

## Diameter and displacement of sphere involutions

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**Abstract.** We show that spheres in all dimensions  $\geq 3$  can be deformed to have diameter larger than the distance between any pair of antipodal points. This answers a question of Yurii Nikonorov.

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### 1 Introduction

The diameter  $\text{diam}(M, d)$  of a compact length space is the maximal distance between pairs of points in  $(M, d)$ ; if  $M$  is a manifold and  $d = d_g$  is induced by a Riemannian metric  $g$ , we write  $\text{diam}(M, g) = \text{diam}(M, d_g)$ . For example, the round  $n$ -sphere of radius  $r$  has  $\text{diam}(\mathbb{S}^n(r)) = \pi r$ . Nikonorov [Ni01] proved the following:

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**Theorem 1.1** (Nikonorov). *If  $(M, d)$  is a length space homeomorphic to the sphere  $\mathbb{S}^2$  and  $I: M \rightarrow M$  is an isometric involution without fixed points, then there exists  $x \in M$  such that  $\text{diam}(M, d) = d(x, I(x))$ .*

The above naturally leads to the following question [Ni01]:

**Question 1** (Nikonorov). *Is there an analogue of Theorem 1.1 for length spaces homeomorphic to the sphere  $\mathbb{S}^n$  for some  $n \geq 3$ ?*

Podobryaev [Po18b] observed that sufficiently collapsed Berger spheres provide a negative answer in dimension  $n = 3$ . In fact, this observation can be easily extended to all *odd* dimensions  $n \geq 3$ , considering the (homogeneous) spheres  $(\mathbb{S}^{2q+1}, g(t))$  obtained scaling the unit round sphere by  $t > 0$  in the vertical direction of the Hopf bundle  $\mathbb{S}^1 \rightarrow \mathbb{S}^{2q+1} \rightarrow \mathbb{C}P^q$ . For all  $t > 0$ , the projection onto  $\mathbb{C}P^q$  remains a Riemannian submersion, hence  $\text{diam}(\mathbb{S}^{2q+1}, g(t)) \geq \text{diam}(\mathbb{C}P^q) = \frac{\pi}{2}$ . Meanwhile, pairs of antipodal points  $x$  and  $I(x) = -x$  on  $(\mathbb{S}^{2q+1}, g(t))$  are also antipodal points on the totally geodesic fiber  $\mathbb{S}^1(t)$ , and thus  $d_{g(t)}(x, I(x)) \leq \pi t$ . Therefore,  $d_{g(t)}(x, I(x)) < \text{diam}(\mathbb{S}^{2q+1}, g(t))$  for all  $t < \frac{1}{2}$ . The latter actually holds for all  $t < \frac{1}{\sqrt{2}}$  due to the explicit computation (3.1) of  $\text{diam}(\mathbb{S}^{2q+1}, g(t))$  by Rakotoniaina [Ra85], recently rediscovered (in dimension 3) by Podobryaev [Po18a].

In this short note, we provide negative answers in *all* dimensions  $n \geq 3$ .

Our first construction involves the *spherical join*  $\mathbb{S}^k(r) * \mathbb{S}^{n-k-1}(r)$ ,  $1 \leq k \leq n-2$ , of spheres of radius  $0 < r < \frac{1}{2}$ , which is a length space (in fact, an Alexandrov space) with diameter  $\frac{\pi}{2}$  and which is homeomorphic to  $\mathbb{S}^n$ , see [GP93, p. 582] or [BH99, p. 63] for details and definitions. Every point in  $\mathbb{S}^k(r) * \mathbb{S}^{n-k-1}(r) \setminus (\mathbb{S}^k(r) \cup \mathbb{S}^{n-k-1}(r))$  can be identified via coordinates  $(x, \rho, y)$ , where  $x \in \mathbb{S}^k(r)$ ,  $y \in \mathbb{S}^{n-k-1}(r)$ , and  $\rho \in (0, \frac{\pi}{2})$ . There is a natural isometric action of  $\text{SO}(k+1) \times \text{SO}(n-k)$  given by  $(A, B) \cdot (x, \rho, y) = (Ax, \rho, By)$ , whose orbits have diameter  $\pi r < \frac{\pi}{2}$ , since

