



On the Possibility of Stellar Lenses in the Black Hole Candidate Microlensing Events MACHO-96-BLG-5 and MACHO-98-BLG-6

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Abstract

Although stellar-mass black holes (BHs) are likely to be abundant in the Milky Way ($N = 10^8 - 10^9$), only 20 have been detected to date, all in accreting binary systems. Gravitational microlensing is a proposed technique to search for *isolated* BHs, which have not yet been detected. Two specific microlensing events, MACHO-1996-BLG-5 (M96-B5) and MACHO-1998-BLG-6 (M98-B6), initially observed near the lens-source minimum angular separation in 1996 and 1998, respectively, have long Einstein crossing times (>300 days), identifying the lenses as candidate black holes. Twenty years have elapsed since the time of lens-source closest approach for each of these events, indicating that if the lens and source are both luminous, and if their relative proper motion is sufficiently large, the two components should be spatially resolvable. In this work, we attempt to eliminate the possibility of a stellar lens for these events by: (1) using Keck near-infrared adaptive optics images to search for a potentially now-resolved, luminous lens, and (2) examining multi-band photometry of the source to search for flux contributions from a potentially unresolved, luminous lens. We combine detection limits from NIRC2 images with light-curve data to eliminate all non-BH lenses for relative lens-source proper motions above 0.81 mas yr^{-1} for M96-B5, and 2.48 mas yr^{-1} for M98-B6. Furthermore, we use WFPC2 broad-band images to eliminate the possibility of stellar lenses at any proper motion. We present the narrow range of non-BH possibilities permitted by our varied analyses. Finally, we suggest future observations to constrain the remaining parameter space via the methods developed in this work.

Unified Astronomy Thesaurus concepts: Gravitational microlensing (672); High-resolution microlensing event imaging (2138); Black holes (162); Stellar-mass black holes (1611); Compact objects (288); Light curves (918)

1. Introduction

The detection of isolated black holes (BHs) remains a problem of both great importance and great difficulty in astrophysics. Core-collapse supernova events mark the deaths of high-mass ($\gtrsim 8 M_\odot$) stars, and are predicted to leave remnant BHs on the order of several to tens of M_\odot . An estimated $10^8 - 10^9$ stellar-mass black holes are predicted to occupy the Milky Way (Agol et al. 2002). However, only ~ 20 have so far been detected, all in accreting binaries (Casares 2006; Reynolds & Miller 2013; Casares & Jonker 2014). More recently, BH binaries have been identified by gravitational waves emitted from their mergers (Abbott et al. 2016). Isolated BHs, which could comprise the majority of the BH population (Wiktorowicz et al. 2019), remain elusive, with no confirmed detections to date. Detecting isolated BHs, and measuring their masses, would help constrain the number density of BHs, as well as the initial-final mass relation—which designates which stars become BHs versus neutron stars or white dwarfs—in turn informing the understanding of BH formation, supernova physics, and the equation of state for nuclear matter (Lu et al. 2016).

While an isolated BH does not produce a detectable electromagnetic radiation signature, it is in principle detectable as a lens in a gravitational microlensing event, whereby the gravitational potential of a massive lensing object refracts and focuses the light of a background source in accordance with their time-dependent angular separation on the plane of the sky (Paczynski 1986; Paczynski & Wambsganss 1993; Mao 2012). One characterizing feature of such an event is the Einstein radius, θ_E , which describes the radius of the source image,

given the physical alignment of an event’s source, lens, and observer, and is defined as:

$$\theta_E = \sqrt{\frac{4GM}{c^2}(d_L^{-1} - d_S^{-1})} \quad (1)$$

where G is the gravitational constant, M is the lens mass, c is the speed of light, d_L is the observer-lens distance, and d_S is the observer-source distance. More readily recoverable from a microlensing light curve, however, is the Einstein crossing time, t_E , which is related to an event’s Einstein radius and relative source-lens proper motion, μ_{rel} , by:

$$\theta_E = \mu_{\text{rel}} t_E. \quad (2)$$

While t_E encodes all of the physical parameters of an event (i.e., lens mass and lens and source distances), in the absence of additional signals such as finite source effects, astrometric shifts, or parallax, one is limited to applying a Bayesian prior from a Galactic model, and estimating (rather than measuring) the lens mass. The only second-order effect considered in this work is parallax, which causes an asymmetric distortion to a point-source point-lens (PSPL) microlensing light curve. In microlensing formalism, the “microlensing parallax,” π_E , is defined as:

$$\pi_E = \frac{1 \text{ au}(d_L^{-1} - d_S^{-1})}{\theta_E} \hat{\theta}_E. \quad (3)$$

The microlensing parallax can be understood as the ratio between the Earth’s orbit and the Einstein radius of the microlensing event, projected onto the observer plane.

Currently, several surveys monitor many tens of square degrees near the Galactic Bulge in search of the photometric variability characteristic of microlensing events—the fourth phase of the Optical Gravitational Lensing Experiment (OGLE-IV; Udalski et al. 1993, 2015), the Microlensing Observations in Astrophysics collaboration (MOA-II; Bond et al. 2001; Sako et al. 2008), and the Korea Microlensing Telescope Network (KMTNet; Kim et al. 2016). Historically, the MACHO Project³ used microlensing to search specifically for MAssive Compact Halo Objects (MACHOs), a hypothesized form of dark matter in the Milky Way halo that may include BHs (Alcock et al. 1993). Previous works have considered events from the MACHO survey, as well as the OGLE survey, in relation to the possible presence of BH lenses (Mao et al. 2002; Wyrzykowski et al. 2016), although these have largely been limited to the examination of microlensing light curves. In this work, we will similarly examine the light curves of two events discovered in the MACHO survey, with the addition of more recent data from several different telescopes.

MACHO-96-BLG-5, and MACHO-98-BLG-6 (hereafter referred to as M96-B5 and M98-B6, respectively) are microlensing events first detected and observed using long-term photometric monitoring (Bennett et al. 2002). M96-B5 and M98-B6 represent two of forty-five candidates detected toward the Galactic bulge. M96-B5 was previously identified in 1996 as a BH candidate, due to its exceptionally long Einstein crossing time of ~ 970 days. For this event, the mass of the lens was estimated to be $M = 6_{-3}^{+10} M_{\odot}$, and its Heliocentric distance within the range of 0.5–2 kpc (Nucita et al. 2006). However, because these estimations were derived from fitting light curves alone—a process that necessarily exhibits degeneracies—they are heavily influenced by the imposed Galactic model prior. Another analysis of this event strongly excluded the possibility of the lens being a main-sequence star, due to brightness constraints given by Hubble Space Telescope data, and their mass constraints ruled out the possibility of the lens being a neutron star (Bennett et al. 2002). The event was found by Smith et al. (2005) to be inconsistent with a microlensing event occurring in a galaxy that did not include stellar-remnant populations, based on simulations of microlensing light curves created from Galactic models that did not include neutron stars, white dwarfs, or black holes. M96-B5 was found to be measurably affected by microlensing parallax (Bennett et al. 2002), and, in addition, exhibits minor perturbations due to xallarap (Poindexter et al. 2005), which refers to the accelerated motion of the source due to its binary companion, and which can complicate the determination of the source’s angular position at the time of the event (Gould & Yee 2014). M96-B5 was designated as a marginal BH candidate, with a determined 37% likelihood of being a black hole (Poindexter et al. 2005).

The second candidate in this work, M98-B6, is a microlensing event, identified in 1998 as a possible BH. The mass of the BH candidate for the event is estimated to be $M = 6_{-3}^{+7} M_{\odot}$ (Nucita et al. 2006), although again, this result was dependent on current Galactic models. The source star has a heliocentric radial velocity of $-39 \pm 20 \text{ km s}^{-1}$, and is classified as a G5 IV spectral type (Soto et al. 2007). Bennett et al. (2002) were not able to strongly exclude the possibility of the lens being either a main-sequence star or a neutron star from their constraints, as both possibilities still have small likelihoods due to the

confidence levels used. The event is consistent with the simulations of Smith et al. (2005), as described in the previous paragraph, which would make the possibility of a main-sequence lens seem more likely. M98-B6 is also affected by parallax, with minor perturbations from xallarap (Poindexter et al. 2005). It is considered to be a weak BH candidate (2.2% likelihood) (Poindexter et al. 2005).

The remainder of this paper is structured as follows: In Section 2 we describe the observations and data sets contributing to this study. In Section 3 we lay out the reduction processes used on the relevant data sets. In Section 4 we examine the detection limits for a luminous lens in recent, near-infrared (NIR) images. In Section 5 we fit microlensing light-curve models to each event, and use the resultant fits to separately constrain the flux contributions from the lens and source. In Section 6 we photometrically and astrometrically analyze the source stars in an effort to determine whether the lens is detectably luminous. In Section 7 we synthesize the different constraints, and we discuss the likelihood of each event being a BH in Section 8. Finally, in Section 9 we present the conclusions of our study.

2. Data Sets

2.1. Keck Observations

The primary data presented in this paper are imaging observations of M96-B5 and M98-B6 taken with the NIR camera (NIRC2) on the W.M. Keck II 10 m telescope behind the laser guide star adaptive optics (LGS AO) system (Wizinowich et al. 2006). Images were captured using the NIRC2 narrow camera in the *Kp* filter over a $10'' \times 10''$ field, with a plate scale of $9.952 \text{ mas pixel}^{-1}$ (Service et al. 2016). Figure 1 shows the two fields, with the target marked at its center in each case.

Both targets were observed on 2016 July 14 UT, approximately 20 yr after peak magnification of the corresponding microlensing events. Each target was observed several times in succession, with a total integration time of 540 s for M96-B5, and 220 s for M98-B6. In order to remove detector artifacts such as bad pixels, images were captured using a random dither pattern, within a $0''.7 \times 0''.7$ box.

A second epoch of NIRC2 data was taken for each of the two events in 2017, so as to constrain motion. Additional details of all observations are provided in Table 1.

2.2. MACHO Light Curves

Both events discussed in this paper were first identified by the MACHO Project, in which 10–20 million stars in the Galactic bulge were surveyed between 1993 and 1999. The primary data set comes from the Mt. Stromlo 1.3 m telescope, via two filters: B_{MACHO} ($\sim 450\text{--}630 \text{ nm}$) and R_{MACHO} ($\sim 630\text{--}760 \text{ nm}$). The establishment of the MACHO Alert system made follow-up observations from additional telescopes possible. As such, there are additional data for both events, from the CTIO 0.9 m telescope, and the Mt. Stromlo 1.9 m telescope (Alcock et al. 2000).

In this work, we used the reduced and calibrated light curves for these targets, taken from Bennett et al. (2002).

³ A full description of the MACHO Project can be found at <http://www.macho.anu.edu.au/Project/Overview/status.html>.

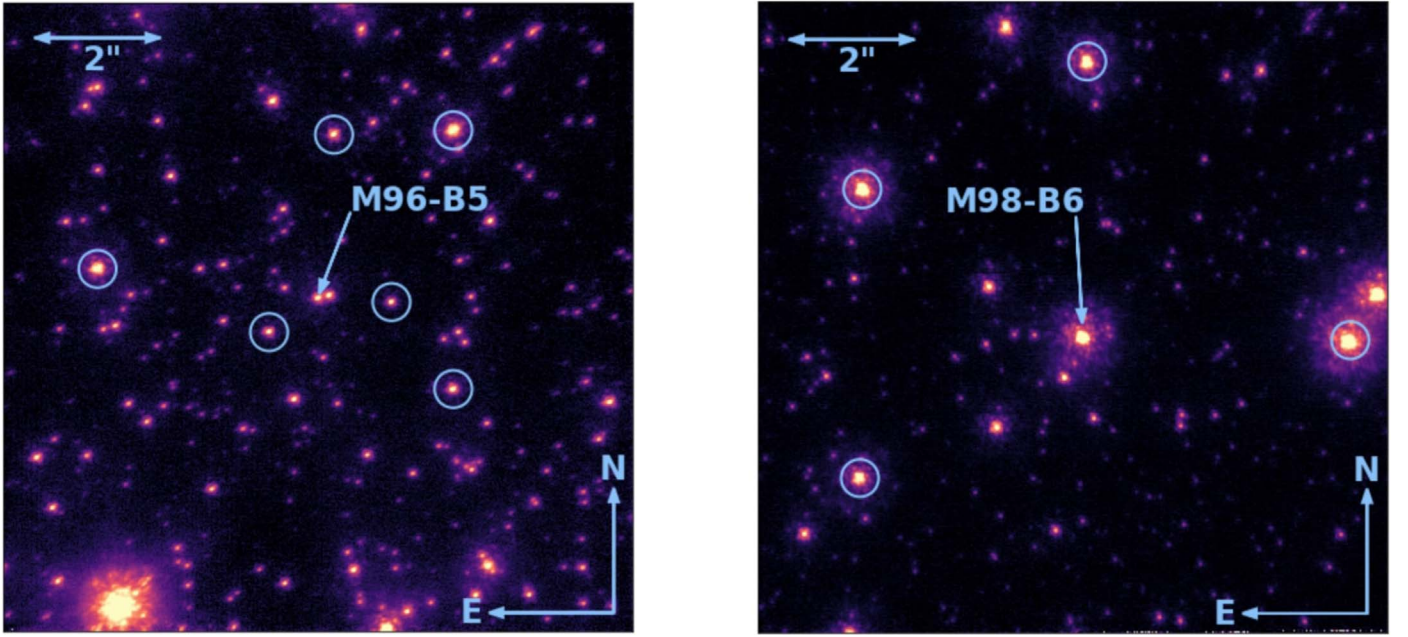


Figure 1. 2016 NIRC2 images of M96-B5 (left) and M98-B6 (right). In each case, the background source star of the microlensing event is labeled with the event name. Stars used to create the mean PSF (see Section 4.1) are circled in light blue. PSF star selection was based on cuts in brightness, proximity to the target, and isolation. Note, the images have a logarithmic color scale.

Table 1
NIRC2 Observations

Target	R.A. (J2000)	Decl. (J2000)	Epoch (UT)	N_{exp}	Int. Time (s)	Coadds	N_{stars}	Strehl	FWHM (mas)	m_{base}
M96-B5	18:05:02.5	−27:42:17	2016-07-14	9	60	1	297	0.22	70	16.864 ± 0.035
			2017-05-21	5	5	6	130	0.21	67	16.909 ± 0.032
M98-B6	17:57:32.8	−28:42:45	2016-07-14	22	10	1	344	0.33	58	12.895 ± 0.033
			2017-06-08	15	2	1	74	0.19	82	12.868 ± 0.035

Note. Strehl and FWHM are the average values of all N_{stars} stars over all N_{exp} individual exposures. Baseline (unlensed) magnitude, m_{base} , indicates the target magnitude in NIRC2’s “Kp” filter.

