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Maximum Likelihood Estimation of Optimal Receiver Operating Characteristic Curves From Likelihood Ratio Observations

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Abstract—The optimal receiver operating characteristic (ROC) curve, giving the maximum probability of detection as a function of the probability of false alarm, is a key information-theoretic indicator of the difficulty of a binary hypothesis testing problem (BHT). It is well known that the optimal ROC curve for a given BHT, corresponding to the likelihood ratio test, is theoretically determined by the probability distribution of the observed data under each of the two hypotheses. In some cases, these two distributions may be unknown or computationally intractable, but independent samples of the likelihood ratio can be observed. This raises the problem of estimating the optimal ROC for a BHT from such samples. The maximum likelihood estimator of the optimal ROC curve is derived, and it is shown to converge to the true optimal ROC curve in the Lévy metric, as the number of observations tends to infinity. A classical empirical estimator, based on estimating the two types of error probabilities from two separate sets of samples, is also considered. The maximum likelihood estimator is observed in simulation experiments to be considerably more accurate than the empirical estimator, especially when the number of samples obtained under one of the two hypotheses is small. The area under the maximum likelihood estimator is derived; it is a consistent estimator of the true area under the optimal ROC curve.

I. INTRODUCTION

Consider a binary hypothesis testing problem (BHT) with observation X . The observation X could be high dimensional with continuous and/or discrete components. Suppose g_0 and g_1 are the probability densities of X with respect to some reference measure, under hypothesis H_0 or H_1 , respectively. Then the likelihood ratio is $R = \frac{g_1(X)}{g_0(X)}$. By the Neyman–Pearson lemma, the optimal decision rule for a specified probability of false alarm, is to declare H_1 to be true if either $R > \tau$, or if a biased coin comes up heads and $R = \tau$, for a suitable threshold τ and bias of the coin. The optimal receiver operating characteristic (ROC) curve, giving the maximum probability of detection as a function of the probability of false alarm, is a key information-theoretic indicator of the difficulty of the BHT. Because we focus on the optimal ROC, which is determined by the BHT rather than the specific decision rule, we use the terms “optimal ROC” and “ROC” interchangeably.

This paper addresses the problem of estimating the ROC curve for a BHT from independent samples $R_1, \dots, R_n$ of

the likelihood ratio. Specifically, we assume for some deterministic sequence, $(I_i: i \in [n])$, that R_i is generated from an instance of the BHT such that hypothesis H_{I_i} is true. This problem can arise if the densities g_0 and g_1 are unknown, but can be factored as $g_k(x) = u(x)h_k(x)$ for $k \in \{0, 1\}$, for some unknown (or very difficult-to-compute) function u and known functions h_0 and h_1 . Then the likelihood ratio can be computed for an observation X using $R = \frac{h_1(X)}{h_0(X)}$, but the distribution of the likelihood ratio depends on the unknown function u . So if it is possible, through simulation or repeated physical trials, to generate independent instances of the BHT, it may be possible to generate the independent samples $R_1, \dots, R_n$ as described.

To elaborate a bit more, we discuss a possible specific scenario related to Cox’s notion of partial likelihood [1]. Suppose $X = (Y_1, S_1, Y_2, S_2, \dots, Y_T, S_T)$, where the components themselves may be vectors. The full likelihood under hypothesis H_k for $k = 0, 1$ is the product of two factors given below, each of which is a product of T factors:

$$\left(\prod_{t=1}^T f_{Y_t|Y^{t-1}, S^{t-1}}(y_t|y^{t-1}, s^{t-1}; k) \right) \cdot \left(\prod_{t=1}^T f_{S_t|Y^t, S^{t-1}}(s_t|y^t, s^{t-1}; k) \right),$$

where $y^t \triangleq (y_{t'}: t' \in [t])$. Cox defined the first factor to be the partial likelihood based on Y and the second factor to be the partial likelihood based on S . If the first factor is very complicated but does not depend on k , and the second factor is known and tractable, we arrive at the form of the total likelihood described above: $g_k(x) = u(x)h_k(x)$ for $k \in \{0, 1\}$.

To avoid possible confusion, we emphasize that the problem considered is an inference problem with independent observations, where the ROC is to be estimated. The space of ROCs is infinite-dimensional. The observations $R_1, \dots, R_n$ are *not* used for a binary hypothesis testing problem.

There is a large classical literature on ROC curves dating to the early 1940s. Much of the emphasis relating to estimating

ROC curves is focused on estimating the area under the ROC curve (AUC), a key performance measure for machine learning algorithms [2]. For estimation of the ROC curves, a popular approach is the binormal model such that the distribution of an observed score is assumed to be a monotonic transformation of Gaussian under either hypothesis, and maximum likelihood estimates of the parameters of the Gaussians are found. See [3], [4] and references therein. The first estimator we consider for the ROC curve, which we call the “empirical ROC curve,” is described by that name in [5]. The empirical ROC curve is the same up to a rotation as the “sample ordinal dominance graph” defined in [6], p. 400.

The paper is organized as follows. Some preliminaries about ROC curves are given in Section II. The empirical estimator of the optimal ROC curve based on using the empirical estimators for the two types of error probabilities is considered in Section III. A performance guarantee is derived based on a well-known bound for empirical estimators of CDFs. The ML estimator of the ROC curve is derived in Section IV. Consistency of the ML estimator with respect to the Lévy metric is demonstrated in Section V. The area under the ML estimator of the ROC curve is derived in Section (VI) and is shown to be a consistent estimator of AUC. Simulations comparing the accuracy of the empirical and ML estimators are given in Section VII, and discussion is in Section VIII. Proofs are found in the appendix.

II. PRELIMINARIES ABOUT OPTIMAL ROC CURVES

A. An extension of a cumulative distribution function (CDF)

The CDF F for an extended random variable R (i.e., R can take the value ∞) is defined by $F(\tau) = \mathbb{P}\{R \leq \tau\}$ for $\tau \in \mathbb{R}$. In this paper ∞ always means $+\infty$. Given a CDF F with $F(0-) = 0$ and possibly a point mass at ∞ , we define an extended version of F , and abuse notation by using F to denote both F and its extension. The extension is defined for $\tau \in \mathbb{R} \cup \{\infty\}$ and $\eta \in [0, 1]$, by $F(\tau, \eta) = (1 - \eta)F(\tau-) + \eta F(\tau)$, where $F(\infty-) = \lim_{\tau \rightarrow \infty} F(\tau)$ and $F(\infty) = 1$. Let $F(\{\tau\}) = F(\tau) - F(\tau-)$ denote the mass at τ . Thus, if R is an extended random variable with CDF F , then $F(\tau, \eta) = \mathbb{P}\{R < \tau\} + \eta \mathbb{P}\{R = \tau\}$. Note the extended version of F is continuous and nondecreasing in (τ, η) in the lexicographically order with $F(0, 0) = 0$ and $F(\infty, 1) = 1$, and hence surjective onto $[0, 1]$. Also, let the extended complementary CDF for F be defined by $F^c(\tau, \eta) = 1 - F(\tau, \eta)$, so that $F^c(\tau, \eta) = \mathbb{P}\{R > \tau\} + \eta \mathbb{P}\{R = \tau\}$.

B. The optimal ROC curve for a BHT

Consider a BHT and let F_0 denote the CDF of the likelihood ratio R under hypothesis H_0 and let F_1 denote the CDF of the observation R under hypothesis H_1 . Then $dF_1(r) = r dF_0(r)$ for $r \in (0, \infty)$ (see Appendix A for details), and $F_1(0) = F_0(\{\infty\}) = 0$, while it is possible that $F_0(0) > 0$ and/or $F_1(\{\infty\}) > 0$.

The likelihood ratio test with threshold τ and randomization parameter η declares H_0 to be true if $R < \tau$, declares H_1 to be true if $R > \tau$, and declares H_1 to be true with probability η

if $R = \tau$. The *optimal ROC curve* is the graph of the function $\text{ROC}(p) : 0 \leq p \leq 1$ defined by $\text{ROC}(p) = F_1^c(\tau, \eta)$ where τ and η are selected such that $F_0^c(\tau, \eta) = p$. Note this is well-defined because F_0 is surjective and for any τ, τ', η , and η' we have $F_0^c(\tau, \eta) = F_0^c(\tau', \eta')$ if and only if $F_1^c(\tau, \eta) = F_1^c(\tau', \eta')$. Equivalently, the optimal ROC curve is the set of points traced out by $P = (F_0^c(\tau, \eta), F_1^c(\tau, \eta))$ as τ and η vary.

Proposition 1: Any one of the functions F_0 , F_1 , or ROC determines the other two.

Remark 1: ROC is a continuous, concave, nondecreasing function over $[0, 1]$ with $R(0) \geq 0$ and $R(1) = 1$. Conversely, any such function is an ROC curve of some BHT.

