

1 *Fine resolution remote sensing spectra improves estimates of gross primary production of*
2 *croplands*

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4 **Authors**

5 Gabriela Shirkey^{a,b*}, Ranjeet John^{c,d}, Jiquan Chen^{a,b,e}, Kyla Dahlin^a, Michael Abraha^{b,e,f}, Pietro Sciusco^{a,b},
6 Cheyenne Lei^{a,b}, David E. Reed^g

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8 ^aDepartment of Geography, Environment & Spatial Sciences, Michigan State University, East Lansing,
9 MI, 48823, USA

10 ^bCenter for Global Change and Earth Observations, Michigan State University, East Lansing, MI, 48823,
11 USA

12 ^cDepartment of Biology, University of South Dakota, Vermillion, SD, 57069, USA

13 ^dDepartment of Sustainability and Environment, University of South Dakota, Vermillion, SD, 57069,
14 USA

15 ^eGreat Lakes Bioenergy Research Center, Michigan State University, East Lansing, MI, 48824, USA

16 ^fW.K. Kellogg Biological Station, Michigan State University, Hickory Corners, MI, 49060, USA

17 ^gEnvironmental Science, University of Science and Arts of Oklahoma, Chickasha, OK, 73018, USA

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19 *Corresponding author: shirkeyg@msu.edu

20 **Abstract**

21 Gross primary production (GPP) is a fundamental measure of the terrestrial carbon cycle critical to our
22 understanding of ecosystem function under the changing climate and land use. Remote sensing enables
23 access to continuous spatial coverage, but remains challenged in heterogeneous croplands. Coarse
24 resolution products, like MOD17A (500 m), may aggregate fragmented land cover types commonly found
25 in heavily managed landscapes and misrepresent their respective contribution to carbon production.
26 Consequently, this study demonstrates the capability of fine-resolution imagery (20-30 m) and available
27 red-edge vegetation indices to characterize GPP across seven Midwest cropping systems. Four sites were
28 established on a 22-year-old USDA Conservation Reserve Program (CRP); and the other three on land
29 conventionally farmed with corn-soybean-wheat rotation (AGR). We compare *in situ* GPP estimates from
30 eddy-covariance towers with ten satellite models: eight variants of the vegetation photosynthesis models
31 (VPM), of which five include a red-edge vegetation index, as well as conventional products Landsat
32 CONUS GPP (30 m) and MOD17A2H V6 (500 m). Daily and cumulative fine-resolution imagery
33 integrated within VPM generally agreed with tower-based GPP in heterogeneous landscapes more than
34 those from MODIS 500 m VPM or conventional GPP products from MOD17AH V6 or Landsat 8
35 CONUS. Replacing EVI2 with red-edge indices NDRE2, NDRE1, and MTCI in Sentinel 2 VPMs notably
36 improved explanation of variance and estimation of cumulative GPP. While existing methods using
37 MODIS- and Landsat-derived GPP are important baselines for regional and global studies, future research
38 may benefit from the higher spatial, temporal, and radiometric resolution.

39 **Keywords:** LUE; GPP; Carbon; Croplands; Remote sensing; Ecosystem function

40 **Abbreviations:**

41 EC: Eddy covariance

42 CRP: Conservation Reserve Program

43 GPP: Gross primary production

44 $\text{GPP}_{\text{Tower}}$: GPP estimate from eddy covariance towers

45 $\text{GPP}_{\text{MODIS}}$: MOD17AH V6 GPP

46 $\text{GPP}_{\text{CONUS}}$: Landsat CONUS GPP

47 $\text{GPP}_{\text{VPM-MODIS}}$: Vegetation photosynthesis model with MODIS data (500 m)

48 $\text{GPP}_{\text{VPM-LS8}}$: Vegetation photosynthesis model with Landsat 8 data (30 m)

49 $\text{GPP}_{\text{VPM-S2}}$: Vegetation photosynthesis model with Sentinel-2 data (20 m)

50 NLCD: National Land Cover Database

51 LUE: Light use efficiency

52 LSWI: Land surface water index

53 PPFD: Photosynthetic photon flux density

54 VI: Vegetation Index

55 VPM: Vegetation photosynthesis model

56 $\text{VPM}_{\text{S2-Clg}}$: Vegetation photosynthesis model with Sentinel-2 (20 m) green chlorophyll index (Clg)

57 $\text{VPM}_{\text{S2-Clr}}$: Vegetation photosynthesis model with Sentinel-2 (20 m) red-edge chlorophyll index (Clr)

58 $\text{VPM}_{\text{S2-NDRE1}}$: Vegetation photosynthesis model with Sentinel-2 (20 m) normalized difference red-

59 edge index 1 (NDRE1)

60 $\text{VPM}_{\text{S2-NDRE2}}$: Vegetation photosynthesis model with Sentinel-2 (20 m) normalized difference red-

61 edge index 2 (NDRE2)

62 $\text{VPM}_{\text{S2-MTCI}}$: Vegetation photosynthesis model with Sentinel-2 (20 m) MERIS terrestrial red-edge

63 chlorophyll index (MTCI)

64 **1. Introduction**

65 Rising demands for food, biofuel, and other commodities across the globe are driving increases in
66 cropland cover and productivity (Godfray et al., 2010; Potapov et al., 2022; Tilman et al., 2011). This
67 intensity increases greenhouse gas (GHG) emissions and threatens ecosystem health through
68 fragmentation and loss of habitat (Houghton et al., 2012; USGCRP, 2018; Zabel et al., 2019). Cropland
69 and managed grasslands are the dominant land cover types of many industrial, newly industrializing as
70 well as developing countries (Bondeau et al., 2007; Foley et al., 2005), totaling 38% of the global land
71 surface (Ramankutty et al., 2008) and ~30% of global net primary production appropriated by humans
72 (Haberl et al., 2007). Given the association between cropland intensification, rising GHG emissions, and
73 threat to biodiversity and ecosystem functions, the United Nations Sustainable Development Goals
74 (SDGs) call for economies to become carbon (C) neutral by 2030 as well as to prioritize food security and
75 ecological resource protection (United Nations, 2015). To aid our understanding of how ecosystem
76 functions respond to changing climate, particularly where cropland is dominant, accurate C estimations
77 are essential.

78 Terrestrial GPP is the major driver of land C sequestration and vital to the global C balance, but is
79 highly variable in croplands due to land management practices (e.g., crop rotation, irrigation,
80 abandonment, etc.). As intensification continues, croplands will also experience an increase in terrestrial
81 gross primary production (GPP), the amount of carbon dioxide ‘fixed’ as organic material through
82 photosynthesis. In addition to physical influences and disturbances (i.e., climate, geomorphology, land
83 cover change, wildfires, floods), the magnitude and dynamics of GPP are also driven by anthropogenic
84 activities that alter land use and land cover dynamics, as well as biogeochemical cycles (Abraha et al.,
85 2018; Anav et al., 2015; Hibbard et al., 2017; Lei et al., 2021; Piao et al., 2009; Sciusco et al., 2020).
86 Therefore, it is challenging to generate specific C balance estimates within croplands (Gelybó et al.,
87 2013).

88 While GPP cannot be directly measured, it can be modeled using the eddy-covariance (EC) method,
89 which partitions net ecosystem exchange (NEE) into GPP and ecosystem respiration (Aubinet et al., 2012;

90 Baldocchi et al., 2012; Lasslop et al., 2010; Papale et al., 2006; Reichstein et al., 2005). Eddy covariance
91 field-scale measures of C, water and energy cycles have provided detailed knowledge on cropland and
92 grassland contributions to GHG exchanges, C budgets and opportunities for natural climate solutions
93 (Abraha et al., 2019; Chen et al., 2018; Hemes et al., 2021; Shao et al., 2017). At regional to global scales,
94 many studies have scaled EC tower observations using data-driven, process based models (Beer et al.,
95 2010; Jung et al., 2009) and found meteorological data have little impact on upscaled GPP with high-
96 quality satellite data (Joiner & Yoshida, 2020). Measures are scaled by evaluating the relationships
97 between tower-based GPP estimates and satellite-based, gridded and reanalysis data of climate,
98 meteorological, and surface-reflectance estimates to constrain and calibrate models that monitor
99 vegetation health and yield (Cai et al., 2021; Kumar & Mutanga, 2017; Lin et al., 2019; Wolanin et al.,
100 2019; Xiao et al., 2011). Scaling and extrapolation to regional or global representativeness should be
101 exercised with caution as it can increase uncertainty (Beer et al., 2010; Chu et al., 2017). This can be
102 understood as the Modifiable Areal Unit Problem (MAUP) that includes (1) the “scale problem”, when
103 areal data is aggregated into several sets of larger units; and (2) the “zoning problem”, when a given set of
104 areal units are recombined into zones that are of the same size but located differently. Both problems
105 result in variation in data values and subsequently different conclusions (Jelinski & Wu, 1996).

106 Similarly, the choice of model and spatial resolution may either inflate or underestimate GPP in
107 heterogeneous croplands. Model comparison is necessary, as it identifies variations that could help
108 identify shortcomings and areas for future improvement (Morales et al., 2005). Comparison is also a
109 prerequisite for analyzing spatiotemporal biosphere-atmosphere fluxes as it reveals effects from different
110 model structures (i.e., structural uncertainty) (Wang et al., 2011; Zhao et al., 2012), parameter values,
111 meteorological input data, and vegetation and soil C pools (Anav, 2015). Therefore, examination of
112 various GPP models and their spatial and temporal variations in croplands is necessary to advance our
113 understanding of land management and land use effects on the global C budget.

114 Integration of EC and remote sensing methods have greatly advanced our ability to estimate GPP.
115 However, due to the intense fragmentation, there can be a mismatch between small patches and

116 conventional remote sensing spatial resolution (Ustin & Middleton, 2021). For example, global products,
117 like the highly utilized 8-day Moderate-Resolution Imaging Spectroradiometer (MODIS) MOD17A2/A3
118 and MYD17A2/A3 GPP products (1 km–500 m), can be challenging if used in the context of land cover
119 areas with complex vegetation or mixed pixels (Running & Zhao, 2015). In fact, coarse remote sensing
120 models may aggregate nearby land cover patches within the same estimate of land cover GPP
121 productivity, introducing a mischaracterization of landscape processes (Reeves et al., 2005; F. Zhang et
122 al., 2012). To estimate GPP within fragmented landscapes under various management practices, remote
123 sensing offers several approaches to estimate GPP using measurements of optical parameters directly
124 related to vegetation activity (Damm et al., 2015; Myneni & Ross, 2012). Advancements in optical
125 sensors, such as those carried aboard Landsat-8 (2013–now) and -9 (2021–now), offer 30 m spatial
126 resolution whereas Sentinel-2 A and B (2015/2017–now) offer 10-20 m spatial resolution and narrow red-
127 edge bands—enabling phenology studies and parametrization at a much higher resolution than previously
128 possible (Li & Roy, 2017).

129 Of the primary remote-sensing based models, the most common are light use efficiency (LUE) based
130 estimates that are built on function convergence theory (Field et al., 1995; Monteith, 1972, 1977), which
131 states that plant canopies will harvest the most light to fix C given the constraints from the environment
132 (Goetz et al., 2000). Following this framework are the production efficiency models (PEMs), where GPP
133 is estimated as a product of the fraction of the photosynthetically active radiation ($f\text{PAR}$) absorbed by the
134 canopy (e.g., Goetz et al., 1999; Ruimy et al., 1999; Running et al., 2004). For example, the Landsat
135 conterminous United States (CONUS) GPP product captures fine spatial scale (30 m) variability in GPP
136 production with biome-specific inputs and provides ready-to-use product covering croplands, forests,
137 grasslands and shrublands (Robinson et al., 2018). The vegetation photosynthesis model (VPM) similarly
138 estimates GPP in various ecosystems, and its performance aligns well with EC GPP (John et al., 2013; Li
139 et al., 2007; Wagle et al., 2015; Xiao et al., 2004a; Xiao et al., 2004b; Zhang et al., 2016).

140 Further, many remote sensing-based GPP models, such as VPM, rely on vegetation indices (VI) as
141 input variables that serve as a proxy of $f\text{PAR}$ and associated nutrient and absorption characteristics. Red-

142 edge bands offered from the Sentinel-2A and B satellites offer additional VIs capable of estimating GPP,
143 as vegetation red-edge (680-780 nm) captures the absorption of chlorophyll at 680 nm and higher
144 absorption at 780 nm, detecting both moderate-to-high values (Gates, D. M., Keegan, H. J., Schleter, J.
145 C., & Weidner, 1965; Gitelson & Merzlyak, 1996; Horler et al., 1983). This is significant as chlorophyll
146 has demonstrated a high sensitivity to seasonal changes and a strong relationship to GPP in croplands
147 (Clevers & Gitelson, 2013; Lin et al., 2019; Wu et al., 2008) . In addition, fine spatial resolution of the
148 Sentinel-2 data provides temporally detailed information for characterizing spatially heterogeneous GPP
149 best in croplands and grasslands compared to forest sites (Lin et al., 2019). Across grassland sites in
150 southeast Australia, Sentinel-2 red-edge data estimates of GPP agreed well with EC GPP ($R^2 = 0.77$ and
151 $RMSE = 0.81 \text{ g C m}^{-2} \text{ day}^{-1}$) (Lin et al., 2019). Sentinel-2 and Landsat 8 data have also been used to
152 estimate a neural network GPP model on five crop fields (four in the USA and one in Germany) ($R^2 =$
153 0.92 and $RMSE = 1.38 \text{ g C m}^{-2} \text{ day}^{-1}$) (Wolanin et al., 2019). EVI2-derived GPP from MODIS (500m,
154 250m) and Sentinel-2 (10m) and EC-derived were evaluated in eight sites in the Nordic region ($R^2 = 0.69$ -
155 0.91 and $RMSE = 0.49-2.19 \text{ g C m}^{-2} \text{ day}^{-1}$) (Cai et al., 2021). Few studies, however, cross-compare
156 product resolutions in VPM to investigate changes across scales within the same cover type; or have
157 tested red-edge VIs. More commonly, VPM is cross-evaluated with other GPP products, such as MOD17,
158 a temperature and greenness model, a greenness and radiation model, and the EC-LUE model (F. Li et al.,
159 2013; Chaoyang Wu et al., 2011). Therefore, red-edge VIs from Sentinel-2 integrated into the VPM may
160 enhance our ability to estimate GPP in heterogeneous croplands (Chen et al., 2011; Turner et al., 2003).

161 In this study, we evaluate whether GPP estimates derived using higher spatial resolution of satellite
162 data is advantageous to conventional remote sensing products in managed croplands. We ask the
163 following questions: (1) Can fine resolution GPP products built with red-edge VIs effectively capture
164 significant differences at field-scale? (2) Are they significantly different from the conventionally used
165 models—MOD17A2H V6 (500m) and Landsat-8 CONUS (30m)? and (3) How consistent are GPP
166 anomalies across models within each site? While coarse resolution GPP products are reasonable for
167 studies of large spatial extents, like global and regional (Running & Zhao, 2015), local-scale estimates of

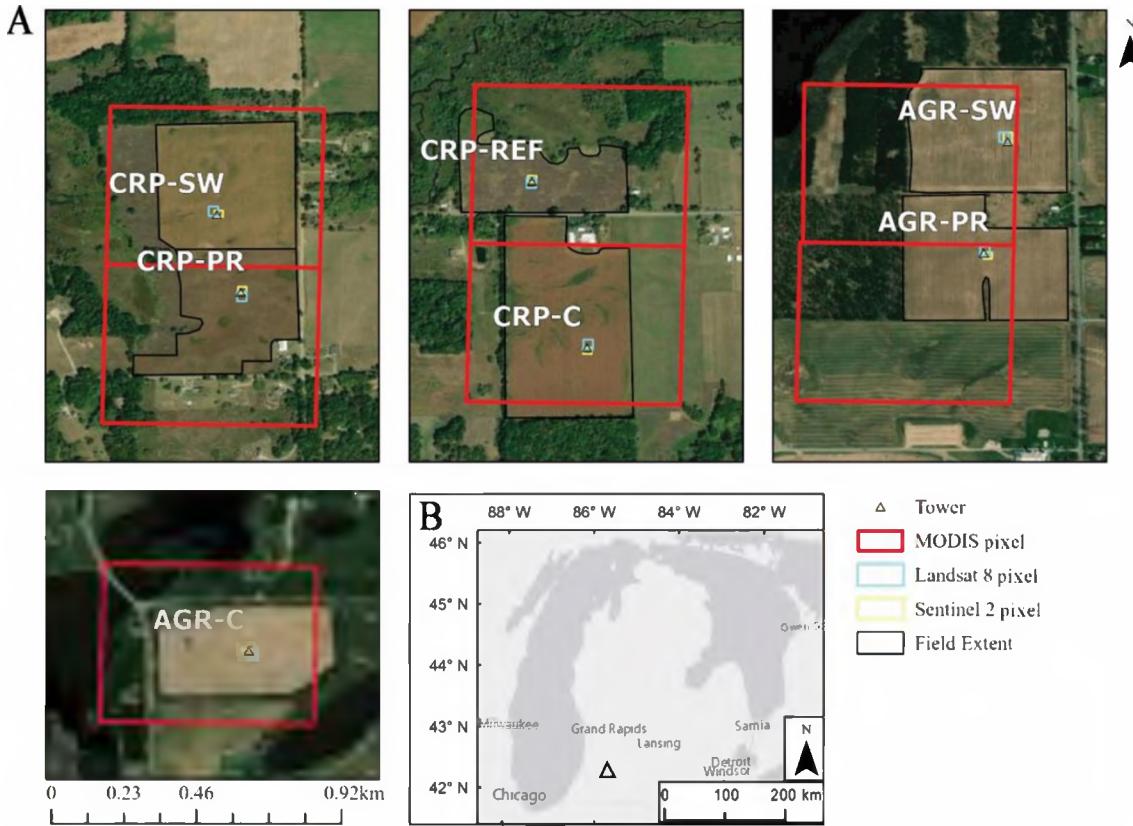
168 GPP are needed for local-scale management, estimates of C sequestration, and for C accounting. We
169 generate site-specific LUE coefficients and model GPP, utilizing the VPM across MODIS (500 m),
170 Landsat-8 (30 m), and Sentinel-2 (20 m) resolutions. By comparing multiple possible approaches to
171 estimating GPP, we show which products are the most accurate in our managed cropping systems.