2.3. Gaia Early Data Release 3

In order to define an absolute astrometric reference frame for measurements of the targets’ proper motions, we use data from Gaia Early Data Release 3 (EDR3) (Brown et al. 2021; Fabricius et al. 2021; Lindegren et al. 2021; Riello et al. 2021). The EDR3 source list was queried for all sources within a $36'' \times 36''$ box, centered on each target. For the stars yielded by this search, we used only position information (R.A. and declination). In addition, a star in EDR3 was found to correspond to the location of the event M98-B5, the relevant characteristics of which are given below in Table 2. This star is the probable source in the lensing event, although this could also be a combination of lens and source (a possibility we will further examine in Sections 5.2 and 6).

2.4. HST Broad-band Photometry

In order to compile multi-band photometry for the microlensing event sources, we utilized archival data from the Hubble Space Telescope’s WFPC2 instrument (HST-GO-8654, PI: Bennet, David P.). Observations were taken across 7 epochs between 1999 and 2003 for M96-B5, and a single epoch in 2000 for M98-B6. The data were taken in four wide filters: F439W, F555W, F675W, and F814W. In all cases, the target fell on the PC chip of the 4-chip camera. This 800×800 pixel

CCD has a plate scale of $45.5 \text{ mas pixel}^{-1}$, corresponding to a $36'' \times 36''$ field of view (Gonzaga 2010). Additional details relating to the HST images used are shown in Table 3. The data used were downloaded in 2018 November.

3. Raw Reduction and Catalog Creation

3.1. Keck Reduction and Star-finding with AIROPA

The initial reduction of raw data from each epoch of observation was carried out by means of our custom NIRC2 reduction pipeline (Stolte et al. 2008; Lu et al. 2009), and included flat-field and dark calibration, sky subtraction, and cosmic-ray removal. The cleaned exposures were corrected for distortion and achromatic differential atmospheric refraction, shifted to a common coordinate system, and then combined, weighted by Strehl using the IRAF routine, *Drizzle* (Fruchter & Hook 2002), as described in Yelda et al. (2010). The final combined image was restricted to individual frames displaying core $\text{FWHM} < 1.25 \text{ FWHM}_{\text{min}}$, where FWHM_{min} is the minimum FWHM of all frames of the particular target and epoch.

For each combined map, we used the point-spread function (PSF) fitting routine, *AIROPA* (Witzel et al. 2016), which is based on *StarFinder* (Diolaiti et al. 2000), to extract a stellar catalog of spatial coordinates and relative brightness. *AIROPA* is used in single-PSF mode, which assumes that the

Table 2
Gaia Data for M98-B5 Position Match

Quantity	Value	Error
Source ID	4062585513471740288	
R.A. (deg)	269.38573681	2.4×10^{-8}
Decl. (deg)	-28.71091478	1.9×10^{-8}
R.A. Proper Motion (mas yr ⁻¹)	-2.98	0.11
Decl. Proper Motion (mas yr ⁻¹)	0.812	0.075
Parallax (mas)	0.150	0.096
Magnitude (g)	16.9661	0.0024
T_{eff} (K)	4465.25	$+478.69/-582.60$
ruwe	1.29	

Note. Properties of the Gaia EDR3 object corresponding to the location of the event M98-B5.

Table 3
WFPC2 Observations

Target	Filter	Epoch	N_{exp}	t_{int} (s)	m_{base}
M96-B5	F439W	2000-06-11	6	2200	20.609 ± 0.034
	F555W	1999-06-15	2	800	18.826 ± 0.016
		2000-06-11	5	3240	19.027 ± 0.027
		2001-06-03	2	800	18.877 ± 0.095
		2001-10-01	2	800	18.884 ± 0.047
		2002-05-25	2	800	19.021 ± 0.009
		2002-10-02	2	800	18.995 ± 0.041
		2003-05-27	2	800	19.042 ± 0.009
	F675W	2000-06-11	5	1080	17.969 ± 0.015
	F814W	1999-06-15	4	800	17.141 ± 0.054
		2000-06-11	5	3240	17.304 ± 0.017
		2001-06-03	4	800	17.336 ± 0.015
		2001-10-02	4	800	17.310 ± 0.026
		2002-05-25	4	800	17.333 ± 0.020
		2002-10-02	4	800	17.365 ± 0.008
		2003-05-27	4	800	17.341 ± 0.009
M98-B6	F439W	2000-06-23	1	40	17.996 ± 0.044
	F555W	2000-06-23	1	260	16.038 ± 0.044
	F675W	2000-06-23	1	100	14.677 ± 0.044
	F814W	2000-06-23	1	100	13.834 ± 0.044

Note. Observational parameters for archival HST data of MB96 and MB98. For a given target, filter, and epoch, there are N_{exp} frames with a combined integration time of t_{int} . The baseline (unlensed) magnitude, m_{base} , represents the mean value and uncertainty in the mean of all frames, in epochs with multiple observations. For epochs with a single observation, the uncertainty was set by inflating the uncertainties of multi-frame epochs with similar exposure times by the square root of the number of frames.

PSF is uniform over the field of view. Firstly, the PSFs of a subset of stars (hereafter “PSF stars”) were averaged to extract a mean PSF. The PSF was then cross-correlated with the image, and stars were identified as peaks with a correlation above 0.8. In addition, we ran *StarFinder* in “deblend” mode, in order to check for a difference in sensitivity to close pairs of stars. There was no difference in the number of stars detected within the central $0''.5$ of either target (the range within which it would be reasonable to find a resolved lens). As such, AIROPA was

run in normal (“non-deblend”) mode for the remainder of this work.

The accuracy of our PSF directly impacts on the contrast (i.e., our ability to detect a faint lens near the brighter source) as well as on astrometric precision. As such, we applied strict criteria in the selection of the PSF stars. Specifically, stars contributed to the mean PSF derivation if they were bright (typically $K_p < 18$ mag), isolated, and within $4''$ of the center of the field. The latter criterion avoids detector edge effects, and ensures that all PSF stars are close to the target of interest, mitigating errors due to spatial variation of the PSF, caused by instrumental aberrations and atmospheric anisoplanatism.

The resulting starlists produced by AIROPA contain positions and fluxes for each star in detector units of pixels and counts, respectively. Residual images with found sources removed were also created for each target/epoch. Instrumental magnitudes were calibrated to K_p using J , H , and K_s magnitudes from the VVV Survey DR2 (Minniti et al. 2017).

3.2. HST Reduction with *img2xyrduv*

In order to extract photometry from the archival HST data, we used the FORTRAN program *img2xyrduv*, developed for use with WFPC2 images (Anderson & King 2006). The code uses criteria set by the user to find stars in an image, before fitting them to a PSF model. The output includes instrumental magnitudes derived from the fluxes, in ADU, as determined by the PSF fits, together with distortion-corrected centroid positions.

To calibrate the magnitudes produced by *img2xyrduv*, we divided the observed flux in ADU by the total exposure time, and applied the VEGAMAG system zero-points for WFPC2 (Gonzaga 2010). However, these zero-points are defined for counts measured in a $0''.5$ radius aperture; we therefore applied an additional ΔZP to calibrate the *img2xyrduv* magnitudes extracted from a smaller aperture. We determined ΔZP by performing aperture photometry on the calibrated images with a $0''.5$ radius aperture, positioned on the centroids’ output by *img2xyrduv*. A sigma-clipped median pixel value in each image was used as the sky value to be subtracted from the aperture sums, and the resulting counts, N_{aper} , were then propagated through the equation

$$m_{\text{aper}} = -2.5 \log_{10} \left(\frac{N_{\text{aper}} \cdot g}{t_{\text{exp}}} \right) \quad (4)$$

along with the gain, g , and exposure time, t_{exp} , to derive the magnitude, m_{aper} . The differences between m_{aper} and the *img2xyrduv* magnitudes for the brightest 10% of stars in an image was median-combined to define $\Delta ZP = m_{\text{aper}} - m_{\text{img}}$. Finally, the calibrated magnitudes were computed as

$$m = m_{\text{img}} + ZP + \Delta ZP \quad (5)$$

where m_{img} is the *img2xyrduv*-determined magnitude, and ZP is the zero-point taken from Holtzman et al. (1995).

3.3. Comparison of Archival and Current Images

Equipped with starlists from both our late-time (2016–2017) Keck images, and early-time images (1999–2003), we can now determine whether a new luminous lens was detected. For a lens to be a black hole, there should be no source in the near vicinity of the late-time images not present in the early-time images.

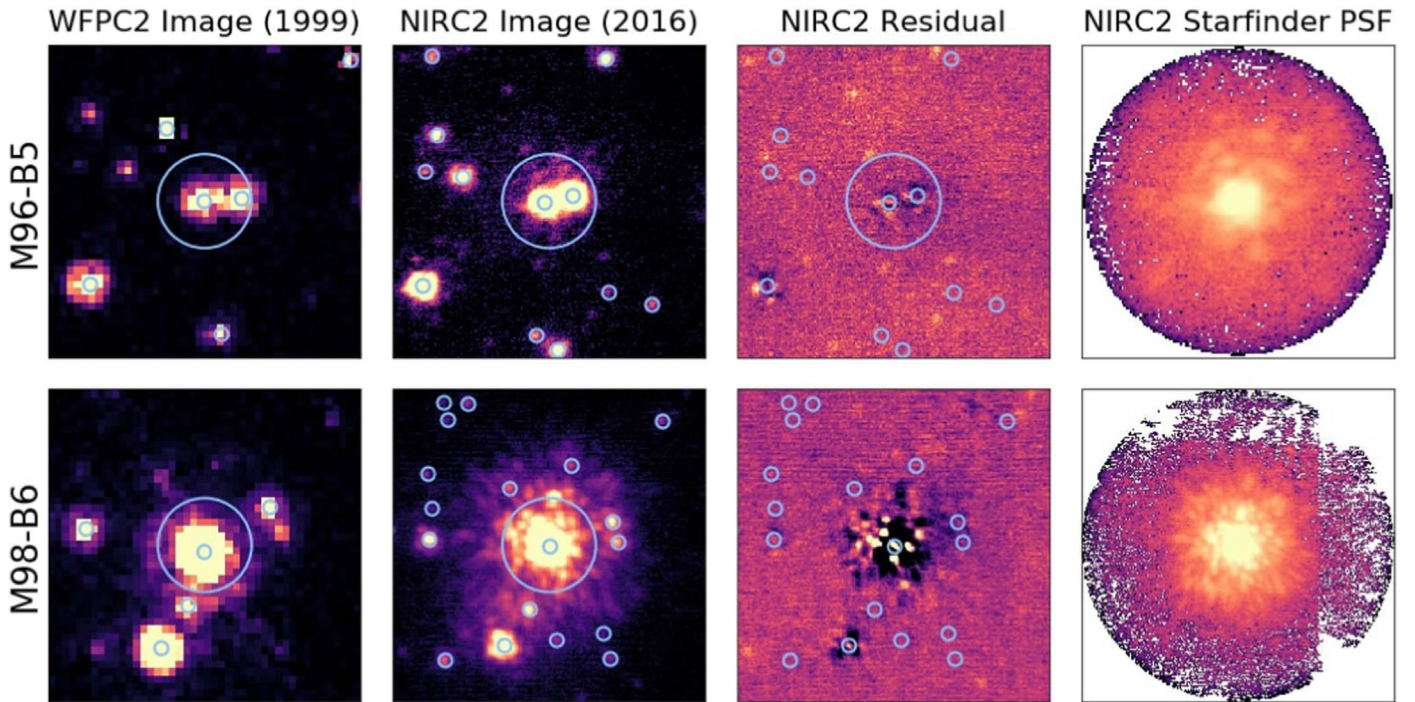


Figure 2. Zoomed-in images of M96-B5 (top), and M98-B6 (bottom). For each row, there is an HST image (right) in 1999, shortly after the microlensing events (left), an NIRC2 image from 2016 (center), and the PSF of the NIRC2 image, as determined by AIROPA (right). The sky images are each $2''$ across, with a large light-blue circle with radius $0.3''$ centered on each target. All sources found by AIROPA are indicated by smaller red circles. In both cases, no new sources have appeared within $0.3''$ of the source, which corresponds to the maximum separation of a lens moving with a proper motion of 15 mas yr^{-1} .

Searching within a radius of $3''$ of the source (corresponding to a maximum proper motion of 15.2 mas yr^{-1} for M96-B5, and 16.7 mas yr^{-1} for M98-B6), no new sources appear. Visual comparisons of these images, for both targets, are shown in Figure 2. To understand the limitations of this comparison, however, we must examine our detection sensitivity.

4. Detection Limits on Luminous Lenses

4.1. Star Planting

To estimate the detection sensitivity of the images, a series of star planting simulations was conducted. Individual stars were planted in each image by taking a copy of the PSF created using the original image. In order to reduce computational time, the main image and background image were cropped from a 1064×1064 pixel array down to 200×200 pixels, and the PSF was cropped down from 200×200 to 30×30 pixels. Usually, the PSF is normalized, such that the integral over the entire PSF has a value of one. However, because the cropped PSF (cPSF) was taken from an initially normalized PSF, the integral over the cropped PSF is less than one. The cPSF was then calibrated to a chosen magnitude and Poisson noise was added. The resulting calibrated and noisy cPSF functioned as an artificial star. This artificial star was then planted in the image, with its center located at pixel position x_i, y_i on the image. A total of 167,445 artificial stars were planted for each event, varying in magnitude from 12.00 to 23.00, with steps of 0.25, and in location from -30 to 30 pixels in both the x - and y -directions around the target. The resulting image, with a single planted star, was analyzed using AIROPA, in an identical manner to that used on the original image, using the exact same PSF. It was also put through StarFinder to determine whether the planted star could be detected. The planted star was considered detected if its position in the new starlist matched

the input location to within a single pixel in both the x - and y -direction, and if its magnitude agreed with the input to within 0.5 mag.

