

The Batchelor Spectrum of Passive Scalar Turbulence in Stochastic Fluid Mechanics at Fixed Reynolds Number

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Abstract

In 1959 Batchelor predicted that the stationary statistics of passive scalars advected in fluids with small diffusivity κ should display a $|k|^{-1}$ power spectrum along an inertial range contained in the viscous-convective range of the fluid model. This prediction has been extensively tested, both experimentally and numerically, and is a core prediction of *passive scalar turbulence*.

In this article we provide a rigorous proof of a version of Batchelor's prediction in the $\kappa \rightarrow 0$ limit when the scalar is subjected to a spatially smooth, white-in-time stochastic source and is advected by the 2D Navier-Stokes equations or 3D hyperviscous Navier-Stokes equations in $\mathbb{T}^d$ forced by sufficiently regular, nondegenerate stochastic forcing. Although our results hold for fluids at arbitrary Reynolds number, this value is fixed throughout. Our results rely on the quantitative understanding of Lagrangian chaos and passive scalar mixing established in our recent works. Additionally, in the $\kappa \rightarrow 0$ limit, we obtain statistically stationary, weak solutions in $H^{-\epsilon}$ to the stochastically forced advection problem *without diffusivity*. These solutions are almost-surely not locally integrable distributions with nonvanishing average anomalous flux and satisfy the Batchelor spectrum at all sufficiently small scales. We also prove an Onsager-type criticality result that shows that no such dissipative, weak solutions with a little more regularity can exist. © 2021 Wiley Periodicals LLC.

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1 Introduction

A fundamental problem in fluid mechanics concerns the behavior of the concentration of a scalar g_t^κ being passively advected by an incompressible fluid velocity u_t while also undergoing some small amount of molecular diffusion. In many circumstances the scalar exhibits complex, (approximately) statistically self-similar patterns over a range of scales, referred to as *passive scalar turbulence* (see, e.g., [48, 80, 89, 100, 103] for more discussions of the physical background and Remark 1.1 for some context for the use of the word “turbulence”).

In this work, we consider a fluid in the periodic box $\mathbb{T}^d$, $d = 2$ or 3 , where the fluid velocity u_t evolves according to a time-continuous, randomly driven ergodic motion. The scalar g_t^κ solves the following advection diffusion equation with stochastic source:

$$\partial_t g_t^\kappa + u_t \cdot \nabla g_t^\kappa - \kappa \Delta g_t^\kappa = \dot{s}_t.$$

Here $\kappa > 0$ is the molecular diffusivity, and the source $\dot{s}_t$ is a white-in-time, Gaussian process supported at low spatial frequencies. For simplicity, it suffices to consider $s_t(x) = b(x)\beta_t$, where b is a nonzero smooth function on $\mathbb{T}^d$ and β_t is a 1D Brownian motion independent from u_t . We will assume that the velocity u_t itself evolves according to an incompressible, stochastically forced fluid model, for instance the *stochastic Navier-Stokes equations* on $\mathbb{T}^2$,

$$\begin{aligned} \partial_t u_t + u_t \cdot \nabla u_t + \nabla p_t - \nu \Delta u_t &= Q \dot{W}_t, \\ \operatorname{div} u_t &= 0, \end{aligned}$$

or the *stochastic hyperviscous Navier-Stokes equations* on $\mathbb{T}^3$, both of which are known to be ergodic with a unique stationary measure under fairly mild nondegeneracy assumptions on the stochastic forcing (see Sections 2.1 for more precise details). We also consider a variety of other finite-dimensional fluid models with better time and space regularity (see Section 2.2).

The presence of the source s_t and the ergodicity of u_t allows for the scalar to settle into a *statistical steady state* with ensemble $\mathbf{E}$, where the scalar input from the source $\dot{s}_t$ is balanced by dissipation due to the diffusion from $\kappa \Delta$ and the law of g_t^κ is the same for all times. Specifically, when $s_t = b\beta_t$, Itô’s formula implies that in a statistical steady state, there is an average constant dissipation rate $\chi := \|b\|_{L^2}^2 > 0$,

$$2\kappa \mathbf{E} \|\nabla g^\kappa\|_{L^2}^2 = \chi$$

providing a mechanism for a *cascade* to high frequencies (see Proposition 1.2 for details).

When κ is taken very small, complex (approximately) self-similar patterns in the scalar g_t^κ emerge. In a statistical steady state, these patterns usually have an L^2 power spectrum that approximates a *power law* over a certain range of frequencies. For physical fluid flows and in numerical simulations of the Navier-Stokes

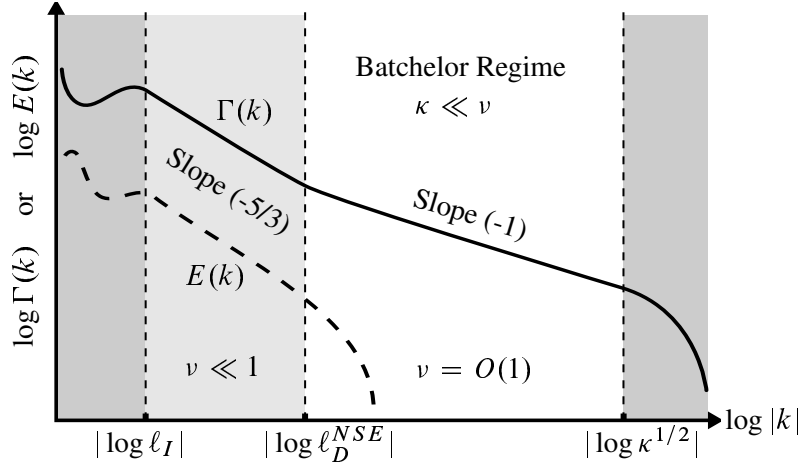


FIGURE 1.1. The solid line above is the full prediction for the power spectrum $\Gamma(k) = |k|^{d-1} \mathbf{E}|\hat{g}^\kappa(k)|^2$ of a statistically stationary passive scalar g^κ advected by a turbulent fluid u_t in 3D. In the Batchelor regime $\kappa \ll \nu$, it is theorized that the power law $|k|^{-1}$ holds for scales between ℓ_D^{NSE} (the dissipative scale for Navier-Stokes) and $\kappa^{1/2}$ (the dissipative scale for Batchelor's regime). Between ℓ_I and ℓ_D^{NSE} one expects *Obukhov-Corrsin statistics*, e.g., the $|k|^{-5/3}$ law in dimension $d = 3$, as depicted by the dashed curve above ($E(k) = |k|^{d-1} \mathbf{E}|\hat{u}(k)|^2$). No universality is expected at length-scales in the integral range above ℓ_I . We emphasize that in the setting of the present manuscript, ν is fixed $O(1)$ and $\kappa \ll 1$; as such, even if ν itself is quite small, our methods do not distinguish the Obukhov-Corrsin regime from the integral range.

equations, such power laws are frequently observed, with different regimes depending on the size of the Schmidt number $\text{Sc} := \text{Pr} / \text{Re}$, where $\text{Re} = \nu^{-1}$ is the Reynold's number and $\text{Pr} = \kappa^{-1}$ is the Prandtl number. In his foundational paper [12], Batchelor predicted that when $\text{Sc} \gg 1$ (known as the Batchelor regime), the steady-state statistics for a passive scalar exhibit a $|k|^{-1}$ power spectrum over the *viscous-convective subrange* of frequencies, known as *Batchelor's law* (or the *Batchelor spectrum*):¹

$$(1.1) \quad \Gamma(|k|) := |k|^{d-1} \mathbf{E}|\hat{g}^\kappa(k)|^2 \approx \chi |k|^{-1} \quad \text{for } (\ell_D^{\text{NSE}})^{-1} \ll |k| \lesssim \kappa^{-1/2},$$

where for each $k \in \mathbb{Z}^d$, $\hat{g}^\kappa(k)$, denotes the Fourier transform of g^κ on $\mathbb{T}^d$ and $\ell_D^{\text{NSE}} = (\nu/\epsilon)^{d/4}$ is the dissipative range for the Navier-Stokes equations with ϵ being the fluid energy dissipation rate.

Since Batchelor made his prediction, engineers and physicists have been making measurements of the spectrum in nature, e.g., temperature and salinity variations

¹ Batchelor's original prediction was actually for scalars on $\mathbb{R}^3$ (see Section 1.1 for more details) instead of the periodic box; the prediction below is adapted to the periodic setting.

in the ocean (see [38, 58, 89] and the references therein), in laboratory experiments (see [2, 56, 68, 83, 104, 105] and the references therein), and in numerical studies (see [4, 23, 40, 62, 109] and the references therein). As discussed in [4, 40, 80] it remains an open problem in physics to determine the settings in which the Batchelor spectrum is expected and to what degree of accuracy it holds. We will briefly discuss some theoretical studies in the physics literature in Section 1.2.

In this paper, we are primarily concerned with the *Batchelor regime* at fixed *Reynolds number*: where ν is considered fixed at an arbitrary (potentially small) number and $\kappa \ll \nu$. It is important to note that at length scales below the dissipative scale ℓ_D^{NSE} for the fluid (or equivalently, frequencies above $(\ell_D^{\text{NSE}})^{-1}$) the velocity field u_t is expected to be smooth while only g_t becomes rougher and rougher as $\kappa \rightarrow 0$, which makes it significantly easier to understand the “nonlinear”² advection term $u_t \cdot \nabla g_t$ in low regularity.

The Batchelor spectrum is, in some sense, predicated on smoothness of the velocity field – it only holds over length scales relative to which the velocity field is essentially smooth. This can be seen from Batchelor’s original argument [12]; see further discussions in [5, 6, 11, 24, 48] and below in Section 1.2. In this regard, the much simpler case of fixed Reynolds number seems to be a reasonable first place to begin any mathematical study of Batchelor-regime passive scalar turbulence, and indeed, of passive scalar turbulence in general. For frequencies below $(\ell_D^{\text{NSE}})^{-1}$, hydrodynamic turbulence gives rise to a different approximate power law (a $|k|^{-5/3}$ law for $d = 3$), known as Obukhov-Corrsin spectra for the passive scalar [31, 90]; see [4, 100]. See Figure 1.1 and the associated caption for a description of these two different expected regimes of passive scalar turbulence.

If one does not fix the Reynolds number and simultaneously takes $\nu, \kappa \rightarrow 0$, while sending $\text{Sc} \rightarrow \infty$, then the fluid itself is becoming turbulent while nevertheless, the viscous-convective subrange remains in the Batchelor regime. This is a situation that we *cannot* treat in this work. Indeed, since almost nothing rigorous has been established mathematically for the (very singular) turbulent limit $\nu \rightarrow 0$ for statistically stationary solutions u_t to the Navier-Stokes equations,³ this appears well out of reach of rigorous mathematical analysis for the time being. One model where this kind of ‘turbulent advection’ has been studied is in the *Kraichnan model*, in which u_t is replaced by an idealized rough-in-space, white-in-time Gaussian velocity field, and the equation for g_t is interpreted as a Stratonovich stochastic transport equation. This model was introduced for this purpose in [71], and there is now a wide literature on this model in physics (see [32, 33, 100] and the references therein). Properties of stochastic transport with rough velocities have also been studied mathematically as well in the work on isotropic stochastic flows [14, 67, 79] and well-posedness by stochastic perturbation [50, 52, 85]. See

² Nonlinear here refers to nonlinearity of the mapping $(u, g) \mapsto u \cdot \nabla g$.

³ For example, it is unknown whether the kinetic energy remains bounded in 3D.

also the recent preprint [41] for a deterministic work on turbulent advection by rough velocities.

Remark 1.1. In the physics and engineering literature, “turbulence” is used to describe a wide range of observed phenomena in dynamics of weakly damped, infinite-dimensional, nonlinear conservative systems in “generic” settings, including both 2D and 3D incompressible or compressible Navier-Stokes, passive scalars advected by fluids, nonlinear dispersive equations, magnetohydrodynamics models, and kinetic models in plasmas [20, 22, 55, 59, 76, 87, 100, 103, 110].

In the Batchelor regime, the passive scalar model we consider is one of the simplest settings in applications where turbulent phenomena can be observed that share many similarities with hydrodynamic turbulence [100], specifically a frequency cascade, “anomalous” dissipation, power laws on the power spectrum, and scaling laws on structure functions.

1.1 Review of Batchelor’s argument

In [12] Batchelor made his prediction by studying the effect of advection and diffusion on pure Fourier modes when the velocity field is a linear “pure straining flow,” namely a linear velocity field $u_t(x) = Ax$ on $\mathbb{R}^3$ whose matrix A is traceless with real distinct eigenvalues. He argued that, upon zooming in on the velocity field all the way down to the viscous-convective subrange, the flow is most likely to be approximated by a pure straining flow (see Section 1.2 for more discussion on the validity of this approximation). For such flows he showed that frequencies increase exponentially fast, and in a steady state exhibit an exact asymptotic formula for the power spectral density.

To understand the essence of this approach, let us consider the case $d = 2$ and take the velocity field $u_t(x) = Ax$ on $\mathbb{R}^2$, where

$$A = \begin{pmatrix} \gamma & 0 \\ 0 & -\gamma \end{pmatrix}.$$

If one takes a pure Fourier mode as initial data $g_0(x) = \sin(\xi_0 \cdot x)$ for the advection diffusion equation without a source, then the solution takes the form $C_t^\kappa \sin(\xi_t \cdot x)$, where the amplitude C_t^κ and frequency ξ_t solve the ODE system

$$\dot{C}_t^\kappa = -\kappa |\xi_t|^2 C_t^\kappa, \quad \dot{\xi}_t = -A \xi_t.$$

If the initial frequency $\xi_0 \in \mathbb{R}^2$ has a nontrivial projection onto $\hat{e}_1 = (1, 0)$, say, for example, $|\langle \xi_0, \hat{e}_1 \rangle| = 1$, then there is an exponential-in-time increase in frequency $|\xi_t| \sim e^{\gamma t}$, indicating a *cascade* from low to high frequencies. At the same time, the amplitude decays double exponentially fast due to diffusion, to wit, $C_t^\kappa \sim \exp(-\kappa e^{2\gamma t}/2\gamma)$, since the diffusion acts more strongly at high frequencies.

To see what effect this has on the steady-state power spectrum, consider a stochastic source $\dot{s}_t = \sin(\xi_0 \cdot x) \dot{\beta}_t$ supported at frequency ξ_0 . In a statistical steady

state, the scalar field g^κ is equal in law to the stochastic integral

$$g^\kappa(x) = \int_0^\infty C_s^\kappa \sin(\xi_s \cdot x) d\beta_s,$$

which is a Gaussian random variable in L_{loc}^2 . Using Itô's isometry and the fact that $\chi := \lim_{R \rightarrow \infty} \int_{[0,R]^2} |\sin(\xi_s \cdot x)|^2 dx$ does not depend on s , we find that the average L^2 mass density carried by frequencies less than $n \geq 0$ is given by

$$\begin{aligned} \langle |\Pi_{\leq n} g^\kappa|^2 \rangle &:= \lim_{R \rightarrow \infty} \int_{[0,R]^2} \mathbf{E} |\Pi_{\leq n} g^\kappa(x)|^2 dx \\ &= \chi \int_0^{t(n)} C_s^{2\kappa} ds, \end{aligned}$$

where $\Pi_{\leq n}$ denotes the projection onto frequencies $|\xi| \leq n$ and $t(n)$ is the unique time such that $|\xi_{t(n)}| = n$ (which exists for large enough n by monotonicity of $t \mapsto |\xi_t|$). The power spectral density is then defined by

$$\Gamma(n) := \frac{d}{dn} \langle |\Pi_{\leq n} g^\kappa|^2 \rangle = t'(n) \chi C_{t(n)}^{2\kappa}.$$

That $|\xi_t| \sim e^{\gamma t}$ implies the asymptotic $t(n) \sim \log n / \gamma$ and $t'(n) \sim \frac{1}{\gamma n}$, therefore

$$\Gamma(n) \sim \frac{\chi}{\gamma n} \exp\left(-\frac{\kappa n^2}{\gamma}\right).$$

We recover Batchelor's prediction $\Gamma(n) \sim \frac{\chi}{\gamma n}$ in the range $1 \ll n \lesssim (\gamma/\kappa)^{1/2}$.

1.2 Going beyond pure straining flows

It is natural to question whether a time-stationary pure straining flow is actually a good approximation of a fluid at small scales. Indeed, since the velocity fields change in time, so too does the approximating linear flow (i.e., the gradient), so one should at least expect a linear phase portrait changing in time. Moreover, there are many coherent Lagrangian structures (e.g., vortices) that locally exhibit shearing or rotational phase portraits, incompatible with the expansion/contraction exhibited by the pure strain flow. Remarkably, however, Batchelor's argument gets the right answer; in fact, Batchelor's law is a robust prediction, holding for a large class of *smooth* incompressible flows not necessarily arising from a physical fluid mechanical model.

The purpose of this paper is to show that a “cumulative” version of Batchelor's prediction (see Theorem [1.3](#) for an exact statement) is a consequence of the *chaotic mixing* properties of u_t proved in our previous works [\[16–18\]](#).

Lagrangian chaos

In short, Batchelor's argument succeeds because, even though the flow u_t is not always well-approximated by a pure straining flow, the linearized time- t motion of passive tracers (i.e., time- t Lagrangian flow) *does* resemble a pure strain flow for large times t . To make this more explicit, recall that in the absence of diffusivity

($\kappa = 0$) and sources ($s_t \equiv 0$), the scalar g_t is given by $g_t = g_0 \circ (\phi^t)^{-1}$, where the *Lagrangian flow map* $\phi^t : \mathbb{T}^d \rightarrow \mathbb{T}^d$ describes the position of a particle $x_t = \phi^t(x)$ starting from $x \in \mathbb{T}^d$ and solves the ODE

$$\frac{d}{dt}\phi^t(x) = u_t(\phi^t(x)), \quad \phi^0(x) = x.$$

The derivative of the flow $D\phi^t(x) : \mathbb{R}^d \rightarrow \mathbb{R}^d$ then solves the linearized equation

$$\frac{d}{dt}D\phi^t(x) = Du_t(\phi^t(x))D\phi^t(x), \quad D\phi^0(x) = \text{Id}.$$

By incompressibility (note $\det D\phi^t(x) \equiv 1$), growth in time of $|D\phi^t(x)|$ for typical x is associated with the development of strongly expanding and contracting directions of $D\phi^t(x)$ for each fixed t , features resembling those of the linear pure strain flow phase portrait. Growth of $|D\phi^t(x)|$ can be quantified in terms of positivity of the Lyapunov exponent

$$(1.2) \quad \lambda_1(x) = \limsup_{t \rightarrow \infty} \frac{1}{t} \log |D\phi^t(x)| > 0$$

for “typical” $x \in \mathbb{T}^d$, which we refer to as *Lagrangian chaos*. Previously Lagrangian chaos has been proved for stationary, white-in-time velocity fields in [13, 15]. In [16], we proved that the Lagrangian flow associated to solutions u_t of the stochastically forced 2D Navier-Stokes and 3D hyperviscous Navier-Stokes is chaotic in the sense that there is a deterministic constant $\lambda_1 > 0$ such that (1.2) holds with lim-sup replaced with lim for all x and all initial fluid configurations, almost surely (see [16] for rigorous statements).

As has been observed by a long line of previous authors (see, e.g., [5, 6, 11, 24, 48, 93]), Lagrangian chaos is associated with a low-to-high transfer of an L^2 mass of passive scalars and provides a clear mechanism for Batchelor's law. Indeed, without diffusivity ($\kappa = 0$) and sources ($\dot{s}_t = 0$) we clearly have that $\nabla g_t \circ \phi^t = (D\phi^t)^{-\top} \nabla g_0$, hence one expects $\|\nabla g_t\|_{L^2}$ to grow exponentially fast in time. In view of L^2 conservation ($\|g_t\|_{L^2} = \|g_0\|_{L^2}$), this is strongly reminiscent of the transfer of L^2 mass from low to high frequencies appearing in Batchelor's original argument for pure shear-strain flow.

We emphasize that the results of [16] and the proof of (1.2) rely crucially upon the stochastic framework: it is often very difficult to provide rigorous proofs of positivity of Lyapunov exponents, even for deceptively simple models such as the Chirikov standard map family [42, 57] (a discrete-time toy model of the Lagrangian flow [32]); see [92, 108] for more discussions. In Navier-Stokes, one of the enemies is the formation of coherent vortices inside of which hyperbolicity is halted (see [10]). The arguments in our paper [16] imply that with probability 1, vortices of this kind cannot permanently trap any particles.

