

## Optimization of site investigation program for reliability assessment of undrained slope using Spearman rank correlation coefficient

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**Abstract:** Site investigation programs (e.g., boreholes) are crucial in characterizing soil properties and stratigraphic configurations. However, the traditional borehole patterns are generally of equally spaced distribution for the slope design, and the locations and total number of boreholes are considerably determined depending on engineers' experience, which may lead to cost-inefficient geotechnical design, especially considering the soil spatial variability. To address this dilemma, this paper presents a Spearman rank correlation coefficient-based scheme to optimize site investigation in slope design, where both locations and total number of boreholes are optimized. Conditional random field simulations are performed to consider the effect of the borehole data on the estimation of the soil property distribution. The superiority of the proposed method to the traditional method is illustrated by a comparison study in an undrained slope example. In this example, the accuracy of the characteristics of the slope (i.e., the factor of safety, location of slip surface, and sliding volume), robustness of the estimated characteristics of the slope, and risk reduction are examined. The comparison results show the effectiveness of the proposed method in accurately estimating the characteristics of the slope without prior knowledge about the slip surface, since the slip surface is unknown for most practical cases prior to the site investigation. The most robust estimate results and risk reduction are obtained using the proposed method. This study can also provide useful references to build an adaptive unequally spaced borehole pattern in practice.

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27      **Keywords:** Optimization; Spatial variability; Slope stability; Spearman rank correlation  
28      coefficient.

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38        **1. Introduction**

39            Natural soils are very complicated and highly variable geomaterials, and they are  
40            products of complex geological processes and depositional environments. To investigate the  
41            soil properties at geotechnical sites, site investigations (e.g., boreholes) are typically  
42            conducted in practice. However, with the restriction of time and budget for most geotechnical  
43            design projects, only a limited number of boreholes at scattered locations over a construction  
44            site are typically planned and executed, which results in significant uncertainties in the  
45            geotechnical characterization of the site (Jiang et al. 2018b&2020; Yang et al. 2019&2022).  
46            Furthermore, geotechnical properties for a given site can exhibit considerable spatial  
47            variability due to the natural fluctuation of material constituents, randomness in the  
48            depositional history, and variable historical loading conditions (Huang et al. 2020), which  
49            causes more challenges in the optimization of the borehole patterns for geotechnical design.

50            Some previous optimization studies aimed to accurately predict the soil properties at  
51            unsampled locations with measured borehole data in geotechnical profiles (e.g., Wang et al.  
52            2017; Cai et al. 2019; Zhao et al. 2021), while other studies focused on uncertainty reduction  
53            in the characterization of the spatial variability (i.e., the mean, standard deviation, and scale of  
54            fluctuation of soil properties) at geotechnical sites (e.g., Lloret-Cabot et al. 2012; Li et al.  
55            2016c; Xiao et al. 2018; Huang et al. 2020; Han et al. 2022). Although these borehole  
56            schemes provide useful means to characterize a given geological profile, they may not be  
57            effective in characterizing the performance of geotechnical systems (e.g., the slope,  
58            foundation, and tunnel). In a geological profile, all soil elements are of equal importance to  
59            provide information about the soil properties, and equally spaced borehole patterns can be  
60            acceptable. However, the optimal borehole patterns are generally related to the failure

mechanism of geotechnical systems. The soil elements at the influence zones that control the failure mechanism of geotechnical systems are more influential in determining the optimal borehole patterns. For instance, [Chwała \(2021\)](#) investigated the effect of the space between two symmetrically distributed soil soundings on the bearing capacity of a rectangular footing foundation. The optimal space was found to depend on the normalized scale of fluctuation by the foundation length. It was concluded that the boreholes in the area with more dissipated energy in the foundation were more effective in reducing the uncertainty of the bearing capacity estimation. [Li et al. \(2016a\)](#) and [Deng et al. \(2017\)](#) showed that the boreholes at the place where the slip surface was extended resulted in a more accurate estimate of the mean and a smaller standard deviation of the factor of safety ( $FS$ ) of the slope, since the soil elements in these areas determined how the slip surface could be formed. However, most current studies to optimize borehole patterns in geotechnical design have equally spaced borehole patterns that follow traditional site investigation programs ([Gong et al. 2014 & 2017](#); [Li et al. 2016a](#); [Li et al. 2016b](#); [Deng et al. 2017](#); [Liu et al. 2020](#)). Hence, the two optimized objectives in the borehole patterns, which are the locations and total number, can be considered a function of the borehole space, since sufficiently many boreholes will be fully distributed in the site for a given borehole space. As mentioned above, since the soil elements at the influence zone have a more considerable effect on the geotechnical system, more boreholes should be arranged at the most important influence zones in sequence, which implies that traditional equally spaced borehole patterns are more likely cost-inefficient.

This paper aims to propose an effective approach to optimize site investigation considering the spatial soil variability in slope engineering based on correlation analysis, where the influence zone can be automatically determined without prior knowledge about the

84 slip surface. The effectiveness of the proposed method is validated in three aspects: the  
85 estimate accuracy, uncertainty reduction, and risk reduction, according to previous studies  
86 (Cai et al. 2019; Jiang et al. 2018b&2020; Yang et al. 2019&2022). The main advantages of  
87 this approach compared to the traditional method are: 1) The influence zone of the slope  
88 system can be automatically determined without prior knowledge about the slip surface; 2)  
89 The locations and total number of boreholes are separately optimized; 3) Most estimate  
90 accuracy and uncertainty reduction (in terms of the robustness) of the characteristics of the  
91 slope can be obtained; 4) Most risk reduction (i.e., expected loss cost) can be reached in the  
92 proposed method; 5) The proposed method is easy to implement due to its simple concept.  
93 The remainder of the paper is organized as follows. The optimization methodology is first  
94 briefly introduced. Then, an undrained slope example is taken to illustrate the effectiveness of  
95 the proposed method. A comparison study is conducted to evaluate the estimated accuracy of  
96 the characteristics of the slope (i.e., the factor of safety, location of slip surface, and sliding  
97 volume) between the proposed method and traditional methods. Afterwards, the robustness of  
98 the estimated results and risk reduction of the entire slope engineering system are  
99 comprehensively assessed. Finally, the concluding remarks are made based on the results.

100

## 101 **2 Methodologies to optimize the site investigation program**

102 Due to the restriction of time and budget for most slope engineering projects, only  
103 limited measured data (e.g., from boreholes) can be obtained. The soil properties at borehole  
104 locations are “known” without uncertainty, while other soil properties from unsampled  
105 locations are estimated by the borehole data with uncertainty. Since the spatial correlations of  
106 soil properties generally decrease with the relative distance, the constraint of the borehole data

107 decreases with the relative distance to the boreholes, which leads to more uncertainty in the  
108 estimate of the soil properties far from existing boreholes. To characterize this feature and the  
109 spatial variability of soil properties, the conditional random field theory is employed to  
110 optimize the site investigation program (Li et al. 2016b; Liu et al. 2017). Conditional random  
111 field simulations can be realized by statistical methods such as the Bayesian method, Hoffman  
112 method, and kriging-based sampling method (Gong et al. 2018). As a linear unbiased  
113 estimation method, the kriging-sampling method uses a weighted linear average of nearby soil  
114 samples to predict soil properties at unsampled locations. The spatial autocorrelation function  
115 and unconditional random field simulations are also incorporated in the generation of  
116 conditional random fields. Thus, the soil property values at sampled locations always match  
117 the known data in the conditional random field simulations by the kriging method. The  
118 kriging method also ensures the uncertainty at unsampled locations in terms of the variance,  
119 which reduces with the distance to the borehole locations, and no uncertainty of soil samples  
120 at the sampled locations (i.e., the variance is zero), which is consistent with our basic  
121 knowledge. In addition, the kriging-sampling method is computationally efficient and easy to  
122 implement, since the high-dimensional matrix can be avoided, and the weight vector needs to  
123 be calculated only once for any number of MCS in the point-by-point prediction of unsampled  
124 soil samples. The kriging method has been validated to give sufficiently accurate and reliable  
125 predictions by both theoretical models and realistic models (Wang et al. 2017; Li et al. 2016b;  
126 Chen et al. 2018; Huang et al. 2019). Therefore, the kriging-sampling method is adopted in  
127 this study. Based on the constructed conditional random fields, correlation analysis using the  
128 Spearman rank correlation coefficient is performed to determine the optimal borehole patterns  
129 (i.e., the locations and total number of boreholes). Although the conditional random field

130 simulations by the kriging method are not new, the conditional random field simulation  
131 procedures should be briefly introduced.

132 **2.1 Conditional random field simulations of the soil properties**

133 The conditional random fields by the kriging method are generated based on  
134 unconditional random field simulations, which are first reviewed as follows. The soil  
135 properties are generally assumed to be lognormally distributed because the soil properties  
136 have nonnegative values (Jiang et al. 2018a&2018b; Gong et al. 2018; Yang et al. 2019; Chen  
137 and Zhang 2021). For a lognormal random field soil property  $s$  with prior knowledge of the  
138 mean  $\mu_s$  and coefficient of variation (COV)  $\delta_s$ , the mean  $\mu_{\ln s}$  and standard deviation  $\sigma_{\ln s}$  of the  
139 equivalent normal random field  $\ln s$  are calculated as follows.

140 
$$\sigma_{\ln s} = \sqrt{\ln(1 + \delta_s^2)} \quad (1a)$$

141 
$$\mu_{\ln s} = \ln(\mu) - 0.5\sigma_{\ln s}^2 \quad (1b)$$

142 The anisotropic exponential autocorrelation structure is adopted to characterize the  
143 correlation coefficient  $\rho_{ij}$  between the normalized soil property  $\ln s$  at two different locations  
144 of  $(x_i, y_i)$  and  $(x_j, y_j)$ , which is calculated as follows.

145 
$$\rho_{ij} = \rho(|x_j - x_i|, |y_j - y_i|) = \exp\left(-\frac{2|x_j - x_i|}{\lambda_{\ln x}} - \frac{2|y_j - y_i|}{\lambda_{\ln y}}\right) \quad (2)$$

146 where  $|x_j - x_i|$  and  $|y_j - y_i|$  are the absolute distances between two positions  $(x_i, y_i)$  and  $(x_j, y_j)$   
147 along the  $X$  and  $Y$  directions, respectively;  $\lambda_{\ln x}$  and  $\lambda_{\ln y}$  are the scales of fluctuation of the  
148 equivalent normal random field  $\ln s$  along the  $X$  and  $Y$  directions, respectively.

