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ABSTRACT

A recent paper by L. Zheng [Phys. Plasmas **30**, 042515 (2023)] presented a critical analysis of standard Lie-transform perturbation theory and suggested that its application to the problem of charged-particle motion in a magnetic field suffered from ordering inconsistencies. In the present Comment, we suggest that this criticism is unjustified and that standard Lie-transform perturbation theory does not need to be modified in its application to guiding-center theory.

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In a recent paper, Zheng¹ suggested that when standard Lie-transform perturbation theory² is applied to the guiding-center theory of charged-particle motion in a magnetic field,^{3–5} ordering inconsistencies arise. Unfortunately, Zheng never defined an ordering parameter (denoted ϵ in the present Comment) in his critique of standard Lie-transform perturbation theory and, here, it is argued that his proposed modification of Lie-transform perturbation theory is completely unnecessary.

In guiding-center theory,^{6,8} the mathematical construction of the magnetic moment relies on the space-time scales (L_B, ω^{-1}) of the confining magnetic field $\mathbf{B} = B \hat{\mathbf{b}}$ to be long compared to the characteristic gyroradius ρ and the gyroperiod $\Omega^{-1} = mc/eB$, respectively, leading to the small dimensionless small parameter⁶

$$\epsilon_B \equiv \rho/L_B \sim \omega/\Omega \ll 1, \quad (1)$$

which is also used in Zheng’s paper. While this dimensional parameter makes physical sense, it is not an ordering parameter *per se* to be used in a perturbation expansion.

In early formulations of guiding-center theory,^{7–11} the dimensional ratio m/e was proposed as an ordering parameter in deriving guiding-center equations of motion, which is consistent with Eq. (1), i.e., $\epsilon_B \propto m/e$. In previous Hamiltonian guiding-center models,^{6,12–14} on the other hand, a dimensionless ordering parameter ϵ was introduced either as a mass renormalization $m \rightarrow \epsilon m$ ¹² or as a charge renormalization $e \rightarrow e/\epsilon$,^{6,13,14} so that the dimensional ratio $m/e \rightarrow \epsilon m/e$ is indeed considered small in both cases (i.e., $\epsilon_B \sim \epsilon$). These

renormalization orderings can then form the basis for a well-defined perturbation-expansion analysis of charged-particle motion in a magnetic field by Lie-transform perturbation methods.²

Depending on the renormalization ordering used, we can begin our guiding-center perturbation analysis with the particle Lagrangian, either expressed according to the charge renormalization as

$$L(\mathbf{x}, \mathbf{p}) = \left(\frac{e}{\epsilon c} \mathbf{A} + \mathbf{p} \right) \cdot \dot{\mathbf{x}} - \left(\epsilon^{-1} e \Phi + \frac{|\mathbf{p}|^2}{2m} \right), \quad (2)$$

or, according to the mass renormalization, as

$$L'(\mathbf{x}, \mathbf{p}) = \left(\frac{e}{c} \mathbf{A} + \epsilon \mathbf{p} \right) \cdot \dot{\mathbf{x}} - \left(e \Phi + \epsilon \frac{|\mathbf{p}|^2}{2m} \right), \quad (3)$$

which are simply related as $L(\mathbf{x}, \mathbf{p}) \equiv \epsilon^{-1} L'(\mathbf{x}, \mathbf{p})$. We note that since the time-dependence of the electromagnetic potentials (Φ, \mathbf{A}) is not relevant to our discussion, it will, therefore, be ignored in what follows. In addition, while $\epsilon_B \sim \epsilon$, these dimensionless parameters play very different roles, i.e., the particle Lagrangians (2) and (3) are still meaningful in the case of a uniform magnetic field (where $\epsilon_B = 0$) or time-independent electromagnetic fields. Moreover, the ordering parameter ϵ is the same dimensionless ordering parameter that appears in the dimensionless equation of motion $\epsilon \bar{\mathbf{x}}'' = \bar{\mathbf{x}}' \times \bar{\mathbf{B}}$ initially studied by Kruskal.^{7,9}

As a result of the Lie-transform perturbation analysis, once again based on a definite choice for ϵ (independent of ϵ_B), the guiding-center

Lagrangian can also either be expressed according to the charge-renormalization ordering^{4-6,13,14} as

$$L_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu, \zeta) = \left(\frac{e}{\epsilon c} \mathbf{A} + p_{\parallel} \hat{\mathbf{b}} \right) \cdot \dot{\mathbf{X}} - H_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu) + \epsilon (mc/e) \mu (\dot{\zeta} - \mathcal{R}^* \cdot \dot{\mathbf{X}}), \quad (4)$$

where the explicit expression for the guiding-center Hamiltonian H_{gc} is not important in what follows, or, according to the mass-renormalization ordering,¹² as

$$L'_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu, \zeta) = \left(\frac{e}{c} \mathbf{A} + \epsilon p_{\parallel} \hat{\mathbf{b}} \right) \cdot \dot{\mathbf{X}} - \epsilon H_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu) + \epsilon^2 (mc/e) \mu (\dot{\zeta} - \mathcal{R}^* \cdot \dot{\mathbf{X}}), \quad (5)$$

