# LONG TIME ASYMPTOTICS OF HEAT KERNELS AND BROWNIAN WINDING NUMBERS ON MANIFOLDS WITH BOUNDARY 

XI GENG ${ }^{1}$ AND GAUTAM IYER ${ }^{2}$


#### Abstract

Let $M$ be a compact Riemannian manifold with smooth boundary. We obtain the exact long time asymptotic behaviour of heat kernels on abelian covering spaces of $M$ with mixed Dirichlet and Neumann boundary conditions. As an application, we study the long time behaviour of the winding number of reflected Brownian motion in $M$. In particular, we establish a Gaussian type central limit theorem showing that when rescaled appropriately, the fluctuation of the winding number is normally distributed with an explicit covariance matrix.


## 1. Introduction.

The long time behaviour of the Brownian winding number is a classical topic and has been extensively studied by many authors. In his seminal work in as early as 1958, Spitzer [Spi58] proved that the total winding angle of a planar Brownian motion around the origin up to time $t$, denoted as $\theta(t)$, satisfies the following long time asymptotics:

$$
\frac{2 \theta(t)}{\log t} \xrightarrow{t \rightarrow \infty} \xi \text { in distribution, }
$$

where $\xi$ is the standard Cauchy distribution.
Since the appearance of this fundamental result, many related interesting questions were put forward and studied in depth by various authors. For instance, In 1987, two physicists Rudnick and Hu [RH87] (see also Rogers and Williams [RW00]) showed that, the winding number of a reflected Brownian motion in an exterior disk (instead of the punctured plane), the limiting distribution becomes of hyperbolic type instead of being Cauchy. It is also natural to study the winding of planar Brownian motion around multiple points or disks. However, in this context, the situation is much more complicated as the "winding number" is intrinsically non-abelian and takes values in a free group. Abelianized versions of planar Brownian winding around multiple points/disks were studied in [PY86, PY89, GK94, TW95]. Various generalizations to the contexts of positive recurrent diffusions, Riemann surfaces as well as higher dimensions were studied in [GK94, LM84, Wat00]. The proofs used in most of the above papers are based on the conformal invariance of planar Brownian motion, and thus are specific to two dimensions. There is also some literature concerning more general types of processes defined by stochastic line integrals. For instance,

[^0]Kuwada [Kuw09] studied large deviation principles and Laplace's approximation for current-valued processes in the Riemannian geometric setting.

The present paper is motivated by the following question: What is the long time behaviour of the abelianized winding number of a normally reflected Brownian motion on a compact Riemannian manifold with boundary? The simplest example of this is the abelianized winding number of a reflected Brownian motion in a bounded planar domain with multiple disks removed. Unlike the previous approach based on conformal invariance, we take a more geometric viewpoint, and this naturally extends to higher dimensions. To be more specific, we lift trajectories of the reflected Brownian motion to a suitable abelian covering space. Using this lifting we relate the abelianized Brownian winding number to the long time behaviour of the heat kernel on this covering space. The exact formulation of this problem and its relation to the long time behaviour of heat kernels is stated precisely in Sections 3 and Section 5.1, below. Our result is a refinement of a classical result by Toby and Werner [TW95], and the relationship to their work is discussed in Section 5.2.

Motivated by the above question, we also study a more fundamental question about the long time behaviour of heat kernels. The study of heat kernels on Riemannian manifolds lies at core of geometric analysis, and sheds light on many deep connections between analysis, geometry, topology and probability. The short time behaviour has been extensively studied in the literature and is relatively well understood (see for instance [BGV92, Gri99] and the references therein). The long time behaviour, on the other hand, is subtly related to global properties of the underlying manifold, and the general picture of this matter is far from being complete.

To our best knowledge, the main scenarios where the exact long time asymptotic behaviour of heat kernel can be determined is summarized as follows. The simplest case is when the underlying Riemannian manifold is compact, with or without boundary. In this case, the spectral theorem shows that the long time asymptotic behaviour is governed by the bottom spectrum of the Laplace-Beltrami operator. In the non-compact setting, the problem is highly non-trivial. Using representation theory, Bougerol [Bou81] determined the exact long time asymptotics for the distribution of $K$-invariant random walks on semi-simple Lie groups $G$, and thus for heat kernels on the associated symmetric spaces $G / K$. Using gradient and Harnack estimates developed by Li and Yau in [LY86], Li [Li86] determined the exact long time asymptotics of heat kernels on Riemannian manifolds with nonnegative Ricci curvature and polynomial volume growth. Using perturbations of elliptic operators, Lott [Lot92] and Kotani-Sunada [KS00] determined the exact long time asymptotics of heat kernel on abelian covers of closed Riemannian manifolds. In a more recent paper, using hyperbolic dynamics and mixing properties of geodesic flows in negative curvature, Ledrappier-Lim [LL15] determined the exact long time asymptotics of the heat kernel on the universal covering space of a negatively curved, closed Riemannian manifold, generalizing the case of the canonical hyperbolic space with constant negative curvature in which the heat kernel can be written down explicitly.

Motivated by the Brownian winding problem mentioned above, we consider abelian covers of compact Riemannian manifolds with smooth boundary, and we impose mixed Dirichlet and Neumann boundary conditions for the Laplacian. Our main result in this part (Theorem 2.1, below) determines the exact long time asymptotics of the heat kernel on abelian covering spaces. We believe this result
is interesting in its own right, and to some extent, is more fundamental than the original motivation from the winding number perspective. Our proof relies on the techniques developed in [Lot92, KS00], which represent the heat kernel in terms of a compact family of heat kernels on twisted line bundles and understanding the perturbation of principal eigenvalues for each of the associated twisted Laplacians.

There is one obstruction in using the above techniques when Dirichlet boundary conditions are imposed on a portion of the boundary. Namely, under a suitable transformation, the main difficulty can be reduced to an elegant eigenvalue minimization problem, that can be stated elementarily as follows. Let $\omega$ be a harmonic one form on the base manifold $M$ which is tangential at the boundary. Consider the following eigenvalue problem

$$
-\Delta \phi_{\omega}-4 \pi i \cdot \nabla \phi_{\omega}+4 \pi^{2}|\omega|^{2} \phi_{\omega}=\mu_{\omega} \phi_{\omega}
$$

under mixed Dirichlet and Neumann boundary conditions. We will shortly see that $\mu_{\omega}$ is the principal eigenvalue of a certain elliptic operator associated to $\omega$, and we use the notation $\mu_{\omega}$ to emphasize the dependence of this eigenvalue on $\omega$. A key ingredient to determining the long time asymptotic behaviour of the heat kernel is understanding the minimum of $\mu_{\omega}$. In the case that $M$ has no boundary (or only Neumann boundary conditions) are imposed, this is easy: the global minimum of $\mu_{\omega}$ is 0 , and is attained precisely when $\omega$ is zero. Under Dirichlet boundary conditions (or under mixed Dirichlet / Neumann boundary conditions, as we consider) the problem is more interesting, and the formulation is surprising. Namely, we will show that:
(i) Over all harmonic 1-forms $\omega$, the bottom spectrum $\mu_{\omega}$ is minimized at precisely those forms whose integral over closed loops is integer-valued.
(ii) The above minimum is of second order. That is, at the minimum, the Hessian of the map $\omega \mapsto \mu_{\omega}$ is a positive definite quadratic form.
Of course, in the case of purely Neumann boundary conditions, the only harmonic 1 -form with integer valued closed loop integrals is identically 0 . Thus the above formulation of the eigenvalue minimization problem is a generalization of the purely Neumann (or boundaryless) case. We will prove it Lemmas 4.4 and 4.5 in Section 4, below.

Finally to succinctly summarize our first main result (Theorem 2.1, below) shows that the heat kernel $\hat{H}(t, x, y)$ on the abelian cover $\hat{M}$ behaves asymptotically like

$$
\hat{H}(t, x, y) \approx \frac{C_{\mathcal{I}}^{\prime}(x, y)}{t^{k / 2}} \exp \left(-\lambda_{0} t-\frac{d_{\mathcal{I}}^{\prime}(x, y)^{2}}{t}\right) \quad \text { as } t \rightarrow \infty
$$

uniformly in $x, y \in \hat{M}$. Here $k$ is the rank of the deck transformation group, $\lambda_{0}$ is the principal eigenvalue of Laplacian on the base manifold $M$ with the specified mixed boundary conditions, and $C_{\mathcal{I}}^{\prime}, d_{\mathcal{I}}^{\prime}$ are explicit functions we define in Section 2, below. Our second main result (Theorem 3.2 in Section 3, below) uses the above heat kernel asymptotics to establish a Gaussian type central limit theorem for the winding number of normally reflected Brownian motions on the base manifold $M$.

Plan of this paper. In Section 2, we state our main result concerning the long time asymptotics of the heat kernel on abelian covers of $M$. In Section 3, we state our main result concerning the long time behaviour of the winding number of reflected Brownian motions on $M$. We prove these results in Section 4 and Section 5 respectively.

## 2. Long time behaviour of the heat kernel on abelian covers.

Let $M$ be a compact Riemannian manifold with a smooth boundary ${ }^{1}$. Let $\hat{M}$ be a Riemannian cover of $M$ with deck transformation group $G$ and covering map $\boldsymbol{\pi}$. We assume throughout this paper that $G$ is a finitely generated abelian group with rank $k \geqslant 1$, and $M \cong \hat{M} / G$. Let $G_{T}=\operatorname{tor}(G) \subseteq G$ denote the torsion subgroup of $G$, and let $G_{F} \stackrel{\text { def }}{=} G / G_{T}$. The order of $G_{T}$ is denoted by $\left|G_{T}\right|$.

Let $\Delta$ and $\hat{\Delta}$ be the Laplace-Beltrami operators on $M$ and $\hat{M}$ respectively. We assume that $\partial M$, the boundary of $M$, is decomposed as the disjoint union of two relatively open components $\partial_{D} M$ and $\partial_{N} M$. Let $H(t, p, q)$ be the heat kernel of $\Delta$ on $M$ with Dirichlet boundary conditions on $\partial_{D} M$ and Neumann boundary conditions on $\partial_{N} M$. Correspondingly on the covering space, let $\partial_{D} \hat{M}=\pi^{-1}\left(\partial_{D} M\right)$ and $\partial_{N} \hat{M}=\boldsymbol{\pi}^{-1}\left(\partial_{N} M\right)$. Let $\hat{H}(t, x, y)$ be the heat kernel of $\hat{\Delta}$ on $\hat{M}$ with Dirichlet boundary conditions on $\partial_{D} \hat{M}$, and Neumann boundary conditions on $\partial_{N} \hat{M}$. Let $\lambda_{0} \geqslant 0$ be the principal eigenvalue of $-\Delta$ with the given boundary conditions.

Our main result concerning the asymptotic long time behaviour of the heat kernel $\hat{H}$ on the covering space $\hat{M}$ is stated as follows.

Theorem 2.1. There exist explicit functions $C_{\mathcal{I}}, d_{\mathcal{I}}: \hat{M} \times \hat{M} \rightarrow[0, \infty)$ (defined in (2.7) and (2.9) below), such that

$$
\begin{equation*}
\lim _{t \rightarrow \infty}\left(t^{k / 2} e^{\lambda_{0} t} \hat{H}(t, x, y)-\frac{C_{\mathcal{I}}(x, y)}{\left|G_{T}\right|} \exp \left(-\frac{2 \pi^{2} d_{\mathcal{I}}^{2}(x, y)}{t}\right)\right)=0 \tag{2.1}
\end{equation*}
$$

uniformly for $x, y \in \hat{M}$. In particular, for every $x, y \in \hat{M}$, we have

$$
\lim _{t \rightarrow \infty} t^{k / 2} e^{\lambda_{0} t} \hat{H}(t, x, y)=\frac{C_{\mathcal{I}}(x, y)}{\left|G_{T}\right|}
$$

The definition of the functions $C_{\mathcal{I}}$ and $d_{\mathcal{I}}$ above requires the construction of an inner product structure on a space of harmonic 1-forms over $M$. More precisely, let

$$
\mathcal{H}^{1} \stackrel{\text { def }}{=}\left\{\omega \in T^{*} M \mid d \omega=0, d^{*} \omega=0, \text { and } \omega \cdot \nu=0 \text { on } \partial M\right\},
$$

be the space of harmonic 1 -forms on $M$ that are tangential on $\partial M$. Here $\nu$ denotes the outward pointing unit normal on $\partial M$, and depending on the context $x \cdot y$ denotes the dual pairing between co-tangent and tangent vectors, or the inner product given by the Riemannian metric. By the Hodge theorem we know that $\mathcal{H}^{1}$ is isomorphic to the first de Rham co-homology group on $M$.

Now define $\mathcal{H}_{G}^{1} \subseteq \mathcal{H}^{1}$ by

$$
\begin{equation*}
\mathcal{H}_{G}^{1}=\left\{\omega \in \mathcal{H}^{1} \mid \oint_{\hat{\gamma}} \pi^{*}(\omega)=0 \text { for all closed loops } \hat{\gamma} \subseteq \hat{M}\right\} . \tag{2.2}
\end{equation*}
$$

[^1]It is easy to see that $\mathcal{H}_{G}^{1}$ is naturally isomorphic ${ }^{2}$ to $\operatorname{Hom}(G, \mathbb{R})$, and hence $\operatorname{dim}\left(\mathcal{H}_{G}^{1}\right)=k$. Define an inner product on $\mathcal{H}_{G}^{1}$ as follows. Let $\phi_{0}$ be the principal eigenfunction of $-\Delta$ with the given boundary conditions, normalized so that $\phi_{0}>0$ in $M$ and $\left\|\phi_{0}\right\|_{L^{2}}=1$. Define the quadratic form $\mathcal{I}: \mathcal{H}_{G}^{1} \rightarrow \mathbb{R}$ by

$$
\begin{equation*}
\mathcal{I}(\omega)=8 \pi^{2} \int_{M}|\omega|^{2} \phi_{0}^{2}+8 \pi \int_{M} \phi_{0} \omega \cdot \nabla g_{\omega} \tag{2.3}
\end{equation*}
$$

where $g_{\omega}$ is $\mathrm{a}^{3}$ solution to the equation

$$
\begin{equation*}
-\Delta g_{\omega}-4 \pi \omega \cdot \nabla \phi_{0}=\lambda_{0} g_{\omega} \tag{2.4}
\end{equation*}
$$

with boundary conditions

$$
\begin{equation*}
g_{\omega}=0 \quad \text { on } \partial_{D} M, \quad \text { and } \quad \nu \cdot \nabla g_{\omega}=0 \quad \text { on } \partial_{N} M . \tag{2.5}
\end{equation*}
$$

In the course of the proof of Theorem 2.1, we will see that $\mathcal{I}$ arises naturally as the quadratic form induced by the Hessian of the principal eigenvalue of a family of elliptic operators (see Lemma 4.5, below).

Using $\mathcal{I}$, we define an inner product on $\mathcal{H}_{G}^{1}$ by

$$
\langle\omega, \tau\rangle_{\mathcal{I}} \stackrel{\text { def }}{=} \frac{1}{4}(\mathcal{I}(\omega+\tau)-\mathcal{I}(\omega-\tau)), \quad \omega, \tau \in \mathcal{H}_{G}^{1}
$$

We will show (see Lemma 4.5 below) that the function $\mathcal{I}(\omega)$ is well-defined, and $\langle\cdot, \cdot\rangle_{\mathcal{I}}$ is a positive definite inner product on $\mathcal{H}_{G}^{1}$.

Remark 2.2. Under Neumann boundary conditions (i.e. if $\partial_{D} M=\emptyset$ ), we know that $\lambda_{0}=0$ and $\phi_{0}$ is constant. In this case, equation (2.4) admits only constant solutions, and $\langle\cdot, \cdot\rangle_{\mathcal{I}}$ is simply the (normalized) $L^{2}$-inner product (see also Remark 2.3, below). Under Dirichlet boundary conditions, however, (2.4) admits a non-trivial solutions, and the inner product $\langle\cdot, \cdot\rangle_{\mathcal{I}}$ is not the standard $L^{2}$-inner product.

