

1 **Multilayer Anisotropy Along the Alaska-Aleutians Subduction Zone**

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14 **Summary**

15 Increasing evidence from seismic methods shows that anisotropy within subduction zones should  
16 consist of multiple layers. To test this, we calculate and model shear wave splitting across the  
17 Alaska-Aleutians Subduction Zone (AASZ), where previous studies have argued for separate  
18 layers of anisotropy in the subslab, slab, and mantle wedge. We present an updated teleseismic  
19 splitting catalog along the span of the AASZ, which has many broadband seismometers recently  
20 upgraded to three components. Splitting observations are sparse in the Western Aleutians, and fast  
21 directions are oriented generally trench parallel. There are significantly more splitting  
22 measurements further east along the AASZ. We identify six regions in the Central and Eastern  
23 Aleutians, Alaskan Peninsula, and Cook Inlet with a high density of splits suitable for multilayered  
24 anisotropy analyses. These regions were tested for multilayer anisotropy, and for five of the six  
25 regions we favor multiple layers over a single layer of anisotropy. We find that the optimal setup  
26 for our models is one with a dipping middle layer oriented parallel to paleospreading. A prominent  
27 feature of our modeling is that fast directions above and below the dipping layer are generally  
28 oriented parallel to the strike of the slab. Additionally, we lay out a framework for robust and  
29 statistically reliable multilayer shear wave splitting modeling.

30

31 **Keywords:** Seismic anisotropy; Dynamics of lithosphere and mantle; Mantle processes;  
32 Subduction zone processes

33

34 **1. Introduction**

35 Insights from a variety of seismic methods such as receiver functions (e.g., Wirth and Long,  
36 2012), surface wave analyses (e.g., Liu et al., 2022), and shear wave splitting (e.g., Reiss et al.,  
37 2018) have shown that there are multiple layers of anisotropy in subduction zones. Analyzing bulk  
38 seismic anisotropy, which in the upper mantle generally arises from the macroscopic alignment of  
39 olivine crystals (e.g., Karato et al., 2008), is important in assessing ongoing mantle dynamics. The  
40 most common method to image anisotropy, teleseismic shear wave splitting (e.g. Long and Silver,  
41 2009), is path-integrated. Any anisotropy existing from the core-mantle boundary to the receiver  
42 will be sampled by the seismic phases of interest (e.g., SKS, SKKS, PKS, collectively termed  
43 XKS). Untangling the contributions from multiple layers to total shear wave splitting requires  
44 forward modeling (e.g., Silver and Savage, 1994). An excellent location to test for and model these  
45 possible anisotropic layers is the Alaska-Aleutians Subduction Zone (AASZ, see **Fig. 1**). Previous  
46 teleseismic (e.g., Lynner, 2021; McPherson et al., 2020; Yang et al., 2021), local (e.g., Karlowska  
47 et al., 2020; Lynner et al., 2024; Richards et al., 2021), and source-side (Lynner and Long, 2014;  
48 Walpole et al., 2017) shear wave splitting studies, as well as surface-wave (Feng et al., 2020; Wang  
49 and Tape, 2014) and body-wave (Gou et al., 2019; Liu et al., 2022; You and Zhao 2012)  
50 tomography studies have suggested that seismic anisotropy varies vertically within the subduction  
51 zone.

52 We provide new teleseismic splitting measurements along the length of the AASZ, a  
53 roughly 3000-km region that has only recently been fully instrumented (with more deployments  
54 planned). Within the AASZ, slab age decreases from  $\sim$ 80 Myr in the west to  $\sim$ 45 Myr in the east  
55 (Heuret and Lallemand, 2005), with slab dip generally shallowing from west to east (Lallemand et  
56 al., 2005). The northeastern portion of the subduction zone likely has toroidal flow around the slab

57 edge (e.g., Jadamec and Billen, 2012), which induces complex seismic anisotropy and mantle  
58 deformation (Yang et al., 2021).

59 Anisotropy in subduction zones exists in four likely regions: the subslab mantle, the slab,  
60 the suprabslab mantle wedge, and the upper plate. Subslab anisotropy may result from entrained  
61 flow associated with the slab (Faccenda and Capitanio, 2013; Walpole et al., 2017) or from more  
62 complicated asthenospheric flow (Long and Silver, 2009; Packzowksi et al., 2014). Both trench  
63 parallel and perpendicular subslab fast directions have been reported in the subslab mantle of the  
64 AASZ (e.g., Lynner and Long, 2014; Walpole et al., 2017). Debate exists regarding the strength of  
65 anisotropy in the subducting slab, though Long and Silver (2009) argue that it likely has a minimal  
66 contribution globally. Other studies, however, suggest slabs may have significant anisotropy due  
67 to fabrics arising from bending-induced faults coupled with dehydration reactions (Faccenda et al.,  
68 2008; Healy et al., 2009; Lee et al., 2020, 2021) or due to fossil anisotropy related to  
69 paleospreading (Audet 2013; Chen et al., 2015; Song and Kim, 2012).

70 Mantle wedge anisotropy may arise from two-dimensional corner flow (e.g., Hall et al.,  
71 2000; Long et al., 2007), olivine fabric transitions due to changes in temperature, pressure, and  
72 hydration (e.g., Jung, 2017; Jung and Karato, 2001; Jung et al., 2006), or changes in flow direction  
73 linked to the slab (e.g., Faccenda and Capitanio, 2012; Jadamec and Billen, 2010; Long and Silver,  
74 2008). The upper plate likely contributes the least anisotropy in subduction zones, with most  
75 estimates placing an upper bound on crustal delay times of 0.3 seconds (Savage, 1999; Silver,  
76 1996). Upper plate lithosphere may contribute if it is thicker and has fossil anisotropy, as in  
77 continents (e.g., Fouch and Rondenay, 2006; Silver, 1996). However, the dynamics of subduction  
78 zones likely thins the upper plate through increased heating (McKenzie, 1969), slab dehydration  
79 (Arcay et al., 2006), and mantle convection (Currie et al., 2008). In the AASZ we have good

80 constraints on subslab anisotropy from source-side splitting (Lynner and Long, 2014; Walpole et  
81 al., 2017) and mantle wedge/upper plate anisotropy from local splitting (Karbowska et al., 2021;  
82 Lynner et al., 2024; Richards et al., 2021; Yang et al., 1995; Yang et al., 2021). Surface-wave and  
83 body-wave tomography studies provide information on anisotropy in the slab itself (Feng et al.,  
84 2020; Gou et al., 2019; Liu et al., 2022; You and Zhao, 2012; Wang and Tape, 2014).

85 The eastern portion of the AASZ has the needed density of shear wave splitting results to  
86 test for possible contributions to seismic anisotropy from different source layers: the subslab, slab,  
87 and mantle wedge. We perform forward modeling of multilayer anisotropy at six subregions within  
88 the AASZ and find that splitting in five subregions is statistically better fit by multiple layers of  
89 anisotropy. We find that our modeling favors flow in the subslab and mantle wedge oriented  
90 parallel or oblique to slab strike, consistent with previous studies (e.g., Liu et al., 2019; You and  
91 Zhao, 2012). Our modeling further demonstrates that a dipping middle layer with the a-axis of  
92 anisotropy oriented parallel to paleospreading is preferred.

93

#### 94 *1.1 Previous Teleseismic Splitting*

95 Several recent studies have examined teleseismic shear wave splitting along portions of the  
96 AASZ, with most focused on the Alaskan subduction zone and eastern Aleutians (e.g., Christensen  
97 and Abers, 2010; Hanna and Long, 2012; Lynner, 2021; McPherson et al., 2020; Perttu et al., 2014;  
98 Richards et al., 2021; Venereau et al., 2019; Yang et al., 2021). There are very few published  
99 teleseismic shear wave splitting results for the western and central Aleutians (e.g., Long and Silver,  
100 2008; McPherson et al., 2020) due to noisy conditions and a previous lack of instrumentation,  
101 though the global compilation of Long and Silver (2008) reports low delay times and trench-  
102 parallel fast directions.

103        The eastern Aleutians are better represented in published studies. Splitting delay times are  
104    generally low, and fast directions are mostly trench parallel (Hanna and Long, 2012; McPherson  
105    et al., 2020; Venereau et al., 2019). Trench parallel fast directions continue into the Alaskan  
106    peninsula (Lynner 2021; McPherson et al., 2020; Venereau et al., 2019). Outboard of the Alaskan  
107    peninsula, splitting becomes more variable. Lynner (2021) reported a transition from trench-  
108    parallel to trench-perpendicular fast directions near the Semidi segment and Shumagin gap,  
109    possibly linked to increased hydration and serpentinization.

110        Further northeast along the subduction zone, splitting is more complicated likely due to  
111    changes in the slab. In the Kenai Peninsula where the slab is relatively flat, fast directions are  
112    generally parallel to plate motion (McPherson et al., 2020; Richards et al., 2021). Events coming  
113    from the east, however, have splits that tend to be more trench parallel (McPherson et al., 2020;  
114    Perttu et al., 2014). The edge of the Pacific slab produces complex mantle flow, with splitting fast  
115    directions that curve around it (McPherson et al., 2020; Venereau et al., 2019). Splitting further  
116    inland in Central Alaska similarly seems linked to the dynamics of the slab (Christensen and Abers,  
117    2010) and has been modeled with multiple layers of anisotropy (Yang et al., 2021).

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### 119    *1.2 Previous Local splitting*

120        Splitting from local-S phases has a relatively small depth range over which it samples  
121    anisotropy compared to splitting from core-refracted XKS phases, and it provides excellent  
122    constraints on the mantle wedge (e.g., Long and Wirth, 2013). Local-splitting studies in the western  
123    and central Aleutians are generally lacking, though Long and Silver (2008) have fast directions  
124    oriented either trench parallel or trench oblique with up to 1.5 seconds of delay time. Lynner et al.  
125    (2024) report mostly trench parallel fast directions in the Central Aleutians, with delay times up to

126 3.0 seconds. In the Alaskan Peninsula, fast directions are mostly oriented trench parallel in the  
127 forearc, with a transition to trench perpendicular in the backarc; delay times vary from 0.1 to 3.0  
128 seconds (Karlopska et al., 2020; Lynner et al., 2024; Richards et al., 2021; Yang et al., 1995).  
129 Local splitting in Central Alaska near the edge of the Pacific slab is oriented roughly trench  
130 oblique, with an average delay time of 0.4 seconds (Yang et al., 2021).

