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# Vertical profiles of ozone concentration collected by an unmanned aerial vehicle and the mixing of the nighttime boundary layer over an Amazonian urban area

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**Abstract:** The nighttime boundary layer was studied in an urban area surrounded by tropical forest by use of a copter-type unmanned aerial vehicle (UAV) in central Amazonia during the wet season. Fifty-seven vertical profiles of ozone concentration, potential temperature, and specific humidity were collected from surface to 500 m a.g.l. at high vertical and temporal resolutions by use of embedded sensors on the UAV. Abrupt changes in ozone concentration with altitude served as a proxy of nighttime boundary layer (NBL) height for the case of a normal, undisturbed, stratified nighttime atmosphere, corresponding to 40% of the cases. The median height of the boundary layer was 300 m. A turbulent mixing NBL constituted 28% of the profiles while the median height of the boundary layer was 290 m. The remaining 32% of profiles corresponded to complex atmospheres without clear boundary layer heights. The occurrence of the three different cases correlated well with relative cloud cover. The results show that the standard nighttime model widely implemented in chemical transport models holds just 40% of the time, suggesting new challenges in modeling of regional nighttime chemistry. The boundary layer heights were also somewhat higher than observed previously over forested and pasture areas in Amazonia, indicating the important effect of the urban heat island.

**Keywords:** Ozone; Amazonia; UAV; boundary layer

## 1. Introduction

The NBL occurs in response to surface cooling associated with the emission of long-wave radiation into space, causing a temperature inversion in the overlying atmospheric column at a maximum vertical extent of about 500 m [1]. For this atmospheric structure in its theoretical state, conditions of atmospheric stability result and there is little or no vertical mixing between the surface layer and the altitudes above the NBL [1]. The atmosphere is described as a normal, undisturbed, stratified nighttime atmosphere. Turbulence is typically considered weak and sporadic, and the time scale of mixing in this layer is taken as several hours [2]. Compared to this theoretical description, there are suggestions of intermittent turbulence associated with overhead jets [3], gravitational wave breaking [4], or baroclinicity [5]. These processes can influence the structure and development of the NBL, including vertical mixing processes across the NBL [6-8]. Moreover, in urban regions, the effects of a heat island, meaning an elevated surface temperature relative to adjacent non-urban regions, can also further affect the development of the NBL [9].

The mechanisms associated with possible NBL mixing can be complex [10]. Thermal and mechanical instabilities, caused by the horizontal and vertical propagation of gravity waves, can initiate sporadic or intermittent turbulent mixing [11-16]. Furthermore, in the presence of strong thermal stratification, the mechanical wind shear near the top of the thermal inversion can lead to the formation of low-level jets, which in turn can induce turbulence and increase mixing [17-19]. Finally, events associated with descending currents of air during convective storms can penetrate into the NBL and induce complete air exchange [20,21]. Given the complexity of these various processes cited above, all of which may be further influenced by the urban heat island, vertical transport in the NBL remains incompletely understood [22-24].

Approaches used to collect atmospheric data to characterize the NBL include radiosondes on tethered balloons, remote sensing aboard airplanes or from the surface, and instrumented meteorological towers. Each approach has varying capabilities and limitations with respect to the temporal and spatial resolution of atmospheric data collection. They are also differentiated by cost and differing logistics requirements. Seibert et al. [25] provide a comparative review, although without reference to unmanned aerial vehicles (UAVs) which were unavailable at that time. Copter-type UAVs have recently become available at mid-level pricing and relatively quick user training, meaning that UAVs are increasingly part of the portfolio of atmospheric scientists. Most relevant for comparison to copter-type UAVs for in situ measurements are radiosondes and tethered balloons (Table S4). Radiosondes have high ascent rates and thus very quickly cross the boundary layer, allowing the collection of relatively few data points. Their position also drifts horizontally with the prevailing winds, and the collected data sets thus do not represent a purely vertical column measurement. Approximately fifty data points of 2 s each spaced by 10 m in the vertical from 0 to 500 m can be considered representative. Tethered balloons have a controlled ascent rate, but they are expensive and logistically complicated to control. Approximately twenty-five data points of 10 s each spaced by 20 m can be considered a representative data set from 0 to 500 m. Mid-level copter-type UAVs used increasingly in scientific deployments can be described as collecting 100 data points of 10 s each spaced by 5 m in the vertical from 0 to 500 m at relatively low cost. This emerging approach for in situ measurements thus complements the traditional approaches by offering improvements in the vertical and temporal resolutions of measurements.

One of the pioneering studies on the characteristics of the Amazonian NBL was carried out by Fisch [26], followed by other robust studies at different seasons by Santos [10] and Neves et al. [16]. In these previous studies, vertical profiles of potential temperature and specific humidity were the main observations used to estimate the NBL height [16,27]. However, for cloudy and partly cloudy conditions, the use of these profiles to infer the NBL height, often yielded ambiguous results because of small differences (i.e., below sensor precision) between the surface values and the top of the boundary layer for temperature and humidity [28]. Nighttime cloudiness is common to various degrees over the tropical forest because of the strong water emissions by forest evapotranspiration under warm conditions [29]. Despite these difficulties, vertical profiles of potential temperature and specific humidity were broadly used for all-sky conditions because of the wide availability of inexpensive sensors, the ease of data analysis, and the strong theoretical underpinning between the vertical profiles and the boundary layer height [30].

As an alternative to potential temperature and specific humidity over forests, chemical tracers might better define the NBL structure. Pal et al. [31] compares the boundary layer with a “volume of the box” whose the mixing and dispersion of various chemical compounds take place. Chemical tracers like ozone, carbon dioxide, methane, nitrogen oxides, aerosol particles, radioactive noble gas radon ( $^{222}\text{Rn}$ ), among others, might provide significant information on the NBL structure depending on local conditions ([31-37]. For this purpose, local criteria include a chemical species whose concentration close to the surface is relatively low, such as because of a reactive sink there with vegetation or chemical reactions, and whose concentration is comparatively high in the mixed atmosphere above the NBL.

Over the tropical forest in central Amazonia, ozone satisfies the necessary criteria [38]. Ozone is produced in the daytime troposphere from photochemical reactions among natural and anthropogenic precursors that include industrial, vehicle, and biosphere emissions [39]. At nighttime, production ceases, and the residual daytime concentration remains in what is effectively a well-mixed infinite reservoir overlying the relatively thin NBL [6,40,41]. At the surface, there is a strong ozone sink through both stomatal and non-stomatal processes [42-44]. Stomatal uptake occurs by dry deposition when ozone meets in specific locations of the plants along the path from outside the leaf to the reaction site inside the apoplast [45]. The uptake rate of stomatal pathway varies among plant species, genotype, plant phenology, leaf age, position in the canopy, and nutrient availability [46-50]. Non-stomatal processes involve ozone deposition to soil, stems, cuticles, along with chemical losses such as reactions with nitric oxide (NO) in the atmosphere in polluted environments [49]. The strong ozone sink at the surface owing to reactive dry deposition or chemical losses thus leads to the expectation of a step function in ozone concentration across the top of the NBL for nighttime atmosphere [8,9,33,34,35], and such profile is suggested as a method in this study to infer the NBL height.

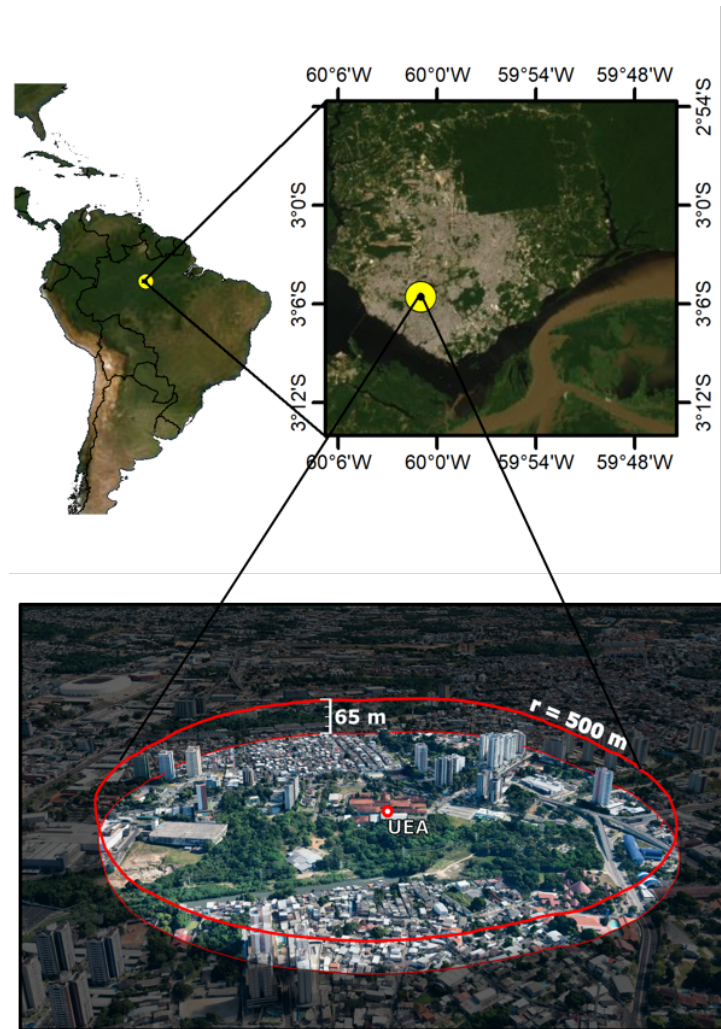
The study described herein focuses on the NBL of urban Manaus, an environment little explored in previous studies in the Amazon but which deserves attention due to the heat island configuration that may imply NBL height differences compared to previous studies on forest and pasture regions (Table S1). In addition, the results of this study highlight that ozone can be used as a tracer to probe the dynamics of the NBL, adding valuable information of the NBL height that supplements traditional measurements from potential temperature and specific humidity when the weather conditions and other factors are not favorable to their use. The primary data set of this study

consists of vertical profiles of ozone concentration, potential temperature, and specific humidity, allowing a comparative assessment among these metrics. A copter-type unmanned aerial vehicle was used in conjunction with a sensing system to collect the vertical profiles. The knowledge generated in this study can contribute to the improvement of atmospheric chemistry and air quality models, responding to the need for further improvement in the vertical observations of atmospheric profiles, especially about the urban environment, where there is greater concern with the social levels of air quality.

## 2. Methodology

### 2.1 Location

Manaus, Brazil, is located at the confluence of two large rivers, Rio Negro and Rio Solimões, in the forested Amazon Basin. It has a population of over 2 million and covers an area of  $11.4 \times 10^6$  km<sup>2</sup> [51]. The climatology of accumulated precipitation and annual and monthly temperature of Manaus are around 2307.4 mm yr<sup>-1</sup> and 26.7 °C, respectively [52]. The UAV flights were carried out on the campus of the School of Technology, Amazonas State University (3.0918° S, 60.0175° W), in the central region of the city. The campus is surrounded by urbanized residential and commercial areas interspersed by forested areas (Figure 1). A view of local land cover around the flight location is also shown in Figure 1. There was a forested region directly around the launch site, which transitioned into urban residential and commercial areas. The maximum infrastructure height was 65 m in the radius of 500 m from the UAV launch site. Although no ground-level continuous ozone monitoring was conducted during the sampling period, ozone concentrations range from 0 to 40 ppb in the wet season in urban Manaus. The highest concentrations occur around noon, and the lowest concentrations are at night.



**Figure 1.** (top) Satellite image of the study area for the city of Manaus in central Amazonia, Brazil. The urban region (white), the interspersed and surrounding forest (green), and the south and northwest rivers (brown and black, respectively) are apparent. Night flights to collect vertical profiles were based on the campus of the Amazonas State University (UEA) (yellow circle; UEA pin). Source: [53]. (bottom) Depiction of the urban canopy around the study area (UEA pin). The maximum infrastructure height is 65 m in the radius of 500 m from the UAV launch site. As seen in the image, there is a forested region directly around the launch site that transitions into an urban residential and commercial area. The image was produced by Google Earth 3D, and the orientation is due north.

## 2.2 Flight platform and instrumentation

A hexacopter unmanned aerial vehicle (DJI Matrice 600 model) was used. It had a maximum flight time of 35 min and a maximum take-off weight of 15 kg, allowing for up to a 5 kg payload. The maximum speed of ascent was  $5 \text{ m s}^{-1}$  and that of descent was  $3 \text{ m s}^{-1}$ . The upper altitude was limited to 500 m above ground level by geofencing from the manufacturer. Standard equipment of the DJI

flight package recorded telemetry of latitude, longitude, and altitude by use of the Global Positioning System (GPS).

A commercially available ozone sensor based on ultraviolet absorption (Personal Ozone Monitor, POM; 2B Technologies Inc) was mounted to the top platform of the UAV. The precision of the measurements ( $1\sigma$ ) was the greater of either 1.5 ppb or 2% of reading. The minimum limit of detection was 3 ppbv. The instrument recorded pressure as well as GPS latitude, longitude, and altitude. The instrument was calibrated weekly by a Model 306 ozone calibrator (2B Technologies Inc), Figure S5. Ozone measurements were made every 10 s at a sampling flow rate of 0.75 L min<sup>-1</sup>. Measurements were binned and averaged across vertical intervals of 15 m from the surface up to 500 m height.

Temperature and relative humidity (RH) along the vertical profiles were recorded by standard sensors (Model U10-003, HOBO). For temperature and RH measurement, the precision was  $\pm 0.35^\circ\text{C}$  from 0° to 50 °C, and  $\pm 2.5\%$  from 10% to 90% RH, respectively. Both meteorological measurements were recorded every 10 s. For the meteorological profiles, the potential temperature and specific humidity were calculated, interpolated every 15 m similar to ozone concentration. At 3 m above the surface but not onboard the UAV, wind velocity was also measured (Wind Monitor Sensor, Model 05103- 5A, R.M. Young Company). The sensor measured wind speed from 0-100 m s<sup>-1</sup> at an accuracy of  $\pm 0.3$  m s<sup>-1</sup> and wind direction at an accuracy of  $\pm 3^\circ$ .

### 2.3 UAV flights

UAV flights took place during the wet season from 30 March 2018 to 11 May 2018. There were 57 flights on 9 different weekdays (Table S2). There were typically 8 flights per night at 30 min intervals from 20:00 to 00:00 (LT). Local time (LT) was 4 h earlier than coordinated universal time (UTC). On some nights, there were fewer than 8 flights because of unforeseen events, such as the rapid formation of clouds suggesting the possibility of precipitation that could compromise the instruments or the UAV. For data collection, an ascent speed of 0.5 m s<sup>-1</sup> was used, and fifty-seven profiles were collected. A summary of flights is listed in Table S2. The flight patterns and flight permissions followed the regulations of the Brazilian National Civil Aviation Agency and associated agencies (RBAC-E No. 94/2017) [54]. The Brazilian Department of Airspace Control closed the airspace to others and authorized flights over the campus of Amazonas State University up to 500 m in height during the flight periods.

### 2.4 Data analysis

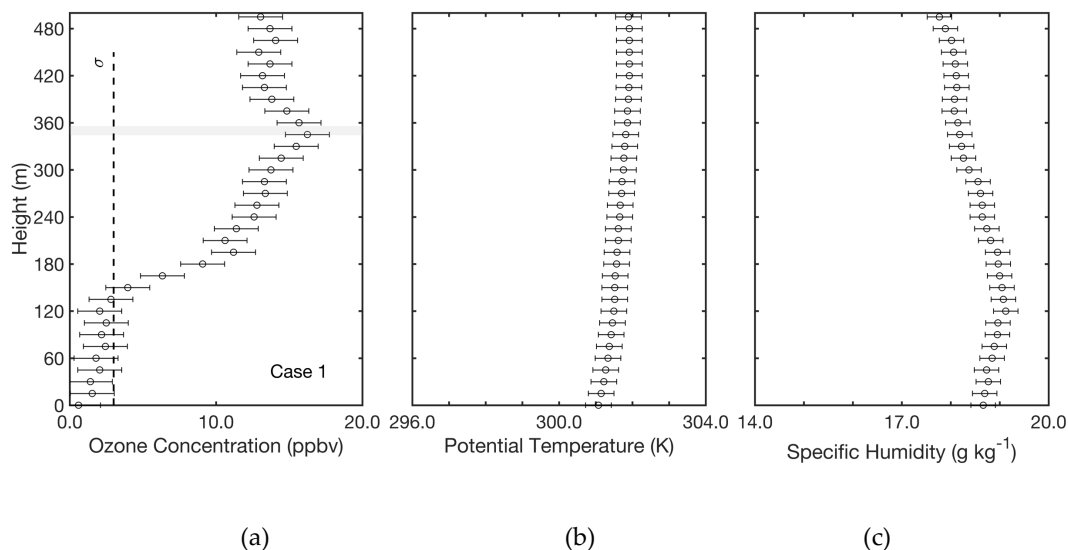
The NBL height was determined based on the profile method. The vertical profile of ozone concentration has a steep slope at the boundary layer top [1]. The atmospheric layer across which a clear inversion occurs in concentration can be used to estimate the NBL height where the profile changes rapidly with height across at least three consecutive altitude points. The lowest point of this layer is taken as the height of the boundary layer [10,55]. For comparison, methods used in other studies to determine the NBL height can include profile method, the bulk Richardson number, mean wind speed, mean potential temperature, gradient method, variance analysis, continuous wavelet transforms, and fitting idealized profiles [1,56].

There are three cases of profiles observed in this study. A normal, undisturbed, stratified nighttime atmosphere is referred to as “case 1”, representing the theoretical NBL profile of a step

function. “Case 2” represents a turbulently mixing NBL with a smooth increase of ozone concentration from surface to NBL top. Other profiles with complex characteristics of both stratified and turbulent atmospheres are classified as “case 3”, in which NBL heights cannot be estimated through the profiles of the tracers. For the weather conditions, the profiles were classified into three categories based on the hourly observation of each flight as clear, partly cloudy, and cloudy skies. Based on the case classification of the observed profiles, a statistical analysis using Cramer’s V was carried out between nominal variables of stratified, turbulent, and complex structures in the NBL (i.e., cases 1, 2, and 3 of the analysis herein) and nominal variables of clear, partly cloudy, and cloudy skies [57]. In addition, estimates of the NBL height obtained by the Global Data Assimilation System (GDAS), through of Real-time Environmental Applications and Display (READY) platform, for the city of Manaus, were also used to compare with the NBL height results of the UAV-observed profiles [58,59].

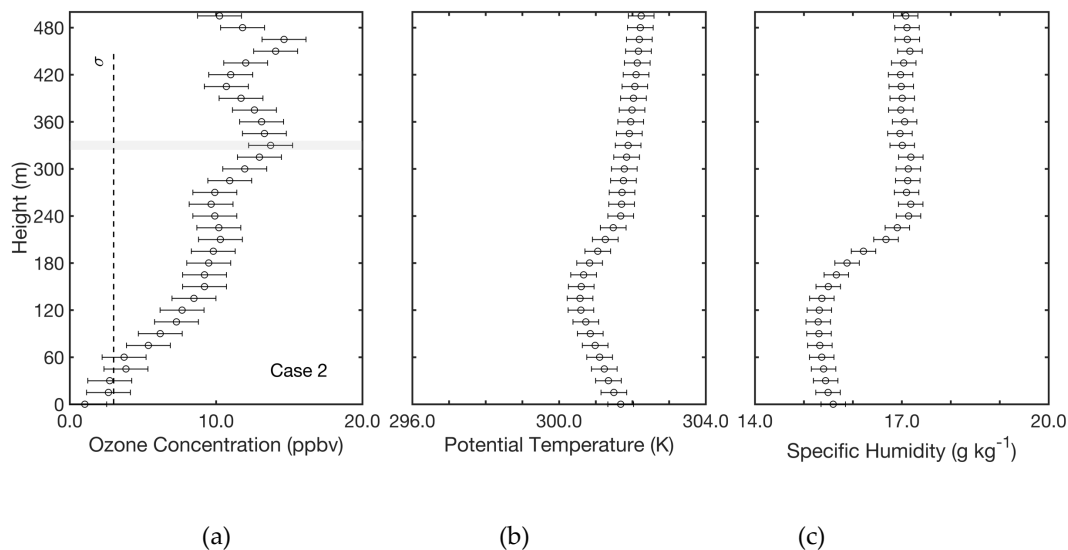
### 3. Results and Discussion

Fifty-seven vertical profiles of ozone concentration, potential temperature, and specific humidity were collected (Figure S1). An example of one data set representative of many profiles (40% of total) is plotted in Figure 2. For this profile, in an abrupt shift the ozone concentration changed by more than 15 ppbv across the altitude range of 150 to 200 m, representing the top of the NBL. For comparison, the change in potential temperature across the profile from surface to 500 m was 1 K, and the top of the NBL was not clearly discernable with this sensor. Specific humidity changed by 1 g kg<sup>-1</sup> and had an inflection point at a similar altitude as that of the shift in ozone concentration. Even so, the inflection point was weak, and as a standalone data set in the absence of the ozone data set the height of the top of the NBL would not be clear. Thus, in this example, ozone concentration represents the conclusive data set, specific humidity is a supportive data set, and potential temperature is not informative. Profiles of the type represented in Figure 2 correspond to a normal, undisturbed, stratified nighttime atmosphere, and they are referred to as “case 1” in the analysis herein, representing the theoretical NBL profile of a step function anticipated by Stull [1].



**Figure 2.** Vertical profiles of (a) ozone concentration, (b) potential temperature, and (c) specific humidity from surface to 500 m on 11 May 2018 at 23:00 LT (flight 57). These profiles are representative of case 1 (i.e., a normal, undisturbed, stratified atmosphere), including 23 of the 57 ozone profiles. The height of NBL based in ozone concentration is showed (grey color). The dotted line is the instrumental limit of detection for ozone (3 ppbv). Local time (LT) is 4 h earlier than UTC.

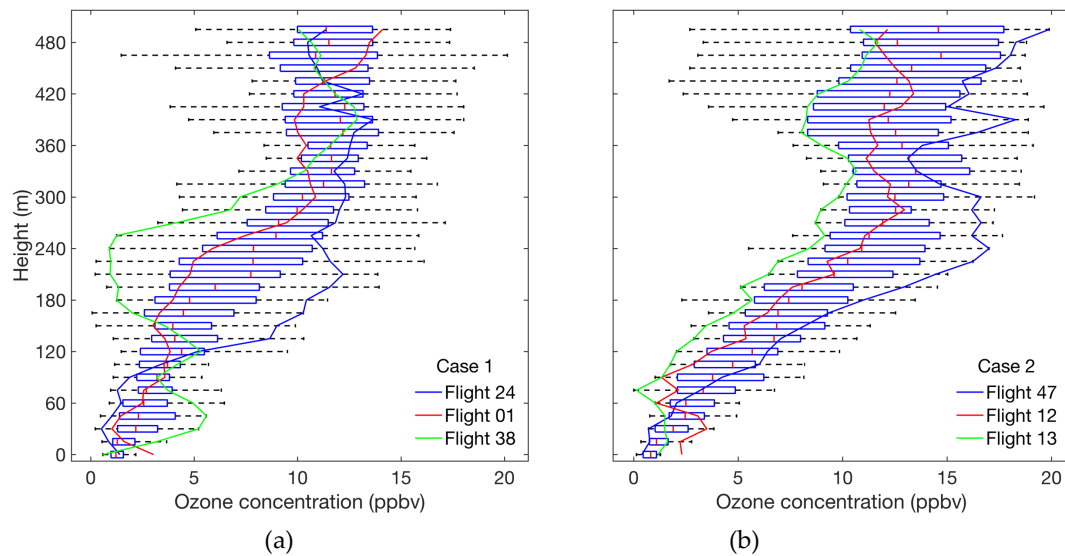
An example of a second data set representative of many other profiles (28%) is plotted in Figure 3. In this profile, in a smooth shift the ozone concentration increased by more than 10 ppbv from surface to 150 m, representing the top of the NBL at 150 m. Inflection points at 150 m were also clear in the vertical profiles of potential temperature and specific humidity, corroborating the ozone profile. For this smooth linear profile of ozone concentration with ascending altitude, a framework for interpretation can be used of an effective diffusivity through turbulent mixing from a fixed concentration of 0 ppbv at the surface (i.e., dry deposition) to 10 ppbv at 150 m (i.e., an overlying mixed atmosphere representing a large reservoir of ozone). A model of effective diffusivity results in the smooth variation in the vertical profile of ozone concentration from 0 to 150 m [60], as observed in Figure 3. Profiles of the type represented in Figure 3 are classified as “case 2” in the analysis herein, representing a turbulently mixing NBL [12,17].



