

A 3.1-5.2GHz, Energy-Efficient Single Antenna, Cancellation-Free, Bitwise Time-Division Duplex Transceiver for High Channel Count Optogenetic Neural Interface

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Abstract—We report an energy-efficient, cancellation-free, bitwise time-division duplex (B-TDD) transceiver (TRX) for real-time closed-loop control of high channel count neural interfaces. The proposed B-TDD architecture consists of a duty-cycled ultra-wide band (UWB) transmitter (3.1–5 GHz) and a switching U-NII band (5.2 GHz) receiver. An energy-efficient duplex is realized in a single antenna without power-hungry self-interference cancellation circuits which are prevalently used in the conventional full-duplex, single antenna transceivers. To suppress the interference between up- and down-links and enhance the isolation between the two, we devised a fast-switching scheme in a low noise amplifier and

used $5\times$ oversampling with a built-in winner-take-all voting in the receiver. The B-TDD transceiver was fabricated in 65 nm CMOS RF process, achieving low energy consumption of 0.32 nJ/b at 10 Mbps in the receiver and 9.7 pJ/b at 200 Mbps in the transmitter, respectively. For validation, the B-TDD TRX has been integrated with a μ LED optoelectrode and a custom analog frontend integrated circuit in a prototype wireless bidirectional neural interface system. Successful *in-vivo* operation for simultaneously recording broadband neural signals and optical stimulation was demonstrated in a transgenic rodent.

Index Terms—Bit-wise time-division duplex (B-TDD), transceiver (TRX), closed-loop control, ultra-wide band (UWB), unlicensed national information infrastructure (U-NII) band, wireless neural interface.

I. INTRODUCTION

OPTOGENETICS is one of the most essential tools for neuroscience research since its first inception in 2005 [1]. With this technique, genetically modified neuronal activities can be excited or inhibited through optical stimulation at a specific wavelength. This cell type specificity ensures higher spatial resolution than the traditional methods such as electrical or ultrasonic stimulations [2]. To relate specific neural patterns of individual neurons to behavioral or cognitive variables, electrophysiological recordings should be combined with optogenetic stimulation [3], [4]. In order to implement a fully bidirectional optogenetic neuromodulation system, many design criteria must be concurrently fulfilled, including high-bandwidth signal recording from a massive number of neurons and precise temporal control of multiple optical stimulation sites. In addition, the implantable system must be integrated in a small form factor and light weight, while restricted by low power consumption and heat dissipation. More specifically, the total system weight, including power sources, assembly cables, passive components, and any interconnections, should be less than 5-gram for free-behaving animal tests in rodents such as rats [5].

Another essential prerequisite for the optogenetic neuromodulation system is a wireless data telemetry because it enables behavioral studies among multiple freely moving subjects without restrictions involved by cable tangling as well as eliminates

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tethering problems of the animals under test [6]–[8]. According to recent literatures [9]–[12], the key requirements for the wireless telemetry for neural interfaces are: 1) high data bandwidth to facilitate the growing demands for high channel-count requirement; 2) low power consumption due to scarce power sources and temperature rise restriction for living tissues [13]; and 3) small footprint for the consideration of longevity of implantable neural interfaces, while embedding 4) duplex functionality for closed-loop modulations. In particular, the recent demand for high channel-count neural interface has pushed the requirement in data bandwidth [14]–[20] aggressively. For uplink, the data rate easily exceeds a few hundred Mbps if the recording channel count becomes larger than 100 [16]–[20]. For downlink, a few 10s of kbps is sufficient as only short commands for simple channel adjustments are transmitted [9]. As closed-loop systems have been further developed, however, the higher channel count is also required in stimulation and the variables to manipulate stimulation patterns and to shape the waveforms have become complicated [4], [19], which demands a several Mbps downlink bandwidth. Current mainstream commercial chipsets such as Bluetooth low energy (BLE), although benefiting from its low power consumption, are not suitable due to its low uplink bandwidth and overdesigned downlink.

One of the most straightforward solutions to realize a full-duplex communication for real-time wireless data telemetry is to employ frequency division duplex (FDD) for receiving and transmitting using two separate antennas. Although it reduces the complexity for ASIC implementation [12], the system becomes bulky due to the footprint constraints not only for the antennas, but also for PCB routing; *i.e.*, the distance between the two antennas that needs to be met for interference cancellation directly correlated to signal wavelengths. As a result, FDD is not suitable for fully implantable applications where the system size needs to be minimized. To realize a compact wireless telemetry, Rajavi *et al.* adopted a surface acoustic wave (SAW) duplexer to provide high- Q bandpass filtering to two adjacent transmission frequency bands with only one antenna [10]. Since the duplexer provides only ~ 50 dB of isolation between TX and RX, an extra cancellation scheme or isolation method is required for a large signal bandwidth. Aside from the isolation problem, the size of the duplexer itself is also $4\times$ larger than the whole chip, which also makes it unsuitable for implantable applications. Instead of commercial off-the-shelf components (COTS), the on-chip signal self-interference cancellation (SIC) schemes either in the analog front-end or in digital circuits have been proposed [11], [21], but their high power consumption and the complexity make the scheme unacceptable for the target application.

In this paper, we report an energy-efficient bit-wise time-division duplex (B-TDD) wireless transceiver for real-time, high channel count, optogenetic neural interface. The proposed transceiver is suitable for freely behaving small animal studies *in vivo* because the duplex operation can be realized with a single antenna, resulting in a compact and high energy-efficient uplink/downlink at 9.7 pJ/b and 0.32 nJ/b, respectively. In addition, a fast-switching low noise amplifier (LNA) and a simple winner-take-all voting circuit have been implemented to achieve reliable operation by enhancing the isolation between up- and

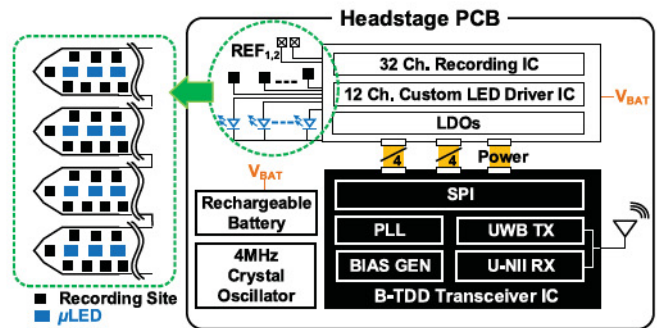


Fig. 1. Wireless optogenetic neural interface block diagram with the proposed B-TDD transceiver.