where $L_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu, \zeta) \equiv \epsilon^{-1} L'_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu, \zeta)$. In both cases, the guiding-center Lagrangian is independent of the gyroangle ζ (up to a specified truncated order in ϵ), and, according to Noether's theorem,¹⁵ the canonically conjugate gyroaction $\partial L_{\text{gc}}/\partial \dot{\zeta} = \epsilon (mc/e) \mu$ is a guiding-center invariant (up to that specified truncated order). Once an ordering choice is made (i.e., using either the renormalizations e/ϵ or e/m), the ϵ -expansion of the guiding-center Lagrangian has to be consistent with this choice. We note that, with the choice $e = m = c = 1$ used by Littlejohn,⁴ the guiding-center Lagrangian (4) corresponds exactly to Eq. (29) obtained by Littlejohn⁸ by Lie-transform perturbation method, with the substitution $\Phi \rightarrow \epsilon \Phi$.

In the guiding-center Lagrangians (4) and (5), the higher-order correction $-(mc/e) \mu \mathcal{R}^* \cdot \dot{\mathbf{X}}$ involves the vector field,^{13,14}

$$\mathcal{R}^* \equiv \mathcal{R} + \frac{1}{2} \nabla \times \hat{\mathbf{b}}, \quad (6)$$

which includes the gyrogauge vector field $\mathcal{R} \equiv \nabla \hat{\mathbf{e}}_1 \cdot \hat{\mathbf{e}}_2$ ^{3,4} that is defined in terms of the local fixed unit-vector basis ($\hat{\mathbf{e}}_1, \hat{\mathbf{e}}_2, \hat{\mathbf{b}} \equiv \hat{\mathbf{e}}_1 \times \hat{\mathbf{e}}_2$), as well as the term $\frac{1}{2} \nabla \times \hat{\mathbf{b}}$ that modifies the standard correction $\frac{1}{2} (\hat{\mathbf{b}} \cdot \nabla \times \hat{\mathbf{b}}) \hat{\mathbf{b}}$ ⁵ in order to take into account guiding-center polarization.¹³ While this higher-order correction is absent from Zheng's work,¹ the gyrogauge vector field \mathcal{R} is needed in the guiding-center Lagrangians (4) and (5) in order to ensure the gyrogauge invariance of the guiding-center equations of motion³⁻⁵ (i.e., the guiding-center Lagrangian dynamics should not only be independent of the gyroangle ζ , but it should also be independent of how the gyroangle is measured in terms of the local perpendicular unit vectors $\hat{\mathbf{e}}_1$ and $\hat{\mathbf{e}}_2$). Hence, a proper guiding-center Lagrangian must, at least, include the combination $\dot{\zeta} - \mathcal{R} \cdot \dot{\mathbf{X}}$, which is gyrogauge-invariant⁴ under the transformation $\zeta \rightarrow \zeta + \psi(\mathbf{X})$, where $\psi(\mathbf{X})$ denotes a locally defined gyrogauge angle, with $\mathcal{R} \rightarrow \mathcal{R} + \nabla \psi$ and $\dot{\zeta} \rightarrow \dot{\zeta} + \dot{\mathbf{X}} \cdot \nabla \psi$. The case for time-dependent fields is further discussed in Refs. 3 and 16, while the importance of the vector field (6) in establishing the faithfulness of the guiding-center representation of particle orbits in nonuniform magnetic fields was recently demonstrated for the case of axisymmetric magnetic geometries.¹⁴

In his critique of standard Lie-transform perturbation analysis, and without explicitly displaying the dimensionless ordering parameter ϵ upon which it is to be based, Zheng¹ mistakenly proceeds to compare the guiding-center Lagrangians (4) and (5), derived with different renormalization orderings, and concludes that, when the guiding-center Lagrangian (5) is truncated at first order, the term $\epsilon^2 (mc/e) \mu \dot{\zeta}$

disappears, while the term $\epsilon (mc/e) \mu \dot{\zeta}$ remains in the guiding-center Lagrangian (4), although it is still a second-order term compared to the lowest order term appearing at ϵ^{-1} . However, Zheng seems to be unaware that the guiding-center Lagrangian (4), which was derived without Lie-transform perturbation method by Cary and Brizard⁶ in what Zheng calls the direct method, was also derived by Lie-transform perturbation method by Littlejohn,⁴ Brizard,⁵ and Tronko and Brizard.¹³