**Figure 3.** Vertical profiles of (a) ozone concentration, (b) potential temperature, and (c) specific humidity from surface to 500 m on 26 April 2018 at 20:30 LT (flight 25). These profiles are representative of case 2 (i.e., a turbulently mixing nighttime atmosphere), including 16 of the 57 ozone profiles. The height of NBL based in ozone concentration is showed (grey color). The dotted line is the instrumental limit of detection for ozone (3 ppbv). Local time (LT) is 4 h earlier than UTC.

Profiles of ozone concentration for cases 1 and 2 of all flights are presented in statistical form in panels (a) and (b) of Figure 4. Horizontal box-whisker statistical plots are shown for selected altitudes from surface to 500 m. Example vertical profiles of ozone concentration for individual flights selected to envelope the statistical representation as well as go through its center are also shown.

260



**Figure 4.** Vertical profiles of the ozone concentration represented by horizontal box-whisker statistical plots at each altitude for (a) stratified atmospheres of case 1 and (b) turbulent atmospheres (case 2). For each box-whisker plot, the median (red bar) of the combined data sets, quartiles (blue box edges), and the minimum and maximum values (black lines) are represented, excluding outliers. For each panel, three actual vertical profiles of individual flights are selected as examples that envelope the statistical representation.

Figure 4a shows that for case 1 of a stratified atmosphere, the ozone concentration typically changed by 10 ppbv across the top of the NBL, based on the analysis of individual flights. For case 2 of a turbulent atmosphere, Figure 4b shows that the ozone concentration smoothly evolved with altitude across the NBL until reaching 10 to 15 ppbv, which is characteristic of the overlying atmosphere. Other profiles were more complex with characteristics of both stratified and turbulent atmospheres, and these complex cases were designated as “case 3”. Vertical profiles corresponding to case 3 are plotted in Figure S1.

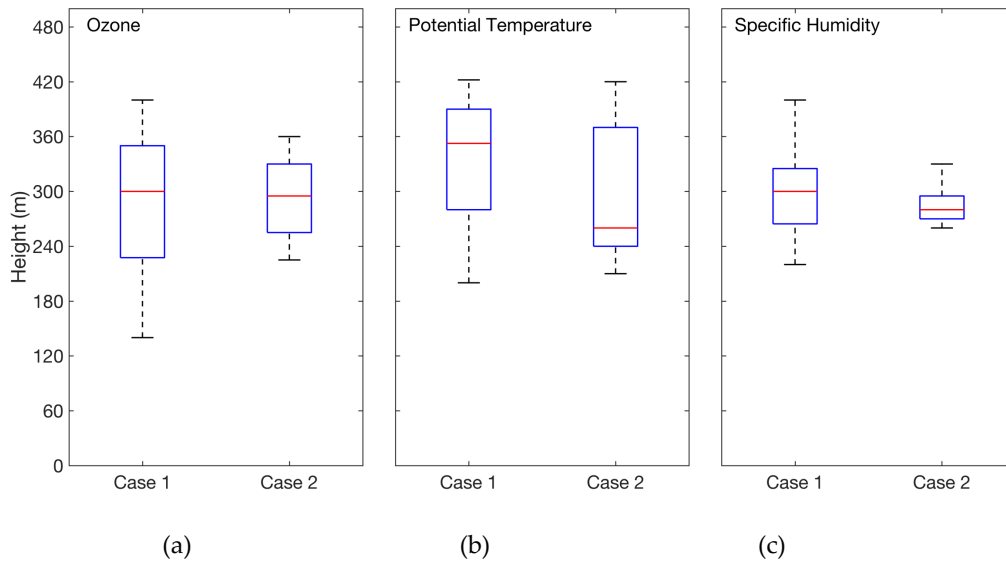
Statistical results of this study as determined from the vertical profiles of ozone concentration are summarized in Table 1. Overall, cases 1, 2, and 3 corresponded to 40%, 28%, and 32% of the profiles, respectively. The median height for the stratified NBL (i.e., case 1) was 300 m, and the height varied from 230 to 350 m as quartiles. For the turbulent atmosphere (i.e., case 2), the median height was lower at 290 m, and the quartiles were 255 to 330 m.

**Table 1.** Count, percent, median of NBL height, and quartiles of NBL height (25% and 75% of distributions) for case classifications for the vertical profiles of ozone concentration in the wet season of 2018. (Case 1) Normal, undisturbed, stratified atmosphere. (Case 2) Turbulently mixing atmosphere. (Case 3) Complex atmosphere characterized by both stratified and turbulent components in the NBL. There is no estimate of NBL height for

case 3.

Case	Count (N)	Percent	Median of NBL Height (m)	Quartiles of NBL Height (m)
1: Stratified atmosphere	23	40%	300	230 and 350
2: Turbulent atmosphere	16	28%	290	255 and 330
3: Complex atmosphere	18	32%	N/A	N/A

A comparative statistical analysis for the NBL height determined from vertical profiles of ozone concentration, potential temperature, and specific humidity is represented in box-whisker plots in panels (a), (b), and (c) of Figure 5. For case 1, the median NBL heights were 300 m, 352 m, and 300 m for these three respective tracers. The corresponding values for case 2 were 290 m, 260 m, and 280 m. As concluded from Figures 2 and 3, a better estimate of the NBL height is obtained from the ozone profiles than from the temperature or humidity profiles, at least for this study environment. There is a limitation of the meteorological proxies, which are normally used to identify the height of the boundary layer in other studies and planetary locations, in the setting of the tropical forest because of strong evapotranspiration [29], leading in some profiles to insignificant differences in temperature and humidity between the surface and the top of the NBL. By comparison, the ozone concentration was a reliable tracer to probe the NBL height in 100% of the profiles for cases 1 and 2, representing 39 profiles in total. A chemical proxy like ozone has a strong advantage in the same setting of a tropical forest because of the surface sinks to forest vegetation under background conditions, as well as further chemical losses in polluted environments. For these several different reasons, the implication of Figure 5 is that the median NBL height estimated by potential temperature has a bias of +52 m for case 1 and 0 m for case 2, compared to retrieval of the NBL height according to ozone concentration. Correspondingly, the median NBL height estimated by specific humidity has respective bias of -30 m and -10 m for cases 1 and 2.



**Figure 5.** Box-whisker statistics plots of the height of the NBL during the wet season of 2018 based on (a) ozone concentration, (b) potential temperature, and (c) specific humidity for case 1 of a stratified atmosphere and case 2 of a turbulent atmosphere. Cases 1 and 2 correspond to 23 and 16 ozone profiles, respectively. For each box-whisker plot, the median (red line) of the combined data sets, quartiles (blue box edges), and the minimum and maximum values (black lines) are represented, excluding outliers. Local time (LT) is 4 h earlier than UTC.

Between cases 1 and 2, no statistically robust differences at the top of the NBL were found for ozone concentration, potential temperature, or specific humidity (Figure S2). This result might be expected because the values at the top of the NBL should correspond to the overlying atmosphere and thus might not be specifically related to the different case 1 and case 2 structures of the underlying NBL. Segregation of the data sets by hour from 20:00 to 00:00 (LT) also showed no trend (Table S2 and Figure S3), again as might be expected because the NBL rapidly develops after sunset at approximately 18:00. An analysis to test the association between predominant wind direction at the surface and the observed cases of stratified, turbulent, and complex atmospheres was inconclusive, which can be explained in part because of the weak nighttime surface winds ( $< 1 \text{ m s}^{-1}$ ).

The Cramer's  $V$  statistic [61] had a  $V$ -value of 0.50 and  $p$ -value of  $< 0.001$  (Table S3), indicating that the NBL structures strongly correlated with the sky conditions. More specifically, there was a 94% possibility that a stratified atmosphere occurred when clear skies prevailed, a 41% possibility of having a turbulent atmosphere under partly cloudy skies, and a 57% chance for a complex NBL structure when cloudy skies were present. These findings corroborate the stability regimes suggested by Malhi et al. [62], where the first regime is related to clear sky conditions (case 1). This regime corresponds to a stable boundary layer configuration characterized by weak or intermittent turbulence, leading to layer stratification along the vertical profile [62–67] and to a boundary layer top that is well-defined by an inflection point in potential temperature [66]. The second atmospheric regime of Malhi et al. is related to partly cloudy or cloudy sky conditions (case 2), which is classified as a weakly stable boundary layer because turbulence tends to be continuous and deep [55,63,65].

The NBL heights observed in this study in an urban region can be compared to earlier studies over rural areas, including forest and pasture surfaces, to explore the influence of the urban island

heat effect. Each surface type has distinct differences in energy partitioning, radiation balance, and aerodynamic roughness [68,69]. For the study herein over an urban region in the wet season, the quartiles of NBL heights were 230 to 350 m during time periods of a stratified atmosphere and 255 to 330 m during time periods of a turbulent atmosphere. Additional statistics are listed in Table 1. Earlier studies focused largely on the dry season [26] or the dry-to-wet transition season [16]. Santos [10], however, carried out measurements in the wet season. Over a forested region, the NBL height varied from 152 to 282 m between 18:00 and 22:00. Over a pasture region, the NBL height ranged from 210 to 227 m between 19:00 and 01:00. A weakly stable regime was common because of intense convective activity, cloudy skies, and slow surface cooling. Based on case 2 of the present study, an implication could be that the typical NBL over the forest is typically 50 to 100 m shallower than over the urban region. Over the pasture, the comparison suggests the typical NBL is 45 to 100 m shallower than over the urban region. For urban areas, in the absence of previous studies in a forested tropical city like Manaus, a comparison can be made to a report for a European city. Dupont et al. [70] reported the NBL height of 300 to 400 m, corroborating the present study. For further comparison, the Global Data Assimilation System [58] estimates the NBL height as 50 to 125 m at the UAV flight location across the period of study (Table S2), which is several hundred meters below the measured NBL heights (Figure S4), highlighting a need to further improve boundary layer representation.

An urban environment has many factors that distinguish it from forested and pasture regions, such as the high heat capacity of building materials, anthropogenic heat sources, the reduction of atmosphere evapotranspiration, and the retention of long-wave radiation due to the increase in atmospheric pollution [71,72]. The combined factors contribute to the urban heat island effect, defined as an increase in surface temperature in urban environments compared the temperature in rural zones. This relatively warmer over the urban region air rises higher, leading to greater vertical development and higher NBL heights and volume compared to pasture and forest regions [73,74]. The increased surface temperature and altered evapotranspiration likewise complicate the use of traditional meteorological tracers (i.e., potential temperature and specific humidity) to estimate NBL height in urban regions.

#### 4. Conclusions

In this study, an unmanned aerial vehicle equipped with a chemical sensing system was used to investigate the vertical profiles of nighttime ozone concentration during the wet season in an urban region of central Amazonian. The ozone concentration was observed to increase from the surface layer to the boundary layer top as a result of reactive dry deposition and chemical losses in the surface layer. The height of the nighttime boundary layer was retrieved based on the vertical ozone profiles. Quartiles of the NBL height varied from 255 to 350 m (cf. Table 1). These estimates are consistent with results from concurrent measurements of specific humidity and potential temperature. The data set presented herein and the new findings highlight the possibilities of improved atmospheric measurements made possible by UAVs as well as the importance of chemical tracers for boundary layer characterization when physical tracers such as specific humidity and potential temperature face challenges, such as over forested regions of high evapotranspiration. The results herein also highlight

shortcomings with respect to many models that have been developed for nighttime atmospheric chemistry and which do not typically include NBL mixing processes, especially for urban regions.

**Supplementary Materials:** The following is available online at [www.mdpi.com/xxx/s1](http://www.mdpi.com/xxx/s1). Figure S1: Vertical profiles of ozone concentration, potential temperature, and specific humidity from surface to 500 m. The case classification of each data set is provided in the inset text. Classifications include (case 1) a normal, undisturbed, stratified nighttime atmosphere based in 23 ozone profiles, (case 2) a turbulently mixing atmosphere based in 16 ozone profiles, and (case 3) a complex atmosphere characterized by both stratified and turbulent components based in 18 ozone profiles. The case classification is discussed in the main text (Section 3). The height of NBL based in ozone concentration is showed (grey color). The dotted line represents the limit of detection for ozone (3 ppb). The horizontal bars represent measurement uncertainty. Local time (LT) is 4 h earlier than UTC. Figure S2: Box-whisker statistics plots of (a) ozone concentration, (b) potential temperature, and (c) specific humidity at the top of the NBL during the wet season of 2018. Results are shown for (case 1) a stratified atmosphere based in 23 ozone profiles and (case 2) a turbulent atmosphere based in 16 ozone profiles. For each box-whisker plot, the median (red line) of the combined data sets, quartiles (blue box edges), and the minimum and maximum values (black lines) are represented, excluding outliers. Figure S3: Vertical profiles of ozone concentration segregated by hour from 20:00 to 00:00 (LT) for the combined data set of case 1 (i.e., normal stratified atmospheres) based in 23 profiles. Local time (LT) is 4 h earlier than UTC. Figure S4: Boundary layer heights segregated by hour from 20:00 to 00:00 (LT) as (blue color) determined by the UAV measurements of this study and as (green color) reported for the Global Data Assimilation System. [58] Local time (LT) is 4h earlier than UTC. Figure S5: Calibration curve for the POM with calibration factors of  $S = 1.00$  and  $Z = +1$  ppbv applied. Table S1: Summary of studies of the NBL in Amazonia, usually between 18:00 and 00:00 LT. Table S2: Summary of flights and the estimated NBL heights for the period from 19 March 2018 to 11 May 2018 at 3.0918° S and 60.0175° W in the urban area of Manaus. Local time (LT) is 4 h earlier than UTC. Wind and wind velocity are from a weather station at ground level. The estimated NBL heights are based on profile cases 1 or 2 (see main text). “N/A” denotes that no estimate was made. The NBL height is also estimated by the Global Data Assimilation System 51 applied to the UAV flight location. The system stability classification is also listed. Table S3: Results of Cramer’s V analysis for the association between the structures of the observed profiles (i.e., cases 1, 2, and 3) and sky conditions (i.e., clear, partly cloudy, and cloudy). Table S4: Comparison of data collection characteristics of radiosondes, tethered balloons, and copter unmanned aerial vehicles (UAVs) for typical measurements of potential temperature, specific humidity, and ozone. For comparison purposes, the height between readings, the number of data points, and the time period to collect data correspond to an altitude profile from 0 to 500 m. The UAV characteristics are for the operational conditions of this study. The characteristics of radiosondes and tethered balloons are adapted from Balsley et al. [75].

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## *Supporting Information*

# **Vertical profiles of ozone concentration collected by an unmanned aerial vehicle and the mixing of the nighttime boundary layer over an Amazonian urban area**

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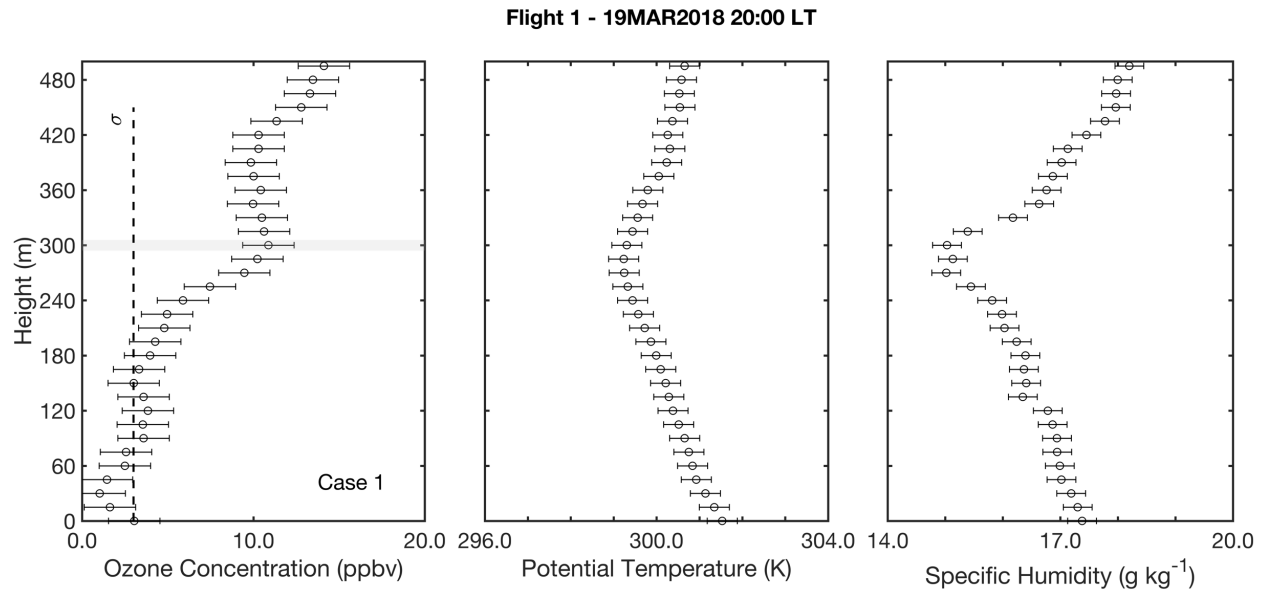
<sup>4</sup> Department of Earth and Planetary Sciences, Harvard University, Cambridge, Massachusetts, 02138, USA; scot\_martin@harvard.edu (S.M.)

\* Correspondence: scot\_martin@harvard.edu; souzaraf@gmail.com. Tel.: +1-617-495-0627 (S.M.); +55-92 98815-2749 (R.S.);

Total SI pages: 67

Total Figures: 5

Total Tables: 4



**Figure S1.** Vertical profiles of ozone concentration, potential temperature, and specific humidity from surface to 500 m. The case classification of each data set is provided in the inset text. Classifications include (case 1) a normal, undisturbed, stratified nighttime atmosphere based in 23 ozone profiles, (case 2) a turbulently mixing atmosphere based in 16 ozone profiles, and (case 3) a complex atmosphere characterized by both stratified and turbulent components based in 18 ozone profiles. The case classification is discussed in the main text (Section 3). The height of NBL based in ozone concentration is showed (grey color). The dotted line represents the limit of detection for ozone (3 ppb). The horizontal bars represent measurement uncertainty. Local time (LT) is 4 h earlier than UTC.

Flight 2 - 19MAR2018 20:30 LT

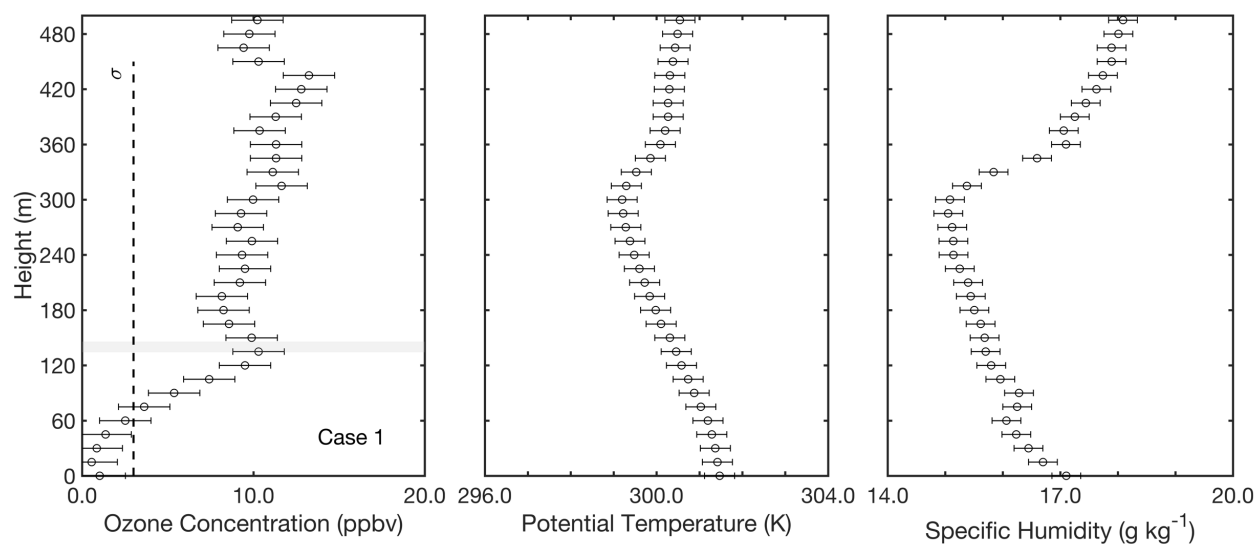


Figure S1 (continued).

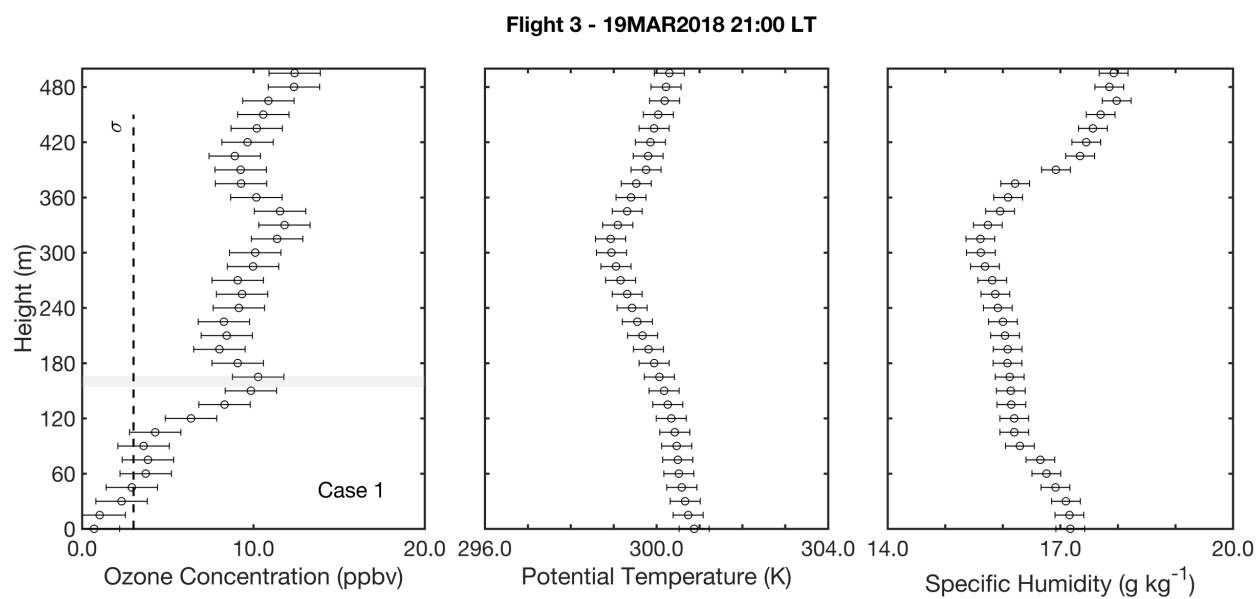


Figure S1 (continued).