Uniform in diffusivity chaotic mixing

For the fluid models considered in this paper, a positive Lyapunov exponent alone is not enough to prove Batchelor’s law. Lagrangian chaos only implies that some “scalar energy” is going to high frequencies; i.e., some small scales are being created. However, we need here that small scales are being created everywhere in a reasonably uniform way with high probability (i.e., with explicit moment bounds on fluctuations in the rate of small scale creation). To quantify this, we use a much stronger property: uniform-in- κ , almost-sure exponential mixing^[4]. In [18], we proved that if $\bar{g}_t^\kappa$ is mean zero and solves the initial value problem

$$\partial_t \bar{g}_t^\kappa + u_t \cdot \nabla \bar{g}_t^\kappa - \kappa \Delta \bar{g}_t^\kappa = 0$$

with diffusivity but *no* random source, then there exists a *deterministic* constant $\gamma > 0$ independent of κ and random constant D_κ (depending on initial fluid configuration) such that

$$\|\bar{g}_t^\kappa\|_{H^{-1}} := \sup_{\|f\|_{H^1}=1} \left| \int f \bar{g}_t^\kappa \, dx \right| \leq D_\kappa e^{-\gamma t} \|\bar{g}_0\|_{H^1},$$

where D_κ also has suitable moment bounds *independent of κ* (see Definition 2.9 and Theorem 2.12 for precise statements). See [102] for a discussion of using negative Sobolev norms to quantify mixing. There is a large mathematical literature on scalar mixing in the mathematics literature; see [1, 25, 41, 45, 65, 77, 97, 107] and the references therein.

To see why uniform-in- κ scalar mixing implies an exponential increase of frequency scale, note that

$$\|\Pi_{\leq N} \bar{g}_t^\kappa\|_{L^2} \leq N \|\bar{g}_t^\kappa\|_{H^{-1}} \leq D_\kappa N e^{-\gamma t} \|\bar{g}_0\|_{H^1},$$

where $\Pi_{\leq N}$ denotes projection to Fourier modes of frequency $\leq N$. From this, one can see that for times $t \gg \frac{\log N}{\gamma}$, most of the scalar has been transferred from frequencies $\leq N$ to higher frequencies^[5]. As in Batchelor’s original argument, this exponentially fast transfer from low to high frequencies is exactly the mechanism that gives rise to Batchelor’s law when u_t is given by Navier-Stokes—one difficulty is of course dealing with potential unboundedness of the random constant D , which captures fluctuations in the mixing time.

Our work [18] builds on our earlier work [17] that proved the corresponding statement for $\kappa = 0$; similarly, this latter work uses the Lagrangian chaos result of [16] as a lemma. Our works [17, 18] are based on analyzing two-point statistics

⁴ One can construct dynamical systems with a positive Lyapunov exponent but arbitrarily slow (e.g., polynomial or logarithmic) mixing/decay of Lagrangian correlations, for example, Pommeau-Manneville maps (see, [78, 96]).

⁵ The appearance of the mixing rate γ here in the estimate $t \gg \frac{\log N}{\gamma}$ for the low-to-high transfer is suggestive of why Lagrangian chaos alone is insufficient to prove Batchelor’s law.

of the Lagrangian flow, and a key step is to upgrade the positivity of the Lyapunov exponent to positivity of the *moment Lyapunov exponents*

$$\Lambda(p) = - \lim_{t \rightarrow \infty} \frac{1}{t} \log \mathbf{E} |D\phi^t(x)|^{-p}, \quad 0 < p \ll 1.$$

This is deeply related to large deviations of the finite-time Lagrangian Lyapunov exponents as $t \rightarrow \infty$ (for the relation of moment Lyapunov exponents to large deviations in the convergence of Lyapunov exponents, see [7–9]). It had already been realized by physicists that fluctuations of Lagrangian Lyapunov exponents should play a key role in Batchelor's law (see discussions in [5, 6, 11] and the references therein), and so our works are in some ways a mathematically rigorous completion of some of these ideas.

1.3 Main results

We now turn to detailed statements of the main results of this paper. After providing some preliminary definitions and conventions, in Section 1.3 we state a “cumulative” version of Batchelor's power law spectrum for fluids at fixed, finite Reynolds number. Section 1.3 describes a version of Yaglom's law, a scaling law analogous to the $-4/5$ law in hydrodynamic turbulence. In Section 1.3 and 1.3, we turn our attention to the description of *ideal passive scalar turbulence*, i.e., the description of a class of low-regularity solutions to the “inviscid” $\kappa = 0$ advection-diffusion equation exhibiting a scale-by-scale flux of L^2 mass from low to high modes.

The velocity field (u_t) will take values in the space $\mathbf{H}$ consisting of mean zero divergence free velocity fields belongs to $H^\sigma = H^\sigma(\mathbb{T}^d; \mathbb{R}^d)$, the Sobolev space of mappings from $\mathbb{T}^d \rightarrow \mathbb{R}^d$ with regularity $\sigma > \frac{d}{2} + 3$; note that this implies velocities are always at least C^3 in space. The *velocity process* (u_t) will evolve in $\mathbf{H}$ according to one of the following stochastic PDEs depending on whether $d = 2$ or 3:

SYSTEM 1 (2D Navier-Stokes equations). When $d = 2$, (u_t) solves

$$\begin{aligned} \partial_t u_t + u_t \cdot \nabla u_t &= -\nabla p_t + \nu \Delta u_t + Q \dot{W}_t \\ \operatorname{div} u_t &= 0, \end{aligned}$$

where $u_0 = u \in \mathbf{H}$. Here, the viscosity $\nu > 0$ is a fixed constant.

SYSTEM 2 (3D hyper-viscous Navier-Stokes). When $d = 3$, (u_t) solves

$$\begin{aligned} \partial_t u_t + u_t \cdot \nabla u_t &= -\nabla p_t - \nu \Delta^2 u_t + Q \dot{W}_t \\ \operatorname{div} u_t &= 0, \end{aligned}$$

where $u_0 = u \in \mathbf{H}$. Here, the hyperviscosity $\nu > 0$ is a fixed constant.

In the above systems, W_t is a cylindrical Wiener process on mean-zero, divergence free L^2 vector fields with respect to an associated canonical stochastic basis $(\Omega_W, \mathcal{F}^W, (\mathcal{F}_t^W), \mathbf{P}_W)$ and Q a positive Hilbert-Schmidt operator on mean-zero,

divergence free L^2 vector fields satisfying suitable nondegeneracy and regularity assumptions. See Section 2.1 for full details. We couple systems 1 or 2 to the advection-diffusion equation

$$(1.3) \quad \begin{aligned} \partial_t g_t^\kappa + u_t \cdot \nabla g_t^\kappa - \kappa \Delta g_t^\kappa &= b \dot{\beta}_t \\ g_0^\kappa &= g, \end{aligned}$$

where β_t is a Wiener process on another canonical probability space denoted by $(\Omega_\beta, \mathcal{F}^\beta, (\mathcal{F}_t^\beta), \mathbf{P}_\beta)$. We denote the product measure $\mathbf{P} = \mathbf{P}_W \times \mathbf{P}_\beta$ our main probability measure on the associated product space $\Omega = \Omega_W \times \Omega_\beta$ with the standard product sigma-algebra $\mathcal{F} = \mathcal{F}^W \otimes \mathcal{F}^\beta$ and filtration $\mathcal{F}_t = \mathcal{F}_t^W \otimes \mathcal{F}_t^\beta$. Equation (1.3) has a $\mathbf{P}$ almost-sure, unique, $\mathcal{F}_t$ -adapted weak solution for every initial $(u, g) \in \mathbf{H} \times L^2$ (see Proposition 2.1 below) and defines a Markov semigroup P_t^κ on bounded, measurable observables $\varphi : \mathbf{H} \times L^2 \rightarrow \mathbb{R}$ via

$$P_t^\kappa \varphi(u, g) = \mathbf{E}_{(u, g)} \varphi(u_t, g_t^\kappa) := \mathbf{E}[\varphi(u_t, g_t^\kappa) | (u_0, g_0^\kappa) = (u, g)].$$

The cumulative Batchelor spectrum

Recall that a probability measure μ on $\mathbf{H} \times L^2$ is called *stationary* for the Markov semigroup P_t^κ if for all bounded, measurable $\varphi : \mathbf{H} \times L^2 \rightarrow \mathbb{R}$ and all $t > 0$,

$$\int P_t^\kappa \varphi \, d\mu = \int \varphi \, d\mu.$$

For observables $\varphi : \mathbf{H} \times L^2 \rightarrow \mathbb{R}$, we frequently write $\mathbf{E}_\mu \varphi(u, g) := \int \varphi \, d\mu$. We will also say a probability measure is stationary for a given process if it is stationary for the corresponding Markov semigroup.

Due to the infinite-dimensionality of $\mathbf{H}$, uniqueness of stationary measures for (u_t) is in general a subtle question: on the domain $\mathbb{T}^2$ this was first proved in [53] in the setting of completely nondegenerate noise, and has by now been established even for highly degenerate noise [60]. In comparison, the homogeneous part of the evolution equation for g_t^κ is linear, and so uniqueness of stationary measures for (u_t, g_t^κ) is relatively straightforward due to the contracting nature on L^2 .

PROPOSITION 1.2. *Assume (u_t) admits a unique stationary probability measure μ on $\mathbf{H}$. Then for all $\kappa > 0$, there exists a unique stationary measure μ^κ for (u_t, g_t^κ) on $\mathbf{H} \times L^2$. Moreover,*

$$(1.4) \quad 2\kappa \mathbf{E}_{\mu^\kappa} \|\nabla g\|_{L^2}^2 = \|b\|_{L^2}^2 =: \chi.$$

Uniqueness of μ^κ is proved in Section 2.5 and has the following consequence by the Birkhoff ergodic theorem: for μ^κ -typical initial $(u, g) \in \mathbf{H} \times L^2$ and any

continuous observable $\phi \in L^1(\mu^\kappa)$ on $\mathbf{H} \times L^2$, we have $\mathbf{P}$ -almost-surely⁶

$$(1.5) \quad \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \phi(u_t, g_t^\kappa) dt = \int \phi d\mu^\kappa.$$

Equation (1.4) follows from (1.5) and Itô's formula. The convergence of time averages to ensemble averages in (1.5) for typical initial data (u, g) confirms the statistically stationary setting described above: typical time-asymptotic behavior is captured by a unique stationary measure μ^κ .

Our main result is Batchelor's law on the *cumulative* power spectrum (see Remark 1.9). Let $\Pi_{\leq N}$ denote the L^2 projection to the Fourier basis functions with frequency $|k| \leq N$ (see Section 2.1).

THEOREM 1.3 (Batchelor's law on the cumulative power spectrum). *There exists an N_0 (depending on v but independent of κ) such that for all $\kappa \in (0, 1)$ sufficiently small and $p \in [1, \infty)$, the following holds with implicit constants⁷ independent of κ and N :*

$$(1.6) \quad (\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^{2p})^{1/p} \approx_p \log N \quad \text{for all } N_0 \leq N \leq \kappa^{-1/2}.$$

Moreover, for all $s \in [0, \sigma - \frac{3d}{2} - 1)$ and $\forall p \in [1, \infty)$,

$$(1.7) \quad (\mathbf{E}_{\mu^\kappa} \|g\|_{H^s}^{2p})^{1/p} \lesssim_{p,s} \kappa^{-s} |\log \kappa|.$$

Remark 1.4. Batchelor's law is often stated with a constant proportional to $\chi = 2\kappa \mathbf{E} \|\nabla g^\kappa\|_{L^2}^2 = \|b\|_{L^2}^2$, as in (1.1). A careful reading of our proof provides a simple estimate on the constants in (1.6) in terms of b , specifically, $\forall s > 0$, the following holds with implicit constants independent of b :

$$(1.8) \quad \log N \frac{\chi^2}{\|b\|_{H^s}^2} \lesssim_{p,s} (\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^{2p})^{1/p} \lesssim_{p,s} \|b\|_{H^s}^2 \log N$$

for all $N_0 \leq N \leq \kappa^{-1/2}$, and that it suffices to take

$$N_0 \approx_{s,\delta} \left(\frac{\|b\|_{H^s}^{2/s}}{\chi^{1/s}} \right)^{1+\delta}$$

for any $\delta > 0$ (the implicit constants in (1.8) will also depend on δ). The use of regularity is because mixing estimates require the source to have *some* positive regularity in order to get quantitative, κ -independent decay rates in negative Sobolev

⁶ When (u_t) is forced with nondegenerate noise, as we do in this paper, it is possible to promote the convergence in (1.5) to *all* initial $(u, g) \in \mathbf{H} \times L^2$ when one considers bounded, uniformly continuous observables $\phi : \mathbf{H} \times L^2 \rightarrow \mathbb{R}$. This follows from (1) the strong Feller property for the Markov semigroup associated to u_t (see [53]) and (2) a small variation of the proof of Proposition 1.2 given in Section 2.5. Details are omitted for brevity.

⁷ We denote $f \lesssim_{p,q,\dots} h$ if there exists a constant $C > 0$ depending on $p, q, \dots$ but independent of the other parameters of interest such that $f \leq Ch$ and $f \approx h$ when $f \lesssim h$ and $h \lesssim f$. For the entire paper, these implicit constants will *never* depend on κ, N , or t .

spaces. It is unclear if Batchelor's law as stated in Theorem 1.3 is still true if b has no more than L^2 regularity. If b takes values in any

$$\Lambda_C = \{b \in H^s : C^{-1}\|b\|_{L^2} \leq \|b\|_{H^s} \leq C\|b\|_{L^2}\},$$

then both implicit constants in (1.6) are proportional to χ and N_0 depends only on C .

Theorem 1.3 implies the following uniform-in- κ estimate:

COROLLARY 1.5. *For all $s > 0$ and $p \geq 1$ the following holds:*

$$(1.9) \quad \sup_{\kappa} \mathbf{E}_{\mu^{\kappa}} \|g\|_{H^{-s}}^{2p} \lesssim_{p,s} 1.$$

PROOF. Note that by Minkowski's inequality (denoting $\Pi_N = \Pi_{\leq N} - \Pi_{\leq N/2}$ for $N \geq 2$ and $\Pi_1 = \Pi_{\leq 1}$),

$$\begin{aligned} (\mathbf{E}_{\mu^{\kappa}} \|g\|_{H^{-s}}^{2p})^{1/p} &\approx \left(\mathbf{E}_{\mu^{\kappa}} \left(\sum_{j \geq 0} 2^{-2sj} \|\Pi_{2^j} g\|_{L^2}^2 \right)^p \right)^{1/p} \\ &\lesssim \sum_{j \geq 0} 2^{-2sj} \left(\mathbf{E}_{\mu^{\kappa}} \|\Pi_{2^j} g\|_{L^2}^{2p} \right)^{1/p}, \end{aligned}$$

which is bounded $\lesssim 1$ by (1.6). $\square$

Remark 1.6. Note that Theorem 1.3 (with $s = 0$) implies the logarithmic divergence in L^2 :

$$(1.10) \quad \mathbf{E}_{\mu^{\kappa}} \|g\|_{L^2}^2 \approx |\log \kappa|.$$

Remark 1.7. The cumulative power spectrum estimate in (1.6) comes in two parts. The lower bound is *easier* to establish and contains relatively little dynamical information: we show in Section 3.2 that it follows from the fact that Lipschitz velocity fields cannot mix a scalar faster than exponential (provided that one has suitable exponential moment estimates to control large deviations). The upper bound on the other hand is much more difficult. It makes crucial use of the optimal, almost-sure uniform-in- κ mixing estimates obtained in our recent work [18], which in turn depends heavily on the results and methods of our earlier works on mixing and Lagrangian chaos [16, 17]. Without these results, we would not be able to obtain an upper bound. See below in Section 1.2 for more discussion on this sequence of works.

Remark 1.8. The proof of the upper bound in (1.6) holds directly for all $N < \infty$. By itself, the estimates on the cumulative power spectrum in (1.6) are not precise enough to localize the dissipative range. Indeed, it is easy to check that (1.6) implies for all $\zeta > 0$,

$$(\mathbf{E}_{\mu^{\kappa}} \|\Pi_{\leq N} g\|_{L^2}^{2p})^{1/p} \approx_{\zeta,p} \log N \quad \text{for all } N_0 \leq N \leq \kappa^{-\zeta}.$$

However, (1.4) provides the additional information needed to localize the dissipative scale to approximately $\kappa^{-1/2}$, as one should expect from parabolic regularity. Indeed,

$$\mathbf{E}_{\mu^\kappa} \|(I - \Pi_{\leq N})g\|_{L^2}^2 \leq \frac{1}{N^2} \mathbf{E}_{\mu^\kappa} \|\nabla g\|_{L^2}^2 = \frac{\chi}{2\kappa N^2}.$$

The estimate (1.7) provides more precise high-frequency moment control, albeit with a logarithmic deviation from (1.4).

Remark 1.9. The cumulative power spectrum estimate (1.6) is a little weaker than (1.1) or a dyadic-shell averaged version (i.e., $\mathbf{E} \|\Pi_{2^j} g^\kappa\|_{L^2}^2 \approx 1$). However, if $\mathbf{E}_{\mu^\kappa} |\hat{g}(k)|^2 \approx F(k)$ for $F(k)$ a monotone function, then (1.6) implies that $F(k) \approx |k|^{-d}$ (and analogously for any dyadic-shell averaged version). In a dyadic-shell averaged version, the only kind of violations of Batchelor's law that is not ruled out by (1.6) are if some dyadic shells have too little mass and/or a sparse set (i.e., zero asymptotic density) of dyadic shells that have too much L^2 mass (but never more than $\log 2^j$). The pointwise version in (1.1) could also be violated if the L^2 mass was not distributed evenly enough in angle. This is the case, for example, for discrete-time pulsed-diffusion models of advection-diffusion by CAT maps (see, e.g., [51]). Bridging this gap is the subject of a possible future line of research: see Section 1.4 below.

Yaglom's law

Yaglom's law was predicted in 1949 in [106] for all passive scalar turbulence regimes, and consists of a reformulation of the constant scale-by-scale L^2 flux characteristic of anomalous dissipation. This is analogous to scaling laws for other turbulent systems, e.g., the Kolmogorov $-4/5$ law for 3D Navier-Stokes (see [19, 55, 88] and the references therein). In [16], we showed as a consequence of Lagrangian chaos that Yaglom's law holds over *some* inertial range with an unspecified lower bound ℓ_κ with $\ell_\kappa \rightarrow 0$ as $\kappa \rightarrow 0$. Theorem 1.3 allows us to show that this law essentially holds over the entire inertial range $\ell \gtrsim \kappa^{1/2}$. The proof is an easy application of the methods of [16, 19] and the a priori estimate (1.10) from Theorem 1.3 and so is omitted for brevity.

COROLLARY 1.10 (Yaglom's law over sharp inertial range). *Denote the finite increment for $h \in \mathbb{R}^d$,*

$$\delta_h g(x) = g(x + h) - g(x).$$

Let $\ell_\kappa > 0$ be such that $\ell_\kappa^{-1} = o((\kappa |\log \kappa|)^{-1/2})$ as $\kappa \rightarrow 0$. Then,

$$(1.11) \quad \lim_{\ell_I \rightarrow 0} \limsup_{\kappa \rightarrow 0} \sup_{\ell \in (\ell_\kappa, \ell_I)} \left| \frac{1}{\ell} \mathbf{E}_{\mu^\kappa} \int_{\mathbb{T}^d} \int_{\mathbb{S}^{d-1}} |\delta_{\ell n} g|^2 \delta_{\ell n} u \cdot n \, dn \, dx + \frac{2}{d} \chi \right| = 0.$$

Note that by (1.10), statistically stationary solutions are blowing up in L^2 , and so (1.11) is only possible with the assistance of a large amount of cancellations.

Remark 1.11. For 3D Navier-Stokes, the Kolmogorov $-4/5$ law together with statistical self-similarity formally predicts the Kolmogorov $-5/3$ power spectrum ($|k|^2 \mathbf{E}|\hat{u}(k)|^2 \approx |k|^{-5/3}$). It is unclear at the moment how intermittency may or may not add corrections [3, 55, 69, 86, 101]. While passive scalar turbulence in the Batchelor regime is expected to display intermittency [62, 80, 91, 94, 99], we nevertheless do not see intermittency corrections to Batchelor’s prediction on the power spectrum, at least in the case where ν is fixed. Heuristically, one might guess this from Yaglom’s law (1.11): the regularity of the velocity implies that (1.11) formally scales like the second-order structure function $\mathbf{E}_{\mu^\kappa} \|\delta_\ell g\|_{L^2}^2$ which formally scales as the power spectrum by the Wiener-Khinchin theorem. Hence, Yaglom’s law suggests a certain rigidity to Batchelor-regime passive scalars that is not present in many other “turbulent” systems.

