

Constitutive modelling of corneal tissue; influence of three-dimensional collagen fiber microstructure

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The cornea, the transparent tissue in the front of the eye, along with the sclera, plays a vital role in protecting the inner structures of the eyeball. The precise shape and mechanical strength of this tissue are mostly determined by the unique microstructure of its extracellular matrix (ECM). A clear picture of the 3D arrangement of collagen fibrils within the corneal ECM has recently been obtained from the secondary harmonic generation images. However, this important information about the through-thickness distribution of collagen fibrils was seldom taken into account in the constitutive modeling of the corneal behavior. The present work creates a generalized structure tensor (GST) model to investigate the mechanical influence of collagen fibril through-thickness distribution. It then uses numerical simulations of the corneal mechanical response in inflation experiments to assess the efficacy of the proposed model. A parametric study is also done to investigate the influence of model parameters on numerical predictions. Finally, a brief comparison between the performance of this new constitutive model and a recent angular integration (AI) model from the literature is given.

1 Introduction

The cornea protects the inner contents of the eye against external insults, provides about two-thirds of eye's refractive power, and transmits nearly 90% of the incident light onto the lens [1, 2]. The proper optical function of the cornea de-

pends on its ability to maintain its precise shape under physiological loading conditions. The corneal extracellular matrix, stroma, constitutes almost the entire corneal thickness and serves as the key component in providing the mechanical strength necessary to resist external and internal forces.

The microstructure of the stroma resembles a lattice structure, where collagen fibrils are embedded in thin parallel-to-the-surface lamellae [3, 4]. The X-ray scattering methods gave detailed information about the preferred collagen fibril orientation in the corneal stroma [5, 6, 7, 8, 9]. In particular, it was found that although collagen fibrils are oriented along with two preferred directions, i.e., nasal-temporal (N-T) and inferior-superior (I-S) within the central region of the human cornea, they tend to be aligned circumferentially in the limbus region. Unlike the human cornea, collagen fibrils in bigger mammals such as bovine are found to be aligned mainly in the I-S direction [10, 11]. The degree of in-plane dispersion varies in depth, i.e., although collagen fibrils are more aligned along with N-T and I-S directions within the posterior thirds, they are more isotropically oriented within the anterior thirds [12]. The images obtained from the X-ray scattering technique could not fully characterize the 3D dispersion of collagen fibrils through the corneal thickness. Nevertheless, the second harmonic generation (SHG) images, about a decades ago, provided a reconstruction of 3D collagen fibril orientation [13, 14]. These images showed that collagen fibrils are highly interwoven in the anterior region but are parallel to each other in the posterior region.

The early works utilized simple linear-elastic or hyperelastic models for representing the corneal constitutive response [15, 16]. Later, linear transverse anisotropic models were used to account for the anisotropic response [17,

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18]. Hyperelastic models considering both isotropic and anisotropic contributions were also used. In these models, the dispersion of collagen fibrils was not considered in early works [19, 20], but was added later [21, 22, 23, 24, 25, 11, 26]. These recent models could be categorized into two groups: the angular integration (AI) models and the generalized structure tensor (GST) models.

The AI-based models have a straightforward formulation, where the free energy corresponding to the continuous collagen fibril distribution is obtained by performing the direct angular integration of an infinitesimal fraction of fibers in a given direction. The statistical description of the collagen fibril distribution could be represented by either distribution probability density function or direct extrapolation of the X-ray scattering data. The AI models with different forms of PDFs have been applied to various soft tissues [27, 28, 29, 30, 31, 32, 33]. The AI models provide relatively good representations of the mechanical response of biological tissues. However, their main disadvantage is that the numerical implementation of their required direct angular integration scheme is complicated and time-consuming.

On the other hand, the GST models are relatively faster. They use the generalized structure tensor with a dispersion parameter to quantify the collagen fibril dispersion [34]. Once the dispersion parameter is specified, the stretching of collagen fibrils at any given macroscopic deformation is known and the required angular integration can be evaluated. However, this model can be used with the limited number of PDFs for collagen fibril orientation because the derivation of analytical relations between PDFs and dispersion parameters is not trivial [34, 35].

The collagen fibril distribution in SHG images suggests that both in-plane and out-of-plane dispersions are essential. In this work, we use a GST model that takes into account both in-plane and out-of-plane collagen fibril distribution throughout the cornea. The in-plane distribution is approximated by fitting the normal distribution function in polar coordinates to the X-ray scattering data [9]. The out-of-plane distribution of collagen fibrils at a given thickness level has been represented by fitting Gaussian curves to the cutoff angle histogram obtained from the SHG images [14]. We numerically implement the proposed GST model in a commercial finite element software Abaqus/Standard [36] by writing a user-defined material subroutine (UMAT). The model performance is studied by simulating the results of inflation tests [37] using six different collagen fibril distribution of transversely isotropic, isotropic, perfect alignment, planar dispersion, planar isotropic, and full-thickness variation. A parametric study is also performed to determine the effects of collagen fibril interweaving on stress profiles across the corneal thickness. Lastly, it is shown that the proposed model has similar functionality as the available AI model from the literature [26], yet cheaper in terms of the computational expenses.

The remainder of this paper is organized as follows. In Section 2, we review the continuum mechanical framework and present the main constitutive equations. The governing equation is briefly summarized in Section 3. The numerical

results are shown in Section 4. Lastly, we finish in Section 5 with some concluding remarks. In Appendix A, we present the details of our code verification.

2 Continuum mechanical framework

This section covers the large deformation kinematics required for describing the hyperelastic anisotropic behavior of the corneal stroma. A similar framework has been previously applied to soft materials [38, 39, 40].

2.1 Kinematics

Let \mathbf{x}_R represent an arbitrary material point in the fixed reference configuration of the body \mathcal{B}_R . The referential body \mathcal{B}_R undergoes a motion $\mathbf{x} = \chi(\mathbf{x}_R, t)$ to the deformed body \mathcal{B}_t with deformation gradient given by

$$\mathbf{F} = \nabla \chi, \quad \text{and} \quad J = \det \mathbf{F} > 0. \quad (1)$$

The right and left Cauchy-Green tensors are given by $\mathbf{C} = \mathbf{F}^\top \mathbf{F}$ and $\mathbf{B} = \mathbf{F} \mathbf{F}^\top$, respectively. The deformation gradient admits the polar decomposition, $\mathbf{F} = \mathbf{R} \mathbf{U}$, where \mathbf{R} is the rotation and $\mathbf{U} = \sqrt{\mathbf{C}}$ is the stretch. The distortional part of the deformation gradient is

$$\mathbf{F}_{\text{dis}} = J^{-1/3} \mathbf{F}, \quad \text{and} \quad \det \mathbf{F}_{\text{dis}} = 1. \quad (2)$$

