



Szegő and Widom Theorems for Finite Codimensional Subalgebras of a Class of Uniform Algebras

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Abstract

We establish versions of Szegő's distance formula and Widom's theorem on invertibility of (a family of) Toeplitz operators in a class of finite codimension subalgebras of uniform algebras, obtained by imposing a finite number of linear constraints. Each such algebra is naturally represented on a family of reproducing kernel Hilbert spaces, which play a central role in the proofs.

Keywords Toeplitz · Neil algebra · Uniform algebra · Reproducing Kernel · Widom · Szegő

1 Introduction

Let \mathbb{C} denote the complex plane, $\mathbb{D} = \{z \in \mathbb{C} : |z| < 1\}$ denote the unit disk, and let $\mathbb{T} = \{z \in \mathbb{C} : |z| = 1\}$ denote the unit circle in the complex plane (so that $\partial\mathbb{D} = \mathbb{T}$). Let t denote Lebesgue measure on \mathbb{T} and let $L^p = L^p(\mathbb{T})$ be the L^p spaces on \mathbb{T} with respect to the normalized measure $\frac{dt}{2\pi}$.

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Let $H^\infty(\mathbb{D})$ denote the bounded, analytic functions on \mathbb{D} and let $H^2(\mathbb{D})$ be the Hardy space of analytic functions on \mathbb{D} with square summable power series coefficients. For $p = 2, \infty$, we adopt the standard identification of $H^p(\mathbb{D})$ with $H^p(\mathbb{T})$, where $H^p(\mathbb{T})$ is viewed as the subspace of $L^p(\mathbb{T})$ containing functions f with vanishing negative Fourier coefficients.

Let $\mathcal{P}^+ = \text{span}\{e^{int} \mid n \in \mathbb{N}\}$ denote the analytic trigonometric polynomials and let $P^2(\mu)$ denote the $L^2(\mu)$ closure of \mathcal{P}^+ . With $P_0^2(\mu) = \{p \in P^2(\mu) \mid p(0) = 0\}$, the following is a result due to Szegő:

Theorem 1.1 (Szegő's Theorem (p. 49 in [18])). *If $\mu > 0$ is a finite measure on \mathbb{T} , then*

$$\inf \left\{ \int_{\mathbb{T}} |1 - p|^2 d\mu : p \in P_0^2(\mu) \right\} = \exp \left(\frac{1}{2\pi} \int_0^{2\pi} \log(h) dt \right),$$

where h is the Radon-Nikodym derivative of μ with respect to Lebesgue measure t .

This paper will generalize Szegő's theorem under the assumption that the measure μ is absolutely continuous with respect to Lebesgue measure with a strictly positive, continuous Radon-Nikodym derivative.

Widom's theorem provides a characterization of the invertibility of a Toeplitz operator with symbol $\phi \in L^\infty$ in terms of the distance from ϕ to H^∞ . Fix $\phi \in L^\infty$ and let $P: L^2 \rightarrow H^2$ be the orthogonal projection onto H^2 . Define $T_\phi: H^2 \rightarrow H^2$ be $Tf = P\phi f$. Such an operator is called a *Toeplitz operator* (with symbol ϕ).

Theorem 1.2 (Widom's Theorem (Theorem 7.30 in [13])). *Suppose $\phi \in L^\infty$ is unimodular. T_ϕ is left-invertible if and only if $\text{dist}(\phi, H^\infty) < 1$.*

Szegő [24] first established his result in 1920, while Widom [26] first established his result in 1960. Since then, different versions of both have been established for a variety of settings. Specifically, there are two types of generalizations that we focus on:

- (i) A change to the underlying set on which our functions are defined. In this vein, let Ω be a finite (connected) Riemann surface, and let $\mathcal{A}(\Omega)$ be the algebra of holomorphic functions on Ω . In this setting, we define H^2 to be the L^2 -closure of $\mathcal{A}(\Omega)$ with respect to the representing measure for a point in a nontrivial Gleason part.
- (ii) The introduction of finitely many algebraic constraints to our algebra of functions to yield a finite-codimensional subalgebra $A \subseteq \mathcal{A}(\Omega)$. As we will record in Theorem 2.1, if we pass to an arbitrary finite-codimensional subalgebra, then A arises via the successive application of finitely many algebraic constraints of the 2-point or Neil type.

For example, the classic disk algebra $A(\mathbb{D})$ (functions holomorphic on \mathbb{D} and continuous on \mathbb{T}) is yielded when $\Omega = \mathbb{D}$ and $A = A(\mathbb{D})$ (i.e., no algebraic constraints).

In the direction of (i), there have been a few generalizations established. For Szegő's result, we have the following: In 1965, Sarason [23] established a version

for the annulus. In 1967, Ahern and Sarason [4] established a version for hypo-Dirichlet algebras. For Widom's result, Abrahamse [1] established a version for multiply connected domains in 1974.

In the direction of (ii), Balasubramanian, McCullough, and Wijesooriya [7] established versions of both the Szegő and Widom results for the Neil Algebra, a constrained subalgebra of $H^\infty(\mathbb{D})$:

$$\mathfrak{A} = \{f \in H^\infty(\mathbb{D}) : f'(0) = 0\}.$$

The following is a brief overview of their results:

Let $S = \{(\alpha, \beta) \in \mathbb{C}^2 : |\alpha|^2 + |\beta|^2 = 1\}$ be the compact unit sphere in \mathbb{C}^2 . For $(\alpha, \beta) \in S$, define the following Hilbert spaces:

$$H_{\alpha, \beta}^2 = \{f \in H^2(\mathbb{D}) : f(0)\beta = f'(0)\alpha\}. \quad (1)$$

In [12], it is observed that these Hilbert spaces each carry a representation of \mathfrak{A} . They go on to show that each $H_{\alpha, \beta}^2$ is a reproducing kernel Hilbert space with kernel

$$k_w^{\alpha, \beta}(z) = k^{\alpha, \beta}(z, w) = (\alpha + \beta z)\overline{(\alpha + \beta w)} + \frac{z^2\overline{w^2}}{1 - \bar{z}w}$$

for $z, w \in \mathbb{D}$. It follows, via the the reproducing property, that

$$\|k_0^{\alpha, \beta}\|^2 = \langle k_0^{\alpha, \beta}, k_0^{\alpha, \beta} \rangle = k_0^{\alpha, \beta} = k^{\alpha, \beta}(0, 0) = |\alpha|^2.$$

Denote by \mathfrak{A}_0 those functions in \mathfrak{A} that vanish at 0. The following is a rewording of Theorem 1.3 in [7]:

Theorem 1.3 (Reformulated Szegő for \mathfrak{A}). *Suppose $\rho > 0$ is a continuous function on \mathbb{T} . Define constants:*

$$C_\rho = \frac{1}{2\pi} \int_0^{2\pi} \log(\rho) dt, \quad \lambda = \frac{\exp(C_\rho)}{2\pi} \int_0^{2\pi} \rho(t) \exp(-it) dt,$$

and $\sigma = \frac{1}{\sqrt{1 + |\lambda|^2}}(1, \lambda) \in S.$

Then,

$$\inf \left\{ \frac{1}{2\pi} \int_{\mathbb{T}} |1 - p|^2 \rho dt : p \in \mathfrak{A}_0 \right\} = \exp(C_\rho) \left(\frac{1}{\|k_0^\sigma\|^2} \right).$$

Observe that $\exp(C_\rho)$ is exactly the quantity that is found on the right hand side of Theorem 1.1.

We now record the Widom result for the Neil Algebra (Theorem 1.6 in [7]). For each $(\alpha, \beta) \in S$, let $P_{\alpha, \beta} : L^2 \rightarrow H_{\alpha, \beta}^2$ denote the orthogonal projection. Given $\phi \in L^\infty$,

define the operator $T_\phi^{\alpha, \beta} : H_{\alpha, \beta}^2 \rightarrow H_{\alpha, \beta}^2$ by $T_\phi^{\alpha, \beta} f = P_{\alpha, \beta} \phi f$. Such an operator is called the Toeplitz operator with symbol ϕ with respect to (α, β) . Let \mathfrak{A}^{-1} denote the collection of invertible elements of \mathfrak{A} .

Theorem 1.4 (Widom for Neil Algebra (Theorem 1.6 in [7])). *Suppose $\phi \in L^\infty$ is unimodular. $T_\phi^{\alpha, \beta}$ is left-invertible for each $(\alpha, \beta) \in S$ if and only if $\text{dist}(\phi, \mathfrak{A}) < 1$. In particular, $T_\phi^{\alpha, \beta}$ is invertible for each $(\alpha, \beta) \in S$ if and only if $\text{dist}(\phi, \mathfrak{A}^{-1}) < 1$.*

In the present work, we generalize these results in both of the directions (i) and (ii) described in the remarks proceeding the statement of Theorem 1.1. However, in the interest of clarity, we start by stating the results only for the topological generalization discussed in (i).

When changing one's underlying domain away from the open disk \mathbb{D} , topological complications arise. For example, when considering \mathbb{D} , we have that $L^2 = H^2 \oplus \overline{H_0^2}$. Passing to the finitely connected case, one finds that $H^2 \oplus \overline{H_0^2}$ is no longer all of L^2 , rather, there is an additional finite-dimensional defect space N such that $L^2 = H^2 \oplus \overline{H_0^2} \oplus N$. This defect space is tied to the number of holes in the domain and is the complexification of the space of real, regular Borel measures on $\partial\Omega$ that annihilate $\mathcal{A}(\Omega) + \overline{\mathcal{A}(\Omega)}$. Abrahamse, in his consideration of multiply connected domains, analyzed this defect space and made heavy use of a theorem that related the space $\overline{H_0^2} \oplus N$ to the space $\overline{v}^{-1} \overline{H^2}$, where v is a function related to the Green's function for Ω . Abrahamse then used a universal covering space and deck transformations to establish his Widom result. (For details on Abrahamse's work described here, see [1].) In our work, we will encounter the N -space and Green's function (see Sect. 4.1). However, to obtain our version of the Widom theorem, we will circumvent the use of a universal covering space by instead appealing to the machinery of Ahern and Sarason for hypo-Dirichlet algebras found in [4] (we review the relevant material in Sect. 2.2).

For a compact, Hausdorff space X , let $C(X)$ denote the continuous, complex-valued functions on X . Recall that a *uniform algebra* \mathcal{A} is a uniformly closed subalgebra of $C(X)$ which contains constants and separates points. When endowed with the sup norm $\|f\| = \sup\{|f(x)| : x \in X\}$, it becomes a Banach algebra. A classic example is the disk algebra $A(\overline{\mathbb{D}})$ of functions which are continuous on \mathbb{T} and extend to be analytic over \mathbb{D} . Let $M_{\mathcal{A}}$ denote its maximal ideal space. Given $x_0 \in M_{\mathcal{A}}$, let M_{x_0} denote the convex space of representing measures for x_0 . Finally, let P_{x_0} denote the Gleason part that contains x_0 . Gamelin [16] shows that under the following hypotheses: M_{x_0} is finite dimensional; the measure dm is taken from the relative interior of M_{x_0} ; all of the representing measures for x_0 are mutually absolutely continuous; P_{x_0} contains more than one point, \mathcal{A} can be viewed as an algebra of analytic functions defined on a finite (connected) Riemann surface. From this point forward, we fix x_0 and dm as above and let X denote the finite (connected) Riemann surface on which \mathcal{A} is defined. In this manner, we see that $\mathcal{A} = \mathcal{A}(X)$.

Let H^2 be the L^2 closure of \mathcal{A} and let $H_0^2 = \{f \in H^2 : \int_{\partial X} f dm = f(x_0) = 0\}$. Let H^∞ be the weak-* closure of \mathcal{A} in L^∞ . In the same spirit as Abrahamse, Gamelin showed in §5 of [16] that $L^2(dm) = H^2 \oplus \overline{H_0^2} \oplus N$ and $H^\infty = H^2 \cap L^\infty$, where N is a finite dimensional subspace of L^∞ arising from the complexification of a finite

dimensional real subspace of L^∞ . For every $n \in N$, let H_n^2 denote the standard H^2 space but endowed with the inner product given by

$$\langle f, g \rangle_n = \int_{\partial X} f \bar{g} e^n dm.$$

Defining the map $\pi_n: \mathcal{A} \rightarrow \mathcal{B}(H_n^2): f \mapsto M_f$, where $M_f: H_n^2 \rightarrow H_n^2: h \mapsto fh$, we have that π_n is an isometric homomorphism into the bounded linear operators on H_n^2 . In short, we say that each H_n^2 carries a representation for \mathcal{A} . We note that, while it is reasonable to discuss when two H_n^2 spaces are unitarily equivalent, we do not need such observations in this paper. In our consideration of all H_n^2 spaces, we allow ourselves redundancy. Each H_n^2 is a reproducing kernel Hilbert space with kernel given by k^n . Let $k_{x_0}^n$ denote said kernel evaluated at x_0 . With $\mathcal{A}_0 = \{f \in \mathcal{A} : \int_{\partial X} f dm = f(x_0) = 0\}$, the following is a Szegő result for \mathcal{A} :

Theorem 1.5 (Szegő Theorem for \mathcal{A}). *Suppose $\rho > 0$ is a continuous function on ∂X . Let $\xi \in H^2$, $\zeta \in \overline{H_0^2}$, $n \in N$ be functions such that $\log(\rho) = \xi \oplus \zeta \oplus n \in H^2 \oplus \overline{H_0^2} \oplus N$. With $C_\rho := \int_{\partial X} \log(\rho) dm$, it follows that*

$$\inf \left\{ \int_{\partial X} |1 - p|^2 \rho dm : p \in \mathcal{A}_0 \right\} = \exp(C_\rho) \left(\frac{1}{\|k_{x_0}^n\|^2} \right).$$

As mentioned earlier, the above theorem carries the assumption that the measure ρdm is absolutely continuous with respect to Lebesgue measure with a strictly positive, continuous Radon-Nikodym derivative ρ . In this vein, the above theorem is a generalization of Theorem 1.1 yielded by only changing the topological structure of the underlying domain. Wermser [25] shows that the uniform algebra \mathcal{A} , being an algebra of analytic functions defined on a finite (connected) Riemann surface, is a hypo-Dirichlet algebra. Thus, the above Szegő result is simply a reformulated special case of Ahern and Sarason's Theorem 10.1 in [4].

To state a Widom result for $\mathcal{A} = \mathcal{A}(X)$, we construct a slightly different family of Hilbert-Hardy spaces that carry representations for A . What will be important is that the family is parameterized by a *compact* parameter space. Since \mathcal{A} can also be viewed as a hypo-Dirichlet algebra, we can use the machinery developed in [4]. Let \mathcal{A}^{-1} denote the invertible elements in \mathcal{A} and let S_{x_0} denote the real linear space of the set of all differences between pairs of measures in M_{x_0} . Ahern and Sarason [4] record that, as a byproduct of \mathcal{A} being hypo-Dirichlet, no non-zero measure in S_{x_0} annihilates $\log(|\mathcal{A}^{-1}|)$ and S_{x_0} has finite dimension σ . Further, it follows that there are σ functions Z_1, \dots, Z_σ and σ measures ν_1, \dots, ν_σ in S_{x_0} such that $\int_{\partial X} \log(|Z_j|) d\nu_i = \delta_{ji}$. For $\alpha = (\alpha_1, \dots, \alpha_\sigma)$, define $|Z|^\alpha := |Z_1|^{\alpha_1} \cdots |Z_\sigma|^{\alpha_\sigma}$. In Sect. 2.3, we introduce a compact parameter space Σ such that, given $\alpha \in \Sigma$, the spaces H_α^2 – defined to be the usual H^2 space but endowed with the inner product given by

$$\langle f, g \rangle_\alpha = \int_{\partial X} f \bar{g} |Z|^\alpha dm$$

– each carries a representation for \mathcal{A} . As with the H_n^2 spaces, this representation is witnessed by the isometric homomorphism $\pi_\alpha: \mathcal{A} \rightarrow \mathcal{B}(H_\alpha^2): f \mapsto M_f$, where $M_f: H_\alpha^2 \rightarrow H_\alpha^2: h \mapsto fh$. In this case, however, our construction of the parameter space Σ will involve passing to a quotient space. As such, questions about the unitary equivalence of two H_α^2 spaces is more relevant. Proposition 2.5 in Sect. 2.3 establishes that two tuples α_1 and α_2 in Σ belong to the same equivalence class in Σ if and only if $H_{\alpha_1}^2$ and $H_{\alpha_2}^2$ are unitarily equivalent.