Next, to define the distance function $d_{\mathcal{I}}: \hat{M} \times \hat{M} \rightarrow \mathbb{R}$ appearing in Theorem 2.1, we take $x, y \in \hat{M}$ and define $\xi_{x, y} \in\left(\mathcal{H}_{G}^{1}\right)^{*} \stackrel{\text { def }}{=} \operatorname{Hom}\left(\mathcal{H}_{G}^{1} ; \mathbb{R}\right)$ by

$$
\begin{equation*}
\xi_{x, y}(\omega) \stackrel{\text { def }}{=} \int_{x}^{y} \boldsymbol{\pi}^{*}(\omega) \tag{2.6}
\end{equation*}
$$

where the integral is taken over any any smooth path in $\hat{M}$ joining $x$ and $y$. By definition of $\mathcal{H}_{G}^{1}$, the above integral is independent of the choice of path joining $x$

[^2]and $y$. We will show that the function $d_{\mathcal{I}}: \hat{M} \times \hat{M} \rightarrow \mathbb{R}$ is given by
\[

$$
\begin{equation*}
d_{\mathcal{I}}(x, y) \stackrel{\text { def }}{=}\left\|\xi_{x, y}\right\|_{\mathcal{I}^{*}}=\sup _{\substack{\omega \in \mathcal{H}_{G}^{1} \\\|\omega\|_{\mathcal{I}}=1}} \xi_{x, y}(\omega), \quad \text { for } x, y \in \hat{M} \tag{2.7}
\end{equation*}
$$

\]

Here $\|\cdot\|_{\mathcal{I}^{*}}$ denotes the norm on the dual space $\left(\mathcal{H}_{G}^{1}\right)^{*}$ obtained by dualising the inner product $\langle\cdot, \cdot\rangle_{\mathcal{I}}$.

Finally, to define $C_{\mathcal{I}}$, we let

$$
\begin{equation*}
\mathcal{H}_{\mathbb{Z}}^{1} \stackrel{\text { def }}{=}\left\{\omega \in \mathcal{H}_{G}^{1} \mid \oint_{\gamma} \omega \in \mathbb{Z}, \text { for all closed loops } \gamma \subseteq M\right\} . \tag{2.8}
\end{equation*}
$$

Clearly $\mathcal{H}_{\mathbb{Z}}^{1}$ is isomorphic to $\mathbb{Z}^{k}$, and hence we can find $\omega_{1}, \ldots, \omega_{k} \in \mathcal{H}_{\mathbb{Z}}^{1}$ which form a basis of $\mathcal{H}_{\mathbb{Z}}^{1}$. We will show that $C_{\mathcal{I}}$ is given by

$$
\begin{equation*}
C_{\mathcal{I}}(x, y)=(2 \pi)^{k / 2}\left|\operatorname{det}\left(\left(\left\langle\omega_{i}, \omega_{j}\right\rangle_{\mathcal{I}}\right)_{1 \leqslant i, j \leqslant k}\right)\right|^{-1 / 2} \phi_{0}(\boldsymbol{\pi}(x)) \phi_{0}(\boldsymbol{\pi}(y)) . \tag{2.9}
\end{equation*}
$$

Note that the value of $C_{\mathcal{I}}(x, y)$ does not depend on the choice of the basis $\left(\omega_{1}, \ldots, \omega_{k}\right)$. Indeed, if $\left(\omega_{1}^{\prime}, \ldots, \omega_{k}^{\prime}\right)$ is another such basis of the $\mathbb{Z}$-module $\mathcal{H}_{\mathbb{Z}}^{1}$, since the change-of-basis matrix belongs to $G L(k, \mathbb{Z})$, it must have determinant $\pm 1$.

We conclude this section by a few remarks on simple and but illustrative cases.
Remark 2.3 (Neumann boundary conditions). If Neumann boundary conditions are imposed on all of $\partial M$ (i.e. $\partial_{D} M=\emptyset$ ), then the definitions of $C_{\mathcal{I}}$ and $d_{\mathcal{I}}$ simplify considerably. As mentioned earlier, under Neumann boundary conditions we have

$$
\lambda_{0}=0 \quad \text { and } \quad \phi_{0} \equiv \operatorname{vol}(M)^{-1 / 2}
$$

and hence

$$
\begin{equation*}
\langle\omega, \tau\rangle_{\mathcal{I}}=\frac{8 \pi^{2}}{\operatorname{vol}(M)} \int_{M} \omega \cdot \tau \tag{2.10}
\end{equation*}
$$

is a constant multiple of the standard $L^{2}$-inner product. Here $\omega \cdot \tau$ denotes the inner product on 1-forms inherited from the metric on $M$. In this case, we have

$$
d_{\mathcal{I}}(x, y)=\left(\frac{\operatorname{vol}(M)}{8 \pi^{2}}\right)^{1 / 2} \sup _{\substack{\omega \in \mathcal{H}_{G}^{1} \\\|\omega\|_{L^{2}(M)}=1}} \int_{x}^{y} \pi^{*}(\omega)
$$

In addition,

$$
C_{\mathcal{I}}(x, y)=\frac{(2 \pi)^{k / 2}}{\operatorname{vol}(M)}\left|\operatorname{det}\left(\left(\left\langle\omega_{i}, \omega_{j}\right\rangle_{\mathcal{I}}\right)_{1 \leqslant i, j \leqslant k}\right)\right|^{-1 / 2}
$$

is a constant independent of $x, y \in \hat{M}$.
Note that under Neumann boundary conditions, the heat kernel $\hat{H}(t, x, y)$ on the covering space $\hat{M}$ decays with rate $t^{-k / 2}$ as $t \rightarrow \infty$. On the other hand, if $\partial M$ has a Dirichlet component with positive volume, then $\lambda_{0}>0$ and $\hat{H}(t, x, y)$ decays with rate $t^{-k / 2} e^{-\lambda_{0} t}$. In addition, in this case $\langle\cdot, \cdot\rangle_{\mathcal{I}}$ is no longer a constant multiple of the standard $L^{2}$ inner product.

Remark 2.4 (Computation of $\omega_{i}$ in planar domains). Suppose for now that $M$ is a bounded planar domain with $k$ disjoint disks excised, and assume that $\operatorname{rank}\left(G_{F}\right)=k$. In this case, the basis $\left\{\omega_{1}, \cdots, \omega_{k}\right\}$ can be constructed directly by solving some
boundary value problems. Indeed, choose $\left(p_{j}, q_{j}\right)$ inside the $j^{\text {th }}$ excised hole and define the harmonic form $\tau_{j}$ by

$$
\begin{equation*}
\tau_{j} \stackrel{\text { def }}{=} \frac{1}{2 \pi}\left(\frac{\left(p-p_{j}\right) d q-\left(q-q_{j}\right) d p}{\left(p-p_{j}\right)^{2}+\left(q-q_{j}\right)^{2}}\right) \tag{2.11}
\end{equation*}
$$

Define $\phi_{j}: M \rightarrow \mathbb{R}$ to be the solution of the PDE

$$
\left\{\begin{array}{cl}
-\Delta \phi_{j}=0 & \text { in } M \\
\partial_{\nu} \phi_{j}=\tau_{j} \cdot \nu & \text { on } \partial M
\end{array}\right.
$$

Then $\omega_{j}$ is given by

$$
\omega_{j}=\tau_{j}+d \phi_{j}
$$

The situation is completely explicit in the case when $M$ is a symmetric annulus (see Example 3.3).

## 3. The abelianized winding of Brownian motion on manifolds.

We now study the asymptotic behaviour of the abelianized winding of trajectories of reflected Brownian motion on the manifold $M$ using the heat kernel asymptotics given by Theorem 2.1. Although we formulate our result in the geometric setting, the intuition is mostly clear when $M$ is a bounded planar domain with multiple disk excised. The notion "abelianized" means we are counting the winding number of the Brownian trajectory around each hole but do not keep track of the order of winding around different holes.

The winding of trajectories can be naturally quantified by lifting them to the universal cover. More precisely, let $\bar{M}$ be the universal cover of $M$, and recall that the fundamental group $\pi_{1}(M)$ acts on $\bar{M}$ as deck transformations. Fix a fundamental domain $\bar{U} \subseteq \bar{M}$, and for each $g \in \pi_{1}(M)$ define $\bar{U}_{g}$ to be the image of $\bar{U}$ under the action of $g$. Also, define $\overline{\boldsymbol{g}}: \bar{M} \rightarrow \pi_{1}(M)$ by

$$
\overline{\boldsymbol{g}}(x)=g, \quad \text { if } x \in U_{g},
$$

to be the map recording which fundamental domain the current position belongs to.
Now given a reflected Brownian motion $W$ in $M$ with normal reflection at the boundary, let $\bar{W}$ be the unique lift of $W$ to $\bar{M}$ starting in $\bar{U}$. Define $\bar{\rho}(t)=\overline{\boldsymbol{g}}\left(\bar{W}_{t}\right) \in$ $\pi_{1}(M)$. Note that $\bar{\rho}(t)$ measures the (non-abelian) winding of the trajectory of $W$ up to time $t$.

Our main result of Theorem 2.1 will enable us to study the asymptotic behaviour of the projection of $\bar{\rho}$ to the abelianized fundamental group $\pi_{1}(M)_{\mathrm{ab}}$. We know that

$$
G \stackrel{\text { def }}{=} \pi_{1}(M)_{\mathrm{ab}} / \operatorname{tor}\left(\pi_{1}(M)_{\mathrm{ab}}\right)
$$

is a finitely generated free abelian group, and we let $k=\operatorname{rank}(G)$. Let $\pi_{G}: \pi_{1}(M) \rightarrow$ $G$ be the projection of the fundamental group of $M$ onto $G$. Fix a choice of loops $\gamma_{1}, \ldots, \gamma_{k} \in \pi_{1}(M)$ so that $\pi_{G}\left(\gamma_{1}\right), \ldots, \pi_{G}\left(\gamma_{k}\right)$ form a basis of $G$.

Definition 3.1. The $\mathbb{Z}^{k}$-valued winding number of $W$, which is denoted as $\rho(t)$, is the $\mathbb{Z}_{k}$-valued coordinate process of $\pi_{G}(\bar{\rho}(t))$ with respect to the basis $\pi_{G}\left(\gamma_{1}\right), \ldots$, $\pi_{G}\left(\gamma_{k}\right)$. Explicitly, $\rho(t)=\left(\rho_{1}(t), \ldots, \rho_{k}(t)\right)$ where

$$
\pi_{G}(\bar{\rho}(t))=\sum_{i=1}^{k} \rho_{i}(t) \pi_{G}\left(\gamma_{i}\right)
$$

Note that the $\mathbb{Z}^{k}$-valued winding number defined above depends on the choice of basis $\gamma_{1}, \ldots, \gamma_{k}$. If $M$ is a planar domain with $k$ holes, we can choose $\gamma_{i}$ to be a loop that only winds around the $i^{\text {th }}$ hole once. In this case, $\rho_{i}(t)$ is the number of times the trajectory of $W$ winds around the $i^{\text {th }}$ hole up to time $t$.

Our main result concerning the asymptotic long time behaviour of $\rho$ can be stated as follows.

Theorem 3.2. Let $W$ be a normally reflected Brownian motion in $M$, and $\rho$ be its $\mathbb{Z}^{k}$ valued winding number (as in Definition 3.1). Then, there exists a positive definite, explicitly computable covariance matrix $\Sigma$ (defined in (3.3), below) such that

$$
\begin{equation*}
\frac{\rho(t)}{t} \xrightarrow{p} 0 \quad \text { and } \quad \frac{\rho(t)}{\sqrt{t}} \xrightarrow{w} \mathcal{N}(0, \Sigma) . \tag{3.1}
\end{equation*}
$$

Here $\mathcal{N}(0, \Sigma)$ denotes a normally distributed random variable with mean 0 and covariance matrix $\Sigma$.

We now describe the covariance matrix $\Sigma$ above. Given $\omega \in \mathcal{H}^{1}$ define the map $\varphi_{\omega} \in \operatorname{Hom}\left(\pi_{1}(M), \mathbb{R}\right)$ by

$$
\varphi_{\omega}(\gamma)=\int_{\gamma} \omega
$$

It is well known that the map $\omega \mapsto \varphi_{\omega}$ provides an isomorphism between $\mathcal{H}^{1}$ and $\operatorname{Hom}\left(\pi_{1}(M), \mathbb{R}\right)$. Hence there exists a unique dual basis $\left\{\omega_{1}, \ldots, \omega_{k}\right\}$ in $\mathcal{H}^{1}$ such that

$$
\begin{equation*}
\int_{\gamma_{i}} \omega_{j}=\delta_{i, j} \tag{3.2}
\end{equation*}
$$

The covariance matrix $\Sigma$ appearing in Theorem 3.2 is given

$$
\begin{equation*}
\Sigma_{i, j} \stackrel{\text { def }}{=} \frac{1}{\operatorname{vol} M} \int_{M} \omega_{i} \cdot \omega_{j} \tag{3.3}
\end{equation*}
$$

The proof of Theorem 3.2 follows quite easily from our heat kernel result of Theorem 2.1, which will be given in Section 5 below. We remark, modulo certain amount of technicalities, that Theorem 3.2 can also be proved by using a probabilistic method. We sketch the argument in Section 5.3. To our best knowledge, even in the Euclidean setting, such a result and its proof are not readily available in the literature.

We now mention a few examples where Theorem 3.2 is applicable.
Example 3.3 (An explicit calculation in the annulus). When $M$ is a bounded planar domain with multiple holes, the limiting Gaussian distribution can be computed quite explicitly following Remark 2.4. We consider the simplest case when $M \subseteq \mathbb{R}^{2}$ is an annulus with inner radius $r_{1}$ and outer radius $r_{2}$ respectively. In this case, $k=1$ and $\rho(t)$ is simply the integer-valued winding number of the reflected Brownian motion in $M$ with respect to the inner hole. To define the one form $\omega_{1}$, choose $p_{1}=q_{1}=0$, and define $\tau_{1}$ by (2.11). Now $\tau_{1} \cdot \nu=0$ on $\partial M$, forcing $\phi_{1}=0$ and hence $\omega_{1}=\tau_{1}$. Thus Theorem 3.2 shows that $\rho(t) / \sqrt{t} \rightarrow \mathcal{N}\left(0, \sigma^{2}\right)$ where

$$
\begin{equation*}
\sigma^{2}=\frac{1}{\operatorname{vol} M} \int_{M}\left|\omega_{1}\right|^{2}=\frac{1}{2 \pi^{2}\left(r_{2}^{2}-r_{1}^{2}\right)} \log \left(\frac{r_{2}}{r_{1}}\right) \tag{3.4}
\end{equation*}
$$

We remark that in this case Wen [Wen17] proved a finer asymptotic result by explicit calculations:

$$
\operatorname{Var}(\rho(t)) \approx \frac{1}{4 \pi^{2}}\left(\ln ^{2}\left(\frac{r_{2}}{r_{1}}\right)-\ln ^{2}\left(\frac{r_{1}}{r_{0}}\right)\right)+\frac{\ln \left(r_{2} / r_{1}\right)}{2 \pi^{2}\left(r_{2}^{2}-r_{1}^{2}\right)}\left(t-\frac{r_{2}^{2}-r_{0}^{2}}{2}+r_{1}^{2} \ln \left(\frac{r_{2}}{r_{0}}\right)\right)
$$

where $r_{0}=\left|W_{0}\right|$ is the radial coordinate of the starting point. Note that Theorem 2.1 only shows $\operatorname{Var} \rho(t) / t \rightarrow \sigma^{2}$ as $t \rightarrow \infty$. Wen's result above goes further by providing explicit limit for $\operatorname{Var} \rho(t)-\sigma^{2} t$ as $t \rightarrow \infty$.

Example 3.4 (Winding in Knot Compliments). Another interesting example is the winding of 3D Brownian motion around knots. Recall that a knot $K$ is an embedding of $S^{1}$ into $\mathbb{R}^{3}$. A basic topological invariant of a knot $K$ is the fundamental group $\pi_{1}\left(\mathbb{R}^{3}-K\right)$ which is known as the knot group of $K$. The study of the fundamental group $\pi_{1}\left(\mathbb{R}^{3}-K\right)$ is important for the classification of knots and has significant applications in mathematical physics. It is well known that the abelianized fundamental group of $\mathbb{R}^{3}-K$ is always cyclic.