C. The Lévy metric on the space of ROC curves

Given nondecreasing functions A, B mapping the interval $[0, 1]$ into itself, the *Lévy distance* between them, $L(A, B)$, is the infimum of $\epsilon > 0$ such that

$$A(p - \epsilon) - \epsilon \leq B(p) \leq A(p + \epsilon) + \epsilon \quad \text{for all } p \in \mathbb{R},$$

with the convention that $A(p) = B(p) = 0$ for $p < 0$ and $A(p) = B(p) = 1$ for $p > 1$. A geometric interpretation of $L(A, B)$ is as follows. It is the smallest value of ϵ such that the graph of B is contained in the region bounded by the following two curves: An upper curve obtained by shifting the graph of A to the left by ϵ and up by ϵ , and a lower curve obtained by shifting the graph of A to the right by ϵ and down by ϵ .

Remark 2: It is easy to see the Lévy metric is dominated by the L_∞ metric $L_\infty(A, B) \triangleq \sup_{p \in [0, 1]} |A(p) - B(p)|$. Note the Lévy metric is equivalent to the L_∞ metric on A and B after rotating the graphs clockwise by 45 degrees, and hence tolerates horizontal deviation better than L_∞ . To see this, consider a perfect ROC curve $\text{ROC} \equiv 1$ and an estimate $\widehat{\text{ROC}}(p) = \min\{cp, 1\}$. Then for large c the uniform norm of the difference is 1, while the Lévy distance $\frac{1}{c+1}$ is small.

Lemma 1: Let $F_{a,0}, F_{a,1}, F_{b,0}, F_{b,1}$ denote CDFs for probability distributions on $[0, \infty]$. Let A be the function defined on $[0, 1]$ determined by $F_{a,0}, F_{a,1}$ as follows. For any $p \in [0, 1]$, $A(p) = F_{a,1}^c(\tau, \eta)$, where (τ, η) is the lexicographically smallest point in $[0, \infty] \times [0, 1]$ such that $F_{a,0}^c(\tau, \eta) = p$. (If $F_{a,0}$ and $F_{a,1}$ are the CDFs of the likelihood ratio of a BHT, then A is the corresponding optimal ROC.) Let B be defined similarly in terms of $F_{b,0}$ and $F_{b,1}$. Then

$$\begin{aligned} L(A, B) &\leq \sup_{\tau \in [0, \infty]} \max\{|F_{a,0}(\tau) - F_{b,0}(\tau)|, |F_{a,1}(\tau) - F_{b,1}(\tau)|\}. \end{aligned} \quad (1)$$

We remark that [7] introduces a topology on binary input channels that is related to the Lévy metric used in this paper.

III. THE EMPIRICAL ESTIMATOR OF THE ROC

Consider a BHT and let F_k denote the CDF of the likelihood ratio R under hypothesis H_k for $k = 0, 1$. Suppose for some positive integers n_0 and n_1 , independent random variables $R_{0,1}, \dots, R_{0,n_0}, R_{1,1}, \dots, R_{1,n_1}$ are observed such that $R_{k,j}$

has CDF F_k for $k = 0, 1$ and $1 \leq i \leq n_k$. A straight forward approach to estimate ROC is to estimate F_k using only the n_k observations having CDF F_k for $k = 0, 1$. In other words, let

$$\widehat{F}_k(\tau) = \frac{1}{n_k} \sum_{i=1}^{n_k} I_{\{R_{k,i} \leq \tau\}}$$

for $k = 0, 1$ and let $\widehat{\text{ROC}}_E$, the *empirical estimator* of ROC, have the graph swept out by the point $(\widehat{F}_0^c(\tau, \eta), \widehat{F}_1^c(\tau, \eta))$ as τ varies over $[0, \infty]$ and η varies over $[0, 1]$. In general, $\widehat{\text{ROC}}_E$ is a step function with all jump locations at multiples of $\frac{1}{n_0}$ and the jump sizes being multiples of $\frac{1}{n_1}$. Moreover, $\widehat{\text{ROC}}_E$ depends on the numerical values of the observations only through the ranks (i.e., the order, with ties accounted for) of the observations.

The estimator $\widehat{\text{ROC}}_E$ as we have defined it is typically not concave, and is hence typically not the optimal ROC curve for a BHT. This suggests the *concavified empirical estimator* $\widehat{\text{ROC}}_{CE}$ defined to be the least concave majorant of $\widehat{\text{ROC}}_E$. Equivalently, the region under the graph of $\widehat{\text{ROC}}_{CE}$ is the convex hull of the region under $\widehat{\text{ROC}}_E$.

We write “ $X_n \rightarrow c$ a.s. as $n \rightarrow \infty$ ” where a.s. is the abbreviation for “almost surely,” to mean $\mathbb{P}\{\lim_{n \rightarrow \infty} X_n = c\} = 1$. The following provides some performance guarantees for the empirical and concavified empirical estimators.

Proposition 2: Let $n = n_0 + n_1$ and $\alpha = \frac{n_0}{n_1 + n_0}$. Then the empirical estimator satisfies

$$\mathbb{P}\{L(\text{ROC}, \widehat{\text{ROC}}_E) \geq \delta\} \leq 2e^{-2n\alpha\delta^2} + 2e^{-2n(1-\alpha)\delta^2}. \quad (2)$$

Moreover, if $\alpha \in (0, 1)$ is fixed and $n_k \rightarrow \infty$ for $k = 0, 1$ with $\frac{n_1}{n_0} = \frac{1-\alpha}{\alpha}$, then $L(\text{ROC}, \widehat{\text{ROC}}_E) \rightarrow 0$ a.s. as $n \rightarrow \infty$. In other words, $\widehat{\text{ROC}}_E$ is consistent in the Lévy metric. In general, $L(\text{ROC}, \widehat{\text{ROC}}_{CE}) \leq L(\text{ROC}, \widehat{\text{ROC}}_E)$, so the above statements are also true with $\widehat{\text{ROC}}_E$ replaced by $\widehat{\text{ROC}}_{CE}$.

Remark 3: A consistency result for the empirical estimator in terms of the uniform norm with some restrictions on the distributions F_0 and F_1 has been developed in [4].

While the bound (2) seems reasonably tight for α near $1/2$, the bound is degenerate if α is very close to zero or one. The maximum likelihood estimator derived in the next section is consistent even if all the observations are generated under a single hypothesis.

IV. THE ML ESTIMATOR OF THE ROC

Consider a BHT and let F_k denote the CDF of the likelihood ratio R under hypothesis H_k for $k = 0, 1$, and suppose for some $n \geq 1$ and deterministic binary sequence $I_i : i \in [n]$, independent random variables $R_1, \dots, R_n$ are observed such that for each $i \in [n]$, the distribution of R_i is F_{I_i} . The likelihood of the set of observations is the probability the observations take their particular values, and that is determined by F_0 and F_1 , and hence, by Proposition 1, also by ROC or by F_0 alone or by F_1 alone. Hence, it makes sense to ask what is the maximum likelihood (ML) estimator of ROC, or equivalently, what is the ML estimator of the triplet

(F_0, F_1, ROC) , given $I_i : i \in [n]$ and $R_i, i \in [n]$. The answer is given by the proposition in this section.

Let φ_n be defined by

$$\varphi_n(\lambda) \triangleq \begin{cases} \frac{1}{n} \sum_{i=1}^n \frac{1}{\lambda + (1-\lambda)R_i} & \text{if } 0 \leq \lambda < 1, \\ 1 & \text{if } \lambda = 1. \end{cases} \quad (3)$$

Note that φ_n is finite over $(0, 1]$, continuous over $[0, 1]$, and convex over $[0, 1]$. Moreover, $\varphi_n(0) = \infty$ if and only if $R_i = 0$ for some i and φ_n has a jump discontinuity at 1 if and only if $R_i = \infty$ for some i .

