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## Harnessing Interpretable and Ensemble Machine Learning Techniques for Precision Fabrication of Aligned Micro-Fibers

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Electrospining is a robust technique for producing micro/nano-scale fibrous structures, influenced by intricate interplays of fluid dynamics, aerodynamics, and electromagnetic forces. Depending on the desired outcome, these fibers can adopt various morphologies, including solid, tubular, concentric, and gradient. Such morphologies are modulated by parameters such as collector configuration, flow rate, voltage, solution properties, and nozel dimensions. However, the task of modeling and predicting these multifaceted morphologies remains complex. Aligned microfibers with 3D orientation hold promise in tissue engineering, regenerative medicine, and drug delivery, necessitating meticulous control over the fabrication parameters. In our research, we tapped into machine learning (ML) to address these challenges. Classification ML models were designed to predict fibrous patterns—aligned, random or jet branching—based on determinants like voltage, flow rate, and collector configurations. Notably, the Random Forest (RF) and Support Vector Machine (SVM) models, especially with radial kernel-trick, displayed outstanding predictive capabilities on the test alace. Furthermore, regression-based ML was harnessed to discern fiber alignment coherency and inter-fiber distances. Models such as Lasso and Ridge regression elucidated predictive coefficients for these characteristics, while ensemble models, like gradient-boosting (GB) decision trees (DT), showcased provess in regression scenarios. Key findings spotlighted the significance of parameters like plate gap for alignment coherency and needle-to-collector distance for inter-fiber spacing, as we strive to gain granular control over micromano feature morphology in electrospinning, understanding predictor-exponse dynamics is imperative. Our investigation underscores the essential role of ML in enhancing both qualitative and quantitative precision in fabricating advanced fibrous structures. Moreover, fixing ML with react-tem process monitoring offers groundbreaking potential, pa

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Electrospinning is a rapid fabrication technique for polymer-based fibrous structures at the micro and nanoscale using dielectric polymer solutions. With applications spanning across diverse domains like healthcare, soft materials, flexible

electronics, energy harvesting, chemical storage, and catalysis, its relevance cannot be overstated [1, 2]. The functional utility of these fibrous structures in specific application areas hinges predominantly on their micro and macro attributes. At the microscopic level, properties such as diameter of the fibrous structures, surface protosity, material composition, and hollow cross-sections are of paramount importance [3]. On the

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macroscopic scale, attributes like fiber orientation (be it aligned or random), orientation degree, dominant directional flow, inter-fiber spacing, and fiber density play pivotal roles [4, 5]. From a manufacturing standpoint, the meticulous manipulation of process parameters facilitates the creation of fibrous constructs that exhibit the desired micro and macro characteristics. Hollow tubular scaffold structures are increasingly sought after in microfluidics, finding applications in areas such as healthcare drue delivery and tissue. increasingly sought after in microfluidies, finding applications in areas such as healthcare, drug delivery, and tissue engineering [6, 7]. When it comes to the fabrication of these hollow, micro-scale fibrous structures (referred to as microtubes), process parameters like flow rate, the distance between needle and collector, and plate-app critically influence the final product's orientation and fiber density. Electrospun fibrous assemblies with a high degree of alignment have found substantial use in tissue engineering, disease modelling, and studies of cell migration, to name a few [8, 9].

One of the major challenges of fabricating highly aligned micro/nano fibers via electrospinning is its high sensitivity to variations in process parameters. To fully harness control over this fabrication technique, it is crucial to understand how these this fabrication technique, it is crucial to understand how these process parameters (predictors) influence both the micro and macro-outcomes (responses) of our process. Various experimental modeling techniques, such as design of experiments, correlation analysis, principal component analysis, regression, and other statistical and machine learning models, are generally applicable to design of the procession of the processi analysis, regression, and other sadastical and machine tenting models, are currently employed to develop predictor-response models for the properties of Electrospun fibrous structures at both the macro and micro scales [10-13].

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Supervised machine learning (ML) techniques, such as linear regression, decision trees, support vector machines, and neural networks, have been successfully integrated into the electrospinning fabrication process [13-16]. Pervez et al. used partial least squares (PLS) and support vector regression-based ML techniques to predict diameters of chitosan-based nanofibers with a high perdiction accuracy [14]. Sarma et al. used an ensemble of ML techniques such as gradient boosting (GB), XGboost (XGB), linear regression, and andom forest (RF) to determine crucial predictors such as feed, polymer concentration, and Flory-Huggins Chi parameter, and how they affect the polyvinylidene fluoride (PVDF) polymer fiber diameter [15]. Morphological parameters such as diameter and inter fiber separation as well as post-fabrication mechanical properties such as strain at break and ultimate tensile strength for polyvinyl alcohol (PVA) for seven different process parameters were modelled using artificial neural network (ANN) by Roldán et al. [17]. Their ML-based modelling approach showed high prediction accuracy and allowed the biomimetic vascular implant fabrication using PVA for their optimal manufacturing setup mined through their ML models [17]. Furthermore, ML techniques are also used to model post-fabrication application of. Insineed from the instance, Sujeeun et al. investigated the crucial in-vitro and physio-chemical data of Electrospun polymeric scaffolds applied to skin tissue engineering applications. For instance, Sujeeun et al. investigated the crucial in-vitro and physio-chemical data of Electrospun polymeric scaffolds applied to skin tissue engineering applications. It is possible to predict and interpret process parameters when that fiber and pore diameter were the most crucial physio-chemical apredictors of performance for the synthetic tissues [18]. Hence, ML has shown that it is possible to predict and interp

