



Fast initial conditions for Glauber dynamics

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Abstract

In the study of Markov chain mixing times, analysis has centered on the performance from a worst-case starting state. Here, in the context of Glauber dynamics for the one-dimensional Ising model, we show how new ideas from information percolation can be used to establish mixing times from other starting states. At high temperatures we show that the alternating initial condition is asymptotically the fastest one, and, surprisingly, its mixing time is faster than at infinite temperature, accelerating as the inverse-temperature β ranges from 0 to $\beta_0 = \frac{1}{2} \arctanh(\frac{1}{3})$. Moreover, the dominant test function depends on the temperature: at $\beta < \beta_0$ it is autocorrelation, whereas at $\beta > \beta_0$ it is the Hamiltonian.

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1 Introduction

In the study of mixing time of Markov chains, most of the focus has been on determining the asymptotics of the worst-case mixing time, while relatively little is known about the relative effect of different initial conditions. The latter is quite natural from an algorithmic perspective on sampling, since one would ideally initiate the dynamics from the fastest initial condition. However, until recently, the tools available for analyzing Markov chains on complex systems, such as the Ising model, were insufficient for the purpose of comparing the effect of different starting states; indeed, already pinpointing the asymptotics of the worst-case state for Glauber dynamics for the Ising model can be highly nontrivial.

Dedicated to the memory of Harry Kesten.

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In this paper we compare different initial conditions for the Ising model on the cycle. In earlier work [11], we analyzed three different initial conditions. The all-plus state is provably the worst initial condition up to an additive constant. Another is a quenched random condition chosen from ν , the uniform distribution on configurations, which with high probability has a mixing time which is asymptotically as slow (one could potentially consider the quenched mixing time w.r.t. other distributions, e.g., the Ising distribution π). A third initial condition is an annealed random condition chosen from ν , i.e., to start at time 0 from the uniform distribution, which is asymptotically twice as fast as all-plus.

Here we consider two natural deterministic initial configurations. The first is the alternating sequence

$$x^{\text{alt}}(i) = \begin{cases} 1 & i \equiv 0 \pmod{2} \\ -1 & i \equiv 1 \pmod{2}, \end{cases}$$

which we will show is asymptotically the *fastest* deterministic initial condition—yet strictly slower than starting from the annealed random condition—for all $\beta < \beta_0 := \frac{1}{2} \operatorname{arctanh}(\frac{1}{3})$ (at $\beta = \beta_0$ they match). The second is the bi-alternating sequence

$$x^{\text{blt}}(i) = \begin{cases} 1 & i \equiv 0, 3 \pmod{4} \\ -1 & i \equiv 1, 2 \pmod{4}. \end{cases}$$

For convenience we will assume that n is a multiple of 4, which ensures that the configurations are semi-translation invariant and turns both sequences into eigenvectors of the transition matrix of simple random walk on the cycle. (This is not necessary for the main result but leads to cleaner analysis.)

In what follows, set $\theta = \theta_\beta = 1 - \tanh(2\beta)$, and let $t_{\text{MIX}}^{x_0}(\epsilon)$ denote the time it takes the dynamics to reach total variation distance at most ϵ from stationarity, starting from the initial condition x_0 . For a distribution μ , the mixing time $t_{\text{MIX}}^\mu(\epsilon)$ is the one for the chain with initial state $x_0 \sim \mu$.

Theorem 1 *For every $\beta > 0$ and $0 < \epsilon < 1$ there exist $C(\beta)$ and $N(\beta, \epsilon)$ such that the following hold for Glauber dynamics for the Ising model on the cycle $\mathbb{Z}/n\mathbb{Z}$ at inverse-temperature β for all $n > N$.*

(i) *Alternating initial condition:*

$$\left| t_{\text{MIX}}^{x^{\text{alt}}}(\epsilon) - \max \left\{ \frac{1}{4-2\theta}, \frac{1}{4\theta} \right\} \log n \right| \leq C \log \log n.$$

(ii) *Bi-alternating initial condition:*

$$\left| t_{\text{MIX}}^{x^{\text{blt}}}(\epsilon) - \max \left\{ \frac{1}{2}, \frac{1}{4\theta} \right\} \log n \right| \leq C \log \log n.$$

Surprisingly, the mixing time for the alternating initial condition at small $\beta > 0$ is actually *faster* than the infinite temperature model: it *decreases* as a function of β before increasing when $\beta > \frac{1}{2} \operatorname{arctanh}(\frac{1}{3})$.

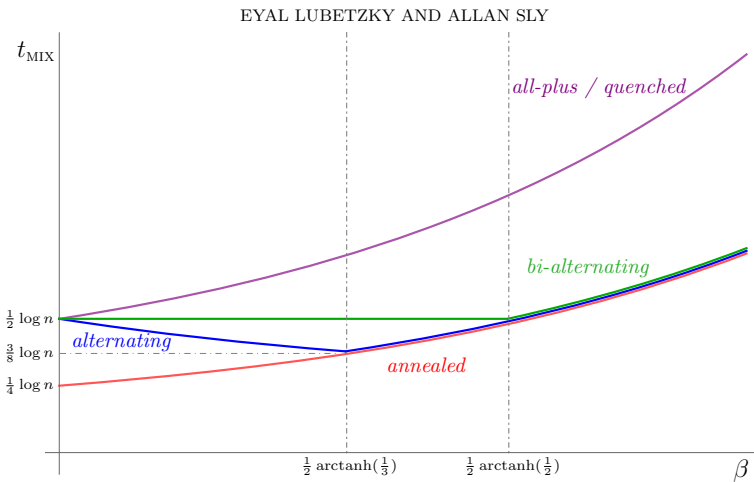


Fig. 1 Asymptotic mixing time from the alternating and bi-alternating initial conditions as per Theorem 1, compared to the known behavior of worst-case (all-plus) and random initial conditions

The following theorem summarizes the bounds we proved in [8,11] for the all-plus and random initial conditions. See Fig. 1 for the relative performance of all these different initial conditions.

Theorem 2 [8,11] *In the same setting of Theorem 1, the following hold.*

(i) *All-plus initial condition $x^+ \equiv 1$:*

$$\left| t_{\text{MIX}}^{x^+}(\epsilon) - \frac{1}{2\theta} \log n \right| \leq C \log \log n.$$

(ii) *Quenched random initial condition:*

$$\nu \left(\left\{ x_0 : \left| t_{\text{MIX}}^{x_0}(\epsilon) - \frac{1}{2\theta} \log n \right| \leq C \log \log n \right\} \right) \rightarrow 1 \text{ as } n \rightarrow \infty.$$

(iii) *Annealed random initial condition:*

$$\left| t_{\text{MIX}}^{\nu}(\epsilon) - \frac{1}{4\theta} \log n \right| \leq C \log \log n. \quad (1.1)$$

(Note that, in the case of the all-plus initial conditions, the mixing time $t_{\text{MIX}}^{x^+}(\epsilon)$ is known in higher precision: it was shown [8,11] to be within an additive constant (depending on ϵ and β) of $\frac{1}{2\theta} \log n$. The quenched mixing time bound also holds when replacing ν by the Ising distribution π ; more generally, if most sites have a modest asymmetry between pluses and minuses in their local neighborhoods then the mixing time is within $O(\log \log n)$ of the worst case one—see [11, Proposition 6.5].)

The upper bounds on the mixing times in Theorem 1 rely on the information percolation framework introduced by the authors in [11]. The asymptotically matching lower bounds in that theorem are derived from two test functions: the Hamiltonian

test function (yielding the bound $\frac{1}{4\theta} \log n$ for both x^{alt} and x^{blt}), which for instance matches our upper bound for x^{alt} whenever $\beta > \beta_0$; and the autocorrelation test function (yielding the bounds $\frac{1}{4-2\theta} \log n$ for x^{alt} and $\frac{1}{2} \log n$ for x^{blt}), which furthermore gives rise to the following lower bound on *every deterministic initial condition*.

