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# A Data Mining Transmission Switching Heuristic for Post-Contingency AC Power Flow Violation Reduction in Real-World, Large-Scale Systems

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## Abstract

Transmission switching has proven to be a highly useful post-contingency recovery technique by allowing power system operators increased levels of control through leveraging the topology of the power system. However, transmission switching remains only implemented in limited capacity because of concerns over computational complexity, uncertainty of performance in AC systems, and scalability to real-world, large-scale systems. We propose a heuristic which uses a sophisticated guided undersampling procedure combined with logistic regression to accurately identify transmission switching actions to reduce post-contingency AC power flow violations. The proposed heuristic was tested on real-world, large-scale AC power system data and consistently identified optimal or near optimal transmission switching actions. Because the proposed heuristic is computationally inexpensive, addresses an AC system, and is validated on real-world large-scale data, it directly addresses the aforementioned issues regarding transmission switching implementation.

**Keywords:** Corrective transmission Switching, Contingency analysis, Large-scale power systems, Heuristics, Data mining

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## 1. Introduction

2 The robustness of the electrical power grid is one of the most vital fea-  
3 tures of our critical infrastructure. Therefore, research efforts which accurately  
4 model operation of the grid and validate its robustness are of great importance  
5 going forward. In particular, methods concerning post-contingency operations  
6 are noteworthy because they mitigate the harm which the grid may undergo  
7 following component failure. One notable analytical technique is contingency  
8 analysis, which allows operators to study the impacts of various contingencies  
9 and develop corrective measures which may be applied should such a failure  
10 occur. One example of a post-contingency corrective measure is transmission  
11 switching, also known as topology control, which we herein study.

12 In the past, the power grid has been modeled using a fixed configuration  
13 (Dehghanian et al., 2015). Using such a modeling paradigm, control on the grid  
14 is exerted only by making dispatch decisions. However, transmission switching  
15 allows system operators an additional method of control by physically switching  
16 transmission lines in and out of the grid. Previous research has demonstrated  
17 that transmission switching has a myriad of potential benefits. In one of the  
18 initial papers on the technique, Fisher et al. (2008) showed that transmission  
19 switching can produce significant reductions in generation fuel costs. Other  
20 works have echoed this conclusion with focuses on sensitivity analysis (Hed-  
21 man et al., 2008; Ruiz et al., 2012) and contingency analysis (Hedman et al.,  
22 2009). In addition to cost, transmission switching has demonstrated usefulness  
23 in preventing loadshed (Escobedo et al., 2014; Dehghanian et al., 2015; Brown &  
24 Moreno-Centeno, 2020), improving system reliability (Korad & Hedman, 2013),  
25 and, as studied herein, reducing post-contingency violations (Li et al., 2017).

26 The herein studied problem, optimal transmission switching, lies within a  
27 class of computationally complex optimization problems in the area of power  
28 systems planning and operations. These problems are of substantial interest to  
29 the operations research community because of their challenging nature and their

30 clear value to practitioners. Important recent work on transmission switching  
31 in particular includes novel formulations and valid inequalities (Kocuk et al.,  
32 2016), development of techniques to solve for transmission switching actions un-  
33 der stochastic conditions (Pichler & Tomaskard, 2016), application of transmis-  
34 sion switching within the unit commitment problem (Schumacher et al., 2017),  
35 and accounting for variable renewable energy sources (Cavalheiro et al., 2018).  
36 A problem fundamentally related to transmission switching is transmission ex-  
37 pansion planning (TEP), wherein optimal solutions suggest new transmission  
38 lines to be invested in and added to the power grid. Skolfield et al. (2022)  
39 derived path-based valid inequalities to ease the difficulty in solution of TEP,  
40 Ghaddar & Jabr (2019) solved TEP using semidefinite programming, and Mor-  
41 eira et al. (2021) developed a three-stage approach to solve TEP under climate  
42 uncertainty.

43 There are other problems in power systems planning and operations which  
44 are of similar interest to the operations research community. Such problems in-  
45 clude power generation expansion, similar to TEP, wherein new generators are  
46 added to the power system (Lohmann & Rebennack, 2017; Pineda & Morales,  
47 2016). Another related problem is in the planning and application of power  
48 grid defense Alguacil et al. (2014), in which transmission lines identified as crit-  
49 ical are hardened from malicious or weather-related events. A third problem  
50 of interest is the optimal phasor measurement unit placement problem (Car-  
51 valho et al., 2018), which seeks to give full real-time visibility of the network at  
52 minimum cost. A class of problems regularly-studied by the operations research  
53 community are the unit commitment and security-constrained unit commitment  
54 problems, wherein generators are scheduled for operations either with or with-  
55 out consideration of potential critical contingencies (Lorca et al., 2016; Zheng  
56 et al., 2013, 2016; Zuniga Vazquez et al., 2022). Finally, a recent topic of interest  
57 from the academic community is in relation to electric vehicles, wherein oper-  
58 ations research techniques can be used to account for power system operations  
59 impacted by vehicle charge and discharge scheduling (Umetani et al., 2017), in-  
60 ventory management (Sun et al., 2019), and relocation (Gambella et al., 2018).

61 We refer the reader to the work by Skolfield & Escobedo (2022), which provides  
62 a robust literature review on applications of operations research techniques in  
63 power systems.

64 This work develops a data mining method which identifies transmission  
65 switching actions to reduce post-contingency voltage magnitude and branch  
66 flow violations. The use of transmission switching to alleviate violations has  
67 been an issue of academic interest over recent years. Balasubramanian et al.  
68 (2016) analyzed switching actions by a major ISO for this expressed purpose.  
69 Zhao et al. (2019) developed a decomposition-based methodology to identify  
70 optimal switching actions to reduce violations in light-load settings. Khodaei  
71 et al. (2010) utilized transmission switching to alleviate violations within the  
72 context of security-constrained unit commitment. Li et al. (2020) developed  
73 sensitivity-based factors to identify switching actions to relieve violations. Shen  
74 et al. (2019) developed a multi-stage approach to reduce voltage violations with  
75 transmission switching. Most noteworthy to this work is (Li et al., 2017), in  
76 which several heuristics to identify switching actions to reduce violations were  
77 developed on real-world, large-scale power system data.

78 The proposed methodology applies a guided undersampling method pro-  
79 posed by (Sung et al., 2022) and then utilizes logistic regression to identify  
80 post-contingency transmission switching candidates to reduce AC power flow  
81 (ACPF) violations. Notably, these data mining methods are computationally  
82 inexpensive and can be quickly executed on real-world AC power system data,  
83 providing greater certainty regarding *both* AC system performance and large-  
84 scale implementation. This is notable because it addresses three of the four  
85 explanations mentioned in (Li et al., 2017) as to why transmission switching is  
86 currently being used only in limited capacity: computational complexity, uncer-  
87 tainty of impact on real-world large-scale power systems, uncertainty of impact  
88 when moving from DC to AC, and transient stability. These four items are  
89 substantiated in detail in the following paragraphs.

