

Mapping skyrmion stability in uniaxial lacunar spinel magnets from first principles

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The identification of general principles for stabilizing magnetic skyrmion phases in bulk materials over wide ranges of temperatures is a prerequisite to the development of skyrmion-based spintronic devices. Lacunar spinels with the formula GaM_4X_8 , with $\text{M} = \text{V}, \text{Mo}$ and $\text{X} = \text{S}, \text{Se}$, are a convenient case study towards this goal, as they are some of the first bulk systems suggested to host equilibrium chiral skyrmions far from the paramagnetic transition. We derive the magnetic phase diagrams likely to be observed in these materials, accounting for all possible magnetic interactions, and prove that skyrmion stability in the lacunar spinels is a general consequence of their crystal symmetry rather than the details of the material chemistry. Our results are consistent with all experimental reports in this space and demonstrate that the differences in the phase diagrams of particular spinel chemistries are determined by the magnetocrystalline anisotropy, up to a normalization factor. We conclude that skyrmion formation over wide ranges of temperatures can be expected in all lacunar spinels, as well as in a wide range of uniaxial systems with low magnetocrystalline anisotropy.

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I. INTRODUCTION

The prediction and experimental demonstration of topologically nontrivial magnetic structures, commonly called magnetic skyrmions [1–3], has sparked considerable interest in the conditions required for the formation of these phases and their potential for applications in spintronic devices [4,5]. Most reports of skyrmion formation in bulk systems have focused on cubic helimagnets, most frequently with the $\text{B}20$ or β -Mn structures— MnSi [3], FeGe [6], Cu_2OSeO_3 [7], and $\text{Co}_x\text{Zn}_y\text{Mn}_z$ [8]—where skyrmions are typically observed in a narrow range of fields and temperatures near the paramagnetic transition. Much larger stability windows for skyrmions have been reported in thin-film systems [9] and, recently, in the bulk uniaxial helimagnet GaV_4Se_8 [10,11] and Heusler alloys such as $\text{Mn}_{1.4}\text{PtSn}$ [12]. The realization of practical skyrmion-based spintronic devices requires the wide stability windows observed in these materials, motivating a search for general principles leading to the formation of thermally robust skyrmion phases.

The lacunar spinels GaM_4X_8 are a convenient model system for studying mechanisms leading to robust skyrmion stability at all temperatures below the Curie temperature. GaV_4S_8 [13] and GaV_4Se_8 [10,11] have been reported as skyrmion hosts with unusually wide thermal stability windows, while GaMo_4S_8 has been suggested as a skyrmion host on the basis of computational data [14]. Materials in this class exhibit significant metal-metal bonding [15,16], with the electronic structure defined by isolated M_4 molecular units. Their magnetic behavior is well described by interactions between effective spins centered on the M_4 clusters [17]. Furthermore, the $R\bar{3}m$ symmetry and strong Dzyaloshinskii-

Moriya interactions (DMIs) common to these systems guarantee that skyrmion formation can be treated with explicit spin models as a largely two-dimensional problem.

Here, we demonstrate that skyrmion stability in GaM_4X_8 is a consequence of the symmetry of these materials rather than specifics of the magnetic interactions, with the exception of magnetocrystalline anisotropy. We construct a field-temperature magnetic phase diagram for the lacunar spinels based on a general cluster expansion Hamiltonian parametrized using density-functional theory (DFT) data [18–23], which we find to be in close agreement with experimental reports. By analyzing the sensitivity of the phase diagram to all symmetrically allowed perturbations in the Hamiltonian, we find that the form of the phase diagram is largely controlled by uniaxial anisotropy, as well as higher-order in-plane anisotropy. In the low-anisotropy regime, skyrmion formation is guaranteed by the lack of a competing canted spin-wave phase magnetized along the high-symmetry axis, consistent with phenomenological predictions [24], which leads us to conclude that the phase behavior we compute is likely to be broadly applicable to uniaxial magnets with strong in-plane DMIs.

II. METHODS

A. Cluster expansion generation and fitting

We construct the magnetic cluster expansion following a methodology similar to that described by Thomas and Van der Ven [23,25,26]. Our cluster expansion of the internal energy only includes magnetic degrees of freedom, where the moment on each M_4 tetrahedron is represented by a three-dimensional unit vector. To construct the cluster expansion, we identify all site clusters up to a target radius and number of sites and the symmetry operations which map each cluster to itself. Then we generate all possible basis functions for spin

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interactions on each cluster. Following previous derivations of cluster expansions for orientational degrees of freedom [20,21,27], we use products of spherical harmonics $|l, m\rangle = \sqrt{4\pi} Y_m^l(\phi, \theta)$ as a complete basis set for spin interactions, where (ϕ, θ) are the spin vector orientation in spherical coordinates. We additionally group these products according to the total symmetry of the interaction to form basis functions of the form

$$|l_1, l_2; L, M\rangle = 4\pi \sum_{m_1, m_2} c_{m_1, m_2, M}^{l_1, l_2, L} Y_{m_1}^{l_1}(\phi_1, \theta_1) Y_{m_2}^{l_2}(\phi_2, \theta_2),$$

where $c_{m_1, m_2, M}^{l_1, l_2, L}$ are Clebsch-Gordan coefficients. This procedure isolates the basis functions corresponding to exchange ($L = 0$), DMIs ($L > 0$, odd), and anisotropy ($L > 0$, even). Finally, we find the purely real component of each basis function invariant to the symmetry of the cluster and, using Gram-Schmidt orthogonalization, obtain an orthonormal basis set for spin interactions on each cluster. The cluster expansion implementation relies on an in-house PYTHON code accelerated using the NUMBA package [28], while general structure processing, data handling, and symmetry analysis rely on the pymatgen package [29]. A detailed description of the cluster expansion and the procedure used to generate interaction functions is available in Supplemental Note 1 [30].