Proposition 3 *Let X_t be Glauber dynamics for the Ising model on $\mathbb{Z}/n\mathbb{Z}$ at inverse-temperature β . For every sequence of deterministic initial conditions x_0 , the dynamics at time*

$$t_\star = \frac{1}{4-2\theta} \log n - 8 \log \log n$$

is at total variation distance $1 - o(1)$ from equilibrium; that is,

$$\lim_{n \rightarrow \infty} \inf_{x_0} \left\| \mathbb{P}_{x_0} (X_{t_\star} \in \cdot) - \pi \right\|_{\text{TV}} = 1.$$

As a consequence of this result and Theorem 1, Part (i), we see that the initial condition x^{alt} is indeed the asymptotically optimal *deterministic* one in the range $\beta < \beta_0$, and that β_0 marks the smallest β where a deterministic initial condition can first match the performance of the annealed random condition.

even though it is believed to be widespread (e.g., Peres conjectured [6, Conjecture 1], [7, §23.2] cutoff for the Ising model on any sequence of transitive graphs when the mixing time is of order $\log n$); see [7, §18]. The mixing time estimates in Theorem 1 (as well as those in Theorem 2) imply, in particular, that Glauber dynamics for the Ising model on the cycle, from the respective starting configurations, exhibits the *cutoff phenomenon*—a sharp transition in its distance from stationarity, which drops along a negligible time period known as the *cutoff window* (here, $O(\log \log n)$, vs. t_{MIX} which is of order $\log n$) from near 1 to near 0. Until recently, only relatively few occurrences of this phenomenon, that was discovered by Aldous and Diaconis in the early 1980's (see [1,2,4,5]), were rigorously verified,

For the Ising model on the cycle, the longstanding lower and upper bounds on t_{MIX} from a worst-case initial condition differed by a factor of 2—in our notation, $\frac{1-o(1)}{2\theta} \log n$ and $\frac{1+o(1)}{\theta} \log n$ —while cutoff was conjectured to occur (see, e.g., [7, Theorem 15.4], as well as [7, pp. 214, 248 and Question 8 in p. 300]). This was confirmed in [8], where the above lower bound was shown to be tight, via a proof that relied on log-Sobolev inequalities and applied to \mathbb{Z}^d , for any dimension $d \geq 1$, so long as the system features a certain decay-of-correlation property known as strong spatial mixing. This result was reproduced in [11] (with a finer estimate for the cutoff window) via the new information percolation method. Soon after, a remarkably short proof of cutoff for the cycle—crucially hinging on the correspondence between the one-dimensional Ising model and the “noisy voter” model—was obtained by Cox, Peres and Steif [3]. It is worthwhile noting that the arguments both in [3] and in [8] are tailored to worst-case analysis, and do not seem to be able to treat specific initial conditions as examined here. In contrast, the information percolation approach does allow one to control the subtle effect of various initial conditions on mixing.

To conclude this section, we conjecture that Proposition 3 also holds for $t_\star = \max\{\frac{1-o(1)}{4-2\theta}, \frac{1-o(1)}{4\theta}\} \log n$, i.e., that x^{alt} is asymptotically fastest among all the deter-

ministic initial conditions at all $\beta > 0$. We further conjecture that the obvious generalization of x^{alt} to $(\mathbb{Z}/n\mathbb{Z})^d$ for $d \geq 2$ (a checkerboard for $d = 2$) is the analogous fastest deterministic initial condition throughout the high-temperature regime.

2 Update support and information percolation

In this section we define the update support and use the framework of information percolation (see the papers [9, 12] as well as the survey paper [10] for an exposition of this method) to upper bound the total variation distance with alternating and bi-alternating initial conditions.

2.1 Basic notation

The Ising model on a finite graph G with vertex-set V and edge-set E is a distribution over the set of configurations $\Omega = \{\pm 1\}^V$; each $\sigma \in \Omega$ is an assignment of plus/minus *spins* to the sites in V , and the probability of $\sigma \in \Omega$ is given by the Gibbs distribution

$$\pi(\sigma) = \mathcal{Z}^{-1} e^{\beta \sum_{uv \in E} \sigma(u)\sigma(v)}, \quad (2.1)$$

where \mathcal{Z} is a normalizer (the partition-function) and β is the inverse-temperature, here taken to be non-negative (ferromagnetic). The (continuous-time) heat-bath Glauber dynamics for the Ising model is the Markov chain—reversible w.r.t. the Ising measure π —where the sites are assigned i.i.d. rate-1 Poisson clocks, and as the clock at some site u rings, the spin of u is replaced by a sample from the marginal of π given all other spins. See [13] for an extensive account of this dynamics. In this paper we focus on the graph $G = \mathbb{Z}/n\mathbb{Z}$ and will let X_t denote the Glauber dynamics Markov chain on G .

An important notion of measuring the convergence of a Markov chain (X_t) to its stationarity measure π is its total-variation mixing time, denoted $t_{\text{MIX}}(\epsilon)$ for a precision parameter $0 < \epsilon < 1$. From initial condition x_0 we denote

$$t_{\text{MIX}}^{x_0}(\epsilon) = \inf \{t : \|\mathbb{P}_{x_0}(X_t \in \cdot) - \pi\|_{\text{TV}} \leq \epsilon\},$$

and the overall mixing time as measured from a worst-case initial condition is

$$t_{\text{MIX}}(\epsilon) = \max_{x_0 \in \Omega} t_{\text{MIX}}^{x_0}(\epsilon),$$

where here and in what follows \mathbb{P}_{x_0} denotes the probability given $X_0 = x_0$, and the total-variation distance $\|\mu_1 - \mu_2\|_{\text{TV}}$ is defined as $\max_{A \subseteq \Omega} |\mu_1(A) - \mu_2(A)| = \frac{1}{2} \sum_{\sigma \in \Omega} |\mu_1(\sigma) - \mu_2(\sigma)|$.

2.2 Information percolation clusters

The dynamics can be viewed as a deterministic function of X_0 and a random “update sequence” of the form $(J_1, U_1, t_1), (J_2, U_2, t_2), \dots$, where $0 < t_1 < t_2 < \dots$ are the update times (the ringing of the Poisson clocks), the J_i ’s are i.i.d. uniformly chosen sites (which clocks ring), and the U_i ’s are i.i.d. uniform variables on $[0, 1]$ (to generate coin tosses). There is a variety of ways to encode such updates but in the case of the one-dimensional model there is a particularly useful one. We add an extra variable S_i which is a randomly selected neighbor of J_i . Then, given the sequence of (J_i, S_i, U_i, t_i) , the updates are processed sequentially as follows: set $t_0 = 0$; the configuration X_t for all $t \in [t_{i-1}, t_i)$ ($i \geq 1$) is obtained by updating the site J_i via the unit variable as follows: if $U_i \leq \theta = 1 - \tanh(2\beta)$ update the spin at J_i to a uniformly random value and with probability $1 - \theta$ set it to the spin of S_i .

With this description of the dynamics, we can work backwards to describe how the configurations at a designated time t_* (or at any intermediate time) depend on the initial condition. The *update support function*, denoted $\mathcal{F}_s(A, s_1, s_2)$, as introduced in [8], is the random set whose value is the minimal subset of Λ which determines the spins of A given the update sequence along the interval $(s_1, s_2]$.

We now describe the support of a vertex $v \in V$ as it evolves backwards in time from s_2 to s_1 . Initially, $\mathcal{F}_s(v, s_2, s_2) = \{v\}$; then, updates in reverse chronological order alter the support: given the next update (J_i, S_i, U_i, t_i) , if $J_i = \mathcal{F}_s(v, t_{i+1}, s_2)$ and $U_i \leq \theta$ then $\mathcal{F}_s(v, t_i, s_2)$ is set to \emptyset , and if $U_i > \theta$ then it is set to S_i . Thus, backwards in time $\mathcal{F}_s(v, t, s_2)$ performs a continuous-time simple random walk with jump rate $1 - \theta$ which is killed at rate θ . We refer to the full trajectory of the update support of a vertex as the *history* of the vertex. The survival time for a walk is exponential and so for $t_1 \leq t_2$,

$$\mathbb{P}(\mathcal{F}_s(v, t_1, t_2) \neq \emptyset) = e^{-(t_2 - t_1)\theta}. \quad (2.2)$$

For general sets A we have that $\mathcal{F}_s(A, s_1, s_2) = \bigcup_{v \in A} \mathcal{F}_s(v, s_1, s_2)$ and taken together the collection of the update supports of the vertices are a set of coalescing killed continuous-time random walks.