149 A fixed value is assigned to the soil element domain instead of at the mesh grids. The  
150 mean of the soil property  $\mu_{\ln s E}$  that should be averaged over the soil element domain is equal

151 to that of the local soil property  $\mu_{\ln s}$ , while the standard deviation of the averaged soil property  
 152  $\sigma_{\ln s E}$  is reduced. For the autocorrelation structure established in Eq. (2), the variance reduction  
 153 factor of the concerned element can be estimated by the equations in [Knabe et al. \(1998\)](#) and  
 154 [Huang and Griffiths \(2015\)](#) with a range of 0-1. There are various sampling methods to  
 155 generate unconditional random fields, such as the local average subdivision method,  
 156 turning-band method, fast Fourier transformation method, and covariance matrix  
 157 decomposition method ([Fenton 1994](#); [Yang and Ching 2021](#)). In this study, the covariance  
 158 matrix decomposition method is used for random field generation. For given mean, standard  
 159 deviation, and autocorrelation structure, the  $n_E \times n_E$  autocorrelation matrix  $\mathbf{R}_{\ln s}$  of the soil  
 160 property between every two soil elements can be constructed. A possible realization of the  
 161 lognormal random field simulation can be generated as follows.

$$162 \quad s_{ij} = \exp\left(\mu_{\ln s E_j} + \sigma_{\ln s E_j} \cdot \ln s_{ij}\right) \quad (3)$$

163 where  $s_{ij}$  is the  $j^{\text{th}}$  numerical element of the  $i^{\text{th}}$  realization of the random field ( $i = 1, 2, \dots, N_p; j$   
 164  $= 1, 2, \dots, n_E$ ),  $N_p$  is the number of realizations of the random field, and  $n_E$  is the number of  
 165 discretized numerical elements of the slope;  $\mu_{\ln s E_j}$  and  $\sigma_{\ln s E_j}$  are the averaged mean and  
 166 standard deviation of the soil property  $\ln s$  over the  $j^{\text{th}}$  numerical element, respectively;  $\ln s_{ij}$  is  
 167 the  $j^{\text{th}}$  element of the  $i^{\text{th}}$  realization of the random field. The matrix  $\ln s_i$  of the soil property for  
 168 all numerical elements is derived as follows.

$$169 \quad \ln s_i = \mathbf{L}_{\ln s} \boldsymbol{\xi}_i \quad (4a)$$

$$170 \quad \mathbf{R}_{\ln s} = \mathbf{L}_{\ln s} \times \mathbf{L}_{\ln s}^T \quad (4b)$$

171 where  $\boldsymbol{\xi}_i$  is an  $n_E \times 1$  standard normal sample vector ( $i = 1, 2, \dots, N_p$ ), which may be obtained  
 172 with Latin hypercube sampling;  $\mathbf{L}_{\ln s}$  is a lower triangular matrix of autocorrelation matrix  $\mathbf{R}_{\ln s}$

173 derived by Cholesky decomposition technique.

174 Suppose that the borehole data are located at the points  $(x_1, y_1), (x_2, y_2), \dots, (x_p, y_p)$  and  
175 the unsampled locations are  $(x_{p+1}, y_{p+1}), (x_{p+2}, y_{p+2}), \dots, (x_{nE}, y_{nE})$ . Based on the generated  
176 unconditional random fields and borehole data, the conditional random fields can be  
177 simulated by the kriging method as follows (Liu et al. 2017):

178 **Step 1:** Calculate the locally averaged mean  $\mu_{lnsE}$  and standard deviation  $\sigma_{lnsE}$  of the soil  
179 property  $s$  in normal space (see Eq. (1));

180 **Step 2:** Generate the unconditional random fields  $lns^{UC}$  of soil property  $s$  in normal space  
181 with obtained mean  $\mu_{lnsE}$ , standard deviation  $\sigma_{lnsE}$ , and scales of fluctuation  $\lambda_{lnx}$  and  $\lambda_{lny}$  (see  
182 Eq. 2 and Eq. 4);

183 **Step 3:** Extract the values at sampled locations from the generated unconditional random  
184 fields as the “known data”. The normalized soil properties  $lns^{KU}$  at unsampled locations can  
185 be estimated by the “known data” as

$$\begin{bmatrix} \mathbf{K} & \mathbf{I} \\ \mathbf{I}^T & 0 \end{bmatrix} \begin{bmatrix} \boldsymbol{\beta} \\ \boldsymbol{\lambda} \end{bmatrix} = \begin{bmatrix} \boldsymbol{\kappa} \\ 1 \end{bmatrix} \quad (5a)$$

$$187 \quad K_{ij} = \rho_{ij} \cdot \sigma_{si} \cdot \sigma_{sj} \quad (i \text{ and } j = 1, 2, \dots, p) \quad (5b)$$

$$188 \quad \boldsymbol{\beta} = [\beta_1, \beta_2, \dots, \beta_p]^T \quad (5c)$$

$$189 \quad \kappa_{ij} = \rho_{ij} \cdot \sigma_{si} \cdot \sigma_{sj} \quad (i = 1, 2, \dots, nE-p; j = 1, 2, \dots, p) \quad (5d)$$

190 where  $\mathbf{K}$  is the covariance matrix derived from borehole data, and each element  $K_{ij}$  of  $\mathbf{K}$  can  
191 be calculated by Eq. (5b);  $\mathbf{I}$  is a  $p \times 1$  vector with all values equal to 1;  $\boldsymbol{\beta}$  is a  $p \times 1$  weight  
192 vector (see Eq. (5c)) with  $\sum_{i=1}^p \beta_i = 1$ ;  $\boldsymbol{\kappa}$  is the vector of covariance between the unsampled  
193 point and borehole data, and each element  $\kappa_{ij}$  of  $\boldsymbol{\kappa}$  is derived from Eq. (5d);  $\square \rho_{ij}$  in Eq. (5b)

194 is the spatial correlation between the  $i^{\text{th}}$  and  $j^{\text{th}}$  borehole data (see Eq. (2)), while that in Eq.  
 195 (5d) is the spatial correlation between the  $i^{\text{th}}$  unsampled point and  $j^{\text{th}}$  borehole data. With  
 196 obtained weight vector  $\beta$ , for example, the soil property value of the  $(p+1)^{\text{th}}$  soil element at  
 197 location  $(x_{p+1}, y_{p+1})$  is estimated from borehole data as

$$198 \quad \ln s^K(x_{p+1}, y_{p+1}) = \sum_{i=1}^p \beta_i \ln s(x_i, y_i) \quad (6)$$

199 **Step 4:** Estimate the normalized soil property values  $\ln s^{\text{KK}}$  at unsampled locations with the  
 200 real known data by repeating step 3.

201 **Step 5:** Obtain the normal conditional random fields as

$$202 \quad \ln s^c(x, y) = \ln s^{\text{KK}}(x, y) + [\ln s^{\text{UC}}(x, y) - \ln s^{\text{KU}}(x, y)] \quad (7)$$

203 where  $\ln s^{\text{UC}}(x, y)$  is the unconditional random field;  $\ln s^{\text{KK}}(x, y)$  is the random field  
 204 estimated by the kriging method for the given borehole data;  $\ln s^{\text{KU}}(x, y)$  is the random field  
 205 estimated by the kriging method, which takes the values at the borehole locations from the  
 206 unconditional random field as the borehole data. According to Eq. (7), the soil properties at  
 207 unsampled locations are estimated as kriging random fields  $\ln s^{\text{KK}}(x, y)$  with a stochastic  
 208 error of  $|\ln s^{\text{UC}}(x, y) - \ln s^{\text{KU}}(x, y)|$ , which increases with the distance between unknown and  
 209 known data. Therefore, the discontinuity of the soil property distribution can be avoided,  
 210 although the estimated soil properties at sampled locations always match the known data.

211 **Step 6:** Transfer the normal conditional random fields into lognormal conditional random  
 212 fields using Eq. (3).

213

214 **2.2 Correlation analysis using Spearman rank correlation coefficient to locate additional  
 215 boreholes**

With the constructed conditional random fields, the characteristics of the slope (i.e., the factor of safety, location of the slip surface, and sliding volume) can be captured by Monte Carlo simulations (MCS). Since stability assessment is the most crucial problem for the slope, the most effective boreholes are more likely to locate at the places where the soil elements are positively related to the factor of safety of the slope. Only the soil strength properties (e.g., the undrained shear strength  $c_u$ ) are modeled by the random fields, and the large values of the strength properties tend to correlate with higher values of  $FS$ . The values of the correlation coefficient between each soil element and  $FS$ , which can be either positive or negative, can be implemented to characterize the contribution of the soil element to the  $FS$  instead of the absolute values of the correlation coefficient. As shown later in the following example application, there are very low negative relations between the soil elements far from the slip surface and  $FS$ , while the soil elements near the slip surface strongly positively correlate with  $FS$ . Various correlation coefficients may be applied for the correlation analysis, such as the Pearson correlation coefficient, Kendall correlation coefficient, and Spearman rank correlation coefficient. Although the Pearson correlation coefficient is much more popular, the Pearson correlation coefficient is generally effective in characterizing linear correlations and more likely to mischaracterize the relationships and cause bias due to the nonnormality of the data (Bishara and Hittner 2015). As an alternative (Bishara and Hittner 2015; De et al. 2016; Thirumalai et al. 2017), the Spearman rank correlation coefficient is 1) applicable for both normal and nonnormal distributed data; 2) effective in characterizing linear or nonlinear correlations; 3) more robust and insensitive to outliers. Compared to Kendall's tau correlation coefficient, the Spearman rank correlation coefficient is less computationally demanded, less complicated and sufficiently accurate to characterize the correlations in this study. Therefore,