A radial completeness curve was created by binning the artificial stars into magnitude bins of 0.25 mag, and radial bins, using a sliding window of 39.72 mas (4 pixels). Within each magnitude-radius bin, the completeness was determined by calculating the percentage of planted stars detected within a given category. A completeness value of 1.0 corresponds to a detection percentage of 100%, and a value of 0.0 corresponds to a detection percentage of 0%. Limiting magnitudes were determined for each radial bin by taking the faintest magnitude with a completeness value of at least 0.95. The limiting magnitudes were given the average magnitude of each bin, and the average radius of each window (Figure 3). No limiting magnitudes were used that exceeded the brightness of the respective source.

4.2. Isochrones Based on Magnitude

The limiting magnitudes were converted to stellar masses, as described below, and used to determine the permitted mass range for an undetected, luminous stellar lens. Synthetic isochrones were generated using the program SPISEA (M. Hosek et al. 2021, in preparation). Isochrones were generated for a given age in $\log(\text{yr})$, distance in pc, and extinction value A_k , assuming solar metallicity. Distances ranged from 1 to 10 kpc, with steps of 1 kpc. The extinction values, which are dependent on the Galactic coordinates and distance of the source, were determined using the Argonaut Skymaps (Green et al. 2015; Green et al. 2018), which output an $E(B - V)$ value. This $E(B - V)$ was then used to calculate an A_V value by assuming that $R_V = 3.1$. Next, the extinction value, A_k , was calculated, using the extinction law given in Schlafly & Finkbeiner (2011). As a proxy for a

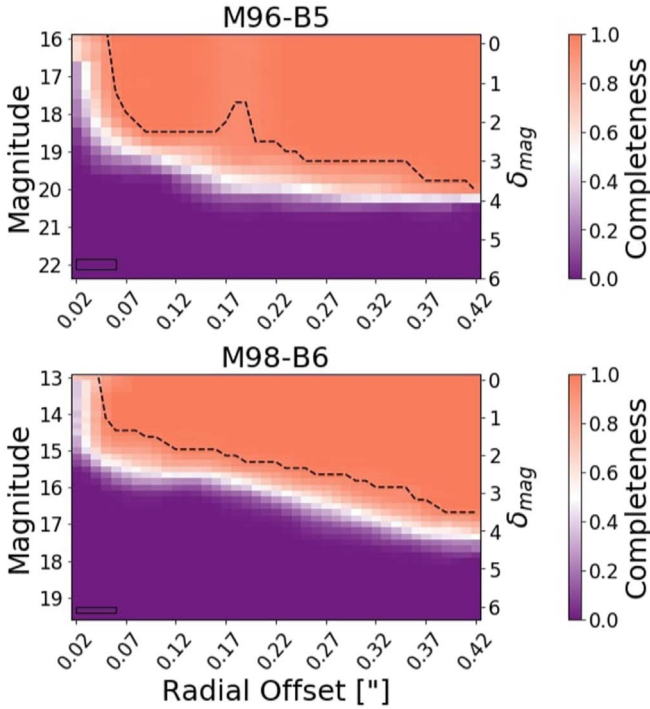


Figure 3. Completeness curves for MB 96-5 (top) and MB 98-6 (bottom). 95% completeness is indicated by dashed black lines. By finding where the detection completeness for a given magnitude goes below 0.95, we determined the magnitude range of a stellar lens undetectable by *Starfinder*. These magnitude ranges provided us with our upper limits for the mass of an undetectable, but luminous, stellar lens.

“zero-age main sequence,” we adopted an age of 100 Myr to obtain a nearly fully main sequence, while also excluding pre-main-sequence stars.

Using the generated isochrones, mass-value outputs were taken for any isochrone entries matching a given limiting magnitude to within 0.2 mag. As such, for each limiting magnitude, corresponding to a radial angular separation from the source, a mass-distance relationship was determined. We note that these mass limits are extracted under the assumption that the lens is a main-sequence star. However, pre-main-sequence or post-main-sequence stars are more luminous for a given mass; our use of a main-sequence mass–luminosity relationship is therefore conservative. Finally, each radial bin was converted into a proper-motion bin, using the respective time elapsed since closest approach, together with the distance value input into the synthetic isochrone. On this basis, our completeness in magnitude/radial separation space has been projected to mass/lens distance/relative proper-motion space. This new parameterization allows our completeness to be related to the microlensing events, the light curves of which are described by physical quantities, including lens mass, M , lens distance, D_L , and relative proper motion, μ_{rel} .

5. Light-Curve Fitting and Analysis

5.1. Fitting Routine and Results

Microlensing models were fit to the light curves described in Section 2.2 by applying the publicly available software package, *pyLIMA*, using the differential evolution fitting method (Bachelet et al. 2017). Each event was fit to a standard point-source point-lens (PSPL) model with parallax. The number of free parameters in the model depends on the number of light

curves for the different filters fitted. For any single-lens parallax event, there are initially five parameters: the time of closest approach between the source and lens (t_0); the impact parameter between the source and the lens in units of the Einstein radius (u_0), the characteristic timescale, or “Einstein crossing time” (t_E); and the North and East components of the microlensing parallax vector ($\pi_{E,N}$ and $\pi_{E,E}$). For each filter, there are two additional parameters: the assumed-to-be-static flux of the source in the absence of lensing, f_s , and the blend flux, f_b , which is the flux from companions to the lens, companions to the source, and/or ambient interloper stars falling incidentally within the seeing disk of the microlensing target (the “target” being the superimposed lens and source) during the event. The values obtained by the fits for this PSPL model for both events are presented in Table 4. Corner plots showing posteriors for all solutions are shown in Figures 12–15.

Furthermore, after each initial fit was conducted, a second fit was run, with the additional constraint that u_0 only be allowed to have values with the opposite sign to the initial u_0 results, in order to find degenerate solutions. For example, if u_0 was first found to equal -0.5 , in the second fit, u_0 was restricted to positive values.

The two flux parameters can be recast to a more intuitive pair of parameters: the unlensed baseline magnitude of the source (m_s), and the blend-source-flux-fraction (b_{sff}), the latter being the ratio of the flux from the source alone to the total flux in the aperture of the images from which the light curves were derived. The transformation is made using the following equations:

$$m_s = 27.4 - 2.5 \log_{10}(f_s) \quad (6)$$

$$b_{\text{sff}} = \frac{f_s}{f_s + f_b}. \quad (7)$$

The resulting m_s and b_{sff} values for a subset of the data (which will be used in the following section) are presented in Table 5.

The PSPL-with-parallax model effectively describes the M98-B6 light curve, fitting with a reduced chi-squared of 1.17 and 1.18 for negative and positive u_0 values, respectively. As is evident in the bottom panel of Figure 4, this event appears to be a smooth PSPL curve, with minor perturbation due to parallax. The fit for M96-B5 is slightly poorer, with a reduced chi-squared of 1.57 and 1.56. Although both models appear to fit the data well, the lack of coverage for times of peak amplification introduces some uncertainty, yielding more variation in solutions than for M98-B6, which has full peak coverage in two filters.

To potentially improve the fit for M96-B5, we attempted fitting to a point-source-binary-lens (PSBL) model, which has three additional parameters: the log of the mass ratio between the two lenses $\log q$; the log of the projected binary separation in units of the Einstein radius, $\log s$; and the position angle between the binary axis and source trajectory, α . However, given that the PSBL model did not significantly increase the quality of the fit ($\chi^2_{\nu} = 1.62$), we will only consider the PSPL results for the remainder of this work.

5.2. Constraining f_{lens}

In cases of a luminous lens or additional light sources within the aperture of the source star, the resultant microlensing light curve exhibits substantial alterations. The additional, unlensed

Table 4
Light-Curve Model Fit Parameters

Parameter	M96-B5 (A)	M96-B5 (B)	M98-B6 (A)	M98-B6 (B)
t_0 [days]	$1766.2^{+1.2}_{-1.3}$	$1773.10^{+0.88}_{-0.93}$	$2413.7^{+1.4}_{-1.5}$	$2407.4^{+1.5}_{-1.6}$
u_0 [θ_E]	$-0.0296^{+0.0049}_{-0.0052}$	$0.0164^{+0.0042}_{-0.0037}$	$-0.174^{+0.019}_{-0.022}$	$0.175^{+0.023}_{-0.023}$
t_E [days]	537^{+92}_{-68}	628^{+100}_{-74}	367^{+41}_{-37}	346^{+45}_{-35}
π_{EN}	$0.0397^{+0.0074}_{-0.0070}$	$-0.0284^{+0.0050}_{-0.0051}$	$-0.087^{+0.023}_{-0.021}$	$0.0294^{+0.023}_{-0.024}$
π_{EE}	$0.076^{+0.012}_{-0.012}$	$0.0535^{+0.0073}_{-0.0077}$	$0.076^{+0.012}_{-0.013}$	$0.0873^{+0.0066}_{-0.0076}$
f_s (MACHO-B)	1900^{+330}_{-320}	1550^{+240}_{-240}	9600^{+1400}_{-1200}	9300^{+1500}_{-1500}
f_b (MACHO-B)	9110^{+250}_{-270}	9400^{+170}_{-190}	3900^{+1100}_{-1400}	4300^{+1400}_{-1500}
f_s (MACHO-R)	4320^{+750}_{-710}	3510^{+540}_{-540}	31400^{+5500}_{-4700}	31000^{+5500}_{-5000}
f_b (MACHO-R)	21820^{+540}_{-590}	22470^{+390}_{-420}	10300^{+4500}_{-5300}	11000^{+4800}_{-5300}
f_s (CTIO)	6100^{+1100}_{-990}	5000^{+770}_{-770}	96000^{+14000}_{-12000}	93000^{+15000}_{-14000}
f_b (CTIO)	26300^{+1100}_{-1200}	27200^{+1000}_{-1000}	31000^{+11000}_{-13000}	35000^{+14000}_{-15000}
f_s (MPS)	183000^{+27000}_{-28000}	177000^{+29000}_{-28000}
f_b (MPS)	56000^{+21000}_{-25000}	63000^{+27000}_{-28000}
χ^2_ν	1.57	1.56	1.17	1.18
d.o.f.	2290	2290	2302	2302

Note. Results of fitting MACHO light curves to PSPL models. Each event has two solutions, with negative and positive u_0 , due to the degeneracy in this parameter, henceforth referred to as “Solution A” and “Solution B,” respectively. Note that the date t_0 is JD-2448623.5.

flux remains constant, while the flux of the source varies, resulting in a smaller apparent maximum magnification, as well as what appears to be a shorter t_E . This information is captured in b_{sff} , which we can rewrite as as

$$b_{\text{sff}} = \frac{f_s}{f_s + f_b} = \frac{f_s}{f_s + f_l + f_n} \quad (8)$$

where f_l is the flux from the lens, and f_n is the flux from neighboring stars. Here, b_{sff} is fit as a free parameter when modeling the photometric light curve.

To constrain f_b , we can combine b_{sff} with two relevant quantities derived from the WFPC2 images. The first quantity is the instrumental magnitude of the target from `img2xymrduv`, as described in Section 3.2. Paired with image exposure time, this magnitude is converted to a count flux, which we interpret as $f_s + f_l$ (and which we refer to as f_{targ}). As the HST images were taken only 2–3 yr after the peak of each event, we assume here that the source and lens would not have had adequate time to separate appreciably. Secondly, by summing the total flux within the $1''/2$ radius circle centered on the source, imitating the observations from the original MACHO data set, we obtain $f_s + f_l + f_n$ (or f_{aper}). We can write the relationships between these quantities as follows:

$$\left(\frac{f_s + f_l}{f_s + f_l + f_n} - \frac{f_s}{f_s + f_l + f_n} \right) (f_s + f_l + f_n) = f_l \quad (9)$$

$$f_l = \left(\frac{f_{\text{targ}}}{f_{\text{aper}}} - b_{\text{sff}} \right) f_{\text{aper}} \quad (10)$$

thereby extracting the lens flux. This quantity is then converted back into a WFPC2 instrumental magnitude, and finally calibrated into Vega magnitude. The corresponding source magnitude is derived similarly. Note that this process is only possible for the components of the light-curve data in the MACHO-Blue and MACHO-Red filters, as their passbands align reasonably well to those of the WFPC2 F555W and F675W filters (shown in the Appendix).

This analysis was conducted for all HST frames in the epoch 2000 June 11, as given in Table 3. Although data exist for M96-B5 in 1999, they are only available in the F555W filter, and were therefore excluded in favor of a slightly later epoch, for the purpose of combining the MACHO-Blue/F555W results with the MACHO-Red/F675W results in a later section. Figure 5 shows a summary of these results, where source and lens magnitudes are plotted as a function of b_{sff} from zero (no source flux) to one (no non-source flux). As shown in this figure, the result is highly sensitive to b_{sff} . The source and lens magnitudes derived from this analysis are presented in Table 5.

In the case of this work’s value of b_{sff} , both solutions for M96-B5 indicate a lens with non-zero flux. For M98-B6, we see that both solutions’ b_{sff} indicate that there is no lens flux, which we would expect in the case of a BH lens. However, the 1σ error bar on b_{sff} does extend into the region of non-zero lens flux. As such, in Table 5 we report the lens magnitudes at the lower boundary of b_{sff} regions as limits on the lens magnitude of this event.

6. Source Analysis

6.1. Astrometric Determination of Source Proper Motion

Prior to the alignment necessary to compute proper motions for the source of M96-B5, the WFPC2 starlists described in Section 3.2 were consolidated into single starlists for each epoch and filter. This was accomplished using the follow-up programs to `img2xymrduv`, `xym2mat` and `xym2bar`, which match and average combine sources in a set of starlists. By combining multiple observations for a given epoch, these collated starlists include uncertainties in centroid positions, which are ultimately necessary to establish the precision of the final proper-motion determination.