For $\phi \in L^\infty$, let M_ϕ denote the operator that multiplies by ϕ . For $\alpha \in \Sigma$, let $V_\alpha: H_\alpha^2 \rightarrow L_\alpha^2$ be the inclusion map. Thus, $P_\alpha = V_\alpha V_\alpha^*: L_\alpha^2 \rightarrow H_{\alpha,D}^2$ is the orthogonal projection onto H_α^2 . For a fixed $\phi \in L^\infty$, we define $T_\phi^\alpha: H_\alpha^2 \rightarrow H_\alpha^2$ by

$$T_\phi^\alpha = P_\alpha M_\phi = V_\alpha^* M_\phi V_\alpha.$$

Call T_ϕ^α the *Toeplitz operator with symbol ϕ with respect to α* . The following is the Widom theorem for \mathcal{A} :

Theorem 1.6 (Widom Theorem for \mathcal{A}). *Suppose $\phi \in L^\infty$ is unimodular. T_ϕ^α is left-invertible for each $\alpha \in \Sigma$ if and only if $\text{dist}(\phi, \mathcal{A}) < 1$. In particular, T_ϕ^α is invertible for each $\alpha \in \Sigma$ if and only if $\text{dist}(\phi, \mathcal{A}^{-1}) < 1$.*

When $X = \Omega$ is a multiply connected planar domain, the above theorem becomes Abrahamse's Theorem 4.1 in [1].

Theorems 1.5 and 1.6 are generalizations of the Szegő and Widom theorems when the underlying domain is changed to a finite (connected) Riemann surface. The other type of generalization is obtained by passing to a finite codimension subalgebra, obtained by imposing a finite number of linear constraints. The prototypical example for this is the Neil Algebra \mathfrak{A} . For the Neil Algebra (and therefore Theorems 1.3 and 1.4) the underlying domain is the disk $X = \mathbb{D}$.

To formulate the Szegő and Widom theorems in the constrained case, we again let $\mathcal{A} = \mathcal{A}(X)$ and now let $A \subseteq \mathcal{A}$ be a finite codimensional subalgebra with codimension d . Let $\Delta := \prod_1^d (\mathbb{C} \cup \{\infty\})$ and denote its elements by $D = (t_1, \dots, t_d)$. A theorem due to Gamelin (reproduced in this paper as Theorem 2.1) details explicitly how A is constructed from \mathcal{A} via inductively imposing algebraic constraints.

Within each H_n^2 , we develop a family of Hilbert-Hardy spaces that carry representations for A . This family, denoted $H_{n,D}^2$ with $(n, D) \in N \times \Delta$, are constructed iteratively from H_n^2 by encoding the algebraic constraints that built A from \mathcal{A} (see Sect. 2.4 for their exact construction). Each $H_{n,D}^2$ is a reproducing kernel Hilbert space with kernel given by $k^{n,D}$. Let $k_{x_0}^{n,D}$ denote said kernel evaluated at x_0 . With $A_0 = \{f \in A : \int_{\partial X} f dm = f(x_0) = 0\}$, the following is our Szegő result:

Theorem 1.7 (Szegő Theorem for A). *Suppose $\rho > 0$ is a continuous function on ∂X . Let $\xi \in H^2$, $\zeta \in H_0^2$, $n \in N$ be functions such that $\log(\rho) = \xi \oplus \zeta \oplus n \in H^2 \oplus H_0^2 \oplus N$. Let $D \in \Delta$ be the unique tuple such that $e^\xi \in H_{n,D}^2$. With $C_\rho := \int_{\partial X} \log(\rho) dm$, it follows that*

$$\inf \left\{ \int_{\partial X} |1-p|^2 \rho dm : p \in A_0 \right\} = \exp(C_\rho) \left(\frac{1}{\|k_{x_0}^{n,D}\|^2} \right).$$

To state our Widom result, we again use the H_α^2 spaces instead. Within each H_α^2 , we define a family of Hilbert-Hardy spaces $H_{\alpha,D}^2$ with $(\alpha, D) \in \Sigma \times \Delta$ such that each $H_{\alpha,D}^2$ carries a representation for A .

For $\phi \in L^\infty$, let M_ϕ denote the operator that multiplies by ϕ . For $(\alpha, D) \in \Sigma \times \Delta$, let $V_{\alpha,D} : H_{\alpha,D}^2 \rightarrow L_\alpha^2$ be the inclusion map. Thus, $P_{\alpha,D} = V_{\alpha,D} V_{\alpha,D}^* : L_\alpha^2 \rightarrow H_{\alpha,D}^2$ is the orthogonal projection onto $H_{\alpha,D}^2$. For a fixed $\phi \in L^\infty$, we define $T_\phi^{\alpha,D} : H_{\alpha,D}^2 \rightarrow H_{\alpha,D}^2$ by

$$T_\phi^{\alpha,D} = P_{\alpha,D} M_\phi = V_{\alpha,D}^* M_\phi V_{\alpha,D}.$$

Call $T_\phi^{\alpha,D}$ the *Toeplitz operator with symbol ϕ with respect to (α, D)* . Let A^{-1} denote the collection of invertible elements of A . The following is the Widom theorem for A :

Theorem 1.8 (Widom Theorem for A). *Suppose $\phi \in L^\infty$ is unimodular. $T_\phi^{\alpha,D}$ is left-invertible for each $(\alpha, D) \in \Sigma \times \Delta$ if and only if $\text{dist}(\phi, A) < 1$. In particular, $T_\phi^{\alpha,D}$ is invertible for each $(\alpha, D) \in \Sigma \times \Delta$ if and only if $\text{dist}(\phi, A^{-1}) < 1$.*

The remainder of the paper is devoted the proofs of Theorems 1.7 and 1.8. These theorems encode both generalizations due to a change in the underlying domain's topology, as well as those due the introduction of algebraic constraints. Some problems of this sort have been considered previously in the literature. In the case of the Neil algebra, a Pick-interpolation result has been established in [12] and an investigation into the spectrum of its Toeplitz operators has been carried out in [11]. More generally, for results related to constrained algebras, see [8,14,20–22], and [9]. In particular, in the special case when the underlying domain is the disk, a Widom-type invertibility theorem for families of Toeplitz operators in the constrained case was obtained by Anderson and Rochberg [6]. For results on multiply connected domains, see [8] and [3]. We also note that there has been work on a Szegő theorem in noncommutative settings. Specifically, where one considers Arveson subdiagonal algebras inside a finite von Neumann algebra. This setting generalizes $H^\infty(\mathbb{D})$ to a non-commutative H^∞ . For work in this direction, see [10] and [19].

1.1 Reader's Guide

In Sect. 2 we collect some preliminary material on hypo-Dirichlet algebras and their constrained subalgebras. Of particular importance will be the results of Ahern and Sarason, [4] and [5], on hypo-Dirichlet algebras and some results of Gamelin [16] on the structure of constrained subalgebras. In both cases we obtain families of reproducing kernel Hilbert spaces on the underlying domain, parameterized in a suitable way. In Sect. 3 we prove Theorem 1.7. Section 4 contains some additional preliminary material on families of Toeplitz operators, and finally Theorem 1.8 is proved in Sect. 5.

2 Setup

2.1 Finite-Codimensional Subalgebras A of \mathcal{A}

In this section we review Gamelin's characterization of finite codimension subalgebras, and fix some facts and notation that will be used in the sequel.

Let \mathcal{A} be a uniform algebra defined on X . Let $x_0 \in X$ and $dm \in M_{x_0}$ such that X is a finite (connected) Riemann surface.

Given a point $\theta \in X$, a *point derivation* at θ is a linear functional D_θ on \mathcal{A} which satisfies

$$D_\theta(fg) = f(\theta)D_\theta(g) + g(\theta)D_\theta(f).$$

A subalgebra $B \subseteq \mathcal{A}$ is a θ -subalgebra if there is a sequence of subalgebras $\mathcal{A} = A_0 \supseteq A_1 \supseteq \dots \supseteq A_k = B$ such that A_i is the kernel of a continuous point derivation D_i of A_{i-1} at θ . The following is an explicit description of all finite codimensional subalgebras A of \mathcal{A} :

Theorem 2.1 (Theorem 9.8 in [16]). *If $A \subseteq \mathcal{A}$ is a finite codimensional subalgebra, then A can be obtained from \mathcal{A} in two steps:*

(i) *There exists a finite number ℓ and, for $1 \leq i \leq \ell$, pairs of points $a_i, b_i \in X$ such that if*

$$B := \{f \in \mathcal{A} : f(a_i) = f(b_i) \text{ for all } 1 \leq i \leq \ell\},$$

then $A \subseteq B \subseteq \mathcal{A}$.

(ii) *There exists a finite number k , and, for $1 \leq j \leq k$, distinct points $c_j \in X$ and c_j -algebras B_j of B such that then $A = B_1 \cap \dots \cap B_k$.*

One may interpret the construction in the following way: All finite codimensional subalgebras A of \mathcal{A} are obtained by iteratively imposing a finite number of algebraic constraints. In particular, there exists a chain $A = A_d \subseteq A_{d-1} \subseteq \dots \subseteq A_1 \subseteq A_0 = \mathcal{A}$ such that at the i^{th} step

(i) $A_i = \{f \in A_{i-1} : f(a) = f(b)\}$ for some $a, b \in X$ or,
(ii) A_i is the kernel of a continuous point derivation of A_{i-1} at some point $c \in X$.

We will refer to the first constraint as *2-point constraint* and the second as a *Neil constraint*.

In this manner each A_i is a codimension one subalgebra of A_{i-1} and d is the codimension of A in \mathcal{A} . The chain of subalgebras $A = A_d \subseteq A_{d-1} \subseteq \dots \subseteq A_1 \subseteq A_0 = \mathcal{A}$ is called a *Gamelin chain*. Let Γ denote the set of points in X that the algebraic constraints are defined on. Let γ denote the total number of constrained values in the creation of A . Thus, given a function $f \in A$, we let $f_\Gamma \in \mathbb{C}^\gamma$ be the vector whose entries consist of f either evaluated at various points or its derivatives evaluated at various points (depending on how the points are encoded into the construction of A).

Example 2.2 Given a uniform algebra $A_0 := \mathcal{A}$,

$$A = \{f \in \mathcal{A} : f(a) = f(b) \text{ and } f'(c) = f'''(c) = 0\}$$

is a finite codimensional subalgebra. We can construct it in the following way: Construct $A_1 = \{f \in \mathcal{A} : f(a) = f(b)\} \subseteq \mathcal{A}$. The functional $D'_c : A_1 \rightarrow \mathbb{C} : f \mapsto f'(c)$ defines a continuous point derivation of A_1 at c . Put $A_2 = \ker(D'_c) = \{f \in A_1 : f'(c) = 0\}$. Now consider the functional $D'''_c : A_2 \rightarrow \mathbb{C} : f \mapsto f'''(c)$. Observe that, given $f, g \in A_2$, we have that $f'(c) = g'(c) = 0$ and thus

$$\begin{aligned} (fg)'''(c) &= f'''(c)g(c) + 3f''(c)g'(c) + 3f'(c)g''(c) + f(c)g'''(c) \\ &= f'''(c)g(c) + f(c)g'''(c). \end{aligned}$$

Therefore D'''_c defines a continuous point derivation of A_2 at c . With $A_3 = \ker(D'''_c) = \{f \in A_2 : f'''(c) = 0\}$, it follows that $A = A_3$. Further, we have $\Gamma = \{a, b, c\}$, $\gamma = 4$ and, given $f \in A$, $\Gamma_f = (f(a), f(b), f'(c), f'''(c))^\top \in \mathbb{C}^4$.

2.2 Hypo-Dirichlet Algebras

In [25], Wermer showed that algebras defined on finite (connected) Riemann surfaces are hypo-Dirichlet. In [4], Ahern and Sarason investigated these algebras in further detail. In this subsection, we reproduce the parts of their work that we'll use frequently.

Given our uniform algebra \mathcal{A} , let \mathcal{A}^{-1} denote the collection of its invertible elements. Now, \mathcal{A} being a hypo-Dirichlet algebra over X guarantees the following:

- (I) The real linear span of $\log(|\mathcal{A}^{-1}|)$ is uniformly dense in $C_{\mathbb{R}}(X)$ (the space of real, continuous functions on X);
- (II) The uniform closure of $\text{Re}(\mathcal{A})$ has finite codimension in $C_{\mathbb{R}}(X)$.

Algebras that obey property (I) are referred to as *logmodular algebras* (see, Sect. II.4 of [17]). It is the additional property (II) that distinguishes hypo-Dirichlet algebras. Letting S_{x_0} denote the real linear span of the set of all differences between pairs of measures in M_{x_0} , we observe that conditions (I) and (II) above imply the following local variants:

- (I') No non-zero measure in S_{x_0} annihilates $\log(|\mathcal{A}^{-1}|)$;
- (II') S_{x_0} has finite dimension σ .

By (II'), we can put $S_{x_0} = \text{span}_{\mathbb{R}}\{\mu_1, \dots, \mu_\sigma\}$. Corollary 1 in §3 in [4] shows that each μ_i is absolutely continuous with respect to dm . Now, put $\lambda_i := d\mu_i / dm$ and define

$$N := \text{span}_{\mathbb{C}}\{\lambda_1, \dots, \lambda_\sigma\}.$$

This N -space turns out to be the same space that was mentioned in the Introduction. Specifically, it is the same space that Gamelin discussed in §5 of [16]. Details on this space and its relation to algebras defined on multiply connected domains can be found in Sect. 4.5 of [15]. We reproduce the necessary information in Sect. 4.1.

It also follows from (I) and (II) that there are σ functions Z_1, \dots, Z_σ in \mathcal{A}^{-1} and σ measures ν_1, \dots, ν_σ in S_{x_0} such that

$$\int_{\partial X} \log(|Z_j|) d\nu_i = \delta_{ji}. \quad (2)$$

We will fix such functions and measures. A small note on notation: For $\alpha = (\alpha_1, \dots, \alpha_\sigma) \in \mathbb{R}^\sigma$, we define

$$|Z|^\alpha = |Z_1|^{\alpha_1} \cdots |Z_\sigma|^{\alpha_\sigma}.$$

Recalling that H^∞ is the weak-* closure of \mathcal{A} in L^∞ , the following lemma is an essential part of the investigations carried out by Ahern and Sarason:

Lemma 2.3 (Lemma 10.1 in [4]). *Let α be a σ -tuple in \mathbb{R}^σ . Then there is a function $h \in H^\infty$ such that $|h| = |Z|^\alpha$ almost everywhere.*

Borrowing from Ahern and Sarason, we will refer to a function $h \in H^p$ as an *inner function* if there exists an $\alpha \in \Sigma$ such that $|h| = |Z|^\alpha$. A function $g \in H^p$ is an *outer function* if $\log(|\int_{\partial X} g dm|) = \int_{\partial X} \log(|g|) dm > -\infty$. These inner functions contain zeros inside of X but, unlike the in the disk, are not unimodular on the boundary; however they do act as isometric multipliers between L_α^p spaces for different α 's.

