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Research Article

Global Existence of Weak Solutions for Compresssible Navier{Stokes{Fourier Equations with the Truncated Virial Pressure Law

Didier Bresch¹, Pierre{Emmanuel Jabin^{2*}, Fei Wang³

¹UMR 5127 CNRS, Univ. Savoie Mont Blanc, LAMA, Universite Savoie Mont Blanc, 73376 Le Bourget du Lac, France,

²Department of Mathematics and Huck Institutes, Pennsylvania State University, State College, PA 16801, USA, ³School of Mathematical Sciences, CMA-Shanghai, Shanghai Jiao Tong University, Shanghai 200240, China,

*Email address for correspondence: pejabin@psu.edu

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Abstract

This paper concerns the existence of global weak solutions da Leray for compressible Navier{Stokes{Fourier systems with periodic boundary conditions and the truncated virial pressure law which is assumed to be thermodynamically unstable. More precisely, the main novelty is that the pressure law is not assumed to be monotone with respect to the density. This provides the rst global weak solutions result for the compressible Navier-Stokes-Fourier system with such kind of pressure law which is strongly used as a generalization of the perfect gas law. The paper is based on a new construction of approximate solutions through an iterative scheme and xed point procedure which could be very helpful to design ecient numerical schemes. Note that our method involves the recent paper by the authors published in Nonlinearity (2021) for the compactness of the density when the temperature is given.

Keywords: Compressible Navier-Stokes, Heat-conduction, Truncated Virial pressure law, Non-monotone pressure, Vacuum state, Global weak solutions.

AMS subject classication: 76N10, 35D30, 35Q30, 35Q86

1. Introduction and main result

This paper is dedicated to Antonn Novotnywho had contributed so many innovative work to the theory of compressible uids, specically to compressible Navier-Stokes-Fourier equations, and unfortunately passed away suddenly on Thursday, June 03 2021.

The non-stationary Navier-Stokes-Fourier equations modeling viscous compressible and heat conducting uids, in the multi-dimensional in space case, have been extensively studied both from a theoretical and a numerical point of view: see [10]. Yet many questions around the existence, uniqueness, or stability of solutions have remained unsolved. The case of non-stationary barotropic Navier-Stokes equations (namely without temperature) is somewhat better understood, in particular for the global existence of weak solutions a la Leray ([13]): see for instance [14], [6], [9], [11], [17], [1], [3] and references cited therein. The present study addresses the theoretical problem of existence of so-called global weak solutions ala Leray for the full system including the evolution of internal energy (temperature dependent case) for the so-called virial pressure law.

One of the well-known diculty of such nonlinear system of uid mechanics with heat-conductivity is that the a priori bounds based on the energy estimates are not strong enough to get equi-integrability of certain quantities, such as the viscous dissipation quantity (see for instance [14]). This is compounded in the present paper by a pressure law that is non-monotone in the density and hence thermodynamically unstable.

A rst helpful approach is to replace the internal energy equation by the entropy inequality supplemented by the total energy balance, as introduced by E. Feireisl and A. Novotny, explained in [7], [8] with appropriate hypothesis on the pressure state laws. Unfortunately, this approach was initially limited to thermodynamically stable state laws, namely

$$@Pj_{\#} > 0; @_{\#}ej > 0;$$

where P is the pressure state law and e is the internal energy depending on the density and the temperature #.

On the other hand, the potential oscillations in the density due to the pressure laws can in principle be controlled through the method in [1,3]. But a major diculty further lies in combining both approaches at the level of an approximate system. We take a dierent point of view to bypass most this issue by constructing solutions through a xed point argument.

Dene, in a periodic domain

= T^d for d 2, the so-called truncated virial pressure law

where > max(4; 2N; d). The virial equation of state seems to have been proposed rst by M. Thiesen in 1885 and intensively studied by H. Kammerlingh Onnes (see [16]) at the beginning of the previous century as an empirical extension of the ideal-gas law. The reader interested by Virial coecients of pure gases and mixtures is referred to [5].

Such pressure laws is not monotone with respect to the density even after a xed value and there-fore is not thermodynamically stable. They are nevertheless commonly used in practice. With proper assumptions on the coecients $B_n(\#)$, one can still ensure that $@_\#ej > 0$ so that the system is at least thermodynamically consistent.

We next consider the compressible Navier{Stokes{Fourier (CNSF) equations for the corresponding state laws,

- (2) $@_t + div(u) = 0;$
- (3) $@_t(u) + \operatorname{div}(u)$
- div S + r P = 0;
- (4) $@_t(E) + \operatorname{div}(uE) + \operatorname{div}(Pu) = \operatorname{div}(Su) + \operatorname{div}(r\#)$

where $E = juj^2=2 + e$ is the energy with P = P(; #) and e = e(; #) respectively stand for the pressure and the (specic) internal energy.

The initial condition are given by

(5)
$$j_{t=0} = 0$$
 $(u)j_{t=0} = m_0$ $(E)j_{t=0} = {}_{0}E_0$:

Note that the above initial conditions determine the corresponding value at t = 0 of the temperature $\#_{t=0} = \#_0$, provided that $@_{\#}e > 0$.

For simplicity, we take the isotropic stress tensor

(6)
$$S = (ru + ru^{T}) + div uld$$

with and two constants satisfying the physical constraint > 0 and + 2=d > 0. In order to be consistent with the second principle of Thermodynamics which implies the existence of the entropy as a closed dierential form in the energy balance, the following compatibility condition, called \Maxwell equation" between P and e has to be satised

This allows to dene the internal energy directly from the pressure law, up to a function only of #, which we take as 0 for simplicity. Namely for any arbitrary $_{\rm C} > 0$, and by using (1),

(8)
$$e(;\#) = \sum_{2}^{\infty} \frac{1}{-P}(^{0};\#) \#_{@\#}(^{\mathbb{Q}P}_{7,\#})$$

$$= m + \frac{1}{-1} \sum_{n=0}^{N} \#^{2} \frac{d}{d\#}(B_{n}(\#)) \frac{n}{n-1} \#^{2} \frac{d}{d\#}(B_{1}(\#)) \log + \#^{2} \frac{d}{d\#}(B_{1}(\#)) : \frac{1}{-P}(B_{1}(\#)) = \frac{1}{2} \frac{d}{d\#}(B_{1}(\#)) = \frac{1}{2} \frac{d}{d$$

The specic entropy s = s(; #) is now also dened up to an additive constant by

If (; #) are smooth and bounded from below away from zero and if the velocity eld is smooth, then the total energy balance can formally be replaced by the thermal energy balance

$$C_v(@_t\# + u r\#)$$
 $div((\#)r\#) = S : ru$ $\#\frac{@_{(\#)}}{P_{@\#}}div u$

where S : ru = Tr(Sru).

Furthermore, dividing by #, we arrive at the entropy equation

(10)
$$@_t(s) + div(su)$$
 $div \frac{\# \# = 1}{\#} S : r \frac{u}{\#} + \frac{j r \# j^2}{\#} : \frac{\#}{\#}$

We will use both of the two equations (4) and (10) involving temperature, at dierent parts of our argument, together with a third technical formulation derived from (4).

We emphasize that, a priori, the system (2)-(4) conserves the total mass

Z Z
$$(t;) dx = Z_{0} dx$$
:

The total energy of the system, which is the sum of the kinetic and the potential energies, reads

E(; #; m) =
$$E(; #; u) dx = Z$$

$$jmj^{2} / 2 + e(; #) dx T^{d}$$

and is also conserved, namely,

$$E(; #; m)(t) = E(_0; #_0; m_0);$$

with m = u, where e is obtained from equation (7).

We need several precise assumptions on the various coecients entering into equations (2)-(4) which we now make explicit.

Assumption on the conductivity (#):

(11)
$$_{1}(\#+1)(\#)_{2}(\#+1);$$
 $_{3}\#^{1}_{0}(\#)_{4}\#^{1}$

where $_1$; $_2$ > 0; and 4. Assumptions on the pressure law P.

(1) The pressure P given by (1) contains a radiative part, namely

(12)
$$\mathscr{Q}_{\#}B_0 > 0 \text{ for } \# = 0;$$

(2) For 2 # =2 with some 4

(13)
$$C^{-1}\#^{*-1} B_0(\#) \#^{*-1}; C^{-1}\#^{*-2} B^0(\#) \#^{*-2};$$

(3) We assume

(14)
$$B_1 C_1$$
 for some $C_1 2 R$;

(4) For n 2, the coecients B_n is concave in the sense that

(15)
$$\frac{d}{d\#}(\#^2B_n^0) = 0;$$

(5) We also assume that the following is true for $n \cdot 0$ and n = 1

(16)
$$j\#^{3}B_{n}^{000}(\#)j + j\#^{2}B_{n}^{00}(\#)j + j\#B_{n}^{(}(\#)j + jB_{n}(\#)j C\#^{(n)_{\#}=1}";$$

(6) There exist some constants B_n and $< min(; 2_\#)$,

(17)
$$j\#^2 B_n^0(\#)j + \#jB_n(\#)j + j\#B_n(\#) \quad B_nj \quad C \#^{(2n)=2};$$

- (7) Finally we also assume the following property on the entropy s
 - (18) The specic entropy s is a concave function of (1; e):

Remark 1.1. The above assumption on s ensures that the C_v coecient is non-negative

(19)
$$C_{v} = \frac{@\epsilon}{@\#} = \frac{1}{\#^{2}} \frac{@^{2}}{@e^{2}} 0$$

where the second equality comes from that @s=@e= # 1.

Remark 1.2. Let us comment that the results described for in instance in [8] are based on a radiative part and a cold pressure part. In the truncated pressure law, this corresponds respectively to the terms $\#B_0(\#)$ and .

We emphasize that none of the assumptions above require a sign on $B_n(\#)$, except on B_0 . Hence as claimed, the truncated virial pressure may not be monotone in for some values of # or .

We are now ready to state our main result.

