

1 **Opposing Hysteresis Patterns in Flow and Outflow Macroscopic Fundamental Diagrams**
2 **and Their Implications**

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ABSTRACT

Two key aggregated traffic models are the relationship between average network flow and density (known as the network or flow-Macroscopic Fundamental Diagram, flow-MFD) and the relationship between trip completion and density (known as Network Exit Function or the output-MFD). The flow- and output-MFD have been shown to be related by average network length and average trip distance under steady state conditions. However, recent studies have demonstrated that these two relationships might have differing patterns when traffic conditions are allowed to vary: the flow-MFD exhibits a clockwise hysteresis loop, while the output-MFD exhibits a counter-clockwise loop. One recent study attributes this behavior to the presence of bottlenecks within the network.

The present paper demonstrates that this phenomenon may arise even without bottlenecks present and offers an alternative, but more general, explanation for these findings: a vehicle's entire trip contributes to a network's average flow, only its end contributes to the trip completion rate. This lag can also be exaggerated by trips with different lengths or uneven congestion distribution, and it can lead to other patterns in the output-MFD such as figure-8 patterns. A simple arterial example and two-bin system are used to demonstrate this explanation and reveal the expected patterns, while simulations of a congestible ring network are used to unveil features that might increase or diminish the differences between the flow- and output-MFDs. Finally, more realistic simulations and empirical field data are used to confirm that these behaviors arise in real networks.

Keywords: flow-MFD; o-MFD; hysteresis loop; figure-eight; urban traffic network dynamics

INTRODUCTION

Traffic networks are complex systems made up of numerous moving parts (e.g., vehicles) and infrastructure elements (e.g., links and nodes). Modeling individual vehicle movements or traffic on the numerous component pieces of these systems – and their resulting interactions – is extremely challenging due to the computational complexity involved. Perhaps for this reason, researchers have also studied relationships between traffic flow features aggregated across entire regions or cities for decades (1–8). The earliest studies of this type were descriptive models that could be used to understand how one feature (e.g., vehicle speed or flow) varied with network use. For example, the two-fluid model considered the relationship between average vehicle speed and the fraction of vehicles moving in traffic (9), and later studies examined how this two-fluid model relationship varied with properties of a network (10). One particularly insightful study proposed the existence of a unimodal relationship between average network flow, q [veh/lane-time], and average network density, k [veh/lane-distance], that – unlike other studies of that era – could be used to describe both uncongested and congested traffic scenarios (1). However, empirical evidence that confirmed the existence of this relationship in practice – known more commonly as the network Macroscopic Fundamental Diagram or flow-MFD – only became available much later (11). This latter study has led to a revival of interest in network-wide traffic flow models and their applications.

One aspect that has been studied in the literature is the conditions under which flow-MFDs might arise in practice. One seminal study found that traffic networks should have either uniform or repeatable congestion distribution patterns for well-defined flow-MFDs to arise (12). However, several studies have found that traffic networks have a natural tendency for congestion to spread unevenly in an unpredictable way, which can result in highly scattered or poorly defined flow-MFDs (13–15). This unstable behavior also leads to hysteresis patterns in which flows are lower when congestion dissipates than as it grows in a network (16–18), and this behavior manifests as clockwise loops on the flow-MFD. These natural tendencies toward unpredictable inhomogeneous congestion distributions can be somewhat mitigated by providing vehicles with advanced information to avoid already congested areas within a network (16, 18) or utilizing adaptive traffic signal control to prioritize movement away from more congested areas (19, 20). Traffic networks can also be carefully partitioned into smaller regions with more uniform congestion patterns to yield more well-defined flow-MFDs (21–24).

While flow-MFDs are generally descriptive (i.e., used to describe how well a network might be operating or compare operations across certain conditions), aggregated relationships like MFDs can also be used to describe traffic network dynamics on a regional level. One study showed how the existence of a flow-MFD also implies the existence of a relationship between the rate at which trips can be completed in a network, f [trips/time], and its use (measured either by average density or average number of vehicles circulating within the network, n [veh]) (25). This latter relationship has sometimes been called the Network Exit Function of output-MFD (o-MFD). Various studies have used o-MFD-based modeling frameworks to develop regional traffic control strategies such as perimeter metering control, physics-based regional congestion pricing street network design, and regional routing schemes, among others.

Under steady-state conditions, the flow- and o-MFDs are related in the following way:

$$f = \frac{q \times L}{l} \quad (1a)$$

$$n = k \times L \quad (1b)$$

where L [lane-distance] is the total length of streets in the network and l [distance/trip] is the average trip length in the network (25). Given the relationships in (1), one would expect that the shape and pattern of the flow- and o-MFDs would be similar. For example, if the flow-MFD exhibits clockwise hysteresis loop patterns then the o-MFD should exhibit a similar shape. However, this doesn't turn out to be the case. Recent studies (26–29) used different traffic flow models (e.g., LWR, accumulation-based and trip-based) to investigate traffic network dynamics under fast-varying demand conditions and found that the o-MFD may exhibit counter-clockwise hysteresis patterns even while the flow-MFD exhibits no hysteresis pattern or clockwise hysteresis patterns. One study (28) attributed this pattern to the presence of internal

bottlenecks within the network that causes outflows to sustain their maximum value until all vehicles that experience congestion have left.

In this present study, we first examine the shapes and patterns of the flow- and o-MFDs on an arterial case where no bottleneck is present to demonstrate that the conflicting hysteresis patterns are not necessarily caused by the presence of internal bottlenecks. Instead, we demonstrate that these are caused by differences in how the flow- and o-MFD are computed: the former considers the entire length of a vehicle's trips, while the latter only considers its end. Then, we show and explained that when the gap in trip distance is large and when congestion is heavily imbalanced over the network, there could be both clockwise and counter-clockwise hysteresis loops and thus a figure-eight pattern in a network's o-MFD, even with no or opposite loops in the flow-MFD. Next, we use a simple network simulation to verify the existence of counter-clockwise and figure-eight hysteresis patterns in the o-MFD and examine how various features might influence the size and shape of these conflicting hysteresis patterns. Finally, we use empirical data to demonstrate that these findings also hold in real-world MFDs.

The remainder of this paper is organized as follows. Some simple scenarios are first used to study the patterns of o-MFD under fast-varying demand. Then, analytical explanations are provided for the existence and cause of the counter-clockwise hysteresis loop in the o-MFD in the absence of bottlenecks and for the existence and cause of the figure-eight hysteresis pattern in a congestible network. This is followed by the investigation of the impact of different network features on the magnitude of the hysteresis loop in the o-MFD using microscopic simulations. Furthermore, empirical data are provided to verify the existence of counter-clockwise and figure-eight hysteresis patterns in real-world networks' o-MFDs. Finally, some discussion and concluding remarks are offered.

CAUSE OF HYSTERESIS PATTERNS IN THE O-MFD

One most recent explanation for the counter-clockwise loop in the o-MFD is provided in Leclercq and Paipuri (2019), which investigated the behavior of traffic states on a long arterial and attributed the counter-clockwise loop to the presence of an internal bottleneck. In this section, a simple arterial that has no bottlenecks is first analyzed to show that counter-clockwise pattern may still arise in the o-MFD when no internal bottlenecks are present. This loop exists even when the flow-MFD exhibits no loop. In addition, an arterial with two exits and a two-bin system are also analyzed to demonstrate that other patterns might exist; e.g., simultaneous clockwise and counter-clockwise hysteresis loop in the o-MFD (thus a figure-eight pattern).

Measurement lag

In this section, traffic behavior on a long arterial will be used to demonstrate why counter-clockwise hysteresis loop can be observed in the o-MFD when demand varies quickly.

Scenario setup

We consider here a one-way arterial of length l_a [length] with a single entrance and exit; see **Figure 1a**. This arterial is assumed to have a single travel lane and, more critically, contain no internal bottlenecks. Traffic on the arterial is assumed to obey a triangular fundamental diagram with a common free flow speed v_f [length/time], capacity Q_m [veh/time] and jam density k_j [veh/length]. As shown in **Figure 1a**, vehicles enter the arterial from left side and travel towards the right. Vehicles are assumed to exit within any external disruption; i.e., there are no external restrictions to vehicle exit rate.

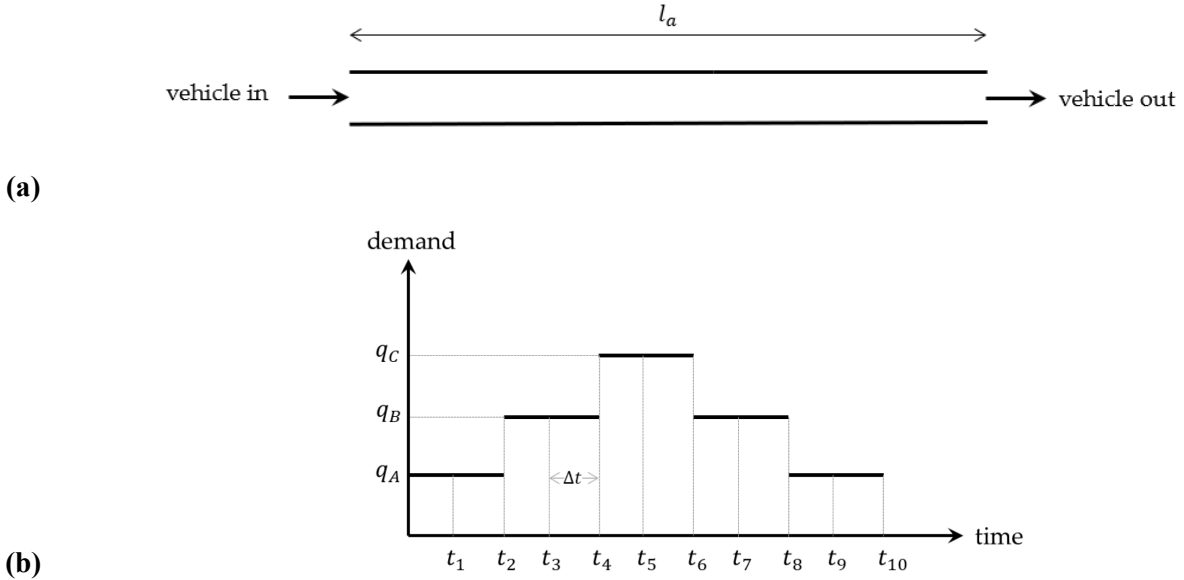


Figure 1 (a) Illustration of one-way arterial setup; and, (b) demand profile used for analytical investigation.