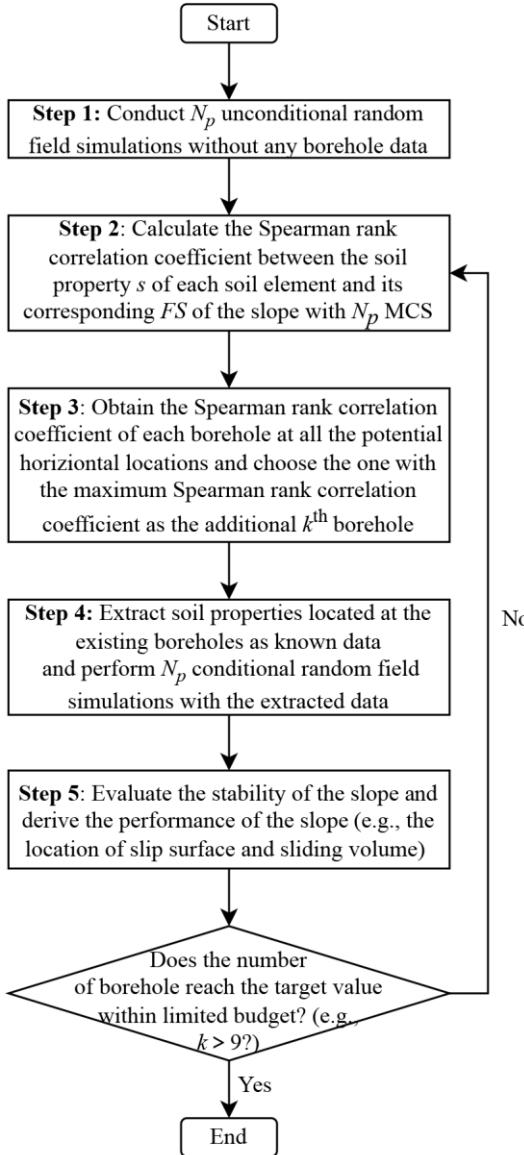
239 the Spearman rank correlation coefficient is adopted to characterize the correlation between  
 240 soil elements and  $FS$ . Suppose that the soil property values of the  $j^{\text{th}}$  numerical element with  
 241  $N_p$  realizations of the random field are  $\mathbf{s}_j = [s_{1j}, s_{2j}, s_{3j}, \dots, s_{Npj}]$  and the factors of safety with  
 242  $N_p$  random field simulations are  $\mathbf{FS} = [FS_1, FS_2, \dots, FS_{Np}]$ . The Spearman rank correlation  
 243 coefficient between the  $j^{\text{th}}$  soil element and  $\mathbf{FS}$  is formulated as:

$$244 \quad \rho_{\text{Spearman}}(\mathbf{s}_j, \mathbf{FS}) = \frac{\sum_{i=1}^{N_p} (n_{1i} - \bar{n}_1)(n_{2i} - \bar{n}_2)}{\sqrt{\sum_{i=1}^{N_p} (n_{1i} - \bar{n}_1)^2} \sqrt{\sum_{i=1}^{N_p} (n_{2i} - \bar{n}_2)^2}} \quad (8)$$

245 where  $n_{1i}$  and  $n_{2i}$  are the ascending or descending sorted positions determined by the values of  
 246 each element in  $\mathbf{s}_j$  and  $\mathbf{FS}$  with  $N_p$  random field simulations, respectively;  $\bar{n}_1$  is the mean of  
 247  $n_{1i}$  ( $i=1, 2, \dots, N_p$ );  $\bar{n}_2$  is the mean of  $n_{2i}$  ( $i=1, 2, \dots, N_p$ ). The Spearman rank correlation  
 248 coefficient can be directly obtained using a command (`corr(sj, FS, 'type', 'spearman')`) in  
 249 MATLAB, where all calculation procedures are involved. After the sensitive soil elements  
 250 with high Spearman rank correlation coefficients are revealed, the stability of the slope can be  
 251 accurately evaluated. Since each soil sample is equally mapped from the random field  
 252 simulations and plays an equal role in building a geotechnical profile, the amount of  
 253 information provided by each soil sample should be considered the same, while the  
 254 importance of information (characterized by the Spearman rank correlation coefficient in this  
 255 study) brought by each soil sample depends on the characteristics (e.g., failure mechanism) of  
 256 the geotechnical systems. The importance of information provided by a borehole is believed  
 257 to be well characterized by its statistics, i.e., the mean or sum of the data from the borehole.  
 258 However, it may be problematic in some scenarios when the sum-based method is adopted.

259 For example, the important local area (e.g., slope toe) that controls the slope stability cannot  
260 be well captured by the sum-based method, since the optimal borehole location is more likely  
261 determined at the place where more data can be obtained by the sum-based method, which is  
262 not consistent with the fact that the boreholes at the slope domain are generally more effective,  
263 although fewer data are measured in this area (Li et al. 2016b). Therefore, the mean Spearman  
264 rank correlation coefficient is adopted to evaluate the effectiveness of the borehole data for  
265 the stability assessment of the slope.

266 The flowchart of the proposed method is illustrated in Figure 1. In the first step,  $N_p$   
267 samples of unconditional random fields are generated with prior knowledge of the mean,  
268 standard deviation, and scales of fluctuation of the soil properties. Then, the degree of the  
269 influence of each soil element on the  $FS$  in terms of the Spearman rank correlation coefficient  
270 is calculated in step 2. In step 3, the effectiveness of the additional borehole along all potential  
271 horizontal locations is evaluated based on the mean Spearman rank correlation coefficient of  
272 the soil elements from the borehole. The optimal borehole is located where the borehole has  
273 the largest Spearman rank correlation coefficient. With the extracted borehole data, the  
274 conditional random fields are simulated to consider the constraint of the added borehole in  
275 step 4. In step 5, the  $FS$ , location of the slip surface, and sliding volume can be evaluated for  
276 the updated borehole pattern. This process will be repeated until the target number of  
277 boreholes ( $N_{BH}$ ) is reached. Whether the target probability of failure or the accuracy of the  
278 target factor of safety is reached may be the optional ended conditions for the optimization.  
279 These values generally depend on the specific slope problems, and the target number of  
280 boreholes with a limited budget is assumed in this study.



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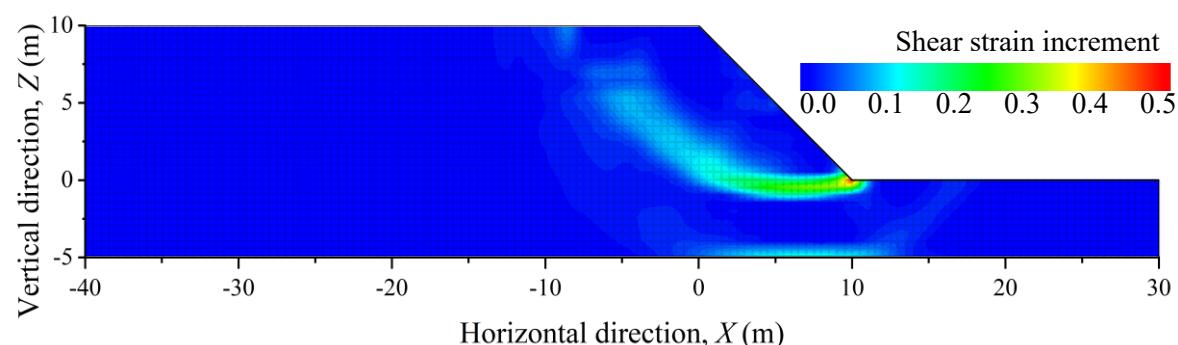
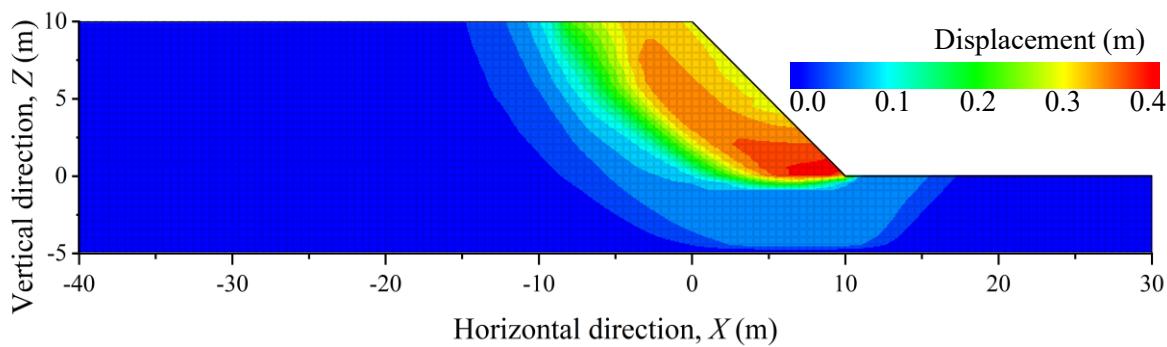
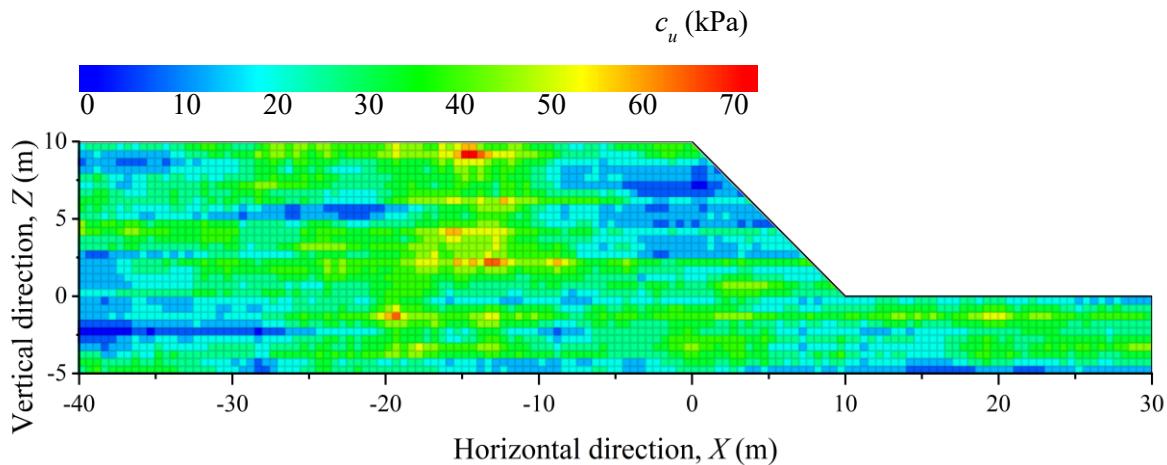
Figure 1. Flow chart of the proposed method for site investigation

285 In this section, an undrained slope with a height of 10 m and a slope angle of 45° (1:1  
 286 slope) is adopted as an example to demonstrate the proposed method. The factor of safety is  
 287 obtained using the strength reduction method built in the 3-D explicit finite difference  
 288 program FLAC3D version 7.0 ([Itasca 2022](#)). The mesh size of the numerical model is 0.5 m

289 by 0.5 m. The elastic-perfectly plastic Mohr–Coulomb model is adopted to model the soil  
 290 behaviors. A fixed boundary is applied to the slope bottom, while the roller boundary is  
 291 applied to the slope back and front faces. The undrained shear strength  $c_u$  is simulated as  
 292 random fields, while other soil properties are set as constant values. The soil properties are  
 293 tabulated in [Table 1](#). The effectiveness of the proposed method is validated by a comparative  
 294 study with traditional methods. To compare with the “true” site characterization, one of the  
 295 generated unconditional random field simulations is taken as a “true” slope ([Shen et al., 2018](#)).  
 296 Therefore, the characteristics of the “true” slope (i.e., the factor of safety, location of the slip  
 297 surface, and sliding volume) can be derived to validate the proposed method. The spatially  
 298 variable soil of the “true slope” with  $FS = 1.05$  is illustrated in [Figure 2\(a\)](#), while the contours  
 299 of the displacement and shear strain increment are shown in [Figure 2\(b\)](#) and [Figure 2\(c\)](#),  
 300 respectively.