The vanishing diffusivity limit

For many turbulent systems consisting of a weakly damped system subjected to forcing, it is expected to be able to pass to the zero-damping limit and obtain statistically stationary solutions for the zero-damping problem [54, 81, 87]. The limiting regime is sometimes referred to as *ideal turbulence* [47]; in this limit, one expects weak solutions in very low regularity spaces with a nonvanishing scale-by-scale flux of conserved quantities through *all* sufficiently small scales. A prominent line of mathematical research in this direction is the work on Onsager’s conjecture for the 3D Euler equations [30, 36, 37, 46, 47, 64], which seeks to identify low-regularity solutions to the Euler equations capable of dissipating kinetic energy as one expects of ideal turbulent solutions to 3D Euler. Work on weak turbulence in dispersive equations can also be considered to be in a type of “ideal turbulence limit” [26, 49].

A consequence of our results on the Batchelor spectrum is a realization of the ideal turbulence program for passive scalar turbulence. Indeed, in contrast with contemporary advances on Onsager criticality for 3D Euler (capable only of generating specific solutions to 3D Euler with nonvanishing flux), in our setting we are able to exhibit probability measures supported in low-regularity spaces, typical samples of which exhibit the desired scale-by-scale flux across all sufficiently small scales.⁸

For this, we consider weak- $*$ subsequential limits of the sequence $\{\mu^\kappa\}$ of stationary measures for the (u_t, g_t^κ) process as $\kappa \rightarrow 0$, yielding (possibly more than one) stationary measures μ^0 for the zero-diffusivity process (u_t, g_t^0) governed by

$$(1.12) \quad \begin{aligned} \partial_t u_t + u_t \cdot \nabla u_t + \nabla p_t - \nu \Delta u_t &= Q \dot{W}_t, \\ \partial_t g_t^0 + u_t \cdot \nabla g_t^0 &= b \dot{\beta}_t. \end{aligned}$$

⁸ See [54, 81] for examples of simplified shell models where the inviscid limit to rough, weak solutions dissipating constant energy through the inertial range was successfully carried out in the statistically stationary regime.

Existence of weak-* limits in H^{-s} , $s > 0$, follows from Prokhorov's theorem and the κ -uniform moment estimates in Corollary 1.5; as a result, the limiting measures μ^0 are supported on some low-regularity subspace of $H^- = \bigcap_{s>0} H^{-s}$. See Section 4.1 for more details. The following summarizes the basic properties of this construction.

THEOREM 1.12 (Vanishing dissipation limit). *There exists a subsequence $\{\mu^{\kappa_n}\}$ and a limit measure μ^0 on $\mathbf{H} \times H^-$ such that for each $s > 0$, μ^{κ_n} converges weakly to μ^0 as a measure on $\mathbf{H} \times H^{-s}$. Moreover, any limit point μ^0 is a stationary measure for (u_t, g_t^0) , and the limit satisfies Batchelor's law over an infinite inertial range: for N_0 as in Theorem 1.3 there holds*

$$(1.13) \quad (\mathbf{E}_{\mu^0} \|\Pi_{\leq N} g\|_{L^2}^{2p})^{1/p} \approx_p \log N \quad \text{for all } N \geq N_0,$$

and moreover, there is nonvanishing L^2 flux:

$$(1.14) \quad \mathbf{E}_{\mu^0} \langle \Pi_{\leq N}(ug), \nabla \Pi_{\leq N} g \rangle = -\frac{1}{2} \|\Pi_{\leq N} b\|_{L^2}^2.$$

Remark 1.13. Note that the absence of the $\kappa \Delta$ dissipation in the transport equation (1.12) makes the existence of nontrivial stationary solutions far from obvious. The Markov process (u_t, g_t^0) has bad regularity properties on $\mathbf{H} \times H^-$ (it is not Feller) due to a lack of stability in the transport equation with respect to $\mathbf{H}$ perturbations of the velocity field, and so a Krylov-Bogoliubov argument using the uniform mixing bound does not apply. See Section 4.3 for more discussion.

Remark 1.14. The nonvanishing flux (1.14) is analogous to Yaglom's law (1.11) for the $\kappa = 0$ equation in that both results say something about the constancy of the L^2 flux in the $\kappa \rightarrow 0$ limit. However, as we show below in Theorem 1.15, μ^0 generic g are not even integrable on $\mathbb{T}^d$, and so we are unsure how to pass to the $\kappa \rightarrow 0$ limit in Yaglom's law directly.

Irregularity of $\kappa = 0$ stationary statistics

As mentioned previously, the limiting stationary statistics associated to μ^0 are very irregular. Indeed, the uniform bound (1.9) used to extract the limit μ^0 suggests that the measure is concentrated, at best, in $H^- = \bigcap_{s>0} H^{-s}$, while the limiting version of Batchelor's law (1.13) implies that

$$(1.15) \quad \mathbf{E}_{\mu^0} \|g\|_{L^2}^2 = \infty;$$

i.e., μ^0 cannot give second moments to functions in L^2 . The primary reason for this irregularity is that, in the absence of a Laplacian, stationary solutions to the zero diffusivity equation

$$(1.16) \quad \partial_t g_t^0 + u_t \cdot \nabla g_t^0 = b \dot{\beta}_t$$

must “anomalously” dissipate the input from the noise through the advection term. Since the velocity field (u_t) is regular, we cannot rely on roughness of the velocity field to dissipate and must rely solely on the mixing properties of (u_t) . Due to

the regularity of (u_t) , one can prove that the $\kappa = 0$ transport equation (1.12) conserves the L^1 norm of g_t^0 , and therefore one should expect that L^1 solutions to (1.16) cannot dissipate. In fact, we are able to confirm that μ^0 assigns zero mass to L^1 (see Section 5.1 for proof):

THEOREM 1.15 (Limiting solutions are not L^1). *Any limit measure μ^0 from Theorem 1.12 satisfies*

$$\mu^0(\mathbf{H} \times L^1) = 0.$$

Remark 1.16. It is important to note that contrary to (1.15), which only states that μ^0 can't have second moments on L^2 , Theorem 1.15 is much stronger in that it implies that μ^0 generic scalars g are “true” distributions in the sense that they do not take values in any space of integrable functions, regardless of moments.

Remark 1.17. In general, DiPerna/Lions theory (see, e.g., [39]) predicts that (1.12) conserves the L^p norm of g_t^0 if the velocity field is in the Sobolev space $W^{1,q}(\mathbb{T}^d)$ for $q = p/(p-1)$. In general, velocity fields (u_t) that are not Lipschitz do not propagate L^1 and should not be considered as belonging to the “Batchelor regime.” See [84] for an example of a continuous $W^{1,p}$ velocity field that does not propagate L^1 and also [41] for a related example.

Theorem 1.15 is based on understanding the formal L^1 conservation law of the inviscid equation (1.16). However, another clear question is to determine how irregular g must be to have a nonvanishing L^2 flux as in (1.14), i.e., studying violation of the L^2 conservation law. This is analogous to the problem for weak solutions of the 3D Euler equations known as *Onsager's conjecture*, which has received a significant amount of mathematical attention in recent years (see [35, 37, 64] and the review [27]). In the context of the 3D Euler equations, Onsager's conjecture states that weak solutions can dissipate energy when not in $C_{t,x}^{0,1/3-}$ and cannot dissipate energy if in $C_{t,x}^{0,1/3+}$. The easier direction, that weak solutions of 3D Euler conserve energy with sufficient regularity, was studied previously in [28, 30, 46]. Specifically, in [28] it was shown that the Onsager-critical space (the space that divides dissipative from conservative) is the Besov space $L_t^3 B_{3,\infty}^{1/3}$.

In the spirit of [28], we show below that the space $L_t^2 B_{2,\infty}^0$ is Onsager-type critical for the passive scalar turbulence problem, where $B_{2,\infty}^0 \subseteq H^-$ is the Besov space of tempered distributions $f \in H^-$ such that

$$\sup_{N \in \{2^j : j \in \mathbb{N}_*\}} \|\Pi_N f\|_{L^2} < \infty$$

(recall that $\Pi_N = \Pi_{\leq N} - \Pi_{\leq N/2}$ is a projection onto the dyadic shell of frequencies of length between N and $N/2$ and $\mathbb{N}_* = \{0\} \cup \mathbb{N}$). Time-integrability will be connected to moments with respect to the stationary measure μ^0 since for statistically stationary processes, expectations of time averages are exactly equal

to ensemble averages. Just past this critical boundary is the space $B_{2,c}^0 \subset B_{2,\infty}^0$ of distributions such that

$$\limsup_{j \rightarrow \infty} \|\Pi_{2^j} f\|_{L^2} = 0,$$

which possess just barely enough regularity to rule out L^2 flux (see Section 5.2).

In order to quantify regularity in $B_{2,\infty}^0$, we introduce generalized fractional derivative norms, which play the same role that the modulus of continuity does to generalize Hölder regularity.

DEFINITION 1.18. We call a multiplier $M : [0, \infty) \rightarrow [1, \infty)$ $B_{2,c}^0$ -suitable if

- (i) M is monotone increasing and $\lim_{k \rightarrow \infty} M(k) = \infty$;
- (ii) M is (globally) Lipschitz-continuous and $\forall C > 0$ and $\exists c > 0$ such that if $C^{-1}|\ell| \leq |k| \leq C|\ell|$,

$$|M(k) - M(\ell)| \leq \frac{c}{\sqrt{1 + |k|^2}} M(\ell) |k - \ell|.$$

Given such an M , we define the generalized Besov norm

$$\|f\|_{B_{2,\infty}^M} := \sup_{N \in \{2^j : j \in \mathbb{N}_*\}} M(N) \|\Pi_N f\|_{L^2}.$$

We show below in Lemma 5.3 that $f \in B_{2,c}^0$ if and only if $\|f\|_{B_{2,\infty}^M} < \infty$ for some $B_{2,c}^0$ -suitable M . We prove the following theorem by contradiction with (1.14) in Section 5.2.

THEOREM 1.19 (Onsager-type criticality of $L_t^2 B_{2,\infty}^0$). *Let μ^0 be a stationary measure for the $\kappa = 0$ limit process extended to $\mathbf{H} \times H^{-1}$. Then for every $p > 2$ and all $B_{2,c}^0$ -suitable M ,*

$$\mathbf{E}_{\mu^0} \|g\|_{B_{2,\infty}^M}^p = +\infty.$$

Remark 1.20. Note that we are not able to show that μ^0 assigns zero mass to $B_{2,c}^0$ as we could for L^1 , and instead can only show that moments with $p > 2$ cannot be finite. This obstruction is related to the fact that moments in μ^0 are related to time integrability of stationary solutions and the fact that the critical space is $L_t^2 B_{2,\infty}^0$. It is unclear if it is possible for μ^0 to assign positive measure to $\mathbf{H} \times B_{2,c}^0$.

Using Theorems 1.19 and 1.15 we can deduce the following about the solutions studied in Theorem 1.3. In particular, we show that moments of solutions diverge in certain norms, analogous to (1.10).

COROLLARY 1.21. *Let Φ on $[0, \infty)$ be a convex monotone function satisfying $\Phi(0) = 0$ and $\lim_{r \rightarrow \infty} \Phi(r)/r = \infty$, and let M be a $B_{2,c}^0$ -suitable multiplier. The unique stationary measure μ^κ on $\mathbf{H} \times L^2$ satisfies the following for each $\delta > 0$*

$$\lim_{\kappa \rightarrow 0} \mathbf{E}_{\mu^\kappa} \left(\int \Phi(|g|) dx \right)^\delta = \infty$$

and for each $p > 2$

$$\lim_{\kappa \rightarrow 0} \mathbf{E}_{\mu^\kappa} \|g\|_{B_{2,\infty}^M}^p = \infty.$$

1.4 Open problems in Batchelor-regime passive scalar turbulence

Theorems [1.3]–[1.21] provide a starting point for a mathematical understanding of Batchelor-regime passive scalar turbulence at fixed Reynolds number. However, there are many remaining open questions, all of which are potentially accessible in the near future using a combination of stochastic PDEs, harmonic analysis, and random dynamical systems. Let us briefly outline these here.

- **INTERMITTENCY.** Certainly the most important set of open questions regard intermittency. Following discussions in, e.g., [29, 55], we can begin to study intermittency by looking at the flatness parameters

$$F_p(N) = \frac{\mathbf{E} \|\Pi_N g\|_{L^{2p}}^{2p}}{(\mathbf{E} \|\Pi_N g\|_{L^2}^2)^p}.$$

A nonintermittent field would satisfy $F_p(N) \leq C(p)$ as $N \lesssim \kappa^{-1/2}$, $N \rightarrow \infty$, $\kappa \rightarrow 0$. An example of such a field is white noise. At the opposite extreme is a maximally intermittent random field consisting of a single Dirac delta function placed with uniform probability on $\mathbb{T}^d$, which satisfies $F_p(N) \approx_p N^{p-1}$. Passive scalar turbulence is expected to be intermittent [62, 91, 94, 99]. A major step in our understanding would be to provide an analytic derivation of powers $\zeta(p)$ such that $F_p(N) \approx N^{\zeta(p)}$ for $N \rightarrow \infty$, $\kappa \rightarrow 0$, if such powers exist.

A helpful intermediate step might be to consider the power spectrum of a discrete-time pulsed diffusion model [51], e.g., using a randomly driven Chirikov standard map to model advection⁹ [21].

- **HOW UNIVERSAL IS “UNIVERSAL”?** Another set of important problems is to study how widely applicable the Batchelor spectrum and other tenets of the theory, such as uniqueness of stationary measures, Lagrangian chaos, etc., to different and more realistic settings.
 - Problems on $\mathbb{T}^d$ with body forcing are far removed from any real physical applications. Extending existing theories to include boundaries (exterior or interior domains) and replacing body forces with boundary driving are probably the most physically important extensions. Even relatively basic questions, such as uniqueness of stationary measures of the Navier-Stokes equations, are to our knowledge, quite challenging and still open for most questions of this type. See [98] for some progress in this direction. A related direction is to study spatially homogeneous solutions on $\mathbb{R}^d$.

⁹ Note that the presence of noise makes this tractable, unlike the deterministic case which is notoriously difficult [42, 57].

- Even on $\mathbb{T}^d$ with stochastic forcing, in the case of the Navier-Stokes equations, our results on Lagrangian chaos and scalar mixing [16–18] cannot handle C_x^∞ forcing yet. It is natural to seek to extend this to C_x^∞ forcing and further to include non-white-in-time forcing such as OU tower forcing (see Section 2.2 and [17]) and the class of bounded forcing studied in [66, 72, 73]. Note that the hypoellipticity theory of Hairer and Mattingly [61] applies to the one-point Lagrangian flow ($\dot{x}_t = u_t(x_t)$) generated by 2D Navier-Stokes with OU tower forcing (and so the (u_t, Z_t, x_t) Markov process has a unique stationary measure); however, our Lagrangian chaos results require strong Feller in order to use the version of the Furstenberg criterion in [16].
- SHARPER REGULARITY ESTIMATES AND STRUCTURE FUNCTION RENORMALIZATION. Even just concerning basic questions related to Batchelor's law (1.6), there are still remaining questions.
 - There are three basic levels of precision when discussing the power spectrum. After the cumulative spectrum, the next most difficult is a dyadic shell-by-shell estimate, which so far remains unaddressed by the results in this paper. The next most difficult after that is the pointwise estimate

$$\mathbf{E}_{\mu^\kappa} |\widehat{g}(k)|^2 \approx |k|^{-d}, \quad N_0 < |k| < \kappa^{-1/2}.$$

In fact, one can even try to search for an estimate of the type (see the discussion in the physics literature, e.g., [40]), where of course we mean that the error is uniformly controlled in κ :

A colon was added here.

$$\mathbf{E}_{\mu^\kappa} |\widehat{g}(k)|^2 = C_B |k|^{-d} + o_{\kappa \rightarrow \infty}(|k|^{-d}), \quad N_0 < |k| < \kappa^{-1/2}.$$

These three basic levels are not equivalent. Pulsed-diffusion models based on discrete-time random dynamical systems might be able to shed some light on the subtle differences between these spectral characterizations.

- It is an interesting and subtle question to determine if the limiting solutions we obtain in Theorem 1.3 are *exactly* in the Onsager critical space $L_t^2 B_{2,\infty}^0$ or, more to the point, whether the $\kappa > 0$ approximations are uniformly bounded in this space, that is,

$$\mathbf{E}_{\mu^\kappa} \sup_{N \in 2^\mathbb{N}} \|\Pi_N g\|_{L^2}^2 \lesssim 1.$$

Please reword to avoid

- Batchelor's law should concern the second-order structure function $\mathbf{E}_{\mu^\kappa} \|\delta_\ell g\|_{L^2}^2$.
 However, as the scalar does not even remain a locally integrable function as $\kappa \rightarrow 0$, it is hard to make sense of exactly how the second-order structure function will behave in and at the limit $\kappa \rightarrow 0$; instead, this may require a suitable renormalization. Similarly, Yaglom's law on the L^2 flux (1.11) is hard to make sense of rigorously at the $\kappa = 0$ limit.

line overrun.

2 Preliminaries

2.1 Fluid models

Let $d = 2$ or 3 . We fix a real Fourier basis of $\mathbf{L}^2 = \{u \in L^2(\mathbb{T}^d, \mathbb{R}^d) : \int u \, dx = 0, \operatorname{div} u = 0\}$ as follows: for $m = (k, i) \in \mathbb{K} := \mathbb{Z}_0^d \times \{1, \dots, d-1\}$, we set

$$e_m(x) = \begin{cases} c_d \gamma_k^i \sin(k \cdot x), & k \in \mathbb{Z}_+^d, \\ c_d \gamma_k^i \cos(k \cdot x), & k \in \mathbb{Z}_-^d. \end{cases}$$

Here, $\mathbb{Z}_0^d := \mathbb{Z}^d \setminus \{0\}$, and $\mathbb{Z}_0^d = \mathbb{Z}_+^d \cup \mathbb{Z}_-^d$ is the partition defined by $\mathbb{Z}_+^d = \{k = (k^{(1)}, \dots, k^{(d)}) \in \mathbb{Z}_0^d : k^{(d)} > 0\} \cup \{k \in \mathbb{Z}_0^d : k^{(1)} > 0, k^{(d)} = 0\}$ and $\mathbb{Z}_-^d = -\mathbb{Z}_+^d$. For each $k \in \mathbb{Z}_0^d$, we have fixed a set $\{\gamma_k^i\}_{i=1}^{d-1}$ of orthonormal vectors spanning the complement of the line spanned by $k \in \mathbb{R}^d$; these are assumed to satisfy $\gamma_{-k}^i = -\gamma_k^i$. The coefficients $c_d > 0$ are normalization constants. Note that if $d = 2$, $\gamma_k = \gamma_k^1$ spans the perpendicular to k , and may therefore be taken to be $\gamma_k = k^\perp / |k|$, $k^\perp := (k^{(2)}, -k^{(1)})$.

In terms of this Fourier basis, we consider the white-in-time, spatially Sobolev stochastic forcing term

$$(2.1) \quad QW_t := \sum_{m \in \mathbb{K}} q_m e_m(x) W_t^m,$$

where W_t^m , $m \in \mathbb{K}$, are a family of independent standard one-dimensional Wiener processes with respect to the canonical stochastic basis $(\Omega_W, \mathcal{F}^W, (\mathcal{F}_t^W), \mathbf{P}_W)$.

The following decay and nondegeneracy assumption is made throughout this and our previous works [16–18].

