



Non-Neutralized Electric Current of Active Regions Explained as a Projection Effect

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Abstract Active regions (ARs) often possess an observed net electric current in a single magnetic polarity. We show that such “non-neutralized” currents can arise from a geometric projection effect when a twisted flux tube obliquely intersects the photosphere. To this end, we emulate surface maps of an emerging AR by sampling horizontal slices of a semi-torus flux tube at various heights. Although the tube has no net toroidal current, its *poloidal* current, when projected along the *vertical* direction, amounts to a significant non-neutralized component on the surface. If the tube emerges only partially as in realistic settings, the non-neutralized current will 1) develop as double ribbons near the sheared polarity inversion line, (2) positively correlate with the twist, and 3) reach its maximum before the magnetic flux. The projection effect may be important to the photospheric current distribution, in particular during the early stages of flux emergence.

Keywords Active regions, magnetic fields · Electric currents and current sheets · Magnetic fields, models · Magnetic fields, photosphere

1. Introduction

1.1. Definitions of Current Neutralization

Magnetic field in the solar interior is believed to exist in a “fibril” state: isolated flux tubes generated from dynamo actions are embedded in a relatively field-free background (Fan, 2009). Strong field strength and twist keep the tubes coherent against vigorous convection (Schüssler, 1979). This places an interesting constraint on the net electric current I . Using

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Ampère's law and Stokes' theorem, we have

$$\begin{aligned} \mathbf{j} &= \nabla \times \mathbf{B}, \\ I &= \int_C \mathbf{j} \cdot \hat{\mathbf{n}} \, dA = \oint_{\partial C} \mathbf{B} \cdot d\mathbf{l}, \end{aligned} \quad (1)$$

where $\mathbf{j}$ is the electric current density, $\mathbf{B}$ is the magnetic field, A is an area on the tube cross section, $\hat{\mathbf{n}}$ is its unit normal vector, C is any surface with area $A = \int_C dA$, ∂C is the perimeter of C , and $\mathbf{l}$ is its tangent vector. For simplicity, we assume unity magnetic permeability. Suppose a magnetic flux tube is compact in space. More specifically, there is a closed loop ∂C such that $\mathbf{B} = 0$ all along the loop. This shows that a compact flux tube has $I = 0$, i.e. it is current-neutralized.

The argument implies *neutralized* electric currents in the axial direction. For a tube with coherent twist, $\mathbf{j}$ near the tube center will point in one direction when projected onto the axis. Conversely, $\mathbf{j}$ in the tube periphery must point in the opposite direction, forming a sheath or a skin layer. The former is termed the “direct current” (DC), and the latter the “return current” (RC; e.g., Melrose, 1995). The flux tube is “current-neutralized” when DC and RC add to zero.

Solar active regions (ARs), formed through emergence of subsurface flux tubes, are known to harbor electric currents in the corona. In many cases, their sheared or sigmoidal loops are incompatible with a current-free, potential field morphology. Moreover, they must contain sufficient free energy to power flares and coronal mass ejections (CMEs). This picture is quite different from the convection zone. Here, the magnetic field is volume-filling and dominates the plasma dynamics.

In the thin layer of the photosphere, the plasma density and pressure decrease rapidly with height; the magnetic field begins to transition from a fibril to a volume-filling state. Maps of the photospheric $\mathbf{B}$, magnetograms, are routinely inferred from spectropolarimetric observations. Assuming a local Cartesian geometry and the photosphere as a thin boundary at $z = 0$, the *vertical* current density j_z and the net current I_z can be estimated from the horizontal field component $\mathbf{B}_h$, similar to Equation (1):

$$\begin{aligned} j_z &= \nabla \times \mathbf{B}_h, \\ I_z &= \int_C j_z \, dA = \oint_{\partial C} \mathbf{B}_h \cdot d\mathbf{l}, \end{aligned} \quad (2)$$

where C is now a finite area lying entirely on $z = 0$.

For an isolated, spatially compact sunspot, there exists a closed loop ∂C lying on $z = 0$ that surrounds the sunspot such that $\mathbf{B}(z = 0) = 0$. This implies $I_z = 0$. That is, all currents that enter the photosphere must return to the convection zone, i.e., they are “balanced”. In practice, however, this is not how net currents are measured for observed ARs. First of all, sunspots are rarely completely isolated. Furthermore, eruptive ARs tend to harbor sunspots of opposite polarities in close proximity. To measure the net current, standard practice is to take C as the contiguous area of a magnetic polarity partially bounded by the polarity inversion line (PIL; i.e. $B_z = 0$). Figure 1(a) of Török et al. (2014) shows a good example. DC and RC are expected to reside in the core region and the periphery, respectively.

1.2. Non-Neutralized Currents in ARs

Ground-based vector magnetograms provided early evidence for non-neutralized currents in the AR photosphere. Leka et al. (1996) followed the evolution of an emerging AR over

several days. A significant net current appears in each magnetic polarity, whose increase cannot be explained by the shearing flows in the photosphere alone and must be carried by the emerging flux. Wheatland (2000) analyzed a sample of 21 ARs. In most cases, the net current for the entire AR is consistent with zero. Within each magnetic polarity, however, it is significantly different from zero.

Using high-resolution vector magnetograms from the Spectropolarimeter (SP) on board the *Hinode* satellite, Ravindra et al. (2011) and Georgoulis, Titov, and Mikić (2012) found that the non-neutralized currents are always accompanied by well-formed, sheared PILs. Meanwhile, Venkatakrishnan and Tiwari (2009) and Gosain, Démoulin, and López Fuentes (2014) found isolated sunspots without a sheared PIL to be well neutralized. This is a natural consequence of Equation (2): the sheared component of $\mathbf{B}_h$ along the PIL should contribute significantly to the line integral around a single magnetic polarity.