301 Table 1. Statistics of the soil properties for the example slope problem

Parameter	Value
Density, $\rho$ (kg/m <sup>3</sup> )	2000
Young’s modulus, $E$ (MPa)	100
Poisson’s ratio, $\nu$	0.30
Mean of undrained shear strength, $c_u$ (kPa)	40
COV of undrained shear strength $c_u$	0.3
Horizontal scale of fluctuation, $\lambda_{\text{Inv}}$ (m)	40
Vertical scale of fluctuation, $\lambda_{\text{Inv}}$ (m)	4



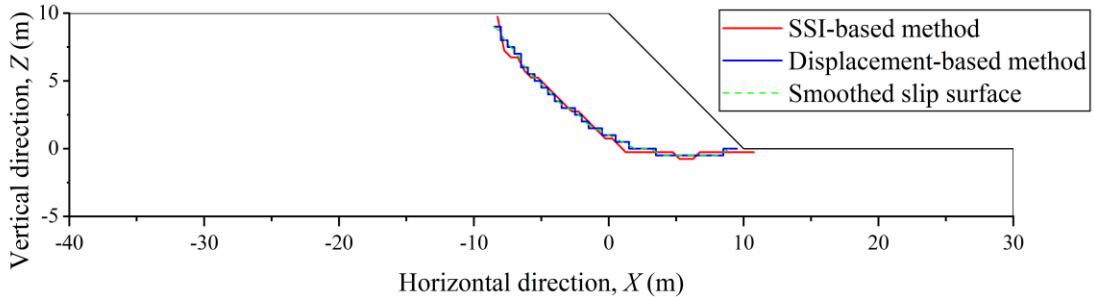
308 Figure 2. Characteristics of the “true” slope ( $FS = 1.05$ )

309

310 **3.1 Illustration of the borehole patterns for the comparison study**

In the traditional method, boreholes generally have an equally spaced distribution or are symmetrically distributed in an estimated influence zone (Gong et al. 2014; Yang et al. 2019&2022). However, the determination of the range of the influence zone considerably depends on the engineers' experience in practice, which leads to cost-inefficient design. For the slope in Figure 2, without loss of generality, 9 boreholes ( $N_{BH} = 9$ ) with a limited budget are assumed for the slope problem. According to Li et al. (2016a) and Deng et al. (2017), boreholes that reveal the location of the slip surface are more effective. In the numerical analysis of slope stability by FLAC3D, two main methods are employed to automatically locate the slip surface (Wang et al., 2020). The first method is the shear strain increment-based (SSI-based) method, and the other method is the nodal displacement-based method. The latter is more extensively used for its simplicity, and it is now built in FLAC3D. This method can also be effective in identifying local failures in 3-D slopes with spatially variable soil (Zhang et al. 2022). Therefore, the nodal displacement-based method is adopted to locate the slip surface in this study. In the nodal displacement-based method, a threshold of the maximum nodal displacement of all mesh grids should be first determined. A soil element where the displacement of all nodes exceeds the threshold of the maximum nodal displacement will be considered a sliding soil element. The sliding surface is identified as the boundary between sliding soil elements and stable soil elements. To determine the threshold value of the maximum nodal displacement, the slip surface derived by the max shear strain increment can be taken as a benchmark (Hicks et al. 2014). The results in Figure 3 indicate that the contour of 35% maximum nodal displacement coincides with the contour of the maximum shear strain increment for the “true” slope. As shown in Figure 3, it is suggested that some advanced smoothing methods such as the polynomial spline technique should be

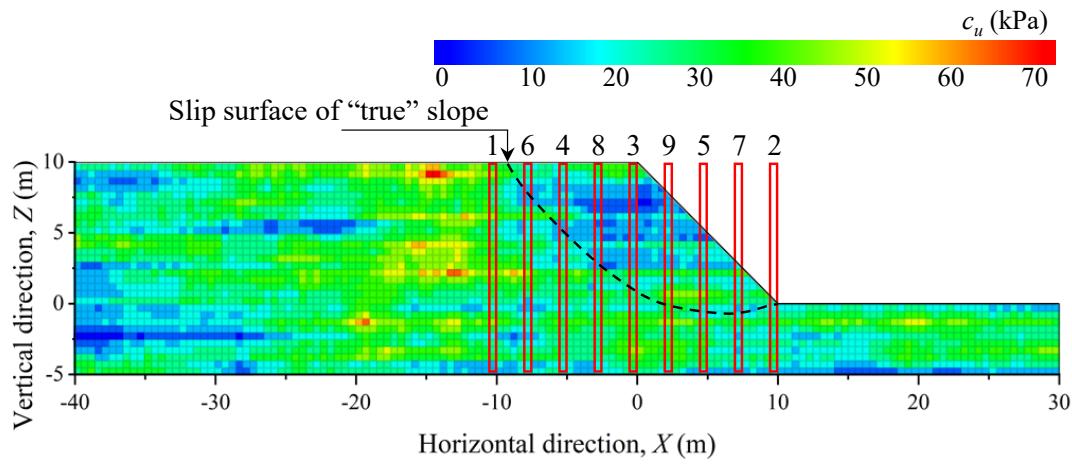
334 applied to the slip surface to satisfy the kinematic demands for the slope (Wang et al. 2020).  
 335 However, the unsmoothed error is negligible in the comparison results. Therefore, the fitting  
 336 technique is not implemented in this study to simplify the calculation of the sliding volume.



337  
 338 Figure 3. Location of the slip surface, which is determined by 35% of the maximum nodal  
 339 displacement and maximum shear strain increment

340  
 341 Based on the traditional method, several boreholes may be equally spaced and applied  
 342 to the area where the slip surface is accurately estimated, which is denoted as the borehole  
 343 pattern with good judgement (see Figure 4(a)). Since the slip surface is bound to go through  
 344 the slope domain, all boreholes can be located at the slope domain, which is denoted as the  
 345 borehole pattern with moderate judgement (see Figure 4(b)). To avoid the nonconservative  
 346 design, a sufficiently larger area (of the model domain) may be estimated for the borehole  
 347 distributions, which is denoted as the borehole pattern with poor judgement (see Figure 4(c)).  
 348 With predefined traditional borehole patterns, Monte-Carlo simulation (MCS) is employed to  
 349 capture the performance of the slope. As shown in Figure 5(a), the mean and standard  
 350 deviation of  $FS$  converge when 800 MCS runs are performed. From Figure 5(b), the mean  
 351 Spearman rank correlation coefficient of the soil elements from the entire numerical model  
 352 and one borehole at the slope crest also becomes stable within 800 runs. Therefore, 1000 runs

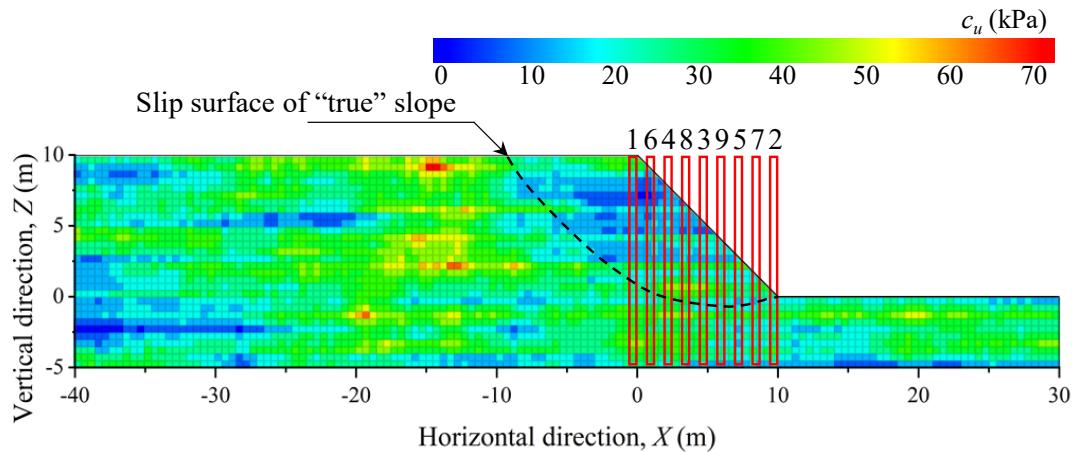
353 of MCS ( $N_p = 1000$ ) are considered sufficient to obtain the slope system responses. With 1000  
 354 runs of MCS, both unconditional and conditional random field simulations are validated by  
 355 the comparison between the preset statistics (e.g., the mean and standard deviation) of soil  
 356 properties and those derived from the simulations (Gong et al. 2018; Huang et al. 2019; Johari  
 357 and Fooladi 2020).