For f , a function on X , we let $\int f d\nu$ denote the σ -tuple

$$\left(\int_{\partial X} f d\nu_1, \dots, \int_{\partial X} f d\nu_\sigma \right)$$

(provided each of the individual integrals exist). We then have the Ahern-Sarason inner-outer factorization:

Theorem 2.4 (Theorem 7.2 in [4]). *Let f be a function in H^p ($1 \leq p < \infty$ such that $|f|$ is log-integrable with respect to all representing measures in M_{x_0}). Then there are, in H^p , an outer function g and an inner function h such that $f = gh$ and $\int_{\partial X} \log(|g|) d\nu = (0, \dots, 0)$. The functions g and h are uniquely determined by f to within multiplicative constants of unit modulus.*

2.3 Representations for \mathcal{A}

With the notation inherited from the previous subsection, let

$$\mathcal{L} := \left\{ \int_{\partial X} \log(|h|) d\nu : h \in \mathcal{A}^{-1} \right\} \subseteq \mathbb{R}^\sigma.$$

Observe that, since each of the Z_j are in \mathcal{A}^{-1} , (2) shows that \mathcal{L} contains the standard basis vectors $e_j = (0, \dots, 0, 1, 0, \dots, 0)$ where the 1 occurs in the j^{th} entry. Thus \mathcal{L} is at least a σ -dimensional subgroup of \mathbb{R}^σ . Theorem 8.1 in [4] shows that \mathcal{L} is discrete

as well. Thus, not only is \mathcal{L} isomorphic to \mathbb{Z}^σ , but the quotient $\mathbb{R}^\sigma/\mathcal{L}$ is isomorphic to the σ -torus \mathbb{T}^σ . In particular, this quotient is compact. We will let Σ denote $\mathbb{R}^\sigma/\mathcal{L}$.

Given any α taken from any equivalence class in $[\alpha] \in \Sigma$, let H_α^2 be the usual H^2 space but endowed with the following inner product:

$$\langle f, g \rangle_\alpha = \int_{\partial X} f \bar{g} |Z|^\alpha dm. \quad (3)$$

As mentioned in the Introduction, each of these spaces carry a representation for \mathcal{A} . The following proposition establishes when two H_α^2 spaces are unitarily equivalent:

Proposition 2.5 *Given two σ -tuples α_1 and α_2 , they both belong to the same equivalence class in Σ if and only if $H_{\alpha_1}^2$ and $H_{\alpha_2}^2$ are unitarily equivalent.*

Proof To start, suppose $\alpha_1, \alpha_2 \in [\alpha] \in \Sigma = \mathbb{R}^\sigma/\mathcal{L}$. Then there exists $\ell \in \mathcal{L}$ such that $\alpha_1 = \alpha_2 + \ell$. In particular, $|Z|^{\alpha_1} = |Z|^{\alpha_2 + \ell}$ so that $|Z|^\ell = |Z|^{\alpha_1 - \alpha_2}$.

Since the function $|Z|^\ell$ is non-negative and in L^1 , it follows from Theorem 6.1 in [4] that there exists an outer function h in H^1 such that $|h| = |Z|^\ell$ almost everywhere. Since h is an outer function, it has no zeros inside X . The fact that $|h| = |Z|^\ell$ guarantees that h has no zeros on ∂X as well. Thus h is invertible in A such that $|h| = |Z|^\ell = |Z|^{\alpha_1 - \alpha_2}$. Thus $|Z|^{\alpha_1} = |h||Z|^{\alpha_2}$. It follows that the $H_{\alpha_1}^2$ and $H_{\alpha_2}^2$ are unitarily equivalent – witnessed by the multiplication operator $M_{|h|^{1/2}}$.

Conversely, suppose $H_{\alpha_1}^2$ and $H_{\alpha_2}^2$ are unitarily equivalent for σ -tuples α_1 and α_2 . Then there exists a unitary operator U such that, for all functions $\phi \in H^2$, $UM_\phi^1 = M_\phi^2$, where M_ϕ^i is the operator on $H_{\alpha_i}^2$ that multiplies by ϕ .

Now, let $k_w^i(z)$ be the reproducing kernel for $H_{\alpha_i}^2$. Observe that if $f \in H_{\alpha_i}^2$, then

$$\langle f, (M_\phi^i)^* k_w^i \rangle_2 = \langle M_\phi^i f, k_w^i \rangle_2 = \langle \phi f, k_w^i \rangle_2 = \phi(w) \langle f, k_w^i \rangle_2 = \langle f, \overline{\phi(w)} k_w^i \rangle_2.$$

Thus we yield the following eigenvector relationships:

$$(M_\phi^1)^* k_w^1 = \overline{\phi(w)} k_w^1 \quad \text{and} \quad (M_\phi^2)^* k_w^1 = \overline{\phi(w)} k_w^2.$$

These relationships immediately imply that $\ker((M_\phi^1)^* - \overline{\phi(w)} I) = \mathbb{C} k_w^1$ and $\ker((M_\phi^2)^* - \overline{\phi(w)} I) = \mathbb{C} k_w^2$. Since unitary maps map kernel spaces to one another, we must have $U k_w^1 = f(w) k_w^2$, where $f(w)$ is a scalar valued function in \mathcal{A} dependent only on w . In a reproducing kernel Hilbert space, it suffices to show equality on the kernels, therefore $U = M_f$. We also have that $U^{-1} = M_{f^{-1}}$. Therefore the unitary operator U is given by multiplication by the invertible function f .

It follows that $|Z|^{\alpha_1} = |f||Z|^{\alpha_2}$. Taking logs and integrating both sides shows that $\ell_f := \int_{\partial X} \log(|f|) d\nu = \alpha_1 - \alpha_2$. Thus, α_1 and α_2 differ by the coordinate of an invertible element of A – meaning $\alpha_1 - \alpha_2 \in \mathcal{L}$. This puts α_1 and α_2 in the same equivalence class in Σ . \square

Remark 2.6 In light of Proposition 2.5, we will denote by α the corresponding equivalence class $[\alpha] \in \Sigma = \mathbb{R}^\sigma/\mathcal{L}$.

As already mentioned in the Introduction, there is another way to construct representation-carrying spaces for \mathcal{A} (albeit, in a manner that does not produce a compact space of parameters). For $n \in N$, let H_n^2 denote the standard H^2 space but with the inner product defined by

$$\langle f, g \rangle_n = \int_X f \bar{g} e^n dm.$$

Each H_n^2 defines a reproducing kernel Hilbert space and carries a representation for \mathcal{A} .

2.4 Representations for A

Let A be a finite codimensional subalgebra of \mathcal{A} generated via the Gamelin chain $A = A_d \subseteq A_{d-1} \subseteq \dots \subseteq A_1 \subseteq A_0 = \mathcal{A}$. While the representations $\pi_n: \mathcal{A} \rightarrow \mathcal{B}(H_n^2): f \mapsto M_f$ and $\pi_\alpha: \mathcal{A} \rightarrow \mathcal{B}(H_\alpha^2)$ clearly give representations of \mathcal{A} , it is less obvious how to construct spaces $H_{n,D}^2 \subseteq H_n^2$ and $H_{\alpha,D}^2 \subseteq H_\alpha^2$ which are invariant under M_f for $f \in A \subseteq \mathcal{A}$ (but not necessarily invariant for $f \in \mathcal{A}$) and thereby generate a richer class of representations $\pi_{n,D}: f \mapsto M_f|_{H_{n,D}^2}$ and $\pi_{\alpha,D}: f \mapsto M_f|_{H_{\alpha,D}^2}$ for $f \in A$, the subalgebra of \mathcal{A} . We take care of this issue next.

This construction is formally the same whether we work inside H_n^2 or H_α^2 ; therefore in describing the construction we temporarily write H^2 to mean either H_n^2 or H_α^2 and use the notation H_D^2 to mean either $H_{n,D}^2$ or $H_{\alpha,D}^2$ depending on the choice of meaning for the notation H^2 .

The representations will be built inductively via the Gamelin chain. A_1 can be constructed from $A_0 = \mathcal{A}$ in one of two ways:

- (i) $A_1 = \{f \in A_0 : f(a) = f(b)\}$ for some $a, b \in X$ or,
- (ii) $A_1 = \{f \in A_0 : f'(c) = 0\}$ for some $c \in X$

If (i) occurs, then we form

$$H_{t_1}^2 = \{f \in H^2 : f(a) = t_1 f(b)\} = \{k_a^0 - t_1 k_b^0\}^\perp \subseteq H^2$$

where $t_1 \in \mathbb{C} \cup \{\infty\}$, and k_a^0 and k_b^0 are the reproducing kernels in H^2 at a and b respectively. Observe that $H_{t_1}^2$ is invariant for A_1 and hence $H_{t_1}^2$ carries a representation for A_1 .

If (ii) occurs, then we form

$$H_{t_1}^2 = \{f \in H^2 : f(c) = t_1 f'(c)\} = \{k_c^0 - t_1 k_{c(1)}^0\}^\perp \subseteq H^2,$$

where $t_1 \in \mathbb{C} \cup \{\infty\}$, k_c^0 is the reproducing kernel in H^2 at c , and $k_{c(1)}^0$ is the reproducing function in H^2 that returns a function's first derivative at c . It follows from the Liebniz rule that $H_{t_1}^2$ is invariant for A_1 and hence $H_{t_1}^2$ carries a representation for A_1 .

Proceeding in this manner along the Gamelin chain, we assume that $H_{t_{i-1}}^2$ holds a representation for A_{i-1} . A_i can only be built from A_{i-1} in one of two ways:

- (i) $A_i = \{f \in A_{i-1} : f(a) = f(b)\}$ for some $a, b \in X$ or,
- (ii) A_i is the kernel of a continuous point derivation D_c of A_{i-1} at some point $c \in X$.

If (i) occurs, then we form

$$H_{t_i}^2 = \{f \in H_{t_{i-1}}^2 : f(a) = t_i f(b)\} = \{k_a^{i-1} - t_i k_b^{i-1}\}^\perp \subseteq H_{t_{i-1}}^2,$$

where $t_i \in \mathbb{C} \cup \{\infty\}$, and k_a^{i-1} and k_b^{i-1} are the reproducing kernels in $H_{t_{i-1}}^2$ at a and b respectively. We claim that $H_{t_i}^2$ is invariant for A_i . Since $A_i \subseteq A_{i-1}$ and $A_{i-1}H_{t_{i-1}}^2 \subseteq H_{t_{i-1}}^2$, it follows that $A_i H_{t_{i-1}}^2 \subseteq H_{t_{i-1}}^2$. Finally, given $g \in A_i$ and $f \in H_{t_i}^2$, we have that $(fg)(a) = f(a)g(a) = t_i f(b)g(b)$ and thus $fg \in H_{t_i}^2$. This shows that $H_{t_i}^2$ is invariant for A_i hence $H_{t_i}^2$ carries a representation for A_i .

If (ii) occurs at the i^{th} iteration. In this case, there exists a natural number n such that $A_i = \ker(D_c) = \{f \in A_{i-1} : D_c(f) = f^{(n)}(c) = 0\}$. Form

$$H_{t_i}^2 = \{f \in H_{t_{i-1}}^2 : f(c) = t_i f^{(n)}(c)\} = \{k_c^{i-1} - t_i k_{c^{(n)}}^{i-1}\}^\perp \subseteq H_{t_{i-1}}^2,$$

where $t_i \in \mathbb{C} \cup \{\infty\}$, k_c^{i-1} is the reproducing kernel in $H_{t_{i-1}}^2$ at c , and $k_{c^{(n)}}^{i-1}$ is the reproducing function in $H_{t_{i-1}}^2$ that returns a function's n^{th} derivative at c . We claim that this Hilbert space is invariant for A_i .

As before, we know $A_i H_{t_{i-1}}^2 \subseteq H_{t_{i-1}}^2$. We need only show that, if $g \in A_i$ and $f \in H_{t_i}^2$, then $(fg)(c) = t_i(fg)^{(n)}(c)$. To see this, first take $f \in M := \{f \in A_i : f(c) = t_i f^{(n)}(c)\} \subseteq H_{t_i}^2$. Observe that, since $fg \in A_{i-1}$, the fact that D_c is a continuous point derivation shows that

$$\begin{aligned} t_i(fg)^{(n)}(c) &= t_i D_c(fg) = t_i(D_c(f)g(c) + D_c(g)f(c)) \\ &= t_i(f^{(n)}(c)g(c) + g^{(n)}(c)f(c)). \end{aligned} \tag{4}$$

However, since $g \in A_i$ and $f \in M$,

$$t_i(f^{(n)}(c)g(c) + g^{(n)}(c)f(c)) = t_i f^{(n)}(c)g(c) = f(c)g(c) = (fg)(c). \tag{5}$$

(4) and (5) show that $(fg)(c) = t_i(fg)^{(n)}(c)$. However, since M is dense in $H_{t_i}^2$, it follows that if $g \in A_i$ and $f \in H_{t_i}^2$, then $fg \in H_{t_i}^2$ – guaranteeing that $H_{t_i}^2$ is invariant for A_i and hence $H_{t_i}^2$ carries a representation for A_i .

Thus, by induction, we have built a reproducing kernel Hilbert space $H_{t_d}^2$ that carries a representation for $A = A_d$. In particular, it is constructed by building a chain of Hilbert spaces

$$H_{t_d}^2 \subseteq H_{t_{d-1}}^2 \subseteq \dots \subseteq H_{t_1}^2 \subseteq H_{t_0}^2 = H^2$$

where each $H_{t_i}^2$ is a codimension-1 subspace of $H_{t_{i-1}}^2$ and each $H_{t_i}^2$ carries a representation for A_i . Thus, our representations for A are parametrized by the d -tuple $(t_1, \dots, t_d) \in \prod_1^d (\mathbb{C} \cup \{\infty\})$.

As mentioned in the Introduction, we will denote the compact product $\prod_1^d (\mathbb{C} \cup \{\infty\})$ by Δ and its tuples by D . Further, given a tuple $D = (t_1, \dots, t_d)$, we will instead denote by H_D^2 the space $H_{t_d}^2$ that carries the representation for A .

We now introduce a multiplication on Δ which makes Δ an algebra. Let $D = (t_1, \dots, t_d)$ and $\tilde{D} = (s_1, \dots, s_d)$ both be tuples in Δ . Let $f \in H_D^2$ and $g \in H_{\tilde{D}}^2$. It follows that the product fg will belong to $H_{\tilde{D}}^2$ where $\tilde{D} = (r_1, \dots, r_d)$ is defined as follows:

$$(\tilde{D})_i := r_i = \begin{cases} t_i s_i & \text{if the } i^{\text{th}} \text{ constraint in the Gamelin chain is a 2-point constraint} \\ \frac{1}{t_i + s_i} & \text{if the } i^{\text{th}} \text{ constraint in the Gamelin chain is a Neil constraint} \end{cases}$$

In this manner, \tilde{D} is uniquely defined. Next, given a function $f \in H_D^2$ where $D = (t_1, \dots, t_d)$, we have that (provided it exists) $f^{-1} \in H_{D^{-1}}^2$ where D^{-1} is given by

$$(D^{-1})_i = \begin{cases} \frac{1}{t_i} & \text{if the } i^{\text{th}} \text{ constraint in the Gamelin chain is a 2-point constraint} \\ -t_i & \text{if the } i^{\text{th}} \text{ constraint in the Gamelin chain is a Neil constraint} \end{cases}$$

Lastly, we will denote by D_Γ the d -tuple defined by:

$$(D_\Gamma)_i = \begin{cases} 1 & \text{if the } i^{\text{th}} \text{ constraint in the Gamelin chain is a 2-point constraint} \\ \infty & \text{if the } i^{\text{th}} \text{ constraint in the Gamelin chain is a Neil constraint} \end{cases}$$

Note that the parameter ∞ is interpreted as the constraint $f(a) = \infty \cdot f^{(n)}(a)$ – equivalently, those functions such that $f^{(n)}(a) = 0$. Therefore, the functions in the space $H_{D_\Gamma}^2$ are then functions that simply obey the constraints imposed on A . We quickly note here that, given any $f \in H_D^2$, if f^{-1} exists, then $ff^{-1} = 1 \in H_{D_\Gamma}^2$.