The current distribution has perceived important implications on solar eruption. Many CME models employ DC-dominated flux ropes as the driver (e.g., Titov and Démoulin, 1999). The inclusion of RC will reduce the outward magnetic “hoop force” that drives the eruption (Forbes, 2010). Observationally, non-neutralized currents indeed correlate with eruptive activities. Liu et al. (2017), Vemareddy (2019), and Avallone and Sun (2020) compared ARs with and without major eruptions using data from the Helioseismic and Magnetic Imager (HMI) aboard the *Solar Dynamics Observatory* (SDO). The quiescent ARs are mostly current-neutralized, while the active ones are not. Falconer (2001) and Kontogiannis et al. (2019) demonstrated the net current as a useful index for space weather predictions.

The origin of the non-neutralized current in ARs is not entirely clear. If flux emergence is responsible, it must explain how it can arise from a current-neutralized subsurface flux tube. Longcope and Welsch (2000) proposed an analytical model where only a fraction of the current passes into the corona. The rest, including most of the weaker RC, is shunted to the surface layers and hidden from the observer. Török et al. (2014) demonstrated a similar effect using the magnetohydrodynamic (MHD) simulation from Leake, Linton, and Török (2013). As a subsurface, neutralized flux tube emerges, non-neutralized current develops simultaneously with the flux emergence and PIL shear. The degree of non-neutralization becomes more pronounced in higher layers as RC remains trapped in lower ones.

Shear and vortex surface flows are often used to induce coronal electric currents in MHD models. Török and Kliem (2003) and Dalmasse et al. (2015) showed that different photospheric line-tied motions can generate different degrees of current-neutralization. Only motions that directly shear the PIL will generate a non-neutralized component. Simulations by Fan (2001) and Manchester et al. (2004) showed that the shear flows on the PIL are driven by the magnetic tension force during flux emergence, which comes from the twisted tube itself as it expands in the corona.

1.3. Outline

Here we explore an alternative origin of the observed, non-neutralized electric current in emerging ARs. Using an analytical flux rope model, we show that a neutralized subsurface flux tube can lead to a significant non-neutralized vertical current on the surface due to a geometric projection effect.

We described two versions current-neutralization in Section 1.1: one in the context of the subsurface flux tube itself, and the other in the context of the photospheric observation. As we shall see, they refer to different components of the current system when the tube axis obliquely intersects the surface. Such a distinction is seldom discussed in the literature, but is central to this work.

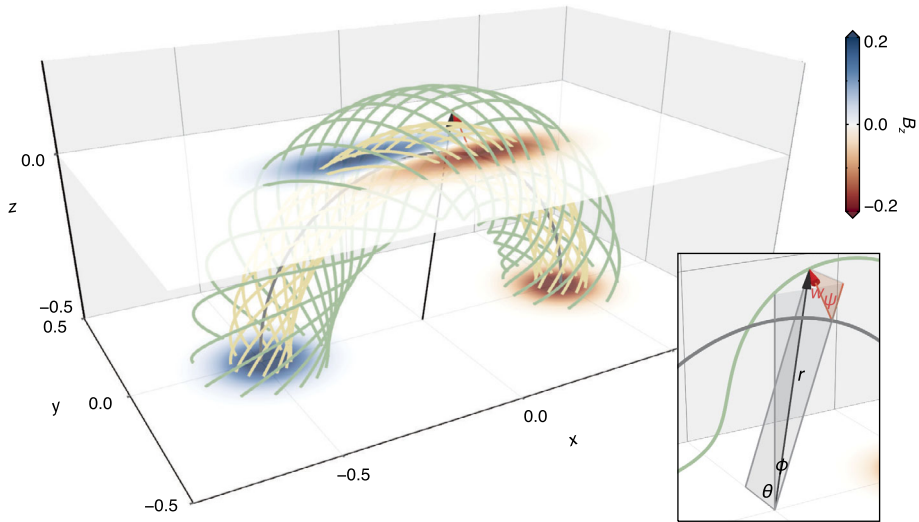


Figure 1 Magnetic field of a partially emerged FG03 flux tube ($R = 0.5$, $a = 0.12$, $q = 0.8$, $h = -0.5$). The tube axis (dark gray curve) just starts to touch the photosphere at $z = 0$. Maps on two horizontal slices at $z = -0.5$ and 0 show B_z distribution. Selective field lines are traced from a distance of $w = 0.08$ (yellow) and 0.18 (green) from the tube axis in the $x = 0$ plane. They are located within the DC core and RC sheath, respectively. The black and red arrows show the radial vector for an arbitrary point in the spherical and torus coordinate system, respectively (see the appendix). The inset illustrates the spherical coordinate (r, θ, ϕ) , and the torus coordinate (w, ψ, ϕ) . The poloidal angle ψ here is negative.

Below, we describe the flux tube model in Section 2, present our results in Section 3, and discuss the implications in Section 4. Additional details of the flux tube model are available in the appendix.

2. Flux Tube Model

2.1. Model Setup

We consider a twisted, semi-torus flux tube model from Fan and Gibson (2003, hereafter FG03). In a global Cartesian coordinate with unit vectors $(\hat{x}, \hat{y}, \hat{z})$, the subsurface tube is centered at $(0, 0, h)$, where $h < 0$ (Figure 1).

The semi-torus tube axis has a radius of R ; it is axisymmetric with a polar axis parallel to $\hat{y}$. In a local spherical coordinate centered at $\mathbf{r}_0$ with unit vector $(\hat{r}, \hat{\theta}, \hat{\phi})$, the magnetic field $\mathbf{B}$ inside the tube is defined as

$$\mathbf{B} = \nabla \times \left[\frac{A(r, \theta)}{r \sin \theta} \hat{\phi} \right] + B_\phi(r, \theta) \hat{\phi}, \quad (3)$$

where

$$\begin{aligned} A(r, \theta) &= \frac{qa^2 B_t}{2} \exp(-w^2/a^2), \\ B_\phi(r, \theta) &= \frac{a B_t}{r \sin \theta} \exp(-w^2/a^2). \end{aligned} \quad (4)$$

Here, r is the radial distance from the origin; θ is the polar angle from the polar axis; ϕ is the azimuth angle where 0 is along $+z$ and increases clockwise toward $+x$ ($-\pi/2 \leq \theta, \phi \leq \pi/2$). Moreover, w is the distance from the tube axis. B_t , q , and a are constants: B_t is the characteristic field strength; q is a measure of the twist; a is the characteristic length scale for the tube radius. Field lines near the tube axis wind about the axis at a rate of q/a per unit length. We truncate $\mathbf{B}$ to 0 outside the surface $w = 3a$. The tube is thus isolated with a circular cross section and a radius of $3a$. Detailed expressions of $\mathbf{B}$ and $\mathbf{j}$ in various coordinate systems are available in the appendix.