Theorem 1.1. Assume the initial data $\#_0$, m_0 and m_0 0 with $m_{Td}^R = M_0 > 0$ satisfy

$$E(_0; \#_0; m_0) = Z \int_{\mathbb{T}^d} \frac{j m_0 j^2}{2 n} e(_0; \#_0) dx < 1$$

where $m_0 = 0$ when $_0 = 0$. Suppose that the pressure state law P(;#) is given by (1) with the assumptions (12){(17) and assume (18) on the entropy. Then there exists a global weak solution (; u; #) to Compressible Navier{Stokes{Fourier System. More precisely it satises (2){(3) with (6) in the distribution sense, the following entropy inequality

(20)
$$@_t(s) + div(su) div $\frac{\# \# 1}{(r\#)} S : \#u + \frac{(\#)jr\#j^2}{\#}$$$

where s is dened by (9) and the energy inequality

$$Z \underbrace{[uj^2 + e(; \#)(t) dx}_{T^d} Z \qquad \qquad \underbrace{jm_0j^2}_{2 \ 0} + _0e(_0; \#_0)dx: T^d$$

Moreover, we have

u 2
$$L^{2}(0;T;H^{1}(T^{d}));$$
 $jmj^{2}=2$ 2 $L^{1}(0;T;L^{1}(T^{d}))$
u 2 $C([0;T];L^{2=(+2)}(T^{d})$ weak);

for any T > 0, the weak regularity

2
$$C([0;T];L(T^d) \text{ weak }) \setminus L^{+a}((0;T) T^d) \text{ where } 0 < a < 1=d$$
2 $L(0;T;L^{=(1-2=d)}(T^d));$ $log \# 2 L^2(0;T;H^1(T^d));$

and the initial conditions satised by (; u; s) in a weak sense

$$j_{t=0} = 0;$$
 $uj_{t=0} = m_0;$ $sj_{t=0^+} 0s(0; \#_0):$

We remark that we use the notation $2 C([0;T];L(T^d))$ weak to mean that is weakly continuous in time in L: for any $t_n ! t$, we have that $(t_n;:)! (t;:)$ for the weak topology of $L(R^d)$.

Theorem 1.1 is the rst result providing global existence of weak solutions for the heat conducting Navier-Stokes equations with a thermodynamical unstable pressure law depending on the density and the temperature.

The main idea in the proof is to separate the density and momentum equations (2)-(3) from the energy equation (4). For a given #(t;x) satisfying appropriate energy bounds, our assumptions on the pressure law let us use [3] (see also the introductory paper [2]) more or less directly. This article focused on the barotropic system, namely (2)-(3), but with pressure laws that are inhomogeneous in time and space. It is thus a good tool for the task of obtaining existence of and u for a given #.

We also need to obtain existence of some # solving (4) for a given and u, again with appropriate energy bounds. This does not seem to t in any classical framework of non-linear parabolic equations and therefore requires careful approach. We use a dierent formulation, that is loosely based on (4) (and formally equivalent when all quantities are smooth). We also need a proper approximated equation to resolve a potential degeneracy where # is close to 0. This nally allows us to obtain a global, weak solution to our variant formulation to (4). We do not have strong enough bounds to recover (4) rigorously from that but it is enough to obtain an inequality in the entropy formulation (20) together with the opposite inequality in the propagation of the total energy (as can be surmised from the formulation in Theorem 1.1).

The last step in the proof is obviously to conclude the xed point argument, through the Leray-Schauder theorem. This is a rather short but very challenging step. The issue is that we cannot yet recover the usual energy estimate: Before we do obtain a xed point, the piece of the energy that we obtain from the existence on (2)-(3) does not t with the piece of the energy that we obtain from (4). This is where the exact formulation of the Leray-Schauder theorem is critical and must be combined with the precise choice we have made of the decomposition.

2. Previous result concerning the compressible Navier-Stokes-Fourier system.

In every previous work concerning the global existence of weak solutions, the viscous stress tensor is assumed to be isotropic

$$S = (ru + ru^T) + divuld;$$

with coecients; either constant or depending only on #. Concerning the pressure state law, we can cite the two following assumptions:

1) The pressure law as a monotone perturbation of the barotropic case. It is due to E. Feireisl who considered pressure laws under the form

$$P(; \#) = P_c() + \#P_\#();$$

where

(21)
$$P_{c}(0) = 0; \quad P_{c}^{(l)}(0) = a_{1}^{-1} \qquad \text{b for } > 0;$$

$$P_{c}(0) = a_{2} + \text{b for all } 0;$$

$$P_{\#}(0) = 0; \quad P_{\#}^{(l)}(0) = 0;$$

$$C(1 + 1);$$

and

$$> d=2;$$
 $< _{2}$ -for d = 2; = $_{3}$ -for d = 3

with constants $a_1 > 0$, a_2 , b and P_c , $P_\#$ in $C[0; +1) \setminus C^1(0; +1)$. In agreement with Maxwell law and the entropy denition, it implies the following form on the internal energy

$$e(; \#) = {P_c(s) \over s^2} ds + Q(\#);$$

where $Q^0(\#) = C_v(\#)$ (specic heat at constant volume). The entropy is given by

$$s(; \#) = \frac{Z_{\#} C_{V}(s)}{s} ds \quad H_{\#}(); ?$$

where $H_{\#}()$ is the thermal pressure potential given through

$$Z$$
 $H_{\#}() = P_{\#}(s) = s^{2}ds: ?$

The heat conductivity coecient is assumed to satisfy

$$_{1}(# + 1) (#) _{2}(# + 1)$$
 for all # 0;

with constants $_1 > 0$ and $_2$. The thermal energy $Q = Q(\#) = {R \atop 0} C_v(z) dz$ has not yet been determined and is assumed to satisfy ${R \atop z \ge [0;+1)} C_v(z) > 0$ and $C_v(\#) c(1+\#^{=2})$. Because the energy and pressure satisfy

$$\frac{@e(;\#)}{@\#} > 0;$$
 $\frac{@P(;\#)}{@} > 0$

the estimate on $H_\#$ gives a control on in $L^1(0; T; L^1($

-)) and through the entropy equation a control on # in $L^2(0; T; L^6($
-)) in dimension 3 and in L²(0; T; L^p(
-)) for all p < +1 in dimension 2.

Because the entropy estimates does not provide an H_x^1 bound on u, E. Feireis I combines it with a direct energy estimate (see below). Therefore one obtains the exact equivalent of estimates as in the barotropic case

z
$$\sup_{t} \quad juj^{2} dx C + E(0; u_{0}); Z$$

$$\sup_{t} \quad dx C; Z^{t}$$

$$Z$$

$$\int_{T} \quad jruj^{2} dx C: 0$$

in this temperature dependent case. Using such information, he may then prove the extra integrability

for 0 < a < min(1=d; 2d=1). We will give more details later-on for such estimate for the truncated virial pressure law.

2) Self-similar pressure laws with large radiative contribution. It is due to E. Feireisl and A. Novotny who consider pressure laws exhibiting both coercivity of type and #⁴ for large densities and tempera-tures namely

$$P(; \#) = \#^{=(-1)}Q(_{\#^{1}=(-1)}) + _{3}\#^{4} \text{ with } a > 0; > 3=2;$$

with

Q 2
$$C^1([0; +1));$$
 Q(0) = 0; $Q^0(Z) > 0$ for all Z 0;

and

$$\lim_{Z + 1} \frac{Q(Z)}{Z} = Q_1 > 0$$
:

In agreement to Maxwell law and the denition of entropy, it implies the following form on the internal energy and the entropy

$$e(; \#) = \left(\frac{1}{1}\right) \frac{\#^{-(-1)}}{Q(\#^{1-(-1)})} + a ; \#^4$$

and

$$s(; \#) = S_{\#^{1=(-1)}} + \frac{4a \#^3}{3}$$

They impose

$$0 < S^{0}(Z) = \frac{1}{1} \frac{Q(Z)}{7} \frac{Q^{0}()Z}{Z} < c < + 1 \text{ for all } Z > 0;$$

with $\lim_{Z + 1} S(Z) = 0$ so that thermodynamical stability holds. Therefore the energy provides uniform bounds in $L^1_x L^1$ for $\#^4$ and . One assumes in this case that the viscosities and heat conductivity satisfy

; 2 C¹([0; +1)) are Lipschitz with
$$(1 + #) (#)$$
; 0 (#); $_0 > 0$;

and

$$2 C^{1}([0;+1); 0(1+\#^{3}) (\#) _{1}(1+\#^{3}); 0 < _{0 1}$$

Almost everywhere convergence of the temperature is obtained using the radiation term. Extra integrability on P(; #) can be derived just as in the barotropic case. Finally the same procedure as in the barotropic case is followed to have compactness on the density, relying heavily on the monotonicity of the pressure @P(; #) = @ > 0. This gives global existence of weak solutions (in a the same sense that we precise later). Remark the term $a\#^4 = 3$ in the pressure law can help to get compactness in space and time using commutation between strictly convex function and weak convergence.

With respect to these previous works, we focus here, as in the barotropic case, in removing the assumption of monotonicity on the pressure law with respect to the density, considering the truncated virial pressure law on which we do not want to assume too restrictive assumptions, namely, a pressure law (1) with the assumptions (12){(18).

3. The direct entropy estimate

3.1. A formal entropy bound

We explain here the general framework for our result on the Navier{Stokes{Fourier system. The estimates here closely follow the ones pioneered by P.{L. Lions, and E. Feireisl and A. Novotny. With respect to the previous discussion, we only present them here in a more general context as in particular we will not need the monotonicity of P.

If one removes the monotonicity assumption on P then thermodynamic stability does not hold anymore. Following P.{L. Lions, it is however possible to obtain the entropy dissipation estimate directly by integrating the entropy equation

$$Z_{t}Z_{jruj^{2}}$$
 $jruj^{2}$ $+$ $(#)$ $fruj^{2}$ $-dxdt$ dt $dx: 0$ $dx: 0$

Therefore the entropy bound dissipation holds under the general assumption that there exists C s.t.

(23)
$$s(; \#) C e(; \#) + : \frac{C}{}$$

Recall that

$$e = m(\#) + \frac{Z}{(P(0;\#) + (0;\#))} d^{0}$$

and

We also have that $@_{\#}s = @_{\#}e = \#$, therefore as long as m(#) 0 with

$$\int_{0}^{\pi} m^{0}(s) ds C(1 + m(\#));$$

and

$$Z = \frac{Q_{\#}P}{Q_{2}}C + C \qquad P \qquad = \frac{\#@_{\#}P}{Q_{2}}d^{0};$$

for some C > 0 then (23) is automatically satised and one obtains the entropy bound dissipation. Moreover if e(#;) ¹=C then one also has that 2 L ¹ L_x.

Assuming now that

with 2, one deduces from the entropy estimate that Z

showing that $\log \# 2 \ L_t^2 H_x^1$ and $\#^{=2} 2 \ L_t^2 H_x^1$ or by Sobolev embedding $\# 2 \ L_t^{=(1 \ 2=d)}$ for d 3. By a Helder estimate, it is also possible to obtain a Sobolev-like, $L_t^p W_x^{1;p_2}$, bound on u

provided that $p_2 = (2 p_2) = = (1 2 = d)$ and $p_1 = (2 p_1) = or$

(24)
$$p_1 = \frac{2}{1+}, \quad p_2 = \frac{2d}{d(+1)} = \frac{2}{2}.$$

Unfortunately this Sobolev estimate does not allow to derive the gain of integrability on the density as usually. Actually one requires a $L_t^2H_x^1$ estimate on u (the critical point is in fact the L_t^2 with value in some Sobolev in x). Instead one can easily extend the argument by E. Feireisl and A. Novotny: For any (), one can write

 $^{0}() + ()) divu:$

This leads to the assumption that there exists some s.t.

