Communication-Efficient Signature-Free Asynchronous Byzantine Agreement

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Abstract—In this work, we focus on the problem of byzantine agreement (BA), in which n distributed processors seek to reach an agreement on an ℓ -bit value, but up to t processors might be corrupted by a Byzantine adversary and act as dishonest nodes. In particular, we consider the communication-efficient BA in an asynchronous setting, where the network communication might have arbitrarily time delay. The primary challenge of designing the BA protocol in this setting is that we need to handle both the message delay from honest nodes and the Byzantine behavior from dishonest nodes simultaneously. In this work we propose a new signature-free asynchronous byzantine agreement (ABA) protocol, which achieves the optimal communication complexity of $O(n\ell)$ when $\ell \geq t \log t$, given $n \geq 5t + 1$. A protocol is said to be signature-free if the protocol design does not depend on the cryptographic machinery such as hashing and signature. To the best of our knowledge, this is the first signature-free ABA protocol that achieves the optimal communication complexity of $O(n\ell)$ when ℓ is almost linearly scaled with t.

I. INTRODUCTION

Byzantine agreement (BA), as a 40-year-old distributed consensus problem (cf. [1], [2]), is one of the fundamental building blocks for distributed computing and cryptography (e.g. [1]–[12]). In the BA problem, n distributed processors seek to reach an agreement on some value, but up to t processors might be corrupted by a Byzantine adversary and act as dishonest nodes. The BA problem has been broadly studied in varying settings, such as authenticated BA (cf. [5]–[12]), unauthenticated BA (cf. [13]-[16]), BA with synchronous communication (cf. [17]-[20]), BA with asynchronous communication (cf. [21]-[33]), binary BA (cf. [13]-[15], [30], [34]), and multi-valued BA (cf. [35]–[45]). In this work, we focus on the communication-efficient multi-valued asynchronous BA (ABA) in an unauthenticated (signature-free) setting. A protocol is said to be signature-free if the protocol design does not depend on the cryptographic machinery such as hashing and signature.

In the research line of signature-free multi-valued ABA, the work of [39] proposed an ABA protocol with communication complexity $O(n\ell+n^5\log n)$, given $n\geq 3t+1$. This result was recently improved in [45] to the communication complexity of $O(n\ell+n^4\log n)$. The communication complexity of [39]

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TABLE I COMPARISON OF DIFFERENT ABA PROTOCOLS

Model	Resilience	Communication complexity	Round complexity	Signature -free
[39]	$t < \frac{n}{3}$	$O(n\ell + n^5 \log n)$	O(1)	yes
[45]	$t < \frac{n}{3}$	$O(n\ell + n^4 \log n)$	O(1)	yes
Proposed	$t < \frac{n}{5}$	$O(\max\{n\ell, nt\log t\})$	O(1)	yes

and [45] is optimal when $\ell \geq n^4 \log n$ and $\ell \geq n^3 \log n$, respectively. A recent work of [16] has shown that the optimal communication complexity $O(n\ell)$ can be achieved when $\ell \geq t \log t$ in the synchronous setting. This inspires us to raise the following question.

Is it possible to achieve the optimal communication complexity $O(n\ell)$ when $\ell \geq t \log t$ in the signature-free asynchronous setting?

In this work, we seek to investigate the above question. Specifically, we propose a new signature-free ABA protocol that achieves the communication complexity of $O(\max\{n\ell, nt\log t\})$, given $n \geq 5t+1$. It implies that the optimal communication complexity of $O(n\ell)$ can be achieved when $\ell \geq t\log t$. To the best of our knowledge, this is the first signature-free ABA protocol that achieves the optimal communication complexity of $O(n\ell)$ when ℓ is almost linearly scaled with t.

The proposed protocol (called as A-COOL) is extended from the COOL protocol introduced in the synchronous setting [16]. Note that, in the asynchronous setting the message transmission might be delayed with arbitrary time. Therefore, we need to handle both the message delay from honest nodes and the Byzantine behavior from dishonest nodes simultaneously. This is the primary challenge of designing the BA protocol in this asynchronous setting.

We provide some comparison between different ABA protocols in Table I and Fig. 1. Note that Fig. 1 focuses on the comparison in the communication complexity exponent, which is defined in (1), capturing the exponent of communication complexity performance. As shown in Fig. 1, compared to the protocols in [39] and [45], A-COOL protocol provides additive gains up to 3 and 2, respectively, in terms of communication complexity exponent performance.

