

A New Connection Between Node and Edge Depth Robust Graphs

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Abstract

Given a directed acyclic graph (DAG) $G=(V,E)$, we say that G is (e,d) -depth-robust (resp. (e,d) -edge-depth-robust) if for any set $S\subseteq V$ (resp. $S\subseteq E$) of at most $|S|\leq e$ nodes (resp. edges) the graph $G-S$ contains a directed path of length d . While edge-depth-robust graphs are potentially easier to construct, many applications in cryptography require node depth-robust graphs with small indegree. We create a graph reduction that transforms an (e,d) -edge-depth-robust graph with m edges into a $(e/2,d)$ -depth-robust graph with $O(m)$ nodes and constant indegree. One immediate consequence of this result is the first construction of a provably $(\frac{n\log\log n}{\log n}, \frac{n}{\log n(\log n)^{\log\log n}})$ -depth-robust graph with constant indegree. Our reduction crucially relies on ST-robust graphs, a new graph property we introduce which may be of independent interest. We say that a directed, acyclic graph with n inputs and n outputs is (k_1,k_2) -ST-robust if we can remove any k_1 nodes and there exists a subgraph containing at least k_2 inputs and k_2 outputs such that each of the k_2 inputs is connected to all of the k_2 outputs. If the graph is $(k_1,n-k_1)$ -ST-robust for all $k_1\leq n$ we say that the graph is maximally ST-robust. We show how to construct maximally ST-robust graphs with constant indegree and $O(n)$ nodes. Given a family \mathbb{M} of ST-robust graphs and an arbitrary (e,d) -edge-depth-robust graph G we construct a new constant-indegree graph $\text{Reduce}(G,\mathbb{M})$ by replacing each node in G with an ST-robust graph from \mathbb{M} . We also show that ST-robust graphs can be used to construct (tight) proofs-of-space and (asymptotically) improved wide-block labeling functions.

1 Introduction

Given a directed acyclic graph (DAG) $G=(V,E)$, we say that G is (e,d) -reducible (resp. (e,d) -edge reducible) if there is a subset $S\subseteq V$ (resp. $S\subseteq E$) of $|S|\leq e$ nodes (resp. edges) such that $G-S$ does not contain a directed path of length d . If a graph is not (e,d) -reducible (resp. (e,d) -edge reducible) we say that the

graph is (e,d) -depth robust (resp. (e,d) -edge-depth-robust). Depth robust graphs have found many applications in the field of cryptography in the construction of proofs of sequential work [MMV13], proofs of space [DFKP15, Pie19], and in the construction of data independent memory hard functions (iMHFs). For example, highly depth robust graphs are known to be necessary [AB16] and sufficient [ABP17] to construct iMHFs with high amortized space time complexity. While edge depth-robust graphs are often easier to construct [Sch83], most applications require node depth-robust graphs with small indegree.

It has been shown [Val77] that in any DAG with m edges and n nodes, there exists a set S_i of $\frac{mi}{\log n}$ edges that will force $\text{depth}(G - S_i) \leq \frac{n}{2^i}$ for all $i < \log n$. For DAGs with constant indegree we have $m = O(n)$ edges so an equivalent condition holds for node depth robustness [AB16], since a node can be removed by removing all the edges incident to it. In particular, there exists a set S_i of $O(\frac{mi}{\log n})$ nodes such that $\text{depth}(G - S_i) \leq \frac{n}{2^i}$ for all $i < \log n$. It is known how to construct a $(c_1 n / \log n, c_2 n)$ -depth-robust graph, for suitable $c_1, c_2 > 0$ [ABP17] and a $(c_3 n, c_4 n^{1-\epsilon})$ -depth-robust graph for small ϵ for [Sch83].

An open challenge is to construct constant indegree $(c_1 ni / \log n, c_2 n / 2^i)$ -depth-robust graphs which match the Valiant bound [Val77] for intermediate values of $i = \omega(1)$ and $i = o(\log n)$. For example, when $i = \log \log n$ then the Valiant bound [Val77] does not rule out the existence of $(c_1 ni / \log n, c_2 n / \log n)$ -depth-robust graphs with constant indegree. Such a graph would yield asymptotically stronger iMHFs [BHK⁺19]. While there are several constructions that are conjectured to be $(c_1 ni / \log n, c_2 n / \log n)$ -depth-robust the best provable lower bound for $(e = cni / \log n, d)$ -depth robustness of a constant indegree graph is $d = \Omega(n^{1-\epsilon})$. For edge-depth robustness we have constructions of graphs with $m = O(n \log n)$ edges which are (e_i, d_i) -edge depth robust for any i with $e_i = mi / \log n$ and $d_i = n / \log^{i+1} n$ — much closer to matching the Valiant bound [Val77].

1.1 Contributions

Our main contribution is a graph reduction that transforms any (e,d) -edge-depth-robust graph with m edges into an $(e/2,d)$ -depth-robust graph with $O(m)$ nodes and constant indegree. Our reduction utilizes ST-robust graphs, a new graph property we introduce and construct. We believe that ST-robust graphs may be of independent interest.

Intuitively, a (k_1, k_2) -ST-robust graph with n inputs I and n outputs O satisfies the property that, even after deleting k_1 nodes from the graph we can find k_2 inputs x_1, \dots, x_{k_2} and k_2 outputs y_1, \dots, y_{k_2} such that *every* input x_i ($i \in [k_2]$) is still connected to *every* output y_j ($j \in [k_2]$). If we can guarantee that the each directed path from x_i to y_j has length d then we say that the graph is (k_1, k_2, d) -ST-Robust.

A maximally depth-robust graph should be $(k_1, n-k_1)$ -depth robust for any k_1 .

Definition 1.1. ST-Robust Let $G=(V,E)$ be a DAG with n inputs, denoted by set I and n outputs, denoted by set O . Then G is (k_1, k_2) -ST-robust if $\forall D \subset V(G)$ with $|D| \leq k_1$, there exists subgraph H of $G-D$ with $|I \cap V(H)| \geq k_2$ and $|O \cap V(H)| \geq k_2$ such that $\forall s \in I \cap V(H)$ and $\forall t \in O \cap V(H)$ there exists a path from s to t in H . If $\forall s \in I \cap V(H)$ and $\forall t \in O \cap V(H)$ there exists a path from s to t of length $\geq d$ then we say that G is (k_1, k_2, d) -ST-robust.

Definition 1.2. Maximally ST-Robust Let $G=(V,E)$ be a constant indegree DAG with n inputs and n outputs. Then G is c_1 -maximally ST-robust (resp. c_1 max ST-robust with depth d) if there exists a constant $0 < c_1 \leq 1$ such that G is $(k, n-k)$ -ST-robust (resp. $(k, n-k, d)$ -ST-robust) for all k with $0 \leq k \leq c_1 n$. If $c_1 = 1$, we just say that G is maximally ST-robust.

We show how to construct maximally ST-robust graphs with constant indegree and $O(n)$ nodes and we show how maximally ST-robust graphs can be used to transform any (e, d) -edge-depth-robust graph G with m edges into a $(e/2, d)$ -depth-robust graph G' with $O(m)$ nodes and constant indegree. Intuitively, in our reduction each node $v \in V(G)$ with degree δ is replaced with a maximally ST-robust graph M_v with δ inputs/outputs. Incoming edges into v are redirected into the inputs I_v of the ST-robust graph. Similarly, v 's outgoing edges are redirected out of the outputs O_v of the ST-robust graph. Because the graph is maximally ST-robust removing k nodes from M_v corresponds to destroying at most $2k$ edges in the original graph G .

Our reduction gives us a fundamentally new way to design node-depth-robust graphs: design an edge-depth-robust graph (easier) and then reduce it to a node-depth-robust graph. The reduction can be used with a construction from [Sch83] to construct a $(\frac{n \log \log n}{\log n}, \frac{n}{\log n (\log n)^{\log \log n}})$ -depth-robust graph. We conjecture that several prior DAG constructions (e.g, [EGS75, Sch83, ABP18]) are actually $(n \log \log n, \frac{n}{\log n})$ -edge-depth-robust. If any of these conjectures are true then our reduction would immediately yield the desired $(\frac{n \log \log n}{\log n}, \frac{n}{\log n})$ -depth-robust graph.

We also present several other applications for maximally ST-robust graphs including the construction of (tight) proofs-of-space and wide block-labeling functions.

2 Edge to Node Depth-Robustness

In this section, we assume the existence of linear sized, constant indegree, maximally ST-robust graphs and use this assumption to construct a transformation of

an (e,d) -edge-depth robust graph with m edges into an (e,d) -node-depth robust graph with constant indegree and $O(m)$ nodes. In the next section we will construct a family of ST-robust graphs that satisfies assumption 2.1.