Let $K$ be a knot in $\mathbb{R}^{3}$. Consider the domain $M=\Omega-N_{K}$, where $N_{K}$ is a small tubular neighborhood of $K$ and $\Omega$ is a large bounded domain (a ball for instance) containing $N_{K}$. Let $W(t)$ be a reflected Brownian motion in $M$, and define $\rho(t)$ to be the $\mathbb{Z}$-valued winding number of $W$ with respect to a fixed generator of $\pi_{1}(M)_{\mathrm{ab}}$. Now $\rho(t)$ contains information about the entanglement of $W(t)$ with the knot $K$. Theorem 3.2 applies in this context, and shows that the long time behaviour of $\rho$ is Gaussian with mean zero and covariance given by (3.3).

In some cases, the generator of $\pi_{1}(M)_{\mathrm{ab}}$, which is used above to define $\rho$, can be written down explicitly. For instance, consider the ( $m, n$ )-torus knot, $K=K_{m, n}$, defined by $S^{1} \ni z \mapsto\left(z^{m}, z^{n}\right) \in S^{1} \times S^{1}$ where $\operatorname{gcd}(m, n)=1$. Then $\pi_{1}(M)$ is isomorphic to the free group with two generators $a$ and $b$, modulo the relation $a^{m}=b^{n}$. Here $a$ represents a meridional circle inside the open solid torus and $b$ represents a longitudinal circle winding around the torus in the exterior. In this case, a generator of $\pi_{1}(M)_{\mathrm{ab}}$ is $a^{n^{\prime}} b^{m^{\prime}}$, where $m^{\prime}, n^{\prime}$ are integers such that $m m^{\prime}+n m^{\prime}=1$. Now $a^{n^{\prime}} b^{m^{\prime}}$ represents a unit winding around the knot $K$, and $\rho(t)$ describes the total number of windings around $K$.

Finally, we remark that Toby and Werner [TW95] studied the long time asymptotics of the winding number of an obliquely reflected Brownian motion in a bounded planar domain. Under normal reflection with windings around disks, their result becomes a law of large numbers. In this case, our result of Theorem 3.2 is a refinement of Toby and Werner's result, since we are able to show that the long time average of the winding number is zero (see Proposition 5.3 below) and we prove a Gaussian type central limit theorem for fluctuations around the mean. A more detailed discussion about our connection with Toby and Werner's work is presented in Section 5.2 below.

## 4. Proof of the heat kernel asymptotics (Theorem 2.1).

We follow the main strategy developed by Lott [Lot92] and Kotani-Sunada [KS00], which is based on an integral representation of the heat kernel $\hat{H}(t, x, y)$ on the covering space $\hat{M}$ in terms of a compact family of heat kernels on twisted bundles over the base manifold $M$. Since $M$ is compact, the long time behaviour of these twisted heat kernels is governed by the principal eigenvalues of the associated twisted

Laplacians. It then turns out that the long time behaviour of $\hat{H}(t, x, y)$ can be studied in terms of the behaviour of the above principal eigenvalues near critical point.

In the case when only Neumann boundary conditions are imposed on $\partial M$ (i.e. if $\partial_{D} M=\emptyset$ ), the arguments in [Lot92, KS00] can be adapted easily. The main difficulty arises under Dirichlet boundary conditions, largely due to the fact that in this case the principal eigenvalue of Laplacian is strictly positive and the principal eigenfunction is non-constant. One needs to solve a non-trivial eigenvalue minimization problem (Lemma 4.4 and Lemma 4.5 below) concerning the perturbation of principal eigenvalues for the twisted Laplacians, which is almost straight forward in the Neumann boundary case.
Plan of this section. In Section 4.1 we describe the Lott/Kotani-Sunada integral representation of the lifted heat kernel. In Section 4.2 we present the proof of Theorem 2.1 based on the integral representation, assuming the correctness of two lemmas (Lemma 4.4 and Lemma 4.5 below) concerning the eigenvalue minimization problem. Finally in Section 4.3 and Section 4.4, we prove Lemma 4.4 and Lemma 4.5 respectively.

### 4.1. The Lott/Kotani-Sunanda integral representation of the lifted heat

 kernel. Let $S^{1}=\{z \in \mathbb{C}| | z \mid=1\}$ be the unit circle and let $\mathcal{G} \stackrel{\text { def }}{=} \operatorname{Hom}\left(G, S^{1}\right)$ be the space of one dimensional unitary representations of $G$. We know that $\mathcal{G}$ is a compact Lie group isomorphic to $\left(S^{1}\right)^{k}$ with a unique normalized Haar measure.For each given $\chi \in \mathcal{G}$, define an equivalence relation on $\hat{M} \times \mathbb{C}$ by

$$
(x, \zeta) \sim(g(x), \chi(g) \zeta) \quad \text { for all } g \in G
$$

and let $E_{\chi}$ be the quotient space $\hat{M} \times \mathbb{C} / \sim$. It follows that $E_{\chi}$ is a complex line bundle on $M . E_{\chi}$ carries a natural connection defined by usual differentiation, which together with the Levi-Civita connection on $M$, induce an associated Laplacian $\Delta_{\chi}$ acting on the space $C^{\infty}\left(E_{\chi}\right)$ of sections of $E_{\chi}$. If we impose Dirichlet boundary conditions on $\partial_{D} \hat{M}$ and Neumann boundary conditions on $\partial_{N} \hat{M}$ respectively, then $-\Delta_{\chi}$ is a self-adjoint and positive definite elliptic differential operator on $L^{2}\left(E_{\chi}\right)$.

The above constructions are easily understood from the following viewpoint. First of all, sections of $E_{\chi}$ can be identified with functions $s: \hat{M} \rightarrow \mathbb{C}$ satisfying the twisting condition

$$
\begin{equation*}
s(g(x))=\chi(g) s(x), \quad \forall x \in \hat{M}, g \in G \tag{4.1}
\end{equation*}
$$

Define the space

$$
\begin{align*}
\mathcal{D}_{\chi} \stackrel{\text { def }}{=}\left\{s \in C^{\infty}(\hat{M}, \mathbb{C}) \mid\right. & s \text { satisfies }(4.1), s=0 \text { on } \partial_{D} \hat{M}  \tag{4.2}\\
& \text { and } \left.\nu \cdot \nabla s=0 \text { on } \partial_{N} \hat{M}\right\}
\end{align*}
$$

Then $\Delta_{\chi}$ is simply the restriction of the usual Laplacian $\hat{\Delta}$ on $\hat{M}$, and the $L^{2}$-inner product is given by

$$
\begin{equation*}
\left\langle s_{1}, s_{2}\right\rangle_{L^{2}} \stackrel{\text { def }}{=} \int_{M} s_{1}\left(x_{p}\right) \overline{s_{2}\left(x_{p}\right)} d p \tag{4.3}
\end{equation*}
$$

for $s_{1}, s_{2} \in \mathcal{D}_{\chi}$. Here for each $p \in M, x_{p}$ is any point on the fiber $\boldsymbol{\pi}^{-1}(p)$ such that the function $p \mapsto x_{p}$ is measurable. The twisting condition (4.1) ensures that (4.3) is independent of the choice of $x_{p}$.

Remark 4.1. When $\chi \equiv \mathbf{1}$ is the trivial representation, $E_{\chi}$ is exactly the trivial line bundle $M \times \mathbb{C}$, sections of $E_{\chi}$ are just functions on $M$, and $\Delta_{\chi}$ is the standard Laplacian $\Delta$ on $M$.

Let $H_{\chi}(t, x, y)$ be the heat kernel of $-\Delta_{\chi}$ on $E_{\chi}$ (see [BGV92] for the general construction of heat kernels on vector bundles). We can view $H_{\chi}$ as a function on $(0, \infty) \times \hat{M} \times \hat{M}$ satisfying the twisting conditions

$$
H_{\chi}(t, g(x), y)=\chi(g) H_{\chi}(t, x, y) \quad \text { and } \quad H_{\chi}(t, x, g(y))=\overline{\chi(g)} H_{\chi}(t, x, y)
$$

The Lott [Lot92] and Kotani-Sunada [KS00] representation expresses $\hat{H}$ in terms of twisted heat kernels $H_{\chi}$.
Lemma 4.2 (Lott, Kotani-Sunada). The heat kernel $\hat{H}$ on $\hat{M}$ satisfies the identity

$$
\begin{equation*}
\hat{H}(t, x, y)=\int_{\mathcal{G}} H_{\chi}(t, x, y) d \chi \tag{4.4}
\end{equation*}
$$

where the integral is performed with respect to the normalized Haar measure $d \chi$ on $\mathcal{G}$.

Proof. Since a full proof can be found in [Lot92, Proposition 38], and [KS00, Lemma 3.1], we only provide a short formal derivation. Suppose $\hat{H}$ is defined by (4.4). Clearly $\hat{H}$ satisfies the heat equation with Dirichlet boundary conditions on $\partial_{D} \hat{M}$ and Neumann boundary conditions on $\partial_{N} \hat{M}$. For the initial condition, observe

$$
H_{\chi}(0, x, y)=\sum_{g \in G} \overline{\chi(g)} \delta_{g(x)}(y)
$$

where $\delta_{g(x)}$ denotes the Dirac delta function at $g(x)$. Integrating over $\mathcal{G}$ and using the orthogonality property

$$
\int_{\mathcal{G}} \chi(g) d \chi= \begin{cases}1 & g=\mathrm{Id} \\ 0 & g \neq \mathrm{Id}\end{cases}
$$

we see that $\hat{H}(0, x, y)=\delta_{x}(y)$, and hence $\hat{H}$ must be the heat kernel on $\hat{M}$.
Remark 4.3. The integral representation (4.4) is similar to Fourier transform and inversion. Indeed, for each $\chi \in \mathcal{G}$, it is easy to see that

$$
H_{\chi}(t, x, y)=\sum_{g \in G} \chi(g) \hat{H}(t, x, g(y))
$$

One can view $\mathcal{G} \ni \chi \mapsto H_{\chi}$ as some sort of Fourier transform of $\hat{H}$, and equation (4.4) gives the inversion formula.
4.2. Proof of the heat kernel asymptotics (Theorem 2.1). The representation (4.4) allows us to study the long time behaviour of $\hat{H}$ in terms of the long time behaviour of $H_{\chi}$, and by the compactness of $M$, the latter is well known from classical spectral theory. More precisely, the twisted Laplacian $\Delta_{\chi}$ admits a sequence of eigenvalues

$$
0 \leqslant \lambda_{\chi, 1} \leqslant \lambda_{\chi, 2} \leqslant \cdots \leqslant \lambda_{\chi, j} \leqslant \cdots \uparrow \infty
$$

and a corresponding sequence of eigenfunctions $\left\{s_{\chi, j} \mid j \geqslant 0\right\} \subseteq \mathcal{D}_{\chi}$ which forms an orthonormal basis of $L^{2}\left(E_{\chi}\right)$. According to perturbation theory, $\lambda_{\chi, j}$ is smooth in
$\chi$, and up to a normalization $s_{\chi, j}$ can be chosen to depend smoothly on $\chi$. The heat kernel $H_{\chi}(t, x, y)$ can now be written as

$$
\begin{equation*}
H_{\chi}(t, x, y)=\sum_{j=0}^{\infty} e^{-\lambda_{\chi, j} t} s_{\chi, j}(x) \overline{s_{\chi, j}(y)} \tag{4.5}
\end{equation*}
$$

Note that since $M$ is compact and $\partial M$ is smooth by assumption, the above heat kernel expansion is uniform in $x, y \in \hat{M}$. This can be seen from the fact that the eigenfunction $s_{\chi, j}$ is uniformly bounded by a polynomial power of eigenvalue $\lambda_{\chi, j}$, together with Weyl's law on the growth of the eigenvalues. Combining (4.5) with Lemma 4.2, we have

$$
\begin{equation*}
\hat{H}(t, x, y)=\sum_{j=0}^{\infty} \int_{\mathcal{G}} e^{-\lambda_{\chi, j} t} s_{\chi, j}(x) \overline{s_{\chi, j}(y)} d \chi \tag{4.6}
\end{equation*}
$$

From (4.6), it is natural to expect that the long time behaviour of $\hat{H}$ is controlled by the initial term of the series expansion. In this respect, there are two key ingredients for proving Theorem 2.1. The first key point, which is the content of Lemma 4.4, will allow us to see that the integral $\int_{\mathcal{G}} e^{-\lambda_{\chi, 0} t} s_{\chi, 0}(x) \overline{s_{\chi, 0}(y)} d \chi$ concentrates at the trivial representation $\chi=\mathbf{1}$ when $t$ is large. Having such concentration property, the second key point, which is the content of lemma 4.5, will then allow us to determine the long time asymptotics of $\hat{H}$ precisely from the rate at which $\lambda_{\chi, 0} \rightarrow \lambda_{0}$ as $\chi \rightarrow \mathbf{1} \in \mathcal{G}$. Note that when $\chi=\mathbf{1}$, the corresponding eigenvalue $\lambda_{1,0}$ is exactly $\lambda_{0}$, the principal eigenvalue of $-\Delta$ on $M$.

Lemma 4.4 (Minimizing the principal eigenvalue). The function $\chi \mapsto \lambda_{\chi, 0}$ attains a unique global minimum on $\mathcal{G}$ at the trivial representation $\chi=\mathbf{1}$.

We prove Lemma 4.4 in Section 4.3 below. Note that when $\chi=\mathbf{1}, \Delta_{\chi}$ is simply the standard Laplacian $\Delta$ acting on functions on $M$. If Neumann boundary conditions are imposed on all of $\partial M$ (i.e. when $\partial_{D} M=\emptyset$ ), $\lambda_{\mathbf{1}, 0}=0$. In this case, the proof of Lemma 4.4 can be adapted from the arguments in [Sun89] (see also a direct proof in Section 4.3 in the Neumann boundary case). However, if Dirichlet boundary conditions are imposed on a portion of $\partial M$ (i.e. $\partial_{D} M \neq \emptyset$ ), then $\lambda_{\mathbf{1}, 0}>0$ and the proof of Lemma 4.4 requires an entirely different approach.

In view of (4.6) and Lemma 4.4, to determine the long time behaviour of $\hat{H}$, we also need to understand the rate at which $\lambda_{\chi, 0}$ approaches the global minimum as $\chi \rightarrow \mathbf{1}$. When $G$ is torsion free, the problem can be reduced to the linear space $\mathcal{H}_{G}^{1}$. To be precise, $\mathcal{H}_{G}^{1}$ can be identified as the Lie algebra of $\mathcal{G}$ in which the exponential map is given by

$$
\begin{equation*}
\mathcal{H}_{G}^{1} \ni \omega \mapsto\left[g \mapsto \chi_{\omega}(g) \stackrel{\text { def }}{=} \exp \left(2 \pi i \int_{x_{0}}^{g\left(x_{0}\right)} \pi^{*}(\omega)\right)\right] \in \mathcal{G}, \tag{4.7}
\end{equation*}
$$

where $x_{0}$ is some base point and the integral is taken over any smooth path in $\hat{M}$ joining $x_{0}$ and $g\left(x_{0}\right)$.

Now the rate at which $\lambda_{\chi, 0} \rightarrow \lambda_{0}$ as $\chi \rightarrow \mathbf{1} \in \mathcal{G}$ can be obtained from the rate at which $\lambda_{\chi_{\omega}, 0} \rightarrow \lambda_{0}$ as $\omega \rightarrow 0 \in \mathcal{H}_{G}^{1}$. In fact, as we will see, the quadratic form induced by the Hessian of the map $\omega \mapsto \lambda_{\chi_{\omega}, 0}$ at $\omega=0$ is precisely $\mathcal{I}(\omega)$ defined by (2.3), and this determines the rate at which $\lambda_{\chi_{\omega}, 0}$ approaches the global minimum $\lambda_{0}$.

Lemma 4.5 (Positivity of the Hessian). For any $\varepsilon>0$, there exists $\delta>0$ such that if $0<|\omega|<\delta$ we have

$$
\begin{equation*}
\left|\lambda_{\chi_{\omega}, 0}-\lambda_{0}-\frac{\mathcal{I}(\omega)}{2}\right|<\varepsilon\|\omega\|_{L^{2}(M)}^{2} \tag{4.8}
\end{equation*}
$$

where $\mathcal{I}(\omega)$ is defined in (2.3). Moreover, the map $\omega \mapsto \mathcal{I}(\omega)$ is a well defined quadratic form, and induces a positive definite inner product on $\mathcal{H}_{G}^{1}$.

