

Sparsifying Sums of Norms

Arun Jambulapati

Computer Science & Engineering
University of Washington
Seattle, USA

jmbapati@alumni.stanford.edu

James R. Lee

Computer Science & Engineering
University of Washington
Seattle, USA

jrl@cs.washington.edu

Yang P. Liu

Mathematics
Stanford University
Palo Alto, USA

yangpliu@stanford.edu

Aaron Sidford

MS&E
Stanford University
Palo Alto, USA

sidford@stanford.edu

Abstract—For any norms $N_1, \dots, N_m$ on $\mathbb{R}^n$ and $N(x) := N_1(x) + \dots + N_m(x)$, we show there is a sparsified norm $\tilde{N}(x) = w_1 N_1(x) + \dots + w_m N_m(x)$ such that $|N(x) - \tilde{N}(x)| \leq \varepsilon N(x)$ for all $x \in \mathbb{R}^n$, where $w_1, \dots, w_m$ are non-negative weights, of which only $O(\varepsilon^{-2} n \log(n/\varepsilon)(\log n)^{2.5})$ are non-zero. Additionally, we show that such weights can be found with high probability in time $O(m(\log n)^{O(1)} + \text{poly}(n))T$, where T is the time required to evaluate a norm $N_i(x)$, assuming that $N(x)$ is $\text{poly}(n)$ -equivalent to the Euclidean norm. This immediately yields analogous statements for sparsifying sums of symmetric submodular functions. More generally, we show how to sparsify sums of p th powers of norms when the sum is p -uniformly smooth.¹

Index Terms—Randomness in Computing

I. INTRODUCTION

Consider a collection $N_1, \dots, N_m : \mathbb{R}^n \rightarrow \mathbb{R}_+$ of semi-norms² on $\mathbb{R}^n$ and the semi-norm defined by

$$N(x) := N_1(x) + \dots + N_m(x).$$

It is natural to ask whether N can be *sparsified* in the following sense. Given nonnegative weights $w_1, \dots, w_m$, define the approximator $\tilde{N}(x) := w_1 N_1(x) + \dots + w_m N_m(x)$. We say that $\tilde{N}$ is s -sparse if at most s of the weights $\{w_i\}$ are non-zero, and that $\tilde{N}$ is an ε -approximation of N if it holds that

$$|N(x) - \tilde{N}(x)| \leq \varepsilon N(x), \quad \forall x \in \mathbb{R}^n. \quad (\text{I.1})$$

A prototypical example occurs for cut sparsifiers of weighted graphs. In this case, one has an undirected graph $G = (V, E, c)$ with nonnegative weights $\{c_e : e \in E\}$, with $n = |V|$ and $N(x) := \sum_{u,v \in E} c_{uv} |x_u - x_v|$. A *weighted cut sparsifier* is given by nonnegative edge weights $\{w_e :$

$e \in E\}$. Defining $\tilde{N}(x) := \sum_{u,v \in E} w_{uv} c_{uv} |x_u - x_v|$, the typical approximation criterion is that

$$|N(x) - \tilde{N}(x)| \leq \varepsilon N(x), \quad \forall x \in \{0, 1\}^V, \quad (\text{I.2})$$

where $x \in \{0, 1\}^V$ naturally indexes cuts in G . A straightforward ℓ_1 variant of the discrete Cheeger inequality shows that (I.2) is equivalent to (I.1) in the setting of weighted graphs.

Benczúr and Karger [BK96] showed that for every graph G and every $\varepsilon > 0$, one can construct an s -sparse ε -approximate cut sparsifier with $s \leq O(\varepsilon^{-2} n \log n)$. Their result addresses the case when each N_i is a 1-dimensional semi-norm of the form $N_i(x) = c_{uv} |x_u - x_v|$. We show that one can obtain similar sparsifiers in substantial generality.

Further, we show how to compute such sparsifiers efficiently when the semi-norm N is appropriately well-conditioned. Say that N is (r, R) -rounded if it holds that $r\|x\|_2 \leq N(x) \leq R\|x\|_2$ for all $x \in \ker(N)^\perp$, where $\ker(N) := \{x \in \mathbb{R}^n : N(x) = 0\}$.

Theorem I.1. *Consider a collection $N_1, \dots, N_m$ of semi-norms on $\mathbb{R}^n$ and $N(x) := N_1(x) + \dots + N_m(x)$. For every $\varepsilon > 0$, there is an $O(\varepsilon^{-2} n \log(n/\varepsilon)(\log n)^{2.5})$ -sparse ε -approximation of N . Further, if the semi-norm N is (r, R) -rounded, then weights realizing the approximation can be found in time $O(m(\log n)^{O(1)} + n^{O(1)})(\log(mR/r))^{O(1)}\mathcal{T}_{\text{eval}}$ with high probability if each N_i can be evaluated in time $\mathcal{T}_{\text{eval}}$.*

Application to symmetric submodular functions. A function $f : 2^V \rightarrow \mathbb{R}_+$ is *submodular* if

$$f(S \cup \{v\}) - f(S) \geq f(T \cup \{v\}) - f(T), \quad \forall S \subseteq T \subseteq V, v \in V \setminus T.$$

A submodular function is *symmetric* if $f(S) = f(V \setminus S)$ for all $S \subseteq V$.

Consider submodular functions $f_1, \dots, f_m : \{0, 1\}^V \rightarrow \mathbb{R}_+$ and denote $F(S) := f_1(S) + \dots + f_m(S)$. Given nonnegative weights $w_1, \dots, w_m$, define $\tilde{F}(S) := w_1 f_1(S) + \dots + w_m f_m(S)$. We say that $\tilde{F}$ is an s -sparse ε -approximation for F if it holds that at most s of the weights $\{w_i\}$ are non-zero and

$$|F(S) - \tilde{F}(S)| \leq \varepsilon F(S), \quad \forall S \subseteq V.$$

We thank anonymous reviewers for several helpful comments. James R. Lee is supported in part by NSF CCF-2007079 and a Simons Investigator Award. Yang P. Liu is supported by a Google Research Ph.D. Fellowship. Aaron Sidford is supported in part by a Microsoft Research Faculty Fellowship, NSF CCF-1844855, NSF CCF-1955039, a PayPal research award, and a Sloan Research Fellowship.

¹This paper is an extended abstract. The full paper can be accessed at <https://arxiv.org/abs/2305.09049>.

²A semi-norm N is nonnegative and satisfies $N(\lambda x) = |\lambda|N(x)$ and $N(x + y) \leq N(x) + N(y)$ for all $\lambda \in \mathbb{R}$, $x, y \in \mathbb{R}^n$, though possibly $N(x) = 0$ for $x \neq 0$.

Motivated by the ubiquity of submodular functions in machine learning and data mining, Rafiey and Yoshida [RY22] established in this setting that, even if the f_i are asymmetric, for every $\varepsilon > 0$, there is an $O(Bn^2/\varepsilon^2)$ -sparse ε -approximation for F , where $n := |V|$ and B is the maximum number of vertices in the base polytope of any f_i . In the case $B \leq O(1)$, their result is tight for (directed) cuts in directed graphs [CKP⁺17].

However, for *symmetric* submodular functions, the situation is better. For such functions $f : 2^V \rightarrow \mathbb{R}_+$ with $f(\emptyset) = 0$, the Lovász extension [Lov83] of f is a semi-norm on $\mathbb{R}^V$ (see Section III-B1). Therefore, Theorem I.1 immediately yields an analogous sparsification result in this setting. In comparison to [RY22], in this symmetric setting, we have no dependence on B , and the quadratic dependence on n improves to nearly linear.

Corollary I.2 (Symmetric submodular functions). *If $f_1, \dots, f_m : 2^V \rightarrow \mathbb{R}_+$ are symmetric submodular functions with $f_1(\emptyset) = \dots = f_m(\emptyset) = 0$, and $F(S) := f_1(S) + \dots + f_m(S)$, then for every $\varepsilon > 0$, there is an $O(\varepsilon^{-2}n \log(n/\varepsilon)(\log n)^{2.5})$ -sparse ε -approximation of F where $n = |V|$.*

Additionally, if the functions f_i are integer-valued with $\max_{i \in [m], S \subseteq V} f_i(S) \leq R$, then the weights realizing the approximation can be found in time $O(mn(\log n)^{O(1)} + \text{poly}(n))\mathcal{T}_{\text{eval}} \log^{O(1)}(mR)$, with high probability, assuming each f_i can be evaluated in time $\mathcal{T}_{\text{eval}}$.

The deduction of Corollary I.2 from Theorem I.1 appears in Section III-B1.