(25)
$$C^{-1} C () C + C;$$

$$P(\#;) \qquad {}^{0}() + () C^{-1} + \#^{2} + {}^{\underline{p}}e(\#;);$$

with

Indeed, with (25), one has

Using that S is Newtonian, this leads to

and the desired H¹ bound follows from (26). It is now possible to follow the same steps to obtain an equivalent of the extra integrability on the density if > d=2

(28)
$$Z_T Z$$
 +a dx dt C(T; E(0; #0; m0)); for all a < 1=d:

Note here that the assumptions (25)-(26) are likely not optimal. They nevertheless already cover the truncated virial law we consider here.

3.2. The assumptions on the pressure law to get the above estimates

For convenience, we repeat here all the assumptions presented above and will show that the truncated virial pressure laws satisfy them under the assumptions related to the coecients B_n. To derive the important estimates mentioned in the sections above, the pressure law P(; #) has to be a positive pressure law satisfying the following properties: For some C > 0 and > d

$$P(;\#) \text{ such that } Z = Z \\ P(;\#) \text{ such that } Z = Z \\ P = M(\#) + Z = M(\#) \\ P(;\#) = M(\#) + Z = M(\#) + Z = M(\#) \\ P(;\#) = M(\#) + Z = M(\#) + Z = M(\#) + Z = M(\#) \\ P(;\#) = M(\#) + Z = M$$

where we recall that a < min(1=d; 2=d 1) = 1=d since > d here. We also assume that the specic heat is positive (as is necessary for the physics) i.e.

(31)
$$C_v = @_{\#}e(;\#) > 0;$$
 8; #;

and that the pressure contains a radiative part

(32)
$$\hat{\mathcal{Q}}_{\#}P(=0;\#) > 0$$
:

We do not need to impose monotony on P and it is enough that

(33)
$$@P(;\#) C ^{1} + C \#^{\#}$$
 with 2 $\# < =2$:

Finally the initial data has to satisfy

and

(35)
$$E_0 = \int_{d^2}^{d} \frac{\mathbf{u}}{(1)^2} \frac{0j^2}{(1)^2} + 0 e(0; \#_0) < + 1:$$

3.3. The truncated virial pressure law satises the properties needed for the estimates above

The truncated pressure law mentioned in the introduction

$$P(; \#) = + \# B_n(\#)^n_{n=0}$$

with > 2N 4 satisfy the assumptions described before. Choosing m = constant for simplicity in this example, this leads to

e(; #) = m +
$$\frac{1}{1} \int_{n^2}^{x^N} \#^2 B^0 (\#) \frac{n}{n} \frac{1}{1} \#^2 B_1^0 (\#) \log + \#^2 B^0 (\#); \frac{1}{n}$$

For simplicity, let us assume that B_1 = constant, which is the normal virial assumption, so that this term vanishes. The entropy reads

- 1) We assume that the pressure contains a radiative part, namely that B_0 is convex in # with C 1 #* 1 B_0 (#) #* 1 and C 1 #* 2 B 0 (#) #* 2 where 2 $_{\#}$ =2. This already satises (32).
- 2) For n 2 , the coecients $B_{\,n}\,$ can have any sign but we require a concavity assumption:

$$\frac{d}{d\#}(\#^2 B_n^0)$$
 0:

This ensures, with the assumption on B_0 , that the specic heat $C_v = @_\#e(;\#)$ satises (31). This is again a classical assumption for the virial. Note that it would be enough to ask this concavity of some of

them and moreover that this is automatically satised if B_n #, that is precisely for the coecients contributing to the non-monotony of P in .

3) We also require some specic bounds on the B_n namely that there exist B_n and " > 0 s.t.

$$j\# B_n^{(}(\#)j + jB_n(\#)j C \#^{\frac{n}{\#-1}}";$$

$$jB_n(\#)j + j\# B_n(\#) B_nj C \#^{2^{-1}}":$$

First of all this gives us a bound from below on e

$$C = \frac{1}{\#\#} \# \# \frac{1}{\#} \# \frac{\#^{N}_{\#}}{n \cdot 1} = \frac{1}{m \cdot 1} \# \frac{1}{m \cdot 1} + \frac{1}{m \cdot 1} + \frac{1}{m \cdot 1} = \frac{1}{m \cdot 1} = \frac{1}{m \cdot 1} + \frac{1}{m \cdot 1} = \frac{1}{m$$

by Young's inequality, so that this implies $(29)_2$. Assumption (33) is proved with an identical calculation. The same calculation also proves Assumption $(29)_1$ by showing that s C (1 + $^#$ + 1).

4) Then choosing

(37)
$$() = \frac{X}{2nN} B_n \frac{n}{n-1} + B_0;$$

and using again the second part of (36) we have that

$$jP ^{0}() + ()j C X j#B_{n}(#) B_{n}j^{n} C X #^{2} ^{1} ^{2n} "^{n}$$

$$C N (^{=2} + \#^{=2} ");$$

still by Young's inequality. This yields the wanted estimate with the right inequalities on $_1$ and $_2$. The same calculation also proves that j@ $_\#$ Pj C ($^{=2+"}$ + $\#^{=2}$ ") with required assumptions on $_3$; $_4$.

Note for a xed # then P (; #) is indeed increasing with respect to after a critical # which depends on # and can be arbitrarily large where # >> 1. This is the reason why P does not satisfy any of the classical monotonicity assumption and why our new approach is needed. Our pressure law has two important parts: the radiative term (corresponding to n = 0) to get compactness on the temperature and the () term to get compactness on the density in time and space.

Remark 3.1. In our work, the viscosity coecients; are independent of the temperature #. Instead several models use temperature dependent coecients (#); (#). To handle that case, the proof given below would have to be modied; the compactness of the temperature would have to be established rst following what has been done in previous work for monotone pressure laws in previous works.

4. The new strategy to get global existence of weak solutions

The main diculty is the construction of regular enough solutions of some approximate system that will allow us to derive our key a priori estimates and pass to the limit. We obtain solutions of the approximate system through a xed point argument that strongly relies on our recent paper [3].

More precisely, we consider the following First Step: We start with a prescribed temperature # so that p(; #(t; x)) satises the assumptions in [3] for an heterogeneous pressure p(; t; x). This provides a map #! (; u) with (; u) a global weak solution of

(38)
$$Q_t + div(u) = 0;$$

and

(39)
$$@_t(u) + div(u$$

 $u)$ $(+)rdivu + r(p(; \#(t; x))) = 0$:

The novelty in the present paper is the Second Step: The construction of the associated temperature through the energy equation corresponding to the pressure without the barotropic part 1 =(1) namely the one corresponding to

$$Pe(; \#) = \# X^{N} B_{n}(\#)^{n}$$
:

To do so, we rewrite the energy equation

(40)
$$@_t(e) + div(eu) + PdRvu = S : ru + div((#)r#)$$

in terms of a quasi-linear parabolic equation on g = e.

Our goal is then to complete the xed point argument by solving this equation for a xed density and velocity eld u. This is a non-trivial problem as the equation is singular and it requires several extra steps:

- First of all, we need to regularize and u in space and time, be far from vacuum for the density and remove the singularity in **e** near the 0 temperature using a parameter ". That will allow us to use in a rst step the classical result [12] by O.A. Ladyzenskaya, V.A. Solonnikov, N.N. Uraltceva and get existence ([12]) of some classical solution **g** for the regularized equation.
- In a second step, we may pass to the limit "! 0 to obtain the actual solution **g**, using the expected a priori estimates for classical solutions.
- The third step consists in recovering the temperature # such that **e**(; #) = **g** using an implicit function procedure thanks to the key property @#**e** > 0 and the fact that # is more regular.
- The last step consists in deriving uniform estimates on # by transforming estimates from step 1 and making sure that there are uniform in the various regularizing parameters. This uniform estimate is obtained through the entropy equation derived from the energy equation as explained earlier.

Once this is done, we obtain a map on the temperature #: From an initial $\#_i$, we obtain (; u) solving (38)-(39). We then obtain the \new" temperature # that solves (40) for those and u.

The Third and Last Step is then to get a xed point on the temperature, for example through Schauder theorem, we need to obtain some compactness on the map. This turns out to be rather straightforward: if $\#_i$ is bounded in some appropriate Sobolev space, then log # belongs to some H^1 and we can derive compactness in space and time using the radiative part in the pressure law.

5. First step: Obtaining and u given

The goal of this section is to obtain existence of appropriate solutions and u if we already know the temperature #. This will form the rst step in our nal xed point argument.

This step heavily relies on the existence result already obtained in [3] to construct (; u) solution of the compressible Navier-Stokes equations with an heterogeneous pressure law P(t; x;) with explicit dependence on time and position.

5.1. Recalling the main result from [3]

The result in [3] requires the following assumptions with > 3d=(d + 2):

(P1) There exists q > 2, 0 = 2 and a smooth function P_0 such that

$$jP(t;x;s) P_0(t;x;s)j CR(t;x) + Cs for R 2 L^q([0;T] T^d)$$

(P2) There exists p < + 2=d 1 and q > 2 with $\#_1 2 L^q([0;T] T^d)$, such that

$$C^{-1}s = \#_1(t;x) P_0(t;x;s) Cs^p + \#_1(t;x)$$
:

(P3) There exists p < + 2=d 1 and $\#_2 2 L^q([0;T] T^d)$ with q > 1 such that

$$j@_tP_0(t;x;s)j Cs^p + \#_2(t;x):$$

(P4)
$$jr_xP_0(t; x; s)j Cs^{-2} + \#_3(t; x)$$
 for $\#_3 2 L^2(0; T; L^{2d=(d+2)}(T^d))$.

and the following one for the propagation of compactness on the density:

(P5) The pressure P is locally Lipschitz in the sense that

$$jP(t; x; z) = P(t; y; w)j = Q(t; x; y; z; w) + C(z^{-1} + w^{-1}) + (Pe(t; x) + Pe(t; y)) = jz = wj$$

for some \mathbb{R}^2 2 $L^{s_0}([0;T]T^d)$ with $s_0 > 1$. Moreover for any sequence $_k(t;x)$ uniformly bounded in $L^1([0;T];L^d)$ then $Q(t;x;y;_k(t;x);_k(t;y))$ is uniformly bounded in $L^{s_1}([0;T];L^2d)$ for some $s_1 > 1$.

