

A Framework for Nucleation in Electrochemical Systems and the E Dendrite Growth

Madison Morey¹, Giacomo Nagaro⁴, Anubhab Halder,³ Sahar Sharifza

¹Division of Materials Science and Engineering, Boston University, Boston, MA 02215, USA

²Department of Mechanical Engineering, Boston University, Boston, MA 02215, USA

³Department of Electrical and Computer Engineering, Boston University, Boston, MA 02215, USA

⁴Department of Chemistry, Boston University, Boston, Massachusetts 02215, USA

⁵Department of Physics, Boston University, Boston, Massachusetts 02215, USA

*Corresponding author: ryanem@bu.edu, 617-353-7767

Abstract

Dendrite growth is directly attributed to the degradation of battery performance. The physical attributes of dendrite growth have been extensively studied, but the underlying mechanisms, computationally, little is understood about the nucleation process and how these factors impact growth. In this study, a numerical model

the surface energy and improve the stability of the interface leading to denser and less dendritic. When the defects cause a decrease in surface energy, they lead to significantly more dendrite growth. Finally, the interplay that surface properties, due to the composition of the solid-electrolyte interphase, have on dendrite growth is investigated showing that the dominating factor in dendrite growth is improved Li^+ transport through the SEI layer. The results of this work can inform approaches to engineering more stable anodes for improved battery performance.

Keywords: Lithium Batteries, Dendrites, Computational Modeling, Numerical Simulation

1. Introduction:

The energy storage capabilities of state-of-the-art Lithium (Li)-ion batteries are limited by the low theoretical capacity of the graphite anode ($\sim 372 \text{ mA h g}^{-1}$)[1]. Current technologies fall short of society's demand for energy storage technologies in electric vehicles and large-scale renewable energy storage[2]. To combat this, the Li-metal battery has emerged as a promising alternative. The Li-metal battery with a Li-metal anode which is considered the holy grail of anode technology

catastrophic failure of the battery[7,8]. A key obstacle in the commercialization of Li metal batteries lies in understanding the morphological evolution of dendrites and developing strategies to control and suppress dendrite growth.

Research into the growth and morphology of Li dendrites has been extensive, but it is still unclear; however, little is known about the nucleation process of Li along the surface. It is also unclear how surface characteristics, such as surface energy, impact this growth. Several proposed modes of nucleation such as top and bottom-induced nucleation have been suggested, but primarily on defect-induced nucleation where subsurface defects can act as nucleation sites or for nucleation or help to stabilize the interface[6]. In particular, the effect of impurities in the lattice of Li metal and Li vacancies have on dendrite growth is not well understood. Impurities, like the ones mentioned above, are present in uncycled Li metal. For example, Li metal films produced via rolling have shown large amounts of Oxygen (O), and Nitrogen (N) impurities[14,15]. Researchers have shown that the amount of impurities can be decreased using specialized production methods such as thermal evaporation, but this can be difficult and time-consuming [15]. Therefore, understanding how to control the surface chemistry and in turn, the Li plating can give insight into

transport properties through this layer changed. Liu *et al.*[17] presented a study looking at the impact that different components of the SEI layer had on the performance of solid-state batteries and in turn the impact it had on Li plating. They used a Li-11 wt % Sr alloy anode and a fluorinated electrolyte. Then, through experimental characterization, they showed that the interfacial energy was lower when the SrF_2 -rich SEI layer was present as opposed to a bare Li anode. This lower energy combined with changes in the mechanical properties of the SEI led to the suppression of dendrite growth after cycling.

Additionally, many groups have studied how size, morphology, and composition impact Li plating for Cu current collectors when initializing the Cu surface. In solid-state batteries (ALMBs) a thin layer of Li is deposited on the Cu current collector. For this application, it is crucial that this thin layer is as uniform as possible. This is similar to desiring a Li metal anode that is void of mechanical defects. Various nucleation control methods such as increasing the number of nucleation sites, using a surface coating that possesses lithophilic sites to control wettability, and forming and ensuring that the distribution of nucleates is homogeneous.

interfaces possessing slower nucleation rates, are more beneficial to the battery performance. Surfaces with a high surface area and reduced surface curvature[21–26].

Lopez *et al.*[22] studied how different polymer coatings impact the Li metal anode. They found that a low surface energy polymer coating with a high degree of wettability and low reactivity leads to larger Li nucleates, better plating, and improved cycling. This is because the low surface energy associated with the polymer coating reduces the interaction with the Li metal anode meaning that it did not decrease the surface area between the Li metal and polymer resulting in large nucleates with a low surface area to minimize the surface area decreasing the reaction flux at the interface. Conversely, a high interfacial energy results in better plating and overall better battery performance. Wang *et al.*[23] used a titanium (Ti) metal shield to aid in guided deposition on a Ti surface. It was shown to have a high interfacial energy providing a higher Li nucleation rate, leading to a low-density distribution of “pancake-like” nucleates and a slow growth rate. They then showed that the initial morphology of Li nucleates on these surfaces was determined through SEM images showing needle-like dendrite growth on a low energy surface and high interfacial energy and flat and non-dendritic growth on the high energy surface.

reactive surface area. The morphology of these initial deposits res growth as opposed to the dendrite growth occurring on the low ener

Researchers have used various methods to model the comp process on both the atomistic and continuum scales[27–30]. Maeda Dynamics to study surface nucleation in anorthite-based glass using (CNT). Applying this model, they were able to calculate the nucleation physical parameters. Lu *et al.*[27] developed a transport-based mod method to aid in the identification of the mechanisms for bubble electrodes. Additionally, Jreidini *et al.*[30] uses CNT to calculate liquid rates and incubation times. They do this using a phase-field crystal the gap between the atomic and mesoscale allowing for the consi subsequent crystal growth. Adopting the techniques that have applications such as crystal nucleation can provide a starting point nucleation in alternate systems, such as electrochemical nucleation [27–30].

Therefore, multiple studies have been proposed to theoretica

charged substrates. Additionally, Monroe and Newman[32] presented a (P2D) surface-energy controlled growth model that incorporated curvature into the growth kinetics. The speed at which nucleates form is influenced by the surface energy of the substrate, which is also influencing dendrite growth. Nagy *et al.*[33] used computational methods to show how parameters including surface energy and overpotential affected the nucleation rate within a system. They showed that an increase in surface energy leads to a higher state nucleation rate because the system has a larger energy to overcome the energy barrier. Further, it was shown that as the applied potential to the system became more negative, the nucleation rate increased.