Assumption 2.1. There is a family of graphs $\mathbb{M} = \{M_n\}_{n=1}^{\infty}$ with the property that for each $n \geq 1$, M_n has constant indegree, $O(n)$ nodes, and is maximally ST-robust.

2.1 Reduction Definition

Let $G = (V, E)$ be a DAG, and let \mathbb{M} be as in Assumption 2.1. Then we define $\text{Reduce}(G, \mathbb{M})$ in construction 2.2 as follows:

Construction 2.2 (Reduce(G, \mathbb{M})). Let $G = (V, E)$ and let \mathbb{M} be the family of graphs defined above. For each $M_n \in \mathbb{M}$, we say that $M_n = (V(M_n), E(M_n))$, with $V(M_n) = I(M_n) \cup O(M_n) \cup D(M_n)$, where $I(M_n)$ are the inputs of M_n , $O(M_n)$ are the outputs, and $D(M_n)$ are the internal vertices. For $v \in V$, let $\delta(v) = \max\{\text{indeg}(v), \text{outdeg}(v)\}$. Then we define $\text{Reduce}(G) = (V_R, E_R)$, where $V_R = \{(v, w) \mid v \in V, w \in V_{\delta(v)}\}$ and $E_R = E_{\text{internal}} \cup E_{\text{external}}$. We let $E_{\text{internal}} = \{((v, u_{\delta(v)}), (v, w_{\delta(v)})) \mid v \in V, (u_{\delta(v)}, w_{\delta(v)}) \in E(H_{\delta(v)})\}$. Then for each $v \in V$, we define an $\text{In}(v) = \{u : (u, v) \in E\}$ and $\text{Out}(v) = \{u : (v, u) \in E\}$ and then pick two injective mappings $\pi_{\text{in}, v} : \text{In}(v) \rightarrow I(V_{\delta(v)})$ and $\pi_{\text{out}, v} : \text{Out}(v) \rightarrow O(V_{\delta(v)})$. We let $E_{\text{external}} = \{((u, \pi_{\text{out}, u}(v)), (v, \pi_{\text{in}, v}(u))) : (u, v) \in E\}$.

Intuitively, to construct $\text{Reduce}(G, \mathbb{M})$ we replace every node of G with a constant indegree, maximally ST-robust graph, mapping the edges connecting two nodes from the outputs of one ST-robust graph to the inputs of another. Then for every $e = (u, w) \in E$, add an edge from an output of $M_{\delta(u)}$ to an input of $M_{\delta(w)}$ such that the outputs of $M_{\delta(u)}$ have outdegree at most 1, and the inputs of $M_{\delta(w)}$ have indegree at most 1. If $v \in V$ is replaced by $M_{\delta(v)}$, then we call v the *genesis node* and $M_{\delta(v)}$ its *metanode*.

2.2 Proof of Main Theorem

We now state the main result of this section which says that if G is edge-depth robust then $\text{Reduce}(G, \mathbb{M})$ is node depth-robust.

Theorem 2.3. *Let G be an (e, d) -edge-depth-robust DAG with m edges. Let \mathbb{M} be a family of max ST-Robust graphs with constant indegree. Then $G' = (V', E') = \text{Reduce}(G, \mathbb{M})$ is $(e/2, d)$ -depth robust. Furthermore, G' has maximum indegree $\max_{v \in V(G)} \{\text{indeg}(M_{\delta(v)})\}$, and its number of nodes is $\sum_{v \in V(G)} |M_{\delta(v)}|$ where $\delta(v) = \max\{\text{indeg}(v), \text{outdeg}(v)\}$.*

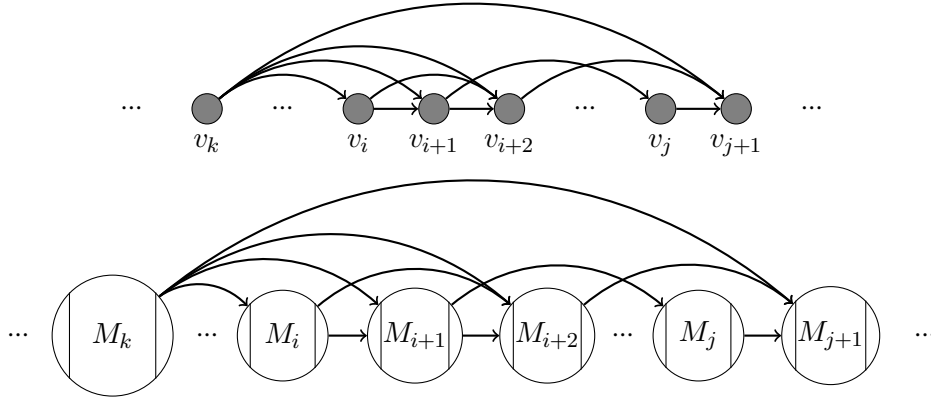


Figure 1: Diagram of the transformation $\text{Reduce}(G, \mathbb{M})$

A formal proof can be found in Appendix B. We briefly outline the intuition for this proof below.

Proof. (Intuition) The first thing we note is that each graph $M_{\delta(v)}$ has constant indegree at most $c\delta(v)$ nodes for some constant $c > 0$. Therefore, the graph G' has $\sum_{v \in V(G)} |M_{\delta(v)}| \leq c \sum_v \delta(v) \leq 2cm$ nodes and G' has constant indegree.

Now for any set $S \subseteq V'$ of nodes we remove from G' we will map S to a corresponding set $S_{irr} \subseteq E$ of at most $|S_{irr}| \leq 2|S|$ irreparable edges in G . We then prove that any path P in $G - S_{irr}$ corresponds to a longer path P' in $G' - S$ that is at least as long. Intuitively, each incoming edge (u, v) (resp. outgoing edge (v, w)) in $E(G)$ corresponds to an input node (resp. output node) in v 's corresponding metanode $M_{\delta(v)}$ which we will label $x_{u,v}$ (resp. $y_{v,w}$). If $S \subseteq V'$ removes at most k nodes from the metanode $M_{\delta(v)}$ then, by maximal ST-robustness, we still can find $\delta(v) - k$ inputs and $\delta(v) - k$ outputs that are all pairwise connected. If $x_{u,v}$ (resp. $y_{v,w}$) is not part of this pairwise connected subgraph then we will add the corresponding edge (u, v) (resp. (v, w)) to the set S_{irr} . Thus, the set S_{irr} will have size at most $2|S|$ Claim B.2 in the appendix).

Intuitively, any path P in $G - S_{irr}$ can be mapped to a longer path P' in $G' - S$ (Claim B.1). If P contains the edges $(u, v), (v, w)$ then we know that the input node $x_{u,v}$ and output node $y_{v,w}$ node in $M_{\delta(v)}$ are still connected in $G' - S$. \square

Corollary 2.4. (of Theorem 2.3) *If there exists some constants c_1, c_2 , such that we have a family $\mathbb{M} = \{M_n\}_{n=1}^{\infty}$ of linear sized $|V(M_n)| \leq c_1 n$, constant indegree $\text{indeg}(M_n) \leq c_2$, and maximally ST-robust graphs, then $\text{Reduce}(G, \mathbb{M})$ has maximum indegree c_2 and the number of nodes is at most $2c_1 m$.*

The next corollary states that if we have a family of maximally ST-robust graphs with $\mathbb{M} = \{M_k\}_{k=1}^\infty$ and depth d_k then we can transform any (e, d) -edge-depth-robust DAG $G = (V, E)$ with maximum degree $\delta = \max_{v \in V} \delta(v)$ into $(e/2, d \cdot d_\delta)$ -depth robust graph. Instead of replacing each node $v \in G$ with a copy of $M_{\delta(v)}$, we instead replace each node with a copy of $M_{\delta, v} := M_\delta$, attaching the edges same way as in Construction 2.2. Thus the transformed graph G' has $|V(G)| \times |M_\delta|$ nodes and constant indegree. Intuitively, any path P of length d in $G - S_{irr}$ now maps to a path P' of length $d \times d_\delta$ — if P contains the edges $(u, v), (v, w)$ then we know that the input node $x_{u, v}$ and output node $y_{u, v}$ node in $M_{\delta, v}$ are connected in $G' - S$ by a path of length at least d_δ .