down-links. Unlike the conventional time division duplex (TDD) operation [22] where the data RX and TX cannot be simultaneously realized without dedicated memories, the proposed B-TDD scheme seamlessly sends and receives data with no storage place on- or off-chip. To verify the feasibility of the proposed B-TDD wireless transceiver *in vivo*, the fabricated transceiver chip has been integrated in a prototype optogenetic wireless neural interface headstage where a custom bidirectional neural interface AFE circuit chip [19], an ultra-light rechargeable Li-battery, a micro-machined opto-electrode [4], [23], and a commercially available antenna are assembled, as shown in Fig. 1. The B-TDD transceiver can support up to 200 Mbps uplink and 10 Mbps downlink for simultaneous recording and stimulation, respectively. This allows for embracing up to >1000 -channel broadband neural recording with 10-b resolution and >100 -channel stimulation with 8-b stimulation waveform adjustment.

This paper is organized as follows. The working principle of the proposed B-TDD is introduced and the related circuit architecture is described in Section II. In Section III, the architecture of the proposed B-TDD transceiver is described. This section provides the detailed description of essential integrated circuit blocks used to realize the proposed B-TDD transceiver. The bench top and *in vivo* measurement results for the proposed transceiver and the prototype wireless bidirectional optogenetic interface are given in Section IV. Finally, Section V concludes the paper.

II. BIT-WISE TIME-DIVISION DUPLEX TRANSCEIVER

The one of the most essential parts for the wireless bidirectional neural interface to be used for the electrophysiology study with freely behaving small animals is the energy-efficient and compact (*e.g.*, having a single antenna) duplex transceiver. To realize an energy-efficient, cancellation-free, single-antenna solution for the duplex wireless transceiver, we devised the B-TDD operation by utilizing the duty-cycled operation of an UWB transmitter and a fast-switching receiver, as shown in Fig. 2. In the time domain, the UWB transmitter emits pulses in a very short duration, which frees up a time slot for receiving signals, as shaded light gray in Fig. 2(a). With a data rate of 200 Mbps, it gives “blank time space” which is almost 80% of a single TX time frame of 5 ns at the given the carrier

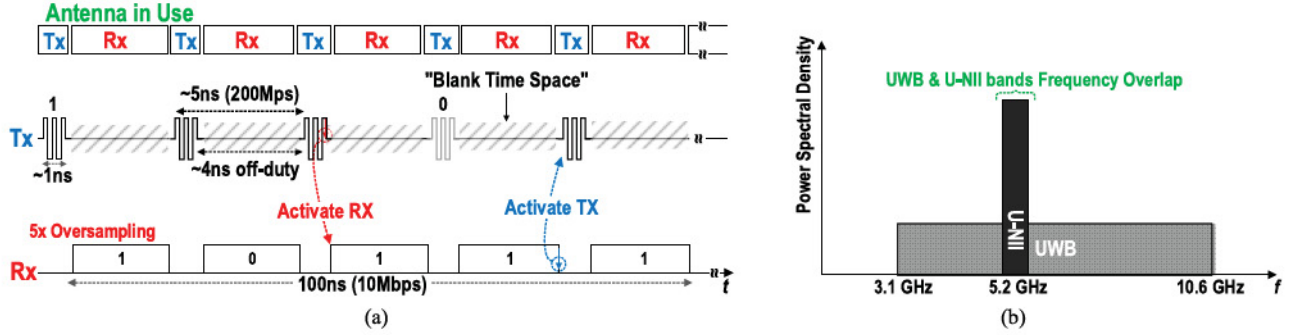


Fig. 2. Conceptual diagram for the waveform allocation in time domain (a), in frequency domain (b) in the proposed B-TDD architecture.

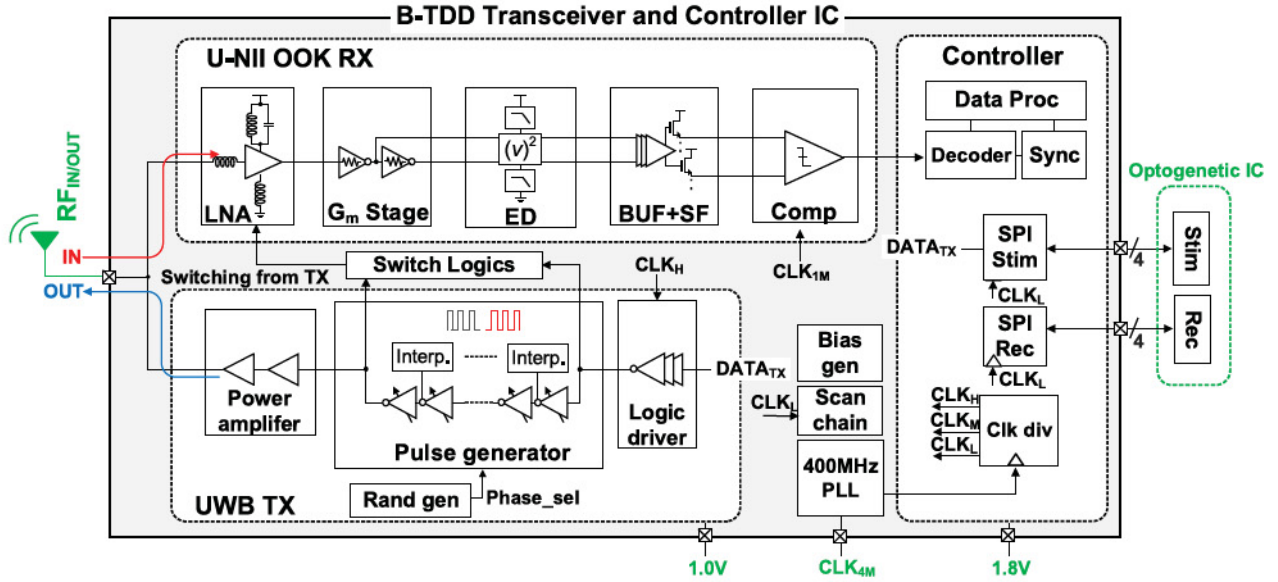


Fig. 3. Top level circuit architecture of the proposed cancellation-free B-TDD transceiver and controller.

