

## Energy-Efficient Packet Scheduling under Two-Sided Delay Constraints

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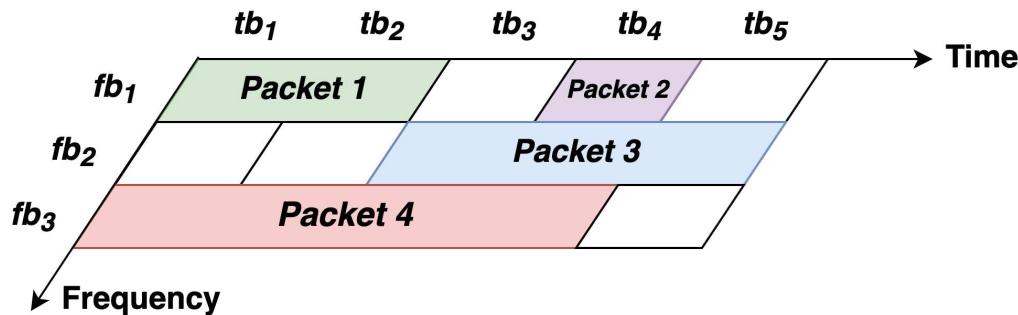
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# Introduction

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\*Cisco Annual Internet Report: 2018-2023 White Paper

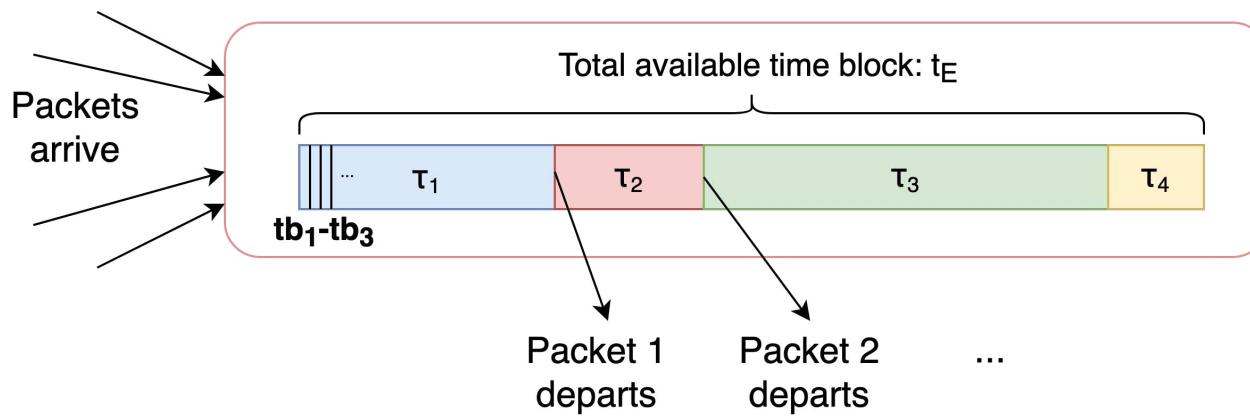
- Ubiquity of networks
  - Estimated to have ~29 billion IP-connected devices by 2023 – 3.6 x World population!\*
  - Ever-growing number of connected devices
- Finite and limited resources (blocks of time, bands of frequency, *etc.*)
  - Need to effectively allocate
- Packet scheduling: A classical problem in wireless communications
  - Allocating finite resources...
  - ... to optimize an objective (energy consumption, delay minimization, quality-of-service requirements, *etc.*)