The following lemma is now straightforward:

Lemma 2.7 *If $f, g \in H_D^2$, then, provided g^{-1} exists, $fg^{-1} \in H_{D_\Gamma}^2$*

Finally we note that Σ and Δ , with their natural topologies, are compact metric spaces.

3 The Szegő Theorem for Constrained Algebras

In this section we detail a few lemmas before exhibiting a proof of Theorem 1.7. The first of which is straightforward to see:

Lemma 3.1 *Given a real-valued $h \in H^2 \oplus \overline{H_0^2}$, if $h(x_0) = 0$, then there exists $\xi \in H^2$ such that $h = \xi \oplus \xi^* \in H^2 + \overline{H_0^2}$. In particular, $\xi(x_0) = 0$ as well.*

Lemma 3.2 *Suppose $\rho > 0$ is a continuous function on ∂X . If $\int_{\partial X} \log(\rho) dm = 0$, then there exists $\xi \in H^2$ and $n \in N$ such that $\log(\rho) = \xi \oplus \xi^* \oplus n \in H^2 \oplus \overline{H_0^2} \oplus N$, where $\xi(x_0) = 0$.*

Proof To begin with, let $\log(\rho) = f \oplus g \oplus n \in H^2 \oplus \overline{H_0^2} \oplus N$. Let P denote the orthogonal projection from L^2 onto H^2 . Observe that, since m is a representing measure for x_0 and $1 \in H^2$,

$$\begin{aligned} \int_{\partial X} \log(\rho) dm &= \langle \log(\rho), 1 \rangle_2 = \langle \log(\rho), P1 \rangle_2 \\ &= \langle P \log(\rho), 1 \rangle_2 = \langle f, 1 \rangle_2 = \int_{\partial X} f dm = f(x_0). \end{aligned}$$

Having assumed that $\int_X \log(\rho) dm = 0$, it follows that $f(x_0) = 0$.

Now, since $\log(\rho)$ is real-valued, we have that $f \oplus g \in H^2 \oplus \overline{H_0^2}$ is also real valued. By Lemma 3.1, there exists $\xi \in H_0^2$ such that $f \oplus g = \xi \oplus \xi^* \in H_0^2 \oplus \overline{H_0^2} \subseteq H^2 \oplus \overline{H_0^2}$. Therefore

$$\log(\rho) = \xi \oplus \xi^* \oplus n \in H^2 \oplus \overline{H_0^2} \oplus N$$

with $\xi(x_0) = 0$. □

Lemma 3.3 *Suppose $\rho > 0$ is a continuous function on ∂X . Put $\tilde{\rho} := e^c \rho$ for some constant c . Let ξ, ζ, n and $\tilde{\xi}, \tilde{\zeta}, \tilde{n}$ be taken such that*

$$\log(\rho) = \xi \oplus \zeta \oplus n \quad \text{and} \quad \log(\tilde{\rho}) = \tilde{\xi} \oplus \tilde{\zeta} \oplus \tilde{n},$$

where both decompositions are occurring in $H^2 \oplus \overline{H_0^2} \oplus N$. If $D, \tilde{D} \in \Delta$ are chosen so that e^ξ and $e^{\tilde{\xi}}$ are in $H_{n,D}^2$ and $H_{\tilde{n},\tilde{D}}^2$ respectively, then $n = \tilde{n}$ and $D = \tilde{D}$ so that $H_{n,D}^2 = H_{\tilde{n},\tilde{D}}^2$ and, in particular, $k_{x_0}^{n,D} = k_{x_0}^{\tilde{n},\tilde{D}}$

Proof Since $\tilde{\rho} = e^c \rho$, we have $\log(\tilde{\rho}) = C + \log(\rho) = (C + \xi) \oplus \zeta \oplus n$. Due to the assumed decompositions, we have

$$\tilde{\xi} \oplus \tilde{\zeta} \oplus \tilde{n} = \log(\tilde{\rho}) = C + \log(\rho) = (C + \xi) \oplus \zeta \oplus n.$$

Since orthogonal decompositions are unique, we have $\tilde{n} = n$ and $\tilde{\xi} = C + \xi$. Let $D = (t_1, \dots, t_d)$, $\tilde{D} = (\tilde{t}_1, \dots, \tilde{t}_d) \in \Delta$ as in the statement of the lemma. To argue

that $D = \tilde{D}$, it suffices to show that $t_i = \tilde{t}_i$ for all i . To this end, recall that each of the t_i are associated to either a 2-point or Neil constraint.

Suppose first that t_i exists such that, at the i^{th} stage of the construction of H_D^2 , we have

$$H_{t_i}^2 = \{k_a^{i-1} - t_i k_b^{i-1}\}^\perp = \{f \in H_{t_{i-1}}^2 : f(a) = t_i f(b)\},$$

where k_a^{i-1} and k_b^{i-1} are the reproducing kernels in $H_{t_{i-1}}^2$ at a and b respectively. Then, since D was chosen so that $e^\xi \in H_D^2$, we must have that $t_i = \exp(\xi(a) - \xi(b))$. Likewise, $\tilde{t}_i = \exp(\tilde{\xi}(a) - \tilde{\xi}(b))$. However, since $\tilde{\xi} = C + \xi$, it follows that

$$\tilde{\xi}(a) - \tilde{\xi}(b) = \xi(a) + C - (\xi(b) + C) = \xi(a) - \xi(b)$$

and therefore $\tilde{t}_i = t_i$.

Suppose instead that t_i exists such that, at the i^{th} stage of the construction of H_D^2 , we have

$$H_{t_i}^2 = \{k_a^{i-1} - t_i k_{a^{(n)}}^{i-1}\}^\perp = \{f \in H_{t_{i-1}}^2 : f(a) = t_i f^{(n)}(a)\},$$

where k_a^{i-1} is the reproducing kernel in $H_{t_{i-1}}^2$ at a , and $k_{a^{(n)}}^{i-1}$ is the reproducing function in $H_{t_{i-1}}^2$ that returns a functions n^{th} derivative at a . Since D was chosen so that $e^\xi \in H_D^2$, we must have $\exp(\xi(a)) = t_i \left. \left(\frac{d^n}{dx^n} \exp(\xi) \right) \right|_a$. Via repeated application of the chain and Liebniz rules, we find

$$\frac{d^n}{dx^n} \exp(\xi) = e^\xi \cdot G,$$

where G is a linear combination of products of $\xi', \dots, \xi^{(n)}$. In particular, we find that

$$t_i = \left. \frac{\exp(\xi)}{\frac{d^n}{dx^n} \exp(\xi)} \right|_a = \left. \frac{\exp(\xi)}{\exp(\xi) \cdot G} \right|_a = \frac{1}{G(a)}.$$

Similarly, $\tilde{t}_i = \frac{1}{\tilde{G}(a)}$ where \tilde{G} is a linear combination of products of $\tilde{\xi}', \dots, \tilde{\xi}^{(n)}$. Since $\tilde{\xi} = C + \xi$, it follows that $\xi^{(j)} = \tilde{\xi}^{(j)}$ for all $1 \leq j \leq n$. This immediately implies that $G(a) = \tilde{G}(a)$ so that $t_i = \tilde{t}_i$.

Having handled both cases, we conclude that $D = \tilde{D}$. This fact, along with $\tilde{n} = n$, allows us to conclude that $H_{n,D}^2 = H_{\tilde{n},\tilde{D}}^2$ and therefore $k_{x_0}^{n,D} = k_{x_0}^{\tilde{n},\tilde{D}}$. \square

Before stating and proving the Szegő theorem for A , we make a small observation. Given any function $\xi \in H^2$, we know that ξ is bounded below on X , and therefore e^ξ will never be zero for any points in X . Due to the nature of the Neil and 2-point constraints, the only functions that can live in two different H_D^2 spaces are those whose constrained values vanish. In other words, functions f for which $f_\Gamma = (0, \dots, 0)^\top \in$

\mathbb{C}^Y . Due to this fact, the function e^ξ cannot live in two different H_D^2 spaces. This justifies the notion that there exists a unique tuple $D \in \Delta$ for which $e^\xi \in H_D^2$.

Theorem 1.7 (Szegő Theorem for A). *Suppose $\rho > 0$ is a continuous function on ∂X . Let $\xi \in H^2$, $\zeta \in \overline{H_0^2}$, $n \in N$ be functions such that $\log(\rho) = \xi \oplus \zeta \oplus n \in H^2 \oplus \overline{H_0^2} \oplus N$. Let $D \in \Delta$ be the unique tuple such that $e^\xi \in H_{n,D}^2$. With $C_\rho := \int_{\partial X} \log(\rho) dm$, it follows that*

$$\inf \left\{ \int_{\partial X} |1 - p|^2 \rho dm : p \in A_0 \right\} = \exp(C_\rho) \left(\frac{1}{\|k_{x_0}^{n,D}\|^2} \right).$$

Proof We begin by observing that it suffices to consider $C_\rho = 0$. If not, we consider $\tilde{\rho} = \exp(-C_\rho) \rho$. We have that $\log(\tilde{\rho}) = -C_\rho + \log(\rho)$. We see immediately that

$$C_{\tilde{\rho}} = \int_{\partial X} \log(\tilde{\rho}) dm = \int_{\partial X} -C_\rho + \log(\rho) dm = -C_\rho + C_\rho = 0.$$

Thus, provided we establish the result for $C_{\tilde{\rho}} = 0$, we have that

$$\inf \left\{ \int_{\partial X} |1 - p|^2 \tilde{\rho} dm : p \in A_0 \right\} = \exp(C_{\tilde{\rho}}) \left(\frac{1}{\|k_{x_0}^{\tilde{n}, \tilde{D}}\|^2} \right) \quad (6)$$

where $\tilde{n} \in N$ and $\tilde{D} \in \Delta$ are the unique vectors such that $\log(\tilde{\rho}) = \tilde{\xi} \oplus \tilde{\zeta} \oplus \tilde{n} \in H^2 + \overline{H_0^2} \oplus N$ and $e^{\tilde{\xi}} \in H_{\tilde{n}, \tilde{D}}^2$. Since $-C_\rho$ is a constant, it follows from Lemma 3.3 that $k_{x_0}^{n,D} = k_{x_0}^{\tilde{n}, \tilde{D}}$. Therefore, since $C_{\tilde{\rho}} = 0$, (6) becomes

$$\inf \left\{ \int_{\partial X} |1 - p|^2 \tilde{\rho} dm : p \in A_0 \right\} = \frac{1}{\|k_{x_0}^{n,D}\|^2}.$$

Thus,

$$\begin{aligned} \inf \left\{ \int_{\partial X} |1 - p|^2 \rho dm : p \in A_0 \right\} &= \exp(C_\rho) \inf \left\{ \int_{\partial X} |1 - p|^2 \tilde{\rho} dm : p \in A_0 \right\} \\ &= \exp(C_\rho) \left(\frac{1}{\|k_{x_0}^{n,D}\|^2} \right). \end{aligned}$$

Henceforth, we assume that $C_\rho = 0$. In view of Lemma 3.2, there exist unique $\xi \in H^2$ and $n \in N$ such that $\log(\rho) = \xi \oplus \xi^* \oplus n \in H^2 \oplus \overline{H_0^2} \oplus N$ with $\xi(x_0) = 0$. Define the space $H^2(\rho)$ to be the standard H^2 space but with the inner product given by

$$\langle f, g \rangle_\rho = \int_X f \overline{g} \rho dm.$$

Let $\overline{A_0}^{\|\cdot\|_{H^2(\rho)}}$ denote the $L^2(\rho)$ closure of A_0 . It suffices to argue that the $H^2(\rho)$ -distance from the vector 1 to the space $\overline{A_0}^{\|\cdot\|_{H^2(\rho)}}$ is equal to $\frac{1}{\|k_{x_0}^{n,D}\|^2}$.

By exponentiating, we have that $\rho = e^\xi e^{\xi^*} e^n$. We claim that $e^\xi \in H^\infty$. Indeed,

$$|e^\xi|^2 = e^\xi e^{\xi^*} = \exp(\xi + \xi^*) = \exp(\log(\rho) - n) = \rho e^{-n}.$$

Since ρ and $n \in N$ are both bounded on ∂X , the above shows that $|e^\xi|^2$ is bounded and therefore $e^\xi \in L^\infty$. However, since $\xi \in H^2$, it follows that $e^\xi \in H^2$ as well and therefore $e^\xi \in H^\infty$. Similarly, $e^{-\xi} \in H^\infty$.

Define the map $U: H^2(\rho) \rightarrow H_n^2$ by $f \mapsto e^\xi f$. (Since e^ξ is bounded, this map is both well defined and bounded.) Observe that $n \in N$ is the unique value that makes U act as an isometry from $H^2(\rho)$ to H_n^2 . That is, given $f \in \overline{A_0}^{\|\cdot\|_{H^2(\rho)}}$, we have that

$$\|Uf\|_n^2 = \|e^\xi f\|_n^2 = \int_{\partial X} |e^\xi f|^2 e^n dm = \int_{\partial X} |f|^2 e^\xi e^{\xi^*} e^n dm = \int_{\partial X} |f|^2 \rho dm = \|f\|_{H^2(\rho)}^2.$$

In particular, defining its inverse by $U^*: H_n^2 \rightarrow H^2(\rho): f \mapsto e^{-\xi} f$, we find that this defines an isometry as well. Thus U is a unitary between $H^2(\rho)$ and H_n^2 . Additionally, recall that $D \in \Delta$ was chosen specifically so that $e^\xi \in H_{n,D}^2$. Now, since U is surjective, we have that $U(\overline{A_0}^{\|\cdot\|_{H^2(\rho)}}) = \{f \in H_{n,D}^2 : f(x_0) = 0\} =: H_{n,D;0}^2$ is exactly those functions in $H_{n,D}^2$ that vanish at x_0 . Since $U(1) = e^\xi$, we can transport our question over to the $H_{n,D}^2$ setting and observe that it suffices to show that the $H_{n,D}^2$ -distance from e^ξ to $H_{n,D;0}^2$ is exactly $\frac{1}{\|k_{x_0}^{n,D}\|^2}$.

Recall that the assumption $C_\rho = 0$ yields $\xi(x_0) = 0$. Therefore $e^{\xi(x_0)} = 1 \neq 0$ and hence $e^\xi \notin H_{n,D;0}^2$. Further, we know that $H_{n,D;0}^2$ is a codimension 1 subspace of $H_{n,D}^2$ and, in particular, $H_{n,D;0}^2 = (\text{span}\{k_{x_0}^{n,D}\})^\perp$, where $k_{x_0}^{n,D}$ is the reproducing kernel for $H_{n,D}^2$ at x_0 .