172 **Methods**

173 *2.1. Study sites*

174 Our study sites are located within the northeast portion of the US Midwest Corn Belt in southwest
175 Michigan, USA, at the Great Lakes Bioenergy Research Center (GLBRC) of the W. K. Kellogg
176 Biological Station (KBS) Long-Term Ecological Research (LTER) sites (42°24' N, 85°24' W, 288m a.s.l.;
177 Figure 1, Table S1). The sites are in a humid continental temperate climate with mean annual air
178 temperature 9.9 °C and mean total annual precipitation 1027 mm (Michigan State Climatologist's Office,
179 2013). Soils are Typic Hapludalfs, well-drained sandy loams (Bhardwaj et al., 2011; Thoen, 1990). From
180 May through September, roughly representing the growing season, mean air temperature and total
181 precipitation are 19.7°C and 523 mm, respectively, with highest temperatures in July (Abraha et al.,
182 2018). Our study period spans March through November (DOY 60–334), including the growing season as
183 well as its onset and offset, for years 2018 and 2019. Precipitation, air temperature, and photosynthetic
184 photon flux density (PPFD) a nearby meteorological stations (<http://lter.kbs.msu.edu/datatables>, accessed
185 June 2020). Seasonal dynamics of GPP are driven by PPFD and temperature in these temperate croplands,
186 where GPP lowers to near-zero in the winter season — DOY 335-59 (December through February) —
187 due to near absence of photosynthetic activity caused by snow cover, harvest as well as low PPFD and
188 temperatures.

189



190
 191 Figure 1. Location of eddy-covariance (EC) flux towers used in this study, where (A) are
 192 individual field extents and individual pixels for MODIS, Landsat-8, and Sentinel-2; and
 193 (B) is the location the towers at Kellogg Biological Station, Michigan, USA.

194 We consider seven study sites that are named according to their land cover history prior to 2009 and
 195 present land cover after land use conversion (i.e., names are interpreted as HISTORIC-PRESENT, Fig. 1).
 196 Two distinct land use histories—agriculturally cultivated land (i.e., AGR-) and Conservation Reserve
 197 Program grassland (i.e., CRP-)—were used. In one group, three fields were managed as CRP grasslands
 198 for 22 years with smooth bromegrass (*Bromus inermis* Leyss)—a cool season C3 grass of Eurasian
 199 origin—as the dominant vegetation (Abraha et al., 2016). The second set of three fields included
 200 conventionally-tilled corn-soybean rotations (AGR) cultivated as such for decades prior to this study.
 201 Both groups were converted to their present land cover types in 2009. Therefore, CRP sites include: (1)
 202 no-till corn (CRP-C); (2) restored prairie (CRP-PR); and (3) switchgrass (CRP-SW); and AGR sites
 203 include (4) no-till corn (AGR-C); (5) switchgrass (AGR-SW); and (6) restored prairie (AGR-PR); and (7)

204 historically preserved CRP land (CRP-REF) (Fig. 1, Table S1). Upon conversion, the former CRP fields
205 held significantly higher soil organic C and nitrogen (N) concentrations than the former AGR fields
206 within its top 0.25m of soil (Abraha et al., 2018b; Zenone et al., 2011). The fields restored to prairie were
207 planted with a mixture of 19 species (Abraha et al., 2016). During the study period, planting dates for
208 AGR-C was May 7, 2018 (DOY 127) and May 11, 2019 (DOY 131); whereas for CRP-C it occurred on
209 May 2, 2018 (DOY 122) and May 6, 2019 (DOY 126).

210 *2.2. Eddy covariance*

211 All EC systems included a LI-7500 open-path infrared gas analyzer (IRGA, LI-COR Bioscience, Lincoln,
212 NE) for CO₂ and water (H₂O) concentration and a CSAT3 three-dimensional sonic anemometer
213 (Campbell Scientific Inc. CSI, Logan, UT) for wind speed and direction measurements. Half-hourly
214 meteorological measurements of incoming and outgoing radiation (CNR1, Kipp & Zonen, Delft, The
215 Netherlands) and air temperature and relative humidity (HMP45C, CSI) were also measured at each site.
216 All EC instruments are mounted 1.5–2.0 m above the vegetation and logged at 10Hz using a Campbell
217 CR5000 datalogger. Half-hourly fluxes were processed in EdiRe for screening out-of-range data due to
218 bad weather, sensors, and/or logger malfunction as well as de-spiking. For full data quality control details,
219 please see Abraha *et al.* (2015).

220 Gapfilling and flux partitioning was completed in the standardized FLUXNET gap-filling algorithm
221 from REddyProc (Wutzler et al., 2018). Gap-filling included a Ustar correction with thresholds estimated
222 using the Moving Point Test (Papale et al., 2006), bootstrap uncertainty within the year, and flux
223 partitioning by daytime (Lasslop et al., 2010). We used quality control flags (“*fqc*”) of 0-3 in this study,
224 where least reliable (i.e., *fqc*=3) estimates comprised less than 0.54% of any site-year, and values outside
225 of three standard deviations were linearly interpolated with the package “*seismicRoll*” (Callahan et al.,
226 2020) in RStudio 1.3.1056 (R Core Team, 2019). We present GPP uncertainty across aggregated values
227 due to estimation of the Ustar threshold, as well as the percent NEE gap-filled prior to partitioning.

228 *2.3. Satellite products and indices*

229 We obtained GPP (kg C m^{-2}) from the MODIS MOD17A2H V6 product (8-day revisit time and 500 m
230 resolution; hereafter $\text{GPP}_{\text{MODIS}}$) and the Landsat 8 CONUS product (16-day revisit time and 30 m
231 resolution; hereafter $\text{GPP}_{\text{CONUS}}$) (Robinson et al., 2018). Both $\text{GPP}_{\text{MODIS}}$ and $\text{GPP}_{\text{CONUS}}$ were retrieved
232 from Google Earth Engine (GEE) platform (Gorelick et al., 2017) using point sampling to select the
233 nearest pixel to the site's tower location. We considered only pixels nearby each tower, which brought us
234 to consider 1 (500x500 m) MODIS pixel and 3x3 Landsat-8 (30x30 m) and Sentinel-2 (20x20 m) pixels.
235 The models used to calculate $\text{GPP}_{\text{MODIS}}$ and $\text{GPP}_{\text{CONUS}}$ are based on the LUE model (Running et al.,
236 2004). However $\text{GPP}_{\text{MODIS}}$ retrieves climate, land cover, $f\text{PAR}$ and LAI parameters from GMAO/NASA
237 (0.5°), MOD12Q1 (500 m), and MOD15A2H (500 m), respectively, whereas $\text{GPP}_{\text{CONUS}}$ retrieves these
238 parameters from Idaho Metdata (4 km), National Land Cover Database (NLCD; 30 m), and MOD09Q1
239 (250 m), respectively. To derive daily estimates, composite images $\text{GPP}_{\text{MODIS}}$ and $\text{GPP}_{\text{CONUS}}$ were divided
240 by 8 and 16, respectively, and multiplied by 1000 to convert from kg C to g C , with final GPP units being
241 expressed as $\text{g C m}^{-2} \text{ d}^{-1}$.

242 For VPM (Section 2.4), we used surface reflectance from MODIS, Landsat-8 and Sentinel-2
243 (acquisition details below) to calculate vegetation indices (VIs). The VIs include (1) the enhanced
244 vegetation index 2 (EVI2) (Jiang et al., 2008) to account for moisture sensitivity; (2) the land surface
245 water index (LSWI) (Xiao et al., 2004b), which is based on the shortwave-infrared (SWIR) and represents
246 vegetation water content and soil moisture. In place of EVI2, we also test VIs including (3) the green
247 Chlorophyll Index (CIg) and red-edge (4) Chlorophyll Index (CIr) (Gitelson et al., 2003, 2006); the (5)
248 normal deviation index of the red edge 1 (NDRE1) (Sims & Gamon, 2002) and (6) normal deviation
249 index of the red edge 2 (NDRE2) (Barnes et al., 2000); as well as the (7) medium-resolution imaging
250 spectrometer, MERIS, terrestrial chlorophyll index (MTCI) (Dash & Curran, 2004). Surface reflectance
251 and land surface temperature layers were quality checked and linearly interpolated for a representative
252 time series.

253 The MODIS MOD09A1 v006 product provides surface reflectance at 500 m resolution every 8 days
254 and it was used to calculate VIs using red (620–670 nm), near-infrared (NIR; 841–875 nm) and SWIR

255 (1628–1652 nm) bands. MODIS Terra has an overpass at 10:30 AM local time. Data was acquired using
256 the USGS AppEEARS online tool (<https://lpdaac.usgs.gov/tools/appears/>, accessed January 2021) and
257 screened for cloud cover and artefacts using QA/QC bits and 500m state flags, as instructed by the
258 MODIS User Guide Tables 10 and 13, to select the best quality data (Vermote et al., 2015). Gaps due to
259 poor quality were linearly interpolated. USGS Landsat 8 surface reflectance (Tier 1) provided 30 m
260 resolution imagery every 16 days to calculate VIs EVI2 (Eq. 4) and LSWI (Eq. 6) using red (636-673
261 nm), NIR (851-879 nm), and SWIR (1566-1651 nm). As for GPP_{LS8-VP} , we acquired Landsat 8 data
262 using GEE, and we used the pixel quality band "QA_PIXEL" to identify cloud and cloud shadow pixels

263 The Sentinel-2 is a constellation of two polar-orbiting satellites in the same sun-synchronous orbit.
264 Surface reflectance over the study area provides a high revisit time of 10 days at the equator for a single
265 and 5 days when 2 satellites under cloud-free conditions, which results in 2-3 days at mid-latitudes.
266 Overpass for Sentinel-2 is 10:30 AM local time and is a compromise for illumination and least potential
267 cloud cover, similar to the overpass time of Landsat and MODIS. Sentinel-2A spatial resolution is offered
268 at 10, 20, and 60 m with a total of 12 multispectral bands; of which, three are red edge bands. Bands used
269 (and their center wavelength) for EVI2 and LSWI include NIR (B8, 842 nm; 20 m spatial resolution), red
270 (665; 10 m spatial resolution), and SWIR (1610 nm; 20 m spatial resolution), respectively. For red-edge
271 indices (Eqs. 5-9), we also included the following: B3 (green, 560 nm), B5 (red-edge, 705 nm), B6 (red-
272 edge, 740 nm), and B7 (red-edge, 783 nm).

273 The red band was resampled to 20 m resolution to match that of NIR and SWIR. Images were
274 obtained from the Copernicus Open Access Hub (<https://scihub.copernicus.eu/dhus/#/home>, accessed
275 February 2021) of the European Space Agency. We downloaded images as level 2A (i.e., surface
276 reflectance) over the study area. Where level 2A was not available, we downloaded level 1C top-of-
277 atmosphere (TOA) images that were then atmospherically corrected to obtain surface reflectance by using
278 the default settings of the Sen2Cor (v. 2.5.5) algorithm (Müller-Wilm et al., 2018). We performed the
279 cloud mask in RStudio by using the cloud mask probability band "MSK_CLDPRB", to identify cloud
280 pixels, and the scene classification map band "SCL", to identify water pixels. We then used a NIR

281 thresholds to identify potential cloud shadow pixels (for more info, see
282 <https://developers.google.com/earth-engine/tutorials/community/sentinel-2-s2cloudless>). We employed
283 ArcMap (v. 10.6) to rescale the surface reflectance to 0–1.

284 Lastly, to understand how heterogeneous systems can benefit from fine-resolution imagery, we
285 estimate the composition (30 m) of land cover type within each of the remote sensing pixels employed to
286 estimate GPP, described above, within ArcGIS Pro (v. 2.9). We acquired land cover from the USGS
287 National Land Cover Database 2019 via GEE (Dewitz & Survey, 2021). Land cover estimates included
288 cropland, water, wetland, grassland, wetlands, developed and forest; where grassland includes pasture,
289 hay, grassland, shrub/scrub, wetlands include woody wetlands and emergent herbaceous wetlands,
290 developed includes open space, and low, middle and high intensity developed areas, and forest includes
291 evergreen, deciduous and mixed forests.

292 *2.4. Vegetation photosynthesis model (VPM)*

293 The VPM model is built similarly to the GPP_{MODIS} equation (Xiao et al., 2004a; Xiao et al., 2004b),
294 however the difference lies in the creation of LUE (ε_g , Eq. 2) from remote sensing and meteorological
295 inputs rather than the use of a look up table, where:

296
$$VPM = \varepsilon_g \times (fPAR) \times (PAR), \quad (1)$$

297
$$\varepsilon_g = \varepsilon_{max} \times Tscalar \times Wscalar \times Pscalar \quad (2)$$

298 Here, *VPM* represents Sentinel-2, Landsat-8 and MODIS VPMs, hereafter GPP_{VPM-S2}, GPP_{VPM-LS8}, and
299 GPP_{VPM-MODIS}, respectively; *fPAR* is the fraction of photosynthetically active radiation absorbed by
300 chlorophyll, *PAR* is photosynthetically active radiation ($\mu\text{mol m}^{-2} \text{s}^{-1}$) acquired from nearby a weather
301 station (<http://lter.kbs.msu.edu/datatables>, accessed June 2020), ε_g is the LUE — the rate of CO₂ uptake
302 ($\mu\text{mol CO}_2 \text{ PAR}^{-1}$). The value of ε_{max} is maximum LUE estimated from a nonlinear hyperbolic
303 Michaelis–Menten model (Wang et al., 2010), and *Tscalar*, *Wscalar* and *Pscalar* are the scaling
304 regulators for the effects of air temperature, water and leaf phenology, respectively, on the vegetation.

305 Common in LUE models, including PEMs, is the application of $f\text{PAR}$ as a function of the normalized
 306 difference vegetation index (NDVI) (Tucker, 1979). It is well acknowledged that NDVI is constrained by
 307 sensitivity to soil moisture and saturates at high leaf densities (Huete et al., 2002). To address this, VPM
 308 applies EVI as a function of $f\text{PAR}$ for an enhanced characterization of vegetation at the global scale
 309 (Huete et al., 2006; Jiang et al., 2008; Xiao et al., 2004a). To calculate $f\text{PAR}$, EVI can act as a linear
 310 function and the coefficient α is set to 1.0 (Xiao et al., 2005; Xiao et al., 2004b). In this study, we apply
 311 EVI2 to avoid high signal to noise ratios from atmospheric interference (e.g., aerosol or residual clouds)
 312 common in blue band wavelengths (Jiang et al., 2008).