To obtain a fit for the interaction coefficients in the cluster expansion from DFT data, we follow a standard methodology designed for the automated generation of phase diagrams [19,31]. First, we enumerate symmetrically distinct collinear and spin-wave configurations compatible with supercells up to size 4. We refine this data set by identifying the least constrained correlation vectors in the input data as the eigenvectors of the correlation covariance matrix with the smallest eigenvalues. We then obtain spin configurations corresponding to these correlation vectors and add them to the fitting data set. Finally, we fit the cluster expansion interaction coefficients using least-squares regression, while using a genetic algorithm to eliminate basis functions from the Hamiltonian so as to maximize the cross-validation score.

B. Monte Carlo sampling and ground-state search

We use a Hamiltonian Monte Carlo approach to sample the finite-temperature behavior given by the cluster expansion Hamiltonian. Our Monte Carlo implementation exactly follows the formalism described by Wang *et al.* [32], with trajectory sampling based on the No U-Turn Sampler/Dynamic Multinomial Sampling methods [33,34]. All Monte Carlo runs reported here are constant-field heating runs, where each temperature step first rejects 800 uncorrelated samples for equilibration and then saves 2000 uncorrelated samples for production. To ensure that the obtained samples are uncorrelated, we set the number of Monte Carlo passes between samples to exceed the estimated autocorrelation decay time.

To identify ground-state spin configurations, we first generate candidate structures using simulated annealing starting from a random configuration and representative configurations of known phases. We then relax each configuration to its local minimum using conjugate gradient minimization and save the lowest-energy structure.

C. Density functional theory calculations

DFT calculations are performed using the Vienna *Ab Initio* Simulation Package (VASP) [35], using the projector-augmented-wave method [36] with the Perdew-Burke-Ernzerhof (PBE) exchange-correlation functional [37]. We do not apply a Hubbard- U correction because our previous benchmarks on GaV_4Se_8 revealed that the standard on-site Hubbard- U approach leads to an incorrect electronic configuration and magnetic behavior [15]. All calculations account for spin-orbit coupling and are converged to 10^{-6} eV in total energy. We use a reciprocal space discretization of 100 k points per \AA^{-3} and a smearing width of 0.05 eV based on a convergence of total energy across all distinct supercells containing 2 formula units of GaMo_4S_8 to 0.5 meV/f.u. To further reduce error arising from changes in the k -point mesh across different supercells, we reference all magnetic configuration energies to that of a *c*-axis ferromagnet computed using the same supercell. In all cases, DFT calculations are done statically, based on the experimentally observed low-temperature structure.

III. RESULTS

A. Magnetic cluster expansion Hamiltonian

We begin by defining an effective spin Hamiltonian for the magnetic behavior of a GaM_4X_8 lacunar spinel in the form of a cluster expansion, which is a summation over interaction correlation functions φ with interaction coefficients J . The correlation functions φ are determined by the lattice type and symmetry of the material, while the interaction coefficients J are specific to each chemistry. Thus, we can systematically explore the magnetic behavior of GaM_4X_8 by establishing which magnetic phase diagrams are likely to arise given the overall form of the Hamiltonian, across possible choices of interaction parameters J .

The full form of a cluster expansion Hamiltonian is

$$E = \sum_{\Omega} \sum_{\alpha} J_{\alpha}^{\Omega} \sum_{\omega \in \Omega} \hat{p}_{\omega}[\phi_{\alpha}^{\Omega}] = \sum_i J_i \varphi_i,$$

where ϕ are interaction basis functions and J are interaction coefficients. Each interaction is defined with respect to a cluster of sites ω , where symmetrically equivalent clusters are grouped into orbits Ω . The interaction basis functions contain all spin couplings consistent with the symmetry of the cluster, which include conventional Heisenberg exchange, DMIs, and anisotropy interactions, as well as any higher-order terms. The symmetry operation \hat{p}_{ω} generates the cluster ω from a reference cluster for its orbit Ω . The total contribution of a basis function ϕ for the symmetrically equivalent clusters in Ω defines the correlation function φ .

We take the symmetry of the crystal to be $R3m$ as shown in Figure. 1(a), which results from a low-temperature distortion of the $F\bar{4}3m$ vacancy-ordered spinel structure along the $\langle 111 \rangle$ direction. The magnetic sublattice consists of a distorted face-centered-cubic (FCC) arrangement of M_4 tetrahedral clusters, shown in Fig. 1(b), where each M_4 tetrahedron can be treated as a single spin vector. As the distance between M_4 clusters is large, we approximate the magnetic energy with only on-site and nearest-neighbor couplings. For the three symmetrically

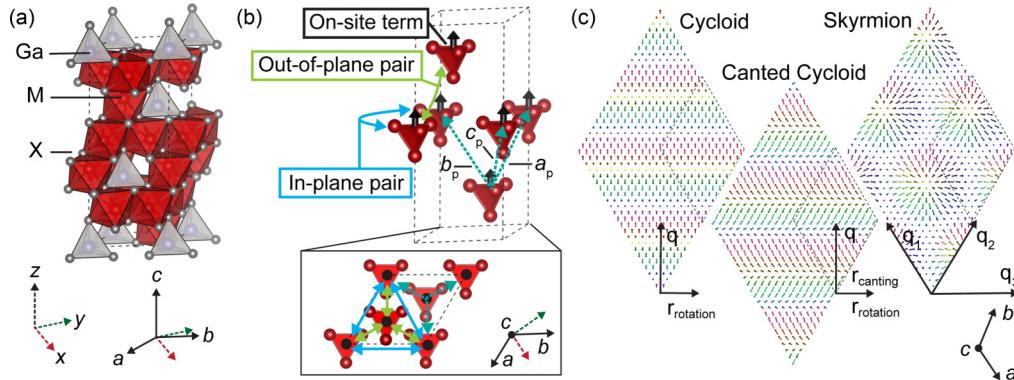


FIG. 1. (a) Low-temperature structure of a GaM_4X_8 lacunar spinel in the $R\bar{3}m$ conventional unit cell. (b) Model for the magnetic structure, treating M_4 tetrahedra as magnetic units forming a face-centered-cubic lattice, where the magnetic Hamiltonian consists of single-site and nearest-neighbor interaction energies. Lattice vectors (a_p , b_p , c_p) shown form the primitive lattice used to define the cluster expansion Hamiltonian. (c) Example configurations of helimagnetic phases observed in lacunar spinels, where q denotes a propagation wave vector and colors correspond to spin orientations.

distinct couplings present (on-site, out-of-plane pair, and in-plane pair), we derive spin-interaction basis functions consistent with the symmetry of each cluster. The basis functions are polynomials of the spin-vector components, up to sixth order for the on-site term and bilinear order for the pair terms. These interactions, listed in Table I, form a complete basis set for the magnetic Hamiltonian that is applicable to any material with a relatively sparse FCC magnetic sublattice and $R\bar{3}m$ symmetry.

