

Carnot metrics, dynamics and local rigidity

CHRIS CONNELL  †, THANG NGUYEN  ‡ and RALF SPATZIER  ‡

† *Department of Mathematics, Indiana University, Bloomington, IN 47405, USA*
(e-mail: connell@indiana.edu)

‡ *Department of Mathematics, University of Michigan, Ann Arbor, MI 48109, USA*
(e-mail: qtn@umich.edu, spatzier@umich.edu)

(Received 14 September 2021 and accepted in revised form 14 September 2021)

In memory of Anatole Katok

Abstract. This paper develops new techniques for studying smooth dynamical systems in the presence of a Carnot–Carathéodory metric. Principally, we employ the theory of Margulis and Mostow, Métivier, Mitchell, and Pansu on tangent cones to establish resonances between Lyapunov exponents. We apply these results in three different settings. First, we explore rigidity properties of smooth dominated splittings for Anosov diffeomorphisms and flows via associated smooth Carnot–Carathéodory metrics. Second, we obtain local rigidity properties of higher hyperbolic rank metrics in a neighborhood of a locally symmetric one. For the latter application we also prove structural stability of the Brin–Pesin asymptotic holonomy group for frame flows. Finally, we obtain local rigidity properties for uniform lattice actions on the ideal boundary of quaternionic and octonionic symmetric spaces.

Key words: sub-Riemannian geometry, dominated splittings, rigidity

2020 Mathematics Subject Classification: 53C17, 53C24, 37D40 (Primary); 53C20 (Secondary)

Contents

1	Introduction	615
1.1	Sub-Riemannian geometry	616
1.2	Smooth slow distributions	618
1.3	Hyperbolic rank rigidity	620
1.4	Local rigidity of projective actions	621
2	Background	621
2.1	Dynamics: dominated splittings	621
2.2	Algebra: varieties of Lie algebras and automorphism groups	622
3	Tangent cones of sub-Riemannian manifolds	626
3.1	Carnot metrics and the Métivier correspondence	626

3.2	Carnot derivatives of maps preserving horizontal distributions	629
4	Sub-Riemannian dynamics	639
5	Application: local rigidity of smooth dominated splittings	642
5.1	Time changes	643
5.2	Geodesic flows	644
5.3	Diffeomorphisms of nilmanifolds	646
5.4	Local rigidity of projective boundary actions	649
6	Local hyperbolic rank rigidity	651
6.1	Holonomy groups of perturbations and hyperbolic rank	652
6.2	Quaternionic and octonionic hyperbolic local rigidity	657
6.3	Measure of maximal entropy for perturbations	658
Acknowledgements		659
A	Appendix. A variation on Benveniste's lemma	659
References		662

1. *Introduction*

Totally non-integrable k -plane distributions E on a manifold N have been of considerable interest in partial differential equations, geometry and control theory. In particular, they play a central role in Hörmander's work on hypoelliptic partial differential operators (e.g. [Hör67]). Such operators arise naturally from nilpotent groups. Fundamental work of Folland, Goodman, Kohn, and Rothschild and Stein developed a converse.

Later on, Gromov [Gro81] introduced tangent cones for general metric spaces and found criteria for their existence. Namely, for a metric space (X, d) a tangent cone at $p \in X$ is a convergent limit in the pointed Gromov–Hausdorff topology of the sequence of pointed metric spaces $(X, p, \lambda d)$ as $\lambda \rightarrow \infty$. Note that tangent cones do not always exist, and when they do exist, they are not always unique. Spun from a key result of Métivier [Mét76], Gromov, Mitchell, Margulis and Mostow, and Pansu, among others, have investigated the existence, uniqueness and structure of the pointed tangent cones for Carnot–Carathéodory metrics [Gro81, Gro96, MM00, MM95, Mit85, Pan89].

In the present paper we explore these tangent cones with the goal of establishing new techniques for the study of Lyapunov exponents of dynamical systems respecting sub-Riemannian metrics. We suspect that such systems will typically possess algebraic features. For example, we use these techniques to establish criteria for the Lyapunov spectra to be arithmetic progressions. This fits into the scope of the recent dueling programs between flexibility and rigidity of Lyapunov exponents. Indeed, pointwise arithmeticity of the Lyapunov spectrum sometimes leads to complete rigidity of the dynamics [But19, But18]. Further afield, constancy or extremality of the Lyapunov spectrum in certain cases yields local rigidity (cf. [Con03, DeW19, DSLVY20, GKS11, GKS20, SY19]). These contrast with results about flexibility of the Lyapunov spectrum for tori and surfaces, (see [BE20, BKH21, CS21, EK19]).

The arithmeticity of Lyapunov spectra has ramifications for both Riemannian geometry and group actions. Indeed, we will discuss rigidity of hyperbolic rank structures in §1.3 and local rigidity of projective actions in §1.4.

1.1. *Sub-Riemannian geometry.* We recall that a smooth manifold N is called a *sub-Riemannian manifold* if

- (1) N is equipped with a smooth distribution E , called a *horizontal distribution*, which satisfies Hörmander's condition (i.e., vector fields tangent to E and their iterated brackets generate TN) and
- (2) E is endowed with a smooth Riemannian metric $\langle \cdot, \cdot \rangle_x$.

The Carnot–Carathéodory metric d_C on N between a pair of points x and y is defined as the infimum of length of curves tangent to E from x to y . By a theorem of Chow [Cho39], the Carnot–Carathéodory metric d_C is finite on connected components of N .

For a horizontal distribution E , at each point $x \in N$ and $i \geq 1$ we define E_x^i to be the subspace of $T_x N$ spanned by all i -fold commutators of vector fields tangent to E . We call a horizontal distribution E *generic (of order r)* at a point $p \in N$ if on a neighborhood U of p the subspaces E_x^i fit together to form a strictly increasing sequence of (smooth) subbundles

$$E = E^0 \subset E^1 \subset \cdots \subset E^r = TU.$$

In this setting, Mitchell [Mit85] showed that the tangent cones at generic points of N are graded nilpotent Lie groups equipped with left-invariant Carnot–Carathéodory metrics which are unique by Margulis and Mostow [MM00]. Following Pansu [Pan89], Margulis and Mostow also developed the notion of a Pansu derivative of a quasi-conformal map on a sub-Riemannian manifold. We will be applying this construction to maps preserving a distribution.

We develop these ideas to understand the dynamics of differentiable maps preserving suitable distributions. Combining the main theorem of Mitchell [Mit85] together with Proposition 3.4 and analyzing (cf. Proposition 3.8) the proof of the main theorem of Margulis and Mostow [MM95] provides the catalyst for our investigations.

THEOREM 1.1. (Tangent cone structure theorem) *Let $f : N \rightarrow N$ be a local C^∞ diffeomorphism of a sub-Riemannian manifold N preserving the horizontal distribution E . Then the set $\Omega := \{x \in N : E \text{ is generic at } x\}$ is open dense and f -invariant. Moreover, we have the following statements.*

- (1) *For every $x \in \Omega$, the tangent cone $TC_x N$ of N at x exists, is a graded nilpotent Lie group with a left invariant Carnot–Carathéodory metric and the tangent cones vary continuously on Ω with respect to the Gromov–Hausdorff topology.*
- (2) *The map f induces a graded Lie group isomorphism $(f_*)_x : TC_x N \rightarrow TC_{f(x)} N$ between the tangent cones $TC_x N$ of N at $x \in \Omega$ and $TC_{f(x)} N$ of N at $f(x)$. We call $(f_*)_x$ the Carnot derivative of f at x .*

With substantially more work, we later prove a foliated version of this theorem (Theorem 4.2). Applying this to an unstable foliation will provide applications in the dynamical setting.

Next we consider the relation between the Carnot derivative and the ordinary one. In the following three theorems we employ a detailed investigation of the proof of the Margulis–Mostow theorem [MM95].

THEOREM 1.2. (Subadditivity of the spectrum at periodic points) *Let $f : N \rightarrow N$ be a local C^∞ diffeomorphism of a sub-Riemannian manifold N preserving the horizontal distribution E . Assume that E is generic at a point $p \in N$ where $f(p) = p$. Suppose the tangent cone $TC_p N$ is $(r+1)$ -step and set $n_{-1} = 0$ and $n_i = \dim E^i(p)$ for $i \in \{0, \dots, r\}$. If $D_p f|_{E_p^i}$ has Lyapunov exponents $(\log \lambda_1, \log \lambda_2, \dots, \log \lambda_{n_0}, \log \lambda_{n_0+1}, \dots, \log \lambda_{n_1}, \dots, \log \lambda_{n_i})$ listed with multiplicity and with $\log \lambda_{n_{j-1}+1}, \dots, \log \lambda_{n_j}$ in non-decreasing order for each $j \in \{0, \dots, i\}$, then for each $i \in \{0, \dots, r\}$ and $j \in \{n_{i-1}+1, \dots, n_i\}$ we have $(i+1) \log \lambda_1 \leq \log \lambda_j \leq (i+1) \log \lambda_{n_0}$.*

Note that at a fixed point, the Lyapunov exponents simply amount to being the logs of the magnitude of the eigenvalues of $D_p f$. In the special case when the tangent cone is the Heisenberg group with its standard contact structure and Carnot–Carathéodory metric, we have a stronger statement.

THEOREM 1.3. (Additivity of the spectrum for Heisenberg cones at periodic points) *Let $f : N \rightarrow N$ be a local C^∞ diffeomorphism of a sub-Riemannian manifold N preserving the horizontal distribution E . Assume that E is generic at a point $p \in N$ where $f(p) = p$. Suppose the tangent cone $TC_p N$ is isomorphic to the Heisenberg group H^{2n+1} . If $\log \lambda_1, \log \lambda_2, \dots, \log \lambda_{2n}$ are the Lyapunov exponents of $D_p f|_E$ listed with multiplicity and $\log \lambda_{2n+1}$ is the remaining Lyapunov exponent of $D_p f$, then $\log \lambda_1 + \log \lambda_2 + \dots + \log \lambda_{2n} = n \log \lambda_{2n+1}$.*

For our next result, given an $(r+1)$ -step graded nilpotent Lie group \mathcal{N} , we denote its graded Lie algebra by $\mathfrak{n} = \bigoplus_{i=0}^r \mathfrak{n}^i$ where $\mathfrak{n}^0, \mathfrak{n}^1 = [\mathfrak{n}^0, \mathfrak{n}^0], \dots, \mathfrak{n}^r = [\mathfrak{n}^r, \mathfrak{n}^0]$. Suppose $f : N \rightarrow N$ is a diffeomorphism of a sub-Riemannian manifold N preserving its distribution E . If the Carnot derivative of f at a fixed point where E is generic is a homothety, then the Lyapunov spectrum is arithmetic.

THEOREM 1.4. (Arithmeticity of the spectrum at periodic points) *Let $f : N \rightarrow N$ be a local C^∞ diffeomorphism of a sub-Riemannian manifold N preserving the horizontal distribution E . Assume that E is generic at a point $p \in N$ where $f(p) = p$, and that the graded automorphism $f_* : TC_p N \rightarrow TC_p N$ induced from f is a homothety. Then there exists a $\lambda > 1$ such that $D_p f|_{E_p^i}$ has Lyapunov exponents $\log \lambda, 2 \log \lambda, \dots, (i+1) \log \lambda$ with corresponding multiplicities $\dim \mathfrak{n}^0, \dots, \dim \mathfrak{n}^i$ for $i = 0, \dots, r$.*

We call a graded nilpotent Lie group *asymmetric* (cf. Definition 2.6 and Lemma 2.7) if its group of graded automorphisms consists of homotheties with respect to some Carnot–Carathéodory metric induced by an inner product on \mathfrak{n}^0 . The asymmetric groups are open in the space of isomorphism classes of nilpotent groups with a given grading, and sometimes non-empty (cf. Examples 2.8 and Corollary 2.10). Since Theorem 1.4 holds for any choice of sub-Riemannian metric on N , induced from an inner product on E , we have the following corollary.

COROLLARY 1.5. *In the above theorem, when TC_pN is an asymmetric nilpotent group, the conclusion holds without the assumption that the induced graded automorphism f_* is a homothety.*

We will apply the natural extension of this theorem to the case of a C^1 diffeomorphism $f : X \rightarrow X$ (or flow $\varphi_t : X \rightarrow X$) leaving invariant a foliation \mathcal{F} with C^∞ leaves tangent to a continuous distribution D . If $E \subseteq D$ is a df -invariant continuous subdistribution, we define the set

$$\Omega = \{v \in X : E \text{ is } C^\infty \text{ in a neighborhood of } v \text{ in } \mathcal{F}(v) \text{ and is horizontal and generic there}\}.$$

Suppose that the distribution E is uniformly C^k along \mathcal{F} (cf. Definition 4.4) for a sufficiently large k and that \mathcal{F} is transversally Hölder continuous. Also assume that f (or the flow φ_t) is C^∞ along leaves, topologically transitive, satisfies the stable closing property (cf. Definition 4.7), and that $df|_D$ is transversally Hölder continuous.

In this setting, the foliated tangent cone structure theorem (Theorem 4.2; cf. Corollary 4.6) provides a common isomorphism class, associated to the distribution D , of graded nilpotent Lie group structures for all tangent cones $TC_v\mathcal{F}(v)$ with $v \in \Omega$ and whose metrics vary continuously on Ω . This leads to our main rigidity result for Lyapunov exponents along leaves of the foliation.

THEOREM 1.6. (Arithmeticity of the Lyapunov spectrum) *Suppose that the graded nilpotent group associated to D on Ω is asymmetric and $(r+1)$ -step. Let μ be any finite f -invariant (respectively, φ_t -invariant) ergodic measure whose support $\text{Supp}(\mu)$ satisfies $\text{Supp}(\mu) \cap \Omega \neq \emptyset$. Then the Lyapunov exponents of f (respectively, φ_1) along \mathcal{F} are $\log \lambda, 2 \log \lambda, \dots, (r+1) \log \lambda$ with multiplicities $\dim E, \dim E^1 - \dim E, \dots, \dim E^r - \dim E^{r-1}$ for some $\lambda = \lambda_\mu > 1$.*

We now consider some applications of the above results.

1.2. Smooth slow distributions. One family of examples where asymmetric nilpotent groups naturally arise are the quaternionic hyperbolic and octonionic hyperbolic symmetric spaces. Here the tangent cones of the stable and unstable foliations of a geodesic flow on compact quotients of these spaces are naturally isomorphic to certain asymmetric nilpotent groups of Heisenberg type (see Examples 2.8 below) corresponding to the nilradical of the full isometry group.

In the case when a flow nearby one of these symmetric flows still has smooth slow distribution we show it is orbit equivalent to the symmetric one.

THEOREM 1.7. *Let ϕ_t^0 be the geodesic flow on a locally quaternionic hyperbolic or octonionic hyperbolic closed manifold M . Then if ϕ_t is any C^∞ flow C^1 -close to ϕ_t^0 for which $E_{\text{slow}, \phi_t}^u$ remains C^∞ along unstable leaves and is sufficiently uniformly C^1 -close (in the sense of Definition 5.2) to that of ϕ_t^0 , then ϕ_t is C^∞ orbit equivalent to ϕ_t^0 .*

We suspect that strong rigidity properties hold whenever slow (un)stable distributions are smooth along leaves of the (un)stable foliation.

Questions 1.8. Can we characterize Anosov or partially hyperbolic diffeomorphisms or flows with smooth E_{slow}^u distributions along the unstable foliation? When are these smoothly orbit equivalent to algebraic ones? Is it sufficient that E_{slow}^u be smooth along unstable leaves and completely non-integrable there?

Note that there are simple non-algebraic examples coming from smooth time changes and suspensions of products (see §5.1). We also remark that there are numerous algebraic Anosov examples (e.g. on tori or products) where the slow distribution is integrable.

We obtain stronger rigidity properties if we restrict to geodesic flows.

THEOREM 1.9. *Let g_0 be a locally quaternionic hyperbolic or octonionic hyperbolic metric on a smooth closed manifold M . Then g_0 is locally rigid within the family of C^2 -close C^∞ metrics whose E_{slow}^u remains C^∞ along unstable leaves and is sufficiently uniformly C^1 -close (in the sense of Definition 5.2) to that of g_0 .*

Another class we can handle are Anosov diffeomorphisms on nilmanifolds arising from asymmetric nilpotent groups. Let M be a closed manifold and let f_0 be a transitive C^∞ Anosov diffeomorphism such that tangent cones of unstable leaves exist everywhere and are isomorphic to a fixed asymmetric $(r+1)$ -step Carnot nilpotent Lie group N . Let E_{slow, f_0}^u be the horizontal distribution along unstable leaves that gives rise to the (graded) structure of N . (As it turns out, E_{slow, f_0}^u is the slow distribution of smallest dimension which is still horizontal.) We obtain the following local spectral rigidity theorem.

THEOREM 1.10. *There is a C^1 open neighborhood U of f_0 in $\text{Diff}^\infty(M)$ such that if $f \in U$ admits a smooth splitting $E_f^u = E_{\text{fast}, f}^u \oplus E_{\text{slow}, f}^u$ along unstable leaves with $\dim(E_{\text{slow}, f}^u) = \dim(E_{\text{slow}, f_0}^u)$, and $E_{\text{slow}, f}^u$ is sufficiently uniformly C^r -close along unstable leaves to E_{slow, f_0}^u , then for any invariant ergodic measure μ there is $\lambda_\mu > 1$ such that the unstable Lyapunov exponents of f with respect to μ , are $\log \lambda_\mu, 2 \log \lambda_\mu, \dots, (r+1) \log \lambda_\mu$ occurring with the same multiplicities as for f_0 .*

We may apply the above theorem to certain Anosov diffeomorphisms that arise on compact nilmanifolds arising as quotients of products of asymmetric nilpotent groups.

COROLLARY 1.11. *Let N be an asymmetric r -step Carnot rational nilpotent group. Let Γ be the lattice and f_0 the Anosov automorphism of $M = (N \times N)/\Gamma$ obtained from Example 5.12. Then there is a C^1 open neighborhood U of f_0 in $\text{Diff}^\infty(M)$ such that if $f \in U$ admits a smooth splitting $E_f^u = E_{\text{fast}, f}^u \oplus E_{\text{slow}, f}^u$ along unstable leaves and $E_{\text{slow}, f}^u$ is sufficiently uniformly C^r -close along unstable leaves to E_{slow, f_0}^u , then for any invariant ergodic measure μ there is $\lambda_\mu > 1$ such that the unstable Lyapunov exponents of f with respect to μ are $\log \lambda_\mu, 2 \log \lambda_\mu, \dots, (r+1) \log \lambda_\mu$ with the corresponding multiplicities as for f_0 .*

Using Theorem 1.3, we obtain a similar corollary to the one above, but for an Anosov automorphism of a nilmanifold arising as a quotient of a non-asymmetric nilpotent group.

COROLLARY 1.12. *Let N be the three-dimensional Heisenberg group. Let Γ be the lattice and f_0 the Anosov automorphism of $M = (N \times N)/\Gamma$ obtained from Example 5.14. Then there is a C^1 open neighborhood U of f_0 in $\text{Diff}^\infty(M)$ such that if $f \in U$ admits a smooth splitting $E_f^u = E_{\text{fast},f}^u \oplus E_{\text{slow},f}^u$ along unstable leaves and $E_{\text{slow},f}^u$ is sufficiently uniformly C^1 -close along unstable leaves to E_{slow,f_0}^u , then for any invariant ergodic measure μ the unstable Lyapunov exponents for f are $\log \lambda_1, \log \lambda_2$ and $\log \lambda_1 + \log \lambda_2$ for some $\lambda_1 > 1$ and $\lambda_2 > 1$ depending on μ .*

1.3. Hyperbolic rank rigidity. A Riemannian manifold M has *higher hyperbolic rank* if every geodesic $c(t)$ in M has a Jacobi field $J(t)$ that makes sectional curvature $\kappa \cong -1$ with $c'(t)$ where $J(t) \neq 0$. Clearly, all rank-one locally symmetric spaces of negative curvature have higher hyperbolic rank after a trivial rescaling of the metric. We made the following conjecture regarding the converse in our recent paper [CNS20, Conjecture 1.3].

Conjecture 1.13. A closed Riemannian manifold with sectional curvatures $\kappa \geq -1$ has higher hyperbolic rank only if it is locally symmetric.

In that paper, we also proved the special case of Conjecture 1.13 when the sectional curvatures satisfy $-\frac{1}{4} \geq \kappa \geq -1$ [CNS20, Theorem 1.1]. Using ergodicity of 2-frame flows, Constantine [Con08, Corollary 1] had already characterized constant curvature manifolds by the hyperbolic rank condition for either odd-dimensional manifolds, just assuming non-positive curvature, or under strong pinching assumptions on the curvature, $-(.93)^2 \geq \kappa \geq -1$. We refer to [CNS20] for more historical discussion, in particular of Hamenstädt's hyperbolic rank rigidity theorem when the curvature is bounded above by -1 .

The current paper began as a sequel to our previous work on the hyperbolic rank rigidity conjecture [CNS20], and indeed we do achieve new results towards Conjecture 1.13. Along the way, we also advance techniques surrounding the Brin–Pesin asymptotic holonomy group for frame flows. We further establish various versions of local rigidity of geodesic flows near the rank-one locally symmetric ones.

One of the main results of the current paper, arising as an application of the results above, is the following local rigidity result for perturbations of locally symmetric metrics with higher hyperbolic rank.

THEOREM 1.14. *Let (M, g_0) be a closed quaternionic or octonionic hyperbolic locally symmetric manifold. Then there is an open C^3 neighborhood U of g_0 such that, for any $g \in U$, if (M, g) has higher hyperbolic rank and $\kappa_g \geq -1$ then (M, g) is locally symmetric.*

By Mostow rigidity, it follows that (M, g) is isometric to (M, g_0) . This of course fails for hyperbolic surfaces. Nevertheless, local rigidity in the real hyperbolic case already follows from our previous paper [CNS20].

Our methods do not give us full local rigidity of higher hyperbolic metrics nearby the complex hyperbolic metric. However, we still obtain equality of the Liouville measure and the Bowen–Margulis measure (the unique measure of maximal entropy) for higher-rank perturbations.

THEOREM 1.15. *Let (M, g_0) be a closed complex hyperbolic manifold. There is an open neighborhood U of g_0 in the C^3 topology among C^∞ metrics with the following property: for $g \in U$ with higher hyperbolic rank and sectional curvature $\kappa \geq -1$, the Liouville measure on SM coincides with the (unique) measure of maximal entropy for the geodesic flow of g on SM .*

1.4. Local rigidity of projective actions. Sullivan initiated the study of local rigidity of lattice actions on boundary spheres in [Sul85]. There have since appeared a number of results of this kind in various contexts (see, for example, [Asa17, Ghy93, Yue95]). We use our methods to establish local rigidity for certain lattice actions on spheres. First recall that the identity component G of the isometry group of a symmetric space acts by diffeomorphisms on its ideal boundary sphere preserving a smooth distribution E_0 , the projection of the slow distribution. This action may also be described in an algebraic way as follows. If $P < G$ is any minimal parabolic subgroup, then we may identify the ideal boundary sphere with G/P on which G naturally acts on the left. We will refer to this action by G , or any subgroup of G , as a projective action.

THEOREM 1.16. *Let $\rho_0 : \Gamma \rightarrow \text{Diff}^\infty(S^k)$ for $k = 4n - 1$ (respectively, $k = 15$) be the projective representation of a cocompact lattice $\Gamma < Sp(n, 1)$ (respectively, $\Gamma < F_4^{-20}$). Let $\rho : \Gamma \rightarrow \text{Diff}^\infty(S^k)$ be a C^1 -close perturbation of ρ_0 . If ρ preserves a C^∞ distribution E , C^1 -close to E_0 , then ρ is C^∞ conjugate to ρ_0 .*

We note that for a sufficiently small C^1 perturbation ρ of ρ_0 there always exists a distribution E which is C^0 -close to E_0 by stability of dominated splittings (see §2.1).

2. Background

2.1. Dynamics: dominated splittings. We begin by reviewing some basic definitions and results about dominated splittings. We will be using these in some of the arguments below.

Definition 2.1. Let $V \rightarrow X$ be a C^0 vector bundle equipped with a continuously varying norm on fibers over a compact smooth manifold X and $\Lambda \subset X$ be an closed invariant subset for a flow $\varphi_t : X \rightarrow X$. We say that Λ admits a *dominated splitting of index k* for a cocycle $\alpha : V \times \mathbb{R} \rightarrow V$ over φ_t provided:

- (1) V restricted to Λ splits into two continuous subbundles $V|_\Lambda = E \oplus F$, both invariant under α_t and with $\dim E = k$; and
- (2) there exist $C > 0$ and $0 < \lambda < 1$ such that for any $x \in \Lambda$,

$$\|\alpha_t|_{E_x}\| \|\alpha_{-t}|_{F_{\varphi_t(x)}}\| \leq C\lambda^t \quad \text{for all } t \geq 0. \quad (2.1)$$

Morally, this definition states that any vector not in E converges uniformly exponentially fast to the subbundle F under α_t .

Examples of dominated splittings include:

- Anosov geodesic flows φ_t on X where $V = TX$, $E = E^{cs} = E^s \oplus E^c$ center (weak) stable distribution, $F = E^u$ strong unstable distribution and $\alpha = d\varphi_t$;

- geodesic flows of locally symmetric manifolds M of non-constant negative curvature restricted to the unstable bundle where $X = SM$, the unit tangent bundle, $V = E^u$ strong unstable distribution, $E = E_{\text{slow}}^u$, $F = E_{\text{fast}}^u$ and $\alpha = d\varphi_t$;
- a one-parameter semisimple subgroup φ_t of a semisimple Lie group where $X = G/\Gamma$ for a cocompact lattice $\Gamma < G$, $V = E^u$ strong unstable distribution, $E = E_{<\lambda}^u$, $F = E_{\geq\lambda}^u$ for any λ in the interior of the Lyapunov spectrum and $\alpha = d\varphi_t$;
- geodesic flows of non-constant negatively curved manifolds with higher hyperbolic rank where $V = E^u$, $E = E_{\text{slow}}^u$, $F = E_{\text{fast}}^u$ and $\alpha = d\varphi$. (cf. §6).

