i\}$. Also, assume $\mathbf{x}_{it}' \mathbf{b}_i(u_{it})$ is increasing in u_{it} . Then,

$$Q_{y_{it}}(\tau | \mathbf{x}_{it}, \mathbf{f}_t, \boldsymbol{\lambda}_i) = \mathbf{x}_{it}' \mathbf{b}_i(\tau) + \mathbf{f}_t' \boldsymbol{\lambda}_i.$$

The quantile literature treats $\mathbf{b}_i(\tau)$ as a nonrandom function of τ , and is interested in estimating this function. Finally, consider $y_{it} = \mathbf{x}_{it}' \mathbf{b}_i(u_{it}) + \mathbf{f}_t(u_{it})' \boldsymbol{\lambda}_i(u_{it})$, where u_{it} is $U(0, 1)$, independent of \mathbf{x}_{it} . Also, assume that the right hand side of y_{it} is increasing in u_{it} (see Koenker 2005 for quantile regression models expressed as functions of uniform random variables), then

$$Q_{y_{it}}(\tau | \mathbf{x}_{it}, \mathbf{f}_t(\tau), \boldsymbol{\lambda}_i(\tau)) = \mathbf{x}_{it}' \mathbf{b}_i(\tau) + \mathbf{f}_t(\tau)' \boldsymbol{\lambda}_i(\tau).$$

Define the error term $\varepsilon_{it,\tau} \equiv y_{it} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau} - \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}$, then $P(\varepsilon_{it,\tau} \leq 0 | \mathbf{x}_{it}, \mathbf{f}_{t,\tau}, \boldsymbol{\lambda}_{i,\tau}) = \tau$. Our purpose is to estimate the unknown conditional quantile function $Q_{y_{it}}(\tau | \mathbf{x}_{it}, \mathbf{f}_{t,\tau}, \boldsymbol{\lambda}_{i,\tau})$ based on the observations $\{(y_{it}, \mathbf{x}_{it}); i = 1, \dots, N, t = 1, \dots, T\}$.

If one ignores the unobservable effects ($\eta_{it,\tau} = 0$), the quantile estimator of $\mathbf{b}_{i,\tau}$ ($i = 1, \dots, N$) is found as the minimizer of the standard quantile loss function:

$$\ell_\tau(Y | X, B_\tau) = \sum_{i=1}^N \sum_{t=1}^T \rho_\tau(y_{it} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau}), \quad (2)$$

where $\rho_\tau(u) = u(\tau - I(u < 0))$ is the quantile loss function, $Y \equiv \{y_{it} | i = 1, \dots, N, t = 1, \dots, T\}$, $X \equiv \{\mathbf{x}_{it} | i = 1, \dots, N, t = 1, \dots, T\}$ and $B_\tau = \{\mathbf{b}_{1,\tau}, \dots, \mathbf{b}_{N,\tau}\}$.

However, if the factor structure exists and is ignored, the estimator of B_τ in the above is biased (see Section 5 and the Monte Carlo simulation result). This is because, similar to Koenker (2004) and Kato, Galvao, and Montes-Rojas (2012), we allow the observables \mathbf{x}_{it} depend on the unobservable effects $\eta_{it,\tau}$ (existence of endogeneity). In such a case, we have to estimate the unknown parameters $B_\tau, \Lambda_\tau = (\boldsymbol{\lambda}_{1,\tau}, \dots, \boldsymbol{\lambda}_{N,\tau})'$, and $F_\tau = (\mathbf{f}_{1,\tau}, \dots, \mathbf{f}_{T,\tau})'$ by simultaneously minimizing the following objective function

$$\ell_\tau(Y | X, B_\tau, F_\tau, \Lambda_\tau) = \sum_{i=1}^N \sum_{t=1}^T \rho_\tau(y_{it} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau} - \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}). \quad (3)$$

A new parameter estimation procedure is proposed in Section 3. Because the likelihood function is nonlinear in the factor structure, inference on interactive fixed effects in model (1) is a challenging problem.

There are several past studies relating to our proposed model (1). Ando and Tsay (2011) consider a quantile regression model with factor-augmented predictors. In their study, the common factors that explain the quantile structure are also allowed to vary across quantiles τ . In contrast to our study, however, their study is about the modeling of a quantile structure in the cross-sectional context. Harding and Lamarche (2014) consider a quantile regression model with interactive effects. In contrast to the heterogeneous regression coefficients in Equation (1), their model only allows homogeneous regression coefficients. Moreover, in their setup, the common factor structure is not allowed to vary across quantiles. When we set the heterogeneous regression coefficients as $\mathbf{b}_{i,\tau} = \mathbf{0}$ for $i = 1, \dots, N$, the

model becomes similar to the quantile factor model of Chen et al. (2017) in the sense that the common factors vary across quantiles. We note that the parameter estimation procedure in model (1) becomes more complicated due to the existence of the term $\mathbf{x}'_{it}\mathbf{b}_{i,\tau}$. Furthermore, the investigation of asymptotic theory becomes challenging; the convergence rate for the estimated common factor structures and the convergence rate for the estimated regression coefficients depend on one another.

Remark 1. Past empirical studies (e.g., Nath and Brooks 2015; Ni, Wang, and Xue 2015) indicated that a set of important (observable) common factors vary with τ . Thus, it is ideal to formulate model (1) so that unobservable common factors vary with quantile points τ because its dimension is often unknown for each τ in practice.

Before, we propose the novel estimation procedures and the asymptotic theory, the set of assumptions on the model is clarified in the next section.

2.2. Assumptions

We first define some notations. Let $\|A\| = [\text{tr}(A'A)]^{1/2}$ be the usual norm of the matrix A , where “tr” denotes the trace of a square matrix. The equation $a_n = O(b_n)$ states that the deterministic sequence a_n is at most of order b_n ; $c_n = O_p(d_n)$ states that the random variable c_n is at most of order d_n in terms of probability and $c_n = o_p(d_n)$ is of a smaller order in terms of probability. The true regression coefficient is denoted by $\mathbf{b}_{i,0,\tau}$. Further, $F_{0,\tau} = (\mathbf{f}_{1,0,\tau}, \dots, \mathbf{f}_{T,0,\tau})'$ and $\Lambda_{0,\tau} = (\boldsymbol{\lambda}_{1,0,\tau}, \dots, \boldsymbol{\lambda}_{N,0,\tau})'$ are the true common factor and its factor loadings. The set of regularity conditions that are imposed on the proposed model are as follows:

Assumption A. Common Factors

Let \mathcal{F} be a compact subset of R^{r_τ} . The common factors $\mathbf{f}_{t,0,\tau} \in \mathcal{F}$ satisfy $T^{-1} \sum_{t=1}^T \mathbf{f}_{t,0,\tau} \mathbf{f}_{t,0,\tau}' \rightarrow \Sigma_{F_\tau}$ as $T \rightarrow \infty$, where Σ_{F_τ} is an $r_\tau \times r_\tau$ positive definite matrix.

Assumption B. Factor Loadings and Regression Coefficients

Let \mathcal{B} and \mathcal{L} be compact subsets R^{p+1} and R^{r_τ} . The regression coefficient $\mathbf{b}_{i,0,\tau}$ and the factor-loading for the common factors satisfy $\mathbf{b}_{i,0,\tau} \in \mathcal{B}$ and $\boldsymbol{\lambda}_{i,0,\tau} \in \mathcal{L}$. In addition, the factor-loading matrix $\Lambda_{0,\tau} = (\boldsymbol{\lambda}_{1,0,\tau}, \dots, \boldsymbol{\lambda}_{N,0,\tau})'$ satisfies $N^{-1} \Lambda_{0,\tau}' \Lambda_{0,\tau}$ being a $r_\tau \times r_\tau$ positive definite matrix for all N .

Assumption C. Idiosyncratic Error Terms

(C1): The random variable $\varepsilon_{it,\tau} = y_{it} - \mathbf{x}'_{it}\mathbf{b}_{i,0,\tau} - \mathbf{f}'_{t,0,\tau}\boldsymbol{\lambda}_{i,0,\tau}$ is independently distributed over i and t , conditional on X , $F_{0,\tau}$ and $\Lambda_{0,\tau}$. In addition, it satisfies $E[|\varepsilon_{it,\tau} - E[\varepsilon_{it,\tau}]|^K] < K!C_\varepsilon^K$ for $K \geq 1$ and positive constant $C_\varepsilon < \infty$.

