

# Multimodal Semi-supervised Learning for Disaster Tweet Classification

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## Abstract

During natural disasters, people often use social media platforms, such as Twitter, to post information about casualties and damage produced by disasters. This information can help relief authorities gain situational awareness in nearly real time, and enable them to quickly distribute resources where most needed. However, annotating data for this purpose can be burdensome, subjective and expensive. In this paper, we investigate how to leverage the copious amounts of unlabeled data generated on social media by disaster eyewitnesses and affected individuals during disaster events. To this end, we propose a semi-supervised learning approach to improve the performance of neural models on several multimodal disaster tweet classification tasks. Our approach shows significant improvements, obtaining up to 7.7% improvements in F-1 in low-data regimes and 1.9% when using the entire training data. We make our code and data publicly available.<sup>1</sup>

## 1 Introduction

The upswing of text and image sharing on social media platforms, such as Twitter, during mass emergency situations has led to numerous opportunities to gain timely access to valuable information that can help disaster relief authorities act quicker and more efficiently. Specifically, as a disaster unfolds, information shared on social media can provide insights into the infrastructure and utility damage, casualties, and missing people. Recent studies have focused on collecting and manually annotating disaster data with respect to such situational awareness categories, followed by training machine learning classifiers to automatically identify situational awareness information, useful for relief operations (Alam et al., 2018b; Ashktorab et al., 2014).

However, disaster events produce large amounts of user-generated data, of which only a small frac-

tion can be annotated, due to the time-sensitive nature of the problem, together with high annotation costs, and also inherent subjectivity associated with annotating data (e.g., tweets).

To address this limitation, we propose a semi-supervised multimodal approach that can leverage the copious amounts of unlabeled data to improve the performance on various multimodal tasks. Specifically, we extend the *FixMatch* (Sohn et al., 2020) algorithm proposed for semi-supervised image classification to a multimodal setting. To account for subjective annotations and potentially overlapping labels, we use soft pseudo-labels instead of the original hard pseudo-labels. We apply the adapted *FixMatch* to the CrisisMMD labeled dataset and tasks (Alam et al., 2018b), to improve the performance of supervised baselines through the use of unlabeled data. We use 122K unlabeled tweets, containing both text and images, collected automatically using text queries about disasters that occurred during the year of 2017.

Experimental results show that our proposed approach produces performance improvements on all three CrisisMMD tasks in various data regimes. Notably, we obtain as much as 7.7% using as few as 250 examples per class and 1.9% improvement when using the entire data. To our knowledge, we are the first to propose a semi-supervised method for multimodal data using *FixMatch* and text-based searches for collecting a large unsupervised dataset. While our experiments focus on disaster tweets, the method can be easily generalized. Finally, we provide an extensive error analysis of our models. We analyze how the supervised model’s predictions change with the introduction of unlabeled data and reinforce the importance of our improved version of *FixMatch*.

Our contributions are as follows:

(1) We extend *FixMatch* algorithm to a multimodal scenario and offer two extensions to the original approach relevant for text and multimodal

<sup>1</sup><https://github.com/iustinsirbu13/multimodal-ssl-for-disaster-tweet-classification>

datasets. (2) We show that inexpensive unlabeled data gathered using text queries and basic preprocessing can be leveraged by our multimodal FixMatch to improve performance on 3 classification tasks. (3) We provide a detailed analysis into the predictions of the semi-supervised approaches, and compare them to their supervised counterparts.

## 2 Related Work

### 2.1 Semi-supervised learning

Semi-supervised learning combines labeled data with large amounts of unlabeled data during training to improve the performance of the models. *MixMatch* (Berthelot et al., 2019b) uses a sharpening technique and guesses low-entropy labels for augmented unlabeled data. Next, it employs *MixUp* (Zhang et al., 2017) to blend the labeled and unlabeled examples. *FixMatch* (Sohn et al., 2020) combines two standard semi-supervised techniques: consistency regularization (Rasmus et al., 2015; Sajjadi et al., 2016; Tarvainen and Valpola, 2017) and pseudo-labeling (Lee et al., 2013). The pseudo-labels are generated using the current model’s predictions on weakly-augmented unlabeled images. Next, the model predicts the pseudo-labels for strongly augmented versions of the same images. *Noisy Student Training* (Xie et al., 2020) first trains a teacher model on the labeled data to predict pseudo-labels for the unlabeled examples. Next, it trains a larger student model on all the data (i.e. labeled and unlabeled) using augmentation and dropout. The teacher model is then replaced by the student, and the process is repeated until convergence.

