



# IdentityKD: Identity-wise Cross-modal Knowledge Distillation for Person Recognition via mmWave Radar Sensors

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## Abstract

Recent advancements in person recognition have raised concerns about identity privacy leaks. Gait recognition through millimeter-wave radar provides a privacy-centric method. However, it is challenged by lower accuracy due to the sparse data these sensors capture. We are the first to investigate a cross-modal method, IdentityKD, to enhance gait-based person recognition with the assistance of facial data. IdentityKD involves a training process using both gait and facial data, while the inference stage is conducted exclusively with gait data. To effectively transfer facial knowledge to the gait model, we create a composite feature representation using contrastive learning. This method integrates facial and gait features into a unified embedding that captures the unique identity-specific information from both modalities. We employ two distinct contrastive learning losses. One minimizes the distance between embeddings of data pairs from the same person, enhancing intra-class compactness, while the other maximizes the distance between embeddings of data pairs from different individuals, improving inter-class separability. Additionally, we use an identity-wise distillation strategy, which tailors the training process for each individual, ensuring that the model learns to distinguish between different identities more effectively. Our experiments on a dataset of 36 subjects, each providing over 5000 face-gait pairs, demonstrate that IdentityKD improves identity recognition accuracy by 6.5% compared to baseline methods.

## CCS Concepts

• Security and privacy → Security services; • Computing methodologies → Machine learning.

## Keywords

Identity recognition, Cross-modality, Knowledge distillation, Contrast learning, Gait, mmWave radar

### ACM Reference Format:

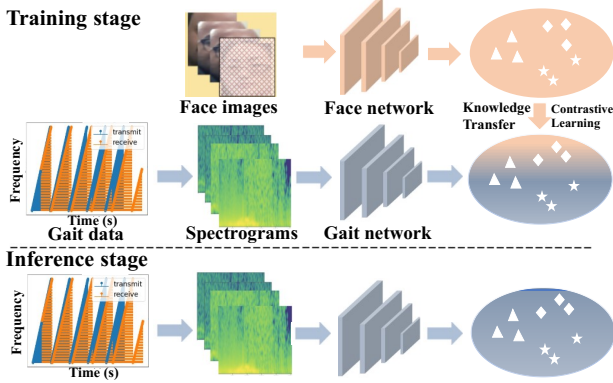
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## 1 Introduction

For decades, the problem of human authentication has been a persistent challenge. Biometric-based recognition was once considered a reliable human authentication method. Common biometrics involve technologies like retina scans [19], voice recognition [8], and facial recognition [32]. However, all these bio-signs necessitate extra effort from individuals for authentication. For instance, facial recognition demands positioning in front of a high-resolution camera to capture unique facial features, and fingerprint methods require one to place his/her fingers on a scanner to detect patterns. These methods are vulnerable to spoofing attacks, where unauthorized users deceive the system with counterfeit biometric traits of a legitimate user [2, 9, 20, 23]. To overcome these issues, researchers have turned to effortless and non-invasive authentication systems using behavioral biometrics, such as gait features. Notably, studies have shown that it is exceedingly difficult to spoof human gait [21], as the uniqueness of an individual's gait makes it challenging to imitate others effectively.

Gait recognition, which analyzes an individual's walking pattern, presents a promising alternative because it is non-invasive and difficult to spoof [15]. Imagine where your identity can be securely recognized without revealing sensitive information like your face. This vision drives our research. Our goal is to recognize individuals based on how they walk, using millimeter-wave (mmWave) radar while preserving privacy. These sensors can capture the movements of a person without showing their face, which is great for privacy. However, gait recognition using mmWave radar sensors faces challenges due to the sparse data these sensors capture, often leading to lower recognition accuracy [1, 25]. To address these challenges, we explore leveraging multimodal learning by incorporating facial data, which inherently contains a much richer and more detailed

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**Figure 1: Cross-modal knowledge transfer.** The face network (teacher) transfers the discriminative knowledge to the gait network (student) during training. During the inference, the gait network only conducts identity recognition. The same shape (triangle, star, diamond) represents the same identity.

set of identity-specific information, to significantly enhance the accuracy and reliability of gait-based identity recognition.