(see, e.g., [BH99, p. 63]),

$$\begin{aligned} d_{\text{join}}^{\text{sph}}((x_1, \rho, y_1), (x_2, \rho, y_2)) &= \arccos(\cos^2 \rho \cos(d(x_1, x_2)) \\ &\quad + \sin^2 \rho \cos(d(y_1, y_2))), \end{aligned}$$

which is bounded from above by  $\max\{d(x_1, x_2), d(y_1, y_2)\} \leq \pi r$ , where  $d$  is used for distances in  $\mathbb{S}^k(r)$  and  $\mathbb{S}^{n-k-1}(r)$ . The involution  $I(x, \rho, y) = (-x, \rho, -y)$  induced by the antipodal maps of each sphere is an isometry without fixed points, and corresponds to the antipodal map of  $\mathbb{S}^n$  under the above homeomorphism. Since  $I$  commutes with the  $\text{SO}(k+1) \times \text{SO}(n-k)$ -action, it leaves invariant each orbit, and thus its maximal displacement is  $\pi r < \frac{\pi}{2}$ . Therefore,  $\mathbb{S}^k(r) * \mathbb{S}^{n-k-1}(r)$ , with  $1 \leq k \leq n-2$  and  $0 < r < \frac{1}{2}$ , yields a negative answer to Question 1 for all  $n \geq 3$ .

The spherical join  $\mathbb{S}^k(r) * \mathbb{S}^{n-k-1}(r)$  is a smooth Riemannian manifold if and only if  $r = 1$ , in which case it is isometric to  $\mathbb{S}^n(1)$ . However, inspired by this construction, we can also produce *smooth* counter-examples to Question 1, as follows:

**THEOREM.** For all  $n \geq 3$ , there is a family of smooth Riemannian metrics  $(g_s)_{s \geq 0}$  on  $\mathbb{S}^n$ , such that  $g_0$  is the unit round metric,  $\text{diam}(\mathbb{S}^n, g_s) \geq \frac{\pi}{2}$ , and the antipodal map  $I(x) = -x$  is an isometry of  $(\mathbb{S}^n, g_s)$  satisfying  $d_{g_s}(x, I(x)) \leq \frac{\pi}{\sqrt{1+\frac{s}{2}}}$  for all  $x \in \mathbb{S}^n$ .

Clearly, for  $s > 6$ , the spheres  $(\mathbb{S}^n, g_s)$  provide a negative answer to Question 1 in all dimensions  $n \geq 3$ . These spheres are Cheeger deformations of  $\mathbb{S}^n(1) \subset \mathbb{R}^{n+1}$  with respect to the block diagonal subgroup of isometries  $\text{SO}(k+1) \times \text{SO}(n-k)$  in  $\text{SO}(n+1)$ , with  $1 \leq k \leq n-2$ . In particular, they are cohomogeneity one manifolds with geometric features similar to  $\mathbb{S}^k(r) * \mathbb{S}^{n-k-1}(r)$ ; e.g., both are positively curved and converge in Gromov–Hausdorff sense to  $[0, \frac{\pi}{2}]$  as  $s \nearrow +\infty$ , respectively  $r \searrow 0$ . In fact, the unifying feature of all constructions in this note is that they are spheres with a distance-nonincreasing map onto  $[0, \frac{\pi}{2}]$  whose fibers are invariant under the antipodal map and can be deformed to have arbitrarily small intrinsic diameter.

## 2 Main construction

Let  $\mathbf{G} = \mathrm{SO}(k+1) \times \mathrm{SO}(n-k) \subset \mathrm{SO}(n+1)$  be the subgroup of block diagonal matrices that act on  $\mathbb{R}^{n+1} = \mathbb{R}^{k+1} \oplus \mathbb{R}^{n-k}$  preserving this orthogonal splitting. Clearly,  $\mathbf{G}$  acts on the unit sphere  $\mathbb{S}^n(1) \subset \mathbb{R}^{n+1}$ , and the unit speed geodesic  $\gamma: [0, \frac{\pi}{2}] \rightarrow \mathbb{S}^n(1)$ , given by  $\gamma(\rho) = \cos \rho e_1 + \sin \rho e_{n+1}$ , where  $\{e_j\}$  is the canonical basis of  $\mathbb{R}^{n+1}$ , meets all  $\mathbf{G}$ -orbits in  $\mathbb{S}^n(1)$  orthogonally. The orbits  $\mathbf{G}(\gamma(0)) \cong \mathbb{S}^k(1) \times \{0\}$  and  $\mathbf{G}(\gamma(\frac{\pi}{2})) \cong \{0\} \times \mathbb{S}^{n-k-1}(1)$  are singular orbits; all the other orbits  $\mathbf{G}(\gamma(\rho)) \cong \mathbb{S}^k(\cos \rho) \times \mathbb{S}^{n-k-1}(\sin \rho)$ ,  $0 < \rho < \frac{\pi}{2}$ , are principal orbits. Using this framework, we may define  $\mathbf{G}$ -invariant metrics on  $\mathbb{S}^n$  by specifying their values on the (open and dense) subset of principal points as the doubly warped product