The coefficients J of each correlation function φ parametrize the variation of the Hamiltonian across different chemistries. Thus, in order to understand the phase behavior of all GaM_4X_8 lacunar spinels with $R\bar{3}m$ symmetry, it is sufficient to evaluate how the field-temperature phase diagram evolves with the components of J . We limit ourselves to J vectors appropriate for locally ferromagnetic materials ($J_7 > 0$, $J_{12} > 0$), allowing for strong spin-orbit coupling. This regime is characteristic of the behavior of skyrmion-hosting lacunar spinels with $\text{M} = \text{V}, \text{Mo}$ and $\text{X} = \text{S}, \text{Se}$, where the observed magnetic phases are ferromagnet, cycloid, canted cycloid, and skyrmion. Example configurations of these phases are shown in Fig. 1(c).

B. Derivation of an example phase diagram for GaM_4X_8

Our strategy for exploring phase behavior in this system is to construct a full field-temperature phase diagram for one choice of J vector and then calculate how perturbations in J translate to changes in phase transitions. While this approach is only strictly valid for small deviations from the initial choice of J , the degree to which extrapolation is valid is determined by whether the form of the phase diagram is more determined by the values of J or by which correlation functions φ are present in the Hamiltonian. In this case, we argue that given an appropriate normalization, the form of the correlation functions φ plays the more important role, leading to a universal behavior of the phase diagram.

We choose our initial J vector, $J^{(0)}$, by fitting the Hamiltonian to reproduce the magnetic behavior of GaMo_4S_8 as computed from DFT. We choose GaMo_4S_8 as a convenient reference point, as a recent paper has suggested that this

material exhibits cycloid and skyrmion phases with particularly short wavelengths [14], which allows us to directly study these phases with the periodic-cell Monte Carlo. Furthermore, the electronic structure of GaMo_4S_8 appears to be reasonably captured by the standard PBE functional, while the better-known V-based analogs require more sophisticated, computationally expensive methods such as RPA [15]. Following a state-of-the-art cluster expansion fitting procedure, as well as a DFT calculation scheme designed to minimize spurious sources of error (details available in the methods), we obtain the $J^{(0)}$ vector listed in Table I with an RMSE of 0.3 meV/formula unit (f.u.) across a total energy range of 7 meV/f.u. The low absolute value of the error justifies our choice of truncating the Hamiltonian at nearest-neighbor interactions and bilinear pair couplings, as the inclusion of any additional basis functions would likely only be capturing noise in the DFT data. While both the total error and the uncertainty on the components of $J^{(0)}$ are small, the significance of these error bars in relation to phase behavior is not immediately clear. However, as our objective is to obtain a reasonable initial $J^{(0)}$ for our perturbative analysis, we proceed to characterize the phase diagram given by this fit and address the role of uncertainty, as well as general perturbations to J , in a later section.

We first establish the ground states of the $J^{(0)}$ Hamiltonian as a function of the total magnetization, which include cycloid, canted cycloid, skyrmion, and ferromagnet phases. The dominant periodicity of a helimagnet is set by the competition between DMIs and exchange, which typically remains close to the period of the cycloid phase. The lowest-energy commensurate cycloid in this system has wave vector $q = [\frac{1}{n}00]$ for $n = 12$, as shown in Fig. 2(a). We thereby choose a (12,12,3) supercell of the conventional unit cell (1296 M_4 units) for a full ground-state enumeration, as this supercell is compatible with all low-energy cycloid variants, as well as the typical sixfold skyrmion lattice phase. We obtain the internal energy profile shown in Fig. 2(b), which, as a function of the magnetization along the c -axis, proceeds through the cycloid phase at low magnetization, the skyrmion phase at intermediate magnetization, and the ferromagnet phase at high magnetization. Repeating the ground-state search for other