frequency of 4 GHz for the UWB TX. This allows for receiving data like a conventional time-division multiplexing (TDM). In frequency domain, due to the wide band characteristics of the UWB, it is evident that we can use the same antenna for the RX, if the RX band resides within 3.1–10.6 GHz as shown in Fig. 2(b). In our transceiver implementation, a center frequency of 5.2 GHz has been chosen for the unlicensed national information infrastructure (U-NII) band receiver structure. By taking advantage of asymmetrical transmission in the proposed transceiver architecture, the receiver takes incoming signals in between the transmission with a lower data rate and provides 5 $\times$ oversampling to enhance reliability. This B-TDD data transmission scheme can realize the real-time closed-loop control with a single antenna, without a power-hungry self-cancellation scheme between TX and RX packets.

Fig. 3 shows the top-level circuit architecture for the implementation of the B-TDD transceiver. It consists of a continuous-time U-NII band receiver, a feedforward edge combiner-based UWB transmitter, a digital controller, and a 400 MHz phase-locked loop (PLL) for the system integration. As mentioned,

the operating bands of the receiver and transmitter are fully overlapped, thus one small antenna can be shared. The U-NII band receiver is designed to interface with the transmitter with a full data rate of 10 Mbps. The U-NII band receiver is comprised of a fast-switching LNA with the first stage amplification of 21 dB, a G_m stage for additional gain of 12 dB, an envelope detector (ED) to down convert the signal to baseband, a buffer stage, and a dynamic comparator for demodulation. The fast-switching LNA is a key block to realize reliable operation of the proposed B-TDD operation, which will be covered in detail in the Section III-A. For TX, our previous feed-forward edge combiner-based UWB structure [24] has been modified with additional phase chopping to enhance energy efficiency. A digital controller with a serial peripheral interface (SPI) is also implemented on-chip to handle the demodulated signal from the receiver with 5 $\times$ oversampling, and to decode the signal and redistribute to the SPI for communication with the recording/stimulation module. A 400 MHz type-II PLL is adopted to generate a system clock from a 4 MHz crystal oscillator [25]. Due to the page limitation, the design of the PLL will not be described in this paper

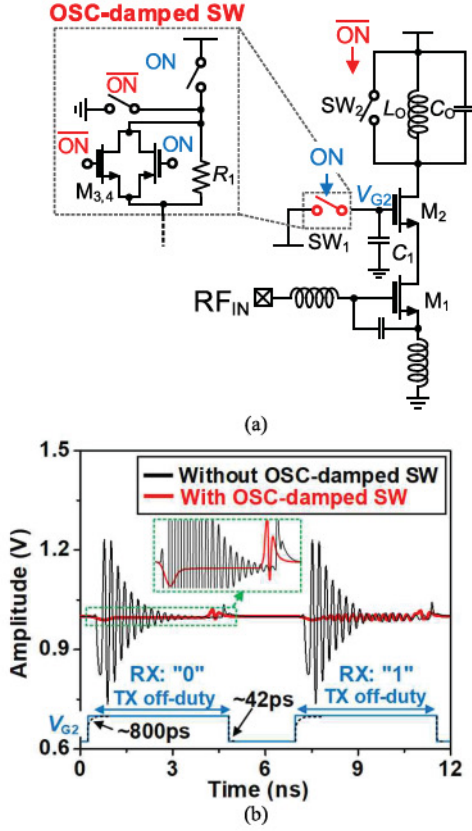


Fig. 4. (a) LNA schematic with the OSC-damped switch, and (b) Damping comparison in SPECTRE simulations.

III. INTEGRATED CIRCUIT IMPLEMENTATION

A. Fast Switching U-NII Band Receiver

The fast and complete switching in the LNA is a key requirement for the reliable operation of the B-TDD architecture because it guarantees a low crosstalk between the up- and downlinks, resulting in low BER. To implement such a switching in the LNA, we use two switches (SW_{1,2}) to control the gate bias of M₂ as well as the output tank in the LNA, as shown in Fig. 4(a). The on-and-off timings of the switches is directly correlated with the transmission signals with a delay of <1 ns, as shown in Fig 2(a). When the baseband sends the data to the transmitter, the data edge is forwarded to logic gates to disable the RX amplification. As soon as TX pulses are transmitted, the last edge will then active the RX to start receiving signals. With the given technology of 65 nm CMOS processes, the fast switching within 4 ns of the time slot is easily implementable. However, if the switching is too fast, particularly during on-switching, it can inject instantaneous current into the tank, resulting in prolonged ringing in a high-*Q* tank. Fig 4(b) shows the ringing (black line) in the output of the LNA from SPECTRE simulations. To alleviate the erroneous decision caused by the ringing, we developed an OSC-damped switch that inserts a 2.5 kΩ damping resistor (*R*₁) in series in the gate of M₂. While turning on the LNA, the charging path *R*₁–*C*₁ gives a larger time constant (800 ps) to smooth out the transition of current injection into the tank, consequently suppressing the ringing, as shown in the enlarged

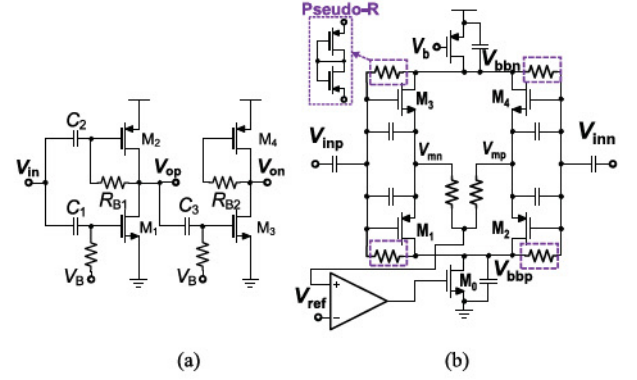


Fig. 5. (a) Self-biased single-to-differential *G_m* stage, and (b) Envelope detector.

section in Fig. 4(b). In the real implementation, the time constant would not be precise as intended, however 20% error of the time constant would be good enough to suppress the ringing. On the other hand, when the edge triggers the RX switch signal to transition from short to open, the oscillation is inherently suppressed by the SW₂ in parallel with the tank. Therefore, to restore the fast operation, a transmission gate composed of M_{3,4} is inserted to reduce the equivalent resistance down to ~130 Ω, recovering the fast operation. In the core of LNA, a source-degeneration scheme is adopted to achieve a narrow band response in our application.