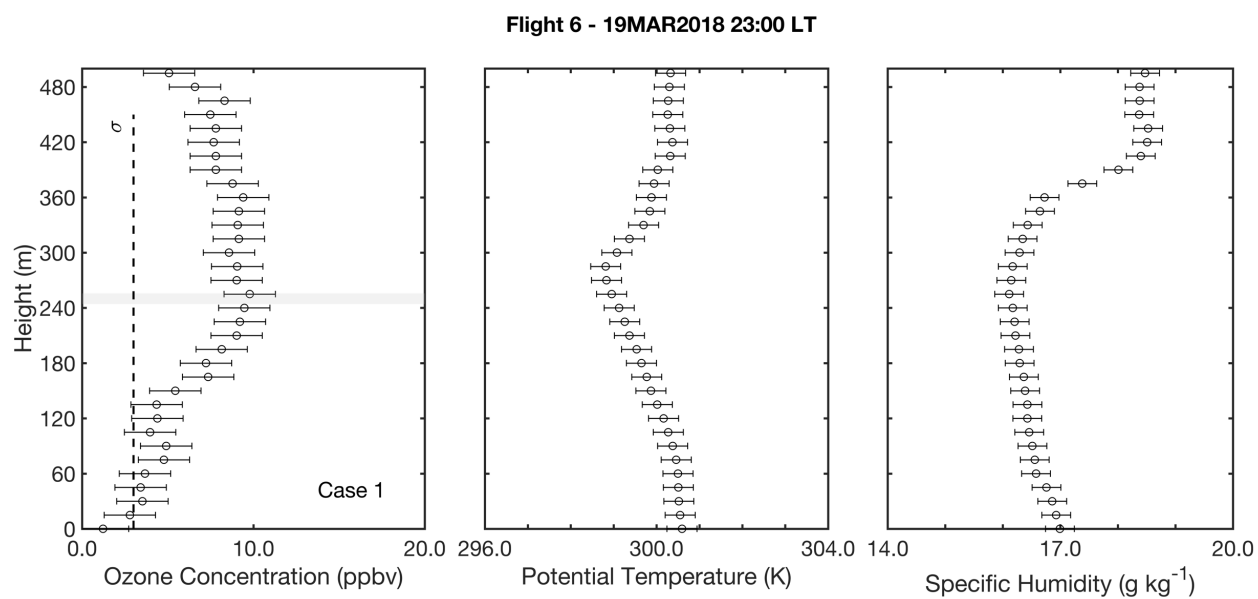
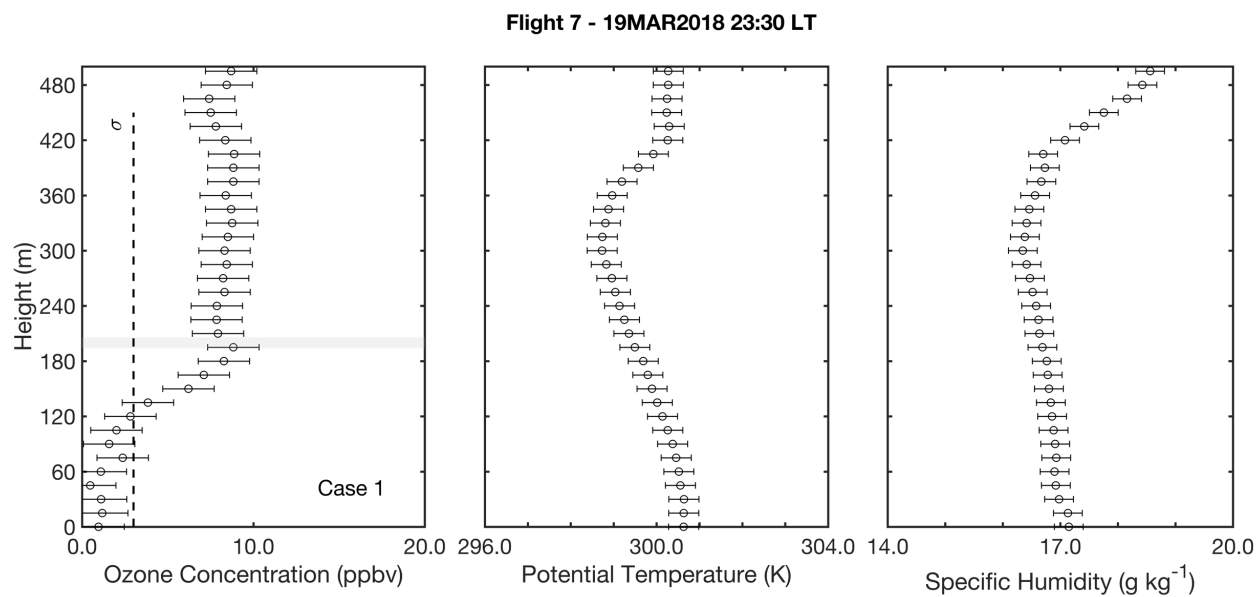


Figure S1 (continued).



**Figure S1 (continued).**

Flight 9 - 20MAR2018 21:00 LT

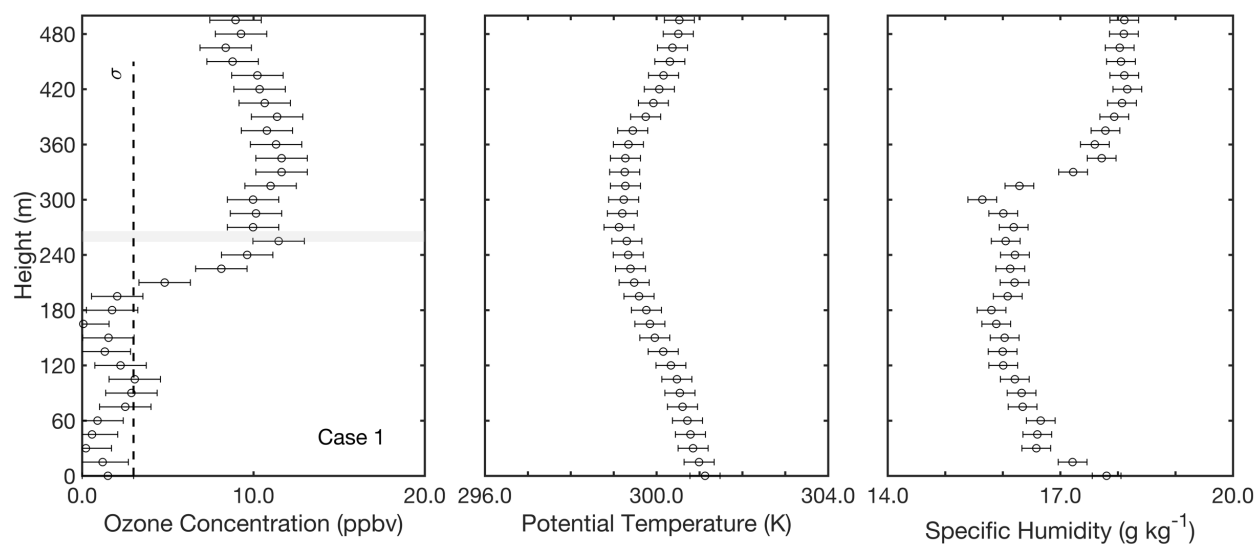
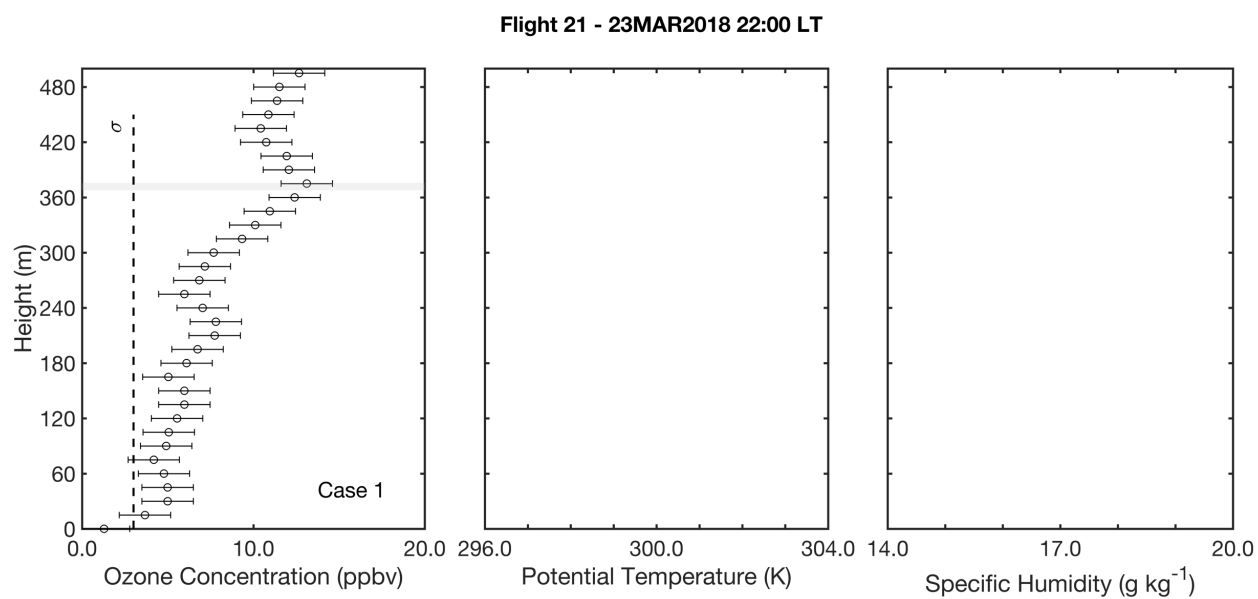
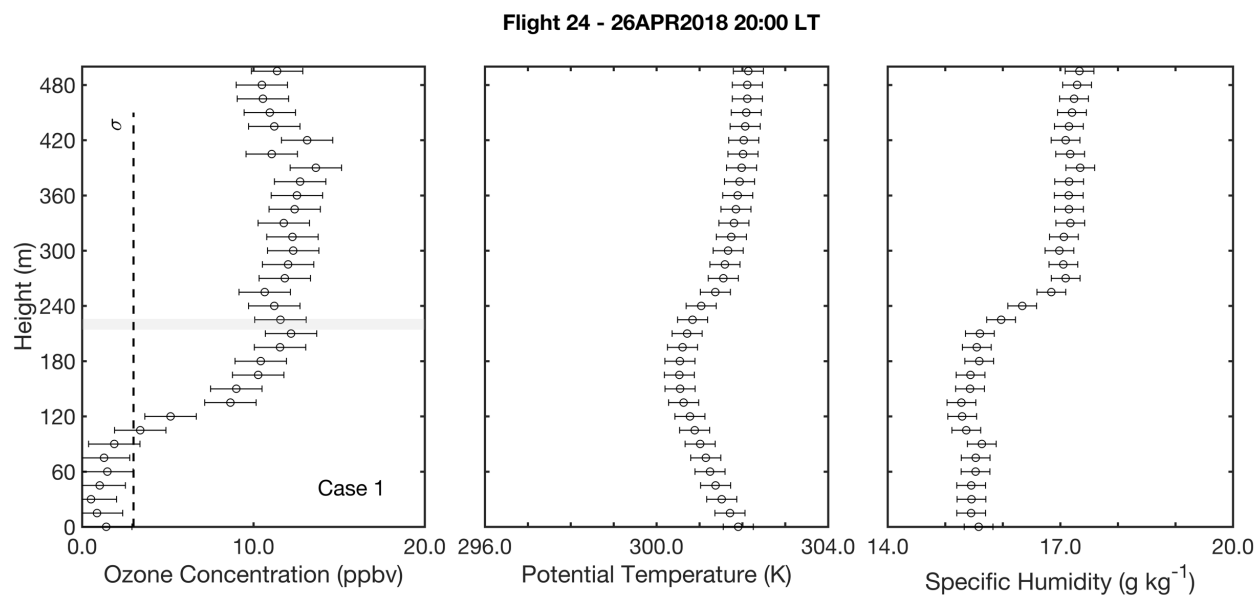


Figure S1 (continued).



**Figure S1 (continued).**



**Figure S1 (continued).**

Flight 31 - 7MAY2018 20:30 LT

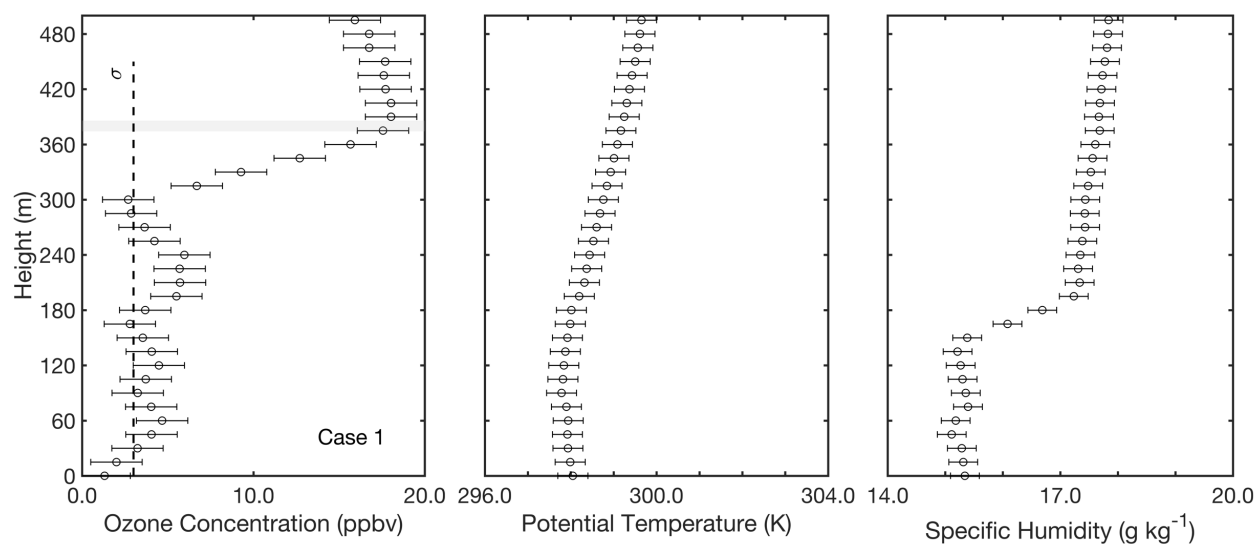
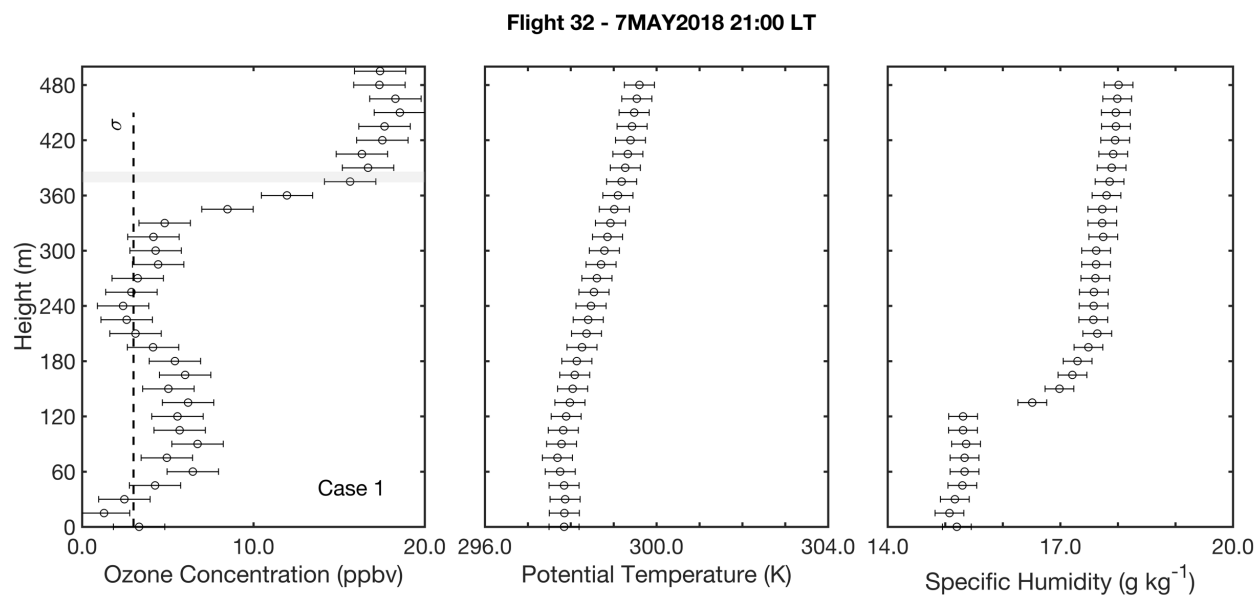


Figure S1 (continued).



**Figure S1 (continued).**

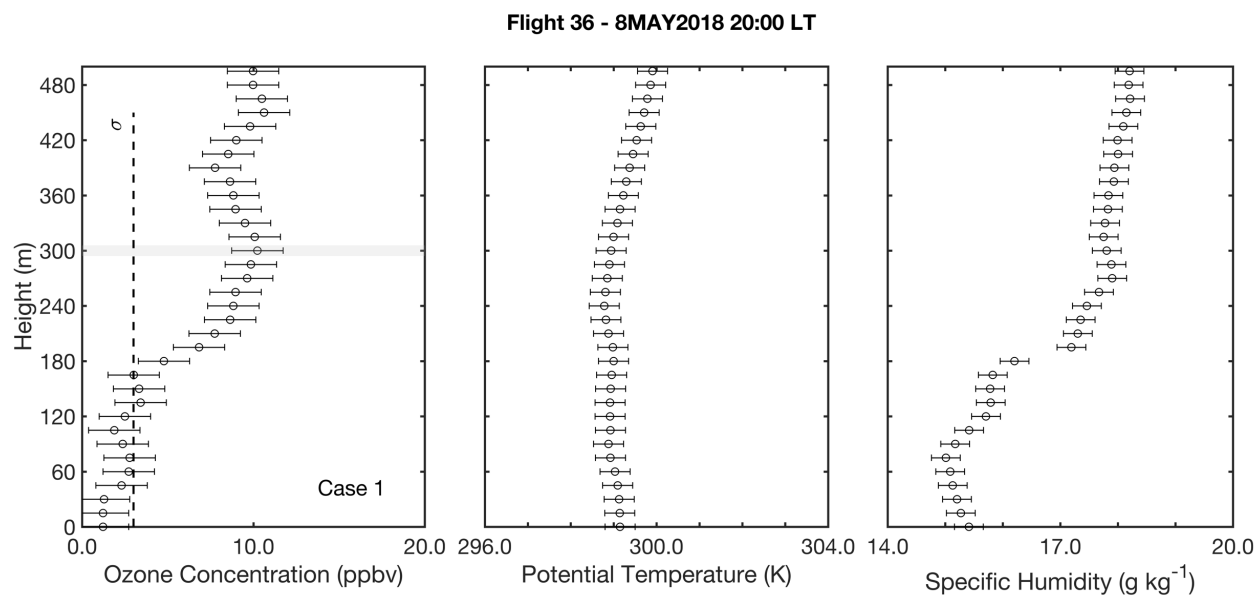


Figure S1 (continued).

Flight 38 - 8MAY2018 21:00 LT

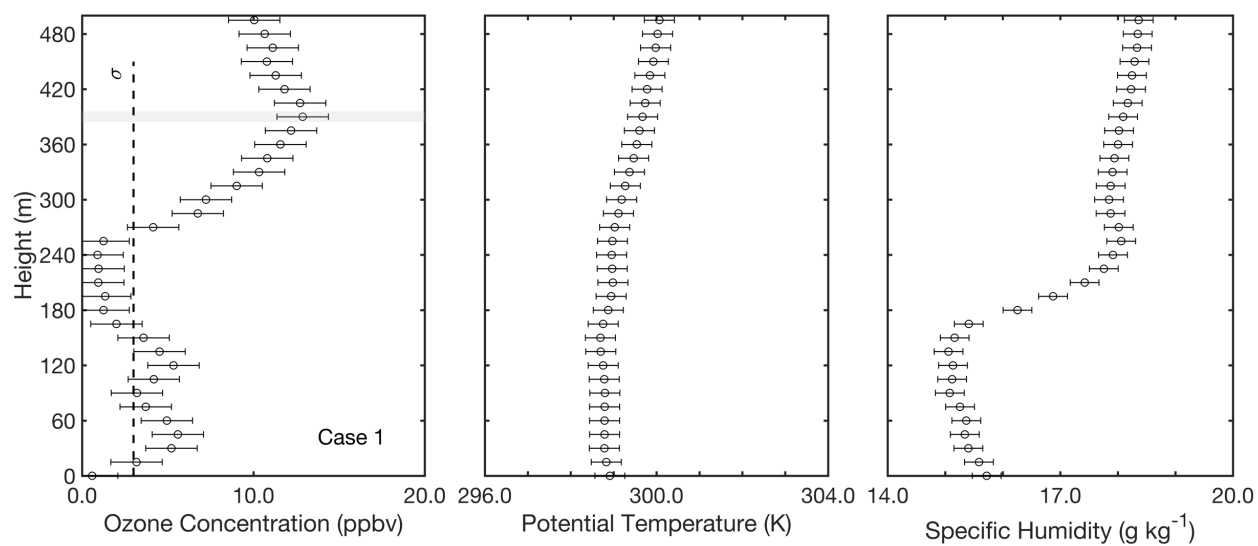


Figure S1 (continued).

Flight 39 - 8MAY2018 22:00 LT

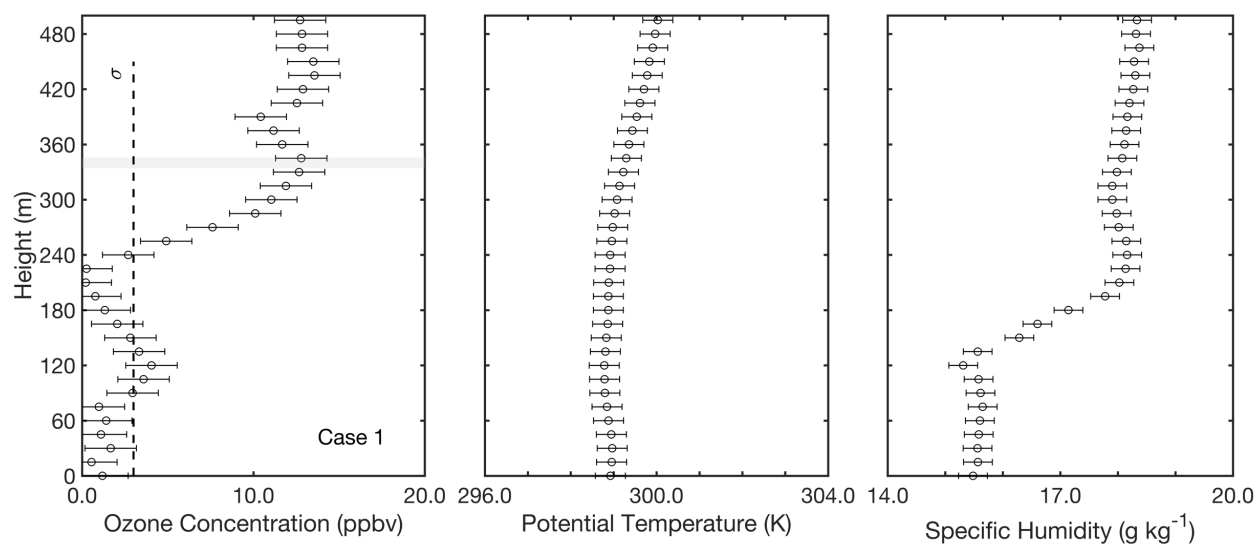


Figure S1 (continued).

