POTENTIAL THEORY WITH MULTIVARIATE KERNELS

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ABSTRACT. In the present paper we develop the theory of minimization for energies with multivariate kernels, i.e. energies, in which pairwise interactions are replaced by interactions between triples or, more generally, n-tuples of particles. Such objects, which arise naturally in various fields, present subtle differences and complications when compared to the classical two-input case. We introduce appropriate analogues of conditionally positive definite kernels, establish a series of relevant results in potential theory, explore rotationally invariant energies on the sphere, and present a variety of interesting examples, in particular, some optimization problems in probabilistic geometry which are related to multivariate versions of the Riesz energies.

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1. Introduction and main results

Numerous questions, which arise in such different disciplines as discrete geometry, physics, signal processing, and many others, can be reformulated as problems of minimization of discrete or continuous pairwise interaction energies, i.e. expressions of the type

$$\frac{1}{N^2} \sum_{x,y \in \omega_N} K(x,y) \quad \text{or} \quad \int_{\Omega} \int_{\Omega} K(x,y) \, d\mu(x) \, d\mu(y), \tag{1.1}$$

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where ω_N is a discrete set of N points, μ is a Borel probability measure on the domain Ω , and K is the potential function describing the pairwise interaction. Perhaps one of the most celebrated examples of such problems is the 1904 Thomson problem, asking for an equilibrium distribution of N electrons on the sphere, which is notoriously still open for most values of N [Th]. This and many other problems stimulated the study of such energies, which has now developed into a full-blown theory, see e.g. [Bj, Fu, HS], whose state-of-the-art is very well presented in a recent book [BHS].

While classical energies (1.1) model pairwise interactions between particles, the present paper, in contrast, initiates the study of optimization problems for more complicated energies, defined by interactions of triples, quadruples, or even higher numbers of particles, i.e. energies of the type

$$E_K(\omega_N) = \frac{1}{N^n} \sum_{x_1, ..., x_n \in \omega_N} K(x_1, ..., x_n),$$
(1.2)

$$I_K(\mu) = \int_{\Omega} \dots \int_{\Omega} K(x_1, \dots, x_n) d\mu(x_1) \dots d\mu(x_n), \tag{1.3}$$

with $n \geq 3$. Energies of this type arise naturally in various fields:

- (i) In different branches of *physics* (nuclear, quantum, chemical, condensed matter, material science etc.), it has been suggested that, if the behavior of the system cannot be accurately modeled by two-body interactions, more precise information may be obtained from three-body or many-body interactions. Such forces are observed among nucleons in atomic nuclei (three-nucleon force) [Ze], in carbon nanostructures [MS], crystallization of atomistic configurations [FTh], cold polar molecules in optical lattices [BMZ], interactions of solid and liquid forms of silicon [StW], interactions between atoms [AT], in "perfect glass" potentials [ZST], and many other areas.
- (ii) Energy integrals with multivariate kernels defined in (1.3) play the role of polynomials on the space $\mathbb{P}(\Omega)$ of probability measures on Ω e.g., their linear span over all $n \in \mathbb{N}$ is dense in the space of continuous functions on $\mathbb{P}(\Omega)$, according to the Stone–Weierstrass theorem. Such functionals on the space of measures appear in optimal transport [Sa] and mean field games [L].
- (iii) A classical example of a three-input energy, coming from geometric measure theory, is given by the total Menger curvature of a measure μ

$$c^{2}(\mu) = \int_{\Omega} \int_{\Omega} \int_{\Omega} c^{2}(x, y, z) d\mu(x) d\mu(y) d\mu(z), \tag{1.4}$$

where $c(x, y, z) = \frac{1}{R(x, y, z)}$ and R(x, y, z) is the circumradius of the triangle xyz. This object plays an important role in the study of the L^2 -boundedness of the Cauchy integral, analytic capacity, and uniform rectifiability [D, MMV].

- (iv) Some questions in probabilistic geometry admit natural reformulations in terms of multi-input energies (1.2) or (1.3). For example, assume that three points are chosen in a domain Ω , e.g. $\Omega = \mathbb{S}^2$, independently at random, according to the probability distribution μ . Which probability distribution maximizes the expected area of the triangle generated by these random points or the volume of the parallelepiped spanned by the random vectors? These quantities can be written as energy integrals (1.2) with n = 3, and higher dimensional versions of such questions call for energies with more inputs, which may be viewed as natural extensions of the classical Riesz energy. Questions of this type are discussed in Section 6.4 and are explored in more detail in [BFGMPV].
- (v) Energies with more than two inputs akin to (1.2) appear in three-point bounds [CW] and, more generally, k-point bounds [DMOV, Mu] in semidefinite programming [BV] a very fruitful method, which led to numerous breakthroughs in discrete geometry. A discussion of this method in the context of the multivariate energy optimization and, in particular, applications to the geometric problems described in Section 6.4 can be found in our follow-up work [BFGMPV].
- (vi) Relations between the L^2 -discrepancy and the two-input energies, in particular, the Stolarsky principle [St], are well known [BDM, Sk]. In a similar spirit, other L^n -norms of the discrepancy or "number variance" with integer values of n lead to n-particle interaction energies (1.2). Some similar ideas have been put forward in [T].

Despite the abundance of applications, there seems to have been no systematic development of a general theory of multi-input energies, unlike the case of classical two-input energies which has been deeply and extensively explored. The present paper makes a first attempt to remedy this shortcoming and to study the general properties of point configurations and measures, minimizing the multi-input energies (1.2)-(1.3), and the relations between the structure of the multivariate kernel K and the energy minimizers. This theory presents many intrinsic obstacles and is far from a straightforward generalization of the two-input case. In particular, in the spherical case $\Omega = \mathbb{S}^{d-1}$ with rotationally-invariant two-input kernels $K(x,y) = F(\langle x,y \rangle)$, classical Schoenberg's theory [S] proves that the uniform surface measure σ minimizes the energy integral in (1.1) if and only if the kernel K is conditionally positive definite. However, in the multi-input case, such a characterization is still elusive: while we obtain various natural sufficient conditions for the surface measure σ to minimize the energy (1.2) in Section 5, counterexamples presented in Section 6 show that none of them are necessary.

The outline of the paper is as follows. In Section 2 we introduce the notation and some of the main definitions, including the notion of n-positive definiteness. In Section 3 we explore some basic properties of multivariate energies. In particular, we analyze the connections between (conditional) positive definiteness of the kernel K, convexity of the energy functional $I_K(\mu)$, and arithmetic and geometric mean inequalities for the mixed energies. The meat of the paper, i.e. the results about minimizers of the n-input energies are concentrated in Sections 4–6.

Section 4 deals with analogues of classical potential theoretic results [Bj, BHS, Fu], which provide certain necessary (Theorem 4.1) and sufficient (Theorem 4.4) conditions for a measure μ to be a minimizer of the n-input energy integral in terms of the (n-1)-fold potential of the kernel K with respect to μ . Even though some of these results by themselves are clear-cut generalizations of standard statements for two-input energies, they yield several interesting consequences in the n-input case. In particular, Theorem 4.8 states that, under some additional assumptions (e.g., if K is n-positive definite), for any $1 \le k \le n-2$, if the measure μ minimizes the (n-k)-input energy I_U , where U is the k-fold integral of K with respect to μ , then μ also minimizes the n-input energy I_K . This statement allows one to simplify proving that a given measure is a minimizer of a multi-input energy by considering energies with a lower number of inputs. A partial converse to Theorem 4.8, for k = n - 2, is given in Theorem 4.9. In addition, in Lemma 4.6, we show that, for n-positive definite kernels, every local minimizer of I_K is necessarily a global minimizer.

In Section 5 we adapt the methods of Section 4 to energies with rotationally invariant kernels on the sphere \mathbb{S}^{d-1} , where symmetries allow for a more delicate analysis, and one has a natural candidate for a minimizer: the uniform surface measure σ . Theorem 5.1 states that energies with conditionally n-positive definite rotationally invariant kernels on the sphere are minimized by the surface measure σ (without any additional assumptions). As mentioned above, it turns out that, in contrast to the classical case n=2, conditional n-positive definiteness is not necessary for σ to minimize the n-input energy, which is shown by examples presented in Propositions 6.9 and 6.10. Nevertheless, Theorem 5.1 allows one to prove that σ minimizes a variety of interesting energies, which did not seem to be accessible by different methods, see e.g. Corollary 5.2. In Theorem 5.3 we obtain very close necessary and sufficient conditions for σ to be a local minimizer of the n-input energy I_K in terms of the minimization properties of the two-input energy with the kernel given by the (n-2)-fold integral of K (or the conditional positive definiteness of this kernel). We also conjecture these are the correct conditions for σ to be a global minimizer of I_K .

Section 6 is dedicated to constructing various classes of n-positive definite kernels, proving that certain kernels of interest are (conditionally) n-positive definite, as well as exhibiting some naturally arising 3-input kernels on the sphere which are not conditionally 3-positive definite, yet the corresponding energies are minimized by the surface measure σ . These examples are presented in Propositions 6.5, 6.9, and 6.10. The first one is closely related to the semidefinite programming method as presented in [BV], while the last two are geometric. The latter kernels are studied in Section 6.4 which addresses some problems from probabilistic discrete geometry. Their main objects may be viewed as multi-input analogues of the classical Riesz energies. In particular, we show that if three random vectors are chosen in the sphere \mathbb{S}^{d-1} independently according to the probability distribution μ , then the expected volume squared of the tetrahedron generated by these vectors (Theorem 6.6) as well as the square of the area of the triangle defined by these points (Theorem 6.7) are maximized if the distribution is uniform, i.e. $\mu = \sigma$. A more

detailed study of such geometric questions is conducted by the authors in [BFGMPV].

While many of the results presented in this paper hold (or can be extended) to a larger class of kernels (e.g., bounded lower semi-continuous, or even singular kernels), given that this is the first effort to establish a theory of multi-input energies, for the sake of brevity and clarity of the exposition, we shall only consider continuous kernels on compact metric spaces in this paper. We shall also restrict our attention to symmetric *n*-input kernels, i.e. functions invariant with respect to any permutation of variables. These assumptions are implicitly present in all of the results presented below, even if not stated explicitly.