Although the source star for M96-B5 is not present in Gaia EDR3, all stars in the catalog, within a $36''$ box, centered on the source, were used as an absolute reference frame, to which all epochs of data were matched. This included both epochs of NIRC2 data, and all epochs of WFPC2 data in the F555W and F814W filters. The starlists from these data sets were matched and transformed into the coordinate system of the EDR3 starlist

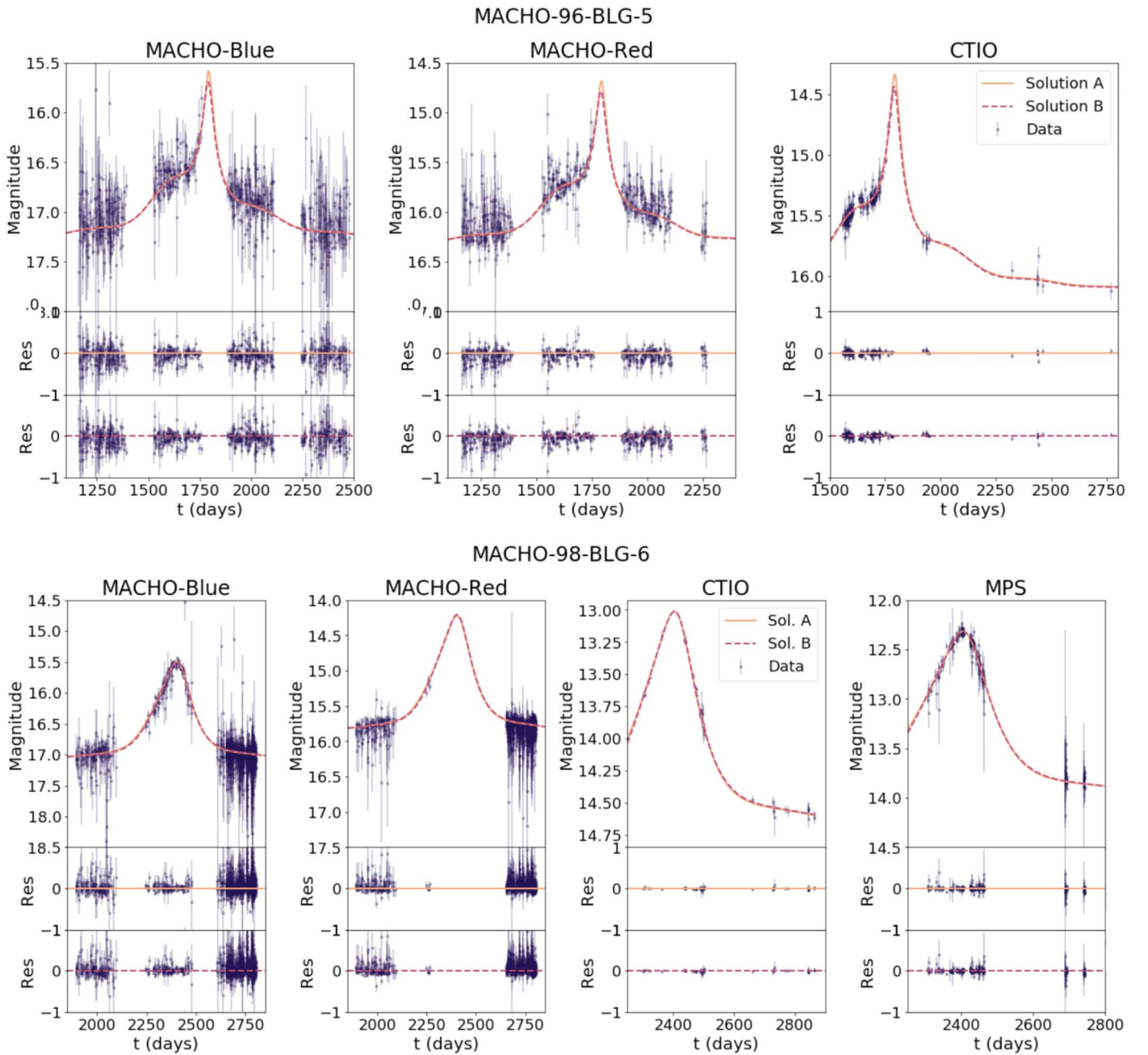


Figure 4. Fitted models of the light curves for M96-B5 (top) and M98-B6 (bottom). In each case, the light-curve data is shown in dark-purple points, the best-fit model with negative u_0 shown in solid orange, and the best-fit model with positive u_0 shown in dashed magenta. The residuals (data—model) for each light curve are shown immediately below, in matching colors and style. Note that the visualization of the data has been truncated to show only the rising/falling of the light curve, and not the baseline (or approximate baseline) measurements. The date t is reported in JD-2448623.5.

using *FlyStar*, a package that performs matching and astrometric transformations of starlists. The resulting relative positions are reported in the [Appendix](#).

Once the cross-epoch alignment was complete, the positions of the source at each epoch were fit to a linear, constant proper-motion model, yielding a proper motion of -2.955 ± 0.022 mas yr $^{-1}$ in the Eastern direction and -0.926 ± 0.022 mas yr $^{-1}$ in the Northern direction, with a reduced chi-squared of 1.38. The proper motion of this target, along with the proper motions of all Gaia EDR3 sources within a $36''$ box centered on the target, are shown in the vector-point diagrams in [Figure 6](#).

Unlike M96-B5, the source star of M98-B6 matches an object included in Gaia EDR3. The position, proper motion,

and parallax of the source in Gaia are given in [Table 2](#). We employ several checks to confirm that this object is indeed the same as our microlensing source. Firstly, we consider the ruwe (renormalized unit weight error) parameter, for which values below 1.4 suggest an unblended source with robust astrometric measurements ([Fabricius et al. 2021](#)). As this source has a ruwe parameter of 1.29, it is unlikely that these are two distinct, but spatially unresolvable stars. Moreover, the ruwe parameter justifies our use of the measured parallax in estimating the source distance (which is $6.7^{+11.9}_{-2.6}$ kpc).

To further confirm that the Gaia object is indeed the source star, and not an unrelated star at a different distance, the procedure described for determining the proper motion of

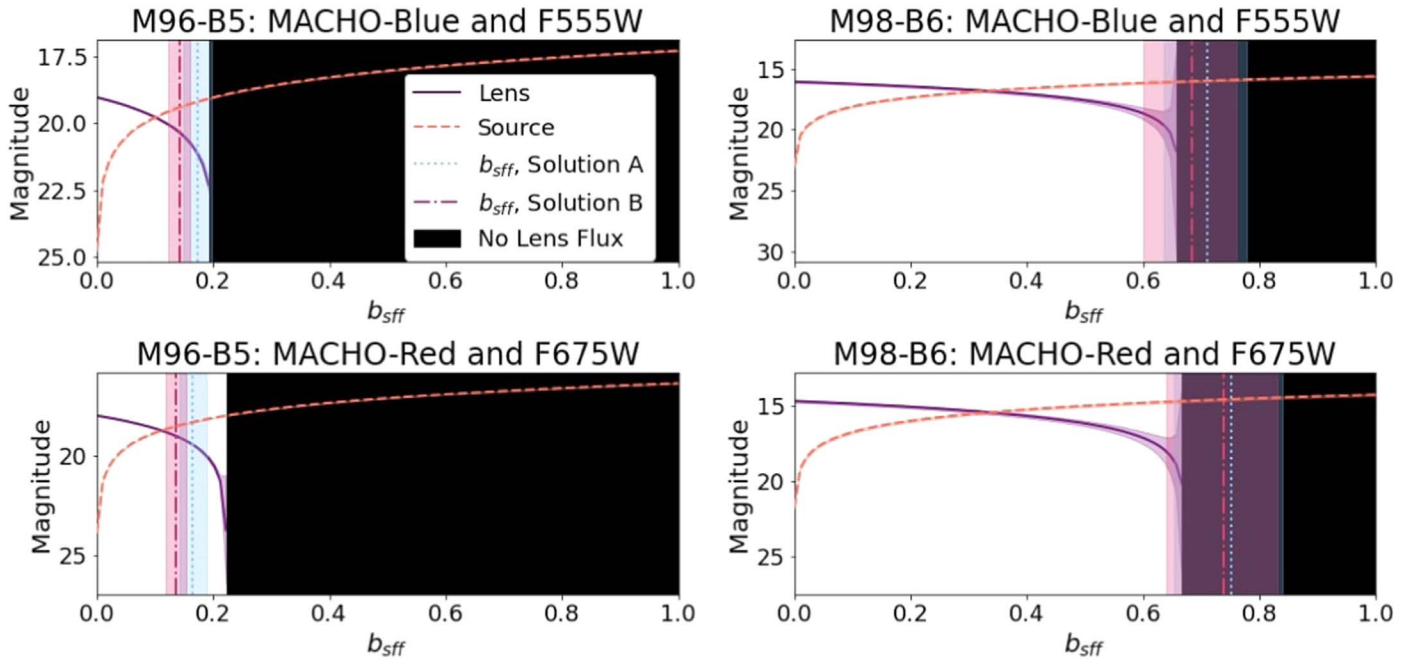


Figure 5. For each target and filter combination, the solid purple curve shows the magnitude of the lens for all possible values of b_{sff} . The dashed orange curve shows the corresponding source magnitude. The vertical lines show the values obtained for b_{sff} from Table 4, where in each case Solution A ($-u_0$) values are denoted by light-blue dotted lines, and Solution B ($+u_0$) values by magenta dotted-dashed lines. The black regions indicate the values of b_{sff} that would result in zero lens flux. The intersections between the lens curve and vertical lines are this work’s estimates of the lens magnitudes. Where the value of b_{sff} falls within a region of zero lens flux, but has an error bar extending into the region of non-zero lens flux, the intersection of the lower b_{sff} boundary and the solid purple curve are taken to be lower limits on the lens magnitude.

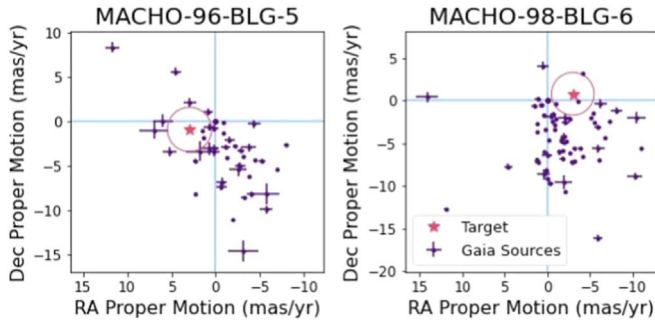


Figure 6. Vector-point diagrams for each target (magenta), each shown with all Gaia sources, within a $36''$ box centered on the respective target (purple). Proper motions are in the Gaia reference frame. A magenta circle centered on each target indicates the region of proper-motion space in which an object would have a proper motion relative to the target of 2.5 mas yr^{-1} . An object falling within this circle, and positioned within $0''.3$ of the target, would not be resolvable from the source in our 2016/2017 images.

M96-B5 above was repeated for M98-B6, in order to compare the results to the proper motion reported in Gaia. The result was a proper motion of $-2.82 \pm 0.35 \text{ mas yr}^{-1}$ in the Eastern direction and $0.47 \pm 0.36 \text{ mas yr}^{-1}$ in the Northern direction. Within uncertainties, this is consistent with the Gaia proper motions of $-2.98 \pm 0.11 \text{ mas yr}^{-1}$ East, and $0.812 \pm 0.075 \text{ mas yr}^{-1}$ North, further supporting the claim that these two sources are one and the same. The proper motion of this source in the context of its field is also shown in Figure 6.

6.2. Photometric Exploration of Source and Lens

As shown in Figure 3, our ability to directly observe a luminous lens becomes more difficult as the radial offset from the source in the image plane decreases. If the relative proper motion between source and lens is small, there may not be

sufficient angular separation between the two objects to resolve them in our NIRC2 images. To explore a scenario in which objects appear blended, even after 20 yr, we use the WFPC2 photometry from the 2000 June 11 (for M96-B5) and 2000 June 23 (for M98-B6) epochs to look for indications of additional unresolved objects in/near the source. Although this concept was initially intended for the purpose of covering cases of low relative proper motion, some back-of-the-envelope calculations show that it should actually hold, regardless of proper motion: high lens mass (BH) microlensing events will produce Einstein radii of a few milliarcseconds, which we can use in conjunction with the light-curve fit’s u_0 values (see Table 4), given in units of the Einstein radius, to show that at time of closest approach, the lens and source in both events should not have been separated by more than $\sim 1 \text{ mas}$. The times between this closest approach and the observations are no more than three years, which, along with the aperture radius of $0''.5$ used for the photometry, means that the relative lens-source proper motion would have to be $\sim 100 \text{ mas yr}^{-1}$ in order for the lens to have moved outside of the aperture. We can see that for both events, the source proper motion is only a few mas yr^{-1} , meaning that the majority of the required 100 mas yr^{-1} would have to be made up by the lens. As such, we can reasonably assume that at the time of the WFPC2 observations, the lens is still within the aperture observing the source.

We will call the hypothetically unresolved lens and source object the “target,” for which the photometric information in four filters is as given in Table 3. In the case of M96-B6, we also have disentangled photometric data for a lens and source in two filters (F555W and F675W), as presented in Table 5. For M98-B6, the disentangled photometry consists of source magnitudes and lower limits on the lens magnitude.

Table 5
Lens Magnitude Constraints

Event	Filter Combination	m_{targ}	Solution	b_{sff}	m_{source}	m_{lens}
M96-B5	MACHO-B/F555W	19.027 ± 0.027	A	$0.173^{+0.025}_{-0.024}$	$19.20^{+0.15}_{-0.16}$	$21.11^{+0.89}_{-0.93}$
			B	$0.141^{+0.019}_{-0.019}$	$19.42^{+0.15}_{-0.15}$	$20.32^{+0.33}_{-0.34}$
	MACHO-R/F675W	17.969 ± 0.015	A	$0.165^{+0.024}_{-0.023}$	$18.30^{+0.15}_{-0.16}$	$19.42^{+0.43}_{-0.45}$
			B	$0.135^{+0.018}_{-0.018}$	$18.52^{+0.15}_{-0.15}$	$18.97^{+0.22}_{-0.23}$
M98-B6	MACHO-B/F555W	16.038 ± 0.044	A	$0.710^{+0.067}_{-0.075}$	$15.96^{+0.15}_{-0.13}$	>18.45
			B	$0.683^{+0.078}_{-0.082}$	$16.00^{+0.16}_{-0.15}$	>18.16
	MACHO-R/F675W	14.677 ± 0.044	A	$0.752^{+0.087}_{-0.10}$	$14.553^{+0.17}_{-0.15}$	>18.38
			B	$0.739^{+0.091}_{-0.099}$	$14.573^{+0.17}_{-0.16}$	>18.44

Note. For a given event, light-curve solution, and filter combination, we present the results derived using the blend fraction, b_{sff} , to separate the target magnitude, m_{targ} , into the source and lens components, m_{source} and m_{lens} , respectively.