An important property of dominated splittings is that they are stable under perturbations (cf. [Sam16, Proposition 2.3] for the case of a derivative of a map and [CP15, Corollary 2.8] applied to the time-one map of a flow). The proofs of the following proposition were written for the case of tangent bundles and derivative cocycles but apply equally well to the case of general vector bundles and cocycles as in Definition 2.1 (see also [BPS19]).

PROPOSITION 2.2. [CP15, Sam16] *Any sufficiently small C^0 perturbation of a cocycle admitting a dominated splitting also admits a dominated splitting of the same index.*

2.2. Algebra: varieties of Lie algebras and automorphism groups. The space of n -dimensional Lie algebras can be identified with the space of Lie brackets on \mathbb{R}^n . Thus it is

$$\mathcal{L}_n = \{c \in \text{Hom}(\Lambda^2 \mathbb{R}^n, \mathbb{R}^n) : c(c(u, v), w) + c(c(v, w), u) + c(c(w, u), v) = 0 \text{ for all } u, v, w \in \mathbb{R}^n\}.$$

Since the defining condition is a quadratic polynomial in the structure coefficients of the bracket c relative to the standard basis of \mathbb{R}^n , \mathcal{L}_n is an affine subvariety of $\text{Hom}(\Lambda^2 \mathbb{R}^n, \mathbb{R}^n)$. The space of n -dimensional nilpotent Lie algebras is

$$\mathcal{NL}_n = \{c \in \mathcal{L}_n : c(c(\dots c(c(u_1, u_2), u_3), \dots), u_n) = 0 \text{ for all } u_1, \dots, u_n \in \mathbb{R}^n\}.$$

This is an algebraic affine subvariety of \mathcal{L}_n since the defining condition is polynomial in the structure coefficients.

Two Lie algebras on \mathbb{R}^n are isomorphic if and only if there is a general linear transformation of \mathbb{R}^n that maps one Lie bracket to the other Lie bracket. Thus, the moduli space of isomorphism classes of nilpotent Lie algebras of dimension n is $\mathcal{NL}_n/\text{GL}(n, \mathbb{R})$.

We will need the following in §4.

THEOREM 2.3. ([BS64], cf. [Zim84, Theorem 3.1.3]) *Orbits of real points of an algebraic group acting on the real points of a real algebraic variety are locally closed in the Hausdorff topology.*

As a consequence, the orbits of $\text{GL}(n, \mathbb{R})$ on \mathcal{NL}_n are locally closed and $\mathcal{NL}_n/\text{GL}(n, \mathbb{R})$ is countably separated and hence Hausdorff.

We now discuss the automorphism group of a Lie group. We start with the following proposition.

PROPOSITION 2.4. *Let G be a connected and simply connected Lie group with Lie algebra \mathfrak{g} . Then the automorphism group $\text{Aut}(G)$ is naturally isomorphic as a Lie group to $\text{Aut}(\mathfrak{g})$ and the latter is a real algebraic variety in $\text{GL}(\mathfrak{g})$.*

Proof. For connected G , $\text{Aut}(G)$ is a closed subgroup of $\text{Aut}(\mathfrak{g})$ with Lie algebra $\text{Der}(\mathfrak{g})$ and these coincide when G is simply connected (cf. [Var84, Theorem 2.75]). Picking a basis of the Lie algebra, a Lie algebra automorphism is completely determined by its associated matrix with respect to this basis. The bracket relations on basis elements give us quadratic polynomial relations in these matrix coefficients. Moreover, any matrix satisfying these relations induces an automorphism. Hence, these polynomial relations provide $\text{Aut}(\mathfrak{g})$ with the structure of a real affine variety in $\text{GL}(\mathfrak{g}) \subset \mathbb{P}_{\mathbb{R}}^{(\dim \mathfrak{g})^2}$. \square

A nilpotent Lie algebra \mathfrak{g} is *graded* if it admits a decomposition $\mathfrak{g} = \bigoplus_{i=0}^r \mathfrak{g}^i$ where $[\mathfrak{g}^i, \mathfrak{g}^j] \subseteq \mathfrak{g}^{i+j}$ for all $i, j \geq 0$ with $i + j \leq r$ and $[\mathfrak{g}^i, \mathfrak{g}^j] = 0$ otherwise. We call a nilpotent Lie algebra \mathfrak{g} *Carnot* if it is graded and $[\mathfrak{g}^0, \mathfrak{g}^j] = \mathfrak{g}^{j+1}$ for all $0 \leq j \leq r - 1$. A nilpotent Lie group G is called *graded* (respectively, *Carnot*) if its Lie algebra is graded (respectively, Carnot). We also call an automorphism of a graded Lie algebra \mathfrak{g} *graded* if it respects the grading. Finally, an automorphism of a connected graded nilpotent group G is *graded* if its corresponding automorphism in $\text{Aut}(\mathfrak{g})$ is graded.

PROPOSITION 2.5. *Let G be a connected and simply connected graded nilpotent Lie group with Lie algebra $\mathfrak{g} = \bigoplus_{i=0}^r \mathfrak{g}^i$. Then the graded automorphism group $\text{Aut}_g(G)$ is isomorphic as a Lie group to the graded automorphism group $\text{Aut}_g(\mathfrak{g})$ of the Lie algebra and the latter is a real algebraic variety in $\bigoplus_{i=0}^r \text{GL}(\mathfrak{g}^i) < \text{GL}(\mathfrak{g})$. In particular, $\text{Aut}_g(\mathfrak{g})$ is a real algebraic group.*

Proof. It is clear that automorphisms preserving the grading are a subgroup of automorphisms lying in $\bigoplus_{i=0}^r \text{GL}(\mathfrak{g}^i) < \text{GL}(\mathfrak{g})$. It is easy to check that the subgroup $\text{Aut}_g(\mathfrak{g}) < \text{Aut}(\mathfrak{g})$ corresponds to the subgroup $\text{Aut}_g(G) < \text{Aut}(G)$ under the natural isomorphism given by the previous proposition. It remains to show that $\text{Aut}_g(\mathfrak{g})$ is a subvariety of $\text{Aut}(\mathfrak{g})$. However, as the graded subspaces are linear, the additional defining equations for the corresponding matrix elements are linear relations. Hence $\text{Aut}_g(\mathfrak{g})$ is also a real algebraic subvariety. Lastly, groups which are real algebraic subvarieties of an algebraic group are themselves algebraic groups. \square

When G is a simply connected graded nilpotent Lie group we can define a one-parameter group of automorphisms $\delta_s : G \rightarrow G$ called the *dilations* whose associated Lie algebra automorphisms $\delta_s : \mathfrak{g} \rightarrow \mathfrak{g}$ are the linear maps given by $\delta_s(x) = s^i x$ for all $x \in \mathfrak{g}^i$. We denote the group of all dilations by $\mathcal{D} = \{\delta_s : s \in \mathbb{R}_+\}$ and observe that it is isomorphic to the multiplicative group \mathbb{R}_+ . The dilations are always in the center of $\text{Aut}_g(\mathfrak{g})$ since they are multiples of the identity on each level.

If \mathfrak{g} is a Carnot Lie algebra then any automorphism in $\text{Aut}_g(\mathfrak{g}) < \bigoplus_{i=0}^r \text{GL}(\mathfrak{g}^i)$ is completely determined by its component in $\text{GL}(\mathfrak{g}^0)$. Consequently, we may identify $\text{Aut}_g(\mathfrak{g})$ with a subgroup of $\text{Aut}_g(\mathfrak{g}^0)$ and write $\text{Aut}_g(\mathfrak{g}) = L\mathcal{D}$ where $L < \text{SL}_{\pm}(\mathfrak{g}^0)$. (Here $\text{SL}_{\pm}(\mathfrak{g}^0)$ is the subgroup of $\text{GL}(\mathfrak{g}^0)$ with elements of determinant ± 1 .) Henceforth we set $d_i = \dim \mathfrak{g}^i$ for $i = 0, \dots, r$.

Definition 2.6. We call a graded nilpotent Lie group G , and its Lie algebra \mathfrak{g} , *asymmetric* if its graded automorphism group has the form $\text{Aut}_g(\mathfrak{g}) = LD$ where L belongs to a compact subgroup of $\text{SL}_\pm(d_0, \mathbb{R})$.

Recall that a surjective map $f : X \rightarrow Y$ between metric spaces is a homothety if $d(f(x), f(y)) = Cd(x, y)$ for some constant $C > 0$ and every $x, y \in X$. If a graded nilpotent Lie group G is Carnot, then we may equip G with a left-invariant Carnot–Carathéodory metric arising from the right invariant distribution corresponding to \mathfrak{g}^0 equipped with any inner product. In this case, the dilations δ_s are homotheties as they simply act by the appropriate scalar multiple of the identity on each level preserving the bracket relations. While other non-trivial automorphisms may be homotheties, for example those that restrict to an isometry on the first level, in general they need not all be homotheties. The next lemma shows that being asymmetric is equivalent to $\text{Aut}_g(\mathfrak{g})$ consisting of homotheties for some Carnot–Carathéodory metric.

LEMMA 2.7. *Let \mathfrak{g} be a Carnot Lie algebra equipped with a right invariant Carnot–Carathéodory metric. If $\text{Aut}_g(\mathfrak{g})$ consists entirely of homotheties, then \mathfrak{g} is asymmetric. Conversely, if \mathfrak{g} is an asymmetric Carnot Lie algebra then $\text{Aut}_g(\mathfrak{g})$ consists of homotheties with respect to some right invariant Carnot–Carathéodory metric.*

Proof. If $\text{Aut}_g(\mathfrak{g}) = LD$ consists of homotheties of a Carnot–Carathéodory metric, then $L < \text{SL}_\pm(\mathfrak{g}^0)$ and each element of L is uniquely determined by its action on \mathfrak{g}^0 . Moreover, each element of L must be an isometry with respect to the given inner product $\langle \cdot, \cdot \rangle_0$ on \mathfrak{g}^0 . Hence L belongs to the compact group $O(d_0, \langle \cdot, \cdot \rangle_0)$.

Conversely, if $\text{Aut}_g(\mathfrak{g}) = LD$ where $L < K$ for some compact subgroup $K < \text{SL}_\pm(d_0, \mathbb{R})$, then K is conjugate into $O(d_0, \langle \cdot, \cdot \rangle_0)$. Equivalently, K belongs to $O(d_0, \langle \cdot, \cdot \rangle_0)$ for the inner product on \mathfrak{g}^0 conjugate to the standard one. This inner product then induces a Carnot–Carathéodory metric for which $\text{Aut}_g(\mathfrak{g})$ are homotheties. \square

Asymmetric Carnot nilpotent groups may at first appear to be somewhat special. However, there are many examples and these algebras are generic in many situations.

Examples 2.8. The following classes of graded nilpotent Lie groups G are asymmetric.

- (1) [Pan89, Proposition 13.1] G belongs to a certain Zariski open dense subset of all 2-step groups with grading $\mathfrak{g} = \mathfrak{g}^0 \oplus \mathfrak{g}^1$ where $\dim \mathfrak{g}^0 \geq 10$ and is even and $3 \leq \dim \mathfrak{g}^1 \leq 2 \dim \mathfrak{g}^0 - 4$,
- (2) [Pan89, Proposition 10.1] G is the (2-step) maximal unipotent subgroup of the isometry group of $\mathbb{H}_{\mathbb{H}}^n$ or $\mathbb{H}_{\mathbb{O}}^2$ for any $n \geq 2$,
- (3) [Pan89, §13] G has an exceptional $(r+1)$ -step *filiform* algebra ($r \geq 3$) of even dimension $r+3$ given by $\mathfrak{g} = \bigoplus_{i=0}^{r+1} \mathfrak{g}^i$ with $\mathfrak{g}^0 = \text{span}\{y_0, z_0\}$ and $\mathfrak{g}^i = \text{span}\{y_i\}$ for $1 \leq i \leq r+1$ with bracket relations $[z_0, y_i] = y_{i+1}$ and $[y_i, y_{r-i}] = (-1)^i y_{r+1}$ for $0 \leq i \leq r$ and all other brackets 0. (The filiform algebras are the graded algebras with minimal possible dimensions of each grading stratum; there are two in each even dimension and one in each odd dimension [Ver70]. However the non-exceptional ones admit non-trivial unipotent graded automorphisms.)

(4) [LDOW14, Theorem 1.2] any G with $\text{Aut}(G) = \mathcal{D}$. Such groups are called *ultrarigid* nilpotent groups. There are examples of these in at least dimensions 16 and 17 [LDOW14, Examples 3.4 and 3.5].

We do not know if asymmetry is always a generic property of Carnot nilpotent groups with respect to the Zariski topology in sufficiently high dimensions. It is an open condition in the Hausdorff topology (see Corollary 2.10).

We observe that the underlying space of all Lie algebras $\mathfrak{g} \in \mathcal{NL}_n$ is \mathbb{R}^n . In particular, we have $\text{Aut}_{\mathfrak{g}} < \text{GL}(\mathfrak{g}) = \text{GL}(n, \mathbb{R})$. We will thus use the topology of pointed Hausdorff convergence on (closed) subgroups of $\text{GL}(n, \mathbb{R})$ which by abuse of notation we call the ‘Hausdorff topology’. In this topology, a sequence of groups G_i converges to G if the Hausdorff distance $d_H(G_i \cap B(1, r), G \cap B(1, r))$ tends to 0 as $i \rightarrow \infty$ for each $r > 0$, where $B(1, r)$ is the ball of radius r around the identity in $\text{GL}(n, \mathbb{R})$ with respect to the operator norm.

We now show that automorphism groups vary semicontinuously in this topology for nilpotent G .

PROPOSITION 2.9. *Let (G_k) be a sequence of connected n -dimensional graded nilpotent Lie groups whose Lie algebras converge to the Lie algebra \mathfrak{g} of G in \mathcal{NL}_n . Then the corresponding graded automorphism groups $\text{Aut}_{\mathfrak{g}}(\mathfrak{g}_k)$ converge to a Lie subgroup of $\text{Aut}_{\mathfrak{g}}(\mathfrak{g}) < \text{GL}(\mathfrak{g})$ with respect to the topology of pointwise convergence.*

Proof. By continuity of the defining polynomial relations satisfied by the matrices in $\text{Aut}_{\mathfrak{g}}(\mathfrak{g}_k)$, any element of the limit will satisfy the polynomial relations required to be in $\text{Aut}_{\mathfrak{g}}(\mathfrak{g})$. Let $H \subset \text{Aut}_{\mathfrak{g}}(\mathfrak{g})$ be the collection of limit points. By definition this is a closed subset of $\text{Aut}_{\mathfrak{g}}(\mathfrak{g})$. Considered as equivalence classes of convergent sequences, it is elementary to verify that the product structure given by $[\{a_n\}] * [\{b_n\}] = [\{a_n b_n\}]$ is well defined and gives H a group structure compatible with that of $\text{Aut}_{\mathfrak{g}}(\mathfrak{g})$. Hence H is a Lie subgroup of $\text{Aut}_{\mathfrak{g}}(\mathfrak{g})$. \square

As a corollary, we deduce that the property of being asymmetric is stable in the variety of nilpotent Lie groups/algebras.

COROLLARY 2.10. *Let G be a connected and simply connected Carnot Lie group of dimension n . If G is asymmetric then there is a neighborhood \mathcal{U} of G in the variety of n -dimensional Carnot Lie groups such that \mathcal{U} consists of asymmetric groups.*

Proof. Let (\mathfrak{g}^k) be a sequence of Carnot Lie algebras converging to \mathfrak{g} in \mathcal{NL}_n . Write $\text{Aut}_{\mathfrak{g}}(\mathfrak{g}) = LD$ where $L = \text{Aut}_{\mathfrak{g}}(\mathfrak{g}) \cap \text{SL}_{\pm}(d_0, \mathbb{R})$ lies in some compact group K . Without loss of generality, we may assume after a conjugation that $L < K = \text{O}(d_0, \mathbb{R})$. Similarly, let $\text{Aut}_{\mathfrak{g}}(\mathfrak{g}^k) = L_k D$ for $L_k = \text{Aut}_{\mathfrak{g}^k}(\mathfrak{g}^k) \cap \text{SL}_{\pm}(d_0, \mathbb{R})$.

By Proposition 2.9, the L_k converge to a subgroup of L . We wish to show that L_k belongs to a compact subgroup. We will first consider L_k^0 , the connected component of the identity of L_k . We fix a norm on \mathbb{R}^n . If the L_k^0 are not contained in a compact group, then the operator norm, $\|\cdot\|_{\text{op}}$ is unbounded on L_k^0 . Then L_k^0 admits a path whose elements have norms taking on all values in $[1, \infty)$, and in particular there is an element a_k with

$\|a_k\|_{\text{op}} = 2$. The sequence $\{a_k\}$ admits a convergent subsequence to an element of determinant ± 1 , but which does not have norm one, leading to a contradiction.

By Proposition 2.5, $\text{Aut}_g(\mathfrak{g}^k)$ and thus L_k are algebraic groups. An algebraic group has only finitely many connected components by [Whi57, Theorem 3]. Therefore L_k must lie in a compact subgroup. \square

3. Tangent cones of sub-Riemannian manifolds

In this section we analyze the structure of tangent cones and relate the derivatives of smooth maps preserving the horizontal distribution to the Carnot derivatives. Under suitable assumptions, this leads to resonances and even arithmeticity of the Lyapunov spectrum.

Throughout this section we will be exploiting the properties of sub-Riemannian manifolds equipped with the generic and horizontal distribution as defined in §1.1. Toward this end, we first recall the notion of a tangent cone.

Definition 3.1. Let (X, d) be a metric space and $x \in X$. We call any pointed Gromov–Hausdorff limit of (X, p, td) when $t \rightarrow \infty$ a *tangent cone* of X at p .

In general, tangent cones of metric spaces at a point may not exist, and when they do, they may not be unique. However, in the setting of sub-Riemannian manifolds, Mitchell [Mit85] showed that they exist, and Margulis and Mostow [MM00] proved that they are unique.

THEOREM 3.2. ([Mit85, Theorem 1], [MM00]) *Let (N, d_C) be a sub-Riemannian manifold. Suppose that the metric d_C comes from a smooth horizontal distribution E . If the distribution E is generic in a neighborhood of $p \in N$ then the tangent cone of N at p exists, is unique and is a Carnot nilpotent Lie group with a right-invariant Carnot–Carathéodory metric induced from the distribution of homogeneous degree-one vector fields tangent to E with the inner product inherited from E .*

The very last statement of the above theorem is not stated explicitly in the cited references, but follows from the construction as will be explained in §3.1. There we will also define the notion of homogeneous vector fields.

We next discuss the construction and structure of this nilpotent group and its relationship to the tangent cone at each point $p \in N$ (cf. [Mit85, §3]). We will need these details for our application to sub-Riemannian dynamics in §4.

3.1. Carnot metrics and the Métivier correspondence. Métivier developed a correspondence between iterated brackets of horizontal vector fields in a neighborhood of a given point $p \in N$ and certain homogeneous vector fields possessing nilpotent bracket relations. We present here a compressed summary of the details.

Let X_i , $i = 1, \dots, d_0 = \dim E$, be smooth vector fields on N that are tangent to and form a basis for the horizontal distribution in a neighborhood U of a point $p \in N$. After possibly shrinking the neighborhood U , among the commutators of the X_i we may choose an ordered subset Y_1, \dots, Y_n that form a basis of $T_p N$ at each point $y \in U$

and such that $Y_1 = X_1, \dots, Y_{d_0} = X_{d_0}$, and together with the next ordered subcollection $(Y_{d_0+1}, \dots, Y_{d_0+d_1})$ form a basis for the first commutator subbundle $E^1(y)$, and so on. We call such a moving frame a *graded basis*. We sometimes index this basis according to the level as $(Y_{0,1}, \dots, Y_{r,d_r})$.

For any smooth vector field X on N , let $s \mapsto \exp sX$ be the one-parameter subgroup of diffeomorphisms acting on N induced by the flow of X , that is, along integral curves of X . For each y in the neighborhood U of p the map $y = \exp(\sum_i y_i Y_i)(p) \mapsto (y_i) \in \mathbb{R}^n$ is a diffeomorphism from U to some neighborhood of 0 in \mathbb{R}^n . We call the collection of components y_i *normal coordinates* on U . We emphasize that normal coordinates do not define (commuting) coordinates in the ordinary sense since the distribution is not integrable.

For a generic horizontal distribution E , we define the *partition floor function* to be $[i]_E := k + 1$ if $\dim E^{k-1}(x) < i \leq \dim E^k(x)$ for $k = 0, \dots, r$ and where we adopt the convention that $\dim E^{-1} = 0$. When the distribution E is understood we simply write $[i]$ instead of $[i]_E$. We define a dilatation $\delta_s : U \rightarrow N$ for $s \in [0, \infty)$ in terms of normal coordinates by taking $\delta_s(y_i) = s^{[i]} y_i$. The δ_s are local diffeomorphisms for $s > 0$.

For a vector field of the form $X = y_{i_1}^{\alpha_1} \cdots y_{i_k}^{\alpha_k} Y_j$, written in terms of the fields Y_j and their associated normal coordinate functions y_j , we define the *degree* of X to be $[j] - \sum_{m=1}^k \alpha_m [i_m]$. By taking the maximum degree over monomial terms we can extend the notion of degree to vector fields of the form $X = \sum_i p_i(y_1, \dots, y_n) Y_i$ for polynomials p_i . Finally, we can extend this notion to arbitrary smooth vector fields in a neighborhood of p by considering the degree of vanishing at p (see [MM00, §3] for details). A vector field is *homogeneous* of degree i if each of its component terms has degree exactly i . We can decompose each vector field X into its homogeneous components. If X has degree at most q and $X^{(q)}$ denotes the homogeneous degree- q part of X at p , and similarly Y has degree at most s at p and $Y^{(s)}$ is its homogeneous degree- s part, then by [MM00, §3] the bracket $[X, Y]$ has degree at most $q + s$ at p and, moreover,

$$[X, Y]^{(q+s)} = [X^{(q)}, Y^{(s)}]. \quad (3.1)$$

For each horizontal vector field X on a neighborhood of p , we obtain a homogeneous degree-one vector field $\widehat{X}_p = \lim_{t \rightarrow \infty} t^{-1}(\delta_t)_*(X)$ on N (see [Mét76, equation (3.2), p. 487]). The vector field \widehat{X}_p is precisely the homogeneous degree-one part at p of the horizontal vector field X . Moreover, the following lemma shows that if X_1 and X_2 are two horizontal fields with $X_1(p) = X_2(p)$, then $\widehat{X}_{1;p} = \widehat{X}_{2;p}$.

LEMMA 3.3. *If X_1, \dots, X_k is a basis of horizontal vector fields in a neighborhood of $p \in N$ for a sub-Riemannian manifold N , and $X = \sum_{i=1}^{d_0} a_i X_i$ is any horizontal vector field on N , then $\widehat{X}_p = \sum_{i=1}^{d_0} a_i(p) \widehat{X}_{i;p}$.*

Proof. Since X is horizontal it has degree at most one, and we can write it in the basis as $X(y) = \sum_i a_i(y) X_i$ for functions a_i on the neighborhood U of p . Express this as $X(y) = \sum_i a_i(p) X_i + \sum_i (a_i(y) - a_i(p)) X_i$. Since the functions $a_i(y) - a_i(p)$ vanish at p , they have degree at most -1 at p and the X_i have degree 1. Hence $\sum_i (a_i(y) - a_i(p)) X_i$ has degree at most 0 and $\widehat{X}_p = \sum_i a_i(p) \widehat{X}_{i;p}$. \square

Métivier [Mét76, Théorème 3.1] showed that the homogeneous vector fields $\widehat{X}_{i;p}$ generate a nilpotent Lie algebra through taking commutators, and Mitchell [Mit85, Lemmas 3.1 and 3.2] showed that the corresponding simply connected nilpotent group with its corresponding Carnot–Carathéodory metric is isometric and isomorphic to the tangent cone at p . By Lemma 3.3, for any horizontal field X we have that \widehat{X}_p is in the span of $\widehat{X}_{i;p}$.

The homogeneous degree-one part \widehat{X}_p of a horizontal field X thus corresponds to a right invariant field \overline{X} on $TC_p N$. In other words, \overline{X} belongs to the Lie algebra of $TC_p N$, which we denote by $\mathfrak{n}_p = \text{Lie}(TC_p N)$. Let $\mathfrak{n}_p^0 \subset \mathfrak{n}_p$ be the subspace spanned by the set of all \overline{X} , and inductively set $\mathfrak{n}_p^i = [\mathfrak{n}_p^0, \mathfrak{n}_p^{i-1}] \subset \mathfrak{n}_p$ for $i \in \{1, \dots, r\}$. The degree of homogeneity of the vector fields provides a natural grading for the Lie algebra \mathfrak{n}_p as pointed out in [MM95, §8.2] and [MM00, §4], furnishing \mathfrak{n}_p with a Carnot nilpotent structure.

Among the k -fold commutators of $\widehat{X}_{i;p}$ we may choose a set of vector fields $\widehat{X}_{k,j;p}$ whose corresponding right invariant fields $\overline{X}_{k,j}$ form a basis of the k th commutator space $\mathfrak{n}_p^k \subset \mathfrak{n}_p$ of \mathfrak{n}_p^0 respecting the grading. In particular, we may choose indices so that $\widehat{X}_{0,j;p} = \widehat{X}_{j;p}$. This provides an isomorphism of Lie algebras, $\mathcal{M}_p : \text{span}\{\widehat{X}_{0,1;p}, \dots, \widehat{X}_{r,d_r;p}\} \rightarrow \mathfrak{n}_p$, where the domain is a Lie algebra of vector fields under the ordinary bracket. We name this identification between linear combinations of the $\{\widehat{X}_{k,j;p}\}$ and elements of \mathfrak{n}_p the *Métivier correspondence* at p . Note that this correspondence depends on the choice of graded basis. By Lemma 3.3, the Métivier correspondence induces a linear inclusion $\iota : E(p) \rightarrow \mathfrak{n}_p$ with image \mathfrak{n}_p^0 by $X(p) \mapsto \overline{X} = \mathcal{M}_p(\widehat{X}_p)$. We will omit the p subscript on vector fields when the base point of the tangent cone is understood.

