

UNIVERSALITY AND SHARP MATRIX CONCENTRATION INEQUALITIES

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ABSTRACT. We show that, under mild assumptions, the spectrum of a sum of independent random matrices is close to that of the Gaussian random matrix whose entries have the same mean and covariance. This nonasymptotic universality principle yields sharp matrix concentration inequalities for general sums of independent random matrices when combined with the Gaussian theory of Bandeira, Boedihardjo, and Van Handel. A key feature of the resulting theory is that it is applicable to a broad class of random matrix models that may have highly nonhomogeneous and dependent entries, which can be far outside the mean-field situation considered in classical random matrix theory. We illustrate the theory in applications to random graphs, matrix concentration inequalities for smallest singular values, sample covariance matrices, strong asymptotic freeness, and phase transitions in spiked models.

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1. INTRODUCTION

1.1. Matrix concentration inequalities. Let Z_1, \dots, Z_n be independent $d \times d$ random matrices with zero mean, and let

$$X := \sum_{i=1}^n Z_i. \quad (1.1)$$

Random matrices of this form arise in numerous applications. As guiding examples, the reader may keep in mind the following very special cases:

- Any random matrix X with centered jointly Gaussian entries may be represented in this form by setting $X = \sum_{i=1}^n g_i A_i$ for suitable deterministic matrices A_i , where g_1, \dots, g_n are i.i.d. standard Gaussian variables.
- Any random matrix X with centered independent entries may be represented in this form as $X = \sum_{i,j=1}^d \eta_{ij} e_i e_j^*$, where η_{ij} are independent centered random variables and e_1, \dots, e_d denotes the standard basis of \mathbb{C}^d .

Many other kinds of summands Z_i arise naturally in a diverse range of pure and applied mathematical problems; cf. [77] and the references therein, and the applications that are discussed in sections 1.3 and 3 below.

Already in the special cases highlighted above, it is clear that random matrices of the form (1.1) can possess a nearly arbitrary structure: the model allows for essentially any pattern of entry variances, dependencies, and distributions. Such general models are outside the reach of classical random matrix theory, which is primarily concerned with the asymptotic behavior of highly symmetric models such as matrices with i.i.d. entries or invariant ensembles [5, 75].

Rather surprisingly, one of the most fruitful ideas that has been developed in the present setting is that one can treat the model (1.1) essentially as though it is a sum of independent *scalar* random variables. This approach results in a somewhat crude

but extremely versatile family of nonasymptotic *matrix concentration inequalities*. Two important examples of such inequalities are:¹

- For a self-adjoint random matrix X with centered jointly Gaussian entries, the noncommutative Khintchine inequality of Lust-Piquard and Pisier [66, §9.8] yields

$$\mathbf{E}\|X\| \lesssim \|\mathbf{E}X^2\|^{\frac{1}{2}}\sqrt{\log d}. \quad (1.2)$$

- For a self-adjoint random matrix X of the form (1.1) with $\|Z_i\| \leq R$ a.s., the matrix Bernstein inequality of Oliveira and Tropp [62, 77] yields

$$\mathbf{E}\|X\| \lesssim \|\mathbf{E}X^2\|^{\frac{1}{2}}\sqrt{\log d} + R\log d. \quad (1.3)$$

To understand the significance of these inequalities, note that $(\mathbf{E}\|X\|^2)^{\frac{1}{2}} \geq \|\mathbf{E}X^2\|^{\frac{1}{2}}$ by Jensen's inequality. The above bounds can therefore capture the norm of very general random matrices up to a logarithmic dimensional factor. The dimensional factor proves to be suboptimal, however, even for the simplest random matrix models (such as those with i.i.d. entries).

The inefficiency of classical matrix concentration inequalities stems from the fact that by mimicking the proofs of scalar concentration inequalities, these bounds ignore noncommutativity of the summands Z_i in (1.1). In the setting of Gaussian random matrices, a significant step toward addressing this inefficiency was recently made by Bandeira, Boedihardjo, and the second author [9], who developed a new class of *sharp* matrix concentration inequalities that capture noncommutativity. For example, if X is a self-adjoint random matrix with centered jointly Gaussian entries, [9, Corollary 2.2] yields

$$\mathbf{E}\|X\| \leq \|X_{\text{free}}\| + C\|\mathbf{E}X^2\|^{\frac{1}{4}}\|\text{Cov}(X)\|^{\frac{1}{4}}(\log d)^{\frac{3}{4}} \quad (1.4)$$

for a universal constant C . Here $\text{Cov}(X)$ denotes the $d^2 \times d^2$ covariance matrix of the entries of X , while X_{free} is a certain noncommutative model of X that arises from free probability theory. As $\|X_{\text{free}}\| \leq 2\|\mathbf{E}X^2\|^{\frac{1}{2}}$, the inequality (1.4) shows that the dimensional factor in (1.2) can be removed as soon as $\|\text{Cov}(X)\| \ll (\log d)^{-3}\|\mathbf{E}X^2\|$, which is a mild assumption in many applications. The theory of [9] yields much more, however: both the support and the empirical distribution of the spectrum of X is close to that of X_{free} , and similar results hold for polynomials of such matrices. Such results open the door to developing a nonasymptotic random matrix theory for nearly arbitrarily structured random matrices.

In view of these developments, it is of considerable interest to extend the Gaussian theory of [9] to the much more general setting (1.1) of sums of independent random matrices. For classical matrix concentration inequalities, this extension has been achieved in two distinct ways: one may either derive both (1.2) and (1.3) by a common method of proof [62, 77], or deduce (1.3) from (1.2) by a symmetrization argument as in [71, 78]. Unfortunately, neither of these approaches appears to give rise to a satisfactory extension of the theory of [9]. The methods of [9] rely heavily on Gaussian analysis, and it is unclear how to adapt them to non-Gaussian situations. On the other hand, sharp inequalities are fundamentally inaccessible by symmetrization, as is explained in [9, §8.2.2].

¹Here and in the sequel, $\|M\|$ denotes the operator norm (i.e., the largest singular value) of a matrix M , and $a \lesssim b$ denotes $a \leq Cb$ for a universal constant C .

1.2. Universality. In this paper, we take an entirely different viewpoint on such problems. To motivate the form of our main results, let us note that if the last term in the inequality (1.3) is negligible, then (1.3) has exactly the same form as the Gaussian inequality (1.2). The main theme of this paper is that this phenomenon has nothing to do with matrix concentration inequalities themselves, but is rather a consequence of a general *universality principle*:

If $\max_{1 \leq i \leq n} \|Z_i\| \ll \|\mathbf{E} X^2\|^{\frac{1}{2}} (\log d)^{-\beta}$ (for an appropriate $\beta > 0$), then the spectrum of a self-adjoint random matrix $X = \sum_{i=1}^n Z_i$ as in (1.1) nearly coincides with that of the Gaussian random matrix G whose entries have the same mean and covariance as X .

This principle directly reduces the study of the spectrum of sums of independent random matrices to that of Gaussian matrices, regardless of what theory is applied to the Gaussian matrices. In particular, it simultaneously explains the phenomenon behind (1.2)–(1.3), and enables us to fully extend the sharp matrix concentration theory of [9] to the model (1.1).

The universality principle was stated above in an informal manner. A detailed formulation of our results will be given in section 2 below. In particular, we will obtain nonasymptotic inequalities that establish closeness both of the spectral distributions of X and G , and of the spectra themselves in Hausdorff distance. (These results apply in a more general setting than (1.1), where the random matrices may have an arbitrary mean.) We further formulate resulting sharp matrix concentration inequalities that arise from the theory of [9].

Universality phenomena have been widely investigated in classical random matrix theory. As in many previous works on this topic, the starting point for our analysis is the cumulant expansion of Barbour [14] and Lytova and Pastur [55], which has been primarily applied to classical random matrix models with independent entries. A rather complicated extension of the cumulant expansion to dependent models appears in [41], where it is used to study random matrices whose entries exhibit decay of correlations. A straightforward extension of Barbour’s method to the dependent setting will be formulated in section 4; such an extension does not in itself require any new idea as compared to [14, 55].

The core contribution of this paper lies in the mechanism that gives rise to universality. To the best of our knowledge, prior universality results are essentially limited to the “classical random matrix regime” where the entry variances are of order $d^{-\frac{1}{2}}$ and the entries are independent or nearly independent (in the sense that they exhibit decay of correlations). In other words, these results rely on restrictive mean-field assumptions. In contrast, the independent sum models (1.1) of the present paper can lie far outside the mean-field regime: they can be highly nonhomogeneous, sparse, and exhibit strong dependence among the entries, and are not assumed to possess any special structure or symmetries. The properties of these models therefore cannot be explained by previous universality results that rely heavily on the special structure of the underlying models.

The central idea of this paper is that universality arises in these models in a different manner through an operator-theoretic mechanism: a key ingredient of our approach are high-order trace inequalities (section 5) that enable us to control the contributions of the terms in the cumulant expansion without imposing any correlation decay or mean-field assumptions. This operator-theoretic viewpoint on

universality, together with a number of other new tools (such as nonstandard concentration inequalities for spectral statistics), provides access to many applications that are not captured by classical random matrix models.

Remark 1.1. Much of the literature on universality of classical random matrix models has focused on establishing universality at or near the scale of the fluctuations of the eigenvalues; see, e.g., [41] and the references therein. It should be emphasized that the results of this paper do not provide any information at the scale of the fluctuations, but rather only at scales at which the spectral statistics exhibit concentration. At the level of generality considered in this paper, the scale of the fluctuations is strongly model-dependent (see, e.g., [73, 28]), so that it is unclear how a meaningful result for generally structured models could be formulated. Even a plausible conjecture in this direction would be of considerable interest.

1.3. Applications. To illustrate the main results of this paper, we will develop several applications that we briefly describe here (see section 3 for detailed statements). Beyond their independent interest, we emphasize that the completely general universality phenomenon described by our main results is the common mechanism underlying all these rather diverse applications.

Random graphs and expanders. The expansion properties of random regular graphs have been extensively studied for graphs of bounded degree k . In particular, such graphs are nearly Ramanujan, i.e., they have the smallest possible (by [61]) second eigenvalue $\lambda_2 = (1+o(1))2\sqrt{k-1}$ to leading order [43]. While the strong expansion properties of such graphs are expected to persist when the degree is allowed to diverge, this situation remains much more poorly understood; see, e.g., the survey [84]. The universality principles of this paper enable us to address this question both in classical and in new situations:

- The permutation model of random regular graphs with n vertices of degree k is nearly Ramanujan when $k \gg (\log n)^4$, addressing a well known question [15, §1.4]. To date, the best known bound in this setting was $\lambda_2 = O(\sqrt{k})$ [44, 39, 36].
- A classical result of Alon and Roichman [2] states that if Γ is any finite group and $k \gg \log |\Gamma|$ generators are chosen uniformly at random, the resulting Cayley graph is an expander. This result cannot be improved for abelian groups. Here we show that under mild assumptions that hold, e.g., for all nonabelian finite simple groups, the Cayley graph defined by choosing $k \gg (\log |\Gamma|)^4$ random generators is nearly Ramanujan. This appears to be the first result of its kind.
- A fundamental result of Bordenave and Collins [20] states that for any fixed base graph H , the new eigenvalues of its random n -lift are bounded as $n \rightarrow \infty$ by the spectral radius of the universal cover of H . Here we show that this conclusion remains valid for any sequence of base graphs H_n whose maximal degrees grow at least polylogarithmically in the number of vertices of their random lifts. Moreover, in this setting we uncover a new phenomenon: when the base graphs are simple, random 2-lifts already achieve the optimal bound.

Matrix concentration inequalities for smallest singular values. By their nature, classical matrix concentration inequalities can only control the largest singular value of nonhomogeneous random matrices. In contrast, the universality principles of this paper apply not only to the largest singular value but also to the entire spectrum.

By combining our results with the Gaussian theory of [9], we are therefore able to obtain sharp matrix concentration inequalities for the smallest singular value of random matrices of the form (1.1) that may be viewed as a nonasymptotic, nonhomogeneous form of the classical Bai-Yin law [7]. Let us emphasize that even if one is interested in suboptimal bounds on the smallest singular value, such information is fundamentally inacceessible by the methods used to prove classical matrix concentration inequalities for general models of the form (1.1).

A direct application yields bounds for the smallest singular value of sparse nonhomogeneous bipartite Erdős-Rényi graphs that are sharp to leading order. To date, the best known bounds [40] were suboptimal for nonhomogeneous graphs.

Sample covariance matrices. Let Y_1, \dots, Y_n be independent, centered random vectors in \mathbb{R}^d . The $d \times d$ random matrix defined by $S := \sum_{i=1}^n Y_i Y_i^*$ is called the (nonhomogeneous) sample covariance matrix. Equivalently, $S = YY^*$, where $Y := \sum_{i=1}^n Y_i e_i^*$ is the $d \times n$ matrix whose columns are Y_1, \dots, Y_n .

A central problem in this setting is to control the deviation of the sample covariance matrix from its mean $\|S - \mathbf{E}S\|$. A curious feature of this problem is that we may express S in terms of a model of the form (1.1) in two different ways: we may either consider S itself as a model of the form (1.1), or we may consider Y as a model of the form (1.1). These two representations give rise to distinct universality principles: roughly speaking, applying our universality principles to S is efficient when n is sufficiently large compared to d , while applying universality to Y is efficient when d is sufficiently large compared to n .

We will illustrate this phenomenon in the setting of nonhomogeneous Gaussian sample covariance matrices with arbitrary covariance matrices of Y_1, \dots, Y_n , for which we obtain nonasymptotic bounds on $\|S - \mathbf{E}S\|$ that are sharp for a wide range of parameters. No sharp bounds appear to be known in the literature at this level of generality. We also discuss non-Gaussian sample covariance matrices, which will be developed further in forthcoming work [63].

Strong asymptotic freeness. A celebrated result of Voiculescu [83] states that the traces of polynomials of independent $N \times N$ Wigner matrices converge as $N \rightarrow \infty$ to the traces of polynomials of certain limiting objects that arise in free probability theory. In an important breakthrough, Haagerup and Thorbjørnsen [47] showed that this convergence holds not only for the trace but also for the norm:

$$\lim_{N \rightarrow \infty} \|p(X_1^N, \dots, X_m^N)\| = \|p(s_1, \dots, s_m)\| \quad \text{a.s.} \quad (1.5)$$

for every noncommutative polynomial p , where X_1^N, \dots, X_m^N are independent $N \times N$ complex Gaussian Wigner matrices and s_1, \dots, s_m is a free semicircular family. This property, called strong asymptotic freeness, is of fundamental importance both to random matrices and in the theory of operator algebras.

Whether (1.5) holds for more general models of random matrices X_i^N is far from clear from the original rather delicate proofs. Previously, the state-of-the-art [4] was that (1.5) holds for matrices with i.i.d. centered entries with unit variance and bounded fourth moment. Very recently, however, the sharp matrix concentration theory of [9] made it possible to establish (1.5) for an extremely general class of Gaussian random matrices, showing that this phenomenon is much more ubiquitous than was previously understood. Our universality principles extend this conclusion

even further to general non-Gaussian random matrices of the form (1.1) under mild assumptions that allow for significant sparsity and dependence.

Phase transitions in spiked models. The behavior of low-rank perturbations of random matrices (so-called “spiked” models) has attracted much attention in pure and applied random matrix theory since the work of Baik, Ben Arous and Péché [8]. The characteristic feature of such models is that they exhibit a phase transition depending on the size of the perturbation: there is a threshold above which one or more isolated eigenvalues detach from the bulk of the spectrum. Most of the literature on this topic is concerned with Wigner matrices or with unitarily invariant models; see, e.g., the survey [27]. The universality principles of this paper enable us to investigate such phenomena in much more general situations, including models that exhibit significant sparsity and dependence. Little appears to be known in this direction: previous work on a special type of low-rank perturbations of sparse random matrices appeared only very recently in [74].

As our primary aim here is to illustrate the main results of this paper, we will focus our attention on sparse and dependent models whose behavior can be reduced by universality to the classical spiked Wigner model. In this setting, we will show how our universality principles enable us to capture the number and locations of the outlier eigenvalues, as well as the overlaps of the associated eigenvectors with those of the low-rank perturbation. However, much more general situations become amenable to analysis in combination with the Gaussian theory of [9], which makes it possible to investigate analogous phase transition phenomena in nonhomogeneous models. The computations involved in the nonhomogenous setting are unrelated to universality, and are treated in detail in [10].

1.4. Organization of this paper. The remainder of this paper is organized as follows. In section 2, we formulate the main results of this paper. Section 3 is devoted to a detailed formulation of the applications described above.

In section 4, we provide a brief self-contained treatment of the multivariate cumulant expansion. Section 5 develops some key tools that are used in the proofs of our main results: high-order trace inequalities that provide the main mechanism for controlling the terms in the cumulant expansion, and certain nonstandard concentration of measure inequalities. The following three sections are devoted to the proofs of our main results. Section 6 proves the universality principles for spectral statistics, while section 7 proves the universality principle for the support of the spectrum. Section 8 is devoted to a truncation argument that extends our main results to models that satisfy minimal moment assumptions. Finally, section 9 is devoted to the proofs of the various applications discussed in section 3.

1.5. Notation. The following notation will be used throughout the paper. We write $[n] := \{1, \dots, n\}$ for $n \in \mathbb{N}$. The algebra of $d \times d$ matrices with values in a $*$ -algebra \mathcal{A} is denoted as $M_d(\mathcal{A})$, and its subspace of self-adjoint matrices is denoted as $M_d(\mathcal{A})_{sa}$. For a matrix or operator X , we denote by $\|X\|$ its operator norm, by $\text{sp}(X)$ its spectrum, and by $|X| := (X^*X)^{\frac{1}{2}}$. For self-adjoint X, Y , we denote by $X \leq Y$ the positive semidefinite order. The identity matrix or operator is denoted as $\mathbf{1}$. For $M \in M_d(\mathbb{C})$, we denote by $\text{Tr } M := \sum_{i=1}^d M_{ii}$ the unnormalized trace and by $\text{tr } M := \frac{1}{d} \text{Tr } M$ the normalized trace. We denote by $W^{k,1}(\mathbb{R})$ the Sobolev space of $f : \mathbb{R} \rightarrow \mathbb{C}$ so that $\|f\|_{W^{k,1}(\mathbb{R})} := \sum_{i=0}^k \int_{-\infty}^{\infty} \left| \frac{d^i}{dx^i} f(x) \right| dx < \infty$. Finally, we use

the convention that when a functional is followed by square brackets, it is applied before any other operations; for example, $\mathbf{E}[X]^\alpha := (\mathbf{E}X)^\alpha$ and $\text{tr}[M]^\alpha := (\text{tr } M)^\alpha$.

2. MAIN RESULTS

2.1. Random matrix models and matrix parameters.

2.1.1. *The general model.* The basic random matrix model of this paper is defined as follows. Fix $d \geq 2$ and $n \in \mathbb{N}$, let $Z_0 \in M_d(\mathbb{C})_{\text{sa}}$ be any deterministic $d \times d$ self-adjoint matrix, and let Z_1, \dots, Z_n be any independent $d \times d$ self-adjoint random matrices with zero mean $\mathbf{E}[Z_i] = 0$ and complex-valued entries. We define

$$X := Z_0 + \sum_{i=1}^n Z_i. \quad (2.1)$$

Note that this model is slightly more general than the model (1.1) discussed in the introduction, in that we allow for an arbitrary mean.

Remark 2.1. The assumption that X is self-adjoint is made primarily for notational convenience. Our main results extend directly to non-self-adjoint matrices as follows. For any matrix $M \in M_d(\mathbb{C})$, define its dilation $\check{M} \in M_{2d}(\mathbb{C})_{\text{sa}}$ as

$$\check{M} := \begin{bmatrix} 0 & M \\ M^* & 0 \end{bmatrix}.$$

If we denote by $M = U|M|$ the polar decomposition of M , it follows that

$$\check{M} = V \begin{bmatrix} -|M| & 0 \\ 0 & |M| \end{bmatrix} V^* \quad \text{with} \quad V := \frac{1}{\sqrt{2}} \begin{bmatrix} U & U \\ -\mathbf{1} & \mathbf{1} \end{bmatrix},$$

where $|M| := (M^*M)^{\frac{1}{2}}$. As V is unitary, this shows that the eigenvalues of \check{M} coincide precisely (including multiplicities) with $\{\pm\sigma_i : i \in [d]\}$, where $\sigma_1, \dots, \sigma_d$ are the singular values of M . Consequently, by applying our results to \check{X} , we can immediately extend their conclusions on the eigenvalues of self-adjoint random matrices to the singular values of non-self-adjoint random matrices.

Singular values of rectangular random matrices are readily reduced to those of square matrices by adding additional zero rows or columns. On the other hand, we emphasize that the results of this paper do not provide bounds on the complex eigenvalues of non-self-adjoint matrices. For further comments on the non-self-adjoint case, see [9, Remark 2.6] and Corollary 2.17.

Associated with the random matrix X are two models that capture its structure in an idealized manner. We introduce these models presently.

2.1.2. *The Gaussian model.* Throughout this paper, we denote by G the Gaussian model that has the same mean and covariance structure as X . More precisely, denote by $\text{Cov}(X)$ the $d^2 \times d^2$ covariance matrix of the entries of X , that is,

$$\text{Cov}(X)_{ij,kl} := \mathbf{E}[(X - \mathbf{E}X)_{ij} \overline{(X - \mathbf{E}X)_{kl}}]. \quad (2.2)$$

We define G to be the $d \times d$ self-adjoint random matrix such that:

1. $\{\text{Re } G_{ij}, \text{Im } G_{ij} : i, j \in [d]\}$ are jointly Gaussian;
2. $\mathbf{E}[G] = \mathbf{E}[X]$ and $\text{Cov}(G) = \text{Cov}(X)$.

Note that as G is a self-adjoint matrix $G_{lk} = \overline{G_{kl}}$, the covariance matrix of the real-valued Gaussian vector $\{\operatorname{Re} G_{ij}, \operatorname{Im} G_{ij} : i, j \in [d]\}$ is fully specified by $\operatorname{Cov}(G)$. Thus the above properties uniquely define the distribution of G .

2.1.3. The noncommutative model. We now introduce a noncommutative model X_{free} that has the same mean and covariance structure as X . To this end, we must recall some basic notions from free probability theory; we refer to [60] for precise definitions and a comprehensive treatment.

Fix a C^* -probability space (\mathcal{A}, τ) , that is, a unital C^* -algebra \mathcal{A} endowed with a faithful trace τ . The following may be viewed as a noncommutative analogue of jointly Gaussian variables with mean μ and covariance C , cf. [60, p. 128].

Definition 2.2. A family of self-adjoint elements $s_1, \dots, s_m \in \mathcal{A}$ is said to be a *semicircular family with mean μ and covariance C* if

$$\tau(s_k) = \mu_k, \quad \tau((s_{k_1} - \mu_{k_1} \mathbf{1}) \cdots (s_{k_p} - \mu_{k_p} \mathbf{1})) = \sum_{\pi \in \text{NC}_2([p])} \prod_{\{i,j\} \in \pi} C_{k_i k_j}$$

for all $p \geq 1$ and $k, k_1, \dots, k_p \in [m]$, where $\text{NC}_2([p])$ denotes the collection of noncrossing pair partitions of $[p]$.

A $d \times d$ matrix $Y \in \text{M}_d(\mathcal{A})$ with \mathcal{A} -valued entries is naturally identified with an element of the C^* -algebra $\text{M}_d(\mathbb{C}) \otimes \mathcal{A}$, which we endow with the normalized trace $\operatorname{tr} \otimes \tau$, cf. [58, Chapter 9]. Define the entry covariance matrix $\operatorname{Cov}(Y)$ as

$$\operatorname{Cov}(Y)_{ij,kl} := \tau((Y_{ij} - \tau(Y_{ij})\mathbf{1})(Y_{kl} - \tau(Y_{kl})\mathbf{1})^*).$$

With these definitions in place, we can now define $X_{\text{free}} \in \text{M}_d(\mathcal{A})_{\text{sa}}$ as follows:

1. $\{\operatorname{Re}(X_{\text{free}})_{ij}, \operatorname{Im}(X_{\text{free}})_{ij} : i, j \in [d]\}$ is a semicircular family;
2. $(\operatorname{id} \otimes \tau)(X_{\text{free}}) = \mathbf{E}[X]$ and $\operatorname{Cov}(X_{\text{free}}) = \operatorname{Cov}(X)$.

Here we write $\operatorname{Re} a := \frac{1}{2}(a + a^*)$ and $\operatorname{Im} a := \frac{1}{2i}(a - a^*)$ for $a \in \mathcal{A}$.

Remark 2.3. As jointly Gaussian variables can always be written as linear combinations of independent standard Gaussian variables, G may be expressed as

$$G = Z_0 + \sum_{i=1}^N A_i g_i$$

for some deterministic matrices $A_1, \dots, A_N \in \text{M}_d(\mathbb{C})_{\text{sa}}$ and i.i.d. (real) standard Gaussians g_1, \dots, g_N (note that this representation is not unique). Given any such a representation, it is readily verified that one may express X_{free} as

$$X_{\text{free}} = Z_0 \otimes \mathbf{1} + \sum_{i=1}^N A_i \otimes s_i,$$

where s_1, \dots, s_N is a *free* semicircular family, that is, with zero mean and identity covariance matrix. Thus the present definition of X_{free} agrees with the one in [9].

2.1.4. *Matrix parameters.* Let X be a self-adjoint random matrix as in (2.1). The following basic parameters will appear in our main results:

$$\sigma(X) := \|\mathbf{E}[(X - \mathbf{E}X)^2]\|^{\frac{1}{2}}, \quad (2.3)$$

$$\sigma_*(X) := \sup_{\|v\|=\|w\|=1} \mathbf{E}[|\langle v, (X - \mathbf{E}X)w \rangle|^2]^{\frac{1}{2}}, \quad (2.4)$$

$$v(X) := \|\text{Cov}(X)\|^{\frac{1}{2}}, \quad (2.5)$$

$$R(X) := \left\| \max_{1 \leq i \leq n} \|Z_i\| \right\|_{\infty}, \quad (2.6)$$

where $\|Y\|_{\infty}$ denotes the essential supremum of the random variable $|Y|$.

The significance of these parameters may be summarized as follows. The parameter $\sigma(X)$ roughly captures the spread of the spectrum of $X - \mathbf{E}X$, as was explained in the introduction. The parameter $\sigma_*(X)$ controls the fluctuations of the spectral statistics of X and G , see, e.g., section 5.2 below. The parameter $v(X)$ quantifies the degree to which the spectral properties of G are captured by those of X_{free} : this is the main outcome of the theory of [9]. Finally, the universality principles of this paper will show that the parameter $R(X)$ quantifies the degree to which the spectral properties of X are captured by those of G .

The parameter $R(X)$ is meaningful only when the random matrices Z_i are uniformly bounded. We will also prove versions of our main results that apply to unbounded summands under minimal moment assumptions. The formulation of these results requires the following modified matrix parameters:

$$\sigma_q(X) := (\text{tr } \mathbf{E}[(X - \mathbf{E}X)^2]^{\frac{q}{2}})^{\frac{1}{q}}, \quad (2.7)$$

$$R_q(X) := (\sum_{i=1}^n \mathbf{E}[\text{tr } |Z_i|^q])^{\frac{1}{q}}, \quad (2.8)$$

$$\bar{R}(X) := \mathbf{E} \left[\max_{1 \leq i \leq n} \|Z_i\|^2 \right]^{\frac{1}{2}} \quad (2.9)$$

for $q < \infty$, and $\sigma_{\infty}(X) := \sigma(X)$, $R_{\infty}(X) := R(X)$.

Remark 2.4. Let us emphasize the following basic facts.

- All these parameters depend only on $X - \mathbf{E}X$, i.e., they do not depend on Z_0 .
- $\sigma(X), \sigma_q(X), \sigma_*(X), v(X)$ only depend on the covariance of the entries of X , and therefore capture the universal behavior that is shared between X , G , and X_{free} .
- In contrast, $R(X), R_q(X), \bar{R}(X)$ are specific to the non-Gaussian model. While we denote these as parameters of X for notational simplicity, we emphasize that these parameters depend on how X is represented as a sum of Z_i as in (2.1).
- Recall the basic inequalities $\sigma_*(X) \leq \sigma(X)$ and $\sigma_*(X) \leq v(X)$ [9, §2.1].

Remark 2.5. In most applications of our theory $v(X), \bar{R}(X) \ll \sigma(X)$ (up to a logarithmic factor in dimension): in this case, our results will show that the spectral edges of X agree with those of X_{free} to leading order, and that the spectral distributions of X and X_{free} agree at a mesoscopic scale.

To help the reader gain some insight into these parameters, we list their order of magnitude for some classical random matrix models in Table 2.1. In all these models, the condition $v(X), \bar{R}(X) \ll \sigma(X)$ is essentially optimal for universality. For

Model	$\sigma(X)$	$v(X)$	$R(X)$	$\bar{R}(X)$
(a) Erdős-Rényi graph $G(d, q)$ (section 3.1)	\sqrt{dq}	\sqrt{q}	1	$O(1)$
(b) Random k -regular graph (section 3.2.2)	\sqrt{k}	$\sqrt{\frac{k}{d}}$	1	1
(c) Wigner matrix: p moments (section 3.1)	\sqrt{d}	1	∞	$O(d^{\frac{2}{p}})$
(d) Band matrix: width k , p moments (section 3.5)	\sqrt{k}	1	∞	$O((kd)^{\frac{1}{p}})$

TABLE 2.1. Order of magnitude of the matrix parameters for some classical models:
 (a) adjacency matrix of Erdős-Rényi $G(d, q)$ graph; (b) adjacency matrix of random k -regular graph with d vertices; (c) Wigner matrix X of dimension d with $\mathbf{E}[X_{ij}] = 0$, $\mathbf{E}[X_{ij}^2] = 1$, $\|X_{ij}\|_p = O(1)$; (d) Band matrix \bar{X} defined by $\bar{X}_{ij} = X_{ij}1_{|i-j| \leq \frac{k-1}{2}}$.

random graphs, this requires that the (average) degree diverges; this is necessary, as the spectral distribution of both Erdős-Rényi and random regular graphs of constant (average) degree does not match the semicircle distribution of the associated Gaussian model. For Wigner matrices whose entries have p bounded moments, we need $p > 4$; this is nearly optimal for the spectral edges, as it is well known that the spectrum has outliers when $p < 4$. The analogous condition for random band matrices is also nearly optimal (cf. Corollary 3.32).

For these classical models, much more precise results have been achieved at the scale of the fluctuations of the eigenvalues using problem-specific methods. Our results do not provide any information at this scale, but are instead able to establish universality for the leading order behavior of the bulk and edges of the spectrum in far more general situations; see section 3 for a diverse range of applications.

2.2. Universality. We now provide precise formulations of the universality principle. We prove several results that capture different aspects of the spectrum.

2.2.1. Universality of the spectrum. In this section, we formulate the universality principle for the spectrum $\text{sp}(X)$ of X . Recall that the Hausdorff distance between two subsets $A, B \subseteq \mathbb{R}$ of the real line is defined as

$$d_H(A, B) := \inf\{\varepsilon > 0 : A \subseteq B + [-\varepsilon, \varepsilon] \text{ and } B \subseteq A + [-\varepsilon, \varepsilon]\}.$$

Our main result is the following.

Theorem 2.6 (Spectrum universality). *For any $t \geq 0$, we have*

$$\mathbf{P}[d_H(\text{sp}(X), \text{sp}(G)) > C\varepsilon(t)] \leq de^{-t},$$

where C is a universal constant and

$$\varepsilon(t) = \sigma_*(X) t^{\frac{1}{2}} + R(X)^{\frac{1}{3}} \sigma(X)^{\frac{2}{3}} t^{\frac{2}{3}} + R(X) t.$$

Moreover,

$$\mathbf{E}[d_H(\text{sp}(X), \text{sp}(G))] \lesssim \sigma_*(X) (\log d)^{\frac{1}{2}} + R(X)^{\frac{1}{3}} \sigma(X)^{\frac{2}{3}} (\log d)^{\frac{2}{3}} + R(X) \log d.$$

Note that while we defined the distributions of X and G in section 2.1, we did not specify their joint distribution. However, the conclusion of Theorem 2.6 is valid regardless of how X and G are defined on the same probability space due to the strong concentration properties of random matrices.

Theorem 2.6 readily yields a universality principle for the spectral edge. In the following, we denote by $\lambda_{\max}(X) := \sup \text{sp}(X)$ the upper edge of the spectrum. (Inequalities for the lower edge follow readily as $\inf \text{sp}(X) = -\lambda_{\max}(-X)$.)

Corollary 2.7 (Edge universality). *For any $t \geq 0$, we have*

$$\mathbf{P} [|\lambda_{\max}(X) - \lambda_{\max}(G)| > C\varepsilon(t)] \leq de^{-t},$$

as well as

$$\mathbf{P} [|\lambda_{\max}(X) - \mathbf{E}\lambda_{\max}(G)| > C\varepsilon(t)] \leq de^{-t},$$

where C is a universal constant and $\varepsilon(t)$ is as in Theorem 2.6. Moreover,

$$|\mathbf{E}\lambda_{\max}(X) - \mathbf{E}\lambda_{\max}(G)| \lesssim \sigma_*(X) (\log d)^{\frac{1}{2}} + R(X)^{\frac{1}{3}}\sigma(X)^{\frac{2}{3}}(\log d)^{\frac{2}{3}} + R(X) \log d.$$

The same bounds hold if $\lambda_{\max}(X), \lambda_{\max}(G)$ are replaced by $\|X\|, \|G\|$, respectively.

The proofs of Theorem 2.6 and Corollary 2.7 are given in section 7.

The above results are meaningful only when $R(X) < \infty$, which requires that the matrices Z_i are uniformly bounded. However, this restriction is almost entirely removed by the following result that is proved in section 8.

Theorem 2.8 (Spectrum universality: unbounded case). *We have*

$$\mathbf{P} [d_H(\text{sp}(X), \text{sp}(G)) > C\varepsilon_R(t), \max_{1 \leq i \leq n} \|Z_i\| \leq R] \leq de^{-t}$$

for all $t \geq 0$ and $R \geq \bar{R}(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}} + 2^{\frac{1}{2}}\bar{R}(X)$, where

$$\varepsilon_R(t) = \sigma_*(X) t^{\frac{1}{2}} + R^{\frac{1}{3}}\sigma(X)^{\frac{2}{3}}t^{\frac{2}{3}} + Rt$$

and C is a universal constant. Moreover,

$$\mathbf{E} [d_H(\text{sp}(X), \text{sp}(G))] \lesssim \sigma_*(X) (\log d)^{\frac{1}{2}} + \bar{R}(X)^{\frac{1}{6}}\sigma(X)^{\frac{5}{6}} \log d$$

whenever $\bar{R}(X) (\log d)^3 \lesssim \sigma(X)$.

2.2.2. Universality of spectral statistics. We now complement the above results by formulating universality principles for various spectral statistics.

We begin by establishing universality of even moments.

Theorem 2.9 (Moment universality). *For any $p \in \mathbb{N}$ and $2p \leq q \leq \infty$, we have*

$$|\mathbf{E}[\text{tr } X^{2p}]^{\frac{1}{2p}} - \mathbf{E}[\text{tr } G^{2p}]^{\frac{1}{2p}}| \lesssim R_q(X)^{\frac{1}{3}}\sigma_q(X)^{\frac{2}{3}}p^{\frac{2}{3}} + R_q(X)p$$

as well as

$$|\mathbf{E}[\text{tr } X^{2p}]^{\frac{1}{2p}} - \mathbf{E}[\text{tr } G^{2p}]^{\frac{1}{2p}}| \lesssim R_q(X)p^2.$$

The first inequality has a better dependence on p , while the second inequality yields a sharper estimate when $R_q(X)p^2 \ll \sigma_q(X)$. Both inequalities are variations of the same proof, which is given in section 6.

Moment bounds provide limited information on the spectrum of a random matrix. Complementary information can be extracted from the resolvent.

Theorem 2.10 (Resolvent universality). *We have*

$$\|\mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}]\| \lesssim \frac{R(X)\sigma(X)^2 + R(X)^3 \log d}{(\text{Im } z)^4}$$

for every $z \in \mathbb{C}$ with $\text{Im } z > 0$. Consequently,

$$\|\mathbf{E}[\varphi(X)] - \mathbf{E}[\varphi(G)]\| \lesssim (R(X)\sigma(X)^2 + R(X)^3 \log d) \|\varphi\|_{W^{5,1}(\mathbb{R})}$$

for every $\varphi \in W^{5,1}(\mathbb{R})$.

We can also generalize Theorem 2.10 to unbounded random matrices, at the expense of somewhat worse quantitative error bounds.

Theorem 2.11 (Resolvent universality: unbounded case). *We have*

$$\|\mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}]\| \lesssim \frac{\sigma_*(X) + \bar{R}(X)^{\frac{1}{10}}\sigma(X)^{\frac{9}{10}}}{(\operatorname{Im} z)^2}$$

for every $z \in \mathbb{C}$ with $\operatorname{Im} z > 0$ and

$$\|\mathbf{E}[\varphi(X)] - \mathbf{E}[\varphi(G)]\| \lesssim (\sigma_*(X) + \bar{R}(X)^{\frac{1}{10}}\sigma(X)^{\frac{9}{10}}) \|\varphi\|_{W^{3,1}(\mathbb{R})}$$

for every $\varphi \in W^{3,1}(\mathbb{R})$, provided that $\bar{R}(X)(\log d)^{\frac{5}{3}} \lesssim \sigma(X)$.

The proofs of Theorems 2.10 and 2.11 are given in sections 6 and 8.

While the above universality principles suffice for many applications, our proofs can be readily adapted to the study of other spectral statistics. In particular, a universality principle for moments of the resolvent $\mathbf{E}[\operatorname{tr}|z\mathbf{1} - X|^{-2p}]$ (Theorem 6.8) will play a central role in the proof of Theorem 2.6. Let us also note that the quantitative bounds of Theorems 2.10 and 2.11 can be considerably improved if one is interested only in the trace of the resolvent, cf. Remark 6.13. However, the norm bounds given here are particularly useful as they contain information on the eigenvectors of the random matrices, as will be explained in section 3.6.

Remark 2.12. For simplicity, we formulated the results of this section only for expected spectral statistics. However, corresponding tail bounds follow by combining these bounds with concentration inequalities for the relevant spectral statistics; cf. Lemma 9.20 for moments, and Proposition 5.10 for general spectral statistics.

Remark 2.13. Theorems 2.10 and 2.11 provide access to the mesoscopic distribution of the random matrices (at a scale determined by $R(X)$ or $\bar{R}(X)$). Their proofs are much simpler than our universality results for the spectral edges, and could also be approached by more traditional methods [32, 33]; they are included here for completeness. While these results apply in principle to arbitrary spectral statistics φ , they do not provide useful bounds on p th moments for large p (and thus for the spectral edges) as this would give rise to analogues of Theorems 2.9 and 6.8 with constants growing exponentially rather than polynomially in p .

2.3. Matrix concentration inequalities. Universality principles show that a non-Gaussian random matrix X behaves as a Gaussian random matrix G , but do not explain in themselves what the spectra of these matrices look like. To apply these results to specific models, our universality principles must be combined with suitable bounds for Gaussian random matrices. We will presently show that both classical matrix concentration inequalities, and new sharp matrix concentration inequalities, arise directly from our main results.

2.3.1. Classical matrix concentration inequalities. We begin by briefly illustrating how two classical matrix concentration inequalities can be recovered from our main results. While direct proofs of these inequalities [77, 56] are considerably simpler (and yield better numerical constants), this provides a new explanation for the form of these inequalities and serves as the simplest illustration of our results.

Example 2.14 (Matrix Bernstein). As $\sigma_*(X) \leq \sigma(X)$ and as $R(X)^{\frac{1}{3}}\sigma(X)^{\frac{2}{3}}t^{\frac{2}{3}} \lesssim \sigma(X)t^{\frac{1}{2}} + R(X)t$ by Young's inequality, Corollary 2.7 implies

$$\mathbf{E}\|X\| \lesssim \mathbf{E}\|G\| + \sigma(X)\sqrt{\log d} + R(X)\log d.$$

We may therefore view the matrix Bernstein inequality (1.3) as a direct consequence of the Gaussian bound (1.2) and Corollary 2.7. The tail bound of [77, Theorem 6.1.1] can also easily be recovered up to universal constants from Corollary 2.7.

Example 2.15 (Matrix Rosenthal). Suppose that $\mathbf{E}[X] = 0$. Then the noncommutative Khintchine inequality [66, §9.8] states that for every $p \in \mathbb{N}$, we have

$$\mathbf{E}[\mathrm{tr} G^{2p}]^{\frac{1}{2p}} \lesssim \sigma_{2p}(X) \sqrt{p}$$

(the norm bound (1.2) follows directly from this estimate by choosing $p \sim \log d$). Combining the noncommutative Khintchine inequality with Theorem 2.9 yields

$$\mathbf{E}[\mathrm{tr} X^{2p}]^{\frac{1}{2p}} \lesssim \sigma_{2p}(X) \sqrt{p} + R_{2p}(X) p,$$

where we used that $R_{2p}(X)^{\frac{1}{3}} \sigma_{2p}(X)^{\frac{2}{3}} p^{\frac{2}{3}} \lesssim \sigma_{2p}(X) \sqrt{p} + R_{2p}(X) p$ by Young's inequality. This matrix Rosenthal inequality [56, Corollary 7.4] may therefore be viewed as another consequence of the universality principle.

2.3.2. Sharp matrix concentration inequalities. A primary motivation behind our universality principles is that they may be combined with the Gaussian theory of [9] to obtain a powerful new family of sharp matrix concentration inequalities for sums of independent random matrices. These inequalities reduce the study of a very large family of nonhomogeneous random matrices to explicit computations. Let us state a prototypical inequality of this kind for sake of illustration.

Theorem 2.16 (Sharp matrix concentration). *For any $t \geq 0$, we have*

$$\mathbf{P}[\mathrm{sp}(X) \subseteq \mathrm{sp}(X_{\mathrm{free}}) + C\{v(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}}(\log d)^{\frac{3}{4}} + \varepsilon(t)\}[-1, 1]] \geq 1 - 2de^{-t},$$

where C is a universal constant and $\varepsilon(t)$ is as in Theorem 2.6. In particular,

$$\mathbf{P}[\lambda_{\max}(X) \geq \lambda_{\max}(X_{\mathrm{free}}) + Cv(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}}(\log d)^{\frac{3}{4}} + C\varepsilon(t)] \leq 2de^{-t}$$

and

$$\begin{aligned} \mathbf{E}\lambda_{\max}(X) &\leq \lambda_{\max}(X_{\mathrm{free}}) + \\ &C\{v(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}}(\log d)^{\frac{3}{4}} + R(X)^{\frac{1}{3}}\sigma(X)^{\frac{2}{3}}(\log d)^{\frac{2}{3}} + R(X)\log d\}. \end{aligned}$$

The same bounds hold if $\lambda_{\max}(X), \lambda_{\max}(X_{\mathrm{free}})$ are replaced by $\|X\|, \|X_{\mathrm{free}}\|$.

Proof. This follows immediately by the union bound from Theorem 2.6 and an application of [9, Theorem 2.1] to the Gaussian matrix G . \square

Theorem 2.16 shows that when $v(X)$ and $R(X)$ are sufficiently small, the spectrum of X is controlled by that of its noncommutative model X_{free} . The latter admits explicit computations using tools of free probability. For example, it was shown by Lehner [54, Corollary 1.5] (cf. [9, §4.1]) that

$$\lambda_{\max}(X_{\mathrm{free}}) = \inf_{B > 0} \lambda_{\max}(B^{-1} + \mathbf{E}X + \mathbf{E}[(X - \mathbf{E}X)B(X - \mathbf{E}X)]),$$

where the infimum is over positive definite $B \in M_d(\mathbb{C})_{\mathrm{sa}}$ (the infimum may be further restricted to B for which the matrix in $\lambda_{\max}(\cdots)$ is a multiple of the identity). On the other hand, one may also easily deduce “user-friendly” bounds in the spirit of [77] whose statements make no reference to free probability.

Corollary 2.17 (“User-friendly” bound). *Let $Y = \sum_{i=1}^n Z_i$, where Z_1, \dots, Z_n are independent (possibly non-self-adjoint) $d \times d$ random matrices with $\mathbf{E}[Z_i] = 0$. Then*

$$\mathbf{P}[\|Y\| \geq \|\mathbf{E}Y^*Y\|^{\frac{1}{2}} + \|\mathbf{E}YY^*\|^{\frac{1}{2}} + C\{v(Y)^{\frac{1}{2}}\sigma(Y)^{\frac{1}{2}}(\log d)^{\frac{3}{4}} + \sigma_*(Y)t^{\frac{1}{2}} + R(Y)^{\frac{1}{3}}\sigma(Y)^{\frac{2}{3}}t^{\frac{2}{3}} + R(Y)t\}] \leq 4de^{-t}$$

for a universal constant C and all $t \geq 0$, and

$$\mathbf{E}\|Y\| \leq \|\mathbf{E}Y^*Y\|^{\frac{1}{2}} + \|\mathbf{E}YY^*\|^{\frac{1}{2}} + C\{v(Y)^{\frac{1}{2}}\sigma(Y)^{\frac{1}{2}}(\log d)^{\frac{3}{4}} + R(Y)^{\frac{1}{3}}\sigma(Y)^{\frac{2}{3}}(\log d)^{\frac{2}{3}} + R(Y)\log d\}.$$

Here we define $\sigma(Y) := \max(\|\mathbf{E}Y^*Y\|^{\frac{1}{2}}, \|\mathbf{E}YY^*\|^{\frac{1}{2}})$ in the non-self-adjoint case, while $\sigma_*(Y), v(Y), R(Y)$ are defined as in section 2.1.4.