The distortional right and left Cauchy-Green deformation tensors are

$$\begin{aligned} \mathbf{C}_{\text{dis}} &= \mathbf{F}_{\text{dis}}^\top \mathbf{F}_{\text{dis}} = J^{-2/3} \mathbf{C} \quad \text{and} \\ \mathbf{B}_{\text{dis}} &= \mathbf{F}_{\text{dis}} \mathbf{F}_{\text{dis}}^\top = J^{-2/3} \mathbf{B}, \end{aligned} \quad (3)$$

respectively. We assume there are two families of collagen fibrils in the corneal stroma with their mean referential directions denoted by unit vectors \mathbf{a}_0^4 and \mathbf{a}_0^6 , respectively. Additionally, we introduce a unit vector \mathbf{a}_n – normal to the plane spanning by \mathbf{a}_0^4 and \mathbf{a}_0^6 – to identify the out-of-plane direction. The invariants $\bar{I}_1, \bar{I}_4, \bar{I}_6$ and \bar{I}_n are written as

$$\begin{aligned} \bar{I}_1 &= \text{tr} \mathbf{C}_{\text{dis}}, \quad \bar{I}_i = \mathbf{C}_{\text{dis}} : \mathbf{a}_0^i \otimes \mathbf{a}_0^i \quad \text{for } i = 4, 6, \\ \text{and} \quad \bar{I}_n &= \mathbf{C}_{\text{dis}} : \mathbf{a}_n \otimes \mathbf{a}_n. \end{aligned} \quad (4)$$

We use the generalized structure tensor \mathbf{H}_i to quantify the dispersion of both families of collagen fibrils [35, 41]

$$\mathbf{H}_i = A \mathbf{1} + B \mathbf{a}_0^i \otimes \mathbf{a}_0^i + (1 - 3A - B) \mathbf{a}_n \otimes \mathbf{a}_n \quad \text{for } i = 4, 6 \quad (5)$$

with constants A and B written as

$$A = 2\kappa_{\text{ip}}\kappa_{\text{op}} \quad \text{and} \quad B = 2\kappa_{\text{op}}(1 - 2\kappa_{\text{ip}}). \quad (6)$$

Note that κ_{ip} and κ_{op} in the above expression are in-plane and out-of-plane dispersion parameters whose characteristics will be discussed in the following.

2.2 PDFs for collagen fibrils with dispersion

The detailed collagen fibril microstructural information could be obtained from the SHG images, which fully characterize their in-plane and out-of-plane angular distributions [13, 14, 26]. Here, the mean orientation of the collagen fibrils at the reference state is represented by a unit vector \mathbf{N} in terms of two Eulerian angles $\Theta \in [0, 2\pi]$ and $\Phi \in [-\pi/2, \pi/2]$. We assume that the base vector \mathbf{e}_3 is the out-

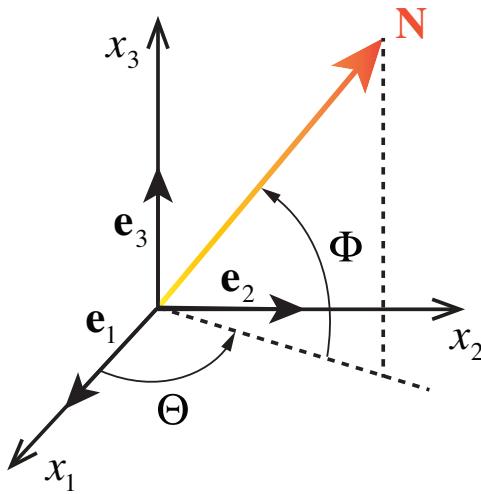


Fig. 1. The mean orientation of collagen fibrils is represented by a unit vector \mathbf{N} in terms of two Eulerian angles Θ and Φ .

of-plane direction (see Figure 1). We use the bivariate Von-Mises distribution function $\rho(\Theta, \Phi) = \rho_{ip}(\Theta)\rho_{op}(\Phi)$ to describe the dispersion of collagen fibrils over the unit sphere [35],

$$\begin{aligned} \rho_{ip}(\Theta) &= \frac{\exp[a \cos 2(\Theta \pm \xi)]}{I_0(a)} \quad \text{and} \\ \rho_{op}(\Phi) &= 2\sqrt{\frac{2b}{\pi}} \frac{\exp[b(\cos 2\Phi - 1)]}{\text{erf}(\sqrt{2b})}, \end{aligned} \quad (7)$$

where a and b denote the concentration parameters for each distribution function $\rho_{ip}(\Theta)$ and $\rho_{op}(\Phi)$, ξ denotes the angle between the mean collagen fibril orientation and the base vector \mathbf{e}_1 , and $I_0(a)$ denotes the modified Bessel function of the first kind of order 0. According to Holzapfel et al. [35], both in-plane and out-of-plane dispersion parameters are defined as

$$\begin{aligned} \kappa_{ip} &= \frac{1}{2\pi} \int_0^{2\pi} \rho_{ip}(\Theta) \sin^2 \Theta d\Theta, \quad \text{and} \\ \kappa_{op} &= \frac{1}{4} \int_{-\pi/2}^{\pi/2} \rho_{op}(\Phi) \cos^3 \Phi d\Phi. \end{aligned} \quad (8)$$

The closed-form relations between dispersion parameters and concentration parameters are obtained from equations

(7) and (8),

$$\kappa_{ip} = \frac{1}{2} - \frac{I_1(a)}{2I_0(a)}, \quad \kappa_{op} = \frac{1}{2} - \frac{1}{8b} + \frac{1}{4} \sqrt{\frac{2}{\pi b}} \frac{\exp(-2b)}{\text{erf}(\sqrt{2b})}, \quad (9)$$

where $\kappa_{ip} \in [0, 1]$ and $\kappa_{op} \in [0, 1/2]$ are dispersion parameters, and $I_1(a)$ is the modified Bessel function of the first kind of order 1. In Figure 2, we project the total PDF in equation (7) onto the surface of a unit sphere with different combinations of in-plane and out-of-plane dispersion parameters; here one family of fibers with orientation \mathbf{a}_0 that is aligned with the unit vector $\mathbf{N} = [1, 0, 0]^\top$ is considered. The out-of-plane normal is set to be $\mathbf{a}_n = [0, 0, 1]^\top$. As $a \rightarrow 0$ and $b \rightarrow 0$, the collagen fibrils are evenly distributed. Conversely, as $a \rightarrow \infty$ and $b \rightarrow \infty$, the collagen fibrils are perfectly aligned long with the mean orientation. The collagen fibrils are isotropically distributed within $x_1 - x_2$ plane as $a \rightarrow 0$ and $b \rightarrow \infty$, and are isotropically distributed within $x_1 - x_3$ plane as $a \rightarrow \infty$ and $b \rightarrow 0$. Accordingly, the generalized structure tensor \mathbf{H} for one family of fibers could be simplified into five special cases:

Perfect alignment – $\mathbf{H} = \mathbf{a}_0 \otimes \mathbf{a}_0$;

Isotropic dispersion – $\mathbf{H} = (1/3)\mathbf{1}$;

Transversely isotropic – $\mathbf{H} = \kappa\mathbf{1} + (1 - 3\kappa)\mathbf{a}_0 \otimes \mathbf{a}_0$ when $\kappa = 1 - 2\kappa_{op}$;

Planar dispersion – $\mathbf{H} = k\mathbf{I} + (1 - 2\kappa)\mathbf{a}_0 \otimes \mathbf{a}_0$ when \mathbf{I} is the 2D identity and k is the dispersion parameter in the plane;

Planar isotropic – $\mathbf{H} = (1/2)\mathbf{1}$.