ASSUMPTION 1. *There exists $\alpha > \frac{5d}{2}$ such that for all $m = (k, i) \in \mathbb{K}$, we have*

$$q_m \approx \frac{1}{|k|^\alpha}.$$

The state space for our fluid velocity fields is

$$\mathbf{H} := \left\{ u \in H^\sigma(\mathbb{T}^d, \mathbb{R}^d) : \int u \, dx = 0, \operatorname{div} u = 0 \right\},$$

where

$$\sigma \in \left(\alpha - 2(d-1), \alpha - \frac{d}{2} \right).$$

Note that by our choice of α , we have $\sigma > \frac{d}{2} + 3$, so $\mathbf{H} \hookrightarrow C^3$. We will write the Navier-Stokes system as an abstract evolution equation on $\mathbf{H}$ by

$$(2.2) \quad \partial_t u + B(u, u) + Au = Q\dot{W} = \sum_{m \in \mathbb{K}} q_m e_m \dot{W}^m,$$

where

$$B(u, v) = (\operatorname{Id} - \nabla(-\Delta)^{-1}\nabla) \cdot \nabla \cdot (u \otimes v)$$

$$Au = \begin{cases} -\nu \Delta u & \text{if } d = 2, \\ -\nu' \Delta u + \nu \Delta^2 u & \text{if } d = 3. \end{cases}$$

The (u_t) process with initial data u is defined as the solution to (2.2) in the mild sense [34, 74]:

$$(2.3) \quad u_t = e^{-tA}u - \int_0^t e^{-(t-s)A} B(u_s, u_s) ds + \int_0^t e^{-(t-s)A} Q dW(s),$$

where the above identity holds $\mathbf{P}_W$ almost surely for all $t > 0$. We have the following well-posedness theorem:

PROPOSITION 2.1 ([34, 74]). *Let $d = 2$ or 3 . Under Assumption 1 for all initial $u \in \mathbf{H} \cap \mathbf{H}^{\sigma'}$ with $\sigma' < \alpha - \frac{d}{2}$ and all $T > 0$, $p \geq 1$, there exists a $\mathbf{P}_W$ -a.s. unique solution (u_t) to (2.3) that is $\mathcal{F}_t^W$ -adapted, and belongs to*

$$L^p(\Omega_W; C([0, T]; \mathbf{H} \cap \mathbf{H}^{\sigma'})) \cap L^2(\Omega_W; L^2(0, T; \mathbf{H}^{\sigma' + (d-1)})).$$

Additionally, for all $p \geq 1$ and $0 \leq \sigma' < \sigma'' < \alpha - \frac{d}{2}$,

$$\begin{aligned} \mathbf{E}_W \sup_{t \in [0, T]} \|u_t\|_{\mathbf{H}^{\sigma'}}^p &\lesssim_{T, p, \sigma'} 1 + \|u\|_{\mathbf{H} \cap \mathbf{H}^{\sigma'}}^p \\ \mathbf{E}_W \int_0^T \|u_s\|_{\mathbf{H}^{\sigma' + (d-1)}}^2 ds &\lesssim_{T, \delta} 1 + \|u\|_{\mathbf{H}^{\sigma'}}^2 \\ \mathbf{E}_W \sup_{t \in [0, T]} \left(t^{\frac{\sigma'' - \sigma'}{2(d-1)}} \|u_t\|_{\mathbf{H}^{\sigma''}} \right)^p &\lesssim_{p, T, \sigma', \sigma''} 1 + \|u\|_{\mathbf{H}^{\sigma'}}^p. \end{aligned}$$

PROPOSITION 2.2. *Under Assumption 1 the process (u_t) solving (2.2) admits a unique stationary measure μ .*

Proposition 2.2 was first proved for $d = 2$ in [53] under Assumption 1; the generalization to $d = 3$ is a straightforward extension.

Remark 2.3. Uniqueness of stationary measures is known for Navier-Stokes under much weaker nondegeneracy conditions than Assumption 1, e.g., the *truly hypoelliptic* setting of [60] with $d = 2$ that only requires to force modes $|m|_\infty \leq 1$. However, Assumption 1 is necessary for the Lagrangian chaos and scalar mixing results in [16–18] because our methods require, for now, strong Feller regularity of the semigroup $t \mapsto u_t$. See remark 2.6 in [16] and remark 2.19 in [17] for more discussion.

Because we require Assumption 1, we do not know how to extend our results to fluid models solving the Navier-Stokes equations that are spatially C^∞ or differentiable in time. However, we are able to apply our results to a class of finite-dimensional fluid models for which solutions are $C_t^k C_x^\infty$. This is the subject of the following short section.

2.2 $C_t^k C_x^\infty$ fluid models governed by finite-dimensional SDE

If the fluid evolves according to a finite-dimensional SDE, then the methods involved are significantly simpler at a technical level and the strength of Hörmander's theorem [63] allows us to impose much weaker conditions on the noise models we consider. Consequently, we can produce fluid models which have better spatial and time regularity.

Below, for QW_t given by (2.1), we define $\mathcal{K}_0 = \{m \in \mathbb{K} : q_m \neq 0\}$. For $m = (k, i) \in \mathbb{K} = \mathbb{Z}_0^d \times \{1, \dots, d-1\}$, we define $|m|_\infty = \max_j |k^{(j)}|$.

For the following finite-dimensional stochastic fluids models we will make the following less restrictive assumption to Assumption 1.

ASSUMPTION 2. Assume $m \in \mathcal{K}_0$ if $|m|_\infty \leq 2$.

For $\mathcal{K} \subset \mathbb{K}$ we define $\mathbf{H}_{\mathcal{K}}$ to be the linear span of the Fourier modes $\{e_m\}_{m \in \mathcal{K}}$. One model we consider is the Stokes system on $\mathbb{T}^d$, $d = 2, 3$, prescribing the time evolution (u_t) on the state space $\mathbf{H}_{\mathcal{K}_0}$ for fixed initial $u_0 \in \mathbf{H}_{\mathcal{K}_0}$ by

$$(2.4) \quad \begin{aligned} \partial_t u_t &= -\nabla p_t + \Delta u_t + Q \dot{W}_t \\ \operatorname{div} u_t &= 0. \end{aligned}$$

When $\mathcal{K}_0$ is finite, (2.4) is a finite-dimensional SDE on $\mathbf{H}_{\mathcal{K}_0} \cong \mathbb{R}^{|\mathcal{K}_0|}$; indeed, it is essentially a product of independent Ornstein-Uhlenbeck processes on $\mathbb{R}^{|\mathcal{K}_0|}$, and in particular an elliptic diffusion on $\mathbb{R}^{|\mathcal{K}_0|}$.

For $N \geq 1$ we define $\mathbf{H}_N \subset \mathbf{H}$ to be the linear span of the e_m with $|m|_\infty \leq N$. Define $\Pi_{\leq N} : \mathbf{H} \rightarrow \mathbf{H}_N$ to be the orthogonal projection. Another model we consider for (u_t) is the Galerkin-Navier-Stokes system, defined for fixed $u_0 \in \mathbf{H}_N$ by

$$(2.5) \quad \begin{aligned} \partial_t u_t &= -\Pi_{\leq N}(\nabla p_t + u_t \cdot \nabla u_t) + \nu \Delta u_t + Q \dot{W}_t \\ \operatorname{div} u_t &= 0, \end{aligned}$$

where implicitly we assume that $q_m \neq 0$ only if $|m|_\infty \leq N$. As with the Stokes system, Galerkin-Navier-Stokes is an SDE on the finite-dimensional space $\mathbf{H}_N$; under Assumption 2, equation (2.5) is known to satisfy the parabolic Hörmander condition [43, 95], and so results in a hypoelliptic diffusion.

Standard finite-dimensional stochastic analysis [75] applies to both (2.4) and (2.5), yielding velocity field processes (u_t) that are $C^{1/2-}$ in time and spatially C^∞ . In addition to these, our methods also apply to a class of models including those that vary C^k in time for any fixed $k \geq 1$. These models are effectively driven by the projection of a coupled system of Ornstein-Uhlenbeck processes. More precisely: fix $2 \leq N \leq M$ and let $\mathcal{A} : \mathbf{H}_M \times \mathbf{H}_M$ be diagonalizable with strictly positive spectrum. Let

$$\Gamma W_t = \sum_{|m|_\infty \leq M} \Gamma_m e_m W_t^m,$$

and let $X : \mathbf{H}_N \times \mathbf{H}_N \rightarrow \mathbf{H}_N$ be a bilinear mapping with $u \cdot X(u, u) = 0$ and $X(e_m, e_m) = 0$ for all $|m|_\infty \leq N$. We consider the following *generalized Galerkin-Navier-Stokes system with OU tower noise*, defined by

$$(2.6) \quad \begin{aligned} \partial_t u_t &= -X(u_t, u_t) + \nu \Delta u_t + Q Z_t \\ \partial_t Z_t &= -\mathcal{A} Z_t + \Gamma W_t. \end{aligned}$$

Here, the noise term applied to the (u_t) process is

$$Q Z_t := \sum_{|m|_\infty \leq N} q_m Z_t^m e_m(x),$$

where $t \mapsto Z_t^m \in \mathbb{R}$ are the Fourier coefficients of Z_t , i.e.,

$$Z_t(x) = \sum_m Z_t^m e_m(x).$$

Note that (u_t) is not a Markov process, but (Z_t) alone and (u_t, Z_t) are. The appropriate nondegeneracy assumption in this setting is as follows:

ASSUMPTION 3. Assume that the coefficients $\{q_m\}$ satisfy Assumption 2 and additionally that the parabolic Hörmander condition holds for the (u_t, Z_t) process on $\mathbf{H}_N \times \mathbf{H}_M$.

THEOREM 2.4. All of the main results in Section 1.3 hold whenever (u_t) evolves according to (2.4) or (2.5) under Assumption 2 or (2.6) under Assumption 3.

Remark 2.5 (see remark 1.10 in [17]). Consider the following example of a system in the setting of (2.6). Fix $n \geq 1$ and consider the model

$$(2.7) \quad u_t(x) = \sum_{|m|_\infty \leq 2} u_t^m e_m(x),$$

where the coefficients u_t^m evolve according to

$$\begin{aligned} \partial_t u_t^m &= -u_t^m + Z_t^{m,0}, \\ \partial_t Z_t^{m,\ell} &= -Z_t^{m,\ell} + Z_t^{m,\ell+1} \quad 1 \leq \ell \leq n-1 \\ \partial_t Z_t^{m,n} &= -Z_t^{m,n} + \dot{W}_t^m. \end{aligned}$$

Up to re-indexing, this fits into the framework of (2.6) with $X \equiv 0$. The parabolic Hörmander condition for (u_t, Z_t) is satisfied, and so Theorem 2.4 holds for (u_t) as above. Notably, solutions (u_t) to (2.7) are C^{n+1} -differentiable in time and smooth (indeed, analytic) in space. The authors hope this serves as an indication that although the methods in this paper rely strongly on the stochastic framework, they are not inherently restricted to the rough time regularity of white-in-time noise.

Going forward, we will assume (u_t) solves (2.2) with Assumption 1 for the remainder of the paper. The application of these arguments to the finite-dimensional models (2.4), (2.5), and (2.6) is straightforward and omitted for brevity.

2.3 Lyapunov functions and exponential estimates

The results in our previous series of papers [17, 18] require the use of the family of Lyapunov functions

$$(2.8) \quad V(u) = V_{\beta, \eta}(u) := (1 + \|u\|_{\mathbf{H}}^2)^\beta e^{\eta \|u\|_{\mathbf{W}}^2}$$

where $\beta \geq 0, \eta > 0$. Here, for velocity fields u we define

$$\|u\|_{\mathbf{W}} := \begin{cases} \|\operatorname{curl} u\|_{L^2}, & d = 2, \\ \|u\|_{L^2}, & d = 3. \end{cases}$$

Below, we formulate a drift condition for the family $V = V_{\beta, \eta}$, ensuring that trajectories of the (u_t) process frequently visit the sublevel sets of V . Define $\eta_* = v/\mathcal{Q}$, where

$$\mathcal{Q} = 64 \begin{cases} \sup_{m \in \mathbb{K}} |k| |q_m|, & d = 2, \\ \sup_{m \in \mathbb{K}} |q_m|, & d = 3. \end{cases}$$

LEMMA 2.6 (Lemma 3.7 in [17]). *Let (u_t) be a solution to the stochastic Navier-Stokes equations (2.2) with initial data $u \in \mathbf{H}$. For all $0 \leq \gamma < v/8, r \in (0, 3), C_0 \geq 0$, and $V(u) = V_{\beta, \eta}$ where $\beta \geq 0$ and $0 < e^{\gamma T} \eta < \eta_*$, there exist constants $c = c(\gamma, r, C_0, \beta, \eta) > 0, C = C(\gamma, r, C_0, \beta, \eta) \geq 1$, such that the following estimate holds for any $T > 0$:*

$$(2.9) \quad \mathbf{E}_W \exp \left(C_0 \int_0^T \|u_s\|_{\mathbf{H}^r} ds \right) \sup_{0 \leq t \leq T} V^{e^{\gamma t}}(u_t) \leq C e^{cT} V(u).$$

Remark 2.7. To connect (2.9) with more standard drift conditions given in, e.g., [82], write P_1 for the Markov semigroup for the Navier-Stokes process (u_t) and apply Jensen's inequality to (2.9) to deduce that $\exists C_L > 0$ such that $P_1 V \leq (e^{C_L} V)^{e^{-\gamma}}$. In particular, we have the following drift condition:

$$\forall \delta > 0, \exists C_\delta > 0 \quad \text{such that} \quad P_1 V \leq \delta V + C_\delta.$$

Note that the contraction constant $\delta > 0$ above can be made *arbitrarily small*. Iterating this bound, it is straightforward to show that $\forall \lambda > 0, \exists K_\lambda$ such that for all $t > 0$ there holds

$$(2.10) \quad P_t V \leq e^{-\lambda t} V + K_\lambda.$$

We will also need the following basic stability estimate for solutions to the Navier-Stokes equations.

LEMMA 2.8. *For all $u, u' \in \mathbf{H}$, let (u_t) and (u'_t) be the corresponding solutions with the same noise path ω . Then $\forall p \in [1, \infty)$, there exists a deterministic $K > 0$ such that the following stability estimate holds for $V(u)$ as in (2.8),*

$$\mathbf{E} \|u_t - u'_t\|_{\mathbf{H}}^p \lesssim_p e^{pKt} (V(u)^p + V(u')^p) \|u - u'\|_{\mathbf{H}}^p.$$

PROOF. Define $w_t = u_t - u'_t$,

$$\partial_t w_t + B(u_t, w_t) + B(w_t, u'_t) + A w_t = 0.$$

The proof proceeds as a variation of, e.g., [17, lemma 3.10]. Analogous to the calculations therein we have for some $C > 0$ and some $r \in (\frac{d}{2} + 1, 3)$

$$\|w_t\|_{\mathbf{W}} \leq \exp\left(C \int_0^t \|u_\tau\|_{H^r} + \|u'_\tau\|_{H^r} d\tau\right) \|u - u'\|_{\mathbf{W}}$$

and for some $q, C > 0$ (possibly a different C),

$$\begin{aligned} \|w_t\|_{\mathbf{H}}^2 &\lesssim \exp\left(C \int_0^t \|u_\tau\|_{H^r} + \|u'_\tau\|_{H^r} d\tau\right) \\ &\quad \times \left(\sup_{0 \leq s \leq t} (\|u_s\|_{\mathbf{H}}^q + \|u'_s\|_{\mathbf{H}}^q)\right) \|u - u'\|_{\mathbf{H}}^2. \end{aligned}$$

The result then follows from Lemma 2.6. $\square$

2.4 Uniform mixing and enhanced dissipation

In this section we will summarize the results of [16–18], which are used to prove Batchelor's law (Theorem 1.3) and the other results of this paper. Throughout, assume (u_t) solves (2.2) and that Assumption 1 holds. Consider the advection-diffusion equation with diffusivity $0 \leq \kappa \ll 1$,

$$(2.11) \quad \partial_t \bar{g}_t + u_t \cdot \nabla \bar{g}_t = \kappa \Delta \bar{g}_t$$

for fixed initial $\bar{g}_0 = g \in L^2$, $\int g dx = 0$. This defines the following (random) two-parameter semigroup of linear operators on L^2 : for $0 \leq s \leq t$, $\omega \in \Omega_W$, and initial $u = u_0 \in \mathbf{H}$, define $S_{t,s}^\kappa(\omega, u) : L^2 \rightarrow L^2$, the two-time solution operator satisfying $\bar{g}_t = S_{t,s}^\kappa(\omega, u) \bar{g}_s$. When starting from $s = 0$ we will write $S_t^\kappa(\omega, u) = S_{t,0}^\kappa(\omega, u)$. Note that $S_0^\kappa(\omega, u) = I$, the identity on L^2 . Note as well the following cocycle property: for any $s, t > 0$, we have

$$S_{t+s}^\kappa(\omega, u) = S_s^\kappa(\theta_t \omega, u_t) S_t^\kappa(\omega, u),$$

where $\theta_t : \Omega_W \rightarrow \Omega_W$ is the standard time-shift on Wiener space defined for each $\omega \in \Omega_W$ by

$$\theta_t \omega(\cdot) := \omega(\cdot + t) - \omega(t).$$

This implies that we can write the two-parameter semigroup $S_{t,s}(\omega, u)$ as

$$(2.12) \quad S_{t,s}^\kappa(\omega, u) = S_t^\kappa(\theta_s \omega, u_s).$$

Note that for any $p \geq 1$, S_t^κ extends in a natural way to a defined mapping on L^p , with range contained in L^p . The same is true of Sobolev spaces H^s , $s > 0$.

Several of the important results in this section involve random constants of the form $D : \Omega_W \times \mathbf{H} \rightarrow \mathbb{R}_{\geq 1}$, the $\mathbf{P}$ -law of which are controlled in terms of $V(u)$. Since random constants of this type appear many times in this paper, we introduce the following definition.

DEFINITION 2.9. Let $D : \Omega_W \times \mathbf{H} \rightarrow \mathbb{R}_{\geq 1}$ be measurable. We say that D has V bounded p^{th} moment if $\exists \beta \geq 0$ such that $\forall 0 < \eta < \eta_*$ we have for $V = V_{\beta, \eta}(u)$

$$\mathbf{E} D^p(\cdot, u) \lesssim_{\eta} V(u).$$

The following lemma is very important since it provides us some control on the fluctuations of the mixing time in terms of the Lyapunov function $V(u)$.

LEMMA 2.10. Let $D : \Omega_W \times \mathbf{H} \rightarrow [1, \infty)$ have V -bounded p^{th} moment. Then, $\forall \lambda > 0$, $\exists K_{\lambda} > 0$ such that

$$(2.13) \quad \mathbf{E} D^p(\theta_t \omega, u_t) \lesssim_{p, \lambda} e^{-\lambda t} V(u) + K_{\lambda}.$$

PROOF. Using, in sequence, the tower property of conditional expectation, the fact that u_t is $\mathcal{F}_t^W$ -measurable and the increment $\theta_t \omega$ is independent of $\mathcal{F}_t^W$ and equations (2.13) and (2.10), we have:

$$\mathbf{E} D^p(\theta_t \omega, u_t) = \mathbf{E}(\mathbf{E}[D^p(\theta_t \omega, u_t) | \mathcal{F}_t^W]) \lesssim \mathbf{E} V(u_t) \lesssim e^{-\lambda t} V(u) + K_{\lambda}. \quad \square$$

The following lemma is a useful corollary of (2.9).

LEMMA 2.11. For all $p \in [1, \infty)$, there exists a (deterministic) $C_0 > 0$ and a random constant $D_0 : \mathbf{H} \times \Omega_W \rightarrow \mathbb{R}_{\geq 1}$ with V -bounded p^{th} moment such that

$$\exp\left(\int_0^t \|\nabla u_{\tau}\|_{L^{\infty}} d\tau\right) \leq D_0(\omega, u) e^{C_0 t}.$$

PROOF. We provide the proof when $p = 1$; other values of p require straightforward adjustments.

