

Quasipositive links and Stein surfaces

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We study the generalization of quasipositive links from the 3-sphere to arbitrary closed, orientable 3-manifolds. Our main result shows that the boundary of any smooth, properly embedded complex curve in a Stein domain is a quasipositive link. This generalizes a result due to Boileau and Orevkov, and it provides the first half of a topological characterization of links in 3-manifolds which bound complex curves in a Stein filling. Our arguments replace pseudoholomorphic curve techniques with a study of characteristic and open book foliations on surfaces in 3- and 4-manifolds.

57R17; 57M25, 32Q28

1 Introduction

The tradition of studying complex varieties in \mathbb{C}^n via their intersection with smooth hypersurfaces has played a motivating role in knot theory almost since its inception. For $n = 2$, the study of braids has been tied especially tightly to this line of inquiry. In [30], Rudolph introduced the notion of quasipositive braids and links in S^3 and showed that each such link arises as the transverse intersection of the unit sphere $S^3 \subset \mathbb{C}^2$ with a smooth algebraic curve $f^{-1}(0) \subset \mathbb{C}^2$, where f is a non-constant polynomial. More generally, Rudolph conjectured that any link in S^3 arising as the transverse intersection between a smooth complex curve and the unit sphere in \mathbb{C}^2 is quasipositive. This was confirmed by Boileau and Orevkov in [7], whose proof uses Gromov’s celebrated theory of pseudoholomorphic curves.

Many of these ingredients have natural analogs when \mathbb{C}^2 is replaced with an arbitrary Stein surface, a complex surface X that admits a proper holomorphic embedding as a closed subset in some \mathbb{C}^n . In this setting, the role of the unit 3-sphere in \mathbb{C}^2 is played by a hypersurface $Y \subset X$ of constant radius in \mathbb{C}^n . The region in X bounded by Y is a *Stein domain*. Any such level set Y in X has a natural contact structure ξ given by complex tangent lines, and we can define *quasipositive* braids and links with respect to open book decompositions of Y compatible with ξ ; see Section 2. Our main theorem says that the analog of Rudolph’s conjecture also holds in this setting.

Theorem 1.1 *The boundary of any smooth, properly embedded complex curve in a Stein domain is a quasipositive link.*

In particular, we show that any such link is transversely isotopic to the closure of a quasipositive braid with respect to an open book whose monodromy is a product of positive Dehn twists along homologically nontrivial simple closed curves; motivated by analogous terminology for Lefschetz fibrations, we call this a *positive allowable* open book. In contrast with [7], our argument entirely avoids Gromov’s theory of pseudoholomorphic curves and any results about positivity of intersections between such curves [26, 25]. Instead, we study complex curves in Stein surfaces via their *characteristic foliations* (described precisely in Definition 4.9). We reduce this to a study of (possibly singular) surfaces in 3-manifolds, where we prove new results relating characteristic and open book foliations; see Theorems 1.3 and 1.4 below.

We also prove a partial converse to Theorem 1.1.

Theorem 1.2 *If $K \subset Y$ is the closure of a quasipositive braid with respect to a positive allowable open book, then K bounds a properly embedded symplectic surface in a Stein filling of Y .*

This offers evidence for a stronger converse to Theorem 1.1: a symplectic surface can always be made pseudoholomorphic by a deformation of the ambient almost-complex structure compatible with the natural symplectic structure on X , though it is unclear whether or not this can be accomplished through a deformation of the Stein structure itself. In the case where ∂X admits a planar open book decomposition, Hedden has shown in [20] that quasipositivity is also a sufficient condition for a braid to bound a complex curve. In a different direction, we point out that the relative version of the symplectic Thom conjecture implies that the surfaces constructed in the proof of Theorem 1.2 are genus-minimizing in their relative homology classes; see [16].

A few words on our notions of quasipositivity are in order. By a classical theorem of Alexander, every closed, orientable 3-manifold admits an open book decomposition. Any link that is braided with respect to this open book can be represented in terms of a *pointed monodromy* of a page of the open book decorated with marked points. We define quasipositive braids for any open book in terms of certain generators of the pointed mapping class group of the page. Moreover, given a closed, orientable contact 3-manifold (Y, ξ) , we say that a transverse (resp. smooth) link type K is *quasipositive* if there is an open book decomposition of Y supporting ξ in which K is transversely (resp. smoothly) isotopic to a quasipositive braid. As evidenced by Theorems 1.1 and 1.2, such links exhibit close connections to complex and symplectic structures.

We also study the natural generalization of strongly quasipositive links, a special class of nullhomologous quasipositive links. These links bound symplectic surfaces in a compact piece of the symplectization of (Y, ξ) , and these surfaces are in fact isotopic to Seifert surfaces in Y . When (Y, ξ) is tight, these Seifert surfaces can be used to show that the Eliashberg-Bennequin inequality is sharp for all strongly quasipositive links. These same ideas can be used to generalize a result of Rudolph's [32]: the only strongly quasipositive knot in a symplectically fillable contact 3-manifold that bounds a smooth, properly embedded “slice” disk in a symplectic filling is the unknot.

As mentioned above, a key step of our proof of Theorem 1.1 involves relating quasipositivity to properties of characteristic foliations on surfaces. These results are framed in terms of Morse functions on surfaces. Following [8, §9.3], we say that a vector field v on a surface S is *weakly gradient-like* for a function $f : S \rightarrow \mathbb{R}$ if the zeroes of v coincide with the critical points of f and $df(v) > 0$ outside the zeroes of v . By extension, we say that a characteristic or open book foliation on S is *weakly gradient-like* for $f : S \rightarrow \mathbb{R}$ if it is directed by a vector field that is weakly gradient-like for f .

Theorem 1.3 *Let (Y, ξ) be a contact 3-manifold containing transverse links K_0 and K_1 that cobound an embedded surface $S \subset Y$, oriented so that $\partial S = K_1 \cup -K_0$. If K_0 is transversely isotopic to a quasipositive braid with respect to a compatible open book (B, π) and the characteristic foliation on S contains only positive singular points and is weakly gradient-like for a Morse function on S , then K_1 is also transversely isotopic to a quasipositive braid with respect to the same open book.*

To prove Theorem 1.3, we strengthen the known relationship between characteristic foliations and open book foliations on surfaces in 3-manifolds. The result below can be viewed as a partial converse to [23, Theorem 2.21].

Theorem 1.4 *Let (Y, ξ) be a contact 3-manifold with compatible open book (B, π) , and suppose that $S \subset Y$ is an embedded surface whose characteristic foliation is weakly gradient-like with respect to a Morse function $f : S \rightarrow \mathbb{R}$. After an isotopy of (B, π) through open books supporting ξ , the open book foliation on S may be assumed to be weakly gradient-like with respect to f near all of its critical level sets.*

Moreover, the isotopy of (B, π) is induced by an ambient isotopy that preserves ξ outside an arbitrarily small neighborhood of each singular point of the characteristic foliation on S .

In fact, we show that Theorems 1.3 and 1.4 hold not only for embedded surfaces $S \subset Y$ but for certain well-behaved singular surfaces. This will play a key role in our study of characteristic foliations on surfaces in 4-manifolds in Section 4.

Remark 1.5 After completing an early draft of this work, the author learned ([21] and [11]) that some of the above results have also been obtained in work-in-progress by a collaboration between Inanc Baykur, John Etnyre, Matt Hedden, Keiko Kawamuro, and Jeremy Van Horn-Morris. By different means, they prove Theorem 1.1 for subcritical Stein fillings of $\#^k(S^1 \times S^2)$, viewed with a planar open book, as well as the same general results concerning quasipositive representatives of strongly quasipositive links in arbitrary open books and Theorem 1.2. See [24] for other recent work on strongly quasipositive braids in arbitrary open books.

Organization We begin by defining quasipositive links in 3-manifolds in Section 2. The precise definition appears in Section 2.3, preceded by an extensive discussion of the framework of pointed open books we use to describe braids in arbitrary open books in Sections 2.1-2.2. In Section 3, we discuss characteristic and open book foliations and prove Theorems 1.3 and 1.4. Our study of Stein surfaces begins in Section 4, where we obtain Theorem 1.1 as a consequence of stronger results for a class of surfaces that generalize complex curves; see Theorems 4.2-4.4. We close with the proof of Theorem 1.2 in Section 5.

Conventions All manifolds and maps between manifolds are assumed to be smooth unless stated otherwise. Given an oriented manifold (or submanifold) with boundary, all boundary components are oriented using the “outward normal first” convention unless otherwise specified.

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2 Quasipositive links in three-manifolds

In this section, we generalize the notion of quasipositivity to braids in arbitrary open books; see [2, 24] for related definitions. Our definitions are framed in the language of pointed open books introduced in [1]; we review and expand on this framework in Section 2.2. Throughout this paper, we assume a familiarity with open book decompositions and contact geometry at the level of [10]. For later reference, we collect a few of these ideas in Section 2.1.

2.1 Open book decompositions and contact structures

Recall that an open book decomposition of a 3-manifold Y is a pair (B, π) , where B is an oriented, fibered link in Y and $\pi : Y \setminus B \rightarrow S^1$ is a fibration. Moreover, we require that the closure F_θ of each fiber $\pi^{-1}(\theta)$ in Y is a Seifert surface for B . The link B is called the *binding* of the open book, and the Seifert surfaces F_θ are the *pages* of the open book.

We can also describe an open book decomposition abstractly using a pair (F, φ) , where F is a compact surface homeomorphic to a page and φ is a diffeomorphism of F that fixes its boundary and encodes the monodromy of the fibration. In particular, this defines a closed 3-manifold $Y_{(F, \varphi)} = (F \times I)/\sim_\varphi$ where the relation is defined by

- (1) $(x, 1) \sim_\varphi (\varphi(x), 0), \quad x \in F$
- (2) $(x, t) \sim_\varphi (x, s), \quad x \in \partial F, \quad t, s \in I.$

We say that (F, φ) corresponds to an open book decomposition (B, π) of a 3-manifold Y if there is a diffeomorphism $Y_{(F, \varphi)} \rightarrow Y$ that pulls π back to the natural fibration from $Y_{(F, \varphi)} \setminus \partial F$ to S^1 .

An open book decomposition of a contact 3-manifold (Y, ξ) is said to be *compatible* with the contact structure if ξ has a contact 1-form α such that $d\alpha$ is an area form on each page and α is positive along the binding. This definition is motivated by a construction of Thurston-Winkelnkemper [34] that associates a contact structure to each open book decomposition of a 3-manifold. Celebrated work of Giroux [18] extends this to a one-to-one correspondence between open books (up to positive Hopf stabilization) and contact structures (up to isotopy) on a 3-manifold.

2.2 Transverse links, braids, and pointed open books.

A link in a contact 3-manifold (Y, ξ) is called *transverse* if it is everywhere transverse to ξ and *Legendrian* if it is everywhere tangent to ξ . All contact structures in this paper will be assumed to be co-oriented, and all oriented transverse links will be assumed to intersect the contact planes positively unless otherwise specified.

Given an open book decomposition on Y , an oriented link is said to be *braided* if it is positively transverse to the pages of the open book. In the case where the open book decomposition is compatible with the contact structure, any braid is naturally braid isotopic to a transverse link. The “transverse Alexander theorem” asserts the converse. The general form of the theorem was proven by Pavelescu, generalizing an earlier result due to Bennequin for links in the 3-sphere; see [29] and [3], respectively.

Theorem 2.1 (Pavelescu) *Given any compatible open book decomposition of a contact 3-manifold (Y, ξ) , every transverse link is transversely isotopic to a braid.*

Remark 2.2 As discussed in [29], Theorem 2.1 holds more generally for oriented arcs ℓ in Y that are positively transverse to ξ and positively braided near their endpoints. Moreover, combining the proof of [29, Theorem 3.2] with the “Bennequin trick” as articulated in [6, Lemmas 1-2], we see that any such arc ℓ within a transverse link K may be braided via a contact isotopy that fixes $K \setminus \ell$.

The classical operations of Markov stabilization and destabilization have analogs for braids in an arbitrary open book; these will be defined precisely below. The following theorem generalizes work of Wrinkle [36] and Orevkov-Shevchishin [28].