2.3 Free energy

The free energy Ψ_R of corneal stroma per unit reference volume is additively decomposed into 1) isotropic contribution from underlying matrix Ψ_R^m , and 2) anisotropic contribution from two families of collagen fibrils Ψ_R^{fi} ,

$$\Psi_R = \Psi_R^m(\bar{I}_1, J) + \sum_{i=4,6} \Psi_R^{fi}(\mathbf{C}_{\text{dis}}, \mathbf{H}_i). \quad (10)$$

The matrix domain is treated as a *nearly*-incompressible neo-Hookean material,

$$\Psi_R^m = \frac{1}{2} G_0(\bar{I}_1 - 3) + \frac{1}{2} K(\ln J)^2 \quad (11)$$

with G_0 denotes the ground state shear modulus, and K denotes the bulk modulus.

The mechanical response of collagen fibrils is modeled by the following exponential form [34],

$$\Psi_R^{fi} = \frac{k_1}{2k_2} \left(\exp(k_2(\bar{I}_i^* - 1)^2) - 1 \right) \quad \text{for } i = 4, 6, \quad (12)$$

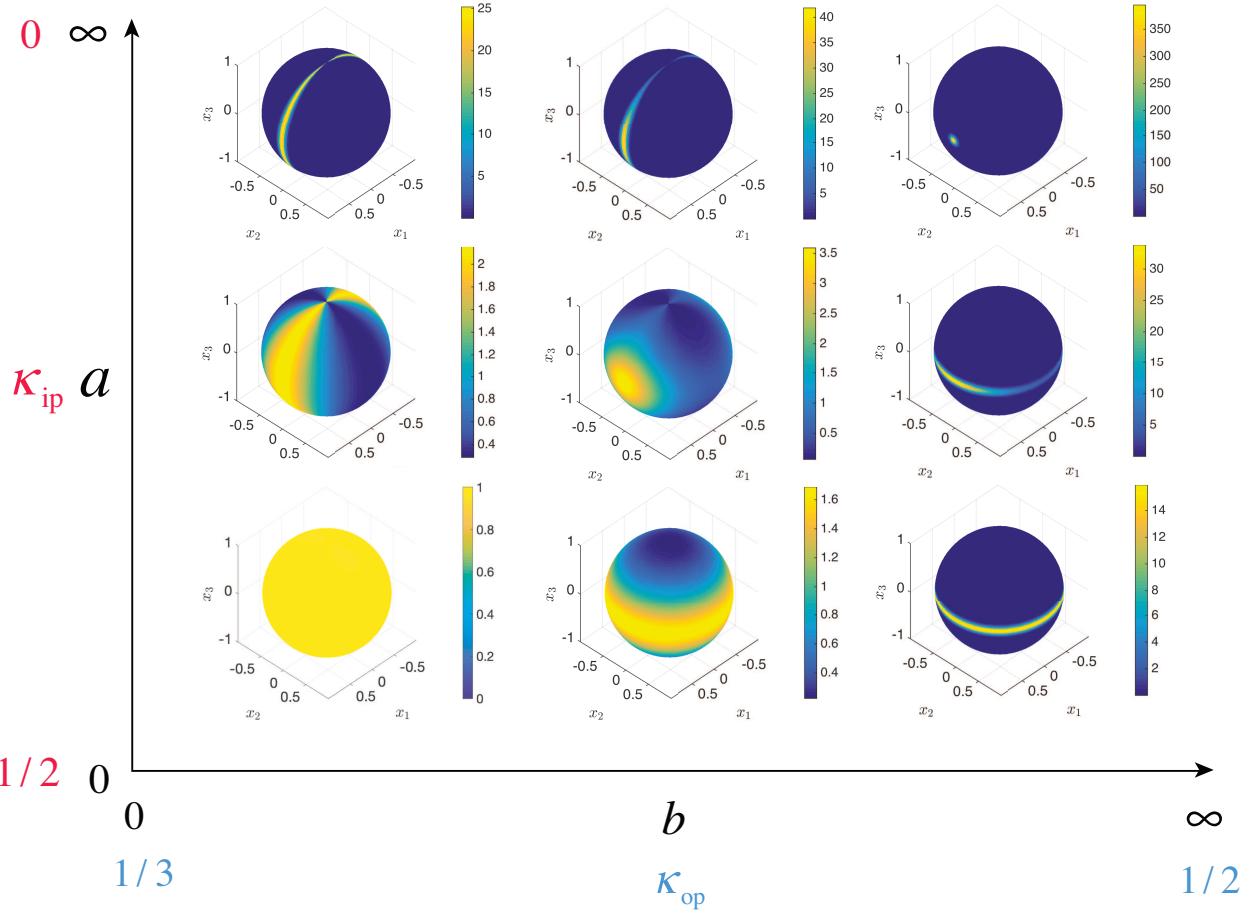


Fig. 2. The total PDF $\rho(\Theta, \Phi)$ in equation (7) is projected onto the surface of a unit sphere considering different in-plane and out-of-plane distributions. The main collagen fibril orientation is $\mathbf{N} = [1, 0, 0]^\top$ with an out-of-plane normal of $\mathbf{a}_n = [0, 0, 1]^\top$.

where k_1 and k_2 denote two the stress-like parameters. The distortional generalized invariant \bar{I}_i^* is given by

$$\begin{aligned} \bar{I}_i^* &= \text{tr}(\mathbf{H}_i \mathbf{C}_{\text{dis}}) \\ &= A\bar{I}_1 + B\bar{I}_i + (1 - 3A - B)\bar{I}_n \quad \text{for } i = 4, 6. \end{aligned} \quad (13)$$

It is worth noting that the collagen fibril free energy does *not* have any volumetric contribution to the total free energy. Furthermore, collagen fibrils are *not* able to withstand any compression, so if $\bar{I}_4 \leq 1$ and $\bar{I}_6 \leq 1$, the free energy ψ_{R}^{fi} is completely omitted in equation (10).