Proof. Combine Theorem 2.16, Remark 2.1, and [9, Lemmas 2.5 and 4.10]. \square

There are many other possible combinations of the results of [9] and in section 2.2 above. For example, unbounded variants of Theorem 2.16 and Corollary 2.17 that involve the parameter $\bar{R}(X)$ instead of $R(X)$ are readily deduced from Theorem 2.8, and we obtain two-sided bounds for the moments and other spectral statistics of X in terms of those of X_{free} by combining the results of section 2.2.2 with those of [9, §2.2]. In the interest of space we do not spell out further combinations of this kind here; the appropriate results are easily applied directly in any given application.

3. APPLICATIONS

In this section, we provide precise formulations of the applications that were introduced in section 1.3 above, and discuss how they arise from our main results. Some technical proofs are postponed until section 9.

3.1. Independent entries. Before we turn to the main applications of this paper, we begin in this short section by bounding the matrix parameters that appear in our main results in the special case of random matrices with independent entries. While much stronger results and more complicated models will be considered in the sequel, our aim here is to help the reader gain some insight into the magnitudes of the parameters that appear in our bounds in the simplest setting.

Let X be a $d \times d$ self-adjoint random matrix so that $(X_{ij})_{i \geq j}$ are independent real random variables. Then we may write X in the form (2.1) as

$$X = \mathbf{E}[X] + \sum_{i \geq j} \xi_{ij} E_{ij} \tag{3.1}$$

where $\xi_{ij} := X_{ij} - \mathbf{E}X_{ij}$, $E_{ij} := e_i e_j^* + e_j e_i^*$ for $i > j$, and $E_{ii} := e_i e_i^*$.

Lemma 3.1. *For the model (3.1), we have*

$$\sigma(X)^2 = \max_i \sum_j \text{Var}(X_{ij}), \quad \sigma_*(X)^2 \leq v(X)^2 \leq 2 \max_{i,j} \text{Var}(X_{ij}),$$

and for any $p \geq 1$

$$R(X) \leq \max_{ij} \|\xi_{ij}\|_\infty, \quad \bar{R}(X) \leq \left(\sum_{i,j} \mathbf{E}[\xi_{ij}^{2p}] \right)^{1/2p}.$$

Proof. As $\sigma(X), \sigma_*(X), v(X)$ are unchanged if we replace X by its Gaussian model, the first equation display follows from [9, Lemma 3.1]. The bound on $R(X)$ follows immediately from the definition using $\|E_{ij}\| \leq 1$. To bound $\bar{R}(X)$, we note that

$$\bar{R}(X)^{2p} \leq \mathbf{E} \left[\max_{i,j} \|\xi_{ij} E_{ij}\|^{2p} \right] \leq \sum_{i,j} \mathbf{E} [\|\xi_{ij}\|^{2p}],$$

where we used Jensen in the first and $\|E_{ij}\| \leq 1$ in the second inequality. \square

The parameter $R(X)$ is finite when the entries of X are uniformly bounded, as is often the case for discrete random matrices; otherwise, $\bar{R}(X)$ must be used. Let us illustrate these parameters in two classical examples.

Example 3.2 (Erdős-Rényi). Let $X_{ij} \sim \text{Bern}(q)$ for all i, j , i.e., X is the adjacency matrix of an Erdős-Rényi graph with d vertices and edge probability q . Then

$$\sigma(X) = \sqrt{dq(1-q)}, \quad \sigma_*(X) \leq v(X) \lesssim \sqrt{q(1-q)}, \quad R(X) \lesssim 1.$$

The Gaussian model $G - \mathbf{E}G$ associated to $X - \mathbf{E}X$ is a Wigner matrix with entry variance $q(1-q)$, for which it is well known that $\mathbf{E}\|G - \mathbf{E}G\| = (1+o(1))2\sqrt{dq(1-q)}$ (see, e.g., [5]). Thus Corollary 2.7 yields

$$\mathbf{E}\|X - \mathbf{E}X\| = (1+o(1))2\sqrt{dq(1-q)} \quad \text{when } dq(1-q) \gg (\log d)^4.$$

The latter condition is optimal up to the power of the logarithm [16]. Note that it is readily verified in this example that $\bar{R}(X) \gtrsim 1$ as long as $\min(q, 1-q) \gtrsim \frac{1}{d^2}$, so that the application of Theorem 2.8 does not yield any improvement here.

Example 3.3 (Wigner matrix with p moments). Suppose that $(X_{ij})_{i \geq j}$ are i.i.d. with zero mean, unit variance, and $\|X_{ij}\|_p \leq C$ for some $p \geq 2$. Then

$$\sigma(X) = \sqrt{d}, \quad \sigma_*(X) \leq v(X) \lesssim 1, \quad \bar{R}(X) \lesssim Cd^{\frac{2}{p}}.$$

As the Gaussian model G is a Wigner matrix with entry variance 1, it is classical that $\mathbf{E}\|G\| = (1+o(1))2\sqrt{d}$ as above. Thus Theorem 2.8 yields

$$\mathbf{E}\|X\| = (1+o(1))2\sqrt{d} \quad \text{when } d \gg C^2 d^{\frac{4}{p}} (\log d)^{12}.$$

In particular, the latter condition holds as soon as $p > 4$. This is again optimal up to the power of the logarithm, cf. Corollary 3.32 below.

We emphasize that the results of this paper do not provide any new information on the classical Examples 3.2 and 3.3, whose spectral properties have been studied in stunning detail in the random matrix theory literature down to microscopic scales inaccessible by our bounds. However, for nonhomogeneous random matrices with independent entries, the theory of this paper provides new results that were not accessible by prior methods; see, e.g., Corollary 3.32 below.

Remark 3.4. Combining Lemma 3.1 with Corollary 2.17 yields “user-friendly” inequalities for random matrices with independent entries. Similar inequalities were obtained in [52, §4.3] by different methods that are specific to the independent entry case. The latter yield slightly better quantitative results in some examples (such as for the Erdős-Rényi model, cf. [52, Example 4.1]), but cannot capture the sharp leading-order term $\|X_{\text{free}}\|$ as in Theorem 2.16. For this reason, the bounds of this paper are often sharper than those of [52] even for independent entry models.

3.2. Random graphs and expanders. While random regular graphs, random Cayley graphs, and random n -lifts appear at first sight to be rather different models, our analysis of all these models will ultimately be based on a basic observation regarding random matrices defined by group representations. We first introduce some general facts, and then consider each of the above models in turn.

3.2.1. Random matrices defined by group representations. Let Γ be a finite group, let $\rho : \Gamma \rightarrow U(d)$ be a nontrivial unitary representation of dimension d , and let g_1, \dots, g_k be i.i.d. random variables drawn uniformly from Γ . Then

$$X = \sum_{i=1}^k (\rho(g_i) + \rho(g_i)^*) \quad (3.2)$$

defines a random matrix of the form (2.1). As $\rho(g_i)$ are unitary, it is easy to see that $\sigma(X) \asymp \sqrt{k}$ and $R(X) \asymp 1$. Therefore, our universality principles show that the spectrum of such matrices behaves as the associated Gaussian model when $k \gg (\log d)^\beta$ for a suitable $\beta > 0$. The random regular graph, Cayley graph, and n -lift models will all arise as variations on this theme.

To understand the behavior of such matrices, it then remains to understand the behavior of the Gaussian model associated to X . The following standard group-theoretic facts will suffice for this purpose.

Lemma 3.5. *Suppose that ρ is irreducible. Then there exists $s \in \{-1, 0, 1\}$ so that*

$$\mathbf{E}[\rho(g_i)] = 0, \quad \text{Cov}(\rho(g_i)) = \frac{1}{d}\mathbf{1}, \quad \mathbf{E}[\rho(g_i)^2] = \frac{s}{d}\mathbf{1}.$$

Proof. The first two statements are standard facts about nontrivial irreducible representations [51, Proposition 4.3.1 and Corollary 4.3.9]. To prove the last statement, we first observe that $\text{Tr } \mathbf{E}[\rho(g_i)^2] =: s \in \{-1, 0, 1\}$ by a theorem of Frobenius and Schur [51, Theorem 6.2.3]. On the other hand, for any $h \in \Gamma$, the random variables $g_i, h^{-1}g_i, g_ih^{-1}$ are uniformly distributed on Γ . Therefore,

$$\rho(h) \mathbf{E}[\rho(g_i)^2] \rho(h^{-1}) = \mathbf{E}[\rho(g_ih^{-1}g_i)] \rho(h^{-1}) = \mathbf{E}[\rho(g_i)^2]$$

for every $h \in \Gamma$, and the conclusion follows by [51, Proposition 4.3.4]. \square

Remark 3.6. Let us emphasize that as $\rho(g_i)$ is not self-adjoint, the entry covariance matrix $\text{Cov}(\rho(g_i))$ as defined in (2.2) does not fully determine the covariance of the real and imaginary parts of the entries of $\rho(g_i)$. In fact, by the Frobenius-Schur theorem used in the proof, it is the value s that determines whether the representation is real ($s = 1$), complex ($s = 0$), or quaternionic ($s = -1$).

3.2.2. Random regular graphs. In this subsection, let Π_1, \dots, Π_k be i.i.d. uniformly distributed random $d \times d$ permutation matrices. Then

$$X = \sum_{i=1}^k (\Pi_i + \Pi_i^*)$$

is the adjacency matrix of a (not necessarily simple) $2k$ -regular graph with d vertices. This is the *permutation model* of random regular graphs. Before we proceed, let us recall a basic fact about the adjacency matrix of any regular graph.

Lemma 3.7 (Alon-Boppana). *Let A be the adjacency matrix of an m -regular graph with d vertices. Then the largest and second largest eigenvalue of A satisfy*

$$\lambda_1(A) = m, \quad \lambda_2(A) \geq \left(1 - C \frac{\log m}{\log d}\right) 2\sqrt{m-1}$$

for a universal constant C . Moreover, $1 \in \mathbb{R}^d$ (the vector all of whose entries are one) is an eigenvector of A with eigenvalue m .

Proof. The statement about the largest eigenvalue and eigenvector follow immediately from the Perron-Frobenius theorem and $A1 = m1$. The bound on the second eigenvalue is a classical result of Alon-Boppana (in this form, see [61]). \square

In the seminal paper [43], Friedman shows that when k is fixed and $d \rightarrow \infty$, the second largest eigenvalue of the adjacency matrix X of the permutation model satisfies $\lambda_2(X) \leq (1 + o(1))2\sqrt{2k-1}$ with high probability. Thus, by Lemma 3.7, such graphs have the largest possible spectral gap to leading order, that is, they are “nearly Ramanujan”. It is an old question whether this conclusion persists when both $k, d \rightarrow \infty$; see, e.g., [15, §1.4], and [84] for further questions of this kind. While some quantitative information can be extracted from proofs of Friedman’s theorem (for example, a special case of [21, Theorem 1.4] shows that Friedman’s result remains valid when $k \ll \frac{\log d}{(\log \log d)^2}$), all known proofs appear to break down for larger k . In the latter regime, it is known [44, 39, 36] that $\lambda_2(X) = O(\sqrt{k})$, but these results cannot recover the optimal constant.

We presently settle this question for $k \gg (\log d)^4$. This leaves only a narrow range of parameters $\frac{\log d}{(\log \log d)^2} \lesssim k \lesssim (\log d)^4$ open.²

Theorem 3.8. *Denote by X^\perp the restriction of X to 1^\perp . Then for every $a > 0$, there is a constant $C > 0$ depending only on a so that*

$$\|X^\perp\| \leq \left(1 + C \frac{(\log d)^{\frac{3}{4}}}{d^{\frac{1}{4}}} + C \frac{(\log d)^{\frac{2}{3}}}{k^{\frac{1}{6}}} + C \frac{\log d}{k^{\frac{1}{2}}}\right) 2\sqrt{2k}$$

with probability at least $1 - d^{-a}$. In particular, $\lambda_2(X) \leq (1 + o(1))2\sqrt{2k-1}$ with probability $1 - o(1)$ whenever $d, k \rightarrow \infty$ with $(\log d)^4 = o(k)$.

Proof. The random matrix X is a special case of the model of the previous section, where we choose ρ to be the permutation representation of the symmetric group S_d . Moreover, $\rho^\perp = \rho|_{1^\perp}$ is an irreducible representation of S_d of dimension $d-1$. We can therefore compute using Lemma 3.5

$$\mathbf{E}[X^\perp] = 0, \quad \|\mathbf{E}[(X^\perp)^2]\| = 2k \left(1 + \frac{s}{d-1}\right)$$

with $|s| \leq 1$, as well as (using that $v(A+B) \leq v(A) + v(B)$)

$$\sigma_*(X^\perp) \leq v(X^\perp) \leq 2v\left(\sum_{i=1}^k \rho^\perp(g_i)\right) = 2\sqrt{\frac{k}{d-1}}, \quad R(X^\perp) \leq 2.$$

The bound on $\|X^\perp\|$ follows directly by applying the tail bound of Corollary 2.17 with $t = (a+3)\log d$. As 1 is an eigenvector of X with eigenvalue $\lambda_1(X)$, we clearly have $\lambda_2(X) \leq \|X^\perp\|$ and the proof is complete. \square

²This remaining range of parameters was recently settled in the subsequent work [34].

Remark 3.9. Theorem 3.8 yields an upper bound on $\lambda_2(X)$ for the permutation model, which agrees with the Alon-Boppana lower bound that holds for *any* regular graph. Note, however, that the Alon-Boppana bound (Lemma 3.7) is only meaningful when $\log k \ll \log d$. A variant of Theorem 3.8 readily shows that for the permutation model, the lower bound $\lambda_2(X) \geq (1 + o(1))2\sqrt{2k - 1}$ remains valid for *any* $k \gg (\log d)^4$, even when the Alon-Boppana bound fails (e.g., combine Corollary 2.7 with [9, Corollary 2.11]). However, when the Alon-Boppana bound fails it need not be the case that random regular graphs are optimal expanders.

3.2.3. Random Cayley graphs. In this subsection we let Γ be a finite group, and let g_1, \dots, g_k be i.i.d. variables drawn uniformly from Γ . We consider the Cayley graph defined by the generating set $\{g_1, \dots, g_k, g_1^{-1}, \dots, g_k^{-1}\}$, and denote its adjacency matrix by X . This model is a special case of (3.2) where $\rho : \Gamma \rightarrow U(\ell_2(\Gamma))$ is the right-regular representation of Γ , that is, $(\rho(g)f)_h = f_{hg}$.

A classical result of Alon and Roichman [2] states that if we choose $k \gg \log |\Gamma|$ generators, then the random Cayley graph is an expander, that is, $\lambda_2(X) = o(k)$ (see also [59] and the references therein for alternative proofs and extensions).³ The remarkable feature of this result is that it holds for *any* finite group Γ . Here we exhibit a new phenomenon: for many groups, choosing $k \gg (\log |\Gamma|)^4$ generators suffices to ensure that the random Cayley graph is nearly Ramanujan, that is, that $\lambda_2(X) \leq (1 + o(1))2\sqrt{2k - 1}$. This cannot happen for an arbitrary group, as the weaker estimates of [2] are essentially optimal for abelian groups. Rather, we show that this is the case for general nonabelian groups as soon as the dimensions of the nontrivial irreducible representations are not too small.

Theorem 3.10. *Denote by $d_0 \leq d_1 \leq \dots \leq d_m$ the dimensions of the isomorphism classes of irreducible representations of Γ , where $d_0 = 1$ corresponds to the trivial representation. Define the parameter*

$$\alpha(\Gamma) := \max_{1 \leq i \leq m} \sqrt{\frac{\log(i+1)}{d_i}}.$$

Then for every $a > 0$, there is a constant $C > 0$ depending only on a so that

$$\|X^\perp\| \leq \left(1 + C\alpha(\Gamma) + C\frac{(\log d_1)^{\frac{3}{4}}}{d_1^{\frac{1}{4}}} + C\frac{(\log |\Gamma|)^{\frac{2}{3}}}{k^{\frac{1}{6}}} + C\frac{\log |\Gamma|}{k^{\frac{1}{2}}}\right)2\sqrt{2k}$$

with probability at least $1 - d_1^{-a}$. In particular, $\lambda_2(X) \leq (1 + o(1))2\sqrt{2k - 1}$ with probability $1 - o(1)$ whenever $\alpha(\Gamma) = o(1)$ and $(\log |\Gamma|)^4 = o(k)$.

Proof. The Peter-Weyl theorem [51, Theorem 5.4.1] states that the right-regular representation decomposes as a direct sum $\rho = \bigoplus_{i=0}^m (\rho_i \otimes \mathbf{1}_{d_i})$ of non-isomorphic irreducible representations ρ_i of Γ , each of which appears with multiplicity d_i (here $\mathbf{1}_d$ is the identity matrix of dimension d). In other words, there is a choice of basis in which X is block-diagonal with blocks $X_i \otimes \mathbf{1}_{d_i}$, where each X_i is of the form (3.2) for a distinct irreducible representation of Γ . As the trivial representation accounts for the action on the eigenvector 1, we obtain $X^\perp = \bigoplus_{1 \leq i \leq m} X_i \otimes \mathbf{1}_{d_i}$.

³The asymptotic notation used here implicitly assumes a family of groups Γ_n and degrees k_n with $n \rightarrow \infty$; we dropped the indexing for simplicity. Note, however, that our results are nonasymptotic; asymptotic statements are given only to clarify their qualitative features.

As in the proof of Theorem 3.8, we can compute using Lemma 3.5

$$\mathbf{E}[X_i] = 0, \quad \sigma(X_i)^2 \leq 2k \left(1 + \frac{1}{d_i}\right), \quad \sigma_*(X_i)^2 \leq v(X_i)^2 \leq \frac{4k}{d_i}, \quad R(X_i) \leq 2$$

for $1 \leq i \leq m$. Thus Corollary 2.17 yields

$$\mathbf{P}\left[\|X_i\| \geq \left(1 + C \frac{(\log d_i)^{\frac{3}{4}}}{d_i^{\frac{1}{4}}} + C \frac{t^{\frac{1}{2}}}{d_i^{\frac{1}{2}}} + C \frac{t^{\frac{2}{3}}}{k^{\frac{1}{6}}} + C \frac{t}{k^{\frac{1}{2}}}\right) 2\sqrt{2k}\right] \leq 4d_i e^{-t}$$

for all $1 \leq i \leq m$ and $t \geq 0$. Choosing $t = 2\log(i+1) + (a+3)\log d_i$ yields

$$\mathbf{P}\left[\|X_i\| \geq \left(1 + C\alpha(\Gamma) + C \frac{(\log d_1)^{\frac{3}{4}}}{d_1^{\frac{1}{4}}} + C \frac{(\log |\Gamma|)^{\frac{2}{3}}}{k^{\frac{1}{6}}} + C \frac{\log |\Gamma|}{k^{\frac{1}{2}}}\right) 2\sqrt{2k}\right] \leq \frac{d_1^{-a}}{(i+1)^2}$$

for all $1 \leq i \leq m$, where C depends only on a . (Here we used that $t \leq (a+5)\log |\Gamma|$ as $d_i \leq |\Gamma|$ and $m+1 \leq |\Gamma|$.) Using $\|X^\perp\| = \max_{1 \leq i \leq m} \|X_i\|$, applying a union bound, and noting that $\sum_{i=1}^{\infty} (i+1)^{-2} < 1$ concludes the proof. \square

The parameter $\alpha(\Gamma)$ in Theorem 3.10 controls the growth rate of the dimensions of the irreducible representations of Γ . The condition $\alpha(\Gamma) = o(1)$ holds as soon as the irreducible representations are sufficiently high-dimensional. This condition is satisfied in many examples. For example, the following result is a slightly stronger form of [12, Lemma 9]; we include the proof for completeness.

Lemma 3.11. *For any sequence Γ_n of nonabelian finite simple groups such that $|\Gamma_n| \rightarrow \infty$, we have $\alpha(\Gamma_n) \rightarrow 0$.*

Proof. The nonabelian finite simple groups are classified [50, §5.1] into 6 families of classical simple groups, 10 families of exceptional simple groups, the alternating groups, and a finite number of sporadic groups. As $|\Gamma_n| \rightarrow \infty$, the sporadic groups are irrelevant. In the following, we fix a non-sporadic finite simple group with $d_1 \leq \dots \leq d_m$ ($m+1 \leq |\Gamma|$) defined as in Theorem 3.10.

If Γ is a classical or exceptional simple group, [50, Tables 5.1.A–B and 5.3.A] yield $\log |\Gamma| \asymp r^2 \log q$ and $d_1 \gtrsim q^{cr}$ for some $r \in \mathbb{N}$ and prime power q , where c is a universal constant. Thus $\alpha(\Gamma)^2 \leq \frac{\log |\Gamma|}{d_1} \lesssim \frac{(\log q^{cr})^2}{q^{cr}} = o(1)$ as $|\Gamma| \rightarrow \infty$.

Now let $\Gamma = \text{Alt}(r)$ be an alternating group with $r \geq 9$; then $\log |\Gamma| \asymp r \log r$, and it follows from [45, §5.1] and [69, Result 2] that $d_1 = r-1$ and $d_2 \geq cr^2$ for a universal constant c . Thus $\alpha(\Gamma)^2 \leq \max\left(\frac{\log 2}{d_1}, \frac{\log |\Gamma|}{d_2}\right) = o(1)$ as $|\Gamma| \rightarrow \infty$. \square

Theorem 3.10 therefore implies that for nonabelian finite simple groups, the Cayley graph defined by choosing $k \gg (\log |\Gamma|)^4$ random generators is nearly Ramanujan with high probability. When we are in addition in the domain of validity of the Alon-Boppana theorem, that is, when $\log k \ll \log |\Gamma|$ (cf. Lemma 3.7), it follows that these random Cayley graphs are optimal expanders.

The formulation of Theorem 3.10 was inspired by [12], where a variant of the Gaussian model G associated to X was introduced on an ad-hoc basis to illustrate certain subtleties in the formulation of matrix concentration inequalities [9, §8.1]. The key point here, however, is that the universality principles of this paper make random matrices of this kind appear in a fundamental manner in the study of the expansion properties of random Cayley graphs.

Remark 3.12. To achieve a sharp bound, Theorem 3.10 requires at least that the smallest dimension d_1 of a nontrivial irreducible representation diverges; that is, Theorem 3.10 is concerned with quasirandom groups in the sense of [46]. This condition also plays a key role in deep results on expansion in finite simple groups of Lie type that were pioneered by Bourgain and Gamburd [23, 24]. In contrast to Theorem 3.10, the latter results require only a bounded number of random generators but do not achieve the near-Ramanujan property of the associated Cayley graphs. Whether both properties can be achieved simultaneously is a long-standing question, see [70] for further discussion and numerical evidence.

It is clear that $d_1 \rightarrow \infty$ is also necessary to obtain an optimal expander with high probability. For example, if $\Gamma = S_d$ is the symmetric group, $d_1 = 1$ corresponds to the sign representation, and the 1×1 block X_1 in the proof of Theorem 3.10 equals twice the sum of k i.i.d. symmetric Bernoulli variables. Thus $\lambda_2(X) \geq \|X_1\|$ already exceeds, say, $3\sqrt{2k-1}$ with constant probability. A similar argument applies to any sequence of groups for which $d_1 \not\rightarrow \infty$. However, in this situation it is still possible to obtain $\lambda_2(X) \leq (1+o(1))2\sqrt{2k-1}$ with constant probability as long as the number of low-dimensional irreducible representations is bounded. Conditions for this to hold follow along the same lines as in Theorem 3.10.

3.2.4. Random lifts. For an m -regular graph, the Alon-Boppana lower bound on the second eigenvalue arises from the fact that $2\sqrt{m-1}$ is the spectral radius of the infinite m -regular tree. This suggests that an analogue of Lemma 3.7 for a *non-regular* graph H should lower bound its second eigenvalue by the spectral radius $\varrho(\hat{H})$ of its universal covering tree \hat{H} . This is captured, at least qualitatively, by [48, Theorem 6.6]. A non-regular graph H may thus be viewed as an optimal expander if its second eigenvalue is bounded by $(1+o(1))\varrho(\hat{H})$ [48, §6].

Amit and Linial [3] and Friedman [42] proposed a model of random graphs that is designed to achieve such optimal expansion properties. Given any base graph $H = ([d], E_H)$ with d vertices, its *random n -lift* $H^{(n)} = ([d] \times [n], E_{H^{(n)}})$ is obtained by duplicating each vertex and edge of the base graph n times, and randomly scrambling the duplicate edges among the duplicate vertices. That is, for each $e \in E_H$ with $e = (i, j)$, $i \leq j$, we construct $e_k \in E_{H^{(n)}}$, $k = 1, \dots, n$ with $e_k = ((i, k), (j, \sigma_e(k)))$, where σ_e is a random permutation that is chosen independently for each $e \in E_H$. The adjacency matrix $X^{(n)}$ of $H^{(n)}$ is

$$X^{(n)} = \sum_{e \in E_H} (A_e \otimes \Pi_e^{(n)} + A_e^* \otimes \Pi_e^{(n)*}),$$

where $\Pi_e^{(n)}$ are i.i.d. uniformly distributed $n \times n$ random permutation matrices and A_e are the $d \times d$ matrices $A_e = e_i e_j^*$ for $e = (i, j)$, $i \leq j$.

It is important to note that for every n , the restriction of $X^{(n)}$ to $\mathbb{C}^d \otimes \mathbb{C}1$ coincides with the adjacency matrix $X^{(1)}$ of H . Thus every eigenvalue of H is also an eigenvalue of $H^{(n)}$. The *new* eigenvalues that are introduced by the random lift are the eigenvalues of $X^{(n)\perp}$, the restriction of $X^{(n)}$ to $\mathbb{C}^d \otimes 1^\perp$. The long-standing conjecture that $\|X^{(n)\perp}\| \leq (1+o(1))\varrho(\hat{H})$ as $n \rightarrow \infty$ for fixed H was proved by Bordenave and Collins in [20]. This shows that random n -lifts are optimal expanders provided the base graph is an optimal expander.

As in the case of random regular graphs, however, it is far from clear whether this phenomenon persists if one considers random n -lifts of an unbounded sequence of base graphs H_n . The best bound to date [21, Theorem 1.4] is restricted to n -lifts of

graphs H with $|E_H| \ll \frac{\log n}{(\log \log n)^2}$ edges. The following result addresses the complementary regime where the maximal degree of H grows at least polylogarithmically in the number of vertices nd of its n -lift $H^{(n)}$.

Theorem 3.13. *Let $H = ([d], E_H)$ be an (undirected, not necessarily simple) graph without self-loops. Denote by $D(H)$ the maximal degree of a vertex of H and by $M(H)$ the maximal multiplicity of an edge of H . Then for every $a > 0$, there is a constant $C > 0$ depending only on a so that the new eigenvalues of $H^{(n)}$ satisfy*

$$\|X^{(n)\perp}\| \leq \left(1 + C \frac{M(H)^{\frac{1}{4}}}{n^{\frac{1}{4}}} \frac{(\log nd)^{\frac{3}{4}}}{D(H)^{\frac{1}{4}}} + C \frac{(\log nd)^{\frac{2}{3}}}{D(H)^{\frac{1}{6}}} + C \frac{\log nd}{D(H)^{\frac{1}{2}}}\right) \varrho(\hat{H})$$

with probability at least $1 - (nd)^{-a}$. In particular, $\|X^{(n)\perp}\| \leq (1 + o(1))\varrho(\hat{H})$ with probability $1 - o(1)$ whenever $(\log nd)^4 = o(D(H))$ and $M(H) = O(n)$.

A surprising aspect of Theorem 3.13 is that when H is a simple graph and $D(H) \gg (\log d)^4$, the conclusion holds already for $n = 2$, that is, for random 2-lifts. This is stark contrast to the bounded degree case, where one must in general let $n \rightarrow \infty$ to achieve an $(1 + o(1))\varrho(\hat{H})$ upper bound. On the other hand, when $n \rightarrow \infty$, a quantitative Alon-Boppana type theorem of [21, Theorem 1.7] shows that there is a broad range of parameters where Theorem 3.13 yields the smallest possible new eigenvalues among all (not necessarily random) n -lifts.

Remark 3.14. The assumption that H has no self-loops was made for simplicity. The proof of Theorem 3.13 will allow for self-loops, but in this case we must let $n \rightarrow \infty$ to achieve a $(1 + o(1))\varrho(\hat{H})$ bound. We already discussed a special case of this setting: when H is the graph with 1 vertex and k self-loops, $H^{(n)}$ coincides with the permutation model of random regular graphs of section 3.2.2.

Remark 3.15. When H is a simple m -regular graph (for which $\varrho(\hat{H}) = 2\sqrt{m-1}$), a result along the lines of Theorem 3.13 can be obtained in a much simpler manner by comparing the norm of X^\perp to that of a Wigner matrix [13, 11]. The primary interest of Theorem 3.13 is that it yields the correct upper bound for general H .

The proof of Theorem 3.13 is given in section 9.1. Let however briefly outline the argument. It is a basic fact (see, e.g., [20]) that $\varrho(\hat{H})$ may be computed as

$$\varrho(\hat{H}) = \left\| \sum_{e \in E_H} (A_e \otimes \lambda(g_e) + A_e^* \otimes \lambda(g_e)^*) \right\|, \quad (3.3)$$

where $(g_e)_{e \in E_H}$ are the free generators of the free group $F_{|E_H|}$ and λ denotes the left-regular representation. On the other hand, Theorem 2.16 enables us to bound the norm of $X^{(n)\perp}$ by that of $X_{\text{free}}^{(n)\perp}$. This almost yields the desired conclusion, except that in $X_{\text{free}}^{(n)\perp}$ the free generators $\lambda(g_i)$ are replaced by certain deformed circular variables. While in general $\|X_{\text{free}}^{(n)\perp}\| > \varrho(\hat{H})$, we will show these quantities coincide to leading order when $D(H) \rightarrow \infty$, concluding the proof.

3.3. Matrix concentration inequalities for smallest singular values. The theory behind classical matrix concentration inequalities [77] is inherently limited to the extreme eigenvalues of random matrices. In contrast, our results control the entire spectrum. This makes it possible, for example, to obtain matrix concentration inequalities for the smallest singular value of non-self-adjoint random matrices.

Such results are fundamentally outside the scope of classical matrix concentration inequalities for general models of the form (2.1) (unless one imposes special structure, see, e.g., [77, §5.2.1] for an example).

We presently state a general result of this kind. In the following, we define the smallest singular value of Y as $s_{\min}(Y) := \inf \text{sp}(|Y|)$.

Theorem 3.16. *Let $Y = Z_0 + \sum_{i=1}^n Z_i$, where Z_0 is a nonrandom $d \times m$ matrix and Z_1, \dots, Z_n are independent centered $d \times m$ random matrices, with $d \geq m$. Then*

$$\begin{aligned} \mathbf{P}[s_{\min}(Y) \leq s_{\min}(Y_{\text{free}}) - C\{v(Y)^{\frac{1}{2}}\sigma(Y)^{\frac{1}{2}}(\log d)^{\frac{3}{4}} \\ - \sigma_*(Y)t - R(Y)^{\frac{1}{3}}\sigma(Y)^{\frac{2}{3}}t^{\frac{2}{3}} - R(Y)t\}] \leq de^{-t} \end{aligned}$$

for all $t \geq 0$, where C is universal constant. Here $\sigma(Y), \sigma_*(Y), v(Y), R(Y)$ are defined as in Corollary 2.17, and Y_{free} is the $d \times m$ matrix so that the real and imaginary parts of its entries is a semicircular family with the same mean and covariance as the real and imaginary parts of the entries of Y .

The proof of Theorem 3.16 will be given in section 9.2 below. A variant of Theorem 3.16 for unbounded random matrices can also be deduced along the same lines, by using Theorem 2.8 instead of Theorem 2.6 in the proof.

In the case that $\mathbf{E}[Y] = 0$, a simple “user-friendly” bound

$$s_{\min}(Y_{\text{free}}) \geq s_{\min}(\mathbf{E}Y^*Y)^{\frac{1}{2}} - \|\mathbf{E}YY^*\|^{\frac{1}{2}} \quad (3.4)$$

was obtained in [9, Lemma 3.15]. This bound gives rise to very simple explicit estimates, but may be far from sharp for nonhomogeneous random matrices. In this case, the quantity $s_{\min}(Y_{\text{free}})$ can also be computed exactly using an explicit variational formula (in the spirit of [54]) that is obtained in [64].

Example 3.17 (Bipartite random graphs). Consider a bipartite random graph with vertex set $[d] \sqcup [m]$ ($d \geq m$) in which each edge (i, j) with $i \in [d], j \in [m]$ is included independently with probability p_{ij} . This is a nonhomogeneous and bipartite analogue of the classical Erdős-Rényi model. The adjacency matrix A of this graph is the $d \times m$ matrix with independent entries $A_{ij} \sim \text{Bern}(p_{ij})$.

A basic question of interest in this setting (cf. [40] and the references therein) is to bound the largest and smallest singular values of $A - \mathbf{E}A$.

Corollary 3.18. *Denote by $\rho := \min_j \sum_i p_{ij}(1 - p_{ij})$, $\gamma := \max_i \sum_j p_{ij}(1 - p_{ij})$, and $k := \max \{ \max_i \sum_j p_{ij}(1 - p_{ij}), \max_j \sum_i p_{ij}(1 - p_{ij}) \}$. Then for every $a > 0$, there is a constant $C > 0$ that depends only on a so that*

$$\begin{aligned} \|A - \mathbf{E}A\| &\leq \sqrt{\rho} + \sqrt{\gamma} + Ck^{\frac{1}{3}}(\log d)^{\frac{2}{3}}, \\ s_{\min}(A - \mathbf{E}A) &\geq \sqrt{\rho} - \sqrt{\gamma} - Ck^{\frac{1}{3}}(\log d)^{\frac{2}{3}} \end{aligned}$$

with probability at least $1 - d^{-a}$, provided that $k \geq \log d$.

Proof. We can express $Y := A - \mathbf{E}A$ as $Y = \sum_{ij} Z_{ij}$ where $Z_{ij} = Y_{ij}e_i e_j^*$ are independent centered random matrices. Then we readily compute $s_{\min}(\mathbf{E}Y^*Y) = \rho$, $\|\mathbf{E}YY^*\| = \gamma$, $\sigma^2(Y) \leq k$, $\sigma_*(Y)^2 \leq v(Y)^2 \leq \max_{ij} p_{ij}(1 - p_{ij})$, and $R(Y) \leq 1$. The conclusion now follows directly from Corollary 2.17, Theorem 3.16, and (3.4). \square

The simplest example of this result is the homogeneous case where $p_{ij} = p < 1$. In this case, the above bounds reduce to

$$1 - \sqrt{\frac{m}{d}} - \frac{C(\log d)^{\frac{2}{3}}}{(dp)^{\frac{1}{6}}} \leq \frac{s_{\min}(A - \mathbf{E}A)}{\sqrt{dp(1-p)}} \leq \frac{\|A - \mathbf{E}A\|}{\sqrt{dp(1-p)}} \leq 1 + \sqrt{\frac{m}{d}} + \frac{C(\log d)^{\frac{2}{3}}}{(dp)^{\frac{1}{6}}}.$$

This shows that the classical Bai-Yin law [7], which applies to dense graphs with constant $0 < p, \frac{m}{d} < 1$ as $d \rightarrow \infty$, remains valid for sparse graphs with average degree $dp \gg (\log d)^4$. In this homogeneous setting, the results of [40] establish the same conclusion in the slightly larger range $dp \gg \log d$. However, for nonhomogeneous graphs, the best known bounds due to [40] are already weaker than those of Corollary 3.18 to leading order, cf. [40, Remark 2.6].

On the other hand, we have formulated the simple bounds of Corollary 3.18 for sake of illustration only: the same proof yields bounds in which $\sqrt{\rho} + \sqrt{\gamma}$ and $\sqrt{\rho} - \sqrt{\gamma}$ are replaced by the optimal leading-order terms $\|Y_{\text{free}}\|$ and $s_{\min}(Y_{\text{free}})$, respectively (where $Y = A - \mathbf{E}A$), which can be computed in terms of explicit variational principles [54, 64]. In other words, in contrast to previous results, we obtain sharp Bai-Yin laws for sparse nonhomogeneous random matrices.

Remark 3.19. More generally, Theorem 3.16 may be viewed as a nonasymptotic, nonhomogeneous Bai-Yin law that is sharp to leading order. It should be emphasized, however, that it can only locate the smallest singular value of Y near that of its noncommutative model Y_{free} . In particular, Theorem 3.16 sheds no light on the invertibility of Y when $s_{\min}(Y_{\text{free}}) = 0$, as is the case, e.g., for square matrices with i.i.d. entries. The latter question is of a fundamentally different nature, which is presently understood for nonhomogeneous models only under restrictive assumptions [72, 35] (see, however, [76] for significant recent progress in this direction).

3.4. Sample covariance matrices. Let Y_1, \dots, Y_n be independent, centered random vectors in \mathbb{R}^d . The $d \times d$ random matrix

$$S = \sum_{i=1}^n Y_i Y_i^* \tag{3.5}$$

is called the (nonhomogeneous) *sample covariance matrix* associated to the data Y_1, \dots, Y_n . Equivalently, we may express $S = YY^*$, where

$$Y = \sum_{i=1}^n Y_i e_i^* \tag{3.6}$$

is the $d \times n$ random matrix with independent columns Y_1, \dots, Y_n . In the classical setting where Y_1, \dots, Y_n are identically distributed, $\frac{1}{n}\mathbf{E}S$ is the covariance matrix of Y_i , and $\frac{1}{n}S$ may be viewed as a statistical estimator of this covariance matrix. A central problem is then to bound the deviation $\frac{1}{n}\|S - \mathbf{E}S\|$ of the estimated covariance matrix from the actual covariance matrix. Here we allow for a more general nonhomogeneous situation where the data Y_1, \dots, Y_n need not be identically distributed, which is of independent interest (see, e.g., [25]).

From the viewpoint of this paper, sample covariance matrices may be approached in two different ways: we may either view S itself as a model of the form (2.1), or we may view Y as a model of the form (2.1). These two interpretations give rise to distinct universality principles. As we will see below, neither approach subsumes the other: they control the behavior of S in complementary regimes.

For simplicity, we focus in this section on “user-friendly” explicit bounds on the expected deviation $\mathbf{E}\|S - \mathbf{E}S\|$; sharp bounds in terms of S_{free} and Y_{free} , as well as high-probability bounds, may be obtained analogously.

3.4.1. Gaussian sample covariance matrices. In this section we consider Gaussian sample covariance matrices, that is, (3.5) where Y_1, \dots, Y_n are independent Gaussian random vectors $Y_i \sim N(0, \Sigma_i)$. In this case, Y is a Gaussian random matrix, to which the Gaussian theory of [9] can be applied.

Theorem 3.20 (Gaussian bound). *Let $Y_i \sim N(0, \Sigma_i)$. Then we have*

$$\begin{aligned} \mathbf{E}\|S - \mathbf{E}S\| \leq 2 \left\| \sum_{i=1}^n \text{Tr}[\Sigma_i] \Sigma_i \right\|^{\frac{1}{2}} + \max_{i \leq n} \text{Tr} \Sigma_i \\ + C \left(\left\| \sum_{i=1}^n \Sigma_i \right\| + \max_{i \leq n} \text{Tr} \Sigma_i \right)^{\frac{3}{4}} \max_{i \leq n} \|\Sigma_i\|^{\frac{1}{4}} \log^{\frac{3}{2}}(d+n). \end{aligned}$$

Proof. By [9, Lemma 3.8], we have $\sigma(Y)^2 = \|\sum_i \Sigma_i\| \vee \max_i \text{Tr} \Sigma_i$ and $v(Y)^2 = \max_i \|\Sigma_i\|$. As $v(Y) \leq \sigma(Y)$, [9, Theorem 3.11 and Proposition 3.12] yield

$$\mathbf{E}\|S - \mathbf{E}S\| \leq 2\|\mathbf{E}[Y \mathbf{E}[Y^* Y] Y^*]\|^{\frac{1}{2}} + \|\mathbf{E}Y^* Y\| + C\sigma(Y)^{\frac{3}{2}}v(Y)^{\frac{1}{2}}\log^{\frac{3}{2}}(d+n)$$

for a universal constant C . The leading terms are readily computed. \square

On the other hand, even when Y is Gaussian, we may view S as a non-Gaussian random matrix of the form (2.1) with $Z_i = Y_i Y_i^*$, to which the universality principles of this paper may be applied. For example, applying Theorem 2.9 yields the following bound, whose proof is given in section 9.3.1.

Theorem 3.21 (S -universality bound). *Let $Y_i \sim N(0, \Sigma_i)$. Then for any $\varepsilon \in (0, 1]$*

$$\mathbf{E}\|S - \mathbf{E}S\| \leq (1 + \varepsilon) 2 \left\| \sum_{i=1}^n \text{Tr}[\Sigma_i] \Sigma_i \right\|^{\frac{1}{2}} + \frac{C}{\varepsilon^3} \left(\left\| \sum_{i=1}^n \Sigma_i^2 \right\|^{\frac{1}{2}} + \max_{i \leq n} \text{Tr} \Sigma_i \right) \log^3(d+n).$$

The fundamental distinction between these bounds is that Theorem 3.21 models S by the noncommutative model S_{free} , while Theorem 3.20 models $S = YY^*$ by the noncommutative model $Y_{\text{free}}Y_{\text{free}}^*$. Somewhat surprisingly, these distinct interpretations have complementary (partially overlapping) domains of validity, which is already illustrated by the simplest possible example.

Example 3.22. Suppose that Y_1, \dots, Y_n are i.i.d. standard Gaussian vectors in \mathbb{R}^d , that is, $\Sigma_i = \mathbf{1}$ for all i . In this setting, the classical Bai-Yin law [7] implies that $\mathbf{E}\|S - \mathbf{E}S\| = (1 + o(1))(2\sqrt{nd} + d)$ when $n, d \rightarrow \infty$ with $\frac{n}{d}$ fixed.

Let us now verify what Theorems 3.20 and 3.21 yield for this model.

- First, note that the Gaussian bound of Theorem 3.20 yields

$$\mathbf{E}\|S - \mathbf{E}S\| \leq 2\sqrt{nd} + d + C(n + d)^{\frac{3}{4}} \log^{\frac{3}{2}}(d+n).$$

Here the leading terms agree with the Bai-Yin law, but the error term is of smaller order if and only if $n \rightarrow \infty$ and $d \gg n^{\frac{1}{2}}(\log n)^3$. This includes the $n \propto d$ setting of the classical Bai-Yin law, but excludes cases where n is much larger than d .

- On the other hand, the universality bound of Theorem 3.21 yields

$$\mathbf{E}\|S - \mathbf{E}S\| \leq (1 + \varepsilon) 2\sqrt{nd} + C\varepsilon^{-3}(\sqrt{n} + d)\log^3(d + n).$$

In this bound, the leading term agrees with the Bai-Yin law only when $n \gg d$, and the error term is of smaller order if and only if $(\log n)^6 \ll d \ll \frac{n}{(\log n)^6}$. This regime excludes the setting of the classical Bai-Yin law, but covers precisely the situation that the Gaussian bound fails to capture.

Combining the above bounds yields $\mathbf{E}\|S - \mathbf{E}S\| \leq (1 + o(1))(2\sqrt{nd} + d)$ whenever $n \rightarrow \infty$ and $d \gg (\log n)^6$. This very general conclusion hides the fact that two complementary approaches were used to capture the large d and large n regimes.

The homogeneous setting of Example 3.22 is special in that $\Sigma_i = \mathbf{1}$ implies $\|S - \mathbf{E}S\| = \|YY^* - n\mathbf{1}\| = \max\{\|Y\|^2 - n, n - \text{smin}(Y^*)^2\}$, so that this case can also be approached using the methods of section 3.3. Such a reduction fails, however, for nonhomogeneous sample covariance matrices. In the general setting, Theorems 3.20 and 3.21 control the behavior of Gaussian sample covariance matrices in complementary regimes that together span a wide range of parameters.

Remark 3.23. Let us note for completeness that Gaussian sample covariance matrices always satisfy $\mathbf{E}\|S - \mathbf{E}S\| \gtrsim \|\sum_i \text{Tr}[\Sigma_i]\Sigma_i\|^{1/2} + \max_i \text{Tr} \Sigma_i$, cf. section 9.3.2. Thus the leading terms in Theorems 3.20 and 3.21 are also lower bounds on $\mathbf{E}\|S - \mathbf{E}S\|$ up to a universal constant. On the other hand, the proofs of these results can even capture the sharp leading term predicted by free probability.