131 Previous studies demonstrated that there is disagreement between local and teleseismic  
132 splitting (Karlopska et al., 2020; Richards et al., 2021). It is important to note that a direct  
133 comparison is not possible given differences in frequency content and incidence angle of the rays.  
134 Regardless, both local and teleseismic studies have shown an increase in delay time with increasing  
135 mantle wedge path lengths (Christensen and Abers; Karlopska et al., 2020; Richards et al., 2021).  
136 This suggests that the mantle wedge is anisotropic, and that it is important to consider the  
137 contribution of anisotropy in the mantle wedge to the splitting of teleseismic XKS phases.

138

## 139 **2. Methods**

### 140 *2.1 Shear wave splitting*

141 We measured shear wave splitting at 152 broadband stations from 12 networks spanning  
142 the Western Aleutians through the Cook Inlet to the Kenai Peninsula of Alaska. Network details  
143 are in **Supplemental Text 1**. We measure splitting from the beginning of data availability for each  
144 station through August 2022. Splits were calculated using an updated version of the SplitLab  
145 package (Deng et al., 2017; Wüstefeld et al., 2008). We use an epicentral distance range of 90° to  
146 160°, which includes optimal distances for PKS and SK(K)S phases. A lower magnitude cutoff of  
147 Mw 5.7 was used. Waveforms were band-pass filtered between 0.04 and 0.125 Hz.

148        The goal of shear wave splitting is to recover both the fast direction (phi) and delay time  
149 (dt) of the split wave. This provides information on the orientation of anisotropy through the fast  
150 direction, and the strength of anisotropy through the delay time. Reported splits were calculated  
151 using the minimum energy method (Silver and Chan, 1991). A common quality control for shear  
152 wave splitting is agreement between methods, so we also calculated solutions for the rotation  
153 correlation method (Bowman and Ando, 1987). Agreement within 15° between the two methods  
154 was required for a split to be considered good, and within 25° for fair. Additional quality controls  
155 on splitting included a signal-to-noise ratio above 5.0, a fast direction error of 25° or less, a delay  
156 time error of 0.7 seconds or less, and a correction from initially elliptical particle motion to  
157 rectilinear particle motion. Example splits are shown in **Supplemental Fig. S1**.

158        We only show fair and good splits in the figures here, though we included some poor splits  
159 with additional quality controls when modeling our results to improve backazimuthal distribution.  
160 Poor splits included in modeling were required to have error ranges of 35° or less for fast direction  
161 and 1.0 seconds for delay time. These splits also used the same values for the difference between  
162 methods. Finally, these poor splits were required to have the same elliptical-to-rectilinear particle  
163 motion as fair and good splits. Nulls (events with no evidence of splitting) were determined from  
164 their initial rectilinear particle motion and a disagreement in delay time between the minimum  
165 energy method (with high delay times) and the rotation correlation method (with low delay times,  
166 close to 0 seconds). An additional metric, splitting intensity (Chevrot, 2000), was calculated and  
167 used to determine nulls: this value is characteristically close to 0 for null events.

168

169        *2.2 Multilayer Modeling*

170 When a shear wave passes through multiple anisotropic layers, it undergoes splitting in  
171 each layer. The signal at the receiver is thus the aggregate of splitting in all layers and is commonly  
172 referred to as “apparent” splitting. For two layers of anisotropy, this results in backazimuthal  
173 periodicity of 90° for changes in fast directions and delay times (e.g., Silver and Savage, 1994).  
174 The inclusion of dipping layers or more than two layers of anisotropy yields more complicated  
175 backazimuthal variations, but still largely retains the 90° periodic nature of the two-layer case.  
176 This periodicity can be used to model the layers that generated the apparent splitting.

177 Layered anisotropy has been modeled from shear wave splitting in various regions and  
178 tectonic settings including subduction zones (e.g., Currie et al., 2004; Eakin and Long, 2013),  
179 transform plate boundaries (e.g., Özalbey and Savage, 1994; Silver and Savage, 1994), orogenic  
180 belts (e.g., Levin et al., 1999), rift zones (e.g., Gao et al., 2010; Hammond et al., 2014), cratonic  
181 regions (e.g., Nathan et al., 2021; Yang et al., 2014), and at ocean islands (e.g., Walker et al., 2001).  
182 Most layered anisotropic studies test for two layers, but some have tested for three layers when  
183 appropriate (e.g., Brechner et al., 1998; Eakin and Long, 2013; Levin et al., 1999; Yang et al.,  
184 2014). Silver and Savage (1994) laid out a method for modeling the effect of multiple layers of  
185 anisotropy, which we follow here.

186 We tested the possibility of one, two, and three layers of anisotropy. In the three-layered  
187 cases, we include models where the middle layer exhibits dipping axes of anisotropy to  
188 approximate the slab and models where all three layers are estimated to be horizontal. This gives  
189 us two suites of three-layered models: horizontal-dipping-horizontal (HDH) and horizontal-  
190 horizontal-horizontal (HHH). One- and two-layer models were calculated using M-Split, a  
191 MATLAB plugin (Abgarmi and Özcar, 2017). Three-layer models were generated following a  
192 similar algorithm using MSAT (Walker and Wookey, 2012), another MATLAB plugin which

193 allows for layers with dipping axes of anisotropy. We will refer to the bottom layer in our models  
194 as the lower layer, and the topmost layer as the upper layer; the respective fast directions and delay  
195 times have the same terminology (see **Supplemental Fig. S2** for schematics of the model  
196 configurations). Note that because the modeling is carried out from a ray perspective, the lower  
197 layer is the first anisotropic layer the ray traverses. In addition to good and fair splits, we also  
198 included quality-controlled poor splits for our modeling. These had error ranges of 35° or less for  
199 fast direction and 1.0 seconds for delay time. We did not include nulls in our modeling.

200 For our layered anisotropy analyses, we implemented the unweighted misfit scheme of M-  
201 Split (Abgarmi and Özcar, 2017). The same misfit calculation was used for all our models. We  
202 also calculated bandfit misfit (Eakin and Long, 2013) for all models, which is an estimate of  
203 whether or not an observed apparent split matches the modeled split. For each measurement, if  
204 both the modeled fast direction and delay time were within the error bounds of the observed split,  
205 the bandfit misfit was set to zero. Otherwise, the bandfit misfit was set to one. This provides a  
206 helpful constraint on the number of measurements matched by each model.

207 Vertically propagating plane waves were assumed for all horizontal layers given the near-  
208 vertical incidence of teleseismic XKS phases. To generate anisotropy from a dipping layer, we  
209 assumed a hexagonal olivine symmetry that was approximated by a transversely isotropic mantle  
210 (Chevrot and van der Hilst, 2003) and rotated the Christoffel matrix using a change of basis (i.e.,  
211 Bond, 1943; Walker and Wookey, 2012; see **Supplemental Text 2** for more information). This  
212 results in a dipping axis of symmetry for the anisotropy in the layer. The dipping layer is treated  
213 as having uniform thickness. For horizontal layers, we assumed that the fast direction and delay  
214 time were constant at all backazimuths. Thus all layers were approximated as horizontal.

215 The first step to model the dipping layers was determining appropriate slab parameters.  
216 The dipping layer is described by slab dip, anisotropic thickness, and the orientation of the a-axis  
217 of olivine (azimuth). Appropriate parameters were determined from Slab2 (Hayes et al., 2018). We  
218 defined a box around each region, and found values from Slab2 within this box (see **Supplemental**  
219 **Text 3** for the boundaries of each region). Because we modeled results at a regional scale, we  
220 tested a range of dips from Slab2. We tested various parameters to determine reasonable delay  
221 times, and ultimately chose a 30 km thick anisotropic layer to balance thickness and strength of  
222 anisotropy. This produced realistic delay times in the dipping layer (~0.5 seconds on average).  
223 There is a trade-off between the strength of anisotropy and the thickness of the dipping layer, so  
224 an identical effect could have been achieved using a thicker layer and weaker anisotropy. This  
225 choice in thickness is further motivated by previous studies that have argued anisotropy within the  
226 slab is likely limited to a relatively thin zone of less than 50 km (e.g., Audet, 2013; Faccenda et  
227 al., 2008). We also tested various orientations for the dipping layer, including strike of the slab,  
228 plate motion in a hotspot reference frame (Gripp and Gordon, 2002), and paleospreading  
229 determined from paleomagnetic data (Maus et al., 2009). Using a coarse grid ( $10^\circ$  increments for  
230 fast direction, 0.2 second increments for delay time), we determined the best-fitting dip as the  
231 value with the lowest unweighted misfit (**Supplemental Table 1**).

232 With the appropriate dipping-layer parameters determined, we ran the models on a finer  
233 grid for two layers and all three dipping layer orientations (trench parallel anisotropy, plate motion  
234 anisotropy, paleospreading anisotropy). For two-layer and three-layer models with a dipping layer,  
235 fast directions were tested from  $-90^\circ$  to  $90^\circ$  using a  $3^\circ$  increment. Delay times varied from 0.4 to  
236 3.0 seconds with 0.1 second increments. We used a coarser grid for the HHH model: fast direction  
237 ran from  $-90^\circ$  to  $90^\circ$  in  $10^\circ$  increments, with delay time running from 0.4 to 3.0 seconds in 0.2

238 second increments. For all setups, the model with the lowest unweighted misfit was deemed the  
239 best-fitting model. The final values used for all model configurations are shown in **Supplemental**  
240 **Table 1**. We also list the trench orientation as it is common for shear wave splitting studies in  
241 subduction zones to describe splits in relation to the trench (i.e., trench parallel or perpendicular).  
242 While slab strike and trench orientation are not necessarily linked, we note that for each modeled  
243 region the two are within 25° of one another, and therefore subparallel.