Proposition 3: The ML estimator $(\widehat{F}_0, \widehat{F}_1, \widehat{\text{ROC}}_{ML})$ is unique and is determined as follows. $\widehat{\text{ROC}}_{ML}$ is the optimal ROC curve corresponding to $\widehat{F}_0$ and/or $\widehat{F}_1$, where:

- 1) If $\frac{1}{n} \sum_{i=1}^n R_i \leq 1$ (implying $R_i < \infty$ for all i), then for $\tau \in [0, \infty)$

$$\widehat{F}_0(\tau) = \frac{1}{n} \sum_{i=1}^n I_{\{R_i \leq \tau\}}; \quad \widehat{F}_1(\tau) = \frac{1}{n} \sum_{i=1}^n I_{\{R_i \leq \tau\}} R_i.$$

- 2) If $\frac{1}{n} \sum_{i=1}^n \frac{1}{R_i} \leq 1$ (implying $R_i > 0$ for all i), then for $\tau \in [0, \infty)$

$$\widehat{F}_0^c(\tau) = \frac{1}{n} \sum_{i=1}^n I_{\{R_i > \tau\}} \frac{1}{R_i}; \quad \widehat{F}_1(\tau) = \frac{1}{n} \sum_{i=1}^n I_{\{R_i \leq \tau\}}.$$

- 3) If neither of the previous two cases holds, then for $\tau \in [0, \infty)$

$$\widehat{F}_0(\tau) = \frac{1}{n} \sum_{i=1}^n I_{\{R_i \leq \tau\}} \frac{1}{\lambda_n + (1 - \lambda_n)R_i}$$

and

$$\widehat{F}_1(\tau) = \frac{1}{n} \sum_{i=1}^n I_{\{R_i \leq \tau\}} \frac{R_i}{\lambda_n + (1 - \lambda_n)R_i},$$

where λ_n is the unique value in $(0, 1)$ so that $\varphi_n(\lambda_n) = 1$.

Remark 4:

- 1) The estimator does not depend on the indicator variables $I_i : i \in [n]$. That is, the estimator does not take into account which observations are generated using which hypothesis.
- 2) Cases 1) and 2) can both hold only if $R_i = 1$ for all i , because $r + \frac{1}{r} \geq 2$ for $r \in [0, \infty]$ with equality if and only if $r = 1$.
- 3) If case 1) holds with strict inequality, then $\widehat{F}_1(\{\infty\}) > 0$, even though $R_i < \infty$ for all i .
- 4) Similarly, if case 2) holds with strict inequality, then $\widehat{F}_0(0) > 0$ even though $R_i > 0$ for all i .
- 5) Suppose case 3) holds. The existence and uniqueness of λ_n can be seen as follows. Since case 2) does not hold, $\varphi_n(0) > 1$. If $R_i = \infty$ for some i then $\varphi_n(1-) < 1$; and if $R_i < \infty$ for all i , then $\varphi'_n(1) = \frac{1}{n} \sum_{i=1}^n (R_i - 1) > 0$, where we have used the fact case 1) does not hold. Thus, $\varphi_n(\lambda) < 1$ if $\lambda < 1$ and λ is sufficiently close to 1. Therefore the existence and uniqueness of λ_n in case 3) follow from the properties of φ_n .

- 6) The proof of Proposition 3 is in Appendix D. Maximizing the likelihood is reduced to a convex optimization problem and the KKT conditions are used.

The following corollary presents an alternative version of Proposition 3 that consolidates the three cases of Proposition 3. It is used in the proof of consistency of the ML estimator.

Corollary 1: The ML estimator is unique and is determined as follows. For $\tau \in [0, \infty)$,

$$\widehat{F}_0^c(\tau) = \frac{1}{n} \sum_{i=1}^n I_{\{R_i > \tau\}} \frac{1}{\lambda_n + (1 - \lambda_n)R_i}$$

and

$$\widehat{F}_1(\tau) = \frac{1}{n} \sum_{i=1}^n I_{\{R_i \leq \tau\}} \frac{R_i}{\lambda_n + (1 - \lambda_n)R_i},$$

where $\lambda_n = \min\{\lambda \in [0, 1] : \varphi_n(\lambda) \leq 1\}$.

Remark 5: It is shown in the proof of Proposition 3 that $\lambda_n \rightarrow \alpha$ a.s. as $n \rightarrow \infty$ if F_0 is not identical to F_1 . Thus, for n large, λ_n is approximately the prior probability that a given observation is generated under hypothesis H_0 and $n\lambda_n$ is approximately the number of observations generated under H_0 . The ML estimator $\widehat{F}_0$ can be written as

$$\widehat{F}_0^c(\tau) = \frac{1}{n\lambda_n} \sum_{i=1}^n I_{\{R_i > \tau\}} \frac{\lambda_n}{\lambda_n + (1 - \lambda_n)R_i},$$

where $\frac{\lambda_n}{\lambda_n + (1 - \lambda_n)R_i}$ can be interpreted as an estimate of the posterior probability that R_i was generated under H_0 .

V. CONSISTENCY OF THE ML ESTIMATE OF THE ROC

Suppose R has CDF F_0 under H_0 and CDF F_1 under H_1 , such that R is also the likelihood ratio. Let α be fixed with $\alpha \in [0, 1]$ and suppose the observations $R_1, R_2, \dots$ are independent, identically distributed random variables with the mixture distribution $\alpha F_0 + (1 - \alpha)F_1$. We are considering the problem of estimating the ROC curve for the BHT for distributions F_0 and F_1 using the ML estimator $(\widehat{\text{ROC}}_{\text{ML}}, \widehat{F}_0, \widehat{F}_1)$ based on the observations $R_1, \dots, R_n$ as $n \rightarrow \infty$. For brevity we suppress n in the notation for $\widehat{F}_0, \widehat{F}_1$, and $\widehat{\text{ROC}}_{\text{ML}}$.

Proposition 4 (Consistency of the ML estimator of the ROC curve): The ML estimator of the ROC curve for H_0 vs. H_1 is consistent. That is, $L(\widehat{\text{ROC}}_{\text{ML}}, \text{ROC}) \rightarrow 0$ a.s. as $n \rightarrow \infty$.

The proof of Proposition 4 is given in Appendix F. The first part of the proof is to establish that if F_0 is not identical to F_1 , then $\lambda_n \rightarrow \alpha$ a.s. as $n \rightarrow \infty$. Thus, the estimators $\widehat{F}_0$ and $\widehat{F}_1$ are close to functions obtained by replacing λ_n by α , and those resulting functions converge to F_0 and F_1 , respectively, by the law of large numbers.

VI. AREA UNDER THE ML ROC CURVE

The area under $\widehat{\text{ROC}}_{\text{ML}}$, which we denote by $\widehat{\text{AUC}}_{\text{ML}}$, is a natural candidate for an estimator of AUC, the area under ROC for the BHT. An expression for it is given in the following

proposition. Let λ_n be defined as in Corollary 1 and for $i, i' \in [n]$, let

$$T_{i,i'} = \frac{\max\{R_i, R_{i'}\}}{2(\lambda_n + (1 - \lambda_n)R_i)(\lambda_n + (1 - \lambda_n)R_{i'})},$$

with the following understanding. Recall that if $R_i = 0$ for some $i \in [n]$ then $\lambda_n > 0$, so the denominator in $T_{i,i'}$ is always strictly positive. Also recall that if $R_i = \infty$ for some $i \in [n]$ then $\lambda_n < 1$, and the following is based on continuity: If $R_i = R_{i'} = \infty$ set $T_{i,i'} = 0$. If $R_i < R_{i'} = \infty$, set $T_{i,i'} = \frac{1}{2(\lambda_n + (1 - \lambda_n)R_i)(1 - \lambda_n)}$.

Proposition 5:

- 1) The area under $\widehat{\text{ROC}}_{\text{ML}}$ is given by

$$\widehat{\text{AUC}}_{\text{ML}} = \frac{1}{n^2} \sum_{i=1}^n \sum_{i'=1}^n T_{i,i'}. \quad (4)$$

- 2) The estimator $\widehat{\text{AUC}}_{\text{ML}}$ is consistent: $\widehat{\text{AUC}}_{\text{ML}} \rightarrow \text{AUC}$ a.s. as $n \rightarrow \infty$.
- 3) Let R, R' be independent random variables and use $\mathbb{E}_0$ to denote expectation when they both have CDF F_0 . Then

$$\text{AUC} = \frac{1}{2} \mathbb{E}_0[\max\{R, R'\}] + F_1(\{\infty\}) \quad (5)$$

$$= 1 - \frac{1}{2} \mathbb{E}_0[\min\{R, R'\}]. \quad (6)$$

- 4) For $i \neq i'$, $\mathbb{E}[T_{i,i'}^{(\alpha)}] = \text{AUC}$, where $T_{i,i'}^{(\alpha)}$ is the same as $T_{i,i'}$ with λ_n replaced by α .

Remark 6:

- 1) The expression (4) can be verified by checking that it reduces to (5) in case $\mathbb{E}_0$ is replaced by expectation using $\widehat{F}_0$ and F_1 is replaced by $\widehat{F}_1$. A more direct proof of (4) is given.
- 2) The true AUC for the BHT is invariant under swapping the two hypotheses. Similarly, $\widehat{\text{AUC}}_{\text{ML}}$ is invariant under replacing λ_n by $1 - \lambda_n$ and R_i by $\frac{1}{R_i}$ for all i . If $R_i = 1$ for all i , $\widehat{\text{AUC}}_{\text{ML}} = 1/2$.
- 3) Part 4) of the proposition is to be expected due to the consistency of $\widehat{\text{AUC}}_{\text{ML}}$ and the law of large numbers, because if n is large, most of the n^2 terms in (4) are indexed by i, i' with $i \neq i'$, and we know, if F_0 is not identical to F_1 , that $\lambda_n \rightarrow \alpha$ a.s. as $n \rightarrow \infty$.