313 $f\text{PAR} = \alpha \times (\text{EVI2})$ (3)

314 $\text{EVI2} = 2.5 \frac{\text{NIR} - \text{RED}}{\text{NIR} + 2.4\text{RED} + 1}$ (4)

315 To evaluate the potential for red-edge bands available from Sentinel-2 to advance the VPM's
 316 applications, we chose to replace EVI2 with one of five red-edge VIs, Clg, Clr, NDRE1, NDRE2 and
 317 MTCI, calculated as:

318 $\text{Clg} = \frac{B7}{B3} - 1$ (5)

319 $\text{Clr} = \frac{B7}{B5} - 1$ (6)

320 $\text{NDRE1} = \frac{B6 - B5}{B6 + B5}$ (7)

321 $\text{NDRE2} = \frac{B8 - B5}{B8 + B5}$ (8)

322 $\text{MTCI} = \frac{B6 - B5}{B5 - B4}$ (9)

323 where the center of each Sentinel-2 band is as follows: B3 (560 nm), B4 (665 nm), B5 (705 nm), B6 (740
 324 nm), B7 (783 nm), B8 (842 nm).

325 Down regulation scalars $W\text{scalar}$, $T\text{scalar}$, $P\text{scalar}$ demonstrate the effects of water, temperature,
 326 and leaf phenology respectively on the vegetation's LUE. $W\text{scalar}$ is estimated as:

327 $W\text{scalar} = \frac{1 + \text{LSWI}}{1 + (\text{LSWI})\text{max}}$ (10)

328 $\text{LSWI} = \frac{\text{NIR} - \text{SWIR}}{\text{NIR} + \text{SWIR}}$ (11)

329 where $(LSWI)_{max}$ is the maximum LSWI during the growing season. $Tscalar$ measures the sensitivity of
330 photosynthesis to temperature, calculated at each time step using the equation developed for the
331 Terrestrial Ecosystem Model (Raich et al., 1991):

332
$$Tscalar = \frac{(T-T_{min})(T-T_{max})}{[(T-T_{min})(T-T_{max})] - (T-T_{opt})^2} \quad (12)$$

333 where T_{min} , T_{max} , and T_{opt} are the photosynthesis minimum, maximum, and optimal temperatures ($^{\circ}$ C),
334 respectively (Raich et al., 1991) (Table S2). If air temperature falls below T_{min} , $Tscalar$ is set to zero.
335 $Pscalar$ accounts for the effects of leaf phenology on photosynthesis at the canopy level. Calculation of
336 $Pscalar$ is dependent on the life expectancy of the leaves. $Pscalar$ has two phases when a canopy is
337 dominated by leaves with a life expectancy of one year (i.e., growing season) without replacement. From
338 bud burst to full leaf expansion, $Pscalar$ is calculated as:

339
$$Pscalar = \frac{1+LSWI}{2} \quad (13)$$

340 whereas following expansion, the $Pscalar$ is set to 1 with no alteration for senescence. Grassland systems
341 such as prairie and switchgrass are set to 1 throughout the study period (Wang et al., 2010; Xiao et al.,
342 2004a).

343 *2.5. Statistical analysis and uncertainty*

344 To understand how tower GPP estimates relate to either NDVI or EVI2, we performed sensitivity tests of
345 both indices to GPP_{Tower} acquired from MODIS, Landsat-8 and Sentinel-2 for each site-year using a
346 procedure outlined in Gitelson (2004):

347
$$S = [d(EVI2)/d(NDVI) \bullet [\Delta(EVI2)/\Delta(NDVI)]]^{-1} \quad (14)$$

348 where $d(EVI2)$ and $d(NDVI)$ are the first derivatives of the indices with respect to GPP_{Tower} and $\Delta(EVI2)$
349 and $\Delta(NDVI)$ are the differences between the maximum and minimum index, respectively. The function S
350 tracks the sensitivity of EVI2 and NDVI to changes in GPP_{Tower} . Values of $S < 1$ can be interpreted where
351 NDVI is more sensitive than EVI2 to GPP_{Tower} , and values $S > 1$ as indicate that EVI2 was more sensitive
352 than NDVI to GPP_{Tower} . When $S = 1$, NDVI and EVI2 are assumed to be equally sensitive. We

353 acknowledge that S does not account for estimate errors of $d(\text{EVI2})/d(\text{NDVI})$, which may bias sensitivity
354 evaluations

355 We evaluated seasonal dynamics of PPFD, air temperature, precipitation, as well as EVI2 and NDVI
356 from MODIS, Landsat-8 and Sentinel-2 in a time series alongside $\text{GPP}_{\text{Tower}}$ for each site-year. A
357 comparison of GPP sums during the study period (March–November) and growing season (June, July,
358 August) evaluates differences between $\text{GPP}_{\text{MODIS}}$, $\text{GPP}_{\text{VPM-MODIS}}$, $\text{GPP}_{\text{VPM-LS8}}$, $\text{GPP}_{\text{VPM-S2}}$, $\text{GPP}_{\text{CONUS}}$, and
359 $\text{GPP}_{\text{Tower}}$. Days without estimates from the VPM model or other products (i.e., days in-between
360 acquisitions) were linearly interpolated within the R package “zoo” to generate cumulative GPP estimates
361 (Zeileis & Grothendieck, 2005).

362 Three metrics were used to evaluate the performance of GPP satellite estimates in comparison with
363 $\text{GPP}_{\text{Tower}}$, including the coefficient of determination (adjusted R^2 , hereafter R^2), root mean square error
364 (RMSE), and Spearman’s Rho (ρ), which is a non-parametric test that estimates the model’s ability to
365 increase or decrease in a similar trend to observed values. Estimates closer to 1 indicate a positive
366 relationship and those closer to -1 indicate a negative relationship. In the linear models, we only included
367 original acquisition days (i.e., days corresponding to satellite acquisitions) that paired tower estimates. To
368 assess model implications on GPP estimates, and by proxy the resolution implications, we tested for
369 significant difference in GPP models among sites with the Kruskal-Wallis test and Dunn post-hoc test in
370 the R packages “stats” and “dunn.test” (Dinno, 2017; Dunn, 1964; Kruskal & Wallis, 1952; R Core
371 Team, 2019). The Kruskal-Wallis test extends from the Wilcoxon Rank test that is used for two samples
372 (Vargha & Delaney, 1998), and determines if there is a significant difference (p -value <0.05) in the
373 median GPP estimate between models. It replaces a one-way analysis of variance (ANOVA) when data is
374 not normally distributed. The result of the Kruskal-Wallis is H , which is interpreted as chi-square; and z is
375 result of the Dunn’s Test for multiple comparisons.

376 Since our study area has strong seasonal changes of temperate zones, our data and predictions
377 violate the statistical assumptions that they are independent and identically distributed. We address this

378 concern of temporal autocorrelation in a second regression analysis by removing interannual and seasonal
379 variation from each time series. We estimated zero-centered daily GPP anomalies and evaluated how
380 these anomalies vary by GPP model and site-year. To generate average GPP seasonality (GPPS) on a
381 daily time step (t) for each site (x) we averaged the daily GPP estimates from the different approaches for
382 each year then smoothed the result with a Gaussian blur of 15 days to remove noise using the R package
383 “smoother” (Hamilton, 2015). To remove interannual differences, we calculated $GPP_{x,yr}$ as the site-year
384 annual mean of all GPP models. GPP anomalies (GPPA) were thus calculated as:

$$GPPA_{x,t} = GPP_{x,t} - GPPS_{x,t} - GPP_{x,yr} \quad (15)$$

385 Therefore, when an anomaly estimate is near-zero it has a small difference from the average,
386 zero-centered seasonal pattern. Once we calculated daily GPPA (Eq. 15), we only included estimates that
387 coincide with model acquisition dates to avoid inflation in our analysis. In the linear regression of
388 anomalies, models agreeing well with GPP_{Tower} will express similar values (i.e., differences from the
389 mean) with GPP_{Tower} . In the linear regression of anomalies, models agreeing well with GPP_{Tower} will
390 express similar values (i.e., differences from the mean) with GPP_{Tower} .
391

392 3. Results

393 3.1. Seasonal changes of climate, vegetation indices and tower GPP

394 Seasonal changes in air temperature, precipitation and PPFD at the LTER/KBS (i.e., study area) revealed
395 that 2018 was on average warmer and drier than 2019 during the study period (March-November) (Fig.
396 S1). For the study area in 2018, there was an average air temperature of 10.59 °C and a cumulative 796
397 mm of precipitation; whereas 2019 had an average air temperature of 9.25 °C and cumulative 896 mm of
398 precipitation. We found GPP_{Tower} increased sharply in May of both years at in all site-years (Fig. 2) due to
399 the temperature increase, where the study area’s monthly average air temperature from April to May
400 increased from 4.49 °C to 18.18 °C in 2018, and 8.47 °C to 13.97 °C in 2019. We also found the study
401 area in 2019 had notably higher cumulative monthly and average daily precipitation in spring months
402 reaching 114(2.8), 92(2.97), and 173(5.77) mm in April, May and June; whereas 2018 had 63(2.1),

403 220(7.10), and 80(2.67) mm, respectively. GPP_{Tower} uncertainty due to Ustar filtering for all site-years
404 was < 3% (0.81–2.97%), with <28% (16.16–27.51%) of NEE identified for gapfilling (Table S4).

405 We found that MODIS 500 m pixels do not well represent each study site and include large
406 aggregations of neighboring land covers (Table S3). One MODIS pixel including a tower may overlap
407 two fields or nearby forest and marshland (Fig. 1). Conversely, the resolution of Sentinel-2 and Landsat 8
408 (20 m and 30 m, respectively) results in homogeneous pixels at each of the seven sites. Therefore,
409 reflectance and vegetation indices from Landsat 8 and Sentinel 2 are more likely to represent the land
410 cover of interest and minimize influence from neighboring vegetation. Monthly variability in GPP_{Tower}
411 during the growing season coincided well with the variations in precipitation, temperature, PPFD and
412 EVI2/red-edge VIs. The GPP_{Tower} during the growing season peaked in late July (DOY 185–217), which
413 closely coincides with peak PPFD and temperature in the study area (Fig. S1). Peak dates of daily GPP at
414 AGR-C and CRP-C from 2018 were delayed by approximately 20 days in 2019; whereas AGR-PR
415 experienced a 15-day delay, and remaining sites peaked within 11 days (Fig 2).

416 The interannual seasonal dynamics of EVI2 differs in amplitude across sites and between satellites
417 (Fig. 2). Maximum EVI2 for Sentinel-2 across sites ranged 0.65–0.86, whereas Landsat-8 and MODIS
418 ranged 0.55–0.80 and 0.59–0.68, respectively. Sentinel-2 best captured the onset, offset, and volatility of
419 the growing season. MODIS and, to a lesser extent, Landsat-8 EVI2 trends often exhibited lower
420 estimates near the growing season peak. Notably, MODIS EVI2 increased before GPP_{Tower} in the onset of
421 the growing season and lags in the offset, particularly in AGR-C, CRP-C, AGR-PR and CRP-REF.
422 Interannual seasonal dynamics of red-edge VIs capture peak growing season GPP well, particularly in
423 corn systems, and reach higher peaks than EVI2 in CRP-PR and CRP-REF sites (Fig. 3). Red-edge VIs
424 also demonstrate a similar trend as GPP during spring and fall in all sites.

425 MODIS EVI2 is more sensitive to variations in GPP_{Tower} ; whereas for Landsat-8 and Sentinel-2, EVI2
426 and NDVI have similar sensitivity (i.e., 0.00 ± 0.10) (Table 1). MODIS EVI2 is more sensitive to
427 GPP_{Tower} in all site years except CRP-SW in 2018. We note that historical cropland sites AGR-C, AGR-

428 PR and AGR-SW as well as CRP-REF and CRP-C have higher sensitivities to MODIS EVI2. For
429 Landsat-8, AGR-C, AGR-PR, CRP-PR and CRP-REF exhibit sensitivities to both NDVI and EVI2 in
430 different years, with CRP-C, AGR-SW and CRP-SW demonstrating higher sensitivities to NDVI in both
431 years. Similarly, Sentinel-2 saw sensitivities change between years, but exhibited slightly higher
432 sensitivity to NDVI in AGR-C, AGR-PR and CRP-SW. Overall, we found Landsat-8 sensitivities
433 remained within ± 0.10 of 1.00 (i.e., equal sensitivity) for 9:14 (i.e., 9 out of 14) site-years, respectively;
434 whereas Sentinel-2 exhibited sensitivities ± 0.10 of 1.00 within 12:14 site-years.

435 Table 1. The relative sensitivity of EVI2 to NDVI. Values of $S < 1$ indicate that NDVI is more
436 sensitive than EVI2, sensitivities are considered to be equal when $S = 1$, and values of $S > 1$
437 indicate EVI2 having a greater sensitivity than NDVI.

Site	MODIS		Landsat-8		Sentinel-2	
	2018	2019	2018	2019	2018	2019
AGR-C	1.31	1.33	1.08	0.99	0.90	0.96
AGR-PR	1.32	1.26	0.94	1.00	0.77	0.94
AGR-SW	1.30	1.22	0.94	0.92	0.99	1.01
CRP-C	1.11	1.13	0.77	0.99	0.78	1.00
CRP-PR	1.07	1.18	1.04	0.86	1.04	0.93
CRP-REF	1.20	1.21	1.22	0.81	1.01	0.91
CRP-SW	0.77	1.08	0.97	0.57	0.95	0.94

438 Differences between sensitivities of EVI2 and red-edge VIs to GPP_{Tower} vary (Table 2). In most
439 cases, NDRE1 is near similar in sensitivity to EVI2 in all sites except CRP-C, where NDRE1 is more
440 sensitive. Between NDRE2 and EVI2, most sites had near-equal sensitivities, except for AGR-SW 2018
441 where EVI2 has higher sensitivity. Both Clg and Clr show a lower sensitivity than EVI2 in all site-years
442 except in CRP-C. Lastly, sensitivities of MTCI and EVI2 were near equal in all site years except AGR-
443 SW 2018, where EVI2 has higher sensitivity. Overall, NDRE1 and NDRE2 have 8:14, Clg and Clr have
444 2:14, and MTCI 5:14 site years with higher sensitivity than EVI2 to GPP_{Tower} .

445

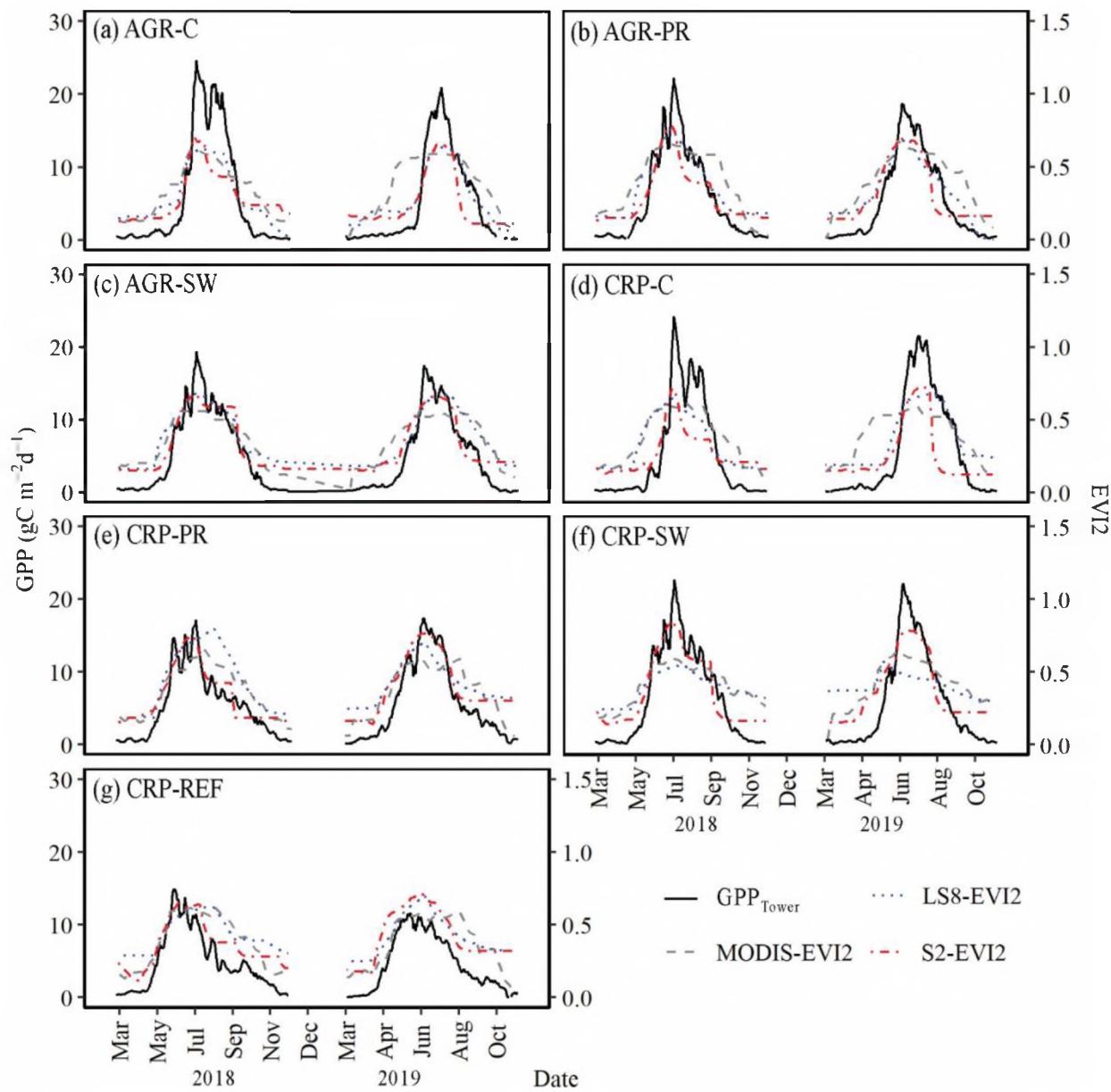
446 Table 2. The relative sensitivity of EVI2 to Sentinel-2 red-edge bands NDRE1, NDRE2, Clg, Clr,
 447 and MTCI. Values of $S < 1$ indicate that the red-edge index is more sensitive than EVI2,
 448 sensitivities are considered to be equal when $S = 1$, and values of $S > 1$ indicate EVI2 having a
 449 greater sensitivity than the respective red-edge index.