Theorem 2.3 (Pavelescu) *Given any compatible open book decomposition of a contact 3-manifold (Y, ξ) , two transverse braids are transversely isotopic if and only if they have a common positive stabilization.*

Following [1], we can encode braids abstractly using *pointed open book decompositions*. In particular, let (F, φ) be an abstract open book corresponding to (B, π) and let $P = \{p_1, \dots, p_n\}$ be a set of distinct marked points in the interior of F . The monodromy φ is isotopic to a diffeomorphism $\widehat{\varphi}$ of F that fixes the marked points setwise and ∂F pointwise, ie a diffeomorphism of the pair (F, P) fixing ∂F . The link in $Y_{(F, \widehat{\varphi})}$ given by $(P \times I)/\sim_{\widehat{\varphi}}$ corresponds to a link K in Y that is braided with respect to (B, π) . We say that K is *encoded* by the pointed open book decomposition $(F, P, \widehat{\varphi})$, and we refer to $\widehat{\varphi}$ as the *pointed monodromy*. Unless otherwise specified, isotopy of the pointed monodromy will be through diffeomorphisms that fix both P and ∂F pointwise. An extension of the argument from [17, §4.4.2] shows that any braid K in (B, π) is encoded by an abstract open book.

The pointed mapping class group of F is generated by Dehn twists about simple closed curves and half-twists along embedded arcs joining distinct marked points; see Figure 1 for local depictions of these twists. We will let D_γ denote a positive Dehn twist about a curve γ and H_α denote a positive half-twist about an arc α , respectively. For later reference, we highlight the behavior of these twists under conjugation:

Lemma 2.4 (cf [13, Fact 3.7]) *Let φ be any diffeomorphism of a surface F .*

- (a) *For any simple closed curve γ in F , we have $\varphi \circ D_\gamma \circ \varphi^{-1} = D_{\varphi(\gamma)}$.*
- (b) *For any embedded arc α in the interior of F , we have $\varphi \circ H_\alpha \circ \varphi^{-1} = H_{\varphi(\alpha)}$.*

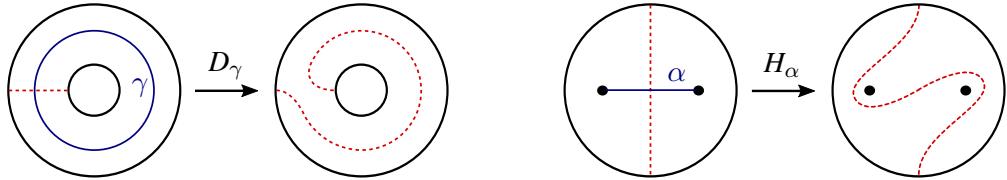


Figure 1: A positive Dehn twist (left) and a positive half-twist (right).

We also reserve the notation P_δ for the ‘‘point-pushing’’ map along a simple closed curve δ through a marked point; as shown in Figure 2, P_δ can be expressed as a product of oppositely-signed Dehn twists along curves parallel to δ . The behavior of point-pushing maps under conjugation is analogous to that of Dehn twists and half-twists.

The next lemma characterizes braid isotopy in terms of abstract pointed open books.

Lemma 2.5 *Suppose $(F, P, \hat{\varphi})$ and $(F, P', \hat{\varphi}')$ are two pointed open books encoding a pair of braids K and K' in the same open book (B, π) , where P and P' are sets of n marked points. The braids K and K' are braid isotopic if and only if $\hat{\varphi}'$ is isotopic to $h \circ \hat{\varphi} \circ h^{-1}$ for a diffeomorphism h of F that sends P to P' and is the identity near ∂F .*

Proof Recall from above that the pairs (Y, K) and (Y, K') are obtained from the mapping tori of $\hat{\varphi} \in \text{Diff}(F, P)$ and $\hat{\varphi}' \in \text{Diff}(F, P')$ by the quotient defined in (2) — that is, by filling in the binding. Moreover, each fiber in the mapping torus corresponds to a page of the open book. Observe that a braid isotopy carrying K to K' extends to an ambient isotopy of Y that preserves each page of the open book and is the identity on a tubular neighborhood of the binding B . If we remove the neighborhood of B , this page-preserving isotopy induces a fiber-preserving diffeomorphism between the mapping tori of $\hat{\varphi} \in \text{Diff}(F, P)$ and $\hat{\varphi}' \in \text{Diff}(F, P')$. Any such map lifts to a diffeomorphism f of $F \times [0, 1]$ of the form $(x, t) \mapsto (f_t(x), t)$ for a smooth family

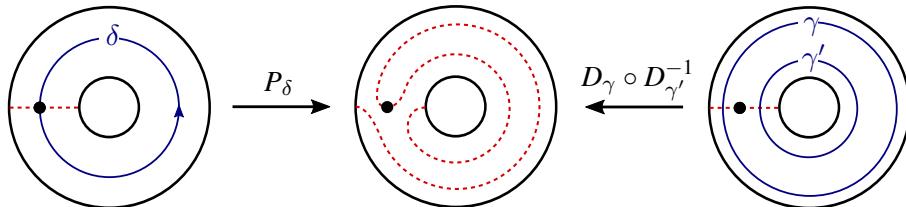


Figure 2: Expressing a point-pushing map as a product of Dehn twists.

$f_t \in \text{Diff}(F)$. Moreover, because the braids in the mapping tori induced by P and P' (ie K and K') are exchanged by the diffeomorphism, we have $f_t(P) = P'$ for all t .

In order to descend to the mapping torus of $\widehat{\varphi}$, f must satisfy $f(x, 1) = f(\widehat{\varphi}(x), 0)$, ie $(f_1(x), 1) = (f_0(\widehat{\varphi}(x)), 0)$, for all $x \in F$. Similarly, since $(f_1(x), 1)$ is identified with $(\widehat{\varphi}'(f_1(x)), 0)$ in the mapping torus of $\widehat{\varphi}'$, we must have $\widehat{\varphi}' \circ f_1 = f_0 \circ \widehat{\varphi}$, ie $\widehat{\varphi}' = f_0 \circ \widehat{\varphi} \circ f_1^{-1}$. Now define $\widehat{\varphi}'_t = \widehat{\varphi}' \circ (f_1 \circ f_{1-t}^{-1})$. Then $\widehat{\varphi}'_t$ is an isotopy between $\widehat{\varphi}'_0 = \widehat{\varphi}'$ and $\widehat{\varphi}'_1 = f_0 \circ \widehat{\varphi} \circ f_0^{-1}$. Moreover, since $f_t(P) = P'$ for all t , we have $\widehat{\varphi}'_t \in \text{Diff}(F, P')$ for all t . This shows that $\widehat{\varphi}'$ is isotopic in $\text{Diff}(F, P')$ to a conjugate of $\widehat{\varphi}$, where the conjugating diffeomorphism carries P to P' . \square

We can also describe braid (de)stabilization in terms of abstract pointed open books: Let p_{n+1} be a point in a collar neighborhood of ∂F on which $\widehat{\varphi}$ is the identity and let α be an arc joining p_{n+1} to p_n (and meeting no other marked points). We say that the pointed open book $(F, P \cup \{p_{n+1}\}, H_\alpha \circ \widehat{\varphi})$ is a *positive Markov stabilization* of the original pointed open book. If K and K' in Y are the corresponding braids with respect to the open book (B, π) , then K' is obtained from K by positive braid stabilization in the same sense defined by Pavelescu as referenced in Theorem 2.3. Negative stabilizations and positive and negative destabilizations are defined similarly and also agree with the corresponding notions defined by Pavelescu.

The next lemma relates stabilization and the addition of half-twists.

Lemma 2.6 *Suppose the braid K_1 is obtained from the braid K_0 by adding a half-twist. If K_0^+ is a positive Markov stabilization of K_0 , then K_1 has a positive Markov stabilization K_1^+ that is obtained from K_0^+ by adding a half-twist of the same sign.*

Proof Without loss of generality, we assume the half-twist is positive. Write the pointed monodromy for K_0 as $\widehat{\varphi}_0$ and the monodromy for K_1 as $\widehat{\varphi}_1 = H_\alpha \circ \widehat{\varphi}_0$, where H_α is the added half-twist. If K_0^+ is obtained from K_0 by braid isotopy and a single positive stabilization, then it is encoded by a pointed open book $(F, P^+, \widehat{\varphi}_0^+)$ with $\widehat{\varphi}_0^+ = h \circ \widehat{\varphi}_0 \circ h^{-1} \circ H_\beta$, where h is a diffeomorphism of F fixing a neighborhood of the boundary, P^+ is the union of $h(P)$ and a new marked point p_{n+1}^+ near the boundary, and β is an arc joining $p_n^+ = h(p_n)$ to p_{n+1}^+ . Define a new braid K_1^+ via the pointed open book $(F, P^+, \widehat{\varphi}_1^+)$ where

$$\widehat{\varphi}_1^+ = h \circ H_\alpha \circ \widehat{\varphi}_0 \circ h^{-1} \circ H_\beta = H_{h(\alpha)} \circ h \circ \widehat{\varphi}_0 \circ h^{-1} \circ H_\beta = H_{h(\alpha)} \circ \widehat{\varphi}_0^+.$$

The first equality shows that K_1^+ is obtained from K_1 by braid isotopy and a single positive stabilization, and the last equality shows that K_1^+ is obtained from K_0^+ by adding a positive half-twist, as desired.

In general, if K_0^+ is obtained from K_0 by applying a sequence of braid isotopies and multiple Markov stabilizations, we may make an analogous argument by induction on the number of Markov stabilizations in the sequence. \square

Finally, we consider the operation of Hopf stabilization on pointed open books. Suppose the transverse link K in (Y, ξ) is encoded by a pointed open book $(F, P, \widehat{\varphi})$. An abstract positive Hopf stabilization of this pointed open book is a triple $(F', P, \widehat{\varphi} \circ D_\gamma)$, where F' is obtained from F by attaching an oriented 1-handle and D_γ is a positive Dehn twist around a curve $\gamma \subset F'$ passing through this 1-handle exactly once and avoiding the marked points. This operation preserves the (transverse) link type:

Lemma 2.7 (cf [1, Corollary 2.5]) *With notation as above, the pointed open books $(F, P, \widehat{\varphi})$ and $(F', P, \widehat{\varphi} \circ D_\gamma)$ represent transversely isotopic links in (Y, ξ) .*

Proof Positive Hopf stabilization preserves the underlying contact 3-manifold and simply changes the open book structure in a standard Darboux ball N with convex boundary. In particular, N is a small neighborhood of an arc in Y that lies in a page F_θ of the original open book and is identified with the properly embedded arc $\gamma \cap F$; see [10, § 2] and [15]. (This can also be seen explicitly by viewing the original and stabilized open books as two different ways of extending a partial open book decomposition for $(Y_0 = Y \setminus \mathring{N}, \xi|_{Y_0})$ to an open book for (Y, ξ) ; see [22] for background on partial open book decompositions.) Moreover, since γ avoids the set of marked points P , the braids represented by $(F, P, \widehat{\varphi})$ and $(F', P, \widehat{\varphi} \circ D_\gamma)$ lie outside N ; here the open book structures coincide. It follows that these braids are naturally identified and, in particular, represent the same transverse link in (Y, ξ) . \square

2.3 Quasipositive braids in an open book

In this section we consider open book decompositions of arbitrary closed, oriented 3-manifolds. We begin with the most basic notion of quasipositivity.

Definition 2.8 A braid in an open book is *quasipositive* if it can be encoded by an abstract pointed open book whose pointed monodromy is isotopic to a product of positive half-twists and arbitrary Dehn twists.

Remark 2.9 To supply more context for this definition, we adopt the perspective of Etnyre-Van Horn-Morris in [12], which views classical quasipositive braids as the monoid generated by positive half-twists in the pointed mapping class group of the disk.

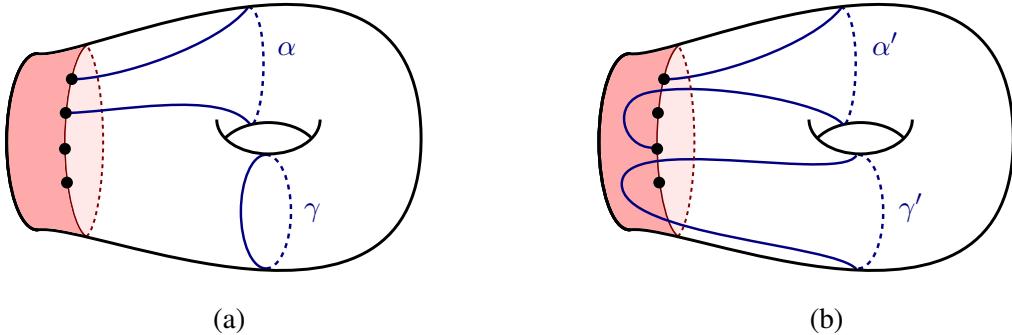


Figure 3: Twists along α and γ are allowed in a strongly quasipositive pointed monodromy, but twists along α' and γ' are not.