Sums of higher powers. In the setting of graphs, *spectral sparsification* [ST11], a notion stronger than (I.2), has been extensively studied. Given semi-norms $N_1, \dots, N_m$ on $\mathbb{R}^n$, define a semi-norm via their ℓ_2 -sum as

$$N(x)^2 := N_1(x)^2 + \dots + N_m(x)^2.$$

If $w_1, \dots, w_m$ are nonnegative weights and $\tilde{N}(x)^2 := w_1 N_1(x)^2 + \dots + w_m N_m(x)^2$, we say that $\tilde{N}^2$ is an s -sparse ε -approximation for N^2 if it holds that at most s of the weights $\{w_i\}$ are non-zero and

$$|N(x)^2 - \tilde{N}(x)^2| \leq \varepsilon N(x)^2, \quad \forall x \in \mathbb{R}^n. \quad (\text{I.3})$$

When $G = (V, E, c)$ is a weighted graph and each $N_i(x)$ is of the form $\sqrt{c_{uv}}|x_u - x_v|$ for some $uv \in E$, (I.3) is called an ε -spectral sparsifier of G . In this setting, a sequence of works [ST11], [SS11], [BSS12] culminates in the existence of $O(n/\varepsilon^2)$ -sparse ε -approximations for every $\varepsilon > 0$. These results generalize [Rud99], [BSS14] to the setting of arbitrary 1-dimensional semi-norms, where

$$N_1(x) = |\langle a_1, x \rangle|, \dots, N_m(x) = |\langle a_m, x \rangle|, \quad a_1, \dots, a_m \in \mathbb{R}^n \quad (\text{I.4})$$

We establish the existence of near-linear-size sparsifiers for sums of powers of a substantially more general class

of higher-dimensional norms. Recall that a semi-norm N on $\mathbb{R}^n$ is said to be p -uniformly smooth with constant S if it holds that

$$\frac{N(x+y)^p + N(x-y)^p}{2} \leq N(x)^p + N(Sy)^p, \quad x, y \in \mathbb{R}^n. \quad (\text{I.5})$$

Note that when $N_i(x) = |\langle a_i, x \rangle|$, then N is 2-uniformly smooth with constant 1. We say that two semi-norms N_X and N_Y are K -equivalent if there is a number $\lambda > 0$ such that $N_Y(z) \leq \lambda N_X(z) \leq K N_Y(z)$ for all $z \in \mathbb{R}^n$. Every norm is 1-uniformly smooth with constant 1 by the triangle inequality, so the next theorem generalizes Theorem I.1.

Theorem I.3 (Sums of p th powers of uniformly smooth norms). *Consider $p \geq 1$ and semi-norms $N_1, \dots, N_m$ on $\mathbb{R}^n$. Denote $N(x)^p := N_1(x)^p + \dots + N_m(x)^p$, and suppose that for some numbers $K, S > 1$ the semi-norm N is K -equivalent to a semi-norm which is $\min(p, 2)$ -uniformly smooth with constant S . Then for every $\varepsilon \in (0, 1)$, there is an $O(s)$ -sparse ε -approximation to N^p such that*

$$s \leq \begin{cases} \frac{K^{2p}}{\varepsilon^2} n (S \psi_n \log(n/\varepsilon))^p (\log n)^2 & 1 \leq p \leq 2 \\ \frac{K^{2p} S^p p^2}{\varepsilon^2} \left(\frac{n+p}{2}\right)^{p/2} (\psi_n \log(n/\varepsilon))^2 (\log n)^2 & p \geq 2. \end{cases}$$

Above, we use $\psi_n \leq O(\sqrt{\log n})$ [Kla23] to denote the KLS constant on $\mathbb{R}^n$ (see Theorem II.3 below).

Note that for $N(x)$ to be $\min(p, 2)$ -uniformly smooth with constant $O(S)$, it suffices that each N_i is $\min(p, 2)$ -uniformly smooth with constant S [Fig76]. To see the relevance of this theorem in the case $p = 2$, note that by John's theorem, every d -dimensional semi-norm is $\sqrt{d}$ -equivalent to a Euclidean norm (which is 2-uniformly smooth with constant 1). So if $A_1, \dots, A_m \in \mathbb{R}^{d \times n}$ and $\hat{N}_1, \dots, \hat{N}_m$ are arbitrary norms on $\mathbb{R}^d$, then taking $N_i(x) := \hat{N}_i(A_i x)$, we obtain an $O(d\varepsilon^{-2}n(\log(n/\varepsilon))^2(\log n)^3)$ -sparse ε -approximation to N^2 , substantially generalizing the setting of (I.4) (albeit with an extra $d(\log(n/\varepsilon))^{O(1)}$ factor in the sparsity).

Unlike in the setting of graph sparsifiers where spectral sparsification is a strictly stronger notion (due to the equivalence of (I.2) and (I.1)), the notions of approximation guaranteed by Theorem I.1 and Theorem I.3 for $p > 1$ are, in general, incomparable. For example, even if $\|\tilde{A}x\|_2 \approx \|Ax\|_2$ for all $x \in \mathbb{R}^n$, it is not necessarily true that $\|\tilde{A}x\|_1 \approx \|Ax\|_1$ for all $x \in \mathbb{R}^n$.

Let us now discuss some consequences of Theorem I.3.

Dimension reduction for ℓ_p sums. Fix $1 \leq p \leq 2$ and a subspace $X \subseteq \ell_p^m$ with $\dim(X) = n$. It is known that for any $\varepsilon > 0$, there is a subspace $\tilde{X} \subseteq \ell_p^d$ with $d \leq O(\varepsilon^{-2}n \log(n)(\log \log n)^2)$ such that the ℓ_p norms on X

and $\tilde{X}$ are $(1 + \varepsilon)$ -equivalent [Tal95]. For $p = 1$, this can be improved to $d \leq O(\varepsilon^{-2} n \log n)$ [Tal90].

Consider the following more general setting. Suppose $Z_1, \dots, Z_m$ are each p -uniformly smooth Banach spaces with their smoothness constants bounded by S . Let us write $(Z_1 \oplus \dots \oplus Z_m)_p$ for the Banach space $Z = Z_1 \oplus \dots \oplus Z_m$ equipped with the norm

$$\|x\|_Z := \left(\|x\|_{Z_1}^p + \dots + \|x\|_{Z_m}^p \right)^{1/p}.$$

Theorem I.3 shows the following: For any n -dimensional subspace $X \subseteq Z$ and $\varepsilon > 0$, there are indices $i_1, \dots, i_d \in \{1, \dots, m\}$ with $d \leq O((S/\varepsilon)^{-2} n (\log(n/\varepsilon))^p (\log n)^{2+p/2})$ and a subspace $\tilde{X} \subseteq (Z_{i_1} \oplus \dots \oplus Z_{i_d})_p$ that is $(1 + \varepsilon)$ -equivalent to X . The aforementioned results for subspaces of ℓ_p^m correspond to the setting where each Z_i is 1-dimensional. The case $p \geq 2$ of **Theorem I.3** similarly generalizes [BLM89].

Application to spectral hypergraph sparsifiers. Consider a weighted hypergraph $H = (V, E, c)$, where $\{c_e : e \in E\}$ are nonnegative weights. To every hyperedge $e \in E$, one can associate the semi-norm $N_e(x) := \sqrt{c_e} \max_{u,v \in e} |x_u - x_v|$, and the hypergraph energy

$$N(x)^2 := \sum_{e \in E} N_e(x)^2.$$

Soma and Yoshida [SY19] formalized the notion of spectral sparsification for hypergraphs; it coincides with the notion of approximation expressed in (I.3). In this setting, a sequence of works [SY19], [BST19], [KKTY21b], [KKTY21a], [JLS23], [Lee23] culminates in the existence of $O(\varepsilon^{-2} n (\log n)^2)$ -sparse ε -approximations to N^2 for every $\varepsilon > 0$.

One can obtain a similar result via an application of **Theorem I.3**, as follows. We can express each hyperedge norm as $N_e(x) = \|A_e x\|_\infty$, where $A_e : \mathbb{R}^n \rightarrow \mathbb{R}^{\binom{[n]}{d}}$ is defined by $(A_e x)_{uv} = x_u - x_v$ for all $\{u, v\} \in \binom{[n]}{d}$. The ℓ_∞ norm on $\mathbb{R}^d$ is K -equivalent to the $\ell_{\lfloor \log d \rfloor}$ norm with $K = O(1)$, and the ℓ_p norm on $\mathbb{R}^n$ is 2-uniformly smooth with constant $S \leq O(\sqrt{p})$ [Han56]. Applying **Theorem I.3** with $S \leq O(\sqrt{\log n})$ and $K \leq O(1)$ yields $O(\varepsilon^{-2} n (\log(n/\varepsilon))^2 (\log n)^4)$ -sparse ε -approximators in this special case, nearly matching the known results on spectral hypergraph sparsification. Additionally, **Theorem I.3** can be applied to give nontrivial sparsification results in substantially more general settings, as the next example shows.