90 **1 – Computational complexity:** The first explanation for lack of widespread  
91 implementation of transmission switching is in regard to computational com-

plexity or, equivalently, the scalability of algorithms. Mixed-integer nonlinear programs (MINLPs), such as the AC optimal transmission switching (ACOTS) problem, are notoriously difficult to solve. Because of this, researchers have primarily tested algorithms on small-scale networks and/or used linearizations to reduce the difficulty of the problem, which cast uncertainty over scalability and solution accuracy, respectively. These two approaches are discussed in greater detail in the following two paragraphs.

**2 – Impact on large-scale systems:** The second explanation is that the overwhelming majority of research on transmission switching studies small-scale systems. A handful of noteworthy research projects have vetted their approaches on large-scale systems. Works relevant to the herein studied problem include (Li et al., 2016, 2017, 2020; Shen et al., 2019) which each utilize transmission switching at a large scale to reduce violations. There have been other noteworthy research efforts which study real-world electric power systems but are not directly applicable to the application discussed here. Carrión et al. (2021) study a related problem of optimal static VAR compensator location at a large scale. Li et al. (2021) extend the traditional DC optimal transmission switching model with connectivity constraints and test on a large-scale system. Ramesh et al. (2021) utilize a decomposition technique to study the security-constrained unit commitment problem with switching and test their results on the Polish test system. Other recent noteworthy projects which utilize real-world sized test cases include (Han et al., 2022a; Mohseni-Bonab et al., 2022; Altun et al., 2020).

In contrast with the above, most works, including the bulk of works cited herein, test their approaches on small-scale systems such as the IEEE 118-bus test case which appear in test case archives such as (Christie, 2000). Real-world systems, however, have up to tens of thousands of buses, obscuring both the impact of complexity and scalability of current approaches. Given that most algorithms are tested on small systems, it remains unclear if these algorithms can be applied in the real world.

**3 – Impact on AC systems:** The third item addresses the concern that

123 benefits derived from DC-based models may not translate to AC models. Be-  
124 cause of the issues associated with solving problems such as the ACOTS, the  
125 majority of transmission switching research focuses on DC-based models. In-  
126 deed, excluding noteworthy examples (Soroush & Fuller, 2014; Bai et al., 2017;  
127 Li et al., 2017, 2016; Kocuk et al., 2017; Shi & Oren, 2015), the papers herein  
128 cited use linearizations to address the various transmission switching problem  
129 variants. This is worrisome because, as demonstrated in (Potluri & Hedman,  
130 2012), transmission switching actions identified by DC models may be infeasible  
131 or result in negative outcomes when implemented in AC systems. Moreover, as  
132 aforesaid, most if not all of these models are only tested on unrealistically small  
133 networks, further clouding the issue of whether conclusions derived from DC  
134 models can be applied to AC systems.

135 **4 – Transient stability** Finally, we note that relatively recent research has  
136 shown that transmission line switching may introduce disturbances into power  
137 systems resulting in transient instability issues (Liu et al., 2011). Despite this  
138 fact, the overwhelming majority of research in this area fails to account for tran-  
139 sient stability. There are a small group of noteworthy exceptions. Alhazmi et al.  
140 (2019) analyze the implications regarding stability and reliability of their trans-  
141 mission switching solutions, but do not account for them within the algorithm  
142 itself. Shi et al. (2019) introduce simple transient security constraints into a two-  
143 stage switching model. Han et al. (2022b) incorporate qualitative constraints to  
144 seek stability maintenance into their topology control model. Mak et al. (2017)  
145 propose a novel optimization model which incorporates constraints to seek tran-  
146 sient stability and an algorithm which incorporates their new model to further  
147 ensure stability. While the above works take steps to reduce concerns regarding  
148 transient stability, to the authors knowledge, the methods described by (De-  
149 hghanian et al., 2015) and (Mak et al., 2017) are the only ones to systematically  
150 verify stability within the algorithm itself. Moreover, the framework proposed  
151 in (Dehghanian et al., 2015) can be combined with virtually any approach.

152 This work makes three primary contributions. First, to the authors' knowl-  
153 edge, our proposed heuristic is the first true data mining technique to classify

154 strong AC transmission-switching actions using power flow information rather  
155 than a simple history of useful switching actions. Second, our method is unique  
156 in the literature in that it directly addresses three of the four issues regarding  
157 transmission switching implementation. Moreover, it can be directly combined  
158 with the framework in (Dehghanian et al., 2015) to address the fourth  
159 issue. Finally, we make a much stronger empirical analysis than the analysis de-  
160 scribed in (Li et al., 2017), studying the impact of an exhaustive set of switching  
161 actions on real-world large-scale power system data, rather than a small subset  
162 of the actions or actions across a small system. A secondary contribution of this  
163 work is that we formalize the problem characterized in (Li et al., 2017).

164 We note that, in recent years, several papers claim to use “previous knowl-  
165 edge” in the context of a data mining framework, but fail to do so in the way  
166 data mining is understood. The authors in (Li et al., 2016) propose a heuristic  
167 where a lookup table containing contingency-specific switching solutions is used  
168 to select potential switching candidates. The authors in (Hedman et al., 2009)  
169 propose a similar heuristic where previously-successful switches are considered  
170 as potential switching actions. Finally, the authors in (Li et al., 2017) extend  
171 the approach in (Hedman et al., 2009) by splitting previously-successful switches  
172 into training and testing sets; these switches are subsequently validated accord-  
173 ingly. However, this method does not incorporate any additional information  
174 other than the switching action itself.

175 In contrast with the above methods, the herein proposed method incorpo-  
176 rates information about the current status of the grid into a sophisticated data  
177 mining method to predict the *impact* of a given candidate switching action.  
178 Succinctly, the resulting method is a true data mining approach which exploits  
179 the set of available information to identify candidate switching actions.

180 The remainder of this paper is organized as follows. Section 2 presents and  
181 describes two optimization models for post-contingency ACPF violation reduc-  
182 tion. Section 3 proposes our data mining heuristic using guided undersampling  
183 and logistic regression. Section 4 discusses the experimental setup and several  
184 implementation issues which are inherent to the proposed methodology and the

185 herein studied problem. Section 5 presents our analysis and demonstrates that  
186 our proposed method identifies optimal and near-optimal switching solutions  
187 and is superior to existing heuristics based on distance to violation elements.  
188 Section 6 concludes the work.