We can say something similar in the more general case. Given a set of marked points P in F , the elements of the pointed mapping class group that can be expressed as products of positive half-twists and arbitrary Dehn twists form a monoid. By Lemma 2.4, it is easy to see that this monoid is preserved by conjugation. In particular, this shows that Definition 2.8 is independent of the choice of the abstract pointed open book $(F, P, \widehat{\varphi})$ used to encode a braid K in (B, π) . Indeed, if K is also encoded by $(F, P', \widehat{\varphi}')$ and $(F, P, \widehat{\varphi})$ is quasipositive, then $\widehat{\varphi}'$ is isotopic to $h \circ \widehat{\varphi} \circ h^{-1}$ for some diffeomorphism h of F (as per the discussion in Section 2.2) and is therefore quasipositive.

We also generalize Rudolph's notion of strongly quasipositive braids [31]:

Definition 2.10 A braid in an open book is *strongly quasipositive* if it can be encoded by an abstract pointed open book $(F, P, \widehat{\varphi})$ where the marked points P lie along the interior edge of a collar neighborhood of ∂F and $\widehat{\varphi}$ is a product of positive half-twists and arbitrary Dehn twists along arcs and curves whose interiors do not meet the collar neighborhood; see Figure 3.

Remark 2.11 Ito and Kawamuro present an equivalent definition in [24, Definition 4.3].

For yet another perspective, we may associate to any marked surface (F, P) a braid group $B_n(F, P)$, where $n = |P|$: the group $B_n(F, P)$ is defined to be the kernel of the forgetful map from the pointed mapping class group to the regular mapping class group of the underlying surface. Using Lemma 2.4 and the discussion that follows it, we see that the pointed monodromy of any pointed open book $(F, P, \widehat{\varphi})$ can be separated into the composition of an element of the braid group $B_n(F, P)$ (expressed as a product

of half-twists $H_{\alpha_1}^{\epsilon_1} \circ \cdots \circ H_{\alpha_\ell}^{\epsilon_\ell}$ with $\epsilon_i = \pm 1$) and a diffeomorphism of F that fixes P pointwise (expressed as a product of Dehn twists $D_{\gamma_1}^{\delta_1} \circ \cdots \circ D_{\gamma_k}^{\delta_k}$ with $\delta_i = \pm 1$ along simple closed curves γ_i missing P). We say that the braid encoded by $(F, P, \hat{\varphi})$ is the *closure* of $H_{\alpha_1}^{\epsilon_1} \circ \cdots \circ H_{\alpha_\ell}^{\epsilon_\ell} \in B_n(F, P)$ with respect to the abstract open book $(F, D_{\gamma_1}^{\delta_1} \circ \cdots \circ D_{\gamma_k}^{\delta_k})$. This gives a natural refinement of the notion of quasipositivity with respect to a given factorization of the monodromy map for the underlying open book:

Definition 2.12 An element of the braid group $B_n(F, P)$ is *quasipositive* if it can be represented as a product of positive half-twists. A braid is *quasipositive with respect to an (abstract) open book* (F, φ) if it can be represented as the closure of a quasipositive braid in $B_n(F, P)$ with respect to (F, φ) , where φ fixes $P \subset F$ pointwise.

As we will demonstrate in the proof of Theorem 1.1, the boundary of a complex curve in a Stein domain is isotopic to the closure of a quasipositive braid with respect to a *positive allowable* open book, ie one where the monodromy for the underlying open book is a product of positive Dehn twists along homologically nontrivial curves.

Finally, as indicated in the introduction, we extend these definitions to transverse and smooth link types: Given a closed, orientable contact 3-manifold (Y, ξ) , we say a transverse or smooth link type K is (*strongly*) *quasipositive* if there is an open book decomposition of Y compatible with ξ in which K is transversely or smoothly isotopic, respectively, to a (strongly) quasipositive braid.

3 Characteristic and open book foliations

Contact structures and open books on a 3-manifold Y naturally induce singular foliations on surfaces $S \subset Y$. For general background on characteristic and open book foliations, we refer the reader to [17] and [23], respectively.

For a rigorous treatment of singular foliations, see [17] (especially Remark 2.5.21). Formally, we define an oriented, singular foliation \mathcal{F} on a surface S to be an equivalence class of vector fields $[v]$, where $[v] = [v']$ if there is a nowhere-zero function f on S such that $v' = fv$. However, we will often conflate a singular foliation with the associated decomposition of S into integral curves of a representative vector field v of \mathcal{F} . Following [17] and [23], we will be concerned with singular foliations up to topological conjugacy; two singular foliations \mathcal{F} and \mathcal{F}' on a surface S are said to be *topologically conjugate* if there exists a homeomorphism of S carrying \mathcal{F} to \mathcal{F}' .

Definition 3.1 Let Y be a 3-manifold containing a smooth, oriented surface S and let Ω be an area form on S . The *characteristic foliation* on $S \subset Y$ induced by $\xi = \ker \alpha$ is the singular foliation on S directed by a vector field v satisfying $\iota_v \Omega = \alpha|_S$.

The existence of such a vector field v is guaranteed by the nondegeneracy of the 2-form Ω . It is straightforward to show that the oriented singular foliation on S defined by v depends only on $\xi = \ker \alpha$ and the co-orientation induced by α (cf [17, §2.5.4]).

An open book decomposition (B, π) of Y also defines a singular foliation on $S \subset Y$; see [3, 5, 23]. This singular foliation admits a description analogous to Definition 3.1. To set this up, let $d\theta$ denote the angular coordinate 1-form on S^1 . Define a 1-form $\lambda = f\pi^*(d\theta)$ on Y , where f is strictly positive on $Y \setminus B$ and is locally given by $f(s, r, \vartheta) = r^2$ in some coordinates $(s, r, \vartheta) \in S^1 \times D^2$ near each component of B . When restricted to $Y \setminus B$, $\ker \lambda$ is a co-oriented, integrable plane field whose maximal integral submanifolds are precisely the pages of the open book (B, π) .

Definition 3.2 The *open book foliation* on S induced by (B, π) is the singular foliation directed by a vector field v satisfying $\iota_v \Omega = \lambda|_S$, with λ as above.

It is straightforward to verify that Definition 3.2 coincides with the definition given in [23]. In particular, note that the regular leaves of the open book foliation on S are tangent to the pages of (B, π) .

These definitions of characteristic and open book foliations naturally extend to oriented surfaces S equipped only with a smooth map $\phi : S \rightarrow Y$, where the conditions $\iota_v \Omega = \alpha|_S$ and $\iota_v \Omega = \lambda|_S$ from Definitions 3.1 and 3.2 are replaced with the conditions $\iota_v \Omega = \phi^* \alpha$ and $\iota_v \Omega = \phi^* \lambda$. We will be particularly interested in maps $\phi : S \rightarrow Y$ that are well-behaved with respect to a Morse function on S .

Definition 3.3 Given a map $\phi : S \rightarrow Y$ and a function $f : S \rightarrow \mathbb{R}$, we say that ϕ is *nonsingular with respect to f* if ϕ restricts to an embedding on each level set of f and on a neighborhood of each critical point of f .

This definition is motivated by the following source of examples.

Lemma 3.4 Given an embedded surface $S \subset Y \times \mathbb{R}$, the map $\phi : S \rightarrow Y$ (induced by $Y \times \mathbb{R} \rightarrow Y$) is nonsingular with respect to $f : S \rightarrow \mathbb{R}$ (induced by $Y \times \mathbb{R} \rightarrow \mathbb{R}$).

Proof The projection $Y \times \mathbb{R} \rightarrow Y$ restricts to a diffeomorphism between each level set $Y_t = Y \times \{t\}$ and Y . Thus ϕ restricts to an embedding on each level set $f^{-1}(t) = S \cap Y_t$.

Next, observe that the map $d\phi$ is nondegenerate wherever S is not tangent to the fibers $\{y\} \times \mathbb{R}$ of the projection $Y \times \mathbb{R} \rightarrow Y$. At any critical point p of f , the surface S is tangent to a level set Y_t , hence is not tangent to the fibers $\{y\} \times \mathbb{R}$. It follows that $d\phi$ is nondegenerate at p , so ϕ is an immersion near p and thus restricts to an embedding on a sufficiently small neighborhood of $p \in S$. \square

3.1 Model subsurfaces

Recall the definition of weakly gradient-like vector fields and singular foliations from Section 1. Observe that if the characteristic or open book foliation on $S \subset Y$ is weakly gradient-like for $f : S \rightarrow \mathbb{R}$, then the regular level sets of f are transverse to the contact planes or pages of the open book, respectively. (This is true, more generally, for the characteristic or open book foliation defined using a smooth map $\phi : S \rightarrow Y$ that is nonsingular with respect to the function f .)

We will extract information from singular foliations on surfaces by decomposing them into “model subsurfaces” that carry simple geometric and topological information. Recall that if S is a disk or a pair of pants, then it admits an obvious Morse function f with a single critical point of even or odd index, respectively. The singular foliation on S induced by the gradient vector field of f is unique up to topological conjugacy (and a choice of orientation). See Figure 4(a,b) for depictions of these models, which we refer to as a *disk with elliptic foliation* and a *pair of pants with hyperbolic foliation*, respectively.

We summarize the significance of these models in the context of open book foliations:

Lemma 3.5 *Consider a 3-manifold with a fixed open book decomposition.*

- (a) *The boundary of a disk with positive (resp. negative) elliptic open book foliation is a positively (resp. negatively) braided unknot meeting each page in one point.*
- (b) *If braids K and K' cobound a pair of pants with hyperbolic open book foliation (oriented so that its boundary is $K' \cup -K$), then K' is obtained from K by braid isotopy and the addition of a half-twist whose sign agrees with the sign of the hyperbolic point.*

Moreover, this holds for singular disks and pairs of pants, provided the maps are nonsingular with respect to the standard Morse functions described above.

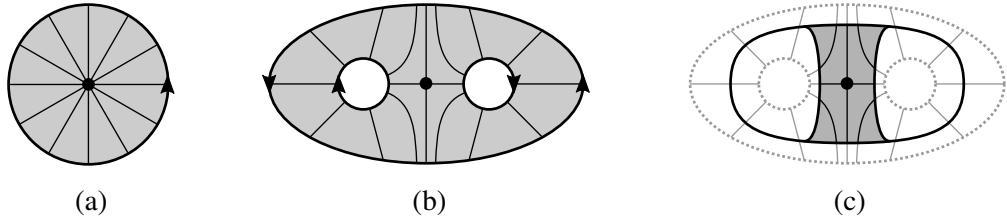


Figure 4: A disk with elliptic foliation and a pair of pants with hyperbolic foliation are shown in (a) and (b), respectively. In (c), the boundary components of the pair of pants are contracted to cobound a band.

Proof The first claim follows immediately from the standard definition of the open book foliation, as elliptic points correspond to intersections with the binding; see [23]. The second claim also follows quickly from definitions, following the method of proof in [4, Lemma 1.6]. In particular, note that any isotopy of K and K' through curves transverse to the open book foliation on S is a braid isotopy. Thus we may contract K and K' towards one another along the leaves of the open book foliation on S until they coincide outside a neighborhood of the hyperbolic point, as depicted in Figure 4(c). The region they enclose is a twisted band, and a local depiction of its embedding is given in Figure 5(c) (which may be compared to [4, Figures 1.12-1.13]). The claim follows.

In the case of a singular disk that is nonsingular with respect to the standard Morse function, part (a) is immediate because any sufficiently small neighborhood of the elliptic point is embedded and has an elliptic open book foliation. For part (b), let $f : P \rightarrow \mathbb{R}$ denote the standard Morse function on the pair of pants P with respect to which the open book foliation is weakly gradient-like and with respect to which the map $P \rightarrow Y$ is nonsingular. We may again contract each of K and K' along the leaves of the open book foliation until they both coincide with the critical level set of f outside a neighborhood of the hyperbolic point. In particular, we may define this isotopy so that each intermediate link K_t and K'_t coincides with a level set of f outside a fixed, embedded neighborhood of the hyperbolic point. This ensures that each intermediate link is embedded and braided. As above we may then locate an embedded, twisted band inside this neighborhood that these modified braids cobound. \square

3.2 Modifying open book foliations

We now prove Theorem 1.4, which allows us to modify an open book on (Y, ξ) so that the open book foliation on a surface S approximates its characteristic foliation.

