

1 ENTROPY CONJUGACY FOR MARKOV MULTI-MAPS 2 OF THE INTERVAL

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ABSTRACT. We consider a class $\mathcal{F}$ of Markov multi-maps on the unit interval. Any multi-map gives rise to a space of trajectories, which is a closed, shift-invariant subset of $[0, 1]^{\mathbb{Z}_+}$. For a multi-map in $\mathcal{F}$, we show that the space of trajectories is (Borel) entropy conjugate to an associated shift of finite type. Additionally, we characterize the set of numbers that can be obtained as the topological entropy of a multi-map in $\mathcal{F}$.

4 1. INTRODUCTION

5 Multi-maps, also called set-valued maps, have been studied in the
6 topological dynamics literature for some time, with such notable ex-
7 amples as [1, 21, 22]. In the past decade multi-maps have been studied
8 extensively, with a particular focus on the topological structure of the
9 associated space of trajectories or a related inverse limit space; see [15].
10 This development has also led to a renewed interest in the dynamics
11 of multi-maps [11, 13, 17, 18]. Additionally, multi-maps are the topo-
12 logical analogues of random maps of the interval, which have received
13 substantial attention, e.g., [4, 10, 14, 23].

14 In the study of single-valued maps of the interval, Markov maps [7]
15 are particularly well-understood. These maps have a finite invariant
16 set such that the map is strictly monotone on the intervals between
17 elements of that set. This structure allows one to associate to each
18 Markov interval map a corresponding shift of finite type that preserves
19 many aspects of the dynamics.

20 Recent work [3, 5, 6, 12] has generalized the notion of Markov interval
21 maps to the setting of multi-maps and established some of their basic
22 properties. In particular, [2] proves that under some conditions on
23 the Markov multi-map, one may find upper and lower bounds for its
24 entropy using associated shifts of finite type.

25 Our main results substantially sharpen this previous work. Under
26 mild conditions on the Markov multi-map, we associate to it a single
27 shift of finite type, and then we establish a close connection (in the

1 form of a Borel entropy conjugacy) between the dynamics of the multi-
 2 map and its associated shift of finite type. In particular, for a Markov
 3 multi-map in the class $\mathcal{F}$ considered here, the topological entropies of
 4 the Markov multi-map and of the associated shift of finite type must
 5 be equal. Furthermore, we demonstrate the richness of the class $\mathcal{F}$ by
 6 showing that any number that appears as the entropy of a shift of finite
 7 type also appears as the entropy of a Markov multi-map in $\mathcal{F}$.

8 **1.1. Statement of main results.** A multi-map of the unit interval
 9 is a function $F : [0, 1] \rightarrow 2^{[0,1]}$, where $2^{[0,1]}$ is taken to be the set of
 10 closed subsets of $[0, 1]$. Given such a multi-map, its trajectory space
 11 $X = X(F)$ is defined by

$$X(F) = \left\{ x = (x_n)_{n=0}^\infty \in [0, 1]^{\mathbb{Z}_+} : \forall n \geq 0, x_{n+1} \in F(x_n) \right\}.$$

12 Further, let $\sigma_X : X \rightarrow X$ denote the left-shift map $(x_n)_{n=0}^\infty \mapsto (x_{n+1})_{n=0}^\infty$
 13 on X . We seek to understand the multi-map F by studying the dy-
 14 namics of the system (X, σ_X) .

15 In Section 3 we introduce a class of multi-maps that we call Markov
 16 multi-maps, and in Definition 3.4 we state what it means for a Markov
 17 multi-map to be properly parametrized. In this work we focus on a
 18 specific class $\mathcal{F}$ of Markov multi-maps (see Definition 3.9): properly
 19 parametrized Markov multi-maps with complete sets of coding and
 20 avoiding words and positive entropy. For any multi-map F in this
 21 class, one may associate to F a square matrix $M = M(F)$ with entries
 22 in $\{0, 1\}$ (see Section 3.2). The matrix M encodes the combinatorial
 23 structure of F . Let Σ_M be the shift of finite type defined by M , with
 24 left-shift map σ_M . The following theorem provides a precise correspon-
 25 dence between a “large” subset of the trajectory space X and a “large”
 26 subset of the SFT Σ_M , where “large” here refers to a notion of entropy.
 27 A precise definition of Borel entropy conjugacy, originally defined by
 28 Buzzi [9] under the term “entropy conjugacy,” appears in Definition
 29 2.2.

30 **Theorem 1.1.** *Let $\mathcal{F}$ be the class of Markov multi-maps specified in*
 31 *Definition 3.9. Let F be in $\mathcal{F}$ with trajectory space X and associated*
 32 *SFT Σ_M . Then (X, σ_X) is Borel entropy conjugate to (Σ_M, σ_M) .*

33 Since Borel entropy conjugacy is known to preserve topological en-
 34 tropy, we immediately obtain the following corollary.

35 **Corollary 1.2.** *Let F be in $\mathcal{F}$ with trajectory space X and associated*
 36 *SFT Σ_M . Then $h_{\text{top}}(X, \sigma_X) = h_{\text{top}}(\Sigma_M, \sigma_M)$.*

1 In fact, since Borel entropy conjugacy provides a correspondence
 2 between all ergodic measures with large enough entropy, the following
 3 corollary is also immediate.

4 **Corollary 1.3.** *Let F be in $\mathcal{F}$ with trajectory space X and associated*
 5 *SFT Σ_M . Then (X, σ_X) has the same number of measures of maximal*
 6 *entropy as (Σ_M, σ_M) . In particular, if (Σ_M, σ_M) is irreducible, then*
 7 *(X, σ_X) is intrinsically ergodic (i.e., has a unique measure of maximal*
 8 *entropy).*

9 *Remark 1.4.* Random maps of the interval have been studied primarily
 10 with an eye towards the existence and properties of absolutely contin-
 11 uous invariant measures, e.g., see [4, 7]. While the entropy conjugacy
 12 guaranteed by Theorem 1.1 provides a correspondence between ergodic
 13 measures of large entropy on X and on Σ_M , it does not address ques-
 14 tions about whether any of these measures is absolutely continuous on
 15 X .

16 Let us now answer a question of Karl Petersen (personal commu-
 17 nication). Let $\mathcal{H}(\mathcal{F})$ denote the set of real numbers $r > 0$ such
 18 that there exists a multi-map $F \in \mathcal{F}$ having trajectory space X with
 19 $h_{\text{top}}(X, \sigma_X) = r$. Recall that Lind has characterized the set of positive
 20 real numbers that arise as the entropy of a SFT as the set of all positive
 21 rational multiples of logarithms of Perron numbers [19].

22 **Theorem 1.5.** *The set $\mathcal{H}(\mathcal{F})$ is equal to the set of all positive rational*
 23 *multiples of logarithms of Perron numbers.*

24 **1.2. Organization of the paper.** In Section 2, we provide back-
 25 ground information and notation concerning shifts of finite type, er-
 26 godic theory, and Borel entropy conjugacy. Section 3 introduces Markov
 27 multi-maps and the class $\mathcal{F}$ of interest. Taken together, Sections 4 –
 28 7 contain the proof of our main result, Theorem 1.1. In Section 8 we
 29 establish some sufficient conditions for a Markov multi-map to be in
 30 $\mathcal{F}$, and then in Section 9 we prove the realization result, Theorem 1.5.
 31 Finally, Section 10 contains some examples of Markov multi-maps.

32 2. BACKGROUND AND NOTATION

33 We denote by $2^{[0,1]}$ the set of all non-empty, closed subsets of $[0, 1]$.
 34 A *multi-map* on $[0, 1]$ is a function $F: [0, 1] \rightarrow 2^{[0,1]}$. The *graph* of
 35 a multi-map F is the set $G(F) = \{(x, y) \in [0, 1]^2: y \in F(x)\}$. A
 36 *trajectory* for F is a sequence $(x_0, x_1, \dots) \in [0, 1]^{\mathbb{Z}^+}$ such that for all
 37 $n \geq 1$, we have $x_n \in F(x_{n-1})$, or equivalently $(x_{n-1}, x_n) \in G(F)$.
 38 We denote by $X = X(F)$ the set of trajectories for F , and we give

1 X the topology it inherits as a subspace of $[0, 1]^{\mathbb{Z}_+}$ with the product
 2 topology. We also define the *left-shift* on X , denoted σ_X , by setting
 3 $\sigma_X(x_0, x_1, \dots) = (x_1, x_2, \dots)$. Observe that σ_X is a continuous mapping
 4 on X , and if $G(F)$ is closed in $[0, 1]^2$, then X is closed in $[0, 1]^{\mathbb{Z}_+}$.

5 **2.1. Shifts of finite type.** Let $\mathcal{A}$ be a finite set, which we call the
 6 *alphabet*. An element $b \in \mathcal{A}^n$ is called a *word* of length n . The full shift
 7 on $\mathcal{A}$ is $\Sigma = \mathcal{A}^{\mathbb{Z}_+}$, endowed with the product topology induced by the
 8 discrete topology on $\mathcal{A}$. Given a set of words $\mathcal{F}$, we may define $\Sigma_{\mathcal{F}} \subseteq \Sigma$
 9 to be the set of points that do not contain any word in $\mathcal{F}$. We refer to
 10 words in $\mathcal{F}$ as *forbidden words*. Then $\Sigma_{\mathcal{F}}$ is closed and invariant under
 11 the left-shift on Σ . If $\mathcal{F}$ is finite, then we refer to $\Sigma_{\mathcal{F}}$ as a *shift of finite*
 12 *type (SFT)*. In this work we restrict attention to SFTs for which all the
 13 forbidden words have length two, called nearest neighbor SFTs. For
 14 more on SFTs, we refer the reader to the book [20].

15 Any nearest neighbor SFT may be expressed in terms of a directed
 16 graph, (V, E) , where the set of vertices V is equal to $\mathcal{A}$, and given
 17 $a, b \in \mathcal{A}$, there is an edge from a to b in the edge set E if and only
 18 if $ab \notin \mathcal{F}$. Furthermore, we associate to any such graph its *adjacency*
 19 *matrix* M , defined as the square matrix indexed by $\mathcal{A}$ such that for
 20 $a, b \in \mathcal{A}$, if $ab \notin \mathcal{F}$ then $M(a, b) = 1$, and otherwise $M(a, b) = 0$.
 21 Note that any zero-one matrix indexed by $\mathcal{A}$ also defines an associated
 22 nearest neighbor SFT (by letting ab be a forbidden word whenever
 23 $M(a, b) = 0$). The nearest neighbor SFT defined by a zero-one matrix
 24 M is denoted by Σ_M , and the left-shift restricted to Σ_M is denoted by
 25 σ_M .

26 In what follows it is convenient to have some notation for words of
 27 arbitrary length that do not contain any forbidden word. For $n \geq 2$, we
 28 let $\mathcal{L}_n$ denote the set of words $a_0 \dots a_{n-1} \in \mathcal{A}^n$ such that $M(a_i, a_{i+1}) =$
 29 1 for each $i = 0, \dots, n-2$. Then let

$$\mathcal{L} = \bigcup_{n \geq 1} \mathcal{L}_n,$$

30 where $\mathcal{L}_1 = \mathcal{A}$.

31 A nearest neighbor SFT defined by the matrix M is *irreducible* if
 32 for every pair of non-empty, open sets $U, V \subseteq \Sigma_M$, there exists $n \geq 1$
 33 such that $\sigma_M^n(U) \cap V \neq \emptyset$. Equivalently, Σ_M is irreducible if for each
 34 $a, b \in \mathcal{A}$, there exists $n \geq 1$ such that $M^n(a, b) > 0$.

35 Consider an arbitrary nearest neighbor SFT Σ_M on alphabet $\mathcal{A}$. It
 36 has an associated finite directed graph Γ , with vertex set $\mathcal{A}$ and an edge
 37 from a to b whenever $M(a, b) = 1$. Let $\mathcal{C}_1, \dots, \mathcal{C}_K \subset \mathcal{A}$ be the vertex
 38 sets of the maximal strongly connected components of Γ , which we call

1 the irreducible components of Γ . For each $\mathcal{C}_k$, the set of points in Σ_M
 2 containing only symbols from $\mathcal{C}_k$ forms an irreducible SFT, which we
 3 denote by $\Sigma_M(\mathcal{C}_k)$. We refer to $\Sigma_M(\mathcal{C}_k)$ as an irreducible component
 4 of Σ_M . Note that the irreducible components $\Sigma_M(\mathcal{C}_1), \dots, \Sigma_M(\mathcal{C}_k)$ are
 5 pairwise disjoint, and the set $\Sigma_M \setminus \bigcup_k \Sigma_M(\mathcal{C}_k)$ contains only wandering
 6 points. See [20, Chapter 4] for more details on this decomposition. We
 7 also denote by $\mathcal{L}(\mathcal{C}_k)$ the set of words of arbitrary length on $\mathcal{C}_k$ that do
 8 not contain a forbidden word.