(P6) For any sequence $_k(t;x)$ uniformly bounded in $L^1([0;T];L(d))$, the functions Q;P satisfy that for some $r_h ! 0$ as h ! 0

$$r_{h} = \sup_{k} \frac{1}{k K_{H} k_{L^{1}}} \sum_{0 = T^{2d}}^{Z} K_{h}(x = y) j P(t; x) P(t; y) j^{s_{0}} + j Q(t; x; y; k(t; x); k(t; y)) j^{s_{1}} dxdydt;$$

where

$$K_h(x) = \frac{1}{(h + jxj)^d};$$
 for $jxj_4;$

with K_h smooth in ^d n B(0; 1=4) and with compact support in ^d n B(0; 1=3).

We are now ready to recall the main result from [3]

Theorem 5.1. Assume the initial data m_0 and m_0 0 with $m_{T^d \ 0} = M_0 > 0$ satisfy

$$E(_{0}; m_{0}) = \frac{Z}{\frac{jm_{0}j^{2}}{2}} \frac{jm_{0}j^{2}}{\frac{+ 0}{2}e_{P}(0; x;_{0}) dx < 1; T^{d}}$$

$$e_{P}(t; x;_{0}) = \frac{Z}{e_{P}(t; x;_{0})} \frac{e_{P}(t;_{0};_{0}) dx}{e_{P}(t;_{0};_{0};_{0}) dx}$$

where

with $m_0 = 0$ when $_0 = 0$. Suppose that the pressure P is given by (1) with properties (12){(17). Then for any T > 0 there exists a global weak solution to Compressible Navier{Stokes System (2){(3) with the strain tensor (6). Namely it satises the equations in a Distribution sense, the following bounds

u 2
$$L^2(0;T;H^1(T^d));$$
 $jmj^2=2 2 L^1(0;T;L^1(T^d))$
2 $C([0;T];L(T^d) \text{ weak }) \setminus L^p((0;T) T^d) \text{ where } 0 1$

and the initial conditions in a weak sense with the heterogeneous pressure state law P satisfying the energy inequality

$$Z = Z_{t}Z$$

$$E_{0}(; u) dx + S : r_{x}u dx ds E_{0}; u_{0})^{T^{d}}$$

$$Z_{t}Z = \int_{0}^{0} T^{d}$$

$$+ div_{x} u(s; x) (P(s; x; (s; x)) - P_{0}(s; x; (s; x))) ds dx$$

$$Z_{t}^{0}Z^{T^{d}}$$

$$+ ((@_{t}e_{0})(t; x;) + u (r_{x}e_{0})(t; x;)) dx ds; 0 T^{d}$$

where

where
$$E_0(;u)=juj^2=2+e_0(t;x;); \qquad e_0(t;x;)=\frac{Z}{e_0(t;x;s)} \frac{P_0(t;x;s)}{s^2} ds;_{ref}$$
 Finally if some sequence P_n satises uniformly the assumptions (P1) (P6) then the corresponding

solution $_n$ is compact in $L^1([0; T]^d)$.

5.2. Existence given

We may easily deduce an existence result from 5.1, by checking that for a given #(t;x), the pressure P(t; x;) = P(#(t; x);), where P(#;) satises (12){(18), also satises (P1)-(P6) above.

Theorem 5.2. Assume that # 2 L $^{"0}([0; T]^d) \setminus L^1([0; T]; W^{;1}(d))$ for some > 0 and $^{"0}$ small enough. Assume that $_{R}P(\#;)$ given by (1) with (12){(17). Assume moreover that the initial data m_{0} and $_{0}$ 0 with $_{T^d}^{\circ} 0 = M_0 > 0 \text{ satisfy}$

$$E(_{0}; m_{0}) = \frac{Z}{\frac{jm_{0}j^{2}}{Z}} \frac{jm_{0}j^{2}}{\frac{+ 0}{2}e_{P}(0; x;_{0}) dx < 1; T^{d}}$$

$$e_{P}(t; x;) = \frac{Z}{\frac{y}{Z}} \frac{p(\#(t; x); s)}{\frac{s^{2}}{Z}} ds:$$
On Them for any $T > 0$ there exists a global

where

with $m_0 = 0$ when $m_0 = 0$. Then for any T > 0 there exists a global weak solution to Compressible Navier{Stokes System (2){(3) with the strain tensor given by (6). More precisely it satises the equations in the distribution sense and the bounds

u 2
$$L^2(0; T; H^1(T^d));$$
 juj²=2 2 $L^1(0; T; L^1(T^d))$
2 $C([0; T]; L(T^d) \text{ weak }) \setminus L^p((0; T) T^d) \text{ where } 0$

with the initial conditions in a weak sense and with the heterogeneous pressure state law P(#(t;x);:) satisfying the energy inequality

Z
$$Z_{t}Z$$

 $E_{0}(; u) dx + S : r_{x}u dx ds E(_{0}; u_{0})$
(41) $T^{d} Z_{t}Z = 0 T^{d}$
 $+ div_{x} u(s; x) (P(\#(s; x); (s; x)) = P_{0}((s; x))) ds dx; 0$

where

$$P_0() = + {X \choose B_n}^n; n=0$$

$$E_0(; u) = juj^2 = 2 + e_0(); e_0 = {Z \choose P_0(s)} \frac{ds}{s^2} e^{ref}$$

Finally if some sequence $\#_n$ is uniformly bounded in L $^{"0}([0; T]^d) \setminus L^1([0; T]; W^{;1}(d))$, then the corresponding solution n is compact in $L^1([0; T]^d)$.

Proof.

Property (P1). We note that

$$jP$$
 $P_{0}j$ $j\#(t;x) B_{n}(\#(t;x))$ $B_{n}j^{n} N^{=2} + X^{N} j\#(t;x) B_{n}(\#(t;x))$ $B_{n}j^{=(-2n)}$:

By assumption (17), this implies that

This leads us to dene

$$R(t; x) = N j#(t; x)j^{=2}$$
;

and we can immediately verify that R 2 $L_{t;x}^q$ for some q > 2 since we assumed that # 2 $L_{t;x}^{0}$ with for "small enough w.r.t.".

Property (P2). We can check (P2) almost immediately as well by taking $\#_1(t; x) = C$ for some large constant C, as for example

$$jP_0$$
 j $jB_n j^n C + C^N;$

where we recall that N = 2.

Properties (P3) and (P4). As indicated in the statement of the theorem, we take $P_0 = {}^{0}()$ () where is given by (37), that is

$$P_0(t; x;) = + X B_n^{N}$$

This directly implies (P3) and (P4) since P_0 does not explicitly depends on t or x and thus $@_tP_0 = 0$ and $r_x P_0 = 0$. Consequently we also have that $@_te_0 = 0$ and $r_x e_0 = 0$ so that we do not have the corresponding terms in the energy equality.

Properties (P5) and (P6). Observe that

$$\begin{split} jP(t;x;z) & P(t;y;w)j \ C \ (z^{-1}+w^{-1})jz \qquad wj \\ & + C \quad j\#(t;x) \ B_n(\#(t;x)) + \#(t;y) \ B_n(\#(t;y))j \ (z^{n-1}+w^{n-1})jz \quad wj \\ & \stackrel{n=0}{\underset{n=0}{\times}} \chi^{N} \\ & + C \quad j\#(t;x) \ B_n(\#(t;x)) \quad \#(t;y) \ B_n(\#(t;y))j \ (z^n+w^n): \end{split}$$

Therefore

We can hence choose any Pe s.t.

$$P^{2}(t;x)$$
 $X \cap J^{m}(t;x) B_{n}(\#(t;x))$ $B_{n}J^{\frac{1}{n}};$

or from (17) again, for some small " > 0,

$$Pe(t;x)$$
 $X = 0$ $y = 0$ y

Of course, since

$$\frac{(2n)(1)}{(n)^2}$$
 as 2 2n + 2n 2 2 2n;

we may simply take

$$Pe(t; x) = C j#(t; x)j$$
 ":

Since # 2 $L_{t;x}^{"0}$ and , this immediately imply that P 2 $\mathfrak{E}_{t;x}$ for some $s_0 > 1$, provided again that "0 is small enough. Moreover since # $2_t L^1 \mathcal{W}^{;1}$ for some > 0, by interpolation we deduce that PE 2 $L_t^{s_0} \mathcal{W}_x^{s_0}$ for some > 0 and for some $s_0 > 1$. This directly implies property (P6) on P. e From (42), we take

$$Q(t;x;y;z;w) = C \int_{0}^{X^{N}} j\#(t;x) B_{n}(\#(t;x)) \quad \#(t;y) B_{n}(\#(t;y)) j(z^{n} + w^{n}):$$

Consider now any sequence $_k$ uniformly bounded in L_t $\mathbb{1}_x$. We may directly bound for $s_1 > 1$ small enough

Still using assumption (17), we have that

$$k\#(t;x)\,B_n(\#(t;x))\quad B_n\,k_{L_t^{s_1}L_x^{=(-n\,s\,)_1}}\,k\#k\qquad \qquad \frac{\frac{2\,n}{2}\quad \ \, "}{L_t^{s_1}\left(-\frac{2\,n}{2}\quad \ \, L_x^{s_1}\left(-\frac{2\,n}{2}\right)\right)_{x}^{-2\,(-\frac{2\,n}{n\,s_1})}\quad \ \, :$$

Clearly both $\frac{2n}{2}$ 1=2 and $\frac{p_{n_1}}{1}$ =2 as long as $s_1 < 2$. Since # 2 $L_{t;x}$, we can take up to $s_1 = 2$ and have $Q(t;x;y;_k(t;y))$ 2 $L_{t;x}$ uniformly in k.

We may similarly prove property (P6) for Q,

From our previous argument we know that $\#B_n(\#)$ B_n does belong to $L_t^{s_1}L_x^{\frac{ns_1}{ns_1}}$ and in fact to some $L_t^pL_x^q$ with $p>s_1$ and $q>\frac{ns_1}{ns_1}$ Moreover since #2 $L_t^1\psi^{;1}$ and B_n is locally Lipschitz from (17), we also have that $\#B_n(\#)$ B_n 2 $L_t^1\psi^{0;1}$ for some 0>0. By interpolation, this nally implies that $\#B_n(\#)$ B_n 2 $L_t^{s_1}W_x^{0;1}$ which proves (P6) for Q.

6. Second step: Solve the temperature equation with , u given

We rst start to solve an equation related to the energy and then use an implicit function procedure to nd the corresponding temperature. This is the important and new part in the global existence construction procedure.

6.1. An equivalent system with good unknowns

From (7), it is straightforward to check that

(43)
$$e = m(\#) + \frac{1}{1} \#^2 X B_n^0(\#) \frac{n}{n} + \#^2 B^0(\#)^{\frac{1}{2}} \div$$

Instead of working on the system involving the quantity e, we present here an equivalent system with what will prove to be an easier unknown to handle

$$(44) g = e;$$

where e is given by

(45)
$$\mathbf{e} = \#^2 \qquad \mathbf{B}_n^0(\#) \frac{\mathbf{n} + \mathbf{1}}{\mathbf{n} + \mathbf{1}} \#^2 \mathbf{B}^0(\#) \frac{\mathbf{1}}{\pi}$$

where we recall that N < =2. Dene a new pressure P b_y

(46)
$$Pe = \# \mathop{B}_{n}(\#)^{n}:$$

Then the good unknown g satises

(47)
$$@_{tg} + div(gu) + P^{e} div u = S : ru + div((#)r#);$$

where S : ru = Tr(Sru) as before.