244 An important step in the layered modeling was to test against the null hypothesis of a single  
245 layer of anisotropy. We ran an F-test for nested models (Mendenhall and Sincich, 2016) to compare  
246 between one layer and multilayer models. This was necessary because there are differences in the  
247 degrees of freedom between each model type. We calculated the F-value as:

248

$$249 \quad F = \frac{(m_1 - m_n)/m_n}{(df_1 - df_n)/df_n} \quad (1)$$

250

251 where  $m_1$  and  $df_1$  are the misfit and degrees of freedom for the one-layer model, and  $m_n$  and  $df_n$  are  
252 the misfit and degrees of freedom for the multi-layer model. We evaluated the F-value at a  
253 probability level of 0.05. Degrees of freedom were calculated by subtracting the number of  
254 parameters for each model from the number of data points being tested. For a single layer, there  
255 were two parameters (fast direction and delay time). For two-layer and HDH models, there were  
256 four (two fast directions, two delay times); for HDH, the strike of the dipping layer, thickness of  
257 the dipping layer, and dip of the dipping layer were set in the final modeling and therefore not  
258 being searched for. For the HHH models, there were six (three fast directions, three delay times).

259 M-Split performs a grid-search for the best-fitting fast direction and delay time for a single  
260 layer of anisotropy (i.e., there is no backazimuthal variation in either parameter). However, a direct

261 comparison of misfit between models with different degrees of freedom is not possible. This is the  
262 utility of the nested model F-test, which considers the relative decrease in misfit compared to the  
263 decrease in degrees of freedom (more complex models have fewer degrees of freedom because  
264 more parameters are being searched for). Comparing the misfit of all models against the single-  
265 layer case using the F-test generally produces a suite of models that are statistically better than the  
266 single-layer case. This suite is a subset of the suite of models that is statistically indistinguishable  
267 from the lowest-misfit model for a given setup and degrees of freedom. For brevity, we will refer  
268 to this suite of models as robust multilayer models from here on out.

269

### 270 **3. Results**

#### 271 *3.1 Shear Wave Splitting Results*

272 We made a total of 761 split and null shear wave splitting measurements at 152 stations. A  
273 total of apparent 309 splits were of either fair or good quality at 116 stations, and 155 nulls at 74  
274 stations (**Fig. 2**). There are fewer apparent splits in the Western Aleutians than in the other regions.  
275 While station-averaged splitting parameters are often reported, we choose not to do so as our  
276 apparent splits exhibit significant backazimuthal variation that would be smoothed over with  
277 averaging. We begin by describing some general trends seen in our apparent splitting results.

278 Because one of the commonly reported orientations for fast directions in subduction zones  
279 is trench parallel, we compare apparent fast directions to the strike of the slab from Slab 2 (Hayes  
280 et al., 2018) according to longitude (**Fig. 3a**). The Western Aleutians have the fewest results, and  
281 apparent fast directions there are tightly clustered and close to slab strike. Moving further east,  
282 most apparent fast directions are not parallel to slab strike. We also compare apparent fast  
283 directions to longitude (**Fig. 3c**) and latitude (**Fig. 3d**). There is a general transition from negative

284 fast directions in the west, to scattered fast directions in the east with a general bias toward more  
285 positive values. This is likely a reflection of the slab strike parallel nature of splits in the Western  
286 Aleutians. Apparent delay times vary across the entire region, with a minimum of 0.4 seconds and  
287 a maximum of 3.5 seconds (both on Akutan Island). We note that while this is large variation in  
288 apparent delay times, these two extrema also have different fast directions and come from different  
289 backazimuths, congruent with multiple layers of anisotropy. The only observed general trends in  
290 delay time are slightly lower values in the Western Aleutians, which range from 0.7 to 1.9 seconds  
291 (**Fig. 3e-f**). Low delay times are found throughout the region, but the range of values increases  
292 moving further to the east.

293 Apparent fast directions across most of the AASZ are scattered and vary backazimuthally.  
294 We identify six regions with a high density of splits that show potential systematic variations in  
295 fast directions (**Fig. 4**). Apparent splits in all these regions show complex splitting patterns,  
296 particularly for the Eastern Aleutians and Okmok. Such backazimuthal variation is diagnostic of  
297 either a dipping axis of anisotropy or multiple layers of anisotropy (Silver and Savage, 1994), with  
298 the former exhibiting  $180^\circ$  periodicity and the latter  $90^\circ$  periodicity. This observation, coupled  
299 with conclusions from previous studies in the AASZ, is a primary motivation for our modeling of  
300 multiple anisotropic layers.

301 *3.2 Modeling Results*

302 We chose to focus our modeling effort on six broader geographic subregions as this  
303 increased the backazimuthal coverage in splitting. Models are generated only for areas with more  
304 than 25 apparent splits (boxed regions in **Fig. 1a**). This includes, from west to east: Okmok (11  
305 stations and 40 splits), the Eastern Aleutians (Akutan and Unalaska Islands, and Unimak; 17  
306 stations and 66 splits), Katmai National Preserve (11 stations and 49 splits), Augustine Volcano (9

307 stations and 30 splits), Iliamna Volcano (6 stations and 33 splits), and Redoubt Volcano (6 stations  
308 and 38 splits). A list of the stations is provided in **Supplemental Text 4**. We were not able to  
309 adequately model any regions west of Okmok due to more limited data coverage.

310 Our statistical analyses show that for all configurations we are able retrieve robust  
311 multilayer models except for at Redoubt where multilayer models are not statistically  
312 distinguishable from a single layer. We therefore do not examine the single best-fitting model as  
313 is done in many studies since this may not be representative of the whole suite of robust models.  
314 Rather, we look for trends in the whole suite of robust multilayer models. An example is shown in  
315 **Fig. 5** for Okmok (where the dipping layer is oriented parallel to paleospreading), other fast  
316 direction histograms are shown in **Supplemental Figs. S3-6**. The fast directions appear to be better  
317 modeled than the delay times (e.g., Aragon et al., 2017; Yuan and Levin, 2014). This may be a  
318 result of the overestimation of delay times when using the minimum energy method (Monteiller  
319 and Chevrot, 2010). As with other modeling studies, we choose not to further consider delay times  
320 as part of our modeling (e.g., Aragon et al., 2017; Dubé et al., 2020; Nathan et al., 2021).

321 A comparison between model configurations for Okmok is shown in **Fig. 6**. The lower  
322 layer for all three setups seems to coalesce on a single value (between 15° and 40°). The upper  
323 layer in the two layer and HHH cases have similar values (~25° to 40°), but the HDH case yields  
324 a different result (clustered around -90°/90°). The middle layer for the HHH case is poorly  
325 constrained with only small peaks, a finding that is consistent across all regions. Histograms for  
326 all regions other than Redoubt are shown in **Supplemental Figs. S3-6** and the modal fast direction  
327 for each setup (i.e., the peak in the histogram) is shown in **Table 1**.

328 Other regions show similar trends as Okmok. In the Eastern Aleutians, lower layer fast  
329 directions for all three configurations are similar, clustering between 50° and 70°. There is slightly

330 more spread in lower layer fast directions for the HHH case than for the two-layer and HDH cases.  
331 Upper layer fast directions for all three configurations are also similar with peaks between 25° and  
332 40°, though the distributions have a large negative skew. For Iliamna, the main peak in lower layer  
333 fast directions for all three model configurations is between 50° and 70°. The two-layer and HDH  
334 cases have other smaller peaks that occur in roughly the same locations (near -40° and between  
335 15° and 30°). The upper layers all have peaks between 30° and 50°, again with a negative skew.  
336 Histograms for all regions are addressed in further detail in **Section 4.2**.

337

338 **4. Discussion**

339 We find that the eastern portion of the AASZ has a sufficient number of shear wave splitting  
340 results to test for contributions from multiple layers of anisotropy. To analyze the nature of depth-  
341 dependent anisotropy in the AASZ, we tested our teleseismic splitting results against models with  
342 one, two, and three layers of anisotropy. An important consideration that is often ignored in layered  
343 modeling of shear wave splitting results is the possibility of a dipping layer. We include a dipping  
344 middle layer in our modeling with several tectonically derived fabrics (plate motion, slab strike,  
345 paleospreading). We identified six subregions with the need backazimuthal coverage to model the  
346 layered anisotropy signal (shown in **Fig. 1a**). Of these subregions, five have robust multilayer  
347 models. Below, we further discuss our preferred layered model in **Section 4.1**. We then compare  
348 the results of our modeling to tectonic constraints and previous splitting and tomography studies  
349 in **Section 4.2**. Finally, we lay out a method to produce robust layered models of shear wave  
350 splitting in **Section 4.3**.

351 *4.1 Preferred Model*

352 Apart from Redoubt, the best solution is one with three layers with a dipping middle layer  
353 of anisotropy. The lower layer likely represents the subslab mantle, the middle dipping layer likely  
354 represents the slab, and the mantle wedge is the upper layer. This is consistent with observations  
355 from other studies that have found at least three distinct regions of anisotropy within the AASZ.  
356 Source-side splitting studies suggest a subslab anisotropic signal (e.g., Lynner and Long, 2014;  
357 Walpole et al., 2017). Local-S splitting constraints show a significant mantle wedge component  
358 (Karbowska et al., 2020; Lynner et al., 2024; Richards et al., 2021; Yang et al., 1995; Yang et al.,  
359 2021), and teleseismic splitting studies (Richards et al., 2021) and anisotropic tomography (Gou  
360 et al., 2019; Liu et al., 2022; You and Zhao, 2012) show that the slab is anisotropic. We place less  
361 weight on the HHH models because they universally result in a middle layer that is poorly  
362 constrained by our splitting data (**Fig. 6**). Additionally, the HHH models generally provide broadly  
363 the same upper- and lower-layer solutions as the two-layer and HDH cases (**Supplemental Figs.**  
364 **S3-6**).