Flight 42 - 8MAY2018 23:30 LT

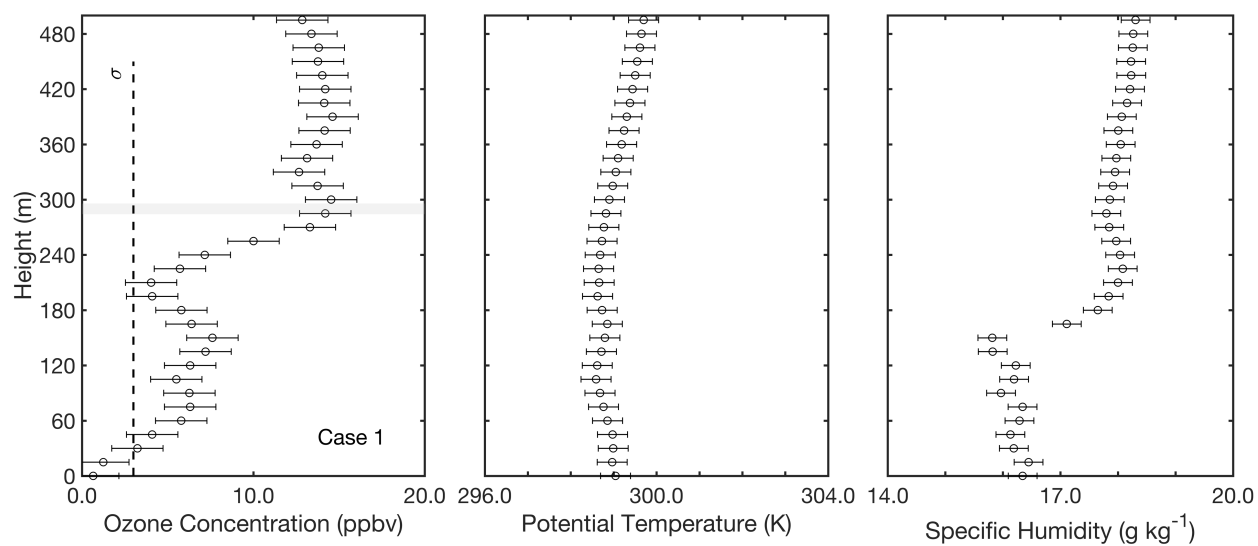
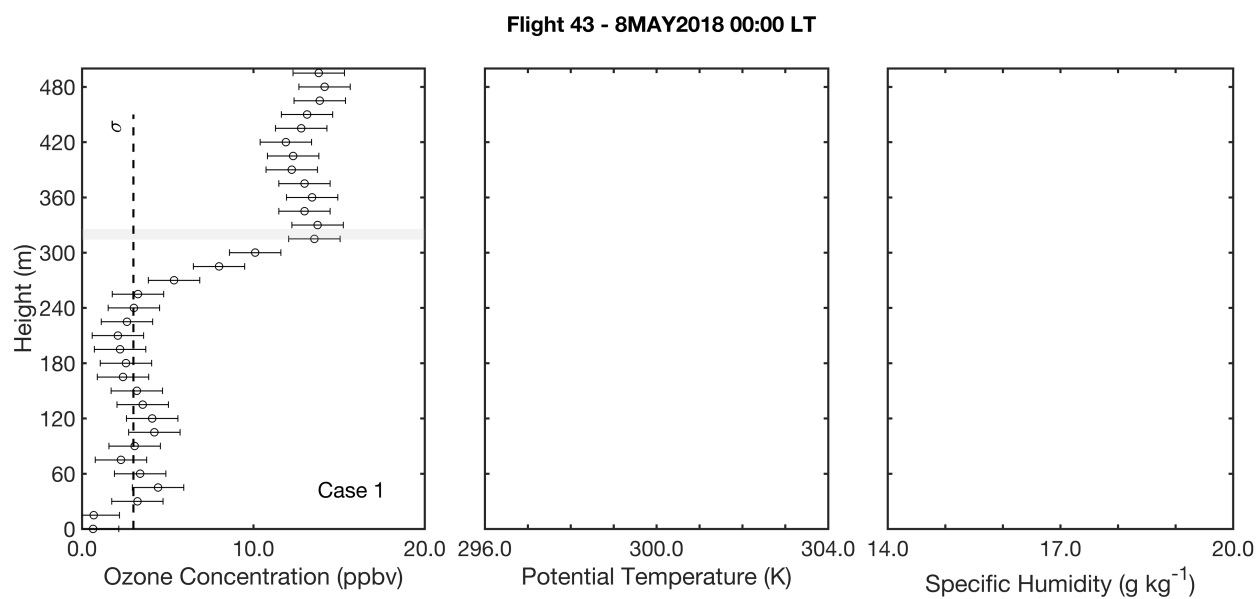
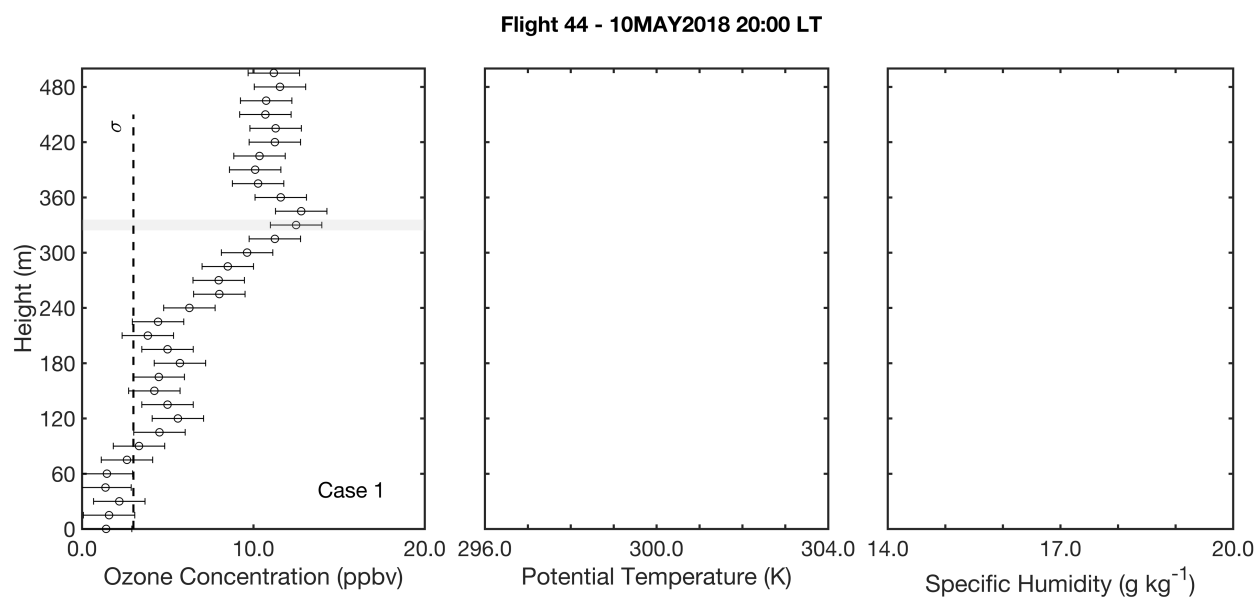


Figure S1 (continued).



**Figure S1 (continued).**



**Figure S1 (continued).**

Flight 49 - 10MAY2018 23:30 LT

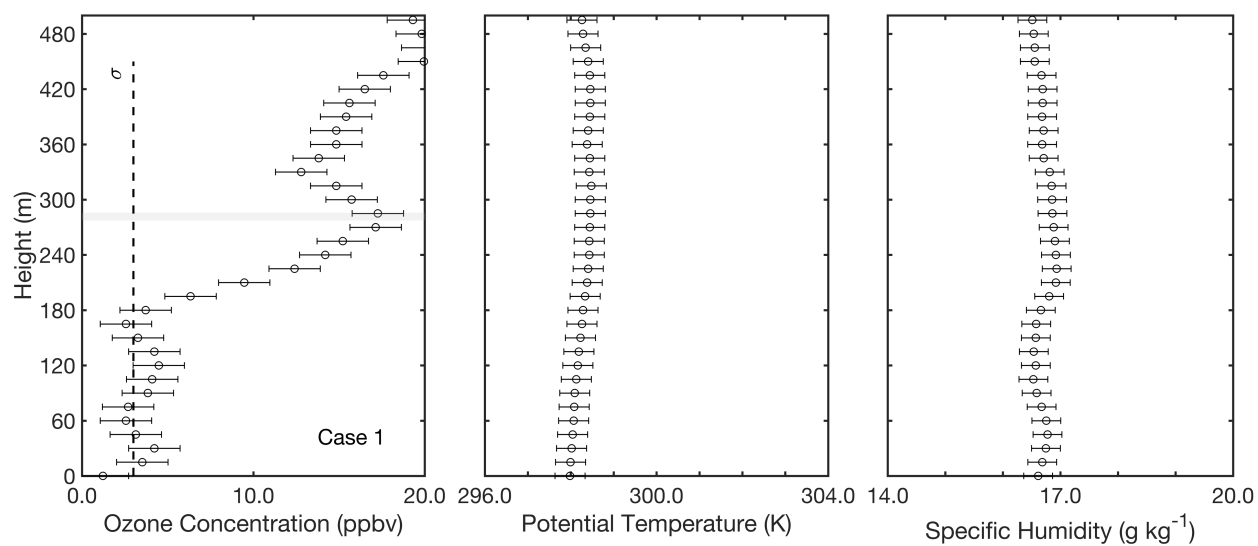
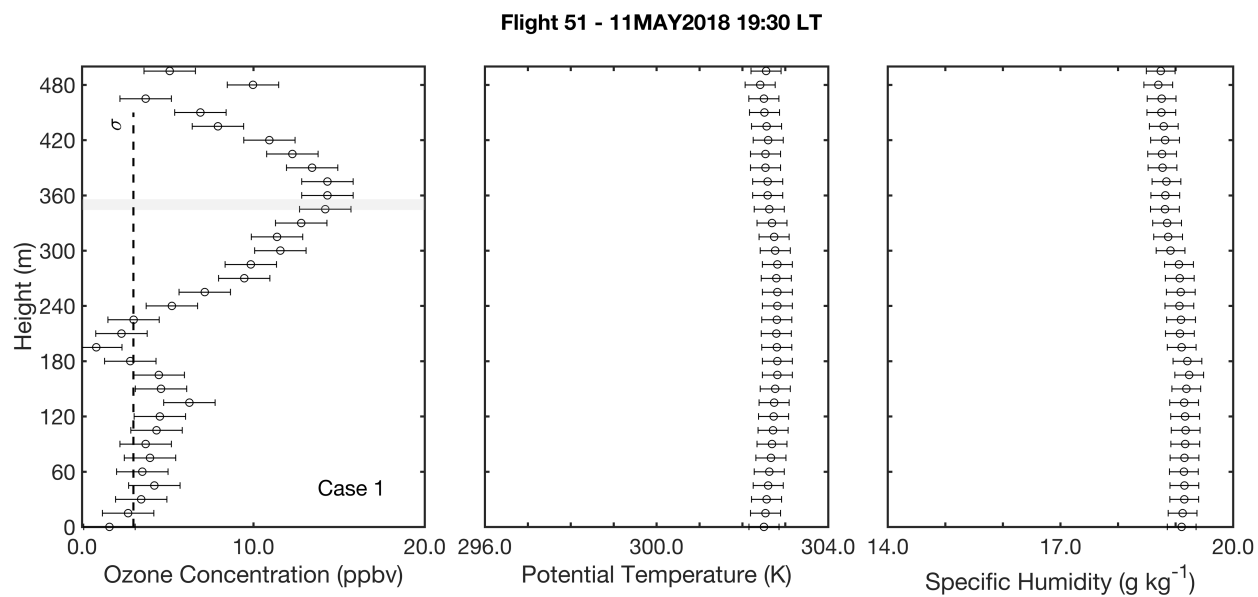
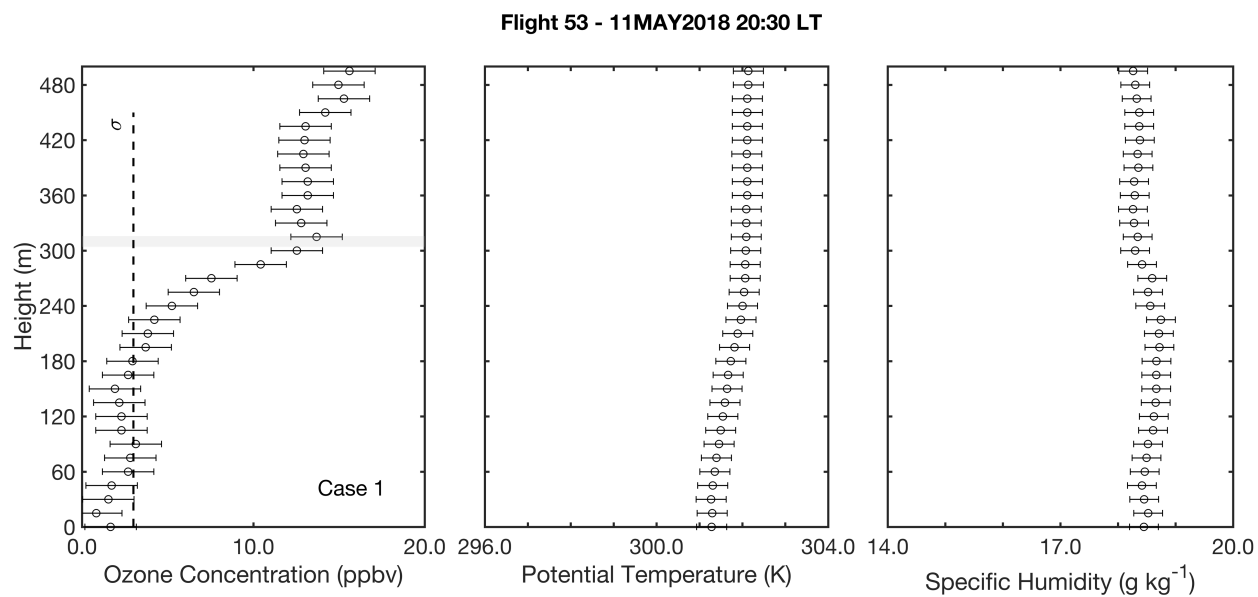


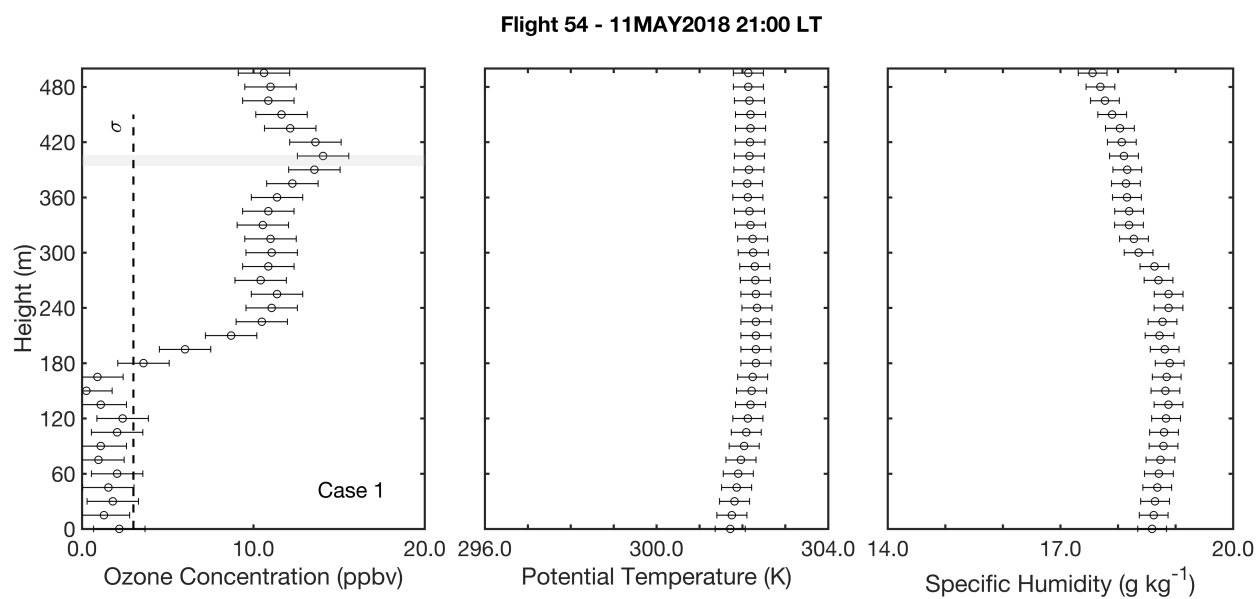
Figure S1 (continued).