While the aforementioned theoretical studies were successful in providing fragments of the nucleation and growth processes, they have several limitations. Garcia's[31] analytical framework provided insight into how charge transfer coefficient, surface tension and overpotential determined the energetic favorability of dendrite nucleation, but the model only considered the formation and growth process of individual nucleation sites and did not consider their impact on subsequent dendrite growth. Monroe and Newman[32] considered the dendrite tip curvature and surface energy on dendrite growth, but their model only considered the nucleation and growth of a single dendrite.

understanding of the impact these parameters and the nucleation growth and morphology after initial nucleation.

In this paper, we utilize a combination of the theoretical concepts to develop a computational model (nucleation-SPH model) that captures their effects on dendrite growth and morphology by considering nucleation but also the interfacial transport and the subsequent growth of dendrites. This work builds off our previous model that included electrochemical migration[12], a spatially and temporally varying extended, concentration-dependent, Butler-Volmer equation that anode-electrolyte interface[10]. Two main additions have been made to nucleation physics. The first is the addition of a radial growth equation which a single Li nucleate grows. The second is the addition of a stochastic equation that tracks how quickly nucleates form in the system with respect to including surface energy and overpotential. While many factors impact nucleation including transport properties[36,37], charging methods[9,13], separator electrode architecture[10] as studied in past papers utilizing the

dendrite growth. SPH also captures the morphology of the dendritic growth. The model is used in conjunction with DFT to study how point defects and impurities in the Li-metal anode impact the surface energy and influence the anode-electrolyte interface to inform the design of more stable batteries. In this work, the model to consider the interplay of interfacial energy and transport phenomena to suppress dendrite growth due to the presence of an LiF-rich SEI layer.

2. Computational Methods:

The model presented in this work solves for species conservation in the electrolyte and at the interface and includes the effects of transport of cations through the interface and electrodeposition. The model extends previous electrodeposition models that surface energy and nucleation have on electrodeposition [10,11] by including through the addition of a radial growth equation for a single hemispherical nucleus and a state nucleation rate equation derived from Classical Nucleation Theory [39].

The Nernst-Planck equation is solved for the change in concentration of the electrolyte, dC/dt , [39]

$$\partial C_i(\vec{r}_f, t) = -\nabla \cdot (D_i \nabla C(\vec{r}, t)) + \nu_i \nabla \cdot (C(\vec{r}, t) \nabla \phi(\vec{r}, t))$$

In a binary electrolyte cations and anions remain electroneutral in the bulk electrolyte. Upon the application of a voltage, electroneutrality can be violated in the diffusion layer due to the consumption of ions at the electrode surface. If electroneutrality is violated a charge imbalance occurs and results in an electric potential gradient. This gradient can be solved via the electrostatic Poisson equation[39]

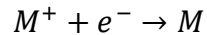
$$\nabla^2 \phi(\vec{r}_f, t) = -\frac{\rho_{charge}}{\epsilon}, \vec{r}_f \in \Omega_f, t > 0$$

where ϵ is the dielectric constant, and the net charge density, ρ_{charge} , is given by

$$\rho_{charge} = F \left(z_{M^+} C_{M^+}(\vec{r}_f, t) - z_A C_A(\vec{r}_f, t) \right)$$

where F is the Faraday constant.

Electrodeposition occurs at the anode-electrolyte interface. During this process, M^+ will be reduced via electrons (e^-) and deposit as metal along the surface.



This is modeled through a reactive boundary condition for cations at the anode-electrolyte interface:

$$D_{M^+} \nabla C_{M^+}(\vec{r}_s, t) + \mu_{M^+} C_{M^+}(\vec{r}_s, t) \nabla \phi(\vec{r}_s, t) = S_s(\vec{r}_s, t),$$

where $\vec{r}_s$ is a location in the solid domain, $S_s(\vec{r}_s, t)$ is the total flux of M^+ into the solid.

where α_a and α_c are the anodic and cathodic transfer coefficients, respectively, k^0 is the exchange current density, R is the gas constant, and T is the temperature. The concentration in the bulk electrolyte is $C_{A,L}$ for anions, $C_{A,L}$ for cations, and $C_{A,L}$ for anions, k^0 is the reaction rate, $\gamma(\vec{r}_s)$ is the surface energy of the Li surface and the electrolyte, and V_m is the molar volume. The radius $r(\vec{r}_s, t)$ is zero for a perfectly flat surface and $k(\vec{r}_s, t) = 2/r(\vec{r}_s, t)$ for a hemispherical nucleus, where $r(\vec{r}_s, t = 0)$ is assumed to be larger than that of the critical radius for a stable nucleate, [40–42]

$$r_{eq}^* = \frac{2\gamma(\vec{r}_s)V_m}{F|\eta|}$$

The overpotential (η) is given by

$$\eta = \phi_{App} - \phi_{eq}$$

the equilibrium potential, ϕ_{eq} , is the difference between the local reference potential and ϕ_{App} is the potential applied to the system.

The growth rate of the individual nuclei radius, dr/dt , is calculated from the Li⁺ flux for that nucleate at the anode-electrolyte interface and the

$$\frac{dr}{dt} = S_n(\vec{r}_s, t) * V_m, \quad \vec{r}_s \in \Gamma$$

where N is the total number of atoms per unit surface area [33], $N_A C_{Li^+}(\vec{r}_s, t) d$, N_A is Avogadro's number and d is the thickness of the electrode in the vicinity of the electrode ($\sim 10 \text{ \AA}$) [33], k_B is the Boltzmann constant, ω_c is the frequency of collision of the atoms with the critical nuclei, ω_c , is [33,38]

$$\omega_c = \frac{S_c i_0}{z_{M^+} e}$$

the exchange current density, i_0 , is defined by $i_0 = F k^0 C_{M^+,L}^{\alpha_c} C_{A,L}^{\alpha_a}$ [10], F is the Faraday constant, i_0 is the exchange current density for ionic species (+1), e is the elementary charge and S_c is the surface area of the critical nucleus in contact to the electrolyte, $S_c = 2\pi r_{eq}^{*2}$. The formation energy of the critical nucleus ΔG_c can be obtained by [33]

$$\Delta G_c = ze(\eta - \phi_{App})$$

The number of atoms in the critical nucleus, g_c , can be obtained by [33]

$$g_c(\vec{r}_s) = \frac{32\pi \gamma(\vec{r}_s)^3 V_m N_A}{3(\eta z F)^3} f(\Theta), \quad \vec{r}_s \in \Gamma$$

where $f(\Theta) = 1/2 - 3/4 \cos(\Theta) + 1/4 \cos^3(\Theta)$ is a function of contact angle Θ .