365 For all regions except Redoubt, there is a suite of models that are statistically better than  
366 the one-layer case. This demonstrates the necessity of testing the null hypothesis of a single layer  
367 of anisotropy. While two-layer solutions oftentimes have slightly lower misfits than three-layered  
368 cases, they are not statistically distinguishable given the difference in free parameters. Given the  
369 evidence from other seismic studies that the AASZ should have an anisotropic slab plus two  
370 additional layers of anisotropy, we prefer the HDH case to the two-layer one.

371 The final constraint that we place on our models is the orientation of the dipping layer. The  
372 choice of orientation for the dipping layer does not seem to have a large effect on the final solution  
373 (see the **Supplemental Figs. S8-9** for all the HDH histograms). We therefore must rely on tectonic  
374 and geologic information to infer the best orientation for the middle dipping layer. Global and

375 regional surface wave tomography (Debayle and Ricard, 2013; Maggi et al., 2006), regional body  
376 wave tomography (Gou et al., 2019; You and Zhao, 2012), and body-wave travel times (Shearer  
377 and Orcutt, 1986) show evidence that the Pacific slab most likely has anisotropy oriented parallel  
378 to paleospreading. Studies of other slabs using receiver functions (Audet, 2013; Song and Kim,  
379 2012) and shear wave splitting (Chen et al., 2015) have also provided evidence for paleospreading-  
380 parallel anisotropy in the subducting slab. We therefore prefer a model with the middle dipping  
381 layer oriented parallel to paleospreading, although we tested and report all three plausible middle  
382 layer cases here (**Supplemental Figs. S8-9**).

383 We will restrict our further discussion to the five regions (Augustine, the Eastern Aleutians,  
384 Iliamna, Katmai, and Okmok) that have HDH models statistically better than the single-layer case.  
385 The misfit for the multilayer cases at Redoubt is generally lower than for a single layer, but the  
386 difference in degrees of freedom results in statistically worse models. Future studies with increased  
387 backazimuthal coverage may resolve this, especially as two other regions near Redoubt (Augustine  
388 and Iliamna) are both fit well by multiple layers of anisotropy, and a previous study further to the  
389 northeast explicitly modeled multiple layers of anisotropy (Yang et al., 2021).

390

391 *4.2 Tectonic Interpretation*

392 In **Fig. 7**, we show histograms of our preferred model for the five regions with robust  
393 multilayer models. In general, both the upper- and lower-layer fast directions converge. The peak  
394 of each histogram is shown in **Table 1**. We begin by comparing the distribution of models to  
395 tectonic constraints, then previous splitting results. As noted in **Section 4.1**, our preferred model  
396 is one in which the lower layer of anisotropy is the subslab, the middle dipping layer (oriented  
397 parallel to paleospreading) is the slab, and the upper layer is the mantle wedge.

398 To test for possible tectonic contributions, we compare our robust multilayer model suites  
399 to plate motion in a hotspot reference frame (Gripp and Gordon, 2002), the strike of the slab (Hayes  
400 et al., 2018), and the paleospreading direction (Maus et al., 2009). These have all been suggested  
401 as possible orientations for anisotropy within subduction zones (e.g., Long and Wirth, 2013; Long  
402 and Silver, 2009). In this region, plate motion varies from  $314^{\circ}$  to  $329^{\circ}$  (Gripp and Gordon, 2002),  
403 or from  $-46^{\circ}$  to  $-31^{\circ}$  in the standard  $-90^{\circ}$  to  $90^{\circ}$  shear wave splitting fast direction coordinate  
404 system. Except for secondary peaks for Iliamna at  $-27^{\circ}$  and Katmai at  $-40^{\circ}$ , plate motion does not  
405 correlate with modeled lower-layer fast directions. It also only correlates with secondary peaks in  
406 modeled upper-layer fast directions (for Katmai and the Eastern Aleutians at  $-40^{\circ}$ ). This suggests  
407 that slab-entrained asthenospheric flow or simple 2-D corner flow (which would both be oriented  
408 parallel to plate motion) is not a prominent feature of the modeled portions of the AASZ.  
409 Paleospreading estimated from paleomagnetic data in this region (Maus et al., 2009) is predicted  
410 to be roughly N-S ( $0^{\circ}$ ) or E-W ( $90^{\circ}$ ), and it appears to be an equally poor match for our modeled  
411 fast directions, only overlapping with the lower layer fast directions for Augustine near  $90^{\circ}$  and  
412 some of the upper layer fast directions for the Eastern Aleutians near  $0^{\circ}$ . This is not surprising, as  
413 paleospreading is most likely to cause anisotropy within the slab (as modeled here) rather than the  
414 subslab or mantle wedge.

415 A better correlation exists between the direction parallel to slab strike and our modeled fast  
416 directions. The lower layers for Katmai ( $33^{\circ}$  fast direction,  $40^{\circ}$  slab strike – **Fig. 7e**), and the  
417 Eastern Aleutians ( $63^{\circ}$  fast direction,  $60^{\circ}$  slab strike – **Fig. 7i**) have peaks at fast directions close  
418 to slab strike. While the misfit peak for Iliamna ( $63^{\circ}$  fast direction) does not correspond to slab  
419 strike, a peak in the bandfit distribution does ( $20^{\circ}$  fast direction,  $25^{\circ}$  slab strike – **Fig. 7a**). The  
420 peaks in upper-layer fast directions match slab strike at Augustine ( $33^{\circ}$  fast direction,  $35^{\circ}$  slab

421 strike – **Fig. 7d**) and Katmai (33° fast direction, 40° slab strike – **Fig. 7f**). Even in cases where the  
422 peak of the misfit distribution does not perfectly match slab strike, the two tend to be close in  
423 orientation. Because of this match, fast directions in both the upper and lower layers can be  
424 generalized as being either parallel or oblique to slab strike.

425 It is common in shear wave splitting studies in subduction zones to refer to fast directions  
426 relative to the orientation of the trench. Our modeling does not utilize trench orientation but rather  
427 slab strike. We show in **Supplemental Table 1** that for all modeled regions the two are within 25°  
428 of each other. This should allow us to compare our modeled results to previous studies that utilize  
429 terms such as “trench parallel” or “trench perpendicular” even though we do not expressly rely on  
430 trench orientation.

431 Previous teleseismic splitting studies in the region have generally not modeled multiple  
432 layers of anisotropy, except for Yang et al., (2021) who found that the edge of the Pacific Slab  
433 produced complex, likely toroidal flow. Splitting along the arc of the AASZ has mostly produced  
434 fast directions parallel to the trench (Christensen and Abers, 2010; Hanna and Long, 2012; Lynner,  
435 2021; McPherson et al., 2020; Richards et al., 2021; Venereau et al., 2019), though local deviations  
436 exist. For instance, Lynner (2021) found a transition from trench-parallel to trench-perpendicular  
437 splits near the boundary between the Semidi segment and the Shumagin Gap. Teleseismic splitting  
438 studies have reported much more complexity in the northeast of the subduction zone near the edge  
439 of the slab (e.g., McPherson et al., 2020; Perttu et al., 2014; Richards et al., 2021). Where the  
440 mantle wedge is relatively thin, fast directions have largely been linked to subslab asthenospheric  
441 flow, both in cases where that flow is trench parallel (Lynner, 2021; McPherson et al., 2020) and  
442 where it is trench-perpendicular (Christensen and Abers, 2010; Hanna and Long, 2012; Perttu et  
443 al., 2014). Because teleseismic splitting has no depth constraints, we cannot directly compare

444 previous results to our robust multilayer models. However, it is a useful confirmation of our own  
445 modeling that previous studies suggest anisotropy at various depths in the AASZ is roughly trench  
446 parallel.

447 We can rely on shear wave splitting from other phases for information on specific depths.  
448 We use the source-side splits of both Lynner and Long (2014) and Walpole et al. (2017) to constrain  
449 subslab anisotropy. Lynner and Long (2014) reported mostly trench-perpendicular source-side  
450 splits throughout the AASZ. However, they do find more complexity moving further east. Walpole  
451 et al. (2017) instead report mostly trench-parallel source-side splits, though they note this may be  
452 due to slight differences in methodology and data coverage. There are also different reference  
453 frames used for analysis, with Walpole et al. (2017) using a slab reference frame and Lynner and  
454 Long (2014) using a receiver-side anisotropy reference frame.

455 Mantle wedge anisotropy can be inferred through local-S splitting (e.g., Long and Wirth,  
456 2013). Previous local-S splitting studies in the Alaskan Peninsula and Cook Inlet have reported  
457 trench-parallel fast directions in the forearc, and trench-perpendicular fast directions in the backarc  
458 (Karlopska et al., 2020; Richards et al., 2021). Augustine and Iliamna straddle the region between  
459 fore- and backarc, and both have a peak in upper-layer fast directions occurring close to slab strike  
460 (between 15° and 40° for Augustine, and between 30° and 45° for Iliamna – **Fig. 7b,d**). Katmai  
461 (on the Alaskan peninsula) also has an upper layer fast direction that matches slab strike (around  
462 30°, **Fig. 7f**). Karlopska et al. (2020) report a mix of trench oblique and parallel splits here, which  
463 somewhat contradicts our own results. Lynner et al. (2024) also report fast directions in Katmai  
464 that are trench oblique (**Fig. 7f**). Further to the southwest, Yang et al. (1995) found roughly trench  
465 parallel fast directions at the Shumagin Gap. Where the mantle wedge is thicker, there is likely a  
466 contribution to teleseismic splitting as well (Christensen and Abers, 2010; Hanna and Long, 2012;

467 Richards et al., 2021; Yang et al., 2021). While teleseismic and local S-waves sample the same  
468 anisotropic structure, differences in frequency content and incidence angle make a direct  
469 comparison difficult. However, they still provide an essential constraint on anisotropy in the mantle  
470 wedge.