We point out that the positivity of the quadratic form $\mathcal{I}(\omega)$ is crucial. As mentioned earlier (Remark 2.3), if only Neumann boundary conditions are imposed on $\partial M, \mathcal{I}(\omega)$ is simply a multiple of the standard $L^{2}$ inner product on 1-forms over $M$, and the positivity is straight forward. The main difficulty again lies in the case of Dirichlet boundary conditions, where the positivity is by no mean obvious. We prove Lemma 4.5 in Section 4.4.

Assuming Lemma 4.4 and Lemma 4.5 for the moment, we can now prove Theorem 2.1. In $[\mathrm{KS} 00]$ for the case without boundary, the authors pointed out that the long time asymptotics is uniformly in $x, y \in \hat{M}$. However, in our modest opinion some essential details seem to be missing. Our main effort in the argument below is devoted to proving uniform convergence. We first consider the case when $G$ is torsion free, and later on show that how the general case can be dealt with from the torsion free case.

Proof of Theorem 2.1 when $G$ is torsion free. Note first that Lemma 4.4 allows us to localize the integral in (4.6) to an arbitrarily small neighborhood of the trivial representation 1. More precisely, we claim that for any open neighborhood $R$ of $\mathbf{1} \in \mathcal{G}$, there exist constants $C_{1}>0$ depending on $R$, such that

$$
\begin{equation*}
\sup _{x, y \in \hat{M}}\left|e^{\lambda_{0} t} \hat{H}(x, y, t)-\int_{R} \exp \left(-\left(\lambda_{\chi, 0}-\lambda_{0}\right) t\right) s_{\chi, 0}(x) \overline{s_{\chi, 0}(y)} d \chi\right| \leqslant e^{-C_{1} t} \tag{4.9}
\end{equation*}
$$

This in particular implies that the long time behaviour of $\hat{H}(t, x, y)$ is determined by the long time behaviour of the integral representation around an arbitrarily small neighborhood of $\mathbf{1} \in \mathcal{G}$.

To establish (4.9), recall that Rayleigh's principle and the strong maximum principle guarantee that $\lambda_{\mathbf{1}, 0}$ is simple. Standard perturbation theory (c.f. [RS78], Theorem XII.13) guarantees that when $\chi$ is sufficiently close to $\mathbf{1}$, the eigenvalue $\lambda_{\chi, 0}$ is also simple (i.e. $\lambda_{\chi, 0}<\lambda_{\chi, 1}$ ). Now, by Lemma 4.4, we observe

$$
\lambda^{\prime} \stackrel{\text { def }}{=} \min \left\{\inf \left\{\lambda_{\chi, 1} \mid \chi \in \mathcal{G}\right\}, \inf \left\{\lambda_{\chi, 0} \mid \chi \in \mathcal{G}-R\right\}\right\}>\lambda_{0}
$$

Hence by choosing $C_{1} \in\left(0, \lambda^{\prime}-\lambda_{0}\right)$, we have

$$
\begin{aligned}
\sup _{x, y \in \hat{M}}\left(\mid \sum_{j=1}^{\infty} \int_{\mathcal{G}} e^{-\left(\lambda_{\chi, j}-\lambda_{0}\right) t} s_{\chi, j}\right. & (x) \overline{s_{\chi, j}(y)} d \chi \mid \\
& \left.+\left|\int_{\mathcal{G}-R} e^{-\left(\lambda_{\chi, 0}-\lambda_{0}\right) t} s_{\chi, 0}(x) \overline{s_{\chi, 0}(y)} d \chi\right|\right) \leqslant e^{-C_{1} t}
\end{aligned}
$$

for all $t$ sufficiently large. This immediately implies (4.9).
For any small neighborhood $R$ of 1 as before, our next task is to convert the integral over $R$ in (4.9) to an integral over a neighborhood of 0 in $\mathcal{H}_{G}^{1}$ (the Lie algebra of $\mathcal{G}$ ) using the exponential map (4.7). To do this, recall $\left\{\omega_{1}, \ldots, \omega_{k}\right\}$ was chosen to be a basis of $\mathcal{H}_{\mathbb{Z}}^{1} \subseteq \mathcal{H}_{G}^{1}$. Identifying $\mathcal{H}_{G}^{1}$ with $\mathbb{R}^{k}$ using this basis, we let
$d \omega$ denote the pullback of the Lebesgue measure on $\mathbb{R}^{k}$ to $\mathcal{H}_{G}^{1}$. Equivalently, $d \omega$ is the Haar measure on $\mathcal{H}_{G}^{1}$ normalized so that the parallelogram with sides $\omega_{1}, \ldots$, $\omega_{k}$ has measure 1. Clearly

$$
\begin{align*}
\int_{R} \exp \left(-\left(\lambda_{\chi, 0}-\lambda_{0}\right) t\right) s_{\chi, 0}( & x) \overline{s_{\chi, 0}(y)} d \chi  \tag{4.10}\\
& =\int_{T} \exp \left(-\left(\mu_{\omega}-\lambda_{0}\right) t\right) s_{\chi_{\omega}, 0}(x) \overline{s_{\chi_{\omega}, 0}(y)} d \omega
\end{align*}
$$

where $\mu_{\omega} \stackrel{\text { def }}{=} \lambda_{\chi_{\omega}, 0}$ and $T$ is the inverse image of $R$ under the map $\omega \mapsto \chi_{\omega}$.
Recall that the eigenfunctions $s_{\chi_{\omega}, 0}$ appearing above are sections of the twisted bundle $E_{\chi_{\omega}}$. They can be converted to functions on $M$ using some canonical section $\sigma_{\omega}$. Explicitly, let $x_{0} \in \hat{M}$ be a fixed base point. For given $\omega \in \mathcal{H}_{G}^{1}$, define $\sigma_{\omega}: \hat{M} \rightarrow \mathbb{C}$ by

$$
\begin{equation*}
\sigma_{\omega}(x) \stackrel{\text { def }}{=} \exp \left(2 \pi i \int_{x_{0}}^{x} \pi^{*}(\omega)\right) \tag{4.11}
\end{equation*}
$$

where $\boldsymbol{\pi}^{*}(\omega)$ is the pullback of $\omega$ to $\hat{M}$ via the covering projection $\boldsymbol{\pi}$, and the integral is taken along any smooth path in $\hat{M}$ joining $x_{0}$ and $x$. Observe that for any $g \in G$, we have

$$
\begin{equation*}
\sigma_{\omega}(g(x))=\sigma_{\omega}(x) \exp \left(2 \pi i \int_{x}^{g(x)} \pi^{*}(\omega)\right)=\chi_{\omega}(g) \sigma_{\omega}(x) \tag{4.12}
\end{equation*}
$$

where $\chi_{\omega} \in \mathcal{G}$ is defined in equation (4.7). Thus $\sigma_{\omega}$ satisfies the twisting condition (4.1) and hence can be viewed as a section of $E_{\chi_{\omega}}$. Now define

$$
\phi_{\omega} \stackrel{\text { def }}{=} \overline{\sigma_{\omega}} s_{\chi_{\omega}, 0} .
$$

Then $\phi_{\omega}(g(x))=\phi_{\omega}(x)$ for all $g \in \mathcal{G}$, and thus $\phi_{\omega}$ can be viewed as a smooth function on $M$.

We can now rewrite (4.10) as

$$
\begin{align*}
& \int_{R} \exp \left(-\left(\lambda_{\chi, 0}-\lambda_{0}\right) t\right) s_{\chi, 0}(x) \overline{s_{\chi, 0}(y)} d \chi  \tag{4.13}\\
&=\int_{T} \exp \left(-\left(\mu_{\omega}-\mu_{0}\right) t-2 \pi i \xi_{x, y}(\omega)\right) \phi_{\omega}(x) \overline{\phi_{\omega}(y)} d \omega
\end{align*}
$$

where $\xi_{x, y}(\omega)$ is defined in (2.6). Thus, using (4.9), we obtain

$$
\begin{equation*}
\sup _{x, y \in \hat{M}}\left|e^{\lambda_{0} t} \hat{H}(x, y, t)-I_{1}\right| \leqslant e^{-C_{1} t}, \quad \text { for } t \text { sufficiently large } \tag{4.14}
\end{equation*}
$$

where

$$
I_{1} \stackrel{\text { def }}{=} \int_{T} \exp \left(-\left(\mu_{\omega}-\mu_{0}\right) t-2 \pi i \xi_{x, y}(\omega)\right) \phi_{\omega}(x) \overline{\phi_{\omega}(y)} d \omega
$$

By making the neighborhood $R$ (and hence also $T$ ) small, we can ensure that $\phi_{\omega}$ close to $\phi_{0}$. Moreover, when $\omega$ is close to 0 , Lemma 4.5 implies $\mu_{\omega}-\mu_{0} \approx \mathcal{I}(\omega) / 2$. We claim that for any $\eta>0$, the neighborhood $R \ni \mathbf{1}$ can be chosen such that

$$
\begin{equation*}
\limsup _{t \rightarrow \infty} \sup _{x, y \in \hat{M}} t^{k / 2}\left(I_{1}-I_{2}\right)<\eta, \tag{4.15}
\end{equation*}
$$

where

$$
I_{2} \stackrel{\text { def }}{=} \int_{\mathcal{H}_{G}^{1}} \exp \left(-\frac{1}{2} \mathcal{I}(\omega) t-2 \pi i \xi_{x, y}(\omega)\right) \phi_{0}(x) \overline{\phi_{0}(y)} d \omega
$$

To avoid breaking continuity, we momentarily postpone the proof of (4.15). Now we see that (4.14) and (4.15) combined imply

$$
\begin{equation*}
\lim _{t \rightarrow \infty}\left(t^{k / 2} e^{\lambda_{0} t} \hat{H}(t, x, y)-t^{k / 2} I_{2}\right)=0 \tag{4.16}
\end{equation*}
$$

Therefore, to complete the proof, we only need to evaluate $I_{2}$ and express it in the form in (2.1).

To do this, write $\omega=\sum c_{n} \omega_{n} \in \mathcal{H}_{G}^{1}$ and

$$
\mathcal{I}(\omega)=\sum_{m, n=1}^{k} a_{m, n} c_{m} c_{n}
$$

where $a_{m, n} \stackrel{\text { def }}{=}\left\langle\omega_{m}, \omega_{n}\right\rangle_{\mathcal{I}}$. Let $A$ be the matrix $\left(a_{m, n}\right)$, and $a_{m, n}^{-1}$ be the $(m, n)$ entry of the matrix $A^{-1}$. Then

$$
\begin{aligned}
I_{2}= & \phi_{0}(x) \overline{\phi_{0}(y)} . \\
& \int_{c \in \mathbb{R}^{k}} \exp \left(-\sum_{m, n=1}^{k} a_{m, n} c_{m} c_{n} t-2 \pi i \sum_{m=1}^{k} c_{m} \xi_{x, y}\left(\omega_{m}\right)\right) d c_{1} \cdots d c_{k} \\
= & \phi_{0}(x) \overline{\phi_{0}(y)} \frac{(2 \pi)^{k / 2}}{t^{k / 2} \operatorname{det}\left(a_{m, n}\right)^{1 / 2}} \exp \left(-\frac{2 \pi^{2}}{t} \sum_{m, n=1}^{k} a_{m, n}^{-1} \xi_{x, y}\left(\omega_{m}\right) \xi_{x, y}\left(\omega_{n}\right)\right) \\
= & \phi_{0}(x) \overline{\phi_{0}(y)} \frac{(2 \pi)^{k / 2}}{t^{k / 2} \operatorname{det}\left(a_{m, n}\right)^{1 / 2}} \exp \left(-\frac{2 \pi^{2}}{t}\left\|\xi_{x, y}\right\|_{\mathcal{I}^{*}}^{2}\right),
\end{aligned}
$$

where the second equality follows from the formula for the Fourier transform of Gaussian distribution. Note that $\phi_{0}$ is real, and therefore

$$
I_{2}=t^{-k / 2} C_{\mathcal{I}}(x, y) \exp \left(-\frac{2 \pi^{2} d_{\mathcal{I}}^{2}(x, y)}{t}\right)
$$

where $C_{\mathcal{I}}$ is defined by (2.9). Combined with (4.16), this finishes the proof of Theorem 2.1 when $G$ is torsion free.

It remains to prove (4.15). Since $\omega \mapsto \phi_{\omega}$ is continuous, there exists a neighborhood $T \ni 0$ such that

$$
\begin{equation*}
\sup _{x \in \widehat{M}}\left|\phi_{\omega}(x)-\phi_{0}(x)\right|<\eta \quad \text { for all } \omega \in T \tag{4.17}
\end{equation*}
$$

Now we know that (4.14) holds with some constant $C_{1}=C_{1}(\eta)>0$ when $t$ is large. Write

$$
t^{k / 2}\left(I_{1}-I_{2}\right)=J_{1}+J_{2}+J_{3}
$$

where

$$
\begin{gathered}
J_{1} \stackrel{\text { def }}{=} t^{k / 2} \int_{T}\left(e^{-\left(\mu_{\omega}-\mu_{0}\right) t}-e^{-\mathcal{I}(\omega) t / 2}\right) \exp \left(-2 \pi i \xi_{x, y}(\omega)\right) \phi_{\omega}(x) \overline{\phi_{\omega}(y)} d \omega \\
J_{2} \stackrel{\text { def }}{=} t^{k / 2} \int_{T} \exp \left(-\frac{1}{2} \mathcal{I}(\omega) t-2 \pi i \xi_{x, y}(\omega)\right)\left(\phi_{\omega}(x) \overline{\phi_{\omega}(y)}-\phi_{0}(x) \overline{\phi_{0}(y)}\right) d \omega
\end{gathered}
$$

and

$$
J_{3} \stackrel{\text { def }}{=} t^{k / 2} \int_{\mathcal{H}_{G}^{1}-T} \exp \left(-\frac{1}{2} \mathcal{I}(\omega) t-2 \pi i \xi_{x, y}(\omega)\right) \phi_{0}(x) \overline{\phi_{0}(y)} d \omega
$$

First, by Lemma 4.5, $\mathcal{I}(\omega)$ is a positive definite quadratic form, and hence the Gaussian tail estimate shows there exists $C_{2}=C_{2}(\eta)>0$, such that

$$
\left|J_{3}\right| \leqslant e^{-C_{2} t}
$$

uniformly in $x, y \in \hat{M}$, when $t$ is sufficiently large.
Next, by (4.17) and the positivity of the quadratic form $\mathcal{I}(\omega)$, we have

$$
\left|J_{2}\right| \leqslant C_{3} \eta t^{k / 2} \int_{T} e^{-\mathcal{I}(\omega) t / 2} d \omega=C_{3} \eta \int_{\sqrt{t} \cdot T} e^{-\mathcal{I}(v) / 2} d v \leqslant C_{4} \eta
$$

uniformly in $x, y \in \hat{M}$.
Finally, to estimate $J_{1}$, first choose $K \subseteq \mathcal{H}_{G}^{1}$ compact such that

$$
\int_{\mathcal{H}_{G}^{1}-K} \exp \left(-\frac{1}{4} \mathcal{I}(v)\right) d v<\eta
$$