There is a zero-flux boundary condition for the anions at the anion adsorption sites

$$D_A(\vec{r}) \nabla C_A(\vec{r}, t) + u_A C_A(\vec{r}, t) = 0, \vec{r} \in \Gamma$$

The governing equations are implemented into the SPH method using the scheme of Tartakovsky *et al.* for Fickian Diffusion and precipitation [44], of Cannon *et al.* for migration [12], the discretization scheme of Morey *et al.* [10] and the heterogenous reaction boundary condition is implemented using the surface reaction (CSR) method [45]. The final forms of the discretized equations are given below, and further details on their implementations and verification are given in the references [9–13].

The Nernst-Planck equation (Eq. (1)) is discretized as

$$\begin{aligned} \frac{DC_{M^+,i}}{Dt} = & \sum_{j \in liquid} \frac{2D_{M^+} m_j \vec{r}_{ij}}{\rho_j (\vec{r}_{ij})^2} (C_{M^+,i} - C_{M^+,j}) \nabla \phi_i \\ & + \sum_{j \in liquid} \frac{m_j \vec{r}_{ij}}{\rho_j (\vec{r}_{ij})^2} \mu_{M^+} (C_{M^+,i} - C_{M^+,j}) (\phi_i - \phi_j) \\ & - S_s \sum_{k \in solid} \frac{m_k}{\rho_k} (\vec{n}_k + \vec{n}_l) (\beta_k + \beta_l) \nabla W_{ik}, \quad i \in fluid \end{aligned}$$

where m , ρ , D and C are the mass, density, diffusion coefficient, and concentration of the particles respectively. The subscript M^+ represents the cations, i and j are individual SPH fluid particles, and k represents the solid particles. μ is the electrochemical potential. The distance between particles i and j is given by $\vec{r}_{ij}$, $\vec{n}$ is the normal vector.

characteristic function used to identify the anode interface. S_s is the surface area of the solid particles.

$$\begin{aligned} \frac{DC_{A,i}}{Dt} = & \sum_{j \in \text{liquid}} \frac{2D_A m_j \vec{r}_{ij}}{\rho_j (\vec{r}_{ij})^2} (C_{A,i} - C_{A,j}) \nabla W_{ij} \\ & + \sum_{j \in \text{liquid}} \frac{m_j \vec{r}_{ij}}{\rho_j (\vec{r}_{ij})^2} \mu_{M^+} (C_{A,i} - C_{A,j}) (\phi_i - \phi_j) \nabla W_{ij}, \end{aligned}$$

where subscript A refers to anion properties.

As the cations are reduced at the interface they will deposit, causing a decrease in cation concentration at the interface. During charging, this loss must be balanced by the rate of gain of the solid (m_k) due to precipitation. This is implemented via the discretization scheme of Tartakovsky *et al.* [44]

$$\frac{Dm_K}{Dt} = S_s \sum_{k \in \text{liquid}} \frac{m_k}{\rho_k} (\vec{n}_k + \vec{n}_l) (\beta_k + \beta_l) \nabla W_{ik},$$

where the subscripts k and i represent solid and liquid particles respectively. When the mass is twice the initial mass, the nearest fluid particle will precipitate and become part of the solid.

The governing equations are implemented into the SPH method using the Large-scale Atomic/Molecular Massively Parallel Simulator (LAMMPS). The simulation domain is discretized as 150 by 150 units of h , which is the smoothing length. There are 360,000 discrete SPH particles with a particle density of 30 particles per unit volume. This is utilized to approximate the sharp boundary at the reactive interface and the

been verified. To do so, both the radius growth equation and the nucleation equation were numerically solved, then simplified, isolated, and then compared to their analytical solutions.

For both verification cases, the system does not model planar diffusion, but rather spherical diffusion. The first verification case is a constant concentration boundary condition at the anode-electrolyte interface. These simplifications allow the specified equation to be solved for an analytical solution. The second verification case is the radial growth equation. Here the system is assumed to be a flat surface, i.e. no nuclei present, where the curvature, k , is equal to zero. This simplification, along with further Eq. (9), to the traditional Butler-Volmer equation without

$$\frac{dr}{dt} = i_0 V_m \left[\exp\left(\frac{\alpha_a F}{RT} \eta\right) - \exp\left(\frac{\alpha_c F}{RT} \eta\right) \right]$$

This simplification allows us to solve the radius equation above for an analytical solution for the radius of nuclei at a particular time ($r(t)$).

$$r(t) = r_0 + i_0 V_m \left[\exp\left(\frac{\alpha_a F}{RT} \eta\right) - \exp\left(-\frac{\alpha_c F}{RT} \eta\right) \right] t$$

The initial nuclei radius, which must be larger than the critical radius, r_0 , thermodynamically favorable to grow is given by r_0 and t is the time. The radius of the nucleates was obtained from the numerical data and compared directly to the analytical solution.

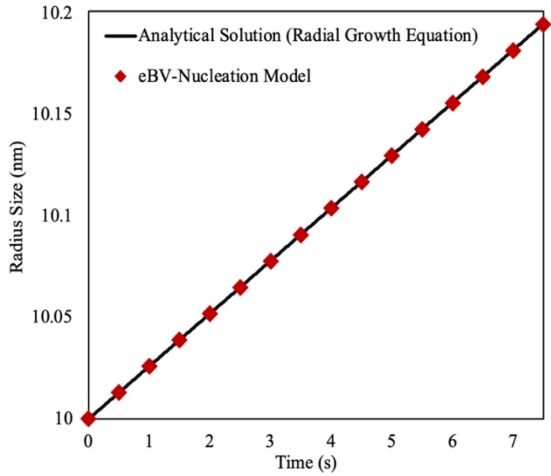


Figure 1: Comparison of numerical solution to analytical solution for radial growth equation.