Example I.4 (Sparsification for matrix norms). Consider a matrix generalization of this setting: $X \in \mathbb{R}^{d \times d}$, and matrices $S_1, \dots, S_m$ with $S_i \in \mathbb{R}^{d_i \times d}$, and $T_1, \dots, T_m$ with $T_i \in \mathbb{R}^{d \times e_i}$. Define $N_i(X) := \|S_i X T_i\|_{op}$, where $\|\cdot\|_{op}$ denotes the operator norm. Then the semi-norm given by

$N(X) := (\|S_1 X T_1\|_{op}^2 + \dots + \|S_m X T_m\|_{op}^2)^{1/2}$ can be sparsified down to $O((d/\varepsilon)^2 (\log(d/\varepsilon))^2 (\log d)^4)$ terms. This follows because the Schatten p -norm of an operator is 2-uniformly smooth with constant $O(\sqrt{p})$ [BCL94], and for rank d matrices, the Schatten p -norm is $O(1)$ -equivalent to the operator norm when $p \asymp \log d$.

Further results and open questions for sums of squared norms. The rank of a hypergraph H is defined as the quantity $r := \max_{e \in E} |e|$. The best-known result for spectral hypergraph sparsification is due to [JLS23], [Lee23]: For every $\varepsilon > 0$, there is an $O(\varepsilon^{-2} \log(r) \cdot n \log n)$ -sparse ε -approximation to N^2 . In the full paper, we obtain the following generalization.

Theorem I.5 (Sums of squares of ℓ_p norms). *Consider a family of operators $\{A_i : \mathbb{R}^n \rightarrow \mathbb{R}^{k_i} : i \in [m]\}$, and $2 \leq p_1, \dots, p_m \leq p$. Suppose that $N_1, \dots, N_m$ are semi-norms on $\mathbb{R}^n$ and that $N_i(x)$ is K -equivalent to $\|A_i x\|_{p_i}$ for all $i \in [m]$. Then for every $\varepsilon > 0$, there is an $O((K^3/\varepsilon)^2 p n \log(n/\varepsilon))$ -sparse ε -approximation to N^2 where $N(x)^2 := N_1(x)^2 + \dots + N_m(x)^2$.*

In particular, if $k_1, \dots, k_m \leq r$, then each $\|A_i x\|_\infty$ is $O(1)$ -equivalent to $\|A_i x\|_p$ for $p \asymp \log r$, and thus **Theorem I.5** generalizes the aforementioned result for spectral hypergraph sparsifiers. One should note that, for any fixed $p \geq 2$, **Theorem I.5** is tight for methods based on independent sampling, by the coupon collector bound. (Although it is known that in some settings [BSS12] the $\log(n)$ factor can be removed by other methods.)

It is a fascinating open question whether the assumption of p -uniform smoothness can be dropped from **Theorem I.3**. In the full version, we show that it is possible to obtain a non-trivial result for sums of p th powers of general norms for $p \in [1, 2]$.

Theorem I.6 (General sums of p th powers). *If $N_1, \dots, N_m$ are arbitrary semi-norms on $\mathbb{R}^n$, $1 \leq p \leq 2$, and $N(x)^p := N_1(x)^p + \dots + N_m(x)^p$, then for every $\varepsilon > 0$, there is an s -sparse ε -approximation to N^p with*

$$s \leq \varepsilon^{-2} \left(n^{2-1/p} \log(n/\varepsilon) (\log n)^{1/2} + n \log(n/\varepsilon)^p (\log n)^{2+p/2} \right).$$

Note that in the $p = 2$ case, applying **Theorem I.3** directly for $K = \sqrt{n}, S = 1, p = 2$ results in a worse sparsity bound of $O(\varepsilon^{-2} n^2 \log(n/\varepsilon)^2 (\log n)^3)$.

II. IMPORTANCE SAMPLING FOR GENERAL NORMS

Let us now fix semi-norms $N_1, \dots, N_m$ on $\mathbb{R}^n$ and define $N(x) := N_1(x) + \dots + N_m(x)$ for all $x \in \mathbb{R}^n$, as in the setting of **Theorem I.1**. Our method for constructing sparsifiers is simply independent sampling: Consider a probability distribution $\rho = (\rho_1, \dots, \rho_m) \in (0, 1]^m$

on $\{1, \dots, m\}$, and then sample M indices $i_1, \dots, i_M$ independently from ρ and take

$$\tilde{N}(x) := \frac{1}{M} \left(\frac{N_{i_1}(x)}{\rho_{i_1}} + \dots + \frac{N_{i_M}(x)}{\rho_{i_M}} \right).$$

We have $\mathbb{E}[N_{i_1}(x)/\rho_{i_1}] = N(x)$, and therefore $\mathbb{E}[\tilde{N}(x)] = N(x)$ for any fixed x .

In order for these unbiased estimators to be suitably concentrated, it is essential to choose a suitable distribution ρ . To indicate the subtlety involved, we recall two choices for the case of graphs. Suppose that G consists of edges $\{u_1, v_1\}, \dots, \{u_m, v_m\}$ and $N_i(x) = |x_{u_i} - x_{v_i}|$ for each $i \in [m]$. Benczúr and Karger [BK96] define ρ_i to be inversely proportional to the largest k such that the edge $\{u_i, v_i\}$ is contained in a maximal induced k -edge-connected subgraph. Spielman and Srivastava [SS11] define ρ_i as proportional to the effective resistance across the edge $\{u_i, v_i\}$ in G .

Let μ denote the probability measure on $\mathbb{R}^n$ whose density is proportional to $e^{-N(x)}$. We will take ρ_i proportional to the average of $N_i(x)$ under this measure:

$$\rho_i := \frac{\int_{\mathbb{R}^n} N_i(x) e^{-N(x)} dx}{\int_{\mathbb{R}^n} N(x) e^{-N(x)} dx}. \quad (\text{II.1})$$

To motivate this choice of $\rho = (\rho_1, \dots, \rho_m)$, let us now explain the general framework for analyzing sparsification by i.i.d. random sampling and chaining.

Symmetrization. For any norm N on $\mathbb{R}^n$, we use the notation $B_N := \{x \in \mathbb{R}^n : N(x) \leq 1\}$. Our goal is to control the maximum deviation

$$\mathbb{E} \max_{x \in B_N} |\tilde{N}(x) - \mathbb{E}[\tilde{N}(x)]|.$$

By a standard symmetrization argument, to bound this quantity by $O(\delta)$, it suffices to prove that for every fixed choice of indices $i_1, \dots, i_M$, we have

$$\mathbb{E}_{\varepsilon_1, \dots, \varepsilon_M} \frac{1}{M} \sum_{j=1}^M \varepsilon_j \frac{N_{i_j}(x)}{\rho_{i_j}} \leq \delta \left(\max_{x \in B_N} \tilde{N}(x) \right)^{1/2}, \quad (\text{II.2})$$

where $\varepsilon_1, \dots, \varepsilon_M \in \{-1, 1\}$ are uniformly random signs.

Chaining and entropy estimates. If we define $V_x := \frac{1}{M} (\varepsilon_1 N_{i_1}(x)/\rho_{i_1} + \dots + \varepsilon_M N_{i_M}(x)/\rho_{i_M})$, then $\{V_x : x \in \mathbb{R}^n\}$ is a subgaussian process, and $\mathbb{E} \max\{V_x : x \in B_N\}$ can be controlled via standard chaining arguments (see the full paper for background on subgaussian processes, covering numbers, and chaining upper bounds). Define the distance

$$d(x, y) := \left(\mathbb{E} |V_x - V_y|^2 \right)^{1/2} = \frac{1}{M} \left(\sum_{j=1}^M \left(\frac{N_{i_j}(x) - N_{i_j}(y)}{\rho_{i_j}} \right)^2 \right)^{1/2}$$

and let $\mathcal{K}(B_N, d, r)$ denote the minimum number K such that B_N can be covered by K balls of radius r in the metric d . Then Dudley's entropy bound asserts that

$$\mathbb{E} \max_{x \in B_N} V_x \lesssim \int_0^\infty \sqrt{\log \mathcal{K}(B_N, d, r)} dr, \quad (\text{II.3})$$

Our goal, then, is to choose sampling probabilities $\rho_1, \dots, \rho_m$ so as to make the covering numbers $\mathcal{K}(B_N, d, r)$ suitably small.