Text and image SSL methods are usually tightly related. For example, Miyato et al. (2016) extends adversarial training from images (Miyato et al., 2015) to text. Specifically, the proposed approach leverages adversarial attacks for consistency regularization by identifying an optimal perturbation for each sample (instead of using random perturbations). *MixText* (Chen et al., 2020) adapts *MixMatch* for text and proposes replacing MixUp method with TMix, a newly introduced approach for interpolating texts in a hidden space. *Unsupervised Data Augmentation*, or *UDA* (Xie et al., 2019) has been shown to be effective both for texts and images. It uses common SSL techniques such as consistency regularization, sharpening and data filtering (i.e., confidence based masking and balancing), together

with qualitative augmentations (i.e. RandAugment for images and back-translation for texts).

### 2.2 Disaster tweet classification

A significant body of research focuses on the benefits of social media information for improving disaster relief efforts. Some of these studies focus on learning from solely textual data (e.g., tweets) (Yin et al., 2012; Guan and Chen, 2014; Yuan and Liu, 2018; Imran et al., 2015; Kryvasheyev et al., 2016; Li et al., 2018a; Enenkel et al., 2018; Alam et al., 2018a; Mazloom et al., 2019; Neppalli et al., 2018; Li et al., 2018b) including semi-supervised learning from text (Li et al., 2021, 2018c). Other studies focus on learning only from images (Lagerstrom et al., 2016; Alam et al., 2017; Li et al., 2019a; Chaudhuri and Bose, 2020; Alam et al., 2018d; Bica et al., 2017; Nguyen et al., 2017; Li et al., 2019b; Weber et al., 2020). However, many tweets posted during disasters contain both text and images, which, if studied jointly, can provide a better portrayal of the damage produced by disasters, or the needs of the affected individuals. Therefore, it is not surprising that multimodal models in the disaster space have recently started to gain popularity (Mouzannar et al., 2018; Rizk et al., 2019; Gautam et al., 2019; Nalluru et al., 2019; Agarwal et al., 2020; Abavisani et al., 2020; Li and Caragea, 2020; Hao and Wang, 2020; Offi et al., 2020).

Sosea et al. (2021) leverages the image-text relationship to improve the performance of multimodal disaster tweet classification. Zou et al. (2021) proposes a framework containing separate feature extractors for each modality, followed by a procedure for fusing the two modalities. The approach proposed in Pranesh et al. (2021) is similar, however, the fusion is performed using an attention mechanism. Dinani and Caragea (2021) uses Capsule Networks to classify disaster images and identify the informativeness of a image. Alam et al. (2021) uses Noisy Student Training (Xie et al., 2020) and a multitasking setting to classify images from disaster tweets. Bidari (2021) proposed a weighting mechanism between predictions of a BERT (Devlin et al., 2018) model trained on text and a VGG16 (Simonyan and Zisserman, 2015) model trained on images.

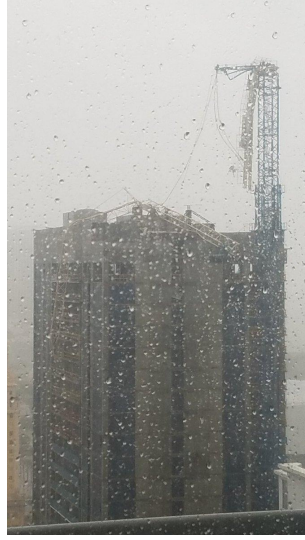
These existing approaches, however, do not use the large amounts of unlabeled multimodal data generated during disasters. In this paper, we propose a semi-supervised approach to leverage this



(a) This 4 BD/2 BA in Mora MUST be seen. Call, text or direct message me for more info!



(b) St. Augustine bed & breakfast picking up the pieces after Hurricane Irma



(c) A huge crane just collapsed on top of building in down town Miami



(d) Irma update: Free roof help available



(e) Magnitude 6.1 aftershock hits Mexico as search for people and pets continues

Figure 1: Examples of errors of the *MMBT* model that are corrected by *FixMatch* on the *Informativeness* and *Humanitarian CrisisMMD* tasks: (a) *MMBT*: *informative*; True: *not informative* (b) *MMBT*: *infrastructure and utility damage*; True: *not humanitarian* (c) *MMBT*: *not informative*; True: *informative* (d) *MMBT*: *infrastructure and utility damage*; True: *rescue, volunteering, or donation effort* (e) *MMBT*: *infrastructure and utility damage*; True: *rescue, volunteering, or donation effort*

data to improve the multimodal disaster tweet classification. Our approach extends *FixMatch* (originally proposed for image classification) to the multimodal setting and introduces two enhancements.