VII. SIMULATIONS

In this section we test the estimators in a simple bi-normal setting. Let X be distributed by $\mathcal{N}(0, 1)$ under H_0 and by $\mathcal{N}(\mu, 1)$ under H_1 . Then the likelihood ratio is $R = \exp(\mu X - \frac{1}{2}\mu^2)$ and the ROC curve is given by $\text{ROC}(p) = 1 - \Phi(\Phi^{-1}(1 - p) - \mu)$, where Φ is the CDF of the standard Gaussian distribution. Simulation results for the three ROC estimators with $\mu = 1$ are shown in Fig. 1 with various numbers of observations under the two hypotheses (n_0, n_1) . For each pair of (n_0, n_1) two figures are shown. The left figure shows the estimated ROC curves and the true ROC curve for a single sample instance of $n_0 + n_1$ likelihood observations. The right figure shows the average Lévy distances of the estimators

over $N = 500$ such sample instances with error bars (i.e., plus or minus sample standard deviations divided by $\sqrt{N}$). The simulation code can be found at [8].

The two empirical estimators have similar performance, while CE outperforms E slightly in terms of the Lévy distance. Note $\widehat{\text{ROC}}_{\text{CE}}$, as the least concave majorant of $\widehat{\text{ROC}}_{\text{E}}$, could be biased toward higher probability of detection as evidenced by the sample instances.

It can be seen that the ML estimator (MLE) achieves much smaller Lévy distance than E or CE. The difference is more pronounced when the number of observations under one hypothesis is significantly smaller than that under the other, as seen in Figs. 1d–1f. This is because E and CE calculate the empirical distributions based on the likelihood ratio observations under the two hypotheses separately before combining the empirical distributions into an estimated ROC curve. As a result, having very few samples under either hypothesis results in errors in estimating the ROC curve regardless of how accurate the estimated distribution under the other hypothesis is. In contrast, every observation contributes to the joint estimation of the pair of distributions in MLE, so the ROC curve can be accurately estimated even when there are very few samples from one hypothesis. In fact, as Section V suggested, MLE works even if all samples are generated from the same hypothesis (see Fig. 1g), while E and CE do not work because one of the distributions cannot be estimated at all. This demonstrates that MLE effectively utilizes samples from either hypothesis based on the relation between F_0 and F_1 (Proposition 1).

Sensitivity of the performance of the estimators to the mean difference μ and the sample composition $\alpha = n_0/(n_0 + n_1)$ is shown in Fig 2, again averaged over $N = 500$ instances. In Fig. 2a, different values of μ are used for fixed $n_0 = n_1 = 100$. In Fig. 2b, different values of α are used for $\mu = 1$ and a fixed total number of samples $n_0 + n_1 = 200$. In both cases, MLE outperforms E and CE consistently and is insensitive to μ and α . Note all three estimators require the knowledge of μ to calculate the likelihood ratios, while MLE does not need the hypothesis labels and hence is completely oblivious to α .

VIII. DISCUSSION

The qualitative differences between the empirical estimator $\widehat{\text{ROC}}_{\text{E}}$ and the ML estimator $\widehat{\text{ROC}}_{\text{ML}}$ are striking. Only the rank ordering of the samples is used by the empirical estimator—not the numerical values. So it is important to track which samples are generated with which distribution. The ML estimator does not depend on which samples were generated with which distribution and exact numerical values are used.

We proved a consistency result for $\widehat{\text{ROC}}_{\text{ML}}$ but perhaps it also satisfies a bound similar to (2). It may be interesting to explore theoretical guarantees on the accuracy of the ML estimator for large, fixed n as a function of the fraction, α , of observations that are taken under hypothesis H_0 .

A BHT is the same as a binary input channel. Work of Blackwell and others working on the comparison of experiments has led to canonical channel descriptions that are

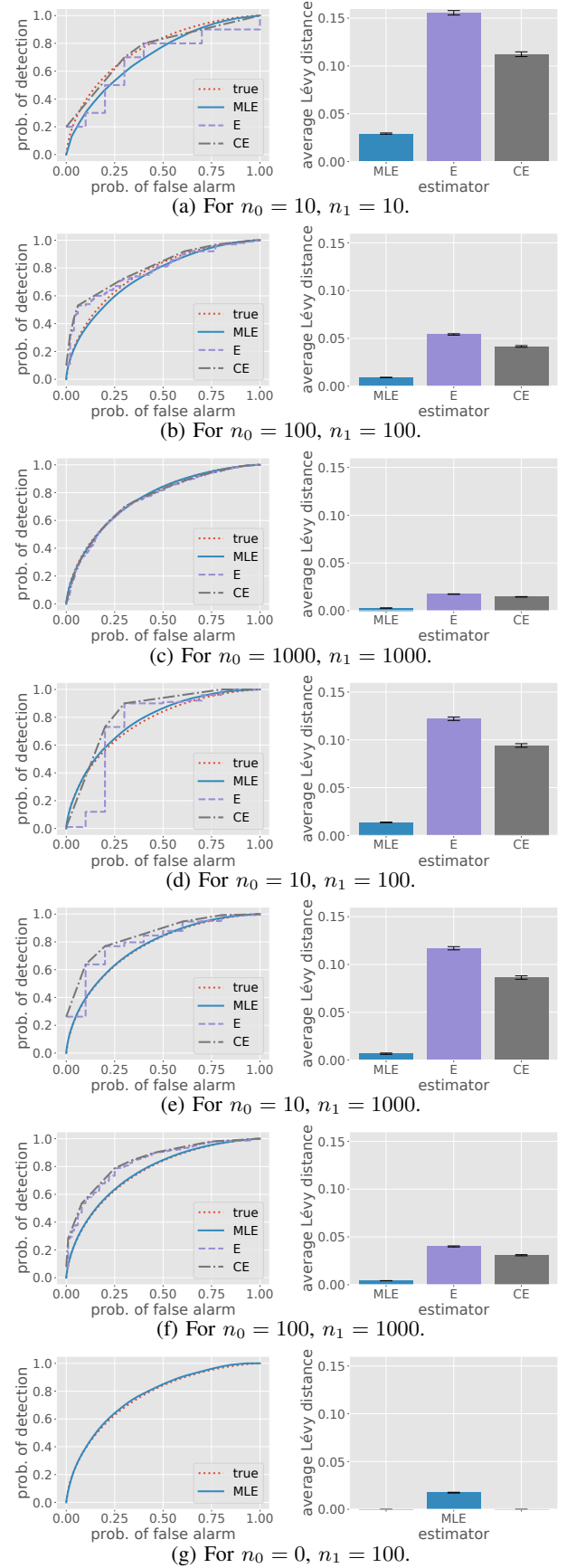
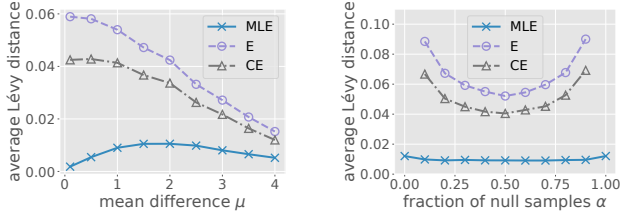


Fig. 1: Sample instances and average errors for $\mu = 1$.



(a) For $n_0 = n_1 = 100$. (b) For $\mu = 1$ and $n_0 + n_1 = 200$.

Fig. 2: Average errors.

equivalent to the ROC curve, such as the Blackwell measure. The Blackwell measure is the distribution of the posterior probability that hypothesis H_0 is true for equal prior probabilities $1/2$ for the hypotheses. See [9] and references therein. It may be of interest to explore estimation of various canonical channel descriptions besides the ROC under various metrics.

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APPENDIX A RELATION OF F_0 AND F_1

Let P_k and g_k denote the probability distribution and the probability density function with respect to some reference measure μ of the observation X in a measurable space $(\mathcal{X}, \Sigma)$ under hypothesis H_k for $k = 0, 1$. In other words, $P_k(A) = \int_A g_k(x) \mu(dx)$ for any $A \in \Sigma$. Let $\rho: \mathcal{X} \rightarrow \mathbb{R} \triangleq \mathbb{R} \cup \{\infty\}$ be defined by

$$\rho(x) = \begin{cases} \frac{g_1(x)}{g_0(x)} & \text{if } g_0(x) > 0, \\ \infty & \text{if } g_0(x) = 0. \end{cases}$$

Then ρ is a Borel measurable function denoting the likelihood ratio given an observation. The probability distribution of the extended random variable $R = \rho(X)$ under H_k is the push-forward of the measure P_k induced by the function ρ for $k = 0, 1$, denoted by ν_k . The probability distribution ν_k restricted to $\mathbb{R}$ is also the unique Borel measure (known as the Lebesgue–Stieltjes (L–S) measure corresponding to F_k , the CDF of R) on $[0, \infty)$ such that $\nu_k([0, \tau]) = F_k(\tau)$ for all $\tau \in [0, \infty)$.

