



The GGCM Phase 2 experiment: global gridded crop model simulations under uniform changes in CO₂, temperature, water, and nitrogen levels (protocol version 1.0)

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Received: 23 August 2019 – Discussion started: 25 October 2019

Revised: 14 March 2020 – Accepted: 19 March 2020 – Published: 18 May 2020

Abstract. Concerns about food security under climate change motivate efforts to better understand future changes in crop yields. Process-based crop models, which represent plant physiological and soil processes, are necessary tools for this purpose since they allow representing future climate and management conditions not sampled in the historical record and new locations to which cultivation may shift. However, process-based crop models differ in many critical details, and their responses to different interacting factors remain only poorly understood. The Global Gridded Crop Model Intercomparison (GGCMI) Phase 2 experiment, an activity of the Agricultural Model Intercomparison and Improvement Project (AgMIP), is designed to provide a systematic parameter sweep focused on climate change factors and their interaction with overall soil fertility, to allow both evaluating model behavior and emulating model responses in impact assessment tools. In this paper we describe the GGCMI Phase 2 experimental protocol and its simulation data archive. A total of 12 crop models simulate five crops with systematic uniform perturbations of historical climate, varying CO₂, temperature, water supply, and applied nitrogen (“CTWN”) for rainfed and irrigated agriculture, and a second set of simulations represents a type of adaptation by allowing the adjustment of growing season length. We present some crop yield results to illustrate general characteristics of the simulations and potential uses of the GGCMI Phase 2 archive. For example, in cases without adaptation, modeled yields show robust decreases to warmer temperatures in almost all regions, with a nonlinear dependence that means yields in warmer baseline locations have greater temperature sensitivity. Inter-model uncertainty is qualitatively similar across all the four input dimensions but is largest in high-latitude regions where crops may be grown in the future.

1 Introduction

Understanding crop yield response to a changing climate is critically important, especially as the global food production system will face pressure from increased demand over the next century (Foley et al., 2005; Bodirsky et al., 2015). Climate-related reductions in supply could therefore have severe socioeconomic consequences (e.g., Stevanović et al., 2016; Wiebe et al., 2015). Multiple studies using different crop or climate models concur in projecting sharp yield reductions on currently cultivated cropland under business-as-usual climate scenarios, although their yield projections show considerable spread (e.g., Rosenzweig et al., 2014; Schauburger et al., 2017; Porter et al., 2014, and references therein). Although forecasts of future yields reductions can be made with simple statistical models based on regressions in historical weather data, process-based models, which simulate the effect of temperature, water and nutrient availability, and atmospheric CO₂ concentration on the process of

photosynthesis and the biology and phenology of individual crops, play a critical role in assessing the impacts of climate change.

Process-based models are necessary for understanding crop yields in novel conditions not included in historical data, including higher CO₂ levels, out-of-sample combinations of rainfall and temperature, cultivation in areas where crops are not currently grown, and differing management practices (e.g., Pugh et al., 2016; Roberts et al., 2017; Minoli et al., 2019). Process-based models have therefore been widely used in studies on future food security (Wheeler and Von Braun, 2013; Elliott et al., 2014a; Frieler et al., 2017), options for climate mitigation (Müller et al., 2015) and adaptation (Challinor et al., 2018), and future sustainable development (Humpenöder et al., 2018; Jägermeyr et al., 2017). They are a necessity for global gridded simulations, which allow understanding the global dynamics of agricultural trade, because global market mechanisms can strongly modulate the economic impacts of regional yield changes (Stevanović et al., 2016; Hasegawa et al., 2018). Global simulations are especially necessary in studying agricultural effects of climate change (Müller et al., 2017), since systematic climate assessments must account for cultivation area changes and crop selection switching (Rosenzweig et al., 2018; Ruane et al., 2018) and must consider inter-regional differences (e.g., Nelson et al., 2014; Wiebe et al., 2015).

Modeling crop responses, however, continues to be challenging, as crop growth is a function of complex interactions between climate inputs, soil, and management practices (Boote et al., 2013; Rötter et al., 2011). Models tend to agree broadly in major response patterns, including a reasonable representation of the spatial pattern in historical yields of major crops and projections of shifts in yield under future climate scenarios (e.g., Elliott et al., 2015; Müller et al., 2017). But process-based models still struggle with some important details, including reproducing historical year-to-year variability in many regions (e.g., Müller et al., 2017; Jägermeyr and Frieler, 2018), reproducing historical yields when driven by reanalysis weather (e.g., Glotter et al., 2014), and low sensitivity to extreme events (e.g., Glotter et al., 2015; Schewe et al., 2019). Global models pose additional challenges due to variable input data quality and limited ability for model calibration. Long-term projections therefore retain considerable uncertainty (Wolf and Oijen, 2002; Jagtap and Jones, 2002; Iizumi et al., 2010; Angulo et al., 2013; Asseng et al., 2013, 2015).

Model intercomparison projects such as the Agricultural Model Intercomparison and Improvement Project (AgMIP; Rosenzweig et al., 2013) are crucial in quantifying uncertainties in model projections (Rosenzweig et al., 2014). Intercomparison projects have also been used to develop protocols for evaluating overall model performance (Elliott et al., 2015; Müller et al., 2017) and to assess the representation of individual physical mechanisms such as water stress and CO₂ fertilization (e.g., Schauburger et al., 2017). However, to

date, few such projects have systematically sampled critical factors that may interact strongly in affecting crop yields. A number of modeling exercises in the last 5 years have begun to use systematic parameter sweeps in crop model evaluation and emulation (e.g., Ruane et al., 2014; Makowski et al., 2015; Pirttioja et al., 2015; Fronzek et al., 2018; Snyder et al., 2019; Ruiz-Ramos et al., 2018), but all involve limited sites and most also limited crops and scenarios.

The Global Gridded Crop Model Intercomparison (GGCMI) Phase 2 experiment is the first global gridded crop model intercomparison involving a systematic parameter sweep across critical interacting factors. GGCMI Phase 2 is an activity of AgMIP, and a continuation of a multi-model comparison exercise begun in 2014. The initial GGCMI Phase 1 (Elliott et al., 2015; Müller et al., 2017) compared harmonized yield simulations over the historical period, with primary goals of model evaluation and understanding sources of uncertainty (including model parameterization, weather inputs, and cultivation areas); see also Folberth et al. (2019) and Porwollik et al. (2017) for more information. GGCMI Phase 2 compares simulations across a set of inputs with uniform perturbations to historical climatology, including CO₂, temperature, precipitation, and applied nitrogen, as well as adaptation to shifting growing seasons (collectively referred to as “CTWN-A”). The CTWN-A experiment is inspired by AgMIP’s Coordinated Climate-Crop Modeling Project (C3MP; see Ruane et al., 2014; McDermid et al., 2015) and contributes to the AgMIP Coordinated Global and Regional Assessments (CGRA; see Ruane et al., 2018; Rosenzweig et al., 2018).

In this paper, we describe the GGCMI Phase 2 model experiments and present initial summary results. In the sections that follow, we describe the experimental goals and protocols; the different process-based models included in the intercomparison; the levels of participation by the individual models. We then provide an assessment of model fidelity based on observed yields at the country level, and show some selected examples of the simulation output dataset to illustrate model responses across the input dimensions.

2 Simulation objectives and protocol

2.1 Goals

The guiding scientific rationale of GGCMI Phase 2 is to provide a comprehensive, systematic evaluation of the response of process-based crop models to critical interacting factors, including CO₂, temperature, water, and applied nitrogen under two contrasting assumptions on growing season adaptation (CTWN-A). The dataset is designed to allow researchers to

- enhance understanding of models sensitivity to climate and nitrogen drivers;

- study the interactions between climate variables and nitrogen inputs in driving modeled yield impacts;
- characterize differences in crop responses to climate change across the Earth’s climate regions;
- provide a dataset that allows statistical emulation of crop model responses for downstream modelers; and
- explore the potential effects on future yield changes of adaptations in growing season length.

2.2 Modeling protocol

The GGCMI Phase 1 intercomparison was a relatively limited computational exercise, requiring yield simulations for 19 crops across a total of 310 model years of historical scenarios, and had the participation of 14 modeling groups. The GGCMI Phase 2 protocol is substantially larger, involving over 1400 individual 30-year global scenarios, or over 42 000 model years; 12 modeling groups nevertheless participated. To reduce the computational load, the GGCMI Phase 2 protocol reduces the number crops to five (maize, rice, soybean, spring wheat, and winter wheat). The reduced set of crops includes the three major global cereals and the major legume and accounts for over 50 % of human calories in 2016: nearly 3.5 billion tons or 32 % of total global crop production by weight (FAO, 2018). This set of major crops has the advantage of historical yield data globally available at subnational scale (Ray et al., 2012; Iizumi et al., 2014), and has been frequently used in subsequent analyses (e.g., Müller et al., 2017; Porwollik et al., 2017).

The Phase 2 protocol involves a suite of uniform perturbations from a historical climate time series. The baseline climate scenario for GGCMI Phase 2 is one of the weather products used in Phase 1, daily climate inputs for 1980–2010 from the 0.5° NASA AgMERRA (“agricultural”-modified Modern Era Retrospective analysis for Research and Applications) gridded reanalysis product. AgMERRA is specifically designed for agricultural modeling, with satellite-corrected precipitation (Ruane et al., 2015). The experimental protocol consists of 9 levels for water supply perturbations, 7 for temperature, 4 for CO₂, and 3 for applied nitrogen, for a total of 756 simulations (Table 1), 672 for rainfed agriculture and an additional 84 for irrigated (W_{∞}). Values of climate variable perturbations are selected to represent reasonable ranges for changes over the medium term (to 2100) under business-as-usual emissions. Values for nitrogen application levels are intended to cover a wide range of potentials. The resulting GGCMI Phase 2 dataset captures the distribution of crop model responses over a wide range of potential future climate and management conditions.