In this work, we consider the following default parameters: $B_t = 1.0$, $R = 0.5$, and $a = 0.12$. Additionally, we limit ourselves to the cases where $q > 0$, such that the flux tube has a right-handed twist.

To emulate flux emergence, we displace the flux tube upward by increasing h toward zero, and evaluate $\mathbf{B}$ and $\mathbf{j}$ on the horizontal slices $z = 0$. This is equivalent to sampling the variables at different heights if the flux tube is fixed in space. The process is demarcated by several key values of h :

- (i) The emergence starts at $h = -(R + 3a) = -0.86$.
- (ii) The axis of the tube reaches the surface at $h = -R = -0.5$.
- (iii) The crest of the tube detaches from the surface at $h = -(R - 3a) = -0.14$.
- (iv) The emergence ends at $h = 0$.

In [FG03](#), the tube field at $z = 0$ was used to prescribe a time-dependent boundary condition that drives the coronal dynamics. Here, we focus solely on the layer $z = 0$ as a proxy of the photospheric observations, ignoring any coronal evolution or its feedback. This approach has been used to help interpret the emerging non-potential field structure observed in the photosphere with success (Lites et al., 1995; Luoni et al., 2011).

2.2. Poloidal-Toroidal Decomposition

The axial direction of a torus is known as the *toroidal* direction, which is just $\hat{\phi}$ in our spherical coordinate. The non-axial direction, on the other hand, includes both $\hat{r}$ and $\hat{\theta}$. We may define a torus coordinate where a non-axial vector can be decomposed into radial and *poloidal* components (see [Figure 1](#) and the appendix). In a constant ϕ plane, the former directs away from the tube axis, while the latter follows a circle around the tube axis.

We show in the appendix that the non-axial $\mathbf{B}$ and $\mathbf{j}$ in the [FG03](#) flux tube are purely poloidal. Using the subscript P (T) to denote the poloidal (toroidal) components, we have in spherical coordinate

$$\mathbf{B}_P = B_r \hat{r} + B_\theta \hat{\theta}, \quad (5)$$

$$\begin{aligned} \mathbf{B}_T &= B_\phi \hat{\phi}, \\ \mathbf{j}_P &= j_r \hat{r} + j_\theta \hat{\theta}, \\ \mathbf{j}_T &= j_\phi \hat{\phi}. \end{aligned} \quad (6)$$

Their respective contributions to the surface observation vary at different stages of the flux emergence, when the tube axis intersects the surface at different angles. In particular, the projected values in the vertical direction can be evaluated by taking the dot product with $\hat{z}$, e.g., $\mathbf{B}_P \cdot \hat{z}$.

2.3. Two Versions of Current Neutralization

Considering the flux tube by itself, we define DC and RC as components of the net toroidal current. For $q > 0$, DC (RC) refers to the net current for $j_\phi > 0$ ($j_\phi < 0$). We denote the total DC as I_T^D , the total RC as I_T^R , and the net toroidal current I_T . We can evaluate them by integrating j_ϕ on a cross section $\phi = 0$:

$$\begin{aligned} I_T^D &= \int_{\phi=0} j_\phi|_{j_\phi>0} dA, \\ I_T^R &= \int_{\phi=0} j_\phi|_{j_\phi<0} dA, \\ I_T &= I_T^D + I_T^R. \end{aligned} \quad (7)$$

For a photospheric vector magnetogram, we denote the total DC in a single magnetic polarity as I_z^D , the total RC as I_z^R , and the net vertical current I_z . For $q > 0$, we can evaluate them by integrating j_z on $z = 0$ where $B_z > 0$:

$$\begin{aligned} I_z^D &= \int_{z=0; B_z>0} j_z|_{j_z>0} dA, \\ I_z^R &= \int_{z=0; B_z>0} j_z|_{j_z<0} dA, \\ I_z &= I_z^D + I_z^R. \end{aligned} \quad (8)$$

We can separately evaluate the projected poloidal and toroidal contribution by integrating $\mathbf{j}_P \cdot \hat{\mathbf{z}}$ and $\mathbf{j}_T \cdot \hat{\mathbf{z}}$ instead of j_z .

The degree of current-neutralization are often quantified by the relative magnitude of DC versus RC. In this study, we use the index

$$R_T = \left| \frac{I_T^D}{I_T^R} \right| \quad (9)$$

for the toroidal current and

$$R_z = \left| \frac{I_z^D}{I_z^R} \right| \quad (10)$$

for the observed vertical current (e.g., Liu et al., 2017; Avallone and Sun, 2020). We will show that a geometric projection effect is capable of producing large I_z and R_z from a flux tube with small I_T and unity R_T .