(C2): The conditional density function of $\varepsilon_{it,\tau}$ given $(\mathbf{x}_{it}, \mathbf{f}_{t,0,\tau}, \boldsymbol{\lambda}_{i,0,\tau})$, denoted as $g_{it}(\varepsilon_{it,\tau} | \mathbf{x}_{it}, \mathbf{f}_{t,0,\tau}, \boldsymbol{\lambda}_{i,0,\tau})$, is continuous. In addition, for any compact set \mathcal{C} , there exists a positive constant $\bar{g} > 0$ (depending on \mathcal{C}) such that $\inf_{c \in \mathcal{C}} g_{it}(c | \mathbf{x}_{it}, \mathbf{f}_{t,0,\tau}, \boldsymbol{\lambda}_{i,0,\tau}) \geq \bar{g}$ for all i and t .

Assumption D. Predictors and Design Matrix

(D1): For a positive constant C_x , predictors satisfy $\sup_{it} \|\mathbf{x}_{it}\| < C_x < \infty$.
(D2): There exist positive constants C_1 and C_2 such that for each X_i ,

$$0 < C_1 < \lambda_{\min}(T^{-1}(X_i, F_{0,\tau})'(X_i, F_{0,\tau})) < \lambda_{\max}(T^{-1}(X_i, F_{0,\tau})'(X_i, F_{0,\tau})) < C_2 < \infty,$$

where $X_i = (\mathbf{x}_{i1}, \dots, \mathbf{x}_{iT})'$, $\lambda_{\min}(A)$ and $\lambda_{\max}(A)$ denote the smallest and the largest eigenvalue of a matrix A , respectively. These inequalities hold with probability one as T approaches infinity.

(D3): Define $A_{i,\tau} = \frac{1}{T} X_i' M_{F_\tau} X_i$, $B_{i,\tau} = (\boldsymbol{\lambda}_{i,0,\tau} \boldsymbol{\lambda}_{i,0,\tau}' \otimes I_T, C_{i,\tau}' = \frac{1}{\sqrt{T}} \boldsymbol{\lambda}_{i,0,\tau}' \otimes (X_i' M_{F_\tau}))$, $M_{F_\tau} = I - F_\tau (F_\tau' F_\tau)^{-1} F_\tau'$. Let \mathcal{F}_τ be the collection of F_τ such that $\mathcal{F}_\tau = \{F_\tau : F_\tau' F_\tau / T = I\}$. We assume

$$\inf_{F_\tau \in \mathcal{F}_\tau} \lambda_{\min} \left[\frac{1}{N} \sum_{i=1}^N E_{i,\tau}(F_\tau) \right] > 0, \quad (4)$$

where $E_{i,\tau}(F_\tau) = B_{i,\tau} - C_{i,\tau}' A_{i,\tau}^{-1} C_{i,\tau}$ and inf is taken under the fixed τ which is the focus.

Remark 2. The full rank assumption in Assumptions A and B is necessary for the number of common factors to be r_τ . In Assumption C, heteroscedasticity is allowed. Although it is outside the scope of this article, the errors can have serial correlation. In such a case, it will require more technical conditions such as those in Bai (2009). Assumption D imposes the regularity condition on design matrix X_i and common factor structure $F_{0,\tau}$. (D2) is the usual rank condition for identification. (D3) is similar to that used in Ando and Bai (2015) and Song (2013). Similar to Belloni and Chernozhukov (2011), Wang et al. (2012), Tang et al. (2013), and Sherwood and Wang (2016), the quantile function under a particular τ is focused rather than the entire quantile function over all possible τ . When the entire quantile function is focused, there are studies that try to ensure the monotonicity of the quantile function as a function of τ , for example, He (1997), Bondell, Reich, and Wang (2010), Dette and Volgushev (2008), Chernozhukov, Fernández-Val, and Galichon (2010), and Yuan, Chen, and Zhou (2017). It is known that if non-crossing is required in linear quantile regression on an unbounded domain in any covariate direction, the quantile function results in the constant slope, location-shift model (Bondell, Reich, and Wang 2010). Therefore, we consider a compact space for \mathbf{x}_{it} , $\mathbf{f}_{t,0,\tau}$, and $\boldsymbol{\lambda}_{i,0,\tau}$ in the assumptions.

3. Estimation

We begin by presenting the reason for which parameters B_τ , F_τ , and Λ_τ should be estimated simultaneously. One might consider a two-step procedure to estimate the model parameters. In the first step, the principal component analysis (see, e.g., Bai 2003; Connor and Korajczyk 1986) is applied to build the common factors. Plugging these estimated common factors into $\ell_\tau(Y|X, B_\tau, F_\tau, \Lambda_\tau)$ in Equation (3), the second step jointly estimates the regression coefficients and factor loadings. However, as discussed in Chen, Dolado, and Gonzalo (2017)

for pure factor models, when there exist common factors that affect the quantiles but not the means, the two-step procedure may result in inconsistent estimators due to the omission of important common factors in the second step purely because the principal component estimator cannot always expand the true common factor space for implementing the second step. Indeed, our empirical analysis indicates that there exist common factors that affect the quantiles but not the means. Therefore, the factor-augmented approach to quantile regression (Ando and Tsay 2011) may not work, and the simultaneous direct minimization of $\ell_\tau(Y|X, B_\tau, F_\tau, \Lambda_\tau)$ in terms of B_τ, F_τ and Λ_τ is important. In Section 3.1, the frequentist estimation procedure is developed. We also propose the novel data-augmentation strategy in Section 3.2.

3.1. Frequentist Estimation

Note that one cannot separately identify F_τ and Λ_τ without further restrictions because they enter the model in a multiplicative way. Following Bai and Ng (2013), we impose the following restrictions $F'_\tau F_\tau / T = I_{r_\tau}$ and $\Lambda'_\tau = (\Lambda'_{1,\tau}, \Lambda'_{2,\tau})'$, with $\Lambda_{1,\tau}$ being an invertible lower triangular matrix. Bai and Ng (2013) demonstrate that this restriction will lead to the identification of F_τ and Λ_τ . We refer to Bai and Ng (2002, 2013) and Stock and Watson (2002) for the identification of the principal component estimator for the mean panel data model. Then, the frequentist estimator is obtained by minimizing the following objective function $\ell_\tau(Y|X, B_\tau, F_\tau, \Lambda_\tau)$ in Equation (3) under the restriction.

Given values of τ and the number of common factors r_τ , the following algorithm can be used to obtain the frequentist estimator.

Estimation Algorithm:

- Step 1. Initialize parameters $\hat{B}_\tau, \hat{F}_\tau$, and $\hat{\Lambda}_\tau$.
- Step 2. Given \hat{F}_τ , update $\hat{b}_{i,\tau}$ and $\hat{\lambda}_{i,\tau}$ as the minimizer of $\sum_{t=1}^T \rho_\tau(y_{it} - \mathbf{x}'_{it} \hat{b}_{i,\tau} - \hat{f}'_{t,\tau} \hat{\lambda}_{i,\tau})$ for $i = 1, \dots, N$.
- Step 3. Given $\hat{b}_{i,\tau}$ and $\hat{\lambda}_{i,\tau}$ ($i = 1, \dots, N$), update $\hat{f}_{t,\tau}$ as the minimizer of $\sum_{i=1}^N \rho_\tau(y_{it} - \mathbf{x}'_{it} \hat{b}_{i,\tau} - \hat{f}'_{t,\tau} \hat{\lambda}_{i,\tau})$ for $t = 1, \dots, T$.
- Step 4. Obtain a QR decomposition of \hat{F}_τ to yield $\hat{F}_\tau = \bar{Q}_\tau^F \bar{R}_\tau^F$, where \bar{R}_τ^F is an upper triangular matrix with positive diagonal elements and \bar{Q}_τ^F is a $T \times r_\tau$ orthogonal matrix such that $\bar{Q}_\tau^{F'} \bar{Q}_\tau^F = I_{r_\tau}$. Then, obtain a QR decomposition of $\bar{R}_\tau^F \hat{\Lambda}_\tau'$, to yield $\bar{R}_\tau^F \hat{\Lambda}_\tau' = \bar{Q}_\tau^\Lambda \bar{R}_\tau^\Lambda$. Here, \bar{R}_τ^Λ is an upper triangular matrix with positive diagonal elements, and \bar{Q}_τ^Λ is an $r_\tau \times r_\tau$ orthogonal matrix such that $\bar{Q}_\tau^{\Lambda'} \bar{Q}_\tau^\Lambda = I_{r_\tau}$. Update the common factor \hat{F}_τ and the factor loading matrix $\hat{\Lambda}_\tau$ as $\hat{F}_\tau = \sqrt{T} \bar{Q}_\tau^F \bar{Q}_\tau^\Lambda$ and $\hat{\Lambda}_\tau' = \bar{R}_\tau^\Lambda$, respectively.
- Step 5. Repeat Step 2 to Step 4 until convergence.

