

## **Board 382: RHLab RELIA: A Remote Integrated Environment for Embedded Computing and RF Communication Systems**

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# **RHLab RELIA: An Integrated Remote Environment for Embedded Computing and RF Communication Systems**

## **Abstract**

The development of technologies designed for the virtualization of signal and information processing experimentation has been persistently constrained by cost-associated hardware limitations, the inability to scale for larger audiences, and the lack of a flexible framework which supports user-specific interaction. Given recent advances in cloud computing, we introduce an adaptable, open-source system harnessing field-programmable gate array (FPGA) and software-defined radio (SDR) platforms to streamline the process of analyzing communication patterns between various individual transmitter-receiver pairs. A real-time user environment designed to complement the GNU Radio toolkit is demonstrated with minimal signal interference, enabling remotely-controlled, real information transfer. User-defined configuration files are processed through various Firejail-secured runner engines and dynamically visualized with adjustable feedback and interaction. By integrating novel images into the ADALM-PLUTO vanilla architecture, improved processed signal resolution was accomplished, with additional potential for ARM processor or FPGA reprogramming.

The findings of this paper are targeted towards individuals of all communities, including those with insufficient access to requisite hardware. To remedy such issues, the integrated environment has been adopted and is currently accessible through LabsLand, a partner in this research, and its network of affiliated universities and institutions. Individual contributions to the constructed system are highly distributable by courtesy of the modular nature of the provided framework, encouraging collaboration and sharing of physical resources. Existing functionalities of LabsLand, including learning management systems, are anticipated to further contribute towards the fostering of a complete, visual environment for users, replicating the actual experience of end users in standard, on-site hardware experimentation without associated localized issues.

## **Introduction**

Numerous lessons learned amidst the COVID-19 crisis have pushed engineers, educators, and other professionals to rethink lab work approaches post-pandemic era. Offering an equivalent to hands-on engineering labs virtually presented itself as a particular challenge during the emergency transition to work-from-home (WFH) and remote learning. This necessitated innovative strategies to create lab-based solutions efficiently and conveniently for all individuals, irrespective of geographic location. One such strategy involved the implementation of remote hardware systems for forming full-fledged remote lab experiences without compromising on

positive aspects of physical hardware experimentation. While the implemented systems may have appeared temporary in nature, and were often inadequate in scale, construction, and integration, the potential effectiveness of using such technologies to replicate, and improve, testing and learning experiences for individuals was noticeable. Such experiences have inspired this work which seeks to design and distribute a new generation of environments offering an open-access solution to costly hardware platforms unobtainable to many under-served communities and institutions with limited resources. This project builds on the success of previously implemented remotely-accessible FPGA systems by expanding scope and incorporating hardware which integrates FPGAs and software-defined radios (SDRs), together with new software enablers, for interdisciplinary projects in scientific and engineering disciplines. The proposed toolkit is replicable across institutions and provides access to industry-grade hardware for all communities. While individual institutions may use this open-source toolkit to create a remote lab for their own purposes, our sustainability plan, in coordination with LabsLand, proposes a scalable solution allowing users to connect individual contributions together in order to decrease equipment purchase costs and cultivate further inter-institutional collaboration by sharing both physical resources and user-generated content.

In this paper, we share our approach in implementing an open-source, integrated remote environment for software defined radio applications using ADALM-PLUTO. In this system, individuals using GNU Radio may design a complete flow from one device emitting a particular signal to another device receiving that signal with a different, separate GNU Radio configured process. By adopting this technology, individuals will be able to analyze real radio waves without encountering small-scale device issues.

## **Related Work**

### *GNU Radio*

GNU Radio is a GPL-licensed, Linux-supporting software framework recognized for its low-level customizability. Signal and information processing units are arranged block-wise in C++, with each block corresponding to various sources/sinks (e.g. signal and noise generation, UDP and USRP I/O, file read/write, oscilloscope visualization, etc.) or operations (e.g. modulation/demodulation, interpolation, FFT, filtering, delays, gain control, etc.). Transceiver outputs are graphed for ease-of-use, although the process of tuning such outputs is arduous, due to the irreproducibility of precise hardware tx/rx chains [1]. The system defined and discussed in this paper aims to address this issue via an interactive user environment which enables end users to tune results in real-time and with sufficient specificity.