Based on thermodynamic restrictions, the Cauchy stress is then given through

$$\mathbf{T} = 2J^{-1} \mathbf{F} \frac{\partial \psi_{\text{R}}}{\partial \mathbf{C}} \mathbf{F}^\top = \mathbf{T}^m + \sum_{i=4,6} \mathbf{T}^{fi}, \quad (14)$$

where

$$\mathbf{T}^m = J^{-1} [G_0(\mathbf{B}_{\text{dis}})_0 + K(\ln J)\mathbf{1}] \quad (15a)$$

$$(\mathbf{B}_{\text{dis}})_0 = \mathbf{B}_{\text{dis}} - \frac{1}{3} \text{tr}(\mathbf{B}_{\text{dis}}) \quad (15b)$$

and

$$\begin{aligned} \mathbf{T}^{fi} &= 2J^{-5/3} [k_1(\bar{I}_i^* - 1) \exp(k_2(\bar{I}_i^* - 1)^2)] [\mathbf{F} \mathbf{H}_i \mathbf{F}^\top \\ &\quad - \frac{1}{3} \text{tr}(\mathbf{H}_i \mathbf{C}) \mathbf{1}] \end{aligned} \quad (16)$$

are the stress contributions from the underlying matrix and collagen fibrils, respectively.

3 Governing equations

The balance of linear momentum in the deformed body \mathcal{B}_t under the equilibrium condition is given by

$$\text{div} \mathbf{T} = \mathbf{0}, \quad (17)$$

where \mathbf{T} the total Cauchy stress given by equation (14). The surface traction on the deformed body surface $\partial \mathcal{B}_t$ is given by

$$\mathbf{t}(\mathbf{n}) = [[\mathbf{T}]] \mathbf{n}, \quad (18)$$

where \mathbf{n} is the out-normal to $\partial\mathcal{B}_t$, and $[[\bullet]]$ is the jump operator, defined as the difference between the quantity inside and outside the domain.

4 Results and Discussion

The proposed model is implemented numerically in Abaqus/Standard [36] by writing a user-defined material subroutine (UMAT), and its verification is found in Appendix A. In this section, we investigate the capabilities of the proposed model by simulating the standard inflation test.

4.1 Experimental measurements

We use the previous inflation experimental results of Anderson et al. [37]. In these experiments, porcine corneal samples, with the narrow ring of surrounding scleral tissue, were mounted such that the portion that connects the limbus and the sclera was fully fixed. An internal pressure with a maximum value of 100 mmHg was gradually (quasi-static condition) applied to the samples' posterior surface. Meanwhile, the apical displacement was continuously monitored by a CCD laser displacement sensor and plotted against the pressure.

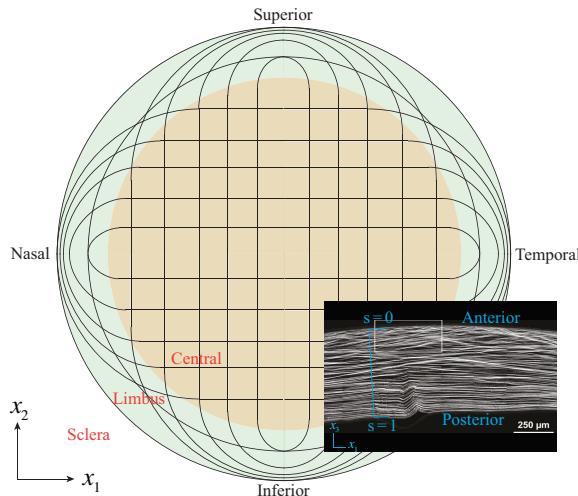


Fig. 3. Schematics of the human cornea. The top view is drawn based on the work from [42]. The key components are Central – a circular region with a radius about 4.5 mm; Limbus – a ring border about 1.5 to 2 mm wide that encircles the periphery of the central region; Sclera – the opaque tissue of the eye; Nasal – the side near the nose; Inferior – the south side; Temporal – the opposite side of nasal; Superior – the north side; Anterior – the outer surface; Posterior – the innermost surface. The inset is a typical SHG image [14] showing the variation of collagen fibril distribution across the thickness.

4.2 Geometry and boundary conditions

The first step in any numerical simulation is to define an accurate geometrical representation of the sample. Since we do not have any information about the exact geometry used in

inflation tests [37], a generic but popular form is adopted. In particular, we use a biconic surface equation in a cylindrical coordinate system $\{\Theta, r, x_3\}$ for both anterior and posterior surfaces of the cornea [24],

$$x_3 - G + \frac{r^2 E}{1 + \sqrt{1 - r^2 F}} = 0 \quad (19)$$

with

$$E = \frac{\cos^2(\Theta - \Theta_{x_1})}{R_{x_1}} + \frac{\sin^2(\Theta - \Theta_{x_1})}{R_{x_2}} \quad (20)$$

and

$$F = (Q_{x_1} + 1) \frac{\cos^2(\Theta - \Theta_{x_1})}{R_{x_1}^2} + (Q_{x_2} + 1) \frac{\sin^2(\Theta - \Theta_{x_1})}{R_{x_2}^2}. \quad (21)$$

Here, G is the maximum vertical height at $r = 0$, both R_{x_1} and R_{x_2} are the maximum curvatures of the principal meridians along x_1 and x_2 directions, respectively. Θ_{x_1} is the direction of the steepest principal meridian, both Q_{x_1} and Q_{x_2} are the asphericity parameters in the directions Θ_{x_1} and $\Theta_{x_1} + \pi/2$, respectively.

We use referential unit vectors \mathbf{a}_0^4 and \mathbf{a}_0^6 to represent the two mean orientations of collagen fibrils (see Figure 4a). In the central region, two families of the collagen fibrils are running from N-T (red) and I-S (blue) directions in a 3-D curved fashion. In the limbus region, one family of collagen fibrils (red) is running circumferentially, and another (blue) is pointing outwards from the center. Additionally, the out-of-plane direction is denoted as the unit vector \mathbf{a}_n (black).

For simplicity, we assume that both families of collagen fibrils share the same in-plane dispersion parameter κ_{ip} . Guided by the previous study on X-ray scattering images [9], the spatial distribution of in-plane dispersion is given by [24]

$$\kappa_{ip}(\Theta) = \left(\frac{\kappa_{ip}^{\min} + \kappa_{ip}^{\max}}{2} \right) - \left(\frac{\kappa_{ip}^{\max} - \kappa_{ip}^{\min}}{2} \right) \cos 4\Theta, \quad (22)$$

where $\kappa_{ip}^{\max} = 0.5$ and $\kappa_{ip}^{\min} = 0.1$ are the maximum and minimum value, respectively. After adding the r dependency, equation (22) becomes

$$\kappa_{ip}(\Theta, r) = \kappa_{ip}^{\min} + \frac{1}{2} (\kappa_{ip}(\Theta) - \kappa_{ip}^{\min}) \left(1 - \cos \frac{2\pi r}{R_{TZ}} \right), \quad (23)$$

where $R_{TZ} = 5.5$ mm denotes the radius of the transition zone. Note that we assigned a homogeneous in-plane dispersion $\kappa_{ip} = 0.5$ in the limbus region. The visualization of equation (23) is shown in Figure 5a. In the process of assigning the out-of-plane parameter κ_{op} across the thickness, we used a local coordinate $s \in [0, 1]$ parallel to the out-of-plane