In Step 1, the initial values of parameters are prepared as follows. First, estimate $\mathbf{b}_{i,\tau}$ ($i = 1, \dots, N$) by minimizing $\ell_\tau(Y|X, B_\tau)$ in Equation (2). Given $\hat{\mathbf{b}}_{i,\tau}$ ($i = 1, \dots, N$), define the variable $Z_\tau = (z_{1,\tau}, \dots, z_{N,\tau})'$ with $z_{i,\tau} = y_i - X_i \hat{\mathbf{b}}_{i,\tau}$. Obtain the principal components' estimate of $\hat{F}_\tau = (\hat{f}_{1,\tau}, \dots, \hat{f}_{T,\tau})'$,

subject to the normalization $F'_\tau F_\tau / T = I_{r_\tau}$, which is \sqrt{T} times the eigenvectors corresponding to the r_τ largest eigenvalues of the $T \times T$ matrix $Z'_\tau Z_\tau$ (see Bai and Ng 2002). Then, obtain $\hat{\lambda}_{i,\tau}$ as the minimizer of $\sum_{t=1}^T \rho_\tau(y_{it} - \mathbf{x}'_{it} \hat{b}_{i,\tau} - \hat{f}'_{t,\tau} \lambda_{i,\tau})$ for $i = 1, \dots, N$. One can step the iteration based on $N^{-1} \sum_{i=1}^N \|\hat{b}_{i,\tau}^{\text{new}} - \hat{b}_{i,\tau}^{\text{old}}\|^2 + (NT)^{-1} \sum_{i=1}^N \sum_{t=1}^T \{(\hat{f}'_{t,\tau} \hat{\lambda}_{i,\tau})^{\text{new}} - (\hat{f}'_{t,\tau} \hat{\lambda}_{i,\tau})^{\text{old}}\}^2 < \delta^2$, where δ^2 is a small value.

Our simulation study found that the above algorithm converges quickly. Under the fixed F_τ , the loss function $\ell_\tau(Y|X, B_\tau, F_\tau, \Lambda_\tau)$ in Equation (3) is convex in B_τ and Λ_τ . This implies that $\ell_\tau(Y|X, B_\tau^{\text{new}}, F_\tau, \Lambda_\tau^{\text{new}}) \leq \ell_\tau(Y|X, B_\tau^{\text{old}}, F_\tau, \Lambda_\tau^{\text{old}})$. Similarly, given B_τ and Λ_τ , $\ell_\tau(Y|X, B_\tau, F_\tau^{\text{new}}, \Lambda_\tau) \leq \ell_\tau(Y|X, B_\tau, F_\tau^{\text{old}}, \Lambda_\tau)$. Therefore, we have

$$\begin{aligned} \ell_\tau(Y|X, B_\tau^{\text{new}}, F_\tau^{\text{new}}, \Lambda_\tau^{\text{new}}) &\leq \ell_\tau(Y|X, B_\tau^{\text{new}}, F_\tau^{\text{old}}, \Lambda_\tau^{\text{new}}) \\ &\leq \ell_\tau(Y|X, B_\tau^{\text{old}}, F_\tau^{\text{old}}, \Lambda_\tau^{\text{old}}), \end{aligned}$$

which implies that the convergence of the algorithm to a local minimum is guaranteed. As it is pointed out in Bai (2009), the loss function of the panel mean model with interactive effects has multiple modes. Convergence to a global optimum is not guaranteed. This also applies to the present framework. However, under large N and T , the convergence is very quick in our simulations and the converged point appears to be the global optimum as it is very close to the true value. In Section 4, we develop the asymptotic property of the frequentist estimator under large N and T .

Remark 3. This idea of Bai and Ng (2013) is employed in Step 4. We first note that the product $\hat{F}_\tau \hat{\Lambda}_\tau'$ remains the same even when the common factor and the factor loading matrix are rotated (see Bai and Ng 2013). Regarding \hat{F}_τ , we see that $\hat{F}_\tau' \hat{F}_\tau / T = (\sqrt{T} \bar{Q}_\tau^F \bar{Q}_\tau^\Lambda)' (\sqrt{T} \bar{Q}_\tau^F \bar{Q}_\tau^\Lambda) / T = \bar{Q}_\tau^{\Lambda'} \bar{Q}_\tau^\Lambda = I_{r_\tau}$. Furthermore, \bar{R}_τ^Λ is an upper triangular matrix with positive diagonal elements; thus, both \hat{F}_τ and $\hat{\Lambda}_\tau$ in Step 4 satisfy the restriction.

3.2. Data-Augmentation Approach for Bayesian Inference

This section develops the data-augmentation approach for Bayesian inference. To implement the data-augmentation approach, we first define the pseudo likelihood

$$L(Y|X, B_\tau, F_\tau, \Lambda_\tau) = \exp \{-\ell_\tau(Y|X, B_\tau, F_\tau, \Lambda_\tau)\}$$

and specify the prior distribution of the parameters as $\pi(B_\tau, F_\tau, \Lambda_\tau)$. Similar to the frequentist estimator, the prior density $\pi(B_\tau, \Lambda_\tau) \pi(F_\tau)$ accommodates the following identification restriction: $F'_\tau F_\tau / T = I_{r_\tau}$ and $\Lambda'_\tau = (\Lambda'_{1,\tau}, \Lambda'_{2,\tau})'$ with $\Lambda_{1,\tau}$ being an invertible lower triangular matrix.

Note that unlike previous studies on Bayesian inference in quantile regression that use the asymmetric Laplace distribution for the error component (Yu and Moyeed 2001; Geraci and Bottai 2007; Yue and Rue 2011), we develop the data-augmentation strategy without directly imposing probability distributions. Then, the posterior density is $\pi(B_\tau, F_\tau, \Lambda_\tau | Y, X) \propto L(Y|X, F_\tau, \Lambda_\tau, B_\tau) \pi(B_\tau, F_\tau, \Lambda_\tau)$, which does not provide analytical density forms. Note that there is no easy method for sampling from their posterior distribution because the error distribution is unknown.

3.2.1. Data-Augmentation Strategy for F_τ

Because the common factor F_τ is subject to the normalization condition $F_\tau' F_\tau / T = I_{r_\tau}$ for identification purposes, F_τ belongs to a hyperball in T dimensions, and its support is restricted to being the Cartesian product of the T -dimensional hyperball. Furthermore, because of the orthogonality requirement, its support is then reduced to a Stiefel manifold S_{T,r_τ} of radius \sqrt{T} (see, e.g., Khatri and Mardia 1977; Tsay and Ando 2012 and references therein). Thus, the prior of F_τ is a flat prior over the Stiefel manifold

$$\pi(F_\tau) = \frac{1}{C(T, r_\tau)} \cdot 1(F_\tau \in S_{T,r_\tau}), \quad (5)$$

where $1(\cdot)$ is the indicator function and $C(T, k) = 2^k \pi^{kT/2} T^{k(2T-k-1)/4} / \{\pi^{k(k-1)/4} \prod_{j=1}^k \Gamma((T-j+1)/2)\}$ is the normalizing constant with $\Gamma(\cdot)$ being the Gamma function.

To derive the conditional posterior of F_τ , we use the following equality

$$\exp(-\{|\kappa| + (2\tau - 1)\kappa\}) = \int_0^\infty \phi(\kappa | (1 - 2\tau)\omega, \omega) \exp(-2\tau(1 - \tau)\omega) d\omega, \quad (6)$$

where $\phi(x|\mu, \omega)$ is the normal density, evaluated at x , for mean μ and variance ω (see, e.g., Polson and Scott 2013). Using this result, the loss contribution of observation y_{it} can be expressed as

$$\begin{aligned} & \exp(-\{|y_{it} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau} - \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}| + (2\tau - 1) \\ & \quad \{y_{it} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau} - \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}\}\}) \\ & \propto \int_0^\infty \exp\left\{-\frac{\{z_{it,\tau} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau} - \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}\}^2}{2\omega_{it,\tau}}\right\} \\ & \quad \exp\{-2\tau(1 - \tau)\omega_{it,\tau}\} d\omega_{it,\tau}, \end{aligned}$$

where $z_{it,\tau} = y_{it} - (1 - 2\tau)\omega_{it,\tau}$. Combining the terms from all observations yields the following expression for the conditional posterior of F_τ , given $\Omega_\tau \equiv \{\omega_{it,\tau} | i = 1, \dots, N, t = 1, \dots, T\}$:

$$\begin{aligned} & \pi(F_\tau | Y, X, B_\tau, \Lambda_\tau, \Omega_\tau) \\ & \propto \prod_{i=1}^N \prod_{t=1}^T \exp\left\{-\frac{\{z_{it,\tau} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau} - \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}\}^2}{2\omega_{it,\tau}}\right\} \times \pi(F_\tau) \\ & \propto \exp\left\{-\frac{1}{2} \sum_{i=1}^N (\mathbf{z}_{i,\tau}^* - F_\tau \boldsymbol{\lambda}_{i,\tau})' \Omega_{i,\tau}^{-1} (\mathbf{z}_{i,\tau}^* - F_\tau \boldsymbol{\lambda}_{i,\tau})\right\} \quad (7) \\ & \times 1(F_\tau \in S_{T,r_\tau}), \end{aligned}$$

where $\Omega_{i,\tau} = \text{diag}\{\omega_{i1,\tau}, \dots, \omega_{iT,\tau}\}$, $\mathbf{z}_{i,\tau}^* = (z_{i1,\tau}^*, \dots, z_{iT,\tau}^*)'$ with $z_{it,\tau}^* = z_{it,\tau} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau}$.