358

359

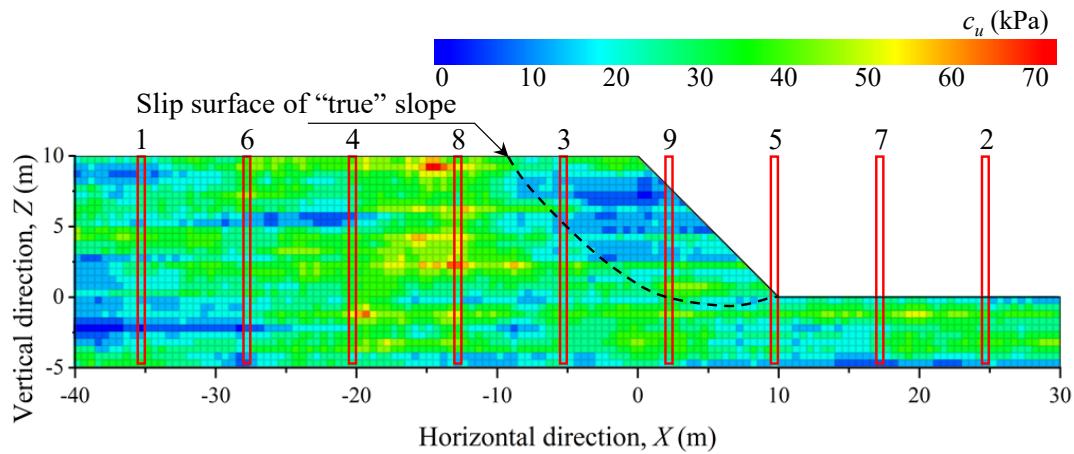
(a) Good judgement



360

361

(b) Moderate judgement



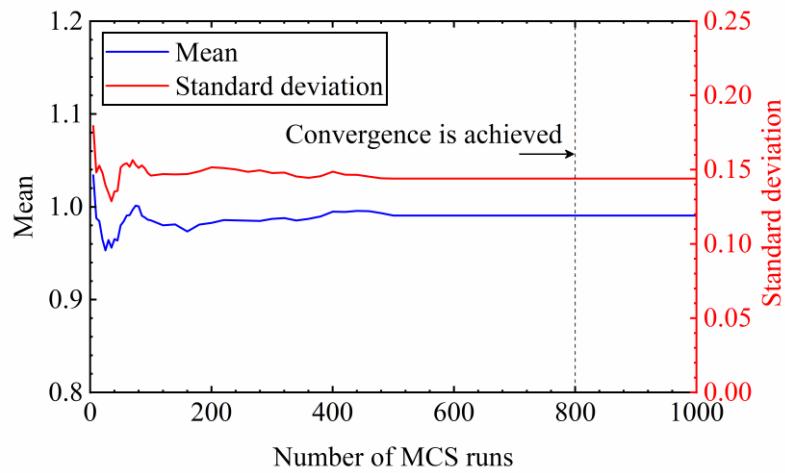
362

363

(c) Poor judgement

364

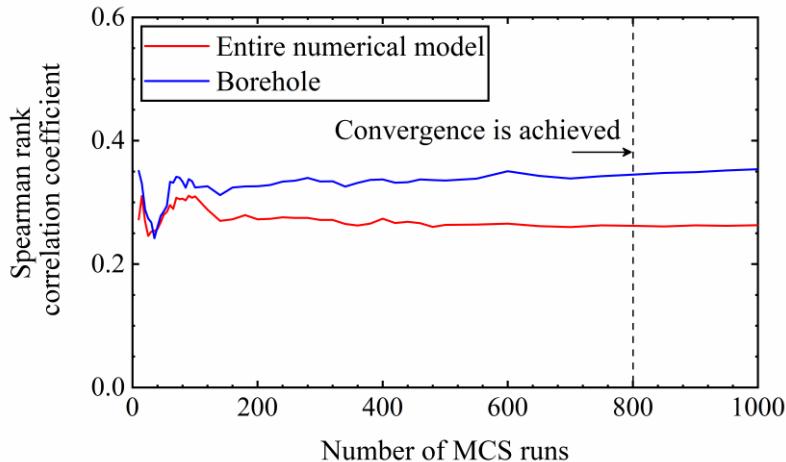
Figure 4. Borehole patterns from traditional methods



365

366

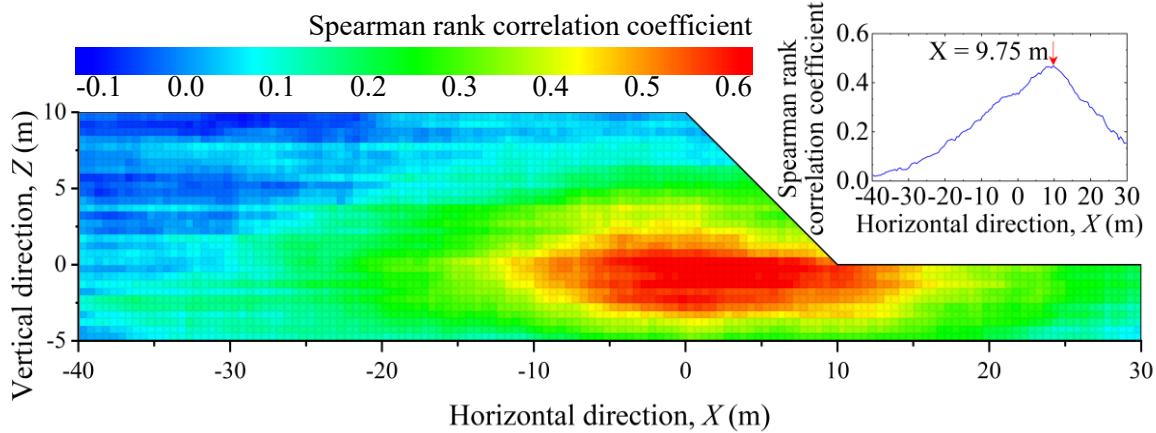
(a) Convergence of FS



367  
 368 (b) Convergence of the Spearman rank correlation coefficient  
 369 Figure 5. Convergence of the  $FS$  and Spearman rank correlation coefficient with the increase  
 370 in number of MCS runs

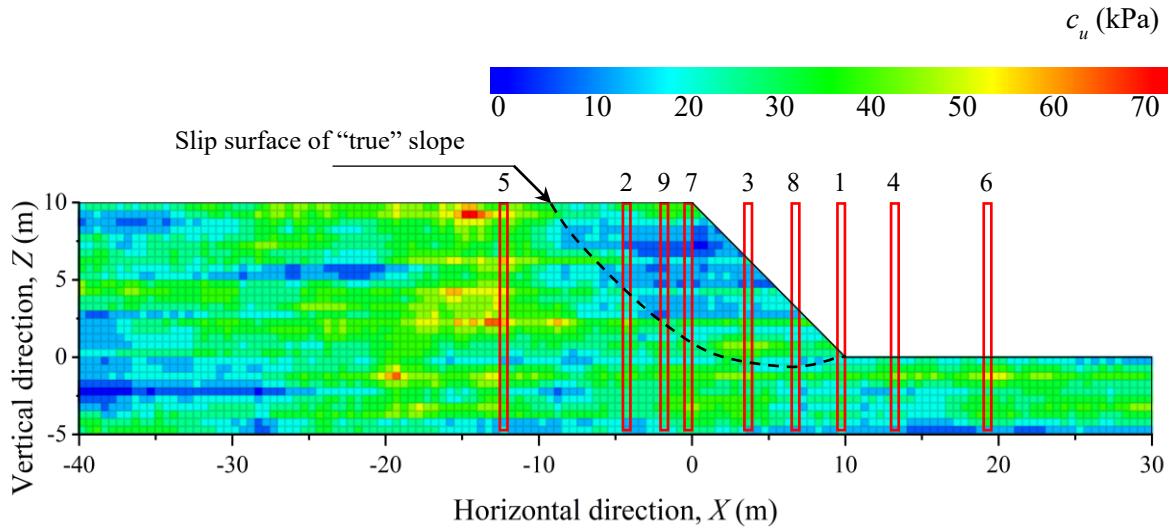
371 Following the proposed site investigation method, the boreholes are added step by step.  
 372 Figure 6 shows the contour of the Spearman rank correlation coefficient without boreholes.  
 373 The soil elements with a large Spearman rank correlation coefficient are distributed at the  
 374 bottom of the slope domain, since these soil elements may determine whether the deep mode  
 375 or shallow mode of failure will occur if no borehole is applied. The first borehole is optimized  
 376 at  $X = 9.75$  m (i.e., at the slope toe), which is consistent with the conclusion from [Jiang et al.](#)  
 377 ([2018a](#)). Thus, the final borehole pattern from the proposed method is illustrated in [Figure 7](#).  
 378 The characteristics of the slope (i.e., the factor of safety, location of the slip surface, and  
 379 sliding volume) with the traditional methods and proposed method are studied in the  
 380 following comparative study.

381



382  
383 Figure 6. Determining the additional borehole from the Spearman rank correlation coefficient

384  $(N_{BH} = 0)$

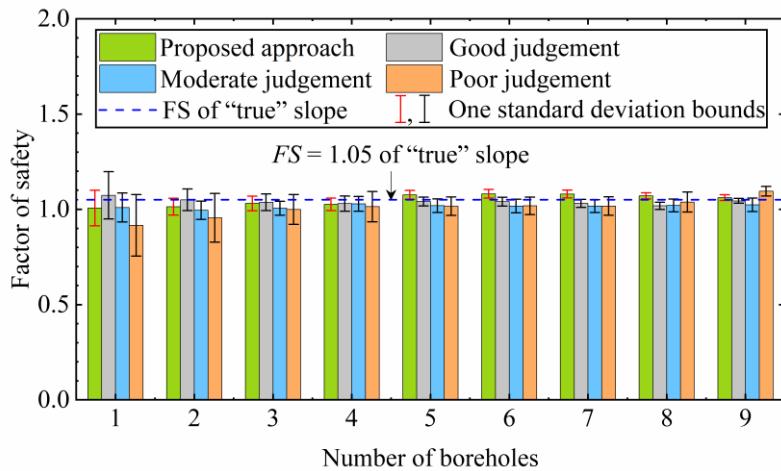


385  
386 Figure 7. Borehole pattern obtained using the proposed method

387  
388 **3.2 Comparison study on the estimate of the slope characteristics**

389 The mean  $FS$  with a (negative or positive) standard deviation from 1000 MCS is  
390 presented in Figure 8. As shown in Figure 8, the difference between  $FS$  of the “true” slope  
391 and mean estimated  $FS$  from all borehole patterns decreases with the number of boreholes.  
392 When the number of boreholes is larger than 3 (i.e.,  $N_{BH} > 3$ ), the error is negligible, which

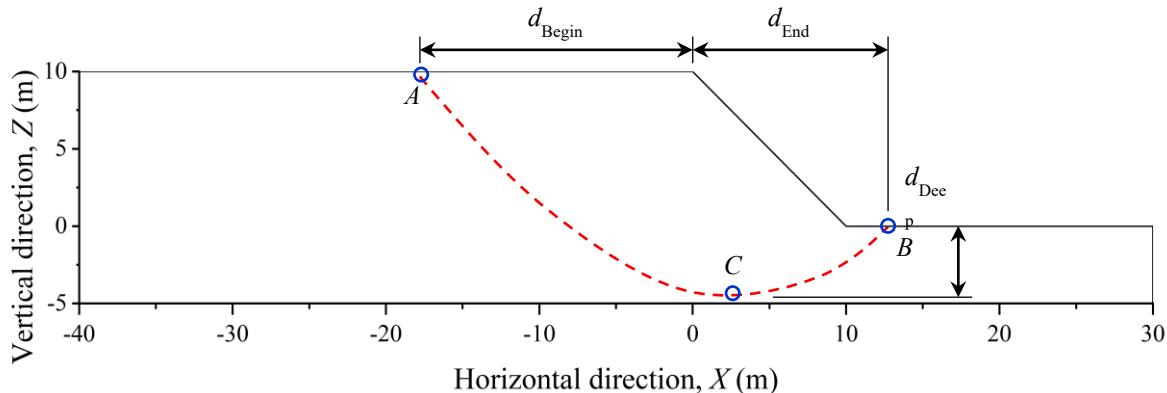
393 implies that the mean  $FS$  can be effectively estimated for all borehole patterns. The standard  
 394 deviation of the  $FS$  rapidly decreases with the increase in number of boreholes by applying  
 395 the borehole patterns from the proposed method and traditional method with good judgement,  
 396 which indicates that these two methods are superior to the other two in reducing the  
 397 uncertainty of  $FS$ .