We propose an identity recognition method based on the knowledge distillation (KD) [11] via gait data from mmWave radar sensors, called IdentityKD. The overview of IdentityKD is shown in Figure. 1. We employ a KD strategy to facilitate the transfer of knowledge from the more informative facial modality to the less informative gait modality during training. However, we empirically find that directly applying conventional KD techniques to our cross-modal teacher-student learning framework does not yield the desired outcomes. We identify two primary factors contributing to this sub-optimal performance: (1) a significant disparity in the latent space domains of the gait and face modalities, and (2) misalignment in the quality of the input data for faces and gaits. Specifically, traditional KD methods typically aim to minimize the difference between the teacher and student outputs, encouraging the student model to mirror the teacher model exactly. However, due to the considerable domain gap between the two modalities, this approach can result in overfitting. Additionally, when the quality of input data from the two sources is not comparable, the efficacy of the distillation process tends to diminish.

To solve these problems, we use contrastive learning to integrate facial and gait features into a unified embedding that captures the unique identity-specific information from both modalities shown in Figure. 1. During training, we use both the radar data (gait) and facial images. Specifically, we first convert the time-series gait data into spectrogram images, which can be processed similarly to images. Then, we use KD to transfer knowledge from the facial data to the gait data. The face network teaches the gait network to understand and learn from the detailed facial information, enhancing its ability to interpret the less detailed gait data. Meanwhile, we employ compositional contrastive learning, a technique that ensures features from the same individual are close together in the feature space (intra-class compactness) and those from different individuals are far apart (inter-class separability). This alignment is crucial for creating a unified representation that accurately captures identity-specific features from facial and gait modalities. Additionally, we

use an identity-wise training strategy that tailors the learning process for each individual. This makes the gait network better at distinguishing between different persons, even if the data quality varies. After training, during the inference stage, the network can recognize persons using only the gait data from mmWave radar sensors.

Our method is tested on a dataset comprising 36 subjects, demonstrating that our approach significantly boosts identity recognition performance by approximately 5% to 9%. Our method ensures that in real-world use, only gait data is needed, which is less invasive and better for privacy. This approach addresses the limitations of radar data and provides a strong solution for security, surveillance, and access control where privacy is crucial. Our contributions are summarized as follows:

- We propose IdentityKD, a novel KD model for person recognition, featured by learnable compositional embeddings that bridge the semantic gap between gait and face modalities and utilize a distillation objective that simultaneously contrasts two modalities within a unified latent space.
- We present an identity-wise distillation strategy that adaptively tailors identity configurations for each subject during training, and refines the weight averaging process to enhance and stabilize the model across all individuals, particularly improving robustness in the least performing classes.
- We conduct experiments on a dataset of 36 subjects, and the results show that our method can effectively improve the accuracy of identity recognition.

## 2 Background

### 2.1 mmWave Radars for Person Identification

**Principles of mmWave Radar.** The mmWave radar operates on the frequency-modulated continuous wave (FMCW) principle, which enables it to measure the range, relative radial speed, and angle of a target [31]. The radar sends out a chirp signal that increases in frequency over time and processes the reflected signals from objects to determine their positions in three dimensions. For range measurement, the distance between the radar and the object is calculated using the formula involving the intermediate frequency (IF), the speed of light, the bandwidth of the chirp, and the chirp duration. A fast Fourier transform (FFT) is performed on the IF signal to measure the range of multiple objects at different distances. For angle estimation, the mmWave radar employs a linear antenna array. By emitting chirps with the same initial phase and sampling the reflected signals with multiple receiver antennas, the radar can determine the phase difference between signals received by consecutive antennas. The angle of arrival (AoA) is then calculated using the phase difference, the wavelength, and the distance between the antennas. This allows for the precise location of objects in a Cartesian coordinate system once the range and AoA are known. Based on the principle of mmWave radar, we can effectively capture relevant information about individuals entering the radar monitoring area, providing a foundation for subsequent data preprocessing.

**Person Identification Using Gait.** Gait, a biometric characteristic observable during walking, inherently includes identity-specific traits that can be used for human identification [3, 7, 13, 24]. Gait-based identification systems work by extracting walking features

from a data sequence, such as step length, arm swing amplitude, and walking pace, and then employing these characteristics as identifiers. As walking involves a sequence of movements, gait feature extraction typically spans multiple frames. In our study, we utilize such sequences to extract gait features from an mmWave radar sensor and to re-identify individuals.