Because the diagonal matrix $\Omega_{i,\tau}$ prevents the derivation of an analytical conditional posterior of F_τ , further analysis of the conditional posterior of F_τ in Equation (8) is not straightforward. To generate the posterior sample of F_τ , we use the Metropolis-Hastings algorithm, which first draws a candidate parameter value F_τ^{new} from the proposal density $p(F_\tau)$. Then, this generated parameter value F_τ^{new} is accepted or rejected based on the acceptance probability

$$\alpha = \min \left\{ 1, \frac{L(Y|X, F_\tau^{\text{new}}, \Lambda_\tau, B_\tau) \pi(B_\tau, F_\tau^{\text{new}}, \Lambda_\tau) / p(F_\tau^{\text{new}})}{L(Y|X, F_\tau^{\text{old}}, \Lambda_\tau, B_\tau) \pi(B_\tau, F_\tau^{\text{old}}, \Lambda_\tau) / p(F_\tau^{\text{old}})} \right\},$$

where F_τ^{old} is the current state of F_τ .

In the practical implementation of the Metropolis-Hastings algorithm, we draw a new candidate F_τ^{new} from a proposal density. Here, a Bingham-von Mises-Fisher distribution with parameter $Z_\tau^* \Omega_{i,\tau}^{-1} \Lambda_\tau$ is employed for the proposal density. We refer to Hoff (2009) for generating a random matrix from Bingham-von Mises-Fisher distribution.

Remark 4. One can assume that $\varepsilon_{it,\tau} = y_{it} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau} - \eta_{it,\tau}$ follows the asymmetric Laplace distribution or its variants, including Kozumi and Kobayashi (2011) and Yan and Kottas (2015). However, we show that it is possible to estimate the unknown parameters without imposing any probability distribution on $\varepsilon_{it,\tau}$.

3.2.2. Prior Specification and Posterior Analysis of B_τ and Λ_τ

Here, we specify the prior densities on B_τ and Λ_τ and derive their conditional posterior distributions, given F_τ and Ω_τ . For simplicity of notation, we first express the loss contribution of observation y_{it} as

$$\begin{aligned} & \exp(-\{|y_{it} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau} - \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}| + (2\tau - 1) \\ & \quad \{y_{it} - \mathbf{x}_{it}' \mathbf{b}_{i,\tau} - \mathbf{f}_{t,\tau}' \boldsymbol{\lambda}_{i,\tau}\}\}) \\ & \propto \int_0^\infty \exp\left\{-\frac{\{z_{it,\tau} - \mathbf{v}_{it,\tau}' \boldsymbol{\gamma}_{i,\tau}\}^2}{2\omega_{it,\tau}}\right\} \\ & \quad \exp\{-2\tau(1 - \tau)\omega_{it,\tau}\} d\omega_{it,\tau}, \end{aligned}$$

where $\mathbf{v}_{it,\tau} = (\mathbf{x}_{it}', \mathbf{f}_{t,\tau}')'$, and $\boldsymbol{\gamma}_{i,\tau} = (\mathbf{b}_{i,\tau}', \boldsymbol{\lambda}_{i,\tau}')'$.

We recall that the first r_τ factor loading vectors $\boldsymbol{\lambda}_{i,\tau}$ correspond to the invertible lower triangular matrix $\Lambda_{1,\tau}$, which comes from the identification restriction. If some elements of $\boldsymbol{\lambda}_{i,\tau}$ must be zero for identification purposes, we can ignore these elements in the estimation and denote the nonzero elements of $(\mathbf{b}_{i,\tau}', \boldsymbol{\lambda}_{i,\tau}')'$ as $\boldsymbol{\gamma}_{i,\tau}$. For these nonzero elements, we simply use the diffuse prior $\pi(\boldsymbol{\gamma}_{i,\tau}) \propto \text{Const}$. Then, the conditional posterior density of $\boldsymbol{\gamma}_{i,\tau}$ is

$$\begin{aligned} \pi(\boldsymbol{\gamma}_{i,\tau} | Y, X, F_\tau, B_{-i,\tau}, \Lambda_{-i,\tau}, \Omega_\tau) & \propto \exp\left\{-\frac{1}{2} (\mathbf{z}_{i,\tau} - W_{i,\tau} \boldsymbol{\gamma}_{i,\tau})' \right. \\ & \quad \left. \times \Omega_{i,\tau}^{-1} (\mathbf{z}_{i,\tau} - W_{i,\tau} \boldsymbol{\gamma}_{i,\tau})\right\}, \end{aligned}$$

where $W_{i,\tau} = (X_i, F_\tau)$ is the design matrix, $B_{-i,\tau} = (\mathbf{b}_{1,\tau}, \dots, \mathbf{b}_{i-1,\tau}, \mathbf{b}_{i+1,\tau}, \dots, \mathbf{b}_{N,\tau})'$ and $\Lambda_{-i,\tau} = (\boldsymbol{\lambda}_{1,\tau}, \dots, \boldsymbol{\lambda}_{i-1,\tau}, \boldsymbol{\lambda}_{i+1,\tau}, \dots, \boldsymbol{\lambda}_{N,\tau})'$. This implies that the conditional posterior density of $\boldsymbol{\gamma}_{i,\tau}$ is the multivariate normal density with mean $(W_{i,\tau}' \Omega_{i,\tau}^{-1} W_{i,\tau})^{-1} W_{i,\tau}' \Omega_{i,\tau}^{-1} \mathbf{z}_{i,\tau}$ and variance-covariance matrix $(W_{i,\tau}' \Omega_{i,\tau}^{-1} W_{i,\tau})^{-1}$.

Remark 5. When the dimension of \mathbf{x}_{it} is large, one can also use a shrinkage prior on $\boldsymbol{\gamma}_{i,\tau}$, including the lasso prior (Park and Casella 2008) and the adaptive lasso prior (Leng et al. 2014). We can easily derive a conditional posterior distribution of $\boldsymbol{\gamma}_{i,\tau}$ based on these previous results. Or, one may also consider using a procedure for variable screening (He, Wang, and Hong 2013) before applying our data augmentation procedure. However, these directions are outside the scope of this article.

3.2.3. Prior Specification and Posterior Analysis of $\omega_{it,\tau}$

We reexpress the loss contribution of observation y_{it} as

$$\begin{aligned} & \exp\left(-\{y_{it} - \mathbf{x}'_{it}\mathbf{b}_{i,\tau} - \mathbf{f}'_{i,\tau}\boldsymbol{\lambda}_{i,\tau}\}/2 + (\tau - 1/2)\right. \\ & \quad \left.\{y_{it} - \mathbf{x}'_{it}\mathbf{b}_{i,\tau} - \mathbf{f}'_{i,\tau}\boldsymbol{\lambda}_{i,\tau}\}\right) \\ & \propto \int_0^\infty \exp\left\{-\frac{\{a_{it,\tau} - (1 - 2\tau)\omega_{it,\tau}\}^2}{2\omega_{it,\tau}}\right\} \\ & \quad \exp\{-2\tau(1 - \tau)\omega_{it,\tau}\} d\omega_{it,\tau}, \end{aligned}$$

where $a_{it,\tau} = y_{it} - \mathbf{x}'_{it}\mathbf{b}_{i,\tau} - \mathbf{f}'_{i,\tau}\boldsymbol{\lambda}_{i,\tau}$.

Under the uniform prior $\omega_{it,\tau} \propto \text{Const.}$, the conditional posterior density of $\omega_{it,\tau}$ is

$$\pi(\omega_{it,\tau} | Y, X, B_\tau, F_\tau, \Lambda_\tau, \Omega_{-\omega_{it,\tau},\tau}) \propto \exp\left\{-\frac{a_{it,\tau}^2}{2\omega_{it,\tau}} - \frac{\omega_{it,\tau}}{2}\right\},$$

which is the generalized inverse-Gaussian distribution with parameter $(1, a_{it,\tau}, 1)$. Thus, we can easily draw a posterior sample of $\omega_{it,\tau}$ using the Gibbs sampler.

