A population of dust-enshrouded objects orbiting the Galactic black hole

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The central 0.1 parsecs of the Milky Way host a supermassive black hole identified with the position of the radio and infrared source Sagittarius A* (refs. 1,2), a cluster of young, massive stars (the S stars³) and various gaseous features^{4,5}. Recently, two unusual objects have been found to be closely orbiting Sagittarius A*: the so-called G sources, G1 and G2. These objects are unresolved (having a size of the order of 100 astronomical units, except at periapse, where the tidal interaction with the black hole stretches them along the orbit) and they show both thermal dust emission and line emission from ionized gas⁶⁻¹⁰. G1 and G2 have generated attention because they appear to be tidally interacting with the supermassive Galactic black hole, possibly enhancing its accretion activity. No broad consensus has yet been reached concerning their nature: the G objects show the characteristics of gas and dust clouds but display the dynamical properties of stellar-mass objects. Here we report observations of four additional Gobjects, all lying within 0.04 parsecs of the black hole and forming a class that is probably unique to this environment. The widely varying orbits derived for the six G objects demonstrate that they were commonly but separately formed.

We used near-infrared (NIR) spectro-imaging data obtained over the past 13 years¹¹ at the W. M. Keck Observatory with the OSIRIS integral field spectrometer¹², coupled with laser guide star adaptive optics wave front corrections¹³. OSIRIS data-cubes have two spatial dimensions-about 3 arcsec × 2 arcsec surrounding Sgr A* with a platescale of 35 mas—and one wavelength dimension that covers the Kn3 band, 2.121–2.229 um, with a spectral resolution of $R \approx 3.800$. We selected 24 data-cubes based on image quality and signal-to-noise ratio; see Methods section 'Observations'. These cubes were processed through the OSIRIS pipeline¹⁴. We also removed the stellar continua to isolate emission features associated with interstellar gas (Methods section 'Continuum subtraction'). The reduced data-cubes were analysed with a three-dimensional visualization tool, OsrsVol15, that simultaneously displays all dimensions of the data-cube. This helps disentangle the many features of this crowded region, which are often superimposed in the spatial dimension but are separable in the wavelength dimension (Fig. 1).

Analysing the data with OsrsVol as well as conventional twodimensional (2D) and one-dimensional (1D) tools, we identify four new compact objects in Brackett-γ line emission (Bry; 2.1661 μm rest wavelength) that consistently appear in the data across the observed timeline. In addition to Bry, all four objects show two [Fe III] emission lines (at 2.1457 μ m and 2.2184 μ m; ref. ¹⁶).

The four objects show many properties in common with G1 and G2 $(compact\,Br\gamma\,emission\,and\,coherent\,orbital\,motion)\,and\,we\,therefore$ name them G3, G4, G5 and G6. G3 was previously identified ($D2^{7,17}$). For this work we independently identified G3 in Bry emission, and G4, G5 and G6 are newly reported. Recently, G6 has been independently examined¹⁸, and interpreted as a bow shock source rather than a G object. We estimate that we are able to detect G objects having Bry flux densities of at least 0.02 mJy, if they lie in a non-confused location.

Several other infrared-excess sources have been identified with L' and K' observations (central wavelengths of 2.2 µm and 3.8 µm, respectively^{7,17}, see Extended Data Fig. 1). We do not include these other sources in this work (except for G3/D2), either because they lie outside the OSIRIS field of view, or because they have not been detected in Bry. or because they have not been consistently detected throughout the 13 years of data. We use Keck/NIRC2 L' imaging data to investigate whether G3, G4, G5 and G6 have detectable L' counterparts, as G1 and G2 do (Methods section 'L' detection analysis'). No L' counterpart was detected for G4, G5 and G6, with upper limits to the flux density of 0.4 mJy, 0.6 mJy and 0.5 mJy, respectively. G3 is detected in L' with a dereddened flux density of 2.5 mJy, consistent with a previous report¹⁷.

None of the G objects was detected in the K continuum. Our detection limit in the K continuum is 0.01 mJy in the OSIRIS spectra (Kn3 filter) and in the K' broadband (2.12 µm central wavelength) a limit of 0.07 mJy was reported for G2¹⁹ (but see ref. ²⁰).

The Bry emission is a key defining feature of the G objects because it probably results from external ionization and does not depend on the mass of a putative central object, and hence its presence is independent of the nature of the G objects (low-mass cloud or extended stellar-mass object). The compactness of such emission is what distinguishes the Gobjects from other presumably short-lived gas blobs that have become detached from larger-scale interstellar structures. The dust heating can be attributed to some combination of the external radiation field and an internal stellar core, if present. Therefore, the

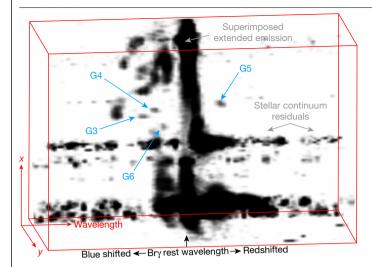


Fig. 1| **2006 OSIRIS data-cube visualized with OsrsVol.** The spatial dimensions (x-y) cover the OSIRIS field of view. The wavelength dimension is centred around Bry ($\pm 1,500 \, \mathrm{km \, s^{-1}}$). G3, G4 and G6 are blueshifted, whereas G5 is redshifted. G1 and G2 are not visible here because they have larger velocities. The extended emission in the middle is near the rest wavelength and it arises from foreground or background gas ('superimposed extended emission'). The emission extending the full length of the wavelength axis at a few positions ('stellar continuum residuals') is associated with continuum subtraction residuals. For this analysis, we only use sources that appear throughout the observed timeline.

lack of detection of the G objects in the L' band does not necessarily have implications for the existence of a stellar object embedded within the ionized external envelope.

The proper motions of the G objects were determined from the Bry centroid in the OSIRIS data (Methods sections 'Aligning OSIRIS epochs' and 'Astrometric measurements and uncertainty'). We furthermore determined the radial velocity of each object by extracting its spectrum over a 1.5-pixel-radius aperture on each data-cube and performing a Gaussian fit to the Bry profile (Methods section 'Radial velocity measurements and uncertainty').

All G objects show large proper motions and have substantial radial velocity shifts; the radial velocity of G3 changed by about 300 km s^{-1} over 13 years (see Fig. 2b and Methods section 'Radial velocity measurements and uncertainty').

Using these measurements (Extended Data Table 2), we determined the orbits of the new G objects with a Keplerian model, using a fitting algorithm¹¹ (Methods section 'Orbit fitting') with six orbital parameters, two parameters accounting for systematic errors in both astrometric positions and radial velocities, and one parameter accounting for correlation within the astrometric measurements. The black hole parameters (mass and Galactic Centre distance) are considered fixed¹¹. The best-fit orbits are illustrated in Fig. 3 and the orbital parameters are reported in Extended Data Table 3. These fits indicate that: (1) G3, G4 and G6 have orbits with modest eccentricities ($e \approx 0.15, 0.3$ and 0.3, respectively). whereas G5 has a very eccentric orbit ($e \approx 0.9$); (2) the orbital periods range between 170 years (for G3) and 1,600 years (for G5); (3) all orbits lie on different planes, none of which contains G1 and G2 orbits or the clockwise stellar disk²¹⁻²³; and (4) the orbits all have periods much longer than the 13 years of observations, which implies a small orbital phase coverage (~9% and ~2% in true anomaly for G3 and G5, respectively). We have run coverage tests to assess the bias attributable to the low phase coverage (Methods section 'Dependence on priors') and the results show that the obtained orbital parameters are not significantly biased (consistent with an unbiased result to within 1σ).

We used a Gaussian fit to the Br γ and the brightest [Fe III] line (2.2184 μ m) profiles to extract fluxes. There is no noticeable flux variation for any of the four newly reported G objects in the 13 years of observations (Methods sections 'Flux calibration', 'Flux measurements' and 'Flux and FWHM summary table'). Nor can we detect any variation in the line width, given the variations in the data quality, instrumental upgrades and the emission line blending with other features.

Our analysis shows that the new objects show many of the same characteristics as G1 and G2, enough to justify defining them as members of a common new class. We define the G objects to have the following characteristics: (1) presence of a distinct source of Br γ emission; (2) spatially compact emission; (3) relatively weak K-band continuum emission (such that $K' - L' \ge 4.5$); and (4) large proper motion and radial velocity shifts over time. By 'compact' we mean that they are unresolved (<0.03'') or slightly resolved (-0.05'').