Since $H_{n,D;0}^2$ is a closed subspace, there exists $f \in H_{n,D;0}^2$ that minimizes $\|e^\xi - f\|_n^2$. This f is exactly $f = \text{proj}_{H_{n,D;0}^2}(e^\xi)$. Observe that $(e^\xi - f) \perp H_{n,D;0}^2$ and therefore $(e^\xi - f) \in \text{span}\{k_{x_0}^{n,D}\}$. Thus,

$$e^\xi - f = \text{proj}_{(H_{n,D;0}^2)^\perp}(e^\xi - f) = \text{proj}_{(H_{n,D;0}^2)^\perp}(e^\xi) = e^{\xi(x_0)} \frac{k_{x_0}^{n,D}}{\|k_{x_0}^{n,D}\|^2} = \frac{k_{x_0}^{n,D}}{\|k_{x_0}^{n,D}\|^2}.$$

Therefore $\|e^\xi - f\|_n^2 = \frac{1}{\|k_{x_0}^{n,D}\|^2}$. But this is exactly the $H_{n,D}^2$ -distance from e^ξ to the space $H_{n,D;0}^2$. We saw earlier that this distance is equal to the desired $H^2(\rho)$ -distance from the vector 1 to the space $\overline{A_0}^{\|\cdot\|_{H^2(\rho)}}$. Hence the proof is complete. \square

Remark 3.4 We note that the computation carried out in this proof, when restricted to the classical setting (with suitable notation adjusted appropriately), does the heavy lifting in establishing a characterization for outer functions in $H^2(\mathbb{T})$. Namely, if A_0 are

those functions in the disc algebra that vanish at zero, and \hat{f} denotes the holomorphic extension of f over \mathbb{D} obtained via the Poisson kernel, then $f \in H^2(\mathbb{T})$ is outer if and only if

$$\inf_{h \in A_0} \left\{ \frac{1}{2\pi} \int_0^{2\pi} |1 - h|^2 |f|^2 d\theta \right\} = |\hat{f}(0)|^2.$$

This characterization can be found as Exercise 6.28 in [13].

4 Invertibility of Toeplitz Operators: Some Preliminary Lemmas

We begin by noting that most of the arguments given here will work in the full setting of a finite (connected) Riemann surface, but one needs to modify the instances involving the Green's function (e.g., arguments given in Sect. 4.3). Thus, for simplicity, we instead consider the underlying domain to be a τ -holed planar domain. In this subsection, details on the Green's function for planar domains are reproduced largely from [1] and [15].

4.1 Green's Function for Planar Domains

Let X be a τ -holed planar domain with $x_0 \in X$. The *Green's function of X with pole at x_0* is defined by

$$G(z, x_0) = -\log(|z - x_0|) + h(z, x_0),$$

where $h(z, x_0)$ is the unique harmonic function of z in X with boundary values given by $\log(|z - x_0|)$. Such an h exists because the Dirichlet problem is solvable on X (the fact that h is unique is guaranteed by the maximum principle for harmonic functions).

Equivalently, the Green's function is the unique function that satisfies the following properties:

- (i) $G(z, x_0)$ is harmonic on $X \setminus \{x_0\}$
- (ii) $G(z, x_0) + \log(|z - x_0|)$ is harmonic near x_0
- (iii) $G(z, x_0) \rightarrow 0$ as $z \rightarrow \partial X$

The Green's function allows us to pass between the representing measure dm and the arclength measure dz . Let H be the multi-valued harmonic conjugate of $-G$ and let v denote the single-valued derivative of $-G + iH$. Then:

Proposition 4.1 (*Reformulated Proposition 6.5 in [15]*). *In the notation just introduced,*

$$dm(z) = \frac{1}{2\pi i} v(z) dz$$

Note that the above proposition can also be found in the discussion immediately proceeding Proposition 1.3 in [1]. One of the best uses of the above proposition is

using v to characterize the N -space discussed in Sect. 2.2. Specifically, if S_{x_0} denotes the real linear span of the set of all differences between pairs of representing measures for x_0 , then each $\mu_i \in S_{x_0}$ is absolutely continuous with respect to dm . Putting $\lambda_i := d\mu_i/dm$, we define

$$N := \text{span}_{\mathbb{C}}\{\lambda_1, \dots, \lambda_\sigma\}.$$

This space turns out to ‘fill out’ L^2 . Specifically, as noted in Sect. 4.5 of [15] and Sect. 2 of [1], we have

$$L^2(dm) = H^2(\partial X) \oplus \overline{H_0^2(\partial X)} \oplus N.$$

Moreover, the following theorem relates this decomposition to the derivative of the Green’s function, v :

Proposition 4.2 (*Theorem 1.7 in [1]*) *The orthogonal complement of $H^2(\partial X)$ in $L^2(dm)$ is $\overline{v^{-1}H^2(\partial X)}$. Therefore $L^2(dm) = H^2(\partial X) \oplus \overline{v^{-1}H^2(\partial X)}$.*

The last result we need involving the Green’s function is the information it encodes about the domain X .

Proposition 4.3 (*Reformulated Proposition 1.4 in [1]*). *If X is a τ -holed planar domain, then the following is true of the function v :*

- (i) *It is meromorphic in a neighborhood of \overline{X} with exactly one pole of order one at x_0 and no other poles.*
- (ii) *It has precisely τ zeros in X , counting multiplicities, and no other zeros in \overline{X}*

A version of the above proposition can also be found as Proposition 6.5 in [15].

4.2 Inner Functions, the Norm of Toeplitz Operators, and Kernels in $H_{\alpha, D}^2$

As mentioned in Sect. 2.2, we will refer to a function $h \in H^p$ as an *inner function* if there exists an $\alpha \in \Sigma$ such that $|h| = |Z|^\alpha$. In this manner, inner functions act as isometric multipliers between L_α^p spaces for different α ’s. A function $g \in H^p$ is an *outer function* if $\log(|\int_{\partial X} g \, dm|) = \int_{\partial X} \log(|g|) \, dm > -\infty$.

Lemma 4.4 *There exists an inner function $\Phi \in H^2$ such that $\Phi_\Gamma = (0, \dots, 0)^\top \in \mathbb{C}^\gamma$. In particular, $\Phi \in H_{\alpha, D}^2$ for every $(\alpha, D) \in \Sigma \times \Delta$.*

Proof The i^{th} entry of the vector $\Phi_\Gamma \in \mathbb{C}^\gamma$ is of the form $\Phi^{(n_i)}(a_i)$ for some $a_i \in X$ and $n_i \geq 0$. Since A is a uniform algebra, we can find an $f_i \in A$ such that $f_i^{(n_i)}(a_i) = 0$. Note that, since we have an algebra over a τ -holed planar domain, we can choose f_i in such a manner that $\log(|f_i|)$ is integrable with respect to all measures in M_{x_0} . Now, since H^2 is defined to be the L^2 closure of A , we have that $f_i \in H^2$. By Theorem 2.4, there exists H^2 functions g_i and h_i such that g_i is outer, h_i is inner, $f_i = g_i h_i$, $\int_{\partial X} \log(|g_i|) \, dm = (0, \dots, 0)$, and $h_i^{(n)}(a_i) = 0$. Since h_i is inner, there exists a γ -tuple α_i such that $|h_i| = |Z|^{\alpha_i}$.

Doing the above for every a_i we then form $\Phi = \prod_{i=1}^{\gamma} h_i$ and $\alpha' = \sum_{i=1}^{\gamma} \alpha_i$. In this manner, Φ is an inner function in H^2 such that $\Phi_{\Gamma} = (0, \dots, 0)^{\top}$ and $|\Phi| = |Z|^{\alpha'}$. Technically, every H_{α}^2 is the same set of functions for every α . Thus, $\Phi \in H_{\alpha}^2$ for every α . Note further that, since $\Phi_{\Gamma} = (0, \dots, 0)^{\top}$, we have that $\Phi \in H_{\alpha, D}^2$ for every $(\alpha, D) \in \Sigma \times \Delta$. \square

Lemma 4.5 *If $\phi \in L^{\infty}$, then $\|T_{\phi}^{\alpha, D}\| = \|\phi\|$ and $(T_{\phi}^{\alpha, D})^* = T_{\bar{\phi}}^{\alpha, D}$.*

Proof Since $M_{\phi}^* = M_{\bar{\phi}}$, we have

$$(T_{\phi}^{\alpha, D})^* = V_{\alpha, D}^* M_{\phi}^* V_{\alpha, D} = V_{\alpha, D}^* M_{\bar{\phi}} V_{\alpha, D} = T_{\bar{\phi}}^{\alpha, D}.$$

Since $V_{\alpha, D}$ is an isometry,

$$\|T_{\phi}^{\alpha, D}\| \leq \|V_{\alpha, D}^*\| \|M_{\phi}\| \|V_{\alpha, D}\| \leq \|M_{\phi}\| = \|\phi\|.$$

Thus, it suffices to show that $\|T_{\phi}^{\alpha, D}\| \geq \|\phi\|$. To this end, let Φ be the inner function from Lemma 4.4 such that $\Phi_{\Gamma} = (0, \dots, 0)^{\top}$. If we denote by H^2 the unweighted H_{β}^2 space and let $\beta \in \Sigma$ be the σ -tuple such that $|\Phi| = |Z|^{-\beta}$, then it follows that Φ is an isometric multiplier from H^2 into $H_{\beta, D}^2$ for every $D \in \Delta$.

Now, denoting by L^2 the unweighted L_{α}^2 space, let $V: H^2 \rightarrow L^2$ denote the inclusion map. Likewise, let $W: \Phi H^2 \rightarrow L_{\beta}^2$ be the inclusion map. (Note here that with this setup, $V^* M_{\phi} V = T_{\phi}$ is the usual Toeplitz operator on H^2 .) Now, let $\Psi \in H^{\infty} \subseteq H^2$ be the inner function given by $|\Psi| = |Z|^{\beta - \alpha}$ (such a function exists by Lemma 2.3). Observe that $\Psi \Phi$ is an isometric multiplier from L^2 to L_{α}^2 . Further,

$$W^* M_{\phi} W = W^* \Psi^* V_{\alpha, D}^* M_{\phi} V_{\alpha, D} \Psi W = W^* \Psi^* T_{\phi}^{\alpha, D} \Psi W \quad (7)$$

Now define the map $U: H^2 \rightarrow \Phi H^2 \subseteq H_{\beta, D}^2$ sending $f \mapsto \Phi f$. As noted earlier, this map is an isometry into $H_{\beta, D}^2$. Thus, for $f, g \in H^2$,

$$\begin{aligned} \langle M_{\phi} W U f, W U g \rangle_{H_{\beta}^2} &= \langle M_{\phi} W \Phi f, W \Phi g \rangle_{H_{\beta}^2} \\ &= \langle M_{\phi} \Phi f, \Phi g \rangle_{L_{\beta}^2} \\ &= \langle \Phi \phi f, \Phi g \rangle_{L_{\beta}^2} \\ &= \langle \phi f, g \rangle_{L^2} \\ &= \langle M_{\phi} f, g \rangle_{L^2} \\ &= \langle M_{\phi} f, P g \rangle_{L^2} \\ &= \langle T_{\phi} f, g \rangle_{H^2}. \end{aligned}$$

Therefore $U^* (W^* M_{\phi} W) U = T_{\phi}$. Combining this with (7), we have that

$$U^* (W^* \Psi^* T_{\phi}^{\alpha, D} \Psi W) U = T_{\phi}.$$

It follows that,

$$\|T_\phi\| = \|U^*(W^* \Psi^* T_\phi^{\alpha, D} \Psi W)U\| \leq \|T_\phi^{\alpha, D}\|$$

and therefore $\|\phi\| = \|T_\phi\| \leq \|T_\phi^{\alpha, D}\|$. \square

Let $w_i^\alpha \in H_\alpha^2$ be the linear combination of reproducing functions in H_α^2 such that for all $f \in H_\alpha^2$, either $\langle f, w_i^\alpha \rangle_\alpha = f(a) - t_i f(b)$ or $\langle f, w_i^\alpha \rangle_\alpha = f(a) - t_i f^{(n)}(a)$. It follows that

$$\text{span}\{w_1^\alpha, \dots, w_d^\alpha\} = (H_{\alpha, D}^2)^\perp.$$

Further, let $h_i^\alpha \in H_\alpha^2$ be the reproducing functions such that $\langle f, h_i^\alpha \rangle_\alpha$ returns either $f(a)$ or $f^{(n)}(a)$ (for some finite n), depending on how a is integrated into the construction of A . In this manner,

$$f_\Gamma = \begin{bmatrix} \langle f, h_1^\alpha \rangle_\alpha \\ \vdots \\ \langle f, h_\gamma^\alpha \rangle_\alpha \end{bmatrix} \in \mathbb{C}^\gamma.$$

An immediate observation is that $w_i^\alpha \in \text{span}\{h_1^\alpha, \dots, h_\gamma^\alpha\}$ for every $1 \leq i \leq d$. This discussion is recorded in the following proposition:

Proposition 4.6 *Given an $(\alpha, D) \in \Sigma \times \Delta$, there exists reproducing functions $h_1^\alpha, \dots, h_\gamma^\alpha$ and $w_1^\alpha, \dots, w_d^\alpha \in H_\alpha^2$ such that*

$$(1) \quad f_\Gamma = \begin{bmatrix} \langle f, h_1^\alpha \rangle_\alpha \\ \vdots \\ \langle f, h_\gamma^\alpha \rangle_\alpha \end{bmatrix} \in \mathbb{C}^\gamma \text{ and}$$

$$(2) \quad (H_{\alpha, D}^2)^\perp = \text{span}\{w_1^\alpha, \dots, w_d^\alpha\},$$

where $w_i^\alpha \in \text{span}\{h_1^\alpha, \dots, h_\gamma^\alpha\}$ for every $1 \leq i \leq d$.

4.3 Pre-Anniliator for A and a Factorization Lemma

In this subsection we begin by asserting the existence of a space \mathcal{M} such that L^∞/A is isometrically isomorphic to \mathcal{M}^* . Due to the Hahn-Banach Theorem, this goal is equivalent to finding $\mathcal{M} \subseteq L^1$ such that $\text{Ann}(\mathcal{M}) = A$. We will continue to use the machinery introduced and discussed in Sect. 4.1. Specifically, recall that, since our uniform algebra \mathcal{A} is a hypo-Dirichlet algebra, the real linear span of the set of differences between pairs of representing measures for x_0 , denoted S_{x_0} , was σ -dimensional. Putting $S_{x_0} = \text{span}_{\mathbb{R}}\{\mu_1, \dots, \mu_\sigma\}$, we noted that each μ_i is absolutely continuous with respect to dm . Thus, with $\lambda_i := d\mu_i/dm$, we can form $N = \text{span}_{\mathbb{C}}\{\lambda_1, \dots, \lambda_\sigma\}$. Specifically, this N space exists such that $L^2 = H^2 \oplus \overline{H_0^2} \oplus N$. In [4], it is shown

that N has a basis consisting of real functions so that, as sets, $\overline{N} = N$. Further, the aforementioned L^2 decomposition can be weighed:

$$L_\alpha^2 = H_\alpha^2 \oplus \overline{H_{0,\alpha}^2} \oplus N. \quad (8)$$

where $\overline{H_{0,\alpha}^2}$ is the complement of H_α^2 with the additional condition that $\int_X f dm = f(x_0) = 0$. Note further that when we consider the unweighted L^2 space ($\alpha = 0$), the above is written without the subscript adornment: $\overline{H_0^2}$.

Now, observe that if $\phi \in A$, then we have that

$$\int_{\partial X} \phi \lambda_i dm = \int_{\partial X} \phi \frac{d\mu_i}{dm} dm = \int_{\partial X} \phi d\mu_i = 0.$$

Thus, every function in N is annihilated by $\phi \in A$.