## 2.2 Cross-modal Knowledge Distillation

Knowledge distillation (KD) is a model compression technique used to transfer knowledge from a complex model (teacher) to a light-weight model (student) to improve the overall performance of the small model [12]. KD techniques aim to minimize the discrepancy between the prediction scores (logits) of the teacher and student models. It has been suggested to broaden the feature information extracted from the model using cross-modal KD. This bridging technique establishes a connection across diverse data modalities to facilitate the transfer of knowledge, ultimately leading to improved performance. In cross-modal KD, most existing approaches focus on closely related modalities, including depth and optical flow images [10] and RGB and depth images [26]. Some researchers employed a multi-modal teacher combining face and speech to oversee the training of a single-modal student model, although they noted a significant disparity between the speech and face data, which posed challenges in enhancing performance [14, 16, 30]. Current work [5] transferred knowledge across image, audio, and video modalities uncovering richer multi-modal knowledge. Inspired by these studies, our paper targets the issue of cross-modal disparities, specifically between facial and gait data for person recognition.

## 2.3 Contrastive Learning

Contrastive self-supervised learning focuses on training an encoder to derive meaningful representations from unlabeled images by bringing together similar samples (positives) and separating dissimilar ones (negatives). In particular, instance discrimination treats augmented versions of the same image (e.g., through random cropping) as positives, while considering distinct images as negatives.

Contrastive learning techniques with unlabeled samples often struggle to capture category-specific information during the feature extraction process. However, when these self-supervised contrastive learning strategies are employed on annotated data, they have been shown to more effectively consolidate features from identical categories, resulting in denser clusters [17]. This validates the utility of supervised contrastive learning in the domain of identity recognition. As a result, we intend to integrate supervised techniques with the principles of contrastive learning to develop a model capable of discerning feature consistency within the same category as well as distinctions across different categories [6]. Our approach will specifically showcase contrastive learning through the use of dual perspectives of an individual's identity: one from a standard RGB image and the other from gait captured by mmWave radar sensors. We will construct contrastive pairs using mmWave radar data, consisting of anchor images and comparative samples. These pairs will then be processed by the contrastive learning network for advanced feature extraction, which we will elaborate on in the subsequent section.

## 3 Methodology

The overall structure of our IdentityKD method is shown in Fig. 2. We first establish a face feature extraction module to serve as the teacher model, extracting features from RGB imagery. Concurrently, we construct a gait feature extraction module that acts as the student model, tasked with gait feature extraction from data obtained via mmWave radar sensors. Subsequently, we employ KD methods to refine the student model through contrastive loss optimization. Additionally, the model is further enhanced through an identity-wise calibrated strategy, balancing the disparity of different classes.

### 3.1 Visual Feature Representation

As shown in Fig. 2, the visual feature extraction module is also the teacher feature extraction module. In this context, the superscripts  $t$  and  $s$  are associated with the teacher and student models, respectively. The input to this module is an RGB facial image sequence  $X_n$ , where each image  $x_i$  in  $X_n$  has dimension  $\mathbb{R}^{3 \times H \times W}$ , with width  $W$  and height  $H$ . The facial dataset  $D_f$  can be expressed as

$$D_f = \{(x_i, y_i)\}_{i=1}^n, \quad n \in \{1, 2, 3, \dots\} \quad (1)$$

where  $x_i$  refers to the  $i$ -th facial sample associated with the teacher model  $t$ .  $y_i$  is the label corresponding to the  $i$ -th sample.