3. Result

3.1. Flux Tube Cross Section

For our fiducial case with $q = 0.8$, the toroidal current density on the tube cross section features a compact DC core and a diffuse RC sheath (Figure 2(a)). Though not strictly axisymmetric because of the bending of the flux tube axis, the sign change occurs near the radius $w \approx a = 0.12$ (Equation (16)). The net toroidal current integrated within w peaks at

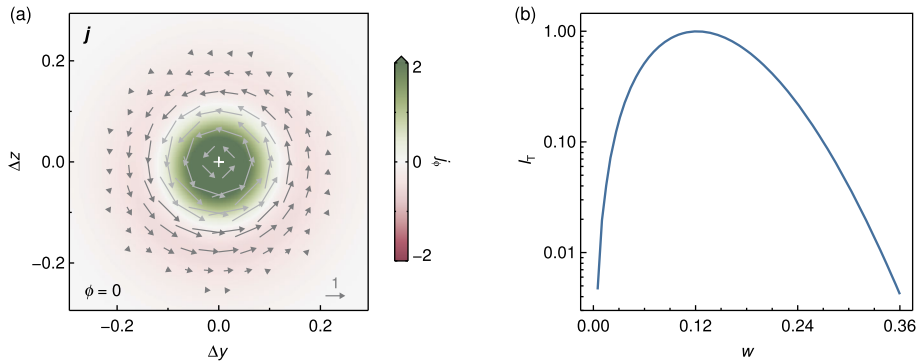


Figure 2 Electric current system on a tube cross section ($q = 0.8$, $\phi = 0$). **(a)** Distribution of $\mathbf{j}$ near the tube axis. The background color shows the toroidal current density j_T ; the arrows show poloidal current density vectors $\mathbf{j}_P$. The tube axis is marked with a cross. The coordinate $(\Delta y, \Delta z)$ indicates the offset from the tube axis in y and z direction. **(b)** Net toroidal current I_T within a tube radius w , normalized by I_T^D of the entire tube.

$w = 0.12$ due to the contribution from DC core. It becomes quite neutralized once the RC sheath is included (Figure 2(b)). For the entire tube $w = 3a = 0.36$, there is $I_T = 0.004I_T^D$ and $R_T = 1.004$. Because I_T^D and I_T^R both linearly scale with q , R_T is independent of the twist.

In contrast, the poloidal current density has a single sign, rotating counter-clockwise around the axis in the same direction as the poloidal field (Equation (21); Figure 2(a)). Its magnitude is independent of q by construct, and is comparable to the toroidal current density for $q = 0.8$.

3.2. Synthetic Surface Observations

The vertical magnetic field B_z shows two elongated polarities when the crest of the tube intersects the surface (Figure 3(a)). These are known observationally as “magnetic tongues”, which are a manifestation of the magnetic twist (López Fuentes et al., 2000). As h increases, the tongues retract and transition into two circles, which correspond to the two legs of the flux tube (Figure 3(b)–(c)). The poloidal and toroidal contributions to the vertical field are more important in the early and late stages, respectively (Figure 3(d)–(i)).

The vertical current density j_z shows two elongated, ribbon-shaped polarities early on (Figure 4(a)). They mainly arise from the projected poloidal component (Figure 4(d)). For $q = 0.8$, j_z is mostly positive in the positive magnetic polarity, so DC dominates. As the tube continues to rise, the RC sheath becomes visible on the surface, and the j_z distribution starts to resemble j_ϕ on the tube cross section (Figure 4(g)–(i)).

For $q = 0.8$, the surface vertical current is highly non-neutralized when the axis just starts to emerge ($h = -R$). I_z and R_z peak at $h = -0.44$ and -0.50 , with a maximum of $I_z = 2.6I_T^D$ and $R_z = 8.8$, respectively (Figure 5(a)–(b)). The dominance of DC is clearly owing to the poloidal contribution (Figure 5(c)). At $h = -0.5$, the contribution of the poloidal component in I_z is about 18 times that of the toroidal counterpart.

To evaluate the general properties of the model, we consider two additional cases for $q = 0.2$ and 0.5 . Several notable features are as follows.

Patterns in surface map.—For $h = -0.5$, the j_z and B_z polarities become better aligned as q increases (Figure 6). This is an interesting feature of the FG03 flux tube, where j_P

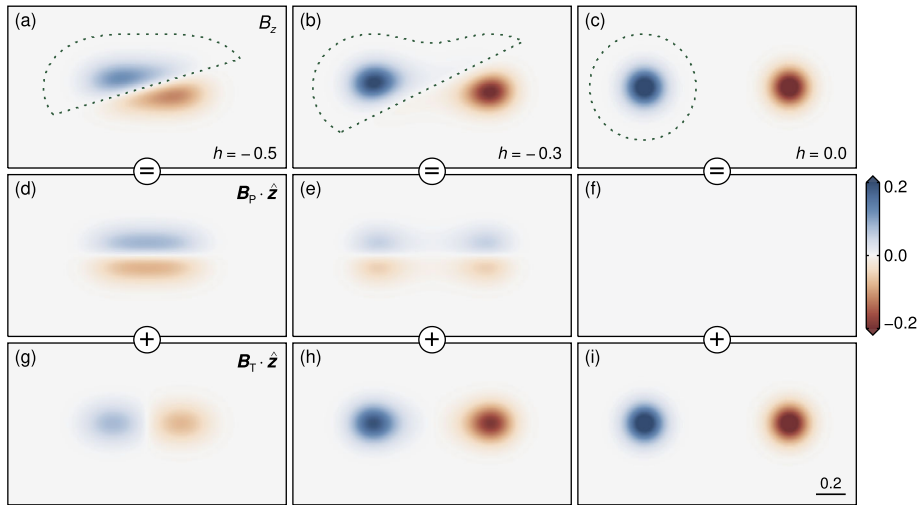


Figure 3 Surface magnetic maps ($q = 0.8$, $z = 0$). (a)–(c) Vertical magnetic field B_z when the tube is centered at $h = -0.5$, -0.3 , and 0 , respectively. Dotted curves indicate regions where $B_z > 0$. (d)–(f) Contribution from the poloidal field $\mathbf{B}_P \cdot \hat{\mathbf{z}}$. (g)–(i) Contribution from the toroidal field $\mathbf{B}_T \cdot \hat{\mathbf{z}}$. The top row is the sum of the middle and bottom rows. For corresponding current density maps; see Figure 4.