189 **2. ACPF Violation Reduction Optimization Model with Transmis-**  
190 **sion Switching**

191 During post-contingency operations, system operators must be provided  
192 with corrective actions which are both quick to identify and can be implemented  
193 with confidence. We note that the execution of transmission switching to alle-  
194 viate power system violations may represent a decreased burden on the system  
195 operator than actions such as a generation re-dispatch (Li et al., 2017). As  
196 an example, ISO New England lists twelve actions to return the system to  
197 “normal” status. These actions, in order listed by ISO New England, are as  
198 follows: adjusting phase shifting transformers, adjusting reactive power flows,  
199 enacting weather-sensitive transmission facility ratings, deviation from economic  
200 dispatch, opening of circuit breakers, manually tripping generators, transmis-  
201 sion switching, exceeding generator maximums, load curtailment, capacity pur-  
202 chases, depletion of temporary reserves, and enacting enhanced facility ratings  
203 (ISO New England, Sep. 2022). It is frequently to the benefit of the system  
204 operator to avoid any of the above actions associated with a computationally  
205 expensive re-dispatch, particularly in the context of contingency response. In  
206 contrast, transmission switching, particularly when executed within the con-  
207 text of a data mining approach such as the one proposed herein, represents a  
208 computationally inexpensive solution to returning the grid to a violation-free  
209 status.

210 One of the traditional manners to derive corrective actions, and in particular  
211 transmission switching actions, is through the solution of optimization models  
212 such as those described in this section. As such, we herein describe the math-  
213 ematical formulation of the ACPF optimization model for violation reduction

214 with transmission switching (ACPF-VR-TS). Note that these problems were  
 215 described qualitatively by the authors in (Li et al., 2017). However, this work  
 216 is the first to formally characterize these problems as optimization models.

217 *2.1. ACPF-VR-TS for Voltage Magnitude Violations*

The ACPF-VR-TS model for voltage magnitude violation reduction is characterized as follows. We note that the notation utilized in this and the forthcoming subsection is defined in Appendix A.

$$\min \sum_{n \in N} V_n^+ + V_n^- \quad (1a)$$

subject to

$$P_i^g - P_i^d = \sum_{\langle i, j \rangle \in K} p_{ij} \quad i \in N \quad (1b)$$

$$Q_i^g - Q_i^d = \sum_{\langle i, j \rangle \in K} q_{ij} \quad i \in N \quad (1c)$$

$$p_{ij} = Z_{ij}(g_{ij}V_i^2 - V_iV_j(g_{ij} \cos \theta_{ij} + b_{ij} \sin \theta_{ij})) \quad \langle i, j \rangle \in K \quad (1d)$$

$$q_{ij} = Z_{ij}(b_{ij}V_i^2 - V_iV_j(g_{ij} \sin \theta_{ij} - b_{ij} \cos \theta_{ij})) \quad \langle i, j \rangle \in K \quad (1e)$$

$$V_n^- \geq V_n^{\min} - V_n \quad n \in N \quad (1f)$$

$$V_n^- \geq 0 \quad n \in N \quad (1g)$$

$$V_n^+ \geq V_n - V_n^{\max} \quad n \in N \quad (1h)$$

$$V_n^+ \geq 0 \quad n \in N \quad (1i)$$

$$\sum_{\langle i, j \rangle \in K} 1 - Z_{ij} = 1 \quad (1j)$$

218 Objective (1a) minimizes the sum of voltage magnitude violations. Constraints  
 219 (1b) and (1c) model active and reactive power injections at bus  $i$ , respectively.  
 220 Constraints (1d) and (1e) model the flow of active and reactive power from  
 221 bus  $i$  to bus  $j$ , respectively, while accounting for transmission switching. Note  
 222 that fixing all binary variables  $Z_{ij}$  to 1 reduces constraints (1b)-(1e) to the  
 223 constraints which characterize the ACPF. Constraints (1f) and (1g) model the  
 224 violation of the voltage magnitude lower bounds. Constraints (1h) and (1i)  
 225 model the violation of the voltage magnitude upper bounds.

226 Finally, Constraint (1j) dictates that the number of allowable transmission  
 227 line switches is equal to one. There are two primary practical explanations for

228 this constraint. First, significant concerns exist regarding transient stability  
 229 with multiple switching actions. Second, physical implementation of transmis-  
 230 sion switching requires substantial effort. This effort magnifies as the number  
 231 of switches increases. We refer the reader to (Brown & Moreno-Centeno, 2020)  
 232 for a detailed discussion on these two topics.

233 *2.2. ACPF-VR-TS for Branch flow Violations*

The ACPF-VR-TS model for branch flow violation reduction is characterized as follows.

$$\min \sum_{\langle i,j \rangle \in K} f_{ij} \quad (2a)$$

subject to

$$(1b)-(1e), (1j) \quad (2b)-(2e), (2j)$$

$$f_{ij}^i \geq p_{ij}^2 + q_{ij}^2 - S_k^2 \quad \langle i, j \rangle \in K \quad (2f)$$

$$f_{ij}^j \geq p_{ji}^2 + q_{ji}^2 - S_k^2 \quad \langle i, j \rangle \in K \quad (2g)$$

$$f_{ij} \geq f_{ij}^i \quad \langle i, j \rangle \in K \quad (2h)$$

$$f_{ij} \geq 0 \quad \langle i, j \rangle \in K \quad (2i)$$

234 Objective (2a) minimizes the sum of branch flow violations. Constraints  
 235 (2f) and (2g) model violation of thermal limits as a function of apparent power.  
 236 Constraint (2h)-(2i) dictates that the flow violation for transmission line  $k$  is  
 237 equal to either zero or the larger of the two violations at each end of the line.

238 **3. Methodology**

239 Traditionally speaking, optimal transmission switching actions are sought  
 240 out by characterizing the power system in a steady state. That is, an optimal  
 241 power flow (OPF) or optimal transmission switching (OTS) model is solved,  
 242 and the switching actions are either obtained directly from the solution (when  
 243 using OTS) or further derived from the solution (when using OPF). However,  
 244 as discussed in Section 1 the solution of MINLPs is exceedingly computationally

245 expensive. When considered in the context of real-time operations, this com-  
246 putational cost is unlikely to be to be satisfied. As such, less computationally-  
247 intensive methods are required, such as the one proposed in the forthcoming  
248 paragraphs.