To provide additional gain in the receiver, an inverter-based, self-biased single-to-differential *G_m* stage is used as shown in Fig. 5(a). In ultralow power applications, an inverter-based resistive-feedback topology is popular because of its simplicity and smaller area consumption compared to *LC* tanks [26]–[28]. Resistive feedback, inverter-based amplifier exhibits a large gain-bandwidth product, resulting in a larger gain since the effective input transconductance becomes twice by utilizing both M₁ and M₂. As shown in Fig. 5(a), *C*₁ and *C*₂ work as decoupling capacitors to separate the bias from the previous stage, *i.e.*, LNA, while M₁ is biased via an additional current source set by *V_B* and M₂ uses a resistive feedback to set the gate biasing point. The output of the first stage will then be forwarded to the gate of M₃ through a decoupling capacitor *C*₃ and further amplified to produce a differential output for envelope detector (ED).

To provide a differential input for the ED, an extra stage to produce a 180-degree phase shift is also implemented through M₃, M₄ and R_{B2}. Note that *v_{G3}* is equal to *v_{on}*. After further amplification in the *G_m* stage, the received signals are sent to the ED differentially. The ED circuit is shown in Fig. 5(b). It takes advantage of the drain current behavior when biased in weak inversion [28]. We have chosen this ED structure because it provides extra gain compared to conventional passive RC filter. When biased in weak inversion, the current of the input transistor pairs (M₁₋₄) can be written as (1) [28], [29]:

$$I_d = I_0 e^{\frac{v_G - V_{th}}{nV_T}} \left(e^{-\frac{v_S}{V_T}} e^{-\frac{v_D^+}{V_T}} - e^{-\frac{v_D^-}{V_T}} \right) \approx I_Q e^{\frac{-v_D^+}{V_T}} \quad (1)$$

where $I_Q = I_0 \cdot \exp[(v_G - V_{th})/nV_T] \cdot \exp(-v_S/V_T)$, *V_T* is the thermal voltage, *V_{th}* is the threshold voltage, and *n* represents a

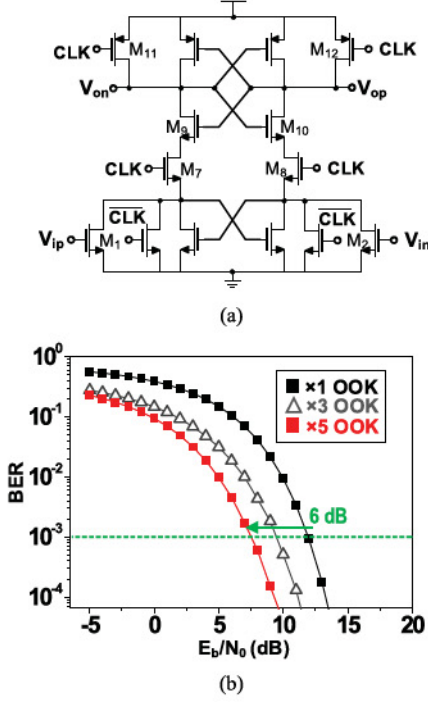


Fig. 6. (a) Dynamic comparator and (b) BER vs. OSR demodulation.

correction factor in the slope of transfer functions for losses due to capacitive division. The power series expansion of (2) can be written as:

$$I_d = I_Q \left[1 + \left(\frac{-v_i^+}{V_T} \right) + \frac{1}{2!} \left(\frac{-v_i^+}{V_T} \right)^2 + \frac{1}{3!} \left(\frac{-v_i^+}{V_T} \right)^3 + \dots \right] \quad (2)$$

If the input signal is written as a single tone sine wave, $v_i^+ = A \sin(2\pi f_{in} t)$, then the 2nd-order term of (2) becomes:

$$I_d \approx \frac{I_Q A^2}{4V_T^2} [1 - \cos(2\pi \cdot 2f_{in} t)] \quad (3)$$

From (3), the DC term can be obtained while the $2f_{in}$ term can be easily filtered out. With the differential structure shown in Fig. 5(b), the differential output voltage ($v_{on} = v_{mp} - v_{mm}$) can then be expressed as:

$$v_{on} = -\frac{I_Q A^2 R_{out}}{2V_T^2} \quad (4)$$

while R_{out} is the output resistance seen at the node. The received RF signal is fed into both gate and source of transistors (e.g., M_{3,4}) to provide a twice gain before squared and low pass filtered to extract the envelope. To provide a differential output, the bottom part of the ED is the mirrored structure by adopting PMOS transistors (M_{1,2}) and a common-mode feedback current source M₀ to define the operating point. With the same analysis method, v_{op} can be easily obtained.

The down-converted signal is buffered and demodulated by a dynamic comparator. A two crossed-coupled pair structure has been employed for the dynamic comparator as shown in Fig. 6(a). When CLK = low, M_{11,12} drag the output nodes to the supply, while M_{7,8} are shut off, leaving no constant current

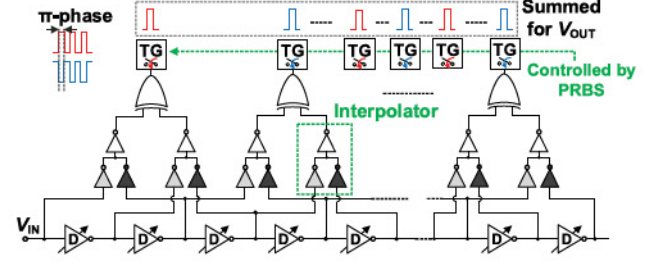


Fig. 7. Random delay frequency hopping edge combiner-based pulse generator.

flowing to either branches. In the meantime, M_{3,4} drag the drain of the input pair to ground for a clean reset. When CLK switches from low to high, the difference at the drains of input transistors gets positively reinforced and further discharges the output node v_{op} and v_{on} at a different rate due to the voltage difference between the input pair. The output latches further enhance the output difference until one of M_{9,10} is turned off, and the comparison process is completed. The transition current also gets shut off once the comparison is completed; so no static power is consumed. During the emission of transmitting signals, the switch pairs in the LNA turn off amplification, which may lead to approximately 20% of signal power loss in receiving the data when compared to the continuous time operation, assuming the transmitter is operating at its full speed. To compensate for this loss, the comparator oversamples $5\times$ at 50 MHz and the demodulated data will be sent to a voting circuit block in a digital controller to determine its final output.