### *Software defined radio (SDR) architectures*

Since the release of Universal Software Radio Peripheral (USRP) in 2003 [2], Software Defined Radio (SDR) has gained significant traction for its versatility in the construction of high-quality communication prototypes. The ability to manage signal processing through FPGAs and other programmable devices, and the subsequent ability "to turn hardware problems into software problems" [3] is a feature which has ensured continual growth in the field, from both developers and end users alike.

ADALM-PLUTO, or PlutoSDR, (as visualized in Figure 1) is one instance of an SDR module developed by Analog Devices, Inc. to help individuals self-learn wireless communication, software-defined radio (SDR), and radio frequency (RF) [4]. This module was selected for the design due to its reliability [5], cost-effectiveness, USB connectivity, high signal-to-noise (SNR) ratio, and full-duplex architecture. Additionally, the ADALM-PLUTO supports a wide range of tools (e.g. Matlab and GNU Radio). Its 12-bit ADC (analog-to-digital converter) and DAC (digital-to-analog converter) provide sufficient signal resolution for most experimentation expected for the design. A Raspberry Pi may be incorporated to control ADALM-PLUTO over high-speed data transfer.

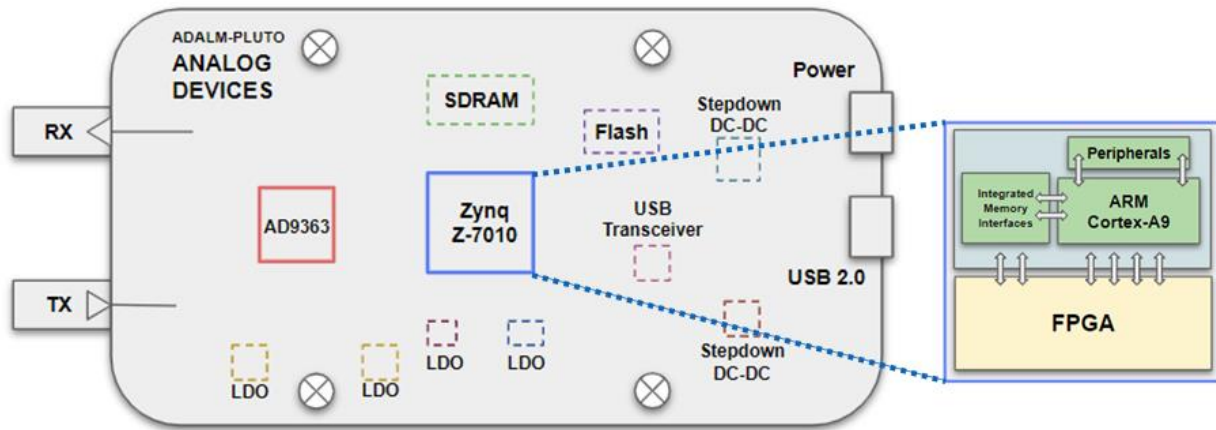


Figure 1: Simplified schematic of the internal structure of an ADALM-PLUTO module

### *Integrated Remote Environments*

Previous publications have attempted to integrate SDR architectures into environments which enable remote hardware access. Xu et al. propose a communications-oriented environment requiring prior allocation of resources through a reservation system (reducing real-time applicability and scalability) and MATLAB. As noted by the authors, if an allocated resource were to behave unresponsively, a user must request a re-allocation of the previously assigned resources [6]. We instead propose a design which enables users to process tasks on any of a wide range of available devices and handles such failures through automatic time-outs, improving scalability and efficiency.

Mikroyannidis et al.'s FORGE design incorporates open-source GNU Radio, rather than MATLAB, as a framework [7]; however, they introduce virtual machines to run SDR, raising potential questions relating to scalability and security, and require a calendar-based system for the allocation of resources. Somashekar et al. similarly use GNU Radio, but on a more limited scope [8]. Somanaidu et al. also suggest an integrated SDR environment without a custom interface for analyzing frequency modulation (FM) signals using the USRP 2901 platform [9], a solution which does not consider scalability and is relatively less cost-effective than our suggested platform.