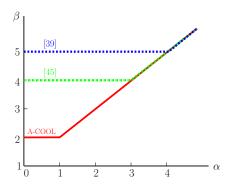


Fig. 1. Communication complexity exponent β vs. message size exponent α of the proposed A-COOL, the protocols in [39] and [45], focusing on the case with $\delta=1$.

This paper is organized as follows. The system model is provided in Section II, while the main results are presented in Section III. The proposed A-COOL is detailed in Section IV. The conclusion is drawn in Section V.

II. SYSTEM MODELS

We consider the ABA problem, in which a set of n distributed processors $\{P_1, P_2, \cdots, P_n\}$ seek to reach an agreement on an ℓ -bit value, but up to t processors might be corrupted by a Byzantine adversary and act as dishonest nodes. The processors are communicated over an asynchronous network. Each pair of processors is connected via a reliable and private communication channel. We consider a static adversary, denoted by \mathcal{A}_t , which selects the set of corrupted processors before starting the protocol. We assume that the adversary has complete knowledge of the state of the other processors. The processors that are not corrupted by the adversary are honest processors. We provide the formal definition of ABA as below.

Definition 1 (ABA). A protocol for a set of processors $\{P_1, P_2, \dots, P_n\}$, where P_i holds an initial ℓ -bit input value w_i , $i \in [1:n]$, is said to be an ABA protocol tolerating an adversary A_t , if the following properties hold

- Termination: Every honest processor eventually almostsurely¹ terminates.
- Consistency: All of the honest processors eventually decide on the same value.
- Validity: If every honest processor holds an initial value w, then all of the honest processors eventually decide on this initial value w.

In this work we use the following three parameters to measure the quality of a BA protocol:

- Resilience: the maximum number of dishonest nodes allowed in the protocol, denoted by t.
- Communication complexity: the total number of communication bits during the protocol execution, denoted by b.
- Round complexity: the expected number of rounds taken by the protocol to terminate, denoted by r.

 1 The probability that an honest processor is undecided after r rounds approaches 0 as r grows to infinity [46].

We define the notion of *communication complexity exponent* of the ABA protocol as

$$\beta(\alpha, \delta) \triangleq \lim_{n \to \infty} \frac{\log b(n, \delta, \alpha)}{\log n}$$
 (1)

where $\alpha \triangleq \lim_{n \to \infty} \frac{\log \ell}{\log n}$ (message size exponent) and $\delta \triangleq \lim_{n \to \infty} \frac{\log t}{\log n}$ (faulty size exponent). β , α and δ capture the exponents of communication complexity b, the message size ℓ and faulty size t respectively with n as the base, when n is large.

Recall that a protocol is said to be signature-free if the protocol design does not depend on the cryptographic machinery such as hashing and signature. A protocol is said to be information-theoretic secure if the protocol can tolerate the computationally unbounded adversary.

III. MAIN RESULTS

In this section we will provide the main results of this work.

Theorem 1 (ABA). For the ABA problem, the proposed A-COOL is a signature-free multi-valued ABA protocol that reaches an agreement on an ℓ -bit value with communication complexity $O(\max\{n\ell, nt \log t\})$, given $n \geq 5t + 1$.

Proof. The proposed A-COOL protocol is provided in Section IV. $\hfill\Box$

Theorem 1 implies that the proposed A-COOL protocol achieves the optimal communication complexity $O(n\ell)$ when $\ell \geq t \log t$. The following result is directly derived from Theorem 1.

Corollary 1 (Communication complexity exponent). For the proposed A-COOL protocol, when $n \ge 5t + 1$, the communication complexity exponent is

$$\beta(\alpha, \delta) = \max\{1 + \alpha, 1 + \delta\}. \tag{2}$$

The proposed A-COOL protocol does not assume the cryptographic machinery such as hashing and signature (signature free). Also, the proposed protocol can tolerate the computationally unbounded adversary (information-theoretic secure).

IV. THE PROPOSED A-COOL PROTOCOL

In this section, we will provide the proposed A-COOL protocol. This proposed A-COOL protocol seeks to reach an agreement on an ℓ -bit value \boldsymbol{w} over n distributed processors $\{P_i\}_{i=1}^n$ under asynchronous communication. In the design of the A-COOL protocol, coding scheme is used to reduce the communication complexity during the information exchange steps. Specifically, the (n, k) Reed-Solomon error correction code will be used in the protocol design. We will show that the proposed A-COOL is a signature-free multi-valued ABA protocol that reaches an agreement on an ℓ -bit value with communication complexity $O(\max\{n\ell, nt \log t\})$, when $n \geq 5t+1$. This result serves as the proof of Theorem 1.