By using the same change of variables $v=\sqrt{t} \omega$, we write

$$
J_{1}=J_{1}^{\prime}+J_{1}^{\prime \prime}
$$

where

$$
\begin{aligned}
J_{1}^{\prime} \stackrel{\text { def }}{=} \int_{K}( & \left.\exp \left(-\left(\mu_{v / t^{1 / 2}}-\mu_{0}\right) t\right)-\exp \left(-\frac{1}{2} \mathcal{I}(v)\right)\right) \\
\cdot & \exp \left(-\frac{2 \pi i}{\sqrt{t}} \xi_{x, y}(v)\right) \phi_{v / t^{1 / 2}}(x) \overline{\phi_{v / t^{1 / 2}}(y)} d v
\end{aligned}
$$

and

$$
\begin{aligned}
J_{1}^{\prime \prime} \stackrel{\text { def }}{=} \int_{\sqrt{t} \cdot T-K}\left(\operatorname { e x p } \left(-\left(\mu_{v / t^{1 / 2}}-\mu_{0}\right)\right.\right. & t)-
\end{aligned} \begin{aligned}
& \left.\exp \left(-\frac{1}{2} \mathcal{I}(v)\right)\right) \\
& \cdot \exp \left(-\frac{2 \pi i}{\sqrt{t}} \xi_{x, y}(v)\right) \phi_{v / t^{1 / 2}}(x) \overline{\phi_{v / t^{1 / 2}}(y)} d v
\end{aligned}
$$

respectively. By Lemma 4.5, we know that

$$
\lim _{t \rightarrow \infty}\left(\mu_{v / t^{1 / 2}}-\mu_{0}\right) t=\frac{1}{2} \mathcal{I}(v)
$$

for every $v \in \mathcal{H}_{G}^{1}$. Therefore, by the dominated convergence theorem, we have

$$
\lim _{t \rightarrow \infty} \sup _{x, y \in \hat{M}}\left|J_{1}^{\prime}\right|=0
$$

To estimate $J_{1}^{\prime \prime}$, choose $\varepsilon>0$ such that

$$
\frac{1}{4} \mathcal{I}(\omega) \geqslant \varepsilon\|\omega\|_{L^{2}(M)}^{2}, \quad \text { for all } \omega \in \mathcal{H}_{G}^{1}
$$

For this $\varepsilon$, Lemma 4.5 allows us to further assume that $T$ is small enough so that

$$
\omega \in T \Longrightarrow \mu_{\omega}-\mu_{0} \geqslant \frac{1}{2} \mathcal{I}(\omega)-\varepsilon\|\omega\|_{L^{2}(M)}^{2} \geqslant \frac{1}{4} \mathcal{I}(\omega) .
$$

In particular, we have

$$
v \in \sqrt{t} \cdot T \Longrightarrow\left(\mu_{v / t^{1 / 2}}-\mu_{0}\right) t \geqslant \frac{1}{4} \mathcal{I}(v)
$$

It follows that

$$
J_{1}^{\prime \prime} \leqslant C_{5} \int_{\sqrt{t} \cdot T-K}\left(\exp \left(-\left(\mu_{v / t^{1 / 2}}-\mu_{0}\right) t\right)+\exp \left(-\frac{1}{2} \mathcal{I}(v)\right)\right) d v
$$

$$
\begin{aligned}
& \leqslant 2 C_{5} \int_{\sqrt{t} \cdot T-K} \exp \left(-\frac{1}{4} \mathcal{I}(v)\right) d v \\
& \leqslant 2 C_{5} \int_{\mathcal{H}_{G}^{1}-K} \exp \left(-\frac{1}{4} \mathcal{I}(v)\right) d v \\
& \leqslant 2 C_{5} \eta
\end{aligned}
$$

uniformly in $x, y \in \hat{M}$.
Combining the previous estimates, we conclude

$$
\varlimsup_{t \rightarrow \infty} \sup _{x, y \in \hat{M}}\left(t^{k / 2}\left(I_{1}-I_{2}\right)\right) \leqslant\left(C_{4}+2 C_{5}\right) \eta
$$

and $\eta$ with $\eta /\left(C_{4}+2 C_{5}\right)$ yields (4.15) as claimed.
When $G$ is has a torsion subgroup, we prove Theorem 2.1 by factoring through an intermediate finite cover.

Proof of Theorem 2.1 when $G$ has a torsion subgroup. Since $G$ can be (non-canonically) expressed as a direct sum $G_{T} \oplus G_{F}$, we define $M_{1}=\hat{M} / G_{F}$. This leads to the covering factorization

where $\boldsymbol{\pi}_{T}$ and $\boldsymbol{\pi}_{F}$ have deck transformation groups $G_{T}$ and $G_{F}$ respectively, and $M_{1}$ is compact.

Recall that $\lambda_{0}$ is the principal eigenvalue of $-\Delta$ on $M$, and $\phi_{0}$ is the corresponding $L^{2}$ normalized eigenfunction. Let $\Lambda_{0}$ be the principal eigenvalue of $-\Delta_{1}$ on $M_{1}$, and $\Phi_{0}$ ) be the corresponding $L^{2}$ normalized eigenfunction. (Here $\Delta_{1}$ is the Laplacian on $M_{1}$.)

Notice that $\pi_{T}^{*} \phi_{0}$, the pull back of $\phi_{0}$ to $M_{1}$, is an eigenfunction of $-\Delta_{1}$ and $\left\|\boldsymbol{\pi}_{T}^{*} \phi_{0}\right\|_{L^{2}(M)}=\left|G_{T}\right|^{1 / 2}$. Thus

$$
\begin{equation*}
\Lambda_{0}=\lambda_{0} \quad \text { and } \quad \Phi_{0}=\frac{\pi_{T}^{*} \phi_{0}}{\left|G_{T}\right|^{1 / 2}} \tag{4.19}
\end{equation*}
$$

Let $\mathcal{I}_{1}\left(\omega_{1}\right)$ be the analogue of $\mathcal{I}$ (defined in equation (2.3)) for the manifold $M_{1}$. Explicitly,

$$
\mathcal{I}_{1}\left(\omega_{1}\right)=8 \pi^{2} \int_{M_{1}}\left|\omega_{1}\right|^{2} \Phi_{0}^{2}+8 \pi \int_{M_{1}} \Phi_{0} \omega_{1} \cdot \nabla g_{1}
$$

where $g_{1}$ is a solution of

$$
-\Delta g_{1}-4 \pi \omega_{1} \cdot \nabla \Phi_{0}=\Lambda_{0} g_{1}
$$

with Dirichlet boundary conditions on $\boldsymbol{\pi}_{T}^{-1}\left(\partial_{D} M\right)$ and Neumann boundary conditions on $\boldsymbol{\pi}_{T}^{-1}\left(\partial_{N} M\right)$. Note that given $\omega_{1} \in \mathcal{H}_{G}^{1}\left(M_{1}\right)$ we can find $\omega \in \mathcal{H}_{G}^{1}(M)$ such that $\boldsymbol{\pi}_{T}^{*}(\omega)=\omega_{1}$. Indeed, since $\operatorname{dim}\left(\mathcal{H}_{G}^{1}(M)\right)=\operatorname{dim}\left(\mathcal{H}_{G}^{1}\left(M_{1}\right)\right)=k$ and $\boldsymbol{\pi}_{T}^{*}: \mathcal{H}_{G}^{1}(M) \rightarrow \mathcal{H}_{G}^{1}\left(M_{1}\right)$ is injective linear map, it must be an isomorphism.

Now using (4.19), we observe that up to the addition of a scalar multiple of $\Phi_{0}$, we have

$$
g_{1}=\frac{\boldsymbol{\pi}_{T}^{*} g}{\left|G_{T}\right|^{1 / 2}}
$$

where $g=g_{\omega}$ is defined in (2.4). Therefore,

$$
\begin{align*}
\mathcal{I}_{1}\left(\omega_{1}\right) & =8 \pi^{2}\left|G_{T}\right| \int_{M}|\omega|^{2} \frac{\phi_{0}^{2}}{\left|G_{T}\right|}+8 \pi\left|G_{T}\right| \int_{M} \frac{\phi_{0}}{\left|G_{T}\right|^{1 / 2}} \omega \cdot \nabla\left(\frac{g}{\left|G_{T}\right|^{1 / 2}}\right) \\
& =8 \pi^{2} \int_{M}|\omega|^{2} \phi_{0}^{2}+8 \pi \int_{M} \phi_{0} \omega \cdot \nabla g=\mathcal{I}(\omega) \tag{4.20}
\end{align*}
$$

Since the deck transformation group of $\hat{M}$ as a cover of $M_{1}$ is torsion free, we can apply Theorem 2.1 to $M_{1}$. Thus, we have

$$
\begin{equation*}
\lim _{t \rightarrow \infty}\left(t^{k / 2} e^{\Lambda_{0} t} \hat{H}(t, x, y)-C_{\mathcal{I}_{1}}(x, y) \exp \left(-\frac{2 \pi^{2} d_{\mathcal{I}_{1}}^{2}(x, y)}{t}\right)\right) \tag{4.21}
\end{equation*}
$$

uniformly on $\hat{M}$. Now using (4.19) and (4.20), we see that

$$
d_{\mathcal{I}_{1}}=d_{\mathcal{I}}, \quad C_{\mathcal{I}_{1}}(x, y)=\frac{1}{\left|G_{T}\right|} C_{\mathcal{I}}(x, y)
$$

and hence the proof is complete.
Remark 4.6. Although we assume that $G$ has positive rank $k$, Theorem 2.1 holds true when $k=0$. In this case, $\hat{M}$ is a finite cover of $M$ and is thus compact. The result follows from the standard heat kernel expansion together with the relation (4.19). Note that in this case we have $\mathcal{C}_{\mathcal{I}}(x, y)=\phi_{0}(\boldsymbol{\pi}(x)) \phi_{0}(\boldsymbol{\pi}(y))$ and $d_{\mathcal{I}}(x, y)=0$.

The rest of this section is devoted to the proofs of the two key Lemmas 4.4 and 4.5 respectively.
4.3. Minimizing the principal eigenvalue (proof of Lemma 4.4). Our aim in this subsection is to prove Lemma 4.4, which asserts that the function $\chi \mapsto \lambda_{\chi, 0}$ attains a unique global minimum at $\chi=1$. The Neumann boundary case is conceptually simpler and we first provide an independent proof for this case. The full proof of Lemma 4.4 under mixed Dirichlet and Neumann boundary conditions will be given later.

Proof of Lemma 4.4 under Neumann boundary conditions. In this case we know that $\lambda_{0}=\lambda_{\mathbf{1}, 0}=0$, and the corresponding eigenfunction $s_{\mathbf{1}, 0}$ is constant. Therefore, to prove the lemma, it suffices to show that $\lambda_{\chi, 0}>0$ for all $\chi \neq \mathbf{1}$.

To see this, given $\chi \in \mathcal{G}$, let $s=s_{\chi, 0} \in \mathcal{D}_{\chi}$ be the principal eigenfunction of $-\Delta_{\chi}$, and $\lambda=\lambda_{\chi, 0}$ be the principal eigenvalue. We claim that for any fundamental domain $U \subseteq \hat{M}$, the eigenvalue $\lambda$ satisfies

$$
\begin{equation*}
\lambda \int_{U}|s|^{2} d x=\int_{U}|\nabla s|^{2} d x \tag{4.22}
\end{equation*}
$$

Once (4.22) is established, it is immediate that $\lambda>0$ when $\chi \neq 1$. Indeed, if $\chi \neq \mathbf{1}$, $s(g(x))=\chi(g) s(x)$ forces the function $s$ to be non-constant, and now equation (4.22) forces $\lambda>0$.

To prove (4.22) observe

$$
\begin{equation*}
\lambda \int_{U}|s|^{2}=-\int_{U} \bar{s} \Delta_{\chi} s=\int_{U}|\nabla s|^{2}-\int_{\partial U} \bar{s} \partial_{\nu} s \tag{4.23}
\end{equation*}
$$

Here, $\partial_{\nu} s=\nu \cdot \nabla s$ is the outward pointing normal derivative on $\partial U$. We will show that the twisting condition (4.1) ensures that the boundary integral above vanishes.

Decompose $\partial U$ as

$$
\partial U=\Gamma_{1} \cup \Gamma_{2}, \quad \text { where } \Gamma_{1} \stackrel{\text { def }}{=} \partial U \cap \partial \hat{M}, \quad \text { and } \Gamma_{2} \stackrel{\text { def }}{=} \partial U-\Gamma_{1}
$$

Note $\Gamma_{1}$ is the portion of $\partial U$ contained in $\partial \hat{M}$, and $\Gamma_{2}$ is the portion of $\partial U$ that is common to neighboring fundamental domains. Clearly, the Neumann boundary condition (4.24) implies

$$
\int_{\Gamma_{1}} \bar{s} \partial_{\nu} s=0 .
$$

For the integral over $\Gamma_{2}$, let $\left(e_{1}, \ldots, e_{k}\right)$ be a basis of $G$ and note that $\Gamma_{2}$ can be expressed as the disjoint union

$$
\Gamma_{2}=\bigcup_{j=1}^{k}\left(\Gamma_{2, j}^{+} \cup \Gamma_{2, j}^{-}\right)
$$

where the $\Gamma_{2, j}^{ \pm}$are chosen so that $\Gamma_{2, j}^{+}=e_{j}\left(\Gamma_{2, j}^{-}\right)$. Using the twisting condition (4.1) and the fact that the action of $e_{j}$ reverses the direction of the unit normal on $\Gamma_{2, j}^{-}$, we see

$$
\begin{aligned}
\int_{\Gamma_{2, j}^{+}} \overline{s(x)} \partial_{\nu} s(x) d x & =-\int_{\Gamma_{2, j}^{-}} \overline{s\left(e_{j}(y)\right)} \partial_{\nu} s\left(e_{j}(y)\right) d y \\
& =-\int_{\Gamma_{2, j}^{-}} \overline{\chi\left(e_{j}\right)} \chi\left(e_{j}\right) \overline{s(y)}\left(\partial_{\nu} s(y)\right) d y \\
& =-\int_{\Gamma_{2, j}^{-}} \overline{s(y)} \partial_{\nu} s(y) d y
\end{aligned}
$$

Consequently,

$$
\int_{\Gamma_{2}} \bar{s} \partial_{\nu} s=\sum_{j=1}^{k}\left(\int_{\Gamma_{2, j}^{+}}+\int_{\Gamma_{2, j}^{-}}\right) \bar{s} \partial_{\nu} s=0
$$

and hence the boundary integral in (4.23) vanishes. Thus (4.22) holds, and the proof is complete.

In the general case when $\partial_{D} M \neq \emptyset, \lambda_{\chi, 0}>0$ for every $\chi \in \mathcal{G}$, and all eigenfunctions are non-constant. This causes the previous argument to break down and the proof involves a different idea. Before beginning the proof, we first make use of a canonical section to transfer the problem to the linear space $\mathcal{H}_{G}^{1}$.

Let $\Omega$ be the space of $\mathbb{C}$-valued smooth functions $f: M \rightarrow \mathbb{C}$ such that $f=0$ on $\partial_{D} M$ and $\langle\nabla f, \nu\rangle=0$ on $\partial_{N} M$. Let $\hat{f}=f \circ \pi: \hat{M} \rightarrow \mathbb{C}$. Now given $\omega \in \mathcal{H}_{G}^{1}$, let $\sigma_{\omega}$ (defined in (4.11)) be the canonical section and $\chi_{\omega} \in \mathcal{G}$ be the exponential as defined in (4.7). Notice that the function $\sigma_{\omega} \hat{f} \in \mathcal{D}_{\chi_{\omega}}$ is a section on $E_{\chi_{\omega}}$. Clearly $\sigma_{\omega} \hat{f}=0$ on $\partial_{D} \hat{M}$. Moreover, since $\omega \cdot \nu=0$ on $\partial M$ we have

$$
\begin{equation*}
\nu \cdot \nabla \sigma_{\omega}=0 \quad \text { on } \partial \hat{M} \tag{4.24}
\end{equation*}
$$

and hence $\nu \cdot \nabla\left(\sigma_{\omega} \hat{f}\right)=0$ on $\partial_{N} \hat{M}$. Thus $\sigma_{\omega} \hat{f} \in \mathcal{D}_{\chi_{\omega}}$, where $\mathcal{D}_{\chi_{\omega}}$ is defined in equation (4.2), and the map $f \mapsto \hat{f} \sigma_{\omega}$ defines a unitary isomorphism between $\Omega \subseteq L^{2}(M)$ and $\mathcal{D}_{\chi_{\omega}} \subseteq L^{2}\left(E_{\chi_{\omega}}\right)$ respecting the imposed boundary conditions.