B. Winner-Take-All Voting Scheme

With RX sampling at 50 MHz, the $5\times$ oversampled data in the dynamic comparator is sent to the digital controller for winner-take-all voting. The voting system will output the demodulated 1-b result based on the majority poll among 5 incoming data. The voting scheme can improve the BER performance by 6 dB at 0.1% error rate compared to the case without the voting from SPECTRE simulations, as shown in Fig. 6(b).

C. Overlap-Free Frequency Hopping Transmitter

For TX, we modified our previous feed-forward edge combiner-based circuit [24]. The simplified conceptual diagram of overlapping-free, frequency-hopping (FH) pulse generators is shown in Fig. 7. In the UWB TX, the generated pulses with regular repetition rates generate the undesirable spectrum of transmitting signals, called “spectral (or comb) lines,” limiting the maximum transmittable power. To address this issue, we adopted the randomly delayed pulses used in DB-BPSK [30]. This scheme allows the UWB transmitter to emit higher power without violating the federal communications commission (FCC) mask, and the communicating distance can be improved by utilizing a FH technique [31]. To implement this scheme, the generated pulses are separated into two groups: red and blue pulses in Fig. 7. With the randomly selected on/off transmission gates (TGs) by the 7-bit pseudorandom binary sequence (PRBS) generator, it produces a pulse train which has

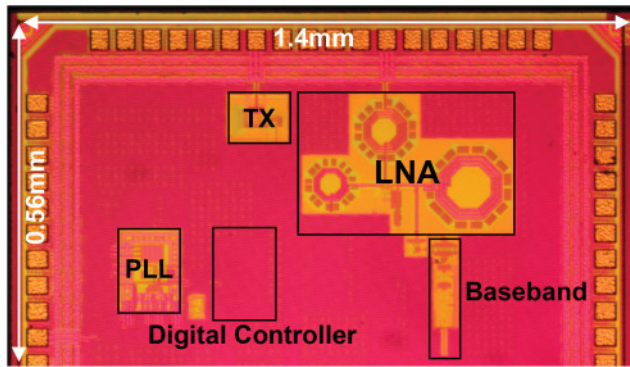


Fig. 8. A microphotograph of the fabricated transceiver chip.

a phase delay of π between the transmitted signals, achieving the random delay between pulse sets. A frequency hopping scheme is also implemented with a variable delay cell chain, by adjusting the current course in each delay cell [24].

D. Digital Controller

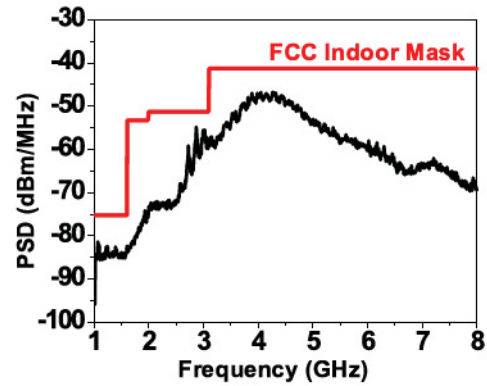
To communicate with the base station and AFE module, a digital controller was also implemented in the transceiver chip. When the module is first initialized, a known serial pattern is sent to the chip with a phase delay. From this, the transceiver chip can capture the correct timing, since the demodulated signal is oversampled at 50 MHz. After this synchronization is completed, the digital controller sets up the recording and stimulation channel parameters based on the header of each bit stream. Once the recording channels are all set, the controller will repeat the command for the stimulation channels. To communicate with the stimulation and recording AFE module [18], two sets of SPI buses are implemented in the controller. The SPI clocks (SCLK) are derived from the 400 MHz PLL while the enable signals are activated based on the header of the received signal. Aside from the communication signals with the recording and stimulation AFE module, the controller also controls the hopping and random delays in the transmitter to eliminate the comb lines and enable high emission power up to 0 dBm.

IV. EXPERIMENT RESULTS

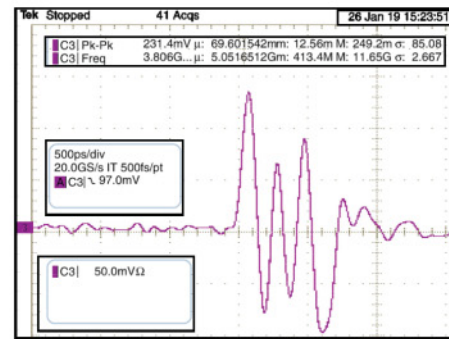
The transceiver chip was fabricated in a 65 nm RF CMOS process. The fabricated chip microphotograph is shown in Fig. 8. The chip area is $1.4 \times 0.56 \text{ mm}^2$ including pads, while the core area is less than 0.35 mm^2 .

A. Benchtop Wireless Module Validation

Fig. 9(a) shows the power spectral density (PSD) of the UWB transmitter. The PSD is under the FCC indoor mask at 200 Mbps where pseudorandom binary sequence (PRBS) trains are generated from frequency hopping and a random delayed scheme. The pulse overlapping is prevented; so there is no peak at half the transmitting frequency, 2.4GHz. Fig. 9(b) shows the enlarged transmitted waveform with P_{out} of -8 dBm and a carrier frequency of 4.8GHz. Fig. 10(a) shows the

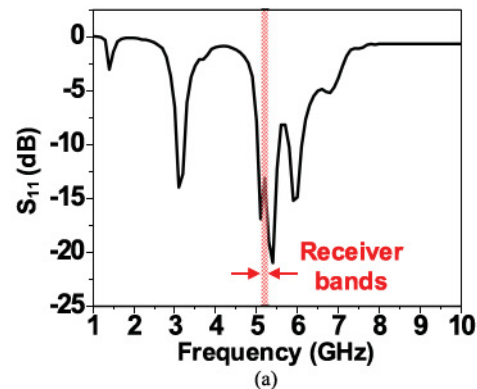


(a)

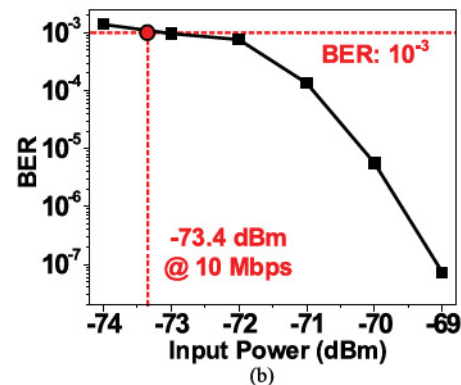


(b)

Fig. 9. (a) UWB PSD at a data rate of 200Mbps and (b) Snapshot of the enlarged transmitted waveform.