9 **2.2. Invariant measures and entropy.** In this work a topological
 10 dynamical system consists of a pair $(\mathcal{X}, T)$, where $T : \mathcal{X} \rightarrow \mathcal{X}$ is
 11 a continuous self-map of a compact metrizable space. For any such
 12 system, we let $\mathcal{M}(\mathcal{X}, T)$ denote the set of Borel probability measures
 13 μ on $\mathcal{X}$ such that $\mu(E) = \mu(T^{-1}E)$ for all Borel sets $E \subset \mathcal{X}$. Note
 14 that $\mathcal{M}(\mathcal{X}, T)$ is a nonempty, convex set that is compact in the weak*
 15 topology. A measure $\mu \in \mathcal{M}(\mathcal{X}, T)$ is called ergodic if $\mu(E) \in \{0, 1\}$ for
 16 all Borel sets E such that $T^{-1}(E) \subset E$. The set of ergodic measures
 17 is denoted by $\mathcal{M}_e(\mathcal{X}, T)$. Note that a measure $\mu \in \mathcal{M}(\mathcal{X}, T)$ is an
 18 extreme point in $\mathcal{M}(\mathcal{X}, T)$ if and only if μ is ergodic.

19 The following notation is used in subsequent sections. For any Borel
 20 set $E \subset \mathcal{X}$, the union of all of its pre-images is denoted

$$\text{Pre}(E) = \bigcup_{n \geq 0} T^{-n}(E).$$

21 Note that $T^{-1}(\text{Pre}(E)) \subset \text{Pre}(E)$, and therefore if $\mu \in \mathcal{M}_e(\mathcal{X}, T)$ then
 22 $\mu(\text{Pre}(E)) \in \{0, 1\}$.

23 We also require some elementary facts regarding the entropy theory
 24 of dynamical systems. Complete definitions and proofs can be found
 25 in [24]. Let $h_{\text{top}}(\mathcal{X}, T)$ denote the topological entropy of the topological
 26 system $(\mathcal{X}, T)$. Furthermore, when the system $(\mathcal{X}, T)$ is understood
 27 and $\mu \in \mathcal{M}(\mathcal{X}, T)$, we denote the measure-theoretic entropy of μ by
 28 $h(\mu)$. The standard variational principle for entropy states that

$$h_{\text{top}}(\mathcal{X}, T) = \sup_{\mu \in \mathcal{M}(\mathcal{X}, T)} h(\mu),$$

29 and the supremum may be taken over only the ergodic measures. Fur-
 30 thermore, for SFTs it is known that the supremum is achieved, and if
 31 the SFT is irreducible, then it has a unique measure of maximal en-
 32 tropy. Furthermore, we note for future use that an irreducible SFT is
 33 entropy minimal, i.e., if X is an irreducible SFT of positive entropy
 34 and Y is a strict subset of X , then $h_{\text{top}}(Y, \sigma|_Y) < h_{\text{top}}(X, \sigma|_X)$ (see [20]
 35 for a proof).

2.3. **Entropy conjugacy.** We adopt the following definition of entropy for Borel sets (following Buzzi [9]).

Definition 2.1. Let $T : \mathcal{X} \rightarrow \mathcal{X}$ be a topological dynamical system. For a Borel set $E \subset \mathcal{X}$, let

$$h_{\text{prob}}(E) = \sup\{h(\mu) : \mu \in \mathcal{M}_e(\mathcal{X}, T), \mu(E) > 0\}.$$

Now we define a notion of entropy conjugacy, which was previously introduced by Buzzi [9].

Definition 2.2. Suppose that $T_0 : \mathcal{X}_0 \rightarrow \mathcal{X}_0$ and $T_1 : \mathcal{X}_1 \rightarrow \mathcal{X}_1$ are topological dynamical systems. We say that they are *Borel entropy conjugate* if there exist Borel sets $E_0 \subset \mathcal{X}_0$ and $E_1 \subset \mathcal{X}_1$ and an invertible Borel bi-measurable map $\psi : \mathcal{X}_0 \setminus E_0 \rightarrow \mathcal{X}_1 \setminus E_1$ such that

- $h_{\text{prob}}(E_0) < h_{\text{top}}(\mathcal{X}_0, T_0)$;
- $h_{\text{prob}}(E_1) < h_{\text{top}}(\mathcal{X}_1, T_1)$; and
- $\psi \circ T_0 = T_1 \circ \psi$ on $\mathcal{X}_0 \setminus E_0$.

It is an easy corollary of the variational principle for topological dynamical systems that if $(\mathcal{X}_0, T_0)$ and $(\mathcal{X}_1, T_1)$ are Borel entropy conjugate, then $h_{\text{top}}(\mathcal{X}_0, T_0) = h_{\text{top}}(\mathcal{X}_1, T_1)$.

Remark 2.3. In his work on topological entropy for non-compact sets, Bowen introduced a notion that he called entropy conjugacy [8]. Bowen's definition of entropy conjugacy requires that the sets E_0 and E_1 have smaller topological entropy (in the dimension-theoretic sense defined in his paper) than the full system and that the conjugating map ψ is continuous. As such, Bowen's notion of entropy conjugacy is stronger than the notion of Borel entropy conjugacy defined above.

3. MARKOV MULTI-MAPS

We now give a precise definition of Markov multi-maps on the interval $[0, 1]$. This definition is based on the one given in [2], though our definition is slightly less general.

Definition 3.1. A Markov multi-map F of the interval $[0, 1]$ is defined by a tuple $(P, \mathcal{A}_0, \mathcal{A}_1, \mathcal{A}_2, D, R, \{f_a\}_{a \in \mathcal{A}_0})$ satisfying the following conditions:

- (1) $P = \{p_0, \dots, p_r\}$ is a partition of the interval $[0, 1]$ with $0 = p_0 < \dots < p_r = 1$;
- (2) $\mathcal{A} = \mathcal{A}_0 \sqcup \mathcal{A}_1 \sqcup \mathcal{A}_2$ is a finite set;
- (3) $D : \mathcal{A} \rightarrow 2^{[0, 1]}$, and for each $a \in \mathcal{A}$, there exists $p_i \in P$ such that

$$D(a) = \begin{cases} [p_i, p_{i+1}], & \text{if } a \in \mathcal{A}_0 \\ \{p_i\}, & \text{if } a \in \mathcal{A}_1 \cup \mathcal{A}_2; \end{cases}$$

- 1 (4) $R : \mathcal{A} \rightarrow 2^{[0,1]}$, and for each $a \in \mathcal{A}$, there exists $u \leq v$ in P such
 2 that $R(a) = [u, v]$ and

$$\begin{cases} u < v, & \text{if } a \in \mathcal{A}_0 \\ u < v \text{ and } R(a) \cap P = \{u, v\}, & \text{if } a \in \mathcal{A}_1 \\ u = v, & \text{if } a \in \mathcal{A}_2; \end{cases}$$

- 3 (5) for each $a \in \mathcal{A}_0$, the map $f_a : D(a) \rightarrow R(a)$ is a homeomor-
 4 phism;
 5 (6) $[0, 1] \subset \bigcup_{a \in \mathcal{A}} D(a)$.

6 **3.1. The graph of a Markov multi-map.** Let F be a Markov multi-
 7 map. For $a \in \mathcal{A}_0$, let $G(a)$ denote the graph of f_a . For $a \in \mathcal{A}_1 \cup \mathcal{A}_2$,
 8 let $G(a) = D(a) \times R(a)$. Then the graph of F is

$$G(F) = \bigcup_{a \in \mathcal{A}} G(a).$$

9 Note that each $G(a)$ is closed in $[0, 1] \times [0, 1]$, and so is $G(F)$. An
 10 example of a Markov multi-map and its graph is given in Example 3.6,
 11 and more examples are shown in Section 10.

12 Now we make some additional graph-related definitions that are used
 13 repeatedly throughout this work.

14 **Definition 3.2.** Let $a \in \mathcal{A}$.

- 15 • Suppose $a \in \mathcal{A}_0$ with $D(a) = [p_i, p_{i+1}]$ and $R(a) = [u, v]$. Define
 16 $D_0(a) = (p_i, p_{i+1})$ and $R_0(a) = (u, v)$, and let $G_0(a)$ be the
 17 graph of $f_a|_{D_0(a)}$.
- 18 • Suppose $a \in \mathcal{A}_1$ with $D(a) = \{p\}$ and $R(a) = [u, v]$. Define
 19 $D_0(a) = \{p\}$ and $R_0(a) = (u, v)$, and let $G_0(a) = \{p\} \times R_0(a)$.
- 20 • Suppose $a \in \mathcal{A}_2$ with $D(a) = \{p\}$ and $R(a) = \{q\}$. Define
 21 $D_0(a) = \{p\}$ and $R_0(a) = \{q\}$, and let $G_0(a) = \{(p, q)\}$.

22 Our results require that F has some additional structure, which we
 23 now begin to define.

24 **Definition 3.3.** We say that F satisfies the *no crossing property* if the
 25 following holds: for all $a, b \in \mathcal{A}_0$, if $G_0(a) \cap G_0(b) \neq \emptyset$ then $a = b$.

26 The following property strictly implies the no crossing property.

27 **Definition 3.4.** We say that F is *properly parametrized* if the collec-
 28 tion $\{G_0(a) : a \in \mathcal{A}\}$ forms a partition of $G(F)$.

29 We think of the no crossing property as a property of the graph $G(F)$
 30 (and the partition P), whereas being properly parametrized depends on
 31 the particular parametrization of the Markov multi-map F . However,

1 these properties are related by Lemma 4.1: if F_0 is a Markov multi-map
 2 with the no crossing property, then there exists a properly parametrized
 3 Markov multi-map F_1 such that $G(F_0) = G(F_1)$.

4 *Remark 3.5.* If F is a Markov multi-map, then it possesses the following
 5 graph *Markov property*: for all $a, b \in \mathcal{A}$, if $D_0(b) \cap R_0(a) \neq \emptyset$, then
 6 $D_0(b) \subset R_0(a)$. This property is used to define the SFT associated
 7 with F , which appears in the next section.

8 **3.2. The SFT associated to a Markov multi-map.** We associate
 9 to any Markov multi-map F an SFT as follows. Let M be the square
 10 matrix indexed by $\mathcal{A}$ such that for $a, b \in \mathcal{A}$,

$$M(a, b) = \begin{cases} 1, & \text{if } D_0(b) \subset R_0(a) \\ 0, & \text{otherwise.} \end{cases}$$

11 Let $\Sigma_M \subset \mathcal{A}^{\mathbb{Z}^+}$ be the nearest neighbor SFT with alphabet $\mathcal{A}$ and
 12 adjacency matrix M .

13 To show how a Markov multi-map may be properly parametrized
 14 and how the adjacency matrix is constructed, we present the follow-
 15 ing example of a fairly simple Markov multi-map with the no-crossing
 16 property.

Example 3.6. The graph in Figure 1 shows the graph of a Markov
 multi-map on $[0, 1]$ with the partition $P = \{0, 1/2, 1\}$. To properly
 parametrize it, we first consider the two diagonal lines, and we index
 them with the set $\mathcal{A}_0 = \{1, 2\}$. Then the vertical line segment is
 indexed by $\mathcal{A}_1 = \{3\}$. Finally this leaves the four endpoints of those
 segments which we index with $\mathcal{A}_2 = \{4, 5, 6, 7\}$. Then we define the
 following:

$$\begin{aligned} D(1) &= [0, 1/2] & R(1) &= [0, 1] & D(2) &= [1/2, 1] & R(2) &= [1/2, 1] \\ D(3) &= \{1/2\} & R(3) &= [1/2, 1] & D(4) &= \{0\} & R(4) &= \{0\} \\ D(5) &= \{1/2\} & R(5) &= \{1\} & D(6) &= \{1/2\} & R(6) &= \{1/2\} \\ D(7) &= \{1\} & R(7) &= \{1\}. \end{aligned}$$

17 Then for all $a \in \mathcal{A} = \mathcal{A}_0 \cup \mathcal{A}_1 \cup \mathcal{A}_2$, if $D(a)$ is a singleton, we let
 18 $D_0(a) = D(a)$, and if $D(a)$ is an interval of the form $D(a) = [p, q]$,
 19 then $D_0(a) = (p, q)$. We define each $R_0(a)$ likewise.