249 It is important to note that, as in (Li et al., 2017), we do not solve the  
250 models outlined in Section 2 via the use of an optimization solver. The primary  
251 reason for this is because of the computational difficulty associated with solving  
252 MINLPs. As such, most work addressing problems similar to those in Section  
253 2 either use linearizations or solve across small systems. In contrast, this work  
254 seeks solutions to these models via a data mining-based heuristic in a manner  
255 tractable at a large scale without linearization. The following two paragraphs  
256 discuss an important feature of transmission switching which contextualizes the  
257 problem within a data mining framework – imbalanced data. Following this,  
258 we present our dual-component guided undersampling method, introduce the  
259 classification methodology, and formalize the proposed method.

260 It is well established in the literature that, regardless of objective (e.g., vi-  
261 olation reduction or cost savings), there are typically only a small number of  
262 transmission switching actions which result in a substantial objective improve-  
263 ment. Thus, in a data mining context, identifying strong transmission switching  
264 actions should be viewed as an imbalanced-data classification problem. In a two-  
265 class setting, imbalanced data refers to a dataset where one class (the majority  
266 class) has cardinality substantially larger than that of the opposing (minority)  
267 class. In such settings, traditional classification algorithms can suffer poor per-  
268 formance because they can simply classify all instances as majority and still  
269 achieve a high classification rate. Therefore, when developing a data mining  
270 approach for transmission switching, one must take care to adequately handle  
271 the problems inherent to imbalanced data.

272 The proposed methodology addresses the imbalanced data problem as fol-  
273 lows. First, we utilize a guided undersampling procedure (Sung et al., 2022)  
274 which undersamples the majority class using two instance-selecting techniques.  
275 The first technique, ensemble outlier-filtering, utilizes a unique ensemble classi-

276 fier to remove both majority and minority outliers from the training data. The  
277 second technique, normalized-cut sampling, undersamples the majority class  
278 such that the density distribution of the majority class is preserved. After our  
279 guided undersampling method, we apply logistic regression to develop the clas-  
280 sification boundary; i.e., to predict which transmission lines are strong candi-  
281 dates. The following subsections detail each of the components of the proposed  
282 methodology.

283 *3.1. Ensemble Outlier-Filtering*

284 The first component of the guided undersampling method used herein is en-  
285 semble outlier-filtering. From a data-analytic perspective, outlier removal is a  
286 critical component of building an effective classifier. However, when the training  
287 data is imbalanced, many outlier filtering techniques demonstrate poor perfor-  
288 mance. To address this, the authors in (Sung et al., 2022) proposed an ensemble  
289 outlier-filtering technique which utilizes the power of an ensemble classifier in  
290 which each training set is balanced. The ensemble outlier-filtering technique is  
291 described as follows. Note that, throughout the remainder of this section, an  
292 important value is the ratio of majority instances to minority instances, known  
293 as the imbalance ratio.

294 Given a set of  $n$ -dimensional data  $X = X_{\text{maj}} \cup X_{\text{min}}$ , with imbalance ratio  
295  $r = \frac{|X_{\text{maj}}|}{|X_{\text{min}}|}$ , ensemble outlier-filtering proceeds as follows.

- 296 1. Partition the majority class  $X_{\text{maj}}$  into  $r$  subsets of equal size, where each  
297 subset has cardinality  $|X_{\text{min}}|$ . Construct  $r$  distinct training subsets:  $X_{\text{min}}$   
298 and one subset of  $X_{\text{maj}}$ .
- 299 2. Train  $r$  logistic regression classifiers, one for each subset of the training  
300 data.
- 301 3. Predict the class of every instance in  $X$  using the majority voting scheme:  
302 instance  $X_i$  is assigned to a class if it is predicted as such by at least  $\frac{r}{2}$   
303 classifiers.
- 304 4. Remove from the training data the outliers – instances whose predicted  
305 class differs from their true class.

306 One salient characteristic of the method described above is that it seeks to  
307 remove both minority and majority from the training data. While the removal  
308 of minority data may appear counterintuitive, as shown in (Sung et al., 2022),  
309 it is critical to strong imbalanced data classification performance.

310 *3.2. Normalized-Cut Sampling*

311 One traditional approach to imbalanced data classification is majority sub-  
312 sampling, in which a subset of the instances from the majority class is selected  
313 from the training data in an effort to address class imbalance. However, as  
314 described in (Sung et al., 2022), the user must take great care to construct their  
315 majority subsample, as they risk an inaccurate decision boundary if there are  
316 regions where the density distribution of the greater majority class does not  
317 persist. To address this, the authors in (Sung et al., 2022) proposed a new  
318 technique, normalized-cut sampling. This method utilizes the normalized-cut  
319 segmentation technique proposed in (Shi & Malik, 2000) to iteratively cluster  
320 the majority class such that the density distribution is preserved and the num-  
321 ber of majority-class clusters is equal to the cardinality of the minority class.  
322 The medoids of the clusters are then selected as the majority class subsample.

323 Given training data  $X = X_{\text{maj}} \cup X_{\text{min}}$ , with  $k = |X_{\text{min}}|$ , the normalized-cut  
324 sampling procedure is described as follows.

1. Construct graph  $G_1 = (V, E)$ , where  $V$  denotes all majority instances and  
 $E$  contains edges between all node pairs in  $V$ . Set edge weights between  
node pair  $(i, j)$  as

$$\mathcal{L}_{ij} = \exp(-\| \mathbf{X}_i - \mathbf{X}_j \|^2) \quad (3)$$

2. Initialize an empty set  $C$ .
3. For  $i = 1 \dots k$ 
  - (a) Utilizing the procedure from (Shi & Malik, 2000), bipartition  $G_i$  into  
clusters  $C_i^1$  and  $C_i^2$ . Add these two clusters to  $C$ .
  - (b) Construct  $G_{i+1}$  using the instances from the cluster in  $C$  with max-  
imum cardinality ( $C_{\text{max}}$ ).

<sup>331</sup> (c) Update  $C = C \setminus C_{\max}$ .

<sup>332</sup> 4. Form the majority subsample with the medoids of the clusters in  $C$ .

<sup>333</sup> *3.3. Logistic Regression*

Logistic regression is a classification model which estimates the probability that a given categorical dependent variable belongs to a particular category (James et al., 2013). Given two categories, denoted numerically as 0 and 1, and a set of  $n$ -dimensional data  $\mathbf{X}_i$  with target variable  $Y_i \in \{0, 1\}$ , the logistic regression model estimates the probability that the target variable is in category 1 as

$$P(Y_i|\mathbf{X}_i) = \frac{e^{\beta_0 + \sum_{j=1}^n \beta_j X_i^j}}{1 + e^{\beta_0 + \sum_{j=1}^n \beta_j X_i^j}}, \quad (4)$$

where  $\beta_0$  is the intercept of the regression function and  $\beta_j$  is the multiplicative regression coefficient associated with the  $j$ -th dimension of the data. The regression coefficients are those which maximize the log-likelihood function

$$\begin{aligned} \ln L(\beta|Y) &= \sum_{i=1}^m Y_i \ln P(Y_i|\mathbf{X}_i) \\ &+ \sum_{i=1}^m (1 - Y_i) \ln(1 - P(Y_i|\mathbf{X}_i)), \end{aligned} \quad (5)$$

<sup>334</sup> where  $m$  denotes the number of observations in the data set.