(a)



(b)

Fig. 10. Receiver characteristics: (a) Input S_{11} , (b) BER vs input power.

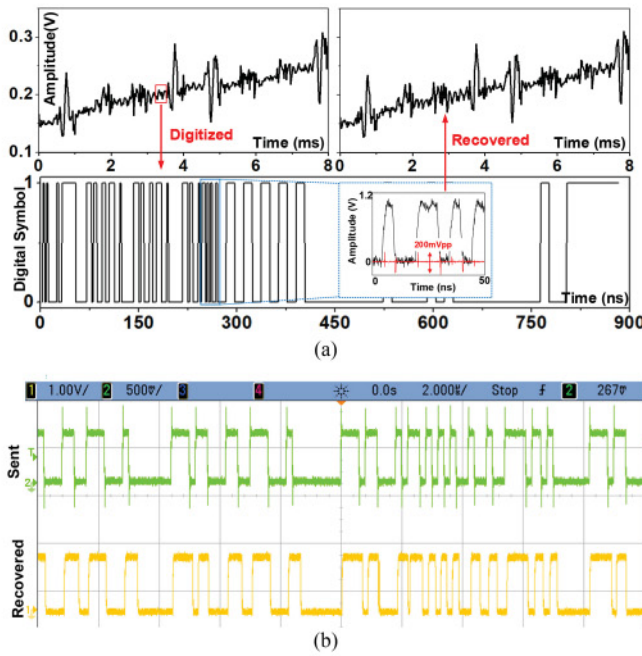


Fig. 11. Transient waveforms: (a) in the transmitter and (b) in the receiver with pre-recorded neural signals.

input matching (S_{11}) of the receiver LNA. The value is under -10 dB at the band of interest (5.15 – 5.25 GHz). The BER is shown as a function of input power in Fig. 10(b). The detectable input power with $< 0.1\%$ BER is -73.4 dBm at 10 Mbps. The time-domain performance of the fabricated B-TDD transceiver has been characterized. Fig. 11(a) shows the transient waveform of the fragmented digitized signals from the pre-recorded neural signal sent to the transmitter. The transmitter output pulses are generated when the input signals toggle, as shown in the inset of Fig. 11(a). The recovered and demodulated waveforms from the receiver are shown in Fig. 11(b) at 10 Mbps. The performance of the fabricated transceiver is compared with the other state-of-the-art works in Table I. Our work achieved a high data rate of 200 Mbps from a relatively lower power consumption thanks to the devised B-TDD scheme that does not require power-hungry SIC circuits, resulting in decent energy efficiencies in both up- and down-links, 9.7 pJ/b and 0.32 nJ/b respectively, while allowing high output power emission. The works in [20] and [31] showed better energy-efficiencies than ours but their output power emissions are limited because of insufficient TX/RX isolations. Our implementation also does not require any additional passive filters nor duplexers at the input/output of the transceiver, thereby the overall system can be compact. In addition, our transceiver chip contains all the digital control functions and clock generation, which further reduces complexity in system integration and operation for *in vivo* experiments.

B. Prototype System Integration and *in-vivo* Validation

A prototype wireless bidirectional optogenetic system is implemented to verify the full functionalities and performance

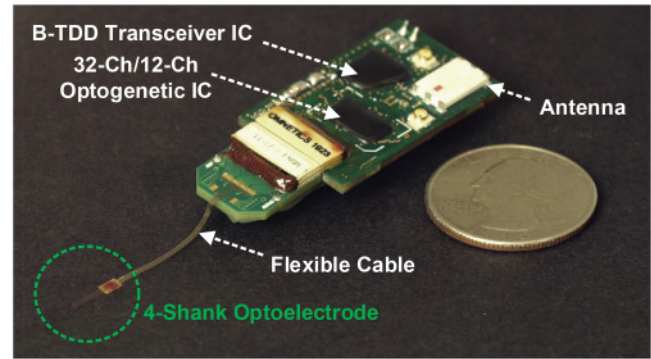


Fig. 12. Assembled optogenetic neural interface where a proposed B-TDD transceiver, a micromachined 32/12 optoelectronic probe, a 32/12 custom AFE and simulator are integrated in a miniaturized headstage [18].

of the B-TDD transceiver. The integrated prototype system is shown in Fig. 12. The system used a commercially available optoelectrode with 12 μ LEDs and 32 recording sites (μ LED-12-32-F, NeuroLight Technologies, USA) [19], [21] in accordance with the functional block diagram illustrated in Fig. 1. In the future, we may be able to integrate a high-density optoelectrode which has over hundreds of recording channels and optical stimulation sites when available [35]. A custom optogenetic AFE IC with low-power 32-channel electrical recording and 12-channel pulse-shaping optical stimulation [19] was assembled with the fabricated B-TDD transceiver chip. Also, a few COTS components, such as a Li-battery (GM301016 TUV UL1642, PowerStream, Canada) and an antenna (ANT1085, TDK Corporation, Japan), were added. The size of the headstage PCB is 38×17 mm². The total system, including the battery, weighs < 5.0 grams that satisfies the weight requirement for rodent experiments ($< 10\%$ of rodent weight). The system can record, stimulate, and communicate data continuously for more than 3 hours without recharging the battery, when operating at 100 μ A with 10% duty-cycled optical stimulation.