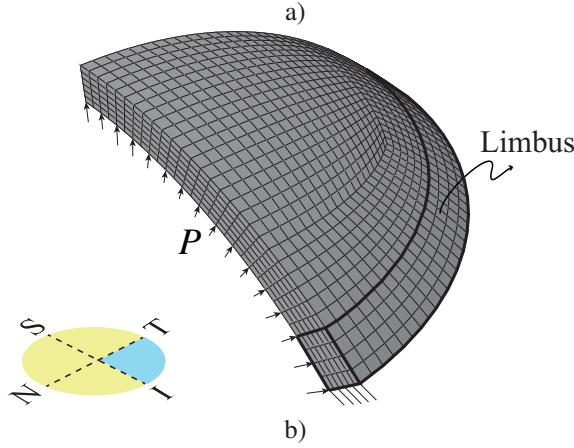
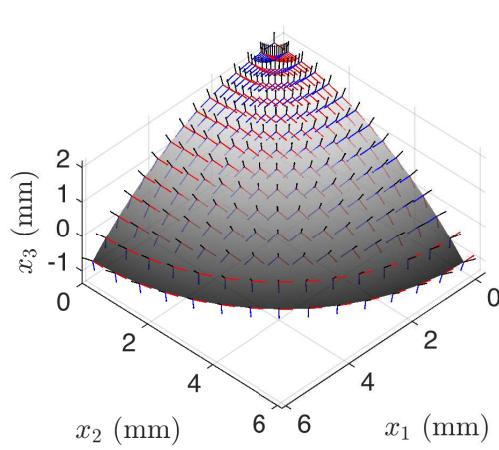


Fig. 4. Assignment of mean collagen fibril orientation and finite element mesh. a) The main orientation of two families of collagen fibrils is represented as two unit vectors of \mathbf{a}_0^4 (red) and \mathbf{a}_0^6 (blue). The out-of-plane direction is denoted by the unit vector \mathbf{a}_n (black). b) The finite element mesh, along with the applied boundary conditions. A quarter of the entire geometry is shown here for clarity.

unit vectors. The local coordinate $s = 0$ at the anterior surface, while $s = 1$ at the posterior surface (see inset plot in Figure 3). Guided by the SHG image, where the degree of interweaving between collagen fibrils is found to be varying exponentially across the thickness, we link the out-of-plane dispersion parameter κ_{op} to the local coordinate s via the following function,

$$\kappa_{op}(s) = \kappa_{op}^{\min} + (\kappa_{op}^{\max} - \kappa_{op}^{\min})(1 - \exp(-\gamma_d s)), \quad (24)$$

where $\kappa_{op}^{\min} = 1/3$ and $\kappa_{op}^{\max} = 1/2$ are minimum and maximum value, respectively, and the constant γ_d controls the non-linearity of the function (see Figure 5b).

The geometry is discretized into U3D8 elements with six elements spanning the thickness, and only a quarter of the entire mesh is presented for clarity (see Figure 4b). For boundary conditions, we fully fix the surface linking the limbus and sclera and applied an internal pressure of $P = 100$ mmHg to the posterior surface.

Before running the simulation, one should pay extra at-

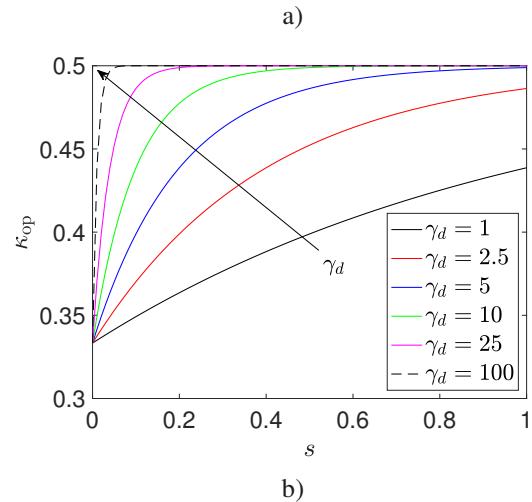
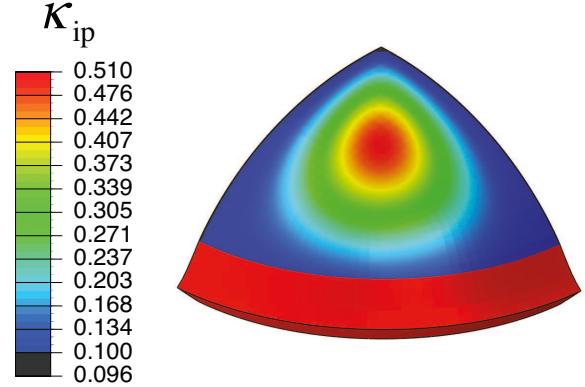


Fig. 5. a) The variation of the in-plane dispersion parameter κ_{ip} as a function of space, b) the variation of the out-of-plane dispersion parameter as a function of corneal thickness s .

tention to the starting point of the simulation. Given that the in-vivo measured dimensions $\mathbf{X}_{\text{physio}}$ of the cornea under a physiological loading of $P_{\text{physio}} = 16$ mmHg, we first obtain the stress-free geometry through a zero-pressure algorithm [43, 44]. In the algorithm, the mesh connectivity is kept unchanged while the zero-pressure nodal coordinates \mathbf{X}_{k+1} are iteratively updated through

$$\mathbf{X}_{k+1} = \mathbf{X}_k + (\mathbf{X}_k^{\text{def}} - \mathbf{X}_{\text{physio}}), \quad (25)$$

where \mathbf{X}_k and $\mathbf{X}_k^{\text{def}}$ denote the zero-pressure and deformed coordinates at k th step. Meanwhile, the mean collagen fibril orientations are consistently mapped back to the zero-pressure configuration. Here, the iteration is terminated based on the global error $e = \|\mathbf{X}_k^{\text{def}} - \mathbf{X}_{\text{Physio}}\|_{\infty}$. The parameters of the biconic equation (19) used for the anterior surface under $P = 16$ mmHg are obtained from previous studies [24], i.e., $R_{x_1} = 7.71$ mm, $R_{x_2} = 7.87$ mm, $\Theta_{x_1} = 0.51\pi$, $Q_{x_1} = Q_{x_2} = -0.41$ and $G = 2.52$ mm. The parameters used for the posterior surface under $P = 16$ mmHg are $R_{x_1} = 6.36$ mm, $R_{x_2} = 6.69$ mm, $\Theta_{x_1} = 0.51\pi$, $Q_{x_1} = Q_{x_2} = -0.52$ and $G = 1.89$ mm. We plot the physiological coordinates as black stars, while the deformed and zero-pressure coordinates at

each iteration as red and blue stars (see Figure 6a). It is observed that the global error is minimized quickly within about ten iterations (see Figure 6b).