Remark 3.6 This theorem holds for a singular surface S that is nonsingular with respect to the Morse function from the statement of the theorem, provided the collection of critical level sets is embedded. The proof given below carries over verbatim.

We will need one preparatory lemma:

Lemma 3.7 *If two smooth, codimension-one foliations \mathcal{F} and \mathcal{F}' on a 3-manifold Y have a common transverse vector field v in a neighborhood U of $p \in Y$, then we may isotope \mathcal{F}' inside U through foliations transverse to v so that it agrees with \mathcal{F} inside a smaller neighborhood of p .*

Proof We may fix local coordinates (x, y, z) centered at p in which v is parallel to ∂_z , \mathcal{F} is given by the z -constant planes, and \mathcal{F}' is given by the level sets of a function $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ satisfying $\partial f / \partial z > 0$. For convenience, we rescale f so that $f(0, 0, 0) = 0$. We will define an isotopy ψ_t of \mathbb{R}^3 from the identity $\psi_0 = \text{id}$ to a diffeomorphism ψ_1 satisfying $\psi_1(x, y, z) = (x, y, f(x, y, z))$ for all (x, y, z) in a neighborhood of $(0, 0, 0)$. Such an isotopy carries the f -constant level sets (ie the leaves of \mathcal{F}') to the z -constant planes (ie the leaves of \mathcal{F}) near $(0, 0, 0)$, as desired. Moreover, the isotopy will preserve the vertical lines $(x, y) \times \mathbb{R}$, hence the leaves of \mathcal{F}' remain transverse to v throughout the isotopy.

We begin by working on an infinite cylinder $D_\delta^2 \times \mathbb{R} = \{(x, y, z) : x^2 + y^2 < \delta^2\}$ for some $\delta > 0$. In particular, given any $\epsilon > 0$, there exists $\delta < \epsilon$ such that $|f(x, y, z)| < \epsilon/2$ on the small cylinder $D_\delta^2 \times [-\delta, \delta]$. We may then find a function $g : D_\delta^2 \times \mathbb{R} \rightarrow \mathbb{R}$ such that $g(x, y, z) = f(x, y, z)$ on $D_\delta^2 \times [-\delta, \delta]$, $g(x, y, z) = z$ on $D_\delta^2 \times (-\infty, -\epsilon]$ and $D_\delta^2 \times [\epsilon, \infty)$, and $\partial g / \partial z > 0$ at all points. Smoothly extend g in any way to the rest of \mathbb{R}^3 .

Now choose a smooth function $\mu : \mathbb{R} \rightarrow [0, 1]$ that is equal to 1 on $[-\delta/2, \delta/2]$ and vanishes outside of $(-\delta, \delta)$. For $t \in [0, 1]$, define a map $\psi_t : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ by

$$\psi_t(x, y, z) = (x, y, (1 - t\mu(x^2 + y^2))z + t\mu(x^2 + y^2)g(x, y, z)).$$

Note that ψ_t is the identity outside $D_\delta^2 \times [-\epsilon, \epsilon]$. To see that ψ_t is a diffeomorphism for all t , we first note that ψ_t maps each vertical line $(x, y) \times \mathbb{R}$ to itself; it then suffices to show that ψ_t restricts to a diffeomorphism on each such line. Observe that

$$d\psi_t(\partial_z) = (0, 0, 1 + t\mu(x^2 + y^2)(\partial g / \partial z - 1)).$$

Since $\partial g / \partial z > 0$ and both t and $\mu(x^2 + y^2)$ lie in $[0, 1]$, we see that the z -component above is positive; that is, $d\psi_t(\partial_z)$ is a positive multiple of ∂_z at all points. Thus ψ_t is a diffeomorphism for all $t \in [0, 1]$. And at any point $(x, y, z) \in D_{\delta/2}^2 \times [-\delta, \delta]$, we have $\psi_1(x, y, z) = (x, y, g(x, y, z)) = (x, y, f(x, y, z))$, as claimed. \square

Proof of Theorem 1.4 We will prove something slightly stronger: Let Γ be any finite collection of level sets of $f : S \rightarrow \mathbb{R}$. We will produce an isotopy of any compatible open book (B, π) through open books supporting ξ so that the open book foliation on S is weakly gradient-like with respect to f on a neighborhood of Γ . For convenience, we assume the critical points of f have distinct values; the general case follows with minor modifications.

We begin with the case of a regular level set $\gamma \subset \Gamma$. The level set γ is transverse to the characteristic foliation on S , so it is a transverse link in (Y, ξ) . By the transverse Alexander theorem (Theorem 2.1 and Remark 2.2), we may braid γ using an ambient contact isotopy. Moreover, the isotopy may be taken to fix all other level sets in Γ . Equivalently, we may isotope (B, π) by the inverse of this ambient isotopy while leaving S fixed. After this isotopy of (B, π) , γ is braided, and the same is true of all other level sets sufficiently close to γ . It follows that the open book foliation is weakly gradient-like with respect to f near γ .

Next consider a critical level set in Γ , which we have assumed contains a unique critical point. Near each regular component of the critical level set, we may apply the above argument. It thus suffices to consider a critical level set with no regular components.

In the case of a minimum or maximum of f , ie a positive or negative elliptic point of the characteristic foliation, the singular component of the level set is just the critical point $p \in S$ itself. Without loss of generality, we assume p is a positive elliptic point (ie local minimum) so that $T_p S = \xi_p$ with orientation. We can find (1) a path in Y from p to the binding B that meets Γ only at p and (2) an ambient contact isotopy that moves p to the binding and is the identity outside a small neighborhood of the path [17, Corollary 2.6.3]. This preserves the characteristic foliation on S but turns p into an elliptic point of the open book foliation (because $T_p S = \xi_p$ is transverse to the binding B). Moreover, the open book foliation is transverse to all regular level sets of f near p . Indeed, for some choice of local coordinates (x, y) on S centered at p , the open book foliation is directed by the radial vector field $v = x\partial_x + y\partial_y$. It is easy to verify that $df(v) > 0$ except at $p = (0, 0)$, as desired, using the fact that f has a local minimum at p . (For example, use these local coordinates to write $f(x, y) = f_{xx}(0, 0)x^2 + f_{xy}(0, 0)xy + f_{yy}(0, 0)y^2 + g(x, y)$, where g is a smooth function whose first and second derivatives all vanish at the origin. Then calculate the determinant of the Hessian for $df(v)$ using that of f .) As above, we may then pull (B, π) back by the ambient contact isotopy to obtain the desired open book foliation on S while leaving S itself fixed.

Next suppose that the critical point p is a saddle of f , which corresponds to a saddle (ie hyperbolic) point of the characteristic foliation. Without loss of generality, we

assume p is a positive hyperbolic point so that $T_p S = \xi_p$ with orientation. We will define a 2-dimensional foliation \mathcal{F} on a neighborhood of p in Y that locally induces a singular foliation on S with a hyperbolic singularity; we will then perturb the open book (B, π) so that its pages coincide with \mathcal{F} . To arrange this, fix a neighborhood U of p in S and a neighborhood $U \times (-\epsilon, \epsilon)$ of p in Y in which ξ is vertically invariant; see [17, Proposition 4.6.22]. By the Morse lemma, we may find coordinates (x, y) on U in which $f(x, y) = x^2 - y^2$. Letting z give the coordinate on $(-\epsilon, \epsilon)$, define a smooth 1-form by $\eta = dz + y dx + x dy$. Since $d\eta = 0$, the plane field $\ker \eta$ is integrable and thus defines a 2-dimensional foliation \mathcal{F} on $U \times (-\epsilon, \epsilon)$ by Frobenius' theorem. Observe that the singular foliation on $S = U \times \{0\}$ is directed by the vector field $v = x\partial_x - y\partial_y$ (seen by noting that v vanishes only at the origin and satisfies $\eta(v) = 0$), which is gradient-like for f near $p = (0, 0, 0)$.

Let R_α be any Reeb vector field for ξ that is positively transverse to the pages of (B, π) . We claim that R_α is also positively transverse to \mathcal{F} near p . In the local coordinates above, ξ coincides with the plane $\ker dz$ at the point $p = (0, 0, 0)$. Thus we have $dz(R_\alpha) > 0$ at $p = (0, 0, 0)$. Since $\eta_p = dz_p$, we have $\eta_p(R_\alpha) > 0$ at p , hence $\eta(R_\alpha) > 0$ in a neighborhood of p .

To set up the perturbation of (B, π) , let \mathcal{F}_0 denote the 2-dimensional foliation of the neighborhood of p induced by the pages of (B, π) . By restricting our neighborhood, we may assume that R_α is positively transverse to both \mathcal{F} and \mathcal{F}_0 . By Lemma 3.7, we can isotope \mathcal{F}_0 through a family of foliations \mathcal{F}_t transverse to R_α such that \mathcal{F}_t agrees with \mathcal{F}_0 outside some neighborhood of p for all t and \mathcal{F}_1 agrees with \mathcal{F} inside some smaller neighborhood of p . The pages remain positively transverse to R_α , so this deformation defines a family of open books (B, π_t) that support ξ . By construction, the open book (B, π_1) induces an open book foliation on S with a hyperbolic point at p . Moreover, since $df(v) \geq 0$ with equality only at p , we see that the new open book foliation is weakly gradient-like with respect to f in the neighborhood.

We now extend this to the rest of the critical component γ . This level set γ is a wedge of two circles; the subset $\gamma \setminus \{p\}$ is a pair of (oriented) open arcs that are transverse to ξ and, near p , are braided with respect to (B, π_1) . Applying Theorem 2.1 and Remark 2.2 again, we may braid $\gamma \setminus \{p\}$ with respect to (B, π_1) via an ambient contact isotopy that fixes a neighborhood of p and all other components of Γ . The open book foliation is preserved near p , and the portion of γ lying outside the neighborhood of p (as well as all nearby level sets) is braided with respect to the open book. It follows that the open book foliation is now gradient-like with respect to f near γ . As above, we then pull the open book back by the isotopy so that we achieve the desired open book foliation on S while leaving S itself fixed.

This argument can be applied to each level set in $\Gamma \subset S$ without modifying the open book foliation near the rest of Γ , so the claim follows by induction on the size of Γ . \square

3.3 Characteristic foliations and quasipositivity

We now prove Theorem 1.3.

Remark 3.8 As with Theorem 1.4 (per Remark 3.6), the proof of Theorem 1.3 given below holds for well-behaved singular surfaces in Y . In particular, $\phi : S \rightarrow Y$ must be nonsingular with respect to a Morse function $f : S \rightarrow \mathbb{R}$ whose collection of critical level sets is embedded in Y , and the characteristic foliation on S induced by ϕ must be weakly gradient-like for f and contain only positive singular points.

Proof of Theorem 1.3 We recall the key hypotheses: the braid K_0 is transversely isotopic to a braid K_0^+ in an open book (B, π) encoded by a quasipositive pointed open book; and the characteristic foliation on S is weakly gradient-like with respect to a Morse function $f : S \rightarrow \mathbb{R}$ with distinct critical values. We may assume that K_0^+ has been chosen to avoid a neighborhood of each critical point. (This can always be achieved by an arbitrarily small transverse braid isotopy of K_0^+ , and it is easy to see that the hypotheses on the presentation of K_0^+ as a quasipositive braid are not affected by a small perturbation.) This simplifies a technical point: To apply Theorem 1.4, we must modify (B, π) using an ambient isotopy that restricts to a contact isotopy outside an arbitrarily small neighborhood of each index-one critical point of $f : S \rightarrow \mathbb{R}$. Since K_0^+ can be chosen to avoid these regions, it is carried along by a transverse isotopy to a braid in the modified open book (B', π') . Furthermore, we may use the ambient isotopy to carry forward the quasipositive pointed open book encoding K_0^+ in (B, π) to a quasipositive pointed open book encoding K_0^+ in (B', π') .