3.4.2. Non-Gaussian models. We now consider more general models where the data Y_1, \dots, Y_n may be non-Gaussian. This makes little difference in the setting of Theorem 3.21: here we already interpreted S itself as a non-Gaussian matrix, and applied the universality principle to compare it with its Gaussian model (the assumption that Y is Gaussian was not used in a fundamental way in the proof).

On the other hand, in order to extend Theorem 3.20 to the non-Gaussian setting, we must compare $S = YY^*$ with HH^* , where H is the Gaussian model associated to Y . Such a comparison can be deduced from our universality principles by means of a linearization argument as in [9, §3.3]. Note that the setting of the following result is far more general than that of the model (3.5).

Theorem 3.24 (Y -universality). *Let $Y = Z_0 + \sum_{i=1}^n Z_i$ be a $d \times m$ random matrix defined as in Theorem 3.16, and let H be the $d \times m$ random matrix so that the real and imaginary parts of its entries are jointly Gaussian with the same mean and covariance as the real and imaginary parts of the entries of Y . Then*

$$|\mathbf{E}\|YY^* - \mathbf{E}YY^*\| - \mathbf{E}\|HH^* - \mathbf{E}HH^*\|\| \lesssim \delta \mathbf{E}\|H\| + \delta^2$$

with

$$\delta = \sigma_*(Y) \log^{1/2}(d + m) + R(Y)^{1/3} \sigma(Y)^{2/3} \log^{2/3}(d + m) + R(Y) \log(d + m).$$

The proof of Theorem 3.24 is in section 9.3.3. We state the result for bounded random matrices for simplicity; similar results for unbounded matrices are obtained by using Theorem 2.8 rather than Theorem 2.6 in the proof.

As Y is already expressed as a sum of independent random matrices in (3.6), it is tempting to attempt to apply Theorem 3.24 with $Z_i = Y_i e_i^*$. Unfortunately, as is illustrated in the following example, such a straightforward application of the universality principle fails to yield meaningful results. The reason is simple: (3.6)

captures only the independence of the data Y_1, \dots, Y_n , but independent data alone does not suffice to ensure universality of sample covariance matrices.

Example 3.25. Let us revisit the Bai-Yin setting of Example 3.22 in the non-Gaussian case, that is, we now assume only that Y_1, \dots, Y_n are i.i.d. centered random vectors with unit covariance matrix $\Sigma_i = \mathbf{1}$ for all i .

In this setting, the Gaussian model H associated to Y in Theorem 3.24 is precisely the $d \times n$ random matrix with i.i.d. standard Gaussian entries. In particular, the classical Bai-Yin law [7] implies that $\mathbf{E}\|HH^* - \mathbf{E}HH^*\| = (1 + o(1))(2\sqrt{\gamma} + 1)d$ when $n, d \rightarrow \infty$ with $\frac{n}{d} = \gamma$ fixed. On the other hand, if we write $Y = \sum_{i=1}^n Z_i$ with $Z_i = Y_i e_i^*$, we clearly have $R(Y)^2 \geq \max_i \mathbf{E}\|Z_i\|^2 = d$, so that

$$\delta \mathbf{E}\|H\| + \delta^2 \gtrsim \frac{(\log d)^2}{2\sqrt{\gamma} + 1} \mathbf{E}\|HH^* - \mathbf{E}HH^*\|.$$

Thus Theorem 3.24 cannot yield universality of the Bai-Yin law in this manner, as its error term is always of larger order than the Gaussian quantity of interest.

The problem that arises here is not an inefficiency of our universality principles, however, but is a genuine phenomenon: at the present level of generality, universality of the Bai-Yin law is simply false. For example, let $Y_i = \sqrt{d} \varepsilon_i e_{I_i}$, where $\varepsilon_1, \dots, \varepsilon_n$ are i.i.d. random signs and I_1, \dots, I_n are i.i.d. uniformly distributed variables on $[d]$. Then Y_1, \dots, Y_n are i.i.d. with zero mean and unit covariance. However, as YY^* is diagonal with multinomially distributed diagonal entries, we have [68]

$$\mathbf{E}\|YY^* - \mathbf{E}YY^*\| = (1 + o(1)) \frac{d \log d}{\log(\gamma^{-1} \log d)} \gg \mathbf{E}\|HH^* - \mathbf{E}HH^*\|$$

when $n, d \rightarrow \infty$ with $\frac{n}{d} = \gamma$ fixed. Thus universality of the Bai-Yin law fails.

Example 3.25 illustrates that even in the classical setting of Bai-Yin law, some additional assumption on the distribution of the vectors Y_i is needed to achieve universality. The additional assumption that would enable us to apply Theorem 3.24 is that each Y_i is itself a sum of independent random vectors of sufficiently small norm. This situation arises naturally in random matrix theory: we presently provide one example of such a model, where the above results yield a considerable improvement on the best known nonasymptotic bounds.

Example 3.26 (Product of random and deterministic matrices). Let A be a $N \times n$ random matrix with independent real entries that have zero mean and unit variance, and let B be a $d \times N$ nonrandom matrix. We are interested in the sample covariance matrix $S = YY^*$ where $Y = BA$. The difficulty of analyzing such models is that even though A has independent entries, the matrix Y generally has highly dependent entries which renders many standard tools of nonasymptotic random matrix theory inapplicable. Here we obtain the following.

Theorem 3.27. *Let $S = YY^*$ with $Y = BA$, where A is a $N \times n$ random matrix with $\mathbf{E}[A_{ij}] = 0$, $\text{Var}(A_{ij}) = 1$, and $\|A_{ij}\|_\infty \leq \alpha$, and let B be a $d \times N$ nonrandom matrix. Assume that $\alpha \leq \sqrt{n}$ and $\|B\|_{\text{HS}} \geq \alpha\|B\|$. Then we have*

$$\begin{aligned} \mathbf{E}\|S - \mathbf{E}S\| &\leq \\ &\left(1 + C \left\{ \left(\frac{\alpha}{\sqrt{n}} \right)^{\frac{1}{15}} + \left(\frac{\alpha\|B\|}{\|B\|_{\text{HS}}} \right)^{\frac{1}{4}} \right\} \log^3(d+n) \right) (2\|B\|_{\text{HS}}\|B\|\sqrt{n} + \|B\|_{\text{HS}}^2), \end{aligned}$$

where C is a universal constant, $\mathbf{E}S = nBB^*$, and $\|M\|_{\text{HS}}^2 := \text{Tr}|M|^2$.

The proof is given in section 9.3.4. While we have formulated a single bound, it should be emphasized that the proof is once again a combination of two distinct universality principles. (We have made no effort to optimize the exponents in the lower-order terms, which are not expected to be optimal.)

It is instructive to compare Theorem 3.27 with previous nonasymptotic results in this setting, which establish bounds analogous to Theorem 3.27 up to a multiplicative factor that depends on the moments of A_{ij} : see [85] and the references therein for subgaussian or subexponential entries, and [82] for a slightly weaker result for entries with bounded fourth moment. The advantage of Theorem 3.27 is twofold. First, Theorem 3.27 reproduces the correct leading-order behavior in the Bai-Yin law (i.e., the case $N = d, B = \mathbf{1}$), while previous results lose at least a multiplicative factor. Second, Theorem 3.27 is applicable to sparse random matrices, while previous bounds are fundamentally inefficient in the sparse setting.

To illustrate this point, suppose that A_{ij} are symmetric Bernoulli variables with $\mathbf{P}[A_{ij} = 0] = 1 - p$ and $\mathbf{P}[A_{ij} = p^{-\frac{1}{2}}] = \frac{p}{2}$. Then Theorem 3.27 yields

$$\mathbf{E}\|S - \mathbf{E}S\| \leq (1 + o(1)) (2\|B\|_{\text{HS}}\|B\|\sqrt{n} + \|B\|_{\text{HS}}^2) \quad \text{for } p \gg \frac{\log^\beta(d + n)}{n \wedge r}$$

for a suitable β , where $r = \|B\|_{\text{HS}}^2\|B\|^{-2}$ is the effective rank of B . On the other hand, as $\mathbf{E}|A_{ij}|^4 = \frac{1}{p}$ diverges as soon as $p \rightarrow 0$, the results of [82, 85] fail to achieve even the correct order of magnitude of the norm in the sparse setting.

Remark 3.28. We have formulated Theorem 3.27 for the case that the entries A_{ij} are uniformly bounded, while prior results [82, 85] also consider unbounded entries. However, our restriction to bounded entries was made for simplicity of exposition only, and is not a fundamental restriction of the proof of Theorem 3.27. A related inequality for the unbounded case may be found in Remark 9.16.

While Example 3.26 provides a natural model where each Y_i is itself a sum of independent random vectors, such an assumption can be restrictive for more general models of sample covariance matrices. On the other hand, in the special (homogeneous) setting of the Bai-Yin law, it was shown in [31] that a much weaker assumption suffices to achieve universal behavior: in this case one need only assume that each Y_i satisfies certain concentration of measure properties, which rules out the counterexample of Example 3.25. In forthcoming work [63], the universality principles of this paper are further refined to capture such concentration assumptions for general (nonhomogeneous) sample covariance matrices.

More generally, the above considerations highlight the broader question whether the universality principles of this paper extend to random matrices that admit more general dependence structures than can be captured by the model (2.1); such principles could enable the analysis of natural models that are outside the scope of this paper. Progress in this direction may be found in [63, 81].

3.5. Strong asymptotic freeness. The celebrated asymptotic freeness theorem of Voiculescu [83] states that if X_1^N, \dots, X_m^N are independent $N \times N$ Wigner matrices and s_1, \dots, s_m is a free semicircular family (i.e., a semicircular family as in Definition 2.2 with zero mean and unit covariance), then

$$\lim_{N \rightarrow \infty} \text{tr } p(X_1^N, \dots, X_m^N) = \tau(p(s_1, \dots, s_m)) \quad \text{a.s.}$$

for every noncommutative polynomial p . This makes it possible to compute the limiting spectral distributions of polynomials Wigner matrices using tools of free probability; see, e.g., [5, Chapter 5]. That the convergence holds also in norm

$$\lim_{N \rightarrow \infty} \|p(X_1^N, \dots, X_m^N)\| = \|p(s_1, \dots, s_m)\| \quad \text{a.s.}$$

is a deep result of Haagerup and Thorbjørnsen [47], who proved it for GUE matrices. The latter strong asymptotic freeness property is of fundamental importance both to random matrices and in the theory of operator algebras.

The methods of [47] are rather delicate, and their extension even to random matrices with i.i.d. entries with bounded fourth moment requires considerable effort [4]. It was therefore long unclear whether the strong asymptotic freeness phenomenon could be expected to hold in the absence of strong symmetry assumptions. That this is indeed the case is a notable application of the sharp matrix concentration theory of [9], which made it possible to establish strong asymptotic freeness of an extremely general class of Gaussian random matrix models.

Here we extend the latter results to an even more general family of non-Gaussian random matrices. To this end, we must show that our universality principles for random matrices of the form (2.1) imply universality for polynomials of such matrices. In the following (asymptotic) result, whose proof is given in section 9.4, this is accomplished by a direct application of known linearization arguments [47, 38] that we use as a black box. However, while we do not develop this direction systematically in this paper, our methods can also be used to obtain nonasymptotic bounds for polynomials of random matrices: for example, Theorem 3.24 may be viewed as a result of this kind for a certain quadratic polynomial.

Theorem 3.29 (Strong asymptotic freeness). *Let s_1, \dots, s_m be a free semicircular family. For each $N \geq 1$, let H_1^N, \dots, H_m^N be independent self-adjoint random matrices of dimension $d_N \geq N$ defined by*

$$H_k^N = Z_{k0}^N + \sum_{i=1}^{M_N} Z_{ki}^N,$$

where Z_{k0}^N is a deterministic self-adjoint matrix and $Z_{k1}^N, \dots, Z_{kM_N}^N$ are independent self-adjoint random matrices with zero mean. Suppose that

$$\lim_{N \rightarrow \infty} \|\mathbf{E}[H_k^N]\| = \lim_{N \rightarrow \infty} \|\mathbf{E}[(H_k^N)^2] - \mathbf{1}\| = \lim_{N \rightarrow \infty} \bar{R}(H_k^N) = 0$$

and that

$$\lim_{N \rightarrow \infty} (\log d_N)^{\frac{3}{2}} v(H_k^N) = 0, \quad \lim_{N \rightarrow \infty} (\log d_N)^2 \max_{1 \leq i \leq M_N} \|Z_{ki}^N\| = 0 \quad \text{a.s.}$$

for every $1 \leq k \leq m$. Then

$$\begin{aligned} \lim_{N \rightarrow \infty} \text{tr } p(H_1^N, \dots, H_m^N) &= \tau(p(s_1, \dots, s_m)) \quad \text{a.s.}, \\ \lim_{N \rightarrow \infty} \|p(H_1^N, \dots, H_m^N)\| &= \|p(s_1, \dots, s_m)\| \quad \text{a.s.} \end{aligned}$$

for every noncommutative polynomial p . Moreover, the analogous result holds if a.s. convergence is replaced by convergence in probability.

Theorem 3.29 applies to a large family of random matrices with non-Gaussian, nonhomogeneous, and dependent entries. In order to illustrate some characteristic features of this result, let us develop one example in more detail.

Example 3.30 (Sparse Wigner matrices). We consider matrices with a deterministic sparsity pattern, where all nonzero entries of the matrix are i.i.d. We emphasize that such random matrices may be highly nonhomogeneous.

Definition 3.31. Let $(\eta_{ij})_{1 \leq i \leq j < \infty}$ be i.i.d. real-valued random variables with zero mean and unit variance, and let $G = ([d], E)$ be a k -regular graph with d vertices. Then the (G, η) -sparse Wigner matrix is the $d \times d$ self-adjoint random matrix X with entries $X_{ij} = k^{-\frac{1}{2}} \eta_{ij} \mathbf{1}_{\{i,j\} \in E}$ for $1 \leq i \leq j \leq d$.

The proof of the following result is given in section 9.4.3.

Corollary 3.32. Let $(\eta_{rij})_{1 \leq r \leq m, 1 \leq i \leq j < \infty}$ be i.i.d. centered random variables with unit variance and $\mathbf{E}[|\eta_{kij}|^p] < \infty$ for some $p > 2$, and let G_N be a k_N -regular graph with $d_N \geq N$ vertices. Let H_r^N be the (G_N, η_r) -sparse Wigner matrix.

a. If $k_N \gg d_N^{\frac{2}{p-2}} (\log d_N)^{\frac{4p}{p-2}}$, then

$$\lim_{N \rightarrow \infty} \text{tr } p(H_1^N, \dots, H_m^N) = \tau(p(s_1, \dots, s_m)) \text{ in probability,}$$

$$\lim_{N \rightarrow \infty} \|p(H_1^N, \dots, H_m^N)\| = \|p(s_1, \dots, s_m)\| \text{ in probability}$$

for every noncommutative polynomial p . If the graphs $G_N = ([d_N], E_N)$ are increasing (i.e., $E_N \subseteq E_{N+1}$ for all N), the convergence also holds a.s.

b. If $k_N \ll d_N^{\frac{2}{p-2}} (\log d_N)^{-\frac{2p}{p-2}}$, then the conclusion of part a. must fail for some entry distribution satisfying the assumptions.

A fundamental phenomenon that is captured by this result is that strong asymptotic freeness requires a tradeoff between sparsity and integrability of the entries. For dense Wigner matrices $k_N = d_N$, we obtain strong asymptotic freeness as soon as the entries have $4 + \varepsilon$ moments for some $\varepsilon > 0$, as was previously shown in [4]. On the other hand, as we bound more moments, increasingly sparse random matrices can still achieve strong asymptotic freeness. This tradeoff is captured nearly optimally by Corollary 3.32, up to logarithmic factors.

In the opposite extreme, when the entries η_{rij} are uniformly bounded, it follows directly from Theorem 3.29 that strong asymptotic freeness holds (in the a.s. sense) as soon as $k_N \gg (\log d_N)^4$. By taking η_{rij} to be symmetric Bernoulli variables, this shows that one can construct $d \times d$ random matrices with independent entries that achieve strong asymptotic freeness using only $O(d \log^5 d)$ bits of randomness.

Remark 3.33. The sparse Wigner model of Example 3.30 is only one special case of the very general setting captured by Theorem 3.29, which also includes several of the examples that were discussed in the previous sections: e.g., random matrices defined by group representations as in section 3.2, or centered adjacency matrices of sparse Erdős-Rényi graphs. Such examples further extend the scope of the strong asymptotic freeness phenomenon beyond what was previously known.

3.6. Phase transitions in spiked models. A widely studied phenomenon in random matrix theory, which dates back to the work of Baik, Ben Arous and Péché [8], is that low-rank perturbations of random matrices (known as “spiked” models) give rise to phase transitions: small perturbations do not affect the limiting eigenvalue statistics, while large perturbations give rise to the appearance of outlier eigenvalues. Several closely related forms of this phenomenon have been investigated by

many authors; see, e.g., the survey [27]. For sake of illustration, we focus here on the following prototypical phenomenon of this kind.⁴

Theorem 3.34 (BBP transition for spiked GOE [17]). *Let G_d be a $d \times d$ self-adjoint random matrix whose entries $(G_{dij})_{i \geq j}$ are independent real Gaussian variables with mean 0 and variance $\frac{1+1_{i=j}}{d}$. Let A_d be a nonrandom $d \times d$ positive semidefinite matrix of rank r whose eigenvalues $\theta_1 \geq \dots \geq \theta_r > 0$ are independent of d .*

a. *We have for $1 \leq i \leq r$*

$$\lambda_i(A_d + G_d) \xrightarrow[d \rightarrow \infty]{a.s.} \begin{cases} \theta_i + \frac{1}{\theta_i} & \text{for } \theta_i > 1, \\ 2 & \text{for } \theta_i \leq 1, \end{cases}, \quad \lambda_{r+1}(A_d + G_d) \xrightarrow[d \rightarrow \infty]{a.s.} 2,$$

where $\lambda_1(M) \geq \dots \geq \lambda_d(M)$ are the eigenvalues of M .

b. *For every $1 \leq i, j \leq r$ such that $\theta_i > 1$ and $\theta_j \neq \theta_i$, we have*

$$\|P_i(A_d)v_i(A_d + G_d)\|^2 \xrightarrow[d \rightarrow \infty]{a.s.} 1 - \frac{1}{\theta_i^2}, \quad \|P_j(A_d)v_i(A_d + G_d)\|^2 \xrightarrow[d \rightarrow \infty]{a.s.} 0,$$

where $P_i(M)$ is the projection on the eigenspace of M associated to the eigenvalue $\lambda_i(M)$, and $v_i(M)$ is any unit norm eigenvector of M with eigenvalue $\lambda_i(M)$.

We aim to understand whether the phenomena described in Theorem 3.34 are universal: do the conclusions remain valid if the GOE matrix G_n is replaced by another random matrix H_d whose entries have the same mean and covariance? Previous results have extended Theorem 3.34 to the setting where H_d has i.i.d. entries above the diagonal under distributional assumptions that require at least some bounded moments of higher order, cf. [27] and the references therein. (Analogues of Theorem 3.34 are also known to hold for non-Gaussian homogeneous models where H_d is invariant under a symmetry group; such models are rather different in spirit from the kind of universality phenomena considered here.)

When applied to this setting, our universality principles can capture many new situations, including sparse and dependent models.

Theorem 3.35. *Let G_d, A_d be as in Theorem 3.34, and let H_d be any $d \times d$ self-adjoint real random matrix of the form (2.1) whose entries have the same mean and covariance as those of G_d . Suppose that $(\log d)^2 R(H_d) \rightarrow 0$ as $d \rightarrow \infty$. Then all the conclusions of Theorem 3.34 remain valid if G_d is replaced by H_d .*

The proof of this result is given in section 9.5. Let us however briefly outline the main ingredients of the proof. On the one hand, Theorem 2.6 shows that the eigenvalues of $A_d + H_d$ concentrate at the locations predicted by Theorem 3.34. On the other hand, for $\theta_i > 1$, let φ_i be a mollification of the indicator function of a small interval around $\theta_i + \frac{1}{\theta_i}$. Then $\varphi_i(A_d + H_d)$ coincides with high probability with the projection onto the linear span of the eigenvectors of $A_d + H_d$ whose eigenvalues concentrate at $\theta_i + \frac{1}{\theta_i}$. We can therefore apply the second part of Theorem 2.10 to establish universality of these eigenprojections.

To illustrate Theorem 3.35, we briefly discuss one simple example.

Example 3.36 (Planted clique in the permutation model). Let X_d be the adjacency matrix of a random $2k_d$ -regular graph with d vertices in the permutation model

⁴The assumption that A_d is positive semidefinite is made here exclusively to simplify the notation; any negative eigenvalues of A_d exhibit a completely analogous transition at $\theta_i = -1$.

defined in section 3.2.2, where $(\log d)^4 \ll k_d \ll d^2$. Choose a subset $E_d \subset [d]$ of vertices so that $|E_d| = (1 + o(1))\theta\sqrt{2k_d}$. Then $1_{E_d}1_{E_d}^* + X_d$ is the adjacency matrix of the random graph in which we planted a clique with vertices E_d .

By Lemma 3.5, the random matrix $(2k_d)^{-\frac{1}{2}}X_d^\perp$, where X_d^\perp is the restriction of X_d to 1^\perp , has the same mean and covariance as a GOE matrix of dimension $d - 1$. Furthermore, the assumptions on k_d and E_d imply that there exist unit vectors $v_d \in 1^\perp$ so that $\|(2k_d)^{-\frac{1}{2}}1_{E_d}1_{E_d}^* - \theta v_d v_d^*\| \rightarrow 0$. Thus applying Theorem 3.35 with $H_{d-1} = (2k_d)^{-\frac{1}{2}}X_d^\perp$ and $A_{d-1} = \theta v_d v_d^*$ shows that the adjacency matrix of the planted model has an outlier eigenvalue (beside its Perron-Frobenius eigenvalue) if and only if $\theta > 1$. In other words, the detectability of a planted clique by an outlier in the spectrum exhibits a phase transition at $|E_d| = \sqrt{2k_d}$.

Let us emphasize that the random matrices that arise in this example are both dependent and may be highly sparse. (For the classical study of spectral detection of planted cliques in dense Erdős-Rényi graphs, see [1].)

Remark 3.37. Even if we consider H_d with i.i.d. entries, sparse matrices are not captured by previous extensions of Theorem 3.34 as their entries have unbounded moments of order $p > 2$ (cf. Example 3.26). Some results for sparse matrices were obtained very recently in [74], but rely on a special choice of A_d .

In this section we have used the classical Gaussian result of Theorem 3.34 as input for the universality theory of this paper. However, much more general results can be obtained in the Gaussian setting by applying the sharp matrix concentration theory of [9]. This approach has two key advantages: it is nonasymptotic, and it yields analogous phenomena in nonhomogeneous situations. The latter are of particular interest in many applications, but are much less well understood than the homogeneous setting [19, 53, 74, 6]. A detailed study of phase transitions in nonhomogeneous models using the methods of [9] and of this paper appears in [10].

4. THE CUMULANT METHOD

The aim of this section is to introduce the basic device that we will use to prove universality throughout this paper. The general setting that will be considered in this section is the following. Let Y_1, \dots, Y_n be independent random vectors in \mathbb{R}^N , and let U_1, \dots, U_n be independent Gaussian random vectors such that Y_i and U_i have the same mean and covariance. Given a function $f : \mathbb{R}^{Nn} \rightarrow \mathbb{C}$, we aim to bound the deviation from the Gaussian model

$$\Delta := \mathbf{E}[f(Y_1, \dots, Y_n)] - \mathbf{E}[f(U_1, \dots, U_n)].$$

There are various classical approaches to such problems. For example, the Lindeberg method replaces Y_i by U_i one term at a time, and then uses Taylor expansion to third order to control the error of each term; similar bounds arise from Stein's method [33, §5]. Unfortunately, in the setting of this paper such methods appear to give rise to very poor bounds. For example, in the context of Theorem 2.9, classical methods yield bounds where the parameter $\sigma_q(X)^2 \leq \sigma(X)^2 := \|\sum_{i=1}^n \mathbf{E}Z_i^2\|$ is replaced by at least $\sum_{i=1}^n \mathbf{E}\|Z_i\|^2$, which is typically much larger.

The reason for the inefficiency of classical approaches to universality is that they require the independent variables to be bounded term by term. In the present setting, bounding the contribution of each summand Z_i in (2.1) separately ignores the noncommutativity of the summands. To surmount this problem, we will work

instead with an exact formula for the deviation Δ in terms of a series expansion in the cumulants of the underlying variables. For our purposes, the advantage of this exact formula is that it will enable us to keep the summands Z_i together, and estimate the resulting terms efficiently using trace inequalities without destroying their noncommutativity. The price we pay for this is that we must expand the deviation Δ to high order in order to obtain efficient estimates.

In the univariate case $N = 1$, the cumulant expansion dates back to the work of Barbour [14], and has been routinely applied to the study of random matrices with independent entries since the work of Lytova and Pastur [55]. In the remainder of this section, we recall the relevant arguments of [14, 55] and spell out their immediate extension to the multivariate case $N > 1$.

4.1. Cumulants. Let W_1, \dots, W_m be bounded real-valued random variables. Then their log-moment generating function is analytic with power series expansion

$$\log \mathbf{E}[e^{\sum_{i=1}^m t_i W_i}] = \sum_{k=1}^{\infty} \sum_{j_1, \dots, j_k=1}^m \frac{1}{k!} \kappa(W_{j_1}, \dots, W_{j_k}) t_{j_1} \cdots t_{j_k}.$$

The coefficient $\kappa(W_1, \dots, W_k)$ is called the *joint cumulant* of the random variables W_1, \dots, W_k . Joint cumulants are multilinear in their arguments and invariant under permutation of their arguments. Moreover, for jointly Gaussian random variables, all joint cumulants of order $k \geq 3$ vanish.

For any subset $J \subseteq [m] := \{1, \dots, m\}$, denote by $W_J := (W_j)_{j \in J}$ the associated subset of random variables. Moreover, denote by $\mathcal{P}([m])$ the collection of all partitions of $[m]$. The following fundamental result [65, Proposition 3.2.1] expresses the relation between joint cumulants and moments.

Lemma 4.1 (Leonov-Shiryaev). *We can write*

$$\mathbf{E}[W_1 \cdots W_m] = \sum_{\pi \in \mathcal{P}([m])} \prod_{J \in \pi} \kappa(W_J).$$

Conversely, we have

$$\kappa(W_1, \dots, W_m) = \sum_{\pi \in \mathcal{P}([m])} (-1)^{|\pi|-1} (|\pi|-1)! \prod_{J \in \pi} \mathbf{E} \left[\prod_{j \in J} W_j \right].$$

The significance of cumulants for our purposes is the following identity. The univariate ($m = 1$) case was proved in [14, Lemma 1] and [55, Proposition 3.1]; the multivariate case follows precisely in the same manner.

Lemma 4.2. *For any polynomial $f : \mathbb{R}^m \rightarrow \mathbb{C}$ and $i \in [m]$, we have*

$$\begin{aligned} \mathbf{E}[W_i f(W_1, \dots, W_m)] &= \\ &\sum_{k=0}^{\infty} \sum_{j_1, \dots, j_k=1}^m \frac{1}{k!} \kappa(W_i, W_{j_1}, \dots, W_{j_k}) \mathbf{E} \left[\frac{\partial^k f}{\partial x_{j_1} \cdots \partial x_{j_k}}(W_1, \dots, W_k) \right]. \end{aligned}$$

Proof. Let $\varphi(x_1, \dots, x_m) := e^{\sum_{j=1}^m t_j x_j}$. Then

$$\begin{aligned} \mathbf{E}[W_i \varphi(W_1, \dots, W_m)] &= \mathbf{E}[\varphi(W_1, \dots, W_m)] \frac{\partial}{\partial t_i} \log \mathbf{E}[e^{\sum_{j=1}^m t_j W_j}] \\ &= \sum_{k=0}^{\infty} \sum_{j_1, \dots, j_k=1}^m \frac{1}{k!} \kappa(W_i, W_{j_1}, \dots, W_{j_k}) t_{j_1} \cdots t_{j_k} \mathbf{E}[\varphi(W_1, \dots, W_m)] \\ &= \sum_{k=0}^{\infty} \sum_{j_1, \dots, j_k=1}^m \frac{1}{k!} \kappa(W_i, W_{j_1}, \dots, W_{j_k}) \mathbf{E}\left[\frac{\partial^k \varphi}{\partial x_{j_1} \cdots \partial x_{j_k}}(W_1, \dots, W_k)\right]. \end{aligned}$$

As any monomial is given by $W_{i_1} \cdots W_{i_l} = \frac{\partial^l}{\partial t_{i_1} \cdots \partial t_{i_l}} \varphi(W_1, \dots, W_m)|_{t_1, \dots, t_m=0}$, the conclusion follows readily by differentiating the above identity. \square

Note that the first two cumulants are given by $\kappa(W) = \mathbf{E}[W]$ and $\kappa(W_1, W_2) = \text{Cov}(W_1, W_2)$. Thus if W_1, \dots, W_m are centered and jointly Gaussian (so that the cumulants of order $k \geq 3$ vanish), the identities of Lemmas 4.1 and 4.2 reduce to

$$\mathbf{E}[W_1 \cdots W_m] = \sum_{\pi \in \mathbf{P}_2([m])} \prod_{\{i,j\} \in \pi} \text{Cov}(W_i, W_j) \quad (4.1)$$

(where $\mathbf{P}_2([m])$ is the collection of pair partitions of $[m]$) and

$$\mathbf{E}[W_i f(W_1, \dots, W_m)] = \sum_{j=1}^m \text{Cov}(W_i, W_j) \mathbf{E}\left[\frac{\partial f}{\partial x_j}(W_1, \dots, W_m)\right]. \quad (4.2)$$

These are none other than the well-known Wick formula and integration by parts formula for centered Gaussian measures.

4.2. Cumulant expansion. We can now express the basic principle that will be used to prove universality. This principle is a direct extension of the method of [14, 55] to the multivariate case; see, e.g., [55, Corollary 3.1].

Theorem 4.3. *Let Y_1, \dots, Y_n be independent centered and bounded random vectors in \mathbb{R}^N , and let U_1, \dots, U_n be independent centered Gaussian random vectors in \mathbb{R}^N such that Y_i and U_i have the same covariance. Assume that $Y = (Y_1, \dots, Y_n)$ and $U = (U_1, \dots, U_n)$ are independent of each other, and define*

$$Y(t) := \sqrt{t} Y + \sqrt{1-t} U.$$

Then we have

$$\frac{d}{dt} \mathbf{E}[f(Y(t))] = \frac{1}{2} \sum_{k=3}^{\infty} \sum_{i=1}^n \sum_{j_1, \dots, j_k=1}^N \frac{t^{\frac{k}{2}-1}}{(k-1)!} \kappa(Y_{ij_1}, \dots, Y_{ij_k}) \mathbf{E}\left[\frac{\partial^k f}{\partial y_{ij_1} \cdots \partial y_{ij_k}}(Y(t))\right]$$

for any polynomial $f : \mathbb{R}^{Nn} \rightarrow \mathbb{C}$ and $t \in [0, 1]$.

Proof. We readily compute

$$\frac{d}{dt} \mathbf{E}[f(Y(t))] = \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^N \left\{ \frac{1}{\sqrt{t}} \mathbf{E}\left[Y_{ij} \frac{\partial f}{\partial y_{ij}}(Y(t))\right] - \frac{1}{\sqrt{1-t}} \mathbf{E}\left[U_{ij} \frac{\partial f}{\partial y_{ij}}(Y(t))\right] \right\}.$$

The conclusion follows by applying Lemma 4.2 conditionally on $\{U, (Y_k)_{k \neq i}\}$ to compute the first term in the sum, and applying (4.2) conditionally on $\{Y, (U_k)_{k \neq i}\}$ to compute the second term in the sum. \square

The model $Y(t)$ should be viewed as an interpolation between the original model Y and the associated Gaussian model U . In particular, Theorem 4.3 yields a bound on the Gaussian deviation by the fundamental theorem of calculus

$$\mathbf{E}[f(Y)] - \mathbf{E}[f(U)] = \int_0^1 \frac{d}{dt} \mathbf{E}[f(Y(t))] dt.$$

We will however often find it necessary to perform a change of variables before applying the fundamental theorem of calculus.

When the function f is not a polynomial, it must be approximated by a polynomial before we can apply Theorem 4.3. The following result is a straightforward combination of Theorem 4.3 with Taylor expansion to order $p - 1$.

Theorem 4.4. *Let Y_1, \dots, Y_n be independent centered and bounded random vectors in \mathbb{R}^N , and let U_1, \dots, U_n be independent centered Gaussian random vectors in \mathbb{R}^N such that Y_i and U_i have the same covariance. Assume that $Y = (Y_1, \dots, Y_n)$ and $U = (U_1, \dots, U_n)$ are independent of each other, and define*

$$Y(t) := \sqrt{t}Y + \sqrt{1-t}U.$$

Let $p \geq 3$ and $f : \mathbb{R}^{Nn} \rightarrow \mathbb{C}$ be a smooth function. Then we have

$$\begin{aligned} \frac{d}{dt} \mathbf{E}[f(Y(t))] = & \\ & \frac{1}{2} \sum_{k=3}^{p-1} \sum_{i=1}^n \sum_{j_1, \dots, j_k=1}^N \frac{t^{\frac{k}{2}-1}}{(k-1)!} \kappa(Y_{ij_1}, \dots, Y_{ij_k}) \mathbf{E} \left[\frac{\partial^k f}{\partial y_{ij_1} \cdots \partial y_{ij_k}}(Y(t)) \right] + \mathcal{R} \end{aligned}$$

for any $t \in [0, 1]$, where the remainder term satisfies

$$\begin{aligned} |\mathcal{R}| \lesssim & \sup_{s, t \in [0, 1]} \left\{ \left| \sum_{i=1}^n \sum_{j_1, \dots, j_p=1}^N \mathbf{E} \left[Y_{ij_1} \cdots Y_{ij_p} \frac{\partial^p f}{\partial y_{ij_1} \cdots \partial y_{ij_p}}(Y(t, i, s)) \right] \right| + \right. \\ & \left. \max_{2 \leq k \leq p-1} \left| \sum_{i=1}^n \sum_{j_1, \dots, j_p=1}^N \frac{\kappa(Y_{ij_1}, \dots, Y_{ij_k})}{(k-1)!} \mathbf{E} \left[Y_{ij_{k+1}} \cdots Y_{ij_p} \frac{\partial^p f}{\partial y_{ij_1} \cdots \partial y_{ij_p}}(Y(t, i, s)) \right] \right| \right\} \end{aligned}$$

with $Y_j(t, i, s) := s^{1_{i=j}} \sqrt{t}Y_j + \sqrt{1-t}U_j$.

Proof. Let $g : \mathbb{R}^{Nn} \rightarrow \mathbb{C}$ be a smooth function, and let g_i be the Taylor expansion of $t \mapsto g(y_1, \dots, y_{i-1}, ty_i, y_{i+1}, \dots, y_n)$ to order $p - 1$ around 0 (evaluated at $t = 1$):

$$g_i(y) := \sum_{l=0}^{p-1} \sum_{j_1, \dots, j_l=1}^N \frac{1}{l!} y_{ij_1} \cdots y_{ij_l} \frac{\partial^l g}{\partial y_{ij_1} \cdots \partial y_{ij_l}}(y_1, \dots, y_{i-1}, 0, y_{i+1}, \dots, y_n).$$

Then

$$\begin{aligned} \frac{\partial^k g}{\partial y_{ij_1} \cdots \partial y_{ij_k}}(y) &= \frac{\partial^k g_i}{\partial y_{ij_1} \cdots \partial y_{ij_k}}(y) + \int_0^1 \frac{(1-s)^{p-k-1}}{(p-k-1)!} \cdot \\ & \quad \sum_{j_{k+1}, \dots, j_p=1}^N y_{ij_{k+1}} \cdots y_{ij_p} \frac{\partial^p g}{\partial y_{ij_1} \cdots \partial y_{ij_p}}(y_1, \dots, y_{i-1}, sy_i, y_{i+1}, \dots, y_n) ds \end{aligned}$$

for all $0 \leq k \leq p-1$ and j_1, \dots, j_k . Choosing $g(Y) := f(\sqrt{t}Y + \sqrt{1-t}U)$ yields

$$\begin{aligned} \frac{1}{2\sqrt{t}} \sum_{i=1}^n \sum_{j=1}^N \mathbf{E} \left[Y_{ij} \frac{\partial f}{\partial y_{ij}}(Y(t)) \right] &= \frac{1}{2t} \sum_{i=1}^n \sum_{j=1}^N \mathbf{E} \left[Y_{ij} \frac{\partial g}{\partial y_{ij}}(Y) \right] \\ &= \frac{1}{2t} \sum_{i=1}^n \sum_{j=1}^N \mathbf{E} \left[Y_{ij} \frac{\partial g_i}{\partial y_{ij}}(Y) \right] + \mathcal{R}_1, \end{aligned}$$

where

$$\mathcal{R}_1 = \frac{t^{\frac{p}{2}-1}}{2} \int_0^1 \frac{(1-s)^{p-2}}{(p-2)!} \sum_{i=1}^n \sum_{j_1, \dots, j_p=1}^N \mathbf{E} \left[Y_{ij_1} \cdots Y_{ij_p} \frac{\partial^p f}{\partial y_{ij_1} \cdots \partial y_{ij_p}}(Y(t, i, s)) \right] ds.$$

As $y_i \mapsto g_i(y)$ is a polynomial of degree $p-1$ and $\kappa(Y_{ij}) = \mathbf{E}[Y_{ij}] = 0$, we can now apply Lemma 4.2 conditionally on $\{U, (Y_k)_{k \neq i}\}$ to compute

$$\begin{aligned} &\frac{1}{2t} \sum_{i=1}^n \sum_{j=1}^N \mathbf{E} \left[Y_{ij} \frac{\partial g_i}{\partial y_{ij}}(Y) \right] \\ &= \frac{1}{2t} \sum_{k=2}^{p-1} \sum_{i=1}^n \sum_{j_1, \dots, j_k=1}^N \frac{1}{(k-1)!} \kappa(Y_{ij_1}, \dots, Y_{ij_k}) \mathbf{E} \left[\frac{\partial g_i}{\partial y_{ij_1} \cdots \partial y_{ij_k}}(Y) \right] \\ &= \frac{1}{2} \sum_{k=2}^{p-1} \sum_{i=1}^n \sum_{j_1, \dots, j_k=1}^N \frac{t^{\frac{k}{2}-1}}{(k-1)!} \kappa(Y_{ij_1}, \dots, Y_{ij_k}) \mathbf{E} \left[\frac{\partial f}{\partial y_{ij_1} \cdots \partial y_{ij_k}}(Y(t)) \right] - \mathcal{R}_2, \end{aligned}$$

where

$$\begin{aligned} \mathcal{R}_2 &= \frac{t^{\frac{p}{2}-1}}{2} \sum_{k=2}^{p-1} \int_0^1 \frac{(1-s)^{p-k-1}}{(p-k-1)!} \cdot \\ &\quad \sum_{i=1}^n \sum_{j_1, \dots, j_p=1}^N \frac{\kappa(Y_{ij_1}, \dots, Y_{ij_k})}{(k-1)!} \mathbf{E} \left[Y_{ij_{k+1}} \cdots Y_{ij_p} \frac{\partial^p f}{\partial y_{ij_1} \cdots \partial y_{ij_p}}(Y(t, i, s)) \right] ds. \end{aligned}$$

Thus the identity in the statement follows precisely as in the proof of Theorem 4.3 with $\mathcal{R} = \mathcal{R}_1 - \mathcal{R}_2$. The estimate on $|\mathcal{R}|$ now follows readily by noting that

$$\sum_{k=1}^{p-1} \int_0^1 \frac{(1-s)^{p-k-1}}{(p-k-1)!} ds = \sum_{k=1}^{p-1} \frac{1}{(p-k)!} \leq e - 1,$$

concluding the proof. \square

5. BASIC TOOLS

The aim of this section is to develop two important tools that will be needed in the proofs of our main results. In section 5.1, we prove a trace inequality that will enable us to control the derivatives that arise in the cumulant expansion of various spectral statistics. In section 5.2, we develop concentration of measure inequalities for the resolvent and for more general spectral statistics.

5.1. A trace inequality. Let $L_p(S_p^d)$ be the Banach space of $d \times d$ random matrices M (that is, $M_d(\mathbb{C})$ -valued random variables on an underlying probability space that we consider fixed throughout the paper) such that $\|M\|_p < \infty$. Here

$$\|M\|_p := \begin{cases} (\mathbf{E}[\text{tr}|M|^p])^{\frac{1}{p}} & \text{if } 1 \leq p < \infty, \\ \|\|M\|\|_{\infty} & \text{if } p = \infty, \end{cases}$$

where we recall that tr denotes the normalized trace. In particular, when $M \in M_d(\mathbb{C})$ is a deterministic matrix, $\|M\|_p$ is the (normalized) Schatten- p norm. In this notation, we can write

$$\sigma_q(X) := \left\| \left(\sum_{i=1}^n \mathbf{E} Z_i^2 \right)^{\frac{1}{2}} \right\|_q, \quad R_q(X) := \left(\sum_{i=1}^n \|Z_i\|_q^q \right)^{\frac{1}{q}}$$

for $q < \infty$ (cf. section 2.1.4).

The following trace inequality will play a key role throughout this paper.

Proposition 5.1. *Fix $k \geq 2$. Let $(Z_{ij})_{i \in [n], j \in [k]}$ be a collection of (possibly dependent) $d \times d$ self-adjoint random matrices such that Z_{ij} has the same distribution as Z_i for each i, j . Let $1 \leq p_1, \dots, p_k, q \leq \infty$ satisfy $\sum_{j=1}^k \frac{1}{p_j} = 1 - \frac{k}{q}$. Then*

$$\left| \sum_{i=1}^n \mathbf{E}[\text{tr} Z_{i1} Y_1 Z_{i2} Y_2 \cdots Z_{ik} Y_k] \right| \leq R_q(X)^{\frac{(k-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-k)}{q-2}} \prod_{j=1}^k \|Y_j\|_{p_j}$$

for any (possibly dependent) $d \times d$ random matrices Y_1, \dots, Y_k that are independent of the random matrices $(Z_{ij})_{i \in [n], j \in [k]}$.

In preparation for the proof of this result, we recall some fundamental tools that will be needed below. We first state a variant of the Riesz-Thorin interpolation theorem for Schatten classes. (The application of complex interpolation in this context was inspired by [79], and was previously used in [9, Lemma 4.5].)

Lemma 5.2. *Let $F : (L_{\infty}(S_{\infty}^d))^k \rightarrow \mathbb{C}$ be a multilinear functional. Then the map*

$$\left(\frac{1}{p_1}, \dots, \frac{1}{p_k} \right) \mapsto \log \sup_{M_1, \dots, M_k} \frac{|F(M_1, \dots, M_k)|}{\|M_1\|_{p_1} \cdots \|M_k\|_{p_k}}$$

is convex on $[0, 1]^k$.

Proof. This follows immediately from the classical complex interpolation theorem for multilinear maps [26, §10.1] and the fact that the spaces $L_p(S_p^d)$ form a complex interpolation scale $L_r(S_r^d) = (L_p(S_p^d), L_q(S_q^d))_{\theta}$ with $\frac{1}{r} = \frac{1-\theta}{p} + \frac{\theta}{q}$ [67, §2]. \square

Next, we recall a Hölder inequality for Schatten classes. We include a proof in order to illustrate Lemma 5.2; the same method will be used again below.

Lemma 5.3. *Let $1 \leq p_1, \dots, p_k \leq \infty$ satisfy $\sum_{i=1}^k \frac{1}{p_i} = 1$. Then*

$$|\mathbf{E}[\text{tr} Y_1 \cdots Y_k]| \leq \|Y_1\|_{p_1} \cdots \|Y_k\|_{p_k}$$

for any $d \times d$ random matrices Y_1, \dots, Y_k .

Proof. It suffices to prove the inequality for any $Y_1, \dots, Y_k \in L_\infty(S_\infty^d)$, that is, we must show that the multilinear functional $F(Y_1, \dots, Y_k) := \mathbf{E}[\text{tr } Y_1 \cdots Y_k]$ satisfies

$$\sup_{Y_1, \dots, Y_k \in L_\infty(S_\infty^d)} \frac{|F(Y_1, \dots, Y_k)|}{\|Y_1\|_{p_1} \cdots \|Y_k\|_{p_k}} \leq 1 \quad \text{for all } \left(\frac{1}{p_1}, \dots, \frac{1}{p_k}\right) \in \Delta,$$

where $\Delta := \{x \in [0, 1]^k : \sum_{i=1}^k x_i = 1\}$. By Lemma 5.2, it suffices to prove the claim only for the extreme points of Δ , that is, when $p_i = 1$ and $p_j = \infty$, $j \neq i$ for some i . But the latter case is elementary, as $|XY|^2 = Y^* X^* XY \leq \|X\|^2 |Y|^2$ and thus $|F(Y_1, \dots, Y_k)| \leq \|Y_{i+1} \cdots Y_k Y_1 \cdots Y_{i-1}\|_\infty \|Y_i\|_1 \leq \|Y_i\|_1 \prod_{j \neq i} \|Y_j\|_\infty$. \square

Finally, we recall without proof the Lieb-Thirring inequality [29, Theorem 7.4].