### 3 Methods

#### 3.1 Baseline Modeling

We employ various single-modal and multi-modal models to compare our proposed approach. First, we experiment with an image-only model, *ResNet-152* (He et al., 2016), on top of which we add a linear layer for classification. Next, we use a *Multimodal Bitransformer (MMBT)* (Kiel et al., 2019) to leverage both the image and text for disaster tweet classification, as it already showed good results on this task (Sosea et al., 2021). We randomly crop and rescale the input images to 224x224, a common size for these types of networks, and also perform a standard horizontal flip and shift augmentation. We denote these approaches by *ResNet Aug* and *MMBT Aug*.

#### 3.2 Semi-supervised learning

To leverage the large amounts of data generated during disaster events, we adapt the *FixMatch* (Sohn et al., 2020) algorithm to the multimodal setting.

*FixMatch* obtains impressive performance on several Computer Vision tasks by combining consistency regularization (Sajjadi et al., 2016; Laine and Aila, 2016) and pseudo-labeling (McLachlan, 1975). *FixMatch* computes the overall loss  $l$  as a weighted sum of two loss terms  $l = l_s + \lambda_u l_u$ , where  $\lambda_u$  is a weighting parameter,  $l_s$  is the loss on labeled data, and  $l_u$  is the loss on unlabeled data. Specifically, in the multimodal setting, the labeled loss is defined as:

$$l_s = \frac{1}{B} \sum_{b=1}^B H(p_b, p_m(\alpha(x_b^{img}), \beta(x_b^{txt})))$$

where  $B$  is the batch size,  $H$  is the cross-entropy loss,  $p_b$  is the one-hot encoding of the true label of a multimodal tweet  $(x_b^{img}, x_b^{txt})$ , and  $p_m$  is the model’s prediction (i.e., probability distribution over possible classes  $y$ ) on a weakly augmented image,  $\alpha(x_b^{img})$ , and weakly augmented text,  $\beta(x_b^{txt})$ . The unlabeled loss is defined as:

$$l_u = \frac{1}{\mu B} \sum_{b=1}^{\mu B} \mathbb{1}_{\tau}(q_b) H(\hat{q}_b, p_m(\mathcal{A}(u_b^{img}), \mathcal{B}(u_b^{txt})))$$



where  $\mu$  is the ratio between the number of labeled and unlabeled examples in a batch, and  $q_b = p_m(\alpha(u_b^{img}), u_b^{txt})$  is the probability distribution over classes  $y$ , for the unlabeled example  $(u_b^{img}, u_b^{txt})$ . The function  $\mathbb{1}_\tau(q_b)$  is used to filter out examples for which the prediction confidence, i.e.,  $\max_y(q_b)$ , is less than a threshold,  $\tau$ . For the remaining examples, the prediction is converted to a pseudo-label using  $\hat{q}_b = \arg \max_y(q_b)$ . Finally, the cross-entropy loss is computed between the one-hot encoding of this pseudo-label and the prediction of the model on a strongly augmented version of the current image,  $\mathcal{A}(u_b^{img})$ , and the corresponding augmented text,  $\mathcal{B}(u_b^{txt})$ . The strong augmentations for image use either RandAugment (Cubuk et al., 2020) or CTAugment (Berthelot et al., 2019a). For text augmentation we experiment with EDA (Wei and Zou, 2019) and back-translation (Edunov et al., 2018). We offer more details about our text augmentation methods in Subsection 4.3.

In this paper, we apply the *FixMatch* algorithm to our multimodal disaster domain, using *MMBT* as the base model. To understand the benefits of the multimodal representation, we also apply *FixMatch* on images only, using *ResNet-152* as the base model. We denote these methods by *MMBT FixMatch* and *ResNet FixMatch*, respectively.

### 3.3 FixMatch Enhancements

We propose two key enhancements to the unlabeled loss computation. First, we use *soft* pseudo-labels ( $q_b$ ) instead of the hard labels ( $\hat{q}_b$ ) used in the original paper:

$$l_u^{LS} = \frac{1}{\mu B} \sum_{b=1}^{\mu B} H(q_b, p_m(\mathcal{A}(u_b^{img}), \mathcal{B}(u_b^{txt})))$$

We argue that, in the disaster domain, there can be significant semantic overlap between two labels. For instance, in Figure 1e, which is labeled with *Rescue, volunteering, or donation effort* for the humanitarian task, there is a destroyed building in the background. By using soft labels, we can also incorporate information about the *Infrastructure and utility damage* class instead of stirring the model towards confidently predicting the example into the *Rescue, volunteering, or donation effort* class.