Note that this parameter $\omega_{it,\tau}$ is not included in the model (1). However, by introducing $\omega_{it,\tau}$ in our MCMC posterior sampling, we obtained the conditional posterior of B_τ and Λ_τ analytically. This allows us to use Gibbs sampling, which improves the efficiency of the MCMC algorithm.

3.2.4. Posterior Sampling Scheme

Due to the non-smoothness of the objective function, it was difficult to obtain the conditional posterior of B_τ and Λ_τ analytically without the data augmentation approach. Thanks to the data augmentation approach, we can analytically obtain the conditional posterior distributions of B_τ , Λ_τ , and Ω_τ . Therefore, we can easily draw the posterior samples by implementing the Gibbs sampling algorithm. To draw F_τ , we can use the Metropolis–Hastings algorithm. We now summarize our data-augmentation strategy (given values of τ and the number of common factors r_τ) as follows.

Posterior Sampling Algorithm:

- Step 1. Initialize the parameters.
- Step 2. Sample F_τ from $\pi(F_\tau | Y, X, B_\tau, \Lambda_\tau, \Omega_\tau)$.
- Step 3. Sample $\boldsymbol{\gamma}_{i,\tau}$ from $\pi(\boldsymbol{\gamma}_{i,\tau} | Y, X, F_\tau, B_{-i,\tau}, \Lambda_{-i,\tau}, \Omega_\tau)$ for $i = 1, \dots, N$.
- Step 4. Sample $\omega_{it,\tau}$ from $\pi(\omega_{it,\tau} | Y, X, F_\tau, B_\tau, \Lambda_\tau, \Omega_{-\omega_{it,\tau},\tau})$ for $i = 1, \dots, N$ and $t = 1, \dots, T$.
- Step 5. Repeat Step 2 to Step 4 for a sufficiently large number of iterations.

To check MCMC convergence, several approaches were previously proposed (see, e.g., Robert and Casella 2004, chap. 12). In this article, we follow Gerlach, Chen, and Chan (2011) by examining trace plots from the MCMC sampler (For more details, see the simulation study in the online supplementary materials). Because the number of parameters is large, a good starting point is helpful for implementing MCMC. Otherwise, the number of MCMC iterations, H , may need to be large so that the MCMC chain gets close to the samples from the posterior distribution. To avoid this computational burden, we use the frequentist estimator in Section 3.1. This allows us to start MCMC from the Bayesian maximum a posteriori.

The outcomes of the above algorithm can be regarded as a random sample from the joint posterior density function after a burn-in period (see, e.g., Ando 2010). We then obtain a set of H posterior samples $\{B_\tau^{(k)}, F_\tau^{(k)}, \Lambda_\tau^{(k)}; k = 1, \dots, H\}$, which can be employed for conducting Bayesian analysis numerically. For example, the Bayesian maximum a posteriori is approximately given as

$$\begin{aligned} \{\tilde{B}_\tau, \tilde{F}_\tau, \tilde{\Lambda}_\tau\} &= \operatorname{argmax}_{\{B_\tau^{(k)}, F_\tau^{(k)}, \Lambda_\tau^{(k)}\}; k=1, \dots, H} \\ &\quad \times L(Y|X, B_\tau^{(k)}, F_\tau^{(k)}, \Lambda_\tau^{(k)}) \pi(B_\tau^{(k)}, F_\tau^{(k)}, \Lambda_\tau^{(k)}), \end{aligned} \quad (8)$$

which is an approximated solution as the maximizer of $L(Y|X, B_\tau, F_\tau, \Lambda_\tau) \pi(B_\tau, F_\tau, \Lambda_\tau)$. In practice, the number of MCMC iterations is finite, and thus the Monte Carlo error (the difference between the exact maximizer and its approximated solution in (8)) exists. However, this Monte Carlo error will converge to zero as $H \rightarrow \infty$. Regarding the Monte Carlo error of MCMC, we refer to Doss et al. (2014), Jones (2004), and references therein.

3.3. Relationship Between the Frequentist Estimator and Bayesian Approach

In Section 3.2, the identification restrictions on F_τ and Λ_τ are accommodated in the prior distribution of F_τ and Λ_τ . Recall, also, that the diffuse prior was used for $\boldsymbol{\gamma}_\tau$. In this case, the Bayesian maximum a posteriori in Equation (8) coincides with the frequentist estimator given in Section 3.1. The above priors were used for illustrating the core idea of our data-augmentation strategy. Even under a different prior specification (e.g., the lasso prior on $\mathbf{b}_{i,\tau}$), one can obtain the Bayesian maximum a posteriori in Equation (8) by modifying our proposed posterior sampling algorithm. In this case, the Bayesian maximum posteriori in Equation (8) no longer coincides with the frequentist estimator.

As an advantage of the Bayesian MCMC procedure, one can construct a Bayesian credible interval for the parameters even when N or T (or both) are small, while the asymptotic theory of the proposed frequentist estimator (see Section 5) relies on the large N and T . An online supplementary materials compares the Bayesian estimators (the posterior mean, mode, median) and frequentist estimators under a small panel. While Bayesian estimators provided smaller estimation errors under a small panel, Bayesian estimators and the frequentist estimator are asymptotically equivalent. This is because the prior information is dominated by the pseudo likelihood $L(Y|X, F_\tau, \Lambda_\tau, B_\tau)$. The performance of the Bayesian estimators and the frequentist estimator became very similar as the panel size increased. Details are given in Section G.3 in the online supplementary materials.

4. Model Selection

In practice, we have to determine the dimension of the interactive effects, r_τ . Although several methods have been proposed to select the number of factors (e.g., Bai and Ng 2002; Amengual and Watson 2007; Hallin and Liška 2007; and Lam and Yao 2012), these methods are fundamentally constructed for mean factor models, not quantile regression models.

One might think that cross-validation can be used for this purpose. However, as described in Ando and Bai (2018), it is not easy to apply cross-validation because of the existence of the factor structure. The reason is as follows. Consider leave-one-individual-out cross-validation. Based on the training sample, we can estimate the regression coefficients and the factor structures by using the algorithm in Section 3. However, it is not possible to obtain the factor loadings of the validation sample (deleted units) because the factor loadings are unit dependent. Instead, one may consider estimating the model based on the information observed up to time $t - 1$ and then forecast the responses of each unit at time t . However, the factor structure at time t is not available to make a forecast. Thus, the pure cross-validation procedure is not easy to apply directly.

In this article, we propose a novel information criterion. The number of common factors is selected by minimizing the following information criterion

$$IC_\tau(r) = \log \left[\frac{1}{NT} \sum_{t=1}^T \sum_{i=1}^N \rho_\tau \left(y_{it} - \mathbf{x}'_{it} \hat{\mathbf{b}}_{i,\tau}(r) - \hat{\mathbf{f}}_{t,\tau}(r)' \hat{\boldsymbol{\lambda}}_{i,\tau}(r) \right) \right] + r \times q(N, T), \quad (9)$$

where $\hat{\mathbf{b}}_{i,\tau}(r)$, $\hat{\boldsymbol{\lambda}}_{i,\tau}(r)$, and $\hat{\mathbf{f}}_{t,\tau}(r)$ is the estimated model parameters given the number of common factors r . The function $q(N, T)$ is a penalty on the dimension of interactive effects. In numerical study, we specify the function as

$$q(N, T) = \log \left(\frac{NT}{N+T} \right) \left(\frac{N+T}{NT} \right). \quad (10)$$

The asymptotic performance of $IC_\tau(r)$ in Equation (9) is investigated in the next section.

5. Asymptotic Theory

Because our modeling procedure is new, it is ideal to investigate its theoretical properties. In this section, we first provide the consistency of the proposed estimator \hat{F}_τ , \hat{B}_τ , and $\hat{\Lambda}_\tau$. Here, the true parameter value $\{F_{0,\tau}, B_{0,\tau}, \Lambda_{0,\tau}\}$ is defined as the minimizer of the expected quantile loss function

$$\ell_{0,\tau}(Y|X, B_\tau, F_\tau, \Lambda_\tau) = E \left[\sum_{i=1}^N \sum_{t=1}^T \rho_\tau(y_{it} - \mathbf{x}'_{it} \mathbf{b}_{i,\tau} - \mathbf{f}'_{t,\tau} \boldsymbol{\lambda}_{i,\tau}) \right] \quad (11)$$

subject to the identification restriction on F_τ and Λ_τ . Here, the expectation is taken with respect to the true conditional distribution of $\{y_{it} : i = 1, \dots, N, t = 1, \dots, T\}$ conditional on X , $F_{0,\tau}$ and $\Lambda_{0,\tau}$. The following proposition provides the average consistency of $\hat{\mathbf{y}}_{i,\tau} = (\hat{\mathbf{b}}'_{i,\tau}, \hat{\boldsymbol{\lambda}}'_{i,\tau})'$ and $\hat{\mathbf{f}}_{t,\tau}$. In general, $\hat{\mathbf{f}}_{t,\tau}$ and $\hat{\boldsymbol{\lambda}}_{i,\tau}$ are estimating a rotation of the true factors and factor loadings unless the latter satisfies the identification restrictions stated in the beginning of Section 3.1 (see also Bai and Ng 2013). For simplicity of notation, we drop the rotation matrix.