Lemma 5.4. *Let Y, Z be $d \times d$ positive semidefinite random matrices. Then*

$$\mathbf{E}[\text{tr } (ZY)^r] \leq \mathbf{E}[\text{tr } Z^r Y^r Z^r]$$

for every $1 \leq r < \infty$.

We can now proceed to the proof of Proposition 5.1.

Proof of Proposition 5.1. Throughout the proof we will assume without loss of generality that $R_q(X) < \infty$, as the conclusion is trivial otherwise. Thus Lemma 5.3 implies that the multilinear functional $\tilde{F} : (\mathbf{M}_d(\mathbb{C}))^k \rightarrow \mathbb{C}$ defined by

$$\tilde{F}(M_1, \dots, M_k) := \sum_{i=1}^n \mathbf{E}[\text{tr } Z_{i1} M_1 Z_{i2} M_2 \cdots Z_{ik} M_k]$$

satisfies $|\tilde{F}(M_1, \dots, M_k)| \leq \prod_{j=1}^k \|M_j\|_\infty$ for all $M_1, \dots, M_k \in \mathbf{M}_d(\mathbb{C})$. Therefore

$$F(Y_1, \dots, Y_k) := \mathbf{E}[\tilde{F}(Y_1, \dots, Y_k)]$$

defines a multilinear functional $F : (L_\infty(S_\infty^d))^k \rightarrow \mathbb{C}$. Throughout the proof, it is implicit in the notation that (Y_1, \dots, Y_k) are taken to be independent of $(Z_{ij})_{i,j}$.

Step 1. Our aim is to show that

$$\sup_{Y_1, \dots, Y_k \in L_\infty(S_\infty^d)} \frac{|F(Y_1, \dots, Y_k)|}{\|Y_1\|_{p_1} \cdots \|Y_k\|_{p_k}} \leq R_q(X)^{\frac{(k-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-k)}{q-2}}$$

for all $(\frac{1}{p_1}, \dots, \frac{1}{p_k}) \in \Delta := \{x \in [0, 1]^k : \sum_{i=1}^k x_i = 1 - \frac{k}{q}\}$. By Lemma 5.2, it suffices to prove the claim only for $(\frac{1}{p_1}, \dots, \frac{1}{p_k})$ that are extreme points of the simplex Δ , that is, when $p_i = \frac{q}{q-k}$ and $p_j = \infty$, $j \neq i$ holds for some i .

By cyclic permutation of the trace, it suffices to consider the case $p_1, \dots, p_{k-1} = \infty$ and $p_k = \frac{q}{q-k}$. To further simplify the statement to be proved, let I be a random variable that is uniformly distributed on $[n]$ and is independent of $(Y_j, Z_{ij})_{i,j}$, and define the random matrices $\mathbf{Z}_j := Z_{Ij}$. Then it suffices to show that

$$n|\mathbf{E}[\text{tr } \mathbf{Z}_1 Y_1 \mathbf{Z}_2 Y_2 \cdots \mathbf{Z}_k Y_k]| \leq R_q(X)^{\frac{(k-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-k)}{q-2}}$$

whenever $\|Y_1\|_\infty = \cdots = \|Y_{k-1}\|_\infty = 1$ and $\|Y_k\|_{\frac{q}{q-k}} = 1$. In the remainder of the proof, we fix Y_1, \dots, Y_k satisfying the latter assumptions.

Step 2. The assumptions on k, p_1, \dots, p_k, q imply that $q \geq k \geq 2$. In the case that $q = k$, we can estimate using Lemma 5.3

$$n|\mathbf{E}[\text{tr } \mathbf{Z}_1 Y_1 \mathbf{Z}_2 Y_2 \cdots \mathbf{Z}_k Y_k]| \leq n\|\mathbf{Z}_1\|_k \|Y_1\|_\infty \cdots \|\mathbf{Z}_k\|_k \|Y_k\|_\infty = R_k(X)^k,$$

completing the proof. We therefore assume in the rest of the proof that $q > k$.

Step 3. Suppose k is even. Denote by $\mathbf{Z}_j = \mathbf{U}_j |\mathbf{Z}_j|$ and $Y_k = V_k |Y_k|$ the polar decompositions of \mathbf{Z}_j and Y_k , respectively. Then we can estimate for $r \geq 1$

$$\begin{aligned} |\mathbf{E}[\text{tr } \mathbf{Z}_1 Y_1 \mathbf{Z}_2 Y_2 \cdots \mathbf{Z}_k Y_k]| &= |\mathbf{E}[\text{tr } |Y_k|^{\frac{1}{2}} \mathbf{Z}_1 Y_1 \mathbf{Z}_2 Y_2 \cdots \mathbf{Z}_k V_k |Y_k|^{\frac{1}{2}}]| \\ &\leq \mathbf{E}[\text{tr } \mathbf{Z}_1 Y_1 \cdots \mathbf{Z}_{\frac{k}{2}} Y_{\frac{k}{2}} Y_{\frac{k}{2}}^* \mathbf{Z}_{\frac{k}{2}} \cdots Y_1^* \mathbf{Z}_1 |Y_k|^{\frac{1}{2}}]^{\frac{1}{2}}. \\ &\quad \mathbf{E}[\text{tr } \mathbf{Z}_k Y_{k-1} \mathbf{Z}_{k-1} \cdots Y_{\frac{k}{2}+1}^* \mathbf{Z}_{\frac{k}{2}+1} \mathbf{Z}_{\frac{k}{2}+1} Y_{\frac{k}{2}+1} \cdots \mathbf{Z}_{k-1} Y_{k-1} \mathbf{Z}_k V_k |Y_k| V_k]^{\frac{1}{2}} \\ &= \mathbf{E}[\text{tr } |\mathbf{Z}_1|^{1-\frac{1}{r}} \mathbf{U}_1^* Y_1 \mathbf{Z}_2 \cdots Y_{\frac{k}{2}-1} \mathbf{Z}_{\frac{k}{2}} Y_{\frac{k}{2}} \cdot \\ &\quad Y_{\frac{k}{2}}^* \mathbf{Z}_{\frac{k}{2}} Y_{\frac{k}{2}-1}^* \cdots \mathbf{Z}_2 Y_1^* \mathbf{U}_1 |\mathbf{Z}_1|^{1-\frac{1}{r}} |\mathbf{Z}_1|^{\frac{1}{r}} |Y_k| |\mathbf{Z}_1|^{\frac{1}{r}}]^{\frac{1}{2}}. \\ &\quad \mathbf{E}[\text{tr } |\mathbf{Z}_k|^{1-\frac{1}{r}} \mathbf{U}_k^* Y_{k-1}^* \mathbf{Z}_{k-1} \cdots Y_{\frac{k}{2}+1}^* \mathbf{Z}_{\frac{k}{2}+1} \cdot \\ &\quad \mathbf{Z}_{\frac{k}{2}+1} Y_{\frac{k}{2}+1} \cdots \mathbf{Z}_{k-1} Y_{k-1} \mathbf{U}_k |\mathbf{Z}_k|^{1-\frac{1}{r}} |\mathbf{Z}_k|^{\frac{1}{r}} V_k |Y_k| V_k^* |\mathbf{Z}_k|^{\frac{1}{r}}]^{\frac{1}{2}} \end{aligned}$$

by Cauchy-Schwarz. Now let

$$r = \frac{q-2}{q-k} \in [1, \infty).$$

Then we have $2\frac{1-\frac{1}{r}}{q} + (k-2)\frac{1}{q} + \frac{1}{r} = 1$. We can therefore estimate

$$\begin{aligned} &|\mathbf{E}[\text{tr } \mathbf{Z}_1 Y_1 \mathbf{Z}_2 Y_2 \cdots \mathbf{Z}_k Y_k]| \\ &\leq \|\mathbf{Z}_1\|_q^{1-\frac{1}{r}} \|\mathbf{Z}_2\|_q \cdots \|\mathbf{Z}_{\frac{k}{2}}\|_q \|\mathbf{Z}_1\|^{\frac{1}{r}} |Y_k| \|\mathbf{Z}_1\|^{\frac{1}{r}} \|^{\frac{1}{r}} \\ &\quad \|\mathbf{Z}_k\|_q^{1-\frac{1}{r}} \|\mathbf{Z}_{\frac{k}{2}+1}\|_q \cdots \|\mathbf{Z}_{k-1}\|_q \|\mathbf{Z}_k\|^{\frac{1}{r}} V_k |Y_k| V_k^* |\mathbf{Z}_k|^{\frac{1}{r}} \|^{\frac{1}{r}} \\ &= n^{-\frac{k-2}{q-2}} R_q(X)^{\frac{(k-2)q}{q-2}} \|\mathbf{Z}_1\|^{\frac{1}{r}} |Y_k| \|\mathbf{Z}_1\|^{\frac{1}{r}} \|^{\frac{1}{r}} \|\mathbf{Z}_k\|^{\frac{1}{r}} V_k |Y_k| V_k^* |\mathbf{Z}_k|^{\frac{1}{r}} \|^{\frac{1}{r}} \end{aligned}$$

by Lemma 5.3, where we used that $\|\mathbf{Z}_j\|_q = n^{-\frac{1}{q}} R_q(X)$ and that $k - \frac{2}{r} = \frac{(k-2)q}{q-2}$. On the other hand, using Lemma 5.4 we obtain

$$\|\mathbf{Z}_1\|^{\frac{1}{r}} |Y_k| \|\mathbf{Z}_1\|^{\frac{1}{r}} \|^{\frac{1}{r}} \leq \mathbf{E}[\text{tr } |Y_k|^r \mathbf{Z}_1^2] = \mathbf{E}[\text{tr } |Y_k|^r \mathbf{E}[\mathbf{Z}_1^2]] \leq \|\mathbf{E}[\mathbf{Z}_1^2]\|_{\frac{q}{2}},$$

where we used that Y_k and \mathbf{Z}_1 are independent and $\| |Y_k|^r \|_{\frac{q}{q-2}} = \| Y_k \|_{\frac{q}{q-k}}^r = 1$.

The analogous term involving \mathbf{Z}_k is estimated identically. We therefore obtain

$$|\mathbf{E}[\text{tr } \mathbf{Z}_1 Y_1 \mathbf{Z}_2 Y_2 \cdots \mathbf{Z}_k Y_k]| \leq n^{-1} R_q(X)^{\frac{(k-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-k)}{q-2}},$$

where we used that $\|\mathbf{E}[\mathbf{Z}_j^2]\|_{\frac{q}{2}} = n^{-1} \sigma_q(X)^2$ for all j . This concludes the proof of the inequality for the case that k is even.

Step 4. Finally, suppose k is odd. Then we apply Cauchy-Schwarz as follows:

$$\begin{aligned} &|\mathbf{E}[\text{tr } \mathbf{Z}_1 Y_1 \mathbf{Z}_2 Y_2 \cdots \mathbf{Z}_k Y_k]| \\ &= |\mathbf{E}[\text{tr } |Y_k|^{\frac{1}{2}} \mathbf{Z}_1 Y_1 \cdots \mathbf{Z}_{\frac{k-1}{2}} Y_{\frac{k-1}{2}} \mathbf{U}_{\frac{k+1}{2}} |\mathbf{Z}_{\frac{k+1}{2}}|^{\frac{1}{2}} \cdot \\ &\quad |\mathbf{Z}_{\frac{k+1}{2}}|^{\frac{1}{2}} Y_{\frac{k+1}{2}} \mathbf{Z}_{\frac{k+3}{2}} \cdots Y_{k-1} \mathbf{Z}_k V_k |Y_k|^{\frac{1}{2}}]| \\ &\leq \mathbf{E}[\text{tr } \mathbf{Z}_1 Y_1 \cdots \mathbf{Z}_{\frac{k-1}{2}} Y_{\frac{k-1}{2}} \mathbf{U}_{\frac{k+1}{2}} |\mathbf{Z}_{\frac{k+1}{2}}|^{\frac{1}{2}} |\mathbf{U}_{\frac{k+1}{2}}^* Y_{\frac{k-1}{2}}^* \mathbf{Z}_{\frac{k-1}{2}} \cdots Y_1^* \mathbf{Z}_1|^{\frac{1}{2}}]^{\frac{1}{2}} \cdot \\ &\quad \mathbf{E}[\text{tr } \mathbf{Z}_k Y_{k-1}^* \cdots \mathbf{Z}_{\frac{k+3}{2}} Y_{\frac{k+3}{2}}^* |\mathbf{Z}_{\frac{k+1}{2}}|^{\frac{1}{2}} |Y_{\frac{k+1}{2}}| \mathbf{Z}_{\frac{k+3}{2}} \cdots Y_{k-1} \mathbf{Z}_k V_k |Y_k| V_k^*]^{\frac{1}{2}}. \end{aligned}$$

The rest of the proof proceeds exactly as in the case that k is even. \square

5.2. Concentration of measure. In the proof of our main results, it will be necessary to control the norms of the resolvents $\|(z\mathbf{1} - X)^{-1}\|$ and $\|(z\mathbf{1} - G)^{-1}\|$ simultaneously over many points $z \in \mathbb{C}$. To this end, we will exploit the fact that these quantities are strongly concentrated around their means.

For the Gaussian model G , such concentration inequalities follow from a routine application of Gaussian concentration, as we recall in section 5.2.1. However, the non-Gaussian model X does not appear to be amenable to off-the-shelf concentration inequalities: while convex Lipschitz functions of sums of independent random matrices (such as the norm $\|X\|$) can be treated using concentration inequalities due to Talagrand, such methods do not apply to the non-convex function $(Z_1, \dots, Z_n) \mapsto \|(z\mathbf{1} - X)^{-1}\|$. In section 5.2.2, we develop a specialized concentration inequality that will play a key role in the proofs of our main results.

Finally, in section 5.2.3, we obtain concentration inequalities for the spectral statistics $\langle v, \varphi(X)w \rangle$ both in the Gaussian and non-Gaussian situations, which may be used in conjunction with Theorem 2.10 to obtain high probability universality bounds for spectral statistics. The proofs of these concentration inequalities rely on concentration of the resolvent as derived in the previous sections. An analogous concentration inequality for moments, which may be used in conjunction with Theorem 2.9, is much simpler and follows from a routine application of Talagrand's concentration inequality; such an inequality is given in Lemma 9.20.

5.2.1. Resolvent norm: the Gaussian case. The Gaussian random matrix G is amenable to a routine application of Gaussian concentration [22, Theorem 5.6] as in [9, Lemma 6.5]. For completeness, we spell out the argument.

Lemma 5.5. *Fix $z \in \mathbb{C}$ with $\text{Im } z > 0$. Then we have for any $x \geq 0$*

$$\mathbf{P} \left[\left| \|(z\mathbf{1} - G)^{-1}\| - \mathbf{E} \|(z\mathbf{1} - G)^{-1}\| \right| \geq \frac{\sigma_*(G)}{(\text{Im } z)^2} x \right] \leq 2e^{-x^2/2}.$$

Proof. Without loss of generality, we may express

$$G = A_0 + \sum_{i=1}^N g_i A_i$$

for some deterministic $A_0, \dots, A_N \in \mathbf{M}_d(\mathbb{C})_{\text{sa}}$ and i.i.d. standard Gaussian variables g_1, \dots, g_N (cf. Remark 2.3). Now consider the function $f : \mathbb{R}^N \rightarrow \mathbb{R}$ defined by

$$f(x) := \left\| \left(z\mathbf{1} - A_0 - \sum_{i=1}^N x_i A_i \right)^{-1} \right\|.$$

As $A^{-1} - B^{-1} = A^{-1}(B - A)B^{-1}$ for invertible matrices A, B , and as $\|(z\mathbf{1} - Y)^{-1}\| \leq (\text{Im } z)^{-1}$ for any self-adjoint matrix Y , we obtain

$$\begin{aligned} |f(x) - f(y)| &\leq \left\| \left(z\mathbf{1} - A_0 - \sum_{i=1}^N x_i A_i \right)^{-1} - \left(z\mathbf{1} - A_0 - \sum_{i=1}^N y_i A_i \right)^{-1} \right\| \\ &\leq \frac{1}{(\text{Im } z)^2} \left\| \sum_{i=1}^N (x_i - y_i) A_i \right\| \leq \frac{\sigma_*(G)}{(\text{Im } z)^2} \|x - y\|, \end{aligned}$$

where we used that

$$\begin{aligned}
\left\| \sum_{i=1}^N (x_i - y_i) A_i \right\| &= \sup_{\|v\|=\|w\|=1} \left| \sum_{i=1}^N (x_i - y_i) \langle v, A_i w \rangle \right| \\
&\leq \sup_{\|v\|=\|w\|=1} \left(\sum_{i=1}^N |\langle v, A_i w \rangle|^2 \right)^{\frac{1}{2}} \|x - y\| \\
&= \sup_{\|v\|=\|w\|=1} \mathbf{E} [|\langle v, (G - \mathbf{E}G)w \rangle|^2]^{\frac{1}{2}} \|x - y\| \\
&= \sigma_*(G) \|x - y\|.
\end{aligned}$$

Thus $\|(z\mathbf{1} - G)^{-1}\| = f(g_1, \dots, g_N)$ is a $\frac{\sigma_*(G)}{(\text{Im } z)^2}$ -Lipschitz function of a standard Gaussian vector. The conclusion is therefore immediate from the Gaussian concentration inequality [22, Theorem 5.6], which states that an L -Lipschitz function of a standard Gaussian vector is L^2 -subgaussian. \square

5.2.2. Resolvent norm: the non-Gaussian case. We now aim to prove an analogue of Lemma 5.5 for the non-Gaussian model X . To this end, we exploit the resolvent identity to prove a specialized concentration inequality using the entropy method [22, Chapter 6]. The result takes a more complicated form than Lemma 5.5, but will nonetheless suffice for the purposes of this paper.

Proposition 5.6. *Fix $z \in \mathbb{C}$ with $\text{Im } z > 0$. Then we have*

$$\begin{aligned}
\mathbf{P} \left[\left| \|(z\mathbf{1} - X)^{-1}\| - \mathbf{E} \|(z\mathbf{1} - X)^{-1}\| \right| \geq \frac{\sigma_*(X)}{(\text{Im } z)^2} \sqrt{x} + \left\{ \frac{R(X)}{(\text{Im } z)^2} + \frac{R(X)^2}{(\text{Im } z)^3} \right\} x \right. \\
\left. + \left\{ \frac{R(X)^{\frac{1}{2}} (\mathbf{E} \|X - \mathbf{E}X\|)^{\frac{1}{2}}}{(\text{Im } z)^2} + \frac{R(X) (\mathbf{E} \|X - \mathbf{E}X\|^2)^{\frac{1}{2}}}{(\text{Im } z)^3} \right\} \sqrt{x} \right] \leq 2e^{-Cx}
\end{aligned}$$

for any $x \geq 0$, where C is a universal constant.

In preparation for the proof, we begin by estimating a type of discrete gradient of the function $(Z_1, \dots, Z_n) \mapsto \|(z\mathbf{1} - X)^{-1}\|$.

Lemma 5.7. *Let (Z'_1, \dots, Z'_n) be an independent copy of (Z_1, \dots, Z_n) . Let X be as in (2.1) and let $X^{\sim i} := Z_0 + \sum_{j \neq i} Z_j + Z'_i$. Then*

$$\|(z\mathbf{1} - X)^{-1}\| - \|(z\mathbf{1} - X^{\sim i})^{-1}\| \leq \frac{2R(X)}{(\text{Im } z)^2}$$

for all i , and

$$\sum_{i=1}^n (\|(z\mathbf{1} - X)^{-1}\| - \|(z\mathbf{1} - X^{\sim i})^{-1}\|)_+^2 \leq W$$

with

$$W := \frac{2}{(\text{Im } z)^4} \sup_{\|v\|=\|w\|=1} \sum_{i=1}^n |\langle v, (Z_i - Z'_i)w \rangle|^2 + \frac{8}{(\text{Im } z)^6} R(X)^2 \left\| \sum_{i=1}^n (Z_i - Z'_i)^2 \right\|.$$

Proof. The first part of the statement follows as

$$\|(z\mathbf{1} - X)^{-1}\| - \|(z\mathbf{1} - X^{\sim i})^{-1}\| \leq \|(z\mathbf{1} - X)^{-1} (Z_i - Z'_i) (z\mathbf{1} - X^{\sim i})^{-1}\| \leq \frac{2R(X)}{(\text{Im } z)^2}$$

using the reverse triangle inequality and $A^{-1} - B^{-1} = A^{-1}(B - A)B^{-1}$ in the first inequality, and $\|(z\mathbf{1} - A)^{-1}\| \leq (\text{Im } z)^{-1}$ in the second inequality.

To prove the second part of the statement, we must estimate more carefully. Let v_*, w_* be (random) vectors in the unit sphere such that

$$\|(z\mathbf{1} - X)^{-1}\| = \sup_{\|v\|=\|w\|=1} |\langle v, (z\mathbf{1} - X)^{-1}w \rangle| = |\langle v_*, (z\mathbf{1} - X)^{-1}w_* \rangle|.$$

Then

$$\begin{aligned} & \|(z\mathbf{1} - X)^{-1}\| - \|(z\mathbf{1} - X^{\sim i})^{-1}\| \\ & \leq |\langle v_*, (z\mathbf{1} - X)^{-1}w_* \rangle| - |\langle v_*, (z\mathbf{1} - X^{\sim i})^{-1}w_* \rangle| \\ & \leq |\langle v_*, (z\mathbf{1} - X)^{-1}(Z_i - Z'_i)(z\mathbf{1} - X^{\sim i})^{-1}w_* \rangle| \\ & \leq |\langle v_*, (z\mathbf{1} - X)^{-1}(Z_i - Z'_i)(z\mathbf{1} - X)^{-1}w_* \rangle| \\ & \quad + |\langle v_*, (z\mathbf{1} - X)^{-1}(Z_i - Z'_i)(z\mathbf{1} - X^{\sim i})^{-1}(Z_i - Z'_i)(z\mathbf{1} - X)^{-1}w_* \rangle|, \end{aligned}$$

where we used twice the identity $A^{-1} - B^{-1} = A^{-1}(B - A)B^{-1}$. But as we have $\|(z\mathbf{1} - X)^{-1}w_*\| \leq (\text{Im } z)^{-1}$ and $\|(\bar{z}\mathbf{1} - X)^{-1}v_*\| \leq (\text{Im } z)^{-1}$, we can estimate

$$\begin{aligned} & \sum_{i=1}^n |\langle v_*, (z\mathbf{1} - X)^{-1}(Z_i - Z'_i)(z\mathbf{1} - X)^{-1}w_* \rangle|^2 \\ & \leq \frac{1}{(\text{Im } z)^4} \sup_{\|v\|=\|w\|=1} \sum_{i=1}^n |\langle v, (Z_i - Z'_i)w \rangle|^2. \end{aligned}$$

On the other hand, we have

$$\begin{aligned} & \sum_{i=1}^n |\langle v_*, (z\mathbf{1} - X)^{-1}(Z_i - Z'_i)(z\mathbf{1} - X^{\sim i})^{-1}(Z_i - Z'_i)(z\mathbf{1} - X)^{-1}w_* \rangle|^2 \\ & \leq \sum_{i=1}^n \|(Z_i - Z'_i)(\bar{z}\mathbf{1} - X)^{-1}v_*\|^2 \|(z\mathbf{1} - X^{\sim i})^{-1}(Z_i - Z'_i)(z\mathbf{1} - X)^{-1}w_*\|^2 \\ & \leq \frac{4R(X)^2}{(\text{Im } z)^4} \sum_{i=1}^n \langle (z\mathbf{1} - X)^{-1}w_*, (Z_i - Z'_i)^2(z\mathbf{1} - X)^{-1}w_* \rangle \\ & \leq \frac{4R(X)^2}{(\text{Im } z)^6} \left\| \sum_{i=1}^n (Z_i - Z'_i)^2 \right\|. \end{aligned}$$

The conclusion follows readily using $(a + b)^2 \leq 2a^2 + 2b^2$. \square

Next, we bound the expectation of the random variable W .

Lemma 5.8. *Let W be defined as in Lemma 5.7. Then*

$$\mathbf{E}[W] \lesssim \frac{\sigma_*(X)^2}{(\text{Im } z)^4} + \frac{R(X)\mathbf{E}\|X - \mathbf{E}X\|}{(\text{Im } z)^4} + \frac{R(X)^2\mathbf{E}\|X - \mathbf{E}X\|^2}{(\text{Im } z)^6}.$$

Proof. First note that as $(a - b)^2 \leq 2a^2 + 2b^2$ and as (Z_1, \dots, Z_n) and (Z'_1, \dots, Z'_n) have the same distribution, we can estimate

$$\mathbf{E}[W] \leq \frac{8}{(\text{Im } z)^4} \mathbf{E} \left[\sup_{\|v\|=\|w\|=1} \sum_{i=1}^n |\langle v, Z_i w \rangle|^2 \right] + \frac{8}{(\text{Im } z)^6} R(X)^2 \mathbf{E} \left\| \sum_{i=1}^n (Z_i - Z'_i)^2 \right\|.$$

To estimate the first term, we apply [22, Theorem 11.8] to obtain

$$\begin{aligned} & \mathbf{E} \left[\sup_{\|v\|=\|w\|=1} \sum_{i=1}^n (\operatorname{Re} \langle v, Z_i w \rangle)^2 \right] \\ & \leq 8R(X) \mathbf{E} \left[\sup_{\|v\|=\|w\|=1} \sum_{i=1}^n \operatorname{Re} \langle v, Z_i w \rangle \right] + \sup_{\|v\|=\|w\|=1} \sum_{i=1}^n \mathbf{E}[(\operatorname{Re} \langle v, Z_i w \rangle)^2], \\ & \leq 8R(X) \mathbf{E}\|X - \mathbf{E}X\| + \sigma_*(X)^2, \end{aligned}$$

and analogously when the real part is replaced by the imaginary part. Thus

$$\mathbf{E} \left[\sup_{\|v\|=\|w\|=1} \sum_{i=1}^n |\langle v, Z_i w \rangle|^2 \right] \leq 2\sigma_*(X)^2 + 16R(X)\mathbf{E}\|X - \mathbf{E}X\|.$$

To estimate the second term, note that

$$\begin{aligned} \mathbf{E} \left\| \sum_{i=1}^n (Z_i - Z'_i)^2 \right\| &= \mathbf{E} \left\| \mathbf{E}_\varepsilon \left[\left(\sum_{i=1}^n \varepsilon_i (Z_i - Z'_i) \right)^2 \right] \right\| \leq \mathbf{E} \left\| \sum_{i=1}^n \varepsilon_i (Z_i - Z'_i) \right\|^2 \\ &= \mathbf{E} \left\| \sum_{i=1}^n (Z_i - Z'_i) \right\|^2 \leq 4\mathbf{E}\|X - \mathbf{E}X\|^2, \end{aligned}$$

where $\varepsilon_1, \dots, \varepsilon_n$ are i.i.d. random signs independent of Z, Z' and \mathbf{E}_ε denotes the expectation with respect to the variables ε_i only. The first equality is trivial, the first inequality is by Jensen, the second equality holds by the exchangeability of (Z_i, Z'_i) , and the second inequality follows by the triangle inequality and $(a+b)^2 \leq 2a^2 + 2b^2$. Combining the above estimates completes the proof. \square

Finally, we show that W has a self-bounding property.

Lemma 5.9. *Let W be defined as in Lemma 5.7, and define*

$$W^{\sim i} := \frac{2}{(\operatorname{Im} z)^4} \sup_{\|v\|=\|w\|=1} \sum_{j \neq i} |\langle v, (Z_j - Z'_j)w \rangle|^2 + \frac{8}{(\operatorname{Im} z)^6} R(X)^2 \left\| \sum_{j \neq i} (Z_j - Z'_j)^2 \right\|.$$

Then $W^{\sim i} \leq W$ and

$$\sum_{i=1}^n (W - W^{\sim i})^2 \leq \left\{ \frac{16R(X)^2}{(\operatorname{Im} z)^4} + \frac{64R(X)^4}{(\operatorname{Im} z)^6} \right\} W.$$

Proof. That $W^{\sim i} \leq W$ is obvious. To prove the self-bounding inequality, let u_*, v_*, w_* be (random) vectors in the unit sphere such that

$$\sup_{\|v\|=\|w\|=1} \sum_{i=1}^n |\langle v, (Z_i - Z'_i)w \rangle|^2 = \sum_{i=1}^n |\langle v_*, (Z_i - Z'_i)w_* \rangle|^2$$

and

$$\left\| \sum_{i=1}^n (Z_i - Z'_i)^2 \right\| = \sup_{\|u\|=1} \sum_{i=1}^n \|(Z_i - Z'_i)u\|^2 = \sum_{i=1}^n \|(Z_i - Z'_i)u_*\|^2.$$

Then

$$W - W^{\sim i} \leq \frac{2}{(\operatorname{Im} z)^4} |\langle v_*, (Z_i - Z'_i)w_* \rangle|^2 + \frac{8}{(\operatorname{Im} z)^6} R(X)^2 \|(Z_i - Z'_i)u_*\|^2.$$

Therefore,

$$\begin{aligned}
& \sum_{i=1}^n (W - W^{\sim i})^2 \\
& \leq \frac{8}{(\text{Im } z)^8} \sum_{i=1}^n |\langle v_*, (Z_i - Z'_i) w_* \rangle|^4 + \frac{128}{(\text{Im } z)^{12}} R(X)^4 \sum_{i=1}^n \|(Z_i - Z'_i) u_*\|^4 \\
& \leq \frac{32}{(\text{Im } z)^8} R(X)^2 \sum_{i=1}^n |\langle v_*, (Z_i - Z'_i) w_* \rangle|^2 + \frac{512}{(\text{Im } z)^{12}} R(X)^6 \sum_{i=1}^n \|(Z_i - Z'_i) u_*\|^2 \\
& \leq \frac{16R(X)^2}{(\text{Im } z)^4} \cdot \frac{2}{(\text{Im } z)^4} \sup_{\|v\|=\|w\|=1} \sum_{i=1}^n |\langle v, (Z_i - Z'_i) w \rangle|^2 \\
& \quad + \frac{64R(X)^4}{(\text{Im } z)^6} \cdot \frac{8}{(\text{Im } z)^6} R(X)^2 \left\| \sum_{i=1}^n (Z_i - Z'_i)^2 \right\|.
\end{aligned}$$

The conclusion follows from the definition of W . \square

We can now complete the proof of Proposition 5.6.

Proof of Proposition 5.6. We begin by noting that the self-bounding property established in Lemma 5.9 implies, by [22, Theorem 6.19], that

$$\log \mathbf{E}[e^{W/a}] \leq \frac{2}{a} \mathbf{E}[W], \quad a = \frac{16R(X)^2}{(\text{Im } z)^4} + \frac{64R(X)^4}{(\text{Im } z)^6}. \quad (5.1)$$

On the other hand, the estimate of Lemma 5.7 implies, by the exponential Poincaré inequality [22, Theorem 6.16], that for $0 \leq \lambda < a^{-\frac{1}{2}}$

$$\log \mathbf{E}[e^{\lambda \{\|(z\mathbf{1} - X)^{-1}\| - \mathbf{E}\|(z\mathbf{1} - X)^{-1}\|\}}] \leq \frac{\lambda^2 a}{1 - \lambda^2 a} \log \mathbf{E}[e^{W/a}].$$

Combining these estimates with a Chernoff bound [22, p. 29] yields

$$\mathbf{P}[\|(z\mathbf{1} - X)^{-1}\| \geq \mathbf{E}\|(z\mathbf{1} - X)^{-1}\| + \sqrt{8\mathbf{E}[W]x} + \sqrt{a}x] \leq e^{-x}$$

for all $x \geq 0$. This yields a tail bound for deviation above the mean.

We must now prove a tail bound for deviation below the mean. This requires a variant of the second inequality of [22, Theorem 6.16], whose proof we spell out for completeness. The last inequality of [22, Theorem 6.15] and Lemma 5.7 imply

$$\text{Ent}[e^{-\lambda \{\|(z\mathbf{1} - X)^{-1}\|\}}] \leq \lambda^2 \vartheta(\lambda b) \mathbf{E}[We^{-\lambda \{\|(z\mathbf{1} - X)^{-1}\|\}}], \quad b = \frac{2R(X)}{(\text{Im } z)^2}$$

for $\lambda \geq 0$, where $\text{Ent}(Z) := \mathbf{E}[Z \log Z] - \mathbf{E}[Z] \log \mathbf{E}[Z]$ and we used that $\vartheta(x) := \frac{e^x - 1}{x}$ is a positive increasing function. In particular, as $b^2 \leq a$ and $\vartheta(1) \leq 2$,

$$\text{Ent}[e^{-\lambda \{\|(z\mathbf{1} - X)^{-1}\|\}}] \leq 2\lambda^2 \mathbf{E}[We^{-\lambda \{\|(z\mathbf{1} - X)^{-1}\|\}}]$$

for $0 \leq \lambda \leq a^{-\frac{1}{2}}$. Applying the duality formula of entropy as in [22, p. 187] yields

$$\text{Ent}[e^{-\lambda \{\|(z\mathbf{1} - X)^{-1}\|\}}] \leq \frac{2\lambda^2 a}{1 - 2\lambda^2 a} \log \mathbf{E}[e^{W/a}] \mathbf{E}[e^{-\lambda \{\|(z\mathbf{1} - X)^{-1}\|\}}]$$

for $0 \leq \lambda \leq (2a)^{-\frac{1}{2}}$. Therefore

$$\frac{d}{d\lambda} \left(\frac{1}{\lambda} \log \mathbf{E}[e^{-\lambda \{\|(z\mathbf{1} - X)^{-1}\|\}}] \right) = \frac{\text{Ent}[e^{-\lambda \{\|(z\mathbf{1} - X)^{-1}\|\}}]}{\lambda^2 \mathbf{E}[e^{-\lambda \{\|(z\mathbf{1} - X)^{-1}\|\}}]} \leq \frac{2a}{1 - 2\lambda^2 a} \log \mathbf{E}[e^{W/a}]$$

for $0 \leq \lambda \leq (2a)^{-\frac{1}{2}}$. Integrating both sides yields

$$\begin{aligned} \log \mathbf{E}[e^{-\lambda \{\|(z\mathbf{1}-X)^{-1}\| - \mathbf{E}\|(z\mathbf{1}-X)^{-1}\|\}}] &\leq \lambda \sqrt{2a} \operatorname{arctanh}(\lambda \sqrt{2a}) \log \mathbf{E}[e^{W/a}] \\ &\leq \frac{2\lambda^2 a}{1 - \lambda \sqrt{2a}} \log \mathbf{E}[e^{W/a}] \leq \frac{4\mathbf{E}[W]\lambda^2}{1 - \lambda \sqrt{2a}}, \end{aligned}$$

where we used $\operatorname{arctanh}(x) \leq \frac{x}{1-x}$ in the second inequality and (5.1) in the last inequality. We can now apply a Chernoff bound [22, p. 29] to obtain

$$\mathbf{P}[\|(z\mathbf{1}-X)^{-1}\| \leq \mathbf{E}\|(z\mathbf{1}-X)^{-1}\| - 4\sqrt{\mathbf{E}[W]x} - \sqrt{2a}x] \leq e^{-x}$$

for all $x \geq 0$. This yields a tail bound for deviation below the mean.

To conclude the proof, it remains to combine the upper and lower tail bounds by the union bound, and to use Lemma 5.8 to estimate $\mathbf{E}[W]$. \square

5.2.3. Spectral statistics. Theorem 2.10 establishes universality of the expectations of spectral statistics of the form $\langle v, \varphi(X)w \rangle$. A corresponding tail bound would follow if we can prove a concentration inequality for such spectral statistics. This problem turns out to be subtle even in the Gaussian case: even when φ is Lipschitz, the Lipschitz property of $(g_1, \dots, g_N) \mapsto \langle v, \varphi(G)w \rangle$ is not obvious. Deep results on the latter problem [30] could be applied in the Gaussian setting, but do not appear to be sufficiently powerful to handle the non-Gaussian case.

Here we take a different approach. Using functional calculus [37, §2.2], $\varphi(X)$ can be expressed as an integral of the resolvent of X . (We will use an essentially equivalent formulation that appears in the proof of [47, Theorem 6.2].) With this representation in hand, we can readily repeat the proof of Proposition 5.6 to obtain a concentration inequality. The main result of this section is the following.

Proposition 5.10. *For $\varphi \in W^{4,1}(\mathbb{R})$ and $v, w \in \mathbb{R}^d$ with $\|v\| = \|w\| = 1$, we have*

$$\mathbf{P}[|\langle v, \varphi(G)w \rangle - \mathbf{E}[\langle v, \varphi(G)w \rangle]| \geq \|\varphi\|_{W^{3,1}} \sigma_*(X) \sqrt{x}] \leq 4e^{-Cx}$$

and

$$\begin{aligned} \mathbf{P}[|\langle v, \varphi(X)w \rangle - \mathbf{E}[\langle v, \varphi(X)w \rangle]| \geq \|\varphi\|_{W^{4,1}} \{(R(X) + R(X)^2)x \\ + (\sigma_*(X) + R(X)^{\frac{1}{2}}(\mathbf{E}\|X - \mathbf{E}X\|)^{\frac{1}{2}} + R(X)(\mathbf{E}\|X - \mathbf{E}X\|^2)^{\frac{1}{2}})\sqrt{x}\}] \leq 4e^{-Cx} \end{aligned}$$

for all $x \geq 0$, where C is a universal constant.

The basis for the proof is the following identity.

Lemma 5.11. *For any $M \in \mathbf{M}_d(\mathbb{C})_{\text{sa}}$, $p \in \mathbb{N}$, and $\varphi \in C_c^\infty(\mathbb{R})$, we have*

$$\begin{aligned} \varphi(M) = -\frac{1}{\pi} \lim_{\varepsilon \downarrow 0} \operatorname{Im} \int_{-\infty}^{\infty} \left(1 + \frac{d}{dx}\right)^p \varphi(x) \times \\ \frac{(1+i)^p}{(p-1)!} \int_0^\infty ((x+t+i(\varepsilon+t))\mathbf{1} - M)^{-1} t^{p-1} e^{-(1+i)t} dt dx. \end{aligned}$$

Proof. The identity follows by following verbatim the proof of [47, Theorem 6.2], noting that we can express $\langle v, \varphi(M)v \rangle = \int \varphi(x) \mu_v(dx)$ for some measure μ_v (the spectral distribution of M with respect to the state $\tau_v(M) := \langle v, Mv \rangle$). \square

We can now use the above representation to establish discrete (and continuous) gradient bounds of $\langle v, \varphi(X)w \rangle$ along the lines of Lemma 5.7.

Lemma 5.12. *Let $X = Z_0 + \sum_{j=1}^n Z_j$ as in (2.1), define $X^{\sim i}$ as in Lemma 5.7, let $G = A_0 + \sum_{i=1}^N g_i A_i$ as in the proof of Lemma 5.5, and let $\|v\| = \|w\| = 1$.*

- a. *The function $(g_1, \dots, g_N) \mapsto \langle v, \varphi(G)w \rangle$ is $C\|\varphi\|_{W^{3,1}\sigma_*}(X)$ -Lipschitz.*
- b. $|\langle v, \varphi(X)w \rangle - \langle v, \varphi(X^{\sim i})w \rangle| \lesssim \|\varphi\|_{W^{3,1}} R(X)$.
- c. $\sum_{i=1}^n |\langle v, \varphi(X)w \rangle - \langle v, \varphi(X^{\sim i})w \rangle|^2 \lesssim \|\varphi\|_{W^{4,1}}^2 V$.

Here C is a universal constant, and V is defined as W in Lemma 5.7 with $\text{Im } z = 1$.

Proof. By a routine approximation argument, we may assume that $\varphi \in C_c^\infty(\mathbb{R})$. Now note that $\langle v, (z\mathbf{1} - G)^{-1}w \rangle$ is $\frac{\sigma_*(X)}{(\text{Im } z)^2}$ -Lipschitz as in the proof of Lemma 5.5. Thus Lemma 5.11 with $p = 3$ shows that $\langle v, \varphi(G)w \rangle$ is Lipschitz with constant

$$\frac{1}{\pi} \cdot 3\|\varphi\|_{W^{3,1}} \cdot \lim_{\varepsilon \downarrow 0} \frac{(\sqrt{2})^3}{2!} \int_0^\infty \frac{\sigma_*(X)}{(\varepsilon + t)^2} t^2 e^{-t} dt \lesssim \|\varphi\|_{W^{3,1}\sigma_*(X)},$$

which establishes part a. Part b. follows in precisely the same manner using that $|\langle v, (z\mathbf{1} - X)^{-1}w \rangle - \langle v, (z\mathbf{1} - X^{\sim i})^{-1}w \rangle| \leq \frac{2R(X)}{(\text{Im } z)^2}$ as in the proof of Lemma 5.7.

For part c., we begin by applying Lemma 5.11 with $p = 4$ to estimate

$$\left(\sum_{i=1}^n |\langle v, \varphi(X)w \rangle - \langle v, \varphi(X^{\sim i})w \rangle|^2 \right)^{\frac{1}{2}} \leq \frac{4}{3!\pi} \int_{-\infty}^\infty \left| \left(1 + \frac{d}{dx} \right)^4 \varphi(x) \right| \times \int_0^\infty \left(\sum_{i=1}^n |\langle v, ((x+t+it)\mathbf{1} - X)^{-1}w \rangle - \langle v, ((x+t+it)\mathbf{1} - X^{\sim i})^{-1}w \rangle|^2 \right)^{\frac{1}{2}} t^3 e^{-t} dt dx,$$

where we used the triangle inequality to bring the Euclidean norm with respect to the index i inside the integral. But it follows as in the proof of Lemma 5.7 that the quantity inside the brackets on the second line is bounded by the random variable W of Lemma 5.7 with $\text{Im } z = t$. The conclusion follows readily. \square

We can now complete the proof of Proposition 5.10.

Proof of Proposition 5.10. By rescaling φ , we may assume without loss of generality that $\|\varphi\|_{W^{3,1}} = 1$ (Gaussian case) or $\|\varphi\|_{W^{4,1}} = 1$ (non-Gaussian case). By a union bound, it suffices to consider separately the real and imaginary parts of $\langle v, \varphi(G)w \rangle$ and $\langle v, \varphi(X)w \rangle$, respectively. The conclusion now follows using Lemma 5.12 by repeating the proofs of Lemma 5.5 and Proposition 5.6 verbatim with $\text{Im } z = 1$. \square

6. UNIVERSALITY OF SPECTRAL STATISTICS

The aim of this section is to prove our main universality principles for spectral statistics. The basic idea behind the proofs is that we will interpolate between the non-Gaussian and Gaussian models, and estimate the rate of change along the interpolation by means of the cumulant expansion and trace inequalities. This program will be implemented for the moments, resolvent moments, and resolvent in sections 6.2, 6.3, and 6.4, respectively. Before we do so, however, we first introduce some basic constructions that are common to all the proofs.

6.1. Preliminaries. We always fix a random matrix X as in (2.1), and let G be its Gaussian model. Throughout this section, we will further assume that X and G are independent of each other; this will entail no loss of generality, as the universality results that are proved in this section—Theorems 2.9, 2.10, and 6.8—are independent of the joint distribution of X and G . Define

$$X(t) := \mathbf{E}X + \sqrt{t}(X - \mathbf{E}X) + \sqrt{1-t}(G - \mathbf{E}G), \quad t \in [0, 1].$$

The random matrix $X(t)$ interpolates between $X(1) = X$ and $X(0) = G$, where the interpolation is chosen so that $\mathbf{E}X(t)$ and $\text{Cov}(X(t))$ are independent of t . The basic principle behind all the proofs of this section is that we aim to compute $\frac{d}{dt}\mathbf{E}[f(X(t))]$ for the relevant spectral statistic $f : M_d(\mathbb{C})_{\text{sa}} \rightarrow \mathbb{C}$ using the cumulant expansion. To this end, we will choose the random vector Y_i in the statements of Theorems 4.3 and 4.4 to be the $2d^2$ -dimensional vector of the real and imaginary parts of the entries of the random matrix Z_i . In the following, we will apply the notation for partitions in section 4.1 without further comment.

For our purposes, it will be convenient to reformulate the resulting expansions by combining them with the cumulant formula of Lemma 4.1. Before we can do so, we must introduce a simple construction that will facilitate working with the second identity of Lemma 4.1. For any $k \in \mathbb{N}$ and partition $\pi \in P([k])$, define random matrices $Z_{i1|\pi}, \dots, Z_{ik|\pi}$ ($i \in [n]$) with the following properties:

1. $(Z_{ij|\pi})_{i \in [n]}$ has the same distribution as $(Z_i)_{i \in [n]}$.
2. $(Z_{ij|\pi})_{i \in [n]} = (Z_{ij'|\pi})_{i \in [n]}$ for indices j, j' that belong to the same element of π .
3. $(Z_{ij|\pi})_{i \in [n]}$ are independent for indices j that belong to distinct elements of π .
4. $(Z_{ij|\pi})_{i \in [n], j \in [k]}$ is independent of X and G .