However, these techniques frequently encounter the bias-variance tradeoff, especially in complex model forms [19]. Therefore, selecting an appropriate model that can accurately fit training data with low bias and predict unknown data with low variance is of paramount importance for process modeling.

Another crucial challenge arises when complex machine learning models act as "Black Box" models, where there is no information available about cause-effect relationships based on physical mechanisms despite their high prediction accuracies [20]. This phenomenon is common in complex models such as neural networks, random forests, and various boosting techniques [21]. While simpler models such as regression and decision trees might not always match the prediction accuracy of more complex models, they offer a clear advantage in interpretability [22]. In manufacturing process improvement, it's not just about achieving high predictive accuracy; understanding the underlying relationships between predictor and response variables— essentially how the model derives its predictions— is equally crucial.

In this experiment, our goal was to utilize minimal data from the post-fabrication process to assess qualitative process variations that result in classifiable outcomes such as random/align fibers (from single jets) and multi-jet electrospinning situations. Furthermore, in our effort to fabricate highly aligned microfibers, we employed multiple classification and regression-based machine learning techniques to map process parameters to outcomes with high alignment coherency and density. Classification-based ML enabled us to identify sets of process parameters conducive to forming either aligned or random fibers from single jets and discerning scenarios of jet branching from singular electrospinning jets. For the classification problem, we employed Natve Bayes (NB), Support Vector Machines (SVM), K-Nearest Neighbors (KNN), Decision Trees (DT), and Random Forest (RF). For regression predictions on fibrous structure alignment coherency and inter-fiber distance, we used penalized linear regression models like Lasso and Ridge, Decision Trees, Random Forest Regressor, and Gradient Boosting (GB) ensemble techniques. Prior literature indicates that these techniques perform well with small datasets (< 100 data points) [15, 23, 24], unlike deep learning techniques, which achieve accurate predictions but require larger training datasets [15] Eleares et al. demonstrated the invaned of samely In this experiment, our goal was to utilize minimal data data points) [15, 23, 24], unlike deep learning techniques, which achieve accurate predictions but require larger training datasets [25]. Floares et al. demonstrated the impact of samper training datasets [25]. Floares et al. demonstrated the impact of samper technique. Their results showed that prediction accuracy reached a sample size < 100[26]. While these techniques have proven effective under limited data conditions, model training through augmented or synthetic data, using design of experiments (DOE)-based techniques and random noise addition, has been reported to mitigate the limitations associated with small data samples from experimental research [27, 28].

Our findings underscored a trade-off: while simpler models elucidated the relationship between predictors and responses, they sometimes compromised on prediction accuracy. Conversely, sophisticated ensemble models like Random Forest and Gradient Boosting excelled in accuracy. In this research, we melded the strengths of both easily interpretable models, shedding light on influential process

parameters, and more intricate techniques known for their parameters, and more intricate techniques known for their predictive prowess. The data-driven conclusions affirm that machine learning is adept at process classification and adeptly predicting unfamiliar data, especially when traditional linear models fall short. This suggests the potential of machine learning as an invaluable tool for in-process diagnostics, enabling real-time parameter adjustments grounded in live learning from accumulated data.

## 2. Materials and Method

## 2.1. Electrospinning System

2.1. Electrospinning System

The electrospinning process was carried out in the coresheath co-axial mode with the objective of producing tube-like fibrous structures. Poly-Caprolactone (PCL) with a molecular weight of 80,000, acquired from Sigma-Aldrich (St. Louis, MO), was prepared in a 12% (w/v) concentration by mixing it with Dichloromethane (DCM) obstained from VWR (Radnor, PA), Poly-ethylene-oxide (PEO) with a molecular weight of 300,000, also purchased from Sigma-Aldrich, was prepared in a 6% (w/v) solution by mixing it with DCM. The PCL-DCM solution was used as the sheath solution, such the PEO-DCM solution was used as the core solution in the co-axial electrospinning system. For our experiment, a robotic electrospinning system (Tongli-Tech, China) was utilized, as depicted in Figure 1. An in-house parallel plate collector with an adjustable plate gap was employed for collecting the fibrous structures. The co-axial setup utilized 2 foc one needles and 21 sheath needles. In this experiment, the core-to-sheath flow rate was maintained at a 12 ratio, with the combined volumetric flow rate indicating their bulk flow rate.