Remark 6.1. From the assumption 14 on P, it follows easily that $\#^2B^0$ Q for n 2, which implies that B_n is a decreasing function in # for n 2. Moreover, in view of assumptions 12 and 14, we have that

$$e > 0;$$
 $e > 0;$ for $e > 0$;

6.2. The solvability of the quasi-linear parabolic system

Consider the equation

(48)
$$Q_t f = (a_i(t; x; f; rf)) + a_0(t; x; f; rf) = 0 (t; x) 2 Q_T = [0; T] T^d$$

with the initial condition

(49)
$$f_{j_{t=0}} = f_0:$$

We recall here the classical assumptions on the functions a_0 and $a = (a_1; a_2; :::; a_d)(t; x; f; p)$ for t 2 [0; T], x 2 T^d, f 2 R and p 2 R^d to obtain a solution f(t; x).

Theorem 6.1 ([12]). Suppose that

• (H1). The system (48) is parabolic in the sense that

(50)
$$c_1(f)jj^2 \xrightarrow{X} @a_{ij} c_2(f)jj^2;_{i;j}$$

where $c_0,\,c_1,\,$ and c_2 are positive, continuous and potentially depend on f.

• (H2). For (t; x) 2 Q_T and for any f and p, the inequality

holds with a continuous function b and a function $_1$ 2 $L^1(Q_T)$.

• (H3). With jfj M where M > 0 is a constant large enough and arbitrary p, we have the bound

(52)
$$\chi^{n} j a_{i} j + \underbrace{ (1 + jpj) + }_{0} + \underbrace{ j a_{0} j}_{i; j=1} c_{3} (1 + jpj^{2}) : i=1$$

for some $c_3 > 0$.

- (H4). The functions a_i, @a_i=@p_j, @a_i=@x_j, and @a_i=@f are Helder continuous with exponent,
 =2, , and respectively.
- (H5). The following bounds holds,

(53)
$$\frac{@a_{i}}{@f}; \frac{@a_{i}}{@t}; \frac{@a_{0}}{@p}; \frac{@a_{0}}{@f}; \frac{@a_{0}}{@t}$$

for any jfj; jpj M for some suciently large constant M, where $_{2}^{(t;x)}(t;x)$ 2 $_{1}^{r;p}$ with r; p 2.

Assuming $f_0 \ge C_x^{2+}$, then there exists a unique solution f of the system 48 such that $f \ge C_x^{1+=2}C_x^{2+}$ Moreover, we have $@_{t,x}f \ge L^2$.

6.3. Solving an approximate system

In order to solve the system, one way is to see (47) as a quasi-linear parabolic equation of the unknown function g, namely # = #(;g). Equation (47) is in the right form since

where

and

(56)
$$a_0 = I^2 \operatorname{div} u \quad S : ru:$$

There are however several regularity issues when trying to apply directly Theorem 6.1, which forces us to introduce several approximations. First of all, there is a singularity in @#=@g when g or # is close to 0. Second the assumptions on the various functions a_i and a_0 require some additional regularity on and u.

This leads us to look at an approximate system where we modify the relation between g and #. More specically, for a given " > 0, we rst solve in $g_{"}$, the system

with

(58)
$$a_{i}^{"}(t;x;g_{"};rg_{"}) = g_{"}u_{i} + (\#_{"}) \underset{@}{\overset{@\#_{i}}{@}} g_{"} + (\#_{"}) \underset{@}{\overset{@\#_{i}}{@}} i$$

and

(59)
$$a_0^{"}(t;x;g_{"};rg_{"}) = P^{e_{"}} div u S : ru$$
:

However we take

(60)
$$g_{"} = e_{"}; \qquad e_{"} = "\frac{\#_{"}}{m} \qquad \#_{n}^{2} \qquad B_{n}^{0}(\#_{"}) \frac{n-1}{n-1} \#_{n}^{2} B_{0}(\#_{"}) \frac{1}{m}$$

which changes the relation between $\#_{\parallel}$ and g_{\parallel} , resolves the degeneracy around #=0 and also implicitly modies the a_i .

Finally, we adapt the pressure Pa to match the new energy and keep

(61)
$$Pe_{"} = " #_{"} log #_{"} + #_{"} B_{n} (#_{"})^{n}:$$

We then have the following existence theorem for the approximate equation.

Theorem 6.2. Let \mathbb{R}^2 be dened in (61) and $\#_{\mathbb{R}}$ be dened in term of $g_{\mathbb{R}}$ through (60) for some $2 C^1 C_{t-x}^{2+}$ and $u 2 C_{t}^1 C_{x}^{2+}$. Then for any initial data $g_0 > 0$ with $g_0 2 C_{x}^{2+}$, there exists a unique classical solution $g_0 2 C_{t-x}^{2+}$ to the system (54) where the $g_0 2 C_{x}^{2+}$ are given respectively by (58) and (59).

Proof. To simplify the notations, within this proof, we omit the "subscript as it will not cause any confusion; we take the limit "! 0 in the next subsection. We use Theorem 6.1 to prove the existence result.

Important relations between g and #. Through (60), we rst observe that # can be seen as #(t; x; g) or #(; g). This can be proved by showing that g is strictly increasing in # by dierentiating (60). We nd that

(62)
$$\frac{@\xi}{@\#} = \text{"} \frac{X}{2nN} \frac{d}{d\#} (\#^2 B^0 (\#_n))_n \frac{n}{1} + \frac{d}{d\#} (\#^2 B_0^0 (\#));$$

and by assumptions 12 and 14 we easily get a lower bound for @g=@#

$$\frac{@g}{@\#}$$
" + 2#B⁰+₀#²B₀₀" + C#¹1:

Using assumptions 12, 14, and 15, we may further deduce an upper bound for @g=@# as

$$\frac{g}{\omega_{\#}}$$
" + C $\#^{(n)_{\#}=1}kk^{n_1}$ " + C $(\#^{\#} + \#^{(N)_{\#}=1})$: OnN

Combining the above two inequalities gives

(63) " +
$$\frac{1}{C}$$
 #* $\frac{0}{C}$ # + C (#* $\frac{1}{C}$ + $\frac{1}{C}$ + $\frac{1}{C}$ *): From the

denition of g in (60), we have that g = 0 if # = 0. As a consequence,

(64) "#+
$$\frac{1}{C}$$
g "#+ C (## + #^(N)#=):

We also need an upper bound of @#=@g in term of g as

together with a lower bound

with M " being a smooth function of g, where we used (63) and (64).

Hypothesis (H1). We also note, for further use, that (11) yields

(67)
$$1 (#) C (g^{-#} + 1):$$

We can then make explicit the various coecients with for example

$$a_i(t; x; g; p) = a_i(; r; u; g; p) = g u_i + (\#(; g)) \frac{g}{g} \frac{g}{p_i + g} (\#(; g)) \frac{g}{g} g_i = \frac{g}{g}$$

This directly implies that

$$a = (\#)^{\#} =$$

where I_d is the identity matrix. Therefore, we obtain

$$\begin{smallmatrix} c_1 j j^2 & \intercal \\ & @p & \underbrace{\begin{smallmatrix} c_2 j j^2 \\ @i \end{smallmatrix}}_{a} \end{smallmatrix}$$

for any 2 R^d provided jgj c_0 where c_1 and c_2 are non-vanishing and depend polynomially on g, which veries (50).

Hypothesis (H2). From the equation

$$g = "#$$
 X $\#^2B_n^0(\#)\frac{n}{n-1} + \#^2B_0^0(\#);$

again viewing # as a function of both g and , we take derivative with respect to , keeping g xed, to get

from where one obtains

$$\frac{@\#}{@} = \frac{P}{P} = \frac{P}{2 + N} = \frac{N}{N} =$$

By (65), assumptions 14 and 15, it holds

Combining (55) with the estimates (65), (67), and (68), we further get

In view of 59, (61), assumptions 12, and 15, we similarly obtain an upper bound of a₀ as

by using again the regularity of and u. Hence the condition (51) is veried by collecting the estimates (69) and (70).

Hypothesis (H3) $\{(H4).$ Next we turn to the verication of (52). First, we compute the derivative of a_i as

$$\frac{(a_i t; ; g; p)}{(a_i x)} = u_i + {}^0(\#)_{(a_i x)} \#^2 \frac{p}{(a_i y)} + (\#)_{(a_i y)} \#^2 \frac{p}{(a_i y)} + {}^0(\#)_{(a_i y)} + {}^0(\#)_{(a_i y)} \#^2 \frac{p}{(a_i y)} + {}^0(\#)_{(a_i y)$$

From (62), it is straightforward to get

$$\frac{@\#}{@g} = \frac{1}{\|P\|_{2nN \ d\#} (\#^2B^0(\#_0))^n = (n \ 1) + \frac{d}{d\#} (\#^2B_0^0(\#_0))};$$

which leads to

$$\frac{@^{2}\#}{?} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n} = (n - 1) + \frac{d}{d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n} = (m - 1) + \frac{d}{d\#} (\#^{2} B^{0} (\#_{n}))^{2} (\#^{2} B^{0} (\#_{n}))^{2}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n} = (n - 1) + \frac{d}{d\#} (\#^{2} B^{0} (\#_{n}))^{2}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n} = (n - 1) + \frac{d}{d\#} (\#^{2} B^{0} (\#_{n}))^{2}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n} = (n - 1) + \frac{d}{d\#} (\#^{2} B^{0} (\#_{n}))^{2}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n} = (n - 1) + \frac{d}{d\#} (\#^{2} B^{0} (\#_{n}))^{2}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n} = (n - 1) + \frac{d}{d\#} (\#^{2} B^{0} (\#_{n}))^{2}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n} = (n - 1) + \frac{d}{d\#} (\#^{2} B^{0} (\#_{n}))^{2}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}} = \frac{P_{2 \, n \, N \, d\#^{2}} (\#^{2} B^{0} (\#_{n}))^{n}}{2 \, m^{2}}$$

By combining our previous bounds, we can prove that

$$X$$
 $ja_ij + \frac{@^i}{a_{00}} (1 + jpj) + jaj c_3(g)(1 + jpj^2)$

for some $c_3 > 0$ which depends on " and is polynomial in g and hence bounded whenever g M. We may perform again similar calculations for all $@a_i = @x_j$ which yields the bound (52). The same formula and the regularity of and u ensures that a_i , $@a_i = @p_j$, $@a_i = @x_j$, and $@a_i = @f$ are Helder continuous with respect to t; x; g; and p. We can check the bound (53) in the same manner.