Vehicles are assumed to enter an initially empty arterial following the demand profile shown in **Figure 1b**. The demand pattern mimics a typical rush with a loading period (from time 0 to t_4 [time]) in which demand increases from 0 to its maximum value of $q_C < Q_m$, the peak in which the maximum demand q_C is maintained (from time t_4 to t_6), and then a recovery period in which the demand drops from q_C to 0 (from time t_6 to t_{10}). To simplify the analytical investigation and without lack of generality, the loading period and recovery period are assumed to consist of periods that have constant intermediate demands $q_A < q_B < q_C$. Furthermore, we assume that each period of constant demand is maintained for a period of $2\Delta t$, where Δt is the time for a vehicle to completely traverse the arterial at the free flow speed. Thus, the entire rush occurs over a period of $10\Delta t$. These latter two assumptions are not necessary and will be relaxed so that demand is allowed to vary throughout the loading and recovery period in the simulation verification.

Analytical analysis of flow-MFD and o-MFD shape

Traffic dynamics on this simple arterial can be readily described using the theory of kinematic waves proposed by Lighthill, Whitham, and Richards (30–32). **Figure 2a** provides a time-space diagram that describes how traffic states evolve along the arterial given the conditions considered. Solid black lines represent interfaces that separate unique traffic states – indicated by colored regions in the figure denoted O, A, B, and C – that arise along the arterial. Note that 0 refers to the zero state in which density and flow are zero, whereas any other state i refers to the associated free-flow state with flow q_i . All interfaces move along the time-space plane at the free flow speed since congestion does not arise along the arterial due to the lack of bottlenecks or external restrictions.

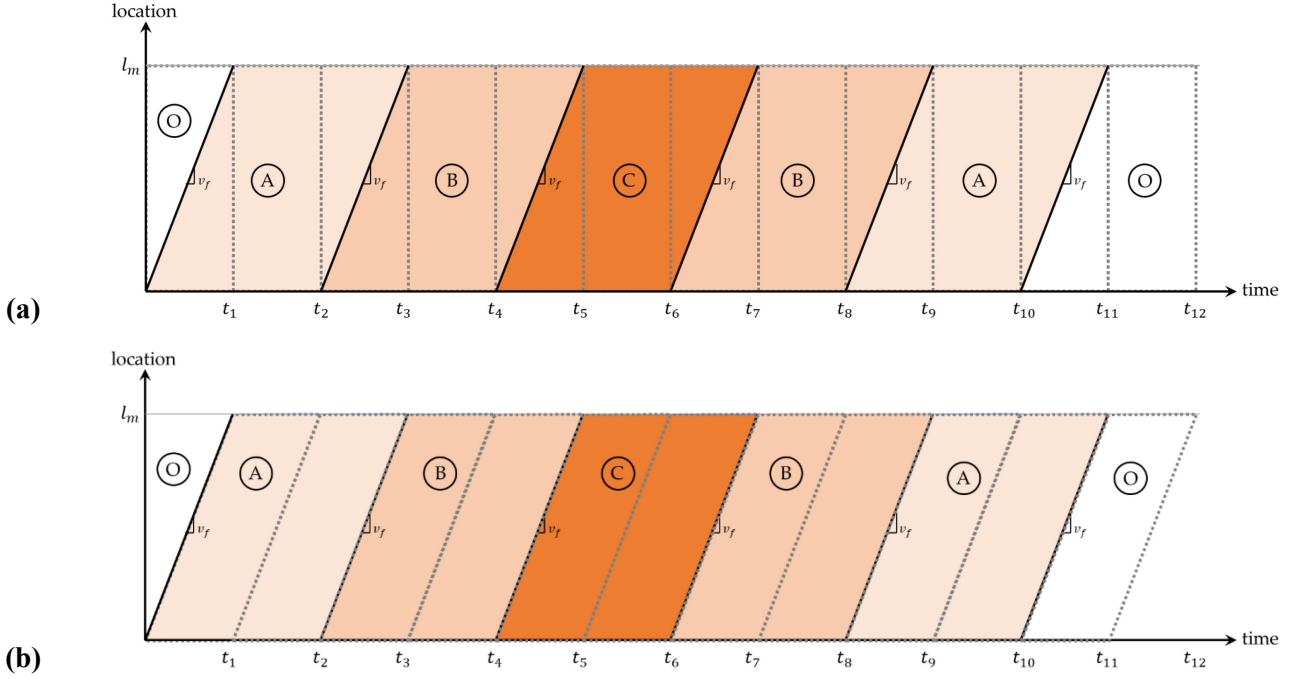
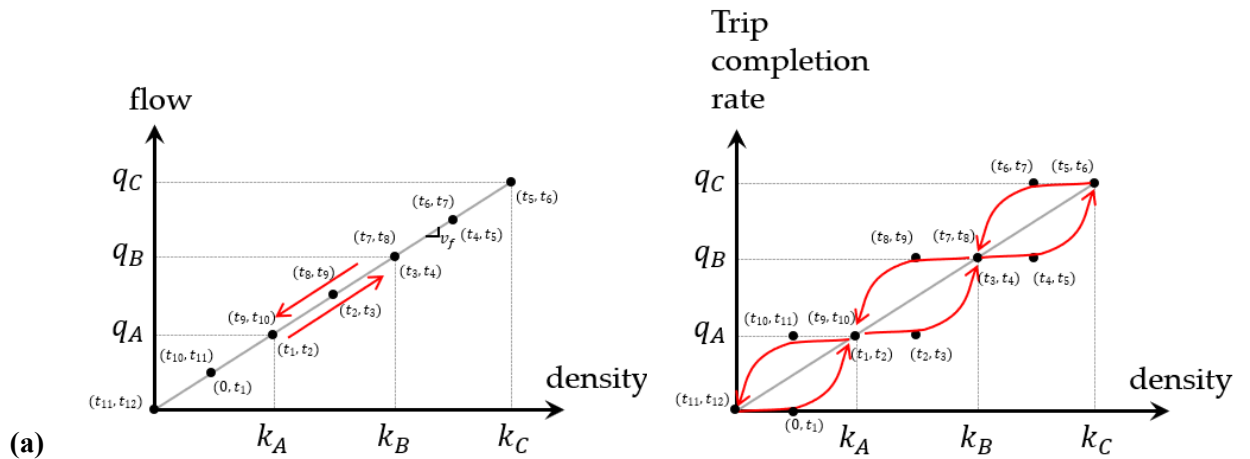


Figure 2 Time-space diagram describing traffic dynamics on arterial under given demand conditions. (a) traditional measurement intervals; and, (b) skewed measurement intervals.

We first consider the shape and pattern of the flow-MFD. Again, for simplicity of calculation and without lack of generalization, let us assume that flow and density are aggregated at regular time intervals of Δt (denoted by the dashed gray rectangles in **Figure 2**). Based on the generalized definitions of Edie, the average flow (likewise density) during any measurement interval is computed as the area-weighted average of the flow (density) in each observed traffic state within that interval (33). For example, the average flow during the first measurement interval from time 0 to t_1 is $\frac{1}{2}(q_0 + q_A) = \frac{1}{2} q_A$. The resulting flow-density relationship obtained from the time-space diagram in **Figure 2a** is shown on the left side of **Figure 3a**. As expected, all observed flow-density points lie along the free flow branch of the fundamental diagram since all observed traffic states are in free flow. More importantly, no hysteresis patterns are observed in the flow MFD.



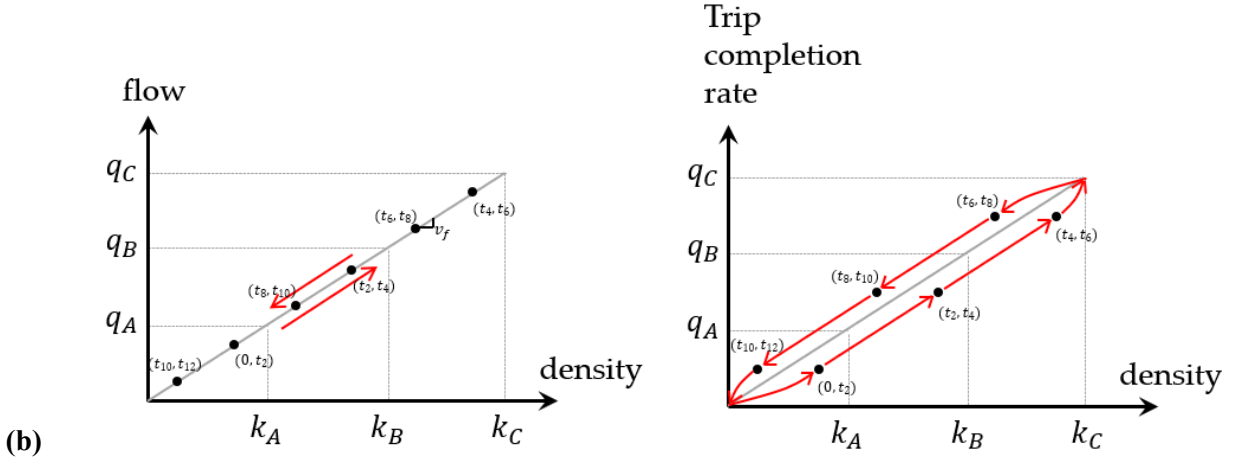


Figure 3 Flow-MFD and o-MFD for the simply arterial example under: (a) constant demand periods of length $2\Delta t$; and, (b) constant demand periods of length Δt .

Next, we consider the shape and pattern of the o-MFD. As average accumulation and density are equivalent to a multiplicative constant (arterial length, l_A), we consider the relationship between trip completion rate and density as the o-MFD here. The trip completion rate is simply the rate of trips leave the arterial section and can be calculated as the flow measured at the end of the arterial (horizontal line at location l_A in **Figure 2**). The resulting o-MFD is provided on the right side of **Figure 3a**. Notice that the o-MFD generally exhibits a counter-clockwise hysteresis pattern in which trip completion rates are lower as density along the arterial increases (i.e., during loading) than as it decreases (i.e., during recovery). This occurs even without the presence of bottlenecks along the arterial for a simple reason: average flow during a measurement interval is computed based on overall vehicle movements during that measurement interval, whereas trip completion rate is only influenced by vehicle movement at the end of the arterial. For example, the flow is positive during the first measurement interval since vehicles have entered and are traveling along the arterial. However, the trip completion rate is zero since no vehicles have reached the end of the arterial to exit the system. Put another way, average flow is a measurement of overall movement along the arterial, while trip completion rate is only a measurement of vehicles reaching the end of their trip. Thus, in the context of this example, trip completion rate “lags” after average flow: changes in entering demand are immediately incorporated into the calculation of average flow, whereas they only influence trip completion rate after some time Δt , in which the first vehicle in the new traffic state arrives at the downstream end of the arterial. If trips could start and end within the same measurement interval, the hysteresis would entirely disappear. For example, consider the flow-MFD and o-MFD were computed using the skewed measurement intervals in **Figure 2b**. Here, each measurement interval is the same size in the time-space plane as those in **Figure 2a**, but are skewed so they move forward in space at the free-flow speed. In this case, a single traffic state would be observed during the entire measurement interval; thus, the flow-MFD would be the same as the free flow branch of the fundamental diagram, and the o-MFD would exhibit no hysteresis. However, while useful in this arterial context, such skewed measurement intervals may not be feasible to study for network-wide operations and thus the hysteresis patterns are bound to arise when traditional measurement intervals are used.