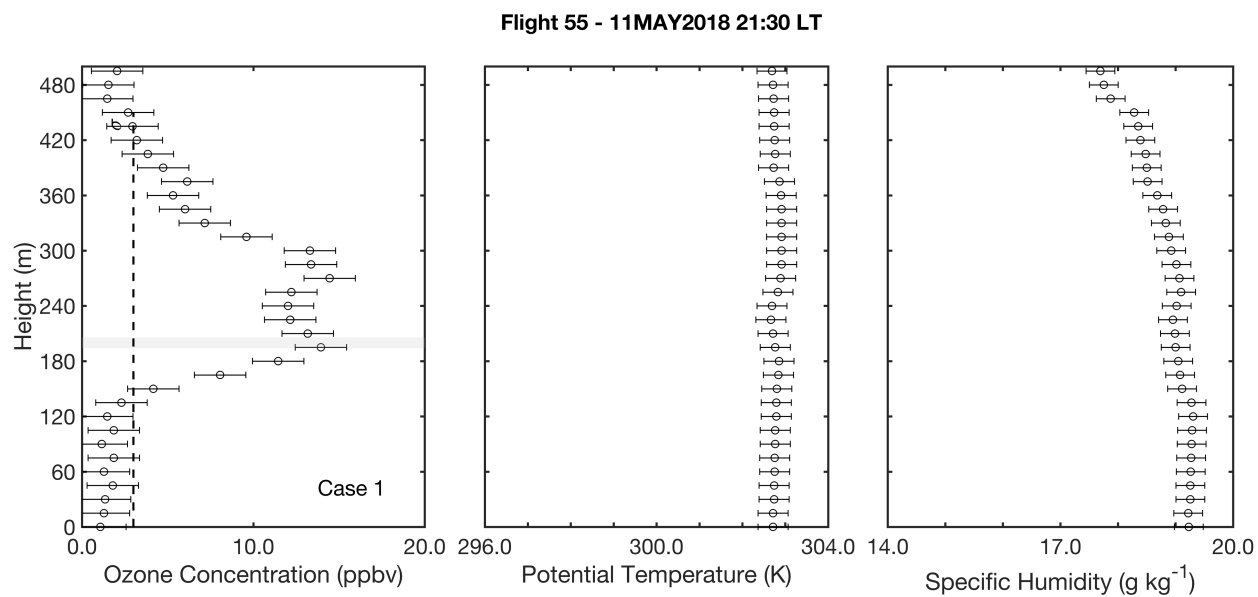
**Figure S1 (continued).**



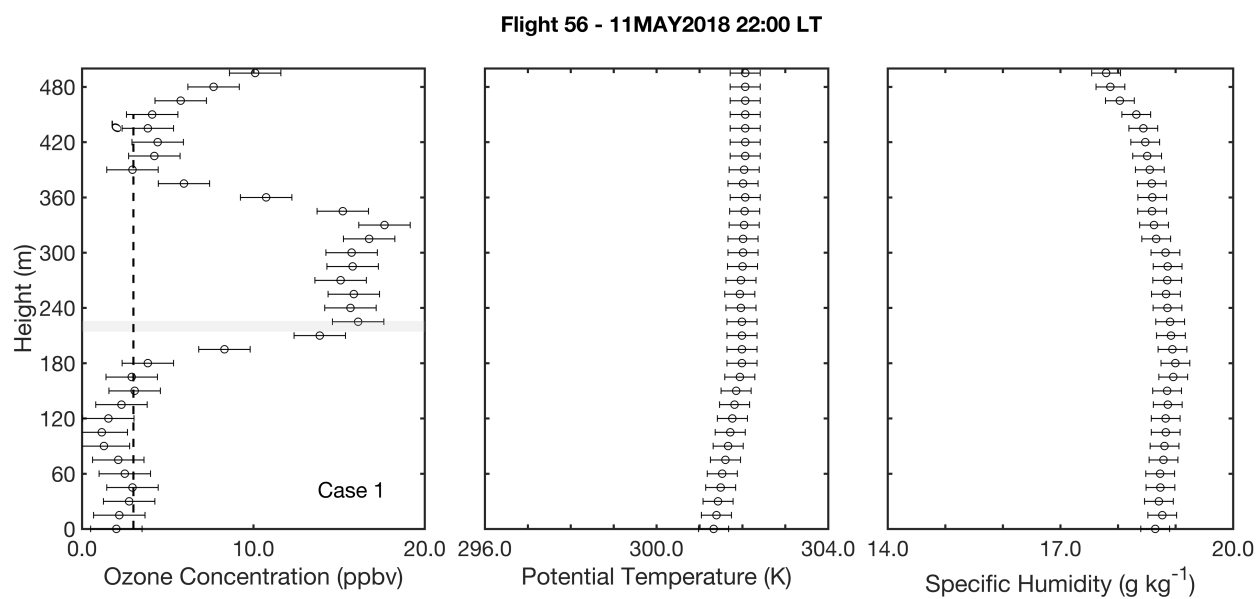
**Figure S1 (continued).**



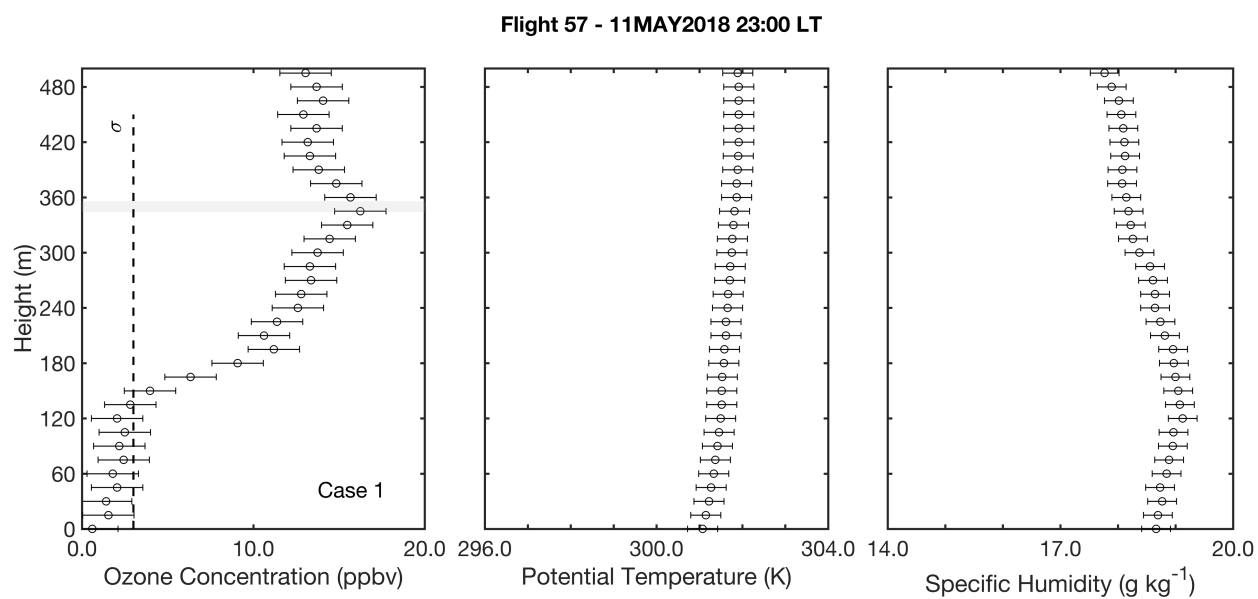
**Figure S1 (continued).**



**Figure S1 (continued).**



**Figure S1 (continued).**



**Figure S1 (continued).**

Flight 4 - 19MAR2018 22:00 LT

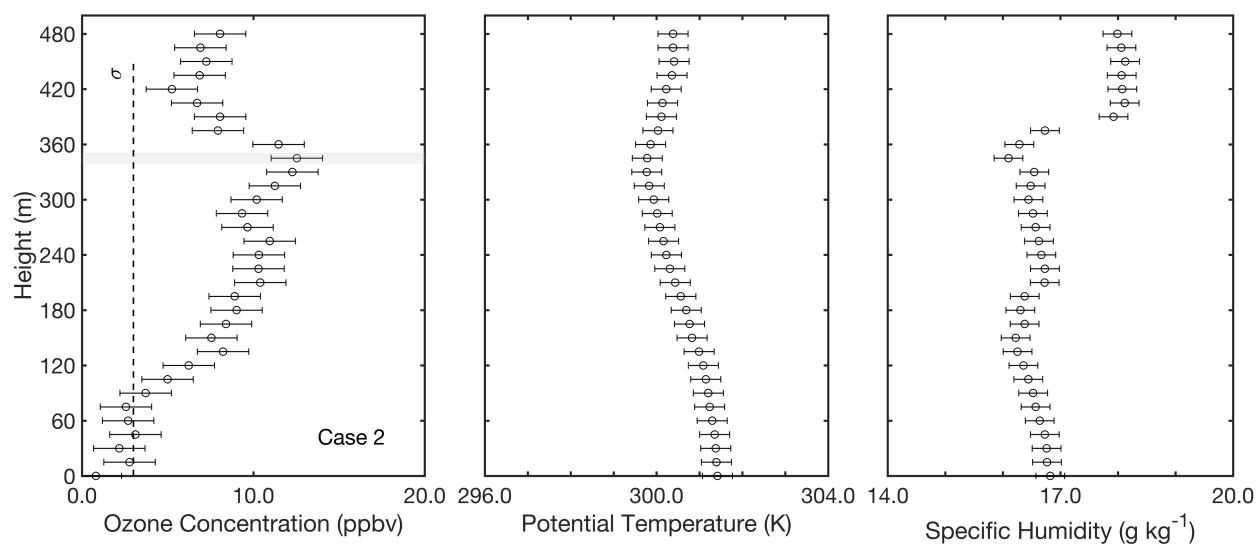
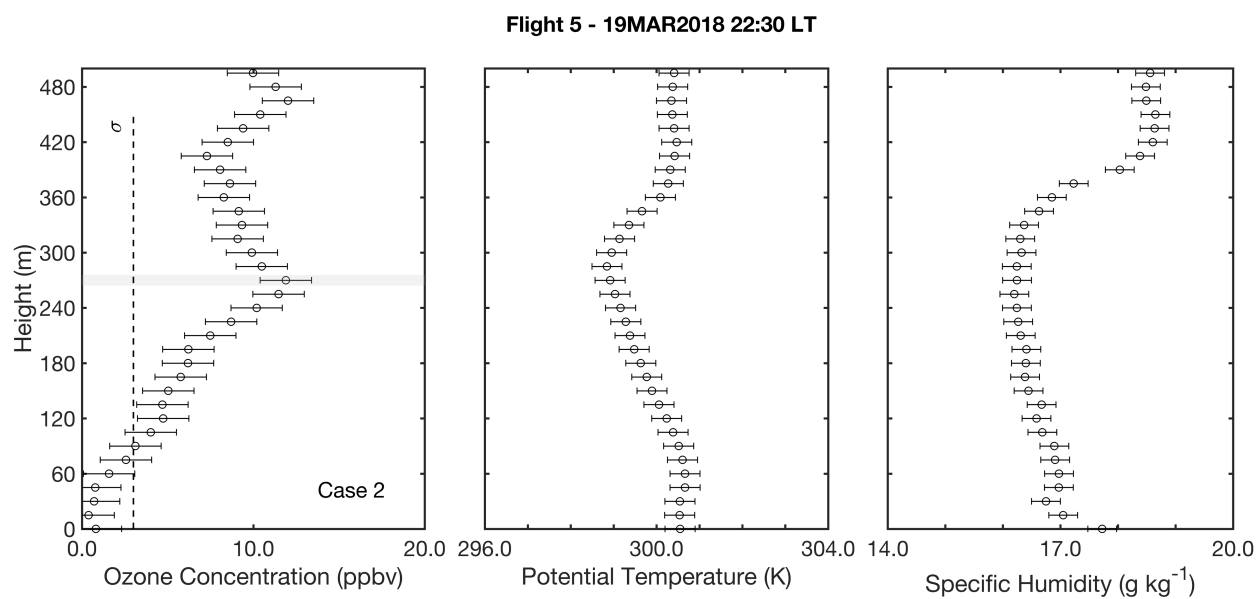


Figure S1 (continued).



**Figure S1 (continued).**

Flight 11 - 22MAR2018 20:30 LT

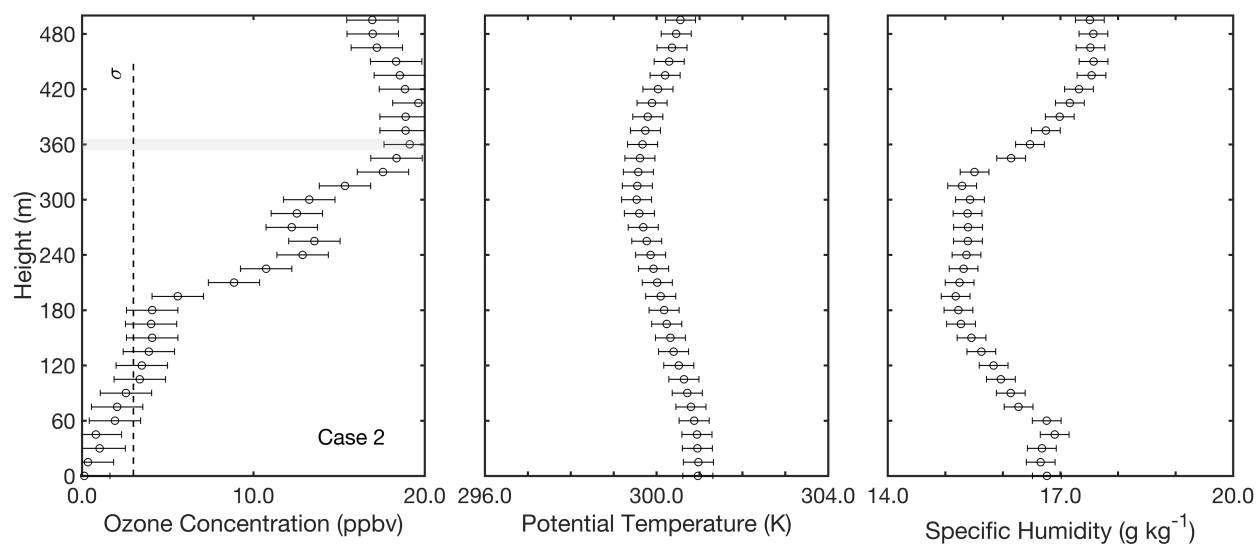


Figure S1 (continued).

Flight 12 - 22MAR2018 21:00 LT

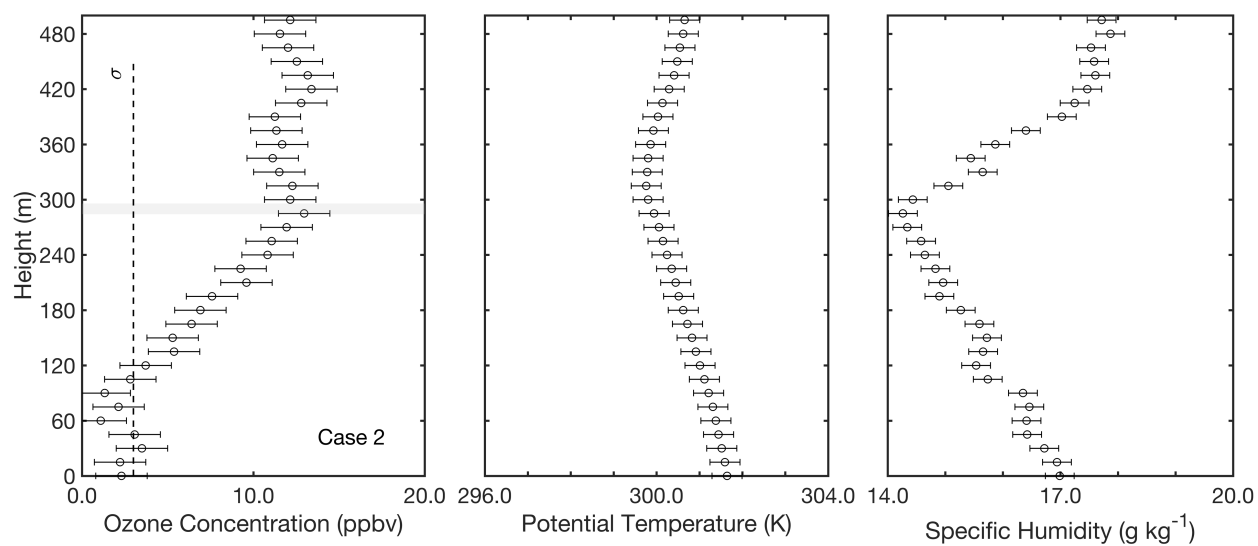


Figure S1 (continued).

Flight 13 - 22MAR2018 22:00 LT

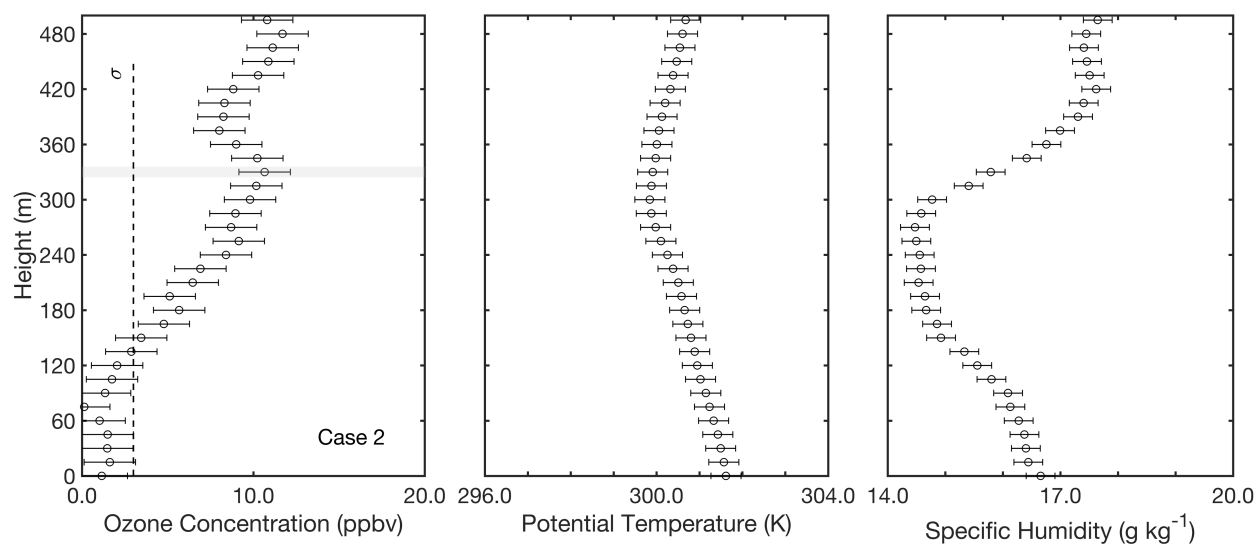


Figure S1 (continued).

Flight 15 - 22MAR2018 23:00 LT

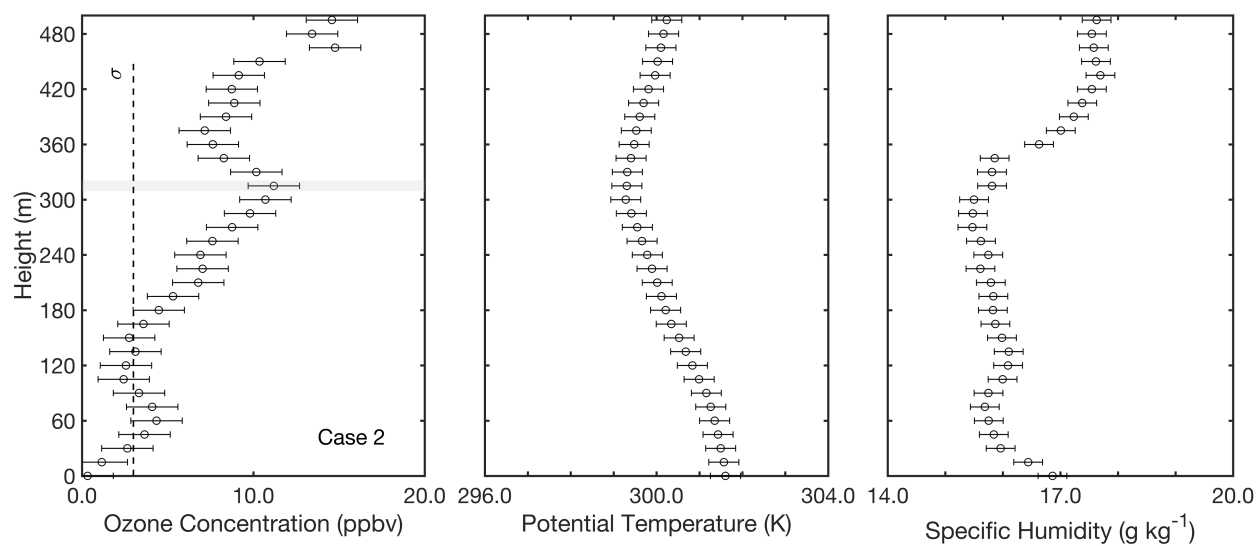


Figure S1 (continued).

Flight 16 - 22MAR2018 23:30 LT

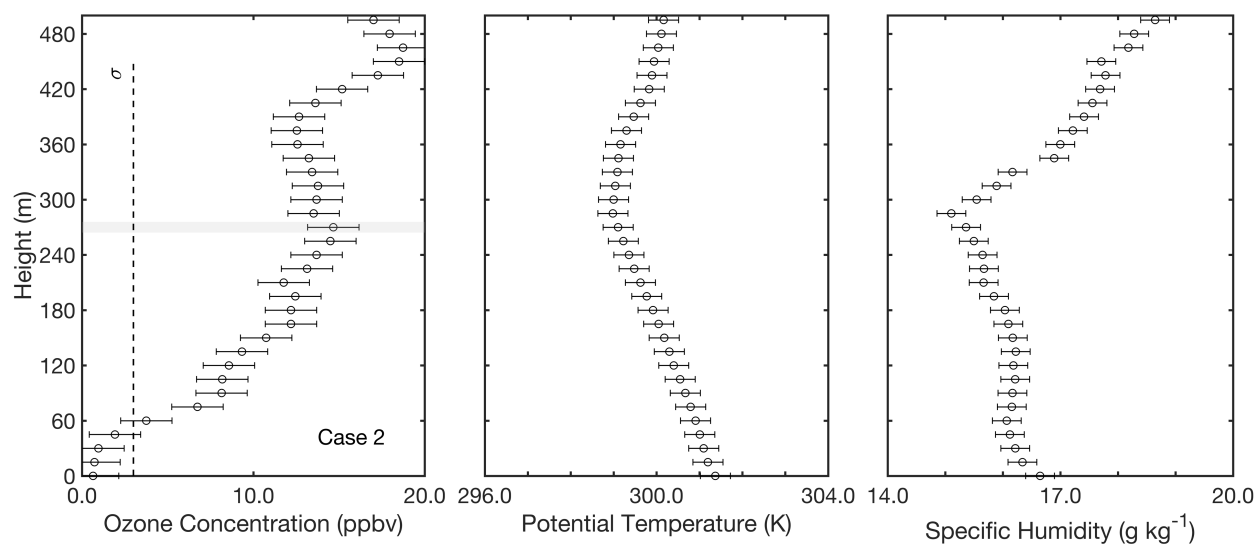


Figure S1 (continued).

Flight 25 - 26APR2018 20:30 LT

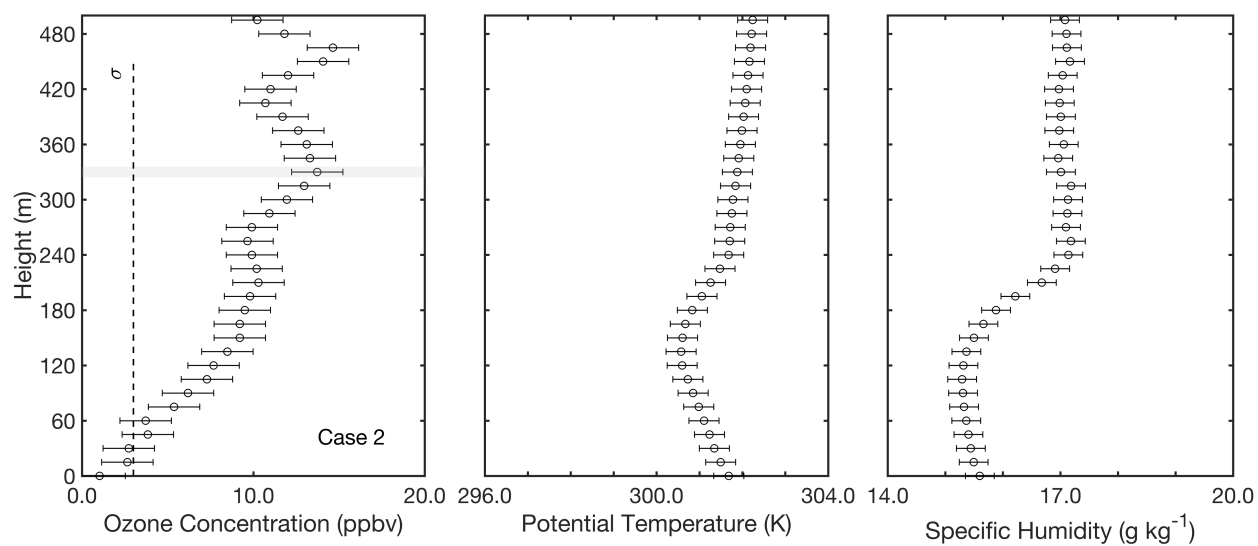
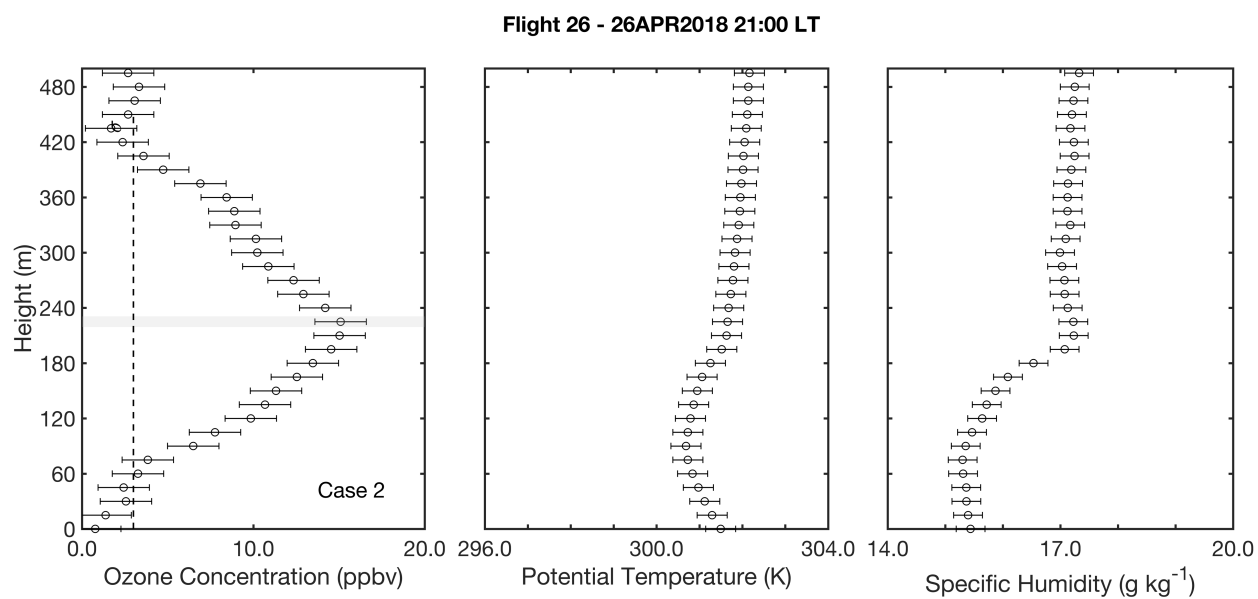


Figure S1 (continued).



**Figure S1 (continued).**

Flight 27 - 26APR2018 21:30 LT

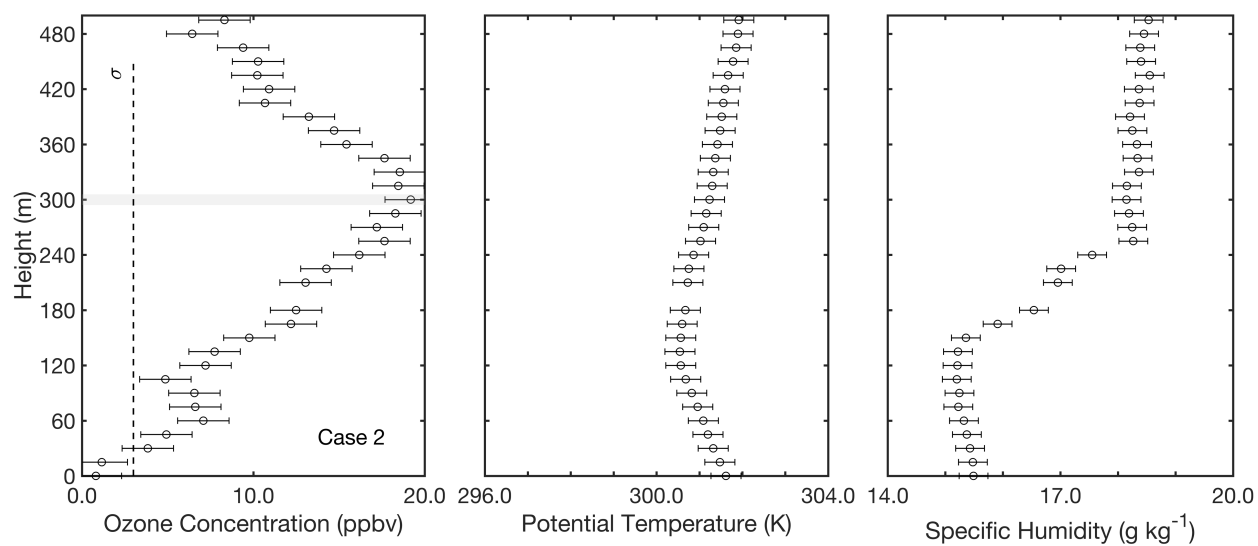


Figure S1 (continued).