This satises all assumptions of Theorem 6.1 as long as we can ensure that g > 0. This follows from a straightforward maximum principle applied to any classical solution of (54): See the positivity part just below.

Positivity of g. We note that we can rewrite (54) as

$$@_{t}g + div(g U) = r_{x}$$
 (#) $\frac{@_{t}}{@_{g}}$ $r_{g} + (#)$ $\frac{@_{t}}{@_{g}} + S : r_{u}$ $P^{e} div u;$

where

$$U = u + (\#) r \frac{@ \#}{g}$$
:

Remark that S:ru 0. Moreover # = 0 when g = 0 and for 0 g 1, we have that

while by (68), we have still for 0 g 1 that

$$\underline{\underline{@}}^{\#} \#^2 \quad \text{"} \quad g^2: \quad \underline{\underline{C}}$$

This ensures that the solution g and then # are both strictly positive.

6.4. Existence of solutions # such that the entropy dened by (9) satises the equation (10).

From the previous result, we may pass to the limit "! 0 to obtain the following existence result.

Theorem 6.3. Assume that 0 2 L_x , $\#^0$ 2 $L_x^\#$. Assume moreover that 2 $L^1([0; T]; L(^d))$ and u 2 $L^2([0; T]; H^1(^d))$ and solve the continuity equation (2). Then there exists # 2 $L^1(0; T; L^\#(^d)) \setminus L([0; T]^{-d})$ such that

for some constant depending on the norms (kk_{L^1L} ; $kuk_{L^2H^1_t}$ and on the initial data ⁰ and #⁰). Furthermore, dening the entropy through the relation

then

(73)
$$ksk_{L_{t}} {}_{t}^{1} {}_{x}^{+} ksuk_{L_{t};x} {}_{1}^{1}C(kk_{L^{1}L_{x}}; kuk_{L^{2}H_{1}}); {}_{t}^{1}$$

and s solves the following inequation in the sense of distributions

(74)
$$@_{t}(s) + div(s u) r_{x} {(\#) \atop \#} r_{x} \# + {1 \atop \#} S : ru + {(\#) \atop \#} jr \# j^{2}$$

with an initial condition satised weakly through the following inequality

(75)
$$sj_{t=0+} {}_{0}s({}_{0}; \#_{0}):$$

Finally dening g through the identities (44)-(45), we also have the energy equality

(76)
$$Z \qquad Z \qquad Z_{t}Z$$

$$= g(t;x) dx = g^{0}(x) dx + (S:ru) P^{0}(s;x) ds dx$$

Proof. The strategy of the proof is straightforward. Given u 2 $L_t^2 H_x^1$, we construct u-2 C 1 that converges to u strongly in $L_t^2 H_x^1$. For simplicity, we consider here an approximation by convolution. Given 2 $L_t^1 L_t^1$, we construct 2 C 1 by convoluting through the same kernel, uniformly bounded in $L_t^1 L_x^1$ and converging to in $L_t^1 L_x^1$ for every p < 1. Observe that the standard commutator estimate implies that

$$@_{t''} + div("u") = R";$$

where R_{+} ! 0 in $L_{+}^{2}L_{x}^{p}$ with 1=p=1=2+1=.

We also choose $\#_{0}^{0} = " + \#^{0}$ which is uniformly in $L_{x}^{\#}$. For any xed " > 0, we then obtain a classical solution $g_{0}^{\#}$ to (54) with (58)-(59). We then have to pass to the limit as "! 0 in the system.

Uniform bounds. The critical point is hence to derive appropriate estimates on g_{\parallel} and $\#_{\parallel}$ that are uniform in ". This is naturally based on equivalent energy and entropy estimates. To start with the energy, by directly integrating the equation on g_{\parallel} rst in space and then in time, we obtain

$$Z$$
 Z $Z_{t}Z$
 $g_{"}(t;x) dx = g_{"}^{0}(x) dx + (S_{"}:ru_{"} Pe_{t} div u_{"})(s;x) dx ds:$

From our assumptions on the initial conditions 0 and $\#^0$, we have uniform bounds on g_n^0 in L^1 . Indeed for any n_{ν} (0) n converges to (0) n strongly in $L^{=n}$. From assumption (16), ($\#^0$) 2 B $_n^0$ ($\#^0$) converges strongly

in $L^{=(n)}$. Since $^{n}+-=1$, we directly obtains that g^{0} converges to g^{0} strongly in L^{1} and $_{x}$ that it is uniformly bounded in L^{1} .

Moreover by convexity of the H¹ norm, we also have that

$$Z_tZ$$

 $S_{"}: ru_{"} dx ds kuk^2_{L_tH_x^{\bullet}}$

This yields that

(77)
$$g_{"}(t;x) dx C + kuk_{L_{H_{t}}^{2}}^{2} + kuk_{L_{H_{t}}^{1}} k_{x}^{p} + k_{L_{t;x}}^{p} +$$

It remains to control the norm in the right-hand side. From the denition of P_"? we have that

From the $L_t^1 L_x$ bound on , this implies that

with $1=q_n = 1=2$ $n= \text{ or } q_n = 2 = (2n)$.

We may now use assumption (17) to further bound

$$k\#_{"} B_{n}(\#_{"}) k_{L_{t}^{2}L_{x}^{q_{n}}} C + C k\#_{"} k_{L_{x}^{2}}^{\frac{2n}{t}}$$

This lets us deduce that for some < 1=2,

For further use in a later section, we also note that we have the more precise estimate

From the denition of g_", we also have that

$$Z \\ g_{"}(t;x) dx = \frac{1}{C} Z \\ \# dx \\ n=2 \\ k\#_{"}^{2} B_{n}^{0}(\#_{"}) _{"k}^{n} k_{L_{t}^{1}L^{1}};$$

Using again the $L_t^1 L_x$ bound on , this implies that

with $1=e_n = 1$ n=.

Now use assumption (16) to obtain, again for some ₹ 1,

$$k\#_{n}^{2} B_{n}^{C}(\#_{n}^{n}) k_{L_{1}^{1}L_{x}^{Q_{n}}} C k\#_{n}^{m} k\#_{L_{1}^{1}L_{x}^{m}}^{Q_{n}}$$

This shows that, again for some € 1,

For further use, we even have the more precise estimate

Therefore, inserting those estimates into (77) yields that

On its own, we cannot obtain a priori estimates just from (80) and we need also an entropy bound. Since for " > 0, g_{\parallel} and $\#_{\parallel}$ are smooth and $\#_{\parallel}$ > 0, we can dene

$$s_{"} = \frac{"}{"}log \#" \qquad X^{N} Be_{n}(\#") \frac{n}{n-1} + \frac{1}{"}Be(\#");$$

with $d\mathbf{E}_n(\#) = d\# = \# B_n^{00}(\#) + 2 B_n^0(\#)$ so that $\# \# \frac{@s^n}{@\#} = \frac{@e^n}{@\#}$. Note that

$$@_{t}g'' = \frac{@g'}{@\#} @_{t}\#'' + \frac{@g'}{@}@_{t}";$$

where we recall that

$$\frac{@g_{!}}{@\#} = " \frac{X}{2nN} d\# (\#_{-}^{2}B^{0}(\#_{n}^{"}))_{n} \frac{n}{1} + \frac{d}{d\#} (\#_{-}^{2}B^{0}(\#_{-}^{"})) > 0;$$

for any " > 0 and for $g_{"} = " e_{"}$,

This lets us write that

$$\frac{@g'}{@\#} (@_t \#_" + u_" r_x \#_") = g_" \operatorname{div} u_" \frac{@g'}{@} (@_{t"} + u_" r_{x"}) \qquad P^{e_n} \operatorname{div} u_" + S_" : ru_" + r_x ((\#_") r_x \#_"):$$

Since we have kept the critical relation,

$$\mathbf{P}^{\mathbf{e}_{n}} = {}^{2} \underbrace{{}^{\mathbf{e}_{n}}}_{\mathbf{e}} \# \underbrace{{}^{\mathbf{e}_{n}}}_{\mathbf{e}} \# \mathbf{e}^{\mathbf{e}_{n}}$$

this yields

$$\frac{@e^{-}}{@\#} (@e^{+} + u^{-} r_{x} \#^{-}) = \frac{@e^{-}}{@} R^{-} \#^{-} \frac{@e^{-}}{@\#} \text{ div } u^{-} + S^{-} : ru^{-} + r_{x} ((\#^{-}) r_{x} \#^{-}):$$

Because the critical relation above also implies that

$$\frac{@s''}{@} = \frac{1}{2} \frac{@\Phi''}{@\#};$$

we nally deduce that

The rst key point to make use of (81) is that we still have that "s" C g". Hence

t to make use of (81) is that we still have that "S" C g". Hence
$$Z_{T}Z = Z_{0} = (\#_{"})^{\frac{1}{2}} \frac{1}{\#^{2}} dx dt C = Z_{T^{d}} = T; x) dx = Z_{T^{d}} = Z_{0} =$$

We may hence immediately use (80) together with the H¹ estimate on u_{-} . We note that, just as for g_{-}^{0} , we have initial uniform bounds on ${}^{0} \, {}_{s}^{0} \, {}_{i}$ in L¹. Indeed since ${}^{0} \, {}_{r}^{0} \, {}_{r}^{0} \, {}_{r}^{0} + {}^{0}$, and ${}^{0} \, {}_{s}^{0} \, {}_{s}^{0} \, {}_{s}^{0}$

$$k'' \log \#_{"}^{0} k_{L^{1}} "j \log "j + "k \#_{L^{1}}! 0; as "! 0:$$

Moreover, again using assumption (16), we also have the strong convergence in L^1 of B.F(#0) (0) in just as for g^0 . Consequently we have the strong convergence in L^1 of $_x^0$ s⁰ to $_x^0$ with a uniform bound in " which allows to derive

$$Z_{T}Z_{0} = (\#_{"})^{j} \frac{r \#_{"}^{2}}{\#_{"}^{2}} dx dt C + kuk_{L^{2}H_{1}^{2}} + C(kk_{L^{1}L}; kuk_{L^{2}H_{1}}) (1 + k\#_{"}k) (82)_{L_{L_{x}}} + kR_{"}k_{L_{t}L_{x}}^{2} s_{"} + \frac{g_{"}^{2}}{2} \frac{g_{"}^{2}}{L_{x}} \cdot t^{p}$$

Our second critical point is that we have a simplied expression

$$S'' + " \frac{@S''}{@} # \frac{1}{"} \frac{@g'}{@} = \frac{\chi^N}{(#"B^0 n B_n)} \frac{n}{n 1}^{n 1};$$

where the $\log \#$ term vanish. In particular this expression is smooth around # = 0 and only blows up as # ! 1.