$$g = d\rho^2 + \varphi(\rho)^2 g_{\mathbb{S}^k} + \psi(\rho)^2 g_{\mathbb{S}^{n-k-1}}, \quad 0 < \rho < \frac{\pi}{2}, \quad (2.1)$$

where  $\varphi$  and  $\psi$  are positive functions satisfying appropriate smoothness conditions at  $\rho = 0$  and  $\rho = \frac{\pi}{2}$ , and  $g_{\mathbb{S}^d}$  is the unit round metric on  $\mathbb{S}^d$ . Cohomogeneity one metrics of the form (2.1) are called *diagonal*. For example, the unit round metric  $g_0 = g_{\mathbb{S}^n}$  is of the above form, with functions  $\varphi_0(\rho) = \cos \rho$  and  $\psi_0(\rho) = \sin \rho$ .

The *Cheeger deformation* of  $g_0$  is the 1-parameter family  $g_s$ ,  $s \geq 0$ , of diagonal cohomogeneity one metrics (2.1) determined by the functions

$$\varphi_s(\rho) = \frac{\cos \rho}{\sqrt{1 + s \cos^2 \rho}} \quad \text{and} \quad \psi_s(\rho) = \frac{\sin \rho}{\sqrt{1 + s \sin^2 \rho}}, \quad (2.2)$$

see [AB15, Ex 6.46]. For all  $s \geq 0$ , the metric  $g_s$  is  $C^\infty$  smooth and  $\mathbf{G}$ -invariant, the orbit space of the  $\mathbf{G}$ -action on  $(\mathbb{S}^n, g_s)$  is  $\mathbb{S}^n/\mathbf{G} = [0, \frac{\pi}{2}]$ , and  $\gamma$  remains a unit speed geodesic orthogonal to all  $\mathbf{G}$ -orbits. As the projection  $\mathbb{S}^n \rightarrow \mathbb{S}^n/\mathbf{G}$  is distance-nonincreasing, we have

$$\mathrm{diam}(\mathbb{S}^n, g_s) \geq \frac{\pi}{2}, \quad \text{for all } s \geq 0. \quad (2.3)$$

Moreover,  $(\mathbb{S}^n, g_s)$  has  $\mathrm{sec} \geq 0$  for all  $s \geq 0$ , and it converges in Gromov–Hausdorff sense to  $\mathbb{S}^n/\mathbf{G} = [0, \frac{\pi}{2}]$  as  $s \nearrow +\infty$ .

The  $\mathsf{G}$ -orbits in  $(\mathbb{S}^n, g)$ , where  $g$  is the cohomogeneity one diagonal metric (2.1), are isometric to the product  $\mathsf{G}(\gamma(\rho)) = \mathbb{S}^k(\varphi(\rho)) \times \mathbb{S}^{n-k-1}(\psi(\rho))$  of round spheres of radii  $\varphi(\rho)$  and  $\psi(\rho)$ . Thus, the distance between any  $x, y \in \mathsf{G}(\gamma(\rho))$  is

$$\begin{aligned} d_g(x, y) &\leq \text{diam}(\mathsf{G}(\gamma(\rho)), g) \\ &= \sqrt{\text{diam}(\mathbb{S}^k(\varphi(\rho)))^2 + \text{diam}(\mathbb{S}^{n-k-1}(\psi(\rho)))^2} = \pi \sqrt{\varphi(\rho)^2 + \psi(\rho)^2}. \end{aligned}$$

Setting  $\varphi$  and  $\psi$  to be the functions in (2.2), one easily checks that the maximum value of the above is achieved at  $\rho = \frac{\pi}{4}$  for all  $s \geq 0$ , and is equal to  $\frac{\pi}{\sqrt{1+\frac{s}{2}}}$ .

