

Augmented Reality and Artificial Intelligence in Industry: Trends, Tools, and Future Challenges

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Abstract

Augmented Reality (AR) is an augmented depiction of reality formed by overlaying digital information on an image of objects being seen through a device. Artificial Intelligence (AI) techniques have experienced unprecedented growth and are being applied in various industries. The combination of AR and AI is the next prominent direction in upcoming years with many industries and academia recognizing the importance of their adoption. With the advancements in the silicon industry that push the boundaries of Moore's law, processors will be less expensive, more efficient, and power-optimized in the forthcoming years. This is a tremendous support and necessity for an AR boom, and with the help of AI, there is an excellent potential for smart industries to increase the production speed and workforce training along with improved manufacturing, error handling, assembly, and packaging. In this work, we provide a systematic review of recent advances, tools, techniques, and platforms of AI-empowered AR along with the challenges of using AI in AR applications. This paper will serve as a guideline for future research in the domain of AI-assisted AR in industrial applications.

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1. Introduction

Industry requirements change every year as the global competition drives continual technological advancement. Augmented Reality (AR) is among the leading technological applications in various domains (Carmigniani et al., 2011). AR is computer-generated virtual information superimposed onto the actual scene called rendering, which is the process of displaying digital information in a realistic manner (Dubois and Nigay, 2000) such that it appears to be a part of the actual environment (Display) (Zhou et al., 2008). While there are many other forms of superimposition of computer-generated objects to “enhance”, i.e., deepen or broaden one’s understanding of the “reality”, AR is the most widely used (Craig, 2013; Cheng et al., 2018). Recently, there has been groundbreaking development in the field of AR, and it has been widely adopted in many industries, including gaming (Kumar et al., 2021), education (Ali, 2020), and entertainment (Mahmood et al., 2017). Developers create inputs in the digital world that adapt to the changes in the user’s environment in real time, such as motion, graphics, and GPS overlays. It has enormous potential when integrated with machine learning (ML) techniques since the recent ML algorithms have achieved great success to process and extract information from images. AR applications have been considered significantly helpful to improve efficiency and efficacy in industrial operations (Fraga-Lamas et al., 2018b). Figure 1 depicts four layers design of AR, ranging from object detection to display associated with AR applications.

Mixed reality (MR) hybridizes physical reality with virtual reality in which the physical and virtual worlds can interact, whereas AR occurs in the physical environment but with information added virtually. MR experiences can be achieved through MR glasses such as Holographic devices (Kozek, 2020). AR, on the other hand, can be experienced through a variety of devices, including AR glasses and smart phones/tablets. AR is emerging as part of the Industry 4.0 revolution due to the popularity of the devices (De Pace et al., 2018).

Industry 4.0 describes the present state of the manufacturing industry. Mechanisation, mass production, and automation were key ideas for Industry 1.0, 2.0, and 3.0 revolutions, respectively (Ababsa, 2020). Industry 3.0

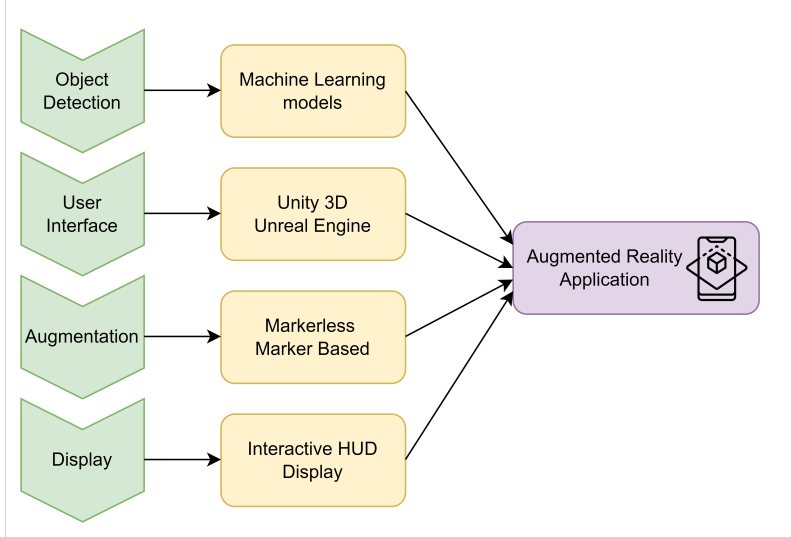


Figure 1: AR's four layers design ranging from object detection to display.

has seen many robots and sensors on the plant floor, automating all potential production tasks. Industry 4.0, also known as smart manufacturing, is based on technologies that aim to 1) accelerate the remaining work that requires human expertise and skills; 2) combine intelligence with automated infrastructure to make robotic systems autonomous and capable of making decisions based on data (Rüßmann et al., 2015). Artificial Intelligence (AI) and ML techniques are promising to improve flexibility and effectiveness of AR systems. The tremendous success of AI/ML in object detection and related tasks demonstrates their applications in the AR domain. AI has the potential to revolutionize AR applications in the same way that AR has revolutionized manufacturing. AI has already made significant improvements in manufacturing industries (Liu et al., 2020), and more implementations can be introduced into applications, such as inspection (Zhang et al., 2019) and information management for materials (Furini et al., 2016).

In this study, we provide a detailed literature review for AR and AI applications in the industry. We keep our survey limited to the articles published between 2010 to 2021. Given that articles are published in multiple sources, we focused our search on three prominent publishers: IEEE, Springer, and Elsevier. In order to limit ourselves to the review topic, we used keywords such as ‘Augmented Reality (AR)’, ‘Artificial Intelligence (AI)’, ‘Industry’,

No.	Keywords Used
1	Artificial Intelligence and Augmented Reality in industry
2	AI and AR in industry
3	Deep learning and augmented reality
4	Deep learning and AR

Table 1: The keywords used for the literature search for AI and AR articles in the context of industry that were published between 2010 and 2021.

and their combinations. The purpose of including these keywords in our study was to cover various AR platforms and frameworks and AI/ML approaches such as regression (Maulud and Abdulazeez, 2020), classification (Schapire, 2015), neural networks, deep learning (Nielsen, 2015), and reinforcement learning (Sutton and Barto, 2018) along with their contribution to AR in the industry applications. We searched on Google Scholar with keywords used in Table 1 and looked for papers that mentioned AR and AI. We reviewed the first ten pages of the search result in Google Scholar as we observed that keywords started diluting into just words in papers appeared in later pages without much relation left between AR and AI. As shown in Figure 2, the number of articles published in the field of AR is gradually increasing overall, except some reduction in the last few years. The pace at which the technology is catching up is remarkable. There is a growing trend in the publications from 2015 as many industries have started recognizing and utilizing AR.