The protocol samples over all possible permutations of individual perturbations; i.e., all values are applied across all crops and regions, so that the protocol includes many combinations that are not realistic. For example, we simulate high

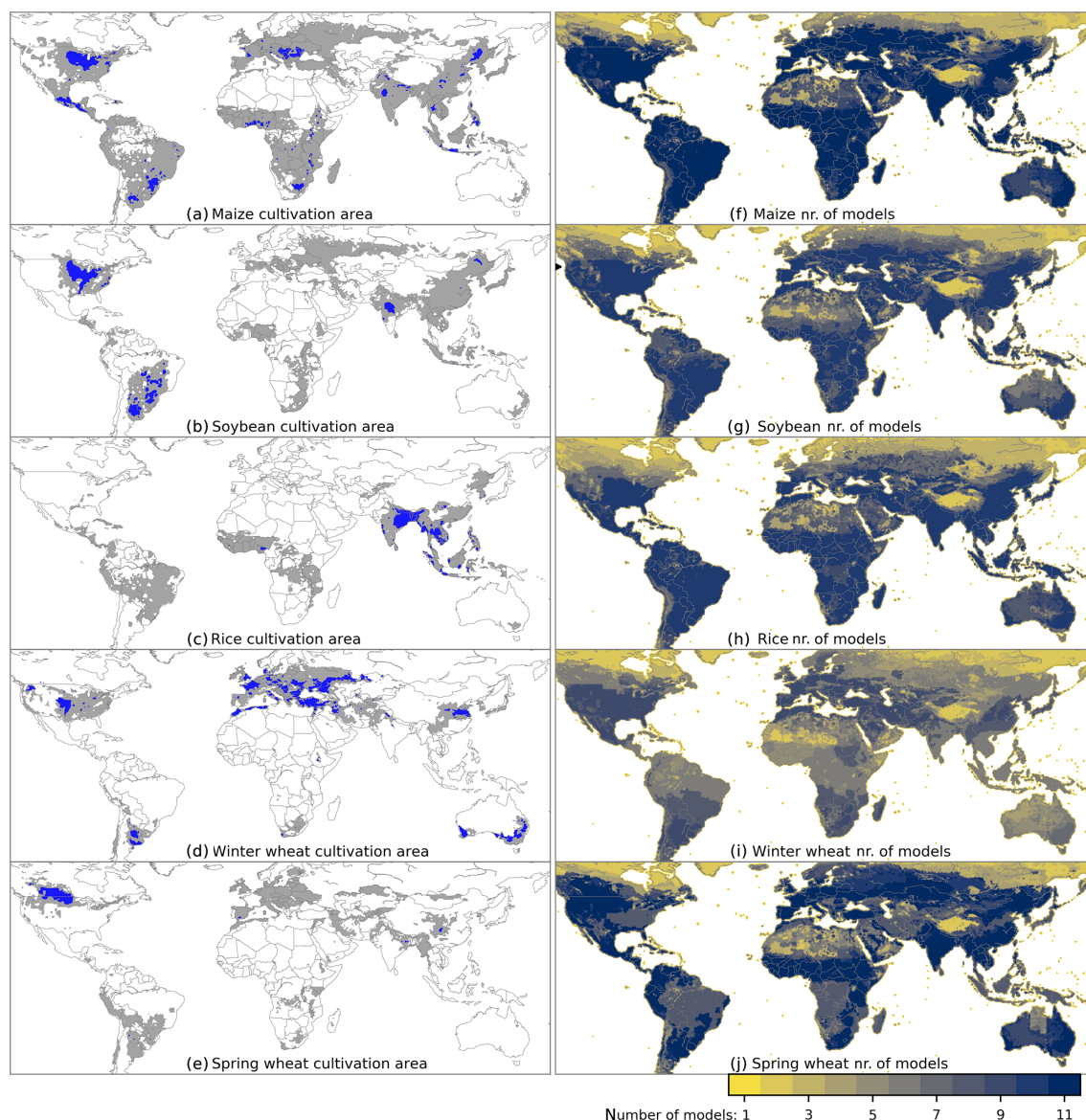


Figure 1. (a–e) Cultivated areas for maize, rice, and soybean from the MIRCA2000 (Monthly Irrigated and Rainfed Crop Areas around the year 2000) dataset (Portmann et al., 2010). Blue indicates grid cells with more than 20 000 ha (10 % of the equatorial grid cell), and the gray contour shows grid cells with more than 10 ha cultivated. Areas for winter and spring wheat areas are adapted from MIRCA2000 and two other sources; see text for details. For irrigated crops, see Fig. S1 in the Supplement. (f–j) Number of models providing simulations for each grid cell. All models provide the minimum areal coverage of the GGCM Phase 2 protocol, but some provide extra coverage at high latitudes or in arid or otherwise unsuitable areas.

N application to soybeans, which are N fixers and need little fertilizer. This choice also means that CO₂ changes are applied independently of changes in climate variables, so that higher CO₂ is not associated with higher temperatures or other particular climate changes. The purpose of the experiment is not to produce individual scenarios that represent realistic future states but to sample over a wide range of parameter space to enable understanding the factors that drive agricultural changes.

While all CTWN perturbations are applied uniformly across the historical time series, they are applied in different ways. CO₂ and nitrogen levels are specified as discrete values applied uniformly over all grid cells. Temperature perturbations are applied as absolute offsets from the daily mean, minimum, and maximum temperature time series for each grid cell, and water perturbations are applied as fractional changes to daily precipitation. The irrigated scenario (W_{∞}) is a particular case of water supply levels, in which crops are assumed to have no water constraints. That is, all crop wa-

Table 1. GGCM Phase 2 input parameter levels for each dimension. Temperature and precipitation values indicate the perturbations from the historical climatology. Irrigated (W_{∞}) simulations assume the maximum beneficial levels of water. Bold font indicates the “baseline” or historical level for each dimension. One model provided simulations at the $T + 5$ level.

Input variable	Simulation input values	Unit
CO ₂ (C)	360 , 510, 660, 810	ppm
Temperature (T)	−1, 0 , 1, 2, 3, 4, 6	°C
Precipitation (W)	−50, −30, −20, −10, 0 , 10, 20, 30, (and W_{∞})	%
Applied nitrogen (N)	10, 60, 200	kg ha ^{−1}
Adaptation (A)	A0: none , A1: new cultivar to maintain original growing season length	–

ter requirements are fulfilled regardless of local water supply limitations. To facilitate comparison, irrigated simulations use the same growing seasons as all other simulations, even though in reality irrigated growing seasons may be different (Portmann et al., 2010), and both irrigated and rainfed cases are simulated with near-global coverage.

The uniform perturbations of the GGCM Phase 2 protocol require some care in interpretation. Temperature and precipitation perturbations should be considered as differences from historical climatology within the growing season only. That is, a $T + 1$ simulation represents a 1 °C warmer growing season, not a 1 °C warmer annual mean temperature. (The distinction is important because in climate projections, winters generally warm more than summers; e.g., Haugen et al., 2018.) In the GGCM Phase 2 protocol, temperature and precipitation perturbations are applied uniformly in space, but future changes in temperature and precipitation will not be spatially or temporally uniform. In a realistic climate projection, higher latitudes generally warm more strongly than lower latitudes (e.g., Hansen et al., 1997), and the northern high latitudes warm more quickly than the southern ones. A GGCM Phase 2 simulation therefore represents a possible future state that could occur in each grid cell but not one that would in reality occur simultaneously in all grid cells across the globe. The GGCM Phase 2 simulations are intended to be used for climate impact assessment not directly but instead as a “training set” for statistical emulation of each crop model. Once an emulator is constructed from the outputs described here, it can be driven with growing-season climate anomalies from any climate model projection. The GGCM Phase 2 protocol does not involve any simulated changes in climate variability, but Franke et al. (2020) demonstrate that these effects are relatively minor and that GGCM Phase 2 emulators can effectively reproduce crop model yields under realistic future climate scenarios.

The area simulated in the GGCM Phase 2 protocol extends considerably outside currently cultivated areas, because cultivation may shift under climate change. Figure 1 shows both the present-day cultivated area of rainfed crops (left) and model coverage (right). (Figs. S1–S2 for currently cultivated area for irrigated crops; model coverage is the same.) Each model covers all currently cultivated areas and much of the uncultivated land area, run at 0.5° spatial resolution. To reduce the computational burden, the protocol requires simulation over only 80 % of Earth land surface area, omitting areas assumed to remain non-arable even under an extreme climate change, including Greenland, far-northern Canada, Siberia, Antarctica, the Gobi and Sahara deserts, and Central Australia. The protocol also allows omitting regions judged unsuitable for cropland for non-climatic reasons. Selection criterion involve a combination of soil suitability indices at 10 arcmin resolution and excludes those 0.5° grid cells in which at least 90 % of the area is masked as unsuitable according to any single index, and which do not contain any currently cultivated cropland. Currently cultivated areas are provided by the MIRCA2000 (Monthly Irrigated and Rainfed Crop Areas around the year 2000) data product (Portmann et al., 2010). Soil suitability indices measure excess salt, oxygen availability, rooting conditions, toxicities, and workability, and are provided by the IIASA (International Institute for Applied Systems Analysis) Global Agro-Ecological Zone model (GAEZ; FAO/IIASA, 2011). The procedure follows that proposed by Pugh et al. (2016). All modeling groups simulate the minimum required coverage, but some provide simulations that extend into masked zones, including, e.g., the Sahara and central Australia (Fig. 1, right).

2.3 Harmonization between models

The 12 models included in GGCM Phase 2 are all process-based crop models that are widely used in impacts assessments (Table 3). Although some models share a common base (e.g., the LPJ or EPIC families of models), they have subsequently developed independently. Wherever possible, the GGCM Phase 2 protocol harmonizes inputs, but differences in model structure mean that several key factors cannot be fully standardized across the experiment. These include soil treatment (which affects soil organic matter and carry-over effects of soil moisture across growing years) and baseline climate inputs.