Following [MM00], define an equivalence class on curves of M by $\alpha \sim \beta$ if and only if

$$\lim_{s \rightarrow 0} \frac{1}{s} d_C(\alpha(s), \beta(s)) = 0.$$

The tangent cone $TC_p N$ can be considered as the space of equivalence classes of curves $[\alpha]$ with $\alpha(0) = p$ which are equivalent to a dilatation orbit curve at p , $[\delta_s y]$ for some $y \in N$, with the distance

$$d([\alpha], [\beta]) = \lim_{s \rightarrow 0} s^{-1} d_C(\alpha(s), \beta(s)). \quad (3.2)$$

The above interpretation generalizes a standard interpretation of the tangent space to a differentiable manifold as the space of equivalence classes of differentiable curves. \square

In the next proposition we will consider the subspace topology on $\mathcal{NL}_n \subset \text{Hom}(\Lambda^2 \mathbb{R}^n, \mathbb{R}^n)$ instead of the coarser Zariski topology of the variety.

PROPOSITION 3.4. *Let (N, d_C) be a smooth sub-Riemannian manifold. Suppose that the metric d_C comes from a generic smooth horizontal distribution E . Then the metrics, nilpotent structures, and the corresponding isomorphism classes, of the tangent cones of N vary continuously on N .*

Proof. We need only show that the isomorphism class of the tangent cones vary continuously locally. By Theorem 3.2, the nilpotent structures depend only on the horizontal

distribution, not the choice of basis above used to construct the structure. Hence we may choose the initial basis freely. We now refer back to the notation at the beginning of §3.1.

For a neighborhood U of a point $p \in N$, by the genericity assumption, we may choose the basis of fields X_i for $i = 1, \dots, d_0$ so that the commutators of X_i in E^k do not degenerate to E^{k-1} at any point of U if they do not do so at the point p . In particular, the same indices can be used to choose the same fields Y_i , for $i = 1, \dots, n$ at each point $x \in U$. Therefore, the construction of all the $\widehat{X}_{k,j;x}$ varies smoothly in a neighborhood of p . This implies that the structure constants of the Lie algebras of the tangent cones vary smoothly on U and hence this implies that the nilpotent structure varies continuously on the space of nilpotent structures described in §2.2. This continuity thus passes to the orbit quotient space of nilpotent isomorphism classes as well.

Lastly, since the metric on $TC_x N$ is a Carnot–Carathéodory metric for the distributions induced by the inclusion of $E(x)$ in \mathfrak{n}_x , the metric also varies continuously on U , and thus on all of N . \square

Remark 3.5. Observe that continuity in the subspace topology on \mathcal{NL}_n equipped with metrics coming from the inner product on E as it varies in an open set implies continuity in the pointed Gromov–Hausdorff topology as it implies convergence on metric nets.

By Theorem 3.2, the metric on $TC_p N$ is a Carnot–Carathéodory metric for the right invariant distribution induced from $\mathfrak{n}_p^0 \subset \mathfrak{n}_p$. Next, we identify the norm on the distribution that gives rise to the metric.

LEMMA 3.6. *The Carnot–Carathéodory metric on $TC_p N$ is induced by the right invariant distribution corresponding to $\mathfrak{n}_p^0 \subset \mathfrak{n}_p$ equipped with the Riemannian inner product coming from $E(p)$ under the above identification.*

We will denote the norm on $E(p)$ by $\|\cdot\|_p$ and that on \mathfrak{n}_p^0 by $\|\cdot\|_{\mathfrak{n}_p^0}$.

Proof. Given a unit-speed sub-Riemannian geodesic segment γ starting at p , let X be its tangent field extended to a smooth horizontal field on the neighborhood U of p . By [MM00, Proposition 5.6], the Carnot–Carathéodory metric induced on $TC_p N$ does not depend on the choice of basis vector fields (satisfying certain assumptions). Using X as a coordinate field, we obtain

$$d_C(p, \delta_s \exp(X)(p)) = d_C(p, \exp(sX)(p)) = d_C(p, \gamma(s)) = s.$$

This implies in $TC_p N$ that $d([p], [\delta_s \exp(X)(p)]) = 1$ by (3.2). Since the identity element in $TC_p N$ is the class $[p]$ of the constant curve, and $\widehat{X} = X$ along its integral curve, $[\delta_s \exp(tX)(p)] = e^{t\widehat{X}}$ and therefore $d(1, e^{t\widehat{X}}) = t$. The induced norm on the first level \mathfrak{n}_p^0 of the Lie algebra then gives $\|\widehat{X}\|_{\mathfrak{n}_p^0} = 1$.

Thus the identification preserves the norm of vectors. Since inner products are uniquely determined by their norms, the inner products are preserved as well. \square

3.2. Carnot derivatives of maps preserving horizontal distributions. Next we recall the notion of the Carnot derivative which will be crucial to our purposes. This object was

first introduced by Pansu in the setting of nilpotent Lie groups in [Pan89] based on earlier work of Mostow on quasiconformal maps of boundaries of rank-one symmetric spaces [Mos73]. We will need the following version due to Margulis and Mostow in the setting of sub-Riemannian manifolds.

Definition 3.7. [MM95, Definition 10.3.1] Let (N, d_C) and (N', d'_C) be sub-Riemannian manifolds, and let $f : (N, d_C) \rightarrow (N', d'_C)$ be a map. For every $p \in N$, we denote by $f_t : (N, p, t d_C) \rightarrow (N', f(p), t d'_C)$ the induced map for every $t > 0$. The function f is called *Carnot differentiable* at p if the sequence f_t converges uniformly as $t \rightarrow \infty$ on compact sets to a map between tangent cones at p and at $f(p)$. And we call f *Carnot differentiable* if it is Carnot differentiable at every point.

In the next few propositions we explore the relationship between the Carnot derivative and the ordinary derivative.

PROPOSITION 3.8. *Let $f : (N, d_C) \rightarrow (N', d'_C)$ be a C^1 local diffeomorphism between sub-Riemannian manifolds generated by generic horizontal distributions E and E' . If f preserves the distributions, that is, $Df(E) = E'$, then f is Carnot differentiable everywhere. Moreover, the Carnot derivative f_* is an isomorphism between the corresponding tangent cones.*

Proof. Since the statement is local, it is enough to consider any sufficiently small precompact neighborhood U of an arbitrary point $p \in N$ where f is a diffeomorphism and we use $f|_U$ instead of f . We assume U is chosen such that there exist smooth horizontal vector fields X_1, \dots, X_{d_0} on U which form a basis for $E(x)$ at each $x \in U$. We let $X'_i = Df(X_i)$ for each $i = 1, \dots, d_0$. By hypothesis, $\{X'_1, \dots, X'_{d_0}\}$ forms a basis of $E'(y)$ at each $y \in U'$. As above, these vector fields give us normal coordinates and we use them to define our respective dilatations δ_s on U and δ'_s on $U' = f(U)$.

We note that $f : U \rightarrow U'$ is a quasi-conformal diffeomorphism since f has uniformly bounded derivatives on the compact set \overline{U} . By [MM95, Theorem 10.5] and its proof, f induces an isomorphism of tangent cones at each point x belonging to a certain full measure set $U^0 \cap f^{-1}(\Omega_{X'_1} \cap \dots \cap \Omega_{X'_{d_0}})$ to be defined shortly. (Note that the f^{-1} was inadvertently left off of the $\Omega_{X'_i}$ in the proof of [MM95].) We will show that both U^0 and $f^{-1}(\Omega_{X'_i})$ for any $i = 1, \dots, d_0$ are all of U in our case.

The definition of U^0 given in [MM95, §10.1] simplifies in our situation. It consists of the density points for the Hausdorff measure of d_C (cf. [MM95, Definition 2.1.4]) for the set A where the Lipschitz constant of f is uniformly bounded. However, since f is C^1 with uniformly bounded derivatives, $A = U$. Moreover, every point $x \in U$ is a density point since U is open.

We now recall the definition of the $\Omega_{X'_i}$ from [MM95]. For $i = 1, \dots, d_0$, the right invariant vector fields $\overline{X}'_i \in \mathfrak{n}_y$ on $TC_y U'$ correspond to the homogeneous degree-one fields $\widehat{X}'_{i;y}$, namely $\overline{X}'_i = \mathcal{M}_y(\widehat{X}'_{i;y})$. Recall that the X'_i were used to define the normal coordinates and the dilatation δ'_s . Hence, along the integral curve of X'_i through y , we have $1/t(\delta'_t)_* X'_i = X'_i$, and hence $\widehat{X}'_{i;y} = \lim_{t \rightarrow \infty} 1/t(\delta'_t)_* X'_i = X'_i$ along the same curve. Let

$e^{s\bar{X}'_i}$ denote the one-parameter subgroup in $TC_y U'$ of the right invariant field \bar{X}'_i , viewed as an element of the Lie algebra \mathfrak{n}_y . Furthermore, following [MM95, §8.6], let ϵ_y denote the homeomorphism of a neighborhood of $1 \in TC_y U'$ to U' which takes the equivalence class of the path $\{\delta'_s z\}_{s \in [0,1]}$ in $TC_y U'$ to the point $z \in U'$. (The equivalence classes of the germs as $s \rightarrow 0$ of the paths $\delta'_s z$ correspond to points in the tangent cone by [Mit85, Lemmas 3.1 and 3.2].)

As in [MM95], for $i = 1, \dots, d_0$ let $A_{X'_i}$ be the set consisting of all points $y \in U'$ such that $s^{-1}d'_C((\exp s X'_i)(y), \epsilon_y(e^{s\bar{X}'_i}))$ tends to 0 uniformly as $s \rightarrow 0$. Finally, the set $\Omega_{X'_i}$ consists of all the density points in $A_{X'_i}$ for the Hausdorff measure of d'_C .

Finally, observe that since $\widehat{X}'_{i;y} = X'_i$ along its integral curve through y , we have

$$\delta'_t \exp(s X'_i)(y) = \delta'_t \exp(s \widehat{X}'_{i;y})(y).$$

The latter curve in s converges in the pointwise Gromov–Hausdorff sense through the metric spaces $(U', y, (d'/t))$ to the curve $e^{s\bar{X}'_i} \in TC_y N'$ as $t \rightarrow 0$. In other words, the curve $\epsilon_y(e^{s\bar{X}'_i})$ coincides with the curve $\exp(s X'_i)(y)$ for every $y \in U'$. In particular, $A_{X'_i} = U'$ and therefore $\Omega_{X'_i} = U'$ since every point of U' is a density point for the Hausdorff measure. \square

Diffeomorphisms preserving the horizontal distribution E share certain properties with their corresponding automorphisms. To investigate this relationship we will need to make certain correspondences more explicit.

Definition 3.9. Let $f : N \rightarrow N'$ be a diffeomorphism of sub-Riemannian manifolds sending the horizontal distribution E to the horizontal distribution E' . Assume that E is generic at a point $p \in N$. For a graded basis Y_1, \dots, Y_n of coordinate vector fields on N around p (respectively, Y'_1, \dots, Y'_n around $f(p)$) with $X_1 = Y_1, \dots, X_{d_0} = Y_{d_0}$ horizontal, let $\mathcal{M}_p : \text{span}\{\widehat{X}_{0,1}, \dots, \widehat{X}_{r,d_r}\} \rightarrow \mathfrak{n}_p$ be the induced Métivier correspondence. We then define

$$\widehat{f}_* : \text{span}\{\widehat{X}_{0,1}, \dots, \widehat{X}_{r,d_r}\} \rightarrow \text{span}\{\widehat{X}'_{0,1}, \dots, \widehat{X}'_{r,d_r}\}$$

by setting $\widehat{f}_*(Z) = \mathcal{M}_{f(p)}^{-1} \circ df_* \circ \mathcal{M}_p(Z)$ where $df_* : \mathfrak{n}_p \rightarrow \mathfrak{n}'_{f(p)}$ is the Lie derivative of the isomorphism $f_* : TC_p N \rightarrow TC_{f(p)} N'$.

LEMMA 3.10. *Let $f : N \rightarrow N'$ be a local C^∞ diffeomorphism of sub-Riemannian manifolds N and N' sending the horizontal distribution E of N to the horizontal distribution E' of N' . Assume that E is generic at a point $p \in N$, and let $f_* : TC_p N \rightarrow TC_{f(p)} N'$ be the induced isomorphism. For any horizontal vector field X we have*

$$\widehat{f}_* \widehat{X} = \widehat{Df(X)}.$$

Moreover, if $(X_{0,1}, \dots, X_{r,d_r})$ is a graded basis around p then $\widehat{f}_[\widehat{X}_{i,k}, \widehat{X}_{j,l}] = [\widehat{f}_* \widehat{X}_{i,k}, \widehat{f}_* \widehat{X}_{j,l}]$.*

Proof. By Proposition 3.8 the limit of the maps f_t given in Definition 3.7 exists and is $f_* : TC_p N \rightarrow TC_{f(p)} N'$.

The push-forward under f of a horizontal vector field X is also horizontal and therefore converges under metric rescaling to a right invariant horizontal field $\widehat{Df}(X)$ by [MM95, Proposition 8.10]. As shown in the proof of [MM95, Theorem 10.5], the image under f_* of the one-parameter subgroup $e^{s\widehat{X}}$ is the one-parameter subgroup of this limit push-forward field. In other words, for all $g \in TC_p N$ and $s \in \mathbb{R}$, we have

$$f_*(e^{s\widehat{X}} g) = e^{s\widehat{Df}(X)} f_*(g).$$

Taking Lie derivatives, we have $df_*(\widehat{X}) = \widehat{Df}(X)$ and therefore under the Métivier correspondence we have $\widehat{f}_*\widehat{X} = \widehat{Df}(X)$ as claimed.

The second statement follows directly from the Métivier correspondence and (3.1) and the fact that $df_*[\widehat{X}_{i,k}, \widehat{X}_{j,l}] = [df_*\widehat{X}_{i,k}, df_*\widehat{X}_{j,l}]$. \square

By Lemma 3.6 the inclusion $\iota : E(p) \hookrightarrow \mathfrak{n}_p$ defined earlier is an isometry onto its image \mathfrak{n}_p^0 with respect to the Riemannian norm and the norm inducing the Carnot–Carathéodory metric. The following corollary gives further relationships between some of the objects defined thus far.

COROLLARY 3.11. *In the setting of Proposition 3.8, the following diagram commutes:*

$$\begin{array}{ccc} E(p) & \xrightarrow{D_p f} & E'(f(p)) \\ \downarrow \iota & & \downarrow \iota' \\ \mathfrak{n}_p & \xrightarrow{d(f_*)} & \mathfrak{n}'_{f(p)} \\ \downarrow \exp & & \downarrow \exp \\ TC_p N & \xrightarrow{f_*} & TC_{f(p)} N' \end{array}$$

where **exp** is the Lie exponential map $\exp(X) = e^X$. Moreover, for all $\xi \in E(p)$, we have $\|D_p f(\xi)\|_{f(p)} = \|df_*(\iota \xi)\|_{\mathfrak{n}_p^0}$.

Proof. The lower part of the diagram commutes as a standard consequence of Lie theory.

By Lemma 3.10, we have $\widehat{f}_*\widehat{X} = \widehat{Df}(X)$. Since $X(p) = \widehat{X}_p(p) \in E(p)$ for a horizontal field X , we have

$$\begin{aligned} df_*(\iota(X(p))) &= df_*(\widehat{X}) = df_*\mathcal{M}_p(\widehat{X}) = \mathcal{M}_{f(p)}\widehat{f}_*\widehat{X} = \mathcal{M}_{f(p)}\widehat{Df}(X) \\ &= \widehat{Df}(X) = \iota'(D_p f(X(p))), \end{aligned}$$

where the third equality is by the definition of \widehat{f}_* . This establishes commutativity of the upper diagram.

The final statement follows from the commutativity of the diagram and the fact that the inclusions are isometric. \square

The following relationship between the differential of a local C^∞ diffeomorphism at a fixed point and its induced automorphism will prove to be crucial. A priori there is no clear connection between the Carnot derivative and the ordinary derivative of a

smooth sub-Riemannian map. However, we are able to establish such a connection in some important special cases.

PROPOSITION 3.12. *Let $f : N \rightarrow N$ be a local C^∞ diffeomorphism of a sub-Riemannian manifold N preserving the horizontal distribution E . Assume that E is generic at a point $p \in N$ where $f(p) = p$, and let $f_* : TC_p N \rightarrow TC_p N$ be the induced automorphism. If $df_{*|_{\mathfrak{n}^0}}$ is diagonalizable with real eigenvalues $(\lambda_1, \dots, \lambda_{d_0})$, then there exists a basis of $T_p N$ such that $D_p f : T_p N \rightarrow T_p N$ is upper triangular with diagonal values $(\lambda_1, \dots, \lambda_{d_0}, \lambda_{i_1} \lambda_{i_2}, \dots, \lambda_{i_1} \lambda_{i_2} \lambda_{i_3}, \dots)$.*

Proof. Again let $U \subset N$ be a small neighborhood around the point p and X_1, \dots, X_n be a graded basis where X_1, \dots, X_{d_0} are horizontal vector fields spanning E on U . As above, normal coordinates define a dilatation $\delta_t : U \rightarrow N$. Then if X and Y are horizontal, by Métivier [Mét76], X and Y are vector fields of degree at most 1 at p and $\widehat{X} = \lim_{t \rightarrow \infty} 1/t(\delta_t)_* X$ is the homogeneous degree-one part of X . Note that $[X, Y]$ is a vector field of degree at most 2 and we denote the homogeneous degree-two part by $[X, Y]^{(2)} = \lim_{t \rightarrow \infty} 1/t^2(\delta_t)_*[X, Y]$.

Without loss of generality we may assume that fields X_1, \dots, X_{d_0} in the chosen basis have corresponding right invariant fields \overline{X}_i which diagonalize f_* on the first level of the Lie algebra \mathfrak{n} . Indeed, by assumption, there are $\lambda_i \in \mathbb{R}$ such that $df_* \overline{X}_i = \lambda_i \overline{X}_i$ for $i = 1, \dots, d_0$.

By Corollary 3.11, for $i = 1, \dots, d_0$ we have $\iota D_p f(X_i(p)) = df_*(\iota(X_i(p))) = df_*(\overline{X}_i) = \lambda_i \overline{X}_i$. Taking ι^{-1} , we have $D_p f(X_i(p)) = \lambda_i X_i(p)$.

By Lemma 3.10, if $[X_i, X_j]$ is a graded basis element, then $\widehat{f}_*[\widehat{X}_i, \widehat{X}_j] = [\widehat{f}_* \widehat{X}_i, \widehat{f}_* \widehat{X}_j]$. Therefore we have

$$\begin{aligned} df_* \mathcal{M}_p[\widehat{X}_i, \widehat{X}_j] &= \mathcal{M}_p[\widehat{f}_* \widehat{X}_i, \widehat{f}_* \widehat{X}_j], \\ df_*[\mathcal{M}_p \widehat{X}_i, \mathcal{M}_p \widehat{X}_j] &= \mathcal{M}_p[\widehat{Df} \widehat{X}_i, \widehat{Df} \widehat{X}_j], \\ [df_* \overline{X}_i, df_* \overline{X}_j] &= \mathcal{M}_p[Df X_i, Df X_j]^{(2)}, \\ \lambda_i \lambda_j [\overline{X}_i, \overline{X}_j] &= \mathcal{M}_p[Df X_i, Df X_j]^{(2)}. \end{aligned}$$

It then follows that

$$[Df X_i, Df X_j]^{(2)} = \lambda_i \lambda_j \mathcal{M}_p^{-1}[\overline{X}_i, \overline{X}_j] = \lambda_i \lambda_j [\widehat{X}_i, \widehat{X}_j] = \lambda_i \lambda_j [X_i, X_j]^{(2)}. \quad (3.3)$$

By hypothesis $\{X_1, \dots, X_{d_0}\} \cup \{[X_i, X_j] : 1 \leq i, j \leq d_0\}$ spans E^1 . Since the homogeneity degree of $Df[X_i, X_j] = [Df(X_i), Df(X_j)]$ and $[X_i, X_j]$ at p is at most 2, $Df[X_i, X_j] - \lambda_i \lambda_j [X_i, X_j]$ has homogeneity degree at most 1. Evaluating (3.3) at p , we have $[Df(X_i), Df(X_j)](p) - \lambda_i \lambda_j [X_i, X_j](p) \in E(p) = E^0(p)$.

Continuing by induction, if X_i and X_j are graded basis fields of degree at most q and s respectively such that $[X_i, X_j]$ is a basis field, then a nearly identical computation shows

$$[Df X_i, Df X_j]^{(q+s)} = \sigma_i \sigma_j [X_i, X_j]^{(q+s)},$$

where by the inductive hypothesis $\sigma_i = \lambda_{i_1} \dots \lambda_{i_k}$ and $\sigma_j = \lambda_{j_1} \dots \lambda_{j_\tau}$ for some indices i_1, \dots, i_k and j_1, \dots, j_τ .

This shows that in the $\{X_i(p)\}$ basis, Df is upper triangular. If, restricted to the horizontal distribution, the diagonal values are $\lambda_1, \dots, \lambda_{d_0}$, then other diagonal elements are products of the λ_i as claimed. \square

Now we are equipped to prove Theorem 1.4 in the introduction.

THEOREM 1.4. *Let $f : N \rightarrow N$ be a local C^∞ diffeomorphism of a sub-Riemannian manifold N . Assume that the horizontal distribution is generic at a point $p \in N$ where $f(p) = p$, and that the graded automorphism $f_* : TC_p N \rightarrow TC_p N$ induced from f is a homothety. Then for some $\lambda > 1$, $D_p f|_{E_p^i}$ has Lyapunov exponents $\log \lambda, 2 \log \lambda, \dots, (i+1) \log \lambda$ with corresponding multiplicities $d_0 = \dim \mathfrak{n}^0, \dots, d_i = \dim \mathfrak{n}^i$ for $i = 0, \dots, r$.*

Proof. Let $(X_{0,1}, \dots, X_{r,d_r})$ be a graded basis of N in a neighborhood of p . As before, we let $\mathcal{M}_p : \text{span}\{\widehat{X}_{0,1}, \dots, \widehat{X}_{r,d_r}\} \rightarrow \mathfrak{n}_p$ be the Métivier correspondence. We will show that with respect to the basis $(X_{0,1}(p), \dots, X_{r,d_r}(p))$, the matrix for $D_p f$ is a block upper triangular matrix. Suppose that $f_* = \delta_\lambda h$, where δ_λ is the dilation of scale $\lambda > 0$ and h is an isometry of the Carnot–Carathéodory metric of $TC_p N$ which necessarily lies in a compact subgroup of the graded automorphism group.

By Lemma 3.10, $\widehat{f}_* \widehat{X}_{0,j} = \widehat{Df}(X_{0,j})$. Thus,

$$\widehat{Df}(X_{0,j}) = \mathcal{M}_p d f_* \mathcal{M}_p^{-1} \widehat{X}_{0,j} = \mathcal{M}_p d f_* \overline{X}_{0,j} = \lambda \mathcal{M}_p d h \overline{X}_{0,j} = \lambda \mathcal{M}_p d h \mathcal{M}_p^{-1} \widehat{X}_{0,j}.$$

Letting $\widehat{dh} = \mathcal{M}_p d h \mathcal{M}_p^{-1}$, we can rewrite the above equation as $\widehat{Df}(X_{0,j}) = \lambda \widehat{dh} \widehat{X}_{0,j}$. Since dh is a graded Lie algebra homomorphism, \widehat{dh} is also a graded Lie algebra homomorphism of $\text{span}\{\widehat{X}_{0,1}, \dots, \widehat{X}_{r,d_r}\}$. In particular, \widehat{dh} preserves $\text{span}\{\widehat{X}_{i,1}, \dots, \widehat{X}_{i,d_i}\}$ for every $i = 0, \dots, r$. It follows that $\widehat{dh} \widehat{X}_{0,j} \in \text{span}\{\widehat{X}_{0,1}, \dots, \widehat{X}_{0,d_0}\}$ for every $j = 1, \dots, d_0$. Therefore, $D_p f(\widehat{X}_{0,j}(p)) = \widehat{Df}(X_{0,j})(p) = (\widehat{dh} \widehat{X}_{0,j})(p) \in \text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{0,d_0}(p)\} = E(p)$.

Consider $X_{1,l}$. Suppose that $X_{1,l} = [X_{0,i}, X_{0,j}]$. By Lemma 3.10, $\widehat{f}_* \widehat{X}_{1,l} = \widehat{f}_* [\widehat{X}_{0,i}, \widehat{X}_{0,j}] = [\widehat{f}_* \widehat{X}_{0,i}, \widehat{f}_* \widehat{X}_{0,j}] = [\widehat{Df} \widehat{X}_{0,i}, \widehat{Df} \widehat{X}_{0,j}]$. And thus,

$$(Df[X_{0,i}, X_{0,j}])^{(2)} = [Df X_{0,i}, Df X_{0,j}]^{(2)} = [\widehat{Df} \widehat{X}_{0,i}, \widehat{Df} \widehat{X}_{0,j}] = \lambda^2 \widehat{dh} \widehat{X}_{1,l}. \quad (3.4)$$

Set $V^{(i)}(p) = \text{span}\{X_{i,1}(p), \dots, X_{i,d_i}(p)\}$ so that $E^i(p) = V^{(0)}(p) \oplus \dots \oplus V^{(i)}(p)$. We note that $\widehat{dh} \widehat{X}_{0,l} \in \text{span}\{\widehat{X}_{0,1}, \dots, \widehat{X}_{0,d_0}\}$ since \widehat{dh} is a graded Lie algebra homomorphism. We observe that for every $l = 1, \dots, d_1$, we have $\widehat{X}_{1,l}(p) \in \text{span}\{X_{1,l}(p), X_{0,1}(p), \dots, X_{0,d_0}(p)\}$. It follows that $(Df[X_{0,i}, X_{0,j}])^{(2)}(p) \in \text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{0,d_0}(p), \widehat{X}_{1,1}(p), \dots, \widehat{X}_{1,d_1}(p)\} = E^1(p)$. On the other hand,

$$(Df[X_{0,i}, X_{0,j}])(p) = (Df[X_{0,i}, X_{0,j}])^{(2)}(p) + (Df[X_{0,i}, X_{0,j}])^{(\leq 1)}(p),$$

where $(Df[X_{0,i}, X_{0,j}])^{(\leq 1)}$ is the homogeneous part of $(Df[X_{0,i}, X_{0,j}])$ of degree at most 1. Evaluating a vector field of degree at most 1 at p , we get a vector in $E(p) = \text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{0,d_0}(p)\}$. Therefore, $(Df[X_{0,i}, X_{0,j}])(p) \in \text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{0,d_0}(p), \widehat{X}_{1,1}(p), \dots, \widehat{X}_{1,d_1}(p)\} = E^1(p)$.