Proposition 4.6 asserted the existence of reproducing functions $h_1, \dots, h_\gamma \in H^2$ such that, given $f \in H^2$,

$$f_\Gamma = \begin{bmatrix} \langle f, h_1 \rangle_2 \\ \vdots \\ \langle f, h_\gamma \rangle_2 \end{bmatrix} \in \mathbb{C}^\gamma.$$

Recall that the construction of the finite codimensional subalgebra A started with the uniform algebra \mathcal{A} and iteratively imposed either 2-point or Neil constraints. Recall that $d \leq \gamma$ denoted the number of iterations necessary to yield our algebra A . For $1 \leq i \leq d$, let s_i denote the linear combination of vectors in $\text{span}\{h_1, \dots, h_\gamma\}$ such that $\langle \phi, s_i \rangle_2 = 0$ for all $\phi \in A$. This directly implies that, given $\phi \in A$,

$$\int_{\partial X} \phi \overline{s_i} dm = \langle \phi, s_i \rangle_2 = 0$$

for every $1 \leq i \leq d$. With $\mathcal{S} := \text{span}\{\overline{s_1}, \dots, \overline{s_d}\}$, we've shown that every function in \mathcal{S} is annihilated by $\phi \in A$.

Example 4.7 Suppose we start with a uniform algebra \mathcal{A} and impose a single 2-point constraint at $a, b \in X$. If we let h_a and h_b be the H^2 functions that reproduce at the points a and b – that is, $f(a) = \langle f, h_a \rangle_2$ and $f(b) = \langle f, h_b \rangle_2$, then $s_{a,b} := h_a - h_b$. In this manner, we find that all functions $\phi \in A$ must obey $\phi(a) = \phi(b)$ and thus,

$$0 = \phi(a) - \phi(b) = \langle \phi, h_b \rangle_2 - \langle \phi, h_a \rangle_2 = \langle \phi, h_a - h_b \rangle_2 = \langle \phi, s_{a,b} \rangle_2.$$

Finally, recall that H^1 is defined to be the L^1 closure of the algebra \mathcal{A} . If we put $H_0^1 := \{f \in H^1 : \int_X f dm = f(x_0) = 0\}$, then we find that, given $\phi \in A$,

$$\int_{\partial X} \phi f dm = (\phi f)(x_0) = 0$$

for all $f \in H_0^1$. Therefore every function in H_0^1 is annihilated by $\phi \in A$. Put $\mathcal{M} = H_0^1 + N + \mathcal{S}$.

Lemma 4.8 $\text{Ann}(\mathcal{M}) = A$.

Proof As noted in the previous discussion, we know that $H_0^1 + N + \mathcal{S} = \mathcal{M}$ is annihilated by any function $\phi \in A$. This shows that $A \subseteq \text{Ann}(\mathcal{M})$. To argue the other inclusion, since $A \subseteq L^\infty$, it is enough to show that if $\phi \in L^\infty$ such that $\int_X \phi h \, dm = 0$ for every $h \in \mathcal{M}$, then $\phi \in A$. To this end, we first note that our algebra A can be interpreted as

$$A = \{f \in H^\infty : f \text{ satisfies the constraints of } A\}. \quad (9)$$

Since $\phi \in L^\infty$, we also have that $\phi \in L^2$. Recall from (8),

$$L^2 = H^2 \oplus \overline{H^2} \oplus N.$$

Additionally, recall that $N = \overline{N}$. Since $\langle \phi, \lambda \rangle_2 = \int_{\partial X} \phi \lambda \, dm = 0$ for every $\lambda \in N$, we must have $\phi \in H^2 \oplus \overline{H_0^2}$. Further, since $H_0^2 \subseteq H_0^1$ and $\int_{\partial X} \phi h \, dm = 0$ for every $h \in H_0^1$, it follows that $\langle \phi, \overline{h} \rangle_2 = \int_{\partial X} \phi h \, dm = 0$ for every $h \in H_0^2$ as well. Hence $\phi \perp \overline{H_0^2}$. This puts $\phi \in H^2$. Since $H^\infty = H^2 \cap L^\infty$ and $\phi \in L^\infty$, it follows that $\phi \in H^\infty$.

Lastly, since $\int_{\partial X} \phi \overline{s_i} \, dm = 0$ for every $1 \leq i \leq d$, this implies (by the construction of the functions s_i) that ϕ must satisfy the constraints of A . Thus, using the formulation given in (9), we find that $\phi \in A$. \square

Proposition 4.9 $L^\infty/A \cong \mathcal{M}^*$.

Proof By the Hahn-Banach Theorem, $X^*/\text{Ann}(Y) \cong Y^*$. In our case, we know that $(L^1)^* \cong L^\infty$. Thus, since Lemma 4.8 showed that $A = \text{Ann}(\mathcal{M})$, it follows that $L^\infty/A \cong \mathcal{M}^*$ as desired. In particular, if we let Λ be the isometric isomorphism from L^∞/A to \mathcal{M}^* , then it is interpreted as the map sending $\pi(\phi) \mapsto (\lambda_\phi)|_{\mathcal{M}}$, where $\lambda_\phi: L^1 \rightarrow \mathbb{C}$ is the functional sending $\psi \mapsto \int_{\partial X} \phi \psi \, dm$. \square

Recalling the notation from Sect. 4.1, let G be the Green's function for the τ -holed planar domain X with pole at x_0 , H be the multi-valued harmonic conjugate of $-G$, and v be the single-valued derivative of $-G + iH$.

The following lemma is a weighted version of Proposition 4.2:

Lemma 4.10 *The orthogonal complement of H_α^2 in L_α^2 is $\overline{v^{-1} H_{0,\alpha}^2}$.*

In light of the decomposition $L_\alpha^2 = H_\alpha^2 \oplus \overline{H_{0,\alpha}^2} \oplus N$, and recalling that (as sets) $N = \overline{N}$, the above lemma implies that

$$H_{0,\alpha}^2 \oplus N = v^{-1} H_\alpha^2.$$

Hence $\mathcal{M} = H_0^1 + N + \mathcal{S} = v^{-1} H^1 + \mathcal{S}$.

Let $\mathcal{M} \subseteq H^1$ be the dense subset of functions analytic on X , continuous on ∂X and with no zeros on ∂X . Note that \mathcal{M} is dense in H^2 as well. With this, let

$$\mathcal{M}_{\mathcal{M}} := v^{-1} \mathcal{M} + \mathcal{S}.$$

This set is dense in \mathcal{M} . We prove a factorization theorem for $\mathcal{M}_{\mathcal{M}}$. Before we do so, however, we need a technical lemma. For a $\omega \in \Sigma$, let H_{ω}^1 denote the usual H^1 space but with norm $\|f\|_{1,\omega} = \int_{\partial X} |f| |Z|^{\omega} dm$. (In this manner, we will let the subscript denote the fact that this is the 1-norm. Similarly, $\|\cdot\|_{2,\omega}$ will denote the 2-norm coming from the inner product discussed in (3) but with $\omega \in \Sigma$.)

Lemma 4.11 *Given $h \in \mathcal{M} \subseteq H_{\gamma}^1$ for some $\gamma \in \Sigma$, there exists $\omega \in \Sigma$ and $F, G \in H^2$ such that $h = FG$, $\|h\|_{1,\gamma} = \|F\|_{2,\gamma-\omega} \|G\|_{2,\gamma+\omega}$, F is invertible, and $F \in \mathcal{M}$.*

Proof Let $h \in \mathcal{M} \subseteq H_{\gamma}^1$. It follows from the definition of \mathcal{M} that h has at most finitely many zeros in X . The proof of Lemma 4.4 guarantees the existence of an inner function g that shares exactly these finitely many zeros (with multiplicity). Let $\omega \in \Sigma$ be taken such that $|g| = |Z|^{\omega}$. Putting $f := h/g$, we have that f is analytic in X , has no zeros on \overline{X} and is continuous on ∂X – therefore f is invertible. In particular, we find that \sqrt{f} is also invertible and lies in $\mathcal{M} \subseteq H^2$.

Observe that

$$\begin{aligned} \|h\|_{1,\gamma} &= \int_{\partial X} |h| |Z|^{\gamma} dm = \int_{\partial X} |g| |f| |Z|^{\gamma} dm \\ &= \int_{\partial X} |f| |Z|^{\gamma+\omega} dm = \|f\|_{1,\gamma+\omega} = \|\sqrt{f}\|_{2,\gamma+\omega}^2. \end{aligned}$$

Further,

$$\|g\sqrt{f}\|_{2,\gamma-\omega}^2 = \int_{\partial X} (|g| |\sqrt{f}|)^2 |Z|^{\gamma-\omega} dm = \int_{\partial X} |\sqrt{f}|^2 |Z|^{\gamma+\omega} dm = \|\sqrt{f}\|_{2,\gamma+\omega}^2.$$

Therefore

$$\|h\|_{1,\gamma} = (\|h\|_{1,\gamma})^{\frac{1}{2}} (\|h\|_{1,\gamma})^{\frac{1}{2}} = \|\sqrt{f}\|_{2,\gamma+\omega} \|g\sqrt{f}\|_{2,\gamma-\omega}.$$

Putting $F = \sqrt{f}$ and $G = g\sqrt{f}$, we find that $h = FG$, $\|h\|_{1,\gamma} = \|F\|_{2,\gamma-\omega} \|G\|_{2,\gamma+\omega}$, F is invertible, and $F \in \mathcal{M}$. \square

Proposition 4.12 *For $h \in \mathcal{M}_{\mathcal{M}} = v^{-1} \mathcal{M} + \mathcal{S}$, there exists $(\beta, D) \in \Sigma \times \Delta$, $f \in H_{-\beta, D}^2$, and $g \in L_{-\beta}^2$ such that*

- (i) $h = fg$
- (ii) $\|h\|_1 = \|f\|_{2,-\beta} \|g\|_{2,\beta}$
- (iii) $\langle \psi, \bar{g} \rangle_2 = 0$ for all $\psi \in H_{-\beta, D}^2$

Proof Let $h = v^{-1}r + h_s \in \mathcal{M}_M = v^{-1}\mathcal{M} + \mathcal{S}$. Let z_1, \dots, z_τ be the zeros of v in X . The proof of Lemma 4.4 guarantees the existence of an inner function $\Phi_v \in H^2$ such that $\Phi_v(z_i) = 0$ for $1 \leq i \leq \tau$. Let Φ^Γ be the actual function produced by Lemma 4.4 so that $\Phi_\Gamma^\Gamma = (0, \dots, 0)^\top \in \mathbb{C}^\gamma$. It follows that the product $\Phi := \Phi_v \Phi^\Gamma$ is inner as well and thus there exists $\alpha \in \Sigma$ such that $|\Phi| = |Z|^\alpha$.

Our first order of business will be showing that

- (a) $\Phi h \in H_{-\alpha}^1$ and
- (b) $\Phi h(x_0) = 0$.

To show (a), we first show that $\Phi^\Gamma h_s \in v^{-1}H^2$. To see this, it suffices to argue that $\Phi^\Gamma h_s \perp \overline{H^2}$. To this end, let $\bar{g} \in \overline{H^2}$. Since $h_s \in \mathcal{S} = \text{span}\{\bar{s}_1, \dots, \bar{s}_d\}$, it suffices to argue that $\langle \Phi^\Gamma \bar{s}_j, \bar{g} \rangle_2 = 0$ for all $1 \leq j \leq d$. Recall, however, that the s_j is simply a linear combination of reproducing functions at the points involved in the construction of A . Therefore, since $\Phi_\Gamma^\Gamma = (0, \dots, 0)^\top$,

$$\langle \Phi^\Gamma \bar{s}_j, \bar{g} \rangle_2 = \int_{\partial X} \Phi^\Gamma \bar{s}_j g \, dm = \int_{\partial X} (\Phi^\Gamma g) \bar{s}_j \, dm = \langle \Phi^\Gamma g, s_j \rangle_2 = 0.$$

Thus we indeed have $\Phi^\Gamma h_s \in v^{-1}H^2$. Next we show that the product of Φ_v and v^{-1} is bounded and analytic. By Proposition 4.3, we know v has exactly τ many zeros. Thus, the τ zeros of v will act as poles in v^{-1} (including multiplicity), but will be canceled when multiplied by Φ_v . Since there were exactly τ many poles, the product has no unbounded components and only a zero at x_0 (coming from the single pole at x_0 in v). In this manner, $\Phi_v(v^{-1}H^2) \subseteq H^2$. In particular, since we showed that $\Phi^\Gamma h_s \in v^{-1}H^2$, it follows that

$$\Phi h_s = \Phi_v(\Phi^\Gamma h_s) \in \Phi_v(v^{-1}H^2) \subseteq H^2.$$

Thus

$$\Phi h = \Phi(v^{-1}r) + \Phi h_s = \Phi^\Gamma(\Phi_v v^{-1}r) + \Phi h_s \in H^1.$$

Since $\Phi h \in H^1$, it is also in $H_{-\alpha}^1$. This shows (a)

We noted that $\Phi^\Gamma h_s \in v^{-1}H^2$. Therefore there exists a function $b \in H^2$ such that $\Phi^\Gamma h_s = v^{-1}b$. Since v^{-1} has a zero at x_0 , $\Phi_v v^{-1}$ is an analytic function with a zero at x_0 . Therefore,

$$\begin{aligned} \int_{\partial X} \Phi h \, dm &= \int_{\partial X} \Phi(v^{-1}r) + \Phi h_s \, dm \\ &= \int_{\partial X} \Phi^\Gamma r \Phi_v v^{-1} \, dm + \int_{\partial X} \Phi_v v^{-1} b \, dm \\ &= (\Phi^\Gamma r \Phi_v v^{-1})(x_0) + (\Phi_v v^{-1} b)(x_0) \\ &= 0 \end{aligned}$$

This shows (b).

Since $\Phi h \in \mathcal{M} \subseteq H_{-\alpha}^1$, it follows from Lemma 4.11 that there exists $\omega \in \Sigma$ and $F, G \in H^2$ such that $\Phi h = FG$ and $\|\Phi h\|_{1,-\alpha} = \|F\|_{2,-(\alpha+\omega)} \|G\|_{2,-\alpha+\omega}$, F is invertible, and $F \in \mathcal{M}$. In this manner, we find that

$$\|h\|_1 = \|\Phi h\|_{1,-\alpha} = \|F\|_{2,-(\alpha+\omega)} \|G\|_{2,-\alpha+\omega}.$$

There must exist some $D \in \Delta$ such that $F \in H_{-(\alpha+\omega), D}^2$. Since F is invertible, G will have to inherit the zero at x_0 .

Now consider the function Φ^{-1} . This function is not necessarily analytic, but we do have that $|\Phi^{-1}| = |Z|^{-\alpha}$ on the boundary. Form the function $g = \Phi^{-1}G$. Observe that, since $\Phi h = FG$, not only do we have

$$h = \Phi^{-1}FG = Fg,$$

but also

$$\begin{aligned} \|g\|_{2,\alpha+\omega}^2 &= \int_{\partial X} |g|^2 |Z|^{\alpha+\omega} dm = \int_{\partial X} |G|^2 |\Phi^{-1}|^2 |Z|^{\alpha+\omega} dm \\ &= \int_{\partial X} |G|^2 |Z|^{-\alpha+\omega} dm = \|G\|_{2,-\alpha+\omega}^2 \end{aligned}$$

so that we have the desired norm-factorization for h :

$$\|h\|_1 = \|\Phi h\|_{1,-\alpha} = \|F\|_{2,-(\alpha+\omega)} \|G\|_{2,-\alpha+\omega} = \|F\|_{2,-(\alpha+\omega)} \|g\|_{2,\alpha+\omega}.$$

Put $\beta := \alpha + \omega \in \Sigma$. It remains to show that $\langle \psi, \bar{g} \rangle_2 = 0$ for all $\psi \in H_{-\beta, D}^2$. Since $\Phi_\Gamma^\Gamma = (0, \dots, 0)^\top$, it follows that $\Phi H^2 = \Phi_v(\Phi^\Gamma H^2)$ is a finite codimensional subspace of $H_{-\beta, D}^2$. Thus, there must exist ρ vectors $w_1, \dots, w_\rho \in H_{-\beta, D}^2$ such that

$$H_{-\beta, D}^2 = \Phi H^2 \oplus \text{span}\{w_1, \dots, w_\rho\}.$$

Observe that if $f \in H^2$, then (since $G(x_0) = 0$),

$$\langle \Phi f, \bar{g} \rangle_2 = \int_{\partial X} \Phi f \bar{g} dm = \int_{\partial X} f \Phi \Phi^{-1} G dm = \int_{\partial X} f G dm = 0.$$

Therefore, it suffices to show that $\langle w_j, \bar{g} \rangle_2 = 0$ for $1 \leq j \leq \rho$.