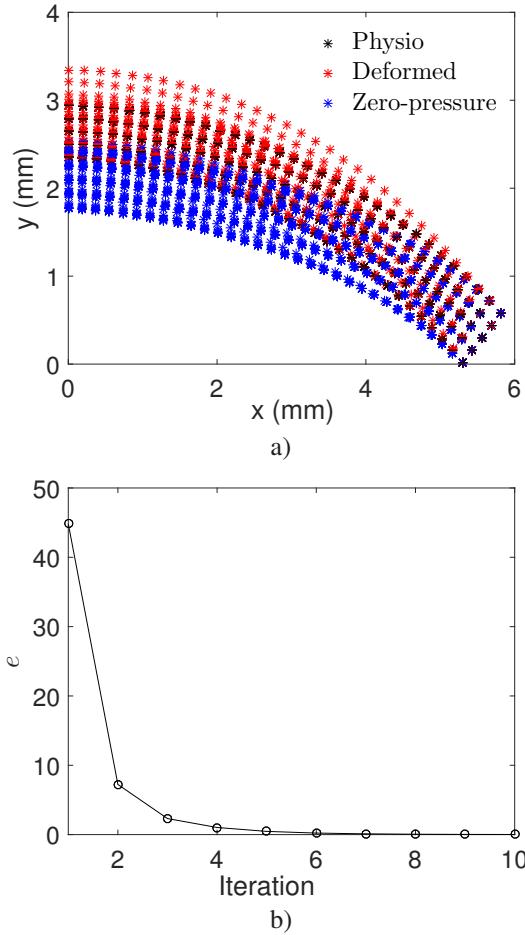


Fig. 6. The zero-pressure algorithm. a) The side view of the converged stress-free configuration. b) The convergence plot.

4.3 Comparison

We consider six different collagen fibril distributions, i.e., transversely isotropic (T.I.), perfect alignment (P.A.), isotropic (I.), planar dispersion (P.D.), planar isotropic (P.I.), and full-thickness variation (F.V.) in our simulation, which are based on material parameters given in Table 1. The parameters are selected, such that the apical rise - pressure curves of both F.V. and T.I. fall onto the experimental data as close as possible (see Figure 9a). The other four cases are simulated using their respective dispersion parameters while keeping mechanical parameters unchanged.

We compare the contours of Von-Mises stress among all cases under internal pressure of $P = 100$ mmHg (see Figure 7). For the cases of T.I., P.A., and P.D., the contours share a similar pattern – a cross mark in the central region – indicating that the collagen fibrils along N-T and I-S directions are under tension. In the case of F.V., the Von-Mises stress

is much lower at the anterior surface. It is because collagen fibrils near the posterior surface are almost perfectly aligned, making them exhibit an earlier stretch-locking than the collagen fibrils at the anterior surface. In the cases of I. and P.I., no significant stretching of the collagen fibrils is observed.

Echoing the main focus of the current study – modeling structural variation in collagen fibrils across the corneal thickness – we plot in Figure 8 the side view of the same Von-Mises stress contour. The F.V. case could predict a reasonable stress profile across the thickness that is in line with the observed collagen fibril distribution in SHG images. On the other hand, the stress is found to be more concentrated at the anterior surface in the cases of T.I., P.A., and P.D. There is no apparent stress gradient across the thickness in the cases of I. and P.I.

In Figure 9a, the simulated apical rise - pressure curves are plotted as lines, while the experimental data obtained from Anderson et al. [37] are plotted as circles. The cases of T.I. and F.V. can capture the experimental results quite well. The case of P.A. exhibits the earliest stretch-locking behavior, while the case of I. shows no fiber engagement under the same boundary conditions. Interestingly, for planar cases of P.D. and P.I., the collagen fibrils exhibit a relatively earlier stretch-locking behavior caused by the narrower dispersion space.

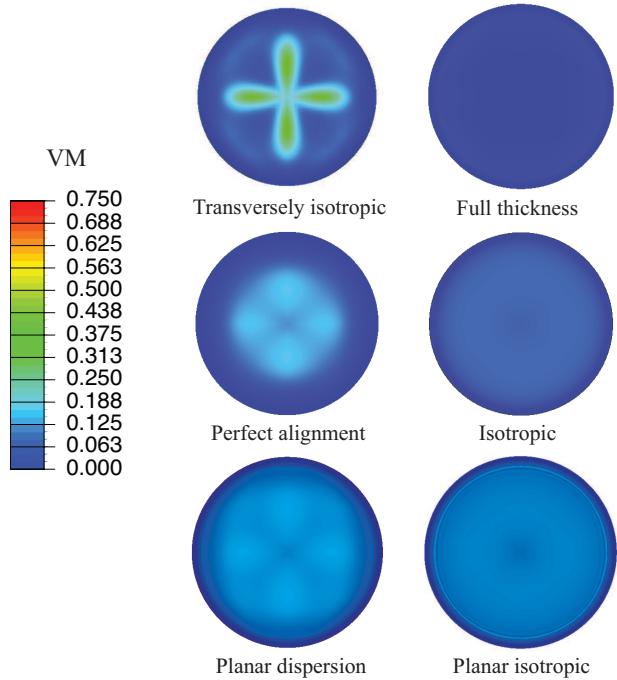


Fig. 7. The distribution of Von-Mises stress (MPa) for six different cases at an internal pressure of $P = 100$ mmHg.

4.4 Parametric study

Here we investigate the influence of decay rate constant γ_d on the mechanical response of corneal stroma under in-

Table 1. Material parameters used in the simulation

	T.I.	P.A.	I.	P.D.	P.I.	F.V.
G_0 (MPa)	0.06	0.06	0.06	0.06	0.06	0.06
K (MPa)	5.5	5.5	5.5	5.5	5.5	5.5
k_1 (kPa)	20	20	20	20	20	0.5
k_2 (-)	400	400	400	400	400	900
κ	[24]	0	1/3	N/A	N/A	N/A
κ_{ip}	N/A	N/A	N/A	Figure 5a	1/2	Figure 5a
κ_{op}	N/A	N/A	N/A	1/2	1/2	Figure 5b
γ_d	N/A	N/A	N/A	N/A	N/A	2.5