Applying Theorem 1.4, we may assume that the boundary $\partial S = K_1 \cup -K_0$ is braided with respect to (B', π') and the open book foliation on S is weakly gradient-like for f near its critical level sets.

Divide S into subsurfaces by splitting it along small neighborhoods $f^{-1}([c - \epsilon, c + \epsilon])$ of its critical level sets $f^{-1}(c)$. For sufficiently small $\epsilon > 0$, the open book foliation on the surface $f^{-1}([c - \epsilon, c + \epsilon])$ is weakly gradient-like for f . Note this implies that each such subsurface has braided boundary. Treating each subsurface separately and arguing inductively on the number of critical points, it suffices to consider these cases:

- (i) S contains no critical points of f , or

- (ii) the open book foliation on S is weakly gradient-like for f and S has a unique critical of (a) even index, or (b) odd index.

In case (i), the surface is a collection of annuli. Since f has no critical points, the characteristic foliation on each annulus is conjugate to a linear foliation. This implies that K_1 is transversely isotopic to K_0 , which in turn is transversely isotopic to a quasipositive braid with respect to (B', π') .

In case (ii-a), the (unique) critical point of even index must correspond to a positive singular point of the characteristic foliation. The surface then consists of a collection of annuli with linear open book foliation and a disk with positive elliptic open book foliation, as depicted in Figure 4. By Lemma 3.5, K_1 is obtained from K_0 by braid isotopy and the addition of a disjoint braided unknot U that bounds a meridional disk of the binding. Since K_0 is transversely isotopic to a quasipositive braid with respect to (B', π') , so is $K_1 = K_0 \cup U$.

In case (ii-b), the (unique) critical point of odd index must correspond to a positive singular point of the characteristic foliation. The surface then consists of a collection of annuli with linear open book foliation and a pair of pants with positive hyperbolic open book foliation. In this case, K_1 is obtained from K_0 by braid isotopy and the addition of a positive half-twist. Since K_0 is transversely isotopic to a quasipositive braid K_0^+ with respect to (B', π') , the transverse Markov theorem implies that K_0 and K_0^+ have a common positive Markov stabilization. Any positive stabilization of a quasipositive braid is quasipositive, so this implies that K_0 can be positively stabilized to a quasipositive braid that, for notational convenience, we will also denote by K_0^+ . By Lemma 2.6, we can find a positive stabilization K_1^+ of K_1 that can be obtained from K_0^+ by adding a positive half-twist. The addition of a positive half-twist preserves quasipositivity, so K_1^+ is also a quasipositive braid with respect to (B', π') . We conclude that K_1 is transversely isotopic to a quasipositive braid.

In each case, it follows that K_1 is transversely isotopic to a quasipositive braid K_1^+ with respect to the isotoped open book (B', π') . As above, we may assume that K_1^+ avoids the neighborhoods of the critical points of $f : S \rightarrow \mathbb{R}$ where the ambient isotopy from Theorem 1.4 failed to be a contact isotopy. We may then reverse the isotopy, carrying (B', π') back to (B, π) and carrying K_1^+ by a transverse isotopy to a quasipositive braid with respect to the original open book (B, π) . \square

Remark 3.9 We can sharpen the above result: If K_0 is transversely isotopic to the closure of a quasipositive braid with respect to an underlying abstract open book (F, φ) with a given factorization of φ into Dehn twists, then K_1 is also transversely isotopic

to the closure of a quasipositive braid with respect to the same factorization of φ into Dehn twists. (See Definition 2.12 and the discussion preceding it.) This is clear in the case where the characteristic foliation contains no hyperbolic points, since K_1 is then obtained from K_0 by isotopy and the addition of disjoint unknots meridional to the binding.

Following the inductive argument above, it suffices to consider the case where S is a pair of pants with hyperbolic open book foliation and $\partial S = K_1 \cup -K_0$. The proof shows that there is *some* pointed open book $(F, P, \widehat{\varphi})$ encoding K_0 in (B', π') such that $\widehat{\varphi}$ is isotopic to φ and K_1 is obtained by adding a positive half-twist H_β to $\widehat{\varphi}$. By hypothesis, the braid K_0 is transversely isotopic to the closure of a quasipositive braid with respect to the given factorization of φ into Dehn twists. As above, this quasipositive braid and K_0 have a common positive Markov stabilization, which we can write as the closure of a quasipositive braid $H_{\alpha_1} \circ \cdots \circ H_{\alpha_\ell}$ with respect to the given factorization of φ into Dehn twists. Mirroring the argument from Lemma 2.6, we carry the half-twist H_β through the sequence of Markov stabilizations and isotopies to a half-twist along a new arc β' so that K_1 is transversely isotopic to the closure of the quasipositive braid $H_{\beta'} \circ H_{\alpha_1} \circ \cdots \circ H_{\alpha_\ell}$ with respect to the given factorization of φ into Dehn twists.

4 Holomorphic curves in Stein surfaces

A complex manifold is *Stein* if it admits a proper holomorphic embedding as a closed subset of some \mathbb{C}^n , and a *Stein surface* X is a Stein manifold of complex dimension two. We say that a (real) hypersurface $Y \subset X$ is *J -convex* if the field of complex tangent lines to $Y \subset X$ forms a contact structure on Y ; here J denotes the almost-complex structure on TX induced by the complex structure on X . Such hypersurfaces naturally arise as regular level sets of *J -convex* functions on X ; see [8, §2.2] for a precise definition. In particular, every Stein surface X admits an exhausting *J -convex* Morse function $\rho : X \rightarrow \mathbb{R}$ whose level sets are *J -convex* at all regular points. In this case, the contact structure can also be described as the kernel of the 1-form given by restricting $\eta = -d^{\mathbb{C}}\rho$ to the level set, where $d^{\mathbb{C}} = J^*d$. (This 1-form is a primitive for a symplectic form $\omega = d\eta$ on X .) For a thorough exposition of the theory of Stein manifolds, we refer the reader to [8].

In our setting, the pair (J, ρ) will often be replaced with a slightly coarser structure: A *Weinstein structure* on a 4-manifold X is a triple (ω, ρ, v) where ω is a symplectic form, ρ is an exhausting Morse function, and v is a complete vector field which is

Liouville for ω (ie $\mathcal{L}_v\omega = \omega$) and gradient-like for ρ ; see [8] for more detail. As above, each regular level set $\rho^{-1}(c)$ has a contact form given by the restriction of the *Liouville form* $\eta = \iota_v\omega$ (which is a primitive for ω). As a key example, any Stein surface X with a J -convex Morse function ρ has a natural Weinstein structure with $\omega = d\eta = -dd^C\rho$ as above and where v is the gradient vector field for ρ with respect to the Riemannian metric $g(\cdot, \cdot) = \omega(\cdot, J\cdot)$.

Our proof of Theorem 1.1 is motivated by a simple observation (cf [7, 14]): Given a smooth holomorphic curve Σ in a Stein surface X and a smooth J -convex hypersurface $Y \subset X$, consider the intersection $\Sigma \cap Y$. If this intersection is transverse, then $\Sigma \cap Y$ forms a smooth link that is transverse to the natural contact structure ξ on Y . Indeed, since $T\Sigma$ and ξ consist of complex lines in TX , their intersection at any point has real dimension zero or two. It follows that $\Sigma \cap Y$ is transverse to the contact structure except for those points p at which Σ is tangent to Y , where $T_p\Sigma = \xi_p \subset T_pY$.

This crude picture suggests a more flexible class of surfaces:

Definition 4.1 (cf [7]) A smoothly embedded, oriented surface Σ in a Weinstein 4-manifold (X, ω, ρ, v) is *ascending* if Σ contains no critical points of $\rho|_X$, the restriction $\rho|_\Sigma$ is a Morse function, and, except at its critical points, each level set $\rho|_\Sigma^{-1}(c)$ is positively transverse to the contact structure on $\rho|_X^{-1}(c)$.

Equivalently, to better mirror the original definition from [7], one can replace the third condition with the inequality $(d\rho \wedge \eta)|_\Sigma > 0$ at regular points of $\rho|_\Sigma$. (We say that a 2-form on the oriented surface Σ is positive if it is a positive multiple of an area form on Σ .) In Section 4.1, we present a third characterization of ascending surfaces phrased in terms of characteristic foliations on surfaces in Weinstein 4-manifolds, which we define precisely in Definition 4.9. These three characterizations of ascending surfaces are shown to be equivalent in Proposition 4.10.

We will show that critical points of $\rho|_\Sigma$ have a sign induced by the symplectic form on X , and complex curves are examples of ascending surfaces whose critical points are all positive (Proposition 4.12). Thus Theorem 1.1 follows from a more general result:

Theorem 4.2 *If Σ is an ascending surface with positive critical points that is properly embedded in a Weinstein domain X , then $K = \partial\Sigma$ is transversely isotopic to a quasipositive braid with respect to a (positive allowable) open book for ∂X .*

This holds more generally in Weinstein cobordisms between contact 3-manifolds:

Theorem 4.3 *Let Σ be an ascending surface with positive critical points in a Weinstein cobordism X between (Y_0, ξ_0) and (Y_1, ξ_1) . If $K_0 = \Sigma \cap Y_0$ is transversely isotopic to a quasipositive braid in a (positive allowable) open book compatible with ξ_0 , then $K_1 = \Sigma \cap Y_1$ is transversely isotopic to a quasipositive braid in a (positive allowable) open book compatible with ξ_1 .*

For ascending surfaces in the symplectization of a contact 3-manifold (Y, ξ) , we have additional control over the choice of compatible open book:

Theorem 4.4 *Let Σ be an ascending surface with positive critical points in a compact piece $Y \times [0, 1]$ of the symplectization of (Y, ξ) . If $K_0 = \Sigma \cap Y_0$ is transversely isotopic to the closure of a quasipositive braid with respect to an open book for (Y, ξ) , then $K_1 = \Sigma \cap Y_1$ is transversely isotopic to the closure of a quasipositive braid with respect to the same open book. In particular, if K_0 is empty, then K_1 is transversely isotopic to a quasipositive braid with respect to any open book supporting (Y, ξ) .*

Viewing complex curves in \mathbb{C}^2 as lying in the symplectization of (S^3, ξ_{st}) , this recovers the theorem of Boileau and Orevkov:

Corollary 4.5 (Boileau-Orevkov) *The boundary of any smooth, properly embedded complex curve in $B^4 \subset \mathbb{C}^2$ is quasipositive (with respect to the standard open book).*

We lay the groundwork for these results with a general study of ascending surfaces in Section 4.1. The main proofs are then given in Sections 4.2 and 4.3.

4.1 Ascending surfaces in Weinstein 4-manifolds

We now provide examples of ascending surfaces in §4.1.1 via two constructions that will be essential to the proof of Theorem 1.2. Then, in §4.1.2, we establish the properties of ascending surfaces that will be used to prove Theorems 4.2-4.4.

4.1.1 Examples of ascending surfaces

Recall that a contact 3-manifold (Y, ξ) with $\xi = \ker \alpha$ has a *symplectization* $\text{Symp}(Y, \xi)$, defined to be $Y \times \mathbb{R}$ with the symplectic form $\omega = d(e^t \alpha)$. This symplectic 4-manifold admits a Weinstein structure with Morse function $\rho(y, t) = t$, Liouville field $v = \partial_t$, and Liouville form $\eta = e^t \alpha$.