20 Next we construct the adjacency matrix corresponding to this graph.
 21 Note that $R_0(1) = (0, 1)$ which contains as subsets all of the following:
 22 $D_0(1)$, $D_0(2)$, $D_0(3)$, $D_0(5)$, $D_0(6)$. However $D_0(4)$ and $D_0(7)$ are not
 23 subsets of $R_0(1)$. This produces the first row of the adjacency matrix
 24 which has a 1 in every column except for the 4th and 7th. We may

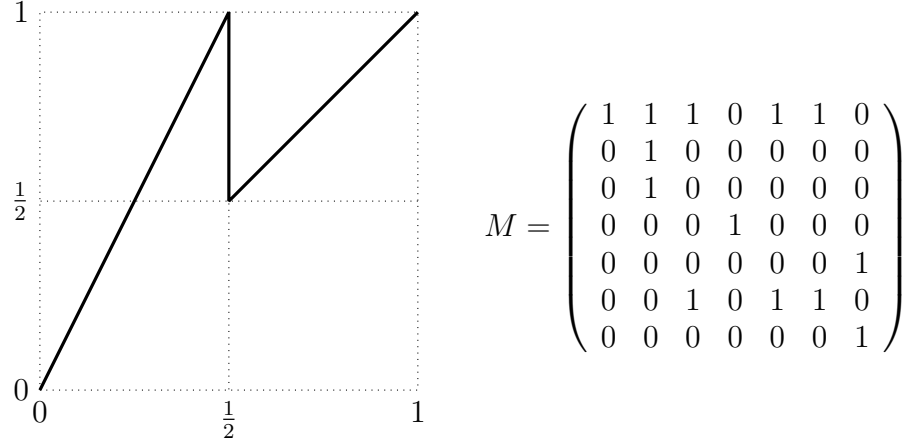


FIGURE 1. The graph of a Markov multi-map and its corresponding adjacency matrix

1 do the same for each element of $\mathcal{A}$ to produce the adjacency matrix
2 pictured in Figure 1.

3

4 In our main results, we relate the SFT Σ_M to the trajectory space
5 X . In particular, Theorem 1.1 establishes sufficient conditions for these
6 systems to be Borel entropy conjugate.

7 **3.3. Nested intervals.** Let F be a properly parametrized Markov
8 multi-map with associated matrix M . Here we associate to each se-
9 quence $\mathbf{a} \in \Sigma_M$ a nonempty closed (possibly degenerate) interval in
10 $[0, 1]$. To begin, for each $a \in \mathcal{A}_0$, we let f_a^{-1} be the standard in-
11 verse function (which exists since f_a is assumed to be a homeomor-
12 phism). For $a \in \mathcal{A}_1 \cup \mathcal{A}_2$, we let f_a^{-1} be the unique map such that
13 $f_a^{-1} : R(a) \rightarrow D(a)$ (which exists since $R(a)$ is non-empty and $D(a)$ is
14 a singleton in this case).

15 Let $u = a_0 \dots a_n \in \mathcal{L}_{n+1}$. Define the set

$$I_u = f_{a_0}^{-1} \circ \dots \circ f_{a_{n-1}}^{-1}(D(a_n))$$

16 We make the following elementary observations.

- 17 • I_u is non-empty. (Since $M(a_i, a_{i+1}) = 1$, we have that $D(a_{i+1}) \subset$
18 $R(a_i)$, so $f_{a_i}^{-1}$ maps $D(a_{i+1})$ into $D(a_i)$.)
- 19 • I_u is a closed (possibly degenerate) interval, since I_u is the image
20 of the closed interval $D(a_n)$ under the continuous, monotone
21 map $f_{a_0}^{-1} \circ \dots \circ f_{a_{n-1}}^{-1}$.
- 22 • $I_{a_0 \dots a_{n+1}} = f_{a_0}^{-1}(I_{a_1 \dots a_{n+1}})$.

- 1 • $I_{a_0\dots a_{n+1}} \subset I_{a_0\dots a_n}$ (since $f_{a_n}^{-1}(D(a_{n+1})) \subset D(a_n)$).
 2 Now consider $\mathbf{a} = (a_n)_{n=0}^\infty \in \Sigma_M$. Then $\{I_{a_0\dots a_n}\}_{n=1}^\infty$ is a nested
 3 sequence of non-empty, closed intervals in $[0, 1]$. Let

$$I_{\mathbf{a}} = \bigcap_{n=1}^{\infty} I_{a_0\dots a_n}.$$

- 4 Then $I_{\mathbf{a}}$ is a non-empty, closed interval. Additionally, we note that

$$I_{\mathbf{a}} = f_{a_0}^{-1}(I_{\sigma(\mathbf{a})}).$$

- 5 These intervals appear in the next section in the definitions that char-
 6 acterize the class of Markov multi-maps in our main results.

- 7 **3.4. Definition of the class $\mathcal{F}$.** In this section we define the class $\mathcal{F}$
 8 of Markov multi-maps that appears in our main results. Let F be a
 9 properly parametrized Markov multi-map with associated matrix M .

- 10 **Definition 3.7.** Suppose $\mathcal{C} \subset \mathcal{A}$ is an irreducible component of the
 11 graph with adjacency matrix M . We say that $\mathcal{C}$ has a *coding word* if
 12 there exists $u \in \mathcal{L}(\mathcal{C})$ such that if $\mathbf{a} \in \Sigma_M(\mathcal{C})$ and $\{n \geq 0 : \sigma^n(\mathbf{a}) \in [u]\}$
 13 is infinite, then $I_{\mathbf{a}}$ is a singleton. Furthermore, we say that F has a
 14 *complete set of coding words* if each irreducible component with positive
 15 entropy has a coding word.

- 16 **Definition 3.8.** Suppose $\mathcal{C} \subset \mathcal{A}$ is an irreducible component of the
 17 graph with adjacency matrix M . We say that $\mathcal{C}$ has an *avoiding word*
 18 if there exists $u \in \mathcal{L}(\mathcal{C})$ such that if $\mathbf{a} \in [u]$, then $I_{\mathbf{a}} \cap P = \emptyset$. Fur-
 19 thermore, we say that F has a *complete set of avoiding words* if the
 20 following condition holds: if $\mathcal{C}$ is an irreducible component with posi-
 21 tive entropy that is entirely contained in $\mathcal{A}_0$, then $\mathcal{C}$ has an avoiding
 22 word.

- 23 Now we are prepared to give a precise definition of the class of
 24 Markov multi-maps that appears in our main results.

- 25 **Definition 3.9.** The class $\mathcal{F}$ consists of all properly parametrized
 26 Markov multi-maps F such that F has a complete set of coding words,
 27 F has a complete set of avoiding words, and the associated SFT Σ_M
 28 has positive entropy.

- 29 **3.5. Finite labeled trajectories.** Here we define some additional ter-
 30 minology that is useful in the following sections.

- 31 **Definition 3.10.** Let $F \in \mathcal{F}$. Let $m \geq 1$. We say that $x = x_0, \dots, x_m \in$
 32 $[0, 1]^{m+1}$ is a *finite trajectory* of F if

$$(x_n, x_{n+1}) \in G(F), \quad \forall n = 0, \dots, m-1.$$

1 Next, we say that $(x, b) \in [0, 1]^{m+1} \times \mathcal{L}_m$ is a *finite labeled trajectory*
 2 (of length $m + 1$) if

$$(x_n, x_{n+1}) \in G(b_n), \quad \forall n = 0, \dots, m - 1.$$

3 Let $\mathcal{T}_m$ be the set of finite labeled trajectories of length $m + 1$. We endow
 4 $\mathcal{T}_m$ with the subspace topology inherited from $[0, 1]^{m+1} \times \mathcal{L}_m$ (which
 5 has the product of the usual topology on $[0, 1]^{m+1}$ and the discrete
 6 topology on $\mathcal{L}_m$).

7 Finally, we say that $(x, b) \in \mathcal{T}_m$ is a *special finite labeled trajectory*
 8 of length $m + 1$ if

$$(x_n, x_{n+1}) \in G_0(b_n), \quad \forall n = 0, \dots, m - 1.$$

9 Let $\mathcal{S}_m$ denote the set of special finite labeled trajectories of length
 10 $m + 1$, and we let $\mathcal{S}_m$ inherit the subspace topology inherited from $\mathcal{T}_m$.

11 *Remark 3.11.* Let F be in $\mathcal{F}$, and let x be a finite trajectory of F of
 12 length $m + 1$. Since $G(F)$ is the union of the sets $\{G(a)\}_{a \in \mathcal{A}}$, there
 13 exists $b \in \mathcal{L}_m$ such that (x, b) is in $\mathcal{T}_m$. In fact, since F is prop-
 14 erly parametrized, the sets $\{G_0(a)\}_{a \in \mathcal{A}}$ form a partition of $G(F)$, and
 15 therefore there exists a *unique* element $b \in \mathcal{L}_m$ such that (x, b) is in
 16 $\mathcal{S}_m$.

17 4. PRELIMINARY RESULTS

18 **4.1. Parametrization lemma.** The following simple result states that
 19 any Markov multi-map with the no-crossing property can be prop-
 20 erly parametrized without changing its graph. Since the space of
 21 trajectories of a Markov multi-map depends only on its graph, this
 22 reparametrization also preserves the space of trajectories.

23 **Lemma 4.1.** *Suppose that F_0 is a Markov multi-map with the no-*
 24 *crossing property. Then there exists a properly parametrized Markov*
 25 *multi-map F_1 with $G(F_0) = G(F_1)$.*

26 *Proof.* Let F be a Markov multi-map with the no-crossing property.
 27 Let $\mathcal{B}_0 = \mathcal{A}_0$. Let

$$\mathcal{B}_1 = \left\{ \{p_i\} \times [p_j, p_{j+1}] : p_i, p_j \in P \text{ and } \exists a \in \mathcal{A}_1, \{p_i\} \times [p_j, p_{j+1}] \subset G(a) \right\}.$$

28 Let

$$\mathcal{B}_2 = \left\{ (p, q) : p, q \in P, (p, q) \in G(F) \right\}.$$

29 Then let F_1 be the Markov multi-map defined by $\mathcal{B}_0$, $\mathcal{B}_1$, and $\mathcal{B}_2$. $\square$

1 **4.2. Graph lemmas.** In this section we prove a few facts about graphs
 2 of Markov multi-maps. Throughout the remainder of this section, we
 3 consider $F \in \mathcal{F}$. Since F is properly parametrized, we know that if
 4 $a, b \in \mathcal{A}$ are distinct elements, then $G_0(a) \cap G_0(b) = \emptyset$. However, it
 5 is possible that $a \neq b$ and yet $G(a)$ has nontrivial intersection with
 6 $G(b)$. The following lemma shows that any such intersection must be
 7 contained in $P \times P$.

8 **Lemma 4.2.** *Let F be in $\mathcal{F}$. Suppose $(x, y) \in G(F) \setminus (P \times P)$. Then*
 9 *there is a unique $a \in \mathcal{A}$ such that $(x, y) \in G(a)$, and furthermore*
 10 *$(x, y) \in G_0(a)$.*

11 *Proof.* Since $(x, y) \in G(F) = \cup_a G(a)$, there must exist some $a \in \mathcal{A}$
 12 such that $(x, y) \in G(a)$. For uniqueness, suppose that $(x, y) \in G(a) \cap$
 13 $G(b)$. By the no-crossing property, for any $a \neq b$, we have $G(a) \cap G(b) \subset$
 14 $P \times P$. Since $(x, y) \notin P \times P$, we conclude that $a = b$.

15 Since $(x, y) \notin P \times P$ and $(x, y) \in G(a)$, we see that $a \in \mathcal{A}_0 \cup \mathcal{A}_1$,
 16 and we must have $(x, y) \in G_0(a)$. $\square$

17 The next lemma asserts that $G(F)$ cannot accumulate along a hori-
 18 zontal line to any point of $G(F) \cap (P \times P)$.

19 **Lemma 4.3.** *Let $(p, q) \in G(F) \cap (P \times P)$. Then there exists an open*
 20 *set $U \subset [0, 1] \times [0, 1]$ such that $(p, q) \in U$ and if $(y, q) \in G_0(a) \cap U$, then*
 21 *$y = p$ and a is the unique element of $\mathcal{A}_2$ such that $G(a) = \{(p, q)\}$.*

22 *Proof.* Let $L_q = [0, 1] \times \{q\}$. By our definition of Markov multi-map,
 23 $L_q \cap G(F)$ is a finite set containing (p, q) . Then there exists a relatively
 24 open interval I in $[0, 1]$ such that $I \times \{q\} \cap G(F) = \{(p, q)\}$. Let
 25 $U = I \times [0, 1]$. Then U is open in $[0, 1] \times [0, 1]$ and if $(y, q) \in G_0(a)$,
 26 then $y = p$ and a must be the unique element of $\mathcal{A}_2$ such that $G(a) =$
 27 $\{(p, q)\}$. $\square$

28 The next two lemmas address the convergence of sequences in the
 29 space of finite labeled trajectories.

30 **Lemma 4.4.** *Let $m \geq 1$. Suppose that $x = x_0, \dots, x_m \in [0, 1]^{m+1}$ is a*
 31 *finite trajectory of F such that*

- 32 $\bullet x_0, \dots, x_{m-1} \in P$, and
 33 $\bullet x_m \in [0, 1] \setminus P$.