Recently, a number of survey articles related to AR and AI are published, and most of them are focused on a specific field or an industrial sector. Kaviyaraj and Uma (2021) summarized the status of AR applications in the education domain and briefly mentioned the benefits of using AI in AR applications. The article highlighted applications of AR in existing learning scenarios, which aim to motivate interactive learning environments. Another work by Gandedkar et al. (2021) provided an insight into the role of AR and AI applications in the field of orthodontic teaching and research. It outlined the limitations of traditional teaching in the field and illustrated the potential of AR and AI in effective learning and conducting research. Sahu et al. (2021) reviewed current AR strategies and identified the limitations of current approaches utilized in AR systems. Corresponding AI solutions to the AR computational pipeline were also discussed. In a recent work by Szajna

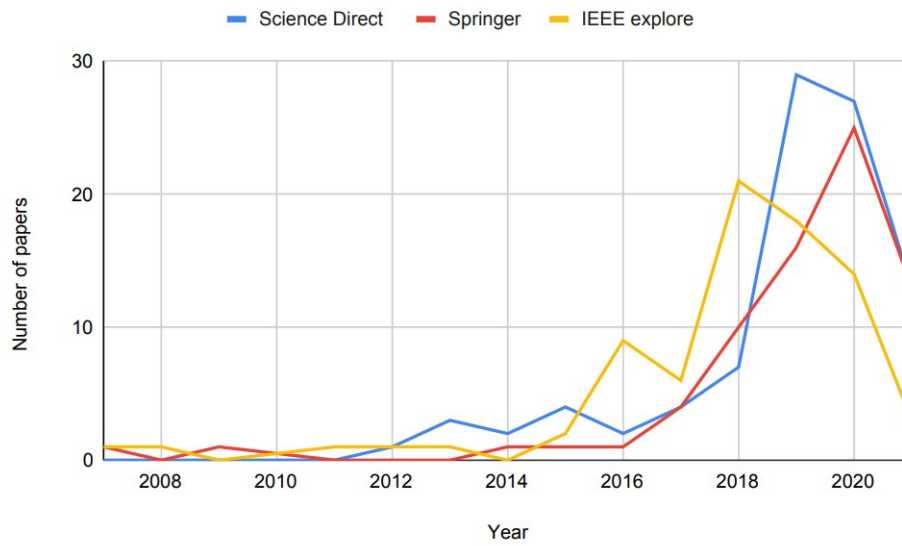


Figure 2: AR articles in the context of industry published between 2010 and 2021.

and Kostrzewski (2022), the need for AR and AI tools in sustainable working environments is emphasized. The authors discussed the benefits associated with AR-AI applications including job simplification and work efficiency. Our work fills the gap in the existing literature by providing a more comprehensive review of AR and AI applications related to various industries in a systematic way. Specifically, we discuss fundamental AR frameworks that are utilized in the industry as well as platforms that are used to create these AR apps. In addition, we explain how AI can be utilized in conjunction with AR to benefit various industry sectors. Lastly, the challenges in AI approaches for AR-assisted manufacturing applications are also outlined. The primary contributions of this work are listed as follows:

- Provide a detailed review of AR and AI research related to various industries.
- Perform a comprehensive analysis of current tactics used for AR computational component.
- Investigate platforms and frameworks that are being used to build different types of AR applications.

- 100 • Summarize the challenges and identify a number of potential areas in
101 the AR ecosystem for future research.

102 The remainder of this paper is organized as follows. Sections 2 and 3 pro-
103 vide a thorough discussion of the various techniques, platforms, and frame-
104 works used in the industry. Section 4 gives a review of the application of
105 AR and AI in different industry sectors. Section 5 covers the most critical
106 and promising areas for future research developed from or influenced by the
107 findings of previous sections. Finally, the work is summarized and concluded
108 in Section 6.

109 2. Machine Learning Methods

110 Recently, AR and ML techniques are gaining huge popularity in the in-
111 dustry. Object detection techniques powered by AR and ML can integrate
112 the current world with the industry sector to provide an enhanced experi-
113 ence. Deep learning (DL) – a sub-field of ML consists of state-of-art algo-
114 rithms – aims to develop unique solutions for many real-world challenging
115 applications. DL techniques consist multiple processing layers to learn hier-
116 archical representations of data with multiple levels of abstraction (LeCun
117 et al., 2015). They are applicable to a wide range of domains since they pro-
118 vide a plethora of valuable and novel applications, solutions, and services.
119 They will become even more popular in the near future as more complex
120 algorithms and architectures are developed (LeCun et al., 2015). Some of
121 the most significant areas of DL applications include computer vision, nat-
122 ural language processing (NLP), sentiment analysis, social computing, and
123 speech recognition.

124 Cheng et al. (2018) demonstrated that combining Convolutional Neural
125 Networks (CNN), a popular DL algorithm, with AR and AI is highly promis-
126 ing. In the realm of computer vision, CNN-based DL models have become
127 essential tools for dynamic image identification problems. There is an abun-
128 dance of DL-based object detection techniques by which AR can be accom-
129 plished efficiently and instantly, including YOLOv3 (Redmon and Farhadi,
130 2018), MobileNet v2 (Sandler et al., 2018), and SSD model (Liu et al., 2016).
131 Table 2 summarizes pros and cons of these three models (Huang et al., 2017;
132 Zhao et al., 2019).

Table 2: Pros and cons of three deep learning methods.

Methods	Pros	Cons
YOLO v3	Faster than SSD	Performance drops significantly as IoU (Intersection over Union) threshold increases
MobileNet	Reduced computational cost and model size	Relatively less accurate
SSD	Simple and faster than YOLO	Not skilled for detecting small objects

2.1. YOLOv3

YOLO (You Only Look Once) (Redmon et al., 2016) enables end-to-end training and performs incredibly fast compared to other DL-based object detection techniques. The merit of YOLO method is that it unifies the separate components of object detection framework into a single neural network and reasons objects globally, which enables its real-time object detection capability while maintaining high average precision. An improved version of YOLO method called YOLOv2 (Redmon and Farhadi, 2017) uses anchor boxes to predict bounding boxes and introduces a new classification model named Darknet-19. A faster version of YOLOv2, called Fast YOLO (Shafiee et al., 2017), enables real-time object detection in videos displaying on resource-constraint embedded devices. Fast YOLO creates an optimized architecture through evolutionary deep intelligence framework, which is then used within a motion-adaptive inference framework to accelerate object detection while reducing energy consumption of the embedded device.

YOLOv3 (Redmon and Farhadi, 2018) is a newer version that operates in 22 ms at 28.2 mAP (mean average precision) on a 320×320 input image, which is three times quicker than SSD (Liu et al., 2016). When compared with YOLOv2, YOLOv3 is a bigger network but with better accuracy.

2.2. MobileNet

The MobileNet model is built on depthwise separable convolutions, a type of factorized convolution that divides a regular convolution into depthwise and pointwise convolutions (Howard et al., 2017). The depthwise convolution used by MobileNets assigns a unique filter to each input channel.

MobileNetV2 includes a fully convolutional layer with 32 filters followed by 19 residual bottleneck layers (Sandler et al., 2018). A consistent expansion

rate is employed throughout the network except the initial layer. The experiments conducted by Sandler et al. (2018) discovered that the expansion rates between 5 and 10 produce almost identical performance curves, and lower expansion rates are suitable for smaller networks while higher expansion rates are good for bigger networks. MobileNet has achieved significant performance in object detection, image classification and segmentation tasks, along with highly memory-efficient inference. A more detailed architecture can be found in the work by Sandler et al. (2018).