## Methods

### Hardware

To enable the delivery of higher resolution processed signals (rather than raw data, which is limited by transmission rate) to hosts, as well as permit reprogramming of the ARM processor and FPGA, customized Buildroot-based images were developed. BR2\_EXTERNAL was selected for this purpose, as the manufacturer buildroot system is not actively maintained [10]. The ADALM-PLUTO firmware was also modified to further expand the existing frequency range, with new frequencies ranging from 70 MHz to 6 GHz. To address prior issues of scalability, as shown in Figure 2, all ADALM-PLUTOs are connected to a router via Ethernet, ensuring individual device access by IP address (in lieu of USB cable). This greatly reduces wiring between Raspberry Pis and ADALM-PLUTOs and expands the spatial scope at which Raspberry Pis and ADALM-PLUTOs may exchange information (providing the added benefit of improved long-term maintenance and reduced signal interference by selective placement).

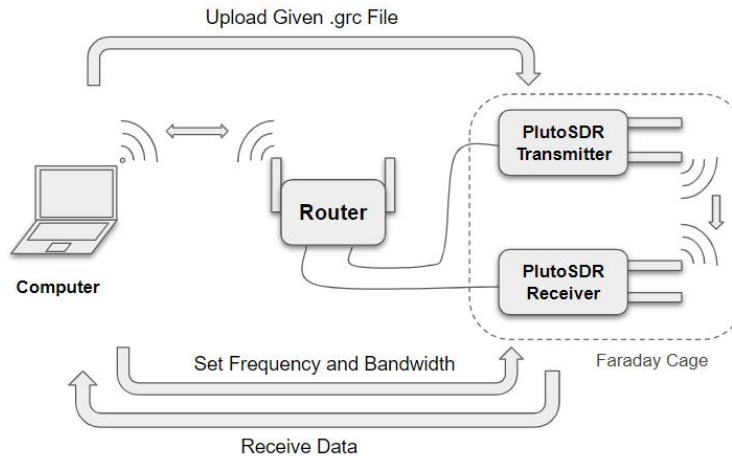


Figure 2: Dual ADALM-PLUTO setup for transmitting and receiving signals

### Software

The software is composed of a central server handling the user interface (UI), scheduling, and data exchange, with authentication handled externally by weblablib [11]. A properly credentialed user may add a pair of receiver and transmitter GNU radio configuration (GRC) files to a Redis memory database (ideal for scaling and streaming large quantities of data), observe file progress (i.e. whether a file is queued, being processed, completed, etc.), or delete a pair of files when applicable. When a receiver (dubbed the “leading device”) is available, the scheduler identifies a receiver GRC file sent by the user based on priority and assigns it to the device. When a transmitter (dubbed the “lagging” device) is available, the scheduler assigns a configuration to it if and only if the leading device has either finished processing the associated receiver file or is actively processing the file. At assignment time, a GRC file is loaded onto a corresponding Raspberry Pi and QT components embedded within each file’s flowgraph are converted into individually-designed blocks before compilation (courtesy of GNU Radio Companion Compiler, or GRCC). Firejail sandboxing is utilized to prevent the execution of malicious contents, or

contents which attempt to access restricted space. A thread responsible for checking file progress interrupts the process if a user requests file deletion or if execution is exceedingly time-exhaustive, ensuring optimal allocation of resources.