Corollary 2.5. *(of Theorem 2.3) Suppose that there exists a family $\mathbb{M} = \{M_k\}_{k=1}^\infty$ of max ST-robust graphs with depth d_k and constant indegree. Given any (e, d) -edge-depth-robust DAG G with n nodes and maximum degree δ we can construct a DAG G' with $n \times |M_\delta|$ nodes and constant indegree that is $(e/2, d \cdot d_\delta)$ -depth robust.*

Proof. (sketch) Instead of replacing each node $v \in G$ with a copy of $M_{\delta(v)}$, we instead replace each node with a copy of $M_{\delta, v} := M_\delta$, attaching the edges same way as in Construction 2.2. Thus the transformed graph G' has $|V(G)| \times |M_\delta|$ nodes and constant indegree. Let $S \subset V(G')$ be a set of nodes that we will remove from G' . By Claim B.1, there exists a path P in $G' - S$ that passes through d metanodes $M_{\delta, v_1}, \dots, M_{\delta, v_d}$. Since M_δ is maximally ST-robust with depth d_δ the sub-path $P_i = P \cap M_{\delta, v_i}$ through each metanode has length $|P_i| \geq d_\delta$. Thus, the total length of the path is at least $\sum_i |P_i| \geq d \cdot d_\delta$. \square

Corollary 2.6. *(of Theorem 2.3) Let $\epsilon > 0$ be any fixed constant. Given any family $\{G_m\}_{m=1}^\infty$ of (e_m, d_m) -edge-depth-robust DAGs G_m with m nodes and maximum indegree δ_m then for some constants $c_1, c_2 > 0$ we can construct a family $\{H_m\}_{m=1}^\infty$ of DAGs such that each DAG H_m is $(e_m/2, d_m \cdot \delta_m^{1-\epsilon})$ -depth robust, H_m has maximum indegree at most c_2 (constant) and at most $|V(H_m)| \leq c_1 m \delta_m$ nodes.*

Proof. (sketch) This follows immediately from Corollary 2.5 and from our construction of a family $\mathbb{M}_\epsilon = \{M_{k, \epsilon}\}_{k=1}^\infty$ of max ST-robust graphs with depth $d_k > k^{1-\epsilon}$ and constant indegree. \square

Corollary 2.7. *(of Theorem 2.3) Let $\{e_m\}_{m=1}^\infty$ and $\{d_m\}_{m=1}^\infty$ be any sequence. If there exists a family $\{G_m\}_{m=1}^\infty$ of (e_m, d_m) -edge-depth-robust graphs, where each DAG G_m has m edges, then there is a corresponding family $\{H_n\}_{n=1}^\infty$ of constant indegree DAGs such that each H_n has n nodes and is $(\Omega(e_n), \Omega(d_n))$ -depth-robust.*

The original Grate’s construction [Sch83], G , has $N=2^n$ nodes and $m=n2^n$ edges and for any $s \leq n$, and is $(s2^n, \frac{N}{\sum_{j=0}^s \binom{n}{j}})$ -edge-depth-robust. For node depth-robustness we only had matching constructions when $s=O(1)$ [ABP17, ABH17] and $s = \Omega(\log N)$ [Sch83] — no comparable lower bounds were known for intermediate s .

Corollary 2.8. *(of Theorem 2.3) There is a family of constant indegree graphs $\{G_n\}$ such that G_n has $O(N=2^n)$ nodes and G_n is $(sN/(2n), \frac{N}{\sum_{j=0}^s \binom{n}{j}})$ -edge-depth-robust for any $1 \leq s \leq \log n$*

In particular, setting $s=\log \log n$ and applying the indegree reduction from Theorem 2.3, we see that the transformed graph G' has constant indegree, $N' = O(n2^n)$ nodes, and is $(\frac{N' \log \log N'}{\log N'}, \frac{N'}{\log N' (\log N')^{\log \log N'}})$ -depth-robust. Blocki et al. [BHK⁺19] showed that if there exists a node depth robust graph with $e = \Omega(N \log \log N / \log N)$ and $d = \Omega(N \log \log N / \log N)$ then one can obtain another constant indegree graph with pebbling cost $\Omega(N^2 \log \log N / \log N)$ which is optimal for constant indegree graphs. We conjecture that the graphs in [EGS75] are sufficiently edge depth robust to meet these bounds after being transformed by our reduction.

3 ST Robustness

In this section we show how to construct maximally ST-robust graphs with constant indegree and linear size. We first introduce some of the technical building blocks used in our construction including superconcentrators [Val76, Pip77, GG81] and grates [Sch83]. Using these building blocks we then provide a randomized construction of a c_1 -maximally ST-robust DAG with linear size and constant indegree for some constant $c_1 > 0$ — sampled graphs are c_1 -maximally ST-robust DAG with high probability. Finally, we use c_1 -maximally ST-robust DAGs to construct a family of maximally ST-robust graphs with linear size and constant indegree.

3.1 Technical Ingredients

We now introduce other graph properties that will be useful for constructing ST-robust graphs.

Grates A DAG $G = (V, E)$ with n inputs I and n outputs O is called a (c_0, c_1) -grate if for any subset $S \subset V$ of size $|S| \leq c_0 n$ at least $c_1 n^2$ input output pairs $(x, y) \in I \times O$ remain connected by a directed path from x to y in $G - S$. Schmitger [Sch83] showed how to construct (c_0, c_1) -grates with $O(n)$ nodes and

constant indegree for suitable constants $c_0, c_1 > 0$. The notion of an maximally ST-robust graph is a strictly stronger requirement since there is no requirement on which pairs are connected. However, we show that a slight modification of Schnitger’s [Sch83] construction is a $(cn, n/2)$ -ST-robust for a suitable constant c . We then transform this graph into a c_1 -maximally ST-robust graph by sandwiching it in between two superconcentrators. Finally, we show how to use several c_1 -maximally ST-robust graphs to construct a maximally ST-robust graph.

Superconcentrators We say that a directed acyclic graph $G = (V, E)$ with n input vertices and n output vertices is an **n -superconcentrator** if for any r inputs and any r outputs, $1 \leq r \leq n$, there are r vertex-disjoint paths in G connecting the set of these r inputs to these r outputs. We note that there exists linear size, constant indegree superconcentrators [Val76, Pip77, GG81] and we use this fact throughout the rest of the paper. For example, Pippenger [Pip77] constructed an n -superconcentrator with at most $41n$ vertices and indegree at most 16.

Connectors We say that an n -superconcentrator is an **n -connector** if it is possible to specify which input is to be connected to which output by vertex disjoint paths in the subsets of r inputs and r outputs. Connectors and superconcentrators are potential candidates for ST-robust graphs because of their highly connective properties. In fact, we can prove that any connectors **n -connector** is maximally ST-robust — the proof of Theorem 3.1 can be found in the appendix. While we have constructions of **n -connector** graphs these graphs have $O(n \log n)$ vertices and indegree of 2, an information theoretic technique of Shannon [Sha50] can be used to prove that any n -connector with constant indegree requires *at least* $\Omega(n \log n)$ vertices — see discussion in the appendix. Thus, we cannot use n -connectors to build linear sized ST-robust graphs. However, Shannon’s information theoretic argument does not rule out the existence of linear size ST-robust graphs.

Theorem 3.1. *If G is an n -connector, then G is $(k, n - k)$ -ST-robust, for all $1 \leq k \leq n$.*

3.2 Linear Size ST-robust Graphs

ST-robust graphs have similar connective properties to connectors, so a natural question to ask is whether ST-robust graphs with constant indegree require $\Omega(n \log n)$ vertices. In this section, we show that linear size ST-robust graphs exist by showing that a modified version of the Grates construction [Sch83] becomes c -maximally ST-robust when sandwiched between two superconcentrators for some constant c .

In the proof of Theorem A in [Sch83], Schnitger constructs a family of DAGs $(H_n | n \in \mathbb{N})$ with constant indegree δ_H , where n is the number of nodes and H_n is $(cn, n^{2/3})$ -depth-robust, for suitable constant $c > 0$. We construct a similar graph G_n as follows:

Construction 3.2 (G_n). We begin with H_n^1 , H_n^2 and H_n^3 , three isomorphic copies of H_n with disjoint vertex sets V_1 , V_2 and V_3 . For each top vertex $v \in V_3$ sample τ vertices x_1^v, \dots, x_τ^v independently and uniformly at random from V_2 and for each $i \leq \tau$ add each directed edge (x_i^v, v) to G_n to connect each of these sampled nodes to v . Similarly, for each node vertex $u \in V_2$ sample τ vertices x_1^u, \dots, x_τ^u from V_1 independently and uniformly at random and add each directed edge (x_i^u, u) to G_n . Note that $\text{indeg}(G_n) \leq \text{indeg}(H_n) + \tau$.

Schnitger's construction only utilizes two isomorphic copies of H_n and the edges connecting H_n^1 and H_n^2 are sampled by picking τ random permutations. In our case the analysis is greatly simplified by picking the edges uniformly and we will need three layers to prove ST-robustness. We will use the following lemma from the Grates paper as a building block. A proof of Lemma 3.3 is included in the appendix for completeness.

Lemma 3.3. [Sch83] *For some suitable constant $c > 0$ any subset S of $cn/2$ vertices of G_n the graph $H_n^1 - S$ contains $k = cn^{1/3}/2$ vertex disjoint paths A_1, \dots, A_k of length $n^{2/3}$ and $H_n^2 - S$ contains k vertex disjoint paths B_1, \dots, B_k of the same length.*

We use Lemma 3.3 to help establish our main technical Lemma 3.4. We sketch the proof of Lemma 3.4 below. A formal proof can be found in Appendix B.