Proposition 1. Under Assumptions A–D, the following results hold:

$$N^{-1} \sum_{i=1}^N \|\hat{\mathbf{y}}_{i,\tau} - \mathbf{y}_{i,0,\tau}\|^2 = o_p(1),$$

$$T^{-1} \|\hat{F}_\tau - F_{0,\tau}\|^2 = T^{-1} \sum_{t=1}^T \|\hat{\mathbf{f}}_{t,\tau} - \mathbf{f}_{t,0,\tau}\|^2 = o_p(1),$$

where $\mathbf{y}_{i,0,\tau} = (\mathbf{b}'_{i,0,\tau}, \boldsymbol{\lambda}'_{i,0,\tau})'$.

The proof of Proposition 1 is given in an online supplementary materials. The result $\|\hat{F}_\tau - F_{0,\tau}\|/T^{1/2} = o_p(1)$ implies that the space spanned by $F_{0,\tau}$ and the space spanned by the estimated factors \hat{F}_τ are asymptotically the same. We also prove the consistency of the estimators in the sense that $\hat{\mathbf{b}}_{i,\tau}$ and $\hat{\boldsymbol{\lambda}}_{i,\tau}$ converge in probability to $\mathbf{b}_{i,0,\tau}$ and $\boldsymbol{\lambda}_{i,0,\tau}$ and uniformly over $1 \leq i \leq N$. In addition, $\hat{\mathbf{f}}_{t,\tau}$ converges in probability to $\mathbf{f}_{t,0,\tau}$ uniformly over $1 \leq t \leq T$.

Theorem 1. Suppose Assumptions A–D, $\log(T)/N^{1/2} \rightarrow 0$ and $\log(N)/T^{1/2} \rightarrow 0$ hold. Then, $\hat{\mathbf{b}}_{i,\tau}$ and $\hat{\boldsymbol{\lambda}}_{i,\tau}$ are uniformly consistent

$$\max_{1 \leq i \leq N} \|\hat{\mathbf{b}}_{i,\tau} - \mathbf{b}_{i,0,\tau}\| = o_p(1), \quad (12)$$

$$\max_{1 \leq i \leq N} \|\hat{\boldsymbol{\lambda}}_{i,\tau} - \boldsymbol{\lambda}_{i,0,\tau}\| = o_p(1). \quad (13)$$

Moreover, the estimated common factor is uniformly consistent

$$\max_{1 \leq t \leq T} \|\hat{\mathbf{f}}_{t,\tau} - \mathbf{f}_{t,0,\tau}\| = o_p(1). \quad (14)$$

Theorem 2 shows that the asymptotic distribution of the estimated regression coefficients, $\hat{\mathbf{y}}_{i,\tau} = (\hat{\mathbf{b}}'_{i,\tau}, \hat{\boldsymbol{\lambda}}'_{i,\tau})'$, is a multivariate normal distribution. Similarly, the asymptotic distribution of the estimated common factor $\hat{\mathbf{f}}_{t,\tau}$ is also a multivariate normal distribution.

Theorem 2. Suppose that Assumptions A–D hold. Assume that $T^{1/2}/N^{1-\gamma} \rightarrow 0$ and $N^{1/2}/T^{1-\gamma} \rightarrow 0$ for a small γ satisfying $1/16 < \gamma < 1/2$. Then, the asymptotic distribution of $T^{1/2}(\hat{\mathbf{y}}_{i,\tau} - \mathbf{y}_{i,0,\tau})$ is normal with mean zero and variance-covariance matrix

$$\Sigma_{i,\tau} = \tau(1-\tau)\Gamma_{i,0,\tau}^{-1}V_{i,0,\tau}\Gamma_{i,0,\tau}^{-1}.$$

Here, $\Gamma_{i,0,\tau}$ and $V_{i,0,\tau}$ are given as $\Gamma_{i,0,\tau} \equiv \text{plim}_{T \rightarrow \infty} T^{-1} \sum_{t=1}^T g_{it}(0|\mathbf{x}_{it}, \mathbf{f}_{t,0,\tau}, \boldsymbol{\lambda}_{i,0,\tau}) \mathbf{z}_{it,0,\tau} \mathbf{z}'_{it,0,\tau}$ and $V_{i,0,\tau} \equiv \text{plim}_{T \rightarrow \infty} T^{-1} \sum_{t=1}^T \mathbf{z}_{it,0,\tau} \mathbf{z}'_{it,0,\tau}$ with $\mathbf{z}_{it,0,\tau} = (\mathbf{x}'_{it,0,\tau}, \mathbf{f}'_{t,0,\tau})'$. Furthermore, the asymptotic distribution of $N^{1/2}(\hat{\mathbf{f}}_{t,\tau} - \mathbf{f}_{t,0,\tau})$ is normal with mean zero and variance-covariance matrix

$$\Theta_{t,\tau} = \tau(1-\tau)\Psi_{t,0,\tau}^{-1}R_{0,\tau}\Psi_{t,0,\tau}^{-1}.$$

Here, $\Psi_{t,0,\tau}$ and $R_{0,\tau}$ are given as $\Psi_{t,0,\tau} \equiv \text{plim}_{N \rightarrow \infty} N^{-1} \sum_{i=1}^N g_{it}(0|\mathbf{x}_{it}, \mathbf{f}_{t,0,\tau}, \boldsymbol{\lambda}_{i,0,\tau}) \boldsymbol{\lambda}_{i,0,\tau} \boldsymbol{\lambda}'_{i,0,\tau}$ and $R_{0,\tau} \equiv \text{plim}_{N \rightarrow \infty} N^{-1} \sum_{i=1}^N \boldsymbol{\lambda}_{i,0,\tau} \boldsymbol{\lambda}'_{i,0,\tau}$, respectively.

The proofs of [Theorem 1](#) and [Theorem 2](#) are given in the supplementary materials. There are some studies on panel data models with factor structures, for example, [Bai \(2009\)](#), [Song \(2013\)](#), and [Ando and Bai \(2015\)](#). However, these results cannot be transferred to our setting directly because these methods were designed for panel “mean” regression models with factor structures instead of panel “quantile” models. Although [Koenker \(2004\)](#) and [Kato, Galvao, and Montes-Rojas \(2012\)](#) investigated the asymptotic property of the panel quantile regression models, their results are derived from panel quantile regression models with “individual fixed effects.” In contrast to these studies, the model (1) contains the factor structures and heterogeneous regression coefficients. In addition, the dimensions of the panel size N and T are diverging. Therefore, a novel proof is developed by addressing these technical difficulties. For the panel “mean” models, [Song \(2013\)](#) and [Ando and Bai \(2015\)](#) imposed $T^{1/2}/N \rightarrow 0$ and $N^{1/2}/T \rightarrow 0$ to obtain the asymptotic distribution. Because of the non-smoothness of the objective function and nonlinearity in terms of parameters, we need slightly stronger conditions on T and N .

Next, we provide a theoretical justification for the use of IC in Equation (9), as none of the previous studies (e.g., [Bai and Ng 2002](#); [Amengual and Watson 2007](#); [Hallin and Liška 2007](#); [Lam and Yao 2012](#)) have addressed the important question of how to determine the number of common factors in a panel quantile regression model with interactive fixed effects. Here, we provide a new solution to this issue and provide a theoretical justification for our proposed model selection criterion.

Theorem 3. Suppose that assumptions in [Theorem 2](#) hold. Under the model selection criterion Equation (9) with penalty $q(N, T)$ that satisfies

$$q(N, T) \rightarrow 0 \text{ and } C_{NT} \times q(N, T) \rightarrow \infty,$$

where $C_{NT} = \min\{N, T\}$, we have a consistent model selector of the true dimension of the interactive effects (i.e., the true number of common factors) $r_{0,\tau}$.

As shown in [Bai and Ng \(2002\)](#), the penalty function Equation (10) satisfies the conditions in [Theorem 3](#). One can also consider an alternative penalty function. However, this is outside the scope of this article.