2.3. Single Shot Multi-Box Detector (SSD)

SSD splits the output space of bounding boxes into a collection of default boxes spanning several aspect ratios and sizes for each feature map position, allowing for object detection in images or videos using a deep neural network (Liu et al., 2016). SSD is straightforward compared to approaches that rely on object proposals since it removes proposal development and subsequent pixel or feature resampling steps, encapsulating all processing in a single network (Endres and Hoiem, 2010). SSD is simple to train and integrate into systems that require a detecting component. In addition, it uses a feed-forward convolutional network to generate a fixed-size array of bounding boxes and score for the occurrence of object class instances in those boxes, accompanied by a non-maximum suppression step to provide final detection. Besides, it adds auxiliary structures to provide detection with properties: multi-scale feature maps and convolutional predictors for detection along with default boxes and aspect ratios.

3. Augmented Reality Frameworks and Platforms

Incorporating cognitive technologies into AR (Shelton and Hedley, 2004), photographs become immersive and engaging in this digital era, providing a better and comprehensive knowledge of a subject. It is a widely used technology that allows organizations to graphically depict products, services, techniques, processes, and other items to users. Many companies utilize AR (Fraga-Lamas et al., 2018a) applications to increase user engagement and efficiently and convincingly depict their subjects. Industries that create AR apps continually improve user experiences by providing brands and SMEs with visually rich and novel ways to portray digital material. Moreover, they are doing it using a variety of AR approaches, some of them are described in Figure 3.

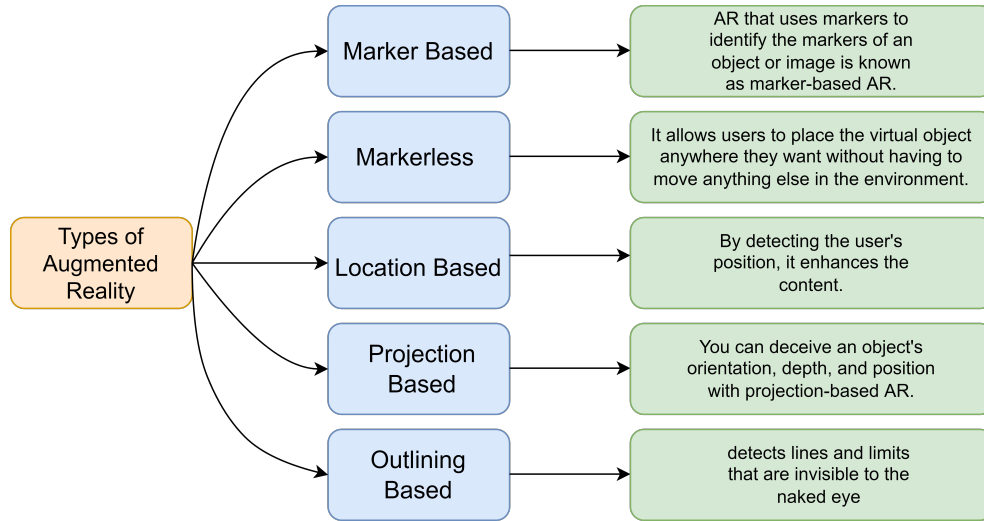


Figure 3: Different types of Augmented Reality applications.

194 Augmented Reality SDK (Software Development Kit) provides APIs for
 195 different tasks within the AR application including object recognition, ob-
 196 ject tracking (Azuma, 1993), and content rendering (Lee et al., 2020). The
 197 module for recognition works as the brain of the app. The tracking module
 198 serves as eyes for the AR experience, while the content rendering component
 199 creates imaginative virtual objects and scenes on the real-time information.
 200 The APIs are provided to developers through SDK for recognizing, tracking,
 201 and rendering in AR applications efficiently (Amin and Govilkar, 2015).

202 Several broad categories may be used to organize AR SDKs: Natural Fea-
 203 ture Tracking (Neumann and You, 1999), Geo-located AR Browsers (Khan
 204 and Andy, 2011), Marker-based AR (Katiyar et al., 2015), and Browser SDKs
 205 (Amin and Govilkar, 2015). A few of them allow users to construct geo-
 206 located AR apps utilizing the GPS and IMU on today's smartphones and
 207 wearables. Marker-based SDKs build AR experiences by using specific pic-
 208 tures called markers (Gherghina et al., 2013). By monitoring planar pictures
 209 or using a SLAM (Simultaneous Location and Mapping) technique (Durrant-
 210 Whyte and Bailey, 2006), Natural Feature Tracking SDKs depend on the
 211 characteristics that really exist in the environment to accomplish the aug-
 212 mentation.

213 Building an AR system from the ground up is challenging and time-
 214 consuming. Many AR frameworks and platforms are created to assist devel-

215 operates focusing on higher-level applications rather than low-level implemen-
216 tations. Next, we will explore a sample subset of the existing platforms and
217 frameworks. A summary is provided in Table 3.

218 3.1. *ARBlocks*

219 ARBlocks (Roberto and Teichrieb, 2012) is a dynamic block-based plat-
220 form aimed towards early childhood educational activities, based on pro-
221 jected augmented reality and physical user interfaces. The apps and the
222 platform itself were created to help educators teach general subjects to chil-
223 dren, such as arithmetic and language skills, as well as help them build crucial
224 skills like motor coordination and collaboration.

225 3.2. *ARCore*

226 ARCore is Google’s AR platform (GoogleARCore, 2018; Lanham, 2018)
227 that allows a user’s phone to perceive its surroundings, interpret the real
228 world, and interact with information through various APIs. ARCore is
229 mainly designed to work on various Android phones running Android 7.0
230 and later. To allow shared AR experiences, several APIs are available across
231 Android and iOS as listed below (GoogleARCore, 2018):

- 232 • Motion tracking: ARCore employs feature points to compute its change
233 in position by detecting visually distinguishable features in the acquired
234 camera picture.
- 235 • Environmental understanding: ARCore is able to detect key points that
236 present similar horizontal or vertical interfaces, such as tables or walls,
237 and makes these surfaces available as geometric surfaces to customers’
238 app. ARCore can also detect the border of geometric plane.
- 239 • Depth understanding: ARCore can use the primary RGB camera to
240 build depth maps that contain information about distances of surfaces
241 from a specific position.
- 242 • Light estimation: ARCore can recognize information about its envi-
243 ronment illumination and present the typical camera image’s intensity
244 and color correction.
- 245 • Oriented points: ARCore employs hit testing to project a beam into
246 the phone camera’s view of the world.

Table 3: Characteristics of various AR platforms and frameworks.