The second verification case is the verification of the nucleation concentration condition is assumed and the resulting equation for given as,

$$\frac{dn(\vec{r}_s, t)}{dt} = N \frac{\omega_c}{g_c} \left(\frac{\Delta G_c}{3\pi k_B T} \right)^{1/2} \exp \left(-\frac{\Delta G_c}{k_B T} \right)$$

Where N is defined as $N = N_A C_{Li} + d$ and is a constant value. This simplifies for the analytical solution, assuming that there are, initially, no nuclei

The final verification compares the numerical result to the system undergoes changes in surface energy. To obtain the data from the surface energy was varied over multiple simulations. The steady then extracted from the simulation data and plotted against Eq. (22). surface energy increases, the steady-state nucleation rate decreases. well with the analytical solution with an average error of less than 5%

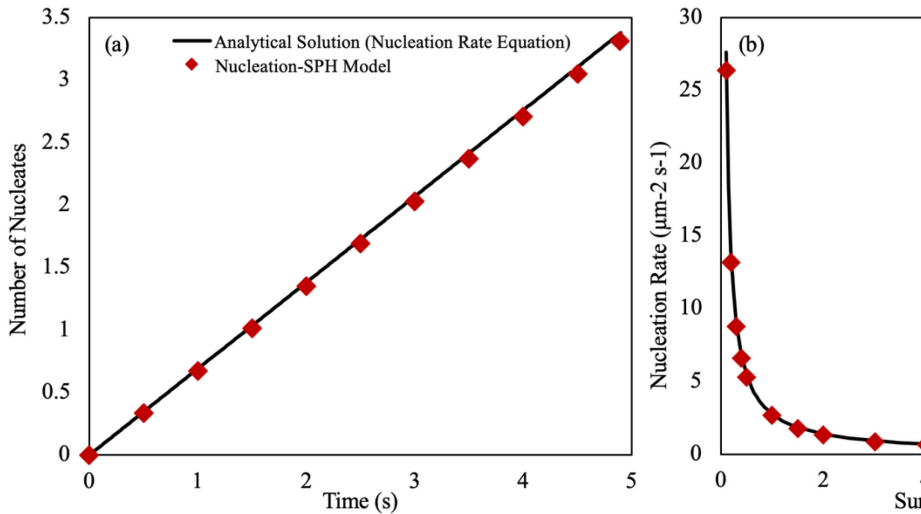


Figure 2: Comparison of numerical solution to analytical solution for the steady comparison with respect to a change in time over five seconds of simulation time (change in surface energy)

2.3 Density Functional Theory Calculations:

valence electrons for Li, Al, C, N, O, F, and P, respectively. Calculations were performed using a plane-wave energy cut off 450 eV, Pulay density mixing [54,55] with a convergence tolerance of 10^{-6} eV/atom and a Marzari-Vanderbilt smearing of occupations [56] (cold smearing) with a width of 0.02 eV.

Starting structures were obtained from the Materials Project database (mp-154, mp-12957, mp-1067793, and mp-157) and re-optimized within the BFGS and MDMin algorithms as implemented in ASE. Subsequently, the Li(100) surface was constructed using ASE and its structure re-optimized at the bulk values. To study substitutional defects (Al, C, N, O, F, P) on the Li(100) surface, a 3x3x3 supercell of Li(100) was created, where $n = 3, 5, 7$ and two Li atoms on opposite faces were replaced by defect atoms. Both faces contain a defect to prevent the formation of a dipole along the perpendicular direction due to the presence of the defect. The defect atoms were placed in the center of the top and bottom faces of the supercell. The structure was optimized while the lattice constants were kept to the bulk values. For structural optimizations, forces on atoms were converged to less than 0.01 eV/Å.

The surface energy was calculated as:

$$E$$

pseudoconvex energy surfaces. The MDMin-optimized geometries are compared to our presented results using the BFGS algorithm. The final surface energies are presented in Table 1. These values are incorporated into our nucleation model in Eq. 14.

Table 1: DFT-Predicted surface energies for a series of defects at different concentrations. For the sake of analysis, the electronegativity associated with the defect is shown.

Defect Type	Concentration ($10^{18} \text{ defects cm}^{-2}$)	Electronegativity
Pristine Li	-	1
Carbon Substitutional	1.0632	2.5
	2.9536	
	5.7888	
Phosphorus Substitutional	1.0632	2.1
	2.9536	
	5.7888	
Fluorine Substitutional	1.0632	4
	2.9536	
	5.7888	
Aluminum Substitutional	1.0632	1.61
	2.9536	
	5.7888	
Oxygen Substitutional	1.0632	3.44
	2.9536	
	5.7888	
Nitrogen Substitutional	1.0632	3.04
	2.9536	

The simulation domain is comprised of an anode, a layer adjacent to the anode, the diffusion layer, where transport occurs, and the dendrite structure. The diffusion layer contains a constant concentration region, a distance L from the anode. The simulation domain prior to dendrite growth. As the simulation progresses, dendrite growth occurs the reactive boundary will adapt to the newly formed dendrite structure. The model presented in Section 2 is a universal model, thus cations and anions will be treated separately respectively. However, for the remainder of the study the cations will be treated as a single species in the application of the method to dendrite growth and electrodeposition.

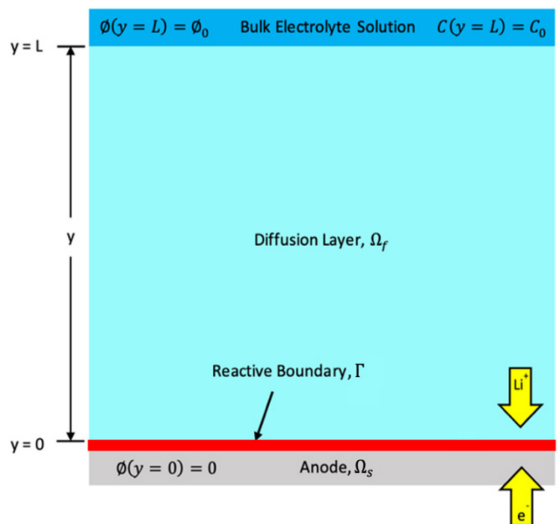


Figure 3: Schematic of the simulation domain including anode surface (Ω_s), growth region (Ω_f), and bulk electrolyte solution (Ω_b).

$$C_i(y = L, t) = C_{i,L}$$

The Li^+ and anion concentrations are equal and constant in the electrolyte. Since
electroneutrality is assumed at this location,

$$z_{\text{Li}^+}C_{\text{Li}^+} + z_A C_A = 0$$

$$\nabla C_i = 0$$

where z_{Li^+} and z_A are the charge of the Li^+ and anions, respectively, and C_{Li^+} and C_A are their respective concentrations. There is no initial concentration gradient for Li^+ or anions.