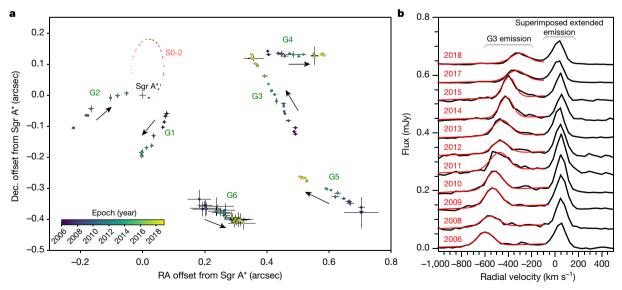


Fig. 2 | **Proper motion and spectrum of the G objects. a**, Observed proper motions (with error bars showing standard deviations) of G objects and S0-2 on the plane of the sky. RA, right ascension; dec., declination. **b**, G3 spectrum (black) and Gaussian fit to the G3 Bry emission (red) in each year. There is no detected variation in the line width, but the G3 emission line blends with

neighbouring features as it changes radial velocity. The large changes in the radial velocity of G3 contrast with the static extended foreground (or background) emission at the rest velocity ('superimposed extended emission'). G objects have Bry emission, large proper motion and radial velocity shift, and are not detected in the K continuum.

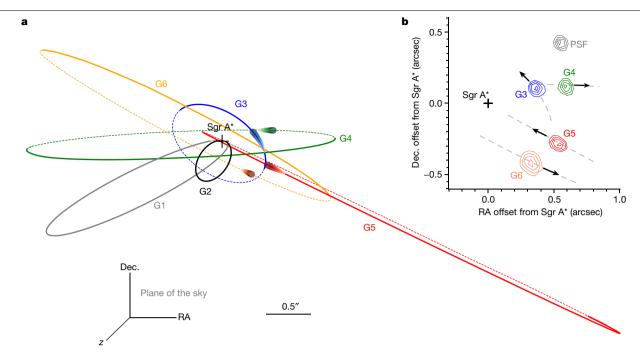


Fig. 3 | Orbits of the Gobjects. a, Orbit models in three dimensions: the portion of the orbit behind the plane of the sky containing Sgr A* is represented as a dashed line, and the part between the observer and Sgr A* is represented as a solid line. The thick short line indicates the time span of the observations (2006–18) and it gets darker and thicker in the direction of the object's motion.

All orbits have different inclinations, eccentricities and periods. b, Contour plots of intensity (in the Kn3 band) of the new G objects in 2018, their orbits (dashed grey lines) and the point-spread function (PSF). All G objects are unresolved or only marginally resolved.

These characteristics distinguish G objects clearly from normal stars. In general, the G objects seem to have very red K-L colours (K'-L'>5.2,6 and 4.5 for G1, G2 and G3, respectively¹⁷), indicating that they are probably enshrouded by dust.

There are also some differences and peculiarities: G3, G4, G5 and G6 are all brighter in Bry than G1 and G2 by about a factor of 2. G1, G2 and G3 have a clear L-band counterpart, unlike G4, G5 and G6. G3, G4, G5 and G6 show [Fe III] emission, whereas G1 and G2 do not. G3 and G4 are unresolved, while G5 and G6 are slightly extended (Fig. 3 inset). G1 was extended after periapse⁹, as G2 was before and after periapse (but reverted to being compact¹⁰). Despite these differences, the shared properties of the G sources warrant their aggregation into a new class with an appreciable population.

G2 was originally interpreted as an ionized gas cloud⁶ and later it was argued that G1 and G2 were knots within a common orbiting fila $ment^{24}. However, this interpretation cannot apply to the new sources as\\$ they have completely different orbits. G1 and G2 have remained intact after passing through periapse and, whereas G2 clearly underwent tidal interaction during its periapse passage¹⁰, its dust component has remained unresolved. This has led several authors 8,9,25-27 to suggest that there might be a stellar core shielded by an extended envelope of gas and dust. The star needs to have a relatively low mass (less than a few solar masses²¹) in order to be compatible with the weakness of the stellar continuum.

Several models (Methods section 'G-object formation scenarios') have been proposed to account for G2 in terms of an optically thick distribution of dust surrounding a star: a young, low-mass star (T Tauri star) that has retained a protoplanetary disk²⁶ or that generates a mass-loss envelope²⁷, or the merger of a binary system^{8,9,25,28}

The binary merger hypothesis (in which the influence of the black hole enhances the probability of a merger through eccentricity oscillations²⁹) can also account for the presence of a population of G objects by interpreting them as relatively long-lived, distended post-merger objects. Assuming the binary merger hypothesis, we have used the number of observed G objects to estimate the required binary fraction³⁰

in the central 0.1 pc, obtaining a lower limit of about 5% for low-mass stars (Methods section 'Binary fraction estimate'). This is compatible with the expected binary fraction³¹, based on dynamical simulations³⁰ and taking into account the physical characteristics of the Galactic Centre. In the most likely scenario³⁰ for the merger hypothesis, the original binaries would have been formed in the last major star formation event at the Galactic Centre $(4-6 \text{ Myr ago}^{23})$.

Therefore, the binary merger hypothesis offers a compelling explanation for the origin of the population of G objects for several reasons: (1) it fits well with the three-body dynamics that are necessarily at play in a dense stellar environment: (2) it is compatible with the observed wide range of G-object eccentricities²⁸; and (3) it fits well with the known star formation history and observed stellar population.

The random distribution of the orbital planes and the broad range of eccentricities of the Gobjects very closely resemble the characteristics of the orbits of the S stars, which more or less occupy the same volume. In all of the star-centred hypotheses for the G objects, the stellar object must have a relatively small mass (less than a few solar masses). At present, in the central parsec, we can directly detect stars with masses down to ~1.5 solar masses²². Therefore, the G objects could be offering a unique window on the low-mass, currently undetectable, part of the S-star cluster.

Online content

Any methods, additional references, Nature Research reporting summaries, source data, extended data, supplementary information, acknowledgements, peer review information; details of author contributions and competing interests; and statements of data and code availability are available at https://doi.org/10.1038/s41586-019-1883-y.

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Methods

Observations

The observations were carried out with OSIRIS LGSAO covering 13 years, as tabulated in Extended Data Table 1. For each epoch of observations, the OSIRIS configuration with a plate-scale of $0.035^{\prime\prime}$ per lenslet was used with the Kn3 (2.121–2.229 μ m) bandpass. A dither sequence with 900 s per integration using a square box pattern centred on Sgr A* with 1.0 arcsec spacing was employed to increase the field of view and to help average-out systematic instrumental features. The data were reduced using the OSIRIS data reduction package, DRP14. The DRP produces a wavelength-calibrated data-cube with two spatial dimensions and one spectral dimension, with the dither sequence median combined into a mosaic.

Continuum subtraction

In order to extract the emission line of the interstellar medium we need to remove the continuum emission coming from the numerous stars in the field. To do so, we selected several spectral ranges devoid of spectral features. These spectral ranges are the same for all epochs and they are chosen to optimize the continuum estimation across the field and across the spectral band. Afterwards, we model the continuum pixel-by-pixel using a spline function. The continuum subtraction is somewhat more complex at the edges of the filter's band but this does not affect our measurements: the continuum around the emission line closest to the edge of the band that we are considering, [Fe III] 2.2184 μm , is still well modelled. We then produce new data-cubes in which the modelled continuum has been subtracted from each spectrum and use those for the rest of the analysis.

L' detection analysis

The Galactic Center Group has gathered L' (at $3.8 \, \mu m$) imaging data in the L' bandpass (at $3.8 \, \mu m$) with the NIRC2 imager at the W. M. Keck Observatory over several of the same epochs observed by OSIRIS and used in this study. These data were analysed to determine whether there are L' sources coincident with the OSIRIS-detected Bry sources via the PSF-fitting tool StarFinder³². We chose the deepest L' epoch (2012.551¹⁷) to search for coincident L' sources.