A key use of these histories is to effectively bound the spread of information, as achieved by the following lemma.

Lemma 2.1 *For any t we have that*

$$\mathbb{P}\left(\max_{v \in \mathbb{Z}/n\mathbb{Z}} \max_{\substack{0 \leq s \leq t \\ \mathcal{F}_s(v, s, t) \neq \emptyset}} |v - \mathcal{F}_s(v, s, t)| \geq \frac{1}{10} \log^2 n\right) \leq O(n^{-10}).$$

Proof For all $t \geq \log^{3/2} n$, Eq. (2.2) implies that $\mathbb{P}(\mathcal{F}_s(\mathbb{Z}/n\mathbb{Z}, t - \log^{3/2} n, t) \neq \emptyset) = O(n^{-10})$; thus, it is sufficient to show that

$$\mathbb{P}\left(\max_{\substack{0 \vee (t - \log^{3/2} n) \leq s \leq t \\ \mathcal{F}_s(v, s, t) \neq \emptyset}} |v - \mathcal{F}_s(v, s, t)| \geq \frac{1}{10} \log^2 n\right) \leq O(n^{-11}).$$

This last probability is bounded above by the probability of a rate $1 - \theta$ continuous-time random walk to make at least $\frac{1}{10} \log^2 n$ jumps by time $\log^{3/2} n$. This is exactly the probability that a Poisson with mean $(1 - \theta) \log^{3/2} n$ is at least $\frac{1}{10} \log^2 n$, which satisfies the required bound by standard tail bounds. \square

3 Upper bounds

We will consider the dynamics run up to time t_* and derive an upper bound on its mixing time. We will first estimate the total variation distance not of the full dynamics but simply at a single vertex from initial conditions x^{alt} and x^{blt} . Throughout the section, we will assume that n is large enough.

Lemma 3.1 *For $v \in \mathbb{Z}/n\mathbb{Z}$ we have that,*

$$\begin{aligned}\|\mathbb{P}_{x^{\text{alt}}}(X_{t_*}(v) \in \cdot) - \pi|_v\|_{\text{TV}} &= \frac{1}{2}e^{-(2-\theta)t_*}, \\ \|\mathbb{P}_{x^{\text{blt}}}(X_{t_*}(v) \in \cdot) - \pi|_v\|_{\text{TV}} &= \frac{1}{2}e^{-t_*}.\end{aligned}$$

Proof We will begin with the case of initial condition x^{alt} . Of course $\pi|_v$ is the uniform measure on $\{\pm 1\}$. The history $\mathcal{F}_S(v, t, t_*)$ is killed before time 0 with probability $1 - e^{-\theta t_*}$ and on this event $X_{t_*}(v)$ is uniform on $\{\pm 1\}$. Condition that it survives to time 0 and let $Y(s) = x^{\text{alt}}(\mathcal{F}_S(v, t_* - s, t_*))$. This is simply a continuous-time random walk on $\{\pm 1\}$ which switches state at rate $1 - \theta$. Thus,

$$\mathbb{P}(Y(s) = a) = \begin{cases} \frac{1}{2} + \frac{1}{2}e^{-2(1-\theta)s} & \text{if } a = x^{\text{alt}}(v), \\ \frac{1}{2} - \frac{1}{2}e^{-2(1-\theta)s} & \text{otherwise.} \end{cases}$$

It therefore follows that $\|\mathbb{P}(Y(t_*) \in \cdot) - \pi|_v\|_{\text{TV}} = \frac{1}{2}e^{-2(1-\theta)t_*}$, and altogether,

$$\|\mathbb{P}_{x^{\text{alt}}}(X_{t_*}(v) \in \cdot) - \pi|_v\|_{\text{TV}} = \frac{1}{2}e^{-2(1-\theta)t_*}e^{-\theta t_*} = \frac{1}{2}e^{-(2-\theta)t_*}.$$

The case of x^{blt} follows similarly, with the exception that $Y(s)$ has jump rate $\frac{1}{2}(1 - \theta)$ since it only switches sign with probability $\frac{1}{2}$ each step. \square

3.1 Update support

In this subsection we analyze the geometry of the update support similarly to [8] in order to approximate the Markov chain as a product measure. Let $\kappa = \frac{4}{\theta}$ and define the support time as $t_- = t_* - \kappa \log \log n$. By Lemma 2.1 we expect the histories to not travel “too far” along the time-interval t_* to t_- ; precisely, if we define \mathcal{B} as the event

$$\mathcal{B} = \left\{ \max_{v \in \mathbb{Z}/n\mathbb{Z}} \max_{\substack{t_- \leq s \leq t_* \\ \mathcal{F}_S(v, s, t_*) \neq \emptyset}} |v - \mathcal{F}_S(v, s, t_*)| \leq \frac{1}{10} \log^2 n \right\},$$

then by Lemma 2.1,

$$\mathbb{P}(\mathcal{B}) \geq 1 - n^{-10}. \quad (3.1)$$

The following event says that the support at time t_- clusters into small well separated components. Let \mathcal{A} be the event that there exists a set of intervals $W_1, \dots, W_m \subset \mathbb{Z}/n\mathbb{Z}$ that (i) cover the support:

$$\{x : \mathcal{F}_s(x, t_-, t_*) \neq \emptyset\} \subset \bigcup_i W_i; \quad (3.2)$$

(ii) have logarithmic size:

$$W_i \leq \log^3 n \quad \text{for every } i; \quad (3.3)$$

and (iii) are well-separated:

$$d(W_i, W_{i'}) \geq \log^2 n \quad \text{for every distinct } i, i'. \quad (3.4)$$

Lemma 3.2 *We have that $\mathbb{P}(\mathcal{A}) \geq 1 - O(n^{-9})$.*

Proof Define the following intervals on $\mathbb{Z}/n\mathbb{Z}$:

$$M_i = \{2i \log^2 n, \dots, (2i + 1) \log^2 n\} \quad \text{for } i \in I := \{1, \dots, \lfloor \frac{n}{2 \log^2 n} \rfloor\}.$$

Restricting \mathcal{B} to $\bigcup M_i$, we let

$$\mathcal{B}' = \left\{ \max_{v \in \bigcup_i M_i} \max_{\substack{t_- \leq s \leq t_* \\ \mathcal{F}_s(v, s, t_*) \neq \emptyset}} |v - \mathcal{F}_s(v, s, t_*)| \leq \frac{1}{10} \log^2 n \right\}.$$

Since $\mathcal{B}' \supset \mathcal{B}$ we have that $\mathbb{P}(\mathcal{B}') \geq 1 - n^{-10}$ by (3.1). Next, let \mathcal{D}_i be the event

$$\mathcal{D}_i = \{\mathcal{F}_s(M_i, t_-, t_*) = \emptyset\}.$$

By a union bound and Eq. (2.2), we have that

$$\mathbb{P}(\mathcal{D}_i^c) \leq |M_i| e^{-\theta \kappa \log \log n} \leq \frac{1}{\log^2 n},$$

and so

$$\mathbb{P}(\mathcal{D}_i^c \mid \mathcal{B}') \leq \frac{\mathbb{P}(\mathcal{D}_i^c)}{\mathbb{P}(\mathcal{B}')} \leq \frac{2}{\log^2 n}.$$