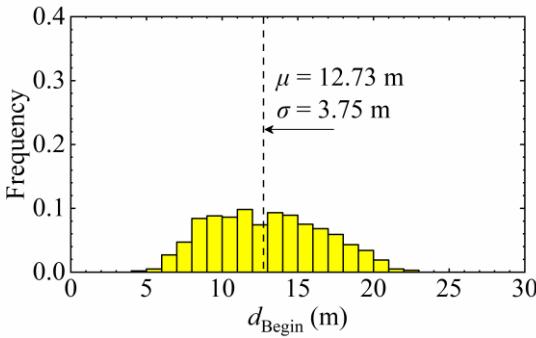
398  
 399 Figure 8. A comparison study of the estimated  $FS$  among different borehole patterns  
 400

401 The uncertainty of the location of the slip surface can be characterized by the area of  
 402 the potential locations of the slip surface (Liu et al. 2017) or the uncertainty of the controlling  
 403 points (Johari and Gholampour 2018; van den Eijnden and Hicks 2018). The latter is used in  
 404 this study for its simplicity. As shown in Figure 9, there are three controlling points  $A$ ,  $B$  and  
 405  $C$  at the slip surface of the slope. The leftmost and rightmost points  $A$  and  $B$  determine the  
 406 range of the influence zone, which can be calculated by summing the horizontal distance from  
 407 point  $A$  to slope crest  $d_{\text{Begin}}$  and that from point  $B$  to slope crest  $d_{\text{End}}$ . The deepest point  $C$  is  
 408 related to the slope failure mechanism. If the vertical distance from point  $C$  to slope toe  $d_{\text{Deep}}$   
 409 is positive, a deep failure mode will occur for the slope. Otherwise, the shallow failure mode

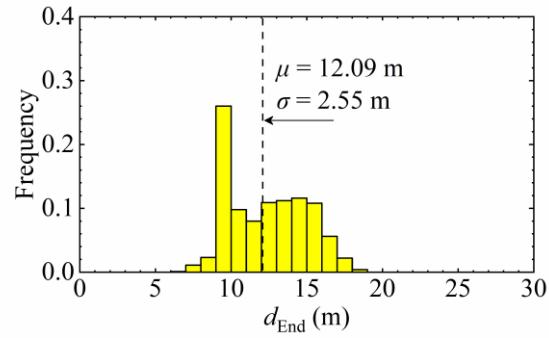
410 can be found. When the location of the slip surface is determined, the sliding volume can be  
 411 easily calculated. With the adopted methods, the location of the slip surface of the “true”  
 412 slope is derived as  $d_{\text{Begin}} = 8.5$  m,  $d_{\text{End}} = 9.5$  m, and  $d_{\text{Deep}} = 0.5$  m, while the sliding volume of  
 413 the “true” slope is  $V = 101.75$  m<sup>2</sup>/m. The estimated results of the location of the slip surface  
 414 and sliding volume without boreholes are summarized in Figure 10. As shown in Figure 10,  
 415 the estimated mean  $\mu$  is far from the “true” value, and the standard deviation  $\sigma$  is large in the  
 416 estimated results of the location of the slip surface and sliding volume, which indicates  
 417 considerable estimate errors and uncertainties in the location of the slip surface when there is  
 418 no site investigation effort (reflected by the total number of boreholes required).



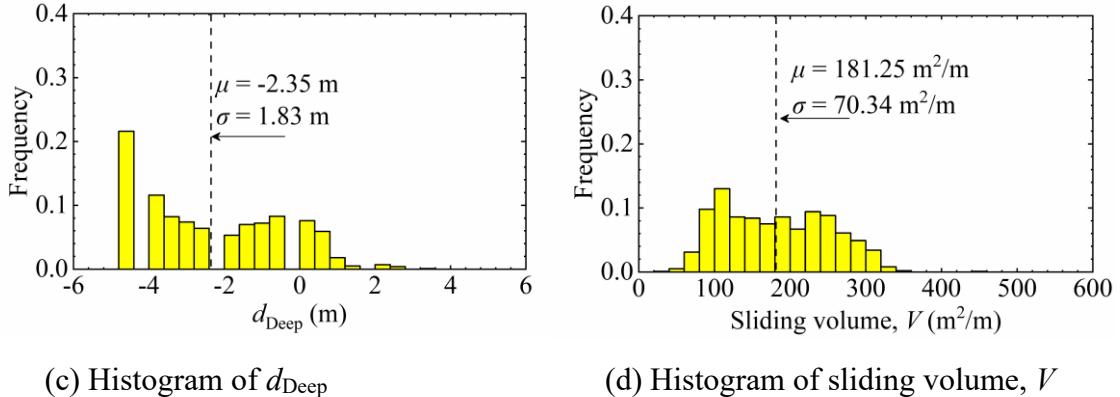
419  
 420 Figure 9. Location of the slip surface characterized using three controlling points



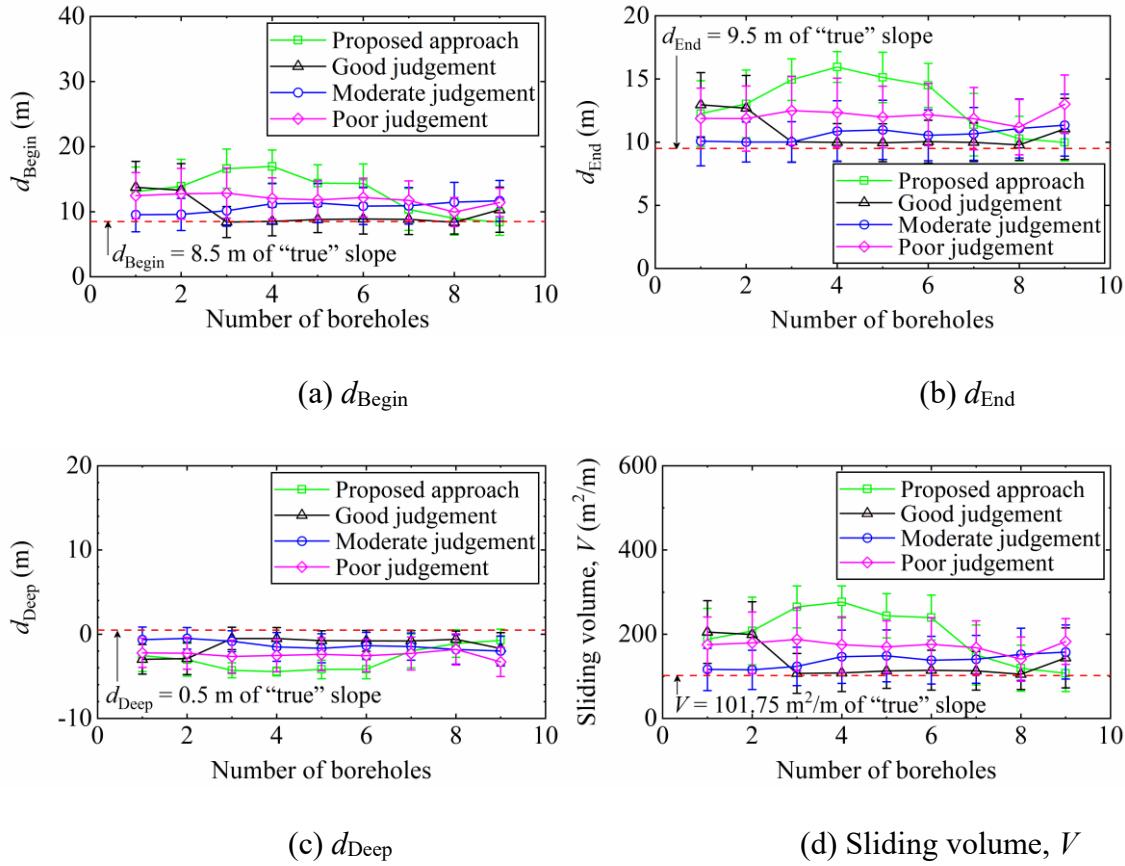
421 (a) Histogram of  $d_{\text{Begin}}$



(b) Histogram of  $d_{\text{End}}$



space may be problematically determined, and the increase in borehole number does not necessarily improve the accuracy in estimating the slip surface and sliding volume, which results in considerable challenges in the borehole configuration for the traditional method. For the proposed method, nine boreholes are required to accurately estimate the slip surface and sliding volume. The proposed method appears to require more effort than the results from good judgement. However, an implicit huge effort may be needed to guarantee the accurate estimation of the location of the slip surface for good judgement in practical slope problems, which is not evaluated in this comparison study. Therefore, the superiority of nonequal spacing planning of the site investigation based on the Spearman rank correlation coefficient is sufficiently demonstrated.



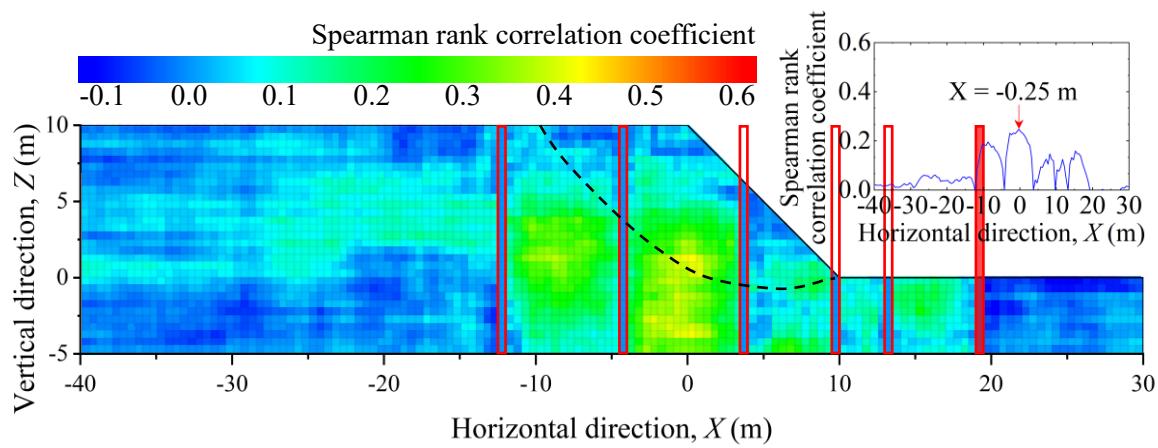
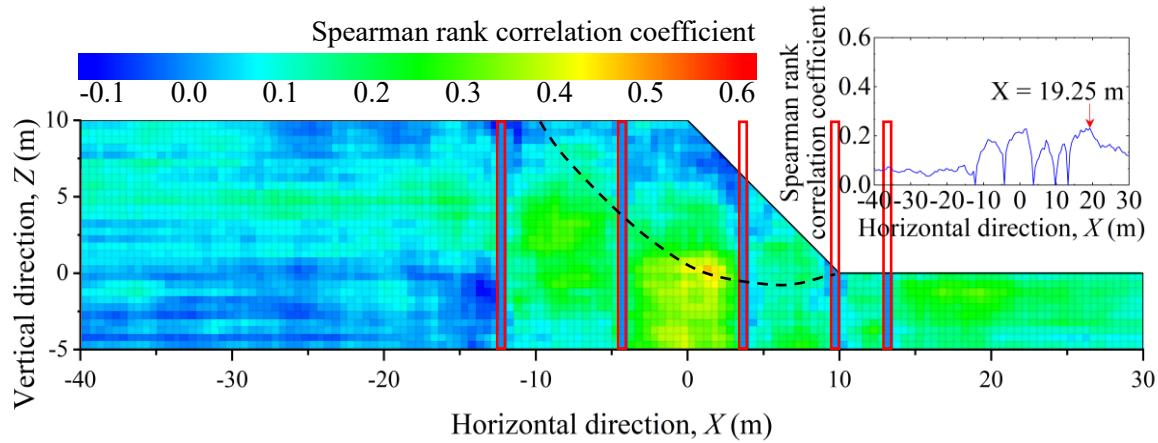
456 Figure 11. A comparison study of the characteristics of the slope with the proposed method