34 *Let w be the unique element of $\mathcal{L}_m$ such that $(x, w) \in \mathcal{S}_m$. If the*
 35 *sequence $\{(y^k, b^k)\}_{k=1}^\infty$ is in $\mathcal{S}_m$ and converges to (x, b) in $[0, 1]^{m+1} \times \mathcal{A}^m$,*
 36 *then $b = w$.*

1 *Proof.* By our hypotheses on $x_0, \dots, x_m$, we have that $w_{m-1} \in \mathcal{A}_1$ and
 2 if $m \geq 2$, then $w_n \in \mathcal{A}_2$ for $n = 0, \dots, m-2$. Let us now show that
 3 $b_0 \dots b_{m-1} = w$.

4 First, note that since $\mathcal{A}^m$ has the discrete topology, for all large
 5 enough k , we have $b^k = b$. Then for all large enough k , we have
 6 $(y_n^k, y_{n+1}^k) \in G(b_n)$ for all $n = 0, \dots, m-1$. Since $G(b_n)$ is closed and
 7 $\{(y_n^k, y_{n+1}^k)\}_{k=1}^\infty$ converges to (x_n, x_{n+1}) , we see that $(x_n, x_{n+1}) \in G(b_n)$
 8 for each $n = 0, \dots, m-1$.

9 Since $x_m \notin P$, Lemma 4.2 gives that there is a unique $a \in \mathcal{A}$
 10 such that $(x_{m-1}, x_m) \in G(a)$, and therefore we must have $b_{m-1} =$
 11 $a = w_{m-1}$. Furthermore, since $x_{m-1} \in P$ and $x_m \notin P$, we see that
 12 $w_{m-1} \in \mathcal{A}_1$, which implies that $D_0(w_{m-1}) = \{x_{m-1}\}$. Then since
 13 $(y_{m-1}^k, y_m^k) \in G_0(b_{m-1}^k) = G_0(b_{m-1}) = G_0(w_{m-1})$ for all large enough k
 14 and $D_0(w_{m-1}) = \{x_{m-1}\}$, we see that $y_{m-1}^k = x_{m-1}$ for all large enough
 15 k .

16 We claim by backwards induction that for each $j = 0, \dots, m-1$, we
 17 have $b_j = w_j$ and $y_j^k = x_j$ for all large enough k . We have established
 18 the base case ($j = m-1$) in the preceding paragraph. Now suppose
 19 it holds for some $j+1$. Let U be given by Lemma 4.3 for the point
 20 (x_j, x_{j+1}) . By the inductive hypothesis, for all large enough k , we
 21 have $y_{j+1}^k = x_{j+1} \in P$. Also, for all large enough n , we must have
 22 $(y_j^k, y_{j+1}^k) \in U$ (since $\{(y_j^k, y_{j+1}^k)\}_{k=1}^\infty$ converges to (x_j, x_{j+1})). Then for
 23 all large enough k , we have $(y_j^k, x_{j+1}) \in U \cap G_0(b_j)$. By our choice of U ,
 24 we must have that $b_j = w_j$ and $y_j^k = x_j$ for all large enough k , which
 25 completes the induction. $\square$

26 **Lemma 4.5.** *Let $m \geq 1$. Suppose that $x = x_0, \dots, x_m \in [0, 1]^{m+1}$ is*
 27 *a finite trajectory of F such that $x_m \in [0, 1] \setminus P$. Let w be the unique*
 28 *element of $\mathcal{L}_m$ such that $(x, w) \in \mathcal{S}_m$. If the sequence $\{(y^k, b^k)\}_{k=1}^\infty$ is*
 29 *in $\mathcal{S}_m$ and converges to (x, b) in $[0, 1]^{m+1} \times \mathcal{A}^m$, then $b = w$.*

30 *Proof.* As $\mathcal{A}^m$ has the discrete topology, we must have that $b^k = b$ for all
 31 large enough k . Then for all large enough k , we have $(y_n^k, y_{n+1}^k) \in G(b_n)$,
 32 which is closed, and therefore $(x_n, x_{n+1}) \in G(b_n)$.

33 Observe that if $(x_n, x_{n+1}) \in G(F) \setminus (P \times P)$, then $b_n = w_n$ by
 34 Lemma 4.2. Now suppose that we have some n such that $(x_n, x_{n+1}) \in$
 35 $P \times P$. Then there exists $N \in [n+2, m]$ such that $x_j \in P$ for all
 36 $j = n, \dots, N-1$ and $x_N \notin P$. Thus $x_n, \dots, x_N$ satisfies the conditions
 37 of Lemma 4.4, and we conclude that $b_n = w_n$. $\square$

5. CONSTRUCTION OF THE JOINT SYSTEM AND FACTOR MAPS

Let F be a Markov multi-map in $\mathcal{F}$ with associated trajectory space X and SFT Σ_M . In the following section, we introduce a topological dynamical system by taking limits of special finite labeled trajectories. We call this system the *joint system*. Then in Sections 5.2 and 5.3, we show that the joint system is in fact a common extension of X and Σ_M . The joint system and its factor maps onto X and Σ_M are central to the construction of the Borel entropy conjugacy in our proof of Theorem 1.1. We establish their key properties in this section.

5.1. The joint system. Let F be a Markov multi-map in $\mathcal{F}$ with associated SFT Σ_M . Here we define a subset V of the product space $[0, 1]^{\mathbb{Z}_+} \times \Sigma_M$, which will serve as a common extension of the trajectory space X and the SFT Σ_M .

Definition 5.1. Let F be in $\mathcal{F}$ with associated trajectory space X and SFT Σ_M . Define a set $V = V(F) \subset [0, 1]^{\mathbb{Z}_+} \times \Sigma_M$ as follows. A pair $(x, \mathbf{a}) \in [0, 1]^{\mathbb{Z}_+} \times \Sigma_M$ is in V if there exists a sequence $\{\ell_k\}_{k=1}^\infty$ of natural numbers tending to infinity and a sequence $\{(y^k, a^k)\}_{k=1}^\infty$ of special finite labeled trajectories, with $(y^k, a^k) \in \mathcal{S}_{\ell_k}$, such that for each $n \geq 0$, the sequence $\{(y_n^k, a_n^k)\}_{k=1}^\infty$ converges to (x_n, a_n) in $[0, 1] \times \mathcal{A}$.

Proposition 5.2. V is closed and invariant under the left shift.

Proof. Suppose that $(x^m, \mathbf{a}^m)$ is a sequence in V that converges in $[0, 1]^{\mathbb{Z}_+} \times \Sigma_M$ to $(x, \mathbf{a})$. For each m , we have that $(x^m, \mathbf{a}^m) \in V$, and therefore there exists a sequence of natural numbers $\{\ell(m, k)\}_{k=1}^\infty$ tending to infinity and a sequence of special finite labeled trajectories $(y^{m,k}, b^{m,k}) \in \mathcal{S}_{\ell(m,k)}$ such that for each m and n ,

$$\lim_k b_n^{m,k} = a_n^m, \quad \text{and} \quad \lim_k y_n^{m,k} = x_n^m.$$

To complete the proof, we exhibit a sequence $\{\ell_j\}_{j=1}^\infty$ of natural numbers and a sequence $\{(z^j, c^j)\}_{j=1}^\infty$ of special finite labeled trajectories to demonstrate that $(x, \mathbf{a}) \in V$.

Let $j \geq 1$. First choose m_j such that for all $n = 0, \dots, j$, we have $a_n^{m_j} = a_n$ and

$$|x_n^{m_j} - x_n| < \frac{1}{2j}.$$

Next choose k_j (depending on m_j) such that $\ell(m_j, k_j) \geq j$ and for all $n = 0, \dots, j$, we have $b_n^{m_j, k_j} = a_n^{m_j}$ and

$$|y_n^{m_j, k_j} - x_n^{m_j}| < \frac{1}{2j}.$$

1 Finally, let $\ell_j = j$, and define

$$z^j = y_0^{m_j, k_j}, \dots, y_j^{m_j, k_j}$$

2 and

$$c^j = b_0^{m_j, k_j} \dots b_j^{m_j, k_j}.$$

3 Then $\{\ell_j\}_{j=1}^\infty$ tends to infinity and $\{(z^j, c^j)\}_{j=1}^\infty$ is a sequence of spe-
 4 cial finite labeled trajectories. Furthermore, for each n , we have that
 5 $\{(z_n^j, c_n^j)\}_{j=1}^\infty$ converges to (x_n, a_n) in $[0, 1] \times \mathcal{A}$. We have thus exhibited
 6 the necessary sequences to establish that $(x, \mathbf{a}) \in V$.

7 To establish shift invariance, suppose that $(x, \mathbf{a}) \in V$. Let us show
 8 that $(\sigma(x), \sigma(\mathbf{a})) \in V$. There exists natural numbers $\{\ell_k\}_{k=1}^\infty$ and spe-
 9 cial finite trajectories $\{(y^k, a^k)\}_{k=1}^\infty$ that witness the fact that $(x, \mathbf{a}) \in$
 10 V . Define $z_n^k = y_{n+1}^k$ and $b_n^k = a_{n+1}^k$. Then the sequences $\{\ell_k - 1\}_{k=1}^\infty$
 11 and $\{(z^k, b^k)\}_{k=1}^\infty$ establish that $(\sigma(x), \sigma(\mathbf{a})) \in V$. $\square$

12 As V is invariant under the left shift, we define $\sigma_V : V \rightarrow V$ by
 13 letting $\sigma_V(x, \mathbf{a}) = (\sigma(x), \sigma(\mathbf{a}))$.

14 In the proof of our main results, we use the joint space V as an
 15 intermediary between the spaces X and Σ_M . To make this connection
 16 precise, we define factor maps from V onto each of X and Σ_M .

17 **5.2. Factoring onto Σ_M .** Here we show that the joint space V from
 18 Definition 5.1 factors onto Σ_M .

19 **Definition 5.3.** Let F be in $\mathcal{F}$ with associated trajectory space X ,
 20 SFT Σ_M , and joint space V . Define the map $\phi : V \rightarrow \Sigma_M$ by the rule
 21 $\phi(x, \mathbf{a}) = \mathbf{a}$.

22 It is clear that ϕ is continuous and commutes with the left shift.

23 *Remark 5.4.* Note that if $M(a, b) = 1$, then $f_a^{-1}(D_0(b)) \subset D_0(a)$. Fur-
 24 thermore, if $y \in D_0(b)$ and $x = f_a^{-1}(y)$, then $(x, y) \in G_0(a)$. Thus, if
 25 $a_0 \dots a_\ell \in \mathcal{L}_{\ell+1}$ and $y_\ell \in D_0(a_\ell)$, then for each $n = 0, \dots, \ell - 1$, we have

$$y_n = f_{a_n}^{-1} \circ \dots \circ f_{a_{\ell-1}}^{-1}(y_\ell) \in D_0(a_n),$$

26 and $(y_n, y_{n+1}) \in G_0(a_n)$.

27 **Proposition 5.5.** ϕ is surjective.

28 *Proof.* Let $\mathbf{a} \in \Sigma_m$. For each $\ell \geq 1$, let $y_\ell^\ell \in D_0(a_\ell)$ be arbitrary. For
 29 $n = 0, \dots, \ell - 1$, let $y_n^\ell = f_{a_n}^{-1} \circ \dots \circ f_{a_{\ell-1}}^{-1}(y_\ell^\ell)$. By Remark 5.4, for each
 30 $n = 0, \dots, \ell - 1$, we have $(y_n^\ell, y_{n+1}^\ell) \in G_0(a_n)$. Also, for each n , we have
 31 that $y_n^\ell \in [0, 1]$, which is sequentially compact. Thus, by a diagonal

1 argument, there exists a subsequence $\{\ell_k\}_{k=1}^\infty$ tending to infinity such
 2 that for each n , there exists $x_n \in [0, 1]$ such that

$$\lim_{k \rightarrow \infty} y_n^{\ell_k} = x_n.$$

3 Setting $x = (x_n)_{n=0}^\infty$, we see that $(x, \mathbf{a}) \in V$ and $\phi(x, \mathbf{a}) = \mathbf{a}$. $\square$

4 The following proposition asserts that ϕ preserves the entropy of
 5 ergodic measures. Its proof is an adaptation of the proof of [2, Theorem
 6 4.1], and we provide it in Appendix A for completeness.

7 **Proposition 5.6.** *Let $\phi : V \rightarrow \Sigma_M$ be as in Definition 5.3. Further-*
 8 *more, let $\mu \in \mathcal{M}_e(V, \sigma_V)$ and $\nu \in \mathcal{M}_e(\Sigma_M, \sigma_M)$ be such that $\nu = \mu \circ \phi^{-1}$.*
 9 *Then $h(\nu) = h(\mu)$.*

10 **5.3. Factoring onto X .** Here we show that the joint space V from
 11 Definition 5.1 factors onto X .