Moreover, conditional on \mathcal{B}' the events \mathcal{D}_i are conditionally independent since the history of M_i is determined by the updates within the set $\{v : d(v, M_i) \leq \frac{1}{10} \log^2 n\}$

which are disjoint. So, for all $i \in I$,

$$\mathbb{P}\left(\mathcal{D}_i^c, \mathcal{D}_{i+1}^c, \dots, \mathcal{D}_{i+\frac{1}{10}\log n}^c \mid \mathcal{B}'\right) \leq \left(\frac{2}{\log^2 n}\right)^{\frac{1}{10}\log n} = n^{-(\frac{1}{5}-o(1))\log \log n} \leq n^{-10},$$

hence,

$$\begin{aligned} \mathbb{P}\left(\mathcal{D}_i^c, \mathcal{D}_{i+1}^c, \dots, \mathcal{D}_{i+\frac{1}{10}\log n}^c\right) &\leq \mathbb{P}\left(\mathcal{D}_i^c, \mathcal{D}_{i+1}^c, \dots, \mathcal{D}_{i+\frac{1}{10}\log n}^c \mid \mathcal{B}'\right) \\ &\quad + \mathbb{P}(\mathcal{B}'^c) \leq 2n^{-10}. \end{aligned}$$

Taking a union bound over all $i \in I$ we have that

$$\mathbb{P}\left(\exists i : \mathcal{D}_i^c, \mathcal{D}_{i+1}^c, \dots, \mathcal{D}_{i+\frac{1}{10}\log n}^c\right) \leq n^{-9}.$$

We have thus arrived at the following: with probability at least $1 - n^{-9}$, for every $v \in \mathbb{Z}/n\mathbb{Z}$ there exists a block of $\log^2 n$ consecutive vertices whose histories are killed before t_- within distance $\frac{1}{5}\log^3 n$ on both the right and the left, implying the existence of the decomposition and completing the lemma. \square

When the event \mathcal{A} holds we will want to refer to one concrete such cover; to this end, we will refer to the canonical choice of the W_i 's obtained by letting X be the set of all points x appearing in the left-hand of (3.2) and letting the W_i 's be the complements of all intervals of length at least $\log^2 n$ in X^c (which amounts to placing any two $x, x' \in X$ with $|x - x'| \leq \log^2 n$ in the same interval W_i).

We set

$$V_i = \mathcal{F}_s(W_i, t_-, t_\star). \quad (3.5)$$

On the event that both \mathcal{A} and \mathcal{B} hold, the sets V_i are disjoint, and satisfy

$$\min_{i,i'} d(V_i, V_{i'}) \geq \frac{1}{2} \log^2 n \quad \text{and} \quad \max_i \text{diam}(V_i) \leq 2 \log^3 n. \quad (3.6)$$

We will make use of Lemma 3.3 from [9], a special case of which is the following.

Lemma 3.3 [9] *For every x_0 , every $0 \leq s \leq t$ and every set of vertices Γ , we have that*

$$\left\| \mathbb{P}_{x_0}(X_t(\Gamma) \in \cdot) - \pi|_{\Gamma} \right\|_{\text{TV}} \leq \mathbb{E} \left[\left\| \mathbb{P}_{x_0}(X_s(\mathcal{F}_s(\Gamma, s, t)) \in \cdot) - \pi|_{\mathcal{F}_s(\Gamma, s, t)} \right\|_{\text{TV}} \right].$$

Using this result with $\Gamma = \mathbb{Z}/n\mathbb{Z}$, combined with the definition (3.5), we have that

$$\left\| \mathbb{P}_{x_0}(X_{t_\star} \in \cdot) - \pi \right\|_{\text{TV}} \leq \mathbb{E} \left[\left\| \mathbb{P}_{x_0} \left(X_{t_-} \left(\bigcup_i V_i \right) \in \cdot \right) - \pi|_{\bigcup_i V_i} \right\|_{\text{TV}} \right].$$

We stress that the sets V_i are measurable w.r.t. the sequence of updates along the time interval (t_-, t_*) (as were the W_i 's that these address), and in particular are independent of the updates at times $t \leq t_-$.

3.2 Coupling with product measures

On the event $\mathcal{A} \cap \mathcal{B}$ we couple $X_{t_-}(\bigcup_i V_i)$ and $\pi|_{\bigcup_i V_i}$ with product measures. Since the V_i 's depend only on the updates along the interval $[t_-, t_*]$ and are independent of the dynamics up to time t_- we will treat the V_i as fixed deterministic sets satisfying (3.6). Let $(\pi^{(1)}, \dots, \pi^{(m)})$ be a product measure of m copies of π . Then, by the exponential decay of correlation of the one-dimensional Ising model,

$$\left\| (\pi^{(1)}|_{V_1}, \dots, \pi^{(m)}|_{V_m}) - \pi|_{\bigcup_i V_i} \right\|_{\text{TV}} \leq n^{-10}. \quad (3.7)$$

Next, let $X_t^{(1)}, \dots, X_t^{(m)}$ be m independent copies of the dynamics up to time t_- . Define the event

$$\mathcal{E} = \left\{ \max_{v \in \bigcup_i V_i} \max_{\substack{0 \leq s \leq t_- \\ \mathcal{F}_s(v, s, t_-) \neq \emptyset}} |v - \mathcal{F}_s(v, s, t_-)| \leq \frac{1}{10} \log^2 n \right\},$$

and for each $1 \leq j \leq m$ define the analogous event

$$\mathcal{E}^{(j)} = \left\{ \max_{v \in \bigcup_i V_i} \max_{\substack{0 \leq s \leq t_- \\ \mathcal{F}_s^{(j)}(v, s, t_-) \neq \emptyset}} |v - \mathcal{F}_s^{(j)}(v, s, t_-)| \leq \frac{1}{10} \log^2 n \right\},$$

where $\mathcal{F}_s^{(j)}$ is the support function for the dynamics $X_t^{(j)}$. From Lemma 2.1, together with a union bound, we infer that

$$\mathbb{P}(\mathcal{E}) = \mathbb{P}(\mathcal{E}^{(j)}) \geq 1 - O(n^{-10}). \quad (3.8)$$

Let \tilde{X}_t denote X_t conditioned on \mathcal{E} and, similarly, let $\tilde{X}_t^{(j)}$ denote $X_t^{(j)}$ conditioned on $\mathcal{E}^{(j)}$. Then

$$\left\| \mathbb{P}(\tilde{X}_{t_-}^{(j)}(V_j) \in \cdot) - \mathbb{P}(X_{t_-}^{(j)}(V_j) \in \cdot) \right\|_{\text{TV}} \leq \mathbb{P}(\mathcal{E}^{(j)}) \leq n^{-10},$$

and so

$$\left\| \mathbb{P}\left((\tilde{X}_{t_-}^{(1)}(V_1), \dots, \tilde{X}_{t_-}^{(m)}(V_m)) \in \cdot\right) - \mathbb{P}\left((X_{t_-}^{(1)}(V_1), \dots, X_{t_-}^{(m)}(V_m)) \in \cdot\right) \right\|_{\text{TV}} \leq n^{-9}.$$

Now, since the laws of the $\tilde{X}_{t_-}(V_i)$ for distinct i depend on disjoint sets of updates, they are independent and equal in distribution to $\tilde{X}_{t_-}^{(i)}(V_i)$, hence

$$(\tilde{X}_{t_-}^{(1)}(V_1), \dots, \tilde{X}_{t_-}^{(m)}(V_m)) \stackrel{d}{=} (\tilde{X}_{t_-}(V_1), \dots, \tilde{X}_{t_-}(V_m)).$$

Since \tilde{X} is X conditioned on \mathcal{E} ,

$$\begin{aligned} & \left\| \mathbb{P} \left((\tilde{X}_{t_-}(V_1), \dots, \tilde{X}_{t_-}(V_m)) \in \cdot \right) - \mathbb{P} \left((X_{t_-}(V_1), \dots, X_{t_-}(V_m)) \in \cdot \right) \right\|_{\text{TV}} \\ & \leq \mathbb{P}(\mathcal{E}) \leq n^{-10}. \end{aligned}$$

Combining the previous three equations we find that

$$\left\| \mathbb{P} \left((X_{t_-}^{(1)}(V_1), \dots, X_{t_-}^{(m)}(V_m)) \in \cdot \right) - \mathbb{P} \left((X_{t_-}(V_1), \dots, X_{t_-}(V_m)) \in \cdot \right) \right\|_{\text{TV}} \leq 2n^{-9}. \quad (3.9)$$

Thus, to show that $\|\mathbb{P}_{x_0}(X_{t_*} \in \cdot) - \pi\|_{\text{TV}} \rightarrow 0$ it is sufficient to prove that

$$\left\| \mathbb{P} \left((X_{t_-}^{(1)}(V_1), \dots, X_{t_-}^{(m)}(V_m)) \in \cdot \right) - (\pi^{(1)}|_{V_1}, \dots, \pi^{(m)}|_{V_m}) \right\|_{\text{TV}} \rightarrow 0. \quad (3.10)$$

3.3 Local L^2 distance

Let $L = 10$, and for each i set

$$S_i = \inf \{s : |\mathcal{F}_s(V_i, t_- - s, t_-)| \leq L\},$$

with $S_i = 0$ if $|V_i| \leq L$.