Site	NDRE1		NDRE2		Clg		Clr		MTCI	
	2018	2019	2018	2019	2018	2019	2018	2019	2018	2019
AGR-C	0.88	0.92	0.87	0.93	1.19	1.13	1.14	1.15	0.98	1.05
AGR-PR	1.08	1.06	1.08	1.09	1.43	1.27	1.34	1.25	1.05	1.06
AGR-SW	1.32	0.95	1.40	1.02	1.61	1.14	1.59	1.12	1.26	1.00
CRP-C	0.73	0.74	0.74	0.75	0.94	0.89	0.97	0.89	0.90	0.86
CRP-PR	0.96	0.93	0.93	0.93	1.26	1.08	1.16	1.08	1.05	0.99
CRP-REF	1.00	1.00	1.12	1.02	1.34	1.20	1.14	1.09	0.93	1.12
CRP-SW	0.96	0.91	0.96	0.94	1.12	1.13	1.26	1.18	1.13	1.04

450 In both years, $\text{GPP}_{\text{VPM-S2}}$ explains more variability and is statistically significant in the linear
 451 regression analysis with $\text{GPP}_{\text{Tower}}$ during the study period (Table S5). $\text{GPP}_{\text{VPM-S2}}$ demonstrates visibly
 452 higher peaks in the growing season than other models, but occasionally over estimates in 2018 (AGR-C,
 453 AGR-PR, CRP-C, CRP-PR, CRP-REF) and in 2019 (CRP-C, CRP-REF). MODIS products generally
 454 underestimate these amplitudes (Figs. 4, 5). MODIS products largely underestimate corn and switchgrass
 455 systems where $\text{GPP}_{\text{VPM-S2}}$ captured GPP dynamics. In addition, VPMs coincide with $\text{GPP}_{\text{Tower}}$ peaks and
 456 variations more than $\text{GPP}_{\text{MODIS}}$ and $\text{GPP}_{\text{CONUS}}$, particularly in corn systems. Average daily $\text{GPP}_{\text{Tower}}$ is
 457 higher in 2018 compared to 2019; where in 2018, the most productive sites (CRP-SW, AGR-C, and
 458 AGR-PR) reached $5.66\text{--}6.27 \text{ g C m}^{-2} \text{ d}^{-1}$ compared to the most productive sites in 2019 (CRP-PR, CRP-C,
 459 and CRP-SW) with a range of $5.73\text{--}5.78 \text{ g C m}^{-2} \text{ d}^{-1}$. Corn systems have the highest daily productivity in
 460 both years but experienced the greatest shift in peak dates between 2018 and 2019. In both years, the
 461 highest daily sum recorded were in sites CRP-C, AGR-C, and CRP-SW while the lowest was observed in
 462 CRP-REF.

463 When exchanging EVI2 for a red-edge VI in the Sentinel-2 VPM, there is a significant improvement
 464 across site-years. Particularly, NDRE1 and NDRE2 improve the Sentinel-2 VPM in eight out of 14 site-
 465 years compared to other red-edge VIs. In 2018, NDRE2 improves AGR-C, CRP-C, and CRP-SW by
 466 improving explanation of variation by 8%, 11% and 4%, respectively; whereas in 2019, it improves
 467 AGR-C, AGR-PR, AGR-SW, CRP-C, and CRP-SW by 7%, 4%, 3%, 16% and 4%, respectively (Table

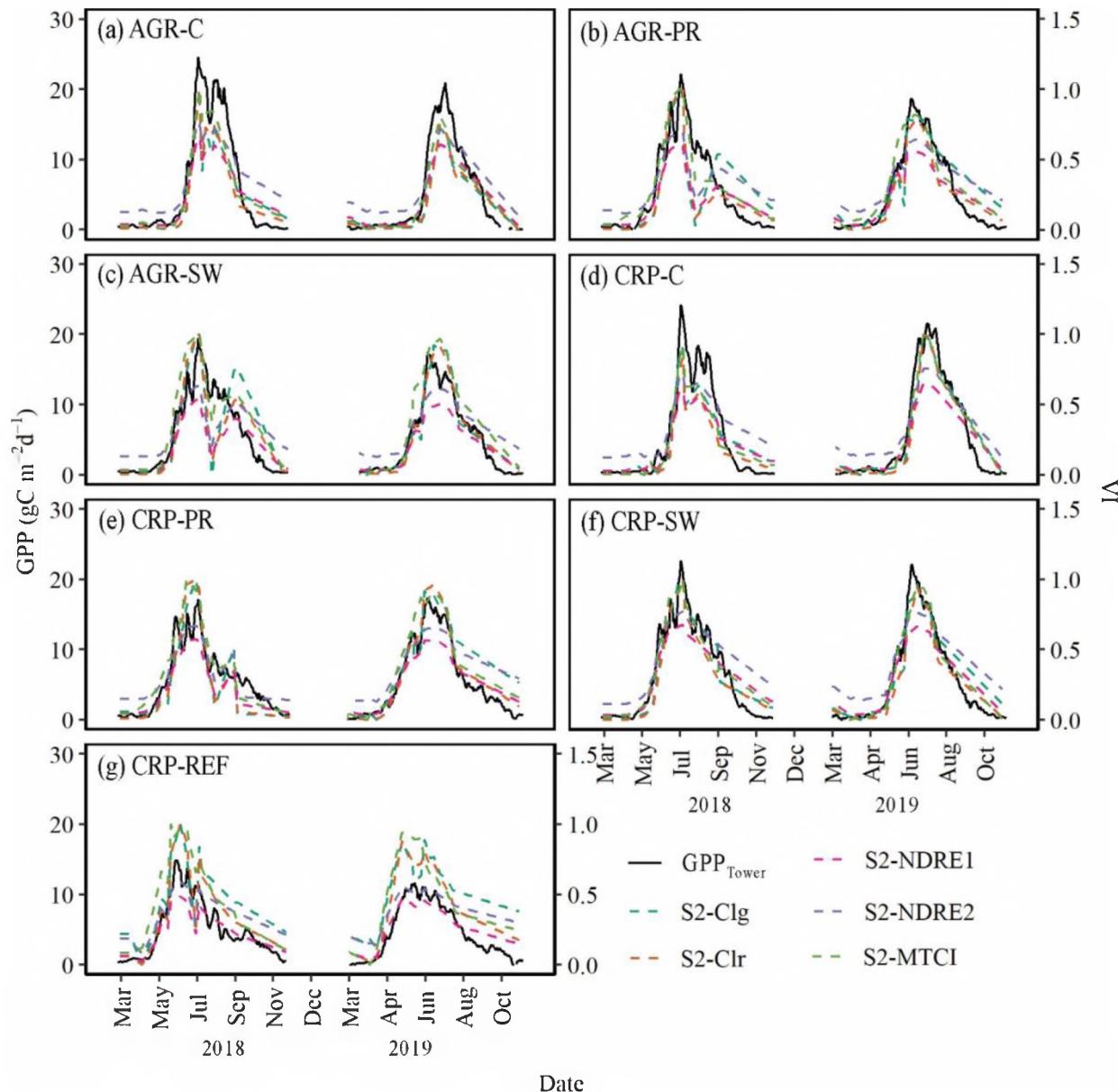
468 S5). NDRE1 also improves AGR-C in both years and CRP-C in 2018 by the same explanation of variance
 469 as NDRE2. While $\text{GPP}_{\text{VPM-LS8}}$ is better than $\text{GPP}_{\text{VPM-S2}}$ in both CRP-C site-years, but with NDRE2 the
 470 VPM improves by 11% and 16% in 2018 and 2019, respectively. Red-edge VIs NDRE1, Clr and Clg do
 471 not improve the Sentinel-2 VPM beyond that of NDRE2. While MTCI does improve the Sentinel-2 VPM
 472 in CRP-REF and explains 4% more variation and is the leading GPP model for both site-years, it still
 473 overestimates during the peak growing like $\text{GPP}_{\text{VPM-S2}}$ and $\text{VPM}_{\text{VPM-Clg}}$ (Fig. 5)



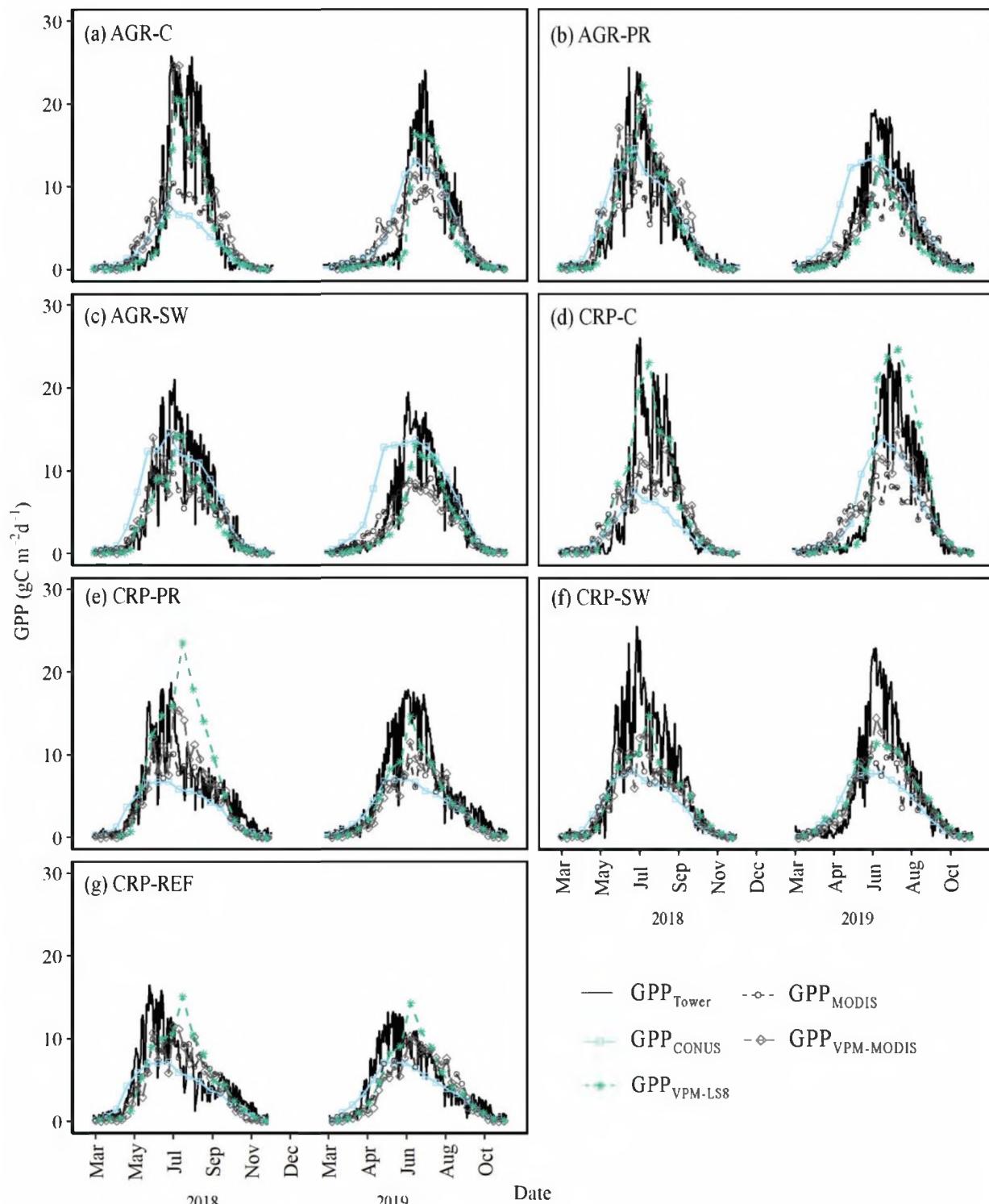
474

475 Figure 2. Daily GPP_{tower} estimates ($\text{g C m}^{-2} \text{ d}^{-1}$) as well as MODIS, Landsat-8, and Sentinel-2
 476 EVI2 at (a) AGR-C, (b) AGR-PR, (c) AGR-SW, (d) CRP-C, (e) CRP-PR, (f) CRP-SW, and (g)
 477 CRP-REF sites 2018–2019.

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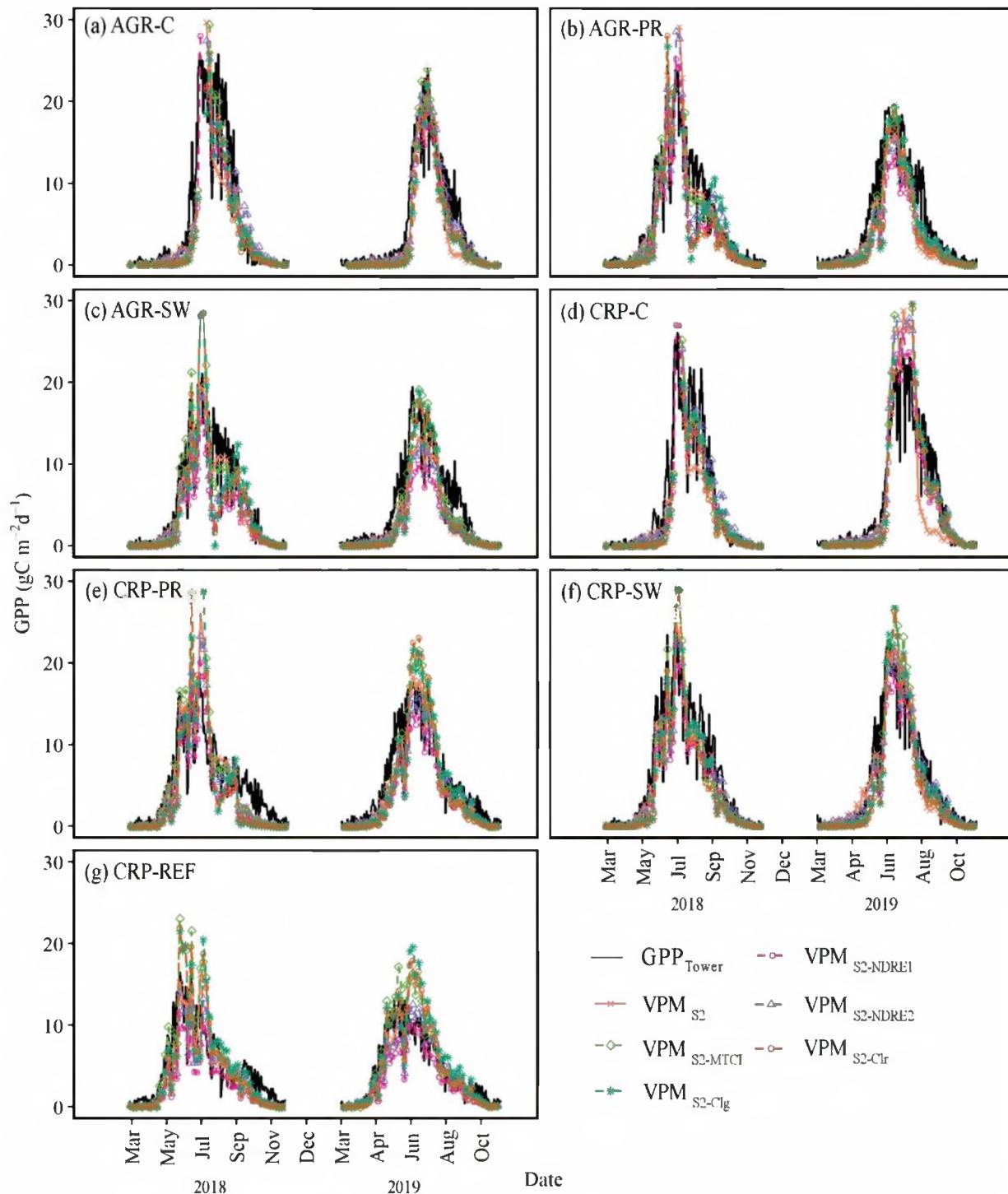


481
482 Figure 3. Daily GPP_{tower} estimates ($\text{g C m}^{-2} \text{ d}^{-1}$) as well as Sentinel-2 red edge vegetation indices
 483 Clg, Clr, NDRE1, NDRE2, and MTCI at (a) AGR-C, (b) AGR-PR, (c) AGR-SW, (d) CRP-C, (e)
 484 CRP-PR, (f) CRP-SW, and (g) CRP-REF sites 2018–2019.