Platforms	Characteristics	
ARBlocks	• Good visualization and Tracking	• Relatively slow
ARCore	• Good understanding of the environment.	• Good for gaming. • AR Tracking isn't consistent • Not stable on older generation devices
ARKit	• Instant AR (Using Lidar) • Good AR rendering devices • supports old devices	• Only for iOS and iPad OS • Free for Xcode features • Charges for app distribution
AR-media	• Offers Cloud based services for AR	• Easy AR project development without coding skills. • Free registration. • Depth mapping isn't available yet
ARToolKit	• Processing happens in real time • fast AR placing is possible	• Can be used only with image markers. • Free and open source
ARWin	• Can be categorized based geometry • Interact in the virtual environment	• Camera resolution constrains more accurate tracking, • Careful calibration of markers is required
Bright	• Comfortable AR HMDs (HoloLens) • Text to speech • Local Processing	• Slow processing as it is done locally • Improper control over functionality
CoVAR	• Eye-Gaze based interaction • Head-Gaze based interaction • Hand Gestures based interaction	• Simulator Sickness • Only head tracking is visible
DUIRA	• Create a realistic virtual digital environment • that reflects real-world experiences	• Requires multiple AR markers • Angle changes in AR markers leads to create different effects
KITE	• Quickly assembled from existing hardware • Initialization is simple	• Only available on a desktop system • Algorithm for mesh reconstruction is not accurate and stable
Nexus	• Spatial-aware applications • Easy and common infrastructure.	• Needs to stores and manages the location information globally • Harder location-aware communication concepts
Vuforia	• Most widely used (Documentations available) • tracking is flicker-less	• Paid license is required for advance AR features
WARP	• A well defined Layered Structure architecture	• Relatively slower processing
Wikitude	• Geo-based tracking available	• License needed for the app development

247 3.3. *ARKit*

248 The AR application development kit (ARKit) was launched by Apple
249 around June 2017 (AppleARKit, 2017; Wang, 2018). This iOS specific kit
250 allows the user to develop AR apps for iPhones and iPads running iOS 11
251 or above. All iOS developers with an Apple developer account may use
252 ARKit SDK. Apple ARKit 5 is the most recent version, which was unveiled
253 at Apple Worldwide Developers Conference (WWDC) in 2021 and provides
254 new features for AR (AppleARKit, 2017):

- 255 • Expanded Face Tracking support: The ultra wide camera in the iPad
256 Pro (5th generation) now supports face tracking as well. The TrueDepth
257 camera can track up to three faces at once.
- 258 • Location Anchors: AR projects may be anchored at a certain latitude,
259 longitude, and altitude using Location Anchors.
- 260 • Depth API: This API may leverage per-pixel depth information about
261 the surrounding environment due to the LiDAR Scanner. This depth
262 information when paired with the 3D model data created by Scene Ge-
263 ometry makes virtual object occlusion even more realistic by allowing
264 for fast placement of virtual objects.
- 265 • Scene Geometry: It makes a topological map of rooms, labeling objects
266 such as floors, doors, etc.
- 267 • Instant AR: The LiDAR Scanner offers exceptionally fast plane iden-
268 tification, allowing AR items to be placed in the actual environment
269 without having to scan them.
- 270 • People Occlusion: Enable immersive AR experience by passing front
271 and back of people in the real world.
- 272 • Motion Capture: Taking motion and poses as arguments to the AR
273 experience and it performs in real-time with single camera.

274 3.4. *AR-media*

275 AR-media SDK (InglobeTechnologies, 2022) is built on a 3D model track-
276 ing technique that detects flat photos and complex 3D objects. A renderer
277 for generating 3D objects, a tracker for identifying the target, a capture for
278 recording frames from the device camera, and native Android and iOS user

279 interfaces are all part of the SDK architecture. AR-media is a cross-platform
280 foundation written in C/C++. This SDK can be used to construct an AR
281 application by capturing images of the object where the user wants the tar-
282 get audience to interact with as well as creating a 3D model that will be
283 overlaid on the tracker established on the online SDK server. OpenCV, nat-
284 ural feature trackers; OpenNI (Falahati, 2013), which allows motion capture
285 with depth cameras; and Inglobe Tracker, a sophisticated 3D tracker, are
286 all included in the framework. Following are the key features of AR-media
287 (InglobeTechnologies, 2022):

- 288 • Cloud-based services are available for creating and managing 3D tar-
289 gets.
- 290 • Fine-tuning of the findings is easy as several tracker settings are avail-
291 able for tweaking.
- 292 • To interface with any other AR platform, the frame is only needed to
293 convert to an OpenCV.Mat object and pass it to the tracker.
- 294 • Real-time 3D tracking of real-world objects in various lighting condi-
295 tions is possible.

296 3.5. *ARToolKit*

297 ARToolKit is an open-source software marker-based AR toolbox (Kato,
298 2007). It is a programming package for creating an AR software that layers
299 an interactive 3D item on an AR marker captured by a smartphone camera.
300 Detecting the coordinates of the AR marker using computer vision tech-
301 niques defines the virtual object’s location and direction. ARToolKit works
302 on various systems and uses OpenGL (Shreiner et al., 2009) for rendering;
303 ARToolKit API is written in C language. It is multi-platform as it can be
304 used on Windows, Mac OS X, Linux, iOS, and Android operating systems.
305 Marker tracking techniques, calibration, and parameter collection are all in-
306 cluded in the AR package of the ARToolKit library. The camera module has
307 procedures for capturing video input data, while the sub-module contains
308 graphic procedures based on the OpenGL and GLUT libraries. Additionally,
309 a variety of ARToolKit extensions for mobile devices are available. Following
310 are the important features of ARToolKit:

- 311 • Perform real-time AR applications.

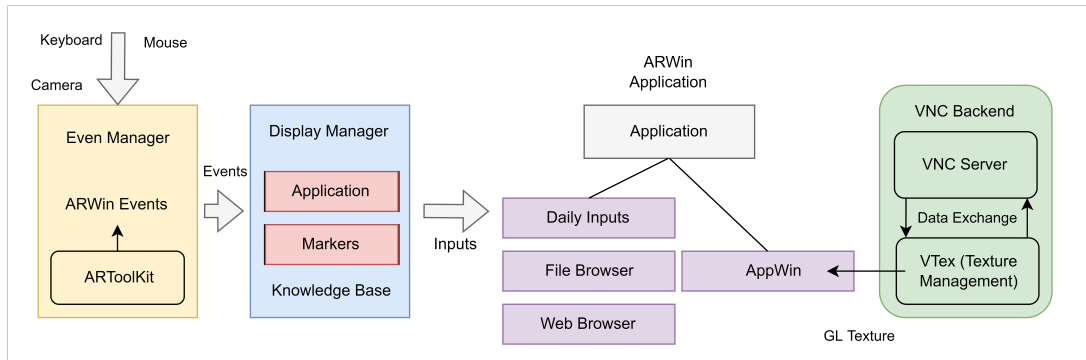


Figure 4: ARWin workflow. Inputs (keyboard/mouse/camera) data is processed, and then communicated in the form of events, which will be displayed on the display, after which the data is processed and provided as an output by the application. This figure is modified from the work by Di Verdi et al. (2003).

- Code for camera calibration is easy to use.
- Position/orientation tracking with a single or stereo camera is possible.

3.6. *ARWin*

ARWin (Di Verdi et al., 2003) is a single-user AR desktop in a 3D environment that allows both classic 2D and innovative 3D programs to populate the physical space above the user’s desk, with some of them improve operations of physical objects on the desk.