Second, we consider a variable weighting scheme for the loss,  $l$ . Originally, *FixMatch* employed a fixed weighting between the labeled and unlabeled loss (e.g.,  $\lambda_u = 1$ ). We argue that the

predictions of the model during the first few epochs are not qualitative, hence using the predicted labels of unlabeled data can hurt the performance. To prevent that, we employ a linear growth of the unlabeled loss. Starting with 0 in the first epoch, we increase this loss in steps of 2 each epoch. Our loss becomes  $l^{LS} = l_s + \lambda_u(t)l_u^{LS}$ , where  $\lambda_u(t) = 2t$ , and  $t$  is the epoch number. We denote the corresponding *MMBT* semi-supervised model by *MMBT Fixmatch LS*, while the corresponding *ResNet-152* model is denoted by *Resnet Fixmatch LS*.

## 4 Experiments

### 4.1 Labeled Data

We evaluate our semi-supervised multimodal approach on CrisisMMD (Alam et al., 2018b), a multimodal Twitter dataset from natural disasters. The dataset contains 18,000 tweets with both text and images extracted during disasters such as the Iraq-Iran Earthquakes or Hurricanes Irma, Harvey and Maria. CrisisMMD was manually labeled for three classification tasks: (1) *Informativeness*: A tweet is labeled as *Informative* or *Not Informative*, depending on whether the tweet is useful for humanitarian aid purposes or not useful. (2) *Humanitarian*: We use the 5-class version of this data (Offi et al., 2020) to alleviate the skewed label distribution. (3) *Damage Assessment*. We use a 2-class version of this data, similar to prior works (Li et al., 2018d). Each tweet image is labeled as depicting *Damage* or *No Damage*.

Although a significant amount of prior work has focused on multimodal tweet classification on CrisisMMD, directly comparing our approach to these methods is challenging, mainly because of the use of different splits for training and evaluation or different setups of the tasks. For example, Sosea et al. (2021) uses different splits and a 3-class version of the humanitarian class. Zou et al. (2021) uses different splits as well and a 4-class version of the humanitarian task. Dinani and Caragea (2021) focuses on improving performance for specific disasters and the data is divided disaster-wise. To this end, in this paper we employ 2 setups. In the first setup (Subsection 5.1), we create our own splits which we release alongside our data. We show the number of examples from the train, development, and test sets for the 3 tasks in CrisisMMD in Table 1 and we provide the class distributions in Table 2. Moreover, to validate our approach against some prior work with publicly released splits, we also

experiment with the splits released by [Offi et al. \(2020\)](#) (Subsection 5.2).

## 4.2 Unlabeled Data

We show that, by using text queries and preprocessing for collecting the unlabeled corpus, the performance of FixMatch can be improved even though the two datasets are not sampled from the same distribution. We used the Twitter Streaming API with a list of relevant keywords for the text in the training dataset. Then we selected 122k unique tweets containing both text and images that do not overlap with CrisisMMD.

The tweets were crawled from Twitter using the Twitter Streaming API (with keywords such as #hurricaneharvey, #harvey, #hurricane, #earthquake) during the following disasters that happened in 2017: Hurricane Harvey, Hurricane Irma, Hurricane Maria, Mexico Earthquake, and Chiapas Earthquake. This collection was filtered for disaster relevance using a Naive Bayes classifier trained on CrisisLexT6 ([Olteanu et al., 2014](#)) to ensure that it mostly contained tweets relevant to disasters. Subsequently, duplicate tweets, retweets and non-English tweets were removed. Finally, we selected only tweets that contained both an image and text.

In addition, we used several methods to clean and filter out duplicates between our dataset and CrisisMMD. This is done in order to make sure that test samples (from CrisisMMD) are not seen during training, not even as unlabeled examples (as part of our unlabeled dataset). First, we removed all retweets (tweets with the “RT” token), and normalized the texts removing characters repetitions (all consecutive identical characters of size  $> 2$  are reduced to only 2 characters) and user mentions. Next, we removed duplicates using the `drop_duplicates` function from the pandas library.

The resulting unlabeled corpus will be made publicly available.