485

486 Figure 4. Temporal changes in $\text{GPP}_{\text{Tower}}$, conventional and VPMs including CONUS and MODIS
 487 resolutions 2018–2019 for the seven study sites: (a) AGR-C, (b) AGR-PR, (c) AGR-SW, (d) CRP-C, (e)
 488 CRP-PR, (f), CRP-SW, and (g) CRP-REF.



489

490 Figure 5. Temporal changes in GPP_{Tower} and Sentinel-2 VPM RS models 2018–2019 for the seven
 491 study sites: (a) AGR-C, (b) AGR-PR, (c) AGR-SW, (d) CRP-C, (e) CRP-PR, (f) CRP-SW, and
 492 (g) CRP-REF.

493 During the study period, GPP_{VPM-S2} estimated 5:14 site-year sums at $\pm 10\%$ that of GPP_{Tower} sums,
494 whereas GPP_{VPM-LS8} had 3:14, GPP_{VPM-MODIS} 2:14, GPP_{MODIS} had 0:14, and GPP_{CONUS} 3:14 (Table 3). When
495 using red-edge VIs, VPM_{S2-NDRE1} models estimated 1:14, VPM_{S2-NDRE2} 5:14, VPM_{S2-MTCI} 6:14, VPM_{S2-Clg}
496 4:14, and VPM_{S2-Clr} had 2:14 site-year sums at $\pm 10\%$ that of GPP_{Tower}. Overall, Sentinel-2 VPMs were
497 closer to the study-period sums of GPP_{Tower} than other models. Cumulative satellite GPP estimates by site-
498 year had difference of $\sim 9\text{--}800 \text{ g C m}^{-2}$ from GPP_{Tower}, with an average difference of $229.69 \text{ g C m}^{-2}$.
499 Models that had a site within $\pm 10\%$ of GPP_{Tower} in both 2018 and 2019 included GPP_{VPM-LS8}, VPM_{S2-}
500 NDRE2, VPM_{S2-Clr} for sites CRP-REF, CRP-C, and CRP-REF, respectively. Model VPM_{S2-MTCI} remained
501 within $\pm 10\%$ of GPP_{Tower} more often than other models including by site-year and cumulative annual GPP
502 during the study period. GPP_{MODIS} and VPM_{S2-NDRE1} underestimated all site-years, but other models
503 overestimated occasionally, including GPP_{VPM-LS8} (5:14), GPP_{VPM-MODIS} (2:14), GPP_{CONUS} (4:14), VPM_{S2-}
504 NDRE2 (1:14), VPM_{S2-MTCI} (5:14), VPM_{S2-Clg} (2:14), and VPM_{S2-Clr} (2:14).

505 Cumulative GPP for the peak growing season (June, July, and August) indicate that VPM_{S2-NDRE2} and
506 VPM_{S2-MTCI} best matched GPP_{Tower}, with 8:14 site-years within $\pm 10\%$ tower sums (Table 4). Non-red-edge
507 model GPP_{VPM-S2} closely followed with 7:14 site-years. When estimated by GPP_{VPM-LS8} and GPP_{VPM-S2} in
508 2018 and by GPP_{VPM-S2} in 2019, cumulative GPP of all sites in the study area was within $\pm 10\%$ of that
509 estimated by GPP_{Tower}. When considering red-edge models, however, VPM_{S2-NDRE2}, VPM_{S2-Clg}, and
510 VPM_{S2-Clr} all estimated both 2018 and 2019 cumulative GPP within $\pm 10\%$ tower sums. However, VPM_{S2-}
511 NDRE1, VPM_{S2-NDRE2}, VPM_{S2-MTCI}, VPM_{S2-Clg}, and VPM_{S2-Clr} overestimated 1:14, 3:14, 9:14, 6:14, and 5:14
512 site-years, respectively. Compared to other models, VPM_{S2-NDRE2} reliably estimated peak growing season
513 cumulative GPP at individual and collective fields.

Table 3. March–November cumulative GPP (g C m^{-2}) as estimated from $\text{GPP}_{\text{Tower}}$, conventional products $\text{GPP}_{\text{MODIS}}$ and $\text{GPP}_{\text{CONUS}}$, and VPM models $\text{GPP}_{\text{VPM-MODIS}}$, $\text{GPP}_{\text{VPM-LS8}}$, $\text{GPP}_{\text{VPM-S2}}$, $\text{VPM}_{\text{S2-NDRE1}}$, $\text{VPM}_{\text{S2-NDRE2}}$, $\text{VPM}_{\text{S2-MTCI}}$, $\text{VPM}_{\text{S2-Clg}}$, $\text{VPM}_{\text{S2-Clr}}$. Values in bold indicate $\pm 10\%$ of total $\text{GPP}_{\text{Tower}}$.

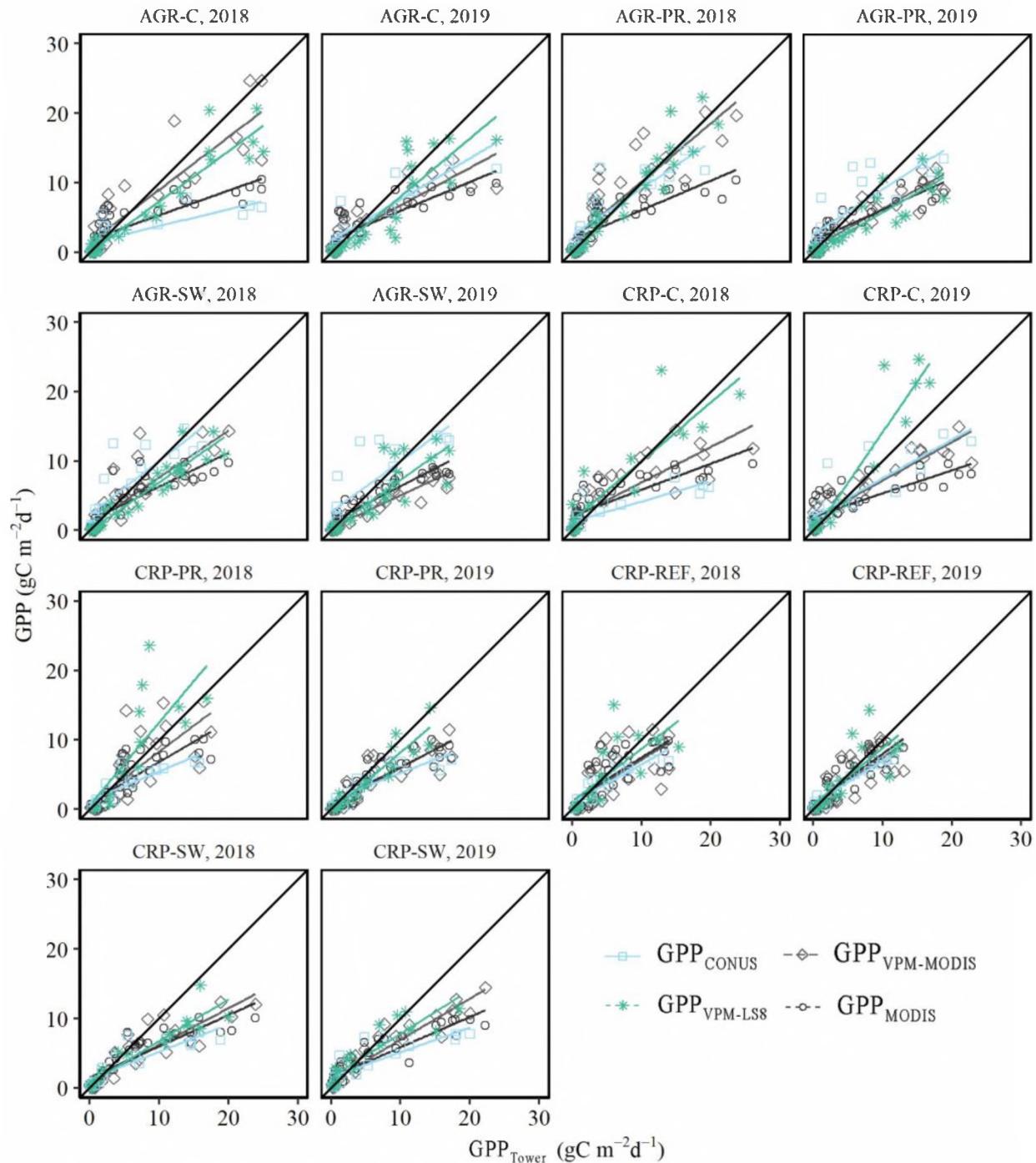
Year	SITE	$\text{GPP}_{\text{Tower}}$	$\text{GPP}_{\text{MODIS}}$	$\text{GPP}_{\text{CONUS}}$	$\text{GPP}_{\text{VPM-}}$				$\text{VPM}_{\text{S2-}}$			
					<i>MODIS</i>	<i>LS8</i>	<i>S2</i>	<i>NDRE1</i>	<i>NDRE2</i>	<i>MTCI</i>	<i>Clg</i>	<i>Clr</i>
2018	AGR-C	1598.83	1092.38	797.32	1649.99	1254.12	1340.96	1226.33	1577.21	1597.10	1369.89	1335.42
	AGR-PR	1554.91	1165.29	1649.75	1802.58	1612.87	1529.12	1124.71	1476.40	1786.66	1503.21	1345.71
	AGR-SW	1501.52	1108.52	1729.91	1241.52	1161.16	1276.53	822.97	1097.84	1522.17	1305.52	1218.87
	CRP-C	1417.42	1122.50	776.11	1206.72	1701.10	1184.19	1146.05	1484.45	1346.03	1340.52	1129.04
	CRP-PR	1469.99	1147.00	967.75	1349.28	1979.34	1439.21	1001.07	1289.68	1592.61	1270.01	1300.73
	CRP-REF	1327.21	1173.51	977.53	1088.91	1341.41	1122.34	741.01	1008.62	1425.93	1343.52	1216.46
	CRP-SW	1725.24	1171.74	1009.05	1152.18	1326.74	1464.69	1243.94	1519.22	1495.99	1443.48	1293.13
	<i>Total</i>	<i>10595.12</i>	<i>7980.93</i>	<i>7907.42</i>	<i>9491.18</i>	<i>10376.75</i>	<i>9357.03</i>	<i>7306.07</i>	<i>9453.42</i>	<i>10766.50</i>	<i>9576.15</i>	<i>8839.37</i>
2019	AGR-C	1340.88	1084.37	1331.38	1120.08	1075.59	1043.42	993.81	1242.04	1111.09	944.38	948.55
	AGR-PR	1465.36	1128.72	1717.36	1032.44	853.29	1013.46	794.34	1002.62	1109.12	1079.95	907.22
	AGR-SW	1366.86	1091.51	1838.63	795.20	1019.06	899.23	635.01	847.33	1141.78	968.39	942.40
	CRP-C	1596.14	1082.76	1437.37	1305.52	2031.73	1456.51	1446.59	1777.44	1888.23	1844.54	1773.22
	CRP-PR	1574.03	1077.00	975.83	1004.45	1233.13	1314.00	965.03	1225.00	1401.90	1407.05	1324.88
	CRP-REF	1265.02	1118.37	986.77	1010.13	1227.60	1328.91	846.67	1109.47	1420.46	1521.20	1357.44
	CRP-SW	1567.16	1128.18	1025.81	1257.41	1341.75	1453.05	1195.85	1488.37	1443.98	1436.62	1260.02
	<i>Total</i>	<i>10175.45</i>	<i>7710.90</i>	<i>9313.14</i>	<i>7525.22</i>	<i>8782.16</i>	<i>8508.59</i>	<i>6877.31</i>	<i>8692.26</i>	<i>9516.56</i>	<i>9202.13</i>	<i>8513.73</i>

Table 4. June–August cumulative GPP (g C m^{-2}) as estimated from $\text{GPP}_{\text{Tower}}$, conventional products $\text{GPP}_{\text{MODIS}}$ and $\text{GPP}_{\text{CONUS}}$, and VPM models $\text{GPP}_{\text{VPM-MODIS}}$, $\text{GPP}_{\text{VPM-LS8}}$, $\text{GPP}_{\text{VPM-S2}}$, $\text{VPM}_{\text{S2-NDRE1}}$, $\text{VPM}_{\text{S2-NDRE2}}$, $\text{VPM}_{\text{S2-MTCI}}$, $\text{VPM}_{\text{S2-Clg}}$, $\text{VPM}_{\text{S2-Clr}}$. Values in bold indicate $\pm 10\%$ of total $\text{GPP}_{\text{Tower}}$.

Year	SITE	$\text{GPP}_{\text{Tower}}$	$\text{GPP}_{\text{MODIS}}$	$\text{GPP}_{\text{CONUS}}$	$\text{GPP}_{\text{VPM-}}$					$\text{VPM}_{\text{S2-}}$		
					<i>MODIS</i>	<i>LS8</i>	<i>S2</i>	<i>NDRE1</i>	<i>NDRE2</i>	<i>MTCI</i>	<i>Clg</i>	<i>Clr</i>
2018	AGR-C	1391.29	738.58	554.12	1275.75	1087.65	1131.24	1065.48	1311.99	1460.64	1225.44	1237.59
	AGR-PR	1184.43	724.16	1039.64	1272.96	1278.57	1261.86	902.85	1121.71	1505.76	1192.06	1173.15
	AGR-SW	1128.22	709.44	1099.14	908.67	892.78	1022.95	629.49	802.30	1221.38	993.42	983.67
	CRP-C	1209.67	722.41	539.37	880.98	1392.21	1005.68	998.37	1232.87	1231.34	1185.96	1042.77
	CRP-PR	904.32	732.37	540.12	985.65	1513.78	1117.23	807.45	1010.78	1293.86	1115.91	1144.93
	CRP-REF	729.02	763.76	534.06	776.52	952.55	785.15	520.92	685.25	986.70	928.80	876.51
	CRP-SW	1277.66	726.96	622.25	799.60	915.50	1211.05	1008.55	1191.43	1259.59	1280.42	1146.39
<i>Total</i>		7824.61	5117.68	4928.71	6900.13	8033.04	7535.16	5933.11	7356.32	8959.27	7922.01	7605.01
2019	AGR-C	1054.59	721.68	975.09	816.75	904.75	959.19	844.38	1034.79	976.78	827.65	826.75
	AGR-PR	1166.85	711.91	1067.32	765.72	694.01	883.87	689.71	830.63	980.70	937.14	825.34
	AGR-SW	1043.18	710.13	1148.15	575.12	788.09	771.31	549.22	694.11	1008.74	874.31	851.93
	CRP-C	1198.79	677.43	1052.35	887.20	1542.26	1344.60	1218.03	1466.30	1630.16	1567.92	1519.85
	CRP-PR	1092.92	699.95	561.12	724.21	883.75	1047.35	780.58	943.20	1170.22	1143.78	1148.72
	CRP-REF	770.39	722.25	545.17	723.68	878.22	964.54	605.65	767.94	991.55	1054.68	985.61
	CRP-SW	1263.43	735.01	637.43	911.20	889.86	1226.98	1024.97	1214.15	1293.07	1245.41	1138.83
<i>Total</i>		7590.15	4978.37	5986.63	5403.88	6580.95	7197.84	5712.54	6951.12	8051.22	7650.90	7297.05