In order to get a handle on the distance d , let us define

$$\mathcal{N}^\infty(x) := \max_{j \in [M]} \frac{N_{i_j}(x)}{\rho_{i_j}},$$

$$\kappa := \max\{\mathcal{N}^\infty(x) : x \in B_N\}.$$

Then we can bound

$$d(x, y) \leq M^{-1/2} \sqrt{\mathcal{N}^\infty(x - y)} \left(\frac{1}{M} \sum_{j=1}^M \frac{|N_{i_j}(x) - N_{i_j}(y)|}{\rho_{i_j}} \right)^{1/2}$$

$$\leq M^{-1/2} \sqrt{\mathcal{N}^\infty(x - y)} \left(2 \max_{x \in B_N} \tilde{N}(x) \right)^{1/2}.$$

Using this in (II.3) allows us to bound $\mathbb{E} \max_{x \in B_N} V_x$ by

$$M^{-1/2} \left(\max_{x \in B_N} \tilde{N}(x) \right)^{1/2} \int_0^\infty \sqrt{\log \mathcal{K}(B_N, (\mathcal{N}^\infty)^{1/2}, r)} dr$$

$$= M^{-1/2} \left(\max_{x \in B_N} \tilde{N}(x) \right)^{1/2} \int_0^{\sqrt{\kappa}} \sqrt{\log \mathcal{K}(B_N, \mathcal{N}^\infty, r^2)} dr, \quad (\text{II.4})$$

where we have used that the last integrand vanishes above $\sqrt{\kappa}$ since $B_N \subseteq \kappa B_{\mathcal{N}^\infty}$.

Dual-Sudakov inequalities. In order to bound the entropy integral (II.4), let us recall the dual-Sudakov inequality (see [PTJ85] and [LT11, (3.15)]) which allows one to control covering numbers of the Euclidean ball. Let B_2^n denote the Euclidean ball in $\mathbb{R}^n$. Then for any norm N on $\mathbb{R}^n$, it holds that

$$\sqrt{\log \mathcal{K}(B_2^n, N, r)} \lesssim \frac{1}{r} \mathbb{E}[N(\mathbf{g})], \quad (\text{II.5})$$

where $\mathbf{g}$ is a standard n -dimensional Gaussian.

An adaptation of the Pajor-Talagrand proof of (II.5) (see Lemma II.2) allows one to show that for any norms N and $\hat{N}$ on $\mathbb{R}^n$,

$$\log \mathcal{K}(B_N, \hat{N}, r) \lesssim \frac{1}{r} \mathbb{E}[\hat{N}(\mathbf{Z})], \quad (\text{II.6})$$

where $\mathbf{Z}$ has density proportional to $e^{-N(x)} dx$. A closely related estimate was proved by Milman and Pajor [MP89]; see the remarks after (II.13). As this fact is simple and essential to our approach, we provide a proof here. We begin with a useful fact which bounds the measure of shifts of convex sets.

Lemma II.1 (Shift Lemma). Suppose N is a norm on $\mathbb{R}^n$. Define the probability measure μ on $\mathbb{R}^n$ by

$$d\mu(x) \propto \exp(-N(x)).$$

Then for any symmetric convex body W and $z \in \mathbb{R}^n$,

$$\mu(W + z) \geq \exp(-N(z)) \mu(W). \quad (\text{II.7})$$

Proof. For any $z \in \mathbb{R}^n$, it holds that

$$\mu(W + z) = \frac{\int_W \exp(-N(x + z)) dx}{\int_W \exp(-N(x)) dx} \mu(W).$$

Now we bound

$$\begin{aligned} \int_W \exp(-N(x + z)) dx &= \int_W \mathbb{E}_{\sigma \in \{-1, 1\}} \exp(-N(\sigma x + z)) dx \\ &\geq \int_W \exp\left(-\mathbb{E}_{\sigma \in \{-1, 1\}} N(\sigma x + z)\right) dx \\ &\geq \int_W \exp(-(N(x) + N(z))) dx \\ &= \exp(-N(z)) \int_W \exp(-N(x)) dx, \end{aligned}$$

where the equality uses symmetry of W , the first inequality uses convexity of $\exp(x)$, and the second inequality uses the triangle inequality for N . $\square$

Lemma II.2. Let N and $\hat{N}$ be norms on $\mathbb{R}^n$. Define the probability measure μ on $\mathbb{R}^n$ so that

$$d\mu(x) \propto \exp(-N(x)).$$

Then for any $\varepsilon > 0$,

$$\log\left(\mathcal{K}(B_N, \hat{N}, \varepsilon)/2\right) \leq \frac{2}{\varepsilon} \int \hat{N}(x) d\mu(x).$$

Proof. By scaling $\hat{N}$, we may assume that $\varepsilon = 1$. Suppose now that $x_1, \dots, x_M \in B_N$ and $x_1 + B_{\hat{N}}, \dots, x_M + B_{\hat{N}}$ are pairwise disjoint. To establish an upper bound on M , let $\lambda > 0$ be a number we will choose later and write

$$\begin{aligned} 1 &\geq \mu\left(\bigcup_{j \in [M]} \lambda(x_j + B_{\hat{N}})\right) = \sum_{j \in [M]} \mu(\lambda x_j + \lambda B_{\hat{N}}) \\ &\stackrel{(\text{II.7})}{\geq} \sum_{j \in [M]} e^{-\lambda N(x_j)} \mu(\lambda B_{\hat{N}}) \\ &\geq M e^{-\lambda} \mu(\lambda B_{\hat{N}}), \end{aligned}$$

where (II.7) used Lemma II.1 and the last inequality used $x_1, \dots, x_M \in B_N$.

Now choose $\lambda := 2 \int \hat{N}(x) d\mu(x)$ so that Markov's inequality gives

$$\mu(\lambda B_{\hat{N}}) = \mu(\{x : \hat{N}(x) \leq \lambda\}) \geq 1/2.$$

Combining with the preceding inequality yields the upper bound

$$(\log(M/2)) \leq \lambda. \quad \square$$

Applying this with $\hat{N} = N^\infty$ yields

$$\log \mathcal{K}(B_N, N^\infty, r) \leq \frac{1}{r} \mathbb{E}[N^\infty(\mathbf{Z})] = \frac{1}{r} \mathbb{E} \max_{j \in [M]} \frac{N_{ij}(\mathbf{Z})}{\rho_{ij}}. \quad (\text{II.8})$$

At this point, it is quite natural to hope that $N_j(\mathbf{Z})$ is concentrated around its mean, in which case the choice $\rho_j \propto \mathbb{E}[N_j(\mathbf{Z})]$ seems appropriate. Indeed, this is the first point at which we will employ convexity in an essential way. The density $e^{-N(x)}$ is log-concave, and therefore $\mathbf{Z}$ is a log-concave random variable. By recent progress on the KLS conjecture, we know that Lipschitz functions of isotropic log-concave vectors concentrate tightly around their mean.

Let ψ_n denote the KLS constant in dimension n . In the past few years there has been remarkable progress on bounding ψ_n [Che21], [KL22], [JLV22], [Kla23]. In particular, Klartag and Lehec established that $\psi_n \leq O((\log n)^5)$, and the best current bound is $\psi_n \leq O(\sqrt{\log n})$ [Kla23].

Exponential concentration and the KLS conjecture. The next lemma expresses a classical connection between exponential concentration and Poincaré inequalities [GM83]. Say that $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ is L -Lipschitz if $\|\varphi(x) - \varphi(y)\|_2 \leq L\|x - y\|_2$ for all $x, y \in \mathbb{R}^n$.

Theorem II.3. There is a constant $c > 0$ such that the following holds. Suppose $\mathbf{X}$ is a random variable on $\mathbb{R}^n$ whose law is isotropic and log-concave. Then for every L -Lipschitz function $\varphi : \mathbb{R}^n \rightarrow \mathbb{R}$ and $t > 0$,

$$\mathbb{P}(|\varphi(\mathbf{X}) - \mathbb{E}[\varphi(\mathbf{X})]| > t) \leq 2e^{-ct/(\psi_n L)}.$$

This implies the following consequence.