Example 4.6 Let $S \subset (Y, \xi)$ be a smoothly embedded surface whose boundary ∂S is a positively transverse link and whose characteristic foliation is Morse-Smale and contains no regular closed leaves. Choose a vector field u directing the characteristic foliation. By Theorem B of [33], there is a Morse function $f : S \rightarrow \mathbb{R}$ such that $df(u) > 0$ at nonzero points of u and $f(S) \subset (-\infty, 0]$ with $f|_{\partial S} \equiv 0$. Viewing $Y \times (-\infty, 0]$ as part of the symplectization of (Y, ξ) , we can define a surface $\Sigma \subset Y \times (-\infty, 0]$ to be the graph of f over $S \subset Y$, ie the image of the map $S \rightarrow Y \times (-\infty, 0]$ defined by $x \mapsto (x, f(x))$. Letting ρ denote the projection $Y \times (-\infty, 0] \rightarrow (-\infty, 0]$, we see that $\rho|_{\Sigma}$ pulls back to the function f on S . The requirement $df(u) > 0$ at regular points implies that regular level sets of f are positively transverse links, so the same is true of the regular level sets of $\rho|_{\Sigma}$. It follows that Σ is an ascending surface in $Y \times (-\infty, 0] \subset \text{Symp}(Y, \xi)$. \diamond

Example 4.7 (Push-in of an immersed Bennequin surface) Suppose a transverse braid K in (Y, ξ) is encoded by a pointed open book $(F, P, \widehat{\varphi})$ where the monodromy can be factored in the form

$$\widehat{\varphi} = H_{\alpha_1}^{\epsilon_1} \circ \cdots \circ H_{\alpha_\ell}^{\epsilon_\ell} \circ \varphi$$

where φ fixes a collar neighborhood N of ∂F containing the marked points and $\epsilon_j = \pm 1$. Fix a set of disjoint arcs in N joining the marked points to ∂F and let $S_0 \subset Y$ be the disjoint union of disks swept out by this family of arcs; see Figure 5(b). Now attach 1-handles h_j to S_0 as follows: The core of h_j will be a copy of the arc α_j lying in the page F_{θ_j} for $\theta_j = 2\pi j/(\ell + 1)$. We can extend this core to a once-twisted band h_j whose sign agrees with that of ϵ_j ; see Figure 5(c). In general, the twisted bands may intersect the interiors of the disks S_0 transversely along embedded “ribbon” arcs. Let S denote the resulting immersed “Bennequin” surface for K .

The open book foliation on the immersed surface S is Morse-Smale and has positive elliptic points along the binding and hyperbolic points along the twisted bands. Using [23, Theorem 2.21], we can isotope ξ (away from ∂S) to another contact structure ξ' so that the characteristic foliation on S is conjugate to the open book foliation. By Gray’s theorem, there is an induced isotopy of S rel boundary so that ξ itself induces the desired characteristic foliation. Now let $f : S \rightarrow \mathbb{R}$ be a Morse function that has a gradient-like vector field that directs the characteristic foliation. Since any self-intersections of S occur between a disk in $S_0 \subset S$ and part of a twisted band lying in $S \setminus S_0$, we can modify f on the disks (in particular, decrease its value) so that the level sets of f are all embedded. As in Example 4.6, the graph of f is an embedded ascending surface in $\text{Symp}(Y, \xi)$. \diamond

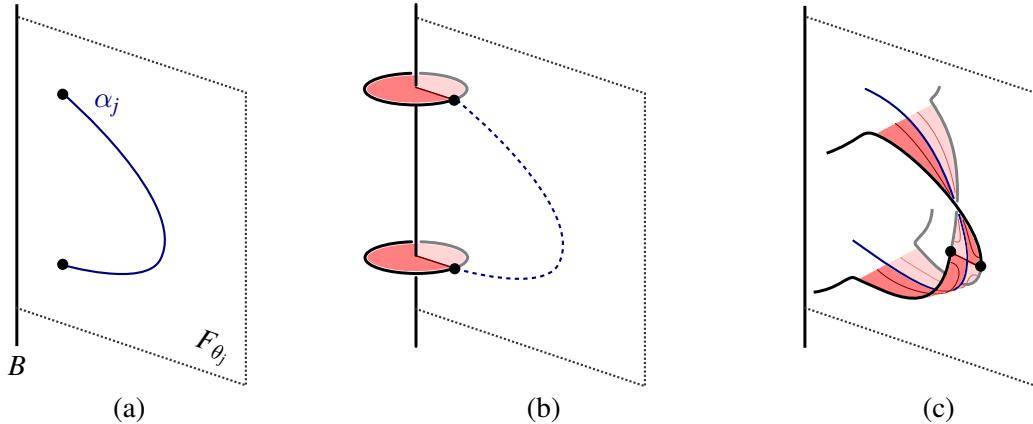


Figure 5: Building a Bennequin surface.

We pause to highlight a corollary. By Example 4.7, every strongly quasipositive transverse link K in (Y, ξ) bounds a Seifert surface whose characteristic foliation is Morse-Smale with positive singularities. By a signed count of elliptic and hyperbolic points in the characteristic or open book foliations on any such surface, we obtain:

Corollary 4.8 *The Eliashberg-Bennequin inequality is sharp for every strongly quasipositive link in a tight contact 3-manifold.* \square

4.1.2 Properties of ascending surfaces

When a 4-manifold X is equipped with a Weinstein structure (ω, ρ, v) , the Liouville form $\eta = \iota_v \omega$ can be used to define a characteristic foliation on any surface in X :

Definition 4.9 Let Σ denote a smooth, oriented surface in X and let Ω be an area form on Σ . The *characteristic foliation* on Σ is the singular foliation directed by the vector field u satisfying $\iota_u \Omega = \eta|_\Sigma$.

As with Definition 3.1, this characteristic foliation is independent of the area form Ω and depends on η only up to multiplication by a positive function. We use characteristic foliations to provide a third characterization of ascending surfaces:

Proposition 4.10 (Characterization of ascending surfaces) *Let $\Sigma \subset X$ be a smooth, oriented surface that avoids the critical points of $\rho : X \rightarrow \mathbb{R}$, and suppose that $\rho|_\Sigma$ is a Morse function. Then the following are all equivalent:*

- (a) Σ is ascending;
- (b) $(d\rho \wedge \eta)|_{\Sigma} > 0$ at regular points of $\rho|_{\Sigma}$;
- (c) the characteristic foliation on Σ is weakly gradient-like for $\rho|_{\Sigma}$.

Proof We will prove $(a) \Rightarrow (b) \Rightarrow (c) \Rightarrow (a)$. Our argument leverages another singular foliation on Σ : the level sets of $\rho|_{\Sigma}$. For a fixed positive area form Ω on Σ , this singular foliation is directed by the vector field w on Σ defined by the equation $\iota_w \Omega = -d\rho|_{\Sigma}$. Note that w orients each level set $\rho|_{\Sigma}^{-1}(c)$ as the boundary of the sublevel set $\rho|_{\Sigma}^{-1}(-\infty, c]$. To see this, fix a weakly gradient-like vector field u' for $\rho|_{\Sigma}$ (reserving u for a vector field directing the characteristic foliation on Σ). Then $\Omega(u', w) = -\Omega(w, u') = d\rho|_{\Sigma}(u') > 0$ at regular points of $\rho|_{\Sigma}$, so w induces the proper ‘‘outward normal first’’ orientation on the level sets of $\rho|_{\Sigma}$.

$(a) \Rightarrow (b)$: With w and u' as above, we begin by observing the equation

$$(3) \quad (d\rho \wedge \eta)|_{\Sigma}(u', w) = d\rho(u') \eta(w) - 0 \cdot \eta(u') = d\rho(u') \eta(w).$$

If Σ is ascending, then each level set $\rho|_{\Sigma}^{-1}(c)$ is positively transverse to $\xi = \ker(\eta|_{\rho^{-1}(c)})$ at its regular points, ie $\eta(w) > 0$ at every regular point of $\rho|_{\Sigma}$. And since u' is weakly gradient-like for $\rho|_{\Sigma}$, we have $d\rho(u') > 0$ at every regular point of $\rho|_{\Sigma}$. Therefore (3) implies $(d\rho \wedge \eta)|_{\Sigma} > 0$ at every regular point of $\rho|_{\Sigma}$, as desired.

$(b) \Rightarrow (c)$: If $(d\rho \wedge \eta)|_{\Sigma} > 0$ at every regular point of $\rho|_{\Sigma}$, then (3) implies $d\rho(u') \eta(w) > 0$ at regular points of $\rho|_{\Sigma}$. And since $d\rho(u') > 0$ at regular points of $\rho|_{\Sigma}$, it follows that $\eta(w) > 0$ at regular points of $\rho|_{\Sigma}$. Now let u be the vector field directing the characteristic foliation on Σ , ie $\iota_u \Omega = \eta|_{\Sigma}$. This satisfies

$$d\rho|_{\Sigma}(u) = -\Omega(w, u) = \Omega(u, w) = \iota_u \Omega(w) = \eta(w) > 0$$

at regular points of $\rho|_{\Sigma}$. This also shows that the zeroes of u must be critical points of $\rho|_{\Sigma}$, so it only remains to show that u vanishes at each critical point of $\rho|_{\Sigma}$. We offer two (related) explanations of this fact.

To set up the first argument, note that we can write $(d\rho \wedge \eta)|_{\Sigma} = g\Omega$ for some non-negative function g on Σ that vanishes only at critical points of $\rho|_{\Sigma}$. Since g is non-negative, it vanishes to even order at critical points, hence the same is true for the 2-form $(d\rho \wedge \eta)|_{\Sigma}$. But since $\rho|_{\Sigma}$ is Morse, it vanishes precisely to second order at its critical points. This implies that $d\rho|_{\Sigma}$ vanishes precisely to first order. Since $(d\rho \wedge \eta)|_{\Sigma}$ vanishes to at least second order, we conclude that $\eta|_{\Sigma}$ must also vanish at critical points. Since Ω is nondegenerate, the vanishing of the 1-form $\eta|_{\Sigma} = \iota_u \Omega$ implies that u vanishes at critical points of $\rho|_{\Sigma}$ as well.

Alternatively, we may argue using local coordinates. For the sake of contradiction, suppose that u is nonvanishing at a critical point p of $\rho|_{\Sigma}$. Since $\rho|_{\Sigma}$ is a Morse function, we may local fix coordinates (x, y) on Σ centered at $p = (0, 0)$ such that $\rho|_{\Sigma}(x, y) = ax^2 + by^2$ for nonzero $a, b \in \mathbb{R}$. As noted above, if u is nonzero at p then $\eta|_{\Sigma}$ is nonzero at p because Ω is nondegenerate and $\eta|_{\Sigma} = \iota_u \Omega$. Therefore η is nonzero on at least one of the vectors ∂_x or ∂_y at $p = (0, 0)$. For simplicity, suppose $\eta(\partial_x) > 0$ at p ; the other cases are similar. For small $\epsilon > 0$, we have $\eta(\partial_x) > 0$ at the regular points $p_{\pm} = (0, \pm\epsilon)$ of $\rho|_{\Sigma}$. Using the expression for $\rho|_{\Sigma}$ above, we calculate

$$(4) \quad (d\rho \wedge \eta)_{p_-}(\partial_x, \partial_y) = -(d\rho \wedge \eta)_{p_+}(\partial_x, \partial_y).$$

But since p_{\pm} is a regular point of $\rho|_{\Sigma}$ and (∂_x, ∂_y) is a positive basis for $T_{p_{\pm}}\Sigma$, we must have $(d\rho \wedge \eta)(\partial_x, \partial_y) > 0$ at both points p_{\pm} , contradicting (4).

(c) \Rightarrow (a) : Let u direct the characteristic foliation on Σ , ie $\iota_u \Omega = \eta|_{\Sigma}$. If u is weakly gradient-like for $\rho|_{\Sigma}$, then we have $d\rho|_{\Sigma}(u) > 0$ at each regular point of $\rho|_{\Sigma}$, hence

$$\eta(w) = \iota_u \Omega(w) = \Omega(u, w) > 0$$

at regular points of $\rho|_{\Sigma}$. Since w directs each regular level $\rho|_{\Sigma}^{-1}(c)$ and η defines the contact form on each level set $\rho^{-1}(c)$, we see that each regular level set $\rho|_{\Sigma}^{-1}(c)$ is a (positively) transverse link in $\rho^{-1}(c)$. Therefore Σ is ascending, as claimed. \square

This allows us to extend an observation from [7] regarding ascending surfaces in \mathbb{C}^2 .

Corollary 4.11 *If an ascending surface $\Sigma \subset X$ is tangent to the contact level set $Y = \rho^{-1}(c)$ at $p \in \Sigma$, then $T_p \Sigma$ coincides with the contact plane at $T_p Y$.*

Proof Such tangencies are precisely the critical points of $\rho|_{\Sigma}$. By Proposition 4.10, each critical point of $\rho|_{\Sigma}$ is a singular point of the characteristic foliation defined by the Liouville 1-form η on Σ , so η vanishes on $T_p \Sigma$. Since $T_p \Sigma$ is a (real) 2-dimensional plane in $T_p Y$ on which η vanishes, we see that $T_p \Sigma$ coincides with the contact plane $\xi_p \subset T_p Y$ defined by $\ker \alpha$ for $\alpha = \eta|_Y$. \square

Since the exterior derivative $d\alpha$ of the contact form $\alpha = \eta|_Y$ is nondegenerate on each contact plane in $\ker \alpha$, Corollary 4.11 implies that the symplectic form $\omega = d\eta$ is nondegenerate on $T_p \Sigma$ at each critical point p of $\rho|_{\Sigma}$. This allows us to associate a sign to each critical point of $\rho|_{\Sigma}$: We say that a critical point p of $\rho|_{\Sigma}$ is *positive* or *negative* according to whether ω is positive or negative on the (oriented) plane $T_p \Sigma$. Equivalently, a critical point p of $\rho|_{\Sigma}$ is *positive* or *negative* according to whether the intrinsic orientation on $T_p \Sigma$ agrees or disagrees, respectively, with the orientation on

the contact plane $\xi_p = \ker \alpha_p$. Thus the sign of the critical point p agrees with the sign of the corresponding singular point in the characteristic foliation on Σ .