The proposed A-COOL protocol is composed of at most four phases, as shown in Algorithm 1. The proposed protocol is guaranteed to satisfy the termination, consistency, and validity conditions. In what follows, we will describe the four phases in detail. In the description of the proposed A-COOL, we will just consider the case of $t \leq \frac{n-1}{5}$ and $t = \Omega(n)$.

We first define some notations that will be used in the protocol design. Let $\boldsymbol{w}^{(i)}$ be the updated value at P_i , $i \in [1:n]$. Let $\mathbf{u}_i^{[p]}(j)$ be the binary link indicator for P_i and P_j , for $p \in [1:3]$ and $i,j \in [1:n]$. Let $\mathbf{s}_i^{[p]}$ be the binary success indicator at P_i , for $p \in [1:3]$ and $i \in [1:n]$. In our design the initial value of $\boldsymbol{w}^{(i)}$ is set as $\boldsymbol{w}^{(i)} = \boldsymbol{w}_i, i \in [1:n]$. The binary link indicator is initially set as $\mathbf{u}_i^{[1]}(j) = 0, i,j \in [1:n]$.

A. Phase 1: exchange symbols and update information

The main idea of Phase 1 is to exchange coded symbols and update information.

1) Encode and exchange symbols: By applying Reed-Solomon error correction code, $P_i, i \in [1:n]$, first encodes its ℓ -bit initial value w_i into ℓ/k -bit symbols as

$$y_j^{(i)} \triangleq \boldsymbol{h}_j^{\mathsf{T}} \boldsymbol{w}_i, \quad j \in [1:n]$$
 (3)

where \boldsymbol{h}_j is defined as $\boldsymbol{h}_j \triangleq [h_{j,1}, h_{j,2}, \cdots, h_{j,k}]^{\mathsf{T}}$, for

$$h_{j,m} \stackrel{\triangle}{=} \prod_{\substack{p=1\\p \neq m}}^{k} \frac{j-p}{m-p}, \quad j \in [1:n], \quad m \in [1:k].$$
 (4)

In our protocol design, the parameter k is designed as $k riangleq \left\lfloor \frac{t}{5} \right\rfloor + 1$. Note that for the (n,k) Reed-Solomon error correction code constructed in the Galois Field $GF(2^c)$, the condition of $n \leq 2^c - 1$ needs to be satisfied (cf. [47]). In this protocol, the parameter c is designed as

$$c \triangleq \left\lceil \frac{\max\{\ell, \ (t/5+1) \cdot \log(n+1)\}}{k} \right\rceil. \tag{5}$$

It can be verified that the condition of $n \leq 2^c - 1$ is satisfied with the designed parameters k and c. In this protocol, each coded symbol $y_j^{(i)}$ has c bits. After this encoding process, P_i , $i \in [1:n]$, sends a pair of coded symbols $(y_j^{(i)}, y_i^{(i)})$ to P_j for $j \in [1:n] \setminus i$.

2) Update information: Upon receiving n-t pairs of symbols $\{(y_i^{(j)},y_j^{(j)})\}_j$, P_i compares the received $(y_i^{(j)},y_j^{(j)})$ with its symbol pair $(y_i^{(i)},y_j^{(i)})$ and sets a link indicator $\mathbf{u}_i^{[1]}(j)$ as

$$\mathbf{u}_{i}^{[1]}(j) = \begin{cases} 1 & \text{if } (y_{i}^{(j)}, y_{j}^{(j)}) = (y_{i}^{(i)}, y_{j}^{(i)}) \\ 0 & \text{else} \end{cases}$$
 (6)

for $i \in [1:n]$. The value of $\mathbf{u}_i^{[1]}(j) = 0$ implies that P_i and P_j might have mismatched value, i.e., $\boldsymbol{w}^{(i)} \neq \boldsymbol{w}^{(j)}$. If $\mathbf{u}_i^{[1]}(j) = 0$, we consider the pair of $(y_i^{(j)}, y_j^{(j)})$ from P_j as a mismatched symbol pair at P_i . By counting the number of mismatched symbol pairs, P_i sets a success indicator $\mathbf{s}_i^{[1]}$ as