Lemma 3.4. *Let G_n be defined as in Construction 3.2. Then for some constants $c > 0$, with high probability G_n has the property that for all $S \subset V(G_n)$ with $|S| = cn/2$ there exists $A \subseteq V(H_n^1)$ and $B \subseteq V(H_n^3)$ such that for every pair of nodes $u \in A$ and $v \in B$ the graph $G_n - S$ contains a path from u to v and $|A|, |B| \geq 9cn/40$.*

Proof. (Sketch) Fixing any S we can apply Lemma 3.3 to find $k := cn^{1/3}/2$ vertex disjoint paths $P_{1,S}^i, \dots, P_{k,S}^i$ in H_n^i of length $n^{2/3}$ for each $i \leq 3$. Here, c is the constant from Lemma 3.3. Let $U_{j,S}^i$ be the upper half of the j -th path in H_n^i and $L_{j,S}^i$ be the lower half and define the event $BAD_{i,S}^{upper}$ to be the event that there exists at least $k/10$ indices $j \leq k$ s.t., $U_{j,S}^2$ is disconnected from $L_{i,S}^3$. We construct B by taking the union of all of upper paths $U_{i,S}^3$ in H_n^3 for each non-bad (upper) indices i . Similarly, we define $BAD_{i,S}^{lower}$ to be the event that there exists at least $k/10$ indices $j \leq k$ s.t. $U_{i,S}^1$ is disconnected from $L_{j,S}^2$ and we construct A

be taking the union of all of the lower paths $L_{i,S}^1$ in H_n^1 for each non-bad (lower) indices i . We can now argue that any pair of nodes $u \in A$ and $v \in B$ is connected by invoking the pigeonhole principle i.e., if $u \in L_{i,S}^1$ and $v \in U_{i',S}^3$ for good indices i and i' then there exists some path P_j^2 in the middle layer H_n^2 which can be used to connect u to v . We still need to argue that $|A|, |B| \geq cn/3$ for some constant c . To lower bound $|B|$ we introduce the event $BAD_S = |\{i : BAD_{i,S}^{upper}\}| > \frac{k}{10}$ and note that unless BAD_S occurs we have $|B| \geq (9k/10)n^{2/3}/2 = 9cn/40$. Finally, we show that $\mathbb{P}[BAD_S]$ is very small and then use union bounds to show that, for a suitable constant τ , the probability $\mathbb{P}[\exists SBAD_S]$ becomes negligibly small. A symmetric argument can be used to show that $|A| \geq 9cn/40$. \square

We now use G_n to construct c -maximally ST-robust graphs with linear size.

Construction 3.5 (M_n). We construct the family of graphs M_n as follows: Let the graphs SC_n^1 and SC_n^2 be linear sized n -superconcentrators with constant indegree δ_{SC} [Pip77], and let H_n^1, H_n^2 and H_n^3 be defined and connected as in G_n , where every output of SC_n^1 is connected to a node in H_n^1 , every node of H_n^3 is connected to an input of SC_n^2 .

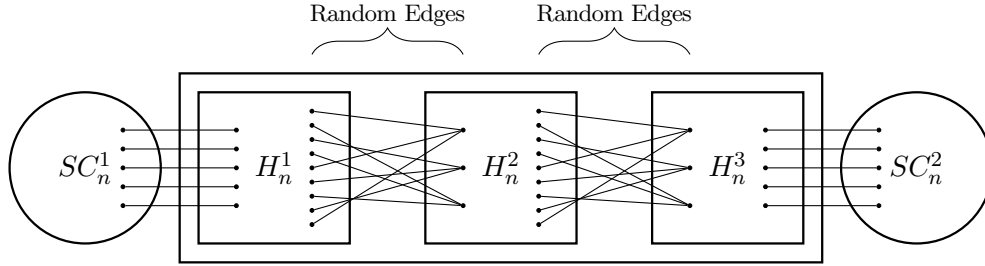


Figure 2: A diagram of the constant indegree, linear sized, ST-robust graph M_n .

Theorem 3.6. *There exists a constant $c' > 0$ such that for all sets $S \subset V(M_n)$ with $|S| \leq c'n/2$, M_n is $(|S|, n - |S|)$ -ST-robust, with n inputs and n outputs and constant indegree.*

Proof. Let $c' = 9c/40$, where c is the constant from G_n . Consider $M_n - S$. Then because $|S \cap (H_n^1 \cup H_n^2)| \leq |S| \leq c'n/2 \leq cn/2$, by Lemma 3.4 with a high probability there exists sets A in H_n^1 and B in H_n^3 with $|A|, |B| \geq \frac{9}{10}k \frac{n^{2/3}}{2} = \frac{9}{40}cn = c'n$, such that every node in A connects to every node in B . By the properties of superconcentrators, the size of the set BAD_1 of inputs u in SC_n^1 that can't reach *any* node in A in $M_n - S$. We claim that $|BAD_1| \leq |S| \leq c'n$. Assume for contradiction that

$|BAD_1| > |S|$ then SC_n^1 contains at least $\min\{|BAD_1|, |A|\} > |S|$ node disjoint paths between BAD_1 and A . At least one of these node disjoint paths does not intersect S which contradicts the definition of BAD_1 . Similarly, we can bound the size of BAD_2 , the set of outputs in SC^n which are not reachable from any node in B . Given any input $u \notin BAD_1$ of SC_n^1 and any output $v \notin BAD_2$ of SC_n^2 we can argue that u is connected to v in $M_n - S$ since we can reach some node $x \in A$ from u and v can be reached from some node $y \in B$ and *any* such pair x, y is connected by a path in $M_n - S$. It follows that M_n is $(|S|, n - |S|)$ -ST-robust. \square

Corollary 3.7. (of Theorem 3.6) *For all $\epsilon > 0$, there exists a family of DAGs $\mathbb{M} = \{M_n^\epsilon\}_{n=1}^\infty$, where each M_n^ϵ is a c -maximally ST-robust graphs with $|V(M_n)| \leq c_\epsilon n$, $\text{indegree}(M_n) \leq c_\epsilon$, and depth $d = n^{1-\epsilon}$.*

Proof. (sketch) In the proof of Lemma 3.3, we used $(cn, n^{2/3})$ -depth robust graphs. When considering the paths A_i and B_j , we were considering connecting the upper half of one path to the lower half of another. Thus, after we remove nodes from M_n , there exists a path of length at least $n^{2/3}$ that connects any remaining input to any remaining output. Thus M_n is c -maximally ST-robust with depth $d = n^{2/3}$. In [Sch83], Schmitger provides a construction that is $(cn, n^{1-\epsilon})$ -depth robust for all constant $\epsilon > 0$. By the same arguments we used in this section, we can construct c -maximally ST-robust graphs with depth $d = n^{1-\epsilon}$, where the constant c depends on ϵ . \square

3.3 Constructing Maximal ST-Robust Graphs

In this section, we construct maximal ST-robust graphs, which are 1-maximally ST-robust, from c -maximally ST-robust graphs. We give the following construction:

Construction 3.8 ($\mathbb{O}(M_n)$). Let M_n be a c -maximally ST-robust graph on $O(n)$ nodes. Let O be a set o_1, o_2, \dots, o_n of n output nodes and let I be a set i_1, i_2, \dots, i_n of n input nodes. Let S_j for $1 \leq j \leq \lceil \frac{1}{c} \rceil$ be a copy of M_n with outputs $\sigma_1^j, \sigma_2^j, \dots, \sigma_n^j$ and inputs $i_1^j, i_2^j, \dots, i_n^j$. Then for all $1 \leq j \leq n$ and for all $1 \leq k \leq n$, add a directed edge from i_k to i_k^j and from σ_k^j to o_k .

Because we connect $\lceil \frac{1}{c} \rceil$ copies of M_n to the output nodes, $\mathbb{O}(M_n)$ has indegree $\max\{\delta, \lceil \frac{1}{c} \rceil\}$, where δ is the indegree of M_n . Also, if M_n has kn nodes, then $\mathbb{O}(M_n)$ has $(k \lceil \frac{1}{c} \rceil + 2)n$ nodes. We now show that $\mathbb{O}(M_n)$ is a maximal ST-robust graph.