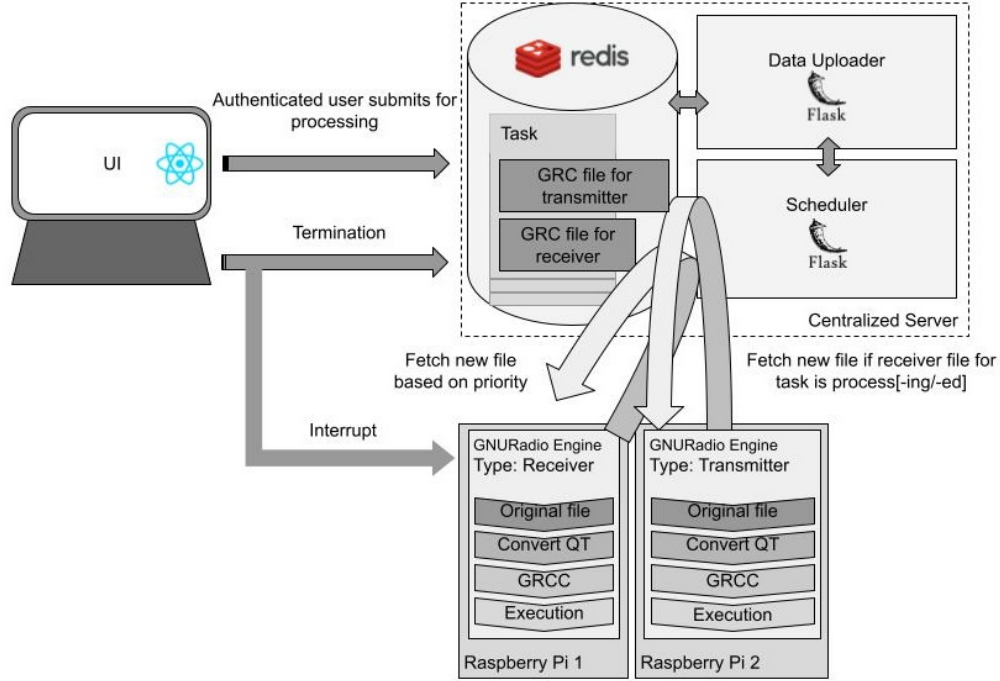


Figure 3: High-level software implementation schematic

## Results

### Hardware

A highly modular system comprised of multiple separate components (each consisting of a Raspberry Pi 4 Model B and ADALM-PLUTO) and a centralized server was developed. SDR libraries provided by the GNU Radio package enable the controlled timing of data acquisition and transmission for each ADALM-PLUTO through HTTP and web sockets. Specifications for the Raspberry Pi and ADALM-PLUTO are included in Table 1 of this paper.

### Software

Interactivity, and the ability of an end user to adjust features dynamically, are crucial towards realizing a full environment for individuals utilizing the system. Users may control parameters in real-time (e.g. amplitude, frequency, power, sampling rate, offset) and customize the handling of incoming data (e.g. arrangement, zoom, pausing, averaging, noise) on a graphical user interface (GUI) associated with the GNU Radio signal processing framework. The GUI is flexible in incorporation and may be integrated into additional SDR hardware devices besides ADALM-PLUTO, as well as any browser.

The link to the associated GitLab repository for this paper is here:

<https://gitlab.com/relia-project/>.

Table 1: Raspberry Pi 4 & ADALM-PLUTO specifications

Specification	Description
Connectivity	USB 2.0
Maximum data rate	480 Mbps
Bandwidth range	200KHz - 20 MHz
Number of channels	2 (1 Tx - 1 Rx)
Type of Antenna	JCG401 - omnidirectional
Processor resolution	64-bits
Operative System	Linux
Programming Language	Python
GRC version	3.10

## Discussion

### *Signal Interference*

Signal interference among multiple ADALM-PLUTO modules was minimized through isolation in nickel and copper sheets, acting as a form of a Faraday cage. Packet Reception Ratio (PRR) for the transmission of 100K sequential ASCII characters under binary phase-shift keying (BPSK) modulation was measured and determined to be approximately 99% at distances of both 10 centimeters and 1 meter, implying minimal signal interference [12] [13].

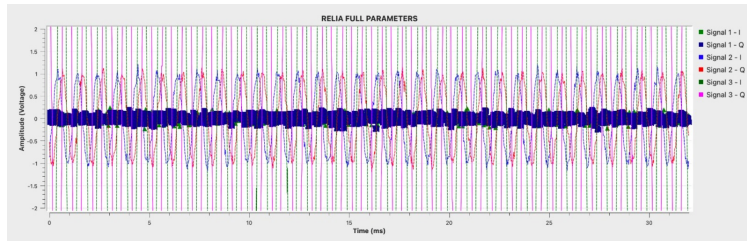
### *Graphical User Interface*

Our UI and GRC (GNU Radio Companion) are both visual interfaces for GNU Radio projects; both take user input from a YAML file containing all parameters and use Python libraries to read configuration files, as well as GNU Radio libraries to canalize and process the streaming data. Differences lie in the visualization framework; while our UI is based on Google Charts Gallery for creating independent interactive data in web browsers, GRC is a graphical interface for GNU Radio, which is a software-defined radio (SDR) toolkit.

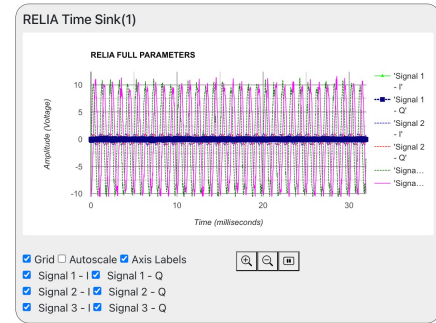
Examples of tools available to users on the GUI are shown in Figure 4. A comparison of multichannel data from different domains: time, frequency, and scatter (constellation), is plotted. Both provide the user the same functionalities (pause, on/off, autoscale, grid on/off, etc.). However, the design of the system's independent windows allow users to monitor and control the streaming data seamlessly, as all controls from a plot are inside every window. It should be noted that, in contrast to GRC, multiple tool windows are available to a given user at a single time, allowing an individual to analyze multiple features of submitted data simultaneously.