Recalling the denition of B_fR, we note that

$$\frac{d}{d\#}(B^{0}_{n} \quad \stackrel{e}{=} B^{0}_{n} + \#B^{00}_{n} \quad \#^{00}_{n} \quad 2^{0}_{n} = B^{0}_{n};$$

so that in the end

$$S'' + " \frac{@S''}{@} # \frac{1}{@} \frac{@g'}{@} = X^N B_n(#")_n \frac{n}{1}^{n + 1}$$
:

Using the $L_t^1 L_x$ bound on , this implies that

with

$$p_n = \frac{1}{p} \quad \frac{n-1}{p} = 1 \quad \frac{1}{p} \quad \frac{n-1}{p} = \frac{1}{2} \quad \frac{1}{p} \quad \frac{n-1}{p} = \frac{1}{2} \quad \frac{n}{p} = q_n;$$

which was the exponent dened earlier when controlling the norm of P_"ein L².

Therefore this term can be bounded in exactly the same way through assumption (17), yielding

$$S'' + " = @ \frac{@S''^{\#}}{@ - | - |} = \frac{1}{@_L} \frac{@\xi''}{2 L_x} C + C(k k_{L^1 L_x}) (1 + k \#'' k):$$

This let us obtain by adding (82) and (80) that

We are now ready to conclude our a priori estimates. By assumption (11) and Poincare inequalities,

$$Z$$
 Z $=$ Z $=$ Z $+$ Z $+$

so that, since 2,

Because < 1=2 and $2_{\#}$, this inequality is enough to bound the right-hand side of (83) in terms of its left-hand side. Hence we eventually have the uniform in " estimates

Those bounds directly imply that # 2 $L^1([0; T]; L^*(^d)) \setminus L([0; T]^d)$ as claimed. Because (#) 1, (85) also shows that

again by Poincare inequality.

To conclude those a priori estimates, note that we nally have that

(87)
$$\sup_{T^{d}} \frac{J_{T} J_{z}^{2}}{\#} dx dt C(kk_{1} ; kuk_{2} ; h_{x}^{2}) : H_{x}^{2} 0$$

Limit passage "! 0. We can now send "! 0 to get a weak solution of (54). From our previous estimates, we know that $g^{_{1}}$ is uniformly bounded in L_{t}^{1} L_{x}^{p} for some p > 1. This lets us extract a sub-sequence, still denoted $g^{_{1}}$, that converges weak-* to some g in L_{t}^{1} L_{x}^{p} for some p > 1.

To derive the compactness on #" through the classical Aubin-Lions approach, we require controls on g" u" and "s" u". We may bound directly by Sobolev embeddings

$$kg"\; u"\; k_{L^1_{t;x}} \;\; ku"\; k_{L_t\; H^2_x} \;\; \underline{k} g"\; k_{L_{t;x}} \underline{\imath}$$

It is straightforward to bound the L^2 norm of g_n in the same manner as we bounded the L^2 norm of Perentier: Assumption (17) indeed implies the same behavior for $\#^2 B_n^0(\#)$ and $\# B_n(\#)$.

For further use, we also observe that by using the " > 0 in (17), we may use some interpolation on $\#_{}^{_{1}}$ between $L_{+}^{_{1}}L_{x}^{_{\#}}$ and $L_{+}^{_{2}}L_{x}^{_{\chi}}$ leading actually to

(88)
$$kg_{\parallel} u_{\parallel} k_{\perp} C(kk_{\perp} k_{\downarrow} k_{\downarrow} k_{\downarrow} k_{\downarrow}); 1$$

for some p > 1. The same applies to P_{ij}^{c} so that we also have that

(89)
$$k \mathbb{P}_{k_{t+x}} C(kk_{L_{t} L_{x}^{1}}; kuk_{L_{t} H_{x}^{2}}); 1$$

for some q > 1.

A similar discussion applies to "s", with in fact much simpler estimates. First of all B_n behaves like # B^{00} + 2_nB^0 instead of $\#^2B^0$ ($\#^2B^0$) instead of $\#^2B^0$) instead of $\#^2B^0$ ($\#^2B^0$) inst

(90)
$$k_{\parallel} s_{\parallel} u_{\parallel} k_{\perp, \nu} C(k_{\perp} k_{\perp} ; ku_{x} k_{\perp} k_{\perp} ; ku_{x} k_{\perp} k_{\perp} ; ku_{x} k_{\perp} k_{$$

for some p > 1.

We now turn to the compactness argument. We may extract a subsequence #, converging weak-* to # in $L^1_tL_x^\#$. Furthermore by (85) it follows that # is compact in space. Since # is also compact in space, the denition (60) of $g_{\#}$ together with our a priori estimates directly implies that $g_{\#}$ is compact in space. For similar reasons, # s# is compact in space.

We now obtain from Equation (57) and Equation (81) that both $@_tg^{\shortparallel}$ and $@_t("s")$ are bounded in $L^1_tW_x^{1;1}$ thanks to (88)-(90) and our previous a priori estimates. By Aubin-Lions, this shows that g^{\shortparallel} and g^{\shortparallel} are compact in $L_{t:x}$.1

Upon further extraction, we may therefore assume that both g_{\parallel} and g_{\parallel} solutions (12) and (15), g_{\parallel} g of and more precisely g_{\parallel} is uniformly away from 0 for g_{\parallel} for any g_{\parallel} 0. This proves that for a xed value of g_{\parallel} (g_{\parallel}) is one-to-one in g_{\parallel} .

The pointwise convergence of g_{\parallel} therefore implies the pointwise convergence of $\#_{\parallel}$ to some #, and hence the compactness and convergence of $\#_{\parallel}$ to # in $L_{t;x}$. A rst consequence is that we may pass to the limit in (60) and obtain that the limits , # and # solve (45). Similarly , # and # solve (72).

Energy equation (76). It remains to pass to the limit in the integral of Equation (57) on g_{\parallel} and in Equation (81). Since u_{\parallel} is converging a:e: to u_{\parallel} we have the a:e: convergence of g_{\parallel} u_{\parallel} and u_{\parallel} s u_{\parallel} to respectively g u and s u. By the equi-integrability provided by (88) and (90), we can apply dominated convergence and obtain the strong convergence of g_{\parallel} u_{\parallel} and u_{\parallel} s u_{\parallel} .

Obviously we directly have the strong convergence of S^- : ru^- . We also have pointwise convergence inside the formula (61) dening P^Q so that , # and P^Q satisfy (46). By (89), we hence have that P^Q converges to P^Q in $L^2_{t;x}$, again by dominated convergence. Since div u^- converges strongly to div u in $L^2_{t;x}$, this yields the convergence of P^Q div u^- . It is now possible to integrate Equation (57) and pass to the limit in all resulting terms to obtain the claimed energy equality (76).

Entropy inequation (74). It remains to derive the limit of Equation (81) on $^{_{\rm H}}$ s $^{_{\rm H}}$. Our previous analysis shows that

$$R_{"} s_{"} + " \frac{@s_{"}}{@} # \frac{1}{@} \frac{@g_{"}}{@} ! 0;$$

strongly as "! 0.

We can also prove that div $\frac{(\#^n)}{\#^n}$ r $\#^n$! div $\frac{(\#)}{\#}$ r # in the distribution sense. Denoting e(#) s.t. $e^0 = \frac{(\#)}{\#^n}$ we note that

$$\frac{(\#")}{\#"}$$
r $\#" = r(e(\#"))$:

As before $e(\#_{"})$ converges a:e: to e(#). By assumption (11), je(#)j C (log #+#). On the other hand, by combining (11) and (85), we also have that

By Sobolev embedding, we have that # is uniformly bounded in $L_t^{2=2}$ with 1=2 = 1=2 1=d (or 2 < 1 for d = 2). By interpolation with the uniform bound in $L_t^1 L_x^\#$, we obtain a uniform bound for

 $\#_{i}$ in $L_{t;x}^{p}$ for some p > 1. As a consequence $e(\#_{i})$ is equi-integrable and converges strongly in $L_{t;x}^{1}$ to e(#), proving the required limit.

It is important to highlight that the same argument would not apply to the limit of div ((#, #) + #). Any anti-derivative of (#) behaves like #⁺¹ as #! 1. Therefore it would not in general be possible to control it through our a priori estimates. This is the main objection that prevents us from passing to the limit in the whole equation (57) for g_".

We are also not able to pass to the limit in the two remaining terms in the right-hand side of Equa-tion (81). We have for example the a:e: convergence of $\frac{1}{\mu_{\parallel}} S_{\parallel} : r u_{\parallel}$ but we cannot prove equi-integrability, as $\frac{1}{4\pi}$ could be large. However we can obtain inequalities which lead to the limiting inequation.

We recall that the function (a; b) ! $\frac{a^2}{b}$ is jointly convex in (a; b). Consequently if some functions a_n ; b_n converge to functions a; b in L^1 (or even in some appropriate weak topology) then $\frac{a^2}{b}$ lim inf $a_n \frac{2}{b_n}$ This immediately implies that

$$\frac{1}{\#}S : ru \lim_{\longrightarrow} \frac{1}{\|S^{*}\|} : ru^{*}:$$

Second by denoting (#) s.t. $0 = ((#))^{1=2} = \#$, we have that

$$(#")^{jr#"j^2} = jr(#")j^2:"$$

Therefore, we also have that

(#)
$$\frac{\int r^{+}j^{2}}{r^{+}}$$
 lim inf (r^{+}) $\frac{\int r^{+}r^{+}j^{2}}{r^{+}}$

(#) $\frac{j_r \# j^2}{\#^2} \liminf_{\substack{":0 \ ":0}} (\#^") \frac{j_r \#^" j^2}{\#^2}$ The same arguments allow us to deduce (71) from our a priori estimates (85)-(87). Concerning (75), we use that

2
$$[0;T]$$
! $(s)(t;)'dx$ ' 2 $C_c^1($) and ' 0

is a sum of a non-decreasing function and a continuous function taking advantage of the entropy inequality. This completes the proof.

7. Third Step: Fixed Point procedure and proof of main result

We are now ready to prove our main result. Denote

$$E = L ([0;T]^d) \setminus L^1([0;T];W^{;1}(^d));$$
 with $^{"0} > 0$

as in Theorem 5.2 and any 0 < 1. For any R > 0, denote as well

$$E_R = f# 2 E j k#k_L **_0 + k#k_L **_1 W_x^{j1} Rg: t;x$$

We now dene the operator L on E that will have a xed point. For a given #i in E, we may use Theorem 5.2 to obtain solutions and u to (2)-(3), and satisfying the estimates

$$2 L_t^{1}L_x$$
; $u 2 L_t^{2}H_x^{1}$:

Hence and u satisfy all the conditions in Theorem 6.3. We may hence apply Theorem 6.3 to obtain # = $L(\#_i)$ that solves the various estimates listed in the statement of Theorem 6.3. In particular by (71), we immediately have, from the bounds (11) on , that

$$Z_{T}Z_{T^d}$$
 $(1 + j#j) \frac{jr_x#j^2}{\#^2} dx dt < 1: 0$

Since # 2 L_t^1 L_x^* as well, Poincare inequality immediately shows that # 2 $L_{t:x}$. Moreover we also have directly from the inequality above that # 2 $L_t H_x$. Hence for any 0 < < 1, we have that # 2 $L_t W^{1/2}$. This implies that L : E ! E.