2. Background and definitions

In what follows, we always assume that (Ω, ρ) is a compact metric space, $n \in \mathbb{N} \setminus \{1\}$, and the kernel $K : \Omega^n \to \mathbb{R}$ is continuous and symmetric, i.e. for any permutation $\pi \in S_n$ and $x_1, ..., x_n \in \Omega$, $K(x_1, ..., x_n) = K(x_{\pi(1)}, ..., x_{\pi(n)})$. We denote by $\mathcal{M}(\Omega)$ the set of finite signed Borel measures on Ω , and by $\mathbb{P}(\Omega)$ the set of Borel probability measures on Ω . Let $\omega_N = \{x_1, x_2, ..., x_N\}$ be an N-point configuration (multiset) in Ω for $N \geq n$. We define the discrete K-energy of ω_N to be

$$E_K(\omega_N) := \frac{1}{N^n} \sum_{j_1=1}^N \cdots \sum_{j_n=1}^N K(x_{j_1}, ..., x_{j_n}), \tag{2.1}$$

and the minimal discrete N-point K-energy of Ω as

$$\mathcal{E}_K(\Omega, N) := \inf_{\omega_N \subset \Omega} E_K(\omega_N). \tag{2.2}$$

Let $\mu_1, ..., \mu_n \in \mathcal{M}(\Omega)$, then we define their mutual energy as

$$I_K(\mu_1, ..., \mu_n) = \int_{\Omega} \cdots \int_{\Omega} K(x_1, ..., x_n) d\mu_1(x_1) \cdots d\mu_n(x_n),$$
 (2.3)

and, for j < n, the j-th potential function as

$$U_K^{\mu_1,...,\mu_j}(x_{j+1},...,x_n) = \int_{\Omega} \cdots \int_{\Omega} K(x_1,...,x_n) d\mu_1(x_1) \cdots d\mu_j(x_j).$$
 (2.4)

Note that since we are working with continuous K, the energy is well defined for all finite signed Borel measures. We will abuse notation by writing μ^k if k of the measures are the same and define the K-energy functional on $\mathcal{M}(\Omega)$ by

$$I_K(\mu) = I_K(\mu^n) = I_K(\mu, ..., \mu).$$
 (2.5)

The definitions of discrete (2.1) and continuous (2.5) energies are compatible in the sense that

$$E_K(\omega_N) = I_K(\mu_{\omega_N}), \quad \text{where } \mu_{\omega_N} = \frac{1}{N} \sum_{j=1}^N \delta_{x_j}$$
 (2.6)

and due to the weak-* density of the linear span of Dirac masses in $\mathbb{P}(\Omega)$

$$\lim_{N \to \infty} \mathcal{E}_K(\Omega, N) = \inf_{\mu \in \mathbb{P}(\Omega)} I_K(\mu). \tag{2.7}$$

We now recall the classical notion of positive definiteness for two-input kernels, which plays an extremely important role in energy optimization problems and which we seek to generalize to n-input kernels. We state the definition in the form which is most relevant to our exposition.

Definition 2.1. A kernel $K: \Omega^2 \to \mathbb{R}$ is called positive definite if for every finite signed Borel measure $\nu \in \mathcal{M}(\Omega)$, the energy integral satisfies $I_K(\nu) \geq 0$.

If the inequality $I_K(\nu) \geq 0$ holds for all $\nu \in \mathcal{M}(\Omega)$ satisfying $\nu(\Omega) = 0$, we call the kernel conditionally positive definite.

A more standard way of stating the definition of positive definiteness of K is by requiring that for all $N \in \mathbb{N}$ and $x_1, ..., x_N \in \Omega$, the matrix $[K(x_i, x_j)]_{0 \le i,j \le N}$ is positive semi-definite, i.e.

$$I_K\left(\sum_{i=1}^N c_i \delta_{x_i}\right) = \sum_{i,j=1}^N K(x_i, x_j) c_i c_j \ge 0$$

for all $c_1, \ldots, c_N \in \mathbb{R}$. Since K is continuous, this is clearly equivalent to Definition 2.1 due to weak-* density of discrete measures.

We extend this notion to *n*-input kernels by demanding that, if one fixes arbitrary values of all but two variables, the resulting two-input kernel is positive definite in the classical sense. For every m < n and $z_1, z_2, ..., z_m \in \Omega$, we define

$$K_{z_1, z_2, \dots, z_m}(x_1, \dots, x_{n-m}) := K(z_1, \dots, z_m, x_1, \dots, x_{n-m}).$$
(2.8)

Definition 2.2. We shall say that a continuous symmetric kernel $K: \Omega^n \to \mathbb{R}$ is (conditionally) n-positive definite if, for all $z_1, z_2, ..., z_{n-2} \in \Omega$, the two-input kernel $K_{z_1,...,z_{n-2}}$ is (conditionally) positive definite in the sense of Definition 2.1.

We would like to emphasize that this definition relies more on the pointwise two-variable structure, rather than the full set of variables. In particular, it does not have any connection to positive definite tensors [Q]. Thus, it may appear that the name n-positive definite might be somewhat misleading. However, from the point of view of energy optimization, which is the main theme of this paper, this nomenclature seems absolutely justified. Indeed, in various statements about minimal energy (e.g., Theorem 4.4, Corollary 4.5, Theorem 5.1), this condition naturally replaces positive definiteness of classical two-input kernels. In addition, non-symmetric multivariate kernels of similar flavor have been considered in the context of k-point bounds in semidefinite programming [DMOV, Mu]. The class of n-positive definite kernels is rather rich: throughout the text, in particular, in Section 6, we present numerous examples of functions with this property.

We immediately observe that this property is inherited by kernels with a lower number of inputs, which are obtained as potentials of K with respect to arbitrary probability measures.

Lemma 2.3. Let n > 2 and assume that K is (conditionally) n-positive definite. Then for every $\mu \in \mathbb{P}(\Omega)$, the potential $U_K^{\mu}(x_1, \ldots, x_{n-1})$ is (conditionally) (n-1)-positive definite.

Proof. Let ν be a finite signed Borel measure on Ω (with $\nu(\Omega) = 0$ if K is conditionally n-positive definite). Then by Fubini–Tonelli

$$I_{\left(U_{K}^{\mu}\right)_{z_{2},...,z_{n-2}}}(\nu) = \int_{\Omega} \int_{\Omega} \int_{\Omega} K(z_{1}, z_{2}, ..., z_{n-3}, z_{n-2}, x, y) d\mu(z_{1}) \ d\nu(x) d\nu(y)$$

$$= \int_{\Omega} \int_{\Omega} \int_{\Omega} K_{z_{1},...,z_{n-2}}(x, y) d\nu(x) d\nu(y) \ d\mu(z_{1}) \ge 0,$$

since $K_{z_1,...,z_{n-2}}$ is (conditionally) positive definite for all $z_1,...,z_{n-2} \in \Omega$.

As a corollary of Lemma 2.3, we observe that if $K: \Omega^n \to \mathbb{R}$ is (conditionally) n-positive definite, then for all $\mu_1, ..., \mu_k \in \mathbb{P}(\Omega)$, with $k \leq n-2$, $U_K^{\mu_1, ..., \mu_k}(x_{k+1}, ..., x_n)$ is (conditionally) (n-k)-positive definite. Naturally, (conditionally) n-positive definite kernels enjoy the same basic properties as their classical two-variable counterparts.

Lemma 2.4. If K and L are n-positive definite, then so are K + L and KL. If $K_1, K_2, ...$ are n-positive definite and $\lim_{n\to\infty} K_n = K$ uniformly, then K is n-positive definite. The statements about the sum and the limit (but not about the product) continue to hold if we replace n-positive definite with conditionally n-positive definite.

The proof of this lemma is straightforward. The statement about the product KL follows from the classical Schur product theorem, and positive definiteness in this statement cannot be replaced by conditional positive definiteness (since, for example, a negative constant is a conditionally n-positive definite function).

3. First principles

In this section we explore some basic properties related to (conditional) n-positive definiteness, such as inequalities for mixed energies and convexity of the energy functionals, as well as connections between these notions. All the kernels in this section are assumed to be continuous and symmetric.

3.1. **Bounds on mutual energies.** In the classical case, mixed energies can be bounded by averages of energies of each individual measure. We refer the reader to Chapter 4 of [BHS] for details.

Lemma 3.1. Suppose K is a conditionally positive definite kernel on Ω^2 . Then for every pair of Borel probability measures μ_1 and μ_2 on Ω , the mutual energy $I_K(\mu_1, \mu_2)$ satisfies

$$I_K(\mu_1, \mu_2) \le \frac{1}{2} (I_K(\mu_1) + I_K(\mu_2)).$$

Furthermore, if K is positive definite, then

$$I_K(\mu_1, \mu_2) \le \sqrt{I_K(\mu_1)I_K(\mu_2)}$$
.

These inequalities can be extended to n-input energies with (conditionally) n-positive definite kernels.

Lemma 3.2. Suppose K is a conditionally n-positive definite kernel on Ω^n . Then for every n-tuple of Borel probability measures μ_1, \ldots, μ_n on Ω , the mutual energy $I_K(\mu_1, \ldots, \mu_n)$ satisfies

$$I_K(\mu_1, \dots, \mu_n) \le \frac{1}{n} \sum_{i=1}^n I_K(\mu_i).$$
 (3.1)

If, moreover, K is n-positive definite,

$$I_K(\mu_1, \dots, \mu_n) \le \prod_{j=1}^n \sqrt[n]{I_K(\mu_j)}.$$
 (3.2)

Proof. We only prove (3.2), as one could repeat the proof below verbatim, with the multiplicative notation replaced by the additive, to arrive at (3.1) (when K is n-positive definite, it would also follow from the arithmetic–geometric mean inequality).

By Lemma 3.1, our claim holds for n=2. Now, suppose our claim holds for some $k \geq 2$, and let $\mu_1, ..., \mu_{k+1} \in \mathbb{P}(\Omega)$. Lemma 2.3 tells us that for $1 \leq j \leq k+1$, $U_K^{\mu_j}$ is k-positive definite, so by our inductive hypothesis

$$I_K(\mu_1, ..., \mu_{k+1}) = I_{U_K^{\mu_1}}(\mu_2, ..., \mu_{k+1}) \le \prod_{j=1}^k \sqrt[k]{I_K(\mu_1, \mu_{j+1}^k)}.$$
(3.3)

Again using the inductive hypothesis, and the fact that K is symmetric, we have that for $1 \le j \le k$,

$$\begin{split} I_K(\mu_1, \mu_{j+1}^k) &= I_K(\mu_{j+1}, \mu_1, \mu_{j+1}^{k-1}) \\ &\leq \sqrt[k]{I_K(\mu_{j+1}, \mu_1^k)} \sqrt[k]{I_K(\mu_{j+1})^{k-1}} \\ &= \sqrt[k]{I_K(\mu_1, \mu_{j+1}, \mu_1^{k-1})} \sqrt[k]{I_K(\mu_{j+1})^{k-1}} \\ &\leq \sqrt[k^2]{I_K(\mu_1)^{k-1}} \sqrt[k^2]{I_K(\mu_1, \mu_{j+1}^k)} \sqrt[k]{I_K(\mu_{j+1})^{k-1}}, \end{split}$$

where in the second and last lines we have used (3.3). Rearranging the terms, we have

$$(I_K(\mu_1, \mu_{j+1}^k))^{\frac{k^2-1}{k^2}} \le I_K(\mu_1)^{\frac{k-1}{k^2}} I_K(\mu_{j+1})^{\frac{k-1}{k}},$$

so that

$$\sqrt[k]{I_K(\mu_1, \mu_{j+1}^k)} \le I_K(\mu_1)^{\frac{1}{k(k+1)}} I_K(\mu_{j+1})^{\frac{1}{k+1}}.$$

Plugging this back into (3.3), we have

$$I_K(\mu_1, ..., \mu_{k+1}) \le \prod_{j=1}^k \sqrt[k]{I_K(\mu_1, \mu_{j+1}^k)} \le \prod_{j=1}^{k+1} \sqrt[k+1]{I_K(\mu_j)}.$$
 (3.4)

Our claim then follows via induction.

The upper bound (3.1) allows us to prove a corresponding lower bound for the mixed energy:

Corollary 3.3. If K is n-positive definite on Ω^n , then for all $\mu_1, ..., \mu_n \in \mathbb{P}(\Omega)$,

$$-\frac{1}{n}\sum_{j=1}^{n}I_{K}(\mu_{j}) \leq I_{K}(\mu_{1},...,\mu_{n}). \tag{3.5}$$

Proof. Suppose n=2, and let $\mu_1, \mu_2 \in \mathbb{P}(\Omega)$. Setting $\mu=\frac{1}{2}(\mu_1+\mu_2)$, we have

$$0 \le 4I_K(\mu) = I_K(\mu_1) + I_K(\mu_2) + 2I_K(\mu_1, \mu_2),$$

since K is positive definite, and (3.5) follows.