In vivo experiments were carried out to validate the feasibility of the prototype wireless bidirectional optogenetic system for simultaneously recording and stimulation on a rodent. The animal procedures were approved by the Institutional Animal Care and Use Committee of the University of Michigan IACUC (protocol number: PRO-7275). One male C57BL/6J mouse (32 g) and one transgenic male mouse (JAX stock #007612) were used in this study. The mice were kept on a regular 12h–12h light–dark cycle and housed in pairs before surgery. No prior experimentation had been performed on these animals. AAV5, CaMKII promoter driven channel rhodopsin-2 (ChR2, AAV5-CaMKIIa-hChR2(H134R)-EYFP) virus was injected in CA1 region of the hippocampus of the wild type of mouse, resulting in expression of ChR2 in pyramidal neurons. Atropine (0.05 mg/kg, s.c.) was administered after isoflurane anesthesia induction to reduce saliva production. The body temperature was monitored and kept constant at 36 – 37 °C with a DC temperature controller (TCAT-LV; Physitemp, Clifton, NJ, USA). Stages of anesthesia were maintained by confirming the lack of nociceptive reflex. Skin of the head was shaved, and the

TABLE I
PERFORMANCE COMPARISON OF DUPLEX TRANSCIVER SYSTEMS

Publication year	This work	2011 [12]	2015 [21]	2020 [22]	2016 [31]	[32]	2017 [34]
Technology (nm)	65	65	65	130	180	N/A	65
Frequency (GHz)	5.2/UWB	0.8-1.4	0.1-1.5	0.915	2.4/UWB	2.4	1.0-1.8
Duplex Scheme	^a Bit-wise TDD	FD/FDD	FDD	TDD	FDD	^b Packet-wise TDD	FDD
Isolation Technique	Fast-switching LNA	Integrated RF filters	Passive mixer first	Switch Controlled	TX spectrum shaping	Switching LNA	Cancellation DAC
T X	Data rate (Mbps)	200	25	20	2.5	2	500
	Max P _{out} (dBm)	^c -3	^c 15	^c -15	-30.6	-18-0	^d -60/-10
	Power (mW)	1.94	N/A	N/A	0.0482	33.8	3.5
	FoM (pJ/b)	9.7	N/A	N/A	19.28	16900	7
R X	Modulation	OOK	QAM	N/A	OOK	N/A	OOK
	Data rate (Mbps)	10	25	6-192	0.1	0.25-2	100
	Power (mW)	3.2	63-69(RX) + 138 (Canceller)	^f 43-56	0.0275	40.5	5
	FoM (nJ/b)	0.32	8.28	^g 0.29	0.275	20.25	0.05
	Sensitivity(dBm)	-73.4	^h -86	^h -81.2	-69	-82	-79.9
Antenna Size (cm ²)		ⁱ 1 × 0.8	N/A (a pair)	^j 5 × 0.9	10.2 × 10.2	1 × 1	1.5 × 1.65
Integration level		Fully integrated	RX + LO + Canceller	RF frontend + LO gen.	Rf frontend + RF-DC	External clk. + controller	Fully integrated
Passive filter		Not required	Required	Not Required	Not Required	Required	Required
Die Area (mm ²)		0.35	4.8	1.5	1.4	0.8	N/A

^aswitching time < 1 ns

^bswitching time = 130 μs

^cwithout external self-interference cancellation

^destimated with noise figure, bandwidth, BER, and isolation

^erequires digital backend self-interference cancellation of >50dB [39]

^ffull chip

^g(full chip power)/(RX BW)

^hBER < 10⁻³

ⁱCommercial antenna used

^jPulseLarsen, W1903

surface of the skull was cleaned by hydrogen peroxide (2%). A 1 mm diameter craniotomy was drilled at 1.5 mm posterior removed over the dorsal CA1 region and virus was injected. Viruses were purchased from the University of North Carolina Vector Core [36]. After the surgery, the craniotomy was sealed with Kwik-Sil (World Precision Instruments) until the day of recording. On the day of recording, mice were anesthetized with isoflurane, the craniotomy was cleaned (virus injected animal) or prepared (transgenic animal) and the μLED optoelectrode was lowered to the CA1 region of the hippocampus. 15 min length of simultaneous recording and stimulation were performed using one μLED from on shank (all μLEDs were tested at least once). The AFE on the headstage was used to record signals ($n = 32$ channels) and to deliver current pulses ($n = 12$ μLEDs). The recorded data were analyzed by custom scripts written in MATLAB (MathWorks, USA). Offline, spikes were detected and automatically sorted using the Kilosort algorithm followed by manual curation using Phy to get well-isolated single units (multi-unit and noise clusters were discarded). To measure the effect of LED stimulation on neuronal activity, peristimulus time histograms (PSTHs) were built around stimulus onset (spike trains were binned into 10-ms bins). Baseline and light-induced firing rate were calculated for each single unit. Baseline was defined as light-free epochs (500 ms) between trials and stimulation period as the light was on (5000 ms). Wilcoxon-signed

rank test was used to compare the mean firing rate per trial ($n = 43$ trials) during baseline and LED stimulation.

The distance between the on-PCB transceiver and the fabricated on-chip transceiver is 1 meter in the setup. The *in vivo* result in transient is shown in Fig. 13, 13(a) and (b) show the direct output from the frontend circuit and the retrieved signal from base station, respectively. 100 μA, 1 Hz with 50% duty cycle current is applied for μLED optical stimulation. With one meter of distance, the retrieved BER maintains < 0.1%. Fig. 14(a) shows the location of μLED probe in the *in-vivo* testing setup. The electrode was lowered to the CA1 region of the hippocampus where LED-2 on shank 3 was turned on at 100 μA, 1 second period and 30% duty cycle. Fig. 14(b) shows the raw signal recorded on shank 3. 2 trials of the light induced neuronal effects are shown, the effect is highlighted in red. Light induced artifacts are also present in the raw data at stimulation onset and offset. Fig. 15(a) shows the details of shank 3 of the μLED probe. Note that LED-2 was illuminated during the example trances. Fig. 15(b) shows the high pass filtered signal of Fig. 14(b) where 4th order Butterworth filter with 600 Hz cutoff corner is applied. Light-induced activity is highlighted in red. Table II shows the comparison of this work to the other recent wireless bidirectional systems. This prototype wireless bidirectional optogenetic achieves the smallest size and weight with low power consumption among the state-of-the-art