# Introduction

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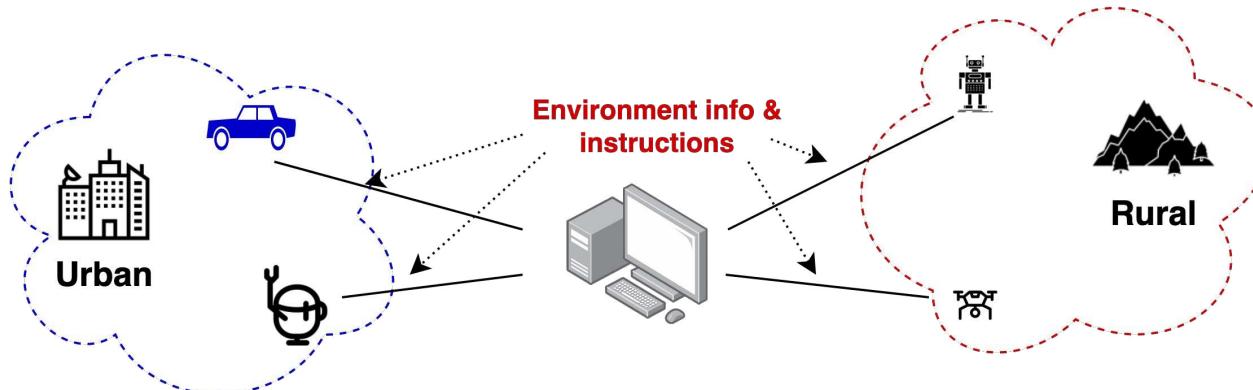
- Our focus: Scheduling **time** to minimize **energy consumption**
  - **Goal:** Serve all packets within a total time block
- Original version [Uysal-Biyikoglu, Prabhakar, El Gamal, ToN '02]



$$\sum_{i=1}^4 \tau_i = t_E$$

- Each packet has individual deadlines = “Delay constraint”
  - Late transmission is bad, avoid it! [Chen, Neely, Mitra, T-IT '08], [Zafer, Modiano, ToN '09], [Shan, Luo, Shen, ComNet '14], etc.

# A Motivating Example



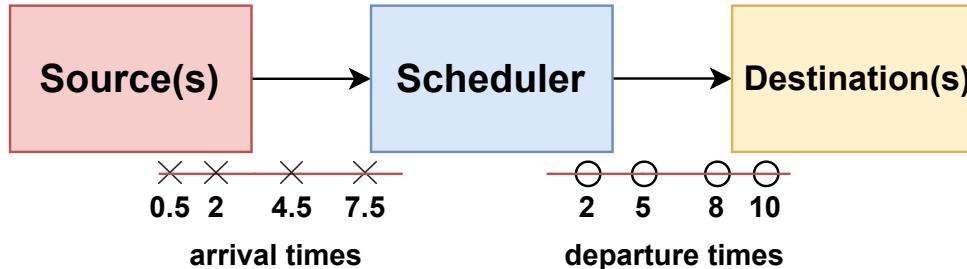
- Want to achieve coordinated action @  $t_R$ 
  - Central unit sends each agent a packet
    - Instructions & environmental information
- Need to send packets in advance (enough time to prepare)
  - Earlier the better! (conventional)
- Environmental information needs to be up-to-date at @  $t_R$ 
  - Later the better! (new)

# Contributions

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- Other applications
  - Secure relaying → packet expiration
  - Molecular communication → molecule degradation
  - Delay requirements & freshness
  - *etc.*
- Need to expand!
- Our work:
  - “Not too late transmission (conventional), but also not too early (new)”
  - Generalizes one-sided formulation to two-sided delay constrained scheduling
  - Provides energy-optimal offline scheduling under two-sided delay deadlines (provable)

# Problem Formulation



- Application-agnostic
- Packets arrive at the scheduler as a time sequence
  - Arrival time of  $i^{th}$  packet:  $t_i$
  - $M$ : Total number of packets
  - Inter-arrival times:  $d_i = t_{i+1} - t_i$
- $\tau$ : The vector that holds each transmission's duration
  - Packet cannot be processed before arrival (causality)
  - The scheduler transmits each packet on the order of reception → first-in first-out (FIFO)