While 10 of the 12 models participating in GGCM Phase 2 use the AgMERRA historical daily climate data product, two models require subdaily input data and thus use different baseline climate inputs: Processes of Radiation, Mass and Energy Transfer (PROMET) uses ERA-Interim reanalysis (Dee et al., 2011), and the Joint UK Land Environment Simulator (JULES) uses a bias-corrected version of ERA-Interim, the 3 h WFDEI (WATCH Forcing Data ERA-Interim) (Weedon et al., 2014), specifically the WFDEI version with pre-

cipitation bias-corrected against the Climate Research Unit (CRU) TS3.101/TS3.21 precipitation totals (Harris et al., 2014). The data products show some differences (Figs. S3–S4, which compare data products over currently cultivated areas for each crop). For example, for maize-growing areas, ERA-Interim daily precipitation is biased high from that in AgMERRA by 7 % ($< 1\sigma$), while mean daily precipitation in WFDEI is only 3 % higher. Precipitation differences are largest in wheat areas, where ERA-Interim is substantially wetter ($+60 \text{ mm yr}^{-1}$ or 10 %). Temperature differences are largest for rice, with ERA-Interim 1°C cooler than AgMERRA, and smaller for other crops, e.g., maize with ERA-Interim 0.45°C cooler and WFDEI 0.1°C warmer. These differences are relatively small compared to the perturbations tested in the protocol.

Planting dates and growing season lengths are standardized across models, following the procedure described in Elliott et al. (2015) for the “fullharm” setting. (The exception is that Phase 2, unlike Phase 1, uses identical growing seasons for rainfed and irrigated cases, to allow for direct comparison of simulations along the W dimension.) This harmonization is important because the parametrization of growing seasons can have strong effects on simulated yields (Müller et al., 2017; Jägermeyr and Frieler, 2018). In all the GGCM Phase 2 crop models, sowing dates are prescribed directly, but the length of the growing season is a product of crop phenology, which is driven mostly by phenological parameters and temperature. Modelers were therefore asked to adjust their phenological parameters so that the average growing season length of the baseline scenario ($C = 360$, $T = 0$, $W = 0$) matched the harmonization target. (The one exception to this harmonization protocol involves CARBON Assimilation In the Biosphere (CARAIB), whose team kept their own growing season specifications rather than tuning to standard lengths.) Two aspects of the procedure should be noted. First, the target growing seasons used in GGCM Phase 2 are crop and location specific. For example, present-day maize is sown in March in Spain, in July in Indonesia, and in December in Namibia (Portmann et al., 2010). Second, because temperature varies between years in the 30-year baseline climatology, realized growing season length will still vary in individual years even after harmonization.

The dependence of harvest dates on climate parameters means that growing seasons will alter under climate change in a model with phenological parameters tuned to match target growing seasons in the baseline climate. In general, warmer future scenarios produce shorter growing seasons. We denote simulations that allow these future changes as “A0” experiments, where 0 denotes “no adaptation”. The GGCM Phase 2 protocol includes a second set of experiments, “A1”, that assume that future cultivars are modified to adjust to changes along the T dimension in the CTWN experiment. For these simulations, modelers adjust phenological parameters for each temperature scenario to hold growing season length approximately constant. (CARAIB sim-

ulations follow the same principle, fixing growing season length at their baseline levels.) That is, the A1 simulations require running a model with seven different choices of cultivar parameters, one per warming level. Parameter settings for $T = 0$ are identical in both A0 and A1. The A1 simulations roughly capture the case in which adaptive crop cultivar choice ensures that crops reach maturity at roughly the same time as in the current temperature regime. This assumption is simplistic, and does not reflect realistic opportunities and limitations to adaptation (Vadez et al., 2012; Challinor et al., 2018) but provides some insight into how crop modifications could alter projected impacts on yields and is sufficiently easy to implement in a large model intercomparison project as GGCM.

Growing seasons for maize, rice, and soybean are taken from the SAGE (Center for Sustainability and the Global Environment, University of Wisconsin) crop calendar (Sacks et al., 2010), gap filled with the MIRCA2000 crop calendar (Portmann et al., 2010) and, if no SAGE or MIRCA2000 data are available, with simulated Lund–Potsdam–Jena managed Land (LPJmL) growing seasons (Waha et al., 2012) and are identical to those used in GGCM Phase 1 (Elliott et al., 2015). In GGCM Phase 2, we separately treat spring and winter wheat and so must define different growing seasons for each. As for the other crops, we use the SAGE crop calendar, which separately specifies spring and winter wheat, as the primary source for 69 % of grid cells. In the remaining areas where no SAGE information is available, we turn to, in order of preference, the MIRCA2000 crop calendar (Portmann et al., 2010) and to simulated LPJmL growing seasons (Waha et al., 2012). These datasets each provide several options for wheat growing season for each grid cell but do not label them as spring or winter wheat. We assign a growing season to each wheat type for each location based on its baseline climate conditions. A growing season is assigned to winter wheat if all of the following hold, and to spring wheat otherwise:

- The monthly mean temperature is below freezing point ($< 0^\circ\text{C}$) at most for 5 months per year (i.e., winter is not too long).
- The coldest 3 months of a year are below 10°C (i.e., there is a winter).
- The season start date fits the criteria that
 - if in the Northern Hemisphere, it is after the warmest or before the coldest month of the year (as winter is around the end/beginning of the calendar year);
 - if in the Southern Hemisphere, it is after the warmest and before the coldest month of the year (as winter is in the middle of the calendar year).

Nitrogen (N) application is standardized in timing across models. N fertilizer is applied in two doses, as is often the

norm in actual practice, to reduce losses to the environment. In the GGCM Phase 2 protocol, half of the total fertilizer input is applied at sowing and the other half on day 40 after sowing, for all crops except for winter wheat. For winter wheat, in practice the application date for the second N fertilizer application varies according to local temperature, because the length of winter dormancy can vary strongly. In the GGCM Phase 2 protocol, the second fertilization date for winter wheat must lie at least 40 d after planting and – if not contradicting the distance to planting – no later than 50 d before maturity. If those limits permit, the second fertilization is set to the middle day of the first month after sowing that has average temperatures above 8 °C.

All stresses in models are disabled other than those related to nitrogen, temperature, and water. For example, model responses to alkalinity, salinity, and non-nitrogen nutrients are all disabled. No other external N inputs are permitted – that is, there is no atmospheric deposition of nitrogen – but some models allow additional release of plant-available nitrogen through mineralization in soils. In LPJmL, the Lund–Potsdam–Jena General Ecosystem Simulator (LPJ-GUESS), and Agricultural Production Systems sIMulator (APSIM), soil mineralization is a part of model treatments of soil organic matter and cannot be disabled. Some additional differences in model structure mean that several key factors are not standardized across the experiment. For example, carryover effects across growing years including residue management and soil moisture are treated differently across models.

2.4 Output data products

All models in GGCM Phase 2 provide 30-year time series of annual crop yields for each scenario, 0.5° grid cell and crop, in units of $\text{t ha}^{-1} \text{ yr}^{-1}$. They also provide all available variables of the following six: total aboveground biomass yield; the dates of planting, anthesis and maturity; applied irrigation water in irrigated scenarios; and total evapotranspiration. We term these seven variables the “mandatory” outputs, but note that some models do not compute all of them; e.g., CARAIB does not compute the anthesis date. Besides these seven “mandatory” data products (Table 2, bold), the protocol requests any or all of 18 “optional” additional output variables (Table 2, plain text). Participating modeling groups provided between 3 (PEPIC) and 18 (APSIM-UGOE) of these optional variables.

All output data are supplied as NetCDF version 4 files, each containing values for one variable in a 30-year time series associated with a single scenario, for all grid cells. Filenames follow the naming conventions of GGCM Phase 1 (Elliott et al., 2015), which themselves are derived from those of ISIMIP (Frieler et al., 2017). Filenames are specified as [model]_[climate]_hist_fullharm_[variable]_[crop]_[global_annual]_[start-year]_[end-year]_[C]_[T]_[W]_[N]_[A].nc4 Here, [model] is the crop model name; [climate] is the original climate input

dataset (typically AgMERRA); [variable] is the output variable (of those in Table 2); [crop] is the crop abbreviation (“mai” for maize, “ric” for rice, “soy” for soybean, “swt” for spring wheat, and “wht” for winter wheat); and [start-year] and [end-year] specify the first and last years recorded on file. [C], [T], [W], [N], and [A] indicate the CTWN-A settings, each represented with the respective uppercase letter and the number indicating the level (e.g., “C360_T0_W0_N200”; see Table 1). Except for the CTWN-A letters, the entire filename needs to be in small caps. All filenames include the identifiers *global* and *annual* to distinguish them as global, annual model output, following the updated ISIMIP file naming convention (Frieler et al., 2017).

Output data are provided on a regular geographic grid, identical for all models. Grid cell centers span latitudes from -89.75° to 89.75° and longitudes from -179.75° to 179.75° . Missing values where no crop growth has been simulated are distinguished from crop failures: a crop failure is reported as zero yield but non-simulated areas (including ocean grid cells) have yields reported as “missing values” (defined as 1×10^{20} in the NetCDF files). Following NetCDF standards, latitude, longitude, and time are included as separate variables in ascending order, with units “degrees north”, “degrees east”, and “growing seasons since 1 January 1980 00:00:00”.

Following GGCM Phase 1 standards, the first entry in each file describes the first complete cropping cycle simulated from the given climate input time series. In the AgMERRA time series used for GGCM Phase 2, the first year provided is 1980 but the date of the first entry can vary by crop and location. In the Northern Hemisphere, for summer crops like maize (sown in spring 1980 and harvested in fall 1980), the first harvest record would be of 1980, but for winter wheat (sown in fall 1980 and harvested in spring 1981) the first harvest record would be of 1981. Output files report the sequence of growing periods rather than calendar years. While there is generally one sowing event per calendar year (since simulations with harmonized growing seasons do not permit double cropping), in some cases harvest events may skip or repeat within a calendar year. For example, because soybeans in North Carolina are typically harvested well into December, some calendar years may include no harvest (if it is not completed until after 31 December) or two harvests (one in January and one 11 months later in the following December).