471 For the Eastern Aleutians, the source-side splitting from neither study (Lynner and Long,  
472 2014; Walpole et al., 2017) matches the robust modeled lower-layer fast directions (**Fig. 7i**).  
473 Iliamna and Augustine do have some overlap with the source-side splitting results, but this overlap  
474 does not occur at the peaks (**Fig. 7a,c**). Both source-side splitting studies agree with a secondary  
475 peak in lower-layer fast directions for Katmai around  $-40^\circ$  (**Fig. 7e**). The source-side splitting of  
476 Walpole et al. (2017) is close to the peak at Okmok (between  $15^\circ$  and  $30^\circ$  – **Fig. 7g**), whereas there  
477 is no overlap for the source-side splits of Lynner and Long (2014). Some caveats apply to our  
478 comparison between robust modeled lower-layer fast directions and source-side splitting. Events  
479 used to analyze the AASZ from Walpole et al. (2017) come from a limited range of backazimuths  
480 and epicentral distances. Lynner and Long (2014) note that caution should be used for their source-  
481 side splits in the Alaskan portion of the AASZ because some events may have long paths through  
482 the slab. Additionally, we calculated an average fast direction for source-side splits from both  
483 studies since we are modeling results over a broader region. This may lead to discrepancies  
484 between our models and the source-side splits.

485 We compare our robust modeling solutions for upper-layer fast directions to local-S splits  
486 from Lynner et al. (2024). Here we see the inverse of source-side splits. Iliamna (**Fig. 7b**), the  
487 Eastern Aleutians (**Fig. 7j**), and Okmok (**Fig. 7h**) have some upper-layer models that match local-  
488 S splitting. Iliamna and the Eastern Aleutians show good agreement between the peak in the  
489 histogram and local-S splitting (around  $48^\circ$  and  $35^\circ$  respectively). Augustine and Katmai show

490 disagreement between robust modeled upper-layer fast directions and local-S splitting. As with  
491 source-side splits, we averaged the local-S splits: this could skew the fast directions if there are  
492 several local splits with large differences from others.

493 In addition to some agreement with subslab and local-S splitting, the lower and upper layers  
494 of our robust models agree with anisotropic tomography studies of the region. Subslab anisotropy  
495 in the AASZ has widely been reported as trench parallel (e.g., Liu et al., 2022; You and Zhao,  
496 2012), though there are reports of trench-perpendicular orientations (Gou et al., 2019). Mantle  
497 wedge anisotropy is more varied, with You and Zhao (2012) finding trench-parallel anisotropy and  
498 Gou et al. (2019) finding trench-perpendicular anisotropy. A study using Pn phases (which sample  
499 the uppermost mantle) also found that fast directions were broadly trench parallel (He and Lü,  
500 2021). These studies have different sensitivities than teleseismic shear wave splitting, so it is  
501 encouraging that they reinforce our robust models.

502 The bulk of the evidence, including previous splitting of different phases, anisotropic  
503 tomography, and our robust multilayer models suggests that fast directions in both the subslab and  
504 the mantle wedge are either parallel or oblique to the strike of the slab, and therefore subparallel  
505 to the trench orientation (**Fig. 7**). Subslab fast directions for Katmai, the Eastern Aleutians are both  
506 roughly parallel to the slab strike. For Iliamna and Augustine, they are oblique to slab strike. In the  
507 mantle wedge, fast directions for Augustine, and Katmai are parallel to slab strike, and are oblique  
508 for Iliamna and the Eastern Aleutians. Only in the case of mantle wedge fast directions for Okmok  
509 do we see anything close to orientations perpendicular to slab strike. This suggests that mantle  
510 flow in the AASZ is along the strike of the slab, possibly related to the toroidal flow induced by  
511 the edge of the slab to the northeast (e.g., Jadamec and Billen, 2012). A tectonic interpretation of  
512 our results is shown in **Fig. 8**.

513

514 *4.3 Best Practices for Layered Anisotropy Modeling*

515 An interesting result of our modeling efforts is that there is oftentimes a mismatch between  
516 the single “best-fitting” modeled fast direction, and the largest cluster of fast directions in the  
517 robust multilayer models (**Fig. 7** and **Supplemental Figs. S7-10**). Previous studies have shown  
518 that modeling multiple layers of anisotropy yields highly nonunique solutions (Latifi et al., 2018;  
519 Rümpker et al., 2022). Only examining the “best-fitting” model may therefore be misleading.  
520 Importantly, we are only showing those models that are statistically better than a single-layer  
521 solution and statistically indistinguishable from the model with the lowest misfit (i.e., the “best-  
522 fitting” model). Many other studies that examine multilayered anisotropy from shear wave splitting  
523 rely on the best-fitting model, which may bias their interpretation.

524 One way to reconcile the difference between the lowest-misfit model and all the robust  
525 multilayer models is to examine the bandfit misfit as well. As noted in **Section 2.2**, this method  
526 compares the calculated model to the error bounds of individual measurements and takes a value  
527 of 0 when the model is within bounds and a value of 1 otherwise. Bandfit is shown in **Figs. 5-7**,  
528 and all models with a bandfit less than or equal to the lowest bandfit plus four are shown. The  
529 bandfit distribution generally agrees with the misfit distribution, and both tend to have peaks at the  
530 same fast direction values (**Fig. 7**). In cases where there is a slightly wider distribution in fast  
531 directions, such as the lower layer at Iliamna, the bandfit can help to provide better constraints.  
532 Even in cases where there is general agreement among the robust models, the bandfit can help to  
533 narrow the range of possibilities.

534 Our layered anisotropy modeling leads us to suggest a pathway to yield the most robust  
535 results. First, adequate backazimuthal coverage is required. Because apparent splitting parameters

536 arising from multilayer anisotropy display 90° periodicity, more than 90° of coverage is  
537 recommended. While this may be possible for individual long-running stations, it is generally not  
538 possible to achieve this through one station alone. Rather, by grouping several stations in  
539 proximity, backazimuthal coverage can be increased. The ideal spacing for these groups is largely  
540 dependent on the region being modeled. For instance, in subduction zones there may be clear  
541 changes in subduction parameters that suggest a specific grouping.

542 Second, basic statistical analysis is required. In its simplest form, this would compare the  
543 best-fitting model against a single-layer case to ensure that there is an improvement in the fit of  
544 the data. There are several methods to achieve this. In this study, we utilize an F-test for nested  
545 models (Mendenhall and Sincich, 2016). Others have used an adjusted R-squared value (e.g.,  
546 Walker et al., 2005). However, as shown in our modeling, comparing the best-fitting model alone  
547 against the single-layer case may be misleading. The use of the nested F-test allows for the  
548 calculation of the entire suite of models that is statistically better than the best-fitting single-layer  
549 model. Third, the calculation of an additional metric to determine how well the data is fit by the  
550 models is advantageous. Here we use the bandfit method implemented by Eakin and Long (2013).  
551 Comparing the suite of models statistically better than the single-layer case and the suite of models  
552 within some value of the lowest bandfit should show which parameters are the ideal solution.

553 Finally, tectonic constraints should be considered when constructing the model. In our  
554 study, we constrain the dipping layer using information from Slab2 (Hayes et al., 2018) and  
555 paleomagnetic data (Maus et al., 2009). Rümpker et al., (2022) note that by constraining one layer  
556 of a grid-search, the solution for the second layer becomes more unique. By using tectonic  
557 information to produce an accurate model, it should be possible to yield robust results. For  
558 subduction zones, using an HDH setup is ideal given the presence of the slab. Constraining the

559 dipping layer is the easiest, as there is reliable information on the strike and dip from Slab2 (Hayes  
560 et al., 2018) and grid-searching for those additional parameters is computationally expensive.

561

## 562 **5. Conclusion**

563 Shear wave splitting in the eastern portion of the Alaska-Aleutians subduction zone from our  
564 analysis shows signs indicative of multilayered anisotropy. In this study, we model these multiple  
565 layers for six subregions. Five of these subregions have a suite of models that are statistically better  
566 than a single-layer case. While we test two and three horizontal layer model setups, we ultimately  
567 favor a model with horizontal lower and upper layers and a dipping middle – the subslab, slab, and  
568 mantle wedge. We find that the dipping slab layer is best approximated with an orientation parallel  
569 to paleospreading, while fast directions for the subslab and mantle are best approximated as  
570 parallel or oblique to slab strike. Our study argues for the necessity of considering tectonic  
571 constraints in shear wave splitting modeling, and the importance of analyzing the statistical  
572 significance of models for a robust result.