Throughout this paper, integrals of the form $\int h(r) dF(r)$ are understood to be Lebesgue–Stieltjes integrals (for the extended real numbers). That is,

$$\int_{\mathbb{R}} h(r) dF(r) \triangleq \int_{\mathbb{R}} h(r) \nu_F(dr),$$

for any Borel measurable function h .

Proposition 6: For any Borel set A in $\mathbb{R}$,

$$\nu_1(A) = \int_A r \nu_0(dr).$$

In other words, when restricted to the Borel sets in $\mathbb{R}$, ν_1 is absolutely continuous with respect to ν_0 , and the Radon–Nikodym derivative is the identity function almost everywhere with respect to ν_0 .

Proof: By the change-of-variables formula for push-forward measures, for any Borel set A in $\mathbb{R}$,

$$\begin{aligned} \nu_1(A) &= \int_{\mathbb{R}} I_A(r) \nu_1(dr) \\ &= \int_{\mathcal{X}} I_A(\rho(x)) P_1(dx) \\ &= \int_{\mathcal{X}} I_A(\rho(x)) g_1(x) \mu(dx) \\ &= \int_{\mathcal{X}} I_A(\rho(x)) \rho(x) g_0(x) \mu(dx) \\ &= \int_{\mathcal{X}} I_A(\rho(x)) \rho(x) P_0(dx) \\ &= \int_{\mathbb{R}} I_A(r) r \nu_0(dr) \\ &= \int_A r \nu_0(dr), \end{aligned}$$

implying the proposition. ■

APPENDIX B PROOFS FOR SECTION II

Proof of Proposition 1: The function F_0 determines F_1 by $F_1(\tau) = \int_{[0, \tau]} r dF_0(r)$ for $\tau \in [0, \infty)$. Conversely, F_1 determines F_0 by $F_0^c(\tau) = \int_{(\tau, \infty)} \frac{1}{r} dF_1(r)$ for $\tau \in [0, \infty)$. So either one of F_0 or F_1 determines the other, and hence also determines ROC as described in Section II-B. To complete the proof it suffices to show that ROC determines F_0 . The function ROC is concave so it has a right-hand derivative on $[0, 1]$ which we denote by ROC' , with the understanding that $\text{ROC}'(0) \in [1, \infty]$ and the convention that $\text{ROC}'(1) = 0$. Then we claim $F_0^c(\tau) = \min \{p \in [0, 1] : \text{ROC}'(p) \leq \tau\}$ for $\tau \in [0, \infty)$. ■

Proof of Lemma 1 : Let the right-hand side of (1) be denoted by ϵ . Note that

$$\epsilon = \sup_{\tau \in (0, \infty), \eta \in [0, 1]} \max\{|F_{a,0}^c(\tau, \eta) - F_{b,0}^c(\tau, \eta)|, |F_{a,1}^c(\tau, \eta) - F_{b,1}^c(\tau, \eta)|\}, \quad (7)$$

because for τ fixed, the right-hand side of (7) is the maximum of a convex function of η and the value at $\eta = 0$ and $\eta = 1$ is obtained by the right-hand side of (1) at τ and τ , respectively. We appeal to the geometric interpretation of $L(A, B)$. Consider any point $(p, B(p))$ on the graph of B . It is equal to $(F_{b,0}^c(\tau, \eta), F_{b,1}^c(\tau, \eta))$ for some choice of (τ, η) . Let $(p', A(p'))$ denote the point on the graph of A for the same choice of (τ, η) . In other words, it is the point $(F_{a,0}^c(\tau, \eta), F_{a,1}^c(\tau, \eta))$. Then $(p, B(p))$ can be reached from $(p', A(p'))$ by moving horizontally at most ϵ and moving vertically at most ϵ . So $(p, B(p))$ is contained in the region bounded between the upper and lower shifts of the graph of A as claimed. ■

APPENDIX C PROOF OF PROPOSITION 2

Proof: The Dvoretzky–Kiefer–Wolfowitz (DKW) inequality with the optimal constant proved by Massart implies:

$$\mathbb{P}\left\{\sup_{\tau \in [0, \infty)} |F_k(\tau) - \widehat{F}_k(\tau)| \geq \delta\right\} \leq 2e^{-2n_k \delta^2}. \quad (8)$$

Combining (8) with Lemma 1 implies (2). The consistency of $\widehat{\text{ROC}}_E$ follows from the Borel–Cantelli lemma and the fact the sum of the right-hand side of (2) over n is finite for any $\delta > 0$.

The final inequality follows from the following observations: $\widehat{\text{ROC}}_{CE}(p) \geq \widehat{\text{ROC}}_E(p)$ for $p \in [0, 1]$, and if $\widehat{\text{ROC}}_E$ is less than or equal to the concave function $p \mapsto \text{ROC}(p + \epsilon) + \epsilon$, then so is $\widehat{\text{ROC}}_{CE}$, by the definition of least concave majorant. ■

APPENDIX D DERIVATION OF $\widehat{\text{ROC}}_{ML}$

Proposition 3 and its corollary are proved in this section.

Proof of Proposition 3: Given the binary sequence $(I_i : i \in [n])$ and the likelihood ratio samples $R_1, \dots, R_n$, let $0 = v_0 < v_1 < v_2 < \dots < v_m < v_{m+1} = \infty$ be the set of unique values of the samples, augmented by $v_0 = 0$ and $v_{m+1} = \infty$ even if 0 and/or ∞ is not among the observed samples. Let $(c_0^0, c_1^0, c_2^0, \dots, c_m^0)$ denote the multiplicities of the values from among $(R_i : I_i = 0)$ and let $(c_1^1, c_2^1, \dots, c_m^1, c_{m+1}^1)$ denote the multiplicities of the values from among $(R_i : I_i = 1)$.

Let $a_j = F_0(\{v_j\})$ for $0 \leq j \leq m$ and let $b = F_1(\{\infty\})$. Thus a_j is the probability mass at v_j under hypothesis H_0 for $0 \leq j \leq m$. The corresponding probability mass at v_j under hypothesis H_1 is $a_j v_j$ for $0 \leq j \leq m$ and the probability mass at v_{m+1} under hypothesis H_1 is b .

The log-likelihood to be maximized is given by

$$\sum_{j=0}^m c_j^0 \log a_j + \sum_{j=1}^m c_j^1 \log(a_j v_j) + c_{m+1}^1 \log b,$$

where $0 \log 0$ is understood as 0 and $\log 0$ is understood as negative infinity. Equivalently, dropping the term $\sum_{j=1}^m c_j^1 \log(v_j)$ which does not depend on F_0 (or F_1 or ROC), the ML estimator is to maximize

$$\sum_{j=0}^m c_j \log a_j + c_{m+1} \log b,$$

where $c_0 \triangleq c_0^0$, $c_{m+1} \triangleq c_{m+1}^1$ and $c_j \triangleq c_j^0 + c_j^1$ for $1 \leq j \leq m$. In other words, c_j is the total multiplicity of v_j in all samples regardless of the hypothesis.

For any choice of F_0 (or F_1 or ROC), the probabilities satisfy the constraint:

$$\sum_{j=0}^m a_j \leq 1 \text{ and } \sum_{j=1}^m a_j v_j + b \leq 1. \quad (9)$$

The inequalities in (9) both hold with equality if the distribution F_0 (or equivalently F_1) assigns probability one to the set $\{v_0, \dots, v_{m+1}\}$. Otherwise, both inequalities are strict. We claim and now prove that any ML estimator is such that both inequalities in (9) hold with equality. It is true in the degenerate special case that $R_i \in \{0, \infty\}$ for all i , in which case an ML estimator is given by $\text{ROC}(p) \equiv 1$, $F_0(0) = 1$ and $F_1(\{\infty\}) = 1$. So we can assume $m \geq 1$ and there is a value j_0 (for example, $j_0 = 1$) such that $1 \leq j_0 \leq m$. If F_0 does not assign probability one to $\{v_0, \dots, v_{m+1}\}$ then the same is true for F_1 , so that strict inequality must hold in both constraints in (9). Then the probability mass from F_0 (and F_1) that is not on the set $\{v_0, \dots, v_{m+1}\}$ can be removed and mass can be added to F_0 at 0 and v_{j_0} and to F_1 at v_{j_0} and ∞ such that both constraints in (9) hold with equality and the likelihood is strictly increased. This completes the proof of the claim.