No L' counterpart was detected for G4, G5 and G6 and we perform star-planting simulations to determine an upper flux limit. We used the Bry positions of the sources and transformed them into the 2012.551 L'coordinate system using a series of linear transformations that take into account stretching, linear offsets, and rotation. For each source, neighbouring L' sources were subtracted out using the flux values identified with StarFinder, K'-identified sources that were not associ $ated\,with\,the\,L'\,sources\,based\,on\,proper\,motions\,were\,also\,subtracted$ from the analysis image assuming that they had the same magnitude and colour profiles as our flux calibration sources (SO-2, SO-12, S1-20 and S1-19,17). The images were then background-subtracted and Lucy-Richardson deconvolved using the background map and model PSF generated from StarFinder. We deconvolved for 8,196 iterations and re-convolved each image with a 3-pixel full-width at half-maximum (FWHM) two-dimensional Gaussian PSF. Point sources of varying magnitude were planted in the image at the positions of G4, G5 and G6 at varying magnitude until they could no longer be detected with a modified version of StarFinder 9,19,33. These magnitudes were then corrected for Galactic Centre extinction³⁴ and converted to flux densities. The L' flux density values for G4, G5 and G6 represent upper limits, but the G5 value may still be contaminated by structured background in that region. The flux density values for G3 are consistent with previous reports¹⁷. All flux densities are reported in Extended Data Table 4. In all the above analyses, the single PSF model generated by StarFinder is adequate to use in this case as the off-axis positions of the candidate G sources do not experience a strong effect of the field-dependent PSF. A by-eye search for G4, G5 and G6 was performed using the L' data coincident with the other OSIRIS epochs, but no sources were cleanly identified as being associated with the three candidate G sources. All deconvolved images in the L'-coincident epochs are shown in Extended Data Fig. 2.

Aligning OSIRIS epochs

For our measurements and analysis, we used 24 epochs of OSIRIS observations. Each epoch consists of a mosaic constructed from frames that have been observed while dithering around the position of the star SO-2. The mosaic is obtained through a median-combine procedure applied through the OSIRIS DRP^{14,35}. In order to extract the astrometry of the G objects, we shifted all mosaics into a common reference frame. To do so we measured the position of two reference stars: S0-12 and S0-14. The choice of these two specific stars was made because they are reasonably well-isolated in this crowded field, they are reasonably bright (for S0-12 $K \approx 14.3$, and for S0-14 $K \approx 13.7$; ref. ²²), and they are close to the observed G objects, thereby minimizing possible systematics in the alignment procedure due to distortion. We have accurate knowledge of the orbital motions—and thus astrometric positions—of these two stars with respect to Sgr A* from previous publications¹¹. Taking into account the reference stars' motions we can put all observations in a common reference frame with Sgr A* at the centre. However, this assumes there is no significant differential distortion from epoch to epoch and that Sgr A* does not move. Given the small field of view covered by OSIRIS at this platescale, any differential distortion should be insignificant. The main source of uncertainty in this procedure comes from the centroid of the Gobjects. On the other hand, the position of the reference stars is very well measured because of the very high signal-to-noise. We also consider an additional systematic uncertainty on the astrometric position in the orbital fit (Methods section 'Orbit fitting').

Astrometric measurements and uncertainty

Analysis of the proper motion of the G objects was performed using two sets of cubes: those that had been processed to remove the continuum (Methods section 'Continuum subtraction') and those with the stellar continuum included. The G sources do not have a continuum detection in the Kn3 bandpass and thus we used the continuum-subtracted cubes to measure their positions. The positions of the G objects were measured in a median-collapsed 2D image produced by combining five spectral channels centred on the peak wavelength of the Bry emission from each G source for each epoch. The peak-fit IDL routine was used to measure the X-Y position in each cube. The X-Y positions were transformed into RA–dec. coordinates relative to Sgr A* using the positions for SO-12 and SO-14 to establish the frame of reference.

S0-12 and S0-14 are stellar sources with well-established position off-sets from Sgr A*, they are relatively isolated spatially, and their motion on the plane of the sky is relatively small over this time frame. The stellar positions were measured using the IDL peak-fit routine of a median-combined 2D image produced from collapsing the spectral dimension of the cube over the range of 2.133–2.158 μm (corresponding to channels 50–150). This wavelength range was chosen because it is a clean part of the spectrum that avoids emission, stellar absorption and atmospheric absorption features. The stellar point sources were mapped to a coordinate system in which Sgr A* is at rest 36,37 . The errors of the position measurements were estimated using a Monte Carlo method with many trials of centroid measures over variable aperture size and position. The measurements are reported in Extended Data Table 2.

Radial velocity measurements and uncertainty

The spectra for each G object were extracted from the continuum-subtracted data-cubes. To extract a 1D spectrum for the purpose of measuring radial velocity, the intensity of each Br γ emission feature was measured at each spectral channel of the data-cube, summing over a 1.5-pixel-radius aperture centred on the peak position of the emission feature.

The emission-line profile was analysed using a Gaussian fitting routine on the emission feature. The fits were performed on a wavelength range that isolates the feature under study as much as possible from other nearby emission features, such as the ambient gas and other G objects. The Gaussian parameter fit yields the central wavelength of the Bry emission line, from which the radial velocity can be calculated relative to the local standard of rest.

Extended Data Fig. 3 displays the extracted spectrum and Gaussian fit for each object as it progresses over time. Changes in radial velocity over the 13-year period are evident for each G object. The velocity measurement errors were computed using the statistical errors of the Gaussian fit. In addition to the detection of Bry emission, G3, G4, G5 and G6 display [Fe III] emission at the same Doppler shift, as shown in Extended Data Fig. 4, which displays the full Kn3 bandpass spectra from 2006-combined data sets for G3, G4, G5 and G6 (as well as G1 and G2 for comparison). G3, G4, G5 and G6 have [Fe III] detections at 2.2184 μm and 2.1457 μm (ref. 16), whereas G1 and G2 show only Bry emission. None of the G objects shows H_2 emission (2.1220 μm), although H_2 is evident in the ambient background material near zero velocity. The measurements are reported in Extended Data Table 2.

Orbit fitting

The astrometric and radial velocity measurements (Extended Data Table 2) are combined in a global orbit fit. The software used for orbit fitting has been previously used for the detection of the relativistic redshift on SO-2¹¹. The orbital modelling assumes Keplerian motion parameterized by the six following orbital elements²: the period (P), the time of closest approach (T_0), the eccentricity (e), the inclination (i), the argument of periastron (ω) and the longitude of the ascending node (Ω). The G objects do not have enough orbital coverage and information to constrain the parameters related to the central mass (the mass of the black hole, the distance to our Galactic Centre R_0 , the position and velocity of the central mass). Therefore, we fixed the values of the black hole mass and R_0 to the ones obtained from SO-2's measurements¹¹, that is, to $M = 3.964 \times 10^6 M_{\odot}$ (where M_{\odot} is the solar mass) and $R_0 = 7.971$ kpc.

Our orbital fits are performed using Bayesian inference with a Multi-Nest sampler 38,39 . The radial velocity measurements are assumed to be independent and normally distributed. To take into account possible systematics at the level of the orbital fit, we use a likelihood that includes a systematic uncertainty ($\sigma_{\rm RV}$) for the radial velocities. In summary, the radial velocity (RV) measurements are assumed to be distributed following:

$$RV_i \sim N[RV(t_i), \sigma_{RV_i}^2 + \sigma_{RV}^2]$$

where RV_i(t) are the predicted radial velocity values, σ_{RV_i} are the measurement uncertainties and where $x \sim \text{N}[\mu, \sigma^2]$ denotes that x is normally distributed around μ with a variance of σ^2 . On the other hand, the astrometric measurements are assumed to be correlated, that is, the likelihood is assumed to be a multivariate normal distribution characterized by a covariance matrix. In addition, to take into account possible systematics at the level of the orbital fit, we also include an additional parameter: a systematic uncertainty for the astrometry, σ_{astro} . The astrometric measurements are therefore assumed to be distributed as:

$$\mathbf{x} \sim N[x(\mathbf{t}_{astro}), \Sigma_x]$$
 and $\mathbf{y} \sim N[y(\mathbf{t}_{astro}), \Sigma_y]$

where $x(\mathbf{t}_{astro})$ and $y(\mathbf{t}_{astro})$ are the predicted astrometric values, Σ_x and Σ_y are the covariance matrices, and $\mathbf{x} \sim N[\boldsymbol{\mu}, \boldsymbol{\Sigma}]$ denotes that the vector \mathbf{x} is normally distributed around the vector $\boldsymbol{\mu}$ with a covariance matrix of $\boldsymbol{\Sigma}$. We model the covariance matrices \mathbf{x} by:

$$\begin{split} & [\boldsymbol{\Sigma}_{\boldsymbol{x}}]_{ij} = [\boldsymbol{\rho}]_{ij} \sqrt{\boldsymbol{\sigma}_{x_i}^2 + \boldsymbol{\sigma}_{\text{astro}}^2} \sqrt{\boldsymbol{\sigma}_{x_j}^2 + \boldsymbol{\sigma}_{\text{astro}}^2} \\ & [\boldsymbol{\Sigma}_{\boldsymbol{y}}]_{ij} = [\boldsymbol{\rho}]_{ij} \sqrt{\boldsymbol{\sigma}_{y_i}^2 + \boldsymbol{\sigma}_{\text{astro}}^2} \sqrt{\boldsymbol{\sigma}_{y_j}^2 + \boldsymbol{\sigma}_{\text{astro}}^2} \end{split}$$

where σ_{astro} is the systematic uncertainty and ρ is the correlation matrix that characterizes the correlation of the measurement errors. This correlation matrix is given by¹¹:

$$[\rho]_{ij} = (1-c)\delta_{ij} + ce^{|-d_{ij}|/\Lambda}$$

where δ_{ij} is the Kronecker delta and d_{ij} is the 2D projected distance between point i and point j:

$$d_{ij} = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$$

Here \varLambda is a correlation length scale that typically takes the value of half the diffraction limit of the detector¹¹, and is fixed here at a value of 35 mas; c is a mixing parameter that is fitted simultaneously with all parameters and that characterizes the strength of the correlation. Corner plots of the best fit are shown in Extended Data Fig. 5 and the best fit parameters are reported in Extended Data Table 3.

In addition, we use uniform priors on all fitted parameters. We show in the next Methods section that this does not bias our estimates.

Dependence on priors

To estimate the orbits of the G objects, we use uniform priors on all eight fitted parameters (six orbital parameters and two systematic uncertainty parameters). Although uniform priors are commonly assumed in orbit fitting, this choice has been shown to cause potential biases in estimated parameters when orbital periods are much longer than the time baseline of observations 40,41. To assess the impact of our fitting procedure in this context, we ran simulations to assess possible biases in the estimated parameters and to test the accuracy of confidence intervals obtained in our analysis⁴¹. We generated 100 mock data sets with simulated measurements at epochs corresponding to our observations. The simulated measurements were randomly drawn from a normal distribution about an assumed 'true' value, with a dispersion equal to the true measurement error at that epoch. We fit each of these 100 mock data sets with the same orbit fitting procedure as described above. The bias on each fitted parameter is computed from the difference between the estimated parameter value and the input parameter value, normalized by the 1σ confidence interval on the corresponding parameter. For all eight fitted parameters, the distribution of bias values is centred around zero for G3, G4, G5 and G6 within the 68% confidence interval, indicating non-biased parameter estimates.

In addition, we evaluate statistical efficiency to demonstrate that the confidence intervals used in this analysis are well-defined and have close to exact coverage. According to the classical definition of a confidence interval, 1 σ confidence intervals inferred from each orbit fit should cover the 'true' value (from the simulated data) 68% of the time. In other words, given 100 randomly drawn simulated data sets, a 68% confidence interval requires that about 68 out of 100 fits produce a confidence interval that covers the true value⁴². However, effective coverage (defined as the experimentally determined percentage of data sets in which the inferred confidence interval covers the true value) is rarely exact. Statistical efficiency, defined as the ratio of effective coverage to stated or expected coverage (for example, 68% for a 1σ confidence interval), is thus a powerful performance diagnostic that can be used to investigate the accuracy of calculated confidence intervals⁴¹. By definition, a statistical efficiency of one indicates exact coverage. The statistical efficiencies for all parameters for G3, G4 and G6 are

consistent with one. For G5, the period is slightly under-covered with a statistical efficiency of 0.81 ± 0.09 , indicating that the inferred confidence interval on G5's period is slightly underestimated. The statistical efficiencies for all other parameters for G5 are consistent with one. This analysis indicates that, in general, confidence intervals calculated in this work provide robust estimates of the statistical uncertainty.

Flux calibration

For this project we perform the absolute flux calibration of OSIRIS data. To do so, we need to apply aperture photometry to isolate sources of known magnitude. Even though many of the stellar sources are well-known, the Galactic Centre is a very crowded environment: no source is truly isolated and the combined background of underlying sources is challenging to determine. To measure the flux of stars on the field we would need to use a very small aperture radius. However, the PSF cannot be easily modelled, since the observations are taken through adaptive optics. Moreover, the OSIRIS field of view is very small, making an accurate empirical knowledge of the PSF impossible.

Instead we use observations of standard A stars, obtained the same night as the Galactic Centre observations. We used: HD 155379, HD 195500 and HD 146606 with 2MASS *K* magnitudes of 6.52, 7.19 and 7.04 respectively. These stars are chosen to be at around the same airmass as the science targets and their observations are taken as close in time as possible to the science observations (within a few hours). These are well-known, bright and isolated sources for which we can use aperture photometry over a very large radius that encompasses almost all of the source. In this way we can gather close to 100% of the flux and avoid problems related to the PSF shape.

The A-star frames are obtained by dithering around the star's position and are treated with the standard calibration procedure to remove atmospheric effects. Here, for each epoch, we use all available frames independently to measure the counts-to-Jy conversion factor and use their dispersion to estimate the corresponding uncertainty. Both the science mosaic and the A-star frames are calibrated in the standard way of the group. For each epoch, for each frame, we perform a 2D Gaussian fit to get the centroid of the source and an estimate of the Gaussian σ . We extract the A-star flux ($F_{\rm ap}$) within a -12-pixel aperture radius, which is -6 times the σ of the 2D Gaussian fit (that is, that encompass -100% of the stars' flux). We subtract the sky background through an annulus 1 pixel larger than the aperture size and of 1-pixel thickness ($F_{\rm an}$). We use the known magnitude of the star (from the 2MASS catalogue) to compute its expected flux in the Kn3 band ($F_{\rm th}$) using Vega as zero-point. The conversion factor is computed as follows:

$$CF = \frac{F_{th}}{F_{ap} - F_{an}} \frac{1}{df}$$

where df is the width of the spectral channel in hertz. The same process is repeated for all frames within one given epoch and the median is adopted as the value for that epoch and the dispersion as the uncertainty. We checked other potential sources of error, such as imprecise pointing on the centre of the star, but we always obtained uncertainties several orders of magnitude smaller than the one coming from the dispersion.

The disadvantage of not using sources within the science field for calibration is that there could be variations of the fraction of photons reaching the detector surface between the science target and calibrator observations—for example, because of variations in the extinction due to passing clouds at the telescope site. However, the variation in extinction due to clouds is usually less than 0.5 mag and should have an impact smaller than the final calibration error. Indeed, the final calibration factor does not vary much from night to night or even year to year. The most dramatic variations are related to instrumental hardware upgrades. Therefore, we have chosen to divide the OSIRIS instrument

timeline into three parts¹⁴: (1) 2006–12 before the grating upgrade; (2) 2012–16 before the spectrograph upgrade; and (3) from 2017 on.

For each of these periods, we consider the median of the conversion factors as the final value and the dispersion of the measurements as its uncertainty. This way we obtain three calibration factors with an error of about 10%.

We also compare the conversion factor obtained with the A stars to the one obtained using multiple stars on the field. In the case of the field stars the values are very sensitive to the applied correction to the aperture flux, and the conversion factor therefore varies more dramatically (even within close epochs) than in the case of the A stars (Extended Data Fig. 6). Therefore, we can affirm that the flux calibration obtained through standard stars is more robust.

Flux measurements

In order to maximize the signal-to-noise ratio, we measured the flux on data-cubes combined year by year (hence 1 cube per year). Multiple datasets were combined for each year using all available epochs to enhance the signal-to-noise ratio in the emission lines, resulting in 11 data-cubes corresponding to 11 years of data taken between 2006 and 2018 (except for 2007 and 2016, where the image quality was too poor and no Kn3 data cube was obtained, respectively).