Theorem 3.9. *Let M_n be a c -maximally ST-robust graph. Then $\mathbb{O}(M_n)$ is a maximal ST-robust graph.*

Proof. Let $R \subset V(\mathbb{O}(M_n))$ with $|R|=k$. Let $R = R_I \cup R_M \cup R_O$, where $R_I = R \cap I$, $R_O = R \cap O$, and $R_M = R \cap \left(\bigcup_{i=1}^{\lceil 1/c \rceil} S_i\right)$. Consider $\mathbb{O}(M_n) - R$. We see that $|R_M| \leq k$, so by the Pidgeonhole Principal at least one S_j has less than cn nodes removed, say it has t nodes removed for $t \leq cn$. Hence $t \leq |R_M|$. Since S_j is c -max ST-robust there exists a subgraph H of $S_j - R$ containing $n-t$ inputs and $n-t$ outputs such that every input is connected to all of the outputs. Let H' be the subgraph induced by the nodes in $V(H) \cup I' \cup O'$, where $I' = \{(i_a, i_a^b) | i_a^b \in H\}$ and $O' = \{(o_a^b, o_a) | o_a^b \in H\}$.

Claim 3.10. The graph H' contains at least $n-k$ inputs and $n-k$ outputs and there is a path between every pair of input and output nodes.

Proof. The set $|I \setminus I'| \leq |I \cap R| + |V(S_j) \cap R| \leq |R| \leq k$. Similarly, $|O \setminus O'| \leq |O \cap R| + |V(S_j) \cap R| \leq |R| \leq k$. Let $v \in I'$ be some input. By the connectivity of H , v can reach all of the outputs in O' . Thus there is a path between every pair of input and output nodes. \square

Thus $\mathbb{O}(M_n)$ is $(k, n-k)$ -ST-robust for all $1 \leq k \leq n$. Therefore $\mathbb{O}(M_n)$ is a maximal ST-robust graph. \square

Corollary 3.11. (of Theorem 3.9) For all $\epsilon > 0$, there exists a family $\mathbb{M}^\epsilon = \{M_k^\epsilon\}_{k=1}^\infty$ of max ST-robust graphs of depth $d = n^{1-\epsilon}$ such that $|V(M_k^\epsilon)| \leq c_\epsilon n$ and $\text{indegree}(M_k^\epsilon) \leq c_\epsilon$.

Proof. Apply Construction 3.8 to the family graphs $\mathbb{M}^\epsilon = \{M_k^\epsilon\}_{k=1}^\infty$ from Corollary 3.7. Then by Theorem 3.9, the family of graphs $\{\mathbb{O}(M_k^\epsilon)\}_{k=1}^\infty$ is the desired family. \square

4 Applications of ST-Robust Graphs

As outlined previously maximally ST-Robust graphs give us a tight connection between edge-depth robustness and node-depth robustness. Because edge-depth-robust graphs are often easier to design than node-depth robust graphs [Sch83] this gives us a fundamentally new approach to construct node-depth-robust graphs. Beyond this exciting connection we can also use ST-robust graphs to construct perfectly tight proofs of space [Pie19, Fis19] and asymptotically superior wide-block labeling functions [CT19].

4.1 Tight Proofs of Space

In Proof of Space constructions [Pie19] we want to find a DAG $G=(V,E)$ with small indegree along with a challenge set $V_C \subseteq V$. Intuitively, the prover will label the graph G using a hash function H (often modeled as a random oracle in security proofs) such that a node v with parents v_1, \dots, v_δ is assigned the label $L_v = H(L_{v_1}, \dots, L_{v_\delta})$. The prover commits to storing L_v for each node v in the challenge set V_C . The pair (G, V_C) is said to be (s, t, ϵ) -hard if for any subset $S \subseteq V$ of size $|S| \leq s$ at least $(1-\epsilon)$ fraction of the nodes in V_C have depth $\geq t$ in $G-S$ — a node v has depth $\geq t$ in $G-S$ if there is a path of length $\geq t$ ending at node v . Intuitively, this means that if a cheating prover only stores $s \leq |V_C|$ labels and is challenged to reproduce a random label L_v with $v \in V_C$ that, except with probability ϵ , the prover will need at least t sequential computations to recover L_v — as long as t is sufficiently large the verifier the cheating prover will be caught as he will not be able to recover the label L_v in a timely fashion. Pietrzak argued that (s, t, ϵ) -hard graphs translate to secure Proofs of Space in the parallel random oracle model [Pie19].

We want G to have small indegree $\delta(G)$ (preferably constant) as the prover will need $O(N\delta(G))$ steps. Additionally, we want $|V_C| = \Omega(N)$ and ϵ to be small while s, t should be larger. Pietrzak [Pie19] proposed to let G_ϵ be an ϵ -extreme depth-robust graph with $N' = 4N$ nodes and to let $V_C = [3N+1, 4N]$ be the last N nodes in this graph. An ϵ -extreme depth-robust graph with N' nodes is (e, d) -depth robust for any $e+d \leq (1-\epsilon)N'$. Such a graph is $(s, N, s/N+4\epsilon)$ -hard for any $s \leq N$. Alwen et al. [ABP18] constructed ϵ -extreme depth-robust graphs with indegree $\delta(G) = O(\log N)$ though the hidden constants seem to be quite large. Thus, it would take time $O(N \log N)$ for the prover to label the graph G . We remark that $\epsilon = s/|V_C|$ is the tightest possible bound one can hope for as the prover can always store s labels from the set V_C .

We remark that if we take V_C to be any subset of output nodes from a maximally ST-robust graph and overlay an $(e = s, d = t)$ -depth robust graph over the input nodes, then the resulting graph will be $(s, t, \epsilon = s/|V_C|)$ -hard — optimally tight in ϵ . In particular, given a DAG $G=(V=[N], E)$ with N nodes define the overlay graph H_G by starting with a maximally ST-robust graph with $|V|$ inputs $I = \{x_1, \dots, x_{|V|}\}$ and $|V|$ outputs O then for every directed edge $(u, v) \in E(G)$ we add the directed edge (x_u, x_v) to $E(H_G)$ and we specify a target set $V_C \subseteq O$. Fisch [Fis19] gave a practical construction of (G, V_C) with indegree $O(\log N)$ that is $(s, N, \epsilon = s/N + \epsilon')$ -hard. The constant ϵ' can be arbitrarily small though the number of nodes in the graph scales with $O(N \log 1/\epsilon')$. Utilizing ST-robust graphs we fix $\epsilon' = 0$ without increasing the size of the graph¹.

¹As a disclaimer we are not claiming that our construction would be more efficient than

Theorem 4.1. *If G is (e,d) -depth robust then the pair (H_G, V_C) specified above is $(s, t=d+1, s/|V_C|)$ -hard for any $s \leq e$.*

Proof. Let S be a subset of $|S| \leq s$ nodes in H_G . By maximal ST-robustness we can find a set A of $N - |S|$ inputs and B of $N - |S|$ outputs such that every pair of nodes $u \in A$ and $v \in B$ are connected in $H_G - S$. We also note since A contains all but s nodes from G that some node $u \in A$ is the endpoint of a path of length t by (s,t) -depth-robustness of G . Since u is connected to *every* node in B this means that every node $v \in B$ is the endpoint of a path of length *at least* $t+1$. \square

This result immediately leads to a $(s, N^{1-\epsilon}, s/N)$ -hard pair for any $s \leq N$ which the prover can label in $O(N)$ time as the DAG G has constant indegree. We expect that in many settings $t = N^{1-\epsilon}$ would be sufficiently large to ensure that a cheating prover is caught with probability s/N after each challenge i.e., if the verifier expects a response within 3 seconds, but it would take longer to evaluate the hash function H a total of $N^{1-\epsilon}$ sequential times.

Corollary 4.2. *For any constant $\epsilon > 0$ there is a constant indegree DAG G with $O(N)$ nodes along with a target set $V_C \subseteq V(G)$ of N nodes such that the pair (G, V_C) is $(s, t = N^{1-\epsilon}, s/N)$ -hard for any $s \leq N$.*

Proof. (sketch) Let G be an $(N, N^{1-\epsilon})$ -depth robust graph with $N' = O(N)$ nodes and constant indegree from [Sch83]. We can then take V_C to be any subset of N output nodes in the graph H_G and apply Theorem 4.1. \square

If one does not want to relax the requirement that $t = \Omega(N)$ then we can provide a perfectly tight construction with $O(N \log N)$ nodes and constant indegree. Since the graph has constant indegree it will take $O(N \log N)$ work for the prover to label the graph. This is equivalent to [Pie19], but with perfect tightness $\epsilon = s/N$.

Corollary 4.3. *For any constant $\epsilon > 0$ there is a constant indegree DAG G with $N' = O(N \log N)$ nodes along with a target set $V_C \subseteq V(G)$ of N nodes such that the pair (G, V_C) is $(s, t, s/N)$ -hard for any $s \leq N$.*

Proof. (sketch) Let G be an $(N, N \log N)$ -depth robust graph with $N' = O(N \log N)$ nodes and constant indegree from [ABH17]. We can then take V_C to be any subset of N output nodes in the graph H_G and apply Theorem 4.1. \square

Finally, if we want to ensure that the graph only has $O(N)$ nodes and $t = \Omega(N)$ we can obtain a perfectly tight construction with indegree $\delta(G) = O(\log N)$.