TABLE II
COMPARISON OF WIRELESS BIDIRECTIONAL OPTOGENETIC SYSTEMS

Publication year		This work	2020 [20]	2020 [37]	2018 [38]
Technology (nm)		65 (RF) 180 (Rec, Stim)	350	180 & COTS (Stim)	130 & COTS (RF)
Bidirectional communication method		B-TDD	FDD	TDM	TDM
Power source		Li-battery	Inductive link	Li-battery	LiPo-battery
System size (mm ²)		38 × 17	70 × 50	43 × 20	—
System weight (g)		4.9	17	6	—
Number of recording channels		32	16	2	10
Number of stimulation channels		12	16 (Optical) 8 (Electrical)	1 (Optical) 1 (Electrical)	4
Recording	Bandwidth (Hz)	1–10k	(1–100) – 10k	0.05–187.5	0.5–7k
	Resolution (bit)	10	10	8.5 ¹	9.8 ¹
	IRN (μV_{rms})	5.7	3.5	1.3	3.2
	Power/Channel (μW)	23.6	50	14.5	11.2
Optical Stimulation	Current range (mA)	0–1	0.8–24.8	0–120	0–35
	Resolution (bit)	10	5	4	N/A
	Modulation	Arbitrary	Exponential decay	PWM	PWM
	Power/Channel (μW)	31	137.5	—	—

¹ADC ENOB

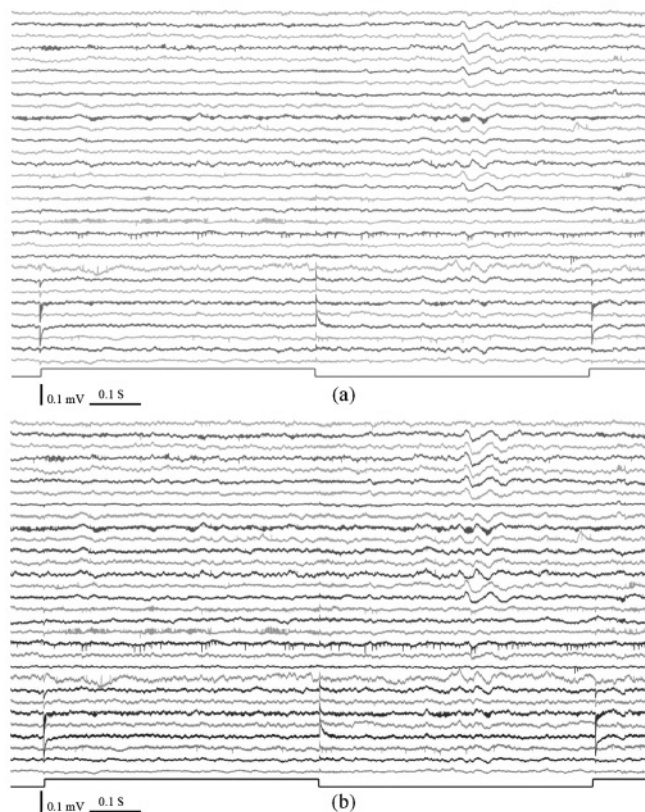


Fig. 13. In vivo testing result: (a) Direct output from the AFE chip and (b) Recovered signal from base station (transceiver output).

works, demonstrating that it is suitable for *in vivo* experiments in freely behaving animals. In addition, considering the high bandwidth allocated for the proposed transceiver, one can easily extend the implementation for higher channel-count wireless neural recording and modulation systems (with pulse shaping functions) without much extra cost and effort [35], which is essential to enable the advancement of neuroscience research for mapping the local circuit network connections in the brain.

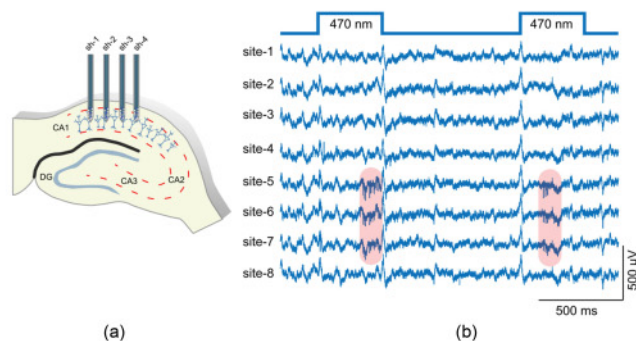


Fig. 14. (a) Location of the μLED probe and (b) Raw signals on shank 3.

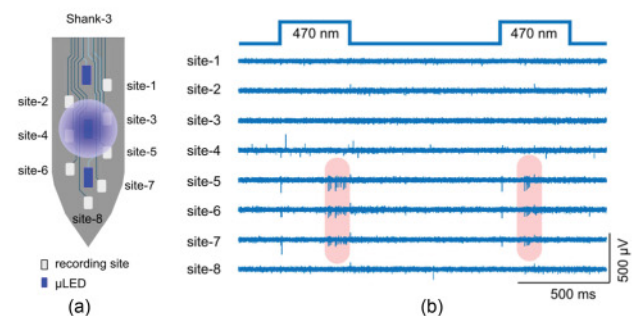


Fig. 15. (a) Details of shank 3 and (b) High pass filtered signal.

V. CONCLUSION

In this paper, we presented a full integration of B-TDD wireless data telemetry for implantable broadband optogenetic neural modulation and recording platform. The B-TDD transceiver utilizes both ultra-wide band and U-NII band to achieve one-antenna solution without power-hungry self-interference cancellation scheme. Data loss due to slow switching between receiving and transmitting is also avoided by adapting the bit-wise switching scheme as well as the asymmetrical data transferring protocol. Together with pre-existing ASICs, the

prototype integrated system was assembled to demonstrate the entire system with a total weight of under 5 g operating on battery power, which makes it suitable for rodent experiments. In *in vivo* experiments, the target neurons were successfully stimulated by the designated corresponding μ LEDs driven by the wireless prototype system and the optically activated neural responses could be monitored in real time with $< 0.1\%$ BER through wireless data transmission.

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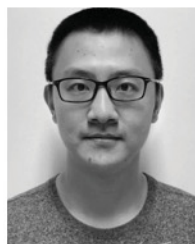


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real-time closed-loop neuroscience experiments in freely moving animals.

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