The Bry line fluxes of the G objects are obtained for each combined data-cube by extracting its spectrum and performing a Gaussian fit to the emission line. Flux measurements were derived from each line profile using an equivalent width method. The equivalent width was computed from the Gaussian fit parameters of the emission features from Bry and [Fe III]. A conversion from measured flux to W m⁻² was established using the flux calibration performed for each epoch from observations of A standards (Methods section 'Flux calibration'). Note that the absolute flux calibration can have relatively high errors in AO systems where the image quality and encircled energy in the data collection can change substantially on short timescales and from night to night. The measured fluxes are dereddened³⁴. The measurements are reported in the following Methods section and in Extended Data Table 4.

Flux and FWHM summary table

The measured flux densities for all objects are reported in Extended Data Table 4, along with measurements of the spatial and spectral width. We do not detect any continuum in the Kn3 band in any of the G sources (we find a detection limit of 0.01 mJy). However, G2 detection in K-broadband imaging data has been claimed 20 , finding a dereddened flux of about 0.25 mJy in $\rm K_s$ (2.18 μm central wavelength), which compares to a detection limit of 0.07 mJy in the K′ band 19 (2.12 μm central wavelength).

G-object formation scenarios

Although many hypotheses have been proposed to explain the origin of G1 and G2, the principal debate has centred on whether they are compact, dusty gas clouds or gaseous features anchored on stellar cores. G1 and G2 were first interpreted as purely gas and dust clouds⁶. However, G1 and G2 have remained intact after passing through periapse, which has led some $^{8.25-27}$ to argue that they must have a stellar core shielded by an extended opaque envelope of gas and dust.

Given the absence of photospheric emission, the original G2 hypothesis⁶ interpreted it as an ionized gas cloud of 3 Earth masses. Since its discovery, the gas has been tidally interacting with the black hole. It was argued ^{10,24} that G1 and G2 are knots of gas and dust that have formed within a common orbiting filament. Indeed, their orbits are similar, but substantially different⁹. A drag force has been invoked to explain this difference¹⁰. However, the common filament interpretation cannot apply to the new sources we present here because of their very different location and orbit.

Given the strong tidal forces near the black hole, and the high flux of ultraviolet radiation in this region, compact gas clouds would supposedly be transient phenomena, unless they could be stably confined by a high external pressure⁴³. Otherwise, they would need to be continuously produced in order to account for the sizable population we observe. The region is rich in gaseous interstellar medium structures, including the Epsilon source⁴⁴ (a nearby feature immediately west of the field), the Minispiral⁴⁵ and the Circumnuclear Disk⁴⁶. It is possible that small pieces of these larger structures get detached and stay in the region for a few decades before getting destroyed, but it is not clear that such gas blobs would be as compact as the observed G sources.

The alternative hypothesis is that the G objects host a star. Whereas G2 is tidally interacting during its closest approach to Sgr A^{*10} , the dust component of G2 has remained unresolved. The emitting gas is unbound at closest approach¹⁰, but that is not inconsistent with the existence of a stellar mass keeping the dust emission compact⁸.

Several models have been proposed to account for G2 in terms of an optically thick distribution of dust surrounding a star: a young, low-mass star (T Tauri star) that has retained a protoplanetary disk 26 (scenario 1) or that generates a mass-loss envelope 27 (scenario 2); or alternatively, the merger of a binary system $^{9.25,28}$ (scenario 3).

In the first scenario, G2 could be a young star that has retained a protoplanetary disk and that was scattered inwards from the massive cluster of young stars distributed on larger scales³⁷. Stars having protoplanetary disks are common in young clusters, but it is unclear whether such disks would survive the abrupt scattering event needed to transfer the protostars onto such tight orbits around the black hole. Furthermore, protoplanetary disks do not last very long except under the most benign conditions (up to 5–7 Myr; ref. 47), therefore a population of such objects in the particularly hostile Galactic Centre environment is not obviously compatible with the timescale of the last star formation event (4-6 Myr ago²³). Therefore, the protostellar disk hypothesis might be ruled out as an explanation for the common origin of these objects unless star formation is continuous at the Galactic Centre, as some have argued 48,49. This matter is still under debate, but any demonstration that a substantial number of protoplanetary disks have survived in the central 0.05 pc of the Galactic Centre would have important implications for our understanding of star formation in this region.

In the second scenario, G2 was proposed to be the product of the mass-losing envelope of a young, low mass, T Tauri star. One open question is whether the observed Br γ emission is caused by collisions or ionization by Galactic Centre stars. In the case of emission by collisions the emission is unrelated to the G objects being located in the vicinity of the black hole, which raises the question of why these objects have not been seen elsewhere.

In the third scenario, G1 and G2 are proposed to be binary merger products. The influence of the black hole will enhance the probability that binary systems merge through eccentricity oscillations due to the eccentric Kozai–Lidov (EKL) mechanism²9. The merging process would inflate the outer layers of the merging binaries, which would produce an extended envelope of dust and gas around the merger product, hiding the central mass for an extended period of time. A few binary mergers are known in the Galaxy $^{50-52}$. However, such mergers took place recently and were discovered because of the strong variability that probably characterizes the early stages of a merger. According to the merger hypothesis, the G objects are more likely to be in a much quieter long-term phase in which the merger has stabilized and is evolving slowly on a Kelvin–Helmholtz timescale. For this reason, it is not meaningful to compare the G objects to presently known mergers, especially because we still have scant quantitative knowledge of how a merger evolves.

The binary merger hypothesis could offer a mechanism to rejuvenate stars in the Galactic Centre, as in the case of blue stragglers^{53,54} (but see ref. ⁵⁵): some of the observed young stars orbiting closely around the central black hole (the S stars) could be the product of the merger of older stars. However, it is unclear whether this process can produce

sufficiently massive stars to account for the S stars (typically $(10-30)M_{\odot}$, ref. 21). The new star resulting from a merger can appear to be from a few Myr to several Gyr younger, depending on the merging circumstances 30 .

Even if the G objects cannot account for the origin of the S stars, they are possibly connected to them. Here we have shown that the orbits of G3, G4, G5 and G6 have very different inclinations. This random distribution of the orbital planes very closely resembles the distribution of the orbits of S stars. If a stellar object is hidden inside a G object it must have a relatively small mass (less than a few solar masses), given the weakness of the continuum emission from these objects. In the central parsec, given the K′ detection limit 19, we can detect stars with masses down to -1.5 M_{\odot} (ref. 56). However, we could detect low-mass binary systems that merge, producing a shell of dust and gas: gas would be ionized by the environmental radiation, whereas dust would be heated by both environmental radiation and the luminous energy emerging from the interior of the G object. The G objects could therefore offer a unique window on the low-mass, currently undetectable, part of the S-star cluster.

As a consistency check, we investigated whether the number of observed G objects is consistent with the expected number of binary mergers (see the following Methods section).

The EKL-induced binary merger hypothesis offers a compelling explanation for the origin of G objects that fits well with the three-body dynamics that are necessarily at play in a dense stellar environment, with the third body being a supermassive black hole. Moreover, a wide range of eccentricities is expected for such binary merger products²⁸, in agreement with what we observe.

Binary fraction estimate

To estimate the binary fraction from the current number of G objects, we assume that all observed G objects are binary merger products (indeed we expect a large fraction of binaries in the Galactic Centre based on the orbital configuration of the stellar disk 57). We assume that all six of the G objects discussed here are relatively recent binary mergers, and that their progenitor binary systems were formed in the latest known star formation event $4-6\,\mathrm{Myr}$ ago. This assumption is supported by the fact that older binaries can only survive in the Galactic Centre if they are very tight, and therefore have a very low probability of merging 30 . They would consequently not contribute substantially to the observed population of G objects. We use binary merger rates 30 and the initial mass function 23 . Given the absence of continuum emission, we assume the G objects come from only the low-mass part of the population. Therefore, the binary fraction of low-mass stars is given by:

$$R = \frac{1}{2} \frac{N_{\rm B}}{N_{\rm m}} \tag{1}$$

where $N_{\rm B}$ is the number of binaries and $N_{\rm m}$ the number of low-mass stars. We should expect about 10% of all binary systems to have merged within a few million years from a given star formation event in the Galactic Centre³⁰. Also, 20%–25% of the initial binary population will have evaporated within the first few million years. So, given the observed number of G objects in the OSIRIS field of view ($N_{\rm G}$ = 6), the number of binaries present today is given by:

$$N_{\rm B} = \frac{N_{\rm G}}{0.1} (1 - 0.25 - 0.1) \tag{2}$$

The initial mass function inferred by Lu et al.²³ is:

$$\frac{\mathrm{d}N}{\mathrm{d}m} = \xi m^{-\alpha} \text{ with } \alpha = 1.7$$

where ξ is a normalization factor. Using this we can compute the number of low-mass stars $(1 M_{\circ} < M < 10 M_{\circ})$, N_{m} :

$$\int_{1M_{\bullet}}^{10M_{\circ}} N_{\rm m} = \xi \int_{1M_{\bullet}}^{10M_{\circ}} m^{-\alpha} \tag{3}$$