Inductively, for $X_{m+1,l} = [X_{m,i}, X_{0,j}]$, we obtain

$$\begin{aligned} (Df[X_{m,i}, X_{0,j}])^{(m+2)} &= [DfX_{m,i}, DfX_{0,j}]^{(m+2)} \\ &= [(DfX_{m,i})^{(m+1)}, \widehat{DfX}_{0,j}] = \lambda^{m+2} \widehat{dh} \widehat{X}_{m+1,l}. \end{aligned} \quad (3.5)$$

And it follows that

$$(D_p f)((X_{m+1,l})(p)) = \lambda^{m+2} (\widehat{dh} \widehat{X}_{m+1,l})(p) + (DfX_{m+1,l})^{(\leq m+1)}(p) \in E^{m+1}(p), \quad (3.6)$$

where the notation $Y^{(\leq m+1)}$ indicates the sum of the homogeneous parts of any vector field Y of degree at most $m+1$.

Therefore, with respect to the basis $(X_{0,1}(p), \dots, X_{r,d_r}(p))$, $D_p f$ is a block upper triangular matrix. We let A_i be the blocks on the diagonal of $D_p f$ corresponding to the basis elements $\{X_{i,1}(p), \dots, X_{i,d_i}(p)\}$, for every $i = 0, \dots, r$. We note that the size of A_i is $\dim(\mathfrak{n}_p^i) \times \dim(\mathfrak{n}_p^i)$. Since $(DfX_{m+1,l})^{(\leq m+1)}(p) \in E^m(p)$, equation (3.6) implies that

$$\text{proj}_{V^{(m+1)}(p)}(D_p f)((X_{m+1,l})(p)) = \text{proj}_{V^{(m+1)}(p)}(\lambda^{m+2} (\widehat{dh} \widehat{X}_{m+1,l})(p)),$$

where $\text{proj}_{V^{(m+1)}(p)}$ is the projection of $T_p N$ onto $V^{(m+1)}(p)$ along the subspace $\check{V}^{(m+1)}(p) := V^{(0)}(p) \oplus \dots \oplus V^{(m)}(p) \oplus V^{(m+2)}(p) \oplus \dots \oplus V^{(r)}(p)$. Thus the (j, l) entry of the block matrix A_{m+1} is the $X_{m+1,j}(p)$ component of $\lambda^{m+2} (\widehat{dh} \widehat{X}_{m+1,l})(p)$, for $j, l \in \{1, \dots, d_{m+1}\}$.

Next, we estimate Lyapunov exponents of block matrices A_0, \dots, A_r . Applying equation (3.5) for f^n instead of f , we obtain

$$\begin{aligned} (Df^n[X_{m,i}, X_{0,j}])^{(m+2)} &= [Df^n X_{m,i}, Df^n X_{0,j}]^{(m+2)} \\ &= [(Df^n X_{m,i})^{(m+1)}, \widehat{Df^n X}_{0,j}] = \lambda^{n(m+2)} \widehat{dh}^n \widehat{X}_{m+1,l}. \end{aligned} \quad (3.7)$$

Since

$$(Df^n[X_{m,i}, X_{0,j}])(p) = (Df^n[X_{m,i}, X_{0,j}])^{(m+2)}(p) + (Df^n[X_{m,i}, X_{0,j}])^{(\leq m+1)}(p)$$

and

$$(Df^n[X_{m,i}, X_{0,j}])^{(\leq m+1)}(p) \in E^m(p),$$

the projection of $(Df^n[X_{m,i}, X_{0,j}])^{(m+2)}(p)$ along $\check{V}^{(m+1)}(p)$ onto $V^{(m+1)}(p)$ is the same as the projection of $\lambda^{n(m+2)} \widehat{dh}^n \widehat{X}_{m+1,l}(p)$ to $V^{(m+1)}(p)$ along $\check{V}^{(m+1)}(p)$.

We claim that

$$\text{span}\{\widehat{X}_{m+1,1}(p), \dots, \widehat{X}_{m+1,k_{m+1}}(p)\} \cap \check{V}^{(m+1)}(p) = \{0\}. \quad (3.8)$$

Indeed, we have $\text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{i,d_i}(p)\} = \text{span}\{X_{0,1}(p), \dots, X_{i,d_i}(p)\}$ for all $i = 0, \dots, m+1$. Moreover, these sets of vectors form bases of their corresponding spanned vector spaces. This implies the claim.

This claim implies that for every $w \neq 0$ in $\text{span}\{\widehat{X}_{m+1,1}(p), \dots, \widehat{X}_{m+1,d_{m+1}}(p)\}$, its projection to $V^{(m+1)}(p)$ along $\check{V}^{(m+1)}(p)$ is non-zero. For every $v \neq 0$ in $V^{(m+1)}(p)$,

there are $c_1, \dots, c_{d_{m+1}} \in \mathbb{R}$ not all being zero such that $v = c_1 X_{m+1,1}(p) + \dots + c_{d_{m+1}} X_{m+1,d_{m+1}}(p)$. We then have

$$\begin{aligned} D_p f^n v &= c_1 (Df^n X_{m+1,1})(p) + \dots + c_{d_{m+1}} (D_p f^n X_{m+1,k_{m+1}})(p) \\ &= c_1 (Df^n X_{m+1,1})^{(m+2)}(p) + \dots + c_{d_{m+1}} (D_p f^n X_{m+1,k_{m+1}}^{(m+2)})(p) \\ &\quad + c_1 (Df^n X_{m+1,1}^{(\leq m+1)})(p) + \dots + c_{d_{m+1}} (D_p f^n X_{m+1,k_{m+1}}^{(\leq m+1)})(p) \\ &= \lambda^{n(m+2)} \widehat{dh}^n (c_1 \widehat{X}_{m+1,1}(p) + \dots + c_{d_{m+1}} \widehat{X}_{m+1,d_{m+1}}(p)) \\ &\quad + c_1 (Df^n X_{m+1,1}^{(\leq m+1)})(p) + \dots + c_{d_{m+1}} (D_p f^n X_{m+1,k_{m+1}}^{(\leq m+1)})(p). \end{aligned}$$

By same argument as above, $D_p f^n v$ and $\lambda^{n(m+2)} \widehat{dh}^n (c_1 \widehat{X}_{m+1,1}(p) + \dots + c_{d_{m+1}} \widehat{X}_{m+1,d_{m+1}}(p))$ have the same projection onto $\text{span}\{X_{m+1,1}(p), \dots, X_{m+1,d_{m+1}}(p)\}$ along $\text{span}\{X_{1,1}(p), \dots, X_{m,d_m}(p)\}$. Since $c_1, \dots, c_{d_{m+1}}$ are not all zero, the vector $c_1 \widehat{X}_{m+1,1}(p) + \dots + c_{d_{m+1}} \widehat{X}_{m+1,d_{m+1}}(p)$ is non-zero, and thus has a non-zero projection on $\text{span}\{X_{m+1,1}(p), \dots, X_{m+1,d_{m+1}}(p)\}$ by (3.8).

Since h is in a compact subgroup of $\text{GL}(n, \mathbb{R})$, there is a subsequence (n_k) such that \widehat{dh}^{n_k} converges to the identity. Choose an arbitrary norm $\|\cdot\|$ on $V^{(m+1)}(p)$. Therefore, we may find two constants $C_1, C_2 > 0$ independent of k such that

$$C_1 \|v\| < \|\text{proj}_{V^{(m+1)}(p)}(\widehat{dh}^{n_k}(v))\| < C_2 \|v\|.$$

Hence,

$$C_1 \lambda^{n_k(m+2)} \|v\| < \|\text{proj}_{V^{(m+1)}(p)}(D_p f^{n_k} v)\| < C_2 \lambda^{n_k(m+2)} \|v\|,$$

for every $v \neq 0$ in $V^{(m+1)}(p)$. It follows that A_{m+1} has all Lyapunov exponents equal to $(m+2) \log \lambda$.

Finally, as is well known, the Lyapunov exponents of a block upper triangular matrix are the same as those of the corresponding block diagonal matrix. \square

If f_* fails to be a homothety, we are still able to recover a system of inequalities among the Lyapunov exponents. This is Theorem 1.2 from the introduction.

THEOREM 1.2. *Let $f : N \rightarrow N$ be a local C^∞ diffeomorphism of a sub-Riemannian manifold N . Assume that the horizontal distribution is generic at a point $p \in N$ where $f(p) = p$. Suppose the tangent cone $TC_p N$ is $(r+1)$ -step and set $n_{-1} = 0$ and $n_i = \dim E^i(p)$ for $i \in \{0, \dots, r\}$. If $D_p f|_{E_p^i}$ has Lyapunov exponents $(\log \lambda_1, \log \lambda_2, \dots, \log \lambda_{n_0}, \log \lambda_{n_0+1}, \dots, \log \lambda_{n_1}, \dots, \log \lambda_{n_i})$ listed with multiplicity and with $\log \lambda_{n_{j-1}+1}, \dots, \log \lambda_{n_j}$ in non-decreasing order for each $j \in \{0, \dots, i\}$, then for each $i \in \{0, \dots, r\}$ and $j \in \{n_{i-1}+1, \dots, n_i\}$ we have $(i+1) \log \lambda_1 \leq \log \lambda_j \leq (i+1) \log \lambda_{n_0}$.*

Proof. By switching f with f^{-1} we observe that it is sufficient to prove just the lower bound. Let $\{X_{0,1}, \dots, X_{r,d_r}\}$ be a graded basis of N in a neighborhood of p . We let $\mathcal{M}_p : \text{span}\{\widehat{X}_{0,1}, \dots, \widehat{X}_{r,d_r}\} \rightarrow \mathfrak{n}_p$ be the Métivier correspondence. Note that $n_i = \sum_{j=0}^i d_j$ for $i = 0, \dots, r$.

Our assumptions imply that the induced map f_* exists as a graded automorphism. Its derivative df_* and the corresponding $\widehat{f}_* = \mathcal{M}_{f(p)}^{-1} \circ df_* \circ \mathcal{M}_p$ are graded Lie algebra automorphisms. With respect to the basis $(\widehat{X}_{0,1}, \dots, \widehat{X}_{r,d_r})$, \widehat{f}_* is a block diagonal matrix. We further assume that we have chosen the initial horizontal basis $X_{0,1}, \dots, X_{0,d_0}$ so that \widehat{f}_* is in real Jordan canonical form with respect to $\widehat{X}_{0,1}, \dots, \widehat{X}_{0,d_0}$.

We note that for every $0 \leq j \leq r$, $\text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{j,d_j}(p)\} = \text{span}\{X_{0,1}(p), \dots, X_{j,d_j}(p)\} \subset T_p N$. Since \widehat{f}_* is a block diagonal matrix, $(\widehat{f}_* \widehat{X}_{j,l})(p) \in \text{span}\{\widehat{X}_{j,1}(p), \dots, \widehat{X}_{j,d_j}(p)\}$ for every $1 \leq l \leq d_j$. On the other hand, $(Df X_{j,l} - \widehat{f}_* \widehat{X}_{j,l})(p) \in \text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{j-1,d_{j-1}}(p)\}$ by Lemma 3.10. Here we used the convention that $\text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{j-1,d_{j-1}}(p)\} = \{0\}$ when $j = 0$. By replacing f by f^n , we have that $(Df^n X_{j,l} - \widehat{f}_* \widehat{X}_{j,l})(p) \in \text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{j-1,d_{j-1}}(p)\}$ for every $n \in \mathbb{N}$. In particular, in the $\widehat{X}_{j,l}$ basis, $D_p f$ is block upper triangular and with diagonal blocks coinciding with the matrix of \widehat{f}_* in this basis. Because $\widehat{f}_* \widehat{X}_{j,l}(p) \in \text{span}\{\widehat{X}_{j,1}(p), \dots, \widehat{X}_{j,d_j}(p)\}$ and $\text{span}\{\widehat{X}_{j,1}(p), \dots, \widehat{X}_{j,d_j}(p)\} \cap \text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{j-1,d_{j-1}}(p)\} = \{0\}$, the growth rate of $Df^n X_{j,l}(p) = D_p f(X_{j,l}(p))$ is at least as large as the growth rate of $\widehat{f}_* \widehat{X}_{j,l}(p)$ for all $1 \leq l \leq d_j$. Hence for any $v = \sum_{i=1}^{d_j} a_i X_{j,1}(p)$ the growth rate of $Df^n v$ is at least as large as the growth rate of $\widehat{f}_*(w)$ where $w = \sum_{i=1}^{d_j} a_i \widehat{X}_{j,1}(p)$. By the block upper triangular structure of $D_p f$, it follows that the growth rate of $D_p f^n(v)$ is at least as large as the minimum of the growth rates of \widehat{f}_* restricted to $\text{span}\{\widehat{X}_{j,1}(p), \dots, \widehat{X}_{j,d_j}(p)\}$.

The conclusion now follows from the fact that the growth rate of $\widehat{f}_* \widehat{X}_{j,i}(p)$ is at least $j+1$ times the minimum of growth rates of $\widehat{f}_* \widehat{X}_{0,1}(p), \dots, \widehat{f}_* \widehat{X}_{0,d_0}(p)$ due to the bracket relations. (Recall from the choice of initial basis that \widehat{f}_* achieves its minimal growth rate on one of the vectors $\widehat{X}_{0,1}, \dots, \widehat{X}_{0,d_0}$.) Since $X_{0,1}, \dots, X_{0,d_0}$ are horizontal, $\widehat{f}_* \widehat{X}_{0,i}(p) = D_p f^n(X_{0,i}(p))$. Thus, the minimum of growth rates of $\widehat{f}_* \widehat{X}_{0,1}(p), \dots, \widehat{f}_* \widehat{X}_{0,d_0}(p)$ is at least $\log \lambda_1$. \square

Remark 3.13. Note also that in the ordering of the Lyapunov exponents given in Theorem 1.2, we may have $\lambda_{d_i+1} < \lambda_{d_i}$. We note that since $D_p f^n(X_{j,l}(p)) = \widehat{f}_* \widehat{X}_{j,l}(p) + Y_n$ for some $Y_n \in \text{span}\{\widehat{X}_{0,1}(p), \dots, \widehat{X}_{j-1,d_{j-1}}(p)\}$, the iterates of the Y_n component may grow faster than $\widehat{f}_* \widehat{X}_{j,l}(p)$ except when $l = d_j$. Hence we may not have $(i+1) \log \lambda_2 \leq \log \lambda_j$ for any $j \in \{n_i+1, \dots, n_{i+1}\}$.

Remark 3.14. We note that Proposition 3.12 and Theorem 1.4 may be combined and slightly generalized as follows. Suppose $df_* : \mathfrak{n}_p \rightarrow \mathfrak{n}_p$ has the form $df_* = D \cdot h$ where D is diagonalizable with positive diagonal values $(\lambda_1, \dots, \lambda_k)$ when restricted to \mathfrak{n}_p^0 and h is an isometry that preserves the eigenspaces of D . Then we obtain Lyapunov exponents of $d_p F$ of the form $\sum_{j=0}^k \log \lambda_{i_j}$ for $k \leq r$ and certain combinations of indices i_j .

Next we present the proof of Theorem 1.3.

THEOREM 1.3. *Let $f : N \rightarrow N$ be a local C^∞ diffeomorphism of a sub-Riemannian manifold N . Assume that the horizontal distribution E is generic at a point $p \in N$ where $f(p) = p$. Suppose the tangent cone $TC_p N$ is isomorphic to the Heisenberg group H^{2n+1} . If $\log \lambda_1, \log \lambda_2, \dots, \log \lambda_{2n}$ are the Lyapunov exponents of $D_p f|_E$ listed with*

multiplicity and $\log \lambda_{2n+1}$ is the remaining Lyapunov exponent of $D_p f$, then $\log \lambda_1 + \log \lambda_2 + \dots + \log \lambda_{2n} = n \log \lambda_{2n+1}$.

Proof. The Heisenberg group H^{2n+1} has a distinguished basis of right invariant vector fields, $\bar{X}_1, \dots, \bar{X}_n, \bar{Y}_1, \dots, \bar{Y}_n, \bar{Z}$ such that $[\bar{X}_i, \bar{Y}_j] = \delta_{ij} \bar{Z}$ and $[\bar{X}_i, \bar{X}_j] = [\bar{Y}_i, \bar{Y}_j] = [\bar{X}_i, \bar{Z}] = [\bar{Z}, \bar{Y}_j] = 0$. By assumption, $TC_p N$ is isomorphic to H^{2n+1} . Hence in a neighborhood of p there is a graded basis of fields $X_1, \dots, X_n, Y_1, \dots, Y_n, Z = [X_1, Y_1]$ such that $\mathcal{M}_p(\hat{X}_i) = \bar{X}_i$, $\mathcal{M}_p(\hat{Y}_i) = \bar{Y}_i$ and $\mathcal{M}_p([\hat{X}_i, \hat{Y}_i]) = \bar{Z}$ for $i \in \{1, \dots, n\}$. In other words, setting $\hat{Z} = [\hat{X}_1, \hat{Y}_1]$, we have $[\hat{X}_i, \hat{Y}_j] = \delta_{ij} \hat{Z}$ and $[\hat{X}_i, \hat{X}_j] = [\hat{Y}_i, \hat{Y}_j] = [\hat{X}_i, \hat{Z}] = [\hat{Z}, \hat{Y}_j] = 0$ for all $i, j \in \{1, \dots, n\}$. Note that by the identity (3.1), we have $Z^{(2)} = \hat{Z}$.

With respect to the chosen basis we have an identification $\mathfrak{n}_p = \mathbb{R}^{2n} \oplus \mathbb{R}$. The graded automorphism group of H^{2n+1} is $\mathbb{Z}_2 \ltimes (\mathrm{Sp}(2n, \mathbb{R}) \times \mathrm{Dil})$ where $\mathrm{Sp}(2n, \mathbb{R})$ is the symplectic group, $\mathrm{Dil} \cong \mathbb{R}_+$ are the dilations and the \mathbb{Z}_2 generator switches \bar{X}_i and \bar{Y}_i for $i = 1, \dots, n$ [Til70]. Since $df_* : \mathfrak{n}_p \rightarrow \mathfrak{n}_p$ is a graded automorphism, there is an $A \in \mathrm{Sp}(2n, \mathbb{R})$, a block matrix $U = \begin{bmatrix} 0 & I_n \\ I_n & 0 \end{bmatrix}$ or $U = I_{2n}$, and $\sigma > 0$ such that df_* has the form $df_*(x, z) = (\sigma U Ax, \sigma^2 z)$. (Here the U matrix represents the corresponding element of \mathbb{Z}_2 .) Since Lyapunov exponents of f^2 are twice those of f and $(UA)^2 \in \mathrm{Sp}(2n, \mathbb{R})$, without loss of generality we may replace f with f^2 and assume $df_*(x, z) = (\sigma Ax, \sigma^2 z)$. Next we show that with respect to the basis $\{X_1(p), \dots, X_n(p), Y_1(p), \dots, Y_n(p), Z(p)\}$ of $T_p N$, $D_p f = \begin{bmatrix} \sigma A & B \\ 0 & \sigma^2 \end{bmatrix}$ for some $2n \times 1$ matrix B .

It follows that with respect to the basis $\{\hat{X}_1, \dots, \hat{X}_n, \hat{Y}_1, \dots, \hat{Y}_n\}$, $\hat{f}_*(\hat{X}_i) = \sigma A \hat{X}_i$ and $\hat{f}_*(\hat{Y}_j) = \sigma A \hat{Y}_j$. We note that $\hat{X}_i(p) = X_i(p)$ and $\hat{Y}_j(p) = Y_j(p)$. By Lemma 3.10, $\hat{f}_*(\hat{X}_i) = \widehat{Df X_i}$ and $\hat{f}_*(\hat{Y}_j) = \widehat{Df Y_j}$. Thus with respect to the basis $\{X_1(p), \dots, X_n(p), Y_1(p), \dots, Y_n(p)\}$, by restricting of $D_p f$ on $\mathrm{span}\{X_1(p), \dots, X_n(p), Y_1(p), \dots, Y_n(p)\}$, we have $D_p f(X_i(p)) = A X_i(p)$ and $D_p f(Y_j(p)) = A Y_j(p)$.

Moreover, we have

$$\begin{aligned} \sigma^2 Z^{(2)} &= \hat{f}_*(Z^{(2)}) = \hat{f}_*([\hat{X}_1, \hat{Y}_1]) = [\hat{f}_*\hat{X}_1, \hat{f}_*\hat{Y}_1] \\ &= [\widehat{Df X_1}, \widehat{Df Y_1}] = (Df[X_1, Y_1])^{(2)} = (Df Z)^{(2)}. \end{aligned}$$

Thus,

$$D_p f(Z(p)) = Df Z(p) = (Df Z)^{(2)}(p) + (Df Z)^{(\leq 1)}(p) = \sigma^2 Z^{(2)}(p) + (Df Z)^{(\leq 1)}(p).$$

We note that $(Df Z)^{(\leq 1)}(p) \in \mathrm{span}\{X_1(p), \dots, X_n(p), Y_1(p), \dots, Y_n(p)\}$. Also, $Z = Z^{(2)} + Z^{(\leq 1)}$ with $Z^{(\leq 1)}(p) \in \mathrm{span}\{X_1(p), \dots, X_n(p), Y_1(p), \dots, Y_n(p)\}$. Hence, with respect to the basis $\{X_1(p), \dots, X_n(p), Y_1(p), \dots, Y_n(p), Z(p)\}$ of $T_p N$, there is a $2n \times 1$ matrix B such that $D_p f = \begin{bmatrix} \sigma A & B \\ 0 & \sigma^2 \end{bmatrix}$.

Now it follows that the Lyapunov exponents of f are $2 \log \sigma$ and the logarithms of the moduli of the eigenvalues of σA . Since $\det(\sigma A) = \sigma^{2n}$, we conclude that $n \log \lambda_{2n+1} = 2n \log \sigma$ is equal to the sum of all other exponents. \square

4. Sub-Riemannian dynamics

We will apply the ideas from the previous section to distributions tangent to foliations invariant under flows and diffeomorphisms. We start with a very general and abstract statement which we then develop in the context of hyperbolic dynamics. We will make the following hypotheses throughout this section.

Standing Hypotheses 4.1.

- X is a smooth compact manifold with $f : X \rightarrow X$ a C^1 diffeomorphism.
- \mathcal{F} is an f -invariant foliation tangent to a continuous distribution D .
- The leaves of \mathcal{F} are C^∞ and f is C^∞ along leaves.
- There is a df -invariant continuous subdistribution $E \subseteq D$.

We define

$$\Omega = \{v \in X : E \text{ is } C^\infty, \text{ horizontal and generic in a neighborhood of } v \text{ in } \mathcal{F}(v)\}.$$

Moreover, at each point $v \in \mathcal{F}(v)$ we have a filtration

$$E(v) = E^0(v) \subset E^1(v) \subset E^2(v) \subset \dots$$

of vector subspaces of $T_v \mathcal{F}(v)$ that are formed by taking the span of i -fold brackets of vector fields tangent to E at v . These form well-defined distributions E^i on Ω and we let $r = r(v)$ be the index such that $E^r(v) = T_v \mathcal{F}(v)$ for $v \in \Omega$. Observe that r is constant on each connected component of $\mathcal{F}(v) \cap \Omega$.

We first establish the following generalization of Theorem 1.1.

THEOREM 4.2. (Foliated tangent cone structure theorem) *Assume Hypotheses 4.1. Then we have the following statements.*

- (1) Ω is f -invariant and intersects every leaf of \mathcal{F} in a (possibly empty) open set.
- (2) For every $v \in \Omega$, the tangent cone $TC_v \mathcal{F}(v)$ of $\mathcal{F}(v)$ at v exists, is a Carnot nilpotent Lie group with a left invariant Carnot–Carathéodory metric and varies continuously on the intersection of Ω with each leaf.
- (3) The map f induces a Lie group isomorphism between the tangent cones $TC_v \mathcal{F}(v)$ of $\mathcal{F}(v)$ at $v \in \Omega$ and $TC_{f(v)} \mathcal{F}(f(v))$ of $\mathcal{F}(f(v))$ at $f(v)$. We call this the Carnot derivative of f at v .
- (4) If for a sufficiently large k , the distribution E is uniformly C^k along \mathcal{F} (see Definition 4.4 below), then Ω is open in X and the tangent cone $TC_v \mathcal{F}(v)$ varies continuously in $v \in \Omega$.

Similarly, for a C^1 flow $\varphi_t : X \rightarrow X$ and flow invariant distributions $E \subseteq D$ the analogous statements hold.

Inspecting the proof below, it will be clear that the degree of uniform regularity C^k of E suffices to be one less than the maximum nilpotency degree of the tangent cones on Ω . These nilpotency degrees are in turn all bounded by the dimension of the leaves of \mathcal{F} minus one.

We will break the proof into two main lemmas.

LEMMA 4.3. *Assume Hypotheses 4.1. Statements (1)–(3) of Theorem 4.2 hold.*

Proof. For every $w \in \mathcal{F}(v)$, we let $E^i(w)$ be the subspace of $D(w)$ spanned by all brackets of vector fields tangent to $E(w)$ of orders at most i . Let $n_i(w) = \dim E^i(w)$. Then $n_i(w)$ is f -invariant by the f -relation of brackets ($df[X, Y] = [df(X), df(Y)]$). Moreover, n_i is lower semicontinuous. Indeed, if a bracket of vector fields of order i does not vanish at a point then it does not vanish in a neighborhood in the unstable manifold of that point. The semicontinuity of n_i implies that n_i is locally constant on an open set of each leaf for every i . This latter open subset of each leaf is the intersection of Ω with that leaf. Because n_i is f -invariant, Ω is also f -invariant.