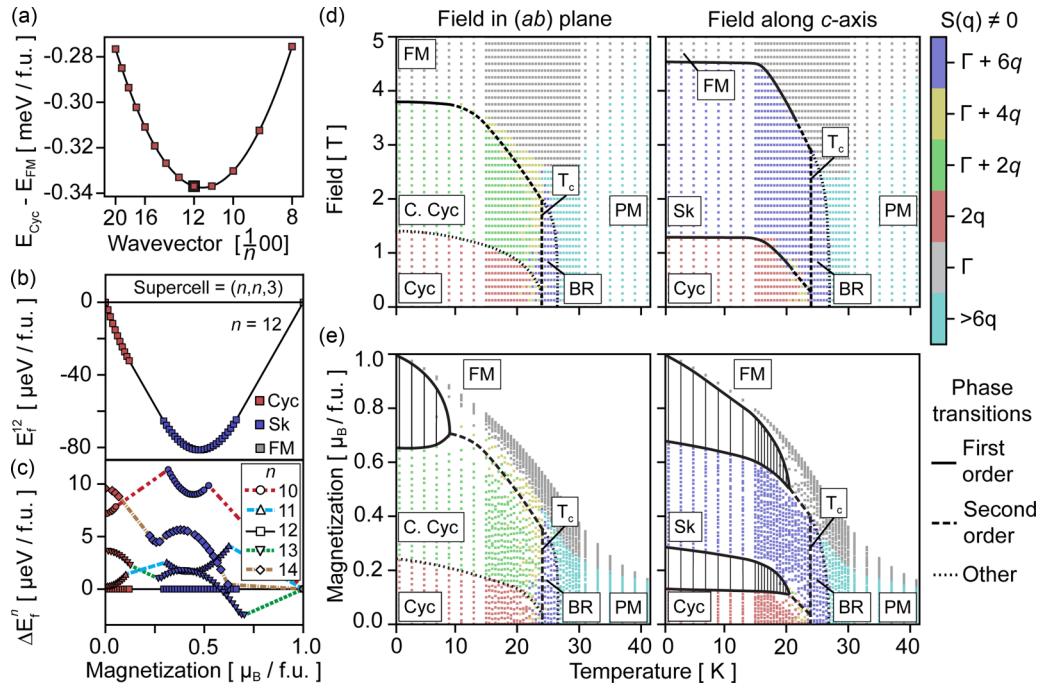


FIG. 2. (a) Energy of an ideal cycloid relative to that of a ferromagnet magnetized along the c -axis, as a function of n , which defines the cycloid propagation wave vector $q_n = [\frac{1}{n}00]$. (b, c) Formation energies of ground-state configurations as a function of the average magnetization along the c -axis, constrained to an $(n, n, 3)$ periodic supercell of the $R\bar{3}m$ unit cell shown in Fig. 1(a). Formation energies are given with respect to the $n = 12$ cycloid and c -axis ferromagnet (b) and the full $n = 12$ ground-state energy profile (c). (d, e) Magnetic phase diagram arising from the $J^{(0)}$ parametrization of the cluster expansion Hamiltonian, as a function of the magnetic field magnitude (d) and total magnetization (e). Colors denote the number of q points for which the structure factor $S(q)$ is nonzero. Phase labels correspond to the ferromagnet (FM), cycloid (Cyc), canted cycloid (C. Cyc), skyrmion (Sk), Brazovskii region (BR), and paramagnet (PM). The locations and orders of phase boundaries are drawn based on Monte Carlo data to best agree with changes in $S(q)$, the topological index (see Supplemental Fig. 1 [30]), discontinuities in internal energy and magnetization, and peaks in fluctuation data. T_c denotes the Curie temperature. Note that “other” denotes a change in the structure factor $S(q)$ not accompanied by any discernible discontinuities in free energy.

$(n, n, 3)$ supercells, we find that while the commensurate cycloid and canted cycloid phases are always minimized for $n = 12$, the skyrmion phase relaxes from $n = 12$ to $n = 13$ at high magnetization ($\approx 8\%$ change in wavelength), as shown in Fig. 2(c). This result is intriguing from the perspective of experimentally detecting skyrmions in diffraction data by means of a shift in the q -vector of the magnetic structure away from that of a cycloid and is consistent with observed changes in the q vector in the skyrmion phase of GaV_4S_8 [13]. However, for the purposes of thermodynamic stability calculations, the difference in energy between the $n = 12$ and the $n = 13$ skyrmion is small enough to be negligible.

The finite-temperature phase diagram of the $J^{(0)}$ Hamiltonian is shown in Figs. 2(d) and 2(e) as a function of the applied field and observed magnetization, respectively. The locations and orders of phase transitions are estimated based on changes in the magnetic structure factor, topological index, discontinuities in internal energy and magnetization, and peaks in fluctuation data.

The low-field phase up to the Curie temperature (T_c) is a cycloid. Magnetization in the (ab) plane leads to a continuous transition into a canted cycloid phase, followed by a transition to a ferromagnet. At low temperatures (approximately $T < 0.5T_c$), the transition from canted cycloid to ferromagnet is first order, while at higher temperatures this transition be-

comes second order. We conclude that the order of the phase transition changes because we observe a peak in the magnetic susceptibility at this point at all temperatures, but the discontinuity in magnetization only exists below $0.5T_c$. Magnetization along the c -axis leads to the formation of the skyrmion phase, followed by the ferromagnet phase. The formation of the topologically nontrivial skyrmion phase is also confirmed by a change in the topological index from 0 to -1 as the c -axis magnetization is increased (see Supplemental Fig. 1 [30]). Both transitions are first order at most temperatures, becoming second order only close to T_c (approximately $T > 0.8T_c$). At low temperatures, skyrmions are stabilized with respect to cycloids enthalpically, consistent with the behavior of the ground-state configurations. However, above approximately $0.67T_c$ the skyrmion region expands at the expense of the cycloid region, indicating that at elevated temperatures, skyrmions are additionally stabilized entropically. Immediately above T_c , the cycloid, canted cycloid, and skyrmion phase regions extend into a partially disordered phase dominated by fluctuations in the (ab) plane at the cycloidal q vectors, as a two-dimensional analog of the Brazovskii region described in cubic helimagnets [38,39]. Note that despite having a structure factor similar to that of the skyrmion phase, the two-dimensional Brazovskii region is topologically trivial as can be seen in Supplemental Fig. 1 [30]. Finally, at higher temperatures, the system fully disorders to form a paramagnet.

TABLE I. Clusters and symmetrized basis functions for the GaM_4X_8 magnetic cluster expansion Hamiltonian and the $J^{(0)}$ vector fitted to GaMo_4S_8 DFT data. Cluster site coordinates and basis functions are given for the reference cluster, in lattice coordinates with respect to the primitive lattice vectors (a_p, b_p, c_p) given in Fig. 1(b). The number of equivalents for each cluster refers to the number of symmetrically equivalent clusters of this type per primitive cell. Basis functions are defined in terms of spherical harmonics $|l, m\rangle$ for the on-site terms and Clebsch-Gordan functions $|l_1, l_2; L, M\rangle$ for pair clusters (r_1, r_2), as described under Methods. The Cartesian form of the basis functions is available in Supplemental Table 1 [30]. Basis function superscripts denote whether the interaction corresponds to exchange (E), DMIs (D), or anisotropy (A). Parentheses in the $J^{(0)}$ vector components denote uncertainty in the last digit.