To this end, recall that Proposition 4.1 gives us that $dm = \frac{1}{2\pi i} v dz$. It follows that $v^{-1} dm = \frac{1}{2\pi i} dz$. Moreover, it follows from the Cauchy integral theorem that, since ∂X is a finite union of closed curves, $\int_{\partial X} f v^{-1} dm = \frac{1}{2\pi i} \oint f dz = 0$ for any analytic, L^1 function f . With these observations (along with the fact that $\Phi^{-1}h^{-1}G = F^{-1}$),

$$\langle w_j, \bar{g} \rangle_2 = \int_{\partial X} w_j \Phi^{-1} G dm = \int_{\partial X} w_j \Phi^{-1} G h^{-1} h dm = \int_{\partial X} w_j F^{-1} (v^{-1} r + h_s) dm. \quad (10)$$

We endeavor to show that the right-most integral in (10) is equal to zero. Since $w_j F^{-1} r$ is an analytic, L^1 function on ∂X , $\int_{\partial X} (w_j F^{-1} r) v^{-1} dm = 0$. Thus, it suffices to show that $\int_{\partial X} w_j F^{-1} h_s dm = 0$ for all w_j . However, since $h_s \in \mathcal{S} = \text{span}\{\bar{s}_1, \dots, \bar{s}_d\}$, it actually suffices to show that

$$\int_{\partial X} w_j F^{-1} \bar{s}_i dm = 0$$

for any i, j .

Since $w_j, F \in H_{-\beta, D}^2$, it follows from Lemma 2.7 that $w_j F^{-1} \in H_{D_\Gamma}^2$. That is, it satisfies the constraints of A . Recall that the s_i are linear combination of reproducing functions at the various points involved in the construction of A . In particular, if any analytic function ϕ satisfies the constraints of A , then $\langle \phi, s_i \rangle_2 = 0$ for all i . This implies that

$$\int_{\partial X} w_j F^{-1} \bar{s}_i dm = \langle w_j F^{-1}, s_i \rangle_2 = 0$$

for all i and j . Therefore $\langle \psi, \bar{g} \rangle_2 = 0$ for $\psi \in H_{-\beta, D}^2$. This completes the proof. \square

4.4 Universal Lower Bound for the Left-Invertible Toeplitz Operators

Let $\phi \in L^\infty$ be fixed and consider the Toeplitz operator $T_\phi^{\alpha, D}$. If we assume this operator is left-invertible, one can find $\varepsilon_{\alpha, D} > 0$ such that $\|T_\phi^{\alpha, D} f\| \geq \varepsilon_{\alpha, D} \|f\|$ for all $f \in H_{\alpha, D}^2$. The goal of this subsection is to prove a uniform version of this statement:

Proposition 4.13 *If $\phi \in L^\infty$ and $T_\phi^{\alpha, D}$ is left-invertible for every $(\alpha, D) \in \Sigma \times \Delta$, then there exists $0 < \varepsilon < 1$ (independent of (α, D)) such that, for every $(\alpha, D) \in \Sigma \times \Delta$ and every $f \in H_{\alpha, D}^2$,*

$$\|T_\phi^{\alpha, D} f\| \geq \varepsilon \|f\|_\alpha$$

We first need a few lemmas. Let L_0^2 denote the usual, unweighted L^2 space and we equip Σ with its usual metric.

Lemma 4.14 *There is a universal constant C such that for all $h_1, h_2 \in L_0^2$ and all $\alpha, \beta \in \Sigma$*

$$|\langle h_1, h_2 \rangle_\alpha - \langle h_1, h_2 \rangle_\beta| \leq C \|h_1\|_0 \|h_2\|_0 \text{dist}(\alpha, \beta).$$

Proof We first note that, since the functions Z are uniformly bounded above and below on X , there is a uniform constant C such that for all $\alpha, \beta \in \Sigma$,

$$|Z|^{\alpha-\beta} - 1 \leq C \cdot \text{dist}(\alpha, \beta)$$

on X . The proof is now straightforward: we have

$$\begin{aligned}\langle h_1, h_2 \rangle_\alpha - \langle h_1, h_2 \rangle_\beta &= \int h_1 \overline{h_2} (|Z|^\alpha - |Z|^\beta) dm \\ &= \int h_1 \overline{h_2} (|Z|^{\alpha-\beta} - 1) |Z|^\beta dm\end{aligned}$$

so

$$|\langle h_1, h_2 \rangle_\alpha - \langle h_1, h_2 \rangle_\beta| \leq C \cdot \text{dist}(\alpha, \beta) \int |h_1 \overline{h_2}| |Z|^\beta dm \leq C \cdot \text{dist}(\alpha, \beta) \|h_1\|_\beta \|h_2\|_\beta$$

and the conclusion follows by the uniform equivalence of the β and 0 norms. \square

Lemma 4.15 *Let \mathcal{H} be a closed subspace of L_0^2 . For each $\alpha \in \Sigma$, let \mathcal{H}_α be the image of the space $\mathcal{H} = \mathcal{H}_0$ under the identity mapping $\iota_\alpha : L_0^2 \rightarrow L_\alpha^2$. Let P_α denote the orthogonal projection of L_α^2 onto \mathcal{H}_α . We let Q_α denote the corresponding operator in L_0^2 :*

$$Q_\alpha := \iota_\alpha^{-1} P_\alpha \iota_\alpha.$$

Then there exists an absolute constant C such that for all $f \in L_0^2$ and all $\alpha, \beta \in \Sigma$,

$$\|Q_\alpha f - Q_\beta f\|_0^2 \leq C \cdot \text{dist}(\alpha, \beta) \|f\|_0^2.$$

Proof Fix f . To unclutter the notation let $g_\alpha = P_\alpha f$ and $g_\beta = P_\beta f$. By definition, g_α is the unique vector in H_α such that

$$\langle f - g_\alpha, h \rangle_\alpha = 0 \quad \text{for all } h \in H = H_\alpha$$

and similarly for g_β . We then have, since the spaces \mathcal{H}_α all coincide with \mathcal{H} ,

$$\begin{aligned}\|g_\alpha - g_\beta\|_\alpha^2 &= \langle g_\alpha - g_\beta, g_\alpha - g_\beta \rangle_\alpha \\ &= \langle f - g_\beta, g_\alpha - g_\beta \rangle_\alpha - \langle f - g_\alpha, g_\alpha - g_\beta \rangle_\alpha \\ &= \langle f - g_\beta, g_\alpha - g_\beta \rangle_\alpha - \langle f - g_\beta, g_\alpha - g_\beta \rangle_\beta\end{aligned}$$

This last expression has the form $\langle h_1, h_2 \rangle_\alpha - \langle h_1, h_2 \rangle_\beta$, where we have put

$$h_1 = f - g_\beta, \quad h_2 = g_\alpha - g_\beta.$$

Observe that $\|g_\alpha\|_\alpha \leq \|f\|_\alpha \leq C\|f\|_0$, similarly for β , so that $\|h_1\|_0, \|h_2\|_0 \leq C\|f\|_0$. Hence, by the continuity of the inner product (Lemma 4.14),

$$\|g_\alpha - g_\beta\|_\alpha^2 \leq |\langle h_1, h_2 \rangle_\alpha - \langle h_1, h_2 \rangle_\beta| \leq C\|h_1\|_0\|h_2\|_0 \cdot \text{dist}(\alpha, \beta) \leq C\|f\|_0^2 \cdot \text{dist}(\alpha, \beta),$$

and the proof is finished by the mutual equivalence (with a universal constant) of the α and 0 norms. \square

We observe that the constants in the above argument do not depend on the choice of the original subspace \mathcal{H} . It then follows immediately that

Lemma 4.16 *There is a universal constant C such that for all $f \in L_0^2$ and all $D \in \Delta$,*

$$\|Q_{\alpha, D} f - Q_{\beta, D} f\|_0^2 \leq C \cdot \text{dist}(\alpha, \beta) \|f\|_0^2.$$

In particular, for fixed $D \in \Delta$, the map from Σ to $B(L_0^2)$ given by

$$\alpha \rightarrow Q_{\alpha, D} := \iota_{\alpha}^{-1} P_{\alpha, D} \iota_{\alpha}$$

is Hölder continuous, with constant independent of $D \in \Delta$:

$$\|Q_{\alpha, D} - Q_{\beta, D}\|_{B(L_0^2)} \leq C \cdot \text{dist}(\alpha, \beta)^{1/2}.$$

Lemma 4.17 *For fixed $\alpha \in \Sigma$, the map from Δ to $B(L_{\alpha}^2)$ given by*

$$D \rightarrow P_{\alpha, D}$$

is Lipschitz continuous, with constant independent of α , that is, for $D, D' \in \Delta$

$$\|P_{\alpha, D} - P_{\alpha, D'}\|_{B(L_{\alpha}^2)} \leq C \cdot \text{dist}(D, D').$$

Proof We give the proof in the case of a single 2-point constraint; the case of a single derivation is similar. The general case then follows by a straightforward induction on the codimension, we leave the details to the reader.

Suppose we have a 2-point constraint $f(a) = f(b)$. In this case Δ is a copy of the Riemann sphere, and for fixed $D \in \Delta$ there exist complex numbers t_a, t_b such that $|t_a|^2 + |t_b|^2 = 1$, and such that the subspace $H_{\alpha, D}^2$ consists of those functions $f \in H_{\alpha}^2$ for which

$$t_a f(a) + t_b f(b) = 0.$$

The t_a, t_b are uniquely determined if we impose the additional requirement that $t_a \geq 0$, which we do from now on. The space Δ is then a metric space if we impose, say, the ℓ^1 metric. Since $I - P_{\alpha, D}$ is the rank-one projection onto the difference of reproducing kernels $t_a k_a^{\alpha} + t_b k_b^{\alpha}$, to prove the desired continuity it suffices to observe that for fixed a and b , the norms of the reproducing kernels $k_a^{\alpha}, k_b^{\alpha}$ are uniformly bounded above and below (away from zero), independently of α . \square

Proposition 4.18 *The map from $\Sigma \times \Delta$ to $B(L_0^2)$ given by*

$$(\alpha, \Delta) \rightarrow Q_{\alpha, D} := \iota_{\alpha}^{-1} P_{\alpha, D} \iota_{\alpha}$$

is continuous.

Proof This follows immediately from Lemmas 4.15 and 4.17, and the fact that the L_α^2 norms are all mutually equivalent, with uniform constants. \square

Proposition 4.13 For $(\alpha, D) \in \Sigma \times \Delta$, we define operators $Q_{\alpha, D}$ and $X_{\alpha, D}$ in L_0^2 by

$$Q_{\alpha, D} := \iota_\alpha^{-1} P_{\alpha, D} \iota_\alpha$$

and

$$X_{\alpha, D} := Q_{\alpha, D} M_\phi Q_{\alpha, D} + (I - Q_{\alpha, D}).$$

By Proposition (4.18), we have that the map $(\alpha, D) \rightarrow X_{\alpha, D}$ is norm continuous.

For fixed (α, D) , there is by hypothesis an $\epsilon(\alpha, D) \in (0, 1]$ such that $\|V_{\alpha, D} T_\phi^{\alpha, D} f\| = \|T_\phi^{\alpha, D} f\| \geq \epsilon(\alpha, D) \|f\|$ for $f \in H_\alpha^2$. Thus, given $F \in L_0^2$ and decomposing it as $F = f + g$ with $f \in H_{\alpha, D}^2$ and $g \in (H_{\alpha, D}^2)^\perp$, (the orthogonal complement taken in L_α^2), we have

$$\begin{aligned} \|X_{\alpha, D} F\|^2 &\geq C \|\iota_\alpha^{-1} X_{\alpha, D} F\|_\alpha^2 \\ &= C (\|V_\alpha T_\phi^{\alpha, D} f\|_\alpha^2 + \|g\|_\alpha^2) \\ &\geq C \epsilon(\alpha, D)^2 (\|f\|_\alpha^2 + \|g\|_\alpha^2) \\ &\geq C' \epsilon(\alpha, D)^2 \|F\|_0^2. \end{aligned}$$

Absorbing the constant C' into the definition of ϵ , it follows that there exists $\epsilon(\alpha, D) > 0$ such that $\|X_{\alpha, D} F\| \geq \epsilon(\alpha, D) \|F\|$ for all $F \in L_0^2$.

To show that this holds with a *uniform* choice of $\epsilon > 0$, suppose no such uniform choice exists; then there exists a sequence (α_n, D_n) from $\Sigma \times \Delta$ and unit vectors $F_n \in L_0^2$ such that $\|X_{\alpha_n, D_n} F_n\| \rightarrow 0$. By compactness, we may assume (α_n, D_n) converges to some (α, D) . Then

$$0 < \epsilon(\alpha, D) \leq \|X_{\alpha, D} F_n\| \leq \|X_{\alpha_n, D_n} F_n\| + \|(X_{\alpha, D} - X_{\alpha_n, D_n}) F_n\|$$

By norm continuity of $X_{\alpha, D}$, the right hand side tends to 0 as n tends to infinity, which is a contradiction. \square

4.5 Invertibility for Toeplitz Operators and Symbols

In this section we collect a few necessary lemmas on the invertibility of not only the Toeplitz operators themselves, but their relation to the invertibility of their symbols as functions in the algebra A .

Lemma 4.19 If $\phi \in L^\infty$ and $\psi \in A$, then for all $(\alpha, D) \in \Sigma \times \Delta$,

$$T_{\psi\phi}^{\alpha, D} = T_\psi^{\alpha, D} T_\phi^{\alpha, D} \quad \text{and} \quad T_{\psi\phi}^{\alpha, D} = T_{\phi}^{\alpha, D} T_\psi^{\alpha, D}.$$

Proof Let $f, g \in H_{\alpha, D}^2$. Since A acts as a multiplier algebra for $H_{\alpha, D}^2$, we also have $\psi g \in H_{\alpha, D}^2$. It follows from Lemma 4.5 that

$$\langle T_{\psi}^{\alpha, D} T_{\phi}^{\alpha, D} f, g \rangle_{\alpha} = \langle T_{\phi}^{\alpha, D} f, T_{\psi}^{\alpha, D} g \rangle_{\alpha} = \langle V_{\alpha, D}^* M_{\phi} V_{\alpha, D} f, V_{\alpha, D}^* M_{\psi} V_{\alpha, D} g \rangle_{\alpha}. \quad (11)$$

Now, since $\psi g \in H_{\alpha, D}^2$, we have that $V_{\alpha, D}^* M_{\psi} V_{\alpha, D} g = \psi g$. However, since ϕf may not be in $H_{\alpha, D}^2$, we have $V_{\alpha, D}^* M_{\phi} V_{\alpha, D} f = V_{\alpha, D}^* \phi f$. These observations allow us to see that

$$\langle V_{\alpha, D}^* M_{\phi} V_{\alpha, D} f, V_{\alpha, D}^* M_{\psi} V_{\alpha, D} g \rangle_{\alpha} = \langle V_{\alpha, D}^* \phi f, \psi g \rangle_{\alpha} = \langle \phi f, V_{\alpha, D} \psi g \rangle_{\alpha} = \langle \bar{\psi} \phi f, g \rangle_{\alpha}. \quad (12)$$

Combining (11) and (12), we have

$$\begin{aligned} \langle T_{\psi}^{\alpha, D} T_{\phi}^{\alpha, D} f, g \rangle_{\alpha} &= \langle \bar{\psi} \phi f, g \rangle_{\alpha} = \langle V_{\alpha, D} \bar{\psi} \phi f, V_{\alpha, D} g \rangle_{\alpha} = \langle \bar{\psi} \phi V_{\alpha, D} f, V_{\alpha, D} g \rangle_{\alpha} \\ &= \langle V_{\alpha, D}^* \bar{\psi} \phi V_{\alpha, D} f, g \rangle_{\alpha}. \end{aligned}$$

But, by definition $V_{\alpha, D}^* \bar{\psi} \phi V_{\alpha, D} = T_{\bar{\psi} \phi}^{\alpha, D}$, so the above becomes:

$$\langle T_{\psi}^{\alpha, D} T_{\phi}^{\alpha, D} f, g \rangle_{\alpha} = \langle T_{\bar{\psi} \phi}^{\alpha, D} f, g \rangle_{\alpha}.$$

Since this holds for all $f, g \in H_{\alpha, D}^2$, it follows that $T_{\bar{\psi} \phi}^{\alpha, D} = T_{\psi}^{\alpha, D} T_{\phi}^{\alpha, D}$. By taking adjoints (and therefore another application of Lemma 4.5), we conclude

$$T_{\psi \bar{\phi}}^{\alpha, D} = (T_{\bar{\psi} \phi}^{\alpha, D})^* = (T_{\psi}^{\alpha, D} T_{\phi}^{\alpha, D})^* = (T_{\phi}^{\alpha, D})^* (T_{\psi}^{\alpha, D})^* = T_{\phi}^{\alpha, D} T_{\psi}^{\alpha, D}.$$

□

Declare an element $\phi \in A$ to be *invertible* in A if $\phi(z) \neq 0$ for all $z \in X$ and $\phi^{-1} = \frac{1}{\phi} \in A$.