## 4.3 Data Augmentations

Data augmentations play a vital part in our FixMatch ([Sohn et al., 2020](#)) framework. Given the multimodal nature of our model, we experiment with both text and image augmentations. For image augmentations, we follow FixMatch and use a standard flip-and-shift as a weak augmentation and RandAugment ([Cubuk et al., 2020](#)) as strong augmentation. For the textual modality, we investigate two different techniques:

- Easy Data Augmentation (EDA) ([Wei and Zou, 2019](#)), which randomly applies 4 possible operators: synonym replacement, random insertion of a word, random swap of 2 words or a random deletion of a word. We used the EDA framework for applying these transformations on 10% of the words in each text.
- Backtranslation ([Edunov et al., 2018](#)) was used previously in UDA ([Xie et al., 2019](#)) and MixText ([Chen et al., 2020](#)). It consists of translating a sentence to another language and then back to the original language, aiming to obtain a new example different from the original text but keeping the same meaning. Inspired by MixText ([Chen et al., 2020](#)), we use FairSeq ([Ott et al., 2019](#)) with Russian as an intermediate language and random sampling with 0.9 temperature instead of beam search in order to ensure the diversity of the augmentations.

## 4.4 Experimental Setup

To separately assess the impact of using multimodal data and of introducing text augmentations, we conduct our experiments in two stages. First, to ensure a fair comparison with the ResNet-based models, which only use the image modality, we experimented with versions of MMBT-based models where no text augmentation is used ( $\mathcal{B}$  is the identity function). Second, we analyze the impact of augmenting each modality separately or performing both text and image augmentations. We propose the following Fixmatch adaptations: **1)** *FixMatchLS<sub>img</sub>* solely augments the image, **2)** *FixMatchLS<sub>eda</sub>* only augments the text using EDA, **3)** *FixMatchLS<sub>img+eda</sub>* augments both modalities, using EDA for text augmentation, and **4)** *FixMatchLS<sub>img+bt</sub>* augments both modalities, using back-translation for text augmentation.

To test the limits of our approach, we also experiment with few labeled training examples (250/500) per class on the Informative task. (Subsection 5.3). All hyperparameters and model setups are available in Subsection 4.5. To attain statistically significant results, we ran each experiment 5 times and report the average of the results. We used 4 Nvidia V100 GPUs to train our models. One experiment takes roughly 20 hours to complete on a single GPU. To improve reproducibility, we will release the splits for each task alongside our code.

DATASET	SIZE	TRAIN	DEV	TEST
INFORMATIVE	13494	10795 (80%)	1349 (10%)	1350 (10%)
DAMAGE	6089	4262 (70%)	913 (15%)	914 (15%)
HUMANITARIAN	8079	6126 (75.8%)	998 (12.4%)	955 (11.8%)

Table 1: Data splits for each task.

DATASET	INFORMATIVE	DAMAGE	HUMANITARIAN
Labels	<i>uninformative</i> (55%)	<i>no damage</i> (70%)	<i>not humanitarian</i> (53%)
	<i>informative</i> (45%)	<i>damage</i> (30%)	<i>other relevant information</i> (22%)
			<i>rescue volunteering or donation effort</i> (15%)
			<i>infrastructure and utility damage</i> (9%)
			<i>affected individuals</i> (1%)

Table 2: Labels distribution for each task.

## 4.5 Hyperparameters

First, we tried to find the best *FixMatch* setup for our experiments (without our extension). To achieve this, we experimented with a variety of setups, by manually tuning the *FixMatch* hyperparameters and choosing the values that yield the best F1 score. The values that were tested for each parameter are detailed in Appendix A. The obtained values that we used in all the reported results are the following: ratio between unlabeled and labeled examples  $\mu = 7$ , weight of the unlabeled loss  $\lambda_u = 1$ , image size 224x224, dropout 0.2, exponential moving average (EMA) with decay 0.999, learning rate  $10^{-5}$  with *ReduceOnPlateau* schedule and *Adam* optimizer, confidence threshold  $\tau = 0.7$ , batch size of 8 with 16 gradient accumulation steps. For image augmentation we used random horizontal flip as weak augmentation and *RandAugment* as strong augmentation in all our experiments.

We apply the best hyperparameters found for the classic *FixMatch* algorithm to our extended *FixMatch LS* version. Our changes are:

- we used *soft labels* instead of hard pseudo-labels for the unlabeled data;
- we used a *linear schedule* for the unlabeled loss weight  $\lambda_u$ .

Note that replacing pseudo labels with soft labels for the unlabeled data completely removes the confidence threshold parameter,  $\tau$ . However, introducing the linear schedule  $\lambda_u(t) = c * t$  for the unlabeled loss adds one extra parameter,  $c$ . This is the only hyperparameter tuned for *FixMatch LS*. We used  $\lambda_u(t) = 2 * t$  in all the experiments.