## 2.2. Design of Experiments and DOE-informed data

2.2. Design of Experiments and LVLT-informera unitagementation
In this experiment, we employed four predictor variables:
Voltage, Bulk Flow Rate, Needle to Collector Distance, and
Plate Gap. A rule of thumb is to use a training dataset that is 10
times larger than the total number of features for training [29-31]. These variables were utilized to predict fiber orientation,
alignment coherency, and inter-fiber distance. The design of experiments (DOE) followed a full factorial design [32] with
four factors, each having three levels. This setup resulted in a
total of 81 data points for analysis. The ranges of the operating
parameters for our design space are shown in Table 1:

Parameter	Lower Bound	Upper Bound
Voltage	10 KV	20 KV
Bulk Flowrate	3.5 ml/h	8 ml/h
Plate Gap	2 cm	6 cm
NC distance	10 cm	25 cm

Additionally, 30 additional design points were generated using the Box-Behnken design [33]. These points included six replicates of the center point and were designated for use as our test set data. Due to the imbalanced response from the initial DOE dataset, consisting of \$1 data points, we opted for design augmentation to address this issue by manually introducing additional parameter combinations within the existing design space. To rectify the imbalance, we gathered supplementary parameter configurations corresponding to Aligned, Jet branch, or Random fibers. The original full factorial design

table underwent augmentation to incorporate the necessary conditions for achieving a balanced response dataset for the classifiable jet instances. Therefore, a balanced dataset, including equal instances of aligned, random, and branching jet conditions (1:11-1 ratio), was established by sugmenting the design table. This involved adding 42 new operating combinations to the existing 81 data points, resulting in a total of 123 row data. The selection of these new operating conditions was done manually to ensure the occurrence of 41 instances each for aligned, random, or jet-branching fibers. Subsequently, the data points obtained from the DDE approach were fitted to a polynomial response-surface model (RSM). The resulting models demonstrated a high multiple-adjusted R-squared value (R≥ 0.95) and an insignificant lack of fit (P>0.10), indicating a robust fit to the augmented design table [34]. These models were then utilized to generate synthetic data using a DDE-informed data augmentation approach [35]. For the classification-type problems, synthetic data were generated based on normial logistic regression techniques based on predictor-response data obtained using DDE [36-38]. This served as training data for the proposed machine learning models. To expand the dataset, the original 123 rows were sampled based on the DDE-informed RSM model using a Monte Carlo deterministic sampling method [39]. This process yielded an approximate total of 1002 balanced synthetic data points with 334 cases for each class, which were employed for training machine learning techniques. table underwent augmentation to incorporate the necessary

2.3. Imaging Systems

The images were captured using an Olympus DSX series digital microscope and subsequently processed using Imagel [40] for getting numeric data about alignment observency (using Alignment) hugin) and inter fiber distance. The aligned and random fibers were determined based on their orientation on the collector (Figure 2e) and the Jet branching was determined based on the near-field imaging of the Taylor cone. It is to be mentioned that jet branching yielded fully chaotic instances of microfibers emanating from multiple jets that cannot be classified under random or aligned orientations, hence a separate classification.



The near-field Taylor cone images were captured using a Sigma 300 mm macro lens with a Nikon TC-201 2X teleconverter on a Nikon D3200 DSLR camera. Together with the teleconverter, macro lens, and the DSLR's 1,5x crop factor, a 900 mm equivalent 24.2 megapixels high resolution images

were obtained to distinguish between single, multiple, or no jet formation on the Taylor Cone. The images were used to label the original data set for the classification-type machine learning approach.

2.4. Machine Learning techniques

The machine learning problems of the classification type involved identifying process parameters that led to aligned fibers, random fiber formation, or jet branching from the Taylor Cone [41]. These phenomena were classified into three distinct outcomes for our analysis. To predict these qualitative outcomes for our analysis. To predict these qualitative outcomes, we employed classification models, annæly Naïve Bayes, K-Nearest Neighbor, Support Vector Classifier, and Decision Tree. The accuracy of the classification models was calculated based on the total number of true positives and negatives out of the overall observations in the predicted and test sets which forms the confusion matrix [42], as follows:

$$Accuracy = \frac{True\ Positive + Tru\ Negative}{Total\ Observations}$$
(1)

The naïve bayes classification method is based on the Bayes orem conditional probability that determines the conditional teome of event A given event B and is expressed by the lowing fem [42]. following form [43]:

$$P(A|B) = \frac{P(B|A)*P(A)}{P(B)}$$
 (2)

Local learners like the K-Nearest Neighbor classification Local learners like the K-Nearest Neighbor classification technique does not construct a specific model; instead, it employs the training data to predict the classification of unknown test data [44]. In this approach, the training set essentially serves as the prediction model [44]. The user specifies the number of neighbors (K) to be considered for classifying the unknown data. The algorithm then computes the Euclidean distance between the test point and neighboring training data, as described by the formula [45].

$$d = \sqrt{\sum_{i=1}^{k} (x_i - y_i)^2}$$
(3)

Here,  $(x_1-y_2)$  is the distance between the unknown point in the test dataset and the known point in the training dataset. For our KNN classification model, we used a wrapper function to tune the hyperparameters of the model based on a 10-fold cross validation approach by varying K from 1 to 1000 on the training data set [46].