<sup>335</sup> Note that the output of the logistic regression model from Equation (4) is the <sup>336</sup> probability that a given datum  $\mathbf{X}_i$  belongs to the class of focus. In our case, this <sup>337</sup> value can be interpreted as the probability that a transmission switching action <sup>338</sup> results in a substantial reduction in post-contingency violation. Therefore, we <sup>339</sup> use this probability to rank the set of all transmission lines.

<sup>340</sup> *3.4. Proposed Methodology*

<sup>341</sup> The previous subsections detailed the two components of the guided under-<sup>342</sup> sampling method as well as a specific classification methodology. Given training <sup>343</sup> data  $X = X_{\text{maj}} \cup X_{\text{min}}$ , the proposed method is formalized as follows.

<sup>344</sup> 1. Apply ensemble outlier-filtering to the training data  $X$  to obtain the clean <sup>345</sup> subsample  $X' = X'_{\text{maj}} \cup X'_{\text{min}}$

346        2. Apply normalized-cut sampling to  $X'_{\text{maj}}$  to further subset the majority  
 347        class and obtain  $X''_{\text{maj}}$ , where  $|X''_{\text{maj}}| = |X'_{\text{min}}|$   
 348        3. Train a logistic regression model on the clean and balanced training data  
 349         $X''_{\text{maj}} \cup X'_{\text{min}}$  to derive the classification model

350        The logistic regression model which is trained in Step (3) can then be uti-  
 351        lized as follows. Given an  $m \times n$ -dimensional data set where  $m$  is the number  
 352        of transmission lines and  $n$  denotes the number of variables describing post-  
 353        contingency ACDF information, the model trained in Step (3) can be directly  
 354        applied to such data to predict which transmission lines are strong switching  
 355        candidates. We elaborate on this process in the following section.

356        From a practical setting, the above-proposed methodology can be imple-  
 357        mented as follows. The model should be trained and validated in an off-line set-  
 358        ting to account for the computational time associated with the dimensionality  
 359        of the data. Following this, whenever a contingency occurs, a post-contingency  
 360        state should be established. The ISO can then gather the system information  
 361        associated with this post-contingency state. This system information can be fed  
 362        into the model as described above, each viable switching action predicted for  
 363        impact, and the superior switching action implemented.

364        **4. Experimental Setup**

365        *4.1. Test Case*

366        The test case utilized for analysis herein consists of emergency management  
 367        system snapshots from the Pennsylvania New Jersey Maryland Interconnection  
 368        (PJM). These snapshots span 167 hours, each with a different load profile, and  
 369        total of 8064 critical contingencies across the entire test case. For a detailed  
 370        description on how these contingencies were identified, we refer the reader to  
 371        (Li et al., 2017). The PJM system consists of approximately 15,500 buses,  
 372        2,800 generators, and 20,500 transmission lines. The total active power load is  
 373        approximately 139 GW and the total reactive power load is approximately 22  
 374        GW.

375 *4.2. Data Development*

376 *4.2.1. Exhaustive Search of Switching Actions*

377 To develop the training data which drives the predictive model, we per-  
378 formed an exhaustive search (henceforth referred to as the “exhaustive search”)  
379 of non-radial transmission switching actions across all critical contingencies from  
380 (Li et al., 2017) as described in the following paragraph. Because it is indeed  
381 exhaustive, this search guarantees that, for each contingency, we will identify  
382 the switching action that reduces the most violations (i.e., the optimal switching  
383 action). This is a salient point which allows this work to be the first to conduct  
384 a thorough analysis using the true optimality gap (as defined in Section 5.1) for  
385 the herein studied heuristics and for a problem of this size. We note that the  
386 exhaustive search is conducted using a series of AC power flow solutions before  
387 and after a switching action has occurred. The analysis of such actions allow for  
388 the data mining approach proposed in Section 3.4 to identify strong switching  
389 actions in seconds, rather than via an optimization methodology, dramatically  
390 reduce the computational cost associated traditional approaches as discussed in  
391 Section 3.

392 We perform the exhaustive search for each hour and critical contingency.  
393 For contingencies which did not include generator failure, all generator outputs  
394 remained at the pre-contingency level with the exception of the slack bus. For  
395 contingencies which simulate generator failure, re-dispatch was performed using  
396 a participation factor as outlined in (LI et al.). Finally, only a single corrective  
397 line switch is implemented. The procedure utilized to generate the data is thus  
398 described in the following steps. Given a power system instance with  $n$  non-  
399 radial lines, the exhaustive search proceeds as follows.

- 400 1. Run ACPF using given input data
- 401 2. Simulate contingency
- 402 3. Calculate re-dispatch (if necessary)
- 403 4. Run ACPF
- 404 5. Record system information

405 6. For  $i = 1 \dots n$

406 (a) Perform line switch

407 (b) Run ACPF

408 (c) Record remaining violation magnitude (if any)

409 Note that, in Steps (5) and (6c), information gathered includes both voltage  
410 magnitude and branch flow violations. As such, the exhaustive search generates  
411 data for both problems outlined in Section 2. The exhaustive search outlined  
412 above was run systematically to include all critical contingencies identified in  
413 (Li et al., 2017) and all feasible line switches. Doing so yields a rich data set  
414 which can be exploited via the use of data mining techniques.

415 *4.2.2. Data Features*

416 There are several important pieces of data collected during step (5) which  
417 drive the prediction methodology. The first set of features describes the switch-  
418 ing element. This set includes branch resistance, reactance, susceptance, ther-  
419 mal rating, and active and reactive power flow. Next, we gathered the mag-  
420 nitude of all violations within a set of distances, calculated using undirected  
421 distance, around the switching element. The third group of data we gathered  
422 were characteristics of the violation elements including bus type, active and re-  
423 active power demand, node degree, resistance, reactance, MVA rating, active  
424 power flow, and reactive power flow. Next, we measured the undirected distance  
425 from the switching element to each violation element, the distance from each  
426 violation element to the contingency element, and the distance from the switch-  
427 ing element to the contingency element. Finally, we gathered distance data in  
428 a directed fashion, using the flow of active power to construct a directed graph.  
429 From this graph we identified distances identical to those described above.