12 **Definition 5.7.** Let F be in $\mathcal{F}$ with associated trajectory space X ,
 13 SFT Σ_M , and joint space V . Define the map $\pi : V \rightarrow [0, 1]^{\mathbb{Z}_+}$ by the
 14 rule $\pi(x, \mathbf{a}) = x$.

15 It is clear that π is continuous and commutes with the left shift. The
 16 following result shows that the image of π is contained in X .

17 **Proposition 5.8.** *Suppose that $(x, \mathbf{a}) \in V$. Then $x \in X$.*

18 *Proof.* Let $n \geq 0$. Since $(x, \mathbf{a}) \in V$, there exists y_n^k and y_{n+1}^k such that
 19 $\lim_k y_n^k = x_n$, $\lim_k y_{n+1}^k = x_{n+1}$, and $(y_n^k, y_{n+1}^k) \in G(a_n)$. Since $G(a_n)$
 20 is closed, we see that $(x_n, x_{n+1}) \in G(a_n)$ for each $n \geq 0$. Then by the
 21 definition of X , we have $x \in X$. $\square$

22 By Proposition 5.8, we have $\pi : V \rightarrow X$. Next we establish that π
 23 in fact maps *onto* X . First, let $V_0 \subset V$ be the set of points $(x, \mathbf{a}) \in V$
 24 such that for each $n \geq 0$, we have $(x_n, x_{n+1}) \in G_0(a_n)$.

25 **Proposition 5.9.** *For each $x \in X$, there exists a unique $\mathbf{a} \in \Sigma_M$ such*
 26 *that $(x, \mathbf{a}) \in V_0$. In particular, $\pi : V \rightarrow X$ is surjective.*

27 *Proof.* Let $x = (x_n)_{n=0}^\infty \in X$. Let $n \geq 0$. Since $(x_n, x_{n+1}) \in G(F)$
 28 and $\{G_0(a) : a \in \mathcal{A}\}$ is a partition of $G(F)$, there is a unique element
 29 $a_n \in \mathcal{A}$ such that $(x_n, x_{n+1}) \in G_0(a_n)$. This uniquely defines a sequence
 30 $\mathbf{a} = (a_n)_{n=0}^\infty$.

31 Let us show that $\mathbf{a} \in \Sigma_M$. Since Σ_M is a SFT defined by the matrix
 32 M , it suffices to show that for each $n \geq 1$, we have $M(a_{n-1}, a_n) = 1$.
 33 Let $n \geq 1$. By construction, we have that $(x_{n-1}, x_n) \in G_0(a_{n-1})$ and
 34 $(x_n, x_{n+1}) \in G_0(a_n)$. Then $x_n \in R_0(a_{n-1})$ and $x_n \in D_0(a_n)$, and

1 therefore $D_0(a_n) \cap R_0(a_{n-1}) \neq \emptyset$. By the Markov property, we conclude
 2 that $D_0(a_n) \subset R_0(a_{n-1})$, and therefore $M(a_{n-1}, a_n) = 1$, as desired.
 3 Finally, note that $(x, \mathbf{a}) \in V$. Indeed, for each $k \geq 1$, let $\ell_k = k$,
 4 $y_n^k = x_n$ and $b_n^k = a_n$. Then we have exhibited the necessary sequences
 5 to establish that $(x, \mathbf{a}) \in V$. $\square$

6. CONSTRUCTING THE BAD SETS

7 Our aim is to show that under certain conditions, we can construct a
 8 Borel entropy conjugacy between X and Σ_M . In this construction, we
 9 identify “bad sets”, on which the Borel entropy conjugacy map will not
 10 be defined. The main source of difficulty in constructing our Borel en-
 11 tropy conjugacy arises from the fact that points in the trajectory space
 12 that stay in the critical set P can have multiple symbolic codings. In
 13 order to deal with this difficulty, we group such symbolic codings into
 14 the “bad sets” and show that we have only removed sets of strictly
 15 smaller entropy than the full system. In fact, we carry out this process
 16 for each irreducible component of Σ_M separately. In the following sec-
 17 tion, we define the critical set of points in X that cause us difficulty.
 18 Then in the following sections we analyze the irreducible components
 19 in detail and construct their bad sets.

20 **6.1. The critical system.** Let F be in $\mathcal{F}$ with trajectory space X ,
 21 SFT σ_M , and joint system V . Consider the set of trajectories contained
 22 in the critical set P :

$$X_P = \{x \in X : \forall n \geq 0, x_n \in P\}.$$

23 Note that X_P is closed and invariant under σ_X . We refer to X_P as
 24 the critical system. Now let $Z = \pi^{-1}(X_P) \subset V$, and note that Z is
 25 closed and invariant under σ_V . As we mentioned above, one of the
 26 main difficulties in relating X and Σ_M lies in the fact that π may not
 27 be injective on Z (or its pre-images under the shift).

28 **6.2. Irreducible components.** We find it useful to distinguish be-
 29 tween the following types of irreducible components for Markov multi-
 30 maps.

31 **Definition 6.1.** Let F be in $\mathcal{F}$ with associated SFT Σ_M . Let $\mathcal{C} \subset \mathcal{A}$
 32 be an irreducible component of the M -graph. We say that

- 33 • $\mathcal{C}$ is of Type I if $\mathcal{C} \subset \mathcal{A}_0$;
- 34 • $\mathcal{C}$ is of Type II if $\mathcal{C} \subset \mathcal{A}_2$;
- 35 • $\mathcal{C}$ is of Type III if it is not Type I or Type II.

1 *Remark 6.2.* Suppose $\mathcal{C}$ is of Type III. Then for each $i \in \{0, 1, 2\}$, we
 2 must have $\mathcal{C} \cap \mathcal{A}_i \neq \emptyset$. In fact, there must exist allowable transitions
 3 in $\mathcal{C}$ from $\mathcal{A}_0$ to $\mathcal{A}_2$ (cross-over), from $\mathcal{A}_2$ to $\mathcal{A}_1$ (into a vertical line),
 4 and from $\mathcal{A}_1$ to $\mathcal{A}_0$ (out of vertical line).

5 Let $\Sigma_M(\mathcal{C})$ denote the irreducible component of Σ_M corresponding
 6 to $\mathcal{C}$. Note that $\Sigma_M(\mathcal{C})$ is an SFT contained in Σ_M . Also, for distinct
 7 irreducible components $\mathcal{C}_1$ and $\mathcal{C}_2$, we have that $\Sigma_M(\mathcal{C}_1)$ and $\Sigma_M(\mathcal{C}_2)$
 8 are disjoint. Let $V(\mathcal{C})$ denote $\phi^{-1}(\Sigma_M(\mathcal{C})) \subset V$, where V is the joint
 9 system. Also, let $Z(\mathcal{C}) = Z \cap V(\mathcal{C})$, where $Z = \pi^{-1}(X_P) \subset V$.

10 **6.3. Constructing the bad sets: Types I and III.** We now show
 11 the existence of our “bad sets” off of which ϕ and π are injective. In
 12 the proof of the following proposition, we use the following immediate
 13 consequence of Lemma 4.5: if $(x, \mathbf{a}), (x, \mathbf{b}) \in V$ and $x_m \notin P$, then for
 14 each $n < m$, we have $a_n = b_n$. Also, for notation, for any word $w \in \mathcal{L}$
 15 and any $\mathbf{a} \in \Sigma_M$, let

$$N_w(\mathbf{a}) = |\{n \geq 0 : \sigma^n(\mathbf{a}) \in [w]\}|.$$

16 **Proposition 6.3.** *Let F be in $\mathcal{F}$ with SFT Σ_M and joint system V .
 17 Suppose that $\mathcal{C}$ is a Type I or Type III irreducible component of the M -
 18 graph such that $h_{\text{top}}(\Sigma_M(\mathcal{C}), \sigma_M|_{\Sigma_M(\mathcal{C})}) > 0$. Then there exists words u^c
 19 and u^a in $\mathcal{L}(\mathcal{C})$ such that if*

$$B_0 = \{\mathbf{a} \in \Sigma_M(\mathcal{C}) : N_{u^c}(\mathbf{a}) < \infty \text{ or } N_{u^a}(\mathbf{a}) < \infty\},$$

20 and $B = \phi^{-1}(B_0)$, then

- 21 (1) $\text{Pre}(Z(\mathcal{C})) \subset B$,
- 22 (2) $h_{\text{prob}}(B) < h_{\text{top}}(V(\mathcal{C}), \sigma|_{V(\mathcal{C})})$, and
- 23 (3) both π and ϕ are injective on $V(\mathcal{C}) \setminus B$.

24 *Proof.* First, suppose that $\mathcal{C}$ is Type I. Since F is in $\mathcal{F}$, it has a complete
 25 set of coding words, and we may select a coding word u^c for $\mathcal{C}$. Similarly,
 26 since F is in $\mathcal{F}$, it has a complete set of avoiding words, and then since
 27 $\mathcal{C}$ is of Type I, we may select an avoiding word u^a for $\mathcal{C}$.

28 Now suppose that $\mathcal{C}$ is Type III. Since $\mathcal{C}$ is of Type III, it contains
 29 a word $u^a = w_0 w_1$ such that $w_0 \in \mathcal{A}_0$ and $w_1 \in \mathcal{A}_1 \cup \mathcal{A}_2$. Note that u^a
 30 is an avoiding word. Furthermore, since $\mathcal{C}$ is of Type III, it contains a
 31 symbol $u^c \in \mathcal{A}_1$. Note that u^c is a coding word for $\mathcal{C}$.

32 For the remainder of the proof, we do not distinguish between whether
 33 $\mathcal{C}$ is Type I or Type III.

34 Then let

$$B_0 = \{\mathbf{a} \in \Sigma_M(\mathcal{C}) : N_{u^c}(\mathbf{a}) < \infty \text{ or } N_{u^a}(\mathbf{a}) < \infty\},$$

35 and let $B = \phi^{-1}(B_0)$. (Note that B_0 and B are invariant.)

1 To establish (1), let $(x, \mathbf{a}) \in \text{Pre}(Z(\mathcal{C}))$. Then there exists N such
 2 that for each $n \geq N$, we have $x \in I_{\sigma^n(\mathbf{a})} \cap P$. Since u^a is an avoiding
 3 word, we see that $N_{u^a}(\mathbf{a}) < \infty$. It follows that $\mathbf{a} \in B_0$, and therefore
 4 $(x, \mathbf{a}) \in B$.

5 Now we establish (2). Let $Y \subset \Sigma_M$ be the SFT obtained by for-
 6 bidding u^c and u^a . Since $\Sigma_M(\mathcal{C})$ is irreducible, it is entropy minimal.
 7 Then $h_{\text{top}}(Y, \sigma|_Y) < h_{\text{top}}(\Sigma_M(\mathcal{C}), \sigma_M|_{\Sigma_M(\mathcal{C})})$, as Y is a strict subsys-
 8 tem of $\Sigma_M(\mathcal{C})$. Suppose μ is an ergodic measure on $\Sigma_M(\mathcal{C})$ such that
 9 $\mu(B_0) = 1$. As μ is ergodic and the words u^c and u^a appear only
 10 finitely for points in B_0 , we must have $\mu([u^c]) = \mu([u^a]) = 0$, and
 11 therefore $\mu(Y) = 1$. Then by the variational principle, we see that
 12 $h(\mu) \leq h_{\text{top}}(Y, \sigma|_Y)$. Taking the supremum over all such μ , we ob-
 13 tain that $h_{\text{prob}}(B_0) \leq h_{\text{top}}(Y, \sigma|_Y) < h_{\text{top}}(\Sigma_M(\mathcal{C}), \sigma_M|_{\Sigma_M(\mathcal{C})})$. Further-
 14 more, since ϕ preserves the entropy of ergodic measures (by Proposition
 15 5.6), we obtain that $h_{\text{prob}}(B) = h_{\text{prob}}(B_0) < h_{\text{top}}(\Sigma_M(\mathcal{C}), \sigma_M|_{\Sigma_M(\mathcal{C})}) =$
 16 $h_{\text{top}}(V(\mathcal{C}), \sigma_V|_{V(\mathcal{C})})$.

17 To show that ϕ is injective on $V(\mathcal{C}) \setminus B$, let $(x, \mathbf{a}) \in V(\mathcal{C}) \setminus B$, and
 18 suppose $(y, \mathbf{a}) \in V(\mathcal{C}) \setminus B$. Then $\mathbf{a} \notin B_0$, and in fact $\sigma^n(\mathbf{a}) \notin B_0$ for
 19 all $n \geq 0$. Let $n \geq 0$. Then $\sigma^n(\mathbf{a})$ contains the word u^c infinitely many
 20 times, and therefore $I_{\sigma^n(\mathbf{a})}$ is a singleton (since u^c is a coding word).
 21 Since we must have both $x_n \in I_{\sigma^n(\mathbf{a})}$ and $y_n \in I_{\sigma^n(\mathbf{a})}$, we conclude that
 22 $x_n = y_n$. As $n \geq 0$ was arbitrary, we have shown that ϕ is injective on
 23 $V(\mathcal{C}) \setminus B$.