The potential at the reactive boundary, Γ , is the reference potential. The potential at the separator is the ground potential.

$$\phi(\vec{r}_s, t) = 0, \vec{r}_s \in \Gamma, t > 0$$

A constant voltage is applied to the top boundary at the constant rate of $\frac{dV}{dt}$, resulting in a fixed potential, ϕ_0 , relative to the reference potential.

$$\phi(y = L, t) = \phi(\vec{r}_f, t), t > 0$$

Upon the application of this charging voltage, the anions will travel toward the cathode while the Li^+ will travel toward the anode. This results in a buildup of Li^+ at the anode. Here the Li^+ will react with electrons (e^-) and deposit as solid lithium.

that is observed experimentally[16]. For example, because the diffusion coefficient is reduced down by approximately two orders of magnitude, the diffusion coefficient is scaled by the same proportion to maintain equivalent ratios between the diffusion coefficient and the initial diffusion coefficient. The physical properties used throughout this work are listed in Table 2.

Table 2: Simulation Parameters

Parameter	Symbol	Value
SPH particle interval	Δx	0.001
Kernel Density [12]	n_{eq}	1.0
Diffusion coefficient* [7,13,60]	D	1.0
Mobility [12]	μ	0.001
Anion and Cation concentration (Initial) [61]	$C_{A,0}/C_{Li^+,0}$	0.0
Anion and Cation concentration (Bulk Electrolyte) [61]	$C_{A,L}/C_{Li^+,L}$	0.0
Transfer coefficients [32]	α_A, α_C	0.5
Reaction Rate* [10]	k^0	1.0
Applied potential	ϕ_{APP}	0.0

* Adjusted parameter to minimize computational time while preserving the physics of the system.

3.1 Qualitative Experimental Comparisons:

The model’s ability to accurately represent a physical system is evaluated by comparing the model results to experimental data. A limitation of experimentally validated models is that they are often only valid for a narrow range of conditions, and the model may not be able to capture the full range of physical phenomena. The model is compared to experimental data for the diffusion coefficient, reaction rate, and applied potential. The model results are compared to experimental data for the diffusion coefficient, reaction rate, and applied potential. The model results are compared to experimental data for the diffusion coefficient, reaction rate, and applied potential.

properties in comparison to a bare Li anode as determined via DFT calculations. It was observed that the plating on the high energy Li-Sr anode was significantly less dendritic (Fig. 4a) than that on the low energy pristine Li anode (Fig. 4c).

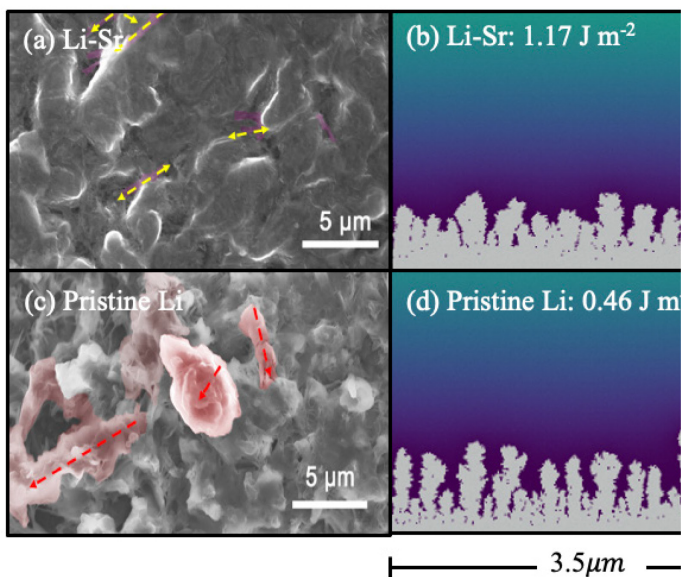


Figure 4: Dendrite comparison of different anodes after cycling. (a) Top-view SEM of Li-Sr anode with high interfacial energy (1.17 J m⁻²) (b) model of Li-Sr anode with high interfacial energy (1.17 J m⁻²) (c) Top-view SEM of Pristine Li anode with low interfacial energy (0.46 J m⁻²) (d) model of Pristine Li anode with low interfacial energy (0.46 J m⁻²). Adapted with permission from S. Liu, X. Ji, J. Yue, S. Hou, P. Wang, J. Han, J. Tu, C. Wang, High Interfacial-Energy Interphase Promoting Safe Lithium Metal Batteries, *Journal of the American Chemical Society*, 2020, 142, 2438–2447. <https://doi.org/10.1021/jacs.9b11750>. Copyright 2020 American Chemical Society.

To compare the model results to that of the experimental results,

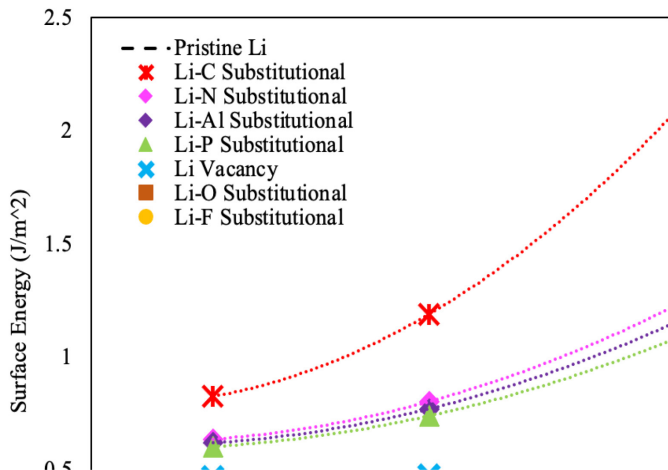
flat morphologies minimize surface area and decrease the rate of reaction being consumed at the interface, the system remains reaction-limited and a mossy morphology as seen in Fig. 4b. These predictions compare well to those reported in Liu *et al.*[17].

Based on the case presented above, as well as additional cases, it is concluded that increased surface energy leads to a more favorable nucleate morphology and higher growth rates resulting in a “layered” deposition as opposed to an “island” morphology. It is concluded that the computational model presented in this paper is a good approximation of the physical system.