Corollary II.4. There is a constant $c > 0$ such that the following holds. Consider a semi-norm N on $\mathbb{R}^n$ and a random vector $\mathbf{Z}$ whose distribution is symmetric and log-concave. Then for any $t > 0$,

$$\mathbb{P}(|N(\mathbf{Z}) - \mathbb{E}[N(\mathbf{Z})]| > t) \leq 2 \exp\left(-\frac{c}{\psi_n} \frac{t}{\mathbb{E}[N(\mathbf{Z})]}\right).$$

Proof. Define the covariance matrix $A := \mathbb{E}[\mathbf{Z}\mathbf{Z}^\top]$ and let $\mathbf{X} := A^{-1/2}\mathbf{Z}$. Then the law of $\mathbf{X}$ is log-concave and isotropic by construction. Thus Theorem II.3 gives the desired result once we confirm the Lipschitz bound

$$N(A^{1/2}x) \leq 2 \mathbb{E}[N(\mathbf{Z})] \cdot \|x\|_2. \quad (\text{II.9})$$

To this end, let N^* denote the dual norm to N and write

$$\begin{aligned} N(A^{1/2}x) &= \sup_{N^*(w) \leq 1} \langle w, A^{1/2}x \rangle \\ &= \sup_{N^*(w) \leq 1} \langle A^{1/2}w, x \rangle \leq \|x\|_2 \sup_{N^*(w) \leq 1} \|A^{1/2}w\|_2. \end{aligned}$$

Then we have

$$\begin{aligned} \|A^{1/2}w\|_2 &= \langle w, Aw \rangle^{1/2} = \left(\mathbb{E}[\langle w, Z \rangle^2] \right)^{1/2} \\ &\leq 2 \mathbb{E}[\langle w, Z \rangle] \\ &\leq 2\mathcal{N}^*(w) \mathbb{E}[N(Z)] \end{aligned}$$

where the penultimate inequality follows from standard facts on moments of log-concave variables: $\langle y, Z \rangle$ is symmetric and log-concave. $\square$

With this in hand, a union bound gives

$$\mathbb{E} \max_{j \in [M]} \frac{N_{ij}(Z)}{\mathbb{E}[N_{ij}(Z)]} \lesssim \psi_n \log M.$$

To make ρ a probability measure, we take $\rho_j := \mathbb{E}[N_j(Z)]/\mathbb{E}[N(Z)]$ for $j = 1, \dots, m$, and then (II.8) becomes

$$\begin{aligned} \log \mathcal{K}(B_N, \mathcal{N}^\infty, r) &\lesssim \frac{1}{r} (\psi_n \log M) \mathbb{E}[N(Z)] \\ &= \frac{1}{r} n \psi_n \log(M), \end{aligned} \quad (\text{II.10})$$

where the last inequality uses $\mathbb{E}[N(Z)] = n$, which follows from a straightforward integration using that the law of Z has density proportional to $e^{-N(x)}$. Thus we have

$$\begin{aligned} &\int_{\sqrt{\kappa}/n^2}^{\sqrt{\kappa}} \sqrt{\log \mathcal{K}(B_N, \mathcal{N}^\infty, r^2)} dr \\ &\lesssim (n \psi_n \log M)^{1/2} \int_{\sqrt{\kappa}/n^2}^{\sqrt{\kappa}} \frac{1}{r} dr \lesssim (n \psi_n \log M)^{1/2} \log n. \end{aligned} \quad (\text{II.11})$$

Standard volume arguments in $\mathbb{R}^n$ allow us to control the rest of the integral:

$$\int_0^{1/n^2} \sqrt{\log \mathcal{K}(B_{\mathcal{N}^\infty}, \mathcal{N}^\infty, r^2)} dr \lesssim 1,$$

and therefore

$$\begin{aligned} &\int_0^{\sqrt{\kappa}/n^2} \sqrt{\log \mathcal{K}(B_N, \mathcal{N}^\infty, r^2)} dr \\ &\lesssim \sqrt{\kappa} \int_0^{1/n^2} \sqrt{\log \mathcal{K}(B_{\mathcal{N}^\infty}, \mathcal{N}^\infty, r^2)} dr \lesssim \sqrt{\kappa}. \end{aligned}$$

Plugging this and (II.11) into (II.4) gives

$$\begin{aligned} &\mathbb{E} \max_{x \in B_N} V_x \\ &\lesssim M^{-1/2} \left(\max_{x \in B_N} \tilde{N}(x) \right)^{1/2} \left(\sqrt{\kappa} + (n \psi_n \log M)^{1/2} \log n \right). \end{aligned}$$

Finally, observe that (II.10) gives the bound $\kappa \lesssim n \psi_n \log(M)$, resulting in

$$\mathbb{E} \max_{x \in B_N} V_x \lesssim \left(\frac{n \psi_n \log(M) (\log n)^2}{M} \right)^{1/2} \left(\max_{x \in B_N} \tilde{N}(x) \right)^{1/2}.$$

Choosing $M \asymp \delta^{-2} n (\log n)^2 \psi_n \log(n/\delta)$ yields our desired goal (II.2).

Modifications for sums of p th powers. In order to apply these methods to sums of p th powers $N(x)^p = N_1(x)^p + \dots + N_m(x)^p$ for $1 \leq p \leq 2$, we use the natural analog of (II.1):

$$\rho_i := \frac{\int_{\mathbb{R}^n} N_i(x)^p e^{-N(x)^p} dx}{\int_{\mathbb{R}^n} N(x)^p e^{-N(x)^p} dx}. \quad (\text{II.12})$$

Note that if $p = 2$ and one defines $N_i(x) := |(Ax)_i|$ for a matrix $A \in \mathbb{R}^{m \times n}$, then ρ_i are exactly the leverage scores of A (up to scaling by n). For $p > 2$, we choose ρ_i proportional to $\int_{\mathbb{R}^n} N_i(x)^p e^{-N(x)^2} dx$.

The main hurdle in this setting is that we only establish the analog of (II.6) for p -uniformly smooth norms. It turns out however that if Z has the law whose density is proportional to $e^{-N(x)^p}$ and N is p -uniformly smooth, then for any norm $\hat{N}$,

$$(\log \mathcal{K}(B_N, B_{\hat{N}}, r))^{1/p} \lesssim \frac{1}{r} \mathbb{E}[\hat{N}(Z)]. \quad (\text{II.13})$$

A closely-related estimate is mentioned in [MP89, Eq. (9)], where instead the distribution of Z is uniform on B_N .

General norms and block Lewis weights. To obtain Theorem 1.6 for general norms, we must resort to a dimension-dependent version of (II.13). Moreover, we need to augment the sampling probabilities in (II.12) in order to effectively bound the diameter $\text{diam}(B_N, \mathcal{N}^\infty)$. For this, as well as for sums of squares of ℓ_p norms (Theorem 1.5), in the full paper we formulate a generalization of ℓ_p Lewis weights, motivated by the construction of weights in [KKT21a], [JLS23], [Lee23].

For a collection of vectors $a_1, \dots, a_k \in \mathbb{R}^n$, the ℓ_p Lewis weights [Lew78], [Lew79] result from consideration of the optimization

$$\max\{|\det(U)| : \alpha(U) \leq 1\}, \quad (\text{II.14})$$

where α is the norm on linear operators $U : \mathbb{R}^n \rightarrow \mathbb{R}^n$ defined by

$$\alpha(U) = \left(\sum_{i=1}^k \|U a_i\|_2^p \right)^{1/p}.$$

Let us now consider a substantial generalization of this setting where $S_1 \cup \dots \cup S_m = \{1, \dots, k\}$ is a partition of the index set. Given $p_1, \dots, p_m \geq 2$ and $q \geq 1$, we define the norm

$$\alpha(U) := \left(\sum_{j=1}^m \left(\sum_{i \in S_j} \|U a_i\|_2^{p_j} \right)^{q/p_j} \right)^{1/q},$$

One can establish properties of the corresponding optimizer of (II.14), leading to the following generalization of the Lewis weights.

Definition II.5 (Block norm). Consider any $p_1, \dots, p_m, q \in [1, \infty]$, and a partition $S_1 \cup \dots \cup S_m = [k]$. For $p_j < \infty$, define

$$\mathcal{N}_j(u) := \left(\sum_{i \in S_j} |u_i|^{p_j} \right)^{1/p_j},$$

and for $p_j = \infty$, take $\mathcal{N}_j(u) := \max\{|u_i| : i \in S_j\}$. Define $\mathcal{N}(u) := \|(\mathcal{N}_1(u), \dots, \mathcal{N}_m(u))\|_q$.