This construction will be fixed in the sequel. (We do not specify the joint distribution of these matrices for different k, π as these will not arise in the analysis.) We can now state a version of Theorem 4.3 in the present setting.

Corollary 6.1. *For any $f : M_d(\mathbb{C})_{\text{sa}} \rightarrow \mathbb{C}$ that is polynomial in the matrix entries,*

$$\begin{aligned} \frac{d}{dt}\mathbf{E}[f(X(t))] &= \\ &\frac{1}{2} \sum_{k=3}^{\infty} \frac{t^{\frac{k}{2}-1}}{(k-1)!} \sum_{\pi \in P([k])} (-1)^{|\pi|-1} (|\pi|-1)! \mathbf{E} \left[\sum_{i=1}^n \partial_{Z_{i1|\pi}} \cdots \partial_{Z_{ik|\pi}} f(X(t)) \right] \end{aligned}$$

where $\partial_B f$ denotes the directional derivative of f in the direction $B \in M_d(\mathbb{C})_{\text{sa}}$.

Proof. We can clearly write $G - \mathbf{E}G = \sum_{i=1}^n G_i$, where G_i is the Gaussian model associated to Z_i and G_1, \dots, G_n are independent.

Let $\iota : M_d(\mathbb{C}) \rightarrow \mathbb{R}^{2d^2}$ be defined by $\iota(M) := (\text{Re } M_{uv}, \text{Im } M_{uv})_{u,v \in [d]}$, let $Y_i = \iota(Z_i)$ and $U_i = \iota(G_i)$, and define $Y(t)$ as in Theorem 4.3. Then we have

$$\iota(X(t)) = \iota(\mathbf{E}X) + \sum_{i=1}^n Y_i(t).$$

In particular, we can equivalently view $f(X(t)) = f(\mathbf{E}X + \sum_{i=1}^n \iota^{-1}(Y_i(t)))$ as a function of $Y(t)$. Applying Theorem 4.3 to the latter yields

$$\begin{aligned} \frac{d}{dt} \mathbf{E}[f(X(t))] &= \frac{1}{2} \sum_{k=3}^{\infty} \frac{t^{\frac{k}{2}-1}}{(k-1)!} \times \\ &\quad \sum_{i=1}^n \sum_{\substack{(u_j, v_j, \alpha_j) \in \mathcal{I} \\ j=1, \dots, k}} \kappa((Z_i)_{u_1 v_1}^{\alpha_1}, \dots, (Z_i)_{u_k v_k}^{\alpha_k}) \mathbf{E} \left[\frac{\partial^k f}{\partial M_{u_1 v_1}^{\alpha_1} \cdots \partial M_{u_k v_k}^{\alpha_k}} (X(t)) \right], \end{aligned}$$

where $\mathcal{I} := [d] \times [d] \times \{\text{R, I}\}$ and we denote $M_{uv}^{\text{R}} := \text{Re } M_{uv}$ and $M_{uv}^{\text{I}} := \text{Im } M_{uv}$. The conclusion follows by applying the second identity of Lemma 4.1 to the cumulant, and using the independence structure of $Z_{ij|\pi}$ to merge the product of expectations in the resulting identity into a single expectation. \square

The following is the analogous version of Theorem 4.4.

Corollary 6.2. *For any $p \geq 3$ and smooth function $f : \mathbf{M}_d(\mathbb{C}) \rightarrow \mathbb{C}$ we have*

$$\begin{aligned} \frac{d}{dt} \mathbf{E}[f(X(t))] &= \\ \frac{1}{2} \sum_{k=3}^{p-1} \frac{t^{\frac{k}{2}-1}}{(k-1)!} \sum_{\pi \in \mathbf{P}([k])} (-1)^{|\pi|-1} (|\pi|-1)! \mathbf{E} \left[\sum_{i=1}^n \partial_{Z_{i1|\pi}} \cdots \partial_{Z_{ik|\pi}} f(X(t)) \right] &+ \mathcal{R}, \end{aligned}$$

where the remainder term satisfies

$$\begin{aligned} |\mathcal{R}| &\lesssim \sup_{s, t \in [0, 1]} \left\{ \left| \sum_{i=1}^n \mathbf{E}[\partial_{Z_i}^p f(X(t, i, s))] \right| + \right. \\ &\quad \left. \max_{2 \leq k \leq p-1} \left| \sum_{\pi \in \mathbf{P}([k])} \frac{(-1)^{|\pi|-1} (|\pi|-1)!}{(k-1)!} \sum_{i=1}^n \mathbf{E}[\partial_{Z_i}^{p-k} \partial_{Z_{i1|\pi}} \cdots \partial_{Z_{ik|\pi}} f(X(t, i, s))] \right| \right\} \end{aligned}$$

with $X(t, i, s) := X(t) - (1-s)\sqrt{t}Z_i$.

Proof. The conclusion follows from Theorem 4.4 in exactly the same manner as we derived Corollary 6.1 from Theorem 4.3. \square

6.2. Moments. The aim of this section is to show that the moments $\mathbf{E}[\text{tr } X^{2p}]$ are close to their Gaussian analogues $\mathbf{E}[\text{tr } G^{2p}]$. To this end, we will first compute $\frac{d}{dt} \mathbf{E}[\text{tr } X(t)^{2p}]$ by means of the cumulant expansion, and then estimate the individual terms to obtain a differential inequality.

We begin by computing the derivatives of the moment function $M \mapsto \text{tr}[M^{2p}]$.

Lemma 6.3. *Let $p \in \mathbb{N}$ and $B_1, \dots, B_k \in \mathbf{M}_d(\mathbb{C})_{\text{sa}}$. Then*

$$\begin{aligned} \partial_{B_1} \cdots \partial_{B_k} \text{tr}[M^{2p}] &= \\ \sum_{\sigma \in \text{Sym}(k)} \sum_{\substack{r_1, \dots, r_{k+1} \geq 0 \\ r_1 + \cdots + r_{k+1} = 2p-k}} \text{tr}[M^{r_1} B_{\sigma(1)} M^{r_2} B_{\sigma(2)} \cdots M^{r_k} B_{\sigma(k)} M^{r_{k+1}}]. \end{aligned}$$

Proof. This follows by applying the product rule k times. \square

We will also need the following estimate.

Lemma 6.4. *For any $k \in \mathbb{N}$, we have*

$$\sum_{\pi \in P([k])} (|\pi| - 1)! \leq 2^k (k - 1)!.$$

Proof. We first crudely estimate

$$\sum_{\pi \in P([k])} (|\pi| - 1)! \leq \sum_{\pi \in P([k])} (|\pi| - 1)! \prod_{J \in \pi} |J|!.$$

Now note that any partition of $[k]$ into m parts can be generated by first choosing $r_1, \dots, r_m \geq 1$ such that $r_1 + \dots + r_m = k$, and then choosing disjoint sets J_1, \dots, J_m with $|J_i| = r_i$. Moreover, each distinct partition is generated precisely $m!$ times in this manner, as relabeling the sets J_i does not change the partition. Therefore

$$\begin{aligned} \sum_{\pi \in P([k])} (|\pi| - 1)! \prod_{J \in \pi} |J|! &= \sum_{m=1}^k (m-1)! \frac{1}{m!} \sum_{\substack{r_1, \dots, r_m \geq 1 \\ r_1 + \dots + r_m = k}} \binom{k}{r_1, \dots, r_m} \prod_{j=1}^m r_j! \\ &= (k-1)! \sum_{m=1}^k \binom{k}{m} = (2^k - 1)(k-1)!, \end{aligned}$$

where the second equality follows as the number of m -tuples of positive integers that sum to k is $\binom{k-1}{m-1}$, and the last equality holds by the binomial theorem. \square

We are now ready to apply the cumulant expansion.

Proposition 6.5. *For any $p \in \mathbb{N}$ with $p \geq 2$, $2p \leq q \leq \infty$, and $t \in [0, 1]$, we have*

$$\begin{aligned} \left| \frac{d}{dt} \mathbf{E}[\text{tr } X(t)^{2p}] \right| &\leq 64p^3 \max\{R_q(X)\sigma_q(X)^2, R_q(X)^3\} \times \\ &\quad \max\{\mathbf{E}[\text{tr } X(t)^{2p}]^{1-\frac{3}{2p}}, (8pR_q(X))^{2p-3}\}. \end{aligned}$$

Proof. Combining Corollary 6.1 and Lemma 6.3 yields

$$\begin{aligned} \frac{d}{dt} \mathbf{E}[\text{tr } X(t)^{2p}] &= \frac{1}{2} \sum_{k=3}^{2p} k t^{\frac{k}{2}-1} \sum_{\pi \in P([k])} (-1)^{|\pi|-1} (|\pi| - 1)! \times \\ &\quad \sum_{\substack{r_1, \dots, r_{k+1} \geq 0 \\ r_1 + \dots + r_{k+1} = 2p-k}} \sum_{i=1}^n \mathbf{E}[\text{tr } X(t)^{r_1} Z_{i1|\pi} X(t)^{r_2} Z_{i2|\pi} \cdots X(t)^{r_k} Z_{ik|\pi} X(t)^{r_{k+1}}]. \end{aligned}$$

Here we used that as $(Z_{i\sigma(j)|\pi})_{i \in [n], j \in [k]}$ and $(Z_{ij|\sigma^{-1}(\pi)})_{i \in [n], j \in [k]}$ have the same distribution for any permutation σ , we can eliminate the sum over σ in Lemma 6.3 by symmetry. Now let $r = \frac{(2p-k)q}{q-k}$, so that $2p - k \leq r \leq 2p$. Let $p_j = \frac{r}{r_{j+1}}$ for $j < k$ and $p_k = \frac{r}{r_{k+1} + r_1}$. Then we can apply Proposition 5.1 to estimate

$$\begin{aligned} &\left| \sum_{i=1}^n \mathbf{E}[\text{tr } X(t)^{r_1} Z_{i1|\pi} X(t)^{r_2} Z_{i2|\pi} \cdots X(t)^{r_k} Z_{ik|\pi} X(t)^{r_{k+1}}] \right| \\ &\leq R_q(X)^{\frac{(k-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-k)}{q-2}} \mathbf{E}[\text{tr } X(t)^r]^{\frac{2p-k}{r}} \\ &\leq R_q(X)^{\frac{(k-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-k)}{q-2}} \mathbf{E}[\text{tr } X(t)^{2p}]^{1-\frac{k}{2p}} \end{aligned}$$

for any $r_1, \dots, r_{k+1} \geq 0$ with $r_1 + \dots + r_{k+1} = 2p - k$. It follows that

$$\left| \frac{d}{dt} \mathbf{E}[\operatorname{tr} X(t)^{2p}] \right| \leq \frac{1}{2} \sum_{k=3}^{2p} (4p)^k R_q(X)^{\frac{(k-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-k)}{q-2}} \mathbf{E}[\operatorname{tr} X(t)^{2p}]^{1-\frac{k}{2p}}$$

using Lemma 6.4, $t \leq 1$, and that the number of $(k+1)$ -tuples of nonnegative integers that sum to $2p - k$ is $\binom{2p}{k} \leq \frac{(2p)^k}{k!}$. To simplify the expression, we estimate

$$\begin{aligned} \left| \frac{d}{dt} \mathbf{E}[\operatorname{tr} X(t)^{2p}] \right| &\leq \frac{1}{2} \sum_{k=3}^{2p} 2^{-k} (8p)^k R_q(X)^{\frac{(k-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-k)}{q-2}} \mathbf{E}[\operatorname{tr} X(t)^{2p}]^{1-\frac{k}{2p}} \\ &\leq \frac{1}{8} \max_{3 \leq k \leq 2p} (8p)^k R_q(X)^{\frac{(k-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-k)}{q-2}} \mathbf{E}[\operatorname{tr} X(t)^{2p}]^{1-\frac{k}{2p}} \\ &\leq 64p^3 \max \left\{ R_q(X)^{\frac{q}{q-2}} \sigma_q(X)^{\frac{2(q-3)}{q-2}} \mathbf{E}[\operatorname{tr} X(t)^{2p}]^{1-\frac{3}{2p}}, \right. \\ &\quad \left. (8p)^{2p-3} R_q(X)^{\frac{(2p-2)q}{q-2}} \sigma_q(X)^{\frac{2(q-2p)}{q-2}} \right\}. \end{aligned}$$

Here we used that the term inside the maximum on the second line is convex as a function of k , so that the maximum is attained at one of the endpoints $k \in \{3, 2p\}$. The proof is readily concluded using that $R^{\frac{q}{q-2}-1} \sigma^{\frac{2(q-3)}{q-2}} \leq (\max\{R, \sigma\})^2$ and $R^{\frac{(2p-2)q}{q-2}-(2p-3)-1} \sigma^{\frac{2(q-2p)}{q-2}} \leq (\max\{R, \sigma\})^2$ (as $q \geq 2p \geq 4$ implies that in both cases the exponents on the left-hand side are positive and sum to 2). \square

It remains to solve the differential inequality in the statement of Proposition 6.5. To this end we will use the following simple lemma.

Lemma 6.6. *Let $f : [0, 1] \rightarrow \mathbb{R}_+$, $C, K \geq 0$, and $\alpha \in [0, 1]$. Suppose that*

$$\left| \frac{d}{dt} f(t) \right| \leq C \max\{f(t)^{1-\alpha}, K^{1-\alpha}\}$$

for all $t \in [0, 1]$. Then

$$|f(1)^\alpha - f(0)^\alpha| \leq C\alpha + K^\alpha.$$

Proof. It follows readily by the chain rule that

$$\left| \frac{d}{dt} (f(t) + K)^\alpha \right| = \alpha (f(t) + K)^{\alpha-1} \left| \frac{d}{dt} f(t) \right| \leq C\alpha,$$

so that

$$|(f(1) + K)^\alpha - (f(0) + K)^\alpha| = \left| \int_0^1 \frac{d}{dt} (f(t) + K)^\alpha dt \right| \leq C\alpha.$$

The conclusion follows as $x^\alpha - y^\alpha \leq (x+K)^\alpha - (y+K)^\alpha + K^\alpha$ for any $x, y \geq 0$. \square

We can now conclude the proof of Theorem 2.9.

Proof of Theorem 2.9: first inequality. If $p = 1$, then $\mathbf{E}[\operatorname{tr} X(t)^{2p}] = \mathbf{E}[\operatorname{tr} X^2]$ is independent of t by construction, and the conclusion is trivial. If $p \geq 2$, we can apply Lemma 6.6 with $\alpha = \frac{3}{2p} \in [0, 1]$ and Proposition 6.5 to obtain

$$|\mathbf{E}[\operatorname{tr} X^{2p}]^{\frac{3}{2p}} - \mathbf{E}[\operatorname{tr} G^{2p}]^{\frac{3}{2p}}| \leq 96p^2 \max\{R_q(X)\sigma_q(X)^2, R_q(X)^3\} + (8pR_q(X))^3.$$

The conclusion follows as $|x^{\frac{1}{3}} - y^{\frac{1}{3}}| \leq |x - y|^{\frac{1}{3}}$ for $x, y \geq 0$. \square

The second inequality of Theorem 2.9 follows by a slight variation of the proof.

Proof of Theorem 2.9: second inequality. Note that $\sigma_{2p}(X) = \sigma_{2p}(X(t))$ for all t , as the definition of $\sigma_{2p}(X)$ depends only on $\text{Cov}(X)$. We can therefore estimate

$$\sigma_{2p}(X)^{2p} = \text{tr}(\mathbf{E}[X(t)^2] - \mathbf{E}[X(t)]^2)^p \leq \text{tr} \mathbf{E}[X(t)^2]^p \leq \mathbf{E}[\text{tr} X(t)^{2p}]$$

for every $t \in [0, 1]$. Here we used that $\text{tr} A^p \leq \text{tr} B^p$ for $B \geq A \geq 0$, and that $A \mapsto \text{tr} A^p$ is convex for $A \geq 0$ [29, Theorem 2.10]. Furthermore, note that

$$R_{2p}(X) \leq R_2(X)^{\frac{q-2p}{p(q-2)}} R_q(X)^{\frac{(p-1)q}{p(q-2)}} \leq \sigma_{2p}(X)^{\frac{q-2p}{p(q-2)}} R_q(X)^{\frac{(p-1)q}{p(q-2)}}$$

by the Riesz convexity theorem and as $R_2(X) = \sigma_2(X) \leq \sigma_{2p}(X)$. Consequently, we can bound the differential inequality in the proof of Proposition 6.5 as

$$\begin{aligned} \left| \frac{d}{dt} \mathbf{E}[\text{tr} X(t)^{2p}] \right| &\leq \frac{1}{2} \sum_{k=3}^{2p} (4p)^k R_{2p}(X)^{\frac{(k-2)p}{p-1}} \sigma_{2p}(X)^{\frac{2p-k}{p-1}} \mathbf{E}[\text{tr} X(t)^{2p}]^{1-\frac{k}{2p}} \\ &\leq \frac{1}{2} \sum_{k=3}^{2p} (4p)^k R_q(X)^{\frac{(k-2)q}{q-2}} \mathbf{E}[\text{tr} X(t)^{2p}]^{1-\frac{k}{2p}+\frac{q-k}{p(q-2)}} \\ &\leq \frac{1}{8} \max_{3 \leq k \leq 2p} (8p)^k R_q(X)^{\frac{(k-2)q}{q-2}} \mathbf{E}[\text{tr} X(t)^{2p}]^{1-\frac{k}{2p}+\frac{q-k}{p(q-2)}}. \end{aligned}$$

By convexity, we may bound all terms in the maximum by their value at either $k = 2 + \frac{q-2}{q} \leq 3$ or $k = 2 + 2p \frac{q-2}{q} \geq 2p$, so that

$$\left| \frac{d}{dt} \mathbf{E}[\text{tr} X(t)^{2p}] \right| \leq \frac{(8p)^{2+\frac{q-2}{q}} R_q(X)}{8} \max \left\{ \mathbf{E}[\text{tr} X(t)^{2p}]^{1-\frac{1}{2p}}, ((8p)^{\frac{q-2}{q}} R_q(X))^{2p-1} \right\}.$$

The conclusion follows from Lemma 6.6. \square

Remark 6.7. That there is considerable room in the proof of Theorem 2.9 is evident from the crude inequality in the first equation display of the proof of Lemma 6.4. This additional room can be used to capture models whose summands Z_i are not uniformly bounded, but have subexponential tails. For the purposes of this paper, such an extension is not needed as the truncation method that will be developed in section 8 below yields far more general results. However, this extra room can be of significant utility in extending the approach of this paper to random matrices that are not captured by the independent sum model (2.1), cf. [63].

6.3. Resolvent moments. The aim of this section is to prove the following universality principle for the moments of the resolvent. This result will form the basis for the proof of Theorem 2.6 (which is given in section 7 below).

Theorem 6.8 (Resolvent moments universality). *We have*

$$|\mathbf{E}[\text{tr} |z\mathbf{1} - X|^{-2p}]^{\frac{1}{2p}} - \mathbf{E}[\text{tr} |z\mathbf{1} - G|^{-2p}]^{\frac{1}{2p}}| \lesssim \frac{R(X)\sigma(X)^2 p^2 + R(X)^3 p^3}{(\text{Im } z)^4}$$

for any $p \in \mathbb{N}$ and $z \in \mathbb{C}$ with $\text{Im } z > 0$.

The proof of Theorem 6.8 is very similar in spirit to that of Theorem 2.9. However, as the resolvent is not a polynomial (and does not have a globally convergent power series), we must truncate the cumulant expansion as in Corollary 6.2.

We begin by computing the derivatives of $M \mapsto \text{tr} |z\mathbf{1} - M|^{-2p}$.

Lemma 6.9. *Let $z \in \mathbb{C}$ with $\operatorname{Im} z > 0$, $p \in \mathbb{N}$, and $M, B_1, \dots, B_k \in M_d(\mathbb{C})_{\text{sa}}$. Denote the resolvent of M as $R_M(z) := (z\mathbf{1} - M)^{-1}$. Then*

$$\begin{aligned} \partial_{B_1} \cdots \partial_{B_k} \operatorname{tr} |z\mathbf{1} - M|^{-2p} = \\ \sum_{\sigma \in \text{Sym}(k)} \sum_{\substack{l, m \geq 0 \\ l+m=k}} \sum_{\substack{r_1, \dots, r_{l+1} \geq 1 \\ r_1 + \dots + r_{l+1} = p+l}} \sum_{\substack{s_1, \dots, s_{m+1} \geq 1 \\ s_1 + \dots + s_{m+1} = p+m}} \operatorname{tr} [R_M(z)^{r_1} B_{\sigma(1)} \\ \cdots R_M(z)^{r_l} B_{\sigma(l)} R_M(z)^{r_{l+1}} R_M(\bar{z})^{s_1} B_{\sigma(l+1)} \cdots R_M(\bar{z})^{s_m} B_{\sigma(k)} R_M(\bar{z})^{s_{m+1}}]. \end{aligned}$$

In particular,

$$|\partial_{B_1} \cdots \partial_{B_k} \operatorname{tr} |z\mathbf{1} - M|^{-2p}| \leq \frac{(2p-1+k)!}{(2p-1)!} \frac{\|B_1\|_k \cdots \|B_k\|_k}{(\operatorname{Im} z)^{2p+k}}.$$

Proof. The identity follows by applying the product rule k times to $\operatorname{tr} |z\mathbf{1} - M|^{-2p} = \operatorname{tr} [R_M(z)^p R_M(\bar{z})^p]$ and using that $\partial_B R_M(z) = R_M(z) B R_M(z)$. To prove the inequality, note that each summand is bounded by $(\operatorname{Im} z)^{-2p-k} \|B_1\|_k \cdots \|B_k\|_k$ by Hölder's inequality and $\|R_M(z)\| \leq |\operatorname{Im} z|^{-1}$, while the sums have $\frac{(2p-1+k)!}{(2p-1)!}$ terms (the latter is most easily seen by applying the first identity with $d = 1$). \square

We can now apply the cumulant expansion.

Proposition 6.10. *For any $z \in \mathbb{C}$ with $\operatorname{Im} z > 0$, $p \in \mathbb{N}$, and $t \in [0, 1]$, we have*

$$\begin{aligned} \left| \frac{d}{dt} \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p}] \right| \\ \lesssim \frac{p^3 R(X) \sigma(X)^2}{(\operatorname{Im} z)^4} \max \left\{ \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p}]^{1-\frac{1}{2p}}, \frac{(32pR(X))^{6p-3}}{(\operatorname{Im} z)^{8p-4}} \right\}. \end{aligned}$$

Proof. Combining Corollary 6.2 with Lemma 6.9 yields

$$\begin{aligned} \frac{d}{dt} \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p}] = \frac{1}{2} \sum_{k=3}^{6p-1} k t^{\frac{k}{2}-1} \sum_{\pi \in \text{P}([k])} (-1)^{|\pi|-1} (|\pi|-1)! \times \\ \sum_{\substack{l, m \geq 0 \\ l+m=k}} \sum_{\substack{r_1, \dots, r_{l+1} \geq 1 \\ r_1 + \dots + r_{l+1} = p+l}} \sum_{\substack{s_1, \dots, s_{m+1} \geq 1 \\ s_1 + \dots + s_{m+1} = p+m}} \sum_{i=1}^n \mathbf{E}[\operatorname{tr} R_{X(t)}(z)^{r_1} Z_{i1|\pi} \cdots R_{X(t)}(z)^{r_l} Z_{il|\pi} \\ R_{X(t)}(z)^{r_{l+1}} R_{X(t)}(\bar{z})^{s_1} Z_{i(l+1)|\pi} \cdots R_{X(t)}(\bar{z})^{s_m} Z_{ik|\pi} R_{X(t)}(\bar{z})^{s_{m+1}}] + \mathcal{R} \end{aligned}$$

with

$$|\mathcal{R}| \lesssim \frac{(8p-1)!}{(2p-1)!} \frac{2^{6p}}{(\operatorname{Im} z)^{8p}} \sum_{i=1}^n \mathbf{E}[\operatorname{tr} Z_i^{6p}].$$

Here we eliminated the sum over permutations σ in the identity as in the proof of Proposition 6.5, and we used Lemma 6.4 and Hölder's inequality in the estimate of the remainder. To proceed, we apply Proposition 5.1 with $p_j = \frac{2p+k}{r_{j+1}}$ for $1 \leq j < l$, $p_l = \frac{2p+k}{r_{l+1}+s_1}$, $p_j = \frac{2p+k}{s_{j-l+1}}$ for $l < j < k$, $p_k = \frac{2p+k}{s_{m+1}+r_1}$, and $q = \infty$ to estimate

$$\begin{aligned} \left| \sum_{i=1}^n \mathbf{E}[\operatorname{tr} R_{X(t)}(z)^{r_1} Z_{i1|\pi} \cdots R_{X(t)}(z)^{r_l} Z_{il|\pi} R_{X(t)}(z)^{r_{l+1}} R_{X(t)}(\bar{z})^{s_1} Z_{i(l+1)|\pi} \right. \\ \left. \cdots R_{X(t)}(\bar{z})^{s_m} Z_{ik|\pi} R_{X(t)}(\bar{z})^{s_{m+1}}] \right| \leq R(X)^{k-2} \sigma(X)^2 \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p-k}]. \end{aligned}$$

We can therefore estimate

$$\begin{aligned} \left| \frac{d}{dt} \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p}] \right| &\leq C \frac{(8p-1)!}{(2p-1)!} \frac{2^{6p}}{(\operatorname{Im} z)^{8p}} \sum_{i=1}^n \mathbf{E}[\operatorname{tr} Z_i^{6p}] \\ &\quad + \frac{1}{2} \sum_{k=3}^{6p-1} \frac{(2p-1+k)!}{(2p-1)!} 2^k R(X)^{k-2} \sigma(X)^2 \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p-k}] \end{aligned}$$

for a universal constant C , where we used Lemma 6.4 and that the sums over l, m, r_j, s_j contain a total of $\binom{2p-1+k}{2p-1}$ terms (cf. the proof of Lemma 6.9). Thus

$$\begin{aligned} \left| \frac{d}{dt} \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p}] \right| &\leq C \frac{(16p)^{6p}}{(\operatorname{Im} z)^{8p}} R(X)^{6p-2} \sigma(X)^2 \\ &\quad + \frac{1}{2} \sum_{k=3}^{6p-1} (16p)^k R(X)^{k-2} \sigma(X)^2 \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p-k}], \end{aligned}$$

where we used $\frac{(2p-1+k)!}{(2p-1)!} \leq (8p)^k$ for $k \leq 6p$ and $\sum_{i=1}^n \mathbf{E}[\operatorname{tr} Z_i^{6p}] \leq R(X)^{6p-2} \sigma(X)^2$.

We now proceed as in the proof of Proposition 6.5. As the terms inside the sum are convex as a function of k , we can estimate

$$\begin{aligned} &\frac{1}{2} \sum_{k=3}^{6p-1} (16p)^k R(X)^{k-2} \sigma(X)^2 \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p-k}] \\ &\leq \frac{1}{8} \max \{ (32p)^3 R(X) \sigma(X)^2 \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p-3}], \\ &\quad (32p)^{6p} R(X)^{6p-2} \sigma(X)^2 \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-8p}] \} \\ &\leq \frac{(32p)^3 R(X) \sigma(X)^2}{8(\operatorname{Im} z)^4} \max \left\{ \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p}]^{1-\frac{1}{2p}}, \frac{(32pR(X))^{6p-3}}{(\operatorname{Im} z)^{8p-4}} \right\}, \end{aligned}$$

where we used that $\mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p+1}] \leq \mathbf{E}[\operatorname{tr} |z\mathbf{1} - X(t)|^{-2p}]^{1-\frac{1}{2p}}$ by Jensen's inequality, and that $\|(z\mathbf{1} - X(t))^{-1}\| \leq (\operatorname{Im} z)^{-1}$. The conclusion follows readily. \square

The proof of Theorem 6.8 is now immediate.

Proof of Theorem 6.8. Combine Proposition 6.10 and Lemma 6.6. \square

6.4. Resolvent matrix. The aim of this section is to prove the resolvent universality principle of Theorem 2.10. In contrast to the universality principles for the moments and resolvent moments, the present result is much more classical in nature as its proof does not require the cumulant expansion; it could therefore also be approached by means of more traditional universality methods as in [32, 33]. In particular, we will apply Corollary 6.2 with $p = 3$: in this special case, the proof of Corollary 6.2 uses only Taylor expansion and no cumulants appear.

Nonetheless, the present situation is somewhat different in nature than the previous universality results in that we bound the difference between the expected resolvents of X and G in norm (as opposed to their traces, see Remark 6.13 below). This introduces some additional subtleties that must be addressed in the proof.

We begin by applying Corollary 6.2 in the present setting.

Lemma 6.11. *We have*

$$\|\mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}]\| \lesssim \left(\frac{R(X)}{(\text{Im } z)^4} + \frac{R(X)^3}{(\text{Im } z)^6} \right) \mathbf{E} \left\| \sum_{i=1}^n Z_i^2 \right\|.$$

Proof. We readily compute

$$\begin{aligned} \partial_{B_1} \partial_{B_2} \partial_{B_3} (z\mathbf{1} - M)^{-1} = \\ \sum_{\sigma \in \text{Sym}(3)} (z\mathbf{1} - M)^{-1} B_{\sigma(1)} (z\mathbf{1} - M)^{-1} B_{\sigma(2)} (z\mathbf{1} - M)^{-1} B_{\sigma(3)} (z\mathbf{1} - M)^{-1}. \end{aligned}$$

Applying Corollary 6.2 to $f(M) = \langle v, (z\mathbf{1} - M)^{-1} w \rangle$ with $p = 3$ yields

$$\begin{aligned} \|\mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}]\| &= \sup_{\|v\| = \|w\| = 1} \left| \int_0^1 \frac{d}{dt} \mathbf{E}[\langle v, (z\mathbf{1} - X(t))^{-1} w \rangle] dt \right| \\ &\lesssim F(Z, Z, Z) + F(Z, Z', Z') + F(Z', Z, Z') + F(Z', Z', Z), \end{aligned}$$

where $Z' = (Z'_i)_{1 \leq i \leq n}$ is an independent copy of $Z = (Z_i)_{1 \leq i \leq n}$,

$$F(Z^{(1)}, Z^{(2)}, Z^{(3)}) = \sup_{\|v\| = \|w\| = 1} \sup_{s, t \in [0, 1]} \left| \sum_{i=1}^n \mathbf{E}[\langle v, \mathbf{R}_{tis} Z_i^{(1)} \mathbf{R}_{tis} Z_i^{(2)} \mathbf{R}_{tis} Z_i^{(3)} \mathbf{R}_{tis} w \rangle] \right|,$$

and $\mathbf{R}_{tis} = (z\mathbf{1} - X(t, i, s))^{-1}$ with $X(t, i, s) = X(t) - (1-s)\sqrt{t}Z_i$. (Note that the term with $|\pi| = 2$ in the bound on $|\mathcal{R}|$ in Corollary 6.2 vanishes as $\mathbf{E}[Z_i] = 0$.)

As $\|\mathbf{R}_{tis}\| \leq (\text{Im } z)^{-1}$ and $\|Z_i\| \leq R(X)$, we have

$$F(Z^{(1)}, Z^{(2)}, Z^{(3)}) \leq \frac{R(X)}{(\text{Im } z)^2} \sup_{\|v\| = \|w\| = 1} \sup_{s, t \in [0, 1]} \sum_{i=1}^n \mathbf{E}[\|Z_i^{(1)} \mathbf{R}_{tis}^* v\| \|Z_i^{(3)} \mathbf{R}_{tis} w\|].$$

Now note that as $A^{-1} - B^{-1} = A^{-1}(B - A)B^{-1}$, we have

$$\begin{aligned} \mathbf{R}_{tis} &= \mathbf{R}_t - (1-s)\sqrt{t} \mathbf{R}_{tis} Z_i \mathbf{R}_t, \\ \mathbf{R}_{tis}^* &= \mathbf{R}_t^* - (1-s)\sqrt{t} \mathbf{R}_{tis} Z_i \mathbf{R}_t^* \end{aligned}$$

with $\mathbf{R}_t = (z\mathbf{1} - X(t))^{-1}$. Thus

$$\begin{aligned} \|Z_i^{(3)} \mathbf{R}_{tis} w\| &\leq \|Z_i^{(3)} \mathbf{R}_t w\| + \frac{R(X)}{\text{Im } z} \|Z_i \mathbf{R}_t w\|, \\ \|Z_i^{(1)} \mathbf{R}_{tis}^* v\| &\leq \|Z_i^{(1)} \mathbf{R}_t^* v\| + \frac{R(X)}{\text{Im } z} \|Z_i \mathbf{R}_t^* v\| \end{aligned}$$

for $s, t \in [0, 1]$. Using $(a+b)(c+d) \leq a^2 + b^2 + c^2 + d^2$ yields

$$\begin{aligned} \mathbf{E}[\|Z_i^{(1)} \mathbf{R}_{tis}^* v\| \|Z_i^{(3)} \mathbf{R}_{tis} w\|] &\leq \mathbf{E}[\langle \mathbf{R}_t w, (Z_i^{(3)})^2 \mathbf{R}_t w \rangle] + \mathbf{E}[\langle \mathbf{R}_t^* v, (Z_i^{(1)})^2 \mathbf{R}_t^* v \rangle] + \\ &\quad \frac{R(X)^2}{(\text{Im } z)^2} (\mathbf{E}[\langle \mathbf{R}_t w, Z_i^2 \mathbf{R}_t w \rangle] + \mathbf{E}[\langle \mathbf{R}_t^* v, Z_i^2 \mathbf{R}_t^* v \rangle]). \end{aligned}$$

We can therefore estimate

$$F(Z^{(1)}, Z^{(2)}, Z^{(3)}) \lesssim \left(\frac{R(X)}{(\text{Im } z)^4} + \frac{R(X)^3}{(\text{Im } z)^6} \right) \mathbf{E} \left\| \sum_{i=1}^n Z_i^2 \right\|$$

whenever $Z^{(k)}$ have the same distribution as Z , concluding the proof. \square

We also need the following simple lemma.

Lemma 6.12. *We have*

$$\mathbf{E} \left\| \sum_{i=1}^n Z_i^2 \right\| \lesssim \sigma(X)^2 + R(X)^2 \log d.$$

Proof. We can estimate

$$\begin{aligned} \mathbf{E} \left\| \sum_{i=1}^n Z_i^2 \right\| &\leq \sigma(X)^2 + \mathbf{E} \left\| \sum_{i=1}^n (Z_i^2 - \mathbf{E} Z_i^2) \right\| \\ &\lesssim \sigma(X)^2 + \left\| \sum_{i=1}^n \mathbf{E}[(Z_i^2 - \mathbf{E} Z_i^2)^2] \right\|^{\frac{1}{2}} \sqrt{\log d} + R(X)^2 \log d \\ &\lesssim \sigma(X)^2 + R(X)\sigma(X)\sqrt{\log d} + R(X)^2 \log d, \end{aligned}$$

where the second line follows from the matrix Bernstein inequality (1.3). The conclusion follows as $R(X)\sigma(X)\sqrt{\log d} \leq \sigma(X)^2 + R(X)^2 \log d$. \square

We can now complete the proof of Theorem 2.10.

Proof of Theorem 2.10. Lemmas 6.11 and 6.12 yield

$$\left\| \mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}] \right\| \lesssim \frac{\sigma(X)^2 + R(X)^2 \log d}{(\text{Im } z)^3} \left(\frac{R(X)}{\text{Im } z} + \frac{R(X)^3}{(\text{Im } z)^3} \right).$$

This yields the first inequality of Theorem 2.10 when $\text{Im } z \geq R(X)$. On the other hand, when $\text{Im } z < R(X)$, we can crudely estimate

$$\begin{aligned} \left\| \mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}] \right\| &\leq \left\| \mathbf{E}[(z\mathbf{1} - X)^{-1}] \right\| + \left\| \mathbf{E}[(z\mathbf{1} - G)^{-1}] \right\| \\ &\leq \frac{2}{\text{Im } z} \leq \frac{2R(X)^3}{(\text{Im } z)^4}, \end{aligned}$$

concluding the proof of the first inequality.

To prove the second inequality, it suffices to consider real-valued $\varphi : \mathbb{R} \rightarrow \mathbb{R}$ (as otherwise we may apply the real-valued inequality separately to the real and imaginary parts of φ). Then $\varphi(X)$ and $\varphi(G)$ are self-adjoint, so we may express

$$\begin{aligned} \left\| \mathbf{E}[\varphi(X)] - \mathbf{E}[\varphi(G)] \right\| &= \sup_{\|v\|=1} \left| \langle v, \mathbf{E}[\varphi(X)]v \rangle - \langle v, \mathbf{E}[\varphi(G)]v \rangle \right| \\ &= \sup_{\|v\|=1} \left| \int \varphi d\mu_v - \int \varphi d\nu_v \right| \end{aligned}$$

where we defined the probability measures μ_v, ν_v for $\|v\| = 1$ so that $\int \varphi d\mu_v = \langle v, \mathbf{E}[\varphi(X)]v \rangle$ and $\int \varphi d\nu_v = \langle v, \mathbf{E}[\varphi(G)]v \rangle$ for all bounded continuous φ . As the first inequality of Theorem 2.10 implies that

$$\sup_{\|v\|=1} \left| \int \frac{1}{z-x} \mu_v(dx) - \int \frac{1}{z-x} \nu_v(dx) \right| \lesssim \frac{R(X)\sigma(X)^2 + R(X)^3 \log d}{(\text{Im } z)^4},$$

the second inequality of Theorem 2.10 follows from [9, Lemma 5.11]. \square

Remark 6.13 (An improved inequality for Stieltjes transforms). The main complication in the proof of Theorem 2.10 arises from the fact that we aim to achieve a norm estimate. If we are only interested in establishing universality of the trace

of the resolvent (that is, of the Stieltjes transform of the empirical spectral distribution), the proof simplifies greatly and yields a better bound. Indeed, the first equation display of the proof of Lemma 6.11 and Hölder's inequality readily yield

$$|\mathbf{E}[\partial_{Y_1} \partial_{Y_2} \partial_{Y_3} \operatorname{tr}(z\mathbf{1} - X(t, i, s))^{-1}]| \leq \frac{6\|Y_1\|_3\|Y_2\|_3\|Y_3\|_3}{(\operatorname{Im} z)^4}$$

for any random matrices Y_1, Y_2, Y_3 . Combining this inequality with the $p = 3$ case of Corollary 6.2 immediately yields the estimate

$$|\mathbf{E}[\operatorname{tr}(z\mathbf{1} - X)^{-1}] - \mathbf{E}[\operatorname{tr}(z\mathbf{1} - G)^{-1}]| \lesssim \frac{1}{(\operatorname{Im} z)^4} \sum_{i=1}^n \mathbf{E}[\operatorname{tr}|Z_i|^3].$$

In particular, in this case the logarithmic dimension dependence is eliminated.

7. UNIVERSALITY OF THE SPECTRUM

The aim of this section is to prove Theorem 2.6 and Corollary 2.7. The main idea behind the proof is that universality of the spectrum can be deduced from the bound on the moments of the resolvent in Theorem 6.8 using a technique that was developed for Gaussian random matrices in [9, §6.2]. The difficulty in the present setting is that the resolvent of the non-Gaussian random matrix X exhibits more complicated concentration properties than in the Gaussian case.

We first introduce some basic estimates in section 7.1. In sections 7.2 and 7.3, we bound the probability that $\operatorname{sp}(X) \subseteq \operatorname{sp}(G) + [-\varepsilon, \varepsilon]$ and $\operatorname{sp}(G) \subseteq \operatorname{sp}(X) + [-\varepsilon, \varepsilon]$, respectively. Combining these bounds yields the Hausdorff distance bound of Theorem 2.6. Finally, Corollary 2.7 will be proved in section 7.4.

7.1. Preliminaries. The basic principle behind the proof is the following deterministic lemma, which is a trivial modification of [9, Lemma 6.4].

Lemma 7.1. *Let $C, K_1, K_2, K_3 \geq 0$, and let $A, B \in M_d(\mathbb{C})_{\text{sa}}$ satisfy*

$$\|(z\mathbf{1} - A)^{-1}\| \leq C\|(z\mathbf{1} - B)^{-1}\| + \frac{K_1}{(\operatorname{Im} z)^2} + \frac{K_2}{(\operatorname{Im} z)^3} + \frac{K_3}{(\operatorname{Im} z)^4}$$

for all $z = \lambda + i\varepsilon$ with $\lambda \in \operatorname{sp}(A)$ and $\varepsilon = 6K_1 \vee (6K_2)^{\frac{1}{2}} \vee (6K_3)^{\frac{1}{3}}$. Then

$$\operatorname{sp}(A) \subseteq \operatorname{sp}(B) + 2C\varepsilon[-1, 1].$$

Proof. Fix $\lambda \in \operatorname{sp}(A)$ and $z = \lambda + i\varepsilon$, where ε is as defined in the statement. As $\|(z\mathbf{1} - A)^{-1}\| = (\operatorname{dist}(z, \operatorname{sp}(A)))^{-1}$, the assumption implies that

$$\frac{1}{\varepsilon} \leq \frac{C}{\sqrt{\varepsilon^2 + \operatorname{dist}(\lambda, \operatorname{sp}(B))^2}} + \frac{K_1}{\varepsilon^2} + \frac{K_2}{\varepsilon^3} + \frac{K_3}{\varepsilon^4}.$$

If $\operatorname{dist}(\lambda, \operatorname{sp}(B)) > 2C\varepsilon$, we would have $\frac{1}{2} < \frac{K_1}{\varepsilon^2} + \frac{K_2}{\varepsilon^3} + \frac{K_3}{\varepsilon^4} \leq \frac{1}{2}$ by the definition of ε , which is impossible. Thus $\operatorname{dist}(\lambda, \operatorname{sp}(B)) \leq 2C\varepsilon$ for all $\lambda \in \operatorname{sp}(A)$. \square

The main idea behind the proof of Theorem 2.6 is that we will engineer the assumption of Lemma 7.1 by using Theorem 6.8 and concentration of measure. Before we turn to the details of the argument, let us prove a crude *a priori* bound on the spectrum that will be needed below.

Lemma 7.2. *We have*

$$\mathbf{P}[\mathrm{sp}(X) \subseteq \mathrm{sp}(\mathbf{E}X) + C\{\sigma_*(X)\sqrt{d+t} + R(X)(d+t)\}[-1, 1]] \geq 1 - e^{-t}$$

and

$$\mathbf{P}[\mathrm{sp}(G) \subseteq \mathrm{sp}(\mathbf{E}G) + C\sigma_*(X)\sqrt{d+t}[-1, 1]] \geq 1 - e^{-t}$$

for all $t \geq 0$, where C is a universal constant.

Proof. Let $N \subset \mathbb{S}^{d-1}$ be a $\frac{1}{4}$ -net of the unit sphere $\mathbb{S}^{d-1} := \{x \in \mathbb{C}^d : \|x\| = 1\}$, that is, $\mathrm{dist}(x, N) \leq \frac{1}{4}$ for all $x \in \mathbb{S}^{d-1}$. A routine estimate [75, p. 110] yields

$$\begin{aligned} \mathbf{P}[\|X - \mathbf{E}X\| \geq x] &\leq \mathbf{P}\left[\max_{v,w \in N} |\langle v, (X - \mathbf{E}X)w \rangle| \geq \frac{x}{4}\right] \\ &\leq |N|^2 \sup_{v,w \in \mathbb{S}^{d-1}} \mathbf{P}\left[|\langle v, (X - \mathbf{E}X)w \rangle| \geq \frac{x}{4}\right]. \end{aligned}$$

By viewing \mathbb{C}^d as a $2d$ -dimensional real vector space, we may use a standard volume argument [75, Lemma 2.3.4] to choose the net N so that $|N| \leq C^d$ for a universal constant C . On the other hand, by Bernstein's inequality [22, Theorem 2.10]

$$\begin{aligned} \mathbf{P}[|\langle v, (X - \mathbf{E}X)w \rangle| \geq 2\sigma_*(X)\sqrt{x} + \sqrt{2}R(X)x] \\ &\leq \mathbf{P}\left[\left|\sum_{i=1}^n \mathrm{Re} \langle v, Z_i w \rangle\right| \geq \sigma_*(X)\sqrt{2x} + R(X)x\right] \\ &\quad + \mathbf{P}\left[\left|\sum_{i=1}^n \mathrm{Im} \langle v, Z_i w \rangle\right| \geq \sigma_*(X)\sqrt{2x} + R(X)x\right] \leq 4e^{-x} \end{aligned}$$

for all $x \geq 0$ and $v, w \in \mathbb{S}^{d-1}$. Combining the above estimates yields

$$\mathbf{P}[\|X - \mathbf{E}X\| \geq 8\sigma_*(X)\sqrt{cd+t} + 4\sqrt{2}R(X)(cd+t)] \leq C^{2d}e^{-cd-t} \leq e^{-t}$$

for all $t \geq 0$, provided the universal constant c is chosen sufficiently large. The first inequality in the statement now follows by noting that

$$\mathrm{sp}(X) \subseteq \mathrm{sp}(\mathbf{E}X) + \|X - \mathbf{E}X\|[-1, 1]$$

by Weyl's inequality $\max_i |\lambda_i(A) - \lambda_i(B)| \leq \|A - B\|$ for self-adjoint matrices A, B [18, Corollary III.2.6] (here $\lambda_i(A)$ is the i th largest eigenvalue of A).