Now suppose our claim holds for some $k \geq 2$, and let $\mu_1, ..., \mu_{k+1} \in \mathbb{P}(\Omega)$. Since by Lemma 2.3 the potential $U_K^{\mu_1}$ is k-positive definite, the inductive hypothesis implies that

$$-\frac{1}{k} \sum_{j=1}^{k} I_{U_K^{\mu_1}}(\mu_{j+1}) \le I_{U_K^{\mu_1}}(\mu_2, ..., \mu_{k+1}) = I_K(\mu_1, ..., \mu_{k+1}).$$

For $1 \le j \le k$, Lemma 3.2 gives us that

$$I_{U_K^{\mu_1}}(\mu_{j+1}) = I_K(\mu_1, \mu_{j+1}^k) \le \frac{1}{k+1} \Big(I_K(\mu_1) + kI_K(\mu_{j+1}) \Big),$$

leading to

$$-\frac{1}{k+1}\sum_{j=1}^{k+1}I_K(\mu_j) \le I_K(\mu_1, ..., \mu_{k+1}),$$

which finishes the proof of the claim.

Lemma 3.2 and Corollary 3.3 imply that if K is n-positive definite on Ω^n and $\mu_1, ..., \mu_n \in \mathbb{P}(\Omega)$, then

$$|I_K(\mu_1, ..., \mu_n)| \le \frac{1}{n} \sum_{j=1}^n I_K(\mu_j).$$
 (3.6)

Of course, since we can choose the probability measures μ_k to be Dirac masses, inequality (3.6) yields pointwise bounds on K. For instance, if K is n-positive definite, then for all $z_1, ..., z_n \in \Omega$,

$$|K(z_1,...,z_n)| \le \frac{1}{n} \sum_{j=1}^n K(z_j,...,z_j),$$

and for conditionally n-positive definite kernels K, this inequality holds without the absolute value. Clearly then, K must achieve its maximum value on its diagonal, something that is already known for the two-input case.

Corollary 3.4. Suppose K is a conditionally n-positive definite kernel. Then

$$K(z_1, \dots, z_n) \le \max_{z \in \Omega} \{K(z, \dots, z)\}.$$
(3.7)

3.2. Convexity. Convexity of the underlying energy functionals naturally plays an important role in energy minimization.

Definition 3.5. Suppose $K: \Omega^n \to \mathbb{R}$. We say that I_K is convex at $\mu \in \mathbb{P}(\Omega)$ if for every $\nu \in \mathbb{P}(\Omega)$ there exists some $t_{\nu} \in (0,1]$, such that for all $t \in [0,t_{\nu})$

$$I_K((1-t)\mu + t\nu) \le (1-t)I_K(\mu) + tI_K(\nu).$$
 (3.8)

We say I_K is convex on $\mathbb{P}(\Omega)$ if inequality (3.8) holds for every $\mu, \nu \in \mathbb{P}(\Omega)$ and all $t \in [0,1]$.

We observe that convexity of I_K on $\mathbb{P}(\Omega)$ is equivalent to the fact that I_K is convex at all $\mu \in \mathbb{P}(\Omega)$. Indeed, if (3.8) fails for some $\mu, \nu \in \mathbb{P}(\Omega)$, then the polynomial $f(t) = I_K((1-t)\mu + t\nu)$ is not convex on the interval [0,1], i.e. f''(t) < 0 on some subinterval $[a,b] \subset [0,1]$. But in this case, one can easily see that I_K fails to be convex at $\mu_a = (1-a)\mu + a\nu$.

Conditional positive definiteness of the kernel K is closely related to convexity of the corresponding energy functional I_K . In fact, as we shall see in Proposition 3.9, when n=2, the two notions are equivalent. For further discussions about the connections between various conditions related to positive definiteness in the classical two-input case, see [BMV].

One-sided implication holds for all $n \geq 2$: as the next proposition shows, convexity of I_K can be deduced from relaxed arithmetic or geometric mean inequalities akin to (3.1) and (3.2). This implies, due to Lemma 3.2, that conditionally n-positive definite kernels K give rise to convex energies.

Proposition 3.6. Let $K: \Omega^n \to \mathbb{R}$ be continuous and symmetric and fix $\mu \in \mathbb{P}(\Omega)$. Suppose that for all $\nu \in \mathbb{P}(\Omega)$ and $0 \le k \le n$,

$$I_K(\mu^k, \nu^{n-k}) \le \frac{k}{n} I_K(\mu) + \frac{n-k}{n} I_K(\nu).$$
 (3.9)

Alternatively, assume that for all $\nu \in \mathbb{P}(\Omega)$ we have $I_K(\nu) \geq 0$ and for all $0 \leq k \leq n$

$$I_K(\mu^k, \nu^{n-k}) \le (I_K(\mu))^{\frac{k}{n}} \cdot (I_K(\nu))^{\frac{n-k}{n}}.$$
 (3.10)

Then I_K is convex at μ . If (3.9) or (3.10) holds for all $\mu \in \mathbb{P}(\Omega)$, then I_K is convex on $\mathbb{P}(\Omega)$.

Proof. Assume that (3.9) holds. For all $t \in [0, 1]$, we have

$$I_K((1-t)\mu + t\nu) = \sum_{k=0}^n (1-t)^k t^{n-k} \binom{n}{k} I_K(\mu^k, \nu^{n-k})$$

$$\leq \sum_{k=0}^n (1-t)^k t^{n-k} \binom{n}{k} \left(\frac{k}{n} I_K(\mu) + \frac{n-k}{n} I_K(\nu)\right)$$

$$= \sum_{k=1}^n (1-t)^k t^{n-k} \binom{n-1}{k-1} I_K(\mu) + \sum_{k=0}^{n-1} (1-t)^k t^{n-k} \binom{n-1}{k} I_K(\nu)$$

$$= (1-t) I_K(\mu) + t I_K(\nu),$$

which proves convexity of the energy functional. The multiplicative inequality (3.10) implies (3.9) by the arithmetic-geometric mean inequality, leading to convexity of K in this case.

Lemma 3.2 with $\mu_1 = \cdots = \mu_k = \mu$ and $\mu_{k+1} = \cdots = \mu_n = \nu$ shows that inequality (3.9) holds, if K is conditionally n-positive definite. This leads to the following corollary.

Corollary 3.7. If K is conditionally n-positive definite, then I_K is convex on $\mathbb{P}(\Omega)$.

To prove the converse implication for n = 2, we start by observing that Proposition 3.6 admits a partial converse:

Lemma 3.8. Suppose $\mu \in \mathbb{P}(\Omega)$ is such that I_K is convex at μ . Then for all $\nu \in \mathbb{P}(\Omega)$,

$$I_K(\mu^{n-1}, \nu) \le \frac{n-1}{n} I_K(\mu) + \frac{1}{n} I_K(\nu).$$
 (3.11)

Proof. Let $\nu \in \mathbb{P}(\Omega)$. Assume $t \in (0,1)$ such that (3.8) holds. Then

$$tI_K(\nu) + (1-t)I_K(\mu) \ge I_K(t\nu + (1-t)\mu)$$

$$= \sum_{j=0}^n (1-t)^j t^{n-j} \binom{n}{j} I_K(\mu^j, \nu^{n-j}).$$

Clearly then

$$\left(t - t^n\right) I_K(\nu) + \left((1 - t) - (1 - t)^n\right) I_K(\mu) \ge \sum_{j=1}^{n-1} (1 - t)^j t^{n-j} \binom{n}{j} I_K(\mu^j, \nu^{n-j}),$$

and dividing by t(1-t), we obtain

$$\left(\sum_{k=0}^{n-2} t^k\right) I_K(\nu) + \left(\sum_{l=0}^{n-2} (1-t)^l\right) I_K(\mu) \ge \sum_{j=1}^{n-1} (1-t)^{j-1} t^{n-j-1} \binom{n}{j} I_K(\mu^j, \nu^{n-j}).$$

If I_K is convex at μ , then we may take the limit as t goes to 0, which gives us

$$I_K(\nu) + (n-1)I_K(\mu) \ge nI_K(\mu^{n-1}, \nu).$$

Observe that if I_K is convex (in particular, convex at ν), switching the roles of μ and ν we obtain

$$(n-1)I_K(\nu) + I_K(\mu) \ge nI_K(\mu, \nu^{n-1}).$$

Therefore, in the case n = 2, 3, Lemma 3.8 provides the converse of Proposition 3.6, in other words, I_K is convex if and only if it satisfies the arithmetic mean inequalities (3.9). We are now ready to demonstrate the equivalence of the conditional positive definiteness of K and the convexity of K for the two-input case.

Proposition 3.9. Suppose $K: \Omega^2 \to \mathbb{R}$ is continuous and symmetric. Then K is conditionally positive definite if and only if I_K is convex.

Proof. Corollary 3.7 gives us one direction. For the other, assume that I_K is convex. Let $\mu \in \mathcal{M}(\Omega)$ satisfy $\mu(\Omega) = 0$. Then there exist $\mu_+, \mu_- \in \mathbb{P}(\Omega)$ and some constant $c \geq 0$ such that $\mu = c(\mu_+ - \mu_-)$. Lemma 3.8 with n = 2 implies that $I_K(\mu_+, \mu_-) \leq \frac{1}{2}(I_K(\mu_+) + I_K(\mu_-))$ and therefore

$$I_K(\mu) = c^2 \Big(I_K(\mu_+) - 2I_K(\mu_+, \mu_-) + I_K(\mu_-) \Big) \ge 0,$$

i.e. K is conditionally positive definite.

It is not completely clear whether this equivalence holds for $n \geq 3$, but evidence suggests that it does not. Indeed, Proposition 6.5 provides an example of a three-input kernel with $\Omega = \mathbb{S}^{d-1}$, which is not conditionally 3-positive definite, but at the same time the energy functional is convex at σ (although we don't know if it is convex at all measures in $\mathbb{P}(\mathbb{S}^{d-1})$) and is minimized by σ .

In this regard, we would also like to point out that a number of our results about energy minimizers do not require the full power of convexity of I_K on $\mathbb{P}(\Omega)$, but rather just the convexity at the presumptive minimizer μ . In particular, condition (4.2), which appears in Theorems 4.4 and 4.8, is implied by inequality (3.11) of Lemma 3.8, and hence it holds if I_K is convex at μ .

Using convexity of the energy functional, one can draw a connection between minimizing the n-input energy I_K and the (n-1)-input energy $I_{U_K^{\mu}}$, thus obtaining our first result about minimizers of multi-input energies.

Proposition 3.10. Let $n \geq 3$. Assume that $K : \Omega^n \to \mathbb{R}$ is continuous and symmetric, I_K is convex, and that $\mu \in \mathbb{P}(\Omega)$ is a minimizer of $I_{U_K^{\mu}}$. Then μ is a minimizer of I_K .

Proof. We first prove that if the energy I_K is convex and $\mu, \nu \in \mathbb{P}(\Omega)$, then

$$I_K(\nu) - I_K(\mu) \ge \frac{n}{n-1} \Big(I_{U_K^{\mu}}(\nu) - I_{U_K^{\mu}}(\mu) \Big).$$
 (3.12)

Indeed, we have $I_{U_K^{\mu}}(\mu) = I_K(\mu)$ and, by Lemma 3.8, $I_{U_K^{\mu}}(\nu) = I_K(\mu, \nu^{n-1}) \le \frac{1}{n} I_K(\mu) + \frac{n-1}{n} I_K(\nu)$. Thus,

$$I_K(\nu) - I_K(\mu) - n\Big(I_{U_K^{\mu}}(\nu) - I_{U_K^{\mu}}(\mu)\Big) = I_K(\nu) - nI_K(\mu, \nu^{n-1}) + (n-1)I_K(\mu)$$
$$\geq (n-2)\Big(I_K(\mu) - I_K(\nu)\Big),$$

which implies inequality (3.12).