573

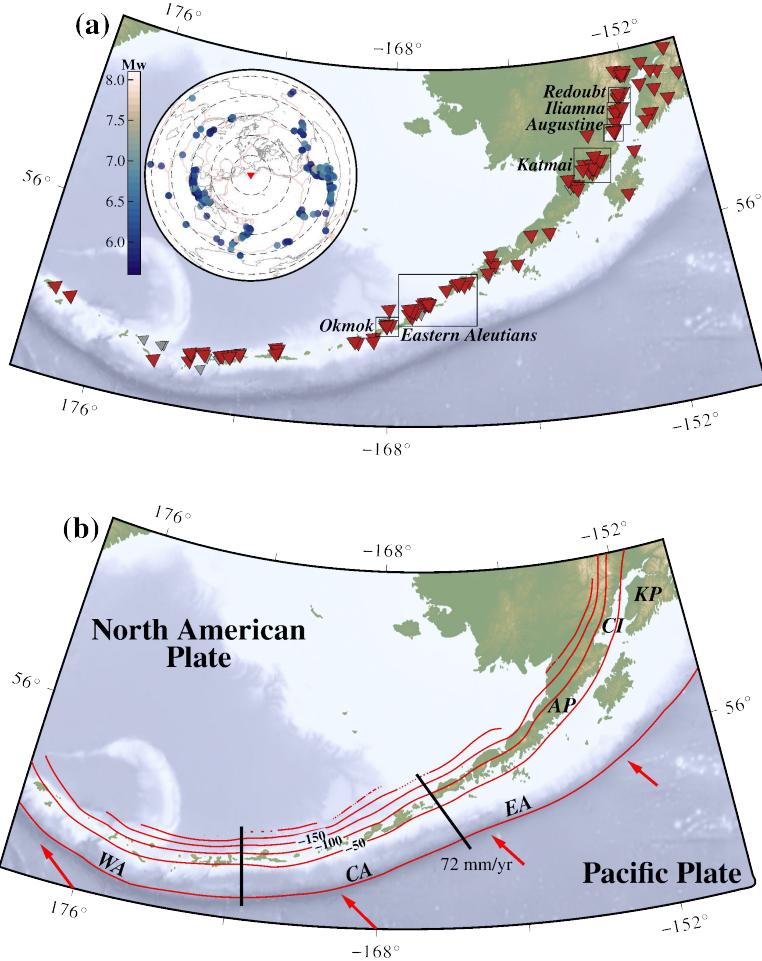
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577 Porritt, David Schlaphorst, and one anonymous reviewer for their constructive feedback. We also  
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579

## 580 **Data Availability Statement**

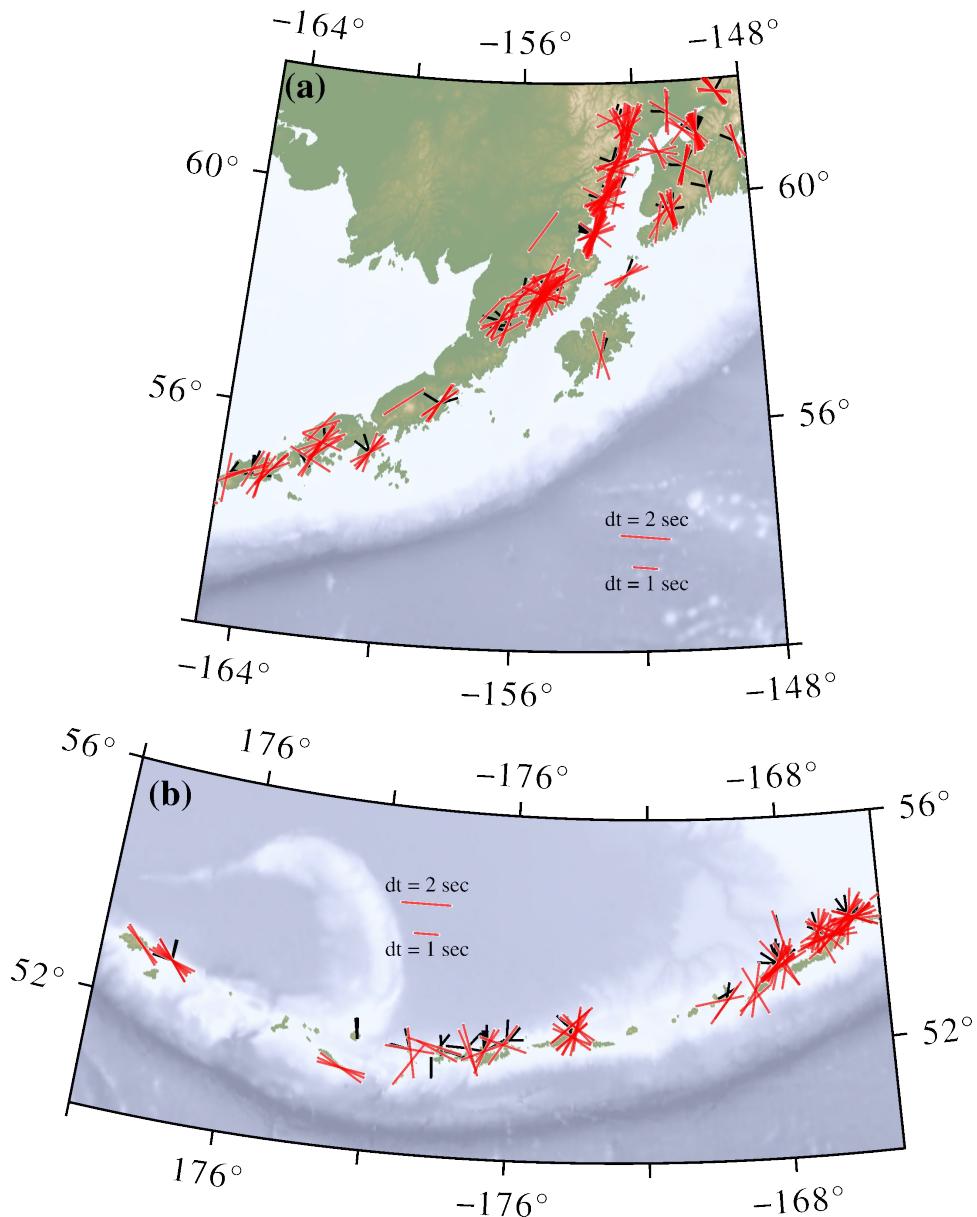
581 All seismic data are freely, publicly available through the Data Management Center of the  
582 EarthScope Consortium. We provide DOIs for all networks in the **Supplemental Material**.  
583 Individual splitting and null measurements are provided in **Table S2**.



584

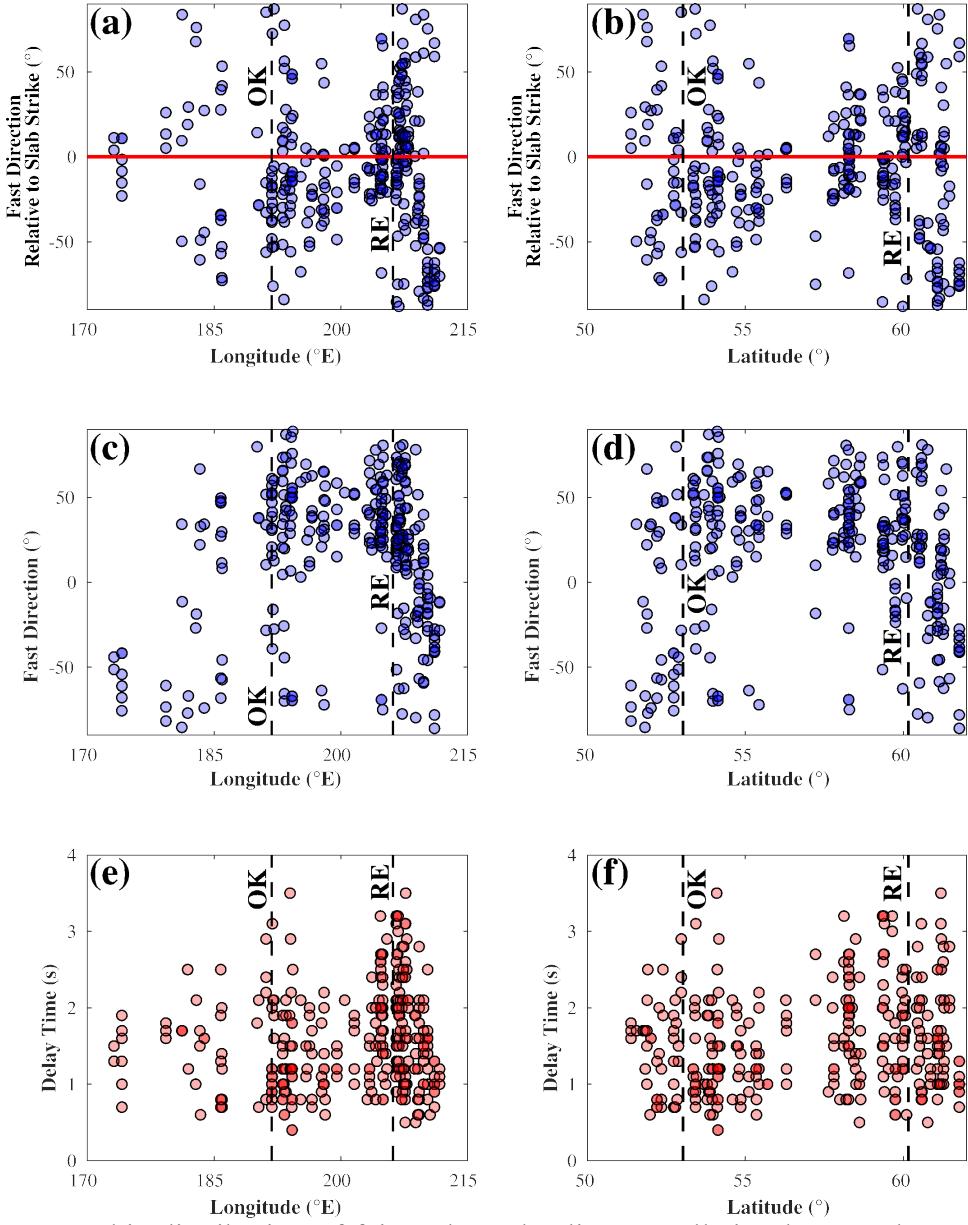
585 **Figure 1:** Station and tectonic information. **(a)** All stations used in this study (inverted triangles).  
 586 Red triangles are those stations with results, while gray triangles were those with no results. Inset  
 587 displays earthquake locations for calculated splits. Boxes show regions modeled – **Figs. 4 and 7**  
 588 show these regions in more detail. **(b)** Tectonic map with slab contours (red lines) from Slab2  
 589 (Hayes et al., 2018) and motion of the Pacific Plate from a hotspot reference frame (Gripp and  
 590 Gordon, 2002). Solid black lines delineate the three regions of the Aleutians (Western, Central,  
 591 and Eastern). AP – Alaskan Peninsula; CA – Central Aleutians; CI – Cook Inlet; EA – Eastern  
 592 Aleutians; KP – Kenai Peninsula; WA – Western Aleutians.