$$\mathbf{s}_{i}^{[1]} = \begin{cases} 1 & \text{if } \sum_{j=1}^{n} \mathbf{u}_{i}^{[1]}(j) \ge n - 2t \\ 0 & \text{else} \end{cases}$$
 (7)

for $i \in [1:n]$. The event of $\mathbf{s}_i^{[1]} = 0$ means that the number of mismatched symbol pairs is more than 2t, which implies

that the initial value of P_i does not match the majority of other processors' initial values. If $\mathbf{s}_i^{[1]} = 0$, P_i updates $\boldsymbol{w}^{(i)}$ as $\boldsymbol{w}^{(i)} = \phi$ (a default value), else keeps the original value of $\boldsymbol{w}^{(i)}$.

3) Exchange success indicators: P_i , $i \in [1:n]$, sends the value of success indicator $\mathbf{s}_i^{[1]}$ to $P_j, j \in [1:n] \setminus i$. Upon receiving n-t success indicators $\{\mathbf{s}_j^{[1]}\}_j$, P_i creates the sets:

$$S_1 \triangleq \{j : \mathbf{s}_j^{[1]} = 1, j \in [1:n]\}, \quad S_0 \triangleq [1:n] \setminus S_1 \quad (8)$$

based on $\{s_j^{[1]}\}_j$. In this step, different processors might have different views on S_0 and S_1 , due to the inconsistent value possibly sent from dishonest processors.

Remark 1. In Phase 1, since $y_j^{(i)}$ defined in (3) has c bits, the communication complexity of exchanging coded data (see Line 3 in Algorithm 1), denoted by b_1 , is $b_1 = 2cn(n-1)$ bits. Since the success indicator $\mathbf{s}_i^{[1]}$ has only 1 bit, the communication complexity of exchanging success indicators (see Line 14), denoted by b_2 , is $b_2 = n(n-1)$ bits.

Remark 2. Note that dishonest processors could send arbitrary (inconsistent) value to different honest processors, which could make honest processors output their updated values differently in this phase. Phase 2 will further handle the issue of inconsistent updated values among honest processors.

B. Phase 2: mask errors, and update success indicator

In this phase, the main goal is to mask errors from honest processors, based on the result of Phase 1.

- processors, based on the result of Phase 1.

 1) Mask errors: If $\mathbf{s}_i^{[1]} = 1$, P_i sets $\mathbf{u}_i^{[2]}(j) = \mathbf{u}_i^{[1]}(j), \forall j \in \mathcal{S}_1$ and $\mathbf{u}_i^{[2]}(j) = 0$, $\forall j \in \mathcal{S}_0$.
- 2) Exchange success indicators: If $\mathbf{s}_i^{[1]} = 1$, P_i updates $\mathbf{s}_i^{[2]}$ as in (7) using updated values of $\{\mathbf{u}_i^{[2]}(j)\}_{j=1}^n$, else sets $\mathbf{s}_i^{[2]} = 0$. Then P_i sends $\mathbf{s}_i^{[2]}$ to $P_j, j \in [1:n] \setminus i$. If $\mathbf{s}_i^{[2]} = 0$, P_i updates $\boldsymbol{w}^{(i)}$ as $\boldsymbol{w}^{(i)} = \phi$, else keeps the original value of $\boldsymbol{w}^{(i)}$.
- 3) Update S_0 and S_1 : Upon receiving n-t success indicators $\{s_j^{[2]}\}_j$, P_i updates the sets of S_0 and S_1 as in (8) for $i \in [1:n]$.

Remark 3. Since the success indicator $s_i^{[2]}$ has 1 bit, the communication complexity of exchanging success indicators in Phase 2 (see Line 26 in Algorithm 1), denoted by b_3 , is $b_3 = n(n-1)$ bits.

C. Phase 3: mask errors, update information, and vote

In Phase 3, the main goal is to mask the rest of the errors from the honest processors, and then vote for stopping in this phase or going to Phase 4.

- phase or going to Phase 4.