6. Empirical Results

6.1. Data and Model

We explore the quantile common factor structures of the global financial markets around the period of the subprime crisis, the period of the European sovereign debt crisis, and the subsequent period. Here, we analyze the stock returns of publicly traded firms and firms traded in over-the-counter trading markets for over 6000 international stocks from over 100 financial markets. To investigate the impact of the subprime crisis and European sovereign debt crisis on the global financial industry, we analyze individual firms’ stock returns belonging to the following industries: Banking, Life Insurance, Nonlife Insurance, Financial Services, and Real Estate Investment and Services. We collect all data from the Datastream database.

To study the dynamic characteristics of the global stock market, we analyze the following three periods.

Period 1: January 1, 2007 to April 31, 2009

Period 2: September 1, 2009 to December 31, 2012

Period 3: January 1, 2013 to March 31, 2015

Period 1 contains some key events during the subprime crisis, including the Chapter 11 bankruptcy of Lehman Brothers in September 2008. The Dow Jones Industrial Average then hit a bottom in the middle of 2009. Although the Dow Jones Industrial Average had been recovering stably since then, the long-term interest rates of Euro zone countries (including Greece, Portugal, and Ireland) started to increase by the end of 2009. In the middle of 2012, the long-term interest rates of the Greece government bond reached above 30%. After the announcement by the European Central Bank indicating free unlimited support for all Euro zone countries, the interest rate dropped by around 10% in December, 2012. Obviously, one could use a different specification for these subperiods. However, similar results are obtained under a different subperiod specification. Stocks with missing returns and stocks with no variation are excluded from the sample used for analysis. The final samples for each period are summarized in [Table 1](#) in an online supplementary materials. Finally, because different financial markets do not have the same trading hours, it is common to use the rolling average, and the two-day returns of each of the firms are therefore, employed for the returns (e.g., [Forbes and Rigobon 2002](#); [Ando and Bai 2017](#)). We consider the following panel quantile regression model with a factor structure:

$$\begin{aligned} Q_{y_{it}}(\tau | \mathbf{x}_{it}) = & \alpha_{i,\tau} + \text{Mkt}_t \times \beta_{\text{Mkt},i,\tau} + \text{HML}_t \\ & \times \beta_{\text{HML},i,\tau} + \text{SMB}_t \times \beta_{\text{SMB},i,\tau} \\ & + \text{RMW}_t \times \beta_{\text{RMW},i,\tau} + \text{CMA}_t \times \beta_{\text{CMA},i,\tau} \\ & + \sum_{k=1}^{11} \text{LMkt}_{t,k} \times \beta_{\text{LMkt},k,\tau} + \mathbf{f}'_{t,\tau} \boldsymbol{\lambda}_{i,\tau}, \end{aligned} \quad (15)$$

where Mkt_t , HML_t , SMB_t , RMW_t , and CMA_t are Fama/French global five factors at time t . Here, Mkt is the return on a region’s value-weighted market portfolio minus the United States one-month T-bill rate, SMB (Small Minus Big) is the average return on the nine small stock portfolios minus the average return on the nine big stock portfolios, HML (High Minus Low) is the average return on the two value portfolios minus the average return on the two growth portfolios, RMW (Robust Minus Weak) is the average return on the two robust operating profitability portfolios minus the average return on the two weak operating profitability portfolios, and CMA (Conservative Minus Aggressive) is the average return

Table 1. Estimated number of common factors r_τ for the quantiles $\tau = 0.05$ and 0.95 .

τ	Period 1	Period 2	Period 3	Period 4
0.05	7	6	3	10
0.95	2	2	4	8

NOTE: Period 1 (January 1, 2007 to April 31, 2009); Period 2 (September 1, 2009 to December 31, 2012); Period 3 (January 1, 2013 to March 31, 2015); Period 4 (January 1, 2007 to March 31, 2015).

on the two conservative investment portfolios minus the average return on the two aggressive investment portfolios. International tests of a five-factor asset pricing model are studied by Fama and French (2016). Further details of these factors and the historical data are obtained from the publicly available Fama/French data library <http://mba.tuck.dartmouth.edu/pages/faculty/ken.french/data-library.html>. A set of factors $\{LMk_{t,k}, k = 1, \dots, 11\}$ is the average return for 11 local stock exchange markets with more than 100 stocks in the dataset.

6.2. Result

6.2.1. Number of Common Factors

In this article, we focus on both the upper and lower quantiles and consider $\tau = 0.05$ and $\tau = 0.95$. We apply the proposed model selection criterion, $IC(r_\tau)$ in Equation (9), to select the number of common factors. The maximum number of common factors is set to 12. For each period, the number of common factors is determined as the minimizer of the IC score. After we obtain the frequentist estimates, we also implemented the posterior sampling procedure described in Section 3.2. The total number of posterior samples is set at 3000. As expected, the difference between the frequentist estimate and Bayesian maximum a posteriori in Equation (8) was negligible. Hereafter, we thus report the results based on the frequentist estimator only.

The number of common factors detected is summarized in Table 1. In this table, the number of common factors for the $\tau = 0.05$ quantile in Period 1 is determined to be $r_\tau = 7$ because it achieved the smallest value of the proposed model-selection criterion, IC. This suggests that there are $r_\tau = 7$ common factors that explain the $\tau = 0.05$ quantile in Period 1. The table shows that the number of common factors in the $\tau = 0.95$ quantile is smaller than that in the $\tau = 0.05$ quantile in Periods 1 and 2. This indicates that the $\tau = 0.05$ quantile exhibits greater variability due to the increase in the degree of complexity. As one of the referees suggested, this difference is partially due to differences in governments or regulations for the different stocks.

The number of common factors for the $\tau = 0.05$ quantile in Period 3 is smaller than that in other periods. This implies that the degree of market heterogeneity decreased in Period 3. In summary, the common factor structures that explain the asset return distribution vary across quantiles. Moreover, the common factor structures are not symmetric in the sense that the structures in the lower tails and the upper tails are different.

6.2.2. Common Factors for the Quantile and for the Mean

To check whether the extracted common factors for the quantile function and the common factors for the mean are perfectly related, we implement canonical correlation analysis. Let \hat{F}_τ be the estimated common factors of dimension r_τ , which is determined by the $IC(r_\tau)$ score. Setting the dimension of the common factor for the mean to be identical to r_τ , we estimate the following asset pricing model with a common

Table 2. The result of canonical correlation analysis between the common factors for quantile τ and the common factors for the mean (see Section 6.2.2).

τ	Period 1	Period 2	Period 3	Period 4
0.05	6/7	5/6	3/3	10/10
0.95	1/2	2/2	4/4	7/8

NOTES: To determine the significant canonical correlation, the 5% significance level is used. Period 1 (January 1, 2007 to April 31, 2009); Period 2 (September 1, 2009 to December 31, 2012); Period 3 (January 1, 2013 to March 31, 2015); Period 4 (January 1, 2007 to March 31, 2015).

factor structure

$$y_{it} = \alpha_i + Mkt_t \times \beta_{Mkt,i} + HML_t \times \beta_{HML,i} + SMB_t \times \beta_{SMB,i} + RMW_t \times \beta_{RMW,i} + CMA_t \times \beta_{CMA,i} + \sum_{k=1}^{11} LMkt_{t,k} \times \beta_{LMkt,k,i} + f'_t \lambda_i + \varepsilon_{it},$$

by minimizing the least-squares objective function $\ell(B, F, \Lambda) = \sum_{i=1}^N \|y_i - X_i \beta_i - F \lambda_i\|^2$ subject to the constraint $F'F/T = I_r$. Numerical optimization can be achieved by the iterative optimization of B, F, Λ based on the previous results (see, e.g., Bai 2009; Song 2013; Ando and Bai 2015; Wang 2017).

Let \hat{F} be the estimated common factors for the mean structure. Then, we apply the canonical correlation analysis for exploring the relationships between \hat{F} and \hat{F}_τ . To check whether all the columns of \hat{F} and \hat{F}_τ are indeed related, we use the significance tests for canonical correlation analysis. Wilks' Lambda is used for this purpose. In determining the significant canonical correlation, the 5% significance level is used. The results are summarized in Table 2.

There is a certain degree of relatedness between the common factor for the quantile and that for the mean. Note that $1/2 = 50\%$ of $\tau = 95\%$ quantile common factors $\hat{F}_{0.95}$ in Period 1 are related to the estimated common factors for the mean structure \hat{F} . Thus, it should be noted that the common factor for the quantile and that for the mean are not always identical, as the statistically significant canonical correlation is smaller than the detected number of common factors for the quantiles. This implies that the two-step procedure to estimate the model parameters (in Section 3) will lead to inconsistent estimates of the regression coefficients and factor loadings. Therefore, our data-augmentation strategy is important for avoiding this issue.