The event and display manager are the two main components of the ARWin architecture as shown in Figure 4. When used together, they substitute the functionalities of a conventional Windows X environment with a window manager. It is the role of the event manager to process input and produce ARWin-specific events. The event manager, for example, is prompted by the camera input to execute marker detection and tracking. The ARToolkit detects markers mounted to the user’s workstation and walls in their office. The space above the user’s desk creates a global vector space. Other input, like keyboard and mouse events, can either be passed through unchanged to the display manager or initiate more complex actions, such as window movement or menu engagement. An ARWin application is created by inheriting the App3d super class, which includes callback methods for event processing and window management services. AppWin is a particular type of program that lets users run old X programs (xterm, emacs) within ARWin. AppWin

333 uses a virtual VNC-enabled X server to run the X program. VNC client
334 connects to an OpenGL texture map and draws the image data to a polygon
335 in the workspace. The targeted application is constantly orientated to face
336 the user directly to optimize application exposure.

337 3.7. *Bright*

338 Bright (Bakshi et al., 2019) is a software solution for those with signif-
339 icant vision impairment. It uses a modern optical see-through AR HMD
340 (head-mounted display) transparent front lenses with a projected display
341 overlay (Kiyokawa, 2012), which contains rich features, greater ease-of-use
342 and cheaper price.

343 While most AR solutions strive to enhance the user’s view of the world
344 by graphically adding objects to the actual world, their approach aimed to
345 address the problem that persons with vision impairments may be missing
346 out on the numerous layers of relevant information that come with vision.
347 A third type of AR is restoring some of these contextual layers by using a
348 speech interface to transmit the results of computational vision processing
349 (e.g. facial recognition). Bright has to be completely self-contained and
350 movable (i.e., not reliant on a local computer), in order to maximize ease
351 of use and comfort. Furthermore, given the wide range of remaining visual
352 acuity among possible users, the system has to be built to be usable even by
353 individuals with no vision at all. As a result, all parts of the user interface
354 have to be voice-controllable.

355 3.8. *CoVAR*

356 CoVAR (Piumsomboon et al., 2017) is a new VR and AR remote col-
357 laboration technology, which allows users to share a 3D model of AR visual
358 interaction. Natural inputs such as eye-gaze, hand movement, and gaze cues
359 are provided to facilitate this mixed platform cooperation.

360 CoVAR is a cross-collaboration solution with a server architecture in
361 which the host server is either an AR or VR server. The Microsoft HoloLens
362 helmet-mounted display is used for AR, whereas the HTC Vive is used for
363 VR. The CoVAR application was created in Unity 5.6. The HoloLens is
364 linked to CoVAR via a Wi-Fi connection on the AR side. The Vive’s ren-
365 dering engine connects directly to the second machine. The two devices
366 are linked by an Ethernet with TCP/IP connection, and Unity Networking
367 handles data sync.

368 3.9. *DUIRA*

369 DUIRA (Chang et al., 2010) is an interactive multimedia learning plat-
370 form which combines AR and Arduino capabilities for ecology education.
371 Learners can take AR marker data using a webcam and create 3D objects
372 on-screen, so that they can learn about plant growth through change AR
373 platform marker.

374 This interactive learning platform was created by utilizing FLARToolKit,
375 Adobe Flash, and an analog clock. Various AR Markers are taken as input
376 signals and filtered by FLARToolKit module and Flash to able to recognize
377 the image content of the AR Markers, and finally, 3D animation and effects
378 are rendered.

379 3.10. *KITE*

380 Kite (Piumsomboon et al., 2013) is mobile AR platform with a magnetic
381 tracker and a depth sensor that is generally available on a desktop system
382 for games and interaction creation. The main goal of this platform was to
383 show four different modalities based on hand input to provide a platform for
384 game designers experimenting with new gaming possibilities in AR.

385 3.11. *Nexus*

386 Nexus (Hohl et al., 1999) is a platform for mobile position-aware apps
387 developed by the University of Stuttgart. Figure 5 shows the architecture
388 of Nexus platform. It supports spatial modeling, network connectivity, and
389 virtual information representation . The architecture is divided into three
390 layers: abstraction of client devices, uniform presentation of information,
391 and fundamental function wrapper. To exhibit distinct data objects, a hier-
392 archical class schema is created. To provide universal access to actual and
393 virtual objects, it allows both local and distributed data management. To
394 enable scalability in various application circumstances, an adaptable module
395 is created. In terms of stability and portability, Nexus outperformed other
396 platforms.

397 3.12. *Vuforia*

398 The Vuforia platform offers a robust and effective computer vision-based
399 image recognition technology and includes a number of features that facili-
400 tates mobile applications and alleviates technical barriers for developers (Si-
401 monetti Ibañez and Paredes Figueras, 2013). Vuforia platform includes the
402 target management system (Target manager), cloud target database, device

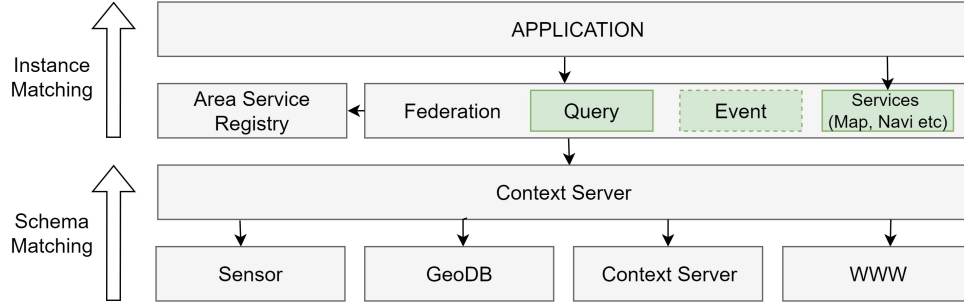


Figure 5: Nexus (Hohl et al., 1999): The architecture depicts the application’s workflow, in which data is delivered from the application to different needs, then to a server for processing, and finally to the sensor.

403 target database, and Vuforia engine. The target that a developer wants to
 404 track is uploaded as an input picture. The mobile app then uses a cloud con-
 405 nection or local storage to access the desired resources. A Vuforia SDK-based
 406 AR application contains a camera that captures frames and passes them to
 407 the tracker, an image converter that converts the image sensor data to a for-
 408 mat suitable for OpenGL ES rendering, and internal monitoring a Tracker
 409 that tracks the contents of the tracker. A tracker that can import and acti-
 410 vate many datasets simultaneously contains computer vision algorithms for
 411 detecting and tracking real-world objects in video captured frames. The SDK
 412 allows both native iOS and Android development, as well as the creation of
 413 AR apps in Unity that are readily transferable across multiple platforms. The
 414 Vuforia SDK supports multi-target setups, markerless picture targets, frame
 415 markers, and cloud recognition targets for monitoring one million targets at
 416 once. The SDK includes capabilities such as virtual buttons for localized
 417 occlusion identification, real-time picture target selection, and the ability to
 418 reconfigure and create target sets based on the circumstance. Following are
 419 the important features of Vuforia:

- 420 • Tracking is effective even when the object is partially obscured in low
 421 light circumstances.
- 422 • It provides quick local target recognition with the ability to simultane-
 423 ously monitor up to five targets.