We can also check that for any R > 0, the image $L(E_R)$ is pre-compact in E. Consider therefore any sequence $\#_n \ge E_R$. From the estimates in Theorem 5.2, we have that for some C_R and the $_n$; u_n obtained from $\#_n$ satisfy the uniform bound

$$\sup k \underset{t}{k} \underset{t}{l}_{t} \underset{x}{l} + \sup k u \underset{n}{k} \underset{n}{l}_{2} \underset{t}{l}_{1} K C : nR$$

Moreover Theorem 5.2 also implies that n is compact in $L_{t:x}$.

Consequently, the estimates (71) from Theorem 6.3 yields, also for some C_R

We next observe that the entropy inequation (74) provides a uniform control on $@_t(ns_n)$. We may indeed rewrite (74) as

$$@_{t}(_{n}s_{n}) + div(_{n}s_{n}u_{n}) + M_{n}(t;x) = r_{x} \underbrace{L(\#_{n})^{(L(\#_{n})\#_{n})} + L(\#_{n})}_{L(\#_{n})} \underbrace{S_{n} : \underline{1ru}_{n} + L(\#_{n})}_{L(\#_{n})^{2}}$$

where $s_n = s(n; L(\#_n))$ and M_n is a sequence of non-negative Radon measures. Hence by integrating in t and x, we have the bound

From (73) and (71), we deduce immediately that the total mass of M_n , as a measure in t and x, is uniformly bounded in n. Using again (73) and (71), this implies that Q_t (s_n)_n is uniformly bounded in $M_{t:x} + L_+^1 W_x^{1;1}$, with $M_{t:x}$ the set of Radon measures with bounded mass.

From the compactness of $_n$, the compactness in space of $L(\#_n)$, we have compactness in space for $_ns_n$ and now compactness in time. Up to extracting a subsequence, we can hence deduce the pointwise convergence of $_ns_n$. Following the same argument as in the proof of Theorem 6.3, and in particular assumption (18), this yields the pointwise convergence of $L(\#_n)$.

From the uniform bounds on $L(\#_n)$ in $L_{t;x}$, this in turn implies the compactness of $L(\#_n)$ in $L_{t;x}$. By interpolation between $L_{t;x}$ and $L_t^2 H_x^1$, we also obtain compactness in $L_t^1 W_x^{;1}$, showing that the image $L(E_R)$ is pre-compact.

The last and more delicate point to use the Leray-Schauder xed point is to show that there exists R s.t. for any #2 E with #=L(#) for L(#), we have that $\#2E_R$. For such #2E with #=L(#), we start with recalling from Theorem 5.2 that

$$Z = Z_{t}Z$$

 $(+ juj^{2}=2) dx + S : r_{x}u dx ds E(_{0}; u_{0})^{T^{d}}$
 $Z_{t}Z$
 $+ div_{x} u(s; x) (P(#(s; x); (s; x)) P_{0}((s; x))) ds dx: 0$

From the denition of P_0 ,

P
$$P_0 = {X^N \choose B_n (\#)} B_n)^n$$
:

Therefore the coecients in P P_0 behave in the same way as for P_n that we had used before and we may use (78) with

This implies that

Z
$$z_{t}Z$$
 $(+juj^{2}=2) dx + jr_{x}uj^{2} dx ds C + C k#k2 $z_{t}^{Td}$$

We will use as an intermediary object the function

It will be important to note that #(t) is continuous in time for a xed choice of #, even if it is of course not equi-continuous for all possible choices of #. On the other hand since # = L(#), any norm of # is bounded by the corresponding norm of L(#). Using the Poincare inequality (84), and since #, this proves that

for some < 1.

Therefore the norms of and u together with # are controlled through the corresponding norms of L(#),

$$Z = Z_{t}Z$$

$$(+ juj^{2}=2) dx + jr_{x}uj^{2} dx ds C_{\#}(t)$$

$$Z = \#$$

$$C^{2} + C^{2}T^{=2} sup_{t}L(\#)^{\#} dx$$

$$Z_{t}Z^{T}^{T} d$$

$$+ C_{T} (L(\#))^{j}rL(\#)^{2}dx dt; 0 T^{d}$$

where the constant C depends only on the initial data and more precisely the initial total energy. Turning to Theorem 6.3, we recall the important Energy equality (76) which implies that

$$Z$$
 Z_tZ $g(t;x) dx C + (S:ru Pe div u) dx ds$

for all time. Using again (78) and the Poincare inequality (84) together with (92) to control R jruj 2 , we obtain that

(93)
$$Z \sup_{T^{d}} g(t;x) dx C (T_{\#}) tT$$

$$Z = \#$$

$$C^{2} + C^{2} T^{=2} \sup_{T^{d}} L(\#)^{\#} dx$$

$$Z_{T} Z^{t} T^{d} (L(\#)) \frac{jrL(\#)j^{2}}{L(\#)^{2}} dx dt : 0$$

From (79), this shows that

On the other hand, since s C g, we also obtain by integrating the inequation (74), and by combining the result with (93) and the previous inequality, we nally obtain the critical estimate

$$Z \qquad Z_{T} Z \\ \sup_{T^{d}} (L\#)^{\#}(t;x) dx + (L(\#))^{\frac{1}{2}} \frac{1}{L(\#)^{2}} dx dt C (t)_{\#}T \\ \qquad \qquad Z \qquad !_{=\#}$$

$$(94) \qquad C^{2} + C^{2} T^{=2} \qquad \sup_{tT = T^{d}} L(\#)^{\#} dx \\ \qquad \qquad Z_{T} Z \\ \qquad \qquad + C_{T} \qquad (L(\#))^{\frac{1}{2}} \frac{1}{L(\#)^{2}} dx dt : 0$$

Of course < 1 but unfortunately we only have 2 # so that we could have that = # > 1, which prevents us from concluding at once and forces us to employ a much more careful argument. The key point is to use the time continuity of # dened in (91). Since < 1, denote

$$M = \sup_{X>0} C_{T=1} X$$
 $X=2;$

and

$$= 2C + 3C_{T=1}C^2 + 2C_{T=1}M$$
:

Assuming that =_# > 1, we choose T 1 s.t.

$$T^{=2}(C)^{=\#} < min(1=2; 1=2C)$$
:

From the continuity of $_{\#}(t)$ in time, we may dene t_0 T the largest time s.t. $_{\#}(t)$. From (94), we also have that

$$Z \sup_{\mathsf{T}^d} (\mathsf{L}\#)^\#(\mathsf{t};\mathsf{x}) \, \mathsf{d}\mathsf{x} \; \mathsf{C} : \mathsf{tt}_0$$

From using a second time (94), we deduce that

$$Z_T Z$$
 (L(#)) $\frac{j_T L(\#)j^2}{L(\#)^2} dx dt 2C^2 + 2C^2 T^{=2}(C)^{=\#} + 2M < 3C^2 + 2M:0$ T^d

However at t = T, taking again (94) now implies that

$$_{\#}(T) C + C T^{=2}(C)^{=_{\#} 1} + C_{T=1}(3C^{2} + 2M) < 2C + 3C_{T=1}C^{2} + 2C_{T=1}M = :$$

This shows that $t_0 = T$ and yields a corresponding bound on L(#) in $L_t^1 = L^\#$ and in $L_{t,x}$ in terms of the initial energy. The same argument that we used at the beginning of the proof then show that $L(\#) \ge E_R$ for some R depending only on the initial energy. Since # = L(#), we also have that $\# \ge E_R$ and we have checked all assumptions of the Leray-Schauder xed point theorem. Consequently, for this choice of T, there exists a xed point $\# \ge E_R$ s.t. # = L(#).

We hence obtain a solution (; u; #) to (2), (3) and the entropy inequation (20) on [0; T]. By combining the estimates in Theorems 5.2 and 6.3, we also recover all a priori estimates in Theorem 1.1

and it only remains to derive the global energy bound to have Theorem 1.1 on [0; T]. We rst add the energy bounds (41) given by Theorem 5.2 and (76) given by Theorem 6.3.

Z Z
$$_{t}$$
Z Z $_{t}$ Z Z $_{t}$ Z $_{t}$ C $_{t}$

By recombining the terms, we obtain that

as we can easily recognize the total energy E of the system. We also emphasize that it was critical in the formulations of both Theorem 5.2 and Theorem 6.3 that the terms P P₀ and Pedo not contain, as we would not be able to make sense of div u. However since n =2, we have no diculty in handling div u n. In particular, we may easily remove the ⁿ terms from (95) through the use of renormalized solutions. Since 2 Lt:x and u 2 Ht:x, the classical theory of renormalized solutions, from [4] for example, shows that for any smooth, bounded function f(), we have in the sense of distributions that

$$@_tf() + div(uf()) = (f() f^0()) div u$$
:

Since 2 L_t 1L and div u 2 $L_{t,x}$? we may now apply this to a sequence f_{-} with $f_{-}(x)$! x^n as "! 0 and

$$_{T^d}^n dx = _{T^d}^{(0)^n} dx \qquad (n \quad 1) \quad \int_{0}^{t} _{T^d}^n div u(s; x) dx ds;$$

$$E(; #; m) dx T^d E(_0; #_0; m_0) dx$$

The last remaining point is to extend this solution on [0; T] to a solution that is global in time. This is naturally achieved by repeating the xed point argument starting from T. To do so, we highlight the conditions on the initial data that Theorem 5.2 and Theorem 6.3 require: one needs $\#^0$ 2 $_x$ L $^\#$, 0 2 $_x$ together with 0 ju 0 j 2 2 L 1 . Equivalently, we can require E(0 ; u 0 ; $\#^0$) < 1. Indeed from (79), we have that Z Z Z Z $_x$ juj 2 dx + dx + $_x$ dx + $_$

$$Z$$
 Z Z $Juj^2 dx + dx + ## dx C E(0; #0; m0): Td$

or again equivalently $E(0; \#_0; m_0)$. From the propagation of energy, we have that $E(; \#; m)_{j_{t=1}}$ is dominated by $E(_0; \#^0; m_0)$ and therefore the existence time T can be chosen uniformly whether starting at t = 0, t = 0T or t = 2T. This ensures global existence.

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