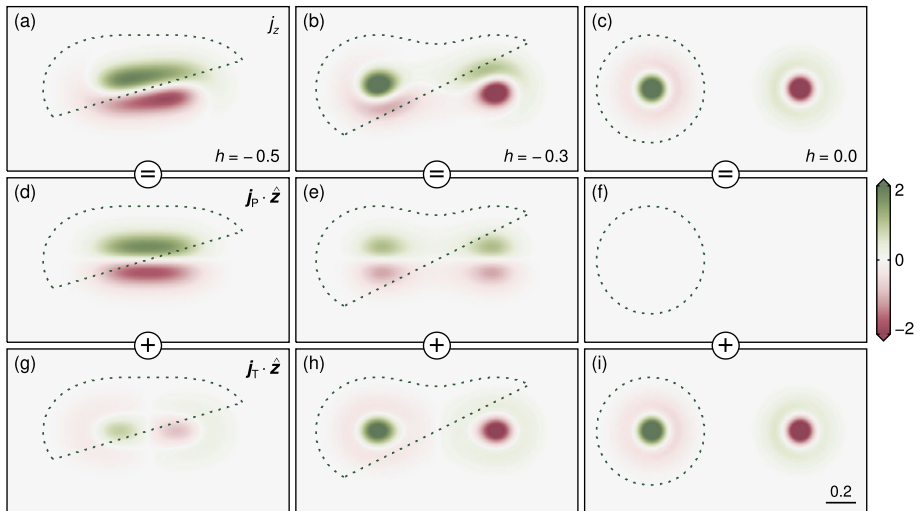


Figure 4 Surface current density maps ($q = 0.8$, $z = 0$). (a)–(c) Vertical electric current density j_z when the tube is centered at $h = -0.5$, -0.3 , and 0 , respectively. (d)–(f) Contribution from the poloidal current $\mathbf{j}_P \cdot \hat{\mathbf{z}}$. (g)–(i) Contribution from the toroidal current $\mathbf{j}_T \cdot \hat{\mathbf{z}}$. Dotted curves indicate regions where $B_z > 0$. The top row is the sum of the middle and bottom rows.

and $\mathbf{B}_P$ depend differently on q . The predominant poloidal current contribution $\mathbf{j}_P \cdot \hat{\mathbf{z}}$ is independent of q (Equation (23)), whereas the toroidal contribution $\mathbf{j}_T \cdot \hat{\mathbf{z}}$ merely appends a curved tail to the j_z ribbon, creating a “Yin–Yang” pattern. Therefore, the j_z patterns remain almost unchanged with q . Contrarily, the poloidal field contribution $\mathbf{B}_P \cdot \hat{\mathbf{z}}$ linearly scales

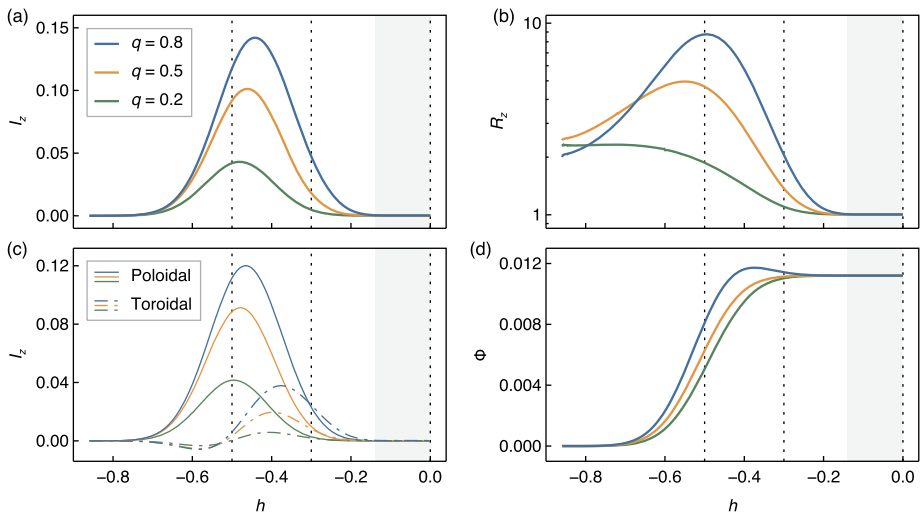


Figure 5 Integrated surface observations for different q . (a) Net current I_z . (b) Ratio between DC and RC R_z . (c) Projected poloidal (thin solid) and toroidal (dash-dotted) components in I_z . (d) Surface magnetic flux Φ ($B_z > 0$ only). Gray bands indicate $h \geq -(R - 3a)$. Dotted lines show the three heights in Figure 4.

with q (Equation (22)). As q increases, the B_z magnetic tongues rotate clockwise to better match the current ribbons. The PIL becomes largely parallel to the j_z ribbons for $q = 0.8$; the horizontal field $\mathbf{B}_h$ is also more sheared. As h increases further, U-shaped field lines in the lower portion of the tube will graze the surface to create “bald patches”, where $\mathbf{B}_h$ on the PIL directs from the negative to the positive side (Titov, Priest, and Demoulin, 1993).

Non-neutralized current vs. twist.—The maximum I_z and R_z both positively correlate with q (Figure 5(a)–(b)). This is because the B_z and j_z polarities become better aligned at higher q : the area occupied by DC increases. The R_z values appear unexpectedly low for $q = 0.8$ early on ($h < -0.8$). We find that the toroidal contribution in I_z is initially negative (Figure 5(c)). This RC component is larger for $q = 0.8$, leading to an overall smaller R_z . It is soon offset by the faster increasing DC component in the poloidal current.