4. Effect of Surface Energies and Transport on Dendrite Growth:

The nucleation-SPH model presented throughout this paper, in addition to the lattice model, was used to investigate how defects in the lattice of the anode impact the growth of the anode-electrolyte interface. It is nearly impossible to have a Li metal anode without any lattice defects including impurity atoms and vacancies [14,15]. This study aims to study how these defects impact the stability of the anode-electrolyte interface and overall performance. To do this, seven different anodes with varying types and concentrations of defects were modeled.

affected by this increase. For most defect types including C, N, Al, and O, the surface energy shows a positive increase in surface energy as the concentration of defect increases. This indicates that surface formation is less favorable with increase of defect-defect interaction. However, F and vacancy show a negative relationship between concentration and surface energy, which may be related to the relative higher electronegativity of F and O, which leads to a net negative charge on the defect, localizing the electron density. These defects may have very little effect on the surface energy in comparison to pristine metallic system; however, the surface energy was still directly proportional to the defect concentration.



The surface energies were then implemented into the nucleation model to see how dendrite growth was impacted by these defects. Fig. 6 shows dendrite growth for selected defects at a concentration of $2.9536(10^{18}) \text{ defects cm}^{-2}$. The growth seen in Fig. 6b for a pristine Li anode with a surface energy of 0.46 J/m² is growth across the surface. This unstable plating is due to the low surface energy of the Li anode. When impurity atoms are present that cause an increase in the surface energy, the growth across the anode is significantly denser (Fig. 6c and d). The higher surface energy creates a large energy barrier for nucleation and growth. Because of this large energy barrier, the rate at which the system forms new nuclei is low, the nucleates are larger with smaller surface curvatures resulting in more stable growth and a smaller reaction flux at the anode-electrolyte interface[23,25]. This stable growth at the interface results in the system remaining in a reaction-limited regime, leading to denser growth. This improvement in plating stability can be seen when impurity atoms are present in the anode (Fig. 6d) because it creates the highest energy barrier. If impurity atoms such as F are present in the crystal lattice, the surface energy is significantly higher, resulting in significantly more branched growth (Fig. 6a). This is due to fast nucleation and growth at the defects.

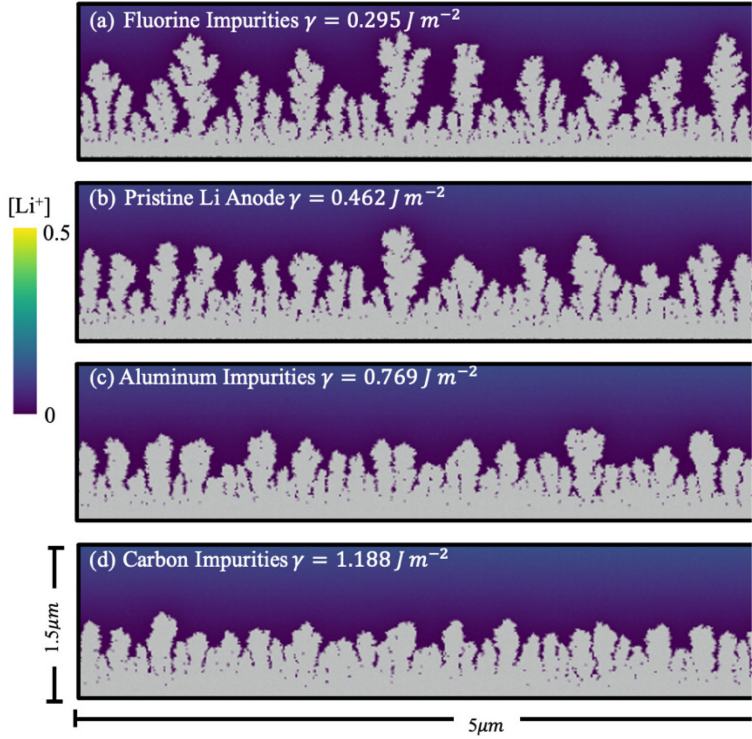


Figure 6: Model prediction of dendrite growth on Li anodes with varying defect type. (a) Pristine Li anode (b) $2.9536(10^{18})$ defects cm^{-2} Fluorine Impurity atoms (c) $2.9536(10^{18})$ Aluminum Impurity atoms (d) $2.9536(10^{18})$ defects cm^{-2} Carbon Impurity atoms. The color scheme for Li^+ and the solid particles are colored grey for visualization.

To further explain these growth regimes, we can visualize the effect of surface energy on the reaction. In the following, we will study the effect of surface energy on the reaction by isolating the effect that surface energy has on the reaction. In the following, the potential was kept constant between cases so that the effect of surface

larger reaction at the interface due to increased reaction sites and This results in the rapid consumption of Li^+ that outweighs the trans leading to the highly negative flux observed at the tips of the dendrite these conditions, the system exists in a transport-limited regime and t the tips of the dendrites before reacting resulting in the branched gro in Fig. 7b[63].

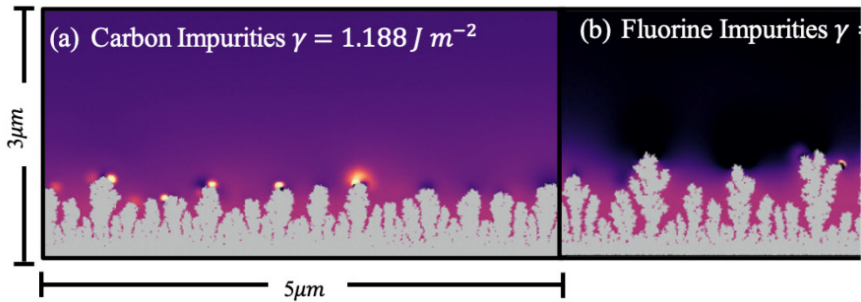


Figure 7: Model prediction of Li dendrite growth on (a) Surface with carbon impurities and (b) surface with Fluorine impurities and a low surface energy. The Li^+ flux are colored gray to distinguish them from the electrolyte.