For every $v \in \Omega$, we consider a small enough neighborhood of v in $\mathcal{F}(v)$. This neighborhood is a sub-Riemannian manifold on which the horizontal distribution E is C^∞ and generic. By Theorem 3.2, the tangent cone $TC_v\mathcal{F}(v)$ exists. The continuity of tangent cones follows from Proposition 3.4. Moreover, the map f is a C^1 diffeomorphism from this neighborhood of v in $\mathcal{F}(v)$ onto a neighborhood of $f(v) \in \Omega$ in $\mathcal{F}(f(v))$. The map f preserves the distribution E , and so by Proposition 3.8, df induces an isomorphism $(df)_* : TC_v\mathcal{F}(v) \rightarrow TC_{f(v)}\mathcal{F}(f(v))$.

The flow case follows by restricting to a single time map $f = \varphi_t$. □

Note that while Ω is open in each leaf, the entire Ω may not be open in X . Next, we will discuss the continuity of tangent cones transversely to the foliation \mathcal{F} . We first recall the relevant topology.

Definition 4.4. Assume a foliation \mathcal{F} of X has C^k leaves. A function on X is called (transversely) uniformly C^k along \mathcal{F} if its k th-order derivatives exist along leaves of the foliation and are continuous on X . A distribution is called uniformly C^k along \mathcal{F} if there are local vector fields forming a basis of the distribution that are uniformly C^k along \mathcal{F} .

We complete the proof of Theorem 4.2 with the following lemma.

LEMMA 4.5. *Assume Hypotheses 4.1. If the distribution E is uniformly C^k along \mathcal{F} for a sufficiently large k , then the set Ω is open in X and the tangent cone $TC_v\mathcal{F}(v)$ varies continuously in $v \in \Omega$. In particular, statement (4) of Theorem 4.2 holds.*

Proof. Let $v \in \Omega$. The distribution E is horizontal and generic in a neighborhood of v in $\mathcal{F}(v)$. Since E is uniformly C^k , a neighborhood of v in X is contained in Ω and thus Ω is open.

For the second claim, choose $v_0 \in \Omega$. As in the proof of Proposition 3.4, on any sufficiently small neighborhood $U \subset \Omega$ of v_0 we may choose a basis X_1, \dots, X_{d_0} of vector fields spanning E such that:

- (1) the X_j vary continuously in the C^k topology; and
- (2) if $\{(j_1, \dots, j_i)\} \subset \{1, \dots, d_0\}^i$ is a family of indices whose corresponding iterated brackets $[\widehat{X}_{j_1}, [\widehat{X}_{j_2}, [\widehat{X}_{j_3}, \dots]]$ form the chosen basis $\{\widehat{X}_{i,j}\}$ of $\mathcal{M}_{v_0}^{-1}(\mathfrak{n}_{v_0}^{i-1})$, then the corresponding brackets also form a basis of $\mathcal{M}_v^{-1}(\mathfrak{n}_v^{i-1})$ for all $v \in U$.

Indeed, for any fixed index j the vector fields $\widehat{X}_j = \widehat{X}_{j,v}$ vary continuously in v , as do the bracket operations, and thus the non-degeneracy of these iterated brackets is an open

condition. It follows that the corresponding nilpotent structures vary continuously, as do the isomorphism classes of the nilpotent tangent cones.

Since the metric on each tangent cone $TC_v\mathcal{F}(v)$ is the Carnot–Carathéodory metric for the distributions induced by the inclusion of $E(v)$ in the Lie algebra \mathfrak{n}_v of $TC_v\mathcal{F}(v)$, the metric also varies continuously on the neighborhood U , and thus on all of Ω . \square

Combining this result with good dynamical properties, we obtain the following corollary.

COROLLARY 4.6. *Assume Hypotheses 4.1. If the distribution E is uniformly C^k for a sufficiently large k , then the isomorphism class of tangent cones $TC_v\mathcal{F}(v)$ is continuous and f -invariant for $v \in \Omega$. Moreover, if f is transitive and E is C^∞ somewhere on a leaf then Ω is open and dense and the isomorphism class of any tangent cone is constant on Ω . The same statements hold for f replaced by a flow φ_t .*

In this setting, we call the isomorphism class of tangent cones obtained in Corollary 4.6 the *Carnot nilpotent structure associated to φ_t* .

Proof. The first claim follows from Theorem 4.2. The topological transitivity of f implies that there is a dense orbit in X which must intersect Ω since Ω is open. If E is C^∞ on any open set of a leaf then Ω is also non-empty and therefore dense since it is invariant under f . The isomorphism class of tangent cones on Ω is constant because isomorphism classes are constant on a dense orbit, depend continuously on the underlying point, and the space of isomorphism classes is Hausdorff by Theorem 2.3. Lastly, the proof holds verbatim for flows by replacing f by φ_t . \square

Kalinin [Kal11] defined a notion of closing property for diffeomorphisms. We define the analogous notion of *closing property* for flows.

Definition 4.7. A flow $\varphi_t : X \rightarrow X$ of a compact manifold X has the *stable closing property* (with exponent λ) if there are $c, \lambda, \delta_0 > 0$ with $\lambda > 0$ such that for every $x \in X$ and some $T \in \mathbb{R}$ with $d(x, \varphi_T(x)) < \delta_0$ there are $p, y \in X$ such that

- (1) p is periodic with period T_0 where $|T_0 - T| < \delta_0$, and
- (2) $d(\varphi_t(x), \varphi_t(p)) < ce^{-\lambda \min\{t, T_0 - t\}} d(x, \varphi_T(x))$ for $0 \leq t \leq T_0$, and
- (3) $d(\varphi_t(p), \varphi_t(y)) < ce^{-\lambda t} d(x, \varphi_T(x))$ and $d(\varphi_t(x), \varphi_t(y)) < ce^{-\lambda(T_0 - t)} d(x, \varphi_T(x))$.

Here y plays a connecting role of being stably related to p and unstably related to x .

Examples of dynamical systems having the closing property include Anosov flows and diffeomorphisms and flows over subshifts of finite type (cf. [Kal11]).

We deduce Theorem 1.6 from the introduction as a conclusion of this section.

THEOREM 1.6. *Assume Hypotheses 4.1. Suppose the distribution E is uniformly C^k for a sufficiently large k and \mathcal{F} is transversally Hölder continuous. Also assume that the C^1 diffeomorphism f (or flow φ_t) is topologically transitive, satisfies the stable closing property and that $df|_D$ is transversally Hölder continuous. Lastly, suppose that the graded nilpotent group associated to D on Ω is asymmetric and $(r + 1)$ -step. Let μ be any finite f -invariant (respectively, φ_t -invariant) ergodic measure whose support*

$\text{Supp}(\mu)$ satisfies $\text{Supp}(\mu) \cap \Omega \neq \emptyset$. Then the Lyapunov exponents of f (respectively, ϕ_1) along \mathcal{F} are $\log \lambda, 2 \log \lambda, \dots, (r+1) \log \lambda$ with multiplicities $\dim E, \dim E^1 - \dim E, \dots, \dim E^r - \dim E^{r-1}$ for some $\lambda = \lambda_\mu > 1$.

Proof. Recall that Ω is the subset obtained from Corollary 4.6. Let $v \in \Omega$ be a periodic point of period T . It follows that $(f^T|_{\mathcal{F}(v)})_* : TC_v \mathcal{F}(v) \rightarrow TC_v \mathcal{F}(v)$ is a graded automorphism of the nilpotent group $TC_v \mathcal{F}(v)$. On the other hand, the isomorphism class of $TC_v \mathcal{F}(v)$ is asymmetric. Hence $(f^T|_{\mathcal{F}(v)})_*$ is a homothety. Suppose $TC_v \mathcal{F}(v)$ is an $(r+1)$ -step Carnot nilpotent Lie group. By Theorem 1.4, there exists $\lambda(v)$ such that the Lyapunov exponents of f^T along \mathcal{F} for v are $T \log \lambda(v), 2T \log \lambda(v), \dots, (r+1)T \log \lambda(v)$.

Since $\text{Supp}(\mu) \cap \Omega \neq \emptyset$, Ω has full μ -measure as it is invariant and μ is ergodic. By [Kal11, Proposition 3.2], Lyapunov exponents of $df|_D$ with respect to any invariant ergodic measure are approximated by those at periodic points. (This proposition is stated for standard $\text{GL}(n, \mathbb{R})$ -valued cocycles; however, following the discussion after [GS97, Proposition 2.6] these estimates may be applied to derivative cocycles as well.) Therefore, there is $\lambda > 1$ such that Lyapunov exponents of f along \mathcal{F} with respect to μ are $\log \lambda, 2 \log \lambda, \dots, (r+1) \log \lambda$. The proof in the case of flows follows verbatim after replacing f by φ_t . \square

While we need greater regularity in Theorem 1.6, the Hölder continuity of E often follows from the dominated splitting assumption. For example, we have the following theorem (cf. also [BP07, Theorem 5.3.2]).

THEOREM 4.8. [CP15, Theorem 4.11 and Remark 4.12] *Let $f : X \rightarrow X$ be a C^2 diffeomorphism and $\Lambda \subset X$ a compact f -invariant set admitting a dominated splitting of the form $T_\Lambda X = E \oplus F$. Then there is $\theta \in (0, 1]$ such that the bundles E and F are θ Hölder continuous. Moreover, $\theta \in (0, 1]$ can be chosen to be any number such that, for all sufficiently large $N \geq 1$,*

$$\|Df^N|_{E(x)}\| \|Df^N|_{F(x)}\|^\theta < \|Df^{-N}|_{F(x)}\|^{-1} \quad \text{for every } x \in \Lambda.$$

Remark 4.9. The analogous statement for flows $\varphi_t : X \rightarrow X$ follows from the above result applied to the time-one map. Moreover, the same proof works for arbitrary C^α cocycles over C^1 diffeomorphisms or flows admitting a dominated splitting for $\alpha \in (0, 1]$.

Lastly, note that Anosov flows with $E = E^s$ is a special case (cf. [Bal95, Appendix by Brin, Proposition 4.4]).

In the next sections we consider applications of our previous results to sundry geometric settings.

5. Application: local rigidity of smooth dominated splittings

In this section we will present some cases where the existence of a leafwise smooth invariant splitting of the unstable bundle leads to some form of rigidity. This provides some evidence for positive answers to Questions 1.8. However, we first show that smooth time changes of flows with uniformly C^k slow distributions along the unstable foliation

maintain this property. Hence, in general, the best rigidity we may expect is smooth orbit equivalence.

5.1. Time changes. Let $\varphi_t : N \rightarrow N$ be the C^∞ flow generated by the vector field $x \mapsto X_x$. Given a positive C^∞ function $\ell : N \rightarrow (0, \infty)$, consider the C^∞ flow ψ_t whose generating vector field is $x \mapsto \ell(x)X_x$. The cumulative time change $\tau : N \times \mathbb{R} \rightarrow \mathbb{R}$ is given by $\tau(x, t) = \int_0^t \ell(\psi_s x) ds$, and hence $\psi_t(x) = \varphi_{\tau(x,t)}(x)$. The inverse function $\sigma(x, t) = \tau^{-1}(x, t)$ satisfies $\varphi_t(x) = \psi_{\sigma(x,t)}(x)$ and corresponds to the cumulative time change for the field rescaling function $k(x) = 1/\ell(x)$.

Anosov and Sinai [AS67] showed that if φ_t is a C^∞ Anosov flow and ψ_t is obtained from φ_t by the multiplication of speeds by ℓ , then ψ_t is Anosov. In fact, they showed that we have a hyperbolic splitting

$$TN = E_{\psi_t}^u \oplus E_{\psi_t}^s \oplus E_{\psi_t}^0$$

for $D\psi_t$ where

$$E_{\psi_t}^u(x) = \{v + z(x, v)X_x : v \in E_{\varphi_t}^u(x)\}$$

for some real-valued function $z(x, \cdot) : E_{\varphi_t}^u(x) \rightarrow \mathbb{R}$ which is linear in its second argument and continuous in x . Following Parry [Par86], we may express the function z as

$$z(x, \xi) = -\ell(x) \int_0^\infty (D\varphi_s \xi(\ell)/\ell(\varphi_s x)^2) ds = \ell(x) \int_0^\infty \xi(k \circ \varphi_s) ds.$$

We now observe that if ℓ is smooth then so are τ , k and σ as functions on N or $N \times \mathbb{R}$. Moreover, if the invariant splitting for $E_{\varphi_t}^u = E_{\text{slow}, \varphi_t}^u \oplus E_{\text{fast}, \varphi_t}^u$ is leafwise smooth, then the graphs

$$E_{\text{slow}, \psi_t}^u = \{v + z(x, v)X_x : v \in E_{\text{slow}, \varphi_t}^u\},$$

$$E_{\text{fast}, \psi_t}^u = \{v + z(x, v)X_x : v \in E_{\text{fast}, \varphi_t}^u\}$$

remain leafwise smooth and invariant under ψ_t . This last statement follows from the formula

$$D\psi_{\sigma(x,t)}(v + z(x, v)X_x) = D\varphi_t v + z(\varphi_t x, D\varphi_t v)X_{\varphi_t(x)}$$

which we apply in forward time to $E_{\text{slow}, \psi_t}^u$ and in backward time in the case of $E_{\text{fast}, \psi_t}^u$. From the explicit formula for $z(x, v)$ we see that its overall regularity restricted to the subbundle $E_{\text{slow}, \varphi_t}^u$ will be the same as that of $E_{\text{slow}, \varphi_t}^u$ since ℓ , k and φ_s are smooth.

We summarize this discussion in the following proposition.

PROPOSITION 5.1. *If a C^∞ Anosov flow φ_t has a uniformly C^k slow unstable distribution along its unstable foliation, then a smooth time change ψ_t also has this property.*

Observe that, in general, such C^∞ time changes ψ_t are not conjugate to φ_t as periodic orbits may have different periods. To obtain explicit examples, we may apply the above proposition to geodesic flows of compact locally symmetric spaces or suspensions of Anosov diffeomorphisms with smooth slow distributions. Flows of the latter type arise from algebraic examples of splittings, for example from products or toral automorphisms.

5.2. Geodesic flows. We next apply the discussion on sub-Riemannian dynamics from the previous section to geodesic flows of closed manifolds of negative sectional curvature. We will prove a local rigidity statement for certain perturbations of a locally quaternionic hyperbolic or octonionic hyperbolic closed manifold.

Definition 5.2. Let \mathcal{A} be a topological space and let $\{\mathcal{F}_\rho\}_{\rho \in \mathcal{A}}$ be a parametrized family of foliations of a manifold M . We say that a parametrized family of dominated splittings $\{T\mathcal{F}_\rho = E_\rho \oplus F_\rho\}_{\rho \in \mathcal{A}}$ is *uniformly C^k continuous* in the parameter if E_ρ and F_ρ are C^k along each leaf of the foliation \mathcal{F}_ρ and their derivatives up to order k vary continuously in the parameter ρ with respect to the given topology on the index set \mathcal{A} . We say two splittings $E_\rho \oplus F_\rho$ and $E_{\rho_0} \oplus F_{\rho_0}$ from a uniformly C^k family of splittings are ϵ -uniformly C^k -close if their derivatives up to order k along their respective foliations \mathcal{F}_ρ and \mathcal{F}_{ρ_0} are ϵ -close.

Remark 5.3. By the permanence theorem [HPS77, Theorem 6.8] the W_g^u foliations for the geodesic flow of g , though only transversely Hölder on all of M , have leafwise smooth distributions that vary continuously in the C^k topology as g varies continuously in the C^{k+1} topology. Even though $E_{\text{fast},g}^u$ is uniformly C^k along W_g^u on each (M, g) , $E_{\text{slow},g}^u$ is only continuous along W_g^u in general. However, even when $E_{\text{slow},g}^u$ is assumed to be C^∞ along leaves of W_g^u , it is not necessarily uniformly C^k on M and may not even be uniformly C^k in the metric parameter g as it varies in the C^{k+1} topology for any $k > 0$. We will need to assume the latter property in some of the statements below.

Consider a smooth n -manifold X . For $n_1 \leq n_2 \leq \dim X$, let $\text{Flag}(n_1, n_2) \rightarrow X$ be the smooth fiber bundle whose fiber $\text{Flag}_x(n_1, n_2)$ is the space of all 2-flags of n_1 -dimensional subspaces of n_2 -dimensional subspaces of $T_x X$. Now let \mathcal{EF} be the subset of C^0 sections $x \rightarrow (E_x \subset F_x) \in \text{Flag}_x(n_1, n_2)$ such that the corresponding distribution F generates a C^0 foliation \mathcal{F} with C^∞ leaves and the E distribution is C^∞ along the leaves of the foliation \mathcal{F} . We write these sections as $E \subset F$ for corresponding distributions E and F . The $C^{0,k}$ topology on \mathcal{EF} is the maximal refinement of the subspace topology inherited from the compact-open topology on C^0 sections of $\text{Flag}(n_1, n_2)$ such that the partial derivatives up to order k of E along the leaves of \mathcal{F} vary continuously.

LEMMA 5.4. *Let X be a smooth closed manifold with a pair of distributions $(E_0 \subset F_0) \in \mathcal{EF}$ such that E_0 restricted to each leaf is generic of order $r + 1$ along the leaves of \mathcal{F} . Then there is an open set $U \subset \mathcal{EF}$ in the $C^{0,r}$ topology such that each $(E \subset F) \in U$ is generic of order $r + 1$ and the subbundles $E = E^0, E^1, \dots, E^r$ of iterated bracket spaces vary continuously as subbundles of $T X$.*

Proof. Since X is closed, F_0 defines a foliation \mathcal{F} , and E_0 is a given distribution, we may find a finite open cover of foliation charts for (X, \mathcal{F}) where on each open chart V , the distribution E_0 is spanned by continuous vector fields X_1, \dots, X_{d_0} which are C^∞ on each leaf of \mathcal{F} and whose successive brackets at each point x generate a filtration $E_0(x) = E_0^0(x) \subset E_0^1(x) \subset E_0^r(x) = F_x$ and fit together to form subbundles locally and hence globally.

Since the X_i vary continuously and the iterated brackets along each leaf vary continuously in the parameters of the $C^{0,r}$ topology, there is an open neighborhood $U \subset \mathcal{EF}$ of

$(E_0 \subset F_0)$ in the $C^{0,r}$ topology for which the iterated brackets of the nearby X_i spanning E continue to be non-zero on all of V . (For sufficiently close foliations \mathcal{F} for the distribution F , the open set V still serves as a chart.)

Since there are only finitely many charts V , by intersecting the resulting open sets U we may find a common neighborhood. \square

LEMMA 5.5. *Let (M, g_0) be a closed negatively curved manifold admitting a leafwise C^∞ dominated splitting $E_{\phi_t^0}^u = E_{\text{fast}, \phi_t^0}^u \oplus E_{\text{slow}, \phi_t^0}^u$ for its geodesic flow ϕ_t^0 . Assume that $(E_{\text{slow}, \phi_t^0}^u \subset E_{\phi_t^0}^u) \in \mathcal{EF}$ and that $E_{\text{slow}, \phi_t^0}^u$ is generic and horizontal of order $r+1$ along the leaves of $W_{\phi_t^0}^u$. Recall that by Proposition 2.2 there is a C^1 neighborhood U of ϕ_t^0 such that any flow $(SM, \phi_t) \in U$ has a dominated splitting $E_{\text{fast}, \phi_t}^u \oplus E_{\text{slow}, \phi_t}^u$. If we further assume that this splitting is C^∞ along unstable leaves and sufficiently uniformly C^r -close (along the unstable foliation) to that of ϕ_t^0 then $(E_{\text{slow}, \phi_t}^u \subset E_{\phi_t}^u) \in \mathcal{EF}$ and $E_{\text{slow}, \phi_t}^u$ is generic and horizontal of order $r+1$ along the leaves of \mathcal{F} . Furthermore, the tangent cone map $v \mapsto TC_v W_{\phi_t}^u$ associated to (M, ϕ_t) exists and is C^0 -close to $v \mapsto TC_v W_{\phi_t^0}^u$, the tangent cone map for ϕ_t^0 , with respect to the Hausdorff topology on the moduli space $\mathcal{NL}_{n-1}/\text{GL}(n-1, \mathbb{R})$.*

Proof. Recall that the dominated splitting condition is an open condition in the C^r topology and thus it holds on some neighborhood U of ϕ_t^0 .

As in the proof of Lemma 4.5, we exploit the fact that both the Carnot metric and the algebraic structure of the tangent cone depend on the construction of the M\'etivier fields $\widehat{X}_{j,k;x}$.

By assumption, the 2-flag of distributions $E_{\text{slow}, \phi_t}^u \subset E^u$ are C^∞ along $W_{\phi_t}^u$ and uniformly close to $E_{\text{slow}, \phi_t^0}^u \subset E_{\phi_t^0}^u$ in the C^r topology. Provided they are close enough, then by Lemma 5.4 $E_{\text{slow}, \phi_t}^u$ is generic of order $r+1$, with nearby subbundles of iterated bracket spaces. In particular, $E_{\text{slow}, \phi_t}^u$ is horizontal as well. Moreover, the construction of the $\widehat{X}_{r-i,j;x}$ for $i = 0, \dots, r$ varies continuously in the C^i topology on the vector fields $X_{0,1;x}, \dots, X_{0,d_0;x}$ locally spanning $E_{\text{slow}, \phi_t}^u$. By hypothesis the latter fields depend continuously in the C^r topology in ϕ_t . We conclude as in the proof of Lemma 4.5 and Proposition 3.4 that the nilpotent structure in $\mathcal{NL}_{n-1}/\text{GL}(n-1, \mathbb{R})$ is C^0 -close as claimed. \square

Remark 5.6. We observe that if metrics vary in the C^{r+1} topology, then the geodesic flows vary in the C^r topology. Hence the same lemma holds for metrics except that U is a C^2 neighborhood of g_0 .

THEOREM 1.7. *Let ϕ_t^0 be the geodesic flow on a locally quaternionic hyperbolic or octonionic hyperbolic closed manifold M . Then if ϕ_t is any C^∞ flow C^1 -close to ϕ_t^0 for which $E_{\text{slow}, \phi_t}^u$ remains C^∞ along unstable leaves and is sufficiently uniformly C^1 -close (in the sense of Definition 5.2) to that of ϕ_t^0 , then ϕ_t is C^∞ orbit equivalent to ϕ_t^0 .*

Proof. We observe that the symmetric flow ϕ_t^0 has a dominated splitting $E^u = E_{\text{fast}}^u \oplus E_{\text{slow}}^u$ which is globally C^∞ and for which E_{slow}^u is generic of order one and horizontal. By Lemma 5.5 there is a C^1 open neighborhood U of ϕ_t^0 where $E_{\text{slow}, \phi_t}^u$ is generic of order one

and horizontal whenever $\phi_t \in U$ has a dominated splitting which is C^∞ along unstable leaves and uniformly C^1 -close along the unstable foliation to that of ϕ_t^0 . Moreover, the associated tangent cones $TC_v W^u(v)$ for ϕ_t are C^0 -close to those of ϕ_t^0 .

Recall that by Examples 2.8 the tangent cone associated to (M, ϕ_t^0) is asymmetric. By Corollary 2.10, after possibly shrinking U , the tangent cone associated to (M, ϕ_t) is also asymmetric. We can shrink U to an even smaller set so that the tangent cone associated to (M, ϕ_t) is 2-step. Thus by Theorem 1.6, the unstable Lyapunov exponents are $\log \lambda$ and $2 \log \lambda$ for a $\lambda > 1$. The multiplicity of the exponents are the dimensions of the slow and the fast unstable distribution. Therefore, the Lyapunov spectra of the geodesic flows on (M, ϕ_t) and (M, ϕ_t^0) are proportional.

We wish to apply [But19, Theorem 3.2] which is stated for the so-called *horizontal measure*, μ_M . We need to verify that this measure has full support. We observe that by [But19, §2.8] this is a Gibbs state for a Hölder potential. These have full support in our setting ([PPS15, p. 50] or [CPZ19, Theorem 4.11]). \square

Remark 5.7. By the Livšic theorem, whenever two orbit equivalent flows have the same periods on periodic points they are conjugate. The regularity of the conjugacy will be at least one less than the regularity of the time change.

THEOREM 1.9. *Let g_0 be a locally quaternionic hyperbolic or octonionic hyperbolic metric on a smooth closed manifold M . Then g_0 is locally rigid within the family of C^2 -close C^∞ metrics whose E_{slow}^u remains C^∞ along unstable leaves and is sufficiently uniformly C^1 -close (in the sense of Definition 5.2) to that of g_0 .*

Remark 5.8. The above theorem is reminiscent of the global rigidity result (Theorem 3) in [BFL92]. While we do not assume any transverse regularity of the splitting in our theorem, we do require that the metric is nearby the locally symmetric one. We also note that there is a C^2 open neighborhood of g_0 such that the unstable distributions of the perturbed manifolds admit dominated splittings by Proposition 2.2.

Proof. The proof is nearly identical to that of Theorem 1.7, except that we note by Remark 5.6 there is a C^2 open neighborhood U of g_0 with the desired properties. Moreover, we finish using Theorem 1.5 of [But19] instead of Theorem 3.2. \square

Remark 5.9. If g_0 is any metric as in Lemma 5.5 whose associated nilpotent tangent cone has an asymmetric Lie algebra, then by Theorem 1.6 its unstable Lyapunov spectrum is of the form $\log \lambda, 2 \log \lambda, \dots, (r+1) \log \lambda$ for some $\lambda > 1$. We can conclude by the proof of Theorem 1.9 that any metric that is sufficiently uniformly C^2 -close along unstable leaves will also have a Lyapunov spectrum of the same form.

5.3. Diffeomorphisms of nilmanifolds. In this section we apply our results to perturbations of automorphisms of certain nilmanifolds with smooth dominated splittings.

Standing assumption: Let M be a closed manifold and let f_0 be a transitive C^∞ Anosov diffeomorphism such that tangent cones of unstable leaves exist everywhere and are isomorphic to a fixed asymmetric $(r+1)$ -step Carnot nilpotent Lie group N . Let E_{slow, f_0}^u

be the horizontal distribution along unstable leaves that gives rise to the tangent cone structure.