Evolution of current and magnetic flux.—As h increases, I_z and R_z initially increase along with the surface magnetic flux Φ (Figure 5(d)). The former peak at $h \approx -R$, when a significant portion of the toroidal magnetic flux is still below the surface. As emergence proceeds, I_z and R_z will decrease due to the toroidal contribution, whereas Φ will continue to increase. For an untwisted flux tube, the maximum Φ is expected to occur at $h = -(R - 3a) = -0.14$, when the crest of the tube fully emerges. Such is the case for both $q = 0.2$ and 0.5 . For $q = 0.8$, however, Φ peaks significant earlier at $h = -0.37$ with a maximum 5% higher than the total toroidal flux. This is owing to the strong poloidal field contribution (Equation (22)). A portion of highly twisted magnetic field lines will intersect the $z = 0$ plane more than two times (Appendix).

We conclude that the observed, non-neutralized vertical current (large I_z and R_z) can arise from a neutralized flux tube (zero I_T and unity R_T) due to the projected poloidal component. The conclusion holds for the early stages of emergence only, when the crest of the tube is partially emerged, and the axis obliquely intersects the surface. For the later stages, the tube axis becomes more perpendicular to the surface. The observed current becomes more neutralized as the toroidal component takes over.

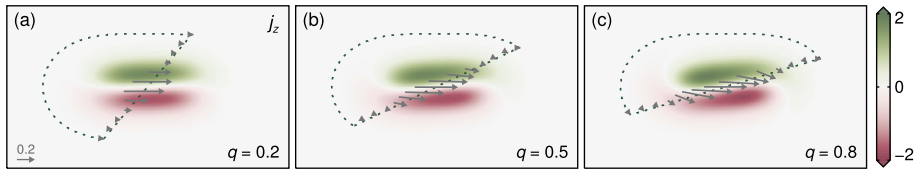


Figure 6 Distribution of j_z at $h = -0.5$, when the apex of the flux rope axis is at the photospheric level. (a)–(c) For $q = 0.2, 0.5$, and 0.8 , respectively. Dotted curves indicate regions where $B_z > 0$. Arrows show B_h on the PIL.

4. Discussion

For an idealized, torus-shaped flux tubes, as long as B_T decreases away from the tube axis, the surface $\mathbf{j}_p \cdot \hat{\mathbf{z}}$ distribution is expected to be bipolar like FG03. Whether the surface current is neutralized will depend on the patterns of $\mathbf{B}_p \cdot \hat{\mathbf{z}}$, which is sensitive to the global magnetic twist (Figure 6). Other conditions being equal, a flux tube with higher twist should possess higher magnetic helicity and free energy, which are known to drive solar eruptions. This, combined with the positive correlation between R_z and q , provides a natural explanation to the increased eruptivity in ARs with significant non-neutralized currents.

We temper our conclusion with some caveats. MHD simulations have shown that it is difficult for a twisted flux tube to rise bodily into the corona (e.g., Fan, 2001; Archontis and Hood, 2010). The concave portions of the field lines are loaded with dense plasma, which prevents the tube axis from rising for more than a few scale heights above the surface. Indeed, the tongue-shaped B_z and j_z polarities (Figures 3(a)) frequently appear in observations (e.g., Poisson et al., 2016) without developing further into two circular polarities. If so, the $h \leq -R$ phase in our model should be more relevant than $h > -R$ in realistic settings. In these early stages of flux emergence, the poloidal component is expected to play a prominent role. We note that counterexamples also exist where the axial flux fully emerges in simulation (e.g., Hood et al., 2009).

In observations, CME-productive ARs frequently exhibit long-lived, narrow DC ribbon pairs that are well aligned with the PIL similar to the $q = 0.8$ case (see, e.g., Figure 1 of Liu et al., 2017 and Figure 3 of Avallone and Sun, 2020). The overall patterns of j_z , however, are filamentary except for the DC ribbons (if present); evidence for a single shell of RC surrounding the DC is also lacking. The observed R_z evolution sometimes show a fast increase with Φ and peaks earlier than Φ (see, e.g., Figure 2 of Vemareddy, 2019 and Figure 3 of Avallone and Sun, 2020). Their absolute values, however, are considerably lower than in our model (Figure 5(b)). The maximum R_z is typically ~ 2 for CME-productive ARs, and at best reaches ~ 4 when the central flux rope structure is largely isolated (Liu et al., 2017).

It is worth mentioning that in ideal MHD, the evolution of $\mathbf{j}$ is fundamentally different from that of $\mathbf{B}$. There is no “frozen-in” theorem for $\mathbf{j}$ so I is not conserved in a flux tube; $\partial \mathbf{j} / \partial t$ will depend not only on the velocity field $\mathbf{v}$ and $\mathbf{j}$ itself, but $\mathbf{B}$ as well (e.g., Invernarity and Titov, 1997). Predicting the behavior of the electric current can be rather difficult without solving the MHD equations for the full system (Parker, 1996).

Our simplistic approach neglects a rich variety of physics during flux emergence. We discuss several possible effects below.

- (i) As the flux tube approaches the surface, it will be flattened into a sheet-like structure due to the diminishing pressure scale height at the top of the convection zone (Spruit,

- Title, and van Ballegooijen, 1987; Cheung et al., 2008). The internal $\mathbf{B}$ and $\mathbf{j}$ distributions will change.
- (ii) The drastic expansion of the emerged flux due to magnetic buoyancy instabilities (Section 3.3 of Cheung and Isobe, 2014) can shunt the RC to the interface layer, as demonstrated by Longcope and Welsch (2000) and Török et al. (2014).
 - (iii) The expansion will also induce a Lorentz force, which drives twist or shear flows on the surface (Longcope and Welsch, 2000; Manchester et al., 2004; Fang et al., 2012a). These flows are capable of producing non-neutralized currents if they act close to the PIL (Dalmasse et al., 2015).
 - (iv) The emerged flux may undergo internal or external reconnection to produce a new flux rope in the corona (Archontis and Török, 2008; Leake, Linton, and Török, 2013; Takasao et al., 2015; Syntelis et al., 2019; Toriumi and Hotta, 2019; Toriumi et al., 2020). This evolution in the magnetic field is reflected in changes of the current distribution.
 - (v) Interactions between different emerging flux regions (e.g. Chintzoglou et al., 2019), and between existing sunspots and newly emerged regions (Fan, 2016; Cheung et al., 2019), are known to cause flares. The foot prints of the reconnecting quasi-separatrix layers (QSLs; e.g., Démoulin, Priest, and Lonie, 1996), demarcated by flare ribbons, often overlap with the pre-flare current ribbons. Observations haven shown that the local j_z can greatly enhance during the eruption (Janvier et al., 2014).
 - (vi) The buffeting effect from the convective flows may fragment the magnetic flux (Cheung et al., 2008; Martínez-Sykora, Hansteen, and Carlsson, 2008; Stein and Nordlund, 2012; Chen, Rempel, and Fan, 2017) and contribute to the filamentary structure of j_z (Yelles Chaouche et al., 2009; Fang et al., 2012b).