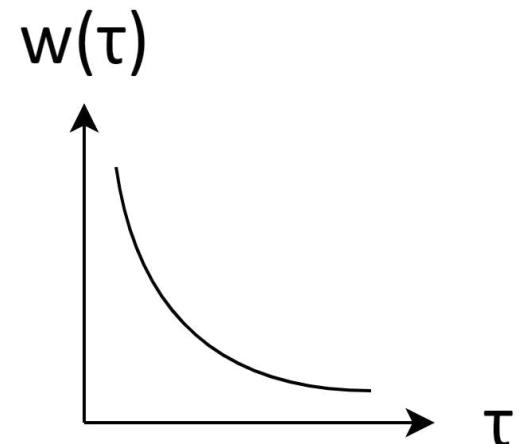
# System Setup: The Objective Function

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- **Goal:** Transmitting all arriving packets within  $[0, t_E]$ , while minimizing an energy cost  $w(\tau)$

- Assumptions on the cost:

- $w(\tau) = \sum_{i=1}^M w(\tau_i)$
- $w(\tau) > 0$
- $w(\tau)$  decreasing in argument  $\tau$
- $w(\tau)$  strictly convex in  $\tau$



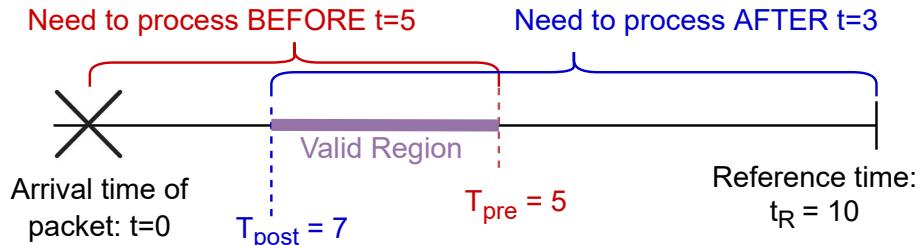
- Processing faster requires increasingly large energy

# System Setup: Constraints

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- **Successful Communication:** All  $M$  packets are available at the destination(s) at a reference time  $t_R$
- Two main requirements:
  1. All packets successfully transmitted towards its destination by the reference time  $t_R$
  2. All packets are active/not expired at time  $t_R$
- 1: cannot be too late (conventional)
  - Upper bounds departure time: “*Pre*”-delay constraint  $\longrightarrow T_{pre}$
- 2: cannot be too early (new)
  - Lower bounds departure time: “*Post*”-delay constraint  $\longrightarrow T_{post}$

# The Optimization Problem



- We consider two-sided delay constraints!

$$\min_{\tau} w(\tau) = \sum_{i=1}^M w(\tau_i)$$

$$\text{s.t. } \sum_{i=1}^k \tau_i \geq \sum_{i=1}^k d_i, \quad k \in \{1, \dots, M-1\},$$

$$\sum_{i=1}^M \tau_i = t_E = \sum_{i=1}^M d_i,$$

$$\sum_{i=1}^k \tau_i \geq t_R - T_{\text{post},k}, \quad k \in \{1, \dots, M\},$$

$$\sum_{i=1}^k \tau_i - \sum_{i=1}^{k-1} d_i \leq T_{\text{pre},k}, \quad k \in \{1, \dots, M\}.$$

} Non-idling constraints (no unused interval)

→ Post-delay constraints

→ Pre-delay constraints

# The Optimization Problem

$$\min_{\tau} \quad w(\tau) = \sum_{i=1}^M w(\tau_i)$$

$$\text{s.t.} \quad \sum_{i=1}^k \tau_i \geq \sum_{i=1}^k d_i, \quad k \in \{1, \dots, M-1\},$$