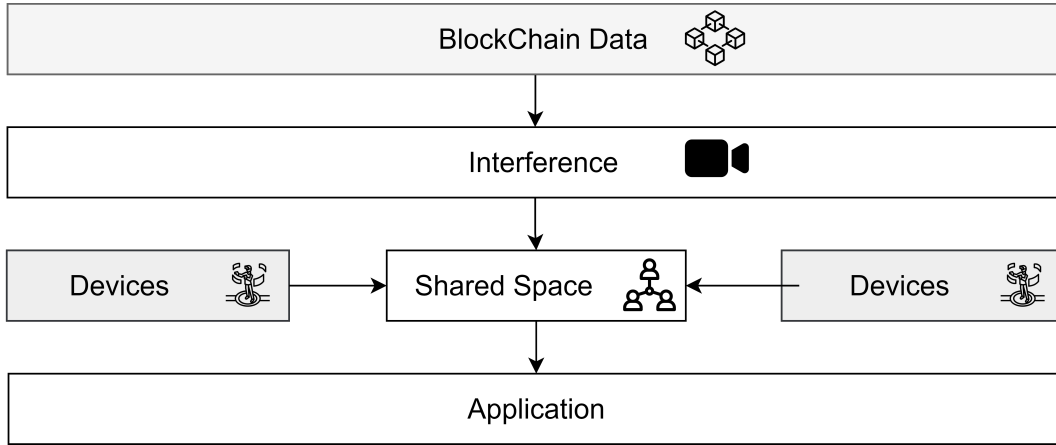


Figure 6: WARP : Worldwide Augmented Reality Platform. This figure is modified from the work by Sosin and Itoh (2019).

- Provides VuMarks, which are a new type of bar code for creating a unique and brand-conscious design and encode data that serves a AR target.

3.13. WARP: Worldwide Augmented Reality Platform

WARP (Sosin and Itoh, 2019) is an architecture that allows enthusiast organizations to contribute equally to build a sensor network. Sosin and Itoh (2019) proposed a distributed Blockchain-based architecture for storing entity pose tracking data. Users can submit tracking entities to the blockchain and distribute them via peer-to-peer network as shown in Figure 6. The underlying facts and foundations used by the other levels are defined by the context layer. It should have tools for quickly adjusting and expanding the scope of the monitoring area by adding or changing tracking entities and communicating these changes to all users. Inference layer receives the input from the previous layer and generates a spatial relationship graphs (SRG) around the user. SRGs, unlike scene graphs, represent connections between real-world and virtual items. Application layer required to allow for the integration of WARP-based apps. To enable the creation of a creative collaborative community, an API for this layer must be established and made available in order to nurture and build AR apps and interactions. When there is a large number of publicly accessible AR applications, widespread acceptance of such a platform will be seen.

445 3.14. Wikitude

446 Wikitude features picture monitoring and classification, 3D model gen-
447 eration with video overlay, and location-based augmented reality (Madden,
448 2011). The Wikitude SDK integrates geo-based and image recognition abili-
449 ties that can provide hybrid tracking. It is heavily based on web technologies
450 (HTML, JavaScript, and CSS) that allow developers to create cross-platform
451 AR experiences known as ARchitect worlds, which are simple HTML pages
452 that can use the ARchitect API to create AR objects. The system view
453 component called ARchitectView may be added to the app user interface to
454 integrate Wikitude SDK into apps. The Wikitude SDK is presently available
455 for both Android and iOS. Following are the important features of Wikitude:

- 456 • The JavaScript API is used to enable animation.
- 457 • 2D and 3D transformations are both available.
- 458 • It has a direction indication as well as a position tracker.

459 4. Augmented Reality and Artificial Intelligence in Industry

460 4.1. Importance

461 AR offers a useful interactive tool for reducing cognitive load by creat-
462 ing a connection between the physical task and supporting documentation
463 by displaying the information without interfering with the user’s ability to
464 concentrate (Kim and Dey, 2016). It is highly valuable in the manufacturing
465 industry, where a variety of jobs such as assembling and maintenance must
466 be accomplished as inexpensively and efficiently as possible.

467 AR applications initially started to show up in interfaces for mobile de-
468 vices (Larasser and Conradt, 1992), and then began appearing in the health-
469 care and automotive industries in 2004 and 2005, respectively (Fischer et al.,
470 2004; Regenbrecht et al., 2005). It eventually made its way into robotics
471 (Green et al., 2008), defense (Livingston et al., 2011), education (Patel et al.,
472 2012), and construction and building management (Chi et al., 2013). In 2017,
473 it gained popularity in the retail and fashion industries (e-commerce) (Dacko,
474 2017), and we began to see the trend of AR and AI in tourism (tom Dieck
475 and Jung, 2018) in 2018.

4.2. *AR in manufacturing*

AR can speed up industrial processes since it allows continuous information sharing without diverting the operator’s attention. As a result, it has become one of the Industry 4.0’s nine essential disruptive technologies (Rüßmann et al., 2015) along with big data analytic (Morabito et al., 2015), autonomous robots (Fahimi, 2009), simulation (Ingalls, 2011), horizontal and vertical system integration (Pérez-Lara et al., 2018), Industrial IoT (Butun, 2020), cybersecurity (Kemmerer, 2003), cloud computing (Dillon et al., 2010), and additive manufacturing (Gebhardt, 2011).

In the manufacturing industry, the majority of AR applications are in three areas: assembly, maintenance, and training. In order to conduct assembly sequences and processes, technicians must follow specified tasks and procedures within these three areas. Operators or staffs who take benefits of AR for installation and service can work with components or tools they have never worked with before. AR reduces the requirement for operational instructions to be memorized. Assembly operations using AR have witnessed 82% reduction in mistakes (Uijlings et al., 2013). Several experiments have been launched to introduce AR into assembly processes. To forecast the user’s assembly intent and handle virtual objects, AR was used to construct an interactive manual assembly design technique, e.g. (Wang et al., 2013b; Chen et al., 2015) applied AR for assembling a gearbox. AR also supports remote assembly processes to meet customization expectations of customers (Mourtzis et al., 2019). As a result, personalization can be easily incorporated to items.

AR has been identified as a useful technique for disseminating information and enhancing training methods. BMW (Werrlich et al., 2017) used a head-mounted display to instruct employees at BMW who assemble engines. Users were taught how to assemble a milling machine as well as how to weld (Peniche et al., 2012; Quandt et al., 2018). After conducting a usability research, it has been found that adopting AR must be promoted for training in industrial assembling and servicing occupations as AR is much more productive than VR (Gavish et al., 2015). In addition, AR has aided in design process by analyzing design variations (Bruno et al., 2019); assembly and disassembly planning (Wang et al., 2013a; Chang et al., 2020); robot orientation planning (Fang et al., 2013); users’ hand movement (Motoyama et al., 2020). AR can aid in the analysis and enhancement of manufacturing processes and products prior to their implementation. This will assist in completing the activities correctly on the first attempt. Furthermore, collaborative AR apps

514 can allow us to tap into the expertise of several people in different parts of
515 the world at the same time.

516 *4.3. Manufacturing aided by AI*

517 The widespread usage of sensors and robotics was ushered in by the in-
518 troduction of automation (Industry 3.0) in manufacturing. As a result of the
519 deployment of sensors, a vast amount of data from the manufacturing process
520 is now available, referred to as big data. The primary goals of Industry 4.0
521 include deriving inference from large data and making robots autonomous
522 so that they can make their own decisions (Motoyama et al., 2020). AI has
523 become widely used as a result of autonomous robots and massive data ana-
524 lytics. AI technologies offer a mechanism to manage and utilize this massive
525 amount of data (Aggour et al., 2019). This information can help production
526 systems adjust with the real time changing requirements in the industry sup-
527 ply chain and customers needs across product life cycle (Zhang and Kwok,
528 2018).