Note also that the trip completion rate is the same at some density values (k_A, k_B, k_C) during loading and recovery in **Figure 3a**. This occurs because of the specific step-wise demand pattern considered used for simplicity of calculations. Long periods of constant demand allow the network to return to a steady-state condition in which the flow-MFD and o-MFD are consistent. If demand is more variable over time (i.e., the same demand does not persist for as long), more clear hysteresis patterns emerge. As an example, **Figure 3b** provides the flow- and o-MFDs for the case where the length of each

constant demand period reduces from $2\Delta t$ to Δt . The change has no impact on the flow-MFD but results in a much clearer counter-clockwise hysteresis pattern in the o-MFD.

Lag due to gap in trip distances

In the previous section, we studied the o-MFD of a simple arterial with one entrance and one exit (thus same trip distance) under a fast-varying demand pattern and found that the measurement lag between trip completion rate and average flow/density lead to a counter-clockwise hysteresis loop in the o-MFD. In this section, a simple arterial with multiple exits (resulting in different trip distances) is studied. As will be shown here, the gap in trip distances causes a lag of outflows at different exits leading to a figure-eight pattern in the o-MFD.

Scenario setup

We consider the same arterial as in the previous section except that there is another exit located $l_a/10$ away from the entrance, shown in **Figure 4a**. It is assumed that half of the vehicles entering the arterial will leave at the former exit and half of the inflow will leave at the latter exit.

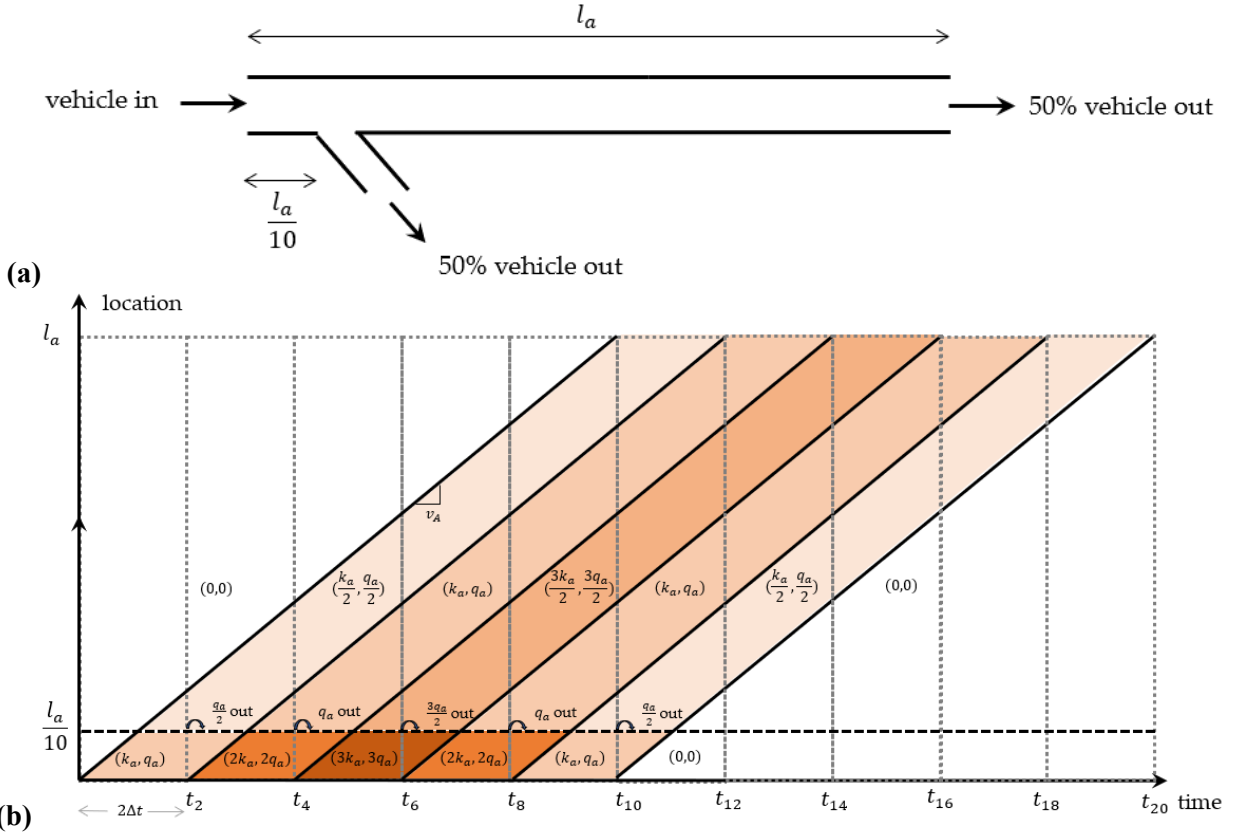


Figure 4 (a) Illustration of one-way arterial with two exits; (b) Time-space diagram describing traffic dynamics on an arterial with two exits.

Vehicles are assumed to enter an initially empty arterial following the same demand profile shown in **Figure 1b**. For simplicity, we assume $q_A < q_B = 2q_A < q_C = 3q_A$. Each period of constant demand is maintained for a period of $2\Delta t$, where Δt is the travel time from the entrance to the former exit at the free flow speed. Thus, the travel time from the entrance to the latter exit at the free flow speed is $10\Delta t$.

Analytical analysis of flow-MFD and o-MFD shape

Similarly, traffic dynamics on this simple arterial can be described using the theory of kinematic waves. **Figure 4b** provides a time-space diagram that describes how traffic states evolve along the arterial given the conditions considered. Solid black lines represent interfaces that separate unique traffic states with flow and density as a function of k_a and q_a arising along the arterial.

Let us assume that flow and density are aggregated at regular time intervals of $2\Delta t$. Based on the generalized definitions (33), the calculated flow-density relationship is shown in **Figure 5a**. Similar to the MFD of a simple arterial with one exit, all observed flow-density points lie along the free flow branch of the fundamental diagram and no hysteresis pattern is observed. The resulting o-MFD is then provided in **Figure 5b**. Interestingly, we can observe combination of both clockwise and counter-clockwise loops exhibiting a “figure-eight” pattern, i.e., the trip completion rate is higher during loading than during recovery for a higher density and lower during loading than during recovery for a lower density. This occurs simply because the gap in trip distances leads to a lag of trip completion rates between the two exits. Specifically, after 50% of vehicles from the loading and peak period leave the arterial at the former exit, the other 50% of vehicles from the loading and peak period have not reached the latter exit yet. As a result, the trip completion rate drops as the inflow drops, corresponding to the blue trajectory in **Figure 5b**. As shown in **Figure 4b**, when the other 50% of vehicles from loading and peak period start to leave at the latter exit at t_{10} , no more vehicles leave at the former exit while trip completion rate at the latter exit follows a similar pattern as the inflow, i.e., increases first, remains at a constant value and finally decreases. This corresponds to the red trajectory in **Figure 5b**. These two trajectories form a clockwise hysteresis loop at a higher density and a counter-clockwise hysteresis loop at a lower density, exhibiting a figure-eight pattern. This figure-eight pattern should be generally expected in freeway o-MFDs as the exits of freeways are far away from each other leading to a significant lag of trip completion rate between different exits.

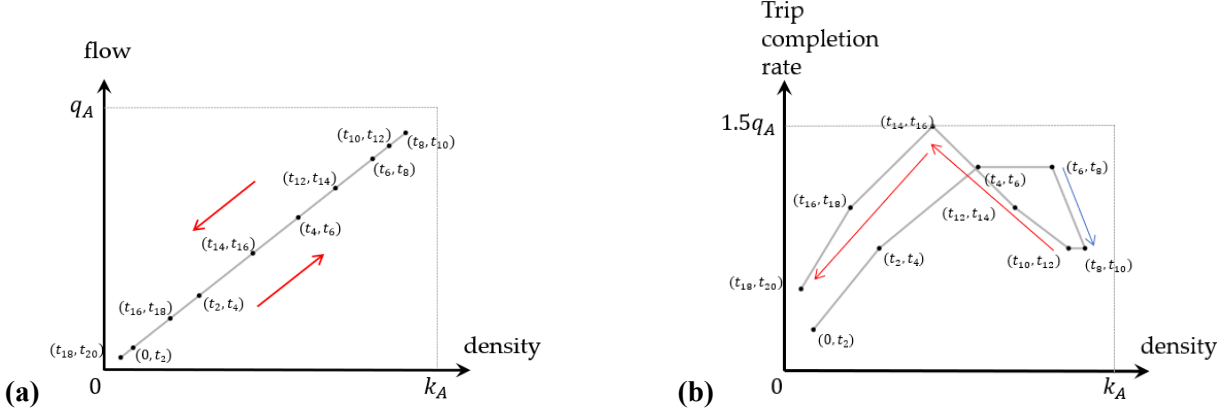


Figure 5 (a) flow-MFD for an arterial with two exits; and, (b) o-MFD for an arterial with two exits.

Lag due to congestion imbalance

Scenario setup

In the previous sections, we consider cases when vehicles can leave the network freely and thus the network is always in free flow. In this section, we study the behavior of the two-bin system used in (16) to analyze the hysteresis patterns under congestion. As will be shown here, the congestion imbalance, which should be generally expected in a two-bin system, can lead to a either counter-clockwise or figure-eight hysteresis pattern in the o-MFD.

The two-bin system considered here is shown in **Figure 6a**. Each of the rectangular regions on the left side of **Figure 6a** can be modeled as a bin of vehicles on the right side of **Figure 6a** if vehicles in each region are uniformly distributed in space. It is also assumed that destinations of 50% of vehicles

entering each bin are in the same bin and destinations of the other 50% of vehicles entering each bin are in the other bin. Network represented by each bin is assumed to have a total length of 10 mi and obey a triangular fundamental diagram with $v_f = 40$ mi/hr; $Q_m = 2000$ veh/hr; $k_j = 250$ veh/mi. We also assume that vehicles will enter each bin following a more variable demand pattern shown in **Figure 6b** with a fixed trip distance of 6 mi. And we set $t_1 = 1$ hr, $t_2 = 2$ hr, $t_3 = 3$ hr, $t_4 = 3.5$ hr. Finally, traffic dynamics are modeled using the trip-based model.