Therefore, any ML estimator is such that the distributions are supported on the set $\{v_0, \dots, v_{m+1}\}$ and the probabilities assigned to the points give an ML estimator if and only if they are solutions to the following convex optimization problem:

$$\begin{aligned} \max_{a \geq 0, b \geq 0} \quad & \sum_{j=0}^m c_j \log a_j + c_{m+1} \log b \\ \text{s.t.} \quad & \sum_{j=0}^m a_j = 1 \text{ and } \sum_{j=1}^m a_j v_j + b = 1. \end{aligned} \quad (10)$$

The relaxed Slater constraint qualification condition is satisfied for (10), so there exists a solution and dual variables satisfying the KKT conditions (see Theorem 3.2.4 in [10]). The Lagrangian is

$$\begin{aligned} L(a, b, \lambda, \mu) = & \sum_{j=0}^m c_j \log a_j + c_{m+1} \log b \\ & - \left(\sum_{j=0}^m a_j - 1 \right) \lambda - \left(\sum_{j=1}^m a_j v_j + b - 1 \right) \mu. \end{aligned}$$

The KKT conditions on (a, b, λ, μ) are

$$\begin{aligned} a \geq 0, b \geq 0; \quad & \sum_{j=0}^m a_j = 1; \quad \sum_{j=1}^m a_j v_j + b = 1; \\ \frac{\partial L}{\partial a_0} \leq 0; \quad & a_0 \cdot \frac{\partial L}{\partial a_0} = 0; \quad \frac{\partial L}{\partial a_j} = 0 \text{ for } j \in [m]; \\ \frac{\partial L}{\partial b} \leq 0; \quad & b \cdot \frac{\partial L}{\partial b} = 0, \end{aligned}$$

where

$$\begin{aligned} \frac{\partial L}{\partial a_0}(a, b, \lambda, \mu) &= \begin{cases} \frac{c_0}{a_0} - \lambda & \text{if } c_0 > 0, \\ -\lambda & \text{if } c_0 = 0; \end{cases} \\ \frac{\partial L}{\partial a_j}(a, b, \lambda, \mu) &= \frac{c_j}{a_j} - \lambda - v_j \mu \quad \text{for } j \in [m]; \\ \frac{\partial L}{\partial b}(a, b, \lambda, \mu) &= \begin{cases} \frac{c_{m+1}}{b} - \mu & \text{if } c_{m+1} > 0, \\ -\mu & \text{if } c_{m+1} = 0. \end{cases} \end{aligned}$$

Solving the KKT conditions yields:

1) If $c_{m+1} = 0$ and $\sum_{j=1}^m v_j c_j \leq \sum_{j=0}^m c_j$, then

$$\begin{aligned} \hat{a}_j &= \frac{c_j}{\sum_{k=0}^m c_k} \quad \text{for } 0 \leq j \leq m; \\ \hat{b} &= 1 - \frac{\sum_{j=1}^m v_j c_j}{\sum_{j=0}^m c_j}; \quad \hat{\lambda} = \sum_{j=0}^m c_j; \quad \hat{\mu} = 0. \end{aligned}$$

2) Otherwise, if $c_0 = 0$ and $\sum_{j=1}^m c_j / v_j \leq \sum_{j=1}^{m+1} c_j$, then

$$\begin{aligned} \hat{a}_j &= \frac{c_j}{v_j \mu} \quad \text{for } 1 \leq j \leq m; \\ \hat{a}_0 &= 1 - \frac{\sum_{j=1}^m c_j / v_j}{\sum_{j=1}^{m+1} c_j}; \\ \hat{b} &= 0; \quad \hat{\lambda} = 0; \quad \hat{\mu} = \sum_{k=1}^{m+1} c_k. \end{aligned}$$

3) Otherwise, $\hat{\lambda} > 0, \hat{\mu} > 0$ are determined by solving

$$\sum_{j=0}^m \frac{c_j}{\lambda + v_j \mu} = 1, \quad (11)$$

$$\sum_{j=1}^m \frac{c_j}{\lambda / v_j + \mu} + \frac{c_{m+1}}{\mu} = 1, \quad (12)$$

and for $0 \leq j \leq m$,

$$\hat{a}_j = \frac{c_j}{\hat{\lambda} + v_j \hat{\mu}}, \quad \hat{b} = \frac{c_{m+1}}{\hat{\mu}}.$$

Multiplying both sides of (11) by λ and both sides of (12) by μ and adding the respective sides of the two equations obtained, yields $\lambda + \mu = \sum_{j=0}^{m+1} c_j = n$. The above conditions can be expressed in terms of the variables R_i , and then replacing μ by $n - n\lambda_n$ and λ by $n\lambda_n$ yields the proposition. ■

Proof of Corollary 1: Corollary 1 is deduced from Proposition 3 as follows. If $R_i = 1$ for $1 \leq i \leq n$ then

the corollary gives that both $\widehat{F}_0$ and $\widehat{F}_1$ have all their mass at $r = 1$, in agreement with Proposition 3. So for the remainder of the proof suppose $R_i \neq 1$ for some i .

Consider the three cases of Proposition 3. If case 1) holds then $\varphi_n(1-) = 1$ and $\varphi'_n(1) = \frac{1}{n} \sum_{i=1}^n (R_i - 1) \leq 0$. Also, $R_i < \infty$ for $1 \leq i \leq n$. Since $R_i \notin \{1, \infty\}$ for at least one value of i , φ_n is strictly convex over $[0, 1]$. Therefore, $\varphi_n(\lambda) > 1$ for $\lambda \in [0, 1)$. Thus, λ_n defined in the corollary is given by $\lambda_n = 1$, and the corollary agrees with Proposition 3.

If case 2) holds then $\varphi_n(0) \leq 1$. Thus, λ_n defined in the corollary is given by $\lambda_n = 0$, and the corollary agrees with Proposition 3.

If neither case 1) nor case 2) holds, then λ_n in the corollary is the same as λ_n in Proposition 3, and the corollary again agrees with Proposition 3. ■

APPENDIX E

FROM POINTWISE TO UNIFORM CONVERGENCE OF CDFs

The following basic lemma shows that uniform convergence of a sequence $(F_n: n \geq 1)$ of CDFs to a fixed limit is equivalent to pointwise convergence of both the sequence and the corresponding sequence of left limit functions, at each of a suitable countably infinite set of points. The CDFs in this section may correspond to probability distributions with positive mass at $-\infty$ and/or ∞ .

Lemma 2 (Finite net lemma for CDFs): Given a CDF F and any integer $L \geq 1$, there exist $c_1, \dots, c_{L-1} \in \mathbb{R} \cup \{-\infty, \infty\}$ such that for any CDF G , $\sup_{c \in \mathbb{R}} |F(c) - G(c)| \leq \delta + \frac{1}{L}$ where

$$\delta = \max_{1 \leq \ell \leq L-1} \max\{|F(c_\ell) - G(c_\ell)|, |F(c_\ell-) - G(c_\ell-)|\}.$$

Proof: Let $c_\ell = \min\{c \in \mathbb{R} \cup \{-\infty, \infty\}: F(c) \geq \frac{\ell}{L}\}$ for $1 \leq \ell \leq L-1$. Also, let $c_0 = -\infty$ and $c_L = \infty$. The fact $F(c_{\ell+1}-) - F(c_\ell) \leq \frac{1}{L}$ for $0 \leq \ell \leq L-1$ and the monotonicity of F and G implies the following. For $0 \leq \ell \leq L-1$ and $c \in (c_\ell, c_{\ell+1})$,

$$G(c) \geq G(c_\ell) \geq F(c_\ell) - \delta \geq F(c) - \delta - \frac{1}{L}$$

and similarly

$$G(c) \leq G(c_{\ell+1}-) \leq F(c_{\ell+1}-) + \delta \leq F(c) + \delta + \frac{1}{L}.$$

Since $\mathbb{R} \subset \{c_1, \dots, c_{L-1}\} \cup (\cup_{\ell=1}^{L-1} (c_\ell, c_{\ell+1}))$, it follows that $|F(c) - G(c)| \leq \delta + \frac{1}{L}$ for all $c \in \mathbb{R}$, as was to be proved. ■

Corollary 2: If F is a CDF, there is a countable sequence $(c_\ell: \ell \geq 1)$ such that, for any sequence of CDFs $(F_n: n \geq 1)$, $\sup_{c \in \mathbb{R}} |F(c) - F_n(c)| \rightarrow 0$ if and only if $F_n(c_\ell) \rightarrow F(c_\ell)$ and $F_n(c_\ell-) \rightarrow F(c_\ell-)$ as $n \rightarrow \infty$ for all $\ell \geq 1$.