First we bound the right tail of the distribution of S_i . If $|\mathcal{F}_s(V_i, t_- - s, t_-)| > L$ then at least $L + 1$ histories from V_i have survived to time $t_- - s$ and not intersected. Hence, by Eq. (2.2),

$$\mathbb{P}(|\mathcal{F}_s(V_i, t_- - s, t_-)| > 10) \leq \binom{|V_i|}{L+1} e^{-(L+1)s\theta} \leq e^{-(L+1)s\theta} \log^{3(L+1)} n.$$

Therefore, for $0 < s < t_-$ we see that

$$\mathbb{P}(S_i \geq s) \leq e^{-s(L+1)\theta} \log^{3(L+1)} n. \quad (3.11)$$

Let \mathcal{I} denote the event that for all i we have that $S_i < t_-$. By (3.11),

$$\mathbb{P}(\mathcal{I}) \leq e^{-(L+1)\theta t_-} n \log^{3(L+1)} n, \quad (3.12)$$

and so $t_* \geq \frac{2}{L\theta} \log n$ implies that $\mathbb{P}(\mathcal{I}) \rightarrow 1$. On the event \mathcal{I} , we define

$$U_i = \mathcal{F}_s(V_i, t_- - S_i, t_-).$$

Applying Lemma 3.3 we have that

$$\begin{aligned} & \left\| \mathbb{P} \left((X_{t_-}^{(1)}(V_1), \dots, X_{t_-}^{(m)}(V_m)) \in \cdot \right) - (\pi^{(1)}|_{V_1}, \dots, \pi^{(m)}|_{V_m}) \right\|_{\text{TV}} \\ & \leq \left\| \mathbb{P} \left((X_{t_- - S_1}^{(1)}(U_1), \dots, X_{t_- - S_m}^{(m)}(V_m)) \in \cdot \right) - (\pi^{(1)}|_{U_1}, \dots, \pi^{(m)}|_{U_m}) \right\|_{\text{TV}}. \end{aligned} \quad (3.13)$$

Lemma 3.4 *There exists $C = C(\beta) > 0$ such that, for every $|U_i| \leq L$ and $0 \leq S_i < t_-$,*

$$\begin{aligned} & \left\| \mathbb{P}_{x_0} \left((X_{t_- - S_i}^{(i)}(U_i) \in \cdot \mid U_i, S_i) - \pi^{(i)}|_{U_i} \right\|_{\text{TV}} \\ & \leq \begin{cases} C t_- \exp[-(t_- - S_i) \min\{2\theta, 2 - \theta\}] & x_0 = x^{\text{alt}}, \\ C t_- \exp[-(t_- - S_i) \min\{2\theta, 1\}] & x_0 = x^{\text{blt}}. \end{cases} \end{aligned}$$

Proof We will consider the case of x^{alt} , the proof for x^{blt} follows similarly. Let R_i denote the first time the history coalesces to a single point:

$$R_i = \inf \{r : |\mathcal{F}_S(U_i, t_- - S_i - r, t_- - S_i)| \leq 1\},$$

with the convention $R_i = t_- - S_i$ if $|\mathcal{F}_S(U_i, 0, t_- - S_i)| \geq 2$. By Eq. (2.2),

$$\mathbb{P}(R_i > r \mid U_i, S_i) \leq \binom{L}{2} e^{-2r\theta}.$$

Denote the vertex $a_i = \mathcal{F}_S(U_i, t_- - S_i - R_i, t_- - S_i)$. By Lemmas 3.1 and 3.3 we have that

$$\begin{aligned} & \left\| \mathbb{P} \left(X_{t_- - S_i}^{(i)}(U_i) \in \cdot \mid U_i, S_i \right) - \pi^{(i)}|_{U_i} \right\|_{\text{TV}} \\ & \leq \mathbb{E} \left[\left\| \mathbb{P} \left(X_{t_- - S_i - R_i}^{(i)}(a_i) \in \cdot \mid U_i, S_i \right) - \pi^{(i)}|_{a_i} \right\|_{\text{TV}} \mid U_i, S_i \right] \\ & \leq \mathbb{E} \left[e^{-(2-\theta)(t_- - S_i - R_i)} \mid U_i, S_i \right]. \end{aligned} \quad (3.14)$$

We estimate the right hand side as follows:

$$\begin{aligned} \mathbb{E} \left[e^{-(2-\theta)(t_- - S_i - R_i)} \mid U_i, S_i \right] & \leq \sum_{k=1}^{\lceil t_- - S_i \rceil} \mathbb{P}(R_i \in (k-1, k)) e^{-(2-\theta)(t_- - S_i - k)} \\ & \leq \sum_{k=1}^{\lceil t_- - S_i \rceil} \binom{L}{2} e^{-2(k-1)\theta} e^{-(2-\theta)(t_- - S_i - k)} \\ & \leq C t_- e^{-(t_- - S_i) \min\{2\theta, 2 - \theta\}}, \end{aligned} \quad (3.15)$$

where the final inequality follows by taking the maximal term in the sum. This, together with (3.14), completes the proof of the lemma. \square

We now appeal to the L^1 -to- L^2 reduction developed in [8,9]. Recall that the L^2 -distance on measures is defined as

$$\|\mu - \pi\|_{L^2(\pi)} = \left(\sum_x \left| \frac{\mu(x)}{\pi(x)} - 1 \right|^2 \pi(x) \right)^{1/2},$$

and set

$$\mathfrak{M}_t = \sum_{i=1}^m \left\| \mathbb{P}_{x_0}[(X_{t-S_i}^{(i)}(U_i) \in \cdot \mid U_i, S_i] - \pi^{(i)}|_{U_i}] \right\|_{L^2(\pi^{(i)}|_{U_i})}^2. \quad (3.16)$$

By [9, Proposition 7],

$$\left\| \mathbb{P} \left((X_{t-S_1}^{(1)}(U_1), \dots, X_{t-S_m}^{(m)}(V_m)) \in \cdot \right) - (\pi^{(1)}|_{U_1}, \dots, \pi^{(m)}|_{U_m}) \right\|_{\text{TV}} \leq \sqrt{\mathfrak{M}_t}. \quad (3.17)$$

We are now ready to prove the upper bound for the main theorem.