Flight 37 - 8MAY2018 20:30 LT

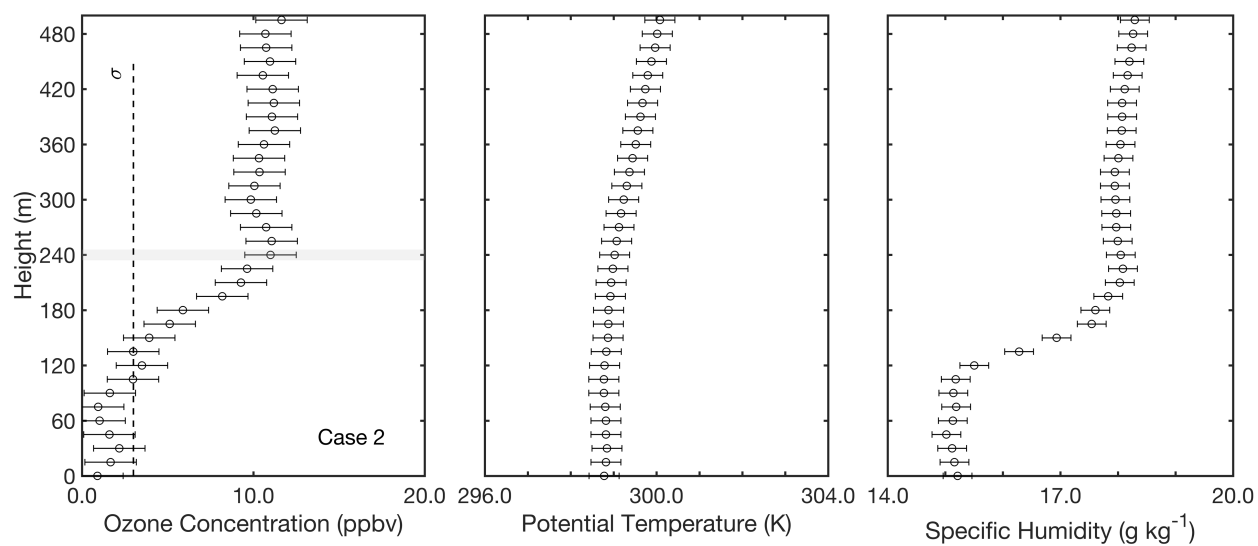
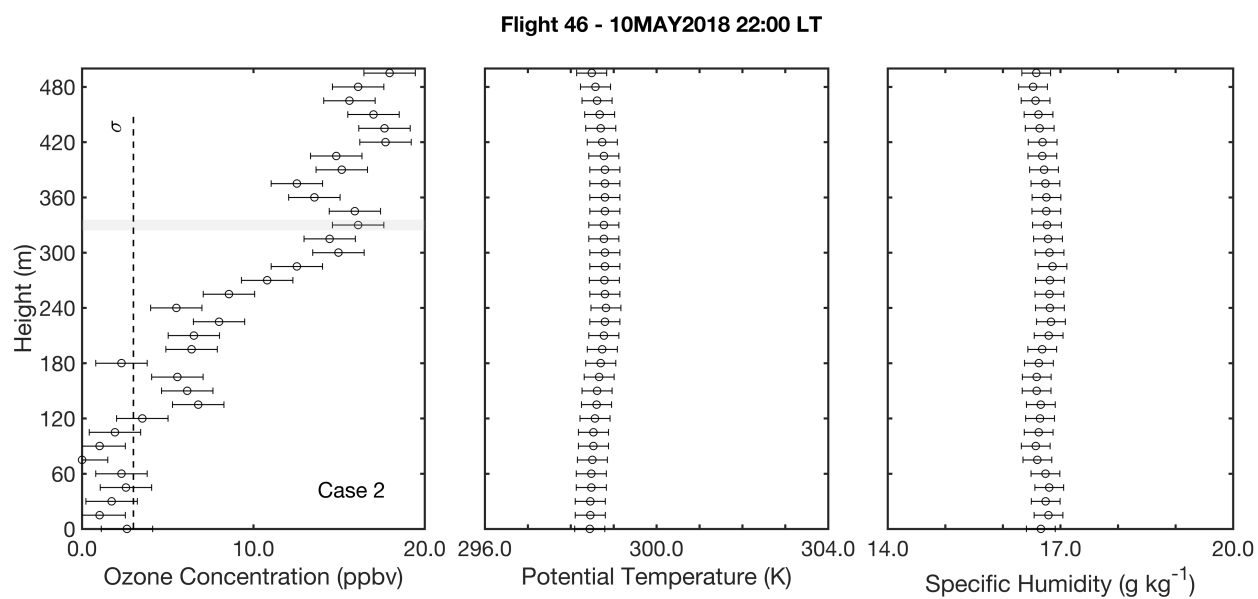
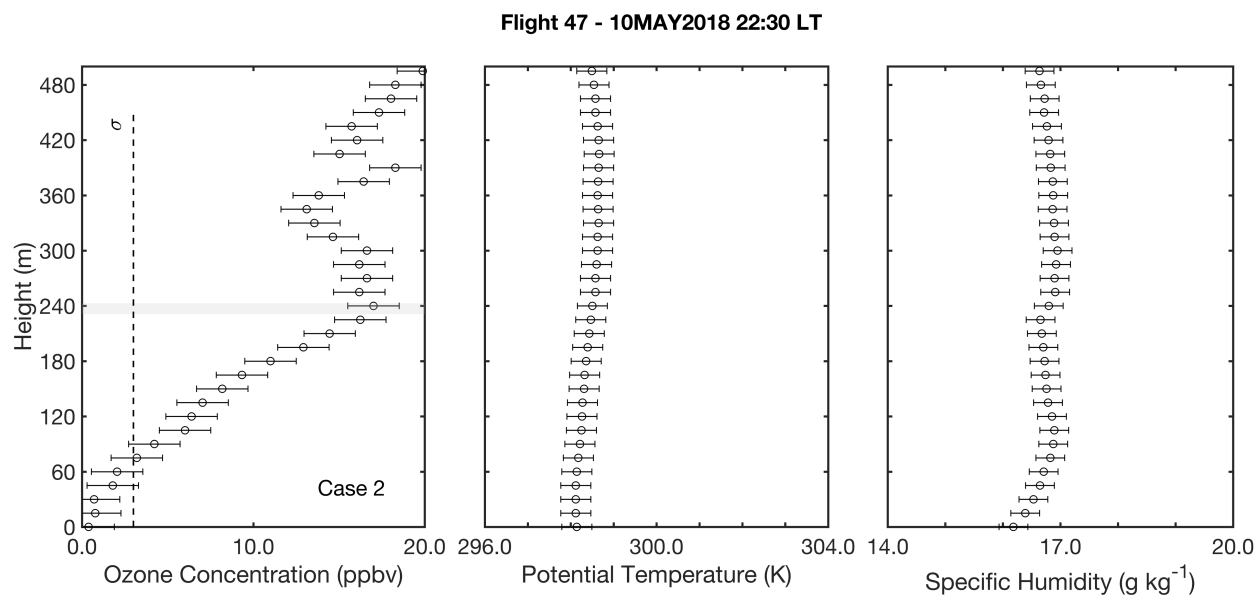


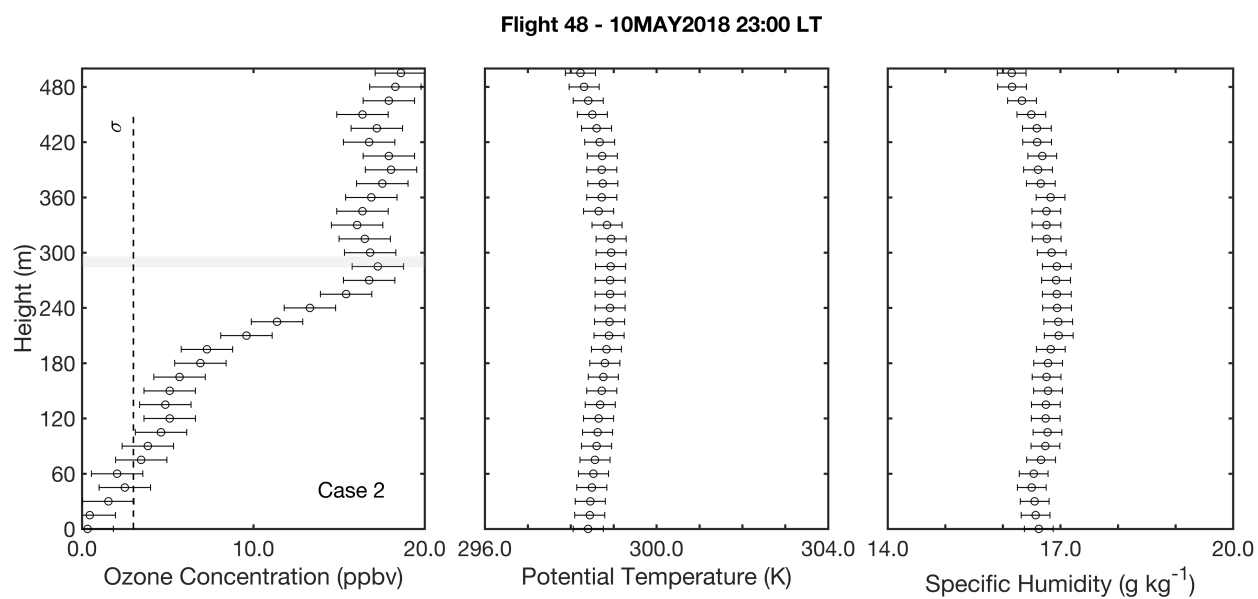
Figure S1 (continued).



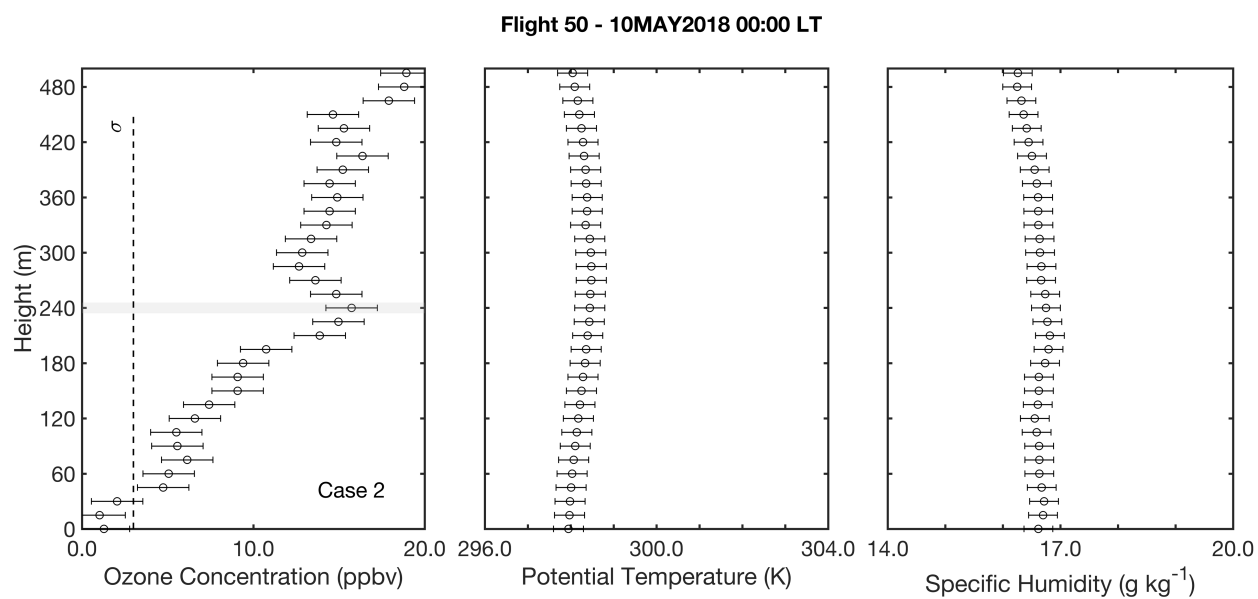
**Figure S1 (continued).**



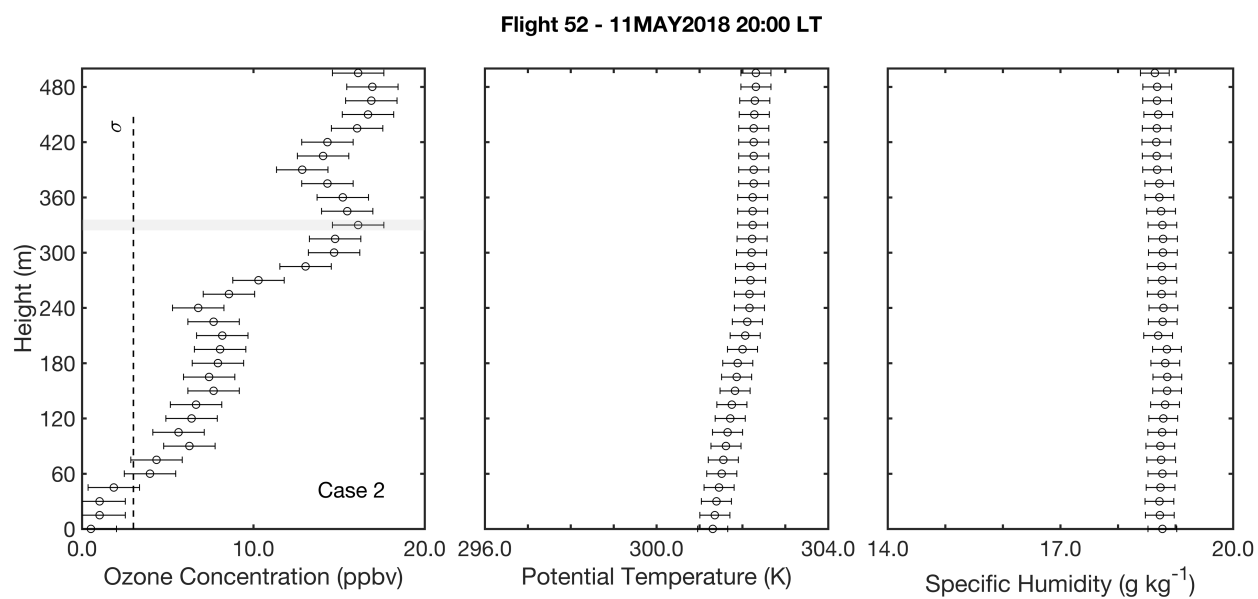
**Figure S1 (continued).**



**Figure S1 (continued).**



**Figure S1 (continued).**



**Figure S1 (continued).**

Flight 8 - 20MAR2018 20:30 LT

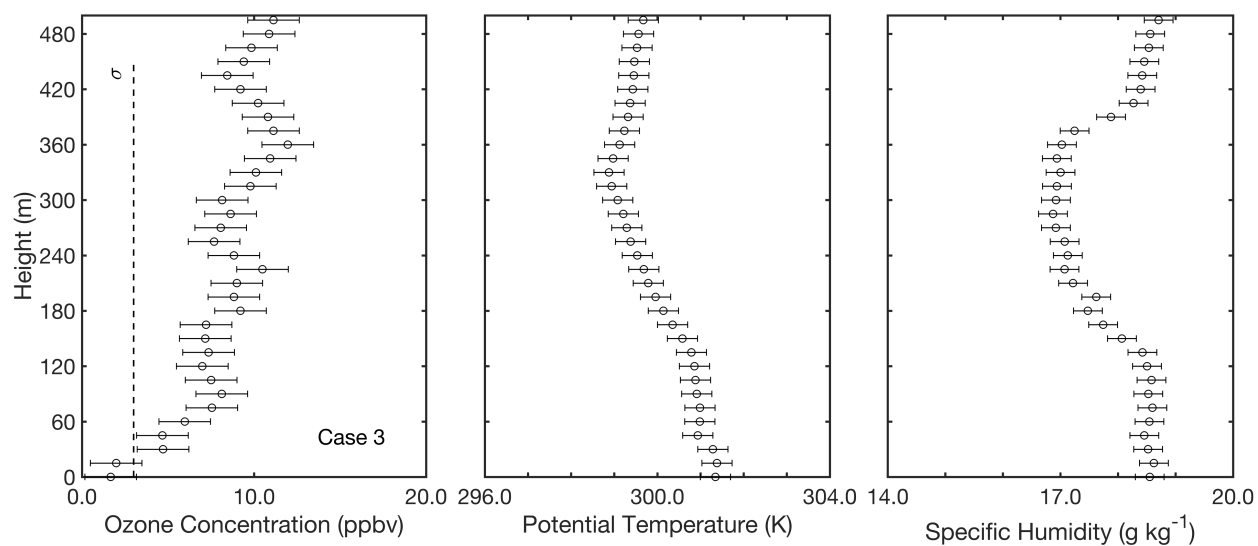
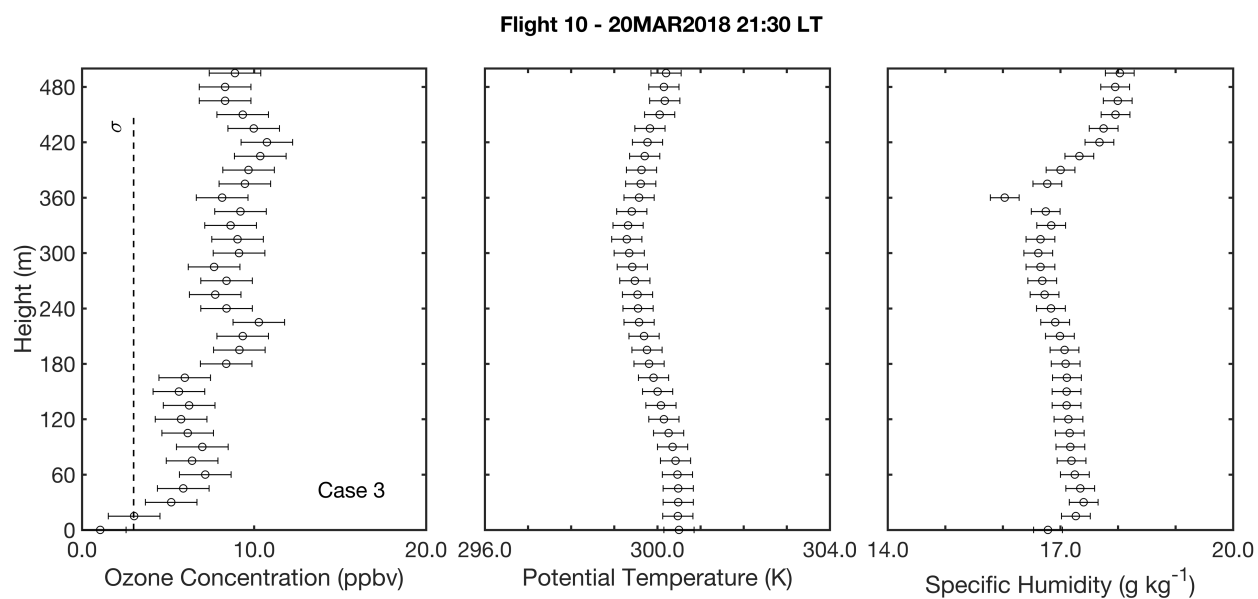


Figure S1 (continued).



**Figure S1 (continued).**

Flight 14 - 22MAR2018 22:30 LT

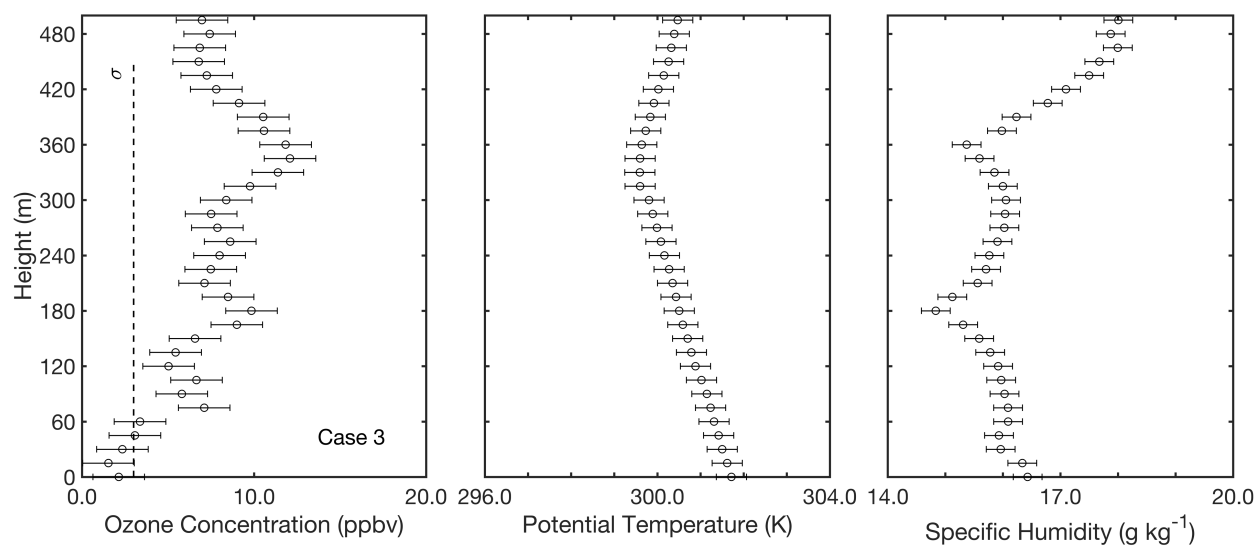
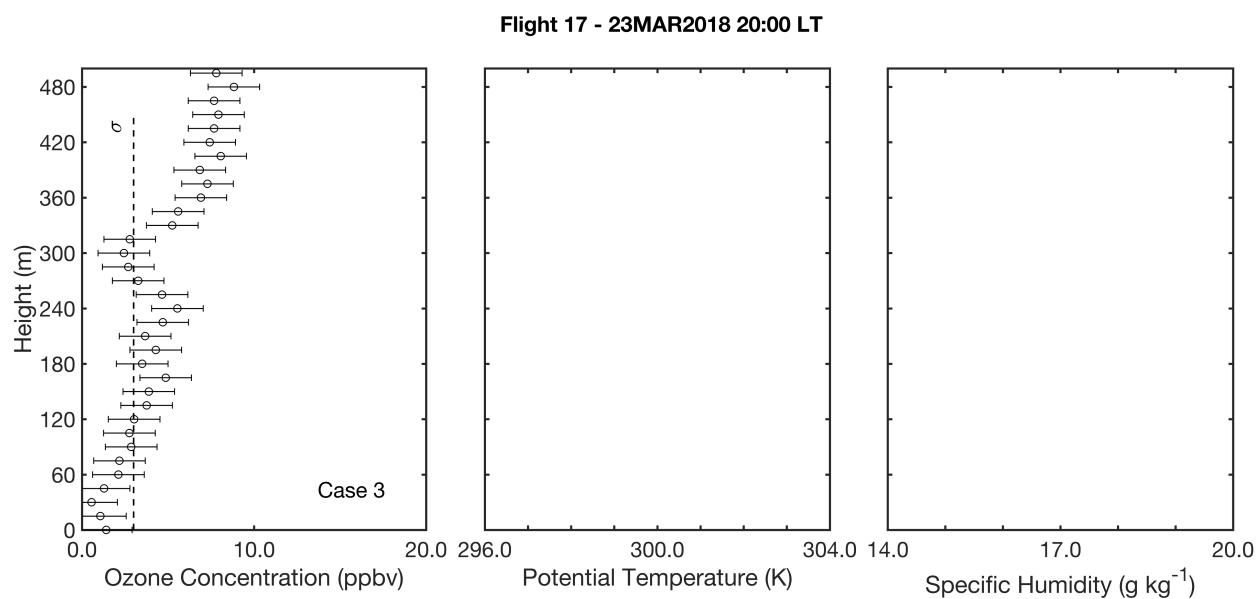
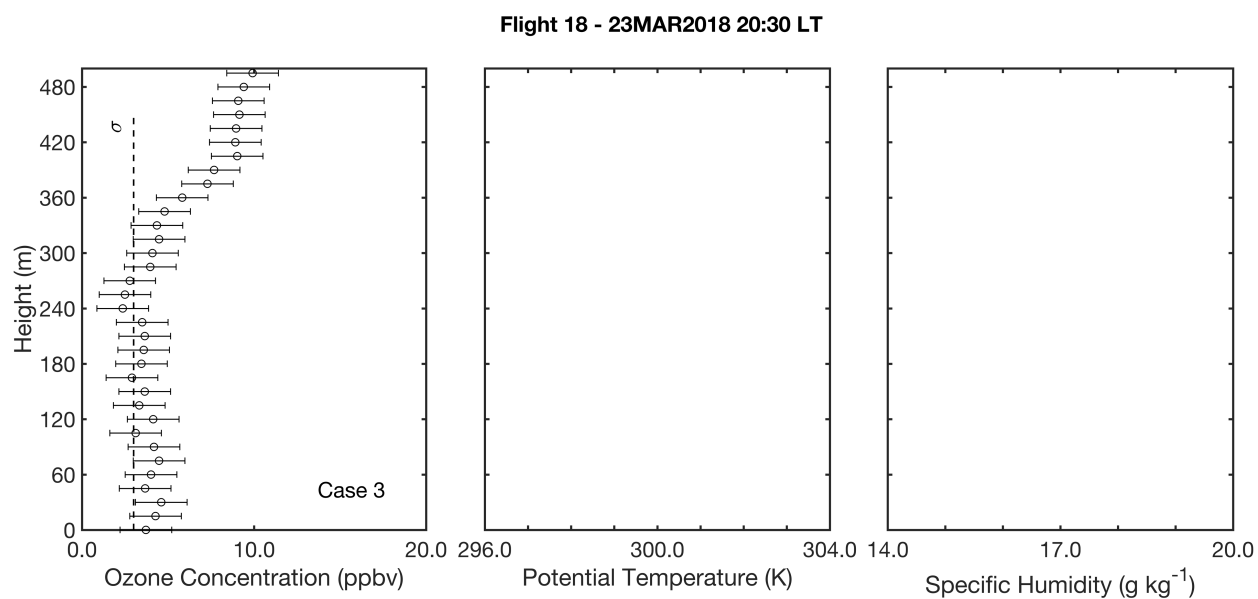


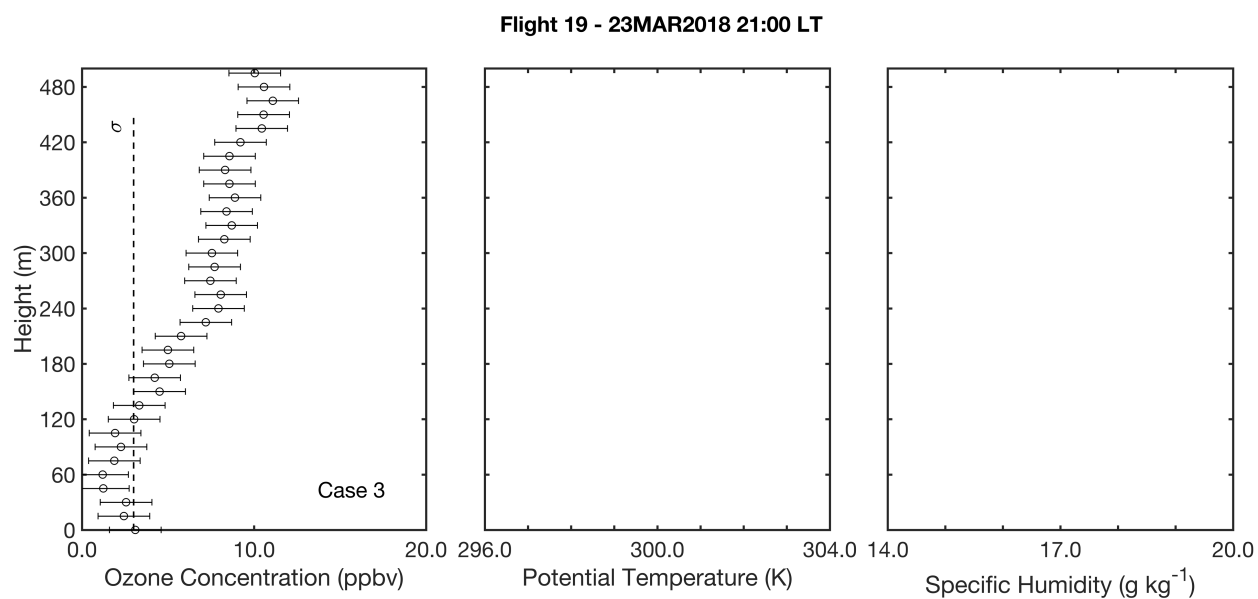
Figure S1 (continued).