In addition to how the type of defect impacts Li plating, the effect of these defects has on plating was also studied. Fig. 8 shows the

energy surface with the smaller amount of F impurity atoms results in smaller dendrites (Fig. 8d) than the surface with the higher concentration of

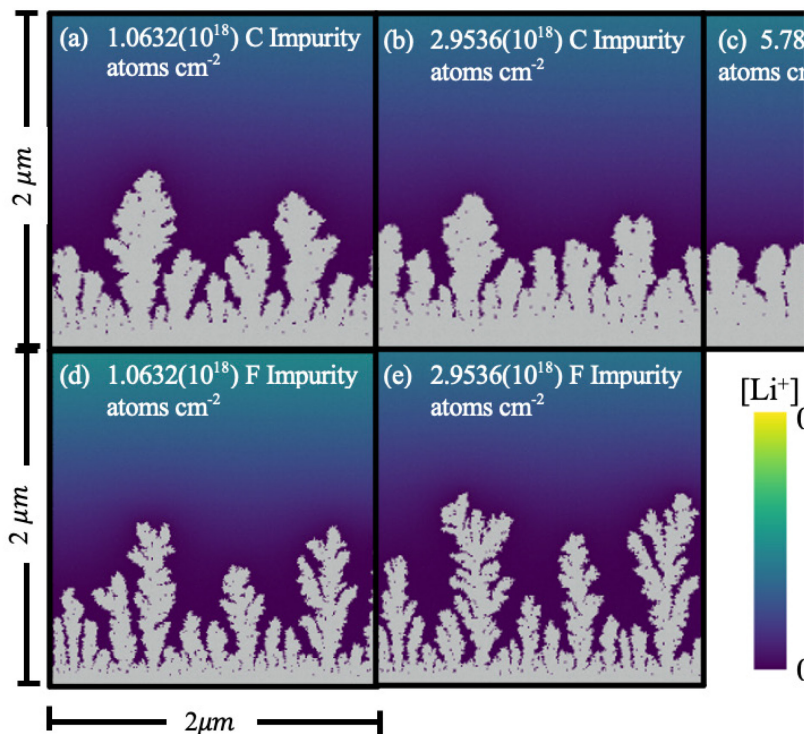


Figure 8: Predicted dendrite growth on surfaces with varying concentration 1.0632(10^{18}) C Impurity atoms cm^{-2} (b) 2.9536(10^{18}) C Impurity atoms cm^{-2} (c) 5.78(10^{18}) F Impurity atoms cm^{-2} (d) 1.0632(10^{18}) F Impurity atoms cm^{-2} (e) 2.9563(10^{18}) F Impurity atoms cm^{-2}

While F impurities in the Li metal anode led to smaller inter-

(001) produces significantly larger and more branched dendritic structures compared to the pristine Li anode (Fig. 9b) due to its low interfacial energy. Conversely, the (111) orientation results in a suppression of dendrite growth and denser structure.

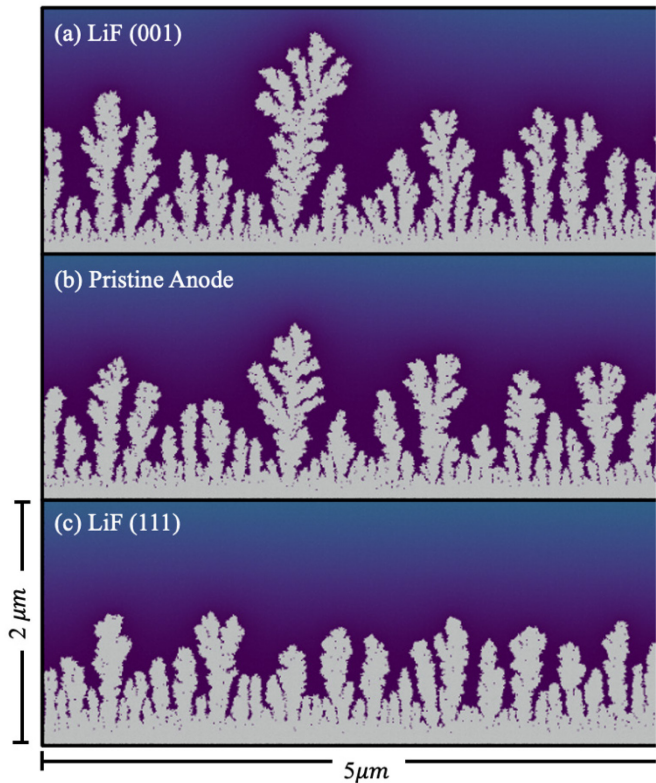
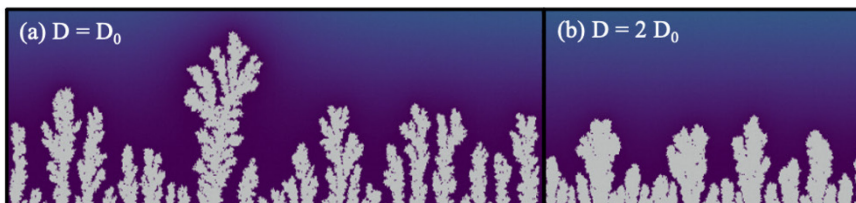


Figure 9: Model prediction for dendrite growth at the anode comparing different SEI components with the pristine Li anode. (a) LiF (001), 0.35 J m^{-2} (b) pristine Li anode, 0.462 J m^{-2} and (c) LiF (111), 0.58 J m^{-2} .

dendrite growth for the anode surface utilizing the surface energy of the varying diffusion coefficients. The LiF (001) surface energy was chosen to study the impact that transport properties play on Li deposition under the effect of the surface energy. Fig. 10a shows the dendrite growth when the diffusion coefficient is equal to the baseline diffusion coefficient, D_0 . Fig. 10b through c show the effect of the diffusion coefficient near the interface increases from twice the base-line diffusion coefficient to five times that of the base-line diffusion. When the diffusion coefficient increases, the dendrites become denser. However, there are still clear dendritic structures at the interface. As the diffusion coefficient increases to $5D_0$ (Fig. 10c) and further, the plating becomes homogenous, and a moss-like morphology is observed. The system remains in a reaction limited regime as opposed to the transport limited regime shown in Fig. 10a. These simulations were compared at an equivalent state-of-charge and mass of Li deposited.



The increased plating stability observed experimentally, which is present, is not due to the interfacial energy alone. Instead, for LiF energy is low, it is dominated by the improved transport of Li^+ at the dendrite growth and a moss-like morphology. While F substitutional d in decreased interfacial energy and problematic dendrite growth (Fig. or question the improved performance seen with an LiF-rich SEI la results indicate the significance of both nucleation and growth in un how the interplay between various physics (i.e. Li^+ transport vs. sur the suppression of dendrites and a more homogenous plating.