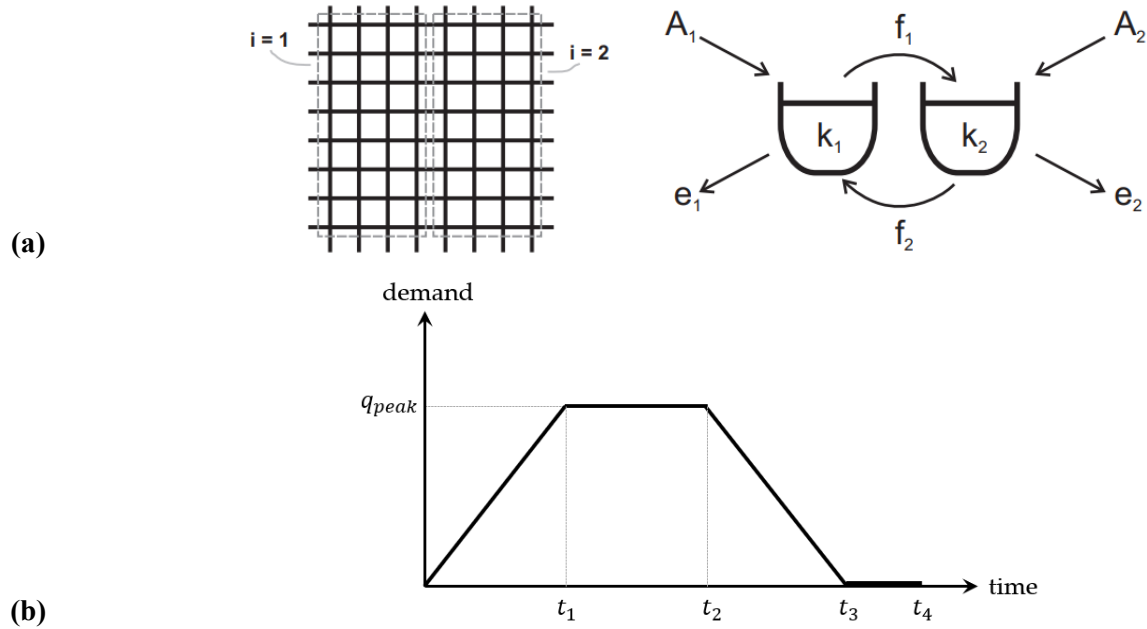


Figure 6 (a) Illustration of a two-bin system (Gayah and Daganzo, 2011a); (b) Demand profile.

Analysis of flow-MFD and o-MFD shape

Figure 7 shows the flow-MFD, o-MFD, density of each bin, and speed of each bin for a case when congestion is slightly imbalanced and a case when congestion is heavily imbalanced under the same demand. Comparison of flow-MFD in **Figure 7a** shows that as vehicles become more unevenly between the two bins, a larger clockwise hysteresis loop will arise in the flow-MFD. Comparison of o-MFD in **Figure 7b** reveals that when the congestion is slightly imbalanced, a counter-clockwise hysteresis loop will be generated in the o-MFD. However, when the congestion is heavily imbalanced, we can observe a figure-eight pattern in the o-MFD. This is because the speed of the bin with a larger density is much lower than the speed of the bin with a smaller density (shown in **Figure 7d**) leading to a lag of trip completion between the two bins. Following a similar trajectory discussed in the previous section, the shape of o-MFD of the entire two-bin system will have a figure-eight pattern caused by the lag due to congestion imbalance. This should be generally expected in real urban networks as congestion is heavily imbalanced on roads in real life.

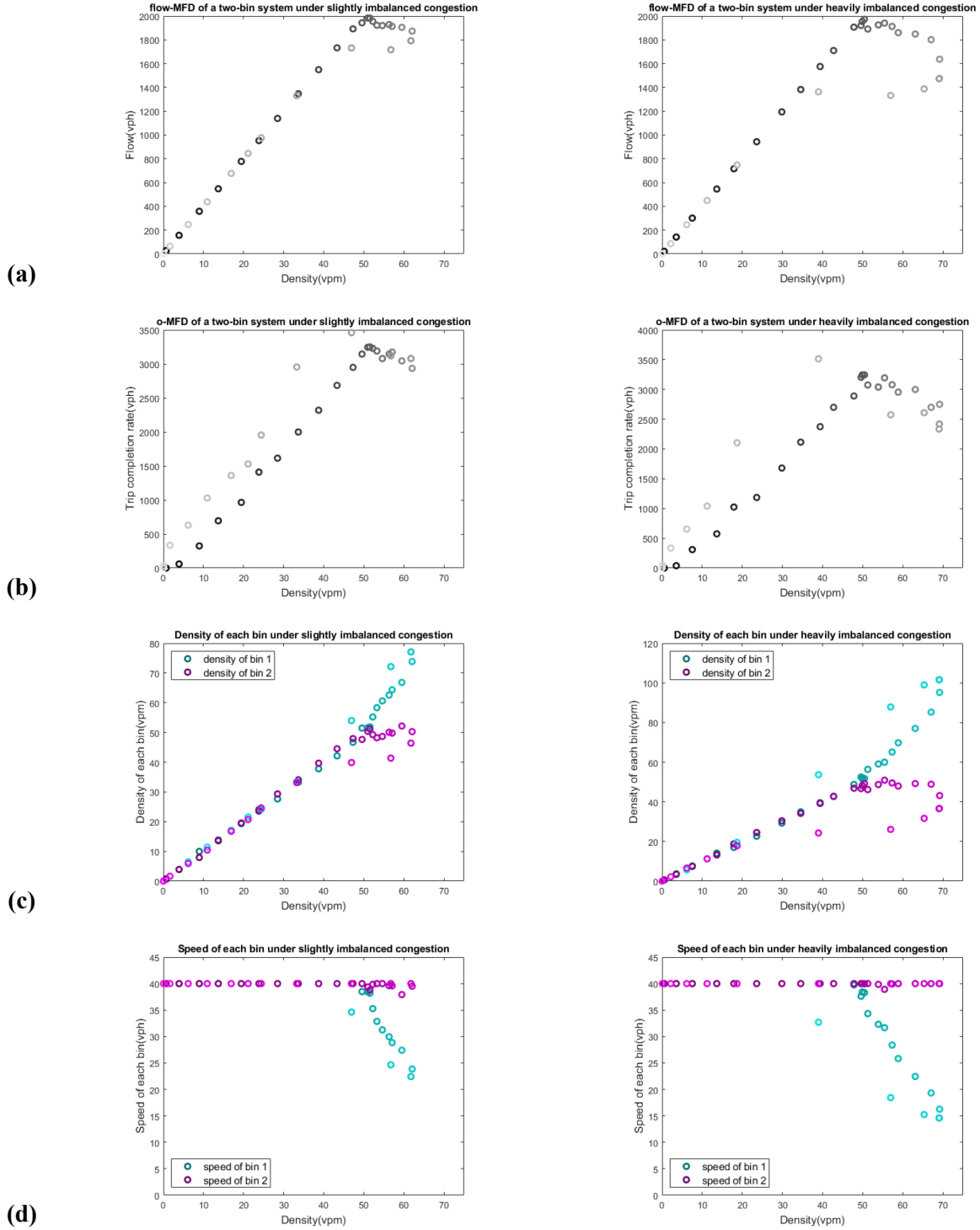


Figure 7 Results for a two-bin system under different congestion imbalances obtained from the trip-based model: (a) flow-MFD; (b) o-MFD; (c) density of each bin; and (d) speed of each bin.

IMPACT OF NETWORK FEATURES ON THE HYSTERESIS PATTERN

In the previous section, we analyzed the causes of hysteresis patterns in the o-MFD of a few simple networks. In this section, we examine the behavior of a ring network and a grid network via microscopic simulations to demonstrate the existence of counter-clockwise patterns and figure-eight patterns in more

realistic networks due to the same reasons outlined in the previous section. We also examine how the counter-clockwise hysteresis patterns in the o-MFD may be influenced by various patterns.

Ring network

Simulation setup

The ring network considered here is illustrated in **Figure 8**. The ring has a total length of 10 miles and traffic along the ring is assumed to obey a triangular fundamental diagram with the following properties: $v_f = 50$ mi/hr; $Q_m = 2000$ veh/hr; $k_j = 200$ veh/mi. The ring contains four entry/exit ramps that are equally spaced along its length, which serve as origins/destinations within the network. Vehicles entering the network are each assigned a specific exit ramp as their destinations and will travel along the ring until they reach their assigned destination to exit and are allowed to exit freely. Entry ramps are treated as unsignalized merges in which entering vehicles are assumed to have priority.

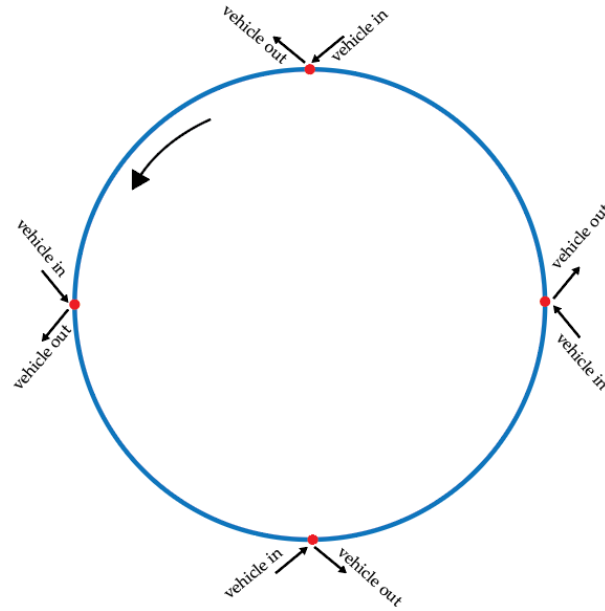


Figure 8 Simulated ring network

The cellular automata model (CAM) consistent with kinematic wave theory is used to simulate the behavior of vehicles on the network (34, 35). In this framework, the ring is broken up into homogeneous discrete cells of length 0.005 miles (equal to average vehicle spacing at jam density) that allow only a single vehicle to occupy any cell at any time period. Vehicle locations are updated at consistent intervals of 0.36 seconds. Average flow and density across the entire network are computed using the generalized definitions of Edie at discrete intervals of 6 minutes (33). Trip completion is measured as the rate vehicles exit the ring at their destination exit ramp.

The simulation starts with an empty network. Trips are equally likely to be generated at the four intersections following a specific demand profile (unless otherwise noted). When a vehicle enters the network from an intersection, one of the other three intersections will be assigned to it as the destination based on the trip distance. Different simulations are then conducted to unveil the impacts of different demand and trip distance patterns on the existence and magnitude of the hysteresis loop in the flow-MFD and o-MFD. Vehicles are assumed to enter the ring following the demand profile shown in **Figure 6b** under the following parameters (unless otherwise specified): $t_1 = 1$ hr, $t_2 = 2$ hr, $t_3 = 3$ hr, $t_2 = 3.5$ hr. In most scenarios, individual vehicle trip distance is set to be 5 miles (i.e., vehicles travel two “segments” and exit at the ramp opposite point of their entry location).