Lemma II.6. Consider $p_1, \dots, p_m \in [2, \infty]$ and $q \in [1, \infty)$. Let $\mathcal{N}_1, \dots, \mathcal{N}_m$ and $\mathcal{N}$ be as in Definition II.5. Fix $A \in \mathcal{L}(\mathbb{R}^n, \mathbb{R}^k)$ with $\text{rank}(A) = n$, and denote for $j = 1, \dots, m$,

$$\alpha_j(U) := \mathcal{N}_j(\|UA^\top e_1\|_2, \dots, \|UA^\top e_k\|_2)$$

Then there is a nonnegative diagonal matrix W such that for $U = (A^\top W A)^{-1/2}$, the following are true:

(1) It holds that

$$\alpha_1(U)^q + \dots + \alpha_m(U)^q = \begin{cases} n & 1 \leq q \leq 2 \\ n^{q/2} & q \geq 2. \end{cases}$$

(2) For all $x \in \mathbb{R}^n$,

$$\mathcal{N}_j(Ax) \leq \alpha_j(U) \|U^{-1}x\|_2 \leq \alpha_j(U) \mathcal{N}(Ax).$$

III. ALGORITHMS

A. Computing the sampling weights via homotopy

We now present an algorithm constructing a sparsifier for $N(x) = N_1(x) + \dots + N_m(x)$ that runs in time $n^{O(1)}$ plus the time required to do $m(\log n)^{O(1)} + n^{O(1)}$ total evaluations of norms $N_i(y)$ for various $i \in [m]$ and $y \in \mathbb{R}^n$. It employs a homotopy-type method that has been used for efficient sparsification in multiple settings (see, e.g., [MP12], [KLM⁺17], [JSS18], [AJSS19]).

To compute reasonable overestimates of the sampling weights $\{\rho_i\}$ from (II.1), one approach is to simply sample from the probability measure μ with density proportional to $e^{-N(x)}$, evaluate the N_i at the sample, and use a scaling of the average evaluation of N_i as the estimate of ρ_i . Sampling from a log-concave distribution, especially those induced by norms, is a well-studied task, and can be done in $n^{O(1)} \log^{O(1)}(nR/r)$ time if N is (r, R) -rounded; see [CV18], [JLLV21] and Theorem III.3, Corollary III.4. If a norm evaluation can be performed in time $\mathcal{T}_{\text{eval}}$, this would naively require time $mn^{O(1)} \log^{O(1)}(nR/r) \mathcal{T}_{\text{eval}}$, whereas we would like our algorithms to run in nearly “input-sparsity time,” as expressed before.

We first observe that one need only sample from a distribution with density $\propto e^{-\tilde{N}(x)}$ for some norm $\tilde{N}$ that is $O(1)$ -equivalent to $N(x)$. Given this fact, for simplicity let us assume that N is a genuine norm that is (r, R) -rounded in the sense that $r\|x\|_2 \leq N(x) \leq R\|x\|_2$ for all $x \in \mathbb{R}^n$. Define the family of norms $N_t(x) := N(x) + t\|x\|_2$.

For $t = R$, it holds that $N_R(x)$ is 2-equivalent to the norm $R\|x\|_2$, and sampling from the distribution with density $\propto e^{-R\|x\|_2}$ is trivial. Therefore we can construct an $n(\log n)^{O(1)}$ -sparse $1/2$ -approximation $\tilde{N}_R(x)$ to $N_R(x)$.

Now assuming we have an $n(\log n)^{O(1)}$ -sparse $1/2$ -approximation $\tilde{N}_t$ to N_t for $r \leq t \leq R$, we construct a sparsifier for $N_{t/2}(x)$ by sampling from the measure with density $\propto e^{-\tilde{N}_t(x)}$. This works because $\tilde{N}_t$ is 2-equivalent to N_t , which is 2-equivalent to $N_{t/2}$. After $O(\log(R/r))$ iterations, we arrive at sparse norm $\tilde{N}$ that is $O(1)$ -equivalent to N , and then by sampling from the distribution with density $\propto e^{-\tilde{N}(x)}$, we are able to construct a sparse ε -approximation to N itself. To handle the case when N is a seminorm we modify this approach to instead obtain $\tilde{N}(x)$ such that $\tilde{N}(x) + \varepsilon r\|x\|_2$ is an ε -approximation to $N_{\varepsilon r}$ and argue that this suffices for $\tilde{N}$ to be an $O(\varepsilon)$ -approximation of N .

B. Details and analysis

We first present an efficient algorithm for sampling in the case $p = 1$. Consider semi-norms $N_1, \dots, N_m$ on $\mathbb{R}^n$ and suppose that each N_i can be evaluated in time $\mathcal{T}_{\text{eval}}$, and that $N(x) := N_1(x) + \dots + N_m(x)$ is (r, R) -rounded for $0 < r \leq R$.

Theorem III.1 (Efficient sparsification). If N is (r, R) -rounded, then for any $\varepsilon \geq n^{-O(1)}$, there is an algorithm running in time $(m(\log n)^{O(1)} + n^{O(1)})(\log(mR/r))^{O(1)} \mathcal{T}_{\text{eval}}$ that with high probability produces an $O(n\varepsilon^{-2} \log(n/\varepsilon)(\log n)^{2.5})$ -sparse ε -approximation to N .

Suppose now that $\tilde{N}$ is a semi-norm on $\mathbb{R}^n$ that is K -equivalent to N , and let μ be the probability measure with density proportional to $e^{-\tilde{N}(x)} dx$.

Lemma III.2 (Sampling to sparsification). For $h \geq 1$, there is an algorithm that, given $O(h\psi_n \log(m+n))$ independent samples from μ and $\varepsilon > 0$, computes with probability at least $1 - (m+n)^{-h}$, an s -sparse ε -approximation to N in time $O(m\psi_n \log(n+m) + s)\mathcal{T}_{\text{eval}}$, where $s \leq O(K^2 \varepsilon^{-2} n \varepsilon^{-2} \log(n/\varepsilon)(\log n)^{2.5})$.

Proof. Let $X_1, \dots, X_k \in \mathbb{R}^n$ be independent samples from μ . Denote, for $i = 1, \dots, m$,

$$\tau_i := \frac{3}{2} \frac{1}{k} (N_i(X_1) + N_i(X_2) + \dots + N_i(X_k))$$

$$\sigma_i := \mathbb{E}[N_i(X_1)].$$

Since μ is log-concave, Corollary II.4 asserts there is a constant $c > 0$ such that

$$\mathbb{P}(|N_i(x_j) - \sigma_i| > t) \leq 2 \exp\left(-\frac{ct}{\psi_n \sigma_i}\right)$$

Consequently, for some $k \lesssim h\psi_n \log(m+n)$, it holds that

$$\mathbb{P}(\sigma_i \leq \tau_i \leq 2\sigma_i, i = 1, \dots, m) \geq 1 - (m+n)^{-h}.$$

Thus (as discussed in the full paper) with high probability sampling proportional to τ_i yields the desired sparse approximation. $\square$

The preceding lemma shows that sampling from a distribution with $d\mu(x) \propto e^{-\tilde{N}(x)}$ suffices to efficiently sparsify a semi-norm N that is K -equivalent to $\tilde{N}$. A long line of work establishes algorithms that sample from a distribution that is close to uniform on any well-conditioned convex body $A \subseteq \mathbb{R}^n$, given only membership oracles to A . In the following statement, let B_2^n denote the Euclidean unit ball in $\mathbb{R}^n$.

Theorem III.3 ([JLLV21, Theorem 1.5], [CV18, Theorem 1.2]). *There is an algorithm that, given a convex body $A \subseteq \mathbb{R}^n$ satisfying $r \cdot B_2^n \subseteq A \subseteq R \cdot B_2^n$ and $\varepsilon > 0$, samples from a distribution that is within TV distance ε from the uniform measure on A using $O(n^3(\log \frac{nR}{\varepsilon r})^{O(1)})$ membership oracle queries to A , and $(n(\log \frac{nR}{\varepsilon r}))^{O(1)}$ additional time.*

When N is a norm, one obtains immediately an algorithm for sampling from the measure μ on $\mathbb{R}^n$ with density $d\mu(x) \propto e^{-N(x)} dx$ using evaluations of $N(x)$.

Corollary III.4. *There is an algorithm that, given an (r, R) -rounded norm N on $\mathbb{R}^n$ and $\varepsilon > 0$, samples from a distribution that is within TV distance ε from the measure μ with density proportional to $e^{-N(x)} dx$ using $O(n^3(\log \frac{nR}{\varepsilon r})^{O(1)})$ evaluations of $N(x)$, and $(n(\log \frac{nR}{\varepsilon r}))^{O(1)}$ additional time.*

Proof. Note that if Z has law μ , then the density of $N(Z)$ is proportional to $e^{-\lambda} \lambda^{n-1}$. Let λ be a sample from the latter distribution. The algorithm is as follows: Sample a point X from the uniform measure on B_N using Theorem III.3, and then output the point $\lambda X / N(X)$. $\square$

Combining Lemma III.2 and Corollary III.4, we see that if one can sample from the distribution induced by a sparsifier, then one can efficiently sparsify and if one can efficiently sparsify, then one can perform the requisite sampling.

This chicken-and-egg problem has arisen for a variety of sparsification problems and there is a relatively simple and standard solution introduced in [MP12] that has been used in a range of settings; see e.g., [KLM⁺17], [JSS18], [AJSS19]).