Lemma 4.20 *Let $\psi \in A$. The following are equivalent:*

- (i) ψ is invertible in A ;
- (ii) There exists $(\alpha, D) \in \Sigma \times \Delta$ such that $T_{\psi}^{\alpha, D}$ is right invertible;
- (iii) $T_{\psi}^{\alpha, D}$ is invertible for every $(\alpha, D) \in \Sigma \times \Delta$.

Moreover, $(T_{\psi}^{\alpha, D})^{-1} = T_{\psi^{-1}}^{\alpha, D}$.

Proof To begin, we suppose ψ is invertible in A and let $(\alpha, D) \in \Sigma \times \Delta$. By definition, ψ does not vanish on X and $\psi^{-1} \in A$. In particular, $\psi^{-1} \psi = \psi \psi^{-1} = 1$. This implies that

$$T_{\psi \psi^{-1}}^{\alpha, D} = T_1^{\alpha, D} = I = T_{\psi^{-1} \psi}^{\alpha, D}.$$

Where I is the identity operator. Now, we observe that both $\overline{\psi}$ and $\overline{\psi^{-1}}$ are in L^∞ . Therefore, by applying Lemma 4.19, we find that

$$T_{\psi^{-1}}^{\alpha, D} T_\psi^{\alpha, D} = T_{\psi\psi^{-1}}^{\alpha, D} = I = T_{\psi^{-1}\psi}^{\alpha, D} = T_\psi^{\alpha, D} T_{\psi^{-1}}^{\alpha, D}.$$

This shows that $T_\psi^{\alpha, D}$ is invertible for every $(\alpha, D) \in \Sigma \times \Delta$. Moreover, we see that its inverse is $T_{\psi^{-1}}^{\alpha, D}$. This establishes that (i) implies (iii). It is clear that (iii) implies (ii). Therefore it remains to show that (ii) implies (i).

To this end, let $(\alpha, D) \in \Sigma \times \Delta$ be a parameter such that $T_\psi^{\alpha, D}$ is right invertible. Then there exists an operator $X_\psi^{\alpha, D}$ such that $T^{\alpha, D} X_\psi^{\alpha, D} = I$ and so, by taking adjoints, $(X_\psi^{\alpha, D})^* (T_\psi^{\alpha, D})^* = I$. It therefore follows that, for any $f \in H_{\alpha, D}^2$,

$$\|f\| = \|(X_\psi^{\alpha, D})^* (T_\psi^{\alpha, D})^* f\| \leq \|(X_\psi^{\alpha, D})^*\| \|(T_\psi^{\alpha, D})^* f\|.$$

Thus, if we put $\delta := \frac{1}{\|(X_\psi^{\alpha, D})^*\|} > 0$, we have that $\|(T_\psi^{\alpha, D})^* f\| \geq \delta \|f\|$. Let $k_w^{\alpha, D}(z)$ be the reproducing kernel for $H_{\alpha, D}^2$. Observe that if $f \in H_{\alpha, D}^2$, then

$$\begin{aligned} \langle f, (T_\psi^{\alpha, D})^* k_w^{\alpha, D} \rangle_\alpha &= \langle T_\psi^{\alpha, D} f, k_w^{\alpha, D} \rangle_\alpha = \langle \psi f, k_w^{\alpha, D} \rangle_\alpha = \psi(w) \langle f, k_w^{\alpha, D} \rangle_\alpha \\ &= \langle f, \overline{\psi(w)} k_w^{\alpha, D} \rangle_\alpha. \end{aligned}$$

Thus we yield the following eigenvector relationship:

$$(T_\psi^{\alpha, D})^* k_w^{\alpha, D} = \overline{\psi(w)} k_w^{\alpha, D}.$$

Since $k_w^{\alpha, D} \in H_{\alpha, D}^2$, we have that

$$|\overline{\psi(w)}| \|k_w^{\alpha, D}\| = \|(T_\psi^{\alpha, D})^* k_w^{\alpha, D}\| \geq \delta \|k_w^{\alpha, D}\|. \quad (13)$$

Let $\Omega = \{w \in X : \psi(w) \neq 0 \text{ and } k_w^{\alpha, D} \neq 0\}$. Observe that Ω is a dense subset of X . Moreover, on Ω , we can form $\frac{1}{\psi}$ and divide by $\|k_w^{\alpha, D}\|$. Thus, (13) implies that $|\frac{1}{\psi}(w)| \leq \frac{1}{\delta}$ for $w \in \Omega$ and hence everywhere by continuity. Thus ψ does not vanish on X and therefore ψ is invertible in A . \square

5 The Widom Theorem for Constrained Algebras

Lemma 5.1 *Let $\phi \in L^\infty$ be unimodular. If there exists $\psi \in A$ such that $\|\phi - \psi\| < 1$, then $T_\phi^{\alpha, D}$ is left-invertible for every $(\alpha, D) \in \Sigma \times \Delta$. Further, if ψ is invertible in A , then $T_\phi^{\alpha, D}$ is invertible for every $(\alpha, D) \in \Sigma \times \Delta$.*

Proof Suppose $\psi \in A$ is such that $\|\phi - \psi\| < 1$. Since ϕ is unimodular, $\|1 - \psi\bar{\phi}\| \leq 1$. Therefore, it follows from Lemma 4.5, that

$$\|1 - T_{\phi\bar{\phi}}^{\alpha, D}\| = \|T_{1-\psi\bar{\phi}}^{\alpha, D}\| = \|1 - \psi\bar{\phi}\| < 1.$$

This directly implies that $T_{\psi\bar{\phi}}^{\alpha, D}$ is invertible. Thus, by Lemma 4.19, it follows that $T_{\phi}^{\alpha, D}$ is left-invertible. Suppose further that ψ is invertible in A . By Lemma 4.20, we have that $T_{\psi}^{\alpha, D}$ is invertible. It follows that $T_{\phi}^{\alpha, D}$ is right invertible and therefore $T_{\phi}^{\alpha, D}$ is totally invertible. \square

Lemma 5.2 *If $f, g \in L^2$, then for all $\alpha \in \Sigma$,*

$$|\langle f, g \rangle_2| \leq \|f\|_{2, -\alpha} \|g\|_{2, \alpha}.$$

Proof Let $\alpha \in \Sigma$. By the classic Cauchy-Schwarz inequality,

$$\begin{aligned} |\langle f, g \rangle_2| &= \left| \int_{\partial X} f\bar{g} \, dm \right| = \left| \int_{\partial X} f\bar{g} |Z|^{-\frac{\alpha}{2}} |Z|^{\frac{\alpha}{2}} \, dm \right| \\ &= \left| \langle f |Z|^{-\frac{\alpha}{2}}, g |Z|^{\frac{\alpha}{2}} \rangle_2 \right| \leq \|f |Z|^{-\frac{\alpha}{2}}\|_2 \|g |Z|^{\frac{\alpha}{2}}\|_2 \end{aligned}$$

Therefore

$$|\langle f, g \rangle_2| \leq \int_{\partial X} |f|^2 |Z|^{-\alpha} \, dm \int_{\partial X} |g|^2 |Z|^{\alpha} \, dm = \|f\|_{2, -\alpha} \|g\|_{2, \alpha}.$$

\square

Lemma 5.3 *Suppose $\phi \in L^\infty$ is unimodular. The distance from ϕ to A is strictly less than one if and only if $T_{\phi}^{\alpha, D}$ is left-invertible for every $(\alpha, D) \in \Sigma \times \Delta$.*

Proof Suppose that the distance from ϕ to A is strictly less than one. Lemma 5.1 implies that $T_{\phi}^{\alpha, D}$ is left-invertible for every $(\alpha, D) \in \Sigma \times \Delta$. Now assume that $T_{\phi}^{\alpha, D}$ is left-invertible for every $(\alpha, D) \in \Sigma \times \Delta$.

By Proposition 4.13, there exists a uniform $\varepsilon > 0$ (independent of (α, D)) such that, for all (α, D) and $f \in H_{\alpha, D}^2$,

$$\|T_{\phi}^{\alpha, D} f\| \geq \varepsilon \|f\|_{\alpha}. \quad (14)$$

Let $h \in \mathcal{M}_M = v^{-1}\mathcal{M} + \mathcal{S}$. By Lemma 4.12, there exists $(-\beta, D) \in \Sigma \times \Delta$, $f \in H_{-\beta, D}^2$, and $g \in L_{-\beta}^2$ such that $h = fg$, $\|h\|_1 = \|f\|_{2, -\beta} \|g\|_{2, \beta}$, and $\langle \psi, \bar{g} \rangle_2 = 0$ for all $\psi \in H_{-\beta, D}^2$. Recall that $P_{-\beta, D}$ is the orthogonal projection from $L_{-\beta}^2$ onto

$H_{-\beta, D}^2$. Thus, on one hand Lemma 5.2 gives rise to the following estimate:

$$\begin{aligned} \left| \int_{\partial X} \phi h \, dm \right| &= \left| \int_{\partial X} \phi f g \, dm \right| \\ &= |\langle \phi f, \bar{g} \rangle_2| \\ &= |\langle \phi f, (I - P_{-\beta, D})\bar{g} \rangle_2| \\ &= |\langle (I - P_{-\beta, D})\phi f, \bar{g} \rangle_2| \\ &\leq \|(I - P_{-\beta, D})\phi f\|_{2, -\beta} \|g\|_{2, \beta}. \end{aligned}$$

While on the other hand, the Pythagorean theorem and the fact that ϕ is unimodular asserts that

$$\begin{aligned} \|f\|_{2, -\beta}^2 &= \|\phi f\|_{2, -\beta}^2 = \|P_{-\beta, D}\phi f + (I - P_{-\beta, D})\phi f\|_{2, -\beta}^2 \\ &= \|P_{-\beta, D}\phi f\|_{2, -\beta}^2 + \|(I - P_{-\beta, D})\phi f\|_{2, -\beta}^2. \end{aligned}$$

Now, combining (14) and the fact that $P_{-\beta, D}\phi f = T_{\phi}^{-\beta, D}f$, the above equality becomes

$$\begin{aligned} \|f\|_{2, -\beta}^2 &= \|T_{\phi}^{-\beta, D}\phi f\|_{2, -\beta}^2 + \|(I - P_{-\beta, D})\phi f\|_{2, -\beta}^2 \geq \varepsilon^2 \|f\|_{2, -\beta}^2 \\ &\quad + \|(I - P_{-\beta, D})\phi f\|_{2, -\beta}^2. \end{aligned}$$

and therefore

$$\|(I - P_{-\beta, D})\phi f\|_{2, -\beta}^2 \leq \sqrt{1 - \varepsilon^2} \|f\|_{2, -\beta}.$$

The above estimate, along with the estimate we had on the integral of ϕh guarantee that

$$\begin{aligned} \left| \int_{\partial X} \phi h \, dm \right| &\leq \|(I - P_{-\beta, D})\phi f\|_{2, -\beta} \|g\|_{2, \beta} \\ &\leq \sqrt{1 - \varepsilon^2} \|f\|_{2, -\beta} \|g\|_{2, \beta} = \sqrt{1 - \varepsilon^2} \|h\|_1. \end{aligned} \tag{15}$$

Note that the above estimate is holding for $h \in \mathcal{M}_M$, a dense subset of \mathcal{M} . Since integrating against ϕ and $\|\cdot\|_1$ are each continuous linear functionals, the fact that inequality in (15) holds for a dense subset of \mathcal{M} immediately implies that it will hold for all $h \in \mathcal{M}$. Recall that by Lemma 4.9, the map $\Lambda: L^\infty/A \rightarrow \mathcal{M}^*$ sending $\pi(\phi) \mapsto (\lambda_\phi)|_{\mathcal{M}}$, where $\lambda_\phi: L^1 \rightarrow \mathbb{C}$ is the functional sending $\psi \mapsto \int_{\partial X} \phi \psi$, is an isometric isomorphism.

Since (15) holds for $h \in \mathcal{M}$, we find that $\|\lambda_\phi(h)|_{\mathcal{M}}\| < 1$. Since Λ is an isometry, this implies that $\|\pi(\phi)\| < 1$. Since the norm of a vector is interpreted as its distance from the ‘zero’ element, this implies that the distance from ϕ to A is strictly less than one. \square

Theorem 1.8 (Widom Theorem for A) Suppose $\phi \in L^\infty$ is unimodular. $T_\phi^{\alpha, D}$ is left-invertible for each $(\alpha, D) \in \Sigma \times \Delta$ if and only if $\text{dist}(\phi, A) < 1$. In particular, $T_\phi^{\alpha, D}$ is invertible for each $(\alpha, D) \in \Sigma \times \Delta$ if and only if $\text{dist}(\phi, A^{-1}) < 1$.

Proof Everything aside from the ‘in particular’ statement has been proven in Lemmas 5.1 and 5.3.

Thus, suppose $T_\phi^{\alpha, D}$ is invertible for each $(\alpha, D) \in \Sigma \times \Delta$. Lemma 5.3 guarantees that there exists $\psi \in A$ such that $\|\psi - \phi\| < 1$. We need to argue that ψ is invertible in A .

By Lemma 5.1, we know that $T_{\bar{\phi}}^{\alpha, D} T_\psi^{\alpha, D}$ and $T_\phi^{\alpha, D}$ are invertible. By taking its adjoint, we have that $(T_\phi^{\alpha, D})^* = T_{\bar{\phi}}^{\alpha, D}$ is invertible. Since both $T_{\bar{\phi}}^{\alpha, D} T_\psi^{\alpha, D}$ and $T_{\bar{\phi}}^{\alpha, D}$ are invertible, we find that $T_\psi^{\alpha, D}$ is necessarily invertible. Applying Lemma 4.20, we conclude that ψ is invertible in A as desired.

Conversely, suppose there exists an invertible $\psi \in A$ such that $\|\psi - \phi\| < 1$. Lemma 5.1 asserts that $T_\phi^{\alpha, D}$ is invertible for all $(\alpha, D) \in \Sigma \times \Delta$. \square

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