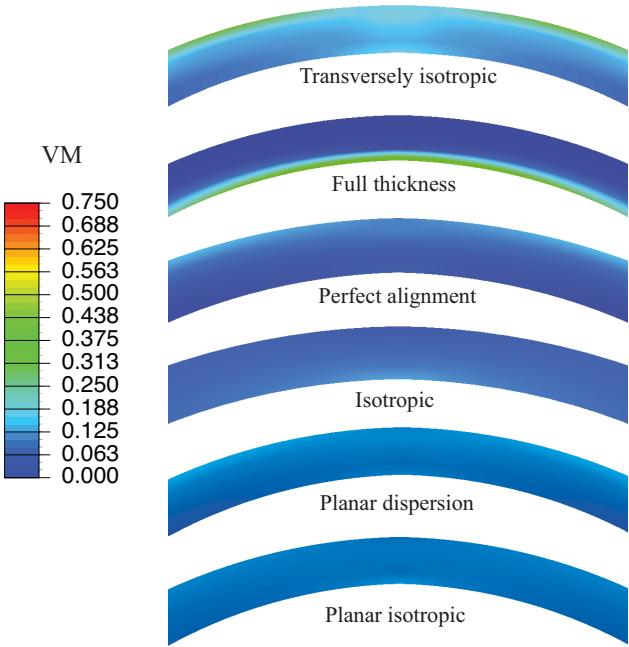


Fig. 8. The through-thickness distribution of Von-Mises stress (MPa) for six different cases at an internal pressure of $P = 100$ mmHg.

flation. Figure 9b compares the apical rise - pressure curves under different values of γ_d . It is seen that the “stretch locking” behavior occurs earlier as γ_d increases. It is because a large fraction of collagen fibrils with the narrower out-of-plane dispersion is engaged in the deformation. The case with $\gamma_d = 2.5$ has a good agreement with the experimental results. More interestingly, as Figure 10 shows, the spots of high-stress concentration move from the posterior to the anterior side as γ_d increases. This result could be useful in terms of predicting the location of the highest stress across the thickness with the known collagen fibril architecture.

4.5 Numerical expensiveness

In this section, we compare the proposed model against a recent AI model [26], in which the collagen fibril free energy is obtained from the angular integration over the unit

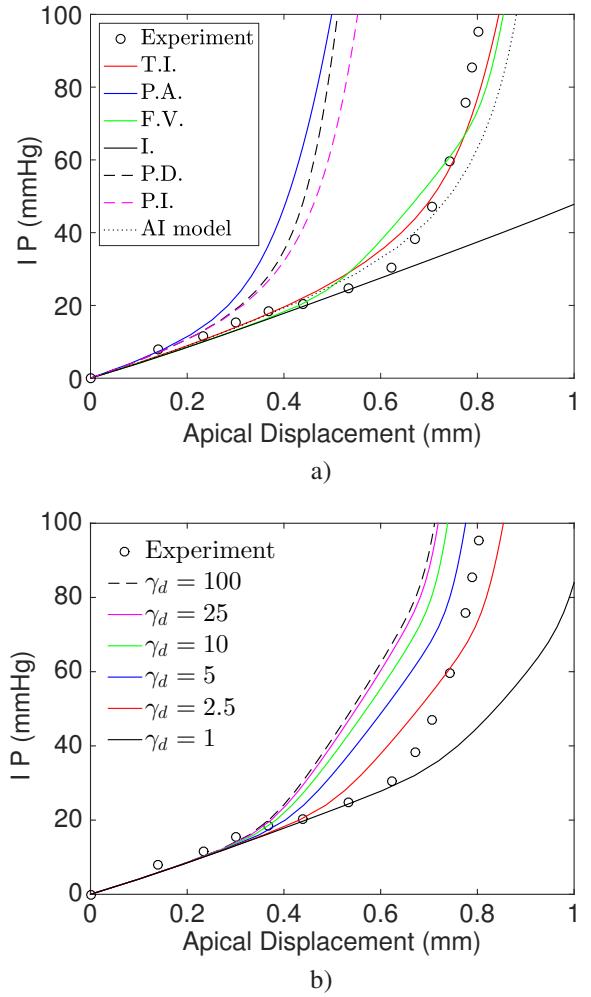


Fig. 9. The apical rise - pressure curves. a) The comparison between experimental data and six different numerical cases of the present work, b) the effects of the exponential decay parameter γ_d on the numerically obtained apical rise - pressure curves.

sphere Ω ,

$$\psi_{\text{R}}^{\text{AI}} = \psi_{\text{R}}^{\text{m}} + \frac{1}{m} \int_{\Omega} \rho(\mathbf{a}_0) w(\lambda_f) d\Omega \quad (26)$$

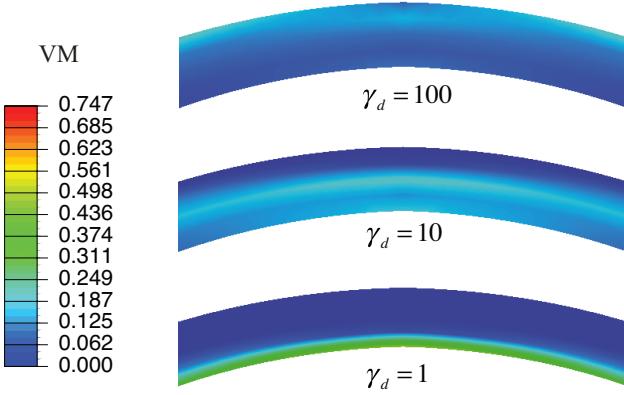


Fig. 10. The effect of different decay rate values constant γ_d on the distribution of Von-Mises stress (MPa) across corneal thickness at $P = 100$ mmHg.

with $d\Omega = \sin\Phi d\Phi d\Theta$ denotes the differential unit sphere, \mathbf{a}_0 denotes the referential collagen fibril orientation, ψ_r^m denotes the matrix free energy, and w denotes the collagen fibril strain energy, which is a function of fiber stretch λ_f . The integral in equation (26) is normalized by $m = \int_{\Omega} \rho(\mathbf{a}_0) d\Omega$. We implement the AI model numerically in Abaqus/Standard [36] by writing UMAT. The simulated apical rise - pressure curve using the AI model, is shown in Figure 9a as the dotted black line, which shows a good agreement with the experimental data. The CPU elapsed time of simulations under the different number of unconstrained degrees of freedom n_{dof} is recorded. It is found that the CPU elapsed time ratio between the two models $t_{\text{AI}}/t_{\text{GST}}$ is proportional to the number of unconstrained degrees of freedom n_{dof} (see Figure 11). Since the double angular integration in equation (26) is evaluated by the Gaussian quadrature scheme, the number of Gauss points has a significant impact on the numerical expensiveness, where the time ratio is nearly 100 at $n_{\text{dof}} = 140$ by using 64 Gauss points. Overall, the proposed model has almost the same feature as the AI one, but it is cheaper in terms of the simulation cost.

5 Concluding remarks

This work develops a continuum mechanics model considering collagen fibril out-of-plane dispersion across the corneal thickness. In particular, the function that links the out-of-plane dispersion parameter to the corneal thickness serves as one of the important contributions of the current work. The proposed model is numerically implemented, and its capabilities are demonstrated by performing numerical simulations of inflation experiments using six different collagen fibril orientations, i.e., transversely isotropic, isotropic, perfect alignment, planar dispersion, planar isotropic, and full-thickness variation.