$$\sum_{i=1}^M \tau_i = t_E = \sum_{i=1}^M d_i,$$

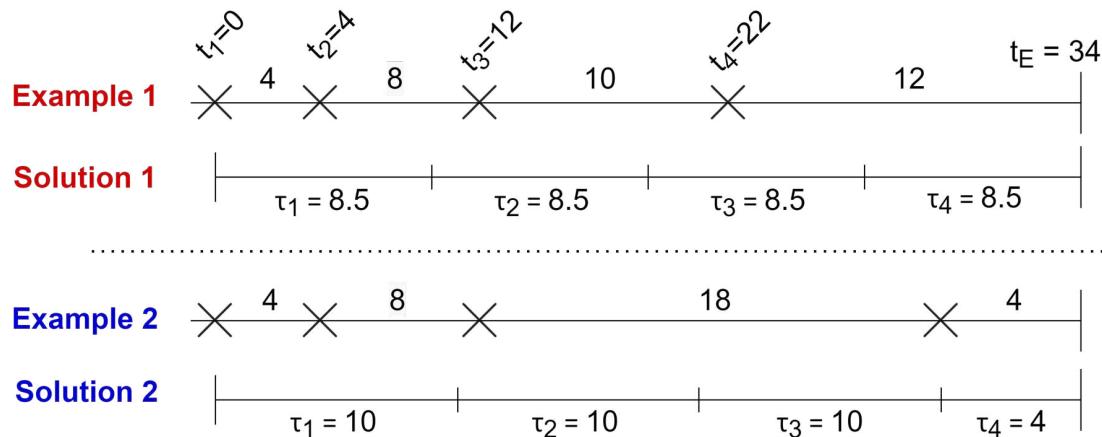
$$\sum_{i=1}^k \tau_i \geq t_R - T_{\text{post},k}, \quad k \in \{1, \dots, M\},$$

$$\sum_{i=1}^k \tau_i - \sum_{i=1}^{k-1} d_i \leq T_{\text{pre},k}, \quad k \in \{1, \dots, M\}.$$

- Address ***offline*** scheduling:
  - Idealized scheduler
  - Knows all arrival times non-causally
  - Knows all  $T_{\text{pre},i}$  and  $T_{\text{post},i}$  beforehand
  
- Solution provides a lower bound on the cost
  - Future Work: Algorithms that rely on statistical information & online algorithms

# Demonstrative Example: The Unconstrained Case

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No restricting pre- and post-delays

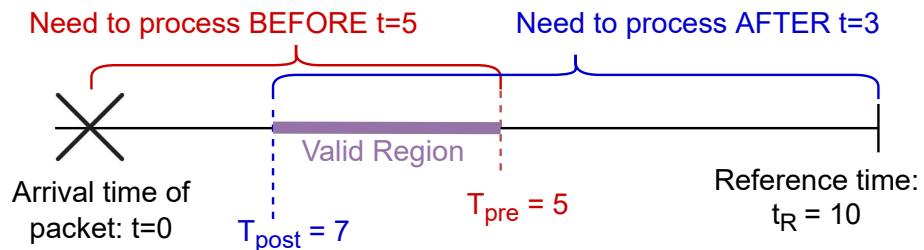
Corresponds to [Uysal-Biyikoglu, Prabhakar, El Gamal, IEEE T-oN '02]

- **Example 1:** Fully balancing feasible. Lowest cost incurred due to convexity
- **Example 2:** Fully balancing not feasible (fourth molecule arrives late)
  - Next best (balancing  $[\tau_1, \tau_2, \tau_3]$ ) feasible
  - $\tau_4 = 4$  trivial
- **Key idea:** *Balance durations as much as possible + Maximally exploit future arrival times*

# The Two-Sided Case: Feasibility

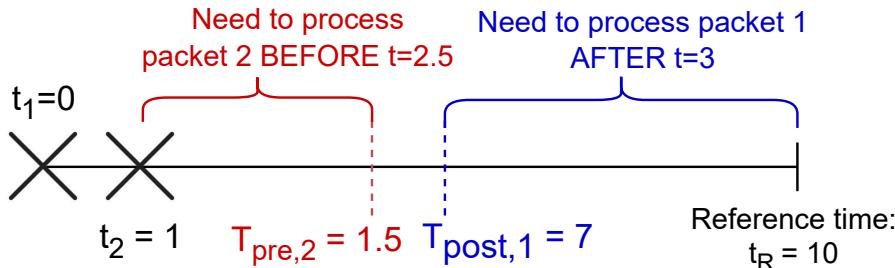
- For the two-sided case, a feasible solution is not guaranteed
  - Under one-sided pre-delay constraints, it is [Chen, Neely, Mitra, IEEE T-IT '08]
- For feasibility:

1) Everyone has a valid region



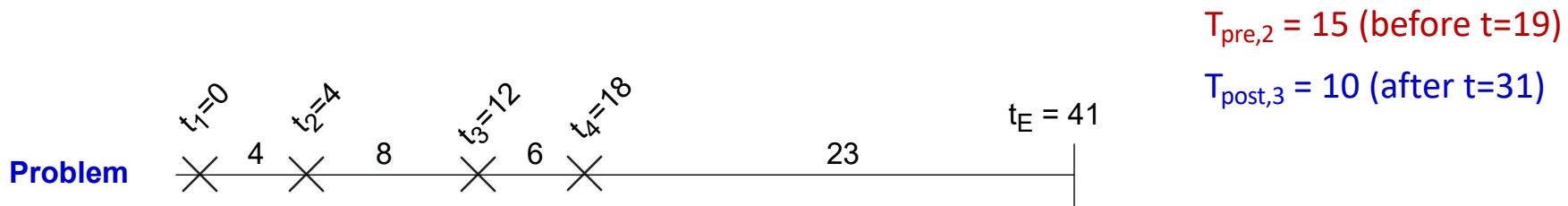
2) No post-delay cross-overs (FIFO)

$$t_i + T_{pre,i} > t_R - T_{post,j}, \forall j = 1, \dots, i-1$$



**INFEASIBLE!** Packet 1 has to wait until  $t=3$   
Guaranteed loss of packet 2

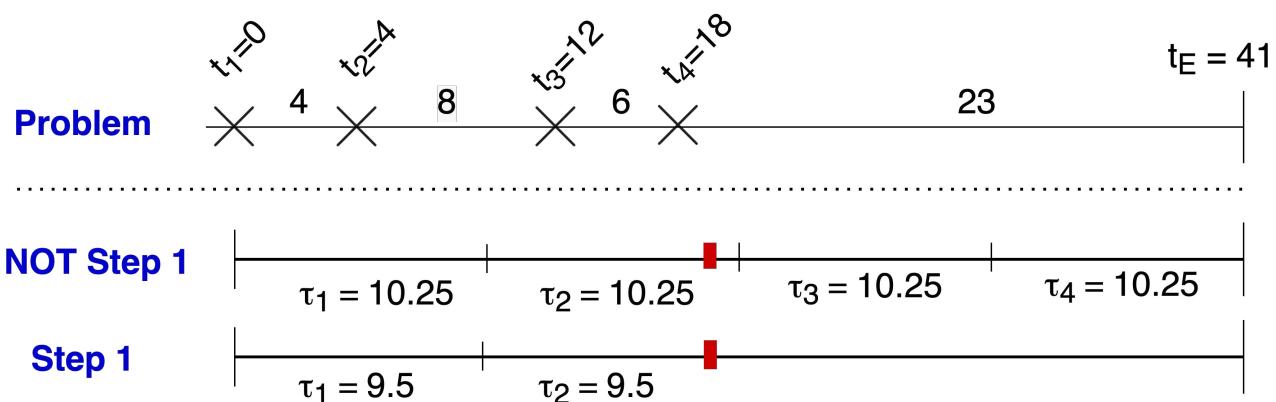
# The Two-Sided Case



- Key idea: Balance as much as possible

# The Two-Sided Case

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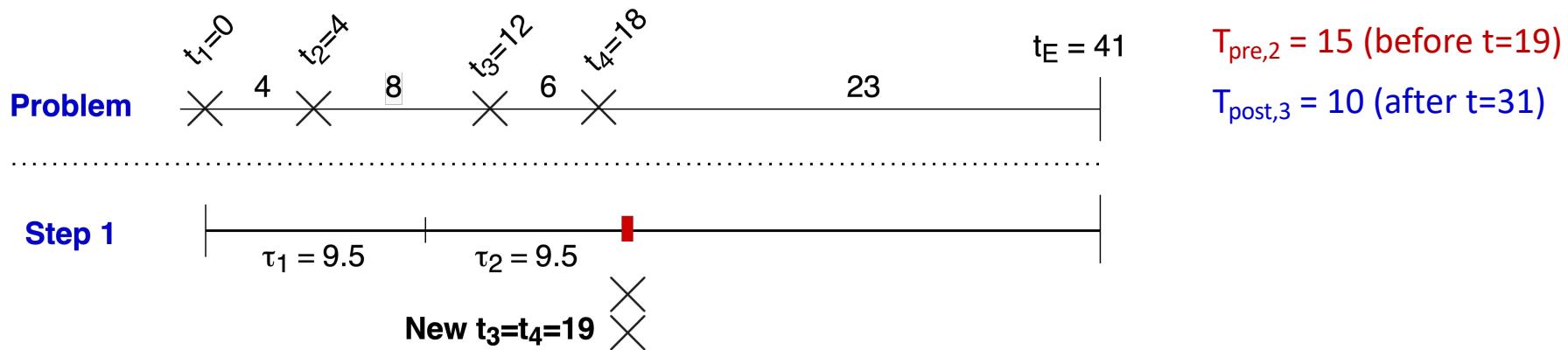