Table 6
Best Synthetic Photometry Matches

Event	Scenario	Component	$\log A_c$ (yr)	D_c (kpc)	T_* (K)	M_*/M_\odot	L_*/L_\odot	R_*/R_\odot	χ^2/pts
M96-B5	Single Target	Source	9.5	8.5	4960	1.41	10.76	4.44	0.144
	Double Target (A)	Source	9.5	8	5043	1.41	7.39	3.56	0.079
		Lens	9	2.5	4584	0.73	0.17	0.66	
	Double Target (B)	Source	9.5	10	4980	1.41	9.76	4.19	0.082
		Lens	8	2	4457	0.70	0.14	0.63	
	Single Target	Source	8.5	7.5	4572	3.19	297.30	27.46	0.057
M98-B6	Double Target (A)	Source	8	16.5	4633	5.11	1466	59.36	0.056
		Lens	10	3.5	5352	0.84	0.54	0.85	
	Double Target (B)	Source	8	16.5	4633	5.11	1466	59.36	0.045
		Lens	10	3.5	5352	0.84	0.54	0.86	
	Single Target	Source	8.5	7.5	4572	3.19	297.30	27.46	0.057
	Double Target (A)	Source	8	16.5	4633	5.11	1466	59.36	0.056

Note. Closest matches from synthetic isochrones to target photometry. For each scenario, the log age and distance to the cluster(s) in which the closest match was found is given, in addition to the effective temperature, mass, luminosity, and radius of the matching object. As a metric of fit, chi-squared per point is reported. For single-target scenarios, chi-squared is calculated with four data points, while double-target scenarios are calculated with six.

In order to identify objects capable of being represented by our photometric data, we again use SPISEA, the stellar-population-generating python package discussed in Section 4.2. SPISEA allows not only for a choice of many parameters for the populations it creates, but also for the simulation of photometry from specific instruments and filters. For the purposes of matching to our data, we simulated photometry for HST’s WFPC2 instrument in the filters F439W, F555W, F675W, and F814W.

To create a sample of stars in which to search, we generated isochrones at a range of cluster distances (1–18.5 kpc, in increments of 0.5 kpc, with the upper limit set by the maximum distance permitted by the M98-B6’s EDR3 parallax measurement) and ages (log age in years spanned 8–10, in increments of 0.5). Metallicity was held constant at solar metallicity, and default evolution and atmospheric models were chosen. A Cardelli extinction law with $R_V = 3.1$ was applied, along with extinction values pulled from the previously cited Argonaut Skymaps. This resulted in a library of 50 isochrones with 200 stars each. The code does not generate compact objects or brown dwarfs.

For each event, we explored three scenarios. In the first, we made the assumption that the WFPC2 photometric data from the 2000 epoch (see Table 3) showed only a single object, and thus looked for the closest single-object match. This was achieved by identifying the minimum chi-squared between the

photometric data and each synthetic photometry object. Although our light-curve fits for M96-B5 indicated a flux contribution from both a lens and source, Figure 5 shows how sensitive this result is to b_{sff} ; even though our result allowed for non-zero lens flux, previous works that have fit the same light curve have obtained blending parameters that, based on the analysis in Section 5.2, would yield zero lens flux. For example, the fit from Bennett et al. (2002) presented two solutions that would put b_{sff} fully in the black region of Figure 5). We note that although our fits yielded lower chi-squared than those of Bennett (2002), there is inherent ambiguity in this event, due to the lack of coverage of the peak magnification. As such, we explore this possibility alongside scenarios more fully supported by this work.

The second and third scenarios we explore for each event involve a single luminous source and single luminous lens, with magnitudes (or magnitude limits, for the lens of M98-B6) dependent on the two light-curve solutions. These disentangled lens and source magnitudes are taken from Section 5.2, in which we derived separate lens and source photometry for filters F555W and F675W. The least-squares search in this scenario operated slightly differently than in the case of a single object. For M96-B5, the matched data points were the F555W and F675W photometry of one object for the source, and one object for the lens, in addition to the F439W and F814W photometry for the summed source and lens combination (as

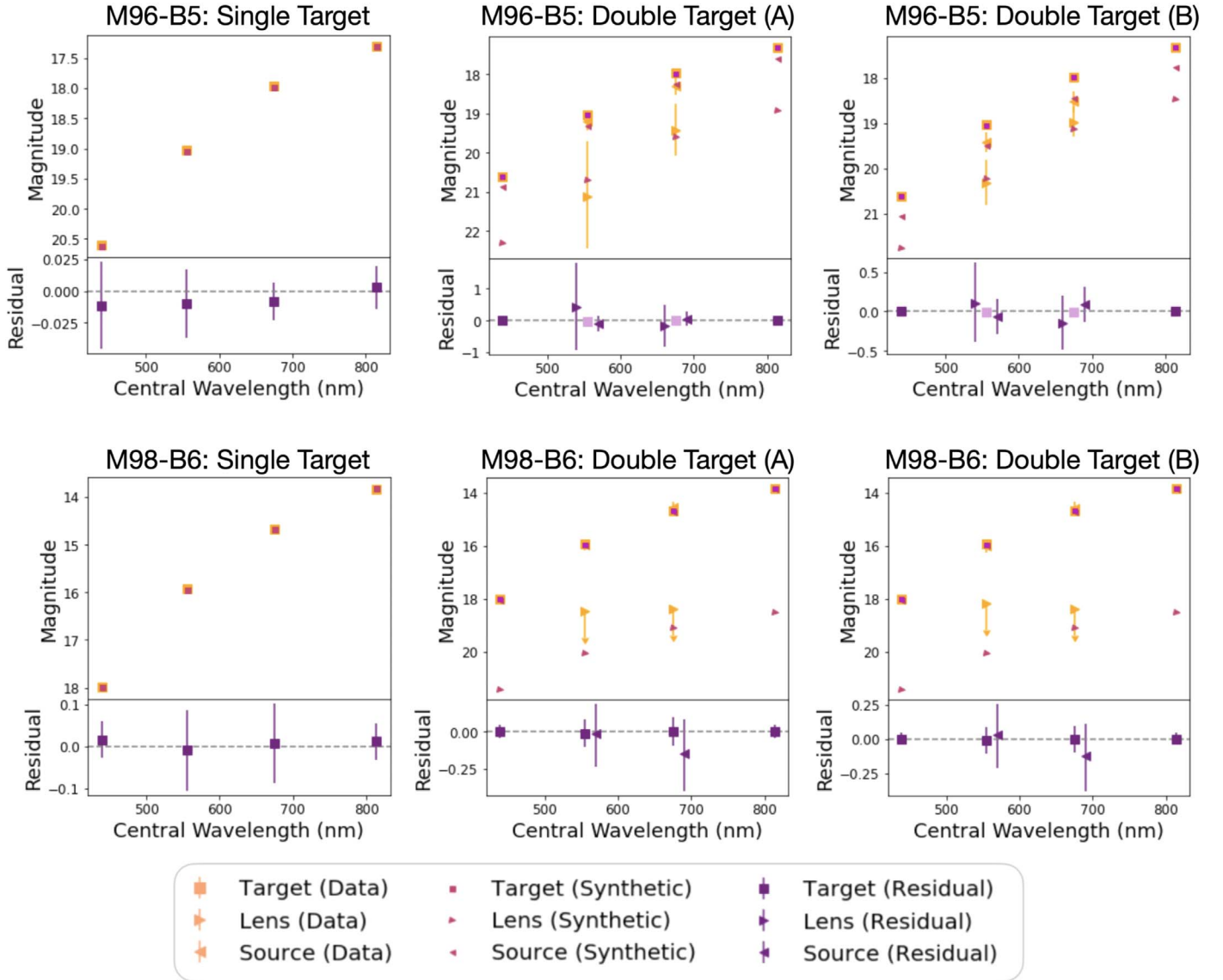


Figure 7. Comparisons of broad-band photometry of event targets with best-matched synthetic data. For each event (M96-B5 in the top row, and M98-B6 in the bottom row), three potential scenarios are considered. In the leftmost panel, the target is assumed to be only the background source (meaning that the lens is either non-luminous, or is spatially resolved from the source). In the middle and rightmost panels, the target is assumed to be an unresolved source and a luminous lens. The disentanglement of the lens and source in these cases is derived from the two solutions to each light-curve fit, with Solution A in the center, and Solution B on the right. In each figure, the total target data is represented by orange squares, and where a separate lens and source are shown, they are represented by orange triangles directed to the right and left, respectively. The synthetic data matches are symbolically represented in the same way, but in magenta, and with smaller markers. In the residual panels at the bottom of each plot, if lens and source points are present, they are slightly offset from their central wavelength in order to improve figure visibility. In addition, only the dark-purple points were used to calculate χ^2 , as the light-purple points represent information that is redundant, but useful for visualization purposes.

there was insufficient data to separate the lens and source contribution in these two filters). Owing to the fact that M98-B6 has lens magnitude limits, rather than specific values, the search was conducted by first finding all objects that fell above the lens limits, then summing each of these with any objects at a greater distance. For each of these combinations, chi-squared was calculated with the two source points (still F555W and F675W), and all four of the combined target points, instead of any lens points. In either case, all six points used were weighted equally in the search.

For each of the four scenarios above, a closest-matched source (or sources and lens) was identified. The physical parameters of the matched sources, as well as a chi-squared per point, are presented in Table 6. Comparisons of the data to the

synthetic photometry for each scenario are illustrated in Figure 7). The isochrones from which each match object was pulled are illustrated in the Appendix.

7. Results

To encapsulate the results of the three analysis sections of this paper (4–6), we will begin by looking at Figure 8, which summarizes the findings of Sections 4 and 5.1, and illustrates the need for Sections 5.2 and 6.

For each event, the colorbar indicates the maximum mass of a stellar lens that may have been undetected by our process of artificial star planting and retrieval in the NIRC2 images, as described in Section 4. This mass limit is presented as a

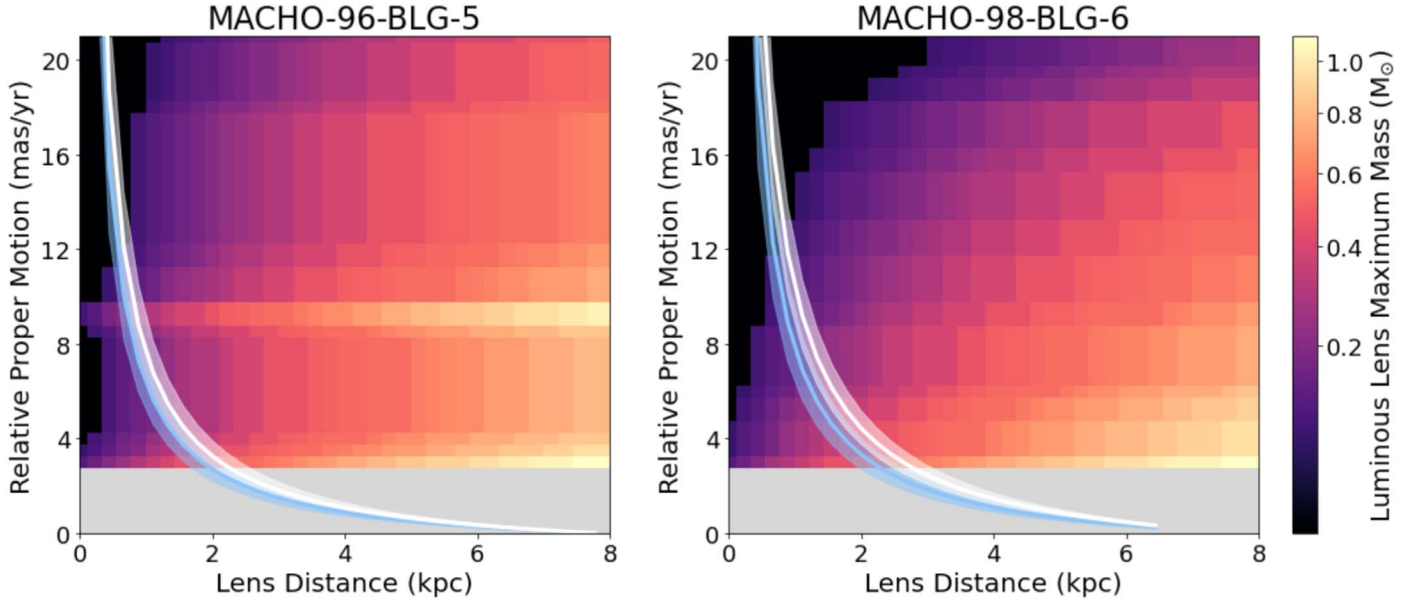


Figure 8. For each event, the colorbar indicates the maximum mass of a stellar lens that may have been undetectable via our process of artificial star planting and retrieval in the NIRC2 images, described in Section 4 as a function of lens distance and relative proper motion, with the black area indicating a parameter space in which no stellar matches were found. The lens distance/relative proper-motion relationship derived from each solution of the light-curve fit is given in cyan and white lines, with the transparent surrounding regions denoting plus- or minus-one sigma to that relationship; Solution A is shown in cyan, and Solution B in white. The gray region represents the possibility of relative proper motions sufficiently low ($<2.5 \text{ mas yr}^{-1}$) that the lens and source are not resolvable. The only stellar lenses allowed by our model fits, and not identified in our NIRC2 images, must be below the masses indicated by the colorbar within the cyan and white bands.

function of lens distance and relative lens-source proper motion, two microlensing parameters that cannot be constrained by a light curve alone. The black area indicates parameter space in which no stellar matches were found. Note that, despite being cast into parameters that are meaningful for microlensing events, the completeness data itself is derived solely from our 2016/17 images of the sources, rather than the microlensing events.

The photometric microlensing light-curve data is incorporated in the cyan and white curves (for Solutions A and B, respectively), which indicate combinations of lens distance and relative lens-source proper motions allowed by the fits in Section 5.1. The surrounding shaded cyan and white regions designate plus- or minus-one sigma to those relationships. The curves assume a source distance of 8.5 kpc for M96-B5, and 7.5 kpc for M98-B6 (each chosen based on the best-matched synthetic object to a single source target, as reported in Table 6). The only stellar lenses allowed by our model fits and not identified in our NIRC2 images must be below the masses indicated by colors within these shaded cyan and white bands.

Combining these two pieces of analysis from two different data sets, we find that the maximum possible mass of a stellar lens in each event is $0.53 M_{\odot}$ and $0.55 M_{\odot}$ for Solutions A and B of M96-B5, and $0.55 M_{\odot}$ and $0.61 M_{\odot}$ for M98-B6, respectively. We note that these mass limits are derived from simulating main-sequence stars, which are less luminous for a given mass than pre-main-sequence or post-main-sequence stars (meaning that these types of stars would all be detectable as well). However, we also note that this does not account for other luminous objects, such as brown dwarfs, or non-BH compact objects.