Inequality (3.12), together with the fact that μ is a minimizer of $I_{U_K^{\mu}}$, implies that for all $\nu \in \mathbb{P}(\Omega)$, we have

$$I_K(\nu) - I_K(\mu) \ge \frac{n}{n-1} \Big(I_{U_K^{\mu}}(\nu) - I_{U_K^{\mu}}(\mu) \Big) \ge 0,$$

hence μ minimizes I_K .

Proposition 3.10 can be viewed as a precursor of some of our more advanced results from Section 4 which show that there is a strong relation between μ minimizing the n-input energy I_K and the energy functional $I_{U_K^{\mu^k}}$ with a lower number of inputs. In fact, Theorem 4.8 contains Proposition 3.10 as a special case. We have nevertheless decided to include this proposition, as it admits a very transparent and elementary proof, which also provides a quantitative relation between the minimization of I_K and $I_{U_K^{\mu}}$.

4. Minimizers of the energy functional

We finally turn to some of the general results about minimizers of energies with multivariate kernels. In the classical two-input case, properties of minimizing measures are closely related to their potentials, see e.g. [Bj, BHS]. Direct analogues of such statements can be obtained for multi-input energies. We start with the necessary condition, which states that the potential of a minimizer is constant on its support. As before, in all of the statements of this section we assume that $K: \Omega^n \to \mathbb{R}$ is continuous and symmetric, even if not explicitly stated.

Theorem 4.1. Let $K: \Omega^n \to R$ be continuous and symmetric. Suppose that μ is a minimizer of I_K over $\mathbb{P}(\Omega)$. Then $U_K^{\mu^{n-1}}(x) = I_K(\mu)$ on $\sup(\mu)$ and $U_K^{\mu^{n-1}}(x) \geq I_K(\mu)$ on Ω .

Proof. The proof is a simple extension of the proof of Theorem 2 in [Bj], and we include it for the sake of completeness. Let $\nu \in \mathcal{M}(\Omega)$ be such that $\nu(\Omega) = 0$ and $\mu(A) + \varepsilon \nu(A) \geq 0$ for all Borel subsets $A \subseteq \Omega$ and $0 \leq \varepsilon \leq 1$. This clearly means that $\mu + \varepsilon \nu \in \mathbb{P}(\Omega)$, so

$$I_K(\mu) \le I_K(\mu + \varepsilon \nu) = \sum_{k=0}^n \binom{n}{k} \varepsilon^k I_K(\mu^{n-k}, \nu^k).$$

Thus, for $0 \le \varepsilon \le 1$,

$$0 \le \varepsilon \left(\sum_{k=1}^{n} \binom{n}{k} \varepsilon^{k-1} I_K(\mu^{n-k}, \nu^k) \right).$$

This means that $I_K(\mu^{n-1}, \nu) \geq 0$.

Suppose, indirectly, that there exist $a, b \in \mathbb{R}$, $z \in \text{supp}(\mu)$ and $y \in \Omega$ such that

$$a = U_K^{\mu^{n-1}}(z) > U_K^{\mu^{n-1}}(y) = b.$$

Let B be a ball centered at z, small enough so that $y \notin B$ and oscillation of $U_K^{\mu^{n-1}}(x)$ is at most $\frac{a-b}{2}$, and let $m = \mu(B)$. Let ν be defined by

$$\nu(A) = m\delta_{\nu}(A) - \mu(A \cap B). \tag{4.1}$$

Then

$$I_K(\mu^{n-1}, \nu) = U_K^{\mu^{n-1}}(y) \cdot m - \int_B U_K^{\mu^{n-1}}(x) d\mu(x) \le bm - \left(a - \frac{a-b}{2}\right)m < 0,$$

which is a contradiction. Thus, if $U_K^{\mu^{n-1}}(z) = a$ for some $z \in \text{supp}(\mu)$, then $U_K^{\mu^{n-1}}(x) \geq a$ for all $x \in \Omega$. Our claim then follows.

Definition 4.2. We shall say that μ is a local minimizer of I_K if it is a local minimizer in every direction, in other words, if for each $\nu \in \mathbb{P}(\Omega)$, there exists $t_{\nu} \in (0,1]$ such that for all $t \in [0,t_{\nu}]$ we have

$$I_K((1-t)\mu + t\nu) \ge I_K(\mu).$$

Observe that this definition differs from the definition of local minimizers with respect to some metric, such as the Wasserstein d_{∞} metric or the total variation norm (the difference is similar to that between the Gateaux and Fréchet derivatives).

Analyzing the proof of Theorem 4.1, we find that for ν defined in (4.1), we can write $\mu + \varepsilon \nu = (1 - \varepsilon)\mu + \varepsilon \widetilde{\nu}$ with $\widetilde{\nu} = \mu + \nu \in \mathbb{P}(\Omega)$. Hence, one arrives at a contradiction even if μ is just a local minimizer.

Corollary 4.3. The statement of Theorem 4.1 remains true if we only assume that μ is a local (not global) minimizer of I_K .

In general, the converse to Theorem 4.1 is not true. However, with some additional convexity assumptions, the necessary condition also becomes sufficient.

Theorem 4.4. Let $K: \Omega^n \to \mathbb{R}$ be symmetric and continuous. Suppose that for some $\mu \in \mathbb{P}(\Omega)$, there exists a finite constant M such that $U_K^{\mu^{n-1}}(x) \geq M$ on Ω and $U_K^{\mu^{n-1}}(x) = M$ on $\operatorname{supp}(\mu)$. Suppose further that for all $\nu \in \mathbb{P}(\Omega)$, there exists some $\alpha \in (0,1)$, possibly depending on ν , such that

$$I_K(\mu^{n-1}, \nu) \le \alpha I_K(\nu) + (1 - \alpha)I_K(\mu).$$
 (4.2)

Then μ is a minimizer of I_K .

Proof. For any $\nu \in \mathbb{P}(\Omega)$, for some $\alpha \in (0,1)$, we have

$$I_K(\mu) = \int_{\Omega} U_K^{\mu^{n-1}}(x) d\mu(x) \le \int_{\Omega} U_K^{\mu^{n-1}}(x) d\nu(x) = I_K(\mu^{n-1}, \nu) \le \alpha I_K(\nu) + (1 - \alpha) I_K(\mu),$$
hence $I_K(\mu) \le I_K(\nu)$.

Some remarks concerning the assumptions of Theorem 4.4, i.e. condition (4.2), are in order. Due to Lemma 3.8, convexity of the energy functional I_K at μ implies condition (4.2) with $\alpha = \frac{1}{n}$. In turn, if K is conditionally n-positive definite, Corollary 3.7 states that I_K is convex, and hence again condition (4.2) is satisfied (alternatively, Lemma 3.2 shows directly that conditional n-positive definiteness of K implies the convexity condition (4.2) of Theorem 4.4 with $\alpha = \frac{1}{n}$). The hierarchy of these conditions can be summarized in the following diagram:

$$K$$
 is n -positive definite $\Longrightarrow K$ is conditionally n -positive definite $\Longrightarrow I_K$ is convex $\Longrightarrow I_K$ is convex at $\mu \Longrightarrow \text{condition (4.2) holds.}$

Therefore, Theorem 4.4 (as well as other statements relying on (4.2), e.g. Lemma 4.6 or Theorem 4.8) may be applied under the assumptions that K is (conditionally) n-positive definite or that I_K is convex at μ .

We also make the following remark: in the case when μ has full support, i.e. $\mathrm{supp}(\mu) = \Omega$, if the first condition of Theorem 4.4 holds, i.e. $U_K^{\mu^{n-1}}(x) = M$ for all $x \in \Omega$, then $I_K(\mu^{n-1}, \nu) = I_K(\mu)$, and the assumption (4.2) is obviously the same as the conclusion of Theorem 4.4. This does not, however, render this case of the theorem useless – on the contrary, if one replaces (4.2) with one of the stronger conditions in (4.3), one obtains an interesting and meaningful statement. (This shows that the most of the content is hidden in the implications presented in (4.3).) We summarize this case in a separate corollary, as it will be of use later.

Corollary 4.5. Let $K: \Omega^n \to \mathbb{R}$ be symmetric and continuous. Suppose that $\mu \in \mathbb{P}(\Omega)$ has full support $\operatorname{supp}(\mu) = \Omega$ and that there exists a constant M such that $U_K^{\mu^{n-1}}(x) = M$ on Ω . Assume also that any of the conditions in (4.3) holds (e.g., K is n-positive definite or I_K is convex). Then μ is a minimizer of I_K .

We also observe that Corollary 4.3 and Theorem 4.4 imply the following local-to-global principle for minimizers of I_K under convexity assumptions.

Lemma 4.6. Let $n \geq 2$ and let μ be a local minimizer of the energy functional I_K . Assume also that condition (4.2) is satisfied. Then μ is a global minimizer of I_K over $\mathbb{P}(\Omega)$.

Proof. Corollary 4.3 shows that the first condition of Theorem 4.4 holds. Together with condition (4.2), this implies that μ is a global minimizer of I_K .

Naturally, the set of minimizers of a convex functional is convex. By Corollary 3.7, for conditionally n-positive definite kernels, the energy I_K is convex, i.e. minimizers of I_K form a convex set in this case.

Proposition 4.7. Let K be a conditionally n-positive definite kernel. Then the set of minimizers of the energy I_K is convex.

While Theorems 4.1 and 4.4 are straightforward generalizations of the corresponding facts for the classical two-input energies, they lead to some interesting consequences for energies with multivariate kernels. In particular, we start by showing that under condition (4.2), if μ minimizes the lower input energy with the kernel $U_K^{\mu^k}$, then it also minimizes the original n-input energy I_K .

Theorem 4.8. Let $K: \Omega^n \to \mathbb{R}$, $n \geq 3$, be symmetric and continuous. Assume that for some $1 \leq k \leq n-2$, the measure $\mu \in \mathbb{P}(\Omega)$ (locally) minimizes the (n-k)-input energy $I_{U_K^{\mu k}}$. Assume also that μ satisfies condition (4.2) of Theorem 4.4. Then μ minimizes the n-input energy I_K .

Proof. Theorem 4.1 (or Corollary 4.3) applied to the kernel $U_K^{\mu^k}$ implies that for all $x \in \Omega$

$$U_K^{\mu^{n-1}}(x) = U_{U_{\kappa}^{\mu^k}}^{\mu^{n-k-1}}(x) \ge I_{U_K^{\mu^k}}(\mu) = I_K(\mu)$$

with equality for $x \in \text{supp}(\mu)$. Condition (4.2) then allows one to invoke Theorem 4.4, which shows that μ minimizes I_K .

The converse to Theorem 4.8 holds for k=n-2 even without any convexity assumptions: in this case, if μ locally minimizes I_K , it also locally minimizes the two-input energy $I_{U_K^{\mu^{n-2}}}$. Moreover, under the additional condition that μ has full support, one can deduce that the measure μ is a global minimizer of $I_{U_K^{\mu^{n-2}}}$, see parts (i)-(ii) of Theorem 4.9 below. Furthermore, this implication may be reversed, if one additionally assumes that μ uniquely minimizes $I_{U_K^{\mu^{n-2}}}$. Observe that, unlike Theorem 4.8, part (iii) of Theorem 4.9 does not require any of the conditions of (4.3) and, unlike part (ii), it does not require the condition $\sup(\mu) = \Omega$.