The support vector machine (SVM) classifies responses by fitting an optimal hyperplane that best separates distinct responses [47]. The data points in the training set closest to this hyperplane, known as marginal points, are termed support vectors [48]. In SVM machine learning, the data are sometimes vectors [48]. In SVM machine learning, the data are sometimes not linearly separable. In such cases, the Kernel Trick [49] is applied, transforming the data into a higher-dimensional feature space where it can be linearly separable using an n-dimensional hyperplane [50]. The SVM commonly employs linear, polynomial, or radial kernel trick methods to aid classification [31]. The hyperparameters of linear SVM (cost function), polynomial SVM (cost function and degrees), and radial SVM (cost function and agamma) were tuned using a wrapper function based on 10-fold cross-validation. The values varied within the range  $22 \le Cost$  Function  $\le 28$ ,  $2 \le Degrees \le 8$ , and  $0.001 \le Gamma \le 10$ .

Decision trees split data points continuously based on similarities and differences in features (predictors) [52]. These trees are interpretable through nodes, sub-nodes, and leaves (end points) where data are classified based on separable features [53]. Random Forests and bagging are ensemble learning techniques [54] that enhance single decision tree outputs by averaging decisions from numerous trees, reducing overfitting in the training set. The decision tree was optimized using pruning [55], identifying the optimal complexity parameter (CP) [56] based on minimum error post-fitting, and using this optimal hyperparameter for refitting a new tree.

In regression problems, we began with simple multiple regression techniques, such as Lasso (least absolute shrinkage and selection operator) and Ridge regressions. Ridge regression, or 12 regularization, shrinks model coefficients close to zero based on their influence [57]. Lasso regression (L1 regularization) can set model coefficients to zero depending on their influence [58]. Both Ridge and Lasso regression on as a penalty function or shrinkage parameter (lambda) to shrink the model coefficients [59]. The model forms for Bidee and Lasso regressions are [60]: forms for Ridge and Lasso regressions are [60]

Ridge Regression Model: 
$$RSS + \alpha \sum_{j=1}^{p} \beta_{j}^{2}$$
 (4)  
Lasso Regression Model:  $RSS + \alpha \sum_{j=1}^{p} |\beta_{j}|$  (5)

Here, RSS is the residual sum of squares from an ordinary least square (OLS) fit, p= number of predictors,  $\beta$  = shrinkage or the penalty parameter. The optimal lambda was tuned using 10-fold cross validation for glmnet (version 4.1-8).

For the regression problem, the Decision Tree regressor was pruned using the optimal complexity parameter as in the classification type problem. The Gradient Boosting (GB) regressor uses error information from the prior trees to improve the model for n number of tree constructs [61]. The learning rate is a crucial parameter in this regard, and we tuned it with a range of learning rates from 10<sup>-10</sup> to 10<sup>10</sup> and extracted the best resquered value in the test set using a loop function.

The r-square values for the regression models were calculated as follows:

$$MSE = \frac{1}{n}\sum_{i=1}^{n}(y_i - \hat{y}_i)^2$$
(6)

$$Var(y) = \frac{1}{n-1} \sum_{i=1}^{n} (y_i - \bar{y})^2$$
 (7)  
 $R^2 = 1 - \frac{MSE}{Var(y)}$  (8)

Where, MSE = mean squared error, Var(y) = variance,  $y_i = actual response$ ,  $\hat{y}_i = predicted response$ ,  $\overline{y} = sample mean$ .

## 3. Results and Discussions

3.1. Microscopic and Neur-Field Images

The data concerning jet branching and single-jet electrospinning was documented during the fabrication process. The single or branched jetting methods produced either aligned fibers collected between two parallel plates or

random fibers gathered in the space between these plates. Figure 2 displays dark-field images captured with an Olympus DSX microscope from single or multiple jet systems, showcasing aligned and random. No fiber conditions (Figure 2e) occurred outside our design space depicted in Table 1. The inset in Figure 2 shows formation of tubular micro fibrous structure from the selected core: sheath configuration after washing away the PEO core in water. It is to be mentioned that jet branching yielded a full-chaotic scenario where end fiber could not be classified into either random or aligned, hence a fully different class was allotted to it. The Taylor cone near-field images are presented in Figure 3. The single-jet condition as depicted in Figure 3a and 3b both the single and branched-jet conditions resulted in aligned and random fiber orientations. It is to be mentioned that the no-fiber condition (Figure 2d) resulted from the no jet Taylor cone instance (Figure 2b) and did not appear in any experimental rum within our design space. Hence, the classification problems were mainly based on aligned, random, and jet-branching; no-fiber/ no-jet conditions were not present in our dataset. random fibers gathered in the space between these plates. were not present in our dataset.