430 We note that the model herein developed is sensitive to the set of features  
431 used to train it. As such, we conducted feature selection prior to training the  
432 model. We utilized the first 83 hours (approximately on half of the data set), to  
433 conduct a forward-stepwise procedure to select a set of features which minimized

434 the optimality gap. As such, all forthcoming experiments were conducted on  
435 the remaining 84 hours of data described in Section 4.1.

436 *4.2.3. Training Data*

437 To train the classification model outlined in Section 3, we took the top  
438 100 switching actions according to the exhaustive search for each hour, crit-  
439 ical contingency, and violation type. We took only the top 100 switches for  
440 three reasons. First, this allowed us to satisfy the memory requirements of the  
441 computational setup used to perform our experiments. Second, we note that  
442 even using the top 100 switching actions results in an imbalanced data set.  
443 Specifically, for voltage magnitude violations, approximately 2.5% of the top  
444 100 switches result in an optimality gap of less than ten percent. For branch  
445 flow violations, only 5.7% switches result in such an optimality gap. Finally, we  
446 note that it has been established in the literature that one successful approach  
447 to majority subsampling is to focus on regions where the majority and minority  
448 classes overlap (Japkowicz, 2000).

449 *4.3. Cross-Validation*

450 Cross-validation is imperative for the development of any predictive model to  
451 properly assess the model’s strength. However, it bears mentioning that cross-  
452 validation in this setting is different than in traditional contexts. In an effort  
453 to minimize bias from similar instances, each fold used during cross-validation  
454 consisted of all contingencies within a single hour out of the 84 hours used for  
455 testing as described in Section 4.2.2. The remaining data used to train the model  
456 consists of all contingencies within the remaining 83 hours. This resulted in an  
457 84-fold cross-validation procedure. On average, each cross-validation iteration  
458 took approximately 25.59 minutes for model training and testing. In addition,  
459 each contingency in the test fold was tested individually for the performance  
460 metric described in Section 5.1. That is, rather than a single data point for  
461 each fold, testing generates a number of data points equal to the number of  
462 contingencies within the given hour.

463 *4.4. Computational Environment*

464 All computational experiments herein described for data generation (Section  
465 4.2) were conducted in a distributed environment on computing nodes which had  
466 22GB of RAM shared by two 2.8 GHz quad core Intel 503 Xeon 5560 processors  
467 using Texas A&M University supercomputing resources. The operating sys-  
468 tem was CentOS Linux version 7.6.1810. All power flows were solved using the  
469 MATPOWER toolbox (Zimmerman et al., 2011). All tasks related to model de-  
470 velopment, feature selection, and cross-validation were conducted on a machine  
471 equipped with 8 GB of RAM memory and a quad-core 1.8 GHz Intel i7-8565U  
472 processor. Ensemble outlier-filtering, normalized-cut sampling, and logistic re-  
473 gression models were implemented using the LIBLINEAR package Fan et al.  
474 (2008) within MATLAB.

475 We note that supercomputing resources were utilized not because of the  
476 computational time associated with model training nor prediction nor the cost  
477 of solution of the power flow problem itself. In contrast, the supercomputing  
478 resources were utilized due to the sheer number of scenarios studied herein.  
479 Specifically, as described in Section 4.1 there were over 8000 contingencies to  
480 test across the 167 hours. Of the roughly 20,500 transmission lines, on the order  
481 of 16,000 resulted in valid switching solutions, resulting in approximately 128  
482 million power flows to solve. Though each such power flow can be solved in  
483 a fraction of a second either in a supercomputing infrastructure or a standard  
484 workstation, it was the number of cores available which made such an analy-  
485 sis feasible given the data provided. It merits mentioning that such data can  
486 be gathered within the context of a regularly-scheduled contingency analysis  
487 procedure.

488 **5. Results**

489 *5.1. Performance Metric*

To measure the effectiveness of our data mining heuristic, we utilize the optimality gap. This measure describes the relative difference between the percent-

age of violations reduced by the optimal switching action and the corresponding value from the best action chosen by the heuristic. We utilize the percentage of violations reduced because it dampens the impact of instances with a particularly large or small initial violation magnitude. As mentioned in Section 4.2.1, we note that the exhaustive search guarantees the identification of the optimal solution. Therefore, the forthcoming analysis using the optimality gap provides context on how closely a heuristic performs relative to the optimal solution. The optimality gap is calculated as follows

$$Gap\% = \frac{V^* - V^H}{V^*} \times 100, \quad (6)$$

490 where  $V^*$  denotes the percentage of violation reduction stemming from the op-  
 491 timal switching action as identified by the exhaustive search, and  $V^H$  denotes  
 492 corresponding value stemming from the switching action proposed by the heuris-  
 493 tic. Note that we calculate this value separately for voltage magnitude violations  
 494 and branch flow violations.

495 *5.2. The Data Mininig Heuristic Consistently Identifies Optimal or Near-Optimal  
 496 Transmission Switching Actions*

497 Table 1 shows the average and standard deviation of the optimality gap  
 498 obtained for the top switching action according to Equation (4), fixed all other  
 499 lines as closed, and solved the ACOPF problem associated with that topology.  
 The results are broken out by violation type.

Table 1: Summary statistics for optimality gap

Violation Type	Mean	St. Dev.
Voltage Magnitude	5.51%	17.60%
Branch Flow	5.89%	93.71%

500  
 501 Table 1 shows that the data mining heuristic produces strong performance in  
 502 terms of optimality gap. Specifically, for both violation magnitude and branch  
 503 flow violations, the average optimality gap of the top switch identified by the  
 504 data mining heuristic is less than six percent, which is a very reasonable result

505 in practice for real-world, large-scale systems. However, the branch flow vio-  
 506 lations produce a relatively large standard deviation. This is largely because  
 507 of three instances, where the data mining heuristic produced optimality gaps  
 508 substantially larger than 100%. Removing these three instances, the standard  
 509 deviation drops to 17.5%, a much more reasonable value. The following para-  
 510 graphs explore these results in greater detail.

511 Figure 1 shows a histogram of the optimality gaps attained by the data  
 512 mining heuristic for the two types of violations. The first finding shown in  
 513 Figure 1 is that the bulk of instances fall either at zero or less than 0.1%. This  
 514 means that, for the bulk of instances herein studied, the data mining heuristic  
 515 identified optimal or near-optimal switching actions.