Instead of simply sampling proportional to $e^{-N(x)}$ directly, we first sample proportional to the density $\exp(-(N(x) + t\|x\|_2))$, where t is chosen large enough that the sampling problem is trivial. This gives a sparsifier for $N(x) + t\|x\|_2$ which, in turn, can be used to efficiently sparsify $N(x) + t/2\|x\|_2$. Iterating allows us to establish Theorem III.1.

Proof of Theorem III.1. Recall our assumption that $r\|x\|_2 \leq N(x) \leq R\|x\|_2$ for all $x \in \ker(N)^\perp$. For $t \geq 0$,

denote $N_t(x) := N(x) + t\|x\|_2$. Note that N_R is 2-equivalent to $R\|x\|_2$, and consequently by sampling from $d\mu(x) \propto \exp(-R\|x\|_2)$ using Corollary III.4, we can use Lemma III.2 to obtain an $\tilde{O}(n)$ -sparse 1/2-approximation to N_R .

Now for any $t \in [\varepsilon r, R]$, suppose $\tilde{N}_t$ is an $\tilde{O}(n)$ -sparse 1/2-approximation to N_t . Note that $\tilde{N}_t$ is $(t/2, 4R)$ -rounded. Thus, using Corollary III.4, we can compute a sample from the distribution with density $\propto e^{-\tilde{N}_t(x)}$ in time $(n \log(R/r))^{O(1)} \mathcal{T}_{\text{eval}}$. We can ignore the total variation error in Corollary III.4 as long as it is less than $m^{-O(1)}$ and charge it to the failure probability. Since $N_{t/2}$ is 2-equivalent to N_t , which is 2-equivalent to $\tilde{N}_t$, we can use Lemma III.2 to obtain an $\tilde{O}(n)$ -sparse 1/2-approximation to $N_{t/2}$.

After $O(\log(R/(\varepsilon r)))$ iterations, one obtains an $\tilde{O}(n)$ -sparse 1/2-approximation to $N_{\varepsilon r}$. A final application of Lemma III.2 obtains an $O(n\varepsilon^{-2} \log(n/\varepsilon)(\log n)^{2.5})$ -sparse ε -approximation to $N_{\varepsilon r}$. To conclude, note that for all $x \in \ker(N)^\perp$, $N_{\varepsilon r}$ is $(1 + \varepsilon)$ -equivalent to N . Moreover, in $N_{\varepsilon r}(x) = N(x) + \varepsilon r\|x\|_2$, only the summand $\varepsilon r\|x\|_2$ fails to vanish on $\ker(N)$. This can be removed from $N_{\varepsilon r}$ to obtain a $(1 + 2\varepsilon)$ -approximation to N with the same sparsity. The result then follows by applying this procedure with a smaller value of ε . $\square$

Remark III.5 (Algorithm for $1 < p \leq 2$). We note that it is possible to extend Theorem III.1 to the setting of $1 < p \leq 2$ under a mild additional assumption. Specifically, we need to assume that each semi-norm N_i is itself K -equivalent to a p -uniformly smooth semi-norm $\mathcal{N}_i$ with constant $\mathcal{S}_p$, and that we have oracle access to $\mathcal{N}_i$.

For any weights $w_1, \dots, w_m \geq 0$, the semi-norm $N_w(x) := (w_1 N_1(x)^p + \dots + w_m N_m(x)^p)^{1/p}$ is then K -equivalent to the semi-norm $\mathcal{N}_w(x) := (w_1 \mathcal{N}_1(x)^p + \dots + w_m \mathcal{N}_m(x)^p)^{1/p}$, where each $\mathcal{N}_i$ is p -uniformly smooth with constant $\mathcal{S}_p$. Since the ℓ_p sum of p -uniformly smooth semi-norms is also p -uniformly smooth quantitatively (see [Fig76]), it holds that N_w is K -equivalent to a semi-norm $\mathcal{N}_w$ that is p -uniformly smooth with constant $O(\mathcal{S}_p)$. One can then proceed along similar lines using the interpolants

$$N_t(x) := \left(N(x)^p + t\|x\|_2^p \right)^{1/p},$$

which are similarly K -equivalent to the p -uniformly smooth norm $\mathcal{N}_t(x) = \left(\mathcal{N}(x)^p + t\|x\|_2^p \right)^{1/p}$, since $\|\cdot\|_2$ is p -uniformly smooth with constant 1 for any $1 \leq p \leq 2$.

1) *Sparsifying symmetric submodular functions:* First recall that the Lovász extension $\bar{F}$ is a semi-norm. This follows because $\bar{F}$ can be expressed as

$$\bar{F}(x) = \int_{-\infty}^{\infty} F(\{i : x_i \leq t\}) dt.$$

Note that the integral is finite because $F(\emptyset) = F(V) = 0$, and clearly $\bar{F}(cx) = c\bar{F}(x)$ for all $c > 0$. Also because F is symmetric we have $F(x) = \int_{-\infty}^{\infty} F(\{i : x_i \leq t\}) dt = \int_{-\infty}^{\infty} F(\{i : x_i \geq t\}) dt = F(-x)$. Finally, it is a standard fact that F is submodular if and only if $\bar{F}$ is convex. Thus, $\bar{F}$ is indeed a semi-norm.

Proof of Corollary I.2. We assume that $\varepsilon \geq m^{-1/2}$, else the desired sparsity bound is trivial.

Let $\tilde{f}_1, \dots, \tilde{f}_m$ denote the respective Lovász extensions of $f_1, \dots, f_m$, and let $\tilde{F}$ denote the Lovász extension of F . Define $\tilde{F}(x) := \bar{F}(x) + m^{-4}\|x\|_2$ and $\tilde{f}_i(x) := \tilde{f}_i(x) + m^{-5}\|x\|_2$ so that $\tilde{F}(x) = \tilde{f}_1(x) + \dots + \tilde{f}_m(x)$. Clearly each $\tilde{f}_i$ is $(m^{-5}, O(nR))$ -rounded as $\tilde{f}_i(x) \leq 2\|x\|_{\infty}R \leq 2R\sqrt{n}\|x\|_2$. Thus Theorem III.1 yields weights $w \in \mathbb{R}_+^m$ with the asserted sparsity bound and such that

$$\left| \tilde{F}(x) - \sum_{i=1}^m w_i \tilde{f}_i(x) \right| \leq \varepsilon \tilde{F}(x), \quad \forall x \in \mathbb{R}^n.$$

Additionally, the unbiased sampling scheme of Section II guarantees that $\mathbb{E}[w_1 + \dots + w_m] = n$, so $\sum_{i=1}^m w_i \leq 2n$ with probability at least $1/2$. Assuming this holds, let us argue that $|F(S) - \sum_{i \in [m]} w_i f_i(S)| \leq 2\varepsilon F(S)$ for all $S \subseteq V$. Indeed,

$$\left| F(S) - \sum_{i=1}^m w_i f_i(S) \right| \leq \varepsilon \tilde{F}(S) + \left(m + \sum_{i=1}^m w_i \right) m^{-5} \|x\|_2 \leq \varepsilon F(S) + m^{-3}.$$

This is at most $2\varepsilon F(S)$ if $F(S) \geq 1$, since we assumed that $\varepsilon \geq m^{-1/2}$.

If, on the other hand, $F(S) = 0$, then we conclude that all $f_i(S) = 0$ for all $i \in \text{supp}(w)$. This is because the weights given by the independent sampling procedure are at least $1/M \geq 1/m$, and each function f_i is integer-valued. Thus $w_1 f_1(S) + \dots + w_m f_m(S) = 0$ as well. $\square$