Cluster type	Basis function	$J^{(0)}$ (meV)
On-site	$\phi_1^A = \sqrt{2} 2, 0\rangle$	0
$r = (0, 0, 0)$	$\phi_2^A = -i(4, -3\rangle + 4, 3\rangle)$	0.03(5)
(1 equiv.)	$\phi_3^A = \sqrt{2} 4, 0\rangle$	0
	$\phi_4^A = 6, -6\rangle + 6, 6\rangle$	0
	$\phi_5^A = -i(6, -3\rangle + 6, 3\rangle)$	0
	$\phi_6^A = \sqrt{2} 6, 0\rangle$	0
Out-of-plane	$\phi_7^E = \frac{\sqrt{2}}{3} 1, 1; 0, 0\rangle$	0.62(5)
$r_1 = (0, 0, 0)$	$\phi_8^D = \frac{i}{3}(1, 1; 1, 1\rangle - 1, 1; 1, -1\rangle)$	0.88(9)
$r_2 = (-1, 0, 0)$	$\phi_9^A = -\frac{i}{3}(1, 1; 2, 1\rangle + 1, 1; 2, -1\rangle)$	0
(3 equiv.)	$\phi_{10}^A = \frac{\sqrt{2}}{3} 1, 1; 2, 0\rangle$	0
	$\phi_{11}^A = \frac{1}{3}(1, 1; 2, 2\rangle + 1, 1; 2, -2\rangle)$	0
In-plane	$\phi_{12}^E = \frac{\sqrt{2}}{3} 1, 1; 0, 0\rangle$	1.07(5)
$r_1 = (0, 0, 0)$	$\phi_{13}^D = (\frac{1}{6} + \frac{i}{\sqrt{12}}) 1, 1; 1, 1\rangle$	0.20(9)
$r_2 = (-1, 0, 1)$	$+ (\frac{1}{6} - \frac{i}{\sqrt{12}}) 1, 1; 1, -1\rangle$	
(3 equiv.)	$\phi_{14}^D = \frac{-i\sqrt{2}}{3} 1, 1; 1, 0\rangle$	0.08(7)
	$\phi_{15}^A = \frac{\sqrt{2}}{3} 1, 1; 2, 0\rangle$	0
	$\phi_{16}^A = (\frac{1}{\sqrt{12}} - \frac{i}{6}) 1, 1; 2, 1\rangle$	0
	$- (\frac{1}{\sqrt{12}} + \frac{i}{6}) 1, 1; 2, -1\rangle$	
	$\phi_{17}^A = (\frac{1}{6} - \frac{i}{\sqrt{12}}) 1, 1; 2, 2\rangle$	0.1(1)
	$+ (\frac{1}{6} + \frac{i}{\sqrt{12}}) 1, 1; 2, -2\rangle$	

C. Variation in phase stability with changes in the Hamiltonian

Having established the finite-temperature phase diagram for one parametrization of the Hamiltonian, $J^{(0)}$, we evaluate how the phase diagram may change as the J coefficients are varied. We first identify normalization factors for the phase diagram to account for changes in the Hamiltonian that amount to rescaling the field and temperature axes. We then use generalized Clausius-Clapeyron relationships to identify which components of the J vector may alter the locations of first-order transitions seen in the phase diagram.

Figure 3(a) shows the phase diagram obtained for $J^{(0)}$, in units of the characteristic temperature and field for this system. The red circles highlight the three first-order transitions that define the low-temperature region of the phase diagram. The normalization factor for temperature is $|J|/k_B$,

as any homogeneous rescaling of the Hamiltonian must also rescale the temperature. The normalization factor for the field is given by the characteristic difference in energy between the low-field and the high-field ground states, which are the cycloid and ferromagnet phases, respectively. In units of the magnetic field, this factor is $2\pi^2 q^2 |J| / \mu_B g M_s$, where q is the magnitude of the cycloid wave vector in lattice coordinates and M_s is the magnetic moment per spin. A full derivation is available in Supplemental Note 2 [30]. Note that this factor is identical to the D^2/A normalization used in previous literature, where D and A are the effective DMI and exchange constants, respectively.

Figure 3(b) plots how the locations of the three low-temperature first-order transitions change with variation in the components of $J^{(0)}$. The left panels account for the correlation functions corresponding to conventional bilinear spin couplings, while the right panels illustrate the effect of higher-order on-site anisotropy terms, plotted schematically in Fig. 3(c). Note that φ_1 corresponds to quadratic single-spin anisotropy, while φ_{10} and φ_{15} are equivalent to XXZ anisotropy for out-of-plane and in-plane exchange, respectively. In this case, these terms yield exactly the same behavior and are plotted as a single line. The change in the phase boundary location $H^\dagger / \frac{2\pi^2 q^2 |J|}{\mu_B g M_s}$ is given by the generalized Clausius-Clapeyron relation,

$$\frac{2\pi^2 q^2 |J|}{\mu_B g M_s} \frac{\partial (H^\dagger / \frac{2\pi^2 q^2 |J|}{\mu_B g M_s})}{\partial J} = \frac{\Delta \langle \varphi \rangle}{\Delta M} - \frac{2H^\dagger}{q} \frac{\partial q}{\partial J} - H^\dagger J,$$

where $\Delta \langle \varphi \rangle$ and ΔM are the change in the correlation functions and magnetization across the first-order phase transition. Note that this expression explicitly accounts for the variation in q and $|J|$ for the purposes of normalizing H^\dagger , while the change in J is expressed in units of $(2\pi^2 q^2 |J|)_{\Delta J=0}$.

The perturbation data shown in the left panel in Fig. 3(b) reveals that the low-temperature region of the phase diagram is largely invariant to changes in most of the J coefficients in the Hamiltonian, save for changes in $|J|$ and q , which amount to rescaling the temperature and field axes. By far the most important correlation functions are those corresponding to uniaxial anisotropy ($\varphi_{1,3,6,10,15}$), which have a qualitatively similar impact on the phase boundaries, and higher-order in-plane anisotropy φ_4 (right panels). The uniaxial terms $\varphi_{1,3,6,10,15}$ shift the skyrmion/ferromagnet boundary, penalizing skyrmion formation in the easy-axis regime. The φ_4 anisotropy function is unique in that it only alters the phase boundaries left unaffected by the uniaxial terms, shifting the cycloid/skyrmion and canted cycloid/ferromagnet boundaries but leaving the skyrmion/ferromagnet boundary unchanged. Fortunately, the only anisotropy function included in the $J^{(0)}$ simulation is φ_2 , which has no impact on the phase boundaries, so that the $J^{(0)}$ results are equivalent to a zero-anisotropy regime where all helimagnetic phases of interest appear at all temperatures. Finally, the only impact of exchange and DMI terms beyond varying q and $|J|$ is to alter the field at which a canted cycloid in the (ab) plane transforms to a ferromagnet.