593

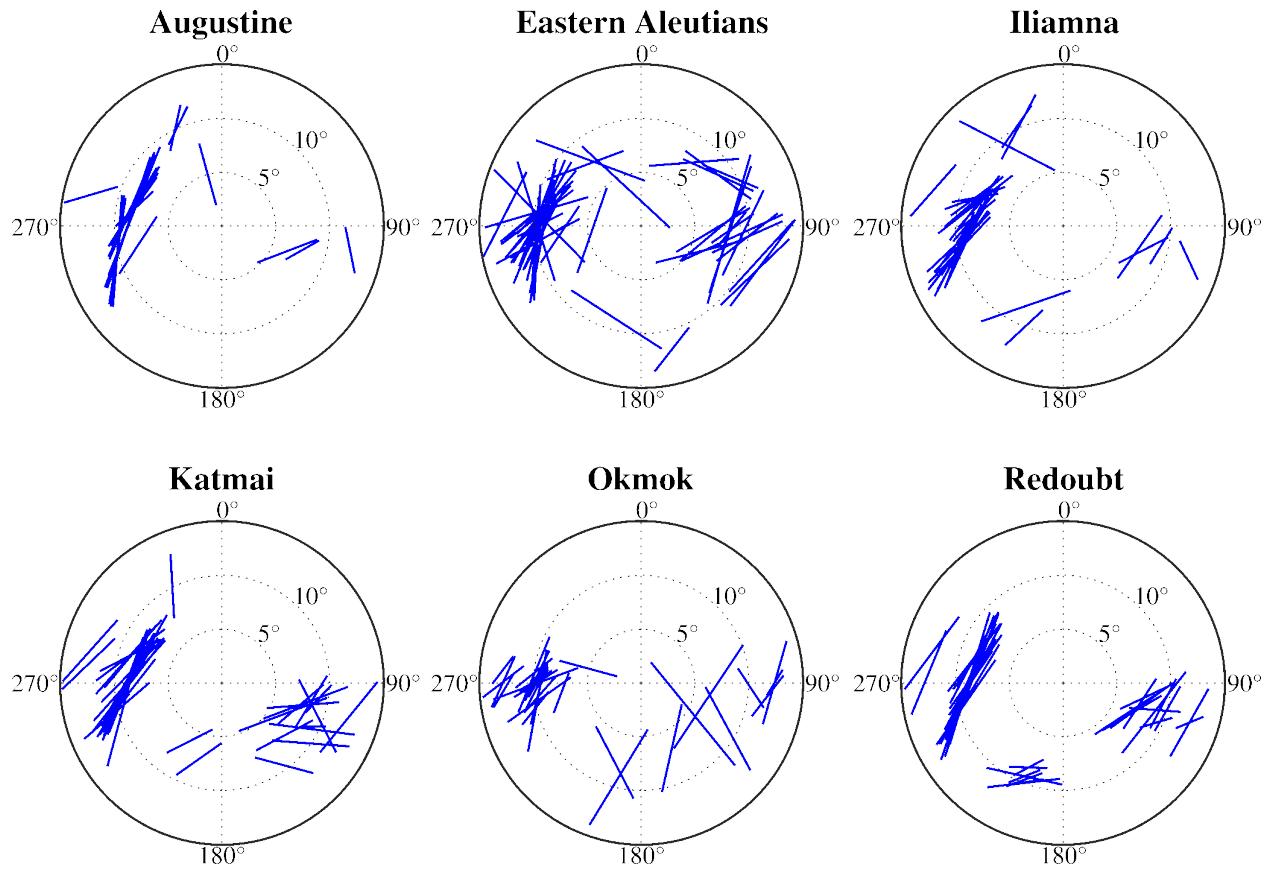


594

595 **Figure 2:** All fair and good splits (in red), plotted at station locations. The orientation of the red  
 596 bars shows fast direction, while the length shows delay time. Nulls are shown in black with the  
 597 orientation showing fast direction; length is set to be the same for all nulls. **(a)** Splits for the Eastern  
 598 Aleutians and Alaskan portion of the AASZ. **(b)** Splits for the Western and Central Aleutians.



599 **Figure 3:** Geographic distribution of fair and good splits. For all six plots, we have marked the  
 600 location of Mount Okmok (OK) and Mount Redoubt (RE) with a dashed line to help orient readers.  
 601 **(a-b)** Fast direction relative to the orientation of the trench from Slab2 (Hayes et al., 2018) plotted  
 602 against longitude and latitude. A value of  $0^\circ$  indicates trench parallel. **(c-d)** Fast direction plotted  
 603 against longitude and latitude. **(e-f)** Delay time plotted against longitude and latitude.



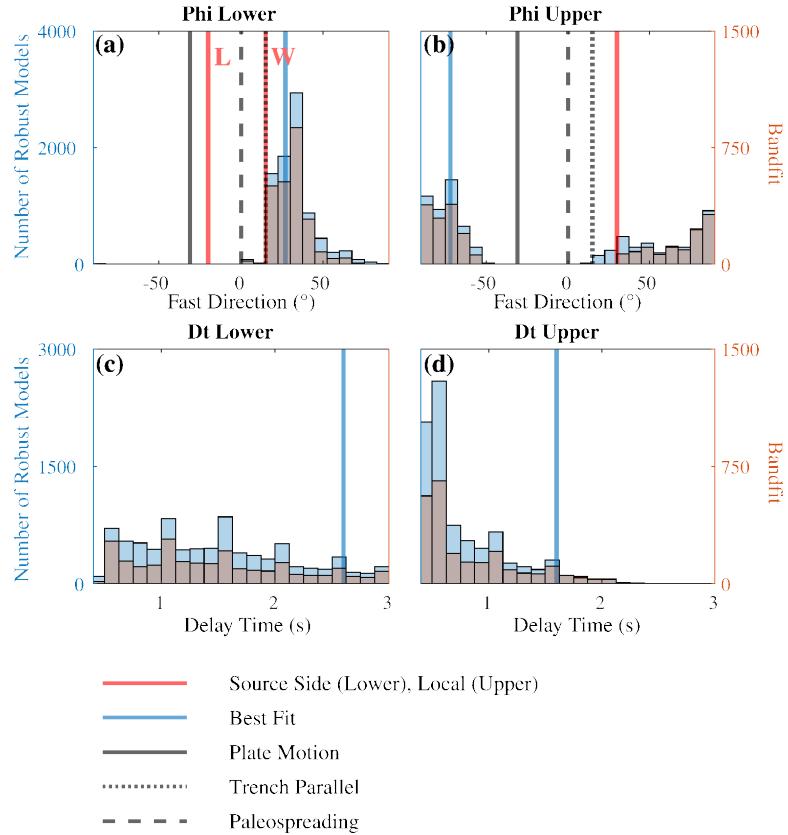
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605 **Figure 4:** Stereoplots of all splits used in modeling from the regions outlined in **Fig. 1**.

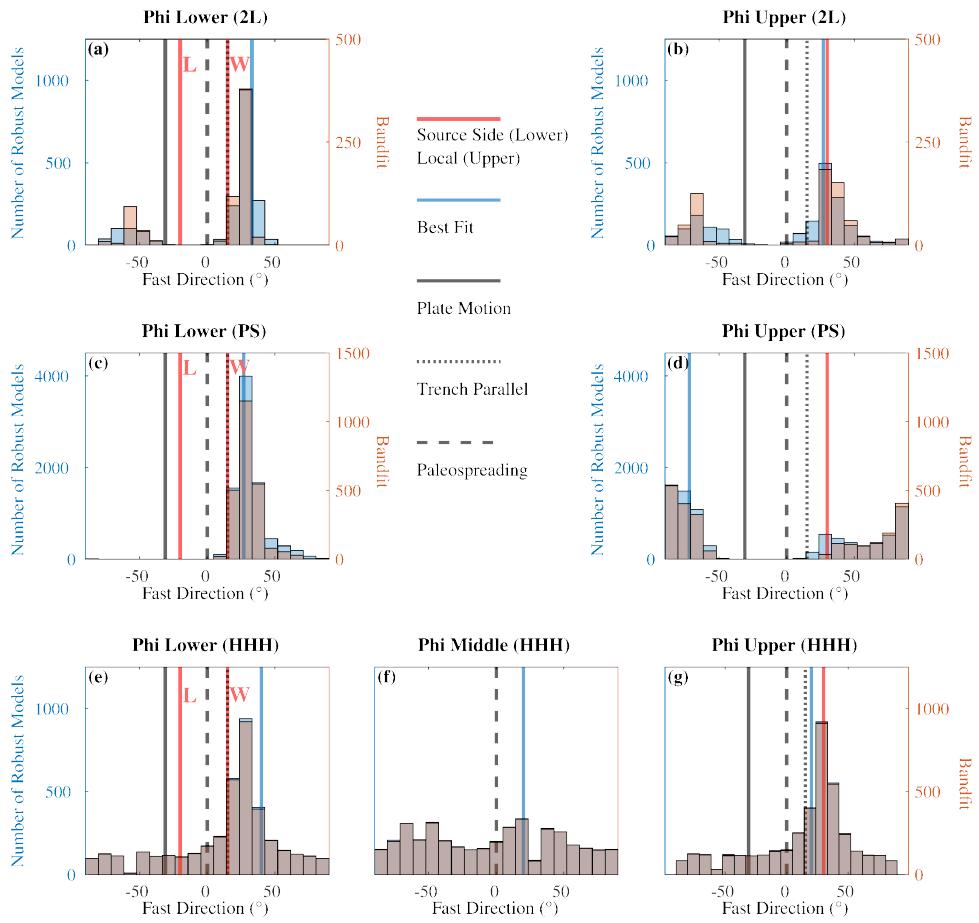
606 Backazimuth of each split is shown along the circumference of the plot (0° to 360°) while

607 inclination angle of each split is shown along the radius (0° to 15°).