The facial input dataset is subjected to random data augmentation for data augmentation to enhance the generalization capacity of the model. The preprocessed RGB data is then put into the teacher model to extract facial features. The teacher is a facial recognition system whose main goal is to learn the Euclidean distance between samples to reduce the distance between facial samples of the same person and increase the distance between facial samples of different people. We propose a feature fusion strategy (details in Sec. 3.3) for minimizing the effect of significant modality distinctions between cross-modal datasets. To avoid the inhomogeneity of the structure of the teacher-student feature capture networks across modalities, we harvest the outputs of the penultimate layer of the teacher and student models for cross-modal fusion. Note that for a classification task, the penultimate layer is the layer before the final classifier. We extract the penultimate feature embeddings before the classifier. In this study,  $x_i$  is fed into the FaceNet [28] encoder  $F^t(\cdot)$  to generate the facial feature representation  $p_i^t$ :

$$p_i^t = F^t(x_i) \quad (2)$$

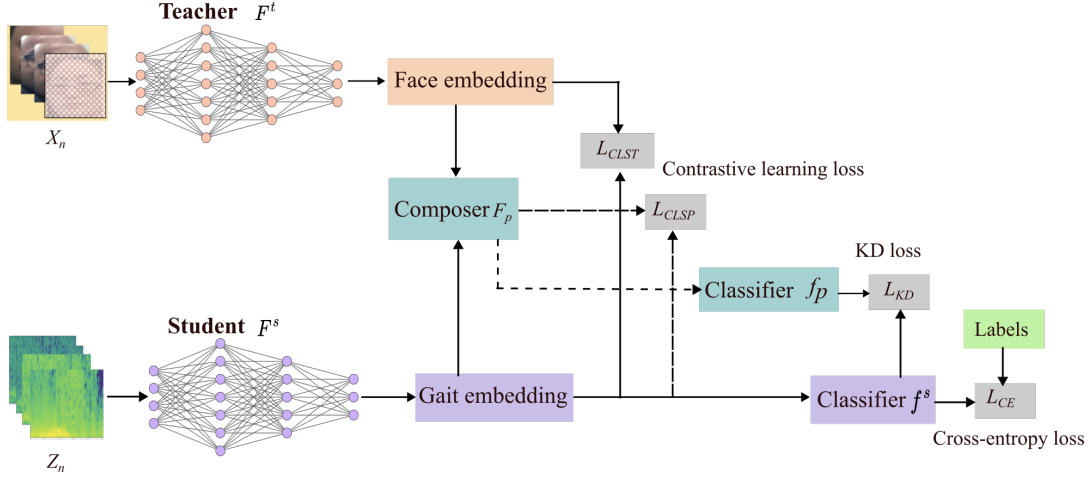
### 3.2 RF Feature Representation

We preprocess the raw gathered gait dataset from mmWave radar to create spectrogram images  $Z_n$ , where each image  $z_i$  in  $Z_n$  has dimension  $\mathbb{R}^{3 \times H \times W}$ . We then feed these images to our student model  $F^s(\cdot)$ , labeling the gait dataset as

$$D_g = \{(z_i, y_i)\}_{i=1}^n, \quad n \in \{1, 2, 3, \dots\} \quad (3)$$

where  $z_i$  refers to the  $i$ -th gait spectrogram image associated with the student model  $s$ .

Our thorough experiments found that the disparity between gait and facial image data modalities is considerable, which complicates the application of knowledge derived from facial features to gait feature enhancement. This leads to ineffective cross-modal knowledge transfer and subpar performance in identity recognition tasks. To address this, we suggest a contrastive learning approach that



**Figure 2: The framework of IdentityKD method where the teacher (face recognition model) transfers discriminative knowledge to the student (gait model). The Composer fuses gait and face embeddings. The framework utilizes contrastive learning loss, KD loss, and cross-entropy loss to optimize student model performance.**

combines the embeddings from both the teacher and student models under a supervised framework. This is designed to bridge the semantic divide, causing dissimilar samples to diverge and similar samples to converge, thereby narrowing the domain and semantic gaps between different types of data. The penultimate feature embeddings, denoted by  $p_i^s$ , are acquired by passing spectrograms through the student model. Following this, a classifier  $f^s(\cdot)$  is employed to produce the ultimate classification output, represented by  $y_i^s$ , which also signifies the student model's final logit outputs.

$$p_i^s = F^s(z_i) \quad (4)$$

$$y_i^s = f^s(p_i^s) \quad (5)$$

### 3.3 Fusion of Multi-Modal Representations

It has been previously noted that student and teacher model embeddings may not align semantically. To reconcile these potential semantic and domain discrepancies between modalities, our approach suggests a correction for the facial image embeddings. This is achieved by merging teacher and student embeddings and anchoring the combined embeddings to the specific aims of our task, thereby bridging the identified semantic gaps. Given that the network structures differ among modalities, the synthesis of cross-modal composition occurs at the penultimate layer.