 1) Mask errors: If $\mathbf{s}_i^{[2]} = 1$, P_i sets $\mathbf{u}_i^{[3]}(j) = \mathbf{u}_i^{[2]}(j), \forall j \in \mathcal{S}_1$ and $\mathbf{u}_i^{[3]}(j) = 0$, $\forall j \in \mathcal{S}_0$.
- 2) Exchange success indicator: If $\mathbf{s}_i^{[2]} = 1$, P_i updates $\mathbf{s}_i^{[3]}$ as in (7) using updated values of $\{\mathbf{u}_i^{[3]}(j)\}_{j=1}^n$, else sets $\mathbf{s}_i^{[3]} = 0$. Then P_i sends $(\mathbf{s}_i^{[3]}, y_j^{(i)})$ to $P_j, j \in [1:n] \setminus i$. If $\mathbf{s}_i^{[3]} = 0$, P_i updates $\boldsymbol{w}^{(i)}$ as $\boldsymbol{w}^{(i)} = \phi$, else keeps the original value of $\boldsymbol{w}^{(i)}$.

Algorithm 1 : A-COOL protocol, code for P_i , $i \in [1:n]$

1: Set
$$w^{(i)} = w_i$$
; $u_i^{[1]}(j) = 0$, $j \in [1:n]$.

Phase 1

2: P_i encodes $w^{(i)}$ into n symbols as $y_j^{(i)} \triangleq h_j^{\mathsf{T}} w_i$, $j \in [1:n]$.

3: P_i sends $(y_j^{(i)}, y_i^{(i)})$ to P_j , $\forall j \in [1:n] \setminus i$.

4: **upon** receiving $n - t$ pairs of symbols $\{(y_i^{(j)}, y_j^{(j)})\}_j$

5: **for** each received $(y_i^{(j)}, y_j^{(j)})$ **do**

6: **if** $((y_i^{(j)}, y_j^{(j)}) = (y_i^{(i)}, y_j^{(i)}))$ **then**

7: P_i sets $u_i^{[1]}(j) = 1$.

8: **else**

9: P_i sets $u_i^{[1]}(j) = 0$.

10: **if** $(\sum_{j=1}^n u_i^{[1]}(j) >= n-2t)$ **then**

11: P_i sets $s_i^{[1]} = 1$.

12: **else**

13: P_i sets $s_i^{[1]} = 0$ and P_i and P_i sets P_i sets P_i sets P_i sets since P_i sets P_i sets P_i sets since P_i sets since P_i sets P