Simulation results

(1) Peak demand (q_{peak})

The impact of peak demand is first investigated. **Figure 9** shows the flow-MFD and o-MFD under peak demands 2000, 2800, and 3000 veh/hr, respectively. Note that the peak demands represent the total inflow across all four entry ramps; thus, the entry flow at individual ramps have a peak of 500 veh/hr/ramp, 700 veh/hr/ramp, and 750 veh/hr/ramp, respectively.

The left-hand side of **Figure 9** shows the flow-MFDs for the various demand conditions. In the lowest demand case, only the free-flow branch of the flow-MFD is observed and no hysteresis loops arise. In contrast, both the free-flow and congested branches of the flow-MFD are observed under the higher demand cases. Furthermore, these higher demand cases exhibit a clear clockwise hysteresis pattern in the flow-MFD as average flows are higher as density increases than as it decreases. This occurs because traffic density along the rings tends toward inhomogeneous spatial distributions as the ring becomes congested (13, 36).

The right-hand side of **Figure 9** shows the o-MFD under different peak demands. It can be clearly observed that all three o-MFDs have a counter-clockwise hysteresis loop. This occurs both when the flow-MFD does not have any hysteresis pattern (low demand) and when it exhibits a clockwise hysteresis pattern (higher demands). This demonstrates that the hysteresis pattern in the flow- and o-MFDs can take completely opposite shapes/patterns (28). However, we show here that this phenomenon occurs even when bottlenecks do not exist within the network. The reason for this, as described in the analytical investigation of a simple arterial in Section 2, is the lagged nature of trip completion rate compared to average flow calculations. Vehicle trips contribute to average flow in the network as soon as they enter the network, but do not contribute to trip completion rate until they reach their destination ramp and exit. Thus, flows increase as demands initially increase as more vehicles arrive onto the network; however, trip completion rate will only increase sometime after when these vehicles arrive at their destinations. Similarly, even though flow drops as demands decrease when fewer vehicles enter the network, vehicles already in the network still need to arrive to their destination and would lead to increased trip completion rate even after the demands fall. To demonstrate that the counter-clockwise loop in the o-MFD is due to measuring the end of vehicle's trips, **Figure 10** plots the average flow in the network for only vehicles within the first and last 25% of their trip for comparison. That is, flow is computed using the measures of Edie but travel distance only contributes to the flow calculation if the vehicle is within the first 25% (or last 25%) of its travel distance. The results confirm that vehicle flows are higher as density increases for vehicles at the beginning of their trips, but lower as density increases for vehicles at the end of their trips.

Furthermore, comparison of the three o-MFDs in **Figure 10** reflects that as peak demand increases, the size of the counter-clockwise loop in the o-MFD significantly increases due to more vehicles accumulated in the network during the recovery period trying to finish their trips. It is worth mentioning that simulations have also been conducted to investigate the impact of increase in demand change rate during the loading and recovery period on the hysteresis loop in the o-MFD when peak demand is held constant. Similar increase of the size of the loop in o-MFD is observed. This is expected as more rapidly varying demands will exacerbate the differences between measures of an entire trip (flow) and measures of a trip end (trip completion rate).

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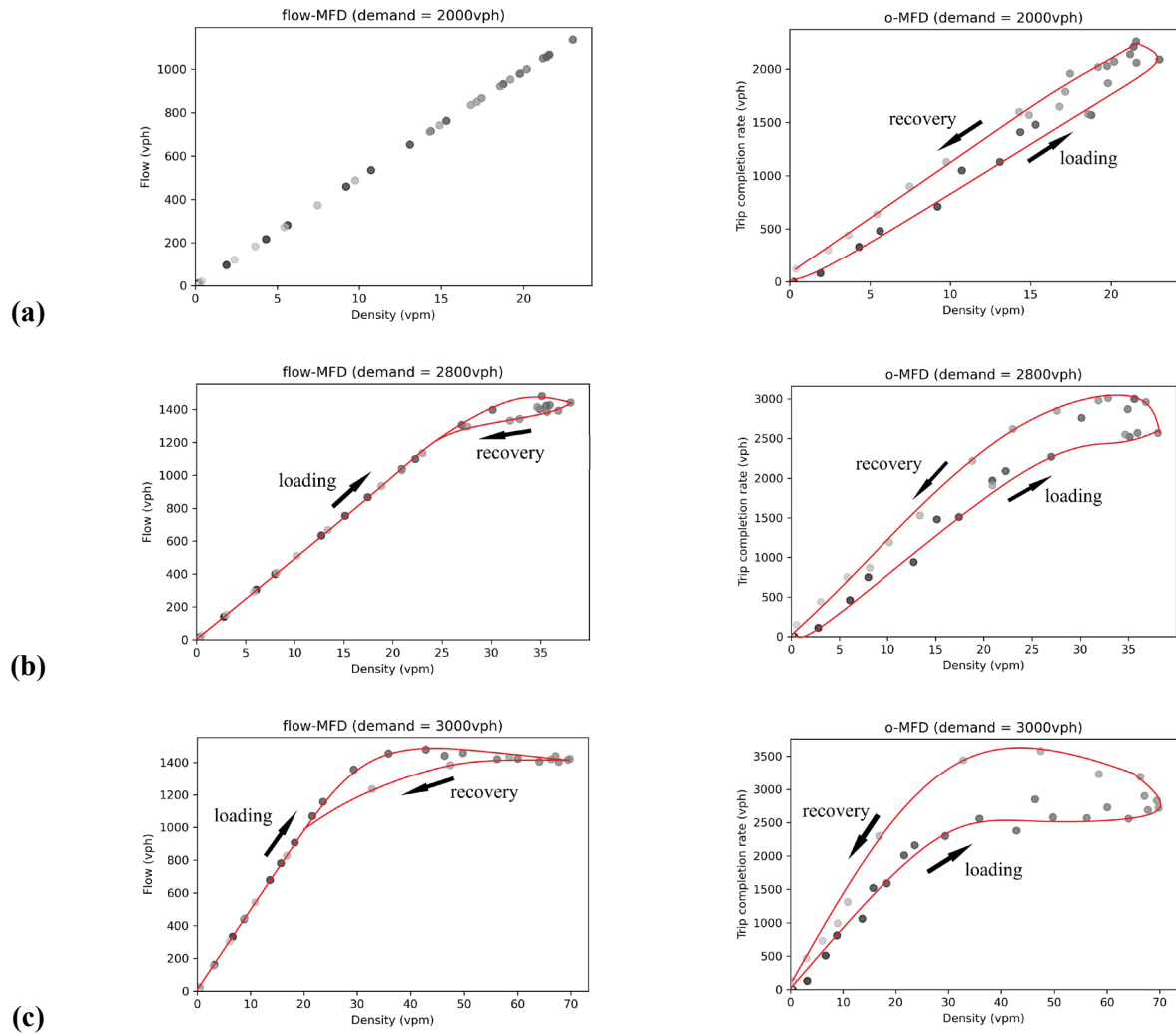


Figure 9 Flow-MFD and o-MFD under different peak demands: (a) $q_{peak} = 2000$ veh/hr; (b) $q_{peak} = 2800$ veh/hr; and, (c) $q_{peak} = 3000$ veh/hr.

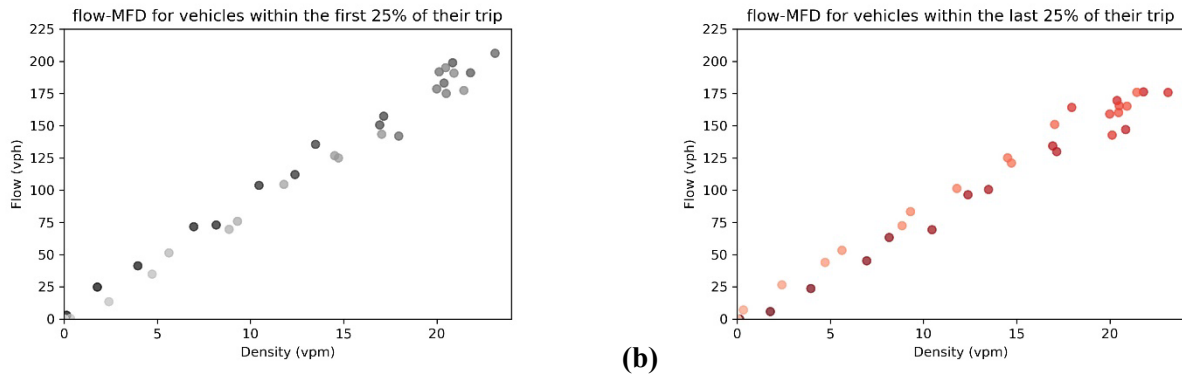


Figure 10 Average flow-MFD relationship for (a) vehicles only within the first 25% of their trips; (b) vehicles only within the last 25% of their trips.

(2) Trip distance

Next, the impact of trip distance on the size and shape of the hysteresis loops are examined. The left side of **Figure 11a, b, and c** show the flow-MFD when trip distances of all vehicles are 2.5 miles (one segment), 5 mile (two segments), and 7.5 miles (three segments), respectively. Comparison of the flow-MFDs shows that as trip distance increases, the network will get more congested due to more time that vehicles spend traveling in the network. Again, the uneven congestion during the loading and recovery period will generate a clockwise hysteresis in the flow-MFD, shown in **Figure 11c**.

The right side of **Figure 11** shows the o-MFD under all three cases. Comparison of the three o-MFDs shows that the hysteresis loop is still counter-clockwise, even as the hysteresis loop in the flow-MFD becomes larger (and is clockwise). Furthermore, the size of this loop in the o-MFD becomes more significant as trip distance increases. Two reasons account for this: 1) longer trip distances will result in a larger delay between when a trip contributes to network flow and when a trip contributes to the trip completion rate, which will enlarge the loop in the o-MFD; and, 2) the maximum accumulation (or maximum density) increases with trip distance. As is shown previously, higher maximum accumulations appear to lead to a larger loop in the o-MFD.