3 Models contributing

The 12 models participating in GGCM Phase 2 are listed in Table 3. Models differ substantially in structure and parameterization and can be separated into two broad categories: site-based (field-scale) models and global ecosystem models. The six site-based models are APSIM, pDSSAT, and the EPIC family of models; the six ecosystem models are

Table 2. Output variables, naming convention, and units in the GGCM Phase 2 protocol. Items in bold text are the mandatory minimum requirements (if model capacities allow for these outputs). Other variables are optionally provided depending on availability and participating modeling groups provided between 3 (PEPIC) and 18 (APSIM-UGOE) of these optional variables.

Variable	Variable name	Units
Yield	yield_<crop>	t ha⁻¹ yr⁻¹ (dry matter)
Total above ground biomass yield	biom_<crop>	t ha⁻¹ yr⁻¹ (dry matter)
Actual planting date	plant-day_<crop>	day of year
Anthesis date^b	anth-day_<crop>	days from planting
Maturity date	maty-day_<crop>	days from planting
Applied irrigation water	pirrww_<crop>	mm yr⁻¹
Evapotranspiration (growing season sum)	etransp_<crop>	mm yr⁻¹ (W_{∞} scenarios only)
Transpiration (growing season sum)	transp_<crop>	mm yr ⁻¹
Evaporation (growing season sum)	evap_<crop>	mm yr ⁻¹
Runoff (total growing season sum, subsurface plus surface)	runoff_<crop>	mm yr ⁻¹
Total available soil moisture in root zone ^a	trzpah2o_<crop>	mm yr ⁻¹
Total root biomass	rootm_<crop>	t ha ⁻¹ yr ⁻¹ (dry matter)
Total reactive nitrogen (N_r) uptake (growing season sum)	tnrup_<crop>	kg ha ⁻¹ yr ⁻¹
Total N_r inputs (growing season sum)	tnrin_<crop>	kg ha ⁻¹ yr ⁻¹
Total N_r losses (growing season sum)	tnrloss_<crop>	kg ha ⁻¹ yr ⁻¹
Gross primary production (GPP)	gpp_<crop>	gC m ⁻² yr ⁻¹
Net primary production (NPP)	npp_<crop>	gC m ⁻² yr ⁻¹
CO ₂ response scaler on NPP	co2npp_<crop>	–{0...∞}
Water response scaler on NPP	h2onpp_<crop>	–{0..1}
Temperature response scaler on NPP	tnpp_<crop>	–{0..1}
N_r response scaler on NPP	nrnpp_<crop>	–{0..1}
Other nutrient response scaler on NPP	ornpp_<crop>	–{0..1}
CO ₂ response scaler on transpiration	co2trans_<crop>	–{0..1}
Maximum stress response scaler	maxstress_<crop>	–{0..1}
Maximum leaf area index (LAI)	laimax_<crop>	m ² m ⁻²

^a Growing season sum, basis for computing average soil moisture. ^b Provided where possible.

LPJmL, LPJ-GUESS, PROMET, CARAIB, Organising Carbon and Hydrology In Dynamic Ecosystems (ORCHIDEE), and JULES. Models employ a variety of approaches for the core modules such as primary production or evapotranspiration. For primary production, site-based models employ light use efficiency approaches and ecosystem models use photosynthesis approaches. For evapotranspiration, most models use Priestley–Taylor, Penman–Monteith or Hargreaves schemes, but JULES and PROMET utilize a land surface model approach instead. Note that models that share a common genealogy may still use different schemes for evapotranspiration: for example, EPIC-TAMU uses Penman–Monteith and EPIC-IIASA uses Hargreaves. To describe soils, most models use either the Harmonized World Soil Database (HWSD) from the FAO (FAO/IIASA/ISRIC/ISSCAS/JRC, 2012) or the ISRIC-WISE database (Batjes, 2005) or a derivation thereof. Table S1 in the Supplement provides details on these model characteristics as well as on implementation, including spin-up, calibration other than growing season, residue management, and irrigation rules.

Table 3 also describes the simulation output contribution of each model to the GGCM Phase 2 archive. Not all modeling groups provided simulations for the full protocol described above. Given the substantial computational requirements, different participation tiers were specified to allow submission of smaller subsets of the full protocol. These subsets were designed as alternate samples across the four dimensions of the CTWN space, with *full* (12) and *low* (4) options for the $C \cdot N$ variables, and *full* (63), *reduced* (31), and *minimum* (9) options for $T \cdot W$ variables (described below). All participating modeling groups provided identical coverage of the CTWN parameter space for different crops, but most differed in CTWN coverage of A0 and A1 scenarios. Since the adaptation dimension was defined as a secondary priority for GGCM Phase 2, some models provided a more limited set of A1 scenarios. Of these, EPIC-IIASA, JULES, and ORCHIDEE-crop provided no A1 scenarios.

The different participation levels are defined by combining the $C \cdot N$ sets with the $T \cdot W$ sets:

- **full:** all 756 A0 simulations (all 12 $C \times N^*$ all 63 $T \times W$);

Table 3. Models included in GGCMI Phase 2 and the number of CTWN-A simulations performed. The maximum number is 756 for A0 (no adaptation) experiments, and 648 for A1 (maintaining growing length) experiments, since T0 is not simulated under A1. “N dim” indicates whether the models are able to represent varying nitrogen levels. Each model provides the same set of CTWN simulations across all its modeled crops, but some models omit individual crops. (For example, APSIM-UGOE does not simulate winter wheat.) Bold numbers indicate those models that provided all specified simulations (with or without varying nitrogen).

Model (key citations)	Maize	Soybean	Rice	Winter wheat	Spring wheat	N dim.	Sims per crop (A0/A1)
APSIM-UGOE, Keating et al. (2003), Holzworth et al. (2014)	X	X	X	–	X	X	44/36
CARAIB, Dury et al. (2011), Pirttioja et al. (2015)	X	X	X	X	X	–	252/216
EPIC-IIASA, Balkovič et al. (2014)	X	X	X	X	X	X	39 / 0
EPIC-TAMU, Izaurralde et al. (2006)	X	X	X	X	X	X	756/648
JULES, Osborne et al. (2015), Williams and Falloon (2015), Williams et al. (2017)	X	X	X	–	X	–	252/0
GEPIC, Liu et al. (2007), Folberth et al. (2012)	X	X	X	X	X	X	430/181
LPJ-GUESS, Lindeskog et al. (2013), Olin et al. (2015)	X	–	–	X	X	X	756/648
LPJmL, von Bloh et al. (2018)	X	X	X	X	X	X	756/648
ORCHIDEE-crop, Wu et al. (2016)	X	–	X	X	–	X	33 / 0
pDSSAT, Elliott et al. (2014b), Jones et al. (2003)	X	X	X	X	X	X	756/648
PEPIC, Liu et al. (2016a), Liu et al. (2016b)	X	X	X	X	X	X	149/121
PROMET, Hank et al. (2015), Mauser et al. (2015), Zabel et al. (2019)	X	X	X	X	X	X	261/232
Totals	12	10	11	10	11	10	5240/3378

- **high**: 362 simulations (all 12 $C \times N$ combinations · reduced $T \times W$ set of 31 combinations);
- **mid**: 124 simulations (low 4 $C \times N$ combinations · reduced $T \times W$ set of 31 combinations); and
- **low**: 36 simulations (low 4 $C \times N$ combinations · minimum $T \times W$ set of 9 combinations).

Of the 12 models submitting data, six followed the *full* protocol; these are marked with bold text in the last column of Table 3. However, note that two of these models (CARAIB and JULES) cannot represent nitrogen effects explicitly and so do not sample over the nitrogen dimension. Two models followed *high* with minor modifications (GEPIC adding an additional T level and PROMET omitting the intermediate N level). One model (PEPIC) followed *mid* but included an additional C level. Three models approximately followed *low*

with APSIM-UGOE and EPIC-IIASA providing some additional $T \times W$ levels and ORCHIDEE-crop omitting some $T \times W$ combinations.

The combinations of perturbation values in the $C \times N$ and $T \times W$ parameter spaces used in the various participation levels are chosen to provide maximum coverage over plausible future values. For the $C \times N$ space, we specify

- *full* as 12 pairs, with four C values (360, 510, 660, 810 ppm) and three N values (10, 60, 200 kg ha^{−1} yr^{−1}) and
- *low* as only four pairs: $C_{360_N_{10}}$, $C_{360_N_{200}}$, $C_{660_N_{60}}$, and $C_{810_N_{200}}$.

For the $T \times W$ space, we specify

- *full* as all seven T levels and nine W levels;

- *reduced* as 31 alternating combinations, with different W s for even T s than for odd T s. For even T s (i.e., T_0 , T_2 , T_4 , T_6), we use $W = -50, -20, 0, +30 = 4 \cdot 4 = 16$ pairs. For odd T s (i.e., T_1 , T_3), we use $W = -30, -10, +10, +30, \text{inf} = 3 \cdot 5 = 15$ pairs;
- *minimum* as nine combinations: $T_{-1}W_{-10}$, T_0W_{10} , T_1W_{-30} , T_2W_{-50} , T_2W_{20} , T_3W_{30} , T_4W_0 , T_4W_{inf} , T_6W_{-20} .

4 Results

To illustrate the properties of the GGCM Phase 2 model simulations, we provide an evaluation of model performance by comparing model and historical yields, and show example results that demonstrate the spread of model responses to climate and management inputs.