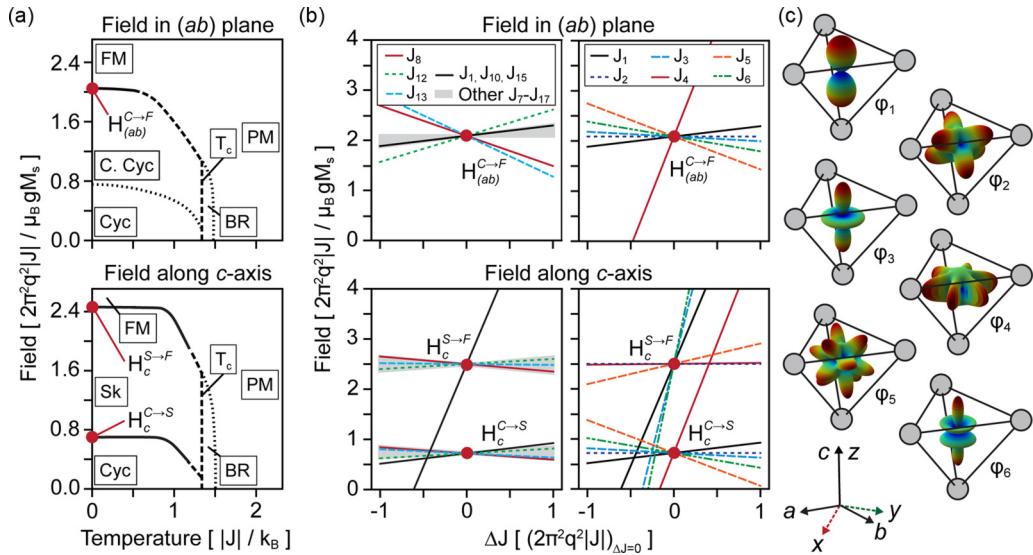


FIG. 3. (a) Normalized magnetic phase diagram derived using the $J^{(0)}$ Hamiltonian, marking three first-order phase transitions: cycloid to ferromagnet in the (ab) plane, $[H_{(ab)}^{C\rightarrow F}]$, and cycloid to skyrmion and skyrmion to ferromagnet along the c -axis ($H_c^{C\rightarrow S}$ and $H_c^{S\rightarrow F}$, respectively). Phase labels are defined in the caption to Fig. 2. (b) Change in the normalized phase transition fields $H_{(ab)}^{C\rightarrow F}$, $H_c^{C\rightarrow S}$, and $H_c^{S\rightarrow F}$ upon variation of the Hamiltonian parameters J . Note that the field normalization factor $2\pi^2 q^2 |J| / \mu_B g M_s$ varies with ΔJ , while the units of ΔJ [$(2\pi^2 q^2 |J|)_{\Delta J=0}$] are taken to be constant. (c) Magnetocrystalline anisotropy functions $\varphi_1, \dots, \varphi_6$ shown relative to an M_4 tetrahedron, where the color and distance from the tetrahedron center along a certain direction represent the value of φ_i for that spin orientation.

D. Skyrmion stability determined by uniaxial anisotropy

At low temperatures, the stability of skyrmions in this system is largely controlled by the presence of uniaxial anisotropy in the form of the $\varphi_{1,3,6,10,15}$ correlation functions, as well as high-order in-plane anisotropy in the form of φ_4 . As uniaxial anisotropy is the most common form of anisotropy observed in uniaxial magnets, we now derive the impact of this term on the skyrmion region at all temperatures, using φ_1 as a proxy for all uniaxial anisotropy functions in the Hamiltonian. We note, however, that in rare cases where higher-order anisotropies ($\varphi_2, \dots, \varphi_6$) are strong, more complex phase behavior is possible.

The evolution of the phase diagram with the coefficient of φ_1 , J_1 , as a function of the field along the c -axis and temperature, is shown in Fig. 4(a). The phase diagram exhibits three broad regions, corresponding to easy-axis, easy-plane, and isotropic scenarios. The skyrmion and cycloid regions are highlighted in blue and red, respectively, for representative slices in each region. We obtain this phase diagram using a linear extrapolation of the Helmholtz free energy A ,

$$A = A^{(0)} + \frac{\partial A}{\partial J_1} \Delta J_1 = A^{(0)} + \langle \varphi_1 \rangle \Delta J_1,$$

where $A^{(0)}$ is the Helmholtz free energy obtained for $J^{(0)}$. As this extrapolation is only applicable at a constant temperature, we neglect any changes in T_c due to changes in J_1 . Similarly, as variation in J_1 has a negligible impact on $|J|$ and no impact on q , the normalization factors for field, temperature, and J are taken to be constant. To check the validity of this extrapolation, we confirm that the extrapolated phase diagrams highlighted in the easy-axis and easy-plane regions in Fig. 4(a) agree with Monte Carlo data for the same conditions.

The impact of uniaxial anisotropy on skyrmion stability is largely determined by the stabilization of the competing out-of-plane and in-plane ferromagnetic and canted cycloid phases. Easy-axis anisotropy favors the out-of-plane ferromagnet configuration and thus suppresses the skyrmion phase and, eventually, the cycloid phase. Easy-plane anisotropy destabilizes the out-of-plane ferromagnet and thus enhances the skyrmion stability region, up to the point where the easy-plane anisotropy is sufficient to stabilize canted cycloids and in-plane ferromagnetic configurations at zero field, at which point the skyrmion region remains stable only at high c -axis fields, consistent with phenomenological solutions [40,41]. Elevated temperatures suppress the effect of anisotropy while preserving the qualitative trends, leading to a much wider range of anisotropy constants for which skyrmions and cycloids are stable than in the low-temperature limit. The profound impact of anisotropy constants on skyrmion stability at low temperatures is reminiscent of recent reports of low-temperature skyrmion stabilization in Cu_2OSeO_3 , where the role of anisotropy is to suppress the competing canted spin-wave phases [42,43].