$$T_{\text{pre},2} = 15 \text{ (before } t=19)$$
$$T_{\text{post},3} = 10 \text{ (after } t=31)$$

- Key idea: Balance as much as possible
- For pre-delays: If need be, satisfy critically!  $\rightarrow \tau_1 + \tau_2 = t_2 + T_{\text{pre},2}$

# The Two-Sided Case

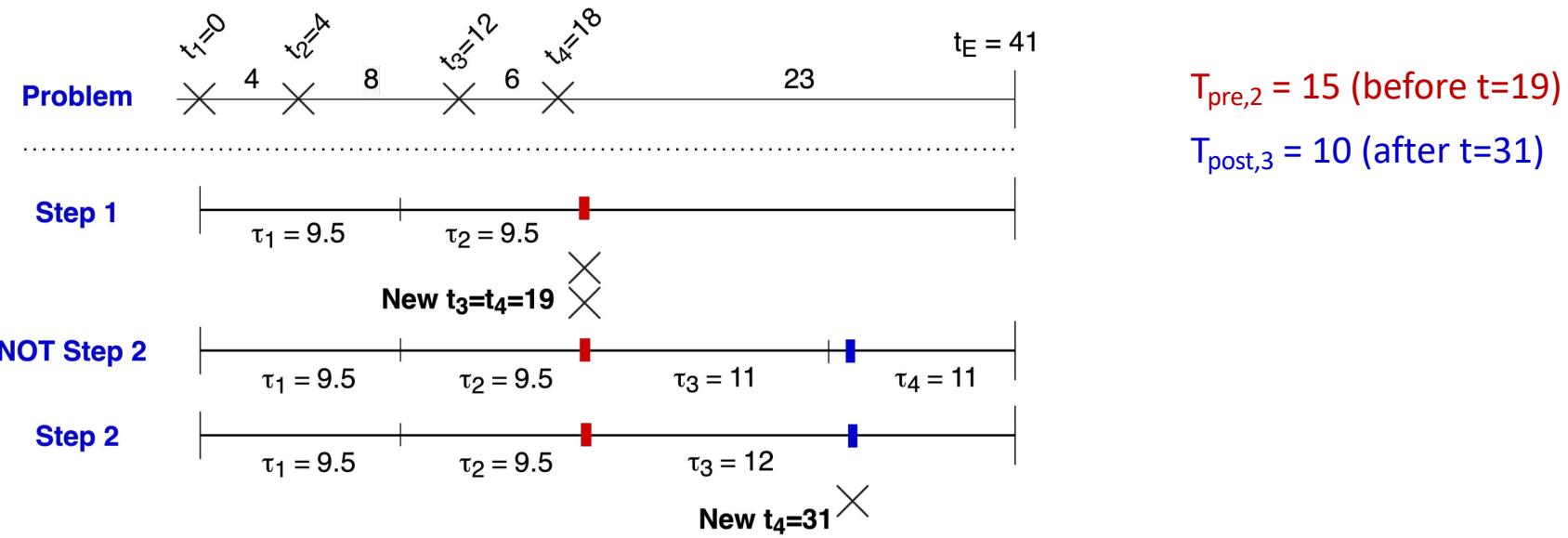
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- Key idea: Balance as much as possible
- **For pre-delays: If need be, satisfy critically!**
- “Shift” arrivals to the critical point