The following proposition shows that Theorem 1.1 is a special case of Theorem 4.2.

Proposition 4.12 *With respect to a generic J -convex Morse function, a smooth J -holomorphic curve in a Stein domain (X, J) is ascending with positive critical points.*

We require a lemma concerning $C^\infty(X, \mathbb{R})$, the space of smooth functions on X .

Lemma 4.13 *Any smooth function $g : X \rightarrow \mathbb{R}$ on a compact 4-manifold X can be approximated (in the C^k -topology, for any prescribed degree k) by a Morse function $h : X \rightarrow \mathbb{R}$. If Σ is a smooth, properly embedded surface in X , then h may be chosen so that $h|_\Sigma$ is Morse and so that Σ avoids the critical points of $h|_X$.*

Proof The first claim follows from [27, Corollary 4.8]. Moreover, inspecting the proof given in [27], we see that h may be chosen so that $h|_\Sigma$ is also Morse. Now let ψ_t be the flow of a vector field on X that is normal to Σ near any critical points of h lying on Σ . Since the critical points of h are isolated, $\psi_t(\Sigma)$ is disjoint from these critical points for small $t > 0$. Equivalently, Σ avoids the critical points of $\psi_t^*h : X \rightarrow \mathbb{R}$ for small $t > 0$, and we may replace h with one of these pullbacks; the Morse condition is open, so $h|_X$ and $h|_\Sigma$ remain Morse. It is clear that these perturbations can be chosen so that the resulting function h approximates g arbitrarily well. \square

Proof of Proposition 4.12 Given a smooth J -holomorphic curve $\Sigma \subset X$ and a J -convex Morse function $\rho : X \rightarrow \mathbb{R}$, we may use Lemma 4.13 to perturb ρ so that $\rho|_\Sigma$ is Morse and Σ avoids the critical points of $\rho|_X$. Recalling that the subspace of J -convex functions in $C^\infty(X, \mathbb{R})$ is open [8, Lemma 3.7] (with respect to the C^2 -topology), we may assume that ρ remains J -convex.

As discussed before Definition 4.1, all regular level sets of $\rho|_\Sigma$ are transverse links in $\rho^{-1}(c)$. And at any critical point p of $\rho|_\Sigma$, $T_p\Sigma$ coincides with the contact plane $\xi_p \subset T_pY$, where Y is the level set of ρ containing p . Both $T_p\Sigma$ and ξ_p are oriented as J -complex tangent lines, so the critical point p of $\rho|_\Sigma$ is positive, as claimed. \square

4.2 Special case: the symplectization

Let Σ be a smooth, oriented surface in $\text{Symp}(Y, \xi)$, where $\xi = \ker \alpha$. The Liouville form $\eta = e^t \alpha$ is obtained by pulling back the contact form α via the projection

$\text{Symp}(Y, \xi) \rightarrow Y$ and multiplying it by a positive function. Therefore the characteristic foliation on Σ induced by η agrees with the characteristic foliation on Σ induced by the composition $\Sigma \hookrightarrow \text{Symp}(Y, \xi) \rightarrow Y$ as discussed before Definition 3.3.

Proof of Theorem 4.4 Let Σ be an ascending surface with positive critical points in a compact piece $Y \times [0, 1]$ of the symplectization of (Y, ξ) with the natural Morse function ρ given by the second-coordinate projection. Suppose that $K_0 = \Sigma \cap Y_0$ is transversely isotopic to a quasipositive braid in a given open book (B, π) for (Y, ξ) . We wish to show that $K_1 = \Sigma \cap Y_1$ is also transversely isotopic to a quasipositive braid in (B, π) . We will reduce to the 3-dimensional setting and apply Theorem 1.3.

We may view K_0 and K_1 as transverse links in (Y, ξ) via the projection $\text{Symp}(Y, \xi) \rightarrow Y$. By a slight perturbation of Σ (through ascending surfaces), we may assume that K_0 and K_1 project disjointly to (Y, ξ) . These transverse links cobound the singular surface $\phi(\Sigma) \subset Y$ obtained via the composition $\phi : \Sigma \hookrightarrow Y \times [0, 1] \rightarrow Y$. For technical reasons (see Remark 3.8), we perturb Σ so that the critical level sets of $\rho|_{\Sigma}$ have disjoint images under ϕ : For each critical level set $\rho|_{\Sigma}^{-1}(t)$, we may perform a small contact isotopy of Y_t that ensures the image of $\rho|_{\Sigma}^{-1}(t)$ under ϕ is disjoint from the image of each of the other critical level sets of $\rho|_{\Sigma}$. This naturally extends to an isotopy of $Y \times [0, 1]$ supported near Y_t that restricts to a contact isotopy on each level hypersurface (and thus preserves the fact that Σ is ascending). Repeating this near every critical level set of $\rho|_{\Sigma}$ induces the desired isotopy of Σ . After this perturbation, the critical level sets of $\rho|_{\Sigma}$ are mapped disjointly by ϕ into Y .

By Lemma 3.4, the map ϕ is nonsingular with respect to $\rho|_{\Sigma} : \Sigma \rightarrow \mathbb{R}$. By Proposition 4.10 and the ensuing discussion of signs of critical points, the characteristic foliation on Σ is weakly gradient-like with respect to $\rho|_{\Sigma}$ and contains only positive singular points. Applying Theorem 1.3 (via Remark 3.8), we conclude that K_1 is transversely isotopic to a quasipositive braid with respect to the chosen open book (B, π) . \square

As a corollary, we recover the theorem of Boileau and Orevkov:

Proof of Corollary 4.5 Let $\Sigma \subset \mathbb{C}^2$ be a smooth complex curve meeting the unit sphere $S^3_1 \subset \mathbb{C}^2$ transversely in a link K . After a small translation, we may assume that Σ lies in $\mathbb{C}^2 \setminus \{0\} \approx \text{Symp}(S^3, \xi_{\text{st}})$ and that the radial distance function restricts to a Morse function on Σ . (Note that any sufficiently small translation of Σ induces a transverse isotopy of the link $K = \Sigma \cap S^3_1$.) By Proposition 4.12, Σ is an ascending surface with positive critical points in $\text{Symp}(S^3, \xi_{\text{st}})$. Applying Theorem 4.4, we see

that $\Sigma \cap S^3_1$ is quasipositive with respect to any open book supporting (S^3, ξ_{st}) , including the standard open book (D^2, id) . \square

4.3 The general case

We now consider ascending surfaces in a general Weinstein cobordism (X, ω, ρ, v) . By definition, an ascending surface Σ in X is sensitive only to the function ρ and the contact structure on level sets of ρ induced by the Liouville 1-form $\eta = \iota_v \omega$. Through this lens, any noncritical region of a Weinstein cobordism looks like the symplectization of a regular level set.

Lemma 4.14 *Suppose (X, ω, ρ, v) is a Weinstein cobordism with no critical points and let (Y, ξ) be a regular contact hypersurface $\rho^{-1}(c)$. Then there is a diffeomorphism*

$$\psi : Y \times [a, b] \subset \text{Symp}(Y, \xi) \rightarrow X$$

such that $\psi^ \rho$ is the second-coordinate projection and ψ restricts to a contactomorphism between the level sets of ρ and $\psi^* \rho$.*

Proof For notational convenience, we assume $c = 0$. As a first step, we construct a diffeomorphism $Y \times [a, b] \rightarrow X$ that pulls ρ back to the second-coordinate projection. Let v be the gradient of ρ defined above. Since ρ has no critical points and X is compact, the function $f = 1/d\rho(v)$ is bounded. By the completeness of v and the boundedness of f , the multiple $v' = fv$ is also complete. This vector field satisfies $d\rho(v') \equiv 1$ and is complete, so the flow of v' defines a diffeomorphism from $Y \times [a, b]$ to X that pulls ρ back to the second-coordinate projection.

Now let ζ_0 be the vertically invariant plane field on $Y \times [a, b]$ defined by ξ on each level set, and let ζ_1 be the plane field obtained by pulling back the natural contact structure on each level set of ρ in X under the diffeomorphism constructed above. We will produce an isotopy of $Y \times [a, b]$ preserving level sets that carries ζ_0 to ζ_1 . Choose 1-forms α_0 and α_1 such that $\zeta_i = \ker(dt \wedge \alpha_i)$. Now define a family of maps π_s from $Y \times [a, b]$ to itself by $\pi_s(y, t) = (y, st)$. The map π_s restricts to a diffeomorphism from $Y \times \{t\}$ to $Y \times \{st\}$ for all $s \in [0, 1]$ and $t \in [a, b]$. The induced family of 1-forms $\alpha_s = \pi_s^* \alpha_1$ on $Y \times [a, b]$ interpolates between α_0 and α_1 as defined above because π_s is the projection $Y \times [a, b] \rightarrow Y \times \{0\}$ for $s = 0$ and is the identity for $s = 1$. It is also easy to see that α_s restricts to a contact form on each $Y \times \{t\}$.

From here, the standard Moser's trick argument produces a vector field V_s such that

- (i) V_s is tangent to the level sets $Y \times \{t\}$,
- (ii) V_s lies in $\ker \alpha_s$, and
- (iii) the flow ψ_s of V_s satisfies $\psi_s^* \alpha_s = \lambda_s \alpha_0$ for some family of smooth positive functions λ_s on $Y \times [a, b]$.

The diffeomorphism ψ_1 of $Y \times [a, b]$ preserves level sets and is seen to carry ζ_0 to ζ_1 :

$$(\psi_1)_* \zeta_0 = (\psi_1)_* \ker(dt \wedge \alpha_0) = (\psi_1)_* \ker(dt \wedge \lambda_1 \alpha_0) = \ker(dt \wedge \alpha_1) = \zeta_1.$$

It follows that the composition of ψ_1 with the original map $Y \times [a, b] \rightarrow X$ provides the desired diffeomorphism. \square

To understand ascending surfaces in the presence of critical points of $\rho : X \rightarrow \mathbb{R}$, we use the natural handle decomposition of X defined by ρ . Results of Eliashberg [9] and Weinstein [35] describe such handle decompositions and the effect of each handle attachment on the contact level sets of ρ . For additional background material, we point the reader to [19], as well as [8, Lemma 11.13] and [10, §5].

Proof of Theorem 4.3 Let (B_0, π_0) be a compatible open book for (Y_0, ξ_0) with respect to which K_0 is quasipositive. We will show that K_1 is quasipositive with respect to a compatible open book (B_1, π_1) for (Y_1, ξ_1) obtained from (B_0, π_0) by positive Hopf stabilization and the addition of positive Dehn twists (along homologically nontrivial curves) into the monodromy. By subdividing X , it suffices to consider the case where X contains at most one critical point. Note that, by the C^2 -openness of J -convex functions, we may choose ρ so that the critical values of $\rho|_X$ and $\rho|_\Sigma$ are all distinct.

If X contains no critical points of ρ , then for any value c there's a diffeomorphism from a compact piece of $\text{Symp}(\rho^{-1}(c))$ to X of the form described in Lemma 4.14. By that lemma and the definition of an ascending surface, it is easy to see that $\Sigma \subset X$ pulls back to an ascending surface with positive critical points in $\text{Symp}(\rho^{-1}(c))$. The claim then follows from Theorem 4.4.