These masses, however, have little to do with the lens masses allowed by the light-curve data. By combining Equations (1)–(3), we can derive a microlensing event’s lens mass as a function of the fit parameters t_E and π_E , and the

relative proper motion, μ_{rel} :

$$M = \frac{t_E \mu_{\text{rel}}}{\kappa \pi_E} \quad (11)$$

where $\kappa = \frac{4G}{1 \text{ au } c^2}$. Furthermore, by assuming a source distance as described above, we can recast this relationship as lens mass as a function of lens distance, using Equations (2)–(3):

$$M = \frac{1 \text{ au} (d_L^{-1} - d_S^{-1})}{\kappa \pi_E^2}. \quad (12)$$

Both relationships for each event and solution are illustrated in Figure 9, in which, similarly to Figure 8, each panel has a gray region representing relative proper motions too low (or corresponding lens distances too high) to resolve a lens and source ($<2.5 \text{ mas yr}^{-1}$). For the purpose of comparison with Figure 8, each panel of Figure 9 also includes a purple region along the bottom, shading all masses below $1.2 M_{\odot}$, i.e., the highest possible undetectable stellar mass, based on our NIRC2 image completeness. In all cases outside the gray regions, the range of lens masses allowed by the light-curve fit is well above the range of stellar masses undetectable in our images, eliminating the possibility of a stellar lens in this parameter space. At the boundary of this region, we find that the lens masses indicated by a relative proper motion of 2.5 mas yr^{-1} are $5.30^{+1.14}_{-0.96} M_{\odot}$ and $8.72^{+1.70}_{-1.46} M_{\odot}$ for solutions A and B of M96-B5, and $2.67^{+0.53}_{-0.49} M_{\odot}$ and $3.17^{+0.52}_{-0.48} M_{\odot}$ for solutions A and B of M98-B6. As all of these are above even a conservative upper limit of a neutron-star mass of $2.16 M_{\odot}$ (Rezzolla et al. 2018), this eliminates the possibility of non-BH compact objects, such as neutron stars and white dwarfs, as well as low-mass, luminous objects such as brown dwarfs, or free-floating planets.

The only remaining exception is the possibility of relative proper motions that are sufficiently low that the lens and source would not have had adequate time to separate appreciably, in

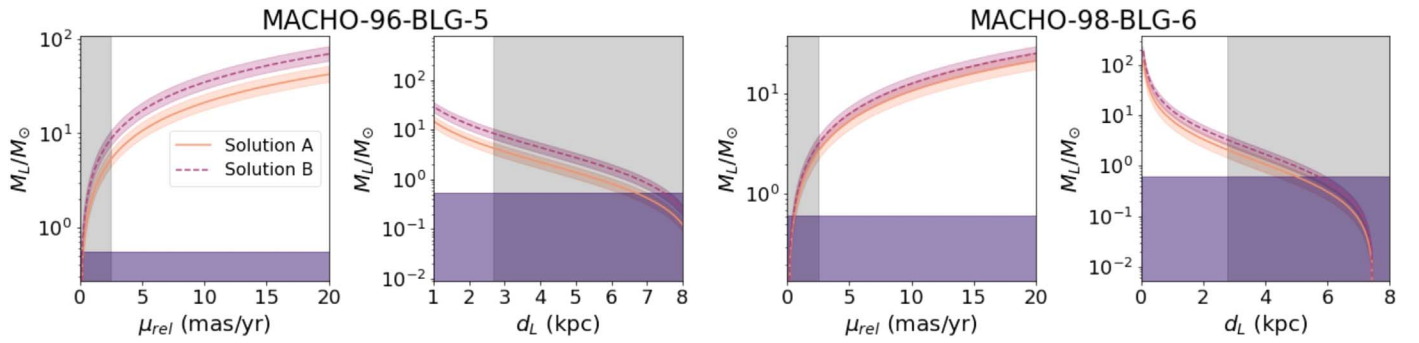


Figure 9. Possible lens masses as a function relative to lens-source proper motion (first and third panels from the left) and as a function of lens distance (second and fourth panels from the left) for both events. In each case, the solid-orange and dashed-magenta lines represent the x -axis variables’ relationship to lens mass, as determined by Solutions A and B of the light-curve fit results, respectively, with shading designating plus or minus 1σ to that relationship. The purple regions identify all possible lens masses at which a stellar lens would have been undetectable using our star finder. The gray region represents the range of sufficiently low relative proper motions and corresponding lens distance limits, that the lens and source are not resolvable. In the regions in which we are able to resolve both lens and source, undetectable masses fall below the masses permitted by the light curves in every case. Note that the curves assume a source distance; in each case, the source distance assumed is that of the best-fit photometric match to a single target, as given in Table 6.

which case a potentially luminous lens would not be detectable in our NIRC2 images, regardless of mass. This possibility is represented by the gray regions at the bottom of each panel in Figure 8, and along the sides of each panel in Figure 9. To address this blind spot, Sections 5.2 and 6 have defined and explored possible scenarios involving photometric and astrometric analysis of WFPC2 images shortly following the events in 2000, the results of which are given in Table 6. We discuss the implications and limitations of these results in the following section.

8. Discussion

8.1. Implications of Light-curve Fit Results

Based on an examination of the light-curve fit parameters alone (in Table 4), we obtain some clues as to the nature of the lens. We first note the exceptionally long t_E , particularly in the case of M96-B5. Given that t_E scales with the square root of the lens mass, these long timescales (as opposed to the days-long events caused by planets, or months-long events caused by stars and lower-mass compact objects) suggest very high masses. Indeed, it would be difficult for lens stars below $\sim 0.6 M_\odot$ (the masses defined as “allowed” in the previous section) to result in microlensing events with timescales of hundreds of days.

If we pair our events’ t_E values with another output of our fits, i.e., π_E (the “microlensing parallax,” defined in Equation (3)), we can place them in the context of the simulations constructed by Lam et al. (2020), which emulate the results of microlensing surveys, while examining the distribution of lens and source objects. One figure from this work, (replicated here as Figure 10), shows the distribution of star, white dwarf, neutron star, and black hole lenses as a function of t_E and π_E . Magenta and purple boxes have been added to the figure to show where our events (M96-B5 and M98-B6, respectively) fall in this distribution. This work reports that when searching for BH lenses in microlensing events, the BH detection rate will be 85% for events with $t_E > 120$ days, and $\pi_E < 0.08$. Solution B for M96-B5 meets this criteria fully, while solution B for M96-B5, and both solutions of M98-B6 meet the t_E cutoff, but have π_E values of up to 0.11.

In the context of the results of Lam et al. (2020), the values of π_E and t_E for both events suggest a similarity to microlensing

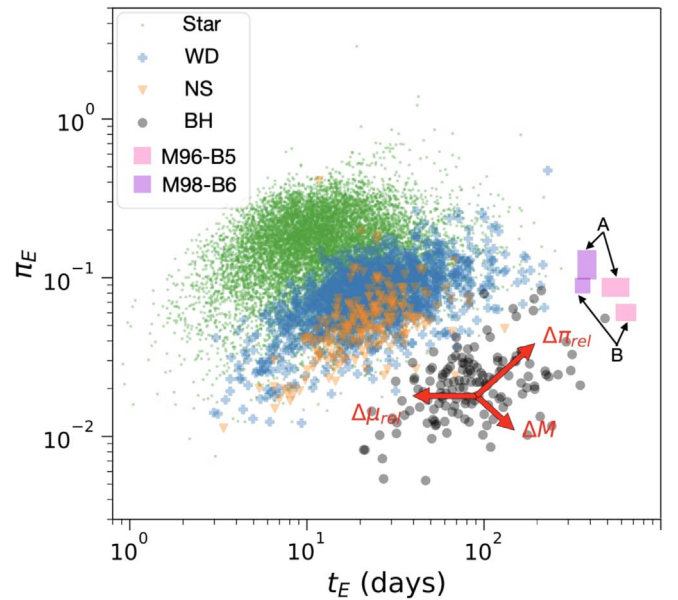


Figure 10. The main panel of Figure 13, taken from Lam et al. (2020), showing the distributions of t_E and π_E by lens type for a simulated microlensing survey. The one-sigma ranges of these parameters from the results of this work’s light-curve fits are shown in magenta and purple boxes, respectively denoting M96-B5 and M98-B6. The two different solutions for each event are marked with “A” and “B” arrows in black.

events simulated with the lenses of compact objects, although a stellar lens is not impossible. However, considering that the detection limits for this event indicate that a stellar lens would only be possible with a relatively low ($\lesssim 0.6 M_\odot$) mass, the fact that the event falls much closer to the high-mass (lower right) corner of the distribution than to the low-mass (top right) corner of the distribution suggests that the lens is not a low-mass main-sequence star. Even though this is not an explicit elimination of a luminous, low-mass lens in either case, it strongly suggests that the low-mass stars left as potential lenses in our analysis are not likely lens candidates.

The possibility of low-mass luminous sources is further diminished by the results shown in Figure 9. For all relative lens-source proper motions above 2.5 mas yr^{-1} , the lens masses allowed by the light-curve fit at any given proper motion or lens distance are well above the range of stellar masses

undetectable in our NIRC2 images, effectively ruling out all stellar lenses in this region of parameter space. Furthermore, we rule out any lens object in this parameter space with a mass below $5.30^{+1.14}_{-0.96} M_{\odot}$ and $2.67^{+0.53}_{-0.49} M_{\odot}$ for M96-B5 and M98-B6, respectively, eliminating the possibility of a low-mass, non-stellar lens, including neutron stars, white dwarfs, brown dwarfs, and free-floating planets. In effect, there is no possibility of a non-BH lens in either event, for relative proper motions above 2.5 mas yr^{-1} . We can reverse this calculation to limit the proper motions even further by recognizing that no luminous lens above $2.16 M_{\odot}$ is possible (as the results in Table 6 show that an the maximum possible masses for a stellar lens do not exceed $1 M_{\odot}$, and all non-stellar objects besides BHs would fall below that limit). Calculating the maximum proper motion allowed at this mass limit via Equation (11), we find that, using the more conservative result for each event, non-BH lenses are only possible at relative proper motions below 1.32 mas yr^{-1} and 2.48 mas yr^{-1} for M96-B5 and M98-B6, respectively. The remainder of this discussion evaluates the likelihood of a BH lens in the parameter space below these proper-motion limits, in which the lens and source would be unresolved in our images.

8.2. Blend Flux Variability in Lens Flux Analysis

Light-curve modeling of M98-B6 shows no indication of a luminous lens at all proper motions (although the 1σ error bar extends slightly into the parameter space of non-zero lens flux). This is not the case for M96-B5, which, for both solutions, appears to have a non-zero amount of lens flux in our results. We note, however, that the result of this analysis is highly sensitive to the value of b_{sff} (which is calculated from the fit parameters f_s and f_b). In using this parameter as the basis of our analysis, we must consider the potential for degeneracies between this parameter, t_E , and u_0 . An event with long t_E , but with low values for u_0 and b_{sff} will be degenerate, with a short t_E event having higher u_0 and b_{sff} .

We can look at previous fits in the literature to see this degeneracy manifest, such as the results for fitting the M96-B5 light curve to a PSPL model with parallax given in Bennett et al. (2002). This work reported three solutions for this event, one of which is similar to our best-fit solution (long t_E , small u_0 and b_{sff}), while the other two illustrate the opposite result (relatively short t_E , with larger values of u_0 and b_{sff}). The values yielded in the latter two solutions for b_{sff} were 0.3 and 0.33 in MACHO-Blue, and 0.28 and 0.31 in MACHO-Red. If applied to the lens flux analysis here, these results would put the lens for M96-B5 squarely in the region of no lens flux, which, paired with the long t_E and small π_E in the context of the results of Lam et al. (2020) cited above, strongly suggest a BH lens. To address this limitation of fitting (as noted previously, the lack of coverage of the peak magnification of this event introduces an inherent ambiguity), we explored a non-luminous lens scenario, in addition to the two luminous lens scenarios for this target, in Section 6.2, which will be further discussed below.

Similarly, by looking at the result obtained for a PSPL-with-parallax fit of M98-B6 in Poindexter et al. (2005), we find three physical solutions for this event (excluding the fourth solution, which has a negative, non-physical blending parameter). All three yielded lower t_E values than our reported ~ 350 days, but with b_{sff} values larger than ours (0.76, 0.85, and 1). This only

serves to support our Section 5.2 result that for this event, there is no measurable contribution of flux from a lens.

8.3. Interpreting Closest Matches in Target Photometry

Due to the degeneracy involving b_{sff} and its impact on our results, we took a conservative approach in using the analysis of Section 5.2 to inform the photometric examination of the source in Section 6.2, and considered both non-luminous and luminous lens scenarios for both events. Note that “target” here refers to the unresolved object, which contains at least light from the source star, and at most light from the source star and an unidentified lens object.

For M96-B5, the scenario in which we consider the target as a single source (the scenario suggested by the Bennett (2002) solution’s high b_{sff} values), we find the best-match $1.41 M_{\odot}$ G9 sub-giant at 8.5 kpc. This distance corresponds to a star in the galaxy’s bulge, which is typically assumed for microlensing events observed in that direction. The two scenarios with a source and a luminous lens have similar objects matched to the source (both $1.41 M_{\odot}$ G9 sub-dwarfs, at 8 kpc and 10 kpc for solutions A and B, respectively), with low-mass main-sequence stars matched to the lens (a K2 at 2.5 kpc, and a K3 at 2 kpc, both with masses $\sim 0.7 M_{\odot}$). Although the quality of the match for the lens+source scenarios appears to be better than that for the single source scenario (chi-squared values of 0.079 and 0.082 for the double objects, versus 0.144 for the single object), if considered in the context of Equation (12), the combinations of lens distance, source distance, and lens mass of either of the double object matches is not allowed by the corresponding light-curve fit. As such, we find no combined source and luminous lens photometric matches that are consistent with all of our data for this event.

The same can be said about our results for M98-B6 (for which our analysis in Section 5.2 had already pointed to zero lens flux, with a small possibility of a luminous lens). Although in all three scenarios, the matched source yields an object with temperature and distance consistent with the EDR3 effective temperature and parallax measurements, all lenses within our magnitude limits yielded masses too low to be allowed, based on the corresponding source and lens distances. Furthermore, the single source is well described, and is consistent with the classification of a previous work (Soto et al. 2007) which used optical spectral fitting to classify this source as a G5 sub-giant.