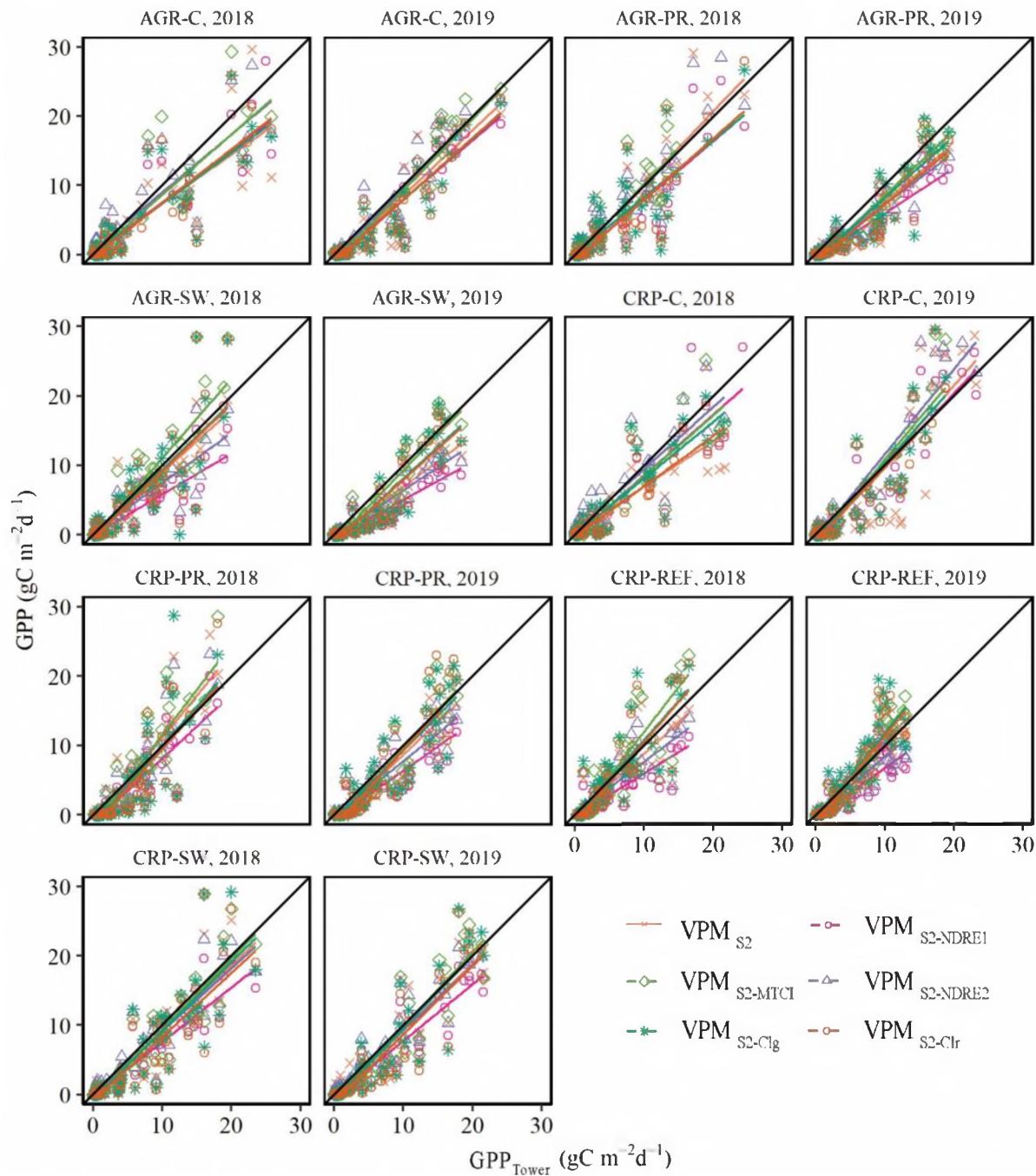
516 In all site years, the finer resolution $\text{GPP}_{\text{VPM-S2}}$ and $\text{GPP}_{\text{VPM-LS8}}$ out-performed $\text{GPP}_{\text{MODIS}}$, $\text{GPP}_{\text{CONUS}}$ and
517 $\text{GPP}_{\text{VPM-MODIS}}$ (Fig. 6, Table S5) and agreed the best with $\text{GPP}_{\text{Tower}}$. Each model had a significant ($p < 0.05$)
518 and strong positive trend with $\text{GPP}_{\text{Tower}}$ in 2018 and 2019. The largest variation in model estimates were
519 found in corn systems for both years and prairie systems in 2018. $\text{GPP}_{\text{VPM-MODIS}}$, $\text{GPP}_{\text{MODIS}}$ and $\text{GPP}_{\text{CONUS}}$
520 models generally underestimated; and $\text{GPP}_{\text{VPM-S2}}$ and $\text{GPP}_{\text{VPM-LS8}}$ models aligned best with the 1:1 slope,
521 with the exception of $\text{GPP}_{\text{VPM-S2}}$ and $\text{GPP}_{\text{VPM-LS8}}$ overestimation of CRP-C 2019 and CRP-PR 2018. In
522 CRP-REF, all models were in close agreement with $\text{GPP}_{\text{Tower}}$. In both years, $\text{GPP}_{\text{MODIS}}$ and $\text{GPP}_{\text{CONUS}}$ had
523 the highest RMSE in corn and switchgrass systems, as well as AGR-PR. In all sites, VPM models had
524 lower RMSE than conventional products $\text{GPP}_{\text{MODIS}}$ and $\text{GPP}_{\text{CONUS}}$ with the exception of CRP-REF (both
525 years) and CRP-PR (2018) (Fig. 8). Compared to $\text{GPP}_{\text{VPM-S2}}$, RMSE at corn sites was lower for $\text{GPP}_{\text{VPM-}}$
526 LS8 for both years and lower for $\text{GPP}_{\text{VPM-MODIS}}$ in 3:4 site-years.

527 When considering enhancements from red-edge VIs in VPM, the NDRE1 and NDRE2 VIs
528 increase explanation of variability in eight out of fourteen site-years (Fig. 7). While RMSE values of red-
529 edge VPMs were often higher in 2018 than that of the EVI2-based $\text{GPP}_{\text{VPM-S2}}$, they were near equal in
530 2019 (Table S5, Fig. 8). Sites that benefitted in both years from red-edge VPMs included AGR-C, CRP-C,
531 and CRP-SW; whereas AGR-PR and AGR-SW only saw benefits in 2019. While both NDRE1 and
532 NDRE2 improve AGR-C in both years and CRP-C in 2018 by the same explanation of variance, NDRE1
533 has a lower RMSE in all three site-years and a closer 1:1 slope in two of three site years.



534

535 Figure 6. Comparison of daily GPP_{tower} with daily GPP_{LS8} , $GPP_{\text{VPM-MODIS}}$, GPP_{MODIS} , and
 536 GPP_{CONUS} by site-year. Solid black line depicts a 1:1 relationship.
 537



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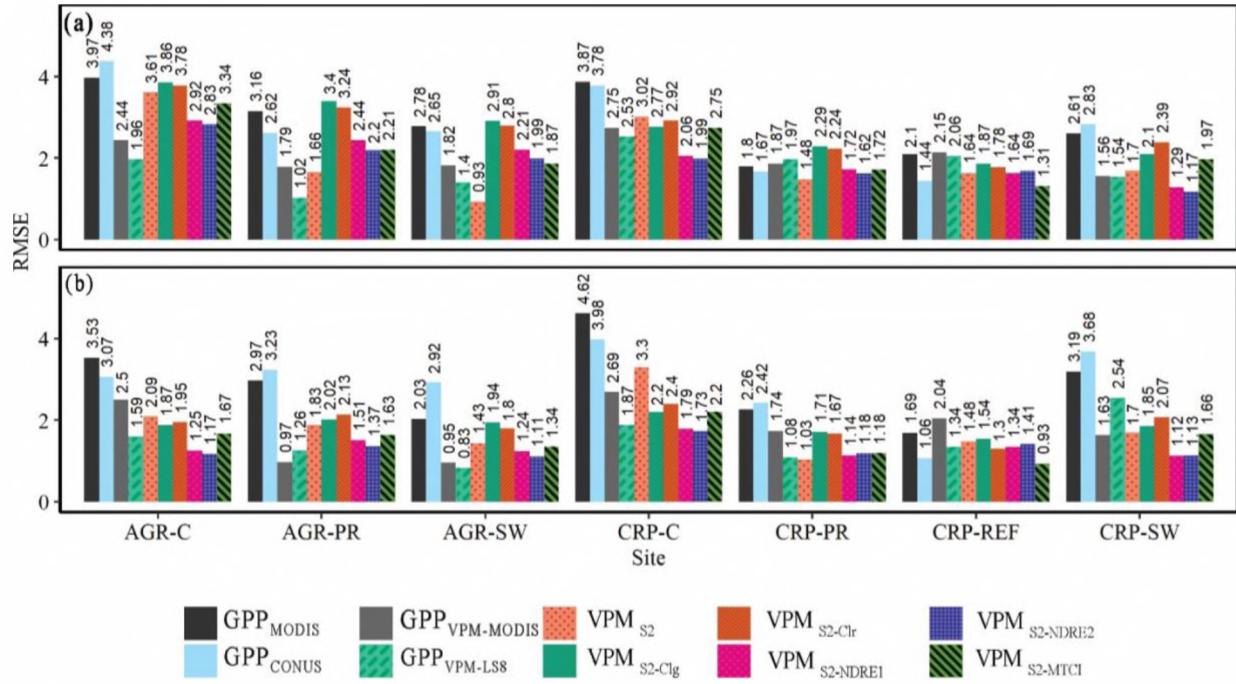
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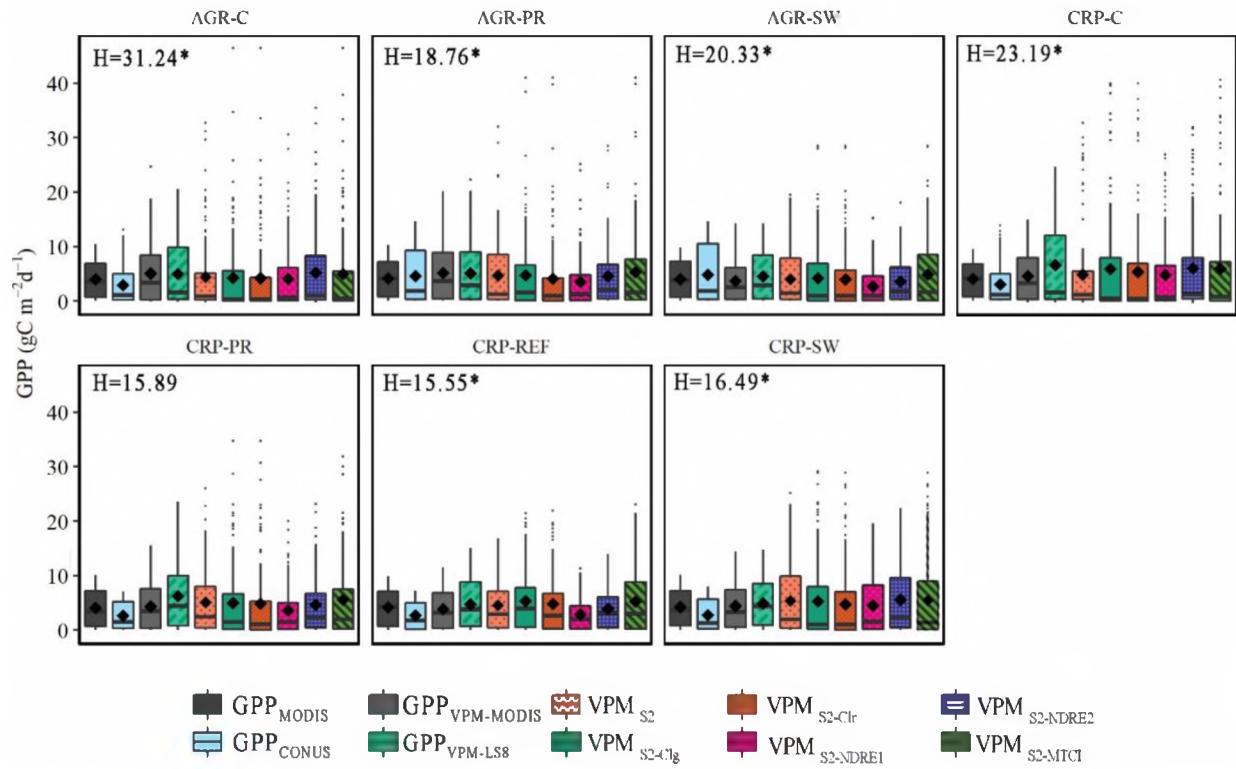
Figure 7. Comparison of daily GPP_{tower} with daily $VPM_{\text{S2-MTCI}}$, $VPM_{\text{S2-Clg}}$, $VPM_{\text{S2-Clr}}$, $VPM_{\text{S2-NDRE1}}$, and $VPM_{\text{S2-NDRE2}}$ by site-year. Solid black line depicts a 1:1 relationship.



543
544
545

Figure 8. Comparison model RMSE ($\text{g C m}^{-2} \text{d}^{-1}$) of daily $\text{GPP}_{\text{Tower}}$ with daily remote sensing GPP models across the seven land cover types in (a) 2018 and (b) 2019.

546 GPP estimates are significantly different between models at all sites, except CRP-PR, according to
547 the Kruskal-Wallis rank sum test ($p < 0.05$) (Fig. 9). A pair-wise post-hoc Dunn test demonstrated that in
548 site AGR-C, significant differences were found between pairs GPP_{MODIS}:VPM_{S2-Clr} and GPP_{MODIS}:VPM_{S2-CIg}
549 ($z = 3.92, p=0.004$; $z = 3.66, p=0.01$, respectively); while CRP-C had differences between GPP_{MODIS}:VPM<sub>S2-
550 Clr</sub> ($z = 3.62, p=0.01$). In sites CRP-PR, CRP-REF, CRP-SW, AGR-PR and AGR-SW, there were no
551 significant ($p < 0.05$) differences between model pairs.



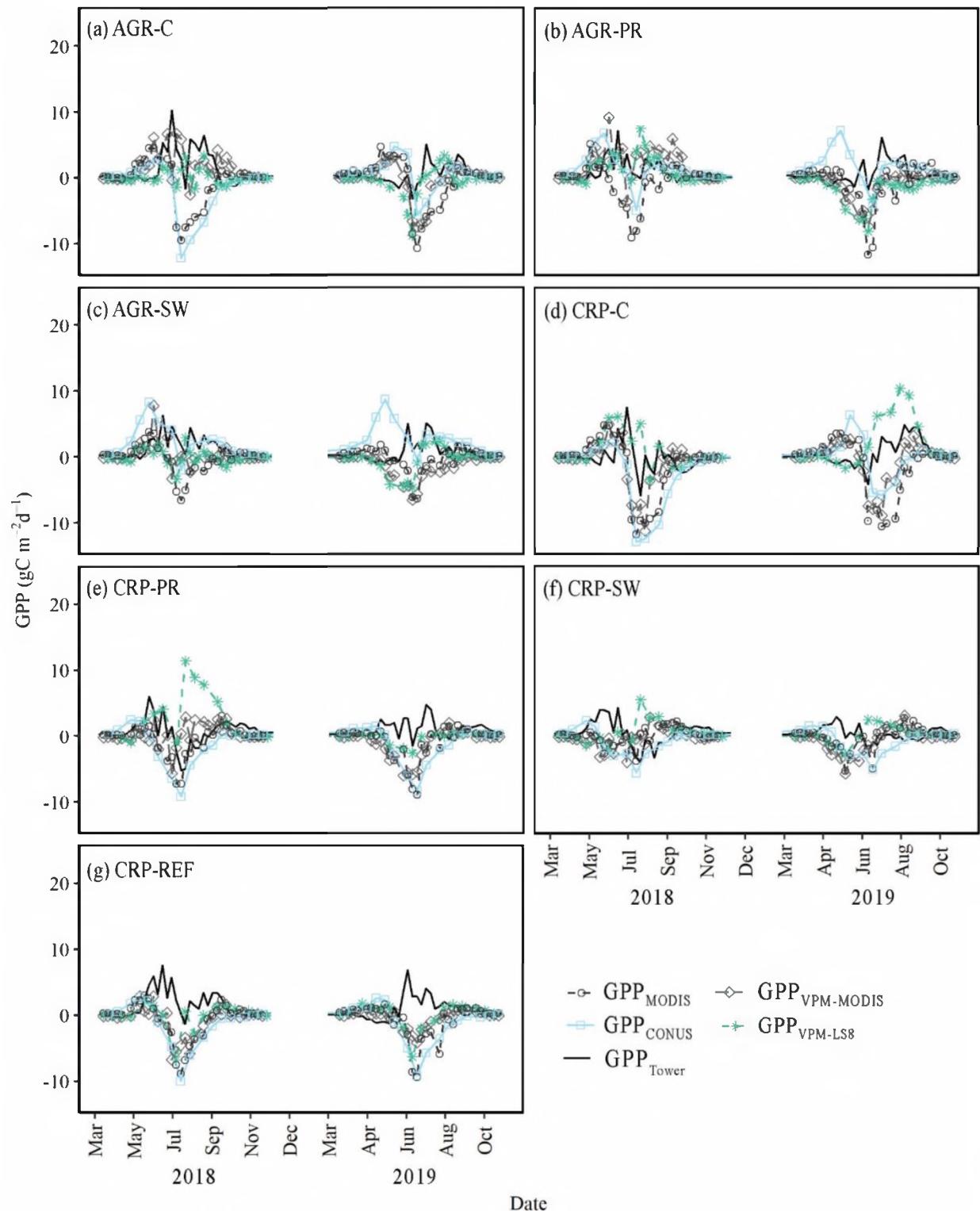
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553 Figure 9. Box-plot comparisons of GPP models by land cover type during 2018–2019. Inside the
 554 boxplot, a black diamond indicates the mean, error bars are mean standard error, and a black
 555 horizontal line depicts the median; outside the boxplot, whiskers indicate the maximum and minimum
 556 values and points indicate outliers. Results of the Kruskal-Wallis include H , which is interpreted as
 557 chi-square. A significant p -value <0.05 is indicated with an *.