Phase 2

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17: if (s_i^{[1]} == 1) then
              \begin{split} &\overset{\cdot}{P_i} \text{ sets } \mathbf{u}_i^{[2]}(j) = \mathbf{u}_i^{[1]}(j), \forall j \in \mathcal{S}_1. \\ &P_i \text{ sets } \mathbf{u}_i^{[2]}(j) = 0, \forall j \in \mathcal{S}_0. \end{split}
19:
              if (\sum_{i=1}^{n} \mathbf{u}_{i}^{[2]}(j) >= n-2t) then
20:
                     P_i \text{ sets } s_i^{[2]} = 1.
21:
22:
                     P_i sets \mathbf{s}_i^{[2]} = 0 and \mathbf{w}^{(i)} = \phi.
23:
24: else
               P_i \text{ sets } s_i^{[2]} = 0.
26: P_i sends \mathbf{s}_i^{[2]} to P_j, j \in [1:n] \setminus i.
27: upon receiving n-t success indicators \{s_i^{[2]}\}_i
               P_i updates S_0 and S_1, based on \{s_i^{[2]}\}_i.
28:
```

Phase 3

29: **if**
$$(s_i^{[2]} == 1)$$
 then
30: P_i sets $u_i^{[3]}(j) = u_i^{[2]}(j), \forall j \in \mathcal{S}_1$.
31: P_i sets $u_i^{[3]}(j) = 0, \forall j \in \mathcal{S}_0$.
32: **if** $(\sum_{j=1}^n u_i^{[3]}(j) >= n-2t)$ **then**
33: P_i sets $s_i^{[3]} = 1$.
34: **else**
35: P_i sets $s_i^{[3]} = 0$ and $\boldsymbol{w}^{(i)} = \phi$.
36: **else**
37: P_i sets $s_i^{[3]} = 0$.
38: P_i sends $(s_i^{[3]}, y_j^{(i)})$ to $P_j, j \in [1:n] \setminus i$.
39: **upon** receiving $n-t$ success indicators $\{s_j^{[3]}\}_j$.
40: P_i updates \mathcal{S}_0 and \mathcal{S}_1 , based on $\{s_j^{[3]}\}_j$.
41: **if** $(\sum_j s_j^{[3]} >= n-2t)$ **then**
42: P_i sets $v_i = 1$.
43: **else**
44: P_i sets $v_i = 0$.
45: P_i runs the one-bit consensus with all other processors on the n votes $\{v_i\}_{i=1}^n$, by using the one-bit consensus protocol from [30].
46: **if** (the consensus of the votes $\{v_i\}_{i=1}^n$ is 1) **then**
 P_i goes to next phase.

Phase 4

48:

49:

50: **if**
$$(\mathbf{s}_i^{[3]} == 0)$$
 then
51: $y_i^{(i)} \leftarrow \text{Majority}(\{y_i^{(j)}: j \in \mathcal{S}_1\}).$
52: P_i sends $y_i^{(i)}$ to P_j , $\forall j \in [1:n] \setminus i.$
53: **if** $(\mathbf{s}_i^{[3]} == 0)$ **then**
54: **upon** receiving $n-t$ symbols $\{y_j^{(j)}\}_j$
55: P_i decodes message and updates it into $\boldsymbol{w}^{(i)}$ based on the received symbols.

 P_i outputs $\mathbf{w}^{(i)} = \phi$ as a final consensus and stops.

56: P_i outputs $w^{(i)}$ as the final consensus and stops.

3) Update S_0 and S_1 : Upon receiving n-t success indicators $\{s_j^{[3]}\}_j$, P_i updates the sets of S_0 and S_1 as in (8) for $i \in [1:n]$.

4) Vote: P_i , $i \in [1:n]$, sets a binary vote as

$$\mathbf{v}_i = \begin{cases} 1 & \text{if } \sum_j \mathbf{s}_j^{[3]} \ge n - 2t \\ 0 & \text{else} \end{cases} \tag{9}$$

based on the n-t received success indicators $\{s_j^{[3]}\}_j$. v_i denotes a vote from P_i for stopping in this phase or going to Phase 4.

5) One-bit consensus on the n votes: $P_i, i \in [1, n]$, runs the one-bit consensus with all other processors on the n votes $\{v_i\}_{i=1}^n$, by using the one-bit consensus protocol from [30].

The consensus can be reached with $O(n^2)$ bits of communication complexity, and O(1) rounds of round complexity, for t < n/5. If the consensus of the votes $\{v_i\}_{i=1}^n$ is 0, then every honest processor P_i outputs $\boldsymbol{w}^{(i)} = \phi$ as a final consensus and stops, else every honest processor goes to Phase 4.

Remark 4. In Phase 3, since $\mathbf{s}_i^{[3]}$ and $y_j^{(i)}$ has 1 bit and c bits respectively, the communication complexity of exchanging pairs of $(\mathbf{s}_i^{[3]}, y_j^{(i)})$, $i \in [1:n], j \in [1:n] \setminus i$ (see Line 38 in Algorithm 1), denoted by b_4 , is $b_4 = (1+c)n(n-1)$ bits.

Remark 5. The work of [30] provides the most efficient unauthenticated binary ABA protocol that achieves the communication complexity $O(n^2)$ and round complexity O(1), assuming a common coin oracle. Since we run the one-

bit consensus from [30], the communication complexity of invoking one-bit consensus (see Line 45 in Algorithm 1), denoted by b_5 , is $b_5 = O(n^2)$ bits. Since the round complexity of this step is constant (i.e., O(1)) and the round complexity of other steps is also constant, it gives that the round complexity of the proposed protocol is constant, i.e., O(1).

Remark 6. It can be proved that at the end of this phase, there exists at most 1 group of honest processors, where the honest processors within this group have the same non-empty updated value $(\mathbf{w}^{(i)} \neq \phi)$, and the honest processors outside this group have the same empty updated value $(\mathbf{w}^{(i)} = \phi)$.

D. Phase 4: exchange coded symbols and make consensus