We obtain the following local rigidity theorem.

THEOREM 1.10. *There is a C^1 open neighborhood U of f_0 in $\text{Diff}^\infty(M)$ such that if $f \in U$ admits a smooth splitting $E_f^u = E_{\text{fast},f}^u \oplus E_{\text{slow},f}^u$ along unstable leaves with $\dim(E_{\text{slow},f}^u) = \dim(E_{\text{slow},f_0}^u)$, and $E_{\text{slow},f}^u$ is sufficiently uniformly C^r -close along unstable leaves to E_{slow,f_0}^u , then for any invariant ergodic measure μ there is $\lambda_\mu > 1$ such that the unstable Lyapunov exponents of f with respect to μ , are $\log \lambda_\mu, 2 \log \lambda_\mu, \dots, (r+1) \log \lambda_\mu$ with the same multiplicity as for f_0 .*

Proof. By the construction of f_0 , tangent cones of unstable manifolds of f_0 exist everywhere and are isomorphic as graded nilpotent Lie groups to N .

We argue as in the proof of Theorem 1.9. The tangent cones of unstable manifolds of f exist everywhere, and such tangent cones are close to N in the variety of Carnot nilpotent Lie groups. By Corollary 2.10, those tangent cones are asymmetric. By Theorem 1.6, there is $\lambda_\mu > 1$ such that all unstable Lyapunov exponents, without multiplicity, of f with respect to μ , are $\log \lambda_\mu, 2 \log \lambda_\mu, \dots, (r+1) \log \lambda_\mu$. The multiplicities are given by the dimensions of the bracket spaces starting with $E_{\text{slow},f}^u$ which have the same dimensions as for f_0 . \square

Recall that for any transitive Anosov diffeomorphism f there is a unique invariant Sinai–Ruelle–Bowen (SRB) measure, which we call σ (see [KH95, 20.3.8] and [Sin72]). For f_0 as in Theorem 1.10, we denote by σ_0 the unique SRB measure for f_0 . In the next corollary we obtain a rigidity statement under an additional assumption which is analogous to a higher hyperbolic rank condition (cf. below).

COROLLARY 5.10. *Suppose we are in the setting as Theorem 1.10 with M a nilmanifold and f_0 an automorphism. In addition, assume $\lambda_\sigma(f) \geq \lambda_{\sigma_0}(f_0)$. Then σ is the measure of maximal entropy for f and has the same Lyapunov spectrum as σ_0 for f_0 .*

Proof. Set $\dim E^{-1} = 0$ and let $d_i = \dim E^i - \dim E^{i-1}$ for $i = 0, \dots, r$. By the Pesin formula and Theorem 1.10, we also have $h_\sigma(f) = \sum_{i=0}^r (i+1) \log \lambda_\sigma(f) d_i$. Moreover, by structural stability f and f_0 are conjugate and so they share the same topological entropies $h_{\text{top}}(f) = h_{\text{top}}(f_0)$. Since f_0 is algebraic, the Lyapunov exponents are independent of the measure and so Haar measure σ_0 is the measure of maximal entropy. Together with our assumptions, we have

$$\begin{aligned} h_{\text{top}}(f) &\geq h_\sigma(f) = \sum_i i \log \lambda_\sigma(f) d_i \\ &\geq \sum_i i \log \lambda_{\sigma_0}(f_0) d_i = h_{\sigma_0}(f_0) = h_{\text{top}}(f_0) = h_{\text{top}}(f). \end{aligned}$$

Hence all of the inequalities are equalities. Therefore $h_{\text{top}}(f) = h_\sigma(f)$ and hence σ is the measure of maximal entropy for f . Moreover, $\lambda_\sigma(f) = \lambda_{\sigma_0}(f_0)$ and so the spectra coincide. \square

As an application we describe a class of examples of special Anosov nil-automorphisms.

Definition 5.11. A nilpotent Lie algebra \mathfrak{n} is called rational if it is a Lie algebra over \mathbb{Q} . A nilpotent Lie group N is called rational if there is a rational Lie algebra \mathfrak{n} such that $\text{Lie}(N) = \mathfrak{n} \otimes \mathbb{R}$.

Example 5.12. [Lau03, Theorem 3.1] Let N be a graded rational nilpotent group. Then there is a lattice $\Gamma < N \times N$ such that the nilmanifold $M = (N \times N)/\Gamma$ admits an Anosov automorphism in which unstable and stable manifolds are vertical and horizontal copies of N .

We obtain the following as an immediate corollary to Theorem 1.10.

COROLLARY 1.11. *Let N be an asymmetric k -step Carnot rational nilpotent group. Let f_0 be the Anosov automorphism of $M = (N \times N)/\Gamma$ obtained from Example 5.12. Then there is a C^1 open neighborhood U of f_0 in $\text{Diff}^\infty(M)$ such that if $f \in U$ admits a smooth dominated splitting $E_f^u = E_{\text{fast},f}^u \oplus E_{\text{slow},f}^u$ along unstable leaves and $E_{\text{slow},f}^u$ is sufficiently uniformly C^r -close along unstable leaves to E_{slow,f_0}^u , then for any invariant ergodic measure μ there is $\lambda_\mu > 1$ such that the unstable Lyapunov exponents of f with respect to μ are $\log \lambda_\mu, 2 \log \lambda_\mu, \dots, (r+1) \log \lambda_\mu$ with the corresponding multiplicities as for f_0 .*

Remark 5.13. In the above corollary, one may replace the hypothesis of a smooth dominated splitting with that of a slow distribution $E_{\text{slow},f}^u$ smooth along unstable leaves. This readily follows from Proposition 2.2.

Even though the Heisenberg group is not asymmetric, we may still obtain resonance of Lyapunov exponents for Anosov diffeomorphisms on products of this group.

Example 5.14. The following example due to Borel [Sma67, Example 1 in I-(3.8)] provides an Anosov diffeomorphism on a nilmanifold whose unstable tangent cones are not asymmetric nilpotent groups. Let N be the three-dimensional Heisenberg group. Consider $(N \times N)/\Gamma$ where Γ is the lattice subgroup whose elements (with respect to the standard basis on the Lie algebra) are of the form $(\alpha, \beta, \gamma, \alpha^\sigma, \beta^\sigma, \gamma^\sigma)$ for $\alpha, \beta, \gamma \in \mathbb{Z}[\sqrt{3}]$ and where σ represents the Galois automorphism with $(a + b\sqrt{3})^\sigma = a - b\sqrt{3}$. Let f_0 be the Anosov diffeomorphism induced from the Lie algebra map $A(a, b, c, d, e, f) = (\lambda a, \lambda^2 b, \lambda^3 c, \lambda^{-1} d, \lambda^{-2} e, \lambda^{-3} f)$ for $\lambda = 2 + \sqrt{3}$. Here the unstable distribution corresponds to the first factor of N with coordinates (a, b, c) and the slow distribution has coordinates (a, b) which is the standard horizontal (and generic) distribution of N .

We may obtain a similar corollary to Corollary 1.11 for the above example.

COROLLARY 1.12. *Let N be the three-dimensional Heisenberg group. Let Γ be the lattice and f_0 the Anosov automorphism of $M = (N \times N)/\Gamma$ obtained from Example 5.14. Then there is a C^1 open neighborhood U of f_0 in $\text{Diff}^\infty(M)$ such that if $f \in U$ admits a smooth splitting $E_f^u = E_{\text{fast},f}^u \oplus E_{\text{slow},f}^u$ along unstable leaves and $E_{\text{slow},f}^u$ is sufficiently uniformly C^1 -close along unstable leaves to E_{slow,f_0}^u , then for any invariant ergodic measure μ the unstable Lyapunov exponents for f are $\log \lambda_1, \log \lambda_2$ and $\log \lambda_1 + \log \lambda_2$ for some $\lambda_1 > 1$ and $\lambda_2 > 1$ depending on μ .*

Proof. We note that this result follows immediately from the analogue of Theorem 1.10 for Heisenberg groups in place of asymmetric groups and resonance in place of arithmeticity in the conclusion. The proof may be duplicated except for two points.

First, we need to show that, under the perturbation, the unstable tangent cones for f are still isomorphic to the Heisenberg group. Since $E_{\text{slow},f}^u$ is sufficiently uniformly C^1 -close along unstable leaves to E_{slow,f_0}^u , the horizontal distribution of $TC_v W_f^u(v)$ remains codimension-one, horizontal and generic. Hence $TC_v W_f^u(v)$ is a 2-step Carnot nilpotent Lie group with one-dimensional center for every $v \in SM$. Moreover, the tangent cones for f are C^0 -close to those for f_0 . The Lie bracket induces a bilinear form $[\cdot, \cdot] : \mathfrak{n}_v^0 \times \mathfrak{n}_v^0 \rightarrow \mathfrak{n}_v^1$ between the first and second levels \mathfrak{n}_v^0 and \mathfrak{n}_v^1 of the Lie algebra \mathfrak{n}_v of $TC_v W_f^u(v)$, and it remains non-degenerate. Consequently, as the center is one-dimensional and there is only one non-degenerate skew symmetric bilinear form on \mathfrak{n}_v^0 for every $v \in SM$, $TC_v W^u(v)$ is isomorphic as a graded nilpotent group to the Heisenberg group N .

Second, we need an analogous result to Theorem 1.6. In turn, we observe that in the proof of Theorem 1.6, we may replace Theorem 1.4 with Theorem 1.3 to obtain the corresponding analogue for the Heisenberg group in the hypotheses and the resonance in the conclusion. Having done so, the analogous result follows. \square

It is easy to construct examples of Anosov diffeomorphisms with integrable slow distributions on tori or products of nilmanifolds. One might ask whether for irreducible Anosov automorphisms of non-abelian nilpotent groups the slow distribution must be horizontal and generic. However, this is not the case. Indeed, the slow unstable distribution of [Shu69, Example 2 on p. 189] is integrable.

As our final application of smooth splittings we will investigate the local rigidity of the projective action of a quaternionic or octonionic hyperbolic lattice on its ideal boundary sphere.

5.4. Local rigidity of projective boundary actions. Sullivan [Sul85] initiated the study of local rigidity of lattice actions on the boundary. Ghys [Ghy93] introduced a suspension construction which relates actions of fundamental groups of surfaces on the circle to Anosov flows. This was later adapted by Yue [Yue95] to the study of lattice actions on higher-dimensional spheres. We will employ this construction to obtain a rigidity theorem for boundary actions (cf. also [Asa17, Theorem 6.1]).

Consider a rank-one symmetric space X with connected component $G < \text{Isom}(X)$ of its isometry group. As is well known, the ideal boundary ∂X of X may be identified as $\partial X = G/P$ for a (minimal) parabolic subgroup P . For a discrete subgroup $\Gamma < \text{Isom}(X)$, let ρ_0 be the action of Γ on ∂X induced from the action of Γ on X . Note that ρ_0 is nothing but the left action on G/P and thus is C^∞ . This action preserves the projection to the boundary of the slow unstable distribution E_0 for the geodesic flow since the stable foliation and the holonomy along it are C^∞ and Γ -equivariant.

We briefly recall the suspension construction mentioned above. Let $\rho : \Gamma \rightarrow \text{Diff}^\infty(\partial X)$ be a C^1 -close perturbation of ρ_0 . More precisely, we assume that ρ is C^1 -close to ρ_0 on a fixed finite set of generators of Γ (we recall that lattices in semisimple groups are always finitely generated). Consider the unit tangent bundle SM for the locally symmetric

space and note $\tilde{M} = X$. We have a diffeomorphism between SX and $(\partial X \times \partial X \setminus D) \times \mathbb{R}$ where D is the diagonal of $\partial X \times \partial X$.

We also have a diffeomorphism $\hat{q} : SX \rightarrow X \times \partial X$ via $v \mapsto \hat{q}(v) = (\pi(v), v(\infty))$, where $\pi(v)$ is the projection of v to its base point. The map \hat{q} descends to a diffeomorphism $q : SM \rightarrow (X \times \partial X)/\hat{\rho}_0$ where $\hat{\rho}_0(\gamma)(x, \xi) = (\gamma x, \rho_0(\gamma)\xi)$ for all $\gamma \in \Gamma$ and $(x, \xi) \in X \times \partial X$. (Here $\Gamma = \pi_1(M)$ acts by deck transformations on X .)

As ρ is C^1 -close to ρ_0 , there is a C^∞ diffeomorphism $f : (X \times \partial X)/\hat{\rho} \rightarrow (X \times \partial X)/\hat{\rho}_0$ where $\hat{\rho}(\gamma)(x, \xi) = (\gamma x, \rho(\gamma)\xi)$ by Proposition A.1. Observe that the actions of $\hat{\rho}$ and $\hat{\rho}_0$ both preserve the leaves of the first-factor foliation $\{X \times \{\xi\} : \xi \in \partial X\}$. Moreover, the map f maps horizontal leaves in $(X \times \partial X)/\hat{\rho}$ to leaves that are C^1 -close to horizontal leaves in $(X \times \partial X)/\hat{\rho}_0$. The manifolds $\hat{q}^{-1}(X \times \{\xi\})$, as ξ varies, are the leaves of the center-stable foliation W^{cs} for the geodesic flow ϕ_t . For each $x \in X$ we let $\sigma_x : \partial X \rightarrow \partial X$ be the map which takes $\xi \in \partial X$ to the opposite endpoint of the geodesic line through x and ξ . Then $\hat{q}^{-1}(\{(y, \sigma_y \circ \sigma_x(\xi)) : y \in X\})$ is precisely the center-unstable manifold $W^{cu}(\hat{q}^{-1}(x, \xi)) \subset SX$ for the geodesic flow ϕ_t on \tilde{M} .

Let V^{cs} be the C^∞ foliation of SM whose leaves for $v \in SM$ are the manifolds $V^{cs}(v) = q^{-1} \circ f([X \times v(\infty)])$, where square brackets denote the $\hat{\rho}$ -equivalence class. Note similarly that the center-stable foliation W^{cs} on SM for the locally symmetric metric has leaves $W^{cs}(v) = q^{-1}([X \times v(\infty)])$ where square brackets denote the $\hat{\rho}_0$ -equivalence class.

Intersecting $V^{cs} \cap W^{cu}$ gives a C^∞ one-dimensional foliation \mathcal{F} which is C^1 -close to the locally symmetric geodesic foliation. Note that for all y in the geodesic line through x and ξ , $\sigma_y \circ \sigma_x(\xi) = \xi$. Hence the foliation \mathcal{F} is the image under $q^{-1} \circ f$ of the quotient by $\hat{\rho}$ of the symmetric geodesic foliation (of the first factor) in $X \times \partial X$.

Using the locally symmetric metric, we obtain a norm on the tangent space to \mathcal{F} from which we may construct a unit vector field Y on SM tangent to these curves. By structural stability, the field Y defines a smooth Anosov flow ψ_t which is Hölder orbit equivalent to the locally symmetric flow ϕ_t . (Note that by invariance of V^{cs} and W^{cu} , and the fact that ψ_t is C^1 -close to ϕ_t , it follows that V^{cs} and W^{cu} are the center-stable and center-unstable foliations for ψ_t .)

THEOREM 1.16. *Let X be a quaternionic hyperbolic space or the Cayley plane, and let $M = X/\Gamma$ for a cocompact lattice $\Gamma < \text{Isom}(X)$. Let $\rho : \Gamma \rightarrow \text{Diff}^\infty(\partial X)$ be a C^1 -close perturbation of ρ_0 which still preserves a C^∞ distribution E nearby to E_0 . Then ρ is C^∞ conjugate to ρ_0 .*

Proof. Consider the slow distribution E_{slow}^u for ψ_t . Since V^{cs} is C^∞ , the center-stable holonomy is C^∞ . Moreover, $E_{\text{slow}}^u \subset V^u$ is holonomy invariant (e.g. by [FK90, Lemma 4]; cf. [CNS20, Lemma 5.5]). Since ϕ_t has a dominated splitting on W^u and is C^1 -close to ψ_t , the latter flow also admits a dominated splitting of $V^u \subset W^{cu}$ and $E_{\text{slow}}^u \subset V^u$ is also continuous. In what follows let $\psi_t^{\rho_0}$ denote the flow on $(X \times \partial X)/\hat{\rho}_0$ given by pulling back ψ_t under q^{-1} . Similarly, let ψ_t^ρ denote the flow on $(X \times \partial X)/\hat{\rho}$ given by pulling back $\psi_t^{\rho_0}$ under f .

It is easier to understand the center-stable holonomy using ψ_t^ρ instead of ψ_t . The center-stable leaves on $(X \times \partial X)/\hat{\rho}$ are quotients of leaves of form $X \times \{b\}$, for $b \in \partial X$.

The center-stable holonomy on the cover $X \times \partial X$ of $(X \times \partial X)/\widehat{\rho}$ is the map preserving the second component in ∂X . There is also a smooth map from each stable leaf in $X \times \partial X$ into ∂X by projecting to the second factor. This map is invariant under center-stable holonomy and ψ_t^ρ . It follows that $df^{-1} \circ q(E_{\text{slow}}^u)$ projects to a well-defined and smooth distribution on ∂X . Consequently, we get a distribution on ∂X that is C^1 -close to E and invariant under $\rho(\Gamma)$. Inverses of projections from the boundary ∂X onto unstable leaves maps E to a subdistribution of E^u that is C^1 -close to $df^{-1} \circ q(E_{\text{slow}}^u)$ and is invariant under the flow ψ_t^ρ . Thus these two distributions coincide. It follows that $df^{-1} \circ q(E_{\text{slow}}^u)$ projects to E under the projection onto the second factor ∂X . Since E is C^∞ and is C^1 -close to E_0 , we have that E_{slow}^u is horizontal and generic everywhere. By Theorem 3.2, we therefore have a tangent cone at each point of the leaves of V^{cs} and this is a perturbation of the quaternionic or octonionic Heisenberg group by Corollary 4.6. The corresponding nilpotent group is asymmetric by Corollary 2.10. Finally, by Proposition 3.12, the Lyapunov exponents all have ratio two.

By [But19, Theorem 3.6], the flow ψ_t is C^∞ orbit equivalent to the flow ϕ_t by a diffeomorphism $G : SM \rightarrow SM$. We lift G to the universal covers and conjugate by \widehat{q} to obtain a diffeomorphism $\widehat{G} : X \times \partial X \rightarrow X \times \partial X$ which intertwines $(q^{-1})^* \phi_t$ and ψ_t^ρ as well as their corresponding center-stable foliations whose leaves are of the form $X \times \{b\}$ for $b \in \partial X$. Thus \widehat{G} induces a well-defined diffeomorphism from ∂X to ∂X that intertwines the ρ_0 and ρ actions. In other words, the perturbed Γ -action is smoothly conjugate to the original Γ -action. \square

6. Local hyperbolic rank rigidity

In this section we prove the local rigidity results of Theorems 1.14–1.16. We first show in §6.1 that perturbations of locally symmetric metrics with higher hyperbolic rank have the same hyperbolic rank as the locally symmetric metric. This is a key step for Theorem 1.14, whose proof we provide in §6.2.

We begin by recalling some facts from [CNS20] about hyperbolic rank.

LEMMA 6.1. *Suppose M is a closed Riemannian manifold of hyperbolic rank k and with sectional curvatures $0 > \kappa \geq -1$. Let $\widehat{\mathcal{E}}(v) \subset v^\perp$ be the subspace consisting of initial vectors w of unstable Jacobi fields of the form $t \mapsto e^t \|_{\phi^t v} w$.*

- (1) *$\widehat{\mathcal{E}}(v)$ is of dimension at least k for every v , by definition.*
- (2) *The set $\widehat{\mathcal{R}} \subset SM$ where $\widehat{\mathcal{E}}(v)$ is of constant dimension k is open and dense by [CNS20, Lemma 2.4].*
- (3) *The map $v \mapsto \widehat{\mathcal{E}}(v)$ is C^∞ on $\widehat{\mathcal{R}}$ by [CNS20, Proposition 3.3].*
- (4) *The lift $E_1^u(v)$ of $\widehat{\mathcal{E}}(v)$ to $T_v W^u(v) = E^u(v) \subset TSM$ is a distribution on $\widehat{\mathcal{R}}$ which is uniformly C^∞ along W^u restricted to $\widehat{\mathcal{R}}$ which consists precisely of the Lyapunov spaces in E^u of exponent 1, by [CNS20, Lemma 4.2]. (We will sometimes refer to the $E_1^u(v)$ space as $E_{\text{fast}}^u(v)$.)*
- (5) *Denote by $\widehat{\mathcal{E}}(v)^\perp$ the orthogonal complement of $\widehat{\mathcal{E}}(v)$ within v^\perp with respect to the Sasaki metric. The lift $E_{<1}^u$ of $\widehat{\mathcal{E}}^\perp$ to E^u is the direct sum of unstable Lyapunov spaces of exponents different from 1, by [CNS20, Lemma 4.3]. (We will sometimes refer to the $E_{<1}^u(v)$ space as $E_{\text{slow}}^u(v)$.)*

We remark that $E_{<1}^u$ is uniformly C^∞ along W^u restricted to $\widehat{\mathcal{R}}$ since it is orthogonal to E_1^u in E^u .

6.1. Holonomy groups of perturbations and hyperbolic rank. The goal of this subsection is to prove the following proposition and its Corollary 6.10.

PROPOSITION 6.2. *Let (M, g_0) be a closed complex, quaternionic or octonionic hyperbolic locally symmetric manifold. Then there is an open C^2 neighborhood U of g_0 such that, for any $g \in U$, if (M, g) has higher hyperbolic rank and $\kappa_g \geq -1$ then (M, g) has hyperbolic rank at least 1, 3 or 7, respectively.*

The proof of this proposition will rely on an analysis of the Brin–Pesin asymptotic holonomy group. Before giving the proof we will establish some notation and several lemmas.

Let $FM \rightarrow SM$ denote the full orthonormal frame bundle which is a (right) principal $\mathrm{SO}(n-1)$ bundle over SM . Let F_2M denote the 2-frame bundle over SM which is a fiberwise quotient of FM by $\mathrm{SO}(n-2)$ acting on the right, that is, we have bundle quotient maps

$$\begin{array}{ccc} FM & \xrightarrow{\pi_{n \rightarrow 2}} & F_2M = FM/\mathrm{SO}(n-2) \\ & \searrow \pi_{n \rightarrow 1} & \downarrow \pi_{2 \rightarrow 1} \\ & & SM = FM/\mathrm{SO}(n-1) \end{array}$$

We endow FM and F_2M with the natural extensions of the Liouville measure by the Haar measures on the fiber. These measures are invariant under their respective frame flows. The k -frame flows commute with the corresponding right action of $\mathrm{SO}(n-1)$ on F_kM . Consider the ergodic component $\mathcal{E}(v, w)$ of the 2-frame flow containing (v, w) with respect to this measure. Moreover, assume (v, w) is a generic 2-frame in the ergodic component $\mathcal{E}(v, w)$. (This means that time averages over the orbit of (v, w) coincide with the space average over $\mathcal{E}(v, w)$ with respect to its ergodic measure.) Without loss of generality we may assume (v, w) is the first two vectors of a full frame f which is also generic in its ergodic component $\mathcal{E}(f) \subset FM$ for the full frame flow. Lemmas 5.1 (see the formulation of the ergodic component $Q(\omega)$ in the proof) and 5.2 of Brin [Bri82] show that

$$\mathcal{E}(f) = \overline{\bigcup_{t \in \mathbb{R}} \Phi_t(C(f))}$$

where $C(f)$ is the smallest set saturated by entire leaves of W_f^s , W_f^u and containing f . Moreover, there is a compact subgroup $B_f^\infty < \mathrm{SO}(n-1)$, called the *ergodic component group*, satisfying

$$\mathcal{E}(f) \cap \pi_{n \rightarrow 1}^{-1}(v) = f \cdot B_f^\infty.$$

This immediately implies that

$$\begin{aligned}\mathcal{E}(v, w) \cap \pi_{2 \rightarrow 1}^{-1}(v) &= \pi_{n \rightarrow 2}(\mathcal{E}(f)) \cap \pi_{2 \rightarrow 1}^{-1}(v) \\ &= \pi_{n \rightarrow 2}(f \cdot B_f^\infty) \cap \pi_{2 \rightarrow 1}^{-1}(v) = f \cdot B_f^\infty \text{SO}(n-2).\end{aligned}$$

It is clear that if $f' = f \cdot h$ for $h \in \text{SO}(n-1)$ then $B_{f'}^\infty = h^{-1} B_f^\infty h$. And by definition if f and f' are in the same ergodic component, then $B_f^\infty = B_{f'}^\infty$. We call B_f^∞ the *(Brin-Pesin) asymptotic holonomy group*, and denote its conjugacy class in $\text{SO}(n-1)$ by B^∞ .

Suppose $v \in SM$ and $v' \in W_{\phi_t}^s(v)$. Fix $k \in \{2, \dots, n\}$ and let $p(v, v')$ be the map from the fiber of the k -frame bundle, $F_k M$, over v to the fiber over v' that takes each frame f to $p(v, v')(f) = \pi_{k \rightarrow 1}^{-1}(v') \cap W_{\Phi_t}^s(f)$. The map $p(v, v')$ corresponds to a unique isometry between v^\perp and v'^\perp which commutes with the right action of $\text{SO}(n-1)$. We will mainly consider the case of the map for $k = 2$. After lifting to the universal cover, one can think of $p(v, v')(f)$ as the result of ‘parallel transporting’ f along $\gamma_v(t)$ out to the boundary at infinity of \tilde{M} and then back to v' along $\gamma_{v'}(t)$.

Similarly, when v' and v belong to the same leaf of $W_{\phi_t}^u$, there is a map $p(v, v')(f) = \pi_{k \rightarrow 1}^{-1}(v') \cap W_{\Phi_t}^u(f)$. Following Brin (see [Bri82, Definition 4.4]) we define the transitivity group at v as follows.