Formally, the facial embedding  $p_i^t$  merges with the gait embedding  $p_i^s$ , through the induction of a residual on the teacher embeddings. The teacher embeddings are refined with a composition function  $F_p(\cdot, \cdot)$ , which introduces a residual function  $f^{st}(\cdot, \cdot)$  that combines two modalities using normalization, concatenation, and a linear transformation:

$$p_i = F_p(p_i^t, p_i^s) = p_i^t + f^{st}(p_i^t, p_i^s), \quad (6)$$

where  $p_i$  is the fused embeddings. This procedure has connections to earlier studies that integrate features from multiple modalities [4], but our methodology focuses on modulating the teacher embedding through an adjustable residual. More critically, to guide outcomes of

the classifier  $f_p(\cdot)$ , we fine-tune  $F_p(\cdot, \cdot)$  with the objective function associated with the subject classification.

### 3.4 Identity-wise Cross-modal Distillation

Previous uni-modal approaches typically focus on transferring knowledge in the prediction space, where the student network is trained to mirror the output of the teacher network. However, this technique is not directly applicable to multimodal KD, as teacher networks are generally pre-trained with diverse task objectives and predict various classes. In light of this, we suggest employing contrastive learning within the latent feature space and then differentiating the class distributions in the predictive space.

**Contrast loss.** With uni-modal and compositional embeddings, we aim to distill knowledge by converging positive pairings and diverging negative ones across different modalities. For instance, positive pairings might consist of a facial image and the corresponding gait data of the same individual. Concretely, for a trio composed of a facial image, gait, and their combined embeddings, a contrastive loss can be calculated for each pairing to strengthen their association within the unified feature space. Formally, the contrastive loss (utilizing InfoNCE [22]) for an embedding pair is calculated as follows:

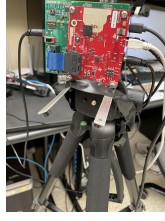
$$L_{CLST} = -\log \frac{\exp(\text{sim}(p_i^s, p_i^t)/\tau)}{\sum_{j=1}^B \exp(\text{sim}(p_j^s, p_j^t)/\tau)} = -\log p_i^{st} \quad (7)$$

$$L_{CLSP} = -\log \frac{\exp(\text{sim}(p_i^s, p_i)/\tau)}{\sum_{j=1}^B \exp(\text{sim}(p_j^s, p_j)/\tau)} = -\log p_i^{sp} \quad (8)$$

where  $L_{CLST}$  is the contrast loss between gait and face embeddings.  $L_{CLSP}$  is the contrast loss between gait and fusion embeddings.  $B$  refers to the size of the mini-batch.  $\tau$  is the temperature factor to control the softness of logits.  $\text{sim}(\cdot, \cdot)$  is the cosine similarity.

The two contrastive learning losses,  $L_{CLSP}$  and  $L_{CLST}$ , play complementary roles in optimizing the feature space for identity recognition. The  $L_{CLSP}$  loss is designed to minimize the distance between





**Figure 3: Data collection environment and mmWave device**

embeddings of data pairs from the same person, thus enhancing intra-class compactness by clustering features of the same identity tightly together. On the other hand,  $L_{CLST}$  aims to maximize the distance between embeddings of data pairs from different individuals, thereby improving inter-class separability by pushing features of different identities further apart. These losses work synergistically:  $L_{CLSP}$  ensures that the model can accurately recognize and group features belonging to the same person, while  $L_{CLST}$  ensures clear boundaries between different identities. Together, they balance the feature space by simultaneously enforcing compact clusters for each identity and distinct separation between different identities. This dual approach harmonizes intra-class and inter-class relationships, ensuring that there is no contradiction between the two objectives and resulting in a robust and discriminative feature representation.