Theorem 4.9. Let $K: \Omega^n \to \mathbb{R}$, $n \geq 3$, be symmetric and continuous and let $\mu \in \mathbb{P}(\Omega)$.

- (i) Let μ be a local minimizer of I_K . Then μ is a local minimizer of the two-input energy $I_{U_{\nu}^{\mu^{n-2}}}$.
- (ii) Let μ be a local minimizer of I_K and assume, in addition, that μ has full support, i.e. $\sup_{\mu} \Gamma(\mu) = \Omega$. Then μ minimizes the two-input energy $I_{U_{\mu}^{n-2}}$ over $\mathbb{P}(\Omega)$.
- (iii) If μ is the unique minimizer of $I_{U_K^{\mu^{n-2}}}$ in $\mathbb{P}(\Omega)$, then μ is a local minimizer of I_K .

Proof. Fix an arbitrary measure $\nu \in \mathbb{P}(\Omega)$. For $t \in [0,1]$, let us define two functions $g_{\nu}(t) = I_K((1-t)\mu + t\nu)$ and $h_{\nu}(t) = I_{U_K^{\mu^{n-2}}}((1-t)\mu + t\nu) = I_K(\mu^{n-2}, ((1-t)\mu + t\nu)^2)$. We have

$$g_{\nu}(t) = (1-t)^{n} I_{K}(\mu) + nt(1-t)^{n-1} I_{K}(\mu^{n-1}, \nu) + \binom{n}{2} t^{2} (1-t)^{n-2} I_{K}(\mu^{n-2}, \nu^{2}) + R_{\nu}(t),$$

where each term in $R_{\nu}(t)$ contains a factor of the form t^k with $k \geq 3$ and, therefore, $R'_{\nu}(0) = R''_{\nu}(0) = 0$,

$$h_{\nu}(t) = (1-t)^2 I_K(\mu) + 2t(1-t)I_K(\mu^{n-1}, \nu) + t^2 I_K(\mu^{n-2}, \nu^2).$$

A direct (elementary, but lengthy) computation, which we omit, shows that

$$h'_{\nu}(0) = \frac{2}{n}g'_{\nu}(0) = 2(I_K(\mu^{n-1}, \nu) - I_K(\mu)), \tag{4.4}$$

$$h_{\nu}''(0) = \frac{2}{n(n-1)}g_{\nu}''(0) = 2(I_K(\mu) - 2I_K(\mu^{n-1}, \nu) + I_K(\mu^{n-2}, \nu^2)). \tag{4.5}$$

We now start by proving (i). Let μ be a local minimizer of I_K . According to Corollary 4.3, we have that $U_K^{\mu^{n-1}}(x) \geq I_K(\mu)$ on Ω and therefore, $I_K(\mu^{n-1}, \nu) \geq I_K(\mu)$ for any $\nu \in \mathbb{P}(\Omega)$. Since g_{ν} has a local minimum at t=0, either $g'_{\nu}(0)>0$, or $g'_{\nu}(0)=0$ and $g''_{\nu}(0)\geq 0$. In the first case, we also have $h'_{\nu}(0)>0$. In the second case, $h'_{\nu}(0)=0$ and $h''_{\nu}(0)\geq 0$, and since h_{ν} is quadratic, this implies that $h_{\nu}(t)=at^2+b$ with $a\geq 0$. Thus, h_{ν} has a local minimum at t=0 for each $\nu\in\mathbb{P}(\Omega)$, i.e. μ is a local minimizer of $I_{U_{\nu}^{\mu^{n-2}}}$.

If in addition μ has full support, then Corollary 4.3 implies that for any $\nu \in \mathbb{P}(\Omega)$, we have $I_K(\mu^{n-1}, \nu) = I_K(\mu)$. Therefore, relations (4.4)-(4.5), together with the fact that g_{ν} has a local minimum at t = 0, show

that $g'_{\nu}(0) = 0$, hence $g''_{\nu}(0) \geq 0$, and at the same time

$$g_{\nu}''(0) = n(n-1)(I_K(\mu^{n-2}, \nu^2) - I_K(\mu)) = n(n-1)\Big(I_{U_K^{\mu^{n-2}}}(\nu) - I_{U_K^{\mu^{n-2}}}(\mu)\Big). \tag{4.6}$$

Hence, μ is a global minimizer of $I_{U_{\kappa}^{\mu^{n-2}}},$ which proves part (ii).

To prove (iii), assume that μ is the unique global minimizer of $I_{U_K^{\mu^{n-2}}}$. Observe that, since the potential of $U_K^{\mu^{n-2}}$ with respect to μ is $U_K^{\mu^{n-1}}$, Theorem 4.1 applied to $U_K^{\mu^{n-2}}$ implies that, just like in part (i), we have $I_K(\mu^{n-1},\nu) \geq I_K(\mu)$. Thus, $g_{\nu}'(0) \geq 0$ by (4.4). If $g_{\nu}'(0) > 0$, there is a local minimum at t=0. If, however, $g_{\nu}'(0) = 0$, then $I_K(\mu^{n-1},\nu) = I_K(\mu)$ and relation (4.6) holds. Since μ uniquely minimizes $I_{U_K^{\mu^{n-2}}}$, this proves that $g_{\nu}''(0) > 0$ for $\nu \neq \mu$. Hence, in each case, g_{ν} has a local minimum at t=0, i.e. μ is a local minimizer of I_K .

For classical pairwise interaction energies, it is well known that the kernel is conditionally positive definite on the support of the minimizer (see, e.g., [FSch]), therefore, we obtain the following corollary to part (ii) Theorem 4.9:

Corollary 4.10. Assume that $\mu \in \mathbb{P}(\Omega)$ with $\operatorname{supp}(\mu) = \Omega$ is a local minimizer of I_K . Then the (n-2)fold potential of K with respect to μ , i.e. the two-variable function $U_K^{\mu^{n-2}}(x,y)$, is conditionally positive
definite on Ω .

Observe that, if the kernel K is conditionally n-positive definite, then, according to Lemma 2.3, $U_K^{\mu^{n-2}}(x,y)$ is conditionally positive definite. Moreover, Theorem 4.8 applies for conditionally positive definite kernels K. Therefore, the statement of Corollary 4.10 may be viewed as a partial converse of Theorem 4.8 for conditionally positive definite kernels. This interplay will manifest itself in an even stronger fashion on the sphere, the situation to be explored in Section 5.

5. Multi-input energy on the sphere

We now restrict our attention to the case when Ω is the unit sphere, i.e. $\Omega = \mathbb{S}^{d-1} \subset \mathbb{R}^d$, where the symmetries and structure of the domain allow one to deduce additional information about energy minimization.

We shall denote by σ the normalized uniform surface measure on the sphere. One of the most natural questions is whether σ minimizes the energy functional over $\mathbb{P}(\mathbb{S}^{d-1})$, or, in other words, whether energy minimization induces uniform distribution.

In this section, we shall be interested in kernels, which (in addition to being continuous and symmetric) are *rotationally invariant*, i.e. have the form

$$K(x_1, \dots, x_n) = F\left((\langle x_i, x_j \rangle)_{i,j=1}^n\right), \tag{5.1}$$

in other words, they depend only on the Gram matrix of $\{x_1,\ldots,x_n\}\subset\mathbb{S}^{d-1}$.

When n = 2, one obtains classical pairwise interaction kernels of the form $K(x, y) = F(\langle x, y \rangle)$. The theory of both discrete and continuous energies with such kernels on the sphere is very rich and goes back at least to Schoenberg [S].

In the case n=3 rotationally invariant kernels are functions of the form

$$K(x, y, z) = F(\langle x, y \rangle, \langle y, z \rangle, \langle z, x \rangle) = F(u, v, t), \tag{5.2}$$

where we set $u = \langle x, y \rangle$, $v = \langle y, z \rangle$, $t = \langle z, x \rangle$, and we shall keep this notation throughout the text (the slightly non-alphabetic order is inherited from [CW]).

Observe that, if the *n*-input kernel K is rotationally invariant, its potential with respect to σ is again rotationally invariant. Indeed, for any $V \in SO(d)$, we have

$$U_K^{\sigma}(Vx_1, \dots, Vx_{n-1}) = U_K^{\sigma}(x_1, \dots, x_{n-1}), \tag{5.3}$$

which easily follows from (5.1) and the facts that $\langle x_i, x_j \rangle = \langle Vx_i, Vx_j \rangle$ and $\langle Vx_i, x_n \rangle = \langle x_i, V^{-1}x_n \rangle$, $1 \leq i, j \leq n-1$, together with the rotational invariance of σ , i.e. $d\sigma(x_n) = d\sigma(V^{-1}x_n)$. Iterating

this observation, one finds that all k-fold potentials of K with respect to σ , i.e. functions $U_K^{\sigma^k}$ with $1 \le k \le n-1$, are rotationally invariant. In particular, when k=n-2, the two-input kernel $U_K^{\sigma^{n-2}}$ depends only on the inner product of the inputs, and for k=n-1, the potential $U_K^{\sigma^{n-1}}$ is just a constant:

$$U_K^{\sigma^{n-2}}(x,y) = G(\langle x,y\rangle) = G(u) \quad \text{and} \quad U_K^{\sigma^{n-1}}(x) = \text{const} = I_K(\sigma). \tag{5.4}$$

Recall that Theorem 4.1 would guarantee the latter condition in the case when σ is a minimizer of I_K . However, for rotationally invariant kernels, this is automatically satisfied, which facilitates the application of the results of Section 4 and will play an important role later, in Theorem 5.1.

Turning to the primary task of understanding when σ minimizes I_K , we first remind ourselves that in the classical case of a two-input energy with a rotationally invariant kernel $G(\langle x, y \rangle)$ on \mathbb{S}^{d-1} , the answer to this question is well understood. In particular, the following three conditions are equivalent, see e.g. [BDM]:

- (i) The uniform surface measure σ minimizes I_G over $\mathbb{P}(\mathbb{S}^{d-1})$.
- (ii) The kernel G is conditionally positive definite on \mathbb{S}^{d-1} .
- (iii) The kernel G is positive definite on \mathbb{S}^{d-1} up to a constant term, i.e. there exists a constant $c \in \mathbb{R}$ such that G + c is positive definite on \mathbb{S}^{d-1} (in fact, one can take $c = -I_G(\sigma)$).

Our goal is to generalize these statements (at least partially) to the case of multi-input energies. We observe that, if a symmetric rotationally invariant kernel K is conditionally n-positive definite on \mathbb{S}^{d-1} , then, according to Lemma 2.3, the potential $G(u) = U_K^{\sigma^{n-2}}(x,y)$ is also conditionally positive definite, and hence, by the discussion above, σ is a minimizer of the two-input energy $I_{U_K^{\sigma^{n-2}}}$. Therefore, since conditionally n-positive definite kernels satisfy condition (4.2), Theorem 4.8 with k=n-2 applies and we obtain the following statement:

Theorem 5.1. Suppose that $K: (\mathbb{S}^{d-1})^n \to \mathbb{R}$ is continuous, symmetric, rotationally invariant, and conditionally n-positive definite on \mathbb{S}^{d-1} . Then σ is a minimizer of I_K over $\mathbb{P}(\Omega)$.

This theorem also easily follows from Theorem 4.4 and the remarks thereafter (or, more precisely, from Corollary 4.5), since, as explained above, the potential $U_K^{\sigma^{n-1}}$ is constant on \mathbb{S}^{d-1} .