REFERENCES

- [AJSS19] AmirMahdi Ahmadi, Arun Jambulapati, Amin Saberi, and Aaron Sidford. Perron-Frobenius theory in nearly linear time: Positive eigenvectors, M-matrices, graph kernels, and other applications. In Timothy M. Chan, editor, *Proceedings of the Thirtieth Annual ACM-SIAM Symposium on Discrete Algorithms, SODA 2019, San Diego, California, USA, January 6-9, 2019*, pages 1387–1404. SIAM, 2019. 7, 8
- [BCL94] Keith Ball, Eric A. Carlen, and Elliott H. Lieb. Sharp uniform convexity and smoothness inequalities for trace norms. *Invent. Math.*, 115(3):463–482, 1994. 3
- [BK96] András A. Benczúr and David R. Karger. Approximating s-t minimum cuts in (n^2) time. In *Proceedings of the Twenty-eighth Annual ACM Symposium on the Theory of Computing (Philadelphia, PA, 1996)*, pages 47–55. ACM, New York, 1996. 1, 4
- [BLM89] J. Bourgain, J. Lindenstrauss, and V. Milman. Approximation of zonoids by zonotopes. *Acta Math.*, 162(1-2):73–141, 1989. 3
- [BSS12] Joshua Batson, Daniel A. Spielman, and Nikhil Srivastava. Twice-Ramanujan sparsifiers. *SIAM J. Comput.*, 41(6):1704–1721, 2012. 2, 3
- [BSS14] Joshua Batson, Daniel A. Spielman, and Nikhil Srivastava. Twice-Ramanujan sparsifiers. *SIAM Rev.*, 56(2):315–334, 2014. 2
- [BST19] Nikhil Bansal, Ola Svensson, and Luca Trevisan. New notions and constructions of sparsification for graphs and hypergraphs. In David Zuckerman, editor, *60th IEEE Annual Symposium on Foundations of Computer Science, FOCS 2019, Baltimore, Maryland, USA, November 9-12, 2019*, pages 910–928. IEEE Computer Society, 2019. 3
- [Che21] Yuansi Chen. An almost constant lower bound of the isoperimetric coefficient in the KLS conjecture. *Geom. Funct. Anal.*, 31(1):34–61, 2021. 5
- [CKP+17] Michael B. Cohen, Jonathan Kelner, John Peebles, Richard Peng, Anup B. Rao, Aaron Sidford, and Adrian Vladu. Almost-linear-time algorithms for Markov chains and new spectral primitives for directed graphs. In *STOC’17—Proceedings of the 49th Annual ACM SIGACT Symposium on Theory of Computing*, pages 410–419. ACM, New York, 2017. 2
- [CV18] Ben Cousins and Santosh S. Vempala. Gaussian cooling and $o^*(n^3)$ algorithms for volume and gaussian volume. *SIAM J. Comput.*, 47(3):1237–1273, 2018. 7, 8
- [Fig76] T. Figiel. On the moduli of convexity and smoothness. *Studia Math.*, 56(2):121–155, 1976. 2, 8
- [GM83] M. Gromov and V. D. Milman. A topological application of the isoperimetric inequality. *Amer. J. Math.*, 105(4):843–854, 1983. 5
- [Han56] Olof Hanner. On the uniform convexity of L^p and l^p . *Ark. Mat.*, 3:239–244, 1956. 3
- [JLLV21] He Jia, Aditi Laddha, Yin Tat Lee, and Santosh S. Vempala. Reducing isotropy and volume to KLS: an $o^*(n^3\psi^2)$ volume algorithm. In Samir Khuller and Virginia Vassilevska Williams, editors, *STOC ’21: 53rd Annual ACM SIGACT Symposium on Theory of Computing, Virtual Event, Italy, June 21-25, 2021*, pages 961–974. ACM, 2021. 7, 8
- [JLS23] Arun Jambulapati, Yang P. Liu, and Aaron Sidford. Chaining, group leverage score overestimates, and fast spectral hypergraph sparsification. In Barna Saha and Rocco A. Servedio, editors, *Proceedings of the 55th Annual ACM Symposium on Theory of Computing, STOC 2023, Orlando, FL, USA, June 20-23, 2023*, pages 196–206. ACM, 2023. Full version at [arXiv:2209.10539](https://arxiv.org/abs/2209.10539). 3, 6
- [JLV22] Arun Jambulapati, Yin Tat Lee, and Santosh S. Vempala. A slightly improved bound for the KLS constant. Available at [arXiv:2208.11644](https://arxiv.org/abs/2208.11644), 2022. 5
- [JSS18] Arun Jambulapati, Kirankumar Shiragur, and Aaron Sidford. Efficient structured matrix recovery and nearly-linear time algorithms for solving inverse symmetric m-matrices. *arXiv*, arxiv:1812.06295, 2018. 7, 8
- [KKTY21a] Michael Kapralov, Robert Krauthgamer, Jakab Tardos, and Yuichi Yoshida. Spectral hypergraph sparsifiers of nearly linear size. In *62nd IEEE Annual Symposium on Foundations of Computer Science, FOCS 2021, Denver, CO, USA, February 7-10, 2022*, pages 1159–1170. IEEE, 2021. 3, 6
- [KKTY21b] Michael Kapralov, Robert Krauthgamer, Jakab Tardos, and Yuichi Yoshida. Towards tight bounds for spectral sparsification of hypergraphs. In Samir Khuller and Virginia Vassilevska Williams, editors, *STOC ’21: 53rd Annual ACM SIGACT Symposium on Theory of Computing, Virtual Event, Italy, June 21-25, 2021*, pages 598–611. ACM, 2021. 3
- [KL22] Bo’az Klartag and Joseph Lehec. Bourgain’s slicing problem and KLS isoperimetry up to polylog. *Geom. Funct. Anal.*, 32(5):1134–1159, 2022. 5
- [Kla23] Bo’az Klartag. Logarithmic bounds for isoperimetry and slices of convex sets. Available at [arxiv:2303.14938](https://arxiv.org/abs/2303.14938), 2023. 2, 5
- [KLM+17] Michael Kapralov, Yin Tat Lee, Cameron Musco, Christopher Musco, and Aaron Sidford. Single pass spectral sparsification in dynamic streams. *SIAM J. Comput.*, 46(1):456–477, 2017. 7, 8

- [Lee23] James R. Lee. Spectral hypergraph sparsification via chaining. In Barna Saha and Rocco A. Servedio, editors, *Proceedings of the 55th Annual ACM Symposium on Theory of Computing, STOC 2023, Orlando, FL, USA, June 20-23, 2023*, pages 207–218. ACM, 2023. Full version at [arXiv:2209.04539](#). 3, 6
- [Lew78] D. R. Lewis. Finite dimensional subspaces of L_p . *Studia Math.*, 63(2):207–212, 1978. 6
- [Lew79] D. R. Lewis. Ellipsoids defined by Banach ideal norms. *Mathematika*, 26(1):18–29, 1979. 6
- [Lov83] L. Lovász. Submodular functions and convexity. In *Mathematical programming: the state of the art (Bonn, 1982)*, pages 235–257. Springer, Berlin, 1983. 2
- [LT11] Michel Ledoux and Michel Talagrand. *Probability in Banach spaces*. Classics in Mathematics. Springer-Verlag, Berlin, 2011. Isoperimetry and processes, Reprint of the 1991 edition. 4
- [MP89] Vitali Milman and Alain Pajor. Cas limites dans des inégalités du type de Khinchine et applications géométriques. *C. R. Acad. Sci. Paris Sér. I Math.*, 308(4):91–96, 1989. 4, 6
- [MP12] Gary L. Miller and Richard Peng. Iterative approaches to row sampling. *arXiv*, arxiv:1211.2713v1, 2012. 7, 8
- [PTJ85] Alain Pajor and Nicole Tomczak-Jaegermann. Remarques sur les nombres d’entropie d’un opérateur et de son transposé. *C. R. Acad. Sci. Paris Sér. I Math.*, 301(15):743–746, 1985. 4
- [Rud99] M. Rudelson. Random vectors in the isotropic position. *J. Funct. Anal.*, 164(1):60–72, 1999. 2
- [RY22] Akbar Rafiey and Yuichi Yoshida. Sparsification of decomposable submodular functions. In *Thirty-Sixth AAAI Conference on Artificial Intelligence, AAAI 2022, Thirty-Fourth Conference on Innovative Applications of Artificial Intelligence, IAAI 2022, The Twelveth Symposium on Educational Advances in Artificial Intelligence, EAAI 2022 Virtual Event, February 22 - March 1, 2022*, pages 10336–10344. AAAI Press, 2022. 2
- [SS11] Daniel A. Spielman and Nikhil Srivastava. Graph sparsification by effective resistances. *SIAM J. Comput.*, 40(6):1913–1926, 2011. 2, 4
- [ST11] Daniel A. Spielman and Shang-Hua Teng. Spectral sparsification of graphs. *SIAM J. Comput.*, 40(4):981–1025, 2011. 2
- [SY19] Tasuku Soma and Yuichi Yoshida. Spectral sparsification of hypergraphs. In Timothy M. Chan, editor, *Proceedings of the Thirtieth Annual ACM-SIAM Symposium on Discrete Algorithms, SODA 2019, San Diego, California, USA, January 6-9, 2019*, pages 2570–2581. SIAM, 2019. 3
- [Tal90] Michel Talagrand. Embedding subspaces of L_1 into l_1^N . *Proc. Amer. Math. Soc.*, 108(2):363–369, 1990. 3
- [Tal95] M. Talagrand. Embedding subspaces of L_p in l_p^N . In *Geometric aspects of functional analysis (Israel, 1992–1994)*, volume 77 of *Oper. Theory Adv. Appl.*, pages 311–325. Birkhäuser, Basel, 1995. 3