The antipodal map  $I: \mathbb{S}^n \rightarrow \mathbb{S}^n$ , which acts as  $I = -\text{Id} \in \text{O}(n+1)$ , commutes with the  $\mathsf{G}$ -action on  $(\mathbb{S}^n, g_s)$ , thus  $I$  leaves invariant all  $\mathsf{G}$ -orbits. In fact,  $I$  restricts to the antipodal map on each sphere factor in  $\mathsf{G}(\gamma(\rho))$ ,  $\rho \in [0, \frac{\pi}{2}]$ . Thus, the displacement of  $I$  on  $(\mathbb{S}^n, g_s)$  satisfies

$$d_{g_s}(x, I(x)) \leq \max_{\rho \in [0, \frac{\pi}{2}]} \text{diam}(\mathsf{G}(\gamma(\rho)), g_s) = \frac{\pi}{\sqrt{1+\frac{s}{2}}}.$$

Together with (2.3), this proves the Theorem in the Introduction.  $\square$

**Remark 2.1.** Not all  $\mathsf{G}$ -invariant metrics on  $\mathbb{S}^n$  are diagonal, i.e., of the form (2.1), if  $n$  is odd. For instance, let  $n = 3$  and  $k = 1$ . For all  $t \neq 1$ , the isometry group of the Berger sphere  $(\mathbb{S}^3, g(t))$  is  $\text{U}(2) \subset \text{SO}(4)$ , which contains  $\mathsf{G} = \text{SO}(2) \times \text{SO}(2)$ , so  $g(t)$  is  $\mathsf{G}$ -invariant. However,  $g(t)$  is not of the form (2.1) if  $t \neq 1$ . Indeed, principal  $\mathsf{G}$ -orbits in  $(\mathbb{S}^3, g(t))$  are isometric to flat 2-tori  $(\mathsf{G}(\gamma(\rho)), g(t)) \cong \mathbb{R}^2/\Gamma_{(\rho, t)}$  and none of the lattices  $\Gamma_{(\rho, t)}$  are rectangular if  $t \neq 1$ . Meanwhile, principal  $\mathsf{G}$ -orbits in  $(\mathbb{S}^3, g)$ , with  $g$  as in (2.1), are rectangular flat tori  $(\mathsf{G}(\gamma(\rho)), g) \cong \mathbb{R}^2/2\pi\varphi(\rho)\mathbb{Z} \oplus 2\pi\psi(\rho)\mathbb{Z}$ .

### 3 Final remarks

#### 3.1 Berger spheres

Let us expand on our discussion of the spheres  $(\mathbb{S}^{2q+1}, g(t))$ , whose Hopf circles are closed geodesics of length  $2\pi t$ . According to [Ra85, Po18a],

$$\text{diam}(\mathbb{S}^{2q+1}, g(t)) = \begin{cases} \frac{\pi}{2\sqrt{1-t^2}}, & \text{if } 0 < t \leq \frac{1}{\sqrt{2}}, \\ \pi t, & \text{if } \frac{1}{\sqrt{2}} < t \leq 1, \\ \pi, & \text{if } 1 < t. \end{cases} \quad (3.1)$$

As pairs of antipodal points  $x$  and  $I(x)$  are joined by half of the Hopf circle to which they belong,  $d_{g(t)}(x, I(x)) \leq \pi t < \text{diam}(\mathbb{S}^{2q+1}, g(t))$  for all  $t < \frac{1}{\sqrt{2}}$ , see Figure 3.1.