Now suppose that $\rho|_X$ has a single critical point, the value of which we will denote by c . For any $\epsilon > 0$, we can further subdivide X into three pieces: two exterior pieces where $|\rho - c| > \epsilon$ and an interior piece where $|\rho - c| \leq \epsilon$. It suffices to prove the claim for the interior piece. First consider the case where the critical point of $\rho|_X$ has Morse index zero. This is equivalent to considering ascending surfaces in the unit ball in $(\mathbb{R}^4, \omega_{\text{st}})$ that miss the origin, so the ascending surface can be viewed in $\text{Symp}(S^3, \xi_{\text{st}})$, where the desired claim again follows from Theorem 4.4.

Next consider the case where the critical point of $\rho|_X$ has Morse index one. By choosing ϵ sufficiently small, we can assume that $\rho|_\Sigma$ has no critical points in X . Furthermore, for small enough ϵ , we may assume Σ is disjoint from a neighborhood of the stable and unstable manifolds of the unique critical point of $\rho|_X$. The level set $Y_1 = \rho^{-1}(c + \epsilon)$ is obtained from $Y_0 = \rho^{-1}(c - \epsilon)$ by removing a pair of small Darboux balls and attaching a copy of $S^2 \times I$ with the appropriate contact structure. After positive Hopf stabilization, we can assume that Y_0 is equipped with an open book (B_0, π_0) such that (1) the attaching region A for the 1-handle lies along the binding B_0 and (2) the transverse link $K_0 = \Sigma \cap Y_0$ is transversely isotopic to a quasipositive braid K_0^+ with respect to (B_0, π_0) . (Note that positive Hopf stabilization of a pointed open book preserves quasipositivity.) Moreover, since the attaching region A is a pair of small Darboux balls, we may assume that the transverse isotopy between K_0 and K_0^+ is performed in the complement of A . Now we construct a natural open book on Y_1 that extends the open book on Y_0 : By an argument similar to the one used in the proof of Lemma 4.14, there is an embedding

$$\Psi : (Y_0 \setminus A) \times [c - \epsilon, c + \epsilon] \hookrightarrow X$$

pulling ρ back to the second-coordinate projection and restricting to a contact embedding on each level set. Since Σ avoids the critical point of $\rho|_X$ (and also avoids its stable and unstable manifolds), we can also assume that Σ lies in the image of this embedding. Define an embedding $\psi : Y_0 \setminus A \hookrightarrow Y_1$ by sending $y \in Y_0 \setminus A$ to $\Psi(y, c + \epsilon)$ in Y_1 . The restriction of the open book (B_0, π_0) to $Y_0 \setminus A$ can then be pushed forward to $\psi(Y_0 \setminus A) \subset Y_1$ and then extended in the natural way over the 1-handle in Y_1 to define a compatible open book (B_1, π_1) on Y_1 . Abstractly, this can be described as follows: if (B_0, π_0) is encoded by (F_0, φ_0) , then (B_1, π_1) is encoded by (F_1, φ_1) where F_1 is the union of F_0 and an oriented 1-handle and φ_1 is the extension of φ_0 to F_1 via the identity on the 1-handle.

Now the quasipositive braid K_0^+ with respect to (B_0, π_0) in $Y_0 \setminus A$ induces a quasipositive braid $K_1^+ = \psi(K_0^+)$ with respect to (B_1, π_1) in $\psi(Y_0 \setminus A) \subset Y_1$. Since the transverse isotopy between K_0 and K_0^+ lies in the domain of ψ , the transverse link $\psi(K_0)$ in Y_1 is transversely isotopic to K_1^+ in Y_1 . And since Σ lies in the image of Ψ and we have assumed $\rho|_\Sigma$ has no critical points in X , we can use Ψ and Σ to realize a transverse isotopy between $\psi(K_0)$ and K_1 in Y_1 . It follows that K_1 is transversely isotopic to the quasipositive braid K_1^+ with respect to (B_1, π_1) .

Finally, we must consider the case where the critical point of $\rho|_X$ has Morse index two. In this case, the argument is nearly identical to the preceding case. The primary difference is that the attaching region A of the Weinstein 2-handle is a neighborhood of

a Legendrian knot Λ in (Y_0, ξ_0) ; see the references [8, 9, 19, 35] given above, especially [8, Lemma 11.13]. Moreover, the contact 3-manifold (Y_1, ξ_1) is obtained from (Y_0, ξ_0) by Legendrian surgery along Λ . Any open book compatible with ξ_0 has a positive Hopf stabilization containing the Legendrian knot Λ in a page; see [10, Corollary 4.23]. As above, we can construct a family of contact embeddings $Y_0 \setminus A \hookrightarrow \rho^{-1}(t)$ for t near c and produce the desired open book (B_1, π_1) from (B_0, π_0) . Abstractly, this corresponds to inserting a positive Dehn twist along the representative of Λ in the page of the open book; see [10, Theorem 5.7]. Note that, since any contact form α for ξ_0 induces an area form $d\alpha$ on each page of (B_0, π_0) , the Legendrian curve Λ must be homologically nontrivial by Stokes' theorem.

It remains to show that K_1 is transversely isotopic to a quasipositive braid with respect to (B_1, π_1) . The family of contact embeddings $Y_0 \setminus A \hookrightarrow \rho^{-1}(t)$ also lets us pull Σ back to an ascending surface in $\text{Symp}(Y_0 \setminus A, \xi_0)$ with no critical points. By the transverse Alexander and Markov theorems, we can find braid representatives of K_0 and K_1 encoded by pointed open books that are related by positive Markov stabilization and destabilization and the addition of a positive Dehn twist. By an argument analogous to the proof of Lemma 2.6, it is easy to show that these operations preserve the property of being transversely isotopic to a quasipositive braid.

In the case where $K_0 = \Sigma \cap Y_0$ is transversely isotopic to the closure of a quasipositive braid with respect to a positive allowable open book, it is clear that the same is true of K_1 because we have modified the original underlying open book only by adding 1-handles, inserting positive Dehn twists along homologically nontrivial curves in the page, and performing positive Hopf stabilizations (which also introduce Dehn twists along homologically nontrivial curves). See also Remark 3.9. \square

Observe that Theorem 4.2 follows by taking K_0 to be empty and viewing a Weinstein domain X as a cobordism from the empty set to ∂X . Theorem 1.1 follows in turn from Theorem 4.2 and Proposition 4.12.

5 Constructions of symplectic surfaces

In this final section, we prove that every quasipositive braid in a positive allowable open book bounds a symplectic surface in some Stein filling of the associated contact 3-manifold. Our strategy will be to construct ascending surfaces with positive critical points and then perform an isotopy to make the surfaces symplectic. This requires a lemma adapted from [7].

Lemma 5.1 *Let Σ be an ascending cobordism with positive critical points in $\text{Symp}(Y, \xi)$ between transverse links K_0 and K_1 in (Y, ξ) . Then Σ can be made symplectic through a compactly supported isotopy of ascending surfaces.*

Proof For any constant $a \geq 1$, define a diffeomorphism ψ_a of $Y \times \mathbb{R}$ by $\psi_a(y, t) = (y, at)$. Assume that Σ is cylindrical outside of $[T_-, T_+]$ and let $\Sigma' = \Sigma \cap [T_-, T_+]$. We will first show that for $a \gg 1$, we have $\omega|_{\psi_a(\Sigma')} > 0$, ie $\psi_a^*(\omega)|_{\Sigma'} > 0$. An elementary calculation gives

$$\psi_a^*(\omega) = ae^{at} dt \wedge \alpha + e^{at} d\alpha = e^{(a-1)t} ((a-1)e^t dt \wedge \alpha + \omega).$$

Recall that $(dt \wedge \alpha)|_{\Sigma} \geq 0$, with equality if and only if the point in Σ is a singular point of $\rho|_{\Sigma}$. In terms of an area form Ω for Σ , this means we can write $e^t(dt \wedge \alpha)|_{\Sigma}$ as $f \cdot \Omega$ with $f \geq 0$. Similarly, we can write $\omega = g \cdot \Omega$. Note that $g > 0$ on a neighborhood of each critical point of $\rho|_{\Sigma}$ because Σ is ascending with positive critical points. Using the compactness of Σ' , it follows that $\psi_a^*(\omega)|_{\Sigma'} > 0$ for $a \gg 1$ and thus $\psi_a(\Sigma')$ is symplectic. Outside of $\psi_a(\Sigma')$, the surface $\psi_a(\Sigma)$ is cylindrical over transverse links. It follows that $\psi_a(\Sigma)$ is a symplectic cobordism between K_0 and K_1 . Moreover, it is easy to check that $\psi_a(\Sigma)$ remains ascending with positive critical points. \square

Remark 5.2 If (Y, ξ) is symplectically fillable and $K_0 = \emptyset$, the relative symplectic Thom conjecture implies that the surfaces constructed are genus-minimizing.

The desired surfaces can now be constructed using Example 4.7 and Lemma 5.1.

Proof of Theorem 1.2 Let (Y, ξ) denote the contact 3-manifold in question. By hypothesis, we have a transverse braid K in Y encoded by a pointed open book $(F, P, \widehat{\psi} \circ \varphi)$ where $\widehat{\psi}$ is a product of positive half-twists and $\varphi = D_{\gamma_1} \circ \dots \circ D_{\gamma_m}$ is a product of positive Dehn twists along homologically nontrivial simple closed curves γ_j in F . The modified pointed open book $(F, P, \widehat{\psi} \circ \text{id})$ is a quasipositive braid K_0 in $Y_0 = \#^k(S^1 \times S^2)$ for $k = 2g(F) + |\partial F| - 1$. The associated contact structure ξ_0 is the unique Stein-fillable contact structure obtained from viewing Y_0 as the boundary of the subcritical Stein domain $X_0 = \natural^k(S^1 \times B^3)$. As constructed in Example 4.7, we can find an ascending surface Σ with positive critical points in a compact piece $Y_0 \times (-\epsilon, 0]$ of the symplectization $\text{Symp}(Y_0, \xi_0)$. By applying Lemma 5.1 and allowing ϵ to increase, we can isotope this surface to be symplectic. After stretching a collar neighborhood of ∂X_0 , the surface Σ in $Y_0 \times (-\epsilon, 0]$ embeds properly and symplectically into X_0 . By construction, the boundary of Σ is the transverse link K_0 encoded by $(F, P, \widehat{\psi} \circ \text{id})$.

Using the Legendrian Realization Principle (see [37] for this special case), we can realize the homologically nontrivial curves γ_j as Legendrian knots Λ_j lying on distinct pages F_{θ_j} in (Y_0, ξ_0) for increasing $\theta_j \in (\pi, 2\pi)$; here we scale θ so that all nontrivial braiding occurs while θ lies in $(0, \pi)$. Performing surgery along each Λ_j with framing -1 (relative to the page framing) corresponds to modifying the pointed open book by introducing a positive Dehn twist along each γ_j in order of increasing θ_j . The result reproduces the original pointed open book $(F, P, \widehat{\psi} \circ \varphi)$. These surgeries can be realized by attaching Stein 2-handles along the Legendrian knots Λ_j to produce a Stein filling X of (Y, ξ) . Moreover, since the handles are attached away from the boundary of Σ , the symplectic structure near Σ is unchanged. It follows that Σ is a symplectic surface in X whose boundary is the original link K . \square

Combining this construction with Theorem 4.2 yields the following characterization:

Corollary 5.3 *A transverse link in (Y, ξ) is quasipositive with respect to a positive allowable open book if and only if it bounds an ascending surface with positive critical points in some Stein filling of (Y, ξ) .* \square

We end this section with an example that demonstrates the failure of Theorem 1.2 for links in the boundary of a Stein domain that are quasipositive braids with respect to a compatible open book whose monodromy is *not* positive allowable.

Example 5.4 Consider an annulus A with a single marked point p as depicted in Figure 2. Letting P_δ denote the push map about the core circle through p , we note that the pointed open book $(A, \{p\}, P_\delta)$ encodes a braid K in $S^1 \times S^2$ with respect to its trivial planar open book. This braid K represents a nontrivial element in $H_1(S^1 \times S^2)$. Since any Stein filling of $S^1 \times S^2$ is diffeomorphic to $S^1 \times B^3$ and $H_2(S^1 \times B^3, \partial(S^1 \times B^3)) = 0$, we see that K cannot bound a surface in any Stein filling. However, as depicted on the right side of Figure 2, K can also be represented by a pointed monodromy consisting of a pair of (oppositely-signed) Dehn twists. This braid is quasipositive with respect to an open book monodromy that is *not* positive allowable, though the underlying open book supports the Stein-fillable contact structure on $S^1 \times S^2$. \diamond

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