Proof: Given F , let $(L_j: j \geq 1)$ be a sequence of integers converging to ∞ . For each j , Lemma 2 implies the existence of $L_j - 1$ values c_ℓ with a specified property. Let the infinite sequence $(c_\ell: \ell \geq 1)$ be obtained by concatenating those finite sequences. ■

APPENDIX F
PROOF OF CONSISTENCY OF ML ESTIMATOR

The proof of the Proposition 4 is given in this section after some preliminary results. Define $\varphi(\lambda)$ for $0 \leq \lambda \leq 1$ by

$$\varphi(\lambda) \triangleq \begin{cases} \mathbb{E} \left[\frac{1}{\lambda + (1-\lambda)R} \right] & \text{if } 0 \leq \lambda < 1, \\ 1 & \text{if } \lambda = 1. \end{cases} \quad (13)$$

For any fixed $\lambda \in [0, 1]$, $\varphi_n(\lambda)$ is the average of n independent random variables with mean $\varphi(\lambda)$, so by the law of large numbers, $\varphi_n(\lambda) \rightarrow \varphi(\lambda)$ a.s. as $n \rightarrow \infty$. Note that φ is finite over $(0, 1]$, continuous over $[0, 1)$, and convex over $[0, 1]$.

Lemma 3: If F_0 is not identical to F_1 , exactly one of the following happens:

- 1) $\varphi(1-) < 1$ and φ is convex;
- 2) $\varphi(1-) = 1$ and φ is strictly convex.

Proof: Note that $\varphi(\lambda) \leq \sup_{r \in [0, \infty]} \frac{1}{\lambda + (1-\lambda)r} = \frac{1}{\lambda}$ for $\lambda \in (0, 1]$, so $\varphi(1-) \leq 1$. The function φ is convex because it is the expectation of a convex function. If $\varphi(1-) = 1$, then $\mathbb{P}\{R_i = \infty\} = 0$ and since it is also assumed that F_0 is not identical to F_1 , $\mathbb{P}\{R_i \notin \{1, \infty\}\} > 0$. Hence, the function in the expectation defining φ is strictly convex with positive probability, so φ is strictly convex. ■

Lemma 4: Suppose F_0 is not identical to F_1 and let λ_n be defined as in Corollary 1. Then $\lambda_n \rightarrow \alpha$ a.s. as $n \rightarrow \infty$.

Proof: Suppose $\alpha = 0$. Then

$$\varphi(0) = \mathbb{E}_1 \left[\frac{1}{R} \right] = \int_{0+}^{\infty} \frac{1}{r} dF_0(r) = 1 - F_0(0) \leq 1.$$

If $\varphi(0) < 1$, then, since $\varphi_n(0) \rightarrow \varphi(0)$ a.s. as $n \rightarrow \infty$, $\varphi_n(0) < 1$ for all sufficiently large n . So $\lambda_n = 0 = \alpha$ for all sufficiently large n , with probability one.

If $\varphi(0) = 1$, then by Lemma 3 it follows that $\varphi(\lambda) < 1$ for $\lambda \in (0, 1)$. So for any such λ fixed, $\varphi_n(\lambda) < 1$ for all sufficiently large n with probability one. Thus, for any fixed $\lambda \in (0, 1)$, $\lambda_n \leq \lambda$ for all large n with probability one, so $\lambda_n \rightarrow 0$ a.s. as $n \rightarrow \infty$. This implies the lemma for $\alpha = 0$.

Suppose $\alpha \in (0, 1)$. Note that

$$\varphi(\alpha) = \int_0^{\infty} \frac{1}{\alpha + (1-\alpha)r} (\alpha + (1-\alpha)r) dF_0(r) = 1.$$

Therefore, Lemma 3 implies that, for any $\epsilon > 0$ such that $\alpha + \epsilon < 1$ and $\alpha - \epsilon \geq 0$, it holds that $\varphi(\alpha + \epsilon) < 1$ and $\varphi(\alpha - \epsilon) > 0$. Therefore, with probability one, $\varphi_n(\alpha + \epsilon) < 1$ and $\varphi_n(\alpha - \epsilon) > 0$ for all sufficiently large n , and therefore $|\lambda_n - \alpha| < \epsilon$ for all sufficiently large n with probability one. This implies the lemma for $\alpha \in (0, 1)$.

Suppose $\alpha = 1$. Since $\mathbb{P}\{R_i < \infty\} = \mathbb{P}_0\{R_i < \infty\} = 1$ it holds that $\varphi(1-) = 1$, so by Lemma 3, φ is strictly convex. Furthermore, $\varphi'(1) = \mathbb{E}_0[R] - 1 \leq 0$. Therefore, $\varphi(\lambda) > 1$ for $\lambda \in [0, 1)$. Thus, for any fixed $\lambda \in [0, 1)$, $\varphi_n(\lambda) > 1$ for all sufficiently large n , with probability one. This implies the lemma for $\alpha = 1$, as needed. The proof of the lemma is complete. ■

Define cumulative distribution functions $\widehat{G}_0$ and $\widehat{G}_1$ by

$$\widehat{G}_0^c(\tau) = \min \left\{ \frac{1}{n} \sum_{i=1}^n I_{\{R_i > \tau\}} \frac{1}{\alpha + (1-\alpha)R_i}, 1 \right\}$$

$$\widehat{G}_1(\tau) = \min \left\{ \frac{1}{n} \sum_{i=1}^n I_{\{R_i \leq \tau\}} \frac{R_i}{\alpha + (1-\alpha)R_i}, 1 \right\}$$

for $\tau \in [0, \infty)$.

Lemma 5: As $n \rightarrow \infty$,

$$\sup_{\tau \in [0, \infty)} |\widehat{F}_k(\tau) - \widehat{G}_k(\tau)| \rightarrow 0 \quad \text{a.s. for } k \in \{0, 1\}. \quad (14)$$

Proof: The following conditions are equivalent: F_0 is identical to F_1 ; $F_0(\{1\}) = 1$; $F_1(\{1\}) = 1$; $\mathbb{P}\{R = 1\} = 1$. If any of these conditions hold then $R_i = 1$ for all i with probability one, so by Corollary 1, $\widehat{F}_0(\{1\}) = \widehat{F}_1(\{1\}) = 1$. Also, $\widehat{G}_0(\{1\}) = \widehat{G}_1(\{1\}) = 1$. So the lemma is true if F_0 is identical to F_1 . For the remainder of the proof suppose F_0 is not identical to F_1 , which by Lemma 4 implies that $\lambda_n \rightarrow \alpha$ a.s. as $n \rightarrow \infty$.

If $0 < \alpha < 1$, the convergence (14) follows immediately from the fact (based on $\lambda_n \rightarrow \alpha$) that, as $n \rightarrow \infty$, the function $r \mapsto \frac{1}{\lambda_n + (1-\lambda_n)r}$ converges uniformly over all $r \in [0, \infty]$ to $\frac{1}{\alpha + (1-\alpha)r}$, and the function $r \mapsto \frac{r}{\lambda_n + (1-\lambda_n)r}$ converges uniformly over all $r \in [0, \infty]$ to $\frac{r}{\alpha + (1-\alpha)r}$.

The proof of (14) in case $\alpha = 0$ or $\alpha = 1$ is more subtle. Here we give the proof for $\alpha = 0$ and $k = 0$. The other three possibilities for α and k follow in the same way. So consider the case $\alpha = 0$. The random variables $R_1, R_2, \dots$ are independent and all have CDF F_1 , and

$$\widehat{G}_0^c(\tau) = \min \left\{ \frac{1}{n} \sum_{i=1}^n I_{\{R_i > \tau\}} \frac{1}{R_i}, 1 \right\} \quad (\text{for } \alpha = 0).$$

Fix an arbitrary $\delta > 0$ and let $\epsilon > 0$ be so small that $\epsilon < 1$ and $2(F_0(\epsilon) - F_0(0)) < \delta$. For any CDF F and $\tau \in [0, \epsilon]$, $F^c(\tau) = (F^c(\tau) - F^c(\epsilon)) + F^c(\epsilon)$ and $|F^c(\tau) - \widehat{F}_0^c(\tau)| \leq F^c(0) - F^c(\epsilon)$. Also note that (since $\epsilon < 1$) $\widehat{F}_0^c(0) - \widehat{F}_0^c(\epsilon) \leq \widehat{G}_0^c(0) - \widehat{G}_0^c(\epsilon)$. Therefore, for $\tau \in [0, \epsilon]$,

$$|\widehat{F}_0^c(\tau) - \widehat{G}_0^c(\tau)| \leq |\widehat{F}_0^c(\epsilon) - \widehat{G}_0^c(\epsilon)| + 2|\widehat{G}_0^c(0) - \widehat{G}_0^c(\epsilon)|.$$

Thus,

$$\begin{aligned} & \sup_{\tau \in [0, \infty)} |\widehat{F}_0^c(\tau) - \widehat{G}_0^c(\tau)| \\ & \leq \sup_{\tau \in [\epsilon, \infty)} |\widehat{F}_0^c(\tau) - \widehat{G}_0^c(\tau)| + 2|\widehat{G}_0^c(0) - \widehat{G}_0^c(\epsilon)|. \end{aligned} \quad (15)$$