Uniaxial anisotropy also varies in the range of field directions for which skyrmions may be observed, with easy-axis anisotropy favoring skyrmions over a wide range of field orientations and easy-plane anisotropy allowing for skyrmions only for fields close to the c -axis. Figure 4(b) shows the evolution of the cycloid and skyrmion phase boundaries as a function of the applied field direction. The color of the phase boundaries corresponds to the field angle, shown in the legend in terms of the angle with respect to the c -axis and high-symmetry directions in the structure. In the isotropic case, the skyrmion region moves to slightly higher fields with increasing θ , up to $\theta_{\max} \approx 40^\circ$, beyond which only cycloid, canted cycloid, and ferromagnet phases are stable. In the

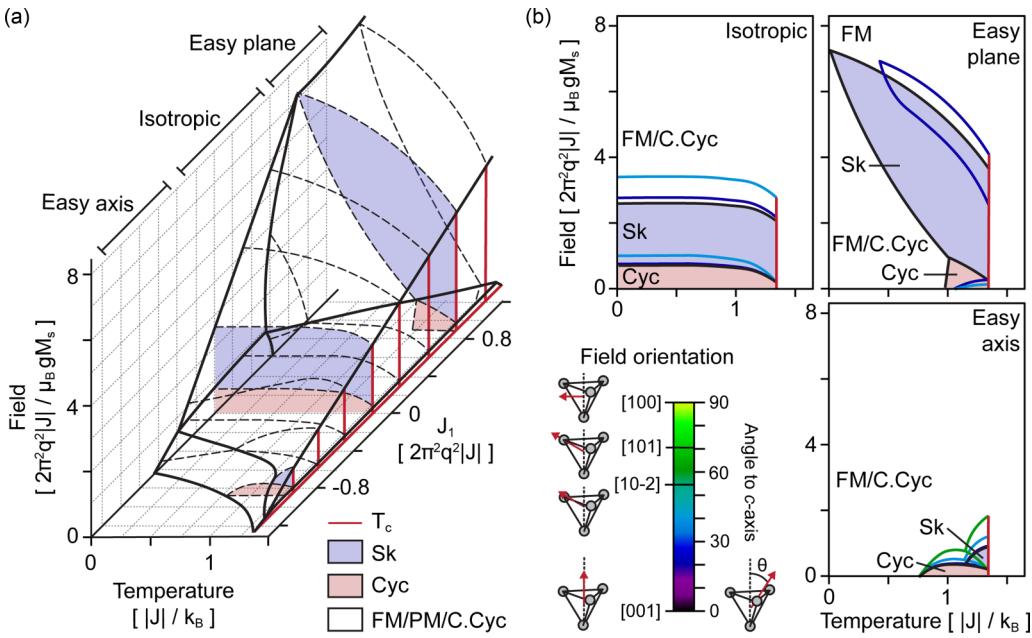


FIG. 4. (a) Variation in the normalized magnetic phase diagram with the uniaxial anisotropy parameter J_1 , focusing on the cycloid and skyrmion phase transitions with an applied field along the c -axis. Representative phase diagrams for the easy-axis, easy-plane, and isotropic cases ($J_1/2\pi^2q^2|J| = -0.9, +0.9, 0$, respectively) are highlighted. Phase labels are defined in the caption to Fig. 2. (b) Variation in skyrmion phase boundaries with the field orientation, for the easy-axis, easy-plane, and isotropic cases. The colors of the phase boundaries denote the angle of the field with respect to the c -axis.

easy-plane case, the skyrmion region quickly narrows with increasing θ , disappearing above $\theta_{\max} \approx 20^\circ$. In the easy-axis case, the skyrmion stability region is much smaller in field magnitude, but wider in field angle, with a high-temperature skyrmion phase appearing up to $\theta_{\max} \approx 70^\circ$. These results, as well as the broad impact of uniaxial anisotropy, confirm the conclusions reached in the phenomenological analysis reported by Leonov and Kezsmarki [44].

The formation of skyrmions in easy-axis systems over a wide range of field orientations is important in the context of resolving skyrmion formation experimentally. The easy-axis scenario leads to skyrmion formation for fields applied along the [101] family of Miller indices of the unit cell shown in Fig. 1(a). These directions correspond to the $\langle 001 \rangle$ axes of variants of the lacunar spinel distorted along directions equivalent to the $\langle 111 \rangle$ axis of the high-temperature $F\bar{4}3m$ phase. In a real material, where all symmetrically equivalent variants of the $\langle 111 \rangle$ distortion are likely to be present, we would thus expect skyrmion phase boundaries following both the black and the green curves, even if the field is applied parallel to the c -axis of one of the variants. This is precisely the scenario observed in GaV_4S_8 [13], which we estimate corresponds to the strongly easy-axis $J_1/2\pi^2q^2|J| = -1.00$ slice of the phase diagram.