## 5 Results

### 5.1 Our data split

As it can be seen in Table 3, our enhanced *FixMatch* models, which use soft-labels and a linear schedule for weighting the unlabeled loss, consistently outperform all the other models on all tasks. On the *Informative* task, *MMBT FixMatch LS* improves the F1 performance of the supervised *MMBT Aug* model by as much as 3.5%. Interestingly, on the *Humanitarian* task, the *MMBT FixMatch* approach, which uses hard labels and a constant loss weighting, obtains similar performance to *MMBT Aug*, which uses no unlabeled data. We attribute this to the nature of the humanitarian task, where the boundary between classes may not be well defined, i.e., an example annotated with class  $y_1$  can exhibit characteristics specific to a different class  $y_2$ . We argue that the use of the “hard labeling” mechanism for these types of tasks can lead to poor model performance. On the other hand, the *MMBT FixMatch LS* manages to prevent this shortcoming, and obtains an F1 increase of 1% over the *MMBT Aug* model. Finally, on the *Damage* task, we observe that the *ResNet* and the *MMBT* perform similarly, which is not surprising, given that the examples in this task were annotated based only on the image in the tweet. However, similar to the *Informative* task, the best semi-supervised approach outperforms the other method by as much as 2.9% F1.

### 5.2 Official data split

Table 4 shows the improvement obtained for the best model so far (*MMBT FixMatch LS*) with the introduction of text augmentation. Here, in order to enable a fair comparison with other methods, we test our best performing approach, *FixMatchLS* using the data splits introduced by Ofli et al. (2020).

MODEL	INFORMATIVE			DAMAGE			HUMANITARIAN		
	P	R	F1	P	R	F1	P	R	F1
RESNET AUG	0.767	0.767	0.766	0.861	0.863	0.858	0.804	0.812	0.806
RESNET FIXMATCH	0.793	0.793	0.793	0.886	0.887	0.886	0.820	0.820	0.816
RESNET FIXMATCH LS	0.804	0.804	0.804	<b>0.887</b>	<b>0.888</b>	<b>0.887</b>	0.829	0.825	0.819
MMBT AUG	0.786	0.785	0.785	0.865	0.867	0.865	0.865	0.862	0.863
MMBT FIXMATCH	0.808	0.806	0.806	0.882	0.882	0.882	0.865	0.865	0.864
MMBT FIXMATCH LS	<b>0.820</b>	<b>0.820</b>	<b>0.820</b>	0.885	0.882	0.883	<b>0.873</b>	<b>0.872</b>	<b>0.872</b>

Table 3: Results on CrisisMMD tasks using image augmentations - best results for each task are highlighted in **bold**.

MODEL	INFORMATIVE			HUMANITARIAN		
	P	R	F1	P	R	F1
OFLI ET AL. (2020) - TXT	0.810	0.810	0.809	0.700	0.700	0.677
OFLI ET AL. (2020) - IMG	0.831	0.833	0.832	0.764	0.768	0.763
OFLI ET AL. (2020)	0.841	0.840	0.842	0.785	0.780	0.783
BIDARI (2021)	-	-	-	0.860	0.830	0.840
PRANESH ET AL. (2021)	-	-	-	-	-	0.855
ALAM ET AL. (2021) - Noisy Student - (*) - IMG	0.878	0.878	0.876	0.786	0.783	0.783
DINANI AND CARAGEA (2021) (*) - IMG	0.838	0.843	0.837	-	-	-
ZOU ET AL. (2021) (*)	0.875	0.876	0.875	0.872	0.911	0.891
SOSEA ET AL. (2021)(*)	-	-	-	0.950	0.920	0.940
<i>MMBT(supervised)</i>	0.887	0.888	0.886	0.865	0.862	0.863
<i>FixMatchLS<sub>img</sub></i>	0.901	0.901	0.899	0.873	0.872	0.872
<i>FixMatchLS<sub>eda</sub></i>	0.897	0.896	0.894	0.878	0.877	0.877
<i>FixMatchLS<sub>img+eda</sub></i>	0.907	0.906	0.904	<b>0.885</b>	<b>0.881</b>	<b>0.881</b>
<i>FixMatchLS<sub>img+bt</sub></i>	<b>0.910</b>	<b>0.908</b>	<b>0.905</b>	0.880	0.879	0.878

Table 4: Comparison of proposed method with state of the art models on official split of CrisisMMD. An asterisk at the end (\*) means that the paper uses different splits. Best results are highlighted in **bold**, for the official split only.