### 3.2. Naïve Bayes (NB) Classifier

3.2. Naīwe Bayes (NB) Classifier

The Gaussian Naīwe Bayes classifiers compute the aposterior probabilities using Bayes' rule [62]. For each class, a probability distribution plot (Figure 4) is generated based on the predictors. Our model output plot shows that jet branching is more prominent (higher probability) for large voltages (>15 kV) and shorter distances (<18 km) with a moderate plate gap (4 cm) and combined flow rate (6 mL/h). Aligned fibers exhibit higher production probabilities for moderate voltage (~15 kV), moderate needle-collector distances (18 cm), and a moderate plate gap and flow rate, as depicted in Figure 4. Randomly formed fibers have a higher probability at lower voltage (<14 kV), shorter needle-collector distances (<16 cm), larger plate gaps (<5 cm), and lower flow rates (<6 mL/h). The Naïve Bayes classification achieved a high accuracy of 92% on our test set. Although the Naïve Bayes classification achieved (63), it has widely been used in many experimental modeling applications with high prediction accuracies (64-67). Also, in our application, the descriptive features, namely voltage, flow rate, plate gap, and needle-collector distance, cam be considered independent by the theory of probability (68) if:

$$P(X_i | X_2) = P(X_i)$$
 (9)  
 $P(X_i | X_2) = P(X_1) \times P(X_2)$  (10)

where, X<sub>i</sub> represents the probable value of the feature variables (such as voltage, distance, plate-gap, and needle-collector-distance) given the value of another feature variable (X<sub>j</sub>) apart from itself, it is notable that in our application, the value of one feature variable does not depend on the value set for another feature variable.

3.3. K-Nearest Neighbor (KNN) Classifler
In contrast, the KNN technique lacks interpretability like
the Naïve Bayes approach. When applied to the test data, the
KNN approach exhibited a lower classification accuracy
(53%). Therefore, directly predicting the test set using the KNN
method, based on the training set data, did not prove to be
useful for our specific multiclass dataset. The classic KNN
models suffer from such skewed training datasets and the

classifications is heavily dominated by the majority class classifications is heavily dominated by the majority class during the test-set predictions [69]. This was avoided in our case by balancing both the original data set and the augmented data set with an equal number of cases for the training data. Misclassification and sensitivity to outliers are major issues for non-optimal neighbor size selection in the KNN algorithm because it employs a distance-based prediction method [70-73]. Classification on the test set ignores the closeness between the data points and makes predictions based on the majority vote in the conventional KNN algorithm [73]. Furthermore, the curse of dimensionality is another common issue leading to low accuracy in the KNN algorithm, as it results in inefficient response predictions when the number of feature variables increases [74].

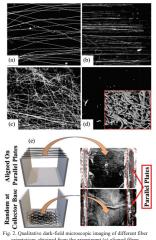


Fig. 2. Qualitative dark-field microscopic imaging of different there orientations obtained from the experiment (a) aligned fibres produced without jet branching (b) aligned fibres produced from jet branching (c) anodmoly oriented fibres (d) no fibres formed or collected between the parallel plates (c) Formation of aligned fibres between the parallel plates and andom fiber at the bottom of the collector. Inset on Figure(d) shows the SEM image of tubular micro fibrous structure formed.

## 3.4. Support Vector Machine (SVM) Classifier The SVM approach with a radial kernel (SVM-R) demonstrated the highest accuracy on the test set compared to the linear (SVM-L) or polynomial kernels (SVM-P), with an optimal cost function (= 4) and gamma (= 0.189). Therefore, for classifying multiclass objects such as in our case

(branching, aligned, and random), the radial kernel SVM is the preferable choice for building accurate models. Although

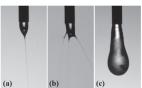


Figure x: Near-field Taylor-cone images for (a) Single Jet (Aligners) (b) Branched Jet (Aligned and Random Fibers) (c) No J (No Fiber).

obtaining interpretable models. Although obtaining interpretable model coefficients directly from an SVM model is not possible, we created visual phase plots for the aligned, random, and branching jet cases by plotting the predictors NC-distance, plate gap, and flowrate against the predictor voltage. In each of the two parameter selections, the other two were set at their midpoint values, i.e., NC-distance = 17.5, Flowrate = 6 m.L/h, and Plate Gap = 4.5 cm. These plots were constructed using the radial kernel with the optimal hyperparameter values

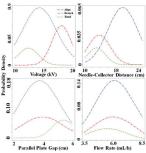


Fig. 4. The probability distribution of the predictors using the Gaussian Naïve-Baves classifier.

that yielded the best results in our study. In Figure 5, the flowrate vs voltage plot shows that for 16 < voltage < 20 kV for flowrates between 4 to 8 ml/h draws the boundary between the formation of Jet branching and Single jets (yielding aligned or random fibers). A narrow region where random fibers were generated was observed between the jet branching and aligned fiber formation zones. The NC-distance vs. voltage plot indicated that when the plate gap was 4 cm and flowrate was 6

mL/h, NC-distance < 12 resulted in random fibers for voltages < 14 kV. Additionally, random fibers were observed for plate gaps larger than 5 cm and voltages < 15 kV, as shown in the plate gap vs voltage plot in Figure 5.