24 To show that π is injective on $V(\mathcal{C}) \setminus B$, let $(x, \mathbf{a}), (x, \mathbf{b}) \in V(\mathcal{C}) \setminus B$.
 25 Let $T = \{m \geq 0 : \sigma^m(\mathbf{a}) \in [u^a]\}$. For each $m \in T$, we have that
 26 $x_m \in I_{\sigma^m(\mathbf{a})} \subset [0, 1] \setminus P$ (since u^a is an avoiding word). Since $(x, \mathbf{a}) \in$
 27 $V(\mathcal{C}) \setminus B$, the set T must be infinite. Let $n \geq 0$. Since T is infinite,
 28 there exists $m > n$ such that $m \in T$. Then $x_m \notin P$. By Lemma 4.5,
 29 we see that $a_n = b_n$. As $n \geq 0$ was arbitrary, we conclude that π is
 30 injective on $V(\mathcal{C}) \setminus B$. $\square$

31 **6.4. Constructing the bad sets: Type II.** We don't have to re-
 32 move any bad sets from Type II components. Indeed, the following
 33 proposition establishes that π and ϕ are injective on the union of all
 34 Type II components.

35 **Proposition 6.4.** *Let F be in $\mathcal{F}$, and let*

$$V_P = \bigcup_{\mathcal{C} \text{ of Type II}} V(\mathcal{C}).$$

36 *Then π and ϕ are injective on V_P .*

1 *Proof.* Suppose $(x, \mathbf{a}), (x, \mathbf{b}) \in V_P$. Then $a_n, b_n \in \mathcal{A}_2$ for all $n \geq 0$,
 2 and we must have $G(a_n) = \{(x_n, x_{n+1})\} = G(b_n)$ for all n . Therefore
 3 $a_n = b_n$ for all $n \geq 0$, and π is injective on V_P .
 4 Suppose that $(x, \mathbf{a}), (y, \mathbf{a}) \in V_P$. Then $D(a_n)$ is a singleton for each
 5 n , and we must have $\{x_n\} = D(a_n) = \{y_n\}$ for all n . Therefore $x_n = y_n$
 6 for all $n \geq 0$, and ϕ is injective on V_P . $\square$

7. PROOF OF THE MAIN RESULT

8 Now that we have constructed the bad sets for each type of irre-
 9 ducible component, we are ready to prove our main result on Borel
 10 entropy conjugacy.

11 **PROOF OF THEOREM 1.1.** Let F be in $\mathcal{F}$ with associated trajectory
 12 space X and SFT Σ_M . Furthermore, let V be the associated joint
 13 space, as in Definition 5.1, and let $\phi : V \rightarrow \Sigma_M$ and $\pi : V \rightarrow X$ be the
 14 maps defined in Definitions 5.3 and 5.7, respectively.

15 Since $F \in \mathcal{F}$, we have that Σ_M has positive entropy. Enumerate
 16 the irreducible components with positive entropy: $\mathcal{C}_1, \dots, \mathcal{C}_J$. For each
 17 $\mathcal{C}_j$ of Type I or Type III, let $B_j \subset V(\mathcal{C}_j)$ be the bad set given by
 18 Proposition 6.3. For each $\mathcal{C}_j$ of Type II, let $B_j = \emptyset$. Furthermore, let

$$B_0 = \phi^{-1} \left(\Sigma_M \setminus \left(\bigcup_{j=1}^J \Sigma_M(\mathcal{C}_j) \right) \right).$$

19 Then let

$$B = \bigcup_{j=0}^J B_j.$$

20 For each $j = 1, \dots, J$, let $A_j = V(\mathcal{C}_j) \setminus B_j$. Note that

$$(7.1) \quad V \setminus B = \bigcup_{j=1}^J A_j.$$

21 **Proposition 7.1.** π is injective on $V \setminus B$.

22 *Proof.* Suppose that $(x, \mathbf{a}), (x, \mathbf{b}) \in V \setminus B$. By (7.1), there exists i, j
 23 such that $(x, \mathbf{a}) \in A_i$ and $(x, \mathbf{b}) \in A_j$. If $x_n \notin P$ for infinitely many n ,
 24 then $\mathbf{a} = \mathbf{b}$ by Lemma 4.5.

25 Now suppose that $x_n \in P$ for all but finitely many n . Then there
 26 exists N such that $\sigma^N(x) \in X_P$. Hence $(x, \mathbf{a}), (x, \mathbf{b}) \in \text{Pre}(Z)$, and
 27 therefore $\mathcal{C}_i$ and $\mathcal{C}_j$ must be of Type II (since $A_k \cap Z = \emptyset$ whenever $\mathcal{C}_k$
 28 is of Type I or Type III). Since π is injective on V_P , we conclude that
 29 $\mathbf{a} = \mathbf{b}$. $\square$

1 **Proposition 7.2.** ϕ is injective on $V \setminus B$.

2 *Proof.* Suppose that $(x, \mathbf{a}), (y, \mathbf{a}) \in V \setminus B$. By (7.1), there exists i, j
 3 such that $(x, \mathbf{a}) \in A_i$ and $(y, \mathbf{a}) \in A_j$. Then $\mathbf{a} \in \Sigma_M(\mathcal{C}_i) \cap \Sigma_M(\mathcal{C}_j)$.
 4 Since distinct irreducible components are disjoint, we see that $i = j$.
 5 Since ϕ is injective on A_i , we conclude that $x = y$. $\square$

6 **Lemma 7.3.** $h_{\text{top}}(X, \sigma_X) = h_{\text{top}}(V, \sigma_V)$.

7 *Proof.* First, by Proposition 5.8, we have that π is a factor map. Since
 8 entropy cannot increase under a factor map, $h_{\text{top}}(X, \sigma_X) \leq h_{\text{top}}(V, \sigma_V)$.
 9 Now fix $\mathcal{C}_i$ such that $h_{\text{top}}(V, \sigma_V) = h_{\text{top}}(V(\mathcal{C}_i), \sigma|_{V(\mathcal{C}_i)})$, and let μ
 10 be an ergodic measure on $V(\mathcal{C}_i)$ such that $h(\mu) = h_{\text{top}}(V(\mathcal{C}_i), \sigma|_{V(\mathcal{C}_i)})$
 11 (which exists $\Sigma_M(\mathcal{C}_i)$ has a measure of maximal entropy and ϕ pre-
 12 serves entropy). Since $h_{\text{prob}}(B_i) < h_{\text{top}}(V(\mathcal{C}_i), \sigma|_{V(\mathcal{C}_i)}) = h(\mu)$, we must
 13 have that $\mu(B_i) = 0$. Then π is injective a set of full μ -measure, and
 14 therefore π is an isomorphism from μ to $\pi\mu = \mu \circ \pi^{-1}$. In particu-
 15 lar, $h_{\text{top}}(V, \sigma|_V) = h_{\text{top}}(V(\mathcal{C}_i), \sigma|_{V(\mathcal{C}_i)}) = h(\mu) = h(\pi\mu) \leq h_{\text{top}}(X, \sigma|_X)$,
 16 where the last inequality follows from the Variational Principle. We
 17 have now shown that $h_{\text{top}}(X, \sigma_X) = h_{\text{top}}(V, \sigma_V)$. $\square$

18 Let $A_X = \pi(V \setminus B)$ and $A_\Sigma = \phi(V \setminus B)$.

19 **Proposition 7.4.** A_X is Borel, $\sigma(A_X) = A_X$, and $h_{\text{prob}}(X \setminus A_X) <$
 20 $h_{\text{top}}(X, \sigma|_X)$.

21 *Proof.* Consider A_i . First suppose that $\mathcal{C}_i$ is of Type II. Then $A_i =$
 22 $V(\mathcal{C}_i)$, which is compact. Thus $\pi(A_i)$ is also compact. In particular,
 23 $\pi(A_i)$ is closed and hence Borel.

24 Now suppose that $\mathcal{C}_i$ is of Type I or Type III. Then there exist words
 25 u and v in $\mathcal{L}(\mathcal{C}_i)$ (in particular, a coding word and any avoiding word)
 26 such that

$$A_i = \bigcap_N \left[\left(\bigcup_{n \geq N} \sigma^{-n}[u] \right) \cap \left(\bigcup_{n \geq N} \sigma^{-n}[v] \right) \right].$$

27 Note that for each n , the sets $[u]$ and $[v]$ are compact. Hence $\pi[u]$ and
 28 $\pi[v]$ are compact and in particular closed. Then

$$\pi(A_i) = \bigcap_N \left[\left(\bigcup_{n \geq N} \sigma^{-n} \pi[u] \right) \cap \left(\bigcup_{n \geq N} \sigma^{-n} \pi[v] \right) \right],$$

29 which shows that $\pi(A_i)$ is Borel. Finally, since $A_X = \cup_i \pi(A_i)$, we
 30 conclude that A_X is Borel.

31 For each A_i , we have $\sigma(A_i) = A_i$, and therefore $\sigma(\pi(A_i)) = \pi(\sigma(A_i)) =$
 32 $\pi(A_i)$. As $A_X = \sqcup_i \pi(A_i)$, we see that $\sigma(A_X) = A_X$.

1 Let ν be an ergodic invariant measure on X such that $\nu(X \setminus A_X) > 0$.
 2 Since A_X is invariant and ν is ergodic, we have that $\nu(X \setminus A_X) = 1$,
 3 and therefore $\nu(A_X) = 0$. Also, ν is supported on some set of the form
 4 $\pi(B_i)$, with $1 \leq i \leq J$. Let μ be an ergodic measure on V such that
 5 $\pi\mu = \nu$. Then $\mu(A) \leq \mu(\pi^{-1}\pi(A)) = \nu(A_X) = 0$, and $\mu(V(\mathcal{C}_i)) =$
 6 1 . Therefore $\mu(B_i) = 1$. Finally, we observe that $h(\nu) \leq h(\mu) \leq$
 7 $h_{\text{prob}}(B_i) \leq \max_i h_{\text{prob}}(B_i)$. Since the right hand side is strictly less
 8 than $h_{\text{top}}(V, \sigma_V)$, which equals $h_{\text{top}}(X, \sigma_X)$ by Lemma 7.3, we conclude
 9 that $h_{\text{prob}}(X \setminus A_X) < h_{\text{top}}(X, \sigma_X)$. $\square$

10 The following proposition may be quite easily deduced from the def-
 11 initions, and we omit its proof.

12 **Proposition 7.5.** A_Σ is Borel, $\sigma(A_\Sigma) = A_\Sigma$, and $h_{\text{prob}}(\Sigma_M \setminus A_\Sigma) <$
 13 $h_{\text{prob}}(\Sigma_M)$.

14 Now define $\psi = \pi|_{V \setminus B} \circ \phi|_{V \setminus B}^{-1} : A_\Sigma \rightarrow A_X$, which will serve as our
 15 Borel entropy conjugacy map.

16 **Proposition 7.6.** ψ is bijective, bi-measurable, and commutes with the
 17 left shift.

18 *Proof.* Taken together, Propositions 7.1 and 7.2 yield that ψ is bijective.
 19 Let $E \subset A_X$ be Borel. Then $\pi^{-1}(E) \cap (V \setminus B)$ is Borel. Also, since
 20 $\phi|_{V \setminus B}$ is an injective continuous map on the Borel set $V \setminus B$, it maps
 21 Borel sets to Borel sets. Therefore $\psi^{-1}(E) = \phi|_{V \setminus B}(\pi^{-1}(E) \cap (V \setminus B))$
 22 is Borel measurable. Therefore ψ is Borel measurable. An analogous
 23 argument shows that ϕ^{-1} is also Borel measurable. Finally, since π and
 24 ϕ commute with the left shift, ψ also commutes with the left shift. $\square$

25 By the previous propositions, we conclude that ψ is the desired Borel
 26 entropy conjugacy between X and Σ_M . $\square$

27 8. SUFFICIENT CONDITIONS FOR F TO BE IN $\mathcal{F}$

28 Now that we have proved Theorem 1.1, we wish to highlight its utility
 29 by establishing some straightforward conditions that are sufficient for a
 30 Markov multi-map F to be in the family $\mathcal{F}$. We focus on the case where
 31 there is an irreducible component $\mathcal{C}$ that contains all of $\mathcal{A}_0$. For single-
 32 valued functions, this condition amounts to the topological transitivity
 33 of the system.