Since $\lambda_n \rightarrow 0$ with probability one, the function $r \mapsto \frac{1}{\lambda_n + (1-\lambda_n)r}$ converges uniformly over all $r \in [\epsilon, \infty]$ to $\frac{1}{r}$. It follows that the supremum term on the right side of (15) converges to zero a.s. as $n \rightarrow \infty$. Since

$$|\widehat{G}_0^c(0) - \widehat{G}_0^c(\epsilon)| \leq \frac{1}{n} \sum_{i=1}^n I_{\{0 < R_i \leq \epsilon\}} \frac{1}{R_i}$$

and

$$\begin{aligned}\mathbb{E} \left[I_{\{0 < R_i \leq \epsilon\}} \frac{1}{R_i} \right] &= \int_{0+}^{\epsilon} \frac{1}{r} dF_1(r) \\ &= \int_{0+}^{\epsilon} dF_0(r) = F_0(\epsilon) - F_0(0),\end{aligned}$$

the law of large numbers implies

$$\limsup_{n \rightarrow \infty} 2|\widehat{G}_0^c(0) - \widehat{G}_0^c(\epsilon)| \leq 2(F_0(\epsilon) - F_0(0)) < \delta$$

with probability one. So $\sup_{\tau \in [0, \infty)} |\widehat{F}_0^c(\tau) - \widehat{G}_0^c(\tau)| \leq \delta$ for all sufficiently large n , with probability one. Since $\delta > 0$ was selected arbitrarily, this completes the proof of (14) for $k = 0$ in case $\alpha = 0$, and hence the proof of Lemma 5 overall. ■

Lemma 6: As $n \rightarrow \infty$,

$$\sup_{\tau \in [0, \infty)} |\widehat{G}_k(\tau) - F_k(\tau)| \rightarrow 0 \quad \text{a.s. for } k \in \{0, 1\}. \quad (16)$$

Proof: Note that

$$\begin{aligned}&\mathbb{E} \left[I_{\{R_i > \tau\}} \frac{1}{\alpha + (1 - \alpha)R_i} \right] \\ &= \int_{\tau+}^{\infty} \frac{1}{\alpha + (1 - \alpha)r} (\alpha + (1 - \alpha)r) dF_0(r) \\ &= F_0^c(\tau), \\ &\mathbb{E} \left[I_{\{R_i \leq \tau\}} \frac{R_i}{\alpha + (1 - \alpha)R_i} \right] \\ &= \int_0^{\tau} \frac{r}{\alpha + (1 - \alpha)r} (\alpha/r + (1 - \alpha)) dF_1(r) \\ &= F_1(\tau).\end{aligned}$$

Hence, by the law of large numbers, for any fixed $\tau \in [0, \infty)$, $\widehat{G}_k(\tau) \rightarrow F_k(\tau)$ with probability one as $n \rightarrow \infty$, for $k \in \{0, 1\}$. It can similarly be shown that $\widehat{G}_k(\tau-) \rightarrow F_k(\tau-)$ with probability one as $n \rightarrow \infty$, for $k \in \{0, 1\}$ for each τ fixed. Pointwise convergence of CDFs and their corresponding left limits implies uniform convergence (see Appendix E), implying (16). ■

Proof of Proposition 4: Lemmas 5 and 6 and the triangle inequality:

$$|\widehat{F}_k(\tau) - F_k(\tau)| \leq |\widehat{F}_k(\tau) - \widehat{G}_k(\tau)| + |\widehat{G}_k(\tau) - F_k(\tau)|,$$

imply that as $n \rightarrow \infty$,

$$\sup_{\tau \in [0, \infty)} |\widehat{F}_k(\tau) - F_k(\tau)| \rightarrow 0 \quad \text{a.s. for } k \in \{0, 1\}.$$

Application of Lemma 1 completes the proof. ■

APPENDIX G

DERIVATION OF EXPRESSIONS FOR AUC AND $\widehat{\text{AUC}}_{\text{ML}}$

Proof of Proposition 5: (Proof of 1) Let $R_{[1]} \leq R_{[2]} \leq \dots \leq R_{[n]}$ denote a reordering of the samples $R_1, \dots, R_n$. Then the region under $\widehat{\text{ROC}}_{\text{ML}}$ can be partitioned into a union of trapezoidal regions, such that there is one trapezoid for each $R_{[i]}$ such that $R_{[i]} < \infty$. The trapezoids are numbered from right to left. If a value $v_j \in (0, \infty)$ is taken on by

c_j of the samples, then the union of the trapezoidal regions corresponding to those samples is also a trapezoidal region.

The area of the i th trapezoidal region is the width of the base times the average of the lengths of the two sides. The width of the base is $\frac{1}{n} \cdot \frac{1}{\lambda_n + (1 - \lambda_n)R_{[i]}}$, corresponding to a term in $\widehat{F}_0$. The length of the left side is $\frac{1}{n} \cdot \sum_{i': i' > i} \frac{1}{\lambda_n + (1 - \lambda_n)R_{[i']}}$, and the length of the right side is greater than the length of the left side by $\frac{1}{n} \cdot \frac{1}{\lambda_n + (1 - \lambda_n)R_{[i]}}$. Summing the areas of the trapezoids yields:

$$\begin{aligned}\widehat{\text{AUC}}_{\text{ML}} &= \frac{1}{n^2} \sum_{i=1}^n \left\{ \frac{1}{(\lambda_n + (1 - \lambda_n)R_{[i]})} \right. \\ &\quad \cdot \left(\left(\sum_{i'=i+1}^n \frac{R_{[i']}}{(\lambda_n + (1 - \lambda_n)R_{[i']})} \right) + \frac{1}{2} \frac{R_{[i]}}{(\lambda_n + (1 - \lambda_n)R_{[i]})} \right) \Big\},\end{aligned}$$

which is equivalent to the expression given 1) of the proposition.

(Proof of 2) The consistency of $\widehat{\text{AUC}}_{\text{ML}}$ follows from Proposition 4, the consistency of $\widehat{\text{ROC}}_{\text{ML}}$.

(Proof of 3) Let $\tau(p)$ and $\eta(p)$ denote values $\tau(p) \in [0, \infty)$ and $\eta(p) \in [0, 1]$ such that $F_0^c(\tau(p), \eta(p)) = p$. Then

$$\begin{aligned}\text{AUC} &= \int_0^1 \text{ROC}(p) dp = \int_0^1 F_1^c(\tau(p), \eta(p)) dp \\ &= \int_0^1 (\eta(p)F_1^c(\tau(p)) + (1 - \eta(p))F_1^c(\tau(p)-)) dp \\ &\stackrel{(a)}{=} \int_0^1 \frac{F_1^c(\tau(p)) + F_1^c(\tau(p)-)}{2} dp \\ &\stackrel{(b)}{=} \mathbb{E}_0 \left[\frac{F_1^c(R) + F_1^c(R-)}{2} \right] \\ &= \mathbb{E}_0 \left\{ \frac{\int_{R+}^{\infty} r' dF_0(r') + \int_R^{\infty} r' dF_0(r')}{2} + F_1(\{\infty\}) \right\} \\ &= \mathbb{E}_0 \left[R' \left(I_{\{R' > R\}} + \frac{1}{2} I_{\{R' = R\}} \right) \right] + F_1(\{\infty\}) \\ &= \frac{1}{2} \mathbb{E}_0[\max\{R, R'\}] + F_1(\{\infty\}) \\ &= \frac{1}{2} \mathbb{E}_0[\max\{R, R'\}] + 1 - \mathbb{E}_0[R] \\ &= 1 - \frac{1}{2} \mathbb{E}_0[R + R' - \max\{R, R'\}] \\ &= 1 - \frac{1}{2} \mathbb{E}_0[\min\{R, R'\}],\end{aligned}$$

where (a) follows from the fact that $\text{ROC}(p)$ is affine over the maximal intervals of p such that $\tau(p)$ is constant, so the integral is the same if $\text{ROC}(p)$ is replaced over each such interval by its average over the interval, and (b) follows from the fact that if U is a random variable uniformly distributed on the interval $(0, 1)$, then the CDF of $\tau(U)$ is F_0 because for any $c \geq 0$, $\mathbb{P}\{\tau(U) > c\} = \mathbb{P}\{U \leq F_0^c(c)\} = F_0^c(c)$. This establishes (5) and (6).

(Proof of 4) This follows from (5) and the fact the CDF of R and R' satisfies $dF(r) = (\alpha + (1 - \alpha)r) dF_0(r)$ over $[0, \infty)$ and $F(\{\infty\}) = (1 - \alpha)F_1(\{\infty\})$. ■