4.1 Evaluation of model performance

All models participating in GGCM Phase 2 have been evaluated against historical yields and site-specific experimental data. Most models (9 of 12, all but CARAIB, JULES, and PROMET) have been evaluated in their global setup in the GGCM Phase 1 evaluation exercise (Müller et al., 2017), and many have used the GGCM Phase 1 online tool to similarly evaluate subsequent model versions (e.g., von Bloh et al., 2018). Evaluating the performance of crop models in the GGCM Phase 2 archive is complicated by the artificial nature of the protocol: the settings in the CTWN-A experiment design do not reflect actual conditions in the real world. The protocol includes one scenario of near-historical climate inputs (T_0 , W_0 , C_{360}), but the prescribed uniform nitrogen application levels do not reflect real-world fertilizer practices. Models also omit detailed calibrations to reflect the performance of historical cultivars.

We provide a partial evaluation of the models' skill in reproducing crop yield characteristics using the methodology of Müller et al. (2017), developed for GGCM Phase 1. Müller et al. (2017) evaluate how well model crop yield responses in a historical run capture real-world yield variations driven by year-to-year temperature and precipitation variations. Following this approach, we compare yields in the GGCM Phase 2 baseline simulations with detrended historical yields from the Food and Agriculture Organization of the United Nations (FAO, 2018) by calculating the Pearson product moment correlation coefficient over 26 years of yield. The procedure is sensitive to the detrending method and the area mask used to aggregate yields; we use a 5-year running mean removal and the MIRCA2000 cultivation area mask for aggregation. In some cases, the model time series are shifted by 1 year to account for discrepancies in FAO or model year reporting. Because the GGCM Phase 2 protocol imposes fixed, uniform nitrogen application levels that are not realistic for individual countries, we evaluate control

runs for each model at multiple N levels whenever possible. Overall, nine of the GGCM Phase 2 models (Table 3) provide historical runs for all three nitrogen levels (10, 60, and 200 kg ha⁻¹ yr⁻¹).

As expected due to the unrealistic features described above, correlation coefficients for the GGCM Phase 2 simulations are slightly lower than those found in the Phase 1 evaluation, but models show reasonable fidelity at capturing year-to-year variation (Fig. 2). For example, global correlation coefficients in Phase 1 and Phase 2, respectively, are 0.89 and 0.74 for maize, 0.67 and 0.64 for wheat, and 0.64 and 0.59 for soybeans. (Phase 1 values are from Figs. 1–4 and 6 in Müller et al., 2017.) Differences in fidelity between regions and crops exceed differences between models; that is, Fig. 2c–f show more color similarity in horizontal than vertical bars. For example, maize in the United States is consistently well simulated, while maize in Indonesia is problematic (mean Pearson correlation coefficients of 0.68 and 0.18, respectively). Note that in this methodology, simulations of crops with low year-to-year variability such as irrigated rice and wheat will tend to score more poorly than those with higher variability. In some cases, especially in the developing world, low correlation coefficients may point to reporting problems in the FAO statistics and to real-world variability caused by variations in management rather than weather (Ray et al., 2012; Müller et al., 2017). No single model consistently exhibits greater fidelity than others. Instead, each model shows near best-in-class performance for at least one location–crop combination. For example, pDSSAT is the best model for maize in the US, LPJmL and GEPIC are best in Germany, PROMET is best in Argentina, and PEPIC and LPJ-GUESS are best in France.

4.2 Model crop yield responses under CTWN forcing

Crop models in the GGCM Phase 2 ensemble show broadly consistent responses to climate and management perturbations in most regions, with a strong negative impact of increased temperature in all but the coldest regions. Mapping the distribution of baseline yields and yield changes shows the geographic dependencies that underlie these results. Absolute yield potentials show strong spatial variation, with much of the Earth's surface area unsuitable for any of these crops (Fig. 3, left). Crop yield changes under climate perturbations also show distinct geographic patterns (Fig. 3, right, which shows fractional yield differences between the baseline and $T + 4$ A0 scenarios). In general, models agree most on yield response in regions where yield potentials are currently high and therefore where crops are currently grown. In A0 simulations, models show robust decreases in yields at low latitudes, and highly uncertain ensemble mean increases at most high latitudes. Low-latitude yield reductions are due in part to shortening of the growing season under warming and in part to the direct effects of higher temperature. In A1 simulations, where growing seasons length does not change,

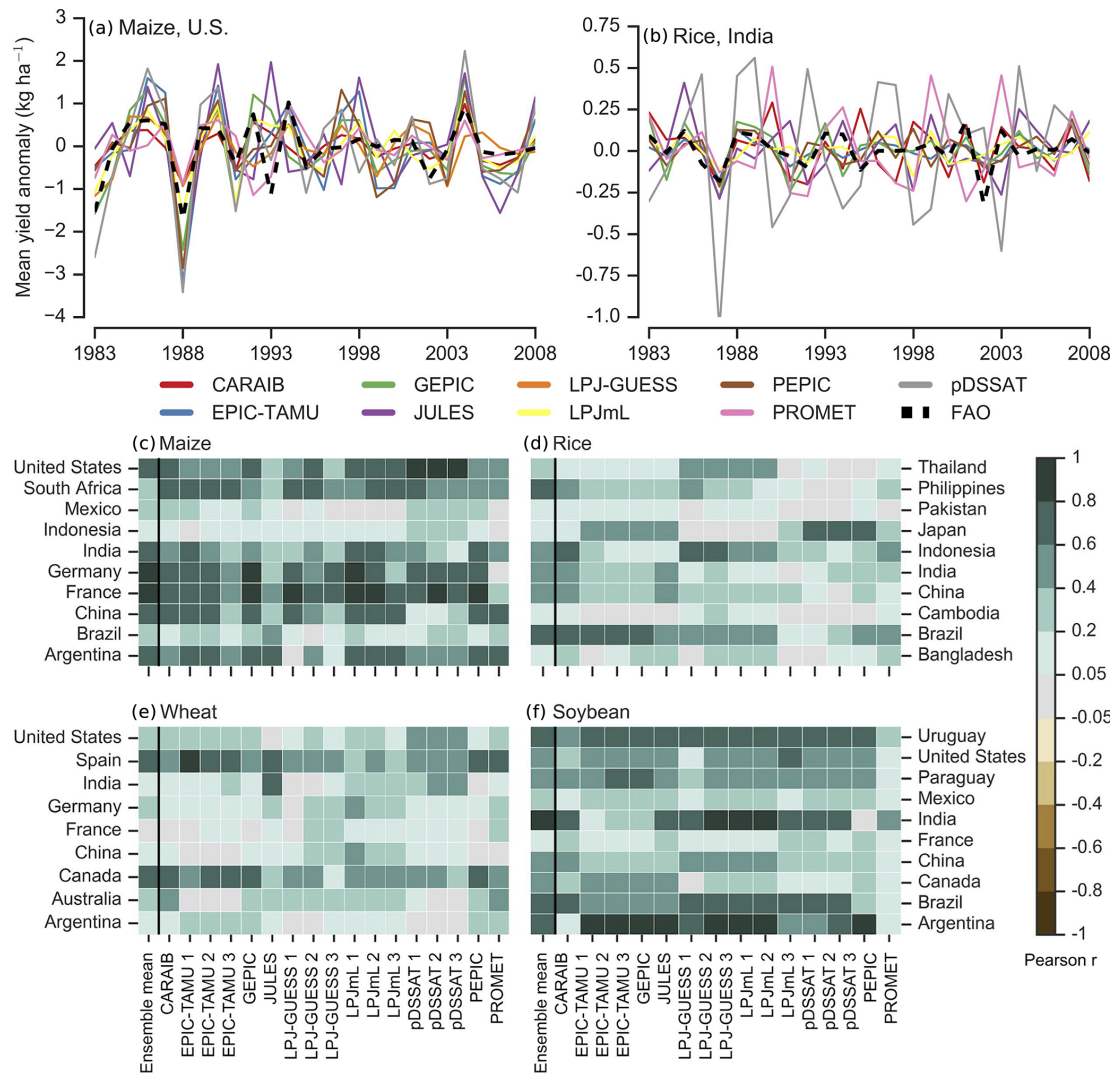


Figure 2. Assessment of crop model performance in GGCMI Phase 2, following the protocol of GGCMI Phase 1 (Müller et al., 2017). **(a, b)** Example time series comparison between simulated crop yield and FAO country statistics (FAO, 2018) at the country level for two example high production countries: US maize and rice in India, both for the 200 kg ha⁻¹ nitrogen application level. **(c–f)** Heatmaps illustrating the Pearson *r* correlation coefficient between the detrended simulated and observed country-level mean yields for the top 10 countries by production for each crop, of those countries with continuous FAO data over 1981–2010. We show separate comparisons for simulations with the three different nitrogen application levels, denoted 1, 2, and 3 for 10, 60, and 200 kg N ha⁻¹, respectively. Panels **(a, c, e)** show correlation of ensemble mean yields with FAO data. Because FAO does not distinguish between wheat types, we sum simulated spring and winter wheat for models that provide both (see Table 3). Note that differences by region and crop are stronger than difference between models; e.g., horizontal bars are more similar in color than vertical bars. Countries are ordered alphabetically, not by production quantity.

temperature-related reductions in yield are more muted (see Fig. S14). In both A0 and A1 simulations, models show some increases in high mountain regions that are currently cold limited.