Set $V = V_{0, \eta}$, where $\eta \in (0, \eta_*)$ is arbitrary. To start, note that by Lemma 2.6 and Chebyshev's inequality, $\exists c = c(\eta) > 0$ such that

$$\begin{aligned} \mathbf{P}\left(\exp\left(2 \int_0^t \|\nabla u_s\|_{L^{\infty}} ds\right) > V(u) e^{4ct}\right) &\leq \frac{\mathbf{E} \exp\left(2 \int_0^t \|\nabla u_s\|_{L^{\infty}} ds\right)}{V(u) e^{4ct}} \\ &\lesssim_{\eta} e^{-3ct}. \end{aligned}$$

By Borel-Cantelli, there exists $N(\omega, u) \geq 1$ with $\mathbf{P}(N(\cdot, u) \geq n) \lesssim_{\eta} e^{-3cn}$ such that

$$\exp\left(\int_0^n \|\nabla u_s\|_{L^{\infty}} ds\right) \leq V(u) e^{4cn} \quad \text{for } n \geq N(\omega, u).$$

To bound when $n < N(\omega, u)$, we find

$$\exp\left(\int_0^n \|\nabla u_s\|_{L^{\infty}} ds\right) \leq D_0(\omega, u) := \exp\left(\int_0^{N(\omega, u)} \|\nabla u_s\|_{L^{\infty}} ds\right)$$

and note that by Cauchy-Schwarz,

$$\begin{aligned} \mathbf{E} D_0(\cdot, u) &\leq \sum_n (\mathbf{P}(N = n))^{1/2} \left[\mathbf{E} \exp\left(2 \int_0^n \|\nabla u_s\|_{L^{\infty}} ds\right) \right]^{1/2} \\ &\leq \sum_n (e^{-3cn})^{1/2} (V(u) e^{4cn})^{1/2} \leq V(u) \sum_n e^{-cn} \lesssim V(u). \quad \square \end{aligned}$$

With these preparations in place, we now state the main results of [16–18].

THEOREM 2.12 (Theorem 1.2 in [18]). *There exists $\kappa_0 > 0$ for which the following holds for all $\kappa \in [0, \kappa_0]$. Let (u_t) solve (2.2) for an arbitrary initial condition $u_0 = u \in \mathbf{H}$. For all $s > 0$, $p \geq 1$, there exists a deterministic $\gamma = \gamma(s, p) > 0$ (depending only on s , p , and the parameters Q , ν , etc.) and a random constant $D_\kappa(\omega, u) : \Omega \times \mathbf{H} \rightarrow [1, \infty)$ (also depending on p , s , as well as κ) such that for all $g \in H^s$,*

$$\|S_t^\kappa(\omega, u)g\|_{H^{-s}} \leq D_\kappa(\omega, u)e^{-\gamma t}\|g\|_{H^s}.$$

The random constant D_κ has V -bounded p^{th} moment with implicit constant independent of κ .

Theorem 2.12 is proved in [17] for $\kappa = 0$ and [18] for $\kappa \in [0, \kappa_0]$. Both papers rely heavily on Lagrangian chaos as proved in [16]. From Theorem 2.12, it is relatively straightforward to prove the following enhanced dissipation result.

THEOREM 2.13 (Theorem 1.3 in [18]). *Let $\kappa_0 > 0$ and $\gamma = \gamma(1, p)$ be as in Theorem 2.12 where $p \geq 2$ is arbitrary. Let (u_t) solve (2.2) for an arbitrary initial condition $u_0 = u \in \mathbf{H}$. Then, there is a random constant $D'_\kappa(\omega, u)$ such that for all $g \in L^2$*

$$\|S_t^\kappa(\omega, u)g\|_{L^2} \leq \min\{1, D'_\kappa(\omega, u)\kappa^{-1}e^{-\gamma t}\}\|g\|_{L^2}.$$

The random constant D'_κ has V -bounded p^{th} moment with implicit constant independent of κ .

THEOREM 2.14 (Theorem 1.5 in [18]). *In the setting of Theorem 2.12 let*

$$\tau_* = \tau_*(\omega, u, g) = \inf\{t : \|g_t\|_{L^2} < \frac{1}{2}\|g\|_{L^2}\}.$$

Then, there exists a $\kappa_0 > 0$, a sufficiently small universal constant such that for all $\kappa \in (0, \kappa_0]$, one has

$$\tau_*(\omega, u, g) \geq \delta(g, u, \omega)|\log \kappa| \quad \text{with probability 1,}$$

where $\delta(g, u, \omega) \in (0, 1)$ is a κ -independent random constant with the property that there exists a $\beta \geq 1$ such that for all $p \geq 1$ and $\eta > 0$ with $V(u) = V_{\beta, \eta}(u)$ we have

$$\mathbf{E}\delta^{-p}(\cdot, u) \lesssim_{p, \eta, \beta} \frac{\|g\|_{H^1}^p}{\|g\|_{L^2}^p} V(u)^p.$$

2.5 Unique stationary measure for (u_t, g_t^κ)

We provide here an argument proving uniqueness of the stationary measure for the passive scalar process (u_t, g_t^κ) on $\mathbf{H} \times L^2$. The following argument is quite general and applies in a variety of cases outside the scope of the main results; see Remark 2.16 below.

PROPOSITION 2.15. *For any $\kappa > 0$, the Markov process (u_t, g_t^κ) admits a unique stationary measure μ^κ on $\mathbf{H} \times L^2$.*

PROOF. It suffices to show that any two ergodic stationary measures $\mu_1^\kappa, \mu_2^\kappa$ for (u_t, g_t^κ) coincide. By standard ergodic theory for random dynamical systems [70] and the ergodic decomposition theorem (see, e.g., [44]), uniqueness of ergodic stationary measures for (u_t, g_t^κ) implies uniqueness of stationary measures.

Assume now that μ_i^κ are two ergodic stationary measures, $i = 1, 2$. To prove $\mu_1^\kappa = \mu_2^\kappa$, it suffices to show that for each bounded, globally Lipschitz $\psi : \mathbf{H} \times L^2 \rightarrow \mathbb{R}$, we have that $\int \psi d\mu_1^\kappa = \int \psi d\mu_2^\kappa$. Without loss of generality, we can assume $\|\psi\|_{\text{Lip}} = 1$.

By ergodicity of μ_i^κ and the Birkhoff ergodic theorem, we have the following for $i = 1, 2$: there is a set $\hat{\mathcal{G}}_i = \hat{\mathcal{G}}_i(\psi) \subset \mathbf{H} \times L^2$ of full μ_i^κ -measure such that for all initial $(u, g) \in \hat{\mathcal{G}}_i$, we have

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{t=0}^{n-1} \psi(u_t, g_t^\kappa) = \int \psi d\mu_i^\kappa$$

with probability 1. Next, observe that μ_i^κ projects to the unique stationary measure μ for the (u_t) process (Proposition 2.2). It follows from Fubini's theorem that for $i = 1, 2$, we have $\mu(\mathcal{G}_i) = 1$, where $\mathcal{G}_i$ is the projection of $\hat{\mathcal{G}}_i$ to $\mathbf{H}$, i.e., $\mathcal{G}_i = \{u \in \mathbf{H} : \exists g \in L^2 \text{ such that } (u, g) \in \hat{\mathcal{G}}_i\}$. Since $\mu(\mathcal{G}_i) = 1$, $i = 1, 2$, we conclude that $\mathcal{G}_1 \cap \mathcal{G}_2$ is nonempty. Fix $u \in \mathcal{G}_1 \cap \mathcal{G}_2$ and let $g, h \in L^2$ be such that $(u, g) \in \hat{\mathcal{G}}_1$, $(u, h) \in \hat{\mathcal{G}}_2$. Observe that

$$g_t - h_t = S_t^\kappa(\omega, u)(g - h),$$

i.e., $g_t - h_t$ solves (2.11). Theorem 2.13 implies $\|g_t - h_t\|_{L^2} \rightarrow 0$ as $t \rightarrow \infty$. Given $\delta > 0$, let $N_0 = N_0(\delta')$ be such that $\|g_t - h_t\|_{L^2} < \delta$ for all $t \geq N_0$.

With these preparations in place, fix $u \in \mathcal{G}_1 \cap \mathcal{G}_2$ and $g, h \in L^2$ such that $(u, g) \in \hat{\mathcal{G}}_1$, $(u, h) \in \hat{\mathcal{G}}_2$. With $\delta > 0$ as above, let $N_0 = N_0(\delta)$. We have

$$\begin{aligned} \left| \int \psi d\mu_1^\kappa - \int \psi d\mu_2^\kappa \right| &\leq \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{t=0}^{n-1} |\psi(u_t, g_t^\kappa) - \psi(u_t, h_t^\kappa)| \\ &= \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{t=N_0}^{n-1} |\psi(u_t, g_t^\kappa) - \psi(u_t, h_t^\kappa)|. \end{aligned}$$

Each summand on the RHS is $\leq \delta$, and so the whole limit is $\leq \delta$. Since $\delta > 0$ was arbitrary, this completes the proof. $\square$

Remark 2.16. The proof given above has two main ingredients: (1) uniqueness for the stationary measure μ on $\mathbf{H}$, and (2) L^2 dissipation estimates for $S_t^\kappa(\omega, u)$ for $\kappa > 0$. Item (1) is known to hold for 2D Navier-Stokes under a very weak nondegeneracy condition on the noise [60], while item (2) holds for a wide variety of fluid models by standard estimates. Thus, the proof given above is applicable at

a much higher level of generality than that of Assumption [1](#), including the setting of 2D Navier-Stokes with “truly hypoelliptic” forcing as in [\[60\]](#).

3 Proof of Batchelor's Law

In this section we prove the main result of this paper, Theorem [1.3](#). To summarize the main approach, observe that by uniqueness of the stationary measure μ^κ for [\(1.3\)](#) (Proposition [2.15](#)), the Birkhoff ergodic theorem implies

$$\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^2 = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \|\Pi_{\leq N} g_t^\kappa\|_{L^2}^2 dt$$

for μ^κ -generic initial $u = u_0 \in \mathbf{H}$, $g = g_0^\kappa \in L^2$. On the other hand, the mild formulation for [\(1.3\)](#) reads as

$$(3.1) \quad g_t^\kappa = S_t^\kappa(\omega, u)g + \int_0^t S_{t,s}^\kappa(\omega, u)b d\beta_s.$$

Using the fact that

$$\mathbf{E}_\beta \left\langle S_t^\kappa(\omega, u)g, \int_0^t \Pi_{\leq N} S_{t,s}^\kappa(\omega, u)b d\beta_s \right\rangle_{L^2} = 0$$

results in the identity

$$(3.2) \quad \begin{aligned} \mathbf{E} \|\Pi_{\leq N} g_t^\kappa\|_{L^2}^2 &= \mathbf{E} \|\Pi_{\leq N} S_t^\kappa(\omega, u)g\|_{L^2}^2 \\ &\quad + \mathbf{E} \int_0^t \|\Pi_{\leq N} S_{t,s}^\kappa(\omega, u)b\|_{L^2}^2 ds \end{aligned}$$

after taking an L^2 norm in $\mathbb{T}^d$, then an expectation, and finally the Itô isometry. By Theorem [2.13](#), the first such term vanishes exponentially fast in L^2 as $t \rightarrow \infty$, and so it is the second term that dominates the long-time behavior of $\mathbf{E} \|g_t^\kappa\|_{L^2}^2$, hence the value of $\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^2$. While the above is stated for $p = 1$, the case $p > 1$ is handled similarly using the Burkholder-Davis-Gundy inequality.

The upper bound for [\(1.6\)](#) in the inertial range is carried out in Section [3.1](#), and the lower bound in Section [3.2](#). The dissipative-range upper bound is done in Section [3.3](#).

3.1 Upper bound in the inertial range

In this section we prove the $\lesssim$ direction of [\(1.6\)](#), that is:

LEMMA 3.1. *Under the conditions of Theorem [1.3](#), there holds for all $p \in [1, \infty)$ and for all $2 \leq N < \infty$,*

$$(3.3) \quad (\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^{2p})^{1/p} \lesssim_p \log N.$$

We begin with the following lemma.

LEMMA 3.2. *For all $p \in [1, \infty)$ and $2 \leq N < \infty$,*

$$\limsup_{t \rightarrow \infty} \int_0^t (\mathbf{E} \|\Pi_{\leq N} S_{t,\tau}^\kappa(\omega, u)b\|_{L^2}^{2p})^{1/p} d\tau \lesssim_p \log N.$$

PROOF. Recall that $\|\Pi_{\leq N} h\|_{L^2} \lesssim N \|\Pi_{\leq N} h\|_{H^{-1}}$ for $h \in L^2$. By (2.12) and Theorem 2.12 followed by Lemma 2.10,

$$\begin{aligned} & \int_0^t (\mathbf{E} \|\Pi_{\leq N} S_{t,\tau}^\kappa(\omega, u)b\|_{L^2}^{2p})^{1/p} d\tau \\ &= \int_0^t (\mathbf{E} \|\Pi_{\leq N} S_{t-\tau}^\kappa(\theta_\tau \omega, u_\tau)b\|_{L^2}^{2p})^{1/p} d\tau \\ &\lesssim \int_0^t (\mathbf{E} D^{2p}(\theta_\tau \omega, u_\tau))^{1/p} \min(1, N^2 e^{-2\lambda(t-\tau)}) d\tau \\ &\lesssim \int_0^t (e^{-\lambda\tau} V(u) + K_\lambda) \min(1, N^2 e^{-2\lambda(t-\tau)}) d\tau \\ &\lesssim (e^{-\lambda t} V(u) + 1) \log N. \end{aligned}$$

The proof then follows by sending $t \rightarrow \infty$. $\square$

We are now ready to complete the proof of Lemma 3.1.

PROOF OF LEMMA 3.1. First observe that, for all $(u, g) \in \mathbf{H} \times L^2$ there holds by (3.1)

$$\|\Pi_{\leq N} g_t\|_{L^2}^{2p} \lesssim_p \|\Pi_{\leq N} S_t^\kappa(\omega, u)g\|_{L^2}^{2p} + \left\| \int_0^t \Pi_{\leq N} S_{t,\tau}^\kappa(\omega, u)b d\beta_\tau \right\|_{L^2}^{2p}.$$

From the initial data term, by Theorem 2.13, $\exists \lambda$ (depending on p) such that for a suitable V as in (2.8),

$$(\mathbf{E} \|\Pi_{\leq N} S_t^\kappa(\omega, u)g\|_{L^2}^{2p})^{1/p} \lesssim \kappa^{-1} V(u) e^{-\lambda t} \|g\|_{L^2}^2.$$

By Burkholder-Davis-Gundy (e.g., [34, theorem 5.2.4]) followed by Minkowski's inequality,

$$\begin{aligned} \mathbf{E} \left\| \int_0^t \Pi_{\leq N} S_{t,\tau}^\kappa(\omega, u)b d\beta_\tau \right\|_{L^2}^{2p} &\lesssim_p \mathbf{E} \left(\int_0^t \|\Pi_{\leq N} S_{t,\tau}^\kappa(\omega, u)\|_{L^2}^2 d\tau \right)^p \\ &\lesssim \left(\int_0^t (\mathbf{E} \|\Pi_{\leq N} S_{t,\tau}^\kappa(\omega, u)b\|_{L^2}^{2p})^{1/p} d\tau \right)^p. \end{aligned}$$

Hence, Lemma 3.2 implies

$$\limsup_{t \rightarrow \infty} (\mathbf{E} \|\Pi_{\leq N} g_t\|_{L^2}^{2p})^{1/p} \lesssim \log N.$$

By standard moment estimates (see, e.g., [74]), for all $p, \kappa > 0$, $\mathbf{E}_{\mu^\kappa} \|g\|_{L^2}^p < \infty$. Hence, by the Birkhoff ergodic theorem, for μ^κ -a.e. $(u, g) \in \mathbf{H} \times L^2$ we have

$$(\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^{2p})^{1/p} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T (\mathbf{E}_{(u,g)} \|\Pi_{\leq N} g_t\|_{L^2}^{2p})^{1/p} dt \lesssim \log N.$$

This completes the proof of Lemma 3.1 $\square$

3.2 Lower bound in the inertial range

In this section we prove the $\gtrsim$ direction of (1.6).

LEMMA 3.3. *Under the conditions of Theorem 1.3 there exists an $N_0 \geq 2$ chosen sufficiently large (depending on b and the fluid parameters only) such that for all $\kappa \in (0, \kappa_0]$ the following holds for all $p \in [1, \infty)$ and all $N \in [N_0, \kappa^{-1/2}]$:*

$$(\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^{2p})^{1/p} \gtrsim_p \log N.$$

We begin with the following, which follows from an H^1 energy estimate and Lemma 2.11

LEMMA 3.4. *There holds (with C_0 and D_0 as in Lemma 2.11)*

$$\|S_t^\kappa(\omega, u)g\|_{H^1} \leq D_0(\omega, u)e^{C_0 t} \|g\|_{H^1}.$$

The next lemma provides the lower bound on the stochastic integral contribution.

LEMMA 3.5. *There exists an $N_0 \geq 2$ chosen sufficiently large (depending on b and the fluid parameters only) such that for all $\kappa \in (0, \kappa_0]$ the following limit holds for all $N \in [N_0, \kappa^{-1/2}]$:*

$$\liminf_{t \rightarrow \infty} \int_0^t \mathbf{E} \|\Pi_{\leq N} S_{t-\tau}^\kappa(\omega, u)b\|_{L^2}^2 d\tau \gtrsim \log N.$$

PROOF. Fix $u \in \mathbf{H}$ and let $\gamma \in (0, 1)$ to be chosen later. Write for $t \geq \gamma \log N$ and $N \geq 2$,

$$\begin{aligned} & \int_0^t \|\Pi_{\leq N} S_{t-r}^\kappa(\theta_r \omega, u_r)b\|_{L^2}^2 dr \\ & \geq \int_{t-\gamma \log N}^t \|S_{t-r}^\kappa(\theta_r \omega, u_r)b\|_{L^2}^2 dr \\ & \quad - \int_{t-\gamma \log N}^t \|\Pi_{>N} S_{t-r}^\kappa(\theta_r \omega, u_r)b\|_{L^2}^2 dr. \end{aligned}$$

The first term is controlled by the H^1 norm growth bound in Lemma 3.4

$$\begin{aligned} & \mathbf{E} \int_{t-\gamma \log N}^t \|\Pi_{>N} S_{t-r}^\kappa(\theta_r \omega, u_r)b\|_{L^2}^2 dr \\ & \lesssim \int_{t-\gamma \log N}^t N^{-2} \mathbf{E} D_0^2(\theta_r \omega, u_r) e^{\lambda(t-r)} dr. \end{aligned}$$

By Lemma 2.10

$$\mathbf{E} D_0^2(\theta_r \omega, u_r) \lesssim e^{-\lambda r} V(u) + K_\lambda,$$

and hence, choosing $\gamma < \lambda^{-1}$, we have

$$\begin{aligned} & \limsup_{t \rightarrow \infty} \mathbf{E} \int_{t-\gamma \log N}^t \|\Pi_{>N} S_{t-r}^\kappa(\theta_r \omega, u_r) b\|_{L^2}^2 dr \\ & \lesssim \gamma N^{\gamma \lambda - 2} \log N \limsup_{t \rightarrow \infty} (e^{-\lambda t} V(u) + K_\lambda) \leq C_0 N^{-1} \gamma \log N \end{aligned}$$

for some constant C_0 universal independent of γ, κ, t, u . This completes the second term in (3.2).