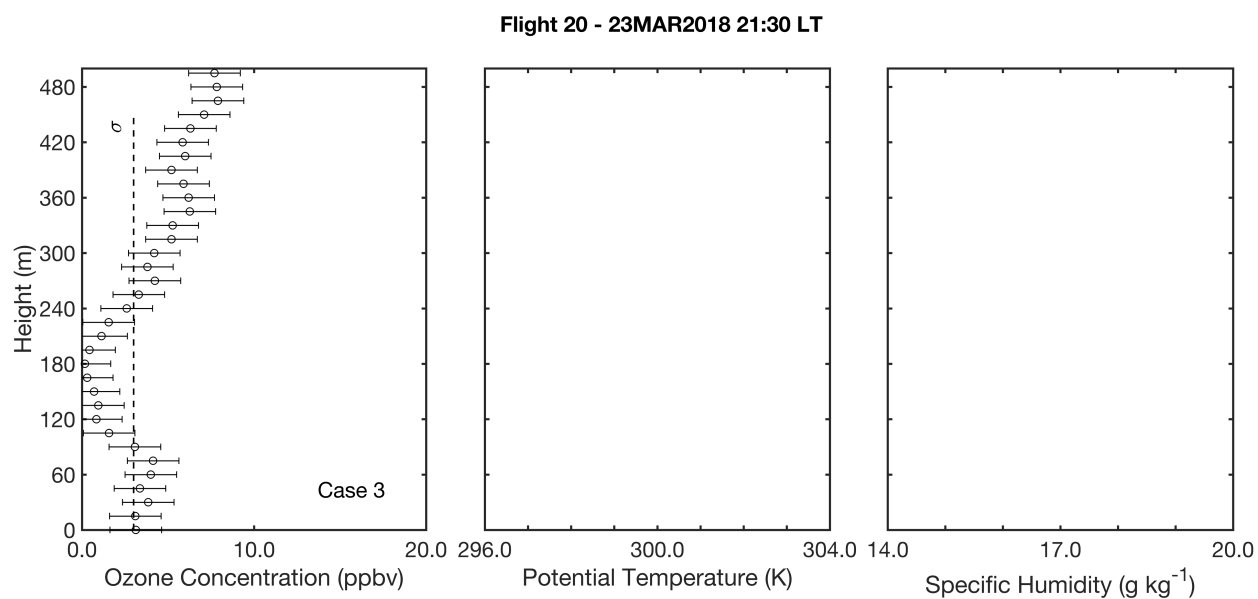
**Figure S1 (continued).**



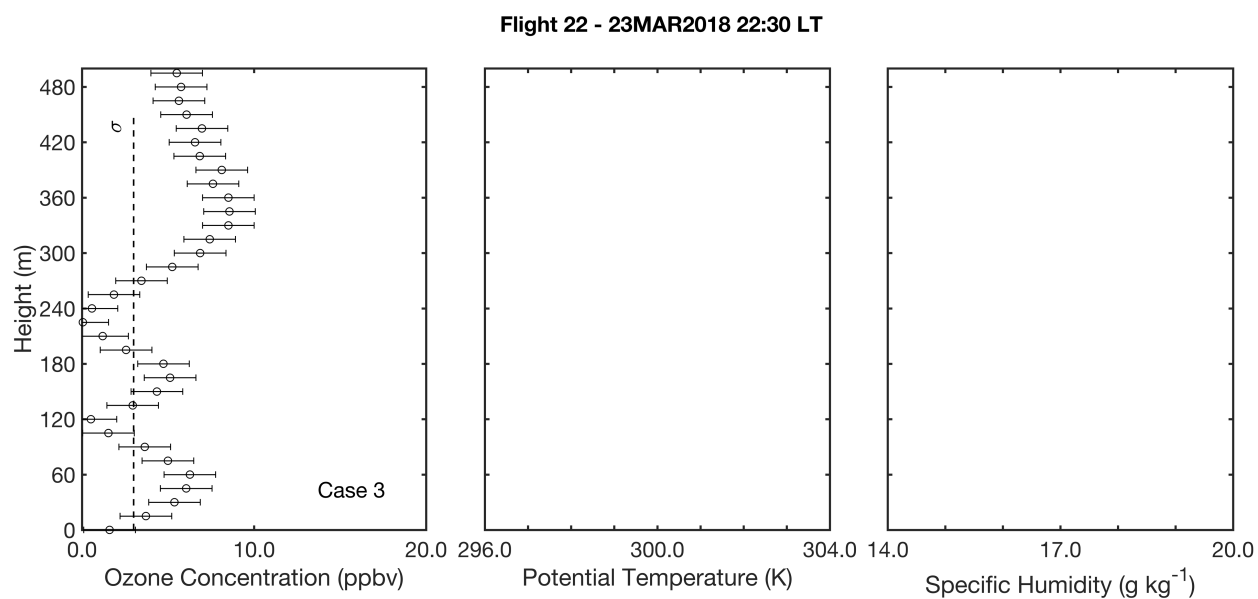
**Figure S1 (continued).**



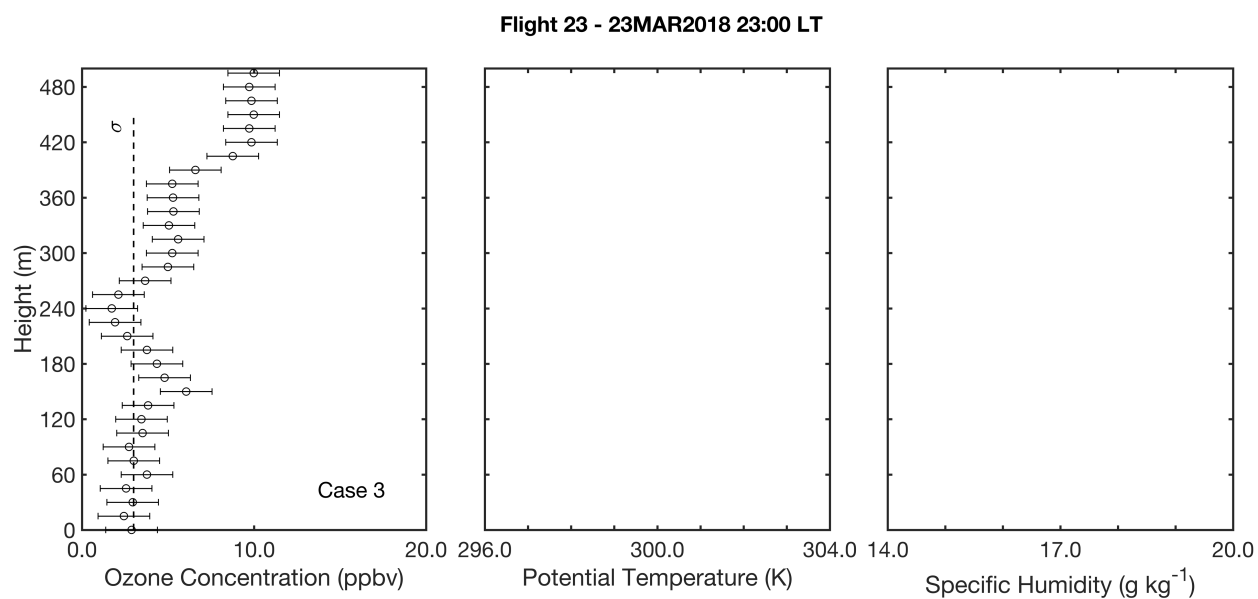
**Figure S1 (continued).**



**Figure S1 (continued).**



**Figure S1 (continued).**



**Figure S1 (continued).**

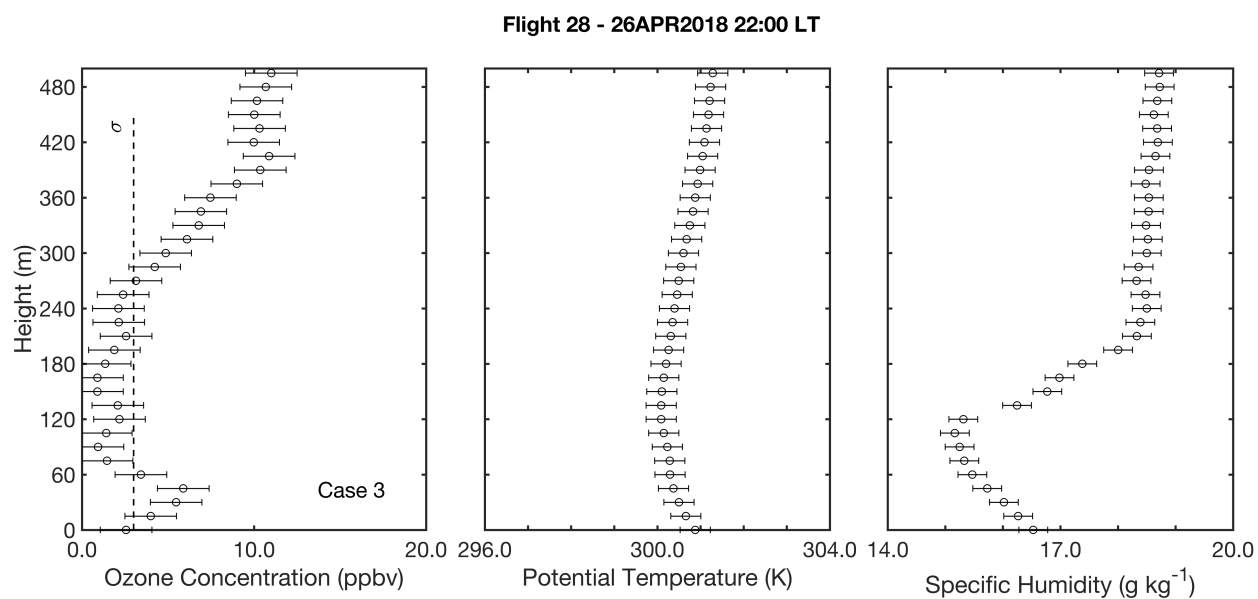


Figure S1 (continued).

Flight 29 - 26APR2018 22:30 LT

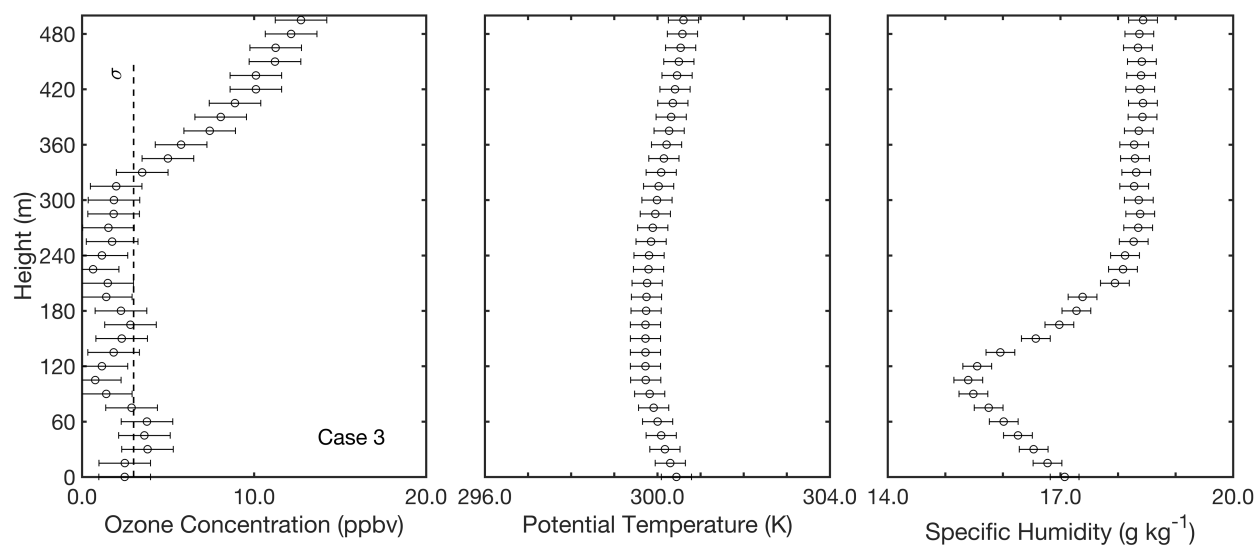


Figure S1 (continued).

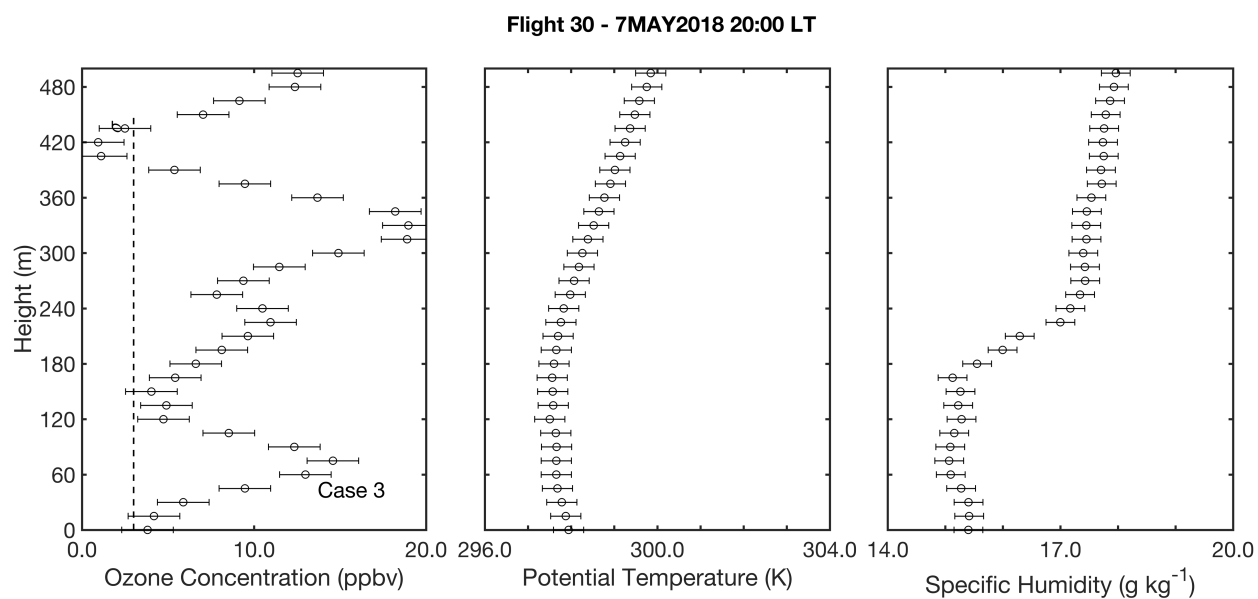
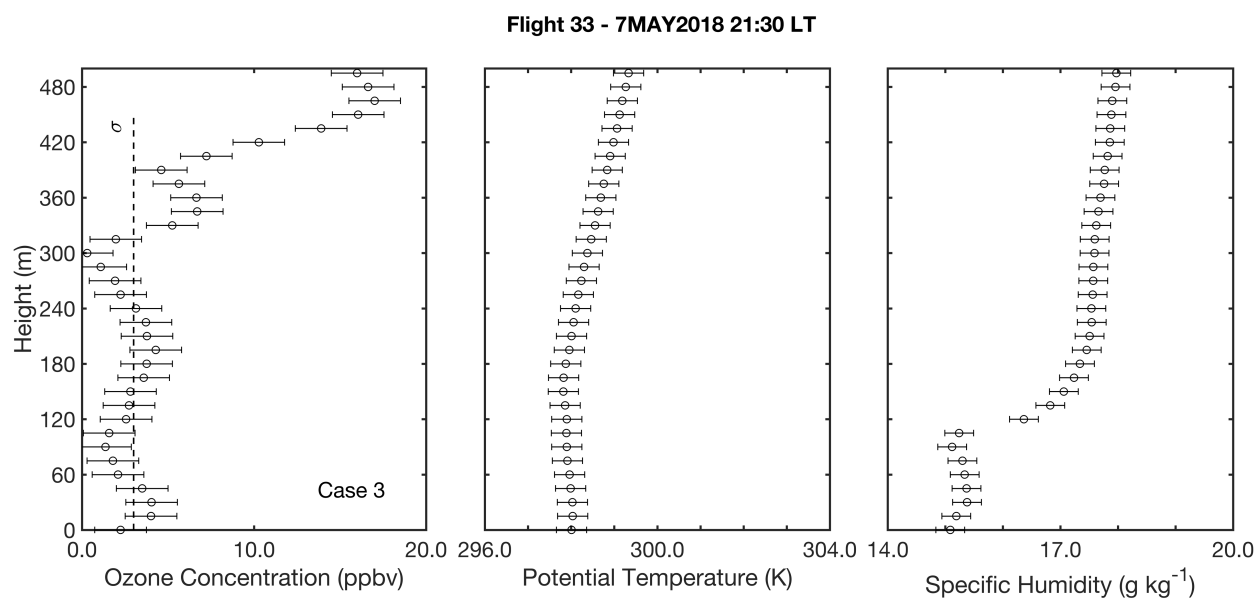


Figure S1 (continued).



**Figure S1 (continued).**

Flight 34 - 7MAY2018 22:00 LT

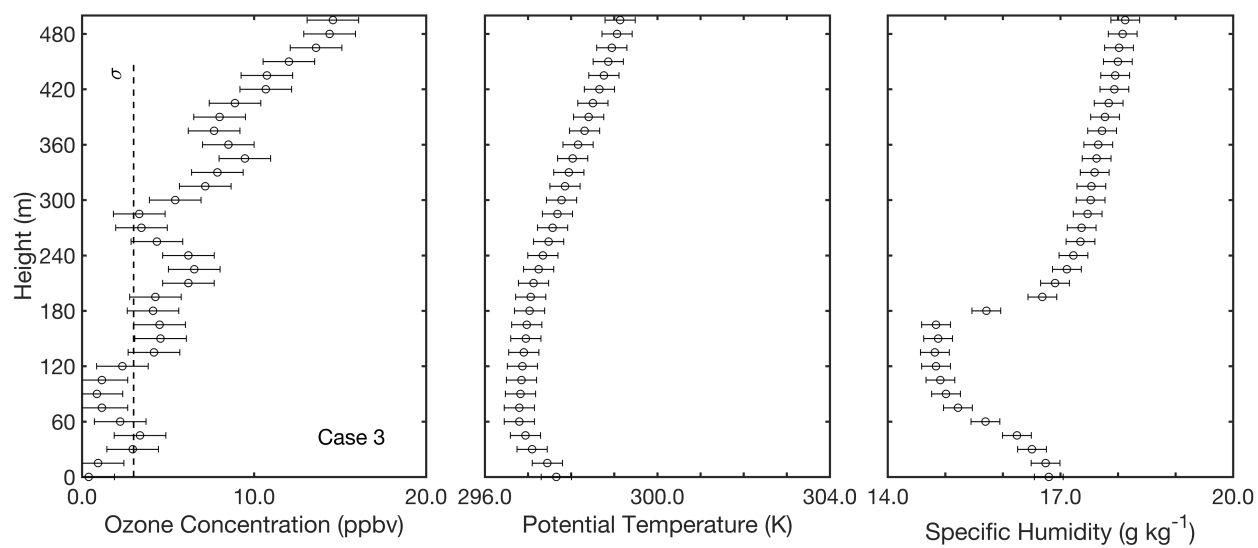
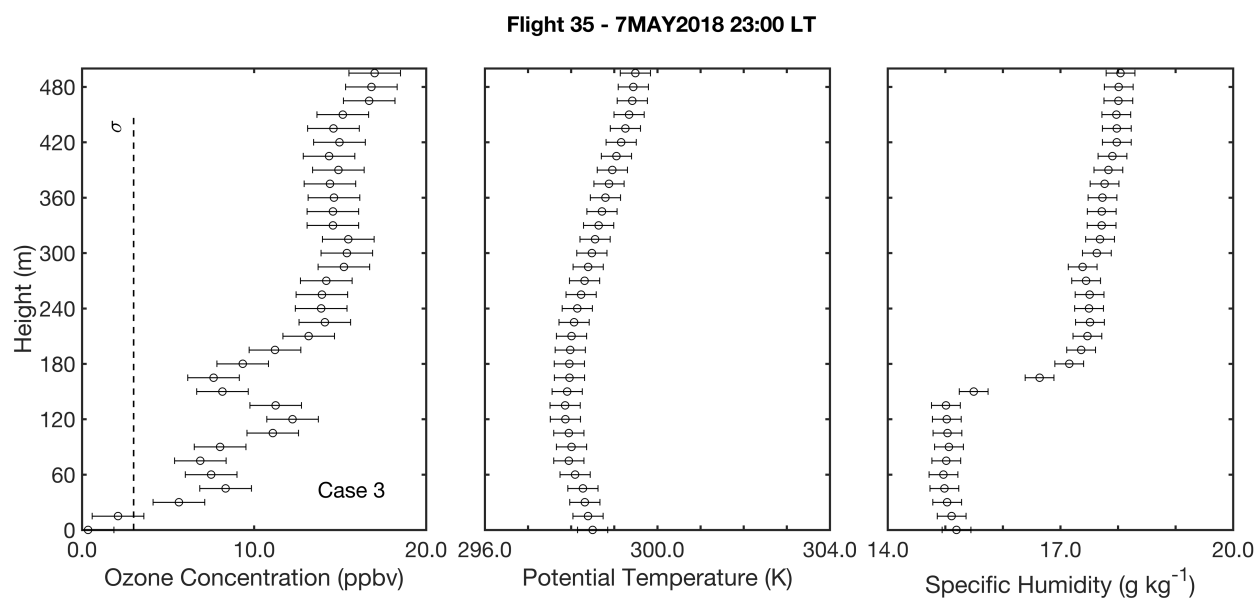
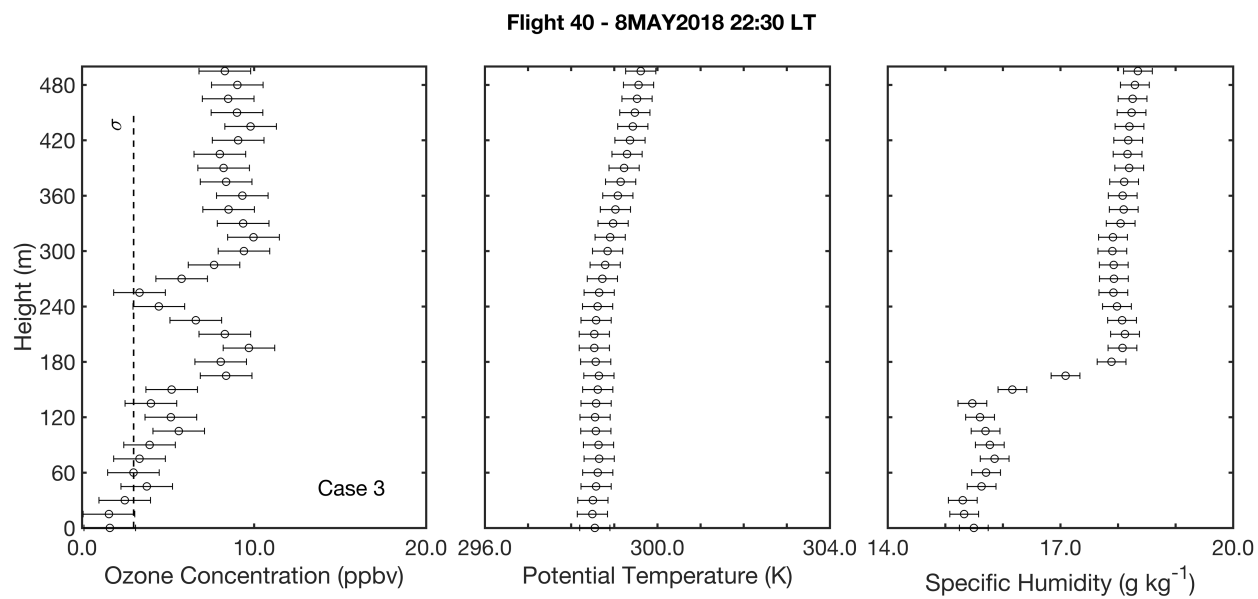


Figure S1 (continued).