[Fis19] for practical parameter settings.

Corollary 4.4. *For any constant $\epsilon > 0$ there is a DAG G with $O(N)$ nodes and indegree $\delta(G) = O(\log N)$ along with a target set $V_C \subseteq V(G)$ of N nodes such that the pair (G, V_C) is $(s, N, s/N)$ -hard for any $s \leq N$.*

Proof. (sketch) Let G be an (N, N) -depth robust graph with $N' = 3N$ nodes from [ABP18]. We can then take V_C to be any subset of N output nodes in the graph H_G and apply Theorem 4.1. \square

4.2 Wide-Block Labeling Functions

Chen and Tessaro [CT19] introduced source-to-sink depth robust graphs as a generic way of obtaining a wide-block labeling function $H_{\delta, W} : \{0, 1\}^{\delta W} \rightarrow \{0, 1\}^W$ from a small-block function $H_{fix} : \{0, 1\}^{2L} \rightarrow \{0, 1\}^L$ (modeled as an ideal primitive). In their proposed approach one transforms a graph G with indegree δ and into a new graph G' by replacing every node with a source-to-sink depth-robust graph. Labeling a graph G with a wide-block labeling function is now equivalent to labeling G' with the original labeling function H_{fix} . The formal definition of Source-to-Sink-Depth-Robustness is presented below:

Definition 4.5 (Source-to-Sink-Depth-Robustness (SSDR) [CT19]). A DAG $G = (V, E)$ is (e, d) -source-to-sink-depth-robust (SSDR) if and only if for any $S \subset V$ where $|S| \leq e$, $G - S$ has a path (with length at least d) that starts from a source node of G and ends up in a sink node of G .

If G is (e, d) -depth robust and G' is constructed by replacing every node v in G with a (e^*, d^*) -source-to-sink-depth-robust (SSDR) and orienting incoming (resp. outgoing) edges into the sources (resp. out of the sinks) then the graph G' is (ee^*, dd^*) -depth robust [CT19] and has cumulative pebbling complexity at least $ed(e^*d^*)$ [ABP17]. The SSDR graphs constructed in [CT19] are $(\frac{K}{4}, \frac{\delta K^2}{2})$ -SSDR with $O(\delta K^2)$ vertices and constant indegree. They fix $K := W/L$ as the ratio between the length of outputs for $H_{\delta, W} : \{0, 1\}^{\delta W} \rightarrow \{0, 1\}^W$ and the ideal primitive H_{fix} . Their graph has δK source nodes for a tunable parameter $\delta \in \mathbb{N}$, $O(\delta K^2)$ vertices and constant indegree. Ideally, since we are increasing the number of nodes by a factor of δK^2 we would like to see the cumulative pebbling complexity increase by a quadratic factor of $\delta^2 K^4$. Instead, if we start with an (e, d) -depth robust graph with cumulative pebbling complexity $O(ed)$ their final graph G' has cumulative pebbling complexity $ed \times \frac{\delta K^3}{8}$. Chen and Tessaro left the problem of finding improved source-to-sink depth-robust graphs as an open research question.

Our construction of ST-robust graphs can asymptotically² improve some of

²While we improve the asymptotic performance we do not claim to be more efficient for practical values of δ, K .

their constructions, specifically their constructions of source-to-sink-depth-robust graphs and wide-block labeling functions.

Theorem 4.6. *Let G be a maximal ST-robust graph with depth d and n inputs and outputs. Then G is an $(n-1, d)$ -SSDR graph.*

Proof. By the maximal ST-robustness property, $n-1$ arbitrary nodes can be removed from G and there will still exist at least one input node that is connected to at least one output node. Since G has depth d , the path between the input node and output node must have length at least d . \square

By applying Theorem 4.6 to the construction in Corollary 3.9, we can construct a family of $(\delta K, (\delta K)^{1-\epsilon})$ -SSDR graphs with $O(\delta K)$ nodes and constant indegree and δK sources. In this case the cumulative pebbling complexity of our construction would be already be $ed \times \delta^2 K^{2-\epsilon}$ which is much closer to the quadratic scaling that we would ideally like to see. We are off by just K^ϵ for a constant $\epsilon > 0$ that can be arbitrarily small. To make the comparison easier we could also applying Theorem 4.6 to obtain a family of $(\delta K^2, (\delta K^2)^{1-\epsilon})$ -SSDR graphs with $O(\delta K^2)$ -nodes and constant indegree. While the size of the SSSDR matches [CT19] our new graph is $(e\delta K^2, d(\delta K^2)^{1-\epsilon})$ -depth robust and has cumulative pebbling complexity $ed \times \delta^{2-\epsilon} K^{4-2\epsilon} \gg ed\delta K^3$.

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Appendix

A Connector Graphs

We say that a directed acyclic graph $G = (V, E)$ with n input vertices and n output vertices is an **n -connector** if for any *ordered list* x_1, \dots, x_r of r inputs and any *ordered list* y_1, \dots, y_r of r outputs, $1 \leq r \leq n$, there are r vertex-disjoint paths in G connecting input node x_i to output node y_i for each $i \leq r$.

A.1 Connector Graphs are ST-Robust

We remarked in the paper that any **n -connector** is maximally ST-robust.

Reminder of Theorem 3.1. *If G is an n -connector, then G is $(k, n - k)$ -*

ST-robust, for all $1 \leq k \leq n$. Proof of Theorem 3.1. Let $D \subseteq V(G)$ with $|D| = k$. Consider $G - D$. Let $A = \{(s_1, t_1), \dots, (s_m, t_m)\}$, where the input $s_i \in S$ is disconnected from the output $t_i \in T$ in $G - D$, or $s_i \in D$ or $t_i \in D$. Let $B = \emptyset$.

Perform the following procedure on A and B : Pick any pair $(s_p, t_p) \in A$ and add s_p and t_p to B . Then remove the pair from A along with any other pair in A that shares either s_p or t_p . Continue until A is empty.

If we consider the nodes of B in G , then there are $|B|$ vertex-disjoint paths between the pairs in B by the connector property, and in $G - D$ at least one vertex is removed from each path. Thus $|B| \leq k$, or we have a contradiction.

If $(s, t) \in G - (D \cup B)$ are an input to output pair, and s is disconnected from t , then by the definition of A and B we would have a contradiction, since

(s,t) would still be in A . Thus all of the remaining inputs in $G - (D \cup B)$ are connected to all the remaining outputs.

Hence, if we let $H = G - (D \cup B)$, then H is a subgraph of G with at least $n - k$ inputs and $n - k$ outputs, and there is a path going from each input of H to each of its outputs. Therefore, G is $(k, n - k)$ -ST-robust for all $1 \leq k \leq n$. \square

Butterfly Graphs A well known family of constant indegree n -connectors, for $n = 2^k$, are the k -dimensional butterfly graphs B_k , which are formed by connecting two FFT graphs on n inputs back to back. See Figure A.1 for an example. By Theorem 3.1, the butterfly graph is also a maximally ST-robust graph. However, the butterfly graph has $\Omega(n \log n)$ nodes and does not yield a ST-robust graph of linear size. Since B_k has $O(n \log n)$ vertices and indegree of 2, a natural question to ask is if there exists n -connectors with $O(n)$ vertices and constant indegree.

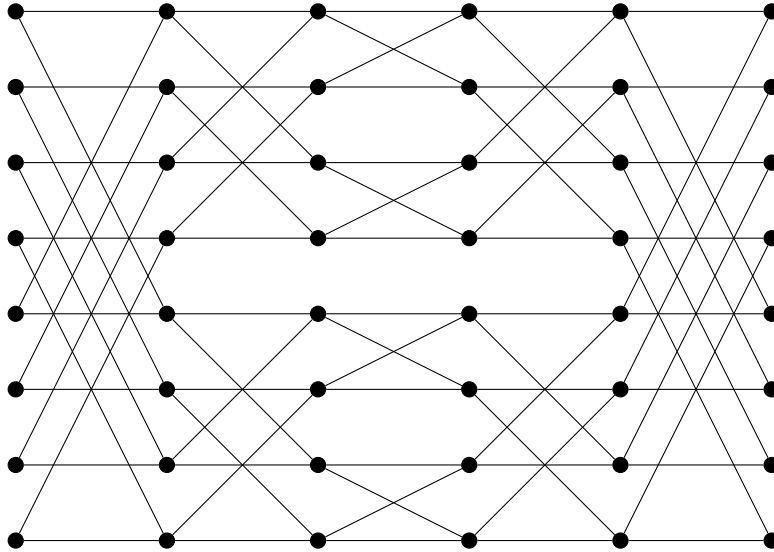


Figure 3: The butterfly graph B_3 is both an 8-superconcentrator and an 8-connector. All edges are directed from left to right.