For the first term in (3.2), we use the stopping time defined in Theorem 2.14 with initial data b :

$$\mathbf{E} \|S_{t-r}^\kappa(\theta_r \omega, u_r) b\|_{L^2}^2 \geq \frac{1}{2} \|b\|_{L^2}^2 \mathbf{P}(\tau_*(\theta_r \omega, u_r) > t - r),$$

where (analogously to Theorem 2.14) $\tau_*(\omega, u)$ is defined by

$$\tau_*(\omega, u) = \inf \left\{ t > 0 : \|S_t^\kappa(\omega, u) b\|_{L^2}^2 \leq \frac{\|b\|_{L^2}^2}{2} \right\}.$$

Theorem 2.14 then implies that $\exists C_1 > 0$ (independent of t, r, κ, u) and $\delta(\omega, u) : \Omega \times \mathbf{H} \rightarrow \mathbb{R}_{>0}$ with $\mathbf{E} \delta^{-1}(\cdot, u) \leq C_1 V(u)$ such that $\tau_* \geq \delta |\log \kappa|$. Using Chebyshev's inequality and an argument similar to that used to prove Lemma 2.10

$$\begin{aligned} \mathbf{P}(\tau_*(\theta_r \omega, u_r) > t - r) & \geq 1 - \mathbf{P}(\delta^{-1}(\theta_r \omega, u_r) > |\log \kappa|/(t - r)) \\ & \geq 1 - \frac{t - r}{|\log \kappa|} \mathbf{E}(\mathbf{E}(\delta^{-1}(\theta_r \omega, u_r) | \mathcal{F}_r)) \\ & \geq 1 - C_1 \frac{t - r}{|\log \kappa|} (e^{-\lambda r} V(u) + K_\lambda). \end{aligned}$$

It follows that for $2 \leq N \leq \kappa^{-1/2}$,

$$\begin{aligned} & \liminf_{t \rightarrow \infty} \mathbf{E} \int_{t-\gamma \log N}^t \|S_{t-r}^\kappa(\theta_r \omega, u_r) b\|_{L^2}^2 dr \\ & \geq \liminf_{t \rightarrow \infty} \frac{1}{2} \|b\|_{L^2}^2 \gamma \log N \left(1 - \frac{C_1 \gamma \log N}{2 |\log \kappa|} (e^{-\lambda t} V(u) + K_\lambda) \right) \\ & \geq \frac{1}{2} \|b\|_{L^2}^2 \gamma \log N \left(1 - \frac{C_1 K_\lambda \gamma}{4} \right). \end{aligned}$$

Therefore, for $K_\lambda C_1 \gamma < 1/8$ and $N > N_0 := 8C_0$,

$$\begin{aligned} \liminf_{t \rightarrow \infty} \mathbf{E} \int_0^t \|\Pi_{\leq N} S_{t-r}^\kappa(\theta_r \omega, u_r) b\|_{L^2}^2 dr & \gtrsim \left(1 - \frac{\gamma}{4} C_1 K_\lambda - 2C_0 N^{-1} \right) \log N \\ & \gtrsim \log N. \end{aligned}$$

□

PROOF OF LEMMA 3.3. By Jensen's inequality,

$$\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^{2p} \geq (\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^2)^p \quad \text{for } p \geq 1,$$

and so in the following argument it suffices to consider the $p = 1$ case. For arbitrary initial data $g \in L^2$, we have by (3.2) that

$$\mathbf{E} \|\Pi_{\leq N} g_t\|_{L^2}^2 \geq \mathbf{E} \int_0^t \|\Pi_{\leq N} S_{t-r}^\kappa(\theta_r \omega, u_r) b\|_{L^2}^2 dr,$$

hence $\liminf_{t \rightarrow \infty} \mathbf{E} \|\Pi_{\leq N} g_t\|_{L^2}^2 \gtrsim \log N$ by Lemma 3.5 for $N_0 < N < \kappa^{-1/2}$. By the Birkhoff ergodic theorem (as in Lemma 3.1 above),

$$\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g_t\|_{L^2}^2 = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \mathbf{E} \|\Pi_{\leq N} g_t\|_{L^2}^2 dt \gtrsim \log N.$$

This completes the proof of Lemma 3.3. $\square$

3.3 Upper bound in the dissipative range

First, we derive the upper bound on the L^2 norm stated in (1.7). If we were not also interested in higher moments we could use the following simple observation using the L^2 balance (1.4) and the upper bound in Batchelor's law, (3.3)

$$\mathbf{E}_{\mu^\kappa} \|g\|_{L^2}^2 \lesssim \mathbf{E}_{\mu^\kappa} \|\Pi_{\leq \kappa^{-1/2}} g\|_{L^2}^2 + \kappa \mathbf{E}_{\mu^\kappa} \|\Pi_{> \kappa^{-1/2}} \nabla g\|_{L^2}^2 \lesssim 1 + |\log \kappa|.$$

The following argument also provides estimates on moments $p > 2$.

LEMMA 3.6. *Under the conditions of Theorem 1.3, there holds for all $p \in [1, \infty)$ and for all $\kappa \in (0, \kappa_0]$*

$$(\mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^{2p})^{1/p} \lesssim_p |\log \kappa|.$$

PROOF. The proof proceeds similarly to that for Lemma 3.3 with the enhanced dissipation estimate (Theorem 2.13) in place of the uniform mixing estimate (Theorem 2.12). As in Lemma 3.3, by Burkholder-Davis-Gundy and Minkowski's inequality,

$$(\mathbf{E} \|g_t\|_{L^2}^{2p})^{1/p} \lesssim (\mathbf{E} \|S_t^\kappa(\omega, u) g\|_{L^2}^{2p})^{1/p} + \int_0^t (\mathbf{E} \|S_{t,\tau}^\kappa(\omega, u) b\|_{L^2}^{2p})^{1/p} d\tau.$$

By Theorem 2.13, $\exists \lambda > 0$ and $D'_\kappa(\omega, u)$ with V -bounded $2p^{\text{th}}$ moments, we have for any $(u, g) \in \mathbf{H} \times L^2$,

$$\begin{aligned} (\mathbf{E} \|g_t\|_{L^2}^{2p})^{1/p} &\lesssim (\mathbf{E} \|S_t^\kappa(\omega, u) g\|_{L^2}^{2p})^{1/p} + \int_0^t (\mathbf{E} \|S_{t,\tau}^\kappa(\omega, u) b\|_{L^2}^{2p})^{1/p} d\tau \\ &\lesssim (\mathbf{E} (D'_\kappa(\omega, u))^{2p})^{1/p} \kappa^{-1} e^{-\lambda t} \|g\|_{L^2}^2 \\ &\quad + \int_0^t (\mathbf{E} (D'_\kappa(\theta_\tau \omega, u_\tau))^{2p})^{1/p} \min(1, \kappa^{-1} e^{-\lambda(t-\tau)}) d\tau. \end{aligned}$$

By Lemma 2.10, we therefore have

$$\begin{aligned} (\mathbf{E} \|g_t\|_{L^2}^{2p})^{1/p} &\lesssim_p V(u) \kappa^{-1} e^{-\lambda t} \|g\|_{L^2}^2 \\ &\quad + \int_0^t (e^{-\lambda \tau} V(u) + 1) \min(1, \kappa^{-1} e^{-\lambda(t-\tau)}) d\tau \\ &\lesssim_p V(u) \kappa^{-1} e^{-\lambda t} (1 + \|g\|_{L^2}^2) + |\log \kappa|. \end{aligned}$$

Hence for all $(u, g) \in \mathbf{H} \times L^2$,

$$\limsup_{t \rightarrow \infty} \mathbf{E} \|g_t\|_{L^2}^{2p} \lesssim |\log \kappa|.$$

Finally, by the Birkhoff ergodic theorem, for μ^κ a.e. $(u, g) \in \mathbf{H} \times L^2$,

$$\mathbf{E}_{\mu^\kappa} \|g\|_{L^2}^{2p} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \mathbf{E}_{(u,g)} \|g_t\|_{L^2}^{2p} dt \lesssim |\log \kappa|^p. \quad \square$$

We now turn to the proof of (1.7) for $q > 0$, which is a relatively straightforward consequence of parabolic regularity and the L^2 a priori estimate in Lemma 3.6. First we prove the following quantitative H^s regularization estimate. Below we use the Fourier multiplier notation: for $m : \mathbb{C}^d \rightarrow \mathbb{R}$ measurable, we define the operator

$$m(\nabla) f = (m(ik) \hat{f}(k))^\vee.$$

LEMMA 3.7. *For all initial data $(u, g) \in \mathbf{H} \times L^2$, for all $\gamma \in (0, \alpha - d - 1)$, $\exists \beta \geq 0$, such that $\forall p \in [1, \infty)$ and $\forall \eta > 0$ there holds for $V = V_{\beta, \eta}$*

$$\mathbf{E} \|(1 + \sqrt{\kappa} \langle \nabla \rangle)^\gamma S_1^\kappa(\omega, u) g\|_{L^2}^p \lesssim_{p, \gamma} V^p(u) \|g\|_{L^2}^p.$$

PROOF. We first deduce a pathwise a priori estimate assuming g is sufficiently smooth. To this end, by Plancherel's identity we have for $t \in [0, 1]$,

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} \|(1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} g_t^\kappa\|_{L^2}^2 \\ &= \sum_{k \in \mathbb{Z}_*^d} (\gamma \log(1 + \sqrt{\kappa} \langle k \rangle) - \kappa |k|^2) (1 + \sqrt{\kappa} \langle k \rangle)^{2\gamma t} |\hat{g}_t^\kappa(k)|^2 \\ &\quad + \left\langle (1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} g_t^\kappa, (1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} \nabla \cdot (u_t g_t^\kappa) \right\rangle_{L^2} \\ &=: \mathcal{I}_1 + \mathcal{I}_2. \end{aligned}$$

For $\mathcal{I}_1$, by $\gamma \log(1 + x) \leq x^2 + C(\gamma)$,

$$\mathcal{I}_1 \lesssim_\gamma \|(1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} g_t^\kappa\|^2.$$

By incompressibility and Plancherel's identity,

$$\begin{aligned} \mathcal{I}_2 &= \langle (1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} g_t^\kappa, \\ &\quad (1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} \nabla \cdot (u_t g_t^\kappa) - \nabla \cdot (u_t (1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} g_t^\kappa) \rangle_{L^2} = \end{aligned}$$

$$\begin{aligned}
&= \sum_{k, \ell \in \mathbb{Z}_*^d} (1 + \sqrt{\kappa} \langle k \rangle)^{\gamma t} \widehat{g}_t^\kappa(k) ((1 + \sqrt{\kappa} \langle k \rangle)^{\gamma t} - (1 + \sqrt{\kappa} \langle k - \ell \rangle)^{\gamma t}) \\
&\quad \times i k \cdot \widehat{u}_t(\ell) \widehat{g}_t^\kappa(k - \ell) \\
&= \sum_{k, \ell \in \mathbb{Z}_*^d} (\mathbf{1}_{|k-\ell| \geq \frac{1}{2}|\ell|} + \mathbf{1}_{|k-\ell| < \frac{1}{2}|\ell|}) (1 + \sqrt{\kappa} \langle k \rangle)^{\gamma t} \widehat{g}_t^\kappa(k) \\
&\quad \times ((1 + \sqrt{\kappa} \langle k \rangle)^{\gamma t} - (1 + \sqrt{\kappa} \langle \ell \rangle)^{\gamma t}) i k \cdot \widehat{u}_t(k - \ell) \widehat{g}_t^\kappa(\ell) \\
&= \mathcal{I}_{2;\text{HL}} + \mathcal{I}_{2;\text{LH}}.
\end{aligned}$$

On the support of the $\mathcal{I}_{2;\text{HL}}$ (here HL stands for “high-low”), we use that $|k| + |\ell| \lesssim |k - \ell|$, together with Cauchy-Schwarz, Young’s inequality, and $H^r \hookrightarrow \widehat{L}^1$ for $r > \frac{d}{2}$ to deduce that for any $r \in (\frac{d}{2} + 1, 3)$,

$$|\mathcal{I}_{2;\text{HL}}| \lesssim \|(1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} g_t^\kappa\|_{L^2} \|g_t^\kappa\|_{L^2} \|(1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} u_t\|_{H^r}.$$

On the support of the $\mathcal{I}_{2;\text{LH}}$, we use the mean value theorem and $|k| \lesssim |\ell|$ to deduce

$$(1 + \sqrt{\kappa} \langle k \rangle)^{\gamma t} - (1 + \sqrt{\kappa} \langle k - \ell \rangle)^{\gamma t} \lesssim \sqrt{\kappa} \gamma t (1 + \sqrt{\kappa} \langle k - \ell \rangle)^{\gamma t - 1} |\ell|.$$

Therefore, by Cauchy-Schwarz, Young’s inequality, and $H^r \hookrightarrow \widehat{L}^1$ for $r > \frac{d}{2}$, for any $r \in (\frac{d}{2} + 1, 3)$ we have

$$|\mathcal{I}_{2;\text{LH}}| \lesssim \|u_t\|_{H^r} \|(1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} g_t^\kappa\|_{L^2}^2.$$

By Grönwall’s inequality, there is some $C > 0$ (independent of g, κ, u, t) such that the following holds:

$$\begin{aligned}
&\|(1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma t} g_t^\kappa\|_{L^2}^2 \\
&\leq \exp\left(Ct + \int_0^t \|u_\tau\|_{H^r} d\tau\right) \|g\|_{L^2}^2 \\
&\quad + \exp\left(Ct + \int_0^t \|u_\tau\|_{H^r} d\tau\right) \int_0^t \|(1 + \sqrt{\kappa} \langle \nabla \rangle)^{\gamma \tau} u_\tau\|_{H^r}^2 \|g_\tau\|_{L^2}^2 d\tau.
\end{aligned}$$

Taking expectations and applying Lemma 2.6 completes the a priori estimate (3.7). For an arbitrary $g \in L^2$, the desired result follows by density. $\square$

LEMMA 3.8. *Under the assumptions of Theorem 1.3 (1.7) holds.*

PROOF. By standard moment estimates (see, e.g., [74]), $\mathbf{E}_{\mu^\kappa} \|g\|_{H^s}^{2p} < \infty$ for $s \in [0, \sigma - \frac{3d}{2} - 1)$ and $p < \infty$. By stationarity,

$$\begin{aligned} \mathbf{E}_{\mu^\kappa} \|g\|_{H^s}^{2p} &= \int \mathbf{E}_{(u,g)} \|g_1^\kappa\|_{H^s}^{2p} d\mu^\kappa(u, g) \\ &\lesssim_p \int \mathbf{E} \|S_1^\kappa(\omega, u)g\|_{H^s}^{2p} d\mu^\kappa(u, g) \\ &\quad + \int \mathbf{E} \left\| \int_0^1 S_{1-\tau}^\kappa(\theta_\tau \omega, u_\tau) b d\beta_\tau \right\|_{H^s}^{2p} d\mu^\kappa(u, g). \end{aligned}$$

By Lemma 3.7, $\exists \beta \geq 0$ such that for $\forall \eta > 0$, $V = V_{\beta, \eta}$, and all $(u, g) \in \mathbf{H} \times L^2$,

$$\mathbf{E} \|S_1^\kappa(\omega, u)g\|_{H^s}^{2p} \lesssim \kappa^{-s p} V^p(u) \|g\|_{L^2}^{2p}.$$

Because $b \in C^\infty$, it follows from Burkholder-Davis-Gundy, Minkowski's inequality, and classical H^s estimates for the transport equation (together with Lemma 2.10) that $\exists \beta \geq 0$ such that $\forall \eta > 0$, there holds for suitable $V = V_{\beta, \eta}$,

$$\mathbf{E} \left\| \int_0^1 S_{1-\tau}^\kappa(\theta_\tau \omega, u_\tau) b d\beta_\tau \right\|_{H^s}^{2p} \lesssim \int_0^1 \mathbf{E} \|S_{1-\tau}^\kappa(\theta_\tau \omega, u_\tau) b\|_{H^s}^{2p} d\tau \lesssim V^p(u).$$

Therefore by Lemmas 3.6 and 3.7 and Hölder's inequality,

$$\mathbf{E}_{\mu^\kappa} \|g\|_{H^s}^{2p} \lesssim \mathbf{E}_{\mu^\kappa} [V^p(u) (1 + \kappa^{-s p} \|g\|_{L^2}^{2p})] \lesssim_p \kappa^{-s p} |\log \kappa|^p.$$

This completes the proof of (1.7). $\square$

4 Vanishing Diffusivity Limit

This section is devoted to the proof of Theorem 1.12 describing weak limits of the stationary measures μ^κ for the passive scalar process (u_t, g_t^κ) . In Section 4.1 we show that such weak limits exist in the weak topology of measures on $\mathbf{H} \times H^{-s}$ and satisfy Batchelor's law (1.13) over an infinite inertial range.

Once these are established, it remains to show that μ^0 is a stationary measure for the passive scalar process (u_t, g_t^0) . As we check in Section 4.2, the latter can be extended to a Markov process defined by a random dynamical system on $\mathbf{H} \times H^{-1}$, the trajectories of which are weak solutions to the passive scalar advection equation at $\kappa = 0$. However, to check that weak limits μ^0 are stationary is a nontrivial task due to poor continuity properties of (u_t, g_t^0) in H^{-1} with respect to perturbations of the initial data $u \in \mathbf{H}$ for the velocity field (u_t) , and so stationarity of μ^0 requires careful justification; see Section 4.3 for more discussion. The proof is completed in Section 4.4.

Finally, we complete this section with a proof of the L^2 nonvanishing flux relation (1.14).

4.1 Existence of weak limits of $\{\mu^\kappa\}$

Corollary 1.5 of Batchelor's law in Theorem 1.12 is that for each $s \in (0, 1]$ we have the uniform in κ estimate

$$(4.1) \quad \sup_{\kappa > 0} \mathbf{E}_{\mu^\kappa} \|g\|_{H^{-s}}^{2p} \lesssim_{s,p} 1.$$

Since $H^{-s/2}$ is compactly embedded in H^{-s} for all $s > 0$, we can use this to show tightness of $\{\mu^\kappa\}$, which permits us to take weak limits by Prokhorov's theorem. Precisely, we have the following.

LEMMA 4.1. *There exists a sequence $\{\kappa_n\}$, $\kappa_n \rightarrow 0$ as $n \rightarrow \infty$, and a measure μ^0 on $\mathbf{H} \times L^2$ such that for each $s \in (0, 1]$, the following holds: $\mu^\kappa \rightarrow \mu^0$ weakly as a measure on $\mathbf{H} \times H^{-s}$; i.e., for each $\phi \in C_b(\mathbf{H} \times H^{-s})$ we have*

$$\int \phi \, d\mu^{\kappa_n} \rightarrow \int \phi \, d\mu^0.$$

PROOF. Fix $s, \epsilon > 0$ and define

$$K = \{h \in H^{-s} : \|h\|_{H^{-s/2}}^2 \leq \epsilon^{-2} \mathbf{E}_{\mu^\kappa} \|g\|_{H^{-s/2}}^2\}.$$

In light of the compact embedding $H^{-s/2} \hookrightarrow H^{-s}$, K is a compact subset of H^{-s} ; by (4.1) and Chebyshev's inequality, we have

$$\sup_{\kappa \in (0, \kappa_0]} \mu^\kappa(\mathbf{H} \times (H^{-s} \setminus K)) \leq \epsilon.$$

It follows by Prokhorov's theorem that $(\mu^\kappa)_{\kappa > 0}$ has a subsequence that converges weakly as a measure on $\mathbf{H} \times H^{-s}$. Choosing $s = s_j = 2^{-j}$ we can extract a diagonal subsequence κ_n and a limit measure μ^0 such that $\mu^{\kappa_n} \rightarrow \mu^0$ weakly as a measure on $\mathbf{H} \times H^{-s_j}$ for every $j > 0$, hence on $\mathbf{H} \times H^{-s}$ for every $s \in (0, 1]$. $\square$

It is now straightforward to verify the infinite-inertial range version of Batchelor's law as in (1.13). With $\mu^0 = \lim_n \mu^{\kappa_n}$ fixed as above, observe that $g \mapsto \|\Pi_{\leq N} g\|_{L^2}$ varies continuously in H^{-s} . Therefore, one may use a straightforward truncation argument along with the fact

$$\sup_{\kappa \in [0, 1]} \mathbf{E}_{\mu^\kappa} \|\Pi_{\leq N} g\|_{L^2}^{2p} < \infty$$

to conclude that

$$\mathbf{E}_{\mu^0} \|\Pi_{\leq N} g\|_{L^2}^{2p} = \lim_{n \rightarrow \infty} \mathbf{E}_{\mu^{\kappa_n}} \|\Pi_{\leq N} g\|_{L^2}^{2p} \approx_p (\log N)^p$$

for all $N \geq N_0$, using the fact that the inertial range $N_0 \leq N \lesssim \kappa^{-1/2}$ grows to all of $\{N \geq N_0\}$ as $\kappa \rightarrow 0$.

4.2 The scalar process (u_t, g_t^0) at $\kappa = 0$

In this section we study the properties of the passive scalar process (u_t, g_t^0) that solves the advection equation

$$(4.2) \quad \partial_t g_t^0 + u_t \cdot \nabla g_t^0 = b \dot{\beta}_t$$

in the absence of any diffusion term. Since the limiting measure μ^0 assigns full measure to H^{-1} , it is natural to consider $t \mapsto g_t^0$ as a process in the negative Sobolev space H^{-1} , for which it will be necessary to show that weak solutions to (4.2) are well-posed for H^{-1} initial data.