MODEL	INFORMATIVE 250/CLASS			INFORMATIVE 500/CLASS		
	P	R	F1	P	R	F1
<i>MMBT(supervised)</i>	0.666	0.667	0.666	0.713	0.704	0.705
<i>FixMatchLS<sub>img</sub></i>	0.695	0.688	0.689	0.741	0.730	0.730
<i>FixMatchLS<sub>eda</sub></i>	0.687	0.673	0.673	0.741	0.731	0.722
<i>FixMatchLS<sub>img+eda</sub></i>	0.701	0.702	0.701	0.759	0.756	0.756
<i>FixMatchLS<sub>img+bt</sub></i>	<b>0.744</b>	<b>0.742</b>	<b>0.743</b>	<b>0.772</b>	<b>0.759</b>	<b>0.760</b>

Table 5: Results on CrisisMMD, Informative task, with few labeled examples per class - best results are highlighted in **bold**.

IMAGE	MODEL	LABEL	
		<i>informative</i>	<i>not informative</i>
(a)	MMBT AUG	0.71	0.29
	FIXMATCH LS	0.09	0.91
(c)	MMBT AUG	0.24	0.76
	FIXMATCH LS	0.98	0.02

Table 6: Examples of predictions for the Informative Task



All the methods without an asterisk (\*) in this table use the same data splits, so they are directly comparable to one another and to our approach. However, as the official splits for multimodal data in CrisisMMD (Alam et al., 2018c) were released in a subsequent work (Ofli et al., 2020), many approaches created their own splits, as we did in the Subsection 5.1. Although they are not directly comparable to us, especially because they use fewer classes for the humanitarian task, we also show some of these results in Table 4 and mark them with an asterisk (\*).

First, we observe that our supervised *MMBT* method performs better than the best comparable baselines (i.e., Ofli et al. (2020) for the Informative task and Pranesh et al. (2021) for the Humanitarian task). Second, we note that augmenting a single modality (i.e., either text or image) improves performance on both tasks, by 1.4% F1 on Humanitarian and 1.3% F1 on Informative. Critically, we obtain the best results when employing augmentations for both modalities simultaneously. Specifically, *FixMatchLS<sub>img+eda</sub>* outperforms both *FixMatchLS<sub>img</sub>* and *FixMatchLS<sub>eda</sub>*. Third, we observe that the best text augmentation is task-dependent. For example, *FixMatchLS<sub>img+eda</sub>* performs better on the Humanitarian task, while *FixMatchLS<sub>img+bt</sub>* is the best method for the Informative task.

Finally, there are two baselines that report higher performance on the Humanitarian task, namely Zou et al. (2021) and Sosea et al. (2021). However, as previously explained, the results are not directly comparable, as they use different versions of the Humanitarian task, with 3 and 4 classes, respectively, instead of 5 classes, as introduced in Ofli et al. (2020), which makes the task a lot easier for them.

### 5.3 Low-data regimes

To test the limits of our approach, we also experiment with few labeled examples (250/500) per class on the informative task, as shown in Table 5. We emphasize that our SSL methods perform substantially better than baselines in these low-resource settings. This is extremely valuable for disaster-related classification, where abundant data at the time of the disaster is hard-to-acquire. Specifically, our results show that, while augmenting the image is more important than augmenting the text in low-data regimes (*FixMatchLS<sub>img</sub>* performs better than *FixMatchLS<sub>eda</sub>*), it is once again clear that augmenting both modalities is always

the best option. Using back-translation instead of EDA gives the best results, obtaining up to 7.7% F1 improvement over the supervised approach.

We emphasize that all improvements of the enhanced *FixMatch* over baselines in this paper are statistically significant, according to a t-test with  $p < 0.01$ . These results show the feasibility of our proposed *FixMatch* variant: using *cheap to acquire* unlabeled data, we improve the performance of supervised models significantly.

### 5.4 Error Analysis

We investigate common errors of the models that use no unlabeled data, which are corrected by our *FixMatch* models. To this end, we first sample 20 such examples for each CrisisMMD task, followed by manually inspecting the output probabilities and the contents of the image and text. We show some examples together with the corresponding ground truths in Figure 1, and provide comparisons between predictions of the *MMBT Aug* and the *FixMatch LS* model in Tables 6 and 7.

We observed a few patterns. First, we spotted some erroneous predictions due to semantic disparities between the textual and the image modalities (i.e., the image and text pinpoint to different labels, hence the final label is subjective). An example is shown in Figure 1b. Second, we encountered a significant number of examples where the image modality is distorted, or contains noise. For instance, in Figure 1c, the photo contains perturbations (i.e., the rain drops) that hinder the capability to observe the main focus of the picture: a *collapsed huge crane*. Third, we observe some examples which contain characteristics specific to more than one class. In Figure 1e, even though the main focus of the tweet is on *Rescue and volunteering* efforts, the image also exhibits traits of the *Infrastructure and utility damage* class: a destroyed building.