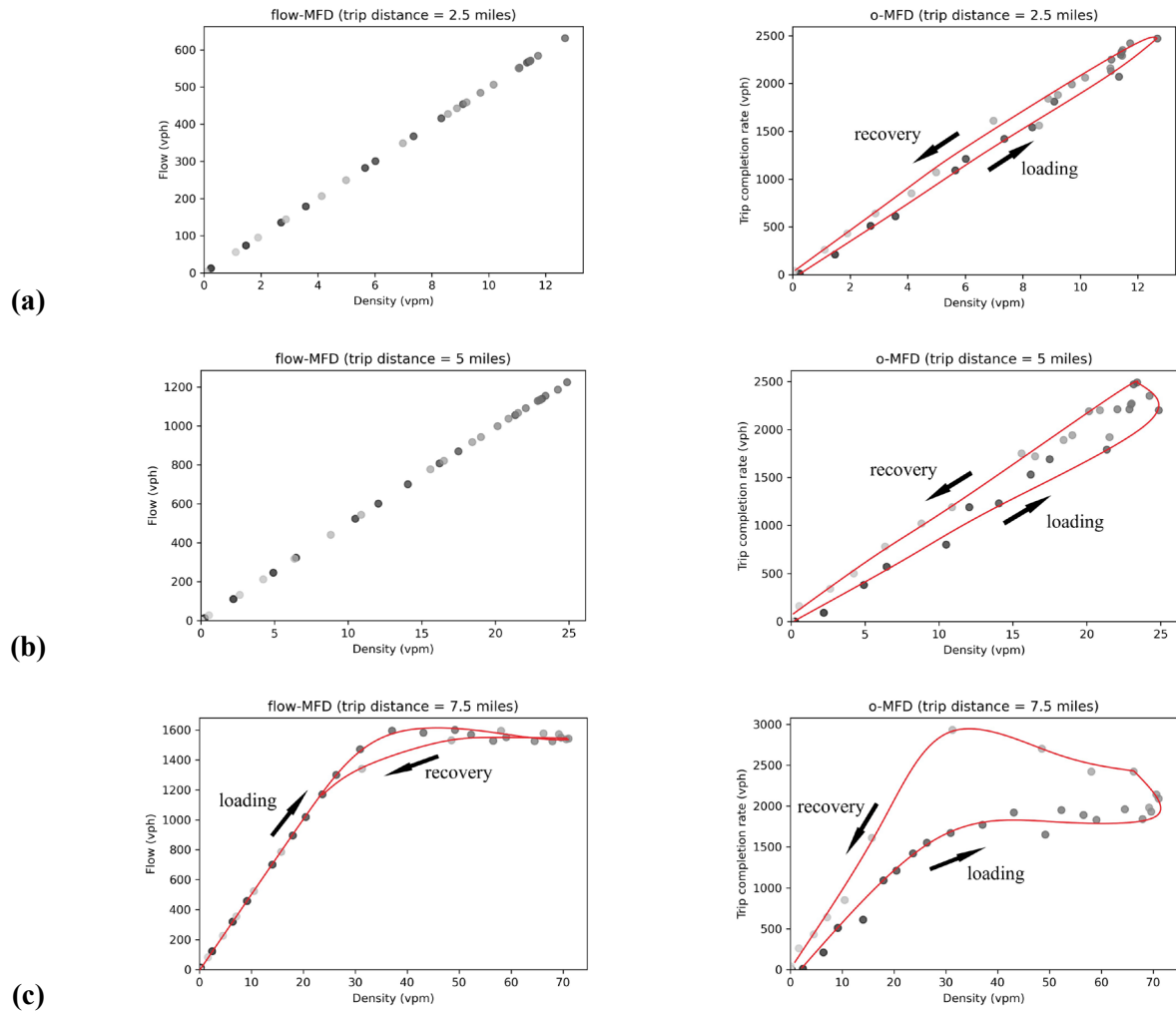


Figure 11 Flow-MFD and o-MFD under trip distance of (a) 2.5 miles; (b) 5 miles; and, (c) 7.5 miles.

(3) Demand distribution

Furthermore, we examine the impact of demand distribution on the shape of flow-MFD and o-MFD.

Figure 12a shows the case where the input demand is evenly distributed evenly across all four intersections; i.e., 25% of the total demand enters from each of the four ramps. **Figure 12b** illustrates the scenario where two opposing ramps each have 30% of total demand entering the network and the other two ramps have 20% of the entering demand each. Similarly, **Figure 12c** demonstrates the case where two opposing ramps each have 35% of the total input demand and the other two ramps have 15% each. The trip distance in all three cases is set to be 5 miles (2 segments), which means vehicles entering at one ramp will leave at the opposite ramp. Therefore, the exiting demand distribution is the same as the input demand distribution in all three cases. The results show that the network will get more congested during the peak hour and thus the size of the loop in both flow-MFD and o-MFD will become larger as demand becomes more unevenly distributed.

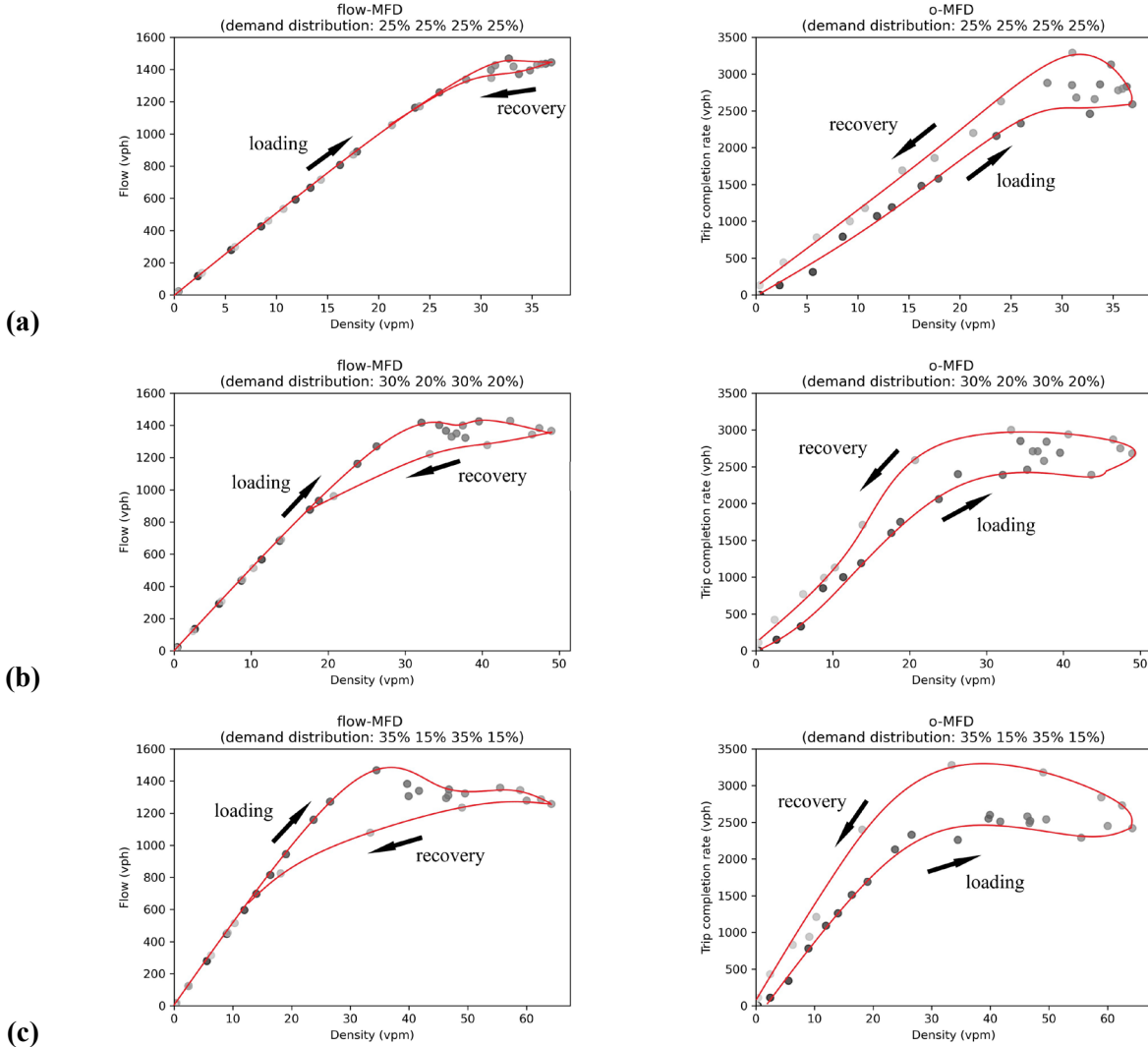


Figure 12 Flow-MFD and o-MFD under different demand distribution: (a) total demand evenly distributed at the four ramps; (b) 30%, 20%, 30%, and 20% of total demand distributed at the four ramps, respectively; and, (c) 35%, 15%, 35%, and 15% of total demand distributed at the four ramps, respectively.

(4) Randomness of trip distance

Finally, we also consider scenarios in which individual vehicle trip lengths are allowed to vary randomly but maintain a fixed mean value. **Figure 13a** shows the flow-MFD and o-MFD for the case in which all vehicles travel exactly 5 miles while **Figure 13b** and **c** show the flow-MFD and o-MFD of networks with trip distances ranging from 2.5 miles to 7.5 miles and mean of 5 miles. Clearly, the size of flow-MFD loop does not change much as trip length becomes more variable. However, the size of the o-MFD loop becomes smaller as trips vary more in length. This is because when trip distance is not fixed, the fast-completed short trips will quickly contribute to the trip completion during the loading period and will shorten the time that the maximum exit flow rate is maintained during the recovery period. As a result, the exit flow rate will be slightly higher during the loading period and slightly lower during the recovery period compared to the scenario when trip distance is fixed, leading to a smaller size of loop in the o-MFD.