Now, since $\omega$ and $\hat{\omega} \stackrel{\text { def }}{=} \boldsymbol{\pi}^{*}(\omega)$ are both harmonic, by direct calculation one finds that

$$
\Delta_{\chi_{\omega}}\left(\hat{f} \sigma_{\omega}\right)=\left(\left(H_{\omega} f\right) \circ \boldsymbol{\pi}\right) \sigma_{\omega}
$$

where $H_{\omega}$ is the self-adjoint operator on $\Omega \subseteq L^{2}(M)$ defined by

$$
\begin{equation*}
H_{\omega} f \stackrel{\text { def }}{=} \Delta f+4 \pi i \omega \cdot \nabla f-4 \pi^{2}|\omega|^{2} f \tag{4.25}
\end{equation*}
$$

Here we used the Riemannian metric to identify the 1-form $\omega$ with a vector field.
The above shows that $\Delta_{\chi_{\omega}}$ is unitarily equivalent to $H_{\omega}$. In particular, eigenvalues of $-H_{\omega}$, denoted by $\mu_{\omega, j}$ are exactly $\lambda_{\chi_{\omega}, j}$, the eigenvalues of $-\Delta_{\chi_{\omega}}$. Moreover, the corresponding eigenfunctions, denoted by $\phi_{\omega, j}$, are given by

$$
\begin{equation*}
\phi_{\omega, j}=\frac{s_{\chi_{\omega}, j}}{\sigma_{\omega}}, \quad j \geqslant 0 \tag{4.26}
\end{equation*}
$$

Note that $\phi_{\omega, j}$ is a well-defined function on $M$ that satisfies Dirichlet boundary conditions on $\partial_{D} M$ and Neumann boundary conditions on $\partial_{N} M$.

We will now prove the general case of Lemma 4.4 by minimizing eigenvalues of the operator $-H_{\omega}$.

Proof of Lemma 4.4. Let $\omega \in \mathcal{H}_{G}^{1}$ and let $\chi_{\omega}=\exp (\omega) \in \mathcal{G}$ be the corresponding representation defined by (4.7). Let $\mu_{\omega}=\mu_{\omega, 0}=\lambda_{\chi_{\omega}, 0}$ and $\phi_{\omega}=\phi_{\omega, 0}$ where $\phi_{\omega, 0}$ is the principal eigenfunction of $-H_{\omega}$ as defined in (4.26) above. Using (4.25) we see

$$
\begin{gather*}
-\Delta \phi_{\omega}-4 \pi i \omega \cdot \nabla \phi_{\omega}+4 \pi^{2}|\omega|^{2} \phi_{\omega}=\mu_{\omega} \phi_{\omega}  \tag{4.27}\\
-\Delta \phi_{0}=\mu_{0} \phi_{0} \tag{4.28}
\end{gather*}
$$

with Dirichlet boundary conditions on $\partial_{D} \hat{M}$ and Neumann boundary conditions on $\partial_{N} \hat{M}$. Here $\mu_{0}$ and $\phi_{0}$ denote the principal eigenvalue and eigenfunction respectively when $\omega \equiv 0$. Note that when $\omega \in \mathcal{H}_{\mathbb{Z}}^{1}$, the corresponding representation $\chi_{\omega}$ is the trivial representation 1. We will show that $\mu_{\omega}$ above achieves a global minimum precisely when $\omega \in \mathcal{H}_{\mathbb{Z}}^{1}$ and $\chi_{\omega}=\mathbf{1}$.

Now let $\varepsilon>0$ and write

$$
\overline{\phi_{\omega}}=\left(\phi_{0}+\varepsilon\right) f \quad \text { where } f \stackrel{\text { def }}{=} \frac{\overline{\phi_{\omega}}}{\phi_{0}+\varepsilon} .
$$

We now multiply both sides of (4.27) by $\overline{\phi_{\omega}}$ and integrate over $M$. For the first term on the left hand side, we have

$$
\begin{aligned}
-\int_{M}\left(\Delta \phi_{\omega}\right)\left(\phi_{0}+\varepsilon\right) f= & \int_{M} \nabla \phi_{\omega} \cdot\left(\left(\phi_{0}+\varepsilon\right) \nabla f+f \nabla \phi_{0}\right)+\int_{\partial M} B_{1} \\
= & \int_{M}\left(\phi_{0}+\varepsilon\right) \nabla \phi_{\omega} \cdot \nabla f \\
& \quad-\int_{M} \phi_{\omega}\left(\nabla f \cdot \nabla \phi_{0}+f \Delta \phi_{0}\right)+\int_{\partial M} B_{2}+\int_{\partial M} B_{1} \\
= & \int_{M}\left(\left(\phi_{0}+\varepsilon\right) \nabla \phi_{\omega}-\phi_{\omega} \nabla \phi_{0}\right) \cdot \nabla f \\
& \quad+\mu_{0} \int_{M} f \phi_{0} \phi_{\omega}+\int_{\partial M} B_{2}+\int_{\partial M} B_{1}
\end{aligned}
$$

where the boundary terms $B_{1}, B_{2}$ are given by

$$
B_{1} \stackrel{\text { def }}{=}-\left(\phi_{0}+\varepsilon\right) f \partial_{\nu} \phi_{\omega}, \quad B_{2} \stackrel{\text { def }}{=} \phi_{\omega} f \partial_{\nu} \phi_{0}
$$

We clarify that even though the functions above are $\mathbb{C}$-valued, the notation $\nabla \phi_{\omega} \cdot \nabla f$ denotes $\sum_{i} \partial_{i} \phi_{\omega} \partial_{i} f$, and not the complex inner product. Similarly, for
the second term on the left hand side of (4.27), using the fact that $\omega$ is harmonic, we have

$$
\begin{aligned}
&-4 \pi i \int_{M}\left(\phi_{0}+\varepsilon\right) f \omega \cdot \nabla \phi_{\omega} \\
&=- 2 \pi i \int_{M}\left(\phi_{0}+\varepsilon\right) f \nabla \phi_{\omega} \cdot \omega \\
&+2 \pi i \int_{M} \phi_{\omega}\left(\left(\phi_{0}+\varepsilon\right) \nabla f+f \nabla \phi_{0}\right) \cdot \omega+\int_{\partial M} B_{3} \\
&=- 2 \pi i \int_{M}\left(\left(\phi_{0}+\varepsilon\right) \nabla \phi_{\omega}-\phi_{\omega} \nabla \phi_{0}\right) \cdot(f \omega) \\
& \quad+2 \pi i \int_{M}\left(\phi_{0}+\varepsilon\right) \phi_{\omega} \nabla f \cdot \omega+\int_{\partial M} B_{3}
\end{aligned}
$$

where the boundary term $B_{3}$ is given by

$$
B_{3} \stackrel{\text { def }}{=}-2 \pi i\left(\phi_{0}+\varepsilon\right) \phi_{\omega} f \omega \cdot \nu
$$

Combining the above, we have

$$
\begin{align*}
\mu_{\omega}-\mu_{0} \int_{M} f \phi_{0} \phi_{\omega}= & \int_{M}\left(\left(\phi_{0}+\varepsilon\right) \nabla \phi_{\omega}-\phi_{\omega} \nabla \phi_{0}\right) \cdot(\nabla f-2 \pi i f \omega)  \tag{4.29}\\
& +\int_{M}\left(\phi_{0}+\varepsilon\right) \phi_{\omega}\left(4 \pi^{2}|\omega|^{2} f+2 \pi i \nabla f \cdot \omega\right)+\int_{\partial M} B_{0}
\end{align*}
$$

where

$$
B_{0} \stackrel{\text { def }}{=} B_{1}+B_{2}+B_{3}=-\left(\phi_{0}+\varepsilon\right) f \partial_{\nu} \phi_{\omega}+\phi_{\omega} f \partial_{\nu} \phi_{0}-2 \pi i\left(\phi_{0}+\varepsilon\right) \phi_{\omega} f \omega \cdot \nu .
$$

The boundary conditions imposed ensure that $B_{0}=0$ on both $\partial_{D} M$ and $\partial_{N} M$.
On the other hand, since $f=\overline{\phi_{\omega}} /\left(\phi_{0}+\varepsilon\right)$, we have

$$
\nabla f=\frac{\left(\phi_{0}+\varepsilon\right) \nabla \overline{\phi_{\omega}}-\overline{\phi_{\omega}} \nabla \phi_{0}}{\left(\phi_{0}+\varepsilon\right)^{2}}
$$

Substituting this into the right hand side of (4.29), we obtain a perfect square:

$$
\begin{equation*}
\mu_{\omega}-\mu_{0} \int_{M} f \phi_{0} \phi_{\omega}=\int_{M}\left|2 \pi \phi_{\omega} \omega-\frac{i\left(\left(\phi_{0}+\varepsilon\right) \nabla \phi_{\omega}-\phi_{\omega} \nabla \phi_{0}\right)}{\phi_{0}+\varepsilon}\right|^{2} \tag{4.30}
\end{equation*}
$$

In particular,

$$
\mu_{\omega}-\mu_{0} \int_{M} f \phi_{0} \phi_{\omega}=\mu_{\omega}-\mu_{0} \int_{M} \frac{\phi_{0}}{\phi_{0}+\varepsilon}\left|\phi_{\omega}\right|^{2} \geqslant 0
$$

Sending $\varepsilon \rightarrow 0$, we obtain $\mu_{\omega} \geqslant \mu_{0}$, and so the function $\mathcal{G} \ni \chi \mapsto \lambda_{\chi, 0}$ attains global minimum at $\chi=1$.

To see that $\chi=\mathbf{1}$ is the unique global minimum point, suppose that $\lambda_{\chi}=\lambda_{0}$ for some $\chi \in \mathcal{G}$. Writing $\chi=\chi_{\omega}$ for some $\omega \in \mathcal{H}_{G}^{1}$, this means $\mu_{\omega}=\mu_{0}$. Fatou's lemma and (4.30) imply

$$
\begin{aligned}
\int_{M} \mid & 2 \pi \phi_{\omega} \omega-\left.\frac{i\left(\phi_{0} \nabla \phi_{\omega}-\phi_{\omega} \nabla \phi_{0}\right)}{\phi_{0}}\right|^{2} \\
& \leqslant \liminf _{\varepsilon \rightarrow 0} \int_{M}\left|2 \pi \phi_{\omega} \omega-\frac{i\left(\left(\phi_{0}+\varepsilon\right) \nabla \phi_{\omega}-\phi_{\omega} \nabla \phi_{0}\right)}{\phi_{0}+\varepsilon}\right|^{2} \\
& =\mu_{\omega}-\mu_{0}=0
\end{aligned}
$$

by assumption. Hence

$$
\begin{equation*}
2 \pi \phi_{\omega} \omega-\frac{i\left(\phi_{0} \nabla \phi_{\omega}-\phi_{\omega} \nabla \phi_{0}\right)}{\phi_{0}}=0 \quad \text { in } M \tag{4.31}
\end{equation*}
$$

Since $\phi_{\omega}=s_{\chi, 0} / \sigma_{\omega}$, we compute

$$
\nabla \phi_{\omega}=\frac{\sigma_{\omega} \nabla s_{\chi, 0}-2 \pi i \sigma_{\omega} s_{\chi, 0} \omega}{\sigma_{\omega}^{2}}
$$

Substituting this into (4.31), we see

$$
\phi_{0} \nabla s_{\chi, 0}=s_{\chi, 0} \nabla \phi_{0}
$$

which implies that

$$
\nabla\left(\frac{s_{\chi, 0}}{\phi_{0}}\right)=0
$$

Therefore, $s_{\chi, 0}=c \phi_{0}$ for some non-zero constant $c$. However, the twisting conditions (4.1) for $\phi_{0}$ and $s_{\chi, 0}$ require

$$
\phi_{0}(g(x))=\phi_{0}(x) \quad \text { and } \quad s_{\chi, 0}(g(x))=\chi(g) s_{\chi, 0}(x),
$$

for every $g \in \mathcal{G}$. This is only possible if $\chi(g)=1$ for all $g \in \mathcal{G}$, showing $\chi$ is the trivial representation 1.
4.4. Positivity of the Hessian (proof of Lemma 4.5). In this subsection we prove Lemma 4.5. The main difficulty is proving positivity, which we postpone to the end.

Proof of Lemma 4.5. Given $\omega \in \mathcal{H}_{G}^{1}$, define

$$
\varphi_{t}=\phi_{t \omega} \quad \text { and } \quad h_{t}=\mu_{t \omega}
$$

where $\phi_{t \omega}=\phi_{t \omega, 0}$ is the principal eigenfunction of $-H_{t \omega}$ (equation (4.26)) and $\mu_{t \omega}$ is the corresponding principal eigenvalue. We claim that

$$
\begin{equation*}
h_{0}^{\prime}=0, \quad h_{0}^{\prime \prime}=\mathcal{I}(\omega) \quad \text { and } \quad \operatorname{Re}\left(\varphi_{0}^{\prime}\right)=0 \tag{4.32}
\end{equation*}
$$

where $h^{\prime}, \varphi^{\prime}$ denote the derivatives of $h$ and $\varphi$ respectively with respect to $t$. This will immediately imply that at $\omega=0$ the quadratic form induced by the Hessian of the map $\omega \mapsto \mu_{\omega}$ is precisely $\mathcal{I}(\omega)$, hence proving (4.8) in the lemma.

To establish (4.32), we first note that (4.27) implies

$$
\begin{equation*}
-\Delta \varphi_{t}-4 \pi i t \omega \cdot \nabla \varphi_{t}+4 \pi^{2} t^{2}|\omega|^{2} \varphi_{t}=h_{t} \varphi_{t} \tag{4.33}
\end{equation*}
$$

Conjugating both sides of (4.33) gives

$$
\begin{equation*}
-\Delta \overline{\varphi_{t}}-4 \pi i(-t) \omega \cdot \nabla \overline{\varphi_{t}}+4 \pi^{2}(-t)^{2}|\omega|^{2} \overline{\varphi_{t}}=h_{t} \overline{\varphi_{t}} \tag{4.34}
\end{equation*}
$$

In other words, $\overline{\varphi_{t}}$ is an eigenfunction of $-H_{-t \omega}$ with eigenvalue $h_{t}$. Since $h_{t}=\mu_{t \omega}$ is the principal eigenvalue, this implies $h_{-t} \leqslant h_{t}$. By symmetry, we see that $h_{-t}=h_{t}$, and hence $h_{0}^{\prime}=0$.

To see that $\varphi_{0}^{\prime}$ is purely imaginary, recall $h_{t}$ is a simple eigenvalue of $-H_{t \omega}$ when $t$ is small. Thus

$$
\begin{equation*}
\overline{\varphi_{t}}=\zeta_{t} \varphi_{-t} \tag{4.35}
\end{equation*}
$$

for some $S^{1}$ valued function $\zeta_{t}$, defined for small $t$. Changing $t$ to $-t$, we get

$$
\overline{\varphi_{-t}}=\zeta_{-t} \varphi_{t}=\zeta_{-t} \overline{\zeta_{t}} \overline{\varphi_{-t}}
$$

Therefore, $\zeta_{-t} \overline{\zeta_{t}}=1$, which implies that $\zeta_{-t}=\zeta_{t}$. In particular, $\zeta_{0}^{\prime}=0$. Differentiating (4.35) and using the fact that $\zeta_{0}=1$, we get

$$
\overline{\varphi_{0}^{\prime}}=-\varphi_{0}^{\prime},
$$

showing that $\varphi_{0}^{\prime}$ is purely imaginary as claimed.
To compute $h_{0}^{\prime \prime}$, we differentiate (4.33) twice with respect to $t$. At $t=0$ this gives

$$
\begin{equation*}
-\Delta \varphi_{0}^{\prime}-4 \pi i \omega \cdot \nabla \varphi_{0}=\lambda_{0} \varphi_{0}^{\prime} \tag{4.36}
\end{equation*}
$$

and

$$
\begin{equation*}
-\Delta \varphi_{0}^{\prime \prime}-8 \pi i \omega \cdot \nabla \varphi_{0}^{\prime}+8 \pi^{2}|\omega|^{2} \phi_{0}=h_{0}^{\prime \prime} \phi_{0}+\lambda_{0} \varphi_{0}^{\prime \prime} \tag{4.37}
\end{equation*}
$$

since $\varphi_{0}=\phi_{0}$. Multiplying both sides of (4.37) by $\phi_{0}$ and integrating over $M$ gives

$$
\begin{equation*}
h_{0}^{\prime \prime}=\int_{M}\left(8 \pi^{2}|\omega|^{2} \phi_{0}^{2}-8 \pi i \phi_{0} \omega \cdot \nabla \varphi_{0}^{\prime}\right) \tag{4.38}
\end{equation*}
$$

Recalling that $\varphi_{0}^{\prime}$ is purely imaginary, we let $g_{\omega}$ be the real valued function defined by $g_{\omega}=-i \varphi_{0}^{\prime}$. Now equation (4.36) shows that $g_{\omega}$ satisfies (2.4). Moreover since $\varphi_{0}=0$ on $\partial_{D} M$ and $\nu \cdot \nabla \varphi_{0}=0$ on $\partial_{N} M$, the function $g_{\omega}$ satisfies the boundary conditions (2.5). Therefore, (4.38) reduces to (2.3), showing that $h_{0}^{\prime \prime}=\mathcal{I}(\omega)$ as claimed.