Definition 6.3. Given any sequence $\sigma = \{v_0, v_1, \dots, v_k\}$ with $v_0 = v, v_k = \phi_T(v)$ for some $T \in \mathbb{R}$ such that each pair $\{v_i, v_{i+1}\}$ lies on the same leaf of $W_{\phi_t}^s$ or $W_{\phi_t}^u$, we have an isometry of v^\perp given by

$$I(\sigma, T) = \Phi_{-T} \circ \prod_{i=0}^r p(v_i, v_{i+1}).$$

The closure of the group generated by all such isometries with $v_0 = v$ is denoted by $H_v < \text{Isom}(v^\perp)$ and is called the *transitivity group*.

After picking an orthonormal full frame f with v as its first vector, H_v can be identified as a subgroup of $\text{SO}(n-1)$. This identification depends on the choice of frame f . Different choices give conjugate identifications. It is well known that the ergodic component group $B_f^\infty < \text{SO}(n-1)$ at a frame f over v coincides with the transitivity group H_v under this identification (see the remark before Lemma 5.2, or Remark 2 of [Bri75a] and Proposition 2 of [Bri75b]). For clarity, we provide the details of this equivalence below.

LEMMA 6.4. *For each $k \in \{2, \dots, n\}$, the ergodic component group coincides with the transitivity group at each $v \in SM$ and $f \in \pi_{k \rightarrow 1}^{-1}(v)$, that is, $B_f^\infty = H_v$, using the identification provided by the frame f .*

Proof. Fix $v \in SM$, and consider any continuous function α on the homogeneous space $\pi_{k \rightarrow 1}^{-1}(v)/H_v$. Lift α to a function $\bar{\alpha} : \pi_{k \rightarrow 1}^{-1}(v) \rightarrow \mathbb{R}$. Using the maps $p(v, v')$ for $v \in SM$, we obtain a continuous extension $\hat{\alpha} : F_k M \rightarrow \mathbb{R}$ given by $\hat{\alpha}(f') = \bar{\alpha}(p(v', v)(f'))$ for any $f' \in \pi_{k \rightarrow 1}^{-1}(v')$. Observe that $\hat{\alpha}$ is well defined and invariant under both the action of H_v and the frame flow. Since continuous functions on $\pi_{k \rightarrow 1}^{-1}(v)/H_v$ separate points,

and continuous flow invariant functions on $F_k M$ are constant on ergodic components, we obtain a surjection from the space of ergodic components to $\pi_{k \rightarrow 1}^{-1}(v)/H_v$. Therefore, $B_f^\infty < H_v$ for any $f \in \pi_{k \rightarrow 1}^{-1}(v)$. On the other hand, as explained in [Bri75a, Remark 2], we also have $H_v < B_f^\infty$. \square

Remark 6.5. Note that the entire formulation of the ergodic component groups, asymptotic holonomy groups and transitivity groups makes sense in the broader context of compact (isometric) group extensions of Anosov flows. Moreover, the above lemma also holds (see [Bri75b]).

For the next lemma, recall that an ϵ -net $F \subset X$ of a metric space X is a subset whose points are pairwise separated with distance at least ϵ , and such that every point $x \in X$ is at distance at most ϵ to a point of F .

LEMMA 6.6. *For any connected semisimple Lie subgroup $K < \mathrm{SO}(n - 1)$, let $F \subset K$ be a δ -net of K that generates a dense subgroup of K . There is a sufficiently small $\epsilon_0 > 0$ such that for any $\epsilon < \epsilon_0$ every ϵ -perturbation of F generates a subgroup of $\mathrm{SO}(n - 1)$ whose closure contains a conjugate $h_\epsilon K h_\epsilon^{-1}$ of K . Moreover, h_ϵ can be chosen so that $h_\epsilon \rightarrow e$ as $\epsilon \rightarrow 0$.*

Proof. First suppose there is no such ϵ_0 . Then there is a sequence $\epsilon_n \rightarrow 0$ and an ϵ_n -perturbation $F_{\epsilon_n} \subset \mathrm{SO}(n - 1)$ of F , with respect to the Hausdorff metric on closed subsets, such that the closure of the group generated by F_{ϵ_n} does not contain a conjugate of K . Let $H_n = \overline{\langle F_{\epsilon_n} \rangle}^0$ be the identity component of the closure of the group generated by F_{ϵ_n} . Consider the Levi decomposition of the connected Lie group H_n , namely $H_n = H_n^{ss} H_n^a$ where H_n^{ss} is maximal semisimple and H_n^a is a closed connected solvable normal subgroup (see [Var84, Theorem 3.18.13] and [Gor94, Theorem 1.4.3]). Since H_n^a is compact connected and solvable, it is an abelian torus. The automorphism group of this torus is discrete. Since H_n is connected the image of the conjugation action $H_n \rightarrow \mathrm{Aut}(H_n^a)$ is trivial. Note also that $H_n^{ss} \cap H_n^a$ is semisimple and therefore trivial. This implies that H_n is a group product of H_n^{ss} and H_n^a .

Since the topology induced by the Hausdorff metric on compact subsets of a compact space is compact, we may pass to a subsequence such that H_n converges to $H = \lim_n H_n$. Let $H^{ss} = \lim_n H_n^{ss}$ and $H^a = \lim_n H_n^a$. The limit of abelian groups is abelian so H^a is abelian. Hence $H = H^{ss} H^a$ since the limit of a product is a product. Since the generators converge, H therefore contains $\overline{\langle F \rangle}^0$, but this is just K . The projection of K to H^a is trivial since K is semisimple and H^a is connected, and hence H^{ss} contains K .

There are only finitely many conjugacy classes of connected semisimple subgroups of $\mathrm{SO}(n - 1)$. For each n the corresponding connected semisimple group H_n^{ss} must belong to one of these. Since H^{ss} contains K , the groups H_n^{ss} must eventually belong to the same conjugacy class, also containing H^{ss} . Therefore for all sufficiently large n , the group H_n^{ss} must contain a conjugate of K . This contradiction establishes the existence of ϵ_0 .

Moreover, we have shown that for every $\epsilon < \epsilon_0$, if F_ϵ is an ϵ -perturbation of F generating a subgroup with closure $H_\epsilon < \mathrm{SO}(n - 1)$, then $H_\epsilon^{ss} = h_\epsilon Q_\epsilon h_\epsilon^{-1}$ for a compact semisimple group Q_ϵ containing K and belonging to one of finitely many conjugacy

classes. In particular, $h_\epsilon K h_\epsilon^{-1} < H_\epsilon^{ss}$. Moreover, Q_ϵ is close to H_ϵ^{ss} as $\epsilon \rightarrow 0$, and so we may assume we have chosen h_ϵ so that $h_\epsilon \rightarrow e$ as $\epsilon \rightarrow 0$. \square

Given two Riemannian metrics $g, g' \in \text{Sym}(T^*M \otimes T^*M)$, there is a unique positive-definite vector bundle endomorphism A of TM such that $g'_x(v, w) = g_x(A_x v, w)$ at each point $x \in M$. Let $q : TM \rightarrow TM$ be the bundle endomorphism $q := A^{-\frac{1}{2}}$. If f is a g -orthonormal frame then $q(f)$ is a g' -orthonormal frame. Thus q defines a smooth $\text{SO}(n)$ -equivariant map of g -orthonormal frames to g' -orthonormal frames. In other words, q induces a principal $\text{SO}(n)$ -bundle isomorphism $q^F : (FM)_g \rightarrow (FM)_{g'}$ (see [BG92, Proposition 1]).

Now consider a C^2 perturbation g_ϵ through C^∞ metrics of a negatively curved metric g_0 . As indicated above, there is a vector bundle isomorphism $q_\epsilon : TM \rightarrow TM$ which restricts to a fiber bundle isomorphism $q_\epsilon : (SM)_\epsilon \rightarrow (SM)_0$ between the unit tangent bundle $(SM)_\epsilon \rightarrow M$ for the metric g_ϵ and $(SM)_0 \rightarrow M$ for the metric g_0 . Moreover, we have a principal $\text{SO}(n)$ -bundle isomorphism $q_\epsilon^F : (FM)_\epsilon \rightarrow (FM)_0$ between the orthonormal frame bundles $(FM)_\epsilon \rightarrow (SM)_\epsilon$ and $(FM)_0 \rightarrow (SM)_0$ which fibers over q_ϵ . We may conjugate the geodesic flow ϕ_t^ϵ for g_ϵ by q_ϵ to obtain a flow $\widehat{\phi}_t^\epsilon : (SM)_0 \rightarrow (SM)_0$. Similarly, we may conjugate the frame flow Φ_t^ϵ for g_ϵ by q_ϵ^F to obtain a flow $\widehat{\Phi}_t^\epsilon : FM \rightarrow FM$ which extends $\widehat{\phi}_t^\epsilon$.

Using Remark 6.5, we may consider the transitivity group $H_v^\epsilon < \text{Isom}(v^\perp)$ for the flow $\widehat{\Phi}_t^\epsilon$. Also, since the map q_ϵ^F is equivariant with respect to the right $\text{SO}(n)$ action, the asymptotic holonomy group for Φ_t^ϵ is the same as B_ϵ^∞ up to conjugacy.

LEMMA 6.7. *Let g_ϵ be a C^2 perturbation through C^∞ metrics of a negatively curved metric g_0 . Let H_v^ϵ be the transitivity group of a vector v for the metric g_ϵ , and suppose transitivity group H_v^0 for g_0 is connected and semisimple. Then for all sufficiently small ϵ , H_v^ϵ contains a conjugate of H_v^0 which limits to H_v^0 as $\epsilon \rightarrow 0$.*

Proof. In order to show there is a relation between H_v^ϵ for different ϵ , we use the description of the transitivity group. Namely, we may construct a net of elements in H_v^ϵ by following a sequence of paths along leaves of $W_{\widehat{\Phi}_t^\epsilon}^u$ and $W_{\widehat{\Phi}_t^\epsilon}^s$ starting from v which lie in a compact set. By the permanence theorem [HPS77, Theorem 6.8], the unstable and stable manifolds for $\widehat{\Phi}_t^\epsilon$, as a compact extension of $\widehat{\phi}_t^\epsilon$ on $(SM)_0$, vary continuously in the C^1 topology under C^2 perturbations. As these manifolds converge on compacta, using sufficiently long u - s paths, we obtain for any $\epsilon > 0$ an ϵ -net in H_v^ϵ that is ϵ -close to an ϵ -net in H_v^0 .

By assumption, the transitivity group H_v^0 is connected and semisimple. Consequently, by Lemma 6.6, the transitivity group H_v^ϵ contains a conjugate of H_v^0 for sufficiently small perturbation parameter $\epsilon > 0$, and these subgroups converge to H_v^0 as $\epsilon \rightarrow 0$. \square

The following lemma can be found in [Con08]; we provide a short proof for convenience. We say that a 2-frame (u, w) has *higher hyperbolic rank* if the sectional curvatures satisfy $\kappa(\phi_t(u) \wedge \|_t w) \equiv -1$ for all $t \in \mathbb{R}$ where $\|_t$ is parallel translation along $\phi_t(u)$.

LEMMA 6.8. *For a flow-invariant, full Liouville-measure subset of $v \in SM$, H_v sends higher hyperbolic rank 2-frames over v to higher hyperbolic rank 2-frames over v .*

Proof. The set of 2-frames (u, w) of higher hyperbolic rank remains invariant under parallel transport. Any 2-frame (u', w') forward asymptotic to the parallel frame field of (u, w) must therefore also have curvature limiting to -1 . If (u', w') is recurrent then (u', w') must have higher hyperbolic rank. If (u'', w'') forward limiting to the parallel frame field of $(-u', w')$ is recurrent then it must similarly have higher hyperbolic rank. If the frame $(-u, \rho w)$ for $\rho \in H_u < \text{Isom}(u^\perp)$ which forward limits to (u'', w'') is recurrent then it has higher hyperbolic rank as well. Finally, the set of bi-recurrent vectors is a flow-invariant full Liouville measure set. \square

The following lemma is trivial, but we include it for completeness.

LEMMA 6.9. *If a sequence of subgroups $K_n < \text{SO}(n)$ converges to $K < \text{SO}(n)$, and a sequence of vectors v_n converges to a vector v , then the stabilizers in K_n of vectors v_n , $\text{Stab}_{\text{SO}(n)}(v_n) \cap K_n$, converge to a subgroup of $\text{Stab}_{\text{SO}(n)}(v) \cap K$.*

Proof. If $k_n \in \text{Stab}_{\text{SO}(n)}(v_n) \cap K_n$ converges to $k \in K$, then clearly $k \in \text{Stab}_{\text{SO}(n)}(v)$. \square

Before proving Proposition 6.2, we describe the Brin–Pesin groups and their actions in the locally symmetric case.

Let (M, g_0) be a closed complex, quaternionic or octonionic hyperbolic locally symmetric manifold. Hence $M = \Gamma \backslash \tilde{M}$ for a cocompact lattice $\Gamma < G := \text{Isom}^0(\tilde{M}, g_0)$, and let $K_x < G$ be the stabilizer of a point x and $L_v < K_x$ the stabilizer of a tangent vector $v \in T_x M$. Observe that the left action of G on the full (oriented) orthonormal frame bundle decomposes $(F\tilde{M})_{g_0}$ into G -orbits, which descend to closed subsets of $(FM)_{g_0}$ since G acts cocompactly on $(F\tilde{M})_{g_0}$. Since the frame flow corresponds to a right action by the one-parameter split Cartan subgroup, by Moore’s theorem [Zim84, Theorem 2.2.6] the quotients of the G orbits by Γ coincide with the ergodic components of the frame flow on $(FM)_{g_0}$ for the lift of the Liouville measure. Since the intersection of the fiber over v with a G orbit coincides with the action of the stabilizer L_v , which is faithful on frames, we have $H_v = L_v$.

For the quaternionic hyperbolic space $\tilde{M} = \mathbb{H}_{\mathbb{H}}^n$ we have $H_v = L_v \cong B^\infty = \text{Sp}(n-1)\text{Sp}(1)$ (here $\text{Sp}(k) := \text{Sp}(2k, \mathbb{C}) \cap U(2k)$), and for the Cayley plane $\tilde{M} = \mathbb{H}_{\mathbb{O}}^2$ we have $H_v = L_v \cong B^\infty = \text{Spin}(8)\text{Spin}(1)$. Quaternionic symmetric space comes endowed with a quaternionic Kähler structure and the Cayley plane with an octonionic Kähler structure (see, for example, [Bes87]). These structures are parallel and thus preserved under the full holonomy group. Thus each higher hyperbolic rank 2-frame is fixed by $\text{Sp}(n-1)$ and $\text{Spin}(8)$, respectively. However, the set of all such frames is acted on transitively by the $\text{Sp}(1)$ and $\text{Spin}(1)$ groups of dimension 3 and 7 respectively, since these groups act transitively on the perpendicular to v in the \mathbb{H} -line (respectively, \mathbb{O} -line) through v .

Proof of Proposition 6.2. By the hyperbolic rank condition, the statement for the complex hyperbolic case is trivial. We proceed by contradiction and suppose there is a sequence of metrics g_{ϵ_n} of higher hyperbolic rank with $\|g_{\epsilon_n} - g_0\|_{C^2} < \epsilon_n$ where ϵ_n tends to 0, but whose hyperbolic ranks are all less than the hyperbolic rank of g_0 .

By Lemma 6.8, for almost every $v \in SM$, $H_{\epsilon_n, v}$ preserves the hyperbolic rank 2-frames over v . Consider a sequence of generic 2-frames (v_n, w_n) for g_{ϵ_n} that limit to a hyperbolic

2-frame (v, w) for g_0 . By Lemma 6.7, if ϵ_n is sufficiently small, the asymptotic holonomy group H_{ϵ_n, v_n} for the perturbed metric g_{ϵ_n} contains a conjugate copy L_{ϵ_n} of H_v , and these converge to H_v as $\epsilon_n \rightarrow 0$. Let $Q_{\epsilon_n} < L_{\epsilon_n}$ be the stabilizers in L_{ϵ_n} of (v_n, w_n) . By Lemma 6.9, Q_{ϵ_n} converges to a subgroup of a conjugate of $\mathrm{Sp}(n-1)$ or $\mathrm{Spin}(8)$, respectively. Hence if ϵ_n is sufficiently small and (v_n, w_n) is chosen to be a hyperbolic 2-frame for g_{ϵ_n} then the L_{ϵ_n} -orbit of (v_n, w_n) , consisting of hyperbolic 2-frames, has dimension at least as large as the dimension of the H_v -orbit of (v, w) . This contradicts the assumption that hyperbolic ranks of g_{ϵ_n} are less than that of g_0 . \square

COROLLARY 6.10. *Let (M, g_0) be a closed complex, quaternionic or octonionic hyperbolic locally symmetric manifold. Then there is an open C^2 neighborhood U of g_0 such that, for any $g \in U$, if (M, g) has higher hyperbolic rank and $\kappa_g \geq -1$ then the hyperbolic rank of every tangent vector to (M, g) is exactly 1, 3 or 7, respectively.*

Proof. If v is a unit tangent vector of (M, g_0) then $v^{\perp_{g_0}} = \widehat{\mathcal{E}}_{g_0}(v) \oplus \widehat{\mathcal{E}}_{g_0}(v)^{\perp_{g_0}}$, where the sectional curvature $\kappa(v \wedge w) = -1$ for every $w \in \widehat{\mathcal{E}}_{g_0}(v)$ and $\kappa(v \wedge u) = -\frac{1}{4}$ for every $u \in \widehat{\mathcal{E}}_{g_0}(v)^{\perp_{g_0}}$.

Similarly, if v is a unit tangent vector of (M, g) , we also have $v^{\perp_g} = \widehat{\mathcal{E}}_g(v) \oplus \widehat{\mathcal{E}}_g(v)^{\perp_g}$, where the sectional curvature $\kappa(v \wedge w) = -1$ for every $w \in \widehat{\mathcal{E}}_g(v)$. Since g is sufficiently C^2 -close to g_0 , the continuity of curvatures in the C^2 topology of Riemannian metrics implies that $\dim(\widehat{\mathcal{E}}_g(v)) \leq \dim(\widehat{\mathcal{E}}_{g_0}(v))$ for every v . In particular, the hyperbolic rank of every tangent vector of (M, g) is at most the hyperbolic rank of (M, g_0) .

On the other hand, by Proposition 6.2, the hyperbolic rank of (M, g) is not smaller than the hyperbolic rank of (M, g_0) . By item (1) of Lemma 6.1, the hyperbolic rank of every tangent vector of (M, g) is exactly the hyperbolic rank of (M, g_0) . \square

6.2. Quaternionic and octonionic hyperbolic local rigidity. We are now ready to prove the main result about higher hyperbolic rank stated in the introduction.

THEOREM 1.14. *Let (M, g_0) be a closed quaternion or octonionic hyperbolic locally symmetric manifold. Then there is an open C^3 neighborhood U of g_0 such that, for any $g \in U$, if (M, g) has higher hyperbolic rank and $\kappa_g \geq -1$ then (M, g) is locally symmetric and isometric to (M, g_0) .*

Proof of Theorem 1.14. By Corollary 6.10, we may choose U such that the hyperbolic rank of every tangent vector of (M, g) is the same as the hyperbolic rank of (M, g_0) .

Next, let $J_\xi(t)$ denote the unstable Jacobi field along $\phi_t(v)$ with initial vector $\xi \in \widehat{\mathcal{E}}(v)$. By Lemma 6.1, we can make the following observations about Oseledets spaces:

$$E_1^u(v) = \{(\xi, J'_\xi(0)) : \xi \in \widehat{\mathcal{E}}(v)\} \quad \text{and} \quad E_{\text{slow}}^u(v) = \{(\xi, J'_\xi(0)) : \xi \in \widehat{\mathcal{E}}(v)^\perp\}.$$

By Corollary 6.10, $\dim E_1^u$ is constant, and by Lemma 6.1, E_1^u is a globally C^∞ distribution on SM . In particular, E_1^u is uniformly C^∞ along W^u for each such metric g . Moreover, as the curvature operator, and hence Jacobi fields, vary C^1 in the C^3 topology on smooth metrics, E_1^u and its first derivatives along W^u vary continuously in the metric parameter with respect to the C^3 topology on smooth metrics. By [CNS20, Lemma 4.3], E_1^u and E_{slow}^u

are perpendicular with respect to the Sasaki metric for g . Hence the dominated splitting $E^u = E_1^u \oplus E_{\text{slow}}^u$ is uniformly C^∞ along unstable leaves. By the permanence theorem [HPS77, Theorem 6.8], E_{slow}^u has C^1 dependency on g as g varies in the C^3 topology. Therefore by Theorem 1.9, M is symmetric for sufficiently C^3 nearby smooth metrics. \square

Remark 6.11. One can show that E_1^u varies continuously in the C^1 topology as the metric g varies in the C^2 topology. However, since E^u may not vary continuously in the C^1 topology as the metric g varies in the C^2 topology, we are not able to conclude that E_{slow}^u varies C^1 in this topology. The latter is necessary to obtain the isomorphism of tangent cones. Hence we require the metrics to be C^3 -close.

We next observe that the higher hyperbolic rank condition in the last theorem may be replaced by a condition on Lyapunov exponents.

COROLLARY 6.12. *In Theorem 1.14, the conclusion still holds if the higher hyperbolic rank assumption is replaced with the assumption that some ergodic measure of full support has a Lyapunov exponent equal to 1.*

This follows from the following lemma, whose proof is essentially that of [CNS20, Corollary 1.4]. (See also [Con03, Theorem 1.3] for the case $\kappa \leq -1$.)

LEMMA 6.13. *Let M be a closed Riemannian manifold with $\kappa \geq -1$. If, with respect to the geodesic flow on SM , some ergodic measure of full support has a Lyapunov exponent equal to 1, then M has higher hyperbolic rank.*

6.3. Measure of maximal entropy for perturbations. For the case of complex hyperbolic metrics, we are not able to obtain full local rigidity. Indeed, our methods require that the tangent cones of unstable leaves are asymmetric, which the Heisenberg group is not. However, we still obtain equality of the Liouville measure and the Bowen–Margulis measure (the unique measure of maximal entropy) for a higher-rank perturbation. The precise result of this subsection is Theorem 1.15 from the introduction.

THEOREM 1.15. *Let (M, g_0) be a closed complex hyperbolic manifold. There is an open neighborhood U of g_0 in the C^3 topology among C^∞ metrics such that if $g \in U$ and (M, g) has higher hyperbolic rank and sectional curvature $\kappa \geq -1$ then the Liouville measure on SM coincides with the (unique) measure of maximal entropy for the geodesic flow of g on SM .*

Proof. We first show that the tangent cone $TC_v W^u(v)$ exists for every $v \in SM$.

By Corollary 6.10, $E_1^u \subset E^u$ is one-dimensional everywhere. By (4) of Lemma 6.1, E_1^u forms a smooth distribution along each leaf of the foliation W^u . By (5) of Lemma 6.1, the lift $E_{\text{slow}}^u = E_{<1}^u$ of $\widehat{\mathcal{E}}^\perp$ to E^u is the direct sum of unstable Lyapunov spaces of exponents different from one. Therefore, E_{slow}^u is uniformly C^∞ along W^u since it is orthogonal to E_1^u in E^u with respect to the Sasaki metric.

By the same argument used in the proof of Theorem 1.14, E_{slow}^u has C^1 dependency on g as g varies in the C^3 topology. In particular, E_{slow}^u is generic everywhere on SM . Also, by Theorem 3.2, the tangent cone $TC_v W_g^u$ exists everywhere.

By Corollary 6.10, the horizontal distribution of $TC_v W_g^u(v)$ has codimension one. Hence $TC_v W_g^u(v)$ is a 2-step Carnot nilpotent Lie group with one-dimensional center for every $v \in SM$. By Lemma 5.5, $TC_v W_g^u(v)$ depends continuously on the metric g in the C^3 topology. Recall that the Lie bracket induces a bilinear form $[\cdot, \cdot] : \mathfrak{n}_v^0 \times \mathfrak{n}_v^0 \rightarrow \mathfrak{n}_v^1$ between the first and second levels \mathfrak{n}_v^0 and \mathfrak{n}_v^1 of the Lie algebra \mathfrak{n}_v of $TC_v W_g^u(v)$. As it is non-degenerate for g_0 , it will also be non-degenerate for g sufficiently close to g_0 . Consequently, as the center is one-dimensional and there is only one, up to isomorphism, non-degenerate skew symmetric bilinear form on \mathfrak{n}_v^0 for every $v \in SM$, $TC_v W^u(v)$ is isomorphic as a graded nilpotent group to the Heisenberg group H^{2k-1} where $\dim M = 2k$.

By Theorem 1.3, if $v \in SM$ is a periodic vector then the sum of the positive Lyapunov exponents (with multiplicity) at v is k . By [Kal11, Theorem 1.4], it follows that with respect to any ergodic invariant probability measure, the entropy of geodesic flow is bounded above by k . On the other hand, by Pesin's entropy formula, the entropy of the geodesic flow with respect to Liouville measure (rescaled to have total volume one) is k . Therefore the (rescaled) Liouville measure is the measure of maximal entropy. \square

Remark 6.14. Local rigidity for higher hyperbolic rank metrics near the complex hyperbolic one would follow from Katok's well-known entropy conjecture stating that the Liouville measure has maximal entropy precisely for locally symmetric manifolds among closed negatively curved manifolds. Alternately, and possibly more simply, it would follow from strict convexity of the difference of topological and measure-theoretic entropy near the complex hyperbolic metric. For real hyperbolic metrics, this was proven by Flaminio [Fla95, Theorem A].

Remark 6.15. As in Corollary 6.12, we may replace the condition on higher hyperbolic rank in Theorem 1.15 with the condition that there is a Lyapunov exponent equal to 1 for some invariant ergodic measure of full support.

Acknowledgments. We thank Boris Kalinin, Karin Melnick and Victoria Sadovskaya for discussions about normal forms, Jeremy Tyson and Anton Lukyanenko for discussions on Carnot–Carathéodory metrics, Boris Hasselblatt and Kurt Vinhage for discussions on the regularity of distributions, Livio Flaminio for discussions on local entropy rigidity for complex hyperbolic space, Tracy Payne for discussions on nilmanifolds and in particular for pointing us to the Lauret examples, and finally Clark Butler for discussions on Lyapunov exponent rigidity. We thank the Departments of Mathematics at Indiana University and the University of Michigan for their hospitality while parts of this work were completed. This work was supported in part by NSF grants DMS 1607260 and DMS 2003712.