8.4. Remaining Possibilities and Future Observations

In discussing what remains, we first examine the limitations of synthetic photometry matching. As discussed above, the potential matches are pulled from synthetic isochrones, which include main-sequence and post-main-sequence stars. This does not account for the possibility of non-stellar lenses, including neutron stars, white dwarfs, and brown dwarfs. Furthermore, objects such as these may have been missed by our lens flux analysis, as this was limited by observations in purely optical wavelengths.

For M96-B5, this parameter space is narrowed down by several X-ray observations of the event, which found the X-ray emission to be consistent with a BH lens (Maeda et al. 2005; Nucita et al. 2006). This leaves white dwarfs, brown dwarfs, and free-floating planets as possible remaining lenses for this event. Based on Equation (11), a white dwarf lens at the Chandrasekar limit of $1.4 M_{\odot}$ would necessitate a relative

proper motion of $0.66^{+0.15}_{-0.12}$ mas yr⁻¹ for solution A, and $0.40^{+0.08}_{-0.07}$ mas yr⁻¹ for solution B. Without X-ray observations, our upper limit on relative proper motion is set by a conservative maximum neutron-star mass of $2.16 M_{\odot}$ (Rezzolla et al. 2018), which yields relative proper motions of $2.02^{+0.46}_{-0.34}$ mas yr⁻¹, and $1.71^{+0.31}_{-0.24}$ mas yr⁻¹. By taking the upper limit of the more conservative solution for each event, we conclude that only a BH lens is possible for relative proper motions above 0.81 mas yr⁻¹ for M96-B5, and 2.48 mas yr⁻¹ for M98-B6.

The results presented here indicate that both M96-B5 and M98-B6 remain extremely good candidates for BH lenses; even though we cannot make a solid confirmation, multiple methods of examination have yielded no compelling alternatives for either event. There remain, however, additional observations and analyses that could potentially illuminate the true nature of the lenses. Primarily, we are concerned with eliminating the possibility of non-BH compact-object or brown-dwarf lenses, unresolved from their source stars. This could be achieved via spectroscopic examination of the source, and searching for a second object in its spectrum, similarly to this work’s analysis of broad-band photometry. The wavelength of observation would depend on the potential lens: near-IR for brown dwarfs, optical or UV for white dwarfs, and UV or X-ray for neutron stars. Measurement of the source spectrum would yield a secondary benefit for M96-B5: an estimation of the source distance from spectral typing (and perhaps a better-constrained distance than that from the Gaia parallax for M98-B6). This would allow for better constraints on our results, which use source distances based on photometric fitting. These straightforward observations would conclusively determine whether anything remains in the narrow region of parameter space in which a BH is not the only possibility.

9. Conclusions

By means of an analysis of high-resolution images and light-curve data, we have eliminated the possibility of a non-BH lens for relative lens-source proper motions above 0.81 mas yr⁻¹ for M96-B5, and 2.48 mas yr⁻¹ for M98-B6. To address the potential for an unresolved, luminous lens, our comparison of source images to synthetic photometry indicates that for both events, a single stellar source is a better fit than a source blended with a stellar lens, eliminating the possibility of a stellar lens at any proper motion. We have discussed the unlikely, but physically possible scenario of brown dwarf or non-BH compact-object lenses with extremely low relative proper motion, and described how this remaining possibility may be constrained by future observations and analyzed with the methods developed in this work.

The majority of this work was completed at U.C. Berkeley, which sits on the territory of xučyun, the ancestral and unceded

land of the Chochenyo speaking Ohlone people, the successors of the historic and sovereign Verona Band of Alameda County. We acknowledge that we have benefited and continue to benefit from the use and occupation of this land. In this acknowledgment, we recognize the importance of taking actions to support the repatriation of indigenous land, and pledge to take and continue action in support of American Indian and Indigenous peoples.

The data presented herein were obtained at the W. M. Keck Observatory, which is operated as a scientific partnership among the California Institute of Technology, the University of California and the National Aeronautics and Space Administration. The Observatory was made possible by the generous financial support of the W. M. Keck Foundation.

The authors wish to recognize and acknowledge the very significant cultural role and reverence that the summit of Maunakea has always had within the indigenous Hawaiian community. We are most fortunate to have had the opportunity to conduct observations from this mountain.

This work has made use of data from the European Space Agency (ESA) mission, Gaia (<https://www.cosmos.esa.int/gaia>), processed by the Gaia Data Processing and Analysis Consortium (<https://www.cosmos.esa.int/web/gaia/dpac/consortium>). Funding for the DPAC has been provided by national institutions, particularly those institutions participating in the Gaia Multilateral Agreement.

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Appendix

This appendix contains supplementary Figures 11–16 and Tables 7 and 8.

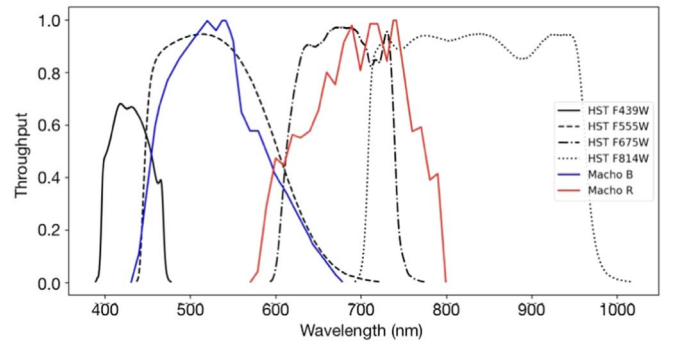


Figure 11. Transmission curves for the two light-curve filters (MACHO-Blue and MACHO-Red) compared to the WFPC2 filters used in the analysis of f_l . We compare MACHO-Blue to F555W, and MACHO-Red to F675W.

M96-B5 Light Curve: MCMC Solution A ($-u_0$)

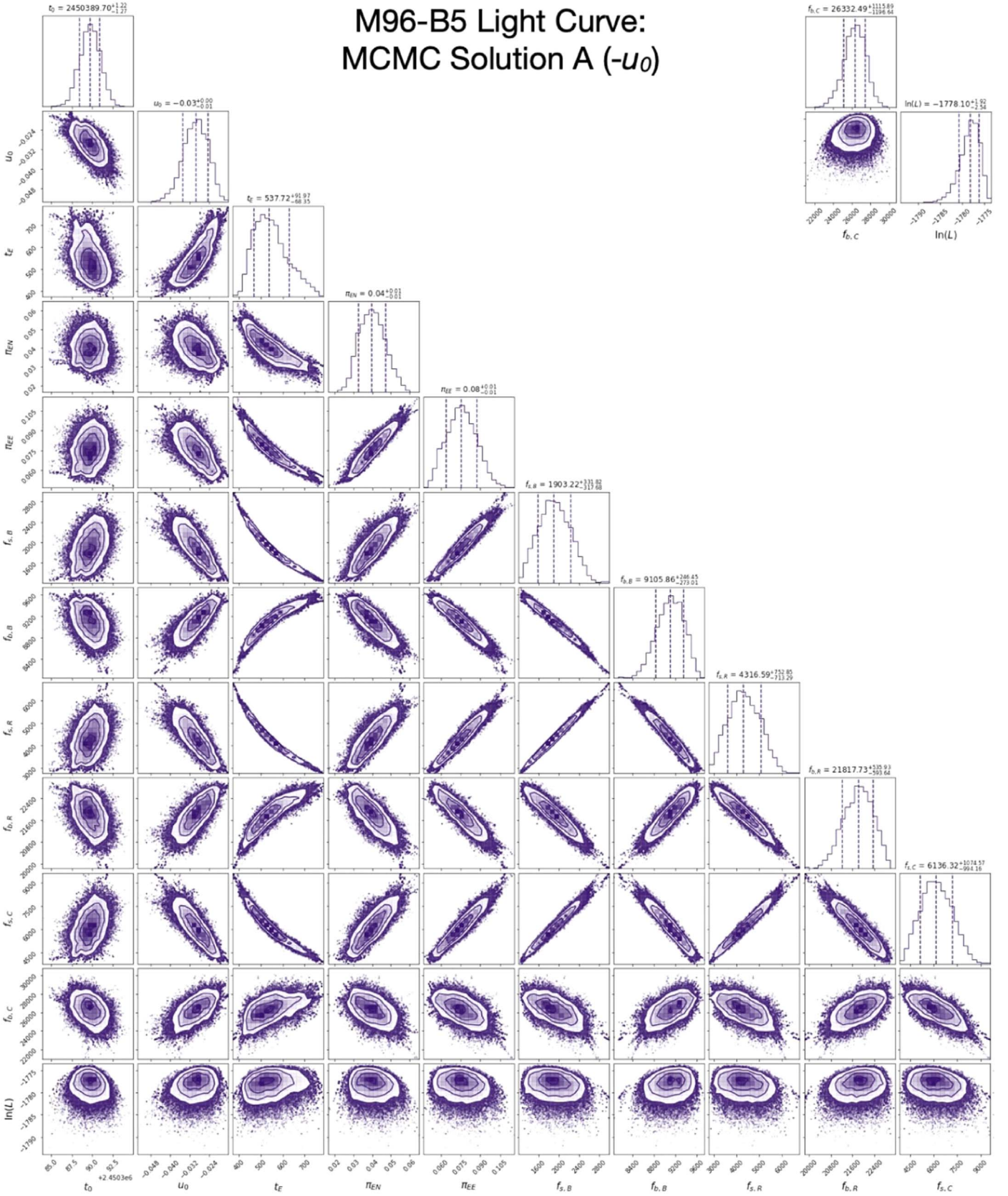


Figure 12. Posterior distributions from one of two MCMC solutions for the light curve of M96-B5, here with negative u_0 . In addition to the 11 parameters defined for Table 4, there is an additional row showing the log-likelihood $\ln L$, defined here as $-0.5 \chi^2$. Note that the two rightmost columns have been repositioned to fit the figure space.

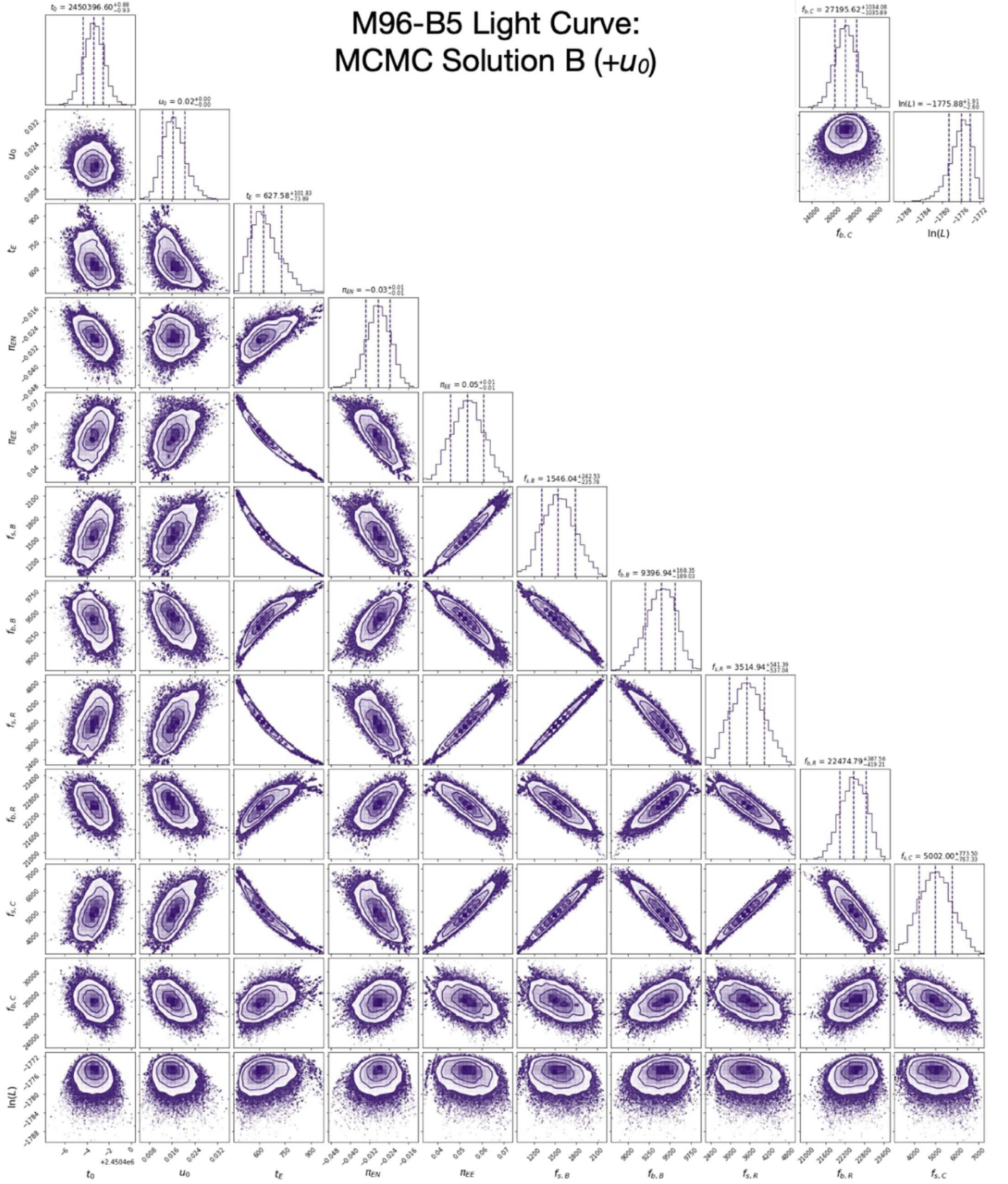


Figure 13. Posterior distributions from one of two MCMC solutions for the light curve of M96-B5, here with positive u_0 . In addition to the 11 parameters defined for Table 4, there is an additional row showing the log-likelihood $\ln L$, defined here as $-0.5 \chi^2$. Note that the two rightmost columns have been repositioned to fit the figure space.