34 **Definition 8.1.** Suppose $\mathcal{C}$ is an irreducible component. We say that
 35 F codes for points on $\mathcal{C}$ if

$$\limsup_n \max \{ \ell(I_{a_0 \dots a_n}) : \mathbf{a} \in \Sigma_M(\mathcal{C}) \} = 0.$$

1 **Lemma 8.2.** *Suppose $\mathcal{C}$ is an irreducible component with $\mathcal{A}_0 \subset \mathcal{C}$. If*
 2 *F codes for points on $\mathcal{C}$, then $\mathcal{C}$ has a coding word and an avoiding*
 3 *word.*

4 *Proof.* Since F codes for points on $\mathcal{C}$, by definition, we must have that
 5 $I_{\mathbf{a}}$ is a singleton for all $\mathbf{a} \in \Sigma_M(\mathcal{C})$. Therefore every word in $\mathcal{L}(\mathcal{C})$ is a
 6 coding word. To see that $\mathcal{C}$ also has an avoiding word, we consider two
 7 cases.

8 Case 1: Suppose $\mathcal{A}_0$ is a strict subset of $\mathcal{C}$. Then $\mathcal{C}$ must be a Type
 9 III component, and we showed in the proof of Proposition 6.3 that
 10 every Type III component has an avoiding word.

11 Case 2: Suppose $\mathcal{A}_0 = \mathcal{C}$. We have shown that $\mathcal{C}$ has a coding word,
 12 so there must exist $a, b \in \mathcal{A}_0$ such that $ab \in \mathcal{L}(\mathcal{A}_0)$ and I_{ab} is a strict
 13 subset of $I_a = D(a)$. This would imply that $D(b)$ is a strict subset of
 14 $R(a)$.

15 By the definition of a Markov multi-map, $D(b)$ is an interval between
 16 adjacent elements of the partition P . It follows that P partitions $R(a)$
 17 into at least two intervals, so there exist distinct elements $p_i, p_j \in P$
 18 such that $[p_i, p_{i+1}] \cup [p_j, p_{j+1}] \subseteq R(a)$. Then there must be $b_1, b_2 \in \mathcal{A}_0$
 19 such that $D(b_1) = [p_i, p_{i+1}]$ and $D(b_2) = [p_j, p_{j+1}]$.

20 The interval I_{ab_1} is a strict subset of I_a , so it contains at most one
 21 endpoint of $D(a)$. Since $\mathcal{A}_0$ is irreducible, there exists $u \in \mathcal{L}(\mathcal{A}_0)$
 22 such that $ab_1ua \in \mathcal{L}(\mathcal{A}_0)$. The interval I_{ab_1ua} is contained in I_{ab_1} , so
 23 it contains at most one endpoint of I_a . Then $I_{ab_1uab_1}$ and $I_{ab_1uab_2}$ are
 24 non-overlapping, so at least one of them is disjoint from P . Therefore
 25 $\mathcal{A}_0$ has an avoiding word. $\square$

26 Next we define what it means for F to be uniformly expanding on $\mathcal{C}$,
 27 and we show that if that is the case, then F codes for points on $\mathcal{C}$. Recall
 28 that for each $a \in \mathcal{A}$, we have a well-defined function $f_a^{-1}: R(a) \rightarrow D(a)$,
 29 and if $u = u_0 \cdots u_n \in \mathcal{L}$, then we define $f_u^{-1} = f_{u_0}^{-1} \circ \cdots \circ f_{u_n}^{-1}$.

30 **Definition 8.3.** Suppose $\mathcal{C}$ is an irreducible component and F is a
 31 Markov multi-map such that f_a is a diffeomorphism for each $a \in \mathcal{A}_0$.
 32 We say that F is uniformly expanding on $\mathcal{C}$ if there exists $N \in \mathbb{N}$ such
 33 that

$$\sup \{ |(f_u^{-1})'(x)| : u \in \mathcal{L}_N(\mathcal{C}) \cap (\mathcal{A}_0)^N, x \in D(u_N) \} < 1.$$

34 **Lemma 8.4.** *Let $\mathcal{C}$ be an irreducible component. If F is uniformly*
 35 *expanding on $\mathcal{C}$, then F codes for points on $\mathcal{C}$.*

36 *Proof.* Let $0 < \lambda < 1$ such that $|(f_u^{-1})'(x)| < \lambda$ for all $u = a_0 \cdots a_{N-1} \in$
 37 $\mathcal{L}_N(\mathcal{C})$ and $x \in R(a_{N-1})$. Then $\ell(I_u) \leq \lambda \ell(R(a_{N-1})) \leq \lambda$. It follows
 38 that for all $k \geq 1$ and $u \in \mathcal{L}_{kN}(\mathcal{C})$, we have $\ell(I_u) < \lambda^k$. Therefore F
 39 codes for points on $\mathcal{C}$. $\square$

1 By combining these results, we arrive at the following sufficient con-
 2 dition for F to be in $\mathcal{F}$.

3 **Corollary 8.5.** *Let F be a properly parametrized Markov multi-map*
 4 *with associated SFT Σ_M . Suppose that $h_{\text{top}}(\Sigma_M, \sigma_M) > 0$, and fur-*
 5 *thermore there is an irreducible component $\mathcal{C}$ with $\mathcal{A}_0 \subset \mathcal{C}$. If F is*
 6 *uniformly expanding on $\mathcal{C}$, then $F \in \mathcal{F}$, and hence (X, σ_X) is entropy*
 7 *conjugate to (Σ_M, σ_M) .*

8 *Proof.* By Lemma 8.4 and Lemma 8.2, the component $\mathcal{C}$ has a coding
 9 word and an avoiding word. Since $\mathcal{A}_0 \subset \mathcal{C}$, no irreducible component
 10 (except possibly $\mathcal{C}$) could be contained in $\mathcal{A}_0$, so F has a complete set
 11 of coding words and a complete set of avoiding words. Thus $F \in \mathcal{F}$, so
 12 by Theorem 1.1, (X, σ_X) is entropy conjugate to (Σ_M, σ_M) . $\square$

13 9. REALIZATION OF ENTROPIES

14 We now prove Theorem 1.5, which we restate here.

15 **Theorem 1.5.** *The set $\mathcal{H}(\mathcal{F})$ is equal to the set of all positive rational*
 16 *multiples of logarithms of Perron numbers.*

17 *Proof.* It suffices to show that for any irreducible SFT with positive
 18 entropy, there is a Markov multi-map in $\mathcal{F}$ with the same entropy.

19 Let Σ_M be an irreducible SFT with positive entropy associated with
 20 the $n \times n$ matrix M . Since Σ_M has positive entropy, there is one row
 21 of M with (at least) two ones. After possibly permuting the alphabet,
 22 suppose the first row has a one in columns k and $k + 1$.

23 Now we define a Markov multi-map F on the interval $[1, n + 2]$ in
 24 terms of its graph. (To illustrate our construction, we give a specific
 25 matrix M in Example 9.1, and we show that graph of the corresponding
 26 multi-map in Figure 2.)

27 Let

$$P = \left\{ 1, 1 + \frac{1}{2}, 2, 2 + \frac{1}{2}, \dots, n, n + \frac{1}{2}, n + 1, n + \frac{3}{2}, n + 2 \right\}.$$

28 For each $i, j \in \{1, \dots, n\}$, we associate the rectangle $[i, i + 1/2] \times [j, j +$
 29 $1/2]$ with the matrix entry $M(i, j)$. If $M(i, j) = 1$, we include (in the
 30 graph of F) a straight line connecting the bottom left corner (i, j) to
 31 the top right corner $(i + 1/2, j + 1/2)$, and if $M(i, j) = 0$, we leave that
 32 rectangle empty. There is one exception to this rule however. We have
 33 assumed that $M(1, k) = M(1, k + 1) = 1$, and instead of including two
 34 separate graphs in those two rectangles, we include one line connecting
 35 $(1, k)$ to $(1 + 1/2, k + 3/2)$.

1 In this way we would have the graph of a multi-map with domain
 2 $\bigcup_{i=1}^n [i, i + 1/2]$. We need F to be defined on all of $[1, n + 2]$, so we
 3 next define the graph in each rectangle of the form $[i + 1/2, i + 1] \times$
 4 $[n + 3/2, n + 2]$, where $i \in \{1, \dots, n\}$. In these rectangles, we include a
 5 straight line connecting the points $(i + 1/2, n + 3/2)$ and $(i + 1, n + 2)$.
 6 Then finally, in each of the rectangles $[n + 1, n + 3/2] \times [n + 3/2, n + 2]$
 7 and $[n + 3/2, n + 2] \times [n + 3/2, n + 2]$, we include a straight line connecting
 8 the bottom left corner to the top right corner.

9 We have described the graph of F , but in order to show it is a Markov
 10 multi-map in $\mathcal{F}$ we should specify the indexing set $\mathcal{A}$ and identify a
 11 coding word and an avoiding word. Let $\mathcal{C}_0$ be a labeling of all of the
 12 straight lines that correspond to ones in the matrix M . (Recall that
 13 the cardinality of $\mathcal{C}_0$ will be one less than the number of ones in M ,
 14 because the ones in the $(1, k)$ and $(1, k + 1)$ entries correspond to just
 15 one straight line in the graph.) Then let $\mathcal{B}_0$ be the additional straight
 16 lines whose ranges were all $[n + 3/2, n + 2]$, and define $\mathcal{A}_0 = \mathcal{C}_0 \cup \mathcal{B}_0$.

17 Each of the straight lines we considered have a bottom left endpoint
 18 and a top right endpoint. Let $\mathcal{C}_2$ and $\mathcal{B}_2$ be the collections of these
 19 left and right endpoints, respectively, and let $\mathcal{A}_2 = \mathcal{C}_2 \cup \mathcal{B}_2$. Finally let
 20 $\mathcal{A}_1 = \emptyset$.

21 Then $\mathcal{C}_0$ is a Type I irreducible component whose corresponding SFT
 22 has the same entropy as Σ_M . To complete the proof, we show that if
 23 $\Sigma(\mathcal{A})$ and $\Sigma(\mathcal{C}_0)$ are the SFTs associated with $\mathcal{A}$ and $\mathcal{C}_0$ respectively,
 24 then $h_{\text{top}}(\Sigma(\mathcal{A})) = h_{\text{top}}(\Sigma(\mathcal{C}_0))$. Towards this end, we show that the
 25 symbols in $\mathcal{B}_0, \mathcal{C}_2$, and $\mathcal{B}_2$ do not increase the entropy.

26 Let $b_0 \in \mathcal{B}_0$ represent the straight line in $[n + 3/2, n + 2] \times [n +$
 27 $3/2, n + 2]$, then any $b \in \mathcal{B}_0$ can only be followed by b_0 . This means
 28 $h_{\text{prob}}(\Sigma(\mathcal{A}_0)) = h_{\text{prob}}(\Sigma(\mathcal{C}_0))$. Now we consider $\mathcal{C}_2$ and $\mathcal{B}_2$. Each of
 29 these individually follows nearly the same pattern as $\mathcal{A}_0$ with only one
 30 difference. Let $a^* \in \mathcal{A}_0$ correspond to the straight line in $[1, 1/2] \times$
 31 $[k, k + 3/2]$, and let $c^* \in \mathcal{C}_2$ and $b^* \in \mathcal{B}_2$ correspond to the respective
 32 endpoints of this line. The symbol a^* can be followed by any symbol
 33 whose domain is $[k, k + 1/2]$ or $[k + 1, k + 3/2]$. On the other hand
 34 c^* can only be followed by points whose first coordinate is k , and b^*
 35 can only be followed by points whose first coordinate is $k + 3/2$. The
 36 SFTs corresponding to $\mathcal{C}_2$ and $\mathcal{B}_2$ are disjoint from one another and are
 37 invariant. It follows that the entropy contributed by these sets is less
 38 than or equal to the entropy from $\mathcal{C}_0$.

39 All of this shows that F is a Markov multi-map whose associated SFT
 40 has the same entropy as (Σ_M, σ_M) . It only remains to show that $F \in \mathcal{F}$.
 41 The only irreducible component in $\mathcal{A}_0$ with positive entropy is $\mathcal{C}_0$. We
 42 must show it has a coding word and an avoiding word. Once again let

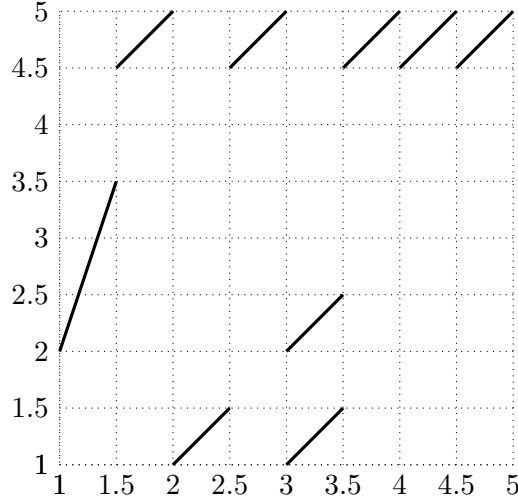


FIGURE 2. Markov multi-map from Example 9.1

1 $a^* \in \mathcal{A}_0$ correspond to the straight line in $[1, 1/2] \times [k, k + 3/2]$. The
 2 range $R(a^*)$ is partitioned by P into three non-overlapping intervals,
 3 so every occurrence of a^* in a word u decreases the length of I_u by a
 4 factor of 3. It follows that a^* is a coding word.