The inequality for the Gaussian matrix G follows in the identical fashion, except that we replace Bernstein's inequality by the Gaussian bound

$$\mathbf{P}[|\langle v, (G - \mathbf{E}G)w \rangle| \geq 2\sigma_*(X)\sqrt{x}] \leq 4e^{-x}$$

(this follows from the Gaussian tail bound [22, p. 22] as the real and imaginary parts of $\langle v, (G - \mathbf{E}G)w \rangle$ are Gaussian variables with variance bounded by $\sigma_*(X)^2$). \square

7.2. Proof of Theorem 2.6: upper bound. The aim of the present section is to prove that $\mathrm{sp}(X) \subseteq \mathrm{sp}(G) + [-\varepsilon, \varepsilon]$ with high probability for a suitable choice of ε . This will be accomplished by showing that the corresponding resolvent norm inequality of Lemma 7.1 holds with high probability.

We begin by showing that this is the case for a single choice of z . Note that the joint distribution of X and G is irrelevant to the following proofs.

Lemma 7.3. *Let $z \in \mathbb{C}$ with $\operatorname{Im} z > 0$. Then*

$$\mathbf{P} \left[\| (z\mathbf{1} - X)^{-1} \| \geq C \left\{ \| (z\mathbf{1} - G)^{-1} \| + \frac{\sigma_*(X)}{(\operatorname{Im} z)^2} \sqrt{x} \right. \right. \\ \left. \left. + \frac{R(X)\sigma(X)^2 x^2 + R(X)^3 x^3}{(\operatorname{Im} z)^4} \right\} \right] \leq 3e^{-x}$$

for all $x \geq \log d$, where C is a universal constant.

Proof. We begin by noting that Markov's inequality implies

$$\mathbf{P} \left[\| (z\mathbf{1} - X)^{-1} \| \geq e \mathbf{E} [\| (z\mathbf{1} - X)^{-1} \|^2 p]^{1/2p} \right] \leq e^{-2p}.$$

By Theorem 6.8, the expectation inside the probability satisfies

$$\mathbf{E} [\| (z\mathbf{1} - X)^{-1} \|^2 p]^{1/2p} \leq d^{1/2p} \mathbf{E} [\| (z\mathbf{1} - G)^{-1} \|^2 p]^{1/2p} + C d^{1/2p} \frac{R(X)\sigma(X)^2 p^2 + R(X)^3 p^3}{(\operatorname{Im} z)^4}$$

for $p \in \mathbb{N}$, where C is a universal constant. Here we used that $\frac{1}{d} \|A\| \leq \operatorname{tr} A \leq \|A\|$ for any positive semidefinite matrix $A \in M_d(\mathbb{C})_{\text{sa}}$.

To proceed, note first that Lemma 5.5 implies

$$\mathbf{E} [\| (z\mathbf{1} - G)^{-1} \|^2 p]^{1/2p} \leq \mathbf{E} \| (z\mathbf{1} - G)^{-1} \| + C \sqrt{p} \frac{\sigma_*(X)}{(\operatorname{Im} z)^2}$$

for $p \in \mathbb{N}$, where C is a universal constant (this follows as the L^p -norm of a σ^2 -subgaussian random variable is at most of order $\sigma\sqrt{p}$, cf. [22, Theorem 2.1]). Another application of Lemma 5.5 therefore yields

$$\mathbf{P} \left[\mathbf{E} [\| (z\mathbf{1} - G)^{-1} \|^2 p]^{1/2p} \geq \| (z\mathbf{1} - G)^{-1} \| + C_1 \sqrt{p} \frac{\sigma_*(X)}{(\operatorname{Im} z)^2} \right] \leq 2e^{-C_2 p}$$

for $p \in \mathbb{N}$ and universal constants C_1, C_2 .

Combining the above bounds yields

$$\mathbf{P} \left[\| (z\mathbf{1} - X)^{-1} \| \geq e d^{1/2p} \| (z\mathbf{1} - G)^{-1} \| + C_1 e d^{1/2p} \sqrt{p} \frac{\sigma_*(X)}{(\operatorname{Im} z)^2} \right. \\ \left. + C e d^{1/2p} \frac{R(X)\sigma(X)^2 p^2 + R(X)^3 p^3}{(\operatorname{Im} z)^4} \right] \leq e^{-2p} + 2e^{-C_2 p}$$

for $p \in \mathbb{N}$. The conclusion follows readily using $d^{1/2p} \leq e^{1/2}$ for $p \geq \log d$. \square

We are now ready to prove one direction of Theorem 2.6.

Proposition 7.4. *For any $t \geq 0$, we have*

$$\mathbf{P} [\operatorname{sp}(X) \subseteq \operatorname{sp}(G) + C\varepsilon(t)[-1, 1]] \geq 1 - de^{-t},$$

where C is a universal constant and $\varepsilon(t)$ is as defined in Theorem 2.6.

Proof. Define the set

$$\Omega_x := \operatorname{sp}(\mathbf{E} X) + C' \{ \sigma_*(X) \sqrt{d+x} + R(X)(d+x) \} [-1, 1],$$

where C' is the universal constant of Lemma 7.2. Then Ω_x is a union of d intervals of length $2C' \{ \sigma_*(X) \sqrt{d+x} + R(X)(d+x) \}$. We can therefore find $\mathcal{N}_x \subset \Omega_x$ with $|\mathcal{N}_x| \leq \frac{4C' d(d+x)}{x}$ such that each $\lambda \in \Omega_x$ satisfies $\operatorname{dist}(\lambda, \mathcal{N}_x) \leq \sigma_* \sqrt{x} + R(X)x$. In particular, for every $\lambda \in \Omega_x$, there exists $\lambda' \in \mathcal{N}_x$ so that

$$\left| \| ((\lambda + i\varepsilon)\mathbf{1} - X)^{-1} \| - \| ((\lambda' + i\varepsilon)\mathbf{1} - X)^{-1} \| \right| \leq \frac{\sigma_* \sqrt{x} + R(X)x}{\varepsilon^2}$$

as well as the analogous bound where X is replaced by G (here we used the identity $A^{-1} - B^{-1} = A^{-1}(B - A)B^{-1}$). We can therefore estimate

$$\begin{aligned}
& \mathbf{P} \left[\|(z\mathbf{1} - X)^{-1}\| \geq C \left\{ \|(z\mathbf{1} - G)^{-1}\| + \frac{3\sigma_*(X)\sqrt{x} + 2R(X)x}{\varepsilon^2} \right. \right. \\
& \quad \left. \left. + \frac{R(X)\sigma(X)^2x^2 + R(X)^3x^3}{\varepsilon^4} \right\} \text{ for some } z \in \text{sp}(X) + i\varepsilon \right] \\
& \leq \mathbf{P} \left[\|(z\mathbf{1} - X)^{-1}\| \geq C \left\{ \|(z\mathbf{1} - G)^{-1}\| + \frac{3\sigma_*(X)\sqrt{x} + 2R(X)x}{\varepsilon^2} \right. \right. \\
& \quad \left. \left. + \frac{R(X)\sigma(X)^2x^2 + R(X)^3x^3}{\varepsilon^4} \right\} \text{ for some } z \in \Omega_x + i\varepsilon \right] + e^{-x} \\
& \leq \mathbf{P} \left[\|(z\mathbf{1} - X)^{-1}\| \geq C \left\{ \|(z\mathbf{1} - G)^{-1}\| + \frac{\sigma_*(X)}{\varepsilon^2}\sqrt{x} \right. \right. \\
& \quad \left. \left. + \frac{R(X)\sigma(X)^2x^2 + R(X)^3x^3}{\varepsilon^4} \right\} \text{ for some } z \in \mathcal{N}_x + i\varepsilon \right] + e^{-x} \\
& \leq (3|\mathcal{N}_x| + 1)e^{-x} \leq \left(1 + \frac{12C'd(d+x)}{x} \right) e^{-x}
\end{aligned}$$

for $x \geq \log d$, where we used Lemma 7.2 in the first inequality and a union bound and Lemma 7.3 in the third inequality (here $C > 1$ is the constant of Lemma 7.3).

Now let $x = Lt$ for a universal constant L . Recalling the standing assumption $d \geq 2$, it is readily seen that we may choose $L > 1$ sufficiently large so that

$$\left(1 + \frac{12C'd(d+x)}{x} \right) e^{-x} \leq de^{-t}$$

for all $t \geq \log d$. Then we have shown that

$$\begin{aligned}
& \mathbf{P} \left[\|(z\mathbf{1} - X)^{-1}\| \leq 3L^3C \left\{ \|(z\mathbf{1} - G)^{-1}\| + \frac{\sigma_*(X)\sqrt{t} + R(X)t}{\varepsilon^2} \right. \right. \\
& \quad \left. \left. + \frac{R(X)\sigma(X)^2t^2 + R(X)^3t^3}{\varepsilon^4} \right\} \text{ for all } z \in \text{sp}(X) + i\varepsilon \right] \geq 1 - de^{-t}
\end{aligned}$$

for all $t \geq \log d$. On the other hand, the same bound holds trivially for $t < \log d$ as then $1 - de^{-t} < 0$. The proof is concluded by applying Lemma 7.1. \square

7.3. Proof of Theorem 2.6: lower bound. We now turn to the complementary inequality $\text{sp}(G) \subseteq \text{sp}(X) + [-\varepsilon, \varepsilon]$ with high probability. The proof is similar in spirit to that of the upper bound, but we must now work with the more complicated concentration inequality of Proposition 5.6. As before, we begin by establishing a resolvent norm inequality for a single choice of z .

Lemma 7.5. *Let $z \in \mathbb{C}$ with $\text{Im } z > 0$. Then*

$$\begin{aligned}
& \mathbf{P} \left[\|(z\mathbf{1} - G)^{-1}\| \geq C \left\{ \|(z\mathbf{1} - X)^{-1}\| + \frac{R(X)\sigma(X)x + R(X)^2x^{\frac{3}{2}}}{(\text{Im } z)^3} + \right. \right. \\
& \quad \left. \left. \frac{R(X)\sigma(X)^2x^2 + R(X)^3x^3}{(\text{Im } z)^4} + \frac{\sigma_*(X)x^{\frac{1}{2}} + R(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}}x^{\frac{3}{4}} + R(X)x}{(\text{Im } z)^2} \right\} \right] \leq 3e^{-x}
\end{aligned}$$

for all $x \geq \log d$, where C is a universal constant.

Proof. As in the proof of Lemma 7.3, we have

$$\mathbf{P}\left[\|(z\mathbf{1} - G)^{-1}\| \geq e \mathbf{E}[\|(z\mathbf{1} - G)^{-1}\|^{2p}]^{\frac{1}{2p}}\right] \leq e^{-2p}$$

and

$$\mathbf{E}[\|(z\mathbf{1} - G)^{-1}\|^{2p}]^{\frac{1}{2p}} \leq d^{\frac{1}{2p}} \mathbf{E}[\|(z\mathbf{1} - X)^{-1}\|^{2p}]^{\frac{1}{2p}} + Cd^{\frac{1}{2p}} \frac{R(X)\sigma(X)^2 p^2 + R(X)^3 p^3}{(\text{Im } z)^4}$$

for $p \in \mathbb{N}$ by Markov's inequality and Theorem 6.8.

To proceed, we use that Proposition 5.6 implies

$$\begin{aligned} \mathbf{E}[\|(z\mathbf{1} - X)^{-1}\|^{2p}]^{\frac{1}{2p}} &\leq \mathbf{E}[\|(z\mathbf{1} - X)^{-1}\|] + C \left\{ \frac{R(X)}{(\text{Im } z)^2} + \frac{R(X)^2}{(\text{Im } z)^3} \right\} p \\ &\quad + C \left\{ \frac{\sigma_*(X) + R(X)^{\frac{1}{2}}(\mathbf{E}\|X - \mathbf{E}X\|)^{\frac{1}{2}}}{(\text{Im } z)^2} + \frac{R(X)(\mathbf{E}\|X - \mathbf{E}X\|^2)^{\frac{1}{2}}}{(\text{Im } z)^3} \right\} \sqrt{p} \end{aligned}$$

for $p \in \mathbb{N}$ by [22, Theorem 2.3]. Another application of Proposition 5.6 yields

$$\begin{aligned} \mathbf{P}\left[\mathbf{E}[\|(z\mathbf{1} - X)^{-1}\|^{2p}]^{\frac{1}{2p}} \geq \|(z\mathbf{1} - X)^{-1}\| + C \left\{ \frac{R(X)}{(\text{Im } z)^2} + \frac{R(X)^2}{(\text{Im } z)^3} \right\} p + C \left\{ \frac{\sigma_*(X) + R(X)^{\frac{1}{2}}(\mathbf{E}\|X - \mathbf{E}X\|)^{\frac{1}{2}}}{(\text{Im } z)^2} + \frac{R(X)(\mathbf{E}\|X - \mathbf{E}X\|^2)^{\frac{1}{2}}}{(\text{Im } z)^3} \right\} \sqrt{p}\right] \leq 2e^{-p} \end{aligned}$$

for $p \in \mathbb{N}$, provided the universal constant C is chosen sufficiently large. Now recall that the matrix Bernstein inequality [77, eq. (6.1.4)] implies

$$(\mathbf{E}\|X - \mathbf{E}X\|^2)^{\frac{1}{2}} \lesssim \sigma(X)\sqrt{\log d} + R(X)\log d \leq \sigma(X)\sqrt{p} + R(X)p$$

for $p \geq \log d$. We can therefore further estimate

$$\begin{aligned} \mathbf{P}\left[\mathbf{E}[\|(z\mathbf{1} - X)^{-1}\|^{2p}]^{\frac{1}{2p}} \geq \|(z\mathbf{1} - X)^{-1}\| + C \left\{ \frac{R(X)\sigma(X)p + R(X)^2 p^{\frac{3}{2}}}{(\text{Im } z)^3} + \frac{\sigma_*(X)\sqrt{p} + R(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}}p^{\frac{3}{4}} + R(X)p}{(\text{Im } z)^2} \right\}\right] \leq 2e^{-p} \end{aligned}$$

for $p \geq \log d$, provided C is chosen sufficiently large. The proof is now readily concluded by combining the above bounds and using $d^{\frac{1}{2p}} \leq e^{\frac{1}{2}}$ for $p \geq \log d$. \square

Remark 7.6. We have emphasized in the introduction that the matrix Bernstein inequality may be viewed as a consequence of the universality principles of this paper. On the other hand, we have used the matrix Bernstein inequality in the proof of Lemma 7.5 to estimate the matrix norms that appear in Proposition 5.6. There is no circular reasoning here: the present section is only concerned with lower bounds on the spectrum of X , while the matrix Bernstein inequality already follows from the upper bound of Proposition 7.4 (or from Theorem 2.9 by choosing $p \asymp \log d$ and $q = \infty$) and the noncommutative Khintchine inequality.

The same remark applies to the application of the matrix Bernstein inequality in the proof of Theorem 2.10 (cf. Lemma 6.12 in section 6.4).

We are now ready to prove the converse direction of Theorem 2.6.

Proposition 7.7. *For any $t \geq 0$, we have*

$$\mathbf{P}[\text{sp}(G) \subseteq \text{sp}(X) + C\varepsilon(t)[-1, 1]] \geq 1 - de^{-t},$$

where C is a universal constant and $\varepsilon(t)$ is as defined in Theorem 2.6.

Proof. By following exactly the same steps as in the proof of Proposition 7.4, we can deduce using Lemmas 7.2 and Lemma 7.5 the inequality

$$\mathbf{P} \left[\|(z\mathbf{1} - G)^{-1}\| \leq C \left\{ \|(z\mathbf{1} - X)^{-1}\| + \frac{R(X)\sigma(X)t + R(X)^2t^{\frac{3}{2}}}{\varepsilon^3} + \frac{R(X)\sigma(X)^2t^2 + R(X)^3t^3}{\varepsilon^4} + \frac{\sigma_*(X)t^{\frac{1}{2}} + R(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}}t^{\frac{3}{4}} + R(X)t}{\varepsilon^2} \right\} \right. \\ \left. \text{for all } z \in \text{sp}(G) + i\varepsilon \right] \geq 1 - de^{-t}$$

for all $t, \varepsilon \geq 0$, where C is a universal constant. Thus Lemma 7.1 implies

$$\mathbf{P}[\text{sp}(G) \subseteq \text{sp}(X) + C\varepsilon'(t)[-1, 1]] \geq 1 - de^{-t}$$

for all $t \geq 0$ and a universal constant C , where

$$\varepsilon'(t) = \sigma_*(X)t^{\frac{1}{2}} + R(X)^{\frac{1}{3}}\sigma(X)^{\frac{2}{3}}t^{\frac{2}{3}} + R(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}}t^{\frac{3}{4}} + R(X)t.$$

It remains to note that

$$R(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}}t^{\frac{3}{4}} \leq \frac{3}{4}R(X)^{\frac{1}{3}}\sigma(X)^{\frac{2}{3}}t^{\frac{2}{3}} + \frac{1}{4}R(X)t$$

by Young's inequality, concluding the proof. \square

We now conclude the proof of Theorem 2.6.

Proof of Theorem 2.6. Combining Propositions 7.4 and 7.7 yields

$$\mathbf{P}[\text{d}_H(\text{sp}(X), \text{sp}(G)) > C\varepsilon(s)] \leq 2de^{-s}$$

for all $s \geq 0$ by the union bound. Choosing $s = 2t$, we obtain

$$\mathbf{P}[\text{d}_H(\text{sp}(X), \text{sp}(G)) > 2C\varepsilon(t)] \leq 2de^{-2t} \leq de^{-t}$$

for $t \geq \log d$, as the latter implies $2e^{-t} \leq \frac{2}{d} \leq 1$ by the standing assumption $d \geq 2$. But for $t < \log d$ the inequality is trivial as then $de^{-t} > 1$. The tail bound follows.

To deduce the expectation bound, we note that

$$\begin{aligned} \mathbf{E}[\text{d}_H(\text{sp}(X), \text{sp}(G))] &\leq C\varepsilon(\log d) + \int_{C\varepsilon(\log d)}^{\infty} \mathbf{P}[\text{d}_H(\text{sp}(X), \text{sp}(G)) > x] dx \\ &= C\varepsilon(\log d) + C \int_{\log d}^{\infty} \mathbf{P}[\text{d}_H(\text{sp}(X), \text{sp}(G)) > C\varepsilon(t)] \frac{d\varepsilon(t)}{dt} dt \\ &\leq C\varepsilon(\log d) + 2dC \int_{\log d}^{\infty} e^{-t} \frac{d\varepsilon(t)}{dt} dt \lesssim \varepsilon(\log d) \end{aligned}$$

using $\int_a^{\infty} e^{-t}t^{\beta} dt \leq C_{\beta}e^{-a}a^{\beta}$ for $a > \frac{1}{4}$, $\beta \in \mathbb{R}$, where C_{β} depends only on β . \square

7.4. Proof of Corollary 2.7. Now that Theorem 2.6 has been established, the proof of Corollary 2.7 follows by routine manipulations.

Proof of Corollary 2.7. We first note that

$$\text{sp}(A) \subseteq \text{sp}(B) + [-\varepsilon, \varepsilon]$$

certainly implies

$$\lambda_{\max}(A) \leq \lambda_{\max}(B) + \varepsilon$$

for any $A, B \in M_d(\mathbb{C})_{\text{sa}}$ and $\varepsilon > 0$. Thus

$$|\lambda_{\max}(A) - \lambda_{\max}(B)| \leq \text{d}_H(\text{sp}(A), \text{sp}(B)),$$

and the first and last bound of Corollary 2.7 follow immediately from Theorem 2.6.

To prove the middle bound, we note that a routine application of Gaussian concentration (see, e.g., [9, Corollary 4.14]) yields

$$\mathbf{P}[|\lambda_{\max}(G) - \mathbf{E}\lambda_{\max}(G)| \geq \sigma_*(X)\sqrt{2t}] \leq 2e^{-t}$$

for all $t \geq 0$. Combined with the first bound of Corollary 2.7, we obtain

$$\begin{aligned} \mathbf{P}[|\lambda_{\max}(X) - \mathbf{E}\lambda_{\max}(G)| > \sigma_*(X)\sqrt{2t} + C\varepsilon(t)] \\ &\leq 2e^{-t} + \mathbf{P}[|\lambda_{\max}(X) - \lambda_{\max}(G)| > C\varepsilon(t)] \leq (d+2)e^{-t} \end{aligned}$$

for all $t \geq 0$. The second inequality of Corollary 2.7 follows for a suitable choice of the universal constant (as in the last step of the proof of Theorem 2.6).

The analogous bounds for $\|X\|, \|G\|$ are proved in an identical manner. \square

8. TRUNCATION

The aim of this section is to prove Theorems 2.8 and 2.11. The basic idea behind these results is the following truncation argument. Let X be as in (2.1), and let G be the associated Gaussian model. Define the truncated model

$$\tilde{X} := Z_0 + \sum_{i=1}^n \mathbf{1}_{\|Z_i\| \leq R} Z_i.$$

Then $X = \tilde{X}$ on the event $\{\max_i \|Z_i\| \leq R\}$, while $R(\tilde{X}) \leq R$. We can therefore obtain universality principles for unbounded X by conditioning on the above event, and applying the results of the previous sections to \tilde{X} .

The problem with this approach is that it does not yield a comparison between the spectra of X and G , but rather between the spectra of X and \tilde{G} , where \tilde{G} is the Gaussian model associated to \tilde{X} . The main difficulty in the implementation of the truncation argument is therefore to compare the spectra of the Gaussian models G and \tilde{G} . To this end, we will first prove general comparison principles for the spectra of Gaussian random matrices in section 8.1. In section 8.2, we will upper bound the relevant parameters in the specific case of G and \tilde{G} . Finally, we combine these estimates in section 8.3 to complete the proof of Theorems 2.8 and 2.11.

8.1. Gaussian comparison principles. The aim of this section is to prove general comparison principles for the spectra of Gaussian random matrices. We begin by stating a comparison principle for the resolvent moments.

Lemma 8.1. *Let H, \tilde{H} be self-adjoint Gaussian random matrices. Then we have*

$$|\mathbf{E}[\text{tr}|z\mathbf{1} - H|^{-2p}]^{\frac{1}{2p}} - \mathbf{E}[\text{tr}|z\mathbf{1} - \tilde{H}|^{-2p}]^{\frac{1}{2p}}| \leq \frac{\|\mathbf{E}H - \mathbf{E}\tilde{H}\|}{(\text{Im } z)^2} + 2p \frac{\Delta(H, \tilde{H})}{(\text{Im } z)^3}$$

for any $p \in \mathbb{N}$, where

$$\Delta(H, \tilde{H}) := \sup_{\|M\| \leq 1} \|\mathbf{E}[(H - \mathbf{E}H)M(H - \mathbf{E}H)] - \mathbf{E}[(\tilde{H} - \mathbf{E}\tilde{H})M(\tilde{H} - \mathbf{E}\tilde{H})]\|.$$

Proof. First, note that as $A^{-1} - B^{-1} = A^{-1}(B - A)B^{-1}$, we have

$$\|(z\mathbf{1} - H)^{-1} - (z\mathbf{1} - (H - \mathbf{E}H + \mathbf{E}\tilde{H}))^{-1}\| \leq \frac{\|\mathbf{E}H - \mathbf{E}\tilde{H}\|}{(\text{Im } z)^2}.$$

Thus we can assume in the sequel that $\mathbf{E}H = \mathbf{E}\tilde{H}$.

Assume without loss of generality that H, \tilde{H} are independent and $\mathbf{E}H = \mathbf{E}\tilde{H}$, and let Y, \tilde{Y} be independent copies of $H - \mathbf{E}H$ and $\tilde{H} - \mathbf{E}\tilde{H}$, respectively. Define

$$H(t) := \mathbf{E}H + \sqrt{t}(H - \mathbf{E}H) + \sqrt{1-t}(\tilde{H} - \mathbf{E}\tilde{H}).$$

By the Gaussian interpolation lemma [9, Lemma 4.11]

$$\frac{d}{dt} \mathbf{E}[\text{tr}|z\mathbf{1} - H(t)|^{-2p}] = \frac{\mathbf{E}[\partial_Y^2 \text{tr}|z\mathbf{1} - H(t)|^{-2p}] - \mathbf{E}[\partial_{\tilde{Y}}^2 \text{tr}|z\mathbf{1} - H(t)|^{-2p}]}{2}.$$

By the product rule, we have

$$\begin{aligned} \partial_B^2 \text{tr}|z\mathbf{1} - H|^{-2p} &= 2p \sum_{k=0}^p \text{Re} \text{tr}[B(z\mathbf{1} - H)^{-k-1} B(z\mathbf{1} - H)^{-p-1+k} (\bar{z}\mathbf{1} - H)^{-p}] \\ &\quad + 2p \sum_{k=0}^{p-1} \text{Re} \text{tr}[B(z\mathbf{1} - H)^{-p-1} (\bar{z}\mathbf{1} - H)^{-k-1} B(\bar{z}\mathbf{1} - H)^{-p+k}]. \end{aligned}$$

We can therefore bound

$$\left| \frac{d}{dt} \mathbf{E}[\text{tr}|z\mathbf{1} - H(t)|^{-2p}] \right| \leq p(2p+1) \Delta(H, \tilde{H}) \mathbf{E}[\text{tr}|z\mathbf{1} - H(t)|^{-2p-2}]$$

by applying Lemma 5.2 to $F(M, M') := \mathbf{E}[\text{tr} YMYM'] - \mathbf{E}[\text{tr} \tilde{Y}M\tilde{Y}M']$ as in the proof of Lemma 5.3, and using $\sup_{\|M\| \leq 1, \|M'\|_1 \leq 1} |F(M, M')| = \Delta(H, \tilde{H})$.

It remains to note that $\mathbf{E}[\text{tr}|z\mathbf{1} - H(t)|^{-2p-2}] \leq (\text{Im } z)^{-3} \mathbf{E}[\text{tr}|z\mathbf{1} - H(t)|^{-2p}]^{1-\frac{1}{2p}}$ and the chain rule readily yield the estimate

$$\left| \frac{d}{dt} \mathbf{E}[\text{tr}|z\mathbf{1} - H(t)|^{-2p}]^{\frac{1}{2p}} \right| \leq (p + \frac{1}{2}) \frac{\Delta(H, \tilde{H})}{(\text{Im } z)^3}.$$

The conclusion now follows by integrating over t (using $p + \frac{1}{2} \leq 2p$). \square

A bound on the Hausdorff distance now follows along familiar lines.

Proposition 8.2. *Let H, \tilde{H} be self-adjoint Gaussian random matrices. Then*

$$\begin{aligned} \mathbf{P}[\text{d}_H(\text{sp}(H), \text{sp}(\tilde{H})) &> C\{\|\mathbf{E}H - \mathbf{E}\tilde{H}\| + \Delta(H, \tilde{H})^{\frac{1}{2}}\sqrt{\log d} \\ &\quad + (\sigma_*(H) + \sigma_*(\tilde{H}))x\}] \leq de^{-x^2} \end{aligned}$$

for all $x \geq 0$, where C is a universal constant and $\Delta(H, \tilde{H})$ is as in Lemma 8.1.

Proof. Note first that

$$\mathbf{E}[\text{tr}|z\mathbf{1} - H|^{-2p}]^{\frac{1}{2p}} \leq \mathbf{E}[\|(z\mathbf{1} - H)^{-1}\|^{2p}]^{\frac{1}{2p}} \leq \mathbf{E}\|(z\mathbf{1} - H)^{-1}\| + C\sqrt{p} \frac{\sigma_*(H)}{(\text{Im } z)^2}$$

for a universal constant C as in the proof of Lemma 7.3. On the other hand,

$$\mathbf{E}[\text{tr}|z\mathbf{1} - \tilde{H}|^{-2p}]^{\frac{1}{2p}} \geq d^{-\frac{1}{2p}} \mathbf{E}\|(z\mathbf{1} - \tilde{H})^{-1}\|.$$

Combining these bounds with Lemmas 5.5 and 8.1 yields

$$\begin{aligned} \mathbf{P}\left[d^{-\frac{1}{2p}}\|(z\mathbf{1} - \tilde{H})^{-1}\| \geq \|(z\mathbf{1} - H)^{-1}\| + \frac{\|\mathbf{E}H - \mathbf{E}\tilde{H}\|}{(\text{Im } z)^2} + 2p \frac{\Delta(H, \tilde{H})}{(\text{Im } z)^3} \right. \\ \left. + C\sqrt{p} \frac{\sigma_*(H)}{(\text{Im } z)^2} + \frac{\sigma_*(\tilde{H}) + \sigma_*(H)}{(\text{Im } z)^2} x\right] \leq 4e^{-x^2/2}. \end{aligned}$$

Choosing $p = \lfloor \log d \rfloor$ and proceeding as in the proof of Proposition 7.4 yields

$$\mathbf{P} \left[\|(z\mathbf{1} - \tilde{H})^{-1}\| \geq L \left\{ \|(z\mathbf{1} - H)^{-1}\| + \frac{\|\mathbf{E}H - \mathbf{E}\tilde{H}\|}{\varepsilon^2} + \frac{\Delta(H, \tilde{H}) \log d}{\varepsilon^3} \right. \right. \\ \left. \left. + \frac{\sigma_*(\tilde{H}) + \sigma_*(H)}{\varepsilon^2} x \right\} \text{ for some } z \in \text{sp}(\tilde{H}) + i\varepsilon \right] \leq de^{-x^2}$$

for all $x \geq 0$, where L is a universal constant. The same bound holds if we reverse the roles of H and \tilde{H} , and the conclusion follows readily from Lemma 7.1. \square

We finally formulate a variant of Lemma 8.1 for the resolvent.

Lemma 8.3. *Let H, \tilde{H} be self-adjoint Gaussian random matrices. Then we have*

$$\|\mathbf{E}[(z\mathbf{1} - H)^{-1}] - \mathbf{E}[(z\mathbf{1} - \tilde{H})^{-1}]\| \leq \frac{\|\mathbf{E}H - \mathbf{E}\tilde{H}\|}{(\text{Im } z)^2} + \frac{\Delta(H, \tilde{H})}{(\text{Im } z)^3},$$

where $\Delta(H, \tilde{H})$ is as in Lemma 8.1.

Proof. As in the proof of Lemma 8.1, it suffices to assume that $\mathbf{E}H = \mathbf{E}\tilde{H}$. Moreover, applying Gaussian interpolation as in the proof of Lemma 8.1 yields

$$\frac{d}{dt} \mathbf{E}[\langle v, (z\mathbf{1} - H(t))^{-1}w \rangle] = \mathbf{E}[\langle v, (z\mathbf{1} - H(t))^{-1}Y(z\mathbf{1} - H(t))^{-1}Y(z\mathbf{1} - H(t))^{-1}w \rangle] \\ - \mathbf{E}[\langle v, (z\mathbf{1} - H(t))^{-1}\tilde{Y}(z\mathbf{1} - H(t))^{-1}\tilde{Y}(z\mathbf{1} - H(t))^{-1}w \rangle].$$

Integrating this identity and taking the supremum over v, w with $\|v\| = \|w\| = 1$ readily yields the conclusion, where we use that Y, \tilde{Y} are independent of $H(t)$. \square

8.2. The truncation error. In order to apply the above comparison principles to G, \tilde{G} , we must estimate the relevant parameters in this case.

Lemma 8.4. $\|\mathbf{E}G - \mathbf{E}\tilde{G}\| \leq \sqrt{2}\sigma_*(X)$ for $R \geq \sqrt{2}\bar{R}(X)$.

Proof. We first note that as $\mathbf{E}X = Z_0$ and by the independence of Z_1, \dots, Z_n

$$\mathbf{E}\tilde{G} - \mathbf{E}G = \mathbf{E}\tilde{X} - \mathbf{E}X = \sum_{i=1}^n \mathbf{E}[1_{\|Z_i\| \leq R} Z_i] = \sum_{i=1}^n b_i^{-1} \mathbf{E}[1_{\max_j \|Z_j\| \leq R} Z_i],$$

where $b_i := \mathbf{P}[\max_{j \neq i} \|Z_j\| \leq R] \geq \mathbf{P}[\max_j \|Z_j\| \leq R]$. We therefore obtain

$$\|\mathbf{E}\tilde{G} - \mathbf{E}G\| = \sup_{\|v\| = \|w\| = 1} \left| \mathbf{E} \left[1_{\max_j \|Z_j\| \leq R} \sum_{i=1}^n b_i^{-1} \langle v, Z_i w \rangle \right] \right| \leq \frac{\sigma_*(X)}{\mathbf{P}[\max_j \|Z_j\| \leq R]^{\frac{1}{2}}}$$

by Cauchy-Schwarz. It remains to note that $\mathbf{P}[\max_j \|Z_j\| \leq R] \geq \frac{1}{2}$ whenever $R \geq \sqrt{2}\mathbf{E}[\max_j \|Z_j\|^2]^{\frac{1}{2}} =: \sqrt{2}\bar{R}(X)$ by Markov's inequality. \square

Lemma 8.5. $\Delta(G, \tilde{G}) \leq 24\bar{R}(X)\sigma(X)$ for $R \geq \bar{R}(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}}$.

Proof. Suppose first that $M \geq 0$ with $\|M\| \leq 1$. We begin by writing

$$\mathbf{E}[(G - \mathbf{E}G)M(G - \mathbf{E}G)] - \mathbf{E}[(\tilde{G} - \mathbf{E}\tilde{G})M(\tilde{G} - \mathbf{E}\tilde{G})] = \\ \sum_{i=1}^n \left\{ \mathbf{E}[1_{\|Z_i\| > R} Z_i M Z_i] + \mathbf{E}[1_{\|Z_i\| \leq R} Z_i] M \mathbf{E}[1_{\|Z_i\| \leq R} Z_i] \right\} \geq 0.$$

Now note that as $\mathbf{E}[Z_i] = 0$, we have $\mathbf{E}[1_{\|Z_i\| \leq R} Z_i] = -\mathbf{E}[1_{\|Z_i\| > R} Z_i]$. Moreover, for any self-adjoint random matrix Y , we have $\mathbf{E}[Y] M \mathbf{E}[Y] \leq \mathbf{E}[Y]^2 \leq \mathbf{E}[Y^2]$ using $\|M\| \leq 1$ and Jensen's inequality. We therefore obtain

$$\|\mathbf{E}[(G - \mathbf{E}G)M(G - \mathbf{E}G)] - \mathbf{E}[(\tilde{G} - \mathbf{E}\tilde{G})M(\tilde{G} - \mathbf{E}\tilde{G})]\| \leq 2 \sup_{\|v\|=1} \sum_{i=1}^n \mathbf{E}[1_{\|Z_i\| > R} \|Z_i v\|^2].$$

To proceed, let Z'_i be independent copies of Z_i , and note that

$$\begin{aligned} \sum_{i=1}^n \mathbf{E}[1_{\|Z_i\| > R} \|Z_i v\|^2] &\leq \sum_{i=1}^n \mathbf{E}[1_{\max_j \|Z_j\| > R} \|Z_i v\|^2] \\ &\leq \sum_{i=1}^n \mathbf{E}[1_{\max_j \|Z_j\| > R} (\|Z_i v\|^2 - \|Z'_i v\|^2)] + \mathbf{P}[\max_j \|Z_j\| > R] \sigma(X)^2 \end{aligned}$$

for $\|v\| = 1$. Moreover, we have

$$\begin{aligned} \sum_{i=1}^n \mathbf{E}[1_{\max_j \|Z_j\| > R} (\|Z_i v\|^2 - \|Z'_i v\|^2)] &\leq \mathbf{E}\left[\left|\sum_{i=1}^n (\|Z_i v\|^2 - \|Z'_i v\|^2)\right|\right] = \\ \mathbf{E}\left[\left|\sum_{i=1}^n \varepsilon_i (\|Z_i v\|^2 - \|Z'_i v\|^2)\right|\right] &\leq 2 \mathbf{E}\left[\left|\sum_{i=1}^n \varepsilon_i \|Z_i v\|^2\right|\right] \leq 2 \mathbf{E}\left[\left(\sum_{i=1}^n \|Z_i v\|^4\right)^{\frac{1}{2}}\right], \end{aligned}$$

where ε_i are i.i.d. random signs that are independent of the other variables, we used that the distribution of (Z_i, Z'_i) is invariant under exchanging Z_i and Z'_i for any i , and we applied Jensen's inequality conditionally on (Z_i) in the last inequality. Bounding $\|Z_i v\|^4 \leq (\max_j \|Z_j\|^2) \|Z_i v\|^2$ and applying Cauchy-Schwarz yields

$$\sum_{i=1}^n \mathbf{E}[1_{\max_j \|Z_j\| > R} (\|Z_i v\|^2 - \|Z'_i v\|^2)] \leq 2 \mathbf{E}[\max_j \|Z_j\|^2]^{\frac{1}{2}} \sigma(X)$$

for $\|v\| = 1$. Putting together all the above estimates yields

$$\begin{aligned} \|\mathbf{E}[(G - \mathbf{E}G)M(G - \mathbf{E}G)] - \mathbf{E}[(\tilde{G} - \mathbf{E}\tilde{G})M(\tilde{G} - \mathbf{E}\tilde{G})]\| &\leq \\ 2 \mathbf{P}[\max_j \|Z_j\| > R] \sigma(X)^2 + 4 \mathbf{E}[\max_j \|Z_j\|^2]^{\frac{1}{2}} \sigma(X) &\leq 6 \mathbf{E}[\max_j \|Z_j\|^2]^{\frac{1}{2}} \sigma(X) \end{aligned}$$

for $R \geq \mathbf{E}[\max_j \|Z_j\|^2]^{\frac{1}{4}} \sigma(X)^{\frac{1}{2}}$ using Markov's inequality in the last step.

Finally, note that any matrix M with $\|M\| \leq 1$ can be written as $M = \operatorname{Re} M + i \operatorname{Im} M$ with $\|\operatorname{Re} M\| = \frac{1}{2} \|M + M^*\| \leq 1$ and $\|\operatorname{Im} M\| = \frac{1}{2} \|M - M^*\| \leq 1$. As any self-adjoint matrix is the difference of its positive and negative parts, we can write $M = M_1 - M_2 + i M_3 - i M_4$ with $M_i \geq 0$ with $\|M_i\| \leq 1$. Applying the above estimate to each M_i and using the triangle inequality concludes the proof. \square

Finally, we must bound the matrix parameters of \tilde{X} .

Lemma 8.6. *We have $R(\tilde{X}) \leq 2R$, $\sigma_*(\tilde{X}) \leq \sigma_*(X)$, and $\sigma(\tilde{X}) \leq \sigma(X)$.*

Proof. The first inequality follows immediately from

$$R(\tilde{X}) = \left\| \max_{1 \leq i \leq n} \|1_{\|Z_i\| \leq R} Z_i - \mathbf{E}[1_{\|Z_i\| \leq R} Z_i]\| \right\|_\infty$$

and the triangle inequality. Next, note that for any (complex) random variable Y and event A , we have $\mathbf{E}[|1_A Y - \mathbf{E}[1_A Y]|^2] \leq \mathbf{E}[1_A |Y|^2] \leq \mathbf{E}[|Y|^2]$. Thus

$$\begin{aligned} \mathbf{E}[|\langle v, (\tilde{X} - \mathbf{E}\tilde{X})w \rangle|^2] &= \sum_{i=1}^n \mathbf{E}[|1_{\|Z_i\| \leq R} \langle v, Z_i w \rangle - \mathbf{E}[1_{\|Z_i\| \leq R} \langle v, Z_i w \rangle]|^2] \\ &\leq \sum_{i=1}^n \mathbf{E}[|\langle v, Z_i w \rangle|^2] = \mathbf{E}[|\langle v, (X - \mathbf{E}X)w \rangle|^2] \end{aligned}$$

for any nonrandom vectors v, w . The remaining bounds follow, respectively, by taking the supremum over $\|v\| = \|w\| = 1$, or by summing over the coordinate basis $w = e_k$ and then taking the supremum over $\|v\| = 1$. \square

8.3. Proof of Theorems 2.8 and 2.11. We now put everything together.

Proof of Theorem 2.8. As $X = \tilde{X}$ on the event $\{\max_i \|Z_i\| \leq R\}$, we obtain

$$\begin{aligned} \mathbf{P}\left[d_H(\text{sp}(X), \text{sp}(\tilde{G})) > C\tilde{\varepsilon}(t), \max_{1 \leq i \leq n} \|Z_i\| \leq R\right] \\ \leq \mathbf{P}\left[d_H(\text{sp}(\tilde{X}), \text{sp}(\tilde{G})) > C\tilde{\varepsilon}(t)\right] \leq de^{-t} \end{aligned}$$

with

$$\tilde{\varepsilon}(t) := \sigma_*(\tilde{X}) t^{\frac{1}{2}} + R(\tilde{X})^{\frac{1}{3}} \sigma(\tilde{X})^{\frac{2}{3}} t^{\frac{2}{3}} + R(\tilde{X}) t.$$

from Theorem 2.6. Moreover, we can replace $\tilde{\varepsilon}(t)$ by $\varepsilon_R(t)$ on the left-hand side of the above inequality as $\tilde{\varepsilon}(t) \leq \varepsilon_R(t)$ by Lemma 8.6.

On the other hand, Proposition 8.2 and Lemmas 8.4, 8.5 and 8.6 imply

$$\mathbf{P}\left[d_H(\text{sp}(\tilde{G}), \text{sp}(G)) > C\{R + \sigma_*(X)\}t^{\frac{1}{2}}\right] \leq de^{-t}$$

for all $t \geq 0$ and $R \geq R_0 := \bar{R}(X)^{\frac{1}{2}} \sigma(X)^{\frac{1}{2}} + \sqrt{2} \bar{R}(X)$. Here we used that we may assume without loss of generality that $t \geq \log d$ in the above estimate (as otherwise the right-hand side exceeds one and the bound is trivial), and that $\Delta(G, \tilde{G}) \leq 24R^2$ by the assumption on R and Lemma 8.5. We may once again replace $\{R + \sigma_*(X)\}t^{\frac{1}{2}}$ by $\varepsilon_R(t)$ on the left-hand side as $t^{\frac{1}{2}} \lesssim t$ for $t \geq \log d$.

Combining the above bounds, we obtain

$$\begin{aligned} &\mathbf{P}\left[d_H(\text{sp}(X), \text{sp}(G)) > 2C\varepsilon_R(t), \max_{1 \leq i \leq n} \|Z_i\| \leq R\right] \\ &\leq \mathbf{P}\left[d_H(\text{sp}(X), \text{sp}(\tilde{G})) + d_H(\text{sp}(\tilde{G}), \text{sp}(G)) > 2C\varepsilon_R(t), \max_{1 \leq i \leq n} \|Z_i\| \leq R\right] \\ &\leq \mathbf{P}\left[d_H(\text{sp}(X), \text{sp}(\tilde{G})) > C\varepsilon_R(t), \max_{1 \leq i \leq n} \|Z_i\| \leq R\right] \\ &\quad + \mathbf{P}\left[d_H(\text{sp}(\tilde{G}), \text{sp}(G)) > C\varepsilon_R(t)\right] \leq 2de^{-t}. \end{aligned}$$

As in the proof of Theorem 2.6, the upper bound can be replaced by de^{-t} if we increase the value of the universal constant on the left-hand side.