3.5. Decision-Tree (DT) and Random Forest (RF) Classifiers
The optimal decision tree, with the appropriate hyperparameters, is depicted in Figure 6. The first split is based on whether the ne-distance is smaller or larger than 18 cm. It is observed that jet branching primarily occurs when the voltage is > 17 kV, especially for needle-collector distances < 18 cm, and when the voltage surpasses 19 kV for needle-collector distances less than 21 cm. Therefore, both voltage and needle-collector distance emerged as crucial indicators of jet branching phenomena, as revealed by the decision tree analysis. Moreover, the distinction between random and aligned fiber formation seems to be influenced by the needle-collector distance and plate gap when the voltage is < 16 kV. The tree classifies that for a large plate gap (> 5 cm) and a nedistance < 18 cm, random fibers are formed. The optimal decision tree exhibited an 89% prediction accuracy on the test data. This accuracy was further improved through the application of Random Forest, an ensemble technique that utilizes bootstrap aggregation [75] to combine outcomes from nultiple trees based on majority voting or averaging in classification problems [76]. 3.5. Decision-Tree (DT) and Random Forest (RF) Classifiers

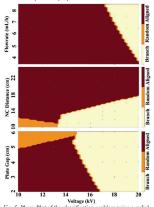


Fig. 5. Phase-Plot of the cla Plot of the classification problem using nel support vector machine (SVM).

Despite the high prediction accuracy offered by the Random orest model, it lacks interpretability and operates as a "Black

The formation of random, aligned, or jet branching phenomena using various classification-type machine learning model for our microfiber dataset has been tabulated in Table 2. It is observed that Naïve Bayes, Support Vector machines with Linear, and radial kernels showed prediction accuracies > 90% for our interpretable models. Ensemble techniques like RF also showed high prediction accuracies, although no efforts were made in the current experiment to decipher the black-box ensemble technique.

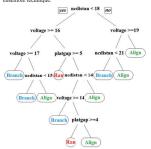


Fig. 6. Decision Tree Classification Aligned, Branch, and Ran (Random) Fiber based on different process parameters. Ran = Random Fiber

able 2. Classification Machine Learning Summary			
Technique	Additional Parameter information	Prediction Accuracy	
NB	Null*	94%	
KNN	Tuned Neighbour Size (k =12)	53%	
SVM-L	Linear Kernal	94%	
SVM-P	Polynomial Kernal	74%	
SVM-R	Radial Kernal	97%	
DT	Pruned (CP = 0.01)	93%	
RF	N = 500 Decision Trees	98%	

3.6. Pearson Correlation for collinearity determination
The Pearson Correlation Coefficient (r) indicates the linear
correlation between two variables. In regression-based
machine learning techniques, it provides insights into choosing
uitable models (either linear or non-linear fitting) for a given
dataset. Figure 7 displays the Pearson Correlation matrix. It is dataset. Figure 7 displays the Pearson Correlation matrix. It is noticeable that Alignment Coherency (Align) exhibits a significant positive correlation with ne-distance (named 'Dist' in Figure 7) and voltage. It also shows a significant negative correlation with the plate gap (P.Gap). Additionally, the interflered distance (Fib.D) displays a notable negative correlation with bulk flowrate (Flow). Consequently, we employed both linear machine learning models such as Lasso and Ridge regression, as well as non-linear model fits like Random Forest

Box" model, providing limited insight into the underlying factors influencing the outcomes. (RF) and Gradient Boosting. The proper choice of linear versus non-linear regressor machine learning models are crucial for (Ar) and tradient Boosting. The proper clothe of linear versus non-linear regressor machine learning models are crucial for numerical data as it may lead to higher or lower prediction accuracies of numerical data based on the chosen model type.

## Ridge & LASSO regressor

3.7. Ridge & LASSO regressor

Table 3 provides a summary of the intercept and predictor coefficients for the linear machine learning techniques (Ridge and Lasso) applied to our alignment coherency data, the ridge and Lasso) applied to our alignment coherency data, the ridge regression model coefficients exhibit smaller values compared to those of the inter-fiber distance. The plate gap exerts the most significant influence on alignment coherency, displaying an inverse relationship. Hence, within the tested plate gap range (2 - 6 cm), smaller plate gaps lead to better alignment coherency. Turthermore, bulk flowrate has the least impact on the alignment model, as indicated by the ridge regression coefficient. The optimal penalty lambda ('Optim Lambda' in Table 3) sets the bulk flowrate to the least impact on the alignment coherency lasso model. In contrast, for the inter-fiber distance model, the bulk flowrate has the most significant effect. With an increase in flowrate, the bulk volume of formed fibers rises, subsequently reducing the inter-fiber distance due to higher fiber density. Both the Ridge and Lasso regression models for the alignment coherency data exhibit high R' yalues (~81%), whereas those for the inter-fiber distance show only 55%. This discrepancy can be attributed to the non-linear relationship between the predictors and the inter-fiber distance, as demonstrated in the Pearson correlation matrix in Figure 7.