529 *4.4. Use of AI and AR in the Education and Industry*

530 AR-assisted industrial applications and AI-driven production have evolved
531 independently and have advanced manufacturing in their own ways. The ma-
532 jority of previous works have attempted to use AR to enhance manufacturing
533 tasks. Many of those attempts are marred by a number of flaws, which can
534 be addressed by incorporating AI into the AR computational framework.

535 Many business verticals, including healthcare, retail, automotive, and
536 transportation, are ready to be transformed by Industrial Internet of Things
537 (IIoT) technologies. The IIoT will increase dependability, output, and cus-
538 tomer happiness in numerous industries. While IIoT with Additive Man-
539 ufacturing (Gebhardt, 2011) improve existing processes and infrastructure,
540 the ultimate goal is to create wholly new and much-improved products and
541 services (Radziwon et al., 2014). Industries that understand how and where
542 IoT based solutions can create operational gains, new (or upgraded) prod-
543 ucts, services, and business models, will have a better chance of success. The
544 IIoT will be integrated with specific essential technologies, devices, software,
545 and applications focusing on enhancing existing processes and augmenting
546 present infrastructure. IIoT encompasses a wide range of technologies, many
547 of which necessitate careful integration and orchestration (Dagnaw, 2020).

4.4.1. Education

Rossano et al. (2020) created an AR application called Geo+, developed using a human-centered design method, to teach primary school students solid geometry in a modern paradigm. Students from third and fourth grades were separated into small groups and application guidelines were based on the Italian Education Department. Geometric shapes were displayed on student's devices, and if they selected one, an augmented item was displayed in a video replay. The authors performed assessments through a pilot study with 4-5 individuals in each group receiving a smart tablet running an AR application. The information was compiled using pre-test and post-test technique's with 10 sets of AR-based questions and activities, and the results were calculated using the t-test method. One limitation found in the AR program was that when students tried to pinch the images on a video to view details, but they were not responsive to zoom in or zoom out. Song et al. (2014) recommended using a multi-agent system technique for developing an AR supported smart classroom, which is a student-centered approach that involves different types of learning processes.

4.4.2. Construction Industry

With the induction of industry 4.0, the construction industry has driven a large portion of the development in integrating AR with AI. In the field of construction, highway work zones are considered as one of the most dangerous places to work. In the year 2018, critical incidents resulted in 124 worker deaths. A major limitation in the highway maintenance and operation is the lack of predictive safety measures that could warn the workers about dangers in advance. Sabeti et al. (2021) provide an integrated design approach for using current breakthroughs in AR and AI to improve highway worker safety by providing real-time multi modal notifications. Sabeti et al. (2021) achieved end-to-end operation latency of 24.83 FPS with 48.7% mAP for BDD100K dataset on the Xavier AGX Jetson board. They also reported real-time communication over 120m with a latency of 5.1ms for the maximum distance. Their mixed-method user research demonstrated that the proposed technology along with the user interface elicit an adequate level of interest and involvement from highway personnel.

4.4.3. Manufacturing Industry

AR and AI is widely used in a variety of sectors of the manufacturing industry. The current innovation pace for the AR development in this industry

584 is astonishing, especially when we consider Industry 4.0 and the adoption of
585 AI systems as discussed in Subakti and Jiang (2018). The authors also pro-
586 posed a concept aligned with an Industry 4.0 vision in which they build and
587 execute a rapid and marker-less mobile AR system for machine registration,
588 visualization, and interaction in smart factories. To detect distinct machines
589 and parts of machinery, a lightweight MobileNets based detection module
590 operating on mobile devices is employed (Howard et al., 2017). Following
591 are the processes in the manufacturing industry where AR is currently being
592 utilised.

593 a) **Testing**

594 Fiorentino et al. (2002) debuted the SpaceDesign MR workspace, based on
595 the StudierStube architecture that enables visualisation and change of car
596 body curvature and engine arrangement among other things. Volkswagen vi-
597 sioned to employ AR to compare computed and real-world crash test pictures
598 (Friedrich et al., 2002). Clear and Present Car, a simulation where one can
599 open the door of a virtual car and experience the inside, dashboard layout,
600 and interface design for usability testing, was created by the MR Lab using
601 data from Daimler-cars (Tonniss et al., 2005). Olwal and Feiner (2004) cate-
602 gorized application areas in construction where AR can be used to improve
603 performance.

604 b) **Assembly**

605 AR can be used to plan and evaluate assembly sequences successfully. In
606 an AR-based hybrid prototyping technique for assembly assessment, a mul-
607 timedia augmentation was used to assist a person in building an industrial
608 device Raghavan et al. (1999); Molineros (2002). A modular AR system was
609 created by Reinhart and Patron (2003) to assist with manual assembly and
610 assembly planning. For verifying and analyzing assembly sequence and in-
611 teractive validation, AR may be used in conjunction with CAD software as
612 well as a wearable computing device. (Liverani et al., 2004). An AR-based
613 interface may be established in the early phases of product design to aid
614 manufacturers with assembly design. Pang et al. (2006) suggested an AR-
615 based proof-of-concept system to assist users in designing assembly features
616 on a real-world assembly platform.

617 c) **Maintenance**

618 In the AR maintenance system, users are supplied with data relevant to
619 a particular task at hand at the appropriate moment Feiner et al. (1993).
620 As a result, AR has the potential to be used in sophisticated machinery
621 maintenance, servicing, inspection, and repair. Instructions will be simpler to

comprehend if they are provided in the form of computer-generated material overlaid on the production line, displaying the important tasks that must be completed step-by-step and how to do so.

d) **Product Design**

During the developed design process, or even during production, products or components are modified or adjusted several times. As a simple and quick tool, the AR simulation environment is great for design evaluation and ergonomic validation. Mixed prototyping, which mixes actual mock-ups of non-reconfigurable elements with 3D visual prototypes, is made possible by AR. Mixed prototyping implies showing virtual prototypes overlaid on actual prototypes in an upgraded environment, obviating the need for actual prototypes to be built (Balcisoy et al., 2000). It enables users to evaluate synthetic prototypes in real-time in a physical setting. It also enables users to conduct in-depth product evaluations, ergonomic validation, assembly sequence validation, and, on occasion, functional verification. Engineers can use high-fidelity simulations to evaluate novel materials, components, and systems before spending time and money building physical prototypes using a hybrid prototyping technique like this.

4.4.4. *Health Care*

Medical care is emerging as one of the most potential application areas for virtual system and AR interactive interface advancements. The development of real-time AR implementation, the clinical use of AR improvements, and the design and evaluation of medicinal training systems are all required (Van Krevelen and Poelman, 2010; Shoaib and Jaffry, 2015).