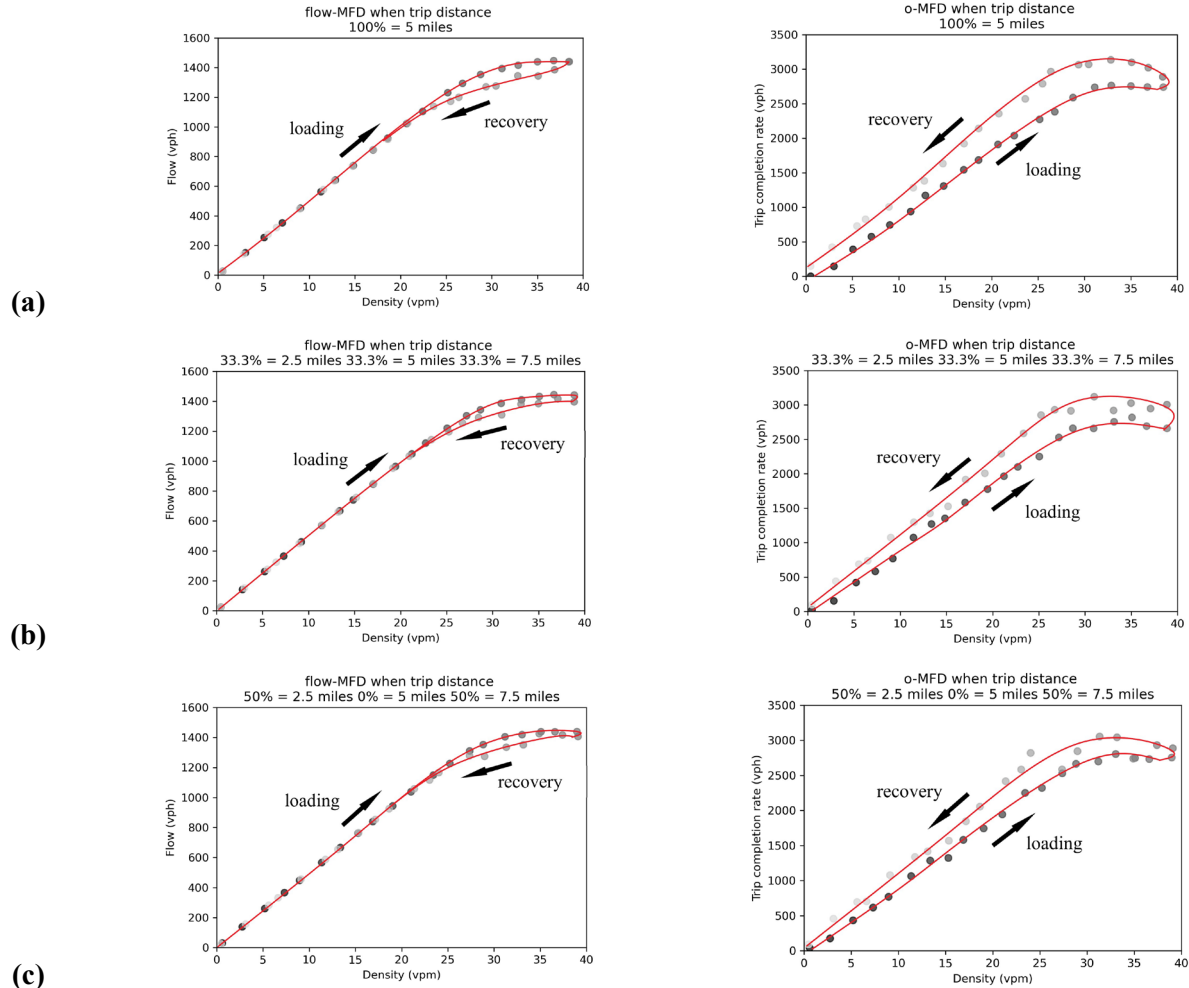


Figure 13 Flow-MFD and o-MFD under different randomness of trip distance: (a) trip distance of all vehicles = 5 miles; (b) trip distance of 33.3% vehicles = 2.5 miles, 33.3% vehicles = 5 miles, and 33.3% vehicles = 7.5 miles; and, (c) trip distance of 50% vehicles = 2.5 miles and 50% vehicles = 7.5 miles.

Two-dimensional grid network

Simulation setup

A simulation of a more realistic two-way grid network in AIMSUN is used to investigate the existence of the counter-clockwise loop and figure-eight pattern in the o-MFD. The network simulated here consists of two-way streets arranged into a simple square grid pattern, shown in **Figure 14a**. Each arterial street is 200 meters long and consists of two travel lanes which have a free flow speed of 40 km/hour and capacity of 2400 veh/hr/lane. Intersections are signalized with a signal plan consists of two phases: one for all movements of eastbound and westbound and the other for all movements of northbound and southbound. The signal has a cycle length of 60 seconds with an equal green time of 26 seconds, yellow time of 3 seconds, and all-red time of 1 second provided to both phases. The signal offsets are set to be 0.

The simulation starts with an empty network. Vehicles gradually enter the network with their origins and destinations located at all intersections (for simplicity). Trips are evenly generated between all OD pairs with an average trip distance of 2 km. The demand follows the profile shown in **Figure 14b**. This demand profile corresponds to the real-life scenario in which a moderate demand is still maintained after the peak hour.

1

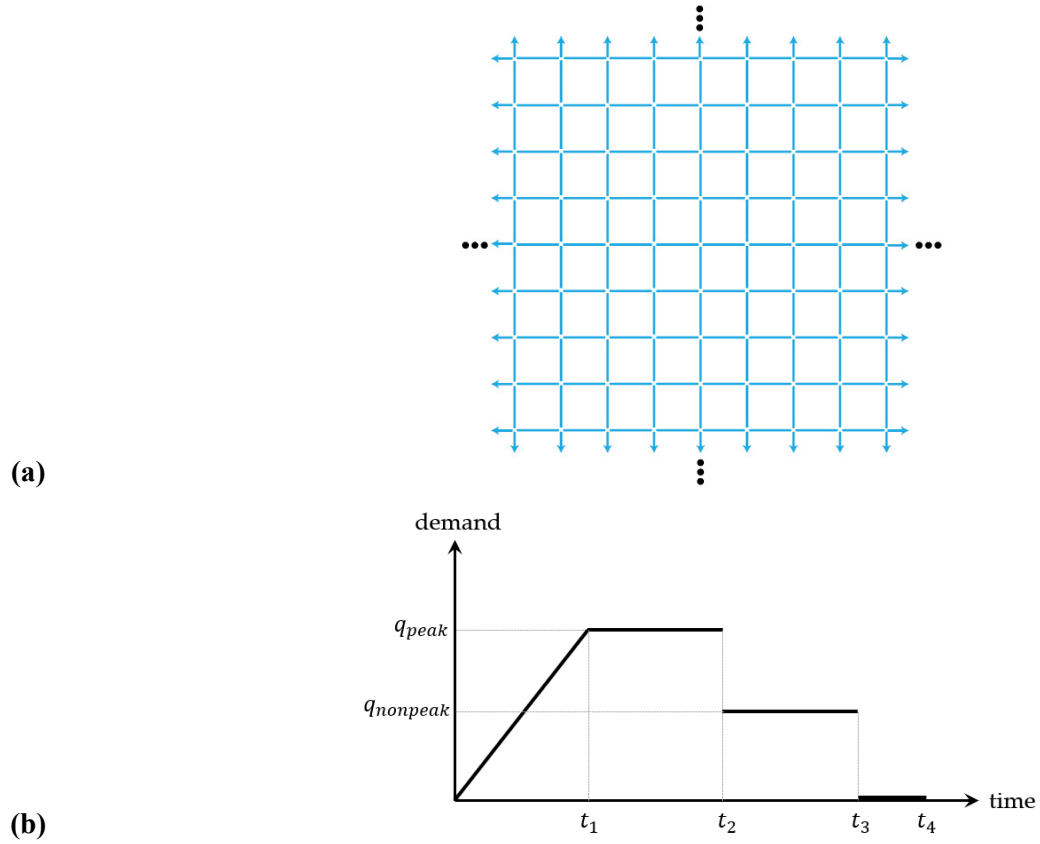


Figure 14 (a) Two-way grid network; and, (b) demand profile.

Simulation results

(1) Range of trip distance

We first investigate the impact of the range of trip distance on the hysteresis pattern in flow-MFD and o-MFD. The left side of **Figure 15a** and **b** provide flow-MFDs obtained from the simulation for trip distance ranging from 1.8 km to 2.2 km and trip distance ranging from 0.2 km to 3.8 km, respectively. As expected, a clear clockwise loop can be observed in the flow-MFD in both cases and the size of the loop does not change with the range of trip distance. The right side of **Figure 15a** and **b** provide o-MFDs for each case. It can be seen in **Figure 15a** that when the range of trip distance is small, the o-MFD has a clear counter-clockwise hysteresis pattern caused by lag of trip completion due to measurement. By comparison, when range of trip distance is large, the lag of trip completion due to the gap in trip distance causes a figure-eight pattern in the o-MFD shown in **Figure 15b**. These simulation results verify our analytical findings in previous sections.

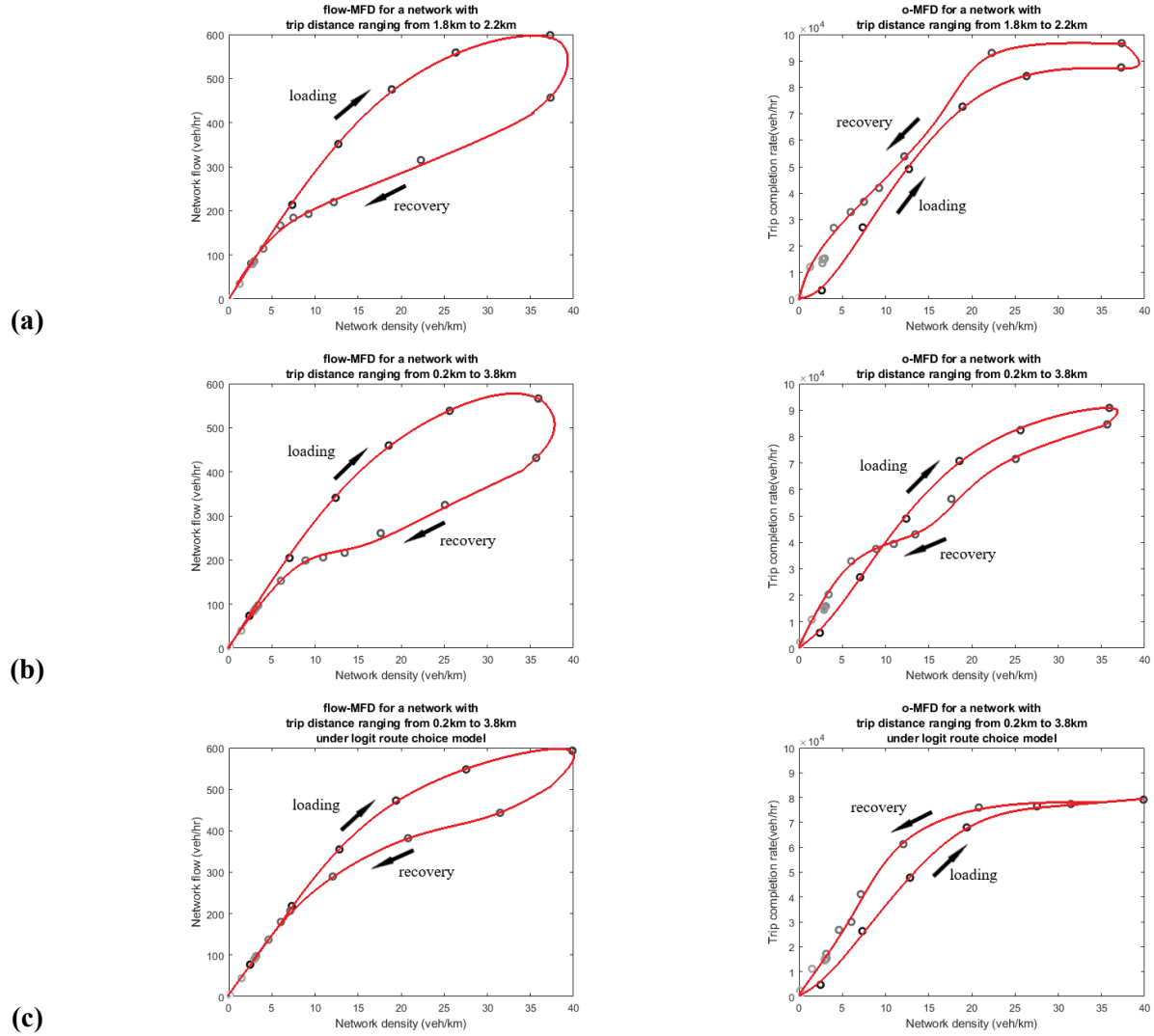


Figure 15 Flow-MFD and o-MFD from AIMSUN simulation (a) for trip distance ranging from 1.8 km to 2.2 km; (b) for trip distance ranging from 0.2 km to 3.8 km; and, (c) under logit model.