A.2 Connector Graphs Have $\Omega(n \log n)$ vertices

An information theoretic argument of Shannon [Sha50] rules out the possibility of linear size n -connectors.

Theorem A.1. (Shannon [Sha50]) *An n -connector with constant indegree requires at least $\Omega(n \log n)$ vertices.*

Intuitively, given a n -connector with constant indegree with constant indegree and m edges Shannon argued that we can use the n -connector to encode any permutation of $[n]$ using m bits. In more detail fixing any permutation π we can find n node disjoint paths from input i to output $\pi(i)$. Because the paths are node disjoint we can encode π simply by specifying the subset S_π of directed edges which appear in one of these node disjoint paths. We require at most m bits to encode S_π and from S_π we can reconstruct the set of node-disjoint paths and recover π . Thus, we must have $m = \Theta(n \log n)$ since we require $\log n! = \Theta(n \log n)$ bits to encode a permutation.

We stress that this information theoretic argument breaks down if the graph G is only ST-robust. We are guaranteed that G contains a path from input i to output $\pi(i)$, but we are not guaranteed that all of the paths are node disjoint. Thus, S_π is insufficient to reconstruct π .

B Missing Proofs

Reminder of Theorem 2.3. *Let G be an (e, d) -edge-depth-robust DAG with m edges. Let \mathbb{M} be a family of max ST-Robust graphs with constant indegree. Then $G' = (V', E') = \text{Reduce}(G, \mathbb{M})$ is $(e/2, d)$ -depth robust. Furthermore, G' has maximum indegree $\max_{v \in V(G)} \{\text{indeg}(M_{\delta(v)})\}$, and its number of nodes is $\sum_{v \in V(G)} |M_{\delta(v)}|$ where $\delta(v) = \max\{\text{indeg}(v), \text{outdeg}(v)\}$.*

Proof of Theorem 2.3.

We know that each graph in \mathbb{M} has constant indegree, and that each node v in G will be replaced with a graph in \mathbb{M} with indegree $\text{indeg}(M_{\delta(v)})$. Thus G' has maximum indegree $\max_{v \in V(G)} \{\text{indeg}(M_{\delta(v)})\}$. Furthermore, the metanode corresponding to the node v has size $|M_{\delta(v)}|$. Thus G' has $\sum_{v \in V(G)} |M_{\delta(v)}|$ nodes.

Let $S \subset V(G')$ be a set of nodes that we will remove from G' . For a specific node $v \in V(G)$ we let $S_v = S \cap (\{v\} \times V_{\delta(v)})$ denote the subset of nodes deleted from the corresponding metanode. We say that the node $v \in V(G)$ is *irreparable* with respect to S if $|S_v| \geq \delta(v)$; otherwise we say that v is *reparable*. If a node v is *reparable*, then because the metanodes are maximally ST-Robust we can find subsets $I_{v,S}$ and $O_{v,S}$ (with $|I_{v,S}|, |O_{v,S}| \geq \delta(v) - |S_v|$) such that each input node $s \in I_{v,S}$ is connected to every output node in $O_{v,S}$.

We say that an edge $(u, v) \in E(G)$ is *irreparable* with respect if u or v is *irreparable*, or if the corresponding edge $e' = (u', v') \in E(G')$ has $u' \notin O_{u,S}$ or $v' \notin I_{v,S}$. We let $S_{irr} \subset E(G)$ be the set of irreparable edges after we remove S from G . We begin the proof by first proving two claims.

Claim B.1. Let P be a path of length d in $G - S_{irr}$. Then there exists a path of length *at least* d in $G' - S$.

Proof. In $G - S_{irr}$ we have removed all of the irreparable edges, so any path in the graph contains only repairable edges. By definition, if (u, v) is a repairable edge, both u and v will be repairable, and $(u, \pi_{out, u}(v)) \in O_{u, S}$ and $(v, \pi_{in, v}(u)) \in I_{v, S}$. Thus the edge corresponding to (u, v) in $G' - S$ will connect the metanodes of u and v , and $(u, \pi_{out, u}(v))$ connects to every node in $I_{u, S}$ and $(v, \pi_{out, v}(u))$ connects to every node in $O_{v, S}$. Thus the edges in $G' - S$ corresponding to the edges in P form a path of length at least d . \square

Claim B.2. Let $S_{irr} \subset E(G)$ be the set of irreparable edges with respect to the removed set S . Then

$$|S_{irr}| \leq 2|S|.$$

Proof. If a node v is repairable with respect to S then let $S_{irr, v}^{in} \subseteq E(G)$ (resp. $S_{irr, v}^{out}$) denote the subset of edges $(u, v) \in E(G)$ (resp. $(v, u) \in E(G)$) that are irreparable because of S_v i.e., the corresponding edge $e' = (u', v') \in E(G')$ has $v' \notin I_{v, S}$ (resp. the corresponding edge $(v', u') \in E(G')$ has $v' \notin O_{v, S}$). Let $S_{irr, v} = S_{irr, v}^{in} \cup S_{irr, v}^{out}$. Similarly, if v is irreparable we let $S_{irr, v} = \{(u, v) : (u, v) \in E(G)\} \cup \{(v, u) : (v, u) \in E(G)\}$ denote the set of all of v 's incoming and outgoing edges. We note that $|S_{irr}| \leq \sum_v |S_{irr, v}|$ since $S_{irr} = \bigcup_v S_{irr, v}$ any irreparable edge must be in one of the sets $S_{irr, v}$. Now we claim that $|S_{irr, v}| \leq |S_v|$ where $S_v = S \cap (\{v\} \times V_{\delta(v)})$ denote the subset of nodes deleted from the corresponding metanode. We now observe that

$$\begin{aligned} |S_{irr, v}| &\leq |S_{irr, v}^{in}| + |S_{irr, v}^{out}| \\ &\leq (\delta(v) - |I_{v, S}|) + (\delta(v) - |O_{v, S}|) \leq 2|S_v|. \end{aligned}$$

The last inequality invokes maximal ST-robustness to show that $\delta(v) - |O_{v, S}| \leq |S_v|$ and $\delta(v) - |I_{v, S}| \leq |S_v|$. If a node v is irreparable then the subsets $I_{v, S}$ and $O_{v, S}$ might be empty since $\delta(v) - |S_v| \leq 0$, but it still holds that $\delta(v) - |O_{v, S}| \leq |S_v|$ and $\delta(v) - |I_{v, S}| \leq |S_v|$.

Thus

$$|S_{irr}| \leq \sum_v |S_{irr, v}| \leq \sum_v 2|S_v| \leq 2|S|.$$

\square

\square

Reminder of Corollary 2.5. (of Theorem 2.3) Suppose that there exists a family $\mathbb{M} = \{M_k\}_{k=1}^{\infty}$ of max ST-robust graphs with depth d_k and constant

indegree. Given any (e,d) -edge-depth-robust DAG G with n nodes and maximum degree δ we can construct a DAG G' with $n \times |M_\delta|$ nodes and constant indegree that is $(e/2, d \cdot d_\delta)$ -depth robust.

Proof of Corollary 2.5. (sketch) We slightly modify our reduction. Instead of replacing each node $v \in G$ with a copy of $M_{\delta(v)}$, we instead replace each node with a copy of $M_{\delta,v} := M_\delta$, attaching the edges same way as in Construction 2.2. Thus the transformed graph G' has $|V(G)| \times |M_\delta|$ nodes and constant indegree. Let $S \subset V(G')$ be a set of nodes that we will remove from G' . By Claim B.1, there exists a path P in $G' - S$ that passes through d metanodes $M_{\delta,v_1}, \dots, M_{\delta,v_d}$. The only difference is that each M_{δ,v_i} is maximally ST-robust *with depth* d_δ meaning we can assume that the sub-path $P_i = P \cap M_{\delta,v_i}$ through each metanode has length $|P_i| \geq d_\delta$. Thus, the total length of the path is at least $\sum_i |P_i| \geq d \cdot d_\delta$. \square

Reminder of Lemma 3.3 [Sch83]. For some suitable constant $c > 0$ any any subset S of $cn/2$ vertices of G_n the graph $H_n^1 - S$ contains $k = cn^{1/3}/2$ vertex disjoint paths A_1, \dots, A_k of length $n^{2/3}$ and $H_n^2 - S$ contains k vertex disjoint paths B_1, \dots, B_k of the same length.