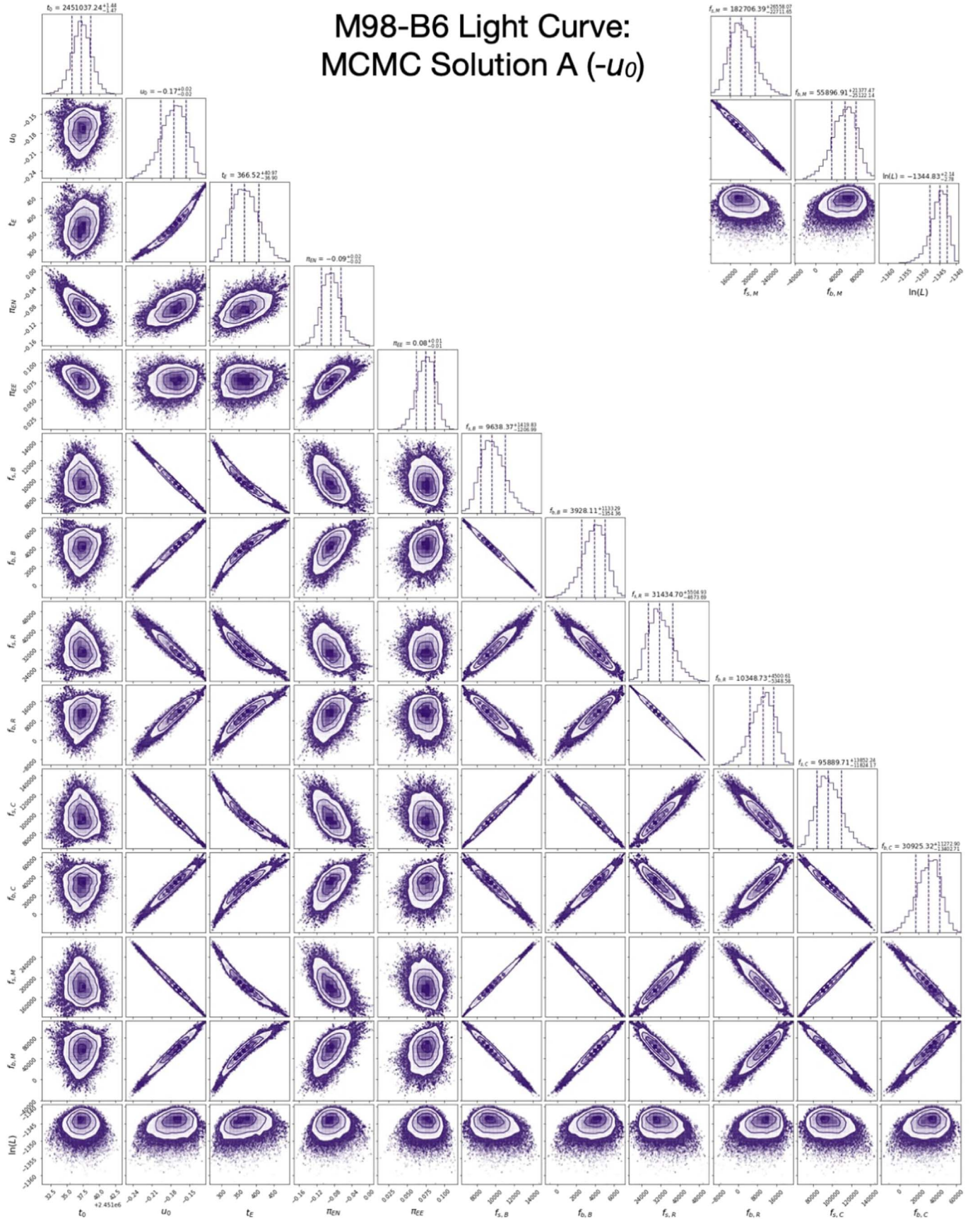


Figure 14. Posterior distributions from one of two MCMC solutions for the light curve of M98-B6, here with negative u_0 . In addition to the 13 parameters defined for Table 4, there is an additional row showing the log-likelihood $\ln L$, defined here as $-0.5 \chi^2$. Note that the three rightmost columns have been repositioned to fit the figure space.

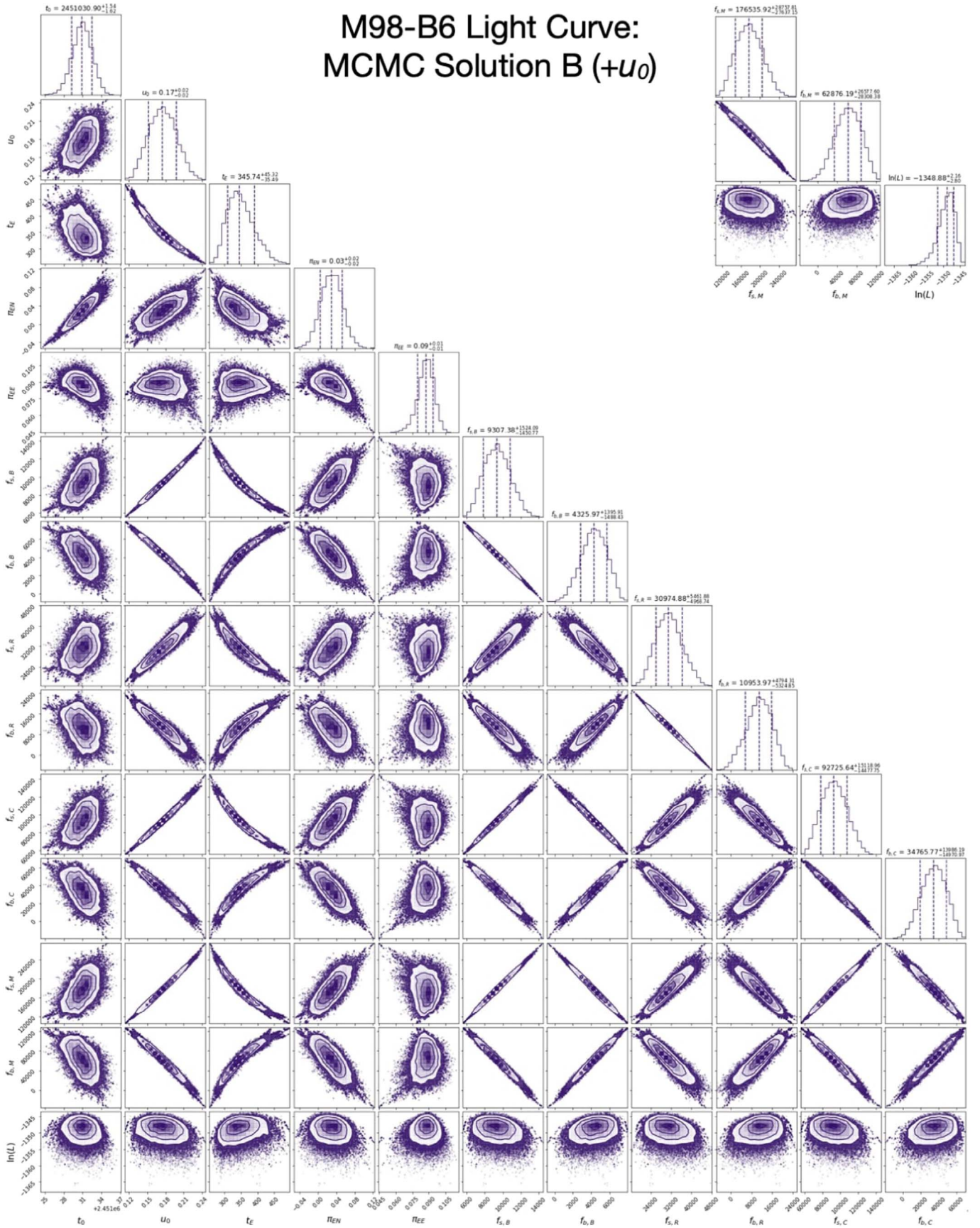


Figure 15. Posterior distributions from one of two MCMC solutions for the light curve of M98-B6, here with positive u_0 . In addition to the 13 parameters defined for Table 4, there is an additional row showing the log-likelihood $\ln L$, defined here as $-0.5 \chi^2$. Note that the three rightmost columns have been repositioned to fit the figure space.

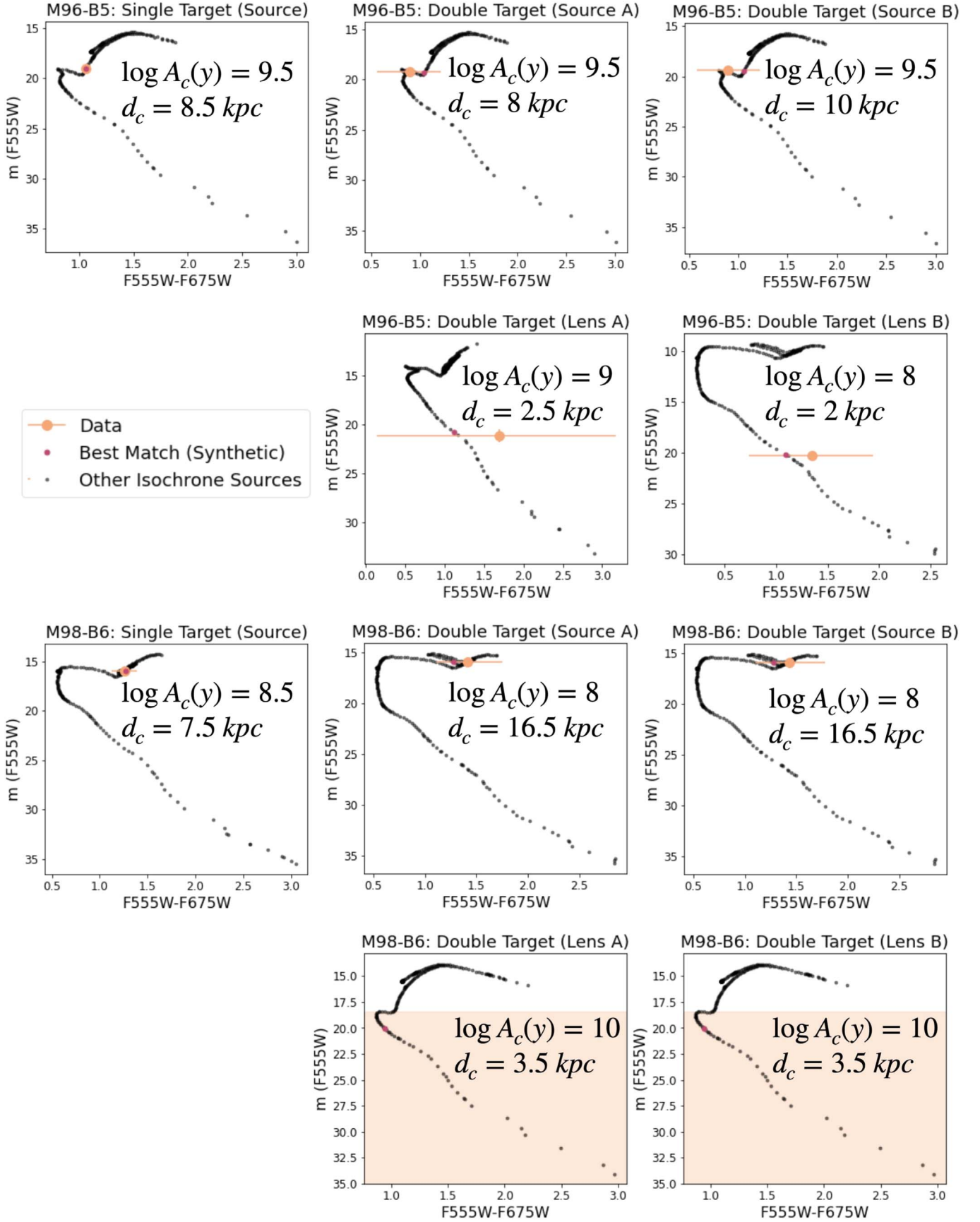


Figure 16. For each of the matched synthetic objects in Table 6, the isochrone from which that object was pulled is illustrated in a single panel here, with the matched source shown in magenta, and all other sources in black. The corresponding observed data point is shown on each panel in orange, with errorbars. For the two instances where we have a limit only on the object magnitude (both lenses for M98-B6), the range allowed by the data is shaded in orange. For each match, the log of the cluster age in years, and the cluster distance in kpc, is reported.

Table 7
M96-B5 Astrometric Measurements

Epoch	Instrument	Filter	R.A. Offset (mas)	Decl. Offset (mas)
1999.452	WFPC2	F555W	53.1 ± 2.3	14.8 ± 0.9
1999.452	WFPC2	F814W	53.1 ± 2.0	16.3 ± 1.2
2000.444	WFPC2	F555W	49.3 ± 1.4	15.5 ± 2.3
2001.419	WFPC2	F555W	46.3 ± 1.4	16.4 ± 4.0
2001.419	WFPC2	F814W	47.5 ± 0.5	14.5 ± 0.3
2001.747	WFPC2	F555W	45.4 ± 3.9	13.8 ± 3.4
2001.750	WFPC2	F814W	47.5 ± 0.9	14.0 ± 0.9
2002.394	WFPC2	F555W	43.2 ± 2.8	16.9 ± 3.1
2002.394	WFPC2	F814W	43.5 ± 1.9	15.7 ± 1.3
2002.750	WFPC2	F555W	43.1 ± 1.8	11.8 ± 1.8
2002.750	WFPC2	F814W	43.2 ± 1.0	13.2 ± 1.0
2003.400	WFPC2	F555W	39.9 ± 1.1	15.6 ± 1.3
2003.400	WFPC2	F814W	40.3 ± 0.6	14.6 ± 0.7
2016.535	NIRC2	<i>Kp</i>	2.07 ± 0.10	0.49 ± 0.20
2017.387	NIRC2	<i>Kp</i>	0.00 ± 0.13	0.00 ± 0.21

Note. Position of M96-B5 from 1999 to 2017. R.A. and decl. offset are measured in miliarcseconds, where the final epoch is placed at 0.0.

Table 8
M98-B6 Astrometry

Epoch	Instrument	Filter	R.A. Offset (mas)	Decl. Offset (mas)
2000.476	WFPC2	F555W	49.3 ± 2.3	2.5 ± 6.1
2000.476	WFPC2	F675W	36.4 ± 4.1	-5.9 ± 2.0
2000.476	WFPC2	F814W	41.7 ± 1.6	-5.2 ± 2.5
2015.500	Gaia	<i>G</i>	0.0 ± 0.1	0.0 ± 0.1
2016.535	NIRC2	<i>Kp</i>	-1.9 ± 0.5	1.6 ± 0.6
2017.436	NIRC2	<i>Kp</i>	-4.7 ± 0.5	3.1 ± 0.8

Note. Position of M98-B6 from 2000 to 2017. R.A. and decl. offset are measured in miliarcseconds, where the Gaia epoch (2015.5) is placed at 0.0.

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