More importantly, Zheng argues that, in contrast to the ϵ -ordering scalings displayed in the guiding-center Lagrangians (4) and (5), the terms $p_{\parallel} \hat{\mathbf{b}} \cdot \dot{\mathbf{X}}$ and $(mc/e) \mu \dot{\zeta}$ must appear at the same order in a modified guiding-center perturbation expansion, which leads him to construct a completely unnecessary (and nonsensical) modification of Lie-transform perturbation theory. However, this modified ordering is clearly inconsistent with the property of gyrogauge invariance based on the following argument. First, by momentarily hiding the ϵ -ordering scalings in Eqs. (4) and (5), the guiding-center Lagrangian can be written as

$$L_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu, \zeta) = \left[\frac{e}{c} \mathbf{A} + p_{\parallel} \hat{\mathbf{b}} - (mc/e) \mu \mathcal{R}^* \right] \cdot \dot{\mathbf{X}} + (mc/e) \mu \dot{\zeta} - H_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu), \quad (7)$$

where we have combined the gyrogauge-correction term $-(mc/e) \mu \mathcal{R}^*$, omitted in Zheng's work,¹ with the spatial components $(e/c) \mathbf{A} + p_{\parallel} \hat{\mathbf{b}}$. Here, we clearly see that these spatial components satisfy the following ordering $\epsilon^{-1} \gg 1 \gg \epsilon$.¹⁷ Hence, after restoring the ϵ -ordering scalings of the spatial components in Eq. (7), we obtain

$$L_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu, \zeta) = \left[\frac{e}{\epsilon c} \mathbf{A} + p_{\parallel} \hat{\mathbf{b}} - \epsilon (mc/e) \mu \mathcal{R}^* \right] \cdot \dot{\mathbf{X}} + \delta (mc/e) \mu \dot{\zeta} - H_{\text{gc}}(\mathbf{X}, p_{\parallel}, \mu), \quad (8)$$

where we have also introduced a dimensionless ordering parameter δ for the gyromotion term $(mc/e) \mu \dot{\zeta}$. Next, we note that the guiding-center Lagrangian (8) now contains the gyrogauge combination

$$(mc/e) \mu (\delta \dot{\zeta} - \epsilon \mathcal{R} \cdot \dot{\mathbf{X}}),$$

which is gyrogauge invariant only if $\delta = \epsilon$ (and not $\delta = 1$ as proposed by Zheng¹), i.e., the term $(mc/e) \mu \dot{\zeta}$ must appear at one order higher than $p_{\parallel} \hat{\mathbf{b}} \cdot \dot{\mathbf{X}}$ in a perturbation expansion leading to a gyrogauge-invariant guiding-center Lagrangian theory, based on either Eq. (4) or Eq. (5). The ordering $\delta = \epsilon$ in Eq. (8) is, therefore, entirely consistent with the renormalization $m/e \rightarrow \epsilon m/e$ of the mass-to-charge ratio used (either implicitly^{4,5} or explicitly^{6,13}) in previous works as the consistent basis for applications of the standard Lie-transform perturbation analysis.

In conclusion, the standard Lie-transform perturbation method² does not need to be modified in its applications to guiding-center theory^{4,6} and, fortunately, the modified Lie-transform perturbation method proposed by Zheng¹ will not be needed in deriving a modified nonlinear gyrokinetic theory.¹⁸ The paper by Zheng¹ reminds us that perturbation theory relies on a well-defined dimensionless ordering parameter $\epsilon \ll 1$, followed by a rigorous algorithm (e.g., Lie-transform perturbation theory) that allows terms to be computed at arbitrary order.

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AUTHOR DECLARATIONS

Conflict of Interest

The author has no conflicts to disclose.

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- ¹⁷In general magnetic geometry, the unit vector $\hat{b} \equiv \partial \mathbf{x} / \partial s$ is defined as the rate of change of the position \mathbf{x} of a point as it moves along a magnetic-field line (where the spatial coordinate s measures distance along that line). Using the Frenet–Serret formulas,¹⁵ with $\hat{e}_1 = \kappa^{-1} \partial \hat{b} / \partial s$ (where κ denotes the Frenet–Serret curvature) and $\hat{e}_2 = \kappa^{-1} \hat{b} \times \partial \hat{b} / \partial s$, we find $\hat{b} \cdot \mathcal{R} = \kappa^{-2} (\hat{b} \times \partial \hat{b} / \partial s) \cdot \partial^2 \hat{b} / \partial s^2 \equiv \tau$, expressed in terms of the Frenet–Serret torsion τ (with units of m^{-1}). Hence, in Eq. (7), the guiding-center parallel momentum $p_{||}$ can be compared with $(mc/e)\mu \hat{b} \cdot \mathcal{R} = (\frac{1}{2}\rho_{\perp}\tau) p_{\perp}$, where we used $(mc/e)\mu \simeq \frac{1}{2} p_{\perp} \rho_{\perp}$ at the lowest guiding-center order. Assuming that the guiding-center spatial ordering (1) holds, so that $\frac{1}{2}\rho_{\perp}|\tau| \ll 1$, we then find that $(mc/e)\mu |\hat{b} \cdot \mathcal{R}| \ll |p_{||}|$, if $|p_{||}| \sim p_{\perp}$ (i.e., away from possible turning points) as is assumed by Zheng.¹ For example, in simple axisymmetric tokamak geometry,¹⁴ we find $|\hat{b} \cdot \mathcal{R}| \simeq 1/qR_0$, where q denotes the safety factor, and R_0 denotes the major radius of the magnetic axis measured from the vertical z -axis.
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