Finally, we show that $\omega \mapsto \mathcal{I}(\omega)$ defined by (2.3) is a well defined positive definite quadratic form on $\mathcal{H}_{G}^{1}$. To see that $\mathcal{I}$ is well defined, we first note that in order for (2.4) to have a solution, we need to verify the solvability condition

$$
\int_{M} \phi_{0}\left(4 \pi \omega \cdot \nabla \phi_{0}\right)=0
$$

This is easily verified as

$$
\begin{equation*}
\int_{M} \phi_{0} \omega \cdot \nabla \phi_{0}=\frac{1}{2} \int_{M} \omega \cdot \nabla \phi_{0}^{2}=0 \tag{4.39}
\end{equation*}
$$

Hence $g_{\omega}$ is uniquely defined up to the addition of scalar multiples of $\phi_{0}$ (the kernel of $\Delta+\lambda_{0}$ ). Now, using (4.39) again, we see that replacing $g_{\omega}$ with $g_{\omega}+\alpha \phi_{0}$ does not change the value of $\mathcal{I}(\omega)$. Therefore, $\mathcal{I}(\omega)$ is a well defined function. The fact that $\mathcal{I}$ defines a quadratic form follows from (2.3) and the fact that

$$
g_{\tau+\omega}=g_{\tau}+g_{\omega} \quad\left(\bmod \phi_{0}\right)
$$

It remains to show that $\mathcal{I}$ is positive definite. Note that, in view of Lemma 4.4, we already know that $\mathcal{I}$ induces a positive semi-definite quadratic form on $\mathcal{H}_{G}^{1}$.

For the convenience of notation, let $g=g_{\omega}=-i \varphi_{0}^{\prime}$ as above. As before, we write

$$
g=\left(\phi_{0}+\varepsilon\right) f_{\varepsilon}, \quad \text { where } f_{\varepsilon} \stackrel{\text { def }}{=} \frac{g}{\phi_{0}+\varepsilon}
$$

and we will multiply both sides of (2.4) by $g$ and integrate. In preparation for this we compute

$$
\begin{aligned}
-\int_{M}\left(\phi_{0}+\varepsilon\right) f_{\varepsilon} \Delta g= & \int_{M} \nabla g \cdot\left(f_{\varepsilon} \nabla \phi_{0}+\left(\phi_{0}+\varepsilon\right) \nabla f_{\varepsilon}\right) \\
& =\lambda_{0} \int_{M} \phi_{0} f_{\varepsilon} g-\int_{M} g \nabla f_{\varepsilon} \cdot \nabla \phi_{0}+\int_{M}\left(\phi_{0}+\varepsilon\right) \nabla f_{\varepsilon} \cdot \nabla g
\end{aligned}
$$

and

$$
\begin{aligned}
4 \pi \int_{M}\left(\phi_{0}+\varepsilon\right) f_{\varepsilon} \omega \cdot \nabla\left(\phi_{0}+\varepsilon\right) & =2 \pi \int_{M} f_{\varepsilon} \omega \cdot \nabla\left(\phi_{0}+\varepsilon\right)^{2} \\
& =-2 \pi \int_{M}\left(\phi_{0}+\varepsilon\right)^{2} \nabla f_{\varepsilon} \cdot \omega
\end{aligned}
$$

We remark that when integrating by parts above, the boundary terms that arise all vanish because of the boundary conditions imposed. Thus, multiplying (2.4) by $\left(\phi_{0}+\varepsilon\right) f_{\varepsilon}$ and integrating gives

$$
\begin{align*}
\lambda_{0} \int_{M} g^{2}\left(1-\frac{\phi_{0}}{\phi_{0}+\varepsilon}\right)= & \int_{M}\left(\phi_{0}+\varepsilon\right) \nabla f_{\varepsilon} \cdot \nabla g-\int_{M} g \nabla f_{\varepsilon} \cdot \nabla\left(\phi_{0}+\varepsilon\right) \\
& +2 \pi \int_{M}\left(\phi_{0}+\varepsilon\right)^{2} \nabla f_{\varepsilon} \cdot \omega \tag{4.40}
\end{align*}
$$

Writing $\tau \stackrel{\text { def }}{=} 2 \pi \omega$ and adding the integral

$$
J_{\varepsilon} \stackrel{\text { def }}{=} \int_{M}\left(\phi_{0}+\varepsilon\right) \tau \cdot \nabla g-\int_{M} g \tau \cdot \nabla\left(\phi_{0}+\varepsilon\right)+\int_{M}\left(\phi_{0}+\varepsilon\right)^{2}|\tau|^{2}
$$

to both sides of (4.40), we obtain

$$
\begin{align*}
J_{\varepsilon}+\lambda_{0} \int_{M} g^{2} & \left(1-\frac{\phi_{0}}{\phi_{0}+\varepsilon}\right)=\int_{M}\left(\phi_{0}+\varepsilon\right)\left(\nabla f_{\varepsilon}+\tau\right) \cdot \nabla g  \tag{4.41}\\
& -\int_{M} g\left(\nabla f_{\varepsilon}+\tau\right) \cdot \nabla\left(\phi_{0}+\varepsilon\right)+\int_{M}\left(\phi_{0}+\varepsilon\right)^{2}\left(\nabla f_{\varepsilon}+\tau\right) \cdot \tau
\end{align*}
$$

Now, since $g=\left(\phi_{0}+\varepsilon\right) f_{\varepsilon}$, we compute

$$
\nabla g=f_{\varepsilon} \nabla\left(\phi_{0}+\varepsilon\right)+\left(\phi_{0}+\varepsilon\right) \nabla f_{\varepsilon}
$$

Substituting this into (4.41) gives

$$
\begin{equation*}
J_{\varepsilon}+\lambda_{0} \int_{M} g^{2}\left(1-\frac{\phi_{0}}{\phi_{0}+\varepsilon}\right)=\int_{M}\left(\phi_{0}+\varepsilon\right)^{2}\left|\nabla f_{\varepsilon}+\tau\right|^{2} \geqslant 0 \tag{4.42}
\end{equation*}
$$

Using (2.3) we see

$$
\begin{equation*}
\mathcal{I}(\omega)=8 \pi^{2} \int_{M}|\omega|^{2} \phi_{0}^{2}+4 \pi \int_{M} \phi_{0} \omega \cdot \nabla g-4 \pi \int_{M} g \omega \cdot \nabla \phi_{0} \tag{4.43}
\end{equation*}
$$

and hence it follows that

$$
\lim _{\varepsilon \rightarrow 0} J_{\varepsilon}=\frac{1}{2} \mathcal{I}(\omega)
$$

Also by the dominated convergence theorem, the second term on the left hand side of (4.42) goes to zero as $\varepsilon \rightarrow 0$. This shows $\mathcal{I}(\omega) \geqslant 0$.

It remains to show $\mathcal{I}(\omega)>0$ if $\omega \neq 0$. Note that if $\mathcal{I}(\omega)=0$, then Fatou's lemma and (4.42) imply

$$
\int_{M} \phi_{0}^{2}|\nabla f+\tau|^{2} \leqslant \liminf _{\varepsilon \rightarrow 0}\left(J_{\varepsilon}+\lambda_{0} \int_{M} g^{2}\left(1-\frac{\phi_{0}}{\phi_{0}+\varepsilon}\right)\right)=0
$$

where $f \stackrel{\text { def }}{=} g / \phi_{0}$. Therefore $\nabla f+\tau=0$ in $M$ and hence $\omega=-\nabla f /(2 \pi)$. Since $\omega \in \mathcal{H}_{G}^{1} \subseteq \mathcal{H}^{1}$, this forces

$$
\Delta f=0 \quad \text { in } M, \quad \text { and } \quad \nu \cdot \nabla f=0 \quad \text { on } \partial M
$$

Consequently $\nabla f=0$, which in turn implies $\omega=0$. This completes the proof of the positivity of $\mathcal{I}$.

## 5. Proof of the winding number asymptotics (Theorem 3.2).

In this section, we study the long time behaviour of the abelianized winding number of reflected Brownian motion on a manifold $M$. We begin by using Theorem 2.1 to prove Theorem 3.2 (Section 5.1). Next, in Section 5.2 we discuss the connection of our results with the work by Toby and Werner [TW95]. Finally, in Section 5.3, modulo certain amount of technicalities which need to be verified, we propose a (sketched) independent probabilistic proof of Theorem 3.2.
5.1. Proof of Theorem 3.2. We obtain the long time behaviour of the abelianized winding of reflected Brownian motion in $M$ by applying Theorem 2.1 in this context. Let $\hat{M}$ be a covering space of $M$ with deck transformation group ${ }^{4} \pi_{1}(M)_{\mathrm{ab}}$. In view of the covering factorization (4.18), we may, without loss of generality, assume that $\operatorname{tor}\left(\pi_{1}(M)_{\mathrm{ab}}\right)=\{0\}$. Note that since the deck transformation group $G=\pi_{1}(M)_{\mathrm{ab}}$ by construction, we have $\mathcal{H}_{G}^{1}=\mathcal{H}^{1}$. Given $n \in \mathbb{Z}^{k}(k=\operatorname{rank}(\mathrm{G}))$, define $g_{n} \in G$ by

$$
g_{n} \stackrel{\text { def }}{=} \sum_{i=1}^{k} n_{i} \pi_{G}\left(\gamma_{i}\right), \quad \text { where } n=\left(n_{1}, \ldots, n_{k}\right) \in \mathbb{Z}^{k}
$$

where $\left\{\pi_{G}\left(\gamma_{1}\right), \ldots, \pi_{G}\left(\gamma_{k}\right)\right\}$ is the basis of $G$ chosen in Section 3. Clearly $n \mapsto g_{n}$ is an isomorphism between $G$ and $\mathbb{Z}^{k}$.

Lemma 5.1. For any $x, y \in \hat{M}$ and $n \in \mathbb{Z}^{k}$ we have

$$
d_{\mathcal{I}}\left(x, g_{n}(y)\right)^{2}=\left(A^{-1} n\right) \cdot n+O(|n|)
$$

where $A$ is the matrix $\left(a_{i, j}\right)$ defined by

$$
\begin{equation*}
a_{i, j} \stackrel{\text { def }}{=}\left\langle\omega_{i}, \omega_{j}\right\rangle_{\mathcal{I}}=\frac{8 \pi^{2}}{\operatorname{vol}(M)} \int_{M} \omega_{i} \cdot \omega_{j} \tag{5.1}
\end{equation*}
$$

Proof. Given $\omega \in \mathcal{H}^{1}$ we compute

$$
\begin{equation*}
\xi_{x, g_{n}(y)}(\omega)=\int_{x}^{y} \boldsymbol{\pi}^{*}(\omega)+\int_{y}^{g_{n}(y)} \boldsymbol{\pi}^{*}(\omega), \tag{5.2}
\end{equation*}
$$

where the integrals are taken along any smooth path in $\hat{M}$ connecting the endpoints. Note that the integrals are well defined, and the second one is independent of $y$. Therre, if for any $g \in G$ we define $\psi_{g}: \mathcal{H}^{1} \rightarrow \mathbb{R}$ by

$$
\psi_{g}(\omega)=\int_{y}^{g(y)} \pi^{*}(\omega)
$$

then (5.2) becomes

$$
\xi_{x, g_{n}(y)}(\omega)=\xi_{x, y}(\omega)+\psi_{g_{n}}(\omega) .
$$

It follows that

$$
d_{\mathcal{I}}\left(x, g_{n}(y)\right)^{2}=d_{\mathcal{I}}(x, y)^{2}+\sum_{i=1}^{k} n_{i}\left\langle\psi_{\pi_{G}\left(\gamma_{i}\right)}, \xi_{x, y}\right\rangle_{\mathcal{I}^{*}}+\sum_{i, j=1}^{k} n_{i} n_{i}\left\langle\pi_{G}\left(\gamma_{i}\right), \pi_{G}\left(\gamma_{j}\right)\right\rangle_{\mathcal{I}^{*}}
$$

Since $\left\{\omega_{1}, \ldots, \omega_{k}\right\}$ is the dual basis to $\left\{\pi_{G}\left(\gamma_{1}\right), \ldots, \pi_{G}\left(\gamma_{j}\right)\right\}$, we have

$$
\left\langle\pi_{G}\left(\gamma_{i}\right), \pi_{G}\left(\gamma_{j}\right)\right\rangle_{\mathcal{I}^{*}}=\left(A^{-1}\right)_{i, j}
$$

[^3]Therefore, the result follows. Note that the second equality of (5.1) follows from the fact that (2.10) holds under Neumann boundary conditions.

Now we prove Theorem 3.2.
Proof of Theorem 3.2. Recall in Section 3 we decomposed the universal cover $\bar{M}$ as the disjoint union of fundamental domains $\bar{U}_{g}$ indexed by $g \in \pi_{1}(M)$. Projecting these domains to the cover $\hat{M}$ we write $\hat{M}$ as the disjoint union of fundamental domains $\bar{U}_{g}$ indexed by $g \in G$. Let $\hat{W}$ be the lift of the trajectory of $W$ to $\hat{M}$, and observe that if $\hat{W}(t) \in \hat{U}_{g_{n}}$, then $\rho(t)=n$.

We use this to compute the characteristic function of $\rho(t) / \sqrt{t}$ as follows. Since the generator of $\hat{W}$ is $\frac{1}{2} \Delta$, its transition density is given by $\hat{H}(t / 2, \cdot, \cdot)$. Hence, for any $z \in \mathbb{R}^{k}$ we have

$$
\begin{aligned}
\boldsymbol{E}^{x}\left[\exp \left(\frac{i z \cdot \rho(t)}{t^{1 / 2}}\right)\right]=\sum_{n \in \mathbb{Z}^{k}} \exp \left(\frac{i z \cdot n}{t^{1 / 2}}\right) & \boldsymbol{P}^{x}\left(\hat{W}(t) \in \hat{U}_{g_{n}}\right) \\
& =\sum_{n \in \mathbb{Z}^{k}} \int_{\hat{U}_{g_{n}}} \hat{H}\left(\frac{t}{2}, x, y\right) \exp \left(\frac{i z \cdot n}{t^{1 / 2}}\right) d y
\end{aligned}
$$

By Theorem 2.1 and Remark 2.3, this means that uniformly in $x \in \hat{M}$ we have

$$
\begin{aligned}
\lim _{t \rightarrow \infty} & \boldsymbol{E}^{x}\left[\exp \left(\frac{i z \cdot \rho(t)}{t^{1 / 2}}\right)\right] \\
& =C_{\mathcal{I}} \lim _{t \rightarrow \infty} \sum_{n \in \mathbb{Z}^{k}} \int_{\hat{U}_{g_{n}}} \frac{2^{k / 2}}{t^{k / 2}} \exp \left(-\frac{4 \pi^{2} d_{\mathcal{I}}\left(x, g_{n}(y)\right)^{2}}{t}+\frac{i z \cdot n}{t^{1 / 2}}\right) d y \\
& =C_{\mathcal{I}} \lim _{t \rightarrow \infty} \sum_{n \in \mathbb{Z}^{k}} \frac{2^{k / 2}}{t^{k / 2}} \exp \left(-\frac{4 \pi^{2}\left(A^{-1} n\right) \cdot n}{t}+\frac{i z \cdot n}{t^{1 / 2}}\right)
\end{aligned}
$$

where the last equality followed from Lemma 5.1 above. Observe that the last term is the Riemann sum of a standard Gaussian integral. Therefore,

$$
\lim _{t \rightarrow \infty} \boldsymbol{E}^{x}\left[\exp \left(\frac{i z \cdot \rho(t)}{t^{1 / 2}}\right)\right]=2^{k / 2} C_{\mathcal{I}} \int_{\zeta \in \mathbb{R}^{k}} \exp \left(-4 \pi^{2}\left(A^{-1} \zeta\right) \cdot \zeta+i z \cdot \zeta\right) d \zeta
$$

This shows that as $t \rightarrow \infty, \rho(t) / \sqrt{t}$ converges to a normally distributed random variable with mean 0 and covariance matrix $A /\left(8 \pi^{2}\right)$. By (3.3) and (5.1) we see that $\Sigma=A /\left(8 \pi^{2}\right)$, which completes the proof of the second assertion in (3.1) of the theorem. The first assertion follows immediately from the second assertion and Chebychev's inequality.
5.2. Relation to the work of Toby and Werner. Toby and Werner [TW95] studied the long time behaviour of the winding of an obliquely reflected Brownian motion in bounded planar domains. In this case, we describe their result and relate it to Theorem 3.2.