Due to these effects, the observed surface $\mathbf{B}$ and $\mathbf{j}$ are unlikely to be identical to those on a subsurface horizontal slice. A distinction between poloidal and toroidal components with respect to their subsurface origin can be difficult in practice. Nevertheless, the simple model here is capable of reproducing several key observational features. The projection effect may be important to the photospheric current distribution, in particular during the early stages of flux emergence.

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Appendix

In [FG03](#), the flux tube is kinematically lifted from subsurface ($z < 0$) at a constant velocity $\mathbf{v}_0 = v_0 \hat{\mathbf{z}}$. As the tube intersects the $z = 0$ plane, its magnetic field $\mathbf{B}_0 = \mathbf{B}(z = 0)$ and $\mathbf{v}_0$ induce an ideal electric field $\mathbf{E} \propto -\mathbf{v}_0 \times \mathbf{B}_0$, which is used as an evolving boundary condition for the domain of interest ($z > 0$). The initial potential field in the $z > 0$ volume interacts with the newly emerged flux, resulting in a sigmoidal flux rope that eventually erupts.

For simplicity, we place the origin at $\mathbf{r}_0 = (0, 0, 0)$ in the Cartesian coordinate (Figure 1). A horizontal slice at $z_0 > 0$ represents the photospheric condition when the tube is centered at a depth of $h = -z_0$.

We define two auxiliary variables: ρ for the projected distance of a point $\mathbf{r}$ to the origin on the $y = 0$ plane, and w for the distance to the tube axis:

$$\begin{aligned}\rho &= (x^2 + z^2)^{1/2}, \\ w &= [(\rho - R)^2 + y^2]^{1/2}.\end{aligned}\quad (11)$$

In our convention, both the Cartesian and the spherical coordinate systems are right-handed (Figure 1). The coordinates (x, y, z) and (r, θ, ϕ) are related by

$$\begin{aligned}x &= r \sin \theta \sin \phi, \\ y &= r \cos \theta, \\ z &= r \sin \theta \cos \phi.\end{aligned}\quad (12)$$

Their unit vectors $(\hat{x}, \hat{y}, \hat{z})$ and $(\hat{r}, \hat{\theta}, \hat{\phi})$ are related by

$$\begin{aligned}\hat{x} &= \sin \theta \sin \phi \hat{r} + \cos \theta \sin \phi \hat{\theta} + \cos \phi \hat{\phi}, \\ \hat{y} &= \cos \theta \hat{r} - \sin \theta \hat{\theta}, \\ \hat{z} &= \sin \theta \cos \phi \hat{r} + \cos \theta \cos \phi \hat{\theta} - \sin \phi \hat{\phi}.\end{aligned}\quad (13)$$

In the spherical coordinate, the three components of the magnetic field $\mathbf{B}$ are

$$\begin{aligned}B_r &= B_t \frac{qR \cos \theta}{r \sin \theta} \exp(-w^2/a^2), \\ B_\theta &= B_t \frac{q(r - R \sin \theta)}{r \sin \theta} \exp(-w^2/a^2), \\ B_\phi &= B_t \frac{a}{r \sin \theta} \exp(-w^2/a^2).\end{aligned}\quad (14)$$

The three Cartesian components are

$$\begin{aligned}B_x &= B_t \frac{qxy + az}{\rho^2} \exp(-w^2/a^2), \\ B_y &= B_t q \frac{R - \rho}{\rho} \exp(-w^2/a^2), \\ B_z &= B_t \frac{qyz - ax}{\rho^2} \exp(-w^2/a^2).\end{aligned}\quad (15)$$

In the spherical coordinate, the three components of the current density $\mathbf{j}$ are

$$\begin{aligned} j_r &= \frac{2B_t R \cos \theta}{a\rho} \exp(-w^2/a^2), \\ j_\theta &= \frac{2B_t(r - R \sin \theta)}{a\rho} \exp(-w^2/a^2), \\ j_\phi &= -\frac{B_t q}{\rho} \left(\frac{2w^2}{a^2} - \frac{R}{\rho} - 1 \right) \exp(-w^2/a^2). \end{aligned} \quad (16)$$

The three Cartesian components are

$$\begin{aligned} j_x &= -\frac{B_t}{\rho^2} \left\{ q \left[\frac{2w^2}{a^2} - \frac{R}{\rho} - 1 \right] z - \frac{2xy}{a} \right\} \exp(-w^2/a^2), \\ j_y &= \frac{2B_t(R - \rho)}{a\rho} \exp(-w^2/a^2), \\ j_z &= \frac{B_t}{\rho^2} \left\{ q \left[\frac{2w^2}{a^2} - \frac{R}{\rho} - 1 \right] x + \frac{2yz}{a} \right\} \exp(-w^2/a^2). \end{aligned} \quad (17)$$

A torus coordinate (w, ψ, ϕ) is related to the Cartesian coordinate as

$$\begin{aligned} x &= (R + w \cos \psi) \sin \phi, \\ y &= -w \sin \psi, \\ z &= (R + w \cos \psi) \cos \phi. \end{aligned} \quad (18)$$

Here w is the radius with respect to the tube axis, and ϕ is the *toroidal* angle with respect to the center of the torus. They are identically defined as in the spherical coordinate. The new coordinate ψ defines the *poloidal* angle, which is the polar angle with respect to the tube axis. It is 0 in the x - z plane, and increase in the same direction as θ (Figure 1).