Proof of Theorem 1, Upper bound Again we focus on the case of x^{alt} . Set

$$t_\star = \frac{1}{(4-2\theta) \wedge 4\theta} \log n + \left(\kappa + \frac{3L+6}{(4-2\theta) \wedge 4\theta} \right) \log \log n.$$

With this choice of t_\star we have that $\mathbb{P}(\mathcal{I}^c) \rightarrow 0$ and so, by Eqs. (3.10), (3.13) and (3.17), it is sufficient to show that

$$\mathbb{E}[\mathfrak{M}_t \mathbb{1}_{\mathcal{I}}] \rightarrow 0. \quad (3.18)$$

Since each vertex is either plus or minus with probability that is uniformly bounded below by $\frac{e^{-2\beta}}{e^{-2\beta} + e^{2\beta}}$, given any choice of conditioning on the other vertices, we have that

$$\min_{U_i} \min_{x \in \{\pm 1\}^{U_i}} \pi|_{U_i}(x) \geq \left(\frac{e^{-2\beta}}{e^{-2\beta} + e^{2\beta}} \right)^L.$$

Comparing the L^1 and L^2 bounds we have that for any measures μ and set U_i ,

$$\begin{aligned} \|\mu|_{U_i} - \pi|_{U_i}\|_{L^2(\pi|_{U_i})}^2 &= \sum_x \frac{1}{\pi|_{U_i}(x)} \left| \mu|_{U_i}(x) - \pi|_{U_i}(x) \right|^2 \\ &\leq 2^L \left(\frac{e^{-2\beta} + e^{2\beta}}{e^{-2\beta}} \right)^L \max_{x \in \{\pm 1\}^{U_i}} \left| \mu|_{U_i}(x) - \pi|_{U_i}(x) \right|^2 \\ &\leq 2^L \left(\frac{e^{-2\beta} + e^{2\beta}}{e^{-2\beta}} \right)^L \|\mu|_{U_i} - \pi|_{U_i}\|_{\text{TV}}^2. \end{aligned}$$

Thus, by Lemma 3.4,

$$\begin{aligned} \mathbb{E}[\mathfrak{M}_t \mathbb{1}_{\mathcal{I}}] &\leq \mathbb{E}\left[2^L \left(\frac{e^{-2\beta} + e^{2\beta}}{e^{-2\beta}}\right)^L \sum_{i=1}^m \left\| \mathbb{P}_{x_0}[(X_{t-S_i}^{(i)}(U_i) \in \cdot \mid U_i, S_i] - \pi^{(i)}|_{U_i}] \right\|_{\text{TV}}^2 \right] \\ &\leq 2^L \left(\frac{e^{-2\beta} + e^{2\beta}}{e^{-2\beta}}\right)^L n \mathbb{E}\left[\left(C t_- e^{-(t_- - S_i) \min\{2\theta, 2-\theta\}}\right)^2\right] \\ &\leq C'(\beta) e^{-t_- \min\{4\theta, 4-2\theta\}} n \log^2 n \mathbb{E}\left[e^{\min\{4\theta, 4-2\theta\} S_i}\right] \\ &= C'(\beta) (\log n)^{-(3L+4)} \mathbb{E}\left[e^{\min\{4\theta, 4-2\theta\} S_i}\right], \end{aligned}$$

for some $C'(\beta)$. Finally, by Eq. (3.11)

$$\begin{aligned} \mathbb{E}\left[e^{\min\{4\theta, 4-2\theta\} S_i}\right] &\leq \sum_{k=1}^{\infty} e^{\min\{4\theta, 4-2\theta\} k} \mathbb{P}(S_i \in (k-1, k)) \\ &\leq \sum_{k=1}^{\infty} e^{\min\{4\theta, 4-2\theta\} k} e^{-(k-1)(L+1)\theta} \log^{3(L+1)} n = O(\log^{3L+3} n). \end{aligned}$$

Combining the previous two inequalities implies that $\mathbb{E}\mathfrak{M}_t \mathbb{1}_{\mathcal{I}} \rightarrow 0$ and hence we have that

$$\left\| \mathbb{P}_{x^{\text{alt}}}(X_{t_*} \in \cdot) - \pi \right\|_{\text{TV}} \rightarrow 0,$$

as required. The proof for x^{blt} follows similarly for the choice of

$$t_* = \frac{1}{2 \wedge 4\theta} \log n + \left(\kappa + \frac{3L+6}{2 \wedge 4\theta}\right) \log \log n.$$

□

4 Lower bounds

In order to establish the lower bound we will analyze two separate test functions. First, in order to analyze our test functions, we establish the following decay of correlation bound.

Lemma 4.1 *Let $V_1, V_2 \subset \mathbb{Z}/n\mathbb{Z}$ such that $d(V_1, V_2) \geq \log^2 n$ and let $f_i : \{\pm 1\}^{V_i} \rightarrow \mathbb{R}$ be functions with $\|f_i\|_{\infty} \leq 1$. Then for any initial condition x_0 and time t we have that*

$$\text{Cov}_{x_0}(f_1(X_t(V_1)), f_2(X_t(V_2))) = O(n^{-5}).$$

Proof We will prove the result by showing that $Y_i = f_i(X_t(V_i))$ can be approximated locally. Let $V_i^+ = \{v : d(v, V_i) \leq \frac{1}{10} \log^2 n\}$ and so the V_i^+ are disjoint. Let \mathcal{J}_i denote

the sigma-algebra of generated by updates in V_i^+ and set $\widehat{Y}_i = \mathbb{E}_{x_0}[Y_i \mid \mathcal{I}_i]$. Since the V_i^+ are disjoint the \widehat{Y}_i depend on independent updates and so are independent. Let

$$\mathcal{G} = \left\{ \max_{\substack{0 \leq s \leq t \\ \mathcal{F}_s(v, s, t) \neq \emptyset}} |v - \mathcal{F}_s(v, s, t)| \geq \frac{1}{10} \log^2 n \right\}$$

be the event in Lemma 2.1. On the event \mathcal{G} , the random variables Y_i are completely determined by the initial condition and the updates in V_i^+ and so $Y_i I(\mathcal{G}) = \widehat{Y}_i I(\mathcal{G})$. Thus,

$$|\mathbb{E}_{x_0}[Y_1 Y_2] - \mathbb{E}[\widehat{Y}_1 \widehat{Y}_2]| \leq \mathbb{E}_{x_0}[2I(\mathcal{G}^c)] = O(n^{-10}).$$

and hence

$$\text{Cov}_{x_0}(Y_1, Y_2) = \text{Cov}_{x_0}(Y_1, Y_2) - \text{Cov}_{x_0}(\widehat{Y}_1, \widehat{Y}_2) = O(n^{-10}),$$

which completes the proof. \square

Since the above bound is uniform in t by taking t to infinity we get the result for X given by the stationary measure as well.

4.1 Autocorrelation test functions

The magnetization test function achieves, at least up to an additive constant, the mixing time from the all-plus initial condition, which is asymptotically the worst-case (see [11]). In this light it is natural to consider test functions for x^{alt} and x^{blt} based on the autocorrelation, $\sum_{i=1}^n X_t(i)x_0(i)$. This can be seen as a special case of a test function based on conditional expectations,

$$R_{x_0, t}(X) = \sum_{i=1}^n X(i) \mathbb{E}_{x_0}[X_t(i)].$$

Because of the special structure of the histories as a killed random walk the expectation has the following useful representation. Let P_t be the semigroup of a continuous-time rate-1 simple random walk on $\mathbb{Z}/n\mathbb{Z}$. Then by the killed random walk representation we have that

$$\mathbb{E}_{x_0}[X_t(i)] = e^{-\theta t} (P_{(1-\theta)t} x_0)(i)$$

The eigenvectors of P_t are $e^{2\pi i k x/n}$ with eigenvalues $1 - \cos(2\pi k/n)$ for $k \in \{0, \dots, n-1\}$. Since the simple random walk is reversible with uniform stationary distribution we can write an orthonormal basis of real eigenvectors η_k with eigenvalues λ_k . Note that both x^{alt} and x^{blt} are eigenvectors of P_t with eigenvalues 2 and 1 respectively and in fact 2 is the largest eigenvalue. We first give a condition for the chain to *not* be sufficiently mixed starting from x_0 .