Projections of strong yield growth at higher latitudes should be treated with caution, since the effects evident in Fig. 3 are due in part to inaccuracies in model representations of present-day crop yields. For example, at latitudes north of 45°, the GGCMI Phase 2 models collectively suggest strong (but uncertain) growth in soybean yields under

warmer conditions (Fig. 3g). However, model differences are greater in the baseline than future simulations and greatest in currently cultivated areas (Fig. 4). Both the mean projected growth and the inter-model spread are driven by three models that show almost zero present-day potential soybean yields across the entire high-latitude region, even in locations where soybeans are currently grown (Fig. 4, left). PROMET, for example, involves a stronger response to cold than other models (e.g., LPJmL) with frost below −8 °C irreversibly killing non-winter crops and prolonged periods of below-

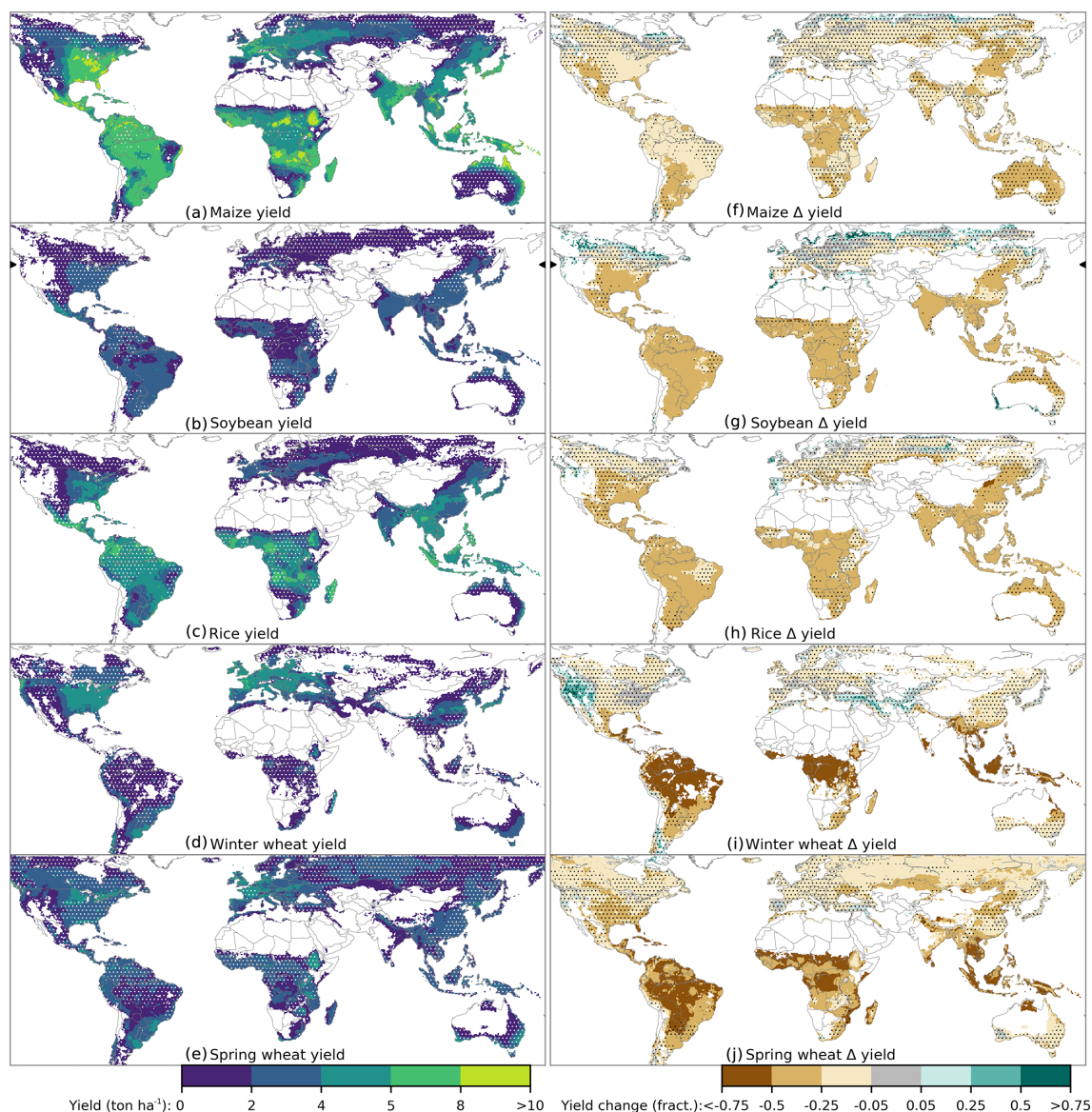


Figure 3. Illustration of the spatial patterns of baseline yields (a–e) and yield changes (f–j) in the GGCM Phase 2 ensemble. The left column shows multi-model climatological (30-year) median yields for the baseline scenario, with white stippling indicating areas where these crops are not currently cultivated. Areas with less than 0.5 t ha^{-1} in the baseline are masked. Absence of cultivation aligns well with the lowest yield contour ($0\text{--}2 \text{ t ha}^{-1}$). The right column shows multi-model mean fractional yield changes in the $T + 4^\circ\text{C}$ scenario relative to the baseline scenario. Areas without stippling are those where models agree on changes: the multi-model mean fractional change exceeds the standard deviation of changes in individual models. Stippling indicates areas of low confidence ($\Delta < 1\sigma$). Some spatial structure in projected changes at high latitudes may be due to differences in model coverage; see Fig. 1.

optimum temperatures also leading to complete crop failure. Over the high-latitude regions simulated by both models, 52 % of grid cells in PROMET report 0 yield in the present climate vs. 11 % of cells in the $T + 4$ scenario, leading to a strong yield gain in warmer future climates. In LPJmL outputs, the same high-latitude area is deemed suitable for cultivation even in baseline climate, with crop failure rates of 4 % and 5 % in present and $T + 4$ cases, so that projected yield changes are modest (Fig. 4). These spurious low base-

line yields result in very large fractional changes in the $T + 4$ warming scenario, when all models agree that conditions become favorable for soybeans. Those models that most accurately reproduce present-day high-latitude soybean yields of $1\text{--}2 \text{ t ha}^{-1}$ (Ray et al., 2012) in fact show a slight decrease in yield under a warming scenario (Fig. 4a). Apparent future yield increases in the multi-model mean are driven by the least realistic simulations.

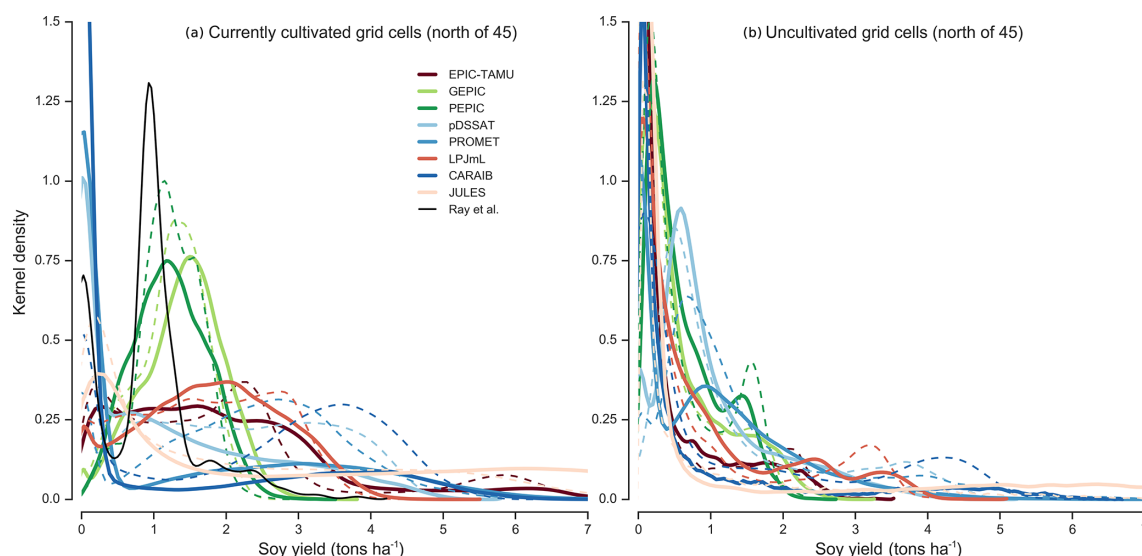


Figure 4. Model probability densities for soybean yields at latitudes north of 45° in historical and warming simulations in the A0 case. While 10 GGCMI Phase 2 models provide simulations (Table 3); we show eight representative models for clarity. Probability density functions are estimated separately for locations with some current cultivation (**a**, approximately 2500 grid cells, unweighted by cultivated area) and for uncultivated locations (**b**, approximately 1500 grid cells), for baseline historical (solid) and $T + 4$ ($^{\circ}\text{C}$) (dashed) simulations. Black line in panel (**a**) shows actual yields from 1997 to 2003 derived from Ray et al. (2012). For historical simulations, models agree on low potential yields in currently uncultivated areas (**b**) but disagree widely on yields in currently cultivated areas (**a**). Color code groups models into those with realistic yield distributions peaking at $1\text{--}2\text{ t ha}^{-1}$ (green), those with flatter distributions extending to unrealistically high values (red), and those with predominantly zero yields (blue). “Green” models show slight decreases under $T + 4$ warming, “red” models moderate increases, and “blue” models large increases.

The GGCMI Phase 2 exercise offers the opportunity to examine and characterize not just crop response to a single temperature change but nonlinearities in responses and interactions between factors. We illustrate a few of these relationships in Figs. 5–6 using A0 simulations to capture maximum climate effects. We choose crops and factors whose effects are reasonably well understood and show that these are reproduced in models. It is expected, for instance, that increases in precipitation should buffer the effects of warmer temperatures and that CO_2 increases should reduce damage to crops in scenarios where water is limited. Models generally confirm expected behavior but also provide insight into unforeseen interactions. To show geographic effects, we divide model responses in Figs. 5–6 by the primary Köppen–Geiger climate regions (Rubel and Kottek, 2010), showing the yield changes across all simulated grid cells in each region. In each panel, we examine relationships between two factors, showing yield response against one for several scenarios of the other, in box plots that show the inter-model spread. The responses highlighted here are qualitatively similar across all crops included in this study (Figs. S5–S9 for all simulated area and S10–S13 for cultivated area only).