Notice that, unlike some statements of Section 4, e.g. Theorem 4.8, for rotationally invariant kernels in the theorem above one does not need to assume anything about energies with a lower number of inputs – conditional positive definiteness alone suffices.

Theorem 5.1 immediately yields some interesting examples:

Corollary 5.2. Let $f:[-1,1] \to \mathbb{R}$ be a real-analytic function with nonnegative Maclaurin coefficients and let F(u,v,t) = f(uvt). Then, for K defined as in (5.2), the uniform surface measure σ minimizes the energy I_K over $\mathbb{P}(\mathbb{S}^{d-1})$.

Proof. Observe first that in this setup, if K_z is positive definite for one point $z \in \mathbb{S}^{d-1}$, it is also positive definite for each $z \in \mathbb{S}^{d-1}$ due to rotational invariance, i.e. Definition 2.2 only needs to be checked at one point. Consider first F(u, v, t) = uvt and fix any $z \in \mathbb{S}^{d-1}$, e.g., $z = e_1$. Then for any $v \in \mathcal{M}(\mathbb{S}^{d-1})$,

$$I_{K_{e_1}}(\nu) = \int_{\mathbb{S}^{d-1}} \int_{\mathbb{S}^{d-1}} \langle x, y \rangle x_1 y_1 d\nu(x) d\nu(y) = \sum_{i=1}^d \left(\int_{\mathbb{S}^{d-1}} x_1 x_i \, d\nu(x) \right)^2 \geq 0,$$

i.e. the kernel $K(x,y,z) = \langle x,y \rangle \langle y,z \rangle \langle z,x \rangle = uvt$ is 3-positive definite, and hence, by Lemma 2.4, so are all of its integer powers, positive linear combinations and their limits. The conclusion now follows from Theorem 5.1.

This corollary provides a whole array of examples: for instance, three-input energies with kernels K(x,y,z) = uvt, or $(uvt)^n$, or e^{uvt} are all minimized by σ . We remark that, while for K = uvt this statement could be proved using semidefinite programing, for higher powers $(uvt)^n$ this would be extremely difficult technically, and for kernels like e^{uvt} almost impossible.

For even exponents, the energies with the kernels $K = (uvt)^{2k}$ can be viewed as three-input generalizations of the well-known p-frame potentials [EO, BGMPV], which are closely related to tight frames

and projective designs [BF, SG]. We also point out that Proposition 6.2 provides a more general class of n-positive definite kernels, which contains K = uvt as a special case.

Unfortunately, unlike the classical two-input case, the converse to Theorem 5.1 is not true: Propositions 6.5, 6.9, and 6.10 show that some kernels, naturally arising in semidefinite programming and geometry, fail to be conditionally n-positive definite, even though σ minimizes corresponding energies (see Theorems 6.6 and 6.7). In other words, conditional n-positive definiteness of the kernel is not equivalent to the fact that σ minimizes the energy.

We suspect that the property that σ minimizes I_K is equivalent to the fact that $U_K^{\sigma^{n-2}}$ is conditionally positive definite, i.e. the two-input energy $I_{U_K^{\sigma^{n-2}}}$ is minimized by σ . This conjecture is supported by all the examples known to us. Conditional positive-definiteness of $U_K^{\sigma^{n-2}}$ obviously follows from conditional n-positive definiteness of K, due to Lemma 2.3, but the converse implication is not true, see e.g. Proposition 6.5. In fact, all the kernels discussed in Section 6.3 (Propositions 6.5, 6.9, and 6.10) possess this property: they are not 3-positive definite, but their potentials U_K^{σ} with respect to σ are (conditionally) positive definite, and the correspondig energies I_K are minimized by σ .

Theorem 5.3 below (which is essentially a restatement of Theorem 4.9 for the spherical case, along with the fact that σ has full support) shows that conditional positive definiteness of $U_K^{\sigma^{n-2}}$ is implied if σ is a local minimizer of I_K , and a partial converse to this statement also holds. Observe that, if the conjecture above is true, then being a local and global minimizer are equivalent for σ : this fact is indeed true for the two-input energies, see [BGMPV].

Theorem 5.3. Let $K: (\mathbb{S}^{d-1})^n \to \mathbb{R}$ be a continuous, symmetric, and rotationally invariant kernel.

- (i) Assume that σ is a local minimizer of I_K in $\mathbb{P}(\mathbb{S}^{d-1})$. Then the uniform measure σ is a global minimizer of the two-input energy $I_{U_K^{\sigma^{n-2}}}$, or, equivalently, $U_K^{\sigma^{n-2}}$ is conditionally positive definite on the sphere \mathbb{S}^{d-1} .
- (ii) Assume that σ is the unique global minimizer of $I_{U_K^{\sigma^{n-2}}}$ over $\mathbb{P}(\mathbb{S}^{d-1})$. Then σ is a local minimizer of the n-input energy I_K .

Theorem 5.3 above shows that if σ is a global minimizer of I_K , then the potential $U_K^{\sigma^{n-2}}$ is conditionally positive definite. We do not know whether the converse of this statement holds. One can show, however, at least for n=3 that if σ minimizes $I_{U_K^{\sigma}}$ (in other words, U_K^{σ} is conditionally positive definite), but fails to minimize I_K , then the global minimizer of I_K cannot be supported on the whole sphere.

Lemma 5.4. Let $K: (\mathbb{S}^{d-1})^3 \to \mathbb{R}$ be a continuous, symmetric, and rotationally invariant three-input kernel. Assume that U_K^{σ} is conditionally positive definite on the sphere \mathbb{S}^{d-1} (i.e. σ minimizes $I_{U_K^{\sigma}}$), but at the same time σ is not a minimizer of I_K . Let μ be a minimizer of I_K . Then $\operatorname{supp}(\mu) \subsetneq \mathbb{S}^{d-1}$.

Proof. Assume, by contradiction, that $\operatorname{supp}(\mu) = \mathbb{S}^{d-1}$. Then, by Theorem 4.1, $U_K^{\mu^2}(x) = I_K(\mu)$ for every $x \in \mathbb{S}^{d-1}$, and therefore,

$$I_{U_K^{\sigma}}(\mu) = I_K(\mu, \mu, \sigma) = \int_{\mathbb{S}^{d-1}} U_K^{\mu^2}(x) \, d\sigma(x) = I_K(\mu).$$

On the other hand, obviously, $I_K(\sigma) = I_{U_K^{\sigma}}(\sigma)$. Since μ is a minimizer of I_K , and σ is not, we have $I_K(\mu) < I_K(\sigma)$. This implies that $I_{U_K^{\sigma}}(\mu) < I_{U_K^{\sigma}}(\sigma)$, which contradicts the conditional positive definiteness of U_K^{σ} .

6. Positive definite kernels

Corollary 5.2 of the previous section already provided a class of 3-positive definite functions. In this section we provide several other classes of kernels that are (conditionally) n-positive definite.

6.1. General classes of (conditionally) n-positive definite kernels. We start with some very natural examples, which show how to construct (conditionally) n-positive definite kernels from kernels with fewer inputs. In particular, we show that an n-input kernel can be constructed from m-input ones, m < n, by

considering the sum or product over all m-element subsets of inputs. We first deal with the statement about the sum.

Proposition 6.1. Let $2 \leq m \leq n-1$, and suppose $H: \Omega^m \to \mathbb{R}$ is continuous, symmetric, and conditionally m-positive definite. Then

$$K(z_1, ..., z_n) := \sum_{1 < j_1 < j_2 < \cdots < j_m < n} H(z_{j_1}, z_{j_2}, ..., z_{j_m})$$

is conditionally n-positive definite.

Proof. Let ν be a finite signed Borel measure on Ω such that $\nu(\Omega) = 0$. Then for any fixed $z_1, ..., z_{n-2} \in \Omega$, since H is conditionally m-positive definite, we have

$$\begin{split} \int_{\Omega} \int_{\Omega} K(z_{1}, \ldots, z_{n-2}, x, y) d\nu(x) d\nu(y) &= \int_{\Omega} \int_{\Omega} \sum_{1 \leq j_{1} < \cdots < j_{m-2} \leq n-2} H(z_{j_{1}}, \ldots, z_{j_{m-2}}, x, y) d\nu(x) d\nu(y) \\ &+ \int_{\Omega} \int_{\Omega} \sum_{1 \leq k_{1} < \cdots < k_{m-1} \leq n-2} \Big(H(z_{k_{1}}, \ldots, z_{k_{m-1}}, x) + H(z_{k_{1}}, \ldots, z_{k_{m-1}}, y) \Big) d\nu(x) d\nu(y) \\ &+ \int_{\Omega} \int_{\Omega} \sum_{1 \leq l_{1} < \cdots < l_{m} \leq n-2} H(z_{l_{1}}, \ldots, z_{l_{m}}) d\nu(x) d\nu(y) \\ &= \sum_{1 \leq j_{1} < \cdots < j_{m-2} \leq n-2} \int_{\Omega} \int_{\Omega} H(z_{j_{1}}, \ldots, z_{j_{m-2}}, x, y) d\nu(x) d\nu(y) \geq 0, \end{split}$$

which shows that K is conditionally n-positive definite.

We can also prove an analogue of Proposition 6.1 for products of positive definite functions.

Proposition 6.2. Let $2 \le m \le n-1$ and assume that $H: \Omega^m \to \mathbb{R}$ is continuous, symmetric, and m-positive definite. If H is a nonnegative function or m = n - 1, then

$$K(z_1, ..., z_n) = \prod_{1 \le j_1 < \dots < j_m \le n} H(z_{j_1}, ..., z_{j_m})$$

is n-positive definite.

Proof. Fix $z_1, \ldots, z_{n-2} \in \Omega$. We can write

$$K(z_1, \dots, z_{n-2}, x, y) = \prod_{1 \le j_1 < \dots < j_m \le n-2} H(z_{j_1}, \dots, z_{j_m})$$
(6.1)

$$\times \prod_{1 \le j_1 < \dots < j_{m-1} \le n-2} H(z_{j_1}, \dots, z_{j_{m-1}}, x)$$
 (6.2)

$$\times \prod_{1 < j_1 < \dots < j_{m-1} < n-2} H(z_{j_1}, \dots, z_{j_{m-1}}, y)$$
(6.3)

$$\times \prod_{1 \le j_1 < \dots < j_{m-1} \le n-2} H(z_{j_1}, \dots, z_{j_{m-1}}, y)$$

$$\times \prod_{1 \le j_1 < \dots < j_{m-2} \le n-2} H(z_{j_1}, \dots, z_{j_{m-2}}, x, y).$$
(6.3)

Observe that the product in line (6.1) is non-negative when $H \ge 0$ or if m = n - 1 (the product is empty in the latter case). The product of lines (6.2) and (6.3) is positive definite as a function of x and y: indeed, it has the form $F(x,y) = \phi(x)\phi(y)$ and hence

$$I_F(\mu) = \left(\int_{\Omega} \phi(x) d\mu(x)\right)^2 \ge 0$$

for any $\mu \in \mathcal{M}(\Omega)$. Finally, every factor in the product in line (6.4) is positive definite as a function of x and y, because H is m-positive definite. Thus, Schur's product theorem (see Lemma 2.4) ensures that the whole product is positive definite as a function of x and y, therefore, K is n-positive definite.

Propositions 6.1 and 6.2 provide us with large classes of n-positive definite kernels. However, these constructions do not exhaust all such kernels. In the following subsection, we provide examples of three-positive definite kernels, which are not obtained from two-input kernels by the methods described above.