558 *3.4. GPP anomaly estimates*

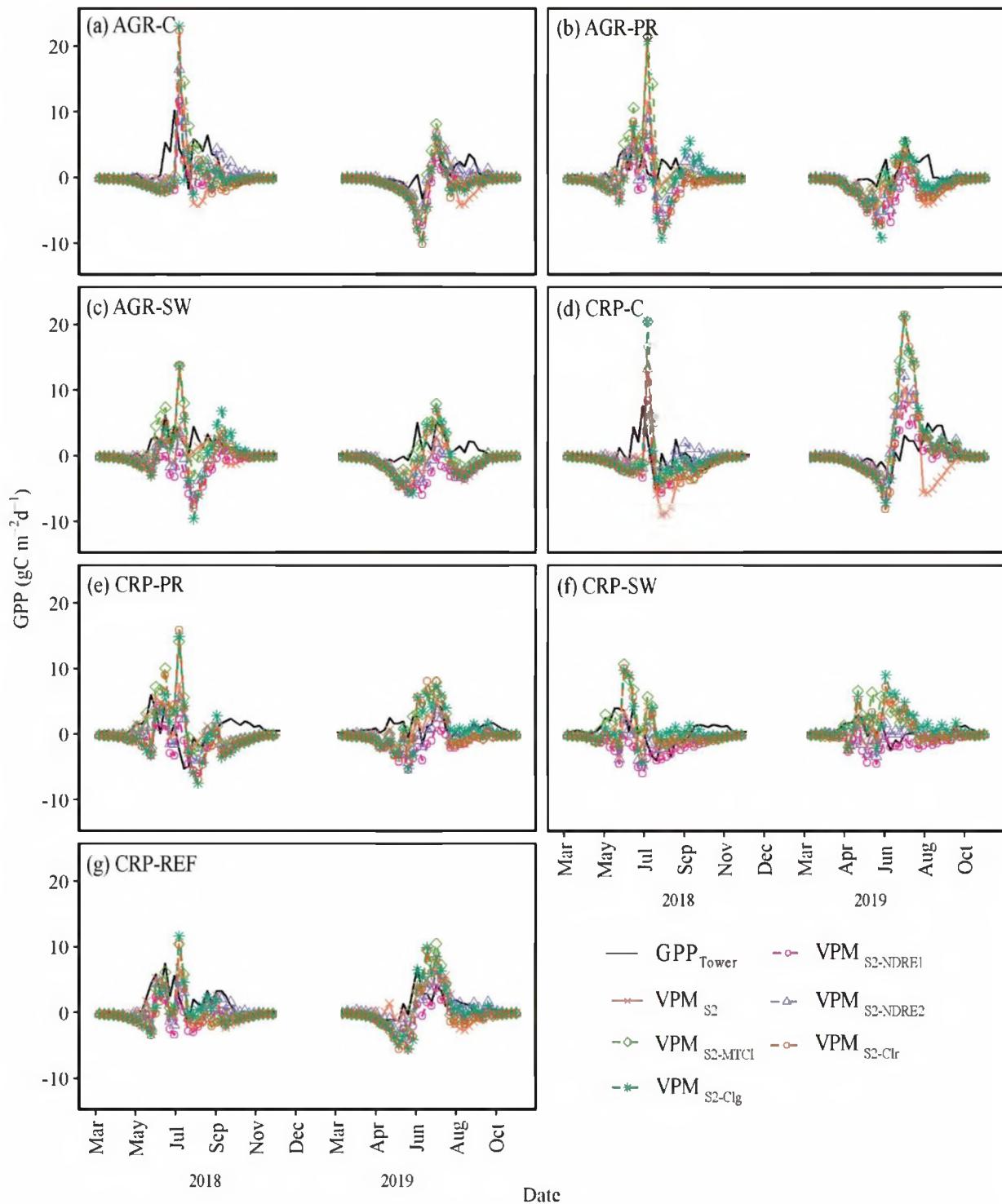
559 We evaluated anomalies generated from each GPP model from seasonal means and found large anomalies
 560 existed in the peak growing seasons (June–August) (Figs. 10,11). GPP_{Tower} anomalies in regression
 561 analysis demonstrated that GPP_{VPM-S2} exhibited the highest positive trend out of conventional models,
 562 with a significant relationship ($p<0.05$) in switchgrass and prairie systems but was second to GPP_{VPM-LS8}
 563 at the corn systems. CRP-REF anomalies did not match well with any model, evidenced by insignificant,
 564 positive trends (Fig. S2, S3 Table S6). In red-edge VPMs, we found that most anomalies occurred during
 565 peak growing season due to models VPM_{S2-MTCI}, VPM_{S2-Clr}, and VPM_{S2-Clg}, which overestimated GPP in

566 2018 site-years and in CRP-C 2019. Generally, $VPM_{S2-NDRE1}$ and $VPM_{S2-NDRE2}$ did not overestimate, with
567 the exception of CRP-C 2019, and had more outliers that underestimated.



568

569 Figure 10. Anomalies of GPP ($\text{g C m}^{-2} \text{d}^{-1}$) from $\text{GPP}_{\text{MODIS}}$, $\text{GPP}_{\text{CONUS}}$, $\text{GPP}_{\text{VPM-MODIS}}$ and $\text{GPP}_{\text{VPM-LS8}}$
 570 over time for the seven study sites: (a) AGR-C, (b) AGR-PR, (c) AGR-SW, (d) CRP-C, (e)
 571 (f) CRP-PR, (f) CRP-REF, and (g) CRP-SW.



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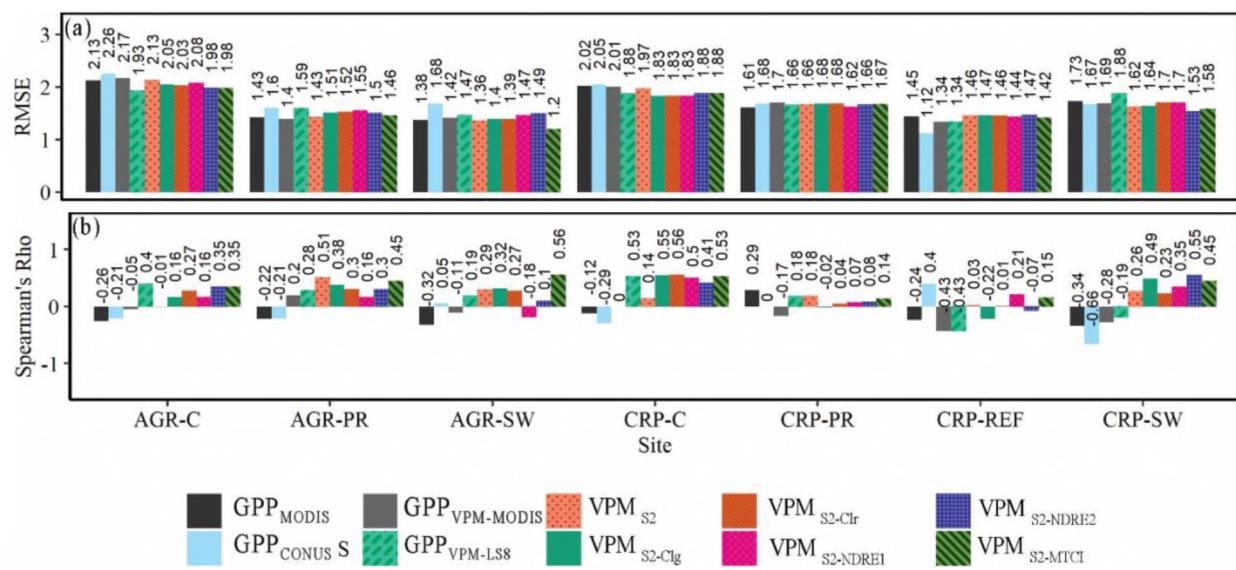
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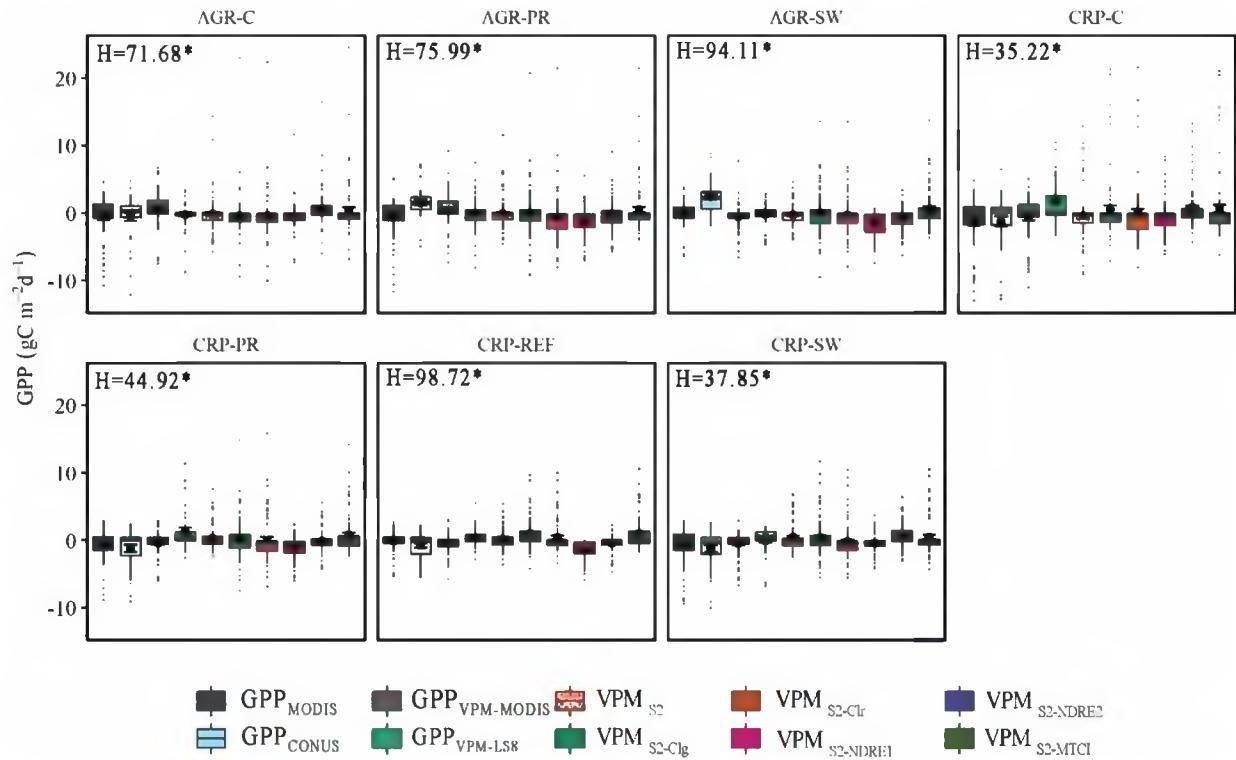
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Figure 11. Anomalies of GPP ($\text{g C m}^{-2} \text{d}^{-1}$) from $\text{GPP}_{\text{VPM-S2}}$, $\text{VPM}_{\text{S2-Clg}}$, $\text{VPM}_{\text{S2-Clr}}$, $\text{VPM}_{\text{S2-NDRE1}}$, $\text{VPM}_{\text{S2-NDRE2}}$, $\text{VPM}_{\text{S2-MTCI}}$ over time for the seven study sites: (a) AGR-C, (b) AGR-PR, (c) AGR-SW, (d) CRP-C, (e) CRP-PR, (f) CRP-REF, and (g) CRP-SW.

576 Anomalies exhibited both positive and negative trends compared to $\text{GPP}_{\text{Tower}}$, with fine-resolution
 577 VPMs outperforming conventional models. Red-edge VPMs had strong, positive trend at the exception of
 578 sites AGR-SW ($\text{VPM}_{\text{S2-NDRE1}}$) and CRP-REF ($\text{VPM}_{\text{S2-Clg}}$, $\text{VPM}_{\text{S2-NDRE2}}$). $\text{GPP}_{\text{VPM-LS8}}$ exhibited the
 579 strongest, positive trend and the lowest RMSE in corn sites between conventional models and $\text{GPP}_{\text{VPM-S2}}$;
 580 whereas $\text{GPP}_{\text{VPM-S2}}$ exhibited this for remaining sites, except CRP-REF (Fig. 12). In red-edge models, the
 581 lowest RMSE was $\text{VPM}_{\text{S2-MTCI}}$ in AGR-C, AGR-PR, and AGR-SW; and variable in remaining sites. Sites,
 582 AGR-C, CRP-C and CRP-SW tend to have higher RMSEs. Conventional $\text{GPP}_{\text{CONUS}}$ and $\text{GPP}_{\text{MODIS}}$ had
 583 negative trends, except for $\text{GPP}_{\text{MODIS}}$ in CRP-PR ($\rho=0.30$) and $\text{GPP}_{\text{VPM-S2}}$ in AGR-SW ($\rho=0.02$) and CRP-
 584 REF ($\rho=0.40$). Similarly, $\text{GPP}_{\text{VPM-MODIS}}$ had a negative or zero trend in all sites except for AGR-PR
 585 ($\rho=0.20$).



586
 587 Figure 12. Comparison of anomaly model RMSE ($\text{g C m}^{-2} \text{d}^{-1}$) and Spearman's Rho
 588 (ρ) coefficients of daily $\text{GPP}_{\text{tower}}$ with daily GPP from all remote sensing models across the seven
 589 land cover types 2018–2019.



591

592 Figure 13. Box-plot comparisons of GPP ($\text{g C m}^{-2} \text{d}^{-1}$) anomalies by model at seven land cover
 593 type during 2018–2019. Inside the boxplot, a black circle indicates the mean, error bars are mean
 594 standard error, and a black horizontal line depicts the median; outside the boxplot, whiskers
 595 indicate the maximum and minimum values and points indicate outliers. Results of the Kruskal-
 596 Wallis include H , which is interpreted as chi-square, and significance p -value $<<0.05$ is indicated
 597 with an asterisk (*).

598 Significant differences exist between anomaly GPP models at each site, according to the Kruskal-
 599 Wallis rank test (Fig. 13). The site with greatest variance from the mean was CRP-C. From the pairwise
 600 comparison Dunn test (Table 5), we also observed that a significant difference in anomaly medians
 601 between $\text{GPP}_{\text{Tower}}$ and $\text{GPP}_{\text{VPM-S2}}$ exist in five sites, including AGR-C, AGR-PR, AGR-SW, CRP-PR, and
 602 CRP-SW. Significant differences also existed between $\text{GPP}_{\text{Tower}}$ and $\text{GPP}_{\text{VPM-LS8}}$ at AGR-PR and AGR-
 603 SW, as well as between $\text{GPP}_{\text{VPM-LS8}}$ and $\text{GPP}_{\text{VPM-S2}}$ in CRP-C. The fewest differences between red-edge
 604 VPMs and $\text{GPP}_{\text{Tower}}$ were with $\text{VPM}_{\text{S2-NDRE2}}$ (AGR-PR, AGR-SW, CRP-PR, CRP-REF) and $\text{VPM}_{\text{S2-MTCI}}$
 605 (AGR-C, AGR-SW, CRP-PR, CRP-REF); and the highest was with $\text{VPM}_{\text{S2-Clr}}$, which was significantly

606 different in seven sites. VPM_{S2-NDRE2} and VPM_{S2-MTCI} also had the fewest differences between other
607 models.