A. Appendix. A variation on Benveniste's lemma

In this appendix we present the proof of the following proposition which may be considered by some to be folklore. However, we could not locate a precise reference for it in the literature. (For the case of C^0 semiconjugacy, see [BM19].) In what follows, if Γ acts by C^k diffeomorphisms on a C^∞ manifold X , and $\tau : \Gamma \rightarrow \text{Diff}^k(F)$ is a representation for

a C^∞ manifold F , then we denote by $\widehat{\tau} : \Gamma \rightarrow \text{Diff}^k(X \times F)$ the representation given by $\widehat{\tau}(\gamma)(x, f) = (\gamma x, \tau(\gamma)(f))$.

PROPOSITION A.1. (Cf. [Ben00, Lemma 5.2]) *Suppose Γ acts freely, properly discontinuously and cocompactly by C^k diffeomorphisms on a C^∞ manifold X for $k \geq 1$. Let F be a closed C^∞ manifold. Let τ_0 and τ be homomorphisms from $\Gamma \rightarrow \text{Diff}^k(F)$ such that τ be C^ℓ -close to τ_0 for $\ell \geq 1$. Then there is C^∞ diffeomorphism between suspensions $f : (X \times F)/\widehat{\tau} \rightarrow (X \times F)/\widehat{\tau}_0$. Moreover, the push-forward by f of the horizontal foliation $\{X \times \{z\} : z \in F\}$ in $(X \times F)/\widehat{\tau}$ is C^ℓ -close to the horizontal foliation in $(X \times F)/\widehat{\tau}_0$.*

Here the map f is C^∞ with respect to the unique compatible C^∞ structures on $(X \times F)/\widehat{\tau}$ and $(X \times F)/\widehat{\tau}_0$ compatible with the respective C^k structures. The above result was proved by Benveniste in the C^∞ case in [Ben00] using the tame Fréchet group structure of $\text{Diff}^\infty(F)$ and the Hamilton–Nash–Moser implicit function theorem. We follow his argument closely. However, even though the Banach manifolds arising in the C^k setting are still tame Fréchet manifolds, $\text{Diff}^k(F)$ is not a tame Fréchet Lie group and we must instead use implicit function theorems for Banach manifolds in Lemma A.2.

LEMMA A.2. *Let \mathcal{X} , \mathcal{Y} , and \mathcal{Z} be Banach manifolds, and $H : \mathcal{X} \rightarrow \mathcal{Y}$ and $G : \mathcal{Y} \rightarrow \mathcal{Z}$ be C^1 maps such that $G \circ H(x) = z_0$ for every $x \in \mathcal{X}$. Suppose that $P : T_{H(x_0)}\mathcal{Y} \rightarrow T_{x_0}\mathcal{X}$ and $Q : T_{z_0}\mathcal{Z} \rightarrow T_{H(x_0)}\mathcal{Y}$ are bounded linear transformations such that $D_{x_0}H \circ P + Q \circ D_{H(x_0)}G = \text{id}$. Then there exist neighborhoods U and V of x_0 and $H(x_0)$ respectively such that $G^{-1}(z_0) \cap V \subset H(U)$.*

Proof. Using local charts, we can assume that \mathcal{X} , \mathcal{Y} , \mathcal{Z} are Banach spaces and $x_0, H(x_0), z_0$ are zero vectors in the Banach spaces. Since $G \circ H = 0$ we have $\text{im } D_0H \subset \ker D_0G$. On the other hand, if there is $v \in \ker D_0G - \text{im } D_0H$, then $v = \text{id}(v) = D_0H \circ P(v) + Q \circ D_0G(v) \in \text{im } D_0H$, which is not possible. Thus, $\text{im } D_0H = \ker D_0G$. Now the conclusion follows immediately from [AN09, Theorem 2.1]. \square

Given closed manifolds M and N , $\text{Diff}^k(M, N)$ is a Banach manifold for every $k \in \mathbb{N}$ [Wit19]. We note that by a Banach manifold we always mean a Banach manifold of class C^∞ .

We also need a discussion about the space of mappings. Let E be a Banach space and let U be a domain in \mathbb{R}^n or in a smooth manifold such that U has smooth boundary. For $\ell \in \mathbb{N}$, we let $C^\ell(U, E)$ denote the space of C^ℓ functions from the closure of U to E . Then $C^\ell(U, E)$ is a Banach space. By [Eli67, Theorem 5.1] (with $\mathfrak{S} = C^k$ and $s = \infty$) and the remark before [Eli67, Theorem 5.2], if D is a smooth Banach manifold admitting a C^∞ connection, then $C^\ell(U, D)$ is a smooth Banach manifold. This condition is satisfied for $D = \text{Diff}^k(F)$. Indeed, the latter is open in $C^k(F, F)$ for $k \geq 1$ by the inverse function theorem and $C^k(F, F)$ satisfies the condition by the discussion at the top of p. 170 in [Eli67]. In particular, $C^\ell(U, \text{Diff}^k(F))$ is a smooth Banach manifold. Moreover, by [Eli67, Theorem 5.2], the tangent bundle to $C^\ell(U, D)$ is naturally isomorphic to $C^\ell(U, TD)$. We note that if $h \in C^\ell(U, \text{Diff}^k(F))$ then the map $U \times F \ni (u, f) \mapsto (u, h(u)(f)) \in U \times F$ is $C^{\min\{\ell, k\}}$.

LEMMA A.3. *Let $F \rightarrow P \rightarrow M$ be a fiber bundle, where F and M are closed manifolds. Let $\{U_1, \dots, U_k\}$ be a cover of M so that $P|_{U_\alpha}$ is trivializable for each α . Let $\{\phi_\alpha\}$ be trivializations, and let $\{\phi_{\alpha\beta}\}$ be the corresponding transition functions. Let $\{\phi'_{\alpha\beta}\}$ be a collection of transition functions which are close to the $\{\phi_{\alpha\beta}\}$ in the C^ℓ topology. Let $V_\alpha \subset U_\alpha$ be compactly contained open sets such that $\{V_\alpha\}$ cover M . Then there are maps $\{h_\alpha : V_\alpha \rightarrow \text{Diff}^k(F)\}$, C^ℓ -close to the constant map to the identity, such that $h_\alpha(u)\phi_{\alpha\beta}(u) = \phi'_{\alpha\beta}(u)h_\beta(u)$ for all $u \in V_\alpha \cap V_\beta$, and all α and β .*

Proof. For each α , we let W_α be an open set with a smooth boundary such that $V_\alpha \subset\subset W_\alpha \subset\subset U_\alpha$. Inductively, we choose $W_{\alpha_0\alpha_1\dots\alpha_i}$ with smooth boundary such that $V_{\alpha_0} \cap V_{\alpha_1} \cap \dots \cap V_{\alpha_i} \subset\subset W_{\alpha_0\dots\alpha_i} \subset\subset W_{\alpha_0\dots\alpha_{i-1}} \cap U_{\alpha_i}$. For each $i = 0, 1, \dots$, we let $\mathcal{C}^i = \bigoplus_{\alpha_0 \neq \alpha_1 \neq \dots \neq \alpha_i} C^\ell(W_{\alpha_0\dots\alpha_i}, \text{Diff}^k(F))$. Each of \mathcal{C}^i is a Banach manifold. Hence, we have

$$T\mathcal{C}^i = \bigoplus_{\alpha_0 \neq \alpha_1 \neq \dots \neq \alpha_i} C^\ell(W_{\alpha_0\dots\alpha_i}, T\text{Diff}^k(F)).$$

We define the coboundary maps

$$\Delta^0 : \mathcal{C}^0 \rightarrow \mathcal{C}^1$$

by $(\Delta^0(u))_{\alpha\beta} = u_\alpha \phi_{\alpha\beta} u_\beta^{-1}$ for every $u \in \mathcal{C}^0$, and

$$\Delta^1 : \mathcal{C}^1 \rightarrow \mathcal{C}^2$$

by $(\Delta^1(v))_{\alpha\beta\gamma} = v_{\alpha\beta} v_{\beta\gamma} v_{\alpha\gamma}^{-1}$ for every $v \in \mathcal{C}^1$. We note that since $\{\phi_{\alpha\beta}\}$ and $\{\phi'_{\alpha\beta}\}$ are transition maps of fiber bundles, $\Delta^1(\phi) = \Delta^1(\phi') = \text{id}$, where id here denotes the constant map to the identity of $\text{Diff}^k(F)$. Moreover, we also have $\Delta^0(\text{id}) = \phi$. To see that Δ^i are C^ℓ maps, we may compute the derivatives

$$(D_u \Delta^0(\xi))_{\alpha\beta} = \xi_\alpha (\phi_{\alpha\beta} u_\beta^{-1}) - (u_\alpha \phi_{\alpha\beta}) \xi_\beta$$

for every $\xi \in T_u \mathcal{C}^0$, and

$$D_v \Delta^1(\zeta)_{\alpha\beta\gamma} = \zeta_{\alpha\beta} (v_{\beta\gamma} v_{\alpha\gamma}^{-1}) + v_{\alpha\beta} (\zeta_{\beta\gamma} v_{\alpha\gamma}^{-1}) - (v_{\alpha\beta} v_{\beta\gamma}) \zeta_{\alpha\gamma}$$

for every $\zeta \in T_1 \mathcal{C}^1$, where we have used the following conventions: if $u : Q \rightarrow Q$ and $v : Q \rightarrow Q$ are smooth maps and ξ is a section of $v^* T Q$, we write $u\xi$ for the section of $(uv)^* T Q$ defined by $u\xi(x) = du_x(\xi_x)$ and write ξu for the section of $(uv)^* T Q$ given by $\xi u(x) = \xi_{u(x)}$.

From the formulas, we see that $D_u \Delta^0$ and $D_v \Delta^1$ are bounded and continuous in $u \in \mathcal{C}^0$ and $v \in \mathcal{C}^1$, respectively.

Let $\{\lambda_\alpha\}$ be a partition of unity subordinate to the cover $\{V_\alpha\}$. We define maps $\kappa^0 : T_\phi \mathcal{C}^1 \rightarrow T_{\text{id}} \mathcal{C}^0$ and $\kappa^1 : T_\phi \mathcal{C}^2 \rightarrow T_{\text{id}} \mathcal{C}^1$ by the formula:

$$(\kappa^0(\zeta))_\alpha = \sum_\gamma \lambda_\gamma \zeta_{\alpha\beta} \phi_{\alpha\gamma}^{-1}$$

and

$$(\kappa^1(\sigma))_{\alpha\beta} = \sum_\gamma \lambda_\gamma \sigma_{\alpha\beta\gamma} \phi_{\alpha\gamma}.$$

It follows that κ^0 and κ^1 are bounded.

Following the proof given in [Ben00, p. 523] verbatim, these satisfy the identity

$$D_{\text{id}}\Delta^0 \circ \kappa^0 + \kappa^1 \circ D_\phi\Delta^1 = \text{id}_{T_\phi C^1}.$$

By Lemma A.2, there is an $h = \{h_\alpha\} \in \mathcal{C}^0$ -close to $\{\text{id}\} \in \mathcal{C}^0$ such that $\Delta^0(h) = \phi'$. Equivalently, $h_\alpha(u)\phi_{\alpha\beta}(u) = \phi'_{\alpha\beta}(u)h_\beta(u)$ for all $u \in V_\alpha \cap V_\beta$, and all α and β . \square

We are now in a position to finish the proof of the main result of this appendix.

Proof of Proposition A.1. Let $\pi : X \rightarrow X/\Gamma$ be the natural covering map. Following [Ben00], we start with an appropriately chosen open cover $\{U_\alpha\}$ of X/Γ with lifts $\{\tilde{U}_\alpha \subset X\}$ such that $\tilde{U}_\alpha \rightarrow U_\alpha$ is a C^∞ diffeomorphism for each index α . The choice of \tilde{U}_α determines trivializations of the bundles $(X \times F)/\widehat{\tau}_0 \rightarrow X/\Gamma$ and $(X \times F)/\widehat{\tau} \rightarrow X/\Gamma$. If $U_\alpha \cap U_\beta \neq \emptyset$, then $\pi|_{\tilde{U}_\beta}^{-1} \circ \pi|_{\tilde{U}_\alpha \cap \pi^{-1}(U_\beta)}$ is the restriction of an element $\gamma_{\alpha\beta} \in \Gamma$. The transition functions for the bundles $(X \times F)/\widehat{\tau}_0$ and $(X \times F)/\widehat{\tau}$ are $\tau_0(\gamma_{\alpha\beta})$ and $\tau(\gamma_{\alpha\beta})$ respectively. By Lemma A.3, there exists an open cover $V_\alpha \subset\subset U_\alpha$ of X/Γ and a family $\{h_\alpha : V_\alpha \rightarrow \text{Diff}^k(F)\}$ of C^ℓ maps that are C^ℓ -close with the constant map to the identity. Since $h_\alpha\tau_0(\gamma_{\alpha\beta}) = \tau(\gamma_{\alpha\beta})h_\beta$, the family $\{h_\alpha\}$ defines a C^ℓ bundle isomorphism $f' : (X \times F)/\widehat{\tau} \rightarrow (X \times F)/\widehat{\tau}_0$ covering the identity map on X .

By Whitney's Theorem, the manifolds $(X \times F)/\widehat{\tau}_0$ and $(X \times F)/\widehat{\tau}$ admit C^∞ structures compatible with their natural C^k structures. Moreover, there is a C^∞ diffeomorphism f that is C^ℓ -close to f' since $\ell \geq 1$. The last statement regarding the foliations follows immediately. \square

REFERENCES

- [AN09] J. An and K.-H. Neeb. An implicit function theorem for Banach spaces and some applications. *Math. Z.* **262**(3) (2009), 627–643.
- [AS67] D. V. Anosov and J. G. Sinai. Certain smooth ergodic systems. *Uspekhi Mat. Nauk* **22**(5 (137)) (1967), 107–172.
- [Asa17] M. Asaoka. Local rigidity problem of smooth group actions. *Sugaku Expositions* **30**(2) (2017), 207–233.
- [Bal95] W. Ballmann. *Lectures on Spaces of Nonpositive Curvature (DMV Seminar, 25)*. Birkhäuser, Basel, 1995, with an appendix by M. Brin.
- [BE20] T. Barthélémy and A. Erchenko. Flexibility of geometrical and dynamical data in fixed conformal classes. *Indiana Univ. Math. J.* **69**(2) (2020), 513–540.
- [Ben00] E. J. Benveniste. Rigidity of isometric lattice actions on compact Riemannian manifolds. *Geom. Funct. Anal.* **10**(3) (2000), 516–542.
- [Bes87] A. L. Besse. *Einstein Manifolds (Classics in Mathematics)*. Springer, Berlin, 1987, No. XII, 510 pp.
- [BFL92] Y. Benoist, P. Foulon and F. Labourie. Flots d'Anosov à distributions stable et instable différentiables. *J. Amer. Math. Soc.* **5**(1) (1992), 33–74.
- [BG92] J.-P. Bourguignon and P. Gauduchon. Spineurs, opérateurs de Dirac et variations de métriques. *Comm. Math. Phys.* **144**(3) (1992), 581–599.
- [BKH21] J. Bochi, A. Katok and F. Rodriguez Hertz. Flexibility of Lyapunov exponents. *Ergod. Th. & Dynam. Sys.* doi: [10.1017/etds.2021.78](https://doi.org/10.1017/etds.2021.78). Published online 18 October 2021.
- [BM19] J. Bowden and K. Mann. c^0 stability of boundary actions and inequivalent Anosov flows. *Ann. Sci. Ec. Norm. Super.*, to appear.
- [BP07] L. Barreira and Y. Pesin. *Nonuniform Hyperbolicity: Dynamics of Systems with Nonzero Lyapunov Exponents (Encyclopedia of Mathematics and Its Applications, 115)*. Cambridge University Press, Cambridge, 2007.

- [BPS19] J. Bochi, R. Potrie and A. Sambarino. Anosov representations and dominated splittings. *J. Eur. Math. Soc. (JEMS)* **21**(11) (2019), 3343–3414.
- [Bri75a] M. I. Brin. Topological transitivity of a certain class of dynamical systems, and flows of frames on manifolds of negative curvature. *Funct. Anal. Appl.* **9**(1) (1975), 9–19.
- [Bri75b] M. I. Brin. The topology of group extensions of C -systems. *Mat. Zametki* **18**(3) (1975), 453–465.
- [Bri82] M. Brin. Ergodic theory of frame flows. *Ergodic Theory and Dynamical Systems, II (College Park, MD, 1979/1980) (Progress in Mathematics, 21)*. Ed. A. Katok. Birkhäuser, Boston, 1982, pp. 163–183.
- [BS64] A. Borel and J.-P. Serre. Théorèmes de finitude en cohomologie galoisienne. *Comment. Math. Helv.* **39** (1964), 111–164.
- [But19] C. Butler. Characterizing symmetric spaces by their Lyapunov spectra. *Preprint*, 2019, [arXiv:1709.08066](https://arxiv.org/abs/1709.08066).
- [But18] C. Butler. Rigidity of equality of Lyapunov exponents for geodesic flows. *J. Differential Geom.* **109**(1) (2018), 39–79.
- [Cho39] W.-L. Chow. Über Systeme von linearen partiellen Differentialgleichungen erster Ordnung. *Math. Ann.* **117** (1939), 98–105.
- [CNS20] C. Connell, T. Nguyen and R. Spatzier. Hyperbolic rank rigidity for manifolds of $\frac{1}{4}$ -pinched negative curvature. *Ergod. Th. & Dynam. Sys.*, **40**(5): 1194–1216, 2020.
- [Con03] C. Connell. Minimal Lyapunov exponents, quasiconformal structures, and rigidity of non-positively curved manifolds. *Ergod. Th. & Dynam. Sys.* **23**(2) (2003), 429–446.
- [Con08] D. Constantine. 2-frame flow dynamics and hyperbolic rank-rigidity in nonpositive curvature. *J. Mod. Dyn.* **2**(4) (2008), 719–740.
- [CP15] S. Crovisier and R. Potrie. *Introduction to Partially Hyperbolic Dynamics, Lecture notes for School on Dynamical Systems, ICTP, Trieste, 2015*.
- [CPZ19] V. Climenhaga, Y. Pesin and A. Zelerowicz. Equilibrium states in dynamical systems via geometric measure theory. *Bull. Amer. Math. Soc. (N.S.)* **56**(4) (2019), 569–610.
- [CS21] P. Carrasco and R. Saghin. Extended flexibility of Lyapunov exponents for Anosov diffeomorphisms. *Trans. Amer. Math. Soc.*, to appear.
- [DeW19] J. DeWitt. Local Lyapunov spectrum rigidity of nilmanifold automorphisms. *J. Mod. Dyn.* **17** (2021), 65–109.
- [DSLVY20] J. De Simoi, M. Leguil, K. Vinhage and Y. Yang. Entropy rigidity for 3D conservative Anosov flows and dispersing billiards. *Geom. Funct. Anal.* **30**(5) (2020), 1337–1369.
- [EK19] A. Erchenko and A. Katok. Flexibility of entropies for surfaces of negative curvature. *Israel J. Math.* **232**(2) (2019), 631–676.
- [Eli67] H. I. Eliasson. Geometry of manifolds of maps. *J. Differential Geom.* **1**(1–2) (1967), 169–194.
- [FK90] R. Feres and A. Katok. Anosov flows with smooth foliations and rigidity of geodesic flows on three-dimensional manifolds of negative curvature. *Ergod. Th. & Dynam. Sys.*, **10**(4) (1990), 657–670.
- [Fla95] L. Flaminio. Local entropy rigidity for hyperbolic manifolds. *Comm. Anal. Geom.* **3**(3–4) (1995), 555–596.
- [Ghy93] É. Ghys. Rigidité différentiable des groupes fuchsiens. *Publ. Math. Inst. Hautes Études Sci.* **78**(1) (1993), 163–185.
- [GKS11] A. Gogolev, B. Kalinin and V. Sadovskaya. Local rigidity for Anosov automorphisms. *Math. Res. Lett.* **18**(5) (2011), 843–858, with an appendix by R. de la Llave.
- [GKS20] A. Gogolev, B. Kalinin and V. Sadovskaya. Local rigidity of Lyapunov spectrum for toral automorphisms. *Israel J. Math.* **238** (2020), 389–403.
- [Gor94] V. V. Gorbatsevich. *Lie Groups and Lie Algebras III: Structure of Lie Groups and Lie Algebras (Encyclopaedia of Mathematical Sciences, 41)*. Springer, Berlin, 1994.
- [Gro81] M. Gromov. *Structures métriques pour les variétés riemanniennes (Textes Mathématiques [Mathematical Texts], 1)*. Eds. J. Lafontaine and P. Pansu. CEDIC, Paris, 1981.
- [Gro96] M. Gromov. Carnot–Carathéodory spaces seen from within. *Sub-Riemannian Geometry (Progress in Mathematics, 144)*. Eds. A. Bellaïche and J.-J. Risler. Birkhäuser, Basel, 1996, pp. 79–323.
- [GS97] E. R. Goetze and R. J. Spatzier. On Livšic’s theorem, superrigidity, and Anosov actions of semisimple Lie groups. *Duke Math. J.* **88**(1) (1997), 1–27.
- [Hör67] L. Hörmander. Hypoelliptic second order differential equations. *Acta Math.* **119** (1967), 147–171.
- [HPS77] M. W. Hirsch, C. C. Pugh and M. Shub. *Invariant Manifolds (Lecture Notes in Mathematics, 583)*. Springer, Berlin, 1977.
- [Kal11] B. Kalinin. Livšic theorem for matrix cocycles. *Ann. of Math. (2)* **173**(2) (2011), 1025–1042.

- [KH95] A. Katok and B. Hasselblatt. *Introduction to the Modern Theory of Dynamical Systems (Encyclopedia of Mathematics and Its Applications, 54)*. Cambridge University Press, Cambridge, 1995, with a supplementary chapter by A. Katok and L. Mendoza.
- [Lau03] J. Lauret. Examples of Anosov diffeomorphisms. *J. Algebra* **262**(1) (2003), 201–209.
- [LDOW14] E. Le Donne, A. Ottazzi and B. Warhurst. Ultrarigid tangents of sub-Riemannian nilpotent groups. *Ann. Inst. Fourier (Grenoble)* **64**(6) (2014), 2265–2282.
- [Mét76] G. Métivier. Fonction spectrale et valeurs propres d'une classe d'opérateurs non elliptiques. *Comm. Partial Differential Equations* **1**(5) (1976), 467–519.
- [Mit85] J. Mitchell. On Carnot–Carathéodory metrics. *J. Differential Geom.* **21**(1) (1985), 35–45.
- [MM00] G. A. Margulis and G. D. Mostow. Some remarks on the definition of tangent cones in a Carnot–Carathéodory space. *J. Anal. Math.* **80** (2000), 299–317.
- [MM95] G. A. Margulis and G. D. Mostow. The differential of a quasi-conformal mapping of a Carnot–Carathéodory space. *Geom. Funct. Anal.* **5**(2) (1995), 402–433.
- [Mos73] G. D. Mostow. *Strong Rigidity of Locally Symmetric Spaces (AM-78)*. Princeton University Press, Princeton, NJ, 1973.
- [Pan89] P. Pansu. Métriques de Carnot–Carathéodory et quasiisométries des espaces symétriques de rang un. *Ann. of Math. (2)* **129**(1) (1989), 1–60.
- [Par86] W. Parry. Synchronisation of canonical measures for hyperbolic attractors. *Comm. Math. Phys.* **106**(2) (1986), 267–275.
- [PPS15] F. Paulin, M. Pollicott and B. Schapira. *Equilibrium States in Negative Curvature (Astérisque, 373)*. Société Mathématique de France, Paris, 2015.
- [Sam16] M. Sambarino. A (short) survey on dominated splittings. *Mathematical Congress of the Americas (Contemporary Mathematics, 656)*. Eds. J. A. de la Peña, J. A. López-Mimbela, M. Nakamura and J. Petean. American Mathematical Society, Providence, RI, 2016, pp. 149–183.
- [Shu69] M. Shub. Endomorphisms of compact differentiable manifolds. *Amer. J. Math.* **91** (1969), 175–199.
- [Sin72] Y. G. Sinai. Gibbs measures in ergodic theory. *Russian Math. Surveys* **27**(4) (1972), 21.
- [Sma67] S. Smale. Differentiable dynamical systems. *Bull. Amer. Math. Soc. (N.S.)* **73**(6) (1967), 747–817.
- [Sul85] D. Sullivan. Quasiconformal homeomorphisms and dynamics II: structural stability implies hyperbolicity for Kleinian groups. *Acta Math.* **155**(1) (1985), 243–260.
- [SY19] R. Saghin and J. Yang. Lyapunov exponents and rigidity of Anosov automorphisms and skew products. *Adv. Math.* **355** (2019), 106764.
- [Til70] H. Tilgner. A class of solvable Lie groups and their relation to the canonical formalism. *Ann. Inst. H. Poincaré Sect. A (N.S.)* **13** (1970), 103–127.
- [Var84] V. S. Varadarajan. *Lie Groups, Lie Algebras, and Their Representations (Graduate Texts in Mathematics, 102)*. Springer, New York, 1984. Reprint of the 1974 edition.
- [Ver70] M. Vergne. Cohomologie des algèbres de Lie nilpotentes. Application à l'étude de la variété des algèbres de Lie nilpotentes. *Bull. Soc. Math. France* **98** (1970), 81–116.
- [Whi57] H. Whitney. Elementary structure of real algebraic varieties. *Ann. of Math. (2)* **66** (1957), 545–556.
- [Wit19] J. Wittmann. *The Banach manifold $C^k(M, N)$. Differential Geom. Appl.* **63** (2019), 166–185.
- [Yue95] C. Yue. Smooth rigidity of rank-1 lattice actions on the sphere at infinity. *Math. Res. Lett.* **2**(3) (1995), 327–338.
- [Zim84] R. J. Zimmer. *Ergodic Theory and Semisimple Groups (Monographs in Mathematics, 81)*. Birkhäuser, Basel, 1984.