Given the number of stars we detect in the OSIRIS field of view ($N_{\rm M}\approx 64$ stars with $M>10M_{\odot}$ is the average for 2018 data), we can determine the normalization factor and estimate the number of low-mass stars from equation (3):

$$\int_{10M_{\circ}}^{30M_{\odot}} N_{\rm M} = \xi \frac{M^{1-\alpha}}{1-\alpha} \Rightarrow \xi \approx 0.15 \Rightarrow N_{\rm m} \approx 478$$

From equations (1) and (2), it follows that the current binary fraction is $P \approx 5\%$

Locally in the Galaxy, the binary fraction of solar-type stars 31 is 50 %. Only about 20% of such binaries—which would be stable in the field—can be stable in the Galactic Centre 28 , which leads to 10% solar-type star binaries in the Galactic Centre. 35% of these binaries have already evaporated after formation 30 , resulting in a surviving binary fraction of 6%–7%, compatible with what we deduce from the observed abundance of G objects.

Data availability

All data generated or analysed during this study are included in this published article.

Code availability

The orbit fit code is publicly available at https://zenodo.org/record/3305315#.XXmLPC3MzUY.

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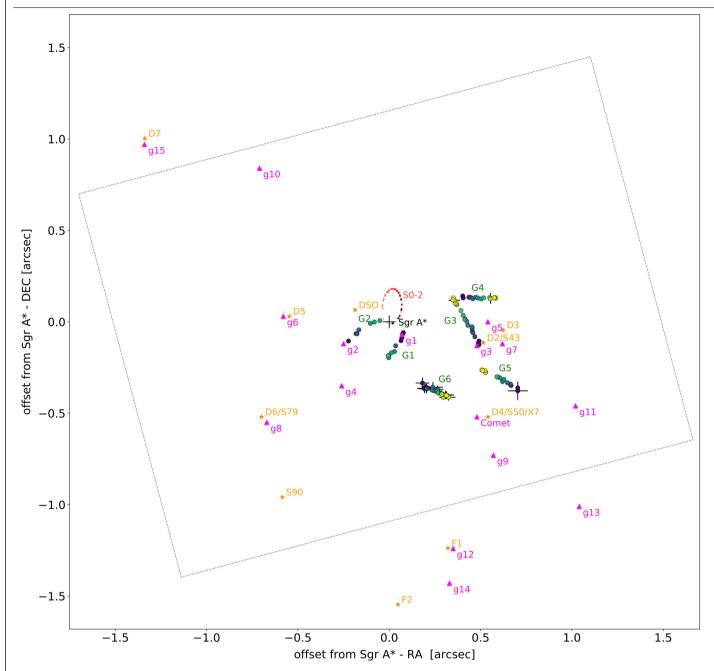
Author contributions A.C., R.D.C. and M.R.M. designed the project, and carried out the analysis and the interpretation of the results. A.M.G. supervised the observing, data acquisition and data reduction. T.D. and D.S.C. obtained and reduced the data. A.H., K.K.O'N. and B.N.S. contributed to the analysis and to the manuscript. A.C. wrote the manuscript with support from M.R.M. and R.N.C., and with contributions from all other authors. All authors provided critical feedback and helped gather data.

Competing interests The authors declare no competing interests.

Additional information

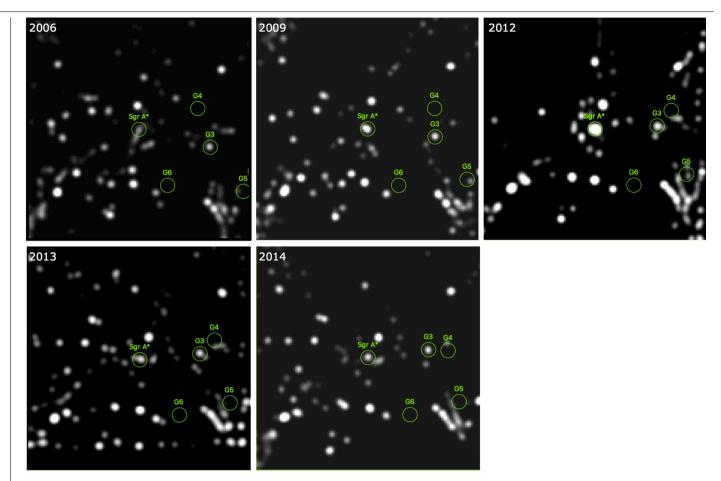
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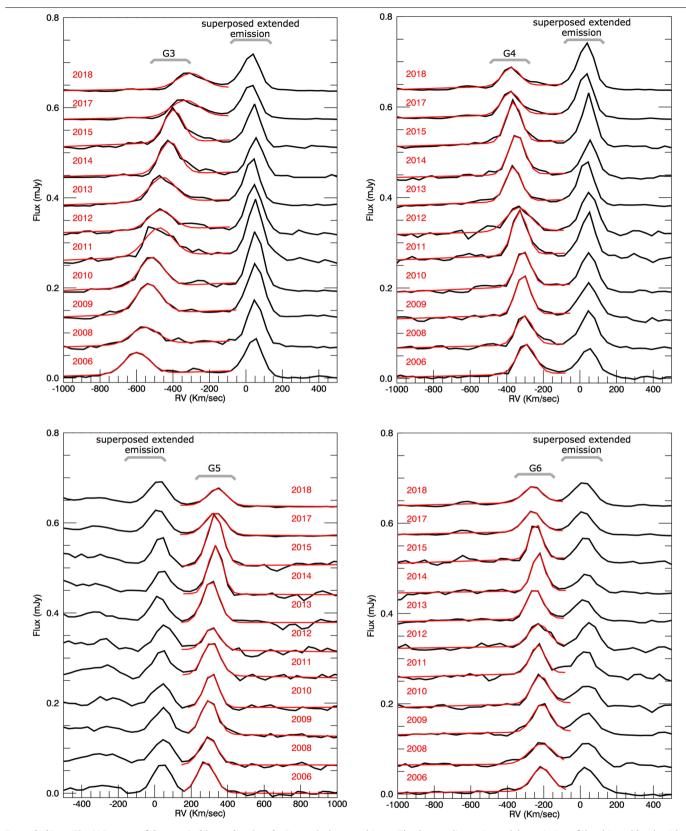


Extended Data Fig. 1 | **Infrared-excess sources and G objects.** Shown are the proper motions of the G sources (from 2006, in blue, to 2018, in yellow) along with the positions of infrared-excess sources 7 in orange (data obtained with

NACO at the VLT in 2005) and 17 in magenta (data obtained with NIRC2 at Keck in 2005). The red trace shows the proper motion of S0-2 (from NIRC2) as reference. The average OSIRIS field is displayed as a dotted rectangle.

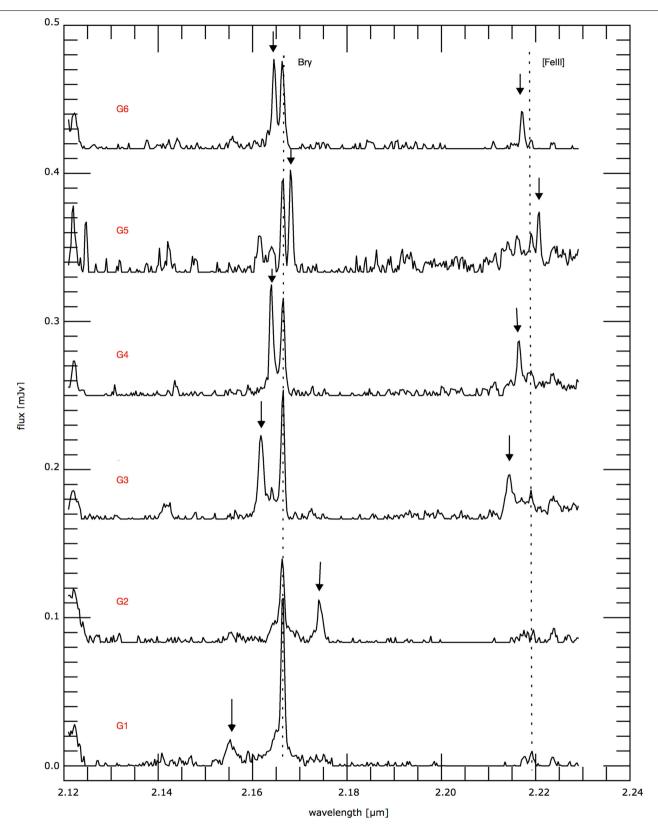


 $\textbf{Extended Data Fig. 2} | \textbf{New G objects in the L band.} \label{eq:local_lo$