608
609Table 5. Dunn test pairwise comparison of significant differences ($p < 0.05$) between models at each site 2018–2019 for GPP anomalies.

	GPP CONUS	GPP MODIS	GPP VPM- MODIS	GPP VPM-LS8	GPP VPM-S2	VPM S2-Clg	VPM S2-Clr	VPM S2- NDRE1	VPM S2- NDRE2	VPM S2-MTCI	GPP Tower
GPP	-	-	-	-	-	-	-	-	-	-	-
CONUS GPP	□□	-	-	-	-	-	-	-	-	-	-
MODIS GPP	□□	-	-	-	-	-	-	-	-	-	-
VPM- MODIS GPP	*□	-	-	-	-	-	-	-	-	-	-
VPM-LS8 GPP	*□		▲▲	△	-	-	-	-	-	-	-
VPM-S2 VPM	*□	▲	▲◆	-	-	-	-	-	-	-	-
S2-Clg VPM	▲*□	▲*	▲*	△■○	-	-	-	-	-	-	-
S2-Clr VPM	*□◆	▲*□■	▲*□■	□△■◆	□■◆	□■◆	◆	-	-	-	-
S2- NDRE1 VPM	◆	◆	◆	-	-	-	-	-	-	-	-
S2- NDRE2 VPM	*□		▲	-	-	-	-	-	-	-	-
S2-MTCI GPP	■○■○	■◆○■	□○□○	*□	▲*□■	▲*□■	▲*□	▲*□■	*□■◆	▲□■○	-
Tower	◆○	■○	-	○▲*□	○	△■◆○	◆○	-	-	-	-

610 Sites: □: AGR-SW, ○: CRP-SW, ◆: CRP-REF, ■: CRP-PR, *: AGR-PR, ▲: AGR-C, Δ: CRP-C

611 **4. Discussion**

612 While VPM developed using MODIS products still provides a valuable product that is widely available
 613 spatially and temporally, complex and heterogeneous land cover types such as managed agricultural-
 614 prairie landscapes benefit from the use of finer spatial resolution imagery (Chen et al., 2019). Fine spatial
 615 resolution reflectance indices from Sentinel-2 and Landsat-8 increased the accuracy of VPM models in
 616 our study. Particularly, when red-edge VIs replace EVI2 in Sentinel 2 VPMs, we found improvements in
 617 model validation, cumulative GPP estimates, and fewer differences between $\text{GPP}_{\text{Tower}}$ medians than that
 618 of $\text{GPP}_{\text{VPM-S2}}$.

619 Sensitivity of VIs EVI2 and NDVI to $\text{GPP}_{\text{Tower}}$ differed greatly between MODIS (500 m) and the
620 finer resolutions of Landsat-8 (30 m) or Sentinel-2 (20 m). If selecting between the two in agricultural-
621 prairie systems, it is prudent to use EVI2. For finer resolution VPMs, NDVI may be suitable upon further
622 study. MODIS had high sensitivity to EVI2 in 13:14 site years than NDVI, of which only 2:14 site-years
623 had sensitivity ± 0.10 of 1.00 (i.e., near equal sensitivity). We find this supports similar research on
624 MODIS LUE-based GPP models, where the ability to capture GPP variations is closely tied to the
625 accuracy of *f*PAR and that 8-day MODIS data do not consistently capture fall and spring's rapid changes
626 in phenology, likely introducing error to annual GPP estimates (Verma et al., 2014). Conversely, near-
627 equal sensitivity was apparent in Landsat-8 and Sentinel-2, with 9:14 and 12:14 site-years with
628 sensitivities ± 0.10 of 1, respectively. Given EVI2 and NDVI uses the same two bands (i.e., NIR, Red), the
629 differences between satellite products could arise from differences in radiometric resolution (i.e.,
630 bandwidth), spatial resolution and sampling frequency. In fact, the wavelength ranges of MODIS,
631 Landsat-8, and Sentinel-2 red bands (nm) are 620–670, 636–673, 650–680, respectively; while the NIR
632 bands are 841–875, 851–879, and 855–875, respectively. These slight differences in bandwidth, along with
633 differences in sampling dates and spatial resolution from Landsat-8 and Sentinel-2, may have resulted in
634 substantial differences in GPP estimates. We found that NDRE1 and NDRE2 were slightly more sensitive
635 than EVI2 to $\text{GPP}_{\text{Tower}}$, with 8:14 site years, that MTCI was near-equal sensitive, and that EVI2 was
636 generally more sensitive to $\text{GPP}_{\text{Tower}}$ than Clr and Clg. Both sensitivities of pairs (1) NDRE1 and NDRE2;
637 and (2) Clr and Clg were similar, respectively, as the equations are similar and the difference within each
638 pair is minimal (Eqs. 4-7).

639 GPP estimates in our study area, and many other Midwestern cropland regions, are notably
640 underestimated by MODIS products, likely due to mixed pixels (Wang et al., 2015; Zhang et al., 2016).
641 We found that land cover (NLCD, 30 m) within a single MODIS 500 m pixel overlapped cropland,
642 developed areas, forests, grasslands and wetlands (Table S3). Our results demonstrated that $\text{GPP}_{\text{VPM-MODIS}}$
643 underestimated, particularly in the peak growing season, at all sites, more than other GPP models. The

644 least to underestimate cumulative GPP includes VPM_{S2-MTCI} during the study period (9:14) and peak
645 growing season (5:14), and VPM_{S2-Clg} in the peak growing season (8:14). When comparing conventional
646 and non-red-edge VPMs, finer resolution VPM models are closer to daily and cumulative GPP_{Tower}, with
647 GPP_{VPM-LS8} capturing the variation in corn systems best and GPP_{VPM-S2} best capturing grassland systems.
648 Additionally, a heavy rainfall in the spring of 2019 (wet year) may have affected GPP production in some
649 sites. Peak growing season (June-August) is also best reflected in GPP_{VPM-S2} compared to other
650 conventional GPP products and GPP_{VPM-LS8}. While over- and underestimation can interfere with scaled-up
651 estimates (Jelinski & Wu, 1996) we found finer resolution (30 m and 20 m) GPP products demonstrated
652 the capacity to improve GPP estimates across various corn and grassland systems.

653 Our anomaly analysis of covariance further enhanced our ability to evaluate interannual variation and
654 identify significant differences between model estimates. In a similar study, covariance between
655 interannual anomalies in MODIS products did not significantly correlate with GPP_{Tower} in croplands;
656 however, few MODIS products except VPM and MOD17A did explain substantial variance in grasslands
657 because they include finer meteorological inputs and account for rapid development and senescence
658 (Verma et al., 2014). Our results reflect this, as GPP_{MODIS} and GPP_{VPM-MODIS} did not significantly correlate
659 with GPP_{Tower} anomalies. We found significant differences in medians between GPP_{VPM-S2}, GPP_{VPM-LS8} and
660 GPP_{Tower} anomalies existed, indicating that one model simply over- or underestimated more often than its
661 counterpart. While significant differences between medians in high-resolution and red-edge VPMs and
662 GPP_{Tower} exist, we do not believe this undermines their demonstrated accuracy in regression analysis and
663 in seasonal summations. Particularly, anomalies of GPP_{Tower} also have significant differences from
664 GPP_{MODIS} and GPP_{VPM-MODIS} medians at three sites, and significant differences with GPP_{VPM-LS8} and
665 GPP_{CONUS} at two sites; whereas it has significant differences with VPM_{S2-NDRE2} and VPM_{S2-MTCI} at four
666 sites. Understanding that MODIS products largely underestimate GPP (Tables 3, 4) and aggregate nearby
667 land covers, we recommend Landsat-8 and Sentinel-2 GPP products. More so, Sentinel-2 VPMs
668 demonstrate greater ability than Landsat-8 products to remain within $\pm 0.10\%$ of both cumulative study

669 period and peak growing season GPP_{Tower} ; with red-edge $VPM_{\text{S2-NDRE2}}$ and $VPM_{\text{S2-MTCI}}$ equal to or out
670 performing $GPP_{VPM-\text{S2}}$, respectively.

671 From both regression analyses in this study, $GPP_{VPM-\text{LS8}}$ still agreed strongest with corn systems
672 compared to $GPP_{VPM-\text{S2}}$, which performed better in grassland systems with its largest anomalies during the
673 peak growing season. However, when incorporating NDRE2 into the Sentinel-2 VPM, it could
674 outperform $GPP_{VPM-\text{LS8}}$ in CRP-C site-years; demonstrating a potential to use red-edge VI with high-
675 resolution imagery in both corn and grassland covers. The only site years where $GPP_{VPM-\text{S2}}$ still
676 outperforms all other models, including red-edge VI VPMs, was in AGR-SW 2018 and in CRP-PR 2018
677 and 2019, where there are narrow differences (Table S5). We conclude that red-edge VIs, particularly
678 NDRE2, may significantly improve the VPM's ability to estimate variations in GPP when used as an
679 alternative to EVI2.

680 While our study area benefitted from finer resolution models, this may not stand true in all landscapes
681 and elsewhere. In Nordic eddy covariance flux measurement sites, modelled GPP with linear regression
682 and EVI2 and various environmental inputs detected a minimal difference with a consistent estimate
683 across MODIS (500 m and 250 m) and Sentinel-2 (10 m) resolutions (Cai et al., 2021). An additional
684 consideration for future studies is GPP production from cover crops, which is a common practice that
685 may influence variability in annual estimates. Ultimately, the choice of GPP product depends on the
686 intended application. Here, we advocate for fine-resolution imagery and the consideration of red-edge in
687 GPP models to capture details at a local-scale that reflects land management and activities in
688 heterogeneous cropland. However, Landsat provides data since 1972 and offers great historical detail far
689 beyond what Sentinel 2 can offer, and may be more suitable for investigations of long-term change.
690 Additionally, further consideration may be placed on temporal resolution, which imparts its own effect on
691 aggregation of disturbance or land management useful for scaling investigations. Differences between
692 Landsat and MODIS data lies in the acquisition and data retrieval, where Landsat is instantaneous and at
693 higher risk of acquiring poor fPAR or LAI due to atmospheric effects and cloud cover and MODIS is a
694 composite taking the best image from an 8-day span (Robinson et al., 2018). Future investigations on

695 resolution and GPP estimates may consider utilizing the newly released MOD17A3HGF v061 product,
696 which may provide different results due to its updated protocol that cleans poor-quality inputs from 8-day
697 LAI/fPAR based on pixel quality control labels. Additionally, the MODIS GPP product FluxSat v2.0
698 offers daily estimates of GPP using FLUXNET eddy covariance tower site data and coincident satellite
699 data (Joiner & Yoshida, 2021).

700 While EC methods provide direct and suitable estimates of CO₂ fluxes at the local scale useful to both
701 calibration and validation of remote sensing GPP models, we acknowledge they are also subject to error
702 and uncertainty that are important to validation of remote sensing models and interannual analysis (Wang
703 et al., 2015). Recent studies show that the flux tower footprint, used in validation and site-specific
704 measurements, often extends beyond the target ecosystem, depending on time and atmospheric conditions
705 (e.g., wind speed and direction) (Chu et al., 2021; Giannico et al., 2018). Consequently, in highly
706 heterogeneous landscapes, multiple EC towers may be required to capture spatial representativeness
707 necessary for validating global scale model grids (Wang et al., 2015). Our results support this, as
708 GPP_{MODIS} and GPP_{VPM-MODIS} underestimated cumulative GPP as well as daily estimates during the study
709 period and growing season (June, July, August).

710 Evaluation and monitoring of GPP with Landsat-8 and Sentinel-2 reveals how terrestrial C responds
711 to land management, climate mitigation policies, and disturbance in heterogeneous cropland systems. It
712 also supports cost-effective land management programs and increases the understanding of anthropogenic
713 disturbances to ecosystem functions. Both Landsat-8 and Sentinel-2 are available freely online and easily
714 accessible via Google Earth Engine, greatly improving their employability in policy and stakeholder
715 programs. For example, the economic benefit of management and incentive programs attract farmers to
716 convert low-producing corn for ethanol to perennial grasses, such as switchgrass, produce co-benefits,
717 such as C sequestration (Kreig et al., 2021). Future applications with red-edge imagery from Sentinel 2
718 will benefit from high spatial and temporal resolution data, paving a way towards near real-time
719 monitoring of GPP.

720 **5. Conclusion**

721 Fine-resolution (30 m and 20 m) satellite imagery and red-edge VIs integrated within VPM generally
722 agree with daily and cumulative GPP_{Tower} in field sites more so than coarse resolution imagery in VPM or
723 conventional GPP products (e.g., GPP_{MODIS} or GPP_{CONUS}) do. A substitution of a red-edge VI for EVI2 in
724 the Sentinel 2 VPMs demonstrated improved explanations of variation and cumulative GPP estimates,
725 compared to EVI2-based $GPP_{\text{VPM-S2}}$.

726 We found that vegetation indices of EVI2 and NDVI express different sensitivities by satellite
727 origin, where MODIS-derived EVI2 had higher sensitivity than NDVI to GPP_{Tower} in all but one site; and
728 Landsat-8 and Sentinel-2 EVI2 and NDVI had near equal sensitivity in most site-years. Compared to
729 EVI2, red-edge VIs NDRE1 and NDRE2 were slightly more sensitive to GPP_{Tower} . Seasonal GPP
730 amplitude and growing season peaks are best captured by Sentinel-2 VPMs, followed by $GPP_{\text{VPM-LS8}}$,
731 whereas conventional products underestimate growing season peaks. Overall, Sentinel-2 VPMs
732 demonstrate greater ability than Landsat-8 and MODIS products to remain within $\pm 0.10\%$ of both
733 cumulative study period and peak growing season GPP_{Tower} ; with red-edge $VPM_{\text{S2-NDRE2}}$ and $VPM_{\text{S2-MTCI}}$
734 equal to or out performing $GPP_{\text{VPM-S2}}$, respectively. Red-edge Sentinel 2 VPMs collectively outperformed
735 conventional GPP models and Landsat 8 products, when considering cumulative GPP estimates, model
736 validations and significant differences between anomaly medians. We conclude that red-edge VIs,
737 particularly NDRE2, may significantly improve our ability to estimate variations in GPP when used as an
738 alternative to EVI2 in GPP models.

739 As many croplands are composed of areas less than 500 m, MODIS derived scalars may be
740 composed of a mix of land cover types and therefore incorrectly estimate GPP. We demonstrated the
741 capability of using $GPP_{\text{VPM-LS8}}$, $GPP_{\text{VPM-S2}}$ and red-edge $VPM_{\text{S2-Clr}}$, $VPM_{\text{S2-Clg}}$, $VPM_{\text{S2-NDRE1}}$, $VPM_{\text{S2-NDRE2}}$,
742 $VPM_{\text{S2-MTCI}}$ in highly heterogeneous cropland, including corn, switchgrass, and restored prairie systems,
743 in both historical cropland and recently converted (i.e., 2009) CRP land. We found that our fine
744 resolution GPP products (30 m and 20 m), and particularly red-edge Sentinel 2 VPMs, agreed best with
745 GPP_{Tower} and are significantly different than MODIS products in multiple cropland sites with differing

746 land use history. While existing methods using MODIS-derived GPP models serve as an important
747 baseline for studies with large spatial extents, future endeavors to estimate GPP in managed landscapes
748 with greater frequency and improved accuracy are accessible and affordable at 30 m and 20 m
749 resolutions.

750 **Acknowledgements**

751 Support for this research was provided by the Great Lakes Bioenergy Research Center, U.S. Department
752 of Energy, Office of Science, Office of Biological and Environmental Research (Awards DE-
753 SC0018409), by the National Science Foundation Long-term Ecological Research Program (DEB
754 1832042) at the Kellogg Biological Station, and by Michigan State University AgBioResearch. Authors
755 are grateful for expert knowledge from Dr. Asko Normets, regarding light use efficiency and eddy
756 covariance data; and Dr. Xiangming Xiao, regarding the vegetation photosynthesis model. Support for
757 this research was made possible by members of the Landscape Ecology and Ecosystem Science Lab,
758 particularly Terenzio Zenone and Michael Abraha who constructed and maintain the research sites. We
759 also acknowledge the significant support and mentorship provided through the FLUXNET ECN
760 community.

761 **Funding**

762 This material is based upon work supported by the National Science Foundation Graduate Research
763 Fellowship under Grant No. (DGE-1848739).

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