Let $\Omega \subseteq \mathbb{R}^{2}$ be a bounded domain with $k$ holes $V_{1}, \cdots, V_{k}$ of positive volume. Let $W_{t}$ be a reflected Brownian motion in $\Omega$ with a reflecting vector field $u \in C^{1}(\partial \Omega)$ that is not necessarily tangential to $\partial \Omega$. Let $p_{1}, \cdots, p_{k}$ be $k$ distinct points in $\mathbb{R}^{2}$. For $1 \leqslant j \leqslant k$, define $\rho\left(t, p_{j}\right)$ to be the winding number of $W_{t}$ with respect to the point $p_{j}$.

Theorem 5.2 (Toby and Werner, 1995). There exist constants $a_{i}, b_{i}$, depending on the domain $\Omega$, such that

$$
\begin{equation*}
\frac{1}{t}\left(\rho\left(t, p_{1}\right), \cdots, \rho\left(t, p_{k}\right)\right) \xrightarrow[t \rightarrow \infty]{w}\left(a_{1} C_{1}+b_{1}, \cdots, a_{k} C_{k}+b_{k}\right) \tag{5.3}
\end{equation*}
$$

where $C_{1}, \ldots, C_{k}$ are standard Cauchy variables. Moreover, for any $j$ such that $p_{j} \notin \Omega, a_{j}$ must be equal to zero.

When $p_{j} \in \Omega$, the process $W$ can wind a large number of times around $p_{j}$ in a short period as it approaches $p_{j}$. This is why the heavy-tailed Cauchy distribution arises in Theorem 5.2, and the limiting process is non-degenerate precisely when each $p_{j} \in \Omega$. This is exactly the situation when Theorem 5.2 is sharp.

On the other hand, if $p_{j} \in V_{j}$, we have $a_{j}=0$ and (5.3) becomes a law of large numbers. In the case with normal reflection, Theorem 3.2 provides the central limit theorem for the fluctuation around the mean. Therefore, in this case our result is a refinement of Theorem 5.2.

It is not pointed out nor can be easily seen from [TW95] why the mean $b_{j}=0$ in the normal reflection case with $p_{j} \in V_{j}$. For completeness, we give a proof of this fact below.

Recall that (see for instance Stroock-Varadhan [SV71]) reflected Brownian motion has the semi-martingale representation

$$
\begin{equation*}
W_{t}=\beta_{t}+\int_{0}^{t} u\left(W_{s}\right) d L_{s} \tag{5.4}
\end{equation*}
$$

where $\beta_{t}$ is a two dimensional Brownian motion, $u$ is the reflecting vector field on $\partial \Omega$, and $L_{t}$ is a continuous increasing process which increases only when $W_{t} \in \partial \Omega$. We also know that the process $W_{t}$ has a unique invariant measure, which is denoted by $\mu$. From [TW95], the constants $b_{j}$ are given by

$$
\begin{equation*}
b_{j}=\frac{1}{2 \pi} \int_{p \in \Omega} \boldsymbol{E}^{p}\left[\int_{0}^{1} u_{j}\left(W_{s}\right) d L_{s}\right] d \mu(p) \tag{5.5}
\end{equation*}
$$

where $u_{j}: \partial \Omega \rightarrow \mathbb{R}$ is defined by

$$
u_{j}(p) \stackrel{\text { def }}{=} \frac{u(p) \cdot\left(p-p_{j}\right)^{\perp}}{\left|p-p_{j}\right|}
$$

and $q^{\perp} \stackrel{\text { def }}{=}\left(-q_{2}, q_{1}\right)$ for $q=\left(q_{1}, q_{2}\right) \in \mathbb{R}^{2}$.
Proposition 5.3. Let $W_{t}$ be a normally reflected Brownian motion in $\Omega$, and $p_{j} \in V_{j}$ for each $j$. Then $b_{j}=0$ for all $j$, and consequently

$$
\lim _{t \rightarrow \infty} \frac{\rho\left(t, p_{j}\right)}{t} \xrightarrow{p} 0
$$

Proof. Fix $1 \leqslant j \leqslant k$. Let $w(t, p)$ be the solution to the following initial-boundary value problem:

$$
\left\{\begin{array}{cl}
\partial_{t} w-\frac{1}{2} \Delta w=0 & \text { in }(0, \infty) \times \Omega  \tag{5.6}\\
\nu \cdot \nabla w=-u_{j} & \text { on }(0, \infty) \times \partial \Omega \\
\lim _{t \rightarrow 0} w(t, \cdot)=0 & \text { in } \Omega
\end{array}\right.
$$

where $\nu$ is the outward pointing unit normal on the boundary. By applying Itô's formula to the process $[0, t-\varepsilon] \ni s \mapsto w\left(t-s, W_{s}\right)$ and using the semi-martingale representation (5.4) of $W_{t}$, we get

$$
\begin{aligned}
w(t, p)-\boldsymbol{E}^{p}\left[w\left(\varepsilon, W_{t-\varepsilon}\right)\right] & =-\boldsymbol{E}^{p}\left[\int_{0}^{t-\varepsilon} \nu \cdot \nabla w\left(W_{s}, t-s\right) d L_{s}\right] \\
& =\boldsymbol{E}^{p}\left[\int_{0}^{t-\varepsilon} u_{j}\left(W_{s}\right) d L_{s}\right]
\end{aligned}
$$

where in the last identity we have used the fact that $d L_{s}$ is carried by the set $\left\{s \geqslant 0: W_{s} \in \partial \Omega\right\}$. Since $\boldsymbol{P}\left(B_{t} \in \partial U\right)=0$, sending $\varepsilon \rightarrow 0$ and using the dominated convergence theorem gives

$$
w(t, p)=\boldsymbol{E}^{p}\left[\int_{0}^{t} u_{j}\left(W_{s}\right) d L_{s}\right]
$$

On the other hand, according to Harrison, Landau and Shepp [HLS85], Theorem 2.8 , the invariant measure $\mu$ of $W_{t}$ is the unique probability measure on the closure $\bar{\Omega}$ of $\Omega$ that $\mu(\partial \Omega)=0$ and

$$
\int_{\Omega} \Delta f(p) d \mu(p) \leqslant 0 \quad \text { for all } f \in C^{2}(\bar{\Omega}) \text { with } \nu \cdot \nabla f \leqslant 0 \text { on } \partial \Omega
$$

Stokes' theorem now implies $\mu$ is the normalized Lebesgue measure on $\Omega$. Consequently,

$$
b_{j}=\frac{1}{2 \pi \operatorname{vol}(\Omega)} \int_{\Omega} \boldsymbol{E}^{p}\left[\int_{0}^{1} u_{j}\left(W_{s}\right) d L_{s}\right] d p=\frac{1}{2 \pi \operatorname{vol}(\Omega)} \int_{\Omega} w(1, p) d p
$$

Integrating (5.6) over $\Omega$ and using the boundary conditions yields

$$
\begin{aligned}
0 & =\partial_{t} \int_{\Omega} w d p-\int_{\Omega} \Delta w d p \\
& =\partial_{t} \int_{\Omega} w d p+\int_{\partial \Omega} u_{j}(p) d p \\
& =\partial_{t} \int_{\Omega} w d p-\int_{\partial \Omega} \nu \cdot \frac{\left(p-p_{j}\right)^{\perp}}{\left|p-p_{j}\right|} d p
\end{aligned}
$$

Since when $p_{j} \in V_{j}$ the vector field $p \mapsto\left(p-p_{j}\right)^{\perp} /\left|p-p_{j}\right|$ is a divergence free vector field on $\bar{\Omega}$, the last integral above above vanishes. Thus

$$
\partial_{t} \int_{\Omega} w d p=0
$$

and since $w=0$ when $t=0, w=0$ for all $t \geqslant 0$, and hence $b_{j}=0$.
5.3. A Probabilistic Proof of Theorem 3.2. As mentioned earlier, Theorem 3.2 can also be proved by using a probabilistic argument. Modulo certain technicalities, we sketch this argument below.

First suppose $\gamma:[0, \infty) \rightarrow M$ is a smooth path. Let $\rho(t, \gamma)$ be the $\mathbb{Z}^{k}$-valued winding number of $\gamma$, as in Definition 3.1. Namely, let $\bar{\gamma}$ be the lift of $\gamma$ to the universal cover of $M$, and let $\rho(t, \gamma)=\left(n_{1}, \ldots, n_{k}\right)$ if

$$
\pi_{G}(\overline{\boldsymbol{g}}(\bar{\gamma}(t)))=\sum_{i=1}^{k} n_{i} \pi_{G}\left(\gamma_{i}\right)
$$

By our choice of $\left(\omega_{1}, \ldots, \omega_{k}\right)$ we see that $\rho_{i}(t, \gamma)$, the $i^{\text {th }}$ component of $\rho(t, \gamma)$, is precisely the integer part of $\theta_{i}(t, \gamma)$, where

$$
\begin{equation*}
\theta_{i}(t, \gamma) \stackrel{\text { def }}{=} \int_{\gamma([0, t])} \omega_{i}=\int_{0}^{t} \omega_{i}(\gamma(s)) \gamma^{\prime}(s) d s \tag{5.7}
\end{equation*}
$$

If $M$ is a planar domain with $k$ holes, and the forms $\omega_{i}$ are chosen as in Remark 2.4, then $2 \pi \theta_{i}(t, \gamma)$ is the total angle $\gamma$ winds around the $k^{\text {th }}$ hole up to time $t$.

In the case when $\gamma$ is not smooth, the theory of rough paths can be used to give meaning to the above path integrals. In particular, when $\gamma$ is the trajectory of semimartingale on $M$, we know that the integral obtained via the theory of rough paths agrees with the Stratonovich integral. To fix notation, let $W$ be a reflected Brownian motion in $M$, and $\rho(t)=\left(\rho_{1}(t), \cdots, \rho_{k}(t)\right)$ to be the $\mathbb{Z}^{k}$-valued winding number of $W$ as in Definition 3.1. Then we must have $\rho_{i}(t)=\left\lfloor\theta_{i}(t)\right\rfloor$, where $\theta_{i}(t)$ is the rough path integral, or equivalently, the Stratonovich integral

$$
\begin{equation*}
\theta_{i}(t)=\int_{0}^{t} \omega_{i}\left(W_{s}\right) \circ d W_{s} \tag{5.8}
\end{equation*}
$$

In Euclidean domains, the long time behaviour of this integral can be obtained as follows. The key point is that the forms $\omega_{i}$ are chosen to be harmonic in $M$ and tangential on $\partial M$. Consequently, using the semi-martingale decomposition (5.4), we see that

$$
\begin{aligned}
\theta_{i}(t) & =\int_{0}^{t} \omega_{i}\left(W_{s}\right) \circ d \beta_{s}+\int_{0}^{t}\left(\omega_{i}\left(W_{s}\right) \cdot u\left(W_{s}\right)\right) d L_{s} \\
& =\int_{0}^{t} \omega_{i}\left(W_{s}\right) d \beta_{s}
\end{aligned}
$$

In particular, $\theta$ is indeed a martingale with quadratic variation given by

$$
\begin{equation*}
\left\langle\theta_{i}, \theta_{j}\right\rangle_{t}=\int_{0}^{t} \omega_{i}\left(W_{s}\right) \cdot \omega_{j}\left(W_{s}\right) d s \tag{5.9}
\end{equation*}
$$

Moreover, by Harrison et. al. [HLS85], the unique invariant measure of $W_{t}$ is the normalized Lebesgue measure. Therefore, according to the ergodic theorem,

$$
\lim _{t \rightarrow \infty} \frac{1}{t}\left\langle\theta_{i}, \theta_{j}\right\rangle_{t}=\frac{1}{\operatorname{vol}(M)} \int_{M} \omega_{i} \cdot \omega_{j}
$$

for almost surely. Now we can conclude from the martingale central limit theorem (see [PS08, Theorem 3.33 and Corollary 3.34]) that

$$
\frac{\theta_{t}}{\sqrt{t}} \xrightarrow[w]{t \rightarrow \infty} \mathcal{N}(0, \Sigma)
$$

where the covariance matrix $\Sigma$ is given by (3.3).
To extend the above argument to the geometric setting, one first needs to establish the analogue of the semi-martingale decomposition (5.4) on manifolds with boundary. While this should be a technical adaptation of [SV71], there is no easily available reference. In addition, one needs to to show that $\theta_{i}$ is a martingale with quadratic variation (5.9). This might be done through a localization argument by breaking the Stratonovich integral defining $\theta_{i}$ (equation (5.8)) into pieces that are entirely contained in local coordinate charts, and using the analogue of (5.4) together with the fact that $\omega \in \mathcal{H}^{1}$. Now the other parts of the argument should be the same as the Euclidean case.

## Acknowledgements.

The authors wish to thank Jean-Luc Thiffeault for suggesting this problem to us and many helpful discussions.

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${ }^{1}$ School of Mathematics and Statistics, University of Melbourne, Melbourne, ViC 3010, Australia.

Email address: xi.geng@unimelb.edu.au
2 Department of Mathematical Sciences, Carnegie Mellon University, Pittsburgh, PA 15213, United States.

Email address: gautam@math.cmu.edu


[^0]:    2010 Mathematics Subject Classification. Primary 58J35; Secondary 58J65, 60F05.
    Key words and phrases. Heat kernel, Reflected Brownian motion, Winding number.
    This material is based upon work partially supported by the National Science Foundation under grants DMS-1252912, DMS-1814147 to GI, and the Center for Nonlinear Analysis.

[^1]:    ${ }^{1}$ The results we state are still true if $M$ has no boundary. In this case, however, the results are already contained in [Lot92, KS00].

[^2]:    ${ }^{2}$ The isomorphism between $\mathcal{H}_{G}^{1}$ and $\operatorname{Hom}(G ; \mathbb{R})$, the dual of the deck transformation group $G$, can be described as follows. Given $g \in G$, pick a base point $p_{0} \in M$, and a pre-image $x_{0} \in \pi^{-1}\left(p_{0}\right)$. Now define

    $$
    \varphi_{\omega}(g)=\int_{x_{0}}^{g\left(x_{0}\right)} \pi^{*}(\omega)
    $$

    where the integral is done over any path connecting $x_{0}$ and $g\left(x_{0}\right)$. By definition of $\mathcal{H}_{G}^{1}$, the above integral is independent of the chosen path. Moreover, since $\pi^{*}(\omega)$ is the pull-back of $\omega$ by the covering projection, it follows that $\varphi_{\omega}(g)$ is independent of the choice of $p_{0}$ or $x_{0}$. Thus $\omega \mapsto \varphi_{\omega}$ gives a canonical homomorphism between $\mathcal{H}_{G}^{1}$ and $\operatorname{Hom}(G, \mathbb{R})$. The fact that this is an isomorphism follows from the transitivity of the action of $G$ on fibers.
    ${ }^{3}$ Note first that one has to verify a solvability condition to ensure that solutions to equation (2.4) exist. Moreover, since $\lambda_{0}$ manifestly belongs to the spectrum of $-\Delta$, the function $g_{\omega}$ is not unique. Nevertheless, the function $\mathcal{I}(\omega)$ is well defined and does not depend on the choice of $g_{\omega}$. We show this in Lemma 4.5, in Section 4.4, below.

[^3]:    ${ }^{4}$ The existence of such a cover is easily established by taking the quotient of the universal cover $\bar{M}$ by the action of the commutator of $\pi_{1}(M)$.