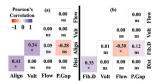


Fig. 7. Pearson's Correlation Table for (a) alignment coherency (%) (Align) and (b) Inter-Fiber Distance (Fib.D) in relation to the different predictors.

# 3.8. Decision Tree and Random Forest (RF) regressor Given the non-linear relationship between the predictors and the response variables, we turned to employing non-linear machine learning models, such as decision trees. The decision tree, optimized with the appropriate CP, achieved R' values of T\(^{1}\) and 64\% on the training set data. The decision tree regressor resulted in intricate tree structures, as illustrated in Figure 8.

In our regression-type problems, single decision trees didn't perform well on our test data, despite fitting the training data very effectively. Decision trees exhibit this bias-variance trade-off issue in regression problems, displaying low bias in the training set but resulting in higher variance in test sets. To enhance the efficiency of our regression model, we opted for Random Forest (RF) with  $n=1000.\,$  Subsequently, it

emonstrated slightly improved R<sup>2</sup> values for both the lignment coherency and inter-fiber distance data, as indicated

Predictor	Ridge (alignment coherency)	Lasso (alignment coherency)	Ridge (inter fiber)	Lasso (inter fiber)
Optm Lambda	0.0041	0.0003	1.84	0.081
(Intercept)	0.3865	0.4191	152.285	126.552
Bulk Flowrate	0.0024	X	-10.4783	-32.4854
Plate Gap	-0.0332	-0.0312	5.6418	12.254
NC Distance	0.01114	0.0107	1.3911	3.9987
V/-14	0.01644	0.0152	6 2760	16 2154

voltage 0.01644 0.0153 6.2760 16.2154

3.9. Gradient Boost (GB) regressor

To enhance our prediction accuracy using decision tree variants, we turned to an ensemble method, Gradient Boosting.
This approach constructs the next best model by combining previous models, aiming to minimize prediction errors.
Boosting not only decreases model bias but also enhances generalization for predicting unknown datasets, exhibiting lower variance when compared to methods like RF and other ensemble techniques. The key lies in determining an optimal learning rate that prevents the model from overfitting the training data. In our model, we optimized the learning rate using a looped function, varying the rate from 10% to 1, and minimizing the RF on the test set for each iteration. The optimized Gradient Boosting models achieved high RF values (~80%) for both the alignment and inter-fiber distance test datasets.

The figure displaying the relative influence of predictors in reducing the mean square error (MSE) in the training dataset for the Gradient Boosting (GB) model is presented in Figure 9. The relative influence assigns standardized numeric values on a scale of 1-100 to each of the predictors such that their cumulative equals to 100 [77]. Predictors that are more crucial in reducing the MSE in the training models are assigned a higher relative influence over others [77]. Pleat Gap (PCapp) and needle-to-collector distance (Dist) appeared to exert the most significant influence on the alignment coherency and inter-fiber distance models, as depicted in Figure 9a and 9b, respectively. Therefore, for our regression analysis, the ensemble method using Gradient Boosting demonstrated the most accurate predictions on the test set. Figures 9c and 9d illustrate the comparison between actual and predicted data for the GB model in alignment coherency and inter-fiber distance, respectively. respectively

Table 3 includes a summary of the machine learning models utilized, along with their corresponding  $\mathbb{R}^2$  values and parameter optimization details. While linear repression models offered interpretability, their predictive accuracy was limited due to the nonlinear correlation between predictors and responses. The Decision Tree technique exhibited low bias, resulting in a good training set  $\mathbb{R}^2$ , but suffered from high variance, leading to a poor test set  $\mathbb{R}^2$ . To enhance the biasvariance trade-off [78], the incorporation of ensemble techniques, such as gradient boosting, improved test set accuracy, albeit at the expense of reduced model interpretability.

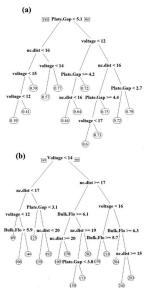


Fig. 8. Pruned Decision Trees for (a) Alignment Coherency (b) Inter Fiber distance

In the current project, we examined only two continuous response variables using four process parameters as predictors. Other factors, such as solution and fluidic properties of the core/sheath materials, relative humidity, and environmental temperature, were not included in the modeling process. Additionally, many other essential macro and micro parameters, including fiber diameter, ross-sectional hollow portion for microtubular structures, and fiber surface pore composition, have not been modeled using machine learning approaches.