**Figure S1 (continued).**



**Figure S1 (continued).**

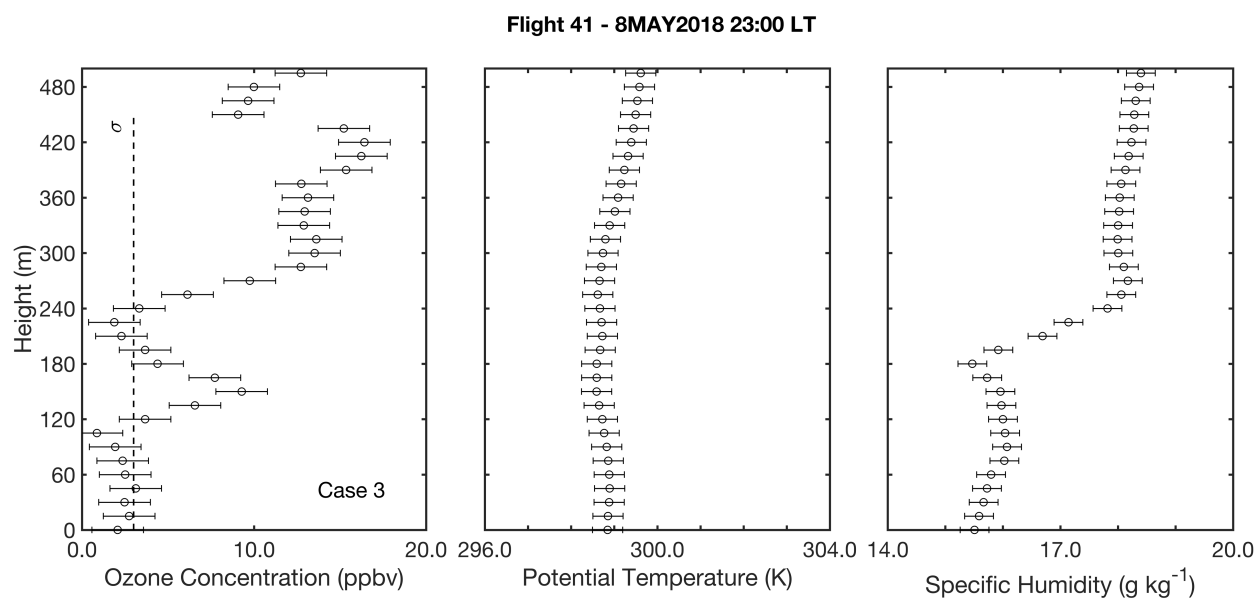
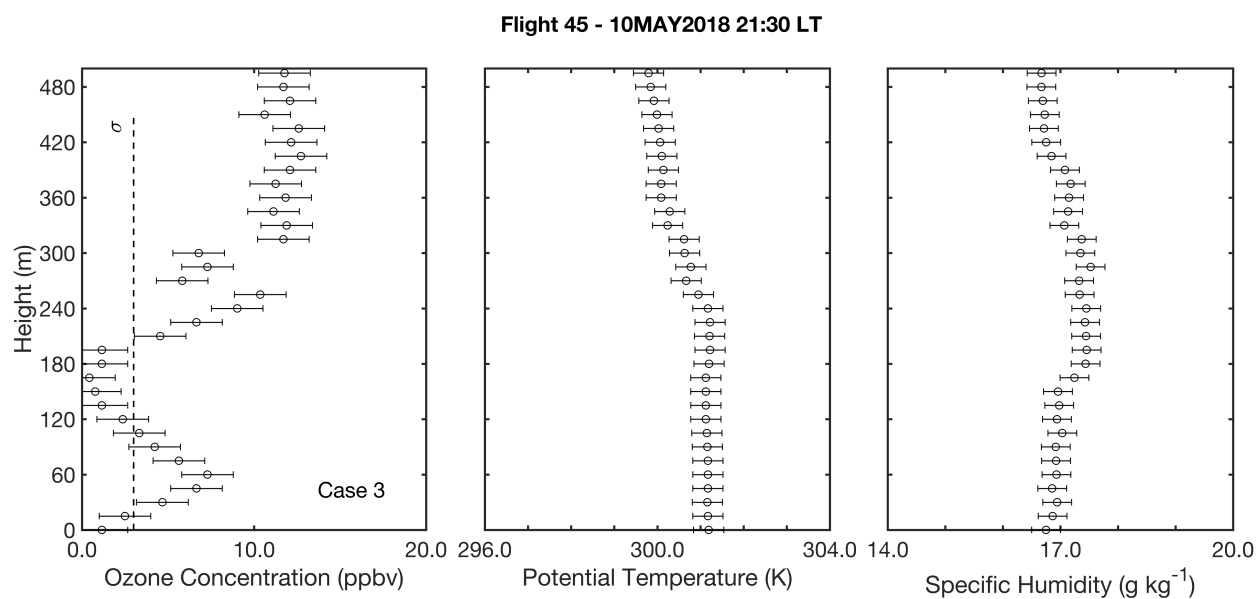
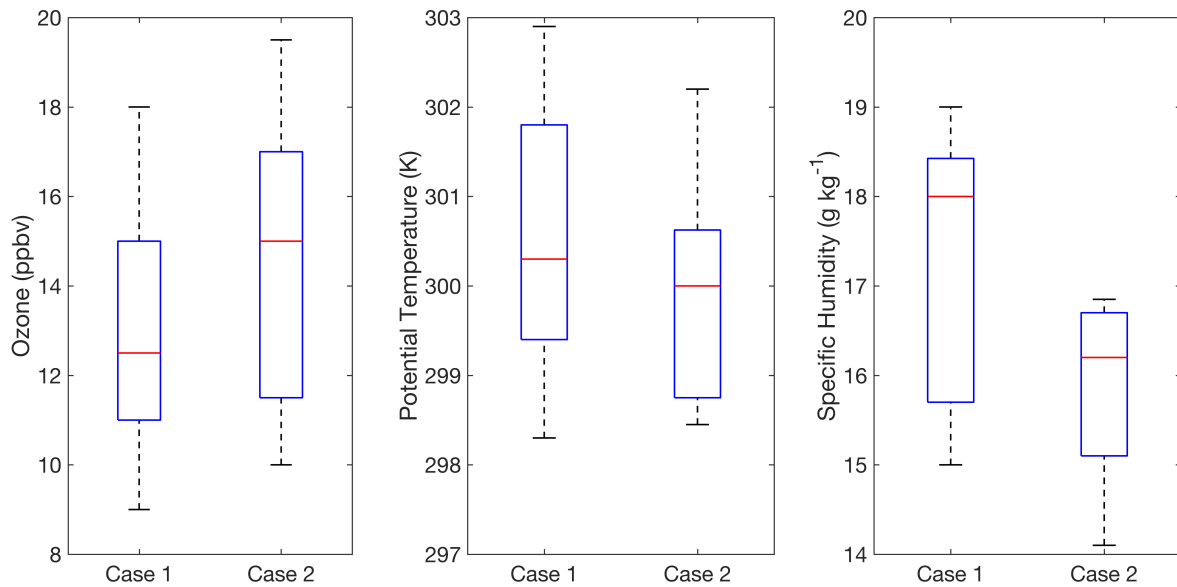


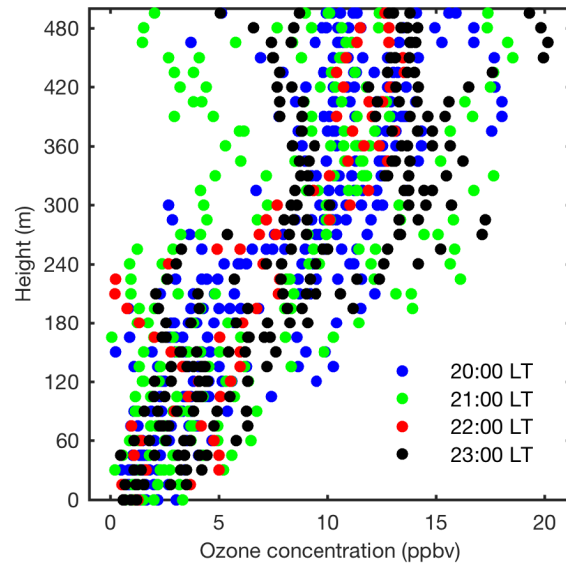
Figure S1 (continued).



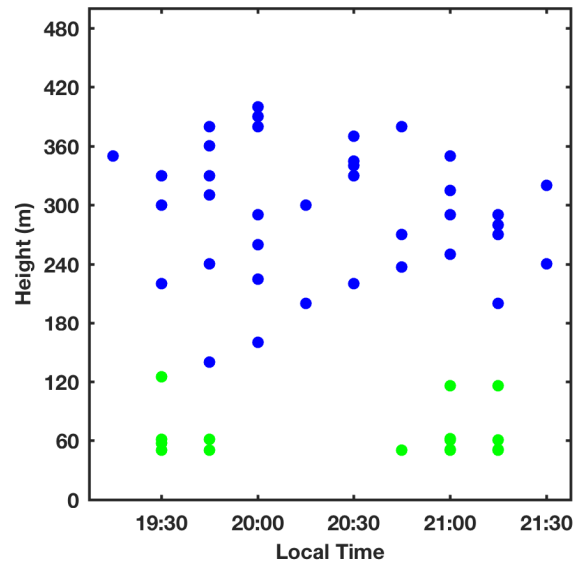
**Figure S1 (continued).**



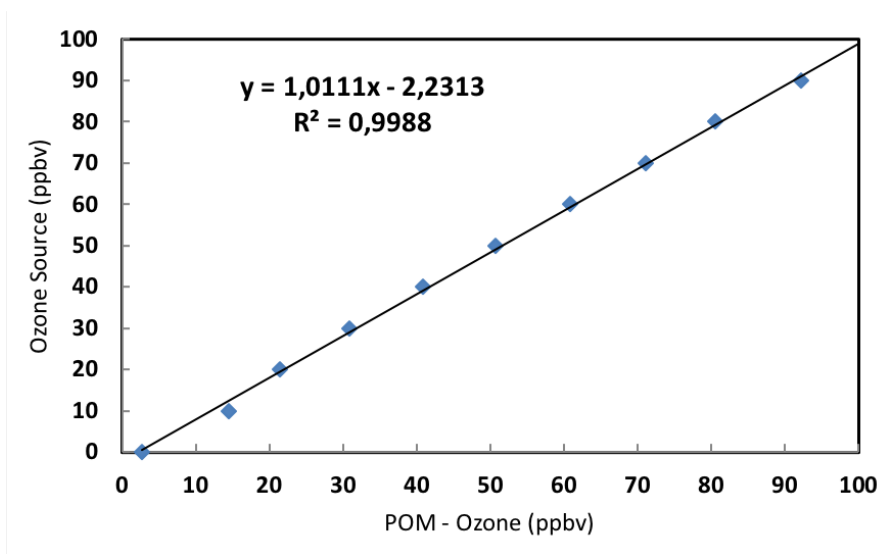
**Figure S2.** Box-whisker statistics plots of (a) ozone concentration, (b) potential temperature, and (c) specific humidity at the top of the NBL during the wet season of 2018. Results are shown for (case 1) a stratified atmosphere based in 23 ozone profiles and (case 2) a turbulent atmosphere based in 16 ozone profiles. For each box-whisker plot, the median (box line) of the combined data sets, quartiles (blue box edges), and the minimum and maximum values (black lines) are represented excluding outliers.



**Figure S3.** Vertical profiles of ozone concentration segregated by hour from 20:00 to 00:00 (LT) for the combined data set of case 1 (i.e., normal stratified atmospheres) based in 23 profiles. Local time (LT) is 4 h earlier than UTC.



**Figure S4.** Boundary layer heights segregated by hour from 20:00 to 00:00 (LT) as (blue color) determined by the UAV measurements of this study and as (green color) reported for the Global Data Assimilation System (GDAS).[51] Local time (LT) is 4h earlier than UTC.



**Figure S5.** Calibration curve for the POM with calibration factors of  $S = 1.00$  and  $Z = +1$  ppbv applied.

**Table S1.** Summary of studies of the NBL, usually between 18:00 and 00:00 LT.

Study	Experiment	Description	NBL Height
Fisch [26]	Rondonia Boundary Layer Experiment	Data collection from radiosonde and tethered balloon, period of 14 days, 4 profiles per night,	190 - 300 m over forest
	(RBLE 2 and RBLE 3)	during the dry season, over forest and pasture	140 - 190 m over pasture
Santos [10]	Experiment and Wet Season Mesoscale Campaign	Data collection from radiosonde and tethered balloon, period of 58 days in dry and wet seasons,	180 - 330 m (dry) and 152 - 282 m (wet) over forest
	(WetAMC-LBA)	over forest and pasture	120 - 230 m (dry) and 210 - 227 m (wet) over pasture
Neves et al. [16]	Radiation, Cloud and Climate Interactions Experiment (RaCCI/LBA)	Data collection from radiosondes, tethered balloon, and sodar, period of 60 days, during the transition from dry to wet season, over pasture	120 - 190 m by tethered balloon, 110 - 130 m by radiosonde, 311 to 377 m by sodar



**Table S2.** Summary of flights and the estimated NBL heights for the period from 19 March 2018 to 11 May 2018 at 3.0918° S and 60.0175° W in the urban area of Manaus. Local time (LT) is 4 h earlier than UTC. Wind and wind velocity are from a weather station at ground level. The estimated NBL heights are based on profile cases 1 or 2 (see main text). “N/A” denotes that no estimate was made. The NBL height is also estimated by the Global Data Assimilation System [58,59] applied to the UAV flight location. The system stability classification is also listed.

Flight Number	Date	Time (LT)	Sky Cover	Case	Ground Wind Direction	Ground Wind Velocity (m s <sup>-1</sup> )	UAV Determined NBL Height (m)	GDAS Estimated NBL Height (m)	GDAS Stability Class
1	19MAR2018	20:00	Clear	1	E	0.1	300	50	Neutral
2	19MAR2018	20:30	Clear	1	E	0.3	140	50	Neutral
3	19MAR2018	21:00	Clear	1	E	0.6	160	N/A	N/A
4	19MAR2018	22:00	Partly cloudy	2	E	0.3	345	N/A	N/A
5	19MAR2018	22:30	Partly cloudy	2	SE	0.1	270	N/A	N/A
6	19MAR2018	23:00	Partly cloudy	1	E	0.3	250	116	Neutral
7	19MAR2018	23:30	Partly cloudy	1	E	0.6	200	116	Neutral
8	20MAR2018	20:30	Cloudy	3	NE	0.8	N/A	50	Neutral
9	20MAR2018	21:00	Cloudy	1	E	0.9	260	N/A	N/A
10	20MAR2018	21:30	Cloudy	3	E	0.8	N/A	N/A	N/A
11	22MAR2018	20:30	Cloudy	2	SE	0.2	360	50	Neutral
12	22MAR2018	21:00	Cloudy	2	E	0.1	290	N/A	Slightly stable
13	22MAR2018	22:00	Partly cloudy	2	NE	0.1	330	N/A	N/A
14	22MAR2018	22:30	Partly cloudy	3	E	0.3	N/A	N/A	N/A
15	22MAR2018	23:00	Partly cloudy	2	E	0.2	315	61	Slightly stable
16	22MAR2018	23:30	Cloudy	2	N/A	N/A	270	61	Slightly stable
17	23MAR2018	20:00	Cloudy	3	S	0.1	N/A	50	Neutral
18	23MAR2018	20:30	Partly cloudy	3	S	0.2	N/A	50	Slightly stable
19	23MAR2018	21:00	Cloudy	3	SE	0.1	N/A	N/A	N/A
20	23MAR2018	21:30	Cloudy	3	S	0.1	N/A	N/A	N/A
21	23MAR2018	22:00	Partly cloudy	1	S	0.1	370	N/A	N/A



22	23MAR2018	22:30	Partly cloudy	3	S	0.1	N/A	N/A	N/A
23	23MAR2018	23:00	Cloudy	3	S	0.1	N/A	50	Slightly stable
24	26APR2018	20:00	Cloudy	1	S	0.1	220	50	Neutral
25	26APR2018	20:30	Partly cloudy	2	N/A	N/A	330	50	Neutral
26	26APR2018	21:00	Partly cloudy	2	N/A	N/A	225	N/A	N/A
27	26APR2018	21:30	Partly cloudy	2	S	0.1	300	N/A	N/A
28	26APR2018	22:00	Partly cloudy	3	NW	0.5	N/A	N/A	N/A
29	26APR2018	22:30	Partly cloudy	3	NW	1.0	N/A	N/A	N/A
30	7MAY2018	20:00	Partly cloudy	3	NE	0.3	N/A	57	Slightly stable
31	7MAY2018	20:30	Partly cloudy	1	N/A	N/A	380	N/A	N/A
32	7MAY2018	21:00	Partly cloudy	1	NE	0.2	380	N/A	N/A
33	7MAY2018	21:30	Partly cloudy	3	W	0.2	N/A	N/A	N/A
34	7MAY2018	22:00	Cloudy	3	NW	0.1	N/A	N/A	N/A
35	7MAY2018	23:00	Partly cloudy	3	E	0.5	N/A	62	Slightly stable
36	8MAY2018	20:00	Clear	1	E	0.3	300	62	Neutral
37	8MAY2018	20:30	Cloudy	2	S	0.4	240	62	Neutral
38	8MAY2018	21:00	Clear	1	NW	0.3	390	N/A	N/A
39	8MAY2018	22:00	Clear	1	NW	0.1	340	N/A	N/A
40	8MAY2018	22:30	Cloudy	3	NW	0.3	N/A	N/A	N/A
41	8MAY2018	23:00	Partly cloudy	3	W	0.2	N/A	50	Slightly stable
42	8MAY2018	23:30	Clear	1	NW	0.5	290	50	Slightly stable
43	8MAY2018	00:00	Clear	1	NW	0.1	320	N/A	N/A
44	10MAY2018	20:00	Partly cloudy	1	NE	0.8	330	125	Neutral
45	10MAY2018	21:30	Partly cloudy	3	E	0.3	N/A	N/A	N/A
46	10MAY2018	22:00	Partly cloudy	2	E	0.5	330	N/A	N/A
47	10MAY2018	22:30	Partly cloudy	2	E	0.7	240	N/A	N/A
48	10MAY2018	23:00	Partly cloudy	2	E	0.3	290	51	Slightly stable



49	10MAY2018	23:30	Partly cloudy	1	E	0.1	240	51	Slightly stable
50	10MAY2018	00:00	Partly cloudy	2	E	0.2	240	N/A	N/A
51	11MAY2018	19:30	Clear	1	W	0.3	350	N/A	N/A
52	11MAY2018	20:00	Clear	2	NW	0.1	330	50	Moderately stable
53	11MAY2018	20:30	Clear	1	NW	0.4	310	50	Moderately stable
54	11MAY2018	21:00	Clear	1	NW	0.2	400	N/A	N/A
55	11MAY2018	21:30	Clear	1	N/A	N/A	200	N/A	N/A
56	11MAY2018	22:00	Clear	1	N/A	N/A	220	N/A	N/A
57	11MAY2018	23:00	Clear	1	N/A	N/A	350	50	Slightly stable

**Table S3.** Results of Cramer's V analysis for the association between the structures of the observed profiles (i.e., cases 1, 2, and 3) and sky conditions (i.e., clear, partly cloudy, and cloudy).

Sky condition	Occurrence			Cramer's V analysis		
	Case 1	Case 2	Case 3	Pearson Chi-square value	Cramer's V value	Significance ( <i>p</i> -value)
Clear	15	1	0			
Partly cloudy	6	12	10	28.33	0.50	< 0.001
Cloudy	2	4	8			



**Table S4.** Comparison of data collection characteristics of radiosondes, tethered balloons, and copter Unmanned Aerial Vehicle (UAV) for typical measurements of potential temperature, specific humidity, and ozone. For comparison purposes, the height between readings, the number of data points, and the time period to collect data correspond to an altitude profile from 0 to 500 m. The UAV characteristics are for the operational conditions of this study. The characteristics of radiosondes and tethered balloons are adapted from Balsley et al. [75].

	Radiosonde	Tethered Balloon	UAV
Ascending Speed ( $\text{m s}^{-1}$ )	5	1.8	0.5
Data read frequency (Hz)	0.5	0.1	0.1
Height between readings (m)	10	20	5
Dwell time at each reading (s)	2	10	10
Number of data points	50	25	100
Time period to collect data (min)	1.7	4.2	17
Max altitude coverage (km)	> 30	< 1-2	< 2.5
Max Payload weight (kg)	< 3	100	< 5
System cost ( $10^3$ \$)	10	10-200	5
Cost per profile	Low-High	Low	Very low
Operational wind speed limit ( $\text{m s}^{-1}$ )	< 10	< 12	< 8
All weather	Yes	No	No