For all crops, warming scenarios with precipitation held constant produce yield decreases in most regions. These impacts are robust for even moderate climate perturbations. For rainfed maize, even a 1°C temperature increase with other

factors held constant produces a median regional decline in potential yield that exceeds the variance across models, in all but the “cold-continental” regions (Fig. 5a). The remaining areas (“warm temperate”, “equatorial”, and “arid”) account for nearly three-quarters of global maize production. In the high-latitude “cold-continental” region, potential yield changes are positive but highly uncertain, for the reasons discussed previously; uncertainties are larger even for maize than for soybeans. (Compare Fig. 5a and b.) Temperature effects are somewhat nonlinear, with the largest impacts for maize in the warm “tropical” region (for soybeans, temperature effects are more complex; see Fig. S5). Precipitation effects on rainfed crops are more strongly nonlinear. The curvature of the precipitation response can be seen by eye in Fig. 5b: soybean yields are strongly negatively impacted by reduced rainfall, peak under increased precipitation of 20 %, and actually decline at higher precipitation levels.

As expected, precipitation and temperature effects interact, with increases in precipitation buffering yield responses to temperature. Increased rainfall mitigates the negative impacts of warmer temperatures caused by increased evapotranspiration (e.g., Allen et al., 1998). For maize, the effect is relatively modest outside the “arid” regions (Fig. 5a). Globally, a 4°C temperature rise with no change in precipitation results in median loss of $\sim 13\%$ of rainfed maize, with all models showing a negative response. With a 20 % increase in

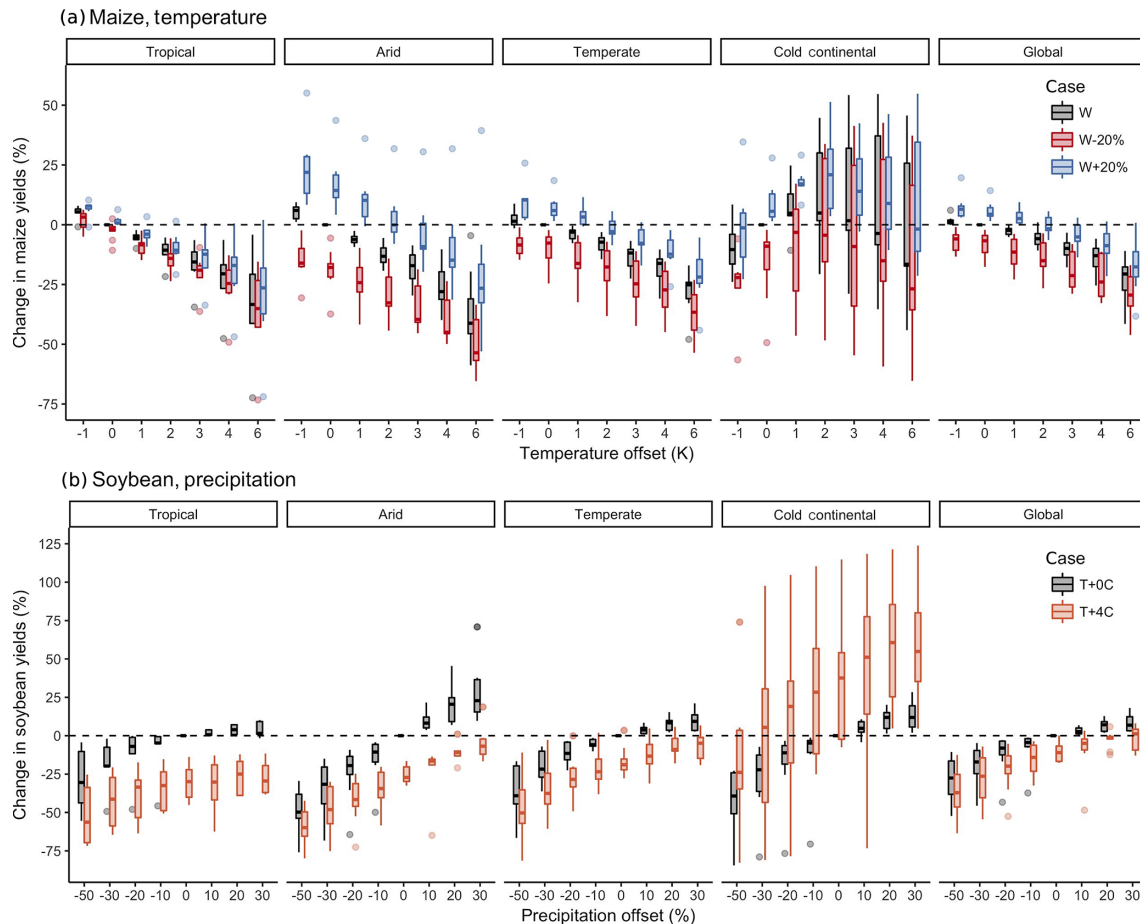


Figure 5. Illustration of the distribution of regional yield changes across the multi-model ensemble, split by Köppen–Geiger climate regions, and with global response in rightmost panel. The y axis is the fractional change in the regional average climatological (30-year mean) potential yield relative to the baseline. Box-and-whisker plots show distribution across models, with median marked; edges are first and third quartiles and whiskers extend to $1.5 \cdot \text{IQR}$. The figure shows all simulated grid cells for each model; see Figs. S10–S13 for only currently cultivated land. We highlight responses to individual factors; note that results are not directly comparable to simulations of realistic projected climate scenarios with identical global mean changes. Models generally agree outside high-latitude regions, with projected changes exceeding inter-model variance. **(a)** Response of rainfed maize to applied uniform temperature perturbations, for three discrete precipitation perturbation levels (-20% , 0% , and $+20\%$), with CO_2 and nitrogen held constant at baseline values (360 ppm and $200 \text{ kg ha}^{-1} \text{ yr}^{-1}$). Outliers in the tropics (strong negative impact of higher T) are the pDSSAT model; outliers in the arid region (strong positive impact of higher P) are JULES. **(b)** Response of rainfed soybeans to applied uniform precipitation perturbations, for two discrete temperature levels. Cases with reduced precipitation show greater inter-model spread than those with increased precipitation. At very large precipitation increases, yield changes level out: benefits saturate once water availability is no longer limiting. Precipitation changes are more important in the arid region, as expected. Note the large uncertainty in the cold continental region, also illustrated in Figs. 3 and 4.

precipitation, the median yield loss is $\sim 8\%$. For soybeans, the equivalent values are $\sim 11\%$ and 1% , respectively. Decreased rainfall, on the other hand, amplifies yield losses and also increases inter-model variance. That is, models agree that the response to decreased water availability is negative in sign but disagree on its magnitude. Outside of arid regions, the interaction effect itself shows little nonlinearity (i.e., response slopes in Fig. 5a and b are roughly parallel). As expected, irrigated crops are more resilient to temperature increases in all regions, especially so where water is already limiting (other than winter wheat; Fig. S9).

Increased CO_2 boosts yields overall through the well-known CO_2 fertilization effect (Fig. 6). The effect is strongest for the C3 crops (wheat, soybeans, and rice), while maize, a C4 grass, has a comparatively muted response. We show irrigated rice and rainfed soy in Fig. 6 as representative C3 crops. The effect of CO_2 on yields is nonlinear, as expected, with significant benefit from small increases but with effects plateauing at higher concentrations (Fig. 6). CO_2 and temperature effects show minimal interaction. This effect is seen in Fig. 6a, which shows nearly parallel response slopes at different CO_2 levels. That is, CO_2 fertilization does little to