608



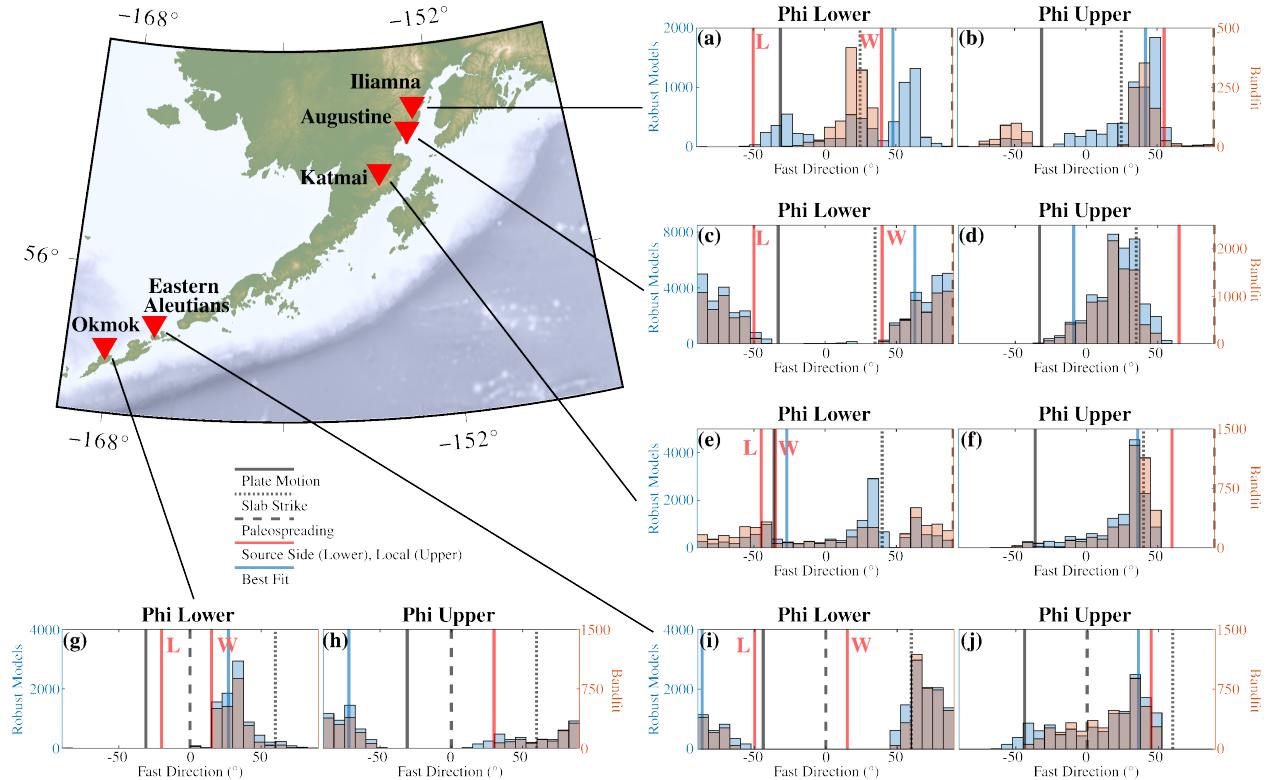
609 **Figure 5:** Suite of models at Okmok that are statistically indistinguishable from the model with  
 610 the lowest misfit, and statistically better than a single-layer case (e.g., robust multilayer models  
 611 blue bars) for our preferred configuration of three layers with a dipping middle layer oriented  
 612 parallel to paleospreading. Bandfit shows the set of models within four of the lowest bandfit model  
 613 (orange bars). **(a-b)** Lower layer and upper layer fast direction suites (Phi Lower and Phi Upper,  
 614 respectively). Source-side splits are from Lynner and Long (2014) and Walpole et al., (2017).  
 615 These are marked with an “L” and “W”, respectively. Local-S splits are from Lynner et al., (2024),  
 616 plate motion is from Gripp and Gordon (2002), slab strike orientation is from Slab2 (Hayes et al.,  
 617 2018), and paleospreading direction is estimated from paleomagnetic data in Maus et al. (2009).  
 618 **(c-d)** Lower layer and upper layer delay time suites (Dt Lower and Dt Upper, respectively).



619

620 **Figure 6:** Comparison of fast direction (phi) model suites for **(a-b)** the two-layer (2L), **(c-d)** HDH  
 621 with middle layer parallel to paleospreading (PS), and **(e-g)** three-layer cases (HHH) at Okmok.  
 622 Robust multilayer models are shown in blue. Bandfit shows the set of models within four of the  
 623 lowest bandfit model (shown in orange). Source-side splits are from Lynner and Long (2014) and  
 624 Walpole et al., (2017). These are marked with an “L” and “W”, respectively. Local-S splits are  
 625 from Lynner et al., (2024), plate motion is from Gripp and Gordon (2002), slab strike orientation  
 626 is from Slab2 (Hayes et al., 2018), and paleospreading direction is estimated from paleomagnetic  
 627 data in Maus et al. (2009).

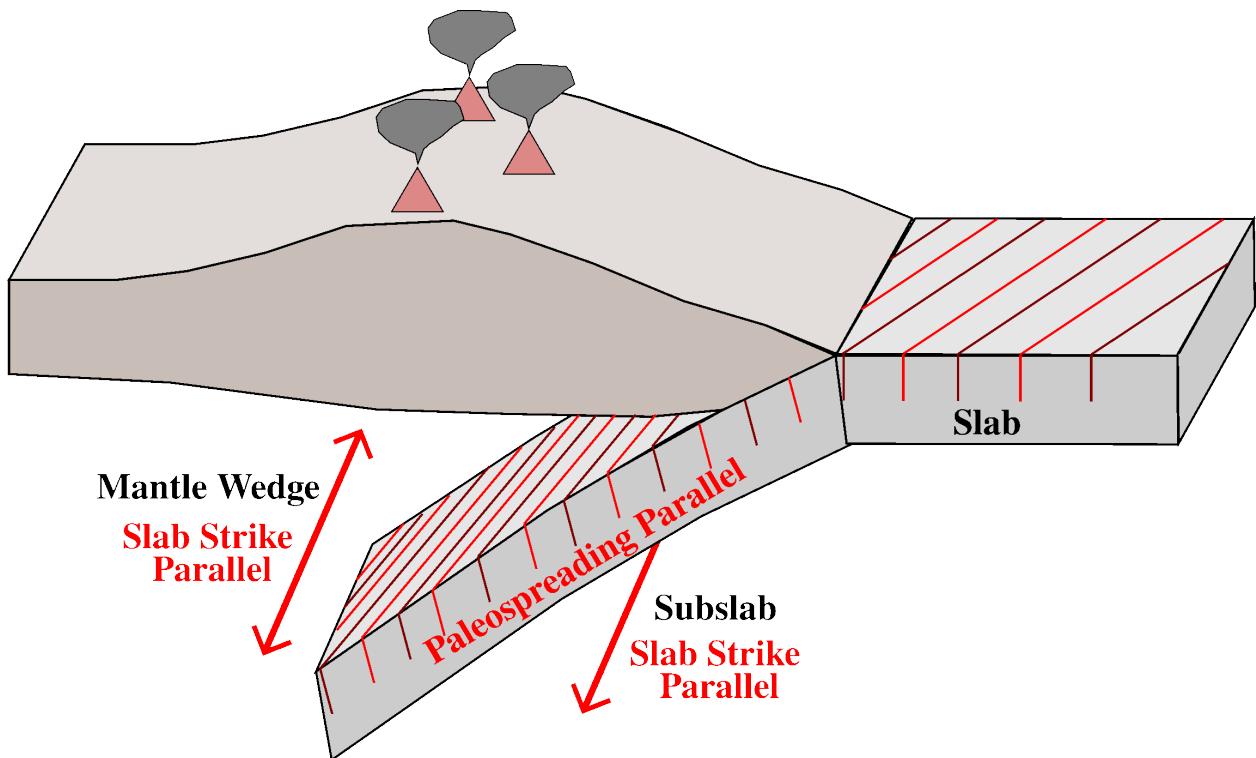
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629

630 **Figure 7:** Preferred configuration (HDH with middle dipping layer oriented parallel to  
 631 paleospreading) robust models for all regions, shown in blue. Only fast directions (phi) are shown  
 632 (see main text for further details). Bandfit shows the set of models within four of the lowest bandfit  
 633 model (shown in orange). Source-side splits are from Lynner and Long (2014) and Walpole et al.,  
 634 (2017). These are marked with an “L” and “W”, respectively. Local-S splits are from Lynner et al.,  
 635 (2024), plate motion is from Gripp and Gordon (2002), slab strike orientation is from Slab2 (Hayes  
 636 et al., 2018), and paleospreading direction is estimated from paleomagnetic data in Maus et al.  
 637 (2009).

638



639

640 **Figure 8:** A cartoon schematic of our preferred interpretation of anisotropy beneath Augustine, the  
 641 Eastern Aleutians, Iliamna, Katmai, and Okmok. Anisotropy is shown in red. For the mantle wedge  
 642 and the subslab, our preferred model is anisotropy oriented parallel to slab strike. In the slab itself,  
 643 our modeling and previous studies suggests anisotropy oriented parallel to paleospreading.

644 **Table 1:** Peak of fast direction histogram for suite of models that are statistically indistinguishable  
 645 from the lowest misfit model, and statistically better than the single-layer case. Histograms for the  
 646 paleospreading case can be seen in **Figure 7**, and all others can be seen in the **Supplementary**  
 647 **Material**. Phi Lower – fast direction in the lowest layer of the model; Phi Upper – fast direction  
 648 in the topmost layer of the model; 2L – two layer case; PS – paleospreading case; HHH – three  
 649 layer case.  
 650

	2L		PS		HHH	
	<i>Phi Lower</i>	<i>Phi Upper</i>	<i>Phi Lower</i>	<i>Phi Upper</i>	<i>Phi Lower</i>	<i>Phi Upper</i>
<b>Augustine</b>	83	30	84	33	71	23
<b>EAL</b>	57	30	63	33	62	33
<b>Iliamna</b>	57	36	63	48	52	42
<b>Katmai</b>	30	30	33	33	23	33
<b>Okmok</b>	23	30	33	-72	23	30

651

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