The unit vectors $(\hat{\mathbf{w}}, \hat{\boldsymbol{\psi}})$ and $(\hat{\mathbf{r}}, \hat{\boldsymbol{\theta}})$ are related by

$$\begin{aligned} \hat{\mathbf{w}} &= \frac{r^2 - R\rho}{wr} \hat{\mathbf{r}} - \frac{Ry}{wr} \hat{\boldsymbol{\theta}}, \\ \hat{\boldsymbol{\psi}} &= \frac{Ry}{wr} \hat{\mathbf{r}} + \frac{r^2 - R\rho}{wr} \hat{\boldsymbol{\theta}}. \end{aligned} \quad (19)$$

In this definition, the axial component is toroidal ($\hat{\boldsymbol{\phi}}$). The non-axial components include the radial ($\hat{\mathbf{w}}$) and poloidal ($\hat{\boldsymbol{\psi}}$) contributions. Using Equations (14), (16), and (19), we find

$$\begin{aligned} B_w &= 0, \\ B_\psi &= \frac{qwB_t}{\rho} \exp(-w^2/a^2), \\ j_w &= 0, \end{aligned} \quad (20)$$

$$j_\psi = \frac{2wB_t}{a\rho} \exp(-w^2/a^2). \quad (21)$$

This indicates that the non-axial $\mathbf{B}$ and $\mathbf{j}$ are purely poloidal.

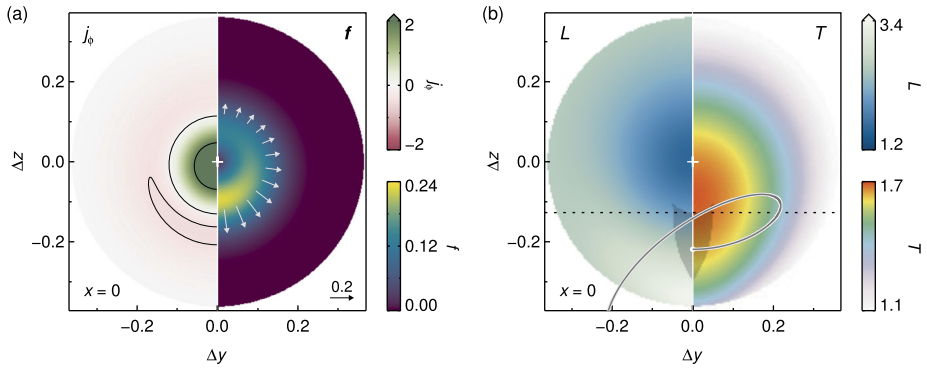


Figure 7 Properties of a FG03 flux tube on a cross section ($q = 0.8$, $\phi = x = 0$). (a) Map of toroidal current density j_ϕ (left) and Lorentz force $\mathbf{f}$ (right). The contours are for $j_\phi = -0.45, 0$, and 2 . The background colors show the force amplitude; the arrows show the force vectors at $w = 0.12$. The tube axis is marked with a cross. (b) Map of the length L (left) and the number of turns T around the axis (right) for field lines passing through the $x = 0$ plane and end at $\Delta z = -0.5$. Horizontal dotted line shows the photosphere for $h = -0.37$ when the observed magnetic flux reaches maximum. A portion of field lines will cross the photosphere four times; one such field line is shown (for $x > 0$). The wedge-shaped shaded region denotes their intersections with $x = 0$.

Using Equations (5), (6), (13), and (16), we can evaluate the contributions of poloidal and toroidal components in B_z and j_z :

$$\mathbf{B}_P \cdot \hat{\mathbf{z}} = B_t \frac{qyz}{\rho^2} \exp(-w^2/a^2), \quad (22)$$

$$\mathbf{B}_T \cdot \hat{\mathbf{z}} = -B_t \frac{ax}{\rho^2} \exp(-w^2/a^2),$$

$$\mathbf{j}_P \cdot \hat{\mathbf{z}} = \frac{2B_t yz}{a\rho^2} \exp(-w^2/a^2), \quad (23)$$

$$\mathbf{j}_T \cdot \hat{\mathbf{z}} = \frac{B_t q x}{\rho^2} \left(\frac{2w^2}{a^2} - \frac{R}{\rho} - 1 \right) \exp(-w^2/a^2).$$

The semi-torus tube is axisymmetric about the y -axis. However, on a cross section with constant ϕ , variables are not axisymmetric about the tube axis. For example, for j_ϕ , the inner, lower portion of the RC sheath appears to be stronger than other parts (Figure 7(a)).

We evaluate the Lorentz force density $\mathbf{f} = \mathbf{j} \times \mathbf{B}$ on the cross section $\phi = 0$. As both the radial field (B_w) and the radial current density (j_w) are zero, $\mathbf{f}$ must be purely radial. The force points away from the axis so the tube tends to expand. It is strongest at the lower portion of the DC core (Figure 7(a)).

We trace field lines in both directions from the $\phi = 0$ plane to investigate their lengths L and turns of twist T around the axis (Figure 7(b)). The latter is evaluated from the change of ψ in the torus coordinate. For $q = 0.8$, the axis of the semi-torus has $L = \pi R = 1.57$; field lines passing through the lower edge are more than twice in length due to twist. Field lines close to the axis have $T = qR/2a = 1.67$; those passing slightly below the axis have a larger T due to increased L .

For the $q = 0.8$ case, we find that a portion of the field lines may intersect the photosphere four times (Figure 8(b)). These field lines cross the $\phi = 0$ plane in a wedge-shaped region below the tube axis, where L and T are both large. This is a result of competition between

the curvatures given by the flux tube axis and by the twist in the flux tube. No such field lines are present for the $q = 0.2$ and 0.5 cases.

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