This concludes the proof of the tail bound. To prove the expectation bound, note that choosing $R = R_0 t$ in the tail bound yields

$$\mathbf{P}[d_H(\text{sp}(X), \text{sp}(G)) > C\delta(t)] \leq e^{-t/2} + \mathbf{P}\left[\max_{1 \leq i \leq n} \|Z_i\| > R_0 t\right]$$

for $t \geq 2 \log d$, where

$$\delta(t) := \sigma_*(X) t^{\frac{1}{2}} + R_0^{\frac{1}{3}} \sigma(X)^{\frac{2}{3}} t + R_0 t^2$$

and we used $de^{-t} \leq e^{-t/2}$ for $t \geq 2 \log d$. We now compute

$$\begin{aligned} \mathbf{E}[\mathbf{d}_H(\mathbf{sp}(X), \mathbf{sp}(G))] &\leq C\delta(2 \log d) + \int_{C\delta(2 \log 2)}^{\infty} \mathbf{P}[\mathbf{d}_H(\mathbf{sp}(X), \mathbf{sp}(G)) > x] dx \\ &= C\delta(2 \log d) + C \int_{2 \log d}^{\infty} \mathbf{P}[\mathbf{d}_H(\mathbf{sp}(X), \mathbf{sp}(G)) > C\delta(t)] \frac{d\delta(t)}{dt} dt \\ &\leq C\delta(2 \log d) + C \int_0^{\infty} e^{-t/2} \frac{d\delta(t)}{dt} dt + C \int_0^{\infty} \mathbf{P}\left[\max_{1 \leq i \leq n} \|Z_i\| > R_0 t\right] \frac{d\delta(t)}{dt} dt \\ &\lesssim \delta(2 \log d) + \mathbf{E}[\delta(\max_i \|Z_i\|/R_0)] \lesssim \delta(2 \log d). \end{aligned}$$

The conclusion follows readily using the assumption $\bar{R}(X)(\log d)^3 \lesssim \sigma(X)$. \square

Proof of Theorem 2.11. As $X = \tilde{X}$ on the event $\{\max_i \|Z_i\| \leq R\}$, we have

$$\mathbf{E}[(z\mathbf{1} - X)^{-1}] = \mathbf{E}[(z\mathbf{1} - \tilde{X})^{-1}] + \mathbf{E}[\{(z\mathbf{1} - X)^{-1} - (z\mathbf{1} - \tilde{X})^{-1}\} \mathbf{1}_{\max_i \|Z_i\| > R}].$$

Thus Markov's inequality yields

$$\|\mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - \tilde{X})^{-1}]\| \leq \frac{2 \mathbf{P}[\max_i \|Z_i\| > R]}{\operatorname{Im} z} \leq \frac{2\bar{R}(X)^2}{R^2 \operatorname{Im} z}.$$

Applying Theorem 2.10 and Lemmas 8.3, 8.4, 8.5 and 8.6 yields

$$\|\mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}]\| \lesssim \frac{\bar{R}(X)^2}{R^2 \operatorname{Im} z} + \frac{\sigma_*(X)}{(\operatorname{Im} z)^2} + \frac{R^2}{(\operatorname{Im} z)^3} + \frac{R\sigma(X)^2 + R^3 \log d}{(\operatorname{Im} z)^4}$$

for $R \geq R_0 := \bar{R}(X)^{\frac{1}{2}}\sigma(X)^{\frac{1}{2}} + \sqrt{2}\bar{R}(X)$.

Now assume first that $\operatorname{Im} z \geq R_0$ and choose $R = R_0^{\frac{1}{2}}(\operatorname{Im} z)^{\frac{1}{2}}$. Then we obtain

$$\|\mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}]\| \lesssim \frac{\sigma_*(X) + R_0}{(\operatorname{Im} z)^2} + \frac{R_0^{\frac{3}{2}} \log d}{(\operatorname{Im} z)^{\frac{5}{2}}} + \frac{R_0^{\frac{1}{2}} \sigma(X)^2}{(\operatorname{Im} z)^{\frac{7}{2}}}.$$

In particular, if $\operatorname{Im} z \geq R_0^{\frac{1}{5}}\sigma(X)^{\frac{4}{5}} + R_0(\log d)^{\frac{2}{3}}$, we obtain

$$\|\mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}]\| \lesssim \frac{\sigma_*(X) + R_0^{\frac{1}{5}}\sigma(X)^{\frac{4}{5}} + R_0(\log d)^{\frac{2}{3}}}{(\operatorname{Im} z)^2}.$$

On the other hand, for $\operatorname{Im} z < R_0^{\frac{1}{5}}\sigma(X)^{\frac{4}{5}} + R_0(\log d)^{\frac{2}{3}}$ we can estimate

$$\|\mathbf{E}[(z\mathbf{1} - X)^{-1}] - \mathbf{E}[(z\mathbf{1} - G)^{-1}]\| \leq \frac{2}{\operatorname{Im} z} \lesssim \frac{R_0^{\frac{1}{5}}\sigma(X)^{\frac{4}{5}} + R_0(\log d)^{\frac{2}{3}}}{(\operatorname{Im} z)^2}.$$

If $\bar{R}(X)(\log d)^{\frac{5}{3}} \lesssim \sigma(X)$, then $R_0(\log d)^{\frac{2}{3}} \lesssim R_0^{\frac{1}{5}}\sigma(X)^{\frac{4}{5}} \asymp \bar{R}(X)^{\frac{1}{10}}\sigma(X)^{\frac{9}{10}}$, and the first part of the theorem follows. The second part of the theorem now follows from [9, Lemma 5.11] as in the proof of Theorem 2.10. \square

9. APPLICATIONS: PROOFS

9.1. Random lifts. The aim of this section is to prove Theorem 3.13. We will first prove a more general result, and then specialize to the case of lifts.

9.1.1. *Strong convergence.* In this section, we let Π_1, \dots, Π_k be i.i.d. uniformly distributed random $n \times n$ permutation matrices, and we fix $A_1, \dots, A_k \in M_d(\mathbb{C})$. We consider the random matrix

$$X = \sum_{i=1}^k (A_i \otimes \Pi_i + A_i^* \otimes \Pi_i^*),$$

and let X^\perp be its restriction to $\mathbb{C}^d \otimes 1^\perp$. Recall that if s_1, \dots, s_{2k} is a free semicircular family, then c_1, \dots, c_k defined by $c_j = \frac{s_j + i s_{k+j}}{\sqrt{2}}$ is a free circular family.

Proposition 9.1. *Let c_1, \dots, c_k be a free circular family, and define*

$$X_F = \sum_{i=1}^k \left\{ \left((1 - \varepsilon^2)^{\frac{1}{2}} A_i + \varepsilon A_i^* \right) \otimes c_i + \left((1 - \varepsilon^2)^{\frac{1}{2}} A_i + \varepsilon A_i^* \right)^* \otimes c_i^* \right\}$$

with $\varepsilon = \frac{1}{\sqrt{n-1}(\sqrt{n} + \sqrt{n-2})}$. Then

$$\mathbf{P}[\|X^\perp\| \geq \|X_F\| + C\{v^{\frac{1}{2}}\sigma^{\frac{1}{2}}(\log nd)^{\frac{3}{4}} + vt^{\frac{1}{2}} + R^{\frac{1}{3}}\sigma^{\frac{2}{3}}t^{\frac{2}{3}} + Rt\}] \leq 2nde^{-t}$$

for all $t \geq 0$, where C is a universal constant and

$$\sigma = \left\| \sum_{i=1}^k \left(A_i A_i^* + A_i^* A_i + \frac{A_i^2 + A_i^{*2}}{n-1} \right) \right\|^{\frac{1}{2}}, \quad R = 2 \max_{1 \leq i \leq k} \|A_i\|,$$

and

$$v = \frac{2}{\sqrt{n-1}} \left\| \text{Cov} \left(\sum_{i=1}^k A_i g_i \right) \right\|^{\frac{1}{2}},$$

where g_1, \dots, g_k are i.i.d. standard real Gaussians.

Proposition 9.1 is an immediate consequence of Theorem 2.16 once we prove that $\sigma(X^\perp) = \sigma$, $R(X^\perp) \leq R$, $\sigma_*(X^\perp) \leq v(X^\perp) \leq v$, and $\|X_{\text{free}}^\perp\| = \|X_F\|$. These facts will be established in the following lemmas, concluding the proof.

Lemma 9.2. *We have $\sigma(X^\perp) = \sigma$ and $R(X^\perp) \leq R$.*

Proof. The bound on $R(X^\perp)$ follows immediately from $\|\Pi_i\| = 1$. To compute $\sigma(X^\perp)$, we note that the restriction of Π_i to 1^\perp a random matrix as in Lemma 3.5 with $d = n - 1$ and $s = 1$ (as this is an $(n - 1)$ -dimensional real representation of the symmetric group; alternatively, the conclusions of Lemma 3.5 can be verified in this case by a direct computation). We can therefore compute

$$\mathbf{E}[X^\perp] = 0, \quad \mathbf{E}[(X^\perp)^2] = \sum_{i=1}^k \left(A_i A_i^* + A_i^* A_i + \frac{A_i^2 + A_i^{*2}}{n-1} \right) \otimes \mathbf{1},$$

and the conclusion follows immediately. \square

Lemma 9.3. *We have $\|X_{\text{free}}^\perp\| = \|X_F\|$.*

Proof. Let $\bar{c}_i := (1 - \varepsilon^2)^{\frac{1}{2}} c_i + \varepsilon c_i^*$. Then we write

$$X_{\text{free}}^\perp = \sum_{i=1}^k (A_i \otimes \Pi_{i,\text{free}}^\perp + A_i^* \otimes \bar{\Pi}_{i,\text{free}}^{\perp*}), \quad X_F = \sum_{i=1}^k (A_i \otimes \bar{c}_i + A_i^* \otimes \bar{c}_i^*).$$

Now note that

$$\tau(\bar{c}_i) = 0, \quad \tau(\bar{c}_i \bar{c}_i^*) = \tau(\bar{c}_i^* \bar{c}_i) = 1, \quad \tau(\bar{c}_i^2) = \tau((\bar{c}_i^*)^2) = \frac{1}{n-1},$$

while applying Lemma 3.5 as in the proof of Lemma 9.2 yields

$$\mathbf{E}[\Pi_i^\perp] = 0, \quad \mathbf{E}[\Pi_i^\perp \Pi_i^{\perp*}] = \mathbf{E}[\Pi_i^{\perp*} \Pi_i^\perp] = \mathbf{1}, \quad \mathbf{E}[(\Pi_i^\perp)^2] = \mathbf{E}[(\Pi_i^{\perp*})^2] = \frac{1}{n-1} \mathbf{1}.$$

The conclusion follows as in the proof of [9, Lemma 7.9]. \square

Lemma 9.4. *We have $v(X^\perp) \leq v$.*

Proof. By Lemma 3.5, we have

$$\text{Cov}(A_i \otimes \Pi_i^\perp) = \iota(A_i)\iota(A_i)^* \otimes \text{Cov}(\Pi_i^\perp) = \iota(A_i)\iota(A_i)^* \otimes \frac{1}{n-1} \mathbf{1},$$

where $\iota : M_d(\mathbb{C}) \rightarrow \mathbb{C}^{d^2}$ maps a matrix to its vector of entries. Therefore, as Π_1, \dots, Π_k are independent, we have

$$\text{Cov}\left(\sum_{i=1}^k A_i \otimes \Pi_i^\perp\right) = \sum_{i=1}^k \text{Cov}(A_i \otimes \Pi_i^\perp) = \frac{1}{n-1} \text{Cov}\left(\sum_{i=1}^k A_i g_i\right) \otimes \mathbf{1}.$$

The conclusion follows from the triangle inequality $v(A + B) \leq v(A) + v(B)$. \square

9.1.2. Free generators and circular variables. The operator X_F in Proposition 9.1 is defined by a free circular family. In the study of random lifts, however, we are interested in the analogous operator where the circular variables c_i are replaced by the left-regular representation $\lambda(g_i)$ of the free generators of F_k . We presently establish a comparison principle between these objects.

Proposition 9.5. *Let c_1, \dots, c_k be a free circular family and let g_1, \dots, g_k be free generators of F_k . Then for any $A_1, \dots, A_k \in M_d(\mathbb{C})$, we have*

$$\left\| \sum_{i=1}^k (A_i \otimes c_i + A_i^* \otimes c_i^*) \right\| \leq \left\| \sum_{i=1}^k (A_i \otimes \lambda(g_i) + A_i^* \otimes \lambda(g_i)^*) \right\| + 2\tilde{\sigma}^{\frac{1}{2}}\tilde{R}^{\frac{1}{2}},$$

where $\tilde{\sigma}^2 = \left\| \sum_{i=1}^k (A_i A_i^* + A_i^* A_i) \right\|$ and $\tilde{R} = \max_{1 \leq i \leq k} \|A_i\|$.

Proof. We proceed in several steps.

Step 1. We begin by noting that if c_1, \dots, c_k is a circular family, c_1^*, \dots, c_k^* is also a circular family. We can therefore write

$$\left\| \sum_{i=1}^k (A_i \otimes c_i + A_i^* \otimes c_i^*) \right\| = \left\| \sum_{i=1}^k (A_i^* \otimes c_i + A_i \otimes c_i^*) \right\| = \left\| \sum_{i=1}^k (\tilde{A}_i \otimes c_i + \tilde{B}_i \otimes c_i^*) \right\|,$$

where we defined the self-adjoint matrices

$$\tilde{A}_i = \begin{bmatrix} 0 & A_i \\ A_i^* & 0 \end{bmatrix}, \quad \tilde{B}_i = \begin{bmatrix} 0 & A_i^* \\ A_i & 0 \end{bmatrix}.$$

Similarly, if g_1, \dots, g_k are free generators of F_k , then $g_1^{-1}, \dots, g_k^{-1}$ are as well, and thus the analogous identities holds when c_i is replaced by $\lambda(g_i)$.

Step 2. For any $A, M \in M_d(\mathbb{C})_{\text{sa}}$ with $M > 0$, define

$$R_A(M) = M^{\frac{1}{2}} \left(\left(\mathbf{1} + (M^{-\frac{1}{2}} A M^{-\frac{1}{2}})^2 \right)^{\frac{1}{2}} - \mathbf{1} \right) M^{\frac{1}{2}}.$$

Then by [54, Theorem 1.1 and p. 454], we have

$$\left\| \sum_{i=1}^k (\tilde{A}_i \otimes \lambda(g_i) + \tilde{B}_i \otimes \lambda(g_i)^*) \right\| = \inf_{M > 0} \left\| 2M + \sum_{i=1}^k (R_{\tilde{A}_i}(M) + R_{\tilde{B}_i}(M)) \right\|.$$

On the other hand, as the circular family c_1, \dots, c_k can be realized by setting $c_i = l_i + l_{k+i}^*$ where l_1, \dots, l_{2k} are canonical creation operators on the free Fock space (cf. [54, §1.2]), we obtain by [54, Corollary 1.4]

$$\left\| \sum_{i=1}^k (\tilde{A}_i \otimes c_i + \tilde{B}_i \otimes c_i^*) \right\| \leq \inf_{M>0} \left\| 2M + \sum_{i=1}^k \frac{\tilde{A}_i M^{-1} \tilde{A}_i + \tilde{B}_i M^{-1} \tilde{B}_i}{2} \right\|.$$

Step 3. We claim that for any $\delta > 0$, there exists $M \geq \frac{\delta}{2} \mathbf{1}$ so that

$$2M + \sum_{i=1}^k (R_{\tilde{A}_i}(M) + R_{\tilde{B}_i}(M)) = \left(\left\| \sum_{i=1}^k (\tilde{A}_i \otimes \lambda(g_i) + \tilde{B}_i \otimes \lambda(g_i)^*) \right\| + \delta \right) \mathbf{1}.$$

Indeed, let $\tilde{g}_1, \dots, \tilde{g}_{2k}$ be the free generators of the free product $\mathbb{Z}_2 * \dots * \mathbb{Z}_2$ of $2k$ copies of \mathbb{Z}_2 , and define the operator $\tilde{X} = \sum_{i=1}^k (\tilde{A}_i \otimes \lambda(\tilde{g}_i) + \tilde{B}_i \otimes \lambda(\tilde{g}_{i+k}))$. Then [54, Theorem 1.1, Lemma 2.3 and Proposition 3.1] show that the above identity is satisfied if we choose the matrix M so that $(2M)^{-1} = (\text{id} \otimes \tau)[((\|\tilde{X}\| + \delta)\mathbf{1} - \tilde{X})^{-1}]$. As $\|\tilde{X}\|\mathbf{1} - \tilde{X} \geq 0$, we clearly have $(2M)^{-1} \leq \delta^{-1}\mathbf{1}$, establishing the claim.

Step 4. Define the function

$$h(x) = \frac{x^2}{2} - ((1+x^2)^{\frac{1}{2}} - 1) = \frac{x^4}{2((1+x^2)^{\frac{1}{2}} + 1)^2}.$$

Then clearly $h(x) \leq \frac{1}{8}x^4$. Thus we have for any self-adjoint A, M with $M > 0$

$$\frac{AM^{-1}A}{2} \leq R_A(M) + \frac{AM^{-1}AM^{-1}AM^{-1}A}{8},$$

where we used that $\frac{1}{2}AM^{-1}A - R_A(M) = M^{\frac{1}{2}}h(M^{-\frac{1}{2}}AM^{-\frac{1}{2}})M^{\frac{1}{2}}$.

Step 5. We now put everything together. Let $\delta > 0$ and choose M as in Step 3. Then we can estimate

$$\begin{aligned} \left\| \sum_{i=1}^k (A_i \otimes c_i + A_i^* \otimes c_i^*) \right\| &\leq \left\| 2M + \sum_{i=1}^k \frac{\tilde{A}_i M^{-1} \tilde{A}_i + \tilde{B}_i M^{-1} \tilde{B}_i}{2} \right\| \\ &\leq \left\| \sum_{i=1}^k (A_i \otimes \lambda(g_i) + A_i^* \otimes \lambda(g_i)^*) \right\| + \delta \\ &\quad + \left\| \sum_{i=1}^k \frac{\tilde{A}_i M^{-1} \tilde{A}_i M^{-1} \tilde{A}_i M^{-1} \tilde{A}_i + \tilde{B}_i M^{-1} \tilde{B}_i M^{-1} \tilde{B}_i M^{-1} \tilde{B}_i}{8} \right\| \\ &\leq \left\| \sum_{i=1}^k (A_i \otimes \lambda(g_i) + A_i^* \otimes \lambda(g_i)^*) \right\| + \delta + \frac{\max_i(\|\tilde{A}_i\|^2 \vee \|\tilde{B}_i\|^2)}{\delta^3} \left\| \sum_{i=1}^k (\tilde{A}_i^2 + \tilde{B}_i^2) \right\|, \end{aligned}$$

where we used $\langle v, \tilde{A}_i M^{-1} \tilde{A}_i M^{-1} \tilde{A}_i M^{-1} \tilde{A}_i v \rangle \leq \|\tilde{A}_i v\|^2 \|M^{-1}\|^3 \|\tilde{A}_i\|^2$ (and analogously for \tilde{B}_i) and $M \geq \frac{\delta}{2}$ in the last line. As $\max_i(\|\tilde{A}_i\|^2 \vee \|\tilde{B}_i\|^2) = \tilde{R}^2$ and $\|\sum_i(\tilde{A}_i^2 + \tilde{B}_i^2)\| = \tilde{\sigma}^2$, the conclusion follows by choosing $\delta = \tilde{\sigma}^{\frac{1}{2}} \tilde{R}^{\frac{1}{2}}$. \square

9.1.3. *Random n -lifts.* We now specialize the above results to the situation of random n -lifts. That is, we fix a base graph $H = ([d], E_H)$, set $k = |E_H|$, and $A_e = e_i e_j^*$ for $e = (i, j) \in E_H$, $i \leq j$. Then the random matrix $X = X^{(n)}$ is the adjacency matrix of the random n -lift of H . Let us begin by estimating the parameters that appear in Propositions 9.1 and 9.5 in this case.

Lemma 9.6. *Denote by $D(H)$ the maximal degree of a vertex of H and by $M(H)$ the maximal multiplicity of an edge of H . Then we have*

$$\tilde{\sigma}^2 \leq \sigma^2 \leq 2D(H), \quad v^2 = \frac{4M(H)}{n-1}, \quad \tilde{R} \leq R \leq 2.$$

Proof. That $\tilde{R} \leq R \leq 2$ is immediate. Now let $A_e = e_i e_j^*$ for $e = (i, j) \in E_H$. Then $A_e A_e^* + A_e^* A_e = e_i e_i^* + e_j e_j^*$ and $A_e^2 + A_e^{*2} = 2e_i e_i^* \mathbf{1}_{i=j}$. Therefore

$$\left\| \sum_{e \in E_H} (A_e A_e^* + A_e^* A_e) \right\| = D(H), \quad \left\| \sum_{e \in E_H} (A_e^2 + A_e^{*2}) \right\| = 2L(H) \leq D(H),$$

where $L(H)$ denotes the maximal number of self-loops attached to a vertex of H . The bounds on $\tilde{\sigma}, \sigma$ follows. Finally, note that $\sum_{e \in E_H} A_e g_e$, where $(g_e)_{e \in E_H}$ are i.i.d. standard real Gaussians, is a matrix with independent entries such that the variance of its (i, j) entry for $i \leq j$ is the number of edges in H between vertices i and j . The computation of v follows immediately. \square

Combining Proposition 9.1 and Lemma 9.6 yields an analogue of Theorem 3.13, in which $\varrho(\hat{H})$ is replaced by $\|X_F\|$. Moreover, Proposition 9.5 and (3.3) readily imply that $\|X_F\| \leq (1 + Cn^{-1} + CD(H)^{-\frac{1}{4}})\varrho(\hat{H})$. Thus the conclusion of Theorem 3.13 holds even when H has self-loops, but with an extra $O(n^{-1})$ error term. However, when H has no self-loops, the special structure of the coefficients A_e enables us to eliminate the $O(n^{-1})$ term, so that the bound can be sharp even when $n \not\rightarrow \infty$.

Lemma 9.7. *If H has no self-loops, then*

$$\|X_F\| \leq \left(1 + \frac{C}{D(H)^{\frac{1}{4}}}\right) \varrho(\hat{H})$$

for a universal constant C .

Proof. Let ε be as in Proposition 9.1. As H is loopless, all A_e are of the form $A = e_i e_j^*$ with $i < j$. If we define $A_\varepsilon = (1 - \varepsilon^2)^{\frac{1}{2}} A + \varepsilon A^*$, then we can compute

$$A_\varepsilon M A_\varepsilon^* + A_\varepsilon^* M A_\varepsilon = M_{jj} e_i e_i^* + M_{ii} e_j e_j^* + \frac{M_{ji} e_i e_j^* + M_{ij} e_j e_i^*}{n-1}.$$

The circular family $(c_e)_{e \in E_H}$ can be realized as $c_e = l_e + \tilde{l}_e^*$ where l_e, \tilde{l}_e are canonical creation operators on a free Fock space [54, §1.2], we have [54, Theorem 1.3]

$$\|X_F\| = \inf_{M > 0} \left\| M^{-1} + \sum_{e \in E_H} (A_{e\varepsilon} M A_{e\varepsilon}^* + A_{e\varepsilon}^* M A_{e\varepsilon}) \right\|,$$

and moreover the infimum is attained by an M so that the quantity inside the norm on the right-hand side is proportional to the identity. We can now reason precisely

as in the proof of [9, Lemma 3.2] that the infimum in the above expression can be taken over diagonal matrices only. Therefore

$$\|X_F\| = \inf_{x \in \mathbb{R}^d, x > 0} \max_{i \in [d]} \left\{ \frac{1}{x_i} + \sum_{j \in [d]: j \sim i} x_j \right\},$$

where $j \sim i$ denotes that there is an edge between i, j in H . As the latter expression does not depend on n , we can conclude that when H has no self-loops, $\|X_F\|$ is unchanged if we set $\varepsilon = 0$. Then Proposition 9.5, (3.3), and Lemma 9.6 yield

$$\|X_F\| \leq \varrho(\hat{H}) + CD(H)^{\frac{1}{4}}.$$

It remains to note that $\varrho(\hat{H}) \geq D(H)^{\frac{1}{2}}$ by (3.3) and [66, eq. (9.7.2)]. \square

We now conclude the proof of Theorem 3.13.

Proof of Theorem 3.13. Applying Proposition 9.1 with $t = (a + 2) \log nd$ yields

$$\mathbf{P} \left[\|X^{(n)\perp}\| \geq \left(1 + C \frac{M(H)^{\frac{1}{4}}}{n^{\frac{1}{4}}} \frac{(\log nd)^{\frac{3}{4}}}{D(H)^{\frac{1}{4}}} + C \frac{(\log nd)^{\frac{2}{3}}}{D(H)^{\frac{1}{6}}} + C \frac{\log nd}{D(H)^{\frac{1}{2}}} \right) \varrho(\hat{H}) \right] \leq (nd)^{-a}$$

using Lemmas 9.6 and 9.7, that $\varrho(\hat{H}) \geq D(H)^{\frac{1}{2}}$ as in the proof of Lemma 9.7, and that $M(H) \leq D(H)$. Here C is a constant that depends on a only. \square

9.2. Smallest singular value. The aim of this section is to prove Theorem 3.16. The proof is based on the following linearization lemma, which we state in a slightly more general form than is needed here as it will be used again in section 9.3.

Lemma 9.8. *Let Y be a $d \times m$ random matrix, and let $B \geq 0$ be a nonrandom $m \times m$ positive semidefinite matrix. Define the $(d+2m) \times (d+2m)$ random matrix*

$$\hat{Y}_\varepsilon := \begin{bmatrix} 0 & Y^* & (B + 4\varepsilon^2 \mathbf{1})^{\frac{1}{2}} \\ Y & 0 & 0 \\ (B + 4\varepsilon^2 \mathbf{1})^{\frac{1}{2}} & 0 & 0 \end{bmatrix},$$

and let $\hat{Y}_{\varepsilon, \text{free}}$ be its noncommutative model. Then

$$\begin{aligned} \text{sp}(\hat{Y}_\varepsilon) \subseteq \text{sp}(\hat{Y}_{\varepsilon, \text{free}}) + [-\varepsilon, \varepsilon] &\implies \\ \begin{cases} \lambda_{\max}(Y^*Y + B + 4\varepsilon^2 \mathbf{1})^{\frac{1}{2}} \leq \lambda_{\max}(Y_{\text{free}}^*Y_{\text{free}} + B \otimes \mathbf{1} + 4\varepsilon^2 \mathbf{1})^{\frac{1}{2}} + \varepsilon, \\ \lambda_{\min}(Y^*Y + B + 4\varepsilon^2 \mathbf{1})^{\frac{1}{2}} \geq \lambda_{\min}(Y_{\text{free}}^*Y_{\text{free}} + B \otimes \mathbf{1} + 4\varepsilon^2 \mathbf{1})^{\frac{1}{2}} - \varepsilon \end{cases} \end{aligned}$$

for any $\varepsilon \geq 0$, where $\lambda_{\max}(X) := \sup \text{sp}(X)$ and $\lambda_{\min}(X) := \inf \text{sp}(X)$.

Proof. The proof is identical to that of [9, Lemma 3.13]. \square

We can now complete the proof of Theorem 3.16.

Proof of Theorem 3.16. We readily compute $\sigma_*(\hat{Y}_\varepsilon) = \sigma_*(Y)$, $\sigma(\hat{Y}_\varepsilon) = \sigma(Y)$, and $v(\hat{Y}_\varepsilon) \leq \sqrt{2} v(Y)$ by [9, Lemma 4.10], while clearly $R(\hat{Y}_\varepsilon) = R(Y)$ by Remark 2.1. Applying Theorem 2.16 and Lemma 9.8 with $B = 0$ therefore yields

$$\mathbf{P} [\lambda_{\min}(Y^*Y + 4\delta(t)^2 \mathbf{1})^{\frac{1}{2}} \leq \lambda_{\min}(Y_{\text{free}}^*Y_{\text{free}} + 4\delta(t)^2 \mathbf{1})^{\frac{1}{2}} - \delta(t)] \leq 6de^{-t},$$

where

$$\delta(t) = C \{ v(Y)^{\frac{1}{2}} \sigma(Y)^{\frac{1}{2}} (\log d)^{\frac{3}{4}} + \sigma_*(Y) t^{\frac{1}{2}} + R(Y)^{\frac{1}{3}} \sigma(Y)^{\frac{2}{3}} t^{\frac{2}{3}} + R(Y) t \}$$

for a universal constant C . Using that $\lambda_{\min}(Y_{\text{free}}^* Y_{\text{free}} + 4\delta(t)^2 \mathbf{1})^{\frac{1}{2}} \geq \text{s}_{\min}(Y_{\text{free}})$ and $\lambda_{\min}(Y^* Y + 4\delta(t)^2 \mathbf{1})^{\frac{1}{2}} \leq \text{s}_{\min}(Y) + 2\delta(t)$, we obtain

$$\mathbf{P}[\text{s}_{\min}(Y) \leq \text{s}_{\min}(Y_{\text{free}}) - 3\delta(t)] \leq 6de^{-t}.$$

It remains to note that we can replace $6d$ by d on the right-hand side if we increase the universal constant C (as in the last step of the proof of Theorem 2.6). \square

9.3. Sample covariance matrices.

9.3.1. *Proof of Theorem 3.21.* Gaussian random matrices are unbounded but possess moments of all orders. Therefore, a result along the lines of Theorem 3.21 can be proved either using Theorem 2.8 or using Theorem 2.9. These two approaches yield similar conclusions; we have chosen the latter approach here as it yields a slightly cleaner bound in the present setting. In preparation for the proof, let us estimate the relevant matrix parameters of the random matrix S of (3.5).

Lemma 9.9. *We have*

$$\sigma(S) = \left\| \sum_{i=1}^n (\text{Tr}[\Sigma_i]\Sigma_i + \Sigma_i^2) \right\|^{\frac{1}{2}}, \quad v(S) \leq \sqrt{2} \left\| \sum_{i=1}^n \Sigma_i^2 \right\|^{\frac{1}{2}}.$$

Proof. The identity for $\sigma(S)$ follows readily using

$$\mathbf{E}[(S - \mathbf{E}S)^2] = \sum_{i=1}^n \mathbf{E}[(Y_i Y_i^* - \Sigma_i)^2] = \sum_{i=1}^n (\mathbf{E}[Y_i Y_i^* \|Y_i\|^2] - \Sigma_i^2)$$

and that $\mathbf{E}[Y_i Y_i^* \|Y_i\|^2] = \text{Tr}[\Sigma_i]\Sigma_i + 2\Sigma_i^2$ by the Wick formula (4.1).

To bound $v(S)$, we reason analogously. We first note that

$$\mathbf{E}[|\text{Tr}[M(S - \mathbf{E}S)]|^2] = \sum_{i=1}^n (\mathbf{E}[|\langle Y_i, M Y_i \rangle|^2] - |\text{Tr}[M \Sigma_i]|^2) \leq 2 \sum_{i=1}^n \text{Tr}[M \Sigma_i M^* \Sigma_i],$$

using $\mathbf{E}[|\langle Y_i, M Y_i \rangle|^2] \leq |\text{Tr}[M \Sigma_i]|^2 + 2 \text{Tr}[M \Sigma_i M^* \Sigma_i]$ by (4.1) and Cauchy-Schwarz. As $2 \text{Tr}[M \Sigma_i M^* \Sigma_i] \leq 2 \text{Tr}[M \Sigma_i^2 M^*]^{\frac{1}{2}} \text{Tr}[\Sigma_i M M^* \Sigma_i]^{\frac{1}{2}} \leq \text{Tr}[(M^* M + M M^*) \Sigma_i^2]$ by Cauchy-Schwarz and Young's inequality, we have

$$v(S)^2 = \sup_{\text{Tr}|M|^2 \leq 1} \mathbf{E}[|\text{Tr}[M(S - \mathbf{E}S)]|^2] \leq \sup_{\text{Tr}|M|^2 \leq 1} \text{Tr} \left[(M^* M + M M^*) \sum_{i=1}^n \Sigma_i^2 \right],$$

and the conclusion follows readily. \square

We must further estimate the parameter $R_q(S)$ in Theorem 2.9.

Lemma 9.10. *For $q \geq 1$, we have $R_q(S) \lesssim n^{\frac{1}{q}} \max_{i \leq n} \{\text{Tr} \Sigma_i + q \|\Sigma_i\|\}$.*

Proof. It follows directly from the definition of $R_q(S)$ that

$$R_q(S) \leq n^{\frac{1}{q}} \max_{i \leq n} \mathbf{E}[\|Z_i\|^q]^{\frac{1}{q}} \leq 2n^{\frac{1}{q}} \max_{i \leq n} \mathbf{E}[\|Y_i\|^{2q}]^{\frac{1}{q}}$$

where we used $\|Z_i\| = \|Y_i Y_i^* - \mathbf{E}Y_i Y_i^*\| \leq \|Y_i\|^2 + \mathbf{E}\|Y_i\|^2$. It remains to note that

$$\mathbf{E}[\|Y_i\|^{2q}]^{\frac{1}{2q}} \leq \mathbf{E}\|Y_i\| + \mathbf{E}[(\|Y_i\| - \mathbf{E}\|Y_i\|)^{2q}]^{\frac{1}{2q}} \lesssim (\text{Tr} \Sigma_i)^{\frac{1}{2}} + \|\Sigma_i\|^{\frac{1}{2}} \sqrt{q},$$

where we used that $\mathbf{E}\|Y_i\| \leq (\text{Tr} \Sigma_i)^{\frac{1}{2}}$ by Cauchy-Schwarz and that $\|Y_i\|$ is $\|\Sigma_i\|$ -subgaussian by Gaussian concentration [22, Theorems 5.6 and 2.1]. \square

We can now complete the proof of Theorem 3.21.

Proof of Theorem 3.21. Theorem 2.9 and [9, Theorem 2.7 and Lemma 2.5] yield

$$d^{-\frac{1}{2p}} \mathbf{E} \|S - \mathbf{E}S\| \leq \mathbf{E}[\text{tr}(S - \mathbf{E}S)^{2p}]^{\frac{1}{2p}} \leq 2\sigma(S) + Cv(S)^{\frac{1}{2}}\sigma(S)^{\frac{1}{2}}p^{\frac{3}{4}} + CR_{2p}(S)p^2$$

for a universal constant C . Now let $p = \lceil \frac{2}{\varepsilon} \log(d+n) \rceil$, so that $\max(d^{\frac{1}{2p}}, n^{\frac{1}{2p}}) \leq e^{\frac{\varepsilon}{4}}$. Moreover, $Cv(S)^{\frac{1}{2}}\sigma(S)^{\frac{1}{2}}p^{\frac{3}{4}} \leq (e^{\frac{\varepsilon}{4}} - 1)2\sigma(S) + \varepsilon^{-1}C^2v(S)p^{\frac{3}{2}}$ by Young's inequality and $e^x \geq 1 + x$. We therefore obtain for any $\varepsilon \in (0, 1]$

$$\mathbf{E} \|S - \mathbf{E}S\| \leq (1 + \varepsilon) 2\sigma(S) + \frac{K}{\varepsilon^3} \left(v(S) + \max_{i \leq n} \text{Tr} \Sigma_i \right) \log^3(d+n),$$

where K is a universal constant and we used Lemma 9.10 and $e^{\frac{\varepsilon}{2}} \leq 1 + \varepsilon$ for $\varepsilon \leq 1$. The conclusion follows readily using Lemma 9.9. \square

9.3.2. A simple lower bound. The aim of this short section is to show that the leading terms of the upper bounds of Theorems 3.20 and 3.21 are also lower bounds up to a universal constant. These results therefore capture the correct “user-friendly” quantity in the present setting. In general, it is not the case these these terms are optimal to leading order, that is up to a factor $1 + o(1)$; if such a sharp bound is desired, the proofs of Theorems 3.20 and 3.21 may be adapted to obtain bounds in terms of $\|Y_{\text{free}}Y_{\text{free}}^* - \mathbf{E}S \otimes \mathbf{1}\|$ and $\|S_{\text{free}} - \mathbf{E}S \otimes \mathbf{1}\|$, respectively.

Lemma 9.11. *In the setting of section 3.4.1, we have*

$$\mathbf{E} \|S - \mathbf{E}S\| \gtrsim \left\| \sum_{i=1}^n \text{Tr}[\Sigma_i] \Sigma_i \right\|^{\frac{1}{2}} + \max_{i \leq n} \text{Tr} \Sigma_i.$$

Proof. We begin by noting that

$$\mathbf{E} \|S - \mathbf{E}S\| \geq \sup_{\|v\|=1} \mathbf{E} \|(S - \mathbf{E}S)v\| \gtrsim \sup_{\|v\|=1} \mathbf{E} [\|(S - \mathbf{E}S)v\|^2]^{\frac{1}{2}},$$

where the last inequality follows by hypercontractivity [49, Theorem 3.50] using that $\|(S - \mathbf{E}S)v\|^2$ is a polynomial of degree 4 of the Gaussian variables Y_{ij} . The first part of the proof of Lemma 9.9 therefore yields

$$\mathbf{E} \|S - \mathbf{E}S\| \gtrsim \left\| \sum_{i=1}^n (\text{Tr}[\Sigma_i] \Sigma_i + \Sigma_i^2) \right\|^{\frac{1}{2}} \geq \left\| \sum_{i=1}^n \text{Tr}[\Sigma_i] \Sigma_i \right\|^{\frac{1}{2}} \geq \max_{i \leq n} \|\Sigma_i\|.$$

On the other hand, we can readily estimate by Jensen's inequality

$$\mathbf{E} \|S - \mathbf{E}S\| \geq \max_{i \leq n} \mathbf{E} \|Y_i Y_i^* - \Sigma_i\| \geq \max_{i \leq n} \text{Tr} \Sigma_i - \max_{i \leq n} \|\Sigma_i\|,$$

where we used that $S - \mathbf{E}S = \sum_{i=1}^n (Y_i Y_i^* - \Sigma_i)$ is a sum of independent centered random matrices. We can therefore estimate

$$\left\| \sum_{i=1}^n \text{Tr}[\Sigma_i] \Sigma_i \right\|^{\frac{1}{2}} + \max_{i \leq n} \text{Tr} \Sigma_i \leq \left\| \sum_{i=1}^n \text{Tr}[\Sigma_i] \Sigma_i \right\|^{\frac{1}{2}} + \max_{i \leq n} \|\Sigma_i\| + \mathbf{E} \|S - \mathbf{E}S\|,$$

and the proof is readily concluded. \square

9.3.3. *Proof of Theorem 3.24.* The proof of Theorem 3.24 combines our universality principles with a linearization argument as in Lemma 9.8.

Proof of Theorem 3.24. Given $B = \|\mathbf{E}YY^*\|\mathbf{1} - \mathbf{E}YY^*$, define

$$\check{Y}_\varepsilon := \begin{bmatrix} 0 & Y & (B + 4\varepsilon^2\mathbf{1})^{\frac{1}{2}} \\ Y^* & 0 & 0 \\ (B + 4\varepsilon^2\mathbf{1})^{\frac{1}{2}} & 0 & 0 \end{bmatrix},$$

and let \check{H}_ε be its Gaussian model. Then a completely analogous argument to the one used in the proof of Lemma 9.8 yields

$$\begin{aligned} d_H(\text{sp}(\check{Y}_\varepsilon), \text{sp}(\check{H}_\varepsilon)) \leq \varepsilon &\implies \\ \begin{cases} |\lambda_{\max}(YY^* + B + 4\varepsilon^2\mathbf{1})^{\frac{1}{2}} - \lambda_{\max}(HH^* + B + 4\varepsilon^2\mathbf{1})^{\frac{1}{2}}| \leq \varepsilon, \\ |\lambda_{\min}(YY^* + B + 4\varepsilon^2\mathbf{1})^{\frac{1}{2}} - \lambda_{\min}(HH^* + B + 4\varepsilon^2\mathbf{1})^{\frac{1}{2}}| \leq \varepsilon \end{cases} \end{aligned}$$

for any $\varepsilon \geq 0$. Using $|a^{\frac{1}{2}} - b^{\frac{1}{2}}|(a^{\frac{1}{2}} + b^{\frac{1}{2}}) = |a - b|$ for $a, b \geq 0$, we obtain

$$\begin{aligned} d_H(\text{sp}(\check{Y}_\varepsilon), \text{sp}(\check{H}_\varepsilon)) \leq \varepsilon &\implies \\ \|\|YY^* - \mathbf{E}YY^*\| - \|HH^* - \mathbf{E}HH^*\|\| \leq (\|Y\| + \|H\| + 2\|\mathbf{E}YY^*\|^{\frac{1}{2}} + 4\varepsilon)\varepsilon, \end{aligned}$$

where we used that $\|M\| - \|N\| \leq |\lambda_{\max}(M) - \lambda_{\max}(N)| \vee |\lambda_{\min}(M) - \lambda_{\min}(N)|$ and $\mathbf{E}HH^* = \mathbf{E}YY^*$. Furthermore, we have $\sigma_*(\check{Y}_\varepsilon) = \sigma_*(Y)$, $\sigma(\check{Y}_\varepsilon) = \sigma(Y)$, and $R(\check{Y}_\varepsilon) = R(Y)$ by [9, Remark 2.6]. Thus Theorem 2.6 yields

$$\begin{aligned} \mathbf{P}[\|\|YY^* - \mathbf{E}YY^*\| - \|HH^* - \mathbf{E}HH^*\|\| > \\ C(\|Y\| + \|H\| + \|\mathbf{E}YY^*\|^{\frac{1}{2}} + \varepsilon(t))\varepsilon(t)] \leq (2d + m)e^{-t} \end{aligned}$$

for all $t > 0$, where C is a universal constant and $\varepsilon(t)$ is as in Theorem 2.6.

To proceed, note that

$$\mathbf{P}[\|H\| > \mathbf{E}\|H\| + C\varepsilon(t)] \leq e^{-t}$$

by Gaussian concentration as in [9, Corollary 4.14], while

$$\mathbf{P}[\|Y\| > \mathbf{E}\|H\| + C\varepsilon(t)] \leq (d + m)e^{-t}$$

by Corollary 2.7 and Remark 2.1. Combining the above bounds yields

$$\mathbf{P}[\|\|YY^* - \mathbf{E}YY^*\| - \|HH^* - \mathbf{E}HH^*\|\| > C\varepsilon(t)\mathbf{E}\|H\| + C\varepsilon(t)^2] \leq C(d + m)e^{-t}$$

for a universal constant C , where we used that

$$\|\mathbf{E}YY^*\| = \|\mathbf{E}HH^*\| = \sup_{\|v\|=1} \mathbf{E}\|H^*v\|^2 \lesssim \sup_{\|v\|=1} (\mathbf{E}\|H^*v\|)^2 \leq (\mathbf{E}\|H\|)^2$$

by hypercontractivity [49, Theorem 3.50]. The conclusion follows by integrating this tail bound as in the proof of Theorem 2.6. \square

9.3.4. *Proof of Theorem 3.27.* Throughout this section we adopt the setting and notation of Theorem 3.27. Its proof combines two distinct universality principles. Let us begin by applying universality to Y .

Proposition 9.12. *We have*

$$\begin{aligned} \mathbf{E}\|S - \mathbf{E}S\| &\leq 2\|B\|_{\text{HS}}\|B\|\sqrt{n} + \|B\|_{\text{HS}}^2 \\ &\quad + C\{\alpha^{\frac{1}{3}}\|B\|^{\frac{1}{3}}(\|B\|\sqrt{n} + \|B\|_{\text{HS}})^{\frac{5}{3}} + \alpha^2\|B\|^2\} \log^2(d + n). \end{aligned}$$

Proof. We will write Y in the form (2.1) as

$$Y = \sum_{i=1}^N \sum_{j=1}^n Z_{ij}, \quad Z_{ij} = A_{ij} B e_i e_j^*.$$

We readily compute

$$\mathbf{E}[YY^*] = n BB^*, \quad \mathbf{E}[Y^*Y] = \|B\|_{\text{HS}}^2 \mathbf{1}, \quad v(Y) = \|B\|, \quad R(Y) \leq \alpha \|B\|$$

(here we used that Y has independent columns Y_1, \dots, Y_n with $\text{Cov}(Y_i) = BB^*$, so that $\|\text{Cov}(Y)\| = \max_i \|\text{Cov}(Y_i)\| = \|B\|^2$). Applying Theorem 3.24 yields

$$|\mathbf{E}\|S - \mathbf{E}S\| - \mathbf{E}\|HH^* - \mathbf{E}HH^*\|\| \lesssim \delta (\|B\|\sqrt{n} + \|B\|_{\text{HS}}) + \delta^2,$$

where

$$\delta \lesssim \alpha^{\frac{1}{3}} \|B\|^{\frac{1}{3}} (\|B\|\sqrt{n} + \|B\|_{\text{HS}})^{\frac{2}{3}} \log^{\frac{2}{3}}(d+n) + \alpha \|B\| \log(d+n)$$

and we used that $\mathbf{E}\|H\| \lesssim \|B\|\sqrt{n} + \|B\|_{\text{HS}}$ (see, e.g., [80, Lemma 5.4]) and $\alpha \geq 1$. On the other hand, $\mathbf{E}\|HH^* - \mathbf{E}HH^*\|$ can be estimated by Theorem 3.20 with $\Sigma_i = BB^*$. Combining all the above bounds yields the conclusion. \square

We now apply universality to S . In preparation for the following computations, we begin by estimating $\sigma(S)$ and $v(S)$. Recall that Y_i denotes the i th column of Y .

Lemma 9.13. *We have*

$$\sigma(S) \leq (\|B\|_{\text{HS}}\|B\| + 2\alpha\|B\|^2)\sqrt{n}, \quad v(S) \leq 4\alpha\|B\|^2\sqrt{n}.$$

Proof. By Lemma 4.1, if W_1, \dots, W_m are independent centered random variables with unit variance and g_1, \dots, g_m are independent standard Gaussians, then

$$\mathbf{E}[W_i W_j W_k W_l] = \mathbf{E}[g_i g_j g_k g_l] + (\mathbf{E}[W_i^4] - 3)1_{i=j=k=l}.$$

We will apply this identity in the case that W_i are entries of the random matrix A . In particular, arguing as in the first part of the proof of Lemma 9.9, we obtain

$$\mathbf{E}[(S - \mathbf{E}S)^2] = n\|B\|_{\text{HS}}^2 BB^* + n(BB^*)^2 + \sum_{i=1}^N \sum_{j=1}^n (\mathbf{E}[A_{ij}^4] - 3)(B^*B)_{ii} B e_i e_i^* B^*.$$

As $\mathbf{E}[A_{ij}^4] \leq \alpha^2$, we readily obtain

$$\sigma(S)^2 \leq n\|B\|_{\text{HS}}^2\|B\|^2 + (1 + \alpha^2)n\|B\|^4,$$

and the bound on $\sigma(S)$ follows using $\alpha \geq 1$.