As previously noted in the Related Work section of this paper, if a resource were to behave unresponsively, the system scheduler would purge the task on the resource, providing an error message for user guidance (alongside additional messages if a GRC file were to fail at compile-time, runtime, etc.) and enabling re-submission to an alternate resource.

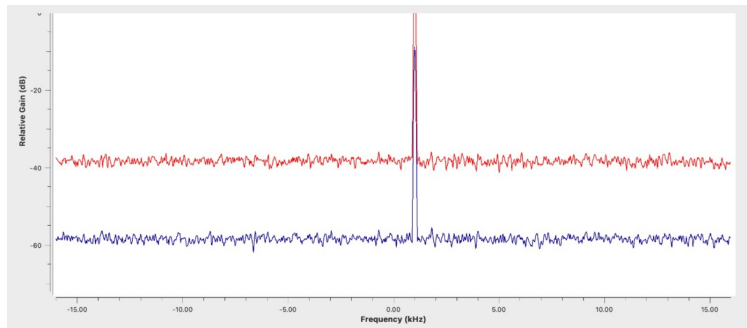




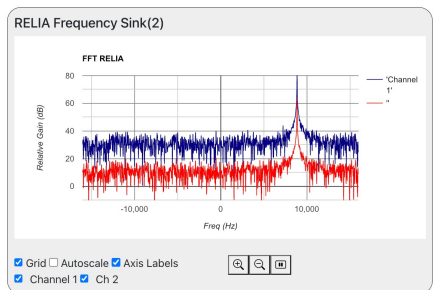
(a) Three-channel time sink I/Q data - GRC



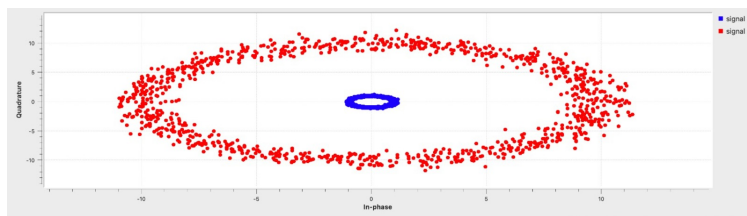
(b) Three-channel time sink I/Q data - Our system



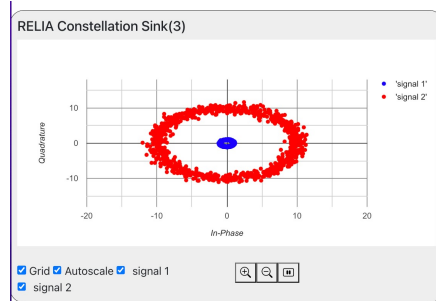
(c) Two-channel frequency sink I/Q data - GRC



(d) Two-channel frequency sink I/Q data - Our system



(e) Two-channel constellation sink I/Q Data - GRC



(f) Two-channel constellation sink I/Q Data - Our system

Figure 4: GRC (left) vs. Our system (right) GUI comparison

### Digital Design Extensions

The system may be applied towards digital design (in addition to communication and signal processing) by harnessing remote access of the FPGA or ARM cores which control a SDR device (e.g. ADALM-PLUTO). Initial configuration tests on ADALM-PLUTO by BR2\_EXTERNAL suggest that reprogramming of the Zynq platform for this end purpose is feasible.



## Conclusion

This paper discusses the construction and implementation of a fully-integrated environment for the remote analysis of signal patterns. Through the incorporation of flexible and scalable features, our real-time system is demonstrated to be practical for larger audiences needing to replicate in-person hardware experimentation virtually. The environment achieves improved signal resolution and is resistant towards external interference, ensuring necessary robustness for real-life use.

The system outlined in this paper is presently available via LabsLand, a partner in this research. The remote laboratories at our research group have been used, through the LabsLand<sup>1</sup> network[14], by 3,700 students from 16 countries over more than 100,000 past laboratory sessions. Learning management systems (e.g. Canvas, Moodle, Sakai, etc.) are integrated and expected to further encourage the use of our system by individuals globally.

## Acknowledgements

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