6.2. Three-positive definite kernels on the sphere. We also provide some examples of kernels on the unit sphere \mathbb{S}^{d-1} . We use the same notation as in Section 5: for $x, y, z \in \mathbb{S}^{d-1}$, we set $u = \langle x, y \rangle$, $v = \langle y, z \rangle$, and $t = \langle z, x \rangle$.

In Corollary 5.2, we showed that K = uvt is 3-positive definite on the sphere. Observe that this is a specific case of Proposition 6.2 above, since $\langle x, y \rangle$ is a positive definite function on \mathbb{S}^{d-1} . More generally, Proposition 6.2 implies that any kernel of the form K(x, y, z) = h(u)h(v)h(t) is 3-positive definite, as long as h is a positive definite function on the sphere.

The kernels considered in Lemmas 6.3 and 6.4 are closely related to the parallelepiped spanned by the vectors x, y, and $z \in \mathbb{S}^{d-1}$. Indeed, setting a = 2 in (6.5), one obtains negative volume squared of this parallelepiped: this kernel is not conditionally 3-positive definite according to Proposition 6.9, even though σ is a minimizer of the corresponding energy, as shown in Theorem 6.6. However, positive definiteness does hold for other values of the parameter a.

Lemma 6.3. *For* a < 1,

$$K(x, y, z) = t^{2} + u^{2} + v^{2} - auvt + \frac{1}{1 - a}$$

$$(6.5)$$

is 3-positive definite.

Proof. Due to rotational invariance, we need only check one value of z. Let $z = e_1$. We have that

$$K(x,y,e_1) = \langle x,y \rangle^2 + x_1^2 + y_1^2 - ax_1y_1 \langle x,y \rangle + \frac{1}{1-a}$$

$$= \left(\langle x,y \rangle^2 - ax_1y_1 \langle x,y \rangle - (1-a)x_1^2y_1^2 \right) + (1-a)x_1^2y_1^2 + x_1^2 + y_1^2 + \frac{1}{1-a}$$

$$= \left(\langle x,y \rangle^2 - ax_1y_1 \langle x,y \rangle - (1-a)x_1^2y_1^2 \right) + \left(x_1^2\sqrt{1-a} + \frac{1}{\sqrt{1-a}} \right) \left(y_1^2\sqrt{1-a} + \frac{1}{\sqrt{1-a}} \right)$$

$$= \sum_{i=2}^d \sum_{k=2}^d x_j y_j x_k y_k + (2-a) \sum_{m=2}^d x_1 y_1 x_m y_m + \left(x_1^2\sqrt{1-a} + \frac{1}{\sqrt{1-a}} \right) \left(y_1^2\sqrt{1-a} + \frac{1}{\sqrt{1-a}} \right).$$

We quickly see that for any finite signed Borel measure $\nu \in \mathcal{M}(\mathbb{S}^{d-1})$,

$$\int_{\mathbb{S}^{d-1}} \int_{\mathbb{S}^{d-1}} K(x, y, e_1) d\nu(x) d\nu(y) = \sum_{j=2}^{d} \sum_{k=2}^{d} \left(\int_{\mathbb{S}^{d-1}} x_j x_k d\nu(x) \right)^2 + (2 - a) \sum_{m=2}^{d} \left(\int_{\mathbb{S}^{d-1}} x_1 x_m d\nu(x) \right)^2 + \left(\int_{\mathbb{S}^{d-1}} \left(x_1^2 \sqrt{1 - a} + \frac{1}{\sqrt{1 - a}} \right) d\nu(x) \right)^2 \ge 0,$$

hence, K is 3-positive definite.

Lemma 6.4. For $a \le 1$, $K(x, y, z) = t^2 + u^2 + v^2 - auvt$ is conditionally 3-positive definite.

Proof. For a < 1, according to Lemma 6.3, $K + \frac{1}{1-a}$ is 3-positive definite. Thus, for any fixed $z \in \mathbb{S}^{d-1}$ and any $\nu \in \mathcal{M}(\mathbb{S}^{d-1})$ with $\nu(\mathbb{S}^{d-1}) = 0$,

$$I_{K_z}(\nu) = I_{K_z + \frac{1}{1-a}}(\nu) \ge 0,$$

i.e. K is conditionally 3-positive definite. Lemma 2.4 then gives the result for a = 1.

6.3. Some counterexamples. While our results provide new and less complicated means to determine minimizers for a wide range of kernels, it is clear that more general ideas are necessary to categorize all kernels on the sphere for which σ is a minimizer. In this subsection, we present naturally arising kernels on the sphere which are not 3-positive definite on the sphere, but yet the three-input energies generated by these kernels are minimized by the uniform measure σ .

The semidefinite programming methods of Bachoc and Vallentin [BV] are more computationally difficult than ours, and would likely be infeasible for non-polynomial kernels in the context relevant to this paper. At the same time, they apply to certain functions which are not covered by our methods from Section 5. In particular, an appropriate version of semidefinite programming implies that the energies with the following kernels (we keep the notation introduced in [BV])

$$S_{0,1,1}^d(x,y,z) = uv + vt + tu ag{6.6}$$

and

$$S_{1,0,0}^d(x,y,z) = (t-uv) + (u-vt) + (v-tu)$$
(6.7)

are both minimized by σ , see [BFGMPV]. However, neither function is conditionally 3-positive definite, as we demonstrate below. This implies that the converse to Theorem 5.1 does not hold. In addition, the potential of both kernels with respect to σ is a positive definite two-input kernel, which provides evidence that this might indeed be the correct necessary and sufficient condition for σ to minimize the three-input energy (see the discussion before Theorem 5.3).

The former example (6.6) is particularly interesting, since the energy functional with this kernel is convex at the minimizer σ , which suggests that conditional n-positive definiteness and convexity of the energy functional are perhaps not equivalent for $n \geq 3$, unlike the two-input case (see Proposition 3.9). We summarize these properties in the following proposition:

Proposition 6.5. Let $\Omega = \mathbb{S}^{d-1}$ and set

$$K(x, y, z) = S_{0,1,1}^d(x, y, z) = uv + vt + tu.$$

The kernel K satisfies the following:

- (i) the uniform measure σ minimizes the energy I_K ,
- (ii) the energy functional I_K is convex at σ ,
- (iii) $U_K^{\sigma}(x,y)$ is positive definite,
- (iv) K is not conditionally 3-positive definite.

Proof. As mentioned above, part (i) follows from the semidefinite programming method [BFGMPV], however, there is also a simple direct proof of this fact. Observe that by symmetry, for any $\nu \in \mathbb{P}(\mathbb{S}^{d-1})$,

$$I_K(\nu) = 3 \int_{\mathbb{S}^{d-1}} \left(\int_{\mathbb{S}^{d-1}} \langle x, y \rangle d\nu(x) \right)^2 d\nu(y) \ge 0 = I_K(\sigma). \tag{6.8}$$

We now turn to parts (ii)-(iii). We first note that

$$U_K^{\sigma}(x,y) = \int_{\mathbb{S}^{d-1}} \langle z, x \rangle \langle y, z \rangle d\sigma(z) = \frac{1}{d} \langle x, y \rangle,$$

which can be proved using the Funk-Hecke formula or by a direct computation (see, e.g., [BDM]). Hence, the kernel $U_K^{\sigma}(x,y)$ is positive definite, i.e. (iii) holds. Therefore σ minimizes the two-input energy with this kernel, i.e., for any $\nu \in \mathbb{P}(\mathbb{S}^{d-1})$,

$$I_{U_K^{\sigma}}(\nu) = I_K(\nu, \nu, \sigma) \ge I_{U_K^{\sigma}}(\sigma) = I_K(\sigma) = 0.$$

Observe also that $U_K^{\sigma^2}(x)=0$ and thus $I_K(\sigma,\sigma,\nu)=0$. For an arbitrary $\nu\in\mathbb{P}(\mathbb{S}^{d-1})$ and $t\in[0,1]$, define $\sigma_t=(1-t)\sigma+t\nu$. Then

$$I_K(\sigma_t) = (1-t)^3 I_K(\sigma) + 3(1-t)^2 t I_K(\sigma, \sigma, \nu) + 3(1-t)t^2 I_K(\nu, \nu, \sigma) + t^3 I_K(\nu)$$

= 3(1-t)t^2 I_K(\nu, \nu, \sigma) + t^3 I_K(\nu).

If $I_K(\nu) > 0$, we can choose t_{ν} so small that for all $t \in (0, t_{\nu})$, we have $I_K(\nu, \nu, \sigma) \leq \frac{1+t}{3t}I_K(\nu)$, since the right-hand side goes to $+\infty$ as $t \to 0$. Then

$$I_K(\sigma_t) \le (1 - t^2)tI_K(\nu) + t^3I_K(\nu) = tI_K(\nu) = tI_K(\nu) + (1 - t)I_K(\sigma).$$

It remains to consider the case $I_K(\nu) = 0$. According to (6.8), in this situation, $\int_{\mathbb{S}^{d-1}} \langle x, y \rangle d\nu(x) = 0$ for ν -a.e. $y \in \mathbb{S}^{d-1}$, and therefore

$$\int_{\mathbb{S}^{d-1}} \int_{\mathbb{S}^{d-1}} \langle x, y \rangle d\nu(x) d\nu(y) = 0.$$

But this implies that

$$I_K(\nu,\nu,\sigma) = I_{U_K^{\sigma}}(\nu) = \int_{\mathbb{S}^{d-1}} \int_{\mathbb{S}^{d-1}} \frac{1}{d} \langle x, y \rangle d\nu(x) d\nu(y) = 0.$$

Thus, when $I_K(\nu) = 0$, we have

$$I_K(\sigma_t) = 3(1-t)t^2I_K(\nu,\nu,\sigma) + t^3I_K(\nu) = 0 = (1-t)I_K(\sigma) + tI_K(\nu)$$

for all $t \in [0,1]$. This finishes the proof that I_K is convex at σ .

Finally, we show that I_K is not conditionally 3-positive definite, i.e. part (iv). Taking $\mu = \delta_{e_2} - \delta_{-e_1}$ and $z = e_1$, a straightforward computation shows that

$$I_{K_z}(\mu) = I_K(\delta_{e_1}, \mu, \mu) = -1 < 0,$$

which proves our claim.

The behavior of the kernel $S_{1,0,0}^d$ is somewhat different. Since

$$I_{S_{1,0,0}^d}(\delta_{e_1},\delta_{e_1},\sigma) = \int_{\mathbb{S}^{d-1}} (1-z_1^2) d\sigma(z) > 0 = I_{S_{1,0,0}^d}(\sigma) = I_{S_{1,0,0}^d}(\sigma,\sigma,\delta_{e_1}) = I_{S_{1,0,0}^d}(\delta_{e_1}),$$

we see that for all $t \in (0,1)$,

$$I_{S^d_{1,0,0}}(t\delta_{e_1}+(1-t)\sigma)=3t^2(1-t)I_{S^d_{1,0,0}}(\delta_{e_1},\delta_{e_1},\sigma)>tI_{S^d_{1,0,0}}(\delta_{e_1})+(1-t)I_{S^d_{1,0,0}}(\sigma),$$

so $I_{S_{1,0,0}^d}$ is not convex at σ , and therefore not conditionally 3-positive definite, according to Corollary 3.7. In particular, this shows that convexity of I_K at σ and the fact that σ is a minimizer of I_K are not equivalent for three-input energies, unlike in the classical two-input case [BMV].