Considering the possibility of multiple positive face-gait pairings within a single batch pertaining to a particular subject, we introduce a multi-class contrastive loss that incorporates the class label  $k$  into its formulation:

$$L_{st}(p_i^s, p_i^t) = -\frac{1}{B_p} \sum_{i=k} \log p_i^{st} - \frac{1}{B_n} \sum_{i \neq k} \log(1 - p_i^{st}) \quad (9)$$

$$L_{sp}(p_i^s, p_i) = -\frac{1}{B_p} \sum_{i=k} \log p_i^{sp} - \frac{1}{B_n} \sum_{i \neq k} \log(1 - p_i^{sp}) \quad (10)$$

where  $B_p, B_n$  represent the counts of positive and negative pairs associated with the gait embedding  $P_i^s$  tagged with class  $k$ . These equations prompt the network to enhance the probabilities attributed to matching pairs and reduce those assigned to mismatched pairs. The multi-class loss synergizes the singular facial modality and the compounded multi-modal knowledge in a compositional manner:

$$L_{cs} = \frac{\gamma}{B} \sum_{i=1}^B L_{st}(p_i^s, p_i^t) + \frac{1-\gamma}{B} \sum_{i=1}^B L_{sp}(p_i^s, p_i) \quad (11)$$

with  $\gamma$  being a hyperparameter for tuning the contribution of each term and  $B$  being the batch size. In essence, the proposed loss  $L_{cs}$  acts as a similarity regulator to synchronize the embeddings within the multi-modal latent space.

**Identity-wise KD loss.** Empirically, we find that the model’s performance varies across different identities, making KD loss unsuitable for all subjects. Inspired by [27], which tailors training to class performance, we introduce a margin  $m$  and use identity-specific training accuracy  $A_i$  to gauge subject difficulty. For a subject  $i$  with training accuracy  $A_i$ , we adjust the margin  $m_i$  for the next epoch based on  $A_i$ . Lower  $A_i$  suggests a higher risk of misclassification, so we reduce  $m_i$ . To prevent  $m_i$  from becoming too small, we introduce a scaling factor  $\lambda_1$ :

$$m_i \leftarrow (\lambda_1 + A_i) \cdot m \quad (12)$$

where  $m$  is typically  $8/255$ . This approach optimizes  $m_i$  during training. We also customize robustness regularization  $\beta_i$  for each subject:

$$\beta_i \leftarrow (\lambda_2 + A_i) \cdot \beta \quad (13)$$

where  $\lambda_2$  is a scaling factor. The KD loss function incorporated by Kullback-Leibler divergence  $KL(\cdot)$  and cross-entropy function  $L_{CE}(\cdot)$  becomes:

$$L_{KD} = \frac{1}{B} \sum_{i=1}^B \frac{L_{CE}(y_i^s, y_i) + \beta_i (KL(f_p(p_i), y_i) - m_i)}{1 + \beta_i} \quad (14)$$

The normalization factor  $1 + \beta_i$  ensures balanced emphasis across subjects. Introducing  $m_i$  integrates the calibrated margin with subject-specific regularization. The total loss is:

$$L = \delta_1 L_{cs} + \delta_2 L_{KD} \quad (15)$$

where  $\delta_1$  and  $\delta_2$  balance each term’s contributions. Note that, unlike [27], which did not apply this method to KD, our identity-wise approach transfers knowledge from facial data to gait data. This novel application of cross-modal KD for identity recognition demonstrates the method’s effectiveness in a new context.

## 4 Experiment

### 4.1 Experimental Setup

**Data collection.** In this study, we employ a Texas Instruments (TI) 77 GHz FMCW radar IWR1843BOOST board in conjunction with a DCA1000EVM board to gather raw gait data within an office setting, as depicted in Fig. 3. The radar system operates from 77 to 81 GHz, covering up to a 4 GHz bandwidth. A Lenovo 740 laptop with TI mmWave studio software is used as a control system for our radar device to configure the FMCW wave parameters such as chirp width, repetition time, and chirp slope. The radar is positioned 1 meter from the 15 m by 20 m detection area, mounted on a tripod at a height of 1.5 meters. This setup aims to minimize occlusions among subjects by ensuring comprehensive monitoring of the entire detection zone. The specific radar settings used in our experiments are detailed in Table 1. This configuration enables the FMCW radar to capture data at 200 frames per second, achieving a range resolution of 4 cm and a velocity resolution of 0.06 m/s. The superior range resolution significantly enhances our ability to distinguish between multiple targets, aiding in the effective detection and separation of subjects. Meanwhile, the fine velocity resolution allows for the collection of detailed gait data, increasing the likelihood of identifying distinctive gait characteristics.