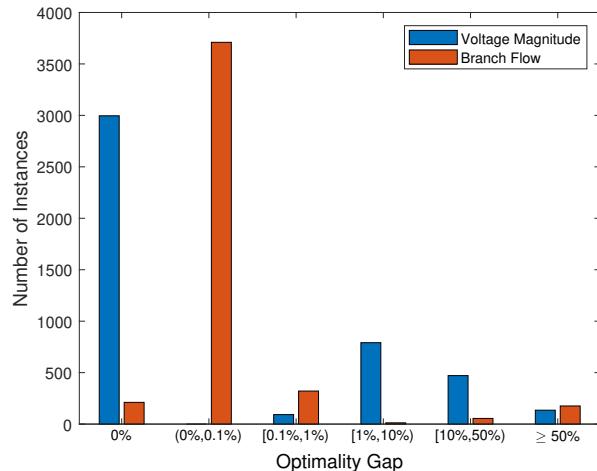


Figure 1: The data mining heuristic attains optimality gaps at or near zero in the overwhelming majority of instances

515  
 516 One additional important finding from Figure 1 is the number of scenarios  
 517 with optimality gaps greater than 50%. Specifically there are 135 such sce-  
 518 narios for voltage magnitude violations and 176 such scenarios for branch flow  
 519 violations. We note that these scenarios make up only approximately 1.7% and  
 520 2.2% of studied instances, respectively, further demonstrating the strength of  
 521 the method.

522 To put these results in context, we note that, as mentioned in Section 4.1,  
523 the data upon which the herein proposed approach was developed consists of 167  
524 distinct load profiles. Each a snapshot of the existing system operated by PJM.  
525 As such, the methodology is robust to changes in the system load. Moreover,  
526 if dramatic changes in the system should occur which significantly impact the  
527 load profile, it is simply a matter of data generation and model re-training to  
528 incorporate these changes into the herein proposed approach.

529 *5.3. The Data Mining Hueristic Attains an Optimality Gap Substantially Smaller  
530 than that of a Distance-based Heuristic*

531 While Section 5.2 showed that the data mining heuristic produced strong  
532 performance in its own right, it is also important to compare against the strongest-  
533 performing existing methods. The authors in (Li et al., 2017) developed distance-  
534 based heuristics which constitute the strongest-performing methods which are  
535 viable at a large scale for the problems outlined in Section 2. Specifically, the  
536 authors in (Li et al., 2017) developed a heuristic which obtains solutions based  
537 on the distance from the candidate branch to the violation element (CBVE).  
538 However, CBVE only identifies switches in the area around the violation element  
539 rather than focusing on characteristics of the switches themselves. Therefore,  
540 the following experiments utilize a candidate pool – a group of switching can-  
541 didates from which the best switch is selected. We note that, to achieve best  
542 performance, we re-conducted feature selection as described in Section 4.2.2 us-  
543 ing a candidate pool of ten. In the interest of full disclosure, we note that the  
544 authors in (Li et al., 2017) also developed a heuristic using the distance from the  
545 switch to the contingency element. However, in our experiments, this method  
546 was effectively dominated by CBVE. We therefore excluded it from our analysis.

547  
548 Table 2 summarizes the performance of the two heuristic methods in terms  
549 of the optimality gap using a candidate pool of size ten. Specifically, Table 2  
550 shows the mean and standard deviation of the optimality gap for the proposed  
551 data mining method, denoted DM-10, against that of the distance-based metric,

552 CBVE, when using a candidate pool of size ten. These results are broken out  
553 by the type of violation.

Table 2: Summary statistics for optimality gap using a candidate pool of size ten

Violation Type	Method	Mean	St. Dev.
Voltage Magnitude	DM-10	3.41%	15.91%
	CBVE	28.94%	8.91%
Branch Flow	DM-10	0.04%	0.81%
	CBVE	1.58%	10.04%

554 Table 2 shows that the data mining heuristic outperforms the distance based  
555 heuristic across the board. In regard to voltage magnitude violations, the pro-  
556 posed heuristic attains an average optimality gap over eight times smaller than  
557 that of the distance-based heuristic. Regarding branch flow violations, the aver-  
558 age optimality gap using the data mining heuristic is almost forty times smaller  
559 than that of the distance-based heuristic; the standard deviation is 12 times  
560 smaller using the same comparison. These results show that, at a high level,  
561 the data mining heuristic has extremely strong performance against distance-  
562 based heuristics in terms of the optimality gap. The remainder of this section  
563 explores these results in greater detail.

564 Figure 2 plots the empirical cumulative distribution function (ECDF) of the  
565 optimality gaps obtained for voltage magnitude violation reduction by both the  
566 proposed data mining heuristic and the distance based heuristic. An ECDF  
567 plots the fraction of data points that are less than or equal to a certain value  
568 for all possible values of the metric of interest. We use this plot because it  
569 characterizes the fraction of instances for which each heuristic achieves a certain  
570 performance.

571 There are two findings from Figure 2. First, for the data mining heuristic,  
572 there is a vertical line at zero which reaches almost 92% of instances. This  
573 means that, in approximately 92% of studied instances, the proposed heuristic  
574 identified the optimal switch. In contrast, the distance-based heuristic had no

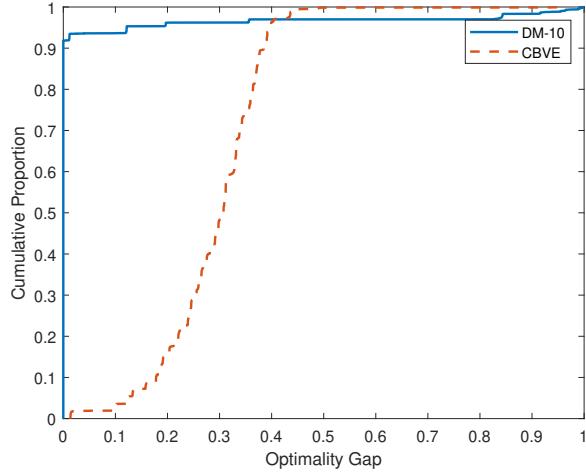


Figure 2: DM-10 dramatically outperforms CBVE for voltage violation reduction in terms of the optimality gap

575 such instances where the optimal switch was found within the candidate pool.  
 576 This can be seen when the blue line diverges from the red line. These results  
 577 show that, for the test case studied here, the data mining heuristic dramatically  
 578 outperforms the distance-based heuristic in identifying optimal or near-optimal  
 579 solutions.

580 The second finding is the relative performance between the data mining  
 581 heuristic and the distance-based heuristic. Specifically, the proposed data min-  
 582 ing heuristic attains an acceptable optimality gap of less than ten percent in  
 583 over 93% of instances and an optimality gap of less than 25 percent in over  
 584 96% of instances, respectively. In contrast, the distance-based heuristic only at-  
 585 tains such performance in 3.3% and 29% of instances, respectively. We can  
 586 therefore conclude that, for the test case studied here, the data mining heuris-  
 587 tic dramatically outperforms the distance-based heuristic in the reduction of  
 588 voltage magnitude violations.