Our proposed *FixMatch* variant is able to correct these types of errors. Moreover, the *FixMatch* model is confident in its predictions, usually assigning a probability over 90% to the correct class.

## 6 Limitations

While our approach provides significant improvements on all CrisisMMD tasks, we also have to acknowledge the limitations of the proposed method. As it generally is the case with semi-supervised approaches, the training time is significantly increased, as more data needs to be passed through



IMAGE	MODEL	LABEL				
		<i>not hum.</i>	<i>other</i>	<i>rescue</i>	<i>damage</i>	<i>affected</i>
(b)	MMBT AUG	0.36	0.06	0.04	0.51	0.09
	FIXMATCH LS	0.89	0.01	0.02	0.07	0.01
(d)	MMBT AUG	0.02	0.03	0.16	0.78	0.01
	FIXMATCH LS	0.03	0.03	0.90	0.01	0.03
(e)	MMBT AUG	0.01	0.01	0.02	0.95	0.01
	FIXMATCH LS	0.01	0.01	0.93	0.04	0.01

Table 7: Examples of predictions for the Humanitarian Task

the model until convergence, comparing to a supervised approach. Regarding our method of collecting unlabeled data by searching for relevant keywords, although it is generic and could be applied to datasets from other domains, it is limited for datasets containing tweets. For other types of datasets, obtaining a relevant unlabeled corpus in the same manner could be more challenging.

## 7 Conclusion

We extended *FixMatch* to multimodal data and proposed two improvements. We applied the improved *FixMatch* on three disaster-centric multimodal tweet classification tasks, and showed that the approach can leverage large unlabeled data to improve supervised model performance. Our semi-supervised approach is general enough and can be easily applied to other datasets, being at the same time very efficient as it does not add any inference complexity to the base model.

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## A Hyperparameters

First, we tried to find the best *FixMatch* setup for our experiments (without our extension). To achieve this, we experimented with a variety of setups, by manually tuning the *FixMatch* hyperparameters and choosing the values that yield the best F1 score:

- For the ratio  $\mu$  between unlabeled and labeled examples we tried values from the set  $\{3, 5, 7\}$ . We observed that setting  $\mu$  to 7 produced the best results. We did not try values bigger than 7 due to computation limitations. However, 7 is the reported best  $\mu$  in the original *FixMatch* paper, too.
- For the weight of the unlabeled loss,  $\lambda_u$ , we experimented with values in the set  $\{1, 10, 50, 100\}$ , and obtained the best results with value 1 (similar to the original paper).
- For image preprocessing, we cropped and rescaled all images to 224x224 size. We also tried to reduce the size of the images to 96x96 to improve computational performance, but the results were heavily affected.
- For image augmentation we used random horizontal flip as weak augmentation and *RandAugment* as strong augmentation in all our experiments.
- Initially, the original paper used no dropout, but we observed that adding 0.2 dropout improved the results.
- Exponential moving average (EMA) with decay 0.999 was kept as in the original paper. We experimented with a smaller decay or without EMA, but this negatively impacted the performance.
- Instead of SGD and *cosine learning rate schedule*, we used *Adam* with a *ReduceOnPlateau schedule*, which improved results.
- We experimented with learning rates from the set  $\{10^{-5}, 5 \times 10^{-5}, 10^{-4}\}$ , and picked  $10^{-5}$  as the optimal value.
- For the confidence threshold  $\tau$ , we found that 0.7 was the best for our tasks. This is compatible with the value chosen in the original paper on the *ImageNet* dataset. We experimented with values in the set  $\{0.5, 0.7, 0.85, 0.95\}$ .
- Due to computation limitations, we used a batch size of 8 with 40 gradient accumulation steps in all our experiments.

We apply the best hyperparameters found for the classic *FixMatch* algorithm to our extended *FixMatch LS* version. Our changes are:

- we used *soft labels* instead of hard pseudo-labels for the unlabeled data
- we used a *linear schedule* for the unlabeled loss weight  $\lambda_u$

Note that replacing pseudo labels with soft labels for the unlabeled data completely removes the confidence threshold parameter,  $\tau$ . However, introducing the linear schedule  $\lambda_u(t) = c * t$  for the unlabeled loss adds one extra parameter,  $c$ . This is the only hyperparameter tuned for *FixMatch LS*. After experimenting with values in the set  $\{1, 2, 3\}$ , we choose  $\lambda_u(t) = 2 * t$  to be our weight in all the experiments.

In order to attain statistically significant results, we ran each experiment 5 times and report the average of the results. We used 4 Nvidia V100 GPUs to train our models. One experiment takes roughly 20 hours to complete on a single GPU.