Doctors employ AR devices as a visualization help during surgery. MRI and CT scan acquire 3D data from patients in real-time, then display and integrate with the patient's real-time perspective. This is beneficial in minimally invasive operations since the difficulty with them is that they limit the surgeon's ability to see into the patient, making the procedure much more difficult. Here, AR aids doctors by providing interior images of the body (Nilsson and Johansson, 2008). Auloge et al. (2020) investigated the practicability, consistency, safety, and patient radiation exposure of an innovative navigational tool that combined AR and AI during percutaneous vertebroplasty in patients with vertebral compression fractures (VCFs). In laparoscopic liver resection surgeries, recognizing the three-dimensional (3D) spatial position and orientation of arteries and tumor(s) is critical. In combination of laparoscopic video footage, AR technology can enable surgeons

659 visualize the patient’s inside anatomy, which can save lives (Luo et al., 2020).

660 4.4.5. *Gaming*

661 Researchers indicate the possible AR settings given for integrated ani-
662 mated agents, and illustrate numerous sophisticated comprehensive materi-
663 als and scenario methodologies in AR through entertainment applications
664 (Barakonyi and Schmalstieg, 2005; Shoaib and Jaffry, 2015). The use of
665 video simulation in the real world elevates the gaming experience to new
666 heights. By rotating a flat-screen display (Maeda et al., 2003) with a nar-
667 row viewing angle and modifying the picture on the display panel according
668 to its orientation, (Maeda et al., 2003)’s framework allows users to recon-
669 struct a featured avatar that they can look at from all sides. Simulating
670 reality as closely as possible, combined with the incorporation of artificial
671 items into the actual environment, can foster interactive empathy amongst
672 participants and their characters. The future will become more dynamically
673 hybrid, with advanced digital artifacts blending into real ones, allowing us to
674 communicate throughout a wide range of spectrum like 5G/6G. Simultane-
675 ously, game-based visualization and interaction approaches may be used in
676 real-world AR applications (Luz et al., 2008).

677 It is now being looked at whether AAA title (Consalvo, 2012) games can
678 be employed successfully in the actual world of gaming using AR. AAA games
679 are high-quality video games produced by huge firms with enormous budgets.
680 The utility of AR applications in games can change how we think about
681 training and multi sensory learning. Recreational games will provide a wide
682 range of new applications in AR growth in the gaming industry (Liarokapis
683 and De Freitas, 2010).

684 Pokemon Go (LeBlanc and Chaput, 2017) was the first AR game to make
685 it to the top of the app store’s download charts. This new generation of
686 mobile internet AR games, on the other hand, is mostly new. Existing ideas
687 are only partially applicable to user comprehension. Customer reactions are
688 driven by hedonic, emotional, and social rewards and social norms, whereas
689 physical hazards inhibit consumer reactions. The value of these drivers, on
690 the other hand, varies depending on the type of user activity (Rauschnabel
691 et al., 2017).

692 5. Challenges

693 When it comes to applying AI approaches to AR-assisted manufacturing
694 applications, there are numerous technological obstacles.

- 695 • Production environments have insufficient object variation to facilitate
696 identification and tracking. As a result, developing generic AI is chal-
697 lenging. Collecting data to capture abnormalities is time and resource-
698 intensive, which makes training of AI systems to recognize anomalies
699 an expensive endeavor. Another problem is gathering and exchang-
700 ing massive data from industrial processes with the AR system. AR
701 systems must be updated and have context awareness in order to be
702 helpful, relevant data must be transmitted to them. If the data is not
703 properly secured, it is possible to gain control of the physical equipment
704 (Khan et al., 2017).
- 705 • Time-varying uncertainties are common in manufacturing processes
706 (Ginsberg et al., 2009). In order for statistical or AI methods to work
707 precisely for AR-assisted manufacturing technologies, these uncertain-
708 ties must be taken into account; numerous problems arise from the
709 management perspective.
- 710 • Implementing AI on a broad scale, as on a production floor, is a chal-
711 lenge in itself as most previous implementations have been designed
712 and evaluated in lab environments (Arinez et al., 2020). It may be re-
713 quired to acquire data from actual machine processes while constructing
714 training datasets for AI systems. Data from machine failures or mal-
715 functions would need to be collected in the event of predictive mainte-
716 nance, diagnostics, or prognostics. This data collection procedure could
717 be hazardous to the developer and expensive to the manufacturer. The
718 most effective component of supervised learning necessitates the use
719 of data labels. Labeling is time-consuming and can necessitate expert
720 labor in production applications.
- 721 • AI models are usually black-box in nature and difficult to interpret,
722 which cast doubt on their credibility. Users' faith in AI-powered AR
723 systems is eroded by a lack of explainability of models' predictions,
724 which must be interpretable or understood by human operators.

- 725 • Human operators and decision-makers must be in the loop and take
726 over anytime the AI or ML system fails unless operations can be totally
727 automated.
- 728 • The fast growth and implementation of AI systems have overtaken the
729 legal framework that governs how and where these systems should be
730 used effectively and securely in applications. To ensure that AI policy
731 is up to date and appropriate for the technology, the government will
732 require new technological knowledge (Dagnaw, 2020). Access to a com-
733 puter and human resources as well as legal and regulatory constraints
734 are critical at the organizational level when it comes to implement AI
735 in manufacturing.

736 While the above-mentioned technical and management hurdles might
737 impede AI's incorporation into AR-assisted production, the benefits of AI-
738 driven AR significantly exceed these challenges. AR systems will evolve into
739 sentient machines, similar to autonomous robots and sensors. AI-powered
740 AR systems will be able to work independently in the production environ-
741 ment with minimum human interaction. AI enables AR systems to interact
742 with the manufacturing environment and human operators to be unified as
743 a whole, facilitating Industry 4.0.

744 6. Conclusion

745 The extent of AI in AR-assisted industry applications is identified in this
746 review work. We investigated various industries including manufacturing
747 landscape where AR and AI fit into industrial operations. The study sum-
748 marized some popular deep learning algorithms employed in the advent of
749 AR, such as YOLO, MobileNets, and SSD models. Then, a brief review of AR
750 platforms and frameworks used to build the AR applications was provided.
751 Furthermore, we discussed the most recent research in both AR-assisted pro-
752 duction and AI-driven manufacturing.

753 Next, the primary technical and management challenges for incorporating
754 AI into AR operations were discussed in detail. Challenges with processing
755 of enormous information for AI in AR systems and organizational issues
756 such as safety, legislation, and trust in AI technology are the key obstacles.
757 However, AI-driven AR-assisted industrial applications' practical advantages
758 much outweigh these drawbacks. Despite the obstacles of applying AI tech-
759 niques into AR-assisted manufacturing applications, the effect of progress

760 and innovation will be significant improvements in AR systems' efficiency,
761 dependability, and utility. Although widespread adoption of AR applica-
762 tions in production is not yet done, the notion of ubiquitous AR is quickly
763 gaining attraction.

764 **CRediT authorship contribution statement**

765 **Jeevan S Devagiri:** Writing - Original Draft, Formal Analysis, Method-
766 ology, Software, Visualization, Data Curation. **Sidike Paheding:** Con-
767 ceptualization, Methodology, Writing - Reviewing and Editing, Supervision,
768 Funding acquisition. **Quamar Niyaz:** Writing - Reviewing and Editing,
769 Conceptualization, Funding acquisition. **Xiaoli Yang:** Writing - Reviewing
770 and Editing, Conceptualization, Funding acquisition. **Samantha Smith:**
771 Writing - Reviewing and Editing, Conceptualization, Funding acquisition.

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