In the next subsection we introduce, two more three-input kernels with a geometric flavor, which have similar properties: they also fail to be 3-positive definite, yet the corresponding energies are minimized by the uniform measure σ .

6.4. Energies with geometric kernels, which are optimized by the uniform surface measure. Riesz energies with the kernel $K(x,y) = ||x-y||^{\alpha}$ are one of the most important classes of two-input energies. In particular, when $\alpha = 1$, maximizing the sum of distances between points or the corresponding distance integrals is a classical optimization problem of metric geometry [AS, Bj, F]. One can construct interesting multi-input analogues of Riesz energies by replacing the distance with other geometric characteristics which depend on n points, such as area and volume. For n = 3, some of the most natural examples include the area of the triangle generated by three points or the volume of the tetrahedron (or the parallelepiped) spanned by three vectors. This can be generalized to higher values of n by considering volumes of various simplices or polytopes generated by n points or vectors.

It is reasonable to conjecture that on the sphere, energy integrals with these three-input kernels (namely, the area of the triangle and the volume of the parallelepiped) are maximized by the uniform measure σ . Probabilistically, this can be reformulated in the following way: assume that three random points are chosen on the sphere \mathbb{S}^{d-1} independently according to a probability distribution μ . The conjecture then states that the expected value of these geometric quantities is maximized when the distribution μ is uniform, i.e. $\mu = \sigma$. The question was posed in this form in [Ro].

This conjecture is supported, among other reasons, by the fact that for the classical case n=2, the analogous kernels $|\sin(\arccos\langle x,y\rangle)| = \sqrt{1-u^2}$ and $||x-y|| = \sqrt{2-2u}$ (i.e. the area of the parallelogram and the Euclidean distance, respectively) are both negative definite kernels on the sphere (up to an additive constant), and hence the corresponding two-input energies are maximized by σ .

In this section, we verify the conjecture above for slightly different, yet closely related kernels V^2 and A^2 : the squares of the said volume and area. In these cases, the kernels are multivariate polynomials, which substantially simplifies the analysis. Theorems 6.6 and 6.7 show that the three-input energies I_{V^2} and I_{A^2} are maximized by the uniform surface measure σ .

Despite the fact that σ is a minimizer of I_{-V^2} and I_{-A^2} , we shall show in Propositions 6.9 and 6.10 that both kernels $-V^2$ and $-A^2$ fail to be conditionally 3-positive definite, which provides yet another proof that the converse to Theorem 5.1 does not hold, unlike in the two-input case.

While in the present paper we only touch upon these questions tangentially, a much more thorough investigation of such geometric problems is undertaken in our paper [BFGMPV].

6.4.1. Volume of the tetrahedron/parallelepiped. Let V(x,y,z) denote the three-dimensional volume of the parallelepiped spanned by the vectors $x, y, z \in \mathbb{S}^{d-1}$. (Observe that the volume of the tetrahedron with vertices at x, y, z, and the origin is $\frac{1}{6}V(x,y,z)$.) The square of the volume V(x,y,z) is given by the determinant of the Gram matrix. Thus we consider the kernel

$$V^{2}(x,y,z) = \det \begin{pmatrix} 1 & u & v \\ u & 1 & t \\ v & t & 1 \end{pmatrix} = 1 - u^{2} - v^{2} - t^{2} + 2uvt, \tag{6.9}$$

where, as before, we set $u = \langle x, y \rangle$, $v = \langle y, z \rangle$, $t = \langle z, x \rangle$. We have the following statement.

Theorem 6.6. Assume that $d \geq 3$ and $\Omega = \mathbb{S}^{d-1}$. Let $V^2(x,y,z) = 1 - t^2 - u^2 - v^2 + 2uvt$ be the square of the volume of the parallelepiped spanned by the vectors $x, y, z \in \mathbb{S}^{d-1}$. Then σ is a maximizer of I_{V^2} over $\mathbb{P}(\mathbb{S}^{d-1})$.

In fact, this theorem also holds for the *n*-input kernel $K(x_1, \ldots, x_n)$ defined as the determinant of the Gram matrix of the set of vectors $\{x_1, \ldots, x_n\} \subset \mathbb{S}^{d-1}$ with $d \geq n \geq 3$. This statement is essentially contained in the works of Rankin [R, 1956] (n = d) and of Cahill and Casazza [CC] (for $d \geq n$). A comprehensive exposition is presented in our paper [BFGMPV].

6.4.2. Area of the triangle. We now turn to the discussion of the area A(x, y, z) of the triangle with vertices x, y, and $z \in \mathbb{S}^{d-1}$. It is a standard geometrical fact that

$$A^{2}(x, y, z) = \frac{1}{4}(\|y - x\|^{2} \cdot \|z - x\|^{2} - \langle y - x, z - x \rangle^{2}).$$
(6.10)

A straightforward computation then shows that

$$A^{2}(x,y,z) = \frac{3}{4} - \frac{1}{2}(u+v+t) + \frac{1}{2}(uv+vt+tu) - \frac{1}{4}(u^{2}+v^{2}+t^{2}).$$
 (6.11)

One could also deduce this identity from Heron's formula. We are now ready to prove that the expectation of the area of the triangle *squared* is maximized by the uniform surface measure σ on the sphere \mathbb{S}^{d-1} .

Theorem 6.7. Suppose $d \geq 2$, and let $A^2(x, y, z)$ be the square of the area of the triangle with vertices at $x, y, z \in \mathbb{S}^{d-1}$. Then the uniform surface measure σ maximizes $I_{A^2}(\mu)$ over $\mathbb{P}(\mathbb{S}^{d-1})$.

Proof. Fix an arbitrary measure $\mu \in \mathbb{P}(\mathbb{S}^{d-1})$. Observe that

$$I_{u}(\mu) = \int_{\mathbb{S}^{d-1}} \int_{\mathbb{S}^{d-1}} \langle x, y \rangle d\mu(x) d\mu(y) = \left\| \int_{\mathbb{S}^{d-1}} x \ \mu(x) \right\|^{2}. \tag{6.12}$$

Furthermore, applying the Cauchy-Schwarz inequality, we obtain

$$I_{uv}(\mu) = \int_{\mathbb{S}^{d-1}} \int_{\mathbb{S}^{d-1}} \langle x, y \rangle \langle z, x \rangle d\mu(x) d\mu(y) d\mu(z) = \int_{\mathbb{S}^{d-1}} \left\langle x, \int_{\mathbb{S}^{d-1}} y d\mu(y) \right\rangle^2 d\mu(x)$$

$$\leq \int_{\mathbb{S}^{d-1}} ||x||^2 \cdot \left\| \int_{\mathbb{S}^{d-1}} y d\mu(y) \right\|^2 d\mu(x) = \left\| \int_{\mathbb{S}^{d-1}} y d\mu(y) \right\|^2 = I_u(\mu). \tag{6.13}$$

This inequality implies that the contribution of the two middle terms in the representation (6.11) is non-positive, i.e. $I_{\frac{1}{2}(uv+vt+tu)-\frac{1}{2}(u+v+t)}(\mu) \leq 0$. Finally, we have a well-known estimate

$$I_{u^2}(\mu) = \int_{\mathbb{S}^{d-1}} \int_{\mathbb{S}^{d-1}} \langle x, y \rangle^2 d\mu(x) d\mu(y) \ge \frac{1}{d}.$$
 (6.14)

The two-input energy appearing above is known as the *frame energy*. Its discrete version was introduced in [BF] in connection to *finite unit norm tight frames* (FUNTF's), for the continuous analogue, see e.g. [BM]. Putting it all together, we find that

$$I_{A^2}(\mu) \le \frac{3}{4} - \frac{1}{4}I_{u^2+v^2+t^2}(\mu) \le \frac{3}{4} - \frac{3}{4d} = \frac{3}{4}\frac{d-1}{d},$$

and it is easy to check that equality holds if $\mu = \sigma$.

Numerous generalizations and refinements of Theorems 6.6 and 6.7 (including characterizations of minimizers) can be obtained. An in-depth discussion of such geometric problems can be found in our follow-up paper [BFGMPV].

6.4.3. Lack of 3-positive definiteness. It now remains to show that the kernels $-V^2$ and $-A^2$ are not conditionally 3-positive definite. We first recall the following lemma:

Lemma 6.8 (Chp. 3, Lemma 2.1, [BCR]). Let Ω be a nonempty set, $x_0 \in \Omega$, $\psi : \Omega^2 \to \mathbb{C}$ be a Hermitian kernel, i.e. $\psi(x,y) = \overline{\psi(y,x)}$, and define

$$\phi(x,y) := \psi(x,y) + \psi(x_0,x_0) - \psi(x,x_0) - \psi(x_0,y).$$

Then ϕ is positive definite if and only if ψ is conditionally positive definite. If $\psi(x_0, x_0) \leq 0$ and

$$\phi_0(x,y) := \psi(x,y) - \psi(x,x_0) - \psi(x_0,y),$$

then ϕ_0 is positive definite if and only if ψ is conditionally positive definite.

We shall now use this lemma to show that our two geometric kernels are not conditionally 3-positive definite.

Proposition 6.9. Assume that $d \ge 3$, and let V(x,y,z) be the volume of the parallelepiped spanned by the vectors $x,y,z \in \mathbb{S}^{d-1}$. Define the kernel $K(x,y,z) = -V^2(x,y,z)$. Then K is not conditionally 3-positive definite.

Proof. Using the representation $V^2(x,y,z) = 1 - u^2 - v^2 - t^2 + 2uvt$ and fixing $z = e_1$, we find that $K_{e_1}(x,y) = u^2 + y_1^2 + x_1^2 - 2ux_1y_1 - 1$. It is easy to check that $K_{e_1}(e_1,e_1) = K_{e_1}(e_1,y) = K_{e_1}(x,e_1) = 0$ and hence

$$K_{e_1}(x,y) + K_{e_1}(e_1,e_1) - K_{e_1}(e_1,y) - K_{e_1}(x,e_1) = K_{e_1}(x,y).$$
 (6.15)

Taking $\nu = \delta_{e_2} + \delta_{e_3}$, one can compute

$$I_{K_{e_1}}(\nu) = -2 < 0,$$

i.e. K_{e_1} is not positive definite. Lemma 6.8 and (6.15) then tell us that K_{e_1} is not conditionally positive definite and thus K is not conditionally 3-positive definite.

We now turn to area squared of a triangle and prove an analogous statement.

Proposition 6.10. Assume that $d \geq 2$. Let A(x,y,z) be the area of the triangle with vertices at $x,y,z \in \mathbb{S}^{d-1}$ and set $K(x,y,z) = -A^2(x,y,z)$. Then K is not conditionally 3-positive definite.

Proof. As computed in (6.11),

$$A^{2}(x,y,z) = \frac{3}{4} - \frac{1}{2}(u+v+t) + \frac{1}{2}(uv+vt+tu) - \frac{1}{4}(u^{2}+v^{2}+t^{2}).$$

Fixing $z = e_1$, we find that

$$4K_{e_1}(x,y) = u^2 + x_1^2 + y_1^2 + 2u + 2x_1 + 2y_1 - 2x_1y_1 - 2ux_1 - 2uy_1 - 3.$$

The rest of the argument almost repeats the proof of Proposition 6.9: we have that

$$K_{e_1}(x,y) + K_{e_1}(e_1,e_1) - K_{e_1}(e_1,y) - K_{e_1}(x,e_1) = K_{e_1}(x,y),$$
 (6.16)

as well as

$$I_{K_{e_1}}(\delta_{e_2} + \delta_{-e_1}) = -2 < 0,$$

and an application of Lemma 6.8 finishes the proof.

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