3.10. Discussion and Future Scope

The present paper delves into the applications of interpretable machine learning techniques for the classification and regression modeling of the electrospinning technique. While black-box models such as Neural Networks, Long-

Short-Term Memory (LSTM), and recurrent neural networks (RNN), etc. may offer more accurate predictions, relying solely on these models does not inherently provide an explanation of how the predictions are made. Nowadays, various model-agnostic interpretability techniques are employed to unveil the workings of these black-box techniques, aiming to combine high accuracy with model interpretability. Partial dependency (PD) plots serve as an example of such techniques, where individual predictors are perturbed to observe their effects on the response variable [79]. However, PD plots assume independence among inputs [80], may generate unrealistic scenarios through predictor perturbation [81], and fail to consider interactions between predictor variables. Similar to PD plots, individual conditional expectations (ICE) plots decode black-box models based on data perturbations [82]. While PD plots aim to average the effect of a feature across the entire dataset, ICE plots analyze the effect of a single feature on one observation [83]. Shapley values represent a refinement over PD plots, incorporating feature interactions and avoiding unrealistic predictor settings to provide a more realistic Short-Term Memory (LSTM), and recurrent neural networks over Phylots, incorporating feature interactions and avoiding unrealistic predictor settings to provide a more realistic protrayal of black-box models [84]. Local interpretable model-agnostic explanations (LIME) offer another approach to interpreting black-box models by providing local interpretations using surrogate models but have been also been assented in the models (GLM) and LASSO [85]. Hence, the surrogate models elucidate the black-box model within the local region. Tree-based surrogate models so and accision trees, are also utilized to interpret black-box models by identifying feature importance through node splitting [86]. In the future, our objective is to develop models based on artificial neural networks (ANN) and provide interpretability for these constructed models using model-agnostic interpretation techniques.

Table 4. Regression Machine Learning Summary

	Technique	Parameter info	Alignment R <sup>2</sup>	Fiber Dist R <sup>2</sup>
	RIDGE	Tuned Lambda	81%	55%
	LASSO	Tuned Lambda	80%	59%
	DT	Pruned (CP = 0.001)	71%	64%
	RF	nTrees = 1000	76%	74%
- 2	GB	(lambda = 0.67)	81%	82%

GB (lambda -0.67) 81% 82%.

In future investigations, we intend to employ a more comprehensive set of predictors to forecast the outcomes of the electrospinning process across a wider range of response parameters. The experiments will include more categorical measures based on the jetting and fiber collection methods as well as numeric measures for regression modelling. We also intend to use deep-learning techniques with larger datasets on top of the existing machine learning techniques. The deep learning techniques will be used with the model-agnostic interpretability techniques to combine high prediction accuracies with model interpretability that will ensure proper and educated use of black box machine learning models. Additionally, we plan to utilize an in-situ process monitoring system to gather qualitative process information related to the electrospinning et, including parameters like whipping length, electrospinning jet, including parameters like whipping length branching distance, and the number of whips. This data will enable us to create a more accurate model for predicting the enane us to create a more accurate model for predicting the final fibrous structure outcome. The goal of using fibrous micro-tubular structure in future experiments will be to aid in nutrient and oxygen transport to and removal of waste and biochemical byproducts from tissue culture in 3D micro-environments in hydrogel scaffolds.

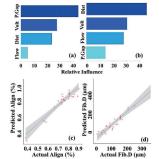


Fig. 9. The relative influence plots obtained from the gradien osting random forest for (a) alignment coherency (%) and (b) inter fiber distance (μm). Actual vs predicted plots for the (c) alignment coherency (%) and (d) inter fiber distance (μm) from the gradient boosting decision tree regression.

4. Conclusion

In this study, we leveraged ML techniques to model both categorical and numerical responses in electroopinning, based on diverse predictors. The work emphasized the use of traditional machine learning techniques that combine the advantages of good prediction accuracy, interpretability, and training on limited experimental data. Classification algorithms, including Naive Bayes, Support Vector Classifier, and Random Forest, showcased remarkable accuracy in classifying electrospinning outcomes such as aligned fibers, random fiber formations (both emanating from single jets), and jet branching within the test dataset. Gaussian Naive Bayes revealed that high voltage and shorter needle-collector distances predominantly instigated jet branching. Concurrently, larger plate gaps were pinpointed by the Naïve Bayes method as key determinants for random fiber formation. The Support Vector Classifier, utilizing an optimally tuned radial kernel, emerged as the most adept model for classification tasks. Its qualitative insights aligned with those from Naïve Bayes, emphasizing larger plate gaps and shorter spinning distances as pivotal for generating random fibrous structures. Decision tree models highlighted voltage values exceeding 17 kV as essential indicators for jet branch formation.

In terms of regression, Ridge and Lasso models indicated a

In terms of regression, Ridge and Lasso models indicated a direct relationship between needle-collector distance and voltage with alignment coherency, while an invertediationship was observed with the plate gap. Conversely, bulk flow rate inversely correlated with inter-fiber distance. Linear models effectively captured alignment coherency data, showcasing strong linear correlations with predictors via the

Pearson Correlation. However, predictions for inter-fiber distance were suboptimal due to inherent non-linearities. Incorporating non-linear regressors, such as the Decision Tree Regressor, led to a modest enhancement in predictive performance. Remarkably, ensemble methods like Random Forest and Gradient Boosting consistently delivered the highest prediction accuracies across both classification and regression tasks. This research accortunates the efficacy of ML in accurately classifying and predicting outcomes in electrospinning micro-fibrous structures. Looking ahead, we aim to integrate ML with in-situ process monitoring, enabling real-time data acquisition for continuous training and optimization of the fabrication process.

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