457 and traditional method

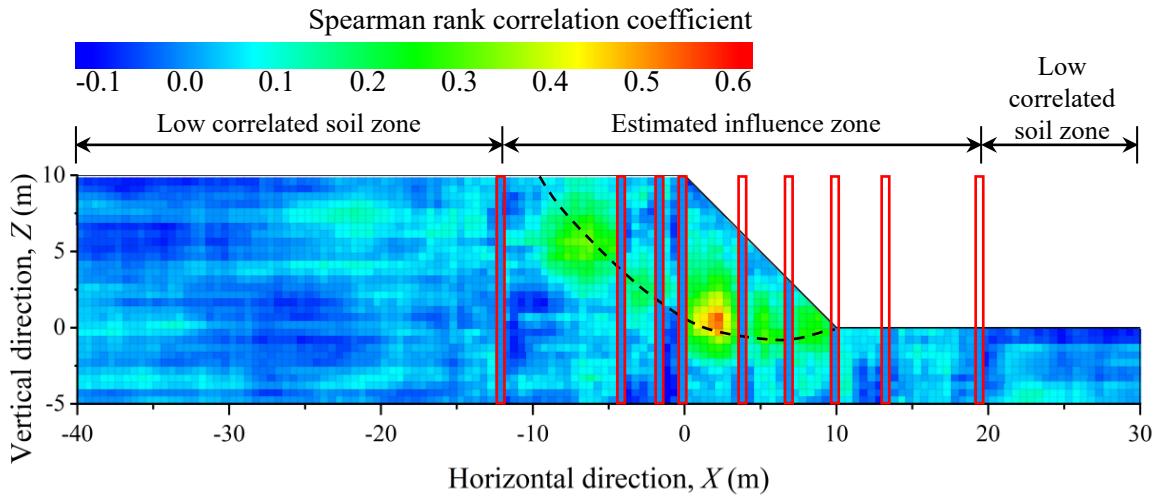
458

459 **3.3 Discussion of the borehole pattern from the proposed method**

460 As mentioned above, effective boreholes should be located to reveal the location of  
461 the slip surface, and the challenge for this objective is how to accurately estimate the range of  
462 the “true” sliding area. [Figure 7](#) shows the final borehole pattern from the proposed method. It  
463 seems the fourth, the fifth and the sixth boreholes are ineffective in this borehole pattern,  
464 since the three boreholes are outside the “true” influence zone. However, the sliding area is  
465 well bracketed by the fourth and fifth boreholes. The two boreholes can be useful to estimate  
466 the influence zone, since a small error will be obtained. The effect of the sixth borehole can be  
467 illustrated by the change in contour of the Spearman rank correlation coefficient with different  
468 numbers of boreholes. The contour of the Spearman rank correlation coefficient with the fifth  
469 and sixth boreholes is plotted in [Figure 12](#). As shown in [Figure 12](#), with five boreholes  
470 applied to the slope, it is still difficult to examine if the area on the right of the fifth borehole  
471 is a low or high correlated soil zone because the large initial investigation area is adopted  
472 (from  $X = -40$  m to  $X = 30$  m). After applying the sixth borehole, this area is updated as a  
473 low-correlated soil zone. Therefore, the sixth borehole can be considered a part of the effort to  
474 automatically identify the influence zone. [Figure 13](#) shows the contour of the Spearman rank  
475 correlation coefficient with nine boreholes from the proposed method. The final influence  
476 zone is derived as the area between the fifth and sixth boreholes, while the remaining area is a  
477 low-correlated soil zone. Therefore, it is effective to automatically estimate the influence zone  
478 for the slope with the proposed method, even if the initial investigation area is considerably  
479 conservatively selected.



484 Figure 12. Illustration of the effect of the sixth borehole from the proposed method



486

487

Figure 13. Estimated influence zone by the proposed method ( $N_{BH} = 9$ )

488

#### 489 4. Robustness analysis and risk assessment

490 In addition to the characteristics of the slope, uncertainty reduction and risk reduction  
 491 are aspects of slope design. In this section, robustness analysis and risk assessment are  
 492 performed to validate the effectiveness of the proposed method in the comparison study.

##### 493 4.1 Robustness analysis

494 The robustness is defined as the sensitivity of the system response to the variation in  
 495 input parameters. The higher robustness of the geotechnical system implies that the system  
 496 can better resist the uncertainty of input parameters. Various robustness measurements are  
 497 formulated in geotechnical engineering, and the signal-to-noise ratio (SNR) is a commonly  
 498 used robustness measurement for slope problems (Gong et al. 2015&2017&2020). In this  
 499 paper, SNR is adopted to assess the robustness of the slope system, and a higher SNR value  
 500 indicates a higher system robustness. The *FS*, location of the slip surface, and sliding volume  
 501 are treated as the response of concern for the slope problem. The robustness of the *FS*,  
 502 location of the slip surface, and sliding volume can be calculated using Eqs. (9-11),

503 respectively. The robustness of the location of the slip surface is evaluated using the average  
 504 SNR of the three controlling points of the slip surface. With the obtained SNR values for the  
 505 FS, location of the slip surface and sliding volume, the robustness of the entire slope system  
 506 can be calculated using Eq. (12) based on a weighted average of three SNR values from Eqs.  
 507 (9-11) (Gong et al. 2017).

$$508 \quad SNR_{FS} = 10 \log_{10} \left( \frac{\mu_{FS}^2}{\sigma_{FS}^2} \right) \quad (9)$$

$$509 \quad SNR_L = \frac{1}{3} (SNR_A + SNR_B + SNR_C) \quad (10a)$$

$$510 \quad SNR_A = 10 \log_{10} \left( \frac{\mu_{d_{\text{Begin}}}^2}{\sigma_{d_{\text{Begin}}}^2} \right) \quad (10b)$$

$$511 \quad SNR_B = 10 \log_{10} \left( \frac{\mu_{d_{\text{End}}}^2}{\sigma_{d_{\text{End}}}^2} \right) \quad (10c)$$

$$512 \quad SNR_C = 10 \log_{10} \left( \frac{\mu_{d_{\text{Deep}}}^2}{\sigma_{d_{\text{Deep}}}^2} \right) \quad (10d)$$

$$513 \quad SNR_V = 10 \log_{10} \left( \frac{\mu_V^2}{\sigma_V^2} \right) \quad (11)$$

$$514 \quad S = w_{FS} SNR_{FS} + w_L SNR_L + w_V SNR_V \quad (12)$$

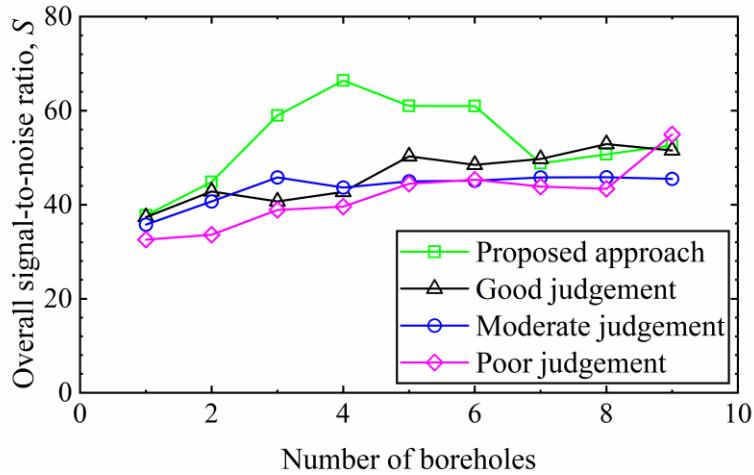
515 where  $SNR_{FS}$ ,  $SNR_L$ , and  $SNR_V$  are the robustness for the estimation of the FS, location of slip  
 516 surface ( $L$ ) and sliding volume ( $V$ ), respectively;  $SNR_A$ ,  $SNR_B$ , and  $SNR_C$  are the robustness for  
 517 the estimation of the horizontal distance of point  $A$  to the slope crest ( $d_{\text{Begin}}$ ), horizontal  
 518 distance of point  $B$  to the slope crest ( $d_{\text{End}}$ ) and vertical distance of point  $C$  to the slope toe  
 519 ( $d_{\text{Deep}}$ ), respectively. The robustness estimation of the location of the slip surface can be  
 520 characterized by the averaged  $SNR_A$ ,  $SNR_B$  and  $SNR_C$ . The overall robustness  $S$  for the slope is

521 a weighted summation of the three terms in Eqs. (9-11). The weighted factors  $w_{FS}$ ,  $w_L$  and  $w_V$   
522 may be determined by their corresponding contributions to the given geotechnical problems.  
523 Here,  $w_{FS} = w_L = w_V = 1$  is assumed for simplicity (Gong et al. 2017).

524 The robustness analysis results for different borehole patterns are plotted in Figure 14.  
525 The highest overall SNR value  $S$  can be obtained from the proposed method, which indicates  
526 that this method finds the most robust estimated characteristics of the slope. The overall SNR  
527 values  $S$  from traditional methods with good judgement and poor judgement increase with the  
528 number of boreholes, while those from the traditional method with moderate judgement  
529 converge at  $N_{BH} = 3$ . It seems that the borehole pattern with good judgement is the most  
530 effective in the robustness analysis, followed by the borehole pattern with moderate  
531 judgement, since all boreholes with good judgement are located at the influence zone and  
532 considerably reduce the uncertainty of the location of the slip surface and sliding volume.  
533 However, although the effect of the boreholes from moderate judgement is overlapped due to  
534 small borehole space and more additional boreholes cannot improve the robustness of the  
535 estimated results of the characteristics of the slope after  $N_{BH} = 3$ , more investigation effort is  
536 required to reach the higher level of robustness for the slope system, which is consistent with  
537 the fact that most boreholes based on poor judgement are outside the “true” influence zone.  
538 Therefore, the superiority of the robustness performance with the proposed method is  
539 sufficiently demonstrated.