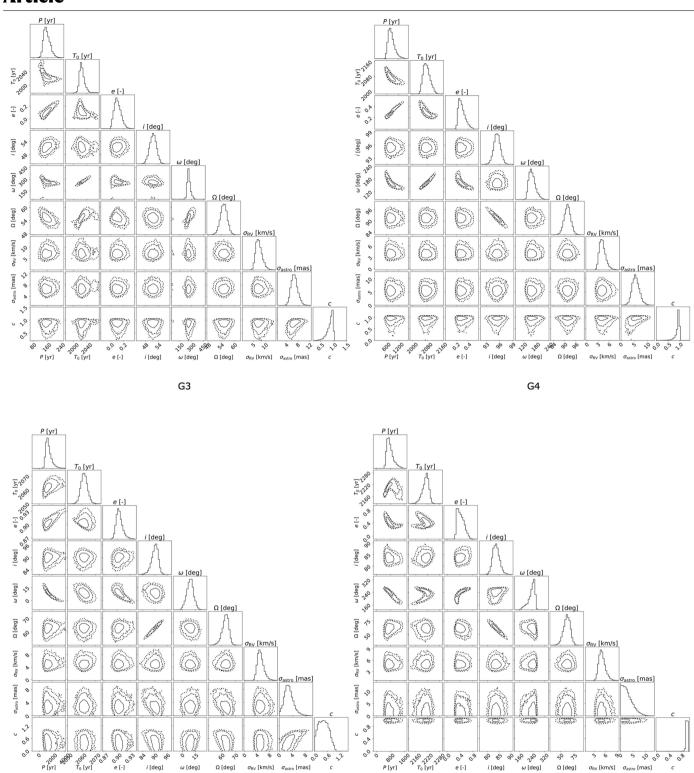
Extended Data Fig. 3 | Spectra of the new G objects showing the Bry emission line over time. Top row, G3 (left) and G4 (right); bottom row, G5 (left) and G6 (right). The spectra are extracted epoch by epoch (black). The Gaussian fit of the Bry emission line (red) is superimposed. There is no significantly detected variation (all values are compatible within 1σ) in the linewidth for any of the

objects. The data quality varies and the emission of the objects blends with neighbouring features as it changes radial velocity (RV) and position: this gives sometimes the impression of a broadening of the line which is not real. The emission line at the rest velocity is part of the extended emission present across the field and does not change with time.



Extended Data Fig. 4 | **Spectra of the G objects showing Bry and [Fe III] emission lines.** The Kn3 spectra of G objects G6–G1 are extracted over an aperture of 1.5-pixel radius from the 2006 combined dataset. The dotted lines show the rest-frame velocity of the Bry and [Fe III] emission lines. G3, G4, G5

and G6 show both Br γ and [Fe III] emission moving at the same velocity (Doppler-shifted emission indicated by the arrows), whereas G1 and G2 show only Br γ emission.



Extended Data Fig. 5 | Corner plots for orbit fitting of G3, G4, G5 and G6. See Methods section 'Orbit fitting' for details of the parameters displayed.

i [deg]

ω [deg]

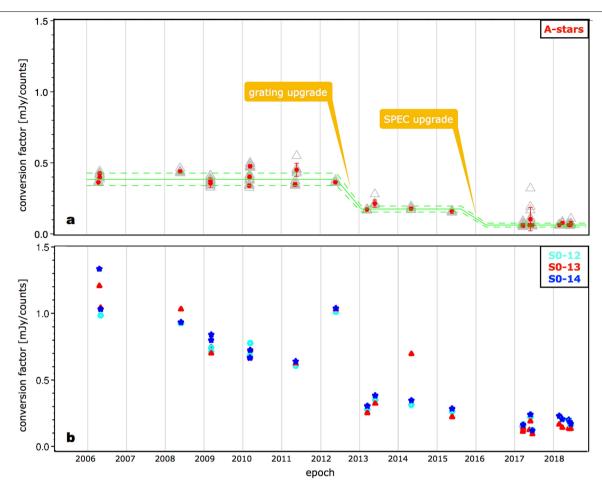
Ω [deg]

 $\sigma_{\rm RV}$ [km/s] $\sigma_{\rm astro}$ [mas]

 $\sigma_{\sf RV}$ [km/s] $\sigma_{\sf astro}$ [mas]

ω [deg]

Ω [deg]



Extended Data Fig. 6 | Unit conversion factors as a function of time. a, Factor obtained using calibration A stars (single frames in grey triangles, median for each epoch in red dots, dispersion used as error bar). **b**, Factor obtained using stars in the science field. The dispersion when using stars in the science field is much larger. We use the A stars, for which most of the variation corresponds to

hardware changes in the instrument. We use the median value for each instrument period (green solid line) and use the dispersion as an estimate of the uncertainty (green dashed lines). See Methods section 'Flux calibration' for details.

Extended Data Table 1 | OSIRIS observations used for the orbital fit

Date	Used for orbit fit	# of frames	FWHM [mas]	LSR corr [km/s]
2006-06-18	G3 G4 G5 G6	9	65	10
2006-06-30	G3 G4 G5 G6	9	59	4
2006-07-01	G3 - G5 G6	9	64	4
2008-07-25	G3 G4 G5 G6	11	60	-7
2009-05-05	G3 G4 G5 -	12	60	30
2009-05-06	G3 G4 G5 G6	12	69	30
2010-05-05	G3 G4 G5 G6	6	67	30
2010-05-08	G3 G6	11	69	29
2011-07-10	G3 G4 G5 G6	6	71	0
2012-07-22	G3 G4 G5 G6	9	81	-6
2013-05-14	G3 G4 G5 G6	11	91	27
2013-07-27	G3 - G5 G6	11	66	-8
2014-07-03	G3 G4 G5 G6	9	66	3
2015-07-21	G3 G6	7	56	-5
2017-05-17	G3 G4 G5 G6	11	73	25
2017-05-18	- G4 - G6	9	94	25
2017-05-19	- G4 - G6	6	86	24
2017-07-19	G3 G6	12	77	-4
2017-08-14	G3 - G5 G6	8	75	-14
2018-04-24	G3 - G5 G6	7	73	34
2018-05-23	- G4 G5 G6	14	91	23
2018-07-22	- G4 - G6	11	77	-6
2018-07-31	G3 G4 G5 G6	11	73	-9
2018-08-11	G3 G4 G5 G6	9	79	-13

The date is reported in YYYY-MM-DD format. All frames had integration times of 900 s. The FWHM value reported is for the star SO-2. To obtain radial velocities in the local standard of rest (LSR) reference frame, each observed radial velocity is corrected for the Earth's rotation, its motion around the Sun, and the Sun's peculiar motion with respect to the LSR.