589 Next, we conducted an identical analysis to the one described above studying  
 590 the impact of the two heuristics on branch flow violations. Figure 3 shows the  
 591 ECDF for both the data mining heuristic and the distance-based heuristic.

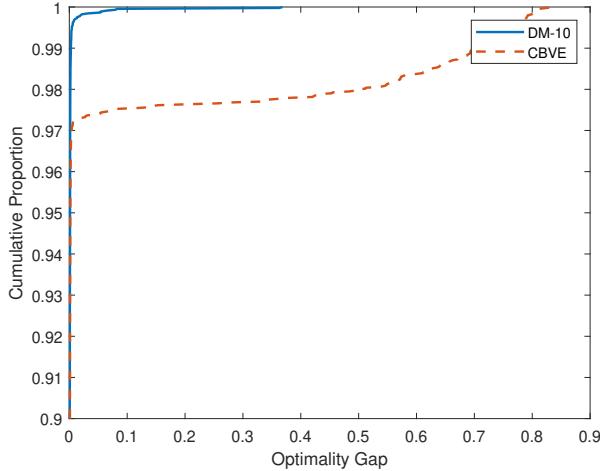


Figure 3: DM-10 performs more strongly in branch flow violations than CBVE

592 Figure 3 shows that, while the two heuristics are much more competitive  
 593 in the case of branch flow violation reduction, the data mining heuristic is still  
 594 the superior method. The first finding from Figure 3 is that both heuristics  
 595 have a long vertical line at or near zero. This shows that both methods have  
 596 strong performance in this case. Specifically, the data mining heuristic attains  
 597 an optimality gap of less than 0.1% in over 92.8% of instances. The distance-  
 598 based heuristic attains such a performance in over 89.5% of instances. If we  
 599 increase the threshold to an optimality gap of one percent, the data mining  
 600 heuristic identifies such a switch in over 99.6% of solution and the distance-  
 601 based heuristic identifies such a switch in over 97.2% of solutions. These results,  
 602 and those described by Figure 2 show that the proposed data mining heuristic  
 603 definitively outperforms the distance based heuristic for the test case studied  
 604 here.

## 605 6. Conclusion

606 This work developed a data mining heuristic to identify transmission switch-  
 607 ing candidates to reduce post-contingency voltage magnitude and branch flow

608 violations. We used real-world large-scale AC power system data to generate a  
609 robust data set to feed into our logistic regression model with guided undersam-  
610 pling. The resulting heuristic demonstrated considerable performance in identi-  
611 fying strong transmission switching solutions, even given the substantial size of  
612 the PJM system. Our methodology shows the ability of data mining methods to  
613 substantially reduce the workload associated with identifying strong transmis-  
614 sion switching candidates for post-contingency violation reduction. While the  
615 specific predictive model (i.e., the features chosen during feature selection and  
616 the regression coefficients) may not be specifically applicable to every system,  
617 the methodology herein proposed should generate a model which exhibits strong  
618 performance on alternate data sets.

619 We first showed that the data mining heuristic has strong performance in  
620 terms of accuracy. Specifically, using only the top switch identified by the data  
621 mining heuristic, the proposed methodology attained an average optimality gap  
622 of 5.5% for voltage magnitude violations and 5.9% for branch flow violations.  
623 Moreover, for both violation types, the bulk of studied instances ( 92% and 93%,  
624 respectively ) result in optimality gaps of less than 0.1%. We therefore conclude  
625 that the data mining heuristic can regularly identify optimal or near-optimal  
626 solutions. We also showed that the data mining heuristic substantially outper-  
627 forms distance-based heuristics in terms of accuracy. Using a candidate pool  
628 of only ten switches, the proposed heuristic outperformed an existing distance-  
629 based heuristic in terms of average optimality gap by over eight times for voltage  
630 magnitude violations and over 35 times for branch flow violations. These find-  
631 ings show that data mining methods such as the data mining heuristic with  
632 guided undersampling developed herein are noteworthy techniques which can  
633 identify optimal and near-optimal candidate switching actions for the herein  
634 studied problem with extremely high regularity.

635 One potential area of future study is the integration of transient stability  
636 integration into or alongside the herein studied method. As discussed in Section  
637 1, the proposed methodology can be paired with that of (Dehghanian et al.,  
638 2015) in order to fully validate transmission switching actions. Moreover, it

639 is possible that transient stability of the system can be integrated into the  
640 prediction step itself using sophisticated methods. An additional area of future  
641 work is in the area of data visualization. It would be beneficial to develop tools  
642 which, within the context of real-time contingency response, could identify either  
643 (1) areas of critical concern or (2) areas with significant improvement due to  
644 transmission switching, and highlight them and the associated impact in real-  
645 time. Such tools could be used in the context of other approach such as the one  
646 proposed by Li et al. (2017).

647 Our method demonstrates the strong performance that data mining meth-  
648 ods can achieve in regard to power systems operation. Specifically, our proposed  
649 method is one of few which uses data mining techniques to address power sys-  
650 tems operations. Moreover, ours is the first true data mining technique applied  
651 to transmission switching in a large-scale AC context. As mentioned previ-  
652 ously, transmission switching is only implemented in limited capacity because  
653 of concerns over computational complexity, uncertainty of AC performance, and  
654 scalability to real-world systems. Because our data mining heuristic is compu-  
655 tationally inexpensive, addresses an AC system problem directly, and has been  
656 rigorously tested on real-world large-scale data, it addresses these three issues  
657 directly. Given the performance of our model, it should be strongly considered  
658 in the use of post-contingency violation reduction. More importantly, it should  
659 motivate the study and development of new data mining techniques to address  
660 this and similar power systems operations problems.

661 **Appendix A. Nomenclature**

662 **Parameters**

$g_{ij}, b_{ij}$	Real/imaginary components of admittance of transmission line $\langle i, j \rangle$
$p_n^d, q_n^d$	Active/reactive power demand at bus $n$
$p_n^g, q_n^g$	Active/reactive power output at bus $n$
$S_{ij}$	MVA rating for line $\langle i, j \rangle$
$V_n^{\min}, V_n^{\max}$	Min/max voltage magnitude at bus $n$

664 **Sets**

665  $\langle i, j \rangle \in K$  Set of transmission lines  
665  $n \in N$  Set of buses

666 **Decision Variables**

667  $g_{ij}, b_{ij}$  Real/imaginary components of admittance of transmission line  $\langle i, j \rangle$   
667  $p_n^d, q_n^d$  Active/reactive power demand at bus  $n$   
667  $p_n^g, q_n^g$  Active/reactive power output at bus  $n$   
667  $S_{ij}$  MVA rating for line  $\langle i, j \rangle$   
667  $V_n^{\min}, V_n^{\max}$  Min/max voltage magnitude at bus  $n$

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