# The Two-Sided Case

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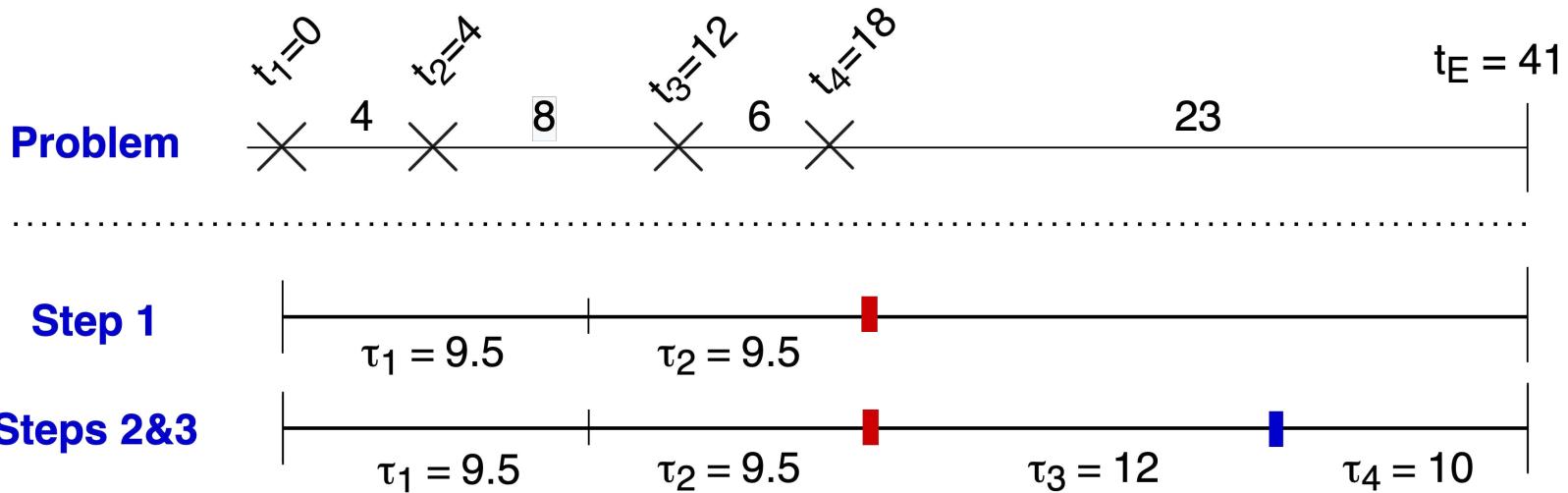


- Key idea: Balance as much as possible
- For both pre- and post-delays: If need be, satisfy critically!
- “Shift” arrivals to the critical point

$$\tau_1 + \tau_2 + \tau_3 = t_R - T_{\text{post},3}$$

# The Two-Sided Case

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- **Provably Optimal!**
- **Proof strategy:**
  - 1)  $w(\tau)$  Schur-convex
  - 2) Showed our algorithm's  $\tau$  gets majorized by any other valid  $\tau'$
  - 3) Combine 1 & 2

# Conclusions

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- Expanded packet scheduling to two-sided delay constraints
  - Covers many new applications
  - Feasible solution may not exist! → provided conditions
  - Devised a **provably optimal** scheduling algorithm
    - Minimizes a convex energy cost
- Solution can also extend to solve the “dual problem”: energy constrained total delay minimization
  - Solved under two-sided delay constrained framework!
    - [**MCG**, UM, 2<sup>nd</sup> round of review @ IEEE T-WC], available on arXiv
- Idealized assumptions on non-causal arrival time information, and pre-/post-delays
  - Future work: Algorithm that rely on only statistical/no information