Lemma 4.2 *If for a sequence of initial conditions x_0 and time points t we have*

$$\lim_{n \rightarrow \infty} \frac{e^{2\theta t} \log^3 n}{\|P_{(1-\theta)t} x_0\|_2} = 0,$$

then

$$\lim_{n \rightarrow \infty} \|\mathbb{P}_{x_0}(X_t \in \cdot) - \pi\|_{\text{TV}} = 1.$$

Proof Let Y be distributed according to the stationary distribution. Then by symmetry,

$$\mathbb{E}[R_{x_0,t}(Y)] = 0,$$

while

$$\mathbb{E}_{x_0}[R_{x_0,t}(X_t)] = \sum_{i=1}^n (\mathbb{E}_{x_0}[X_t(i)])^2 = e^{-2t\theta} \|P_{(1-\theta)t} x_0\|_2^2.$$

To estimate the variance, observe that

$$\begin{aligned} \text{Var}_{x_0}(R_{x_0,t}(X_t)) &= \sum_{i=1}^n \sum_{j=-n/2+1}^{n/2} \text{Cov}(X_t(i) \mathbb{E}_{x_0}[X_t(i)], X_t(i+j) \mathbb{E}_{x_0}[X_t(i+j)]) \\ &\leq e^{-2t\theta} \sum_{j=-n/2+1}^{n/2} \sum_{i=1}^n |(P_{(1-\theta)t} x_0)(i)| \\ &\quad |(P_{(1-\theta)t} x_0)(i+j)| |\text{Cov}(X_t(i), X_t(i+k))|. \end{aligned}$$

By Lemma 4.1, this is at most

$$\begin{aligned} &e^{-2t\theta} \sum_{j=-\log^2 n}^{\log^2 n} \sum_{i=1}^n |(P_{(1-\theta)t} x_0)(i)| |(P_{(1-\theta)t} x_0)(i+j)| \\ &\quad + O(n^{-10}) e^{-2t\theta} \sum_{j=-n/2+1}^{n/2} \sum_{i=1}^n |(P_{(1-\theta)t} x_0)(i)| |(P_{(1-\theta)t} x_0)(i+j)| \\ &\leq O(\log^2 n) e^{-2t\theta} \|P_{(1-\theta)t} x_0\|_2^2, \end{aligned}$$

where the final inequality follows by the rearrangement inequality. Since Lemma 4.1 also applies to the stationary distribution, we further have

$$\text{Var}(R_{x_0,t}(Y)) = O(\log^2 n) e^{-2t\theta} \|P_{(1-\theta)t} x_0\|_2^2.$$

Our test function considers the set $A = \{x \in \{\pm 1\}^{\mathbb{Z}/n\mathbb{Z}} : R_{x_0,t}(x) \geq \frac{1}{2}e^{-2\theta t} \|P_{(1-\theta)t}x_0\|_2^2\}$. Therefore, by Chebyshev's inequality,

$$\mathbb{P}_{x_0}(X_t \in A^c) \leq \frac{\text{Var}_{x_0}(R_{x_0,t}(X_t))}{(\mathbb{E}_{x_0}[R_{x_0,t}(X_t)] - \frac{1}{2}e^{-2\theta t} \|P_{(1-\theta)t}x_0\|_2^2)^2} = O\left(\frac{e^{2\theta t} \log^2 n}{\|P_{(1-\theta)t}x_0\|_2^2}\right),$$

and so by the assumption of the lemma $\mathbb{P}_{x_0}(X_t \in A) \rightarrow 1$. Similarly,

$$\mathbb{P}(Y \in A) \leq \frac{\text{Var}(R_{x_0,t}(Y))}{(\frac{1}{2}e^{-2\theta t} \|P_{(1-\theta)t}x_0\|_2^2)^2} = O\left(\frac{e^{2\theta t} \log^2 n}{\|P_{(1-\theta)t}x_0\|_2^2}\right),$$

so $\mathbb{P}(Y \in A) \rightarrow 0$ which completes the lemma. \square

We can now establish Proposition 3, giving a lower bound for any deterministic initial condition.

Proof of Proposition 3 Writing $x_0 = \sum_j b_j \eta_j$ we have that

$$\|P_t x_0\|_2^2 = \left\| \sum_j b_j \eta_j e^{-\lambda_j t} \right\|_2^2 = \sum_j b_j^2 e^{-2\lambda_j t} \geq e^{-4t} \sum_j b_j^2 = e^{-4t} \|x_0\|_2^2 = e^{-4t} n,$$

where the inequality follows from the fact that all the eigenvalues are bounded by 2. Thus,

$$\frac{e^{2\theta t_\star} \log^3 n}{\|P_{(1-\theta)t_\star}x_0\|_2} \leq \frac{e^{(4-2\theta)t_\star} \log^3 n}{n} \leq \frac{1}{\log n},$$

and so, by Lemma 4.2, we have that $\|\mathbb{P}_{x_0}(X_{t_\star} \in \cdot) - \pi\|_{\text{TV}} \rightarrow 1$, as claimed. \square

This gives the right bound in the case of x^{alt} since it is an eigenvector of eigenvalue 2. For x^{blt} we get a stronger lower bound. Since it has eigenvalue 1,

$$\|P_t x^{\text{blt}}\|_2^2 = \|e^{-t} x^{\text{blt}}\|_2^2 = e^{-2t} \|x^{\text{blt}}\|_2^2 = e^{-2t} n.$$

So, taking $t_\star = \frac{1}{2} \log n - 8 \log \log n$,

$$\frac{e^{2\theta t_\star} \log^3 n}{\|P_{(1-\theta)t_\star}x_0\|_2} = \frac{e^{2t_\star} \log^3 n}{n} \leq \frac{1}{\log n},$$

and hence by Lemma 4.2 we have that

$$\|\mathbb{P}_{x^{\text{blt}}}(X_{t_\star} \in \cdot) - \pi\|_{\text{TV}} \rightarrow 1. \quad (4.1)$$

4.2 Hamiltonian test functions

The alternating initial condition x^{alt} is an extreme value for the Hamiltonian and measuring its convergence to stationarity gives another test of convergence. Such test functions were studied in [11] to analyze the a random annealed initial condition. To treat x^{alt} and x^{blt} in a unified manner, consider the function $R : \{\pm 1\}^{\mathbb{Z}/n\mathbb{Z}} \rightarrow \mathbb{R}$ given by

$$R(X) = \sum_{i=1}^{n/4} X(4i)X(4i+1).$$

For every x_0 and t we have that, by Lemma 4.1,

$$\text{Var}_{x_0}(R(X_t)) = \sum_{i=1}^{n/4} \sum_{j=1}^{n/4} \text{Cov}(X(4i)X(4i+1), X(4j)X(4j+1)) = O(n \log^2 n). \quad (4.2)$$

If Y is taken from the stationary distribution by taking a limit as $t \rightarrow \infty$, then we also have that $\text{Var}(R(Y)) = O(n \log^2 n)$. Let \mathcal{H} denote the set of all histories of the vertices from time t_* , and consider $\mathbb{E}_{x_0}[X_{t_*}(i)X_{t_*}(i') \mid \mathcal{H}]$. If the histories of i and i' merge then $X_{t_*}(i)$ and $X_{t_*}(i')$ must take the same value and $\mathbb{E}_{x_0}[X_{t_*}(i)X_{t_*}(i') \mid \mathcal{H}] = 1$. If the histories do not merge and at least one is killed before reaching time 0 then it is equally likely to be ± 1 so $\mathbb{E}_{x_0}[X_{t_*}(i)X_{t_*}(i') \mid \mathcal{H}] = 0$. Thus, the boundary condition can only play a role when both histories survive to time 0 and do not merge, as captured by the event

$$\mathcal{K}_{i,i'} = \{|\mathcal{F}_S(i, 0, t_*)| = |\mathcal{F}_S(i', 0, t_*)| = 1, \mathcal{F}_S(i, 0, t_*) \neq \mathcal{F}_S(i', 0, t_*)\}.$$