The parameter $v(S)$ can be estimated analogously, but an adequate bound also follows from a standard concentration argument. Indeed, note that

$$v(S)^2 = \sup_{\text{Tr}|M|^2=1} \text{Var}(\text{Tr} MS) = \sup_{\text{Tr}|M|^2=1} \sum_{i=1}^n \text{Var}(\langle Y_i, M Y_i \rangle).$$

By the convex Poincaré inequality [22, Theorem 3.17] and Cauchy-Schwarz, we obtain $\text{Var}(\langle Y_i, M Y_i \rangle) \leq 16\alpha^2\|B\|^4$ for $\text{Tr}|M|^2 = 1$, concluding the proof. \square

Next, we estimate the parameter $R_q(S)$ in Theorem 2.9.

Lemma 9.14. *For $q \geq 1$, we have $R_q(S) \lesssim n^{\frac{1}{q}} \{\|B\|_{\text{HS}}^2 + \alpha^2 q\|B\|^2\}$.*

Proof. The convex concentration inequality [22, Theorems 6.10 and 2.1] yields that $\mathbf{E}[\|Y_i\|^{2q}]^{\frac{1}{2q}} \leq \|B\|_{\text{HS}} + C\alpha\sqrt{q}\|B\|$, where we used $\mathbf{E}\|Y_i\| \leq \mathbf{E}[\|Y_i\|^2]^{\frac{1}{2}} = \|B\|_{\text{HS}}$. The conclusion follows directly as in the proof of Lemma 9.10. \square

We can now proceed as in the proof of Theorem 3.21.

Proposition 9.15. *We have for $\varepsilon \in (0, 1]$*

$$\mathbf{E}\|S - \mathbf{E}S\| \leq (1 + \varepsilon) 2\|B\|_{\text{HS}}\|B\|\sqrt{n} + \frac{C}{\varepsilon^3} (\|B\|_{\text{HS}}^2 + (\alpha\sqrt{n} + \alpha^2)\|B\|^2) \log^3(d + n).$$

Proof. Apply Lemmas 9.13 and 9.14 precisely as in the proof of Theorem 3.21. \square

We now complete the proof of Theorem 3.27.

Proof of Theorem 3.27. It is convenient to define $\gamma = \frac{\|B\|_{\text{HS}}}{\|B\|\sqrt{n}}$ and $\delta = \frac{\alpha}{\sqrt{n}}$. In terms of these dimensionless parameters, Proposition 9.12 can be expressed as

$$\frac{\mathbf{E}\|S - \mathbf{E}S\|}{n\|B\|^2} \leq 2\gamma + \gamma^2 + C\{\delta^{\frac{1}{3}}(1 + \gamma)^{\frac{5}{3}} + \delta^2\} \log^2(d + n)$$

while Proposition 9.15 yields

$$\frac{\mathbf{E}\|S - \mathbf{E}S\|}{n\|B\|^2} \leq 2\gamma + C\{(\gamma^2 + \delta + \delta^2)^{\frac{1}{4}}\gamma^{\frac{3}{4}} + \gamma^2 + \delta + \delta^2\} \log^3(d + n),$$

where in the last equation we used $\inf_{\varepsilon \leq 1} \{2\varepsilon\gamma + \frac{K}{\varepsilon^3}\} \leq 3K^{\frac{1}{4}}\gamma^{\frac{3}{4}} + 3K$.

Now note that the assumptions of the theorem imply $\delta \leq 1$ and $\gamma \geq \delta$. Using $\delta^2 \leq \delta^{\frac{1}{3}}(1 + \gamma)^{\frac{5}{3}}$, $\frac{\delta^{\frac{1}{3}}(1 + \gamma)^{\frac{5}{3}}}{2\gamma + \gamma^2} \lesssim \frac{\delta^{\frac{1}{3}}}{\gamma} + (\frac{\delta}{\gamma})^{\frac{1}{3}}$ and $\frac{\delta}{\gamma} \leq 1$, we can rearrange and combine the above inequalities to estimate

$$\frac{\mathbf{E}\|S - \mathbf{E}S\|}{n\|B\|^2} \leq \left(1 + C\left\{\min\left(\frac{\delta^{\frac{1}{3}}}{\gamma}, \gamma^{\frac{1}{4}} + \gamma\right) + \frac{\delta^{\frac{1}{4}}}{\gamma^{\frac{1}{4}}}\right\} \log^3(d + n)\right) (2\gamma + \gamma^2).$$

We conclude with $\min(\frac{a}{\gamma}, \gamma^{\frac{1}{4}} + \gamma) \leq \min(\frac{a}{\gamma}, \gamma^{\frac{1}{4}}) + \min(\frac{a}{\gamma}, \gamma) \leq a^{\frac{1}{5}} + a^{\frac{1}{2}}$ and $\delta < 1$. \square

Remark 9.16 (Unbounded entries). The formulation of Theorem 3.27 for bounded A_{ij} is not a fundamental restriction of our approach: results for unbounded entries can be obtained analogously by using our universality principles for unbounded random matrices. We have restricted to the bounded case largely for simplicity and brevity of exposition. However, in order to illustrate some features of the unbounded case, let us briefly discuss these here in the context of the slightly simpler problem of estimating $\|Y\|$ (as opposed to $\|YY^* - \mathbf{E}YY^*\|$).

Let $Y = BA$ with A, B as in Theorem 3.27, except that we now assume only that $\|A_{ij}\|_s \leq \alpha$ for some $4 < s < \infty$. We write Y in the form (2.1) as in the proof of Proposition 9.12. Applying Theorem 2.8 as in the proof of Corollary 2.17 yields

$$\mathbf{E}\|Y\| \leq \|\mathbf{E}YY^*\|^{\frac{1}{2}} + \|\mathbf{E}Y^*Y\|^{\frac{1}{2}} + C\{v(Y)^{\frac{1}{2}}\sigma(Y)^{\frac{1}{2}} + \bar{R}(Y)^{\frac{1}{6}}\sigma(Y)^{\frac{5}{6}}\} \log(d + n)$$

provided that $\bar{R}(Y) \log^3(d+n) \leq \sigma(Y)$. All parameters in this bound were already computed in the proof of Proposition 9.12 except $\bar{R}(Y)$, which we estimate as

$$\begin{aligned} \bar{R}(Y) &= \mathbf{E} \left[\max_{i \leq N} \max_{j \leq n} A_{ij}^2 \|Be_i\|^2 \right]^{\frac{1}{2}} \leq \mathbf{E} \left[\sum_{i=1}^N \sum_{j=1}^n |A_{ij}|^s \|Be_i\|^s \right]^{\frac{1}{s}} \\ &\leq \alpha n^{\frac{1}{s}} \left(\sum_{i=1}^N \|Be_i\|^s \right)^{\frac{1}{s}} \leq \alpha n^{\frac{1}{s}} \|B\|^{1-\frac{2}{s}} \|B\|_{\text{HS}}^{\frac{2}{s}}. \end{aligned}$$

Combining the above estimates, we obtain the bound

$$\mathbf{E}\|Y\| \leq \left(1 + \frac{C \log(d+n)}{(n \vee r)^{\frac{1}{4}}} + \frac{C \alpha^{\frac{1}{6}} \log(d+n)}{(n \vee r)^{\frac{1}{12} - \frac{1}{3s}}} \right) (\|B\| \sqrt{n} + \|B\|_{\text{HS}})$$

for $\alpha \log^3(d+n) \leq (n \vee r)^{\frac{1}{2} - \frac{2}{s}}$, where $r = \|B\|_{\text{HS}}^2 \|B\|^{-2}$ is the effective rank of B and we used that $\|B\| \sqrt{n} + \|B\|_{\text{HS}} \geq (\|B\| \sqrt{n})^{1-t} \|B\|_{\text{HS}}^t$ for any $t \in [0, 1]$.

This result should be compared to the best previous bound in this setting due to Vershynin [82], which states that $\mathbf{E}\|Y\| \leq C(s)\alpha(\|B\| \sqrt{n} + \|B\|_{\text{HS}})$ where $C(s) < \infty$ for $s > 4$. In contrast, our bound yields $\mathbf{E}\|Y\| \leq (1 + o(1))(\|B\| \sqrt{n} + \|B\|_{\text{HS}})$ as soon as $n \vee r \gg (\alpha^{\frac{1}{6}} \log(d+n))^{\beta(s)}$, which not only yields the best possible constant for a bound of this kind (in view of the Bai-Yin law) but also allows α to diverge without affecting the estimate to leading order. We emphasize a key feature of both bounds that was highlighted in [82]: they do not depend on the inner dimension N , despite that $\bar{R}(Y)$ is defined as a maximum over nN random variables.

9.4. Strong asymptotic freeness. The main aim of this section is to prove Theorem 3.29. In section 9.4.1, we first develop the special case of bounded random matrices by means of a linearization argument. The result is then extended to the general setting in section 9.4.2 by employing a truncation argument as in section 8. Finally, Corollary 3.32 will be proved in section 9.4.3.

9.4.1. Linearization. The aim of this section is to prove the following special case of Theorem 3.29 for bounded random matrices. The general case will be deduced from this result in the next section by a truncation argument.

Theorem 9.17. *Let s_1, \dots, s_m be a free semicircular family, and let H_1^N, \dots, H_m^N be independent self-adjoint random matrices as in Theorem 3.29. Suppose*

$$\lim_{N \rightarrow \infty} \|\mathbf{E}[H_k^N]\| = \lim_{N \rightarrow \infty} \|\mathbf{E}[(H_k^N)^2] - 1\| = 0$$

and

$$\lim_{N \rightarrow \infty} (\log d_N)^{\frac{3}{2}} v(H_k^N) = \lim_{N \rightarrow \infty} (\log d_N)^2 R(H_k^N) = 0$$

for every $1 \leq k \leq m$. Then

$$\begin{aligned} \lim_{N \rightarrow \infty} \text{tr } p(H_1^N, \dots, H_m^N) &= \tau(p(s_1, \dots, s_m)) \quad a.s., \\ \lim_{N \rightarrow \infty} \|p(H_1^N, \dots, H_m^N)\| &= \|p(s_1, \dots, s_m)\| \quad a.s. \end{aligned}$$

for every noncommutative polynomial p .

The difficulty here is that we are interested in general noncommutative polynomials of random matrices, while our universality principles apply only to the linear situation of (2.1). To reduce the former to the latter, we will use classical linearization arguments that we presently recall.

Proposition 9.18 (Linearization). *Let H_1^N, \dots, H_m^N be self-adjoint random matrices and let s_1, \dots, s_m be a free semicircular family.*

a. *Suppose that for every $d' \in \mathbb{N}$ and $A_0, \dots, A_m \in M_{d'}(\mathbb{C})_{sa}$*

$$\text{sp}(A_0 \otimes \mathbf{1} + \sum_{k=1}^m A_k \otimes H_k^N) \subseteq \text{sp}(A_0 \otimes \mathbf{1} + \sum_{k=1}^m A_k \otimes s_k) + [-\varepsilon, \varepsilon]$$

eventually as $N \rightarrow \infty$ a.s. for all $\varepsilon > 0$. Then

$$\limsup_{N \rightarrow \infty} \|p(H_1^N, \dots, H_m^N)\| \leq \|p(s_1, \dots, s_m)\| \quad \text{a.s.}$$

for every noncommutative polynomial p .

b. *Suppose that for every $d' \in \mathbb{N}$ and $A_0, \dots, A_m \in M_{d'}(\mathbb{C})_{sa}$*

$$\lim_{N \rightarrow \infty} \text{tr} \left[(A_0 \otimes \mathbf{1} + \sum_{k=1}^m A_k \otimes H_k^N)^{2r} \right] = (\text{tr} \otimes \tau) \left[(A_0 \otimes \mathbf{1} + \sum_{k=1}^m A_k \otimes s_k)^{2r} \right]$$

a.s. for all $r \in \mathbb{N}$. Then

$$\lim_{N \rightarrow \infty} \text{tr} p(H_1^N, \dots, H_m^N) = \tau(p(s_1, \dots, s_m)) \quad \text{a.s.}$$

for every noncommutative polynomial p .

Proof. The first part is proved in [47, Lemma 1 and pp. 758–760]. The second part follows directly from the proof of [38, Lemma 1.1]. \square

To apply the linearization argument in the present setting, we use the following.

Lemma 9.19. *Let H_1^N, \dots, H_m^N be random matrices as in Theorem 9.17, and fix $d' \in \mathbb{N}$ and $A_0, \dots, A_m \in M_{d'}(\mathbb{C})_{sa}$. Define the random matrix*

$$\Xi^N = A_0 \otimes \mathbf{1} + \sum_{k=1}^m A_k \otimes H_k^N,$$

and let Ξ_{free}^N be the associated noncommutative model. Then

$$\text{sp}(\Xi^N) \subseteq \text{sp}(\Xi_{\text{free}}^N) + [-\varepsilon, \varepsilon]$$

eventually as $N \rightarrow \infty$ a.s. for every $\varepsilon > 0$, and for every $r \in \mathbb{N}$

$$\lim_{N \rightarrow \infty} \left| \text{tr}[(\Xi^N)^{2r}]^{\frac{1}{2r}} - (\text{tr} \otimes \tau)[(\Xi_{\text{free}}^N)^{2r}]^{\frac{1}{2r}} \right| = 0 \quad \text{a.s.}$$

Proof. It follows as in the proof of [9, Lemma 7.8] that $\sigma(\Xi^N) = O(1)$ and $\sigma_*(\Xi^N) \leq v(\Xi^N) = o((\log d_N)^{-\frac{3}{2}})$. Moreover, it is clear from the definition of Ξ^N that

$$R(\Xi^N) = \max_{k \leq m} \|A_k\| R(H_k^N) = o((\log d_N)^{-2}).$$

Applying Theorem 2.16 with $t = 3 \log d_N$ yields

$$\mathbf{P} \left[\text{sp}(\Xi^N) \subseteq \text{sp}(\Xi_{\text{free}}^N) + o(1)[-1, 1] \right] \geq 1 - \frac{2d'}{d_N^2} \geq 1 - \frac{2d'}{N^2}.$$

The first conclusion follows by the Borel-Cantelli lemma.

On the other hand, Theorem 2.9 and [9, Theorem 2.7] yield for all $r \in \mathbb{N}$

$$\lim_{N \rightarrow \infty} \left| \mathbf{E}[\text{tr}(\Xi^N)^{2r}]^{\frac{1}{2r}} - (\text{tr} \otimes \tau)[(\Xi_{\text{free}}^N)^{2r}]^{\frac{1}{2r}} \right| = 0.$$

In particular, $\mathbf{E}[\text{tr}(\Xi^N)^{2r}]^{\frac{1}{2r}} = O(1)$ as $(\text{tr} \otimes \tau)[(\Xi_{\text{free}}^N)^{2r}]^{\frac{1}{2r}} \leq \|\Xi_{\text{free}}^N\| \leq 2\sigma(\Xi^N)$. To conclude, we need to show that $\text{tr}[(\Xi^N)^{2r}]^{\frac{1}{2r}}$ concentrates around $\mathbf{E}[\text{tr}(\Xi^N)^{2r}]^{\frac{1}{2r}}$ a.s. To this end, we apply Lemma 9.20 below with $t = 2 \log d_N$ to estimate

$$\mathbf{P}\left[|\text{tr}[(\Xi^N)^{2r}]^{\frac{1}{2r}} - \mathbf{E}[\text{tr}(\Xi^N)^{2r}]^{\frac{1}{2r}}| \geq o(1)\right] \leq \frac{1}{d_N^2} \leq \frac{1}{N^2},$$

and the conclusion follows by Borel-Cantelli. \square

Above we used the following concentration inequality.

Lemma 9.20. *For any random matrix as in (2.1), we have*

$$\mathbf{P}\left[|(\text{tr } X^{2r})^{\frac{1}{2r}} - \mathbf{E}[\text{tr } X^{2r}]^{\frac{1}{2r}}| \geq C(\sigma_*(X) + R(X)^{\frac{1}{2}} \mathbf{E}[\text{tr } X^{2r}]^{\frac{1}{4r}}) \sqrt{t} + CR(X)t\right] \leq 2e^{-t}$$

for all $t \geq r$.

Proof. We begin by writing $(\text{tr } X^{2r})^{\frac{1}{2r}} = \sup_{f \in \mathcal{F}} |\sum_{i=0}^n f(Z_i)|$ where

$$\mathcal{F} = \{Z \mapsto x \text{Re } \text{tr}[MZ] + y \text{Im } \text{tr}[MZ] : x^2 + y^2 \leq 1, \|M\|_{\frac{2r}{2r-1}} \leq 1\}.$$

Then

$$\sup_{f \in \mathcal{F}} \sum_{i=0}^n \text{Var}(f(Z_i)) \leq \sup_{\|M\|_1 \leq 1} \sum_{i=1}^n \mathbf{E}|\text{tr } MZ_i|^2 = \sigma_*(X)^2$$

as $\|M\|_1 \leq \|M\|_{\frac{2r}{2r-1}}$ and as the extreme points of S_1^d are rank one matrices, and

$$\sup_{f \in \mathcal{F}} \max_{0 \leq i \leq n} \|f(Z_i) - f(Z'_i)\|_\infty \leq 2R(X)$$

where Z'_i is an independent copy of Z_i . We now apply⁵ [57, Theorem 3] to estimate

$$\begin{aligned} \mathbf{P}\left[|(\text{tr } X^{2r})^{\frac{1}{2r}} - \mathbf{E}[(\text{tr } X^{2r})^{\frac{1}{2r}}]| \geq C(\sigma_*(X) + R(X)^{\frac{1}{2}} \mathbf{E}[(\text{tr } X^{2r})^{\frac{1}{2r}}]^{\frac{1}{2}}) \sqrt{t} + CR(X)t\right] \leq 2e^{-t} \end{aligned}$$

for all $t \geq 0$. Consequently

$$|\mathbf{E}[\text{tr } X^{2r}]^{\frac{1}{2r}} - \mathbf{E}[(\text{tr } X^{2r})^{\frac{1}{2r}}]| \lesssim (\sigma_*(X) + R(X)^{\frac{1}{2}} \mathbf{E}[(\text{tr } X^{2r})^{\frac{1}{2r}}]^{\frac{1}{2}}) \sqrt{r} + R(X)r$$

by [22, Theorem 2.3], and we conclude by combining the above inequalities. \square

We can now conclude the proof of Theorem 9.17.

Proof of Theorem 9.17. Let Ξ^N and Ξ_{free}^N be as in Lemma 9.19. It follows from the proofs of [9, Lemmas 7.9 and 7.10] that

$$\text{sp}(\Xi_{\text{free}}^N) \subseteq \text{sp}(A_0 \otimes \mathbf{1} + \sum_{k=1}^m A_k \otimes s_k) + [-\varepsilon, \varepsilon]$$

eventually as $N \rightarrow \infty$ for every $\varepsilon > 0$, and that

$$\lim_{N \rightarrow \infty} (\text{tr} \otimes \tau)[(\Xi_{\text{free}}^N)^{2r}] = (\text{tr} \otimes \tau)[(A_0 \otimes \mathbf{1} + \sum_{k=1}^m A_k \otimes s_k)^{2r}]$$

for all $r \in \mathbb{N}$. Thus Lemma 9.19 and Proposition 9.18 yield

$$\begin{aligned} \lim_{N \rightarrow \infty} \text{tr } p(H_1^N, \dots, H_m^N) &= \tau(p(s_1, \dots, s_m)) \quad \text{a.s.}, \\ \limsup_{N \rightarrow \infty} \|p(H_1^N, \dots, H_m^N)\| &\leq \|p(s_1, \dots, s_m)\| \quad \text{a.s.} \end{aligned}$$

⁵While the statement of [57, Theorem 3] assumes that $\|f\|_\infty \leq b$ for all $f \in \mathcal{F}$, only the weaker assumption $\|f(\xi_i) - f(\xi'_i)\|_\infty \leq 2b$ is used in the proof. We also optimized the conclusion over ε .

for every noncommutative polynomial p . To conclude, note that

$$\begin{aligned}\liminf_{N \rightarrow \infty} \|p(H_1^N, \dots, H_m^N)\| &\geq \liminf_{N \rightarrow \infty} (\text{tr} |p(H_1^N, \dots, H_m^N)|^{2r})^{\frac{1}{2r}} \\ &= \tau(|p(s_1, \dots, s_m)|^{2r})^{\frac{1}{2r}} \quad \text{a.s.}\end{aligned}$$

for any $r \in \mathbb{N}$, where we used that $|p|^{2r}$ is also a polynomial. As

$$\lim_{r \rightarrow \infty} \tau(|p(s_1, \dots, s_m)|^{2r})^{\frac{1}{2r}} = \|p(s_1, \dots, s_m)\|$$

(here we use that τ is faithful), the conclusion follows. \square

9.4.2. Proof of Theorem 3.29. To prove Theorem 3.29 in the general setting, we will combine Theorem 9.17 with the truncation arguments of section 8. Before we proceed to the proof, we state an elementary lemma that will be needed below.

Lemma 9.21. *Let $(Y_n)_{n \geq 1}$ be a sequence of real-valued random variables such that $|Y_n| \rightarrow 0$ a.s. as $n \rightarrow \infty$. Then there is a nonrandom sequence $(a_n)_{n \geq 1}$ with $a_n \rightarrow 0$ as $n \rightarrow \infty$, such that $|Y_n| \leq a_n$ eventually as $n \rightarrow \infty$ a.s.*

Proof. Let $Y_n^* := \sup_{m \geq n} |Y_m|$, and let $n_k := \inf\{n : \mathbf{P}[Y_n^* > 2^{-k}] \leq 2^{-k}\}$. Then clearly n_k is nondecreasing, and $n_k < \infty$ as we assumed $|Y_n| \rightarrow 0$ a.s. Moreover, we may assume without loss of generality that $n_k \rightarrow \infty$, as otherwise $Y_n^* = 0$ a.s. for some n and the conclusion is trivial. We may therefore define $(a_n)_{n \geq 1}$ by setting $a_n = 2^{-k}$ for $n_k \leq n < n_{k+1}$, $k \geq 0$. As by construction

$$\mathbf{P}[|Y_n| > a_n \text{ for some } n_k \leq n < n_{k+1}] \leq \mathbf{P}[Y_{n_k}^* > 2^{-k}] \leq 2^{-k},$$

the conclusion follows by the Borel-Cantelli lemma. \square

We can now complete the proof of Theorem 3.29.

Proof of Theorem 3.29. We first note that it suffices to prove the a.s. version of the theorem, as the in probability version follows immediately from the a.s. version using the classical fact that a sequence of random variables converges in probability if and only if every subsequence has an a.s. convergent subsequence.

We therefore assume from now on that the assumptions of the theorem hold in the a.s. sense. By Lemma 9.21, the assumptions imply that there exists a nonrandom sequence (a_N) with $a_N \rightarrow 0$ as $N \rightarrow \infty$ such that

$$\max_{1 \leq k \leq m} \max_{1 \leq i \leq M_N} \|Z_{ki}^N\| \leq (\log d_N)^{-2} a_N$$

eventually as $N \rightarrow \infty$ a.s. Now define the truncated random matrices

$$\tilde{H}_k^N := Z_{k0}^N + \sum_{i=1}^{M_N} \mathbf{1}_{\|Z_{ki}^N\| \leq (\log d_N)^{-2} a_N} Z_{ki}^N$$

as in section 8. Then $\tilde{H}_k^N = H_k^N$ eventually as $N \rightarrow \infty$ a.s. for all k . To complete the proof, it therefore suffices to show that $\tilde{H}_1^N, \dots, \tilde{H}_m^N$ satisfy the assumptions of Theorem 9.17. To this end, note first that by Lemma 8.6

$$(\log d_N)^2 R(\tilde{H}_k^N) \leq 2a_N \xrightarrow{N \rightarrow \infty} 0.$$

Using $\mathbf{E}[|1_A Y - \mathbf{E}[1_A Y]|^2] \leq \mathbf{E}[|Y|^2]$ as in the proof of Lemma 8.6, we also have

$$(\log d_N)^{\frac{3}{2}} v(\tilde{H}_k^N) \leq (\log d_N)^{\frac{3}{2}} v(H_k^N) \xrightarrow{N \rightarrow \infty} 0.$$

It remains to estimate $\mathbf{E}[\tilde{H}_k^N]$ and $\mathbf{E}[(\tilde{H}_k^N)^2]$.

To bound $\mathbf{E}[\tilde{H}_k^N]$, note that it was shown in the proof of Lemma 8.4 that

$$\|\mathbf{E}[\tilde{H}_k^N] - \mathbf{E}[H_k^N]\| \leq \frac{\sigma_*(H_k^N)}{\mathbf{P}[\max_j \|Z_{kj}^N\| \leq (\log d_N)^{-2}a_N]^{\frac{1}{2}}}.$$

But as $\max_j \|Z_{kj}^N\| \leq (\log d_N)^{-2}a_N$ eventually a.s., the denominator on the right-hand side converges to one and the numerator satisfies $\sigma_*(H_k^N) \leq v(H_k^N) \rightarrow 0$. As by assumption $\|\mathbf{E}[H_k^N]\| \rightarrow 0$, we conclude that $\|\mathbf{E}[\tilde{H}_k^N]\| \rightarrow 0$ as well.

To bound $\mathbf{E}[(\tilde{H}_k^N)^2]$, note that setting $M = 1$ in the proof of Lemma 8.5 yields

$$\begin{aligned} & \|\mathbf{E}[(\tilde{H}_k^N - \mathbf{E}\tilde{H}_k^N)^2] - \mathbf{E}[(H_k^N - \mathbf{E}H_k^N)^2]\| \\ & \leq 2\mathbf{P}[\max_j \|Z_{kj}^N\| > (\log d_N)^{-2}a_N] \sigma(H_k^N)^2 + 4\bar{R}(H_k^N)\sigma(H_k^N). \end{aligned}$$

The right-hand side converges to zero as $\max_j \|Z_{kj}^N\| \leq (\log d_N)^{-2}a_N$ eventually a.s. and as $\bar{R}(H_k^N) \rightarrow 0$ and $\sigma(H_k^N) = O(1)$ by assumption. As $\|\mathbf{E}[\tilde{H}_k^N]\| \rightarrow 0$, $\|\mathbf{E}[H_k^N]\| \rightarrow 0$, and $\|\mathbf{E}[(H_k^N)^2] - \mathbf{1}\| \rightarrow 0$, we conclude that $\|\mathbf{E}[(\tilde{H}_k^N)^2] - \mathbf{1}\| \rightarrow 0$. \square

9.4.3. Proof of Corollary 3.32. Before we proceed to the proof of Corollary 3.32, we first state another elementary probabilistic lemma.

Lemma 9.22. *Let $(Y_n)_{n \geq 1}$ be a sequence of i.i.d. random variables with $\mathbf{E}[|Y_n|^p] < \infty$ for some $p > 0$. Then $\lim_{n \rightarrow \infty} n^{-\frac{1}{p}} \max_{m \leq n} |Y_m| = 0$ a.s.*

Proof. By the union bound and as $\sum_{k \geq 0} 2^k 1_{2^k \leq x} \leq 2x$, we can estimate

$$\sum_{k \geq 0} \mathbf{P}\left[2^{-\frac{k}{p}} \max_{m \leq 2^k} |Y_m| \geq \varepsilon\right] \leq \sum_{k \geq 0} 2^k \mathbf{P}\left[|Y_1|^p \geq 2^k \varepsilon^p\right] \leq \frac{2\mathbf{E}[|Y_1|^p]}{\varepsilon^p} < \infty$$

for any $\varepsilon > 0$. Thus

$$\lim_{k \rightarrow \infty} \max_{2^{k-1} \leq n < 2^k} n^{-\frac{1}{p}} \max_{m \leq n} |Y_m| \leq 2^{\frac{1}{p}} \lim_{k \rightarrow \infty} 2^{-\frac{k}{p}} \max_{m \leq 2^k} |Y_m| = 0 \quad \text{a.s.}$$

by the Borel-Cantelli lemma. \square

We can now complete the proof of Corollary 3.32.

Proof of Corollary 3.32. We prove both parts separately.

Part a. It suffices to verify that the assumptions of Theorem 3.29 are satisfied. Let $G_N = ([d_N], E_N)$ be k_N -regular, and write

$$H_k^N = \sum_{i < j: \{i, j\} \in E_N} \frac{\eta_{kij}}{\sqrt{k_N}} (e_i e_j^* + e_j e_i^*).$$

Then $\mathbf{E}[H_k^N] = 0$ and $\mathbf{E}[(H_k^N)^2] = \mathbf{1}$ by construction. Furthermore, we have

$$\lim_{N \rightarrow \infty} (\log d_N)^{\frac{3}{2}} v(H_k^N) = \sqrt{2} \lim_{N \rightarrow \infty} (\log d_N)^{\frac{3}{2}} k_N^{-\frac{1}{2}} = 0$$

by the assumption of part a. On the other hand, note that

$$\mathbf{E}\left[\max_{1 \leq i \leq M_N} \|Z_{ki}^N\|^2\right] \leq \frac{1}{k_N} \mathbf{E}\left[\max_{i < j: \{i, j\} \in E_N} |\eta_{kij}|^p\right]^{\frac{2}{p}} \leq \frac{(k_N d_N)^{\frac{2}{p}}}{k_N} \mathbf{E}[|\eta_{kij}|^p]^{\frac{2}{p}}.$$

As the assumption of part a. implies $(k_N d_N)^{\frac{2}{p}} k_N^{-1} \ll (\log d_N)^{-4}$, we have shown that $(\log d_N)^2 \bar{R}(H_k^N) \rightarrow 0$ as $N \rightarrow \infty$. This simultaneously verifies both remaining assumptions of the in probability version of Theorem 3.29.

If in addition E_N is increasing, we can use Lemma 9.22 to obtain

$$\limsup_{N \rightarrow \infty} (\log d_N)^2 \max_{1 \leq i \leq M_N} \|Z_{ki}^N\| \lesssim \lim_{N \rightarrow \infty} (k_N d_N)^{-\frac{1}{p}} \max_{i < j: \{i,j\} \in E_N} |\eta_{kij}| = 0 \quad \text{a.s.},$$

where we used that $(\log d_N)^2 k_N^{-\frac{1}{2}} \lesssim (k_N d_N)^{-\frac{1}{p}}$ by the assumption of part a. The remaining conclusion of part a. then follows from the a.s. version of Theorem 3.29.

Part b. Fix any $p > 2$. Then we may choose a distribution of the entries η_{kij} such that $\mathbf{E}[\eta_{kij}] = 0$, $\text{Var}(\eta_{kij}) = 1$, and $\mathbf{P}[|\eta_{kij}| > x] = (x \log x)^{-p}$ for all $x \geq x_0$ (here $x_0 > 0$ is a sufficiently large constant). As $\mathbf{E}[|\eta_{kij}|^p] < \infty$, the assumptions of Corollary 3.32 are satisfied. Now note that as $\|M\| \geq \max_{i,j} |M_{ij}|$, we have

$$\mathbf{P}[\|H_1^N\| > k_N^{-\frac{1}{2}} x] \geq \mathbf{P}\left[\max_{i < j: \{i,j\} \in E_N} |(H_1^N)_{ij}| > k_N^{-\frac{1}{2}} x\right] = 1 - (1 - (x \log x)^{-p})^{\frac{k_N d_N}{2}}$$

for $x \geq x_0$. Choosing $x = (k_N d_N)^{\frac{1}{p}} (\log d_N)^{-1}$ yields $(x \log x)^{-p} \geq (k_N d_N)^{-1}$ for all sufficiently large N , where we used $k_N \leq d_N$. We have therefore shown that

$$\mathbf{P}[\|H_1^N\| > k_N^{\frac{1}{p}-\frac{1}{2}} d_N^{\frac{1}{p}} (\log d_N)^{-1}] \geq 1 - e^{-\frac{1}{2}}$$

for all large N . But the assumption of part b. implies that $k_N^{\frac{1}{p}-\frac{1}{2}} d_N^{\frac{1}{p}} (\log d_N)^{-1} \rightarrow \infty$. This stands in contradiction to the conclusion of part a., which would imply in particular that $\|H_1^N\| \rightarrow \|s_1\| = 2$ in probability. \square

9.5. Phase transitions in spiked models. Here we prove Theorem 3.35. We first prove convergence of the outlier eigenvalues (as in part a. of Theorem 3.34), and then consider the eigenvectors (as in part b. of Theorem 3.34).

In the following, it will be convenient to introduce the notation

$$B(\theta) := \begin{cases} \theta + \frac{1}{\theta} & \text{for } \theta > 1, \\ 2 & \text{for } \theta \leq 1, \end{cases}$$

and to write $\theta_1 \geq \dots \geq \theta_s > 1 \geq \theta_{s+1} \geq \dots \geq \theta_r > 0 =: \theta_{r+1}$. The assumptions of Theorem 3.35 will be assumed to hold without further comment.

9.5.1. Outlier eigenvalues. We begin by a direct application of universality.

Lemma 9.23. $d_H(\text{sp}(A_d + H_d), \text{sp}(A_d + G_d)) \rightarrow 0$ as $d \rightarrow \infty$ a.s.

Proof. We readily compute $\sigma(A_d + H_d) = O(1)$ and $\sigma_*(A_d + H_d) = O(d^{-\frac{1}{2}})$, while by assumption $R(A_d + H_d) = o((\log d)^{-2})$. Theorem 2.6 with $t = 3 \log d$ yields

$$\mathbf{P}[d_H(\text{sp}(A_d + H_d), \text{sp}(A_d + G_d)) > o(1)] \leq \frac{1}{d^2},$$

and the conclusion follows by the Borel-Cantelli lemma. \square

When combined with Theorem 3.34, Lemma 9.23 suffices to detect the presence and locations of any outlier eigenvalues. However, Hausdorff convergence is not sufficiently strong to establish convergence of individual eigenvalues. In the present setting, this stronger conclusion can however be achieved by combining universality with the min-max principle. To this end we will use the following lemma.

Lemma 9.24. Fix any orthonormal eigenvectors $v_{d,1}, \dots, v_{d,r}$ of A_d with eigenvalues $\theta_1, \dots, \theta_r$, respectively, and let $Q_{d,i}$ be the projection onto $\{v_{d,1}, \dots, v_{d,i}\}^\perp$. Then $\lambda_1(Q_{d,i}(A_d + H_d)Q_{d,i}^*) \rightarrow B(\theta_{i+1})$ as $d \rightarrow \infty$ a.s. for $i = 1, \dots, r$.

Proof. The identical argument as in Lemma 9.23 yields that

$$|\lambda_1(Q_{d,i}(A_d + H_d)Q_{d,i}^*) - \lambda_1(Q_{d,i}(A_d + G_d)Q_{d,i}^*)| \xrightarrow{d \rightarrow \infty} 0 \quad \text{a.s.}$$

But $Q_{d,i}G_dQ_{d,i}^*$ is GOE of dimension $d - i$ (scaled by a factor $(\frac{d-i}{d})^{\frac{1}{2}} = 1 + o(1)$). Thus applying Theorem 3.34 to $Q_{d,i}(A_d + G_d)Q_{d,i}^*$ yields the conclusion. \square

We can now deduce the convergence of the eigenvalues.

Corollary 9.25. $\lambda_i(A_d + H_d) \rightarrow B(\theta_i)$ as $d \rightarrow \infty$ a.s. for $1 \leq i \leq r + 1$.

Proof. Note first that $\lambda_i(A_d + H_d) \leq \lambda_1(Q_{d,i-1}(A_d + H_d)Q_{d,i-1}^*)$ by the min-max principle. Thus $\limsup_{d \rightarrow \infty} \lambda_i(A_d + H_d) \leq B(\theta_i)$ a.s. by Lemma 9.24.

Next, note that the empirical spectral distribution of H_d converges a.s. to the standard semicircle distribution by Theorem 3.29. This implies in particular that $\liminf_{d \rightarrow \infty} \lambda_i(A_d + H_d) \geq \liminf_{d \rightarrow \infty} \lambda_i(H_d) \geq 2$ a.s. for all $1 \leq i \leq r + 1$. Thus we obtain $\lambda_i(A_d + H_d) \rightarrow B(\theta_i) = 2$ as $d \rightarrow \infty$ a.s. for $s + 1 \leq i \leq r + 1$.

On the other hand, by Lemma 9.23 and Theorem 3.34, each $B(\theta_i)$ with $1 \leq i \leq s$ is a limit point of the spectrum of $A_d + H_d$ as $d \rightarrow \infty$. If $\theta_1 > \theta_2 > \dots > \theta_s$ are all distinct, this immediately implies $\liminf_{d \rightarrow \infty} \lambda_i(A_d + H_d) \geq B(\theta_i)$ a.s., concluding the proof. If $\theta_1, \dots, \theta_s$ are not distinct, we can choose $0 \leq A'_d \leq A_d$ of rank r with distinct nonzero eigenvalues so that $\lambda_i(A'_d) \geq \theta_i - \varepsilon$ for all $1 \leq i \leq r$. Then

$$\liminf_{d \rightarrow \infty} \lambda_i(A_d + H_d) \geq \liminf_{d \rightarrow \infty} \lambda_i(A'_d + H_d) \geq B(\theta_i - \varepsilon) \quad \text{a.s.},$$

and the conclusion follows as $\varepsilon > 0$ is arbitrary. \square

9.5.2. Outlier eigenvectors. A universality statement for eigenvectors of $A_d + H_d$ can be obtained using Theorem 2.10. This yields the following conclusion.

Lemma 9.26. *Let $\varepsilon > 0$ be sufficiently small that $I_i := \theta_i + \frac{1}{\theta_i} + [-\varepsilon, \varepsilon]$ are disjoint for distinct values of θ_i . Then for all $1 \leq i \leq s$ and nonrandom $v_d \in \mathbb{C}^d$, $\|v_d\| = 1$*

$$|\langle v_d, 1_{I_i}(A_d + H_d)v_d \rangle - \langle v_d, 1_{I_i}(A_d + G_d)v_d \rangle| \xrightarrow{d \rightarrow \infty} 0 \quad \text{a.s.}$$

Proof. Let $\varphi_i : \mathbb{R} \rightarrow [0, 1]$ be a smooth function so that $\varphi_i(x) = 0$ for $x \notin I_i$ and $\varphi_i(x) = 1$ for $x \in \theta_i + \frac{1}{\theta_i} + [-\frac{\varepsilon}{2}, \frac{\varepsilon}{2}]$. Then the second part of Theorem 2.10 yields

$$|\mathbf{E}[\langle v_d, \varphi_i(A_d + H_d)v_d \rangle] - \mathbf{E}[\langle v_d, \varphi_i(A_d + G_d)v_d \rangle]| \xrightarrow{d \rightarrow \infty} 0.$$

On the other hand, applying Proposition 5.10 with $x = 2C^{-1} \log d$ yields

$$\mathbf{P}[\langle v_d, \varphi_i(A_d + H_d)v_d \rangle - \mathbf{E}[\langle v_d, \varphi_i(A_d + H_d)v_d \rangle]] \geq o(1) \leq \frac{4}{d^2},$$

and analogously for $A_d + G_d$. Thus the Borel-Cantelli lemma yields

$$|\langle v_d, \varphi_i(A_d + H_d)v_d \rangle - \langle v_d, \varphi_i(A_d + G_d)v_d \rangle| \xrightarrow{d \rightarrow \infty} 0 \quad \text{a.s.}$$

But $\varphi_i(A_d + H_d) = 1_{I_i}(A_d + H_d)$ and $\varphi_i(A_d + G_d) = 1_{I_i}(A_d + G_d)$ eventually as $d \rightarrow \infty$ a.s. by Corollary 9.25 and by part a. of Theorem 3.34, respectively. \square

The desired properties of the eigenvectors now follow directly in the case that $\theta_1 > \dots > \theta_s$ are all distinct. The main difficulty is to remove the latter requirement by means of a suitable perturbation argument.

Corollary 9.27. *For any $1 \leq i \leq s$ and $1 \leq j \leq r$, we have*

$$\|P_j(A_d)v_i(A_d + H_d)\|^2 \xrightarrow[d \rightarrow \infty]{a.s.} \left(1 - \frac{1}{\theta_i^2}\right)1_{\theta_j = \theta_i}.$$

Proof. If $\theta_1 > \dots > \theta_s$ are all distinct, then $1_{I_i}(A_d + H_d) = v_i(A_d + H_d)v_i(A_d + H_d)^*$ and $1_{I_i}(A_d + G_d) = v_i(A_d + G_d)v_i(A_d + G_d)^*$ eventually as $d \rightarrow \infty$ a.s. for $1 \leq i \leq s$ by Corollary 9.25 and part a. of Theorem 3.34. The conclusion then follows readily by applying Lemma 9.26 and part b. of Theorem 3.34.

In the general case, let $A'_d = \sum_{m=1}^r \theta'_m v_m(A_d)v_m(A_d)^*$ be a perturbation of A_d (for a choice of orthonormal eigenvectors $v_m(A_d)$) with distinct $\theta'_1 > \dots > \theta'_r$ and such that $|\theta_m - \theta'_m| \leq \varepsilon$ for all m . Let $J_i := \{k : \theta_k = \theta_i\}$, and let $Q_i(A'_d + H_d)$ be the projection on the linear span of $\{v_k(A'_d + H_d) : k \in J_i\}$. We claim that

$$\limsup_{d \rightarrow \infty} \left| \|P_j(A_d)\tilde{v}_{d,i}\|^2 - \left(1 - \frac{1}{\theta_i^2}\right)1_{\theta_j = \theta_i} \right| \lesssim \varepsilon \quad \text{a.s.}$$

for any (possibly random) choice of unit vector $\tilde{v}_{d,i} \in \text{ran}(Q_i(A'_d + H_d))$. Indeed, writing $\tilde{v}_{d,i} = \sum_{k \in J_i} c_{d,k} v_k(A'_d + H_d)$ with $\sum_{k \in J_i} c_{d,k}^2 = 1$, we can compute

$$\begin{aligned} \|P_j(A_d)\tilde{v}_{d,i}\|^2 &= \sum_{m \in J_j} \sum_{k,l \in J_i} c_{d,k} c_{d,l} \langle v_k(A'_d + H_d), v_m(A_d) \rangle \langle v_m(A_d), v_l(A'_d + H_d) \rangle \\ &= \sum_{k \in J_i} c_{d,k}^2 \left(1 - \frac{1}{(\theta'_k)^2}\right)1_{\theta_j = \theta_i} + o(1) \quad \text{a.s.} \end{aligned}$$

as $d \rightarrow \infty$, where we used that $|\langle v_m(A_d), v_l(A'_d + H_d) \rangle|^2 \rightarrow (1 - \frac{1}{(\theta'_l)^2})1_{m=l}$ a.s. as A'_d has distinct eigenvalues. The claim follows as $\theta \mapsto 1 - \frac{1}{\theta^2}$ is Lipschitz on $[1, \infty)$.

For any projection matrices $P, Q \in M_d(\mathbb{C})_{\text{sa}}$ and $c \in \mathbb{R}$, we can write

$$\sup_{v \in \text{ran } Q, \|v\|=1} \left| \|Pv\|^2 - c \right| = \|Q(P - c\mathbf{1})Q\|.$$

Using this identity, the above claim may be rewritten as

$$\limsup_{d \rightarrow \infty} \|Q_i(A'_d + H_d)(P_j(A_d) - (1 - \frac{1}{\theta_i^2})1_{\theta_j = \theta_i}\mathbf{1})Q_i(A'_d + H_d)\| \lesssim \varepsilon \quad \text{a.s.}$$

On the other hand, when ε is sufficiently small, Corollary 9.25 ensures that the eigenvalues $\{\lambda_k(A'_d + H_d) : k \in J_i\}$ are separated from the rest of the spectrum of $A'_d + H_d$ by a positive gap as $d \rightarrow \infty$. A routine application of the Davis-Kahan theorem [18, Theorem VII.3.1 and Exercise VII.1.11] yields

$$\|Q_i(A'_d + H_d) - Q_i(A_d + H_d)\| \lesssim \|A'_d - A_d\| \leq \varepsilon$$

eventually as $d \rightarrow \infty$ a.s. As we may choose $\varepsilon > 0$ arbitrarily small, it follows that

$$\|Q_i(A_d + H_d)(P_j(A_d) - (1 - \frac{1}{\theta_i^2})1_{\theta_j = \theta_i}\mathbf{1})Q_i(A_d + H_d)\| \xrightarrow{d \rightarrow \infty} 0 \quad \text{a.s.}$$

The conclusion follows as $v_i(A_d + H_d) \in \text{ran}(Q_i(A_d + H_d))$. \square

Combining Corollaries 9.25 and 9.27 concludes the proof of Theorem 3.35.

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