The results show that the proposed model can replicate the experimental pressure displacement curves very well. It also predicts a reasonable stress profile across the corneal thickness. A parametric study on the decay rate constant in-

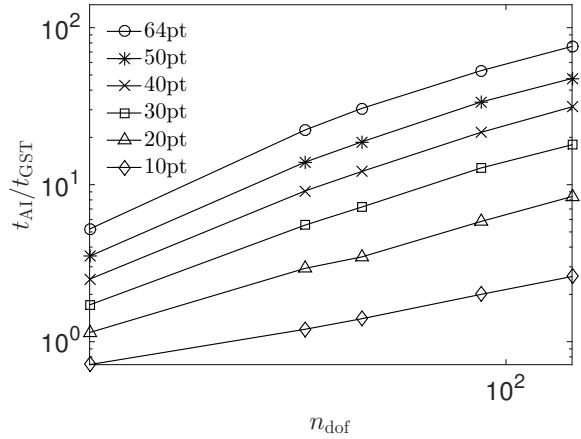


Fig. 11. CPU elapsed time ratio between AI and GST approach $t_{\text{AI}}/t_{\text{GST}}$ as a function of the total numbers of unconstrained degrees of freedoms n_{dof} . The effects of Gauss points have also been investigated.

dicates that the stress profile across the thickness is sensitive to the collagen fibril out-of-plane dispersion. From the perspective of computational expenses, compared to a recent AI model [26], the performance of the proposed model stands out because while it requires much less computational power, it has almost the same functionality.

Looking towards the future, more work yet remains. For example, the model could be strengthened by incorporating more detailed collagen fibril structural information – the interactions between collagen fibril layers. The model could also be extended by adding dissipative mechanisms such as viscoelasticity and considering the corneal gel-like behavior – poroelasticity and fluid migration [45, 46].

Acknowledgements

The authors acknowledge the support in part by the Grant 1635290 from the National Science Foundation, the division of Civil, Mechanical, and Manufacturing Innovation.

A Appendix: Verification of finite element implementation

To verify the numerical implementations, we compare our simulated results with the analytically tractable solutions. We prescribe a simple shear motion to a matrix cube embedded with a family of collagen fibril with a mean direction of $\mathbf{a}_0^4 = [a_x, a_y, 0]^T$ and an out-of-plane direction of $\mathbf{a}_n = [-a_y, a_x, 0]^T$ (see Figure 12a). To make sure they are unit vectors, the condition of $\sqrt{a_x^2 + a_y^2} = 1$ has to be fulfilled. According to Gurtin [47], the simple shear deforma-

tion is given by

$$[\mathbf{F}] = \begin{bmatrix} 1 & \gamma & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad [\mathbf{B}] = \begin{bmatrix} 1 + \gamma^2 & \gamma & 0 \\ \gamma & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad (27)$$

$$[\mathbf{C}] = \begin{bmatrix} 1 & \gamma & 0 \\ \gamma & \gamma^2 + 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

with $\gamma = \tan\theta$ denotes the amount of shear. Referring to equation (5), the generalized structure tensor is given by

$$[\mathbf{H}] = \begin{bmatrix} A + Ba_x^2 + Ca_y^2 & Da_x a_y & 0 \\ Da_x a_y & A + Ba_y^2 + Ca_x^2 & 0 \\ 0 & 0 & A \end{bmatrix} \quad (28)$$

with $C = 1 - 3A - B$ and $D = 2B + 3A - 1$. Next, the generalized invariant in equation (13) is now given by

$$I_4^* = 2A + Ba_x^2 + Ca_y^2 + 2Da_x a_y \gamma + (A + Ba_y^2 + Ca_x^2)(\gamma^2 + 1). \quad (29)$$

Since the simple shear deformation is a volume preserved motion (i.e., $J = 1$), the Cauchy stress in equation (14) could be written as

$$\mathbf{T} = G_0 \mathbf{B} + 2[k_1(I_4^* - 1) \exp(k_2(I_4^* - 1)^2)] [\mathbf{F} \mathbf{H} \mathbf{F}^\top] + P \mathbf{1}, \quad (30)$$

where P is a constitutively indeterminate pressure that is introduced to satisfy the incompressibility constraint. On the numerical side, a single element (U3D8) in Abaqus/Standard [36] is prescribed with the same deformation. We also take $K = 10^3 G_0$ to secure a nearly incompressible condition in the simulations.

Figure 12b compares the analytical solutions against the numerical solutions for the shear stress given by

$$T_{12} = G_0 \gamma + 2[k_1(I_4^* - 1) \exp(k_2(I_4^* - 1)^2)] [\alpha + \beta \gamma], \quad (31)$$

where two constants are $\alpha = (2B + 3A - 1)a_x a_y$ and $\beta = A + Ba_y^2 + (1 - 3A - B)a_x^2$, respectively. The stress is normalized by the matrix shear modulus G_0 , and three different combinations of dispersion parameters are considered. The excellent agreement between the numerical and analytical solutions suggests that our numerical implementation is fully verified.

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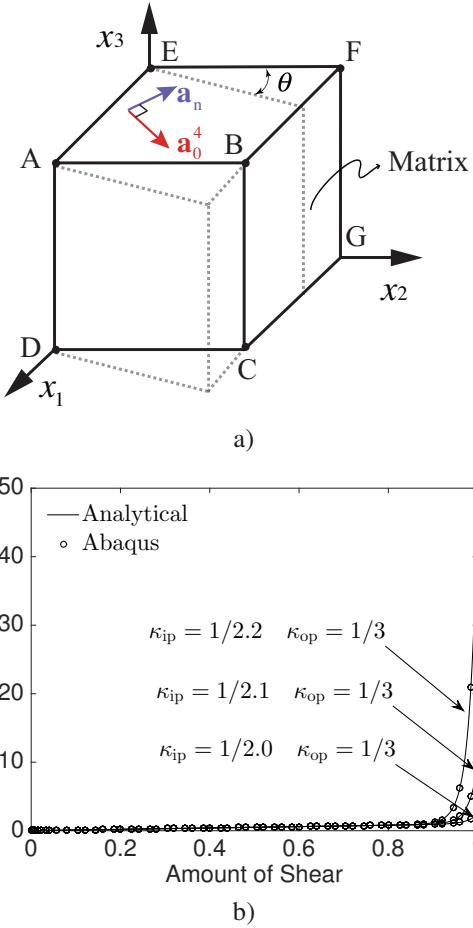


Fig. 12. Verification of our numerical implementation. a) The schematics of a matrix cube embedded with a family of collagen fibrils with a mean direction of $\mathbf{a}_0^4 = [1, 1, 0]^\top$ and an out-plane direction of $\mathbf{a}_n = [-1, 1, 0]^\top$ undergone the simple shear motion. b) Comparison between analytical solutions and numerical solutions; three different combinations of dispersion parameters were used.

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