**Table 1: Radar configuration parameters**

Parameter	Value	Parameter	Value
Start frequency	77 GHz	Bandwidth	900.9 MHz
No. of samples/chirp	230	Sampling rate	5000 ksp/s
No. of chirps/frame	200	ADC Samples	256
Frame periodicity	33 ms	Frequency slope	15 MHz/us

We recruit 36 volunteers to create our dataset. Participants are instructed to walk naturally within an office space. Walks directed towards and away from the radar are both considered separate instances. Each volunteer completes 100 walking trials, yielding

100 raw radar captures per person. The analog signal from mmWave radar is first digitized into a discrete beat signal. Then, a range-FFT is applied to produce a range-time map. We execute Short-Time Fourier Transforms (STFT) across the range bins, creating spectrograms that detail the micro-Doppler signatures of human movement. Finally, these spectrograms are merged to form the final mmWave gait biometric and structured into  $256 \times 256$  pixels, aligning with the format of the facial data.

We use the Logitech-C920s Pro 1080 Webcam to collect the RGB facial image data while monitoring the gait data. We use MTCNN face detector [29] to conduct face detection and alignment, and then crop the face images to  $160 \times 160$  pixels. During model training, random data augmentation is applied to RGB input images. Thirty-six people's faces are included in  $5000 \times 36$  images.

**Model.** We select ResNet18 as the Baseline for our student model. For the teacher model, we utilize FaceNet [28] which is a model pre-trained for face recognition tasks with an accuracy of 99.08%.

**Evaluation metrics.** We use the accuracy (ACC) (%), Recall (%), and F1-score (%) as the evaluation indicators for models.

**Training setup.** During the training, FaceNet is frozen. Adam optimizer [18] is used to optimize the ResNet18 model. An epoch of 200 is run with 128 batches. The learning rate is initially set to  $1e-4$  and the MultiStepLR learning rate decay algorithm is used for adjusting the learning rate.  $\gamma$  and  $\tau$  are set to 0.8 and 5.0, respectively.

## 4.2 Experimental Results

We compare IdentityKD with GaitSet [3], GaitPart [7], GaitGL [13], and CRF [24] under normal walking with view 0 in Table 2. IdentityKD demonstrates exceptional performance in identity recognition by achieving an accuracy of 98.58% using gait data, significantly surpassing other gait recognition methods such as GaitSet, GaitPart, GaitGL, and CRF, which record accuracies of 88.09%, 89.21%, 88.75%, and 93.95%, respectively. This remarkable performance highlights IdentityKD's effectiveness in utilizing cross-modal knowledge distillation, where facial data is leveraged during training to enhance the recognition capabilities of gait data during inference. The method nearly matches the accuracy of FaceNet (99.08%), illustrating its ability to integrate identity-specific information from both facial and gait modalities. This cross-modal integration enables IdentityKD to outperform traditional gait recognition approaches, showcasing its robustness and potential for real-world applications that prioritize privacy by using non-invasive gait data for identity verification.

**Table 2: Comparisons of different methods using gait data.**

Method	GaitSet	GaitPart	GaitGL	CRF	IdentityKD
ACC	88.09	89.21	88.75	93.95	<b>98.58</b>

We also assess IdentityKD, benchmarking it against the vanilla KD [12], the contrast fusion-based KD (CFKD) [5], the margin-based KD (MKD) [16], and the Baseline method. CFKD and MKD are cross-modal KD methods. We present the results in Table 3.

IdentityKD achieves the highest scores in all metrics (ACC: 98.58%, Recall: 99.01%, F1: 98.43%), suggesting it is superior in balancing precision and recall while maintaining high overall accuracy. The next best performer is MKD, followed by CFKD, then vanilla KD. The Baseline method exhibits the least performance, with its

accuracy falling short by approximately 6.5% compared to that of IdentityKD.