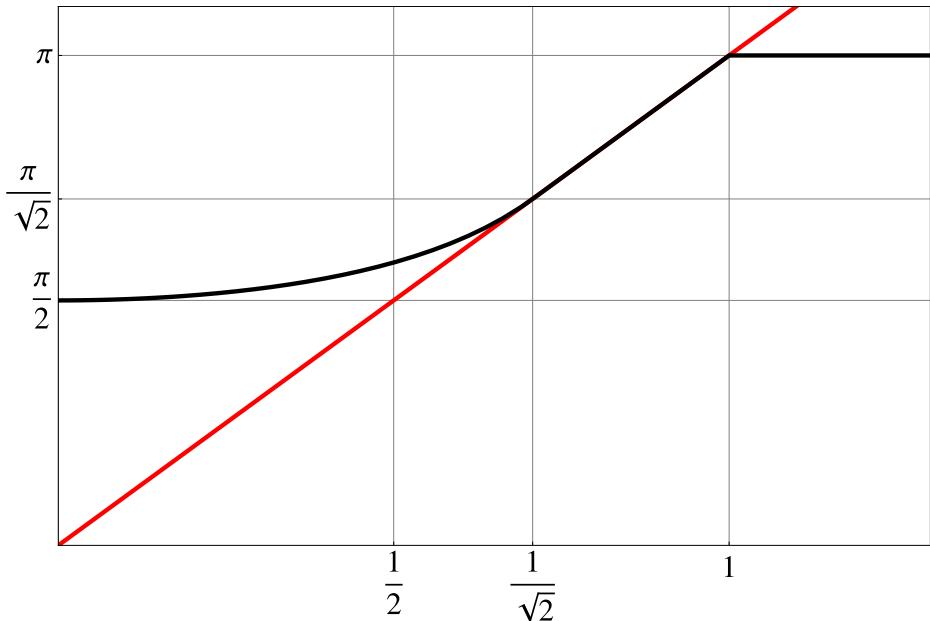


Figure 3.1: Diameter (black) and half length of Hopf circle (red) in  $(\mathbb{S}^{2q+1}, g(t))$ .

A similar situation occurs on the Berger spheres  $(\mathbb{S}^{4q+3}, h(t))$  and  $(\mathbb{S}^{15}, k(t))$  obtained by scaling the unit round sphere by  $t > 0$  in the vertical direction of the Hopf bundles  $\mathbb{S}^3 \rightarrow \mathbb{S}^{4q+3} \rightarrow \mathbb{H}P^q$  and  $\mathbb{S}^7 \rightarrow \mathbb{S}^{15} \rightarrow \mathbb{S}^8(\frac{1}{2})$ , respectively. Namely, for all  $t > 0$ , the projection map of these bundles remains a Riemannian submersion, and thus  $\text{diam}(\mathbb{S}^{4q+3}, h(t)) \geq \text{diam}(\mathbb{H}P^q) = \frac{\pi}{2}$  and  $\text{diam}(\mathbb{S}^{15}, k(t)) \geq \text{diam}(\mathbb{S}^8(\frac{1}{2})) = \frac{\pi}{2}$ . Pairs of antipodal points belong to the same Hopf circle, hence to the same (totally geodesic) fiber, which is isometric to  $\mathbb{S}^3(t)$  or  $\mathbb{S}^7(t)$ , so  $d_{g(t)}(x, I(x)) \leq \pi t$ . Thus, for sufficiently small  $t > 0$ , these spheres also provide a negative answer to Question 1.

### 3.2 First Laplace eigenvalue

Spectral geometry provides an alternative path to show that Berger spheres yield a negative answer to Question 1, by considering

$$g \longmapsto \lambda_1(M, g) \text{ diam}(M, g)^2,$$

where  $\lambda_1(M, g)$  is the smallest positive eigenvalue of the Laplace–Beltrami operator. This scale-invariant functional is bounded from below by  $\frac{\pi^2}{4}$  on compact connected homogeneous spaces [Li80]. Moreover, one has that  $\lambda_1(\mathbb{S}^{2q+1}, g(t)) \leq 4(q+1)$  for all  $t > 0$ , since

$$\lambda_1(\mathbb{S}^{2q+1}, g(t)) = \min \left\{ 4(q+1), 2q + \frac{1}{t^2} \right\} = \begin{cases} 4(q+1), & \text{if } t \leq \frac{1}{\sqrt{2q+4}}, \\ 2q + \frac{1}{t^2}, & \text{if } t \geq \frac{1}{\sqrt{2q+4}}, \end{cases}$$

see [BP13, Prop. 5.3]. Similar upper bounds on  $\lambda_1$  for  $(\mathbb{S}^{4q+3}, h(t))$  and  $(\mathbb{S}^{15}, k(t))$  can be obtained from [BLP22]. This yields a positive diameter lower bound, independent of  $t > 0$ , that could be used in lieu of the exact value (3.1) for  $(\mathbb{S}^{2q+1}, g(t))$  or of the submersion lower bound  $\frac{\pi}{2}$  in general. However, this spectral lower bound on the diameter is weaker than the latter, and becomes arbitrarily small as  $q \nearrow +\infty$ .

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