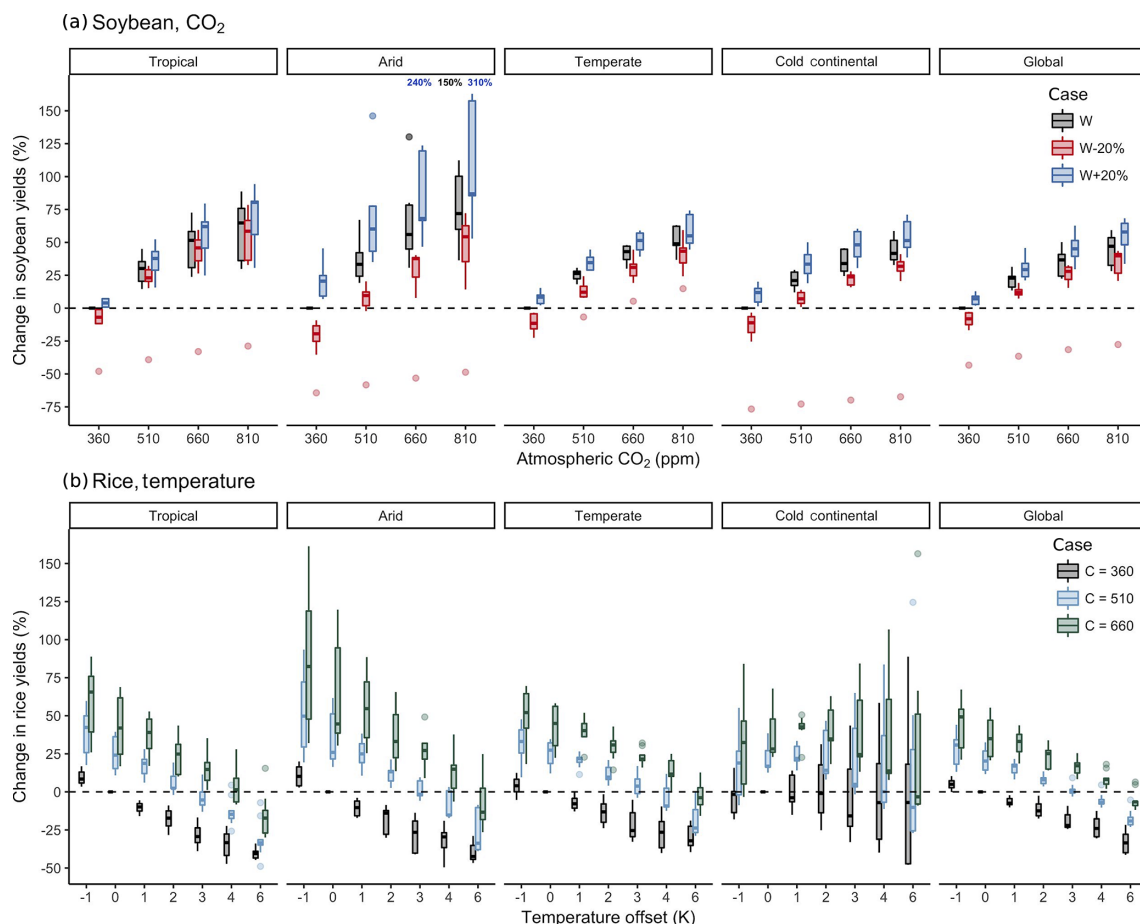


Figure 6. Illustration of the distribution of regional yield changes across the multi-model ensemble, here for soybeans and rice for the A0 case. Conventions are as in Fig. 5. **(a)** Response of rainfed soybeans to atmospheric CO₂, for three discrete precipitation perturbation levels with temperature and nitrogen held constant at baseline values. Low outliers are the EPIC-TAMU model and the high outliers in the arid region are the JULES model. Reduced precipitation tends to steepen the CO₂ response and increased precipitation tends to flatten it, as expected. Reduced precipitation tends to increase the inter model spread, especially at the highest CO₂ levels. **(b)** Response of irrigated rice for three discrete CO₂ levels, with nitrogen and precipitation held constant. CO₂ does not change the nature of temperature response respective to baseline as the slopes at each CO₂ level are relatively constant.

change the nature of the temperature response. On the other hand, CO₂ and precipitation effects interact strongly, as expected since higher CO₂ levels allow reduced stomatal conductance and evapotranspiration losses, mitigating the effect of reduced rainfall (e.g., McGrath and Lobell, 2013). This interaction is seen in Fig. 6b as smaller yield losses from reduced rainfall when CO₂ levels are higher. For example, for soy, raising CO₂ to 510 ppm actually outweighs the multi-model median damages caused by a 20 % precipitation reduction in all climate regions. All crops show similar behavior, but note that model uncertainties for wheat are substantially higher than those for other crops. (Compare Fig. 6a for soy and Fig. S7 for wheat.)

We show some additional cases in the Supplement. As noted previously, the A1 adaptation simulations involve significantly moderated temperature impacts relative to the A0 simulations shown here (Fig. S14). Figures S15 and S16

show the response in the nitrogen dimension and an irrigation water demand response example.

5 Discussion and conclusions

The GGCMI Phase 2 experiment provides a database designed to allow detailed study of crop yields in process-based models under climate change. While previous crop model intercomparison projects in the climate change context have focused on simulations along realistic projected climate scenarios (e.g., Rosenzweig et al., 2014), the use of systematic input parameter variations in GGCMI Phase 2, with up to 756 scenarios, allows not only comparing yield sensitivities to changing climate and management inputs but also evaluating the complex interactions between important driving factors: CO₂, temperature, water supply, and applied nitrogen.

The global extent of the experiment also allows identifying geographic shifts in high potential yield locations. With 12 participating models and 31 simulation years per scenario, the complete database constitutes over 150 000 years of gridded global yield simulation output for each crop.

Preliminary results shown here highlight some of the insights facilitated by the simulation exercise and lend confidence in the models. In validation tests of historical simulations, year-to-year correlations in modeled and actual country-level yields are similar to those of GGCM Phase 1. In simulations of scenarios with perturbed climate and management factors, models broadly agree on changes outside the high latitudes, with the magnitude of changes at nearly all perturbation levels exceeding the inter-model spread. At high latitudes, differences between models may result from differences in their assumed yields in current cold conditions. In simulations with multiple perturbations, interactions between major yield drivers (e.g., temperature and precipitation in Fig. 5, or precipitation and CO₂ in Fig. 6) generally follow expectations and produce physically reasonable responses in crop yields.

Users should however be aware of some limitations of the GGCM Phase 2 experiment that affect its potential applications. First, absolute yield values in the baseline scenario, driven by 1981–2010 historical climate, will generally not match observed yields over this time period. In order to match current yields, process-based models must be re-tuned to account for the constant evolution of crop cultivar genetics and management practice (e.g., Jones et al., 2017). GGCM Phase 2 is intended as a study of model responses to changes in climatic conditions, which are assumed insensitive to the adjustments needed to reproduce present-day yields. The baseline scenario also includes no trend in CO₂, and no individual case involves realistic country-specific nitrogen application levels (Elliott et al., 2015).

The second major caveat is that no individual GGCM Phase 2 simulation is itself a realistic future yield projection. The uniform applied offsets in temperature and precipitation sample over potential changes, and do not individually capture the spatially heterogeneous warming and precipitation changes expected in realistic climate projections. GGCM Phase 2 simulation results can be used for impacts projection but only with the construction of an emulator of crop yield response to climatological changes, which can then be driven by arbitrary climate scenarios. Such emulators are shown to accurately reproduce crop model output under realistic climate projections, even though the GGCM Phase 2 experiment does not sample over potential changes in the higher-order moments in temperature and precipitation distributions (Franke et al., 2020). Note that some factors that may affect future climate-driven yield impacts cannot be captured by the GGCM Phase 2 models in any usage, since models do not include representations of pests, diseases, and weeds. Offline crop model simulations (i.e., with prescribed rather than dynamically simulated atmospheric conditions) can also

not capture any feedbacks on the climate from land use, such as irrigation impacts on humidity (e.g., Decker et al., 2017).

We expect that the GGCM Phase 2 simulations will yield multiple insights in future studies. Potential applications include, as mentioned, the construction of emulators and yield response surfaces that can be used for both model diagnosis and impacts assessment. Specific studies could include analyzing the drivers of temperature-related yield losses (which may be due to both direct thermal effects or to shortening growing seasons); the benefits of adaptation; interactions between CO₂ and water or other CTWN factors affecting yield; changes in nitrogen use efficiency; geographic shifts in regional production; and regional differences in yield sensitivities to CTWN-A factors. Emulators based on the dataset can be used to identify hotspots of crop system vulnerability and to conduct rapid assessment of new climate projections. In general, the development of multi-model ensembles involving systematic parameter sweeps has large promise both for increasing understanding of potential future crop responses and for improving process-based crop models.

Code and data availability. All input data are available via zenodo at <https://doi.org/10.5281/zenodo.3773827> (Müller et al., 2020). For the minimum cropland mask, choose the `boolean_cropmask_ggcmi_phase2.nc4` file. Growing period data for wheat are now divided up into winter and spring wheat, whereas all other growing season data (maize, rice, soybean) are the same as in Phase 1.

Supplement. The supplement related to this article is available online at: <https://doi.org/10.5194/gmd-13-2315-2020-supplement>.

Author contributions. JE, CM, and ACR designed the research. CM, JJ, JB, PC, MD, PF, CF, LF, MH, RCI, IJ, CJ, NK, MK, WL, SO, MP, TAMP, AR, XW, KW, and FZ performed the simulations. JF, JJ, CM, and EM performed the analysis, and JF, EM, and CM prepared the manuscript. All authors contributed to editing the manuscript.

Competing interests. The authors declare that they have no conflict of interest.

Acknowledgements. This research was performed as part of the Center for Robust Decision-making on Climate and Energy Policy (RDCEP) at the University of Chicago. This is paper number 35 of the Birmingham Institute of Forest Research. Computing resources were provided by the University of Chicago Research Computing Center (RCC). We thank two anonymous reviewers for their helpful comments.

Table 4. DOIs for model data outputs. All model output data can be found at <https://doi.org/10.5281/zenodo/XX>, where XX is the value listed in the table.

Model	Maize	Soybean	Rice	Winter wheat	Spring wheat
APSIM-UGOE	2582531	2582535	2582533	2582537	2582539
CARAIB	2582522	2582508	2582504	2582516	2582499
EPIC-IIASA	2582453	2582461	2582457	2582463	2582465
EPIC-TAMU	2582349	2582367	2582352	2582392	2582418
JULES	2582543	2582547	2582545	–	2582551
GEPIC	2582247	2582258	2582251	2582260	2582263
LPJ-GUESS	2581625	–	–	2581638	2581640
LPJmL	2581356	2581498	2581436	2581565	2581606
ORCHIDEE-crop	2582441	–	2582445	2582449	–
pDSSAT	2582111	2582147	2582127	2582163	2582178
PEPIC	2582341	2582433	2582343	2582439	2582455
PROMET	2582467	2582488	2582479	2582490	2582492

Financial support. RDCEP is funded by NSF (grant no. SES-1463644) through the Decision Making Under Uncertainty program. James Franke was supported by the NSF NRT program (grant no. DGE-1735359) and the NSF Graduate Research Fellowship Program (grant no. DGE-1746045). Christoph Müller was supported by the MACMIT project (grant no. 01LN1317A) funded through the German Federal Ministry of Education and Research (BMBF). Alex C. Ruane was supported by NASA NNX16AK38G (INCA) and the NASA Earth Sciences Directorate/GISS Climate Impacts Group. Christian Folberth was supported by the European Research Council Synergy (grant no. ERC-2013-SynG-610028) Imbalance-P. Pete Falloon and Karina Williams were supported by the Newton Fund through the Met Office program Climate Science for Service Partnership Brazil (CSSP Brazil). Karina Williams was supported by the IMPREX research project supported by the European Commission under the Horizon 2020 Framework program (grant no. 641811). Stefan Olin acknowledges support from the Swedish strong research areas BECC and MERGE, together with support from LUCCI (Lund University Centre for studies of Carbon Cycle and Climate Interactions). R. Cesar Izaurralde acknowledges support from the Texas Agrilife Research and Extension, Texas A & M University.

Review statement. This paper was edited by David Lawrence and reviewed by two anonymous referees.

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