5. Conclusions

A novel dendrite growth model that captures the nucleat electrolyte interface through the expansion of a previous mo transport[11,13], a spatially and temporally varying electric field kinetics[10] was presented. To capture nucleation physics, a radial g hemispherical nucleate as well as a steady-state nucleation rate v

the accuracy of the model. In addition, the ability of the model to reproduce experimental results was evaluated through qualitative comparison to experimental results. The model predicted that a higher interfacial energy surface led to decreased nucleation and a suppression of dendrite growth [17,21–26]. The morphology of the dendrites predicted by the nucleation model was in good agreement with the experimental results for both the high and low surface energy conditions.

The model was then coupled with DFT calculations to evaluate the effect of impurity atoms, and the concentration of these defects impacted the surface energy. DFT was used to calculate the surface energy for the Li anode when specific impurities (N, C, P, Al) and vacancies were present. These energies were then compared to the surface energy of the Li metal anode. The results show that when certain impurity atoms are present, the surface energy increases while other impurities such as F decrease the surface energy. Vacancies show very little deviation from the pristine anode. Additionally, a linear relationship between the concentration of impurity atoms and surface energy was observed. For atoms with smaller electronegativities (N, C, P, Al) surface energy and concentration were directly proportional meaning that as the concentration of impurity atoms increases, the surface energy increases. Conversely, for high electronegativity atoms such as F, the surface energy decreases as the concentration of impurity atoms increases.

surface. When C impurity atoms were present, the surface energy increased, and the suppression in the dendrite growth was observed. Finally, the surface energy reached the lowest surface energy (0.294 J m^{-2}) resulting in extensive dendrite growth. In addition to the type of defect present, the concentration of defects also played a role. For example, F, as the concentration of defect atoms increased, the surface energy decreased, leading to branched and problematic dendrites. C impurity atoms had the opposite effect. As the concentration of impurity atoms of C increased, the surface energy decreased, which resulted in significant improvement to the homogeneity of Li plating across the interface.

Based on the predicted results from the nucleation-SPH model and the experimental results it can be concluded that higher surface energy leads to more stable Li plating[16,17,21–26]. Additionally, this work shows that using a metal anode such as C can greatly improve the deposition where there is instability. Further, a higher concentration of beneficial atoms will lead to more stable plating across the anode due to the direct proportionality between concentration and surface energy and the large energy barrier for the system to overcome to form new nuclei.

specified surface facets resulting in more growth, when considering
consider the impact it has on Li^+ transport near the anode. It was shown
transport effects as well as the interfacial energies, an LiF-rich SEI layer
transport, a suppression of dendritic growth, and a more stable inter-

In this work, we consider the impact that interfacial energy has on SEI
morphology by decoupling the interfacial energy from other physical parameters
allowing us to compare each case under equivalent conditions. While this
regarding the impact of interfacial energies under the conditions that we study
is important to note that this does not negate the importance of other
parameters such as charging conditions, transport properties, and electrolyte
example, while the trends presented exist under our specific conditions, they
applied to the system the impact that interfacial energy has on the morphology
influential. Thus, while computational models like the one presented here provide
insight into the physics occurring and how they are influenced by individual
the system in its entirety through the combination of computation and experiment
critical to the commercialization of lithium metal batteries.

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Author Declarations

Conflict of Interest

The authors have no conflict to disclose.

Data Availability

Data on dendrite growth and morphology were obtained via the LAMMPS code base modified for SPH and our system. The SPH data that support the findings of this study are available in the GitHub repository and the codes used to obtain the data are available at <https://github.com/emilymryan/LAMMPS-Dendrite-Nucleation-and-Growth>.

D_i	diffusion coefficient, $\mu\text{m}^2 \text{s}^{-1}$
e^-	electrons
$E_{Bulk\ of\ Defect}$	energy per atom of a chunk of defect atoms, J
E_{defect}	energy of Li slab of a specific number of defected atoms
E_{surf}	slab surface energy, J
F	Faraday constant, C mol^{-1}
g_c	number of atoms in the critical nucleus
ΔG	formation energy of critical nucleus, J
h	smoothing length, μm
i_0	exchange current density, $\text{A } \mu\text{m}^{-2}$
k	curvature, μm^{-1}
k^0	reaction rate constant, $\mu\text{m s}^{-1}$
K_B	Boltzmann constant, J K^{-1}
Li_+	lithium ions
m	mass of an individual particle, μg
M^+	cations
n	number of nucleates in the system
$\vec{n}$	normal vector
N	total number of atoms per unit surface area
N_A	Avogadro's number, μmol^{-1}
r	radius of nuclei, μm
r_{eq}^*	critical nuclei radius, μm
$\vec{r}_f$	location in the liquid domain (diffusion layer)
$\vec{r}_{lj}$	distance between particles, μm
$\vec{r}_s$	location in the solid domain (anode and dendrites)
r_0	initial nuclei radius
R	ideal gas constant, $\text{J mol}^{-1} \text{K}^{-1}$
S_c	surface area of nucleate exposed to the electrolyte, μm^2
S_n	flux for a single hemispherical nucleate, $\mu\text{mol } \mu\text{L}^{-1} \text{s}^{-1}$
S_s	total flux in system, $\mu\text{mol } \mu\text{L}^{-1} \text{s}^{-1}$
t	time, s

η	overpotential, V
Θ	contact angle
μ_i	migration coefficient, $\mu\text{m}^2 \text{V}^{-1} \text{s}^{-1}$
ρ	density of a particle, $\mu\text{g} \mu\text{m}^{-3}$
ρ_{charge}	net charge density, $\text{C} \mu\text{m}^{-3}$
Φ_{App}	applied potential, V
Φ_{eq}	equilibrium potential, V
ω_c	frequency of collision of cations with critical nuclei, s
Ω_f	fluid domain (diffusion layer)
Ω_s	Solid domain (anode and dendrites)

Abbreviations

Al	aluminum
C	carbon
CNT	classical nucleation theory
CSR	continuum surface reaction
Cu	copper
DFT	density functional theory
F	fluorine
LAMMPS	large-scale atomic/molecular massively parallel simulation
Li	lithium
N	nitrogen
ND	nanodiamond
O	oxygen
P	phosphorus
PAW	projector-augmented wave
P2D	pseudo two-dimensional
SEI	solid-electrolyte interphase layer
SPH	smoothed particle hydrodynamics

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