Proof of Lemma 3.3 [Sch83]. Consider $H_n^1 - S$. Since H_n^1 is $(cn, n^{2/3})$ -depth-robust and $|S| = cn/2$, there must exist a path $A_1 = (v_1, \dots, v_{n^{2/3}})$ in $H_n^1 - S$. Remove all vertices of A_1 and repeat to find A_2, \dots . Then we finish with $cn/(2n^{2/3}) = cn^{1/3}/2$ vertex disjoint paths of length $n^{2/3}$. We perform the same process on H_n^2 to find the B_i . \square

Reminder of Lemma 3.4. Let G_n be defined as in Construction 3.2. Then for some constants $c > 0$, with high probability G_n has the property that for all $S \subset V(G_n)$ with $|S| = cn/2$ there exists $A \subseteq V(H_n^1)$ and $B \subseteq V(H_n^3)$ such that for every pair of nodes $u \in A$ and $v \in B$ the graph $G_n - S$ contains a path from u to v and $|A|, |B| \geq 9cn/40$.

Proof of Lemma 3.4. By Lemma 3.3, we know that in $G_n - S$ there exists $k := cn^{1/3}/2$ vertex disjoint paths P_1^i, \dots, P_k^i in each H_n^i of length $n^{2/3}$. Here, c is the constant from Lemma 3.3. Let $U_{j,S}^i$ be the upper half of the j -th path in H_n^i and $L_{j,S}^i$ be the lower half, both of which are relative to the removed set S .

Let $D_{i,j,S}^{lower}$ (resp. $D_{i,j,S}^{upper}$) be an indicator random variable the event that $U_{j,S}^1$ (resp. $U_{j,S}^2$) is disconnected from $L_{i,S}^2$ (resp. $L_{i,S}^3$). Now for each $i \leq k$ define the event $BAD_{i,S}^{upper}$ to be the event that $\sum_j D_{i,j,S}^{upper} \geq k/10$ i.e., the lower path $L_{i,S}^3$ in H_n^3 is disconnected from at least $k/10$ distinct upper paths $U_{j,S}^2$ in H_n^2 . Similarly, define $BAD_{j,S}^{lower}$ to be the event that $\sum_i D_{i,j,S}^{lower} \geq k/10$ i.e., the upper path $U_{j,S}^1$ is disconnected from at least $k/10$ distinct lower paths $L_{i,S}^2$ in H_n^2 .

We now set $GOOD_S^{upper} = [k] \setminus \{i : BAD_{i,S}^{upper}\}$ and $GOOD_S^{lower} = [k] \setminus \{i :$

$BAD_{i,S}^{lower}$ and define

$$B_S := \bigcup_{i \in GOOD_S^{upper}} U_{i,S}^3, \quad \text{and} \quad A_S := \bigcup_{i \in GOOD_S^{lower}} L_{i,S}^1.$$

Now we claim that for every node $u \in A_S$ and $v \in B_S$ the graph $G_n - S$ contains a path from u to v . Since $u \in A_S$ we have $u \in L_{i,S}^1$ for some $i \in GOOD_S^{lower}$. Similarly, $v \in U_{i',S}^3$ for some $i' \in GOOD_S^{upper}$. By the pigeonhole principle there must exist some j s.t. $U_{j,S}^2$ connects to $L_{i',S}^3$ and $U_{i,S}^1$ connects to $L_{j,S}^2$. Thus, we can connect u to v by routing from u to $U_{i,S}^1$ to $L_{j,S}^2$ to $U_{j,S}^2$ to $L_{i',S}^3$ and finally to v . Thus, every pair of nodes in A_S and B_S are connected.

It remains to argue that (whp) for any set S the resulting set $|B_S| = |GOOD_S^{upper}|n^{2/3}$ and $|A_S| = |GOOD_S^{lower}|n^{2/3}$ are sufficiently large. Now we define the events

$$BAD_S^{lower} := |\{i : BAD_{i,S}^{lower}\}| > \frac{k}{10}$$

$$BAD_S^{upper} := |\{i : BAD_{i,S}^{upper}\}| > \frac{k}{10}.$$

Intuitively, BAD_S occurs when more than a small fraction of the events $BAD_{i,S}$ occur. Assuming that BAD_S^{upper} never occurs then for any set S we have

$$|B_S| \geq |GOOD_S|n^{2/3} \geq (9/10)kn^{2/3}/2 = 9cn/40.$$

Similarly, if BAD_S^{lower} never occurs for any set S we are guaranteed to have $|A_S| \geq 9cn/40$.

Consider, for the sake of finding the probabilities, that S is fixed before all of the random edges are added to G_n . We will then union bound over all choices of sets S . First we bound $\mathbb{P}[BAD_{i,S}^{upper}]$ and $\mathbb{P}[BAD_{i,S}^{lower}]$. Union bounding over all $\binom{k}{10}$ subsets we have

$$\begin{aligned} \mathbb{P}[BAD_{i,S}^{upper}] &\leq \binom{k}{10} (1-c/40)^{\tau n^{2/3}/2} \\ &\leq e^k \left(\frac{1}{e}\right)^{c\tau n^{2/3}/80}. \end{aligned}$$

A slightly different calculation holds for $\mathbb{P}[BAD_{i,S}^{lower}]$ since we connect each node in H_n^2 to τ random nodes in H_n^1 and we are now considering the upper path $U_{j,S}^1$ instead of the lower path $L_{i,S}^3$.

$$\begin{aligned}\mathbb{P}\left[BAD_{i,S}^{upper}\right] &\leq \binom{k}{10} \left(1 - \frac{1}{2n^{1/3}}\right)^{\tau(k/10)n^{2/3}/2} \\ &\leq e^k \left(\frac{1}{e}\right)^{c\tau n^{2/3}/80}.\end{aligned}$$

By selecting $\tau > 81 \cdot 80/c^2$ to ensure that $e^k \left(\frac{1}{e}\right)^{c\tau n^{2/3}/80} \leq e^{-80n^{2/3}/c}$.

We remark that for $i \neq j$ the event $BAD_{i,S}^{upper}$ is independent of $BAD_{j,S}^{upper}$ since the τ random incoming edges connected to L_i^2 are sampled independently of the edges for L_j^2 .

We will show that the probability of the event BAD_S^{upper} is very small and then take a union bound over all possible S to show our desired result.

$$\begin{aligned}\mathbb{P}\left[BAD_S^{upper}\right] &\leq \binom{k}{k/10} \mathbb{P}\left[BAD_{1,S} \wedge \dots \wedge BAD_{k/10,S}\right] \\ &= \binom{k}{k/10} \mathbb{P}\left[BAD_{1,S}^{upper}\right]^{k/10} \\ &\leq e^k \left[\left(\frac{1}{e}\right)^{80n^{2/3}/c}\right]^{\frac{cn^{1/3}}{20}} \\ &= \left(\frac{1}{e}\right)^{4n-k}.\end{aligned}$$

Finally, we take the union bound over every possible S of size $cn/2$ nodes. Since G_n has $2n$ nodes there are at most $2^{2n} \leq e^{2n}$ such sets. Thus,

$$\mathbb{P}\left[\exists S \text{ s.t. } BAD_S^{upper}\right] \leq e^{2n} \mathbb{P}\left[BAD_S^{upper}\right] \leq \left(\frac{1}{e}\right)^{2n-k} \ll e^{-n}.$$

Thus, except with negligible probability for any S of size $cn/2$ the event BAD_S^{upper} does not occur for any set S selected *after* G_n is sampled. Similarly, we can reason about the event BAD_S^{lower} . We now utilize the fact that

$$\mathbb{P}\left[BAD_{j,S}^{lower} : BAD_{1,S}^{lower}, \dots, BAD_{j-1,S}^{lower}\right] \leq \mathbb{P}\left[BAD_{j,S}^{lower}\right].$$

Intuitively, this holds because the event $BAD_{i,S}^{lower}$ means that for some set of $k/10$ lower paths (WLOG say $L_{1,S}^2, \dots, L_{k/10,S}^2$) we are guaranteed that none of

the edges these paths hit $U_{i,S}^1$ which only makes it more likely that those edges hit $U_{j,S}^1$ potentially preventing the event $BAD_{j,S}^{lower}$ from occurring.

$$\begin{aligned}
\mathbb{P}[BAD_S^{lower}] &\leq \binom{k}{k/10} \mathbb{P}[BAD_{1,S}^{lower} \wedge \dots \wedge BAD_{k/10,S}^{lower}] \\
&= \binom{k}{k/10} \mathbb{P}[BAD_{1,S}^{lower}] \prod_{j>1} \mathbb{P}[BAD_{j,S}^{lower} : BAD_{1,S}^{lower}, \dots, BAD_{j-1,S}^{lower}] \\
&\leq \binom{k}{k/10} \mathbb{P}[BAD_{1,S}^{lower}]^{k/10} \\
&\leq e^k \left[\left(\frac{1}{e} \right)^{80n^{2/3}/c} \right]^{\frac{cn^{1/3}}{20}} \\
&= \left(\frac{1}{e} \right)^{4n-k}.
\end{aligned}$$

Thus, it follows that $\mathbb{P}[\exists S \text{ s.t. } BAD_S^{upper}] \leq e^{-n}$. □