The idea of this phase is to calibrate and update the final value of the honest processors in the set of S_0 such that every honest processor outputs the same value as the final consensus.

- 1) Update symbols with majority rule: P_i , $i \in \mathcal{S}_0$, updates the value of $y_i^{(i)}$ as $y_i^{(i)} \leftarrow \text{Majority}(\{y_i^{(j)}: j \in \mathcal{S}_1\})$, where the coded symbols $\{y_i^{(j)}\}_{j \in \mathcal{S}_1}$ were received in Phase 3. Majority(\bullet) is a function defined to return the most frequent value in the list, based on the majority rule. Note that P_i , $i \in \mathcal{S}_1$ keeps its previous value of $y_i^{(i)}$.
- 2) Broadcast updated symbol: $P_i, i \in [1:n]$, sends the value of $y_i^{(i)}$ to $P_j, \forall j \in [1:n] \setminus i$.
- 3) Decode: Upon receiving n-t coded symbols $\{y_j^{(j)}\}_j$, P_i decodes message and updates it into $\boldsymbol{w}^{(i)}$ using the n-t received symbols, for $i \in \mathcal{S}_0$. For P_i , $i \in \mathcal{S}_1$, it skips this step.
- 4) Stop: P_i , $i \in [1:n]$, outputs $\boldsymbol{w}^{(i)}$ as the final consensus and stops.

Remark 7. In Phase 4, since $y_i^{(i)}$ has c bits, the communication complexity of exchanging the coded symbols (see Line 52 in Algorithm 1), denoted by b_6 , is $b_6 = cn(n-1)$ bits.

Remark 8. Note that up to $\lfloor \frac{n-k}{2} \rfloor$ Byzantine errors can be corrected in the design of an (n,k) error correction code, using some efficient decoding algorithms [47]–[49]. It can be verified that in Step 3 of this phase, every honest processor decodes and outputs the same message, with the parameter design of k and c in this protocol.

E. Performance analysis of A-COOL

This section provides the performance analysis of the proposed A-COOL protocol.

Lemma 1. A-COOL reaches an agreement on an ℓ -bit value with the communication complexity of $O(\max\{n\ell, nt \log t\})$ bits and the round complexity of O(1) rounds, given $n \geq 5t + 1$.

Proof. The proposed A-COOL reaches an agreement on an ℓ -bit value given $n \geq 5t + 1$ (see Lemma 2).

By adding the communication complexity b_1, b_2, \dots, b_6 expressed in Remarks 1, 3, 4, 5 and 7, respectively, the total

communication complexity of the proposed A-COOL, denoted by b, is computed as

$$b = \sum_{i=1}^{6} b_{i}$$

$$= O(cn(n-1) + n^{2})$$

$$= O(\max\{\ell/t, \log n\} \cdot n(n-1) + n^{2})$$

$$= O(\max\{\ell n^{2}/t, n^{2} \log n\}) \text{ bits}$$
(10)

where c is designed as $c = \left\lceil \frac{\max\{\ell,\ (t/5+1)\cdot\log(n+1)\}}{k} \right\rceil$ for $k = \left\lfloor \frac{t}{5} \right\rfloor + 1$. In the description of the proposed A-COOL, we just considered the case of $t \leq \frac{n-1}{5}$ and $t = \Omega(n)$. For this case, the total communication complexity shown in (10) can be rewritten as $b = O(\max\{n\ell, nt\log t\})$ bits. It can also be shown that the same communication complexity performance can be achieved, for the case with relatively small t compared to n. Due to the lack of space, the detail is provided in the long version [50]. By combining the above two cases, we conclude that the total communication complexity of A-COOL is $b = O(\max\{n\ell, nt\log t\})$ bits.

Given that the round complexity of the one-bit consensus in Phase 3 is constant, it implies that the round complexity of the proposed protocol is constant, i.e., O(1).

Lemma 2. The proposed A-COOL is a signature-free ABA protocol, which satisfies the termination, consistency and validity conditions in all executions, given $n \ge 5t + 1$.

Proof. The proof of Lemma 2 will use the tools from coding theory and graph theory. Due to the lack of space, the proof is provided in the long version [50].

V. CONCLUSION

In this work, we studied the ABA problem and proposed a new signature-free protocol, i.e., A-COOL, which is communication efficient. Specifically, the proposed A-COOL protocol achieves the optimal communication complexity $O(n\ell)$ when $\ell \geq t \log t$, given $n \geq 5t+1$. The proposed A-COOL protocol can also be extended to the asynchronous Byzantine broadcast (ABB) problem, by adding one step of broadcasting ℓ -bit message from the leader to the distributed processors. The ℓ -bit message sent from the leader will serve as the initial value at every distributed node in the ABA problem. Then, the proposed A-COOL can be applied here to achieve the same performance as in the ABA setting, in terms of resilience, communication complexity and round complexity.

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