540

541



542

543

Figure 14. Overall robustness with the increase in number of boreholes

544

545

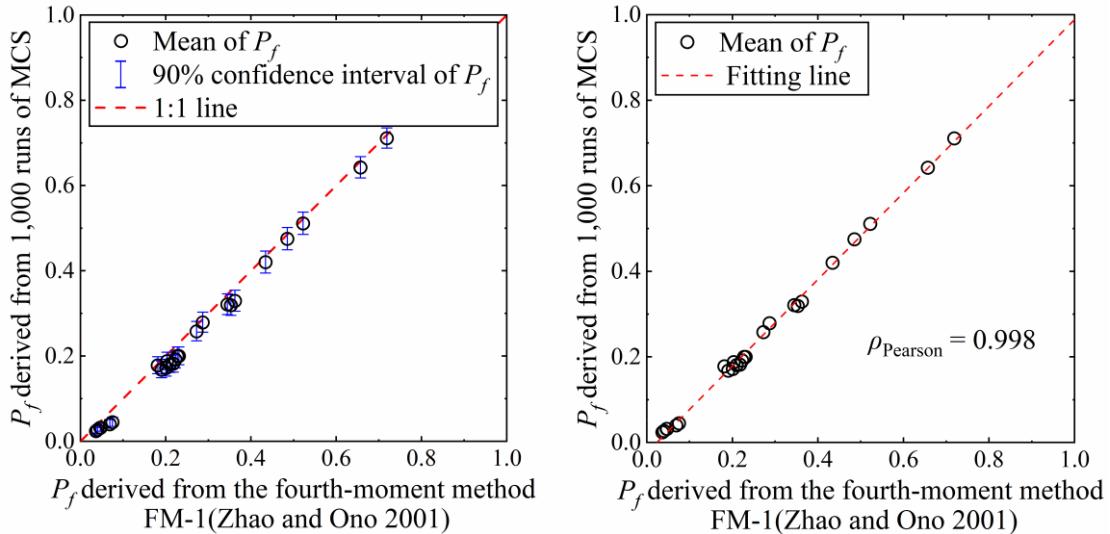
## 4.2 Risk assessment

546 Risk assessment can provide information for risk-informed decision-making. Herein,  
 547 the risk assessment for site investigation of slope problems is conducted following [Yang et al.](#)  
 548 ([2019](#)). According to [Yang et al. \(2019\)](#), the total loss cost  $C_{\text{total}}$  with different numbers of  
 549 boreholes can be described as

550 
$$C_{\text{total}} = N_{\text{BH}} \cdot C_{\text{BH}} + P_f \cdot C_{\text{false}} \quad (13)$$

551 where  $N_{\text{BH}}$  is the number of boreholes;  $C_{\text{BH}}$  is the average cost of one borehole;  $P_f$  is the  
 552 probability of failure of the slope; the  $C_{\text{false}}$  is the of making a false decision. To improve the  
 553 computational efficiency of the calculation of  $P_f$ , the MCS-based moment method FM-1 is  
 554 adopted to estimate the probability of failure ([Zhao and Ono 2001](#); [Zhang et al. 2022](#)). The  
 555 MCS is first performed to derive the dimensionless moments of the limit state function that  
 556 define the slope failure based on  $FS$ . Then, the formulas related to dimensionless moments are  
 557 utilized to estimate the probability of failure. Detailed descriptions and formulas can be found  
 558 in [Zhao and Ono \(2001\)](#) and [Zhang et al. \(2022\)](#). Figure 15 shows the validations of the

559 moment method FM-1 to estimate the probability of failure in this slope example, where the  
 560 analyses are performed for 25 slope scenarios with different numbers of boreholes. As shown  
 561 in [Figure 15\(a\)](#), the probabilities of failure from the FM-1 moment method are well bracketed  
 562 by the 90% confidence intervals of the probabilities of failure from the MCS. The Pearson  
 563 correlation coefficient between  $P_f$  obtained from the MCS and that from the FM-1 moment  
 564 method is 0.998 in [Figure 15\(b\)](#), which implies a strong linear correlation between them and  
 565 validates the accuracy of the FM-1 moment method. The cost of each borehole is assumed to  
 566 be  $C_{BH} = \$AUD\ 5,000$ , and the loss of making the false unsafe assessment of the slope  
 567 stability is assumed to be  $C_{false} = \$AUD\ 150,000$  following [Yang et al. \(2019\)](#), although the  
 568 measured data may be suggested to be more acceptable for the risk assessment if there are  
 569 available data.



570  
 571 (a)  $P_f$  from MCS versus that from FM-1      (b) Pearson correlation coefficient analysis  
 572  
 573 Figure 15. Validation of the moment method FM-1 (Zhao and Ono 2001) in estimating the  
 574 probability of slope failure in this study

575       Figure 16 shows that the expected total loss cost first decreases and subsequently  
576       increases with the number of boreholes for the proposed method. A minimum expected loss  
577       cost of approximately \$AUD 25,000 with five boreholes ( $N_{BH} = 5$ ) is obtained in the proposed  
578       method. From Eq. (13), the expected total loss cost consists of two parts: the cost of the  
579       boreholes and the expected loss cost of making a false decision. With the increase in number  
580       of boreholes applied to the slope, the mean  $FS$  will approach the “true”  $FS$ , and the standard  
581       deviation of  $FS$  will decrease. Since the “true”  $FS$  is 1.05, which is larger than 1,  $P_f$  will be  
582       close to 0 when sufficient boreholes are located at the slope, so the loss cost of making a false  
583       decision approaches 0. The total cost of the loss cost will be dominated by the cost of the  
584       boreholes. A minimum loss cost of approximately \$AUD 31,000 with the same site  
585       investigation effort ( $N_{BH} = 5$ ) is reached in the borehole pattern with good judgement.  
586       Compared to the risk assessment results from good judgement, an approximate 19% loss cost  
587       can be avoided from the proposed method. A similar trend of the loss cost to the proposed  
588       method can be obtained in the traditional method with moderate judgement, and the minimum  
589       loss cost is reached with four boreholes ( $N_{BH} = 4$ ). However, the loss cost from moderate  
590       judgement is higher than these two methods, since a small borehole space results in the  
591       overlapped effect of the applied boreholes. For poor judgement, the total cost decreases with  
592       the increase in number of boreholes, but it generally yields the highest amount of total cost,  
593       which can be explained by the fact that the uncertainty of  $FS$  cannot be effectively reduced  
594       based on the method from poor judgement (see Figure 8). Therefore, the advantage of the  
595       proposed method in risk reduction is sufficiently validated.

596       The estimated accuracy of the characteristics of the slope, robustness of the estimated  
597       results and risk reduction of the proposed method are evaluated in an undrained slope

example. It is suggested to adopt five boreholes ( $N_{BH} = 5$ ) for the slope problem when applying the proposed method, since the overall performance of the slope system can be well evaluated from many perspectives. For instance, when five boreholes are configured in this slope, the “true” influence zone can be estimated with tolerable error, and the risk reduction is maximal. For the robustness analysis, the borehole pattern with  $N_{BH} = 5$  is the second highest cost-effective borehole pattern in Figure 14. Thus,  $N_{BH} = 5$  is considered the optimal number for the proposed method based on the gain-sacrifice relationship between cost and investigation effort.

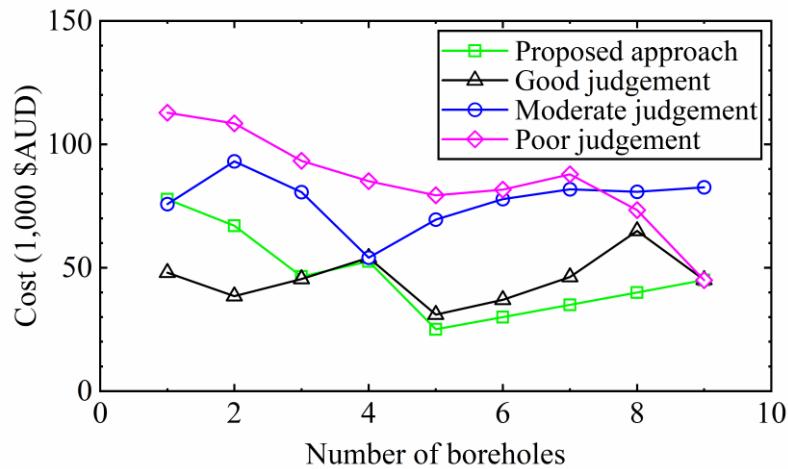


Figure 16. A comparison study of risk assessment of different borehole patterns

## 5. Summary and conclusions

This paper proposed an optimization method for geotechnical site investigation to minimize the risk and associated site investigation effort and maximize the robustness of the slope system. The proposed method can optimize the location and number of boreholes without prior knowledge about the slip surface, which results in adaptive patterns of borehole planning based on the Spearman rank correlation coefficient with unequal space for a given

615 slope site. Compared to the traditional method, the advantages of the proposed method are:

616 1) The location and number of boreholes can be optimized considering the synthesized  
617 system responses (e.g., *FS*, location of slip surface and sliding volume, robustness, and risk)  
618 in the proposed method. The proposed method accurately estimates *FS*, the location of the slip  
619 surface, and the sliding volume if sufficient boreholes are applied.

620 2) The proposed method can similarly reduce the uncertainty of *FS* compared with the  
621 traditional method with good judgement and tends to obtain a more robust site investigation  
622 program than traditional borehole patterns.

623 3) The proposed method minimizes the risk with the optimized number of boreholes.  
624 The effectiveness of this optimized borehole pattern on the estimate of the range of influence  
625 zone and robustness of the slope system can also be reached in this scenario.

626 4) The proposed method is straightforward and easy to implement to automatically  
627 identify the range of the sliding area with unequally spaced borehole patterns, which provides  
628 a reference to build an adaptive unequally spaced borehole pattern without prior knowledge  
629 about the slip surface in practice.

630

### 631 **CRediT authorship contribution statement**

632 **Liang Zhang:** Conceptualization, Methodology, Software, Visualization, Writing –  
633 original draft. **Lei Wang:** Conceptualization, Methodology, Writing – review & editing,  
634 Supervision.

635

### 636 **Declaration of Competing Interest**

637 The authors declare that they have no known competing financial interests or personal

638      relationships that could have appeared to influence the work reported in this paper.

639

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644      Science Foundation.

645

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