Let Y be an independent configuration distributed as π and let \mathbb{E}_π denotes the expectation started from the stationary measure. Then

$$\begin{aligned} & \mathbb{E}_\pi [X_{t_*}(i)X_{t_*}(i+1) \mathbb{1}_{\mathcal{K}_{i,i+1}} \mid \mathcal{H}] \\ &= \mathbb{E}_\pi [X_0(\mathcal{F}_S(i, 0, t))X_0(\mathcal{F}_S(i+1, 0, t)) \mathbb{1}_{\mathcal{K}_{i,i+1}} \mid \mathcal{H}] \\ &= \mathbb{E}[Y(\mathcal{F}_S(i, 0, t))Y(\mathcal{F}_S(i+1, 0, t)) \mathbb{1}_{\mathcal{K}_{i,i+1}} \mid \mathcal{H}] \geq 0, \end{aligned} \quad (4.3)$$

as the ferromagnetic Ising model is positively correlated. In a graph with two vertices connected by an edge, the correlation of spins of the Ising model can be found to be $\tanh \theta$. Correlations are monotone in the edges of the graph, so for neighboring vertices in $\mathbb{Z}/n\mathbb{Z}$ we have $\mathbb{E}[Y(i)Y(i+1)] \geq \tanh \theta > 0$. It was shown in the proof of Theorem 6.4 of [11] that

$$\mathbb{P}(\mathcal{F}_S(i, 0, t) = \{i\}, \mathcal{F}_S(i+1, 0, t) = \{i+1\}) \geq c_1 t^{-2} e^{-2\theta t},$$

and so

$$\begin{aligned} & \mathbb{E}_\pi [X_{t_\star}(i)X_{t_\star}(i+1)\mathbb{1}_{\mathcal{K}_{i,i+1}} \mid \mathcal{H}] \\ & \geq \tanh(\theta)\mathbb{P}(\mathcal{F}_S(i, 0, t_\star) = \{i\}, \mathcal{F}_S(i+1, 0, t_\star) = \{i+1\}) \\ & \geq c_1 \tanh(\theta)t_\star^{-2}e^{-2\theta t_\star}. \end{aligned} \quad (4.4)$$

We will compare this bound with the behavior under the initial conditions x^{alt} and x^{blt} .

Claim 4.3 For $x_0 \in \{x^{\text{alt}}, x^{\text{blt}}\}$ and $i \equiv 0 \pmod{4}$ we have that

$$\mathbb{E}_{x_0} [X_{t_\star}(i)X_{t_\star}(i+1)\mathbb{1}_{\mathcal{K}_{i,i+1}} \mid \mathcal{H}] \leq 0.$$

Proof We first treat the case of x^{alt} . Let $Z_1(t)$ and $Z_2(t)$ be independent rate- $(1-\theta)$ continuous-time simple random walks with initial conditions $Z_1(0) = i$ and $Z_2(0) = i+1$. Let T denote the first time the walks hit each other and $W(t) = x^{\text{alt}}(Z_1(t))x^{\text{alt}}(Z_2(t))$. By the killed random walk representation of the histories, we have that

$$\begin{aligned} \mathbb{E}_{x^{\text{alt}}} [X_{t_\star}(i)X_{t_\star}(i+1)\mathbb{1}_{\mathcal{K}_{i,i+1}} \mid \mathcal{H}] &= e^{-2\theta} \mathbb{E} [x^{\text{alt}}(Z_1(t_\star))x^{\text{alt}}(Z_2(t_\star))\mathbb{1}_{T > t_\star}] \\ &= e^{-2\theta} \mathbb{E} [W(t_\star)\mathbb{1}_{T > t_\star}]. \end{aligned}$$

Note that $W(t)$ is itself a Markov chain with state space $\{\pm 1\}$ and transition rate $2(1-\theta)$, and so

$$\mathbb{E}[W(t+s) \mid W(s)] = e^{-4(1-\theta)s}W(s). \quad (4.5)$$

Thus, since $W(0) = -1$ by the definition of x^{alt} , and $W(T) = 1$, applying (4.5) we get

$$\begin{aligned} \mathbb{E} [W(t_\star)\mathbb{1}_{T > t_\star}] &= \mathbb{E} [W(t_\star)] - \mathbb{E} [W(t_\star)\mathbb{1}_{T \leq t_\star}] \\ &= -e^{-4(1-\theta)t_\star} - \mathbb{E} \left[\mathbb{1}_{T \leq t_\star} \mathbb{E} [W(t_\star) \mid T] \right] \\ &= -e^{-4(1-\theta)t_\star} - \mathbb{E} \left[\mathbb{1}_{T \leq t_\star} e^{-4(1-\theta)(t_\star-T)} \right] \leq 0. \end{aligned}$$

Hence, $\mathbb{E}_{x^{\text{alt}}} [X_{t_\star}(i)X_{t_\star}(i+1)\mathbb{1}_{\mathcal{K}_{i,i+1}} \mid \mathcal{H}] \leq 0$.

For x^{blt} , the process $x^{\text{blt}}(Z_1(t))x^{\text{blt}}(Z_2(t))$ is again a Markov chain but with transition rate $1-\theta$. The requirement that i is a multiple of 4 was chosen to ensure that $x^{\text{blt}}(Z_1(0))x^{\text{blt}}(Z_2(0)) = -1$. The argument is otherwise unchanged. \square

Combining Lemma 4.5 with Eq. (4.4), we obtain that

$$\begin{aligned} & \mathbb{E}_\pi [X_{t_\star}(i)X_{t_\star}(i+1)] - \mathbb{E}_{x^{\text{alt}}} [X_{t_\star}(i)X_{t_\star}(i+1)] \\ &= \mathbb{E}_\pi [X_{t_\star}(i)X_{t_\star}(i+1)\mathbb{1}_{\mathcal{K}_{i,i+1}}] - \mathbb{E}_{x^{\text{alt}}} [X_{t_\star}(i)X_{t_\star}(i+1)\mathbb{1}_{\mathcal{K}_{i,i+1}}] \\ &\geq c_1 \tanh(\theta)t_\star^{-2}e^{-2\theta t_\star}, \end{aligned}$$

and thus

$$\mathbb{E}[R(Y)] - \mathbb{E}_{x_0}[R(X_{t_\star})] \geq c_1 \tanh(\theta) t_\star^{-2} e^{-2\theta t_\star} \frac{n}{4}. \quad (4.6)$$

We are now ready to prove the second lower bound.

Lemma 4.4 *Set*

$$t_\star = \frac{1}{4\theta} t_\star - \frac{5}{\theta} \log \log n.$$

For $x_0 \in \{x^{\text{alt}}, x^{\text{blt}}\}$ we have

$$\lim_{n \rightarrow \infty} \|\mathbb{P}_{x_0}(X_{t_\star} \in \cdot) - \pi\|_{\text{TV}} = 1.$$

Proof Denote by A the event

$$A = \{x \in \{\pm 1\}^{\mathbb{Z}/n\mathbb{Z}} : R(x) \geq \frac{1}{2}(\mathbb{E}[R(Y)] + \mathbb{E}_{x_0}[R(X_{t_\star})])\}.$$

By Chebyshev's inequality and Eqs. (4.2) and (4.6)

$$\mathbb{P}_{x_0}(X_{t_\star} \in A) \leq \frac{\text{Var}_{x_0}(R(X_{t_\star}))}{\left(\frac{1}{2}(\mathbb{E}[R(Y)] - \mathbb{E}_{x_0}[R(X_{t_\star})])\right)^2} = O\left(\frac{n \log^2 n}{t_\star^{-4} e^{-4\theta t_\star} n^2}\right) \rightarrow 0,$$

and similarly

$$\mathbb{P}(Y \in A^c) \leq \frac{\text{Var}(R(Y))}{\left(\frac{1}{2}(\mathbb{E}[R(Y)] - \mathbb{E}_{x_0}[R(X_{t_\star})])\right)^2} \rightarrow 0.$$

Hence, $\|\mathbb{P}_{x_0}(X_{t_\star} \in \cdot) - \pi\|_{\text{TV}} \rightarrow 1$, as claimed. \square

Proof of Theorem 1, Lower bound The case of x^{alt} follows from combining Proposition 3 and Lemma 4.4, while the lower bound for x^{blt} follows from Eq. (4.1) and Lemma 4.4. \square

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