6.2.3. Do the Stock Exchange and Industry Matter?

To explore the effects of stock exchanges and industries on individual stock returns, we apply a clustering approach to the estimated regression coefficients and factor loadings $\{(\hat{b}'_{i,\tau}, \hat{\lambda}'_{i,\tau}); i = 1, \dots, N\}$ to create a set of groups based on the similarities in the sensitivity to the common factors. If the source of the sensitivity to the factors (both observables and unobservables) is solely attributable to stock exchanges, it is expected that the two-way table of the assigned group membership from the clustering approach against the stock exchanges will be diagonal. To save space, clustering results are provided in the online supplementary materials. In short, the firm industry and the stock exchange on which a firm is listed are important factors to be considered. However, we also note

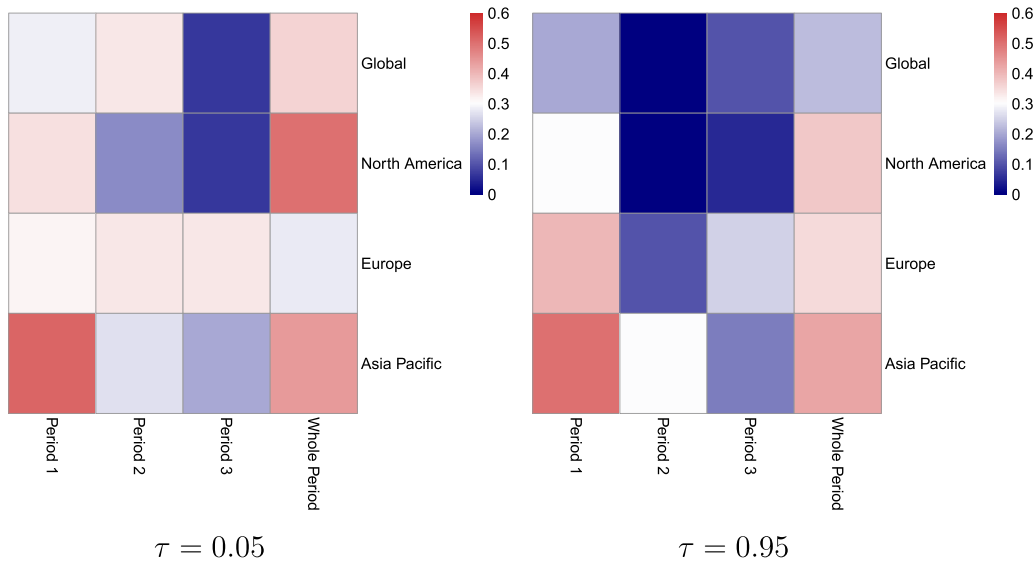


Figure 1. Link between the extracted common factors and Fama and French factors for each region (see Section 6.2.4). Each cell represents the fraction of statistical significant common factors explained by Fama and French factors. Period 1 (January 1, 2007 to April 31, 2009); Period 2 (September 1, 2009 to December 31, 2012); Period 3 (January 1, 2013 to March 31, 2015); Period 4 (January 1, 2007 to March 31, 2015).

that these nominal factors are insufficient to fully capture the underlying market structures.

6.2.4. Meaning of Common Factors and Regional Effects

Because the estimated common factors do not have an immediate economic interpretation, we explore the economic meanings of the estimated common factors. Here, we regress the estimated common factors on Fama and French's 5 factors (Global, North America, Europe, and Asia Pacific). These factors and the historical data are obtained from the publicly available Fama/French data library. Because there are 5 factors (Mkt, SMB, HML, RMW, and CMA) in each of the four regions, each of the estimated common factors is regressed on the set of 20 (Fama and French's 5 factors \times 4 regions) variables. Mathematically, let $f_{jt,\tau}$ be the estimated value of the j th common factor at time t and at the τ th quantile; we then run the following regression $f_{jt,\tau} = \mathbf{z}'_t \boldsymbol{\gamma}_j + e_{jt}$, where \mathbf{z}_t is the twenty-dimensional vector of Fama and French's factors. Then, we conduct statistical significance tests of the least-squares estimate $\hat{\boldsymbol{\gamma}}_j$.

To clearly demonstrate the regional effects, we calculate the following. We simply count the number of statistically significant Fama and French factors for each region. For example, in the lower quantile $\tau = 0.05$, there are $r_\tau = 7$ common factors in Period 1. For each of the factors, we run the following regression: $f_{jt,\tau} = \mathbf{z}'_t \boldsymbol{\gamma}_j + e_{jt}$ for $j = 1, 2, \dots, r_\tau$. To investigate a connection to North America, we count the total sum of the number of significant Fama and French North America 5 factors across the seven ($r_\tau = 7$) regressions. Note that a particular Fama and French factor may be counted multiple times across the regressions. Because the number of common factors r_τ varies across quantiles and periods, we convert this count into percentage terms by dividing it by $5 \times r_\tau$, which is the upper bound of the count. For example, in the lower quantile $\tau = 0.05$ in Period 1, the total sum of the number of significant Fama and French North America 5 factors is divided by $5 \times r_\tau =$

$5 \times 7 = 35$. The same operation is performed for the others, Global, Europe and Asia Pacific.

Figure 1 summarizes the results. We see that the extracted common factors are less connected to Fama and French's global factors than regional factors. This implies that the extracted factors are more related to Fama and French's regional factors. We note that the Fama/French global five factors are included in the explanatory variables Equation (15). Because the extracted common factors are still connected to the Fama and French's global factors, our model is useful in treating the endogeneity problem.

6.2.5. Discussion

The goal of our empirical analysis is to analyze the quantile co-movement of a large number of financial time series by investigating the quantile co-movement structure of the global financial market. We are interested primarily in the empirical questions described in the introduction. Here, we would like to provide a summary of our empirical findings.

Regarding the first question; "Do the quantile common factor structures that explain asset return distribution vary across quantiles?" we found that the number of common factors varies across quantiles. The number of common factors also varies over time. This is one of the reasons that understanding current financial market structures is important because the market structure changes over time.

We found empirical evidence to answer the second question. The common factor structure is not symmetric in the sense that the number of common factors in the lower tail τ is larger than that in the upper tail in Periods 1 and 2. This implies that there is greater heterogeneity in the lower tail than in the upper tail in these two periods.

Third, Table 2 indicates that there is a fair degree of relatedness between the common factor for the quantile and that for the mean. However, they are not identical. Therefore, the two-step procedure described in Section 3 would lead to inconsistent

parameter estimation results. To avoid such undesirable results, our initialization algorithm and data-augmentation strategy are important.

Fourth, the stock exchange on which a firm is listed is partially related to the extracted factor structures. These observable stock characteristics are not sufficient to explain the extracted factor structures. This implies that diversification based on the stock exchange on which a firm is listed is inadequate, as the common factor structures are not fully connected with these nominal classifications.

Finally, there are special characteristics of the quantiles of financial markets. Compared to Period 3, the number of common factors in Periods 1 and 2 is larger. This implies that the heterogeneity of the global financial market decreased after Period 2. Figure 1 shows that the unobservable common factor structures are more connected to Asia Pacific regional factors during the subprime crisis (Period 1). This implies that the model (15) is missing some observable factors relating to Asia Pacific regional factors. In summary, the important common factors that govern asset return distributions vary across quantiles. These findings, derived from our general procedure, offer useful insights for institutional investors and regulators.

6.2.6. Robustness Check

For the vectors of observable factors in Equation (15), we use Fama and French's (2016) global five factors and a set of average returns for 11 local stock exchange markets with more than 100 stocks in the dataset. It is also possible to implement the proposed modeling procedure under a different specification of the vectors of observable factors. For example, together with Fama and French's (2016) global five factors, one can consider a set of average returns for local stock exchange markets with more than 50 stocks in the dataset. However, similar results are obtained under this specification.

The rolling two-day average of returns is used to cope with the differences in international market trading hours. Similar results can be obtained under daily returns instead of a two-day rolling average.

7. Conclusion

In this article, we introduced a new panel quantile regression model with interactive fixed effects. The model has attractive features, including heterogeneous regression coefficients, unobservable common factors that vary across quantiles, and the ability to cope with endogeneity by allowing observable factors depend on unobservable factors and factor loadings.

To address endogeneity and a large number of parameters, we proposed frequentist and Bayesian data-augmented inference procedures. This allowed us to directly estimate the model parameters. Theoretical properties were established for the frequentist estimator. We also developed a new approach for selecting the number of common factors. Our empirical analysis delivered many insightful findings, which are of interest for investors and market regulators.

Supplementary Materials

Supplementary materials, including technical proofs and simulation results, for this article are available online.

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