To formulate this, recall that the solution operator $S_t^0(\omega, u) : L^2 \rightarrow L^2$, defined by

$$S_t^0(\omega, u)g = g \circ (\phi_{\omega, u}^t)^{-1},$$

solves (4.2) in the absence of the noise term $b \dot{\beta}_t$, where $\phi_{\omega, u}^t : \mathbb{T}^d \rightarrow \mathbb{T}^d$ is the Lagrangian flow associated to (u_t) . By incompressibility, for $f \in H^1, g \in L^2$, we have

$$(4.3) \quad \int f S_t^0(\omega, u)g \, dx = \int (f \circ \phi_{\omega, u}^t)g \, dx.$$

LEMMA 4.2. *The following holds:*

- (a) *For each $t > 0$ the operator $S_t^0(\omega, u)$ defined by (4.2) admits a unique extension to a bounded linear operator on H^{-1} satisfying (4.3) for all $g \in L^2, f \in H^{-1}$, and for all $g \in H^{-1}, t \mapsto S_t(\omega, u)g$ is strongly continuous in H^{-1} .*
- (b) *For initial data $g \in H^{-1}$ the unique weak solution g_t^0 to equation (4.2) is given by*

$$g_t^0 = S_t^0(\omega, u)g + \int_0^t S_{t-s}^0(\theta_s \omega, u_s) b \, d\beta_s.$$

PROOF. Part (b) follows from (a), which in turn follows from a density argument and the following estimate for $g \in L^2$

$$(4.4) \quad \|S_t^0(\omega, u)g\|_{H^{-1}} \leq \bar{D}(\omega, u)e^{ct} \|g\|_{H^{-1}},$$

where $c > 0$, and for each $p \in [1, \infty)$ we can take $\bar{D}(\omega, u) : \Omega \times \mathbf{H} \rightarrow \mathbb{R}_{\geq 1}$ to have a V -bounded p^{th} moment. To see this, fix $f \in H^1, g \in L^2$, and observe that by Grönwall's inequality and Lemma 2.11

$$\begin{aligned} |\nabla(f \circ \phi_{\omega, u}^t)(x)| &\leq \exp\left(\int_0^t \|\nabla u_s\|_{L^\infty} \, ds\right) |\nabla f(\phi_{\omega, u}^t(x))| \\ &\leq D_0(\omega, u)e^{ct} |\nabla f(\phi_{\omega, u}^t(x))|, \end{aligned}$$

where $c > 0$ and $D_0(\omega, u)$ has a V -bounded p^{th} moment. Using incompressibility of $\phi_{\omega, u}^t$, we obtain

$$\|f \circ \phi_{\omega, u}^t\|_{H^1} \leq D_0(\omega, u)e^{ct} \|f\|_{H^1},$$

hence

$$\begin{aligned} \left| \int S_t^0(\omega, u) g f dx \right| &= \left| \int g(f \circ \phi_{\omega, u}^t) dx \right| \leq \|g\|_{H^{-1}} \|f \circ \phi_{\omega, u}^t\|_{H^1} \\ &\leq D_0(\omega, u) e^{ct} \|g\|_{H^{-1}} \|f\|_{H^1}. \end{aligned}$$

We conclude $\|S_t^0(\omega, u)g\|_{H^{-1}} \leq D_0(\omega, u)e^{ct}\|g\|_{H^{-1}}$, as desired. Strong continuity of $t \mapsto S_t^0$ follows by density of $C^\infty(\mathbb{T}^d)$ in H^{-1} . $\square$

4.3 Stationarity of μ^0 : restricted Feller property of (u_t, g_t^0)

With the evolution $t \mapsto g_t^0$ defined, let P_t^0 denote its corresponding Markov semigroup:

$$P_t^0 \phi(u, g) := \mathbf{E}_{(u, g)} \phi(u_t, g_t^0)$$

for each bounded measurable $\phi : \mathbf{H} \times H^{-1} \rightarrow \mathbb{R}$. We seek to show that if μ^0 is a weak limit of μ^{κ_n} , $\kappa_n \rightarrow 0$, then μ^0 is stationary for (u_t, g_t^0) ; equivalently, it suffices to show that for all globally Lipschitz, bounded $\phi : \mathbf{H} \times H^{-1} \rightarrow \mathbb{R}$, we have

$$\int P_1^0 \phi d\mu^0 = \int \phi d\mu^0.$$

By the weak convergence $\mu^{\kappa_n} \rightarrow \mu^0$ and stationarity of μ^{κ_n} , it suffices to show that

$$\lim_{n \rightarrow \infty} \int P_1^{\kappa_n} \phi d\mu^{\kappa_n} = \int P_1^0 \phi d\mu^0,$$

where P_t^κ is the Markov semigroup on $\mathbf{H} \times L^2$ for the process (u_t, g_t^κ) . To this end the strategy is to write

$$\begin{aligned} (4.5) \quad & \left| \int P_1^{\kappa_n} \phi d\mu^{\kappa_n} - \int P_1^0 \phi d\mu^0 \right| \\ & \leq \left| \int (P_1^{\kappa_n} \phi - P_1^0 \phi) d\mu^{\kappa_n} \right| + \left| \int P_1^0 \phi (d\mu^{\kappa_n} - d\mu^0) \right| \end{aligned}$$

and show that each term vanishes as $n \rightarrow \infty$. The first term is relatively straightforward to bound, having to do with the nearness of $g_t^{\kappa_n}, g_t^0$ when initiated at the same initial condition $g \in L^2$ and subjected to the same noise sample $b\beta_t$. This is dealt with by Lemma 4.4 below.

The second term in (4.5) is more challenging. One would like to use weak convergence to justify passing the limit using weak convergence $\mu^{\kappa_n} \rightarrow \mu^0$, but this will not work: to the best of our knowledge, the semigroup P_t^0 for (u_t, g_t^0) does not send continuous functions on $\mathbf{H} \times H^{-1}$ to continuous functions $\mathbf{H} \times H^{-1}$, namely, P_t^0 is not *Feller* on $\mathbf{H} \times H^{-1}$. When $\kappa > 0$ it is a straightforward consequence of parabolic regularity that the semigroup P_t^κ is Feller on $\mathbf{H} \times L^2$. However, when $\kappa = 0$ this mechanism is not available and consequently P_t^0 is not necessarily Feller on $\mathbf{H} \times H^{-1}$ due to a lack of stability of the transport equation in H^{-1} under perturbations of the velocity field.

Instead, we will show the following *restricted Feller property*: namely, P_t^0 has the Feller property in $\mathbf{H} \times H^{-1}$ when restricted to initial g in a bounded subset of L^2 . We state this property below for Lipschitz observables.

LEMMA 4.3 (Restricted Feller). *Let $\phi \in \text{Lip}(\mathbf{H} \times H^{-1})$; then for all $u, u' \in \mathbf{H}$ and $g, g' \in L^2$ we have*

$$|P_1^0 \phi(u, g) - P_1^0 \phi(u', g')| \lesssim \|\phi\|_{\text{Lip}} W(u, g, u', g') (\|u - u'\|_{\mathbf{H}} + \|g - g'\|_{H^{-1}}),$$

where

$$W(u, g, u', g') = (V(u) + V(u'))(1 + \|g\|_{L^2})(1 + \|g'\|_{L^2}),$$

and $V = V_{\beta, \eta}$ for a sufficiently large universal $\beta > 0$ and all $\eta > 0$.

PROOF. To prove this, it suffices to consider two cases: (i) $u = u'$ and $g \neq g'$ and (ii) $u \neq u'$ and $g' = g$.

Case (i) is straightforward since the difference between any two solutions g_t and g'_t to (4.2) with different initial data and the same noise and same velocity field (u_t) immediately satisfy

$$g_t - g'_t = S_t^0(\omega, u)(g - g');$$

hence by (4.4),

$$\begin{aligned} |P_1^0 \phi(u, g) - P_1^0 \phi(u, g')| &\leq \|\phi\|_{\text{Lip}} \mathbf{E} \bar{D}(u, \cdot) \|g - g'\|_{H^{-1}} \\ &\lesssim \|\phi\|_{\text{Lip}} V(u) \|g - g'\|_{H^{-1}}. \end{aligned}$$

For case (ii) let u_t and u'_t be two solutions to (1) with initial data u and u' , respectively, and g_t and g'_t the solutions to (4.2) with velocity fields (u_t) and (u'_t) , respectively, and the same initial data $g \in H^1$. Then the difference $\tilde{g}_t = g_t - g'_t$ satisfies

$$\partial_t \tilde{g}_t + u_t \cdot \nabla \tilde{g}_t + (u_t - u'_t) \cdot \nabla g'_t = 0, \quad \tilde{g}_0 = 0,$$

and therefore can be written as

$$\tilde{g}_t = \int_0^t S_{t-s}^0(\theta_s \omega, u_s) [(u_s - u'_s) \cdot \nabla g'_s] ds.$$

It follows from (4.4) (choosing $\bar{D}$ to have a V -bounded fourth moment) that for $0 \leq s < t \leq 1$

$$\begin{aligned} \|S_{t-s}^0(\theta_s \omega, u_s) [(u_s - u'_s) \cdot \nabla g'_s]\|_{H^{-1}} &\leq \bar{D}(\theta_s \omega, u_s) \|(u_s - u'_s) \cdot \nabla g'_s\|_{H^{-1}} \\ &\leq \bar{D}(\theta_s \omega, u_s) \|u_s - u'_s\|_{W^{1, \infty}} \|g'_s\|_{L^2}, \end{aligned}$$

where in the last inequality we used that if $f \in W^{1, \infty}$ and $h \in H^{-1}$, then $\|fh\|_{H^{-1}} \leq \|f\|_{W^{1, \infty}} \|h\|_{H^{-1}}$, which can be seen by duality between H^1 and H^{-1} . Consequently, we have

$$\mathbf{E} \|\tilde{g}_1\|_{H^{-1}} \leq \int_0^1 \mathbf{E} [\bar{D}(\theta_s \omega, u_s) \|u_s - u'_s\|_{\mathbf{H}} \|g'_s\|_{L^2}] ds.$$

We use Hölder's inequality under $\mathbf{E}$. The fourth moment $\mathbf{E}\bar{D}(\omega, u)^4$ is bounded $\lesssim V(u)$ by construction, while by Lemma 2.8 we have $\mathbf{E}\|u_s - u'_s\|_{\mathbf{H}}^4 \lesssim (V(u) + V(u'))\|u - u'\|_{\mathbf{H}}$. To bound $\mathbf{E}\|g'_s\|_{L^2}^2$, we estimate as follows: by Itô's formula,

$$\|g'_s\|_{L^2}^2 = \|g\|_{L^2}^2 + 2\chi s + \int_0^s \langle g'_r, b \rangle_{L^2} d\beta_r.$$

By taking $\mathbf{E}$ of both sides, the stochastic integral vanishes, hence $\mathbf{E}\|g'_s\|_{L^2}^2 = \|g\|_{L^2}^2 + 2\chi s$. Putting this together, we conclude for suitable $V(u)$

$$\begin{aligned} |P_1\phi(u, g) - P_1\phi(u', g)| &\leq \|\phi\|_{\text{Lip}} \mathbf{E}\|\tilde{g}_1\|_{H^{-1}} \\ &\lesssim_p \|\phi\|_{\text{Lip}} (V(u) + V(u'))(1 + \|g\|_{L^2})\|u - u'\|_{\mathbf{H}}. \quad \square \end{aligned}$$

4.4 Stationarity of μ^0 : Completing the proof

It suffices to show that the right-hand side of (4.5) vanishes. The first term $|\int (P_1^{\kappa_n}\phi - P_1^0\phi)d\mu^{\kappa_n}|$ in (4.5) will be estimated using the following.

LEMMA 4.4. *Let g_t^κ and g_t^0 have the same initial data $g \in L^2$, the same velocity field (u_t) , and the same source path $b\beta_t$. Then,*

$$\mathbf{E}\|g_1^\kappa - g_1^0\|_{H^{-1}} \lesssim V(u) \int_0^1 \kappa \mathbf{E}\|g_s^\kappa\|_{H^1} ds.$$

PROOF. Note that $\tilde{g}_t^\kappa = g_t^\kappa - g_t^0$ satisfies

$$\partial_t \tilde{g}_t^\kappa + u_t \cdot \nabla \tilde{g}_t^\kappa - \kappa \Delta g_t^\kappa = 0.$$

with $\tilde{g}_0^\kappa = 0$. This implies that

$$\tilde{g}_1^\kappa = \kappa \int_0^1 S_{t-s}^0(\theta_s \omega, u_s) \Delta g_s^\kappa ds,$$

and therefore using the H^{-1} bound (4.4) on $S_{t-s}^0(\theta_s \omega, u_s)$, we find

$$\|\tilde{g}_1^\kappa\|_{H^{-1}} \lesssim \kappa \int_0^1 \bar{D}(\theta_s \omega, u_s) \|g_s^\kappa\|_{H^1} ds,$$

where $\bar{D}(\omega, u)$ has V -bounded first moment. Taking an expectation w.r.t. ω and applying Lemma 2.6 completes the proof. $\square$

From here, to prove convergence $\int (P_1^{\kappa_n}\phi - P_1^0\phi)d\mu^{\kappa_n} \rightarrow 0$, we have from Lemma 4.4 and the Lipschitz property of ϕ that

$$|(P_1^\kappa\phi - P_1^0\phi)(u, g)| \leq \|\phi\|_{\text{Lip}} \mathbf{E}\|g_1^\kappa - g_1^0\|_{H^{-1}} \lesssim V(u) \int_0^1 \kappa \mathbf{E}\|g_s^\kappa\|_{H^1} ds,$$

hence upon integrating in μ^κ and using Cauchy-Schwarz,

$$\int |P_1^\kappa\phi - P_1^0\phi| d\mu^\kappa \lesssim \kappa \int_0^1 (\mathbf{E}_{\mu^\kappa} \|g\|_{H^1}^2)^{1/2} ds \lesssim \sqrt{\kappa}$$

by the energy balance relation $\kappa \mathbf{E}_{\mu^\kappa} \|g_t\|_{H^1}^2 = \chi$ (see (1.4)).

It remains to show that $|\int P_1^0 \phi(d\mu^{\kappa_n} - d\mu^0)| \rightarrow 0$ in (4.5). As observed already, this does not follow immediately from weak convergence since $P_1^0 \phi$ need not be continuous. Instead, we will use the restricted Feller property from Lemma 4.3, which guarantees continuity of $P_1^0 \phi$ along $g \in L^2$. To bridge the gap from L^2 to H^{-1} , we use the following mollification argument: for $\delta \in (0, 1)$ and $g \in H^{-s}$, $s \in (0, 1]$, define $T_\delta g$ to be the mollification¹⁰ of g , and define the regularized semigroup

$$(P_1^0 \phi)_\delta(u, g) := P_1^0 \phi(u, T_\delta g).$$

Note that a straightforward duality argument shows that

$$\|T_\delta g - g\|_{H^{-1}} \lesssim \delta^{1-s} \|g\|_{H^{-s}}.$$

This, in turn, gives rise to the following approximation property for $(P_1^0 \phi)_\delta$.

LEMMA 4.5. *For each $\delta \in (0, 1)$, $s \in (0, 1]$, $(P_1^0 \phi)_\delta \in C_b(\mathbf{H} \times H^{-1})$, and for each globally Lipschitz $\phi : \mathbf{H} \times H^{-1} \rightarrow \mathbb{R}$ and $g \in H^{-s}$, we have*

$$|(P_1 \phi)_\delta - P_1 \phi|(u, g) \lesssim V(u) \delta^{1-s} \|g\|_{H^{-s}},$$

where $V = V_{\beta, \eta}$ for any $\beta > 0$ and $\eta > 0$.

PROOF. Note that Lemma 4.3 implies $(P_1^0 \phi)_\delta \in C_b(\mathbf{H} \times H^{-1})$. For $g \in H^{-s}$, denote g_1^δ and g_1 solutions at time $t = 1$ of the transport equation (4.2) with the same velocity path (u_t) and noise $b\beta_t$ but with different initial data $T_\delta g$ and g , respectively. We have

$$\begin{aligned} |((P_1^0 \phi)_\delta - P_1^0 \phi)(u, g)| &\leq \mathbf{E} |\phi(u_1, g_1^\delta) - \phi(u_1, g_1)| \\ &\leq \|\phi\|_{\text{Lip}} \mathbf{E} \|S_1^0(u, \omega)(T_\delta g - g)\|_{H^{-1}} \\ &\lesssim V(u) \|T_\delta g - g\|_{H^{-1}} \lesssim V(u) \delta^{1-s} \|g\|_{H^{-s}}, \end{aligned}$$

having used (4.4) and the V -boundedness of the first moment of $\bar{D}$. $\square$

To complete the proof: for $\delta > 0$, we estimate

$$\begin{aligned} \left| \int P_1^0 \phi(d\mu^{\kappa_n} - d\mu^0) \right| &\leq \left| \int (P_1^0 \phi)_\delta(d\mu^{\kappa_n} - d\mu^0) \right| \\ &\quad + \int |(P_1^0 \phi)_\delta - P_1^0 \phi|(d\mu^{\kappa_n} + d\mu^0). \end{aligned}$$

The first term on the right vanishes as $n \rightarrow \infty$ since $(P_1 \phi)_\delta \in C_b(\mathbf{H} \times H^{-1})$ by Lemma 4.2 and $\mu^{\kappa_n} \rightarrow \mu^0$ weakly. For the second term, Lemma 4.5 and Cauchy-Schwarz imply

$$\int |(P_1 \phi)_\delta - P_1 \phi|(d\mu^{\kappa_n} + d\mu^0) \lesssim \delta^{1-s} ((\mathbf{E}_{\mu^{\kappa_n}} \|g\|_{H^{-s}}^2)^{1/2} + (\mathbf{E}_{\mu^0} \|g\|_{H^{-s}}^2)^{1/2}),$$

¹⁰Here mollification is defined by convolution with $\eta_\delta = \delta^{-d} \eta(\cdot/\delta)$, where η is a smooth, symmetric, compactly supported test function with $\int \eta = 1$.

which converges to 0 as $\delta \rightarrow 0$ uniformly in κ_n by (4.1). This completes the proof of stationarity of μ^0 for P_t^0 , the last item remaining from Theorem 1.12.

4.5 Nonvanishing flux

We conclude this section by proving the nonvanishing flux law (1.14). To do this, we remark that $\Pi_{\leq N} g_t^\kappa$ satisfies

$$\Pi_{\leq N} g_t^\kappa = \Pi_{\leq N} g_0^\kappa - \int_0^t \Pi_{\leq N} (u_s \cdot \nabla g_s^\kappa) ds + \Pi_{\leq N} b \beta_t,$$

and therefore applying Itô's formula gives

$$\begin{aligned} \|\Pi_{\leq N} g_t^0\|_{L^2}^2 &= \|\Pi_{\leq N} g_0^0\|_{L^2}^2 - 2 \int_0^t \langle \Pi_{\leq N} g_s, \Pi_{\leq N} (u_s \cdot \nabla g_s) \rangle_{L^2} 0 ds \\ &\quad + \|\Pi_{\leq N} b\|_{L^2}^2 t + \int_0^t 2 \langle \Pi_{\leq N} g_s, \Pi_{\leq N} b \rangle_{L^2} d\beta_s. \end{aligned}$$

Taking expectation, integrating the initial data (u, g) with respect to the stationary measure μ^0 , and using the stationarity of (u_t, g_t^0) with respect to μ^0 , we readily obtain the flux balance

$$\mathbf{E}_{\mu^\kappa} \langle \Pi_{\leq N} g, \Pi_{\leq N} (u \cdot \nabla g) \rangle_{L^2} = \frac{1}{2} \|\Pi_{\leq N} b\|_{L^2}^2.$$

Using the divergence free property and integrating by parts in the L^2 inner product gives (1.14).

5 Irregularity of the Limiting Statistically Stationary Solutions

In the previous section, we produced a $\kappa \rightarrow 0$ subsequential limit of μ^κ which converges to a stationary measure μ^0 of the Markov semigroup associated with (u_t, g_t^0) , where the scalar solves

$$(5.1) \quad \partial_t g_t^0 + u_t \cdot \nabla g_t^0 = b \dot{\beta}_t.$$

Since there is no dissipation in the equation, the input from the noise must be “anomalously” dissipated by the mixing mechanism (that is, the formally conservative transport equation must nonetheless dissipate). As discussed in Section 1.3, this requires a degree of roughness of statistically stationary g_t^0 . Specifically, in this section we prove

- (a) μ^0 -generic $(u, g) \in \mathbf{H} \times H^- = \mathbf{H} \times \bigcap_{\delta>0} H^{-\delta}$ are such that g is not locally integrable, hence are ‘strictly’ distributions (Theorem 1.15);
- (b) the Besov space $L_t^2 B_{2,\infty}^0$ is “Onsager-type critical” in the sense that no statistically stationary solution g_t^0 can have even a small amount of additional regularity (Theorem 1.19).