(2) Driver adaptivity

Then we investigate the impact of driver adaptivity on the hysteresis patterns. In **Figure 15b**, drivers simply take the shortest path and is not adptive to real-time congestion. Observation of the simulation shows that the center of the network is more congested than the periphery of the network resulting in a congestion imbalance. By comparison, in **Figure 15c**, a logit model embedded in AIMSUN is used. Under the logit model, drivers minimize their travel time based on the real-time speed of each road and thus are adaptive to real-time congestion. Observation of the simulation shows that vehicles are more evenly distributed in the network than vehicles in **Figure 15b**. Comparison of flow-MFDs in **Figure 15b** and **Figure 15c** reveals that when congestion is less unevenly distributed, the size of the hysteresis loop will decrease. Comparison of o-MFDs in **Figure 15b** and **c** prove that the figure-eight pattern in o-MFD is caused by lag of trip completion due to congestion imbalance.

EMPIRICAL EVIDENCE

In this section, empirical evidence is provided for hysteresis patterns in the o-MFD. First, evidence of this counter-clockwise hysteresis behavior in the o-MFD is found for an urban network in Shenzhen, China. Second, similar evidence is identified for a freeway in Dutch in the existing literature.

Shenzhen Nanshan District

Evidence for the existence of figure-8 pattern in a networks o-MFD is first obtained from empirical data in Shenzhen, China. The dataset used for this study is a large-scale vehicle location dataset captured by the App called Baidu Map (37). Data of Nanshan district in the dataset is analyzed in this paper because a higher demand is observed in this district during the peak hour. Outflow MFDs were computed using known trip completions for the set of taxis and compared to the accumulation of taxis within the region, which are assumed to be representative of typical traffic conditions.

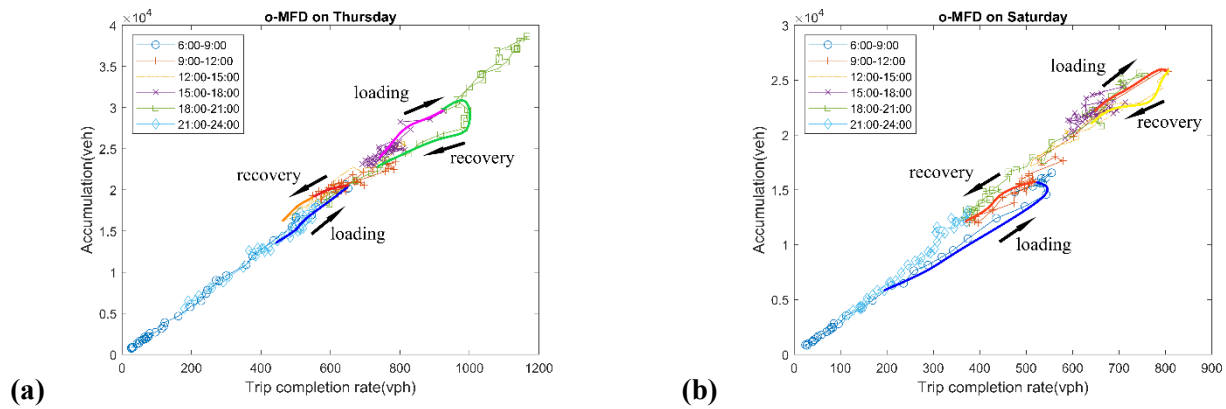


Figure 16 o-MFD in Nanshan district on (a) Thursday; and, (b) Saturday.

In **Figure 16a**, we can observe a small counter-clockwise hysteresis loop at a medium density formed by the loading period (6:00-9:00) and recovery period (9:00-12:00) and a large clockwise hysteresis loop at a higher density formed by the loading period (15:00-18:00) and recovery period (18:00-21:00). In **Figure 16b**, we can observe a large counter-clockwise hysteresis loop at a medium density formed by the loading period (6:00-9:00) and recovery period (9:00-12:00) and a small clockwise hysteresis loop at a higher density formed by the loading period (9:00-12:00) and recovery period (12:00-15:00). These prove the existence of figure-eight pattern in the o-MFD caused by lag of trip completion due to congestion imbalance in real-life urban networks.

Dutcher freeway

Furthermore, there is also empirical evidence to support the finding of figure-eight patterns in the o-MFD from existing literature. One example is provided in **Figure 17**, which shows the flow-MFD and o-MFD of Dutch freeway A13-L (38). The freeway stretch is about 16 km in length and includes 6 on-ramps and 6 off-ramps.

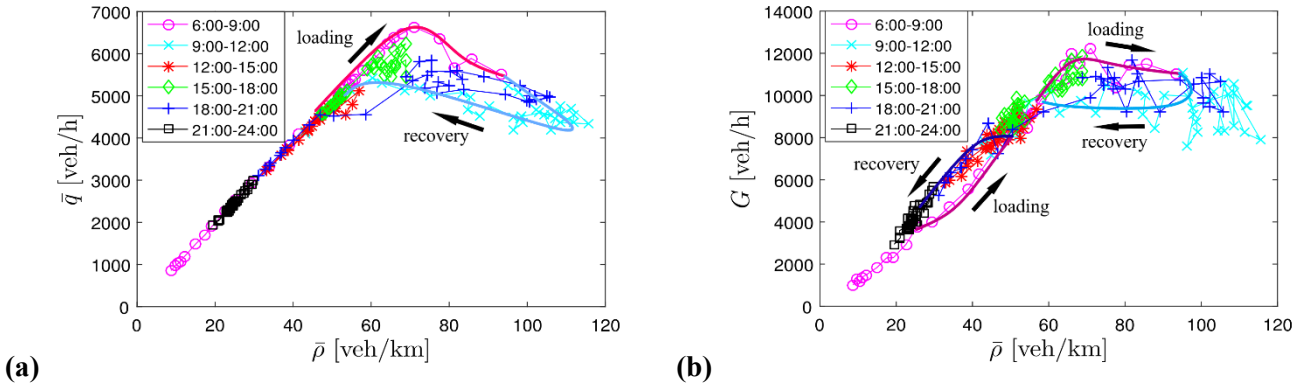


Figure 17 Example of empirical evidence from (38): (a) flow-MFD; and, (b) o-MFD.

In the flow-MFD in **Figure 17a**, we can clearly observe no hysteresis loop in the free-flow regime and a clockwise hysteresis loop in the capacity regime formed by the loading period (6:00-9:00) and recovery period (9:00-12:00). By contrast, o-MFD in **Figure 17b** has a figure-eight pattern, i.e., a counter-clockwise hysteresis loop can be seen in the free-flow regime formed by the loading period (6:00-9:00) and recovery period (21:00-24:00) while a clockwise hysteresis loop can be observed in the capacity regime formed by the loading period (6:00-9:00) and recovery period (9:00-12:00). This validates the existence of figure-eight pattern in the o-MFD caused by lag of trip completion due to the gap in trip distance.

SUMMARY OF FINDINGS AND IMPLICATIONS

This paper first studies the existence and cause of the hysteresis loop in the o-MFD of general networks under fast-varying demand. While this phenomenon has been previously attributed to the presence of bottlenecks in previous studies, we show here that this arises in the case where no bottlenecks are present using a simple arterial scenario. Instead, the counter-clockwise hysteresis loop in the o-MFD arises due to the delay between vehicles entering and exiting in the network. Specifically, vehicles only contribute to the o-MFD when they end their trip. Additionally, since vehicles contribute to the flow-MFD for the entire length of their trip but only to the o-MFD at the end of their trip, this can create opposing hysteresis patterns between the flow- and o-MFDs: the flow-MFD loop is likely to be clockwise due to congestion imbalance growth, while the o-MFD loop is counter-clockwise. Moreover, it is also shown that when the gap in trip distance or imbalance congestion causes a lag of trip completion at different locations/exits, a figure-eight pattern can arise in the o-MFD.

Then, the impacts of different network features on the size and shapes of these loops are investigated via simulations. The behavior of a ring network is first simulated using CAM. It is found that larger and more rapidly-varying traffic demands and longer, less-variable trip distances lead to larger counter-clockwise loops in the o-MFD. Then a more realistic grid network is simulated in AIMSUM. Results reveal that when the range of trip distance is small and drivers are more adaptive to congestion, a counter-clockwise hysteresis loop is expected in the o-MFD. By contrast, when the range of trip distance is large and drivers are less adaptive to congestion, a figure-eight pattern will arise in the o-MFD.

Finally, this paper provides some empirical evidence that verifies the existence of counter-clockwise loop and figure-eight pattern in a network's o-MFD under fast-varying demand.

Overall, this paper contributes to the growing literature on relationships between traffic variables aggregated across large spatial regions and how these relationships are influenced by network features. The results suggest that relationships between the flow-MFD and o-MFD that exist under steady-state conditions – specifically those shown in (1) – are not likely to describe the relationships between these models in dynamic cases, since their overall patterns are so different. This is a significant finding as very

few empirically observed o-MFDs exist in the future, even though the o-MFD is critical to MFD-based modeling frameworks for the design of regional traffic control studies and other features. Thus, new methods are needed to more accurately estimate o-MFDs in dynamic scenarios so that this tool can accurately describe traffic network dynamics. One promising source is the use of large-scale vehicle trajectory data of – e.g., the PNEUMA dataset (37) – which can be used to estimate both flow- and o-MFDs. Unfortunately, the PNEUMA dataset contains data for short, non-overlapping periods during the rush and thus cannot provide the o-MFD for an entire, continuous rush period. However, future work should be done to expand upon this type of data collection so that researchers have a better understanding of both the o-MFD under dynamical conditions and its relationship to the flow-MFD.

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AUTHOR CONTRIBUTION

The authors confirm contributions to the paper as follows: study conception and design: G. Xu, P. Zhang, V. V. Gayah, and X. Hu; analysis and interpretation of results: G. Xu, P. Zhang, V. V. Gayah, and X. Hu; draft manuscript preparation: G. Xu, P. Zhang, V. V. Gayah, and X. Hu. All authors reviewed the results and approved the final version of the manuscript.

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