5 We can also use a^* to construct an avoiding word. Let $u = u_1 \cdots u_m \in$
 6 $\mathcal{L}(\mathcal{C}_0)$ be any word such that $a^*ua^* \in \mathcal{L}(\mathcal{C}_0)$. The interval I_{a^*u} is a strict
 7 subset of $[1, 1 + 1/2]$, so it contains at most one point of P . There is
 8 then an element $b \in \mathcal{C}_0$ such that $I_{a^*ua^*b}$ is disjoint from P and hence
 9 an avoiding word. Therefore $F \in \mathcal{F}$. $\square$

10 *Example 9.1.* Consider the 3×3 matrix

$$M = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 0 \end{pmatrix}.$$

11 Using the method outlined in the proof of Theorem 1.5, this matrix
 12 would yield the graph pictured in Figure 2. Recall we stipulated that
 13 there must be at least two adjacent 1s in the first row of the matrix.
 14 These appear in the second and third columns of M . This gives us a
 15 line in the graph connecting the points $(1, 2)$ and $(1.5, 3.5)$.

16 For the rest of the graph, note that if we rotate the matrix counter-
 17 clockwise ninety degrees, then the pattern of 1s in the matrix matches
 18 the pattern of lines in the lower portion of the graph.

10. EXAMPLES

We show various examples demonstrating the utility of our results. We begin by showing that Theorem 1.1 generalizes the well-known result for the case that F is single-valued.

Example 10.1. Suppose F is any uniformly expanding (single-valued) Markov map. Then Corollary 8.5 recovers the well-known fact that F is entropy conjugate to its combinatorial SFT.

Next we give an example of a Markov multi-map that is not uniformly expanding but still satisfies the hypotheses of Theorem 1.1.

Example 10.2. Let $P = \{0, 1/3, 2/3, 1\}$, $\mathcal{A}_0 = \{1, 2, 3, 4\}$, $\mathcal{A}_1 = \emptyset$, and $\mathcal{A}_2 = \{5, \dots, 10\}$. Let

$$\begin{array}{ll} D(1) = [0, 1/3] & R(1) = [1/3, 2/3] \\ D(2) = [1/3, 2/3] & R(2) = [0, 2/3] \\ D(3) = [1/3, 2/3] & R(3) = [2/3, 1] \\ D(4) = [2/3, 1] & R(4) = [1/3, 2/3]. \end{array}$$

For each $a \in \{1, 2, 3\}$, let $G(a)$ be a straight line from the bottom left corner to the top right corner of $D(a) \times R(a)$, and let $G(4)$ be a straight line from the top left to the bottom right of $D(4) \times R(4)$. Then we define $G(5) = \{(0, 1/3)\}$, $G(6) = \{(1/3, 2/3)\}$, $G(7) = \{(2/3, 1)\}$, $G(8) = \{(1/3, 0)\}$, $G(9) = \{(2/3, 1/3)\}$, $G(10) = \{(1, 1/3)\}$ (all of the endpoints of $G(1), \dots, G(4)$). This defines a Markov multi-map whose graph is pictured in Figure 3.

Then $\mathcal{A}_0$ and $\mathcal{A}_2$ are both irreducible components with $\mathcal{A}_0$ (a Type I component) having greater entropy. The graph $G(3)$ has slope 2, but the rest of the graphs $G(1), G(2)$, and $G(4)$ have slope 1, so F is not uniformly expanding on $\mathcal{A}_0$. However, $3 \in \mathcal{L}_1$ is a coding word, because each time the symbol 3 appears in a word $u \in \mathcal{L}$, the length of the interval I_u is divided in half. Also $331 \in \mathcal{L}_3$ is an avoiding word, because $I_{331} = [3/6, 7/12]$. Thus $F \in \mathcal{F}$, so by Theorem 1.1 (X, σ_X) is entropy conjugate to (Σ_M, σ_M) .

Next we show an example with a Type III irreducible component.

Example 10.3. Let $P = \{0, 1/2, 1\}$, $\mathcal{A}_0 = \{1, 2\}$, $\mathcal{A}_1 = \{3, 4\}$, and $\mathcal{A}_2 = \{5, 6, 7, 8, 9\}$. Let

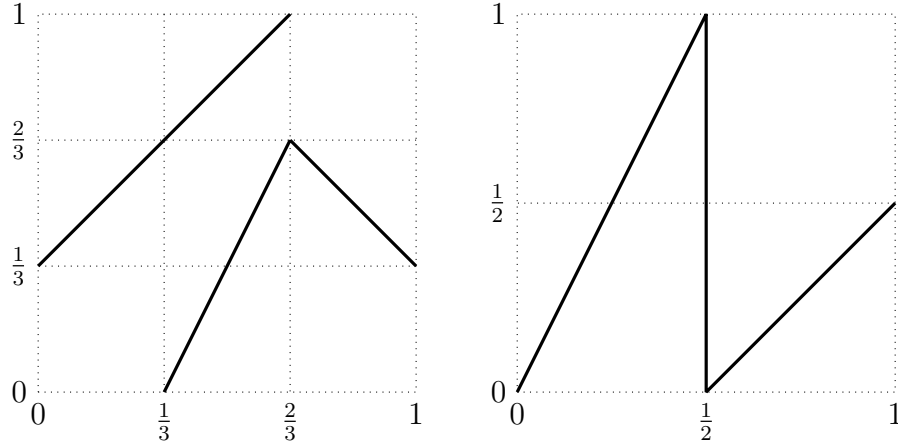


FIGURE 3. Markov multi-maps from Example 10.2 (left) and Example 10.3 (right)

$$\begin{array}{ll}
 D(1) = [0, 1/2] & R(1) = [0, 1] \\
 D(2) = [1/2, 1] & R(2) = [0, 1/2]
 \end{array}$$

Let $G(1)$ be the straight line connecting $(0, 0)$ and $(1/2, 1)$, and let $G(2)$ be the straight line connecting $(1/2, 0)$ and $(1, 1/2)$. Then let $G(3)$ and $G(4)$ be the vertical lines $\{1/2\} \times [0, 1/2]$ and $\{1/2\} \times [1/2, 1]$ respectively. Finally, define $G(5), \dots, G(9)$ so that they are the endpoints of the graphs of $G(1), \dots, G(4)$. The graph of this Markov multi-map is pictured in Figure 3.

In this case, two symbols from $\mathcal{A}_2$ represent the points $\{(0, 0)\}$ and $\{(1/2, 0)\}$. For simplicity, say these are $G(8)$ and $G(9)$. Then $\mathcal{C} = \{1, \dots, 7\}$ is a Type III irreducible component which means it must have a coding and an avoiding word. In this case, we can use $u = 13 \in \mathcal{L}_2$ as both a coding and an avoiding word, because $I_{13} = \{1/4\}$. Since there is no Type I component, we automatically have $F \in \mathcal{F}$.

Finally we give an example that does not satisfy our hypotheses, and for which $h_{\text{top}}(\Sigma_M, \sigma_M)$ is strictly greater than $h_{\text{top}}(X, \sigma_X)$.

Example 10.4. Define a Markov multi-map as follows. Let $P = \{0, 1\}$, $\mathcal{A}_0 = \{1, 2\}$, $\mathcal{A}_1 = \emptyset$, and $\mathcal{A}_2 = \{3, 4\}$. Let $D(1) = D(2) = R(1) = R(2) = [0, 1]$. Let $f_1, f_2: [0, 1] \rightarrow [0, 1]$ be defined by $f_1(x) = x^2$ and $f_2(x) = x^3$. Let $G(3) = \{(0, 0)\}$, and $G(4) = \{(1, 1)\}$.

1 Then the only non-trivial irreducible component is $\mathcal{A}_0 = \{1, 2\}$, and
 2 $\Sigma_M(\mathcal{A}_0)$ is the full shift on two symbols, which has entropy $\log 2$. How-
 3 ever, the only non-wandering points of (X, σ_X) are the fixed points
 4 $(0, 0, \dots)$ and $(1, 1, \dots)$, so $h_{\text{top}}(X, \sigma_X) = 0$.

5 Note that $I_u = [0, 1]$ for all $u \in \mathcal{A}_0$, so this multi-map has neither
 6 coding words nor avoiding words. Thus $F \notin \mathcal{F}$, and Theorem 1.1 does
 7 not apply.

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22 APPENDIX A. PROOF OF PROPOSITION 5.6

23 Here we aim to prove Proposition 5.6. First, we recall the result of
 24 Katok [16] relating the measure-theoretic entropy of an ergodic mea-
 25 sure to Bowen balls. Consider a compact metric space $(\mathcal{X}, d)$ and a
 26 continuous transformation $T : \mathcal{X} \rightarrow \mathcal{X}$. For $n \geq 1$, define the metric
 27 d_n on $\mathcal{X}$ by setting

$$d_n(x, y) = \max\{d(T^k(x), T^k(y)) : k = 0, \dots, n-1\}.$$

28 For $\epsilon > 0$, an (n, ϵ) -ball is a ball of radius ϵ with respect to the metric
 29 d_n . Now let μ be in $\mathcal{M}_e(\mathcal{X}, T)$. For $\alpha \in (0, 1)$, $\epsilon > 0$, and $n \geq 1$, let
 30 $s(T, n, \epsilon, \alpha)$ denote the minimal cardinality of a collection of (n, ϵ) -balls
 31 whose union has μ -measure at least α . Katok showed that

$$h(\mu) = \lim_{\epsilon \rightarrow 0^+} \limsup_n \frac{1}{n} \log s(T, n, \epsilon, \alpha).$$

32 Let us now prove that the factor map $\phi : V \rightarrow \Sigma_M$ preserves the
 33 entropy of all ergodic measures.

34 **PROOF OF PROPOSITION 5.6.** As entropy cannot increase under factor
 35 maps, we have $h(\nu) \leq h(\mu)$. To complete the proof, we establish the
 36 reverse inequality. Fix $\alpha \in (0, 1)$. For $n \geq 1$, let $r(n, \alpha)$ denote the

1 minimal cardinality of a set of words $W \subset \mathcal{L}_n$ such that

$$(A.1) \quad \nu\left(\bigcup_{w \in W} [w]\right) \geq \alpha.$$

2 Let $\epsilon > 0$. For $n \geq 1$, let $s(n, \epsilon, \alpha)$ denote the minimal cardinality of a
3 collection $\mathcal{U}$ of (n, ϵ) balls in V such that

$$\mu\left(\bigcup_{U \in \mathcal{U}} U\right) \geq \alpha.$$

4 Now let $n \geq 1$. Select a set $W = \{w_1, \dots, w_K\} \subset \mathcal{L}_n$ with cardinality
5 $K = r(n, \alpha)$ and satisfying (A.1). By the construction given in the
6 proof of [2, Theorem 4.1], for each k , there exists a collection $\mathcal{U}_k$ of
7 (n, ϵ) balls in V such that

$$\phi^{-1}([w_k]) \subset \bigcup_{U \in \mathcal{U}_k} U,$$

8 and

$$|\mathcal{U}_k| \leq (n+1) \left(\left\lceil \frac{1}{\epsilon} \right\rceil + 1 \right).$$

9 Let $\mathcal{U} = \cup_k \mathcal{U}_k$. Note that

$$\mu\left(\bigcup_{U \in \mathcal{U}} U\right) \geq \mu\left(\bigcup_{k=1}^K \phi^{-1}([w_k])\right) = \nu\left(\bigcup_{k=1}^K [w_k]\right) \geq \alpha,$$

10 and furthermore

$$|\mathcal{U}| \leq \sum_{k=1}^K |\mathcal{U}_k| \leq (n+1) \left(\left\lceil \frac{1}{\epsilon} \right\rceil + 1 \right) r(n, \alpha).$$

11 Hence

$$s(n, \epsilon, \alpha) \leq |\mathcal{U}| \leq (n+1) \left(\left\lceil \frac{1}{\epsilon} \right\rceil + 1 \right) r(n, \alpha).$$

12 Taking the limit supremum of this inequality as n tends to infinity
13 yields

$$\limsup_n \frac{1}{n} \log s(n, \epsilon, \alpha) \leq \limsup_n \frac{1}{n} \log r(n, \alpha).$$

14 By Katok [16], as we let ϵ tend to 0, we obtain

$$h(\mu) \leq h(\nu).$$

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