**Table 3: Comparison of IdentityKD against existing KD.**

Method	ACC	Recall	F1
Baseline	92.17	92.77	93.13
vanilla KD	94.91	94.25	93.90
CFKD	96.12	95.97	96.45
MKD	96.38	96.16	96.18
IdentityKD	<b>98.58</b>	<b>99.01</b>	<b>98.43</b>

The outperformance of IdentityKD firmly attests to its robustness and efficacy in gait-based identity recognition tasks. It demonstrates the advantage conferred by incorporating facial data within the training paradigm, thereby substantially augmenting the discriminative capacity of mmWave radar for gait-based identity recognition. Notably, this advancement is realized while rigorously adhering to privacy considerations, given that the use of facial data is restricted solely to the training phase. During operational deployment, the inference relies exclusively on gait data, thereby ensuring a privacy-preserving recognition system.

**Table 4: Person recognition results under different student model structures and metrics.**

Method	ACC	Recall	F1
ResNet18	<b>98.58</b>	<b>99.01</b>	<b>98.43</b>
MobileNet	88.24	87.20	85.69
EfficientNet	95.88	92.20	94.98
Vgg16	87.62	84.25	87.50

## 4.3 Ablation Study

**Impact of student model structure.** Table 4 presents the identity recognition performance of various deep learning architectures when applied as student models in the IdentityKD framework.

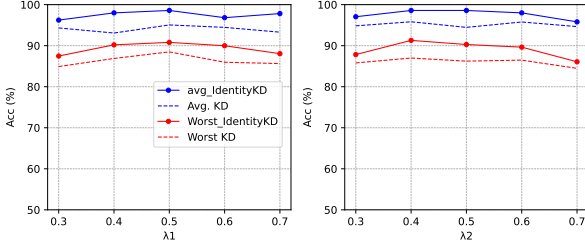
ResNet18 shows the highest accuracy (94.71%) and Recall (94.15%), indicating its proficiency in correctly identifying positive instances. MobileNet and Vgg16 show improved performance compared to the 4-subject dataset but still lag behind the ResNet models. EfficientNet parallels ResNet18's 95.88% accuracy, making it a highly efficient and practical choice for deployment. Overall, the table illustrates that while all models benefit from KD, there is a clear hierarchy in performance, with ResNet models outperforming MobileNet, EfficientNet, and Vgg16, highlighting the importance of model selection in the context of scale and complexity.

**Impact of contrastive learning loss.** In IdentityKD, contrastive learning loss plays a crucial role, facilitating the learning of a compositional embedding that bridges the gap between cross-modal data while capturing semantics pertinent to the task. Our evaluation compares the efficacy of contrast losses derived from KL divergence and noise-contrastive estimation (NCE), as shown in Table 5. We can see that while both methods are effective for the identity task, the NCE method demonstrates a marginal advantage over KL in terms of these performance metrics.

**Impact of identity-wise configuration.** We investigate the influence of base scaling factor  $\lambda_1$  and  $\lambda_2$  by conducting experiments

**Table 5: Comparison of contrast losses from KL and NCE.**

Method	ACC	Recall	F1
KL	97.24	97.05	96.98
NCE	98.58	99.01	98.43

**Figure 4: The average (solid) and the worst class robustness (dotted) of models trained with different  $\lambda$ .**

of IdentityKD and identity-wise vanilla KD with  $\lambda$  varying from 0.3 to 0.7 shown in Fig 4. We can see that IdentityKD with different  $\lambda_1$  and  $\lambda_2$  show better overall and the worst class robustness than vanilla KD, among which  $\lambda_1 = 0.5$  and  $\lambda_2 = 0.4$  performs best.

## 5 Conclusion

We develop IdentityKD which uses gait data from mmWave radar with the assistance of facial images for person recognition. This technique mitigates the challenges posed by data misalignment through knowledge distillation methodology, augmented by a compositional embedding strategy. To bolster the model’s robustness across various identities, we incorporate contrast learning along with identity-wise calibration into the knowledge transfer process. Our streamlined student model is designed to preserve individual privacy while still achieving precise identification through mmWave radar data. Comparative evaluations demonstrate that our method outperforms the baseline, offering exceptional performance improvements by 6.5%.

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