Extended Data Table 2 | Measured values of positions and radial velocities

	epoch	RA	err	DEC	err	RV	err		epoch	RA	err	DEC	err	RV	err
	53904.4	0.487	0.007	-0.117	0.005	-594	2		53904.4	0.402	0.005	0.142	0.004	-293	1
	53916.3	0.492	0.009	-0.125	0.006	-600	2		53916.3	0.405	0.009	0.131	0.006	-291	2
	53917.3	0.492	0.009	-0.105	0.006	-592	2		54672.3	0.436	0.008	0.135	0.006	-304	1
	54672.3	0.469	0.009	-0.082	0.005	-555	3		54956.5	0.445	0.009	0.133	0.009	-310	1
	54956.5	0.455	0.004	-0.052	0.001	-536	2		54957.5	0.447	0.012	0.133	0.004	-313	1
	54957.5	0.458	0.004	-0.059	0.003	-531	2		55321.5	0.458	0.012	0.126	0.006	-314	1
	55321.5	0.454	0.003	-0.035	0.003	-518	1		55752.3	0.473	0.005	0.134	0.004	-330	1
	55324.5	0.454	0.008	-0.027	0.002	-512	2		56130.3	0.484	0.023	0.131	0.010	-334	2
G3	55752.3	0.431	0.004	-0.019	0.010	-478	3	G4	56426.5	0.502	0.005	0.125	0.002	-345	1
00	56130.3	0.425	0.005	0.002	0.004	-464	3	04	56841.3	0.517	0.009	0.131	0.005	-346	1
	56426.5	0.416	0.002	0.015	0.001	-450	2		57890.4	0.550	0.004	0.133	0.003	-360	1
	56500.3	0.414	0.004	0.014	0.002	-438	2		57891.5	0.554	0.012	0.128	0.029	-360	1
	56841.3	0.405	0.002	0.036	0.001	-419	1		57892.5	0.553	0.012	0.125	0.008	-360	1
	57224.3	0.393	0.009	0.062	0.005	-398	1		58261.4	0.581	0.004	0.132	0.003	-361	1
	57890.4	0.370	0.005	0.094	0.002	-324	3		58321.3	0.583	0.005	0.128	0.002	-368	2
	57953.3	0.369	0.003	0.098	0.002	-312	2		58330.3	0.578	0.005	0.133	0.004	-363	2
	57979.2	0.362	0.005	0.102	0.003	-318	2		58341.3	0.575	0.006	0.132	0.003	-365	1
	58232.5	0.356	0.032	0.118	0.010	-298	3		epoch	RA	err	DEC	err	RV	err
	58330.3	0.351	0.005	0.131	0.003	-288	2		53904.4	0.19	0.03	-0.37	0.02	-210	2
	58341.3	0.349	0.009	0.120	0.005	-300	2		53916.3	0.18	0.04	-0.33	0.03	-207	2
	epoch	RA]	err	DEC	err	RV	err	G6	53917.3	0.20	0.02	-0.35	0.01	-209	1
	53904.4	0.70	0.06	-0.38	0.05	267	2		54672.3	0.20	0.05	-0.36	0.03	-210	2
	53916.3	0.70	0.01	-0.37	0.01	281	2		54957.5	0.21	0.05	-0.37	0.02	-210	1
	53917.3	0.70	0.01	-0.36	0.01	276	1		55321.5	0.24	0.05	-0.36	0.03	-212	2
	54672.3	0.67	0.01	-0.35	0.01	296	2		55324.5	0.27	0.03	-0.37	0.02	-225	1
	54956.5	0.66	0.01	-0.34	0.00	297	1		55752.3	0.24	0.03	-0.37	0.01	-232	2
	54957.5	0.66	0.01	-0.34	0.00	304	1		56130.3	0.25	0.03	-0.38	0.01	-227	2
	55321.5	0.65	0.01	-0.33	0.00	311	1		56426.5	0.26	0.02	-0.38	0.01	-230	1
	55752.3	0.62	0.01	-0.33	0.01	311	1		56500.3	0.26	0.02	-0.38	0.01	-230	1
G5	56130.3	0.63	0.01	-0.31	0.01	314	2		56841.3	0.27	0.01	-0.39	0.01	-229	1
	56426.5	0.61	0.00	-0.31	0.00	327	0		57224.3	0.29	0.03	-0.39	0.02	-244	1
	56500.3	0.59	0.00	-0.30	0.00	329	1		57890.4	0.30	0.02	-0.40	0.01	-238	1
	56841.3	0.59	0.00	-0.30	0.00	331	0		57891.5	0.30	0.02	-0.41	0.01	-237	1
	57890.4	0.53	0.00	-0.28	0.00	352	0		57892.5	0.30	0.02	-0.41	0.01	-240	2
	57979.2	0.53	0.00	-0.28	0.00	354	1		57953.3	0.30	0.02	-0.40	0.01	-245	1
	58232.5	0.52	0.01	-0.27	0.00	360	1		57979.2	0.29	0.03	-0.40	0.01	-240	1
	58261.4	0.52	0.00	-0.27	0.00	358	1		58232.5	0.31	0.05	-0.40	0.02	-253	2
	58330.3	0.51	0.01	-0.26	0.00	363	2		58261.4	0.32	0.04	-0.41	0.02	-244	1
	58341.3	0.51	0.00	-0.27	0.00	358	2		58321.3	0.31	0.03	-0.40	0.02	-237	1
									58330.3	0.31	0.02	-0.40	0.01	-241	1
									58341.3	0.31	0.02	-0.40	0.01	-244	1

Data are shown for G3, G4, G5 and G6. The epochs are reported as modified Julian date (MJD). The positions (RA and dec.) are offsets from Sgr A* in arcseconds. The position uncertainties are the standard deviation obtained through a Monte Carlo method. The radial velocities (RV) are in km s⁻¹ and have been corrected for the local standard of reference (LSR). The reported radial velocity uncertainties (err.) are purely statistical (1 σ of the line fit). There is an additional systematic uncertainty that we fold into the orbit fit.

Extended Data Table 3 | Best fit orbital parameters

	P [yr]	T0 [yr]	е	i [deg]	ω	Ω	σ_{astro}	σ_{RV}	С
G3	156+22	2024+9	$0.11^{+0.06}_{-0.05}$	$52^{+1.5}_{-1.6}$	261 ⁺²³ ₋₁₆	55 ^{+1.5} _{-1.6}	$6.7^{+1.3}_{-1.1}$	$7.2^{+1.6}_{-1.1}$	$0.89^{+0.08}_{-0.15}$
G4	815^{+190}_{-126}	2075^{+21}_{-16}	$0.28^{+0.07}_{-0.05}$	$95.4^{+0.8}_{-0.7}$	160+18	$92^{+1.7}_{-1.8}$	$5.5^{+1.5}_{-1.3}$	$4^{+0.9}_{-0.7}$	$0.96^{+0.03}_{-0.1}$
G5	1392+555	2062+2	$0.9^{+0.01}_{-0.01}$	$90.1^{+1.4}_{-1.7}$	$8.8^{+3.7}_{-4.1}$	$62.9^{+2.1}_{-2.6}$	$2.8^{+1.5}_{-1.2}$	$4.9_{-0.8}^{+1.1}$	$0.42^{+0.27}_{-0.25}$
G6	732+224	2211+13	$0.41^{+0.13}_{-0.09}$	$83.6^{+1.5}_{-1.3}$	242+13.8	$61.7^{+5.8}_{-6.4}$	$2.4^{+2.6}_{-1.7}$	5 ^{+0.9} _{-0.7}	$0.99^{+0.01}_{-0.02}$

We show the median and central 68% confidence interval of the best-fit orbital parameters for G3, G4, G5 and G6. See Methods section 'Orbit fitting' for nomenclature.

Extended Data Table 4 | Emission from the G objects

	NIRC2				C	SIRIS		
		flux	density	FWHM	;	S/N		
	L' [mJy]	Br γ [mJy]	[FeIII] [mJy]	spectral [km/s]	spatial ["]	Brγ	[FeIII]	
G3	2.5±0.5	1.16±0.15	0.59±0.11	156±5	0.10±0.02	24	14	
G4	<0.38±0.08	1.10±0.14	0.49±0.09	117±2	0.10±0.02	34	16	
G5	<0.57±0.11	0.99±0.13	0.44±0.08	110±2	0.12±0.02	17	16	
G6	<0.54±0.10	0.82±0.12	0.37±0.07	127±5	0.13±0.02	28	19	
G1	0.6±0.05	0.48±0.15	<0.027±0.005	293±20	0.10±0.04	8	-	
G2	2.12±0.15	0.65±0.19	<0.027±0.003	174±14	0.08±0.04	13	-	

We report properties of this emission: flux densities, spectral and spatial widths (as FWHM), and signal-to-noise ratios (S/N). The L' flux densities come from NIRC2 2012 measurements (GI is brighter in earlier epochs¹⁷). The total flux density for Bry and [Fe III] (2.2184 μ m) come from OSIRIS (average of all observing). For comparison, we report GI and GZ measurements from 2006 where all GI objects are detectable in OSIRIS data. All fluxes are dereddened³⁴. The spectral and spatial FWHM (an average of the x- and y-FWHM) are measured for Bry. These values are not corrected for instrumental line width and PSF size (respectively ~100 km s⁻¹ and ~75 mas). The S/N of the other [Fe III] line has a value of ~6 for all objects.