E. Predicted phase diagrams for V and Mo systems

Finally, we use the phase diagram shown in Fig. 4 to evaluate the magnetic phase diagrams of several V- and Mo-based spinels. Our estimates for the value of the reduced anisotropy $J_1/2\pi^2q^2|J|$ for GaV_4S_8 , GaV_4Se_8 , GaMo_4S_8 , and GaMo_4Se_8 are listed in Table II, with phase diagrams given by field-temperature slices in Fig. 4(a) at the given

level of anisotropy. The magnetic phase diagrams of GaV_4S_8 and GaV_4Se_8 have been studied in-depth experimentally and offer a direct comparison to our results. We similarly rely on experimental data to obtain T_c , q , and J_1 for the V systems [11,13]. Experimental data on GaMo_4S_8 and GaMo_4Se_8 are more sparse, but as these systems are well represented by DFT, we use computational data to obtain estimates for the magnetic parameters. Given the small energy scale and critical importance of the anisotropy constants to phase behavior, we obtain the value of the anisotropy constants independently of other terms in the magnetic Hamiltonian, using data computed within the same unit cell so as to minimize numerical noise arising from k -point discretization error. Specifically, the energy of orienting a ferromagnetic configuration along various crystallographic directions, computed using the primitive cell of the structure, fully constrains $J_{1,\dots,6}$ independently of any exchange or DMI terms. Thus, we are able to refine the cluster expansion fit by first fitting $J_{1,\dots,6}$ to this high-accuracy anisotropy data and then fitting all other terms to the full data set. As a result, we are able to reduce the fitting error

TABLE II. Behavior of V- and Mo-based lacunar spinels based on the phase diagram shown in Fig. 4. T_c , q , and J_1 data for the V systems is based on experimental data from Refs. [13] and [11], while data for the Mo systems is based on our DFT calculations.

	T_c (K)	q	J_1 (μeV)	$J_1/2\pi^2q^2 J $
GaV_4S_8	13	1/26	-25	-1.00
GaV_4Se_8	18	1/27	2	0.06
GaMo_4S_8	23	1/12	-34	-0.17
GaMo_4Se_8	27	1/20	25	0.29

of the anisotropy energy to the level of μeV , as can be seen in Supplemental Fig. 2 [30], sufficient to reliably resolve the anisotropy constants.

IV. DISCUSSION

A. Broad applicability of the uniaxial skyrmion phase diagram

A direct comparison of our predicted phase diagram to experimental results reported for GaV_4S_8 and GaV_4Se_8 lends credibility to our analysis. In both cases, the phase diagrams obtained using the reduced anisotropy values from Table II are in qualitative agreement with experiment. We quantitatively reproduce the temperature behavior but predict phase transitions at fields 1.5 to 2 times larger than those observed. The most likely source for this error is a deviation in $\mu_B g M_s$ away from our assumed value of $2 \mu_B$. We also neglect the impact of stray fields, which destabilize the cycloid and Néel skyrmion states seen here in favor of a ferromagnetic configuration with 180° domain walls [24]. In the strong DMI regime relevant to lacunar spinels, this error does not qualitatively change the results. However, the impact of stray fields becomes pronounced for cycloidal systems with weak DMIs, limiting the applicability of Fig. 4(a) to systems well away from the long-wavelength cycloid stability bounds derived by Bogdanov and Hubert [24]. Furthermore, the agreement between the phase behavior we derive in Fig. 4 and that obtained phenomenologically for the same symmetry [40,41,44] provides an important consistency check for our atomistic model of the magnetic behavior of these skyrmion-host materials.

The insensitivity of the skyrmion region of the phase diagram to the values of DMIs and exchange suggests that the phase behavior seen in Fig. 4(a) may generalize to other uniaxial systems. We observe that high-moment Néel skyrmions form preferentially to canted cycloids when the magnetic field is orthogonal to the rotation axis of any cycloidal variant. This mechanism is independent of any specific interaction parameters and arises from the fact that canted cycloids only develop a moment parallel to their rotation axis as shown in Fig. 1(c). Thus, we speculate that a similar mechanism may lead to Néel skyrmion formation over wide field and temperature ranges in other systems where cycloid variants have rotation axes constrained to a single plane. Based on symmetry arguments alone, this behavior is most likely in strong-DMI, low-anisotropy systems whose point group is one of $6mm$ (C_{6v}), $3m$ (C_{3v}), $4mm$ (C_{4v}), or $mm2$ (C_{2v}) [45]. If we assume that a similar mechanism is applicable to the formation of canted helices and antiskyrmions, materials with $42m$ (D_{2d}) and $\bar{4}$ (S_4) point-group symmetry may also exhibit this behavior. Several phenomenological analyses of skyrmion formation in C_{nv} , D_{2d} , and S_4 crystals [40,41,44] report similar results, lending support to a broad applicability of these trends.

B. Parametrization of magnetic cluster expansion Hamiltonians

An important implication of our results is that uncertainty quantification is essential to the construction of magnetic cluster expansion Hamiltonians. Conventional cluster expansion fitting techniques rely on the minimization of the total error

against DFT energies. This methodology works well when all interactions have similar energy scales and when working with discrete degrees of freedom such as atomic configurations [46]. However, this approach is not sufficient when relatively small energy terms, such as the magnetocrystalline anisotropy explored here, play a decisive role in determining which phases form. By analyzing the sensitivity of the phase diagram to the values of the interaction coefficients through generalized Clausius-Clapeyron relations and linear free energy extrapolation based on $\partial A / \partial J_i = \langle \varphi_i \rangle$, one can identify terms in the cluster expansion which play an outsized role in determining the phase behavior. In particular, one can use this approach to evaluate the importance of terms not included in the original Hamiltonian, due to either basis set truncation or elimination during the fitting process. Once all important terms are known, the fitting procedure must be adjusted to ensure that these terms are fitted accurately [47,48], which may increase the average error of the fit but, nonetheless, yields more qualitatively correct predictions of phase behavior.

V. CONCLUSION

We have demonstrated that skyrmion stability across a wide range of fields and temperatures in GaM_4X_8 lacunar spinels is a general consequence of the symmetry of the material and the fact that magnetocrystalline anisotropy energy is typically small. We reproduce the complex magnetic phase diagrams of these materials, including long-wavelength magnetic order, without relying on empirical parameters, and thus gain insight into the relationship between spin-orbit coupling and skyrmion formation. We find that magnetic cluster expansions parametrized using density functional theory data can accurately predict this magnetic phase diagram provided that the fitting procedure leads to a high-fidelity form for the anisotropy energy. More generally, reliable magnetic phase diagram prediction requires an evaluation of the impact of fitting error and uncertainty on phase stability. As we find that the magnetic phase behavior here is determined by simple, transferable mechanisms dictated by point-group symmetry, we speculate that our observations are likely broadly applicable to uniaxial systems with C_{nv} , D_{2d} , and S_4 symmetry.

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