Part (a) is carried out by applying a variant of the DiPerna-Lions theory of renormalized solutions for the transport equation and is carried out in Section 5.1, while part (b) is carried out in Section 5.2.

5.1 μ^0 generic functions cannot be L^1

Our proof is by contradiction, based on invariance of $\mathbf{H} \times L^1$ by solutions to (5.1).

LEMMA 5.1. *The set $\mathbf{H} \times L^1$ is almost surely invariant for (u_t, g_t^0) : if $u_0 \in \mathbf{H}$ and $g_0^0 \in L^1$, then $g_t^0 \in L^1$ for all $t > 0$.*

PROOF. This follows from Lemma 4.2(b) by noting that due to the smoothness of b , the stochastic convolution

$$\int_0^t S_{t-s}^0(\theta_s \omega, u_s) b \, d\beta_s$$

takes values in (at least) L^2 , and S_t^0 propagates L^1 regularity. In fact, we have

$$\|S_t^0(\omega, u)g\|_{L^1} = \|g \circ (\phi_{\omega, u}^t)^{-1}\|_{L^1} = \|g\|_{L^1}$$

by the fact that $\phi_{\omega, u}^t$ is volume preserving. $\square$

To continue, we will find it convenient to show that any L^1 -valued solutions to (5.1) can be renormalized in the sense of DiPerna and Lions [39], meaning that we show that $F(g_t^0)$ solves another transport-type equation for some suitably regular function $F : \mathbb{R} \rightarrow \mathbb{R}$. In our setting the velocity field (u_t) is not rough, which allows for the transport part of the equation to be easily renormalized, but the presence of noise introduces Itô corrections and imposes higher regularity requirements on F . In what follows we define

$$F(z) := \sqrt{1 + |z|^2}.$$

LEMMA 5.2. *Let $g^0 \in L^1$ and g_t^0 be a mild solution to (5.1); then the following holds almost surely:*

$$(5.2) \quad \begin{aligned} \int F(g_t^0) dx &= \int F(g_0^0) dx + \int_0^t \left(\int \frac{b^2}{2F(g_s^0)^3} dx \right) ds \\ &\quad + \int_0^t \left(\int \frac{g_s^0 b}{F(g_s^0)} dx \right) d\beta_s. \end{aligned}$$

PROOF. For a given function $f \in L^1$, we denote by $(f)_\delta$ the mollification of f (see the proof of Lemma 4.5). It is straightforward to show that $(f)_\delta \rightarrow f$ both in L^1 and pointwise a.e. Since g_t^0 is a weak solution to (5.1), we see that $(g_t^0)_\delta$ solves the following equation almost surely:

$$(g_t^0)_\delta = (g_0^0)_\delta - \int_0^t u_s \cdot \nabla (g_s^0)_\delta \, ds + (b)_\delta \beta_t + \int_0^t R_\delta(u_s, g_s^0) \, ds,$$

where we write

$$R_\delta(u_t, g_t^0) = u_t \cdot \nabla (g_t^0)_\delta - (u_t \cdot \nabla g_t^0)_\delta$$

for the commutator term, noting that convolution $(\cdot)_\delta$ does not commute with $u_t \cdot \nabla$. Since the equation for $(g_t^0)_\delta$ holds pointwise as an identity on smooth functions for

each $x \in \mathbb{T}^d$, we can apply Itô's formula to $F((g_t^0)_\delta(x))$ to deduce the pointwise identity

$$(5.3) \quad \begin{aligned} F((g_t^0)_\delta) &= F((g_0^0)_\delta) - \int_0^t u_s \cdot \nabla F((g_s^0)_\delta) ds + \int_0^t \frac{1}{2} F''((g_s^0)_\delta) (b)_\delta^2 ds \\ &\quad + \int_0^t F'((g_s^0)_\delta) (b)_\delta d\beta_t + \int_0^t F'((g_s^0)_\delta) R_\delta(u_s, g_s^0) ds. \end{aligned}$$

Here we have used the fact that $(g_t^0)_\delta$ is smooth and therefore $F'(g_t^0)u_t \cdot \nabla(g_t^0)_\delta = u_t \cdot \nabla F((g_t^0)_\delta)$. Itô's formula for the unbounded function $F(z) = \sqrt{1 + |z|^2}$ is justified in this case because $F((g_t^0)_\delta) \lesssim_\delta 1 + \|g_t^0\|_{L^1}$; hence for each $t \in \mathbb{R}_+$,

$$\mathbf{P}\left(\sup_{s \in [0, t]} \|F((g_s^0)_\delta)\|_{L^\infty} < \infty\right) = 1.$$

Next, we note that since $\operatorname{div} u_t = 0$, it is standard that (see [39])

$$\int |R_\delta(u_t, g_t^0)| dx \leq \|u_t\|_{W^{1, \infty}} \left(\int_{B_\delta} |y \cdot \nabla \eta_\delta| dy \right) \sup_{|y| < \delta} \|g_t^0(\cdot + y) - g_t^0(\cdot)\|_{L^1}.$$

Since $\int |y \cdot \nabla \eta_\delta| dy = \int |y \cdot \nabla \eta| dy$ and g_t^0 belongs to L^1 almost surely, we conclude by the L^1 -continuity of spatial translations that for each $t \in \mathbb{R}_+$

$$(5.4) \quad R_\delta(u_t, g_t^0) \rightarrow 0 \quad \text{in } L^1 \text{ as } \delta \rightarrow 0 \text{ almost surely.}$$

Using the facts

$$F'(z) = \frac{z}{F(z)}, \quad F''(z) = \frac{1}{F(z)^3}, 0$$

we can integrate (5.3) and use the fact that u_t is divergence free to obtain

$$(5.5) \quad \begin{aligned} \int F((g_t^0)_\delta) dx &= \int F((g_0^0)_\delta) dx + \int_0^t \left(\int \frac{1}{2} \frac{(b)_\delta^2}{F((g_s^0)_\delta)^3} dx \right) ds \\ &\quad + \int_0^t \left(\int \frac{(b)_\delta (g_t^0)_\delta}{F((g_s^0)_\delta)} dx \right) d\beta_t \\ &\quad + \int_0^t \left(\int \frac{(g_t^0)_\delta}{F((g_t^0)_\delta)} R_\delta(u_s, g_s^0) dx \right) ds. \end{aligned}$$

The proof will be complete if we can pass the $\delta \rightarrow 0$ limit in both sides of (5.5) almost-surely for each fixed t . Since we have $(g_t^0)_\delta \rightarrow g_t^0$ in L^1 and almost everywhere on $\mathbb{T}^d$, as well as the convergence of the commutator (5.4) in L^1 and $(b)_\delta \rightarrow b$ in L^2 , we can use bounded convergence to pass the $\delta \rightarrow 0$ limits almost-surely in every term of (5.5) except for the stochastic integral. To deal with the

stochastic integral, note that by Itô's formula

$$\begin{aligned} \mathbf{E} \left| \int_0^t \left(\int \frac{(b)_\delta (g_t^0)_\delta}{F((g_s^0)_\delta)} - \frac{bg_t^0}{F(g_s^0)} dx \right) d\beta_t \right|^2 \\ = \mathbf{E} \int_0^t \int \left| \frac{(b)_\delta (g_t^0)_\delta}{F((g_s^0)_\delta)} - \frac{bg_t^0}{F(g_s^0)} \right| dx ds \rightarrow 0 \end{aligned}$$

as $\delta \rightarrow 0$ by the bounded convergence theorem. $\square$

We are now ready to prove Theorem [1.15](#).

PROOF OF THEOREM [1.15](#). We assume that $\mu^0(\mathbf{H} \times L^1) > 0$ in pursuit of a contradiction. By Lemma [5.1](#), $\mathbf{H} \times L^1$ is an invariant set for (u_t, g_t^0) , and so the conditional measure

$$\hat{\mu}^0 := \frac{\mu^0(\cdot \cap (\mathbf{H} \times L^1))}{\mu^0(\mathbf{H} \times L^1)}$$

is another stationary measure for (u_t, g_t^0) that assigns full measure to $\mathbf{H} \times L^1$.

We would like to conclude the proof by taking expectations of both sides of [\(5.2\)](#) using stationarity with respect to $\hat{\mu}^0$. However, we are unable to justify this, since a priori we do not know whether $F(g_t^0)$ has finite moments. To get around this, apply Itô's formula to $\phi(\int F(g_t^0) dx)$, where ϕ is a bounded C^2 function, to deduce

$$\begin{aligned} \phi \left(\int F(g_t^0) dx \right) &= \phi \left(\int F(g_0^0) dx \right) \\ &+ \int_0^t \left(\int \frac{b^2}{2F(g_s^0)^3} dx \right) \phi' \left(\int F(g_s^0) dx \right) ds \\ &+ \frac{1}{2} \int_0^t \left(\int \frac{g_s^0 b}{F(g_s^0)} dx \right)^2 \phi'' \left(\int F(g_s^0) dx \right) ds \\ &+ \int_0^t \left(\int \frac{g_s^0 b}{F(g_s^0)} dx \right) \phi' \left(\int F(g_s^0) dx \right) d\beta_s. \end{aligned}$$

Taking the expectation and integrating the initial data with respect to $\hat{\mu}^0$ (crucially using that $\hat{\mu}^0$ assigns full measure to L^1), we find

$$\mathbf{E}_{\hat{\mu}^0} \left[\left(\int \frac{b^2}{F(g)^3} dx \right) \phi' \left(\int F(g) dx \right) + \left(\int \frac{gb}{F(g)} dx \right)^2 \phi'' \left(\int F(g) dx \right) \right] = 0.$$

For $\epsilon > 0$, define $\phi(z) = \frac{z}{1+\epsilon z}$, so that

$$\mathbf{E}_{\hat{\mu}^0} \frac{\int \frac{b^2}{F(g)^3} dx}{(1 + \epsilon \int F(g) dx)^2} = \mathbf{E}_{\hat{\mu}^0} \frac{2\epsilon \left(\int \frac{gb}{F(g)} dx \right)^2}{(1 + \epsilon \int F(g) dx)^3} \leq 2\epsilon \|b\|_{L^2}^2.$$

Sending $\epsilon \rightarrow 0$ and applying monotone convergence gives

$$\mathbf{E}_{\hat{\mu}^0} \int \frac{b^2}{F(g)^3} dx = 0,$$

which contradicts $\hat{\mu}^0(\mathbf{H} \times L^1) = 1$. Therefore $\mu^0(\mathbf{H} \times L^1) = 0$, which completes the proof. $\square$

5.2 Onsager-type criticality of $L_t^2 B_{2,\infty}^0$

In this section we prove Theorem 1.19. Recall Definition 1.18 of a $B_{2,c}^0$ -suitable multiplier M , and the associated generalized Besov norm

$$\|f\|_{B_{2,\infty}^M} = \sup_{N \in \{2^j : j \in \mathbb{N}_*\}} M(N) \|\Pi_N f\|_{L^2}.$$

We denote by $B_{2,\infty}^M$ the space of tempered distributions f with $\|f\|_{B_{2,\infty}^M} < \infty$. The following lemma shows that we can exhaust $B_{2,c}^0$ in terms of the spaces $\{B_{2,\infty}^M\}$.

LEMMA 5.3. *The following holds:*

$$B_{2,c}^0 = \bigcup_M B_{2,\infty}^M,$$

where the union is over all $B_{2,c}^0$ -suitable multipliers M .

PROOF. That $\|f\|_{B_{2,\infty}^M} < \infty \Rightarrow f \in B_{2,c}^0$ follows from $\lim_{k \rightarrow \infty} M(k) = \infty$.

Conversely, let $g \in B_{2,c}^0$. Let C_0 be such that $\sup_{j \in \mathbb{N}_*} \|\Pi_{2^j} g\|_{L^2} \leq C_0$. By $g \in B_{2,c}^0$, there exists a strictly increasing sequence $\{N_k\}_{k=1}^\infty \subseteq \{2^j : j \in \mathbb{N}\}$ such that $\forall N \geq N_k, \|\Pi_N g\|_{L^2} < 2^{-k}$. Define $M(k) : [1, \infty) \rightarrow [1, \infty)$ to be the monotone increasing multiplier

$$M(k) = \begin{cases} 2 & k < N_1, \\ \frac{2^j}{N_{j+1}-N_j} (N_{j+1} - k) + \frac{2^{j+1}}{N_{j+1}-N_j} (k - N_j) & N_j \leq k \leq N_{j+1}. \end{cases}$$

We see that M is piecewise linear with slope ≤ 1 , and therefore satisfies conditions (i) and (ii) of Definition 1.18. $\square$

We introduce Littlewood-Paley decomposition for future use. Let $\zeta \in C_0^\infty(\mathbb{R}; \mathbb{R})$ be such that $\zeta(\xi) = 1$ for $|\xi| \leq 1$ and $\zeta(\xi) = 0$ for $|\xi| \geq 3/2$, and define $\psi(\xi) = \zeta(\xi/2) - \zeta(\xi)$, supported in the range $\xi \in (1, 3)$. Denote, for each $N > 0$, $\zeta_N(\xi) := \zeta(N^{-1}\xi)$ and $\psi_N(\xi) := \psi(N^{-1}\xi)$. For $f \in L^2(\mathbb{R})$ we define the Littlewood-Paley projections

$$\pi_N f := \psi_N(\nabla) f \quad \text{and} \quad \pi_{\leq N} f := \zeta_N(\nabla) f.$$

Note by Definition 1.18 (denoting $\mathbb{N}_* = \{0\} \cup \mathbb{N}$ and analogously for $\mathbb{Z}_*^d = \{0\} \cup \mathbb{Z}^d$ below),

$$\begin{aligned} & \sup_{N \in \{2^j : j \in \mathbb{N}_*\}} M(N) \|\Pi_N g\|_{L^2} \\ & \approx \|M(|\nabla|)\pi_{\leq 1} g\|_{L^2} + \sup_{N \in \{2^j : j \in \mathbb{N}_*\}} \|M(|\nabla|)\pi_N g\|_{L^2}. \end{aligned}$$

LEMMA 5.4. *For any $(u, g) \in \mathbf{H} \times H^{-1}$, if $\|g\|_{B_{2,\infty}^M} < \infty$ for some $B_{2,c}^0$ -suitable M , then*

$$|\langle \pi_{\leq N} g, \pi_{\leq N} \nabla \cdot (ug) \rangle| \lesssim \frac{1}{M^2(N)} \|g\|_{B_{2,\infty}^M}^2 \|u\|_{\mathbf{H}}.$$

PROOF. By the incompressibility of u and Plancherel's identity,

$$\begin{aligned} & \langle \pi_{\leq N} g, \pi_{\leq N} \nabla \cdot (ug) \rangle \\ & = \langle \pi_{\leq N} g, \pi_{\leq N} \nabla \cdot (ug) - \nabla \cdot (u\pi_{\leq N} g) \rangle \\ & = \sum_{k, \ell \in \mathbb{Z}_*^d} (\mathbf{1}_{|\ell| < 2|k-\ell|} + \mathbf{1}_{|\ell| \geq 2|k-\ell|}) \zeta_N(k) \widehat{g}_t(k) \\ & \quad \times (\zeta_N(k) - \zeta_N(\ell)) i k \cdot \widehat{u}_t(k-\ell) \widehat{g}_t(\ell) \\ & =: \mathcal{I}_{HL} + \mathcal{I}_{LH}. \end{aligned}$$

Note that due to the presence of the cutoffs $(\zeta_N(k) - \zeta_N(\ell))$, we see that one of $|k|$ or $|\ell|$ must be larger or equal to $\frac{1}{2}N$ for the corresponding term in the summation to be nonzero. The “high-low” term is treated by noting that on the support of the summation, $|k| + |\ell| \lesssim |k-\ell|$, and therefore for any $\delta > 0$,

$$\begin{aligned} |\mathcal{I}_{HL}| & \lesssim \frac{1}{N^2} \sum_{k, \ell \in \mathbb{Z}_*^d} \mathbf{1}_{|\ell| < 2|k-\ell|} |\zeta_N(k) \widehat{g}_t(k) \langle k-\ell \rangle^3 \widehat{u}_t(k-\ell) \widehat{g}_t(\ell)| \\ & \lesssim \frac{1}{N^2} \sum_{k, \ell \in \mathbb{Z}_*^d} \mathbf{1}_{|\ell| < 2|k-\ell|} \frac{1}{\langle k \rangle^\delta \langle \ell \rangle^\delta} |\zeta_N(k) \widehat{g}_t(k) \langle k-\ell \rangle^{3+2\delta} \widehat{u}_t(k-\ell) \widehat{g}_t(\ell)|. \end{aligned}$$

Then, using Cauchy-Schwarz, Young's inequality, and $H^r \hookrightarrow \widehat{L}^1$ for $r > d/2$, (recall $\sigma > 3 + \frac{d}{2}$),

$$|\mathcal{I}_{HL}| \lesssim_\delta \frac{1}{N^2} \|g\|_{H^{-\delta}}^2 \|u\|_{\mathbf{H}} \lesssim \frac{1}{M(N)^2} \|g\|_{B_{2,\infty}^M}^2 \|u\|_{\mathbf{H}},$$

where the last inequality followed from $M(N) \lesssim N$ by Definition 1.18 and the embedding $H^{-\delta} \hookrightarrow B_{2,\infty}^0$.

We turn next to the “low-high” term. First, by the mean value theorem,

$$(5.6) \quad |\zeta_N(k) - \zeta_N(\ell)| \lesssim \frac{1}{N} |k - \ell|.$$

Second, observe that on the support of the summation, we have $N \approx |k| \approx |\ell|$ because of the frequency cutoff and that at least one of $|k|$ or $|\ell|$ must be larger or equal to $\frac{1}{2}N$, but one of $|k|$ and $|\ell|$ must also be less than $3N$. Therefore, we deduce from part (ii) of Definition [1.18](#) and [\(5.6\)](#),

$$|\mathcal{I}_{LH}| \lesssim \frac{1}{M(N)^2} \sum_{k, \ell \in \mathbb{Z}_+^d} \mathbf{1}_{|\ell| \geq 2|k-\ell|} |\zeta_N(k) M(|k|) \hat{g}(k) \langle k-\ell \rangle \hat{u}(k-\ell) M(|\ell|) \hat{g}(\ell)|.$$

Again by using Cauchy-Schwarz, Young's inequality, and $H^r \hookrightarrow \widehat{L}^1$ for $r > d/2$,

$$|\mathcal{I}_{LH}| \lesssim \frac{1}{M(N)^2} \|g\|_{B_{2,\infty}^M}^2 \|u\|_{\mathbf{H}}.$$

This completes the proof. $\square$

PROOF OF THEOREM [1.19](#). We proceed by contradiction and assume

$$\mathbf{E}_{\mu^0} \|g\|_{B_{2,\infty}^M}^p < \infty \quad \text{for some } p > 2.$$

By repeating the proof of the flux balance [\(1.14\)](#) as in Section [4.5](#) with $\pi_{\leq N}$ replacing $\Pi_{\leq N}$, we have

$$(5.7) \quad \mathbf{E}_{\mu^0} \langle \pi_{\leq N} g, \pi_{\leq N} \nabla \cdot (ug) \rangle = \frac{1}{2} \|\pi_{\leq N} b\|_{L^2}^2.$$

However, Lemma [5.4](#) and the assumption that $\mathbf{E}_{\mu^0} \|g\|_{B_{2,\infty}^M}^p < \infty$ for some $p > 2$ implies that

$$\begin{aligned} |\mathbf{E}_{\mu^0} \langle \pi_{\leq N} g, \pi_{\leq N} \nabla \cdot (ug) \rangle| &\lesssim \frac{1}{M(N)^2} \mathbf{E}_{\mu^0} \left[\|g\|_{B_{2,\infty}^M}^2 \|u\|_{\mathbf{H}} \right] \\ &\lesssim \frac{1}{M(N)^2} \left(\mathbf{E}_{\mu^0} \|g\|_{B_{2,\infty}^M}^p \right)^{2/p} \left(\mathbf{E} \|u\|_{\mathbf{H}}^{\frac{p}{p-2}} \right)^{\frac{p-2}{p}} \\ &\lesssim \frac{1}{M(N)^2}. \end{aligned}$$

On the other hand, $\lim_{N \rightarrow \infty} \frac{1}{2} \|\pi_{\leq N} b\|_{L^2}^2 = \chi$, and so by choosing N sufficiently large in [\(5.7\)](#) gives the desired contradiction. $\square$

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